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NAVAL UNDERSEA WARFARE CENTER DIVISION  
1176 HOWELL STREET  
NEWPORT RI 02841-1708

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PATENT COUNSEL  
NAVAL UNDERSEA WARFARE CENTER  
1176 HOWELL ST.  
CODE 00OC, BLDG. 112T  
NEWPORT, RI 02841

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Inventor            Christopher M. DeAngelis

If you have any questions please contact James M. Kasischke, Deputy Counsel, at 401-832-4736.

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PROBABILITY DISTRIBUTION CLASSIFICATION PROCESSOR

TO WHOM IT MAY CONCERN:

BE IT KNOWN THAT CHRISTOPHER M. DeANGELIS AND ROBERT C. HIGGINS, employees of the United States Government, citizens of the United States of America, residents respectively of Cranston, County of Providence, State of Rhode Island and Tiverton, County of Newport, State of Rhode Island, have invented certain new and useful improvements entitled as set forth above of which the following is a specification:

JEAN-PAUL A. NASSER, ESQ.  
Reg. No. 53372  
Naval Undersea Warfare Center  
Division Newport  
Newport, RI 02841-1708  
TEL: 401-832-4736  
FAX: 401-832-1231

1 Attorney Docket No. 79833

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3 PROBABILITY DISTRIBUTION CLASSIFICATION PROCESSOR

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5 STATEMENT OF GOVERNMENT INTEREST

6 The invention described herein may be manufactured and used  
7 by or for the Government of the United States of America for  
8 governmental purposes without the payment of any royalties  
9 thereon or therefore.

10

11 CROSS REFERENCE TO OTHER RELATED APPLICATIONS

12 Not applicable.

13

14 BACKGROUND OF THE INVENTION

15 (1) Field of the Invention

16 The present invention relates generally to classifying  
17 probability distributions and, more particularly, to a neural  
18 network system and method for processing random data with an  
19 unknown probability distribution function to thereby classify the  
20 best represented probability distribution thereof.

21 (2) Description of the Prior Art

22 The basic prior art technique for classifying probability  
23 distributions involves the use of the histogram. The purpose of  
24 a histogram is to graphically summarize the distribution of a  
25 data set. The histogram graphically attempts to show the

1 following: the center (i.e., the location) of the data, the  
2 spread (i.e., the scale) of the data, the skewness of the data,  
3 the presence of outliers, and the presence of multiple modes in  
4 the data. One disadvantage of the histogram technique is that  
5 refinements must often be made in the data interval sizes to  
6 classify the distribution, which often involves a trial and error  
7 approach. Another disadvantage is the time-consuming requirement  
8 for visual examination of the features of the histogram to  
9 provide indications of the proper distributional model for the  
10 data so that a hypothesis can be formed as to the type of  
11 distributional model. Mathematical means of confidence such as  
12 the probability plot or a goodness-of-fit test can then be used  
13 to verify the hypothesized distributional model.

14 After obtaining a hypothesis utilizing the histogram, the  
15 probability plot is a graphical technique for assessing whether  
16 or not a data set follows a given distribution such as the normal  
17 or Weibull. The data are plotted against a theoretical  
18 distribution in such a way that the points should form  
19 approximately a straight line. Departures from this straight  
20 line indicate departures from the specified distribution. The  
21 correlation coefficient associated with the linear fit to the  
22 data in the probability plot is a measure of the goodness of the  
23 fit. Estimates of the location and scale parameters of the  
24 distribution are given by the intercept and slope. Probability  
25 plots can be generated for several competing distributions to see

1 which provides the best fit, and the probability plot generating  
2 the highest correlation coefficient is the best choice since it  
3 generates the straightest probability plot.

4 Another means for verifying the hypothesis for the  
5 probability distribution is the Anderson-Darling goodness-of-fit  
6 test, which tests if a sample of data came from a population with  
7 a specific distribution. It is a modification of the Kolmogorov-  
8 Smirnov (K-S) test and gives more weight to the tails than does  
9 the K-S test. The K-S test is distribution-free in the sense  
10 that the critical values do not depend on the specific  
11 distribution being tested. The Anderson-Darling test makes use  
12 of the specific distribution in calculating critical values.  
13 This has the advantage of allowing a more sensitive test and the  
14 disadvantage that critical values must be calculated for each  
15 distribution.

16 In the field of statistics, due to the difficulty as  
17 explained above, for determining the probability distribution of  
18 random data, assumptions are usually made about the probability  
19 characteristics of a sample of random data because the  
20 probability distribution is otherwise unknown. The probability  
21 distribution function, if known, would provide information about  
22 the frequency of occurrence of each data element in a sample of  
23 random (non-deterministic) data that consists of several data  
24 elements. Statistics like the mean and standard deviation of the  
25 data are estimated based on assumptions about the shape of the

1 probability distribution function that characterizes random data.

2 Therefore, the calculated statistics associated with a Binomial  
3 Distribution will be different from a Poisson or a Gaussian  
4 Distribution, or any other type of distribution. When modeling  
5 parameters (i.e. phase, amplitude, and frequency) associated with  
6 certain types of acoustic interference like reverberation,  
7 multipath or noise, the models may typically assume a Gaussian or  
8 some other distribution to represent these acoustic phenomena.

9 The following U.S. Patents describe various prior art  
10 systems that may be at least related to the problems discussed  
11 above, but which do not provide suitable solutions.

12 U.S. Patent Application No. 2001/0031064 A1, published  
13 October 18, 2001, to Donescu et al., discloses a method of  
14 inserting a watermarking signal in a set of coefficients  
15 representing a digital image in which at least one subset of  
16 coefficients is modified by the watermarking signal. For each  
17 representative coefficient to be modified, a neighborhood of the  
18 representative coefficient to be modified is determined. A  
19 neighborhood in a dictionary of neighborhoods is selected  
20 according to a predetermined criterion of similarity with the  
21 neighborhood for the representative coefficient under  
22 consideration. The representative coefficient is modified as a  
23 function of the watermarking signal.

24 U.S. Patent No. 6,324,532, issued November 27, 2001, to  
25 Spence et al., discloses a signal processing apparatus and

1 concomitant method for learning and integrating features from  
2 multiple resolutions for detecting and/or classifying objects.  
3 The signal processing apparatus comprises a hierarchical pyramid  
4 of neural networks (HPNN) having a "fine-to-coarse" structure or  
5 a combination of the "fine-to-coarse" and the "coarse-to-fine"  
6 structures.

7 U.S. Patent No. 6,278,970, issued August 21, 2001, to  
8 Benjamin P. Milner, discloses how to calculate the log frame  
9 energy value of each of a pre-determined number n of frames of an  
10 input speech signal and apply a matrix transform to the n log  
11 frame energy values to form a temporal matrix representing the  
12 input speech signal. The matrix transform may be a discrete  
13 cosine transform.

