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Final Report

By

W. L. Mclntire R. C. Malott

December 1966

U. S. ARMY AVIATION MATERIEL LABORATORIES FORT EUSTIS, VIRGINIA

CONTRACT DA 44-177-AMC-318(T)

ALLISON DIVISION -GENERAL MOTORS INDIANAPOLIS, INDIANA

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The objective of this program was to conduct an analytical and experimental study to derive or establish accurate factors for inclusion in spur gear design formula for the accurate appraisal of gear bending strength.

This report presents the results of this investigation. An accurate spur gear bending strength formula was determined and an IBM 7090 computer program using the substantiated formula was provided.

This command concurs in the conclusions made by the contractor,

Task 1M121401D14414

Contract DA 44-177-AMC-318(T) USAAVLABS Technical Report 66-85 December 1966

ADVANCEMENT OF SPUR GEAR DESIGN TECHNOLOGY

Final Report

EDR 4743

by

W. L. Mclntire and R. C. Malott

Prepared by

Allison Division \bullet General Motors Indianapolis, Indiana

for

U. S. ARMY AVIATION MATERIEL LABORATORIES FORT EUSTIS, VIRGINIA

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FOREWORD

This is the final report on the Allison project entitled "Advancement of Spur Gear **Design** Technology. " This project was conducted during the 13-month period from 29 **June** 1965 through 28 July 1966 for the U.S. Army Aviation Materiel Laboratories (USAAVLABS) under contract DA 44-177-AMC-318(T).

USAAVLABS technical direction was provided by Mr. R. Givens. Mr. W. L. Mclntire served as the Allison project engineer. The principal investigators at Allison were Mr. R. C. Malott, Mr. F. G. Leland, Mr. K. V. Young, and Mr. W. W. Gunkel. The project was reviewed periodically with Mr. R. L. Mattson of General Motors Research for suggestions and comments.

Permission was obtained from the American Gear Manufacturers Association (AGMA) to print AGMA 220. 02, Tentative AGMA Standard for Rating the Strength of Spur Gear Teeth, in this final report.

SUMMARY

This report presents the results of an analytical and experimental program to derive and substantiate a bending strength design formula for spur gears. The program consisted of:

- Static single tooth fatigue testing of ¹⁶ gear designs in ^a design experiment to determine the effect of four geometric variables—diametral pitch, pressure angle, fillet size, and fillet configuration (full form ground or protuberant hobbed).
- Evaluation of the ability of five current calculation methods—AGMA, Dolan-Broghamer, Heywood, Kelley-Pedersen, and Lewis—to predict the relative ranking of the ¹⁶ fatigue test gear endurance limits.
- Statistical analyses of the fatigue test data to develop ^a predictive formula and relative significance values of the four geometric variables and their two- and three-factor interactions.
- ^A strain gage and photostress experimental evaluation to measure stress on eight of the fatigue test gears for comparison with calculated stresses and fatigue test endurance limits.
- R. R. Moore rotating beam fatigue tests of the gear material to establish basic material strength for comparison with fatigue test endurance limits.
- Measurement of the fatigue test gear crack location for comparison with location of the weakest section as predicted by the Lewis and Dolan-Broghamer calculation methods.
- Metallurgical examination of five representative fatigue test gears to verify material processing and mode of failure.
- ^A dynamic test at high pitch line velocities—up to 26,000 feet per minute—to determine speed effect on gear tooth bending stress.
- Development of ^a computer program to calculate gear tooth bending stress from the basic gear geometry, thus eliminating the need for a gear tooth layout.

The results of the program were as follows:

- The AGMA method of calculating gear tooth bending stress predicted the greatest number of correct rankings of the ¹⁶ fatigue test gear endurance limits. This method also predicted the rank position with the least average error.
- Comparison of endurance limits, based on applied load, calculated from the fatigue test data for each of the ¹⁶ gear designs was made by statistical tests of significance. Diametral pitch and pressure angle had a significant effect on gear tooth bending fatigue strength. The AGMA formula successfully compensated for the significant variables determined by the base-line applied load analyses.
- The strain gage stress values obtained tend to verify the AGMA calculated stresses. The average strain rate measured on the fatigue test gears was within 2. ⁵ percent of the strain rate calculated by the AGMA formula.
- The basic gear material endurance limit determined by the R. R. Moore rotating beam test was 182, 000 p. s. i. when modified for single-direction bending. The fatigue test gear average endurance limit based on AGMA calculated stress was 182, 000 p. s. i. It appears, therefore, that basic material strength can be very closely related to AGMA calculated gear stress and endurance limit.
- Fatigue test gear crack location was nearer the Dolan-Broghamer than the Lewis predicted location, as expected.
- Metallurgical examinations verified good processing of the fatigue test gears and fatigue as the mode of failure. Failures were initiated at random locations across the face width of the gears, indicating minimal influence of surface finish, material inclusions, corner edge break, and test rig alignment.
- Steady hoop stresses were measured in the dynamic test at the weakest section. The measured stresses were ⁷⁰ percent of the calculated root diameter hoop stress. The measured stress was 14,000 p. s. i. which is considered sufficient to necessitate its inclusion in bending stress determinations for high-speed gears.
- The dynamic test also measured dynamic fluctuating gear tooth level stresses. Stresses indicated a dynamic stress factor increasing with the square of the rotational speed. The dynamic factor was 1.8 at 26,000-feet-per-minute-pitch-line velocity.
- The computer program developed accurately determined the root fillet configuration by calculating the true radius or trochoidal fillet depending on the manufacturing method and the tool (hob) dimensions. The Lewis weakest section is determined by iteration. The gear tooth dimensions determined are used in the AGMA formula to determine bending stress. A hoop stress at the root diameter is then calculated to account for the effect of speed on gear tooth bending stress. The steady hoop stress and the fluctuating bending stresses are then combined by means of a modified Goodman diagram to produce a combined stress and an expected failure life. The modified Goodman diagram was based on the average S/N curve determined by the fatigue test gears.

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INTRODUCTION

The purpose of the project was to conduct an analytical and experimental investigation to derive factors and formulae which can be used to appraise accurately spur gear tooth bending strength for aircraft applications.

The objective of the project was twofold-to substantiate an accurate spur gear bending strength formula and to provide an IBM 7090 computer program using the substantiated formula. Correlation of a basic material strength with this formula was desired.

There are four common modes of gear failure—tooth breakage, surface pitting, scoring, and wear. Tooth breakage is the most severe and often causes considerable secondary damage and sometimes catastrophic failure of an entire gear unit. It may be caused accidentally, such as when a foreign object passes through a tooth mesh, or it may be caused by the repetitive high bending stresses near the root of the tooth when under load.

Many factors affecting the bending fatigue strength of gear teeth are not treated with precision in current spur gear design formulae. This is because the magnitude and interrelationships of the various factors have not been accurately assessed. Gear tooth bending strength is a function of geometric variables such as pressure angle, diametral pitch, tooth width, root fillet form, and root fillet radius. It is also influenced by manufacturing variables such as surface finish, residual stress, material, and processing technique. Operating variables such as speed, alignment, dynamic loading, and vibration affect the fatigue life. A thorough analysis of these variables will permit more accurate assessment of gear life expectancy.

Considerable research has been accomplished in analyzing gear tooth bending strength; however, there is wide variation in the type of analysis, test data, and field experience. In many instances extensive extrapolation has been required to apply these data to carburized gears designed to current standard geometric proportions. The program described herein was conducted in an effort to establish correlation between analytical methods and actual test results for lightweight aircraft gearing.

Current methods of calculating gear tooth bending stress are based on analytical studies and photoelastic tests. These methods produce calculated stresses which are appreciably lower than measured gear stresses and basic material strengths. Thus the calculations are most often used to compare similar designs. An "ideal" gear tooth bending strength formula would relate the operating gear tooth stress to the basic material strength in such a way as to produce a gear life which has been substantiated by fatigue test. It was therefore the intent of the subject program to provide a more accurate bending stress formula by also relating calculated stress and fatigue test results to the basic material strength. R. R. Moore tests of carburized specimens were used to provide a basic material strength.

To accomplish the program, the following analytical and experimental analyses were conducted.

- Design Analysis—An analytical review was made of current spur gear tooth bending strength formulae. Each formula was analyzed and compared to determine the effects of design variables.
- Experimental Evaluation—A photostress analysis was conducted to evaluate the location and distribution of the maximum stress on actual fatigue test gears. Strain gage stress measurements were obtained for correlation with stress calculations.
- Gear Tooth Fatigue Tests—A single tooth fatigue test was conducted to investigate the effect of diametral pitch, pressure angle, root fillet size, and root fillet configuration on fatigue life. Eighty gears were manufactured. Extreme care was taken to reduce all possible manufacturing variances which might affect fatigue life. Metallurgical investigations of the fatigue failures were also made to ensure that the basic material was sound and was properly heat treated. Four teeth on each gear were available for fatigue testing.
- R. R. Moore Tests—R. R. Moore tests were conducted using the same heat of material used for the test gears. The data obtained were used for comparison with the bending endurance strengths from the gear fatigue tests.
- Dynamic Tests—An existing accessory gear in an Allison 501-D13 gearbox was instrumented with strain gages. The gear was operated at high speed (pitch line velocity of 27, 000 feet/minute) at load and no-load conditions to investigate the effect of speed on bending stress. The data obtained were reduced to determine the effect of centrifugal and dynamic loads on bending stress.
- Final Computer Program—Data from the previously mentioned items were formulated into an IBM 7090 computer program for spur gear bending strength.

ANALYSIS OF PROBLEM

HISTORICAL REVIEW

^A review of gear tooth bending strength theory was made. The results of this review are discussed in the following paragraphs.

In 1887, Mr. A. B. Couch in an American Society of Mechanical Engineers (ASME) meeting was asked for a rule to determine safe gear loads (reference 62). He expressed surprise and replied that "the rules furnished (available) are in number bountiful and in variety nearly infinite. " He reported that a fellow ASME member had compiled a list of 30 to 40 such rules. In these different rules, safe load varied directly as the square and in a few instances even as the cube of circular pitch. Face width was the only other widely considered factor. The same discussion group expressed an awareness of dynamic loads when they commented, "The cog gearing of power levers used in threshing, owing to the irregular draft of horses, is subjected to heavier strains. "

In 1892, Mr. Wilfred Lewis presented a paper which related gear tooth bending strength to tooth geometry. The formula derived in this paper is the basis for most bending stress calculation methods used today. Publication of the Lewis formula did not result in its immediate unanimous adoption. However, it did accelerate further analytical and experimental investigations. Charts and computer programs based on the Lewis formula were developed to expedite gear designs (references 27 and 44). A cantilever beam bending formula for a rectangular section was used to calculate bending stress from 100-times size gear tooth layouts at successive sections 0. 100-inch apart to determine the minimum load section for an arbitrary constant stress (reference 31). This work served to verify the principles of the Lewis formula. The improved accuracy required and the higher peripheral speeds of gears necessitated three basic changes to the Lewis formula which have been accepted by general usage—the addition of the Dolan-Broghamer stress concentration factor, the addition of a compressive stress term, and consideration of tooth loading at the high point of single tooth contact or at the pitch diameter rather than at the tip.

The Dolan-Broghamer stress concentration formula is based on photoelastic stress work accomplished at the University of Illinois Engineering Experiment Station in 1942 (reference 16). Their formula is included in the current AGMA Standard 220:02 which is included in this report as Appendix VI. This formula is included in many stress and engineering handbooks as a modified Lewis formula or as a part of the AGMA standard.

Other investigators have obtained photoelastic stress results in close agreement with those of Dolan and Broghamer (references ¹ and 10). Prior to the Dolan-Broghamer formula, the stress concentration factors included only a limited number of geometric variables and thus were not as universally applicable (reference 58).

The existence of stresses other than bending stresses in the critical root area of a gear tooth was recognized at an early date. Calculation and vectorial addition of shear stress, from the tangential (circumferential) component of the tooth load, were accomplished and published in 1897 (reference 31). Several current tooth strength formulae include shear stress; the AGMA standard does not. See Appendix VI. For a given tooth load, shear stress would be greate. . a pressure angle gear of 14. ⁵ degrees than for a similar one of 25 degrees.

Compressive stress from the tooth load radial component has been accepted for summation with the gear tooth bending stress. The AGMA standard (Appendix VI) includes a compressive stress term. More recently, an additional compressive stress at the tensile root fillet has been expressed. This additional stress is due to the moment about the gear tooth radial center line from the radial component of the tooth load. An unsymmetrical stress distribution across the weakest section results, which tends to relieve the bending stresses in both the tensile (load side) and compressive (unloaded side) root fillet areas. The gear tooth load components are shown in Figure 1. These static stresses are present in the photoelastic models used to determine stress concentration factors. Thus, their effect is included in the stress concentration factor if the calculated stress used as a basis does not include any such component load stress.

Figure 1. Gear Tooth Static Load Analysis.

Tip loading, as used in **the original Lewis formula, was often changeo to pitch line loading to account for load sharing at the tip. It was only recently that the exact point of maximum loading for spur gears was recognized (reference 61). This latest refinement permitted more accurate assessment of safety and/or dynamic factors.**

Speed effect curves were developed from **experimental data on cast iron gears** which had been operated under increasing load until tooth breakage occurred (reference 42). The shape of the curves was similar to the curves **currently in the AGMA standard** (speed effect becomes constant at higher speeds). The same curve shape can also be observed in current gear scoring versus speed work curves (reference 8).

A review of the Engineering Index volumes for 1950 through 1965 reveals approximately 1255 abstracts on gears. Ten percent of these involve gear tooth bending strength calculation, fatigue testing, or dynamic factors. Almost 20 percent are from foreign sources, mostly German. The yearly output of such articles is nearly constant over this time period.

Several gear tooth strength formulas are of current interest. Five have been investigated and applied to the ¹⁶ fatigue test gear configurations—Lewis, Dolan-Broghamer, Heywood, Kelley-Pedersen, and AGMA. ^A full ground root fillet radius was assumed for all gears in this study. The stresses for each configuration are listed in Table I. The average, range, and variation in stress for each method relative to the Lewis sti ess are shown in Figure *2,* The Kelley-Pedersen method produced a high average stress and by far the greatest range of stress (75 percent of the average Lewis stress). The average stress of the ¹⁶ gears as computed by the five formulas varied from ¹⁵⁰ to 187 percent of the average Lewis stress. The AGMA method produced the smallest average stress and the smallest range (20 percent of the average Lewis stress). In contrast, the Lewis stresses calculated for the ¹⁶ test gear configurations loaded to 1000 pounds per inch of face width varied by over 400 percent. All five formulas identify the same configurations as having the highest and the lowest stresses (boxed numbers in Table I). The highest stresses are most often calculated by the Heywood method, while the lowest stresses in all cases were determined by the Lewis formula, which does not consider stress concentration.

The geometric construction and formula for each of the five gear tooth strength calculation methods are shown in Figures 3, 4, and ⁵ and in Tables ¹¹ and III. The Dolan-Broghamer and AGMA methods use Lewis geometric construction (Figure 3) and thus are similar to each other. ^A detailed discussion of the Dolan-Broghamer and AGMA methods and factors is given in the section titled Discussion of Results.

The Heywood and Kelley-Pedersen construction methods (Figures ⁴ and 5, respectively) incorporate features which generally lower the position of the weakest section. The Heywood construction method contains several arbitrary features which are not suitable for use with all gear design systems. Variations such as nonstandard addendums and dedendums, which are often used in aircraft designs to balance bending strength or sliding velocity, are examples.

The Kelley-Pedersen method constructs the Lewis parabola, then rotates the tangent line around the root fillet through a "stress shift" angle. Both the Kelley-Pedersen and Heywood methods contain stress concentration factor terms,

Figure 2. Relative Gear Tooth Bending Stress.

where :

- **W • tangential component of load applied at vertex of inscribed parabola**
- **F • face width of tooth**
- **St) maximum bending stress**
- **h * height of equivalent constant stress parabolic beam**
- **t • thickness of beam at weakest section**
- **p circular pitch**

Figure 3. Lewis Construction and Gear Tooth Bending Stress Formula.

>ter for protuberance cut. * Root (liamc

p

x designates low stress range configuration.

xx designates high stress range configuration.

Notes:

¹ A value of 1. 0 was used for Km (load distribution factor). High and low calculated stress configurations are boxed.

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S_b = maximum fillet stress

Figure 5. Kolley-Pedersen Construction and Gear Tooth Bending Stress Formula.

		$S_b = K \left[\frac{6 W h}{t^2 F} - \frac{W}{t F} \tan \phi_L \right]$
where		
	$W =$	tangential load at load point
	ϕ _L =	pressure angle at load point
	$h, t =$	load height and maximum stress section tooth thickness from gear tooth layout (Lewis construction)
F		= gear tooth face width
$S_{\mathbf{b}}$	$\Xi_{\rm{max}}$	combined stress (from radial and flexural components of load) at the ten- sile fillet
K	\equiv	concentration factor for combined stress at tensile fillet
	÷.	maximum observed tensile stress computed combined stress
	\equiv	0.22 + $\left(\frac{t}{r_f}\right)^{0.2}$ $\left(\frac{t}{h}\right)^{0.4}$ for 14.5-degree pressure angle
		0. 18 + $\left(\frac{t}{r_f}\right)^{0.15}$ $\left(\frac{t}{h}\right)^{0.45}$ for 20-degree pressure angle
r_f	Ξ	minimum fillet radius at bottom of the trochoidal fillet of a generated
		tooth as determined by procedure developed by Mr. A. H. Candee.
	Ξ	$r_i + r_t$
r_i	\equiv	$b_i^2/(R - b_i)$ = minimum radius of curvature of trochoid at center of edge radius
b_i	÷,	$b - r_t$ = dedendum to center of tool edge radius
r_t	\equiv	tool edge radius
b	\equiv	length of dedendum of the gear
$\mathbf R$	$\mathcal{L} = \mathcal{L}$	radius of the pitch circle
t	\equiv	thickness of tooth at theoretical weakest section (Lewis)
h	$=$	height of load position above the theoretical weakest section

TABLE **II DOLAN-BROGHAMER GEAR** TOOTH BENDING STRESS FORMULA

$$
S_{t} = \frac{W_{t}Ko}{Kv} \left(\frac{P_{d}}{F}\right) \frac{Ks Km}{J}
$$
\nwhere
\n
$$
S_{t} = \text{calculated tensile stress at the root of the tooth}
$$
\n
$$
W_{t} = \text{transmitted tangential load at operating pitch diameter}
$$
\n
$$
Ko = \text{overload factor}
$$
\n
$$
F_{d} = \text{transverse diametral pitch}
$$
\n
$$
F = \text{net face width}
$$
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$$
\left.\begin{matrix}\n\text{Total area} \\
\text{Total area}
$$

TABLE III (CONT) AGMA **GEAR** TOOTH BENDING STRESS FORMULA

Ks ⁼ **size factor ^J Km » load distribution** factor Stress Distribution **J** s **geometry** factor ** $\frac{1}{K_f m_N}$ for spur gears $\bf J$ $=$ tooth form factor K_f = stress correction factor *m^* ⁼ load sharing ratio $K_f = H + \left(\frac{t}{\pi}\right)^2 \left(\frac{t}{h}\right)^2$ = Dolan-Broghamer Stress Concentration Factor Pressure Angle (Degrees) $H = 0.22$ 14.5 0.18 20
0.20 14.5 $J = 0.20$ 0. 15 20 $L = 0.40$ 14.5
0.45 20 0.45 t, h, and r_f from gear tooth layout (Lewis construction) m_N = normally 1 for spur gears $\frac{1}{\cos\phi}$ $\frac{1}{\mu}$ $\left(\frac{1.5}{\sin\phi}\right)$ for spur gears $Y =$ $\frac{\cos \phi}{\cos \phi}$ $\frac{1}{\cos \phi}$ $\left(\frac{1}{X} \cdot \frac{1}{t}\right)$ ϕ = tooth pressure angle ϕ _L = load pressure angle t ⁼ tooth thickness at the section of maximum stress (Lewis construction) $X =$ tooth strength factor from layout (Lewis construction) r_f = radius of curvature of fillet at point tangent to root circle (may also be calculated) $S_t \leq \frac{Sa}{K_T} \frac{KL}{K_R}$ where $Sa =$ allowable stress for material K_L = life factor temperature factor factor of safety $\kappa_{\rm R}$

In summary, review of **the literature** indicated that wide variations of bending strength **could be calculated for a given** configuration. Little data are available which attempt **to correlate basic material strengths** from laboratory tests with actual gears. It was **thus apparent that a controlled fatigue** experiment with full-size tooth proportions could **aid the development** of **a** more accurate method of calculating bending strength. Basic **material strength** data from R. R. Moore tests for correlation would also enhance the **analysis.**

DESIGN OF EXPERIMENT

Four factors of gear tooth geometry were investigated in a statistically designed experiment. Each of the factors selected was expected to affect gear tooth life. The experiment was designed to indicate if these factors interacted and if the observed results were statistically significant. The geometric factors evaluated were:

The experiment planned involved cycling three gear teeth to failure at each of four stress levels for each of the ¹⁶ possible combinations of the four geometric factors investigated. Evaluation of the effects of the four geometric factors was to be based on the finite life portion of the resulting fatigue (S/N) curves.

DESIGN OF FATIGUE TEST GEARS

Drawings of the ¹⁶ fatigue test gears are presented in Appendix I. Table IV lists the pertinent dimensions for the 16 fatigue test gear configurations.

Diametral pitch values of 6 and 12 were selected. ^A diametral pitch of ⁶ is typical for main power train gears in turboprop and helicopter aircraft engine transmissions. ^A diametral pitch of 12 provides a reasonable 2:1 variation; it also represents typical aircraft engine accessory drive train practice.

The pressure angles of 20 and 25 degrees were selected since they represent aircraft engine design practice.

Each gear tooth design has a maximum fillet radius size that can be accommodated between the active profile diameter **and** the root diameter. Using this maximum value of 100 percent, the minimum fillet radii for the test gears were specified as 80 percent for one design experiment level. **The** other level was set at 50 percent for the 20-degree pressure angle gears and 60 percent for the 25-degree gears to maintain a minimum actual fillet radius of 0. 025 inch. A manufacturing tolerance of 20 percent was thus provided with a minimum variation of 20 percent in fillet size.

The fatigue test gears were made without a rim and web to eliminate possible complications. Twenty-four tooth gears were chosen to avoid undercutting and to provide reasonable gear sizes.

TABLE IV FATIGUE TEST GEAR DIMENSIONS

«HPSTC —high point of single tooth contact.

f

♦♦**Percent of maximum possible.**

6

Face widths of 0.500 inch for the 6-pitch gears and 0.250 inch for the 12-pitch gears were selected to provide slightly larger axial width than tooth thickness at the weakest section in bending. The face widths maintain proportional similarity between the two gear pitches. Carburized case depths were also varied to maintain proportional similarity.

