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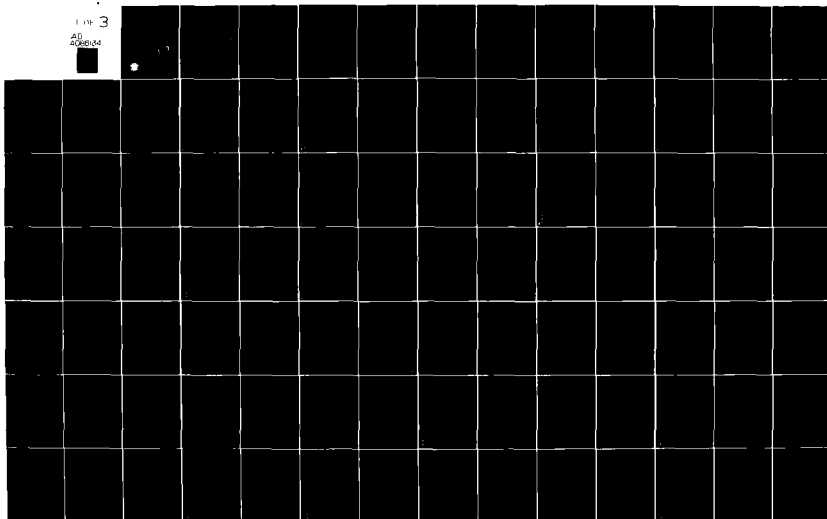
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DESIGN AND IMPLEMENTATION OF A SPEECH CODING ALGORITHM AT 9600 --ETC (11)
APR 80 J L MELSA, D L COHN, A ARORA DCA100-79-C-0005

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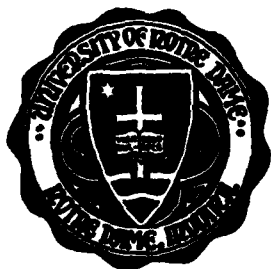
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FINAL REPORT
VOLUME 2

DESIGN AND IMPLEMENTATION
OF A SPEECH CODING ALGORITHM
AT 9600 B/S

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Department of

ELECTRICAL ENGINEERING

UNIVERSITY OF NOTRE DAME, NOTRE DAME, INDIANA

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FINAL REPORT
VOLUME 2
DESIGN AND IMPLEMENTATION
OF A SPEECH CODING ALGORITHM
AT 9600 B/S

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Prepared for

Defense Communications Agency
Defense Communications Engineering Center
1860 Wiehle Avenue
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✓ to generate very high quality speech output. Although each of these elements has been previously applied to speech coding, the combination of all four of these elements has not been studied before. The speech coding algorithm has been implemented on a pair of CSPI MAP 300 Array Processors in real-time in the full-duplex mode.

This report has been bound in two volumes. The first volume contains the narrative description of the algorithm and its development and includes Chapters 1 through 11 and Appendices A through D of the report. The second volume describes the real-time MAP implementation and includes Chapters 12 and Appendices E through G. ✓

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ABSTRACT

This report describes a speech coding algorithm for digital transmission of speech at a rate of 9600 bits per second and the implementation of this algorithm on a speech processing system.

The algorithm combines

- Pitch extraction loop
- Pitch compensating adaptive quantizer
- Sequentially adaptive linear predictor
- Adaptive source coding

to generate very high quality speech output. Although each of these elements has been previously applied to speech coding, the combination of all four of these elements has not been studied before. The speech coding algorithm has been implemented on a pair of CSPI MAP 300 Array Processors in real-time in the full-duplex mode.

This report has been bound in two volumes. The first volume contains the narrative description of the algorithm and its development and includes Chapters 1 through 11 and Appendices A through D of the report. The second volume describes the real-time MAP implementation and includes Chapters 12 and Appendices E through G.

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CHAPTER 12

THE REAL-TIME IMPLEMENTATION

12.1 Introduction

In this chapter, the final form of the real-time implementation of the PARC algorithm in a full duplex mode will be presented. The whole implementation will be decomposed into four parts. Each part is described in detail in the following sections. Block diagrams, flow charts and timing diagrams are given to help reader understand the implementation. The program listings are in Appendix G.

Before presenting the implementation, the system components used will be described. A MAP-300 (Macro Arithmetic Processor) produced by Computer Signal Processing, Inc. is used to implement the speech coding algorithm (see Table 12.1). A host computer and MAP-300 system block diagram is shown in Fig. 12.1. The MAP-300 consists of six programmable processing elements as well as memory and peripherals:

- A. A Central Processing Unit (CSPU) functions as the executive controller by interpreting commands from the host computer, setting up and scheduling the other processors, and performing arithmetic and logic operations.
- B. An Arithmetic Processor (AP) consists of two subprocessors. An Arithmetic Processing Unit (APU) carries out the floating point arithmetic calculations. An Arithmetic Processing Scroll (APS) is a data addressing device for the APU.
- C. An Input/Output Scroll (IOS-2) transfers bit streams into or out of a modem.
- D. An Analog Data Acquisition Module (ADAM) samples and quantizes input analog signals into digital signals and stores them into main memory.

Table 12.1
MAP-300 Speech Processing System

Item No.	Qty.	Model Number	Description
1	1	1030	MAP-300 Processor
2	1	2030	8K x 32 MOS Memory
3	1	2050	16K x 32 MOS Memory
4	1	2203	8K x 32 MOS Memory
5	1	2120	2K x 32 Bipolar Memory
6	1	3100	PDP-11 Interface
7	1	4020	Model 2SM/ I/O Scroll
8	2	4040	Bus Switch
9	1	5120	Analog Data Acquisition Module
10	1	5130	Analog Output Module
11	1	6100	Expansion Chassis
12	1	6200	Auxiliary Power Supply
13	1	03-1360585	GTE Speech Processing Interface

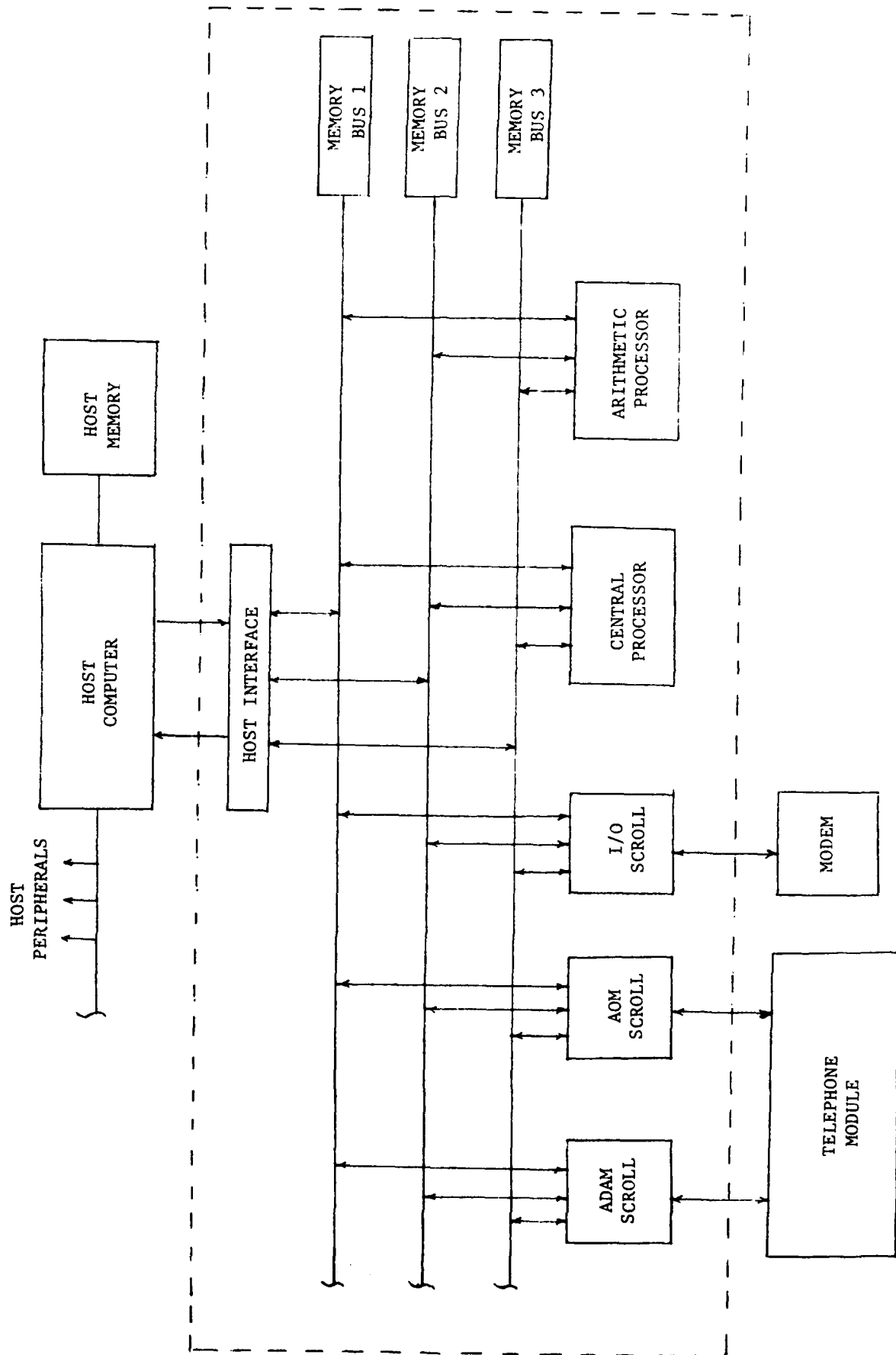


Fig. 12.1 MAP-300 System Block Diagram

- E. An Analog Output Module (AOM) converts input digital signals into analog signals and outputs them to a telephone module.
- F. A Host Interface Scroll (HIS) acts as a communication and data transfer medium between the host computer and the MAP-300 system.

This array processor system provides two classes of software. The first class is the software designed specifically for array processing. It is an executive-driver-subroutine package resident in the MAP-300 and in the host computer which permits direct calling of routines to perform arithmetic operation, to manage MAP memory, to define even higher level routines. A MAP user can execute array processing operations with simple Fortran calls in the host computer. The sophisticated programmer even can implement his own processing algorithms in MAP assembly languages. To implement the PARC digitization system, some new array and non-array functions, which are described later, are employed. The second class consists of utility programs including a cross-assembler and a cross-simulator. These may be used to add new routines to the array processing library.

The array processor can be used as a peripheral to a host computer, using host peripherals for data storage and interface for data and commands transfer between them. However, after initialization, it can stand alone by using proper control functions in the host.

The underlying design principles of the real-time implementation are as follows: First, in order to study system performance, the flexibility of changing system parameters such as speech algorithm parameters, buffer sizes and buffer starting locations must be provided. Second, in order to be in the real-time mode, the arithmetic execution time and the overhead time have to be reduced. The arithmetic execution time can be

decreased by efficiently utilizing the arithmetic processors. The overhead time can be decreased by utilizing all processors as asynchronously and as simultaneously as possible. However, the necessary synchronization between processors has to be carefully considered.

After several months of study, the final real-time PARC communication system consists of the following programs:

1. Host programs: Fortran PARC main program
Fortran PARC host support program
2. AP programs: PARC-transmitter pitch computation program
PARC-transmitter speech digitization program
PARC-receiver
3. CSPU programs: Encoder program
Decoder program
Synchronization program
Transmitter buffer pointers update program
Receiver buffer pointers update program
4. IOS programs: ADAM program
ADM program
IOS-2 program

The main function of the host Fortran programs is to initialize the MAP-300 system with the real-time PARC algorithm, to set up the proper command sequences and to initiate them. After that, the MAP-300 system can execute the PARC without any further commands from the host computer. The two PARC-transmitter programs and the PARC-receiver program require sophisticated arithmetic operations and will be executed in the AP. Those programs requiring logic and bit operations include encoder, decoder, synchronizer and address pointers update programs. These will

be executed in the CSPU. A/D converting, D/A converting and bit-transfer will be executed in the ADAM, the AOM and the IOS-2 respectively. These five processors operate in parallel. The host Fortran modules will be described below; they present the whole picture of the PARC. The rest of the programs will be presented in the following sections.

The flow chart of the real-time PARC main program is shown in the Fig. 12.2. The module can be divided into two steps: An initialization step and a processing step. In each step, each processor has its own role.

1. The initialization step:

In this step, the host computer will initialize the whole algorithm by reading in system parameters, configuring logical buffers, initializing logical buffers, loading ADAM and AOM, and creating appropriate command sequences called function lists. The logical buffers and the function lists, which are fairly complicated, will be described later. In this step, only three processors in the MAP-300 system have been used as follows:

- A. The CSPU acts as the resource controller. Responding to a host command, it loads an A/D program to the ADAM, loads a D/A program to the AOM, configures the logical buffers, and loads appropriate arithmetic functions into the AP.
- B. The AP executes these arithmetic functions which will reset the logical buffers.
- C. The HIS acts as an interface between the host computer and the MAP-300.

The Fortran host support program, which is the host support module for those new array and non-array functions in the real-time PARC

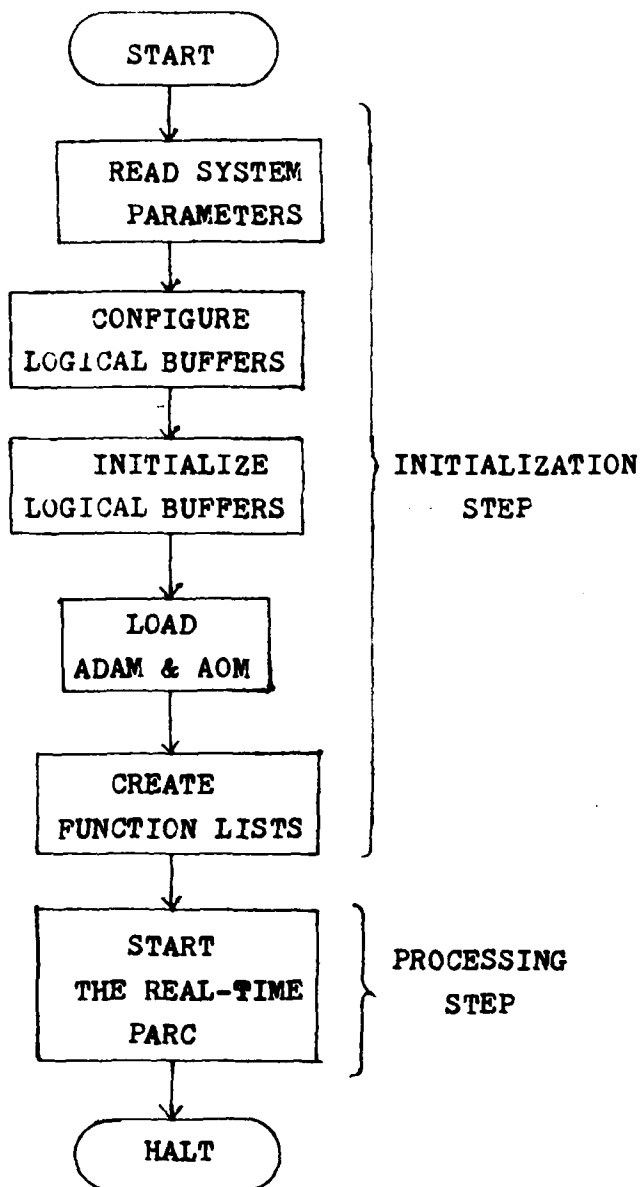


Fig. 12.2 The Flow Chart of the Main Program

algorithm, interfaces the main program to the host/MAP driver module.

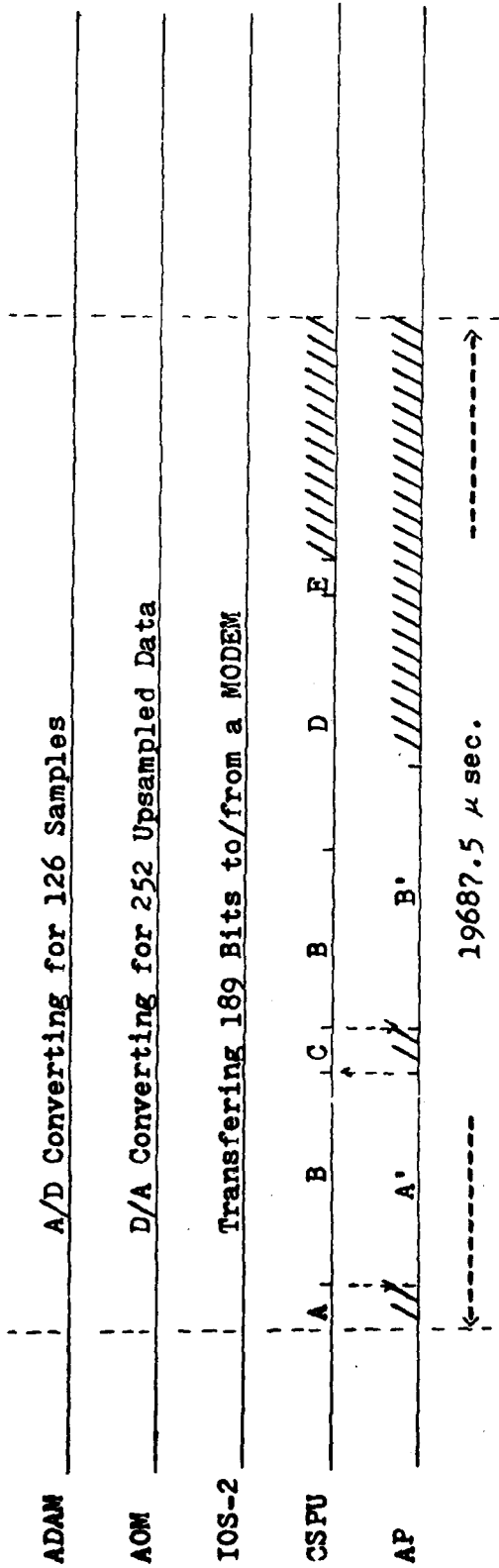
The main functions of this support program are as follows:

- 1) Check each argument for the proper range and return error code.
- 2) Pack arguments for the MAP in a Function Control Block (FCB)
- 3) Determine any host absolute addresses that must be evaluated while constructing the Data Control Block (DCB).
- 4) Pass DCB to the host/MAP driver.

2. The processing step:

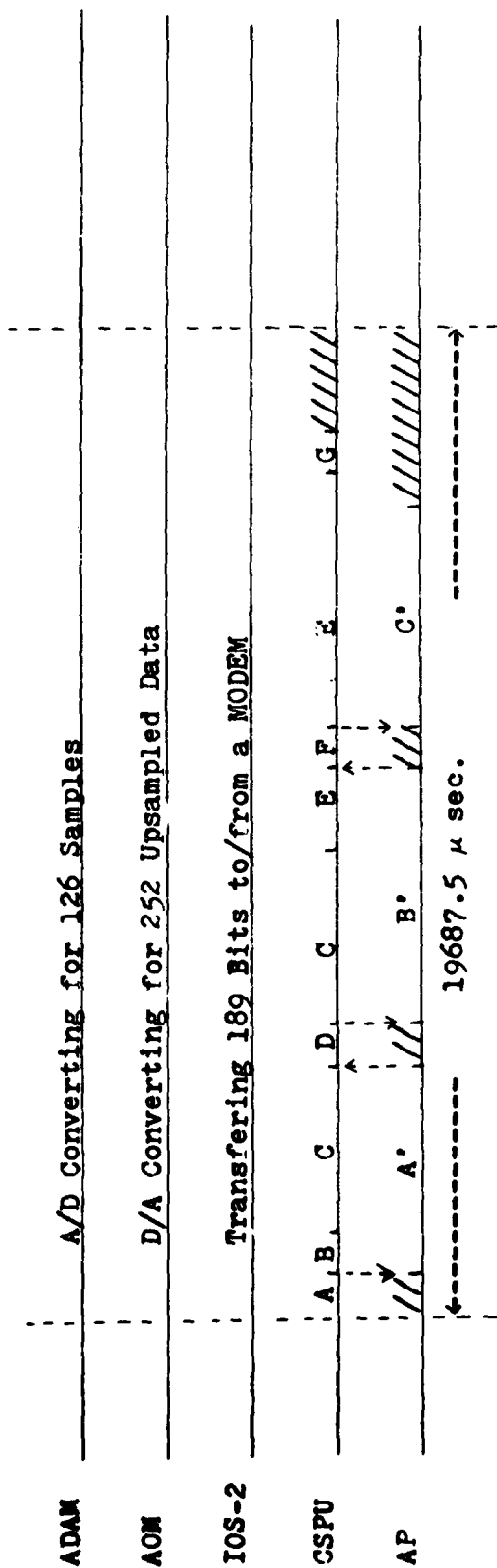
After initialization, the MAP-300 can execute the real time PARC algorithm without any further commands from the host computer. Because of the fixed delay for the whole system (refer to Section 2.2), a fixed time slot has been chosen as a main parameter to synchronize all the processors in the MAP-300 system as shown in Fig. 12.3 and Fig. 12.4. In each time slot, a particular function list, which is described below, will be executed. This fixed time slot is set to be 19687.5 microseconds which is precisely the period for ADAM to process 126 samples, the period for AOM to process 252 upsampled data, and the period for IOS-2 to process 189 bits.

The function lists, whose relationships are shown in Fig. 12.5, are eight sets of command sequences. When the real-time PARC is initiated, the first function list, which starts the ADAM, the AOM and the IOS-2, is executed. Afterward, the main control function list (the second function list) is executed by the CSPU. This function list assures the synchronization of the receiver. The execution of the list is as follows:



- A: Load the APU and the APS with the Pitch Computation Program
 B: Encoder
 C: Load the APU and the APS with the Speech Digitization Program
 D: The Channel Synchronization Program
 E: Update the PARC-Transmitter Address Pointers
 A': The Pitch Computation Program
 B': The Speech Digitization Program

Fig. 12.3 The Timing Diagram for the Synchronization Operation



- A: Load the APU and the APS with the Pitch Computation Program
- B: Update the PARC-Receiver Address Pointers
- C: Encoder
- D: Load the APU and the APS with the Speech Digitization Program
- E: Decoder
- F: Load the APU and the APS with the PARC-Receiver Program
- G: Update the PARC-transmitter Address Pointers
- A': The Pitch Computation Program
- B': The Speech Digitization Program
- C': The PARC-Receiver Program

Fig. 12.4 The Timing Diagram for the Normal PARC Operation

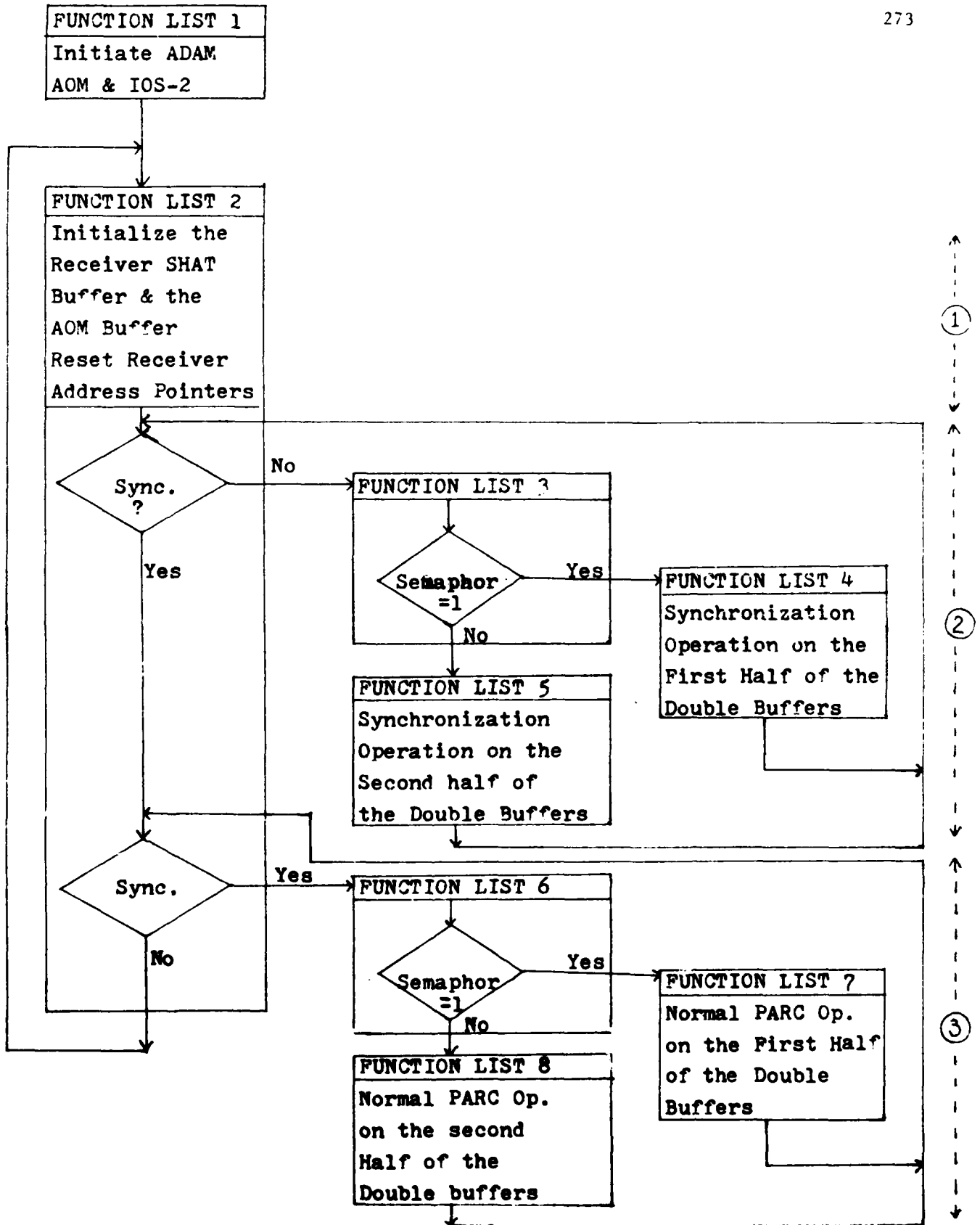


Fig. 12.5

The Flow Chart of Function Lists

1. It initializes the receiver SHAT buffer and the AOM buffer.
Also, it resets the receiver address pointers.
2. If the channel synchronization does not exist, it keeps executing the synchronization operation until a channel synchronization is set. The synchronization operation consists of the PARC-transmitter, the encoder and the synchronizer.
3. If the channel synchronization exists, it keeps executing the normal PARC operation until a channel synchronization is lost.
The normal PARC operation consists of the PARC-transmitter, the encoder, the decoder and the PARC-receiver.
4. Go to 1.

Because of parallel data processing which speeds up the whole system (refer to the Section 2.2), the double buffering technique is employed. Therefore, the synchronization operation and the normal PARC operation each consists of three function lists: A control function list, a function list which operates on the first half of the double buffers and a function list which operates on the second half of the double buffers. The control function list checks a semaphore which resides in the MAP memory and then executes a function list which will operate on the proper buffers. The reason for this is to have a continuity of data flow for the PARC-transmitter. For instance, suppose the receiver loses the channel synchronization after the normal PARC operation on the first half of the double buffers. Then the main control function list executes the synchronization operation. The control function of the synchronization operation checks the semaphore and then executes the synchronization operation on the second half of the double buffers. So, the transmitter

gets a continuous data flow. The main control function list will keep executing until the MAP-300 system is terminated.

In the synchronization operation, which consists of the function lists 3, 4 and 5 (shown in Fig. 12.3), the role of each processor in a time slot is described as follows:

- 1) The ADAM samples and quantizes the input analog signal from the telephone module and stores these samples into MAP main memory. In a time slot, it produces 126 quantized samples.
- 2) The AOM acts as a D/A converter and outputs 252 silence samples since no information flows into the receiver.
- 3) The IOS-2 acts as an input/output interface between the MAP-300 and the channel modem. In a time slot, it transfers 189 bits out of the encoder bit buffer and reads 189 bits into the decoder bit buffer.
- 4) The CSPU functions as follows in sequence:
 - A: It loads the AP with the pitch computation program.
 - B: It executes the encoder. However, upon request from an APU interrupt, it suspends the current operation and
 - C: Loads the AP with the speech digitization program.
It restarts the encoder after the loading.
 - D. It executes the channel synchronization program.
 - E. It updates the PARC-transmitter address pointers.
- 5) The AP executes the arithmetic part of the PARC-transmitter. After finishing each program, it will interrupt the CSPU to indicate that it is free for the next operation, if any. In this operation, the AP has two jobs:

A: The pitch computation program.

B: The speech digitization program.

These five processors function in parallel. The ADAM, AOM and IOS-2 operate continuously without any interrupt. However, the CSPU and the AP have to finish their own job inside the time slot in order to be in real-time.

The normal PARC operation (shown in Fig. 12.4) which consists of the function lists 6, 7 and 8, has the same ADAM and IOS-2 operation as the synchronization operation. However, the CSPU, the AOM and the AP have different operations as follows:

- 1) The ADAM samples and quantizes the input analog signal from telephone module and stores these samples into MAP main memory. In a time slot, it produces 126 quantized samples.
- 2) The AOM acts as a D/A converter and outputs 252 unsampled reconstructed speech samples to the telephone module.
- 3) The IOS-2 acts as an input/output interface between the MAP-300 and the channel modem. In a time slot, it transfers 189 bits out of the encoder bit buffer and reads 189 bits into the decoder bit buffer.
- 4) The CSPU functions as follows in sequence:
 - A: It loads the AP with the pitch computation program.
 - B: It updates the receiver address pointers.
 - C: It executes the encoder. However, upon request from an APU interrupt, it suspends the current operation and
 - D: Loads the AP with the speech digitization program. It restarts the encoder after the loading.

- E. It executes the decoder. Upon request from an APU interrupt, it suspends the current operation and
 - F. Loads the AP with the PARC-receiver program. It restarts the decoder after the loading.
 - G. It updates the transmitter address pointers.
- 5) The AP executes the PARC-transmitter and the PARC-receiver. After finishing each program, it will interrupt the CSPU to indicate that it is free for the next processing, if any. In this operation, the AP has three jobs:
- A: The pitch computation program.
 - B: The speech digitization program.
 - C: The PARC-receiver program.

In this operation, the timing control is very important which will be discussed in the next section.

The subsequent sections will describe each of the subsystems in the real-time PARC system. The next section explains the design of the PARC-transmitter. The complicated buffer system, buffer control and the speech digitization will also be described. The corresponding noiseless source encoder will be explained in Section 12.4.

Section 12.3 describes the design of the PARC-receiver. Although some parts of the system are the same as in the transmitter, the different design of the buffering and upsampling will be depicted. The corresponding noiseless source decoder will be explained in Section 3.5.

12.2 The PARC-Transmitter

In this section, the main line of the real-time PARC-Transmitter, which resides in the AP, will be presented. The corresponding encoder will be discussed in Section 12.4. The block diagram of the PARC algorithm is shown in Fig. 2.2 and discussed in Chapter 2.

Because of the limit on the size of the AP memory, the whole PARC-Transmitter algorithm cannot be implemented as a single AP program. So, the PARC-Transmitter has to be cut into two subprograms, namely, the pitch computation program and the speech digitization program, as shown in Fig. 12.6. Those portions of the algorithm which operate on blocks of speech samples will be put in the pitch computation program. Those portions include: input gain factor calculation, system noise reducer, adaptive filter and pitch extractor. These elements of the algorithm which process speech sample-by-sample will be combined into the speech digitization program. These elements are the adaptive quantizer, the inverse quantizer, the adaptive predictor and the pitch extraction.

Before any further description of the design of this PARC-Transmitter, the buffer system has to be depicted. There are seven buffers employed by the PARC-Transmitter as shown in Table 12.2.

Among them, ADAM, LEVEL and BIT buffers are double buffers which allow one processor to fill one half of the buffer while another processor processes on the other half. The SAMPLE, VHAT and SHAT buffers are circular buffers which allow continuous access. However, the additional address pointers, which indicate the starting locations of those circular buffers at the beginning of a time slot, have to be considered. The PARAMETER buffer is a single buffer which stores of system parameters such as predictor coefficients, quantizer output

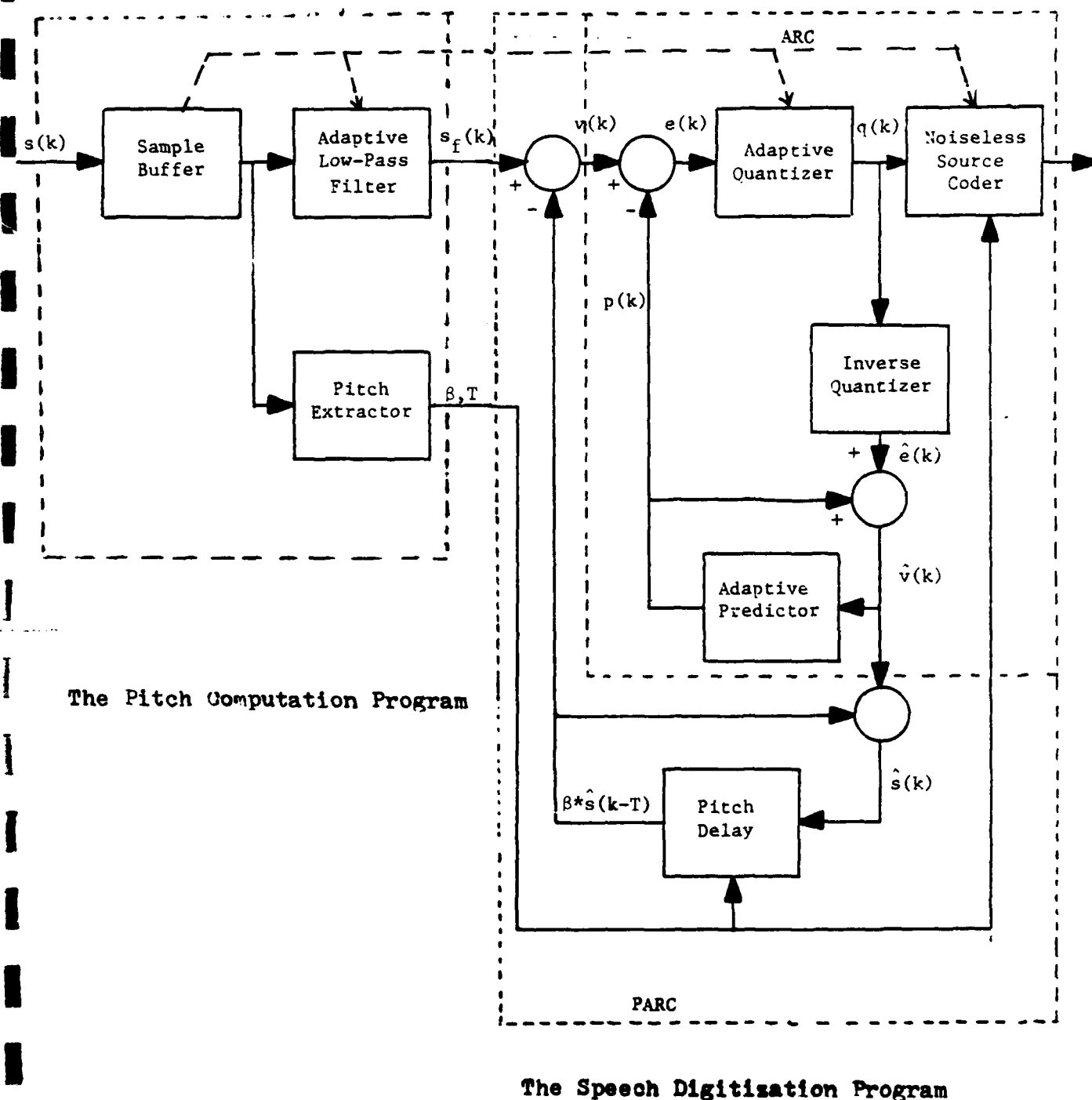


Fig. 12.6 THE BLOCK DIAGRAM OF THE PARC

Table 12.2 Buffer Configuration in the PARC-Transmitter

Name	Bus #	Starting Location	Ending Location	Buffer Size	Buffer Type
ADA1	3	3072 3198	3197 3323	126 126	Double Buffers, Short Floating Point
SAMPLE	3	0	1023	1024	Circular Buffer, Short Floating Point
VHAT	2	0	1023	1024	Circular Buffer, Short Floating Point
SHAT	3	1024	2047	1024	Circular Buffer, Short Floating Point
PARAMETER	2	3072	3231	20	Single Buffer, Long Floating Point
LEVEL	1	25000 27000	25599 27599	600 600	Double Buffer, Long Fixed Point
BIC	1	25700 27700	25899 27899	200 200	Double Buffers, Long Fixed Point

scaling factors, quantizer expansion factors, and the number of bits associated to each quantizer level.

The PARC-Transmitter employs four processors: The ADAM, the AP, the CSPU and the IOS-2. In order to achieve parallel processing, the double buffering technique is used. The function of these buffers associated to the processors at a time slot is shown in Fig. 12.7. At a time slot, the following processes are executed in parallel:

1. While the ADAM is filling a half of the ADAM buffer, the AP is accessing the other half.
2. While the AP is filling a half of LEVEL buffer, the CSPU is accessing the other half.
3. While the CSPU is filling a half of the BIT buffer, the IOS-2 is accessing the other half.

In the next two subsections, the pitch computation program and the speech digitization program will be described. The complicated buffer controller will also be presented.

12.2.1 The Pitch Computation Program

The pitch computation program contains the gain controller, a noise reducer, a buffer controller, the adaptive filter and the pitch extractor. The APU flow chart and the corresponding APS flow chart, including the controlling flows are depicted in Figs. 12.8 & 12.9. The detail functions are described as follows and the parallel processing is shown:

1. In response to the function list, the CSPU loads the APU and the APS modules of the pitch computation program into the APU and the APS respectively.
2. The CSPU then sets flag RI which will initiate the APS module.

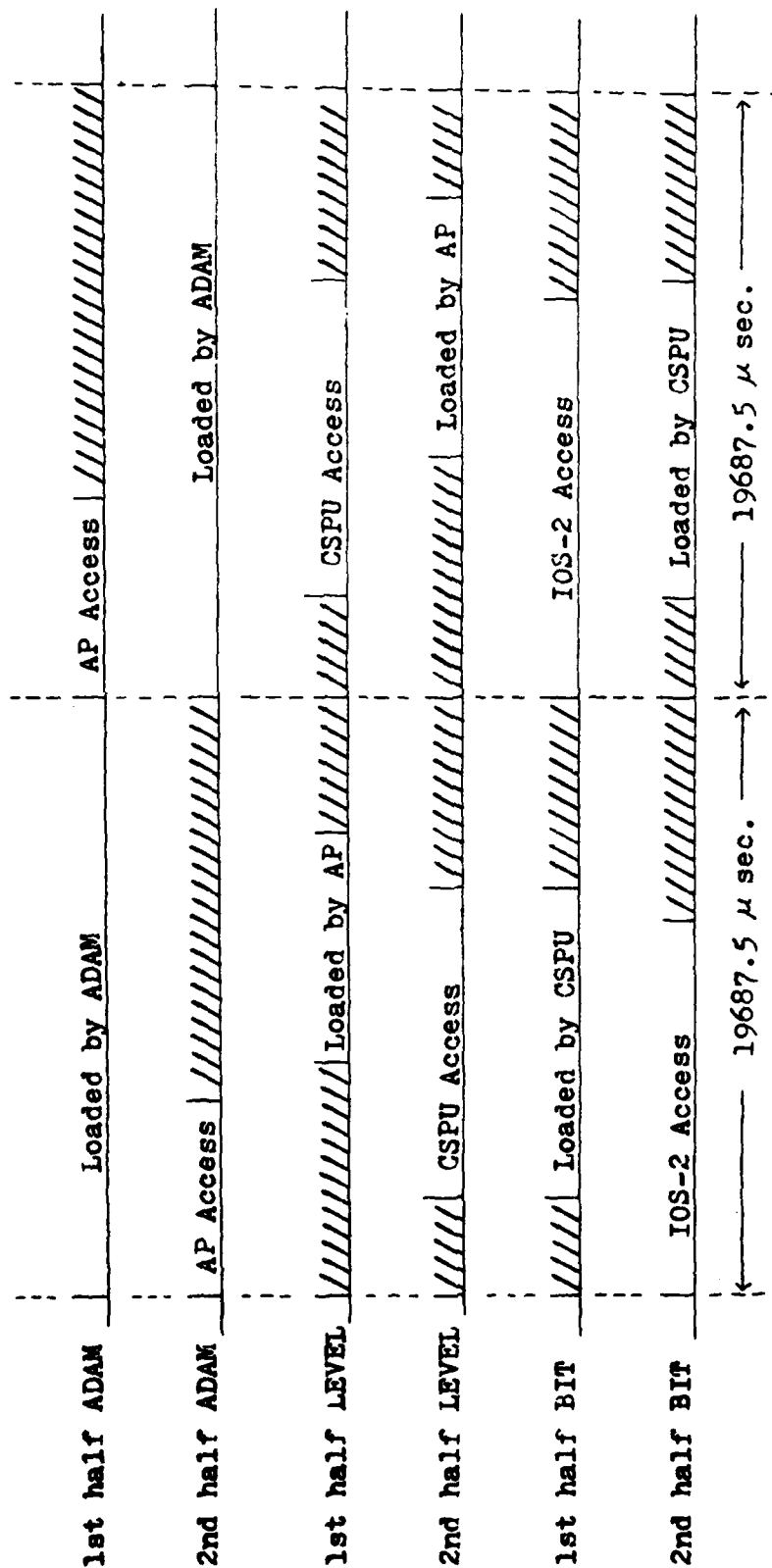


Fig. 12.7 The Double Buffering in the PARC-transmitter

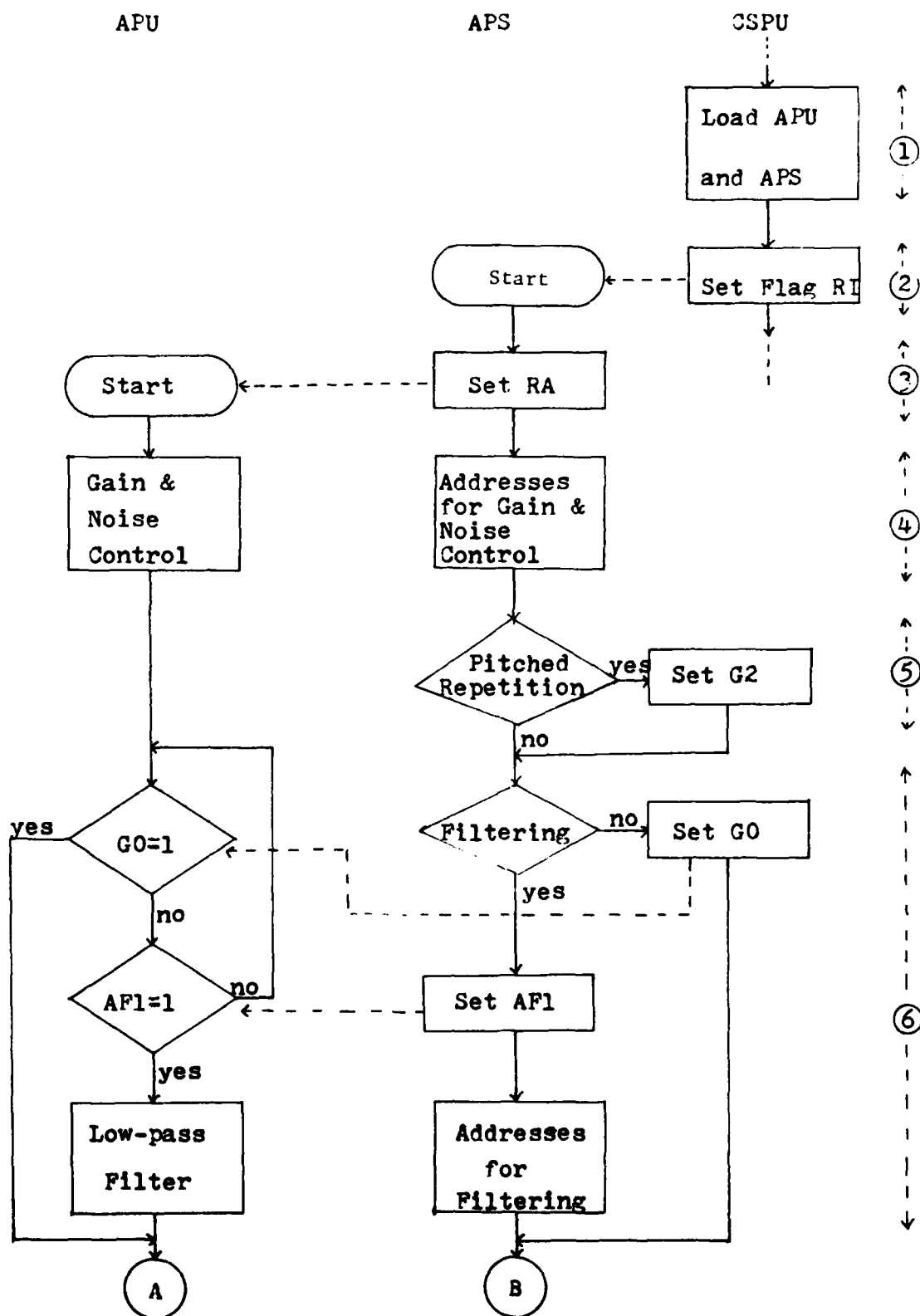


Fig. 12.8a The Flow Chart of the Pitch Computation Program

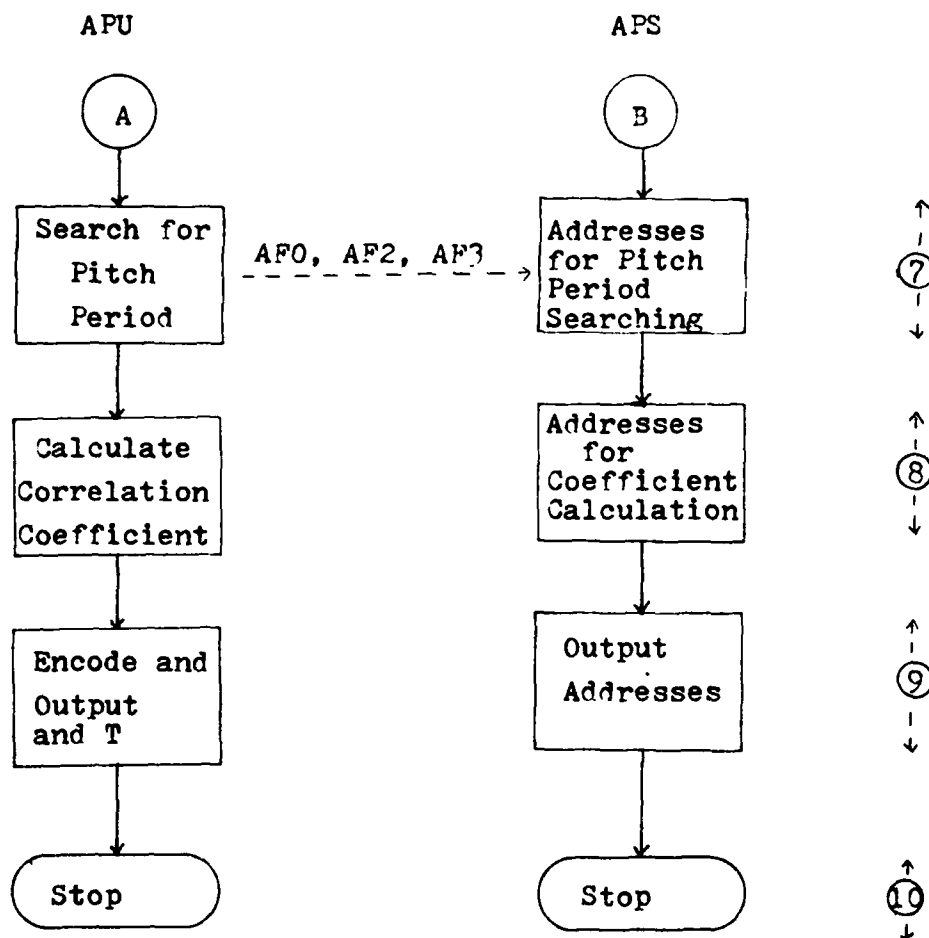


Fig. 12.8b The Flow Chart of the Pitch Computation Program

3. The APS module sets flag RA which will start the APU module.
4. The APS produces the addresses of the noise reducing parameter, the gain factor, 126 input data addresses from the ADAM buffer and 126 output data addresses to the SAMPLE buffer.

The APU reads 126 input samples whose addresses are given by the APS, reduces their noise, multiplies by the gain factor and outputs to the SAMPLE buffer. The input samples from the ADAM are 11-bit precision plus a sign bit in a range of $[2047/2048, -2048/2048]$. After being read by the AP, these are converted into 32-bit floating point numbers.

5. The APS checks the fullness of the SAMPLE buffer, sets the flag G2 if it is over the pitch repetition threshold.
6. The APS again checks the fullness of the SAMPLE buffer. If it is under the filtering threshold, the APS sets the flag G0 and jumps to Step 7. If it is over the threshold, the APS sets the flag AF1 and produces addresses for the filtering. The APU waits for the signals from the APS. If the flag G0 is set, it goes to Step 7. Otherwise, it executes the filtering process which is described in Section 2.3.

7. The APS produces addresses for the data used to compute the pitch period. The APU computes the pitch period using the AMDF technique (refer to Section 2.4). In order to speed up the whole real-time system, all processors have to be utilized as asynchronously and as simultaneously as possible., i.e., the minimum use of the communication flags between the APU and the APS. However, because of the limit on the number of the registers in the APS, three flags are used in this portion to search for the pitch period as shown in Fig. 3.9. In this block, the APU determines how many iterations are left to be executed. The APS has to wait for the information, the flags AFO and AF1, at the end of each iteration.
8. The APS produces addresses for the data used to calculate the pitch correlation coefficient. If the flag G2, which indicates the pitched repetition, is set, it produces addresses starting a pitched repetition block behind. The APU calculates the pitch correlation coefficient.
9. The APS produces output addresses. The APU encodes the pitch period and the pitch correlation coefficient and outputs them to the MAP memory.
10. The AP interrupts the CSPU to indicate that it is finished.

12.2.2 The Speech Digitization Program

The speech digitization program contains the pitched repetition, the adaptive predictor, a maximum number of processed samples controller, a reciprocal function, the pitch extraction, the adaptive quantizer, the inverse adaptive quantizer, the bit buffer controller, the underflow controller, and a parameter update. The APU and the APS flow chart including the control flows are depicted in the Fig. 12.10 because the number of samples which are processed by the transmitter varies in each time slot, the flags APO, AF3 and G1 are used to communicate between the APU and the APS. The flag APO, which is controlled by the APU, is used to indicate the beginning of the digitization loop. The flag G1, which is controlled by the APU and the APS, is used to indicate an underflow of the sample biffer or reaching the maximum number of samples permitted in the time slot. The flag AF3, which is controlled by the APU, is used to indicate that at least 157 information bits have been generated.

