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ELECTROMAGNETIC WAVE PROPAGATION SCHEME

STATEMENT OF GOVERNMENT INTEREST

BACKGROUND OF THE INVENTION

1. Field of the Invention

The present invention generally relates to an electromagnetic wave propagation scheme for use with sensors on undersea vehicles.

2. Description of the Related Art

Undersea vehicles, such as submarines, autonomous undersea vehicles, and autonomous undersea platforms, typically use sensors that are external to the pressure hull of the undersea vehicles. Such sensors are used to measure or detect pressure, acceleration, magnetic fields and acoustic energy. One such sensor is known as a MEMS (Micro Electronic Mechanical System) sensor. MEMS sensors are miniaturized sensors that are very adaptable to the undersea environment.

1 waveguide are defined by the liquid medium and the hull outer
2 surface. In one embodiment, the electrically conductive member
3 comprises microstrip. In another embodiment, the electrically
4 conductive member comprises stripline. In a further embodiment,
5 the electrically conductive member comprises metal tape. In one
6 embodiment, the apparatus further comprises a parasitic radiator
7 embedded in the dielectric material and in electrical signal
8 communication with the waveguide. In one embodiment, the
9 dielectric material is formed by a Special Hull Treatment ("SHT")
10 made from a commonly used material such as dura which is well
11 known in the art.

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BRIEF DESCRIPTION OF THE DRAWINGS

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The figures are for illustration purposes only and are not drawn to scale. The invention itself, however, both as to organization and method of operation, may best be understood by reference to the detailed description which follows taken in conjunction with the accompanying drawings in which:

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FIG. 1 is a block diagram of a communication system that incorporates the electromagnetic wave propagation channel of the present invention;

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FIG. 2 is a partial cross-sectional view of the electromagnetic wave propagation channel of the present invention; and

1 FIG. 3 is a perspective view, in diagrammatic form, of the
2 electromagnetic wave propagation channel of the present invention
3 embodied in the skin of an undersea vehicle.

4
5 DESCRIPTION OF THE PREFERRED EMBODIMENT

6 In describing the preferred embodiments of the present
7 invention, reference will be made herein to FIGS. 1-3 of the
8 drawings in which like numerals refer to like features of the
9 invention.

10 As used herein, the terms "electromagnetic wave" and
11 "electromagnetic signals" are used interchangeably and are
12 construed to have the same meaning. As used herein, the terms
13 "hull" and "pressure hull" includes the hulls of ocean-going
14 vessels, submarines, undersea or underwater vehicles, motor
15 boats, and pleasure craft. As used herein, the term "liquid
16 medium" includes oceans, lakes, and rivers. Therefore, although
17 the ensuing description is in terms of the present invention
18 being used in conjunction with an undersea vehicle, it is to be
19 understood that the present invention can be used with almost any
20 type of vessel configured for travel through a liquid medium.

21 Referring to FIG. 1, there is shown communication system 10
22 that utilizes the electromagnetic wave propagation channel of the
23 present invention. Communications system 10 generally comprises
24 transceiver 12, electromagnetic wave propagation channel 14 of

1 the present invention, parasitic radiator 15 and sensor network
2 16.

3 Transceiver 12 includes circuitry for generating and
4 transmitting an encoded R.F. (radio frequency) or microwave
5 signal. The encoded signal contains data that defines
6 interrogation and/or read signals that are used to address
7 individual sensors in sensor network 16. In a preferred
8 embodiment, the encoded signal contains data that defines a code
9 that corresponds to a particular sensor thereby allowing each
10 sensor to be individually addressed. The encoded signal generated
11 by transceiver 12 also includes a signal component that powers
12 the sensors in sensor network 16. Transceiver 12 also includes
13 processing circuitry for processing sensor data detected by the
14 sensors of sensor network 16.

15 In one embodiment, transceiver 12 includes circuitry for
16 formatting sensor data signals into a format that is suitable for
17 processing by a central processor (not shown) that is typically
18 located within the undersea vehicle. In one embodiment,
19 transceiver 12 includes circuitry for converting the formatted
20 sensor data signals into optical signals. In such an embodiment,
21 transceiver 12 includes a fiber optic penetrator (not shown) that
22 functions as an interface between transceiver 12 and the central
23 processor (not shown) within the undersea vehicle.