Two root fillet configurations are in general use in aircraft gearing—full form ground and protuberance hobbed. Since almost all aircraft engine gears have ground involute profile surfaces, the root fillet radii can be ground during the same operation, thus producing a "full form" ground gear. The ground root area is subject to grinding burns, excessive case removal, and/or high residual stresses if the grinding procedures are not carefully specified and controlled. Ground root fillets may be produced by formed wheels with true radii or specially shaped fillets, or by generation which produces trochoidal fillets.

Robbing the gear with a special hob that has protrusions at the tips results in a controlled amount of undercut in the root area, thus producing a protuberance gear. Involute grinding can be accomplished after hardening without grinding the root fillet radii. The full residual stress developed by case hardening is retained. The root surface finish will be as hobbed unless a grinding operation is incorporated.

^A trochoidai fillet is produced by a protuberant hob or shaper cutter. (The undercut could be broached into the gear tooth.)

The protuberance cut gears are necessarily slightly thinner at the weakest section and have smaller root diameters as compared with full form ground gears; thus, the bending stress is increased. The material strength should also be greater. The resulting fatigue life, however, is not predictable because of the many factors involved which can not be accurately assessed.

^A generated ground fillet was used for the f-:ll form gears to maintain similarity with the protuberant fillet configuration. All gears were shot peened in the root. The fillet type designation part of the designed experiment, therefore, included changes in tooth thickness, root diameter, case depth, and surface treatment. Figure ⁶ shows two typical fatigue test gears.

MANUFACTURE OF FATIGUE TEST GEARS

Fatigue test gear manufacturing was controlled to minimize variation within and between each of the ¹⁶ groups. Significant efforts were made to maintain constant metallurgical microstructure and surface treatment as well as geometry. Specific items of control were as follows.

- All material was from ^a single heat (Carpenter Steel Company heat number 61629). The material was forged from 6-inch round corner squares to 2. 875- and 5. 125 inch bar stock form. The raw material record is given in Table V.
- All heat treat operations were performed at the same time except carburizing (due to two different case depths required) and stress relief after grinding (due to time limits).
- Copper plating prior to hardening and stripping of copper plate after hardening were each accomplished simultaneously on all parts.
- Shot blasting and peening were accomplished simultaneously on all gears of each group.

Figure 6. Typical Fatigue Test Gears.

- Gear tooth hobbing and grinding were accomplished by using an arbor that stacked all gears of each group. Each gear was honed separately.
- All test gears were black-oxide coated simultaneously (except for several sets which were processed early to permit initiation of testing).
- The high point of concentricity of all gears in each set was matched at each gear grinding operation, and gears were carefully aligned to obtain uniformity of stock removal.

TABLE V RAW MATERIAL RECORD

TABLE V (CONT) RAW MATERIAL RECORD

Many in-process and finished part measurements were made to $h =$ define stock removal and to record the final geometry of each part. Tables VI and VII list the protuberant **cut gear measurements and** analysis. Tables VIII and EX provide comparable data **for the ground fillet gears.**

The root diameter, dimension over pins, root radius, and protuberance undercut depth **are the critical** dimensions for the fatigue specimens.

Most of **the** gears had some, usually slight, dimensional deviation. All the gears of **each** group were well within the dimensional tolerance limits. Thus, ropeatabilily of **fatigue test** data within any group should be excellent due to the stack machining techniques employed. Some variation from the designed experiment, however, may occur between groups. These variations could be eliminated by basing bending stress calculations on actual rather than print dimensions.

Sample routing sheets for a full ground (EX-78772) and a protuberant cut gear (EX-78776) are given in Appendix II,

Table ^X lists the fatigue test gear hob dimensions necessary to define the gear tooth root fillet shape. The dimensions given must be modified by the finish stock allowance to obtain an accurate finished gear configuration. The full ground root fillet configuration hobs are listed to permit analysis of the finish stock allowance in the root fillet area rather than for bending stress determination.

TEST RIG DESIGN AND PROCEDURE

The test rig was designed for single tooth fatigue testing of either the 2- or 4-inch-pitchdiameter gear. Single tooth testing was sclected over a dynamic four-square gear test to permit accurate control of test variables. Adjacent teeth on the test gear were removed to ensure single tooth contact.

Two design concepts were considered for the fatigue testing device — a hydraulic servovalve system where a measured torque is applied on the test gear to produce the desired tooth load and an electromagnetic shaker for use as the input loading device. The two concepts were evaluated on the basis of available equipment, usage experience, and inherent advantages and disadvantages. Design studies showed that the electromagnetic shaker was preferred, provided that a high frequency of operation could be achieved at the specified test loads. Additional considerations were accurate tooth load measurements and good dynamic stability.

To achieve the desired operational requirements, a fatigue test rig was designed with inherent high axial and radial stiffness of all load transmitting and reacting components and with a load cell at the point of **tooth** loading. The fatigue rig was coupled to an e'ectromagnetic shaker. Operation at or near a system resonance of approximately 200 c. p. s. was realized. The principle of operation of the fatigue test rig is shown sche matically in Figure 7.

The shaker driving force was applied directly to a mass which, in turn, loaded the gear tooth through a load cell. The mass was supported flexibly in the direction of loading and was stabilized in all radial directions by two disk-type flexible plates.

TABLE VI TABULATION OF PROTUBERANT FILLET GEAR MEASUREMENTS*

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TABLE VH ANALYSIS OF PROTUBERANT FILLET GEAR MEASUREMENTS*

*** All dimensions in inches.**

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** Dimension over pins calculated for 0.000 to 0.004 backlash with mating gear on standard centers. Therefore, dimension over pins tolerances equivalent to 0.002 change in tooth thickness or 0.001 stock allowance per surf The 0.0039 tolerance for 25-degree pressure angle gears and 0.0300 average finishing stock after hob are equ to 0.0077 per surface. The 0.0047 tolerance for 20-degree pressure angle gears and 0.0355 finishing stock af **hob are equivalent to 0. 0076 per surface.**

***** Questionable reading—deleted from averages.**

tFc)r large-diameter gears.

ir on standard centers. Therefore, **IFC i** For small-diameter gears. *is* **or 0.001 stock allowance per surface. ige finishing stock after hob are equivalent ; gears and 0. 0355 finishing stock after**

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TABLE VIII TABULATION OF GROUND FILLET GEAR MEASUREMENTS*

All dimensions in inches. $\pmb{\ast}$

** Setup part not included.

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TABLE IX ANALYSIS OF GROUND FILLET GEAR MEASUREMENTS*

*** All (iimeiisions in inches.**

** Dimension over pins calculated for 0,000 to 0.004 backlash with mating gear on standard centers. **pins tolerances equivalent to 0. 002 change in tooth thickness or 0. 001 stock allowance per surface.** 25-degree pressure angle gears and 0.0300 average finishing stock after hob are equivalent to 0.00 **tolerance for 20-degree pressure angle gears and 0. 0355 finishing stock after hob are equivalent to**

- **t** For large-diameter gears.
- **[|] t For smal1-diameter gears.**

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. There! , e. The ^C 0077 per ., aishing stock after hob are equivalent tc 0. 0076 per surface. to 0.007(with mating gear on standard centers. Therefore, dimension over s or 0, 001 stock allowanee per surface. The 0. 0039 tolerance for ig stock after hob are ^e quivalent to 0. 0C 77 per surface. The 0. 0047

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Figure 7. Principle of Operation of Fatigue Test Rig.

The required static preload was provided by compressing a relatively low spring rate coil spring. Inertia loading of the tooth, using the moving mass, made possible considerable force amplification at and near the system axial resonance. The forced dynamic load was about the mean value which, in this case, was the static preload. Figure 8 shows the test rig in its final configuration. Figure 9 shows the rig coupled to the shaker.

The load cell incorporated at the point of tooth loading to provide accurate control of both static and dynamic tooth loading during fatigue testing was an Allison designed strain gage type cell. Figure 10 shows the load cell instrumented with axial and circumferential strain gages, and Figure ¹¹ shows the load cell in its final assembly. The strain gage hookup was a four-active-arm bridge. The bridge signal output was directly proportional to the change in applied thrust, independent of load cell bending and temperature change, and $2(1 + \mu)$ **times** as large as the corresponding output of a single strain gage. The symbol μ is Poisson's ratio.

The automatic control system of the electromagnetic shaker was not used. Excellent control stability was realized by manual control.

A series of check-out procedures was performed prior to dynamic testing. The following paragraphs present the check-out procedures in the sequence in which they were performed.

• Radial Spring Rate of Fatigue Rig

The fatigue rig was installed in the electromagnetic shaker and instrumented with dial indicators as shown in Figure 12. With gear EX-78784 installed and statically loaded by means of the bias spring loading device, the radial deflections were measured. The radial spring rate of the system as determined by test was 5,900, 000 pounds/inch. This high radial spring rate verified the design objective of high system stiffness to ensure accurate load application at the high point of single tooth contact and good alignment of all moving parts during operation.

• Dimensional Check-Out

Measurements were made to verify that contact between the load member tip and the gear tooth occurred \cdot ; the high point of single tooth contact. The measurements verified tip spacing to the center of the pilot shaft to be as designed, and to ensure tip contact at the high point of single tooth contact during fatigue. Figures 13 and 14 show typical dimensions for the 6- and 12-pitch gears.

• Tooth Load Distribution

Gear EX-78784 was designated as the check-out gear. The gear was instrumented with strain gages and a thermocouple, as shown in Figure 15. The instrumented gear was installed in the fatigue test rig, and a static load was applied in 1000-pound increments to 3000 pounds. The strain read-out of the two gages on face A was compared for indication of nonuniform loading or misalignment, The gages indicated uniform loading and good alignment. Accurate location of the strain gages was verified by inserting a small piece of shim stock, 0. 003 inch thick, between the load member tip and the gear tooth. The shim stock was inserted an equal distance on both sides of the gear tooth, and differential strain was compared. The differential strain was of equal value, verifying good strain gage location.

• Dynamic Resonance Frequency

To determine the system operating frequency, a frequency scan was made versus shaker driver current. With the check-out gear installed and preloaded to 1000 pounds, the frequency scan was made from ⁵⁰ to 500 c. p. s., plotting driver current while dynamically applying ± 800 pounds of load to the gear tooth. The frequency scan indicated that the system resonance frequency was 240 c.p. s. with a reduction of 20:1 in driver coil current at resonance. Figure ¹⁶ shows the relative response.

• Dynamic Separation

To ensure continued contact betwe jn the gear tooth and the load member tip and to determine differential load margin, the output signal of a dynamic gage on face B was displayed on an oscilloscope. By varying the dynamic load about a constant preload, the signal wave shape was analyzed. Figure 17 presents the pictorial wave shape analysis. The analysis shows that a minimum of 20 pounds differential is required to maintain contact between the tooth and load tip.

• Load Cell Calibration

To eliminate inaccuracies in the loading, a precise calibration was made on the load cell. The load cell was tested in a Baldwin press as shown in Figures ¹⁸ and 19. The load was applied in 500-pound increments to 5000 pounds maximum; the output of the strain gage bridge was recorded. Each load cell was tested five times for repeatability. Figure 20 shows typical calibration data, The calibration of the load cell repeated within one percent in the new condition and within two percent after usage.

To allow the load member tip to contact the gear test tooth at the high point of single tooth contact, a number of teeth were removed as shown in Figure 21. Figure 21 shows load sides A and B. Teeth 1, 2, 3, and 4 are the test teeth, and teeth $1X$, $2X$, $3X$, and 4X are the load reaction teeth.

Figure 8. Fatigue Teat Rig Schematic.

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Figure 10. Load Cell Showing Instrumentation.

Figure 11. Assembled Load Cell.

Figure 12. Instrumented Fatigue Test Rig.

Figure 13. Typical Dimensions of 6-Pitch Gear Test Setup.

Figure 14. Typical Dimensions of 12-Pitch Gear Test Setup.

Figure 16. Test System Resonant Frequency.

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Load Member • Bridge

Dynamic Strain Gage

Alternating Load-+1230 Pounds No Separation No Separation

Static Preload—1320 Pounds
Alternating Load— \pm 1230 Pounds
Alternating Load— \pm 1310 Pounds

Separation Separation

Static Preload—1320 Pounds Static Preload—1320 Pounds Alternating Load—±1345 Pounds Alternating Load—±1380 Pounds

Figure 17. Dynamic Strain Gage Signal Showing Tooth-to-Load Tip Contact.

Figure 18. Load Cell Test Setup.

Figure 19. Close-up of Load Cell Test Setup.

Figure 20. Typical Load Cell Calibration Curve.

Figure 21. Test Gear Showing Teeth Removed.

The test procedure required that the test tooth, once positioned, be preloaded with a bias load which was equal to one-half of the total fatigue load. Once the preload was obtained and verified by the load cell, an alternating load was applied about a mean which was the preload. The tentative plan was that three gear teeth be tested for each combination of variables until fatigue failure occurred or 10^7 cycles were accumulated.

During testing, the dynamic load at the load cell (signal from strain gage bridge) was monitored and recorded on a strip chart recorder. A typical strip chart recording is shown in Figure 22.

Figure 22. Typical Strip Chart Recording of Test Gear Dynamic Load.

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RESULTS

FATIGUE TESTS

The fatigue test program was based on a designed experiment for evaluation of four **geometric variables**—diametral pitch, pressure angle, root fillet size, and root fillet configuration. **Two** levels of each variable were employed requiring ¹⁶ different gear **configurations. See** Table IV. Initially, three teeth from each gear configuration were **to be tested at** four stress levels. Failures were required to permit test evaluation **on the** finite portion of the S/N curve. Early test experience with the small ¹² diametral pitch gears indicated only a 30-percent spread between the desired m_k imum and maximum stress levels. The maximum stress was determined by the short test time (3 to ⁵ minutes) and high stresses that could cause plastic yielding and thus result in **a** different mode of failure. The minimum stress was determined by a high percent of runouts to 10,000, 000 cycles without failure. It was decided, therefore, to obtain fourfailures at three stress levels to permit a 10-percent difference between levels.

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Table XI lists the fatigue test data—load, cycles to failure, and configuration—for the 214 gear teeth tested. Of this total, 173 failed; the remaining gear tooth tests were terminated at 2×10^6 or 10^7 cycles.

Fatigue test data for each configuration are plotted as S/N curves based on unit load in Figures 23 through 38. Unit load is defined as tne equivalent load in pounds on a tooth having a diametral pitch of ¹ and a face width of ¹ inch. The mean curve drawn through the data was calculated by a procedure explained in detail in Appendix **III.** Proportionality factors can be used to relate applied load (test rig load), unit load, Lewis stress, Dolan-Broghamer stress, AGMA stress, Heywood stress, and Kelley-Pedersen stress for any single gear configuration. Therefore, S/N curves of the test data based on any of these stress calculation methods would produce the same fit of the mean curve to the data points. S/N curves based on AGMA calculated stress are presented in Appendix IV.

A series of reworks was initiated during the test program to modify or perfect parts related to the fatigue rig. The areas involved are discussed in the following paragraphs.

Cooling Air

As a result of the high fatigue loads required for the gears having a diametral pitch of 6, it became necessary to provide cooling air to the fatigue tooth at the tension fillet *and* lubrication between the tooth and load cell tip. The need for cooling air at the compression fillet became apparent when two gears cracked from the tooth root to the gear center. Metallurgical analysis indicated that high localized temperatures existed during the final phase of tooth fatigue. Additional cooling air eliminated this problem. All but three teeth on the large gears **were** tested with the additional cooling air. It is believed that the test results for these three teeth were not seriously biased.

Tip

The initial design specified that the contact surfaces of the tips be coated with plasma spray tungsten carbide. The process was to provide a surface which would offer resistance to wear, scuffing, and distortion. **However,** after limited usage, the coating cracked and cavitated. **The first** rework, **nitriding the** contact surface, was an improvement under low-load conditions, but the surface distorted under high loads. The second

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							Test	
Part	Serial	Tooth	Load (pounds)			Cycles to	Frequency	Y Corr
Number	Number	Number	Static	Dynamic	Total	Failure	(c, p, s,)	S/N Side
EX-78772	CX 9092	$\mathbf{1}$	5340	5300	10,640	Void Data		0.3657
		$\mathbf 2$	4810	4770	9,580	1 585×104	220	0.3657
		3	4810	4770	9,580	1.715×10^4	220	0.3637
			4810	4770	9,580	2.38×104	220	0.3597
	CX 9091		4430	4230	8,660	1.06×10^4	220	0.3697
		$\bf{2}$	4430	4230	8,660	1.32×10^4	220	0.3577
		$\overline{\mathbf{3}}$	4430	4230	8,660	1.3×10^4	220	0.3677
		$\overline{\mathbf{4}}$	3995	3795	7,790	2.38×10^4	220	
	CX 9090	$\mathbf{1}$	3600	3400	7,000	5.8×10^{4}	220	
		$\mathbf 2$	3995	3795	7,790	4.8×10^{4}	220	
		$\overline{\mathbf{3}}$	3995	3795	7,790	4.0×10^4	220	
EX-78774	CX 9067	$\mathbf{1}$	5900		Void Data High Dynamic Load		220	0.3547
		$\overline{\mathbf{c}}$	5390	5190	10,580	1.188×10 ⁴	220	0.3607
		3	5390	5190	10,580	8.9×10^3	220	0.3617
		$\overline{\mathbf{4}}$	5390	5190	10,580	6.6×10^3	220	0.3557
	CX 9068	$\mathbf{1}$	4860	4660	9,520	1.076×10^4	220	0.3576
		$\overline{\mathbf{2}}$	4860	4660	9,520	1.32×104	220	0.3576
		$\overline{\mathbf{3}}$	4860	4660	9,520	1.32×10^4	220	0.3546
		4	4385	4185	8,570	3.43×10^{4}	220	0.3586
	CX 9064		4385	4185	8,570	1.32×10^4	220	0.3536
		$\bf{2}$	4385	4185	8,570	1.98×10^{4}	220	0.3616
		$\mathbf{3}$	4385	4185	8,570	2.64×10^4	220	0.3536
		$\boldsymbol{4}$	4385	4185	8,570	1.85×10^4	220	0.3536
	CX 9065	$\mathbf{1}$	4385	4185	8,570	1.7×10^4	220	0.3586
		$\mathbf 2$	4385	4185	8,570	1.85×10^4	220	0.3606
		$\overline{\mathbf{3}}$	4385	4185	8,570	2.64×10^{4}	220	0.3496
		4	4385	4185	8,570	1.85×10^4	220	0.3526
EX-78776	CX 9010		4340	4300	8,640	6.6×10^3	220	0.3793
		$\boldsymbol{2}$	3910	3870	7,780	7.92×104	220	
		3	3910	3870	7,780	1.32×10^4	220	
		4	3910	3870	7,780	1.04×10^4	220	0.3933
	CX 9008	$\mathbf{1}$	3600	3400	7,000	1.78×10^4	220	
		$\mathbf 2$	3600	3400	7,000	5.94×10^4	220	0.3873
		3	3600	3400	7,000	206×10^{4}	220	
		4	3250	3050	6,300	6.6×10^{4}	220	0.3903
	CX 9009		2950	2750	5,700	$10^7 \rightarrow$	220	
		\bf{c}	325%	3050	6,300	Void Data		0.3883
		3	3250	3050	6,300	Void Data		
		$\overline{\mathbf{4}}$	3250	3050	6,300	1.3×10^5	220	
	CX 9007	$\mathbf{1}$	3250	3050	6,300	5.3×10^4	220	
						2.9×10^{4}		
EX-78778	CX 9054	\mathbf{I} $\overline{\mathbf{2}}$	4400	4200 4200	8,600		220	0.3637
			4400		8,600	3.96×10^{4}	220	0.3757

TABLE XI GEAR TEETH FATIGUE TEST DATA

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					Test Frequency			
Part	Serial	Tooth	Load (pounds)			Cycles to	(c, p, s,)	
Number	Number	Number	Static	Dynamic	Total	Failure		
		3	4400	4200	8,600	2.1×10^4	220	
		4	3970	3770	7,740	9.23×10^{4}	220	
	CX 9057		3970	3770	7,740	8.71×10 ⁴	220	
		$\overline{\mathbf{c}}$	3970	3770	7,740	1.346×10^5	220	
		3	3583	3383	6,965	Void Data \rightarrow		
		4	3583	3383	6,965	2.0 \times 10 ⁶ →	220	
	CX 9056	$\mathbf{1}$	3583	3383		7.65×10^4	220	
		$\overline{\mathbf{2}}$	3583		6,965	6.6×104	220	
				3383	6,965			
EX-78780	CX 9097	1	4900	4700	9,600	5.28×10^5	220	
		$\overline{\mathbf{2}}$	4900	4700	9,600	6.6X10 ⁴	220	
		3	4900	4700	9,600	5.94×10 ⁴	220	
		4	5500	5300	10,800	4.62×10 ⁴	220	
	CX 9098	1	5500	5300	10,800	4.125×10 ⁴	220	
	CX 9095	$\mathbf{1}$	5500	5300	10,800	4.62 \times 10 ⁴	220	
		$\overline{\mathbf{2}}$	4420	4220	8,640	2.0×10^5	220	
		3	4420	4220	8,640	1.85×10 ⁵	220	
		4	4420	4220	8,640	1.85×10 ⁵	220	
	CX 9096	$\mathbf{1}$	6040	5840	11,880	1.32×10^4	220	
		$\overline{\mathbf{2}}$	6040	5840	11,880	6.6×10^3	220	
		$\overline{\mathbf{3}}$	6040	5840	11,880	6.6×10^3	220	
EX-78782	CX 9113	$\mathbf{1}$	6360	6160	12,520	9.5×10^3	220	
		$\overline{\mathbf{2}}$	6360	6160	12,520	Void Data	$\overline{}$	
		$\overline{\mathbf{3}}$	5730	5530	11,260	5.38×10^4	220	
		4	5730	5530	11,260	1.42×10^5	220	
	CX 9112	$\mathbf{1}$	5110	4910	10,020	1.19×105	220	
		$\overline{\mathbf{2}}$	5110	4910	10,020	5.93×10^4	220	
		3	511C	4910	10,020	$2.0 \times 10^6 \rightarrow$	220	
		4	4600	4400	9,000	107	220	
	CX 9111		5730	5530	11,260	1.32×10 ⁴	220	
		$\mathbf 2$	6360	6160	12,520	1.32×10^4	220	
		3	6360	6160	12,520	1.76×10 ⁴	220	
EX-78784	CX 9072	1	5250	5050	10,300	1.8×10^4	220	
		$\overline{\mathbf{c}}$	5250	5050	10,300	1.8×10^4	220	
		3	5250	5050	10,300	8.6×10^3	220	
		4	4220	4020	8,240	1.345×10^5	220	
	CX 9070	1	4220	4020	8,240	$2.0 \times 10^6 \rightarrow$	220	
		$\mathbf 2$	4220	4020	8,240	3.313×10^5	220	
		$\bf{3}$	3800	3600	7,400	2.0 \times 10 ⁶ →	220	
		\ddagger	3800	3600	7,400	2. 0×10^6 →	220	
	CX 9073	$\mathbf{1}$	3800	3600	7,400	3.96×10^{3}		
							220	

TABLE XI (CONT)

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TABLE XI (CONT)

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TABLE XI (CONT)

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rework involved fabricating tips with carburized surfaces. The carburized surfaces **did not distort** under high **load; thus,** carburizing appeared to be a desirable process **for this type of testing. It is believed that** the difficulties encountered did not affect **the data because** each condition **was** recognized early and was corrected.