The detail functions are as follows:

1. In response to the function list, the CSPU loads the APU and the APS modules of the speech digitization program into the APU and the APS respectively.
2. The CSPU then sets the flag RI which will initiate the APS module.
3. The APS module sets the flag RA which will start the APU module.
4. The APS produces the addresses of the system counters. The APU reads in the system counters. The system counters are the BIT counter, SAMPLE counter and the LEVEL counter. Because the fixed time slot is used as the main parameter for the

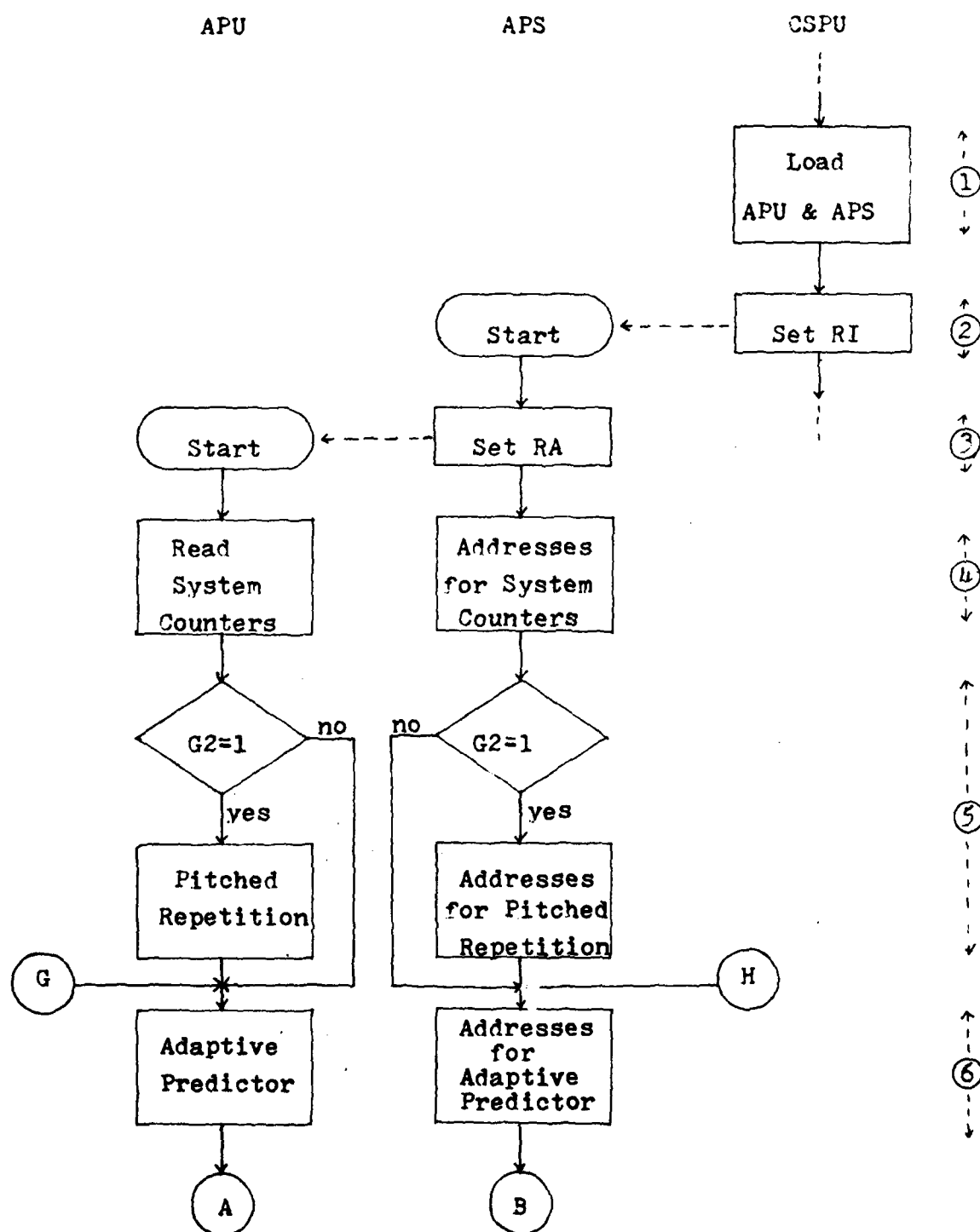


Fig. 12.10a The Flow Chart of the Speech Digitization Program

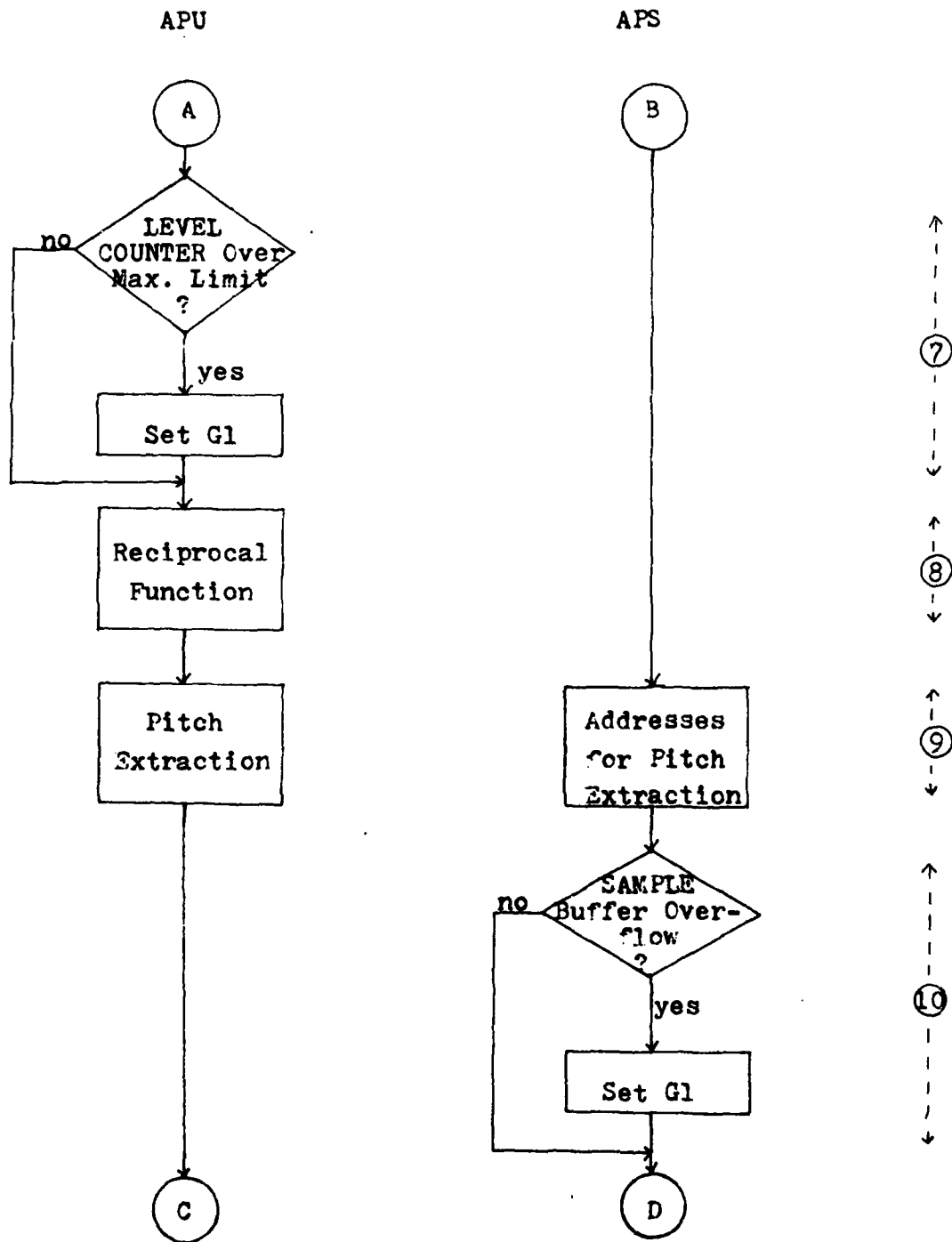


Fig. 12.10b The Flow Chart of the Speech Digitization Program

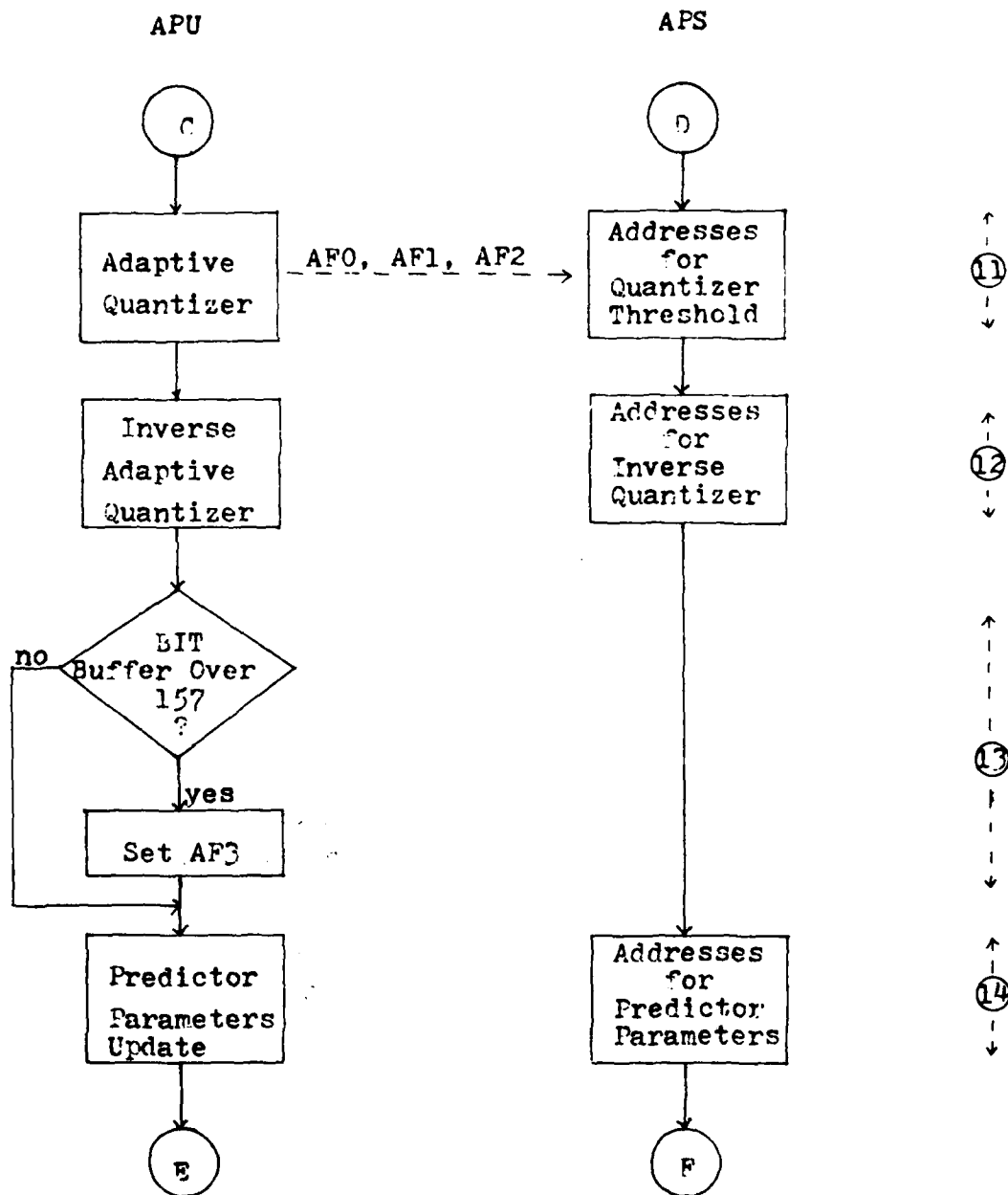


Fig. 12.10c The Flow Chart of the Speech Digitization Program

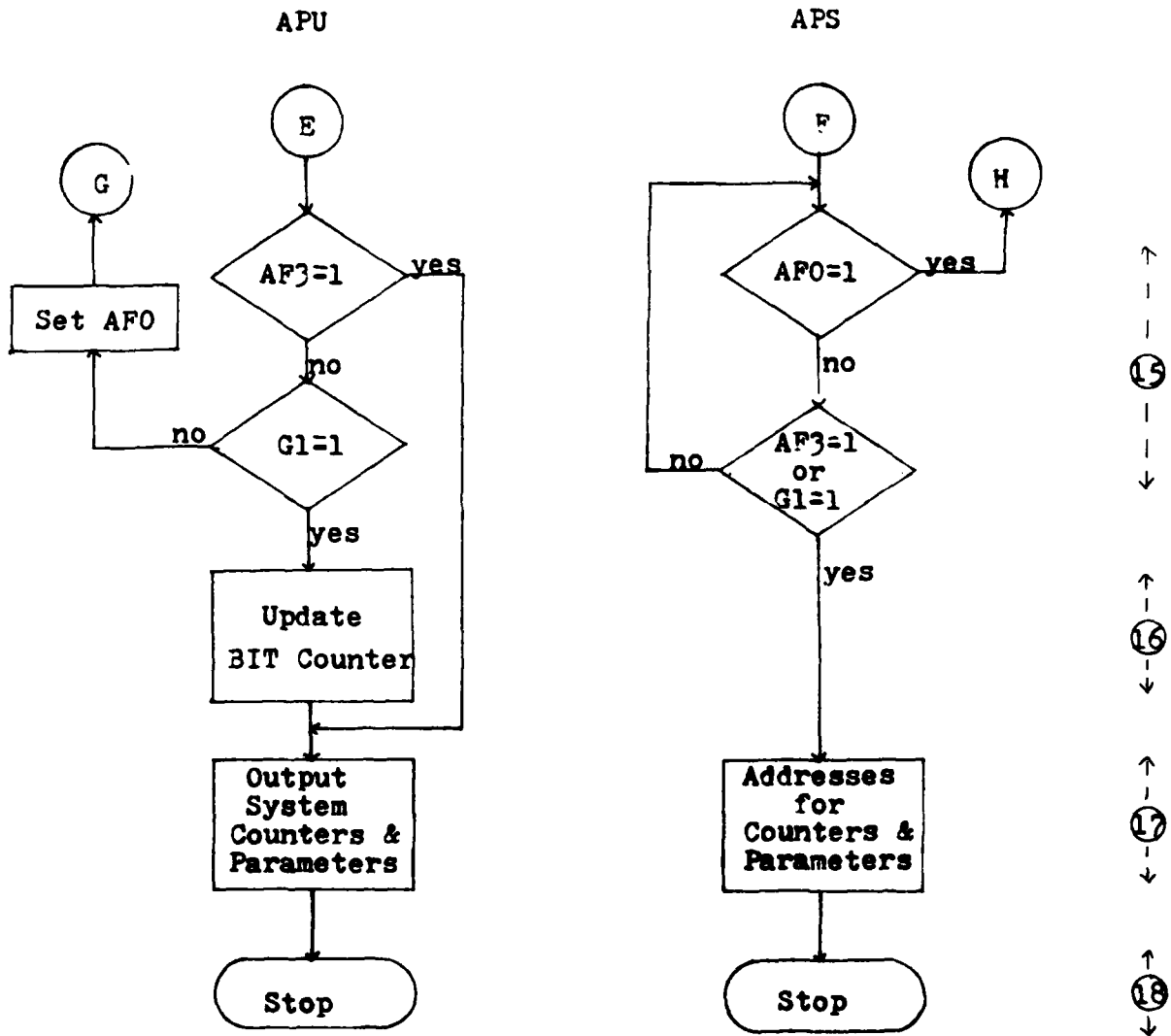


Fig. 12.10d The Flow Chart of the Speech Digitization Program

real-time system, the IOS-2 transfers 189 bits in a time slot. However, as described in Chapter 2, only 157 bits are available to encode the quantizer levels. the BIT counter is used to control the PARC-Transmitter so as to generate just more than 157 information bits. The SAMPLE counter is used to count the total number of samples processed by the PARC-Transmitter during a time slot. The address pointer update program will use this information to update the address pointers in the transmitter circular buffers. The LEVEL counter is used to limit the maximum number of samples which can be processed in a time slot. This assures real-time operation.

5. The APU and the APS check the flag G2 which is controlled by the pitch computation program to indicate the condition of the pitched repetition. If flag G2 is clear, there is no pitched repetition and the APU and the APS go to Step 6. Otherwise, the APS produces the addresses of SHAT buffer for the pitched repetition. The APU executes the pitched repetition. The size of the pitched repetition is a system parameter which can be input from the main Fortran program. The design of the real-time system assumes that the overflow of the sample buffer can be absolutely controlled by the pitched repetition. Thus, the size of the repetition has to be carefully considered.
6. The APS produces addresses for the predictor. The APU executes the predictor which employs a fourth order prediction.
7. The APU checks the LEVEL counter and sets the flag G1, if the counter is over the maximum number of samples allowed to be executed by the PARC-Transmitter.

8. The APU executes the reciprocal function to compute $1/(\text{RMS})^2$ and $1/\sigma$. To do the reciprocal of a 32-bit floating point number, the APU usually employs an 8 x 256 read only memory which has only 8-bit precision in the mantissa part. Thus, a special subalgorithm is used to increase the precision.
9. The APS produces addresses for the pitch extraction. The APU executes the pitch extraction.
10. The APS checks the SAMPLE buffer and sets the flat G1 if the buffer is empty.
11. The APU and the APS quantize the input sample. Three flags are employed to communicate between the APU and the APS. The way to quantize an input sample is as follows:
 - A. The APU signals the APS to produce the threshold address.
 - B. The APU compares the magnitude of the input sample with the threshold.
 - C. If the threshold is larger than the magnitude, the APU signals the APS to stop the searching and jumps to the inverse quantizer portion. Otherwise, the APU checks whether the threshold is the largest one. If it is, the APU signals the APS and jumps to inverse quantizer portion. If it is not, control is returned to Step A.

This design allows variable quantizer levels and reduces searching time, because most of the input samples are dropped in the first two levels.
12. The APU and the APS execute the inverse quantizer.
13. The APU updates and checks the BIT counter and sets the flag AF3 if the 157-bit is reached.

14. The APU and the APS update the predictor parameters.
15. If the flag G1, which indicates an underflow of the SAMPLE buffer or reaching the maximum number of samples permitted in the time slots, is set, the APU goes to Step 16. If the flag AF3, which indicates the condition of BIT counter, is set, the APU goes to Step 17. Otherwise, the APU sets the flag AFO and goes to Step 6. The APS waits for the signals from the APU. If the flag AFO is set, it goes to Step 6. Otherwise, it goes to Step 17.
16. If this step is executed, there has been an underflow in the SAMPLE buffer, i.e., less than 157 bits are generated. The APU updates the BIT counter to account for a NULL code which indicates underflow. If the BIT counter is still less than 157 bits, the BIT counter is reset to synchronize the counters between the PARC-Transmitter and the encoder.
17. The APU and the APS output the contents of the system counters and parameters.
18. The AP interrupts the CSPU to indicate that it is finished.

12.3 The PARC Receiver

In this section, the PARC-Receiver, which resides in the AP, will be presented. The corresponding decoder and channel synchronizer will be explained in Section 12.5. The principal elements of the receiver, which is shown in Fig. 2.8, are also part of the transmitter. So, the implementation of receiver is much the same as that of the transmitter.

Before the description of the design of the PARC-Receiver, the buffer system has to be depicted. There are six buffers employed by the receiver as shown in Table 12.3.

Table 12.3 Buffer Configuration in the PARC-Receiver

Name	Bus#	Starting Location	Ending Location	Buffer Size	Buffer Type
AOM	2	3584	3835	252	Double Buffer, Short Floating Point
		3840	4091	252	
VHAT	3	2048	3071	1024	Circular Buffer, Short Floating Point
SHAT	2	2048	3071	1024	Circular Buffer, Short Floating Point
PARAMETER	2	4096	4255	80	Single Buffer, Long Floating Point
LEVEL	1	26000	26599	600	Double Buffer, Long Fixed Point
		28000	28599	600	
BIT	1	29000	30023	1024	Circular Buffer, Long Fixed Point

Among them, the AOM and the LEVEL buffers are double buffers which allow one processor to fill one-half of the buffer while another processor to process on the other half. This increases the parallel ability of the receiver. The VHAT, the SHAT and the BIT buffers are circular buffers which allow continuous access. However, the additional address pointers, which indicate the starting locations of these circular buffers at the beginning of each time slot, have to be considered. The structures of the LEVEL buffer and the BIT buffer will be explained in Section 12.5. The PARAMETER buffer is a single buffer which stores system parameters such as predictor coefficients, quantizer output scaling factors and quantizer expansion factors.

The flow chart of the receiver is shown in Fig. 12.11. The detailed functions are described as follows and the parallel processing is shown:

1. In response to the function list, the CSPU loads the APU and the APS modules of the PARC-Receiver program into the APU and the APS respectively.
2. The CSPU sets the flag RI which will initiate the APS module.
3. The APS then sets the flag RA which will start the APU module.
4. The APS produces 126 input addresses of the SHAT buffer and 252 output addresses of the AOM buffer. The APU processes the upsampling operation on 126 input reconstructed speech samples and produces 252 unsampled data points. The upsampling operation employs the linear interpolation technique which is explained in Section 2.8. The APU also limits the values of output data to be in the range of $[-2048/2048, 2047/2048]$ which is acceptable for the AOM.

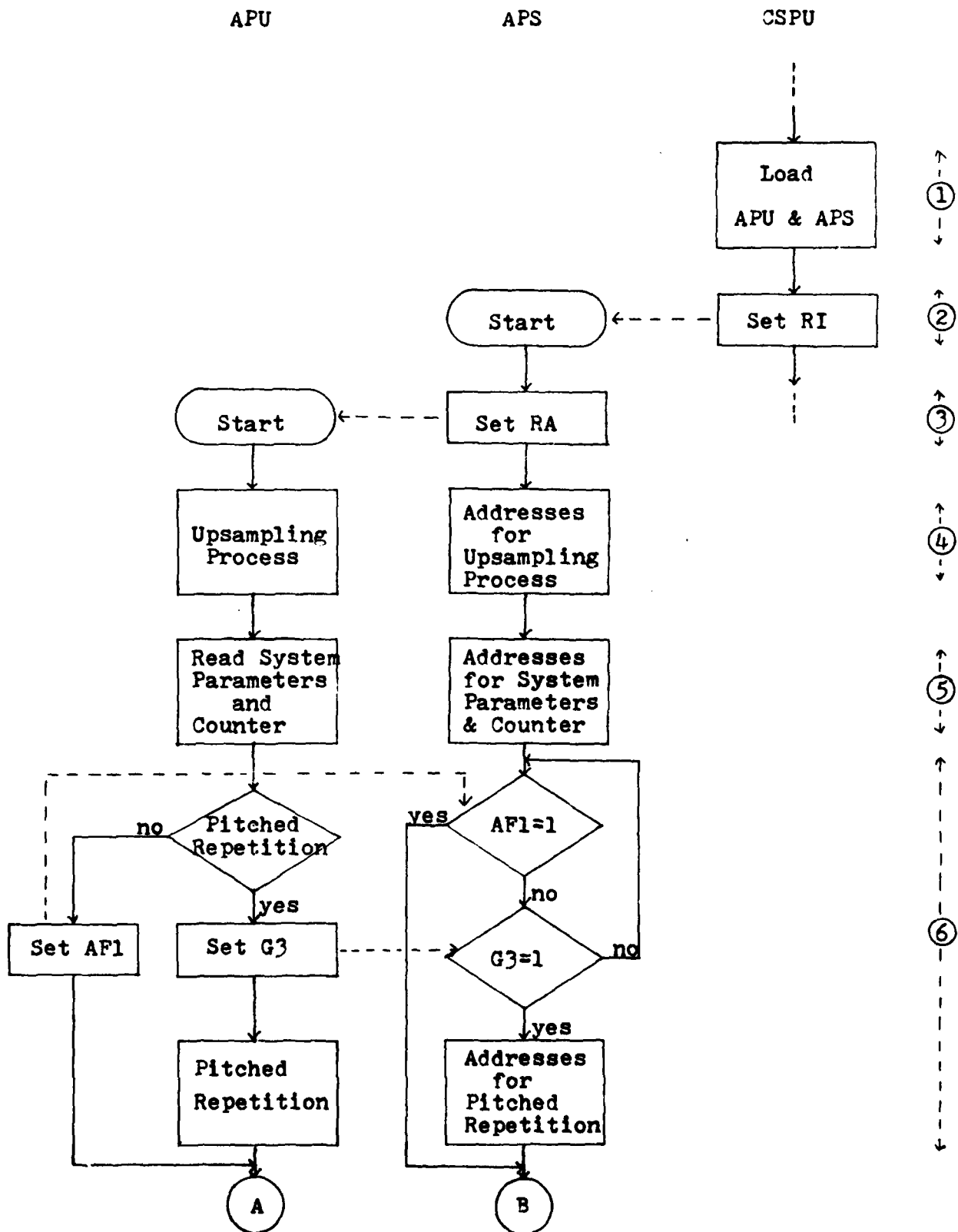


Fig. 12.11 The Flow Chart of the PARC-Receiver Program

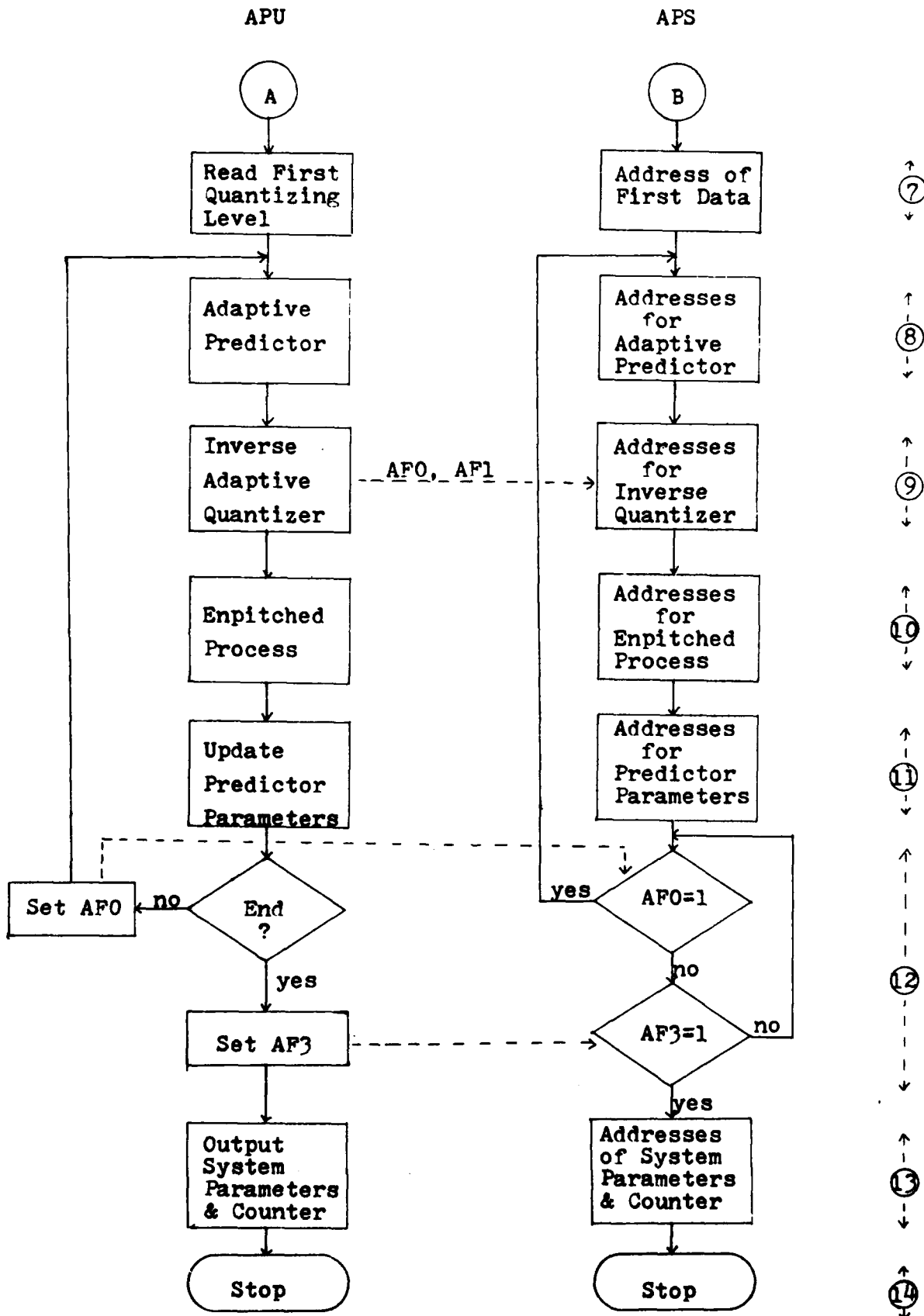


Fig. 12.11 The Flow Chart of the PARC-Receiver Program

5. The APS produces addresses of the system parameters and a counter. The APU reads the system parameters and the counter. There is only one system counter, the SAMPLE counter, which is used to count the total number of samples processed by the PARC-Receiver during a time slot. The receiver address pointer update program will use this information to update the address pointers of the receiver circular buffers.
6. The APU checks the first data in the LEVEL buffer and decides the condition of the pitched repetition. If no pitched repetition is employed, it sets the flag AF1 and goes to Step 7. Otherwise, it sets flag G3 and processes pitched repetition. The APS waits for signals from the APU. If the flag AF1 is set, it goes to Step 7. If the flag G3 is set, it produces addresses for the pitched repetition operation.
7. The APS produces the second data which is the first received quantizing level in the LEVEL buffer. The APU reads the first quantizing level.
8. The APS produces the addresses for the adaptive predictor. The APU processes the adaptive predictor which employs a fourth order prediction.
9. The AP operates the inverse adaptive quantizer. Two flags, AFO and AF1, are used to communicate between the APU and the APS.
10. The APS produces the address of $\hat{V}(K-T)$. The APU restores the pitch redundancy as shown in Eq. (2.1).
11. The APS produces addresses of the predictor parameters. The APU updates the predictor coefficients.

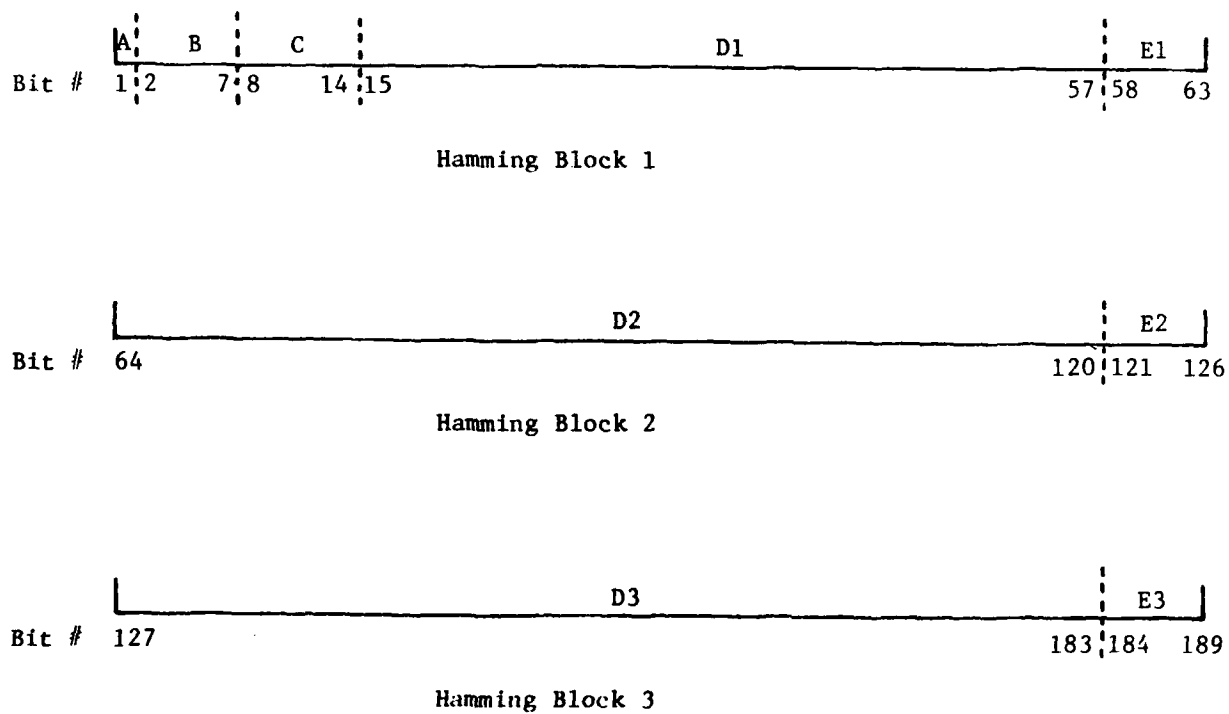
12. The APU reads the next data in the LEVEL buffer and checks whether it has reached the end of the buffer. If it has, the APU sets the flag AF3 and goes to Step 13. Otherwise, it sets the flag AF0 and goes to Step 8. The APS waits for signals from the APU. If the flag AF3 is set, it goes to Step 13. If the flag AF0 is set, it goes to Step 8 to continue the receiver loop.
13. The AP outputs the system parameters and the counter to the MAP memory.
14. The AP interrupts the CSPU to indicate that it is finished with the PARC-Receiver.

12.4 Noiseless Source Coder

This section describes the implementation of the noiseless source coder on the central processor of the MAP 300 called CSPU. As discussed in Section 2.7, the source coder performs several functions. Its primary purpose is encoding the quantizer levels and the side information for each block of N_B samples processed by the PARC transmitter. In addition, it supplies the bit pattern for frame synchronization and the parity code for channel error control.

At its input, the encoder shares a double buffer containing the pitched repetition indicator and N_B quantizer levels each with the PARC transmitter. The corresponding pitch reduction parameters β, T are in two sets of locations in the scalar table. At its output, it shares a double buffer containing 189 bits each with the IOS, the processor which interfaces with a digital modem.

The encoder strives to form a frame of 189 bits from the quantizer levels and the side information generated by the transmitter. The frame is subdivided into three Hamming blocks of 63 bits each. A Hamming block contains 57 information bits and 6 parity bits. Each of the 57 information bits in a block is protected against errors. Depending on whether or not pitched repetition is indicated, the output frame assumes one of two formats Figs. 12.12 and 12.13. The encoder proceeds sequentially to build the different fields in the output frame. It handles one Hamming block at a time. The parity codeword for the block is updated each time a bit is output. Immediately after the 57th information bit in a Hamming block is transferred, the parity codeword for that block is output. The codeword is then initialized for the next block, and the encoder continues to output further information bits. This



Field	Contents
A	Synchronization bit
B	Pitch period T
C	Pitch correlation coefficient β
D1, D2, D3	Quantizer levels
E1, E2, E3	Parity bits for error control

Fig. 12.12 Normal Format for Bit Frame Output of Encoder



Hamming Block 1

Field	Contents
A	Synchronization bit
B	Pitch period T
C'	False β , for pitched repetition
C	Pitch correlation coefficient β
D1	Quantizer levels
E1	Parity bits for error control

Fig. 12.13 Format of first Hamming Block during pitched repetition

process is repeated for three Hamming blocks, completing the output frame of 189 bits.

Fig. 12.14 shows the flow chart for the encoder. The program listing is contained in Appendix G. The encoder starts with field A, Fig. 12.12. It fetches the previous sync bit from a location where it was saved and inverts it. This new value is saved for use in the next frame. It is also output to field A. Next the encoded value of T is fetched and transferred to the output buffer, field B. The value of the pitched repetition indicator is then checked. If affirmative, the code 0000000 is transferred to field C', Fig. 12.13. Next the partially encoded value of β is fetched. It must be between 0 and 96 indicating one of 97 possible levels. Using this as an index, a 7-bit code is retrieved from the β encode table and output to field C, Figs. 12.12, 12.13. After this the quantizer levels are fetched one by one. The corresponding code-lengths and code-words are retrieved from the Q-level encode table and transferred to the output buffer until the fields D1, D2, and D3 are filled. This should coincide with the exhausting of the N_B Q-levels generated by the transmitter.

An exception to this occurs when the sample buffer runs out. The block of quantizer levels do not generate enough bits to fill up the fields D1, D2, and D3. In this case, a null code 11111110 is output to indicate the end of quantizer level information. If there is still more space available, it is padded in with 1's. The null code and the padding bits are error-protected the same as any other information bits.

The source code used here is a variable-length to variable-length mapping, and it is not necessary that fields D1, D2, and D3 are exactly filled by encoding an integer number of quantizer levels. The extra bits after a

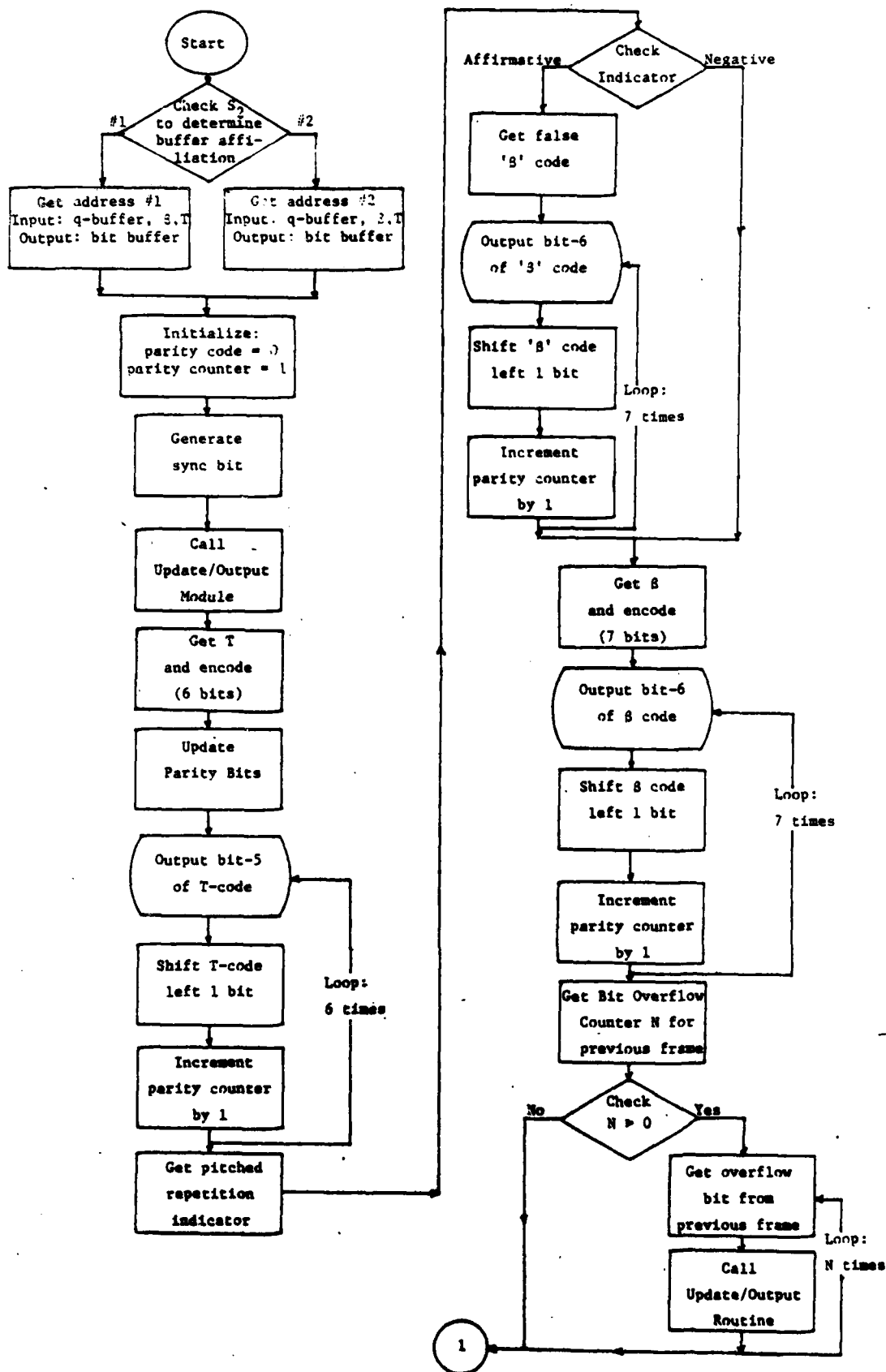


Fig. 12.14a Block Diagram for Encoder

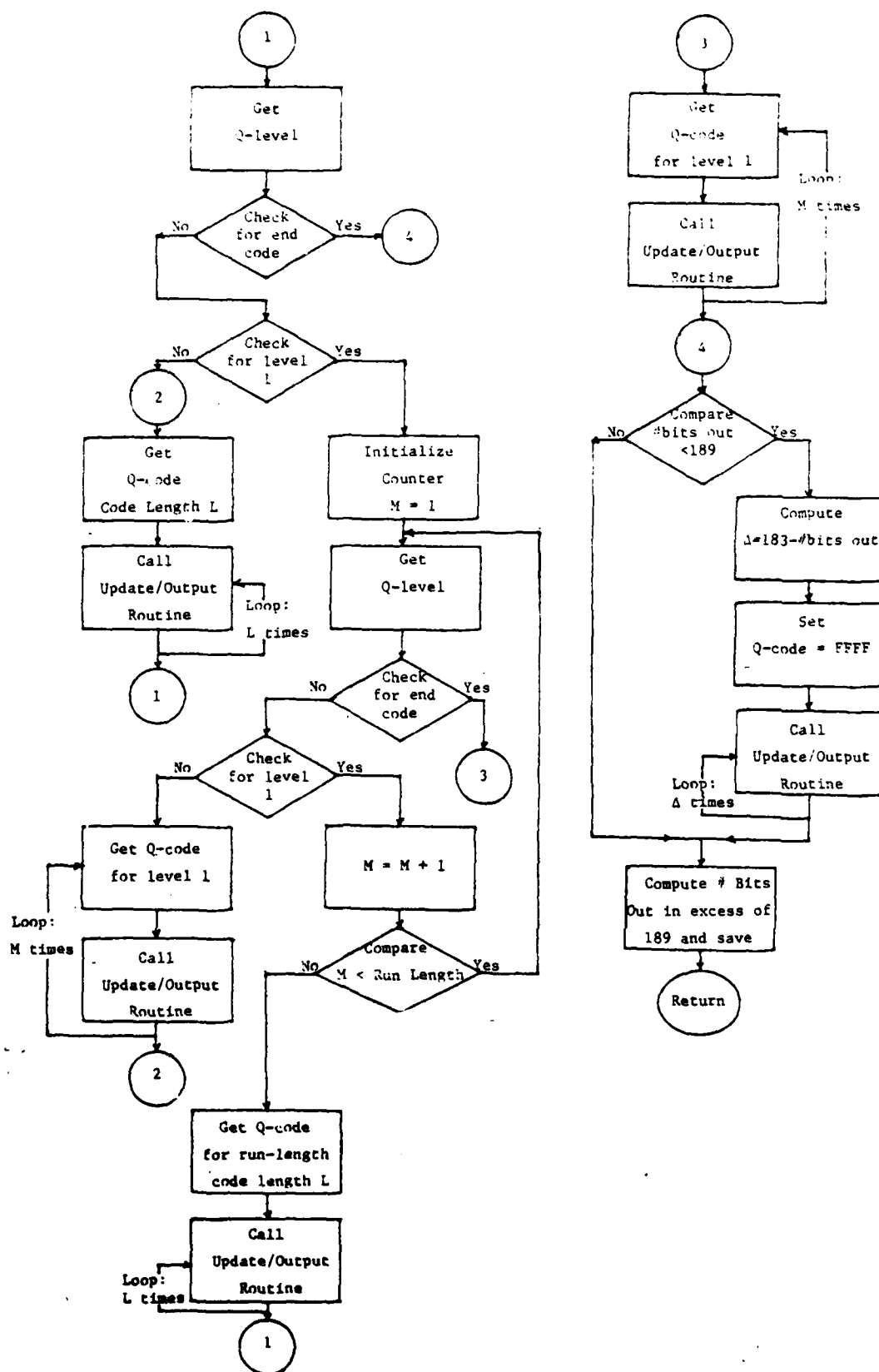
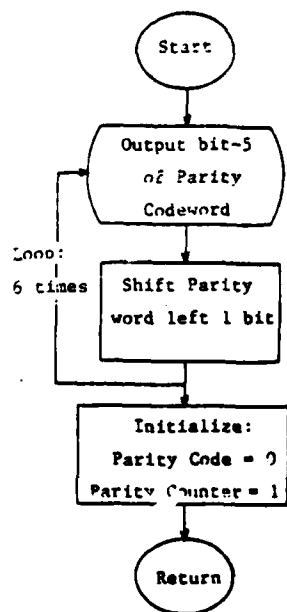


Fig. 12.14b Block Diagram for Encoder

A) Parity Output Routine



B) Update/Output Routine

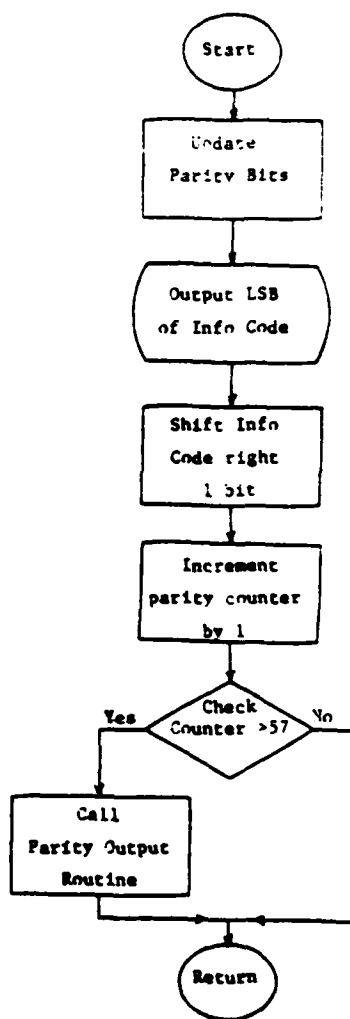


Fig. 12.14c Block Diagram for Encoder

Hamming block is full are passed to the appropriate field in the next Hamming block.

All the programs in each processor need to be able to process a block of information within a time frame of $19687.5 \mu \text{ sec}$ for the algorithm to keep in real time. This necessitated giving program efficiency priority over flexibility. The following is a list of the constraints on the encoder program as a result of this:

(i) All buffers used by the encoder must be located in Bus 1. They can be relocatable, as long as they do not occupy memory locations above 64K.

(ii) All the inputs to the encoder program must be in the fixed number format. The quantizer levels must be pre-multiplied by 2 to facilitate direct indexing. The values of β and T must be partially encoded. T must be limited to 64 values from 0 to 63, and β to 97 values from 0 to 96. Pitched repetition and the end of quantizer levels must be indicated by negative numbers.

(iii) The source code has the following constraints. The code for level 1 is 0. The locations for the run length code and the null code in the Q -level encoding table are 0 and 24, respectively. The other 11 codes for the quantizer levels Q are at locations $2Q$.

(iv) Because the LSB of a code-word is transmitted first, the code-word received at the decoder is inverted, e.g., 110 $\rightarrow$ 011. To compensate for this, the code-words stored in the Q -encoding table must be inverted and right justified.

(v) The Q -encoding table must contain $(L-1)$ for the various code lengths, L .

(vi) The code to indicate pitched repetition is 0000000. The 97

quantized values of β may not use any pattern with 2 or less 1's in it.

This is to give the pitched repetition indicator additional error protection.

(vii) The run length value can be selected at initialization.

(viii) Finally, the block of N_B quantizer levels should not generate more than 196 bits. Since the encoder does not monitor the maximum number of bits generated, the transmitter must ensure this limit.

12.5 Synchronizer, Decoder

This section describes the implementation of the decoder on the central processor of the MAP 300 called CSPU. The decoder essentially inverts at the receiver the operation performed by the encoder at the transmitter. From each received frame of 189 bits, it generates a block of N_B quantizer levels, the pitched repetition indicator, and the pitch extraction parameters for use by the PARC receiver. In addition, it performs several other operations. It monitors transmission errors, and corrects up to one error per Hamming block in the received frames. Because the received bit stream is arranged in frames, the decoder acquires the initial frame synchronization using the synchronization bit pattern transmitted by the encoder. Later, it monitors the received sync pattern to ascertain that synchronization is not lost. It monitors the state of the sample buffer in the PARC receiver to make sure the buffer does not overflow or underflow. Finally, it controls the mode of operation of the entire PARC algorithm.

The different operations outlined here are performed in different modules in the decoder. The decoder program is subdivided into three modules: the initialization module; the synchronization acquisition module; and the decoder module. The function to be performed and correspondingly the module to be used is determined by the three values of a function select switch, S1. The first time the program goes in for sync acquisition, several parameters and buffers need to be initialized. This mode is indicated by a value of 0 for S1. Subsequent sync acquisition operations are indicated by a value of -1 for S1. After frame sync has been established, the decoder can perform its task of inverting the bit stream to quantizer levels. This mode is indicated by a value of 1 for S1.

The decoder shares a double buffer with the PARC receiver at its output. A second function select switch, S2, indicates which half of the double buffer the decoder must use in the current time frame.

At its input, the decoder shares a circular buffer 1024 bits long with the IOS. The decoder expects to receive 189 bits in each time frame. However the clock that controls the inflow of the bit stream is at the other end of the communication system. It is different from the clock that measures the time frame at the decoder. On the average, the decoder does receive 189 bits per time frame. However, because of the different clocks, there could be temporary deviations. The large circular buffer which is several times the frame size allows for these deviations without causing a conflict between the decoder and the IOS over the bits being read out of and written into the buffer. The IOS, which receives the bit stream from the digital channel, has its base pointer which indicates the position of the base of the current frame to be entered into the buffer. When the PARC algorithm is initiated, the base pointer of the decoder which indicates the base of the frame of bits it should process in the current time frame is set several blocks behind the input pointer controlled by the IOS. Each processor updates its pointer independently at the end of the time frames. As long as the input and output rates match on the average, no conflict should occur and the two pointers should remain reasonably separated.

On being called, the decoder checks S1 and transfers control to the appropriate module. The module performs its function, and then it sets up the control and updates the relevant parameters and information for the operation in the next time frame. The program listing of the decoder is included in Appendix G. The following subsections describe in detail the operation of the three modules that make up the decoder.

12.5.1 Synchronization Acquisition Module

Before the decoder can start inverting the received bit stream, the boundaries of the frames, marked by the sync bit, must be located. This task is achieved by the synchronization module, over several time frames. The sync acquisition algorithm is described in Chapter 3. The implementation here varies slightly from the description in Chapter 3. This is to reduce the amount of computation and memory storage required and to make the program more time efficient. The block diagram of the sync acquisition module is shown in Fig. 12.15.

The encoder inserts an oscillating bit S_i in field A, Fig. 12.12, for synchronization. The decoder generates a similar pattern of expected sync bit values, $\hat{S}_i$. During sync acquisition, the correlation of $\hat{S}_i$ and each of the 189 bit positions starting from the base pointer is computed. A cumulative correlation tally from one time frame to the next for each of the bit positions is stored separately. Just in case the sync sequence being generated at the decoder is the inverse of the sync pattern being received from the transmitter, a cumulative tally of correlations with $\bar{\hat{S}}_i$ is also saved for each of the bit positions. The bit position corresponding to the maximum cumulative tally in each time frame is kept. When the correlation tally for a particular bit is maximum for ten consecutive frames, it is assumed the sync bit has been located. That position, marking the beginnings of frames generated by the encoder, is saved.

If at the end of a sync acquisition operation, it is determined that sync has not yet been acquired, the program sets up for one more sync operation in the next time frame. The base pointer in the circular buffer is updated by 189. The current value of $\hat{S}_i$ is inverted and saved. And the function select switch S2 is changed to indicate opposite buffer affiliations

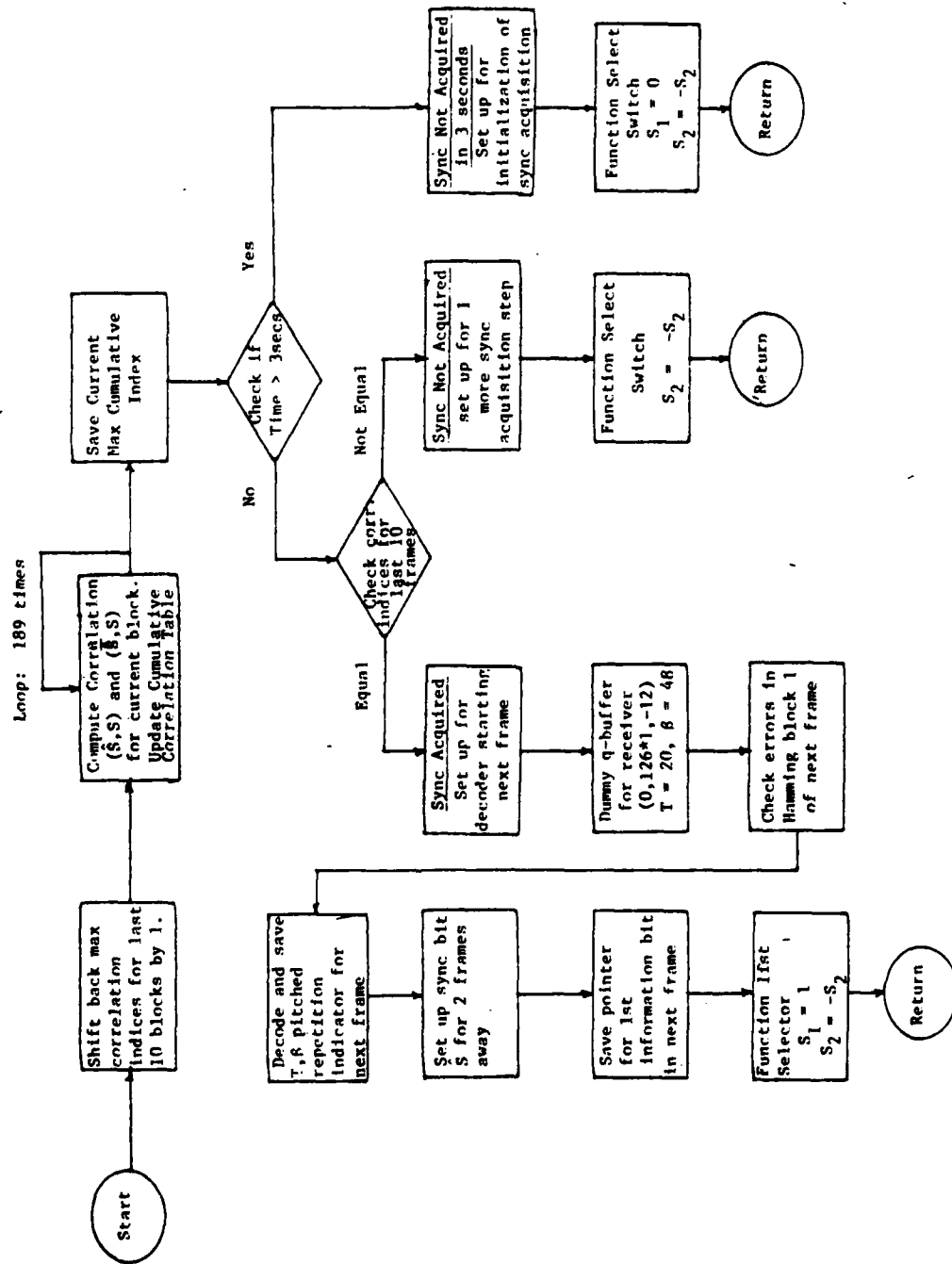


Fig. 12.15 Block Diagram for Sync Acquisition

for the next time frame.

If synchronization is achieved, preparations are made for subsequent decoder operations. In addition to the above controls and parameters, several others are updated. Function select switch S1 is changed to 1 to indicate a decoder operation in the next frame. Although no decoder operation has so far been performed, a dummy buffer consisting of 126 level 1's is prepared for use by the PARC receiver. Error check is conducted on the first Hamming block of the next bit frame; and up to one error is corrected. T, β and the pitched repetition indicator for the next frame are decoded and saved for output later. This leads to the location of the first bit in the field B1, Fig. 3.12, of the next frame. This is called the 1st information bit, information about quantizer levels. Its location is saved for use in the next frame. The cost function for sync monitor is initialized to -1. And the expected sync value $\hat{S}_{i+1}$ is set to match the next received sync value S_{i+1} . Finally, the state of the receiver sample buffer is initialized to a buffer-full condition. The control is then returned to the MAP executive.

12.5.2 Decoder Module

This module is the heart of the decoder. It corrects for transmission errors, if possible; monitors frame synchronization; inverts the received bit sequence to information usable by the PARC receiver; and performs buffer control on the receiver sample buffer. Its block diagram is shown in Fig.12.16.

After it decides its buffer affiliation by checking S2, it does error detection and correction on the 2nd and 3rd Hamming blocks of the current bit frame and the 1st Hamming block of the next bit frame. The reason for this offset between the bit frame and the error control frame is to make the extra bits generated during the encoding of the current frame available to the decoder when it performs the decoding. The extra bits reside at the

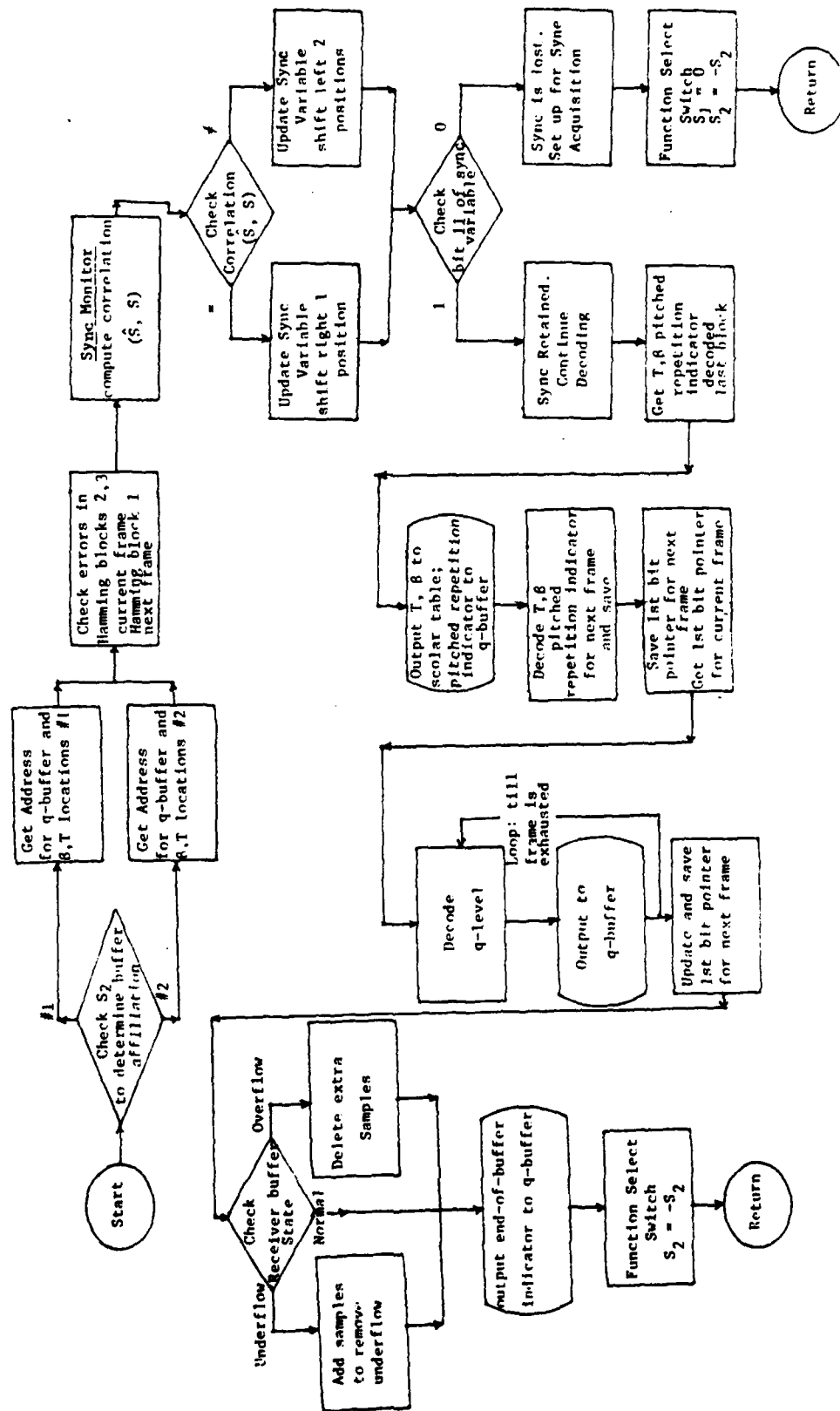


Fig. 12.16 Block Diagram for Decoder

beginning of field B1, Fig. 12.12 of the next frame.

The next step is sync monitor. The basis of the algorithm is explained in Chapter 3. The sync variable starts with an initial value of -1, FFFF in hexadecimal representation. The received sync bit S_i is compared with its expected value $\hat{S}_i$ using the logical operation EXOR. If equal, the bits in the sync variable v_i are shifted right one position. Bit 15, the sign bit is retained 1 in this operation. If not equal, the sync variable is shifted left two positions, causing 0's to be inserted in the least significant bits of v_i .

Bit 11 of v_i is monitored. If it is 0, sync is declared lost. The module sets the switch S1 to 0 to indicate a series of sync acquisition operations starting in the next time frame, and returns control to the MAP executive.

As long as bit 11 of v_i is 1, sync is declared preserved, and the module continues to its next phase of operation, source decoding. The pitch reduction parameters β and T which were decoded and saved in the previous time frame are output to their appropriate locations in the scaler table. The pitched repetition indicator, also decoded in the previous time frame, is transferred to the output buffer. If affirmative, the receiver buffer pointer is updated by the length of the repetition block.

After this, the pitch reduction parameters and the pitched repetition indicator for the next time frame are decoded and saved. This leads to the position of the 1st information bit in the next frame. If there were any extra bits in the current frame, the decoder will know where to look for them when it needs them.

The source decoding is a tree searching operation along the coding tree. Each successive bit received represents a node in the tree. Starting from the root of the tree, bits are read in, until the last bit received represents the termination of the tree. The corresponding quantizer level(s) are determined

from the decoding table and transferred to the output buffer. This process continues until either a null code is received or all the bits in the current frame are exhausted. At the end of the the decoding operation, the location of the 1st information bit for the next frame is saved.

The decoder can correct transmission errors to a point, after which errors filter through to the received bit stream. Errors have two effects on the decoding procedure. The quantizer levels generated are wrong. And the number of quantizer levels N_B in the current block can be different from what it should have been. This causes the state of the sample buffers in the transmitter and receiver to lose correspondence. To correct for this, the decoder provides a steady drift in the state of the receiver buffer. When N_B for a received block is 126, it indicates that the transmitter was processing silence when it generated this block and its sample buffer was empty. Correspondingly, the receiver buffer should be full. A few extra level 1's are added to the q-buffer generated for the receiver; so that if errors have caused the receiver to move away from its buffer-full condition, it should slowly drift back. This alleviates the mismatch between the buffer states at the receiver and the transmitter.

Finally, the state of the receiver sample buffer is checked. If it underflows, extra level 1's are added to remedy it's negative state. If it overflows, the extra samples are deleted.

After this, the module updates various controls and parameters for another decoder operation in the next time frame. It then returns control to the MAP executive.

12.5.3 Initialization Module

The initialization module precedes the first of a sequence of sync

acquisition operations. Sync acquisition requires two buffers initialized for its proper operation. This is done by the initialization module. The locations which contain the bit positions with max correlation tallies from the last ten frames are initialized to -1. The buffer where the correlation tallies are stored is initialized to 0. The switch S1 is set to -1 to indicate subsequent sync acquisition operations.

In addition, the length of the pitched repetition block is retrieved from the function control block and saved for later use in the decoder. It also gets the base address of the input buffer. It then transfers control to the sync acquisition module.

12.5.4 Decoder Constraints

As with the other modules in the PARC algorithm, the stress in developing the decoder program is execution efficiency rather than flexibility. This is to try and meet the rather tight limitations of real time operation. The following constraints are imposed on the decoder:

(i) All buffers used by the decoder must reside on Bus 1. They can be relocatable, as long as they do not occupy memory locations above 64K.

(ii) The input for this program is a circular buffer of length 1024. The information bit must be contained in the LSB of each word.

(iii) All the outputs of the decoder are in the fixed point number format. The β and T are partially encoded and are represented by 7 and 6 bits respectively. β is allowed one of 97 codewords, 0 to 96, and T one of 64, 0 to 63. Pitched repetition and end-of-quantizer-levels are indicated by negative numbers.

(iv) The run length value can be selected at initialization.

12.6 Program Timing and Speed

The programs in the real time implementation of PARC get executed in parallel on the different processors of the MAP 300. The set of programs on a given processor must be executed once in each time frame. The number of samples processed by these programs is not constant. It varies from about 50 during the voiced regions of speech to about 520 during the transition regions following voiced speech. For the algorithm to operate at its peak performance, the programs should be able to process the maximum number of 520 samples within a time frame. This is, however, limited by processor speeds and program efficiency.

