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**DTIC QUALITY INSPECTED 1**

2  
3 A MARINE PROPULSION SYSTEM FOR UNDERWATER VEHICLES

4  
5 STATEMENT OF GOVERNMENT INTEREST

6 The invention described herein may be manufactured and used  
7 by or for the Government of the United States of America for  
8 governmental purposes without the payment of royalties thereon or  
9 therefor.

10  
11 BACKGROUND OF THE INVENTION

12 (1) Field of the Invention

13 The invention relates to marine propulsion systems and is  
14 directed more particularly to a propulsion system for an  
15 underwater vehicle.

16 (2) Description of the Prior Art

17 Traditional electrically powered marine propulsion systems  
18 generally include (1) an energy source, such as a battery or AC  
19 generator, (2) a power conversion means for converting the  
20 current output of the energy source, (3) an electric motor, (4) a  
21 coupling system for transferring the motor output, which coupling  
22 system usually includes shafts, bearings and linkages, (5) a  
23 propulsor for imparting thrust to the vehicle, and (6) a cooling  
24 system for removing waste heat from the assembly. The cooling  
25 system typically includes a circulation pump, a heat exchanger  
26 and piping. Inasmuch as space is at a premium in underwater

1 vehicles, there is a need to eliminate as many propulsion  
2 components as possible.

3 Further, proper alignment of the motor, coupling system and  
4 propulsor must be maintained. Otherwise, vibrations result  
5 which, in turn, cause noise and wear. In military applications,  
6 noise can lead to early detection and interception, resulting in  
7 failed missions.

8 Still further, in traditional systems the fairing of the  
9 stern portion of a marine vehicle places severe restrictions on  
10 the diameter of the motor. The efficiency of a permanent magnet,  
11 brushless electric motor varies in direct relationship to the  
12 number and length of permanent magnet poles. That is, increasing  
13 the number and/or length of magnet poles increases efficiency,  
14 power density, and output torque. However, because of the  
15 limited space available, the magnet poles necessarily are limited  
16 in number and dimension. There is a need to increase output  
17 torque such that the propulsor can rotate at a lower speed and  
18 operate more efficiently and more quietly.

19  
20 SUMMARY OF THE INVENTION

21 It is, therefore, an object of the invention to provide a  
22 marine propulsion system for underwater vehicles, wherein the  
23 system comprises fewer components, operates more efficiently and  
24 quietly, and in which alignment of components is not a problem.

25 With the above and other objects in view, as will  
26 hereinafter appear, a feature of the present invention is the

1 provision of a marine propulsion system for underwater vehicles,  
2 the propulsion system comprising motor inner stator assemblies  
3 disposed in hull portions of the vehicle, fixed blades extending  
4 outwardly from an after hull portion, a shroud fixed to outer  
5 ends of the fixed blades and encircling the hull portions, and a  
6 motor outer stator assembly disposed in the shroud. A rotor hub  
7 is disposed in an annular formed by the hull portions, the hub  
8 having permanent magnet assemblies therein adjacent the motor  
9 inner stator assemblies, and having blades mounted thereon and  
10 extending outwardly therefrom and comprising permanent magnets,  
11 outer ends of the rotor blades being adjacent the motor outer  
12 stator assembly. Activation of the stator assemblies, preferably  
13 by polyphase A.C. excitation, induces movement in the permanent  
14 magnet assemblies and rotor blades to cause the rotor hub and  
15 rotor blades to rotate. Rotation of the rotor blades serves to  
16 provide propulsive thrust to the vehicle.

17 In accordance with a further feature of the invention, there  
18 is provided a marine propulsion system for underwater vehicles,  
19 the propulsion system comprising a stern hull portion of the  
20 vehicle, a rigid tube extending from an after surface of the  
21 stern hull portion, and an after hull portion fixed to the tube,  
22 the tube and the after hull portion being immovable relative to  
23 the stern hull portion, the after hull portion being spaced from  
24 the stern hull portion to define therebetween an annular recess.  
25 A motor forward stator assembly is disposed in an after surface  
26 of the stern hull portion and defines a forward wall of the

