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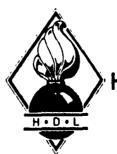
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NORMAL MODE ANALYSIS OF A FUZE SUPPORT STRUCTURE USING NASTRAN (PART I)

by
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April 1972



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Details of illustrations in this document may be better studied on microfiche

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ABSTRACT

A support structure for a proposed guided missile electronic fuze was designed with the aid of the NASA Structural Analysis (NASTRAN) linite element structural analysis program. Two differently mounted mock-up fuze models were fabricated and tested under a sinusoidal 2-g load applied in the transverse, as well as the axial, direction. Good correlation was obtained between the values of natural frequency measured experimentally and those obtained from the digital computer program.

CONTENTS

ABST	PRACT
1.	INTRODUCTION
2.	COMPUTER-AIDED DESIGN
3.	EXPERIMENTAL STUDY12
	3.1 Model Description
4.	RESULTS18
5.	CONCLUSIONS19
€.	RECOMMENDATIONS
APPI	ENDIX A. INPUT DATA TO NASTRAN FOR FUZE MODEL A-128
APPI	ENDIX B. SAMPLE OF NASTRAN OUTPUT FOR FUZE MODEL A-131
TABI	LES
	No. 10 10 10 10 10 10 10 10 10 10 10 10 10
I.	
II.	
III.	
IV.	Fuze mock-up weight
v.	
-	
FIG	
1.	
2	Fore-mounted fuze structural model (F-1)
3	
	mock-up models9
4.	
5	
6.	
7.	NASTRAN mathematical model for A-1 model11
8.	
9.	Structural mcck-up of fuze components14
10	
	center of gravity, and accelerometers
11.	Structural fuze model showing dummy component arrangement,
	center of gravity, and accelerometers
12.	First structural mask-un halo shaker alarker alarker alarker
13	
14.	
15.	
	mock-up
16.	
	mock-up21

1. INTRODUCTION

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A design study was made of a guided missile electronic fuze support structure. The structure was required to carry the loads developed during all missile environments and to have its lowest natural frequency as high as possible.

This natural frequency was intended to be high enough to insure that driving forces at this frequency would not be encountered during the life of the missile. On the other hand, if the natural frequency and internal damping were high enough, even though the driving forces were at frequencies near the structure's natural frequency, the transmissibility would be low enough to prevent the occurrence of large displacements.

The basic geometry of the fuze housing was initially assumed to be a rectangular box, $5 \times 5 \times 6$ in. The total weight of the fuze and supporting structure was 10 lb, with 3 lb being allotted for the structure itself.

There were two phases of the design study. Phase one was a computer-mided analytical study of proposed configurations that utilized the NASA Structural Analysis (NASTRAN) digital computer program for finite element analysis of structures. Phase two was an experimental study of two structures tested to obtain results for comparison with the values obtained from phase one.

When the study began, the crientation of the rectangular fuze box with respect to the missile launch axis had not been determined, nor had it been decided whether the fuze would be attached to the fore or aft side of the 13-in. inner diameter bolting ring; the bolting ring was already part of the missile structure. A more desirable strut span was possible by the aft mounting than by the fore mounting procedure.

For these reasons two different orientations and two different mounting adapters were studied. In particular, analyses were undertaken assuming box orientations with both the five- and six-in. dimension in the direction of the missile axis.

Experimentally, two different types of mounting pads were investigated: one for forward mounting of the fuze, and the other for aft mounting. The letters A and F are used to designate aft and fore mounting, respectively. The numbers 1 and 3 are used to designate the six-in. (fig. 1 and 2) and the five-in. dimension oriented in the direction of the missile axis, respectively.

2. COMPUTER-AIDED DESIGN

The NASTRAN computer program for finite element analysis of structures was utilized to design the fuze support structure. NASTRAN is a finite element computer program for structural analysis of almost every kind of structure and type of construction. Structural elements are provided for specially representation of the more common types of construction, including rods, beams, shear panels, plates, and shells of revolution. Composite types of construction, such as the fuze structure analyzed in this report, are treated by combinations of these elements or by the use of "general" elements tailored to a specific requirement. Two of the formats available with the program, the static analysis format (Format 1) and the normal mode analysis (Format 3), were used in the design process.

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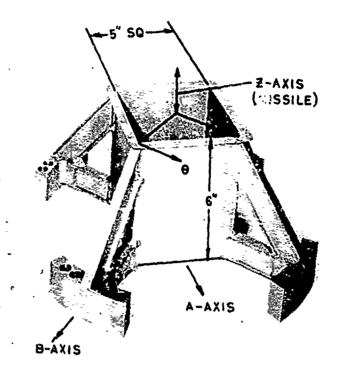


Figure 1. Aft-mounted fuze structural mode: (A-1).

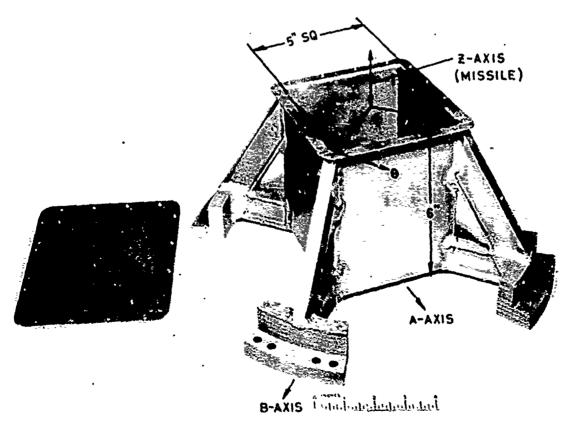


Figure 2. Fore-mounted fuze structural model (F-1).

The static format was used to determine the stress level in the structure due to an equivalent 50-g launch load, and the normal mode analysis was used to determine the mode shapes and natural frequencies of the fuze support.

Figure 1 shows the aft-mounted model (A-1) that was studied experimentally. The box portion of the fuze was connected to four pads, which bolt to the mounting ring in the missile, by four struts whose cross section was an I-beam, and by four shorter legs of similar cross section (fig. 3, 5, and 6). The various fuze components were arranged in a predetermined fashion inside the box, and 6-1b/ft³ polyurethane foam was used to encapsulate these in place. Figure 7 shows one quarter of the mathematical model used in the NASTRAN program for the aft-mounted support structure. It was necessary to use only one quarter of the structure in the analytical investigation, since symmetry about two perpendicular planes exists for the A-1 case.

