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3 A LOW-POWER REMOTELY READABLE SENSOR

4
5 STATEMENT OF GOVERNMENT INTEREST

6 The invention described herein may be manufactured and used
7 by or for the Government of the United States of America for
8 governmental purposes without the payment of any royalties
9 thereon or therefor.

10
11 BACKGROUND OF THE PRESENT INVENTION

12 (1) Field of the Invention

13 The present invention relates to a sensor system, and a
14 method for operating such a system, which comprises a sensor
15 apparatus for gathering information, converting the information
16 to digital data and communicating such data via an RF encoded
17 signal to a remote reader system. More specifically, this
18 invention relates to a system for remotely reading the current
19 state of one or more sensor apparatus in a reader field of view
20 whereby the reader transmits an RF signal that is received,
21 modulated and re-radiated by each and every sensor apparatus in
22 the reader field of view. The sensor-module, re-radiated RF
23 signals contain discriminating information and digital data
24 frame. The reader, which will nearly simultaneously receive RF
25 signals from every sensor apparatus in the reader's field of
26 view, can use the discriminating information to identify each
27 specific sensor apparatus so that each digital data frame can be

1 addressed according to the specific sensor apparatus transmitting
2 the data frame.

3 (2) Description of the Prior Art

4 New battle-space scenarios (the Expeditionary Sensor Grid,
5 for example) include deploying large numbers of unattended
6 sensors that monitor certain aspects of the environment. The
7 sensors must have low power consumption in order to function
8 unattended for long periods. Further, the sensors should be
9 capable of covert operation. That is, the sensors should not be
10 detectable as a result of reflected or self-generated
11 electromagnetic emissions, even in the visible spectrum.
12 However, in order to be useful, the information gathered by the
13 sensors must find its way to regional data-fusion centers for
14 analysis and evaluation. What is needed, therefore, is a covert
15 and versatile sensor system that can be used in a wide range of
16 physical environments.

17
18 SUMMARY OF THE INVENTION

19 Accordingly, the present invention comprises a plurality of
20 remotely readable sensor apparatus and reader systems for
21 collecting data frames from each and every sensor apparatus
22 within the reader field of view. Each sensor apparatus comprises
23 a sensor means for converting one or more environmental
24 observable(s) into information signal(s), a memory means and a
25 digital processor means for converting information signal(s) into
26 digital data and appending such other discriminating digital data
27 as, for example, a time stamp, location stamp and sensor address

1 to form a digital data frame, a modulator means for modulating
2 the state of a diode connected to an antenna with the digital
3 data frame, and a timing means for controlling the digital-data-
4 frame start times. The modulated states of the diode connected
5 to a sensor-apparatus antenna are chosen such that the angle of
6 the antenna reflection coefficient is modulated between two
7 values separated by approximately 180 degrees, such that a
8 carrier signal received by the antenna effects a bi-phase
9 modulated signal containing the digital data frame that is
10 reflected by the sensor-apparatus antenna toward the reader
11 receiver antenna.

12 The invention includes a reader system which comprises a
13 reader transmitter for generating the carrier signal, a reader
14 antenna for transmitting the carrier signal to the sensor
15 apparatus, a receiving antenna for receiving the reflected signal
16 from the sensor apparatus, a reader receiver for processing the
17 received signal to form a processed received signal, a
18 demodulator for recovering the sensor-apparatus-generated data
19 frame, a processor for saving and fusing the data frames received
20 from a plurality of sensor apparatus, and a means for relaying
21 the fused data to another location.

22 The present invention also includes a method for remotely
23 sensing environmental data which comprises the steps of
24 collecting a plurality of environmental inputs via at least one
25 sensing means, formatting said plurality of environmental inputs
26 as digital data, collecting said digital data, storing said
27 collected digital data in a memory means as a data frame, said

1 memory means accessible by a sensor system having a sensor
2 antenna, constructing a data packet from said data frame,
3 encoding said data packet to construct a modulation sequence,
4 driving an RF modulator with said modulation sequence, generating
5 a carrier signal with a reader transmitter and directing said
6 carrier signal at said sensor antenna, receiving said carrier
7 signal at said sensor system via said sensor antenna, bi-phase
8 modulating said received carrier signal to produce a reflected
9 signal, receiving said reflected signal with a reader receiver,
10 processing said reflected signal to produce a processed signal,
11 decoding said processed signal to produce said data packet, and
12 recovering said data frame from said data packet.

