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S6801 USER'S GUIDE

Version 1.0

STATIC ANALYSIS OF PLANE FRAME AND TRUSS STRUCTURES

by

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PREFACE

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INTRODUCTION

S6801 is a plane frame and truss structural analysis program that is limited to static loads. It computes the displacements and the member end actions for each end of each member. The member end actions include the axial and shear forces, and the in-plane moment. The program is unique since the problem is posed with respect to the member. This means the user describes the problem member by member instead of building separate data tables and relating the tables to complete the problem description.

CAPABILITIES

S6801 is a static analysis program for plane frame and truss structures. It computes the member end actions and displacements for each member. The member end actions include the axial load, the shear load, and the bending moment quantities at each end of the member. The displacements include the horizontal and vertical displacement as well as the end rotation.

Member information is used by the user to pose the problem to the program. This means the section properties, displacement degrees of freedom, boundary conditions, joint coordinates, and load information are all associated with the member. This method of input is unique when compared to most frame analysis programs where most of this information is described in separate tables. The separate tables are then related using node numbers, member numbers, section property numbers, material type numbers, and member load case numbers.

This program allows loads to be applied to the joints and the members. The joint loads include horizontal and vertical forces, and the in-plane moment. The member loads include uniformly distributed horizontal and vertical loads, and horizontal and vertical concentrated loads applied at any location along the member length. This program calculates end actions of sloped members using actual (sloped) member lengths as compared to the use of projected member lengths.

The program only permits one modulus of elasticity, thus it cannot be used to analyze problems that contain more than one material.

Currently, the size of the problem is limited to the following: 200 members, 175 displacements, and nine load cases.

SOLUTION METHOD

The program employs the stiffness method of analysis. This method is fully described in most structural analysis textbooks, some of which are dedicated to the analysis of framed structures. It is assumed that the user is familiar with this method of analysis.

The solution process requires development of three matrices. The structure stiffness matrix is formed from the member section property

and material information. The applied loads are used to form the load matrix or vector. The unknown displacements are determined using Gaussian elimination. The displacement results are used to compute the internal forces and moments at each end of each member.

PROBLEM DATA PREPARATION

A sketch of the structure model is prepared. Each member is numbered, the order is not important but the sequence must be without gaps. The permissible displacements and rotations at each end of each member are numbered, again in a sequence without gaps. The following rules apply to the displacement and rotation scheme:

- 1. A member end release option may be employed. This means the "end 1" may be pinned (released) instead of fixed, while "end 2" always remains fixed. When the end release option is used, one must ensure the displacement numbering is consistent, which means there must not be a rotational displacement number assigned to the released end.
- 2. A displacement number is not assigned to a rotation that is associated with a pin.
- 3. Reactions are considered fixed, therefore a displacement number cannot be assigned.
- 4. Free ends (cantilever) are assigned a "pinned" condition and given x and y displacement numbers (see line type C), but no rotation numbers.
- 5. Enter a cross-sectional area for a member even though in some cases it is arbitrary and doesn't affect the solution.
- 6. Hinged ends of members are assigned a pinned condition and given a y displacement number and a z rotation number.

A second sketch is recommended for the loading conditions. In fact, each load case (multiple load conditions) might have a separate sketch. The following loading rules apply:

- 1. The forces are applied in the direction of the structure x and y axes, the moments are applied about the z axis (i.e., in the plane of the structure).
- 2. The forces and moments must be resolved into components that coincide with the direction of the structure axes.
- 3. The positive direction of the forces coincides with the positive direction of the x and y axis. The x forces are positive to the right, the y forces are positive up. The moments are positive with respect to the right-hand rule where the x axis is crossed into the y axis to determine the positive rotation of the moment.
- 4. The forces due to gravity are always in the negative y direction.

- 5. Joint loads may be entered with the load data for any member that frames into the joint; however, the load must only be entered once.
- 6. When locating member concentrated loads, use the direction measured from "end 1" to "end 2" as positive.

The data definition lines are required to describe the problems that will be analyzed. These lines can be prepared using a word processor, a screen editor, or a line editor. A right-hand tabulation feature is suggested to simplify insuring the data are entered in the proper field. The prepared data file must contain only alphanumeric characters, no special or nonprinting characters are permitted. Each of the lines are described below.

Line Type A:

A title consisting of up to 66 characters

Line Type B:

<u>Variable</u>	Column	Description
E	1 - 10	Modulus of elasticity (ksi) for all members
NM	11 - 15	Total number of members in the model
NU	16 - 20	Total number of displacements
NL	21 - 25	Total number of load cases

Line Type C:

Line Type C thru Line Type G are repeated as a group for each member, NM times.

<u>Variable</u>	Column	<u>Description</u>
NC(1) NC(2) NC(3) NC(4) NC(5) NC(6) DX(J,1) DY(J,1)	1 - 5 6 - 10 11 - 15 16 - 20 21 - 25 26 - 30 31 - 40 41 - 50	Horizontal displacement number at End 1 of the member Vertical displacement number at End 1 of the member Rotational displacement number at End 1 of the member Horizontal displacement number at End 2 of the member Vertical displacement number at End 2 of the member Rotational displacement number at End 2 of the member X coordinate (FT) of the member End 1 Y coordinate (FT) of the member End 1
DX(J,2) DY(J21)	51 - 60 61 - 70	X coordinate (FT) of the member End 2 Y coordinate (FT) of the member End 2

Line Type D:

<u>Variable</u>	Column	Description
NM	1 - 5	Member number
AM	6 - 15	Member cross-section area (in. 2)
XI	16 - 25	Member moment of inertia about the Z axis (in. 4)
KL	26 - 30	Member End 1 fixity: 0 = pinned, 1 = fixed
KU	31 - 35	Member End 2 fixity: 0 = pinned, 1 = fixed

Line Type E:

Line Type E is repeated NL times

<u>Variable</u>	Column	Description
UV	1 - 10	Value of uniformly distributed vertical load (kips/ft)
UH	11 - 20	Value of uniformly distributed horizontal load (kips/ft)
NPV	21 - 25	Total number of vertical concentrated member loads
NPH	26 - 30	Total number of horizontal concentrated member loads
JL	31 - 35	Joint load location:
		None $JL = 0$
		End 1 $JL = 1$
		End 2 $JL = 2$

Line Type F:

Line Type F is required only for joint loads as indicated by the JL parameters in Line Type E.

<u>Variable</u>	Column	Description
ACT(1) ACT(2) ACT(3)	11 - 20	Value of horizontal joint force (kips) Value of vertical joint force (kips) Value of joint moment (kip ft)

Line Type G:

Line Type G is repeated NPV plus NPH times. NPV and NPH are parameters found on Line Type E. Vertical loads are grouped and ordered first.

<u>Variable</u>	Column	Description
A	1 - 10	Value of concentrated force (kips)
В	11 - 20	Location of the force measured from the member End 1 toward the member End 2 (ft)

EXECUTION INSTRUCTIONS

The program is designed to run on an IBM PC compatible personal computer having at least 512K memory and a math coprocessor. There are a number of ways to execute the program, each will be discussed.

Installation

The S6801 program is on a single diskette containing:

S6801.EXE	The executable program.
TRUSS.DAT	Truss sample problem.
FRAME DAT	Frame sample problem

BUILDING. DAT A building frame sample problem.

RUNS6801.BAT The batch execute file.

RMFORT, ERR The execution error message file.

These files should be copied to the hard disk or to another floppy disk before the program is used. The standard DOS COPY Command can be used:

COPY A:*.* C: For the hard disk COPY A:*.* B: For the floppy disk

The program is now ready to run using one of the methods described below.

Standard Execution

The standard way of executing the program involves preparing an input file and running the program with the print output going to a file. The program assumes the input data is contained in the file S6801.DAT. The data can be prepared using any line or screen editor program, such as the DOS EDLIN editor. The user should prepare this file using the S6801.DAT file name, or the input can be prepared using any file name, and then copying the prepared file to S6801.DAT by using the standard DOS COPY Command. The program will write the print output to \$6801.0UT. The S6801.OUT file can be printed using the standard DOS PRINT Command. The program, S6801.EXE, is executed by typing S6801.

Output Redirection

The user can use the DOS SET Command to redirect the output. default input, output, and plot file names can be changed by:

SET S6801.DAT= your input file name SET S6801.OUT= your output file name

Then the program can be run by the S6801 command. CAUTION! The DOS redirection mechanism is active for the duration of the run of the program. The SET Command stays set until the connection is broken in the following manner, or through a system reboot:

SET S6801.DAT= SET S6801.OUT=

Batch File Execution

The program can be run with a batch file. For example, the batch file might be called RUNS6801.BAT, and it would contain:

SET S6801.DAT=%1 SET S6801.OUT=LPT1 S6801

SET S6801.DAT=

SET S6801.OUT=

The program would then be executed by the command:

RUNS6801 <your data file name>

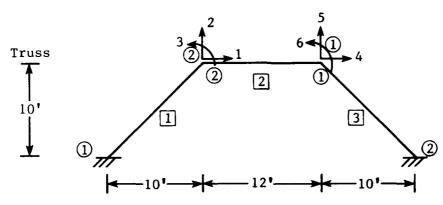
SAMPLE PROBLEMS

Three sample problems are provided to demonstrate the capabilities of the program. They will also help demonstrate how to prepare the data for the program. A typical truss problem is provided in Appendix A. Appendix B shows a typical frame program. A typical rigid frame two-story building is shown in Appendix C. Each appendix provides a sketch of the structural model and the loading conditions. The problem data file is presented along with the respective output information.

ACKNOVLEDGMENT

The General Electric Company gave the original version of S6801 to the Naval Facilities Engineering Command in 1968. Mr. Frank E. Eby enhanced the original version of the program and made it available to the Engineering Field Divisions through commercial time sharing computer service bureaus. Mr. Steve Davis of the Naval Civil Engineering Laboratory converted the program to operate on a microcomputer. He also reformatted the output to improve its readability. Mr. Troy E. Gillium validated the test problems.

Appendix A TRUSS SAMPLE PROBLEM



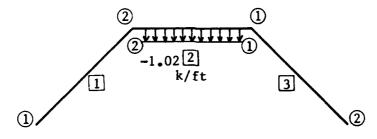
1 Member Number

End Number

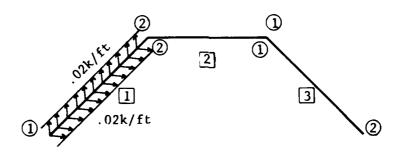
Number

Displacement

Load Case 1



Load Case 2



Load Case 3

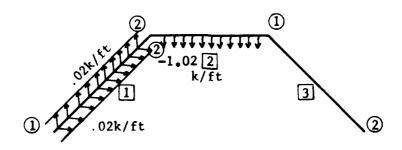


Figure A-1. Truss sample problem.