Another difficulty involved tip rotation under high loads during the fatigue test of the 4. O-inch-pitch-diameter gears. By rotating, the load point was changed; thus, one data point was affected and was discarded. To prevent rotation, a small piece of shim stock was spot-welded to the outside diameter of the tip and load cell, locking the two together and preventing rotation.

Gage Locating Block

Interference between the gage locating block and the stub tooth was discovered early in the program. This interference **would have** prevented true angular positioning of the gear tooth on the contact surface of the tip, thus defining a load point other than the high point of single tooth contact. The gage blocks were reworked for clearance; no data points were affected.

Bias Spring

The original bias spring had a spring rate of 2000 pounds per inch, which was not sufficient to preload the 4. O-inch-pitch-diameter gears. Therefore, springs with a spring rate of 20,000 pounds per inch were purchased to satisfy the preload requirements.

Load Cell

It was discovered during the rework of the tips that the squareness and flatness of the tip surface mating with the load cell affected load cell calibration. The rework that most effectively corrected this difficulty was lapping of the two surfaces. Once good surface contact was established, the difficulty was eliminated. A number of data points (32 total) were affected by this condition. ^A series of tests was conducted where this condition existed; the test was duplicated. This yielded a correction factor which was applied to the affected data points. It is believed that the data were corrected with sufficient accuracy to avoid distortion of the final evaluation.

Test Frequency

The gears having a diametral pitch of 12 were tested at two frequencies—50 and **240** c. p. s. The frequency of 240 c.p. s. **was** at system resonance. The 50-c.p. s. frequency was selected for use at the **higher** test loads to provide increased duration of fatigue test time. The time required **to** establish the test rig load was thereby maintained small when compared with the fatigue time at load. The literature indicates that less than a 2-percent difference in fatigue life would be expected from this change in frequency (reference 20). A similar nonresonance operating procedure was not possible with the gears having a diametral pitch of 6 without overloading the shaker. Quicker establishment of the load on the larger gears was possible without overloading, so there was no strong requirement for a drop in test frequency.

FAILED GEAR TOOTH CRACK MEASUREMENTS

A comparison was made of the calculated location of the weakest section of each

tooth and the actual location. To do this, the crack in each tailed tooth was measured and recorded. See Table XI. The bar charts in Figures 39 and 40 summarize the results of this investigation. For each configuration, the location of the crack at the tooth surface was measured from the outside diaaieter and center line of the tooth, within an estimated 0.002 inch. The average dimension corrected for outside diameter variations is plotted for comparison with the theoretical locations as determined by both Lewis and Kelley-Pedersen construction. The charts indicate that for all configurations, Kelley-Pedersen construction locates the weakest section of the tooth closer to the actual measured location than does Lewis constriction. The gears having a diametral pitch of 12 show the measured location to be, on the average, 0, 015 inch closer to the root than the Lewis theoretical locations. In the gears having a diametral pitch of 6, the deviation is proportional or 0. 030 inch closer to the root than the calculated Lewis location. For a graphical presentation of these data, a typical tooth profile trace of each configuration was made. Two such traces are shown in Figures 41 and 42. The weakest section is shown on each trace as calculated by Lewis and Kelley-Pedersen **and** as measured.

It would be **natural** to conclude from the examination of these results alone that the Kelley-Pedersen construction provides a more accurate means to locate the true weakest **section** of the tooth. However, fatigue test data have already shown that the AGMA stress formula using the Lewis tooth form factor most nearly approximates the endurance characteristics of the gear material. The reason for this paradox may be the change of tooth geometry as the tooth deflects under load. Another possibility is the Kelley-Pedersen stress formula, which was derived from a photoelastic study. It may be assumed that the method derived for locating the weakest section is accurate, as the experimental data show. However, the stress concentration factor employed may require modification to obtain a stress value comparable to the true stress in the material. Unfortunately, further pursuit of this phase of the investigation was not possible within the scope of this program; it should be considered, however, in future studies.

Crack measurements were obtained on twelve EX-78774 gears (configuration 3). These data were statistically analyzed to calculate a standard deviation of 0.48×10^{-4} and a variance of 0.234×10^{-4} from the 0.3581 corrected average "Y" value for this configuration. These data tend to indicate the consistency of fatigue test gear manufacturing and test.

METALLURGICAL INVESTIGATIONS

Metallurgical examinations of failed test gears were conducted to determine mode of failure, origin of failure, microstructure, case depth, hardness gradient, and material cleanliness.

Six gears were submitted for metallurgical investigation as follows:

Calculated Location of Weakest Section From Gear Figure 39. Location of Fracture Compared With Outside Diameter (Diametral Pitch = 6).

go C) **oM ii** ^o **J3 a*** ^o a> **CO -u** 3 rn **ft. t5** \mathbf{e} metra. **C** \mathbf{r} On \mathbf{r} \mathbf{r}
 \mathbf{r} On \mathbf{r} \mathbf{r} **¹ 0) ⁵ ⁵ ^s o T3 0)** Q **Tf** •<-> e**n**
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The following metallurgical conclusions were made.

- Failure of the tested teeth occurred in fatigue.
- The fatigue failures of the tested gear teeth originated in the carburized case of the root radius below the loaded involute.
- Electron fractographs were used to determine the precise origin of failure. The failures appeared to be predominantly multiple.
- The microstructure of the carburized case of the various gears was typical of spheroidized carbides in a martensitic matrix with no indication of carbide network in the areas of failure in the root radii. The core microstructures were of tempered martensite.
- The effective case depth, measured to the R_c 50 level, was indicated to be approximately 0.030 inch on test gears (EX-78773 and EX-78775); approximately 0.040 inch on test gears $EX-78777$, $EX-78779$, and $EX-78782$; and approximately 0. 050 inch on test gear EX-78784.
- The test gear material was clean and free from inclusions.
- The material conformed to the compositional requirements of AMS-6265.

Electron fractographs of the failure surfaces of the four failed teeth of test gear EX-78784, serial number CX 9069, confirmed a fatigue failure mode on each surface, as shown in Figures 43, 44, 45, and 46. Visual examination of the failure surfaces of the failed teeth of all submitted gears revealed similar straight-line failures, some of which displayed occasional arrest lines of progressing, typical of fatigue, originating in the root radii. Visual examination of test gear EX-78782, serial number CX 9113, revealed an additional fatigue failure progressing radially from below the root on the nonloaded side of a failed tooth to the center of the gear. (This isolated failure, discussed in the subsection titled Fatigue Tests, was due to localized temperature and was subsequently corrected by cooling the gear.) Microexamination of transverse sections through the failure surfaces of failed teeth from each of the submitted gears revealed straight-line failures typical of fatigue. These failures originated in the carburized case structure in the root radius below the loaded involute, as shown in Figures 47 through 52. The failures, typically, had multiple origins, indicating equalized loading in clean material. Unetched, polished specimens revealed good material quality. The microstructures were of spheroidized carbides in a martensitic matrix with no carbide network in the case and tempered martensite in the core. A typical core microstructure **of** tempered martensite is shown in Figure 53. Effective case depth measured to the R_c 50 level varied approximately 0. 030 inch on part numbers EX-78773 and EX-78775; approximately 0. 040 inch on part numbers EX-78777, EX-78779, and EX-78782; and approximately 0. 050 inch on part number EX-78784. Case hardness of the various test gears was R_c 61 to 62 at 0.002 inch below the surface with a diminishing gradient as shown in Table XII. Spectrographic analysis indicated conformance of the material in the test gears to the compositional requirements of AMS-6265. Photographs indicating case depths around root fillet contour are shown in Figures 54 through 59.

Fluorescent penetrant inspection of the test gears indicated that all failures of the teeth occurred in the root radii, as indicated in Figures 60 through 65. **Fluorescent** penetrant inspection of test gear part number EX-78782, serial number CX 9113, revealed an additional radial crack, as shown in Figure 64. Visual examination **of the** surfaces of failure revealed flat fractures with multiple origins of failure, **but** only occasional arrest lines indicative of fatigue, as shown in **Figures** 66 **through 70.** Visual examination of the failure surface of the radial **failure** in **test gear part number** EX-78782, serial number CX 9113. revealed a **smooth failure** with **arrest lines of** progression, typical of fatigue, originating below **the root radius** on **the unloaded side** of a failed tooth and progressing to the hub. as shown in Figure 71.

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Magnification: 2,500X Magnification: 10,000X

EX-78784, Serial Number CX 9069

Figure 43. Fractographs of Surface of Failure of Gear Tooth Number 1 Showing Failure Contour Typical of Fatigue.

Magnification: 2,500X Magnification: 10,000X

EX-78784, Serial Number CX 9069

Figure 44. Fractographs of Surface of Failure of Gear Tooth Number 2 Showing Failure Contour Typical of Fatigue.

Magnification: 2,500X Magnification: 10,000X

r:X-78784, Serial Number CX 9069

Figure 45. Fractographs of Surface of Failure of Gear Tooth Number ³ Showing Failure Topography Typical of Fatigue.

Magnification: 2,500X Magnification: 10,000X

EX-78784, Serial Number CX 9069

Figure 46. Fractographs of Surface of Failure **of Gear Tooth Number 4** Showing Failure Topography Typical of **Fatigue.**

Magnification: 100X Etchant: Vilella's Reagent EX-78773, Serial Number CX 9077

Figure 47. Photomicrograph of Transverse Section Through Failure Surface of Failed Tooth Showing Straight-Line Failure Typical of Fatigue Originating in the Carburized Case Hardened Root Radius.

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Magnification: 100X Etchant: Villella's Reagent EX-78775, Serial Number CX 9100

Figure 48. Photomicrograph of Transverse Section **Through Failure Surface of Failed** Tooth Showing Straight-Line Failure Surface Typical **of Fatigue** Originating in **the** Case Hardened Root Radius.

Magnification: 100X Etchant: Vilella's Reagent EX-78777, Serial Number CX 9059

Figure 49. Photomicrograph of Transverse Section Through Failure Surface of Failed Tooth Showing Straight-Line Failure Surface Typical of Fatigue Originating in Carburized Case in the Root Radius.

Magnification: 100X Etchant: Vilella's Reagent EX-78779, Serial Number CX 7104

Figure 50. Photomicrograph of Transverse Section Through Failure **Surface of Failed** Tooth Showing Straight-Line Failure Surface Typical of Fatigue **Originating** In **the** Case Hardened Root Radius.

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Magnification: 100X Etchant: Villella's Reagent EX-78782, Serial Number CX 9113

Figure 51. Photomicrograph of Transverse Section Through Failed Tooth Showing Straight-Line Failure Typical of Fatigue Through a Carburized Case on Martensitic Microstructure.

Magnification: 100X Etchant: Vilella's Reagent EX-78784, Serial Number CX 9069

Figure 52. Photomicrograph of Transverse Section Through Failure Surface of Failed Tooth Showing a Straight-Line Failure Surface Typical of Fatigue Through Case Hardened Microstructure.

Magnification: 250X Etchant: Vilella's Reagent EX-78777, Serial Number CX 9059

Figure 53. Photomicrograph of Transverse Section Through Test Gear Showing Typical Core Structure of Tempered Martensite.

Figure 54. Photograph of Section Through Test Gear Showing Case Depth Around Root Fillet Contour.

Magnification: $6 \times$ EX-78775, Serial Number CX 9100 **Figure 55. Photograph of Section Through Test** Gear **Showing** Case **Depth Around Root Fillet Contour.**

Magnification: 6X EX-78777, Serial Number CX 9059

Figure 56. Photograph of Section Through Test Gear Showing Case Depth Around Root Fillet Contour.

Magnification: $6X$ EX-78779, Serial Number CX 9104

Figure 57. Photograph of Section Through Test Gear Showing Carburized Case Depth Around Root Fillet Contour.

Magnification: 6X EX-78782, Serial Number CX 9113

Figure 58. Photograph of Section Through Test Gear Showing Carburized Case Depth Around Root Fillet Contour.

Magnification: 6X EX-78784, Serial Number CX 9069

Figure 59. Photograph of Section Through Test Gear Showing Carburized Case Depth Around Root Fillet Contour.

Magnification: IX EX-78775, Serial Number CX 9077

Figure 60. Blacklight Photograph of Test Gear Showing Cracks Indicated by Fluorescent Penetrant Inspection in Root Radii of Tested Teeth.

Magnification: IX EX-78775, Serial Number CX 9100

Figure 61. Blacklight Photograph of Test Gear Showing Cracks Indicated by Fluorescent Penetrant Inspection in Root Radii of Failed Teeth.

Magnification: IX EX-78777, Serial Number CX 9059

Figure 62. Blacklight Photograph of Test Gear Showing Cracks Indicated by Fluorescent Penetrant Inspection in Center Root Radius Adjacent to Failed Tooth.

Magnification: IX EX-78779, Serial Number CX 9104

Figure 63. Blacklight Photograph of Test Gear Showing Cracks Indicated by Fluorescent Penetrant Inspection in Root Radii of Failed Teeth. \circ

Magnification: IX EX-78782, Serial Number CX 9113

Figure 64. Blacklight Photograph of Test Gear Showing Radial Crack and Failed Teeth.

Magnification: 1X EX-78784, Serial Number CX 9069

> Figure 65. Blacklight Photograph of Test Gear Showing Cracks Indicated by Fluorescent Penetrant Inspection in Root Radii of Teeth 1, 2, 3, and 4.

Magnification: 9X EX-78773, Serial Number CX 9077

Figure 66. Photomicrograph of Surface of Failure of Tooth From Test Gear.

Magnification: 9X

EX-78775, Serial Number CX 9100

Figure 67. Photomicrograph of Surface of Failure of Failed Tooth From Test Gear Showing Flat Failure in Root Radii of Teeth.

Magnification: 9X EX-78779, Serial Number CX 9104

Figure 68. Photomicrograph of Surface of Failure of Tooth From Test Gear.

Magnification: 9X EX-78782, Serial Number CX 9113 Figure 69. Photomicrograph of Surface of Failure of Tooth 1 of Test Gear Showing Multiple Origins of Failure in Root of Loaded Involute - No Typical Arrest Lines of Fatigue Progression.

Magnification: 9X EX-78782, Serial Number CX9113 Figure 70. Photomicrograph of Surface of Failure of Tooth 3 of Test Gear Showing Multiple Origins of Failure and No Distinct Arrest Lines Typical of Fatigue Progression.

Magnification: 5X EX-78782 Serial Number CX 9113

Figure 71. Photomicrograph of Radial Surface of Failure of Test Gear Showing Marks of Fatigue Progression From Below the Root to the Hub.

Depth Below	R_c Readings							
Carburized	EX-78773	EX-78775	EX-78777	EX-78779	EX-78782	EX-78784		
Surface (inch)	CX 9077	CX 9100	CX 9059	CX 9104	CX 9113	CX 9069		
0.002	61	62	61	62	61	61		
0.005	61	61	60	61	61	61		
0.010	60	60	58	59	60	62		
0.015	56	58	57	55	57	62		
0.020	55	58	57	54	57	57		
0.025	55	54	55	54	55	57		
0.030	$51*$	$51*$	53	55	53	56		
0.035	46	46	51	55	51	56		
0.040	42	46	$51*$	$53*$	$48*$	55		
0.045	40	44	47	47	46	52		
0.050	42	45	46	48	46	$52*$		
0.055	42	43	45	46	44	48		
0.060	41	43	45	45	43	45		
0.065	41	41	42	44	44	46		
0.070	41	41	42	43	43	45		
0.075				42	42	45		
0.080					42	45		
0.085						43		
0.090					$-$	43		

TABLE XH RECORD OF HARDNESS GRADIENT TESTS OF TEST GEARS

All hardness readings were taken at the root radii adjacent to the failure surface.

R. R. MOORE TESTS

R. R. Moore test specimens **were** manufactured from the same heat of material as the **test gears.** Manufacturing **followed** heat treating and grinding routings used for the **gears** as **closely** as **feasible.** The process routing for the specimens is presented in **Table Xm. The test results are** given in Table XIV.

TABLE XIII SPECIMEN PROCESS ROUTING PROCEDURE

- Carburize and anneal per EPS* 202 to an effective case depth of 0.035 inch as determined by the fracture specimen.
- 2. Harden and temper per EPS 202 and PCI** 8000 and stabilize per EPS 202.
	- Core Hardness $-R_c$ 40 Case Hardness $-R_{15/N}$ 90 (R_C 60)
- 3. Grit blast with 80-grit shot.
- 4. Remove 0.010 to 0.016 inch from outside diameter by grinding.
- 5. Stress relieve per EPS 202 and PCI 8000.
- 6. Nital etch per EIS **t** 1510.
- 7. Shot peen per EPS 12140 followed by EPS 12176.
- 8. Stress relieve per EPS 202 and PCI 8000.
- 9. Coat with black oxide per AMS-2485.
- * Allison Engineering Processing Specification.
- Allison Process Control Instruction.
- **t** Allison Engineering Inspection Specification.

EXPERIMENTAL INVESTIGATIONS

In this phase α , the program, photostress and strain gage measurements were used to investigate the location and magnitude of the maximum bending stress.

By cementing a sheet of special plastic* to the gear face (actual fatigue test gear) and trimming to the contour of the test tooth, it was possible to obtain indications of stress distribution, stress values along the tooth contour, and maximum stress locations. A large field reflection polariscope $(LF/Z$ meter) and a telemicroscope were used to study in some detail the point of high stress.

To complement the photostress analysis, strain gages were installed in the root of the gear tooth at the theoretical point of maximum stress as shown in Figure 72. The gear was mounted to the fatigue test rig and loaded by means of the bias spring.

The protuberance hobbed gear, part number EX-78776 (with a 20-degree pressure angle and ^a minimum fillet radius), was selected for stress analysis.

The plastic sheet manufacturer supplied the calibration of the optical strain constant of 1080 microinches per inch per fringe or tint-of-passage (sharp line between red and blue).

Special birefringent material, plastic sheet type S, 0. 120 inch thick, Model Number X-10062, Instruments Division of The Budd Company. Phoenixville, Pennsylvania

Specimen Number	Stress (p. s. i.)	Test Cycles* $(X 10^3)$	Surface Finish (microinches)	Failure Origin	Failure Location	
18	130,000	106,584	23tJ27	Terminated		
17	135,000	105,951	25 to 28	Terminated		
$\mathbf{2}$ 6	140,000 140,000	101,234 102,384	30 to 35 25 to 30	Terminated Terminated		
15	140,000	111,435	20 to 25	Terminated		
14 $\mathbf{1}$	150,000 150,000	74 138	25 to 30 32 to 37	Surface Surface	Off center *** Slightly off center t	
$\boldsymbol{4}$ 13	150,000 150,000	50,683 90,852	30 to 35 28 to 32	Subsurface ** Surface	Center: Slightly off	
11	150,000	103,034	8 to 13	Terminated	center	
10 7 $\overline{\mathbf{5}}$ $\overline{3}$	160,000 160,000 160,000 160,000	44 134 3,317 6,061	25 to 28 12 to 20 25 to 30 30 to 35	Surface Surface Surface Surface	Center Off center Center Center	
16	170,000	74	25 to 30	Surface	Slightly off center	
9	170,000	114	20 to 25	Surface	Center	
8 12	170,000 170,000	187 228	10 to 15 28 to 32	Surface Surface	Center Center	
\star Arithmetic average.						

TABLE XIV R. R. MOORE TEST RESULTS

Within effective case. **

t Center is midpoint of specimen.

t Slightly off center is 1/16 to 1/4 inch from midpoint.

Off center is 1/4 to 1/2 inch from midpoint.

The photostress gear was statically loaded in 1000-pound increments. Readings were taken at each 1000-pound step, and photographs were taken at zero and 4000 pounds. This load limit was chosen as the stopping point because the concentration of strain was so confined and was beyond the reading capacity of the LF/Z meter.

The greatest stress concentration, as measured by the LF/Z meter, occurred at the calculated point for the placement of the strain gages. The strain rate was 1080 microinches per inch (32,400 p.s.i.) per 1000 pounds of load by photostress and 1140 microinches per inch (34, 200 p. s. i.) by strain gage. Figure ⁷³ illustrates the stress distribution for the 4000-pound load point. Since monochromatic light was not used, both isoclinic lines (lines of stress direction) and tints-of-passage are seen us the darker lines and cannot be defined without the aid of the color photographs.

Figure 72. Schematic of Instrumentation on Photostress Gear.

To permit comparison of calculated stresses with actual measured stresses, one tooth from each of the eight 4-inch-pitch-diameter gears was instrumented with strain gages. Static strain versus load at the high point of single tooth contact was obtained. Each gear was instrumented with strain gages as shown in Figure 74. The radial location of the gages was at the expected crack point based on crack measurements from the gears (diametral pitch ⁼ 12) that were available at the time.

The gears were tested on the fatigue test rig using the same procedure for installation as used for fatigue and photostress tests. The results of the data are shown in Figures 75 and 76. The gages were located on the tension side except for one on the compression side of one gear.

DYNAMIC TESTS

The effect of speed on bending stress can be categorized as follows.

- Centrifugal stress, ^a steady-state stress at any particular speed caused by internal forces. As noted in Figure 77, this effect consists of tensile stresses in the tooth and hoop stresses in the gear rim.
- Dynamic stress, ^a cyclic stress with ^a constant peak magnitude at any particular speed caused by tooth load, imperfect tooth meshing, load sharing, and other geometrical and manufacturing properties of the gear. It is cyclic since it occurs only when the tooth is under load, e.g., in mesh with a mating gear. This is shown graphically in Figure 78.

Figure 73. Gear Tooth Showing Photostress Pattern at 4000-Pound Load.

Lead Wire Path - Face A Face B 2X	Typical Gear Configuration Gear Q $+$		Strain Gage Mounting Procedure l. oxide. 2. 3. 4. 5.	Vapor blast to remove black Wipe with W. T. Bean neutralizer. No. 910 contact cement. Protect gage with Dow Corning silicon wax fluid F145. Attach 4-foot-long lead wires.		Attach strain gage with Eastman		
EA-06-031DE-120- Two Required per Tooth Face A *Strain gages to be installed on both A and B faces on this gear.								
		Pitch	Pressure					
	Part	Diameter Angle		Serial	Tooth			
	Number					(inches) (degrees) Number Number Radius, R		
	EX-78772	4.0	20	CX9090	4	1.7959		
Lay out scribe marks	EX-78774	4.0	20	CX9066	\mathbf{l}	1.8023		
as shown on both sides. Then draw line between	EX-78776	4.0	20	CX9007	\overline{c}	1.7713		
scribe marks. Locate	EX-78778	4.0	20	CX9056	$\overline{\mathbf{3}}$	1.7781		
strain gage grid on								
scribe line adjacent to	EX-78780*	4.0	25	CX9096	4	1.7804		
edge break on face A.	EX-78782	4.0	25	CX9111	4	1.8058		
	EX-78784	4.0	25	CX9071	$\boldsymbol{4}$	1.7741		
	EX-78786	4.0	25 ₂	CX9012	$\mathbf{1}$	1.7751		

Figure 74. Schematic of Strain Gage Instrumentation for 4-Inch-Pitch-Diameter Gear.