13

14 BRIEF DESCRIPTION OF THE DRAWINGS

15 These and other features and advantages of the present
16 invention will be better understood in view of the following
17 description of the invention taken together with the drawings
18 wherein:

19 FIG. 1 is a block diagram of the components of the sensor
20 and reader systems of the present invention;

21 FIG. 2 is a diagram showing the location in operation of the
22 sensor and reader systems of the present invention;

23 FIG. 3 is an illustration of a sensor system of the present
24 invention affixed to a vehicle; and

25 FIG. 4 is an illustration of a sensor system of the present
26 invention deployed upon a body of water.

1 DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENT(S)

2 As is described more fully below, the sensor system of the
3 present invention is versatile, covert, and free of reflections
4 and self-generated electromagnetic emissions.

5 With reference to Fig. 2, there is illustrated the general
6 configuration of the present invention. In a preferred
7 embodiment, each of a plurality of sensor systems 14 is read by
8 an emitted RF signal 21 that is reflected from sensor system 14
9 as a reflected RF signal 23. The emitted RF signal 21 is emitted
10 by a reader system 15 and the reflected RF signal 23 is read by
11 the reader system 15. The emitted RF signal 21 can be
12 constructed using low power consumption CMOS components and only
13 passive RF components. Phase modulation of the reflected RF
14 signal 23 can be accomplished with a single P-N junction device
15 located on each sensor system 14 that is selected to have a
16 minority-carrier lifetime that is long compared with a period of
17 the emitted RF signal 21. The RF signal does not radiate at any
18 frequency unless it is receiving an emitted RF signal 21 from a
19 reader 15. Further, the phase modulation imposed on the
20 reflected RF energy 23 comprises a pseudo-random code that is
21 known to the reader 15 and cannot easily be detected by an alien
22 reader. Bi-phase modulation is chosen because the Fourier
23 frequency components of the reflected signal ideally does not
24 include a frequency component at the incident carrier frequency
25 and the sensor apparatus will not appear as a target when
26 illuminated by a radar. In this way, a sensor can remain

1 electromagnetically quiet even when it is interrogated by a
2 reader emitting an RF signal.

3 An antenna with a reactively terminated feed is highly
4 reflective in its band of operation and will have a radar cross-
5 section approaching the capture area of the antenna. If the
6 angle of the feed termination reflection coefficient is bi-phase
7 modulated between two angles separated by approximately 180
8 degrees while the magnitude of the reflection coefficient remains
9 close to unity, then the reflected double sideband suppressed
10 carrier signal will be nearly the same power as the received
11 carrier signal and will contain the data frame imposed by the
12 sensor modulator. A properly designed reader receiver can detect
13 the bi-phase modulation on the reflected RF signal, which will
14 contain any information encoded into the feed-termination
15 reflection-coefficient angle modulation.

16 The angle of an antenna feed-termination reflection
17 coefficient can be bi-phase modulated by a suitably imbedded PN
18 diode structure using simple low-power CMOS logic. The RF
19 properties of a PN diode are dependent on the diode's minority-
20 carrier lifetime. The state of the device is modulated at
21 frequencies below the reciprocal of the minority-carrier
22 lifetime. At frequencies above the reciprocal of the minority
23 carrier lifetime, the device appears to be a low-loss capacitor,
24 which is either very small or very large depending on whether the
25 PN diode is biased in the forward direction or in the reverse
26 direction. Thus, a properly chosen PN diode could be two-state
27 modulated at frequencies up to several tens of MHz using a low-

1 power CMOS driver circuit and "look" like a two-state switched
2 capacitor to a microwave signal.

3 In a preferred embodiment, the sensors are deployed in an
4 expeditionary sensor grid and are periodically monitored by over
5 flying the sensors with a remotely managed unmanned aerial
6 vehicle, UAV, equipped with a suitable reader. The UAV can link
7 the sensor information directly with a regional data-fusion
8 center.

9 A preferred embodiment of the remotely readable sensor
10 system is illustrated in FIG. 1. The system comprises a sensor
11 system 14 and a reader system 15. The reader system 15 acquires
12 information from the sensor system 14 across a medium by
13 transmitting an RF signal that is received, phase modulated, and
14 re-transmitted by the sensor system 14.