DATA INPUT FILE

							CO	OLUMN			
LINE		1		2		3	4	5	6	7	8
TYPE	1234567	89012	3456	5789012	34567	89012	34567890123	3456789012:	3456789012:	345678901234 	567890
A	FRAME S	AMPLE	PRO	DBLEM C	NE	<u>.</u>					
В	1500	.00	3	6	3						
C-1	0	0	0	1	2	3	0.00	0.00	10.00	10.00	
D-1	1	352	.00	14197	.00	1	1				
E-1.1	o	.00		0.00	0	0	0				
E-1.2) 0	.02		0.02	0	0	0				
E-1.3	o	.02		0.02	0	0	0				
C-2	4	5	6	1	2	3	22.00	10.00	10.00	10.00	
D-2	2	352	.00	14197	7.00	1	1				
E-2.1	-1	.02		0.00	0	0	0				
E-2.2) 0	.00		0.00	0	0	0				
E-2.3	-1	.02		0.00	0	0	0				
C-3	4	5	6	0	0	0	22.00	10.00	32.00	0.00	
D-3	3	352	.00	14197	7.00	1	1				
E-3.1	lo	.00		0.00	0	0	0				
E-3.2	1	.00		0.00	0	0	0				
E-3.3	L	.00		0.00	0	0	0				

TRUSS SAMPLE PROBLEM

MODULUS OF ELASTIC TOTAL NUMBER OF ME TOTAL NUMBER OF JO TOTAL NUMBER OF LO	MBERS DINT DISPLACE	ements		00 KSI 3 6 3	
MEMBER NUMBER AREA MOMENT OF INERTI	1	352.00 14197.00	IN.**2 IN.**4		
DISPLACEME HORIZONTAL V	NT IDENTIFICERTICAL ROTE	ATIONAL		COORDINATES X 0.00	Y
END 1 0 END 2 1	2	-	1		
LOAD CASE NUMBER UNIFORM VERTICA UNIFORM HORIZON NUMBER OF CONCE NUMBER OF CONCE JOINT LOAD APPI	AL LOAD ITAL LOAD INTRATED VER' INTRATED HOR	IZONTAL LO			
LOAD CASE NUMBER UNIFORM VERTICA UNIFORM HORIZON NUMBER OF CONCE NUMBER OF CONCE JOINT LOAD APPI	AL LOAD ITAL LOAD ENTRATED VER ENTRATED HOR	IZONTAL L			
LOAD CASE NUMBER UNIFORM VERTICA UNIFORM HORIZON NUMBER OF CONCE NUMBER OF CONCE JOINT LOAD APPI	AL LOAD TTAL LOAD ENTRATED VER ENTRATED HOR	IZONTAL L			

MEMBER NUMBER	2		
AREA		352.00	IN.**2
MOMENT OF INERTIA		14197.00	IN. **4

MOMENT	OF INERTIA		14197.0	0 IN.**4		
	DISPLACEMEN RIZONTAL VE				COORDINATES X	, , ,
END 1		KIICAL KU)IAIIUNAL	1	22.00	
END 2		2	-	1	10.00	
DIND Z	•	4	3	•	10.00	10.00
LOAD CA	SE NUMBER	1				
UNIFO	RM VERTICAL	LOAD			-1.02	KIPS/FT
UNIFO	RM HORIZONT	AL LOAD			0.00	KIPS/FT
NUMBE	R OF CONCEN	TRATED VE	RTICAL LO	ADS	0	
	R OF CONCEN			LOADS	0	
JOINT	LOAD APPLI	ED TO MEM	IBER END		0	
LOAD CA	SE NUMBER	2				
	RM VERTICAL				0.00	KIPS/FT
	RM HORIZONT					KIPS/FT
NUMBE	R OF CONCEN	TRATED VE	RTICAL LO	ADS	0	•
NUMBE	R OF CONCEN	TRATED HO	RIZONTAL	LOADS	0	
JOINT	LOAD APPLI	ED TO MEM	IBER END		0	
UNIFO	SE NUMBER RM VERTICAL	LOAD				KIPS/FT
	RM HORIZONT					KIPS/FT
	R OF CONCEN				0	
	R OF CONCEN LOAD APPLI			LOADS	0	
MEMBER 1	NUMBER	3				
AREA				0 IN.**2		
MOMENT	OF INERTIA	•	14197.0	0 IN.**4		
	DISPLACEMEN RIZONTAL VE			END FIXITY	COORDINATES	(FEET)
END 1		5	6	1	22.00	10.00
END 2	0	0	Ō	1	32.00	0.00
LOAD CAS	SE NUMBER	1				
	RM VERTICAL	LOAD			0.00	KIPS/FT
UNIFO	RM HORIZONT	AL LOAD				KIPS/FT
NUMBE	R OF CONCEN	TRATED VE	RTICAL LO	ADS	0	•
NUMBE	R OF CONCEN	TRATED HO	RIZONTAL	LOADS	0	
JOINT	LOAD APPLI	ED TO MEM	IBER END		0	

UNIFORM VERTICAL LOAD 0.00 KIPS	•
UNIFORM HORIZONTAL LOAD 0.00 KIPS	S/FT
NUMBER OF CONCENTRATED VERTICAL LOADS 0	
NUMBER OF CONCENTRATED HORIZONTAL LOADS 0	
JOINT LOAD APPLIED TO MEMBER END 0	
LOAD CASE NUMBER 3 UNIFORM VERTICAL LOAD 0.00 KIPS	ያ/ም
UNIFORM HORIZONTAL LOAD 0.00 KIPS	•
NUMBER OF CONCENTRATED VERTICAL LOADS 0	-,
NUMBER OF CONCENTRATED HORIZONTAL LOADS 0	
JOINT LOAD APPLIED TO MEMBER END 0	

