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Computer Solutions to Heat and Diffraction Equations in High Energy Laser Windows

Volume II

PETER D. GIANINO
BERNARD BENDOW
N. GRIER PARKE, III
THEODORE A. BARRETT



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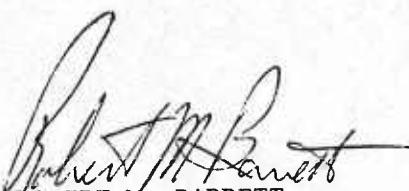
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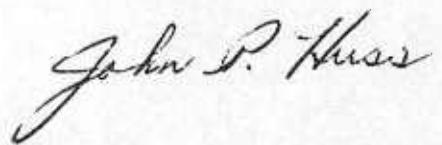
NICHOLAS F. YANNONI, Chief
Optical Techniques Branch
Solid State Sciences Division

APPROVED:



ROBERT M. BARRETT
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22 22	16. ABSTRACT (Continue on reverse side if necessary and identify by block number) The LQ-10 Infrared Laser Window Program was initiated at AFCRL (now RADC/DET) in 1971 to develop a mechanically superior, highly transmitting optical window for CO ₂ and chemical lasers to be used by the Air Force for military applications. From the earliest stages of that program it became evident that the principal failure mechanism of the window would be thermal lensing, that is, the distorting and defocusing of the laser beam as it propagated through the solid. For this reason analytical tools were	next page →

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20. Abstract (Continued)

developed to predict the extent of this lensing in various candidate materials under a variety of conditions. This work contributed to selection of appropriate materials, as well as to design of geometrical configurations, in which the lensing could be reduced. To quantify the effects of thermal lensing, an efficient computer program package was developed and programmed to run on a CDC6600 computer. The package was written to handle Gaussian-shaped beams incident on either a thin disc- or annular-shaped cylindrical window. Three coupled programs make up the package: TEMP5, which solves the full heat transport equation within the window for any given set of initial and boundary conditions on each surface; TIKIRK, which solves the vector Kirchhoff diffraction integrals for the beam transmitted to the far field; and DISPLAY, which plots these temperatures and/or intensities in a variety of ways, including three-dimensional perspective views. Volume I of this report lays the theoretical foundations underlying these programs and presents graphical results for two model problems using disc- and annular-shaped windows. Volume II is a "user's manual." It describes how each program functions, enumerates the constituent subroutines and subprograms, gives complete Fortran listings, and even provides typical detailed commands to initiate and run the programs in both the Intercom and Batch modes of operation. Results of this work should substantially aid engineers in planning configurations and specifications for current and conceptual systems.

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Computer Solutions to Heat and Diffraction Equations in High Energy Laser Windows

Volume II

7. INTRODUCTION

In Volume II we will give a detailed documentation of the Fortran programs TEMP5, TIKIRK and DISPLAY, explaining how to implement them. This will include: listings of main and ancillary programs and subroutines, plus an explanation of their functions; derivations of how the heat, boundary condition (BC) and diffraction intensity equations are transformed into algorithms solvable by the computer; flow charts; and, glossaries of variables for some of the more important subroutines. Since programs TEMP5 and TIKIRK have been coded to permit systems operation under both an Intercom and Batch mode, we will list typical interactive commands and card deck setups which control these two types of operation. Because program DISPLAY can function only in the Batch mode, we will list typical card deck setups for its operation.

Much of the details presented in Volume II appeared originally in the following unpublished reports from Parke Mathematical Laboratories, Inc., Carlisle, Mass.:

- (i) N.G. Parke, III, "Program TEMP5," Sci. Rpt. No. 1 (April 1973); also documented as AFCRL Rpt TR-73-0039 by the same author.

(Received for publication 26 November 1976)



- (ii) T.B. Barrett, "An Interactive Set of Programs Using Program TEMP5 for the Determination of Calorimetric Material Parameters from Experimental Data on Cylindrical IR Laser Window Materials," Tech. Memo. No. 16 (Oct. 1973).
- (iii) T.B. Barrett, "TIKIRK Program," PML Rpt. 110, with revision (April 1974).
- (iv) T.B. Barrett, "GETDATA Subroutine," PML Rpt. 111 (May 1974).
- (v) T.B. Barrett, "DISPLAY Program," PML Rpt. 116 (May 1974).

8. TEMP5 PROGRAM

8.1 Introductory Remarks

Initial attempts to code the numerical solution to the heat and BC equations used the Crank-Nicolson method.¹¹ This procedure leads to a pentagonal system of linear difference equations, which are usually solved by an appropriate iteration technique.¹² However, if the edges of the "net" of points — at which the temperature is to be evaluated — is situated at the boundaries, three problems arise:

- (1) Iteration techniques must be used.
- (2) Symmetry dictates that along the window axis ($\rho = 0$) there be no heat flow across the window center, that is, $\partial u / \partial \rho = 0$. Under this condition, however, the term $(1/\rho)(\partial u / \partial \rho)$ which occurs in the partial differential equation would be indeterminate.
- (3) A satisfactory finite-difference analog must be found for the general BC's, which have the form:

$$\frac{\partial u}{\partial \nu} + hu = g . \quad (38)$$

[cf, Eq. (32) of Volume I].

These difficulties were resolved as follows:

- (1) The Crank-Nicolson method was replaced by the Implicit Alternating Difference (IAD) method.¹¹ This procedure reduces the algebraic problem at each stage to the inversion of a tridiagonal matrix. The Thomas algorithm is employed and iteration is avoided. The cost of this approach for a problem involving two space variables is a two-time-level pair of difference equations.

-
11. Carnahan, B., Luther, H.A., and Wilkes, J.O. (1969) Applied Numerical Methods, Wiley and Sons, Inc., New York.
 12. Parke, N.G., III (1971) Technical Memorandum No. 4, Parke Mathematical Laboratories, Inc., Carlisle, Massachusetts, unpublished.

(2) By applying L'Hospital's rule along the cylinder axis there results:

$$\lim_{\rho \rightarrow 0} (\rho^{-1}) (\partial u / \partial \rho) = \partial^2 u / \partial \rho^2.$$

(3) A suitable finite difference analog for Eq. (38) is established by shifting the "net" half an increment off the boundaries.

To see how the finite difference method is applied, consider a transverse cross-sectional cut through the window's center (that is, the plane of the cross-section is perpendicular to the window's faces). The borders of the resulting rectangular cross-section are parallel to the ρ and ξ axes (see Figure 1, Volume I). Because of the rotational symmetry, only one half of the section need be shown. The geometry of the choice of net points superimposed on this cut is indicated in Figure 19. The window faces occur at the lines marked $\xi = \xi_1$, and $\xi = \xi_2$; the inner and outer cylindrical surfaces are denoted by the lines marked $\rho = \rho_1$ and 1, respectively. The ρ, ξ coordinates of each net point are represented by the indices i, j , respectively, with i running from 0 to $M+1$, and, j running from 0 to $N+1$. That is,

$$\begin{aligned}\rho_i &= \rho_1 + \left(i - \frac{1}{2} \right) \cdot \Delta \rho, \quad i = 0, 1, \dots, M+1 \\ \xi_j &= \xi_1 + \left(j - \frac{1}{2} \right) \cdot \Delta \xi, \quad j = 0, 1, \dots, N+1.\end{aligned}\tag{39}$$

These coordinates are measured relative to the surfaces ρ_1 and ξ_1 , respectively. All of the net points bearing one or both of the indices 0, $M+1$ and $N+1$ fall outside of the window itself and are considered to be "fictitious" or "corner" points.

8.2 Finite Difference Analogs for the General BC's

It is now possible to write the finite difference analog of the general BC's for the shifted net. First, we note that the derivative term $\partial u / \partial v$ in Eq. (38) differs for each surface due to the sign conventions chosen for ρ and ξ . For example, at the surfaces $\rho = \rho_1$ and $\rho = 1$, the term $\partial u / \partial v$ becomes $-$ and $+$ $\partial u / \partial \rho$, respectively; while at the surfaces $\xi = \xi_1$, and $\xi = \xi_2$ it becomes $-$ and $+$ $\partial u / \partial \xi$, respectively. Thus, the finite difference analogs of the BC's become:

$$\frac{u_{0,j} - u_{1,j}}{\Delta \rho} + h_1 \frac{u_{0,j} + u_{1,j}}{2} = g_1 \text{ at } \rho = \rho_1\tag{40}$$

$$\frac{u_{M+1,j} - u_{M,j}}{\Delta \rho} + h_2 \frac{u_{M+1,j} + u_{M,j}}{2} = g_2 \text{ at } \rho = 1\tag{41}$$

for $j = 1, 2, \dots, N-1$

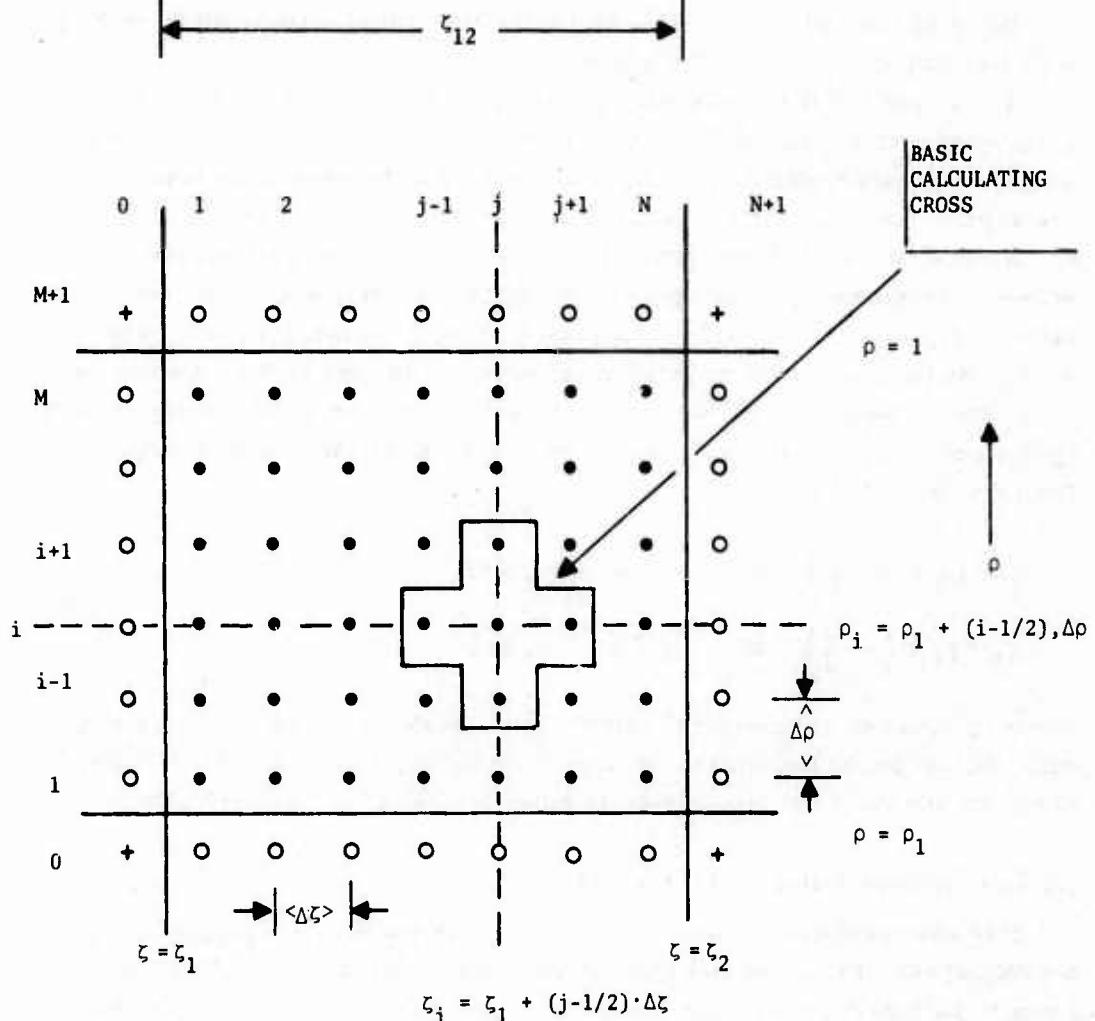


Figure 19. Geometry of Finite Difference Net. The boundaries are straddled by a net point and a fictitious point

$$\frac{u_{i,o} - u_{i,1}}{\Delta\xi} + h_3 \frac{u_{i,o} + u_{i,1}}{2} = g_3 \text{ at } \xi = \xi_1 \quad (42)$$

$$\frac{u_{i,N+1} - u_{i,N}}{\Delta\xi} + h_4 \frac{u_{i,N+1} + u_{i,N}}{2} = g_4 \text{ at } \xi = \xi_2 \quad (43)$$

When these are solved for the "fictitious" points, one obtains

$$u_{o,j} = \left[\frac{2 - h_1 \cdot \Delta\rho}{2 + h_1 \cdot \Delta\rho} \right] u_{1,j} + \left[\frac{2 \cdot \Delta\rho \cdot g_1}{2 + h_1 \cdot \Delta\rho} \right] \quad (44)$$

$$u_{M+1,j} = \left[\frac{2 - h_2 \cdot \Delta\rho}{2 + h_2 \cdot \Delta\rho} \right] u_{M,j} + \left[\frac{2 \cdot \Delta\rho \cdot g_2}{2 + h_2 \cdot \Delta\rho} \right] \quad (45)$$

$$u_{i,o} = \left[\frac{2 - h_3 \cdot \Delta\xi}{2 + h_3 \cdot \Delta\xi} \right] u_{i,1} + \left[\frac{2 \cdot \Delta\xi \cdot g_3}{2 + h_3 \cdot \Delta\xi} \right] \quad (46)$$

$$u_{i,N+1} = \left[\frac{2 - h_4 \cdot \Delta\xi}{2 + h_4 \cdot \Delta\xi} \right] u_{i,N} + \left[\frac{2 \cdot \Delta\xi \cdot g_4}{2 + h_4 \cdot \Delta\xi} \right]. \quad (47)$$

We saw in Section 3.3, Volume I, that all BC's of practical interest can be represented by appropriate choices of the g_i and h_i . With this capability in the above analogs, the resulting computer program becomes very flexible.

8.3 Finite Difference Equations for I.A.D. Method

Having set up the "net," we shall now use the I.A.D. method on the parabolic heat equation having the general form [cf Eq. (29), Volume I]:

$$\frac{\partial u}{\partial \tau} = \frac{\partial^2 u}{\partial \rho^2} + \rho^{-1} \frac{\partial u}{\partial \rho} + \frac{\partial^2 u}{\partial \xi^2} + q \quad (48)$$

where

$$q = A \exp(-\rho^2/2\sigma_e^2).$$

In the first finite difference equation set, the analog of the partial derivatives with respect to ρ will be written at the new time level $n + 1$, and the analog of the ξ -derivative written at the old level n . Here, n is even starting with $n = 0$. To complete the cycle, the second finite difference equation set is written at the new time level $n + 2$ for derivatives in the ξ direction. In other words, the equations are now implicit in ξ -direction and explicit in the ρ -direction. Partial derivatives with respect to ρ are written in terms of values of u at the, now old, time level $n + 1$. These "intermediate" values of u are sometimes designated u^* (meaning a correction). They are not accurate representations of the u . This point is discussed in detail by von Rosenberg.¹³

Our analogs for the various partial derivatives take the forms:

$$(u_{\rho\rho})_{i,j,n+1} = \frac{u_{i+1,j,n+1} - 2u_{i,j,n+1} + u_{i-1,j,n+1}}{(\Delta\rho)^2}, \quad (49)$$

$$\left(\frac{1}{\rho} u_\rho\right)_{i,j,n+1} = \frac{u_{i+1,j,n+1} - u_{i-1,j,n+1}}{2\rho_i(\Delta\rho)}, \quad (50)$$

$$(u_{\xi\xi})_{i,j,n} = \frac{u_{i,j+1,n} - 2u_{i,j,n} + u_{i,j-1,n}}{(\Delta\xi)^2}, \quad (51)$$

$$(u_\tau)_{i,j,n+1/2} = \frac{u_{i,j,n+1} - u_{i,j,n}}{(\Delta\tau)}, \quad (52)$$

and

$$q(\rho_i, \xi_j) = q_{i,j}. \quad (53)$$

The subscripts i, j merely represent generalized indices and extend over the generalized ranges: $i = 1, 2, \dots, M$ and $j = 1, 2, \dots, N$. After substitution, the first set of I.A.D. equations are:

13. von Rosenberg, D.U. (1969) Methods for the Numerical Solution of Partial Differential Equations, American-Elsevier Publishing Co., Inc., New York.

$$\frac{u_{i+1,j,n+1} - 2u_{i,j,n+1} + u_{i-1,j,n+1}}{(\Delta\rho)^2} + \frac{u_{i+1,j,n+1} - u_{i-1,j,n+1}}{2\rho_i(\Delta\rho)} \quad (54)$$

$$+ \frac{u_{i,j+1,n} - 2u_{i,j,n} + u_{i,j-1,n}}{(\Delta\xi)^2} + q_{i,j} = \frac{u_{i,j,n+1} - u_{i,j,n}}{\Delta\tau} .$$

The second set of I.A.D. equations is:

$$\frac{u_{i+1,j,n+1} - 2u_{i,j,n+1} + u_{i-1,j,n+1}}{(\Delta\rho)^2} + \frac{u_{i+1,j,n+1} - u_{i-1,j,n+1}}{2\rho_i(\Delta\rho)} \quad (55)$$

$$+ \frac{u_{i,j+1,n+2} - 2u_{i,j,n+2} + u_{i,j-1,n+2}}{(\Delta\xi)^2} + q_{i,j} = \frac{u_{i,j,n+2} - u_{i,j,n+1}}{\Delta\tau} .$$

It is convenient to introduce the parameters

$$\lambda = \frac{\Delta\tau}{(\Delta\rho)^2}, \quad \mu = \frac{\Delta\tau}{(\Delta\xi)^2} . \quad (56)$$

Observe that Eqs. (54) are tridiagonal, containing the unknowns

$$u_{i+1,j,n+1}, \quad u_{i,j,n+1}, \quad u_{i-1,j,n+1}$$

and can be solved by the Thomas algorithm. Likewise, Eqs. (55) are tridiagonal, containing the unknowns

$$u_{i,j+1,n+2}, \quad u_{i,j,n+2}, \quad u_{i,j-1,n+2}$$

and can likewise be solved by the Thomas algorithm.

Before continuing, let us take up the mathematics of the Thomas algorithm (which will be incorporated in the subroutine TRIDAG, to be explained later).

8.4 The Solution of a Tridiagonal System of Equations

The whole purpose of the implicit-alternating direction method is to reduce the number of unknown variables at the "next" time level to three in any one equation. Such a set of equations is called a tridiagonal system that has a relatively

simple solution. This strategy avoids "iteration" techniques of the Crank-Nicolson approach, described in Parke.¹²

The general form of a tridiagonal system of equations is

$$b_1 v_1 + c_1 v_2 = d_1$$

$$a_2 v_1 + b_2 v_2 + c_2 v_3 = d_2$$

$$a_3 v_2 + b_3 v_3 + c_3 v_4 = d_3$$

.....

$$a_i v_{i-1} + b_i v_i + c_i v_{i+1} = d_i$$

.....

$$a_{N-1} v_{N-2} + b_{N-1} v_{N-1} + c_{N-1} v_N = d_{N-1}$$

$$a_N v_{N-1} + b_N v_N = d_N$$

where*

d_i . =. known quantities

a_i, b_i, c_i . =. known coefficients

v_i . =. unknown quantities .

The tridiagonal matrix is defined as the matrix of coefficients a, b, c alone.

We follow the treatment in Carnahan.¹¹ To continue, the validity of the form

$$v_i = \gamma_i - \frac{c_i}{\beta_i} v_{i+1} \quad (58)$$

can be demonstrated. The constants γ_i and β_i are to be determined. Indeed, substitution into the i -th equation of (57) gives

$$a_i \left(\gamma_{i-1} - \frac{c_{i-1}}{\beta_{i-1}} v_i \right) + b_i v_i + c_i v_{i+1} = d_i \quad .$$

*The symbol . =. means "is defined as."¹¹

As a result

$$v_i = \frac{d_i - a_i \gamma_{i-1}}{b_i - \frac{a_i c_{i-1}}{\beta_{i-1}}} - \frac{c_i v_{i+1}}{b_i - \frac{a_i c_{i-1}}{\beta_{i-1}}}$$

where we have the recursion relations

$$\beta_i = b_i - \frac{a_i c_{i-1}}{\beta_{i-1}} ; \quad \gamma_i = \frac{d_i - a_i \gamma_{i-1}}{\beta_i} . \quad (59)$$

From the first of Eqs. (57), we have

$$v_1 = \frac{d_1}{b_1} - \frac{c_1 v_2}{b_1}$$

where

$$\beta_1 = b_1 , \quad \gamma_1 = d_1 / \beta_1 . \quad (60)$$

Finally, from the last of Eqs. (57), we have

$$v_N = \frac{d_N - a_N v_{N-1}}{b_N} = \frac{d_N - a_N \left(\gamma_{N-1} - \frac{c_{N-1}}{\beta_{N-1}} v_N \right)}{b_N} \quad (61)$$

where

$$v_N = \frac{d_N - a_N (\gamma_{N-1})}{b_N - \frac{a_N c_{N-1}}{\beta_{N-1}}} = \frac{d_N - a_N \gamma_{N-1}}{\beta_N} = \gamma_N . \quad (61a)$$

To summarize the complete algorithm for the solution of the tridiagonal system, we have

$$v_N = \gamma_N$$

$$v_i = \gamma_i - \frac{c_i v_{i+1}}{\beta_i} \quad ; \quad i = N-1, N-2, \dots, 1 \quad (62)$$

where the β 's and γ 's are determined by the recursion formulae

$$\beta_1 = b_1 \quad , \quad \gamma_1 = d_1 / \beta_1$$

$$\beta_i = b_i - \frac{a_i c_{i-1}}{\beta_{i-1}} \quad ; \quad i = 2, 3, \dots, N \quad (63)$$

$$\gamma_i = \frac{d_i - a_i \gamma_{i-1}}{\beta_i} \quad ; \quad i = 2, 3, \dots, N$$

8.5 Putting the I.A.D. Equations into Tridiagonal Form

Using Eqs. (56), the first I.A.D. set becomes, from Eq. (54)

$$\lambda[u_{i+1,j,n+1} - 2u_{i,j,n+1} + u_{i-1,j,n+1}] + \frac{\lambda \cdot \Delta\rho}{2(\rho_1 + (i - 1/2) \cdot \Delta\rho)}^* \times \\ \times [u_{i+1,j,n+1} - u_{i-1,j,n+1}] = d_i + u_{i,j,n+1} \quad (64)$$

Writing in the standard form

$$b_1 u_{1,j,n+1} + c_1 u_{2,j,n+1} = d_1 \\ \dots \dots \dots \\ a_i u_{i-1,j,n+1} + b_i u_{i,j,n+1} + c_i u_{i+1,j,n+1} = d_i \\ \dots \dots \dots \\ a_M u_{M-1,j,n+1} + b_M u_{M,j,n+1} = d_M \quad (65)$$

we find that, in general, that is, for $i \neq 1, i \neq M$

$$a_i = \lambda \left(1 - \frac{\Delta\rho}{2\rho_1 + (2i - 1) \cdot \Delta\rho} \right) = \lambda \left(1 - \frac{\Delta\rho}{2\rho_i} \right) \quad (66)$$

~~$\frac{\lambda \cdot \Delta\rho}{2\rho_i}$~~

$$b_i = - (2\lambda + 1) \quad (67)$$

$$c_i = \lambda \left(1 + \frac{\Delta\rho}{2\rho_1 + (2i-1) \cdot \Delta\rho} \right) = \lambda \left(1 + \frac{\Delta\rho}{2\rho_i} \right) \quad (68)$$

$$d_i = - \mu(u_{i,j+1,n} - 2u_{i,j,n} + u_{i,j-1,n}) - \Delta\tau \cdot q_{ij} - u_{i,j,n} \quad (69)$$

We notice that from Eq. (44)

$$a_1 u_{0,j,n+1} = a_1 \left\{ \left[\frac{2 - h_1 \cdot \Delta\rho}{2 + h_1 \cdot \Delta\rho} \right] u_{1,j} + \left[\frac{2 \cdot \Delta\rho \cdot g_1}{2 + h_1 \cdot \Delta\rho} \right] \right\} \quad (70)$$

Hence, we have to change b_1 according to

$$b_1 \leftarrow b_1 + a_1 \left[\frac{2 - h_1 \cdot \Delta\rho}{2 + h_1 \cdot \Delta\rho} \right] \quad (71)$$

We also have to change d_1

$$d_1 \leftarrow d_1 - a_1 \left[\frac{2 \cdot \Delta\rho \cdot g_1}{2 + h_1 \cdot \Delta\rho} \right] \quad (72)$$

Similarly we have to change b_M

$$b_M \leftarrow b_M + c_M \left[\frac{2 - h_2 \cdot \Delta\rho}{2 + h_2 \cdot \Delta\rho} \right] \quad (73)$$

using Eq. (45). Likewise

$$d_M \leftarrow d_M - c_M \left[\frac{2 \cdot \Delta\rho \cdot g_2}{2 + h_2 \cdot \Delta\rho} \right] \quad (74)$$

It should be observed that as long as $j \neq 1$ or $j = N$, the d 's require no further modification because their computation involves only "net" points at time level n . However, when $j = 1$, the fictitious points $u_{i,0,n}$ are involved. Also, when $j = N$,

the fictitious points $u_{i,N+1,n}$ are involved. The simplest way to handle this is to "border" the $u_{i,j,n}$ array by computing $u_{i,0,n}$ with Eq. (46) and $u_{i,N+1,n}$ with Eq. (47) just before computing the first sets of a, b, c, d for the ξ -explicit, ρ -implicit I.A.D. set.

To summarize, in step I we modify b_1, d_1, b_M, d_M having extended $u_{i,j,n}$ with Eqs. (46) and (47).

