

REPORT DOCUMENTATION PAGE

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IMPROVED MODELS AND UNDERSTANDING FOR FIELD-REVERSED CONFIGURATION (FRC) THRUSTERS

Robert Martin¹, Eder Sousa², Robert Lilly², Michael Kapper²

¹AIR FORCE RESEARCH LABORATORY,
²ERC INC.,
EDWARDS AIR FORCE BASE, CA USA



U.S. AIR FORCE

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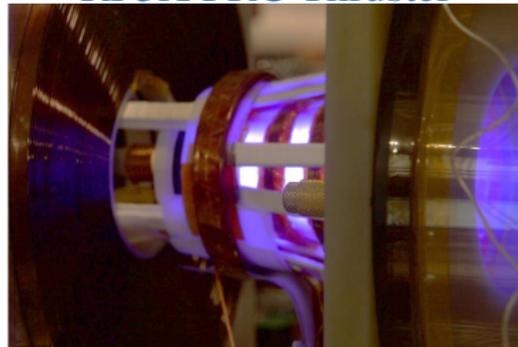
- 1 INTRODUCTION & CHALLENGES
- 2 MODEL ENHANCEMENTS
- 3 LEARNING IN PARAMETER SPACE
- 4 CONCLUSION & FUTURE DIRECTIONS



Field-Reversed Configuration:

- Concept from Fusion Energy
 - Challenge Scaling Down for Propulsion

RP3X FRC Thruster

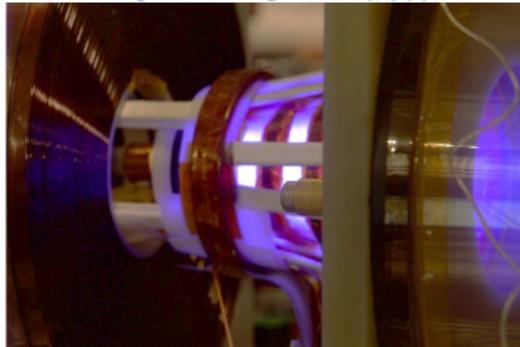




Field-Reversed Configuration:

- Concept from Fusion Energy
 - Challenge Scaling Down for Propulsion
- Electrodeless (+ Limits Erosion)

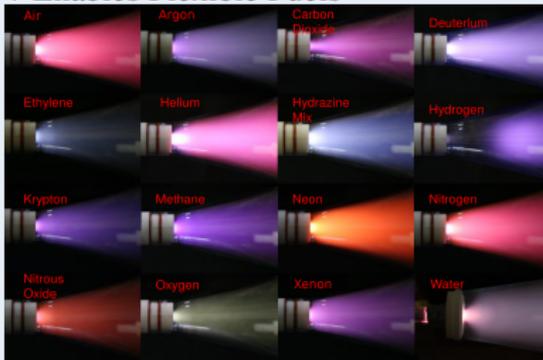
RP3X FRC Thruster





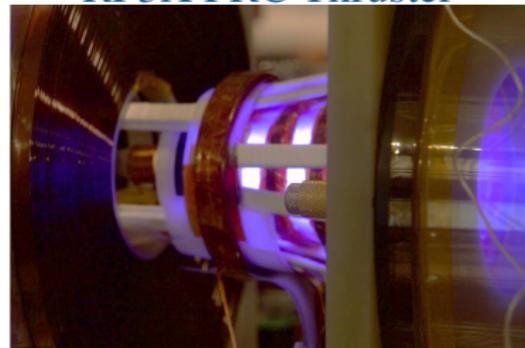
Field-Reversed Configuration:

- Concept from Fusion Energy
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- Electrodeless (+ Limits Erosion)
- Acceleration Mechanism $J \times B$
 - + Enables Flexible Fuels



Pancotti, et al, "Adaptive Electric Propulsion for ISRU Missions", 20th Adv. Space Prop., 11/2014

RP3X FRC Thruster

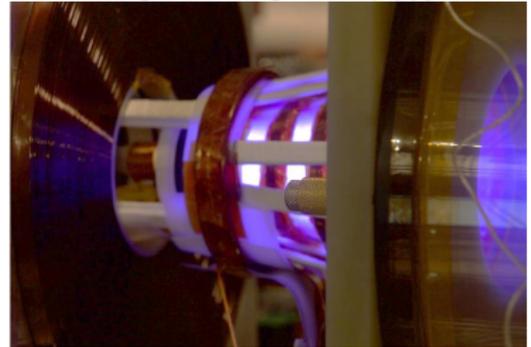




Field-Reversed Configuration:

- Concept from Fusion Energy
 - Challenge Scaling Down for Propulsion
- Electrodeless (+ Limits Erosion)
- Acceleration Mechanism $J \times B$
 - + Enables Flexible Fuels
- Pulsed Operation
 - + Tunable Thrust/ISP
 - Complex Coupled Dynamics
 - High Dimensional Parameter Space

RP3X FRC Thruster



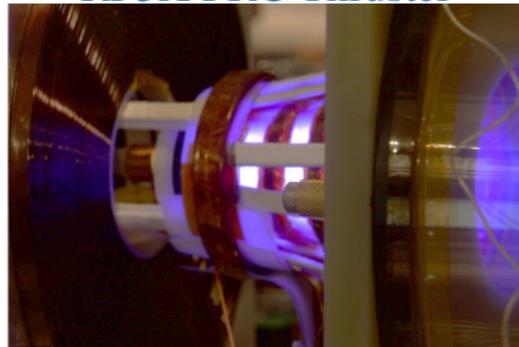


Field-Reversed Configuration:

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 - Complex Coupled Dynamics
 - High Dimensional Parameter Space
- Common Challenges/Benefits for EM
 - + MPD/PIT/PPT

Complex Devices to Design

RP3X FRC Thruster





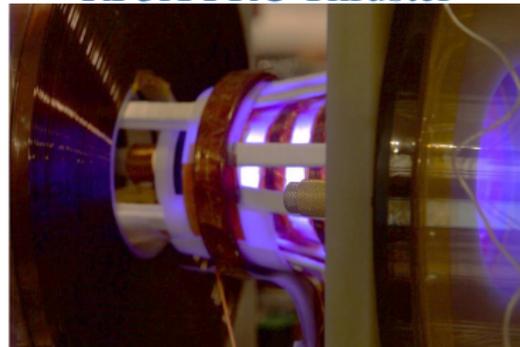
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 - Complex Coupled Dynamics
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- Common Challenges/Benefits for EM
 - + MPD/PIT/PPT
 - + Similar Tools Required

Complex Devices to Design

Pose Significant Modeling Challenge

RP3X FRC Thruster

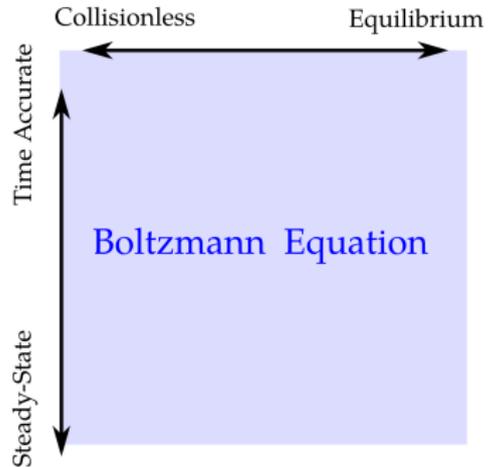




The Boltzmann Equation for $f(\mathbf{x}, \mathbf{v}; t)$:

$$\frac{\partial f_s}{\partial t} + \mathbf{v} \cdot \frac{\partial f_s}{\partial \mathbf{x}} + \frac{q_s}{m_s} (\mathbf{E} + \mathbf{v} \times \mathbf{B}) \frac{\partial f_s}{\partial \mathbf{v}} = \left(\frac{\partial f_s}{\partial t} \right)_{coll}$$

