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Approved for Public Release
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TARGET SYSTEM GIVING ACCURACY AND ENERGY

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STATEMENT OF GOVERNMENT INTEREST

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The invention described herein may be manufactured and used by or for the Government of the United States of America for governmental purposes without payment of any royalties thereon or therefor.

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BACKGROUND OF THE INVENTION

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(1) Field of the Invention

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The invention relates to a target that locates and quantifies the impact of a projectile on a target. This invention more particularly relates to a range and target system for supercavitating underwater projectiles.

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(2) Description of the Prior Art

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Until recently, it has not been feasible to shoot bullets underwater. Currently, however, supercavitation drag reduction allows bullets to be fired underwater at velocities sufficiently high to inflict damage on a target.

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United States Patent No. 5,778,725 discloses a prior art range for testing these underwater supercavitating munitions.

1 The prior art system includes a gun mount aiming the gun along a
2 nominal trajectory. Baffle plates, each having an aperture
3 therethrough, are mounted along the nominal trajectory of the
4 range. Witness screens and motion detectors are used to note
5 passage of the projectile. A bullet receptacle is aligned to
6 receive the projectile. The components are placed in the body
7 of liquid in alignment with each other such that the projectile
8 fired from the gun passes through the apertures in the baffle
9 plates, through the witness screens, through the sensors, and
10 into the receptacle. The sensors measure the projectile's
11 position as a discrete function of time. The witness screens
12 provide an indication as to the projectile's trajectory and
13 energy level. The receptacle retains the projectile for
14 retrieval and examination. This system requires the presence of
15 sensors along the nominal trajectory of the projectile. Witness
16 screens require replacement after each projectile is fired.

17 In view of the prior art, it is now deemed desirable to
18 have a target for such test range wherein impact energy and
19 accuracy can be measured. Existing ranges utilized in testing
20 atmospheric projectiles do not provide an estimate of impact
21 energy. Because underwater projectiles transit a high drag
22 environment, impact energy is of primary importance in assessing

1 the ability of the projectile to destroy a target. Accuracy and
2 reliability are determined by measuring the impact location.

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SUMMARY OF THE INVENTION

5 It is, therefore, an object of the invention to provide a
6 target for a test range that includes an impact plate having at
7 least three strain sensors positioned on the plate. The strain
8 sensors are preferably piezoelectric sensors. The sensors are
9 connected to a data acquisition board for receiving a signal
10 from each sensor upon impact of a projectile on the plate. The
11 data acquisition board is joined to a processor for calculating
12 impact location and energy. Optionally multiple sensors can be
13 provided having different orientations for accounting for
14 different strain components in the plate.

15 With the above and other objects in view, as will
16 hereinafter appear, a feature of the present invention is the
17 provision of a target that can calculate both impact energy and
18 accuracy upon impact of a projectile.

19 The above and other features of the invention, including
20 various novel details of construction and combinations of parts,
21 will now be more particularly described with reference to the
22 accompanying drawings and pointed out in the claims. It will be
23 understood that the particular device and method embodying the

1 invention are shown by way of illustration only and not as
2 limitations of the invention. The principles and features of
3 this invention may be employed in various and numerous
4 embodiments without departing from the scope of the invention.

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6 BRIEF DESCRIPTION OF THE DRAWINGS

7 Reference is made to the accompanying drawing in which is
8 shown an illustrative embodiment of the invention, from which
9 its novel features and advantages will be apparent.

10 The FIG. shows a target of the current invention.

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12 DESCRIPTION OF THE PREFERRED EMBODIMENTS

13 A target 10 of the current invention is shown in FIG.
14 Target 10 is a plate 12 having sensors 14A and 14B positioned
15 thereon. Plate 12 is preferably a steel plate having sufficient
16 thickness to absorb the energy of a projectile of interest. The
17 dimensions of plate 12 are calculated to account for the
18 expected accuracy of the projectile. Sensors 14A and 14B are
19 positioned about a region of expected impact 16 on plate 12.
20 Perpendicular sensors 14A are positioned to measure the strain
21 created from the impact perpendicular to the wave front.
22 Parallel sensors 14B are positioned to measure the strain
23 created parallel to the impact wave front. Perpendicular

1 sensors 14A produce higher amplitudes for low frequency signals,
2 and the parallel sensors 14B will produce higher amplitudes for
3 the high frequency component of the signals. The sensor
4 orientation shown having both kinds of sensors provides the best
5 results by retaining high and low frequency content. Sensors
6 14A and 14B are preferably lead-zirconium-titanate (PZT) strain
7 sensors; however, other electrical strain sensors could be used.

8 A multichannel data acquisition board 18 is joined to
9 sensors 14A and 14B by cables 20. Data acquisition board 18
10 includes a plurality of Analog to Digital converters for
11 converting received analog signals into digital signals which
12 can be analyzed by a processor 22. Board 18 can be a data
13 acquisition board such as the National Instruments 6115 data
14 acquisition board or the like. Multiple boards can be receive
15 all channels of data. Processor 22 can be a well known industry
16 standard processor having sufficient speed to capture the data.
17 The data received by the data acquisition board gives the
18 arrival time information for the hyperbolic tracking algorithm
19 discussed hereinafter. The hyperbolic tracking algorithm
20 determines the impact location of the projectile.

$$21 \quad (X - x_1)^2 + (Y - y_1)^2 = C * (t - t_1)^2 \quad (1)$$

$$22 \quad (X - x_2)^2 + (Y - y_2)^2 = C * (t - t_2)^2 \quad (2)$$

1 $(X - x_3)^2 + (Y - y_3)^2 = C * (t - t_3)^2$ (3)

2 where:

3 (x_1, y_1) , (x_2, y_2) , and (x_3, y_3) are the locations of the sensors;

4 C is the wave speed of steel (5,050 m/s);

5 X and Y are impact locations;

6 t is the time of impact; and

7 t_1 , t_2 , and t_3 are the times the impact is detected at the

8 respective sensor.

9 Equations (1), (2) and (3) are solved for X and Y by the
10 substitution method until convergence within a predetermined
11 tolerance value. Other solutions methods can be used within the
12 scope of this invention.

13 Impact energy is calculated by experimentally determining a
14 sensor output amplitude/energy transfer function. The processor
15 22 can apply the transfer function to give the impact energy.
16 The calculated impact energy and location can be provided to the
17 user by a display or saved in a file.

18 There is thus provided a smart target for an underwater gun
19 test range. The target has sensors and instrumentation that
20 allow the calculation of impact energy and accuracy. The target
21 is especially adapted to an underwater test range for use with
22 supercavitating projectiles.

1 It is to be understood that the present invention is by no
2 means limited to the particular construction herein disclosed
3 and/or shown in the drawings, but also comprises any
4 modifications or equivalents within the scope of the claims.

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TARGET SYSTEM GIVING ACCURACY AND ENERGY

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ABSTRACT OF THE DISCLOSURE

6 A target for a test range includes an impact plate having
7 at least three strain sensors positioned on the plate. The
8 sensors are connected to a data acquisition board for receiving
9 a signal from each sensor upon impact of a projectile on the
10 plate. The data acquisition board is joined to a processor for
11 calculating impact location and energy. Optionally multiple
12 sensors can be provided having different orientations for
13 accounting for different strain components in the plate.