15 Environmental inputs 1 are collected by the sensing circuits
16 2 and formatted as digital data. Environmental inputs may
17 include, but are not limited to, temperature, motion, latitude,
18 longitude, and sound data. A data processor 3 collects the data,
19 appends local information, and writes the collected data into a
20 First In First Out (FIFO) memory 4 according to a preset timing
21 algorithm. The memory 4 stores a single frame of data
22 representing a sliding time interval. For example, the sensor
23 may collect a data set within each time interval, T , and the
24 memory may store N data sets representing one frame. Then, the
25 time interval represented by a memory frame extends back in time
26 for a period equal to $N \times T$. Each time a new data set is loaded

1 into memory 4 by the data processor 3, the oldest data set is
2 discarded.

3 The modulation signal generator 5 reads the current data
4 frame stored in memory 4, applies a pre-amble and a post-amble to
5 create a data packet, encodes the data packet, and constructs a
6 modulation sequence that is used to drive the RF bi-phase
7 modulator 6. The process of encoding the data packet may involve
8 encryption. The modulation signal generator 5 continues to drive
9 the RF modulator 6 with the current packet until a time interval
10 T has passed and a new data set has been loaded into memory 4.
11 Then, the cycle begins anew.

12 The RF modulator functions by changing the angle of the
13 reflection coefficient presented to the sensor antenna 7.
14 Changing the bias on a P-N junction device that terminates the
15 antenna feed line changes the reflection-coefficient angle. The
16 P-N junction device is modulated between two different reactive
17 states by a two-state signal supplied by the modulation signal
18 generator 5. The two reactive states of the P-N junction device
19 are mapped into two reflection-coefficient states that have
20 substantially equal magnitude and substantially opposite phase
21 [phase differs by about 180 degrees]. A passive two-port
22 matching network accomplishes the mapping.

23 The P-N junction device used in the RF Modulator 6 is chosen
24 to have a minority-carrier lifetime that is short compared to the
25 highest modulation frequency and long compared to a period of the
26 RF signal transmitted by the reader system 15. Thus, the device
27 state is easily changed by the modulator signal using very little

1 power and the device absorbs very little of the RF power
2 transmitted by the reader 15.

3 The reader transmitter 9 generates a carrier signal that may
4 be frequency or phase modulated and may be pulsed. The carrier
5 signal is fed to the reader antenna 8 and directed to the sensor
6 antenna 7. The antennas 7,8 may or may not be directional.
7 However, the reader transmitter 9, reader antenna 8 and reader
8 receiver 10, taken together, have a minimum detectable sensor-
9 antenna capture area at the range of the sensor antenna 7 that is
10 dependent on the effective radiated power of the reader
11 transmitter in the direction of the sensor apparatus. Then, in
12 order for the reader 15 to be able to read a sensor 14, the
13 antenna capture area of the sensor antenna 7, in the direction of
14 the reader antenna 8 must be greater than the minimum detectable
15 sensor antenna capture area of the reader system in the direction
16 of the sensor 14.

17 In operation, the reader-transmitted signal arrives at the
18 sensor antenna 7, is bi-phase modulated by the RF modulator 6 and
19 reflected to the reader antenna 8. The path loss associated with
20 this process is significant and is similar to the path loss
21 associated with radar detection of an object at the range of the
22 sensor apparatus that has a radar cross section equal to the
23 capture area of the sensor-apparatus antenna 7. The path loss
24 increases at least as fast as the fourth power of the separation
25 between the reader transmit-and-receive antennas 8 and the sensor
26 antenna 7.