14 U.S. Patent No. 6,006,186, issued December 21, 1999, to Chen  
15 et al., discloses a method and an apparatus for a parameter  
16 sharing speech recognition system. Speech signals are received  
17 into a processor of a speech recognition system. The speech  
18 signals are processed using a speech recognition system hosting a  
19 shared hidden Markov model (HMM) produced by generating a number  
20 of phoneme models, some of which are shared. The phoneme models  
21 are generated by retaining as a separate phoneme model any  
22 triphone model having a number of trained frames available that  
23 exceeds a prespecified threshold. A shared phoneme model is  
24 generated to represent each of the groups of triphone phoneme  
25 models for which the number of trained frames having a common

1 biphone exceed the prespecified threshold. A shared phoneme  
2 model is generated to represent each of the groups of triphone  
3 phoneme models for which the number of trained frames having an  
4 equivalent effect on a phonemic context exceed the prespecified  
5 threshold. A shared phoneme model is generated to represent each  
6 of the groups of triphone phoneme models having the same center  
7 context. The generated phoneme models are trained, and shared  
8 phoneme model states are generated that are shared among the  
9 phoneme models. Shared probability distribution functions are  
10 generated that are shared among the phoneme model states. Shared  
11 probability sub-distribution functions are generated that are  
12 shared among the phoneme model probability distribution  
13 functions. The shared phoneme model hierarchy is reevaluated for  
14 further sharing in response to the shared probability sub-  
15 distribution functions. Signals representative of the received  
16 speech signals are generated.

17 U.S. Patent No. 5,924,066, issued July 13, 1999, to Amlan  
18 Kundu, discloses a system and method for classifying a speech  
19 signal within a likely speech signal class of a plurality of  
20 speech signal classes. Stochastic models include a plurality of  
21 states having state transitions and output probabilities to  
22 generate state sequences, which model evolutionary  
23 characteristics and durational variability of a speech signal.  
24 The method includes extracting a frame sequence, and determining  
25 a state sequence for each stochastic model with each state

1 sequence having full state segmentation. Representative frames  
2 are determined to provide speech signal time normalization. A  
3 likely speech signal class is determined from a neural network  
4 having a plurality of inputs receiving the representative frames  
5 and a plurality of outputs corresponding to the plurality of  
6 speech signal classes. An output signal is generated based on  
7 the likely stochastic model.

8 U.S. Patent No. 6,336,109, issued January 1, 2002, to Gary  
9 Howard, discloses a method of processing data relating to a  
10 plurality of examples using a data classifier arranged to  
11 classify input data into one of a number of classes, and a rule  
12 inducer, comprising the steps of: (i) inputting a series of  
13 inputs to the data classifier so as to obtain a series of  
14 corresponding outputs; (ii) inputting the series of outputs and  
15 at least some of the series of inputs to the rule inducer so as  
16 to obtain a series of rules which describe relationships between  
17 the series of inputs to the data classifier and the series of  
18 corresponding outputs from the data classifier.

19 U.S. Patent No. 6,314,399, issued November 6, 2001, to  
20 Deligne et al., discloses an apparatus that generates a  
21 statistical class sequence model called A class bi-multigram  
22 model from input training strings of discrete-valued units, where  
23 bigram dependencies are assumed between adjacent variable length  
24 sequences of maximum length N units, and where class labels are  
25 assigned to the sequences. The number of times all sequences of

1 units occur are counted, as well as the number of times all pairs  
2 of sequences of units co-occur in the input training strings. An  
3 initial bigram probability distribution of all the pairs of  
4 sequences is computed as the number of times the two sequences  
5 co-occur, divided by the number of times the first sequence  
6 occurs in the input training string. Then, the input sequences  
7 are classified into a pre-specified desired number of classes.  
8 Further, an estimate of the bigram probability distribution of  
9 the sequences is calculated by using an EM algorithm to maximize  
10 the likelihood of the input training string computed with the  
11 input probability distributions. The above processes are then  
12 iteratively performed to generate statistical class sequence  
13 model.

14 U.S. Patent No. 6,239,740, issued May 29, 2001, to Collins  
15 et al., discloses an efficient algorithm for evaluating the  
16 (weighted bipartite graph of) associations between two sets of  
17 data with Gaussian error, e.g., between a set of measured state  
18 vectors and a set of estimated state vectors. First a general  
19 method is developed for determining, from the covariance matrix,  
20 minimal d-dimensional error ellipsoids for the state vectors,  
21 which always overlap when a gating criterion is satisfied.  
22 Circumscribing boxes, or d-ranges, for the data ellipsoids are  
23 then found and whenever they overlap the association probability  
24 is computed. For efficiently determining the intersections of  
25 the d-ranges a multidimensional search tree method is used to

1 reduce the overall scaling of the evaluation of associations.  
2 Very few associations that lie outside the predetermined error  
3 threshold or gate are evaluated. Empirical testing for variously  
4 distributed data in both three and eight dimensions indicate that  
5 the scaling is significantly reduced from  $N^2$ , where  $N$  is the size  
6 of the data set. Computational loads for many large scale ( $N > 10$ -  
7 100) data association tasks may therefore be significantly  
8 reduced by this or related methods.

9 U.S. Patent No. 6,131,089, issued October 10, 2000, to  
10 Campbell et al., discloses classifiers and a comparator that  
11 perform an identification method to identify a class as one of a  
12 predetermined set of classes. The identification method is based  
13 on determining the observation costs associated with the  
14 unidentified class. The identification method includes combining  
15 models representing the predetermined set of classes and the  
16 unidentified vectors representing the class. The predetermined  
17 class associated with the largest observation cost is identified  
18 as the class. Additionally, a unique, low-complexity training  
19 method includes creating the models, which represent the  
20 predetermined set of classes.

21 U.S. Patent No. 6,041,299, issued March 21, 2000, to  
22 Schuster et al., discloses an apparatus for calculating a  
23 posteriori probabilities of phoneme symbols and a speech  
24 recognition apparatus using the apparatus for calculating a  
25 posteriori probabilities of phoneme symbols. A feature

1 extracting section extracts speech feature parameters from a  
2 speech signal of an uttered speech sentence composed of an  
3 inputted character series, and a calculating section calculates  
4 the a posteriori probability of a phoneme symbol of the speech  
5 signal, by using a bidirectional recurrent neural network. The  
6 bidirectional recurrent neural network includes an input layer  
7 for receiving the speech feature parameters extracted by the  
8 feature extracting means and a plurality of hypothetical phoneme  
9 symbol series signals, an intermediate layer of at least one  
10 layer having a plurality of units, and an output layer for  
11 outputting the a posteriori probability of each phoneme symbol.  
12 The input layer includes a first input neuron group having a  
13 plurality of units, for receiving a plurality of speech feature  
14 parameters and a plurality of phoneme symbol series signals, a  
15 forward module, and a backward module.

