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3 PRECISION MICROWAVE/MILLIMETER WAVE

4 MODULATED SIGNAL SOURCE

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6 STATEMENT OF GOVERNMENT INTEREST

7 The invention described herein may be manufactured and
8 used by or for the Government of the United States of America for
9 Governmental purposes without the payment of any royalties
10 thereon or therefor.

11

12 BACKGROUND OF THE INVENTION

13 (1) Field of the Invention

14 The present invention relates to a variable frequency
15 signal generator.

16 (2) Description of the Related Art

17 Previously, to perform injected signal measurements to
18 verify system performances required multiple bulky pieces of
19 expensive test equipment. This equipment often would not easily
20 provide the pulse to pulse parameter agility with the accuracy
21 and stability offered by the invention described herein.

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1 spectrum is then modulated by a programmed high precision pulse
2 repetition interval (PRI) signal coming from a circuit board
3 containing pulse characteristics as small as 1 nanosecond (s)
4 pulsewidth. One frequency picket at a time is filtered by a
5 yttrium iron garnet (YIG) filter and appropriate attenuation is
6 set by a digitally variable attenuator to yield the desired
7 precision microwave/millimeter modulated signals.

8

9 BRIEF DESCRIPTION OF THE DRAWINGS

10 A more complete understanding of the invention and many
11 of the attendant advantages thereto will be readily appreciated
12 as the same becomes better understood by reference to the
13 following detailed description when considered in conjunction
14 with the accompanying drawings wherein like reference numerals
15 refer to like parts and wherein:

16 FIG. 1 is a block diagram of the overall system; and

17 FIG. 2 is a block diagram of the circuit board.

18

19 BRIEF DESCRIPTION OF THE PREFERRED EMBODIMENT

20 The preferred embodiment of the invention is discussed.
21 While specific part numbers, implementations, and configurations

1 are discussed, it should be understood that this is done for
2 illustration purposes only. A person skilled in the relevant art
3 will recognize that other components, implementations, and
4 configurations may be used without departing from the spirit and
5 scope of the invention.

6 With reference to FIG. 1, signal source generator 10
7 outputs RF test signals to various frequency bands. A miniature
8 oscillator 12 injects a low frequency at high power. This output
9 is fed into a step recovery diode 14 which generates many combed
10 output frequencies. In the disclosed embodiment, oscillator 12
11 is a 500 megahertz (MHZ) oscillator with 30 dBm output power, and
12 step recovery diode 14 is a 500 MHZ step recovery diode. The
13 output of step recovery diode 14 is a spectrum of frequencies
14 from 2-18 GHz, with 500 MHZ apart comb pickets. This spectrum is
15 then modulated with desired PRI by p-type intrinsic n-type (PIN)
16 diode 16. The output is a broad band spectrum of variable width
17 pulses and variable pulse repetition intervals. One frequency
18 picket at a time is filtered by YIG filter 18. A digitally
19 variable attenuator 20 is then applied to set the appropriate
20 attenuation for each pulse of the output signal.

1 The present invention uses three relays 24, 26, and 28
2 to switch between four RF paths (Bands 1, 2, 3 and 4). Relay 24
3 switches the signal between Bands 1 and 2 and Bands 3 and 4.
4 Relay 26 further routes the signal between Band 1 (2-8 GHz) and
5 Band 2 (8-18 GHz). Relay 28 further routes the signal between
6 Band 3 (18-26.5 GHz) and Band 4 (27-39 GHz). To achieve these
7 higher frequencies with the preferred embodiment, tripler 30 is
8 used to take regular 6-13 GHz pickets and obtain 18-39 GHz (i.e.,
9 three times the value of the lower frequency).

10 With reference also to FIG. 2, all the controls to the
11 RF components in the present invention come from circuit board
12 22. Part numbers are shown in parentheses on FIG. 2 for
13 illustrative purposes only. A person skilled in the art will
14 recognize that other parts may be substituted and still be within
15 the scope of the present invention.

16 With power supplied to circuit board 22, it
17 accomplishes the following tasks:

- 18 a. Output attenuation control DVA0-DVA7 to
19 attenuator 20;
- 20 b. Output YIG tuning control TUNE0-TUNE11 to YIG
21 filter 18;

- c. Output relay control RLY0-RLY5 to relays 24,
26, and 28;
- d. Output high precision PRI with pre-programmed
pulse characteristics as small as 10 ns pulsewidth
to PIN diode 16; and
- e. Capability of tuning digital attenuator 20 and
YIG filter 18.