1 The maximum range at which a sensor apparatus can be read is
2 dependent on the magnitude of the reader-transmitter 9 effective
3 radiated power in the direction of the sensor apparatus and range
4 can be increased by increasing transmitter power or by moving the
5 reader transmitter 9 closer to the sensor apparatus. The reader
6 transmitter 9 and the reader receiver 10 may be in different
7 locations in some embodiments. The reader-transmitter 9 may
8 collect data frames within its field of view from a plurality of
9 sensor apparatus in one read interval. A read interval, as used
10 herein, is defined as the time interval for a plurality of
11 sensors to respond to a single read signal sent out from the
12 reader-transmitter 9 within its field of view. Experimentation
13 with one embodiment of the present invention shows that an
14 average read interval is about ten seconds. In another
15 embodiment, the reader transmitter 9 may be replaced by a local
16 signal of opportunity, such as a weather radar signal of the
17 signal of a television broadcast. The reader receiver 10
18 processes the return signal and separates out the sidebands that
19 are a result of the modulation introduced by the sensor 14. The
20 sidebands are separated in frequency from the carrier signal
21 generated by the transmitter 9 by an extent that exceeds the
22 extent of the clutter spectrum plus the Doppler spectrum expected
23 from the sensor environment. The receiver 10 also removes any
24 transmitter modulation and Doppler shift so that the encoded
25 modulation sidebands sent to the demodulator 11 are a close
26 replica of the modulation sidebands generated by the sensor-
27 apparatus RF modulator 6. The demodulator 11 detects the current

1 data packet and sends it to the information decoder 12 where the
2 data frame is recovered. Each new data frame is stored in a
3 local memory 13 for transmission to a data fusion center.
4 Low-power circuits, CMOS for example, may be used in the sensors
5 of the present invention in order to extend the battery life of a
6 TAG that is designed in the subject manner. Further, a sensor
7 apparatus may be located where energy harvesting techniques can
8 extend sensor-apparatus life indefinitely. The sensor apparatus
9 does not radiate at any frequency but can be read remotely by
10 reader that has been designed to detect the bi-phase modulation
11 on the reflected RF signal. Any digital sensor-apparatus response
12 can be encrypted to avoid unwanted detection. The sensor-
13 apparatus can be completely self-contained and can be made as
14 small as the minimum sensor-antenna capture area observable by
15 the reader system.

16 In an alternative embodiment, one or more co-located
17 wireless other-sensor means can modify the information encoded in
18 the sensor-apparatus memory if an other-sensor wireless receiver
19 is included in the sensor apparatus to receive the new
20 information. In this way, a sensor-apparatus of the present
21 invention can be used to gather and fuse data from nearby
22 wireless sensors.

23 In addition, the entire sensor apparatus can be disguised as
24 a covert adjunct to any object of interest and would only be
25 detectable electronically at the correct sideband of a reflected
26 RF signal. The modulation may be spread in spectrum such that it
27 is nearly unobservable.

1 The sensors of the present invention can be affixed to a
2 vehicle. With reference to FIG. 3, there is illustrated an
3 embodiment wherein the sensor system 14 takes the form of a
4 license plate. Such a license plate can be "read" by reader
5 mounted on the front of a following car in order to gather
6 information about a particular vehicle. Wireless other sensors
7 within the vehicle could relay information to the license-plate
8 sensor apparatus, which could then be recovered by a reader. With
9 reference to FIG. 4, there is illustrated an alternative
10 embodiment wherein the sensor apparatus 14 is fashioned to float
11 on the surface of a body of water.

2
3 A LOW-POWER REMOTELY READABLE SENSOR

4
5 ABSTRACT OF THE DISCLOSURE

6 A plurality of remotely readable sensor apparatus and reader
7 systems for collecting data frames from all apparatus within the
8 reader field of view. Each sensor apparatus converts one or more
9 environmental observable into information signals, converts the
10 information signals into digital data and appends other
11 discriminating digital data as desired to form a digital data
12 frame. The state of a diode, connected to an antenna with the
13 digital data frame, is modulated and a timing apparatus controls
14 the digital-data-frame start times. The modulated states of the
15 diode connected to a sensor-apparatus antenna are chosen so the
16 angle of the antenna reflection coefficient is modulated between
17 two values separated by approximately 180 degrees, so a carrier
18 signal received by the antenna effects a bi-phase modulated signal
19 containing the digital data frame that is reflected by the sensor-
20 apparatus antenna toward the reader receiver antenna.