24 Referring to FIGS. 1, 2 and 3, electromagnetic wave
25 propagation channel 14 is in electrical signal communication with

1 transceiver 12 and parasitic radiator 15. Wave propagation
2 channel 14 utilizes pressure hull 18 of the undersea vehicle.
3 Specifically, wave propagation channel 14 generally comprises
4 outer surface 18a of pressure hull 18, a coating of dielectric
5 material 22 that is disposed over outer surface 18a, and
6 electrically conductive member 24 that is embedded within
7 dielectric material 22. Dielectric material 22 has a
8 predetermined dielectric constant and insulates electrically
9 conductive member 24 from the liquid medium 26. Dielectric
10 material 22 has an outer surface 27 that is exposed to liquid
11 medium 26. When hull 18 is disposed in liquid medium 26 and
12 liquid medium 26 contacts outer surface 27 of dielectric material
13 22, a waveguide is formed by liquid medium 26, dielectric
14 material 22, electrically conductive member 24, and hull outer
15 surface 18a. The signals transmitted by transceiver 12 propagate
16 through the waveguide. The boundaries of the aforementioned
17 waveguide are hull outer surface 18a and liquid medium 26. The
18 electromagnetic wave propagation through dielectric material 22
19 emulates the properties and characteristics of a Goubau wave
20 which is well known in the art.

21 In one embodiment, the coating of dielectric material 22 has
22 a thickness between one (1) and three (3) inches. However,
23 dielectric material 22 can be configured to have a thickness less
24 than one (1) inch or more than three (3) inches. In one
25 embodiment, dielectric material 22 is formed by a process known

1 in the art as Special Hull Treatment ("SHT"). In such a process,
2 conductive member 24 is inserted into dielectric material 22 as
3 the dielectric material is being poured or disposed over outer
4 surface 18a. However, it is to be understood that other suitable
5 processes and materials may be used to form the coating of
6 dielectric material 22.

7 In one embodiment, conductive member 24 is configured as
8 microstrip which is well known in the art. In another
9 embodiment, conductive member 24 is configured as stripline which
10 is well known in the art. In a further embodiment, conductive
11 member 24 is configured as metal tape.

12 In a preferred embodiment, the properties, dimensions and
13 characteristics of dielectric material 22 and conductive member
14 24 are selected to effect efficient propagation of
15 electromagnetic waves or signals at predetermined R.F. or
16 microwave frequencies.

17 Preferably, the environmental conditions (i.e. pressure,
18 temperature, etc.) to which wave propagation channel 14 will be
19 exposed are considered when determining the dimensions and
20 properties of conductive member 24 and when selecting the
21 particular dielectric material so as to avoid significant
22 impedance mismatches.

23 Parasitic radiator 15 is embedded in dielectric material 22
24 and is in electrical signal communication with wave propagation
25 channel 14. Parasitic radiator 15 radiates the signals generated

1 by transceiver 12 through dielectric material 22. Parasitic
2 radiator 15 may be realized by any one of a number of well known
3 suitable techniques or schemes.

4 Sensor network 16 comprises a plurality of sensors that are
5 arranged in an array, grid, plane or any other suitable
6 configuration. Sensor network 16 further comprises a transceiver
7 that is configured to receive and decode the signals radiated
8 from parasitic radiator 15. Each sensor may be configured as a
9 MEMS sensor described in the foregoing description. However,
10 other suitable sensors may be used as well. The transceiver of
11 sensor network 16 generates and transmits an encoded R.F. or
12 microwave signal that contains data that represents the sensor
13 output data. The encoded signals transmitted by the transceiver
14 of sensor network 16 are received by parasitic radiator 15. As a
15 result, the encoded signals generated by the transceiver of
16 sensor network 16 propagate through electromagnetic wave
17 propagation channel 14 and are received by transceiver 12.
18 Transceiver 12 decodes and processes the received signals and
19 routes the processed signal to the central processor (not shown)
20 within the undersea vehicle.

21 In one embodiment of the invention, each sensor has an
22 inactive operational mode and an active operational mode. When
23 the sensors are in the inactive operational mode, each sensor
24 utilizes energy from the signals generated by transceiver 12 to
25 power the sensor electronic circuitry and/or to charge micro-

1 batteries that power the sensors. When the sensors are in the
2 active operational mode, transceiver module 12 receives the
3 encoded signals generated by the transceiver associated with the
4 sensor network, decodes these signals, formats the decoded
5 signals into a format that is suitable for processing by the
6 central processor (not shown), and converts the formatted signals
7 into optical signals. As described in the foregoing description,
8 the optical signals are routed to the central processor (not
9 shown) via the optical penetrator.