In operation of the present invention, circuit board 22 is directed to accomplish its tasks by a microprocessor 32, which is programmed to either a routine of generating test signals or a routine to adjust attenuation and YIG filter hysteresis. In the first routine, the RF output is modulated according to the pre-programmed PRI, and in the second routine the frequencies are passed as continuous wave (CW). To generate pulses, the program describes pulse characteristics in time, such as a pulse is on or high for 200 μ s and then it is off or low for 5 μ s. At the time of execution, this information is loaded into a set of first-in, first-out memories 34, 36, and 38 (FIFOs). FIFOs 34, 36, and 38 are basically a table of pulse descriptions from which one line at a time is provided to a programmable logic device 40. Device 40 functions as a highly accurate and reliable counter.

1 Programmable logic device 42 receives time intervals from the
2 counter (device 40) to output a pulse where the output Q is
3 appropriately high or low. Additional precision to the pulse
4 characteristics is added by delay line 44, which defines pulses
5 to the accuracy of 1 ns.

6 For any given test signal, circuit board 22 has the
7 capability to add more attenuation to any RF test signal. The
8 attenuation is controlled by writing an 8-bit value (DVA0-DVA7)
9 to latch 46, which latches the value for digital attenuator 20.
10 This value can be adjusted for every picket and the desirable
11 power level can be obtained. Here, every bit adds 0.25 dB
12 attenuation, thus 0xFF gives the maximum attenuation step of 32
13 dB. If a constant power level of, say, -50 dB is desired for all
14 then all the pickets can be lowered to -50 dB, one by one, when a
15 picket is filtered. Circuit board 22 also implements the
16 capability to store the desired attenuation settings in a static
17 random access memory 48 (SRAM) table which can be recalled for
18 any pre-programmed configuration.

19 The circuit board 22 is also capable of tuning the YIG
20 filter 18. There are two issues with YIG filter 18. The first
21 is parking YIG filter 18 around a desired picket frequency, and

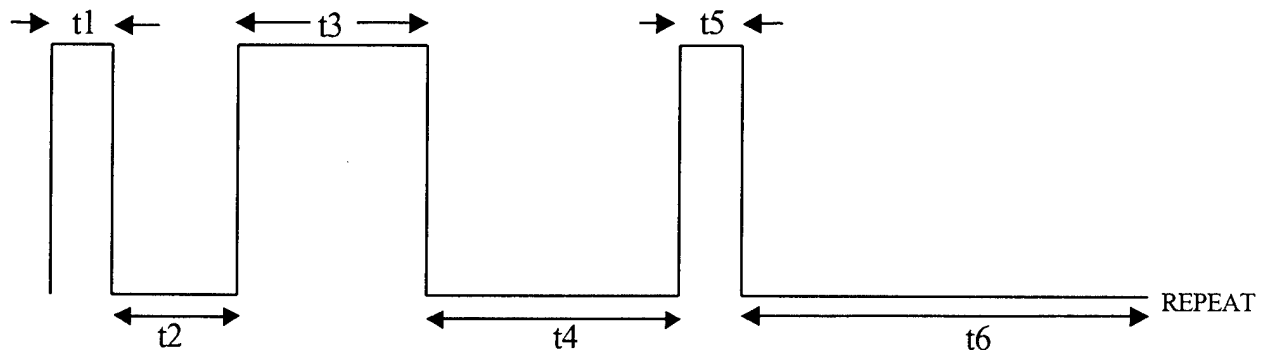
1 the second is making necessary adjustment for any frequency drift
2 caused by temperature, linearity and hysteresis. Parking of YIG
3 filter 18 is predetermined for the designed unit by 12-bit values
4 (TUNE0-TUNE11) where 0xFFF-0x000 covers 2-18 GHz. Since pickets
5 out of comb generator 14 are 500 MHz apart, a value of 0xF7F
6 moves YIG filter 18 to 2.5 GHz, and a value of 0xEFF takes it to
7 3.0 GHz and so on. This tuning is accomplished by writing TUNE0-
8 TUNE7 to a latch 50 and TUNE8-TUNE11 to programmable logic device
9 52 that provides four latched lines for the four most significant
10 bits (MSB) of tuning word.