The average number of samples that need to be processed by any program is 126; and it is imperative that the programs be able to process at least a few extra samples if necessary. Currently, the programs do satisfy this minimum requirement. The pitched reduction program, PARC transmitter, and PARC receiver which operate on the AP can process about 150 samples per time frame. The encoder and decoder programs which operate on the CSPU can process about 200 samples per time frame. So currently, the limit on the number of samples processed is set at 150. This exceeds the minimum requirement only marginally, and speeding up the programs would improve the performance of the algorithm considerably. Some ways to achieve this improvement are suggested below, and it is expected that different programs will execute 20% to 50% faster as a result of these modifications.

The pitched reduction program which currently requires about 5 msec can be speeded up 100% by doubling the parallelism in its computation. The transmitter and receiver programs need to be reorganized in terms of their register usage and operation sequencing. This should provide approximately 30% speed

improvement. These changes should increase the number of samples processed on the AP by about 50%.

The encoder can be speeded up 25% by rearranging the encoding table and changing all memory access from indirect to direct addressing. This would require the input quantizer levels to be $2(q-1)$ instead of $2q$ as they are now. The decoder can be improved slightly by rearranging its decoding table and operation sequencing.

Two of the three buses on the MAP 300 have slower MOS memories. Changing these to the fast bipolar memory would also help the speed on the various processors because of the large number of memory transfers performed in each time frame. With these modifications, it is expected the algorithm would be able to process 250-300 samples per time frame instead of the 150 it does now. Although this still allows the algorithm to operate well below its peak level of fidelity, this is about the level of performance that can be expected given the current speed of the MAP 300 array processor.

APPENDIX E

RESAMPLING PROGRAM

During the course of this project, because of the different sampling rates at which digitized speech was available from various sources and the different rates at which it was utilized, it was found necessary to develop an efficient resampling program to enable us to easily change sampling rates of speech. The following briefly describes the resampling algorithm and the operational details of the program. Fig. E.1 shows the flow chart, and program listings are included at the end of this appendix.

Sampled speech is the pulse amplitude representation of an analog speech signal at a sequence of time points separated by T_1 . At another sampling rate, it is the PAM representation of the same signal at a different set of points separated by T_2 . The new set can be obtained by interpolation from the first set of samples. So as also to limit the bandwidth of signals, interpolation was performed by discrete convolution of the original samples with the truncated impulse response of an ideal low pass filter. A first order Hamming window was used for truncation to reduce the effects of truncation. The impulse response and the Hamming window have the following form:

$$H_F(t-\tau) = 2F \operatorname{sinc}(2F \pi \tau) \quad -\infty < \tau < \infty$$

and

$$W_T(t-\tau) = \alpha + (1-\alpha) \cos(\pi \tau/2T) \quad -T < \tau < T$$

$$\alpha = 0.7$$

The convolution function is the product of these two. The discrete version of the convolution function is scaled down by T_1 , to compensate for the scaling introduced by discrete filtering.

$$C_1(nT_2 - (m-1)T_1) = \frac{2F}{T_1} \{ \alpha + (1-\alpha) \cos [((mT_1 - nT_2) + iT_1)/NT_r] \}$$

$$\{ \operatorname{sinc}[2F\pi((mT_1 - nT_2) + iT_1)] \}, \quad \frac{-NT_r}{T_1} < i < \frac{NT_r}{T_1}$$

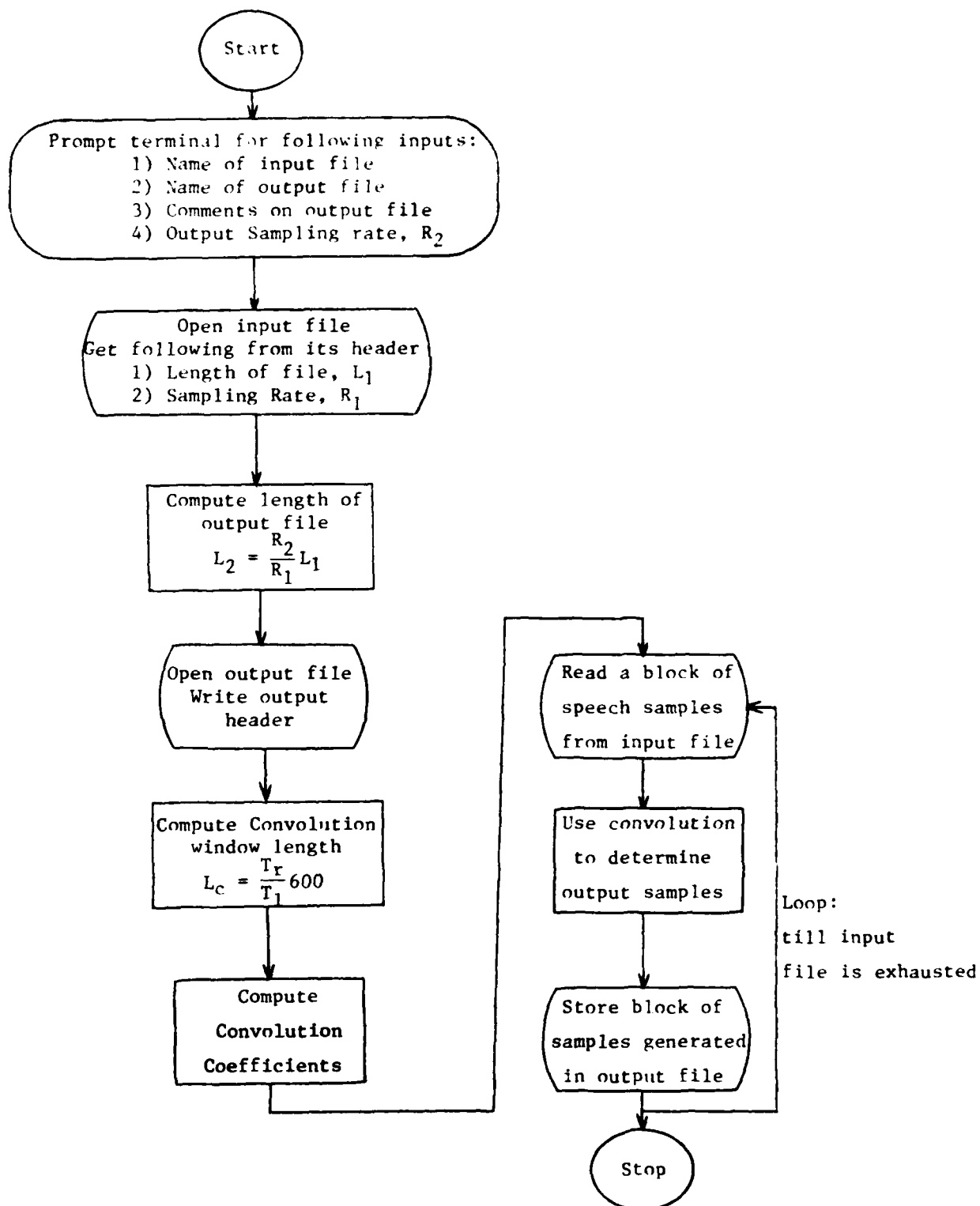


Fig. E.1 Flow Chart for the Resample Program

Here nT_2 identifies the n th output sample and mT_1 the closest preceding input sample.

Because the phase $(mT_1 - nT_2)$ changes arbitrarily, the correlation coefficients need to be computed for each output sample. However, if the two sampling rates are integer submultiples of a higher frequency $1/T_r$ called the reference frequency, the C_i need to be evaluated only once at the reference frequency. The phase $(mT_1 - nT_2)$ is always a multiple of T_r , and a subset of these coefficients can be utilized to perform the convolution. This reduces the computation required in the program by about an order of magnitude. For the different rates required in this project, the frequency 96000 is an integer multiple and was selected as the reference frequency.

Two versions of the resampling program were developed. In the first, all computation, initialization as well as the convolution (which comprises the bulk of the computation in resampling) is done on the PDP 11/60. In the second, the convolution is performed on the MAP 300 array processor using the SNAP-II software package of array functions supplied by CSPI. The PDP 11 does the initialization and handles the I/O interfacing between the disk and the MAP 300. The second version is almost an order of magnitude faster than the first.

E.1 Operating Details

The program is segmented into four modules. The main program acquires all relevant parameters required for the resampling operation, either from the header record of the input speech file or from the terminal. This program prompts for each input from the terminal, and if requested, gives a brief description, shows an acceptable example, and specifies the bound on the value of the input. The second module performs the convolution for resampling. The other two modules assist in the initialization by computing the convolution coefficients. Between the two versions of the program only the second module is different. The appropriate module is selected during the process of task-building.

To obtain an executable task image, the appropriate modules must be compiled and task-built. The following describes this process for the RSX11M operating system on a PDP 11 computer. The compilation step for each module has the following form.

```
>FOR MODULE = MODULE/I4
```

The task-building step is slightly different for the two versions. The command format for the first version is:

```
>TKB
TKB> QRESAM/CP/FP = MOD1, MOD2, MOD3, MOD4
TKB> /
ENTER OPTIONS:
TKB> UNITS = 7
TKB> ACTFIL = 7
TKB> //
```

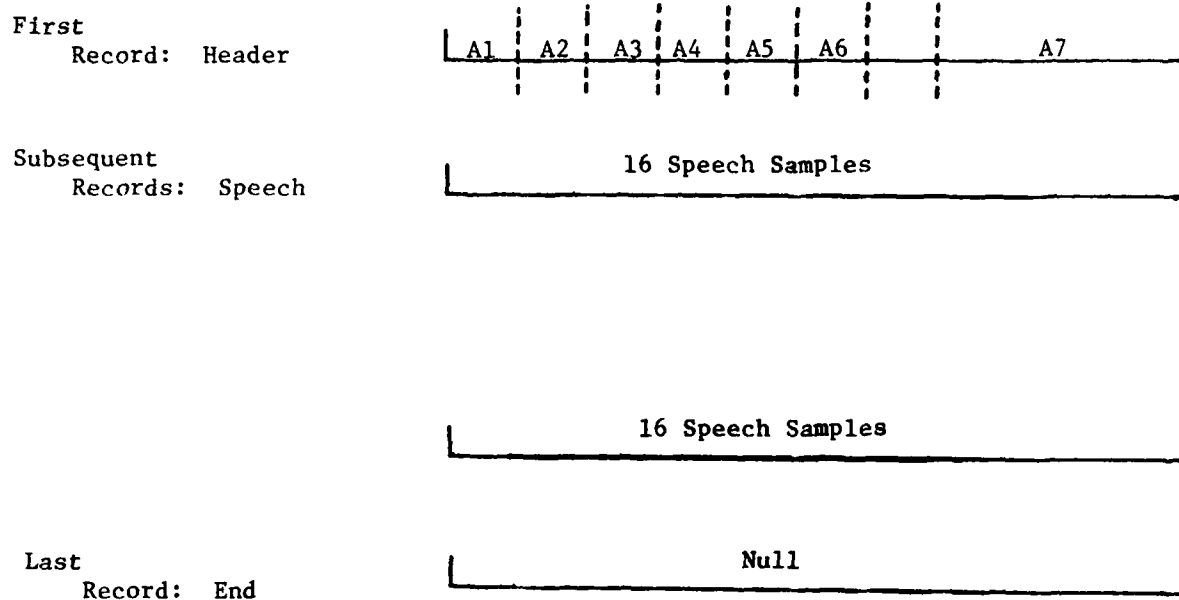
The underlined text is the prompt by the computer. The following text is the response by the user.

For the second version, the SNAP library must also be included in the task-building step.

```
>TKB
TKB> MRESAM/CP/MP = MOD1, MOD2, MOD3, MOD4, SNAPLIB/LB
TKB> /
ENTER OPTIONS:
TKB> UNITS = 10
TKB> ACTFIL = 10
TKB> //
```

The program requires the input speech file to conform to the Notre Dame speech file format. Fig. E.2 illustrates this format. The first record is the header. The seven fields in it are sentence identification number, sampling rate, number of samples in the files, lower and upper cutoff frequencies, truncation number for the convolution window, and comments identifying the speech file. The upper cutoff frequency is not used in this program. The truncation number which specifies the length of the convolution window is internally computed by the program based on the input sampling rate. Each of the subsequent records in the file contain 16 speech samples in the 15 format. The amplitude of speech samples is limited between -2048 and 2047. The speech file must end with a null record.

The output file generated by the resampling program also conforms to this format.



Format for each record of 80 columns

Header: (6I5, 10X, 2042)

Speech: (16I5)

Fig. E.2 Notre Dame Speech File Format

```

*****
*
*
*      MAINLINE INFO QRESAMPLE
*
*
*****

                ARVIND S ARORA

THIS PROGRAM SEEKS OUT THE INFORMATION NECESSARY TO
RUN THE QRESAMPLE SUBROUTINE. IT THEN OPENS THE INPUT AND OUTPUT
FILES,WRITES THE OUTPUT HEADER AND TRANSFERS CONTROL TO
QRESAMPLE. THE FOLLOWING INFORMATION IS SOUGHT:

1)NAM1      INPUT FILE NAME
2)NAM2      OUTPUT FILE NAME
3)IRATE1    INPUT SAMPLING RATE (FROM INPUT FILE HEADER)
4)IRATE2    OUTPUT SAMPLING RATE
5)NLEN1
5)NLEN1
5)NLEN2

LENGTH OF INPUT FILE (FROM INPUT FILE HEADER)
LENGTH OF OUTPUT FILE, ONLY IF PARTIAL
OUTPUT IS DESIRED
FILTER CORNER FREQ
(FILTER RESTRICTED TO INTEGER SUB-MULTIPLES OF 96000)
(IGNORE)
8)IF2      TRUNCATION NO. FOR FILTER
9)ITRUN    NO. OF TERMS IN FILTER=2*ITRUN+1
          (THIS IS DETERMINED BY THE PROGRAM DEPENDING ON IF1)
10)HEAD1   INPUT FILE HEADER COMMENTS (FROM INPUT FILE)
11)HEAD2   OUTPUT FILE HEADER COMMENTS

```

```

0001 INTEGER=2 NAM1(16),NAM2(16),HEAD1(20),HEAD2(20)
0002 LOGICAL=1 ANS,CHAR(3)
0003 COMMON /RESAM/NIEN1,NLEN2,IRATE2
0004 COMMON /COFF/IF1,IF2,ITRUM,IRATE1
0005 DATA CHAR/. . .N.V./
0006 TYPE '. . . SOLICITING INFORMATION FOR RESAMPLING.'
0007 TYPE '. . .
0008 TYPE '. . .
0009 TYPE 1009 IVANTO TO SEE EXAMPLES?
0010 ACCEPT 1003,ANS
0011 IFL=1
0012 IF(ANS.EQ.CHAR(3)) IFL=2
C ----- BEGIN QUERY
100 CONTINUE
C ----- NAME OF INPUT FILE
0014 IF(IFL.EQ.1) GO TO 110
0015 TYPE '. . . EXAMPLE OF FILE NAME *.
0016 TYPE '. . . DK:LSB.S01S11564.DAT.1'
0017 TYPE 1010 ENTER INPUT FILE NAME
0018 ACCEPT 1001,NAM1
0019 NAM1(16)=*

```

```

0020  C ----- OPEN INPUT FILE. IF ERROR IN OPENING, INDICATE ERROR
0021  C AND ASK AGAIN
0022  OPEN(UNIT=1, NAME=NAM1, TYPE='OLD', READONLY, SHARED, ERR=128)
0023  READ(1, 1000) ISEN, IRATE1, NLEN1, IF1, IF2, ITRUN, HEAD1
0024  ECHO INPUT FILE NAME AND INPUT HEADER
0025  TYPE 1004, NAM1
0026  TYPE 1005, ISEN, IRATE1, NLEN1, IF1, IF2, ITRUN, HEAD1
0027  GO TO 120
0028  CONTINUE
0029  TYPE '...' ERROR -- FAILED TO OPEN SPECIFIED FILE'
0030  TYPE '...' POSSIBLE REASONS: FILE DOES NOT EXIST'
0031  TYPE '...' DEVICE NOT AVAILABLE'
0032  GO TO 110
0033  CONTINUE
0034  OUTPUT FILE PARAMETERS
0035  TYPE '...' RESAMPLING PARAMETERS'
0036  OUTPUT SAMPLING RATE
0037  IF (IFL.EQ.1) GO TO 140
0038  TYPE '...' EXAMPLE OF OUTPUT SAMPLING RATE ...'
0039  TYPE '...' THE USUAL RATES FOR SPEECH ARE 6000<RATE<16000'
0040  TYPE '...' FOR EXAMPLE 6400'
0041  CONTINUE
0042  TYPE 1011  IOUTPUT SAMPLING RATE
0043  ACCEPT 'IRATE2'
0044  TYPE 'IRATE2'
0045  CHECK IF RATE IS LEGAL
0046  IF (IRATE2.GT.0.AND.96000/IRATE2=IRATE2.EQ.96000) GO TO 150
0047  TYPE '...' ERROR -- CAN'T HAVE RATE<0'
0048  TYPE '...' OR SUBMULTIPLE OF 96000'
0049  GO TO 140
0050  CONTINUE
0051  CORNER FREQUENCIES
0052  IF (IFL.EQ.1) GO TO 160
0053  TYPE '...' EXAMPLE OF FILTER CORNER FREQUENCIES F1 ...'
0054  TYPE '...' THE USUAL RANGE IS RATE/2>F1>0'
0055  TYPE '...' FOR EXAMPLE 3000'
0056  CONTINUE
0057  TYPE 1012  ICORNER FREQ
0058  ACCEPT 'IF1'
0059  TYPE 'IF1'
0060  CHECK IF FREQS. ARE LEGAL
0061  IF (IF1.GT.0) GO TO 170  ILLEGAL
0062  TYPE '...' ERROR -- ILLEGAL FREQUENCY'
0063  TYPE '...' F1>0'
0064  GO TO 160
0065  CONTINUE
0066  TRUNCATION NUMBER
0067  ITRUN=6000/IRATE1/96000
0068  TYPE 'ITRUN'
0069  DETERMINE LENGTH OF OUTPUT FILE
0070  NLEN2=FLOAT(NLEN1)*FLOAT(IRATE2)/FLOAT(IRATE1)
0071  NBLK=NLEN2/100*1
0072  TYPE '...' THE ESTIMATED LENGTH OF THE OUTPUT FILE IS'
0073  TYPE '...', NLEN2, ' SAMPLES, OR ', NBLK, ' BLOCKS ON DISK'
0074  TYPE 1013  IASK IF PARTIAL OUTPUT WANTED

```

```

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GRESAMINF.FTN /14/TR:BLOCKS/WR

2006 ACCEPT 1003,ANS
2007 IF(ANS.NE.CHAR(3)) GO TO 2008 ICOMPLETE OUTPUT
2008 TYPE 1014 I DESIRED LENGTH OF FILE
2009 ACCEPT ' ',NLEN2
2010 TYPE ' ',NLEN2
2011 CONTINUE
2012 C -----
2013 OUTPUT FILE NAME
2014 TYPE 1019 IPROMPT FOR OUTPUT FILE NAME
2015 ACCEPT 1001,NAM2
2016 TYPE 1004,NAM2
2017 NAM2(16)=#
2018 C -----
2019 HEADER COMMENTS
2020 TYPE ' ',# ENTER HEADER COMMENTS, 40 CHARACTERS OR LESS'
2021 IF(IFL.EQ.1) GO TO 210
2022 TYPE 1015, HEAD1
2023 CONTINUE
2024 C -----
2025 IHEADER COMMENTS PROMPT
2026 TYPE 1016 IHEADER COMMENTS PROMPT
2027 ACCEPT 1001,HEAD2
2028 TYPE ' ',# THE HEADER CARD FOR THE OUTPUT FILE IS:'
2029 TYPE 1005,ISEN,IRATE2,NLEN2,IF1,IF2,ITRUN,HEAD2
2030 ONE OPPORTUNITY TO CHANGE ENTRIES
2031 C -----
2032 TYPE 1017 IVANNA CHANGE SOMETHING
2033 ACCEPT 1003,ANS
2034 IF(ANS.EQ.CHAR(3)) GO TO 1008 I DO WANT TO CHANGE
2035 OPEN(UNIT=2,NAME=NAM2,TYPE='NEW',CARRIAGECONTROL='LIST',ERR=220)
2036 WRITE(2,1000) ISEN,IRATE2,NLEN2,IF1,IF2,ITRUN,HEAD2
2037 TYPE ' ',# BEGINNING RESAMPLING. WILL INFORM YOU ' ,
2038 I'ON COMPLETION'
2039 CALL RESAMP(1,2)
2040 STOP
2041 220 CONTINUE
2042 TYPE ' ',# ERROR -- FAILED TO OPEN OUTPUT FILE'
2043 TYPE ' ', LOCATE PROBLEM AND TRY AGAIN'
2044 STOP
2045 1000 FORMAT(615,10X,20A2)
2046 1001 FORMAT(20A2)
2047 1002 FORMAT(615)
2048 1003 FORMAT(A1)
2049 1004 FORMAT(1X,20A2)
2050 1005 FORMAT(1X,615,10X,20A2)
2051 1006 FORMAT('S' DO YOU WISH TO SEE EXAMPLES OF RESPONSES? (Y,N):')
2052 1007 FORMAT('S' ENTER INPUT FILE NAME. NAME=')
2053 1008 FORMAT('S' ENTER RESAMPLING RATE. RATE=')
2054 1009 FORMAT('S' ENTER CORNER FREQ F1=')
2055 1010 FORMAT('S' WOULD YOU LIKE A PARTIAL OUTPUT? (Y,N):')
2056 1011 FORMAT('S' ENTER LENGTH DESIRED. LENGTH=')
2057 1012 FORMAT('S' EXAMPLE: ',20A2)
2058 1013 FORMAT('S' COMMENTS: ')
2059 1014 FORMAT('S' DO YOU WISH TO CHANGE ENTRIES? (Y,N):')
2060 1015 FORMAT('S' ENTER TRUNCATION NUMBER. ITRUN=')
2061 1016 FORMAT('S' ENTER OUTPUT FILE NAME. NAME=')
2062 1017
2063 1018
2064 1019
2065 1101
2066 1102
2067 1103
2068 1104
2069 1105
2070 1106
2071 1107
2072 1108
2073 1109
2074 1110
2075 1111
2076 1112
2077 1113

```

```

C *****
C "
C " SUBROUTINE RESAMP(NIN,NOUT) "
C "
C *****
C
C ARVIND S ARORA
C
C PROGRAM DESCRIPTION:
C
C THIS PROGRAM RESAMPLES A GIVEN FILE AT ONE SAMPLING
C RATE TO THAT AT ANOTHER SAMPLING RATE. BECAUSE THE COEFFS
C REQUIRED FOR THE FILTERING OPERATION DURING RESAMPLING ARE
C COMPUTED ONLY ONCE AT 96000 SAMPLES/SEC. THE INPUT AND
C OUTPUT FREQUENCIES ARE RESTRICTED TO INTEGER SUB-MULTIPLES
C OF 96000, E.G. 16000, 12000, 9600, 6400. HOWEVER THIS MAKES
C THIS PROGRAM OPERATE AN ORDER OF MAGNITUDE FASTER THAN THE
C GENERAL VERSION OF RESAMP. ALL COMPUTATIONS IN THIS PROGRAM
C ARE DONE IN THE PDP-11 CPU.
C
C THE PROGRAM REQUIRES THE FOLLOWING INFORMATION BEFORE IT
C CAN RESAMPLE A GIVEN FILE:
C 1) NIN LUN FOR INPUT FILE
C 2) NOUT LUN FOR OUTPUT FILE
C 3) NLEN1 LENGTH OF INPUT FILE
C 4) NLEN2 LENGTH OF OUTPUT FILE
C 5) IRATE1 SAMPLING RATE OF INPUT FILE
C 6) IRATE2 SAMPLING RATE OF OUTPUT FILE
C 7) IF1 CORNER FREQ OF FILTER
C 8) IF2 (IGNORED)
C 9) ITRUN (IGNORED)
C
C IN ADDITION THE INPUT AND OUTPUT FILES MUST BE OPEN
C FOR ACCESS.
C
C DATA FORMATS:
C
C BOTH THE INPUT & OUTPUT SAMPLES MUST HAVE VALUES V IN THE
C RANGE -2048 TO 2047 (12 BIT RESOLUTION). THEY MUST BE STORED
C USING A (1615) FORMAT.
C
C SIGNIFICANT VARIABLES:
C
C 1) A1 INPUT FILE BUFFER (INTEGER*2)
C 2) A2 OUTPUT FILE BUFFER (INTEGER*2)
C 3) H FILTER COEFFS (REAL)
C SYMMETRIC, CENTRE COEFF IN H(1),
C COEFFS ONLY FOR +VE TIME

```

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 QRESAMP.FTN /I4/TR:BLOCKS/VR

C CALLS TO SUBROUTINES:

1)SUBROUTINE ERRSET(24,...,FALSE...)
 2)FUNCTION-SUBROUTINE SECNDS(TIME)
 3)SUBROUTINE COEFF(H??)

```

9991 SUBROUTINE RESAMP(NIN,NOUT)
9992   INTEGER*2 A1(32),A2(16)
9993   DIMENSION H(64)
9994   COMMON /RESAMP/NLEN1,NLEN2,IRATE2
9995   COMMON /COFF/IF1,IF2,ITRUN,IRATE1
9996   CONTINUE
9997   NLEN2=NLEN2-1
9998   IF(96888/IRATE1=IRATE1.NE.96888) GO TO 118
9999   IF(96888/IRATE2=IRATE2.NE.96888) GO TO 118
1000   GO TO 128
1001   C ----- INDICATE ILLEGAL FREQUENCIES AND STOP
1002   118 CONTINUE
1003   CLOSE(UNIT=NIN,DISPOSE='SAVE')
1004   CLOSE(UNIT=NOUT,DISPOSE='DELETE')
1005   TYPE '*** ERROR QUICK RESAMPLE.'
1006   TYPE '...'
1007   TYPE '...THIS SUBROUTINE HANDLES ONLY A LIMITED SET OF FREQS.'
1008   TYPE '...INPUT AND OUTPUT FREQS MUST BE SUBMULTIPLES OF 96888'
1009   TYPE '...AND YOUR FREQS ARE, IN FREQ=,IRATE1, OUT FREQ=,IRATE2'
1010   STOP
1011   128 CONTINUE
1012   CALL ERRSET(24,...,FALSE...)
1013   C ----- INITIALIZE CLOCK TO COMPUTE TIME REQUIRED FOR RESAMPLING
1014   CLCK=SECNDS(8.8)
1015   288 CONTINUE
1016   C ----- INITIALIZE ALL VARIABLES AND THE INPUT BUFFER
1017   INTV1=96888/IRATE1
1018   INTV2=96888/IRATE2
1019   NBUF1=328
1020   NBUF2=168
1021   IHOLD=ITRUN
1022   ITRUN=688/INTV1
1023   NFLG1=ITRUN+1
1024   NFLG2=NBUF1-ITRUN
1025   IBUF1=NFLG1+MOD((NBUF1-NFLG1+1),16)
1026   DO 218 IAI=1,IBUF1-1
1027     A1(IAI)=8
1028   218 CONTINUE
1029   READ(NIN,1888)(A1(IAI),IAI=IBUF1,NBUF1)
1030   C ----- INITIALIZE INDICES
1031   IA1=8
1032   IA2=8
1033   IBUF2=1
1034   C ----- CAL SUBROUTINE TO COMPUTE COEFFICIENTS
1035   CALL COEFF(H)
1036   INTVN=INTV1+1

```

```

TRA--PL--B2-16--44--5-A--AGE
RESAMP.FIN /14/TR:BLOCKS/WR

C----- BEGIN CONVOLUTION LOOP FOR FILTERING
22# CONTINUE
C----- COMPUTE PHASE AND INITIALIZE INDICES FOR CONVOLUTION
IPHASE=IA2-INTV2-IA1*INTV1
IIN=IBUF1-1
IIP=IBUF1+1
IHN=INTVN+IPHASE
IHP=INTVN-IPHASE
C----- PERFORM CONVOLUTION
SUM=H(1+IPHASE)*A1(IBUF1)
DO 25# I1=IHN,601,INTV1
SUM=SUM+H(I1)*A1(IIN)+H(IHP)*A1(IIP)
IIN=IIN-1
IIP=IIP+1
IHP=IHP+INTV1
25# CONTINUE
ITEMP=SUM
IF(ITEMP.GE.2048) ITEM=2047
IF(ITEMP.LT.-2048) ITEM=-2048
A2(IBUF2)=ITEMP
C----- CONVOLUTION COMPLETED
C
C----- INCREMENT VARIOUS INDICES
IA2=IA2+1
IBUF2=IBUF2+1
C----- FIND CORRESPONDING INDICES IN THE INPUT FILE
INEXT=INTV2-IA2/INTV1
IBUF1=IBUF1+INEXT-IA1
IA1=INEXT
C----- CHECK IF OUTPUT FILE IS COMPLETE
IF(IA2.LE.NLEN2) GO TO 30# IIF NOT COMPLETE, PROCEED
IF FILE COMPLETE, WRITE OUTPUT BUFFER, CLOSE FILES & QUIT
WRITE(NOUT,1000) (A2(J),J=1,IBUF2-1)
NLEN2=NLEN2+1
ITRUN=I HOLD
C----- FIGURE OUT TIME TAKEN, SAY OPERATION COMPLETE & QUIT
CLICK=SECONDS(CLCK)
TYPE '...', TIME FOR RESAMPLING = '.CLCK.' SECONDS'
TYPE '...'
TYPE '...', RESAMPLING OPERATION COMPLETE.'
RETURN
C----- CHECK IF OUTPUT BUFFER IS FULL
30# CONTINUE
IF(IBUF2.LE.NBUF2) GO TO 31# IIF NOT FULL, PROCEED
IF FULL, WRITE OUT OUTPUT BUFFER & INITIALIZE FLAG IBUF2
WRITE(NOUT,1000) A2
IBUF2=1
C----- CHECK IF RUN OUT OF INPUT BUFFER
31# CONTINUE
IF(IBUF1.LE.NFLG2) GO TO 35# IIF NOT RUN OUT, PROCEED
IF RUN OUT, REPLENISH BUFFER BY MOVING OLD DATA OVER
IFLNXT=NFLG1+MOD((IBUF1-NFLG1),16)
ISHFT=IBUF1-IFLNXT
IBUF1=IFLNXT
DO 32# J=ISHFT+1,NBUF1

```



```

C SIGNIFICANT VARIABLES:
C
C      1) A1      INPUT FILE BUFFER (INTEGER*2)
C      2) A2      OUTPUT FILE BUFFER (INTEGER*2)
C      3) M        FILTER COEFFS (REAL)
C              SYMMETRIC. CENTRE COEFF IN M(1),
C              COEFFS ONLY FOR +VE TIME
C
C CALLS TO SUBROUTINES:
C
C      1)SUBROUTINE ERRSET(24,...,FALSE..)
C      2)FUNCTION-SUBROUTINE SECNDS(TIME)
C      3)SUBROUTINE COEFF(M?7)
C      4)SUBROUTINES IN SNAP LIBRARY
C.....
C
C      SUBROUTINE RESAMP(NIN,MOUT)
C      INTEGER*2 A1(648),A2(648)
C      INTEGER SPZB47,SNZB48,SFLAG
C      DIMENSION M(681)
C      COMMON /RESAM/NLEN1,NLEN2,IRATE2
C      COMMON /COFF/IF1,IF2,IITRUM,IRATE1
C      CONTINUE
C 100----- NAMES OF VARIOUS BUFFERS IN MAP AND HOST
C      NMW1=1      I INPUT BUFFER IN HOST: A1
C      NMR2=2      I OUTPUT BUFFER IN HOST: A2
C      NBR1=2B     I
C      NBR2=21
C      MB12=22
C      MBR3=23
C      MGR4=24
C      MRR5=25
C      MRB6=26
C      MB13=27
C      MZERO=29
C      MOR1=11
C      MO11=12
C      MOR2=13
C      MOT2=14
C      MCB=36
C      MC1=31
C      MC2=32
C 2----- NAMES OF VARIOUS SCALARS IN MAP
C      SPZB47=5B
C      SNZB48=51
C      SFLAG=52
C      IF(96888/IRATE1*IRATE1.NE.96888) GO TO 11B
C      IF(96888/IRATE2*IRATE2.NE.96888) GO TO 11B
C      IF(IRATE1.GT.32888.OR.IRATE1.LT.6488) GO TO 11B
C      IF(IRATE2.GT.32888.OR.IRATE2.LT.6488) GO TO 11B
C      GO TO 12B
C
C      0001
C      0002
C      0003
C      0004
C      0005
C      0006
C      0007
C
C      0008
C      0009
C      0010
C      0011
C      0012
C      0013
C      0014
C      0015
C      0016
C      0017
C      0018
C      0019
C      0020
C      0021
C      0022
C      0023
C      0024
C      0025
C      0026
C      0027
C      0028
C      0029
C      0030
C      0031
C      0032
C      0033

```

```

C ----- INDICATE ILLEGAL FREQUENCIES AND STOP
110 CONTINUE
CLOSE(UNIT=NIN,DISPOSE='SAVE')
CLOSE(UNIT=NOUT,DISPOSE='DELETE')
TYPE '*** ERROR QUICK RESAMPLE.'
TYPE '...'
TYPE '...' THIS SUBROUTINE HANDLES ONLY A LIMITED SET OF FREQS.
TYPE '...' INPUT AND OUTPUT FREQS MUST BE SUBMULTIPLES OF 96000.
TYPE '...' AND MUST LIE BETWEEN 6400 AND 32000.
TYPE '...' AND YOUR FREQS ARE, IN FREQ=,IRATE1, OUT FREQ=,IRATE2
STOP
120 CONTINUE
CALL ERASET(24,.....FALSE,.)
INITIALIZE CLOCK TO COMPUTE TIME REQUIRED FOR RESAMPLING
CLK=SECONDS(0.0)
C ----- CALL SUBROUTINE TO COMPUTE COEFFICIENTS
C ----- CALL SUBROUTINE TO COMPUTE COEFFICIENTS
200 C ----- CCNVOOLUTION LOOP STARTING #200
CONTINUE
INTV1=96000/IRATE1
INTV2=96000/IRATE2
NPACK1=1920/INTV1
NPACK2=1920/INTV2
C ----- OPEN MAP
C ----- CALL REPORT(10,MPOPN(0))
C ----- CONFIGURE INPUT AND CCNVOOLUTION BUFFERS
CALL REPORT(20,MPCLB(MB1,0,3120,0,1,0))
CALL REPORT(30,MPCLB(MB2,5040,0,0,0,0,0,INTV1,0))
CALL REPORT(40,MPCLB(MB12,5040,0,0,0,0,0,INTV1,0))
CALL REPORT(50,MPCLB(MB13,1200,0,0,0,0,0,INTV1,0))
CALL REPORT(55,MPCLB(MB13,1200,0,0,0,0,0,INTV1,0))
SIZE=000/INTV1-1
CALL REPORT(60,MPCLB(MB4,1200,0,0,0,0,0,INTV1,0))
CALL REPORT(70,MPEOB(MB5,MBR2))
CALL REPORT(80,MPCLB(MB6,5040,0,0,0,0,0,INTV1,0))
C ----- CONFIGURE OUTPUT BUFFERS
CALL REPORT(90,MPCLB(29,9000,0,0,0,0,0,INTV1,0))
CALL REPORT(100,MPEOB(MB1,29))
CALL REPORT(110,MPCLB(29,11000,0,0,0,0,0,INTV1,0))
CALL REPORT(120,MPEOB(MB2,29))
CALL REPORT(130,MPCLB(29,9000,0,0,0,0,0,INTV1,0))
CALL REPORT(140,MPEOB(MB1,29))
CALL REPORT(150,MPCLB(29,11000,0,0,0,0,0,INTV1,0))
CALL REPORT(160,MPEOB(MB2,29))
C ----- CONFIGURE COEFF BUFFERS
CALL REPORT(170,MPCLB(MC0,0,1200,0,0,1,0))
CALL REPORT(180,MPCLB(MC1,1200,0,0,1,0))
CALL REPORT(190,MPCLB(MC2,1200,0,0,1,0))
C ----- CONFIGURE MOST RESIDENT BUFFERS
CALL REPORT(200,MPODN(MB1,1,1),A1(NPACK1))
CALL REPORT(202,MPODN(MB2,A2(1),A2(NPACK2))
INITIALIZE INPUT BUFFER AREA TO ZERO
CALL REPORT(205,MPCLB(29,0,4500,0,1,0))
CALL REPORT(206,MPCLB(MZERO,0,4500,0))
CALL REPORT(207,VSM1(28,0,MZERO,0))
C ----- WRITE IN THE SCALARS

```

```

0070 CALL REPORT(211,MPVST(SP2B47,2B47,.1,1))
0080 CALL REPORT(212,MPVST(SN2B48,-2B48,.1,1))
0090 CALL REPORT(213,MPVST(SFLAG,1B,.1,1))
0100 C ----- COPY COEFFS INTO COEFF BUFFER
0110 CALL REPORT(220,MPVDB(MC1,H(1),4,1,H(51)))
0120 CALL REPORT(230,MPVDB(MC2,H(1),4,1,H(51)))

```

C ---- MAP FUNCTION LISTS

```

C ----- FUNCTION LIST 1 (USES OUTPUT BUFFER 1)
0004 CALL REPORT(245,MPBFL(1))
0005 CALL REPORT(255,VFLT(MBR2,39,MB12,5))
0006 CALL REPORT(265,DCVH(MOR1,INTV2,MBR1,MCB))
0007 CALL REPORT(275,VSMAL(MBR4,1,MBR6,5))
0008 CALL REPORT(285,VSMAL(MBR3,1,MBR5,5))
0009 CALL REPORT(295,VCLIP(MOR1,SP247,MOR1,SN2548))
0010 CALL REPORT(305,VFIX(MO11,38,MOR1,11))
0011 CALL REPORT(315,MPBFO(MB12,NHR1,2,1))
0012 CALL REPORT(325,MPBFI(MO11,NHR2,2,1))
0013 CALL REPORT(335,MPEFL(1))

```

C ----- FUNCTION LIST 2 (USES OUTPUT BUFFER 2)

```

00094 CALL REPORT(348,MP8FL(2))
00096 CALL REPORT(358,VFLTY(MBR2,39,MB12,8))
00098 CALL REPORT(368,DCVM(MOR2,INTV2,MBR1,MC8))
00099 CALL REPORT(378,VSMAL(MBR4,1,MBR6,8))
00099 CALL REPORT(388,VSMAL(MBR3,1,MBR5,8))
00099 CALL REPORT(398,VFLX(MOR2,SP2847,MOR2,SN2848))
0100 CALL REPORT(408,VFLX(MO12,38,MOR2,11))
0101 CALL REPORT(418,MP8FO(MB12,NHR1,2,1))
0102 CALL REPORT(428,MP8FI(MO12,NHR2,2,1))
0103 CALL REPORT(438,MPEFL(2))

```

C ----- FUNCTION LIST 3 (MASTER FUNCTION LIST)

```

0104 CALL REPORT(45,MPBFL(3))
0105 CALL REPORT(45B,MPXFL(1))
0106 CALL REPORT(45B,MPXFL(2))
0107 CALL REPORT(47B,MPEFL(3))
      C ----- END OF FUNCTION LISTS IN MAP

```

C ----- PREPARING FOR LOOP IN HOST

100

C ---- INITIALIZE VARIOUS POSITION FLAGS, INITIALIZE INPUT BUFFER

READIN IN ENVIRONMENTALLY SAFE MARCH 11
BUFFER IN MAP, TURN OVER OUTPUT BUFFER TO MAP

```
READ(NIN,1000)(A(I),I=1,NPACK)
CALL REPORT(500,NPACK,M013-A(1),2,1,A(NPACK))
```

CALL REPORT(SUB,VFLT(MBR3.39.MB13.0))
CALL REPORT(SUB,VFLT(MBR3.39.MB13.0))

3

```
READ(NIN,1000000)(A1(JA1),JA1=1,NPACK1)
CALL REPORT(520,MPVDB(MB12,A1(1),2,1,A1(NPACK1)))
```

CALL REPORT(538,MPFBA(NHR2))

3

OUT-8

CALL REPORT 1008 1008
----- 3

----- NO. 1 STOP
CONTINUED

C - - - - INPUT TO MAP

```

0117 C CALL REPORT(555,MPVBA(NHR1))
0118 READ(MIN,1000,ERR=455)(A1(A1),IA1=1,NPACK1)
0119 GO TO 555
C -----
0120 455 RUN OUT OF INPUT, FILL IN WITH ZEROS
CONTINUE
0121 DO 465 JAI=IA1,NPACK1
0122 A1(JAI)=0
0123 CONTINUE
C -----
0124 465 IF NOT RUN OUT, CARRY ON WITH SAMPLES READ IN
CONTINUE
0125 CALL REPORT(565,MPFBA(NHR1))
OUTPUT FROM MAP
C -----
0126 CALL REPORT(575,MPVBA(NHR2))
0127 IOUT=IOUT+NPACK2
0128 IF(IOUT.GE.NLEN2) GO TO 555
0129 WRITE(ROUT,1000)(A2(IA2),IA2=1,NPACK2)
0130 CALL REPORT(595,MPFBA(NHR2))
0131 GO TO 455
C ----- END OF HOST LOOP
C -----
C ----- IF YOU GOT ALL OUTPUT SAMPLES, STOP MAP LOOP AND RETURN
C -----
0132 555 CONTINUE
C -----
0133 ILST2=NPACK2+NLEN2-IOUT
0134 WRITE(ROUT,1000)(A2(IA2),IA2=1,ILST2)
C -----
0135 FIGURE OUT TIME TAKEN, SAY OPERATION COMPLETE & QUIT
CLCK=SECONDS(CLCK)
TYPE '...'
TYPE '...' TIME FOR RESAMPLING =',CLCK,' SECONDS'
TYPE '...'
TYPE '...' RESAMPLING OPERATION COMPLETE.'
C -----
0136 CLOSE MAP
CALL REPORT(615,MPCLS(B))
RETURN
C -----
C ----- AND THEN THERE'S THE FORMAT STATEMENTS
0142 1000 FORMAT(16I5)
0143 END

```

PORTMAN IV-PLUS V82-S1 16:17:53 15-APR-88
 MAPRESAM1.FTH /14/TR:BLOCKS/VR

PAGE 8

```

C ----- SUBROUTINE TO REPORT MAP ERRORS
C
0001 SUBROUTINE REPORT(I,J)
0002 INTEGER*2 I,J
0003 IF(J.EQ.0) RETURN
0004 TYPE *, 'MAP ERROR', J, ' AT', I
0005 STOP
0006 END

```


PAGE 2

15-APR-88

16:10:34

FORTRAN IV-PLUS V02-51
GCOEFF.PTN /14/TR:BLOCKS/WR0014 RETURN
0015 END

APPENDIX F CVSD ALGORITHM

In this appendix, the CVSD algorithm will be discussed. Before the design of this real-time CVSD system can be presented, it is essential to understand the structure of CVSD systems.

F.1 The CVSD System

In this section, the structure of a CVSD system is presented. The system described here is identical to that of [1]. A schematic of an encoder and decoder pair for CVSD is shown in Figure F.1.

A CVSD encoder is simply a delta modulator with an adaptive stepsize. In order to minimize the difference between adjacent samples, the input signal $s(k)$ is normally oversampled. Typically, the sampling rate is 16 k samples per second. Since one bit per sample is transmitted, the transmission rate is 16 K bits per second.

The encoder quantizes the difference $e(k)$ between an input speech sample and its estimate which is predicted by a first order predictor.

$$e(k) = s(k) - \alpha * \hat{s}(k-1)$$

where $\hat{s}(k-1)$ is the reconstructed speech of the input speech sample at time $k-1$. Then the encoder outputs a single bit, $b(k)$, for each corresponding input sample where

$$b(k) = \begin{cases} 1 & \text{if } e(k) \geq 0 \\ 0 & \text{if } e(k) < 0 \end{cases}$$

The adaptive stepsize logic derives its output $\Delta(k)$ from the bit stream $b(k)$ and an appropriate initial state,

$$\Delta(k) = \beta * \Delta(k-1) + g(k)$$

where

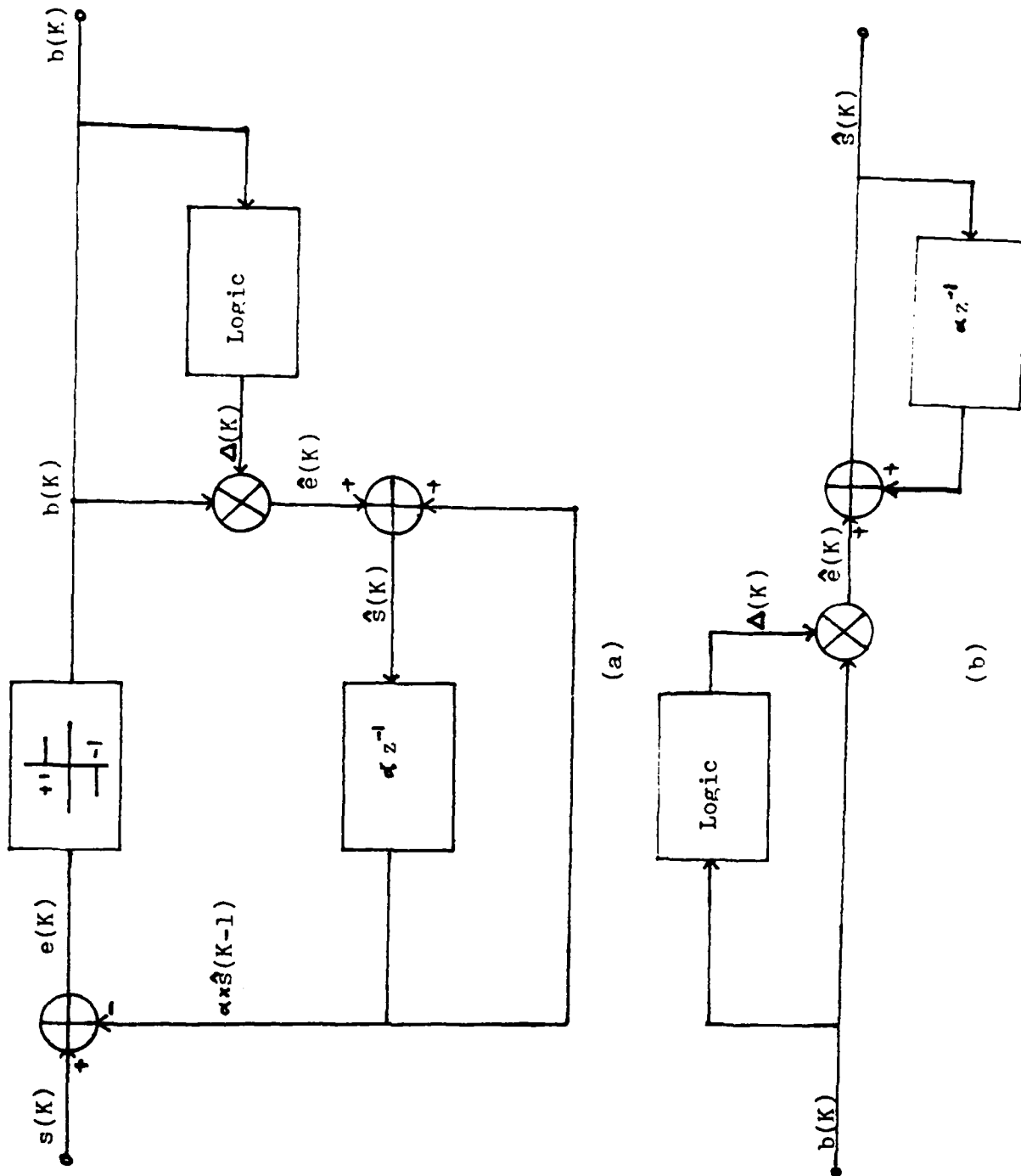


Fig. F.1 The CVSD System (a) Encoder (b) Decoder

$$g(k) = \begin{cases} \Delta_{\max} * (1 - \beta) & \text{If } b(k) = b(k-1) = b(k-2) \\ \Delta_{\min} * (1 - \beta) & \text{otherwise} \end{cases}$$

For a long run in which no three consecutive bits are identical, the stepsize approaches $\Delta_{\min}$. On the other hand, if the many consecutive bits are the same, the stepsize will approach $\Delta_{\max}$.

The estimate of the difference signal is given by

$$\hat{e}(k) = b(k) * \Delta(k)$$

Then the reconstructed speech is computed from

$$\hat{s}(k) = \alpha * \hat{s}(k-1) + \hat{e}(k)$$

Because the reconstructed speech in the transmitter is determined solely by the bit stream $b(k)$ and an agreed initial state, the receiver can produce the same reconstructed speech samples if no channel error occur.

Normally, there is no best criteria to judge the performance of a speech algorithm. However, the basic signal to noise ratio criteria is used here.

$$SNR = 10 * \log_{10} \frac{\sum_{k=1}^M s(k)^2}{\sum_{k=1}^M (s(k) - \hat{s}(k))^2}$$

F.2 The Real-Time CVSD System

In this section, the design of the real-time CVSD system is presented. The major design decisions and real-time algorithm are discussed. The program listings are followed.

F.2.1 Design Overview

In order to design a real-time speech system, several points have to be considered. First, the flexibility of changing system parameters such as

speech algorithm parameters, buffer sizes and buffer starting locations must be provided. This allows system performance to be studied without any further modification of the real-time program. However, this approach will increase overhead time. Therefore, a "pre-bound" concept will be introduced. Second, the arithmetic execution time has to be minimized. This can be done by efficiently utilizing the arithmetic processors. Therefore, the "hiding" technique which hides additions inside the period of multiplication will be employed. Third, in order to decrease overhead time, all processors have to be utilized as asynchronously and as simultaneously as possible. However, the necessary synchronization between the processors has to be considered.

The real-time CVSD implementation employs five MAP processors to do speech processing asynchronously and simultaneously. The whole algorithm is divided into two steps: An initialization step and a processing step. Each processor has its own role in each step.

1. The Initialization Step

In this step, the host computer will initialize the MAP-300 system, set up the appropriate command sequence, and initiate the real-time CVSD algorithm. Each processor in the MAP-300 has to do the following functions:

- A. The CSPU acts as the resource controller. Responding to a host command, it loads a data acquisition program into the ADAM, loads digital-to analog conversion program into the AOM, configures the buffers, loads an arithmetic function into the AP which will reset the contents of the buffers, builds a recurrent sequence of commands called a function list and prebinds the APS module of the CVSD program.

- B. The AP executes the arithmetic function which is loaded by the CSPU. The purpose of this execution is to reset the buffers.

2. The Processing Step

After initialization, the MAP-300 can execute its functions without any further commands from host computer. The role of each processor are described as follows:

- A. The CSPU acts as the resource controller. Responding to each interrupt, it updates the contents of the corresponding processor control block. Responding to the function list, it checks the availability of the appropriate buffer and initiates AP operation by loading the CVSD program from MAP memory. The synchronization is also done by CSPU which is described in the next section.
- B. The APU executes the real-time CVSD algorithm.
- C. The APS produces data addresses and acts as the controller of the real-time CVSD system.
- D. The ADAM samples the input speech signal from telephone module and stores them into MAP memory.
- E. AOM converts input digital samples into an analog signal and output it to telephone module.

In the next two subsections, the detailed description of these two steps will be presented.

F.2.2 The Initialization Step

The initialization step, which is controlled by host computer, includes reading system parameters, giving commands to the CSPU and building a function list. The algorithm is shown in Fig. F.2.

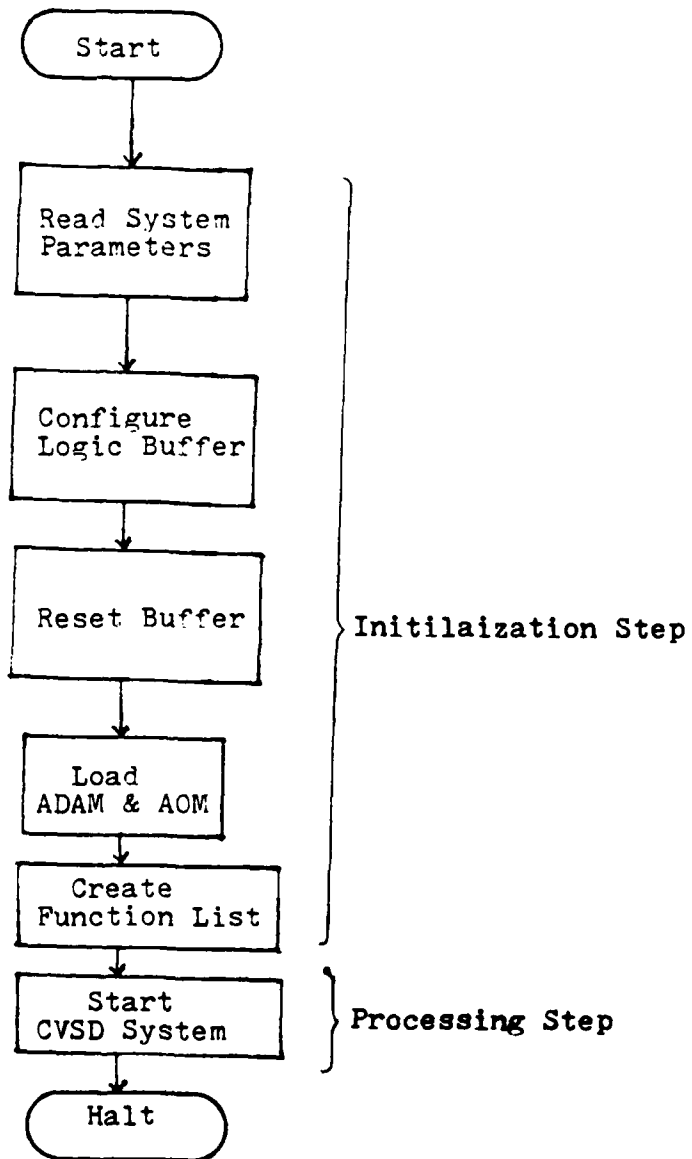


Fig. F.2 Algorithm for Initialization Step

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DESIGN AND IMPLEMENTATION OF A SPEECH CODING ALGORITHM AT 9600
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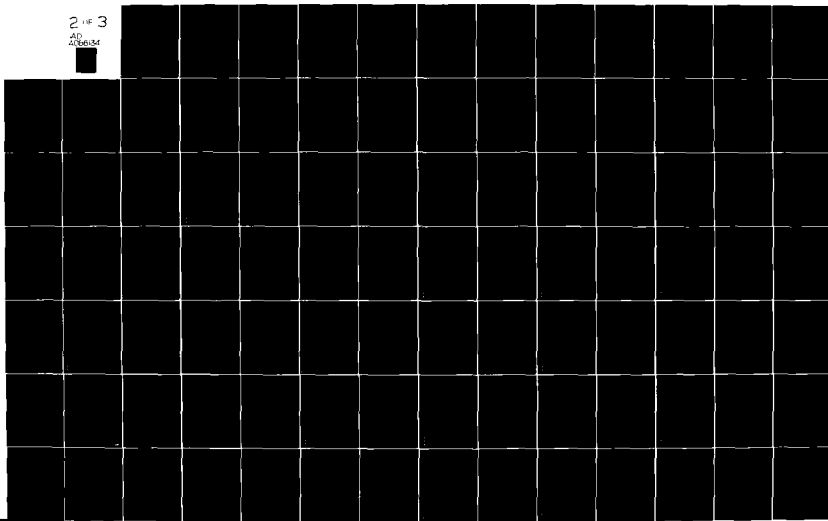
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There are two points worth to note as follows:

1. Because of parallel processing in the MAP-300, the synchronization between the AP and the AOM, and between the AP and the ADAM has to be considered. Memory is the common place which every processor has to access. Therefore, the synchronization is done by checking buffer availability as follows:

- A. If the first ADAM buffer is busy, CSPU goes to wait. Otherwise, goes to Step B.
- B. CSPU initiates AP. AP starts to read input samples from the first ADAM buffer, execute CVSD function and output results into the first AOM buffer.
- C. If the second ADAM buffer is busy, CSPU goes to wait, otherwise, goes to Step D.
- D. CSPU initiates AP. AP does the same function as Step B except it reads samples from the second ADAM buffer and outputs results to the second AOM buffer.
- E. Go to Step A.

This structure is included in a function list.

2. In order to increase the flexibility of changing system parameters, there are some substitutive attributes inside the APS module. In a normal operation, CSPU gets values for those attributes from a host command and then binds them with the APS module before loading it into the APS memory. In order to decrease this overhead time, a "pre-bound" has to be done prior to real-time execution. The prebinding process will create a new APS module from old APS module by permanently binding the attributes. At the execution time, all normal operations of binding and buffer protection will be bypassed. Thus, the overhead time is decreased.

F.2.3 The Processing Step

In the processing step, each of three processors has a program. Among them, the data acquisition and data output programs, which are included in the Simple Notation for Array Processing library (SNAP library), are fairly simple. The actual CVSD algorithm is executed by the AP processor.

The real-time CVSD program can be divided into two parts as follows:

1. APU module of CVSD algorithm which is shown in Fig. F.3 will do the whole arithmetic operation described in the Section F.1. The input and output data are directed by APS module. The "hiding" technique is employed to reduced execution time.
2. The APS module of the CVSD algorithm which is shown in Fig. F.4 will produce address sequences of input and output data for APU module. Also, APS module acts as the controller of the real-time CVSD system. This AP control protocol is shown in Fig. F.5 and described as follows:
 - * CPU starts APS-input by setting RI
 - * APS sets the program counter for write routine and starts APS-output by setting RO.
 - * APS starts APU by setting RA.
 - * After producing addresses for input data, APS-input turns itself off by clearing RI.
 - * When FI is cleared, APU leaves the loop.
 - * After producing addresses for output data, APS-output turns itself off by clearing RO.
 - * APU turns itself off by clearing RA.
 - * CSPU is interrupted by both RAI (RA off) and DNI (AP done).

