

Serial Number            09/677,649  
Filing Date              3 October 2000  
Inventor                 Daniel W. French  
                              John J. Vaillancourt  
                              Edward R. Levine

NOTICE

The above identified patent application is available for licensing. Requests for information should be addressed to:

OFFICE OF NAVAL RESEARCH  
DEPARTMENT OF THE NAVY  
CODE 00CC  
ARLINGTON VA 22217-5660

**DISTRIBUTION STATEMENT A**  
Approved for Public Release  
Distribution Unlimited

20011126 136

2  
3 A RIGID STING EXTENSION FOR OCEAN TURBULENCE  
4 MEASUREMENT FROM AN UNMANNED UNDERWATER VEHICLE  
5

6 STATEMENT OF GOVERNMENT INTEREST

7 The invention described herein may be manufactured and used  
8 by or for the Government of the United States of America for  
9 governmental purposes without the payment of any royalties  
10 thereon or therefor.  
11

12 BACKGROUND OF THE INVENTION

13 (1) Field of the Invention

14 The present invention relates to a system for mounting  
15 turbulence sensors in front of an unmanned underwater vehicle  
16 undisturbed from the hydrodynamic effects of the leading edge or  
17 nose of the unmanned underwater vehicle.

18 (2) Description of the Prior Art

19 Underwater vehicles, manned and unmanned, have been used for  
20 a variety of different purposes. Depending upon the purpose, one  
21 or more sensors may be mounted to the vehicle. For example, U.S.  
22 Patent No. 5,425,001 to Polvani illustrates a method and  
23 apparatus for navigating a killer vehicle towards a mine emitting  
24 underwater a magnetic field by using measurements of the mine's  
25 magnetic field. The measurements are gathered by at least two  
26 magnetic sensors affixed to the killer vehicle.  
27

1        Some underwater vehicles are provided with a folded  
2        hydrophone array in their nose, which array forms part of a  
3        forward-looking sonar for obstacle avoidance, mine detection, and  
4        the like. U.S. Patent Nos. 5,363,343 to Klein and 5,602,801 to  
5        Nussbaum et al. illustrate such vehicles.

6        Yet other underwater vehicles have been provided with  
7        acoustic transducer means for detecting the presence of a target  
8        mounted to a nose portion of the underwater vehicle. U.S. Patent  
9        No. 4,079,687 to Mentcher, for example, illustrates one such  
10       vehicle having a detachable acoustic acquisition system mounted  
11       to the nose of the vehicle.

12       Unmanned underwater vehicles also have been used to collect  
13       ocean turbulence data; however, the sensors have been mounted on  
14       these vehicles in a way which allowed the hydrodynamic effects of  
15       the unmanned underwater vehicles to interfere with the data  
16       gathering operations.

#### 17       SUMMARY OF THE INVENTION

18       Accordingly, it is an object of the present invention to  
19       provide an underwater vehicle which can be used to collect ocean  
20       turbulence data without interference from the hydrodynamic  
21       effects of the vehicle.

22       It is a further object of the present invention to provide  
23       an improved system for mounting sensors to the nose of an  
24       underwater vehicle.  
25

1           It is yet a further object of the present invention to  
2 provide an improved mounting system which documents and removes  
3 any noise caused by the mounting system.

4           These and other objects are accomplished with the present  
5 invention by providing a system for collecting ocean turbulence  
6 data which includes an underwater vehicle having a means for  
7 collecting ocean turbulence data without interference from the  
8 hydrodynamic effects of the vehicle. The data collecting means  
9 comprises at least one sensor for collecting the ocean turbulence  
10 data and means for positioning the at least one sensor  
11 sufficiently forward of the nose of the vehicle to avoid  
12 interference from the hydrodynamic effects of the vehicle. The  
13 data collecting means is also provided with means for  
14 compensating for motion not induced by turbulence.

15           Other details of the present invention, as well as other  
16 objects and advantages attendant thereto, are set forth in the  
17 following description and the accompanying drawings in which like  
18 reference numerals depict like elements.