10 In one embodiment of the invention, conductive member 24 is
11 configured as a conductive lattice having a plurality of
12 conductive members 24 that are embedded within and extend
13 throughout the dielectric material 22 so as to form a plurality
14 of waveguides that are in electrical signal communication with
15 each other. This configuration is useful when a plurality of
16 sensor networks are utilized. In such a configuration, each
17 waveguide corresponds to a particular sensor network and
18 transceiver 12 generates and outputs encoded radio frequency
19 signals or microwave signals that contain data that defines
20 particular codes wherein a particular code corresponds to a
21 particular sensor grid and a particular sensor within that sensor
22 grid. This embodiment enables transceiver 12 to interrogate,
23 read or power individual sensors within a particular sensor grid.

24 Useful techniques and schemes for interrogating, powering
25 and reading sensor networks are described in commonly owned and

1 co-pending U.S. Patent Application Serial No. 10/652,084, filed
2 25 August 2003, the disclosure of which is incorporated herein by
3 reference. The techniques and schemes described in the
4 aforementioned pending application may be used in conjunction
5 with the present invention.

6 Although the foregoing description is in terms of the sensor
7 network being embedded in dielectric material 22, it is to be
8 understood that the sensor network can be located on the exterior
9 of the dielectric material 22. In such an embodiment, the
10 interface for coupling the encoded electromagnetic signals
11 generated by transceiver 12 to the input of the transceiver of
12 the sensor network is embedded within the dielectric material 22.

13 Electromagnetic wave propagation channel 14, parasitic
14 radiator 15 and dielectric material 22 cooperate to substantially
15 eliminate the need to use bundles of wires to communicate with
16 the sensors. As a result, the present invention provides a
17 substantial cost savings when a significantly large number of
18 sensors are being used. Furthermore, electromagnetic wave
19 propagation channel 14, parasitic radiator 15 and dielectric
20 material 22 enable transceiver 12 to detect encoded signals from
21 individual sensors regardless of the direction from which these
22 signals emanate. Thus, the present invention allows the sensors
23 to be efficiently, accurately and quickly interrogated and read
24 thereby providing an active laboratory for hydrophone monitoring,

1 platform self-quieting, cancellation of magnetic signatures, and
2 other monitoring and processing activities.

3 The electromagnetic wave propagation channel of the present
4 invention can be used in conjunction with commercially available
5 integrated circuits dedicated to R.F. or microwave communication
6 as well as commercially available DSP (digital signal processor)
7 circuits.

8 While the present invention has been particularly described,
9 in conjunction with a specific preferred embodiment, it is
10 evident that many alternatives, modifications and variations will
11 be apparent to those skilled in the art in light of the foregoing
12 description. It is therefore contemplated that the appended
13 claims will embrace any such alternatives, modifications and
14 variations as falling within the true scope and spirit of the
15 present invention.

ELECTROMAGNETIC WAVE PROPAGATION SCHEME

ABSTRACT OF THE DISCLOSURE

6 An apparatus for effecting propagation of electromagnetic
7 waves, comprising a hull outer surface, a dielectric material
8 disposed over the hull outer surface, and an electrically
9 conductive member embedded within the dielectric material. When
10 a liquid medium contacts the dielectric material, the liquid
11 medium, the hull outer surface, the dielectric material and the
12 electrically conductive member cooperate to provide a waveguide
13 through which electromagnetic waves can propagate wherein the
14 boundaries of the waveguide are defined by the liquid medium and
15 the hull outer surface. A sensor network can be provided within
16 the dielectric material for receiving power and transmitting
17 information.

