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FABRICATION AND EXPERIMENTAL TECHNIQUES IN INTEGRATED OPTICS

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NAVAL AVIONICS CENTER

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September 15, 1981

Final Report

for

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U.S. Naval Avionics Center Indianapolis, Indiana

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FABRICATION AND EXPERIMENTAL TECHNIQUES IN INTEGRATED OPTICS

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ABSTRACT

A program to investigate the characteristics of integrated optical components, coupling between optical waveguides and other optical components and waveguide fabrication technology was initiated in February 20, 1981 for Naval Avionics Center under contract N00163 81 H 1798. The work performed under this contract is summarized in this report. The Navy technical monitor was Dr. K. J. Jones.

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1.0 INTRODUCTION

Since the useful bandwidth of a coherent source is proportional to its oscillating frequency, and the frequency of a laser radiating in the visible or near infrared spectra is of the order of 10¹⁴ Hz, its useful bandwidth is tremendous. Many optical devices and systems have been conceived to take advantage of the tremendous bandwidth of lasers. However, the weight, size and alignment problems of bulk optical devices and their susceptibility to mechanical vibrations, air turbulence and temperature fluctuation prevent these devices from becoming practical. Recently interest has turned to integrated optical devices and systems, since many of the problems associated with bulk optical devices are absent in the integrated or guided-wave devices.

In February 1981, an integrated optical device program was initiated at Technology Associates, Inc. for Naval Avionics Center (NAC). The objectives were to provide the technical support for the enhancement of NAC's in-house integrated optics (IO) activities in upgrading its experimental facilities and evaluation capabilities, and to assist NAC personnel in screening, evaluating and assessing appropriate IO material, components and technologies for specific systems of current and future interst to NAC.

Optical waveguides are the basic building blocks of any IO system. Optical components can be built from, and optical subsystems can be connected by the optical waveguides. The potential exists that all optical components and associated electronics may be fabricated on a common substrate. Waves can be coupled into or out of the waveguides via prism, endfire or grating coupling. So far as experimental investigations are concerned, prism couplers are probably the most versatile tool for coupling radiation into or out of waveguides and for characterizing guided modes. On the other hand, end-fire coupling is the most reliable. The prism (Figure 1) and end-fire (Figure 2) coupling schemes will be discussed in Sections 2 and 3 respectively. Grating coupling, not attempted in this work, will not be discussed in this report. The effective index of refraction and the attenuation constant are two basic and important characteristics of optical waveguides. Techniques to estimate these waveguide parameters are discussed in Sections 4 and 5. Experiments involving infrared or near infrared radiation are discussed in Section 6. Methods of fabricating practical optical waveguides are presented in Section 7.

2.0 PRISM COUPLING

A dielectric slab waveguide consisting of a substrate region with an index of refraction n_s , a film region of an index n_f , and a cover region with an index n_c , is the simplest possible optical waveguide structure. Many modes can be supported by the structure, depending upon the free-space wavelength λ , the thickness h of the firm, and the values of n_s , n_f and n_c . Let $N_{eff,m}$ be the effective index of refraction of the m-th guided mode, then $N_{eff,m}$ is related to these parameters via the dispersion relation [1, 2]:

-2-

$$\frac{2\pi h}{\lambda} \sqrt{n_f^2 - N_{eff,m}^2} = \Psi_m(n_f, n_s, n_c, N_{eff,m})$$
(1)

where

$${}^{\#(n_{f},n_{s},n_{c},N_{eff,m}) = m\pi + \phi_{s}(n_{f},n_{s},N_{eff,m}) + \phi_{c}(n_{f},n_{c},N_{eff,m})}$$
(2)

$$\phi_{s}(n_{f},n_{s},N_{eff,m}) = \arctan\left[\left(\frac{n_{f}}{n_{s}}\right)^{2}\rho\left(\frac{N_{eff,m}^{2}-n_{s}^{2}}{n_{f}^{2}-N_{eff,m}^{2}}\right)^{1/2}\right]$$
(3)

$$\phi_{c}(n_{f},n_{c},N_{eff,m}) = \arctan\left[\left(\frac{n_{f}}{n_{c}}\right)^{2}\left(\frac{N_{eff,m}^{2} - n_{c}^{2}}{n_{f}^{2} - N_{eff,m}^{2}}\right)^{1/2}\right]$$
(4)

and $\rho = 0$ for TE modes and $\rho = 1$ for TM modes.

2.1 Basic principle of prism coupling:

If a prism with an index n_p and an angle ε is placed next to the film, (see inserts of Figures 3 and 4) and an optical beam is incident upon the boundary between the film and the prism at an angle such that the projection of the phase velocity of the incoming beam in the prism matches exactly with c/N_{eff} , c being the speed of light in vacuum, of the m-th guided mode, then the m-th guided mode will be excited. This is the basic principle of prism coupling. The angle of incidence α or α' , n_p , ε and N_{eff} are related by the relations below [1, 2]:

$$N_{eff} = \sin\varepsilon (n_p^2 - \sin^2 \alpha)^{1/2} + \cos\varepsilon \sin\alpha$$
 (5)

$$N_{eff} = \sin \varepsilon (n_p^2 - \sin^2 \alpha^2)^{1/2} - \cos \varepsilon \sin \alpha^2$$
 (6)

The angles α , α' and ϵ are defined in the inserts to Figures 3 and 4.

2.2 Design considerations for prism couplers:

The key component of a prism coupler is, of course, the prism. The following points should be taken into account in selecting prisms:

(1) The prism should be as small as practical.

(2) The prism material should be as hard as possible to minimize the effects of scratching and chipping [2].

(3) The index of the prism should be somewhat larger, not merely slightly larger, than the index of the film, e.g., $n_p > n_f + 0.1$ or $n_p > n_f + 0.2$.

(4) To avoid spurious response due to repeated reflections from the prism surfaces, one should avoid prisms with angles of 30° , 45° , 60° , 90° or other rational fractions of 360° [2].

(5) If a half-prism, as depicted in Figures 1, 3 and 4, is used, the angle at the corner where the guided modes are launched should be sharp and well defined.

(6) The prism should have a flat top, rather than a sharp apex, so that pressure can be applied uniformly to the prism.