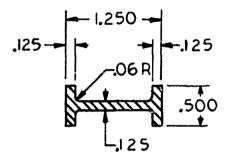


Figure 3. Cross section of legs and struts for A-1 and F-1 structural mock-up models.

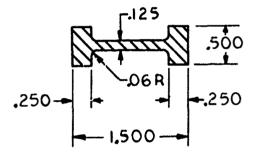


Figure 4. Cross section of legs and struts for A-3 mathematical model.

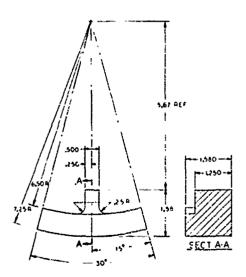


Figure 5. Aft-mounted pad.

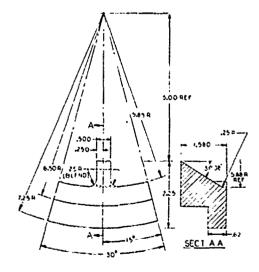


Figure 6. Fore-mounted pad.

In figure 7, one and two digit numbers refer to grid points. Numbers 101 through 148 identify homogeneous quadralateral membrane and bending elements, 201 through 207 identify simple beam elements, and 301 through 309 identify rod elements. The quadralateral elements are capable of resisting moments and forces applied in any direction with the exception that they cannot withstand a moment applied about an axis normal to the large faces of the element. The rod elements can withstand only tension or compression forces and torsional moments, whereas the bar elements can withstand axial forces, shear in two directions, as well as bending and torsional moments.

The quadralateral elements were used to represent the box walls that were 1/16-in. thick and made from 6061-T6 aluminum alloy. The bar elements were used to represent the struts and the legs and were taken to be of "I" cross section. These also were made of 6061-T6 aluminum. The mounting pads were not included in the mathematical model, but their effect was assumed to constrain grid points 23 and 48 (the ends of the legs and struts) to such an extent that no displacements or rotations were permitted.

The rod elements represent the polyurethane foam and were taken to be oriented only in the Z-direction. In reality, they should be oriented in all directions, but there was no convenient NASTRAN element to represent this continuum situation. To include other rods in the X and Y directions would have made it necessary to have a large number of additional grid points and would have significantly increased the computer time required. The total area of the rods equalled the area of the top face of the box. When viewing the computer results with this mathematical model, it will be necessary to remember that the deflections obt. ned in the X and Y directions will be larger than expected, since the stiffness of the polyurethane foam in these directions was neglected.

Typical input and output from the computer is shown in the appendix for normal mode analysis format and for the model shown in figure 4.

The weight of the fuze box and internal support structure was approximately 1 lb, leaving 6 lb for the weight of the simulated fuze components. These 6 lb were distributed in the mathematical model as follows: The top and bottom of the can were each assumed to carry 1.5 lb, and each of the four sides was assumed to carry 0.75 lb. This weight was distributed uniformly on each of the areas in question and was entered into the computer as nonstructural mass. This particular distribution was chosen because the foam material was thought to be capable of distributing the load uniformly and was capable of transmitting shear loading to the box sides. The center of gravity of the simulated fuze components was, therefore, assumed to lie at the geometric center of the box. Three different configurations were investigated on the computer:

- Model A-1; the aft-mounted box with the 6-in. dimension in the direction of the missile axis.
- Model F-1; a fore-mounted support structure of the same orientation,
- Model A-3; an aft-mounted model with a 5-in. dimension in the direction of the missile axis.

The grid-point computer input for the three models is given in appendix Λ .

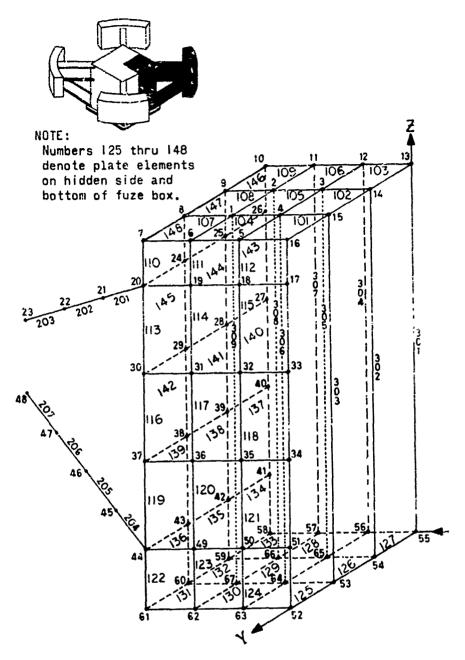


Figure 7. NASTRAN mathematical model for A-1 model.

For models A-1 and F-1, with I-shaped cross sections having the dimensions given in figure 3 (which correspond to the physical dimensions of the experimental models tested), the results for natural frequency given in tables I and II were obtained. The results for natural frequency for model A-3 are given in table III. For model A-3, less material was used in the legs and struts, since they did not need to be as long as in A-1 and F-1. This material savings was utilized to make the flanges of the legs and struts twice as thick as the A-1 and F-1 models (fig. 4).

TABLE I. Natural Frequencies Obtained for Model A-1

MODEC	NASTRAN	EXPERIMENTAL
ONE (θ)	-	630
TWO (θ, Ζ)	722	800
THREE (0,Z,A)	902	1000

TABLE II. Natural Frequencies Obtained for Model F-1

MODES	NASTRAN	EXPERIMENTAL			
ONE (θ)	_	620			
TWO (0,Z)	715	890			
THREE (θ,Z,A)	1070	920			

TABLE III. Natural Frequencies Obtained for Model A-3

м	ODES	NASTRAN*
ONE	(6)	
TWO	(θ,2)	. 720
THREE	(θ,2,A)	1100

^{*}Values given are those which have the same mode shapes as those for the A-1 and F-1 models.