Figure 75. Calibration Curve **for Gear Test Rig-** 20-Degree Pressure Angle.

As shown in Figure 78, doubling the speed not only increases the frequency of the dynamic stress, but also raises the centrifugal stress level and the amplitude of the dynamic stress.

To better understand the effects of speed on gear tooth bending stress, a gear was instrumented and strain data were recorded during actual running conditions. Data were recorded to 26, 500 feet per minute pitch-line velocity. The gear tested was the propeller brake outer member (part number 6829395) in a 501-Dl3 turboprop engine gearbox. The instrumentation consisted of strain gages located on the tooth as shown in Figure 79. One tooth had gages located on the tension side and another tooth, 180 degrees, had gages on the compression side. Two gages were located in the root and two at the point of expected maximum stress in the root fillet.

Figure 76. Calibration Curve **for** Gear Test Rig- 25-Degree Pressure Angle.

By means of electronic test data recording, the centrifugal stress and the dynamic stress were separated. This was possible since centrifugal stress is a steady-state stress and dynamic stress is a cyclic stress. The centrifugal stress was obtained by taking strain gage readings under zero-load conditions at various speeds. The dynamic stress was taken under loaded conditions and was the peak strain reading above the centrifugal base line.

The gear train used is shown schematically in Figure 80. The power input was through the main accessory drive gear which mated with the test gear. The load was applied by means of ^a water brake attached to the alternator drive. To calibrate the strain gages, torque was applied in a static condition. The instrumented tooth was rolled through the highest load point for maximum stress calibration. This setup is shown in Figure 81. The test gear and mating gear meet AGMA class ¹⁰ to ¹² tolerances. The gear geometry and tolerances are shown in Figure 82.

Hoop Stress (Circumferential Tensile)

Figure 77. Gear Tooth Bending Stress Schematic.

Figure 78. Diagram Showing Effect of Speed on Gear Tooth Stresses.

Figure 79. Dynamic Test Gear Strain Gage Instrumentation.

To isolate the stresses due to speed effects in the tooth root, the instrumented gear was first tested at zero load in the reduction gearbox. Using a three-wire strain gage hookup and allowing gearbox oil temperatures to stabilize, strain due to centrifugal loads was recorded. Testing was conducted at essentially zero tangential loads for speeds varying from 10, 000 to 15, 000 r. p. m. Figure 83 shows the centrifugal strain (tension) on the gear tooth.

The gear was then loaded by means of a water brake to obtain stress versus speed data. The strain gage instrumentation was routed through a slip-ring assembly, and the gage signal was recorded by a 16-channel Miller oscilloscope recorder. The gear was tested

Figure 80. Schematic of T56 Propeller Brake Gear Train.

at speeds of 10, 000 to 15, 530 r, p. m. **and** tangential loads of 350 to **950** pounds. Figure 84 shows data from foui strain gages. The data shown represent the average strain range at the speed at which the gear was tested. Of the eight gages installed, only these four survived the testing schedule.

Figure 81. T56 Gearbox Used for Dynamic Gear Test.

0.006 to 0.010 backlash with mating gear on STD centers

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DISCUSSION OF RESULTS

EVALUATION PROCEDURE

The test results were evaluated by the following steps:

- 1. Determine predictive ability of the five calculation methods.
- 2. Compare strain gage and photostress data with calculated stress.
- 3. Determine significance of geometric variables based on most predictive calculation methods.
- 4. Determine basic material strength and design value.
- 5. Compare test data and design value to the literature.
- 6. Analyze centrifugal and dynamic load effects.
- 7. Establish computer program.

PREDICTIVE ABILITY OF CALCULATION METHODS

The predictive ability of the five methods studied for calculating bending stress was evaluated by use of the mean endurance limits fitted through the fatigue test gear data points. Proportionality factors were used to convert the unit load endurance limits for each gear configuration to endurance limit values based on each of the stress calculation methods. These endurance limit values are listed in Table XV and are ranked in descending order. Average, range, and variation in endurance strength for each calculation method are also given. The AGMA method produced the smallest variation which is considered to be one of the best criteria for evaluation of the various calculation methods. Also, the test rig (applied load) ranked all the larger (6-diametralpitch) gears first as would be expected. However, the Heywood and Kelley-Pedersen method also ranked all but one of the large gears first, indicating that these calculation methods may not adequately compensate for changes in diametral pitch.

Further analyses were made by comparing the rank given to each test gear configuration by each calculation method with the test rig load endurance limit ranking. Since a high stress should result in a low life, the calculated stress rankings were inverted. The results of this comparison are given in Table XVI. The AGMA formula predicted the greatest number of correct rank positions (6 out of 16) and also had the best average prediction accuracy (within 1.25 rank positions).

The endurance limit for fatigue test gear configuration number ³ appears to be abnormally low. See Table XV. It was therefore deleted from critical calculations (range and variation) but not from averages. This configuration (part number EX-78774) did have dimensional discrepancies (0. 070-inch root fillet radius instead of 0. 080-inch minimum print requirement). This should have lowered the life to approach that of configuration number 1, which is the same except for 0. 050-inch minimum root fillet radius. The life was actually only two-thirds of that of configuration number 1. The test data had very low fatigue life scatter, which may be indicative of a severe stress concentration. Since the low endurance life was not determined until late in the program, no metallurgical investigations of this gear were accomplished.
Continued analysis of the **fatigue** test results based on individual measured physical **dimensions** rather than part number drawing dimensions could appreciably increase the **confidence** level of **the results.** The test results of one gear have been corrected to ^a **10-percent** lower **stress level** to adjust for a 0. 010-inch oversize root diameter. Thus, **correction of** all data to compensate for individual sizes within the ± 0. 002-inch root **diameter** drawing tolerance would adjust relative calculated stresses by approximately 4 percent. Similar changes could be made for individually measured tooth thicknesses and fillet radii. The protuberant hobbed configurations could be revised, based on measured hob dimensions.

To accomplish the individual analysis described for each fatigue test tooth would require conversion of the present computer program to permit operation on the smaller IBM 1130 rather than on the IBM 7094. The program would also require revision to eliminate unnecessary output and thus would avoid overloading the smaller computer. Also, the input would have to be modified to use the measured dimensions directly. Table XVII lists the critical root diameter, root fillet radius, and over-pin dimensions for each gear.

Each fatigue test gear tooth was examined to determine and record the edge break condition in the failure region. See Table XVII. These edge breaks were not as consistent as desired due to the difficulty of controlling a hand operation. Direct comparison of edge break and fatigue life failed to indicate any general influence of edge break on the test results.

STRAIN GAGE DATA

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Evaluation of the static strain gage measurements confirmed the validity of the AGMA method of calculating bending strength. Table XVIII shows the measured strain gage data in terms of strain rate for each configuration tested. The remaining columns show a comparison of the various methods of calculating bending strength in terms of strain rate. The percent deviation shows the magnitude of difference between the measured and calculated strain for each configuration. The AGMA method produces a minimum difference for each configuration. The last column shows the stress concentration factor calculated from the difference between the Lewis calculated *and* the measured data.

To further indicate the degree of correlation, Figure 85 shows stress versus load for the measured data and the AGMA calculation. The percent deviation of the calculated stress from the measured stress is shown in Figure 86. The present AGMA method gave the smallest deviation from **the** measured stress.

Since none of the formulas considered fillet configuration, the data were split into two groups—full form ground and protuberance hobbed. Although Figure 86 shows that the averages for the two groups differed, statistical "t" tests indicated that these differences could have occurred by chance alone. (See Appendix III for description of "t" tests.) The comparisons were based on four data points in each set. Real differences would have to be very large to be detectable in such small samples. The results were therefore not inconsistent with the analysis of endurance limits which showed that, based on about 200 points, the fillet configuration does produce different endurance limits based on AGMA stresses. Even with this small sample, the results, while not conclusive, have the same sense as the more comprehensive analysis; i. e. , protuberance hobbed fillet should produce a higher endurance limit when stresses are calculated with the AGMA formula.

TABLE XV RANKED ENDURANCE LIMITS FOR VARIOUS STRESS CALCULATION METHODS

Note: Configuration number ³ was delet ed from range and variation calculation when it was lowest value.

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Figure 86. Comparison of Methods for Calculating Gear Stress.

TABLE XVI

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 $\bar{\gamma}$.

 ${\small\texttt{TABLE XVI}}\\ \texttt{FATIGUE TEST GERA R MEASURED DIMENSIONS}$

TABLE XVII (CONT)

 $\begin{array}{c} 1 \\ 1 \\ 1 \end{array}$ $\frac{1}{2}$

TABLE XVIII MEASURED STRESS OF FATIGUE TEST GEARS COMPARED WITH CALCULATED STRESS

^{*}Strain Rate -- and a hea/inch/1000 pounds

an di Kabupatèn Bandung Kabupatèn Kalèndher Kabupatèn Kabupatèn Kabupatèn Kabupatèn Kabupatèn Kabupatèn Kabupatèn

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In summary, the bar chart in Figure 87 shows the average degree of correlation for the various methods of calculation versus the measured data. It is apparent that the AGMA method offers the greatest degree of correlation.

PHOTOSTRESS DATA

As described in the section titled Results, the photostress investigations showed the stress location and stress distribution to be in agreement with the theoretical location.

EFFECT OF GEOMETRIC VARIABLES OF GEAR FATIGUE TEST

The following studies of the data evatyate the four variables of the gear fatigue test. Despite the high precision achieved in the manufacture of test gears, the scatter in fatigue life was high. Many run-outs (termination of test before failure) occurred, although the planned stress levels were altered in an attempt to fail teeth with ¹⁰⁷ cycles. It was decided, therefore, to base the analysis on the endurance limit produced by each of the 16 configurations of gear teeth by developing a mathematical model for the S/N curve. The derivation of the analytical model is included in Appendix V. This method was used to determine the characteristic and fit of the S/N curve for all the fatigue test points, stress curves, and R. R. Moore curves. S/N curves were fitted to the gear tooth fatigue data with respect to basic applied load. AGMA calculated stress, and Kelley-Pedersen calculated stress. The basic applied load (lest rig load) was used as a positive baseline since it is unaffected by any calculations. The AGMA calculated stress was of prime interest, since it was determined to be the best predictive calculation method. The Kelley-Pedersen method was used as a second stress method to provide direct comparison for the AGMA method. The endurance limits obtained from the S/N curves were used to evaluate each of the four geometric variables and their interactions—i. e., diametral pitch, pressure angle, fillet size, and fillet configuration.

Figure 87. Comparison of Calculated and Measured Stresses.

^A summary of significant test results is given in the following paragraphs. The preselected significance level was a > 0. 05, which corresponds to a statistical "t" value of 2. 0. This level indicates that the result would occur 95 out of 100 times. A discussion of the statistical test of significance is included in Appendix III.

Diametral Pitch

As would be expected, due to the different face width and pitch, a significant effect was found for diametral pitch (6 and 12) based on applied load. It would be expected that stress calculations would adequately consider these geometric variables. It was found that the AGMA stress calculation did adequately predict a stress level. The Kelley-Pedersen method reduced the significance value but was still very significant. Table XK summarizes these data (the load values have been corrected for diametr?¹ ^itch and load for comparison).

Pressure Angle

A significant effect was found due to the change in 20- and 25-degree pressure angle gears based on applied load. Also, it would be expected that the stress calculation should adequately predict this geometric effect. The study indicated that the AGMA and Kelley-Pedersen calculation methods adequately predicted the stress level. Table XX summarizes these data (the load values have been corrected for pressure angle for comparison),

TABLE XX EFFECT OF PRESSURE ANGLE ON GEAR FATIGUE DATA

Pressure Angle (degrees)	'.oad (pounds)	Corrected Load (pounds)*	AGMA Stress (p. s. i.)	Kelley-Pedersen Stress (p. s. i.)
20 25	3802 4328	5027 4328	176.500 183,600	104, 480 105, 700
	20-degree average Y - 0, 4302 25-degree average Y . 0, 5688	*Correction for pressure angle was made by averaging Y values for 20- and 25-degree pressure angle gears. 3802 x	0.5688	5027 pounds

Fillet Size

For the practical range of fillet sizes tested, no significant difference was found on the basis of applied load or AGMA calculations. A significant difference was found, however, on the basis of the Kelley-Pedersen calculated stress. These data are summarized as follows:

Fillet Configuration

For the fillet configurations tested—full form and protuberance hobbed—no significant difference was found on the basis of applied load or the Kelley-Pedersen method. ^A significant difference was found, however, on the basis of calculated AGMA stress. These data are summarized as follows:

The average endurance limit for each variable and the corresponding statistical "t" value for the tests of significance are presented in Table XXI. Several interactions were found, as indicated in the table.

It is apparent that the AGMA formula adequately predicts gear tooth bending stress with but two exceptions: fillet configuration and the interaction of pressure angle, fillet radius, and fillet configuration. No exact reason for these differences can be shown. The difference may be due to any of the changes previously listed between the two fillet configurations such as residual stress, case depth, surface finish, etc. In view of the interaction obtained and its relative value, the difference may be due to the accumulation of errors in extrapolation of the stress concentration factor.

The significant differences between levels for each factor are apparent. Changing the value assigned to any significant geometric factor produces a change in the endurance limit. This limit is larger than can be explained by the inherent variability associated with fatigue testing. For example, diametral pitch was significant in terms of basic load, as was expected. The reduction in endurance limit in going from a diametral pitch of ⁶ to ¹² was 4879 pounds. The fillet configuration was not significant in terms of basic load; the difference between endurance limits for the full form and the protuberance configuration was only 326 pounds.

The interpretation of significant interactions is more difficult. In general, it can be stated that the change in endurance limits caused by changing one factor is dependent on the value assigned to the interacting factor. An example is provided by the significant AB interaction associated with applied load. See Table XXI. At the 20-degree pressure angle, the endurance limit is reduced from 5780 to 1610 pounds in going from a diametral pitch value of ⁶ to 12; at the 25-degree pressure angle, the endurance limit

 ${\bf TABLE}$ TABLE XXI
 ${\bf ATENACTIONS}$

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is reduced from 7650 to 1930 pounds for the same change in diametral pitch. This example is shown graphically in Figure 88, The interaction is indicated by the convergence of the lines; i. e. , the difference in endurance limits between a 20- and a 25 degree pressure angle is not the same at the two values of diametral pitch. The information used is presented in Tables XXII, XXIII, and XXIV for the basic applied load and the AGMA and Kelley-Pedersen calculated stress.

Figure 88. Significant Two-Factor Interactions.

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TABLE XXII
ENDURANCE LIMITS BASED ON BASIC GEAR TOOTH LOADING

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TABLE XXIII
ENDURANCE LIMITS BASED ON AGMA CALCULATED STRESS

The endurance limit for test gear configuration number 1 (EX-78774) was increased from a computed 96,600-p.s.i. AGMA stress value to 159,200 p.s.i. It was necessary to neutralize this low value to prevent bias to the designed experiment. The new value was determined by proportioning the configuration number ¹ endurance limit based on fillet size. Fillet size is the only difference between configurations 1 and 3. The basic applied load and Kelley-Pedersen endurance limit for configuration ³ were similarly proportioned.

BASIC MATERIAL STRENGTH

An ideal bending stress calculation would permit direct correlation of tooth strength with the basic material strength. R. R. Moore rotating beam fatigue test data were compared with fatigue test gear data to determine the degree of correlation.

The R. R. Moore S/N curve shown in Figure 89 presents the basic bending strength of the carburized AMS-6265 material of the test gears. R. R. Moore rotating beam specimens are related to gears as described in the iollowing paragraphs.

Type of Loading

The R. R. Moore test bar rotates while supporting a bending load. This results in complete reversal of the bending load on the test bar once each revolution. The relationship of fatigue data for the two types of loading is indicated in the modified Goodman diagram in Figure 90. Metallurgical investigations showed that the fatigue failures for the R. R. Moore samples and the test gears started on the carburized case surface. The modified Goodman diagram, therefore, is based on the case material properties. The ultimate strength level for the case was calculated by increasing the measured ultimate strength of the core material by the ratio of the case hardness and the core hardness at the surface:

180, 000
$$
\times \frac{58}{38}
$$
 = 274, 000 p. s. i.

Points A and B in Figure 89 are located on the S/N curve to establish 10^8 and 10^5 cycle lines. These points are then plotted on the modified Goodman diagram. Figure 90, at the zero mean stress ordinate. Since the gear tooth load was in one direction only, the one-direction line was drawn at a slope of 2. A slope of ² is used since the mean stress is one-half of the maximum stress for one-direction loading as shown in the following sketch. The intersection of the one-direction line and the cycle lines,

points C *and* D, establish points for an R. R. Moore S/N data curve modified for the fatigue test gear mode of loading. The modified S/N curve is shown in Figure 89. This modification is not required for use with idler gear applications where the gear tooth is subjected to complete reversal of loading.

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Figure 90. Modified Goodman Diagram.

Size Effect

R. R. Moore standard specimens are 0. 250-inch-diameter bars. Generally, for bending, the endurance strength tends to decrease as size increases. To relate the size effect factor to carburized gears, it is recommended that the factor be "one." The literature indicates that the decrease of endurance strength for size is approximately ² percent for carburized material; however, this effect has not been completely tested.

Surface Effect

Usually R. R. Moore specimens are polished. For this analysis, however, the R. R. Moore specimens were ground to the same surface finish as the gear roots; thus, the surface effect factor is "one." R. R. Moore data from polished samples must be reduced 10 percent.

Stress Concentration

R. R. Moore specimens are considered to have no stress concentration. Most current gear tooth bending stress calculation methods incorporate a stress concentration term based on tooth geometry. Therefore, no further consideration of stress concentration is required.

Reliability

Both R. R. Moore and **fatigue test** data have been analyzed based on mean endurance **strength (50 percent failures) for** comparison. Depending on the application, any **confidence level** may be selected for the gear design.

Surface Treatment

The R. R. Moore samples in this program were carburized, shot peened, and black oxided to the same specifications as the gears. Thus, the surface treatment factor is $"$ cne. $"$

All of the aforementioned factors except stress concentration, size effect, and mode of loading are considered as one for this analysis. Thus, the modified R. R. Moore data as plotted on the S/N curve of Figure 89 are comparable (within ² percent) to a calculated stress that incorporates a stress concentration factor.

Figures 91, 92, 93, and 94 show the fatigue test data with respect to size and pressure angle plotted against AGMA stress. Superimposed on these curves is the endurance strength line from the modified R. R. Moore data developed previously. It is considered significant that close correlation is indicated for the AGMA method and the basic R. R. Moore data. A further comparison is made in Figures 95 and 96 by superimposing the R. R. Moore S/N curve on the protuberance hobbed and the full form ground data. A final comparison is made by averaging the fatigue test gear data and comparing with the R. R. Moore S/N curve. Figure 97 shows this comparison. It is apparent that extremely close correlation was demonstrated between the overall AGMA stress calculation for the gear fatigue tests and the basic strength as determined by the R. R. Moore data.

The endurance strengths previously listed in Tables XXII, XXIII, and XXIV are plotted in Figure 98 and are compared to the basic R. R. Moore data. It is apparent that the Lewis, Heywood, and Kelley-Pedersen methods do not approach the basic material strength. The Dolan-Broghamer and AGMA methods, which are very similar, do bracket the basic material strength line.

DEVELOPMENT OF DESIGN VALUE

The S/N curve of Figure 97 was obtained from an average of all the fatigue test data. It represents a mean or 50-percent failure estimate of the test data. For design purposes, a much lower failure probability would normally be required. An endurance limit consistent with such a higher reliability was obtained as follows. If some of the differences among the derived endurance limits are attributed to geometric factors and combined into one group, a distributed quantity results. The group of endurance limits has an average value and some scatter or dispersion about this average. A meaningful statement of the form of this distribution is not possible because there are only 16 points. However, a plot of these points on normal probability paper (Figure 99), using the mean rank procedure, indicates that an assumption of normalcy is reasonable. Assuming normalcy, a lower tolerance value can be calculated for the endurance limit. The average, \bar{X} , and standard deviations of the distribution were calculated after deleting the endurance limit derived from configuration 3. The K factor for a one-sided tolerance limit was obtained from tables which can be found in standard statistical texts. This K factor for a proportion $P = 0.99$ and a probability of 0.80 is 3.212. The 1-percent endurance limit is then \bar{X} - K_a or 182, 000 - 3. 212 (24, 900) = 102, 000 p. s. i. The

Figure 92. AGMA Stress Fatigue Test Data (Diametral Pitch = 12; Pitch Diameter = 2 Inches; Pressure Angle = 25 Degrees).

Figure 95. S/N Diagram for Protuberant Fillet.

Figure 96. S/N Diagram for Full Form Ground Fillet.

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Figure 97. Average Fatigue Endurance Strengths Compared With R. R. Moore Data.

probability statement then is: "There is 95 percent probability (confidence) that at least 99 percent of the endurance limits of gears will be greater than $102,000$ p. s. i. ". Thus, a fatigue reliability factor of approximately 182, 000/102, 000 = 1.78 is indicated.

The S/N curve representing the overall average and a tolerance representing 1-percent failure are shown in Figure 100. Using the 1-percent line as a design value, it is estimated that ¹ percent of the gear teeth will experience failure in bending. This statement is only an approximation, being restricted by the range of variables investigated, the significant effect of some of the geometric factors, and the limited knowledge of relating failure analysis of a single tooth to the probability of failure of one or more teeth on a gear.

LITERATURE COMPARISON

A comparison of the data with the literature indicates good correlation. Figures 101 through 104 show a comparison of the fatigue test points with the data published in reference 54. The data in the paper have been reduced to AGMA stress for comparison with the fatigue test data. In general the scatter is similar, with some fatigue points showing early failures.

Additional comparison was made with AGMA Proposed Standard 411. 02, which specifies allowable endurance life values with load and stress distribution factors. This comparison is shown in Figure 105. Table XXV summarizes these data for AGMA, R. R. Moore, and the fatigue test gears. There is close correlation of the gear test data

Figure 98. Methods of Calculating Stress for Endurance Strength Based on Fatigue Test Gears Compared With R. R. Moore Endurance Strength.

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Figure 99. Distribution of Endurance Limits.

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endurance strengths for 10^7 cycle life with the basic R. R. Moore data. The selection of the load and stress distribution factors for the fatigue test gears was based on the dynamic tests (Figure 109) for a gear at 16, 000 feet/minute pitch-line velocity. It is obvious that selection of the various load and stress distribution factors may change the calculated stress appreciably.

