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NAVAL RESEARCH LABORATORY REPORT

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REPORT ON EXAMINATION AND TEST OF RCA VICTOR COMPANY MODEL CXC HIGH FREQUENCY DIRECTION FINDER (Serial No. 2)

By S. A. Greenleaf

Report No. 1001

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OFFICE OF NAVAL RESEARCH
NAVAL RESEARCH LABORATORY

WASHINGTON 20, D. C.

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REPORT ON EXAMINATION AND TEST

OF

RCA VICTOR COMPANY MODEL CXC RIGH

FREQUENCY DIRECTION FINDER. (Serial No.2)

Tests conducted 27 July to 18 August, 1933, and 11 September to 6 October 1933.

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1. AUTHORIZATION

Problem D2-3 was authorized in Bureau of Engineering letter S67/69 (3-3-W8) of 3 April 1933.

2. PURPOSE OF TESTS

Examination and Test of RCA Victor Company Model CXC Righ Frequency Direction Finder, Serial No. 2, (Receiver Type CRV-46-AAB) to determine the general suitability and limitations of this model direction finder for Naval use.

3. DESCRIPTION OF APPARAIUS

This equipment consists of a receiver, 14-1/2" wide, 12-11/16" high and 3-1/2" deep, with a loop collector, hand wheel, and indicator mounted directly on top of the receiver, the loop being enclosed in a circular aluminum casting 16" in diameter, the entire receiver-loop assembly standing 39-1/4" high. A separate metal box, 10" x 12" x 18-3/4", contains a six volt lead cell A battery and 135 volts of dry cell B batteries, with a 36" cable and multiple plug for connection to the receiver.

The weight of the loop, drive and receiver assembly is 53 pounds, and the battery box 89 pounds.

An extension is provided for the loop drive shaft, together with a deck mounting flange and bearing unit. There is a plug on the front panel for the single wire balancing antenna, but separate support for the antenna must be provided for the antenna when installed.

The receiver is a six tube unit employing an autodyne circuit with an oscillating first detector, two stages of 23 Kc i-f amplification, i-f oscillator, second detector, and a single audio stage, with an electrostatically shielded output transformer, designed for use with head phones having an impedance of 22000 ohms at 1000 cycles.

The frequency range is 2000 to 15,000 Kcs, covered in five bands by means of a tap switch, the bands being as follows, with ample overlap:

Band	1	1900-2875 K	es
11	2	2875-4350	11
	3	4350-6490	11
- 11	4	6490-9680	1:
- 11	5	9680-15650	11

Tuning is accomplished with a single dial, with a vernier adjustment. Other controls on the panel consist of the

frequency range tap switch for positions 1 to 5, volume control, regeneration control, balancing condenser, filament switch and switch for the CW oscillator. There is also a meter for indicating filament and plate voltages, jack for the antenna plug, two phone jacks, and socket for the battery plug.

The input circuit consists of a two turn untuned loop, in series with the primary of a coupling unit, the center of this inductance being grounded. The balancing condenser has two sets of stationary plates connected to either side of the loop terminals, with the antenna on the single set of rotary plates, by means of which quadrature currents are introduced to balance the residuals in the loop. The secondary of the coupling unit is tapped into five sections, permitting the sections to be shorted out by the frequency band switch. This circuit is tuned and coupled directly to the grid of the combination detector-oscillator, this being the only circuit with variable tuning controlled from the panel. The screen grid circuit of this tube has a feed-back coil coupled to the grid coil to cause the tube to oscillate, oscillations being controlled by a variable resistor to regulate the screen grid voltage.

The inner anode, or screen grid circuit is electron coupled to the plate or output circuit. By the combination of the incoming signal with the oscillation frequency, a heterodyne beat note of 23 Kcs is produced, which is fed to the i-f coupler, consisting of a singlé coil shunted by a trimmer condenser, which in turn is coupled to the grid of the first i-f tube through another trimmer condenser.

Volume is controlled by regulation of the voltage on the screen grids of the two 1-f tubes with a variable resistor.

Two stages of i-f amplification are followed by the i-f detector, to which is coupled a separate i-f oscillator for use in CW reception. This tube is controlled by a toggle switch, mounted on the panel, which opens and closes the plate circuit. The i-f detector is followed by one stage of audio frequency amplification, a double section filter being contained in the plate circuit of the detector tube ahead of the interstage transformer. The output of the audio amplifier is fed into the output transformer which is provided with an electrostatic shield between primary and secondary, the secondary being also electrostatically balanced with respect to ground.

Tetrode tubes, commercial type '36, are used for the combination detector-oscillator, the two stages of i-f amplification and the i-f detector; a triode commercial type '37 for the Cartillator, and a position, according

type '38 for the audio amplifier.

In the first detector condenser and grid leak are used for detection, while in the second detector biased grid detection is used. Grid bias voltages are obtained by the use of resistors in the cathode legs of the i-f, second detector and audio stages. Plate voltages are supplied as required, by taps on the bank of B batteries.

This equipment has two pilot lights controlled by the filament switch, one each to illuminate the receiver tuning dial, and the loop indicator dial.

4. METHOD OF CONDUCTING TESTS

A model LC standard signal generator was used to supply test voltages for sensitivity and selectivity measurements, and a General Radio output meter type 483C, resistance 20,000 ohms to measure outputs. A General Radio signal generator type 604B was used to furnish signals for calibration and test of directional characteristics at close range. Signals from fixed land stations were used for taking bearings, principally NAA and WAR.

Signals from an airplane type XREL were used also for taking bearings. This ship was equipped with a transmitter Model GHX.

For the purpose of this test, the following definitions are applicable, and methods of procedure are shown:

Standard output is 5 milliwatts, or 10 volts across 20000 ohms.