A possible design of prism is shown in Figure 5. For a flint glass prism (with $n_p = 1.75$) of the shape shown in Figure 5, the dependence of N_{eff} as functions of α or α' calculated from (5) or (6), are shown in Figure 3. If the prism is made of an uniaxial crystal like rutile (TiO₂) with its optic axis parallel to the edge of 91.0°, i.e., perpendicular to the figure shown, the extraordinary index $n_e = 2.87$ should be used for n_p . Figure 4 depicts the relationship between N_{eff} and α or α' for such a rutile prism. Theoretically, coupling to substrates with N_{eff} values ranging from 1.4179 to 2.7036 can be achieved with the rutile prism and these values correspond to the coupling angles of $\alpha' = 90.^{\circ}$ and $\alpha = 90.^{\circ}$ respectively. In reality, the useful range is limited to 1.7295 ($\alpha' = 40.^{\circ}$) to 2.6112 ($\alpha = 50.^{\circ}$) region.

2.3 Operations of prism couplers:

In addition to a finite number of guided modes, a waveguide structure can support a continuum of radiation modes in the cover (air) region above the film and the substrate region below the film. These fields are referred to as the air and substrate modes respectively. The air mode has an oscillatory field distributions in all regions and has an effective index of refraction N_{eff} smaller than n_c . When N_{eff} is increased beyond n_c , there is the substrate mode which has an exponentially decaying field distribution in the cover region and oscillatory field distributions in the film and substrate regions. For the guided modes, $n_s < N_{eff} < n_f$, and the field decays exponentially in the air as well as the substrate region.

As a specific example, consider a waveguide consisting of a Corning 7059 glass film ($n_f = 1.555$) of thickness $h = 1.0 \ \mu m$ and a substrate of pyrex glass ($n_s = 1.45$), of thickness of 0.1 cm. So far as the guided modes are concerned, the pyrex glass can be considered as infinitely thick. Two TE modes may be supported by the Corning 7059/pyrex structure with $N_{eff} = 1.5356$, and 1.4780. Suppose a glass prism with an index of $n_p = 1.75$ as shown in Figure 5 is used in the experiment. For $\alpha' > 27.^{\circ}$, the air mode is excited.

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Although the air mode is reflected from the substrate-air boundary, the reflection coefficient is small ($|\rho|^2 = 0.034$). If the laser beam is not blocked by any objects, it would emerge behind the pyrex glass. As the incident angle is increased with $\alpha' < 27$.°, or $\alpha < 10.4$ °, the substrate mode is excited. The optical beam is totally reflected at the air-substrate boundaries. As a result, the beam is trapped in the pyrex glass. A dot appears at each point where the reflection occurs. Since the reflection is very efficient, with $|\rho|^2 = 1$., a series of dots become visible. The distance between dots is a function of the thickness of substrate and will vary with α . For a pyrex glass of thickness of 0.1 cm, the distance between dots on the same boundary would vary from 0.10 cm to 1.27 cm as the angle changes from $\alpha' = 25$.° to $\alpha = 10.0^\circ$. As α approaches 13.6°, a continuous streak would appear, and this is the TE₁ mode with N_{eff} = 1.4780. When α is increased to 20.°, TE₀ mode with N_{eff} = 1.5356 would be excited.

From the above discussion, three points helpful to the proper interpretation of, and the successful operation of the prism coupling experiments become obvious:

(1) If possible, there should be no reflective object behind the substrate. Thus the air mode, if it is excited, will not be reflected. If this cannot be done, then, the space behind the substrate should be made accessible. By probing the space behind the substrate, one can differentiate the air mode reflected by the object behind the substrate from the substrate mode reflected by the boundary of the substrate.

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(2) From the coupling angle where a series of dots begins to appear, one can use (5) or (6) to estimate the index of refraction of the substrate.

(3) As the coupling angle is changed, the distance between dots increases. The limiting case should be very close to the highest guided mode.

3.0 END-FIRE COUPLING

As mentioned previously, end-fire coupling, also known as butt coupling, is one of three methods available for coupling light into or out of an optical waveguides. As implied by the name, light is coupled into the waveguide through the end surface of the waveguide, as shown in Figure 2. In any optical waveguide, energy is concentrated in a thin layer, with a thickness of the order of a few wavelengths at most near the waveguide surface. The region near the corner of the waveguide is critical to end-fire coupling. Techniques have been developed specifically to polish the corner region of the substrate [3]. In connection with this work, a jig for polishing the end surfaces of optical waveguides has been designed and is to be used in conjunction with the existing polishing facility at NAC. This work is currently in progress.

3.1 Transformation of Gaussian beams by lens or lenses:

To achieve maximum coupling into the optical waveguide, the cross section and beam divergence of the incoming optical beam must match that of the waveguide. The optical beam emitted by a HeNe laser is typically of the Gaussian form. In particular the irradiance distribution of a

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TEM₀₀ Gaussian beam is given by $\mathbf{I}_0 e^{-2r^2/\omega^2}$. The beam radius ω is defined as the radius where the irradiance is reduced to e^{-2} of its peak value \mathbf{I}_0 at the beam center (r = 0). The beam radius ω_0 (or diameter) at the beam waist, i.e., the point with the smallest beam radius (or diameter), is usually specified. In the Fraunhofer zone, the full angle of divergence is $2\lambda/(\pi\omega_0)$. For example, a Spectra Physics Model 145 laser has a beam diameter, of 0.5 mm and the beam diverges at full angle of 1.7 mrad. For these lasers, the beam waist is usually located at the output mirror. A simple lens with a focal length of f can be used to change the beam radius. Let ω_{0a} and ω_{0b} be the radii of the beam waists of the incoming and outgoing beams as shown in Figure 6. ω_{0a} , ω_{0b} and their locations z_a and z_b with respect to the lens are related by

$$\frac{1}{\omega_{ob}^{2}} = \frac{1}{\omega_{oa}^{2}} \left(1 - \frac{z_{a}}{f}\right)^{2} + \left(\frac{\pi\omega_{oa}}{f\lambda}\right)^{2}$$
(7)
$$z_{b} = f + \frac{(z_{a} - f)f^{2}}{(z_{a} - f)^{2} + (\pi\omega_{oa}^{2}/\lambda)^{2}}$$
(8)

where λ is the wavelength of the radiation [4]. If the beam waist ω_{oa} of the incoming beam is located at the front focal point of the lens, i.e., $z_a = f$, then the beam waist ω_{ob} is located at the back focal point $z_b = f$ and has a value

$$r_{ob} = \frac{f\lambda}{\pi\omega}_{oa}$$
 (9)

For example, a lens with a focal length of 10 cm will transform a HeNe

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laser beam ($\lambda = 0.633 \ \mu m$) with ω_{oa} of .25 mm to a beam with $\omega_{ob} = 80.59 \ \mu m$.

Since the cross section of a planar waveguide is thin and wide, it may be necessary to use a cylindrical lens to transform the circular optical beam into an elliptical shape. The above equations may be used twice, one for the major axis and one for the minor axis.