			END 1			END 2	
LOAD CASE	MEMBER NUMBER	AXIAL FORCE (KIPS)	SHEAR (KIPS)	MOMENT (KIP-FT)	AXIAL FORCE (KIPS)	SHEAR (KIPS)	MOMENT (KIP-FT)
1	1	9.35	-0.70	-2.74	-9.35	0.70	-7.10
2	1	-0.40	0.00	-0.01	0.00	0.00	-0.01
3	1	8.95	-0.70	-2.75	-9.35	0.70	-7.11
1	2	7.10	-6.12	-7.10	-7.10	-6.12	7.10
2	2	0.00	0.00	0.00	0.00	0.00	0.01
3	2	7.11	-6.12	-7.11	-7.11	-6.12	7.11
1	3	9.35	0.70	7.10	-9.35	-0.70	2.74
2	3	0.00	0.00	0.00	0.00	0.00	0.01
3	3	9.35	0.70	7.11	-9.35	-0.70	2.75

JOINT DISPLACEMENTS

			RNO I			KND Z	
LOAD CASE	MEMBER Number	HOR I ZONTAL FEET	VERTICAL FEET	ROTATION RADIANS	HORIZONTAL FEET	VERTICAL FEET	ROTATION RADIANS
1	1	0.00000	0.00000	0.00000	0.00008	-0.00043	-0.00021
2	1	0.00000	0.00000	0.00000	0,00000	0.00000	0.00000
3	1	0.00000	0.00000	0.00000	80000,0	-0.00043	-0.00021
1	2	-0.00008	-0.00043	0.00021	0.00008	-0,00043	-0.00021
2	2	0.00000	0.00000	0,00000	0,00000	0.00000	0.00000
3	2	-0.00008	-0.00043	0.00021	0.00008	-0.00043	-0.00021
1	3	-0.00008	-0.00043	0.00021	0,00000	0.00000	0.00000
2	3	0.00000	0.00000	0.00000	0,00000	0.00000	0.00000
3	3	-0.00008	-0.00043	0.00021	0.00000	0.00000	0.00000

Appendix B FRAME SAMPLE PROBLEM

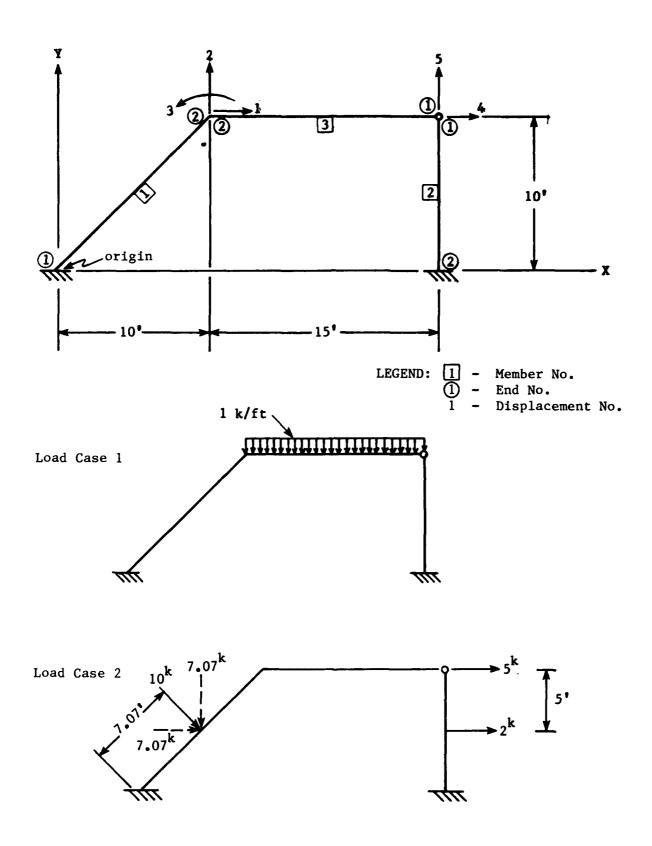


Figure B-1. Frame sample problem.

DATA INPUT FILE

	COLUMN									
LINE	1	l	. 2		3	4	5	6	7	8
TYPE	1234567890	12345	6789 0:	12345	6789012	23456789012	2345678901	2345678901	2345678901	234567890
- A	FRAME SAMI	PLE PR	ORLEM	TWO						
В	30000.00			2	•					
C-1	0 (_	2	3	0.00	0.00	10.00	10.00	
D-1	1	10.00	10	00.00	1	1				
E-1.1	0.00)	0.00	0	0	0				
E-1.2	0.00)	0.00	1	1	0				
G-1.2V	-7.07	7	7.07							
G-1.2H	7.07	7	7.07							
C-2	4 5	5 0	.0	0	0	25.00	10.00	25.00	0.00	
D-2	2	10.00	10	00.00	0	1				
E-2.1	0.00)	0.00	0	0	0				
E-2.2	0.00)	0.00	0	1	1				
F-2.2	5.00)	0.00		0.00					
G-2.2H	2.00		5.00							
C-3	1 ' -	5 0	_	2	3	25.00	10.00	10.00	10.00	
D-3	3	10.00		00.00	0	1				
E-3.1	-1.00		0.00	0	0	0				
E-3.2	0.00)	0.00	0	0	0				

