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TRANSLATION

DETERMINATION OF THE PROFILE OF LEAST RESISTANCE OF AN ANNULAR WING

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AIR FORCE SYSTEMS COMMAND

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DETERMINATION OF THE PROFILE OF LEAST RESISTANCE OF AN ANNULAR WING

BY: B. I. Borisov

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DETERMINATION OF THE PROFILE OF LEAST RESISTANCE OF AN ANNULAR WING

B. I. Borisov

A thin axisymmetric wing in a supersonic flow at velocity \mathbf{V}_{0} is examined. We start from the linearized equation for the velocity potential:

$$(M^2-1)\frac{\partial^2 q}{\partial \bar{z}^2} = \frac{\partial^2 q}{\partial \bar{z}^2} + \frac{1}{\bar{z}}\frac{\partial q}{\partial \bar{z}}$$

We introduce dimensionless variables

$$x = \frac{\bar{x}}{\bar{r}_0 + M^2 - 1}, \quad r = \frac{\bar{r}}{\bar{r}_0} \tag{1}$$

In these variables we will have

$$\frac{\partial^2 \varphi}{\partial r^2} = \frac{\partial^2 \varphi}{\partial r^2} + \frac{1}{r} \frac{\partial \varphi}{\partial r}.$$
 (2)

The boundary conditions for this equation are the following: when $\mathbf{r}=\mathbf{1}$ we have

$$\frac{dq}{dr} = r_{ii}V_{ii}\beta_{ii}(x) \quad \text{on the outer surface of the body,}$$

$$\frac{dq}{dr} = r_{ii}V_{ii}\beta_{ii}(x) \quad \text{on the inner surface of the body;}$$
(3)

when $r = 1 \pm x$ potential $\varphi = 0$.

Here $\beta_e(x)$, $\beta_1(x)$ are the angles between axis ox and the tangents to the outer and inner surface of the body at the given point.

The solution is sought in the form

$$\psi = \overline{r_0} V_0 \int_0^{\pi} \beta_r (x - \tau) \psi_1 (r, \tau) d\tau \qquad \text{(outer problem)}$$

$$\psi = \overline{r_0} V_0 \int_0^{\pi} \beta_i (x - \tau) \psi_2 (r, \tau) d\tau \qquad \text{(inner problem)}$$

Calculating using the method of characteristics, the functions ψ_1 and ψ_2 were found on the surface of the body

$$\psi_1(1,x) = -1 + 0.4195x - 0.0795x^2,$$

$$\psi_2(1,x) = 1 + 0.209x + 0.651x^2,$$
(5)

From the Bernoulli equation we have the following formula for pressure:

$$p = p_{\bullet} - V_{e} a_{ij} \frac{\partial \tau}{\partial \bar{x}}. \tag{6}$$

We will examine the symmetrical profile of an annular wing of length 1 (Fig. 1);

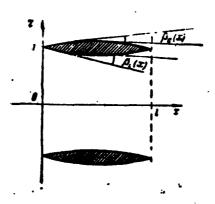


Fig. 1.

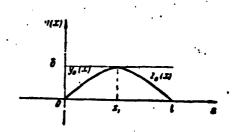


Fig. 2.

 $\beta_c(x)^* = -\beta_l(x) := \beta(x).$

From Formula (6) it is easy to obtain the drag

$$Q = 2\pi \frac{V_{0,m}^2}{|M^2-1|} \int_0^1 \Im(x) \frac{d}{dx} \int_0^x \Im(x-\tau) \psi(\tau) d\tau dx,$$

where $\psi(\tau)$ designates the function $\psi(\tau) = \psi_2(1, \tau) - \psi_1(1, \tau)$.

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Thus, the drag force is proportional to the integral

$$I = \int_{0}^{\pi} \beta(x) \frac{d}{dx} \int_{0}^{\pi} \beta(x-\tau) \dot{\gamma}(\tau) d\tau dx.$$

Let $\beta(x) = y'(x)$; then y(x) will be the equation of the profile in the new coordinates (Fig. 2). On the strength of this, integral I can be reduced to the form

$$I = \int_{0}^{1} \left[y'^{2}(x) \dot{\gamma}_{0} + y'(x) \int_{0}^{\pi} y'(\tau) \dot{\gamma}'(x - \tau) d\tau \right] dx. \tag{7}$$

where $\psi_0 = \psi(0)$.