The beam collected by a microscope objective or a lens may be too wide for some application. Two lenses, with focal lengths f_1 and f_2 and spaced at a distance $f_1 + f_2$, may be used to change the beam diameter by a factor of f_2/f_1 , as shown in Figure 1. By choosing $f_2 < f_1$, the beam diameter is reduced. If $f_2 > f_1$, on the other hand, the beam is expanded. If a small pinhole is inserted at the common focal point of these two lenses, the lens-pinhole combination also acts as a spatial filter.

3.2 Horns for channel waveguides:

Typically, a channel waveguide is 3 to 6 µm wide and 1 to 2 µm thick. Thus channel waveguides are thin and narrow. Although the prism coupling or the end-fire coupling may be used to couple light into a channel waveguide, it is difficult to align the optical beam with respect to the channel waveguide. To relieve the alignment difficulty, a horn structure may be used to transform a planar waveguide to a channel waveguide gradually. Linearly, exponentially or parabolically tapered horns have been proposed by various authors [5 - 9]. As explained by Burns, Milton and Lee [8], the most practical horn is of the parabolic shape. For parabolic horns, the width W of the horn is given by

$$W = \sqrt{2k\lambda_g z + W_o^2}$$
(10)

where k is a constant and $\lambda_g = \lambda/N_{eff}$ is the local effective guide wavelength of the channel waveguide. W_o and other parameters are as shown in Figure 7. Unless the channel width, W, is very narrow such that the lowest order mode (in the x-direction as shown in Figure 7) is near to its cutoff point, λ_g can be approximated by λ_o/n_f [8]. As a specific example, again consider a HeNe laser with a beam diameter of 0.5 mm ($\omega_o = 250 \mu$ m) at its beam waist. Two lenses with $f_1 = 16 f_2$ and spaced at a distance of $f_1 + f_2$ (Figure 1) can be used to reduce the beam radius to 15.6 μ m. The beam diameter at the entrance point is 31.2 μ m. Therefore $W_{max} = 40 \mu$ m is chosen, Horns have been designed to transform $W_{max} = 40 \mu$ m to channel waveguides of width 5, 10 and 20 μ m respectively. Suppose that the channel waveguides and the tapering horns are to be built on photoresist waveguides with $n_f = 1.6$. With the selection of k = 0.8, all parameters of (10) are specified. The equations describing the horns for 5, 10 and 20 μ m

$$W^2 = 25.0 + 0.6328 |z|, \quad 0 \le z \le 2488.9 \ \mu m$$
 (11)

$$W^{2} = 100.0 + 0.6328 |z| \qquad 0 \le z \le 2369.6 \ \mu m$$
 (12)

$$W^2 = 400. + 0.6328 |z|, \quad 0 \le z \le 1895.7 \ \mu m$$
 (13)

For z = 0, $W = 5 \mu m$, 10 μm and 20 μm respectively, and $W = 40 \mu m$ when z exceeds the values specified in (11), (12) or (13).

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4.0 FILM INDEX AND THICKNESS

One of the most useful features of prism coupling is the relationship between α (or α) and N_{eff}. When α or α is measured experimentally, and when n_p and ε are known, N_{eff} can be computed from (5) and (6). This feature, in conjunction with the dispersion relationship (1), can be used to estimate n_f and h.

For a waveguide, $n_{\rm g}^{},\,n_{\rm g}^{}$ and λ are usually known while $n_{\rm f}^{}$ and h are unknown. If one of the coupling angles is measured and N_{eff} is computed from (5) or (6), we have one equation ((1)) yet two unknowns. There is insufficient information to solve for n_f and h. When two or more coupling angles are determined, the index n_f and thickness h of the thin film can be evaluated, provided that the indices of the substrate and the cover, n_{c} and n_{c} , are known. Cases where three or more waveguide modes are determined have to be treated differently from the cases where two wavequide modes are determined. In either case, considerable numerical computation is needed to deduce the final results from the experimentally measured data. A computer program written to carry out the necessary iteration and computation is listed in the Appendix. The theoretical foundation and the algorithm of the computer program are explained in this section. Also included are typical results obtained by the computer program. The input and output instructions are contained in the program MAIN. Additional functions of the program MAIN and various subroutines will be explained in the following sections.

4.1 Waveguides with two modes measured:

Suppose that two coupling angles are determined and N eff,m with $m = \mu$ and v are computed. Then, substituting N eff, μ and N eff, ν into (1) and rearranging the resultant equations, we obtain

$$n_{f}^{2} = \frac{\left(N_{eff,\mu}\right)^{2} \psi_{\nu}^{2} - \left(N_{eff,\nu}\right)^{2} \psi_{\mu}^{2}}{\psi_{\mu}^{2} - \psi_{\nu}^{2}}$$
(14)

This is a nonlinear equation for n_f and a simple iteration scheme can be used to solve for n_f . Specifically, a trial value for n_f is assumed and (14) is used to compute a new n_f . If the new n_f differs from the old n_f considerably, the new n_f is used to compute a newer n_f . This process is repeated until a satisfactory accuracy is achieved. Once n_f is known, it is a simple matter to solve for h from (1). The computation for N_{eff} from α is carried out at the beginning of the program MAIN. The second part of program MAIN is related to the iteration for n_f and the simple calculation for h.

4.2 Waveguides with three or more modes measured:

The cases where three or more waveguide modes are measured, assuming the waveguide has three or more modes, are much more complicated. Suppose that M coupling angles are measured, with $M \ge 3$. Each measured coupling angle corresponds to a value for $N_{eff,m}$, which in turn leads to an equation with a specific value for $N_{eff,m}$. There are M equations ($M \ge 3$) and yet there are only two unknowns. One cannot solve for the unknowns from these equations unless M-2 equations are redundant. In the ideal situation where the experimental results are infinitely precise and without error, M-2 equations will be redundant. In any real experiment, however, there will be

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experimental error or inaccuracy; n_f and h cannot be determined from the measured coupling angles. Instead of "solving" for n_f and h from $N_{eff,m}$, the best estimates for n_f and h are sought. Reasonable values of n_f , h are assumed and used in conjunction with the known values of n_s and n_c to compute the effective index of refraction from the dispersion relation (1). The effective index of refraction so obtained is labeled as $N_{eff,m}(n_f,h)$. The values of n_f and h are then searched so that $N_{eff,m}$ match with $N_{eff,m}(n_f,h)$. Following Ulrich and Torge [2], an error sum is defined as:

$$\sigma(n_f,h) = \Sigma \left[N_{eff,i} - N_{eff,i} (n_f,h) \right]^2$$
(15)