#### 19           BRIEF DESCRIPTION OF THE DRAWINGS

20           FIG. 1 is a side sectional view of an unmanned underwater  
21 vehicle having a system for mounting turbulence sensors in  
22 accordance with the present invention;

23           FIG. 2 is an enlarged sectional view of the system for  
24 mounting turbulence sensors to the nose of an unmanned underwater  
25 vehicle; and  
26

FIG. 3 is a front view of a stinger used to mount the turbulence sensors to the nose of the unmanned underwater vehicle.

#### DESCRIPTION OF THE PREFERRED EMBODIMENTS

Referring now to the drawings, FIG. 1 illustrates an unmanned underwater vehicle 10 having a plurality of turbulence sensors 12 mounted to the forward end or the nose portion 14 of the vehicle 10 by a stinger 16. Referring now to FIGS. 2 and 3, the stinger 16 is rigidly mounted to the nose portion 14 of the vehicle 10. The stinger 16 preferably is formed by a tapered cylindrical housing 18. In a preferred embodiment of the present invention, the housing 18 is joined to the nose portion 14 by a bolt ring 20 which may also provide a water tight seal if required. The housing 18 may be formed from any suitable material known in the art which is capable of withstanding the depths at which the vehicle 10 is intended to operate and which is waterproof. For example, the housing 18 may be formed from a high strength, lightweight metallic material.

As shown in FIGS. 2 and 3, the forward end 22 of the housing 18 has a plurality of apertures 24 for receiving and accommodating the sensors 12. The apertures 24 may be arranged in any desired manner. For example, there may be seven apertures 24 with six of the apertures being arranged in a circle and the seventh aperture being positioned at the center of the circle. Turbulence sensors 12 are positioned in the apertures 24 and have leading edges 26 which are located in front of the forward end 22

1 of the housing 18. The housing 18 has a length sufficient to  
2 position the sensors 12 so that they are not disturbed by  
3 hydrodynamic effects of the nose portion 14 of the vehicle 10.

4 The turbulence sensors 12 may comprise any suitable sensors  
5 known in the art for measuring hydrodynamic turbulence.

6 Preferably, the turbulence sensors 12 are shear detectors that  
7 are capable of detecting transverse shear. This includes shear  
8 in vertical and athwartship directions. Typically, the sensors  
9 12 cannot detect shear in an axial direction.

10 It is desirable that the data being gathered by the sensors  
11 12 be gathered in a non-corrupt manner. To this end, one or more  
12 accelerometers 28 are positioned within the base of the housing  
13 18. The accelerometers 28 may be secured in a block as shown in  
14 FIG. 2. The purpose of the accelerometers 28 is removing  
15 vibrational noise caused by the stinger itself from the  
16 turbulence data.

17 A monitoring device 30 is positioned within the nose 14 of  
18 the vehicle 10. The monitoring device 30 can be any suitable  
19 means known in the art for collecting the data gathered by the  
20 sensors 12 and storing it for later downloading and  
21 documentation. A stinger communication cable 32 extends between  
22 the accelerometers 28 and each of the sensors 12. A data cable  
23 34 connects the monitoring device 30 to the accelerometers 28 and  
24 the turbulence sensors 12. The accelerometers 28 detect motion  
25 caused by the vehicle 10 so as to compensate for motion not  
26 induced by turbulence. In a preferred embodiment, the cable 32  
27

1 is mounted to a rigid structure. This allows the cable to be  
2 secured and aligned inside the stinger 16.

3 The principal advantage of the system for mounting  
4 turbulence sensors in front of an unmanned underwater vehicle of  
5 the present invention is that it allows data to be collected in  
6 its pure form. There are no disturbances from the unmanned  
7 underwater vehicle. Further, any vibration noise from the  
8 stinger is documented and removed.

9 The mounting system of the present invention allows a wide  
10 range of probes or sensors to be used. Overall size and length  
11 could be changed depending on the nature of the data to be  
12 collected.