With this increased cross section, the results obtained for the natural frequencies with the NASTRAN program are given in table II. It should be noted that the normalized deflections and rotations of all grid points, as well as plotted mode shapes, among other things, were obtained as output, but are not presented in this report. An example of the output for A-1 is contained in appendix B.

3. EXPERIMENTAL STUDY

3.1 Model Description

Two models were constructed to check the values of the natural frequencies from the computer for the fore- (F-1) and aft- (A-1) mounted fuze support structures. Figures 1 and 2 show the fore- and aft-mounted fuze structural models.

The fuze box itself was 1/16-in.-thick alodined 6061-T6 aluminum alloy fabricated by bending and welding flat sheet material.

The legs and struts of cross section given in figure 3 were welded to the box; to these were welded the mounting pads shown in figures 5 and 6.

Fuze components were simulated by aluminum blocks of expected size and shape. Figures 8, 9 and 11 give the sizes and arrangement of the individual blocks. This particular arrangement of components gave the center of gravity location shown in figures 10 and

Two Endevco Series 2200 accelerometers were mounted to the simulated component (piece number 11 in fig. 10 and 11) by mounting studs. One was oriented in the negative 2-direction, and the other was oriented in the radial direction aligned with one of the leg axes. (See figure 7 for the coordinate system definition.)

The simulated fuze component assembly was then inserted into the box. Correct standoff distances were maintained by pieces of pre-cast polyurethane foam. The top was attached and 6-lb/ft³ polyurethane foam was injected through predrilled holes with an approximate 15 percent overfill factor being utilized. The package was cured overnight in an oven at 150°F.

Axial Accelerometer

Accelerometer

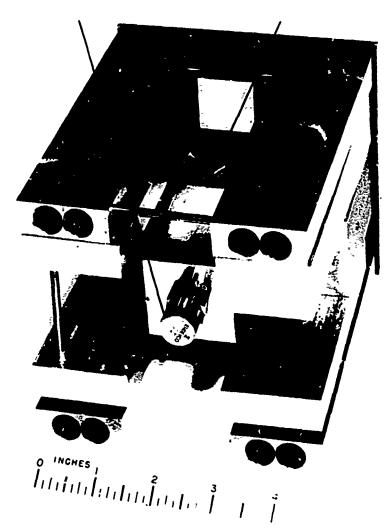


Figure 8. Structural mock-up of fuze components.

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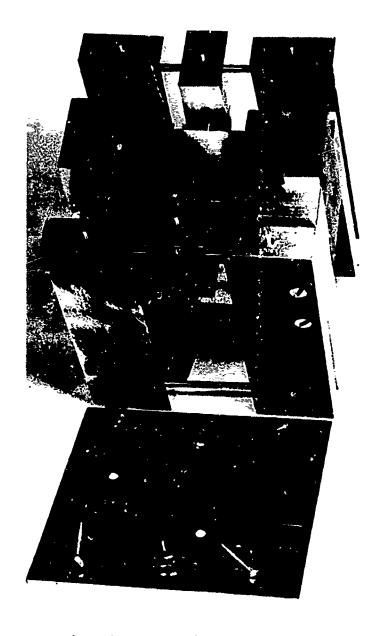


Figure 9. Structural mock-up of fuze components.

After cooling, three additional accelerometers were placed on the outer surface of the fuze package. One was oriented in the negative Z-direction, physically located less than an inch away from the previously mentioned axial accelerometer located on the transmitter block. The second exterior accelerometer was placed on one of the sides of the fuze box and had its axis in the X-Y plane making an angle of 45 deg with the axis of the interior accelerometer oriented in the radial direction. The fifth and final accelerometer on the package was mounted perpendicularly to the web face of one of the struts (in the theta direction) and was used to record rotations of the package about the Z-axis and/or movement of the struts.

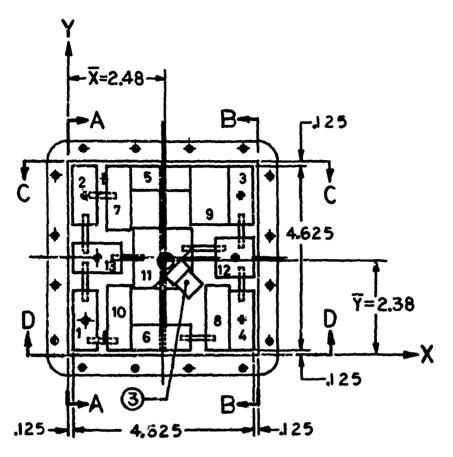


Figure 10. Structural fuze model showing dummy component arrangement, center of gravity, and accelerometers.

Every effort was made to perform identical tests on both A-1 and F-1 units (figs. 12 and 13). The single exception was that the exterior accelerometers on A-7 were Endevco 2200 series, weighing 1.2 oz. each, and those on the F-1 fuze package were Wilcoxon series 102 accelerometers, weighing 0.132 oz. Table IV gives a breakdown for the two units.

TABLE IV. Fuze Mock-up Weight

Box and Top	1.12	1b
Simulated Components	5.92	1b*
Total, A-1	10.12	lb
Total, F-1	10.16	lb

^{*}includes 2 Endevco accelerometers.
Total includes accelerometers and welds.

3.2 A-1 Model Tests

The aft-mounted model was tested by the shock and vibration testing group at HDL on a servo-controlled MB-C25 electrodynamic shaker table and vibra-plane (slip table) system.