FRAME SAMPLE PROBLEM

MODULUS OF ELAST: TOTAL NUMBER OF I TOTAL NUMBER OF I	MEMBERS JOINT DISPLACE	30000.0 3 5 2	3		
MEMBER NUMBER	1	10.00	TN 440		
AREA MOMENT OF INER	ΓΙA		IN.**2 IN.**4		
	MENT IDENTIFIC VERTICAL ROTA			COORDINATES X	Y
END 1 0 END 2 1	0 2	0 3	1 1	0.00 10.00	0.00 10.00
END 2 1	2	3	1	10.00	10.00
LOAD CASE NUMBER UNIFORM VERTIC UNIFORM HORIZONUMBER OF CONC NUMBER OF CONC JOINT LOAD AP	CAL LOAD ONTAL LOAD CENTRATED VERT CENTRATED HORT	ZONTAL L			IPS/FT IPS/FT
LOAD CASE NUMBER					
UNIFORM VERTICUNIFORM HORIZ					IPS/FT IPS/FT
NUMBER OF CON		rical Loa	DS	0.00 K	IFB/FI
NUMBER OF CON	CENTRATED HOR	IZONTAL L		1	
JOINT LOAD AP	PLIED TO MEMBI	ER END		0	
CONCENTRATED ME (KIPS)	MBER LOAD	DISTANCE (FEE		1	
	VERTICAL				
-7.07		7	. 07		
	HORIZONTAL				
7.07		7	. 07		

MEMBER NUMBER 2
AREA 10.00 IN.**2
MOMENT OF INERTIA 100.00 IN.**4

DISPLACEMENT IDENTIFICATION END COORDINATES (FEET) HORIZONTAL VERTICAL ROTATIONAL FIXITY X Y END 1 5 0 0 25.00 10.00 END 2 0 0 0 1 25.00 0.00 LOAD CASE NUMBER

UNIFORM VERTICAL LOAD 0.00 KIPS/FT
UNIFORM HORIZONTAL LOAD 0.00 KIPS/FT
NUMBER OF CONCENTRATED VERTICAL LOADS 0
NUMBER OF CONCENTRATED HORIZONTAL LOADS 0
JOINT LOAD APPLIED TO MEMBER END 0

LOAD CASE NUMBER 2

UNIFORM VERTICAL LOAD 0.00 KIPS/FT

UNIFORM HORIZONTAL LOAD 0.00 KIPS/FT

NUMBER OF CONCENTRATED VERTICAL LOADS 0

NUMBER OF CONCENTRATED HORIZONTAL LOADS 1

JOINT LOAD APPLIED TO MEMBER END 1

HORIZONTAL JOINT LOAD 5.00 KIPS
VERTICAL JOINT LOAD 0.00 KIPS
ROTATIONAL JOINT LOAD 0.00 KIPS

CONCENTRATED MEMBER LOAD DISTANCE FROM END 1 (KIPS)

HORIZONTAL

2.00 5.00

MEMBER NUMBER 3

AREA 10.00 IN.**2

MOMENT OF INERTIA 100.00 IN.**4

DISPLACEMENT IDENTIFICATION END COORDINATES (FEET) HORIZONTAL VERTICAL ROTATIONAL FIXITY X Y 10.00 END 1 5 0 0 25.00 1 2 3 END 2 1 10.00 10.00

LOAD CASE NUMBER 1	
UNIFORM VERTICAL LOAD	-1.00 KIPS/FT
UNIFORM HORIZONTAL LOAD	0.00 KIPS/FT
NUMBER OF CONCENTRATED VERTICAL LOADS	0
NUMBER OF CONCENTRATED HORIZONTAL LOADS	0
JOINT LOAD APPLIED TO MEMBER END	0
LOAD CASE NUMBER 2	
UNIFORM VERTICAL LOAD	0.00 KIPS/FT
UNIFORM HORIZONTAL LOAD	0.00 KIPS/FT
NUMBER OF CONCENTRATED VERTICAL LOADS	0
NUMBER OF CONCENTRATED HORIZONTAL LOADS	0
JOINT LOAD APPLIED TO MEMBER END	0

			END 1	END 2				
LOAD CASE	MEMBER NUMBER	AXIAL FORCE (KIPS)	SHEAR (KIPS)	MOMENT (KIP-FT)	AXIAL FORCE (KIPS)	SHEAR (KIPS)	MOMENT (KIP-FT)	
1	1	7.03	2.63	27.18	-7.03	-2.63	10.04	
2		-2.61	10.68	59.94	2.61	-0.68	20.43	
1	2	8.17	3.11	0.00	-8.17	-3.11	31.10	
2	2	1.36	2.67	0.00	-1.36	-4.67	36.70	
1	3	3.11	-8.17	0.00	-3.11	-6.83	-10.04	
2	3	-2.33	-1.36	0.00	2.33	1.36	-20.43	

JOINT DISPLACEMENTS

			END 1			END 2	
LOAD CASE	MEMBER Number	HORIZONTAL FEET	VERTICAL FEET	ROTATION RADIANS	HORIZONTAL FEET	VERTICAL FEET	ROTATION RADIANS
1	1	0.00000	0.00000	0.00000	0.04991	-0.05038	-0.00582
2	1	0.00000	0.00000	0.00000	0.05260	-0.05243	-0.00141
1	2	0.04975	-0.00027	0.00000	0.00000	0.00000	0.00000
2	2	0.05272	-0.00005	0.00000	0.00000	0.00000	0.00000
1	3	0.04975	-0.00027	0.00000	0.04991	-0.05038	-0.00582
2	3	0.05272	-0.00005	0.00000	0.05260	-0.05243	-0.00141