Sensitivity is shown as the voltage induced in the loop antenna in microvolts to produce standard output, with a gain adjustment for .5 volts noise. For this measurement voltage from a standard signal generator was applied to the terminals of a coupling coil, placed at a suitable distance from the loop antenna, and the field intensity in microvolts per meter at the loop antenna was calculated. The effective height of the loop antenna was also calculated, and from these two factors the induced voltage was determined.

Selectivity is shown as the ratio of input for standard output, at percentages of frequency above or below resonant frequency to the input for standard output at resonant frequency. This measurement was also obtained by inducing voltages in the loop antenna by means of a coupling coil to which the signal generator voltage was applied.

The following tests were made:

(a) Sensitivity, CW input.

(b) Selectivity, MCW input.

(c) Maximum noise level, CW oscillator on and off.

(d) Bearings taken at eight points through 360 degrees using signals from signal generator at a distance of 100 feet from direction finder.

(e) Test for minimum shift due to detuning and balancer, and change of position of balancing antenna with respect to receiver-loop assembly.

(f) Bearings taken on fixed land stations at various distances.

(g) Bearings taken on plane transmission.

(h) Test of detuning due to balancer.

(i) Test for minimum displacement from 180°.

(j) Test for body effects.

5. RESULT OF TESTS

- (a) Sensitivity with CW input, and gain adjustment for 0.5 volts noise level, is shown on plates 1 to 3 inclusive. In order to obtain the required noise level, it was necessary to greatly reduce the gain, thus decreasing the sensitivity.
- (b) Selectivity with CW input modulated 30% at 1000 cycles, taken with the second oscillator off, and full gain adjustment, is shown on plates 4 to 9 inclusive. Due to the combination detector-oscillator which heterodynes the incoming signal to produce a 23KC beat note, this may be accomplished by tuning either 25 Kcs above or below the signal frequency and there are therefore two resonance peaks in the selectivity curve 46 Kcs apart, the image response being about equal to the signal response. On plate 6, which is the curve taken at 3650 Kcs, both peaks are shown, this being typical with respect to the double peak feature, for all sensitivity curves.
- (c) Maximum noise level both with CW oscillator on and off, is shown on plates 10 to 12 inclusive.
- (d) With the signal generator placed at a distance of 100 feet from the loop, bearings were taken at eight points with the following results:

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Freq. Kc.	Prue B∋aring <u>sighted</u>	DF Bearing	DF Reciprocal bearing	Devia- tion
6150 10800 6150 10800 6150 10800 6150 10800 6150 10800 6150 10800 6150 10800	21.5 21.5 61.5 61.5 100 100 135 135 175.5 175.5 123 223 223 285 285 339.5 339.5	26 26 63 64 95 95 132 132 177 177 224.5 224.5 285 235 343	206 206 243 243 245 275 275 310.5 357 357 44.5 44.5 105 105	-4.5 -4.5 -1.5 -2.5 +5 +5 +3 -1.5 -1.5 -1.5 -1.5 -1.5 -3.5

During this test the bearing of the balancing antenna was placed on an approximate bearing of 260° from the receiver-loop assembly, suspended at a vertical angle of 30° from horizontal, length of antenna 19.5 feet. The deviation shown is believed to be caused primarily by induction fields present to which any loop collector is subject, due to arrangement of the equipment, and other conditions existing at the particular location used. On distant signals further deviation may be introduced by the balancer due to the horizontal polarization of waves.

(e) with the signal generator placed at a distance of 200 feet from the loop, the position of the balancing antenna was changed with respect to the receiver-loop assembly, to note any shift in bearing due to such change, with the following tabulated results:

Frequency	DF	Balance dial	DF Reciprocal	Balance dial	Bearing of Ant.from Rec- eiver loop
9800 Kc	95 95 95 94 95 95 95 95	-15 -10 -5 -5 -5 -5 -7.5 -15	275 275 275 274 275 275 275 276 276	0 -5 -10 -10 -10 -12.5 -5	45° 90° 135° 180° 225° 270° 305° 360°

The same antenna was used as in (d), placed at the same angle throughout test. This shows a maximum shift of one degree in bearing due to change in position of antenna.

Pest for shift in bearing due to change in balancer shows the following tabulated results:

Frequency	Balancer	Approx.Minimum	Minimum
8040 }	-25	3280	7000
WAR	-30 -35	3280	328°
9050)	-20	3100	
NAA }	-25 -30	310°	3100
9800	-5	940	
Sig.gen.	-10 -15	940	940

Bearings cannot be taken when signal is detuned, due to sharp tuning necessary to produce the heterodyne beat note frequency of 23 Kc.

(f) Using the same balancing antenna as in (d) and in all cases at an approximate bearing of 260°, the following results were obtained in taking bearings on fixed land stations.

Stations.	Total	Avarage	Maximum	Minimum		-	
Frequency	Dearings	Average Error	Error	Error	Dis	tance	
4015	1.	1.5	-1.5	-1.5	5	miles	
8040	12	14.9	+28.5	+2.5	5	11	
8040	2	18.5	+18.5	+18.5	8	11	
8040	479	11.4	+11.5	+11	14	11	
8410	4	10	+10	+10	5	11	
8410	1	8	+8	+8	8	11	
8870	2	19.5	+23.5	-15.5	5	11	
12060	26	17.3	-40	-3	5	n ti	
12060	4	6.2	-14	0	8	11	
12060	7	20.5	-25	-11.5	14	11	
12060	2	5.2	+6.5	-4	21	11	
12615	16	9.1	-19.5	+1	5	11	
12615	3	21.6	+22	+21	8	11	
13305	1	20.5	-20.5	+20.5	21	- 11	
			· Little Colonia				

Poor minima resulted in taking bearings at a distance of 21 miles and at greater distances satisfactory minima could not be obtained due to attenuation of the ground wave.