EVALUATION OF DYNAMIC EFFECTS

Centrifugal Stress

Centrifugal stress consists of two major parts-hoop stress and centrifugal force stress. The hoop stress is a circumferential tensile stress at the root diameter caused by the tendency of the rim to expand from centrifugal force. The centrifugal force stress is a radial tensile stress caused by the centrifugal force exerted by the gear tooth.

The measured centrifugal stress was found to be much higher than the calculated stress caused by centrifugal forces on the gear teeth. However, the measured stress was found to coincide closely with the calculated hoop stress. This was true for both the root and the active profile positions. This suggested that the hoop stress spread onto the active profile of the gear tooth. Figure 106 shows a comparison of calculated centrifugal force stress, calculated hoop stress, and measured centrifugal stress. The measured stress was found to be 75 percent of the calculated hoop stress.

Figure 102. Comparison of Test Data With ASME Paper 63-WA-199 (Reference 54).

Figure 104. Comparison of Test Data With ASME Paper 63-WA-199 (Reference 54).

Figure 105. Comparison of Test Data With AGMA Standard 411.02 Design Limits.

Figure **106.** Comparison of Calculated and Measured Gear Stresses.

No detailed study was made of the possible effect of various gear tooth geometries and/or rim proportions on centrifugal stress at the weakest section. The similarity of the hoop stress and centrifugal force formula, both of which vary with the square of the speed, and the similarity of normal gear tooth geometry (unit diametral pitch rule) suggest that the observed proportional values should remain essentially constant. Design use of the calculated hoop stress should therefore be conservative.

Hoop stress, S_h , can be calculated by the following equation:

$$
S_h = P \frac{v^2}{g}
$$

where

- $V =$ velocity at rim, inches/second
- P ⁼ material density, pounds/cubic inch
- g ⁼ gravitational acceleration constant, 386 inches/second squared

Since the stress was desired at the root diameter, the equation may be expressed as:

$$
S_h = \frac{N}{60g} \text{ P D}_r = 0.000136 \text{ PND}_r
$$

where

• t

 $N =$ rotational speed, r.p.m.

$$
D_r
$$
 = root diameter, inches

P = material density, pounds/cubic inch

Since the centrifugal stress is at a constant level (at constant speed), use of a modified Goodman diagram was required to permit combining with the alternating bending stress from the normal tooth load. See Figure 107, The S/N curve developed from the fatigue test program (Figure 97) was used at the zero centrifugal stress ordinate to construct the modified Goodman diagram. The Goodman diagram may be used to determine the endurance strength required for the bending stress calculation given a desired life, speed, and gear size.

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Figure 107. Modified Goodman **Diagram** Combining Centrifugal and Bending Stresses.

For example, the dynamic test gear when operating at 16, 000 r. p. m. has a calculated hoop stress of 20,000 p.s.i. For 10^7 cycle life, a bending stress of 175,000 p.s.i. would be permitted based on the **modified** Goodman diagram. Based on direct addition of the centrifugal and bending stress (an improper procedure), the S/N curve would permit only 152, 000-p. s. i. bending stress. Also, this gear, if designed for 10^7 *y le* life without considering centrifugal stress, would actually have a mean life expectan y of slightly less than 10^5 cycles or only 1 percent of that anticipated. To calculate a more comprehensive gear tooth bending stress under high-speed operating conditions, the hoop stress must be combined with bending stress by use of the modified Goodman diagram.

Dynamic Stress

Figure ¹⁰⁸ is a plot of the peak dynamic stress versus r. p. m. The strain readings were converted to stress and **plotted against** gear r.p.m. for three load conditions—380,

570, and 766 pounds (1000, 1400, and 2000 pounds/inch of face width). The curves represent the best fit square curve above the static base line; thus, the amount of increase above the static stress level is equal to the square of the ratio of the speed. The static stress level is the measured stress at zero r, p, m , for pure tangential load. It was felt that a square curve would be the most desirable, since the dynamic effect could be related to kinetic energy which involves velocity squared. Again, the measured dynamic stress does not include ahy constant centrifugal stress.

Figure ¹⁰⁹ shows ^a dynamic stress correction factor derived from the curves in Figure 108,

Figure 110 is a comparison of the dynamic factor as previously described with the one given in AGMA Standards 220. 02 (Appendix VI). Curves 1, 2. and ³ represent various grades of gear quality with ¹ being the highest quality gear. The propeller brake gear used in testing would be defined as a grade 1 gear. The two curves agree within 8 percent at 8000 feet/minute. Also, the AGMA data do not exceed 8000 feet/minute.

Although the dynamic data presented are very limited, they do indicate trends for high speed, lightweight gearing. It is recommended, therefore, that the curve of Figure 100 be used as a design factor for applications above 8000 feet/minute. Below this speed, a factor of one should be satisfactory for close-tolerance aircraft applications.

Figure 108. Graph Showing Peak Dynamic Stresses During Testing.

Figure 109. Dynamic Stress Factor as a Function of Pitch Line Velocity.

Figure 110. Comparison of Dynamic Stress Factors.

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ESTABLISHMENT OF COMPUTER PROGRAM

Analysis of the fatigue test data indicates fiat the AGMA formula is the most accurate for predicting ranking, produces the least variation in calculated endurance limits, best matches experimentally measured stresses, and accommodates the geometric variables with the least difference of significant values. The AGMA formula was selected, therefore, for use in the computer program. The AGMA formula also is a well known method-it is required by some Government specifications (reference 47).

The Lewis gear tooth geometry form factor values (Y), as calculated by the computer, should be more accurate than values normally obtained by graphical layouts. The point of tangency between the inscribed parabola and the generated trochoidal root fillet as well as the trochoidal root fillet contour can be established with precision.

^A dynamic factor is an input item of the computer program. The dynamic factor for a given application may be obtained from existing AGMA curves, the curve presented in Figure 109, literature sources, or from direct "in-house" measurements.

Hoop stress is calculated in the program and combined with the AGMA calculated bending stress based on the modified Goodman diagram. A mathematical expression for the combined stress is:

$$
S_c = US - \frac{US [US - (S_h + S_t)]}{US - S_h}
$$

where

^Sc ⁼ combined stress, p. s. i.

S^ ⁼ hoop stress, p. s. i. (reference page 130)

St ⁼ tensile stress (AGMA), p. s. i, (reference page 10)

US ⁼ ultimate strength of the material, p. s. i.

Life cycles are then determined from the combined stress and the S/N curve based on R. R. Moore rotating beam tests of the gear material. The life may be modified further by the AGMA temperature factor and reliability factor (factor of safety) as indicated by the expression:

$$
L = S_c K_T K_R
$$

where

L ⁼ life in cycles

^Sc ⁼ combined stress, p. s. i.

KT ⁼ AGMA temperature factor (reference page 11)

KR ⁼ AGMA factor of safety (reference page 11)

The term « indicates the S/N curve stress-to-life cycle relationship.

Both AGMA bending stress and the combined bending and hoop stresses are printed out. Life is printed out if it is in the finite life area of the modified Goodman diagram; otherwise, an infinite life or an excessive stress note is printed.

Considerable effort was expended in graphical analysis of the Lewis gear tooth form factor Y and its relationship to the Dolan-Broghamer stress concentration factor Kf. It is expected that strength **and stress** concentration factors should be geometrically **related.** Gear sets with **the** following range of parameters were computed and plotted:

- \bullet Pressure angle -14 , 5, 20, and 25 degrees
- Nv.mber of teeth in pinion—12 through ⁵²
- \bullet Gear ratio-1.0 through 10.0
- Hob tip radius—100, 75, 50, and ²⁵ percent of maximum possible
- \bullet Dedendum factor 1.157, 1.2, 1.3, and 1.4
- Tooth thickness at pitch diameter—100, 90, and ¹¹⁰ percent of half of the circular pitch

The parametric plcts were not smooth, overlapping curves as expected. The original Dolan-Broghamer data (from reference 16) were therefore analyzed. Computer-determined dimensions (h, t, and θ_{L}) for the given gear teeth do not coincide with the dimensions for the plastic models as tabulated in reference 16. The computer values plot as smooth curves while the original data do not; this indicates that the error is most likely that which is inherent with the drafting layout procedure. Computed Kf values based on corrected geometry and observed stresses produce data which vary by \pm 11 percent from that computed by the formula as indicated in Table XXVI.

Work to generate a formula to duplicate the corrected stress concentration factors obtained has not been completed.

The Dolan-Broghamer photoelastic data were obtained from models having pressure angles of 14. ⁵ and 20 degrees, diametral pitch of 2, and a dedendum factor of 1, 157, Graphical analyses should be used with the new stress concentration formula to determine the validity of the extrapolation if K_f values throughout the range of gear tooth geometric variables, as previously investigated. Similar analysis of additional photoelastic data (such as from Kelley-Pedersen work) would be valuable for correlation,

A new stress concentration factor, developed as described, would considerably enhance the correlation of the test data and would be a valuable modification to the AGMA formula and the computer program.

Model				[Number K_f (Dolan-Broghamer) K_f (AGMA) K_f (Calculated) K_f (Calculated) / K_f (AGMA)]
$6 - 1$	1.53	1.511591	1.500636	0. 99272
$6 - 2$	1.65	1.647910	1.733851	1.05218
$6 - 3$	1.82	1.832482	1.876810	1.02417
$6 - 4$	2.18	2.097727	2.117530	1.00943
$6 - 5$	1.56	1.558408	1.638576	1,05146
$6 - 6$	1.68	1,694056	1.817664	1.07295
$6 - 7$	1.86	1.877288	1,959995	1.04405
$6 - 8$	2.10	2.141456	2.287704	1.06826
$6 - 9$	1.68	1.644061	1.826440	1.11088
$6 - 10$	1.76	1.783399	1.936391	1.08579
$6 - 11$	1.94	1.970920	2.057944	1.04414
$6 - 12$	2.21	2.241207	2.314211	1.03257

TABLE XXVI COMPARISON OF STRESS CONCENTRATION FACTORS

Model				Number K_f (Dolan-Broghamer) K_f (AGMA) K_f (Calculated) K_f (Calculated) /K _f (AGMA)
$7 - 1$	1.57	1.588621	1.589230	1.00037
$7 - 2$	1.68	1,735900	1.746881	1.00633
$7 - 3$	1.93	1.936614	1.882616	0.97211
$7 - 4$	2.37	2.228237	2.168161	0.97307
$7 - 5$	1.69	1.664860	1,788942	1.07747
$7 - 6$	1.86	1,810860	1.843543	1.01800
$7 - 7$	2.04	2.008900	1.986026	0.98860
$7 - 8$	2,30	2.297209	2.124755	0.92495
$7 - 9$	1,74	1.750553	1.938912	1.10756
$7 - 10$	1.90	1.899773	2.085223	1.09758
$7 - 11$	2.10	2.101321	2.215057	1.05420
$7 - 12$	2.40	2.394263	2.368038	0.98905
$8 - 1$	1.62	1.629011	1.687625	1.03597
$8 - 2$	1.74	1.782054	1,782343	1,00011
$8 - 3$	1.94	1.991574	1.913581	0.96083
$8 - 4$	2.25	2.298240	2.063709	0.89796
$8 - 5$	1.74	1.724950	1.883809	1.09205
$3 - 6$	1.86	1.876333	1,956013	1,04247
$8 - 7$	2.06	2.082457	2.165639	1.03990
$8 - 8$	2.31	2.384652	2.271327	0.95244

TABLE XXVI (CONT)

Kf (AGMA) computed by formula from corrected geometry.

Kf (Calculated) computed from corrected geometry and observed **stress.** [|]

CONCLUSIONS

The following conclusions are made from this study.

The investigation of four geometric variables indicated that the endurance strength was significantly affected by changes in pitch diameter and pressure angle. These effects were in some instances greater than those predicted by bending stress calculations. The effects of fillet size and fillet configuration—full form or protuberance—were not significant with respect to the endurance strength of the configurations tested. Stress calculations did not accurately consider the fillet configuration.

- ^t A basic material strength curve for carburized AMS-6265 was established by R. R. Moore specimens. This strength curve correlated very closely with the AGMA method of calculating stress.
- By averaging all fatigue lest data points, ^a design S/N curve was established. For design purposes, a 1-percent failure endurance strength of 102, 000 p. s. i. was also established.
- Of the five strength formulas investigated, the AGMA bending strength formula provides the most accurate method for assessment of spur gear tooth bending strength,
- The limited dynamic testing conducted indicated that ^a dynamic factor for lightweight aircraft gears should be considered for applications with a pitch line velocity over 8000 feet/minute.
- ^A centrifugal speed factor is necessary for high pitch line velocity applications.
- ^A modification is required to the Dolai; -Broghamer stress concentration factor used in the AGMA formula to consider tooth geometry more accurately.
- The AGMA formula modified to incorporate ^a centrifugal speed, ^a high speed dynamic factor, and to use R. R. Moore material strength data will produce an accurate estimate of gear tooth bending stress and life_{ϵ_{ℓ}} The dynamic fluctuat-

 $W_t K_o / P_d K_s K_m$ ing stress alculated by the AGMA formula, $S_t = \frac{W_t - W_O}{K_W} \frac{F_O}{F} = \frac{K_S - K_m}{J}$, is combined

with the steady centrifugal hoop stress formula, Sn = $\rho = \frac{V^2}{Z}$, to produce a g

combined stress, S_c , as follows:

$$
S_c = US - \frac{US [US - (S_h + S_t)]}{US - S_h}
$$

The terms are defined on page 135. Life cycles may then be determined from an S/N curve based on R. R. Moore rotating beam tests of the gear material. The life may be modified further by the AGMA temperature and reliability factors as follows:

$$
L \propto S_c K_T K_R
$$

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APPENDIX I

FATIGUE TEST GEAR DRAWINGS

This appendix consists of the fatigue test gear drawings for the ¹⁶ configurations tested. These drawings are shown in Figures 111 through 126. The spur gear main accessory drive and propeller brake outer member are shown in Figures ¹²⁷ *and* 128, respectively.

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Figure 111. Fatigue Test Gear Configuration 1-EX-78772.

Figure 112. Fatigue Test Gear Configuration 2-EX-78773.

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OTH SPACE SHALL BE FULLY GROUND INCLUDING ROOT

A AND ADJACENT FILLETS AFTER HEAT TREAT, NO

SCONTINUITY SHALL OCCUR AT THE BLEND OF THE FILLET

DIUS WITH THE ROOT DIA AND INVOLUTE SURFACES. SHOT

EN THE ENTIRE TOOTH SPACE

MATERIAL - AMS 6265 STEEL FORGED BARS

348 IZ PLACES ৯ **SIDE B** SDE $A \circledast$

LREMOVE IZ TEETH SPACED AS SHOWN AFTER GEAR TEETH ARE TO FINISHED SIZE ANUALL GENR TOOTH INSPECTION (82) REQUIREMENTS ARE COMPLETED

ELECTRO CHEMICAL ETCH POSITION NUMBERS ON TEETH AS SHOWN. RECORD INVOLUTE PROFILE AND LEAD CHECKS FOR SIDE A OF TEETH I.23, AND 4; AND FOR SIDE B OF TEETH N, X2, X3 AND X4. RECORD POSITION MUMBERS ON TOOTH TO TOOTH SPACING ERROR CHECKS

DIA A SHALL BE CONCENTRIC WITH PD WITHIN .002 TIR

BREAK SHARP EDGES .010 UOS

MACHINE ALL OVER.

SURFACE CHARACTERISTICS NOT CONTROLLED BY A √
SYMBOL SHALL BE COMMEN∷. RATE WITH GOOD MANU -**FACTURING PRACTICES WHICH PRODUCE ACCEPTABLE OUALITY LEVELS.**

HEAT TREAT PER EPS 202

CASE HARDEN GEAR TEETH OUTSIDE 1.570 DIA
(OPTIONAL TO CASE HARDEN ALL OVER) EFFECTIVE CASE
DEPTHS AS FOLLOWS: 23 23 POLLOMS.
020-030 BEFORE FINISHING ROCKWELL HARDNESS - CASE CSB MIN

INSPECT PER EIS 985 (MAGNETIC)

NITAL ETCH PER EIS 1510 THEN BLACK OXIDE PER AMS 2485

ALL DIMENSIONS TO BE MET AFTER PROCESSING FORGING SHALL CONFORM TO EDI 138 AND EIS 502

 $2000 - 2000$

ANCE WITH EDI 9

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 $2 - EX - 78773$.

Figure 113. Fatigue Test Gear Configuration 3-EX-78774.

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Figure 114. Fatigue Test Gear Configuration 4-EX-78775.

n 4-EX-78775.

Figure 115. Fatigue Test Gear Configuration 5-EX-78776.

tion $5 - EX - 78776$.

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Figure 116. Fatigue Test Gear Configuration 6-EX-78777.

P.005 MAX 16/ JURFACE E **XANDED** F **V** BEFORE APO **SHOT PEENING JEFOR!** 0360 2 MIN. **ENIN-** \sqrt{G} DO NOT FINISH
SHOT PEENED ROOT
|NSIDE THIS DIA XTEND <mark>IISH</mark>
ED RC… S D/L ENLARGED VIEW OF GEAR PROFILE **SCALE NONE** TCH ALLISON PART NO.
ETTER, SER' AND SERIAL
478-741 OR 742 **958 TYPICAL**
548 EPLACES ₽ $31DEB$ BREAK SHARP EDGES, 010 UOS REAK DIA À SHALL BE CONCENTRIC WITH PD WITHIN .002 TIR -1 ∧A s \circledast MACHINE ALL OVER. PEEN GEAR TEETH PER EPS 12140 FOLLOWED BY EPS 12176
REMAINING SURFACES MAY BE PEENED PER EPS 12140
UNLESS SPECIFICALLY CONTROLLED BY A V SYMBOL ACHIM ACOM
KLOM
MAIN
LESS < *= 41* R IN THE FOLLOWING SEQUENCE SURFACE CHARACTERISTICS NOT CONTROLLED BY A V
STANDOL SHALL BE COMMENSURATE WITH GOOD MANU-FACE Chain of HO GEAR TEETH, CARBURIZE AND HARDEN FACTURING PRACTICES WHICH PRODUCE ACCEPTABLE **BOL SHA OUNLITY LEVELS. RAING FROM A RANG AND AN INCLUDE ALL SURFACES BETWEEN**
UTT LENGE THE ROOT DIA
AT THE MISHINE AREA F PER EPS 13066
SELL ³⁰²⁻⁰⁰⁴ PER SURFACE HEAT TREAT PER EPS 202 CASE HARDEN GEAR TEETH OUTSIDE 1.570 DIA
(OPTIONAL TO CASE HARDEN ALL OVER) EFFECTIVE CASE
DEPTHS AS FOLLOWS: SE H **PTION :.. ' IRFACES AS REQUIRED** DEP 1745 - DEFORE FINISHING
2015-030 AFTER FINISHING
200 ROCKWELL HARDNESS - CASE CSB MIN **PTHS** DRUMBER SURFACE E TO FINISH SIZE α CKWE INSPECT PER EIS 985 (MAGNETIC) MATERIAL - AMS 6265
STEEL FORGED BARS **SPEC** BLACK OXIDE PER AMS 2485 ACK (ALL DIMENSIONS TO BE MET AFTER PROCESSING $DIMJ.$ FORGINGS SHALL CONFORM TO EDI 198 AND EIS SOE **P6/N6**

777.

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Figure 117. Fatigue Test Gear Configuration 7-EX-78778.

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Figure 118. Fatigue Test Gear Configuration 8-EX-78779.

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 $9 - EX - 78780.$

Figure 120. Fatigue Test Gear Configuration 10-EX-78781.

tion 10-EX-78781.

Figure 121. Fatigue Test Gear Configuration 11-EX-78782.

 $1 - EX - 78782.$

tion 12-EX-78783.

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ration 13-EX-78784.

Figure 124. Fatigue Test Gear Configuration 14--EX-78785.

ENLARGED VIEW OF GEAR PROFILE **SCAI.E NONE**

ECTRO CHEMICAL ETCH ALLISON PART NO. AND LAST
IANGE LETTER, "SER"AND SERIAL NO. HERE PER AS 478-7AI OR 7A'E

PROCESS GEAR IN THE FOLLOWING SEQUENCE

I. AFTER CUTTING GEAR TEETH CARBURIZE AND HARDEN

2. AREA F SHALL, INCLUDE ALL SURFACES BETWEEN

THE APD AND THE ROOT DIA
22 SOLUTION MACHINE AREA F PER EP

4 GRIND INVOLUTE SURFACE E TO FINISH SIZE

3 SHOT PEEN SURFACES AS REQUIRED

DIA À SHALL BE CONCENTRIC WITH PD WITHIN .002 TIR

BREAK SHARP EDGES .010 UOS

MACHINE ALL OVER. PEEN GEAR TEETH PER EPS / 2/40 FOLLOWED BY EPS 12176
REMAINING SURFACES MAY BE PEENED PER EPS 1214C
UNLESS SPECIFICALLY CONTROLLED BY A V SYMBOL

SURFACE CHARACTERISTICS NOT CONTROLLED BY A V SYMBOL SWILL BE CO'RIENSURATE WITH 6000 MANU -FACTURING PRACTICES WHICH PRODUCE ACCEPTABLE **QUALITY LEVELS.**

HEAT TREAT PER EPS 202

CASE HARDEN GEAR TEETH OUTSIDE 1.570 DIA
(OPTIONAL TO CASE HARDEN ALL OVER) EFFECTIVE CASE
DEPTHS AS FOLLOWS: DEP' 130-030 BEFORE FINISHING
05-030 BEFORE FINISHING
DOCKWELL HARDNESS - CASE CSO MIN

INSPECT PER EIS 985 (MAGNETIC)

BLACK OXIDE PER AMS 2485

ALL DIMENSIONS TO BE MET AFTER PROCESSING

FORGING SHALL CONFORM TO EDI 198 AND EIS SOZ

 $-2,2006 - 0009$

MATERIAL-AMS 6265 STEEL **FORGED BARS**

PER EPS 13066

DIA
CORDANCE WITH EDI 9 2318

tion $14 - EX - 78785$.

Figure 125. Fatigue Test Gear Configuration 15-EX-78786.

177

Figure 126. Fatigue Test Gear Configuration 16-EX-78787.

179

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aration 16-EX-78787.

Figure 127. Main Accessory Drive Spur Gear (6829396).

ur Gear (6829396).

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Figure 128. Propeller Brake Outer Member (6829395).

ber (6829395).

APPENDIX II

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SAMPLE PROCESS ROUTING SHEETS

This appendix consists of sample process routing sheets for a full form ground fillet gear (EX-78772, Figure 129) and for a protuberant hobbed gear (EX-78776, Figure 130). The processing routings for all ¹⁶ fatigue test gear part numbers were identical except for the changes required by the two root fillet configurations, as shown in these samples, and for the difference in carburized case depth required by the two diametral pitches.

Figure 129. Typical Routing Sheet for Full Form Ground Fillet Gear, EX-78772 (Sheet 1 of 9).

ROUTE SHEET

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ROUTE SHEET

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Figure 129. Typical Routing Sheet for Full Form Ground Fillet Gear, EX-78772 (Sheet 2 of 9).