Appendix C BUILDING SAMPLE PROBLEM

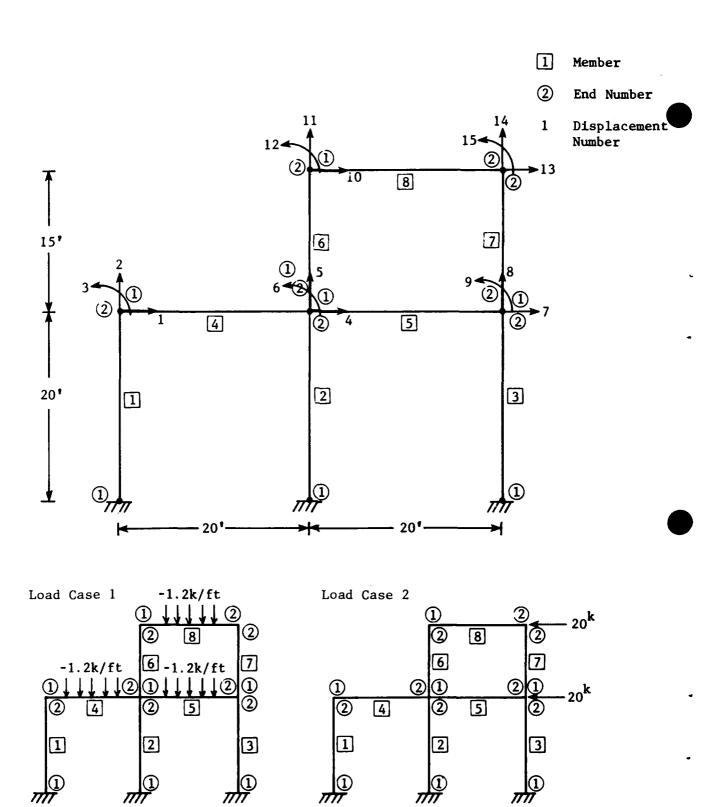


Figure C-1. Building sample problem.

DATA INPUT FILE

						C	OLUMN			
LINE		1	2		3	•	5	6	7	8
TYPE	123456789	012345	67890123	456	789012	3456789012	34567890123	34567890123	34567890123	4567890
A	FRAME SAM	PLE PRO	OBLEM TH	REE			· · · · · · · · · · · · · · · · · · ·			
В	30000.0	0 8	15	2						
C-1	0	0 0	1	2	3	0.00	0.00	0.00	20.00	
D-1	1	20.00	200.	00	1	1				
E-1.1	0.0	0	0.00	0	0	0				
E-1.2	0.0	0	0.00	0	0	0				
C-2	l o	0 0	4	5	6	20.00	0.00	20.00	20.00	
D-2	2	20.00	200.	00	1	1				
E-2.1	0.0	0	0.00	0	0	0				
E-2.2	0.0	0	0.00	0	0	0				
C-3	l o	0 0		8	9	40.00	0.00	40.00	20.00	
D-3	3	20.00	200.	00	1	1				
E-3.1	0.0		0.00	0	0	0				
E-3.2	0.0	0	0.00	0	0	2				
F-3.2	-20.0	0	0.00		0.00					
C-4		2 3		5	6	0.00	20.00	20.00	20.00	
D-4	4	10.00	300.	00	1	1				
E-4.1	-1.2		0.00	0	0	0				
E-4.2	0.0	0	0.00	0	0	0				
C-5	4	5 6	7	8	9	20.00	20.00	40.00	20.00	
D-5	5	10.00	300.	00	1	1				
E-5.1	-1.2	0	0.00	0	0	0				
E-5.2	0.0	0	0.00	0	0	0				
C-6	4	5 6	10	11	12	20.00	20.00	20.00	35.00	
D-6	6	20.00	180.	00	1	1				
E-6.1	0.0	0	0.00	0	0	0				
E-6.2	0.0	0	0.00	0	0	0				
C-7	7	8 9	13	14	15	40.00	20.00	40.00	35.00	
D-7	7	20.00	180.	00	1	1				
E-7.1	0.0	0	0.00	0	0	0				
E-7.2	0.0	0	0.00	0	0	2				
F-7.2	-20.0		0.00		0.00					
C-8		1 12		14	15	20.00	35.00	40.00	35.00	
D-8	L		300.		1	1				
E-8	-1.2		0.00	0	0	0				
E-8	0.0		0.00	0	0	0				

BUILDING SAMPLE PROBLEM

MODULUS OF E KSI TOTAL NU TOTAL NUMBER TOTAL NUMBER	MBER OF ME OF JOINT	30000.0 8 15 2	0			
MEMBER NUMBE AREA MOMENT OF		1		IN.**2 IN.**4		
	LACEMENT 1				COORDINATES	G (FEET)
END 1	0	0	0		0.00	0.00
	1	2	3		0.00	
UNIFORM H NUMBER OF NUMBER OF JOINT LOA	ERTICAL LO ORIZONTAL CONCENTRA CONCENTRA D APPLIED	DAD LOAD ATED VERTI ATED HORIZ TO MEMBER	ONTAL L			KIPS/FT KIPS/FT
LOAD CASE N	ERTICAL LO				0.00	KIPS/FT
	ORIZONTAL					KIPS/FT
	CONCENTRA		CAL LOA	DS	0	
NUMBER OF	CONCENTRA	ATED HORIZ	ONTAL L	OADS	0	
JOINT LOA	D APPLIED	TO MEMBER	END		0	
MEMBER NUMBE	R	2				
AREA				IN.**2		
MOMENT OF	INERTIA		200.00	IN.**4		