13 While the mounting system of the present invention has been  
14 described in the context of unmanned underwater vehicles, it  
15 should be recognized that it could also be used on manned  
16 underwater vehicles.

17 While the housing 18 has been shown as having a plurality of  
18 apertures 24, it is possible to construct the housing 18 with a  
19 single aperture for housing a single sensor.

20 It is apparent that there has been provided in accordance  
21 with the present invention a rigid sting extension for ocean  
22 turbulence measurement from an unmanned underwater vehicle which  
23 fully satisfies the means, objects and advantages set forth  
24 hereinbefore. While the present invention has been described in  
25 the context of particular embodiments thereof, it is apparent  
26 that there are many alternatives, modifications, and variations  
27 which could be made. It is intended to embrace such

1 alternatives, modifications, and variations,

2



1 Attorney Docket No. 78733

2  
3 A RIGID STING EXTENSION FOR OCEAN TURBULENCE  
4 MEASUREMENT FROM AN UNMANNED UNDERWATER VEHICLE

5  
6 ABSTRACT OF THE DISCLOSURE

7 The present invention relates to a system for collecting  
8 ocean turbulence data without interference from the hydrodynamic  
9 effects of the vehicle. The ocean turbulence data collection  
10 system comprises an underwater vehicle, such as an unmanned  
11 underwater vehicle, at least one sensor for collecting the ocean  
12 turbulence data, and a stinger arrangement mounted to the nose  
13 portion of the vehicle for positioning the at least one sensor  
14 sufficiently forward of the nose portion of the vehicle to avoid  
15 interference from the hydrodynamic effects of the vehicle. The  
16 collection system is also provided with at least one  
17 accelerometer for compensating for motion not induced by  
18 turbulence.

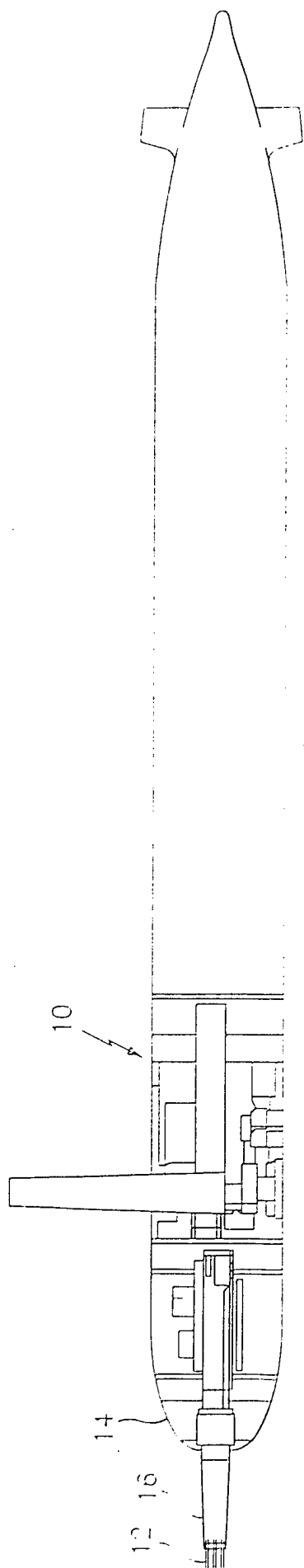


FIG. 1

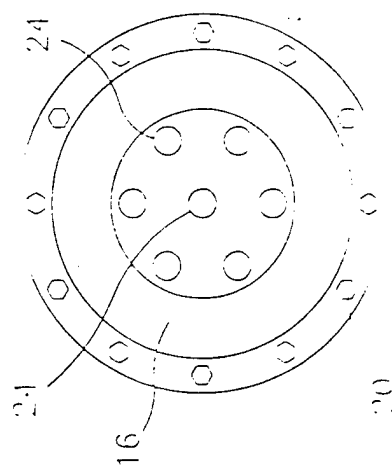


FIG. 3