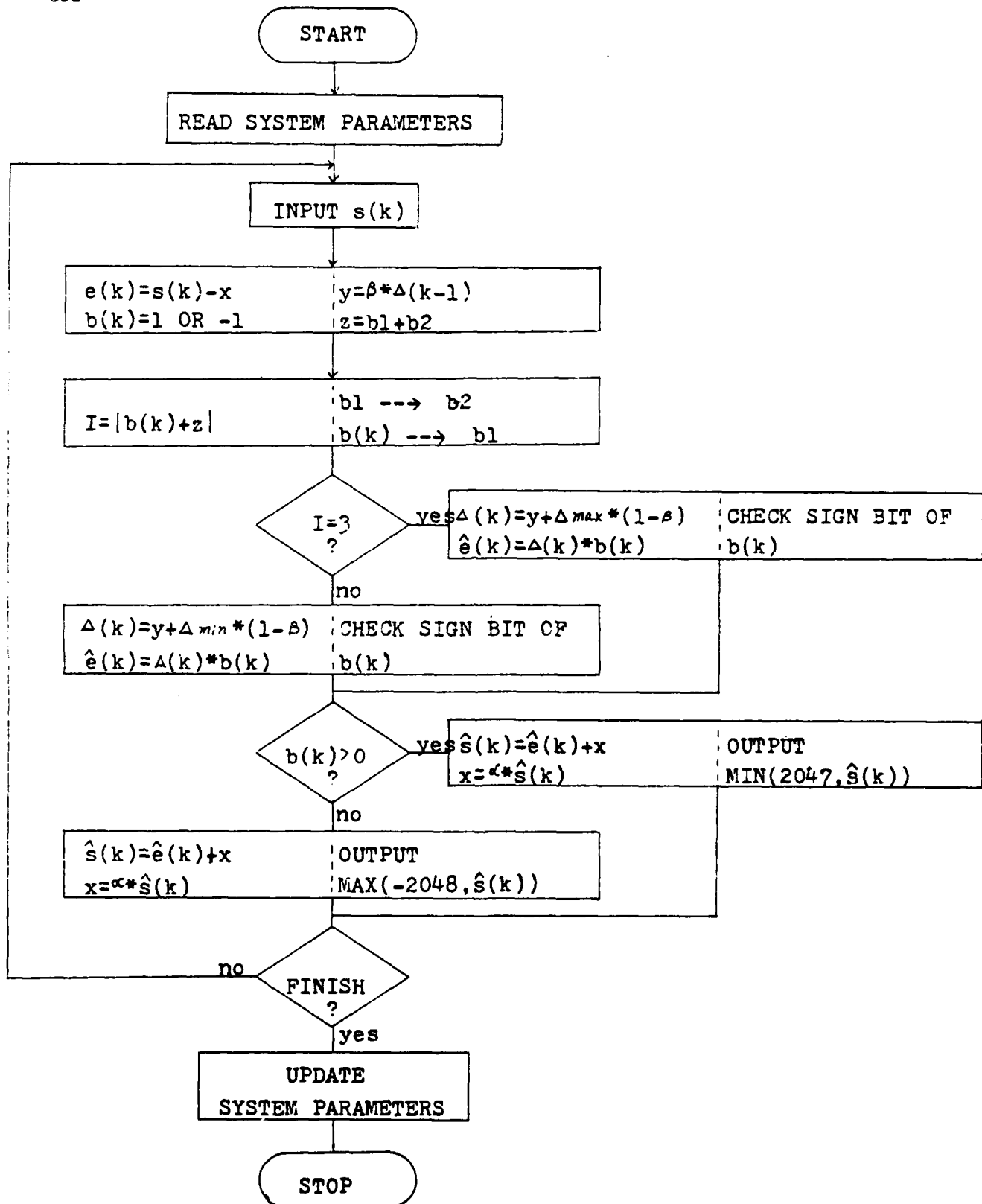
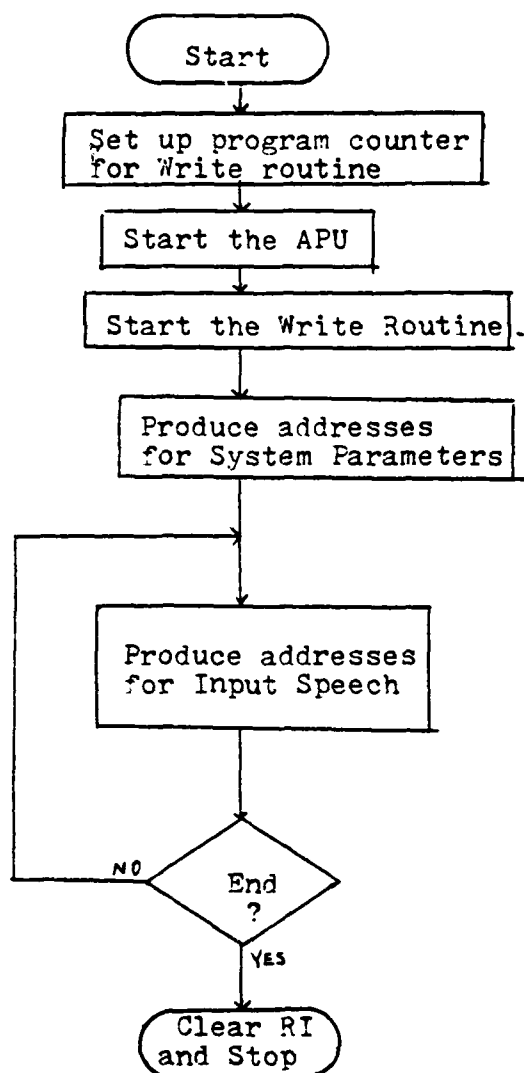
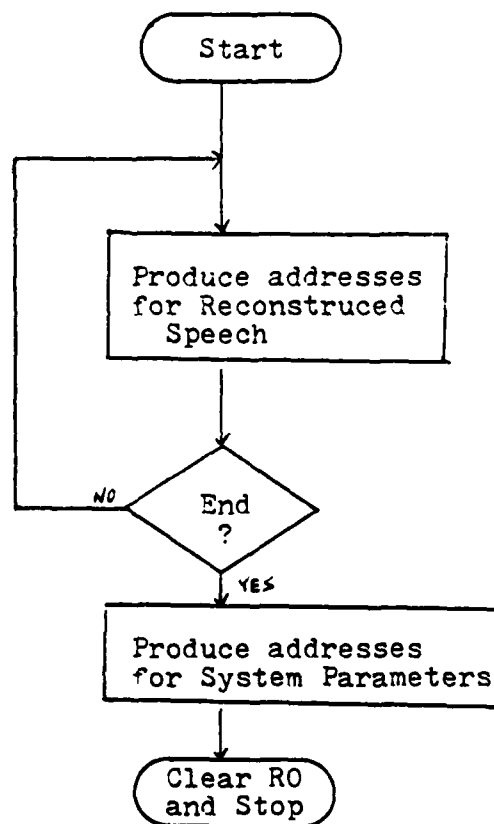


Fig. F.3 APU Flow Chart



(a)



(b)

Fig. F.4 APS Flow Chart

(a) APS-Input

(b) APS-Output

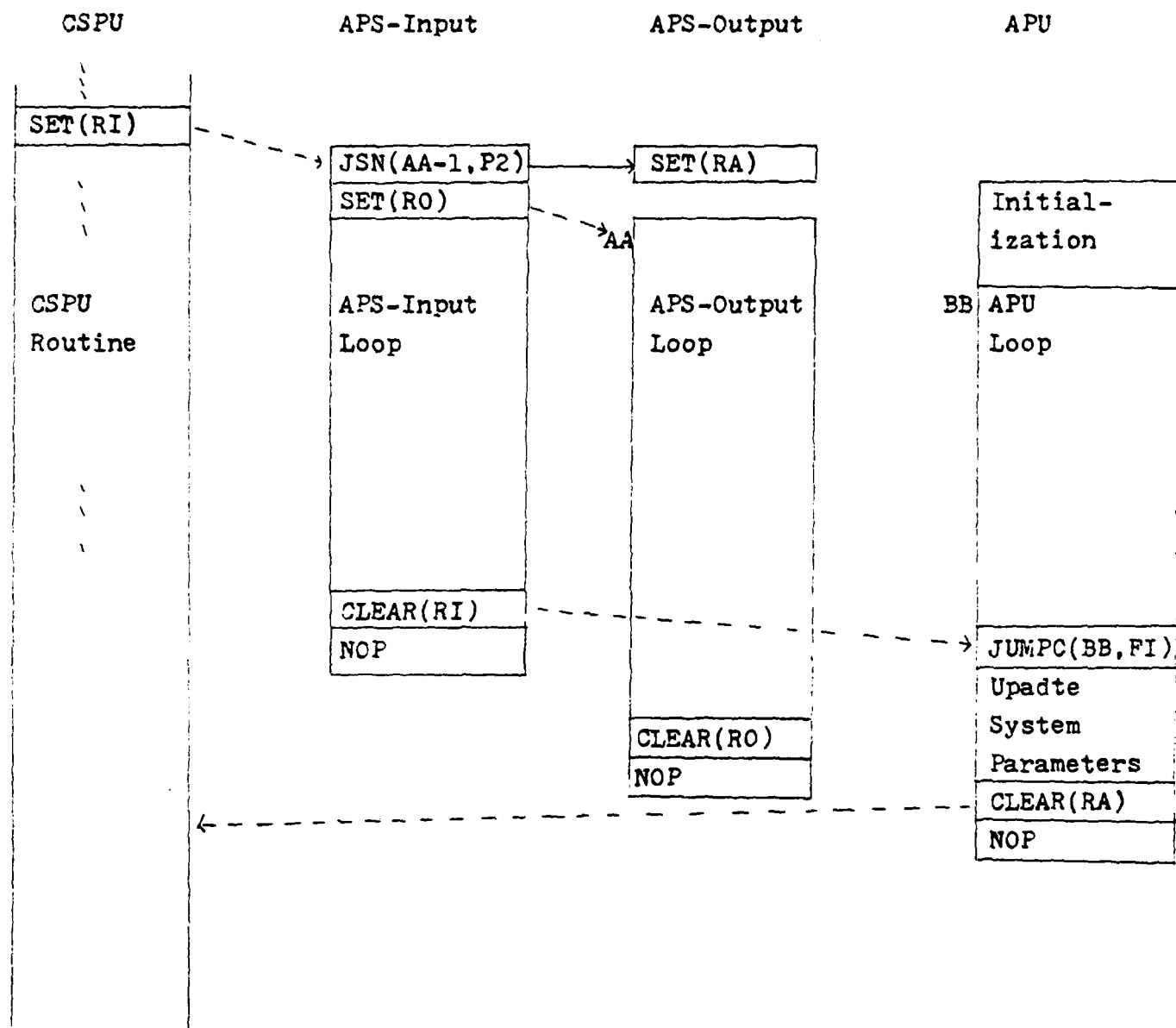


Fig. F.5 The AP Control Protocol

F.3 Conclusion

The execution time for the real-time CVSD algorithm is approximately 12 micro-seconds per sample. So, this implementation can be used with a sampling rate up to 83 KHz in the real-time mode. A set of parameters which gives a very good quality of speech is as follows:

$$\Delta_{\max} = 750$$

$$\Delta_{\min} = 25$$

$$\alpha = 0.94$$

$$\beta = 0.99$$

A two seconds sample speech is executed by this algorithm, and a 11.87 db signal-to-noise ratio performance is obtained.

F.4 Reference

- [1] R. W. Schafer et. al., "Tandem Interconnection of LPC and CVSD Digital Speech Coders" Final Report to Defense Communications Agency, DCA Contract No. DCA 100-76-C-0073, November, 1977.

```

PAGE 1: MAP MODULE OF C V S D PROGRAM --- VERSION 1 --- FEB. 19, 1988

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(00004) *
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MAP MODULE OF C V S D PROGRAM --- VERSION 1 --- FEB. 19, 1988
*****
* REAL-TIME CVSD TRANSMITTER *
*****

DATA: 2/19/88
MAVLIN YEH

PROGRAM NAME : CVSD.ND1

PROGRAM DESCRIPTION:

THIS MAP-FUNCTION SIMULATES AN ADAPTIVE DELTA-MODULATOR WHICH
USES A FIRST ORDER PREDICTOR WITH THE COEFFICIENT ALPHA AND
A FIRST ORDER ADAPTOR WITH THE COEFFICIENT BETA. THE VALUES OF
ALPHA AND BETA ARE TRANSFERRED FROM HOST PROGRAM TO MAP SCALAR
TABLE.

PROCEDURE OF FUNCTIONS:

1.READ IN SPEECH --- S(K)
2.CALCULATE THE PREDICTING ERROR --- E(K)=S(K)-P(K)
3.PASS E(K) THROUGH DELTA MODULATOR AND PRODUCE L(K)
4.GET THE LOGIC OUTPUT G(K)
5.CALCULATE ADAPTIVE STEP SIZE --- D(K)=BETA*D(K-1)+G(K)
6.CALCULATE RECONSTRUCTED PREDICTING ERROR --- EHAT(K)=L(K)*D(K)
7.CALCULATE RECONSTRUCTED SPEECH --- SHAT(K)=SHAT(K-1)+EHAT(K)
8.UPDATE PREDICTOR'S PARAMETER = ALPHA=SHAT(K)

THIS PROGRAM PROVIDES UPPER LIMIT AND LOWER LIMIT OF OUTPUT
DATA. THESE TWO LIMITS ARE TRANSFERRED FROM HOST PROGRAM.
THIS PROGRAM CONTAINS TWO SUB-PROGRAMS WHICH ARE CVSD FOR APU
AND V2260D FOR APS. PASSING THROUGH MAP-SIMULATOR, CVSD TAKES
2.669 MICROSECONDS. (LOOP TIME)

CALL TO THIS PROGRAM:

CALL CVSD(Y,A,U)
OR
MAP=CVSD(Y,A,U)

WHERE V=OUTPUT BUFFER FROM MAP

```

PAGE 1: MAP, MODULE OF C-M-S D-PROGRAM - VERSION 19.000000

```

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00000794
00000001
00000200
000021FC
000000E0
000000F5
000000A6
000040B2
000040B0
000021FC
000040B0

U=INPUT BUFFER TO MAP
A=STARTING LOCATION OF THE FOLLOWING PARAMETERS
1ST PARAMETER = UPPER LIMIT OF OUTPUT DATA
2ND PARAMETER = LOWER LIMIT OF OUTPUT DATA
3RD PARAMETER = LOWER LOGIC OUTPUT
4TH PARAMETER = HIGHER LOGIC OUTPUT
5TH PARAMETER = BETA
6TH PARAMETER = THRESHOLD FOR LOGIC
7TH PARAMETER = DELTA
8TH PARAMETER = ALPHA

CONTAINS FOR ASSEMBLY
MSS=0
DMYS=$794
BUS1S=$0001
TOESPRT=$200
CSPUSNOS=$21FC
AFDTS=$0E8

DISPATCH TABLE ENTRY
FCB=245
0L=AFDTS+3*2*(FCB-128)
ADDR CVSDS(R7,1)
ADDR V2260DS(R7,1)
ADDR CSPUSNOS(1,0)
APU & APS MODULES
0L=$4000
APU MODULE
FUNCTIONS:
**** ADM1 ****
READ SCALARS
CALCULATE E(K)
CALCULATE D(K)
CALCULATE EHAT(K) & SHAT(K)
UPDATE PREDICTOR'S PARAMETERS

DUMMY OUTPUT SPACE
BUS 1
TOP OF EXEC
LOCATION OF NO-CSPU SUPPORT
STARTING ADDRESS OF AFDT

FCB=245
STARTING LOCATION OF AFDT FOR 245
APU=CVSD
APS=V22600
NO CSPU

STARTING LOCATION OF CVSD AND V22600

**** ADM2 ****
READ SCALARS
LOGIC OPERATION
UPDATE LOGIC PARAMETERS
NO OPERATION
BOUND THE OUTPUT DATA

```



```

PAGE 41 MAP MODULE OF C.V.S.D PROGRAM VERSION 1.0000 19. FEB 1987

A19 04834 4300260 (00133)      ; DELTA=BETA*DELTA+G(K)  L(K)=1 OR -1
A1A 04836 0000000 (00134)      ;
      MOV(R,M0) \ NOP
A1B 04838 0420000 (00135)      ; EHAT=DELTA;L(K)
A1C 0483A 0090000 (00136)      ;
      MOV(R,EX0) \ NOP
A1D 0483C 0000000 (00137)      ;
      NOP \ MOV(EX1,M0)      RENEW M0=DELTA
A1E 0483E 901F000 (00138)      ; IF L(K)=1 GO TO LOOP4
      JUMPC(LOOP4,T2)
      *
A1F 04840 0000000 (00139)      L(K)--1 --- TEST IF OUTPUT DATA < LOWER LIMIT
      MOV(P,A1) \ NOP
      JUMPC(LOOP4,F1)
      *
A20 04842 0000000 (00140)      MOV(P,A5) \ NOP
A21 04844 0000000 (00141)      ADD(A5,A1) \ NOP
A22 04846 0000000 (00142)      MOV(R,EX0) \ NOP
A23 04848 0000000 (00143)      MOV(R,M6) \ MOV(EX1,A1)
A24 0484A 0000000 (00144)      MUL(M6,M3) \ MAX(A1,A7)
A25 0484C 0000000 (00145)      NOP \ MOV(R,QQ)
A26 0484E 0000000 (00146)      MOV(P,A1) \ NOP
A27 04850 0000000 (00147)      JUMPC(LOOP,F1)
      *
A28 04852 0000000 (00148)      L(K)=1 --- TEST IF OUTPUT DATA > UPPER LIMIT
A29 04854 0000000 (00149)      MOV(P,A5) \ NOP
A2A 04856 0000000 (00150)      ADD(A5,A1) \ NOP
A2B 04858 0000000 (00151)      MOV(R,EX0) \ NOP
A2C 0485A 0000000 (00152)      MOV(R,M6) \ MOV(EX1,A1)
A2D 0485C 0000000 (00153)      MUL(M6,M3) \ MIN(A1,A6)
A2E 0485E 0000000 (00154)      NOP \ MOV(R,QQ)
A2F 04860 0000000 (00155)      JUMPC(LOOP,F1)
      *
A30 04862 0220000 (00156)      R(A1) \ MUL(M0,M7)
A31 04864 0000000 (00157)      MOV(R,QQ) \ R(A4)
A32 04866 0000000 (00158)      NOP \ MOV(OQ),R(A3)
A33 04868 0000000 (00159)      NOP \ MOV(R,QQ)
A34 0486A 0000000 (00160)      CLEAR(RA)
A35 0486C 2032000 (00161)      NOP
A36 0486E 0000000 (00162)      JUMP(B)
A37 04870 0000000 (00163)      *
      *
A38 04872 0000000 (00164)      R(A1) \ MUL(M0,M7)
A39 04874 0000000 (00165)      MOV(R,QQ) \ R(A4)
A3A 04876 0000000 (00166)      NOP \ MOV(OQ),R(A3)
A3B 04878 0000000 (00167)      NOP \ MOV(R,QQ)
A3C 0487A 0000000 (00168)      CLEAR(RA)
A3D 0487C 2032000 (00169)      NOP
A3E 0487E 0000000 (00170)      JUMP(B)
A3F 04880 0000000 (00171)      *
      *
A40 04882 0000000 (00172)      R(A1) \ MUL(M0,M7)
A41 04884 0000000 (00173)      MOV(R,QQ) \ R(A4)
A42 04886 0000000 (00174)      NOP \ MOV(OQ),R(A3)
A43 04888 0000000 (00175)      NOP \ MOV(R,QQ)
A44 0488A 0000000 (00176)      CLEAR(RA)
A45 0488C 2032000 (00177)      NOP
A46 0488E 0000000 (00178)      JUMP(B)
A47 04890 0000000 (00179)      *
      *
A48 04892 0000000 (00180)      R(A1) \ MUL(M0,M7)
A49 04894 0000000 (00181)      MOV(R,QQ) \ R(A4)
A4A 04896 0000000 (00182)      NOP \ MOV(OQ),R(A3)
A4B 04898 0000000 (00183)      NOP \ MOV(R,QQ)
A4C 0489A 0000000 (00184)      CLEAR(RA)
A4D 0489C 2032000 (00185)      NOP
A4E 0489E 0000000 (00186)      JUMP(B)
A4F 048A0 0000000 (00187)      *
      *
A48 04872 4600260 (00173)      ; DELTA=BETA*DELTA+G(K)  L(K)=1 OR -1
A49 04874 0000000 (00174)      ;
      MOV(R,M0) \ NOP
A4A 04876 1000000 (00175)      ;
      JUMPC(LOOP2)
      *

```

PAGE 5: MAP MODULE OF C V S D PROGRAM --- VERSION 1 --- FEB. 19, 1988

84878 88888838 (88177)
(88178)
(88179)

CVSDSSZ=8A-CVSDSSA
END
EJECT

; COMPUTE THE SIZE OF THE MODULE

PAGE 51

MAP MODULE OF C.V.S.D. PROGRAM - VERSION 19.0000

APS3-V22600

```

(00180) *
(00181) *
(00182) *
(00183) *
(00184) *
(00185) *
(00186) *
(00187) *
(00188) *
(00189) *
(00190) *
(00191) *
(00192) *
(00193) *
(00194) *
(00195) *
(00196) *
(00197) *
(00198) *
(00199) *
(00200) *
(00201) *
(00202) *
(00203) *
(00204) *
(00205) *
(00206) *
(00207) *
(00208) *
(00209) *
(00210) *
(00211) *
(00212) *
(00213) *
(00214) *
(00215) *
(00216) *
(00217) *
(00218) *
(00219) *
(00220) *
(00221) *
(00222) *
(00223) *

```

```

04878 000048C2
0487A 000048B4
0487C 0001
0487D 004A
0487E 000048B2

```

```

A00 04880 00201540
A01 04882 02300030

```

```

A02 04884 04C20000
A03 04886 068A0002
A04 04888 088A0002
A05 0488A 0A8A0002
A06 0488C 0C8A0002
A07 0488E 0E8A0002
A08 04890 108A0002
A09 04892 128A0002
A0A 04894 148A0002
A0B 04896 168A0002
A0C 04898 188A0002

```

```

A0D 0489A 1A701000
A0E 0489C 1C500000
A0F 0489E 1E320000
A10 048A0 20BA9000
A11 048A2 22191001

```

THIS IS APS PROGRAM FOR CVSD.
IT EMPLOYES TWO INPUT-BUFFERS AND TWO OUTPUT-BUFFERS.
ALSO ONE CAN REPEAT THIS PROGRAM WITHOUT LOADING IT AGAIN.

```

EVEN      V2260DS1      ; START ON WORD BOUNDARY
ADDR      V2260DS+2*V2260DS ; PTR TO CONSTR INSTR BLOCK
DATA      1             ; STARTING ADDR. OF SCALAR
DATA      V2260DSZ      ; ONE SCALAR
ADDR      V2260DSA      ; SIZE
EVEN      ; CHAIN ANCHOR

V2260DS BEGIN APS(V2260D) ; BEGIN OF THIS MODULE

JSN(V2260DS-1,P2)        ; SET APS-OUTPUT PC P2
SET(RO)                  ; RUN APS-OUTPUT

SCALAR ADDRESSES
LOAD(BR0,MSS(1),L,TF)   ; UPPER LIMIT
ADD(BR0,2,TF)           ; LOWER LIMIT
ADD(BR0,2,TF)           ; LOWER LOGIC OUTPUT
ADD(BR0,2,TF)           ; HIGHER LOGIC OUTPUT
ADD(BR0,2,TF)           ; BETA
ADD(BR0,2,TF)           ; THRESHOLD
ADD(BR0,2,TF)           ; ALPHA
ADD(BR0,2,TF)           ; DELTA
ADD(BR0,2,TF)           ; L(K-1)
ADD(BR0,2,TF)           ; L(K-2)
ADD(BR0,2,TF)           ; ALPHA=SHAT(K-1)

1ST INPUT PROGRAM
LOAD(BR3,[1])           ; SET STARTING ADDR.
LOAD(BR1,MSS)           ; COUNTER--- SAMPLE SIZE - 1
SUB(BR3,MSS)             ; BASE ADDRESS - SPACING
ADD(BR3,[9],TF)         ; GIVE ADDR.
SUBL(BR1,1),JUMPP(V2260DS3) ; CHECK END ?

```

[illegible]

PAGE 8: MAP MODULE OF C.V.S. D. PROGRAM VERSION 1.19.1999

```

AFDTS: 000E8 (00064) (00069)
BUSIS: 00091 (00061) (00259)
CSPUSNOS: 021FC (00063) (00073)
CVSDS: 04002 (00071) (00094)
CVSDSSA: 00000 (00091) (00102) (00177)
CVSDSSZ: 00030 (00092) (00177)
DMYS: 00794 (00060)
FCB: 000F5 (00060) (00069)
LOOP: 0000C (00117) (00150) (00162)
LOOP1: 00030 (00131) (00173)
LOOP2: 00010 (00136) (00175)
LOOP3: 00030 (00151) (00164)
LOOP4: 00020 (00139) (00155)
MSS: 00000 (00059) (00205) (00220) (00221) (00232) (00233)
TOESPRT: 00200 (00257) (00259)
V22600S: 04000 (00062) (00250)
V22600S1: 00000 (00072) (00190) (00197) (00253)
V22600S3: 00010 (00222) (00223)
V22600S5: 00016 (00200) (00231)
V22600S6: 00019 (00234) (00235)
V22600SA: 04002 (00193) (00244)
V22600S1: 040C2 (00189) (00251)
V22600S5: 00002 (00190) (00205)
V22600S2: 0004A (00192) (00253)

```

LINES WITH ERRORS: 0 (MAP VERSION 000101.10) E- 0

/TR:BLOCKS/VR

UU

```

*****
*                                     *
*          CVSD HOST SUPPORT PROGRAM          *
*                                     *
*****

```

DATE: 11/14/79
MAVLIN YEH

CVSD HOST SUPPORT PROGRAM

CALL CVSD(Y,A,U)

OR

MAP=CVSD(Y,A,U)

WHERE: Y=OUTPUT BUFFER

A-STARTING LOCATION OF SCALARS

U-INPUT BUFFER

INTEGER FUNCTION CVSD(Y,A,U)

INTEGER Y, A, U, FCBGN

CVSD=FCBGN(245,Y,A,U,B,B,B,B,5)

RETURN

END

11111
22222
33333
44444
55555

FORTRAN IV-PLUS V02-11
CVSDHS TR-CKS/

PAGE 2

28:01:27 28-MAR-88

PROGRAM SECTIONS

NUMBER	NAME	SIZE	ATTRIBUTES
1	SCODE1	25	RV,I,CON,LCL
2	SPDATA	6	RV,D,CON,LCL
3	SIDATA	12	RV,D,CON,LCL

ENTRY POINTS

NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS
------	------	---------	------	------	---------	------	------	---------

CVSD	I*2	1-888888						
------	-----	----------	--	--	--	--	--	--

VARIABLES

NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS
A	I*2	F-888884	U	I*2	F-888886	Y	I*2	F-888882

FUNCTIONS AND SUBROUTINES REFERENCED

FCBGN

TOTAL SPACE ALLOCATED = 888126 43

NO FPP INSTRUCTIONS GENERATED

CVSDHS,CVSDHS/-SP-CVSDHS

+CVSDBN.FTN

/TR:BLOCKS/VR

```

*****
C      C V S D
C      IN REAL TIME MODE
C
*****

```

PROGRAM: REALCVSD.FTN

DATE: 2-19-88
MAVLIN VEN

THIS PROGRAM DOES NOT HAVE THE SOURCE CODING ROUTINES AND CVSD-RECEIVER.

ITS FUNCTION IS DESCRIBED AS FOLLOWS:

A CVSD TRANSMITTER IS SIMPLY A DELTA MODULATOR WITH AN ADAPTIVE STEP SIZE. IN ORDER TO MINIMIZE THE DIFFERENCE BETWEEN ADJACENT SAMPLES, THE INPUT SIGNAL $S(K)$ IS NORMALLY OVERSAMPLED. TYPICALLY, THE SAMPLING RATE IS 16K BITS PER SECOND.

THE TRANSMITTER QUANTIZES THE DIFFERENCE $E(K)$ BETWEEN AN INPUT SPEECH SAMPLE AND ITS ESTIMATE WHICH IS PREDICTED BY A FIRST ORDER PREDICTOR.

$$E(K) = S(K) - \text{ALPHA} * \text{SHAT}(K-1)$$

WHERE $\text{SHAT}(K-1)$ IS THE RECONSTRUCTED SPEECH OF THE INPUT SPEECH SAMPLE AT TIME $K-1$.

THEN THE TRANSMITTER OUTPUTS A SINGLE BIT, $B(K)$, FOR EACH CORRESPONDING INPUT SAMPLE WHERE

$$B(K) = \begin{cases} 1 & \text{IF } E(K) > 0 \\ 0 & \text{IF } E(K) \leq 0 \end{cases}$$

$$B(K) = \begin{cases} 1 & \text{IF } E(K) < 0 \\ 0 & \text{IF } E(K) \geq 0 \end{cases}$$

THE ADAPTIVE STEP SIZE LOGIC DRIVES ITS OUTPUT $\Delta(K)$ FROM THE BIT STREAM $B(K)$ AND AN APPROPRIATE INITIAL STATE.

$$\Delta(K) = \text{BETA} * \Delta(K-1) + G(K)$$

WHERE

$$G(K) = \begin{cases} 1 & \text{DELTA-MAX} * (1 - \text{BETA}) \quad \text{IF } B(K) = B(K-1) \\ 0 & \text{OTHERWISE} \end{cases}$$

$$G(K) = \begin{cases} 1 & \text{DELTA-MIN} * (1 - \text{BETA}) \quad \text{IF } B(K) \neq B(K-1) \\ 0 & \text{OTHERWISE} \end{cases}$$

$$\text{SHAT}(K) = \text{ALPHA} * \text{SHAT}(K-1) + E(K)$$

$$\text{SHAT}(K) = \text{ALPHA} * \text{SHAT}(K-1) + E(K)$$

$$\text{SHAT}(K) = \text{ALPHA} * \text{SHAT}(K-1) + E(K)$$

$$\text{SHAT}(K) = \text{ALPHA} * \text{SHAT}(K-1) + E(K)$$

$$\text{SHAT}(K) = \text{ALPHA} * \text{SHAT}(K-1) + E(K)$$

$$\text{SHAT}(K) = \text{ALPHA} * \text{SHAT}(K-1) + E(K)$$

THE SET OF PARAMETERS WHICH CAN GET THE BEST RESULT FOR CHANNEL NOISE ARE AS FOLLOWS:

$$\begin{aligned} \text{ALPHA} &= 0.94 \\ \text{BETA} &= 0.99 \\ \text{DELTA-MAX} &= 75 \\ \text{DELTA-MIN} &= 25 \end{aligned}$$

THE WAY TO SET UP CVSD IN MAP-388 IS AS FOLLOWS:

1. TO PRODUCE A NEW SNAP-LIBRARY:

F4P CVSDHS-CVSDHS

LBR SNPLIB/IN-CVSDHS

2. TO PRODUCE A CVSD TASK FILE:

F4P REALCVSD-REALCVSD


```

FORTRAN IV-PLUS V02-B1          19:59:12    28-MAR-88          PAGE 3
CVSDBN.FTN    /TR:BLOCKS/VR

0031      SCAL(8)=SCAL(8)/16.**3
0032      TYPE = '...' TYPE IN SAMPLING FREQ.'
0033      READ(4,*)FREQ
0034      WRITE(6,*)' SAMPLING FREQUENCY =',FREQ
0035      CLOSE(UNIT=4)
0036      DEFINE BUS IDENTIFIERS
0037      IBUS1=64
0038      IBUS2=128
0039      IBUS3=192
0040
0041      C---
0042
0043      C
0044      MAP CONFIGURATION BEGINS HERE
0045      M=MPOPM(1)
0046      DO 100 I=1,2
0047      SSIZE=(I-1)*SIZE
0048      M=MPCLB(IBUS3+BSIN(I),B,B+SSIZE,SIZE,REAL,CONTIG,SHORT)
0049      M=MPCLB(IBUS2+BSIN(I),B,B+SSIZE,SIZE,REAL,CONTIG,SHORT)
0050      INITIALIZE THESE BUFFERS
0051      M=VSHA1(BSIN(1),B,BSIN(1),B)
0052      M=VSHA1(BSHTR(1),B,BSHTR(1),B)
0053
0054      CONTINUE
0055      M=MPCLB(IBUS1+IDAOM,38888,B,512,B,FIXED,CONTIG,LONG)
0056      M=MPCLB(IBUS1+IDADM,31888,B,512,B,FIXED,CONTIG,LONG)
0057      M=MPCLB(IBUS1+11,10246,100,2,1,B)
0058      CREATE PREBOUND FUNCTION
0059      M=MPCBF(11,25B)
0060      M=CVSD(BSHTR(1),5B,BSIN(1))
0061      M=CVSD(BSHTR(2),5B,BSIN(2))
0062      M=MPTEF(B)
0063
0064      C
0065      LOAD THE ADAM AND AOM
0066      M=ADMD(IDAOM,FREQ,B,BSHTR(2),BSHTR(1),2)
0067      M=ADMSD(IDADM,FREQ,1,B,B,CHAN1,BSIN(2),BSIN(1))
0068      M=MPLDS(AOM,1052,IDAOM)
0069      M=MPLDS(ADM,1052,IDADM)
0070      M=MPVST(5B,SCAL(1),15,1)
0071
0072      C---
0073
0074      FUNCTION LIST
0075      M=MPBFL(FL1)
0076      M=MPVT(2,BSIN(1))
0077      M=MPXBF(25B)
0078      M=MPVT(2,BSIN(2))
0079      M=MPXBF(251)
0080      M=MPBFL(FL1)
0081      M=MPRAA(ADM,B,B,AOM,B,B)
0082      M=MPVHL(B,B,FL1)
0083
0084      GO INTO WAIT STATE
0085      TYPE = '...' REAL TIME CVSD IS RUNNING ...
0086      TYPE = '...' TYPE IN B-STOP OR 1-CHANGE PARAMETERS'
0087      READ(5,*)LDAT
0088      IF(LDAT.NE.B.AND.LDAT.NE.1)GO TO 500
0089      M=MPSAA(AOM)
0090      M=MPSAA(ADM)
0091      M=MPCLS(B)
0092      IF(LDAT.EQ.1)GO TO 999
0093      STOP
0094      END

```

PROGRAM SECTIONS

NUMBER	NAME	SIZE	ATTRIBUTES
1	SCODE1	882522	681 RV,I,CON,LCL
2	SPDATA	888762	249 RV,D,CON,LCL
3	S1DATA	888328	184 RV,D,CON,LCL
4	SVARS	888248	88 RV,D,CON,LCL
5	STEPS	888882	1 RV,D,CON,LCL

VARIABLES

NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS
ADM	I*2	4-888116	ALT	I*2	4-888174	ADM	I*2	4-888112
DELTH	R*4	4-888284	FIXED	I*2	4-888164	FL1	I*2	4-888184
IBUS1	I*2	4-888228	IBUS2	I*2	4-888222	IBUS3	I*2	4-888224
IOS2	I*2	4-888186	ISIZE	I*2	4-888282	LDATE	I*2	4-888236
REAL	I*2	4-888168	SHORT	I*2	4-888178	SIZE	R*4	4-888176
						CMPLX	I*2	4-888162
						FREQ	R*4	4-888214
						IDADM	I*2	4-888114
						LONG	I*2	4-888166
						SSIZE	R*4	4-888232
						THRE	R*4	4-888218
						CONTIG	I*2	4-888172
						I	I*2	4-888238
						IDAOM	I*2	4-888118
						M	I*2	4-888226

ARRAYS

NAME	TYPE	ADDRESS	SIZE	DIMENSIONS
BSNTR	I*2	4-888188	888884	2 (2)
BSIN	I*2	4-888874	888884	2 (2)
CHAN1	I*2	4-888128	888848	16 (16)
SCAL	R*4	4-888888	888874	38 (15)

LABELS

LABEL	ADDRESS	LABEL	ADDRESS	LABEL	ADDRESS
188	88	988	1-882348	999	1-888876

FUNCTIONS AND SUBROUTINES REFERENCED

ADMSD	ADMID	CLOS	CVSD	MPBFL	MPCBF	MPCLB	MPCLS	MPEFL	MPLDS	MPOPN	MPRAA	MPSAA	MPTBF	MPVHL	MPVST
MPUT	MPXBF	VSNAL													

TOTAL SPACE ALLOCATED = 884266 1115

CVSDBN,CVSDBN/-SP-CVSDBN

APPENDIX G

PROGRAM LISTINGS FOR REAL TIME IMPLEMENTATION OF PARC ON MAP-300

This appendix contains the program listings of all the modules in the real time implementation of the PARC algorithm on the MAP-300 array processor. There are twenty modules in all, some in the PDP-11, and others in the various processors of the MAP 300. Ten modules execute in the MAP-300. Nine of these have host support programs in the PDP-11. And finally, there is the main program in the PDP-11 which sets up and initializes the real time PARC operation on the MAP-300.

The following is a list of these programs and the processors they execute on.

1.	PARC Mainline	PDP-11
2-10.	Host Support Subroutines	PDP-11
11.	Receiver Update Module	CSPU/MAP-300
12.	Transmitter Update Module	CSPU/MAP-300
13.	Initialization Module	CSPU/MAP-300
14.	Pitch Computation Module	AP/MAP-300
15.	PARC Transmitter Module	AP/MAP-300
16.	PARC Receiver Module	AP/MAP-300
17.	Encoder Module	CSPU/MAP-300
18.	IOS Simulator	CSPU/MAP-300
19.	Decoder Module	CSPU/MAP-300
20.	Digital I/O Module	IOS/MAP-300

Operator Sequence to Run PARC at DCA

The two MAP's at DCA have different logical device names, MP and MA. There is a different task images corresponding to each MAP, called PARP.TSK and PARA.TSK. The task names for these programs are NDP and NDA.

To run the real time PARC algorithm, the following steps must be followed for each MAP. For the steps shown below, the devices are called MX. The underlined text is the computer response at the terminal. The rest of the text is the operator input.

```

> LOA MX:      (Load the map device)
> INS MXLD/TASK = ... XLO      (Install map loader program)
> XLO          (Load the map executive including PARC routines.
                The executive is called NDQL)
> INS PARX     (Install the initialization routines for PARC)
> NDX          (Run the initialization program)

```

MODE ?(1 - Internal Loopback, 2-Full Duplex)

```

2              (Mode Selection)

```

These steps for setting up and executing the PARC algorithm are combined into an indirect command file called PARC.CMD. If the indirect command file is used, the operator only needs to run the program (NDX) and select the mode.

PARC96.FTN

/TR:BLOCKS/VR

```

*****
"      PITCH EXTRACTION ADAPTIVE RESIDUAL CODER
"      P A R C
*****

```

MAR 25, 1985

```

REAL TIME IMPLEMENTATION INCLUDING ENCODER, DECODER,
IOS LOOP-BACK.

```

```

5551 REAL SCAL3(26), SCAL1(15), SCAL2(29), A1(85), A2(85)
5552 REAL OUTSCA(25), EXPN(25), T(25), B(25), HOBETA
5553 INTEGER ADM1, ADM2, SAMP, TXVHAT, T1SHAT, T2SHAT, TXPARA
5554 INTEGER INIS(14), KBLK, AOM1, AOM2, AOM3, AOM4
5555 INTEGER RCVHAT, R1SHAT, R2SHAT, RCPARA, BOUT1, BOUT2, TBLK, FBLK
5556 INTEGER RCVNT2
5557 INTEGER IOSPCH(255), SIZE
5558 INTEGER ENCT(35), ENCB(97), DECT(256), DECB(128)
5559 INTEGER PHSTA(8), DECTAB(2, 14), ISEL(3), OFFSET
5560 INTEGER ENTRB, ENTRT, DCRCCT, DCRCB
5561 INTEGER QTR1, QTR2, BTR1, BTR2, ORC1, ORC2, BRC
5562 INTEGER ITBTR1, ITBTR2, ITBRC1, ITBRC2
5563 INTEGER ADM, AOM, IOS, IOS2
5564 INTEGER IDADM, IDAOM, IDIOS
5565 INTEGER IFSEL, CHAN1(16)
5566 INTEGER REAL, CMPLX, FIXED, LONG, SHORT, CONTIG, ALT
5567 DATA IBUS1, IBUS2, IBUS3/64, 128, 192/
5568 DATA ADM1, ADM2, BOUT1, BOUT2/1, 2, 3, 4/
5569 DATA SAMP, TXVHAT, T1SHAT, T2SHAT, TXPARA/5, 6, 7, 8, 9/
5570 DATA RCVHAT, R1SHAT, RCVHAT2, RCPARA/15, 11, 12, 13/
5571 DATA ENTRB, ENTRT, DCRCCT, DCRCB/14, 15, 16, 17/
5572 DATA QTR1, QTR2, ORC1, ORC2, BTR1, BTR2, BRC/18, 19, 20, 21, 22, 23, 24/
5573 DATA IDADM, IDAOM, IDIOS/27, 28, 29/
5574 DATA CHAN1/1, -1, 14-B/
5575 DATA LONG, SHORT, REAL, CMPLX, FIXED, CONTIG, ALT/B, 1, 2, 1, 2, 1, 2/
5576 DATA AOM1, AOM2, AOM3, AOM4/31, 32, 33, 34/
5577 DATA ADM, AOM, IOS, IOS2/23, 22, 16, 2/
5578 DATA ITBTR1, ITBTR2, ITBRC1, ITBRC2, IFSEL/88, 91, 94, 96, 85/
5579 DATA IFPQL, IFPRC, IFPIOS, IFMODE, IFSYNC, IFRCVR/1, 2, 3, 4, 5, 6/
5580 DATA IFSYN1, IFSYN2, IFREC1, IFREC2/7, 8, 9, 15/

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5581 DATA ENCT/3, 7, 5, 2, 5, 3, 11, 5, 47,
1 6, 95, 7, 191, 2, 1, 3, 3, 5, 15,
2 6, 31, 7, 63, 7, 127, 7, 255, 7, 255/
5582 DATA DECTAB/14, -25, 5, 1, 5, 2, 13, 3, 61, 4,
1 125, 5, 253, 6, 4, 7, 12, 8, 65, 9,
2 124, 15, 252, 11, 254, -12, 255, -12/
5583 DATA ENCB/7, 11, 13, 14, 15, 19, 21, 22, 23, 25, 26, 27, 28, 29, 35, 31,
1 35, 37, 38, 39, 41, 42, 43, 44, 45, 46, 47, 49, 55, 51, 52, 53,
2 54, 55, 56, 57, 58, 59, 65, 61, 62, 63, 67, 69, 71, 73, 74,
3 75, 76, 77, 78, 79, 81, 82, 83, 84, 85, 86, 87, 88, 89, 95, 91,
4 92, 93, 94, 95, 97, 98, 99, 155, 151, 152, 153, 154, 155, 156,

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      C
0034      DATA PHBTA/B,1,2,4,8,16,32,64/

      C
0035      INFORMATION AND PARAMETERS

      C
0036      OPEN(UNIT=4,NAME='PARA.DAT',SHARED,TYPE='OLD',READONLY)
      TYPE *, TYPE IN FILTER PARAMETERS : A, B?
0037      READ(4,*)SCAL1(2),SCAL1(3)
      TYPE *, TRANSFER BLOCK SIZE (MULTIPLES OF 2) ?
0038      READ(4,*)TBLK
      TYPE *, FILTERING BLOCK SIZE?
0039      READ(4,*)FBLK
      TYPE *, CORRELATION BLOCK SIZE (MULTIPLES OF 4) ?
0040      READ(4,*)KBLK
      INIS(3)=FBLK-1
0041      INIS(5)=KBLK-1
0042      INIS(7)=TBLK
0043      INIS(14)=TBLK
0044      FFBLK=FBLK
0045      RKBLK=KBLK
0046      TTBLK=TBLK
0047      SCAL1(1)=TTBLK/2.-B.5
0048      SCAL1(4)=FFBLK-B.5
0049      SCAL1(5)=RKBLK/4.-B.5

      C
0050      SCAL3(5)=TTBLK-B.5
      TYPE *, RUN LENGTH, BIT # FOR LEVEL 1 AND BIT # FOR RUN LENGTH CODE ?
0051      READ(4,*)SCAL2(5),BIT1,BITLNT
0052      SCAL2(16)=SCAL2(5)*BIT1-BITLNT
0053      NRUNE=SCAL2(5)-1
0054      SCAL2(15)=SCAL2(5)

      C
0055      TYPE *, PITCH PERIOD SEARCH RANGE: FROM ? TO ?
      READ(4,*)ITSTRT,ITEND
0056      TSTRT=ITSTRT
0057      TEND=ITEND
0058      INIS(4)=ITSTRT-1
0059      INIS(10)=ITSTRT
0060      SCAL1(6)=TEND-TSTRT+B.5
0061      SCAL1(8)=TEND-B.5
0062      SCAL1(10)=TSTRT

      C
0063      TYPE *, BIT BLOCK SIZE, # BITS NULL CODE, GAP SIZE, # BITS PHONEY BETA ?
      READ(4,*)SCAL2(2),SCAL2(21),IGAP,SCAL2(6)
0064      INIS(6)=IGAP
0065      INIS(9)=IGAP
0066      INIS(13)=IGAP
0067      GAP=IGAP
0068      SCAL2(7)=GAP-B.5
0069      SCAL3(19)=SCAL2(7)

      C
0070      TYPE *, GAP THRESHOLD & FILTER THRESHOLD ?
      READ(4,*)INIS(1),INIS(2)

```

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```

C
D
TYPE ' ' VALUES FOR RMSHIN,ALAD,ALP,SMIN,G,AINV,INIT STATE?
READ(4,' ')RMSHIN,ALAD,ALP,SMIN,G,AINV,STATE
N=4
SCAL2(18)=AINV*(1/ALAD-1)
SCAL2(19)=ALAD
SCAL2(20)=N-2.5
SCAL2(3)=RMSHIN/16.**3
SCAL2(4)=STATE
SCAL2(8)=RMSHIN/16.**3
SCAL2(9)=N-2.5
SCAL2(10)=1-ALP
SCAL2(11)=ALP
SCAL2(12)=SMIN
SCAL2(13)=G
SCAL3(6)=RMSHIN/16.**3
SCAL3(7)=STATE
SCAL3(9)=RMSHIN/16.**3
SCAL3(11)=ALAD
SCAL3(18)=N-2.5
SCAL3(15)=1-ALP
SCAL3(16)=ALP
SCAL3(12)=SMIN
SCAL3(14)=G
SCAL3(17)=AINV*(1/ALAD-1)

C
D
TYPE ' ' OF QUANTIZER LEVELS?
READ(4,' ')IK
IL=IK/2
SCAL2(14)=IL
ILL=IL+1
TYPE ' ' OUTPUT SCALING FACTORS FROM 1 TO',ILL
TYPE ' ' EXPANSION/CONTRACTION FACTORS FROM 1 TO',ILL
READ(4,'')(EXPN(J),J=1,ILL)
TYPE ' ' # BITS CORRESPONDING TO EACH LEVEL FROM 1 TO',IK
READ(4,'')(B(I),I=1,IK)
K1=9
K11=9
A1(K1)=(OUTSCA(1)+OUTSCA(2))/2
T(1)=A1(K1)
A1(K1+1)=OUTSCA(1)
A1(K1+2)=EXPN(1)
A1(K1+3)=B(1)
A1(K1+4)=B(1)
A2(K11)=EXPN(1)
A2(K11+1)=OUTSCA(1)
DO 48 I=2,ILL
T(I)=(OUTSCA(1)+OUTSCA(I+1))/2
K11=K11+2
A2(K11)=EXPN(1)
A2(K11+1)=OUTSCA(1)
K1=K1+5
A1(K1)=T(1)
A1(K1+1)=OUTSCA(1)
A1( 2)=( 1)

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      A1(K1+3)=B(1)
      A1(K1+4)=B(1+IL)
      K1=K1+5
      A1(K1)=OUTSCA(ILL)
      A1(K1+1)=EXPN(ILL)
      A1(K1+2)=B(ILL)
      A1(K1+3)=B(ILL+IL)
      K1=K1+2
      A2(K1)=EXPN(ILL)
      A2(K1+1)=OUTSCA(ILL)
      DO 44 I=1,IL
      K1=K1+2
      A2(K1)=A2(9+2*I)
      A2(K1+1)=A2(9+2*I+1)
      CONTINUE
      44
C
      TYPE *, ' UPPER LIMIT OF BETA?'
      READ(4,*)UBETA
      SCAL1(11)=-UBETA
      SCAL1(12)=-UBETA
      SCAL3(13)=SCAL1(12)
C
      TYPE *, ' OF QUANTIZATION LEVELS FOR BETA?'
      READ(4,*)QBETA
      IQBETA=QBETA
      HQBETA=IQBETA/2
      SCAL1(13)=HQBETA/(UBETA*(2.**15))
      SCAL1(14)=HQBETA/(UBETA*(2.**24))
      SCAL1(15)=1./SCAL1(14)
      SCAL3(8)=1./SCAL1(13)
C
      TYPE *, ' SAMPLING FREQUENCY FOR ADAM?'
      READ(4,*)FREADM
C
      TYPE *, ' INVERSE GAIN FACTOR FOR MASKING LSBS?'
      READ(4,*) SCAL3(24)
      SCAL3(24)=1./SCAL3(24)**13)
      TYPE *, ' MAX. Q-BUFFER LENGTH ( < 500 )?'
      READ(4,*) SCAL3(25)
      TYPE *, ' GAIN FACTOR AT ADAM INPUT?'
      READ(4,*) SCAL3(26)
      SCAL3(26)=SCAL3(26)/SCAL3(24)
C
      SCAL1(7)=1./12.**15)
      SCAL1(9)=B.BB1
      SCAL2(1)=B
      SCAL2(17)=1./12.**14)
      SCAL2(22)=SCAL1(7)
      SCAL2(23)=B
      SCAL2(26)=B
      SCAL2(29)=B
      SCAL3(18)=2.**14
      SCAL3(20)=SCAL1(7)
      SCAL3(21)=B
      SCAL3(22)=2047./16.**3)
      SCAL3(23)=-2048./16.**3)

      18BIT COUNTER
      11/2**14

      10N FOR TRANSMITTER
      18BIT
      11/2**14
      11/2**15
      10N FOR RECEIVER

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#165      INIS(8)=1823      IBUFFER SIZE - 1
#166      INIS(11)=INIS(8)      ISTARTING LOCATION FOR RECEIVER BUFFER
#167      INIS(12)=2848      IINI. VALUE FOR A(1)
#168      A1(1)=AINV
#169      A2(1)=AINV
#170      CLOSE(UNIT=4)

      CREATE INFORMATION FILE
      ***** REAL-TIME PARC ALGORITHM *****
      WRITE(6,*) 'PARAMETERS FOR THE ADAPTIVE FILTER:'
      WRITE(6,*) 'A=', SCAL1(2), 'B=', SCAL1(3)
      WRITE(6,*) 'TRANSFER BLOCK SIZE =', TBLK
      WRITE(6,*) 'FILTERING BLOCK SIZE =', FBLK
      WRITE(6,*) 'CORRELATION BLOCK SIZE =', KBLK
      WRITE(6,*) 'RUN LENGTH =', SCAL2(5), 'BIT # FOR ITS CODE =', BITLMT
      WRITE(6,*) 'BIT # FOR LEVEL 1 =', BIT1
      WRITE(6,*) 'PITCH PERIOD SEARCHING RANGE =', ITSTRT, 'TO', ITEND
      WRITE(6,*) 'BIT BLOCK SIZE =', SCAL2(2), 'NULL BIT # =', SCAL2(21)
      WRITE(6,*) 'GAP SIZE =', IGAP, 'PHONY BETA BITS =', SCAL2(6)
      WRITE(6,*) 'RMSMIN =', RMSMIN, 'ALAD =', ALAD, 'ALP =', ALP
      WRITE(6,*) 'SMIN =', SMIN, 'G =', G, 'AINV =', AINV, 'STATE =', STATE
      WRITE(6,*) 'NUMBER OF QUANTIZER LEVELS =', IK
      WRITE(6,*) 'OUTPUT SCALING FACTOR:'
      WRITE(6,*) 'OUTSCA(1), I=1, ILL)
      WRITE(6,*) 'EXPANSION/CONTRACTION FACTORS:'
      WRITE(6,*) 'EXPN(1), I=1, ILL)
      WRITE(6,*) 'QUANTIZER THRESHOLDS:'
      WRITE(6,*) 'T(1), I=1, ILL)
      WRITE(6,*) 'OF BITS CORRESPONDING TO EACH LEVEL:'
      WRITE(6,*) 'UB(1), I=1, IK)
      WRITE(6,*) 'UPPER BETA LIMIT =', UBETA, 'LOWER BETA LIMIT =', SCAL1(11)
      WRITE(6,*) 'OF QUANTIZING LEVELS FOR BETA =', IOBETA
      WRITE(6,*) 'GAP THRESHOLD =', INIS(1), 'FILTER THRESHOLD =', INIS(2)
      WRITE(6,*) 'ADAM SAMPLING FREQ =', FREADM, 'AOM SAMPLING FREQ =', FREADM
      WRITE(6,*) 'INV. GAIN FACTOR FOR MASKING LSBs =', 1./SCAL3(24)*2.**13)
      WRITE(6,*) 'MAX. O-BUFFER LENGTH =', SCAL3(25)
      WRITE(6,*) 'GAIN FACTOR AT ADAM INPUT =', SCAL3(24)*SCAL3(26)

      C----- SET UP ROUTINE FOR IOS TRANSFER
      C
      CALL ASSIGN(3, 'SY:IOSDC.CSP')
      CALL FPMID(IOSPGM, SIZE, MSGERR)
      IF(MSGERR.EQ.0) GO TO 88
      TYPE *, 'ERROR', MSGERR, ' IN IOS PROGRAM'
      STOP
      CONTINUE
      88
      C----- SET IOS DATA RATE
      C
      CNTS=256.-(1.536E6/(4.*2.*FREADM))
      CNTD=256.-(1.536E6/(8.*1.5.*FREADM))
      CNTIOS=256.*CNTD/CNTS
      IF(CNTIOS.GT.32767.) CNTIOS=CNTIOS-65536.
      IOSPGM(2)=CNTIOS

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C ----- SET UP HEADER AND TRAILER BLOCK FOR IOS FUNCTION

```

#182 DO 200 I=1,SIZE
#183 I1=SIZE+1-I
#184 IOSPGM(I1+2)=IOSPGM(I1)
#185
#186 IOSPGM(1)=SIZE
IOSPGM(2)=256*BRC+BTR1
#187
#188 IOSPGM(SIZE+2+1)=B
#189 IOSPGM(SIZE+2+2)=2
#190 IOSPGM(SIZE+2+3)=256*B+BTR2
#191 IOSPGM(SIZE+2+4)=B
#192 IOSPGM(SIZE+2+5)=B
#193 IOSPGM(SIZE+2+6)=1
#194 IOSPGM(SIZE+2+7)=-1
#195 IOSPGM(SIZE+2+8)=-1
#196 IOSPGM(SIZE+2+9)=-1
IOSPGM(SIZE+2+10)=-1

```

MAP BUFFER COFIGURATION

```

#197 CONTINUE
#198 M=MPOPN(1)
#199 M=MPIBC(B)
#200 M=MPCLB(1BUS3+ADM1,3072..126..REAL,CONTIG,SHORT)
#201 M=MPCLB(1BUS3+ADM2,3072..126..126..REAL,CONTIG,SHORT)
#202 M=MPCLB(1BUS2+AOM1,3584..252..REAL,CONTIG,SHORT)
#203 M=MPCLB(1BUS2+AOM2,3840..252..REAL,CONTIG,SHORT)
#204 M=MPCLB(1BUS2+AOM3,3584..126..REAL,CONTIG,SHORT)
#205 M=MPCLB(1BUS2+AOM4,3840..126..REAL,CONTIG,SHORT)
#206 M=MPCLB(1BUS3+SAMP,B..1024..REAL,CONTIG,SHORT)
#207 M=MPCLB(1BUS2+TXVHAT,B..1024..REAL,CONTIG,SHORT)
#208 M=MPCLB(1BUS3+T1SHAT,1024..1024..REAL,CONTIG,SHORT)
#209 M=MPCLB(1BUS2+TXPARA,3072..80..REAL,CONTIG,LONG)
#210 M=MPCLB(1BUS3+RCVHAT,2048..1024..REAL,CONTIG,SHORT)
#211 M=MPCLB(1BUS3+RCVHT2,3068..4..REAL,CONTIG,SHORT)
#212 M=MPCLB(1BUS2+R1SHAT,2048..1024..REAL,CONTIG,SHORT)
#213 M=MPCLB(1BUS2+RCPARA,4096..80..REAL,CONTIG,LONG)
#214 M=MPCLB(1BUS1+IDAOM,23000..250..FIXED,CONTIG,LONG)
#215 M=MPCLB(1BUS1+IDADM,23250..250..FIXED,CONTIG,LONG)
#216 M=MPCLB(1BUS1+IDIOS,23500..200..FIXED,CONTIG,LONG)
#217 M=MPCLB(1BUS1+ENTRB,24000..100..FIXED,CONTIG,LONG)
#218 M=MPCLB(1BUS1+ENTRT,23900..30..FIXED,CONTIG,LONG)
#219 M=MPCLB(1BUS1+DCRCT,24100..256..FIXED,CONTIG,LONG)
#220 M=MPCLB(1BUS1+DCRCB,24400..128..FIXED,CONTIG,LONG)
#221 M=MPCLB(1BUS1+QTR1,25000..600..FIXED,CONTIG,LONG)
#222 M=MPCLB(1BUS1+BTR1,25700..200..FIXED,CONTIG,LONG)
#223 M=MPCLB(1BUS1+QRC1,26000..600..FIXED,CONTIG,LONG)
#224 M=MPCLB(1BUS1+QTR2,27000..600..FIXED,CONTIG,LONG)
#225 M=MPCLB(1BUS1+BTR2,27700..200..FIXED,CONTIG,LONG)
#226 M=MPCLB(1BUS1+QRC2,28000..600..FIXED,CONTIG,LONG)
#227 M=MPCLB(1BUS1+BRC,29000..1024..FIXED,CONTIG,LONG)

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```

C
C
C      INITIALIZE THESE BUFFERS
M=VSMAL(ADM1,B,ADM1,B)
M=VSMAL(ADM2,B,ADM2,B)
M=VSMAL(AOM1,B,AOM1,B)
M=VSMAL(AOM2,B,AOM2,B)
M=VSMAL(AOM3,B,AOM3,B)
M=VSMAL(AOM4,B,AOM4,B)
M=VSMAL(SAMP,B,SAMP,B)
M=VSMAL(TXVHAT,B,TXVHAT,B)
M=VSMAL(TISHAT,B,TISHAT,B)
M=VSMAL(RCVHAT,B,RCVHAT,B)
M=VSMAL(RISHAT,B,RISHAT,B)

C
C
C      INITIALIZE Q-BUFFERS FOR ENCODER
DO 98 I=1,138
  DECT(I)=2
  DECT(I)=1
  DECT(128)=-12
  DECT(129)=-12
  DECT(138)=-12
M=MPVDB(OTR1,DECT(1),2,B,DECT(138))
M=MPVDB(OTR2,DECT(1),2,B,DECT(138))

C
C
C      CONSTRUCT DECODE TABLES
1.DECT - SIZE:256
DO 188 I=1,256
  DECT(I)=B
CONTINUE

188
C
DO 182 I=1,14
  II=DECTAB(1,I)+1
  DECT(II)=DECTAB(2,I)+2
CONTINUE

182
C
C
C      2.DECB - SIZE:128
DO 185 I=1,128
  DECB(I)=48
CONTINUE

185
C
DO 186 I=1,97
  II=ENCB(1)+1
  DECB(II)=I-1
CONTINUE

186
C
DO 187 I=1,8
  II=PHBTA(1)+1
  DECB(II)=-1
CONTINUE

187
C
C      INITIALIZE FUNCTION LIST SELECTOR