Figure 129. Typical Routing Sheet for Full Form Ground Fillet Gear, EX-78772 (Sheet 3 of 9).

ROUTE SHEET

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Figure 129. Typical Routing Sheet for Full Form Ground Fillet Gear, EX-78772 (Sheet 4 of 9).

Figure 129. Typical Routing Sheet for Full Form Ground Fillet Gear, EX-78772 (Sheet 5 of 9).

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ROUTE SHEET

Figure 129. Typical Routing Sheet for Full Form Ground Fillet Gear, EX-78772 (Sheet 8 of 9).

PEV $\frac{1}{\alpha}$ a REV \overline{R} **MACHINE** Purnace Lathe Lathe EX-78776
NEXT ASSENBLY NUMBER PART OR TOOL NUMBER TOOL CODE DRAWING NUMBER MODEL NO $8 - 78 - 76$ **TOOL NO** Barden at 1750° and temper per EPS 202 and PCI 8000 for control.
C34-C38.
CAUTION: Core harden all 16 lots of gears at same time. $5ⁿ$ dia x 1" long Impect and attach serial number. Start log of FCI 8000 and required information. Forward parts to Dept. 846. Hold until all 16 lots of gears are ready to core harden. ROUTE SHEET WATERIAL SPEC - SIZE POTREd Bar Machine to sketch Oper. #13 and deburr.
Transfer tag. PATIGUE TEST GEAR Mechine to sketch Oper. 1 and deburr. OPERATION Rockwall and memaflux. MAT NAME Grit blast. **P-8-55** \mathbf{r} $\overline{\mathbf{5}}$ Ł WRITTEN BY 8563 8563 8627 $\overline{\mathbf{r}}$ $\frac{1}{2}$ 619 859 819 APPROVED **The All All All All All** OPER NO SHEET 1 $\mathbf{1}$ $\boldsymbol{\mathcal{L}}$ σ \rightarrow \overline{r} \mathbf{v} \blacksquare

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Figure 130. Typical Routing Sheet for Protuberant Hobbed Gear, EX-78776 (Sheet 1 of 9).

195

ROUTE SHEET

Figure 130. Typical Routing Sheet for Protuberant Hobbed Gear, EX-78776 (Sheet 3 of 9).

Figure 130. Typical Routing Sheet for Protuberant Hobbed Gear, EX-78776 (Sheet 4 of 9).

ROUTE SHEET

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ROUTE SHEET

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Figure 130. Typical Routing Sheet for Protuberant Hobbed Gear, EX-78776 (Sheet 5 of 9).

Figure 130. Typical Routing Sheet for Protuberant Hobbed Gear, EX-78776 (Sheet 6 of 9).

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 $\frac{1}{2} \sum_{i=1}^{n} \mathbf{y}_i \mathbf{z}_i^T$

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APPENDIX III

MATHEMATICAL DESCRIPTION OF STATISTICAL TREATMENT OF TEST DATA

This appendix consists of a detailed description of the mathematical model developed to linearize the test data, its substantiation, its use to determine an endurance limit, and the determination of the variability associated with this endurance limit. A description of the method used to determine the significance of main effects and interactions for the four designed experiment variables is included. Finally, a mathematical equation developed to assign numerical values to the four geometric factors studied is described.

DERIVATION OF S/N CURVE

Analytical Model

There were two requisites for the mathematical model; it should linearize the relationship between cycles-to-failure and stress to define the endurance limit accurately,and it should make the variance of the transformed cycles equal within the range of interest for stress to make tests of significance meaningful.

The mathematical model developed is:

$$
Life_T = \left(\frac{1}{K}\right)^C = A + Bx
$$

where

I

 $K = kilocycles to failure$

x = applied stress
C = linearizing par

 $=$ linearizing parameter

A and B ⁼ constants to be determined by the least squares fitting method

The model was checked against two relatively large sets of data. The transformed data are plotted in Figures 131 and 132. The points and the fitted curve are presented in conventional S/N format in Figures 133 and 134. The linearity of the transformed data is evident by inspection. The homogeneity of variances was checked using Bartlett's
test. The stress (or strength) at infinite life is clearly shown at Life $_T = (1)^C = 0$. test. The stress (or strength) at infinite life is clearly shown at Life_T = $\left(\frac{1}{K}\right)$

The value of ^C was selected by trial **and** error because of time limitations. Further development work is suggested to automate the optimization of C and to investigate an

$$
alternate transformation, Life_T = \frac{1}{log (CK)}
$$

Treatment of Runouts

Runout data were used in one of *wo ways. If only runouts occurred at any one stress level, the runouts were treated as failures at 10^9 cycles. Where both runouts and failures occurred at a stress level for any configuration, the data were plotted on normal probability paper using mean ranks to plot the cumulative probability. The points were fitted with a straight line with a slope that best fit all sets of data. The cycles at 50-percent failure represented the average life for all teeth tested at that stress level for the configuration. This value of life, weighted for the associated number of failed teeth, was used in the least squares fit of the complete S/N line.

Figure **132.** Transformed **Gear Tooth Fatigue Data—British Steel EN 39A.**

Analysis

The least squares fit of the S/N line **for** each combination of gear **factors represents** a solution to the equation Life_T = A + Bx. Recalling that the endurance limit occurs at Life $T = 0$, it follows that $A + Bx = 0$ at this point. Subtracting A from both sides of the equation and dividing through by B, **and** since A is negative, the value of x at **the** endurance limit is simply A/B.

Each endurance limit A/B has a measure of variability associated **with it. This** variability is indicated by the scatter in **test** points about the line, which results from inherent variability in material, processing, and testing factors. The variability or variance. $(\sigma_{A/B})^2$, of each intercept was derived through error propagation techniques (reference 20):

$$
(\sigma_{A/B})^2 = \frac{1}{B^2} \sigma_A^2 + \frac{A^2}{B^4} \sigma_B^2 + \frac{2A}{B^3} \sigma_{AB}^2
$$

where the components $\sigma_{\rm A}{}^2$, $\sigma_{\rm B}{}^2$, and $\sigma_{\rm AB}{}^2$ represent the variance of A, variance of B, and covariance of A and B, respectively. The variances of A, B, and the covariance

Figure 133. R. R. Moore Rotating Bending Test Data.

Figure 134. Gear Tooth Fatigue Data—British Steel EN 39A.

of ^A and B were evaluated using the techniques presented in reference 3. Briefly, a matrix arising from the least squares solution of A and B is set up and inverted. The inverse elements of the least squares matrix, when multiplied by the variance, S_{ρ}^2

 Σ (Life_T - A - Bx)² $\frac{1}{n-2}$ (where n is the number of test points defining the line) associated with regression, are the variances of A, B, and the covariance of A and B.

To test the significance of main effects and interactions, linear combinations of the 16 endurance limits were computed and **then** divided by the appropriate standard deviation. The linear combination divided by the standard deviation constitutes the criterion for "t" tests of significance.

r-rATISTICAJ. TESTS OF SIGNIFICANCE

The concept of statistical tests of significance arises because of the innerent variability associated with any type of testing. In particular, the variability associated with fatigue testing is large.

If repeat iatigue tests are made under identical test conditions, the computed endurance limits will not be identical, but will be distributed about the average of the computed values. If one or more test conditions are changed (i.e., geometric factors), a criterion may be set up to determine if the magnitude of the change in endurance limits is larger than can be expected due to chance alone—at a preselected probability level.

The criterion established was the "t" test, where "t" is the observed difference in **endurance limits** generated from **two** different test conditions. These test conditions **were then divided** by the **standard** deviation of the difference;

"t" =
$$
\frac{EL_1 - EL_2}{\sqrt{s_1^2 + s_2^2}}
$$

where

- $EL₁$ = the endurance limit associated with the first test condition
- $EL₂$ = the endurance limit associated with the second test condition
- ${\rm S_1}^2$ and ${\rm S_2}^2$ = the variances a**ssoci**ated with the respective endurance limits

The critical "t" value is a number based on degrees of freedom (related to number of data points), and some preselected significance level α (an arbitrary risk of making a wrong conclusion). The degrees of freedom for the gear test program was approximately 50. The significance level was selected as $a = 0.05$. Therefore, if the computed "t" was equal to or greater than 2. 0, it was concluded that the factor evaluated caused a real (or significant) change in endurance limit. For the mathematical sense, a is defined as the probability that a "t" value larger than the critical "t" will result if the evaluated geometric factor has no true effect on endurance limit; therefore, if a "t" larger than the critical "t" is computed, the odds are ¹⁹ to ¹ that the effect is real.

Some modification of the "t" tests of significance was necessary because of unequal sample sizes in the ¹⁶ combinations of the four geometric factors. The resulting "t" tests are set up by first obtaining the difference between weighted average associated with low and high values assigned to the geometric factors, and then dividing by an approximate standard deviation.

$$
"t" = \frac{\left(\frac{\Sigma W_L EL_L}{\Sigma W_L} - \frac{\Sigma W_H EL_H}{\Sigma W_H}\right)}{\sqrt{\frac{1}{64} \sum_{i=1}^{16} \sigma_i^2}}
$$

where

- W ⁼ sample size
- EL ⁼ endurance limit
- $L = low$
- $H = high$

The undefined indices of summation include run numbers to which low values and high values, respectively, have been assigned for the evaluation of any factor or interaction.

Confidence intervals are also based on the same critical "t" values and variances used in tests of significance. Confidence intervals are set up by the equations:

$$
LL = EL - "t"_{a/2} \times S_{EL}
$$

$$
UL = EL + "t"_{a/2} \times S_{EL}
$$

For mathematical terms, the probability is $(1-a)$ that the resulting interval will contain **the true** endurance limit.

An example of a test of significance is provided for the main effect—diametral pitch. For convenience, the following notation is defined:

By convention, the presence of a letter (associated with a geometric factor) indicates that the high value is assigned to that factor. The absence of a letter indicates that the low level is assigned to that factor. Further, (1) means that the low level is assigned to all factors. Thus, the configuration ab means gears of ¹² diametral pitch, 25-degree pressure angle, small radius, and protuberance ground.

To test the significance of diametral pitch using the notation developed, a linear combination of 16 computed endurance limits was set up.

> $L = 1/8$ $\left[a + ab + ac + abc + ad + abd + acd + abcd \right]$ - $1/8$ $[(1) + b + c + bc + d + bd + cd + bcd]$

The first group contains all gear configurations of 12 diametral pitch, and the second group contains all configurations of ⁶ diametral pitch.

The variance of L, which is the same for all tests, is:

$$
L^{2} = \frac{1}{64} \left[\sigma_{a}^{2} + \sigma_{ab}^{2} + \dots + \sigma_{abcd}^{2} \right] + \frac{1}{64} \left[\sigma_{(1)}^{2} + \dots + \sigma_{bcd}^{2} \right]
$$

A "t" test of significance is set up by dividing L by the standard deviation of σ_{I} or "t" $\frac{L}{2}$

$$
\sigma_{\rm L}
$$

The four main effects, all two-factor interactions and all three-factor interactions, were tested using this method. The exact linear combination for any specified effect or interaction is found in reference ¹⁴ or 29,

PREDICTIVE EQUATION BASED ON TEST RESULTS

A second objective in the analysis of gear tooth fatigue failures was to develop a single predictive equation incorporating numerical values assigned to the geometric factors in addition to the basic applied load. The technique is as follows:

1. Define a linear mathematical model

$$
Life_T = A + Bx
$$

where

2. Redefine the geometric factors

The coefficients ^A and ^B in the linear model are defined by the geometric factors as follows:

 $A = (a0 + a1 U1 + \ldots + a4 U4 + a5 U1 U2 + \ldots + a10 U3 U4 + a11 U1 U2 U3 + \ldots +$ al4 U2 U3 U4)

 \blacktriangle

 $B = (b0 + b1 U1 + \dots + b14 U2 U3 U4)$

In terms of the refined coefficients, the expanded model is:

 $\text{Life}_{\text{T}} = (1/\text{K})^{1/2} \cdot \text{\textsterling}} = (a0 + a1 \text{ U1} + \ldots + a14 \text{ U2 U3 U4}) +$ $(b0 + b1 U1 + \ldots + b14 U2 U3 U4) X$

The individual coefficients were evaluated using the least squares technique.

The following geometric factors affect fatigue life and are listed in order of decreasing importance:

- 1. (Pressure angle \times diametral pitch \times dedendum) \times load
- 2. Pressure angle \times diametral pitch \times dedendum
- 3. Pressure angle ^X diametral pitch
- 4. Pressure angle ^X dedendum ^X fillet radius
- 5. Pressure angle \times fillet radius
- 6. Pressure angle \times load
- 7. Pressure angle
- 8. Dedendum
- 9. Diametral pitch ^X dedendum
- 10. (Pressure angle \times diametral pitch) \times load
- 11. Dedendum ^X fillet radius

In terms of coding, the finalized equation is:

Life_T = $(1/K)^{1/2.2}$ = 2.27864 - 5.47376 \times 10⁻² (U1) - 1.18640 (U3) -8, 97196 \times 10⁻³ (U1 U2) + 1, 20233 \times 10⁻¹ (U1 U4) -

\n3. 67334
$$
\times
$$
 10⁻² (U2 U3) + 4. 43879 \times 10⁻¹ (U3 U4) +
\n9. 11496 \times 10⁻³ (U1 U2 U3) - 1. 17884 \times 10⁻¹ (U1 U3 U4) (load) +
\n \times {-3. 58085 \times 10⁻⁶ (U1) - 1. 09015 \times 10⁻⁶ (U1 U2) +
\n1. 75948 \times 10⁻⁶ (U1 U2 U3)\n

The standard deviation (σ_{γ}) associated with the predictive equation is 0.0656.

The equation can be used to predict transformed kilocycles only within the range of interest for applied load values and only within the range of values assigned to the geometric factors from which the equation was derived.

The most efficient use of the predictive equation can be obtained by first computing transformed kilocycles using observed values itr the geometric factors and the applied load, and then converting to cycles or kilocycles, as desired. To obtain an approxiroad, and their converting to cycles or allocycles, as desired. To octain an approach mate confidence interval for k locycles to failure, add and subtract the quantity $(Z_{a/2} \times 0.0656)$ to and from the calculated Y = transformed kilocycles $(Z_{a/2}$ is a confidence factor to be obtained from a table of areas for the normal distribution). These computed upper and lower limits are then transformed to kilocycles using the same procedures used to convert ^Y to kilocycles.

The equation, although derived from valid test data, is yet untried in the predictive sense. It may be that additional testing, at more than two levels per geometric factor, may be required to derive a mathematical model suitable for general usage in predicting gear failures.

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APPENDIX IV

AGMA CALCULATED STRESS VERSUS LIFE AND TRANSFORMED LIFE

This appendix consists of life versus AGMA calculated stress plots of the fatigue test data points for each of the ¹⁶ gear configurations. See Figures 135 through 150. The calculated mean S/N curve fitting the data points is drawn on each plot. Also included are transformed life versus AGMA calculated stress plots of the fatigue test data points for each of the ¹⁶ gear configurations. See Figures ¹⁵¹ through 166. Life and transformed life versus alternating stress (R, R. Moore) data are shown in Figures ¹⁶⁷ and 168, respectively.

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AGMA Stress - p.s.i. x 1000

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 ϵ).

Figure 167. Fatigue Test Gear Life Data (R. R. Moore).

Figure 168. Fatigue Test Gear Transformed Life Data (R. R. Moore).

APPENDIX V

DESCRIPTION OF COMPUTER PROGRAM

This appendix consists of a complete description of the computer program and includes the program equations, input data sheet, source program print-out, and a sample problem. The equations are given in both engineering and computer program terms.

DESCRIPTION OF PROBLEM

Gear tooth bending strength is one of the major criteria in gear design. Gear tooth loading is cyclic in nature, therefore subjecting the material to fatigue. The critical section is close to the root diameter. Failure usually results in fracture of an entire tooth from the gear rim.

Calculation of gear tooth bending stress requires geometrically precise description of the root fillet contour and location of the critical section. The point of the involute tooth profile at which the transmitted load produces the maximum bending stress is also required. Knowledge of the mounting and operating conditions of the unit in which the gear is assembled is required to assess the increase in bending stress caused by misalignment, overloads, system dynamics, and centrifugal forces. Gear material ultimate strength and fatigue data must be kr.own to convert the calculated stress to anticipated gear life.

The purpose of this program is to calculate gear tooth bending stress and gear life considering these factors.

METHOD OF SOLUTION

The gear tooth geometry has been developed using basic formulas available in the literature. The hob dimensions have been used to generate in the program the trochoidal fillet contour resulting on a finished gear from some gear processing procedures. A true radius fillet is used when a shaped contour is specified in the program input. The program uses an iteration routine to inscribe a parabola (per Lewis construction) and to locate its tangent point with the root fillet contour. The Lewis dimensional parameters for the weakest section thus obtained are then calculated. These parameters are then used in the AGMA formula as given in AGMA 220. 02 (Appendix VI herein) to calculate ^a bending stress, ^A hoop stress at the root diameter is also calculated. The AGMA temperature factor and factor of safety are applied to the bending and hoop stresses, which are then combined by use of a modified Goodman diagram. The modified Goodman diagram is based on an ultimate strength and S/N curve determined for the material used and the gear tooth designs tested; they may be easily changed within the program. A life is also determined from the modified Goodman diagram.

COMPUTER TYPE AND PROGRAM LANGUAGE

The subject program is written in FORTRAN IV language for use on an IBM 7094 computer.

There must be four, five, or six cards per data set depending on data input for words 4 and ⁵ on Card 1. Data sets may be stacked. Computer running time will be approximately 0. ¹ minute per set of data.

INPUT DATA

A sample input data form is shown in Figure 169. Each set of data requires four, five, or six **cards. A** description of the cards follows.

Input Card ¹

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*** SHAPED**
* HOBBED

IDENTIFICATION
NUMBER

Figure 169. Sample Input Data Form.

01866年12月14日年12月14日年12月14日年12月14日12月14日12月22日12月22日12月22日12月22日12月14日12月14日12月14日12日12日12日12日12月12日12日12日12月12日12月12日12月12日12月12日12月12日

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SEE FIGTIO

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PRESSURE ANGLE

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Input Card ⁵

 \mathcal{L}_{max}

This card is needed only when words ⁴ and ⁵ of Card ¹ are given as "HOBBED" and "0" or "2, " respectively. This card is for PINION only. See Figure 170.

Figure 170, Standard or Protuberance Hob Form for Input.

Input Card ⁶

This card is needed only when words ⁴ and ⁵ of Card ¹ are given as "HOBBED" and "l" or "2," respectively. This card is for GEAR only and is the same format as input Card 5.

PROGRAM EQUATIONS

Computer program input symbols in both engineering (AGMA) and program terms are listed as follows.

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The computer program equations in both engineering (AGMA) and program terms follow. The basic geometric equations for gear teeth can be obtained or developed from textbooks.

$$
\frac{\text{AGMA}}{\text{BCC}} = \left[\frac{\left(DOB}{Db}\right)^2 - 1\right]^{1/2} \qquad \text{EBCG} = \left[\frac{\left(DDBB}{DBG}\right)^2 - 1\right]^{1/2}
$$
\n
$$
\text{BCC} = (\text{TAN}\phi_x(\text{mg} + 1)) - (\epsilon_{BCG} \times \text{mg}) \qquad \text{EBCP} = (\text{FXTA}(\text{AMG} + 1)) - (\epsilon_{BCG} \times \text{Rmg}) \qquad \text{EBCP} = (\text{FXTA}(\text{AMG} + 1)) - (\epsilon_{BCG} \times \text{Rmg}) \qquad \text{EBCP} = (\text{FXTA}(\text{RMG} + 1)) - (\epsilon_{BCT} \times \text{Rmg}) \qquad \text{EBCP} = (\text{FXTA}(\text{RMG} + 1)) - (\epsilon_{BCT} \times \text{Rmg}) \qquad \text{EBCP} = \text{EBCP} - \frac{2 \times \text{PI}}{\text{ANP}} \qquad \text{EBSP} = \text{EECP} - \frac{2 \times \text{PI}}{\text{ANP}}
$$
\n
$$
\text{FSTCC} = \epsilon_{BCG} - \frac{2\pi}{NG} \qquad \text{EESG} + \text{EECG} + \frac{2 \times \text{PI}}{\text{ANG}}
$$
\n
$$
\epsilon_{BCTG} = \epsilon_{BCG} - \frac{2\pi}{NG} \qquad \text{EESG} = \text{EBCG} - \frac{2 \times \text{PI}}{\text{ANG}}
$$
\n
$$
\epsilon_{AOMA} = \left[\frac{(\text{OMA})}{\text{B}}\right)^2 - 1\right]^{1/2} \qquad \text{E}_{OGMA} = \left[\frac{(\text{DOOMA})}{DBF}\right)^2 - 1
$$
\n
$$
\text{G}_{BC} = \left[\epsilon_{BCP}^2 + 1\right]^{1/2} \text{db} \qquad \text{DBCP} = \left[\text{EBSP}^2 + 1\right]^{1/2}
$$
\n
$$
\text{G}_{BCT} = \left[\epsilon_{BCP}^2 + 1\right]^{1/2} \text{db} \qquad \text{DESP} = \left[\text{EESP}^2 + 1\right]^{1/2}
$$
\n
$$
\text{D}_{BCT} = \left[\epsilon_{BCG
$$

$$
EBCG = \left[\left(\frac{DODBG}{DBG}\right)^2 - 1\right]^{1/2}
$$

\n
$$
EBCP = (FXTA(AMG + 1)) - (EBCG \times AMG)
$$

\n
$$
EECG = (FXTA(RMG + 1)) - (EECP \times RMG)
$$

\n
$$
EBSP = EECP - \frac{2 \times PI}{ANP}
$$

\n
$$
EESP = EBCP + \frac{2 \times PI}{ANP}
$$

\n
$$
EBSG + EECG + \frac{2 \times PI}{ANG}
$$

\n
$$
ECSG = EBCG - \frac{2 \times PI}{ANG}
$$

\n
$$
EOPMA = \left[\left(\frac{DOPMA}{DBP}\right)^2 - 1\right]^{1/2}
$$

\n
$$
EOGMA = \left[\left(\frac{DOGMA}{DBP}\right)^2 - 1\right]^{1/2} \times DBP
$$

\n
$$
DBSP = \left[EBCP^2 + 1\right]^{1/2} \times DBP
$$

\n
$$
DESP = \left[EESP^2 + 1\right]^{1/2} \times DBP
$$

\n
$$
DECP = \left[EECP^2 + 1\right]^{1/2} \times DBP
$$

\n
$$
DECC = \left[EBCG^2 + 1\right]^{1/2} \times DBG
$$

\n
$$
DBSG = \left[EEGG^2 + 1\right]^{1/2} \times DBG
$$

\n
$$
DESG = \left[EEGG^2 + 1\right]^{1/2} \times DBG
$$

1/2

 \times DBG

AGMA

 m_{max} = NG (ϵ_{OG} - TAN **(Np(«OP** " **TAN^¥J)/2»**

 $\frac{m_{\text{N}}}{m_{\text{min}}}$ = NG (ϵ_{BCG} - TAN ϕ_x) + θ $(\mathtt{NP}~(c_{\mathbf{ECP}} - \mathtt{TAN}\boldsymbol{\phi}_{\mathbf{x}}))/2$ w

See Figure 171.

$$
SIN (AN) = \frac{0.5 \text{ t}_{C}}{0.5 \text{ D}}
$$
\n
$$
\widehat{AN} = ARC TAN \left(\frac{AN}{\sqrt{1 - AN^{2}}}\right)
$$
\n
$$
t = \widehat{AN} \times D
$$
\n
$$
t_{x} = D_{x} \left[\left(\left(\frac{t}{D}\right) + INV\phi\right) - INV\phi_{x} \right]
$$

Program

$$
AMPMA = ANG (EOGMA - FXTA) +ANP (EOPMA - FXTA)/2 =AMPMI = ANG (EECG - FXTA) +ANP (EECP - FXTA)/2 =
$$

AN =
$$
\frac{0.5 \times \text{TPMIS}}{0.5 \times \text{DP}}
$$

AN = ATAN $\left(\frac{\text{AN}}{\sqrt{1 - \text{AN}^2}}\right)$
TPMIS = AN × DP
TPMIN = D × P $\left[\left(\left(\frac{\text{TPMIS}}{\text{DP}}\right) + ZF\right) - ZFX\right]$

Figure 171. Arc and Chordal Tooth Thickness.