Most of the bearings were taken on transmitters at the Naval Radio Station, Arlington (NAA) and the Army Station

There is a complicated array of antenna at both of these stations used with numerous transmitters on low, intermediate and high frequencies, and discrepancies were noted between the bearings taken on a given station on closely related frequencies. A shift in the center of radiation is believed to be caused by this arrangement and must be taken into account in considering the accuracy of the observed bearings. The same deviation table was also used at locations 8, 14 and 21 miles distant as at Bellevue, 5 miles

(g) Bearings taken on signals from a Naval plane type XRE1, equipped with a model GHX transmitter show the following results.

On a straightway course from location of direction finder, 1640 true, the following bearings were noted, Frequency 8270 Kcs. Altitude 1500 feet.

<u>Time</u>	Bearing	Reciprocal	Error	Distance	Remarks
1048.5 1049 1054 1056	172 170 170 170	350 350	-7 -7 -7 -7	4.3 5.8 20.3 26.1	
1058 1100 1102 1103.5 1104.5 1106. 1108 1109.5 1110.5	150 150 154 165 170 170 173 172	32 -4 31.8 -3 29.4 -3 25.8 -5 23.4 -7 20.6 -7 14.7 -5 11	32 31.8 29.4 25.8 23.4 20.6 14.7	Left turn 180°	
1112 1113 1113.5	172 173 175	352	-8 -9 -11	4.8 2.4 1.2	

On a straight away course from location of direction finder, 164° true, the following bearings were noted, Frequency 12405 Kcs. Altitude 1500 feet.

Time	Bearing	Reciprocal	Error	Distanc	e Remarks
1333 1357 1341 1343	180 200 198 198		-16 -36 -34	2 10 18	
1347 1349 1350.5	175 175 175	18	-34 -11 -11 -11	22 30 34	
1352			1.1	37 40	Poor minima Over Potomac -
1353				42	signals weak. Signals faded out.
1355				46	Signals in but
1357 1403.5				50 63	Signals out Signals in but
1406 1407 1421				70 70	no minima Signals out Turned back
1424				44.1 39	Signals in but no minima Signals stronger
1425 1430 1434 1435.5	180 180 170 160	360	-16 -16 -6	28,8 22	but no minima Broad minimum
1436.5 1440 1442 1443.5 1446	160 163 165 167 170	345	+4 +4 +1 -1 -3 -6	20.3 18.6 12.7 9.3 6.8	

On a straight away course from location of direction finder, 1640 true, the following bearings were noted. Frequency 4135 Kcs. Altitude 1500 feet.

<u>lime</u>	Bearing	Reciprocal	Error	Distanc	De Remarks
1032 1034 1036.5 1042 1044 1049	170 170 170 170	350	-8 -8 -8 -8	12.6 16.2 20.7 30.6 34.2	10.004.10
1050.5				47	Making circle over Potomac
1000.5	200		-2		Signals out Very poor min.

Time	Bearing	Réciprocal	Error	Distance	Remarks
1054		a a			wide circle over Potomac signals fading badly - no
1056.5 1102 1104 1109.5 1112.5 1114 1118	170 170 160 170 170		-8 -8 +4 -3 -8 -18	45 40.9 29.4 28.1 19.9	minima Signals good but no minima Signals fading

On a straight away course from location of direction finder, 1640 true, the following bearings were noted. Frequency 4135 Kcs. Altitude 1500 feet.

1102.5 1104.5 1105.5 1107 1108.5 1111 1113 1120	170 163 165 167 170 170	250	-6 +1 -1 -3 -6 -6	4.4 7.9 9.6 12.2 14.8 19.1 22.6	Transmitter
1128				48.8	trouble Signals but no
1131 1140 1141				5 <u>4</u> 70	minima " " " Turned 180° cignals but no
1151.5	170		-6	48 47	minima South bank Potomac Very poor minimum

Transmitter trouble balance of run.

On a circular run, with a radius of 10 miles around location of direction finder following bearings were note. Frequency 8270 Kcs. Altitude 2000 feet.

Time	Bearing	True	Error	Distanc	e Remarks
1026 1031 1039 1041 1044 1047	210 135 80 75 45 340	174 98 45 25 347 313	36 38 55 50 58 27	10	Washington in line of Bearing Un n n n

On a straight away course from location of direction finder, the following bearings were noted: Frequency 8270. Altitude 3000 feet.

1516.5 1518 1520	302 302 302	300 300 300	-1.5 -1.5 -1.5	39.5 41.9 45.2			
1521 1600	310	318	+9	5	Signals	faded	out

(h) Test for detuning of signal due to shift of balancer condenser showed the following results:

The balancer scale runs from 0 to 90 on either side of neutral position and on 1810 Kcs no effect was observed in shifting from 0 to 90.

On 6440 Kcs no effect was observed in shifting from 0 to 30. At 60 signal was reduced 29.2% and at 90 to zero.

On 15500 Kcs at 30 signal was reduced by 73.8% and at 60 to zero.

With a suitable antenna, tests showed this balancer to be normally used between 0 and 20.

- (i) Throughout tests in taking bearings on different methods of transmission, no displacement from 180° greater than one degree was observed in taking reciprocal bearings.
- (j) Throughout tests no body effect was noticed, the output transformer being electrostatically shielded and balanced to ground.