1 recess. A motor after stator assembly is disposed in a forward  
2 surface of the after hull portion and defines an after wall of  
3 the recess. Stator blades are fixed to the after hull portion  
4 and extend outwardly therefrom. A shroud is fixed to outer ends  
5 of the stator blades and encircles the recess. A motor outer  
6 stator assembly is disposed in the shroud. A rotor hub is  
7 disposed in the recess and is rotatable on the tube. Permanent  
8 magnet assemblies are disposed in the rotor hub and are adjacent,  
9 respectively, the motor forward stator assembly and the motor  
10 after stator assembly. Rotor blades comprising permanent magnets  
11 are fixed to and extend outwardly from the rotor hub, the rotor  
12 blades having outer ends adjacent the motor outer stator  
13 assembly. Electrical conductors extend from a power source in  
14 the hull to the motor forward, after, and outer stator  
15 assemblies. Electrical current from the power source is  
16 conducted by electrical conductors to the stator assemblies to  
17 cause the permanent magnet assemblies of the rotor hub and the  
18 rotor blades to move, to cause the rotor assembly to rotate on  
19 the tube. Rotation of the rotor blades serves to provide  
20 propulsive thrust to the vehicle.

21 The above and other features of the invention, including  
22 various novel details of construction and combinations of parts,  
23 will now be more particularly described with reference to the  
24 accompanying drawings and pointed out in the claims. It will be  
25 understood that the particular device embodying the invention is  
26 shown by way of illustration only and not as a limitation of the

1 invention. The principles and features of this invention may be  
2 employed in various and numerous embodiments without departing  
3 from the scope of the invention.  
4

#### 5 BRIEF DESCRIPTION OF THE DRAWINGS

6 Reference is made to the accompanying drawings in which are  
7 shown illustrative embodiments of the invention, from which its  
8 novel features and advantages will be apparent.

9 In the drawings:

10 FIG. 1 is a perspective view of portions of a propulsion  
11 system, illustrative of an embodiment of the invention;

12 FIG. 2 is similar to FIG. 1, but with shroud portions  
13 removed revealing portions of the structure not seen in FIG. 1;

14 FIG. 3 is a sectional view of substantially an upper half of  
15 the propulsion system;

16 FIG. 4 is a partial sectional view normal to the section of  
17 FIG. 3;

18 FIG. 5 is a sectional view through one rotor blade;

19 FIG. 5A is similar to FIG. 5, but shows an alternative  
20 embodiment of rotor blade;

21 FIG. 6 is a front elevational view of a rotor permanent  
22 magnet assembly;

23 FIG. 7 is a front elevational view of a stator windings  
24 assembly;

25 FIG. 8 is a perspective view of a stator inner backing iron;  
26 and

1           FIG. 9 is a perspective view of the stator outer backing  
2 iron.

3  
4                           DESCRIPTION OF THE PREFERRED EMBODIMENTS

5           Referring to FIG. 3, it will be seen that the illustrative  
6 marine propulsion system for underwater vehicles includes a motor  
7 forward inner stator assembly 20 and a motor after inner stator  
8 assembly 22 in a stern hull portion 24 of an underwater vehicle  
9 26. Fixed stator blades 28 extend outwardly from hull portion 24  
10 (FIGS. 2 and 3). A shroud 30 (FIGS. 1 and 3) is fixed to outer  
11 ends of fixed stator blades 28 and encircles hull portion 24. A  
12 motor outer stator assembly 32 is disposed in shroud 30.

13           A rotor hub 40 is disposed in an annular recess 34 in hull  
14 portion 24. Mounted in hub 40 are forward and after permanent  
15 magnet assemblies 42, 44, respectively adjacent motor forward and  
16 after inner stator assemblies 20, 22. Rotor blades 46 comprising  
17 at least in part permanent magnet material, extend outwardly from  
18 rotor hub 40. Outer ends 48 of rotor blades 46 are adjacent  
19 motor outer stator assembly 32.

20           Referring still to FIG. 3, it will be seen that fixed stator  
21 blades 28 are hollow, and that shroud 30 is hollow, and that  
22 electrical conductor means 50 extend from a polyphase A.C. power  
23 source 52, preferably a three phase A.C. source, in hull portion  
24 24, to forward inner stator assembly 20, and through a rigid tube  
25 54 to after inner stator assembly 22, and through hollow stator  
26 blades 28 and hollow shroud 30 to outer stator assembly 32.

1 Preferably, a circular band 56 is fixed to outer ends 48 of  
2 rotor blades 46 (FIGS. 1-4), band 56 being adjacent a windings  
3 portion 58 of outer stator assembly 32 and defining therebetween  
4 a gap 60.