AGMA Program

$$
\cos \phi_{\mathbf{x}} = \frac{Db}{D_{\mathbf{x}}}
$$
\n
$$
\hat{\phi_{\mathbf{x}}} = \text{ARC TAN} \left(\frac{\sqrt{1 - \phi_{\mathbf{x}}^2}}{\phi_{\mathbf{x}}} \right)
$$
\n
$$
\hat{\phi_{\mathbf{x}}} = \text{LRTAN} \left(\frac{\sqrt{1 - \phi_{\mathbf{x}}^2}}{\phi_{\mathbf{x}}} \right)
$$
\n
$$
\text{INV } \phi_{\mathbf{x}} = \text{TAN } (\phi_{\mathbf{x}}) - \hat{\phi_{\mathbf{x}}}
$$
\n
$$
\text{EVALUATE: } \mathbf{F} = \text{LRTAN} \left(\frac{\sqrt{1 - F^2}}{F} \right)
$$
\n
$$
\text{EVALUATE: } \mathbf{F} = \text{LRTAN} \left(\frac{\sqrt{1 - F^2}}{F} \right)
$$
\n
$$
\text{EVALUATE: } \mathbf{F} = \text{LRTAN} \left(\frac{\sqrt{1 - F^2}}{F} \right)
$$
\n
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\text{EVALUATE: } \mathbf{F} = \text{LRTAN} \left(\frac{\sqrt{1 - F^2}}{F} \right)
$$
\n
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\text{EVALUATE: } \mathbf{F} = \text{LRTAN} \left(\frac{\sqrt{1 - F^2}}{F} \right)
$$
\n
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\text{EVALUATE: } \mathbf{F} = \text{LRTAN} \left(\frac{\sqrt{1 - F^2}}{F} \right)
$$
\n
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\text{EVALUATE: } \mathbf{F} = \text{LRTAN} \left(\frac{\sqrt{1 - F^2}}{F} \right)
$$
\n
$$
\text{EVALUATE: } \mathbf{F} = \text{LRTAN} \left(\frac{\sqrt{1 - F^2}}{F} \right)
$$
\n
$$
\text{EVALUATE: } \mathbf{F} = \text{LRTAN} \left(\frac{\sqrt{1 - F^2}}{F} \right)
$$
\n
$$
\text{EVALUATE: } \mathbf{F} = \text{LRTAN} \left(\frac{\sqrt{1 - F^2}}{F} \right)
$$
\n
$$
\text{EVALUATE: } \mathbf{F} = \text{LRTAN} \left(\frac{\sqrt{1 - F^2}}{F} \right)
$$
\n
$$
\text
$$

Basic Hob Data (See Figure 172.)

Program

TSA = $\frac{\pi}{N}$ DHPA = $N \times \frac{HLEAD}{4}$ HADDN = 0.5 (DHPA - D_R) $HPAR = 0.017453293 \times HPA$ $HTTN = HTT + 2 (HADDN - HADD) TAN (HPAR)$ $HTTR = 0.5 \times HTT - HADD \times TAN (HPAR)$ HA = HTTR - <mark>HTIPR-HPW</mark>
COS(HPAR) $HRCTRX = HA + HTIPR \times TAN (HPAR)$ $RHPA = 0.5 DHPA$ HRCTRP ⁼ HADDN - HTIPR \widehat{HPCA} = ARC TAN $\left(\frac{HRCTRX}{HRCTRP}\right)$ $HYP = \sqrt{HRCTRX^2 + HRCTRP^2}$

Wrap pitch line of hob around gear pitch circle by equal increments and calculate path of hob tip radius center. See Figure 173.

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Figure 172. Standard or Protuberance Hob Form for Calculation.

Figure 173. Tooth Generation by Hob.

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INC ⁼ 0, I X HTTN PPPOS ⁼ 0 PPPOS PPA RHPA (increment of change) **(pitch** point position—first time through increase PPPOS by increments each time) $HPCTR = VPPPOS² + RHPA²$ \widehat{PHA} = ARC TAN $\left(\frac{\text{PPPOS}}{\text{RHPA}}\right)$ PPPHA ⁼ PPA - PHA $HPCX = HPCTR \times SIN (PPPHA)$ $HPCY = HPCTR \times COS$ (PPPHA) RCTRA ⁼ HPCA + PPA RCTX *⁼* HYP X SIN (RCTRA) - HPCX $RCTY = HPCY - HYP \times COS (RCTRA)$

Calculate points where hob tip radius is making final cut in fillet of gear. See Figuie 174.

Figure **174.** Fillet Generation by **Hob.**

 $FCPLA$ **-** ARC TAN $\left(\frac{HRCTRP}{PPPOS}\right)$

FCA « FCPLA - PPA

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XFIL » RCTX + HTIPR X COS (FCA)

 $YFL = RCTY - HTIPR \times SIN (FCA)$

Convert location of fillet points from center of tooth space to center of gear tooth. See Figure 175.

 (XFL) FSA = ARC TAN $\left(\frac{1}{\text{YFL}}\right)$ $FTA = TSA - \widehat{FSA}$ RFIL = $\sqrt{\text{XFL}^2 + \text{YFL}^2}$ $XTFIL = RFL \times SIN (FTA)$ $YTFIL = RFL \times COS (FTA)$

Find parabola for evaluating bending stress. See Figure 176.

Figure 175. Generated Tooth Fillet. Figure 176. Trochoidal Fillet

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Inscribed Lewis Parabola.

 $FTCA = \frac{\pi}{2} - TSA$ $\mathbf{FTPA} = \mathbf{F} - (\mathbf{FTCA} + \mathbf{FCA})$ **FPARA** = $\frac{\pi}{2}$ - FTPA $AB = T \times TAN$ (FPARA)

 $H = 0.5 DV - YTFIL$

Reiterate for new T. H, and YTFIL values until AB ⁼ 2H is satisfied.

Find the radius of curvature of generated fillet tangent to parabola. See Figure 177. SIDEA ⁼ YFIL - (RHPA - HADDN)

HYPA =
$$
\frac{\text{SIDEA}}{\text{COS (FCA)}}
$$

ANGLEA = 0.5 $((\frac{\pi}{2}) + \text{FCA})$

 $FLR = HYPA \times TAN (ANGLEA)$

Figure 177. Radius of Curvature at Weakest Section.

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Find X value from parabola **and diameter** of the weakest section of tooth. See Figure **178.**

Program $\textbf{ANGLED} = \textbf{ARC TAN} \left(\frac{1}{H} \right)$ T **ADJ** = SIN (ANGLED) X DIM $\approx \frac{ADJ}{COS (ANG)}$ COS (ANGLED) - H DW = 2 $\sqrt{T^2 + YTFIL}^2$

Find coordinates to center of true fillet radius. See Figures 179 and 180

 $H = \frac{DR}{2} + RF$ When $\frac{DB}{2} \leq H$, then (Figure 179):

$$
CPR = \frac{0.5 DB}{H}
$$

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Figure 178. Diameter of Weakest Section and Lewis *Y* **Value.**

 \bullet

Figure 179. Coordinates at Center of True Fillet Radius—Base Circle Below Root Diameter.

Figure 180. Coordinates at Center of "rue Fillet Radius—Base Circle Above Root Diameter.

CPRA = ARC TAN
$$
\left(\frac{V_1 - CPR^2}{CPR}\right)
$$

\nOPP = $V_H^2 - (0.5 DB)^2$
\nA = OPP - RF
\nH1 = $V_A^2 + (0.5 DB)^2$
\nCA = $\frac{0.5 DB}{H1}$
\nCARA = ARC TAN $\left(\frac{V_1 - CA^2}{CA}\right)$
\nZCA = TAN (CARA) - CARA
\nB = CPRA - CARA - ZCA
\nFAPRA = PK + B
\nXCENT - SIN (FAPRA) × H
\nYCENT = COS (FAPRA) × H
\nWhen $\frac{DB}{2}$ > H, then (Figure 180):
\nXX = $\left(\frac{DB}{2}\right)$ SIN (PK)
\nFAPSI = $\frac{XX + RF}{H}$
\nFAPRI = ARC TAN $\left(\frac{FAPSI}{V_1 - FAPSI^2}\right)$
\nXCENT = SIN (FAPRA) × H
\nYCENT = COS (FAPRA) × H
\nFind parabola for evaluating bending

Find parabola for evaluating bending stress. Also, find X value and diameter of weakest section. See Figure 181.

Program

ALPHA = 0.1 (First time only)
\n
$$
V = SIN (ALPHA) \times RF
$$

\n $VI = VRF^2 - V^2$
\nT = XCENT - VI

 $\ddot{}$

 $\label{eq:1} \frac{1}{\sqrt{2}}\left(\frac{1}{\sqrt{2}}\right)^{2} \left(\frac{1}{\sqrt{2}}\right)^{2}$

Figure 181. True Fillet Radius Inscribed Lewis Parabola.

 $YA =$ $\frac{T}{TAN (ALPHA)}$ $H = (RV - YCENT) + V$

Reiterate for new value of ALPHA until YA ⁼ 2H is satisfied.

$$
YB = YCENT - V
$$

 $DW = VYB^2 + T^2 \times 2$
$Q = \text{ARC} \text{ TAN} \left(\frac{H}{T}\right)$ $Q = \frac{\pi}{2} - Q$ **XDIM ⁼ T X TAN (Q) AGMA** $T = \frac{63025 \times Hp}{100}$ **IP** $W_t = \frac{2 \times T}{T}$ **^P** $G = \eta P \times R_{mg}$ **S h ⁼** $\frac{v^2}{2}$ **g b**¹ = **b** - **rT** $r_1 = \frac{b_1^2}{Rp + b_1}$ $r_f = r_1 + r_T$ χ 0. 20 $K_f = 0.22 + \left(\frac{T}{r_f}\right)^{0.20} \left(\frac{T}{h}\right)$ 0.40 $K_f = 0.18 + \left(\frac{T}{r_f}\right)^{0.15} \left(\frac{T}{h}\right)^{0.45}$ $K_f = 0.14 + \left(\frac{T}{r_f}\right)^{0.11} \left(\frac{T}{h}\right)^{0.50}$ $J = \frac{1}{K_f \times m_g}$ W_t K_0 Pd K_s K_m $\overline{K_V}$ **F J TQ _ 63025 X HORSES** $WT = \frac{2 \times TQ}{BDMD}$ **Program RPMP RPMP** $RPMG = RPMP \times RMG$ \mathbf{v}^2 **SHOOP = RHO** 386.064 **Bl ⁼ HADD - HTIPR** $R1 = \frac{B1^2}{RP + B1}$ **RFMI ⁼ Rl ⁺ HTIPR** $KF = 0.22 + \left(\frac{T}{PEM} \right)^{0.20} \left(\frac{T}{H}\right)^{0.40}$ *{RFMI)* **\H/ ,0.15** $KF = 0.18 + \left(\frac{T}{RFMI}\right)^{3.18} \left(\frac{T}{H}\right)$ $\left(\frac{T}{T}\right)^{0.11}(\overline{T})$ **\RFMI/** *\ Hj* 0.45 0.50 **KF ⁼ 0. 14 + YAGMA** $SB = \frac{WT \times KO}{KV} = \frac{PDX}{FMND} = \frac{KS \times KM}{I}$ $KF \times MN$ **KV FMINP**

Program

Combine bending and centrifugal stress on the modified Goodman diagram. See Figure 182.

From S/N curve in Figure 183, find the life cycle endurance limit.

Figure 182. Modified Goodman Diagram Combining Centrifugal and Bending Stresses.

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Figure 183. Fatigue Test Gear Endurance Strength for Computer Program.

SOURCE PROGRAM LISTING

The source program is listed on the following pages. Comment cards have been used to define generated symbols within the program. Several subroutines are used and are also listed.

SOURCE PROGRAM PRINT-OUT

```
\mathbf C* EXTERNAL SPUR GEARS - FOR *
\mathbf cEVALUATING BENDING STRESS
                         \bullet\bullet\mathbf C\bulletPROGRAMED BY M.R. CHAPLIN
                                                           \bullet\mathbf cALLISON, DIV. OF GMC
\mathsf{C}* * * * * * * * * * * * * * * *
\mathbf{C}REAL KT, KR, KM, KO, KV, MN, JP, JG, KFP, KFG, KSP, KSG
       INTEGER CODE
                                                                                          20CIMENSICN CIAP(6),DIAG(6),FPRA(6),FPDE(6),FPSI(6),FPCQ(6),FPTA(6),
                                                                                           30*ZFP(6), FGRA(6), FGCE(6), FGSJ(6), FGC0(6), FGTA(6), ZFG(6),
                                                                                           40
      *DvP{6},RVP{6},ALP+P{6},TP{6},HP{6},DWP{6},XDIMP{6},
                                                                                           50
      *CVG(6),RVG(6),ALPPG(6),TG(6),HG(6),DWG(6),XDIMG(6),
                                                                                          60
      *SBP(6), SBG(6), SBP+DP(6), SBGHOP(6), YPAGMA(6), YGAGMA(6),
                                                                                          70
      *FILRP(6), FILRG(6), XCYC(5), YPST (5),
                                                          JP(5), JG(5), KFP(5),
                                                                                          80
      *KFG(5), G1(12), G3(12)90
       EQUIVALENCE (DIAP(1), DBCP), (DIAP(2), DBSP), (DIAP(3), CP),
                                                                                         100
      *(DIAP(4), DXPI, (DIAP(5), DESP), (DIAP(6), DECP),
                                                                                         110*{CIAG(1), DECG), (DIAG(2), UBSG), (DIAG(3), DG), (DIAG(4), DXG),
                                                                                         120
      *IOIAG(5), DESG, {}, [DIAG(6), DECG]130C
   LOGICAL UNIT/PODE (LIN=5 INPUT 5/RCD)
\mathbf{c}\mathbf C\mathbf cLIN = 5140
       L0U=6150
     1 READ (LIN,2) ANP, ANG, CNSTO, CUTTER, CODE, HORSES, RPMP, RHO, KT, KR, KM,
                                                                                         160
      *PHIN, PNC, BPIN, BMAX, TPMIS, TIMAS, TGM2S, TGMAS, L,
                                                                                         170
      *DOPMI,DCPMA,CCGMI,DOGMA,FMINP,FMING,BRKP,BRKG,
                                                                                         180
      *DRPMI, DRPMA, DRGMI, DRGMA, RFMIP, RFMIG, UCP, UCG, KO, KV
                                                                                         190
                                                                                         200
     2 FORMAT (2FS.0, F10.0, A6, 2X, ! 2, 2F10.0, 4F5.0/
      #2F10.0,2F5.0,4F10.0,12/
                                                                                         210
      *6F10.0,2F5.0/
                                                                                         220
      *4F10.0,6F5.0)
                                                                                         230
\mathbf cCOMMON RHPA, HPCA, FYP, HRCTRP,
                                              TSA, FCA, YFIL
                                                                                         240
\mathbf cAP=ANP
                                                                                         250
       AG=ANG
                                                                                         260
C
   DATA STATEMENTS - USED TO DEFINE VARIABLE TITLES FOR OUTPUT
\mathbf{r}ſ.
                                                   .6HBSTC (.SHLPSTC),
      DATA (G1(N), N=1, 12) /6HBC (LP, 6HC)
                                                                                         340
                         ,6FPP (OP, 6H)
                                               ,6HESTC (,6HHPSTC),
                                                                                         350
     *6HPP (ST,6FD)
                                                                                         360
      *EHEC (FP,6FC)
      DATA (Q3(N),N=1,12) /6HBC (HP,6HC)
                                                   , GHBSTC (, GHHPSTC),
                                                                                         370
      *6HPP (ST,6FD) .6FPP (OP,6H)
                                               ,6HESTC (,6HLPSTC),
                                                                                         380
     *6HEC (LP,6FC)
                                                                                         390
\mathbf{C}400
      CATA SHAPEC/6PSHAPED/
      CATA PINION, GEAR /6HPINION, 6HGEAR /
                                                                                         410
\mathsf{C}DATA (XCYC(P), P=1,5) /4., 5., 6., 7., 8./
                                                                                         420DATA (YPSI {M), M= 1,5)/265000.,212000.,198000.,186000.,182000./
                                                                                         430
\mathbf c. . . . . . . . . . .
\mathbf cC
\mathsf{C}RN -- CCNVERT FROM DEGREES TO RADIANS
\mathbf cDEGR -- CCNVERT FROM RADIANS TO DEGREES
C
      RN=.017453293
                                                                                         450
      DEGR=57.2957795131
                                                                                         460
      PI=3.1415926535898
                                                                                         470
      IPHI=PHIN
                                                                                         480
```


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530 IF (SBPHOP(5)-182000.) 624,624+626 2180 2190 624 WRITE (LOU.1008) PINION GO TO 628 2200 626 CALL CISCOT (SBPHCP(5).DUMA.YPSI.XCYC.DUMB.-31.5.0.EXP) 2210 628 IF (S8GHOP(2)-182COC.) 63C,63C,632 2220 630 WRITE (LOU, 1008) SEAR 2230 GO TO 609 2240 632 CALL CISCCT (SEGHCP(2), DUMA, YPSI, XCYC, DUMB, -31, 5, 0, EXG) 2250 $\mathbf c$ 609 WRITE (LOU.ICCS) PINION.GEAR 2320 2330 $N = 3$ CC 201 $I = 2.5$ 2340 WRITE (LOU,1010) CLINI,QLINE1),SBPHOP(E),Q3IN),Q3INE1),SBGHOP(I) 2350 201 N=NE2 ?360 WRITE (LCU.999) PINION.GEAR 999 FCRMAT (///26X36HP E N D I N G S T R E S S (AGMA)//21X, A6, 28X $*, A6$ $N = 3$ CD 202 $I = 2, 5$ WRITE (LOU, 1010) CI(N), QI(NE1), SBP(1), Q3(N), Q3(NE1), SBG(1) 202 N=NE2 WRITE (LOU, 5995) SHOOPP, SHOOPG 9999 FORMAT (///20X11H+00P STRESS/10X6HPINION23X4HGEAR/F19.4,15XF12.4) IF (SBPHOP(5)-182000.) 612, 612, 610 2370 610 WRITE (LOU,1011) PINION, EXP 2380 612 IF (SEGHOP(2)-182000.) 1,1,614 2390 614 WRITE (LOU.1011) GEAR.EXG 2400 LOOO FORMAT(IH124X23HNCN STANDARD SPUR GEARS/35X25HDECREASED CENTER DIS **STANCES** 1001 FORMAT(IH124X19HSTANDARD SPUR GEAPS/35X24HSTANDARD CENTER DISTANCE \bullet 1002 FORMAT(1H124X22HNCN STANDARD SPUR GEARS/35X25HINCREASED CENTER DIS #TANCE) 1003 FORMAT(///5X15FBENDING STRESS A6, 9H AT HPSTC/4X31HEXCEEDS ULTIMAT *E OF 27400C. PSI) 1004 FORMAT (///25X35HINPUT DATA SECTIC N///5X *ISHNUMBER CF TEETH9X6HCENTER9X 1H*7X4HCODE7X2HHPL1X3HRPM5X #THDENSITY6)2HKT7X2HKR7X2HKM/5X15HPINION **GEAR8X** *BHDISTANCE?9X 18HPINION LB/CL. IN/5X14,6X14,F17.6,8XA6, *2X12,1X2F14.4,4F9.4) 1005 FORMAT (/5X8HPRESSURE5X9HDIAMETRAL9X8HBACKLASH8X25HCHORDAL TOCTH T *HK -PINIONEX23HCHORDAL TOOTH THK -GEAR/SX5HANGLE8X5HPITCH11X3HMIN (STD PD) MAX *6X3HMAX6X25HMIN **PAX6X24HMIN** (STD PD) */F14.6, F13.6, F11.4, F9.4, F13.6, 3X2F14.6, F15.6) 1006 FORMAT (/S)BHPRESSURESX9HDIAMETRAL9X8HBACKLASH8X21HARC TOOTH THK -*PINION10X15HARC TCOTH THK ~GEAR/5X5HANGLE8X5HPITCH11X3HMIN6X3HMAX *6X21HPIN (STD PD) MAXICX20HMIN $(510 P0)$ MAX /F14.6, F13.6, *F11.4, F9.4, 2F13.6, 7X2F11.6) 1007 FORMAT (//SX2CHOUTSIDE DIA - PINION9X2CHOUTSIDE DIA - GEAR7X *18HFACE WICTH - MIN4X13HMAX TIP BREAK/5X3HMIN14X3HMAX9X3HMIN14X *3HMAX7XEHPINION8X4HGEAR4X6HPINION3X4HGEAR/3X2F11.6,7X2F11.6,5X #2F10.6,3X2F7.4//5X20HROOT DIA - PINICN9X20HROOT CIA $-$ GFAR *7X18HFILLET RADIUS-MIN4X13HMAX UNDERCUT5X2HKO7X2HKV/5X3HMIN14X #3HMAX9X3HMIN14X3HMAX7X6HPINION8X4HGEAR4X6HPINION3X4HGEAR/3X #2F11.6,7X2F11.6,1X2F12.6,3X2F7.4,2F9.4) 1008 FORMAT (///5X15HBENDING STRESS-A6,17H-AT HPSTC IS LESS/4X *S6HTHAN THE ENDURANCE LIMIT OF 182000. PSI - INFINITE LIFE.) S T R E S S3X10H(CCPBINED)// 1009 FORMAT(///26X27HB E N D I N G $*21X, A6, 28X, A6$ 1010 FORMAT (10),2A6,F15.4,5X,2A6,F15.4) 1011 FORMAT (//SX12HLIFE CYCLES ,A6,19H 10 TO A EXPONET CF,F7.2) 2000 FORMAT (IH134X37HO U T P U T D A T A SECTICN) GO TO 1