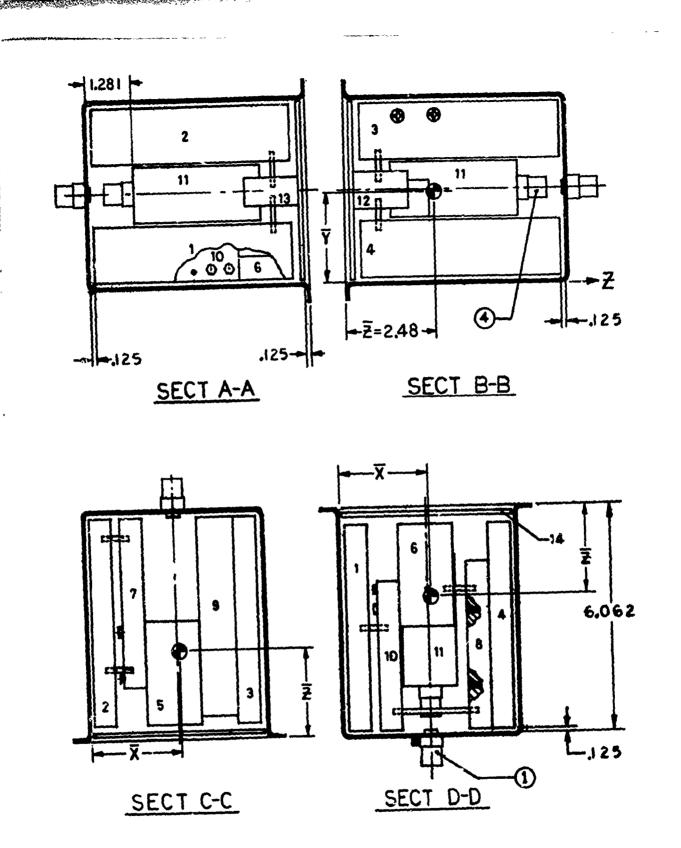


Figure 11. Structural fuze model showing dummy component arrangement, center of gravity, and accelerometers.

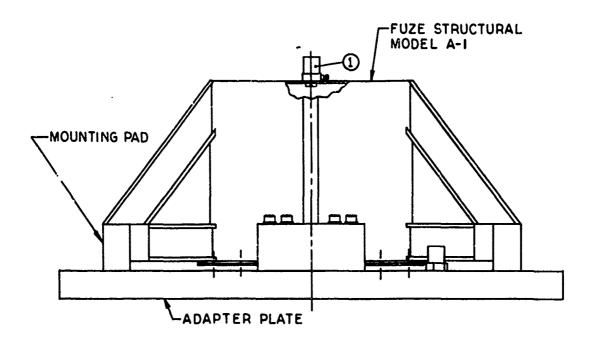


Figure 12. Fuze structural mockup A-1 on shaker adapter plate.

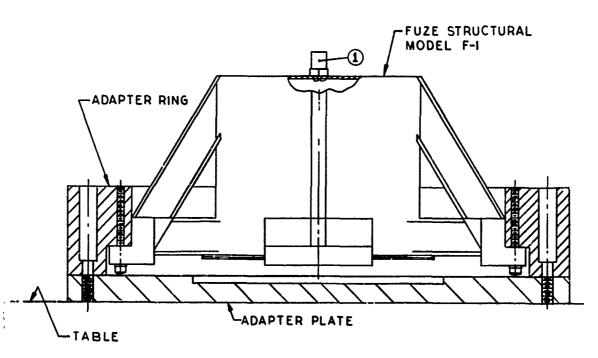


Figure 13. Fuze structural mockup F-1 on shaker adapter plate.

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Before testing the fuze package, the adapter plate was attached to the shaker table and tests conducted in both axial and transverse direction to insure that the shaker system had no significant resonances within the range of 20-2000 Hz. The fuze package was then attached to the adapter plate as shown in figure 12 and subjected to sinusoidal vibrations in the Z and X directions at load levels of 2 g with the frequency swept logarithmically from 20 to 2000 and back to 20 Hz in 13 minutes.

Figures 14 and 15 show the fuze structural mock-up being tested in the axial direction. In this direction three runs were conducted at a 2-g load level.

The package was then placed on the slip table and two 2-g vibration tests were conducted with the sinusoidal force being applied in the X direction (fig. 16).

Good shaker amplitude control was achieved in the first 2-g run in the axial direction. However, normal amplitude tolerance (±10 percent) was exceeded severalfold over two narrow, closely spaced frequency bands in all other tests. These data were therefore less reliable.

3.3 F-1 Model Tests

The fore-mounted model was tested on an MB-C150 s..aker and slip table system by General Testing Laboratories (GTL) at their site in Hartwood, Virginia.

A special adapter ring was required to simulate the forward mounting condition. A drawing of the package attached to this ring and an adapter plate is shown in figure 13. As before, axial and transverse tests were conducted on the adapter ring, adapter plate, and shaker alone to determine their response in the range of frequencies of interest.

The package was then bolted to the adapter ring and sinusoidal 2-g loads were applied in the axial (Z) and two transverse directions (X and 45 deg from the X directions). Once again the frequency range from 20 to 2000 and back to 20 Hz was swept in 13 minutes. Shaker Shaker control throughout the entire test program at GTL was excellent, and the data obtained were complete.

4. RESULTS

The data obtained from the tests are presented in figures 17 through 25, where amplification (recorded g-level divided by table input g-level) versus frequency is plotted for each of the five accelerometer locations in each of the three different directions of loading. The results obtained from the fore- and aft-mounted models were both plotted on the same figure for direct comparison.

For the A-1 model the natural frequencies are seen to occur at 630, 800, 1000, and 1600 Hz. The resonance at 630 Hz was observed only as a rotation about the Z-axis with no other accelerometer showing any increase in amplification at this frequency. The 800-Hz mode is excited only under transverse loading conditions with the 1000-Hz mode being present in the data obtained from both the axial and transverse vibrations. The 1600-Hz resonance was evident only on exterior-mounted accelerometers and not on those that were placed on the simulated fuze components. For the F-1 model, the natural frequencies occurred near 620, 890, 920, and 1650 Hz. Once again, the 620-Hz value was due to a rotation

only. The 890- and 1650-Hz values were obtained from transverse excitations only, and the 920-Hz mode was the only mode excited during axial vibration. These values of natural frequencies are summarized in table V.

TABLE V. Experimentally Obtained Natural Frequencies (Hz)

A-1	630	800	1000	1600	
F-1	620	890	920	1650	

Tables I and II show that it was possible to match resonant frequencies obtained experimentally with a frequency and mode shape obtained using NASTRAN. This correspondence was not complete, however, as NASTRAN produced more frequencies in the range 20-2000 Hz than were found in the vibration experiment (app. B). At least some of the additional natural frequencies obtained by NASTRAN can be discounted, because the mode shapes indicated movement in places that would not have been detected by the accelerometers used in the experiments. In addition, no information was available from the normal mode analysis, which indicated the amplification factor for each natural frequency. Thus, the possibility exists that some of the frequencies obtained by NASTRAN were of too small an order to be detected by the experimental equipment. Finally, an improved mathematical NASTRAN model would most likely eliminate some of those frequencies that cannot be discounted according to the reasoning explained above. This would also correct the failure of the NASTRAN solutions to correspond to the frequencies detected by the accelerometer mounted on one of the struts.