5 As shown in FIGS. 4 and 5, rotor blades 46 may be hollow  
6 with walls 62 formed of a rigid metal, such as steel, and the  
7 hollow interior filled with a permanent magnet material 64, such  
8 as powdered iron, or the like. Alternatively, as shown in FIG.  
9 5A, each rotor blade 46 may constitute a rigid discrete permanent  
10 magnet 66, of magnetized iron, or the like. The rotor blades 46  
11 are polarized such that the outer ends 48 thereof alternate in  
12 polarity, as shown in FIG. 4.

13 Referring to FIGS. 5 and 5A, it will be seen that rotor  
14 blades 46 are of a turbine blade configuration in fore-and-aft  
15 section, and include a rounded leading edge 68, a tapered  
16 trailing edge 70, a generally convex suction side 72, and a  
17 generally concave pressure side 73.

18 As illustrated in FIGS. 1 and 3, shroud 30 in fore-and-aft  
19 section is of a hydrofoil configuration throughout its extent  
20 which, as noted above, encircles vehicle 26.

21 Forward inner stator assembly 20 forms at least in part a  
22 forward wall 74 of recess 34 (FIG. 3), and after inner stator  
23 assembly 22 forms at least in part an after wall 76 of recess 34.  
24 Forward inner stator assembly 20 includes a forward backing iron  
25 78 and a forward winding assembly 80, the latter being spaced  
26 from forward permanent magnet assembly 42 to define forward gap

1 82 therebetween. Similarly, after inner stator assembly 22  
2 includes an after backing iron 84 and an after winding assembly  
3 86, the latter spaced from after permanent magnet assembly 44 to  
4 define after gap 88.

5 Forward and after inner stator assemblies 20, 22 are  
6 interconnected by a rotor hub inner cylinder 90 over which is  
7 disposed rotor hub outer cylinder 91, which together form rotor  
8 hub 40, rotor blades 46 being fixed to outer cylinder 91 which,  
9 in turn, is fixed to inner cylinder 90. Rotor blades 46 may be  
10 formed integrally with outer cylinder 91.

11 Hub 40 is annularly shaped and is rotatably mounted on tube  
12 54, as by bearings 94. Fixed to an after end of tube 54 is an  
13 after hull portion, or fairwater, 95. Hull portions 24 and 95  
14 form therebetween recess 34. The inner stator assembly 20 is  
15 disposed in hull portion 24 and the after inner stator assembly  
16 22 is disposed in hull portion 95 (FIG. 3).

17 Outer stator assembly 32 includes outer windings 58 and an  
18 outer back iron 96, windings 58 forming the bottom of a recess 98  
19 in an inside surface 112 of shroud 30, recess 98 receiving  
20 circular band 56 and rotor blade outer ends 48.

21 Forward winding assembly 80 (FIG. 7) comprises a ring 100  
22 having thereon a series of windings 102, all in electrical  
23 communication with conductor means 50 (FIG. 3). After winding  
24 assembly 86 similarly comprises a ring having thereon a series of  
25 windings, all in electrical communication with conductor means  
26 50. In FIG. 7, there is illustrated forward winding assembly 80.

1 After winding assembly 86 is substantially of the same  
2 configuration, size and structure as forward winding assembly 80.  
3 The windings 102, 102' and 102" of both the forward and after  
4 winding assemblies 80, 86 are respectively disposed substantially  
5 parallel to opposing surfaces 104 of forward permanent magnet  
6 assembly magnets 108 and after permanent magnet assembly magnets.  
7 Preferably, the windings are in sets of three to receive  
8 polyphase excitation from the polyphase A.C. source 52. In FIGS.  
9 3 and 6, there is shown forward permanent magnet assembly 42  
10 comprising a ring 110 having therein magnets 108 of alternating  
11 polarity, and a rotor backing iron 114. Similarly, the after  
12 permanent magnet assembly 44 comprises a ring having therein  
13 magnets of alternating polarity, virtually identical to that  
14 shown in FIG. 6, and a rotor backing iron 116. The stator outer  
15 windings portion 58 is provided with windings which are  
16 concentric with circular band 56.

17 In operation, the application of typically three-phase A.C.  
18 electrical current to conductor means 50 serves to activate  
19 forward and after windings 102 and outer windings 58, which act  
20 upon permanent magnet assemblies 42, 44 and permanent magnet  
21 rotor blades 46, to cause movement of the permanent magnets 108,  
22 and thereby rotative movement of the rotor hub 40. As rotor  
23 blades 46 turn through the annulus between hub 40 and shroud 30,  
24 water is forced therethrough, providing thrust to vehicle 26.  
25 Stator blades 28 are fixed aft of rotor blades 30 and serve to  
26 damp turbulence churned up by rotor blades 46.