Now let us turn to step II of the I.A.D. method. We begin with Eqs. (55) and write

$$\mu[u_{i,j+1,n+2} - 2u_{i,j,n+2} + u_{i,j-1,n+2}] = d_j + u_{i,j,n+2} - \Delta\tau \cdot q_{ij} . \quad (75)$$

These equations are to be written in the standard form:

$$\begin{aligned} b_1 u_{i,1,n+2} + c_1 u_{i,2,n+2} &= d_1 \\ \dots &\\ a_j u_{i,j-1,n+2} + b_j u_{i,j,n+2} + c_j u_{i,j+1,n+2} &= d_j \\ \dots &\\ a_N u_{i,N-1,n+2} + b_{N-1} u_{i,N,n+2} &= d_N \end{aligned} \quad (76)$$

We find again that, in general, that is, for $j \neq 1$ or $j \neq N$

$$\begin{aligned} a_j &= \mu , \quad b_j = -(2\mu + 1) , \quad c_j = \mu , \\ d_j &= -\lambda [u_{i+1,j,n+1} - 2u_{i,j,n+1} + u_{i-1,j,n+1}] - \frac{\lambda \cdot \Delta\rho^*}{2\rho_1 + (2i-1) \cdot \Delta\rho} \\ &\quad [u_{i+1,j,n+1} - u_{i-1,j,n+1}] - \Delta\tau \cdot q_{ij} - u_{i,j,n+1} . \end{aligned} \quad (77)$$

Using Eq. (46) for $u_{i,0,n+2}$, we change b_1 to

$$b_1 \leftarrow b_1 + a_1 \left[\frac{2 - h_3 \cdot \Delta\xi}{2 + h_3 \cdot \Delta\xi} \right] . \quad (78)$$

* $-\lambda\Delta\rho/2\rho_1$

We also change d_1 to

$$d_1 \leftarrow d_1 - a_1 \left[\frac{2 + \Delta\xi \cdot g_3}{2 + h_3 \cdot \Delta\xi} \right]. \quad (79)$$

Similarly we use Eq. (47) for $u_{i,N,n+2}$ to change b_{N-1} to

$$b_N \leftarrow b_N + c_N \left[\frac{2 - h_4 \cdot \Delta\xi}{2 + h_4 \cdot \Delta\xi} \right]. \quad (80)$$

and

$$d_N \leftarrow d_N - c_N \left[\frac{2 + \Delta\xi \cdot g_4}{2 + h_4 \cdot \Delta\xi} \right]. \quad (81)$$

Again, as long as $i \neq 1$, or $i \neq M$, the d 's require no further modification because their computation involves only "net" points at time level $n + 1$. However, when $i = 1$, the fictitious points $u_{0,j,n+1}$ are involved. Also, when $i = M$, the fictitious points $u_{M+1,j,n+1}$ are involved. The simplest way to handle this is to "border" the $u^* = u_{i,j,n+1}$ array by computing $u_{0,j,n+1}$ with Eq. (44) and $u_{M+1,j,n+1}$ with Eq. (45) before starting on the second half of the I.A.D. set. We shall keep the $0, 2, \dots, n$ even level u 's in an array $U(I, J)$. We shall keep the $1, 3, \dots, n$ odd level u 's in an array $USTAR(I, J)$.

8.6 The Time Coordinate

The time coordinate τ_n is constructed so as to be controlled by an integer n and an increment $\Delta\tau$ in a special way. Because we are using the I.A.D. method, the "net" values of temperature are only valid when u is an even integer. In addition, it should be noted that $\Delta\tau$ may be changed before entering a new cycle involving an alternating difference pair of finite difference equations.

Initially, temperature varies relatively rapidly with time. This means that rather closely spaced time units should be selected at which to calculate the temperature. Later, as the temperature approaches its steady state value, its change is less rapid so that it seems reasonable, especially from the viewpoint of conserving computer time, to calculate temperatures at much larger intervals of time. This can be accomplished by allowing the time interval $\Delta\tau$ at a particular choice of n to increase according to the scheme:

$$\Delta\tau(n) = 2^{n/n_0} \Delta\tau_0. \quad (82)$$

$\Delta\tau_0$ is some arbitrarily-selected initial value of $\Delta\tau$, n is a positive even integer and n_0 is some arbitrary positive integer, called the "doubling count number," because when n reaches n_0 , $\Delta\tau$ will double to $2\Delta\tau_0$. Making n_0 very large is equivalent to holding $\Delta\tau(n) = \Delta\tau_0$.

Meanwhile, the time coordinate τ_n is formed according to the prescription:

$$\tau_n = 2 \sum_{k=0}^n \Delta\tau(k) = 2\Delta\tau_0 \sum_{k=0}^n 2^{k/n_0} \quad (83)$$

in which k is incremented in steps of 2 up to n . This prescription will hold up to the limit $n = n_L$. The actual value of n_L will be determined by the parameter n_{max} , a positive integer which is inputted at the start of the program. The integer n_L will be equal to $n_{max} - 2$ if n_{max} is even, or, to $n_{max} - 1$ if n_{max} is odd. At $n = n_L$, the increment is designated by $\Delta\tau(n_L)$ and the time by τ_{n_L} . That is:

$$\Delta\tau(n_L) = 2^{n_L/n_0} \Delta\tau_0 \quad (84)$$

$$\tau_{n_L} = 2 \Delta\tau_0 \sum_{k=0}^{n_L} 2^{k/n_0} \quad (85)$$

For times greater than τ_{n_L} , corresponding to $n > n_L$, the increment will remain fixed at $\Delta\tau(n_L)$, whereas the time will be given by:

$$\tau_n = \tau_{n_L} + \Delta\tau(n_L) \cdot (n - n_L)/2 \quad (86)$$

The time τ_n will keep increasing by these fixed increments until it reaches some arbitrarily-fixed upper limit τ_{max} , at which point the program initiates a termination procedure.

By virtue of another time-control parameter, the program also makes provision for turning the source off and then determining the temperature changes as the window cools off. This occurs at $\tau = \tau_{off}$, where, of course, τ_{off} must be $\leq \tau_{max}$.

Should τ_n , as determined by Eq. (86), become greater than τ_{off} at the start of a time loop, and if $\tau_{off} < \tau_{max}$, then the time-incrementing procedure is reinitiated. On the other hand, should τ_n exceed τ_{off} at the start of a time loop, and if $\tau_{off} = \tau_{max}$, then the subroutine CYLTMP (to be described later) does not

continue with the calculation, but returns control to the main program. Thus, the actual maximum time value will usually be slightly less than τ_{off} if the window is being irradiated, and will be slightly less than τ_{max} if the window is experiencing a cooling phase.

From the analysis above, we see that, apart from the running index n , usually 4, or, at most 5, parameters are required to control the time coordinate, viz, n_0 , n_{max} , $\Delta\tau_0$, τ_{max} and τ_{off} . The time interval $\Delta\tau$ can be enlarged by increasing $\Delta\tau_0$ or n_{max} , or by decreasing n_0 .

8.7 The Main Program and Principal Subroutines

The coding necessary to input all of the data, to carry out all of the required calculations, including the I.A.D. prescriptions, and finally, to print out the results constitutes a major programmed package, named the T1MP5 program. This package consists of eight principal subroutines called into execution by one very short main program. This latter program has also been designated as TEMP5. However, whenever we use the term "TEMP5 program" throughout this report we will always mean the collective "package" rather than this one main program, unless stated otherwise.

The TEMP5 program is composed of the following:

- (1) TEMP5 - a very short program whose principal purpose is to call the 2 principal subroutines DATINIT and CYLTMP.
- (2) DATINIT - a subroutine which inputs all required parameters necessary for program operation by a call to subroutine GETDATA. It initializes the principal arrays used by subroutine CYLTMP. It also calls subroutine GAUSS.
- (3) CYLTMP - the "core" subroutine of the TEMP5 program. It calculates the temperature u according to the I.A.D. method using both subroutines TRIDAG and SPLNI and then the related integrals F1 and F2 again using SPLNI. It stores u , F1 and F2 in unformatted form on a file named TAPE3. These temperatures (u) are calculated at the RHO, ZED lattice points and are designated by the variable name U(I, J).
- (4) TRIDAG - the subroutine which implements the Thomas algorithms for solving a system of simultaneous linear equations having a tridiagonal coefficient matrix.
- (5) GAUSS - a subroutine for loading the volume heating source term Q with a truncated Gaussian distribution into the program.
- (6) SPLNI - The subroutine which finds the third order spline function for a function $y(x)$ given at the points $(X(I), Y(I))$. It is used both for integrating the F1 and F2 functions as well as for interpolating values of u at the RFIN, ZFIN lattice points, which occur halfway between the RHO, ZED lattice points. These interpolated temperatures are designated by the variable name UFIN(I, J). They enable

us to calculate temperatures out to the window's edges. SPLNI, which follows Chapter 8 of Ralston and Wilf,¹⁴ is a modification of the IBM standard Scientific Subroutine Package subroutine SPLIE.

(7) GETDATA - obtains data from the operator. It can be used as a universal inputting subroutine for either the Batch or Intercom modes of operation of any program requiring input data. (More will be said about these two modes later.) However, it was written mainly for Intercom operation. It also calls on subroutines SSWTCH and RJUST.

(8) SSWTCH - reads in the first three data values (and prints out appropriate messages) for GETDATA control. (It should be noted that SSWTCH is not the same as the CDC Fortran subroutine bearing the same name.)

(9) RJUST - right adjusts all numerical values.

The TEMP5 program has been coded to permit operation under either Batch processing or Intercom. The latter mode permits relatively easy interactive use, as implemented under CDC Scope 3.4 with the CDC6600.

The complete Fortran listings for each of the above are given in Appendix A.

8.8 Implementation of Some of the Subroutines

8.8.1 DATINIT

The implementation of the TEMP5 program begins with the inputting of all required program parameters and the initializing of the working arrays which will eventually be used by CYLTMP. DATINIT accomplishes all of this by a call to GETDATA. Furthermore, DATINIT assigns default values to the VALUE portion of DATAIN, which is an array of TEMP5 parameters, and also assigns names and format codes to the NAME and FORMAT portions of DATAIN. This will be described in more detail in Section 8.8.4 on GETDATA.

A complete tabulation of all the required input data is given in Table 2. The table lists both the data and the variable names, their corresponding default values, formats, the particular major programming package in which each quantity is ultimately used, and a succinct description. The default values listed in Table 2 for the material properties such as refractive index, absorption coefficient, etc., pertain to KCl.

It should be noted that although all of the variables itemized in Table 2 may be inputted at this stage of the program, not all of them will actually be used in TEMP5. Many of them will be called up later in the TIKIRK and DISPLAY programs.

14. Ralston, A., and Wilf, H. S. (1967) Mathematical Methods for Digital Computers, Vol. II, Wiley and Sons, Inc., New York.

Another factor to be noted in Table 2 is that the values of M and N have been chosen to be 80 and 20, respectively. Since the indices on the RHO and ZED coordinates extend from 0 to M+1, and, 0 to N+1, respectively, this means that the net depicted in Figure 3 consists of 82 points along the radial direction and 22 points along the axis. Meanwhile, since the indices on the RFIN, ZFIN coordinates extend from 1 to M+1, and, 1 to N+1, respectively, then the array of points at which interpolation occurs consists of 81 points along the radial direction and 21 points along the axis.

8.8.2 CYLTMP

The temperature-related terms U, F1 and F2 really constitute the principal output of the entire TEMP5 program. Computation of these quantities, as prescribed by Eqs. (29), (30), (16) and (17), are actually carried out by the subroutine CYLTMP, with the aid of TRIDAG and SPLNI. Figure 20 shows a flow chart for the CYLTMP algorithm. Table 3 gives a glossary of the variable names.

Source turn-off is accomplished in subroutine CYLTMP by setting the volume source term (array q) and "boundary" source term (array g) to 0 at the appropriate time. At the end of each τ -cycle through CYLTMP, the temperature distribution at $\tau + \Delta\tau$ has been computed where τ is the time at the start of the cycle. Thus, a check is made at the start of each cycle to see if $\tau + \Delta\tau$ is less than τ_{off} . If it is, then the cycle continues normally with the source terms "on." When $\tau + \Delta\tau$ first becomes equal to or greater than τ_{off} , a "flag" is set and a new $\Delta\tau$ is computed such that $\tau + \Delta\tau = \tau_{off}$ and the cycle continues. When the subroutine returns to the start of the next cycle, the source term is set to 0. In addition the variable NN is reset to 0 and $\Delta\tau$ is computed as was done for source turn-on.

8.8.3 TRIDAG

This is a subroutine for solving a system of linear simultaneous equations having a tridiagonal coefficient matrix. The equations are numbered from IF through L, and their subdiagonal, diagonal, and superdiagonal coefficients are stored in arrays A, B, C. The computed solution vector ($V(IF)$,, $V(L)$) is stored in array V.

The mathematical details of all of the steps involved in solving the tridiagonal equations have been given in Section 8.4.

The coding for subroutine TRIDAG is taken from Carnahan et al¹¹ on page 446.

8.8.4 GETDATA

8.8.4.1 Description

This subroutine is designed for inputting problem data when a program is run under CDC6600 INTERCOM control. It may also be used, however, for inputting

Table 2. Input Data for the Implementation of the TEMP5 Program

(1) DATAIN Seq. No.	(2) Datum Name	(3) Variable Name	(4) Default Value	(5) Format Code	(6) Usage Code	(7) Description
1*	I1	I1	2	0	T	Print/punch F1, F2 and param- eters.
2*	I2	I2	2	0	T, K	Print TAU, LMDA, MU, MN, NO, INIT, ICNTR. Also, use 1 if IKIRKP option is desired; use 2 for IKIRK option. (see Sec. 9.2.)
3*	I3	I3	2	0	T	Print arrays: KK, A, B, C, D, UPRIM in CYLTMP; also initial values of U, USTAR, etc.
4*	I4	I4	2	0	T	Print U and Q after initial data read-in or com- putation.
5*	I5	I5	2	0	T	Print array UFIN at every fifth value of both RFIN and ZFIN.
6*	I6	I6	2	0	T	Punch array UFIN and parameters.
7*	I7	I7	2	0	T	Print array U at the following RHO(I) and ZED(J) points: I=2, 2+MI, 2+2MI, 2+3MI, ..., ≤ 81 J=2, 2+NI, 2+2NI, 2+3NI, ..., ≤ 21 .
8	M	M	80	0	T	M+1 is the number of radial points at which temperature data is outputted.
9	N	N	20	0	T	N+1 is the number of axial points at which temperature data is outputted.

*For I1 through I7: If the value is set equal to 1, then appropriate output will be printed; if the value is set equal to 2, then output will be suppressed.

Table 2. Input Data for the Implementation of the TEMP5 Program (Cont.)

(1) DATAIN Seq. No.	(2) Datum Name	(3) Variable Name	(4) Default Value	(5) Format Code	(6) Usage Code	(7) Description
10	MI	MI	1	0	T	Every MI-th point in the radial direction is printed (see I7).
11	NI	NI	1	0	T	Every NI-th point in the axial direction is printed (see I7).
12	ICNT	ICNT	1	0	T	Array U is printed out for every ICNT-th time cycle (see I7).
13	IU	IU	0	0	T	If 0, temperature distribution U initialized to U0. If 1, initial temperature distribution read-in on file tape ICARD.
14	IQ	IQ	1	0	T	If IQ = 0, initialize source Q to zero. If IQ = 1, initialize source Q to Gaussian. If IQ ≠ 0, 1 read source Q from file tape ICARD.
15	<u>N0</u>	<u>N0</u>	2	0	T	The arbitrary positive integer n_0 in Eq. (82) of text.
16	NMX	NMX	11	0	T	nmax (see Sec. 8.6).
17	IRUN	IRUN	100	0		Not used.
18	ICARD	ICARD	5	0	T	Input file for some of the input controlled by IU, IQ.

Table 2. Input Data for the Implementation of the TEMP5 Program (Cont.)

(1) DATAIN Seq. No.	(2) Datum Name	(3) Variable Name	(4) Default Value	(5) Format Code	(6) Usage Code	(7) Description
19	IPRINT	IPRINT	6	0	T	Output file for all TEMP5 output except for some of the "interactive" output and unformatted temperature output.
20	IPNCH	IPNCH	-	0	N	In original TEMP5, identifies "punch" output file.
21	ITAP3	ITAP3	3	0	T	Unformatted output file for time-temperature.
22	ITAP4	ITAP4	4	0	T	"Interactive" input file.
23	RHO1	RHO1	0	1	T	ρ_1
24	RHO12	RHO12	1	1	T	ρ_{12}
25	ZED1	ZED1	-.5546	1	T	ξ_1
26	ZED12	ZED12	1.1092	1	T	ξ_{12}
27	DTAU <u>0</u>	DTAU <u>0</u>	.0035	1	T	$\Delta\tau_o$
28	TAUMX	TAUMX	5.0	1	T, K	τ_{max} (see Sec. 8.6).
29	TAUOFF	TAUOFF	5.0	1	T	τ_{off} (see Sec. 8.6).
30	SIG	SIG	.1292	1	T, K	Either σ or σ_e (see Eq. (33) or (37)).
31	<u>Q0</u>	<u>Q0</u>	0	1	T	If you want $A = \Delta\tau_c/2\sigma^2$ (see Eq. 37), then set $Q0 = A$. (Be sure $A \geq .001$; highly unlikely to be otherwise). If you want $A = 1/2 \sigma_e^2$ (see Eq. 33), then set $Q0 < .001$ (say, 0).
32	<u>U0</u>	<u>U0</u>	0	1	T	Initial (uniform) temperature distribution.

Table 2. Input Data for the Implementation of the TEMP5 Program (Cont.)

(1) DATAIN Seq. No.	(2) Datum Name	(3) Variable Name	(4) Default Value	(5) Format Code	(6) Usage Code	(7) Description
33	EPS	EPS	.001	1	T	Error tolerance in spline interpolation.
34 to 37	G1(1), G1(2), G1(3), G1(4)	G1	0, 0, 0, 0	1	T	Surface heat flux (see Eqs. (33) or (37)).
38 to 41	H1(1), H1(2), H1(3), H1(4)	H1	0, .0113 .0113 .0113	1	T	Surface heat transfer coefficient (see Eqs. (33) or (37)).
42	MATERIAL	MATER	KCL	-1		Cylinder material identifier. Used for identification purposes only. It is not "used" by any program, but can, of course, be printed in TIKIRK listings and on DISPLAY plots.
43	REF. IND.	NX	1.47	1	K	Cylinder refractive index.
44	BETA	BETA	.00048	1	K	Bulk absorption coefficient (cm^{-1}).
45	THER.COND	K	.0653	1	K	Thermal conductivity ($\text{W}/\text{cm} \cdot {}^\circ\text{C}$).
46	LAMBDA	LAMBDA	10.6	1	K	Wavelength (microns).
47	S1R	S1R	-.34E-5	1	K	Stress optic coefficient $S_1^0({}^\circ\text{C})^{-1}$.
48	S1T	S1T	.05E-5	1	K	Stress optic coefficient $S_1^0({}^\circ\text{C})^{-1}$.
49	S2R	S2R	.1E-5	1	K	Stress optic coefficient $S_2^0({}^\circ\text{C})^{-1}$.
50	S2T	S2T	-.1E-5	1	K	Stress optic coefficient $S_2^0({}^\circ\text{C})^{-1}$.
51	DENSITY	DEN	1.98	1	K	Density (gm/cm^3).
52	SPEC.HEAT	CP	.691	1	K	Specific heat ($\text{J}/\text{gm} \cdot {}^\circ\text{C}$).
53	RADIUS	R	1.258	1	K	Radius (cm).

Table 2. Input Data for the Implementation of the TEMP5 Program (Cont.)

(1) DATAIN Seq. No.	(2) Datum Name	(3) Variable Name	(4) Default Value	(5) Format Code	(6) Usage Code	(7) Description
54	EXPER	EXPER	2	-1		Not used.
55	PWR	PW	24.7	1	K	Transmitted power P_t , in watts (see Eq. 9).
56	R1	R1	81	0		Not used.
57	Z1	Z1	11	0		Not used.
58	R2	R2	1	0		Not used.
59	PLT? IY, 2N	IPILOT	1	0		Not used.
60	PROBNO	PROBNO	2347	-1		Problem number-for plot identification.
61	TICU	TICU	.5	1		Not used.
62	XLEN	XLEN	20.	1		Not used.
63	YLEN	YLEN	9.	1		Not used.
64	X-SCALE	SCALEX	12.	1		Not used.
65	Y1-SCALE	SCALEY1	.2	1		Not used.
66	Y2-SCALE	SCALEY2	.2	1		Not used.
67 to 71	XTITLE1 2, 3, 4, 5	XTITLE	time	-1	D	The x-axis is given a title of the form "XTITLE scale is n units/tic" where n may be scalex. Also parameter title.
72 to 76	YTITLE1 2, 3, 4, 5	YTITLE1	temp-deg. C above amb	-1	D	Similar to XTITLE, "surface" title in DISPLAY.
77 to 81	YTITLE2 2, 3, 4, 5	YTITLE2	mean temp above amb	-1		Not used.
82	OPERATOR	NAME	GIANINO	-1	D	Plot identification (required for picking up plots at central site).

Table 2. Input Data for the Implementation of the TEMP5 Program (Cont.)

(1) DATAIN Seq. No.	(2) Datum Name	(3) Variable Name	(4) Default Value	(5) Format Code	(6) Usage Code	(7) Description
83 to 87	XTI 2, 3, 4, 5		radial distance rho-(cm)	-1	D	Title for "x-axis" in DISPLAY.
88 to 92	YT1 2, 3, 4, 5		axial distance, z-(cm)	-1	D	Title for "y-axis" in DISPLAY.

N.B. 0 means "zero"; 0 means "oh".

Explanation of Columns

- (1) The sequence number of the datum stored in array DATAIN.
- (2) Datum name used by operator when he inputs the data. This name is a character string. E.g., I1 means 2HI1 in Hollerith notation.
- (3) The symbolic name used in the TEMP5 program. The same quantity may be given a different variable name in other programs that used the quantity.
- (4) The value that will be assigned to each item listed, unless a different value is inputted.
- (5)
 - 0 ≡ integer (I10) format.
 - 1 ≡ floating point (E10.0) format.
 - 1 ≡ character string (6A10) format, that is, up to 60 characters are permitted.
- (6)
 - N ≡ not used.
 - Y ≡ used in TEMP5 program.
 - K ≡ used in TIKIRK program.
 - D ≡ used in DISPLAY program.

Table 3. Glossary of Variable Names^{*†}

A(I)	. =. Tridiagonal system . =. coefficient vectors.
B(I)	. =. Tridiagonal system . =. coefficient vectors.
BETA(I)	. =. Auxiliary variable: Thomas Algorithm for TRIDAG matrix inversion.
C(I)	. =. Tridiagonal system . =. coefficient vectors.
D(I)	. =. Tridiagonal system . =. coefficient vectors.
DRHO	. =. Program control parameter . =. $\Delta\rho = (\rho_2 - \rho_1)/M$.
DTAU	. =. Time increment parameter . =. $\Delta\tau$.
DTAU <u>0</u>	. =. Time increment parameter . =. $\Delta\tau_0$.
DZED	. =. Program control parameter . =. $\Delta\xi = (\xi_2 - \xi_1)/N$.
E(I)	. =. Space increment array . =. DRHO, DZED.
EPS	. =. Error tolerance in iterative steps.
F1(I)	. =. An array of integrals.
F2(I)	. =. An array of integrals.
G(I)	. =. Coefficient in general boundary condition.
GAMMA	. =. Auxiliary working variables-Thomas Algorithm (see Eq. (58)).
GAUSS	. =. Subroutine for loading Q with a truncated Gaussian distribution.
GF(X, Y, Z)	. =. Statement function = $(2.*Y*Z)/(2.+X*Y)$.
G/H	. =. Given nondimensional surface temperature.
G(I)	. =. g_1, g_2, g_3, g_4 . . =. boundary condition parameter.
G1(I)	. =. Buffer to retain input G(I). G(I) modified during program execution.
H(I)	. =. h_1, h_2, h_3, h_4 . . =. boundary condition parameter. Film coefficient.
HF(X, Y)	. =. Statement function . =. boundary condition . =. $(2.-X*Y)/(2.+X*Y)$ (see Eqs. (44)-(47)).

*The symbol . =. means "is defined as."

† 0 means "zero"; 0 means "oh."

Table 3. Glossary of Variable Names (Cont.)

<u>H=0, G=0</u>	. =. No heat crosses boundary . =. physical significance of H and G.
H1(I)	. =. Buffer to retain input H(I). H(I) is modified during program execution.
I	. =. Indexing variable.
ICARD	. =. Logical device number for card reader.
ICNT	. =. Number of I. A. D. cycles between printouts.
ICNTR	. =. Number of I. A. D. cycles since last printouts.
IF	. =. Indexing variable.
II	. =. I-1.
IKEY	. =. Logical device number for keyboard (or card) input.
IPM(I)	. =. Basic program parameters integer: see equivalence statements.
IPNCH	. =. Logical device number for the card punch.
IPRINT	. =. Logical device number for line printer.
IQ	= <u>0</u> . =. Initialize Q to zero . =. no absorption. = 1 . =. Calculated Q for Gaussian distribution. = 2 . =. Read in value of Q.
IRUN	. =. Run number.
ITAP3	. =. Logical device number for TAPE3.
ITAP4	. =. Logical device number for TAPE4.
ITYPE	. =. Printing out on operators terminal (if possible). Logical device number.
IU	= <u>0</u> . =. Initialize U (temp) to zero. = 1 . =. Read in initial value of U.
I1	. =. Punch and print F1, F2, and parameters. Control for output.
I2	. =. Print TAU, LMDS, MU, NN, NO, ICNT, ICNTR. Control for output.
I3	. =. Print KK, A, B, C, D, UPRIM . =. Initialize values of U, USTAR, etc. TRIDAG debug.
I4	. =. Print U and Q after initial data read-in or computed.

Table 3. Glossary of Variable Names (Cont.)