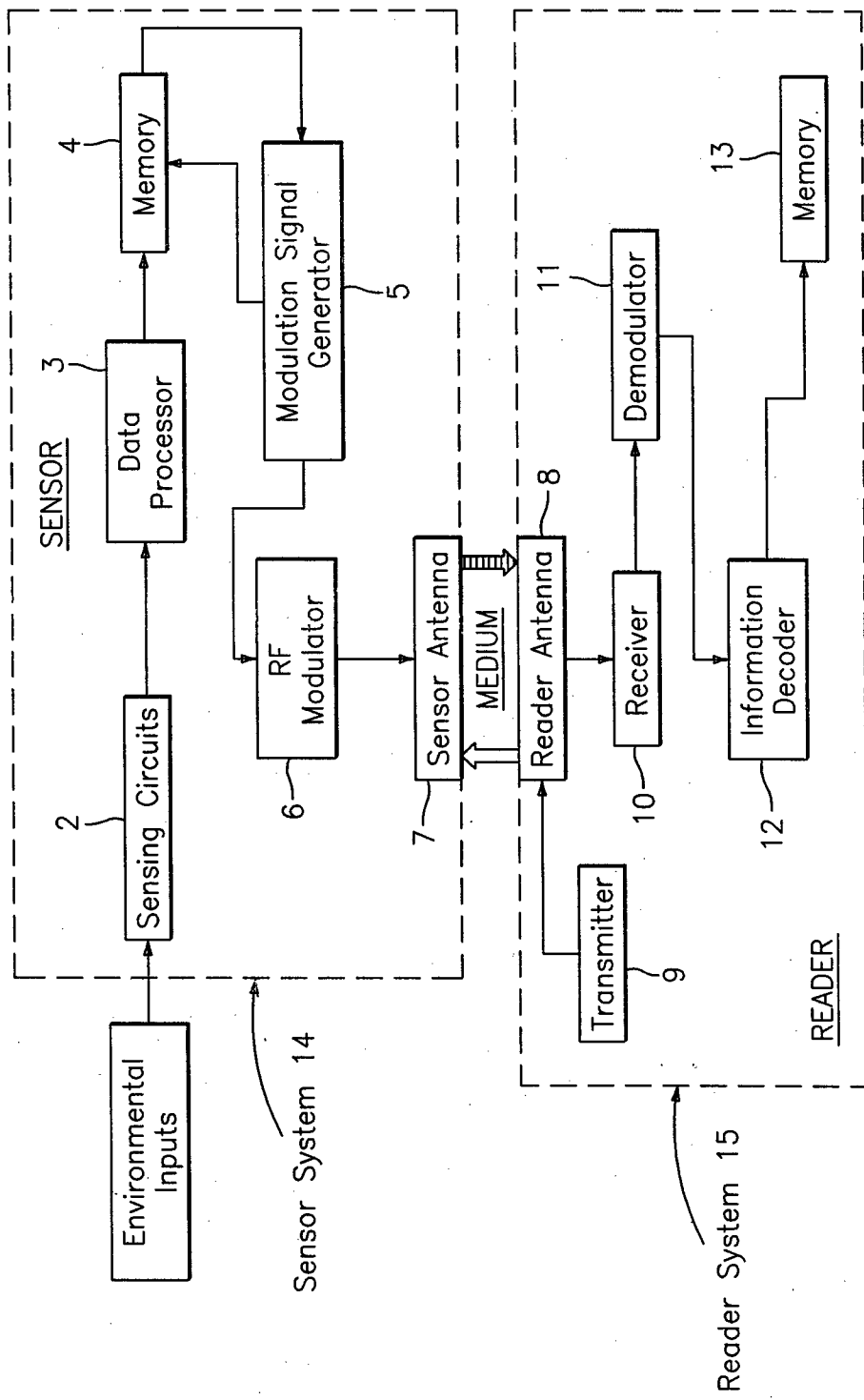


FIG. 1

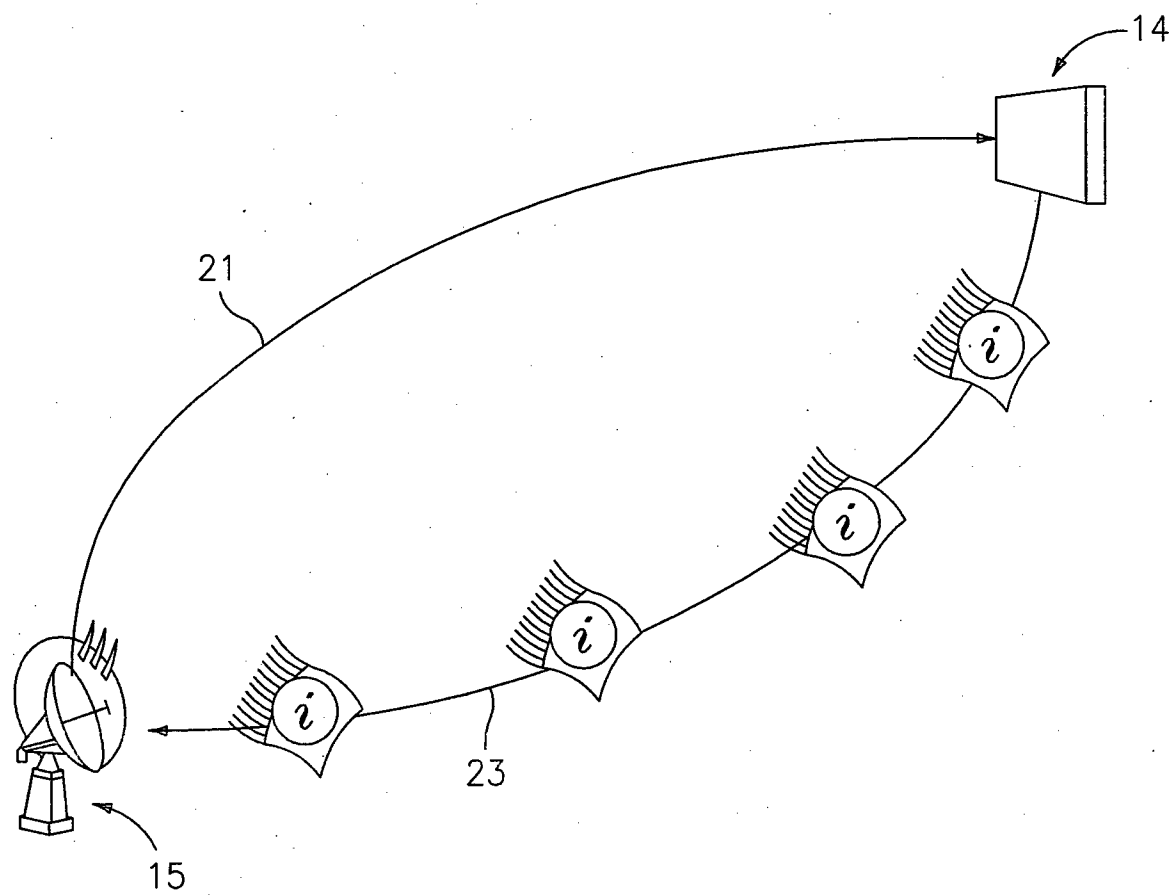