Range of Validity

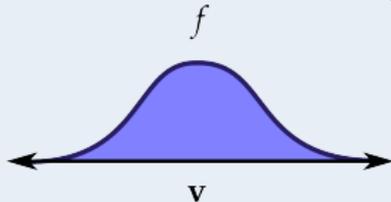




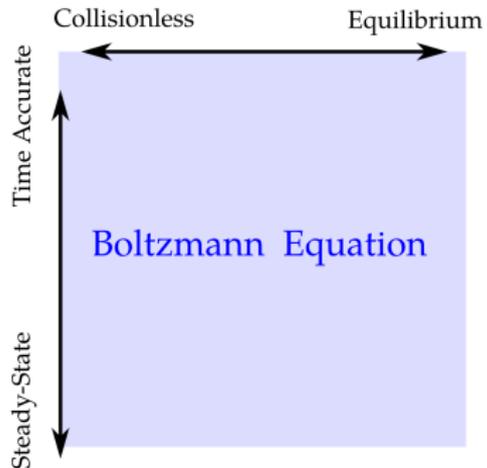
TOOL DEVELOPMENT SPANNING REGIMES

The Boltzmann Equation for $f(\mathbf{x}, \mathbf{v}; t)$:

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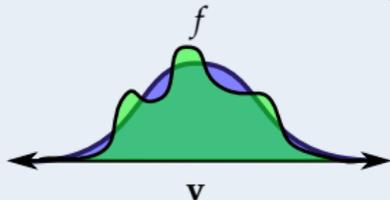
Range of Validity



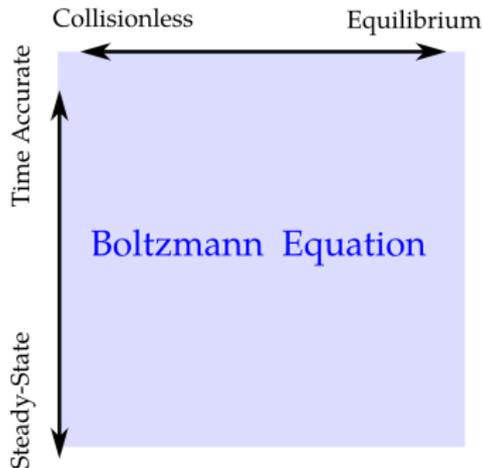


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Range of Validity





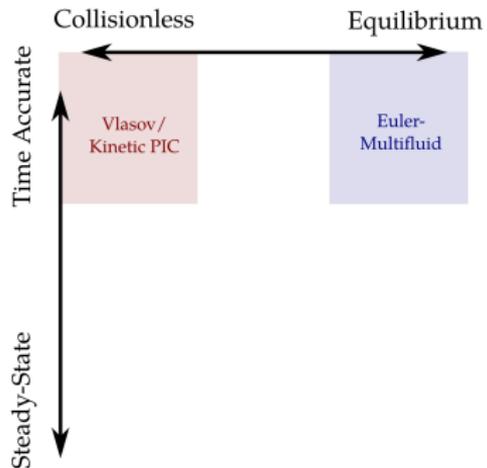
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● Collisionality Limits:

$$(\text{Vlasov}) 0 \leftarrow \left(\frac{\partial f_s}{\partial t} \right)_{coll} \rightarrow \infty (\text{Euler})$$

Range of Validity





The Boltzmann Equation for $f(\mathbf{x}, \mathbf{v}; t)$:

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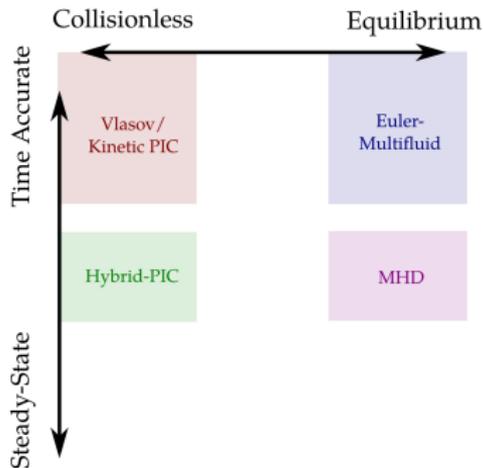
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- Ohm's Law:

$$(m_e \ll m_i) \rightarrow \frac{\partial f_e}{\partial t} \equiv 0$$

Range of Validity





The Boltzmann Equation for $f(\mathbf{x}, \mathbf{v}; t)$:

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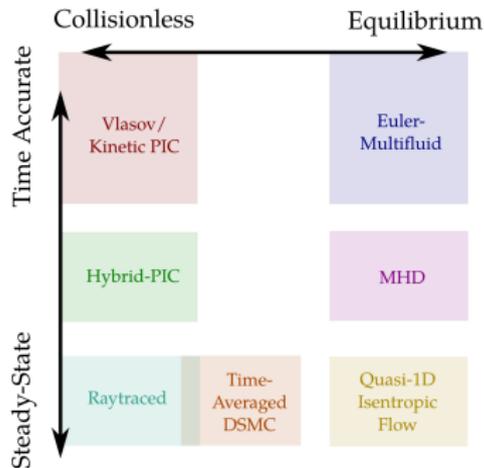
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- Steady-State Solutions:

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Range of Validity





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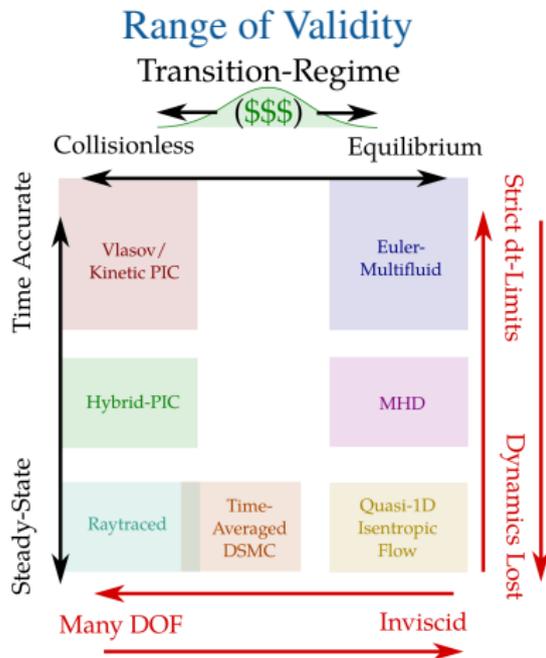
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$$(m_e \ll m_i) \rightarrow \frac{\partial f_e}{\partial t} \equiv 0$$

- Steady-State Solutions:

$$\frac{\partial}{\partial t} \equiv 0$$

Limits Exchange Accuracy for Cost





The Boltzmann Equation for $f(\mathbf{x}, \mathbf{v}; t)$:

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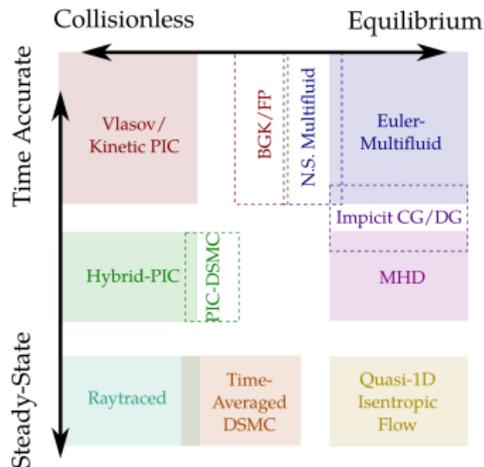
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- Steady-State Solutions:

$$\frac{\partial}{\partial t} \equiv 0$$

Limits Exchange Accuracy for Cost
Transition Incurs Costs to Limit

Range of Validity





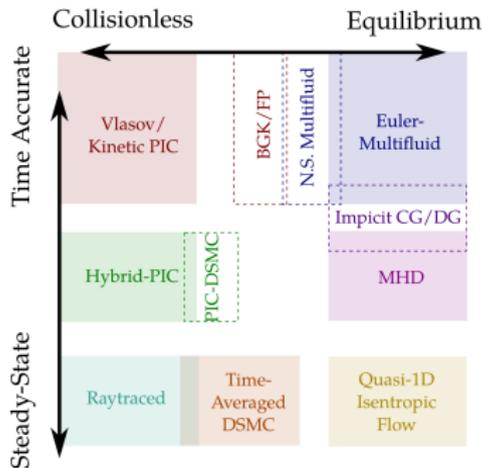
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- Collisionality Limits:
(Vlasov) $0 \leftarrow \left(\frac{\partial f_s}{\partial t} \right)_{coll} \rightarrow \infty$ (Euler)
- Ohm's Law:
 $(m_e \ll m_i) \rightarrow \frac{\partial f_e}{\partial t} \equiv 0$
- Steady-State Solutions:
 $\frac{\partial}{\partial t} \equiv 0$