I5	. =. Print I, J, UFIN(I, J, K).
I6	. =. Punch UFIN and parameters.
I7	. =. Print I, J, U(I, J) on half increment shifted lattice.
J	. =. Indexing variable.
JJ	. =. Varies with J for indexing.
K	. =. Indexing variable . =. see cross reference.
KK, KS, L	. =. Indexing variables.
LMDA	. =. $\lambda = \Delta\xi(\Delta\rho)$. =. Special parameter.
M	. =. ρ -net length . =. $M \cdot \Delta\rho = 1 - \rho_1$.
MI	. =. Step size for output do-loop . =. ρ -direction.
MS	. =. Number of given data points.
MU	. =. $\mu = \Delta\tau / (\Delta\xi)^2$.
M1	. =. M+1. Loop indexing variable.
M2	. =. M1+1. Loop indexing variable.
N	. =. Special parameter . =. Count of Tau increments.
NF	. =. Number of time intervals.
NFF	. =. Duplicate storage for NF.
NI	. =. Step size for output do-loop . =. zed direction.
NMX	. =. N_{max} .
NN	. =. n.
NS	. =. Number of Spline Interpolated arguments.
NSEQ	. =. Sequencing index for punched card output.
<u>N0</u>	. =. Delta Tau doubling count.
N1	. =. N+1.
N2	. =. N1+1.
PARAM(I)	. =. Basic program parameters, REAL, see equivalence statements.
Q(I, J)	. =. Source distribution.

Table 3. Glossary of Variable Names (Cont.)

<u>QQ</u>	. =. Working variable used in do-loop for Q(I, J).
QUA(I)	. =. Values of integral SS from X(I) to X(N).
<u>Q0</u>	. =. Control parameter for calculation of Q(I, J) in GAUSS.
REX	. =. RNN/RNO.
RFIN(I)	. =. Even R-Lattice point coordinates.
RHO(I)	. =. Half-interval shifted.
RHO1	. =. ρ_1 .
RHO12	. =. $1 - \rho_1$.
RI	. =. II.
RJ	. =. JJ . =. RJ/2.
RM	. =. M.
RN	. =. N.
RNN	. =. Real representation of NN to avoid mixed mode in Delta Tau calculation.
<u>RNO</u>	. =. Real representation of <u>N0</u> to avoid mixed mode in Delta Tau calculation.
RRR(I)	. =. RFIN(I).
SIG	. =. Variance of Gaussian beam intensity dist.
SIG2	. =. SIG squared.
SS1(I)	. =. First derivatives of U.
SS2(I)	. =. Second derivatives of U.
TAU	. =. Nondimensional time . =. τ .
TAUMX	. =. Maximum tau to be computed . =. τ_{\max} .
TFIN	. =. Array of τ -values for which we take printed or punched output.
U(I, J)	. =. Array of nondimensional temperatures on RHO-ZED lattice.
UCARD	. =. UFIN buffer for card and line printer output.
UFIN(I, J, K)	. =. U on RFIN-ZFIN lattice at Kth time.

Table 3. Glossary of Variable Names (Cont.)

UPRIM(I)	. =. Storage of results of solutions to tridiagonal equations.
USPLN(I)	. =. Temporary work space used between Rho-splining and Zed-splining.
USTAR(I, J)	. =. Intermediate temperature distribution in I. A. D. method.
<u>U0</u>	. =. U(I, J). For uniform initial temperature option.
V	. =. Computed solution vectors in TRIDAG.
X(I)	. =. Array of strictly increasing abscissa.
XR(I)	. =. RHO(I).
XX	. =. Work space for desired abscissas.
XZ(I)	. =. RHO protection.
YU(I)	. =. UFIN(I, J).
ZED(I)	. =. Nondimensional axial coordinate [cm] . =. Z/A.
ZED1	. =. Lower Zed boundary . =. ξ_1 .
ZED12	. =. $\xi_2 - \xi_1$.
ZFIN(I)	. =. Lattice coordinates that land on boundary instead of half shifted position. Used for CYLTMP Algorithm.
ZJ	. =. JJ.
ZZZ(I)	. =. ZFIN(I).

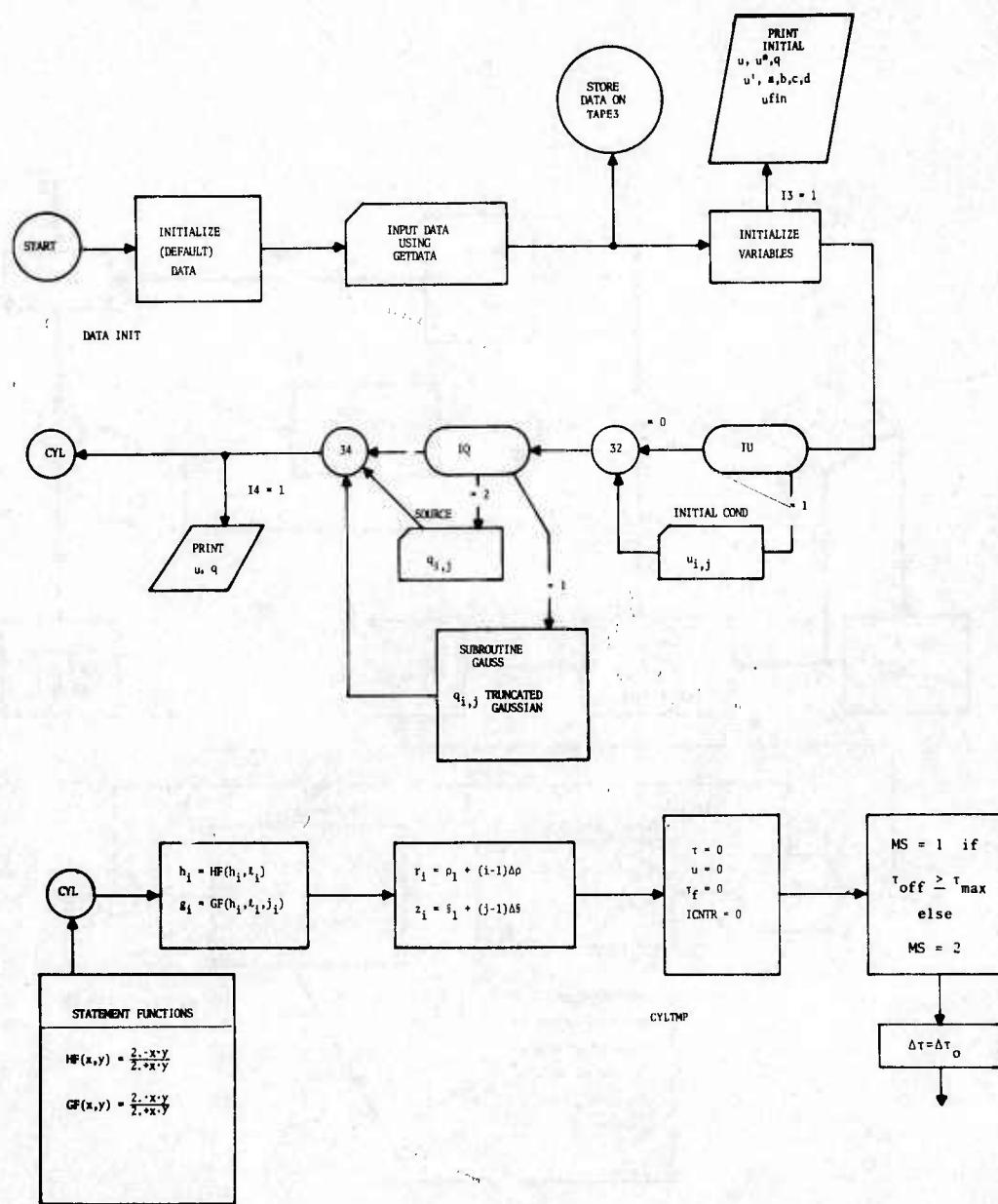


Figure 20. Flow Chart for the CYLTMP Algorithm (Sheet 1 of 4)

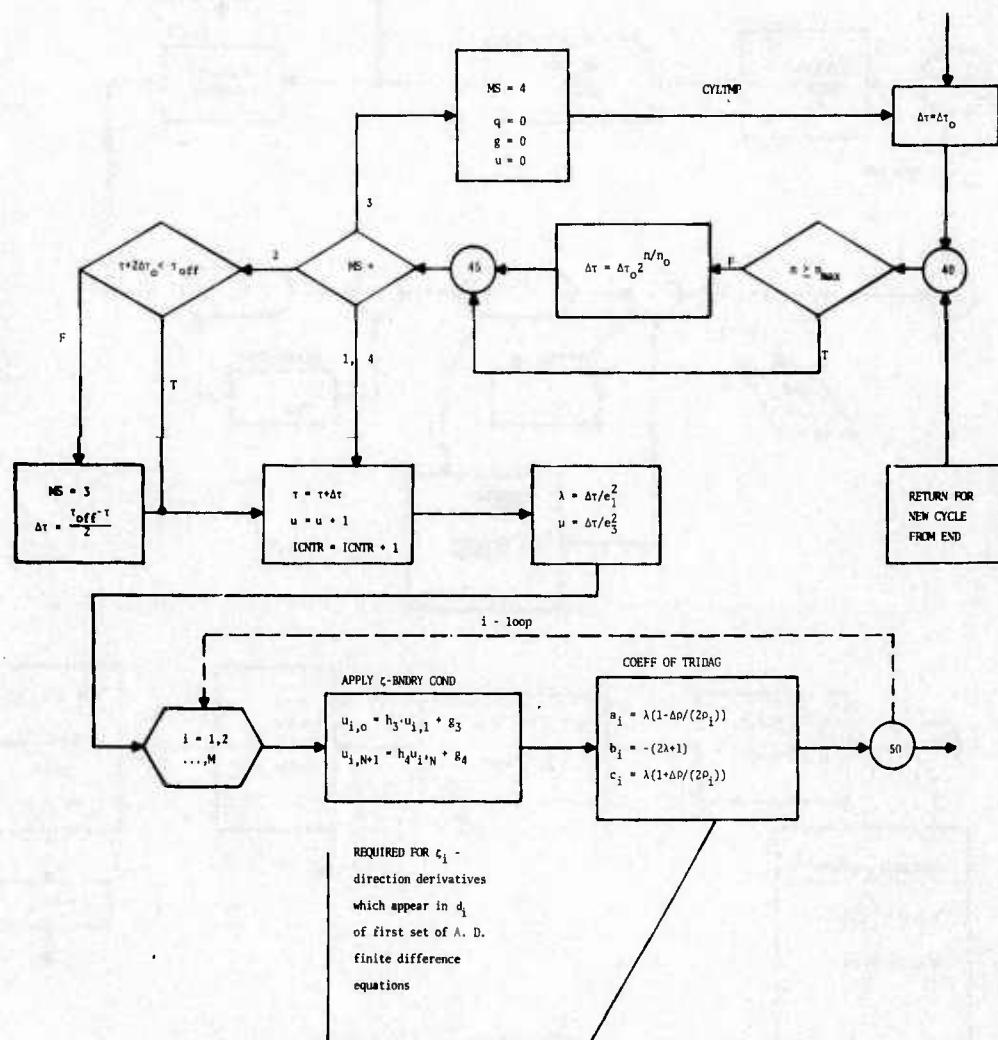


Figure 20. Flow Chart for the CYLTMP Algorithm (Sheet 2 of 4)

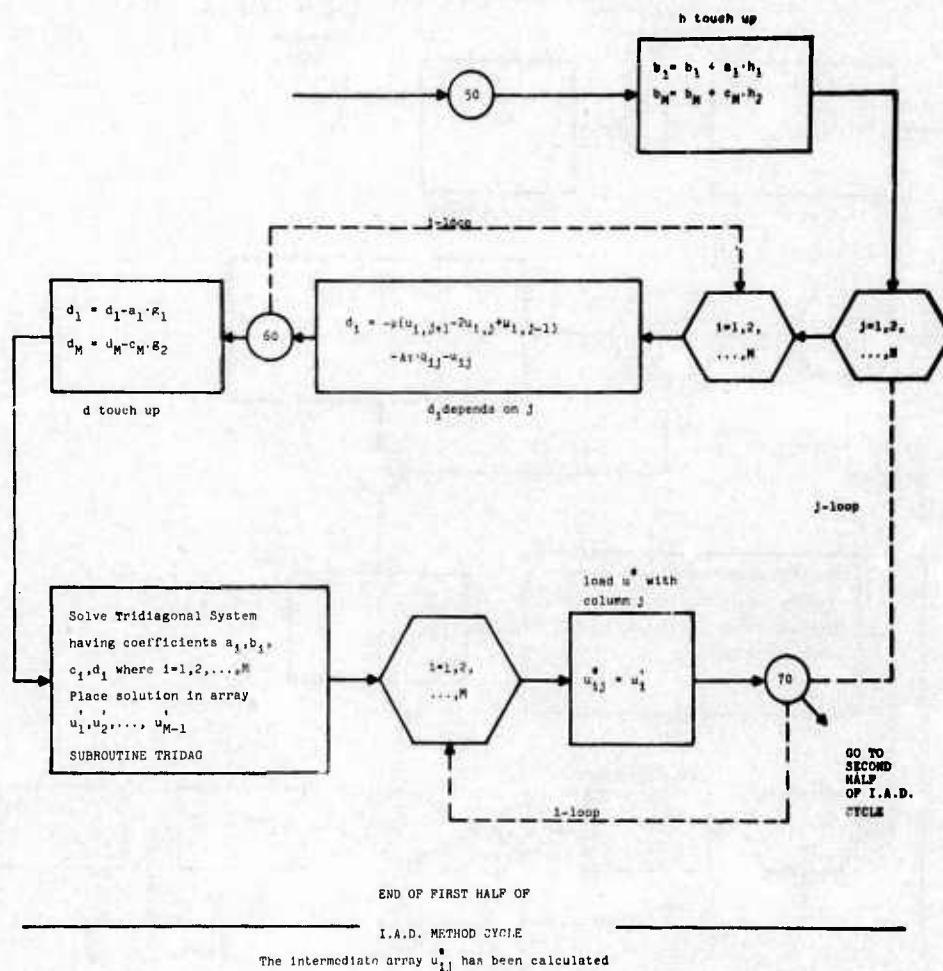


Figure 20. Flow Chart for the CYLTMP Algorithm (Sheet 3 of 4)

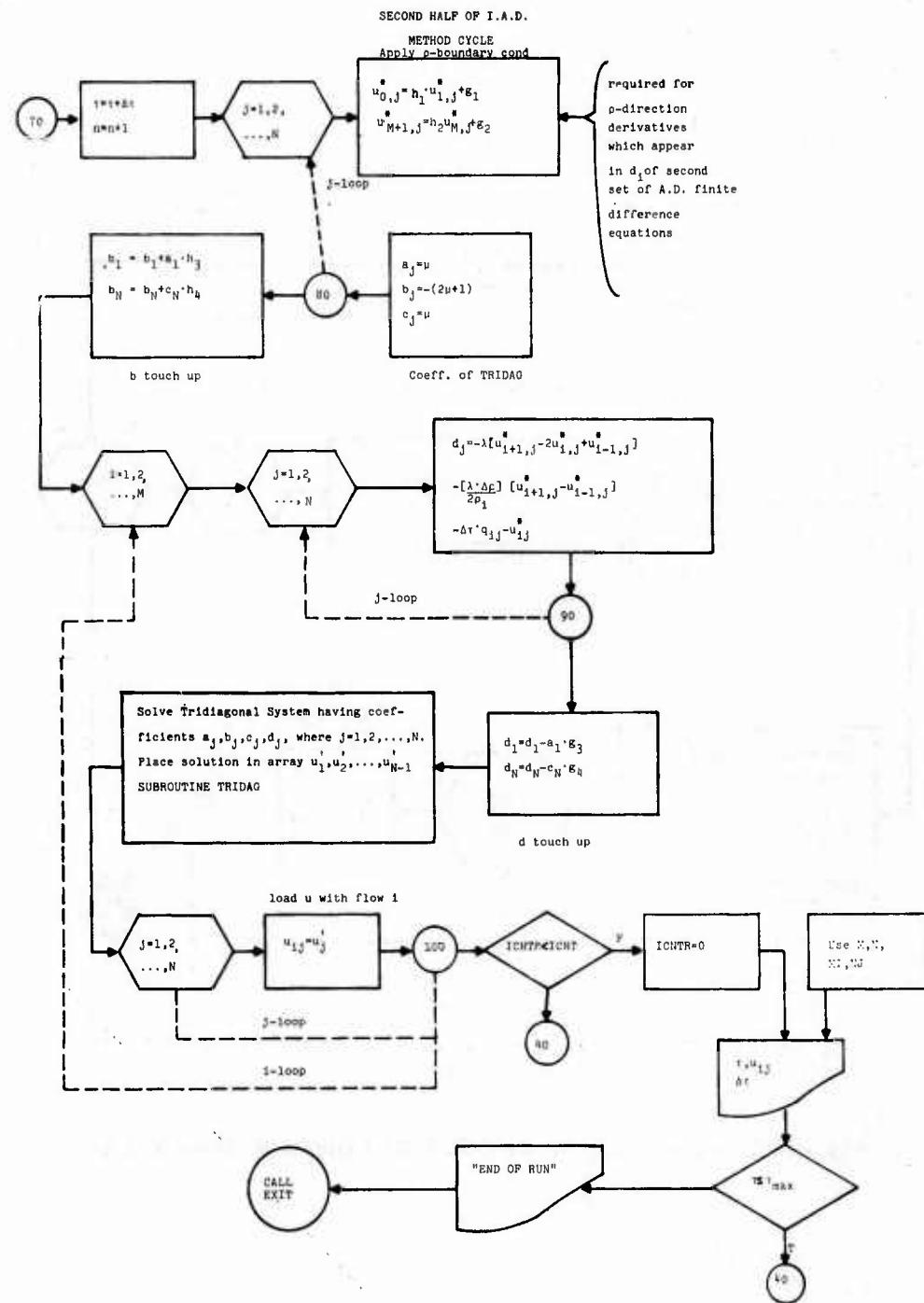


Figure 20. Flow Chart for the CYLTMP Algorithm (Sheet 4 of 4)

data when the program is "batched." The data which is obtained through GETDATA is stored in array DATAIN as an n by 3 array, where n is the maximum number of data to be inputted. Each datum consists of three parts (hence $n \times 3$), which is herein referred to as VALUE, NAME, and FORMAT. VALUE is the numerical or character string value which will be stored for the datum; NAME is a character string (up to ten characters) by which the datum may be identified. FORMAT is a code number (-1, 0, or 1) which is used to indicate that the datum is to be interpreted respectively as: character string, integer, or real (floating point) number.

The first three data required by GETDATA are not part of DATAIN, but are used to control the operation of GETDATA. In INTERCOM mode each of these three data are preceded by questions as follows:

- 1) READ DATA FILE -n?- (n is the file number)
- 2) DEFAULTS LISTED?-
- 3) NAME-VALUE MODE?-

The input data is either YES or NO (the default is NO). If the answer to 1) is YES, then array DATAIN is filled from the first record on TAPE-n. Normally, DATAIN should be filled with defaults in the calling program. These default values will then be replaced by new "default" values obtained from TAPE-n.

If the answer to 2) is YES, then the default DATAIN is printed out in the form:

NAME=VALUE.

FORMAT is indicated by the form in which VALUE is printed. Integers are numerical values with no decimal point; floating point numbers are printed with a decimal point and possibly an exponent. Character strings are indicated by single quotes. The default values are listed in the order in which they are stored in DATAIN.

If the answer to question 3) is YES, then the NAME-VALUE input-mode is used to input data; otherwise, the LIST mode is used. These two input modes are described in detail below.

After these "control" data have been inputted, the DATAIN data are inputted.

8.8.4.2 List Mode

In the LIST mode, GETDATA starts out by printing the first NAME in DATAIN and then waits for the operator to type the VALUE to be assigned to NAME. Similarly, it sequences up to the last NAME in DATAIN, and then prints out a message "data input complete," after the last VALUE in the sequence has been given by the operator. The operator defaults a value by punching the "space," "carriage return" keys (denoted below as SP, CR, respectively). If at any time the operator realizes that an error has been made in typing any preceding VALUE (not just the

current one), it may be corrected by typing \$, CR. This causes a shift to the NAME-VALUE mode, under which both the VALUE and NAME must be given by the operator. By this means, VALUES which were assigned earlier in the sequence can be changed. After the correct name and value have been given by the operator, the LIST mode continues where it left off. For example, if the NAME, OPERATOR was listed and the operator had typed \$ next to this NAME, the same NAME would be typed again upon return from the NAME-VALUE mode. It might be noted that if a VALUE has been typed (and not signaled with \$) which is incompatible with the FORMAT to be associated with that value, then the subroutine automatically goes into the NAME-VALUE mode after typing the message: "wrong data type-try again."

The NAME-VALUE mode has the feature of terminating input, whenever SP, CR are typed, when the program is waiting for a new NAME, VALUE pair. Thus, it may be convenient to terminate inputting when in the LIST mode, by typing \$, then SP, CR after the NAME-VALUE mode has been initiated.

8.8.4.3 Name-Value Mode

In this mode, the program first types out the words "name" (6 blanks) "value.....", and then waits expectantly with the type head directly under the "n" of "name." The operator must then type the NAME and corresponding VALUE, with the VALUE starting under or after the "v" of "value." The "...." after "value" indicate the maximum field for inputting numerical data. If the operator types a NAME which is unrecognizable, the message "try again" is typed, followed by another "name" (6 blanks) value.....". A mistake is corrected by merely typing the NAME of the datum to be corrected followed by its correct VALUE. (If a format mistake has been made--see LIST MODE--then the message "wrong data type-try again" is printed indicating that the name-value should be retyped. The "name value...." header is printed only once (or every time an unrecognizable NAME has been inputted) since thereafter it is easy to start NAME and VALUES in the correct positions. (The typehead is always placed under "n" when new data is expected.)

Data input is terminated by typing SP, CR whenever the typehead is under the "n" column of the header.

The field width for all data is ten. Specifically, integers (format=0) are read under I10 format; reals (format=1) are read under E10.0 format. Character strings (format=-1) are read under A10 format, but up to 60 characters may be inputted "at once" provided contiguous space in DATAIN has been provided for them. For example, suppose that DATAIN(10, 2), DATAIN(11, 2), DATAIN(12, 2) are given the NAMES XTITLE(1), XTITLE(2), XTITLE(3), respectively (implying that space for up to 30 "XTITLE" characters has been provided for), then the entire "XTITLE" could be inputted as follows:

NAME	VALUE.....
XTITLE(1)	DISTANCE ALONG X-AXIS (INCHES)

In the LIST MODE it is also possible to input six numerical data values at "one time." This should only be done when the job is "batched," in which case six data values may be placed on one card, each one occupying a 10-column field. Data which is not to be changed should be replaced by blanks. All or some of the data may be defaulted by using an end-of-record card after the last data to be inputted, causing GETDATA to return to the program or subroutine. If no data is included in the input file a call to GETDATA will have no effect (default DATAIN as provided by the calling program will be used), except the end-of-file indicator INDIC will be set to 1.

GETDATA has a special "gimmick" in that if it is called with a value of INDIC other than 0, it may be used to input a single datum in the LIST mode. To be used in this mode, INDIC should be set equal to the location in DATAIN of the value desired, for example, 50 for DATAIN (50, 1).

According to standard Fortran practice, trailing blanks (of numerical values) are treated as zeros. For example, 10E1 would be interpreted as 10E1~~0000~~ (that is, 10^{10000}) and 1 would be interpreted as 1~~000000000~~ (that is, 1×10^9). GETDATA calls a subroutine (RJUST) which removes all trailing blanks from numerical (but not character string) data so that trailing blanks are not treated as zeros.

8.8.4.4 Entry-Parameter List:

SUBROUTINE GETDATA (DATAIN, NV, IIN, IOUT1, IOUT2, IIN1, ISIZE, ISIZET, INDIC) Parameters:

- DATAIN - 3 dimensional array of values, names and formats.
- NV - amount of data to be inputted.
- IIN - input file number for GETDATA.
- IOUT1 - "interactive" (primary) output file for GETDATA.
- IOUT2 - secondary output file (stores formatted names and values which are returned by GETDATA).
- IIN1 - "scratch" input/output file for reading in "default" values of DATAIN and outputting DATAIN as modified by GETDATA. (Unformatted i/o).
- ISIZE - DATAIN is assumed to be dimensioned (ISIZE, 3) in the calling program. It is the size of the first dimension of DATAIN.
- ISIZET - 3* ISIZE.

INDIC - an end of file indicator. A value of 1 is returned if an end-of-file on input occurs. If INDIC is given a value other than 0 in the calling program, GETDATA will go into the LIST mode to obtain DATAIN (INDIC-).

When operating under INTERCOM, files IIN and IOUT1 should be "connected." The storage required for GETDATA plus its two required subroutines RJUST and SSWTCH is 266 words.

8.8.4.5 Algorithm

All data "cards" are read using 6A10 format. If the first word is blank, then the subroutine goes to the next "card" (LIST-mode) or terminates (NAME-VALUE mode). In the LIST mode, fields are searched for the first blank field, upon which the next "card" is read. In NAME-VALUE mode, the search is made only if the FORMAT code for the datum is -1, indicating a possible character string greater than 10 characters. In LIST mode, a search is made of each field to see if \$ occurs using AFCRL subroutine MXGETX. If it does, a jump is made to the NAME-VALUE mode of input. All values which are to be interpreted as numbers (integer or real) have their character string representations right adjusted using PML subroutine RJUST. The conversion from character string to coded number is done with the DECODE statement using the appropriate format (I10, E10.0, or A10).

The CDC subroutine ERRSET is called in case of a bad format. A bad format causes a jump to NAME VALUE mode of input.

8.8.4.6 Special Caution and Features

There are three different formats recognized by GETDATA: floating point (E10.0), integer (I10), and character string (6A10).

These formats are given the codes 1, 0, -1, respectively. The E10.0 format converts any decimal number which can be "sensibly" written as a string of ten or less characters into CDC6600 floating point number representation. Examples of permissible character strings are:

328.5678E4

328.5678+4 (the E may be omitted)

3285678.

3285678 (a decimal point is not necessary)

-5.77E-10

Specifically, a floating point number may be written with or without an exponent (which may be indicated by the letter E followed by a signed or unsigned integer OR a signed integer). It may or may not have a decimal point. Blanks are ignored.

The I10 format converts any decimal integer which can be written as a sequence of 10 or less characters from the set $[+, -, 0, \dots, 9]$ into a CDC6600 integer. Trailing, as well as leading blanks within the field are effectively ignored. This is convenient since it is easier to input 1 for instance, as opposed to ~~0000000001~~ or 0000000001. Note, however, that 3~~00~~2 would be interpreted as 3002, that is, intermediate blanks are considered to be zeros. (Note that an all blank field is NOT equivalent to 0 for GETDATA.)