5. CONCLUSIONS

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Figures 17 through 25, which are discrete point plots selected from continuous recorder traces, provide the basis for some conclusions.

Figures 17 and 22, which show the response of an accelerometer attached to a fuze package support strut, give evidence that the lowest natural frequency for both models A-1 and F-1 occurred at about 630 Hz in a rotational mode about the Z-axis. This mode was excited when the vibration inputs to the models were in either axial or transverse directions.

The next natural frequencies of large amplification occurred at about 800 Hz and near 1000 Hz, measured on the box surface. These coincided with two of the NASTRAN modes (Table I).

The lowest frequencies excited by axial vibration were 900 Hz for the fore-mounted model and 820 Hz for the aft-mounted model, measured inside the box (fig. 19). No comparison with a NASTRAN prediction was possible since the mathematical model did not include internal grid points.

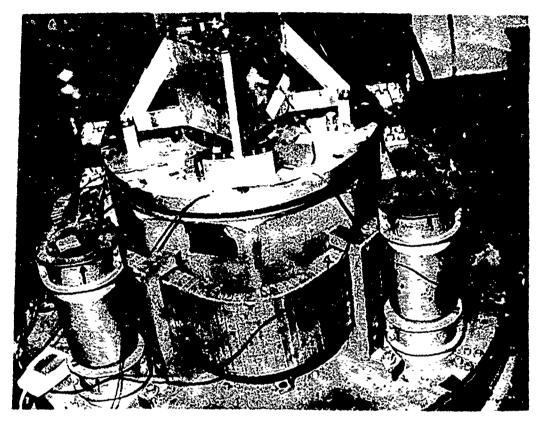
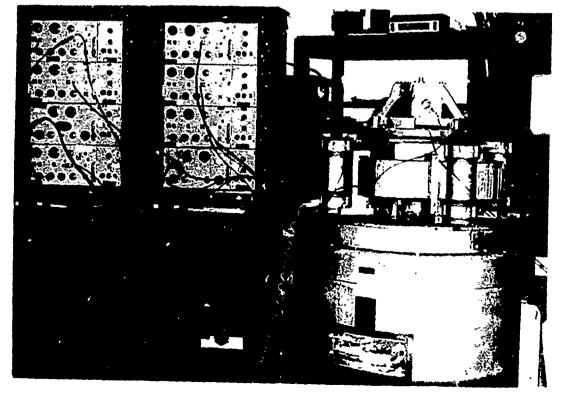


Figure 14. Fuze structural mockup A-1 ready for vibration test.



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Figure 15. Vibration test setup for Z-axis exitation of A-1 fuze mockup.

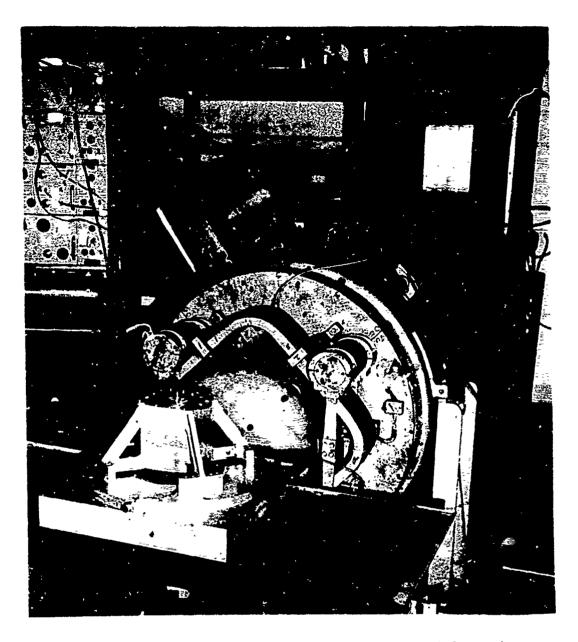
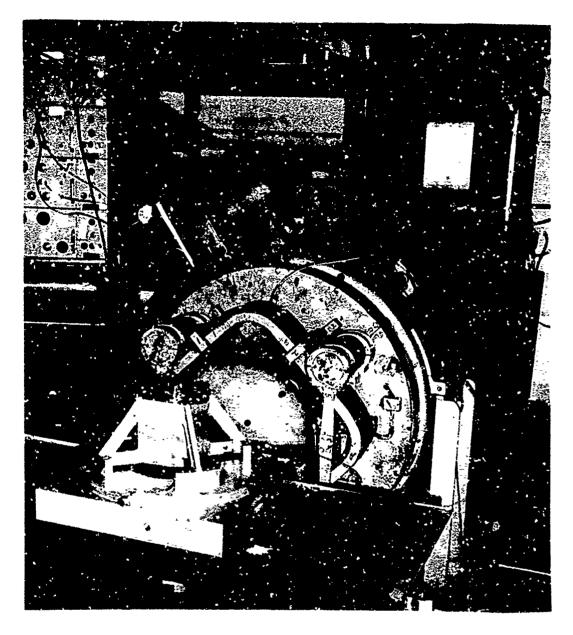


Figure 16. Vibration test setup for transverse exitation of A-1 fuze mockup.

6. RECOMMENDATIONS

The proposed fuze structure design study should be continued in the following ways:

First, since a better picture now exists of the actual fuze size, geometry, and orientation, this information should be used as input to the NASTRAN program. This input should utilize the previously mentioned formats. The structure should then be examined under sinusoidal loading at or near predicted natural frequencies to determine damage potential of resonant loading.



Migrie 1 Vibration test setup for transverse exitation of A-1 fuze mockup.

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An improved mathematical model should be employed that utilizes more grid points and more realistically represents the polyurethane foam in the X and Y directions. (Such a model is in progress and will be reported in Part II of this study.)