```

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```

C
#265      ISEL(1)=B
#266      ISEL(2)=-1
#267      ISEL(3)=56

C----- OFFSET
C
#268      OFFSET=2

C----- INITIALIZE ENCODE-DECODE TABLES
C
#269      M=MPVDB(ENTRT,ENCT(1),2,B,ENCT(3B))
#270      M=MPVDB(ENTRB,ENCB(1),2,B,ENCB(97))
#271      M=MPVDB(ENCRCT,DECT(1),2,B,DECT(256))
#272      M=MPVDB(DCRCT,DECB(1),2,B,DECB(128))
C      INITIALIZE PARAMETERS, SCALARS FOR PARC
C
#273      M=MPVST(5B,SCAL1(1),15,1)
#274      M=MPVST(6B,SCAL2(1),29,1)
#275      M=MPVST(9A,SCAL3(1),26,1)
#276      M=MPVST(5B,INIS(1),14,1)
#277      M=MPVDB(TXPARA,A1(1),4,1,A1(8B))
#278      M=MPVST(IFSEL,ISEL(1),3,B)
#279      M=MPVDB(RCPARA,A2(1),4,1,A2(8B))

C----- SET UP IOS TRANSFER ROUTINE AND LOAD IOS
C
#280      M=MPVDB(IDIOS,IOSPGM(1),2,B,IOSPGM(2B))
#281      M=MPLDS(IOS,IOS2,IDIOS)

C----- LOAD ADAM, AOM FUNCTIONS
C
#282      M=ADMSD(IDADM,2,B,1,B,2,CHAN1,ADM2,ADM1)
#283      M=AOMID(IDAOM,1,B,2,AOM2,AOM1,OFFSET)
#284      M=MPLDS(ADM,IOS2,IDAOM)
#285      M=MPLDS(AOM,IOS2,IDAOM)

C----- FUNCTION LISTS
C
C----- FUNCTION LIST FOR Q-LEVEL LOOP-BACK OPERATION
C
#286      M=MPBFL(IFPRC)
#287      M=MPVT(2,ADM1)
#288      M=PICH3(ITBTR1,ADM1)
#289      M=PCTX(ITBTR1+2,QTR1)
#290      M=MPVT(1,1)
#291      M=RC(ITBTR1,59)
#292      M=TX(56)
#293      M=PCRC(ITBTR1+1,QTR1,AOM3)
#294      M=MPVT(2,ADM2)
#295      M=PICH3(ITBTR2,ADM2)
#296      M=PCTX(ITBTR2+2,QTR2)
#297      M=MPVT(1,1)
#298      M=RC(ITBTR2,59)

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188 ---> 94
1 SAME AS ISEL(3)
189 ---> 95

191 ---> 96


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#337 M=PICH3(ITBTR2,ADM2)
#338 M=PCIX(ITBTR2+2,QTR2)
#339 M=DECD(BRC,IFSEL,ORC1,ITBRC1,ORC2,ITBRC2,DCRCT,DCRCB,IGAP)
#340 M=MPVT(1,1)
#341 M=TX(56)
#342 M=MPEFL(B)

C ----- PARC FULL OP FUNC LIST - 1
C
#343 M=MPBFL(IFREC1)
#344 M=MPVT(2,ADM1)
#345 M=RC(ITBRC1,59)
#346 M=PICH3(ITBTR1,ADM1)
#347 M=ENCD(QTR2,BTR2,ENTRB,ENTRT,ITBTR2,ITBRC1,59)
#348 M=PCIX(ITBTR1+2,QTR1)
#349 M=PCRC(ITBRC1+1,ORC1,ADM3)
#350 M=DECD(BRC,IFSEL,ORC1,ITBRC1,ORC2,ITBRC2,DCRCT,DCRCB,IGAP)
#351 M=MPVT(1,1)
#352 M=TX(56)
#353 M=MPEFL(B)

C ----- PARC FULL OP FUNC LIST - 2
C
#354 M=MPBFL(IFREC2)
#355 M=MPVT(2,ADM2)
#356 M=RC(ITBRC2,59)
#357 M=PICH3(ITBTR2,ADM2)
#358 M=ENCD(QTR1,BTR1,ENTRB,ENTRT,ITBTR1,ITBRC2,59)
#359 M=PCIX(ITBTR2+2,QTR2)
#360 M=PCRC(ITBRC2+1,ORC2,ADM4)
#361 M=DECD(BRC,IFSEL,ORC1,ITBRC1,ORC2,ITBRC2,DCRCT,DCRCB,IGAP)
#362 M=MPVT(1,1)
#363 M=TX(56)
#364 M=MPEFL(B)

C ----- FUNCTION LIST TO RUN PARC WITH Q-LEVEL LOOP-BACK
C
#365 M=MPBFL(IFPOL)
#366 M=INI(58,NRUNL)
#367 M=MPRNS(105,1052,B)
#368 M=MPRAA(ADM,B,ADM,B)
#369 M=MPVT(2,ADM2)
#370 M=RCINI(61)
#371 M=MPVHL(B,B,IFPRC)
#372 M=MPEFL(B)

C ----- READY TO RUN. SELECT MODE AND GO
C
#373 CONTINUE
#374 TYPE '...' SELECT OPERATION MODE:'
#375 TYPE '...' - STOP PROGRAM.
#376 TYPE '...' 1 - Q-LEVEL LOOP-BACK IN MEMORY. (NO 105)'
#377 TYPE '...' 2 - BIT STREAM LOOP-BACK THRU 105. (FULL DUP OP.)'
#378 ACCEPT 'LMODE
#379 GO TO(75B,58B,68B) LMODE+1

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```

C ----- OPERATION MODE 1
C
8388 M-MPXFL(IFPOL)
8389 TYPE '...' PARC IN Q-LEVEL LOOP-BACK MODE (NO IOS)'
8390 TYPE '...'
8391 GO TO 788
C ----- OPERATION MODE 2
C
8394 M-MPXFL(IFPIOS)
8395 TYPE '...' PARC IN FULL DUPLEX MODE (THRU IOS)'
8396 TYPE '...'
C ----- STOP ADM,ADM,IOS, CLOSE MAP, AND STOP.
C
788 CONTINUE
      PAUSE ' TYPE RES... TO CONTINUE'
      M-MPSAA(ADM)
      M-MPSAA(ADM)
      M-MPCLS(B)
      GO TO 85
      CONTINUE
      M-MPCLS(B)
      STOP
      END
785

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FORTRAN IV-PLUS V02-51
PARC96.FTN /TR:BLOCKS/VR
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PROGRAM SECTIONS

NUMBER	NAME	SIZE	ATTRIBUTES
1	SCODE1	012752 2885	RV,I.CON,LCL
2	SFOATA	001030 268	RV,D.CON,LCL
3	SIDATA	002024 522	RV,D.CON,LCL
4	SVARS	005756 1527	RV,D.CON,LCL
5	STEMPS	000004 2	RV,D.CON,LCL

VARIABLES

NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS
ADM	I*2	4-005440	ADM1	I*2	4-002334	ADM2	I*2	4-002336	AINV	R*4	4-005664
ALP	R*4	4-005650	ALT	I*2	4-005534	AOM	I*2	4-005442	AOM1	I*2	4-002410
AOM3	I*2	4-002414	AOM4	I*2	4-002416	BITLMT	R*4	4-005610	BITI	R*4	4-005604
BOUT2	I*2	4-002432	BRC	I*2	4-005426	BTRI	I*2	4-005416	BTR2	I*2	4-005420
CNTD	R*4	4-005740	CNTIOS	R*4	4-005744	CNTS	R*4	4-005734	CONTIG	I*2	4-005532
DCRCT	I*2	4-005406	ENTR8	I*2	4-005402	ENTRT	I*2	4-005404	FBLK	I*2	4-002436
FIXED	I*2	4-005524	PREADM	R*4	4-005726	G	R*4	4-005660	GAP	R*4	4-005634
I	I*2	4-005706	IBUS1	I*2	4-005536	IBUS2	I*2	4-005540	IBUS3	I*2	4-005542
IDAOM	I*2	4-005452	IDIOS	I*2	4-005454	IFMODE	I*2	4-005552	IFPIOS	I*2	4-005550
IFPRC	I*2	4-005546	IFRCVR	I*2	4-005556	IFREC1	I*2	4-005564	IFREC2	I*2	4-005566
IFSYN1	I*2	4-005554	IFSYN1	I*2	4-005560	IFSYN2	I*2	4-005562	IGAP	I*2	4-005632
IK	I*2	4-005676	IL	I*2	4-005700	ILL	I*2	4-005702	IOS	I*2	4-005444
IOBETA	I*2	4-005724	ITBRC1	I*2	4-005434	ITBRC2	I*2	4-005436	ITBTR1	I*2	4-005430
ITEND	I*2	4-005620	ITSTRT	I*2	4-005616	J	I*2	4-005704	KBLK	I*2	4-005752
K11	I*2	4-005712	LMODE	I*2	4-005754	LONG	I*2	4-005526	M	I*2	4-005710
N	I*2	4-005674	NRUNL	I*2	4-005514	OFFSET	I*2	4-005400	OBETA	R*4	4-005720
ORC2	I*2	4-005424	QTR1	I*2	4-005412	QTR2	I*2	4-005414	RCPARA	I*2	4-002426
RCVHT2	I*2	4-002440	REAL	I*2	4-005520	RKBLK	R*4	4-005574	RSHAT	I*2	4-005640
R2SHAT	I*2	4-002424	SAMP	I*2	4-002340	SHORT	I*2	4-005530	SIZE	I*2	4-003262
STATE	R*4	4-005670	TBLK	I*2	4-002434	TEND	R*4	4-005626	TSTRT	R*4	4-005622
TXPARA	I*2	4-002350	TXVHAT	I*2	4-002342	TISHAT	I*2	4-002344	T2SHAT	I*2	4-002346

ARRAYS

NAME	TYPE	ADDRESS	SIZE	DIMENSIONS
A1	R*4	4-000430	000500	(00)
A2	R*4	4-001130	000500	(00)
B	R*4	4-002210	000120	(00)
CHAN1	I*2	4-005460	000040	(16)
DECB	I*2	4-004662	000400	(128)
DECT	I*2	4-003662	001000	(256)
DECTAB	I*2	4-005302	000070	(2,14)
ENCB	I*2	4-003360	000302	(97)
ENCT	I*2	4-003264	000074	(30)
EXPX	R*4	4-001750	000120	(20)
INIS	I*2	4-002352	000034	(14)
IOSPGM	I*2	4-002442	000620	(200)
ISEL	I*2	4-005372	000006	(3)
OUTSCA	R*4	4-001630	000120	(20)

FORTAN IV-PLUS V02-51
TRRC.FTN /TR:BLOCKS/VR

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PROGRAM SECTIONS

NUMBER	NAME	SIZE	ATTRIBUTES
1	SCODE1	73	RV,I,CON,LCL
3	SIDATA	6	RV,D,CON,LCL
4	SVARS	3	RV,D,CON,LCL
6	MPZZZ	101	RV,D,OVR,CBL

ENTRY POINTS

NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS
INI	I*2	1-000000						

VARIABLES

NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS
HRD	I*2	4-000002	HR1	R*4	6-000304	HVS	I*2	4-000000
LEVEL	I*2	6-000310	LRUN	I*2	F-000004*	ISA	I*2	F-000002*

ARRAYS

NAME	TYPE	ADDRESS	SIZE	DIMENSIONS
FCB	I*2	6-000260	000014	6 (6)
FCBRG	I*2	6-000000	000026	11 (11)
FCBSZ	I*2	6-000026	000232	77 (11,7)
MPDCB	I*2	6-000274	000010	4 (4)

LABELS

LABEL	ADDRESS	LABEL	ADDRESS	LABEL	ADDRESS
100	**	200	1-000144		

FUNCTIONS AND SUBROUTINES REFERENCED

MPERR RUNMP

TOTAL SPACE ALLOCATED = 000556 183

```

FORTRAN IV-PLUS V02-51      12:47:28      15-APR-80      PAGE 3
TRNC.FTN  /TR:BLOCKS/WR

      C
      C      INTEGER FUNCTION TX(ISA)
      C 11.  TX(ISA) --- UPDATE PROGRAM FOR APS MODULES FOR PARC-TRANSMITTER
      C
      C      FCB = 114
      C
      C      CALL FORMAT:
      C
      C      MAP=TX(ISA)
      C      WHERE ISA --- THE STARTING INTEGER SCALAR LOCATION
      C
      C      INTEGER FCBRG,FCBSZ,HWS,FCB,MPDCB,HRD,LEVEL
      C      INTEGER ISA
      C      COMMON /MPZZZ/FCBRG(11),FCBSZ(11,7),FCB(6),MPDCB(4),HRI,LEVEL
      C
      C      TX=B
      C      DO 100 I=1,11
      C      FCBRG(I)=B
      C      FCBRG(2)=114
      C      CHECK ARGUMENT
      C      IF(ISA.LT. B .OR. ISA.GT. 127)TX=-1
      C
      C      IF(TX.EQ. B)GO TO 200
      C      CALL MPERR(TX)
      C      RETURN
      C
      C      FCBRG(3)=ISA
      C      TX=RUNMP(FCBRG(1),FCBSZ(1,3))
      C
      C      RETURN
      C      END

```

FORTAN IV-PLUS V02-51
TRAC.FTM /TR:BLOCKS/VR

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PROGRAM SECTIONS

NUMBER	NAME	SIZE	ATTRIBUTES
1	SCODE1	000214	78
3	SIDATA	000014	6
4	SVARS	000006	3
6	MPZZZ	000312	101

ENTRY POINTS

NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS
TX	1*2	1-000000									

VARIABLES

NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS
HRD	1*2	4-000002	HRI	R*4	6-000304	HVS	1*2	4-000000	I	1*2	4-000004
LEVEL	1*2	6-000310							ISA	1*2	F-000002*

ARRAYS

NAME	TYPE	ADDRESS	SIZE	DIMENSIONS
FCB	1*2	6-000260	000014	6 (6)
FCBRG	1*2	6-000000	000026	11 (11)
FCBSZ	1*2	6-000026	000232	77 (11,7)
MPDCB	1*2	6-000274	000010	4 (4)

LABELS

LABEL	ADDRESS	LABEL	ADDRESS	LABEL	ADDRESS	LABEL	ADDRESS
100	**	200	1-000144				

FUNCTIONS AND SUBROUTINES REFERENCED

MPERR RUNMP

TOTAL SPACE ALLOCATED = 000550 100

```

FORTRAN IV-PLUS V02-51      12:47:34      15-APR-80      PAGE 5
TRRC.FTN

      C
      C      INTEGER FUNCTION RC(SA,ISA)
      C III.  RC(SA,ISA) --- UPDATE PROGRAM FOR APS MODULES OF PARC-RECEIVER
      C      FCB = 113
      C      CALL FORMAT:
      C      MAP=RC(SA,ISA)
      C      WHERE SA --- SCALAR LOCATION FOR T
      C      ISA --- THE STARTING INTEGER SCALAR LOCATION
      C
      C      INTEGER FCBRG,FCBSZ,HWS,FCB,MPDCB,HRD,LEVEL
      C      INTEGER SA,ISA
      C      COMMON /MPZZZ/FCBRG(11),FCBSZ(11,7),FCB(6),MPDCB(4),MRI,LEVEL
      C
      C      RC=0
      C      DO 100 I=1,11
      C      FCBRG(I)=0
      C      FCBRG(2)=113
      C      CHECK ARGUMENTS
      C      IF(SA.LT.0.OR.SA.GT.127)RC=-1
      C      IF(ISA.LT.0.OR.ISA.GT.127)RC=-2
      C
      C      IF(RC.EQ.0)GO TO 200
      C      CALL MPERR(RC)
      C      RETURN
      C
      C      FCBRG(9)=SA
      C      FCBRG(11)=ISA
      C      RC=RUNMP(FCBRG(1),FCBSZ(1,5))
      C
      C      RETURN
      C      END

```

FORTRAN IV-PLUS V02-51
TRNC.FTN /TR:BLOCKS/VR

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PROGRAM SECTIONS

NUMBER	NAME	SIZE	ATTRIBUTES
1	SCODE1	83	RV,I.COM,LCL
3	SIDATA	6	RV,D.COM,LCL
4	SVARS	3	RV,D.COM,LCL
6	MPZZZ	101	RV,D.OVR,GBL

ENTRY POINTS

NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS
RC	1*2	1-000000						

VARIABLES

NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS
HRD	1*2	4-000002	HR1	R*4	6-000304	HVS	1*2	4-000000
LEVEL	1*2	6-000310	SA	1*2	F-000002*	ISA	1*2	4-000004
								F-000004*

ARRAYS

NAME	TYPE	ADDRESS	SIZE	DIMENSIONS
FCB	1*2	6-000260	000014	6 (6)
FCBGC	1*2	6-000000	000026	11 (11)
FCBSZ	1*2	6-000026	000232	77 (11,7)
MPDCB	1*2	6-000274	000010	4 (4)

LABELS

LABEL	ADDRESS	LABEL	ADDRESS	LABEL	ADDRESS
100	**	200	1-000170		

FUNCTIONS AND SUBROUTINES REFERENCED

MPERR RUNMP

TOTAL SPACE ALLOCATED - 000602 193

```

FORTRAN IV-PLUS V02-51      12:47:41    15-APR-88      PAGE 7
TRAC.FTN      /TR:BLOCKS/VR

      C
      C      INTEGER FUNCTION PICH3(SA,U)
      C IV.  PICH3 -- FOR BETA, T COMPUTATION AND FILTER, GAPPING OPERATIONS
      C
      C      FCB = 248
      C
      C      CALL FORMAT:
      C      MAP=PICH3(SA,U)
      C
      C      WHERE SA --- SCALAR LOCATION FOR ENCD. BETA, BETA AND T
      C      U --- INPUT ADAM BUFFER
      C
      C      INTEGER SA,U
      C      IDUMY=8
      C      PICH3=FCB6N(248,B.SA,U,IDUMY,B,B,B,6)
      C      RETURN
      C      END

```

0001

0002
0003
0004
0005
0006

FORTRAM IV-PLUS V02-51
TRRC.FTN /TR:BLOCKS/VR

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PROGRAM SECTIONS

NUMBER	NAME	SIZE	ATTRIBUTES
1	SCODE1	000102	RV,I,CON,LCL
2	SPDATA	000014	RV,D,CON,LCL
3	SIDATA	000038	RV,D,CON,LCL
4	SVARS	000002	RV,D,CON,LCL

ENTRY POINTS

NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS
PICH3	I*2	1-000000						

VARIABLES

NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS
IDUHV	I*2	4-000000	SA	I*2	F-000002	U	I*2	F-000004

FUNCTIONS AND SUBROUTINES REFERENCED

FCBGN

TOTAL SPACE ALLOCATED = 000158 52

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TRRC.FTN /TR:BLOCKS/VR

```

0001      C      INTEGER FUNCTION PCTX(SA,U)
          C V.    PCTX -- PARC-TRANSMITTER
          C      FCB = 242
          C      CALL FORMAT:
          C      MAP=PCTX(SA,U)
          C      WHERE SA --- THE SCALAR LOCATION FOR BETA
          C      U --- OUTPUT QUANTIZING BUFFER
          C
          C      INTEGER SA,U
          C      IDUMY=0
          C      PCTX=FCBGN(242,B,SA,U,IDUMY,B,B,B,6)
          C      RETURN
          C      END
0002
0003
0004
0005
0006

```

FORTRAN IV-PLUS V02-S1
TRRC.FTN /TR:BLOCKS/WR

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PROGRAM SECTIONS

NUMBER	NAME	SIZE	ATTRIBUTES
1	SCODE1	000102	33 RV,I.CON,LCL
2	SPDATA	000014	6 RV,D.CON,LCL
3	SIDATA	000030	12 RV,D.CON,LCL
4	SVARS	000002	1 RV,D.CON,LCL

ENTRY POINTS

NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS
PCTX	I*2	1-000000						

VARIABLES

NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS
IDUHY	I*2	4-000000	SA	I*2	F-000002	U	I*2	F-000004

FUNCTIONS AND SUBROUTINES REFERENCED

FCBGN

TOTAL SPACE ALLOCATED = 000150 52

```

FORTRAN IV-PLUS V02-51          PAGE 11
TRRC.FTN                        12:47:48    15-APR-68

C
C
0001      INTEGER FUNCTION PCRC(SA,U,V)
C
C VI.      PCRC ---- PARC-RECEIVER
C
C          FCB = 243
C
C          CALL FORMAT:
C          MAP=PCRC(SA,U,V)
C
C          WHERE SA --- SCALAR NUMBER FOR INPUT ENCD. BETA AND T
C          V --- AOM BUFFER
C          U --- INPUT QUANTIZING BUFFER
C
0002      INTEGER SA,U,V
0003      PCRC=FCBGN(243,B,SA,U,B,V,B,B,7)
0004      RETURN
0005      END

```

FORTAN IV-PLUS V82-S1
TRAC.FTH

12:47:48

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/TR:BLOCKS/VR

PROGRAM SECTIONS

NUMBER	NAME	SIZE	ATTRIBUTES
1	SCODE1	34	RV,I,CON,LCL
2	SPDATA	6	RV,D,CON,LCL
3	SIDATA	12	RV,D,CON,LCL

ENTRY POINTS

NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS
PCRC	I*2	1-888888						

VARIABLES

NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS
SA	I*2	F-888882*	U	I*2	F-888884*	V	I*2	F-888886*

FUNCTIONS AND SUBROUTINES REFERENCED

FCBGN

TOTAL SPACE ALLOCATED = 888158 52

```

FORTRAN IV-PLUS V02-51      12:47:52      15-APR-88      PAGE 13
TRNC.FTN      /TR:BLOCKS/VR

C
0001      INTEGER FUNCTION RCINI(ISA)
C
C VII. RCINI(ISA) --- INITIALIZATION PROGRAM FOR APS MODULES OF RECEIVER.
C
C
C FCB = 116
C
C CALL FORMAT:
C
C MAP-RCINI(ISA)
C WHERE ISA --- THE STARTING INTEGER SCALAR LOCATION
C
C INTEGER FCBRG,FCBSZ,HVS,FCB,MPDCB,HRD,LEVEL
C INTEGER ISA
C COMMON /MPZZZ/FCBRG(11),FCBSZ(11,7),FCB(6),MPDCB(4),HRI,LEVEL
C
C RCINI=0
C DO 100 J=1,11
C FCBRG(1)=0
C FCBRG(2)=116
C CHECK ARGUMENT
C IF(ISA .LT. 0 .OR. ISA .GT. 127)RCINI=-1
C
C IF(RCINI .EQ. 0)GO TO 200
C CALL MPERR(RCINI)
C RETURN
C
C FCBRG(3)=ISA
C RCINI=RUNMP(FCBRG(1),FCBSZ(1,3))
C
C RETURN
C END
0002
0003
0004
0005
0006
0007
0008
0009
0010
0011
0012
0013
0014
0015
0016

```

FORTRAN IV-PLUS V02-51
TRRC.FTN /TR:BLOCKS/JR

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PROGRAM SECTIONS

NUMBER	NAME	SIZE	ATTRIBUTES
1	SCODE1	71	RV,I,CON,LCL
3	STDATA	6	RV,D,CON,LCL
4	SVARS	3	RV,D,CON,LCL
6	MPZZZ	101	RV,D,OVR,GBL

ENTRY POINTS

NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS
RCINI	I*2	1-000000						

VARIABLES

NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS
HRD	I*2	4-000002	HR1	R*4	6-000304	HVS	I*2	4-000000
LEVEL	I*2	6-000310				I	I*2	4-000004
						ISA	I*2	F-000002*

ARRAYS

NAME	TYPE	ADDRESS	SIZE	DIMENSIONS
FCB	I*2	5-000260	000014	6 (6)
FCBRG	I*2	6-000000	000026	11 (11)
FCBSZ	I*2	6-000026	000232	77 (11,7)
MPDCB	I*2	6-000274	000010	4 (4)

LABELS

LABEL	ADDRESS	LABEL	ADDRESS	LABEL	ADDRESS
100	**	200	1-000106		

FUNCTIONS AND SUBROUTINES REFERENCED

MPERR RUNMP

TOTAL SPACE ALLOCATED = 000552 101

FORTAN IV-PLUS V#2-B1
TRAC.FTN /TR:BLOCKS/VR

12:47:58

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C
C

.TRAC/NOSP=TRRC

```

FORTRAN IV-PLUS V02-S1      12:48:04      15-APR-80      PAGE 1
ENCD.FTN /TR:BLOCKS/VR

      C
0001      C
      C -----
      C      INTEGER FUNCTION ENCD(QHAT,OUTB,BETA,ENCT,ISTB,SID,ISID)
      C      HOST SUPPORT MODULE FOR SOURCE CODING THE Q-OUTPUT OF
      C      THE PARC ALGORITHM.
      C
      C      FCB=110
      C
      C      CALLING SEQUENCE:
      C      M=ENCD(QHAT,OUTB,BETA,ENCT,ISTB,SID,ISID)
      C
      C      WHERE:
      C      QHAT = Q-OUTPUT BUFFER, LENGTH=400
      C      OUTB = OUTPUT BIT BUFFER, LENGTH=200
      C      BETA = CODING TABLE FOR 99 BETA VALUES, LENGTH=100
      C      ENCT = SOURCE CODE BUFFER, LENGTH=30
      C      CONTAINS FOR EACH LEVEL:
      C          1ST WORD: CODE LENGTH-1
      C          2ND WORD: CODE
      C
      C      ISTB = SID IN INTEGER TABLE WHERE T,BETA ARE LOCATED
      C      SID = SCALAR ID FOR RCVR UPDATE
      C      ISID = INT. SCALAR ID FOR RCVR UPDATE
      C
      C      INTEGER FCBRG,FCBSZ,HVS,FCB,MPDCB,HRD,LEVEL
      C      INTEGER QHAT,OUTB,BETA,ENCT,ISTB,SID,ISID
      C      COMMON /MPZZZ/FCBRG(11),FCBSZ(11,7),FCB(6),MPDCB(4),HRI,LEVEL
      C
      C      ENCD=0
      C      DO 100 I=1,11
      C      FCBRG(I)=0
      C      CONTINUE
      C      FCBRG(2)=110
      C
      C ----- CHECK BID VALUES
      C
      C      IF(QHAT.LT.1.OR.QHAT.GT.63) ENCD=-1
      C      IF(OUTB.LT.1.OR.OUTB.GT.63) ENCD=-2
      C      IF(BETA.LT.1.OR.BETA.GT.63) ENCD=-3
      C      IF(ENCT.LT.1.OR.ENCT.GT.63) ENCD=-4
      C
      C ----- CHECK SCALAR VALUES
      C
      C      IF(ISTB.LT.1.OR.ISTB.GT.127) ENCD=-5
      C      IF(SID.LT.1.OR.SID.GT.127) ENCD=-6
      C      IF(ISID.LT.1.OR.ISID.GT.127) ENCD=-7
      C
      C      IF(ENCD.EQ.0) GO TO 150
      C      CALL MPERR(ENCD)
      C      RETURN
      C
      C      CONTINUE
      C      FCBRG(3)=ISTB
      C      FCBRG(4)=OUTB
      C      FCBRG(5)=QHAT
      C      FCBRG(6)=BETA
      C      FCBRG(7)=ENCT

```

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FORTAN IV-PLUS V02-51
 ENCD.FTN /TR:BLOCKS/VR

0026 FCORG(9)=SID
 0027 FCORG(11)=ISID

0028 C ENCD=RUNMP(FCORG(1),FCBSZ(1,5))

0029 C RETURN
 0030 END

FORTRAM IV-PLUS V02-51
ENDC.FTN /TR:BLOCKS/VR

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PROGRAM SECTIONS

NUMBER	NAME	SIZE	ATTRIBUTES
1	SCODE1	988478	156
3	SIDATA	888814	6
4	SVARS	888886	3
6	MP22Z	888312	181

ENTRY POINTS

NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS
ENDC	1*2	1-888888									

VARIABLES

NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS
BETA	1*2	F-888886*	ENCT	1*2	F-888818*	HRD	1*2	4-888882	HR1	R*4	6-8888384
I	1*2	4-888884	ISID	1*2	F-888816*	ISTB	1*2	F-888812*	LEVEL	1*2	6-8888318
QHAT	1*2	F-888882*	SID	1*2	F-888814*				OUTB	1*2	F-888884*

ARRAYS

NAME	TYPE	ADDRESS	SIZE	DIMENSIONS
FCB	1*2	6-8888268	888814	6 (6)
FCBGR	1*2	6-8888888	888826	11 (11)
FCBSZ	1*2	6-888826	888232	77 (11.7)
MPDCB	1*2	6-8888274	888818	4 (4)

LABELS

LABEL	ADDRESS	LABEL	ADDRESS	LABEL	ADDRESS	LABEL	ADDRESS
188	**	158	1-8888354				

FUNCTIONS AND SUBROUTINES REFERENCED

MPERR RUNMP

TOTAL SPACE ALLOCATED = 881824 266

FORTAN IV-PLUS V82-51
ENCD.FTN /TR:BLOCKS/VR

C

.ENCD/NOSP=ENCD

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FORTRAN IV-PLUS V02-51      12:48:21    15-APR-88      PAGE 1
TRBUF.FTN      /TR:BLOCKS/VP

C
0001      INTEGER FUNCTION TRBUF(DBUF1,DBUF2,INIT,CBUF)
C
C ----- HOST SUPPORT MODULE FOR DOUBLE BUFFER TO CIRC BUFF TRANSFER
C PROGRAM.
C ----- IOS SIMULATOR IN CSPU. (ON/OFF HOOK SIMULATION)
C
C      FCB=112
C
C ARGUMENTS:
C      DBUF1 = BID OF DOUBLE BUFFER 1
C      DBUF2 = BID OF DOUBLE BUFFER 2
C      INIT = INT. SCALAR ID FOR INIT. SELECT SWITCH
C      INIT+1 = INT. SCALAR ID FOR IOS MODE
C      # - OFF HOOK
C      1 - ON HOOK
C      CBUF = BID FOR CIRCULAR BUFFER
C
C      INTEGER FCBRG,FCBSZ,HWS,FCB,MPDCB,HRI,LEVEL,RUNMP
C      INTEGER DBUF1,DBUF2,INIT,CBUF
C      COMMON /MPZZZ/FCBRG(11),FCBSZ(11,7),FCB(6),MPDCB(4),HRI,LEVEL
C
C      TRBUF=#
C      DO 100 I=1,11
C      FCBRG(I)=#
C      CONTINUE
C      FCBRG(2)=112
C
C ----- CHECK ARGUMENTS
C
C      IF(DBUF1.LT.1.OR.DBUF1.GT.63) TRBUF=-1
C      IF(DBUF2.LT.1.OR.DBUF2.GT.63) TRBUF=-2
C      IF(INIT.LT.1.OR.INIT.GT.127) TRBUF=-3
C      IF(CBUF.LT.1.OR.CBUF.GT.63) TRBUF=-4
C
C      IF(TRBUF.EQ.#) GO TO 150
C      CALL MPERR(TRBUF)
C      RETURN
C
C      CONTINUE
C      FCBRG(3)=INIT
C      FCBRG(4)=DBUF1
C      FCBRG(5)=DBUF2
C      FCBRG(7)=CBUF
C
C      TRBUF=RUNMP(FCBRG(1),FCBSZ(1,4))
C
C      RETURN
C      END

```

FORTAN IV-PLUS V02-51
TRBUF.FTN /TR:8LOCKS/VR

12:48:21 15-APR-88

PAGE 2

PROGRAM SECTIONS

NUMBER	NAME	SIZE	ATTRIBUTES
1	SCODE1	88326	187
3	SIDATA	88814	6
4	SVARS	88884	2
6	MPZZZ	88318	188

ENTRY POINTS

NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS
TRBUF	1*2	1-888888						

VARIABLES

NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS
CBUF	1*2	F-888818*	DBUF1	1*2	F-888882*	DBUF2	1*2	F-888884*
1	1*2	4-888882	INIT	1*2	F-888886*	LEVEL	1*2	6-888886
						HR1	1*2	6-888884
						HVS	1*2	4-888888

ARRAYS

NAME	TYPE	ADDRESS	SIZE	DIMENSIONS
FCB	1*2	6-888268	88814	6 (6)
FCRG	1*2	6-888888	88826	11 (11)
FCBSZ	1*2	6-888826	88832	77 (11,7)
MPDCB	1*2	6-888274	88818	4 (4)

LABELS

LABEL	ADDRESS	LABEL	ADDRESS	LABEL	ADDRESS
188	**	158	1-888252		

FUNCTIONS AND SUBROUTINES REFERENCED

MPERR RUNMP

TOTAL SPACE ALLOCATED = 888656 215

NO FPP INSTRUCTIONS GENERATED

FORTAN IV-PLUS V#2-51
TRBUF.FTN /TR:BLOCKS/VR
PAGE 3

12:48:29 15-APR-88

C

.TRBUF/NOSP=TRBUF

```

FORTAN IV-PLUS V02-S1      12:48:36      15-APR-88      PAGE 1
DECD.FTN      /TR:BLOCKS/VR

0001      C      INTEGER FUNCTION DECD(ICB,ISL,OOB1,ITB1,OOB2,ITB2,DECT,DECB,IG)
C-----      MOST SUPPORT MODULE FOR DECODING BIT STREAM INPUT FOR THE
C      PARC RECEIVER.
C      FCB=111
C      CALLING SEQUENCE:
C      M=DECD(ICB,ISL,OOB1,ITB1,OOB2,ITB2,DECT,DECB,IG)
C      WHERE:
C      ICB = INPUT BIT BUFFER, CIRCULAR, LENGTH=1024
C      ISL = FUNCTION LIST SELECTOR
C      ISL1 = 0 - INITIALIZE, SYNCHRONIZE
C      -1 - SYNCHRONIZE
C      +1 - DECODE
C      ISL2 = -1 - FUNC. LIST 1
C      +1 - FUNC. LIST 2
C      ISL3 = INT. SCAL ID FOR XMTR UPDATE
C      OOB1 = OUTPUT QHAT BUFFER 1, LENGTH=400
C      ITB1 = INT. SC. TABLE LOC. FOR T.BETA 1, LENGTH=2
C      OOB2 = OUTPUT QHAT BUFFER 2, LENGTH=400
C      ITB2 = INT. SC. TABLE LOC. FOR T.BETA 2, LENGTH=2
C      DECT = Q-LEVEL DECODE TABLE, LENGTH=256
C      DECB = BETA DECODE TABLE, LENGTH=128
C      IG = GAP SIZE IN INTEGER FORMAT

0002      C      INTEGER FCBRG,FCBSZ,HVS,FCB,MPDCB,HRI,LEVEL,RUNMP
0003      C      INTEGER ICB,ISL,OOB1,ITB1,OOB2,ITB2,DECT,DECB
0004      C      COMMON /MPZZZ/FCBRG(11),FCBSZ(11,7),FCB(6),MPDCB(4),HRI,LEVEL
C      DECD=0
C      DO 100 I=1,11
C      FCBRG(I)=0
C      CONTINUE
C      FCBRG(2)=111
C-----      CHECK BID VALUES
C      IF(ICB.LT.1.OR.ICB.GT.63) DECD=-1
C      IF(OOB1.LT.1.OR.OOB1.GT.63) DECD=-3
C      IF(OOB2.LT.1.OR.OOB2.GT.63) DECD=-5
C      IF(DECT.LT.1.OR.DECT.GT.63) DECD=-7
C      IF(DECB.LT.1.OR.DECB.GT.63) DECD=-8
C-----      CHECK SID VALUES
C      IF(ISL.LT.1.OR.ISL.GT.127) DECD=-2
C      IF(ITB1.LT.1.OR.ITB1.GT.127) DECD=-4
C      IF(ITB2.LT.1.OR.ITB2.GT.127) DECD=-6
C-----      CHECK GAP SIZE
C      IF((IC.LT.1) OR (IG.GT.125)) DECD=-9

```

FORTAN IV-PLUS V02-51
 DECD.FTN /TR:BLOCKS/VR PAGE 2

12:48:36 15-APR-80

```

C
0019 IF(DECD.EQ.0) GO TO 150
0020 CALL MPERR(DECD)
0021 RETURN
C
0022 CONTINUE
0023 FCBRG(3)=ISL
0024 FCBRG(4)=OQB2
0025 FCBRG(5)=OQB1
0026 FCBRG(6)=ITB2
0027 FCBRG(7)=ITB1
0028 FCBRG(8)=DECT
0029 FCBRG(9)=DECB
0030 FCBRG(10)=IG
0031 FCBRG(11)=ICB
C
0032 DECD=RUNMP(FCBRG(1),FCBSZ(1,5))
C
0033 RETURN
0034 END

```

FORTAN IV-PLUS V02-S1
DECD.FTN /TR:BLOCKS/VR

12:48:36 15-APR-88

PAGE 3

PROGRAM SECTIONS

NUMBER	NAME	SIZE	ATTRIBUTES
1	SCODE1	177	RV.I.CON.LCL
3	SIDATA	6	RV.D.CON.LCL
4	SVARS	2	RV.D.CON.LCL
6	MPZZZ	188	RV.D.OVR.GBL

ENTRY POINTS

NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS
DECD	I*2	1-000000						

VARIABLES

NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS	NAME	TYPE	ADDRESS
DECB	I*2	F-000028*	DECT	I*2	F-000016*	HRI	I*2	6-000304
ICB	I*2	F-000002*	IG	I*2	F-000022*	ISL	I*2	F-000004*
LEVEL	I*2	6-000306	OQB1	I*2	F-000006*	OQB2	I*2	F-000012*

ARRAYS

NAME	TYPE	ADDRESS	SIZE	DIMENSIONS
FCB	I*2	6-000268	000014	6
FCBRG	I*2	6-000000	000026	11
FCBSZ	I*2	6-000026	000232	77
MPDCB	I*2	6-000274	000010	4

LABELS

LABEL	ADDRESS	LABEL	ADDRESS	LABEL	ADDRESS
100	**	150	1-0000430		

FUNCTIONS AND SUBROUTINES REFERENCED

MPERR RUNMP

TOTAL SPACE ALLOCATED = 001072 205

NO FPP INSTRUCTIONS GENERATED

FORTAN IV-PLUS VB2-51
DECD.FTN /TR:BLOCKS/VR
PAGE 4

12:48:47 15-APR-88

C

.DECD/NOSP-DECD

```

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(00002) *
(00003) *
(00004) *
(00005) *
(00006) *
(00007) *
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MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1980
*****
* REAL TIME IMPLEMENTATION OF THE P A R C ALGORITHM *
* *****
*
PROGRAM: PARC.MAP
JAN. 30, 1980
MAVLIN YEH
ARVIND S ARORA

```

P A R C (PITCH EXTRACTED, ADAPTIVE, PREDICTIVE RESIDUAL ENCODER) IS A SPEECH COMPRESSION ALGORITHM DEVELOPED AT THE DEPARTMENT OF ELECTRICAL ENGINEERING, UNIVERSITY OF NOTRE DAME UNDER CONTRACT FROM THE DEFENCE COMMUNICATION AGENCY. THE ALGORITHM HAS BEEN CURRENTLY DEVELOPED AND OPTIMIZED FOR DIGITAL TRANSMISSION OF SPEECH AT 9600 BAUD.

THE REAL TIME IMPLEMENTATION OF P A R C HAS BEEN DONE ON THE MAP-300 ARRAY PROCESSOR. SEVEN OF THE EIGHT PROGRAM MODULES USED IN THE IMPLEMENTATION ARE CONTAINED IN THIS FILE:

1. INITIALIZATION AND UPDATING.
2. ESTIMATION OF THE PITCH PERIOD AND THE CORRELATION COEFFICIENT REQUIRED FOR PITCH REDUNDANCY REMOVAL (PRR).
3. PARC-TRANSMITTER.
4. PARC-RECEIVER.
5. DOUBLE-BUFFER (189*2) TO CIRCULAR-BUFFER (1024) TRANSFER PROGRAM. THIS IS USED TO SIMULATE THE FUNCTION OF THE IOS2.
6. THE SOURCE ENCODER PREPARES THE DIGITAL BIT STREAM BY ENCODING THE QUANTIZER LEVELS AND THE PRR SIDE INFORMATION PUT OUT BY THE PARC TRANSMITTER. IT USES A VARIABLE-LENGTH TO VARIABLE-LENGTH ENCODING SCHEME.
7. THE DECODER PERFORMS TWO FUNCTIONS. IT FIRST ACQUIRES FRAME SYNCHRONIZATION ON THE INCOMING BIT STREAM. IT THEN DECODES THE BIT STREAM TO THE QUANTIZER LEVELS AND THE PRR INFORMATION FOR USE BY THE PARC RECEIVER.

EJECT

```

PAGE      2:      MAP MODULES FOR THE P A R C ALGORITHM      --- JAN. 30, 1980

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*****
*
*      INITIALIZATION AND UPDATE FOR P A R C
*
*****

THIS MODULE CONTAINS 4 PROGRAMS: RCS, TXS INIS AND RCINIS

RCS: TO UPDATE THE ADDRESS POINTERS IN PARC-RECEIVER
TXS: TO UPDATE THE ADDRESS POINTERS IN PARC-TRANSMITTER
INIS: TO INITIALIZE THE PARAMETERS IN APS MODULES, ENCODER, DECODER
RCINIS: TO INITIALIZE THE POINTERS OF RECEIVER

SYMBOL DEFINITION TO INTERFACE WITH THE MAP-300 EXEC, VER. 3.5:

BCTSA=$582
FDTSUFCB=$8C4
ISVTS=$502
SVTS=$382
SYSSFLGS=$1FFC
MSKSRBYT=$00FF
FLS=$0001
ISVT1S=ISVTS+1
ISVT2S=ISVTS+2
ISVT3S=ISVTS+3
ISVT4S=ISVTS+4
ISVT5S=ISVTS+5
WRD4=3
WRD5=4

*****
*
*      DISPATCH TABLE ENTRIES
*
*****
FCB = 110
#L = FDTSUFCB+(FCB-110)*2

0004 0000000E (00074) FCB = 110
0005 000000C4 (00075) #L = FDTSUFCB+(FCB-110)*2
0006 00004FC2 (00076) ADDR ENCD$
0007 00005102 (00077) ADDR DCD$
0008 00005116 (00078) ADDR TRSDC
0009 00004000 (00079) ADDR RCS
000A 00004036 (00080) ADDR TXS
000B 0000405C (00081) ADDR INIS
000C 00004000 (00082) ADDR RCINIS
000D 00004000 (00083)
000E 00004000 (00084) #L = $4000
000F 00004000 (00085)

*****
*
*      SCALAR TABLE
*
*****
:SCALAR TABLE
:SYSTEM FLAG POSITION
:MASK OFF LEFT BYTE

```

PAGE 3: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1988

(000000) EJECT

PAGE 7: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1980

```

B483F F05405B3 (00206)      MOVHR      R5,ISVT1S(R2)
B4841 4A4A (00207)          ANDRR      R4,R5
B4842 E040A21 (00208)      MOVHR      R4,DASTX
B4844 F040A25 (00209)      MOVHR      R4,VHSTX
B4846 4C46 (00210)          ADDR      R4,R3
B4847 4A4A (00211)          ANDRR      R4,R5
B4848 E040A25 (00212)      MOVHR      R4,VHSTX
B484A F040A1D (00213)      MOVHR      R4,SSTX
B484C 4C46 (00214)          ADDR      R4,R3
B484D F061FFCE (00215)      MOVHR      R6,SYSSFLGS
B484F 5A6C0004 (00216)      ANDKR      R6,R6,S4
B4851 0010A958 (00217)      JMP          CONT2S,EQ
B4853 F00DFCE (00218)      MOVLM      S6,SYSSFLGS
B4855 F0640504 (00219)      MOVHR      R6,ISVT2S(R2)
B4857 4C4C (00220)          ADDR      R4,R6
B4858 4A4A (00221)          ANDRR      R4,R5
B4859 E040A1D (00222)      MOVHR      R4,SSTX
B485B 0E70 (00223)          RETURN
                                EVEN
                                EJECT
                                (00224)
                                (00225)
                                (00226)

```

```

;MASK FOR SAMPLE BUFFER
;
;OUTPUT TRANSFERING POINTER
;
;ADD N OF TX
;MASKING
;OUTPUT VBAT POINTER
;
;ADD N OF TX
;GET SYSTEM FLAG
;CHECK G2
;JUMP IF G2=0
;RESET G2
;GET PITCH REPETITION SIZE
;ADD PITCH REPETITION SIZE
;MASKING
;OUTPUT S POINTER

```

MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1988

PAC:

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 (00269) *
 (00270) *

INIS MODULE TO INITIALIZE APS PARAMETERS.

IT INITIALIZES THE FOLLOWING PARAMETERS:

PITCH REPETITION THRESHOLD, FILTER THRESHOLD, FILTERING SIZE, ISTART,
 CORRELATION SIZE, PITCH REPETITION SIZE, NSTX, SSTX, DASTX, VHSTX

INTEGER SCALAR SEQUENCE: PITCH REPETITION THRESHOLD, FILTER THRESHOLD,
 FILTER SIZE - 1, ISTART - 1, KBLK - 1, PITCH REPETITION SIZE

FCB FORMAT (16 BIT WORD FORMAT SHOWN)

WORD	LEFT BYTE	RIGHT BYTE
1	115	INTEGER SCALAR
2	B	B
3	B	B
4	B	B
5	B	B

MOVJK R2,R1,MSKSRBYT
 MOVHR R3,ISVTS(R2)
 ;GET INTEGER SCALAR
 ;PITCH REPETITION THRESHOLD

:NIS
 :OFF (00265)
 :2532 (00270)

```

PAGE      9:      MAP MODULES FOR THE P A R C ALGORITHM      --- JAN. 38, 1988

#4868 E0304A4F (#0271)      MOVHM      R3,INSGTH      ;WRITE PITCH REPETITION THRESHOLD
#4862 F0340503 (#0272)      MOVHM      R3,ISVT1S(R2)      ;FILTER THRESHOLD
#4864 E0304A57 (#0273)      MOVHM      R3,INSFTH      ;WRITE FILTER THRESHOLD
#4866 F0340504 (#0274)      MOVHM      R3,ISVT2S(R2)      ;FILTER SIZE - 1
#4868 E0304A68 (#0275)      MOVHM      R3,INSFBS      ;WRITE FILTER SIZE - 1
#486A F0340505 (#0276)      MOVHM      R3,ISVT3S(R2)      ;STARTING CORRELATION 0 - 1
#486C E0304A8F (#0277)      MOVHM      R3,INSCST      ;WRITE STARTING CORRELATION 0
#4870 F0340506 (#0278)      MOVHM      R3,ISVT4S(R2)      ;CORRELATION BLOCK SIZE - 1
#4872 E0304A9F (#0279)      MOVHM      R3,INSCSZ      ;WRITE CORRELATION BLOCK SIZE - 1
#4874 E0304AF1 (#0280)      MOVHM      R3,ISVT5S(R2)      ;PITCH REPETITION SIZE
#4876 E0304CB1 (#0281)      MOVHM      R3,INSGSZ      ;WRITE PITCH REPETITION SIZE
#4878 E0304F18 (#0282)      MOVHM      R3,INSTX      ;
#4879 E0304F1B (#0283)      DECR      R3,1      ;PITCH REPETITION SIZE - 1
#487B 4E36      MOVHM      R3,INSCR      ;
#487C E0304430 (#0284)      SUBRM      R3,R3      ;RESET R3
#487E E0304A21 (#0285)      MOVHM      R3,INSTX      ;
#487F E0304A25 (#0286)      MOVHM      R3,DASTX      ;
#4880 E0304A25 (#0287)      MOVHM      R3,VHSTX      ;
#4881 E0304A1D (#0288)      MOVHM      R3,SSSTX      ;
#4882 E0304A1D (#0289)      MOVHM      R3,SSSTX      ;
#4883 E0304A1D (#0290)      MOVHM      R3,SSSTX      ;
#4884 2611      INCR      R1,1      ;POINT TO RUN LENGTH
#4885 702200FF (#0291)      MOVVM      R2,R1,SFF      ;VALUE OF RUN LENGTH
#4886 E0205115 (#0292)      MOVVM      R2,LSRUN      ;INIT VAL FOR ENCD, DECD
#4887 0C20      CCR      R2      ;R2=1
#4888 E0205114 (#0293)      MOVVM      R2,VDEL      ;BIT CNT.=1, FOR ENCD
#4889 0D20      CLR      R2      ;R2=0
#488A E0205408 (#0294)      MOVVM      R2,PSBASE      ;BASE OF FRAME POINTER,DEC
#488B E0205408 (#0295)      MOVVM      R2,PSBASE      ;
#488C 0E70      RETURN      ;
#488D E0205408 (#0296)      EVEN      ;
#488E 0E70      EJECT      ;

```

--- INITIALIZATION FOR THE ENCODER AND DECODER

PAGE 18: MAP MODULES FOR THE P A R C ALGORITHM ---- JAN. 38, 1988

RCINIS MODULE TO INITIALIZE APS PARAMETERS OF RECEIVER.
 IT INITIALIZES THE FOLLOWING PARAMETERS:
 NSRC, VHSRC, SHSRC, DASRC AND G3
 INTEGER SCALAR SEQUENCE: STARTING LOCATION OF RECEIVER BUFFER
 TRANSFER BLOCK SIZE
 FCB FORMAT (16 BIT WORD FORMAT SHOWN)

WORD	LEFT BYTE	RIGHT BYTE
1	116	INTEGER SCALAR #
2	#	#
3	#	#
4	#	#
5	#	#

RCINIS
 MOVWK R2,R1,MSKSRBYT
 MOVMR R3,ISVTS(R2)
 MOVRM R3,VHSRC
 RCINIS
 GET INTEGER SCALAR #
 STARTING LOCATION OF RECEIVER BUF
 REACT

(00305) *
 (00306) *
 (00307) *
 (00308) *
 (00309) *
 (00310) *
 (00311) *
 (00312) *
 (00313) *
 (00314) *
 (00315) *
 (00316) *
 (00317) *
 (00318) *
 (00319) *
 (00320) *
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 (00348) *

04898 702200FF (00346) RCINIS
 04892 F0340502 (00347)
 04894 E0304F2D (00348)

PAGE 11: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1980

04896 00304FF (00349)	MOVW	R3, SHSRC	
04898 0040504 (00350)	MOVW	R4, ISVT2S(R2)	
0489A 4E38 (00351)	SUBW	R3, R4	
0489B 00304ED3 (00352)	MOVW	R3, DASRC	
0489D 00FFFC (00353)	MOVL	\$7, SYSSFLGS	
0489F 4E36 (00354)	SUBW	R3, R3	
048A1 0030466 (00355)	MOVW	R3, NSRC	
048A2 0E70 (00356)	RETURN		
048A3 0000 (00357)	EVEN		
000048A4 (00358)			
000048A4 (00359)	CONIS = 0L		
000048A4 (00360)			
000048A4 (00361)	EJECT		

TRANSFER SIZE
RESET G3

PAGE 12:

MAP MODULES FOR THE P A R C ALGORITHM

--- JAN. 30, 1980

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(00364) *
(00365) *
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*****
*
*      ADAPTIVE FILTERS AND
*      PITCH PERIOD AND CORRELATION CALCULATION
*
*****
IT USES V3.5 MAP-EXECUTIVE

* DESCRIPTION:
THIS PROGRAM CALCULATES THE PITCH PERIOD AND CORRELATION COEFFICIENT
OF A BLOCK SAMPLES. ALSO, DEPENDING ON THE CONDITION OF THE SAMPLE
BUFFER IN TRANSMITTER, IT WILL EMPLOY ADAPTIVE FILTER AND/OR PITCH
REPETITION.

* THIS PROGRAM EMPLOYS THE FOLLOWING BUFFERS:

1. ADAM BUFFER: ADAM SAMPLES INPUT ANALOG SIGNALS AND PUTS THE
CORRESPONDING QUANTIZED DIGITAL SIGNALS INTO THIS BUFFER.
--- DOUBLE BUFFERING --- SHORT FLOATING FORMAT ---
2. SAMPLE BUFFER: THE INPUT DATA COME FROM ADAM BUFFER. THE PURPOSE
OF THIS BUFFER IS TO PROVIDE BUFFER CONTROL TECHNIQUE.
--- CIRCULAR BUFFER --- SHORT FLOATING FORMAT ---
3. WHAT BUFFER: THIS BUFFER CONTAINS RECONSTRUCTED REDUCED SPEECH
SAMPLES FROM RARC-TRANSMITTER. ( THIS PROGRAM ONLY DEFINES THE
STARTING LOCATION OF WHAT POINTER.)

* SYMBOLIC DEFINITIONS:

TBLK: TRANSFERING BLOCK SIZE FROM ADAM BUFFER TO SAMPLE BUFFER
FBLK: FILTERING BLOCK SIZE
KBLK: CORRELATION BLOCK SIZE
IEND: UPPER LIMIT OF PITCH PERIOD
SSTX: DATA POINTER IN SAMPLE BUFFER FOR USING IN PARC-TRANSMITTER
DASTX: DATA POINTER IN SAMPLE BUFFER FOR THE TRANSFER FROM ADAM
      BUFFER
VHSTX: WHAT POINTER IN WHAT BUFFER
INSGTH: LOCATION OF PITCH REPETITION THRESHOLD
INSFTH: LOCATION OF FILTER THRESHOLD
INSFBS: LOCATION OF FBLK-1
INSCST: LOCATION OF LOWER LIMIT OF PITCH PERIOD
INSCSZ: LOCATION OF CORRELATION BLOCK SIZE -1
INSGSZ: LOCATION OF PITCH REPETITION SIZE

```

PAGE 13: MAP MODULE FOR THE P A R C ALGORITHM --- JAN. 38, 1988

* RESTRICTIONS:

1. TBLK SHOULD BE MULTIPLE OF 2. THIS RESTRICTION CAN BE REMOVED IF THOSE STATEMENTS MARKED **A** ARE SLIGHTLY MODIFIED. THE PURPOSE OF THIS RESTRICTION IS TO REDUCE THE DATA TRANSFERING TIME.
2. IT IS ASSUMED THAT DASTX NEVER OVERRIDES SSTX. THAT IS CONTROLLED BY 3. BY PITCH REPETITION THRESHOLD AND SIZE.
3. KBLK SHOULD BE MULTIPLE OF 4.
4. THE ABSOLUTE VALUES OF UPPER LIMIT AND LOWER LIMIT OF CORRELATION COEFFICIENT SHOULD BE THE SAME.
5. THE SEQUENCE OF INPUT SCALARS ARE AS FOLLOWS:
TBLK/2-A.B.FBLF-B.5.KBLK-B.5.SEARCHING SIZE-B.5.2*-15,
IEND-B.5.B.8881,1START,LB,UB,HL/(UB*2**15),HL/(UB*2**24),
2**24*UB/HL
6. THE LOCATIONS OF ARRAYS ARE AS FOLLOWS:
SAMPLE BUFFER: B(3) ... 1823(3)
WHAT BUFFER: B(2) ... 1823(2) --- THE SIZE AND STARTING LOCATION OF THIS BUFFER CAN BE CHANGED BY SLIGHTLY MODIFICATIONS IN TRANSMITTER PROGRAMS.