The 6A10 format allows character strings of up to 60 characters to be inputted "at once." However, one must make sure that sufficient space has been provided to receive character strings of length greater than 10, since each computer word holds a maximum of 10 characters. Any of the 64 characters listed in Appendix A of the CDC Fortran Extended Manual (more or less equivalent to the set on an INTERCOM teletype terminal) are permissible characters in the string. However, the character \$ has special significance. When operating in the LIST mode, its appearance signifies that a mistake has been made in inputting some value, and the subroutine temporarily reverts to the NAME-VALUE mode. In this mode, \$ has no special significance and is accepted as a legitimate character.

GETDATA assumes that DATAIN has been filled with default VALUES, as well as with the desired NAMES and FORMATS. This initialization of DATAIN can be done by the calling program OR by GETDATA itself, by reading in a DATAIN record from file IIN1.

It is usually convenient to equivalence DATAIN to a block of variables in the calling program. This simplifies subsequent handling of the values returned by GETDATA to the calling program.

GETDATA also prints out the following error messages to aid the programmer:

i) "try again"

Occurs when in the NAME-VALUE mode and an unrecognizable NAME is given.

ii) "file n is empty"

Occurs when an attempt is made to fill DATAIN from an empty file.

iii) "wrong data type - try again"

Occurs when a bad format is given for the datum.

9. TIKIRK PROGRAM

9.1 Introductory Remarks

The principal objective of the TIKIRK program is to compute the Kirchhoff intensity function, as given in Eqs. (23) or (28), Volume I. Before this can be accomplished, however, the file TAPE3 containing the nondimensional temperature w versus nondimensional time τ , as outputted by program TEMP5, must be available. Besides providing the nondimensional mean temperature distributions F_1 and F_2 mentioned previously, this file also provides as the first record an array of constants which are required to dimensionalize the data into real temperature versus real time (cf, Sections 3, 4, and 5 of Volume I and Table 2 of Volume II). For a more complete description of this file, see Section 9.5.

9.2 Program Options

The TIKIRK program has been set up to operate under two different options; each one being brought into play by an appropriate choice of the parameter $I2$ in TEMP5 (see Table 2). The first option uses subroutine IKIRK, which calculates the intensity I as a function of space and time for a Gaussian source term. It does so using a 24-point Gaussian integration routine. It is the option that would be used under most circumstances. The second option constitutes a special test case. A subroutine called IKIRKP is used to evaluate the intensity functions on either one of the two mutually orthogonal axes going through the Gaussian focal point for the special case of a window having a uniform mean temperature.

Allowing the control parameter $I2$ in the TEMP5 program to remain equal to its default value of 2, causes the first option to be utilized, while setting $I2=1$ brings the second option into play.

Since the form of numerical quadrature employed in option #1 may not be accurate for all parameter values which occur in practice, a third option, which uses a subroutine called IKIRK1, is also available. This program is highly accurate (because its integration methods are more exact), but it is extremely slow. It should be used for relatively small ranges of the space-time variables, for example, as a "spot check" for IKIRK.

9.3 Principal Functions and Subroutines

The TIKIRK program requires that various operations, such as integration, interpolation, Bessel function computation, etc., be carried out during the process of its execution. These operations are performed by various function subprograms and subroutines. The names of these functions and subroutines are listed below, together with their principal tasks:

- (1) TIKIRK - the main program which calls the other subroutines and subprograms into execution. It also acts as the input/output interface for the main real functions IKIRK, IKIRKP and IKIRK1 (see below).
- (2) IKIRK - the main real function for option #1.
- (3) PHI - the function which computes $\Phi^{\rho, \theta}$.
- (4), (5) J_0 and J_1 - real functions; compute $J_0(\rho v)$ and $J_1(\rho v)$, respectively.
- (6) RTAPE3 - subroutine; reads and linearly interpolates (in time) temperature values from TEMP5. It also linearly interpolates in time and then outputs the dimensionalized window temperature function in a form suitable for plotting via program DISPLAY.
- (7), (8) ALI and ATSE - interpolation subroutines for PHI. ALI uses the Aitken-Lagrange method.
- (9) DQG24A - subroutine; computes x-values for Gaussian integration.
- (10) DQG24B - subroutine; does Gaussian integration.
- (11) IKIRKP - the main real function for option #2.
- (12) COMPUTE - subroutine; computes the approximations to the integrals which are used in option IKIRKP.
- (13) JI - a real function which computes moments of Bessel functions.
- (14), (15) BESJF and BESJ - a function and a subroutine, respectively, which compute the Bessel function for a given argument and order.
- (16) GETDATA - a subroutine for interactively inputting data.
- (17), (18) SSWTCH and RJUST - subroutine used by GETDATA. (See Sections 8.7 and 8.8 for more detailed explanations of GETDATA, SSWTCH and RJUST.) The listings for these two subroutines have already been given in Appendices A.8 and A.9.
- (19) PRT - printed output subroutine.

All three options mentioned above use the same "core package" of the following function subprograms and subroutines in their execution: TIKIRK, PHI, J_0 , J_1 , RTAPE3, ALI, ATSE, GETDATA, SSWTCH, RJUST and PRT. In addition to these, option #1 uses IKIRK plus the subroutines DQG24A and DQG24B, while option #2 utilizes IKIRKP plus COMPUTE, JI, BESJF and BESJ.

We have given this entire package of 19 main programs, subroutines, etc., constituting the TIKIRK program for options #1 and #2 only, the permanent file name (PFN) of TIBX.

The complete Fortran listings for each of the above function subprograms and subroutines are given in Appendix B.

9.4 Inputting the Data

After program TEMP5 has been executed, output file TAPE3 has been produced and the TIKIRK program attached, various program control data and constants pertaining to the calculation of the intensity function must be inputted, regardless of the option desired. A list of these data is given in Table 4. (The array containing this information is called DATAIN1 in the TIKIRK program.) The column headings are identical with those of Table 2, except that there is no Usage Code column included here. Their meanings are cited in a footnote in the table.

The total "load" storage required for the TIKIRK program is 56133 B words. (The program will operate with a core memory of 60K.) Single precision is used for most calculations. In fact, a comparison of IKIRK and IKIRKP indicates agreement to 4 significant figures.

Since the maximum number of sample "v-values" is 100, then MP should be ≤ 100 . If more sample values are required, then array BUF should be dimensioned accordingly. Producing the full array of 100×100 function values takes 327 cpu secs (with OPT=1).

9.5 Program Files

The TIKIRK program depends on unformatted output from the TEMP5 program and requires up to 6 files. The names of the files used are (in the order they appear in the program statement):

TAPE4 - "Interactive" input file for inputting data via GETDATA. It is used for formatted read and must be set to INPUT for batch operation.

TAPE5 - "Interactive" output file for outputting messages from GETDATA and for outputting a small amount of program flow information.

TAPE3 - Unformatted file outputted by TEMP5. This file, among other things, contains the mean temperature distribution functions F1 and F2 required by IKIRK and IKIRKP. In addition, the first record is the 100 by 3 array referred to as DATAIN containing various constants required by TIKIRK and contained in Table 2. The following temperature records are assumed to be of the form:

NF, TFIN, RFIN(82), ZFIN(22), UFIN(82, 22), F1(82), F2(82)

TAPE7 - Unformatted file containing the intensity distribution function in a form suitable for DISPLAY. The first two records are the 100 by 3 data arrays DATAIN and DATAIN1, the contents of which contain all pertinent program parameters as well as labeling information for DISPLAY. All subsequent records are of the form:

Table 4. Program Control Data and Constants Pertaining to the Calculation of the Intensity Function. The column headings are identical with those of Table 2, except that there is no Useage Code column included here.

(1) Seq. No.	(2) Datum Name	(3) Variable Name	(4) Default Value	(5) Format Code	(6) Description
1	X0	X0	1500.	1	Gaussian focus X ₀ (meters).
2	X1	X1	1000.	1	Minimum X-value (meters).
3	X2	X2	2000.	1	Maximum X-value (meters).
4	RHOP1	RHOP1	0.	1	Minimum ρ' -value (cm).
5	RHOP2	RHOP2	2.	1	Maximum ρ' -value (cm).
6	MP	MP	100	0	To calculate J values of intensity along the ρ' (or v) axis, where J = any integer, and have each calculation spaced by ρ'_{\max}/J (or v_{\max}/J) units, set MP = J + 1.
7	NP	NP	100	0	To calculate K values of intensity along the X (or u) axis, where K = any integer, and have each calculation spaced by $(X_{\max} - X_{\min})/K$ [or, $(u_{\max} - u_{\min})/K$] units, set NP = K + 1.
8	T1	TIM(1)	10.	1	Array of time values for function evaluation (seconds). Note that if $t_{i+1} < t_i$ then the program stops. Never set T1 = 0; use some small number instead, e.g., 1E-6.
9	T2	TIM(2)	-1	1	
-	-	-	-	-	
17	T10	TIM(10)	-1	1	Used by IBM Sci. Sub. ALI in interpolation of Φ^{ρ} , Φ^{θ} .
18	EPSI	EPSI	.001	1	Used by IBM Sci. Sub. ALI and ATSE in interpolation of Φ^{ρ} and Φ^{θ} , MINT is the number of points used in the interpolation.
19	MINT	MINT	6	0	Use 1 for controlling debug output. Use 2 when producing a TAPE8 file for plotting purposes.
20	IPRNT	IPRINT	1	0	Number of points for Gaussian integration. Note that this number should be changed if and only if the Gaussian integration subroutine is changed.
21	NGAUS	NGAUS	24	0	

Table 4. Program Control Data and Constants Pertaining to the Calculation of the Intensity Function. The column headings are identical with those of Table 2, except that there is no Useage Code column included here. (Cont.)

(1) Seq. No.	(2) Datum Name	(3) Variable Name	(4) Default Value	(5) Format Code	(6) Description
22	MODE	MODE	2	0	Use 1 if you want $I(X, \rho', t)$. Use 2 if you want $I'(u, v, t)$. (See Eqs. (28) and (23)).
23	UMIN	UMIN	-40.	1	Minimum u-value.
24	UMAX	UMAX	40.	1	Maximum u-value.
25	VMIN	VMIN	0.	1	Minimum v-value.
26	VMAX	VMAX	10.	1	Maximum v-value.
27 to 31	ST1 2, 3, 4, 5	- Kirchhoff intensity function		-1	"Surface" title (see DISPLAY).
32 to 36	PTI 2, 3, 4, 5	- Time (seconds)		-1	"Parameter" title (see DISPLAY).
37 to 41	XTI 2, 3, 4, 5	- Nondimen- sional radial distance, V		-1	"X-axis" title (see DISPLAY and note below).
42 to 46	YTI 2, 3, 4, 5	- Nondimen- sional axial distance, U		-1	"Y-axis" title (see DISPLAY and note below).
47	MSKIP	-	5	0	Of the J values of intensity calculated along the ρ' (or v) axis (see MP), every MSKIP-th value will be printed out.
48	NSKIP	-	5	0	Of the K values of intensity calculated along the X (or u) axis (see NP), every NSKIP-th value will be printed out.

NOTE: If mode = 1, then the above x, y-titles are replaced by "radial distance, rho-prime (cm)" and "axial distance, X (relative to gauss focus) (cm)," respectively.

N. B. 0 means "zero; o means "oh".

Explanation of Columns

- (1) The sequence number of the datum stored in array DATAIN1.
- (2) Same as in Table 2.
- (3) The symbolic name used in the TIKIRK program. A blank variable name means that that part of DATAIN1 has not been equivalenced to another variable.
- (4) Same as Table 2.
- (5) Same as Table 2.

I, NP, U, T, MP, XMIN, XMAX, (MP intensity values)

where

I = 1, ..., NP for each value of time, T

NP = number of axial points

U = axial distance (either u or x depending on mode)

T = dimensionalized time

MP = number of radial points

XMIN = minimum radial distance (either VMIN or RHOP1
depending on mode)

XMAX = maximum radial distance (either VMAX or RHOP2
depending on mode)

TAPE8 - Unformatted file containing the temperature distribution function
in a form suitable for display. The first record contains the 100
by 3 data array DATAIN. All subsequent records have the same
form as that listed above for TAPE7 except:

U = distance along window axis (cm)

XMIN = inner window radius (usually 0)

XMAX = outer window radius
(MP temperature values)

TAPE6 - Formatted "output" file. This file contains output suitable for
printing in the following sequence:

- 1) Contents of DATAIN
- 2) Contents of DATAIN1
- 3) Array of x-values used for Gaussian integration (if IPRNT=1 and
IKIRK is called).
- 4) I, U, XMIN, XMAX, T every rth I value
Intensity (I, J), J=1, MP, 5 if IPRNT=1

9.6 Implementing the Program

9.6.1 GENERAL INSTRUCTIONS

All of the TIKIRK data listed on Table 4 are inputted by two calls to subroutine
GETDATA, regardless of the option desired. Normally, in the first call to
GETDATA the required data (viz, the first DATAIN array) are obtained from file

TAPE3 by answering "yes" to the query READ DATA FILE-3? Then no changes are made to these data by returning a "space" in the "name value" mode of inputting data. On the second call to GETDATA, the operator always answers "no" to the query READ DATA FILE-7? and "yes" to the query NAME-VALUE MODE? At this point he enters the names and values of all of the input data whose numerical values differ from the default values as shown in Table 4.

The above information is sufficient for inputting the data when using the first option (that is, IKIRK). However, for those circumstances in which options #2 or #3 are desired, additional instructions are required and will be discussed in the next two sections.

Typical detailed commands which can be used to run all of the programs in both the Intercom and Batch modes are listed in various Attachments after Section 11. The "A" attachments pertain to full system operation in the Intercom mode; the "B" attachments exhibit typical control deck setups used to operate the system in the Batch mode.

Attachment 1 shows how to initiate and run a typical TEMP5- and TIKIRK-type calculation, catalog the results on permanent file and then print out these results. If a TEMP5 calculation has already been made and cataloged, Attachment 2 reveals how to change a few of the input variables so that a new temperature distribution may be obtained. If the TEMP5 calculation has been completed and cataloged, Attachment 3 indicates how to make changes in the TIKIRK parameters so that either a different portion of the former diffraction pattern or a completely new diffraction pattern will be produced with each change. Attachment 4 lists the commands necessary to produce the file, called TAPE8, which contains the temperature distribution in the window. This file is required in order to plot the temperatures.

Throughout all of the attachments, PFN stands for "permanent file name" and LFN for "logical file name."

9.6.2 SPECIAL INSTRUCTIONS FOR IKIRKP OPTION

As mentioned previously, the IKIRKP option will be employed when I2=1 in TEMI-5. It then calculates the intensities along either the X- or the ρ' -axes if MODE is set equal to 1, or, along either the u- or the v-axes if MODE=2. The choice of the value for MODE is made, of course, at the second call to GETDATA when inputting the data for the TIKIRK program. Specifically, IKIRKP assumes that the window temperature is constant throughout and that it may or may not be a function of time. This assumption considerably simplifies the integrations delineated in Eq. (23), Volume I, which lead to the intensity function. The details of the mathematics leading to the evaluation of $I'(u, 0, t)$ and $I'(0, v, t)$ are enumerated in Appendix C.

In addition to this choice of I_2 , a few other input parameters in TEMP5 must be fixed to assure that all of the conditions imposed on the window are properly accounted for. If the window temperature is to remain fixed with time (implying that there is no source), the IQ must be set to zero and U_0 to the appropriate temperature. Also, all $H_1(I)$ must equal zero, otherwise, if the window temperature is allowed to vary with time, then IQ must be set equal to 1, U_0 to the appropriate initial temperature and all $H_1(I)$ to zero. Furthermore, the numerical value of σ must be ≥ 0.601 (corresponding to $\alpha \leq 0.8325$), otherwise, the message " $\alpha^* * 2$ is out of range" will be outputted. The reason for this restriction on σ is given in Appendix C.

In Table 5 we list the values that should be used for certain TIKIRK input parameters whenever IKIRKP is employed.

Table 5. Values Used for Certain TIKIRK Input Parameters Whenever IKIRKP is Employed.

MODE	Intensity Function Wanted	MP	NP	X1	X2	RHOP2
1	$I(X, 0, t)$	1	*	*	*	-
	$I(0, \rho', t)$	*	1	X_0	-	*
MODE	Intensity Function Wanted	MP	NP	UMIN	UMAX	VMAX
2	$I'(u, 0, t)$	1	*	*	*	-
	$I'(0, v, t)$	*	1	<u>0</u>	-	*

*Means that operator should insert whatever value he desires.

-Means that that particular parameter is of no consequence.

The commands listed in the attachments apply equally as well to the IKIRKP option. The only responses which the operator will change will be those special values of the input parameters discussed above.

9.7 The IKIRK1 Option and an Alternate TIKIRK Package

The IKIRK1 option #3 is not contained in the TIKIRK program as described in Sections 9.1 through 9.6. However, a second TIKIRK program package has been assembled which not only offers option #3 but incorporates #1 and #2 as well. Thus, it can be substituted for the original program, if desired. This package consists essentially of four parts, each one to be stored in the computer under its own PFN. The first part contains a main program, also called TIKIRK, plus those

function subprograms and subroutines making up the "core package" listed in Section 9.3 (viz, PHI, J0, J1, RTAPE3, ALI, ATSE, GETDATA, SSWTCH, RJUST and PRT). This "core package" will be utilized by the last three parts. The main program, called TIKIRK, is a slightly modified form of the main program TIKIRK first introduced in Section 8.3. As before, its principal role is to call the other subroutines and subprograms into execution. Since this first part would play a major role in computing the diffraction pattern of the transmitted beam and call upon the various options, it too has been given the PFN of TIBX by us, whenever it has been used.

The next three parts pertain to options #3, #1, and #2 in that order and we have assigned them their own particular PFN. Each one of these parts includes a major function subroutine which is also given the name IKIRK. The modified TIKIRK main program mentioned above, summons a given option by putting in a call to IKIRK. Which IKIRK (and its concomitant subroutines) gets executed depends upon which one was attached just previous to the call. (It should be noted that in this alternate TIKIRK package, the control parameter I2 no longer plays any role in determining which option will be utilized.) This procedure is demonstrated in Attachment 5, which lists typical control commands for running this new TIKIRK package under either Intercom or Batch mode of operation:

The second part, as noted above, pertains to option #3 (IKIRK1). Besides its major function subroutine IKIRK, it contains the following three subroutines:

(1) FREAL1 - computes the products of the functions $f_w f_x$ and $f_w f_y$ (see Eqs. 23-27, Volume I). It has 4 entry points since actually 4 functions have to be integrated.

(2) DCADRE - an integration subroutine from the IMSL set of routines. It requires the external function subroutine FREAL1 as one of the arguments.

(3) UERTST - required by DCADRE to output error messages.

We have stored this second part under the PFN of IK1BX.

The third part pertains to option #1, which was also referred to as IKIRK in Sections 9.2-9.6. Besides its major function subroutine, called IKIRK, it contains the two subroutines DQG24A and DQG24B, mentioned in Section 9.3. To this part, we have given the PFN of IKBX.

The fourth part contains option #2 (IKIRKP). Besides its major function subroutine, called IKIRK, it utilizes the four subroutines COMPUTE, JI, BESJF and BESJ, previously mentioned in Section 9.3. We have given the PFN of IKPBX to this part.

The Fortran listings for the modified TIKIRK program — the three major function subroutines which are each called IKIRK and which lead into each of the three options, as well as the subroutines FREAL1, DCADRE and UERTST — are given in Appendix D. All of the other subprograms and subroutines mentioned above are the same as those listed in Appendix B.

It has already been noted that option #3 (IKIRK1) is exceedingly slow. However, it may be possible to speed it up by increasing the absolute and relative errors which are presently set at 10^{-3} and 10^{-6} , respectively. In addition, the maximum value of the error parameter IER in DCADRE, as well as the maximum estimated bound on the absolute error in integration, is always printed out.

Whenever the results of IKIRK1 disagree with the results of IKIRK (option #1), those of the former should be preferred because of its greater inherent accuracy.

10. DISPLAY PROGRAM

10.1 Introductory Remarks

Program DISPLAY is a general purpose program for displaying two-dimensional arrays of numbers which, intuitively at least, can be thought of as a surface which has been sampled over an evenly spaced grid. The array size is essentially limited (by computer storage capabilities) to a maximum of 100 by 100; there is no minimum size other than the practical one that it does not make good sense to use a program such as this to display a single point. However, it may make sense to use the program to display one-dimensional arrays; for example, an array of size 1 by n. As will be explained in detail later, three types of display are offered by the program: contour map, perspective view, and multiple cross sections (parallel to two rectangular coordinate axes only). Moreover, the program is designed to display several such arrays at one RUN with the idea in mind that these arrays represent the evolution in time (or with some other parameter) of a function of two variables.

In addition to merely plotting the arrays in one or more of the above mentioned forms, this program labels all plots (provided the labeling information is furnished) and lists pertinent experimental parameters (if desired). Most of this labeling information is supplied in one or more data arrays, the structure of which has been described in DATAIN (see Section 8.8). The rest of the labeling information is provided in the records which contain the array rows.

Program control is afforded by a set of input "commands" which are supplied by input cards. The program interprets each command, obeys each command, and terminates when all commands have been followed (or when time runs out).

Before the program is used, it must be somewhat "tailored to fit." This is accomplished through the use of a fixed number of input data which must be supplied in entirety. Examples of such data are: plot id, maximum plot size, array of indices for obtaining labeling information, etc. A complete list of such data is provided in Section 10.2.

The program allows for selection of the starting "time" and its increment assuming that the surface to be displayed is a function of "time." ("Time" may be any suitable parameter.) A surface cross-section may be displayed as a function of time on a single coordinate frame.

10.2 General Instructions

The surfaces to be displayed are assumed to be stored on file TAPE3 in unformatted records where each logical record consists of one "row" of the mp x np array of floating point numbers representing the surface. In addition, each record contains the information: row number (I), total number of rows (NP), y-value to be associated with that row (Y), parameter value (if any) to be associated with (T), number of samples in the row (MP), x-value to be associated with the first element of the row (XMIN), x-value to be associated with the last element of the row (XMAX). Specifically, each record must have the form:

I, NP, Y, T, MP, XMIN, XMAX, (F(I, J; T), J=1, MP)

where $F(\cdot, \cdot; T)$ is the function to be displayed. Thus, for each value of the parameter T, NP logical records represent one "surface." Several such "surfaces" corresponding to several values of T may be stored on file TAPE3 and exhibited by DISPLAY.

In addition to the above mentioned "surfaces," file TAPE3 may contain any number (including 0) of "information" records, the contents of which include information (such as experimental parameters) which should be printed on each plot and plot titles. Each such information record must be an array (which will be called here DATAIN) of the form DATAIN(100, 3). Thus, each datum is represented by three parts called (in the order in which they appear) VALUE, NAME, and FORMAT. DATAIN is stored in unformatted form. VALUE is the numerical or character string value of the datum, NAME is a character string of up to ten characters which may be used to identify the datum, while FORMAT is a format code number (-1, 0 or 1) which specifies whether the datum value is to be interpreted as a character string (-1), integer (0), or floating point number (1). (See GETDATA, Section 8.8.4.)

These DATAIN records (if any) must be the first records on file TAPE3. Titles (if any) must appear only in the last DATAIN record.

10.3 Data Cards

The following data cards must be inputted to tailor the program for the user's particular application. The number in parenthesis in front of each datum name is the card column at which to start the datum. The number in parenthesis following the datum is the default value of the datum. If the default value is to be used, leave the corresponding card field blank.

Data Card #1

(1)	XMAX	(100.)	Maximum plot length in inches.
(11)	YMAX	(12.)	Maximum plot width in inches.
(21)	PPI	(10.)	Number of points/inch for contours.
(31)	TICU	(.5)	Number of inches between tic-marks for user defined x-y plots.
(41)	XLEN	(10.)	x-y plot coordinate frame x-size.
(51)	YLEN	(8.)	x-y plot coordinate frame y-size.
(61)	SCALEX	(1.)	x-y plot x-scale, that is, no. of x-units/tic-mark.
(71)	SCALEY	(1.)	x-y plot y-scale, that is, no. of y-units/tic-mark.

Data Card #2

(1)	XMIN	(0.)	{	The minimum x-value and y-value to be plotted for user-defined x-y coordinate frame x-y plots.
(11)	YMIN	(0.)		
(21)	NAME	(GIANINO)		User's name to appear on plot.
(31)	PROB. NO.	(2347)		4-digit user's problem number.

Data Card #3

This card provides information for the two-dimensional array INDEX, which is the index of locations for labeling information assumed to be contained in the last DATAIN on the file containing the surfaces to be plotted. INDEX consists of pairs of numbers wherein the first number is the starting location of the label and the second number is the length of the label. If there is no such data, then this card may be left blank and the labeling will not be done. If the letter D is placed in column 1 of this card, the default values shown below are used. In addition to the values of INDEX, the field starting in column 41 should contain the number of DATAIN arrays on TAPE3.

(1)	INDEX(1, 1)	(1)	Surface title.
(6)	INDEX(1, 2)	(30)	Surface title length (characters).
(11)	INDEX(2, 1)	(4)	Parameter title.
(16)	INDEX(2, 2)	(30)	Parameter title length.
(21)	INDEX(3, 1)	(7)	x-title.
(26)	INDEX(3, 2)	(30)	x-title length.
(31)	INDEX(4, 1)	(10)	y-title.
(36)	INDEX(4, 2)	(30)	y-title length.
(41)	NDA	(2)	Number of DATAIN arrays on TAPE3. The INDEX information is taken from the last DATAIN array.

We employ the following numerical values on data card #3 for displaying the intensity (using TAPE7) and the temperature (using TAPE8):

for TAPE7:	27	29	32	14	37	33	42	32	
for TAPE8:	72	20	67	13	83	24	88	31	1

Data Cards #4A, 4B, etc.