16 U.S. Patent No. 5,999,893, issued December 7, 1999, to  
17 Lynch, Jr. et al., discloses a classification system that uses  
18 sensors to obtain information from which features, which  
19 characterized a source or object to classified, can be extracted.  
20 The features are extracted from the information and compiled into  
21 a feature vector, which is then quantized to one of M discrete  
22 symbols. After N feature vectors have been quantized, a test  
23 vector having components which are defined by the number of  
24 occurrences of each of the M symbols in N the quantized vectors  
25 is built. The system combines the test vector with training data

1 to simultaneously estimate symbol probabilities for each class  
2 and classify the test vector using a decision rule that depends  
3 only on the training and test data. The system classifies the  
4 test vector using either a Combined Bayes test or a Combined  
5 Generalized likelihood ratio test.

6 The above disclosed prior art does not provide an automatic  
7 system and method which can be easily implemented with hardware  
8 or on a computer to classify random data into any type of the  
9 probability distribution and which does not involve visual  
10 examination, trial and error approaches, iterative techniques,  
11 measures of confidence, and the like. It is the inventors'  
12 belief that in the design of many signal processors, knowledge  
13 about the probability and statistical characteristics of the  
14 noise that contaminates a signal input may improve the capability  
15 of the processor. Accordingly, exact knowledge of these  
16 phenomena would provide more accurate results. Moreover, it is  
17 the inventors' belief that an automatic mechanism to conveniently  
18 process a set of data samples and determine the associated  
19 probability distribution would therefore likely be invaluable to  
20 researchers. As discussed above, the prior art does not provide  
21 such a method. The need for solutions to the above-described  
22 problems has been long felt but the solutions have not been  
23 forthcoming. Consequently, those skilled in the art will  
24 appreciate the present invention that addresses the above and  
25 other problems.

1 SUMMARY OF THE INVENTION

2 It is a general purpose and object of the present invention  
3 to provide an improved system and method for determining a  
4 probability distribution for random data.

5 It is another general purpose and object of the present  
6 invention to provide a system and method to which the random data  
7 can be input for automatically determining which of several  
8 different types of probability distributions best describe the  
9 random data.

10 It is another objection of the present invention to utilize  
11 a plurality of trained neural networks to sample the random data  
12 for determining the probability distribution thereof.

13 These and other objects, features, and advantages of the  
14 present invention will become apparent from the drawings, the  
15 descriptions given herein, and the appended claims. However, it  
16 will be understood that above listed objects and advantages of  
17 the invention are intended only as an aid in understanding  
18 aspects of the invention, are not intended to limit the invention  
19 in any way, and do not form a comprehensive list of objects,  
20 features, and advantages.

21 According, the present invention provides a system for  
22 determining a probability distribution of random data wherein the  
23 system may comprise one or more elements such as, for example,  
24 one or more first neural networks each trained to recognize a  
25 first probability distribution of the random data, one or more  
26 second neural networks each trained to recognize a second  
27 probability distribution of the random data, and a decision logic

1 module for comparing outputs for the one or more first neural  
2 networks and the second neural networks to thereby select the  
3 first probability distribution or the second probability  
4 distribution as best describing the probability distribution of  
5 the random data. The decision logic module is preferably  
6 operable for selecting the probability distribution of the random  
7 data based on a set of rules related to specified ranges of  
8 values of the outputs for first neural networks and the second  
9 neural networks.

10 The system may further comprise a window generator for  
11 providing a selected size sample of the random data to the one or  
12 more first neural networks and the one or more second neural  
13 networks. In one preferred embodiment, the system comprises a  
14 plurality of the first neural networks and a plurality of the  
15 second neural networks wherein the window generator is operable  
16 for providing variable size samples to each of the plurality of  
17 first neural networks and the plurality of second neural  
18 networks.

19 Other elements of the system may further comprise a  
20 parameter estimator operable for determining one or more  
21 statistical parameters of the selected size sample. The  
22 parameter estimator preferably produces an output receivable by  
23 the decision logic module for determining whether to continue  
24 processing the random data or to stop processing the random data.

25 Preferably, a normalizer is utilized for normalizing the  
26 random data to fall within a selected range of values.

1 In operation, the present invention provides a method for  
2 automatically determining a probability distribution for random  
3 data which may comprise one or more steps such as, for instance,  
4 providing different size samples of the random data to a first  
5 plurality of neural networks, providing the different size  
6 samples of the random data to a second plurality of neural  
7 networks, and comparing outputs of the first plurality of neural  
8 networks with the outputs of the second plurality of neural  
9 networks for determining the probability distribution of the  
10 random data.

11 The method further comprises providing a set of logic rules  
12 for determining the probability distribution of the random data  
13 based on ranges of values of the outputs of the first plurality  
14 of neural networks and the outputs of the second plurality of  
15 neural networks.

16 The method may further comprise training the first plurality  
17 of neural networks to produce a selected output value in response  
18 to random data corresponding to a first probability distribution,  
19 and training the second plurality of neural networks to produce a  
20 selected output value in response to random data corresponding to  
21 a second probability distribution.

22 The method may preferably further comprise determining  
23 statistical parameters of the different size samples of the  
24 random data.

25 In a preferred embodiment, the method comprises utilizing a  
26 sliding window of random data for the different size data samples  
27 whereby the sliding window of random data changes after each use

1 by adding a selected number of new data samples and subtracting a  
2 corresponding number of previously processed data samples.

3  
4 BRIEF DESCRIPTION OF THE DRAWINGS

5 A more complete understanding of the invention and many of  
6 the attendant advantages thereto will be readily appreciated as  
7 the same becomes better understood by reference to the following  
8 detailed description when considered in conjunction with the  
9 accompanying drawings, wherein like reference numerals refer to  
10 like parts and wherein:

11 FIG. 1A is a schematic of one possible neural network  
12 configuration for a component of the system in accord with the  
13 present invention;

14 FIG. 1B is a schematic of one neuron in a layer of neurons  
15 of a neural network such as the neural network of FIG. 1A;

16 FIG. 2 is a block diagram for one possible probability  
17 distribution classification processor in accord with the present  
18 invention for two probability distributions;

19 FIG. 3 is a graph showing possible outputs for the six  
20 artificial neural networks (ANN) processors of the probability  
21 distribution classification processor of FIG. 2;

22 FIG. 4 is a graph showing outputs of the parameter estimator  
23 for the probability distribution classification processor of FIG.  
24 2; and

25 FIG. 5 is a block diagram for the rule-based decision aide  
26 of the probability distribution classification processor of FIG.