6. CONCLUSIONS

The usable sensitivity of the receiver used in this equipment is fairly good, after reducing the gain considerably to reach a noise level of 0.5 molts. Continually cannot be obtained in operating at a higher noise level

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when adjusting for minimum signal or a null point. The selectivity is very high except for the image response of intensity equal to the signal frequency response, these points being separated by 46 Kcs. The operation of the receiver is very stable except with respect to the band change switch. Contacts would often fail to make and the inability to detect this failure except by the absence of signals gives the operator no warning that the receiver is not functioning. A more sturdy type of switch construction is desirable. As a direction finder, the equipment functions very satisfactorily when taking bearings on signals at close range, 100 feet being the distance for first test, and excellent minima are obtainable, the deviation found being comparatively small.

As intended by the manufacturer this equipment, with a given satisfactory operation at short range should give useful results in taking bearings on signals where the ground wave predominates, with normally polarized waves.

Inasmuch as attenuation of the ground wave to a point where signals are no longer of sufficient strength to enable taking of bearings is not coincident with the introduction of horizontally polarized waves accuracy can only be obtained to the degree that the latter factor is absent.

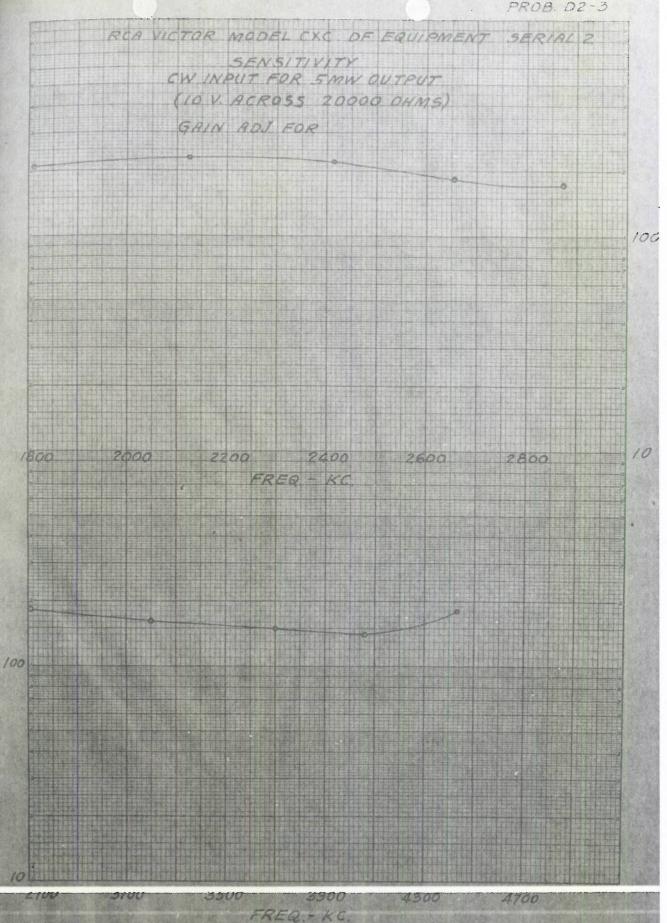
Results in taking bearings on fixed land stations at various frequencies up to 21 miles distant show an average error of 13.1° for 85 bearings.

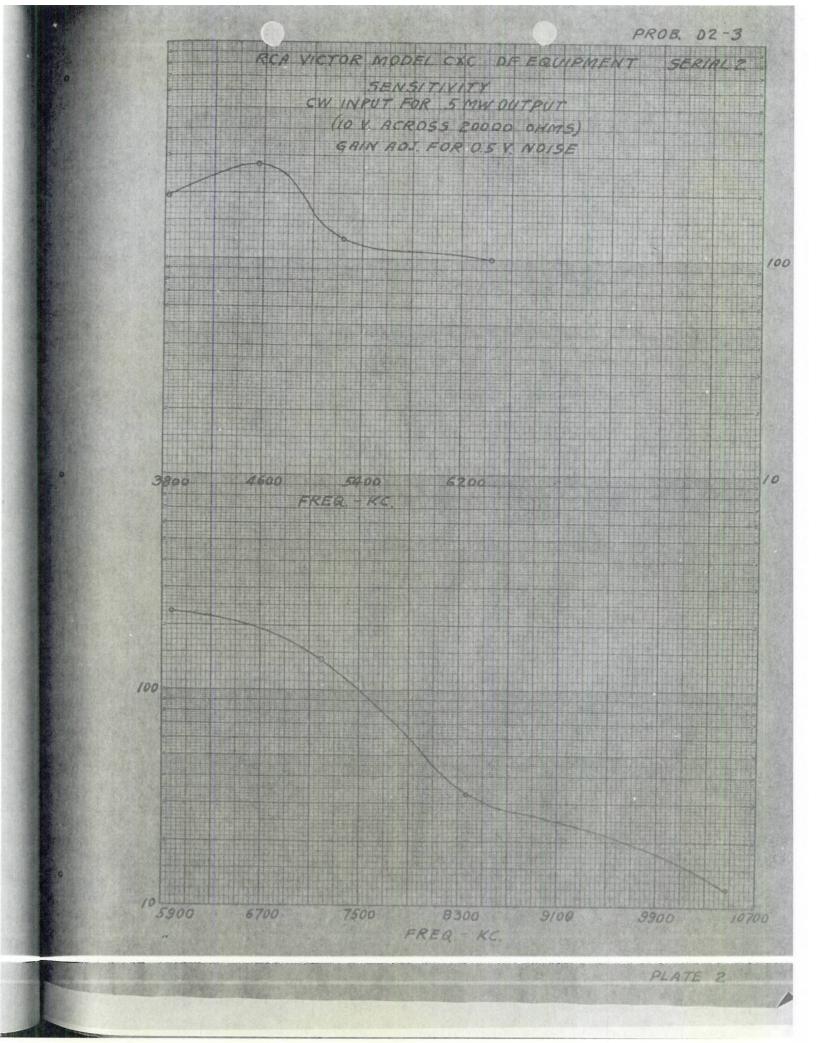
On plane transmission on various frequencies up to 47 miles distant, where course of plane was parallel to line of bearing, average error of 8.3° for 55 bearings. When course of plane was at right angles to line of bearing, on a frequency of 8270 kcs at a distance of 10 miles, average error of 40.6° for 6 bearings. These results are in agreement with previous findings of this laboratory that the use of a direction finder with loop collector on high frequencies will not give accuracy comparable with that obtained when used on intermediate frequencies, except where only the ground wave is present.