These cards contain the sequence numbers of data in DATAIN which are to be listed at the beginning of each run of DISPLAY. The sequence numbers pertaining to the TEMP5 parameters have been listed in Table 2, while those pertaining to the TIKIRK parameters have been listed in Table 4. There must be one card for each DATAIN array (see the last entry number in data card #3 above). For example, in our particular data card #3 above for the TAPE7 case, the default value of 2 is implied as the NDA entry, signifying that 2 cards must be used. The first card contains the sequence numbers of the TEMP5 parameters, while the second contains the sequence numbers of the TIKIRK parameters. The objective is to list both sets of parameters on the plots. In data card #3 above for the TAPE8 case, the NDA value of 1 was employed, indicating that only one card is to be used, viz, that containing the sequence numbers of the TEMP5 parameters which are to be listed on the plots.

The sequence numbers start in columns 1, 3, 5, 7, . . . for a total of up to 40 indices per card. The default is a blank card. When the default is used, no DATAIN data is to be listed.

The above cards comprise the mandatory data cards. The remaining cards are the "command" cards which indicate what kinds of plots are wanted.

10.4 Command Cards

As stated previously, the DISPLAY program has the capability of 3 different types of plots, viz, multiple x-y, perspective view and contour map. Consequently, there is a command to control each type and they are indicated by the keywords PLOT, PERSPECTIVE and CONTOUR, respectively. The abbreviations PL, P and C, respectively, may also be used. These keywords are modified by certain parameters p_i . We now enumerate all of the modifying parameters of these command keywords and their meanings:

- (1) Command: PLOT (p_1 , p_2 , p_3 , p_4 , p_5 , p_6)

The parameters p_1 , p_2 , p_4 and p_5 are integers. In the process of creating a TAPE7 or TAPE8 file, up to ten times had to be chosen at each of which a temperature or an intensity distribution was calculated. These ten times were designated by the datum names T1, T2, ..., T10 (see Table 4). The first two parameters in the above command allow for control in selecting which times are to be chosen in the DISPLAY program. For example, the above command directs that the appropriate data corresponding to every p_1 -th time value is to be displayed, starting with the p_2 -th value (that is, T_{p_2}).

Recall that both the temperature and the intensity can be plotted either as a function of radial distance or of axial distance. The parameter p_3 can account for either of these two types of plots by taking on the code symbol X when it is a radial distance plot that is desired, or, the code symbol Y, when the axial distance plot is wanted.

For a temperature calculation, the TEMP5 program sets up a net of 82 temperature points in the radial direction (r), extending from the inner to the outer window radius, and 22 temperature points in the axial direction (z), extending from the entrance to the exit faces. Consequently, there are 22 cross-sectional surfaces of T versus r (that is, 22 type-X plots) and 82 cross-sectional surfaces of T versus z (that is, 82 type-Y plots). Thus, depending on the symbol given by p_3 , the above PLOT command directs that on one coordinate frame every p_4 -th T-versus-distance surface is to be plotted starting with the p_5 -th surface.

On the other hand, for intensity calculations, the TIKIRK program establishes a net in the far field consisting of NP intensity points along the axial line (X), extending from some minimum to some maximum axial distance, and MP intensity points in the radial direction (ρ'), starting from the axial line and going perpendicular to it. Consequently, there are NP cross-sectional surfaces of I versus r (that is, NP type-X plots) and MP cross-sectional surfaces of I versus z (that is, MP type-Y plots). Again, depending on the symbol given by p_3 , the PLOT

command directs that every p_4 -th I-versus-distance surface is to be plotted on one coordinate frame starting with the p_5 -th surface.*

The parameter p_6 can take on any one of the following code symbols: NA, NAS, NE, NES, DN or DNS. These symbols will be explained in Section 10.4, paragraph (4).

The default values for the above 6 parameters are: $p_1 = p_2 = p_4 = p_5 = 1$, $p_3 = X$ and $p_6 = NA$.

(2) Command: PERSPECTIVE (p_1, p_2, p_3, p_4)

The parameters p_1 and p_2 are the same as in the PLOT command above. The numerical value p_3 is the magnitude of the view angle in degrees, measured from the plane of the window's exit face. Parameter p_4 can take on the code symbols NA or NE only.

The default values are: $p_1 = p_2 = 1$, $p_3 = 45$ and $p_4 = NA$.

(3) Command: CONTOUR (p_1, p_2, p_3, p_4)

The parameters p_1 and p_2 are the same as in the PLOT command above. The integer p_3 refers to the number of contour levels of constant temperature, or intensity, that are to be plotted, up to a maximum of 50. Parameter p_4 can take on any one of the code symbols NA, NE or DN.

The default values are: $p_1 = p_2 = 1$, $p_3 = 10$ and $p_4 = NA$.

Note that in the above three commands, parameters are separated by commas. Missing parameters are indicated by commas (with no blank spaces between commas), or by a right parenthesis. If the keyword only appears, then default parameters are assumed.

(4) Meaning of Code Symbols NA, NAS, NE, NES, DN and DNS

The letter N means that the functions to be displayed are first normalized before being plotted, that is, the transformation

$$z \rightarrow \frac{c}{(z_{max} - z_{min})} (z - z_{min})$$

(where z refers to the value of the ordinate) is made, where the value of c = 100 for CONTOUR plots; for PERSPECTIVE plots, it depends on the size of the array to be displayed. The latter N has a slightly different connotation for X-Y plots. Here, it means that the array is scaled such that it will fit in a coordinate frame with nice scale values. The second letter A or E indicates whether the normalization is over all (A) surfaces or whether each (E) surface is normalized separately, that is, the z_{max} , z_{min} are searched for over all arrays or over each array individually. The letters DN mean don't normalize, that is, do not do the above

*There is a circumstance in which the above meaning for p_4 does not apply. See Section 10.4, paragraph (4).

transformation. Note that for PERSPECTIVE displays normalization always occurs. Therefore, DN should never be used. This is done mainly to force the plot to remain within the plot paper boundaries. Again, for X-Y plots the connotation is slightly different, in that in this case the user must provide plot scale values.

The letter S indicates that there will be superimposed on a single coordinate frame many time curves (as chosen by p_1 and p_2) for a given cross-section, rather than having several cross-sections appear on a single frame for one particular time. Since the time variable can have as many as 10 values, then there can be as many as 10 time surfaces, that is, curves, superimposed on one frame. If it is desired to have one coordinate frame for each value of time that has been utilized, then the S should be omitted. This situation definitely pertains to CONTOUR and PERSPECTIVE plots.

When NA or NAS is used, the values assigned to SCALEX, SCALEY on data card #1 and XMIN, YMIN on data card #2 are ignored, so then the computer selects values which are more appropriate for the ranges of ordinate and abscissa involved. When NE or NES is used, the operator must select his own values for these data.

For X-Y plots, it is recommended that either NA or NAS be used. If NE or NES is employed instead, the operator should beware of erroneous coordinate scaling by ensuring that the values for any subsequent maxima and minima do not exceed those of the initial maximum and minimum. If the S is used in these plots, then parameter p_4 has no effect since several surfaces corresponding to several time values at one cross-section are to be plotted, rather than several cross-sections for one time value.

If no command card is included, then the default command of PERSPECTIVE is assumed. Several commands, one per card, may be given for any single run of the program. For example, a perspective display might be followed by a contour display or several perspective displays from several view angles might be called for by a sequence of PERSPECTIVE commands.

Typical detailed commands used for running the DISPLAY program in the Batch mode only are listed in Attachment 6. We do not run this program in the Intercom mode because usually there is not sufficient space allocated on Intercom to allow the program to run to completion.

10.5 Examples of the Use of the Three Different Plotting Commands

In Section 6 of Volume I, we presented many examples of the three different kinds of plots that program DISPLAY was capable of generating, listing in the figure captions the plot commands which controlled the actual plotting of these

curves. We are now in a position to understand and to analyze how these commands control the graphing.

For example, in Figure 3 the command is PLOT (1, 1, Y, 100, 1, NAS). The keyword PLOT indicates that a multiple X-Y plot is involved. The first two parameters (1, 1) mean that every time value available is to be utilized, starting with time value #1 (that is, T1). In this example, there were 9 time curves used (T1 through T9), which are shown on the right hand side of the figure. Whether the curves drawn will represent temperature - or intensity - versus distance depends on whether the permanent file attached previously to the PLOT command was a TAPE8 - or TAPE7 - type file, respectively. For this particular case, it was a TAPE8 file. The third parameter (Y) signifies that the abscissa is the axial distance through the window. The fourth and fifth parameters (100, 1) signify that every 100th T - versus - z surface is to be plotted, starting with the first (that is, starting with the surface existing at zero radial distance, which is through the center of the window). Since there are only 82 T - versus - z surfaces, then setting $p_4 = 100$ can be seen as a ploy for selecting only the first surface ($p_5 = 1$) to the exclusion of all others. In other words, the selection of any value of p_4 greater than 82 would have ensured the same result. The sixth parameter (NAS) indicates that the normalization is to occur over all surfaces and that all of the (9) time curves are to be superimposed on one coordinate frame.

In Figures 4 and 5 the same kind of information was desired except that the T - versus - z profiles were to occur at constant radial distances of 15 and 30 cm, respectively. Since these distances represent ~50 percent and ~100 percent of the radial distance up the window, the parameter p_5 was chosen to be equal to 41 and 81, respectively. (Actually, because of the way the 82 radial positions were chosen, p_5 -values of 1, 41 and 81 represent distances of 0.6 percent, 49.4 percent and 99.4 percent up the radial axis, respectively.)

In Figure 6 we wanted to superimpose plots of T - versus - z at the above 3 radial positions at the fixed time of 5 sec, which is the 8th time value. The p_1, p_2 pair of 4, 8 signifies that every 4th time value is to be plotted, starting with T8. As above, this is a ploy to select only T8 and to exclude the others, since there are only 9 times available. Any $p_1 > 2$ would have produced the same result. The p_4, p_5 pair of 40, 1 means that every 40th surface is to be plotted, starting with surface #1. Thus, surfaces #1, 41 and 81 are plotted. Because we want these 3 surfaces, properly normalized, to be superimposed on one coordinate frame at the one fixed time, we leave off the letter S in the parameter p_6 .

Temperature is plotted against radial distance for the same model problem in Figure 7 (hence, $p_3 = X$). Here, we wanted to plot all 21 T - versus - r surfaces (therefore, $p_4 = p_5 = 1$) at 1 and 5 sec. (The reason for there being only 21 rather

than 22 surfaces is due to the way we chose the points; the 22nd point falls outside of the window.) Thus, we choose p_1 and p_2 to be 3 and 5, respectively, meaning that every 3rd time is selected, starting with $T_5 (=1 \text{ sec})$. As before, dropping the letter S in parameter p_6 ensures one coordinate frame for each time chosen.

Figures 8 and 9 are examples of T - versus - r temperature plots at approximately $1/4$ and $3/4$ of the way through the window (hence, $p_5 = 6$ and 16), respectively. Note that setting $p_1 = p_2 = 1$ assures that all times are accounted for and are superimposed because of the S in p_6 . Letting p_4 be greater than 22 (here, 100) assures that only that one particular surface will be plotted.

Figures 10 and 11 pertain to the annular-shaped window. Setting $p_5 = 11$ and 21 results in plots for T - versus - r surfaces through the middle and at the exit face of the window, respectively.

Figures 12-14 show multiple X-Y plots for intensity. In Figure 12 we wanted every time included (hence, $p_1 = p_2 = 1$) of T - versus - axial distance plots (hence, $p_3 = Y$) along the axis ($p_5 = 1$), with no other radial distances included ($p_4 = 100$); and all of the time curves are to be superimposed (hence, S in p_6). In this particular example, we let $MP = 100$. Thus, any p_4 - value ≥ 100 would have ensured that only those surfaces along the axis would be used.

The axial range is covered by NP points; in our particular example, $NP = 61$. In Figure 13 we wanted to have superimposed time plots of I - versus - ρ' (hence, $p_3 = X$) at the center of the axial range only (hence, $p_4 = 100$, $p_5 = 31$). At a time of 3 sec (that is, $p_2 = 7$), the Gaussian focal point occurs at a distance of 830 m along the axis (corresponding to $p_5 = 34$). Figure 14 displays the I - versus - ρ' graph for this time only.

The plot command for the PERSPECTIVE graphs of Figures 15 and 16 use the default values. Even though a 3D plot was drawn for all 9 times, only a few representative cases are presented here.

For contour plots we wanted the time values of 2 and 8 sec only. Hence, $p_1 = 3$ and $p_2 = 6$ in Figures 17 and 18. Twenty contour lines are shown (thus, $p_3 = 20$). Since we wanted each one of these contours to be labeled with its dimensioned temperature value, rather than a normalized value, we chose the code symbol DN for p_4 .

In summary, we can say that program DISPLAY is used mainly to provide a "readable" output of functions of two variables. The PERSPECTIVE plot furnishes a very good general "view" of the function in question. CONTOUR also provides a good view as well as quantitative knowledge of the function values. PLOT (either X-cross-sections or Y-cross-sections) supplies the most quantitative output but usually the least satisfactory overall "view" of the function. It should be pointed out that PLOT can be used for functions of one variable.

10.6 Principal Functions and Subroutines

The various operations associated with the DISPLAY program are carried out by the following subprograms, subroutines and functions:

- (1) DISPLAY - the main program which calls the other subroutines and functions into execution.

All of the following are subroutines:

- (2) PLOTT1 - draws and titles coordinate frame. It also does the scaling, if it isn't supplied by the user.
- (3) PARMPLT - prints out parameters at the beginning of each plotting run.
- (4) FILL - selects data from DATAIN and places it in a 2D array which, in turn, is passed to PARMPLT for printing.
- (5) CFRAIME - draws and labels the coordinate frame for contour and perspective plots.
- (6) INTERP - converts user commands and command parameters to subroutine control arguments: It also calls subroutine NUMB to decode parameters.
- (7) NUMB - used by INTERP to convert display code numbers in the commands to the proper internal representation of numbers in the computer.
- (8) ARROW - draws the arrow used above the rectangular coordinate frame in perspective plots.
- (9) APLACE - locates arrow-head for perspective view angle.
- (10) RD1 - reads TAPE3 and fills up appropriate arrays to be plotted. Finds maxima and minima of the surfaces to be plotted, if necessary.
- (11) CLEV - returns various equispaced contour levels.
- (12) SKIP - skips over a designated number of records (that is, "surfaces") while reading TAPE3.
- (13) FACE - a system library program which draws the PERSPECTIVE plots. It also uses the library subroutines HIDE, DRAW, SORT and PARFIT.
- (14) CONTOR - a system library program which draws the CONTOUR plots. It also calls the library subroutines NEIBOR and FOUR as well as the Calcomp plot subroutines.
- (15) RJUST - right adjusts all numerical input data. Its Fortran listing is given in Appendix A. 9.
- (16) SYMBL - converts a floating point number using a G10.3 format to a display code.

The complete Fortran listings for each of the above programs, subroutines and functions are given in Appendix E.

10.7 Algorithms

10.7.1 MULTIPLE X-Y DISPLAYS

The PLOT display graphs either $f(\cdot, y_i)$ ($p_3 = X$) or $f(x_i, \cdot)$ ($p_3 = Y$) for selected values of y_i or x_i determined by command parameters p_4 and p_5 . Specifically:

$$i = p_5 + (k - 1) \cdot p_4 \quad (k = 1, \dots, \dots) .$$

Subroutine PLOTT1 is called after each "surface" array has been filled by subroutine RD1. One of two types of coordinate frames are then drawn by PLOTT1 depending on command parameter p_6 . If $p_6 = NA$ or NE , the scaling is done by the Calcomp subroutine SCALE and the coordinate axes are drawn by Calcomp subroutine AXIS. If $p_6 = DN$, then the user-provided scale is used and the coordinate frame is drawn by a set of statements within PLOTT1.

After the coordinate frame has been drawn, the individual surface "cross-sections" represented by $f(\cdot, y_i)$ or $f(x_i, \cdot)$ are plotted as continuous curves. Each curve is labeled with a symbol and symbol table.

10.7.2 PERSPECTIVE DISPLAY

For perspective displays the surface is always normalized in such a way that the display will approximately fill the same plot area regardless of the size of the surface array. The view elevation angle is fixed at approximately 45 degrees while the view azimuthal angle can be any value (given by the parameter p_3 of the PERSPECTIVE command). To produce a better display, the surface is always bordered by zeroes.

The complete perspective display is produced by calls from the main program to four subroutines (which may, in turn, call other subroutines): APLACE, FACE, CFRAME, and ARROW.

After establishing some display constants, a call is made to APLACE which returns the point at which to place the head of the view direction arrow. Next, a surface of constant height is produced and a call made to FACE with a "switch" positioned such that FACE merely returns values of XMIN, YMIN, DX, DY which will be used on subsequent calls to FACE. The surface is next normalized and a "display frame" is plotted. Because of the difficulty of drawing a coordinate frame for a perspective display, a coordinate frame quite similar to that used for the contour display is drawn adjacent to each perspective display. The only difference is that an angle of view arrow is drawn on the frame. This frame, then, is

produced by calls to CFRAME (see Section 10.7.3 on contour display) followed by a call to ARROW which plots an arrow at the point found by APLACE. Finally, FACE is called to produce the perspective display.

10.7.3 CONTOUR DISPLAY

The contour display is produced by calls to three subroutines: CLEV, CFRAME, and CONTOR. Subroutine CLEV returns p_3 contour levels in array ZLEVS, evenly spaced between the surface maximum and minimum (but exclusive of the surface minimum). The surface may or may not be normalized according to parameter p_4 .

After CLEV has been called, the contour "frame" is drawn by a call to subroutine CFRAME. An example of the frame produced by CFRAME is shown below (small letters indicate numerical or character-string values which are inserted):

surface title
ALL FUNCTION VALUES HAVE
BEEN SCALED ACCORDING TO -

$$z \Rightarrow \frac{c \cdot (Z - ZMIN)}{(ZMAX - ZMIN)}$$

WHERE ZMAX = zmax
ZMIN = zmin
ARE THE MAX. AND MIN.
VALUES OVER ALL SURFACES
or (VALUES OF THE SURFACE)
parameter = value

The contour map is then drawn by a call to CONTOR. Each contour level line is identified by a unique (mod 13) symbol which is printed next to the contour map along with the contour level value which the symbol represents.

10.8 Batch and Intercom Modes

Attachment 6 gives a typical set of commands for running the DISPLAY program under the Batch mode only. The Intercom mode does not have sufficient capacity to handle most plotting jobs, since approximately 142,000 octal words are required in the central memory to run the program (including the plot software). The program will run under Intercom if the arrays in unlabeled common are changed from (102, 102) to (22, 22).

Running time of the program is determined by the size of the array to be displayed, the number of commands and the command parameters. As an example,

a 100 by 100 array was displayed with CONTOUR (20 levels), PLOT (10 cross-sections) and PERSPECTIVE in a total CP time of 82.8 sec.

10.9 Other Features

Various quantities which might be useful for debugging purposes are outputted on file TAPE6. These quantities are:

- 1) XMAX, YMAX, PPI, TICU
- 2) XLEN, YLEN, SCALEX, SCALEY
- 3) XMIN, YMIN
- 4) INDEX (8 integers)
- 5) NDA (if not 0)
- 6) IND (four lines of integers representing the locations in DATAIN of data to be plotted).
- 7) 4) and 5) repeated for each DATAIN.
- 8) Command parameters. (Note that the command itself can be inferred from the form of the parameters.)
- 9) NP, MP
- 10) ZMAX, ZMIN, TIM, ZMIN
- 11) XMAX, YMIN, YMAX, FLAG1 (Note: FLAG1 is a logical variable which is "FALSE" if an end-of-file has been reached on file TAPE3.)
- 12) 9) and 10) possibly repeated.
- 13) XMINF, YMINF, DX, DY (Only for perspective display; these are scale parameters.)

In addition to the output which comes directly from program DISPLAY, the subroutine CONTOUR (used in contour display) and FACE (used in perspective display) output various quantities (see subroutine listings).

10.10 Program Files

In addition to OUTPUT, which is used only by the operating system to output messages, DISPLAY uses files TAPE4, TAPE6 and TAPE3.

TAPE3: TAPE3 is the main input file containing the surfaces to be displayed as well as the information records containing titles, etc. All records are unformatted. The file structure is as follows:

record 1: datain-1 (100, 3)
record 2: datain-2 (100, 3)
.
.
These records may be absent (nda=0)
.
.
record nda: datain-nda (100, 3)
.
.
.
record nda+1 row 1 of surface 1
.
.
.
record nda+np row np of surface 1
row 1 of surface 2
.
.
.
row np of surface 2
.
.
last record row np of surface N

Each "row" of the surface has a record of the form given in the first paragraph of Section 10.2.

TAPE4: TAPE4 is the "card" input file. It uses formatted data as described in the first paragraph of Section 10.3.

TAPE6: TAPE6 is the formatted output file for messages and debug quantities. See Section 10.8 for a partial listing of TAPE6 records.

11. OTHER CAPABILITIES

The computer programs described in this report either have been extended, or are capable of being extended, to various other aspects of the window problem. For example, a program has been written and successfully implemented in fitting the theoretical temperature distribution produced by program TEMP5 to various experimentally measured temperature distributions. More specifically, the temperature at one or more points on the window's surfaces are measured as a function

of time, as a source is turned on, then off. The theoretical temperature rise and fall is made to approximate the experimental values by a judicious choice of various parameters (such as absorption coefficient, β , and the theoretical boundary conditions, as given by the h_i and g_i) which describe the thermal properties of the window material. The details of this procedure are contained in Technical Memorandum No. 16 by T.B. Barrett, Parke Mathematical Labs. (Oct. 1973).

Another phenomenon which could definitely affect the diffraction pattern in the far field would be multiple internal reflections of the laser beam within the window.¹⁵ Analysis shows that this condition can be handled effectively if each exponential term in Eqs. (25), (26) and (27) is replaced according to the prescription:

$$\exp(i k \Phi^\gamma) \rightarrow t_1 t_2 \exp\{ik \Phi^\gamma\} / [1 - r_1 r_2 \exp\{2ik(\Phi^\gamma + \Phi')\}] \quad (87)$$

in which Φ^γ is still determined by Eq. (18) and the extra phase factor Φ' is given by:

$$\Phi'(\rho) = nL + \Delta L_b(\rho) \quad , \quad (88)$$

where ΔL_b is the amount by which the window bulges when heated by the beam. The t 's and r 's are amplitude transmission and reflection coefficients, respectively. The subscript 1 refers to the window's entrance face, and 2 to its exit face. They are given by Weil:⁸

$$t_1 = 2/(n+1)$$

$$t_2 = 2n/(n+1) \quad , \quad (89)$$

$$r_1 = r_2 = -(n-1)/(n+1) \quad .$$

Another capability inherent in the program is allowing an axial (that is, z) dependency in the volume heating source term Q . There are two alternate ways in which this could be effected:

(1) Replace subroutine GAUSS (refer to Appendix A.5) by another, which is also to be called GAUSS. This new subroutine is to have the same arguments as before (see card #7120 in Appendix A.5). However, now the Q -array will contain

15. Bendow, B., Gianino, P.D., Hordvik, A., and Skolnik, L.H. (1973) Optics Commun. 7:219; and Skolnik, L.H., Bendow, B., Gianino, P.D., and Cross, E.F. (1974) AFCRL-TR-74-0085 (III), p. 967.

the appropriate z-dependence. The variable names in the argument are defined in the glossary in Table 3.

(2) If the Batch mode is to be employed, an alternate procedure would be to insert the following data cards in the GETDATA stack. Referring to Attachment 1B, use

IQ	2
ICARD	4

on line 34, and, after the blank card on line 35 insert the desired Q-array using format 7F10.3. At present, Q is dimensioned (82, 22).

Other possible extensions of the computer program include:

- (1) Temperature dependence of some of the material parameters, such as refractive index n, thermal conductivity K and thermal lensing parameters S_i^γ .
- (2) Multiple layers, or coatings, on the window to eliminate reflections and/or to compensate the thermal lensing.¹⁶
- (3) Time dependence in the volume source term Q.

Trying to account for an angular (that is, θ) asymmetry in the beam's cross-section would not be a feasible extension, for it would necessitate a complete rewriting of the program, expanding it from a 2-dimensional to a 3-dimensional treatment.

16. Bendow, B., and Gianino, P.D. (1975) *Appl. Optics* 14:277; and Bendow, B., Gianino, P.D., Flannery, M., and Marburger, J. (1975) Proc. of the Fourth Annual Conf. on Infrared Laser Window Materials, C.R. Andrews and C.L. Strecker (Editors), Advanced Research Project Agcy., Arlington, Virginia, p. 299.

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Attachment 1

Commands to Run TEMP5 and TIKIRK

Here, the goal is to initiate and run a specified TEMP5 and a TIKIRK calculation, then print out and catalog the results on permanent file (PF). Before beginning this job, one should have previously stored in the computer the following two PF's: TEBX (the PFN for the TEMP5 program), and, TIBX (the PFN for the TIKIRK program described in Sections 6.1 - 6.6). A third ancillary program, T3D, whose use is optional, is available to be added to the previous two. Given the PFN of T3BX, it prints out functions F1 and F2 (see Eqs. (16) and (17), Volume I). The Fortran listing for program T3D is given in Appendix F. Incidentally, the third letter (B) in each of the above PFN's means that the PF is in binary form.

A. Intercom Commands

The following is a typical set of Intercom commands:

<u>Line No.</u>	<u>Computer types out..</u>	<u>Operator Response</u>	<u>Comments</u>
1	COMMAND-	ETL(450)	Extends time length to 450 octal sec.
2	COMMAND-	CONNECT(TAPE4,TAPE5)	

<u>Line No.</u>	<u>Computer types out..</u>	<u>Operator Response</u>	<u>Comments</u>
..... Start of TEMP5 calculation.....			
3	COMMAND-	A TTACH(TEB, TEBX, ID=GIANINO)	TEB is LFN for TEBX.
4	COMMAND-	TEB	
5	READ DATA FILE-3? N		N=no (because you want to create a new TAPE3)
6	DEFAULTS LISTED? N		Customary answer.
7	NAME-VALUE MODE? Y		Y=yes .
8	NAME VALUE....	BETA .003 17 1 etc. - - - - - - -	(i) Enter the new TEMP5 variables here. See Table 2 Volume II. (ii) The name of the vari- able starts under N in NAME; its numeri- cal value under V in VALUE.
9	DATA INPUT COM- PLETE WORK OF DATINIT COMPLETE... WORK OF CYLTMP COMPLETE... END OF RUN EXIT ----CP SECS EXE- CUTION... TEMP5 Calculation has been completed.....		
10	COMMAND	CONNECT(OUTFUT)	Lines 10-13 cause F1 and F2 to be printed out at remote terminal facility (AU). They may be omitted, if desired.
11	COMMAND-	A TTACH(T3B, T3BX, ID=GIANINO)	T3B is LFN for T3BX.
12	COMMAND-	T3B,,A	A is merely a surrogate name .
	END T3D .. CP SECS EXECUTION..		
13	COMMAND-	ROUTE,A,ST=RMT, FID=GIAAU,DC=PR.	
14	COMMAND-	REQUEST(PAT,*PF)	Lines 14-17 create a new TAPE3-type PF. We arbitrarily give it the PFN of T3NX. PAT is merely a LFN.