27 2.

1 DESCRIPTION OF THE PREFERRED EMBODIMENT

2 Referring now to the drawings and, more particularly, to  
3 FIG. 2, there is shown system 10 which is a block diagram for a  
4 preferred embodiment of a probability distribution classification  
5 processor in accord with the present invention. The present  
6 invention therefore provides system and methods for classifying  
7 the form of the probability distribution that describes a sample  
8 of random data elements.

9 To simplify the description and operation of this processor,  
10 the design of system 10 presented here will have the capability  
11 to classify only two different probability distributions.  
12 However, it will be understood that the addition of capability to  
13 classify data into other probability distributions will be  
14 substantially the same as discussed herein below for two  
15 frequently occurring probability distributions. Thus, it will be  
16 understood that the processor capability can be readily expanded  
17 to automatically classify the random data into any number of  
18 different types of possible probability distributions. In one  
19 embodiment, the capability for considering different probability  
20 distributions could be switchable or selectable so that  
21 consideration of any of numerous different probability  
22 distributions could be easily switched on as desired for testing  
23 by the user.

24 In the embodiment of the invention disclosed in FIG. 2, two  
25 different probability distributions are considered by system 10.

26 The first probability distribution is the well-known Uniform  
27 distribution that represents data where each random element

1 (number) has the same probability of occurrence. The second  
2 probability distribution to be considered is the well-known  
3 Gaussian distribution that represents data where each element has  
4 a different probability of occurrence with the larger positive  
5 and negative random elements (numbers) occurring less frequently  
6 than the smaller ones. When the mean is zero, the Gaussian  
7 distribution is referred to as a Normal distribution.

8 FIG. 1A and 1B show artificial neural network (ANN) elements  
9 that are trained to recognize a particular type of probability  
10 distribution, such as the Uniform distribution or the Gaussian  
11 distribution. Neural network 12 may comprise several layers of  
12 interconnected neurons wherein each neuron, such as neuron 14,  
13 may preferably be connected to each neuron of the previous layer  
14 of neurons and to each neuron of the subsequent layer of neurons.

15 It will be understood that neural network 12 may be much larger  
16 than shown in FIG. 1A and/or comprise more layers and/or more  
17 neurons per layer. For instance, to process 100 data inputs  
18 simultaneously, the neural network may comprise a first layer of  
19 100 neurons. Each neuron in each layer, such as neuron 14 of  
20 FIG. 1B, may simply weight and sum inputs 16 and offset by a bias  
21 17 with adder 18. The result of adder 18 is passed through  
22 activation function 20.

23 Activation function 20, which may be a Sigmoid function, is  
24 used to limit the permissible amplitude range of output 22. For  
25 instance, the output may be limited to between zero to one or  
26 from minus one to plus one. Neuron output 22 is passed on to  
27 each neuron in the next layer of neurons and so on until the last

1 layer produces output 24 for the neural network, such as the  
2 respective outputs of neural networks 26, 28, 30, 32, 34, and 36  
3 of system 10 shown in FIG. 2.

4 Training the neural network(s) involves adaptively and  
5 systematically selecting the weights and bias of each neuron  
6 within the network to minimize the error between the actual  
7 output and the desired one. For example, if it desired to have a  
8 neural network produce a one when the input random data is  
9 uniformly distributed and a zero otherwise, the internal weights  
10 and bias of each neuron are established by an adaptive iterative  
11 process to make this happen. After the network has been trained,  
12 the output will provide a measure of the uniformity of the  
13 distribution of the random data. A detailed description of a  
14 neural network may be found in the literature (e.g., *Neural*  
15 *Networks* by Simon Haykin, 1994). The specific type of neural  
16 network that is used in this application may preferably be a back  
17 propagation model. In this type of model, the correct weights  
18 and bias of each are established by modifying the last layer of  
19 neuron parameters first in an attempt to produce the desired  
20 output, then if necessary modifying the previous layer, and so  
21 forth.

22 FIG. 2 is therefore a block diagram of one embodiment of  
23 system 10 for a Probability Distribution Classification Processor  
24 in accord with the present invention. Input data 38 preferably  
25 consists of or comprises a finite set of random numbers. As a  
26 first step in a preferred embodiment of the invention, the entire  
27 set of random numbers is preferably normalized to a new set of

1 data between -1 and +1 in normalizer 40. Normalization  
2 simplifies the process of training the neural networks. The  
3 Gaussian distribution artificial neural network (ANN) classifier  
4 can thereby be trained using a finite number of statistics. For  
5 example, training may be performed using Gaussian data  
6 representing standard deviations from 0.1 to 1 in increments of  
7 0.1 and means from -1 to +1 in increments of 0.1. Each Gaussian  
8 and Uniform neural network classifier will be trained using a  
9 different sized sliding window of normalized data as indicated at  
10 42. Therefore, system 10 will be comprised of several different  
11 neural networks, such as networks 26, 28, 30, 32, 34, and 36  
12 corresponding to the number of different sliding windows of data  
13 samples for each type of distribution to be classified.

14 After normalizing, the numbers are processed by artificial  
15 neural networks (ANN) 26, 28, 30, 32, 34, and 36. In this  
16 example, the intervals or windows comprise 100, 500, and 1000  
17 data samples. However, other interval sizes could also be  
18 utilized and/or additional interval sizes could be utilized.  
19 Preferably at least two different interval or window sizes are  
20 utilized for comparison purposes as discussed hereinafter.  
21 Sliding window function 42 may be used to select the data samples  
22 for the respective networks. For instance, using a 100 sample  
23 sliding window, the first 100 data values (samples 1 through  
24 100) are selected and processed, then the second 100 values  
25 (samples 2 through 101) are selected and processed; this process  
26 continues until all the data has been processed. The 500 and  
27 1000 sample windows of data are processed in the same manner with

1 all sliding window operations (100, 500, and 1000) performed  
2 concurrently.

3 In FIG. 2, three ANN Gaussian Distribution Classification  
4 processors 26, 28, and 30 as well as three ANN Uniform  
5 Distribution Classification processors 32, 34, and 36 are shown.  
6 The three ANN Gaussian processors will be capable of processing  
7 data windows of 100, 500, and 1000 samples of the normalized  
8 random data respectively. The three ANN Uniform processors will  
9 have a corresponding capability. As discussed earlier, a 100  
10 sample sliding window function 42 will initially select data  
11 samples 1 through 100 for processing. Then, data samples 2  
12 through 101 are selected. This process continues incrementally  
13 until all the data has been processed. Each ANN Uniform and each  
14 ANN Gaussian processor will be trained to produce an output  
15 between 0 and 1 for each sliding window increment of data, where  
16 the output of the ANN is proportional to the degree in which the  
17 data matches the respective distribution. Each output will be  
18 stored within Rule-Based Decision Aide 44 until all the data has  
19 been processed by the neural networks. It should be noted that  
20 any number of ANNs can be employed at any window size to enhance  
21 the data classification process. Figure 3 shows one set of  
22 possible ANN 26, 28, 30, 32, 34, and 36 outputs with respect to  
23 each increment of the sliding window.