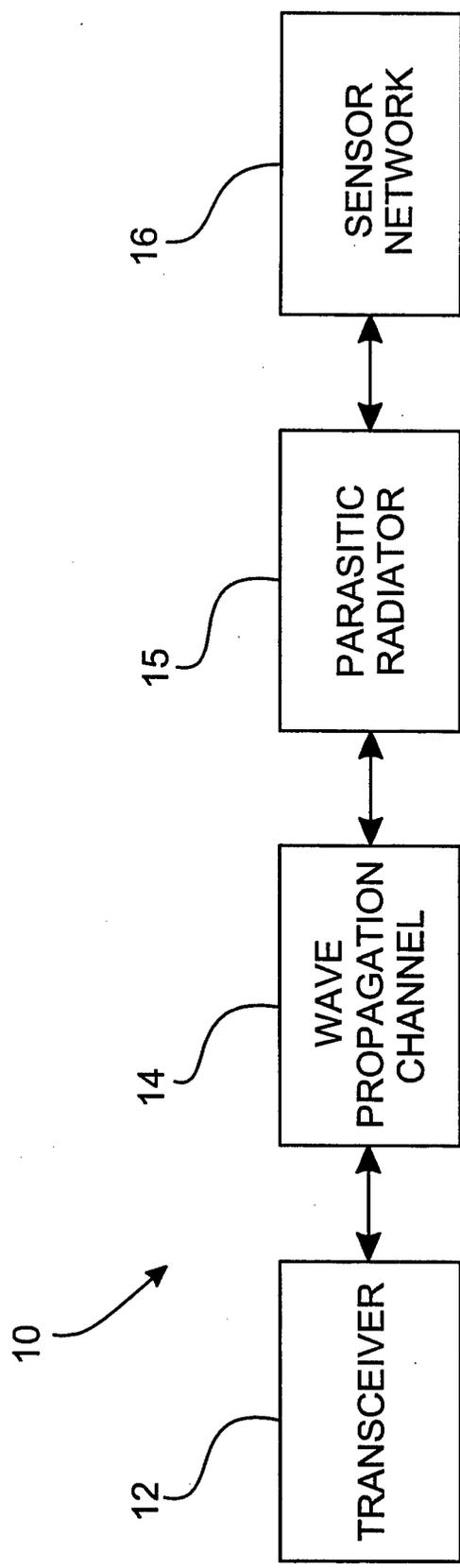


FIG. 1

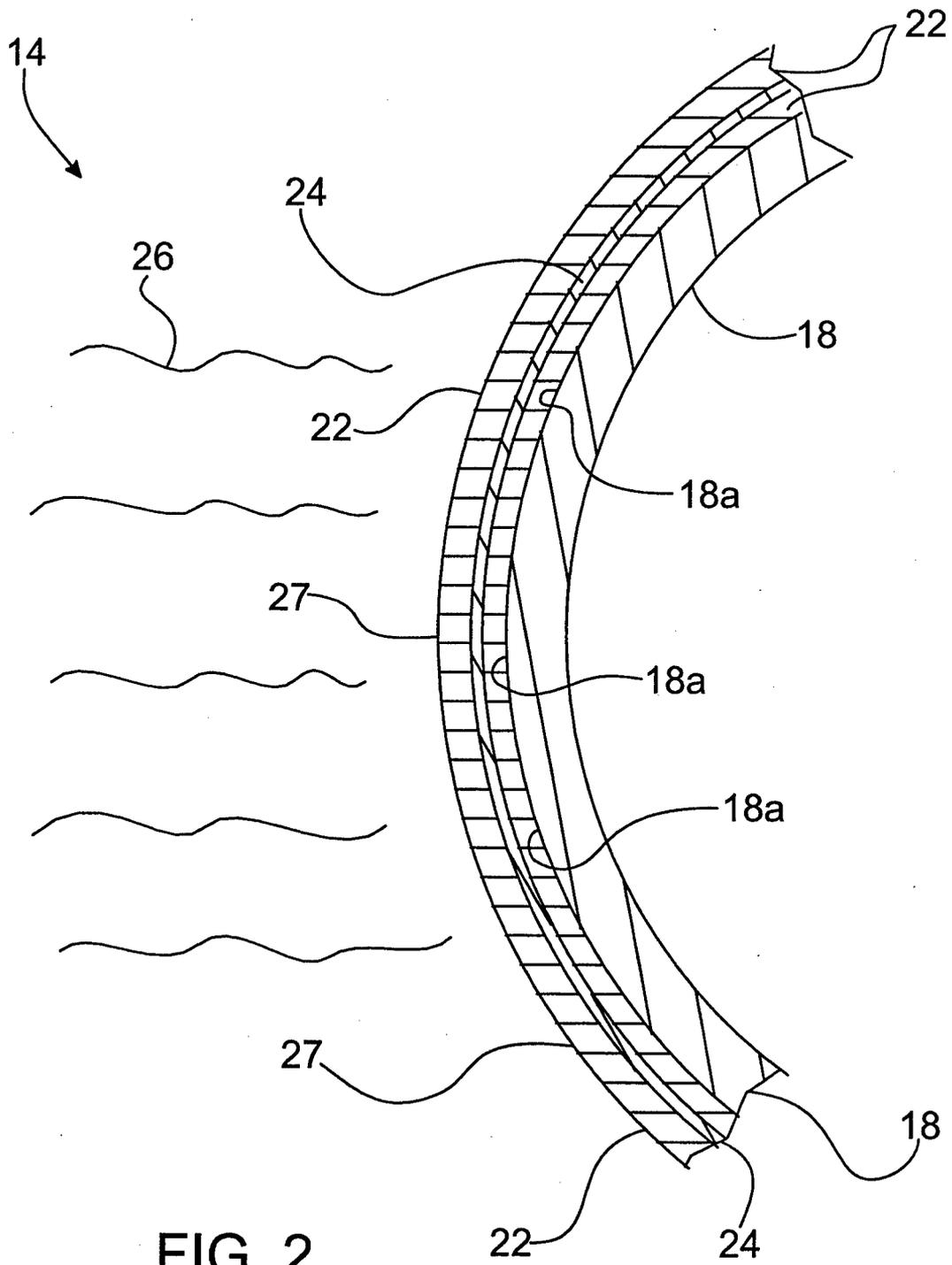