<u>Line No.</u>	<u>Computer types out..</u>	<u>Operator Response</u>	<u>Comments</u>
15	COMMAND-	REWIND(TAPE3)	
16	COMMAND-	COPY(TAPE3, PAT)	
17	COMMAND-	CATALOG(PAT, T3NX, ID=GIANINO, RP=999)	
18	COMMAND-	ROUTE, TAPE6, ST=RMT, FID=GIAAU, DC=PR.	Causes the information on TAPE6, containing the TEMP5 results, to be printed out at remote terminal facility (AU). Also clears TAPE6.
(ASIDE: If all that is desired is the temperature distribution in the window, this would be a convenient place to stop).			
..... Start of TIKIRK calculation.....			
19	COMMAND-	ATTACH(TIB, TIBX, ID=GIANINO)	TIB is LFN for TIBX.
20	COMMAND-	TIB	
21	READ DATA FILE-3? Y		Because you want to use information from the "new" TAPE3, viz. T3NX.
22	DEFAULTS LISTED?- N		
23	NAME-VALUE MODE?- Y		
24	NAME VALUE... (space, return)		Do not enter any value here; just hit the "space" and "return" keys.
DATA INPUT COMPLETE			
25	READ DATA FILE-7?- N		Answer here is always "no".
26	DEFAULTS LISTED?- N		
27	NAME-VALUE MODE?- Y		
28	NAME VALUE... X1 800 NP 26 - - - -		(i) Enter the new TIKIRK variables here. See Table 4, Volume II. (ii) See Comment (ii) on Line 8.
29	DATA INPUT COMPLETE		TIKIRK calculation has been completed.

<u>Line No.</u>	<u>Computer types out..</u>	<u>Operator Response</u>	<u>Comments</u>
	NEW VALUE OF TAU IS... -		Prints out the 10 values of TAU corresponding to time values T1 through T10. See Eq. (13), Volume I.
30	COMMAND-	ROUTE, TAPE6, ST=RMT, FID=GIAAU, DC=PR.	Routes the TAPE6 information, containing the TIKIRK results, to remote terminal (AU) for printout.
31	COMMAND-	REQUEST(PIT, *PF)	Lines 31-34 create a new TAPE7-type PF. We arbitrarily give it the PFN of TKX. PIT is merely a LFN. This new PF can be used as the input in the DISPLAY program for plotting the intensity.
32	COMMAND-	REWIND(TAPE7)	
33	COMMAND-	COPY(TAPE7, PIT)	
34	COMMAND-	CATALOG(PIT, TKX, ID=GIANINO, RP=999)	

B. Batch Commands

<u>Card No.</u>	<u>Command</u>	<u>Comments</u>
1	Job ID with T=2000, core memory=170K	
2	ATTACH(TEB, TEBX, ID=GIANINO)	
3	REQUEST(TAPE3, *PF)	Assigns TAPE3 to permanent file.
4	TEB(INPUT, OUTPUT)	Loads and executes TEBX.
5	REWIND(TAPE6)	
6	COPY(TAPE6, OUTPUT)	Prints output.
7	CATALOG(TAPE3, T3NX, ID=GIANINO, RP=999)	
8	ATTACH(TIB, TIBX, ID=GIANINO)	
9	REQUEST(TAPE7, *PF)	
10	REWIND(TAPE6)	
11	TIB(INPUT)	
12	REWIND(TAPE6)	
13	COPY(TAPE6, OUTPUT)	

<u>Card No.</u>	<u>Command</u>		<u>Comments</u>
14	CATALOG(TAPE7, TKX, ID=GIANINO, RP=999)		
15	EXIT, S.		All commands after EXIT, S. are executed if and only if TEB terminates abnormally, e.g., exceeds time limit.
16	REWIND(TAPE6)		
17	COPY(TAPE6, OUTPUT)		
18	CATALOG(TAPE3, T3NX, ID=GIANINO, RP=999)		
19	CATALOG(TAPE7, TKX, ID=GIANINO, RP=999)		
20	7/8/9		EOR Card.
21	N		
22	N		
23	Y		
24A	BETA	.003	
B	I7	1	
-	-	-	
-	-	-	
-	-	-	
25	-----		Blank card.
26	7/8/9		EOR card.
27	Y		
28	N		
29	Y		
30	-----		Blank card.
31	N		
32	N		
33	Y		
34A	X1	800	
B	NP	26	
-	-	-	
-	-	-	
-	-	-	
35	-----		Blank card.
36	6/7/8/9		EOF card.

If only temperature distribution in the window is desired, the above series of commands would be reduced to the following:

<u>Card No.</u>	<u>Command</u>
C1	Job ID with T=60, corememory=60K
C2	ATTACH(TEB, TEBX, ID=GIANINO)
C3	REQUEST(TAPE3,*PF)
C4	TEB(INPUT,OUTPUT)
C5	REWIND(TAPE6)
C6	COPY(TAPE6,OUTPUT)
C7	CATALOG(TAPE3, T3NX, ID=GIANINO, RP=999)
C8	EXIT,S.
C9	REWIND(TAPE6)
C10	COPY(TAPE6,OUTPUT)
C11	CATALOG(TAPE3, T3NX, ID=GIANINO, RP=999)
C12	7/8/9
C13	N
C14	N
C15	Y
C16A B - - -	BETA .003 17 1 - - - - - -
C17	(blank card)
C18	6/7/8/9

Attachment 2

Commands to Modify a Temperature Distribution

Assume that a TEMP5 calculation has already been performed and the results cataloged under the PFN of T3NX (cf. lines 14-17 in Attach. 1A). Further, assume that one wants to change only a few of the input variables and then calculate a new temperature distribution. The following commands indicate how the previous results may be utilized.

A. Intercom Commands

<u>Line No.</u>	<u>Computer types out..</u>	<u>Operator Response</u>	<u>Comments</u>
1	COMMAND-	ETL(450)	
2	COMMAND-	CONNECT(TAPE4, TAPE5)	
3	COMMAND-	REWIND(TAPE6)	Clears TAPE6.
4	COMMAND-	REWIND(TAPE7)	Clears TAPE7.
5	COMMAND-	ATTACH(PET, T3NX, ID=GIANINO)	Attaches former TAPE3 with LFN of PET.
6	COMMAND-	COPY(PET, TAPE3)	Copies "former" TAPE3 onto a "new" TAPE3, which is given the LFN of TAPE3. Thus, the original file (T3NX) is still intact and available for future use.

<u>Line No.</u>	<u>Computer types out..</u>	<u>Operator Response</u>	<u>Comments</u>
7	COMMAND-	ATTACH(TEB, TEBX, ID=GIANINO)	
8	COMMAND-	TEB	
9	READ DATA FILE-3?- N		
10	DEFAULTS LISTED?- N		
11	NAME-VALUE MODE?- Y		
12	NAME VALUE.....	SIG .4 PWR 1E7 - - - - - -	Enter those TEMP5 variables which are to be changed. Also, see Comment (ii) on Line 8, Attach. 1A.
13	Same as line 9, et seq., Attach. 1A. However, when one gets to the et equivalent of line 17, Attach. 1A, one should give the new PFN, seq. say, T3QX.		

B. Batch Commands

<u>Card No.</u>	<u>Command</u>	<u>Comments</u>
1	Job ID with T=1000, CM=60K	
2	ATTACH(PET, T3NX, ID=GIANINO)	Attaches old TAPE3.
3	REQUEST(TAPE, *PF)	If new TAPE3 is to be permanent.
4	COPY(PET, TAPE3)	
5	RETURN(PET)	Return if you want to use at a later date. Otherwise, could purge it.
6	ATTACH(TEB, TEBX, ID=GIANINO)	
7	TEB(INPUT, OUTPUT)	
8	CATALOG(TAPE3, T3QX, ID=GIANINO, RP=999)	The new TAPE3 is given the PFN of T3QX.
9	REWIND(TAPE6)	
10	COPY(TAPE6)	
11	7/8/9	EOR card.
12	Y	
13	N	

<u>Card No.</u>	<u>Command</u>			<u>Comments</u>
14	Y			
15A B	SIG PWR	.4 1E7		Enter those TEMP5 variables which are to be changed. Also, see comment on line 34, Attach. 1B.
-	-	-		
-	-	-		
16	(blank card)			
17	6/7/8/9			EOF card.

Attachment 3

Commands to Recalculate TIKIRK, Given TEMP5 Results

There are certain input variables which will affect the computed spatial intensity pattern (and possibly even the dimensioned temperature distribution in the window), but not the normalized temperature distribution. The input parameters which belong to this category are most of the variables found in Table 4 and those in Table 2 which are accompanied by the code letter K in the Useage Code column (Col. # 6).

As in Attach. 2, we assume that a previous TEMP5 calculation is available under the PFN of T3NX. Now, we desire to observe the effects which changes in the above-mentioned variables have on the computed intensity pattern. For each set of changes made, the TIKIRK program must be executed. The following gives a representative series of typical commands necessary to implement this procedure.

A. Intercom Commands

<u>Line No.</u>	<u>Computer types out...</u>	<u>Operator Response</u>	<u>Comments</u>
1-4	Same as in Attach. 2A.		
5	COMMAND-	ATTACH(TAPE3, T3NX, ID=GIANINO)	Attaches PF with LFN of TAPE3.



<u>Line No.</u>	<u>Computer types out...</u>	<u>Operator Response</u>	<u>Comments</u>
6-21	Repeat lines 19 through 34, inclusive, from Attach. 1A. However, on line 24 enter the desired TEMP5 variables, if any, which you want to change and which do not affect the normalized temperature distribution in the window. (Note that TEMP5 parameters are being entered at this stage, even though the TIKIRK program currently has control.)		
	On line 28 enter only those TIKIRK variables whose magnitudes are to be different from the default values.		
	On line 34 select a different PFN for the new TAPE7-type PF just completed.		
 End of TIKIRK calculation.....		
	If you want to change the variables again and repeat the TIKIRK calculation:		
22	COMMAND- TIB		
23	Repeat lines 21 through 34, inclusive, from Attach. 1A, subject to the same comments as noted in line 6 above.		
	Each time the variables are to be changed and the TIKIRK calculation is to be recomputed, repeat lines 22 and 23 above.		

B. Batch Commands

If run as a separate problem, assume that the TEMP5 PF having PFN of T3NX has already been created.

<u>Card No.</u>	<u>Command</u>
1	Job ID with T=2000, CM=170K
2	ATTACH(TIB, TIBX, ID=GIANINO)
3	ATTACH(TAPE3, T3NX, ID=GIANINO)
4	REQUEST(TAPE7, *PF)
5	TIB(INPUT)
6	REWIND(TAPE6)
7	COPY(TAPE6, OUTPUT)
8	CATALOG(TAPE7, TKX, ID=GIANINO)

Plus cards #26-#36, inclusive, of Attach. 1B.

Attachment 4

Commands to Produce a TAPE8 for Temperature Plots

The temperature distribution information contained on the file called TAPE3 is not in the proper format for plotting purposes. Rather, this information must be transferred in the appropriate format to another file, called TAPE8, which is suitable for plotting by the DISPLAY program. This attachment gives all of the commands required to generate and catalog a TAPE8 file, provided that the temperature results are already on a TAPE3-type PF. We assume that this latter file has already been created and given the PFN of T3NX.

A. Intercom Commands

<u>Line No.</u>	<u>Computer types out...</u>	<u>Operator Response</u>	<u>Comments</u>
1	COMMAND-	ETL(450)	
2	COMMAND-	CONNECT(TAPE4, TAPE5)	
3	COMMAND-	REWIND(TAPE6)	
4	COMMAND-	REWIND(TAPE7)	
5	COMMAND-	ATTACH(TAPE3, T3NX, ID=GIANINO)	
6	COMMAND-	ATTACH(TIB, TIBX, ID=GIANINO)	

<u>Line No.</u>	<u>Computer types out..</u>	<u>Operator Response</u>	<u>Comments</u>
7	COMMAND-	TIB	
8	READ DATA FILE=3?- Y		
9	DEFUALTS LISTED?- N		
10	NAME-VALUE MODE?- Y		
11	NAME VALUE.... (space, return)		
12	READ DATA FILE-7?- N		
13	DEFUALTS LISTED?- N		
14	NAME-VALUE MODE?- Y		
15	NAME VALUE.....	NP 1 MP 1 IPRNT 2 T1 time value - # 1 (in sec) - - - T10 time value # 10 (in sec)	(i) Only the data shown here can be entered. (ii) See Comment (ii) on line 8, Attach. 1A. (iii) Only those temperatures will be plotted which correspond to the (dimensioned) times given by T1, T2, etc. Linear interpolation is done, if necessary.
16	COMMAND-	REQUEST(DOG, *PF)	
17	COMMAND-	REWIND(TAPE8)	
18	COMMAND-	COPY(TAPE8, DOG)	
19	COMMAND-	CATALOG(DOG, TEMPX, ID=GIANINO, RP=999)	Lines 16-19 create a new TAPE8-type PF whose PFN is TEMPX and whose LFN is DOG.

ASIDE: If you want to calculate the diffraction pattern concomitant with the temperature distribution contained in the permanent file T3NX as mentioned above, refer to Attach. 3A., starting with line #22.

B. Batch Commands

<u>Card No.</u>	<u>Command</u>	<u>Comments</u>
1	Job card, T=20, CM=60K	
2	ATTACH(TAPE3, T3NX, ID=GIANINO)	
3	REQUEST(TAPE8, *PF)	
4	ATTACH(TIB, TIBX, ID=GIANINO)	

<u>Card No.</u>	<u>Command</u>		<u>Comments</u>
5	TIB(INPUT)		
6	CATALOG(TAPE8, TEMPX, ID=GIANINO		
7	7/8/9		EOR card.
8	Y		
9	N		
10	Y		
11	----		Blank card.
12	N		
13	N		
14	Y		
15	NP	1	For cards #15-27, see comments, line 15, Attach. 4A.
16	MP	1	
17	IPRNT	2	
18	T1	time value # 1	On cards #18-27, all time values are in seconds.
-	-	-	
-	-	-	
-	-	-	
27	T10	time value # 10	
28	-----		Blank card.
29	6/7/8/9		EOF card.

Attachment 5

Commands for Running Alternate TIKIRK Program

Assume that the alternate TIKIRK program, introduced in Section 9.7, Volume II, has been stored in the computer and is available for use, rather than the original TIKIRK program (as discussed in Sections 9.1-9.6). This alternate program is also given the PFN of TIBX. Let us further assume that we want to utilize option #3, which has the PFN of IK1B. The revised commands to run this alternate program are:

A. Intercom Commands

<u>Line No.</u>	<u>Computer types out..</u>	<u>Operator Response</u>	<u>Comments</u>
1-19	Same as Attach. 1A.		
20	COMMAND-	ATTACH(IKB, IK1B, ID=GIANINO)	IKB is the LFN for this file.
21	COMMAND-	XEQ	Indicates the following commands are loader commands.
22	OPTION =	LOAD=TIB, IKB	Causes loading of the main program TIKIRK and subroutine IKIRK.



<u>Line No.</u>	<u>Computer types out..</u>	<u>Operator Response</u>	<u>Comments</u>
23	OPTION =	EXECUTE=TIKIRK	Initiates execution.
24- 37	Same as lines 21-34, inclusive, Attach. 1A.		

The above commands would be the same for the other two options (# 1 and 2), except that on line 20 the appropriate PFN would be entered in place of IK1B. However, the LFN of IKB must be maintained.

B. Batch Commands.

<u>Card No.</u>	<u>Command</u>
1	Job card, T=2000, CM=170K
2	ATTACH(TIB, TIBX, ID=GIANINO)
3	ATTACH(TAPE3, T3NX, ID=GIANINO)
4	ATTACH(IKB, IK1B, ID=GIANINO)
5	REQUEST(TAPE7, *PF)
6	LOAD(TIB, IKB)
7	EXECUTE(TIKIRK)
8	REWIND(TAPE6)
9	COPY(TAPE6)
10	CATALOG(TAPE7, TKX, ID=GIANINO, RP=999)
11	7/8/9
12	Y
13	N
14	Y
15	(blank card)
16	N
17	N
18	Y

<u>Card No.</u>	<u>Command</u>		
19A	X1	800	
B	NP	26	
-	-	-	
-	-	-	
20	(blank card)		
21	6/7/8/9		

Attachment 6

Batch Commands for Running DISPLAY Program

(1) Intensity Plots

Let us assume that a TAPE7-type file, having the PFN of T7X and containing the intensity information to be plotted, has already been created.

<u>Card No.</u>	<u>Command</u>	<u>Comments</u>
1	Job ID, T=300, CM=170000	
2	ATTACH(DISB, DISBX, ID=GIANINO)	Attaches the DISPLAY program, whose PFN is DISBX and whose LFN is DISB.
3	ATTACH(TAPE3, T7X, ID=GIANINO)	Attaches the permanent file T7X, using the LFN of TAPE3.
4	ATTACH(PEN, ONLINEOPEN)	Cards #4-13 control the plotting process.
5	LIBRARY(PEN)	
6	LDSET(PRESET=ZERO)	
7	DISB(INPUT)	



<u>Card No.</u>	<u>Command</u>	<u>Comments</u>
8	REWIND(TAPE6)	
9	COPY(TAPE6)	
10	DISPOSE, PLOT, *OL.	
11	EXIT.	
12	REWIND(TAPE6)	
13	COPY(TAPE6)	
14	7/8/9	
15	Data card #1	See Section 10.3 for details on data cards.
16	Data card #2	
17	Data card #3	Use the values pertaining to TAPE7.
18A B	Data card #4A Data card #4B	Cards 18A and 18B contain the sequence nos. of those TEMP5 and TIKIRK parameters, respectively, which are to be listed with the plots.
19	Plot command cards (one or more)	See Section 10.4 for details on plot command cards.
20	6/7/8/9	

(2) Temperature Plots

Suppose that a TAPE8-type file has already been created, having the PFN of TEMPX and containing the temperature distribution within the window. Then, the commands to obtain temperature plots are the same as in Part (1), above, with the following exceptions:

<u>Card No.</u>	<u>Command</u>	<u>Comments</u>
3	ATTACH(TAPE3, TEMPX, ID=GIANINO)	Again, the PF is given the LFN of TAPE 3.
17	Data card #3	Use the values pertaining to TAPE8.
18B	(Remove data card #4B)	

If it is desired to have any of the above plots drawn with red ink, card #10 above would be replaced by the following:

<u>Card No.</u>	<u>Command</u>	<u>Comments</u>
10	DISPOSE, PLOT,*PL. RED INK PLEASE	The word RED starts in col. 21.

Appendix A

Fortran Listings for TEMP5 Program



A.1 Main Program TEMPS

```

1      PROGRAM TEMPS(TAPE4=128,TAPES=128,TAPE3=128,OUTPUT=128)      000100
C
5      C TEMPS IS THE PROGRAM NAME ASSIGNED TO A PROGRAM BEING ADAPTED    000110
C FROM PROGRAM TEMP4 FOR THE PURPOSE OF REDUCTION OF EXPERIMENTAL    000120
C DATA ( H VS T ) TO DETERMINE H AND RETA. JUNE 1972 BY N.G.PARKE.    000130
C THE MEANING OF THE SYMBOLS AND PARAMETERS FOR THIS PROGRAM        000140
C ARE DESCRIBED IN THE COMMENT CARDS WITH SUBROUTINE DTAFT WHICH IS  000150
C CALLED BY THIS PROGRAM AFTER IT HAS READ IN THE INITIAL          000160
C PARAMETERS AND DATA. A PARAMETER AND DATA DECK IS PUNCHED        000170
C OUT BY DTAFT. DTAFT ALSO PRINTS OUT ANY DEBUG DATA INDICATED     000180
C BY PARAMETERS II - I7.                                         000190
C
10     C SUBROUTINE DTAFT IS A MODIFICATION OF SUBROUTINE TMP88        000200
C FOR AFCRL BY N.G.PARKE IN JUNE 1972.                            000210
C
15     C THIS SUBROUTINE WAS ORIGINALLY MODIFIED ON 4 APRIL 1972 TO SHIFT  000220
C THE DATA TO EVEN INCREMENTS, USING SPLINE INTERPOLATION AND      000230
C THE CHOSEN ARBITRARY BOUNDARY CONDITIONS. THIS MODIFICATION    000240
C WAS MADE BY N.G.PARKE.                                         000250
C
20     C THE PARENT PROGRAM WAS TEMP4 FOR CALCULATING THE UNSTEADY HEAT  000260
C CONDUCTION IN A FINITE CYLINDER SUBJECT TO GENERAL BOUNDARY      000270
C CONDITIONS ON ALL ZEN AND RHO SURFACES. IT THEN COMPUTES THE    000280
C INTEGRALS F1 AND F2, REQUIRED BY DR. RENDON AND PUNCHES. THE    000290
C INPUT PARAMETERS AND F1 AND F2, IF II = 1.                      000300
C
25     C THE CYLINDER IS HEATED BY A VOLUME SOURCE DISTRIBUTION.        000310
C CYLINDRICAL SYMMETRY IS ASSUMED, I.E., THE PARABOLIC             000320
C PARTIAL DIFFERENTIAL EQUATION IS IN CYLINDRICAL COORDINATES     000330
C WITH THE ANGLE VARIABLE MISSING.                                000340
C
30     C THE NET OF SPACE POINTS IS SHIFTED HALF AN INCREMENT FROM      000350
C BOUNDARIES WHICH ARE PECTANGULAR IN CYLINDRICAL COORDINATES.    000360
C THIS NET IS BOUDED BY A FICTITIOUS SET OF POINTS THAT           000370
C ALLOW THE EASY WRITING OF GENERAL BOUNDARY CONDITIONS.          000380
C TEMPS IS A PROGRAM WHICH IS BASED ON                           000390
C THE IMPLICIT ALTERNATING DIFFERENCE METHOD OF INTEGRATING       000400
C A PARABOLIC PARTIAL DIFFERENTIAL EQUATION. IT IS CALLED         000410
C THE I.A.D. METHOD FOR SHORT.                                 000420
C
35     C IN ADDITION TO THE USUAL LIBRARY OF MATHEMATICAL               000430
C AND SYSTEM SUBROUTINES, TEMP4 REQUIRES THE SUBROUTINES TRIDAG     000440
C AND GAUSS, AS WELL AS THE SSP ROUTINE OSF FOR INTEGRATING.    000450
C
40     C
45     C THE THEORETICAL BASIS FOR THIS PROGRAM IS FULLY DOCUMENTED    000460
C IN TM NO. 5. NATHAN GERT PARKE III, PARKE MATHEMATICAL LABS.    000470
C INC., ONE RIVER ROAD, CARLISLE, MASS. 01741. NOVEMBER 1971.    000480
C MODIFICATIONS FOR VERSION TEMP4 WILL APPEAR IN TM NO. 7.    000490
C
50     C INPUT AND INITIALIZATION CONTROL CHARACTERS                  000500
C II = 0 .=. TEMP DISTRIB U INITIALIZED TO 00                   000510
C II = 1 .=. TEMP INITIAL DISTRIBUTION READ IN ON <ICARD<    000520
C IO = 0 .=. SOURCE DISTRIB Q INITIALIZED TO ZERO            000530
C IO = 1 .=. CALCULATE AND INITALIZE Q AS A TRUNCATED GAUSSIAN  000540
C DISTRIBUTION.                                              000550
C IO = 2 .=. SOURCE DISTRIBUTION READ IN ON ICARD.            000560
C
55     C USE OF THE BOUNDARY CONDITION PARAMETERS G AND H*          000570
C
60     C A PERFECT INSULATING BOUNDARY IS CHARACTERIZED BY G = 0, H = 0  000580
C NEWTON'S LAW OF COOLING IS CHARACTERIZED BY G = 0, H = FILM COEFF 000590
C GIVEN HEAT INPUT IS CHARACTERIZED BY G = INPUT, H = 0           000600
C GIVEN TEMPERATURE IS CHARACTERIZED BY G/H = TEMPO AND          000610
C BOTH G AND H VERY LARGE, E.G., G = TEMP * 1.25, H = 1.E25.       000620
C
65     C HF(Y,Y) AND GF(X,Y,Z) ARE STATEMENT FUNCTIONS OF THE FORM    000630
C USED IN EQUATIONS (19), . . . , (24) IN TM NO. 5 TO APPLY THE   000640
C THE GENERAL BOUNDARY CONDITIONS IN CALCULATING THE FICTITIOUS    000650
C POINTS IN THE U AND USTAR ARRAYS. ....                         000660
C
70     C
75     C HF(Y,Y) AND GF(X,Y,Z) ARE STATEMENT FUNCTIONS OF THE FORM    000670
C USED IN EQUATIONS (19), . . . , (24) IN TM NO. 5 TO APPLY THE   000680
C THE GENERAL BOUNDARY CONDITIONS IN CALCULATING THE FICTITIOUS    000690
C POINTS IN THE U AND USTAR ARRAYS. ....                         000700
C
80     C
85     C
90     C
95     C