Limits Exchange Accuracy for Cost
Transition Incurs Costs to Limit
 $(v = 0 \neq v \rightarrow 0)$
 But Relaxes/Removes Assumptions

Range of Validity





The Boltzmann Equation for $f(\mathbf{x}, \mathbf{v}; t)$:

$$\frac{\partial f_s}{\partial t} + \mathbf{v} \cdot \frac{\partial f_s}{\partial \mathbf{x}} + \frac{q_s}{m_s} (\mathbf{E} + \mathbf{v} \times \mathbf{B}) \frac{\partial f_s}{\partial \mathbf{v}} = \left(\frac{\partial f_s}{\partial t} \right)_{coll}$$

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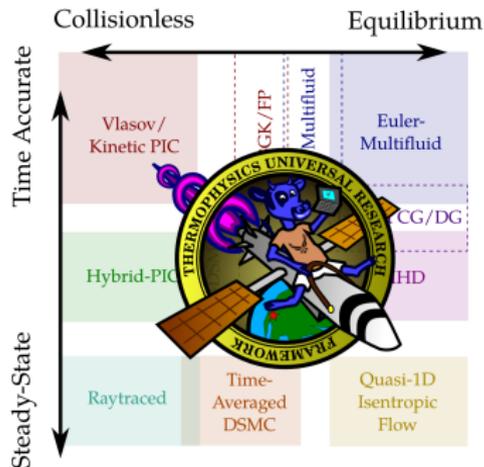
- Steady-State Solutions:

$$\frac{\partial}{\partial t} \equiv 0$$

Limits Exchange Accuracy for Cost
Transition Incurs Costs to Limit

TURF: For Exploring Efficient Methods
Minimizing Cost/Accuracy & Redundancy

Range of Validity

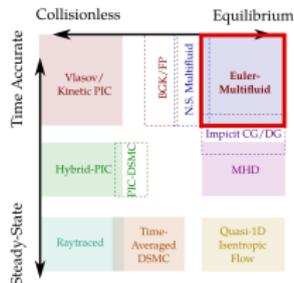
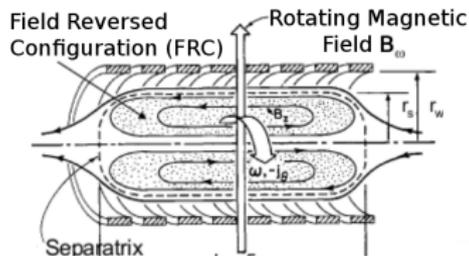




Apollo Formation Simulations:

- RMF $\rightarrow j_{\theta} \rightarrow B_z$ -Reversal

DG FRC-Formation

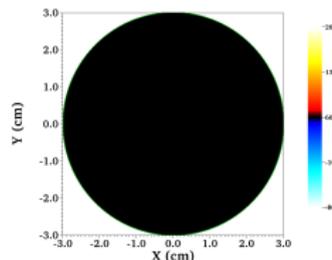
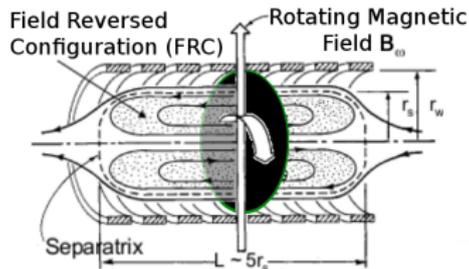




Apollo Formation Simulations:

- RMF $\rightarrow j_\theta \rightarrow B_z$ -Reversal
- Initially Conditions:
Fully Ionized Xe Gas
 $n_i=n_e=10^{20}/m^3$
60G Bias (Z) + 60G RMF @ 1MHz

DG FRC-Formation



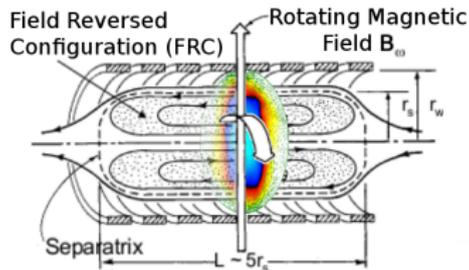
$t=0\omega$



Apollo Formation Simulations:

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Fully Ionized Xe Gas
 $n_i = n_e = 10^{20} / m^3$
60G Bias (Z) + 60G RMF @ 1MHz
- Strong Reversal B_z Reversal by 180°

DG FRC-Formation



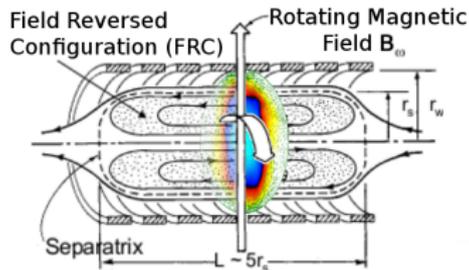
$t=0-0.5\omega$



Apollo Formation Simulations:

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Fully Ionized Xe Gas
 $n_i=n_e=10^{20}/m^3$
60G Bias (Z) + 60G RMF @ 1MHz
- Strong Reversal B_z Reversal by 180°
- Reversal Weakens, 180° - 360°

DG FRC-Formation



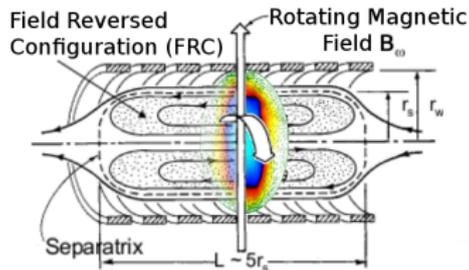
$$t=0.5-1.0\omega$$



Apollo Formation Simulations:

- RMF $\rightarrow j_\theta \rightarrow B_z$ -Reversal
- Initially Conditions:
Fully Ionized Xe Gas
 $n_i=n_e=10^{20}/m^3$
60G Bias (Z) + 60G RMF @ 1MHz
- Strong Reversal B_z Reversal by 180°
- Reversal Weakens, 180° - 360°
- Cycle Repeats
(But Lower Amplitude)

DG FRC-Formation



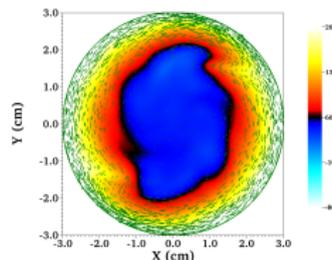
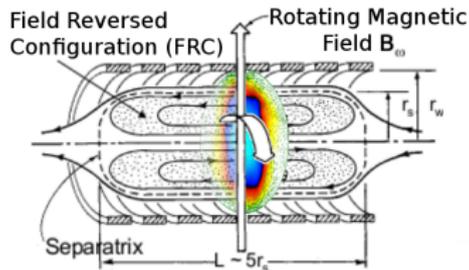
$$t=1.0-2.0\omega$$



Apollo Formation Simulations:

- RMF $\rightarrow j_{\theta} \rightarrow B_z$ -Reversal
- Initially Conditions:
Fully Ionized Xe Gas
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60G Bias (Z) + 60G RMF @ 1MHz
- Strong Reversal B_z Reversal by 180°
- Reversal Weakens, 180° - 360°
- Cycle Repeats
(But Lower Amplitude)
- Parameter Space is being Explored

DG FRC-Formation



$t=1.0-2.0\omega$

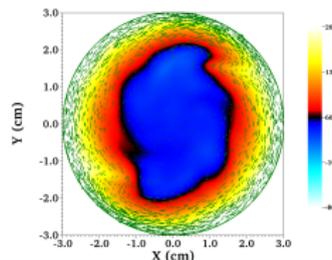
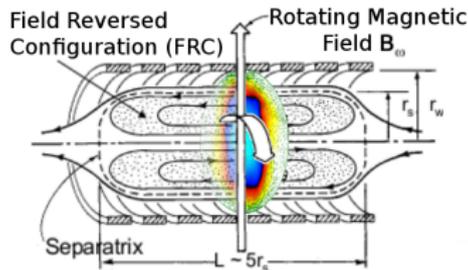


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- Parameter Space is being Explored

Also Needs Experimental Validation!