24 Parameter Estimator 46 shown in FIG. 2 will also provide  
25 information to Rule-Based Decision Aide 44. Relevant statistics  
26 like the mean and standard deviation and/or other statistics are  
27 preferably measured and stored within Rule-Based Decision Aide 44

1 as each sliding window of data is processed by the Parameter  
2 Estimator 46. FIG. 4 shows the type of information that the  
3 Parameter Estimator provides such as mean and standard deviation  
4 for each increment of the sliding window. In this case, it will  
5 be noticed that curve 54 for the mean 100 window samples, curve  
6 56 for the mean 500 window samples, and curve 58 for the mean  
7 1000 window samples tend to gravitate roughly about the same  
8 approximate values. The standard deviations 60, 62, and 64 of  
9 the three different window sample sizes are somewhat more  
10 variable. This information is fed to Rule-Based Decision Aid 44  
11 to be acted upon based on the rules provided therein and to be  
12 available if required to further describe the selected  
13 probability distribution.

14 Rule-Base Decision Aide 44 uses the inputs from the  
15 Parameter Estimator 46 and Neural Networks 26-36 to decide what  
16 type of distribution best describes the data samples. FIG. 5  
17 provides a block diagram of the components of Rule-Based Decision  
18 Aide 44. As neural networks 26-36 and Parameter Estimator 46  
19 process the data, the outputs of these functions are stored in  
20 Database 48. Then Data Evaluator 50 processes and examines these  
21 outputs (like the ones seen in Figures 3 and 4) to determine if  
22 the progressively larger sliding windows have produced less  
23 variability in the ANN 26-36 and Parameter Estimator 46 outputs.  
24 If the standard deviation and/or mean of the outputs calculated  
25 by the Data Evaluator 50 do not significantly change as the  
26 sliding window size increases, the decision is made to STOP  
27 processing and any one of the sample neural network outputs may

1 be utilized. If the standard deviation does decrease with window  
2 size, the outputs corresponding to the 1000 sample sliding window  
3 are averaged to get the most representative single values for ANN  
4 Uniform output 36, ANN Gaussian output 30. These values along  
5 with the normalized mean and standard deviation (Parameter  
6 Estimator 46) outputs, are passed along to Decision Logic  
7 component 52 in FIG. 5. This component classifies the  
8 Probability Distribution based on a pre-determined logic scheme.

9 For example, in one logic scheme, if the ANN Uniform mean  
10 output is between 0.0 and 0.5, and the ANN Gaussian mean output  
11 is between 0.5 and 1.0, then Rule-Based Decision Aide 44 decides  
12 the data fits most closely to a Gaussian probability  
13 distribution. On the other hand, if the mean ANN Uniform output  
14 is between 0.5 and 1.0, and the mean ANN Gaussian output is  
15 between 0.0 and 0.5, then Rule-Based Decision Aide 44 decides the  
16 data fits most closely to a Uniform probability distribution.  
17 However, if the mean ANN Uniform output and the mean ANN Gaussian  
18 output are both within a selected range around 0.5, then Rule-  
19 Based Decision Aide 44 decides that more data is needed and the  
20 data processing continues using larger windows as discussed  
21 above. Other logic schemes can be utilized which will relate to  
22 the value for which each group of neural networks have been  
23 trained to output for the probability distribution the respective  
24 group of neural networks is trained to recognize.

25 As mentioned earlier, each of the six neural networks (ANN)  
26 are trained in advance, each with a different sliding window  
27 size. Each ANN Uniform network 32-36 is trained on data that is

1 known in advance to be uniformly distributed data. This data can  
2 be generated using one of many commercially available uniform  
3 random number generators. The ANN Uniform adaptive elements 32-  
4 36 will be trained to converge to values that produce an output  
5 close to 1 when the input data is Uniformly distributed and close  
6 to 0 if it is not. Hence, the output of each Uniform neural  
7 network 32-36 when processing non-training data will be a value  
8 between 0 and 1 that will indicate how close the data matches  
9 uniformly distributed data. Likewise, the ANN Gaussian networks  
10 26-28 are trained on data that is known in advance to be Gaussian  
11 distributed data. This data can be generated using one of many  
12 commercially available Gaussian random number generators. This  
13 training process is more complicated because the ANN Gaussian  
14 networks are trained to recognize Gaussian data regardless of the  
15 mean or Standard deviation. Training will consist of using data  
16 characterized by different means or standard deviations. The  
17 range of standard deviations will be 0 to 1 in increments of 0.1;  
18 the range of means will be -1 to +1 in increments of 0.1. The  
19 output will be 1 if the input data is Gaussian.

20 The advantage that this disclosure provides is the increased  
21 statistical knowledge about a data set with probability  
22 characteristics that are unknown. This disclosure enables one to  
23 process the data and classify the probability distribution. The  
24 process is performed automatically, is not an iterative process,  
25 and does not involve visual examination or the implementation of  
26 mathematical measures of confidence. Furthermore, the disclosure  
27 may be extended to include any other distribution.

1           Many additional changes in the details, materials, steps and  
2 arrangement of parts, herein described and illustrated to explain  
3 the nature of the invention, may be made by those skilled in the  
4 art within the principle and scope of the invention. It is  
5 therefore understood that within the scope of the appended  
6 claims, the invention may be practiced otherwise than as  
7 specifically described.

1 Attorney Docket No. 79833

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PROBABILITY DISTRIBUTION CLASSIFICATION PROCESSOR

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ABSTRACT OF THE DISCLOSURE

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A system and method are disclosed which preferably comprises

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several groups of artificial neural networks (ANNs) for

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classifying the probability distribution of random data. Each

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group of artificial neural networks is preferably trained to

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produce a selected output in response to data having a particular

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probability distribution. Each of the group of artificial neural

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networks preferably analyzes a different sample size of data. A

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parameter estimator module calculates statistical parameters for

15

the different size data samples. The outputs of the several

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groups of artificial networks and of the parameter estimator are

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analyzed by a rule based decision logic module which then selects

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the type of probability distribution that best describes the

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random data based on rules that correspond to ranges of values of

20

the outputs of the artificial neural networks.