0

6

END

1

1

FIXITY

COORDINATES (FEET)

X

20.00

20.00

Y

0.00

20.00

DISPLACEMENT IDENTIFICATION

0

5

HORIZONTAL VERTICAL ROTATIONAL

0

END 1

END 2

LOAD CASE NUMBER UNIFORM VERTICAL LOAD UNIFORM HORIZONTAL LOAD NUMBER OF CONCENTRATED NUMBER OF CONCENTRATED JOINT LOAD APPLIED TO	D VERTICAL LOAD HORIZONTAL LO			KIPS/FT KIPS/FT
LOAD CASE NUMBER UNIFORM VERTICAL LOAD UNIFORM HORIZONTAL LOAD NUMBER OF CONCENTRATED NUMBER OF CONCENTRATED JOINT LOAD APPLIED TO	D VERTICAL LOAD HORIZONTAL LO			KIPS/FT KIPS/FT
MEMBER NUMBER 3 AREA MOMENT OF INERTIA	20.00 200.00	IN.**2 IN.**4		
DISPLACEMENT IDEN HORIZONTAL VERTICAL END 1 0 0 END 2 7 8	ROTATIONAL	FIXITY 1	X 40.00	Y 0.00
LOAD CASE NUMBER UNIFORM VERTICAL LOAD UNIFORM HORIZONTAL LOA NUMBER OF CONCENTRATED NUMBER OF CONCENTRATED JOINT LOAD APPLIED TO	D VERTICAL LOAI HORIZONTAL LO			KIPS/FT KIPS/FT
LOAD CASE NUMBER UNIFORM VERTICAL LOAD UNIFORM HORIZONTAL LOAD NUMBER OF CONCENTRATED NUMBER OF CONCENTRATED JOINT LOAD APPLIED TO HORIZONTAL JOINT LOAD VERTICAL JOINT LOAD ROTATIONAL JOINT LOAD	VERTICAL LOAD HORIZONTAL LO		0.00 0 0 2 -20.00 0.00	KIPS/FT KIPS/FT KIPS KIPS KIPS

MEMBER AREA MOMEN		R INERTIA	4		IN.**2 IN.**4		
END 1 END 2	IOR I ZO		IDENTIFICA ICAL ROTAT 2 5		FIXITY 1	COORDINATES X 0.00 20.00	Y 20.00
UNIF UNIF NUME NUME	FORM V FORM H BER OF BER OF	CONCENTR	OAD	ONTAL LO		-1.20 K 0.00 K 0 0	IPS/FT IPS/FT
UNIF UNIF NUME NUME	FORM V FORM H BER OF BER OF	CONCENTR	OAD	ONTAL LO			IPS/FT IPS/FT
MEMBER AREA MOMEN		R INERTIA	5		IN.**2 IN.**4		
		NTAL VERT	IDENTIFICAT	IONAL	FIXITY	COORDINATES	Y
END 1 END 2		7	5 8	6 9	1	20.00 40.00	20.00 20.00
UNIF NUME NUME	ORM VORM HER OF	ERTICAL L ORIZONTAL CONCENTR CONCENTR		ONTAL LO			IPS/FT IPS/FT
UNIF NUMB NUMB	ORM VORM HER OF	ERTICAL L ORIZONTAL CONCENTR CONCENTR		ONTAL LO			IPS/FT IPS/FT

MEMBER NUM AREA MOMENT (BER F INERTIA	6	20.00 180.00			
	SPLACEMENT				COORDINATES	` ,
END 1	ZONTAL VER	5	6	1	X 20.00	Y 20.00
END 2	10	11	12	1	20.00	35.00
UNIFORM UNIFORM NUMBER NUMBER	NUMBER VERTICAL HORIZONTAL OF CONCENTE OF CONCENTE OAD APPLIE	LOAD L LOAD RATED VERT RATED HORI	ZONTAL L		0.00 K 0.00 K 0 0	
UNIFORM UNIFORM NUMBER NUMBER	NUMBER VERTICAL 1 HORIZONTAL OF CONCENTE OF CONCENTE OAD APPLIES	LOAD L LOAD RATED VERT RATED HORI	ZONTAL L		0.00 K 0.00 K 0 0	
MEMBER NUM AREA MOMENT C	BER F INERTIA	7		IN.**2 IN.**4		
	SPLACEMENT ZONTAL VERT				COORDINATES X	(FEET)
END 1	7	8	9	1	40.00	20.00
END 2	13	14	15	1	40.00	35.00
UNIFORM UNIFORM NUMBER NUMBER	NUMBER VERTICAL I HORIZONTAI OF CONCENTE OF CONCENTE OAD APPLIE	COAD C LOAD RATED VERT RATED HORI	ZONTAL L			IPS/FT IPS/FT
UNIFORM UNIFORM NUMBER NUMBER	NUMBER VERTICAL I HORIZONTAI OF CONCENTE OF CONCENTE OAD APPLIE	COAD C LOAD RATED VERT RATED HORI	ZONTAL L		0.00 K 0.00 K 0 0	