If the experimental results are perfectly accurate, we should look for n_f and h such that $\sigma = 0$. Because of the presence of the experimental error and inaccuracy, this is not possible. Instead we look for the values of n_f and h which minimize σ , and they are found by requiring

$$\frac{\partial \sigma}{\partial n_f} = 0 \tag{16}$$

$$\frac{\partial \sigma}{\partial h} = 0$$
 (17)

A gradient method [2] is used to solve for n_f and h from the simultaneous equations (16) and (17), and this is done by calling the subroutine GRDT. The basic idea of the gradient method is quite simple. Suppose a relief or a surface of σ is plotted as a function of (n_f,h) . Let σ at a particular

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point (n_f,h) be evaluated. If $\sigma = 0$, this particular point corresponds to the desired solution. If $\sigma > 0$, then a point with a smaller value of σ should be chosen. If one is standing on the relief, then the best possible move is to move in the direction of steepest descent, which is precisely the direction of the negative gradient. In GRDT, σ for a given (n_f,h) , and its eight neighboring points, are calculated by repeatedly calling the subroutine ERSUM. In the process, it is necessary to solve for the effective index of refraction from (1) numerically. A quadratic interpolation algorithm expounded by Muller is used for this purpose [10]. To make use of the MULLER subroutine, the dispersion relation (1) is coded as the subroutine DISP. A valley is reached when (16) and (17) are satisfied.

4.3 Examples:

To test the accuracy of the program, two test runs have been made. The parameters of the waveguide and prism, the "observed" coupling angles and the results of the computation are listed below.

(1) Waveguide 1:

 $n_s = 1.5000, n_c = 1.0000, n_p = 1.7552, \epsilon = 50.0^{\circ}.$ $n_f = 1.6500, h = 2.0000 \mu m,$ $\alpha = 35.95^{\circ}, 32.80^{\circ}, 28.80^{\circ}.$ Computed $n_f = 1.6503$, Error = 0.018%. Computed h = 2.0352 \mu m, Error = 1.76%.

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(2) Waveguide 2:

 $n_s = 1.4500$, $n_c = 1.0000$, $n_p = 1.7552$, $\varepsilon = 50.0^\circ$. $n_f = 1.5500$, $h = 2.8000 \ \mu m$, $\alpha = 21.10^\circ$, 19.75°, 17.10°. Computed $n_f = 1.5495$, Error = 0.03%.

Computed h = $2.7348 \mu m$, Error = 2.3%.

The coupling angles are read and interpolated from a curve similar to Figure 3 or 4 and are accurate to $\pm 0.1^{\circ}$. Comparison of the computed values for n_f and h with those assumed values shows that the results are quite good, despite of the inaccuracy in reading the coupling angles.

5.0 ATTENUATION

Although the attenuation of the Quided beam can be determined by using two or three prisms [11, 12], the data so obtained is not very reliable. Instead, an optical fiber may be used to probe the intensity of the guided beam and the attenuation constant can be deduced from the measured data. Many optical films are polycrystalline in nature. The grain boundaries are distributed more-or-less uniformly throughout the film, and act as the scattering centers. Streaks of light appear when light is scattered by the scattering centers. The intensity of the scattered light is proportional to the intensity of the guided beam and can be used as a measure of the intensity of the guided beam. By platting the intensity of scattered light as a function of position along the propagating beam, one can estimate the attenuation constant. A simple way to perform the experiment is to use a TV camera. The video image recorded by the camera can be processed electronically. A microscope objective or an optical fiber may be used to pick up the scattered light [13, 14]. Because of its size and

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flexibility, an optical fiber is preferred. A fixed orientation of the fiber relative to the waveguide and a constant separation between the fiber tip and the waveguide should be maintained throughout the measurement. To avoid fluctuation or "scattering" of the data, the numerical aperture of the fiber should not be too small. The reading taken when the fiber is near the edges of the waveguide should be discarded. It is also desirable to probe the scattered light as a function of position transverse to the propagating beam and to integrate the signal so measured. Of course, such a measurement would be very time-consuming.

A Gamma Scientific Radiometer interfaced with a Hewlett-Packard 9825 Computer/Controller and various attachments are available for use at NAC. All that is needed is to construct a stable platform so that the fiber can be moved relative to the waveguide in a fixed, predetermined fashion.

6.0 EXPERIMENTAL OBSERVATIONS WITH INJECTION LASERS

Since semiconductor injection lasers are small and can be modulated directly at high frequency, they are favored in many communication and signal processing applications. The bandgap of GaAs, or ternary and quaternary compounds based on GaAs material, is such that radiation emitted from GaAs injection lasers are in the near infrared region and are invisible to human eyes. In addition, the radiation from these lasers diverges quickly. Unless a simple means is found to trace or to "see" the laser beam, it would be very difficult to align various optical components with respect to the invisible beam. Ways must also be found to collect and to collimate the beam before it diverges. Other than these two complications, experiments involving GaAs or other semiconductor lasers with near infrared (IR)

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emission are essentially the same as the experiments using lasers in the visible spectra.

Two simple ways of "seeing" emission in near IR spectra are IRphosphor plates and image converters. While the phosphor plates are easy to use, their sensitivity is rather low. Two crucial components of an image converter are a photocathode and a fluorescent screen. Electrons are ejected from the photocathode as a result of the photon bombardment. The electrons so released are accelerated toward the fluorescent screen which emits light in the visible region. Thus the IR or near IR image is converted into a visible one. Depending on the photocathodes used, the image converter may be used in different spectral regions. For example, S-1 cathodes, which are typically used in many commercially available image converters or IR viewers, are useful in the range between 0.3 to 1.2 µm with its peak response in the 0.7 to 0.9 µm range, which coincides with the emission spectra of GaAs lasers.

TV cameras equipped with Si cathodes can also be used to view near IR or IR emission. However, TV cameras are too heavy and bulky for initial alignment purpose, although they are very useful for the final viewing or detailed measurement.

The active, light-emitting area of an injection laser is quite small and generally has a rectangular shape. As a result, the beam emitted by an injection laser has an elliptical cross section with a large angle of divergence. Typically, the beam divergences are 10.° (parallel to the pn junction) x 30.° (perpendicular to the junction), i.e., 170 x 520 mrad. For comparison, it is noted that the beam divergence of a typical HeNe laser is about 1 to 2 mrad. Since the beam diverges fast, a lens with a small F-number or a microscope objective with a large numerical aperture (N.A.) can be used to collect the beam before it diverges. The F-number of a lens is defined as the ratio of the effective focal length f to the diameter d of the aperture:

$$F - number \equiv f/d$$
 (18)

For a microscope objective situated in the air and accepting beams within a cone of half-angle θ , the numerical aperture is

N.A. =
$$\sin \theta$$
 (19)

For lenses corrected for coma and spherical aberration and with infinite object distance, these two quantities are related:

$$F - number = \frac{l}{2N.A.}$$
(20)

For reference purpose and for convenience of alignment, it is convenient to superimpose a visible light with the invisible beam. A mirror and a cube beam splitter have been used for this purpose.