```

C.....ASSIGN LOGICAL NUMBERS TO ICARD,IKEY,IPRINT AND ITYPE USING
 75 INPUT DEVICE 1, OR CHANGE THE FIRST READ CARD TO REQUIRED DEVICE NO
 THIS MAKES THE PROGRAM EASILY TRANSFERABLE TO COMPUTERS WITH
 DIFFERENT LOGICAL DEVICE NUMBER ASSIGNMENTS.
 C
 C PARAMETERS I1,...,I7 FOR CONTROLLING THE PRESENCE AND ABSENCE OF
 80 OUTPUT 1.=. OUTPUT 2.=. INHIBIT.
 C I1 .=. PUNCH AND PRINT F1,F2; AND PARAM
 C I2 .=. PRINT TAUM,MU,MU,NN,NU,ICNT,ICNTR
 C I3 .=. PRINT KK,A,B,C,D,UPRIM ALSO INITIAL VALUES OF U,USTAR ETC
 C I4 .=. PRINT U AND D AFTER INITIAL DATA READ IN OR COMPUTED
 85 C I5 .=. PRINT I=IIFIN(T,JK).
 C I6 .=. PUNCH UFIN AND PARAMETERS.
 C I7 .=. PRINT I,IU(T,J) ON HALF INCREMENT SHIFTED LATTICE.
 THE HALF INCREMENT SHIFTED LATTICE IS THE ONE USED BY US TO
 WRITE THE PROGRAM EASILY FOR GENERAL BOUNDARY CONDITIONS.
 90 C
 SUBROUTINE SPLN1(N,M,EPS,X,Y,I,SS,SS2,QUA)
 THIS IS A MODIFICATION OF SSP SUBROUTINE SPLIE TO MAKE QUA AN
 ARRAY TO MAKE THE INTEGRAL A FUNCTION OF X
 C QUA = INTEGRAL OF SS FROM X(1) TO X(N) - QUA IS AN ARRAY
 95 C
 ETNO THIRD ORDER SPLINE FCT FOR A FCT Y(X) GIVEN AT THE
 C POINTS (X(I),Y(I))
 FOLLOWING CHAP.2 OF VOL2 OF RALSTON + WILF
 C
 100 C N = NO.OF GIVEN DATA POINTS
 C M = NO.OF SPECIFIED ARGUMENTS T(I) FOR WHICH THE SPLINE
 C SS=ITS FIRST DER.SS1 AND SECOND DER.SS2 ARE TO BE COMPUTED
 C EPS = ERROR TOLERANCE IN ITERATIVE STEPS
 C X= ARRAY OF STRICTLY INCREASING ABSCISSAS
 105 C Y = ARRAY OF FCT VALUES
 C T = ARRAY OF DESIRED ABSCISSAS
 C SS = ARRAY OF SPLINE VALUES. SS1+SS2 DERIVATIVES
 C LIMITATIONS N NOT LARGER THAN 50
 C
 110 C THE ADDITION OF THE SPLINE SUBROUTINE HAS MADE IT NECESSARY TO
 INTRODUCE SOME NEW SYMBOLS AND ARRAYS
 C EPS .=. ERROR TOLERANCE IN THE ITERATIVE STEPS
 C X(22) .=. WORK SPACE FOR ARRAY OF STRICTLY INCREASING ABSCISSAS
 C Y(22) .=. WORK SPACE FOR ARRAY OF FCT VALUES
 115 C XX(22) .=. WORK SPACE FOR DESIRED ABSCISSAS
 C SS(22) .=. SPLINE VALUE OF U
 C SS1(22) .=. SPLINE VALUE OF FIRST DERIVATIVE OF U
 C SS2(22) .=. SPLINE SECOND DERIVATIVE OF U
 C QUA .=. INTEGRAL OF SS FROM X(1),X(NN)
 120 C USPIN(22,22) .=. TEMPORARY WORK SPACE. USED BETWEEN RHO-SPLINING
 AND ZED SPLINING
 C MS .=. NO. OF GIVEN DATA POINTS
 C NS .=. NO. OF SPLINE INTERPOLATED ARGUMENTS
 C
 125 C ----- PROGRAM STATEMENTS -----
 C
 130 C WRITE <PROGRAM TEMPS - A PROGRAM FOR CALLING A SUBROUTINE CYLTMP,
 WHICH USES PROGRAM TEMP4 MODIFIED AND DETERMINES H AND RETA FROM
 EXPERIMENTAL RUNS OF TEMPERATURE VS TIME.<
 C
 135 C
 140 C
 C
 145 C
 150 C

END

A.2 Subroutine DATINIT

```

1      SUBROUTINE DATINIT          001630
C
2      REAL LMDA, MU              001640
3      COMMON A(82),B(82),C(82),D(82),UPRIM(82),RHO(82),RFIN(82), 001650
4      *U(82,22),USTAR(82,22),Q(82,22),UFIN(82,22),USPLN(82,22), 001660
5      *ZFIN(22),ZED(22),E(4),G(4),H(4),LMDA,MU,NN,M1,N1,M2,N2,NF 001670
C
6      REAL NX,K,I0              001680
7      INTEGER P1,Z1,R2            001690
8      INTEGER DATAIN            001700
9      DIMENSION DATAIN(100,3)    001710
10     COMMON/ALOCK1/
11     *I1,I2,I3,I4,I5,I6,I7,MN,MI,NI,ICNT,IU,IQ,NO,NMX,TRUN, 001720
12     *ICAPD,IPPRINT,IPNCH,ITAP3,ITAP4,RHO12,ZED12,UTAU0, 001730
13     *TAU0X,TAUOFF,SIG,0.0,U0,EPS,G1(4),MATER,NX,BETA, 001740
14     *K,LAMRDA,SIR,SIT,S2P,S2T, 001750
15     *DEN,CP,R,EXPER,PW,R1,Z1,R2,IPLOT,PROBNO,TICU,XLEN,YLEN,SCALEX, 001760
16     *SCALEY1,CALEY2,XTITLE(5),YTITLE1(5),YTITLE2(5),NAME 001770
17     EQUIVALENCE (II,DATAIN)   001780
18     DATA (DATAIN(I,1),I=1,92)/7*2,80,20,3*1,0,1,2,11,100,4,6,6,3, 001790
19     *4,0,1,,-.5546,1.1092,.0035,5,5,1292,2*0,.,001,4*0,.,0,3*.015, 001800
20     *3HKCL,1.47,4.8E-4,.053,10,6,-.34E-5,.05E-5,.-1E-5,1.98, 001810
21     *.691,1.259,1H1,24,7,91,171,17H7204,5,20,9,30,1,1, 001820
22     *10HTIME(<ECON,3HDS),3IH,10HTEMP-DEG,10H ABOVE AMB, 001830
23     *3*14,10HMEAN TEMP,10H ABOVE AMB,3*14,7HBARRETT, 001840
24     *10HRADIAL DIS,10HTANCE,RHO-.4H(CM),IH,1H,10HAXIAL DIST, 001850
25     *10HANCE,7-(CM,1H),1H,1H / 001860
26     DATA (DATAIN(I,2),I=1,92)/2H11,2H12,2H13,2H14,2H15, 001870
27     *2H16,2H17,1H0,1HN,2H11,2H12,2H13,2H14,2H15, 001880
28     *2H16,2H17,1H0,1HN,2H11,2H12,2H13,2H14,2H15, 001890
29     *2H16,2H17,1H0,1HN,2H11,2H12,2H13,2H14,2H15, 001900
30     *2H16,2H17,1H0,1HN,2H11,2H12,2H13,2H14,2H15, 001910
31     *2H16,2H17,1H0,1HN,2H11,2H12,2H13,2H14,2H15, 001920
32     *2H16,2H17,1H0,1HN,2H11,2H12,2H13,2H14,2H15, 001930
33     *2H16,2H17,1H0,1HN,2H11,2H12,2H13,2H14,2H15, 001940
34     *2H16,2H17,1H0,1HN,2H11,2H12,2H13,2H14,2H15, 001950
35     *2H16,2H17,1H0,1HN,2H11,2H12,2H13,2H14,2H15, 001960
36     *2H16,2H17,1H0,1HN,2H11,2H12,2H13,2H14,2H15, 001970
37     *2H16,2H17,1H0,1HN,2H11,2H12,2H13,2H14,2H15, 001980
38     *2H16,2H17,1H0,1HN,2H11,2H12,2H13,2H14,2H15, 001990
39     *2H16,2H17,1H0,1HN,2H11,2H12,2H13,2H14,2H15, 002000
40     *2H16,2H17,1H0,1HN,2H11,2H12,2H13,2H14,2H15, 002010
41     *2H16,2H17,1H0,1HN,2H11,2H12,2H13,2H14,2H15, 002020
42     *2H16,2H17,1H0,1HN,2H11,2H12,2H13,2H14,2H15, 002030
43     *2H16,2H17,1H0,1HN,2H11,2H12,2H13,2H14,2H15, 002040
44     *2H16,2H17,1H0,1HN,2H11,2H12,2H13,2H14,2H15, 002050
45     I1=1,I2=1,I3=1,I4=1,I5=1,I6=1,I7=2 002060
46     ICAD0=5 002070
47     INDTC=0 002080
48     IPRTNT=6 002090
49     ITAD0=3 002100
50     ITAD0=4 002110
51     M=80 002120
52     N=20 002130
53     MI=NI=1 002140
54     ICNT=1 002150
55     IU=0 002160
56     IQ=1 002170
57     NO=? 002180
58     NMN=11 002190
59     IRUN=100 002200
60     RHO12=0. 002210
61     RHO12=1. 002220
62     ZED12=-.5546 002230
63     ZED12=1.1092 002240
64     DTAU0=.0035 002250
65     TAU0X=5.0 002260
66     TAU0FF=5.0 002270
67     SIG=.1292 002280
68     Q0=10=0. 002290
69     EPS=.001 002300
70     G1(1)=G1(2)=G1(3)=G1(4)=0, 002310
71     H1(1)=0. 002320
72     H1(2)=H1(3)=H1(4)=.0113 002330
73     MATER=10-HKL 002340
74     NX=1,47 002350
75     BETA=4,RF=4 002360

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75      K=.653          002370
        DFN=1.980        002380
        CD=.691          002390
        R=1.258          002400
        EXPFR=10**#2      002410
        T0=24.7          002420
        RI=91            002430
        ZI=91            002440
        R2=91            002450
        IOLOT=1          002460
        NAME=10HRARRETT   002470
        PGPNO=10H7204     002480
        TIC#=5           002490
        XLEN=20.          002500
        YLEN=9E0          002510
        SCALEX=12E0        002520
        SCALY1=-2E0        002530
        SCALY2=-2E0        002540
        XTITLE(1)=10HTIME/SECON 002550
        XTITLE(2)=10HDS1    002560
        YTITLE1(1)=10HTEMP-DEGC 002570
        YTITLE1(2)=10H ABOVE AMR 002580
        YTITLE2(1)=10HMFAN TEMP. 002590
        YTITLE2(2)= 10H ABOVE AMR. 002600
1210    CALI GETDATA (DATAIN,92,4,5,6+3,100,300,INDIC) 002610
100      WRITE(ITAB3) DATAIN 002620
        NF=n            002630
        M1=n+1          002640
        N1=n+1          002650
        M2=N1+1          002660
        N2=N1+1          002670
        002680
105      C
        C.....CALCULATE THE INCREMENT ARRAY, E(I)...
        C
        RM=M            002690
        RN=N            002700
        002710
110      E(1)=RH012/RM 002720
        E(2)=E(1)        002730
        E(3)=ZED12/RN    002740
        E(4)=E(3)        002750
        002760
115      DRHO=E(1)      002770
        DZEN=E(3)        002780
        NSEn=0            002790
        002800
120      C
        C.....INITIALIZE U,USTAR,Q,UPRIM,A,B,C,D,...,.....
        C
        DO 20 I = 1,M2  002810
        UPRIM(I) = 0.    002820
        002830
        A(I) = 0.         002840
        B(I) = 0.         002850
        C(I) = 0.         002860
        D(I) = 0.         002870
        002880
        DO 20 J = 1,N2  002890
        U(I,J) = 0.0      002900
        USTAR(I,J) = 0.   002910
        002920
130      20 0(I,J) = 0.  002930
        C
        C      USTAR,Q,UPRIM,A,B,C,D, INITIALIZED TO ZERO. U = U0 002940
        DO 21 I = 1,M1    002950
        DO 21 J = 1,N1    002960
        21 UFIN(I,J) = 0  002970
        002980
135      C
        C      UFIN HAS BEEN INITIALIZED TO ZERO 002998
        C
        C      PUTS ZETA - COORD IN ZFIN(J) 003000
        C
        DO 17 J = 1,N1  003010
        JJ = J - 1       003020
        ZJ = JJ          003030
        17 ZFIN(J) = ZED1 + 7J*DZED 003040
        003050
        003060
145      C
        C      PUTS RHO-COORD IN RFIN(I) 003070
        C
        DO 18 I=1,M1    003080
        II = I - 1       003090
        003100
        003110

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150      RT = II          003120
150      18 RFIN(I) = RH01 + RI*DRHO 003130
C       C     PUTS HALF-INC RHO-COORD IN RH0(I) 003140
C
155      DO 46 I = 1+M2 003150
        II = 2*I-3 003160
        RI = II 003170
        RI = RI/? 003180
        46 RH0(I) = RH01 + RI*DRHO 003190
160      WRITE(1,IPRINT,290) (I,RH0(I),I=1+M2) 003200
C
C       C     PUTS HALF-INC ZED-COORD IN ZEU(J) 003210
C
165      DO 55 J = 1+N2 003220
        II = 2*J-3 003230
        RJ = JJ 003240
        RJ = RJ/? 003250
        55 ZED(J) = ZED1 + RJ*DZED 003260
        WRITE(1,IPRINT,291) (I,ZED(J),J=1+N2) 003270
C
170      C     DEBUG PRINTOUT CONTROLLED BY I3 003280
C
        GO TO (2,3), I3 003290
2      WRITE(1,IPRINT,260) U 003300
        WRITE(1,IPRINT,260) USTAR 003310
        WRITE(1,IPRINT,260) O 003320
        WRITE(1,IPRINT,260) UPTRIM 003330
        WRITE(1,IPRINT,260) A 003340
        WRITE(1,IPRINT,260) B 003350
        WRITE(1,IPRINT,260) C 003360
        WRITE(1,IPRINT,260) D 003370
        WRITE(1,IPRINT,260) UFTN 003380
        3 IF(TU,EQ,0) GO TO 32 003390
        READ(1,ICAPD,225) U 003400
185      32 IF(TQ,EQ,0) GO TO 34 003410
        IF(TQ,EQ,1) GO TO 33 003420
        READ(1,ICAPD,225) Q 003430
        GO TO 34 003440
        33 CALL GAUSS(IPRINT,STG,RHO*M2+N2+0,00) 003450
        34 GO TO (35,36), I4 003460
        35 WRITE(1,IPRINT,260) U 003470
        WRITE(1,IPRINT,260) ((0(I,J)+I=2,M1),J=2,N1) 003480
        36 NN = 0 003490
        003500
190      003510
        003520
        003530
        003540
        003550
        003560
195      WRITE(1,IPRINT,280) 003570
C
        RETURN 003580
C
        003590
        003600
C
210      FORMAT(6F12.5) 003610
220      FORMAT(7T5,T71,T5,I5) 003620
225      FORMAT(7F10.3) 003630
260      FORMAT(140+10(E10.3,3X)) 003640
280      FORMAT(1H0,*END OF DATINIT*) 003650
290      FORMAT(1H0,*J,RHO(I) =*.5(I5,F8.4)) 003660
292      FORMAT(1H0,*J,ZED(J) =*.5(I5,F8.4)) 003670
330      FORMAT(1I5+T71+I5,I5) 003680
331      FORMAT(7T5,T71+I5,I5) 003690
335      FORMAT(5F12.5,T71,I5,I5) 003700
336      FORMAT(4F12.5,T71,I5,I5) 003710
210      END 003720

```

A.3 Subroutine CYLTMP

```

1      SUBROUTINE CYLTMP          003730
      REAL LMDA, MU              003740
      COMMON/BLOCK1/              003750
      *I2,I3,I4,I5,I6,I7,M,N,MI,NI,ICNT,IU,IQ,NO,NMX,TRUN, 003760
      *ICARD,IPOINT,IPNCH,ITAP3,ITA04,RHO1,RHO12,ZED1,ZED12,UTAU0, 003770
      *TAUMX,TAUOFF,SIG,NN,UN, EPS,G1(4),MATER,NX,BETAB, 003780
      *K,LAMDA,SIR,SIT,S20,S2T, 003790
      *DFN,CPR,EXPER,PW,R1,Z1,R2,IPL0,PROBNO,TICU,XLEN,YLEN,SCALEX, 003800
      *SCALEY1,SCALFY2,XTITLE(5),YTITLE1(5),YTITLE2(5),NAME 003810
      COMMON A(82),B(82),C(82),D(82),UPRIM(82),RHO(82),RFIN(82), 003820
      UJ(82,22),USTAR(82,22),O(82,22),UFIN(82,22),USPLN(82,22), 003830
      ZFIN(22),ZED(22)+G(4)*H(4),LMDA,MU,NN,MI,NI,M2,N2,NF 003840
      DIMENSION F1(82),F2(82),X(82),Y(82),SS(82),SS1(82),SS2(82), 003850
      OUA(82),YU(82),RRP(82),XR(82),ZZZ(22),XZ(22),T(1) 003860
      HF(X+Y) = (2.-X*Y)/(2.+X*Y) 003870
      GF(X+Y+Z) = 2.*Y*Z/(2.+X*Y) 003880
      DO 12 I = 1,4 003890
      G(I) = G1(I) 003900
      12 H(I) = H1(I) 003910
      WRITE(IPRINT,255) E 003920
      DRHO = E(1) 003930
      O7E0 = E(3) 003940
      C 003950
      C.....NOW WE RELOAD ARRAYS H AND G , USING FUNCTIONS HF AND GF 003960
      25 C 003970
      C 003980
      DO 10 I = 1,4 003990
      G(I) = GF(H(I)*E(I),G(I)) 004000
      10 H(I) = HF(H(I)*E(I)) 004010
      C 004020
      30 DO 3 I=1,M1 004030
      3 RRP(I)=RFIN(I) 004040
      DO 4 T=1,NI 004050
      4 ZZZ(I)=ZFIN(I) 004060
      C.....WE NOW WRITE OUT THE NEW VALUES OF ARRAYS G AND H. 004070
      35 C 004080
      WRITE(IPRINT,250) G 004090
      WRITE(IPRINT,245) H 004100
      TAU = 0. 004110
      ICNTR = 0 004120
      NF = 0 004130
      TFIN = 0.0 004140
      MS=2 004150
      IF (TAUOFF .GE. TAUMX) MS=1 004160
      C 004170
      C .....MAIN ENTRY FOR NEW I,A,D. CYCLE ..... 004180
      C 004190
      45 55 DTAU=DTAU0 004200
      40 IF (NN.GE.NMX) GO TO 45 004210
      IF (NN .EQ. 0) GO TO 45 004220
      50 C 004230
      C CONDITIONAL CALCULATION OF UTAU, WHEN NN.LT.NMX 004240
      C 004250
      RNN = NN 004260
      RNO = NO 004270
      REX = RNN/RNO 004280
      DTAU = DTAU0*2.*REX 004290
      C 004300
      C.....INCREMENT TAU,NN,ICNTR,..... 004310
      C 004320
      60 45 GOTO (330,340,360,370) MS 004330
      340 IF (TAU+2E0*DTAU .LT. TAUOFF) GOTO 330 004340
      MS=1 004350
      DTAU=(TAUOFF-TAU)/2E0 004360
      GOTO 330 004370
      65 360 MS=4 004380
      DO 350 J=1,N2 004390
      DO 350 I=1,M2 004400
      O(I,J)=0E0 004410
      350 CONTINUE 004420
      G(1)=G(2)=G(3)=G(4)=0. 004430
      NN=0 004440
      GOTO 55 004450
      330 TAU=TAU+DTAU 004460
      NN = NN + 1 004470
      ICNTR = ICNTR + 1 004480
      LMDA = DTAU/DRHO**2 004490
      MU = DTAU/DZED**2 004500
      GO TO (47,48),I2 004510
      47 WRITE(IPRINT,265) TAU,LMDA,MU,NN,NO,ICNT,ICNTR

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```

80      48 DO 50 I = 2,M1          004520
        U(I,1) = H(3)*U(I,2)+G(3)
        U(I,N2) = H(4)*U(I,N1)+G(4)
        A(I) = LMDA*(I-E(I))/2./RHO(I)
        B(I) = -(2.*LMDA+1)
50      C(I) = LMDA*(I+E(I))/2./RHO(I) 004530
85      C      COMPLETE THE BORDERING OF THE COMPUTATION LATTICE 004540
C      004550
C      004560
C      004570
C      004580
90      004590
        DO 13 J = 2,N1          004600
        U(I,J) = H(1)*U(2,J)+G(1)
13      U(M2,J) = H(2)*U(M1,J)+G(2) 004610
C      004620
C      004630
C      004640
C      004650
C      004660
95      R(2) = R(2) + A(2)*H(1) 004670
        R(M1) = R(M1) + C(M1)*H(2)
        DO 70 J = 2,N1          004680
        DO 60 I = 2,M1          004690
60      D(I) = -MU*(U(I,J+1)-2.*U(I,J)+U(I,J-1))-DTAU*Q(I,J)-U(I,J) 004700
C      004710
100     C.... TOUCH UP OF COEFFICIENTS B(I)..... 004720
C      004730
C      004740
D(2) = D(2) - A(2)*G(1) 004750
D(M1) = D(M1) - C(M1)*G(2) 004760
CALI TRIDAG(2,M1,A,B,C,D,UPRIM) 004770
105     C.... WE HAVE JUST SOLVED THE TRIIDIAGONAL EQUATIONS..... 004780
C.... THE RESULTS ARE STORED IN UPRIM.. THE CONTENTS OF UPRIM.. 004790
C.... MUST NOW BE TRANSFERRED TO COLUMN J OF ARRAY USTAR..... 004800
C      004810
110      DO 63 KK = 2,M1          004820
        GO TO (63,64), I3          004830
63      WRITE(IP,INT,285) KK,A(KK)+B(KK)+C(KK),D(KK),UPRIM(KK) 004840
64      DO 70 K = 2,M1          004850
70      USTAR(K,J) = UPRIM(K) 004860
115     C
C      CALCULATE U ON BOUNDARY AND EVEN LATTICE POINTS BY 004870
C      BELLOW INTERNAL SPLINE EXTRAPOLATION TO BOUNDARY POINTS. 004880
C      004890
C      004900
C      004910
120      IF (ICNTR.GT.1) GO TO 16          004920
NF = NF+1 004930
TFIN = TAU - DTAU 004940
C      004950
C      004960
125      BELLOW MODIFICATION OF SPLINE INTERPOLATION BEGINS AT THIS POINT 004970
C      IT CONSISTS OF EXTRAPOLATIONS TO THE BOUNDARY, USING SLOPE SSU 004980
C      AND VALUE SS AT INTERIOR POINTS RHO(2),RHO(M1),ZED(2)*ZEN(N1). 004990
C      OTHER CALCULATIONS ARE MADE BY THIRD ORDER SPLINE INTERPOLATION 005000
C      AND THE ACCURACY OF THE INTERPOLATION IS CONTROLLED BY THE 005010
C      CHOICE OF OF EPS 005020
130     C
C      THE FIRST STEP IN THE PROCESS IS SPLINE INTERPOLATION OF U(I,J) 005030
C      RELATIVE TO RHO-VALUES. INDEX I. 005040
C      005050
C      005060
135     DO 160 I = 2,M1          005070
160     X(I-1) = RHO(I) 005080
        DO 161 J = 1,M1          005090
161     XR(J) = RHO(J) 005100
        XR(1) = RHO(2) 005110
        XR(M1) = RHO(M1) 005120
140     DO 162 J = 2,N1          005130
        DO 163 I = 2,M1          005140
163     Y(I-1) = U(I,J) 005150
C      005160
C      005170
145     IF (I.GT.1) GO TO 1 005180
        WRITE(IP,INT,210) 005190
        WRITE(IP,INT,200) X 005200
        WRITE(IP,INT,200) Y 005210
        CALL SPLNT(M,M1,EPS,X,Y,XR,SS,SS1,SS2,QUA) 005220
        CALL SPLNT(M,M1,EPS,X,Y,XR,SS,SS1,SS2,QUA) 005230
C      005240
C      005250
150     SS AND SS1 ARE USED AT THE END POINTS IN THE BB VERSION. 005260
        DO 164 KS = 1,M1

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155      164 USPLN(KS,J) = SS(KS)
C       EXTRAPOLATION TO ROINNDARY, USING SS AND SS1
C       USPLN(I,J) = SS(1)+(RFIN(1)-RHO(2))*SS1(1)
C       USPLN(M1,J) = SS(M1)+(RFIN(M1)-RHO(M1))*SS1(M1)
162 CONTINUE
160      C       WE NOW HAVE EVEN RHO-INTERPOLATED VALUES OF U. WE NEED EVEN
C       ZED-INTERPOLATED VALUES OF U TO INSERT IN UFIN(I,J,K).
C       THE FOLLOWING STEP DOES SPLINE INTERPOLATION IN THE ZEU-DIRECTION
165      C
C       DO 166 T = 2,N1
166      X(T-1) = ZED(1)
DO 167 J = 1,N1
167      X7(J) = Z77(J)
X7(1) = ZED(2)
X7(N1) = ZED(N1)
DO 168 T = 1,M1
DO 169 I = 2,N1
169      Y(J-1) = USPLN(T,I)
175      C
C       IF(T.GT.1) GO TO 2
C       WRITE(IPRINT,210)
C       WRITE(IPRINT,200) X
C       WRITE(IPRINT,200) Y
180      C
C       2 CALL SPLN(N,N1,EPS,X,Y,XZ+SS+SS1+SS2,QUA)
C       CALL SPLN(N,N1,EPS,X,Y,XZ+SS+SS1+SS2,QUA)
C
C       THE INTERPOLATED RESULT IS NOW STORED IN UFIN
185      C
DO 170 J = 1,N1
170      UFIN(I,J) = SS(I)
C       EXTRAPOLATION TO ROINNDARY, USING SS AND SS1
C       UFTN(T,1) = SS(1)+(ZFTN(1)-ZED(2))*SS1(1)
C       UFTN(I,N1) = SS(N1)+(ZFTN(N1)-ZED(N1))*SS1(N1)
190      C
168 CONTINUE
C       THIS COMPLETES THE CALCULATION OF UFIN(I,J) FOR THE CURRENT
C       VALUE OF K = NF BY THIRD ORDER SPLINE INTERPOLATION AND
C       EXTRAPOLATION TO THE ROINNDARIES.
195      C
DO 130 T = 1,M1
DO 131 J = 1, N1
132      YU(I) = UFIN(I,J)
T(I) = ZFTN(I)
CALL SPLN(I,M1+1,EPS,ZFTN,YU,I,SS,SS1,SS2,QUA)
130      F1(I) = QUA(N1)
C
C       THIS COMPLETES THE CALCULATION OF F1
205      C
DO 136 I = 1,M1
136      YU(T) = F1(I)*RFIN(T)
T(I) = RFIN(I)
CALL SPLN(I,M1+1,EPS,ZFTN,YU,T,SS,SS1,SS2,QUA)
210      C
DO 138 IT = 2,M1
138      F2(TI) = QUA(IT)/ZFTN(IT)**2
F2(I) = 1.5*F1(I)
C
C       THIS COMPLETES THE CALCULATION OF F2
215      C
WRITE(IPRINT,381) NF,TFIN,RFIN,ZFTN,UFIN,F1,F2
C
C       IF T1 = 1 TYPE OUT F1 AND F2.
C       IF T5 = 1 TYPE OUT UFTN.
220      C
IF(T1.EQ.2.AND.T5.EQ.2) GOTO 370
IF(T1.NE.1) GOTO 371
WRITE(IPRINT,381)
DO 373 T=1,M1+5
373      WRITE(IPRINT,381), T,F1(I)+F2(I)
371      IF(T5.NE.1) GOTO 370
WRITE(IPRINT,382)
DO 374 T=1,M1+5
374      WRITE(IPRINT,382), T,(UFIN(I,J)+J=1,N1,S)

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230      370 CONTINUE
C      THE RECORD OF THE SPLINE CALCULATION AND INTEGRATION HAVE BEEN    006020
C      WRITTEN AS THE NEXT RECOR ON TAPE 3.                                006030
C..... THIS IS THE END OF THE FIRST HALF OF THE I.A.D. CYCLE.          006040
C..... THE INTERMEDIATE ARRAY USTAR HAS BEEN CALCULATED. .....
235      C
C       16 TAU = TAU + DTAU
C       NN = NN + 1
C
C..... APPLY THE RHO BOUNDARY CONDITIONS. .....
240      C
DO 90 J = 2,NI
USTAR(1,J)=H(1)*USTAR(2,J)+G(1)
USTAR(M2,J)=H(2)*USTAR(M1,J)+G(2)
A(J) = MU
245      B(J) = -(2.*MU+1.)
80 C(J) = MU
C
C..... COEFFICIENT B TOUCH UP.....
C
250      B(2) = B(2) + A(2)*H(3)
B(NI) = B(NI) + C(NI)*H(4)
C
C..... CALCULATION OF COEFFICIENTS U .....
C
255      DO 100 I = 2,NI
DO 90 J = 2,NI
D(J) = -LMDA*(USTAR(I+1,J)-2.*USTAR(I,J)+USTAR(I-1,J))
D(J) = D(J) - LMDA*DHO/2./RHO(I)*(USTAR(I+1,J)-USTAR(I-1,J))
90 D(J) = D(J) - DTAU*D(I,J) - USTAR(I,J)
260      C
C.... TOUCH UP OF THE D COEFFICIENTS....
C
D(2) = D(2) - A(2)*G(3)
D(NI) = D(NI) - C(NI)*G(4)
265      C
C..... CALL TRIDAG TO SOLVE THE TRIDIAGONAL SYSTEM OF EQUATIONS..
C..... THE RESULT WILL BE RETURNED IN UPRIM ARRAY. .....
C
CALL TRIDAG(2,NI,4,R,C,D,UPRIM)
270      DO 93 KK = 2,NI
GO TO (93,94),I3
93 WRITE(IPRINT,285)KK,A(KK)+B(KK)+C(KK),D(KK),UPRIM(KK)
94 DO 100 J = 2,NI
100 U(I,J) = UPRIM(J)
275      IF(ICNTR.LT.ICNT) GO TO 40
C
C..... AT EACH RETURN TO 40 BEGINS ANOTHER I.A.D. CYCLE. ..
C
ICNTR = 0
280      GO TO (111,112),I7
111 CONTINUE
WRITE(IPRINT,271) TAU+DTAU
DO 110 I = 2,NI,MY
WRITE(IPRINT,275) I,RHO(I)
285      110 WRITE(IPRINT,320)(U(I,J),J=2,NI,NI)
112 CONTINUE
IF(TAU>TAUMX) GO TO 40
C      WHEN TAU EXCEEDS TAUMX. THIS SUBROUTUE RETURNS TO THE MAIN PROGRAM
C      TENDS, AFTER PRINTING <TAU,GT,TAUMX - CYLTMP RET TO TEMPS<
290      C..... END OF I.A.D. CYCLE .....
WRITE(IPRINT,111)
RETURN
11 FORMAT(1H0,*TAU,GT,TAUMX - CYLTMP RET TO TEMPS*)
200 FORMAT(1H0,10F10.4)
210 FORMAT(1H0,*DEB1IG X,Y+XX*)
245 FORMAT(1H0,*H1,H2,H3,H4 =*,4(E10.3,3X))
250 FORMAT(1H0,*G1,G2,G3,G4 =*,4(E10.3,3X))
255 FORMAT(1H0,*F1,F2,E7,E4 =*,4(E10.3,3X))
265 FORMAT(1H0,*TAU,LMDA,MU,NN,N0,ICNT,INCTR =#,3(E10.3,3X)/415)
270 FORMAT(1H0,*TAU = *,F10.3,*DTAU = *E10.3)
275 FORMAT(1H0,*I,RHO = *15*F10.4)
285 FORMAT(1H0,15*3*5(F10.7,3X))
290 FORMAT(1H ,10(E10.3,3X))
380 FORMAT(1H ,10(E10.3,3X))