FIG. 2

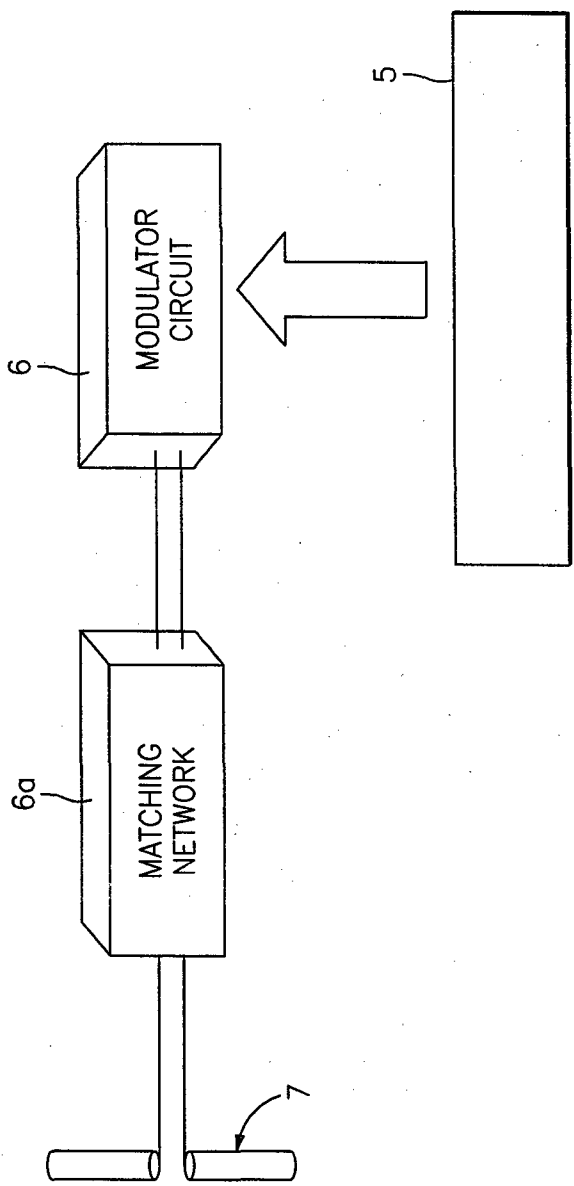


FIG. 2a