7.0 FABRICATION OF OPTICAL WAVEGUIDES

Many schemes are available for fabricating the waveguides. Depending on the fabrication process, the index profile in the substrate and film regions may vary considerably. A three-layer structure, with $n_f > n_s > n_c$, is the simplest optical waveguide configuration. In most optical waveguides, the transition from the film region to the substrate region is gradual rather than abrupt. Extensive reviews of all existing fabrication processes have been reported by Chang et. al., [16], by Tien et. al., [17, 18], and by Zernike [19]. Not all waveguides are applicable in practical systems, however. Here, the fabrication of waveguides which are potentially useful in practical systems are reviewed. Specifically, techniques useful in forming solutiondeposited waveguides, and waveguides based on glass and lithium niobate substrates are considered. In terms of practicality, waveguides based on GaAs should also be included in the list. As is well known, fabrication of semiconductor thin-films is a precise and complex discipline. Numerous articles and books are devoted to the subject of semiconductor thin-films in general, and GaAs or ZnO material [20-23] in particular. Therefore, optical films based on GaAs or ZnO materials are not included in the review.

7.1 Solution deposited waveguides:

Of all techniques available for producing optical films and components, techniques based on solution deposition are the simplest. Most thin-film fabrication processes have their origin in microelectronics. These techniques are eminently suited for fabricating small or miniature components. If optical films or components with large areas are needed, solution deposition or rf discharge polymerization are probably the best candidates [24-30]. The properties of polymeric thin-films have been studied by Swalen et. al., [24]. Some details of fabricating photoresists (Kodak's KPR, and Shiple AZ1350), polyurethane, epoxy, lead silica, polystyrene (PS), polymethyl

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methacrylate (PMMA), styrene acrylonitrile copolymer (SAN) or combinations of PMMA and SAN have been reported [25 - 29]. The combination of PMMA and SAN has an interesting property in that the index of the film can be adjusted from 1.489 to 1.563 by properly mixing PMMA with SAN. The pertinent fabrication parameters are summarized in Table 1. The shortcomings of these films include a short life time and in some cases, attenuation is sensitive to ambient humidity [29].

After the solution is prepared, it can be applied onto a solid substrate, usually a glass slide. Uniform coating can be achieved by dipping, horizontal flow, spinning coating or "doctor blading" methods [24]. "Dipping" simply means dipping the glass slide into the solution and then withdrawing the slide from the solution with constant speed. The film thickness is controlled by the viscosity of the solution, and, to some extent, the speed of withdrawing. The slide is dried and/or baked in a horizontal position. The horizontal flow method starts with covering the slide with the solution from a syringe, the slide is then brought to a vertical position so that the excess solution is drained. The slide is returned to the horizontal position for drying and/or baking. In spin coating, the slide is placed in a spinner. After the slide is covered with the solution, it is spun with a specific speed and for a specific duration so as to achieve a given thickness. Since the speed and duration of spin can be controlled, in addition to the density and the viscosity of the solution, the films so obtained are quite uniform. In the "doctor blading" method, a knife edge is used to spread the solution along the surface of the slide.

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7.2 Glass waveguides:

Most optical systems used in communication or sensor applications will require optical fibers as their transmission media. At present, optical fibers are made of glass or quartz and have indices of refraction in the range of 1.5 to 1.6. Since the 10 components are a part of the communication or sensor system, it is necessary to interface the 10 components to the optical fibers. To reduce the reflection loss at the interfaces, the indices of the glass fibers and the 10 components should be matched as closely as practical. Waveguides based on glass or quartz substrate are the natural choice in those applications. R.F. sputtering [31 - 38], chemical vapor deposition (CVD) [39], vacuum or electron beam deposition [35, 40], ion implantation [41 - 43], and ion exchange [44 - 52] methods have been used in forming waveguides on various glass slides. Thermal evaporation in vacuum is probably the simplest way of depositing thin films onto a substrate. However, films produced by thermal evaporation tend to be quite lossy. If the electron-beam evaporation process is used, films 2 to 4 μ m thick may be obtained with an attenuation slightly larger than 1.0 dB/cm [40] which is comparable to the waveguides made by sputtering processes.

Films of good quality with various compositions may be produced by the r.f. sputtering process. The composition of the gases in which sputtering is performed, the rf power and duration of sputtering can be controlled with ease. The gas pressure and the temperature of the substrate can also be adjusted to some extent. These fabrication parameters can be varied to form films having the desired composition and thickness. Obviously, the film thickness is directly proportional to the duration of sputtering. The

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rf power can be varied to tailor the index of sputtered film, and the stoichiometry of the film can be compensated by admitting various gases in the various stages of sputtering [33, 34]. The sputtering parameters and the properties of the films so obtained are summarized in Table 2.

The refractive index of a film is a function of the density and the electronic polarizability of the constituent species, and is described by the Clausius-Mossotti relation [53]. If the density of the material is increased, so is the index of refraction. More importantly, if the composition of the material is changed so that species with small electronic polarizability are replaced by species with large electronic polarizability, the index of refraction is also increased. In forming waveguides by solution deposition, thermal evaporation or r.f. sputtering, layers of material with higher index are deposited onto substrates, and the resulting index profiles are more-or-less abrupt. In the ion exchange process, however, an optical waveguide is formed when ions with small polarizability near the substrate surface are replaced by ions with larger polarizability, and the index profile of an ion-exchanged waveguide changes gradually from the surface (i.e., the "film" region) to the substrate region. Ion exchange processes can be used to form waveguides in glass, lithium niobate or other substrates. In this section, the discussion is restricted to glass or quartz. Typically, a glass slide is immersed at elevated temperature in molten salts containing the ions to be exchanged. Compounds such as KNO_3 , $T1NO_3$, and $NaNO_3$ [44], or AgNO₃ [45-47, 50], or AgNO₃ and NaNO₃ [51], or a eutectic melt of Li_2SO_4 and K_2SO_L [48] have been used in conjunction with various glasses. Alternatively, a solid silver film or a vapor stream of silver, produced

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by thermal evaporation, may be used instead of melts [49, 52]. The exchange process can be done with or without the assistance of an electric field. In the presence of an electric field, the speed of ion exchange is increased, and processing time can be reduced. Electric fields can also be used to make the index profile more abrupt and to move the peak of the index profile to the interior region of the substrate. By diffusing Ag^+ , Tl^+ and K^+ ions into the glass to replace Na^+ and Li^+ ions, the index of the diffused region will be higher than the index of the undiffused region. Masks with windows or apertures can be placed on the glass surface so that ion exchange is restricted to the selected regions. In this fashion, strip waveguides can be formed [46]. The fabrication parameters of ion exchange process are tabulated in Table 3.