1           There is thus provided a marine propulsion system having  
2 higher efficiency, power density and output torque than  
3 conventional systems, primarily due to the increased diameter of  
4 the rotor, which is not constrained to hull dimensions. There is  
5 further provided a propulsion system not requiring a cooling  
6 system for the motor, and therefore no circulation pump and  
7 attendant structure. The gaps 60, 82, and 88 permit flow of  
8 water between stator and rotor components, carrying away heat  
9 that otherwise would have to be removed by a cooling assembly.  
10 There is still further provided a system wherein there is no need  
11 for a coupling between motor and propulsor, and therefore no need  
12 for the usual attendant bearings and linkages. Thus, fewer  
13 components are required, reducing costs and potential sources of  
14 failure.

15           It is to be understood that the present invention is by no  
16 means limited to the particular construction herein disclosed  
17 and/or shown in the drawings, but also comprises any  
18 modifications or equivalents,

1 Navy Case No. 77314

2  
3 A MARINE PROPULSION SYSTEM FOR UNDERWATER VEHICLES

4  
5 ABSTRACT OF THE DISCLOSURE

6 A marine propulsion system for underwater vehicles includes  
7 motor inner stator assemblies disposed in hull portions of the  
8 vehicle, fixed blades extending outwardly from an after one of  
9 the hull portions, a shroud fixed to outer ends of the fixed  
10 blades and encircling the hull portions, and a motor outer stator  
11 assembly disposed in the shroud. A rotor hub is disposed in an  
12 annular recess formed by the hull portions, the hub having  
13 permanent magnets therein adjacent the motor inner stator  
14 assemblies, and has rotor blades mounted thereon and extending  
15 outwardly therefrom and being at least in part of a permanent  
16 magnet material, outer ends of the rotor blades being adjacent  
17 the motor outer stator assembly. Activation of the stator  
18 assemblies by a polyphase A.C. power source induces movement in  
19 the permanent magnets and rotor blades to cause the rotor hub and  
20 blades to rotate. The rotation of the rotor blades serves to  
21 provide propulsive thrust to the vehicle.