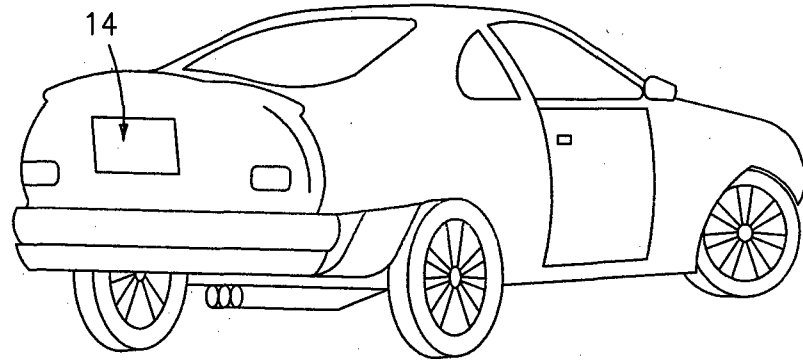


FIG. 3

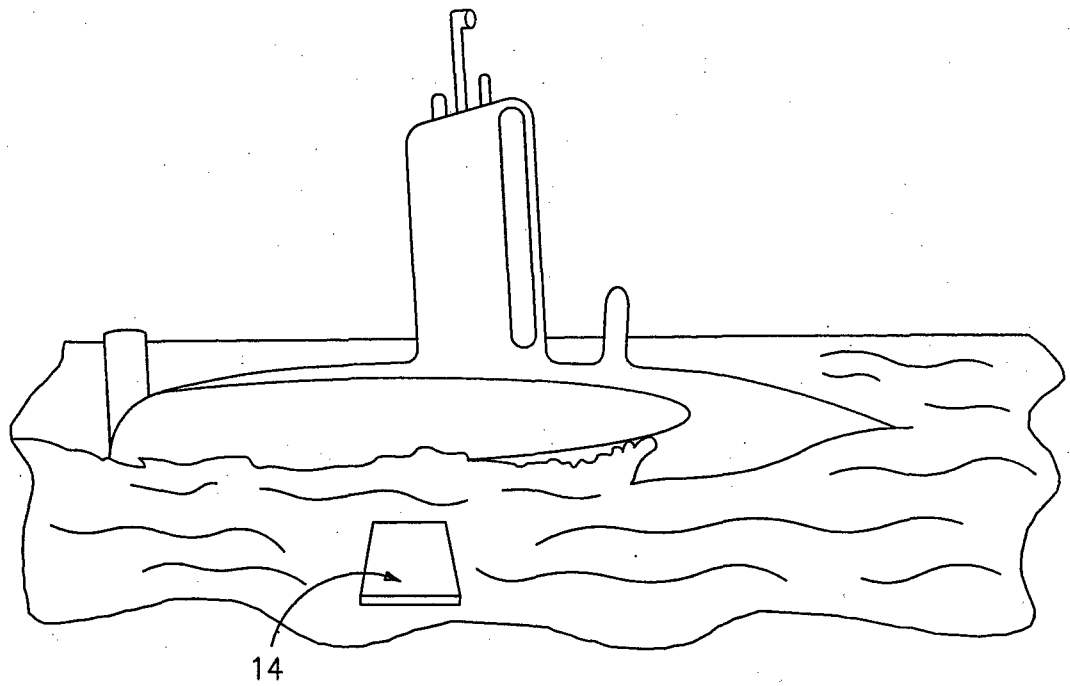


FIG. 4