DG FRC-Formation



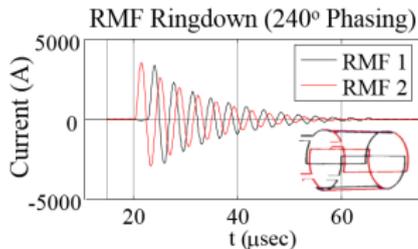
$$t=1.0-2.0\omega$$



High Fidelity Validation:

- FRCs are Dynamic Pulsed Devices

DG FRC-Formation



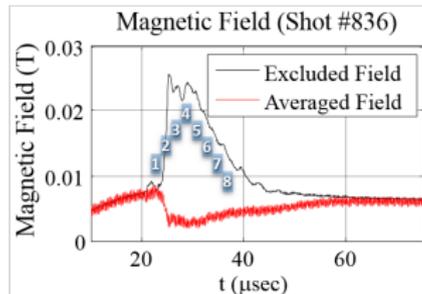
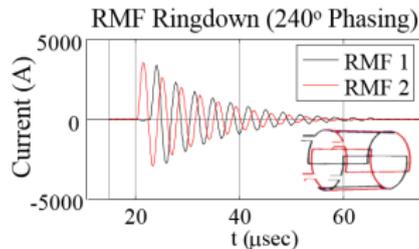
MSNW Ar FRC Formation



High Fidelity Validation:

- FRCs are Dynamic Pulsed Devices
- Ext. Probes avoid Disruption ...but Mostly Limited View

DG FRC-Formation



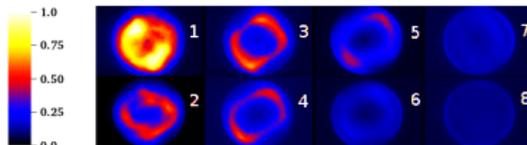
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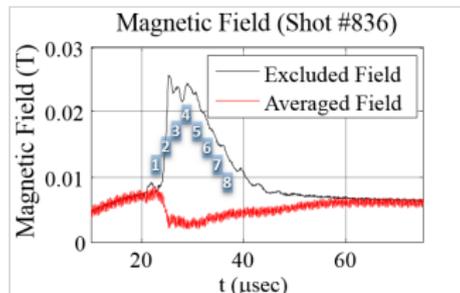
High Fidelity Validation:

- FRCs are Dynamic Pulsed Devices
- Ext. Probes avoid Disruption
...but Mostly Limited View
- Fast Camera:
Absolute Magnitudes Difficult
Relatively High Dimensional

DG FRC-Formation



(False Color Intensity - MSNW Fast Camera Studies)



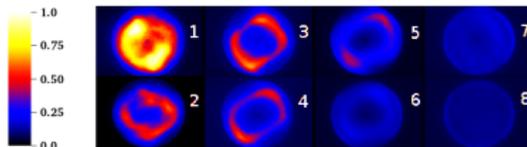
MSNW Ar FRC Formation



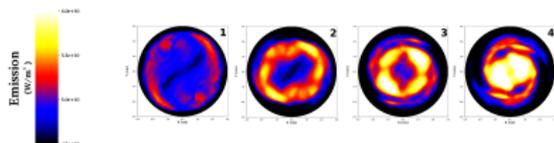
High Fidelity Validation:

- FRCs are Dynamic Pulsed Devices
- Ext. Probes avoid Disruption ...but Mostly Limited View
- Fast Camera:
Absolute Magnitudes Difficult
Relatively High Dimensional
- Emission from IonMix (n_e, T_e) Table
- Plotted at Equivalent ω

DG FRC-Formation



(False Color Intensity - MSNW Fast Camera Studies)



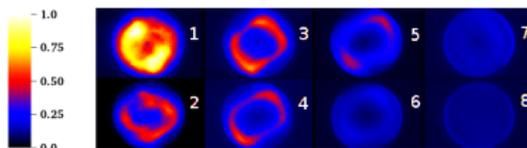
(Apollo Multifluid Simulation Emission Intensity)



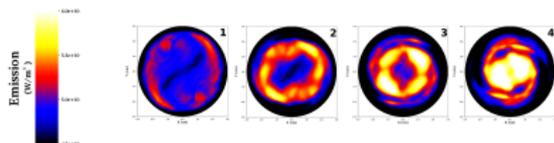
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Absolute Magnitudes Difficult
Relatively High Dimensional
- Emission from IonMix (n_e, T_e) Table
- Plotted at Equivalent ω
- Similar Structures in 2 & 3
Despite Different Conditions

DG FRC-Formation



(False Color Intensity - MSNW Fast Camera Studies)



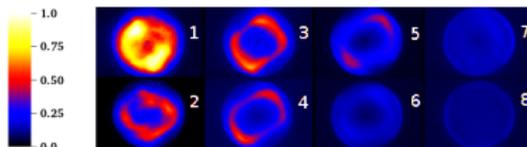
(Apollo Multifluid Simulation Emission Intensity)



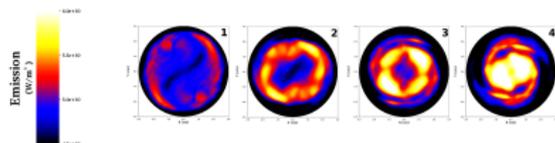
High Fidelity Validation:

- FRCs are Dynamic Pulsed Devices
- Ext. Probes avoid Disruption ...but Mostly Limited View
- Fast Camera:
Absolute Magnitudes Difficult
Relatively High Dimensional
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Despite Different Conditions
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Simulation Intensifies in 4+

DG FRC-Formation



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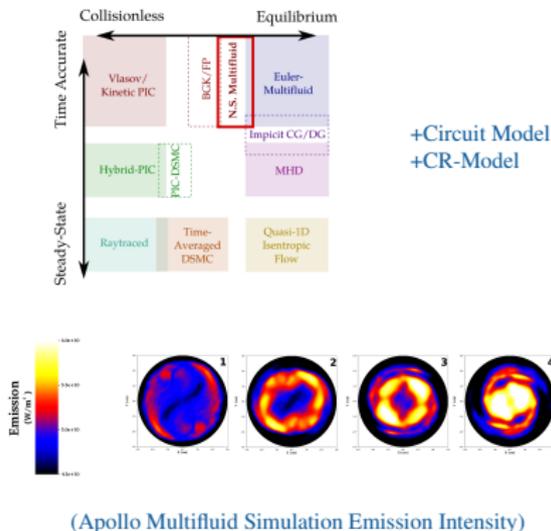


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Model Needs Additional Physics

DG FRC-Formation





AFRL Model Development/Project Synergies:

Model	Need	Platform	Project	Progress	Demo
Circuit	BC/Energy Cons.	TURF	1 & 2	Runtime Arbitrary ODE B.C.s	Lorenz DSMC Inflow
Radiative	Physics/Energy Cons.	R&D	3	Full Level-Grouped Ar Model	Abrantes PhD (UCLA 2018)
Multi-Fluid	Physics/Stability	Apollo	4	N.S./Braginskii	Poiselle/Taylor Couette
Multi-Fluid	Physics/Stability	TURF/R&D	4	Hybrid Entropy/Energy Cons.	Einfeldt/Step/Cylinder/Jet
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Projects:

1. In-House AFRL 6.2 Research
2. AFOSR Comp Math Lab-Task (New), PO: Fahroo
3. AFOSR Plasma/Electro-energetics Lab-Task, PO: Marshall
4. AFOSR Space Propulsion & Power, PO: Birkan



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N.S. MULTIFLUID DEFINITIONS

$$\partial_t \mathbf{Q} + \nabla \cdot \mathbf{F}^{Hyp} + \nabla \cdot \mathbf{F}^{Para} = \mathbf{S}^{EM} + \mathbf{S}^{ie}$$

\mathbf{Q}	\mathbf{F}^{Hyp}	\mathbf{F}^{Para}	\mathbf{S}^{EM}	\mathbf{S}^{ie}
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Progress:

Classic (Newtonian) and Braginskii Formulations Implemented



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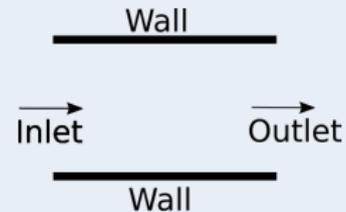
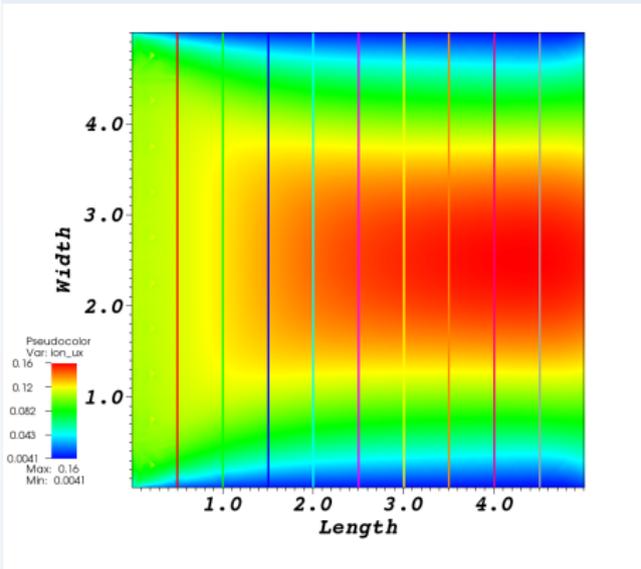
Classic (Newtonian) and Braginskii Formulations Implemented

Validation Cases:

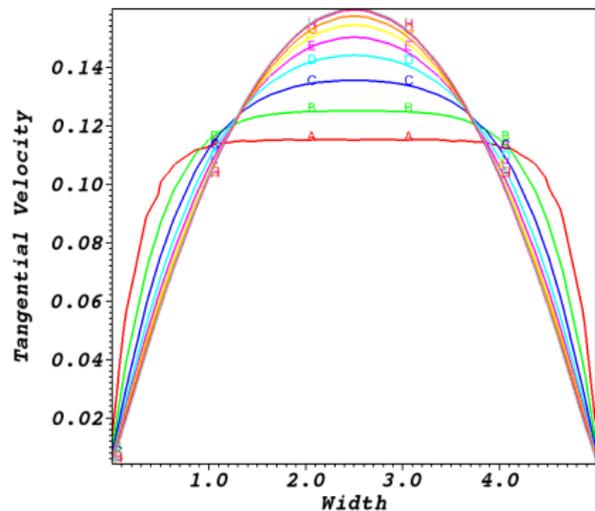
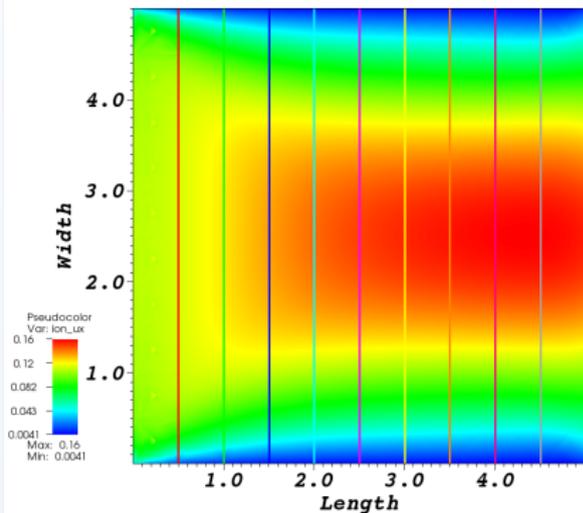
Newtonian	Braginskii
Channel Flow: ✓	Hartman: (Pending)
Cylindrical Couette: ✓	Magneto-Rotational Instability: (Pending)



CHANNEL FLOW RESULTS



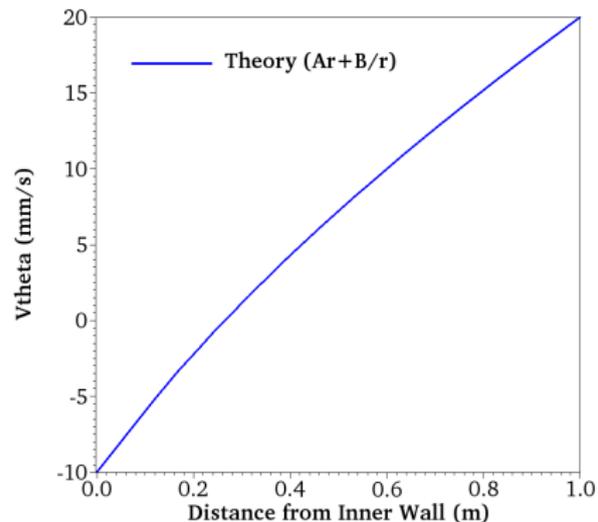
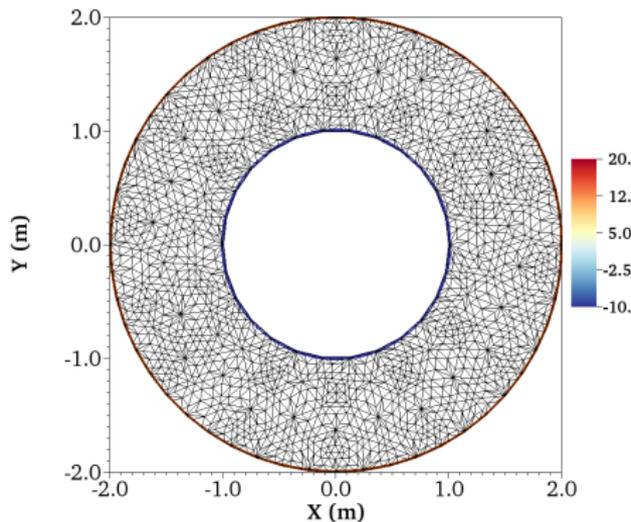
- A solid, no slip, boundary is enforced at the walls
- The input boundary uses a fixed Dirichlet condition. The flow is low subsonic (0.10 Mach).
- The exit using a von Neumann boundary condition on all variables except for pressure, which is set to the inlet condition.
- The chosen Reynolds number is approximately 30.



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TAYLOR COUETTE RESULTS



- Counter rotating solid, no slip, boundary is enforced at the inner/outer walls
- Reynolds number independent solution is rapidly established
- Good Agreement with Analytic Solution Attained



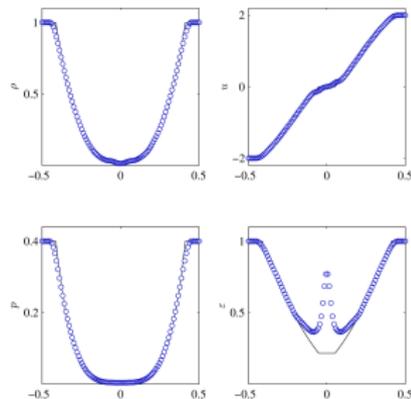
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- Strong Rarefactions often break Fluid Codes (i.e. Negative Pressures/Artificial Heating)
- Low- β Numerical Instabilities in Apollo (Low- T_e)

Einfeldt 1-2-3 : Energy



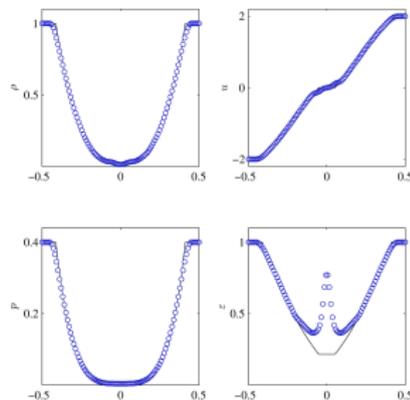
Solution to Einfeldt's 1-2-3 problem as obtained with conservation of energy. (Kapper PhD, OSU, '09)



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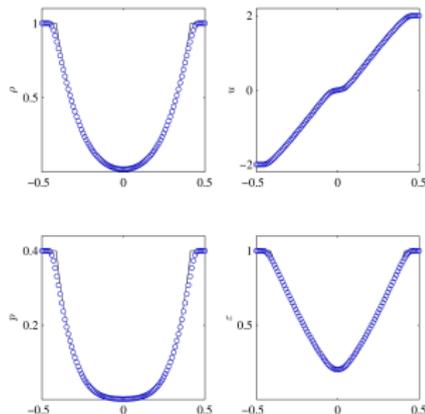
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Einfeldt 1-2-3 : Entropy