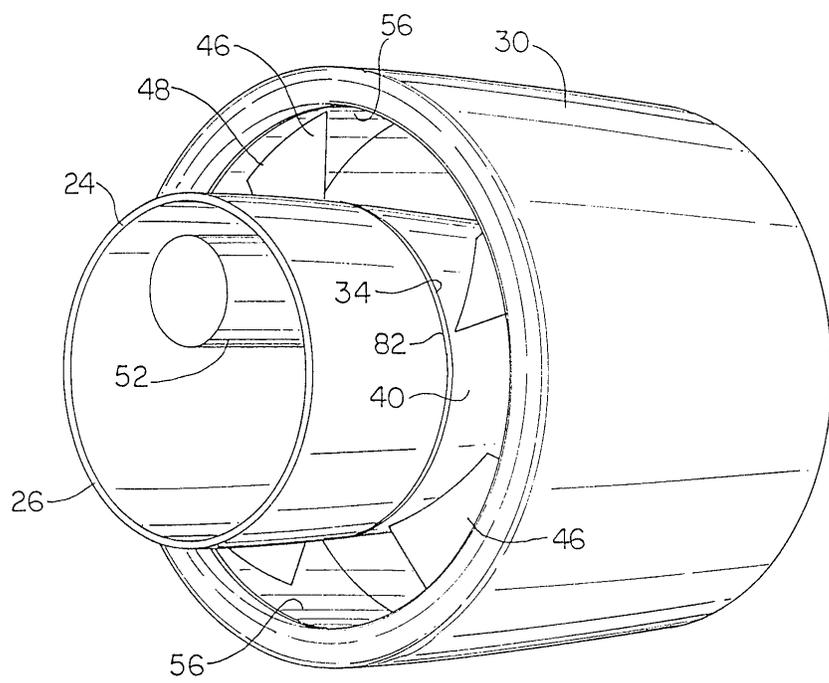


FIG. 1

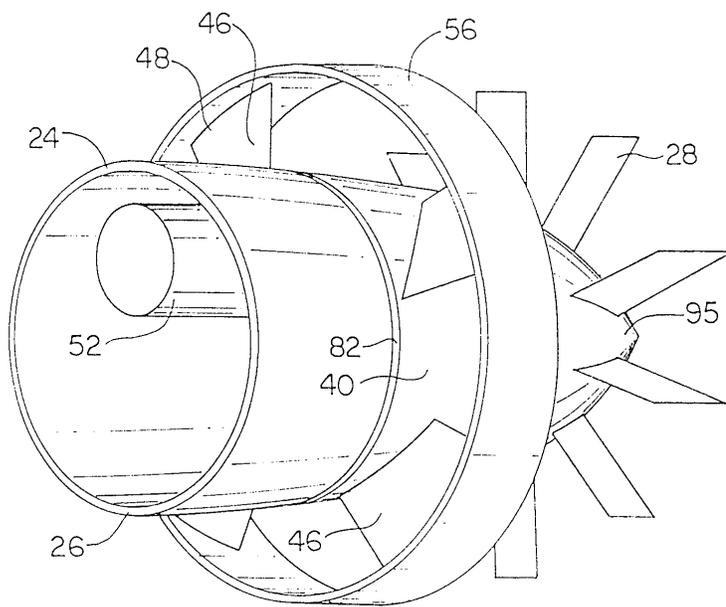


FIG. 2

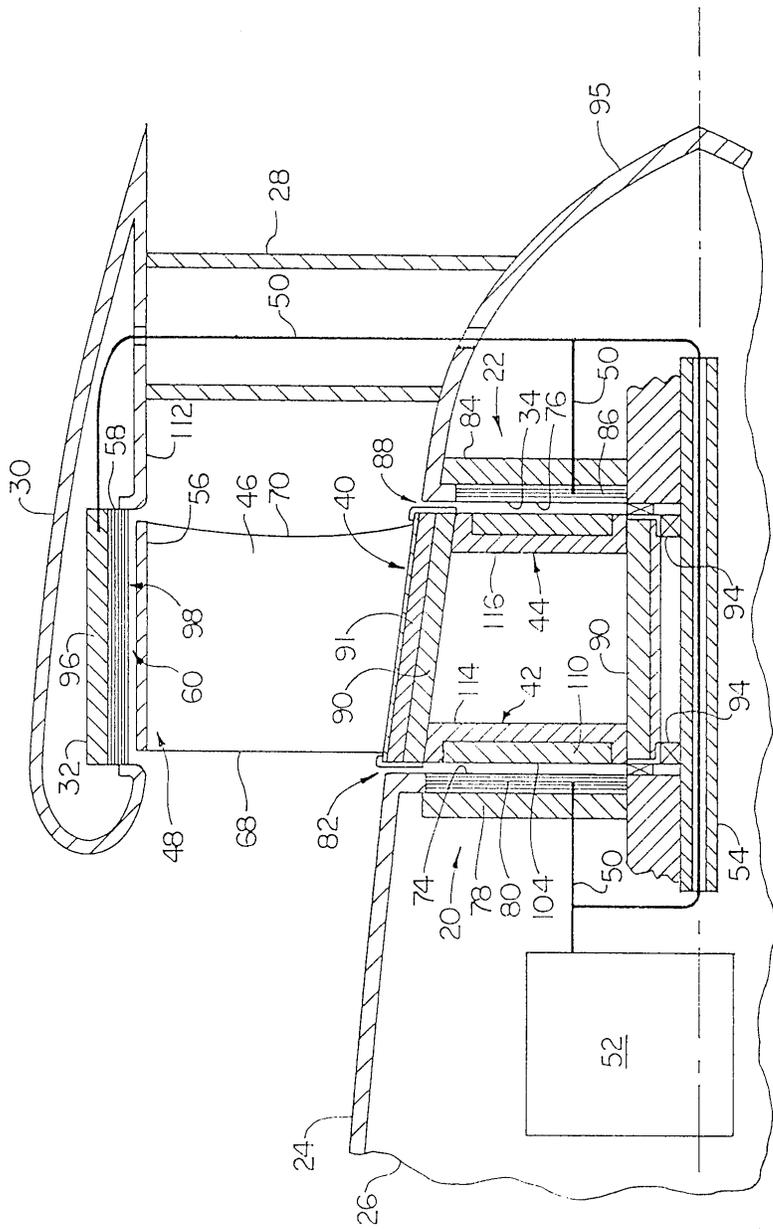


FIG. 3

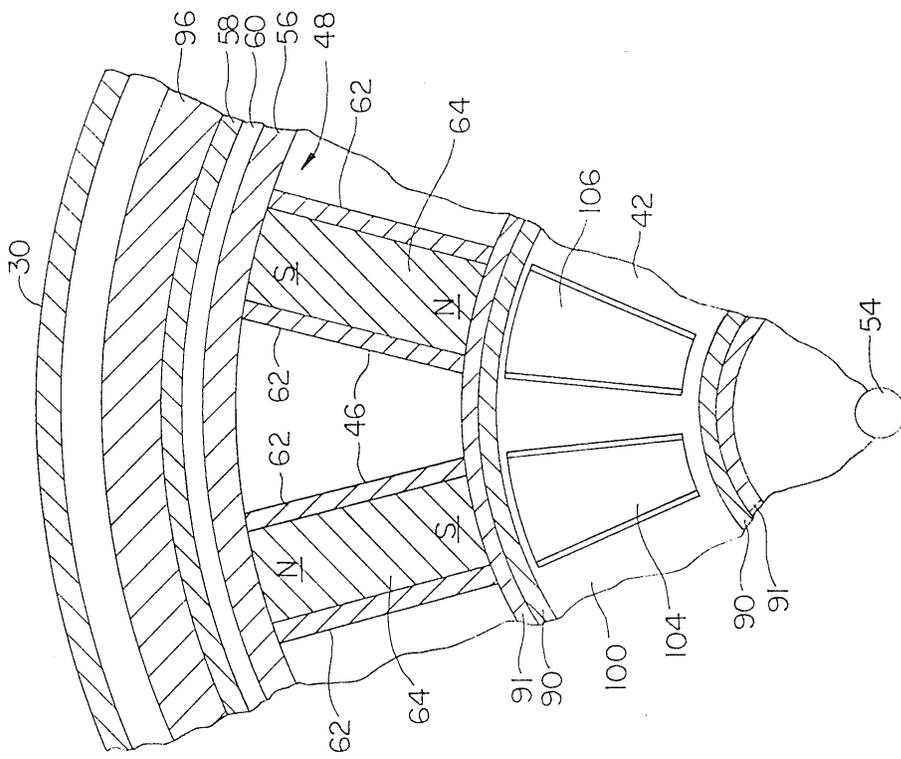