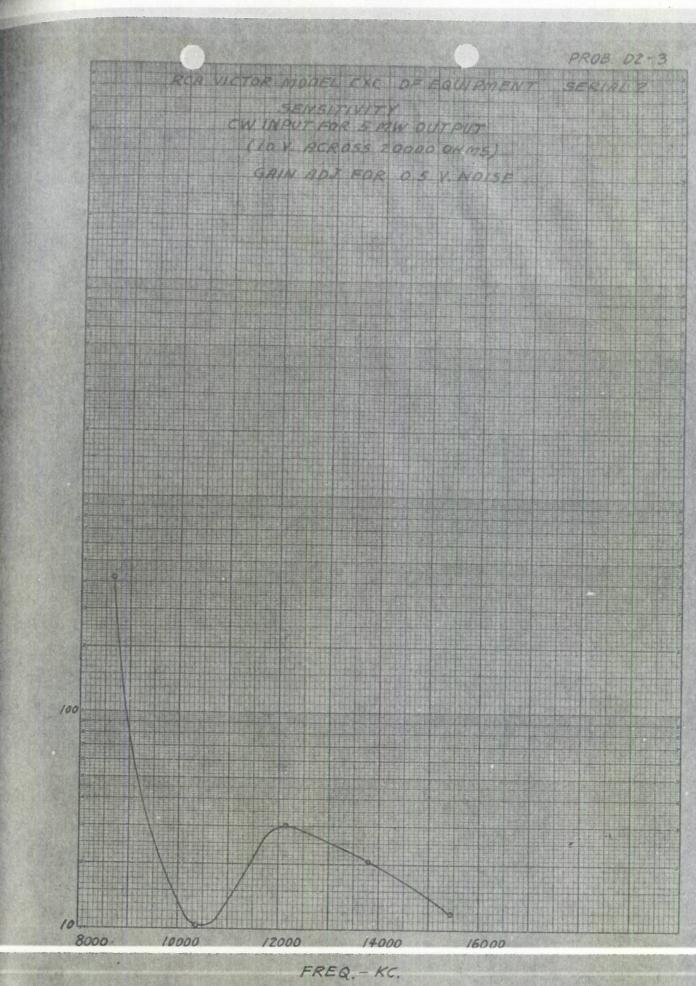
It is, however, believed that a test made at this location will in all probability not give a full representation of the limitations of the equipment when used under Naval Service conditions, such as at sea, or on shore in taking bearings over water.

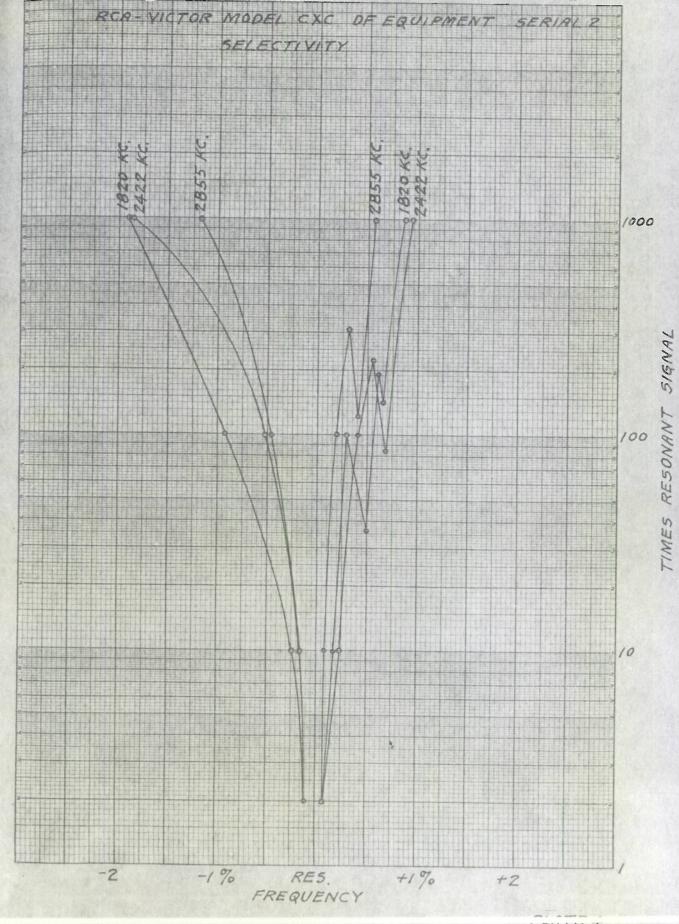
Topographical and other conditions in this vicinity are such as to produce erratic distortions in the wave front and investigations have shown that receiving conditions in this locality are seriously affected by dead spots and other influences due to the irregular combinations of land and water in the paths of transmission.