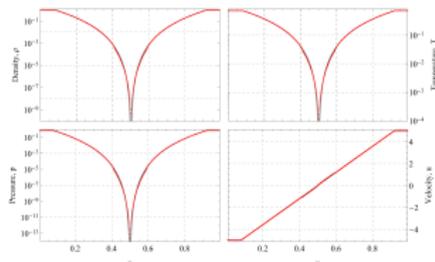
Solution to Einfeldt's 1-2-3 problem as obtained with conservation of entropy. (Kapper PhD, OSU, '09)



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- Updated Method Enables Extreme Pressure Ratios (Kapper, 2018)

Einfeldt Vacuum Limit : Entropy



Solution to Einfeldt's Vacuum Limit (Mach 5, $\gamma=7/5$) problem as obtained with conservation of entropy and new linearization. (Kapper 18)

$$T/T_0=10^{-4}$$

$$\rho/\rho_0=10^{-9}$$

$$P/P_0=10^{-13}$$



Entropy Formulation:

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$$\begin{bmatrix} Q \\ \rho_e \\ \rho_e \mathbf{u}_e \\ \mathcal{E}_e \\ \rho_i \\ \rho_i \mathbf{u}_i \\ \mathcal{E}_i \end{bmatrix} \rightarrow \begin{bmatrix} Q \\ \rho_e \\ \rho_e \mathbf{u}_e \\ \rho_e s_e \\ \rho_i \\ \rho_i \mathbf{u}_i \\ \mathcal{E}_i \end{bmatrix}$$

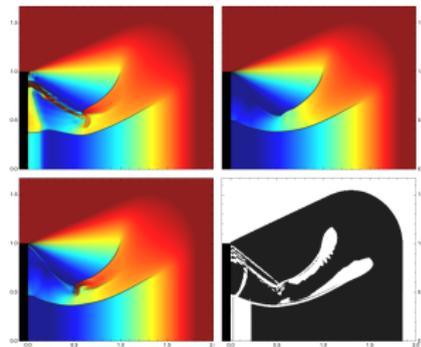
$$s_e = P_e / \rho_e^\gamma$$



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Linde-Roe Corner Expansion



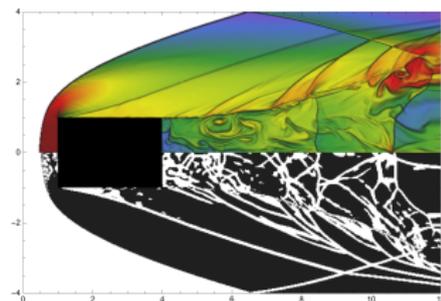
Top Left: Energy Conservation
Top Right: Entropy Conservation
Bottom Left: Hybrid Solution
Bottom Right: Hybrid Compression Flag
(Kapper '18)



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Mach 10.2 Cylinder



Plot of $\log T$ plus simulated Schlieren (top) and Hybrid Switch (bottom)

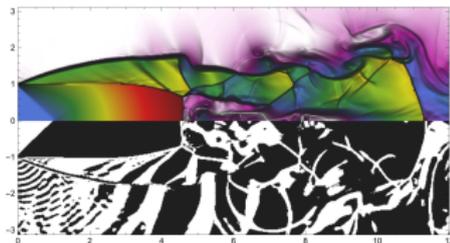
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Mach 1.5 Underexpanded Jet



Plot of Mach plus simulated Schlieren (top) and Hybrid Switch (bottom)

(Kapper '18)



Complex Design Space for Pulsed EM:

- Device Geometry: Length/Diameter/Pitch Angle/etc.
- Gas Flow: Mass Flow/Injection/Mixture/Rate/Density/Pre-Ionization
- Electrical: Energy/Coil Shape/Switching Speed/Frequency/Phase/Bias Field

15+ Dimensional Design Space...
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- Theory: Simplified Analysis Bounding Envelope/Reducing Dimension
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RMF Characterized by Dimensionless Parameters:

- $\lambda = R/\delta$, where $\delta = (2\eta/\mu_o\omega)^{1/2}$ is the classical skin depth
- $\gamma = \omega_{ce}/\nu_{ei}$, where $\nu_{ei} = \eta(ne^2/m_e)$ is the electron-ion collision frequency

These parameter can be expressed in terms of RMF intensity, frequency and the plasma resistivity:

$$\bullet \lambda = R \left(\frac{\mu_o\omega}{2\eta} \right)^{1/2} \quad \gamma = \frac{1}{e} \left(\frac{B\omega}{n\eta} \right)$$

Theory: Hugrass (Aust. J. Phys. 38, 157 1985)

Semi-Emperical: Milroy (PoP 6, 2771 1999)

(RMF penetration in a fixed ion plasma column)

Question: Does this Relationships hold in MFPM?

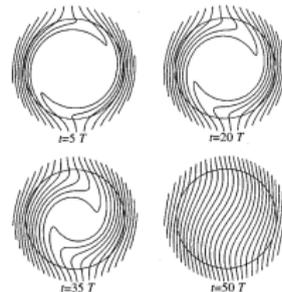


FIG. 1. Evolution of magnetic field lines as the RMF penetrates a plasma column.

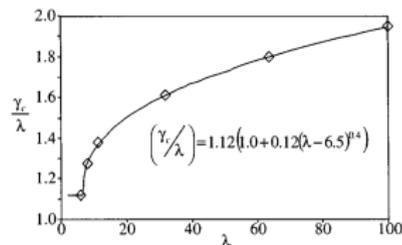


FIG. 4. Critical value of γ vs λ .

Milroy, PoP 6, 2771 (1999)



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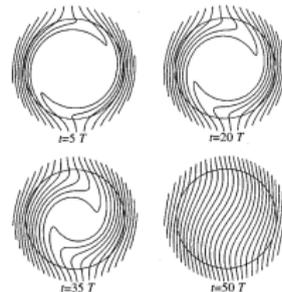


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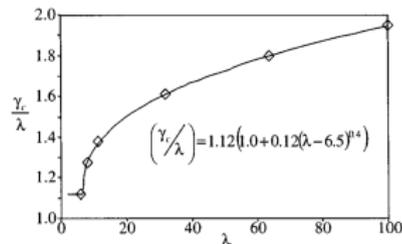


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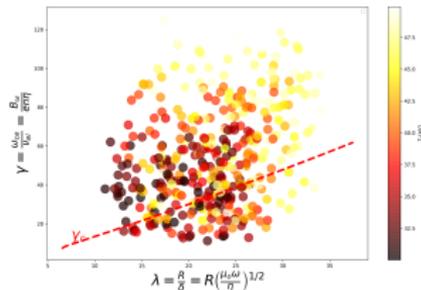
Milroy, PoP 6, 2771 (1999)



Machine Learning on MFPM Data:

- Randomly Explored (ω , B_ω , T_e) with MFPM
- Points Plotted w.r.t. (λ , γ) from Theory

MFPM Simulated Dataset



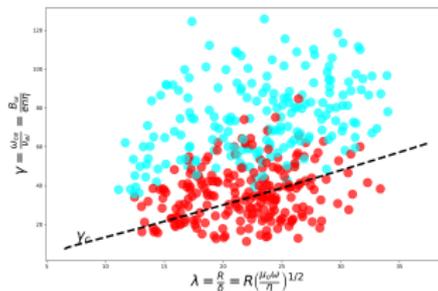
- Density, $n = 1 \times 10^{19} m^{-3}$
- $2\pi \times 10^5 Hz < \omega < 10\pi \times 10^5 Hz$
- $5G < B_\omega < 30G$
- Electron temperature, $30eV < T_e < 50eV$



Machine Learning on MFPM Data:

- Randomly Explored (ω, B_ω, T_e) with MFPM
- Points Plotted w.r.t. (λ, γ) from Theory
- Theory: Necessary but Not Sufficient