7.3 Lithium niobate waveguides:

Since lithium niobate and lithium tantalate are highly transparent and have large electro-optic coefficients, they are commonly used waveguide materials. In particular, lithium niobate waveguides have been used to demonstrate the feasibility of many device concepts and practical systems. The epitaxial growth by melting method has been used to grow a solid solution of $(\text{LiNb0}_3)_{\alpha}(\text{LiTa0}_3)_{1-\alpha}$ onto LiTa0_3 substrate [54]. A guiding layer can also be formed by thermally diffusing, or diffusing under electric field, metals like Cu, Al, Ge, Cr, Fe, and Nb into LiTa0_3 [55 - 57], or by releasing Li_20 from the surface of LiNb0_3 or LiTa0_3 [58,59]. By far the most popular method is to deposit a layer of transition metal like Ti, V or Ni, on the surface of LiNb0_3 and to diffuse these elements into the

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substrate. This is known as the in-diffusion process [60]. Of the transition metals mentioned, Ti is the most popular element used, and it leads to the well known Ti:LiNbO₃ waveguides [60 - 64]. In the diffusion process, the temperature of the substrate has to be raised, Li_2 O is released from the surface resulting in an unwanted out-diffused waveguide at the surface of the substrate. Considerable effort was devoted to the elimination of the out-diffused layer [65 - 70]. The simplest way of suppressing the outdiffused waveguide layer is to add water vapor in the diffusion gas [70]. Table 4 lists most pertinent parameters in forming in-diffused waveguides.

Ion exchange methods have also been used to form optical waveguides on LiNb03 and LiTa03 [71, 72]. By exchanging Li⁺ ions or the vacant sites for Li⁺ ions with metallic ions, optical waveguides can also be formed in LiNb0, of LiTa0,. By placing polished x-cut plate of LiNb0, in molten AgNO₃ at 360°C for 3 to 15 hours, waveguides capable of supporting 1 to 3 TE modes were obtained by Shah [71]. The attenuation constant was measured with an optical fiber probe to be 6 dB/cm. The increase in the extraordinary index of refraction is quite large, $(\Delta n_p \approx 0.12)$. But the change in the ordinary index of refraction is insignificant, and no TM modes were observed. Experiments were also performed showing that the electro-optic coefficients of LiNbO₂ are not significantly affected by the ion exchange process. Y-cut $LiNb0_3$ or $LiTa0_3$ samples were also placed in AgN0₃ melt for 24 hours, no waveguide layer was formed, however. Additional work reported by Jackel [72] showed that the loss can be reduced to the 0.8 to 2.0 dB/cm region. Larger change in the extraordinary index of refraction has been obtained when the Li^+ ions are exchanged with Tl^+ ions in molten $TlNO_3$.

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8.0 CONCLUSION

With the introduction of integrated optics, a new class of optical components and systems emerge. Thin-film optical waveguides are the building blocks of these systems. Methods for fabricating, and experimental and numerical techniques for characterizing these waveguides were studied. Techniques useful for performing experiments in visible and infrared spectra were discussed. This study serves as a brief introduction to a new horizon in command, control and communication systems which has particular utility in avionics instrumentation.

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APPENDIX - LISTING OF A COMPUTER PROGRAM

In this Appendix, the program MAIN and the subroutines used to compute or estimate the refractive index n_f and the thickness h of the film from the measured coupling angles are listed. These programs, written in the standard Fortran language, have been tested as described in the main text of this report.

	program main(input,output)
	common /d1/ lambda, nefms(20), m(20), nss, ncs, mrho, nlines
	common /d3/ neft(20)
	real nsincinfinpilambda
	real nss.ncs.nfs.kw
	dimension theta(20), m(20)
	real neft(20), nefm(20), nefms(20)
	external ersum
c	open(1,file='mdata', status='old')
c	rewind 1
	read(5,180)ns,nc,np,lambda,epsm,mrho
130	format(5(f8.4,2x),i2)
	anp2=np*np
	nss=ns*ns
	ncs=nc*nc
	pi=3.141592654
	if(mrho .eq. 0) write (6,190)
	if(mrho .eq. 1) write (6,191)
190	format(3x, 'TE MODES')
191	format(3x, 'TM_MODES')
	write(6,183)ns,nc,np,epsm,lambda
183	format(2x, 'ns= 'f8.4, ' nc= 'f8.4, ' np= 'f8.4, ' angle of prism = '
	1 f9.4,3x,′ lambda≖ ′f8.4)
	epsmr=epsm*pi/180.
	do 184 i=1,20
	read(5,*,end=299) m(i),theta(i)
184	nlines≖i
C	
	write(6,185)
135	format(3x, 'More than 20 m-lines ? ')
	goto 999
C	
299	do 298 i=1,nlines
299	write(6,186) m(i), theta(i)
186	format(3x, i2, f8. 4, ′ degrees′)

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C do 220 ie=1, nlines thetar=theta(ie)*pi/180. nefm(ie)=sin(thetar)*cos(epsmr)+(sin(epsmr)*sqrt(anp2-sin(thetar) 1 #sin(thetar))) nefms(ie)=nefm(ie)+nefm(ie) neft(ie)=nefm(ie) write(6,215) ie,theta(ie),nefm(ie) 215 format(3x, i2, '-th coupling angle = 'f8.3, 3x, 'N eff = 'f8.4) 220 continue C if(nlines .gt. 2) goto 500 nf#1.048*amax1(nefm(1), nefm(2)) nfs≖nf*nf fts=1. ftc=1.do 300 iq=1,15 if(mrho .eq. 1) ftc=(nfs/ncs)*(nfs/ncs) if(mrho .eq. 1) fts=(nfs/nss)*(nfs/nss) phis=atan(sqrt(fts*(nefms(1) - nss)/(nfs - nefms(1)))) phic=atan(sqrt(ftc*(nefms(1) - ncs)/(nfs - nefms(1)))) psi1=m(1)*pi+phis+phic phis=atan(sqrt(fts*(nefms(2) - nss)/(nfs - nefms(2)))) phic=atan(sqrt(ftc*(nefms(2) - ncs)/(nfs - nefms(2)))) psi2=m(2)*pi+phis+phic f=(nefms(2)*psi1*psi1~nefms(1)*psi2*psi2)/(psi1*psi1 ~psi2*psi2) test=abs((nfs-f)/nfs) ff=sqrt(f) write(6,315)ff,nf,test 315 format(3x, 'nf= 'e14.6, 3x, 'last nf= 'e14.6, 'test= ' e14.6) if(test .1t. 0.000001) goto 400 nf=ff nfs=f 300 continue write(6, 320)320 format(3x, '*** 2 m-lines, not converging in 15 iterations, ***') goto 999 400 w1=lambda*psi1/(2.*pi*sqrt(nfs-nefms(1))) w2=lambda*psi2/(2.*pi*sqrt(nfs-nefms(2))) write(6,316)nf,w1, w2 315 format(3x, 'nf= 'f8.4,3x, 'w1= 'f10.4,3x, 'w2= 'f10.4,3x, ' microns') if(nlines .eq. 2) goto 999 500 kw=2.*pi*w1/lambda hx=1. e-8 hy=i. e −8 epsiln=1. e-6 call grdt(ersum, hx, hy, nf, kw, epsiln) w=kw*lambda/(2.*pi) write(6,349)nf,w 349 format(3x, 'nf= 'f8.4,3x, 'w= 'f10.4,3x, ' microns') 999 stop end