It appears that the lowest resonant mode obtained for the proposed fuze structure was sufficiently high for component survival. The second natural frequency, which was excited by transverse vibration (800 Hz for A-1 and 890 Hz for F-1), was of a more serious nature. Therefore, some consideration might be given to increase these frequencies as well as those that occurred in the axial mode of vibration. The lowest natural frequency of the axial mode can be raised by increasing the moments of inertia of the legs and struts; this can be done within specified weight limitations. This weight addition, however, also adds to the supported weight, and there are indications (from other NASTRAN runs performed but not reported here) that this tends to lower slightly the natural frequencies excited by transverse vibration. The suggestion, therefore is that the NASTRAN program be utilized to its full potential, and such things as tapered, laminated, and unsymmetrical beam sections be investigated, if these natural frequencies are to be increased.

The assum, tion was made that the mounting pads gave absolute fixity to the ends of the legs and struts. This, in reality, is not true, because the ring on which these pads are mounted moves due to elasticity of the missile itself. It is recommended that by the use of scalar points and connecting linear springs, the NASTPAN program be used to determine the natural frequencies as a function of missile elasticity.

Finally, it was noted that there was a small decrease in the natural frequencies when the original dip-brazed structure was welded. If possible, a mock-up of the proper size, orientation, and mounting pad type, manufactured by a casting process should be tested and compared with NASTRAN results obtained for a similar welded structure.

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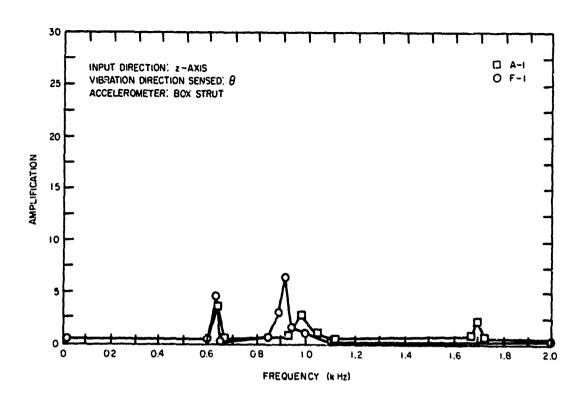


Figure 17. Response of models A-1 and F-1 to 2-g sinusoidal input.

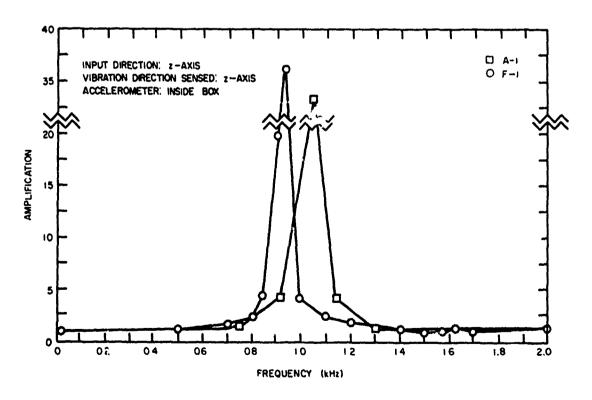


Figure 18. Response of models A-1 and F-1 to 2-g sinusoidal input.

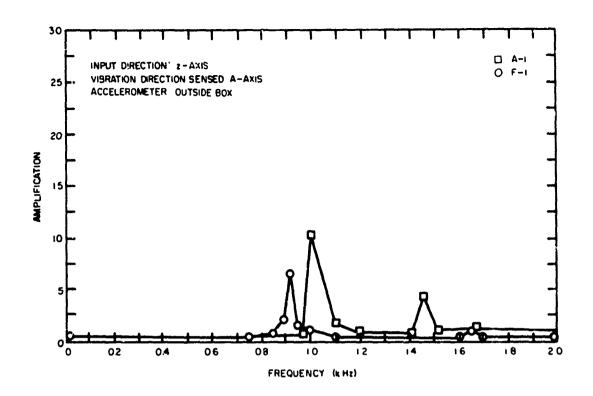


Figure 19. Response of models A-1 and F-1 to 2-g sinusoidal input.

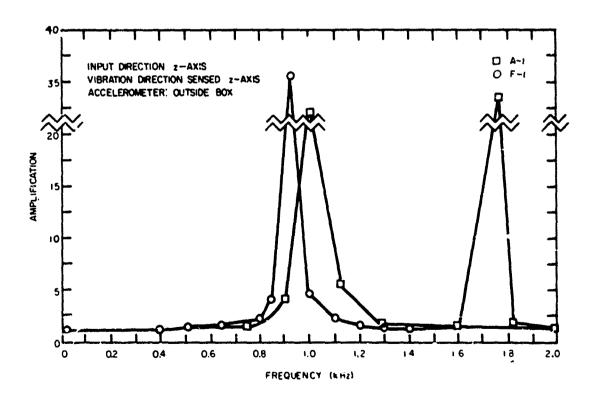


Figure 20. Response of models A-1 and F-1 to 2-g sinusoidal input.

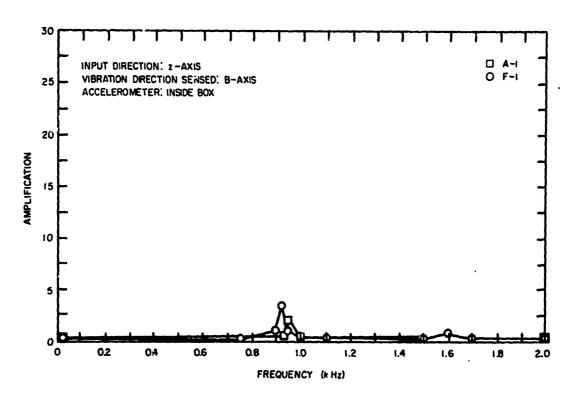


Figure 21. Response of models A-1 and F-1 to 2-g sinuscical input.

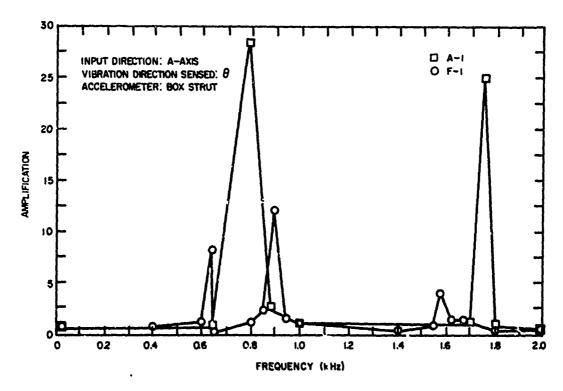


Figure 22. Response of models A-1 and F-1 to 2-g sinusoidal input.