Observed B_z -Reversal



Confusion Matrix

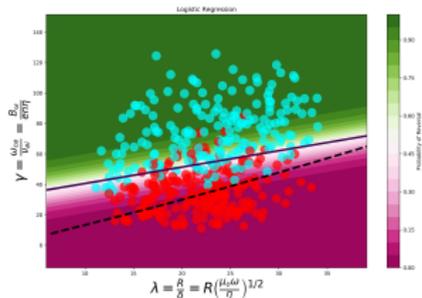
-	Pred No	Pred Yes
Actual No	23	21
Actual Yes	0	36



Machine Learning on MFPM Data:

- Randomly Explored (ω, B_ω, T_e) with MFPM
- Points Plotted w.r.t. (λ, γ) from Theory
- Theory: Necessary but Not Sufficient
- Classical Classifiers Explored
- Fewer False Positives & Higher γ_c

Predicted B_z -Reversal Logistic Regression



Confusion Matrix

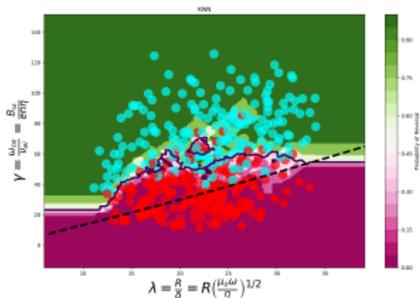
	Pred No	Pred Yes
Actual No	39	5
Actual Yes	4	32



Machine Learning on MFPM Data:

- Randomly Explored (ω, B_ω, T_e) with MFPM
- Points Plotted w.r.t. (λ, γ) from Theory
- Theory: Necessary but Not Sufficient
- Classical Classifiers Explored
- Fewer False Positives & Higher γ_c
- Balancing Complexity vs. Accuracy?

Predicted B_z -Reversal K-Nearest Neighbors



Confusion Matrix

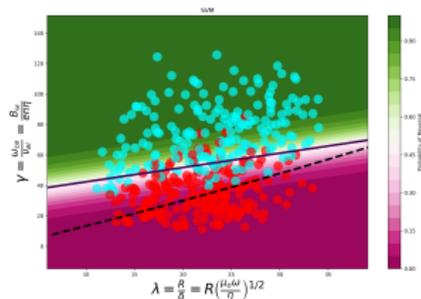
-	Pred No	Pred Yes
Actual No	38	6
Actual Yes	5	31



Machine Learning on MFPM Data:

- Randomly Explored (ω, B_ω, T_e) with MFPM
- Points Plotted w.r.t. (λ, γ) from Theory
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- Classical Classifiers Explored
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- Balancing Complexity vs. Accuracy?

Predicted B_z -Reversal Support Vector Machines



Confusion Matrix

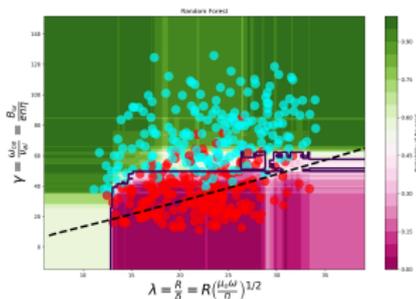
-	Pred No	Pred Yes
Actual No	39	5
Actual Yes	4	32



Machine Learning on MFPM Data:

- Randomly Explored (ω, B_ω, T_e) with MFPM
- Points Plotted w.r.t. (λ, γ) from Theory
- Theory: Necessary but Not Sufficient
- Classical Classifiers Explored
- Fewer False Positives & Higher γ_c
- Balancing Complexity vs. Accuracy?

Predicted B_z -Reversal Random Forest



Confusion Matrix

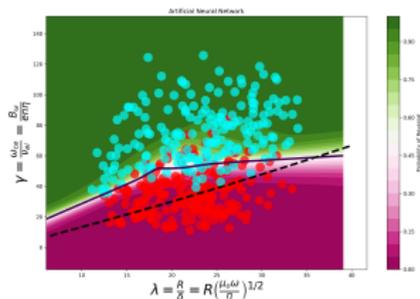
-	Pred No	Pred Yes
Actual No	37	7
Actual Yes	3	33



Machine Learning on MFPM Data:

- Randomly Explored (ω, B_ω, T_e) with MFPM
- Points Plotted w.r.t. (λ, γ) from Theory
- Theory: Necessary but Not Sufficient
- Classical Classifiers Explored
- Fewer False Positives & Higher γ_c
- Balancing Complexity vs. Accuracy?
- Artificial Neural Network (ANN) with Stochastic Gradient Descent
- Better Classification w/o Extreme Complexity

Predicted B_z -Reversal ANN



Confusion Matrix

-	Pred No	Pred Yes
Actual No	39	5
Actual Yes	2	34



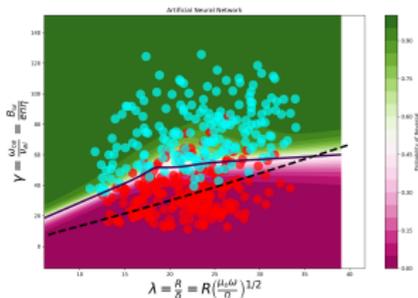
Machine Learning on MFPM Data:

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- Points Plotted w.r.t. (λ , γ) from Theory
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- Better Classification w/o Extreme Complexity

Open Questions:

- Classification Space (λ , γ) Right for MFPM?
- Relevant Dimensions beyond 2D?
- Data Requirements in 3+D Classification?
- Do Experiments Exhibit Similar Trends?

Predicted B_z -Reversal ANN



Confusion Matrix

-	Pred No	Pred Yes
Actual No	39	5
Actual Yes	2	34



LEARNING: RMF PENETRATION

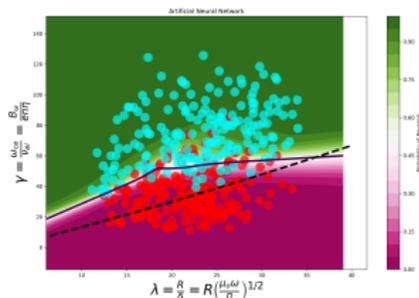
Machine Learning on MFPM Data:

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Predicted B_z -Reversal ANN



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Actual No	39	5
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ACTIVE SUBSPACE FOR REVERSAL?

Curse of Dimensionality:

- Optimization Cost Exponential w/ Dim





Curse of Dimensionality:

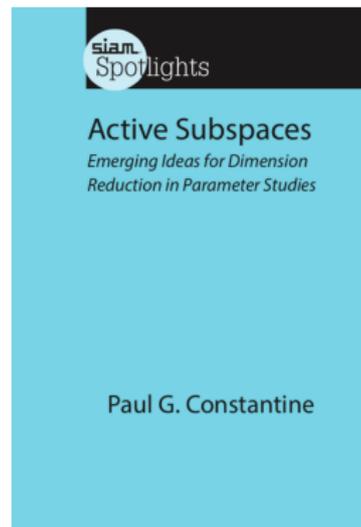
- Optimization Cost Exponential w/ Dim
- Not all Dimensions Created Equal!





Curse of Dimensionality:

- Optimization Cost Exponential w/ Dim
- Not all Dimensions Created Equal!





Curse of Dimensionality:

- Optimization Cost Exponential w/ Dim
- Not all Dimensions Created Equal!
- First Step: Identify Dominant Dimensions



ACTIVE SUBSPACES

GOAL

Make intractable high-dimensional parameter studies tractable by discovering and exploiting low-dimensional structure.

DEFINE

First $n < m$ eigenvectors of $\int \nabla f \nabla f^T \rho dx$

DISCOVER

First $n < m$ eigenvectors of $\frac{1}{N} \sum_{i=1}^N \nabla f_i \nabla f_i^T$

APPROXIMATION

$$f(x) \approx g(W_T^T x)$$

INTEGRATION

$$\int f(x) \rho dx$$

OPTIMIZATION

minimize $f(x)$



<http://activesubspaces.org>

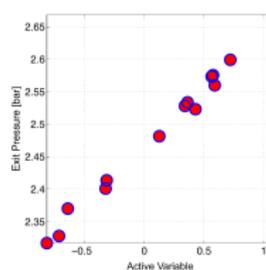


Curse of Dimensionality:

- Optimization Cost Exponential w/ Dim
- Not all Dimensions Created Equal!
- First Step: Identify Dominant Dimensions
- Often Works in Complex Looking Problems (Dominant Low-D Structure is Common)



Active subspaces helped us optimize an expensive scramjet model.