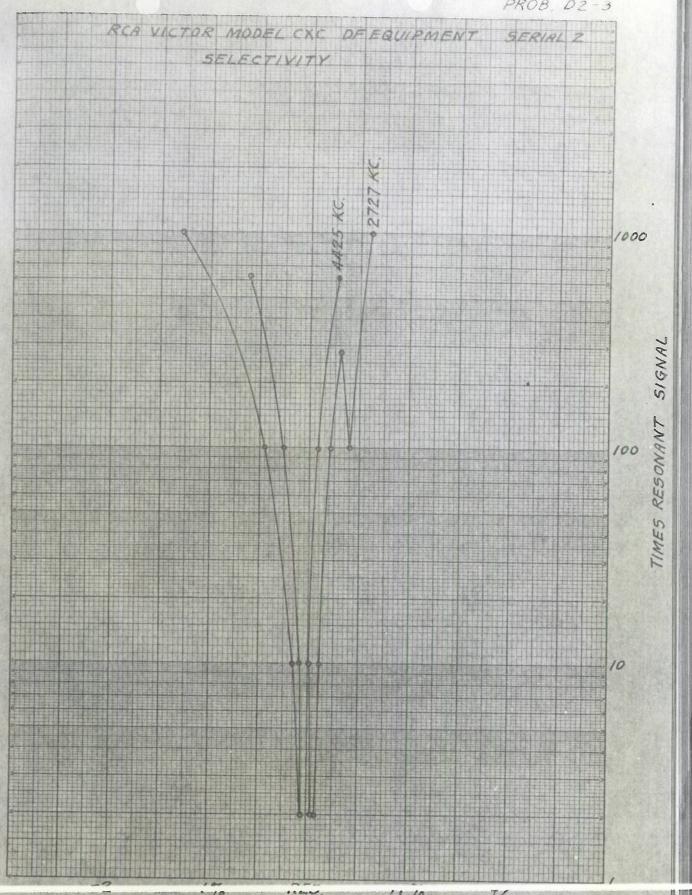
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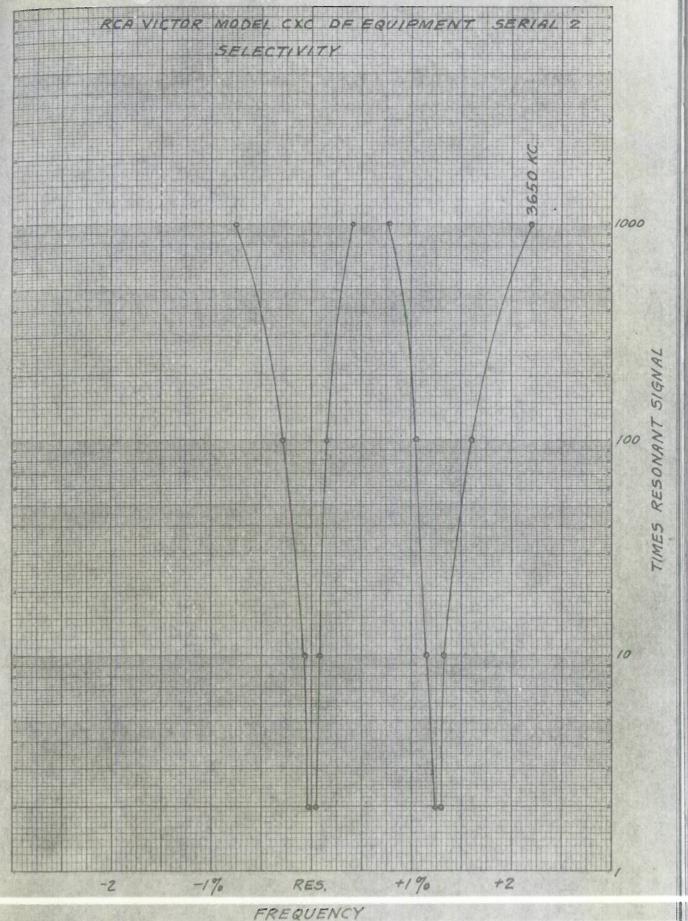