11 The second issue regarding the frequency drift is
12 solved by adding an 8-bit offset value to the tuning word. This
13 offset can slightly move the filter either to the right or left
14 of the predetermined parked frequency, depending on positive or
15 negative offset value. Here 0x01 offset adjusts the drifted
16 frequency to approximately 0.04 MHz and 0x1B offset adjusts to 1
17 MHz. Circuit board 22 also implements the capability to store
18 the desired offset settings in SRAM 48 table which can be
19 recalled for any pre-programmed configuration.

20 Device 52 provides five latched lines to switch relays
21 24, 26, and 28 from either normally closed position to normally

1 open path. The designed unit uses three relay lines RLY0-RLY2 at
2 relay 24 to first split 2-18 GHz signals from 18-39 GHz which
3 comes from tripled 6-13 GHz. Relays 26 and 28 split 2-8 GHz from
4 8-18 GHz; and 18-26.5 GHz from 26-40 GHz. These relays are set
5 appropriately by microprocessor 32 according to wherever YIG
6 filter 18 is tuned.

7 Any complex pulse description can be characterized by
8 following intervals of on or off periods:



9 where, for example $t_1=120$ ns is the time interval that the first
10 pulse is on or high;
11
12 $t_2=500$ ns is the time interval that the first
13 pulse is out or low;
14
15 $t_3=368$ ns is the time interval that the
16 second pulse is on or high;
17
18 $t_4=1\mu$ s is the time interval that the second
19 pulse is off or low;
20
21 $t_5=12$ ns is the time interval that the third
22 pulse is on or high; and

t6=3 μ s is the time interval that the third pulse is off or low.

And, after (120 ns+500 ns+368 ns +1 μ s +12 ns +3 μ s) = 5 μ s, the sequence is repeated.

Using these characteristics, the FIFO table can be filled. The time intervals can be translated into a binary number, where an integer of two 8-bit words define a value of 50 ns/bit with fine resolution defined by a 6-bit word with a value of 1 ns/bit. The FIFO table also keeps track of the on or off state by a control bit. Another control bit determines the end of the table from where the pulses are to repeat themselves, resulting in a pulse repetition frequency.

The FIFO table contains the following:

Time Int.	CNT 0	CNT 1	FRES 0-5 (fine res)	HIGH BYTE	LOW BYTE
	0=more entry	0=off state	all zeros = no fine res.	all ones = no high byte	all ones = no low byte
	1=end of table	1=on state	1 ns/bit	50 ns/bit (D8-D15)	50 ns/bit (D0-D7)
t1 120ns ON	0	1	01 0011	1111 1111	1111 1101
t2 500ns OFF	0	0	00 0000	1111 1111	1111 0110

t3 368ns ON	0	1	01 0001	1111 1111	1111 1001
t4 1µs OFF	0	0	00 0000	1111 1111	1110 1100
t5 12ns ON	0	1	00 1100	1111 1111	1111 1111
t6 3 µs OFF	1	0	00 0000	1111 1111	1100 1000
EOT Repeat					

1
2 In the circuit of the present invention, the LOW BYTE values
3 are passed to FIFO 34, HIGH BYTE values are passed to FIFO 36,
4 and CNT 0, CNT 1, FRES 0-5 values are passed to FIFO 38. Device
5 40 is a 16-bit counter that counts up to 0xFF and receives next
6 timing interval from FIFOs 34, 36, and 38. Device 42 keeps track
7 of the output pulse, Q, being high or low through a flip-flop
8 (not shown, e.g., 74AC74). If any fine resolution component is
9 to be added to the pulse characteristic, delay line 44 counts
10 down to 0x00; and the delay is combined by a NOR gate (not shown,
11 e.g., 74F02) for the flip-flop.

12 The present invention also provides for capability of tuning
13 digital attenuator 20 and YIG filter 18 for any unique output at
14 the end. Four control lines allow the manipulation of the
15 microprocessor, from which one can write to SRAM 48. The values
16 for attenuation and YIG offset can be stored and recalled for
17 desired output power level and for adjustments to the YIG

1 hysteresis. Two of the lines provide unlimited programming
2 capability via serial communication with the microprocessor.

3 The precision microwave/millimeter wave modulated signal
4 source is a relatively low cost, compact, highly accurate and
5 stable signal source covering the 2 to 40 GHz frequency range.
6 The highly accurate and versatile selection of signal parameters
7 along with its compact size makes this design useful as an
8 embedded built in test signal source.

9 It will be understood that many additional changes in the
10 details, materials, steps, and arrangement of parts, which have
11 been herein described and illustrated in order to explain the
12 nature of the invention, may be made by those skilled in the art
13 within the principle and scope of the invention.