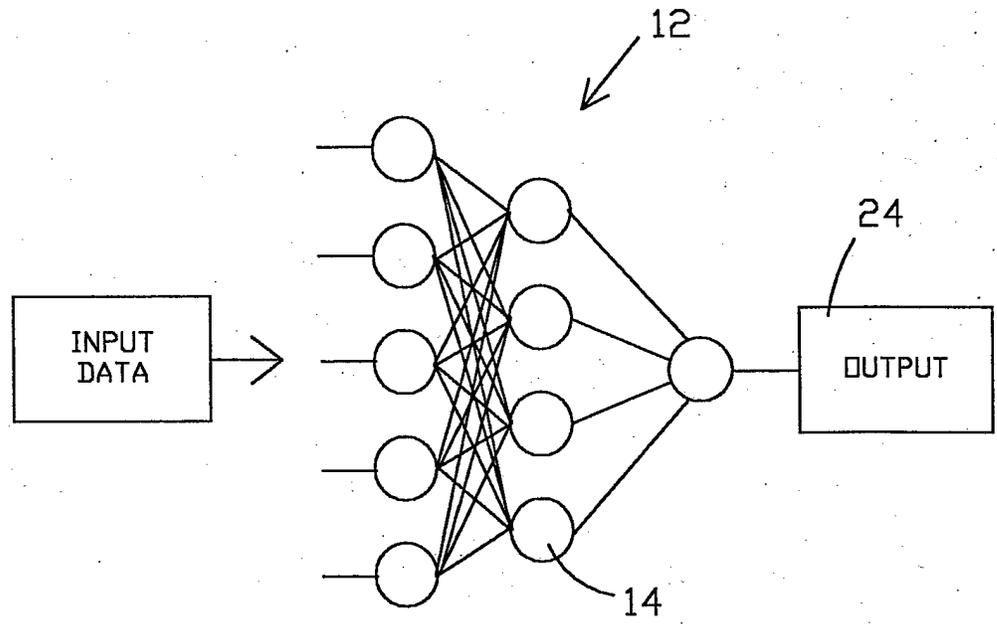


FIG. 1A

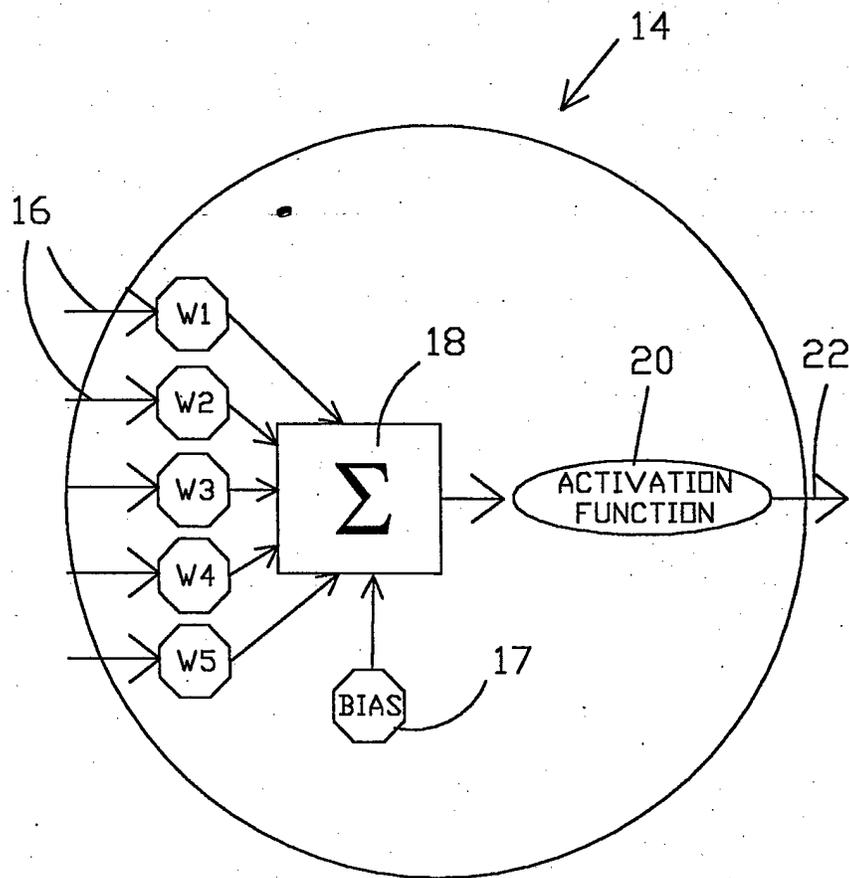


FIG. 1B