HORIZONTAL JOINT LOAD	-20.00 KIPS
VERTICAL JOINT LOAD	0.00 KIPS
ROTATIONAL JOINT LOAD	0.00 KIPS

MEMBER N AREA MOMENT	NUMBER	8	10.00 300.00			
HO END 1 END 2	DISPLACEMEN DRIZONTAL VE 10 13			END FIXITY 1	COORDINATES X 20.00 40.00	(FEET) Y 35.00 35.00
UNIFO UNIFO NUMBE NUMBE	ASE NUMBER DRM VERTICAL DRM HORIZONT ER OF CONCEN ER OF CONCEN	AL LOAD TRATED VE	RIZONTAL L		-1.20 K 0.00 K 0 0	IPS/FT IPS/FT
UNIFO UNIFO NUMBE	ASE NUMBER ORM VERTICAL ORM HORIZONT ER OF CONCEN	AL LOAD				IPS/FT IPS/FT

JOINT LOAD APPLIED TO MEMBER END

			END 1			END 2	
LOAD	MEMBER				AXIAL		
CASE	NUMBER	FORCE	SHEAR	MOMENT	FORCE	SHEAR	MOMENT
		(KIPS)	(KIPS)	(KIP-FT)	(KIPS)	(KIPS)	(KIP-FT)
1	1	10.54	-1.23	-7.72	-10.54	1.23	-16.87
2	1	11.20	-13.33	-148.02	-11.20	13.33	-118.66
1	2	38.98	0.48	3.67	-38.98	-0.48	5.96
2	2	10.38	-14.73	-157.52	-10.38	14.73	-137.11
1	3	22.47	0.75	5.47	-22.47	-0.75	9.48
2	3	-21.57	-11.93	-139.10	21.57	11.93	-99.58
1	4	1.23	10.54	16.87	-1.23	13.46	-45.97
2	4	13.33	11.20	118.66	-13.33	-11.20	105.24
1	5	-1.85	13.37	52.37	1.85	10.63	-25.05
2	5	16.47	13.38	119.51	-16.47	-13.38	148.18

++++ PLANE STRUCTURE ANALYSIS ++++ (Continued)

			END 1		END 2				
LOAD	MEMBER NUMBER	AXIAL FORCE (KIPS)	SHEAR (KIPS)	MOMENT (KIP-FT)	AXIAL FORCE (KIPS)	SHEAR (KIPS)	MOMENT (KIP-FT)		
1	6	12.16	-2.59	-12.35	-12.16	2.59	-26.56		
2	6	8.19	-11.60	-87.64	-8.19	11.60	-86.35		
1	7	11.84	2.59	15.56	-11.84	-2.59	23.35		
2	7	-8.19	-8.40	-48.60	8.19	8.40	-77.41		
1	8	2,59	12.16	26.56	-2.59	11.84	-23.35		
2	8	11.60	8.19	86.35	-11.60	-8.19	77.41		

JOINT DISPLACEMENTS

			END 1			END 2	
LOAD	MEMBER	HORI ZONTAL	VERTICAL	ROTATION	HORIZONTAL	VERTICAL	ROTATION
CASE	NUMBER	FEET	FEET	RADIANS	FEET	FEET	RADIANS
1	1	0.00000	0.00000	0.00000	0.00229	-0.00035	-0.00220
2	1	0.00000	0.00000	0.00000	-0.28381	-0.00037	0.00705
1	2	0.00000	0.00000	0.00000	0.00221	-0.00130	0.00055
2	2	0.00000	0.00000	0.00000	-0.28470	-0.00035	0.00490
1	3	0.00000	0.00000	0.00000	0.00234	-0.00075	0.00096
2	3	0.00000	0.00000	0.00000	-0.28579	0.00072	0.00949
1	4	0.00229	-0.00035	-0.00220	0.00221	-0.00130	0.00055
2	4	-0.28381	-0.00037	0.00705	-0.28 4 70	-0.00035	0.00490
1	5	0.00221	-0.00130	0.00055	0.00234	-0.00075	0.00096
2	5	-0.28470	-0.00035	0.00490	-0.28579	0.00072	0.00949
1	6	0.00221/	-0.00130	0.00055	-0.00416	-0.00160	-0.00229
2	6	-0.28470	-0.00035	0.00490	-0. 44 710	-0.00055	0.00516
1	7	0.00234	-0.00075	0.00096	-0.00433	-0.00105	0.00252
2	7	-0.28579	0.00072	0.00949	-0.44787	0.00092	0.00372
1	8	-0.00416	-0.00160	-0.00229	-0.00433	-0.00105	0.00252
2	8	-0.44710	-0.00055	0.00516	-0.44787	0.00092	0.00372

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	No bene	fit O	1	2	3 4	5	6	7	8	9	10	Very beneficial
2.	Was it eas	sy to	use	(use	r fr	iend	11 y)	?				
	Diffic	ult 0	1	2	3 4	5	6	7	8	9	10	Very easy
3.	Does this	softw	are	make	dec	isic	ons	mor	e r	eli	able	?
		No 0	1	2	3 4	5	6	7	8	9	10	Yes
4.	Does it be	etter	docu	ment	the	des	sign	1?				
		No 0	1	2	3 4	5	6	7	8	9	10	Yes
5.	Did it sa	ve tim	e?									
	Yes	No _		Est	imat	ed p	erc	ent	sa	ved	?	
6.	What would	d make	fut	ure	softi	ware	e mc	re	use	r f	rien	dly?
7.	What furt	her su	ppor	t wo	uld :	you	lik	ke t	o h	ave	on	the GEMS system?
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