FIG. 2

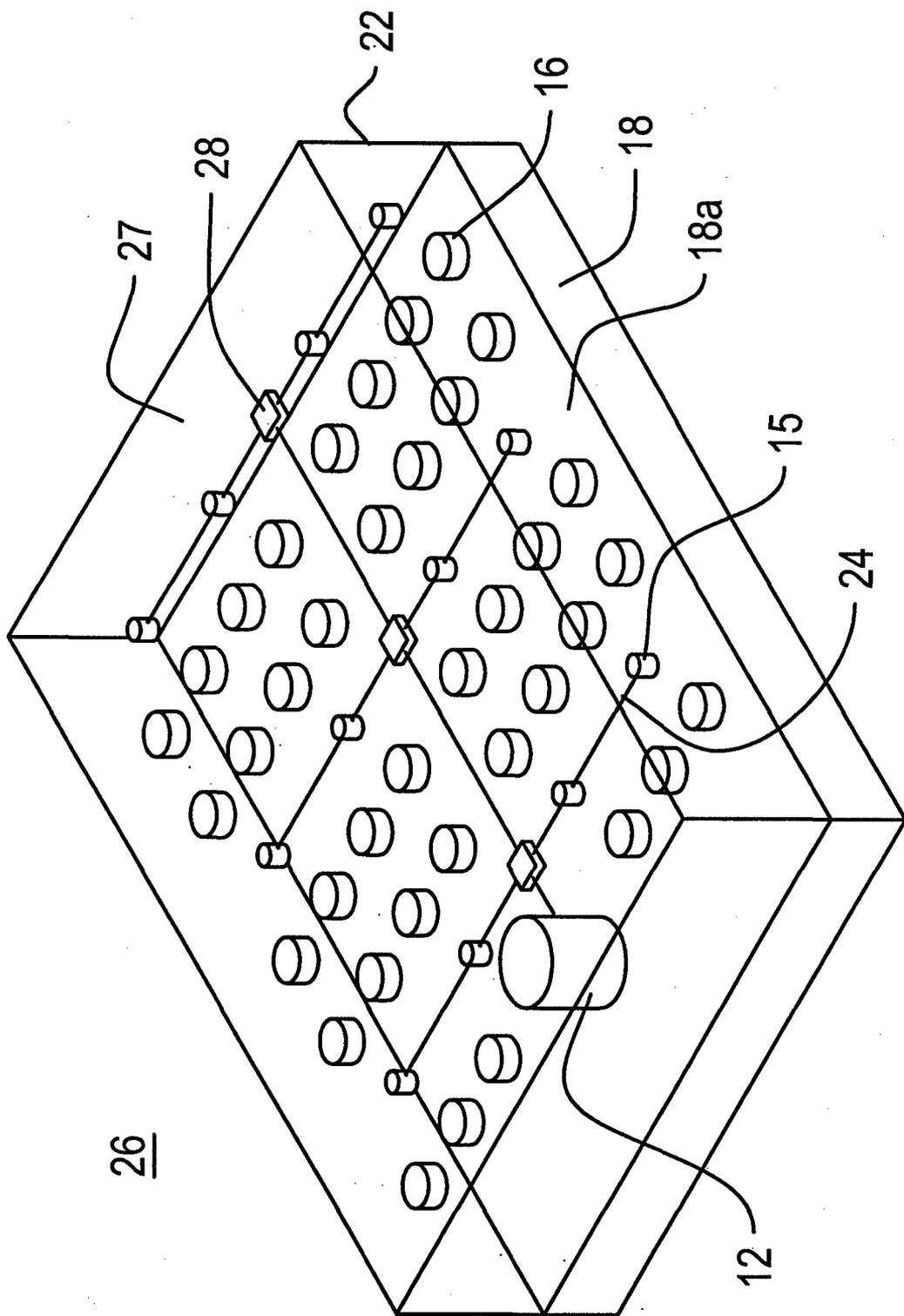


FIG. 3