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subroutine disp(aneffs, dispft) common /d1/ lambda, nefms(20), m(20), nss, ncs, mrho, nlines common /d2/ nfx,wy,mij,factor real nf, nfx, nss, ncs, nfs dimension m(20) nfs=nfx*nfx pi=3.141592654 anefs=aneffs/factor fts=1. ftc=1.if(mrho .eq. 1) ftc=(nfs/ncs)*(nfs/ncs) if(mrho .eq. 1) fts=(nfs/nss)*(nfs/nss) phis=atan(sqrt(fts*(anefs-nss)/(nfs -anefs))) phic=atan(sqrt(ftc*(anefs-ncs)/(nfs -anefs))) psi=mij*pi+phis+phic dispft=wy*sqrt(nfs-anefs)- psi write(6,980)nfx,wy,aneffs,dispft 980 format(1x, 'disp', 4(e14.6, 1x)) return end

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function ersum(rtn, rtw) common /d1/ lambda, nefms(20), m(20), nss, ncs, mrho, nlines common /d2/ nfx,wy,mij,factor common /d3/ neft(20) real neft(20), nefmij real lambda, nefms(20),nss,ncs,nfx dimension m(20) complex rtsf(4) external disp logical fnreal real nfse kn=0 n=1 ep1=1. e-6 ep2=1. e-6 fnreal=. true. maxit=100 ersum≈0. factor=1. e+4 nfx=rtn wu≖rtw nfse=nfx*nfx ijn=nss*factor ijm=nfse*factor −1 do 100 ij=1, nlines ijkm=0 mij=m(ij) nefmij=sqrt(nefms(ij)) rts=(neft(ij))*(neft(ij)) rtsf(1)=rts*factor 210 call muller(kn, n, rtsf, maxit, ep1, ep2, disp, fnreal) call disp(rtsf(1), dispft) rts=real(rtsf(1)/factor) if(rts.gt. nss..and. rts.lt. nfse) goto 220 if(ijkm.gt. 0) gato 250 ijkm=1 ansf=nss+factor call disp(ansf,ftr1) do 240 ijk=ijn, ijm,2 ansf=ijk call disp(ansf,ftr) if(ftr*ftr1 .ge. 0.) goto 249 rtsf(1) = ansfgoto 210 249 ftr1=ftr 250 write(6,251)ijk, rtn, rtw, ansf, ftr 251 format(1x, 'ersum 'i3,2(1x,f10.7),1x, 'ansf= 'e14.6, ' ftr= 'e14.6, 1/ 4x, 'but, no root is found. ') 240 continue 220 neft(ij)=sqrt(rts) ijkm=0 ersum=ersum + (rts -nefmij)*(rts-nefmij) write(6,998)ij, rtn, rtw, rts, dispft 998 format(1x, 'ersum 'i3,2(1x,f10,7),1x, 'rts= 'e14.6,1x, 'disp= 'e14.6) 100 continue return end

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subroutine grdt(fn, hx, hy, rtx, rty, epsiln) external fn noit=0 100 noit=noit+1 fO=fn(rtx,rty) f1=fn(rtx+hx, rtu) f2=fn(rtx,rty+hy) f3=fn(rtx-hx, rty) f4=fn(rtx,rty-hy) f5=fn(rtx+hx, rty+hy) f6=fn(rtx-hx,rty+hy) f7=fn(rtx-hx, rty-hy) f8=fn(rtx+hx, rty-hy) sx=(f1-f3)/(2. #hx) sy=(f2-f4)/(2, *hy)sxx=(f1 -2. #f0 +f3)/(hx#hx) syy=(f2 -2. +f0 + f4)/(hy+hy)sxy=(f5 - f6 -f8 + f7)/(4. *hx*hy) write(6, 141)f0, f1, f2, f3, f4, f5, f6, f7, f8, sx, sy, sxx, sy, sxy 141 format(3x, 'grdt f0, f1,f2,f3,f4 f5,f6,f7,f8 sx,sy sxx,syy,sxy ' $1/3x_1 e_{12}$, 4, /4(3x, e_{12}, 4)/4(3x, e_{12}, 4)/4(3x, e_{12}, 4)/2(3x, e_{12}, 4) 2/3(3x, e12.4)) det=sxx*syy −sxy*sxy rtx1=rtx + (sy*sxy -sx*syy)/det rty1=rty + (sx*syy -sy*sxx)/det write(6,142)det, rtx,rty,rtx1,rty1 142 format(3x, 'det= 'e14.6, 1/3x, 'rts, rtu= '2(3x, e14. 6) /3x, 'rtx1, rty1= '2(3x, e14. 6)) error=sqrt((rtx1-rtx)*(rtx1-rtx) +(rty1-rty)*(rty1-rty)) error=error/sqrt(rtx*rtx +rty*rty) write(6,998)noit if(error .le. epsiln) goto 110 rtx=rtx1 rtu=rtu1 998 format(3x, 'grdt noit= 'i4) noit=noit+1 if(noit .gt. 20) write(6,120) if(noit .le. 20) goto 100 120 format(3x, 'more than 20 iteration. ') 110 return end 32.8 1 2 28.8





Figure 2 End Fire Coupling

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EFFECTIVE INDEX OF REFRACTION



figure 4 Effective refractive index vs coupling angle for a rutile prism



Thickness: 0.4375" For rutile prisms, the optical axis should be perpendicular to the paper.

Figure 5 A possible design for a prism.