FIG. 4

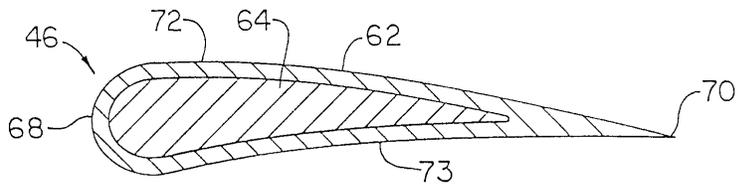


FIG. 5

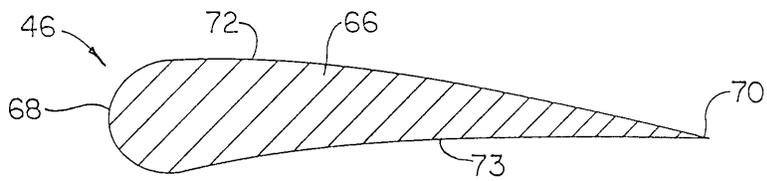


FIG. 5A

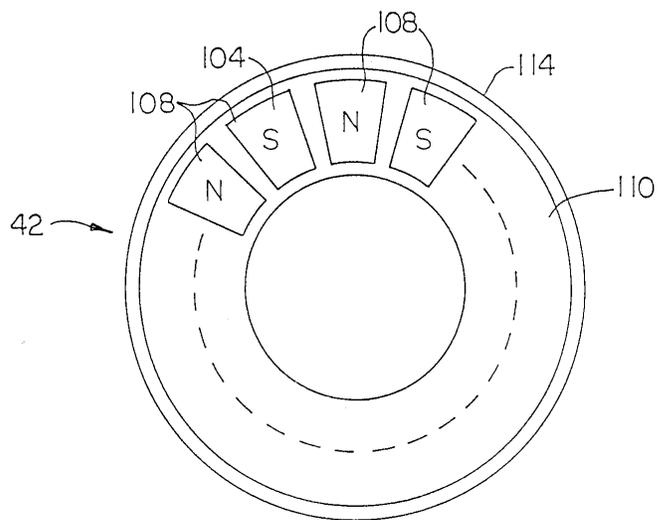


FIG. 6