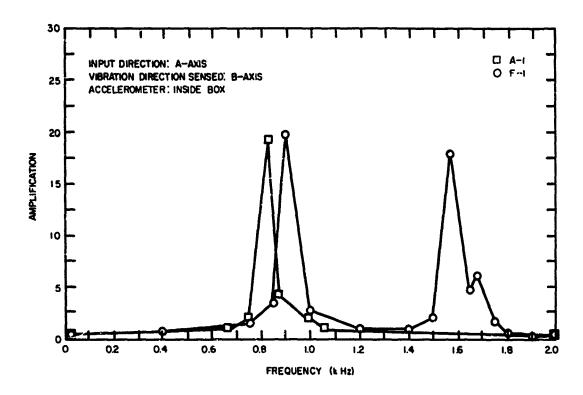


Figure 23. Response of models A-1 and F-1 to 2-g sinusoidal input.

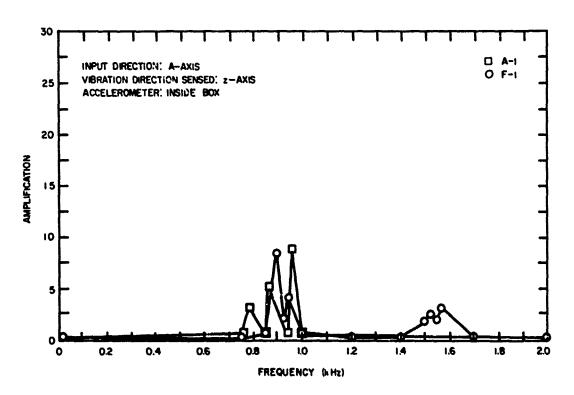


Figure 24. Response of models A-1 and F-1 to 2-g sinusoidal input.

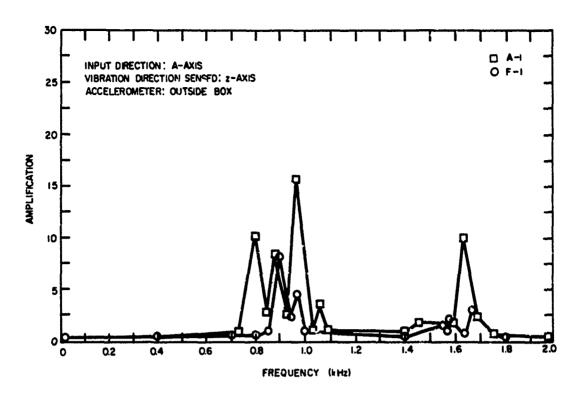


Figure 25. Response of models A-1 and F-1 to 2-g sinusoidal input.

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APPENDIX A. INPUT DATA TO NASTRAN FOR FUZE MODEL A-1

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1	LHAR	201	20	20	21	1.0	1.0	1.0	ï	•• •• •
2	CBAR	505	20	21	22	1.0	1.0	1.0	1	
3	CRAR CBAR	703 204	20 21	22 44	23 45	1.0 1.0	1.0 1.0	1.0	1	
5	CBAR	205	21	45	46	1.0	1.0	6.0	i	
6	CHAR	206	21	46	47	1.0	1.0	6.0	ī	
7	CHVK	20 <i>1</i>	21	47	48	1.0	1.0	6.0	1	
8 9	€0402€ 634	? 1.0	0.0	.0 1.0	•0	•0	•0	•0	1.0	134
10	CORU2R	i	Ö	.0	•0	.0	•0	•0	1.0	123
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12 13	CQUAD2	101 102	22 22	5 4	16 15	15 14	4	•0		
14	COUNTS	103	22	3	14	13	12	•0		
15	CQUAQZ	194	22	6	5	4	ĩ	.0		
16	COUADZ	105	22	1	4	3	2	•0		
17 18	COUADS	10^ 10/	22 22	4	3 6	12 1	11 8	•0		
19	C:UADZ	108	22	8	ĭ	ž	ÿ	.0		
20	COUNTS	109	22	4	2	11	10	•0		
21	COUAL 2	116	27	20	19	6	!	•0		
22 23	COUAL 2	111	25 25	19 18	18 17	5 16	6 5	•0		
24	COUADZ	113	25	30	3i	19	žο	·ŏ		
25	CCIVVING	114	25	31	32	18	19	• 0		
26 27	CULARY	115	25	32	33	17	18	•0		
26	SUAUES SUAUES	116 117	25 25	37 36	36 35	31 32	30 31	•0		
29	CHUADZ	116	25	35	34	33	32	•0		
30	Conves	119	75	44	47	36	37	•0		
3 i 32	CORVES	123	25	49	50	35 34	36	•0		
33	0.11 AT 2 0.11 AT 2	121 122	25 25	50 61	51 62	49	35 44	•0		
34	CHANS	123	25	62	63	50	49	.c		
35	CCUAU2	124	25	63	52	51	50	•0		
36 37	CCUAU2 CCUAU2	125 176	22 22	63 64	64 65	53 54	52 53	•0		
38	CHAP 2	127	22	65	56	55	54	.0		
39	COLASIZ	178	22	66	57	56	65	• C		
40 41	CONVES	129 130	22 22	67 62	66 67	65 64	64 63	•0		
42	COUADZ	131	22	61	60	67	62	•0 •0		
43	CQUARZ	132	22	60	59	66	67	•0		
44	CHUANZ	133	22	59	59	57	66	•0		
45 46	CHUADS	134 135	25 25	59 60	42 43	41 42	5 ե 59	•0		
47	6.2641.2	136	25	61	44	43	60	•0		
48	COUNDS	137	25	42	39	40	41	• 0		
49 50	CUUADZ	138	25	43	38	39 30	42	•0		
50 51	CONVOS	139 140	25 25	44 39	37 28	38 ?7	43 40	•0		
>2	CANVI-5	141	25	38	29	28	39	.0		
53	CUUVUS	142	25	37	30	29	38	•0		
54 55	COUAD2 COUAD2	143 144	25 25	28 29	25 24	26 25	27	•0		
56	COUNTS	145	25	30	20	24	28 29	•0		
57	CLUAT 2	166	25	25	9	10	26	•0		
58 50	COUAGE	147	25	24	8	9	25	•0		
59 60	CRUADZ	143 301	25 23	20 55	7 13	8	24	•0		
61	CRGO	302	23	54	14					
62	CRUD	303	23	53	15	Ren	oduced f			
63 54	CRUD	304	23	26	75	best	available	CODY	O.	
65	CKOD	305 306	23 23	55 64	3 4		,,-014	-Jp7.		
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70	LATD	MAX	517	••	2110040		10			GAEU
71	GRUSET		1				1			
72 73	GRID	1		1.667	1.667	6.0				
73 74	6410 6410	2		1.667 .833	.833 .833	6.0 6.0				
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132 GR 133 GR 134 GR 135 SR 136 GR 137 GR 138 GR 139 F/	18 19 20 21 22 21 22 23 24 25 27 28 27 28 27 28 27 28 27 28 27 28 28 28 28 28 28 28 28 28 28 28 28 28	10.0L6	667 4 5 5 5 5 5 5 667 6 333 6 0 0	2.5	.0 .0 .0		123456		
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143	4111 4 MFT 52	14	15 54	16	17	33	11	12	EMET
145 0	4111 5	41 57	40 58	27	26	10			EHAT
147 6	4111 45	ĩ	ź	3	4	64	65	66	EMBT
149 6	MAT 67 MIT1 46	19	18	31	32	36	35	49 24	TIMS
150 &	MBT 50 MIT1 56	42	43	39	38	29	28		6567
152 6 153 (1 154 8	MIT 25 MIT1 456 1567 20 1678 60 MARAN GROPY	5 30 61 1 100	6 37 62	7 45 63	8 46	4;	21 44	22 59	6678