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3 PRECISION MICROWAVE/MILLIMETER WAVE

4 MODULATED SIGNAL SOURCE

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6 ABSTRACT OF THE DISCLOSURE

7 The precision microwave/millimeter wave modulated
8 signal source is a relatively low cost, compact, highly accurate
9 and stable signal source covering the 2 to 40 Gigahertz frequency
10 range. The pulse width and amplitude level of the output signal
11 can be changed on every pulse in the signal pulse train. Pulse
12 width range is 5 nanoseconds to 1 millisecond. Pulse repetition
13 intervals can be changed between each pulse set with usable range
14 from 10 nanoseconds to 100 milliseconds. Interval parameters can
15 be adjusted with 1 nanosecond resolutions with stabilities of +/-
16 200 picoseconds. The highly accurate and versatile selection of
17 signal parameters, along with its compact size, makes this design
18 useful as an embedded built in test signal source. This built in
19 signal source can be used for verification of system performance
20 for many electronic warfare systems.

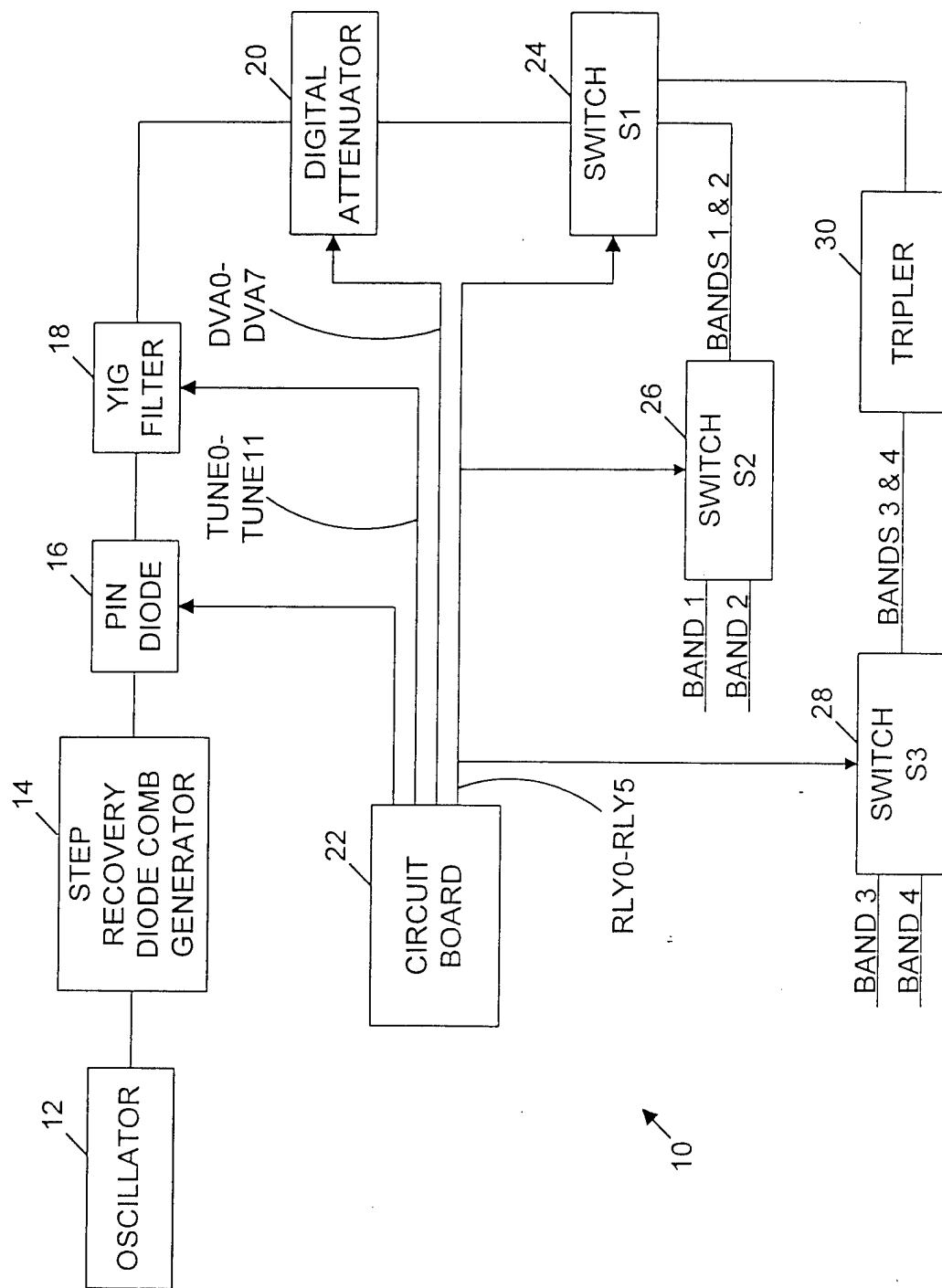


FIG. 1

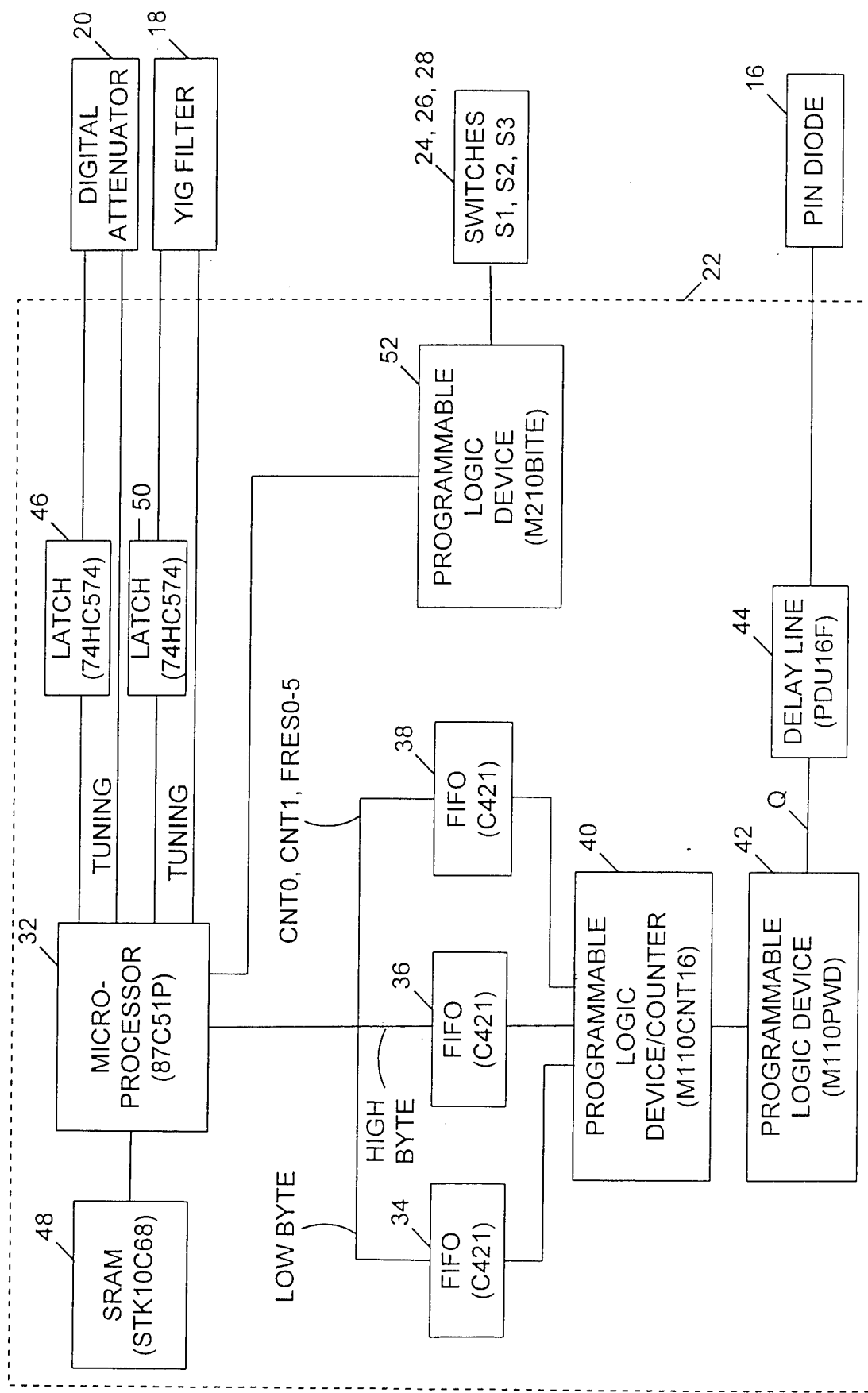


FIG. 2