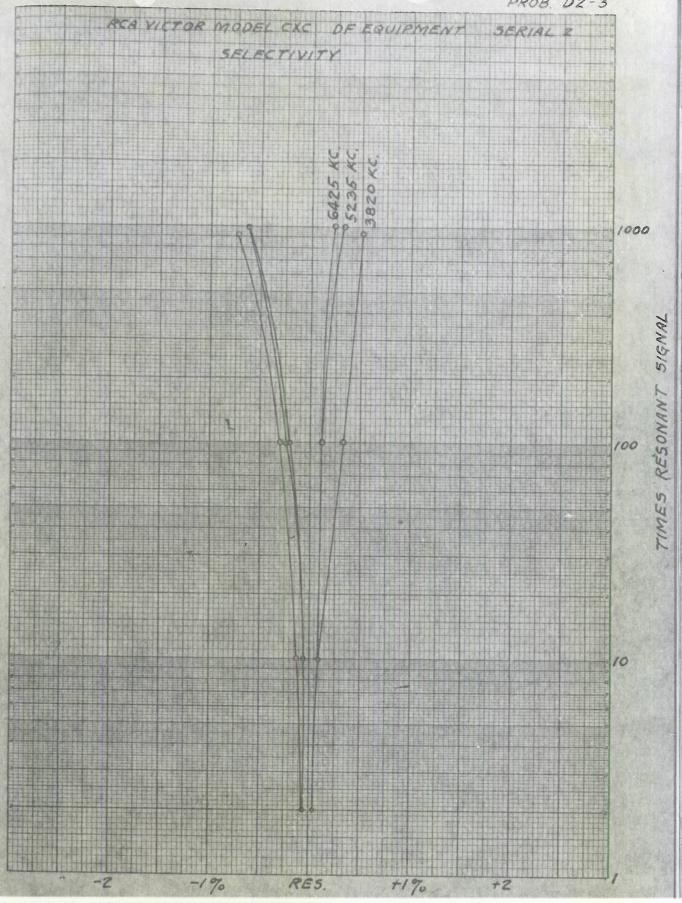


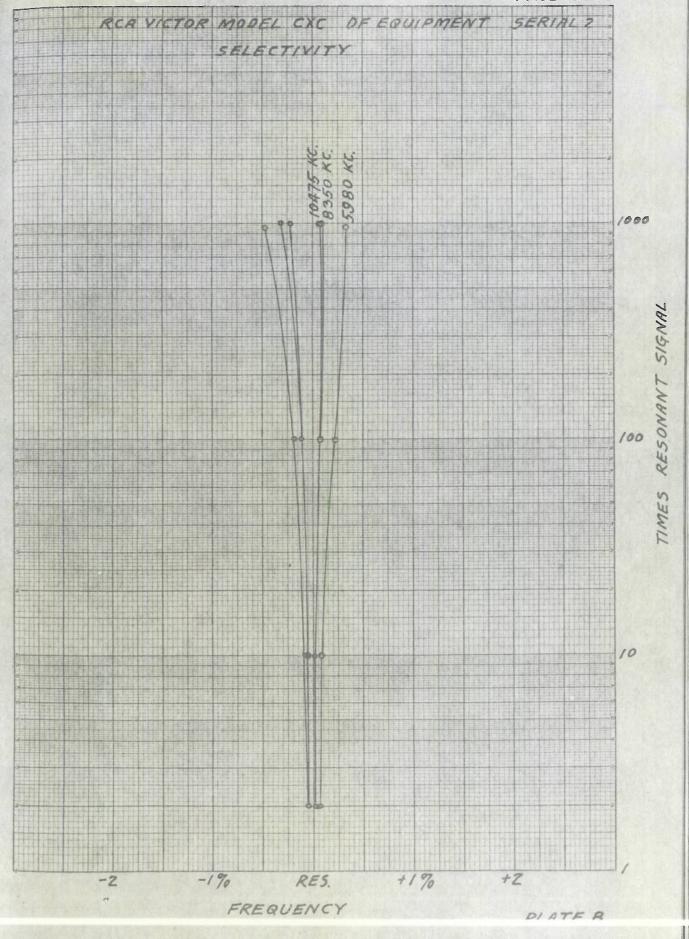


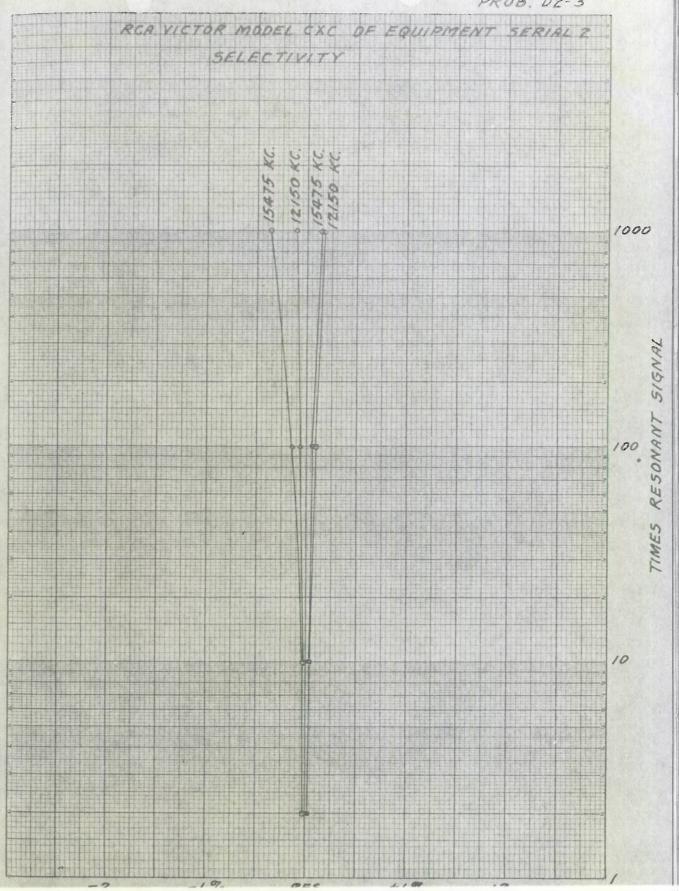


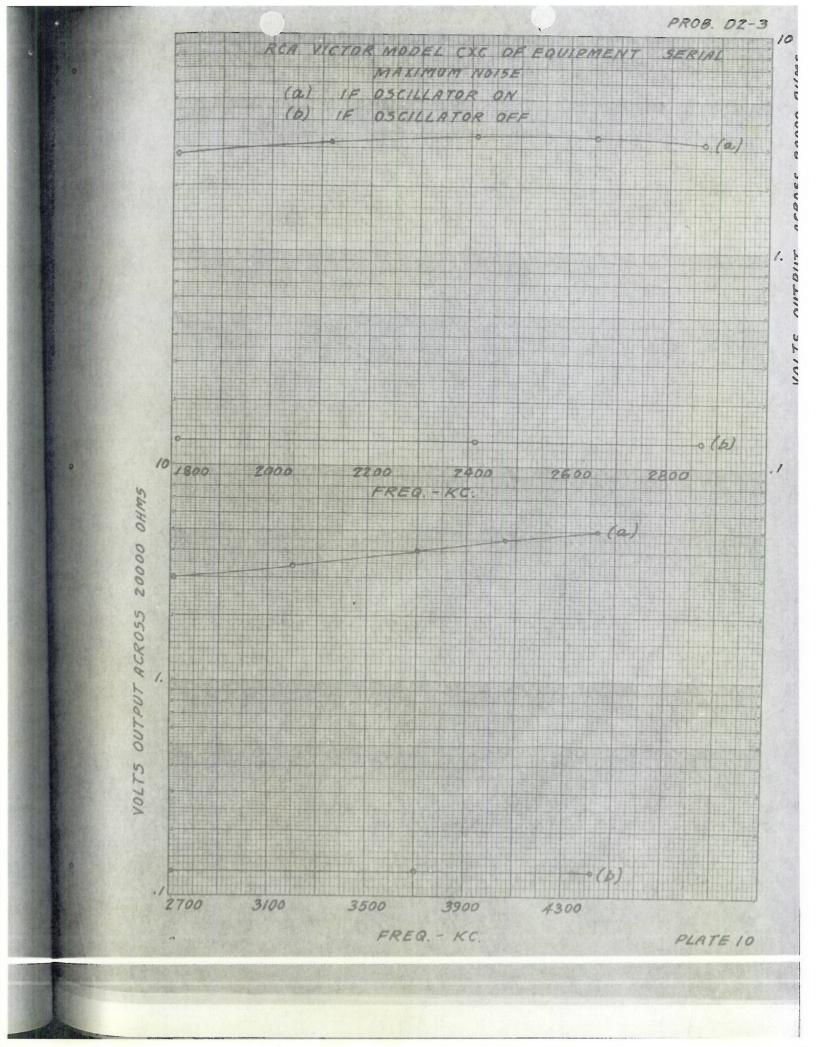