We will seek the minimum of this integral under the condition $y(x_1) = \delta$, that is, with a given thickness of the profile 2δ . We will write the equation of line y(x) as

$$y(x) = \frac{y_0(x) \text{ when } 0 < x \le x_1}{z_0(x) \text{ when } x_1 \le x \le l.}$$
 (8)

After simplifications the first variation of integral &I will have the form

$$\begin{aligned}
\hat{v}_{i} &= \left[-y_{i0}^{2} \dot{\gamma}_{0} + z_{i0}^{2} \dot{\gamma}_{0} \right]_{x_{i}} \delta x_{1} - \int_{0}^{x} \left[2 \dot{\gamma}_{0} y_{0} + \frac{d}{dx} \int_{0}^{x} y_{0} \dot{\gamma}' (x - \tau) d\tau + \frac{d}{dx} \int_{x}^{x_{i}} y_{0} \dot{\gamma}' (x - \tau) d\tau + \frac{d}{dx} \int_{x_{i}}^{x_{i}} z_{0}' \dot{\gamma}' (\tau - x) d\tau \right] \delta y dx - \\
&- \int_{x_{i}}^{x_{i}} \left[2 \dot{\gamma}_{0} z_{0}^{2} + \frac{d}{dx} \int_{x_{i}}^{x_{i}} z_{0}' \dot{\gamma}' (x - \tau) d\tau + \frac{d}{dx} \int_{x_{i}}^{x_{i}} z_{0}' \dot{\gamma}' (\tau - x) d\tau + \frac{d}{dx} \int_{x_{i}}^{x_{i}} z_{0}' \dot{\gamma}' (x - \tau) d\tau \right] \delta y dx = 0.
\end{aligned} \tag{9}$$

The necessary condition of the extremum is $\delta I = 0$. We will narrow the class of permissible curves, having fixed point (x_1, y_1) and line $z_0(x)$. Then condition $\delta I = 0$ will be the same as equating the first integral in Formula (9) to zero. Similarly, the necessary condition of the extremum with variation only of $z_0(x)$ will be the

equating of the second integral to zero.

Hence,

$$|-y_0(y_0+z_0(y_0))| dx_1=0.$$

Thus we have the necessary condition of the extremum

$$2\dot{\varphi}_{0}y_{0} := \frac{d}{dx} \int_{0}^{x} y_{0}\dot{\gamma}'(x-z) dz + \frac{d}{dx} \int_{x}^{x} y_{0}\dot{\gamma}'(z-x) dz + \frac{d}{dx} \int_{x}^{x} z_{0}\dot{\gamma}'(z-x) dz = 0,$$

$$2\dot{\varphi}_{0}z_{0} + \frac{d}{dx} \int_{x}^{x} z_{0}\dot{\gamma}'(x-z) dz + \frac{d}{dx} \int_{x}^{x} z_{0}\dot{\gamma}'(z-x) dz + \frac{d}{dx} \int_{x}^{x} z_{0}\dot{\gamma}'(z-x) dz + \frac{d}{dx} \int_{0}^{x} y_{0}\dot{\gamma}'(x-z) dz = 0,$$

$$y_{0}'|_{x_{1}} = z_{0}'|_{x_{1}}$$

and boundary conditions

$$y_0(0) = 0, \quad y_0(x_1) = \delta, \quad z_0(x_1) = \delta, \quad z_0(l) = 0.$$
 (11)

We substitute in (10) the well-known function

$$\psi(x) = 0.73 x^2 - 0.21 x + 2.$$

The solution of System (10) with Boundary Conditions (11) is as follows:

$$y_0 = \frac{\delta}{\sin \frac{kl}{2}} \sin kx$$
, $z_0 = \frac{\delta}{\sin \frac{kl}{2}} \sin k(l-x)$, $x_1 = \frac{\delta}{2}$.

where k = 0.85.

Converting to dimensional coordinates by Formulas (1) and causing the radius of the annular wing r_0 to tend toward infinity we obtain at the limit

$$y_0 = \frac{\delta}{\frac{1}{2}}\overline{x}, \quad z_0 = \frac{\delta}{\frac{1}{2}}\overline{(l-\overline{x})},$$

that is, a rhomboid profile which coincides with the well-known

solution in the plane problem.

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Department of Wave- and Gasdynamics

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