* CALL THIS FUNCTION:

MAP = PICH3(SA,U)
WHERE SA --- SCALAR * FOR PITCH PERIOD
U --- BUFFER * FOR ADAM BUFFER

CONTAINS FOR ASSEMBLY

```

MSS=B
DHYS=$794
BUSIS=$8881
TOESPRT=$288
CSPUSNOS=$21FC
AFDTS=$8E8

SVT588=SVTS+188
SVT518=SVT588+2
SVT548=SVT518+6
SVT568=SVT548+4
SVT638=SVT568+18
SVT688=SVT638+18
SVT788=SVT688+4
SVT748=SVT788+8

DUMMY OUTPUT SPACE
:BUS 1
:TOP OF EXEC.
:LOCATION OF NO-CSPU SUPPORT
:STARTING ADDRESS OF AFDT

:SCALAR TABLE 58

:ADD TWO SCALAR

```


PAGE 16: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 38, 1988

```

A1C 848DE 888888EE (88538)
A1D 848EB 84588448 (88539)
A1E 848E2 88288888 (88540)
      (88541) *
      (88542) *
      (88543) *
      (88544) *
      (88545) *
      (88546) *
      (88547) *
      (88548) *
      (88549) *
      (88550) *
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      (88564) *
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      (88576) *
      (88577) *
      (88578) *
      (88579) *
      (88580) *
      (88581) *

A1F 848E4 88818881 (88541)
A20 848E6 88EE8888 (88542)
A21 848E8 88588888 (88543)
A22 848EA 84588448 (88544)
A23 848EC 41888888 (88545)
A24 848EE 88888888 (88546)
A25 848F0 4F888888 (88547)
A26 848F2 88888888 (88548)
A27 848F4 8892889C (88549)
A28 848F6 881E881F (88550)
      (88551) *
      (88552) *
      (88553) *
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      (88571) *
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      (88576) *
      (88577) *
      (88578) *
      (88579) *
      (88580) *
      (88581) *

A29 848F8 88038888 (88551)
A2A 848FA 88F88888 (88552)
A2B 848FC 28242824 (88553)
A2C 848FE 8888888F (88554)
A2D 848FF 88168816 (88555)
      (88556) *
      (88557) *
      (88558) *
      (88559) *
      (88560) *
      (88561) *
      (88562) *
      (88563) *
      (88564) *
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      (88566) *
      (88567) *
      (88568) *
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      (88575) *
      (88576) *
      (88577) *
      (88578) *
      (88579) *
      (88580) *
      (88581) *

      M6=SF(K-1)
      M6=SF(K-1)

      MOV(P,A1)
      MOV(IA,M6) \ NOP
      MOV(EX1,A8) \ MOV(IA,M6)
      MOV(EXO),MUL(M8,M6) \ MUL(M8,M6)
      ADD(A8,A1) \ MOV(EX1,EXO)
      MOV(R,EXO) \ NOP
      SUB(A2,A7) \ MOV(EX1,A8)
      NOP \ SUB(A8,A1)
      MOV(R,A2) \ MOV(R,00)
      JUMPC(LOOP1,T1)

      INITIALIZATION FOR SEARCHING PITCH PERIOD
      REGISTERS TO BE USED LATER:
      ADM1: A3,A6,EXO
      ADM2: A4,A6

      INPUT SEQUENCE: KBLK/4,SEARCHING SIZE - 8.5
      FLAGS AFFECTED: G8
      MOV(IQ,A3) \ NOP
      MOV(IA,EXO) \ NOP
      CLEAR(G8)
      NOP \ MOV(IA,A4)
      MOV(ZERO,A6)
      FIND T
      REGISTERS AFFECTED:
      ADM1: A8,A1,A2,A3,A5,A6
      ADM2: A8,A1,A2,A4,A5,A6
      INPUT SEQUENCE: S(J-T),S(J),S(J),S(J-T),S(J-T),S(J),S(J)
      FLAGS AFFECTED: AF8,AF1,AF3

```

```

(00582) *
(00583) *
A2E 04902 20492049
A2F 04904 20482040
A30 04906 00F10000 LOOP6
A31 04908 000000F1 (00587)
A32 0490A 00F00000 (00588)
A33 0490C 000000F0 (00589)
(00590) *
A34 0490E 49004900
A35 04910 12851285 (00592)
A36 04912 00F10000 (00593)
A37 04914 000000F1 (00594)
A38 04916 46854685 (00595)
A39 04918 00F00000 (00596)
A3A 0491A 000000F0 (00597)
(00598) *
A3B 0491C 49164916 (00599)
A3C 0491E 12851285 (00600)
A3D 04920 00F10000 (00601)
A3E 04922 000000F1 (00602)
A3F 04924 46854685 (00603)
A40 04926 00F00000 (00604)
A41 04928 000000F0 (00605)
A42 0492A 4F760896 (00606)
A43 0492C 00930898 (00607)
A44 0492E 901E0034 (00608)
(00609) *
A45 04930 00554F00 (00610)
A46 04932 46A00850 (00611)
A47 04934 9009004E (00612)
(00613) *
A48 04936 20292029 (00614)
A49 04938 00530894 (00615)
A4A 0493A 00920892 (00616)
A4B 0493C 00150815 (00617)
A4C 0493E 00160816 (00618)
A4D 04940 1000002F (00619)
(00620) *
A4E 04942 4E560000 (00621)
A4F 04944 00530000 (00622)
A50 04946 00160815 (00623)
A51 04948 00000894 (00624)
A52 0494A 911E0050 (00625)

; FIRST SEARCHING
; SIGNAL APS TO PRODUCE DATA
; A1=S(J-T)
; AB=S(J)
;
; R=S(J)-S(J-T)
; R=ABS(S(J)-S(J-T))
;
; A6=SUM3
;
; R=S(J)-S(J-T)
;
; R=SUM3
; R=SEARCHING SIZE-1
; EXO=KBLK/4
;
; A3=KBLK/4
; A2=IEND-B.5-T
;
; R=SMALL-SUM3
; A3=KBLK/4
;
; ----
; A4=SEARCHING SIZE-1

```


PAGE 19: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 38, 1988

```

A6F B4984 B8964596 (B8678)
A7B B4986 B8CFB88B (B8671)
A71 B4988 B8E9B88B (B8672)
A72 B498A 4F74B894 (B8673)
A73 B498C B888B8CF (B8674)
A74 B498E B888B8E9 (B8675)
A75 B499B B885B885 (B8676)
A76 B4992 B893B898 (B8677)
A77 B4994 9B1EB88B (B8678)
      (B8679) *
      (B8680) *
      (B8681) *
      (B8682) *
      (B8683) *
      (B8684) *
      (B8685) *
      (B8686) *
      (B8687) *
      (B8688) *
      (B8689) *
      (B8690) *
      (B8691) *
A78 B4996 B85B88EA (B8692)
A79 B4998 4AB8B8F4 (B8693)
A7A B499A B8F14A8B (B8694)
A7B B499C B888B8E7 (B8695)
A7C B499E B888B8F9 (B8696)
A7D B49AB B888B88E (B8697)
A7E B49A2 B888B854B (B8698)
A7F B49A4 B88F88F7 (B8699)
A8B B49A6 4C34B884 (B8700)
A81 B49AB B8F73A8B (B8701)
A82 B49AA B888B89C (B8702)
A83 B49AC 9B1EB88B (B8703)
      (B8704) *
A94 B49AE 2E8B888B (B8705)
A85 B498B 46A846AB (B8706)
A86 B4982 846B888B (B8707)
A87 B4984 168B888B (B8708)
A88 B4986 B888B885B (B8709)
A89 B4988 48314616 (B8710)
A8A B498A B88E888A (B8711)
A8B B498C 844B889B (B8712)
A8C B498E B84AB88B (B8713)
A8D B49CB B888B88B (B8714)

MOV(A6),ADD(A4,A6)
MOV(IQ,M7) \ NOP
MOV(IQ,M1) \ NOP
MOV(A4),SUB(A3,A7) \ MOV(R,A4)
NOP \ MOV(IQ,M7)
NOP \ MOV(IQ,M1)
MOV(P,A5)
MOV(R,A3) \ MOV(R,EXO)
JUMPC(LOOP9,T1)

OUTPUT BETA AND T

REGISTERS TO BE USED:

ADM1: A6,A1,A4,A7,M6,M2,M5,M7,EXO
ADM2: A6,A2,A4,A6,A7,M2,M6,EXO

INPUT SEQUENCE: 1/2**15,IEND-B.5,B.88B1,1START,LOWER BETA LIMIT,
UPPER BETA LIMIT
OUTPUT SEQUENCE: T(IN INTEGER)

MOV(EXT,A6) \ MOV(IQ,M2)
ADD(A6,A4) \ MOV(IQ,A4)
MOV(IQ,A1) \ SUB(A4,A2)
NOP \ MOV(IQ,A7)
NOP \ MOV(A4),SUB(A4,A7)
NOP \ MOV(R,M6)
NOP \ MUL(M2,M6)
MOV(R,M7) \ MOV(IQ,A7)
MOV(A4),SUB(A1,A4) \ MOV(P,A4)
MOV(IQ,A7) \ ALIGN(A4)
MOV(R,NULL) \ MOV(R,OO)
JUMPC(RESET,T1)

RCP(A4) \ NOP
MOV(MB),ADD(A5,A6) \ ADD(A5,A6) \ MB=FB
MUL(MB,M7) \ NOP
MOV(EXO),K(2) \ NOP
MOV(P,A6) \ MOV(EXT,A6)
MOV(A1),SUB(A1,A6) \ MOV(A6),ADD(A6,A6) \ R=2-A6
MOV(R,M6) \ MOV(R,M2)
MUL(MB,M6) \ MOV(R,EXO)
MOV(EXT,M2) \ NOP
MOV(P,EXO) \ NOP

M2=1./(2.**15)
A4=IEND-B.5
A7=1START
ENCODE T
M6=T
A7=LOWER BETA

R=SUM1
A6=SUM1
R=SUM1
M2=SUM1
EXO=SUM1

```



```

PAGE 21:      MAP MODULES FOR THE P A R C ALGORITHM      --- JAN. 30, 1980

      00000000 (00750) PICH3SSZ-0A-PICH3SSA
      04A06    (00759)      END
              (00760)      *
              (00761)      EJECT
              (00761)
      ! COMPUTE THE SIZE OF THE MODULE

```



```

PAGE 23:          AP MODULES FOR THE P A R C ALGORITHM      --- JAN. 30, 1980

A15 04A30 2A210039 (00006)
A16 04A3A 2CA10001 (00007)
A17 04A3C 2E0A0001 (00008)
A18 04A3E 30210039 (00009)
A19 04A40 32A10001 (00010)
A1A 04A42 34200004 (00011)
A1B 04A44 362020F8 (00012)
A1C 04A46 380A0001 (00013)
A1D 04A48 3A210039 (00014)
A1E 04A4A 3CA10001 (00015)
A1F 04A4C 3E201C01 (00016)
      (00017) *
      (00018) *
      (00019) *
      (00020) *
      (00021) *
      (00022) *
      (00023) *
      (00024) *
      (00025) *
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      (00048) *
      (00049) *

      VLOOP3
      VLOOP4

      ADDL(BV2,1)
      AND8(BV2,BW,TF)
      ADD(BR3,1,TF)
      ADDL(BV2,1)
      AND8(BV2,BW,TF)
      SUBL(BR2,4),JUMPP(VLOOP2)
      ADDL(BR2,3),JUMPN(CKP)
      ADD(BR3,1,TF)
      ADDL(BV2,1)
      AND8(BV2,BW,TF)
      SUBL(BR2,1),JUMPP(VLOOP4)

      CHECK ADAPTIVITY (INCLUDING FILTERING AND PITCH REPETITION)

      REGISTERS PERMANENTLY USED BY THIS PROGRAM:

      BV2=THE POINTER FOR ADAM OUTPUT ADDRESS
      BV1=THE POINTER FOR PARC INPUT ADDRESS

      REGISTERS AFFECTED: BR0,BR2,BR3
      FLAGS AFFECTED: G2,AF1

      INSGTH=0L+1
      LOAD(BR3,650)
      MOV8(BR2,BV2)
      SUB8(BR2,BV1),JUMPP(CONT1)
      ADD(BR2,1024)
      INSGTH=0L+1
      LOAD(BR0,500)
      SUB8(BR2,BR3),JUMPN(NEXT1)
      SET(G2)
      ADD8(BR2,BR3)
      SUB8(BR2,BR0),JUMPN(NOFTR)
      SET(AF1)

      INITIALIZE PITCH REPETITION THRESHOLD
      PITCH REPETITION THRESHOLD

      **
      INITIALIZE FILTER THRESHOLD
      NO FILTER THRESHOLD
      IF < 0 -> PITCH REPETITION
      -> PITCH REPETITION
      IF > 0 -> NO FILTER IS EMPLOYED
      SIGNAL APU --- FILTERING

      FILTER

      REGISTERS AFFECTED: BR0,BR2,BR3,BW0

      LOAD(BR0,SVT510),L,TF)
      MOV8(BR2,BV1,TF)
      ADD(BR0,2,TF)

      A20 04A62 54C203E0 (00047)
      A21 04A64 56A90012 (00048)
      A22 04A66 580A0002 (00049)

```

PAGE 24: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1980

```

A20 04A60 5A9A0002 (00050)
      0000A60 (00051)
A21 04A6A 5C40004F (00052)
      0000A6A (00053)
A22 04A6C 5E7003FF (00054)
      0000A6C (00055)
A23 04A6E 60010015 (00056)
      0000A6E (00057)
A24 04A70 622A0001 (00058)
      0000A70 (00059)
A25 04A72 64A90007 (00060)
      0000A72 (00061)
A26 04A74 66220001 (00062)
      0000A74 (00063)
A27 04A76 68A90007 (00064)
      0000A76 (00065)
A28 04A78 6A2A0002 (00066)
      0000A78 (00067)
A29 04A7A 6C900007 (00068)
      0000A7A (00069)
A30 04A7C 6E220001 (00070)
      0000A7C (00071)
A31 04A7E 70A90007 (00072)
      0000A7E (00073)
A32 04A80 72010039 (00074)
      0000A80 (00075)
A33 04A82 74010007 (00076)
      0000A82 (00077)
A34 04A84 76093501 (00078)
      0000A84 (00079)
A35 04A86 78003C00 (00080)
      0000A86 (00081)
A36 04A88 7A300024 (00082)
      0000A88 (00083)
A37 04A8A 7CC203EE (00084)
      0000A8A (00085)
A38 04A8C 7E9A0002 (00086)
      0000A8C (00087)
A39 04A8E 8000A00F (00088)
      0000A8E (00089)
A40 04A90 80400013 (00090)
      0000A90 (00091)
A41 04A92 82010011 (00092)
      0000A92 (00093)
A42 04A94 84310011 (00094)
      0000A94 (00095)
A43 04A96 860000FE (00096)
      0000A96 (00097)
A44 04A98 88000000 (00098)
      0000A98 (00099)
A45 04A9A 8A000000 (00100)
      0000A9A (00101)
A46 04A9C 8C000000 (00102)
      0000A9C (00103)

      ADD(BR0,2,TF)
      INSB=0L+1
      LOAD(BR0,79)
      LOAD(BR3,1023)
      MOV(BV0,BR2)
      ADD(BR2,1)
      AND(BR2,BR3,TF)
      SUB(BR2,1)
      AND(BR2,BR3,TF)
      ADD(BR2,2)
      AND(BR2,BR3,TF)
      SUB(BR2,1)
      AND(BR2,BR3,TF)
      ADDL(BV0,1)
      AND(BV0,BR3,TF)
      SUBL(BR0,1),JUMPP(VLOOP1)
      JUMP(NOFR+1)

      PITCH PERIOD AND CORRELATION COEFFICIENT CALCULATIONS

      REGISTERS AFFECTED: BR0,BV0,BV3

      FLAGS AFFECTED: G0

      SET(G0)
      LOAD(BR0,SVTS4S(1),L,TF)
      ADD(BR0,2,TF)
      INSCST=0L+1
      LOAD(BR0,19)
      MOV(BV0,BR0)
      MOV(BV3,BR0)

      SEARCHING T

      REGISTERS AFFECTED: BR0,BR2,BR3,BV0

      FLAGS AFFECTED: AF0,AF3
      FLAGS SENSED: AF0,AF2,AF3

      JUMPS(FINISH,AF2)
      JUMPS(RECORD,AF3)
      JUMPC(IN4,AF0)
      CLEAR(AF0)

      FILTERING BLOCK
      ;INI. FILT. BLK. SIZE
      ;FILTERING SIZE
      ;MASK**
      ;SF(K-1) POINTER
      ;S(K)
      ;SF(K-1)
      ;S(K)
      ;SF(K-1)
      ;S(K)
      ;SF(K)
      ;LOOPING

      ; SIGNAL APU --- NO FILTERING
      ;KBLK/4
      ;CORRELATION SIZE
      ;INI. LOWER LIMIT OF T
      ;STARTING 0 OF CORRELATION
      ;INI VALUE OF T

      ;JUMP IF FINISH PITCH PERIOD SEARCHING
      ;RECORD T
      ;WAIT FOR SIGNAL

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PAGE 27: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1980

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(00974) *
(00975) *
(00976) *
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(01017) *

```

PITCH EXTRACTION ADAPTIVE RESIDUAL CODER
P A R C

IT USES V3.5 MAP-EXECUTIVE

* DESCRIPTION:

THIS IS A SPEECH CODING PROGRAM IN MAP-300 ARITHMETIC PROCESSOR FOR DIGITAL TRANSMISSION OF SPEECH AT A RATE OF 9600 BITS PER SECOND. THE ALGORITHM COMBINES PITCH EXTRACTION LOOP, PITCH COMPENSATING ADAPTIVE QUANTIZER, SEQUENTIALLY ADAPTIVE PREDICTOR.

1. THE REDUNDANCY OF SPEECH IS REMOVED IN THE PITCH EXTRACTION LOOP BLOCK BY BLOCK.
2. THE SEQUENTIALLY ADAPTIVE PREDICTOR USING BACKWARD ADAPTION IS USED TO FORM AN ESTIMATE OF PITCH REDUCED SIGNAL.
3. THE ERROR IN THIS ESTIMATE IS NORMALIZED AND QUANTIZED BY THE PITCH COMPENSATING ADAPTIVE QUANTIZER.
4. IF PITCH REPETITION MODE HAPPENS, A BLOCK OF SHAT IS DUPLICATED.

* SYMBOLIC ABBREVIATIONS:

INSTX LOCATION OF PITCH REPETITION SIZE IN APS MODULE

* BUFFERS:

1. SAMPLE BUFFER: IT CONTAINS INPUT SPEECH SAMPLES AND FILTERED INPUT SPEECH SAMPLES.
--- CIRCULAR BUFFER --- SHORT REAL FORMAT ---
2. WHAT BUFFER: IT CONTAINS RECONSTRUCTED REDUCED SPEECH SAMPLES.
--- CIRCULAR BUFFER --- SHORT REAL FORMAT ---
3. SHAT BUFFER: IT CONTAINS RECONSTRUCTED SPEECH SAMPLES.
--- CIRCULAR BUFFER --- SHORT REAL FORMAT ---
4. Q BUFFER: IT CONTAINS OUTPUT QUANTIZING LEVELS.
--- DOUBLE BUFFERS --- INTEGER * 2 FORMAT ---
5. PARAMETER BUFFER: IT CONTAINS PARAMETERS FOR QUANTIZER INCLUDING A(8),(T(J),OUT(J),EXP(N(J),B(J)) (IN SEQUENCE)

* RESTRICTION:

PAGE 28: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 38, 1988

1. THE ORDER OF THE PREDICTOR IS 4.
 2. THE LOCATIONS OF SOME ARRAYS ARE AS FOLLOWS:
 SAMPLE BUFFER: B(3) ... 1023(3)
 WHAT BUFFER: B(2) ... 1023(2)
 SHAT BUFFER: 1024(3) ... 2047(3)
 PARAMETER BUFFER: 3072(2) ...
 3. THE SEQUENCE OF INPUT SCALARS ARE AS FOLLOWS:
 BITCOUNT, BIT BUFFER SIZE, RMS, STATE VARIABLE, RUN LENGTH,
 PHONY BETA BITS, GAP SIZE, RMSMIN, N-2.5, 1-ALP, ALP, SWIN,
 G, NQ, RUN LENGTH, COMPANSATOR, 2*-14, AINV*(1/ALAD-1),
 ALAD, N-2.5, NULL BITS, 1/2*15, NSTX, ENCD, T, ENCD, BETA,
 BETA, ENCD, T, ENCD, BETA, BETA

* TO CALL THIS FUNCTION:

MAP = PCTX(SA,U)
 WHERE SA --- THE SCALAR LOCATION FOR BETA
 U --- THE BUFFER # FOR OUTPUT QUANTIZING LEVELS

DISPATCH TABLE ENTRY

FCB242=242
 #L=AFDTS*3+2*(FCB242-128)
 ADDR PCTXS(R7,1)
 ADDR VPCTXS(R7,1)
 ADDR CSPUSNOS(1,1,B)
 APU & APS MODULE
 #L=CON25
 APU MODULE
 EVEN PCTXSSA
 DATA PCTXSSZ
 DATA PCTXSSZ
 BEGIN APU(PCTX)
 #M=3
 #A=0
 INITIALIZATION

FCB=242
 ; STARTING LOCATION OF AFDT FOR 242
 ; APU=PCTX
 ; APS=VPCTX
 ; NO CPU SUPPORT

; START ON WORD BOUNDARY
 ; STARTING ADDRESS
 ; SIZE
 ; START OF APU MODULE

000000F2 (01018) *
 00000094 (01019) *
 00000094 (01020) *
 00000094 (01021) *
 00000094 (01022) *
 00000094 (01023) *
 00000094 (01024) *
 00000094 (01025) *
 00000094 (01026) *
 00000094 (01027) *
 00000094 (01028) *
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 00000094 (01054) *
 00000094 (01055) *
 00000094 (01056) *
 00000094 (01057) *
 00000094 (01058) *
 00000094 (01059) *
 00000094 (01060) *
 00000094 (01061) *

PAGE 38: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 38, 1988

```

A08 0480A 00F10AEB (B1106)
A09 0480C 49400000 (B1107)
A10 0480E 000000F6 (B1108)
A11 0480E 000000F6 (B1109)
A12 0480E 000000F6 (B1110)
A13 0480E 000000F6 (B1111)
A14 0480E 000000F6 (B1112)
A15 0480E 000000F6 (B1113)
A16 0480E 000000F6 (B1114)
A17 0480E 000000F6 (B1115)
A18 0480E 000000F6 (B1116)
A19 0480E 000000F6 (B1117)
A20 0480E 000000F6 (B1118)
A21 0480E 000000F6 (B1119)
A22 0480E 000000F6 (B1120)
A23 0480E 000000F6 (B1121)
A24 0480E 000000F6 (B1122)
A25 0480E 000000F6 (B1123)
A26 0480E 000000F6 (B1124)
A27 0480E 000000F6 (B1125)
A28 0480E 000000F6 (B1126)
A29 0480E 000000F6 (B1127)
A30 0480E 000000F6 (B1128)
A31 0480E 000000F6 (B1129)
A32 0480E 000000F6 (B1130)
A33 0480E 000000F6 (B1131)
A34 0480E 000000F6 (B1132)
A35 0480E 000000F6 (B1133)
A36 0480E 000000F6 (B1134)
A37 0480E 000000F6 (B1135)
A38 0480E 000000F6 (B1136)
A39 0480E 000000F6 (B1137)
A40 0480E 000000F6 (B1138)
A41 0480E 000000F6 (B1139)
A42 0480E 000000F6 (B1140)
A43 0480E 000000F6 (B1141)
A44 0480E 000000F6 (B1142)
A45 0480E 000000F6 (B1143)
A46 0480E 000000F6 (B1144)
A47 0480E 000000F6 (B1145)
A48 0480E 000000F6 (B1146)
A49 0480E 000000F6 (B1147)
A50 0480E 000000F6 (B1148)
A51 0480E 000000F6 (B1149)

MOV(1QA,A1) \ NEG(A7)
SUB(A2,A1) \ NOP
NOP \ MOV(1QA,A6)
MOV(R,A2) \ MOV(R,OQ)
MOV(1QA,OQ) \ SUB(A6,A7)
NOP \ MOV(R,A6)
JUMPC(GAP1,T2)
JUMP(PRE3)

PREDICTOR

REGISTERS USED:
ADM1: A7
ADM2: A2,A5

REGISTERS AFFECTED:
ADM1: A1,A5,A7,M2,M7
ADM2: A1,A2,A3,A6,M5,M1,M6,M7,EXO

FLAGS AFFECTED: AF,B,GI

INPUT SEQUENCE: RMSMIN,N-2.5.1-ALP,ALP,A(I),VHAT(K-I)

FUNCTIONS: P(K) = SUM(A(I) * VHAT(K-I))
          RMS = ALP*(RMS-RMSMIN) + (1-ALP)*ABS(VHAT(K-I)) + RMSMIN
          RMS ** 2

MOV(1QA,A1) \ MOV(1QA,A6)
SET(AFB)
K(1) \ MOV(1QA,A6)
NOP \ MOV(1QA,A3)
NOP \ MOV(1QA,M6)
MOV(A1),SUB(A7,A1) \ MOV(1QA,M6)

MOV(1QA,M2) \ NOP
MOV(1QA,M7) \ NOP
MUL(M2,M7) \ MOV(1QA,A1)
MOV(ZERO,A5) \ ABS(A1)
MOV(R,A7) \ NOP
JUMPC(QCKP,T1)
SET(GI)
NOP \ MOV(R,M7)

MOV(1QA,M2) \ NEG(A7)
M7=VHAT(K-1)
P1=A(1)*VHAT(K-1)
A5=B.
DECRE. Q COUNTER

SIGNAL Q-LIMIT REACHED
M7=ABS(VHAT(K-1))

```


PAGE 32: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1980

```

A30 0486A 08314831 (01194)
A39 0486C 080E080E (01195)
A3A 0486E 054084C0 (01196)
A3B 04870 300000AF (01197)
A3C 04872 300000AF (01198)
      (01199) *
      (01200) *
      (01201) *
      (01202) *
      (01203) *
      (01204) *
      (01205) *
      (01206) *
      (01207) *
      (01208) *
      (01209) *
      (01210) *
      (01211) *
      (01212) *
      (01213) *
      (01214) *
      (01215) *
      (01216)
A3D 04874 080E0800 (01217)
A3E 04876 080E0800 (01218)
A3F 04878 04EE4780 (01219)
A40 0487A 16000800 (01220)
A41 0487C 08000800 (01221)
A42 0487E 08F408F1 (01222)
A43 04880 08000800 (01223)
A44 04882 08F00800 (01224)
A45 04884 08F10800 (01225)
A46 04886 08060800 (01226)
A47 04888 4E290894 (01227)
A48 0488A 080E0800 (01228)
      (01229) *
      (01230) *
      (01231) *
      (01232) *
      (01233) *
      (01234) *
      (01235) *
      (01236) *
      (01237) *

MOV(A1),SUB(A1,A3) \ MOV(A1),SUB(A1,A3) \ R=2-P1
MOV(R,M6) \ MOV(R,M6) \ M6=2-P1
MUL(M2,M6) \ MUL(M1,M6) \ P=FB*(2-P1)
CALL(RCP1) \ CALL SUBROUTINE RCP1
CALL(RCP1)

CALCULATE REDUCED SPEECH

REGISTERS USED:
ADM1:
ADM2: A4,A7

REGISTERS AFFECTED:
ADM1: A0,A1,A4,A6,M1,M5,M6,M7
ADM2: A1,A4,A6,M0,M4,M7

INPUT SEQUENCE: SHAT(K-T),BETA,SMIN,G,NQ,RUNCOUNT,COMPANSATION,S(K),1/2

FUNCTIONS: V(K) = S(K) - BETA * SHAT(K-T)
          SAMPLE COUNT = SAMPLE COUNT + 1

MOV(IGA,M7) \ NOP \ M7=SHAT(K-T)
MOV(IGA,M1) \ NOP \ M1=BETA
MOV(M6),MUL(M1,M7) \ ADD(A4,A7) \ M6=1/2*SIZE
K(1) \ MOV(IGA,M0) \
NOP \ MOV(IGA,M7) \
MOV(IGA,A4) \ MOV(IGA,A1) \
NOP \ MOV(IGA,A6) \
MOV(IGA,A0) \ NOP \ A0=COMPANSATION
MOV(P,A6) \ MOV(R,M4) \ A1=S(K)
MOV(M1),SUB(A1,A6) \ MOV(R,A4) \ A6=BETA*SHAT(K-T)
MOV(IGA,M5) \ NOP \ M5=1/2*14

M0=SMIN
M7=G
A1=NQ
A6=RUNLENGTH

QUANTIZER

REGISTERS USED:
ADM1: A0,A2,A4,A5,M1,M5,M6
ADM2: A1,A2,A5,A6,A7,M0,M7

REGISTERS AFFECTED:
ADM1: A1,A2,A3,A4,M1,M2,M7,EXO

```



```

A5C 04002 00004F20 (01282)
A5D 04004 00000200 (01293)
A5E 04006 00510000 (01284)
A5F 04008 00000000 (01285)
A60 0400A 91040007 (01286)
      (01287) *
      (01288) *
      (01289) *
A61 0400C 004A00E9 (01290)
A62 0400E 00EF008E (01291)
A63 0400F 056004CF (01292)
A64 04010 00000300 (01293)
A65 04012 00530051 (01294)
A66 04014 00400000 (01295)
A67 04016 45600320 (01296)
A68 04018 00500000 (01297)
A69 0401A 00930049 (01298)
      (01299) *
A6A 0401C 009C0000 (01300)
A6B 0401E 00000075 (01301)
A6C 04020 490002C0 (01302)
A6D 04022 20202020 (01303)
A6E 04024 00A00000 (01304)
A6F 04026 00090000 (01305)
A70 04028 04A00000 (01306)
A71 0402A 00840000 (01307)
A72 0402C 3A000000 (01308)
A73 0402E 009C0000 (01309)
A74 04030 10000070 (01310)
A75 04032 00840000 (01311)
A76 04034 3A000000 (01312)
A77 04036 009C0000 (01313)
A78 04038 001F0070 (01314)
A79 0403A 420002C0 (01315)
A7A 0403C 00920000 (01316)
A7B 0403E 00F10000 (01317)
A7C 04040 49A00000 (01318)
A7D 04042 00920000 (01319)
A7E 04044 001E0000 (01320)
A7F 04046 20002040 (01321)
      (01322) *
      (01323) *
      (01324) *
      (01325) *

      NOP \ SUB(A1,A7)
      MOV \ MOV(EXO),R(A5)
      MOV(EXT,A1) \ NOP
      MOV \ MOV(R,EXO)
      JUMPS(NEGA,GB)
      ERROR >= B
      MOV(EXT,M2) \ MOV(IGA,M1)
      MOV(IGA,M7) \ MOV(R,M6)
      MUL(M2,M7) \ MOV(M7),MUL(M1,M6)
      MOV(P,EXO) \ MOV(P,EXO)
      MOV(EXT,A3) \ MOV(EXT,A1)
      MUL(M1,M5) \ NOP
      ADD(A3,A5) \ MAX(A1,A3)
      MOV(EXT,EXO) \ MOV(R,A5)
      MOV(R,A3) \ MOV(EXT,M1)
      MOV(R,OQ) \ NOP
      JUMPC(QUAN4,AF3)
      SUB(A4,A1) \ R(A6)
      CLEAR(AF3)
      MOV(P,NULL) \ NOP
      MOV(R,M1) \ NOP
      MUL(M1,M5) \ NOP
      MOV(P,A4) \ NOP
      ALIGN(A4) \ NOP
      MOV(R,OQ) \ MOV(R,A0)
      JUMP(QUAN5)
      MOV(P,A4) \ SUB(A0,A7)
      ALIGN(A4) \ NOP
      MOV(R,OQ) \ MOV(R,A0)
      JUMPC(QUAN5,T2)
      ADD(A0,A2) \ R(A6)
      MOV(R,A2) \ MOV(R,A0)
      MOV(IGA,A1) \ NOP
      SUB(A2,A1) \ NOP
      MOV(R,A2) \ NOP
      JUMPC(ADAP1,T1)
      SET(AF3)
      ADAPTATION
      REGISTERS USED:

      M1=OUT(J)
      M6=STATE VARIABLE(SI)
      M7=P1 P=OUT(J)=SIZE
      EXO=OUT(J)=SIZE
      A1=SIZE=EXP(J)
      P=1/2**14
      OUT(J)=SIZE+PRE
      EXO=+-OUT(J)=SIZE
      A3=VHAT(K)
      OUTPUT VHAT(K)
      JUMP IF Q(L)=1
      CALCULATE L
      CLEAR AF3
      M1=L
      READY TO ALIGN
      OUTPUT L
      A0=RUNCOUNT
      OUTPUT L=1
      DECREMENT A0
      A6=RUNLENGTH
      A0=RUNCOUNT
      JUMP IF NO ENOUGH FOR RUN LENGTH
      COMPASATING
      A1=B(K)
      UPDATE BITCOUNT
      JUMP IF BITCOUNT > B
      SIGNAL END OF PARC

```

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(01326) *
(01327) *
(01328) *
(01329) *
(01330) *
(01331) *
(01332) *
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(01336) *
(01337) *
(01338) *
(01339) *
(01340) *
(01341) *
(01342) *
(01343) *
(01344) *
(01345) *
(01346) *
(01347) ADAP1
(01348)
(01349)
(01350)
(01351) *
(01352)
(01353)
(01354)
(01355)
(01356)
(01357)
(01358)
(01359)
(01360)
(01361)
(01362)
(01363)
(01364)
(01365)
(01366)
(01367) ADAP2
(01368)
(01369)

ADM1: A3,A6
ADM2: A7,M1,M7

REGISTERS AFFECTED:

ADM1: A0,A1,A4,A5,A6,M1,M2,M6
ADM2: A3,M1,M6,M7,EXO

INPUT SEQUENCE: AINV*(1/ALAD-1),ALAD,N-2.5,NULL BITS,
OUTPUT SEQUENCE: SHAT(K-1),A(1),VHAT(K-1)

FLAGS AFFECTED: GB

FUNCTIONS: ERR = G * EHAT(K) / (RMS ** 2)
          A(1) = (A(1) + AINV*(1/ALAD-1)) * ALAD + VHAT(K-1)*ERR
          SHAT(K) = VHAT(K) + BETA*SHAT(K-1)
          OUTPUT SHAT(K) AND A(1)
          A(1) = A(1)*ALAD + VHAT(K-1)*ERR
          OUTPUT A(1)

MOV(IGA,A4) \ NOP
MOV(IGA,M6) \ NOP
NOP \ MOV(IGA,A3)
MOV(IGA,A0) \ NOP

MOV(IGA,A5) \ MUL(M1,M7)
ADD(A5,A4) \ NOP
MOV(M2),ADD(A3,A6) \ MOV(P,M1)
MUL(M2,M6) \ MOV(IGA,M7)
MOV(IGA,M1) \ MUL(M1,M7)
MOV(R,00) \ NOP
MOV(A1),MUL(M1,M6) \ MOV(P,EXO)
MOV(EXT,A6) \ MOV(IGA,M6)
ADD(A6,A1) \ MUL(M1,M6)
CLEAR(G0)
MOV(R,00) \ NOP
MOV(P,A1) \ MOV(P,EXO)
MOV(EXT,A6) \ NOP
ADD(A6,A1) \ NOP
MOV(R,00) \ NOP
MOV(IGA,M1) \ NOP
MUL(M1,M6) \ MOV(IGA,M7)
NOP \ MUL(M1,M7)

;A4=AINV*(1/ALAD-1)
;M6=ALAD
A3=N-2.5
;A0=NULL BIT
;A5=A(1)
;A(1)+A4
;M2=R1
;P2=ALAD*A1
;M1=A(2)
;OUTPUT SHAT(K)
;A1=P2
;A6=VHAT(K-1)*ERR
;R=NEW A(1)
;OUTPUT A(1)
;A1=ALAD*A(2)
;A6=VHAT(K-2)*ERR
;R=NEW A(2)
;OUTPUT A(2)
;M1=A(1)
;P=A(1)*ALAD
M7=VHAT(K-1)
P=VHAT(K-1)*ERR

P1=G*EQ/RMS**2
M1=P1
M7=VHAT(K-1)
P3=VHAT(K-1)*P1
EXO=P3
M6=VHAT(K-2)
P=VHAT(K-2)*ERR
EXO=VHAT(K-2)*ERR
M7=VHAT(K-1)
P=VHAT(K-1)*ERR

```

```

A96 0AC26 00010000 (01370)
A97 0AC20 0056AF60 (01371)
A98 0AC2A 41C00000 (01372)
A99 0AC2C 009C0000 (01373)
A9A 0AC2E 901F0000 (01374)
A9B 0AC30 00000000 (01375)
      (01376)
      (01377)
      (01378)
      (01379)
      (01380)
A9C 0AC32 910000A2 (01381)
A9D 0AC34 90050011 (01382)
      (01383)
      (01384)
      (01385)
      (01386)
      (01387)
      (01388)
      (01389)
      (01390)
      (01391)
      (01392)
      (01393)
      (01394)
      (01395)
      (01396)
      (01397)
      (01398)
      (01399)
      (01400)
      (01401)
      (01402)
      (01403)
A9E 0AC36 00400000 (01404)
A9F 0AC38 00920000 (01405)
AA0 0AC3A 911E00A2 (01406)
AA1 0AC3C 00120000 (01407)
AA2 0AC3E 00000000 (01408)
AA3 0AC40 00000000 (01409)
AA4 0AC42 02400A00 (01410)
AA5 0AC44 0000025C (01411)
AA6 0AC46 009C0000 (01412)
AA7 0AC48 00C20000 (01413)

MOV(P,A1) \ MOV(P,EXO)
MOV(EXT,A6) \ SUB(A3,A7)
ADD(A6,A1) \ NOP
MOV(R,00) \ MOV(R,A3)
JUMPC(ADAP2,T2)
NOP
END OF PROCESSING ?
FLAGS SENSED: G1,AF3
JUMPS(FEND,AF3)
JUMPC(PRE3,G1)
NULL MODE
REGISTERS USED:
ADM1: A0,A2
ADM2: A2,A5,A7,M4
REGISTERS AFFECTED:
ADM1: A2
ADM2: M3,EXO
FLAGS AFFECTED: G1,AF3,RA
INPUT SEQUENCE: 1/2**15
OUTPUT SEQUENCE: END CODE,BIT COUNT,RMS,STATE VARIABLE, OF SAMPLES
FUNCTIONS: IF MORE THAN TWO NULL CODES, SET BIT COUNT = 0
            OTHERWISE UPDATE BITCOUNT
            OUTPUT END CODE, BITCOUNT, RMS, SIZE AND SAMPLE COUNTER

SUB(A2,A0) \ NOP
MOV(R,A2) \ NOP
JUMPS(FEND,T1)
MOV(ZERO,A2) \ NOP
NOP \ MOV(IQA,M3)
NOP \ MUL(M3,M4)
R(A2) \ NEG(A7)
NOP \ MOV(OQ),R(A2)
MOV(R,00) \ MOV(P,EXO)
MOV(EXT,A2) \ MOV(OQ),R(A5)

;A1=A(I)*ALAD
;A6=VHAT(K-1)*ALAD
;R=NEW A(I)
;OUTPUT NEW A(I)
;END ?

;JUMP IF BITCOUNT < 0
;JUMP IF NOT RUN OUT OF SAMPLE

;UPDATE BITCOUNT
;
;JUMP IF BITCOUNT < 0
;RESET BITCOUNT TO SYNC. TRANSMISSIONS
;M3=1./(2.**15)
;
;
;OUTPUT END CODE
;OUTPUT BITCOUNT
;OUTPUT RMS

```

NOTRE DAME UNIV IN DEPT OF ELECTRICAL ENGINEERING
DESIGN AND IMPLEMENTATION OF A SPEECH CODING ALGORI
APR 80 J L MELSA, D L COHN, A ARORA OCA

THM AT 9600 --ETC(U)

APR 80 J L MELSA, D L COHN, A ARORA

DCA100-79-C-0005

ML

3 of 3

AD
A088534

END
DATE
FILMED
8-80
DTIC


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(01448) *
(01449) *
(01450) *
(01451)
(01452)
(01453)
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(01458) *
(01459) *
(01460) *
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(01484)
(01485)
(01486)
(01487)
(01488)
(01489) *
(01490) *
(01491) *

B4C7C 00004082
B4C7E 0000ACF4
B4C80 0001
B4C81 0100
B4C82 0000AC92

APS MODULE OF PCTX PROGRAM

EVEN
ADDR VPCTXSI
DATA VPCTXS+2*VPCTXS
DATA 1
DATA VPCTXSZ
ADDR VPCTXSA
EVEN

;START ON WORD BOUNDARY
;PTR TO CONSTR INSTR BLOCK
;STARTING ADDR. OF SCALARS
;ONE SCALAR
;SIZE
;CHAIN ANCHOR

THE FOLLOWING REGISTERS ARE PERMANENTLY USED BY THIS PROGRAM

BR1: ADDRESS OF VHAT(K)
BR2: ADDRESS OF S(K-1)
BR3: ADDRESS OF SHAT(K-T-1)
BV0: 1023
BV1: ADDRESS OF SHAT(K-1)
BV2: SD(K+N-1)
BV3: QUANTIZER OUTPUT ADDRESS - 1

INITIALIZATION

REGISTERS AFFECTED: BR0,BR2,BV3

INPUT SEQUENCE: BIT COUNT, BIT BUFFER SIZE, RMS, SIZE, RUN LENGTH,
PITCH REPETITION SIZE

SET(RA)

LOAD(BR0,SVT63S(1),L,TF)
ADD(BR0,2,TF)
ADD(BR0,2,TF)
ADD(BR0,2,TF)
ADD(BR0,2,TF)
LOAD(BR0,SVT118S(1),L,TF)
LOAD(BR0,[1])
SUB(BR2,MSS)
SUB(BR0,MSS)
MOVB(BV3,BR0)

;BITCOUNT
;BIT BUFFER SIZE
;RMS
;STATE VARIABLE
;RUN LENGTH
;O-BUFFER LIMIT
;O BUFFER

;
;ADDRESS POINTER OF Q BUFFER - 1

CHECK PITCH REPETITION

```


PAGE 41: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1980

```

A47 #4012 9E004CEA (#1500)
A48 #4014 900046A8 (#1501)
A49 #4016 92200028 (#1502)
A4A #4018 940A000A (#1503)
A4B #401A 96004660 (#1504)
A4C #401C 980A000A (#1505)
A4D #401E 9A20002A (#1506)
A4E #4020 9C005160 (#1507)
A4F #4022 9E0A0002 (#1508)
A50 #4024 A0200029 (#1509)
A51 #4026 A20A0002 (#1500)
A52 #4028 A40055E4 (#1591)
A53 #402A A60A0002 (#1592)
A54 #402C A8005660 (#1593)
A55 #402E AA0A0004 (#1594)
A56 #4030 AC110013 (#1595)
A57 #4032 AE910000 (#1596)
A58 #4034 B1310039 (#1597)
A59 #4036 B2C20426 (#1603)
A5A #4038 B48A0002 (#1604)
A5B #403A B68A0002 (#1605)
A5C #403C B88A0002 (#1606)
A5D #403E BA120001 (#1607)
A5E #4040 BC4A0C00 (#1608)
A5F #4042 BE990000 (#1609)
A60 #4044 C0120001 (#1610)
A61 #4046 C20A0002 (#1611)
A62 #4048 C40E0400 (#1612)
A63 #404A C6090020 (#1613)
A64 #404C C8100011 (#1614)
A65 #404E CA990000 (#1615)
A66 #4050 CC120001 (#1616)
A67 #4052 CE4A0C00 (#1617)
A68 #4054 D0910011 (#1618)
A69 #4056 D291003A (#1619)
A6A #4058 D4C40C04 (#1620)
A6B #405A D6990000 (#1621)
A6C #405C D891003A (#1622)
A6D #405E DA120001 (#1623)

JUMPS(VQUAN2,AF2)
JUMPC(VQUAN1,AF0)
CLEAR(AFB)
ADD(BR0,10,TF)
JUMP(VQUAN1)
ADD(BR0,10,TF)
CLEAR(AF2)
JUMP(SHIFT)
ADD(BR0,2,TF)
CLEAR(AF1)
ADD(BR0,2,TF)
JUMPS(VNEGA,GB)
ADD(BR0,2,TF)
JUMP(VNEGA+1)
ADD(BR0,4,TF)
MOV8(BV1,BR1)
ANDB(BV1,BV0,TF)
ADDL(BV3,1,TE)

ADAPTION

REGISTERS AFFECTED: BR0,BR1,BV1

LOAD(BR0,SVT79S(1),L,TF)
ADD(BR0,2,TF)
ADD(BR0,2,TF)
ADD(BR0,2,TF)
SUB(BR1,1)
LOAD(BR0,3072(2),L,TF)
ANDB(BR1,BV0,TF)
SUB(BR1,1)
ADD(BR0,2,TF)
LOAD(BR0,1024(3),S)
ADD(BR0,BR2)
MOV8(BV1,BR0,TF)
ANDB(BR1,BV0,TF)
SUB(BR1,1)
LOAD(BR0,3072(2),L)
MOV8(BV1,BR0,TF)
ADDL(BV1,2,TF)
LOAD(BR0,3076(2),L,TF)
ANDB(BR1,BV0,TF)
ADDL(BV1,2,TF)
SUB(BR1,1)

;ERROR > ALL T(K)
;WAIT FOR SIGNAL
;SEND T(K)
;SEND OUT(J)
;OUT(J)
;EXPN(J)
;B(K)
;VHAT(K) ADDRESS
;L ADDRESS

;AINV*(1/ALAD-1) **
;ALAD
;N-2.5
;NULL BITS
;GET ADDRESS POINTER FOR VHAT BUFFER
;STARTING ADDRESS OF A(I) **

;SHAT(K) ADDRESS
;VHAT(K-2) ADDRESS
;A(1) ADDRESS
;A(2) ADDRESS

```



```

(01667) *
(01668) *
(01669) *
(01670) *
(01671) *
(01672) *
(01673) *
(01674) *
(01675) *
(01676) *
(01677) *
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(01697) *
(01698) *
(01699) *
(01700) *
(01701) *
(01702) *
(01703) *
(01704) *
(01705) *
(01706) *
(01707) *
(01708) *
(01709) *
(01710) *

```

PITCH EXTRACTION ADAPTIVE RESIDUAL CODER

P A R C
RECEIVER

* DESCRIPTION:

THIS IS A SPEECH CODING PROGRAM IN MAP-300 ARITHMETIC PROCESSOR FOR DIGITAL TRANSMISSION OF SPEECH AT A RATE OF 9600 BITS PER SECOND. THE ALGORITHM COMBINES PITCH EXTRACTION LOOP, PITCH COMPENSATING ADAPTIVE QUANTIZER, SEQUENTIALLY ADAPTIVE PREDICTOR.

1. THE SEQUENTIALLY ADAPTIVE PREDICTOR USING BACKWARD ADAPTION IS USED TO FORM AN ESTIMATE OF PITCH REDUCED SIGNAL.
2. THE ERROR OF THIS ESTIMATE IS RECONSTRUCTED BY INVERSE QUANTIZER.
3. THE REDUNDANCE OF THE CURRENT SAMPLE IS CALCULATED BY PITCH EXTRACTION LOOP.
4. THE RECONSTRUCTED SPEECH IS THE SUM OF THIS ERROR, THE ESTIMATE AND THE REDUNDANCE.

* SYMBOLIC ABBREVIATIONS:

SHSRC --- THE LOCATION OF SHAT POINTER
TSRC --- THE LOCATION OF PITCH PERIOD FOR RECEIVER
VHSRC --- THE LOCATION OF VBAT POINTER
INSRC --- THE LOCATION OF (PITCH REPETITION SIZE - 1)

* BUFFERS:

1. Q BUFFER: IT CONTAINS INPUT QUANTIZING LEVELS.
2. --- IN 16-BIT INTEGER*2 FORMAT --- DOUBLE BUFFERS ---
VHAT BUFFER: IT CONTAINS RECONSTRUCTED REDUCED SPEECH.
3. --- CIRCULAR BUFFER --- IN SHORT-REAL FORMAT ---
SHAT BUFFER: IT CONTAINS RECONSTRUCTED SPEECH.
4. --- CIRCULAR BUFFER --- IN SHORT-REAL FORMAT ---
ADM BUFFER: IT CONTAINS UPSAMPLED SHAT DATA.
5. --- DOUBLE BUFFER --- SHORT REAL FORMAT ---
PARAMETER BUFFER: IT CONTAINS THE PARAMETERS FOR INVERSE QUANTIZER.

SEQUENCE : A(8),(ENPN(J),OUT(J)) --- IN LONG-REAL FORMAT ---

* RESTRICTION:

1. THE ORDER OF THE PREDICTOR IS 4.
2. INITIALLY, THE SHAT BUFFER SHOULD BE IN FULL CONDITION.
3. THE LOCATIONS OF SOME ARRAYS ARE AS FOLLOWS:

SHAT BUFFER --- 2048(2) ... 3071(2)
 VBAT BUFFER --- 2048(3) ... 3071(3)
 AOM BUFFER --- 3584(2)-4095(2)
 PARAMETER BUFFER --- 4096(2) ...
 WHERE QUANTIZER LEVELS ARE DEFINED AS FOLLOWS:
 FROM LOWEST TO HIGHEST
 Q(N),Q(N-1),...,Q(N/2+2),Q(1),Q(2),...,Q(N/2+1)

* CALL TO THIS FUNCTION:

MAP = PCRC(SA,U,V)
 WHERE SA --- SCALAR LOCATION OF ENCD. BETA
 U --- BUFFER # FOR INPUT Q BUFFER
 V --- AOM BUFFER #

DISPATCH TABLE ENTRY

FCB243=243
 #L=AFDTs*3*2*(FCB243-128)
 ADDR PCRCs(R7,1)
 ADDR VPCRCs(R7,1)
 ADDR CSPUSNOS(1,0)
 APU & APS MODULE
 #L=CON3S
 APU MODULE
 EVEN PCRCSSA
 DATA PCRCSSZ
 BEGIN APU(PCRC)
 #M=3
 #A=0

:START ON WORD BOUNDARY
 :STARTING ADDRESS
 :SIZE
 :START OF APU MODULE

(01711) *
 (01712) *
 (01713) *
 (01714) *
 (01715) *
 (01716) *
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 (01751) *
 (01752) *
 (01753) *
 (01754) *

000000F3
 00000089A

0009A 001E4D86
 0009C 001E4EC2
 0009E 001021FC

00004D84

04D84 0000
 04D85 009A

00000003
 00000000

```

PAGE 45: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1980

(01755) *
(01756) *
(01757) *
(01758) *
(01759) *
(01760) *
(01761) *
(01762) *
(01763) *
(01764) PCRCSSA K(0.5)
A00 04D86 16601600 MOV(10A,A5) \ NOP
A01 04D88 08F50000 MOV(10A,A6) \ NOP
A02 04D8A 08F60000 MOV(MI),K(1)
A03 04D8C 16891600 MOV(10A,A2) \ NOP
A04 04D8E 08F20000 MOV(10A,A7) \ NOP
A05 04D90 08F00000 MOV(A7),MIN(A5,A6) \ MOV(R,A7)
A06 04D92 6D170000 MOV(A7),MAX(A5,A6) \ MOV(R,A7)
A07 04D94 66100000 MOV(10A,A1) \ NOP
A08 04D96 08F10000 MIN(A1,A5) \ NOP
A09 04D98 6D200000 MOV(A1),MAX(A1,A6) \ NOP
A10 04D9A 66310000 MOV(R,EX0) \ NOP
A11 04D9C 08980000 MOV(A1),ADD(A5,A1) \ NOP
A12 04D9E 41110000 MOV(R,M7) \ MOV(EX1,EX0)
A13 04DA0 84E00000 MUL(MI,M7) \ NOP
A14 04DA2 4F400000 SUB(A2,A7) \ NOP
A15 04DA4 08500000 MOV(EX1,A5) \ NOP
A16 04DA6 08500000 MOV(P,00) \ NOP
A17 04DA8 088C0000 MOV(R,A2) \ MOV(EX1,00)
A18 04DAA 08920000 JUMPC(TRAN,T1)
A19 04DAC 901E0000

INITIALIZATION
(01785) *
(01786) *
(01787) *
(01788) *
(01789) *
(01790) *
(01791) *
(01792) *
(01793) *
(01794) *
(01795) *
(01796) *
(01797) *
(01798) *

REGISTERS AFFECTED:
ADM1: A0,A1,A2,M0,M1,M3,M5,M6,M7
ADM2: A0,A2,A3,A4,A6,A7,M0,M2,M6

INPUT SEQUENCE: ENCD,BETA,RMS,STATE VARIABLE,UB*2**15/HL,RMSMIN,N-2.5
ALAD,SMIN,UB,G,1-ALP,ALP,AINV*(1/ALAD-1),2**14,PITCH REP

ADM1 *****
ADM2 *****
ADM1 *****
ADM2 *****

MOV(10A,A1) \ NOP
;A1=ENCD. BETA

DATA TRANSFER FROM SHAT BUFFER TO ADM BUFFER

REGISTERS USED:
ADM1: A0,A1,A2,A5,A6,A7,M1,M7,EX0
ADM2: A0,A1,A7,M1,M7,EX0

INPUT SEQUENCE: 2047/16**3,-2048/16**3,TRANSFER SIZE/2-0.5,SHAT(K-1),SHA
OUTPUT SEQUENCE: (SHAT(K-1)*SHAT(K))/2,SHAT(K)

;A5=2047/(16**3)
;A6=-2048/(16**3)
;A2=TRANSFER SIZE/2-0.5
;SHAT(K-1)
;LIMITING
;LIMITING

;LOOPING

```

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(01711) *
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(01744) *
(01745) *
(01746) *
(01747) *
(01748) *
(01749) *
(01750) *
(01751) *
(01752) *
(01753) *
(01754) *

      * RESTRICTION:
      1. THE ORDER OF THE PREDICTOR IS 4.
      2. INITIALLY, THE SHAT BUFFER SHOULD BE IN FULL CONDITION.
      3. THE LOCATIONS OF SOME ARRAYS ARE AS FOLLOWS:
          SHAT BUFFER --- 2048(2) ... 3071(2)
          VBAT BUFFER --- 2048(3) ... 3071(3)
          AOM BUFFER --- 3584(2)-4095(2)
          PARAMETER BUFFER --- 4096(2) ...
          WHERE QUANTIZER LEVELS ARE DEFINED AS FOLLOWS:
          FROM LOWEST ..... TO ..... HIGHEST
          Q(N),Q(N-1),...,Q(N/2+2),Q(1),Q(2),...,Q(N/2+1)

      * CALL TO THIS FUNCTION:
          MAP = PCRC(SA,U,V)
          WHERE SA --- SCALAR LOCATION OF ENCD. BETA
                U --- BUFFER # FOR INPUT Q BUFFER
                V --- AOM BUFFER #

DISPATCH TABLE ENTRY
FCB243=243
#L=AFDTS+3*2*(FCB243-128)
ADDR PCRC(R7,1)
ADDR VPCRC(R7,1)
ADDR CSPUSNOS(1,8)
APU & APS MODULE
#L=CON3S
APU MODULE
EVEN PCRCSSA
DATA PCRCSSZ
DATA PCRCSSZ
BEGIN APU(PCRC)
#N=3
#A=0
PCRC
(01751) PCRC
(01752)
(01753)
(01754)

      * START ON WORD BOUNDARY
      * STARTING ADDRESS
      * SIZE
      * START OF APU MODULE
  
```


PAGE 49: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 38, 1988

```

A6D 84E68 8588888C (81931)
A6E 84E62 88888894 (81932) *
      (81933) *
      (81934) *
      (81935) *
      (81936) *
      (81937) *
      (81938) *
      (81939) *
      (81940) *
      (81941) *
      (81942) *
      (81943) *
      (81944)
A6F 84E64 88F58849 (81944)
A7B 84E66 88A88888 (81945)
A71 84E68 888A8888 (81946)
A72 84E6A 852888EF (81947)
A73 84E6C 88818888 (81948)
A74 84E6E 88EA84E8 (81949)
A75 84E78 88818888 (81950)
A76 84E72 885388ED (81951)
A77 84E74 416888A8 (81952)
A78 84E76 889C8888 (81953)
A79 84E78 88818888 (81954)
A7A 84E7A 88538828 (81955)
A7B 84E7C 41688888 (81956)
A7C 84E7E 889C8893 (81957)
      ADAP
A7D 84E88 88EA8888 (81958)
A7E 84E82 852888EF (81959)
A7F 84E84 8888884E (81960)
A8B 84E86 88818888 (81961)
A81 84E88 88534F68 (81962)
A82 84E8A 41688888 (81963)
A83 84E8C 889C8893 (81964)
A84 84E8E 881F887D (81965) *
      (81966) *
      (81967) *
      (81968) *
      (81969) *
      (81970) *
      (81971) *
      (81972) *
      (81973) *
A85 84E98 888888F5 (81974) CKEND

      MOV(M2,M4) \ MOV(R,M4)
      MOV(P,EXO) \ MOV(R,A4)
      ADAPTATION
      REGISTERS AFFECTED:
      ADM1: A1,A3,A5,M2
      ADM2: A3,M1,M5,M7,EXO
      INPUT SEQUENCE: A(1), VHAT(K-1)
      OUTPUT SEQUENCE: A(1)
      MOV(IQA,A5) \ MOV(EXI,M1)
      ADD(A5,A8) \ NOP
      MOV(R,M2) \ NOP
      MUL(M2,M5) \ MOV(IQA,M7)
      MOV(P,A1) \ NOP
      MOV(IQA,M2) \ MUL(M1,M7)
      MUL(M2,M5) \ MOV(P,EXO)
      MOV(EXI,A3) \ MOV(IQA,M5)
      ADD(A3,A1) \ MUL(M1,M5)
      MOV(R,OQ) \ NOP
      MOV(P,A1) \ MOV(P,EXO)
      MOV(EXI,A3) \ R(A8)
      ADD(A3,A1) \ NOP
      MOV(R,OQ) \ MOV(R,A3)
      MOV(IQA,M2) \ NOP
      MUL(M2,M5) \ MOV(IQA,M7)
      NOP \ MUL(M1,M7)
      MOV(P,A1) \ MOV(P,EXO)
      MOV(EXI,A3) \ SUB(A3,A7)
      ADD(A3,A1) \ NOP
      MOV(R,OQ) \ MOV(R,A3)
      JUMPC(ADAP,T2)
      CHECK END OF RECEIVER
      REGISTERS AFFECTED:
      ADM1:
      ADM2: A5
      NOP \ MOV(IQA,A5)
      A5=L

```

```

      A5=A(1)
      R1=A(1)+ANIV*8.88787
      M2=R1
      P2=ALAD*R1
      M1=A(2)
      P3=VHAT(K-1)*P1
      EXO=P3
      M5=VHAT(K-2)
      P=VHAT(K-2)*ERR
      ----
      EXO=VHAT(K-2)*ERR
      R=N-2.5
      A3=N-2.5
      M7=VHAT(K-1)
      P=VHAT(K-1)*ERR
      EXO=VHAT(K-1)*ERR
      COUNTER=COUNTER-1
      ----
      A1=A(1)*ALAD
      A3=VHAT(K-1)*ALAD
      R=NEW A(1)
      OUTPUT NEW A(1)
      END ?

```



```

PAGE 53: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1980

A2A 04F16 540034E9 (02102) *
A2B 04F18 56002AA7 (02103) *
A2C 04F1A 58000038 (02104) *
A2D 04F1C 5A3A0001 (02105) *
A2E 04F1E 5C310039 (02106) *
A2F 04F20 5E390000 (02107) *
A30 04F22 6000002A (02108) *
A31 04F24 62310000 (02109) *
A32 04F26 6401002A (02110) *
A33 04F28 66002D81 (02111) *
A34 04F2A 68000029 (02112) *
A35 04F2C 6A5E0000 (02113) *
A36 04F2E 6C007060 (02114) *
A37 04F30 6EC41000 (02115) *
A38 04F32 70200028 (02116) *
A39 04F34 72100001 (02117) *
A3A 04F36 74190000 (02118) *
A3B 04F38 7600002A (02119) *
A3C 04F3A 78120001 (02120) *
A3D 04F3C 7A0A0002 (02121) *
A3E 04F3E 7C190000 (02122) *
A3F 04F40 7E00002A (02123) *
A40 04F42 80120001 (02124) *
A41 04F44 820A0002 (02125) *
A42 04F46 84190000 (02126) *

; JUMP IF NO PITCH REPETITION
; WAIT FOR APU SIGNAL
; INIT PITCH REPETITION SIZE
; PITCH REPETITION SIZE
;
; SHAT(K-T)
; SHAT(K)
; LOOPING

; JUMPS(COUNT,AF1)
; JUMPC(BWAIT,G3)
; INSRC-0L+1
; LOAD(BR0,59)
; ADD(BR3,1)
; ADDL(BW3,1)
; AND8(BR3,BW0)
; ADD8(BR3,BW1,TF)
; AND8(BW3,BW0)
; ADD8(BW3,BW1,TF)
; SUBL(BR0,1),JUMPP(VLOP1)

INITIALIZATION

REGISTERS AFFECTED: BR1

FLAGS AFFECTED: AF1

CLEAR(AF1)
VHSRC-0L+1
LOAD(BR1,2048(3),S)
JUMP(ENDCK)

PRODUCING ADDRESSES FOR PREDICTOR WITH CIRCULAR BUFFER

REGISTERS AFFECTED: BR0,BR1

FLAGS AFFECTED: AF0

LOAD(BR0,4096(2),L,TF)
CLEAR(AF0)
SUB(BR1,1)
AND8(BR1,BW0)
ADD8(BR1,BW1,TF)
SUB(BR1,1)
ADD(BR0,2,TF)
AND8(BR1,BW0)
ADD8(BR1,BW1,TF)
SUB(BR1,1)
ADD(BR0,2,TF)
AND8(BR1,BW0)

```

PAGE 54: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1980

```

A43 04F48 0699002A (02146)
A44 04F4A 00120001 (02147)
A45 04F4C 00A00002 (02148)
A46 04F4E 0C190000 (02149)
A47 04F50 0E99002A (02150)
A48 04F52 001A0004 (02151)
A49 04F54 02190000 (02152)
A4A 04F56 0419002A (02153)
      (02154) *
      (02155) *
      (02156) *
      (02157) *
      (02158) *
      (02159) *
      (02160) *
      (02161) *
      (02162) *
      (02163) *
      (02164) *
      (02165) *
      (02166) *
      (02167) *
      (02168) *
      (02169) *
      (02170) *
      (02171) *
      (02172) *
      (02173) *
      (02174) *
      (02175) *
      (02176) *
      (02177) *
      (02178) *
      (02179) *
      (02180) *
      (02181) *
      (02182) *
      (02183) *
      (02184) *
      (02185) *
      (02186) *
      (02187) *
      (02188) *
      (02189) *

A48 04F50 0644100A (02164)
A4C 04F5A 000001E9 (02165)
A4D 04F5C 0A004C08 (02166)
A4E 04F5E 0C200020 (02167)
A4F 04F60 0E0A0004 (02168)
A50 04F62 00004C60 (02169)
A51 04F64 020A0002 (02170)
A52 04F66 04200029 (02171)
A53 04F68 060A0002 (02172)
      (02173) *
      (02174) *
      (02175) *
      (02176) *
      (02177) *
      (02178) *
      (02179) *
      (02180) *
      (02181) *
      (02182) *
      (02183) *
      (02184) *
      (02185) *
      (02186) *
      (02187) *
      (02188) *
      (02189) *

A54 04F6A 003A0001 (02178)
A55 04F6C 0A390000 (02179)
A56 04F6E 0C09002A (02180)
A57 04F70 0E010013 (02181)
A58 04F72 00310039 (02182)
A59 04F74 02310000 (02183)
A5A 04F76 0401002A (02184)
      (02185) *
      (02186) *
      (02187) *
      (02188) *
      (02189) *

      ADD(BR1,BV1,TF)
      SUB(BR1,1)
      ADD(BR0,2,TF)
      AND(BR1,BV0)
      ADD(BR1,BV1,TF)
      ADD(BR1,4)
      AND(BR1,BV0)
      AND(BR1,BV1)

      PRODUCING ADDRESSES FOR QUANTIZER

      CONTROLLED BY HANDSHAKE SIGNAL (AF0,AF1) FROM APU PROGRAM

      REGISTERS AFFECTED: BR0

      FLAGS AFFECTED: AF0,AF1
      FLAGS SENSED: AF0,AF1

      LOAD(BR0,4106(2),L)
      JUMPS(VQ3,AF1)
      JUMPC(VQ1,AF0)
      CLEAR(AF0)
      ADD(BR0,4)
      JUMP(VQ1)
      ADD(BR0,2,TF)
      CLEAR(AF1)
      ADD(BR0,2,TF)

      ADDRESSES OF SHAT(K-T),VHAT(K),SHAT(K)

      REGISTERS AFFECTED: BR3,BV2,BV3

      ADD(BR3,1)
      AND(BR3,BV0)
      ADD(BR3,BV1,TF)
      MOV(BV2,BR1,TF)
      ADDL(BV3,1)
      AND(BV3,BV0)
      ADD(BV3,BV1,TF)

      ADAPTION

      USING CIRCULAR BUFFER

      ;ADDRESS OF EXPN(1) -6
      ;FIND CORRESPONDING QUANTIZING LEVEL
      ;WAIT FOR SIGNAL
      ;
      ;EXPN(3)
      ;OUT(3)
      ;SHAT(K-T)
      ;VHAT(K)
      ;
      ;SHAT(K)

```

PAGE 55: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1980

```

A58 04F70 06C41000 (02190) *
A59 04F71 06C41001 (02191) *
A60 04F72 06C41002 (02192) *
A61 04F73 06C41003 (02193) *
A62 04F74 06C41004 (02194) *
A63 04F75 06C41005 (02195) *
A64 04F76 06C41006 (02196) *
A65 04F77 06C41007 (02197) *
A66 04F78 06C41008 (02198) *
A67 04F79 06C41009 (02199) *
A68 04F80 06C41010 (02200) *
A69 04F81 06C41011 (02201) *
A70 04F82 06C41012 (02202) *
A71 04F83 06C41013 (02203) *
A72 04F84 06C41014 (02204) *
A73 04F85 06C41015 (02205) *
A74 04F86 06C41016 (02206) *
A75 04F87 06C41017 (02207) *
A76 04F88 06C41018 (02208) *
A77 04F89 06C41019 (02209) *
A78 04F90 06C41020 (02210) *
A79 04F91 06C41021 (02211) *
A80 04F92 06C41022 (02212) *
A81 04F93 06C41023 (02213) *
A82 04F94 06C41024 (02214) *
A83 04F95 06C41025 (02215) *
A84 04F96 06C41026 (02216) *
A85 04F97 06C41027 (02217) *
A86 04F98 06C41028 (02218) *
A87 04F99 06C41029 (02219) *
A88 04FA0 06C41030 (02220) *
A89 04FA1 06C41031 (02221) *
A90 04FA2 06C41032 (02222) *
A91 04FA3 06C41033 (02223) *
A92 04FA4 06C41034 (02224) *
A93 04FA5 06C41035 (02225) *
A94 04FA6 06C41036 (02226) *
A95 04FA7 06C41037 (02227) *
A96 04FA8 06C41038 (02228) *
A97 04FA9 06C41039 (02229) *
A98 04FAA 06C41040 (02230) *
A99 04FAB 06C41041 (02231) *
A00 04FAC 06C41042 (02232) *
A01 04FAE 06C41043 (02233) *

; STARTING ADDRESS OF A(1)
; OUTPUT A(1)
; INPUT L
; JUMP IF NOT FINISH
; WAIT FOR APU SIGNAL

REGISTERS AFFECTED: BR0,BR1,BV2
LOAD(BR0,4096(2),L,TF)
SUB(BR1,1)
ANDB(BR1,BV0)
ADDR(BR1,BV1,TF)
MOVB(BV2,BR0,TF)
SUB(BR1,1)
ADD(BR0,2,TF)
ANDB(BR1,BV0)
ADDR(BR1,BV1,TF)
ADDL(BV2,2,TF)
SUB(BR1,1)
ADD(BR0,2,TF)
ANDB(BR1,BV0)
ADDR(BR1,BV1,TF)
ADDL(BV2,2,TF)
SUB(BR1,1)
ADD(BR0,2,TF)
ANDB(BR1,BV0)
ADDR(BR1,BV1,TF)
ADDL(BV2,2,TF)
ADD(BR1,5)

END OF RECEIVER ?