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25 CALL CISSER (ZARG.TABZ.1.NZ.10Z.NPZ) 01SC0170 NX-NY/NZ DISCOISO **APZL=NPZ&IEZ** DISC0190 $1 - 1$ 01SC0200 **IF LIPSY** DISC0210 $3C, 30, 4C$ 30 CALL CISSER (XA, TABX, I, NX, IDX, NPX) DISC0220 DO 35 JJ=APZ, NPZL DISC0230 NPY(I)=(JJ-1)*NXENPX(1) **DISC0240** DISC0250 NPX(I)=NPX(I) $35 1 - 161$ DISC0260 GO TO 50 01SC0270 **DISCO280** 40 CO 45 JJ=NFZ, NPZL $IS = (JJ - I) * NXGI$ DISC0290 CALL CISSER (XA, TABX, IS, NX, IDX, NPX(I)) 01500300 NPY ([)=NPX([) DISC0310 45 $[-161]$ DISC0320 50 CO 55 1=1,1P12 01SC0330 NLOC=NPX(I) DISC0340 01SC0350 NLOCY=NPY(I) 55 CALL LAGRAN (XA, TABX(NLOC), TABY(NLOCY), IPIX, YY(I)) DISC0360 CALL LAGRAN (ZARG, TABZINPZ), YY, IP1Z, ANS) 01500370 **DISC0380** 70 RETURN **END** 01SC0390 SIBFTC LAGRAD LIST LAGROOIN **CLAGRAN LAGR0020** SUBROUTINE LACRAN (XA, X, Y, N, ANS) **LAGR0030** DIMENSION X(200), Y(200) $SUM = 0.0$ **LAGROOSO** 003 $1=1,N$ **LAGR0060** PROD=Y(I) **LAGR0070** LAGROORD LO 2 $J=1,N$ $A=X(I)-X(J)$ LACR9100 IF (A) $1, 2, 1$ $1.8=(XA-X(J))/A$ LAGRO110 PROD=PROD*E **LAGR0120** LAGR0130 2 CONTINUE 3 SUM=SUM&PRCD LAGRO140 LAGRO150 ANS=SUM **RETURN LAGRO160** LAGRO170 FND SIBFTC UNSD LIST **UNS 0010 CUNS** SUBROUTINE UNS (IC, IA, IDX, IDZ, IMS) **UNS 0020** IF (IC) $5.5.10$ **UNS 0030 UNS 0040** 5 $INS=1$ **UNS 0050** $NC=-IC$ **UNS 0060** GO TO 15 10 IMS=0 **UNS 0070** $NC = IC$ UNS 0080 15 IF (NC-100) **UNS 0090** $20, 25, 25$ **UNS 0100** $20 I A = 0$ **UNS 0110** GC TO 30 **UNS 0120** $25 I A = 1$ $NC = NC - 100$ UNS 0130 **UNS 0140** 30 IDX=NC/10 **UNS 0150** IDZ=NC-ICX*10 **UNS 0160 RETURN END** UNS 0170 SIBFTC CISSED LIST 01550010 **CCISSER** SUBROUTINE CISSER (XA, TAB, I, NX, IO, NPX) 01550020 DIMENSION TAB(200C) DI550030 DISS0050 NPT=IC&I

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SAMPLE PROBLEM

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OUTPUT SHEET

APPENDIX VI

AGMA STANDARD 220. 02

Following is a reprint of "Tentative AGMA Standard for Rating the Strength of Spur Gear Teeth, " by permission of V. C. Sears, American Gear Manufacturers Association.

FOREWORD

This standard is for rating tht strength of spur gear teeth. It contains the following:

BASIC RATING FORMULA

This section enumerates the factors iwwn ro affect strength. Numerical values are presented (or those factors which have been evaluated by analytical means, test results or field experience*. Suggestions are made for the factors which are not now capable of being expressed accurately. New knowledge and more definite measurement of these parameters will continually necessitate revisions and improvements.

In addition to the above, it ia contemplated to publish design practices, such as AGMA 220.02A, having specific application under the heading of:

DESIGN PRACTICES FOR SPECIALIZED APPLICATIONS

It is recognized that it is sometimes desirable to provide simplified design practice data applicable to a specialized field of application. These individual design practices will enable enclosed speed reducer, mill gear, aircraft or other specialized product designers to record the modifications and limitations they wish to use.

Basic data illustrating the coordination of rating for all types of gears is contained in Tentative Information Sheet AGMA 22'.01, "Strength of Spur, Helical, Herringbone and Bevel Gear Teeth.".

The first draft of the revision to this standard was prepared by the committee in September, 19^5. It was approved by the AGMA membership as of April 7, 196}.

Tables or other self-supporting sections may be quoted or extracted in their entirety. Credit lines should read; "Extracted from AGMA Standard /or Rating the Strength of Spur Gear Teeth (ACMA 220.02), with the permission of the publisher, the American Gear Manufacturers Association, One Thomas Circle, Washington, D. C. 20005".

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W. Coleman, Gleason Works, Rochester, New York

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I. Koenig, Hewitt-Robins, Inc., Chicago, Illinois

C. F. Schwan, Reliance Electric & Enyineering Co., Cleveland, Ohio

J. C. Straub, Wheelabrator Corp., Mishawaka, Indiana

F. A. Thoma, De Laval Turbine, Inc., Trenton, New Jersey

N. A. Wilson, Morgan Construction Co., Worcester, Mass.

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AGMA Standards and related publications represent minimum or average data, conditions or application. They are subject to constant improvement, revision or withdrawal as dictated by experience. Any person woo refers to AGMA technical publications should satisfy himself that he has the latest information available from the Association on the subject matter.

TENTATIVE AGMA STANDARD STRENGTH OF SPUR GEAR TEETH

Basic Rating Formula

1.1 This standard presents the fundamental foimulas for the strength of spur gear teeth. It includes all of the factors which are known to affect gear tooth strength. This standard is based on Information Sheet AGMA 225.01 and is iherefore coordinated with strength ratings for helical and bevel gears.

1.2 Both pinion and rear teeth must be checked for bending strength rating to account for differences in geometry factors, material properties, and numbers of tooth contact cycles under load.

1.3 Other AGMA standards contain numerical values to be used to rate gears for specific applications. These should be consulted when applicable.

1.4 Where no applicable specific AGMA standard is est iblished, numerical values may be estimated for the factors in the *fv* **. imenri¹ formula and an approximate stren >. ' ⁱ ci.**

1.5 The formul-.. ^ ... *\r* **this reference apply to external gears unless oth^rvise noted.**

1.6 The symbols used, wherever applicable, conform to Standard AGMA 111.03 "Letter Symbols for Gear Engineering" (ASA B6.5-1954) and "Letter Symbols for Mechanics of Solid Bodies" (ASA Z10.3-1948).

1. Scope 2. Fundamental Bending Stress Formula

2.1 The basic equation for the bending stress in a gear is calculated as follows:

$$
s_t = \frac{W_t K_o}{K_o} \frac{P_d}{F} \frac{K_s K_m}{J}
$$

Where:

- **£, = calculated tensile bending stress at the root of the tooth, psi**
- **W, = transmitted tangential load at operating pitch dia. lbs. (see Section 4). Load ^K0 = overload factor (see Section 9)** *^Kv* **= dynamic factor (see Section 8)** $\left(p \right)$ = **diametral** pitch

Tooth

\n
$$
\begin{cases}\n r_d = \text{parameter of the line.} \\
 \text{Size} = \text{face width, in.}\n \end{cases}
$$

$$
F = \text{face width, in.}
$$

$$
f = \int K_s = \text{size factor (see Section 7)}
$$

- Stress $\left\{ K_m = \text{Load distribution factor (see Section 6)} \right\}$ **bution /**
	- **>./ = geometry factor (see Section 5)**

t.l.l Noce that the above equation ia divided into **three groups** of **terms, the** first of which is concerned **with the load,** the second with tooth size, and the third with stress distribution.

2.2 The relation of calculated stress to allowable stress is:

$$
s_{t} \leq \frac{s_{at} K_{L}}{K_{R} K_{T}}
$$

Where:

- s_{at} = allowable bending stress for material, psi (see Section 13)
- calculated bending stress, psi **(see** paragraph 2.1)
- *KL* life factor (see Section 11)
- K_T = temperature factor (see Section 12)
- K_R = factor of safety (see Section 10)

3. Fundamental Power Formula

3.1 In preparing handbook data, for gear designs already developed, the following formula can be used to directly calculate the power which can be transmitted by a given gear set:

$$
P_{at} = \frac{n_P d}{126,000 K_o} \frac{K_v}{K_m} \frac{F}{K_s P_d} \frac{J_s}{K_R K_T}
$$

Where:

$$
P_{at} = \text{allowable power of gear set, hp}
$$

 n_p = pinion speed, rpm

d = operating pitch diameter of pinion, in.

4. TrammlUed Tangential Load

4.1 The transmitted tangential load is calculated directly from the power transmitted by ihe gear set. (When operating near a critical speed of the drive, a careful analysis of conditions must be made.) When the transmitted load is not uniform, consideration should be given not only to the peak load and its anticipated number of cycles, but also to intermediate loads and their number of cycles.

4.2 The transmitted tangential load is:

$$
W_t = \frac{33,000 P}{v_t} = \frac{2T}{d} = \frac{126,000 P}{n_p d}
$$

Where:

 $P = power transmitted, hp$

- $T =$ pinion torque, lb.in.
- $v_t =$ pitch line velocity, fpm

5. Geometry Factcr — *J*

5.1 The geometry factor evaluates the shape of the tooth, the position at which the most damaging load is applied, stress concentration due to geometric shape and the sharing of load.

5.2 See Appendix ^A for a further discussion of spur gear geometry factors, and paper AGMA 229.07, "Spur and Helical Gear Geometry Factors."

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5.3 Accurate spur gears develop the most critical stress when load is applied at the highest point of the tooth where a single pair of teeth is carrying all the load. Less accurate spur gears, having errors that prevent two pairs of teeth from sharing the load, may be stressed most heavily when load is applied ar the tip. Figures 1A and IB show the geometry factor for equal addendum involute spur gears of 20 deg and 25 deg pressure angle. In these curves, it is assumed that the theoretical stress concentration factor is not affected seriously by surface finish, plasticity, residual stresses or other factors.

3.3.1 Table ¹ shows the variation in base pitch be* tween the gear and pinion which determines whether or npt load sharing exists in 20 degree pressure angle spur gears.

6. Load Distribution Factor — *^K^m*

6.1 The load distribution factor depends upon the combined effect of:

- **1. misalignment of axes of rotation**
- **2. lead deviations**
- **3. elastic deflection of shafts, bearings and housing.**

6.2 Figures 2 and ³ illustrate misalignment and its effect on load distribution.

6.3 The effect of different rates of spur gear misalignment is shown in Figure 4.

6.4 When the misalignment is knovn, use Figure 4 to select *^Km. ^F^m* **represents the face width having just 100 per cent contact for a given tangential load and alignment error. Generally** *^Fm* **should exceed F.**

6.3 Manufacturers of precision gears with face widths greater than 6 inches generally find it necessary to control misalignment by other means than allowed rates of misalignment. To handle such cases, Table 2 shows appropriate values of *^K .*

6.6 When the estimated or actual misalignment is not known, the *Km* **factor may be obtained from Table 3.**

7. Size Factor K

7.1 The size factor reflects non-uniformity of ma terial properties. It depends primarily on:

- **1) tooth size;**
- **2) diameter of parts;**
- **3) rat'o tooth size to diameter of pan;**
- **4} face width;**
- **3) area of stress pattern;**
- **6) ratio of case depth to tooth size;**
- **7) hardenability and heat treatment of materials.**

7.2 The size factor may be taken as unity for most spur gears provided a proper choice of steel is made for the size of the parts and the case depth or hardness pattern is adequate.

7.3 Standard size factors for spur gear teeth have .not yet been established for cases where there is a detrimental size effect. In such cases a size factor greater than unity should be used.

Table 1 **Limiting Error** in Action for Steel Spur Gear

(Variation in Base Pitch)

***llse upper curves on Fig. ¹ — highest point of single tooth loading.**

****Use lower curve of Fig. ¹ — tip loading.**

8. Dynamic Factor \rightarrow K_v

8.1 The dynamic factor depends on:

- **1) effect of tooth spacing and profile errors.**
- **2) effect of pitch line and rotational speeds.**
- **3) inertia and stiffness of all rotating elements.**
- **4) transmitted** *load* **pet inch of face.**
- **5) tooth stiffness.**

8.2 Figure 5 shows some of the dynamic factors that are commonly used.

Curve No. ¹ — To be used with high precision shaved or ground spur gears where the effect ot toe items listed in paragraph 8.1 are such that no appreciable dynamic load is developed.

Curve No. ² — To be used with high precision shaved or ground spur gears when the items listed in paragraph 8.1 can develop a dynamic load.

Curve No. ³ — To be used with spur gears finished by bobbing or shaping.

8.3 When milling cutters are used to cut the teeth or inaccurate teeth are generated, lower dynamic factors than shown must be used since the dynamic factor reflects the effect of inaccuracies in profile, tooth spacing and runout.

9. Overload Factor K_o

9.1 The overload factor makes allowances for the roughness or smoothness of operation of both the driving and driven apparatus. Specific overload factors can only be established after considerable field experience is gained in a particular application.

9.2 In determining the overload factor, consideration should be given to the fact that many prime movers develop momentary overload torques appreciably greater than those determined by the nameplate ratings of either the prime mover or the driven apparatus.

9.3 In the absence of specific overload factors, the values in Table 4 should be used.

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Table 2 Load Distribution Factor **for** Precision Wide-Face **Spur** Gears — ^K

 ~ 10 m were 1000

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Condition of Support	Face Width, in.			
	2 in. Face and Under	6 in. Face	9 in. Face	16 in. Face and Over
Accurate mountings, low bearing clearances, minimum elastic deflection, precision gears	1.3	1.4	1.5	1.8
Less rigid mountings, less accurate gears, contact across full face	1.6	1.7	1.8	2.0
Accuracy and mounting such that less than full face contact exists	over 2.0			

Table 3 Load Distribution Factor — *K.*

¹ Note that this table is for speed decreasing drives only. For speed increasing drives add

0.01
$$
\left(\frac{N_G}{N_P}\right)^2
$$
 to the factors in Table 4.

Where:

$$
N_P =
$$
 number of teeth in the piano

 N_G = **number** of **teeth** in the **gear.**

9.4 Service factors have been established where field data is available for specific applications. These service factors include not only the overload factor, but also the life factor and factor of safety. Service factors for many applications are listed in other AGMA Standards, and should be used whenever available. If a specific service factor is used in place of the overload factor K_{0} , use a value of 1.0 for K_R and K_L .

10. **Factor** of **Safety** \longrightarrow K_P

10.1 The factor of safety is introduced in this equation to offer the designer an opportunity to design for high reliability or, in some instances, to design for a calculated risk. Table 5 shows a suggested list of factors of safety to be applied to the fatigue strength of the material rather than to the tensile strength. For this reason, the values are much smaller than customarily used in other branches of machine design.

10.1.1 Failure in the following table does not mean an immediate failure under applied load, but rather a shorter life than the minimum specified.

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Table 5 Factors of Safety — K_R

Fatigue Strenctli

10.2 Table 6 shows safety fnctors to be applied to the yield strength of the material. These values must be applied to the maximum peak load to which the gears are subjected.

Table 7 Life Factor $-K_L$

'case carburized 55*63 *R,*

Table 6 **Factors** of **Safety** $- K_R$

Yield Strencth

11. Life **Factor** — K_L

11.1 The life factor adjusts the allowable loading for the required number of cycles. Table 7 shows typical values, for use with the allowable stress values of Figure 6 or Table 8.

12. Temperatwe Factor — *^KT*

12.1 When gears operate at oil or gear blank temperatures not exceeding 250 degree F, K_T is generally taken as unity. In some instances, it is necessary to use a *^KT* value greater than unity **for** case carburized gears at a temperature above 160 degree F. One basis of correction is:

$$
K_T = \frac{460 + T_F}{620}
$$

Where:

 T_F = The peak operating oil temperature in degrees Fahrenheit.

13. Allowable Bendlm Stress —

s_{at} and s_{av}

13.1 An allowable design bending stress for unity application tfactor and 10 million cycles of load application is detetipined by field experience, for each material and condition of that material. This stress is designated *sat.*

13.2 The allowable stress for gear materials varies considerably with heat treatment, forging or casting practice, material composition, and with various surface treatments.

13.3 Frequently, shot peening permits a higher allowable stress to be used.

13.4 The allowable fatigue design stress for steel is shown in Figure 6. These values are suggested for general design purposes.

13.3 The allowable fatigue design stress for surface hardened steel and other materials is shown in Table 8.

13.6 Use 70 pet cent of the *sat* **values for idler gears and other gears where the teeth are loaded in both directions.**

13.7 When the gear is subjected to infrequent momentary high overloads the maximum allowable **stress is determined by the allowable yield properties rather than rhe fatigue strength of the material.** This stress is designated as s_{av} . Figure 7 shows **suggested values! for allowable yield strength, for through hardened steel. In these cases the design should be checked to make :ertain that the teeth are not permanently deformed. When yield is the governing stress, the stress concentration factor is sometimes considered ineffective.**

 λ

Table 8 Allowable Fatigue Design Stress — *sat*

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FIG. 2 EXAMPLE OF A PINION AND GEAR MISALIGNED UNDER NO LOAD. TEETH CONTACT AT LEFT HAND END AND ARE OPEN AT RIGHT HAND END.

FIG. 3 LOAD DISTRIBUTION ACROSS FACE WIDTH FOR VARIOUS CONTACT CONDITIONS

SPUR GEAR LOAD DISTRIBUTION FACTOR $-K_m$ **FIG. 4**

FIG. 6 ALLOWABLE FATIGUE STRESS FOR STEEL GEARS-S_{at}

ALLOWABLE YIELD STRENGTH - Say $FIG. 7$

APPENDIX A

SPUR GEAR GEOMETRY FACTOR

1. Geometry Factor

$$
J = \frac{Y}{K_f m_N}
$$

Where:

- *J* **= geometry factor**
- $Y = \text{tooth form factor}$
- *K,* **= stress correction factor**
- m_N = **load** sharing ratio
	- **2. Tooth Form Factor -**

2.1 ^V is detervined for the most critical position of load application. This is at the tip of the tooth when load sharing does not exist and usually at the highest load position for single tooth contact when load sharing does exist.

2.2 The ^V factor, which considers both the tangential (bending) and radial (compressive) components of the load is calculated as follows:

$$
Y = \frac{1}{\cos \phi_L} \left(\frac{1.5}{x} - \frac{\tan \phi_L}{t} \right)
$$

Where:

$$
\phi = \text{pressure angle}
$$

2.3 Use the following procedure to determine *Y.*

2.3.1 Lay out a generated tooth profile at a scale of one diametral pitch *(Pj),* **as shown in Figures Al end A2.**

2.3.2 When load sharing exists (Fig. *M),* **lay a scale tangent to the base circle and locate the position where the distance from thi- intersection point with the pitch circle to (he intersection point with the profile equals** distance z_c – inches (obtained **from Figures A3 or A4). This locates line** *aa.*

2.3.3 When load sharing does not exist (Fig. A2), draw line *aa* **through point** *p* **and tangent to the base circle. This locates line** *aa.*

2.3.4 Through point / draw line *bb* **perpendicular to the tooth center line. The included angle between** lines *aa* and *bb* is angle p_i .

2.3.5 Draw line *cde* **tangent to the tooth fillet radius (»,) at** *c,* **intersecting line** *bb* **at** *d* **and the tooth center line at c so that** *cd* **=** *de.*

2.3.6 Draw line *fe.*

2.3.7 Through point *e* **draw a line perpendicular to** *fe,* **intersecting the tooth center line at** *n.*

2.3.8 Through point *e,* **draw a line** *me* **perpendicular to the tooth center line.**

2.3.9 Measure the following from the tooth layout:

 $mn = X -$ **inches** $me = t/2 - inches$ **angle** *4iL*

2.3.10 Calculate form factor *Y.*

APPENDIX A

S.l Screa« correction **factor depeoda** on:

3. Biress Correction Factor \rightarrow K ,

- 1) effective stress concentration;
- 2) location of load;
- 3) plasticity effects;
- 4) residual stress effects;
- 5) material composition effects;
- 6) surface finish:
	- a) resulting from gear production
	- b) resulting from service.
- 7) Hertz stress effects;
- 8) size effect;
- 9) end of tooth effects.

3.2 The following stress correction factor is that of Dolan and Broghamer and only includes the effects of items ¹ and 2.

$$
K_f = H + \left(\frac{t}{r_f}\right)^f + \left(\frac{t}{b}\right)^L
$$

Where:

H, *J* and ^L are obtained from Table A-l. For other pressure angles, the values of *H, J* and L can be obtained by interpolation and extrapolation.

- \boldsymbol{h} $=$ distance /m measured from the layout — inches
- *2* - distance *me* measured from the layout — inches

$$
r_1 = r_1 + r_T
$$

Where:

 r_T edge radius of tool — inches. For a cutter with chamfered teeth, take $r_T = 0$.

$$
= \frac{b_1^2}{R_o + b_1}
$$

Where:

 r_1

 R_{α} = the relative radius of curvature of the pitch circle of the gear and the pitch line or pitch circle of the generating tool. For generation by a rack or hob, *R0* equals the pitch radius *R* of the gear being generated. For generation by a pinion-shaped cutter, $1/R_o$ = $1/R$ + $1/R_c$, where R_c is the pitch radius of the cutter.

$$
b_1 = b - r_T
$$

Where:

= dedeudum — inches \boldsymbol{b}

3.3 Plasticity reduces the effect of stress concentration and is partially measured by the life factor of Table 7. When more accurate data such as notch sensitivity values are available, they may be used,

3.4 If more exact values for the stress correction factor are available, they may be used.

4. Load Sharing Ratio $\frac{m_N}{m_N}$

4.1 Load sharing ratio is influenced by profile contact ratio.

4.2 The most critical position of spur gear load application normally occurs when only one tooth is in contact.

Therefore, $m_N = 1.0$.

TIP LOADING FIG. A-2 TOOTH FORM FACTOR LAYOUT WITHOUT LOAD SHARING

FIG. A-3 Z_c – FOR HIGHEST POINT OF SINGLE TOOTH CONTACT WHEN LOAD SHARING EXISTS BETWEEN TEETH

FIG. A-4 ^Zc-FOR HIGHEST POINT OF SINGLE TOOTH CONTACT WHEN LOAD SHARING EXISTS BETWEEN TEETH

The user of this Standard (AGMA 220.02) may find these other AGMA Standards of value as reference data:

Number Title

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^A more complete list *of* **AGMA** Standards published by the American **Gear** Manufacturers Association is **available** upon request.

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