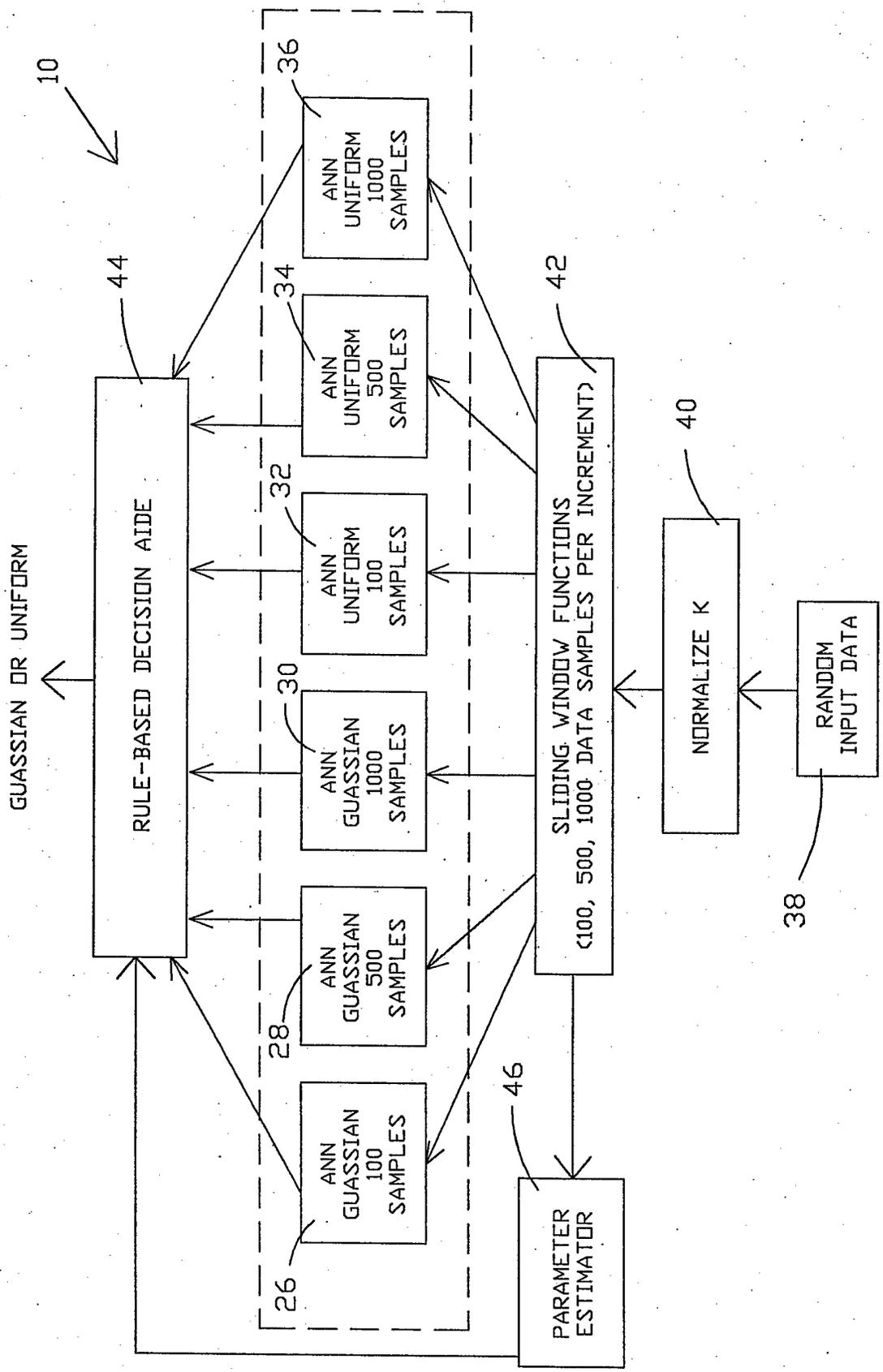


FIG. 2

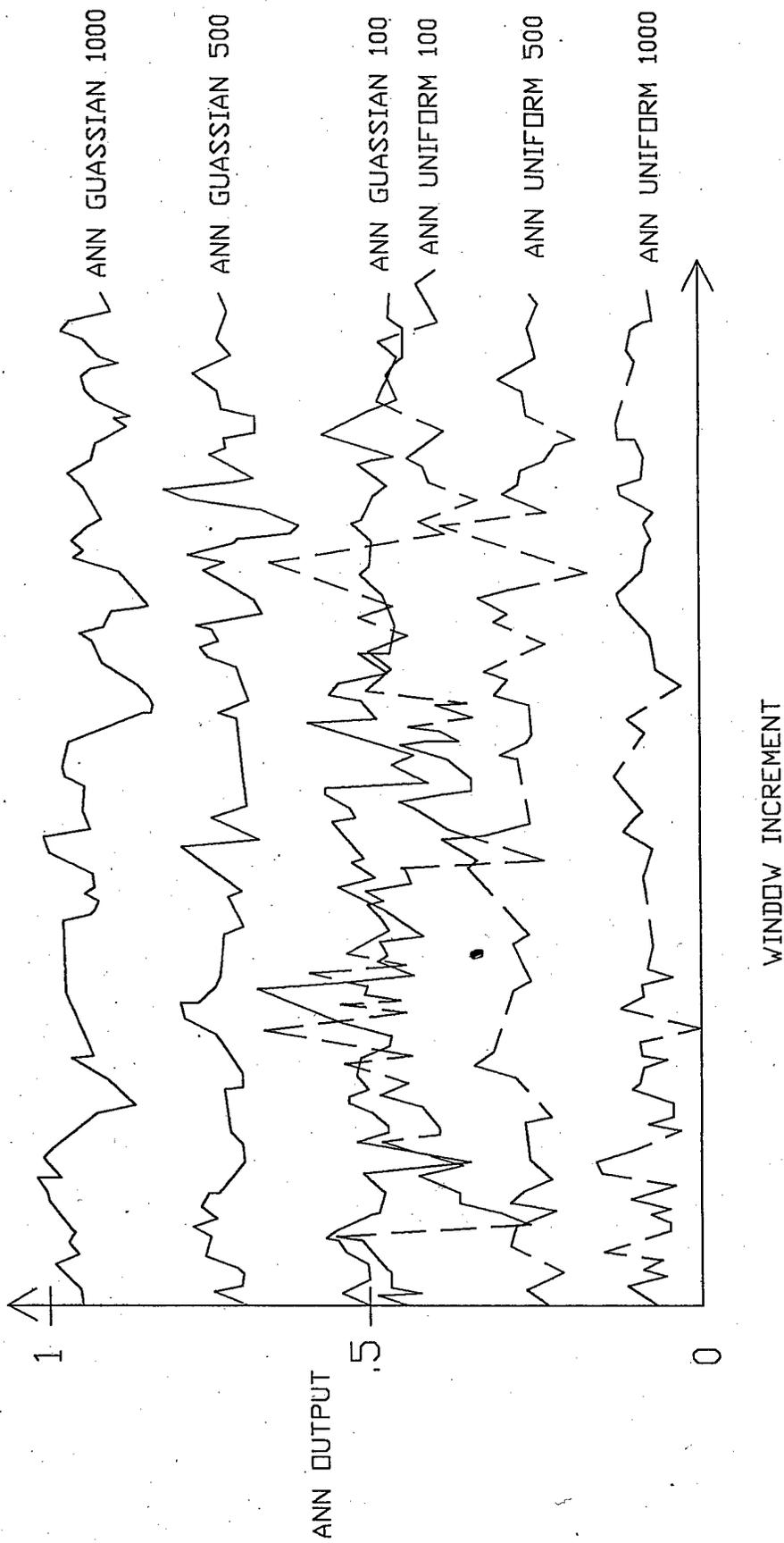


FIG. 3