REGISTERS AFFECTED: BR2
FLAGS SENSED: AF0,AF3
ADD(BR2,1,TE)
NOP
JUMPS(VPRE1,AF0)
JUMPC(VLOP2,AF3)

END OF RECEIVER 1

REGISTERS AFFECTED: BR0,BV3
FLAGS AFFECTED: AF3
LOAD(BR1,SVT111S(1),L,TF)
CLEAR(AF3)
LOAD(BR0,SVT99S(1),L)

```

```

PAGE 56:      MAP MODULES FOR THE P A R C ALGORITHM      --- JAN. 30, 1980

A77 04F00 EEB10011 (02234)      MOV8(BV3,BR,TF)      ;STATE VARIABLE
A78 04F02 F0B10032 (02235)      SUBL(BV3,2,TF)      ;RMS
A79 04F04 F21A0002 (02236)      ADD(BR1,2)      ;# OF SAMPLES
A7A 04F06 F5310013 (02237)      MOV8(BV3,BR1,TE)
A7B 04F08 F6200031 (02239)      CLEAR(RI)
A7C 04F0A F8000020 (02239)      NOP
A7D 04F0C FAD00060 (02240)      JUMP(B)
      (02241) *
      00004F06 (02242) VPCRC5A=0C      ;CHAIN ANCHOR
      (02243) *
      04F0E      (02244) *      END
      (02245) *      EVEN
      (02246) *
      (02247) *
      (02248) *      STORAGE BLOCK FOR CONSTRUCTED INSTRUCTIONS
      (02249) *
      04F0E 00000000 (02250) VPCRC51 DATA 2F'0.0'
      ...
      (02251) *
      00000100 (02252) VPCRC5Z=0L-VPCRC5      ;COMPUTE MODULE SIZE
      (02253) *
      (02254) *      TOP OF EXEC
      (02255) *
      (02256) *      TOES=0L
      (02257) *      0L=TOESPR
      (02258) *      ADDR      TOES(.BUS1S)
      (02259) *      END
      (02260) *
      (02261) *      EVEN
      (02262) *      EJECT

```

PAGE 57: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1980

```

(02263) *
(02264) *
(02265) *
(02266) *
(02267) *
(02268) *
(02269) *
(02270) *
(02271) *
(02272) *
(02273) *
(02274) *
(02275) *
(02276) *
(02277) *
(02278) *
(02279) *
(02280) *
(02281) *
(02282) *
(02283) *
(02284) *
(02285) *
(02286) *
(02287) *
(02288) *
(02289) *
(02290) *
(02291) *
(02292) *
(02293) *
(02294) *
(02295) *
(02296) *
(02297) *
(02298) *
(02299) *
(02300) *
(02301) *
(02302) *
(02303) *
(02304) *
(02305) *
(02306) *

```

ARVIND S. ARORA

NAME: ENCLS FCB: 110

THIS PROGRAM TAKES A BLOCK OF QUANTIZER OUTPUTS FROM THE PARC ALGORITHM AND ENCODES THEM INTO A BIT STREAM FOR DIGITAL TRANSMISSION. EACH OUTPUT BLOCK HAS 189 BITS CONSISTING OF 1 SYNC BIT, 6 BITS FOR T, 7 BITS FOR BETA, 7 BITS FOR 'PHONEY' BETA IF APPLICABLE, 18 BITS FOR PARITY CHECK, AND THE REST (157 BITS) FOR QUANTIZER OUTPUT INFORMATION.

ENCODER CONSTRAINTS:

```

1-- THE NUMBER OF QUANTIZER OUTPUTS IN THE INPUT BUFFER MUST GENERATE NO
    MORE THAN 196 BITS.
1-- NONE OF THE BUFFERS IN THIS PROGRAM MUST OCCUPY MEMORY LOCATIONS
    HIGHER THAN 32K.
1-- THERE ARE SEVERAL CONSTRAINTS ON THE SOURCE CODE:
    1. THE CODE FOR LEVEL 1 IS 0.
    2. THE CODE FOR 'PHONEY' BETA IS 000,000.
    3. RUN LENGTH IS FIXED AT 14. (UNLESS LOCATION LSRUN IS MODIFIED)
    4. THE CODE 111,111 IS AN ALTERNATE NULL CODE.
    5. BECAUSE THE LSB OF THE CODE-WORD IS TRANSMITTED FIRST, THE RECEIVER
       GETS AN INVERTED CODE, EG. 110 --> 011. TO COMPENSATE FOR THIS,
       THE ENCODING TABLE MUST CONTAIN INVERTED CODES, RIGHT JUSTIFIED.
    6. LOCATION 0 IN THE ENCODING TABLE CONTAINS THE CODE FOR RUN LENGTH.
    7. LOCATION 2*12 IN THE ENCODING TABLE CONTAINS THE CODE FOR NULL CODE.
1-- ALTHOUGH THE CODES FOR Q-LEVELS ARE INVERTED BY THE ALGORITHM, THE
    CODES FOR T, BETA, 'PHONEY' BETA ARE NOT.
1-- THE VARIOUS INPUTS TO THIS PROGRAM NEED TO BE PROVIDED IN THE
    FOLLOWING FORMATS:
    N=2          FIXED FORMAT (ENCODED T)
    0<T<63      FIXED FORMAT (ENCODED T)
    0<BETA<96    FIXED FORMAT (ENCODED BETA)
    -VE NO.      FIXED FORMAT
    1. Q-LEVELS
    2. T
    3. BETA
    4. 'PHONEY' BETA

```

PAGE 58: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1988

FIXED FORMAT

-VE 12

(#2307) ; 5. END CODE

(#2308) ;

(#2309) ;

(#2310)

EJECT

```

(02311) ;
(02312) ;
(02313) ;
(02314) ;
(02315) ;
(02316) ;
(02317) ;
(02318) ;
(02319) ;
(02320) ;
(02321) ;
(02322) ;
(02323) ;
(02324) ;
(02325) ;
(02326) ;
(02327) ;
(02328) ;
(02329) ;
(02330) ;
(02331) ;
(02332) ;
(02333) ;
(02334) ;
(02335) ;
(02336) ;
(02337) ;
(02338) ;
(02339) ;
(02340) ;
(02341) ;
(02342) ;
(02343) ;
(02344) ;
(02345) ;
(02346) ;
(02347) ;
(02348) ;
(02349) ;
(02350) ;
(02351) ;
(02352) ;
(02353) ;
(02354) ;

```

THE FUNCTION CONTROL BLOCK IS AS FOLLOWS:

```

-----
|                                     |
| FCB # 110 | ISTB |
|-----|-----|
| OUTB | QHAT |
|-----|-----|
| BETA (TABLE) | ENCT (TABLE) |
|-----|-----|
| SCAL ID(RC UPDATE) |
|-----|
| INT SC ID(RC UPD) |
|-----|

```

*** NOTE: ENABLE LINES WITH * IN COL. 1 TO ASSEMBLE THIS PROGRAM BY ITSELF.

--- SYMBOL DEFINITION TO INTERFACE WITH SNAP-11 EXEC. REL 3.05

```

BCTSBA=$502
FDT$UFCB=$8C4
ISVTS=$502
SVSSFLG=$1FFCE
TOESOLD=$5000
TOESPTR=$200
SVTS=$302
--- TOP OF MEMORY POINTER
*OL=TOESPTR
ADDR TOESNEW(,1)
--- DISPATCH TABLE ENTRIES
*OL=FDT$UFCB
ADDR ENCD$

```

PAGE 68: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1988

```

(2355) ;
(2356) ;---- CSPU MODULE FOR THE ENCODER
(2357) ;
(2358) ;OL=TOESOLD
(2359) ;---- I. BASE ADDRESS FOR 4 BUFFERS AND INDEX FOR T.BETA
(2360) ;
(2361) ;---- INDEX FOR T.BETA
(2362) ;
(2363) ENCD5 MOVW R2,R1,S0FF ;SID FOR T.BETA
(2364) MOVW R2,I1D5TB ;SAVE IN LOC I1D5TB
(2365) ;
(2366) ;---- UPDATE RECEIVER
(2367) ;
(2368) ; CALL R7,RCS
(2369) ;
(2370) ;---- ADDRESS FOR QHAT
(2371) ;
(2372) ;
(2373) ; INCR R1,1
(2374) MOVW R6,R1,S0FF ;BID FOR QHAT
(2375) CALL .BASES ;SUBROUTINE TO RETRIEVE BASE ADDR.
(2376) MOVW R4,AD5QHAT ;SAVE IN LOC AD5QHAT
(2377) ;
(2378) ;---- ADDRESS FOR OUTB
(2379) ;
(2380) MOVW R6,R1
(2381) LRS R6,8 ;BID FOR OUTB
(2382) CALL .BASES ;SUB. TO GET BASE ADDR.
(2383) MOVW R4,AD5OUTB ;SAVE IN LOC AD5OUTB
(2384) ADDR R5,S0FFD ;BASE ADDR + 189
(2385) MOVW R4,AD5OUTT ;SAVE IN LOC AD5OUTT 8. ADDR+189
(2386) ;
(2387) ;---- ADDRESS FOR ENCT, INDEXED BY R1
(2388) ;
(2389) ; INCR R1,1
(2390) MOVW R6,R1,S0FF ;BID FOR ENCT
(2391) CALL .BASES ;SUBROUTINE TO GET BASE ADDR.
(2392) IORIR R4,S0FF2 ;INSERT INDEX REG.1
(2393) MOVW R4,AD5ENCT ;SAVE IN LOC AD5ENCT
(2394) ;
(2395) ;---- ADDRESS FOR BETA, INDEXED BY R1
(2396) ;
(2397) MOVW R6,R1

```

84FC2 702200FF
84FC4 E0205112

84FC6 2001
84FC7 2000

84FC8 2611
84FC9 706200FF
84FCB 060050FF
84FCD 04405106

84FCF 6062
84FD0 3C60
84FD1 060050FF
84FD3 04405108
84FD5 9C50000D
84FD7 04405110

84FD9 2611
84FDA 706200FF
84FDC 060050FF
84FDE 96400002
84FEB 0440510A

84FE2 6062

PAGE 62: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 35, 1988

```

#5013 0020501F (#2442) JMP ENS51,GTZ
#5016 00400026 (#2443) MOVIR R4,SS006
#5017 0010 (#2444) CLR R1
#5018 00905108 (#2445) ENSS0
#501A 00005109 (#2446) MOVRR R1,0ADSOUTB
#501C 00405018 (#2447) INCM ADSOUTB+1
#501E 2667 (#2448) DJP R4,ENS50
#501F 00005107 (#2449) INCR R6,7
#5021 00005112 (#2450) INCM ADSQAT+1
#5023 3A51 (#2451) ENSS1
#5024 2652 (#2452) INCR R6,7
#5026 001A0382 (#2453) INCM ADSQAT+1
#5027 0000510C (#2454) ENSS1
#5029 00400006 (#2455) MOVRR R5,IIDSTB
#502C 2A6A (#2456) LLS R5,1
#502D 2811 (#2457) INCR R5,2
#502E 447C (#2458) MOVRR R1,SVTS(R5)
#502F 00905108 (#2459) MOVRR R5,0ADS0BETA
#5031 2661 (#2460) MOVIR R4,SS006
#5032 00005109 (#2461) CLR R1
#5033 3A51 (#2462) SRCL 6,R5
#5036 00405028 (#2463) INCR R1,1
#5037 2001 (#2464) XORRR R7,R6
#5038 2000 (#2465) MOVRR R1,0ADSOUTB
#5039 0030504A (#2466) INCR R6,1
#503D 0090510E (#2467) INCM ADS(UTB+1)
#503F 1010 (#2468) LLS R5,1
#5041 00905108 (#2469) DJP R4,ENS60
#5043 2661 (#2470) INCR R1,1
#5044 00005109 (#2471) INCM ADS(UTB+1)
#5046 0000510F (#2472) INCM ADS(UTB+1)
#5048 0040503D (#2473) DJP R4,ENS60

#5037 2001 (#2474) NOP
#5038 2000 (#2475) MOVRR R4,VDEL
#5039 0030504A (#2476) JMP ENS00.LTZ
#503D 0090510E (#2477) MOVRR R1,0ADSOLD8
#503F 1010 (#2478) SKP EQZ
#5041 00905108 (#2479) XORRR R7,R6
#5043 2661 (#2480) MOVRR R1,0ADSOUTB
#5044 00005109 (#2481) INCR R6,1
#5046 0000510F (#2482) ADSOUTB+1
#5048 0040503D (#2483) INCM ADSOLD8+1
#504A 0000510F (#2484) DJP R4,ENS70

```

>0. NO PHONEY BETA
PHONEY BETA -000,0000 (7 BITS)
CODE LENGTH - 1 (+VE INDEX)
R1=0
OUTPUT
INCREMENT O-INDEX
LOOP 7 TIMES
INCREMENT H-INDEX BY 7
INCREMENT I-INDEX

SID FOR BETA
VALUE OF BETA (0-98)
CODE FOR BETA
CODE LENGTH - 1 (+VE INDEX)
MSB OF BETA, SKIP IF 0
R1=1, IF MSB IS 1
PARITY UPDATE FOR 1
OUTPUT
INCREMENT H-INDEX
INCREMENT O-INDEX
NEXT BIT IN MSB

GET DELTA VALUE
DEL<0, NO BITS LEFT OVER
GET OLD OUTPUT
PARITY UPDATE FOR 1
OUTPUT
INCR H-INDEX
INCREMENT O-INDEX
INCR OLD O-INDEX

--- VII. FIRST, OUTPUT ANY EXTRA BITS FROM LAST BLOCK

--- JAN. 30, 1980

ADDRESS	INSTR	OP	DATA	COMMENT
00000	182B	SKPL		IF 57 INFO BITS, OUT 6 PARITY BITS
00001	06005DEF	CALL		NEXT BIT TO LSB
00002	3C51	LRS		
00003	0C405B7D	DJP		
00004				
00005	E5005107	INCH		INCR I-INDEX
00006	0000550A	JMP		
00007				
00008				
00009	FC205115	ADDMR		1-CNTR=1-CNTR+13 (0 OF B'S, +VE INDEX)
00010	0D50	CLR		CODE FOR Q=1 IS B, R5=B
00011	E0D0510B	MOVHR		OUTPUT
00012	5097 2661	INCR		INCR H-INDEX
00013	E5005109	INCH		INCR O-INDEX
00014	92600B39	CMPIR		DEL=H-IND -57
00015	509C 182B	SKPL		
00016	06005DEF	CALL		IF 57 INFO BITS, OUTPUT 6 PARITY BITS
00017	0C205B95	DJP		
00018				
00019	00005554	JMP		
00020				
00021	FC205115	ADDMR		1-CNTR=1-CNTR+13 (0 OF B'S, +VE INDEX)
00022	0D50	CLR		Q=1, CODE IS B, R5=B
00023	E0D0510B	MOVHR		OUTPUT
00024	5097 2661	INCR		INCR H-INDEX
00025	E5005109	INCH		INCR O-INDEX
00026	92600B39	CMPIR		DEL=H-IND -57
00027	509C 182B	SKPL		
00028	06005DEF	CALL		IF 57 INFO BITS, PUT OUT 6 PARITY BITS
00029	0C205B96	DJP		
00030				
00031	F0405109	MOVHR		MOVE O-INDEX TO R3
00032	FE405111	SUBMR		DIFF=O-INDEX -189
00033	013050E4	JMP		IF DIFFERENCE +VE, READY TO QUIT
00034				
00035	90100010	MOVIR		INDEX FOR NULL CODE (12+2)
00036	C0C0510A	MOVHRL		NULL CODE, LENGTH IN R5, R4
00037	501A0001	MOVKR		LSB TO R1

PAGE 66: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1980

```

(02617) ; - TO OUTPUT 6 PARITY BITS (MSB FIRST)
(02618) ; - INITIALIZE PARITY CHECK WORD (R7) TO 0
(02619) ; - INITIALIZE H-INDEX (R6) TO 1
(02620) ;
(02621) ; PAROUTS MOVIR R3,00005 TO MOVE OUT 6 BITS (+VE INDEX)
(02622) ; PAR51 MOVKR R6,R7,00020 6TH BIT TO R6
(02623) ; LRS R6,5 SHIFT BIT TO LSB
(02624) ; MOVRM R6,0ADSOUBS OUTPUT
(02625) ; INCHM ADSOUBS+1 INCREMENT O-INDEX
(02626) ; LLS R7,1 NEXT BIT TO 6TH POSITION
(02627) ; DJP R3,PAR51
(02628) ;
(02629) ; MOVIR R6,00001 INITIALIZE R6 TO 1
(02630) ; CLR R7 INITIALIZE R7 TO 0
(02631) ;
(02632) ; RETURN
(02633) ;
(02634) ;
(02635) ; --- SUBROUTINE BASES
(02636) ;
(02637) ; - TO GET BASE ADDR AND MEM BUS FOR BUFFER (NOT INDEX REGISTER)
(02638) ; - R6 = BID
(02639) ; - R4,R5 = BASE ADDRESS
(02640) ;
(02641) ; BASES R6,1 INDEX=BID*2
(02642) ; MOVML R4,8CTSBAR6 GET BASE ADDR FROM BCT
(02643) ; ANDIR R4,00006 KEEP ONLY BUS ID
(02644) ; LLS R4,3 MOVE BUS ID TO BITS 4,5
(02645) ; RETURN
(02646) ;
(02647) ;
(02648) ; --- LEAVE SPACE FOR VARIOUS VARIABLES
(02649) ;
(02650) ;
(02651) ; ADOSHAT DATA F'0.0'
(02652) ; ADSOUBS DATA F'0.0'
(02653) ; ADSENCI DATA F'0.0'
(02654) ; ADSBETA DATA F'0.0'
(02655) ; ADSOLDB DATA F'0.0'
(02656) ; ADSOUBT DATA F'0.0'
(02657) ; IDSTB DATA 00000
(02658) ; VSSYN DATA 00001
(02659) ; VSDCL DATA SFFFF
(02660) ; LSRUN DATA 00000

```

PAGE 57: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 35, 1985

```

(02661) :
(02662) :
(02663) : --- UPDATE TOP OF MEMORY
(02664) :
(02665) : TOESNEV=0L
(02666) : END
(02667) : EVEN
(02668) : EJECT

```

PAGE 68: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1968

```
(#2669) ;
(#2670) ;
(#2671) ;
(#2672) ;
(#2673) ;
(#2674) ;
(#2675) ;
(#2676) ;
(#2677) ;
(#2678) ;
(#2679) ;
(#2680) ;
(#2681) ;
(#2682) ;
(#2683) ;
(#2684) ;
(#2685) ;
(#2686) ;
(#2687) ;
(#2688) ;
(#2689) ;
```

```
*****
*
* *** PROGRAM TRBUF ***
*
*****
```

```
PROG:TRSDC          ARVIND S. ARORA
FCB = #112
```

THIS PROGRAM TRANSFERS ELEMENTS FROM A DOUBLE BUFFER (109 LONG EACH) TO A CIRCULAR BUFFER (1024 LONG). THIS IS USEFUL IN TESTING THE PARC ALGORITHM WITHOUT THE USE OF THE IOS2. THIS PROGRAM ESSENTIALLY SIMULATES THE IOS2 IN THE CPU. SINCE THIS PROGRAM ADDS TO THE CPU TIME, WHICH IS ALREADY AT PREMIUM, THE SAMPLING RATE MUST BE LOWERED BY ABOUT 33 PERCENT.

EJECT

PAGE 69: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1980

```

(B2698) ;
(B2699) ;
(B2700) ;
(B2701) ;
(B2702) ;
(B2703) ;
(B2704) ;
(B2705) ;
(B2706) ;
(B2707) ;
(B2708) ;
(B2709) ;
(B2710) ;
(B2711) ;
(B2712) ;
(B2713) ;
(B2714) ;
(B2715) ;
(B2716) ;
(B2717) ;
(B2718) ;
(B2719) ;
(B2720) ;
(B2721) ;
(B2722) ;
(B2723) ;
(B2724) ;
(B2725) ;
(B2726) ;
(B2727) ;
(B2728) ;
(B2729) ;
(B2730) ;
(B2731) ;
(B2732) ;
(B2733) ;

```

THE FUNCTION CONTROL BLOCK IS AS FOLLOWS:

```

-----
|                                     |
|                                     |
| FCB @ 112 | INIT                 |
|-----|-----|
| DBUF2 | DBUF1                   |
|-----|-----|
|                                     |
|                                     |
| CBUF                                         |
|-----|-----|
|                                     |
|                                     |
|                                     |
|-----|-----|

```

*** NOTE: ENABLE LINES WITH * IN COLUMN 1 TO ASSEMBLE THIS ROUTINE ALONE.

---- SYMBOL DEFINITION TO INTERFACE WITH SNAP-II EXEC. REL 3.05

```

      BCISBA=8582
      FOTSUCB=88C8
      ISVTS=8502
      SYSSFLGS=81FFCE
      TOESOLD=8518F
      TOESPTR=8288

      *OL-TOESPTR
      ADDR TOESNEW(.1)

      ---- DISPATCH TABLE ENTRY

      *OL-FOTSUCB
      ADDR TRSDC

      ---- CSPU MODULE FOR BUFFER TRANSFER, DOUBLE BUFF. --> CIRCULAR BUFF.

      *OL-TOESOLD

      ---- CHECK INIT. SCALAR SELECT

```

PAGE 78: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1980

05116 707200FF	(02734) :	MOVW	R7,R1,SEF		
05118 2611	(02735) :	MOVLM	\$27,SYSSFLGS		
05119 006E0502	(02736) :	INCR	R1,1		
0511B 00205135	(02737) :	MOVHR	R6,ISVTS(R7)		
0511D 0030512A	(02738) :	JMP	TR\$20,GTZ		
	(02739) :	JMP	TR\$10,LTZ		
	(02740) :				
	(02741) :				
	(02742) :				
0511F 0060	(02743) :	CCR	R6		
	(02744) :				
05120 2611	(02745) :	INCR	R1,1		
05121 0022	(02746) :	MOVHR	R2,R1		
05122 3A21	(02747) :	LLS	R2,1		
05123 C0440502	(02748) :	MOVHRL	R4,BCT\$BA(R2)		
05125 E050514F	(02749) :	MOVHR	R5,ADOUT		
	(02750) :				
05127 CC00515F	(02751) :	MOVZM	IND\$OUT		
05129 2711	(02752) :	DECR	R1,1		
	(02753) :				
	(02754) :				
0512A 0060	(02755) :	NEG	R6		
0512B E06E0502	(02756) :	MOVHR	R6,ISVTS(R7)		
	(02757) :				
0512D 0072	(02758) :	MOVHR	R7,R1		
0512E 3C77	(02759) :	LRS	R7,7		
0512F C04E0502	(02760) :	MOVHRL	R4,BCT\$BA(R7)		
05131 E050514C	(02761) :	MOVHR	R5,ADIN		
05133 0000513F	(02762) :	JMP	TR\$25		
	(02763) :				
	(02764) :				
	(02765) :				
05135 0060	(02766) :	NEG	R6		
05136 E06E0502	(02767) :	MOVHR	R6,ISVTS(R7)		
	(02768) :				
05138 707200FF	(02769) :	MOVW	R7,R1,SEF		
0513A 3A71	(02770) :	LLS	R7,1		
0513B C04E0502	(02771) :	MOVHRL	R4,BCT\$BA(R7)		
0513D E050514C	(02772) :	MOVHR	R5,ADIN		
	(02773) :				
	(02774) :				
0513F F0705160	(02775) :	MOVHR	R7,SIZES		
05141 2771	(02776) :	DECR	R7,1		
	(02777) :				

TIMING INSTRUCTION
 >0,NORMAL OPERATION BUF 1
 <0,NORMAL OPERATION BUF 2
 :=0,INITIALIZATION
 SET SCALAR SELECT TO -1
 GET BASE ADDR FOR CIRC. BUFF
 SAVE ADDR
 SET SID SELECT
 SAVE
 GET BID FOR DOUBLE BUFF 1
 GET BASE ADDR
 SAVE BASE ADDR
 COMPLEMENT SID SELECT
 SAVE
 GET BID FOR DOUBLE BUFF 2
 GET BASE ADDR
 SAVE BASE ADDR
 GET BUFFER SIZE
 SET UP COUNTER

PAGE 71: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1980

```

(B2770) ;
(B2779) ;
(B2780) ;
(B2781) ;
(B2782) ;
(B2783) ;
(B2784) ;
(B2785) ;
(B2786) ;
(B2787) ;
(B2788) ;
(B2789) ;
(B2790) ;
(B2791) ;
(B2792) ;
(B2793) ;
(B2794) ;
(B2795) ;
(B2796) ;
(B2797) ;
(B2798) ;
(B2799) ;
(B2800) ;
(B2801) ;
(B2802) ;
(B2803) ;
(B2804) ;
(B2805) ;
(B2806) ;
(B2807) ;
(B2808) ;
(B2809) ;
(B2810) ;
(B2811) ;
(B2812) ;
(B2813) ;
(B2814) ;
(B2815) ;
(B2816) ;
(B2817) ;
(B2818) ;
(B2819) ;
(B2820) ;
(B2821) ;

      GET MODE FOR IOS FROM INIT+1
      DEC R1,1
      MOVW R5,R1,SFF
      INCR R5,1
      MOVW R5,ISVTS(R5)
      ISID FOR INIT
      ISID FOR IOS MODE
      GET IOS MODE WORD

      SET UP IN/OUT ADDR INDICES
      CLR R3
      MOVW R2,INDSOUT
      INP IND
      OUT IND

      TRANSFER LOOP
      MOVW R6,ADIN(R3)
      MOVW R6,R5
      ADD IN IOS MODE

      MOVW R6,ADSOUT(R2)
      INCR R3,1
      INCR R2,1
      ANDIR R2,S83FF
      UPDATE INP COUNTER
      OUT COUNTER
      MOD 1#24

      DJP R7,TR83B
      SAVE OUT INDEX

      MOVW R2,INDSOUT
      MOVW $7,SYSSFLGS
      TIMING INSTRUCTION, G3
      RETURN
      EVEN

      SPACE FOR DATA
      ADIN DATA F'B.B'
      ADSOUT DATA F'B.B'
      INDSIN DATA S888B
      INDSOUT DATA S888B
      SIZES DATA S8D
      UPDATE TOP OF MEMORY

```

PAGE 72: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 31, 1981

(#2822) 1
 (#2823) *
 (#2824) *
 (#2825)
 (#2826)

TOESNEV=0L
 END
 EVEN
 EJECT

08161 0000

PAGE 73: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1980

```

(02827) ;
(02828) ;
(02829) ;
(02830) ;
(02831) ;
(02832) ;
(02833) ;
(02834) ;
(02835) ;
(02836) ;
(02837) ;
(02838) ;
(02839) ;
(02840) ;
(02841) ;
(02842) ;
(02843) ;
(02844) ;
(02845) ;
(02846) ;
(02847) ;
(02848) ;
(02849) ;
(02850) ;
(02851) ;
(02852) ;
(02853) ;
(02854) ;
(02855) ;
(02856) ;
(02857) ;
(02858) ;
(02859) ;
(02860) ;
(02861) ;
(02862) ;
(02863) ;
(02864) ;
(02865) ;
(02866) ;
(02867) ;

```

ARVIND S. ARORA

NAME: DCDRS FCB: 111

THIS PROGRAM TAKES FRAMES OF 189 BITS (LSB IN THE 16 BIT WORDS
OUTPUT BY THE IOS2), SYNCHRONIZES ON THE FRAME, AND DECODES THE BITS
INTO A BLOCK OF QUANTIZER LEVELS TO BE USED BY THE RECEIVER OF THE
PARC ALGORITHM.

DEPENDENT ON THE VALUES OF 2 FUNCTION SELECT INDICATORS, IT SELECTS
EITHER TO DECODE, OR SYNCHRONIZE, OR INITIALIZE AND SYNCHRONIZE. IT
ALSO DECIDES WHICH OF THE TWO Q-OUT BUFFERS TO FILL UP.

THE Q-OUT BUFFER HAS THE FOLLOWING FORMAT: PHONEY BETA INDICATOR
(-1 MEANS PHONEY BETA PRESENT), QUANTIZER LEVELS (1 TO 11, AND A RUN-
LENGTH CODE TO BE DECODED TO 14 LEVEL 1 OUTPUTS), AND AN END-OF-BLOCK
CODE (-VE 12).

EACH TIME THE PROGRAM IS STOPPED, THE MODULE MUST BE RE-LOADED
OR LOCATIONS PSBASE,LSRUN RESET TO ENSURE PROPER INITIALIZATION.

THIS PROGRAM ALSO SIMULATES THE STATE OF THE SHAT BUFFER IN THE
RECEIVER TO ENSURE THE BUFFER DOES NOT UNDER-FLOW OR OVER-FLOW.

CONSTRAINTS:

- 1) THE CONSTRAINTS ON THE SOURCE CODE ARE THE SAME AS THOSE ON THE ENCODER.
- 2) THE OUTPUT OF THE DECODER HAS THE SAME FORM AS THE INPUT OF THE ENCODER.
- 3) THE INPUT OF THIS PROGRAM IS A CIRCULAR BUFFER OF LENGTH 1024.
- 4) ALL THE BUFFERS USED IN THIS PROGRAM MUST RESIDE ON BUS 1.

EJECT

PAGE 74:

MAP MODULES FOR THE P A R C ALGORITHM ---- JAN. 30, 1980

```

(02868) 1
(02869) 1
(02870) 1
(02871) 1
(02872) 1
(02873) 1
(02874) 1
(02875) 1
(02876) 1
(02877) 1
(02878) 1
(02879) 1
(02880) 1
(02881) 1
(02882) 1
(02883) 1
(02884) 1
(02885) 1
(02886) 1
(02887) 1
(02888) 1
(02889) 1
(02890) 1
(02891) 1
(02892) 1
(02893) 1
(02894) 1
(02895) 1
(02896) 1
(02897) 1
(02898) 1
(02899) 1
(02900) 1
(02901) 1
(02902) 1
(02903) 1
(02904) 1
(02905) 1
(02906) 1
(02907) 1
(02908) 1
(02909) 1
(02910) 1
(02911) 1

```

THE FUNCTION CONTROL BLOCK HAS THE FOLLOWING FORMAT:

```

-----
1
-----
1 FCB # 111 1 ISELECT 1
-----
1 0082 1 0081 1
-----
1 ITB2 1 ITB1 1
-----
1 DECT (TABLE) 1 DECB (TABLE) 1
-----
1 ICAP 1 ICB 1
-----

```

*** NOTE: ENABLE ALL LINES WITH * IN COLUMN TO ASSEMBLE THIS PROGRAM ALONE.

--- SYMBOL DEFINITION TO INTERFACE WITH SNAP-II EXEC. REL 3.05

```

8CTS8A-S582      BASE OF SCALAR TABLE
FOTSUFCE-S8C6    FCB # 111
ISVTS-S582       BASE OF INTEGER SCALAR TABLE
NOSMAX-S9        (NO OF WORDS IN SYNC CORR. COMPUTATION)
SYSSFLG-S1FFCE   SYSTEM FLAG LOCATION
TOESOLD-S5288    OLD TOP OF MEMORY
TOESPTR-S288     TOP OF MEMORY POINTER
SVTS-S382        BASE OF SCALAR TABLE

--- TOP OF MEMORY POINTER
*OL=TOESPTR
ADDR TOESNEW(.1)

```

```

PAGE 78: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30. 1988

      (B2912) : --- DISPATCH TABLE ENTRIES
      (B2913) :
      (B2914) : OL=FDTSUFCB
      (B2915) :
      (B2916) : ADDR DCDRS
      (B2917) :
      (B2918) :
      (B2919) : --- CSPU MODULE FOR THE DECODER
      (B2920) :
      (B2921) : OL=TOESOLD
      (B2922) :
      (B2923) : FIRST DECIDE WHICH OPERATIONS ARE TO BE DONE
      (B2924) :
      (B2925) : DCDRS MOVNR R1,BASFCB STACK FCB POINTER
      (B2926) : NOP 2 SAVE SPACE FOR TIMING INSTRUCTION

      (B2927) :
      (B2928) : --- USE FUNCTION SELECT INDICATOR TO DECIDE OPERATION
      (B2929) :
      (B2930) : MOVNR R2,R1,SBFF GET SID OF ISL
      (B2931) : MOVNR R2,SIDSL SAVE SID
      (B2932) : MOVNR R3,ISVTS(R2) GET ISL1
      (B2933) : JMP DECS,GTZ ISL1 > B, DECODER
      (B2934) : JMP SYNC,LTZ ISL1 < B, SYNCHRONIZE
      (B2935) :
      (B2936) : ISL1 = B, INITIALIZE & SYNCHRONIZE
      (B2937) :
      (B2938) :
      (B2939) :
      (B2940) :
      (B2941) : 1) SET ISL1 TO -1
      (B2942) :
      (B2943) : EVEN
      (B2944) : CCR R3 SET R3=-1
      (B2945) : MOVNR R3,ISVTS(R2) SET ISL1 TO -1
      (B2946) :
      (B2947) : 2) SET MAX CORRELATION INDEX WORDS (1B) TO -1
      (B2948) :
      (B2949) : CCR R5 R5=-1
      (B2950) : MOVNR R4,MOSMAX INDEX=9 (FOR 1B WORDS)
      (B2951) : MOVNR R5,PSMAX(R4) MAX CORR WORD = -1
      (B2952) : DJP R4,INS2B
      (B2953) :
      (B2954) : 3) GET BASE ADDRESS OF Q-BUFFER1 & SAVE IN BASQOB

```

```

PAGE 76: MAP MODULES FOR THE P A R C ALGORITHM ---- JAN. 30, 1980

( #2955 ) ;
( #2956 ) ;
( #2957 ) ;
( #2958 ) ;
( #2959 ) ;
( #2960 ) ;
( #2961 ) ;
( #2962 ) ;
( #2963 ) ;
( #2964 ) ;
( #2965 ) ;
( #2966 ) ;
( #2967 ) ;
( #2968 ) ;
( #2969 ) ;
( #2970 ) ;
( #2971 ) ;
( #2972 ) ;
( #2973 ) ;
( #2974 ) ;
( #2975 ) ;
( #2976 ) ;
( #2977 ) ;
( #2978 ) ;
( #2979 ) ;
( #2980 ) ;
( #2981 ) ;
( #2982 ) ;
( #2983 ) ;
( #2984 ) ;
( #2985 ) ;
( #2986 ) ;
( #2987 ) ;
( #2988 ) ;
( #2989 ) ;
( #2990 ) ;
( #2991 ) ;
( #2992 ) ;
( #2993 ) ;
( #2994 ) ;
( #2995 ) ;
( #2996 ) ;
( #2997 ) ;
( #2998 ) ;

( TO BE USED FOR STORING SYNC CORRELATION VALUES )
( INDEXED BY R2 )

INCR R1,1
MOVW R2,R1,SBFF BID OF OOB1
LLS R2,1 BID*2
MOVW R3,BCTSSA(R2) GET BASE ADDR WORD FOR OOB1
MOVW R3,S14 BUS 1, IND REG R2
MOVW R3,BASQOB SAVE BASE ADDR

---- UPDATE PROGRAM LOCATIONS REFERRING TO OOB
MOVW R4,OOB10
MOVW R4,OOB11
MOVW R4,OOB12
MOVW R4,OOB13
MOVW R4,OOB14
MOVW R4,OOB15

4) INITIALIZE OOB BUFFER TO 0
MOVW R2,S18F R2=399
CLR R5
OQB10=0L+1
INS4 MOVW R5,BASQOB(R2) INIT OOB TO 0
DJP R2,INS4

5) GET BASE ADDR OF INPUT CIRCULAR BUFFER, IND REG R3, SIZE=1024
INCR R1,3
MOVW R2,R1,SBFF BID OF ICB
LLS R2,1 BID*2
MOVW R3,BCTSSA(R2) GET BASE ADDR WORDS FOR ICB
MOVW R3,S16 BUS 1, IND REG R3
MOVW R3,BASQOB SAVE BASE ADDR

---- MODIFY PROGRAM LOCATIONS REFERRING TO ICB
MOVW R4,ICB10
MOVW R4,ICB11
MOVW R4,ICB12
MOVW R4,ICB13
MOVW R4,ICB14

```

PAGE 77: MAP MODULES FOR THE P A R C ALGORITHM ---- JAN. 30, 1980

```

051A8 E0405355 (02999)      MOVHM R4,ICB2F
051A9 E0405353 (03000)      MOVHM R4,ICB21
051AF E0405376 (03001)      MOVHM R4,ICB22
051B1 E0405303 (03002)      MOVHM R4,ICB23
051B3 E04053C1 (03003)      MOVHM R4,ICB24
051B5 E04053D6 (03004)      MOVHM R4,ICB25
051B7 E0405406 (03005)      MOVHM R4,ICB26
051B9 E0405435 (03006)      MOVHM R4,ICB27
                                ; 6) SAVE GAP SIZE
                                ; (03007)
                                ; (03008)
                                ; (03009)
                                ; (03010)
                                ; (03011)
                                ; (03012)
                                ; (03013)
                                ; (03014)
                                ; (03015)
                                ; (03016)
                                ; (03017)
                                ; (03018)
                                ; (03019)
                                ; (03020)
                                ; (03021)
                                ; (03022)
                                ; (03023)
                                ; (03024)
                                ; (03025)
                                ; (03026)
                                ; (03027)
                                ; (03028)
                                ; (03029)
                                ; (03030)
                                ; (03031)
                                ; (03032)
                                ; (03033)
                                ; (03034)
                                ; (03035)
                                ; (03036)
                                ; (03037)
                                ; (03038)
                                ; (03039)
                                ; (03040)
                                ; (03041)
                                ; (03042)

051B8 6022                MOVHM R2,R1
051BC 3C20                LRS R2,8
051BD E0205405            MOVHM R2,VSGAP

                                GET GAP SIZE
                                SAVE GAP SIZE

                                *** SYNCHRONIZATION ***

                                ; 1) SHIFT MAX CORR. INDEX WORDS BACK ONE
                                ; I.E. P(I-1)=P(I)
                                ; (03021)
                                ; (03022)
                                ; (03023)
                                ; (03024)
                                ; (03025)
                                ; (03026)
                                ; (03027)
                                ; (03028)
                                ; (03029)
                                ; (03030)
                                ; (03031)
                                ; (03032)
                                ; (03033)
                                ; (03034)
                                ; (03035)
                                ; (03036)
                                ; (03037)
                                ; (03038)
                                ; (03039)
                                ; (03040)
                                ; (03041)
                                ; (03042)

051BF 0000                EVEN
051C0 90100009            MOVIR R1,NOSMAX
051C2 2711                DECR R1,1
051C3 90200009            MOVIR R2,NOSMAX
051C5 F0420488            MOVHM R4,PSMAX(R1)
051C7 E0440406            MOVHM R4,PSMAX(R2)
051C9 2721                DECR R2,1
051CA 8C1061C5            DJP R1,SCS1F

                                SYNC
                                ; (03022)
                                ; (03023)
                                ; (03024)
                                ; (03025)
                                ; (03026)
                                ; (03027)
                                ; (03028)
                                ; (03029)
                                ; (03030)
                                ; (03031)
                                ; (03032)
                                ; (03033)
                                ; (03034)
                                ; (03035)
                                ; (03036)
                                ; (03037)
                                ; (03038)
                                ; (03039)
                                ; (03040)
                                ; (03041)
                                ; (03042)

051C8 90100009            MOVIR R1,NOSMAX
051C2 2711                DECR R1,1
051C3 90200009            MOVIR R2,NOSMAX
051C5 F0420488            MOVHM R4,PSMAX(R1)
051C7 E0440406            MOVHM R4,PSMAX(R2)
051C9 2721                DECR R2,1
051CA 8C1061C5            DJP R1,SCS1F

                                SCS1F
                                ; (03026)
                                ; (03027)
                                ; (03028)
                                ; (03029)
                                ; (03030)
                                ; (03031)
                                ; (03032)
                                ; (03033)
                                ; (03034)
                                ; (03035)
                                ; (03036)
                                ; (03037)
                                ; (03038)
                                ; (03039)
                                ; (03040)
                                ; (03041)
                                ; (03042)

051C8 90100009            MOVIR R1,NOSMAX
051C2 2711                DECR R1,1
051C3 90200009            MOVIR R2,NOSMAX
051C5 F0420488            MOVHM R4,PSMAX(R1)
051C7 E0440406            MOVHM R4,PSMAX(R2)
051C9 2721                DECR R2,1
051CA 8C1061C5            DJP R1,SCS1F

                                ; 2) UPDATE SYNC HISTOGRAM FOR CURRENT FRAME
                                ; (03031)
                                ; (03032)
                                ; (03033)
                                ; (03034)
                                ; (03035)
                                ; (03036)
                                ; (03037)
                                ; (03038)
                                ; (03039)
                                ; (03040)
                                ; (03041)
                                ; (03042)

051C8 90100009            MOVIR R1,NOSMAX
051C2 2711                DECR R1,1
051C3 90200009            MOVIR R2,NOSMAX
051C5 F0420488            MOVHM R4,PSMAX(R1)
051C7 E0440406            MOVHM R4,PSMAX(R2)
051C9 2721                DECR R2,1
051CA 8C1061C5            DJP R1,SCS1F

                                ; --- SET UP FOR UPDATING
                                ; (03034)
                                ; (03035)
                                ; (03036)
                                ; (03037)
                                ; (03038)
                                ; (03039)
                                ; (03040)
                                ; (03041)
                                ; (03042)

051CC 9030000C            MOVIR R3,8BC
051CE FC300400            ADDMR R3,PSBASE
051D0 9A3000FF            ANDIR R3,00FF
051D2 0040                CLR R4
051D3 0060                CLR R5
051D4 90200179            MOVIR R2,$179
051D6 F01004CF            MOVHM R1,VSSYNC

                                R3=180
                                CURRENT BASE IND + 180
                                MAX CORR INDEX THIS BLOCK
                                MAX CORR VALUE
                                HISTOGRAM INDEX R2=377
                                SYNC BIT VALUE TO R1

```

PAGE 70: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1988

```

05108 9A100001 (03043) ANDIR R1,00001 MASK LSB
05109 9A100001 (03044) READY TO MOVE IN BIT 1
0510A 9A700001 (03045) SCS20 MOVIR R7,01
0510B 9A700001 (03046) ICB15=OL+1
0510C 9A700001 (03047) ANDMR R7,BAS1CB(R3) MOVE LSB OF INPUT WORD
0510D 4472 (03048) KORRR R7,R1 RESULT OF CORR. OF SYNC WITH INFO BIT
0510E 002001EE (03049) JMP SCS22,GTZ ;SAME = 0, DIFFERENT = 1
0510F 002001EE (03050) JUMP FOR DIFFERENT
0510G 002001EE (03051) ;
0510H 002001EE (03052) ; --- FOR MATCH WITH SYNC BIT
0510I 002001EE (03053) ;
0510J 002001EE (03054) OOB11=OL+1
0510K 002001EE (03055) MOVMR R6,BAS00B(R2) R6=SYNC COR VAL FOR CURRENT BIT
0510L 2661 (03056) INCR R6,1 ADD 1 TO IT
0510M 426A (03057) CMPRR R6,R5 CMPR WITH MAX SO FAR (R6-R5)
0510N 002001EE (03058) JMP SCS21,LTZ THIS VALUE < MAX SO FAR
0510O 400C (03059) MOVRR R5,R6 IF MAX, UPDATE MAX VALUE
0510P 4044 (03060) MOVRR R4,R2 UPDATE MAX INDEX
0510Q 002001EE (03061) OOB12=OL+1
0510R 002001EE (03062) SCS21 MOVRR R6,BAS00B(R2) SAVE NEW CORR VALUE
0510S 2721 (03063) DECR R2,1 DECR HIST INDEX
0510T 002001EE (03064) JMP SCS24
0510U 002001EE (03065) ;
0510V 002001EE (03066) ; --- FOR NO MATCH WITH SYNC BIT
0510W 002001EE (03067) ;
0510X 2721 (03068) SCS22 DECR R2,1 DECR HIST INDEX
0510Y 002001EE (03069) OOB13=OL+1
0510Z 002001EE (03070) MOVMR R6,BAS00B(R2) SYNC CORR VAL TO R6
0510A 2661 (03071) INCR R6,1 (R6-R5)
0510B 426A (03072) CMPRR R6,R5 THIS VAL NOT MAX
0510C 002001EE (03073) JMP SCS23,LTZ IF MAX, UPDATE MAX VAL
0510D 400C (03074) MOVRR R5,R6 IF MAX, UPDATE MAX INDEX
0510E 4044 (03075) MOVRR R4,R2
0510F 002001EE (03076) OOB14=OL+1
0510G 002001EE (03077) SCS23 MOVRR R6,BAS00B(R2) SAVE NEW CORR VAL
0510H 002001EE (03078) ;
0510I 002001EE (03079) ; --- MERGE HERE BOTH CASES, MATCH OR NO-MATCH
0510J 002001EE (03080) ;
0510K 002001EE (03081) SCS24 DECR R3,1 INP IND
0510L 002001EE (03082) ANDIR R3,003FF MOD 1/24
0510M 002001EE (03083) DJP R2,SCS20 DEC HIST IND & LOOP
0510N 002001EE (03084) ;
0510O 002001EE (03085) ; --- IF NOT SYNC IN 10 SECONDS, REINITIALIZE
0510P 002001EE (03086) ;

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PAGE 79:      MAP MODULES FOR THE P A R C ALGORITHM      --- JAN. 30, 1980

(03007) ;      CMPMR R5,TSLIM      CMPR IN TERMS OF NO OF ITERATIONS
(03008) ;      JMP SC808,GTZ      >10 SECS. REINIT.
(03009) ;
(03010) ;      3) IF PRESENT MAX INDEX NOT THE SAME AS LAST TIME'S, CHECK IT OUT
(03011) ;      JMP SC831      (NOTE: SKIP OVER THIS CHECK. TEMPI
(03012) ;      MOVMR R2,PSMAX      PREV MAX IND.
(03013) ;      CMPRR R2,R4      (R2-R4)
(03014) ;      JMP SC831,EQZ      IF SAME JUMP
(03015) ;      ;IF NOT,
(03016) ;      OOBIS=OL+1
(03017) ;      MOVMR R6,BASO0B(R2)      GET OLD MAX VAL
(03018) ;      CMPRR R6,R5      (PAST VAL-PRESENT VAL)
(03019) ;      JMP SC831,LEZ      IF PAST VAL LESS,JMP
(03020) ;      MOVRR R4,R2      SAVE NEW MAX INDEX
(03021) ;      MOVRR R4,PSMAX
(03022) ;      SC831
(03023) ;      4) CHECK IF SYNCHRONIZATION ACHIEVED
(03024) ;      IF ALL 10 PREV VALS OF MAX IND ARE THE SAME, WE HAVE SYNC
(03025) ;
(03026) ;      MOVIR R2,NOSMAX
(03027) ;      CMPMR R4,PSMAX(R2)      CMPR CURRENT & PREV VAL
(03028) ;      JMP SC870,NEZ      NOT EQUAL, NOT SYNC
(03029) ;      DJP R2,SC841
(03030) ;      5) SYNCHRONIZED. SET UP FOR RETURNING TO RECEIVER
(03031) ;      --- SET UP 2 BLOCKS SYNC VAL. (NOT NEXT)
(03032) ;      SRBCL R,R4      CHECK IND, EVEN OR ODD
(03033) ;      JMP SC851      ODD-CURRENT SYNC BIT RIGHT, LEAVE
(03034) ;      MOVIR R7,SO001      EVEN-CURRENT SYNC BIT IS WRONG
(03035) ;      XORRR R7,VSSYNC      INVERT FOR 2 BLOCKS AWAY
(03036) ;      NOP 1
(03037) ;      SC851
(03038) ;      --- UPDATE BASE OF CURRENT FRAME POINTER
(03039) ;      MOVMR R3,PSBASE
(03040) ;      ADDR R3,SBD
(03041) ;      ANDIR R3,SO3FF
(03042) ;      MOVRR R3,PSBASE
(03043) ;      --- SET UP BIT-1 POINTER
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(03972) ;
(03973) ;
(03974) ;
(03975) ;
(03976) ;
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(03988) ;
(03989) ;
(03990) ;
(03991) ;
(03992) ;
(03993) ;
(03994) ;
(03995) ;
(03996) ;
(03997) ;
(03998) ;
(03999) ;
(04000) ;

```

PAGE 88: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1980

```

(03131) ;
05226 3C41      LRS      R4.1      R4/2+BASE IS BIT-1 POINTER
05226 4C46      ADDR     R4.R3
05227 9A403FF   ANDIR    R4.03FF   MOD 1#24
05229 E0405489 MOVHR    R4.P8BIT1

(03136) ;
(03137) ; ---- FUNCTION LIST SELECTOR UPDATE
(03138) ;
05228 F0205486 MOVHR    R2.SIDSL
05229 90700001 MOVIR    R7.S1
05229 90700001 MOVHR    R7.ISVTS(R2)
05229 90700001 INCR     R2.1
05231 2621     MOVHR    R6.ISVTS(R2)
05232 F0640502 NEG      R6
05234 0060     MOVHR    R6.ISVTS(R2)
05235 E0640502

(03146) ;
(03147) ; 5) INITIALIZE BETA, T, AND Q-OUT FOR NEXT RECEIVER OPERATION
(03148) ;
(03149) ; ---- INITIALIZE T-B I.E.2B, AND BETA=48 I.E. B.B
(03150) ;
05237 F0105484 MOVHR    R1.BASFCB
05239 2612     INCR     R1.2
0523A 6022     MOVHR    R2.R1
0523B 0260     TEST     R6
0523C 1030     SKP      LTZ
0523D 3C20     LRS      R2.8
0523E 9A2000FF ANDIR    R2.SFF

(03158) ;
05240 0D10     CLR      R1
05241 3A21     LLS      R2.1
05242 E0140382 MOVHR    R1.SVTS(R2)