157	Pear	2C	30	.25	2.76-3	52	1.3-3			
158	PBAR	21	31	.25	2.76-3	52	1.3-3			
153	PGUAD2	22	32	6.25-2	1.56-4	J. L	1.3-3			
160	PQUAL2	25	32	6.25-2	6-46-5					
161	PAUD	23	33	1.0	.0					
162	SECGO	1	13	\$	12	3	5	,		
163	SFLGP	5	20	ì	21	7		4	10	
104	SECGA	ý	23	ĭo	22	íı	25	8	24	
Lus	SECOP	13	ĩ	14	3	15	11	12	4	
166	SECCP	17	35	ls	36	19	9 37	16	19	
167	SECUP	21	53	52	63	23	5 <i>1</i> 65	20	38	
168	SEGGP	25	40	26	39	27		24	41	
109	SFIGN	29	54	30	5?	31	55	28	56	
170	Seagn	33	49	34	61	35	51	32	50	
171	\$5.,61	37	60	38	59	39	45	36	47	
172	SEGGP	41	42	42	43	43	58	40	57	
173	SFLSP	45	62	46	64	43 47	44	44	48	
174	SFLGP	49	46	50	29		66	48	67	
175	\$7,000	53	16	54	7	51	26	52	31	
176	STAGE	57	14	58	27	55	2	56	6	
177	SEGGE	ői	34	62	33	59	28	60	30	
178	Secor	02	8	02	23	63	32	64	17	
179	Stage	56	ï,							
130	\$1,U3P	67	18							
1 01	\$961	10	4	41	42				_	
167	ESPCII	34	26	29		43	40	37	38	ESPC11
103	SPCI	íó	5	19	28	27	24	25		
164	1.SF-C1.2	36	3,	34	19 49	17	31	32	33	ESPC12
165	.201	10	6	1		50	51			
1-5	£5PC13	14	4	55	2 56	11	12	13	3	£5PC13
1 5 7	657614	23	64	55 67	36 15	57	54	65	66	ESPC14
163	5061	10	156	13						
109	£50C15	34	21 21	52	14	15	16	17	33	ESPC15
193	SPLI	10	246	13	53	54	55	_		
191	ESPEIS	40	41	58	12 57	11	10	26	27	ESPC16
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APPENDIX B. SAMPLE OF NASTRAN OUTPUT FOR FUZE MODEL A-1.

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-	R2	2. 3.42.9.22E-01	4.5349855-01	3.2291355-01	1.6583116-01	1.646640E-03	7.036797E-03	9.8833936-04	1.355582E-C1	2.8214385-01	3.4339446-01	5.537450E-01	3.901860E-01	0.0	0.3	0.0	0.0	0.0	0.0	0.0	2.839692E-03	2.467392E-03	1.521580E-03	0.0	2.947088E-02	7.473201E-02	20-31600000000000000000000000000000000000	-9.43012de-02	20-31/66-71-9-	-3-45/418E-02	CO-3000000000000000000000000000000000000	0	0.0	0.0	0.0	0.0	-1.205507E-02	-4.221941E-02	-8-4" 1940E-02	-1.037120E-01	-5.120346E-03	-5.672846E-03	-6.427474E-03	1.1096456-03	3-169313E-04	5.037209E-04	2.359556E-04		000
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KEAL E10	12	1.2334086-04	6.504753E-05	5.76983>1-05	1-1095005-04	1.5513226-04	1.7508285-04	1.1929926-04	57965E-	2.364153E-05	0.0	0.0	0.0	0.0	5.286.242505	1.0726306-64	1.4821126-04	-1.3083826-01	-1.0649431-01	4.621013E-GZ	-7-2943855-05	-4.3520576-05	-2.426482E-05	o•0	-4.838262E-05	-2.495434E-05	0 (0.0	-5-5516316-05	-1-170810F-04	-1-3574 (OE-04-	-11.7793186-02	-1.0387465-01	5.9413385-02	4.710201t-02	1.8571416-02	-3.592641E-05	-2.052842E-05	-0.204086t-06	o•0	0.0	-1.470314E-04	-4.608/76E-C4	-8.142767E-04	-2.432178E-04	9-6170556-05	1.646511E-04	0.0 6.306443103	1.270008E-01
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