- Multiphysics model of hypersonic scramjet
- 7 input parameters
- No gradients
- Noisy function evaluations
- 2 hours per evaluation

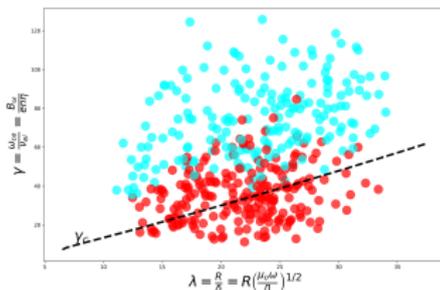
DIMENSION REDUCTION: 7 to 1

<http://activesubspaces.org>



Curse of Dimensionality:

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- Often Works in Complex Looking Problems (Dominant Low-D Structure is Common)
- Low-D Structure in Random FRC Data?



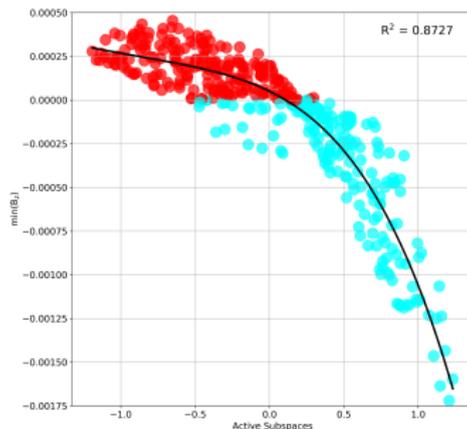
Random Points:

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- $5G < B\omega < 30G$
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Curse of Dimensionality:

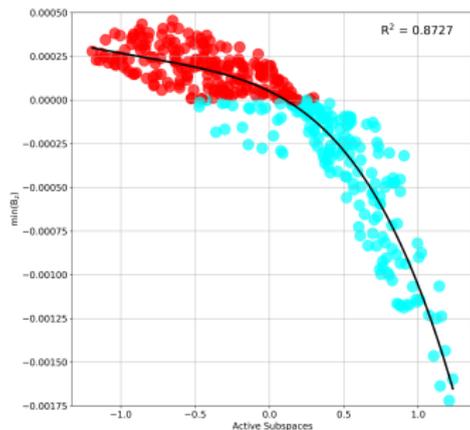
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- Low-D Structure in Random FRC Data?
- Active Subspace for $\text{Min}(B_z)$ in (ω, B_ω, T_e)





Curse of Dimensionality:

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- Needs Experimental Validation
 - Result Model Artifact?
 - Exp. has Many More Dimensions



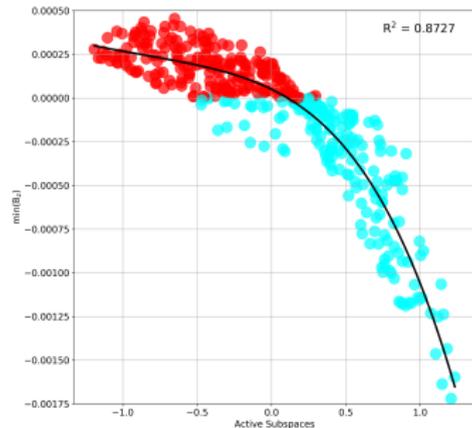


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- Needs Experimental Validation
 - Result Model Artifact?
 - Exp. has Many More Dimensions

EP Exp Produce Data Faster than Simulation

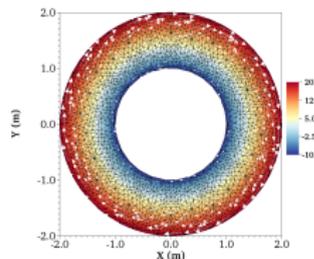
Active Subspaces in the Experimental Loop?





AFRL Pulsed EP Progress:

- **Enhanced Models**
 - Viscous Multi-Fluid
 - Hybrid Entropy/Energy Conservation
- **Improved Understanding**
 - Classifiers & Machine Learning
 - Reduced Dimensionality



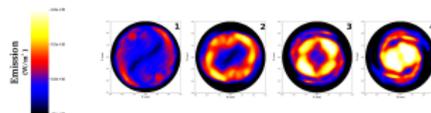
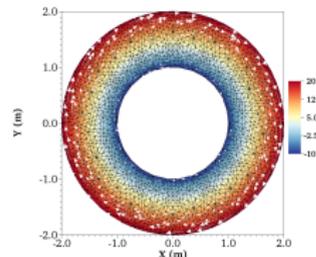


AFRL Pulsed EP Progress:

- **Enhanced Models**
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Near Term Goals:

- **Integrate Models**
 - Porting DG MFPM to TURF
 - Verify Braginskii Implementation
 - Circuit BCs
 - Radiation Losses
- **Re-Engage with Experimental Community**





AFRL Pulsed EP Progress:

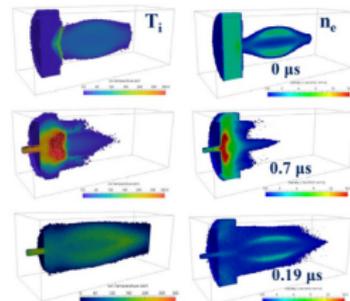
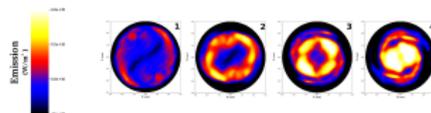
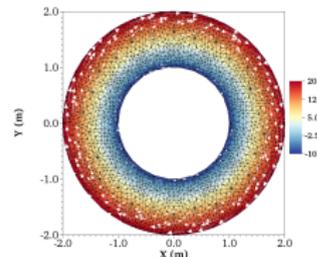
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Near Term Goals:

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Long Term Goals:

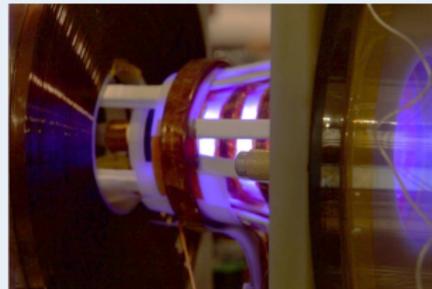
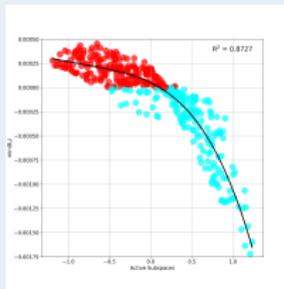
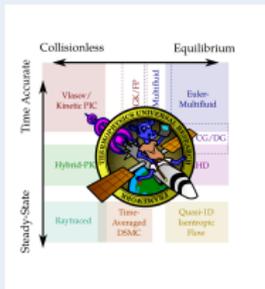
- **Cross-Verify MFPM/Kinetic Assumptions**
- **Quantify Extrapolative Model Power**
- **Optimize Design of Pulsed EP in High-D**
- **Actively Control Pulsed EP Systems**



HYPERS Simulation Results for MSX
Omelchenko, *Phys Rev E*. **92**, 023105, 2015



Thank You



Work Supported through AFOSR Task 17RQCOR465 (PO: Birkan)

Questions?



The Braginskii equations:

- Implementation of Parabolic Flux: $\mathbf{\Pi}_\alpha$, and \mathbf{q}_α (Viscosity & Heat Flux)
- The viscosity begins with the classic Newtonian tensor (1).

$$\overleftrightarrow{\mathbf{W}} = \nabla \mathbf{u} + \nabla \mathbf{u}^T - \left(\frac{2}{3} \nabla \cdot \mathbf{u} \right) \overleftrightarrow{\mathbf{I}} \quad (1)$$

- $\overleftrightarrow{\mathbf{W}}$ is rotated into the magnetic field coordinate frame.
- $\overleftrightarrow{\mathbf{W}}_r$ is then decomposed into parallel, perpendicular, and gyroviscous \mathscr{W}_i
- Each of \mathscr{W}_i components is multiplied by a scalar η_i .

Finally,

$$\mathbf{\Pi}_\alpha = rot_{lab} \left(\sum_{i=0}^{N=4} \eta_i \mathscr{W}_i \right) \quad (2)$$