(03162) ;
05244 90100030 MOVIR    R1.S30
05246 2622     INCR     R2.2
05247 E0140382 MOVHR    R1.SVTS(R2)

(03166) ;
(03167) ; ---- INITIALIZE NEXT Q-OUT BUFF [1 (NO PH BETA), 126 B'S, -12]
(03168) ;
05249 F0105484 MOVHR    R1.BASFCB
05248 2611     INCR     R1.1
0524C 6022     MOVHR    R2.R1
0524D 0260     TEST     R6
0524E 1030     SKP      LTZ
0524F 3C20     LRS      R2.8

```

ISL1 = 1, FOR DECODER
SET ISL1 TO +1
SID OF ISL2
VAL OF ISL2
ISL2=-ISL2

GET FCB POINTER
POINT TO ITB IN FCB
GET VALS OF ITB1 AND ITB2
CHECK FUNCTION LIST FOR NEXT OP.
ISL2=-1, FUNC. LIST 1
ISL2=1, FUNC. LIST 2
KEEP APPROP. ITB

OUT T=B I.E. 2B

OUT BETA=48 I.E. B.B

BID WORD

ISL2=-1 FUNC LIST 1
ISL2=1 FUNC LIST 2

PAGE 91: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 35, 1985

```

#5258 9A2#FFF (#3175) ANDIR R2,FFF
#5252 3A21 (#3176) LLS R2,1
#5253 C#44#582 (#3177) MOVHRL R4,BCT$BA(R2) ADDR OF NEXT Q-OUT BUFF
#5255 9#4#514 (#3179) MOVIR R4,$14 BUS 1, IND REG R2
#5257 844#54AE (#3181) MOVHRL R4,BASOQB SAVE
#5259 E#5#5262 (#3184) MOVHRL R5,OQB$1
#5258 E#5#526A (#3185) MOVHRL R5,OQB$2
#525D 9#2#57E (#3188) MOVIR R2,$7E Q-LEVEL 1*2
#525F 9#5#5262 (#3189) MOVIR R6,$2
#5261 E#6454AE (#3191) SC$52 OQB$1=CL+1 126 1'S TO OQB
#5263 8C2#5261 (#3192) DJP R2,SC$52
#5265 9#2#57F (#3194) MOVIR R2,$7F
#5267 9#6#FFF4 (#3195) MOVIR R6,$FFF4 END CODE= -12
#5269 E#6454AE (#3197) MOVHRL R6,BASOQB(R2)
#5268 F#6#5406 (#3201) MOVHRL R6,SZ$SHAT
#526D 266F (#3202) INCR R6,16
#526E E#6#5487 (#3203) MOVHRL R6,P$SHAT
#5270 F#1#5484 (#3205) MOVHRL R1,BASFCB
#5272 2613 (#3206) INCR R1,3
#5273 7#22#FFF (#3209) MOVHRL R2,R1,$$FFF
#5276 3A21 (#3211) LLS R2,1
#5278 C#44#582 (#3212) MOVHRL R4,BCT$BA(R2) R4,R5=BASE ADDR WORDS
#5279 9#4#51E (#3213) MOVIR R4,$$1E BUS1, IND REG R7
#527A 844#5482 (#3214) MOVHRL R4,BASDEC
#527C E#5#526E (#3216) MOVHRL R5,DEC$1$
#527D 844#5482 (#3218)

```

---- UPDATE PROGRAM LOC IN NEXT SECTION REFERRING TO OQB

---- INITIALIZE POINTER IN SHAT CIRCULAR BUFFER

---- SET UP BASE ADDR OF BETA DECODE TABLE, IND REG R7

---- MODIFY PROGRAM LOCATIONS WHICH REFER TO DEC\$

PAGE 03: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1980

```

052AC 2631      (03263)      INCR R3.1      MOD 1024
052AD 9A3003FF  (03264)      ANDIR R3.003FF
052AE 052661    (03266)      IJN R4.0C054
052AF 89A052A5  (03267)      IJN R4.0C054
052B1 0270      (03268)      IJN R4.0C054
052B2 001052BE  (03269)      TEST R7
052B3 001052BE  (03270)      JMP SC0541.EQZ
052B4 2771      (03271)      DECR R7.1
052B5 00305489  (03272)      MOVHR R3.0581T1
052B6 00305489  (03273)      ADDR R3.07
052B7 4C3E      (03274)      ANDIR R3.003FF
052B8 9A3003FF  (03275)      MOVHR R5.00001
052B9 9A3003FF  (03276)      XORHR R5.00001
052BA 00500001  (03277)      IJN R5.00001
052BB 00500001  (03278)      IJN R5.00001
052BC 00500001  (03279)      IJN R5.00001
052BD 00500001  (03280)      IJN R5.00001
052BE 00500001  (03281)      IJN R5.00001
052BF 00500001  (03282)      IJN R5.00001
052C0 00500001  (03283)      IJN R5.00001
052C1 00500001  (03284)      IJN R5.00001
052C2 00500001  (03285)      IJN R5.00001
052C3 00500001  (03286)      IJN R5.00001
052C4 00500001  (03287)      IJN R5.00001
052C5 00500001  (03288)      IJN R5.00001
052C6 3A71      (03289)      LLS R7.1
052C7 00500001  (03290)      ICB13-0L+1
052C8 00500001  (03291)      MOVHR R1.00000(R3)
052C9 00500001  (03292)      IOKR R7.01.00001
052CA 00500001  (03293)      INCR R3.1
052CB 00500001  (03294)      ANDIR R3.003FF
052CC 00500001  (03295)      DJP R4.0C055
052CD 00500001  (03296)      MOVHR R7.05T
052CE 00500001  (03297)      IJN R7.05T
052CF 00500001  (03298)      IJN R7.05T
052D0 00500001  (03299)      IJN R7.05T
052D1 00500001  (03300)      IJN R7.05T
052D2 00500001  (03301)      IJN R7.05T
052D3 00500001  (03302)      IJN R7.05T
052D4 00500001  (03303)      IJN R7.05T
052D5 00500001  (03304)      IJN R7.05T
052D6 00500001  (03305)      IJN R7.05T
052D7 00500001  (03306)      IJN R7.05T
052D8 00500001  (03307)      IJN R7.05T
052D9 00500001  (03308)      IJN R7.05T
052DA 00500001  (03309)      IJN R7.05T
052DB 00500001  (03310)      IJN R7.05T
052DC 00500001  (03311)      IJN R7.05T
052DD 00500001  (03312)      IJN R7.05T
052DE 00500001  (03313)      IJN R7.05T
052DF 00500001  (03314)      IJN R7.05T
052E0 00500001  (03315)      IJN R7.05T
052E1 00500001  (03316)      IJN R7.05T
052E2 00500001  (03317)      IJN R7.05T
052E3 00500001  (03318)      IJN R7.05T
052E4 00500001  (03319)      IJN R7.05T
052E5 00500001  (03320)      IJN R7.05T
052E6 00500001  (03321)      IJN R7.05T
052E7 00500001  (03322)      IJN R7.05T
052E8 00500001  (03323)      IJN R7.05T
052E9 00500001  (03324)      IJN R7.05T
052EA 00500001  (03325)      IJN R7.05T
052EB 00500001  (03326)      IJN R7.05T
052EC 00500001  (03327)      IJN R7.05T
052ED 00500001  (03328)      IJN R7.05T
052EE 00500001  (03329)      IJN R7.05T
052EF 00500001  (03330)      IJN R7.05T
052F0 00500001  (03331)      IJN R7.05T
052F1 00500001  (03332)      IJN R7.05T
052F2 00500001  (03333)      IJN R7.05T
052F3 00500001  (03334)      IJN R7.05T
052F4 00500001  (03335)      IJN R7.05T
052F5 00500001  (03336)      IJN R7.05T
052F6 00500001  (03337)      IJN R7.05T
052F7 00500001  (03338)      IJN R7.05T
052F8 00500001  (03339)      IJN R7.05T
052F9 00500001  (03340)      IJN R7.05T
052FA 00500001  (03341)      IJN R7.05T
052FB 00500001  (03342)      IJN R7.05T
052FC 00500001  (03343)      IJN R7.05T
052FD 00500001  (03344)      IJN R7.05T
052FE 00500001  (03345)      IJN R7.05T
052FF 00500001  (03346)      IJN R7.05T

```

TEST PARITY SYNDROME
-0, NO ERROR, JUMP

SET UP INDEX FOR ERROR
BIT1 IND + SYNDROME - 1
MOD 1024

INVERT LSB AT ENA LOC

DECODE VALUE OF NEXT T (IMP BUFF MUST CONTAIN MSB FIRST)

VALUE OF NEXT BETA, PHONEY BETA

TO INITIALIZE PHONEY BETA
INITIALIZE PHONEY BETA
LOOP COUNTER FOR 2

INDEX FOR BETA CODE
BETA CODE LENGTH = 7 BITS


```

(03361) ;--- INVERT SYNC VALUE
(03362) ;
(03363) SC27# MOVIR R1,00001
(03364) ;--- XORR R1,VSSYNC
(03365) ;
(03366) ;--- UPDATE BASE OF CURRENT BLOCK FRAME
(03367) ;
(03368) MOVIR R3,PSBASE
(03369) ADDIR R3,SBD
(03370) ANDIR R3,SB3FF
(03371) MOVRM R3,PSBASE
(03372) ;
(03373) ;--- UPDATE FUNCTION LIST SELECTOR ISL2
(03374) ;
(03375) MOVIR R3,SIDSISL
(03376) INCR R3,1
(03377) MOVRM R6,ISVTS(R3)
(03378) NEG R6
(03379) MOVRM R6,ISVTS(R3)
(03380) ;
(03381) ;--- READY TO RETURN. GO FOR XMTR UPDATE
(03382) ;
(03383) JMP DCS9# CALL FOR XMTR UPD
(03384) ;
(03385) ;--- *** DECODER ***
(03386) ;
(03387) ; 1) GET ISL2 TO DECIDE FUNC LIST 1 OR 2
(03388) ;
(03389) EVEN
(03390) MOVIR R1,BASFCB
(03391) MOVRM R2,SIDSISL
(03392) INCR R2,1
(03393) MOVRM R3,ISVTS(R2)
(03394) ;
(03395) NOP 2
(03396) ;
(03397) ; 2) BASE ADDR FOR Q-OUT AND SID FOR T,BETA
(03398) ;
(03399) JMP DCS2#,LTZ
(03400) ;
(03401) ; ISL=-1,FUNC LIST1,BUFF#2
(03402) ; ISL= 1,FUNC LIST2,BUFF#1

```

PAGE 86: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1968

```

#531F 2611      (R3394)      INCR      R1,1      BID FOR OQB1
#532F 7022#FFF  (R3395)      MOVW      R2,R1,SBFF
#5322 3A21      (R3396)      LLS        R2,1
#5323 C044#002  (R3397)      MOVW      R4,BCTSA(R2)
#5325 9040#012  (R3398)      MOVIR     R4,SB12
#5327 0440#4AE  (R3399)      MOVRML   R4,BASOQB
#5329 2611      (R3401)      INCR      R1,1
#532A 7022#FFF  (R3402)      MOVW      R2,R1,SBFF
#532C E020#485  (R3403)      MOVRM    R2,S1DSTB
#532E 0000#33E  (R3404)      JMP       DCS21
#5329 2611      (R3405)      INCR      R1,1
#532A 7022#FFF  (R3406)      MOVW      R2,R1,SBFF
#532C E020#485  (R3407)      MOVRM    R2,S1DSTB
#532E 0000#33E  (R3408)      JMP       DCS21
#5330 2611      (R3409)      INCR      R1,1
#5331 6022      (R3410)      MOVW      R2,R1
#5332 3C27      (R3411)      LRS       R2,7
#5333 C044#002  (R3412)      MOVW      R4,BCTSA(R2)
#5335 9040#012  (R3413)      MOVIR     R4,SB12
#5337 0440#4AE  (R3414)      MOVRML   R4,BASOQB
#5339 2611      (R3415)      INCR      R1,1
#533A 6022      (R3416)      MOVW      R2,R1
#533B 3C28      (R3417)      LRS       R2,8
#533C E020#485  (R3418)      MOVRM    R2,S1DSTB
#533E 0000#33E  (R3419)      JMP       DCS21
#533F E000#47C  (R3420)      MOVW      R5,OOB26
#5341 E000#407  (R3421)      MOVRM    R5,OOB27
#5343 9020#002  (R3422)      MOVW      R2,SB0B2
#5345 F000#489  (R3423)      MOVRM    R5,PSBIT1
#5347 9C50#03F  (R3424)      ADDIR     R5,SB03F
#5349 9A50#3FF  (R3425)      ANDIR     R5,SB03FF
#534B 9020#002  (R3426)      MOVW      R2,SB0B2
#534D 4C3A      (R3427)      MOVRM    R5,PSBIT1
#534E 9A30#3FF  (R3428)      ADDIR     R5,SB03F
#534F 9A30#3FF  (R3429)      ANDIR     R5,SB03FF
#5350 9020#002  (R3430)      MOVW      R2,SB0B2
#5352 4C3A      (R3431)      MOVRM    R5,PSBIT1
#5353 9A30#3FF  (R3432)      ADDIR     R5,SB03F
#5354 9A30#3FF  (R3433)      ANDIR     R5,SB03FF
#5355 9020#002  (R3434)      MOVW      R2,SB0B2
#5357 4C3A      (R3435)      MOVRM    R5,PSBIT1
#5358 9A30#3FF  (R3436)      ADDIR     R5,SB03F
#5359 9A30#3FF  (R3437)      ANDIR     R5,SB03FF

```

ISL=-1 BUFF#2

R4,R5=BASE ADDR
BUS 1, IND REG R1

SAVE SID FOR T,BETA

SAVE SID FOR T,BETA

R5 CONTAINS OQB ADDR

COUNTER FOR 3 BLOCKS
SAVE BIT1 POINTER IN R5

POINT TO NEXT FRAME I.E.+63

POINT TO PARITY BIT

PAGE 87: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 38, 1988

```

#5350 #D7#      (R3438)
#5351 9#4#5#5#5 (R3439)
#5353 3A71      (R3440) DC#31
#5355 5#5#5#5#5 (R3441) IC#22=OL+1
#5354 F#6#5#4#C (R3442) MOVHR R6,BASICB(R3)
#5356 5#7#C#5#1 (R3443) IORRR R7,R6,5#5#5#1
#5358 2631      (R3444) ;
#5359 9A3#5#3#F (R3445) ; INCR R3,1
#5358 2631      (R3446) ; ANDIR R3,5#3#F
#5358 8C4#5#3#5 (R3447) ; DJP R4,DC#31
#5358 8C4#5#3#5 (R3448) ;
#5358 8C4#5#3#5 (R3449) ; ---- PARITY CHECK ON 57 BITS
#5358 8C4#5#3#5 (R3450) ;
#5358 8C4#5#3#5 (R3451) ;
#5358 8C4#5#3#5 (R3452) ;
#5358 8C4#5#3#5 (R3453) ;
#5358 8C4#5#3#5 (R3454) ;
#5358 8C4#5#3#5 (R3455) ;
#5358 8C4#5#3#5 (R3456) ;
#5358 8C4#5#3#5 (R3457) ;
#5358 8C4#5#3#5 (R3458) ;
#5358 8C4#5#3#5 (R3459) ;
#5358 8C4#5#3#5 (R3460) ;
#5358 8C4#5#3#5 (R3461) ;
#5358 8C4#5#3#5 (R3462) ;
#5358 8C4#5#3#5 (R3463) ;
#5358 8C4#5#3#5 (R3464) ;
#5358 8C4#5#3#5 (R3465) ;
#5358 8C4#5#3#5 (R3466) ;
#5358 8C4#5#3#5 (R3467) ;
#5358 8C4#5#3#5 (R3468) ;
#5358 8C4#5#3#5 (R3469) ;
#5358 8C4#5#3#5 (R3470) ;
#5358 8C4#5#3#5 (R3471) ;
#5358 8C4#5#3#5 (R3472) ;
#5358 8C4#5#3#5 (R3473) ;
#5358 8C4#5#3#5 (R3474) ;
#5358 8C4#5#3#5 (R3475) ;
#5358 8C4#5#3#5 (R3476) ;
#5358 8C4#5#3#5 (R3477) ;
#5358 8C4#5#3#5 (R3478) ;
#5358 8C4#5#3#5 (R3479) ;
#5358 8C4#5#3#5 (R3480) ;
#5358 8C4#5#3#5 (R3481) ;

```

COUNTER FOR 6 BITS

NEXT PARITY BIT
LOAD TO LSB OF PARITY WORD

INP INDEX

SET UP INP INDEX
COUNTER 56 - 5

INFO WORD
MASK BIT 1
PARITY UPDATE FOR 1

INP IND

SET UP ERROR IND

LOOP FOR 3 H-FRAMES

UPDATE FOR SYNC MONITOR

```

PAGE 88:      MAP MODULES FOR THE P A R C ALGORITHM      --- JAN. 30, 1980

      (M3482) ;
      (M3483) ;
      (M3484) ;
      (M3485) ;
      (M3486) ;
      (M3487) ;
      (M3488) ;
      (M3489) ;
      (M3490) ;
      (M3491) ;
      (M3492) ;
      (M3493) ;
      (M3494) ;
      (M3495) ;
      (M3496) ;
      (M3497) ;
      (M3498) ;
      (M3499) ;
      (M3500) ;
      (M3501) ;
      (M3502) ;
      (M3503) ;
      (M3504) ;
      (M3505) ;
      (M3506) ;
      (M3507) ;
      (M3508) ;
      (M3509) ;
      (M3510) ;
      (M3511) ;
      (M3512) ;
      (M3513) ;
      (M3514) ;
      (M3515) ;
      (M3516) ;
      (M3517) ;
      (M3518) ;
      (M3519) ;
      (M3520) ;
      (M3521) ;
      (M3522) ;
      (M3523) ;
      (M3524) ;
      (M3525) ;

      (M3379 4B3A)
      (M337A F87B54D3)
      (M337C 9B1B8B81)
      (M337E F41B54CF)
      (M338B 9A1B8B81)
      (M338C 8B8B5383)
      (M3382 F41B64AC)
      (M3384 2A82)
      (M3386 3B71)
      (M3388 1B8B)
      (M3387 3A72)
      (M3388 E87B54D3)
      (M338A 2B3E)
      (M338B 8B8B53A2)
      (M338D F87B5488)
      (M338F 9C7B8B8D)
      (M3391 9A7B83FF)
      (M3393 E87B5488)
      (M3395 F87B5486)
      (M3397 B06B)
      (M3398 E86E85B2)
      (M339A 2671)
      (M339B F86E85B2)
      (M339D B86B)
      (M339E E86E85B2)
      (M33A8 8B8B54A6)

      V(I+1)=RIGHT SHIFT 1 [V(I)], IF CORRELATED
      V(I+1)=LEFT SHIFT 2 [V(I)], NOT CORRELATED
      BIT 11 CLEAR ==> SYNC LOST
      MOVRR R3,R5 POINT TO NEXT SYNC BIT
      MOVRR R7,VSPAR GET SYNC VARIABLE
      MOVIR R1,8B8B1 CHECK CORR. IN THIS FRAME
      XORRR R1,VSSYNC
      ANDIR R1,8B8B1
      ICB23=OL+1
      XORRR R1,BASICB(R3) 1 - MATCH , 0 - NO MATCH
      SRBCL R,R1
      ARS R7,1 CORRELATED
      SKP R UNCORRELATED
      LLS R7,2
      MOVRR R7,VSPAR SAVE NEW VALUE
      SRBCL 11,R7 IF BIT 11 CLEAR, SYNC LOST
      JMP DC55B SYNC RETAINED, GO TO DECODE
      ---- IF SYNC LOST, SET UP FOR SYNC ACQUISITION NEXT TIME
      MOVRR R7,PSBASE
      ADDIR R7,8BD UPDATE BASE OF FRAME POINTER
      ANDIR R7,8B3FF
      MOVRR R7,PSBASE
      ---- UPDATE FUNCTION SELECT FLAGS AND RETURN
      ISL1=B
      ISL2=-ISL2
      MOVRR R7,SIDISL
      CLR R6
      MOVRR R6,ISVTS(R7)
      INCR R7,1
      MOVRR R6,ISVTS(R7)
      NEG R6
      MOVRR R6,ISVTS(R7)
      ---- GO FOR XMTR UPDATE
      JMP DC59B JUMP FOR XMTR UPD

```

PAGE 89: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 31, 1981

```

(03526) ;
(03527) ;
(03528) ; 5) MOV T,BETA,PH BETA TO THEIR LOCATIONS
(03529) ;
(03530) ; ---- MOVE T TO INTEGER SCALAR TABLE
(03531) ;
(03532) ; DC 5H MOVHR R7,SIDSTB
(03533) ; LLS R7.1
(03534) ; MOVHR R6,VST
(03535) ; MOVHR R6,SVTS(R7)
(03536) ;
(03537) ; ---- MOVE BETA TO ITS LOCATION IN INTEGER SCALAR TABLE
(03538) ;
(03539) ; INCR R7.2
(03540) ; MOVHR R6,VSBETA
(03541) ; MOVHR R6,SVTS(R7)
(03542) ;
(03543) ; ---- NOW MOVE PHONEY BETA TO LOCATION IN OUTPUT BUFFER
(03544) ;
(03545) ; MOVHR R1,BASOQB+1 INITIALIZE OUTPUT POINTER
(03546) ; MOVHR R6,VSPHB GET PHONEY BETA VALUE
(03547) ;
(03548) ; ---- UPDATE SHAT BUFFER POINTER IF PHONEY BETA
(03549) ;
(03550) ; JMP DC51,GTZ NO PH. BETA. JUMP AND PROCEED
(03551) ; MOVHR R7,VSGAP GET GAP SIZE
(03552) ; ADDR R7,PSHAT UPDATE SHAT POINTER
(03553) ;
(03554) ; DC51 PUSHX1 R1,R6 OUTPUT PH. BETA VALUE
(03555) ;
(03556) ; 6) DECODE NEXT T,BETA, PH BETA (R3,R5 STILL HAV LOC FOR NEXT FRAME)
(03557) ;
(03558) ; ---- FIRST T
(03559) ;
(03560) ; INCR R3.1
(03561) ; ANDIR R3,SB3FF POINT TO 1ST BIT (MSB) OF T
(03562) ;
(03563) ; MOVHR R4,RS
(03564) ; CLR R7
(03565) ;
(03566) ; DC56H LLS R7.1
(03567) ; ISB24=0L+1
(03568) ; MOVHR R6,BASICB(R3)
(03569) ; IORR R7,R6,SB5B1

```

PAGE 98: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1988

```

      (B3578) ;
      B33C4 2631      INCR      R3,1      INP IND
      B33C5 9A3B3FF      ANDIR      R3,5B3FF
      (B3579) ;
      B33C7 8C4B3BF      DJP        R4,DC86B
      (B357A) ;
      B33C9 E87B340B      MOVHR     R7,VST      SAVENEW T
      (B357B) ;
      (B357C) ;
      (B357D) ;
      (B357E) ;
      (B357F) ;
      (B3580) ;
      (B3581) ;
      (B3582) ;
      (B3583) ;
      (B3584) ;
      (B3585) ;
      (B3586) ;
      (B3587) ;
      (B3588) ;
      (B3589) ;
      (B358A) ;
      (B358B) ;
      (B358C) ;
      (B358D) ;
      (B358E) ;
      (B358F) ;
      (B3590) ;
      (B3591) ;
      (B3592) ;
      (B3593) ;
      (B3594) ;
      (B3595) ;
      (B3596) ;
      (B3597) ;
      (B3598) ;
      (B3599) ;
      (B359A) ;
      (B359B) ;
      (B359C) ;
      (B359D) ;
      (B359E) ;
      (B359F) ;
      (B35A0) ;
      (B35A1) ;
      (B35A2) ;
      (B35A3) ;
      (B35A4) ;
      (B35A5) ;
      (B35A6) ;
      (B35A7) ;
      (B35A8) ;
      (B35A9) ;
      (B35AA) ;
      (B35AB) ;
      (B35AC) ;
      (B35AD) ;
      (B35AE) ;
      (B35AF) ;
      (B35B0) ;
      (B35B1) ;
      (B35B2) ;
      (B35B3) ;
      (B35B4) ;
      (B35B5) ;
      (B35B6) ;
      (B35B7) ;
      (B35B8) ;
      (B35B9) ;
      (B35BA) ;
      (B35BB) ;
      (B35BC) ;
      (B35BD) ;
      (B35BE) ;
      (B35BF) ;
      (B35C0) ;
      (B35C1) ;
      (B35C2) ;
      (B35C3) ;
      (B35C4) ;
      (B35C5) ;
      (B35C6) ;
      (B35C7) ;
      (B35C8) ;
      (B35C9) ;
      (B35CA) ;
      (B35CB) ;
      (B35CC) ;
      (B35CD) ;
      (B35CE) ;
      (B35CF) ;
      (B35D0) ;
      (B35D1) ;
      (B35D2) ;
      (B35D3) ;
      (B35D4) ;
      (B35D5) ;
      (B35D6) ;
      (B35D7) ;
      (B35D8) ;
      (B35D9) ;
      (B35DA) ;
      (B35DB) ;
      (B35DC) ;
      (B35DD) ;
      (B35DE) ;
      (B35DF) ;
      (B35E0) ;
      (B35E1) ;
      (B35E2) ;
      (B35E3) ;
      (B35E4) ;
      (B35E5) ;
      (B35E6) ;
      (B35E7) ;
      (B35E8) ;
      (B35E9) ;
      (B35EA) ;
      (B35EB) ;
      (B35EC) ;
      (B35ED) ;
      (B35EE) ;
      (B35EF) ;
      (B35F0) ;
      (B35F1) ;
      (B35F2) ;
      (B35F3) ;
      (B35F4) ;
      (B35F5) ;
      (B35F6) ;
      (B35F7) ;
      (B35F8) ;
      (B35F9) ;
      (B35FA) ;
      (B35FB) ;
      (B35FC) ;
      (B35FD) ;
      (B35FE) ;
      (B35FF) ;

```

TO INITIALIZE PHONEV BETA
INITIALIZE PHONEV BETA

DECODE VAL OF BETA

THIS POSITION MEANS ERROR IN BETA
; FORCE BETA TO 0.0

HANG ONTO 1ST INFO BIT IN NEXT FRAME (IN R5)
MOVHR R5,R3

MOV TO DECODE QUANTIZER OUTPUTS

PAGE 31: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 35, 1968

```

      (R3614) ;
      (R3615) ;
      (R3616) ;
      (R3617) ;
      (R3618) ;
      (R3619) ;
      (R3620) ;
      (R3621) ;
      (R3622) ;
      (R3623) ;
      (R3624) ;
      (R3625) ;
      (R3626) ;
      (R3627) ;
      (R3628) ;
      (R3629) ;
      (R3630) ;
      (R3631) ;
      (R3632) ;
      (R3633) ;
      (R3634) ;
      (R3635) ;
      (R3636) ;
      (R3637) ;
      (R3638) ;
      (R3639) ;
      (R3640) ;
      (R3641) ;
      (R3642) ;
      (R3643) ;
      (R3644) ;
      (R3645) ;
      (R3646) ;
      (R3647) ;
      (R3648) ;
      (R3649) ;
      (R3650) ;
      (R3651) ;
      (R3652) ;
      (R3653) ;
      (R3654) ;
      (R3655) ;
      (R3656) ;
      (R3657) ;

      MOVHR R3,PSINFO
      MOVHR R2,PSBIT1
      SUBRR R3,R2
      ANDIR R3,803FF
      MOVIR R4,R3
      SUBRR R4,R3

      MOVHR R3,PSINFO
      MOVIR R2,R2
      CLR R7
      JMP DC871

      MOVIR R4,R3
      DC878

      LLS
      MOVHR R6,BASIC8(R3)
      TORR R7,R6,R1

      INCR R3,1
      ANDIR R3,803FF

      MOVHR R6,BASDECT(R7)
      JMP DC872,LTZ
      JMP DC873,GTZ

      DJP R4,DC871
      JMP DC875

      ;--- NULL OR RUN LENGTH CODE
      CMPHR R6,VSTHR
      JMP DC881,GTZ

      MOVHR R7,LSRUN
      MOVIR R6,R2
      ADDR R1,R7
      RPT R7

      INITIALIZE LOOP COUNTER
      IMP INDEX
      LOOP COUNTER
      CODE ACCUMULATOR

      <# NULL OR RUN LENGTH
      ># CODE WORD
      ; -# NOT YET CODE WORD
      ; LOOP BACK FOR NEXT IMP
      END OF H-FRAME PROCESSING

      +VE NULL CODE
      COUNTER FOR 14 1'S
      GONNA OUTPUT LEVEL 1*2
      SET UP OUT POINTER
      OUTPUT TO BUFFER

```

PAGE 92: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1980

```

0041A 0020000 (03650) MOVHM R6,B(R1)
0041C 0070 (03659) ;
0041D FC100110 (03660) CLR R7
0041F 2012 (03661) ADDHM R1,LSRUN
(03662) INCR R1,2
00420 004003FE (03663) ;
(03664) DJP R4,DCS71
00422 000000420 (03665) ;
(03666) JMP DCS75
(03667) ;
(03668) ;---- CODE WORD
(03669) ;
00424 341C (03670) DCS73 PUSHX1 R1,R6
00426 0070 (03671) CLR R7
(03672) ;
00428 004003FE (03673) DCS74 DJP R4,DCS71
(03674) ;
(03675) ;---- AT THE END OF EACH H-FRAME
(03676) ;
00420 2636 (03677) DCS75 INCR R3,6
00429 9A3003FF (03678) ANDIR R3,S03FF
(03679) ;
0042B 002003FC (03680) DCS76 DJP R2,DCS70
(03681) ;
(03682) ;---- END OF 3 H-FRAMES I.E. ONE INFO FRAME OF 189 BITS
(03683) ;
0042D 403A (03684) MOVHR R3,R5
(03685) ;
(03686) ;
0042E 0260 (03687) TEST R6
0042F 00200464 (03688) JMP DCS84,GTZ IF FRAME COVERED EXACTLY QUIT
(03689) ;
00431 90400000A (03690) MOVIR R4,SA LAST LEVEL, 11 MORE BITS
(03691) ;
00433 3A71 (03692) DCS77 LLS R7,1
00435 000000430 (03693) IC827=0L+1
00436 F00004AC (03694) MOVHR R6,BASICB(R3)
00438 00700001 (03695) IORHR R7,R6,S0001
(03696) ;
00430 2631 (03697) INCR R3,1
00430 9A3003FF (03698) ANDIR R3,S03FF
(03699) ;
00430 0000043C (03700) DECT21=0L+1
00430 F0000400 (03701) MOVHR R6,BASDECT(R7)

```

FOR NEXT CODE WORD
SET UP OUT POINTER AFTER
RPT INSTR HAS DECR IT BY LRUN+2

LOOP FOR NEXT INP

END OF H-FRAME PROCESSING

LOOP FOR 3 H-FRAMES

AT THE END OF 189 FRAME
UPDATE TO NEXT INFO BIT

PAGE 93: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 38, 1988

```

08430 0010844E (03702)      JMP      DC879, EQZ      NOT YET CODE
0843F 00208462 (03703)      JMP      DC808, GTZ      CODE WORD
                                !LTZ, NULL OR RUN LENGTH
                                !---- NULL CODE
08441 F2608404 (03706)      CMPMR    R6, V8THR      THRESHOLD--16
08443 00208464 (03707)      JMP      DC804, GTZ      >THR, NULL CODE
                                !<THR, RUN LENGTH
                                !---- RUN LENGTH CODE, OUTPUT 14 1'S
08445 F0708110 (03711)      MOVMR    R7, LSRUN      COUNTER FOR 14 1'S
08447 00608002 (03712)      MOVIR    R6, S2      LEVEL 1*2
08449 341C      DC870      PUSHX1   R1, R6      OUTPUT TO BUFFER
0844A 0C708449 (03717)      DJP      R7, DC870
                                !
0844C 00008464 (03719)      JMP      DC884
0844E 0C408433 (03721)      DJP      R4, DC877
08450 00008464 (03722)      JMP      DC884
                                !
                                !---- LAST CODE WORD
08452 341C      DC880      PUSHX1   R1, R6
08453 00008464 (03729)      JMP      DC884
08455 403A      DC801      MOVRR    R3, R5
                                !
                                !---- AFTER A NULL CODE, PUT IN 5 EXTRA LEVEL 1'S
                                ! ONLY IF 0 SAMPLES OUT = 126
08456 0060807F (03736)      MOVIR    R6, S7F      126*1
08458 4E62      SUBRR    R6, R1      126-(ADDR+N)
08459 FC6084AF (03737)      ADDMR    R6, BASOQB*1      126-(BASE ADDR+N)+BASE ADDR
0845B 01108464 (03738)      JMP      DC884, NEZ      N .NE. 126, NO EXTRA SAMPLES
                                !
0845D 00708004 (03741)      MOVIR    R7, S4      COUNTER FOR 5 1'S
0845F 00608002 (03742)      MOVIR    R6, S2      LEVEL 1*2
08461 341C      DC883      PUSHX1   R1, R6      OUTPUT LEVEL 1'S
08462 0C708461 (03745)      DJP      R7, DC883

```

```

PAGE 94: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1980

(03746) ;
(03747) ;
(03748) ; --- CHECK RECEIVER BUFFER FULL
(03749) ;
(03750) DCS84
(03751) MOVNR R7, SZSSSHAT
(03752) MOVNR R6, PSSSHAT
(03753) SUBIR R6, 57F
(03754) SUBMR R1, BASOQB+1
(03755) ADDR R6, R1
(03756) CHPR R6, R7
(03757) JMP DCS86, LEZ
(03758) SUBRR R6, R7
(03759) SUBRR R1, R6
(03760) MOVNR R6, R7
(03761) JMP DCS89
(03762) ;
(03763) ; --- CHECK RECEIVER BUFFER EMPTY CONDITION
(03764) DCS86
(03765) CHPR R6, 58
(03766) JMP DCS89, GEZ
(03767) ;
(03768) MOVIR R7, 52
(03769) OQB26=OL+1
(03770) DCS87
(03771) MOVNR R7, BASOQB(R1)
(03772) INCR R1, 1
(03773) IJN R6, DCS87
(03774) ;
(03775) CLR R6
(03776) DCS89
(03777) MOVNR R6, PSSSHAT
(03778) ; --- NULL CODE
(03779) ;
(03780) MOVIR R6, 5C
(03781) NEG R6
(03782) OQB27=OL+1
(03783) MOVNR R6, BASOQB(R1)
(03784) ;
(03785) ; 5, UPDATE FOR NEXT OPERATION OF DECODER
(03786) ;
(03787) ; --- NEXT INFO BIT POINTER
(03788) MOVNR R3, PSINFO
(03789) ;

GET REC BUFFER SIZE
REC BUFFER POINTER
SAMPLES REMOVED FROM BUFF. 126+1
COMPUTE # SAMPLES OUTPUT
SAMPLES ADDED TO SHAT BUFF.
(BUFF. POINTER - BUFF. SIZE)
NOT FULL. JMP AND PROCEED
NO. OF EXTRA SAMPLES
DELETE THE EXTRA SAMPLES
SHAT POINTER = 1024
GO FOR END CODE

(BUFF POINTER - 0)
NOT EMPTY, PROCEED
IF EMPTY, FILL WITH LEVEL 1'S
LEVEL 1*2

OUTPUT LEVEL 1
OUT IND

SHAT POINTER = 0
SAVE NEW SHAT POINTER

NULL CODE = -12

```

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```

(03798) ;--- NEXT BIT1 POINTER
(03791) ;
0540A F05054B9      MOVMR R5,PSBIT1
0540C 9C500000      ADDIR R5,SBD
0540E 9A5003FF      ANDIR R5,S03FF
05490 E05054B9      MOVMR R5,PSBIT1
(03796) ;
(03797) ;--- NEXT BASE OF FRAME
(03798)      MOVMR R3,PSBASE
05494 9C300000      ADDIR R3,SBD
05496 9A3003FF      ANDIR R3,S03FF
05498 E03054B8      MOVMR R3,PSBASE
(03802) ;
(03803) ;--- NEXT SYNC VALUE
(03804)      MOVIR R7,S0001
0549A 90700001      XORRM R7,VSSVNC
0549C F07054CF      ;
(03806) ;
(03807) ;--- FUNCTION LIST SELECTOR ISL2
(03808)      MOVMR R2,SIDSISL
0549E F02054B6      INCR R2,1
054A0 2621          MOVMR R3,ISVTS(R2)
054A1 F0340502      NEG R3
054A3 0030        MOVMR R3,ISVTS(R2)
054A4 E0340502      ;
(03813) ;
(03814) ;--- ALL DONE. SO RETURN
(03815) ;
(03816) ;
(03817) ;--- UPDATE XMTR BEFORE RETURNING
(03818) ;
054A6 0E70      DCS90      RETURN
(03819)      MOVMR R1,SIDSISL
054A7 2612      INCR R1,2
054A8 9C100502  ADDIR R1,ISVTS
054AA 00004036  JN0      TXS
SID FOR FUNC SEL.
POINT TO IFSEL3
COMPUT ADDR FOR IFSEL3
GO TO XMTR UPDATE MODULE

(03824) ;
(03825) ;--- LEAVE SPACE FOR VARIOUS VARIABLES
(03826) ;
(03827) ;
054AC 00000000  BAS1CB  DATA F'0.0'
054AE 00000000  BASOQB  DATA F'0.0'
054B0 00000000  BASDEC  DATA F'0.0'
054B2 00000000  BASDEC  DATA F'0.0'
054B4 0000      BASFCB  DATA 00
054B5 0000      SIDSTB  DATA 00

```

```

PAGE      96:      MAP MODULES FOR THE P A R C ALGORITHM      --- JAN. 30, 1980

#B486 #####          ( #3834 ) $IDSISL        DATA         $0
#B487 #####          ( #3835 ) PSSNAT         DATA         $0
#B488 #####          ( #3836 ) PSBASE         DATA         #####
#B489 #####          ( #3837 ) PSBITI         DATA         $0
#B49A #####          ( #3838 ) PSINFO         DATA         $0
#B4BB #####          ( #3839 ) PSMAH          DATA         1BF'$.0'

...
#B4CF #####          ( #3840 ) VSSYNH         DATA         $1
#B4D0 #####          ( #3841 ) VST           DATA         $0
#B4D1 #####          ( #3842 ) VBETA          DATA         $0
#B4D2 #####          ( #3843 ) VSPH8          DATA         $0
#B4D3 #####          ( #3844 ) VSPAR          DATA         $4###
#B4DA FFEF          ( #3845 ) VSTHR          DATA         $FFE$
#B4DE #####          ( #3846 ) VSGAP          DATA         $0
#B4D6 #####          ( #3847 ) SZSSHAT        DATA         $38$
#B4D7 #####          ( #3848 ) TSLIM          DATA         $0
#B4E0 #####          ( #3849 ) *LSRUN         DATA         SD
#B4E1 #####          ( #3850 ) ;             ;
#B4E2 #####          ( #3851 ) ;             ;
#B4E3 #####          ( #3852 ) !--- UPDATE TOP OF MEMORY
#B4E4 #####          ( #3853 ) ;             ;
#####4D8          ( #3854 ) TOESHEW=0L
#####200          ( #3855 ) 0L=TOESPRT
#B200          ( #3856 ) ADDR TOESHEW(,BUSIS)
#B20A          ( #3857 ) END

```


PAGE 98: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1980

DC821:	MS33E (MS484) (MS421)	
DC828:	MS347 (MS431) (MS479)	
DC831:	MS353 (MS448) (MS448)	
DC832:	MS361 (MS456) (MS465)	
DC833:	MS377 (MS478) (MS478)	
DC838:	MS3A2 (MS503) (MS532)	
DC851:	MS388 (MS558) (MS554)	
DC860:	MS38F (MS566) (MS574)	
DC861:	MS3D1 (MS584) (MS584)	
DC862:	MS3D4 (MS587) (MS595)	
DC863:	MS3E8 (MS608) (MS608)	
DC878:	MS3FC (MS629) (MS688)	
DC871:	MS3FE (MS627) (MS631)	(MS644) (MS664) (MS673)
DC872:	MS418 (MS641) (MS658)	
DC873:	MS424 (MS642) (MS678)	
DC874:	MS426 (MS673)	
DC875:	MS428 (MS646) (MS666)	(MS677)
DC876:	MS428 (MS688)	
DC877:	MS433 (MS692) (MS722)	
DC878:	MS448 (MS716) (MS717)	
DC879:	MS44E (MS722) (MS722)	
DC888:	MS482 (MS753) (MS727)	
DC881:	MS488 (MS681) (MS731)	
DC882:	MS486 (MS736)	
DC883:	MS481 (MS744) (MS745)	
DC884:	MS484 (MS688) (MS728)	(MS728) (MS723) (MS729) (MS739) (MS758)
DC886:	MS478 (MS756) (MS764)	
DC887:	MS478 (MS769) (MS771)	
DC889:	MS481 (MS768) (MS765)	(MS775)
DC890:	MS486 (MS348) (MS723)	(MS725) (MS725)
DC893:	MS182 (MS777) (MS728)	
DEC818:	MS2E6 (MS217) (MS316)	
DEC828:	MS3DF (MS219) (MS397)	
DEC88:	MS314 (MS293) (MS383)	
DEC728:	MS487 (MS232) (MS363)	
DEC721:	MS43C (MS233) (MS378)	
DMY8:	MS794 (MS436) (MS918)	(MS911) (MS913) (MS914)
EN8188:	MS0CD (MS286)	
EN8181:	MS0D5 (MS2592)	(MS2688)
EN8182:	MS0E4 (MS258)	(MS2588) (MS2684)
EN8111:	MS0E2 (MS2597)	(MS2688)
EN838:	MSFF6 (MS2412)	(MS2416)
EN848:	MS085 (MS2429)	(MS2437)
EN858:	MS018 (MS2446)	(MS2448)

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MAP MODULES FOR THE P A R C ALGORITHM

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```

EN001: 0001F (02442) (02451)
EN002: 00020 (02451) (02459)
EN003: 00030 (02476) (02483)
EN004: 0004A (02478) (02486) (02505) (02535)
EN005: 00054 (02480) (02491) (02549)
EN006: 00066 (02492) (02502)
EN007: 00068 (02489) (02509)
EN008: 0006E (02511) (02516)
EN009: 0007D (02522) (02532)
EN010: 00092 (02515) (02539)
EN011: 00095 (02541) (02547)
EN012: 000A3 (02513) (02553)
EN013: 000A6 (02555) (02562)
EN014: 000B2 (02498) (02566)
EN015: 000BC (02572) (02582)
EN016: 000C2 (00076) (02363)
EN017: 0007B (02126) (02228)
EN018: 00081 (00063)
EN019: 0006E (00074) (00078)
EN020: 000FB (00462) (00463)
EN021: 000F2 (01040) (01041)
EN022: 000F3 (01734) (01735)
EN023: 000C4 (00058) (00075)
EN024: 000A2 (01381) (01486) (01488)
EN025: 0002A (00047)
EN026: 0006F (00098) (00953)
EN027: 00028 (01831) (01833)
EN028: 000BC (01118) (01112)
EN029: 0010D (02993) (03046)
EN030: 00297 (02994) (03245)
EN031: 002A9 (02995) (03289)
EN032: 002C8 (02996) (03287)
EN033: 002D0 (02997) (03387)
EN034: 00355 (02999) (03441)
EN035: 00363 (03000) (03457)
EN036: 00376 (03001) (03476)
EN037: 00383 (03002) (03494)
EN038: 003C1 (03003) (03567)
EN039: 00306 (03004) (03588)
EN040: 00408 (03005) (03632)
EN041: 00435 (03006) (03693)
EN042: 00112 (02364) (02424) (02455) (02657)
EN043: 00176 (02951) (02952)
EN044: 00193 (02979) (02988)

```

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```

INCSZ: 04A0F (00277) (00070)
INCSZ: 04A0F (00279) (00095)
INFSB: 04A0B (00275) (00051)
INFTM: 04A07 (00273) (00034)
INCSZ: 04AF1 (00281) (00055)
INCSZ: 04AF1 (00271) (00029)
INCSZ: 04AF1 (00284) (02107)
INRC: 04C01 (00282) (01500)
INRX: 0004A (00090) (00090)
IN1: 00047 (00094) (00054)
IN2: 00043 (00090) (00092)
IN4: 0615E (02017)
IN8IN: 0615F (02761) (02709)
IN8OUT: 0486C (00081) (00269)
IN18: 05170 (02944)
IN18: 05170 (00059)
IN18: 05170 (02738) (02756)
IN18: 05170 (03367) (03369)
IN18: 05170 (00064) (00136)
IN18: 05170 (00065) (00138)
IN18: 05170 (00066) (00147)
IN18: 05170 (00067) (00152)
IN18: 05170 (00068) (00200)
IN18: 05170 (00295) (02509)
IN18: 05170 (00506) (00619)
IN18: 05170 (00544) (00583)
IN18: 05170 (00498) (00511)
IN18: 05170 (00728) (00754)
IN18: 05170 (00730) (00751)
IN18: 05170 (00591) (00608)
IN18: 05170 (00612) (00621)
IN18: 05170 (00625) (00633)
IN18: 05170 (00655) (00678)
IN18: 05170 (00435) (00707)
IN18: 05170 (02009) (02090)
IN18: 05170 (00062) (00201)
IN18: 05170 (00134) (00355)
IN18: 05170 (00202) (00206)
IN18: 05170 (01206) (01433)
IN18: 05170 (00036) (00038)
IN18: 05170 (02097) (02098)
IN18: 05170 (00039) (00067)
IN18: 05170 (01404)
IN18: 05262 (03184) (03190)

ISVT18: 05170 (00065) (00066) (00067) (00068) (00130) (00203) (00270) (00347)
ISVT28: 05170 (02767) (02784) (02932) (02945) (03141) (03143) (03145) (03347)
ISVT38: 05170 (03386) (03517) (03519) (03521) (03810) (03812) (03822)
ISVT48: 05170 (00286) (00272)
ISVT58: 05170 (00219) (00274) (00350)
LSRUN: 05170 (02539) (02553) (02660) (03653) (03661) (03713)
LOOP0: 05170 (00634)
LOOP1: 05170 (00756)
LOOP2: 05170 (00756)
LOOP4: 05170 (00756)
LOOP6: 05170 (00756)
LOOP7: 05170 (00756)
LOOP8: 05170 (00756)
LOOP9: 05170 (00756)
N00: 05170 (00788) (00930) (01407) (01408) (01557) (02044) (02045) (02059)
N00RBYT: 05170 (00269) (00346)
N00R: 05170 (00456) (00457)
N00X: 05170 (00455)
N00A: 05170 (01206) (01433)
N00T1: 05170 (00036) (00038)
N00MAX: 05170 (02097) (02098)
N00FTR: 05170 (00039) (00067)
N00L1: 05170 (01404)
N00B1: 05262 (03184) (03190)

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PAGE 181: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 35, 1985

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OQB2: 0526A (03105) (03196)
OQB3: 0519A (02967) (02978)
OQB4: 051E2 (02968) (03054)
OQB5: 051EA (02969) (03061)
OQB6: 051FB (02970) (03069)
OQB7: 051F8 (02971) (03076)
OQB8: 05206 (02972) (03098)
OQB9: 0547C (03422) (03768)
OQB0: 05487 (03423) (03781)
OQB1: 05488 (03299) (03336)
OQB2: 05489 (03125) (03336) (03361) (03518) (03798) (03881)
OQB3: 0548A (03331) (03617) (03255) (03272) (03288) (03429) (03618) (03792) (03795) (03837)
OQB4: 0548B (02951) (03026) (03624) (03788) (03838)
OQB5: 05487 (03283) (03852) (03827) (03894) (03183) (03839)
OQB6: 054F1 (02622) (02627) (03751) (03775) (03835)
OQB7: 054EF (02588) (02638) (02546) (02561) (02598) (02621)
OQB8: 04086 (01737) (01751)
OQB9: 05888 (01748) (01764) (02818)
OQB0: 0589A (01749) (02818)
OQB1: 0589B (01054) (01057) (01444)
OQB2: 0589C (01055) (01444)
OQB3: 05829 (05638) (05666)
OQB4: 058A6 (05485) (05479)
OQB5: 05898 (05476) (05493) (05788)
OQB6: 0589B (05477) (05788)
OQB7: 0582C (01849) (01981)
OQB8: 0583F (01071) (01077)
OQB9: 0582A (01168) (01171)
OQB0: 05811 (01185) (01113) (01136) (01382)
OQB1: 0581D (01147) (01149)
OQB2: 05846 (01092) (01093) (01097)
OQB3: 05852 (01272) (01273) (01268)
OQB4: 0586D (01283) (01442)
OQB5: 05865 (01294) (01439)
OQB6: 05875 (01381) (01311)
OQB7: 05878 (01318) (01314) (01317)
OQB8: 0588F (01278) (01441)
OQB9: 04088 (05879) (05126)
OQB0: 04098 (05882) (05346)
OQB1: 058AF (01197) (01198) (01422)
OQB2: 05868 (05891) (05942)
OQB3: 058A9 (05782) (05758)

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PAGE 182: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1980

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SSTX:      04A1D (00213) (00222) (00289) (00789)
SC81B:     051C8 (03026) (03029)
SC82B:     051DA (03048) (03083)
SC821:     051E9 (03088) (03082)
SC822:     051EE (03088) (03088)
SC823:     051F7 (03073) (03077)
SC824:     051F9 (03064) (03081)
SC831:     0520B (03092) (03096) (03101)
SC841:     0520F (03109) (03111)
SC851:     0521C (03118) (03121)
SC852:     05261 (03191) (03192)
SC853:     05298 (03244) (03250)
SC854:     052AB (03257) (03266)
SC8541:    052BE (03270) (03280)
SC855:     052C6 (03296) (03293)
SC856:     052D8 (03303) (03321)
SC857:     052D8 (03306) (03314)
SC858:     052EF (03318) (03327)
SC86B:     052F8 (03345)
SC87B:     052FD (03110) (03353)
SH8RC:     04F0F (00141) (00151)
SHIFT:     00051 (01007) (01008)
SI081SL:   054B6 (02931) (03139)
SI087B:    054B5 (03403) (03417)
SIGNAL:     00090 (01029) (02007)
SIZES:     0516B (02775) (02819)
START:     0000B (01497)
SVT8:      00302 (00060) (00120) (00442) (02426) (03161) (03165) (03535) (03541)
SVT111B:   00464 (00454) (00486) (02231)
SVT115B:   00468 (00457) (00458) (02038)
SVT117B:   0046C (00488) (00489) (00784)
SVT118B:   0046E (00489) (01485) (00783)
SVT50B:     003E6 (00442) (00443) (00047)
SVT51B:     003EE (00444) (00445) (00076)
SVT54B:     003F2 (00445) (00446) (00924)
SVT56B:     00404 (00446) (00447) (01480) (01643)
SVT63B:     0040E (00447) (00448) (01506)
SVT68B:     00412 (00448) (00449) (01529)
SVT74B:     0041A (00449) (00450) (01558)
SVT79B:     00426 (00450) (00451) (01583)
SVT83B:     0042E (00451) (00452) (01642)
SVT98B:     00446 (00452) (00453) (02048)
SVT99B:     0044A (00453) (00454) (02233)

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PAGE 183: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1988

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SYNCS:          #B1CB (#2934) (#3023)
SV38FLGS:      1FFCE (#0061) (#0143)
SZ38SHAT:      #64D6 (#3201) (#3750) (#0146) (#0216) (#0210) (#0353)
TSLIM:         #64D7 (#3048) (#3047)
TSRC:          #4F13 (#0132) (#2095)
TOESNEW:       #64D8 (#3054) (#3056)
TOESPRAT:      #6208 (#0430) (#3055)
TR91B:         #512A (#2740) (#2755)
TR82B:         #6135 (#2739) (#2766)
TR82B:         #613F (#2762) (#2775)
TR83B:         #5148 (#2795) (#2004)
TR8DC:         #5116 (#0070) (#2735)
TRAN:          #0008 (#1772) (#1703)
TX8:           #4036 (#0008) (#0201) (#3023)
VSBETA:        #64D1 (#3327) (#3540) (#3600) (#3842)
VSDCL:         #6114 (#0297) (#2474) (#3600) (#2659)
VSCAP:         #54D6 (#3012) (#3551) (#3846)
VSPAR:         #54D3 (#3336) (#3409) (#3501) (#3844)
VSPHB:         #54D2 (#3300) (#3319) (#3546) (#3581) (#3602) (#3843)
VSSYN:         #5113 (#2411) (#2410) (#2658)
VSSYN:         #54CF (#3042) (#3120) (#3354) (#3492) (#3805) (#3840)
VST:           #54D8 (#3295) (#3534) (#3576) (#3841)
VSTHR:         #54D4 (#3650) (#3707) (#3845)
VADAP:         #0008 (#2192)
VCHECK:        #0072 (#1505) (#1521) (#1633) (#1635)
VCONT1:        #0046 (#1667) (#1660) (#1578)
VEND:          #0076 (#1634) (#1641)
VGAP:          #001A (#1613) (#1620)
VHRC:          #4F2D (#0133) (#0140) (#0340) (#2124)
VHTX:          #4A25 (#0209) (#0212) (#0208) (#0795)
VLOOP:         #0023 (#1629) (#1633)
VLOOP1:        #0036 (#0060) (#0066)
VLOOP2:        #000E (#0799) (#0811)
VLOOP3:        #001A (#0790) (#0811)
VLOOP4:        #001C (#0813) (#0816)
VLOP1:         #002D (#2109) (#2110)
VLOP2:         #0071 (#2221) (#2223)
VMEGA:         #0008 (#1591) (#1593) (#1594)
VPCRC8:        #4EC2 (#1730) (#2019) (#2026) (#2252)
VPCRC9A:       #4F06 (#2022) (#2242)
VPCRC81:       #4F0E (#2018) (#2250)
VPCRC88:       #0013 (#2019) (#2059)
VPCRC8Z:       #0100 (#2021) (#2252)
VPCXTX8:       #4C04 (#1044) (#1453) (#1459) (#1662)

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PAGE 184: MAP MODULES FOR THE P A R C ALGORITHM --- JAN. 30, 1985

VPCTH8A: B4C92 (B1486) (B1682)
 VPCTH8I: B4B02 (B1482) (B1668)
 VPCTH8S: B0030 (B1483) (B1637)
 VPCTH8Z: B0109 (B1485) (B1662) (B0773) (B0969)
 VPICH38: B4A8E (B0486) (B0767)
 VPICH38A: B4A16 (B0772) (B0968)
 VPICH38I: B4AF6 (B0766) (B0967)
 VPICH38S: B0060 (B0767) (B0930)
 VPICH38Z: B00EA (B0769) (B0969)
 VPRE1: B0037 (B2134) (B2222)
 VQ1: B004C (B2166) (B2166) (B2169)
 VQ3: B0061 (B2165) (B2178) (B1584)
 VQUARI: B0046 (B1579) (B1581)
 VQUAH2: B004C (B1587) (B1588)
 VQUAH3: B004F (B1579) (B1588)
 VTRAR: B000D (B2047) (B2052)
 WAIT: B0056 (B0630) (B0631)
 WRD4: B0003 (B0009) (B0126)
 WRD6: B0004 (B0078) (B0129)

LINE WITH ERRORS: B (MAP VERSION 000101.10) E- B

PAGE 1:

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      *** IOSDC ***
      ARVIND S. ARORA      FEB 11, 1988

      IOS-2 PROGRAM TO INTERFACE THE BITSTREAM FROM THE PARC ALGORITHM
      TO THE MODEN. THE SOURCE CODER AT THE TRANSMITTER STORES THE OUTPUT
      IN A DOUBLE BUFFER, AND THE DECODER REQUIRES ITS INPUT TO BE IN A
      CIRCULAR BUFFER. THIS PROGRAM OUTPUTS THE CONTENTS OF THE DOUBLE
      BUFFERS THROUGH THE IOS2 TO THE DIGITAL INTERFACE, AND INPUTS THE
      RECEIVED BITSTREAM OF THE DIGITAL INTERFACE TO THE CIRCULAR BUFFER.
      THE PROGRAM OPERATES IN FULL DUPLEX FOR COMPATIBILITY WITH THE
      RS-423 MODEN USED IN THE PRESENT SYSTEM.

      REGISTER & FLAG USAGE:
      RB: XMTR BUFFER SWITCH, RB=ADSTX TO INDICATE BUFFER 1
      R1: XMTR BUFFER ADDRESS POINTER
      R2: RCVR BUFFER ADDRESS POINTER
      F1: FLAG TO INDICATE MODE OF OPERATION,
          F1-CLEAR TO INDICATE INITIALIZE
          F1-SET TO INDICATE NORMAL OPERATION
      P1: FLAG SET INDICATES RECEIVER DATUM AVAILABLE
      P2: FLAG SET INDICATES XMTR READY FOR NEXT DATUM

      ----- IOS-2 MODULE
      ---
      SYMBOL DEFINITIONS
      ADSTXA=D'26700'
      ADSTXB=D'27700'
      SZSTX =D'100'
      ENDSTXA=ADSTXA+SZSTX-1
      ENDSTXB=ADSTXB+SZSTX-1
      AD8RCC=D'29800'
      SZ8RC=D'1024'
      END8RCC=AD8RCC+SZ8RC-1
      CLCRATE=8ECC4

```


PAGE 4:

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ADDRCC: 07140 (00040) (00042) (00061) (00100) (00092)
ADSTXA: 06464 (00034) (00037) (00060) (00091) (00082)
ADSTXB: 06C34 (00035) (00038) (00073) (00081) (00082)
CLCRATE: 06C44 (00044) (00063)
ENDSRCC: 07547 (00042) (00099)
ENDSTXA: 06525 (00037) (00070)
ENDSTXB: 06CF8 (00038) (00080)
IOSINIT: 00004 (00060) (00063) (00080) (00093) (00099) (00101)
IOSLOOP: 00007 (00066) (00070) (00083) (00088) (00099) (00101)
IOSSTOP: 00025 (00103)
IOSDCS: 0001F (00067) (00097)
RCC8: 00400 (00041) (00042)
SZSRC: 00000 (00036) (00037) (00038)
TX8: 0000C (00066) (00072)
TXAS: 0000F (00077)
TXBS: 00017 (00073) (00087)

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LINES WITH ERRORS: 0 (MAP VERSION 000101.10) E- 0