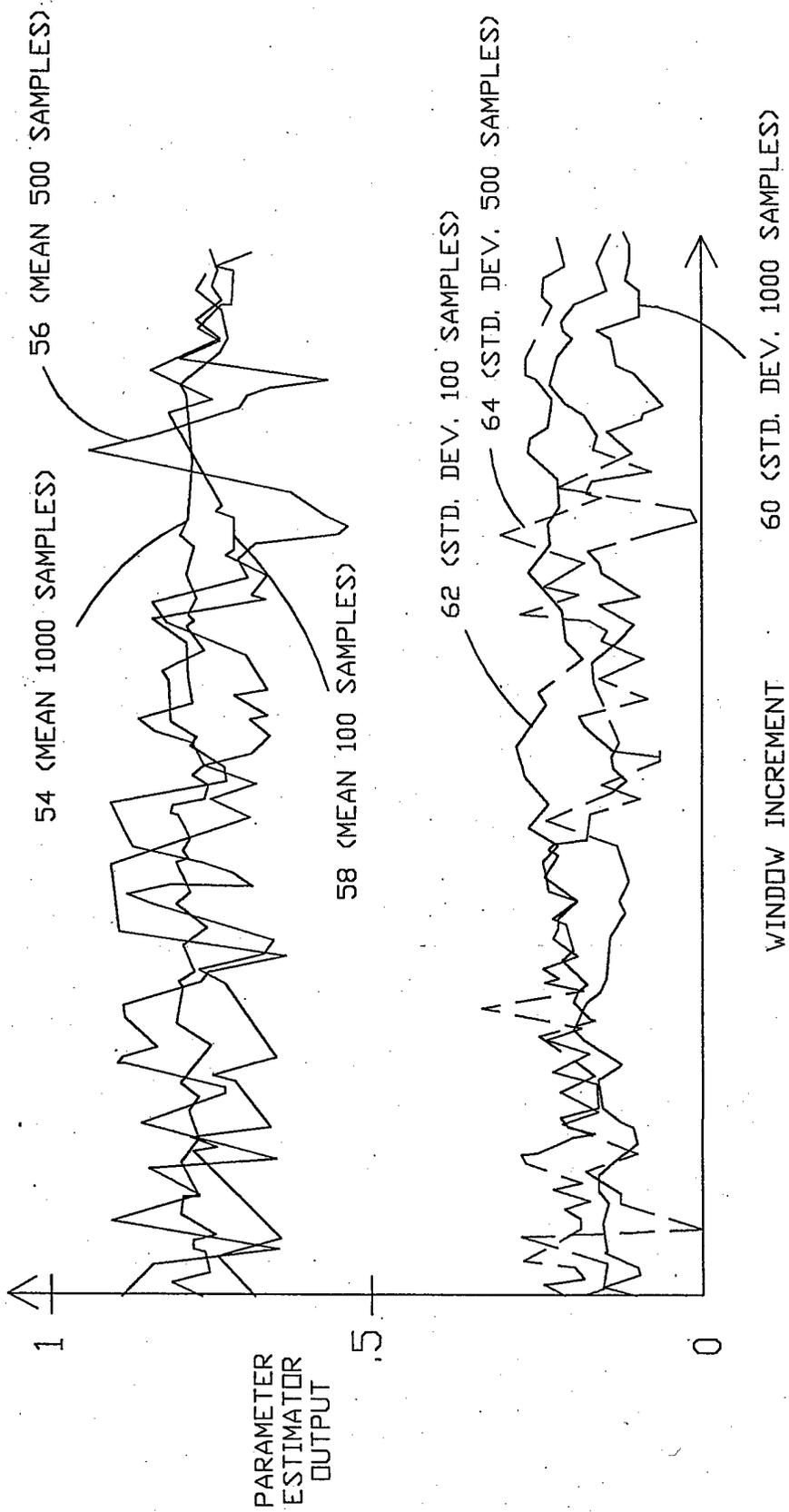


FIG. 4

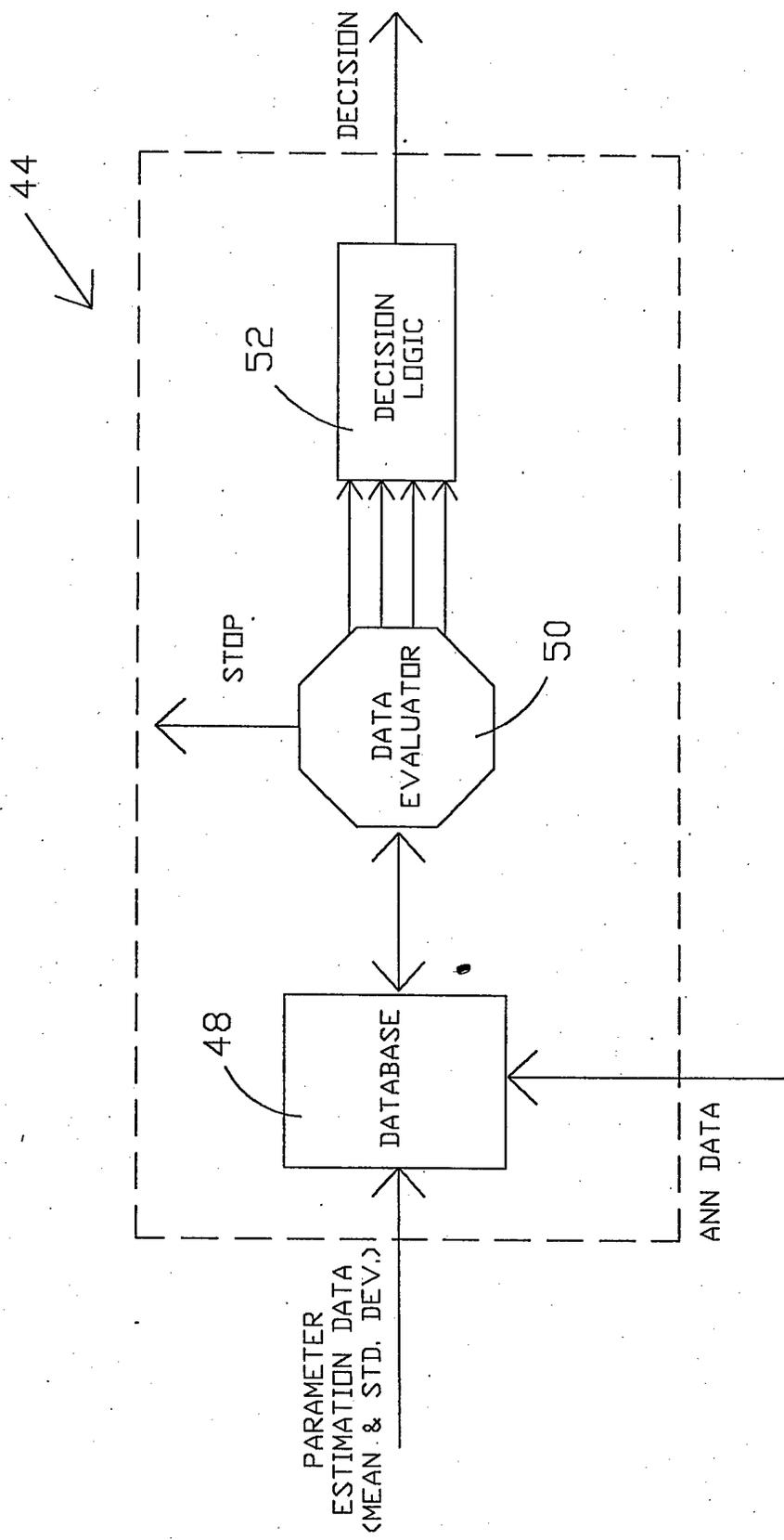


FIG. 5