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ri in Material	Polyure	į	Epaxy Resins	teed-Sillce	Polymethy! methacrylate (PHWA) and styrema-acrytanitrile copolymmer (SAM)	Polystyrene (PS)		Photoresists	$\left[\right]$
Compared A	Epoxylite 9653-1 A	Nidiand LRSOD 7-C-23	Areidite 509	Emisitone 112, A	Dupont Elvacita 2009 (PNMA)	Polymerised polystyrens	Shipley A2-1350	Shipley AL-1350	Rodeh IJPR
e punadacoj	E powylice 9653-1 B	Nidland LE500 10-6-32	Areldice 951	Emulsitone 112, 6	Union Carbide, RND \$500 (SAM)			.	
Thimer C or Solvent	Ridiana 66-C-30	17 -1-30	07-3-99	Methanol	/tethlisobutylectone (MIBK) with .013 GE silicon oil (electronic stade) stali (so)	Toluene just below boiling soint ('100°C)		.	
Thinner .			Ethenel					.	T.
Autio A-0:0:0	tata t	31:115	7:1:16:72	teta.	SAM, Preva any proportion, seivent 10% wt.	1 g. of P5 in 50 c.c. of solvent			
Drying Environment	ale	alr	e î r	1	litrogen	alr			;
Brying Time)0 min.	60 min.	60 min.	60 min.	30 aln.	IS ain.		5 ain.	60 min.
Builing Tangaratura	65°C	3.59	3.001	10°C	5,08 3,74			3.99	3.56
Baning Time	60 min.	120 ain.	120 min.	10 =1n.	73 hrs. 24 hrs.			S ain.	S ala.
Typical Thickness	1	1 4.2	1 2.2	m 6.0	2 ° 3.5 m	0.2 - 0.5 μπ	- 0.6 un after	- 54:0 -	3 5-
Index of file at .6]]	1.555	1.573	1.581	1.664	I.489 to I.563, adjustable	1.9	1.618	• •	1.615
Acconuction of .6]] we	l at/ca	* **/ca	0.3 db/cm	0,5 dB/cm	- 0.2 dl/cm for 2 um or thinner - 1.2 dl/cm for 1.5 um film	- 1 d0/cm			7 dh/c=
de l'eronce	£. 7	¥. ¥	hr. 26	hef. 26	laf. 21	R(. 2	Aef. 25	m(, 26	M1. 24
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Table 2. Optical Waveguides on Glass by r.f. sputtering

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Substrate Material	Glass	Corning 8370	Glass	Soda-lime glass
Film Material	Corning 7059	Corning 8390	Zn0	Corning 7059
Sputtering Ambient	0 ₂	1	Ar and O ₂	80% Ar, 20% 0 ₂
Pressure	1	1		1x10 ⁻³ to 3x10 ⁻³ Torr
R.F. Power Density	,	t	I	0.8 to 4.0 w/cm ²
Typical Film Thickness	שח 3.	.76 µm	1.59 µm	8
Index at .633 µm	1.62	1.73	1.973	1.53 to 1.58 (depending on r.f. power)
Attenuation at .633 µm	l dB/cm	1	ĩ	~ l.8 dB/cm
Reference	Ref. 31	Ref. 32	Ref. 35	Ref. 33, 34

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Table 3 Fabrication Parameters for Forming lon-Exchanged Waveguides

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Substrate	Soda-lime glass	Aluminosilicate	Soda-lime glass	Soda-lime glass	Soda-lime glass	Soda-lime glass	Soda-lime glass	Boros i l i cate g l ass
lon Sources	AgNO ₃ meits	KN0 ₃ melts	AgN0 ₃ melts	1% AgNO ₃ in NaNO ₃	Li ₂ So ₄ , 80 mol.\$ K ₂ So ₄ , 20 mol.\$	Thermally evaporated Ag vapor	AgNO ₃ or Ag Film	Mixture of TIN0 ₃ ,KN0 ₃ & NaN0 ₃
Exchanging ions	Ag ** Na +	K +• Na⁺	Ag tu Na ⁺	Ag t_s Na ⁺	Litena ⁺	Ag + Na +	Ag + Na +	T1 + X+ T1 + Na+
Temperature (typical value)	225°-270°C (225°C)	360°-365°C	220°-350°C (280°C)	315°C	520°-620°C (575°C)	215°-245°C	170°-300°C (250°C)	530°C
Duration	24 hrs.	24 hrs.	16-256.min.	2 hrs.	1-17 min.	1-32 min.	15-120 min.	23 hrs 72 hrs
Electric field	0	0	0	0	0	(5~10)×10 ⁴ v/m	0~5×10 ⁵ v/m	700 V/m
Δn at .633 µm	0.08	O	0.095	Depending on dilution	0.015	0.08		0.005 to 0.1
No. of Modes	8	-	multimodes	Depending on dilution	17	12	1	1
Attenuation at .633 µm	0.1 dB/cm		ł		0.5-1.2 dB/cm	1 dB/cm		.1 dB/cm
References	Ref. 45	Ref. 45	.Ref. 47	Ref. 51	Ref. 48	Ref. 52	Ref. 49	Ref. 44

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Table 4 Fabrication parameters for in-diffuses

LiNb0₃ and LiTa0₃ waveguide

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Substrate	LINb03	Linbo ₃	LiTa03	LiTa03	LiTa03	LiTa03
Metal to be diffused (typical)	TI,V,NI (TI)	Ti **	QN	ą	3	Cu or CuO
Thickness before diffusion	200-800Å	100-500Å	150-1500å	200-1300Å	5000Å	
Temperature	850-1000°C (960°C for T1)	1050°C	1100°C*	1200°C *	800°C	550°C
Duration	6 hrs.	5 hrs.	- 6 hrs.	4-18 hrs.	- 1 hr.	l hr.
Atmosphere	Flowing Ar, 0 ₂	Flowing 0 ₂	Ar	Ar	Air or Ar	Air
Electric field during diffusion	0	o	0	0	o	10 ⁴ v/m
Diffusion depth	1-3 µm	1-2 µm	I	1	120 µm	25 µm
dn at .633 µm	Δn _o ⁻ 0.01 Δn _e -0.04	1	۵.0 [°] 0 م	∆n [~] 0.018 ⁰ to 0.03	۵۵ [°] 0.003	Δn ₀ ~0.005 Δn _e ~0.005
Attenuation at .633 µm	~l dB/cm	•	ı	1.2 dB/cm	•	•
References	Ref. 60	Ref. 64	Ref. 55	Ref. 57	Ref. 56	Ref. 56
*Poled following diffusion	5					

**Purity of Ti: 99.97\$

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