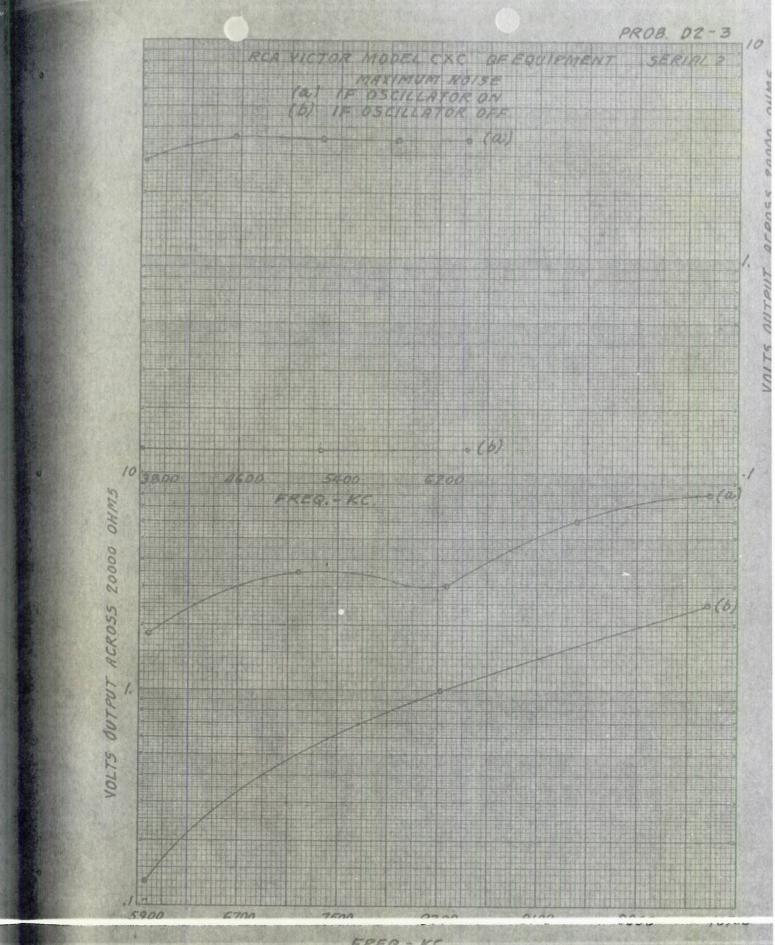


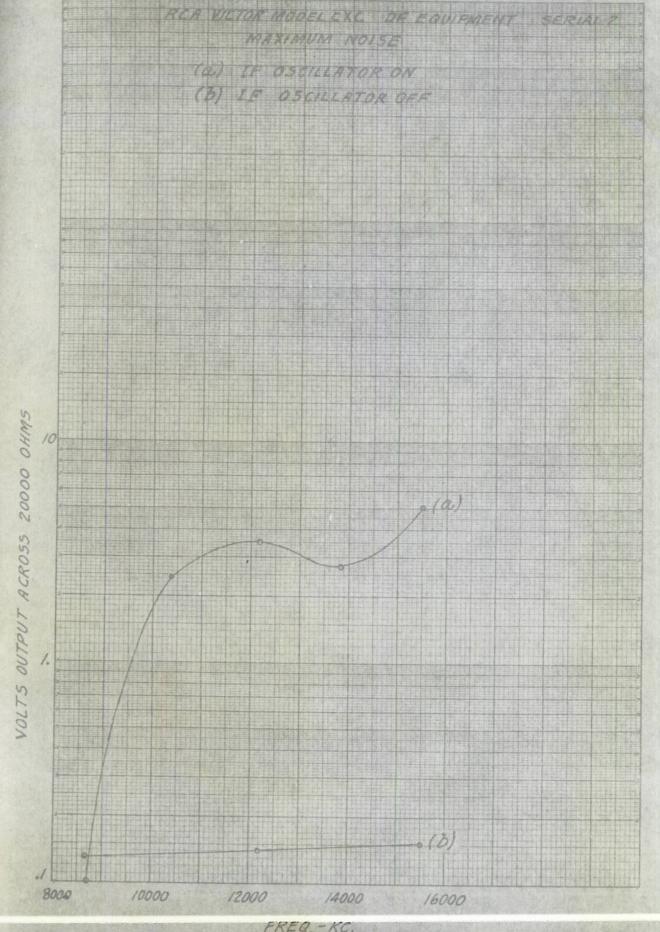












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