```

305	181 FORMAT (1H0,I5,2(3X,F10.3))	006770
	182 FORMAT (1+1H0,*1+10X*UFIN(I,J) FROM J= 1 TO N1 *#/)	006780
	183 FORMAT (1H0,I5,10(3X,F10.3),1+1H0+10X,9(3X,E10.3),/,	006790
	+1H0+23X,4(3X,E10.3))	006800
	END	006810

A.4 Subroutine TRIDAG

1	1 SUBROUTINE TRIDAG (TF,L,A+B,C+D+V)	006820
	C	006830
	THE SUBROUTINE FOR SOLVING A SYSTEM OF LINEAR SIMULTANEOUS	006840
	EQUATIONS HAVING A TRIDIAGONAL COEFFICIENT MATRIX.	006850
5	C THE EQUATIONS ARE NUMBERED FRUM TF THROUGH L, AND THEIR	006860
	SUB-DIAGONAL, DIAGONAL, AND SUPER-DIAGONAL COEFFICIENTS ARE	006870
	STORED IN ARRAYS A+B+C. THE COMPUTED SOLUTION VECTOR	006880
	C V(IF).....V(L) IS STORED IN ARRAY V.	006890
	C	006900
10	10 DIMENSION A(1)+B(1)+C(1)+D(1)+V(1)+BETA(82)+GAMMA(82)	006910
	C	006920
COMPUTE ARRAYS BETA AND GAMMA.....	006930
	C	006940
	BETA(IF) = B(IF)	006950
15	GAMMA(IF) = D(IF)/BETA(IF)	006960
	IFPI = TF + 1	006970
	DO I = IFPI,L	006980
	BETA(I) = B(I) - A(I)*C(I-1)/BETA(I-1)	006990
	1 GAMMA(I) = (D(I)-A(I)*GAMMA(I-1))/BETA(I)	007000
20	C	007010
COMPUTE FINAL SOLUTION VECTOR V	007020
	C	007030
	V(L) = GAMMA(L)	007040
	LAST = L-1 IF	007050
25	DO 2 K = 1, LAST	007060
	I = L-K	007070
	2 V(I) = GAMMA(I) - C(I)*V(I+1)/BETA(I)	007080
	RETURN	007090
	C	007100
30	END	007110

A.5 Subroutine GAUSS

```

1      SUBROUTINE GAUSS(IPRINT,SIG,RHO,M,N,Q,QQ)          007120
      DIMENSION RHO(1),Q(M,N)
      IF(<IG.EQ.0.) GO TO 20
      STG2 = STG*2
      IF(Q.GE.,001) GO TO 5
      1000 QD=.5/SIG2
      5 M1 = M-1
      N1=N-1
      DO 10 I = 2,M1
      RHO2 = RHO(I)**2
      QTEST=.5*RHO2/STG2
      IF (QTEST .GT. 220.) 1020,1030
      1020 QD=1.
      GOTO 1040
      1030 QD=10*EXP(-QTEST)
      1040 CONTINUE
      DO 10 J = 2,N1
      10 Q(I,J) = QD
      RETURN
      20 WRITE(IPRINT,100)
      100 FORMAT(1H0,*SIG = 0. DEFAULT OPTION IS Q = 0*)
      RETURN
      END

```

A.6 Subroutine SPLNI

```

1      SUBROUTINE SPLNI(M,EPS,X,Y,I,SS,SS1,SS2,QUA)        007350
C
C      FIND THIRD ORDER SPLINE FCT FOR A FCT Y(X) GIVEN AT THE 007360
C      POINTS (X(I),Y(I)) 007370
C      FOLLOWING CHAP.9 OF VOL2 OF RALSTON + WILF 007380
C
C      N = NO. OF GIVEN DATA POINTS 007390
C      M = NO. OF SPECIFIED ARGUMENTS T(I) FOR WHICH THE SPLINE 007400
C      SS+ITS FIRST DER.SS1 AND SECOND DER.SS2 ARE TO BE COMPUTED 007410
C      EPS = ERROR TOLERANCE IN ITERATIVE STEPS 007420
C      X= ARRAY OF STRICTLY INCREASING ABSCISSAS 007430
C      Y = ARRAY OF FCT VALUES 007440
C      T = ARRAY OF DESTINED ABSCISSAS 007450
C      SS = ARRAY OF SPLINE VALUES . SS1+SS2 DERIVATIVES 007460
C      QUA = ARRAY OF VALUES OF INTEGRAL FROM X(I) TO X(N) 007470
C      LIMITATIONS N NOT LARGER THAN 50 007480
C
C      DIMENSION X(1),Y(1),T(1),SS(1),SS1(1),SS2(1),QUA(1) 007490
C      DIMENSION H(82),H2(82),DELY(82),B(82),DELSY(82) 007500
C      DIMENSION S2(82),C(82),S3(82)
C      DATA OMEGA/1.0717968/ 007510
C      N1=N-1
C      3 DO 51 I=1,N1
C      H(I)=X(I+1)-X(I) 007520
C      51 DELY(I)=(Y(I+1)-Y(I))/H(I) 007530
C      4 DO 52 I=2,N1
C      H2(I)=H(I-1)+H(I) 007540
C      52 R(I)=.5*(I-1)/ H2(I) 007550
C      DELSY(I)=(DELY(I)-DELY(I-1))/H2(I) 007560
C      S2(I)=2.*DELSY(I) 007570
C      C(I)=3.*DELSY(I) 007580
C      S2(I)=0. 007590
C      S2(N)=0. 007600
C      5 ETA=0. 007610
C      6 DO 10 I=2,N1 007620
C      7 W=(C(I)-R(I)*S2(I-1)-(S2(I)-R(I))*S2(I+1)-S2(I))*OMEGA 007630
C      8 IF (ABS(W)-ETA) 10,10,9 007640
C      9 ETA=ABS(W) 007650
C      10 S2(I)=S2(I)+W 007660

```

```

40      13 IF (ETA-EPS) 14,5,5          007740
41      14 DO 53 I=1,N1            007750
53      S3(I)=(S2(I+1)-S2(I))/H(I) 007760
45      15 DO 41 J=1,M            007770
46      16 T=1                  007780
54      17 IF (T(J)-X(I)) 58,17,55 007790
55      18 IF (T(J)-X(N)) 57,59,59 007800
56      19 IF (T(J)-X(I)) 60,17,57 007810
57      20 I=I+1            007820
58      21 GO TO 56            007830
59      22 WRITE(6,44) J          007840
44      23 FORMAT (14,24H TH ARGUMENT OUT OF RANGE) 007850
50      24 GO TO 61            007860
51      25 I=N            007870
52      26 I=I-1            007880
55      27 HT1=T(J)-X(I)        007890
56      28 HT2=T(J)-X(I+1)        007900
57      29 PROD=HT1*HT2        007910
58      30 SS2(J)=S2(I)+HT1*S3(I) 007920
59      31 DEL=S=(S2(I)+S2(I+1)+SS2(J))/6. 007930
60      32 SS(I)=Y(I)+HT1*DELY(I)+PROD*DELSS 007940
61      33 SS1(J)=DELY(I)+(HT1+HT2)*DELSS+PROD*S3(I)/6. 007950
61      34 CONTINUE            007960
62      35 QUA(I) = C.0          007970
63      36 DO 42 I=1,N1            007980
65      37 QUA(I+1)=QUA(I)+.5*H(I)*(Y(I)+Y(I+1))-H(I)**3*(S2(I)+S2(I+1))/24. 007990
66      38 RETURN            008000
67      39 END            008010

```

A.7 Subroutine GETDATA

```

1      SUBROUTINE GETDATA(DATAIN,NV,IIN,IOUT1,IOUT2,IINI,ISIZE      008020
2      ,TSZET,INDIC)      008030
3      C THE MAIN PURPOSE OF THIS SUBROUTINE IS TO INPUT CHARACTER STRING OR      008040
4      C NUMERICAL DATA IN A CONVERSATIONAL MODE I.E. FOR INPUTTING DATA      008050
5      C TO PROGRAMS BEING RUN UNDER INTERCOM.      008060
6      C IT ALSO MAY BE USED FOR BATCH PROCESSING-IN WHICH CASE THE DATA      008070
7      C SHOULD APPEAR 6 VALUES TO A CARD. DATA WHICH IS NOT TO BE CHANGED      008080
8      C SHOULD BE REPLACED BY BLANKS. FOR BATCH ALL OR SOME OF THE DATA MAY      008090
9      C BE DEFAULTED BY USING AN EOF AFTER THE LAST DATA TO BE INPUTTED.      008100
10     C THE SUBROUTINE ASSUMES THAT DEFAULT VALUES HAVE BEEN ASSIGNED      008110
11     C AND WILL PRINT OUT THESE DEFAULT VALUES BEFORE ASKING FOR DATA INPUT. 008120
12     C IT ASKS FOR NEW VALUES BY PRINTING OUT THE NAMES OF THE DATA AND THEN 008130
13     C SKIPPING A LINE. VALUES TO BE ASSIGNED TO THE NAMES SHOULD BE      008140
14     C ENTERED STARTING IN THE SAME COLUMN AS THE START OF THE NAME.      008150
15     C EACH DATUM IS ASSIGNED TO COLUMNS AND UP TO 6 ITEMS MAY BE INPUTTED 008160
16     C IN A SINGLE ROW.      008170
17     C ARGUMENTS*****      008180
18     C DATAIN (DIMENSION (NV,7) WHERE NV IS THE TOTAL # OF DATA      008190
19     C TO BE INPUTTED)      008200
20     C DATAIN HOLDS THE FOLLOWING INFORMATION ABOUT EACH DATUM-      008210
21     C NAME, VALUE, CODE WHERE-      008220
22     C NAME => NAME BY WHICH THE DATUM IS IDENTIFIED TO THE USER (IT MAY OR 008230
23     C MAY NOT BE EQUAL TO THE FORTRAN VARIABLE NAME TO BE ASSIGNED TO THE 008240
24     C DATUM.)
25     C VALUE => NUMERICAL OR CHARACTER STRING VALUE TO BE ASSIGNED (THE DATUM) 008250
26     C CODE => HOW THE DATUM IS TO BE INTERPRETED      008260
27     C -1 => CHARACTER STRING      008270
28     C 0 => INTEGER      008280
29     C 1 => FLOATING POINT NUMBER      008290
30     C NV TOTAL NUMBER OF DATUM TO BE INPUTTED      008300
31     C IIN FILE NO. FOR INPUTTING      008310
32     C IOUT1 PRIMARY OUTPUT FILE      008320
33     C IOUT2 SECONDARY OUTPUT FILE      008330
34     C TSZET SIZE OF FIRST DIMENSION OF DATAIN      008340
35     C ISIZE = 008350

```

```

35      DIMENSION DATAIN(1ST2ET),IA(6)          008360
       COMMON/SFNSE/IINNN,TOUTNN,INDLCC
       INTEGER DATAIN,F
       EXTERNAL SSWTCH
       CALL ERRSET(KOUNT,20000)
       KOUNT1=KOUNT
       IF(INDIC.NE.0) 200,210
200   ISW=2
       LL=n
       L=INDIC-1
       GOTO 1055
210   CONTINUE
       ISW=1
       IDOL=000000000000000053B
       IINNN=IIN
       IOUTNN=IOUT1
       IOUTI=IOUT1
       ISN=1
       TBLANK=10H
       CALL SSWTCH(IINN,ISW3,10HREAD DATA +SHFILE-),RETURNS(106n)
       IF (ISW3 .EQ. 1) 1300,1290
1300  WRITE(IOUT1,17) IINN
       REWIND IINN
       READ(IINN) DATAIN
       REWIND IINN
       IF (EOF(IINN)) 1400,1290
1400  WRITE(IOUT1,24) IINN
       1290 CONTINUE
       CALL SSWTCH(0,ISW4,10HDEFAULTS L,SHIFTED),RETURNS(1060)
       IF (ISW4 .NE. 1) GOTO 1150
       WRITE(IOUT1,1)
       1140 DO 110 I=1,NV
           II=rSIZE+I
           III=I
           II2=II+rSIZE
           IF (DATAIN(II2)) 1020,1030,1040
1020  WRITE(IOUTT,2) DATAIN(II)+DATAIN(III)
           GOTO 110
1030  WRITE(IOUTT,3) DATAIN(II)+DATAIN(III)
           GOTO 110
1040  WRITE(IOUTT,4) DATAIN(II)+DATAIN(III)
110   CONTINUE
           GOTO (1150,1130),TSN
1150  CALL SSWTCH(0,ISW5,10HNAME-VALUE,SH MODE),RETURNS(106U)
       IF (ISWS .EQ. 1) 1270,1050
1050  L=1
       ISW=2
       LL=n
       1055 L=L+LL
       IF (L .GT. NV) GOTO 1060
1060  WRITE(IOUT1,18) DATAIN(rSIZE+L)
       LL=1
       DO 100 J=1,6
           IA(J)=104
100   CONTINUE
       READ(IIN,10) (IA(J)),J=1,6
       IF (EOF(IIN)) 1320,1070
1320  INDLC=1
       GOTO 1060
1070  IF (IA(1) .EQ. TBLANK) GOTO 1055
       DO 180 J=1,6
       DO 180 K=1,10
       IF (MXGETX(IA(J)+K+1) .EQ. INDUL) GOTO 1270
180   CONTINUE
       DO 190 J=1,6
           JR=L+J-1
           F=DATAIN(JR+2*rSIZE)
           IF (F) 190,1100,1110
1100  IF (IA(J) .NE. TBLANK) DECODE(10,11,IA(J)) DATAIN(JR)
           GOTO 1080
1100  CALL RJUST(IA(J))
           IF (IA(J) .NE. TBLANK) DECODE(10,12,IA(J)) DATAIN(JR)
           GOTO 1080
1110  CALL PJUST(IA(J))
           IF (IA(J) .NE. TBLANK) DECODE(10,13,IA(J)) DATAIN(JR)
1080  IF (IA(J) .EQ. TBLANK) GOTO 1081
1081  LL=j-1
       IF (INDIC.NE.0) LL=1000
       IF (KOUNT .EQ. KOUNT1) GOTO 1055

```

115	KOUNT1=KOUNT	009140
	WRITE(IOUT1,25)	009150
1270	WRITE(IOUT1,23)	009160
1250	WRITE(IOUT1,8)	009170
DO 150 I=1,6	009180	
IA(I)=104	009190	
120 150	CONTINUE	009200
	READ(IN,10) (IA(I),I=1,6)	009210
	IF (EOF(IN)) 1330,1085	009220
1330	INDTCC=1	009230
125	GOTO 1060	009240
1085	IT=IA(1)	009250
	IF (IT .EQ. 1BLANK) GOTO 1060	009260
	DO 130 I=1,NV	009270
	J=I+ISIZE	009280
130	IF (II .EQ. DATAIN(J)) GOTO 1160	009290
	CONTINUE	009300
	WRITE(IOUT1,16)	009310
	GOTO 1270	009320
1160	F=DATAIN(J+ISIZE)	009330
135	JJ=J-ISIZE	009340
	IF (F) 1170,1180,1190	009350
1170	DO 160 I=2,6	009360
	IF (IA(I) .EQ. 1BLANK .AND. I.GT.2) GOTO 1240	009370
	DECODE(10,11,IA(I)) DATAIN(JJ+I-2)	009380
140	160 CONTINUE	009390
	GOTO 1240	009400
	1180 CALL RJUST(IA(2))	009405
	DECODE(10,12,IA(2)) DATAIN(JJ)	009410
	GOTO 1240	009420
145	1190 CALL RJUST(IA(2))	009425
	DECODE(10,13,IA(2)) DATAIN(JJ)	009430
1240	IF (KOUNT .EQ. KOUNT1) GOTO (1250+1310) ISW	009440
	KOUNT1=KOUNT	009450
	WRITE(IOUT1,25)	009460
150	GOTO 1250	009470
	1060 WRITE (IOUT1,14)	009480
	IF (IOUT2 .EQ. 0) GOTO 1140	009490
	WRITE (IOUT2,15)	009500
	IOUT2=IOUT2	009510
155	ISN=2	009520
	GOTO 1140	009530
1130	INDTCC=INDICC	009540
	RETURN	009550
1	FORMAT(/,* THE DEFAULT INPUT DATA ARE*)	009560
2	FORMAT(1X,A10,*=*,A10,*=*)	009570
3	FORMAT(1X,A10,*=*,I10)	009580
4	FORMAT(1X,A10,*=*,G16.6)	009590
5	FORMAT(//)	009600
6	FORMAT(/,* ENTER DATA. START IN COL. BENEATH START OF NAME*)	009610
165	7 FORMAT(8X,6A10)	009620
	8 FORMAT(8X)	009630
10	FORMAT(6A10)	009640
11	FORMAT(A10)	009650
12	FORMAT(I10)	009660
170	13 FORMAT(E10.0)	009670
	14 FORMAT(/,* DATA INPUT COMPLETE*)	009680
15	FORMAT(/,* THE INPUT DATA VALUES ARE*)	009690
16	FORMAT(1X,* TRY AGAIN*)	009700
17	FORMAT(/,1X,* READING DATA FROM *I5)	009710
18	FORMAT(1X,A10,*=*)	009720
23	FORMAT(8X,*NAME VALUE...,*)	009730
24	FORMAT(1X,* FILE*,I5,* IS EMPTY*)	009740
25	FORMAT(1X,* WRONG DATA TYPE-TRY AGAIN*)	009750
	END	009760

A.8 Subroutine SSWTCH

1	SUBROUTINE SSWTCH(I, I, M1, M2), RETURNS(M)	009770
	COMMON/ONSENSE/IIN, TOUT, INDIC	009780
	IF (I .EQ. 0) GOTO 100	009790
	WRITE(IOUT1,1) M1,M2,T	009800
5	GOTO 110	009810
	100 WRITE(IOUT1,2) M1,M2	009820
	110 READ(IIN,3) JJ	009830
	J=2	009840
	IF (JJ .EQ. 1HY) J=1	009850
10	INDIC=EOF(IIN)	009860
	IF (/INDIC) 1000,1010	009870
	1000 RETURN M	009880
	1010 RETURN	009890
	1 FORMAT(1X,A10,A5,T2,*?-*?)	009900
15	2 FORMAT(1X,A10,A5,*?-*?)	009910
	3 FORMAT(A1)	009920
	END	009930

A.9 Subroutine RJUST

1	SUBROUTINE RJUST(I)	009940
	DIMENSION LC(9)	009950
	DATA (LC=77555555555555555555B,777755555555555555B,	009960
	+77777755555555555555B,777777755555555555B,	009970
5	+77777777755555555555B,777777777555555555B,	009980
	+777777777775555555B,777777777775555555B,	009990
	+77777777777775555555B)	010000
	LR=I	010010
	IBITS=0	010020
10	DO 100 I=1,9	010030
	IBITS=IBITS+6	010040
	LR=ACK(IBITS).OR.LR	010050
	IF (/LR.EQ.LC(I)) GOTO 110	010060
	100 CONTINUE	010070
	GOTO 120	010080
15	110 L=SHIFT(I,IBITS)	010090
	120 RETURN	010100
	END	010110

Appendix B

Fortran Listings for TIKIRK Program, Options No. 1 and No. 2 Only



B.1 Main Program TIKIRK

```

1      PROGRAM TIKIRK(TAPE4=R0/B0,TAPES=80/80,TAPE3,TAPE7+TAPE8.          000100
      +TAPE6=80/R0,OUTPUT=0)
C THIS PROGRAM CAN BEST BE DESCRIBED AS THE I/O INTERFACE FOR FUNCTION      000110
C SUBROUTINE IKIRK WHICH COMPUTES THE KIRKHOFF INTENSITY FUNCTION AS      000120
C DESCRIBED IN AFCRL-72-0565.                                              000130
5      C   THE INPUT FALLS INTO THREE CLASSES*
C   1) INPUT HAVING TO DO WITH PROPERTIES OF THE WINDOW MATERIAL AND      000140
C   THE LASER BEAM, NAMELY: QUANTITIES CGS UNLESS OTHERWISE INDICATED      000150
C
C SIG  => VALUE OF SIGMA IN GAUSSIAN BEAM                                000160
C LAMBDA => WAVELENGTH OF THE LIGHT BEAM IN MICRONS                      000170
10     C P  => TOTAL BEAM POWER                                         000180
C R  => WINDOW RADUS                                              000190
C RETA => BULK ABSORPTION COEFFICIENT                                     000200
C K  => THERMAL CONDUCTIVITY                                         000210
C NX  => INDEX OF REFRACTION                                         000220
C S1R  => S SUB-1,SUP-RHO                                         000230
C S1T  => S SUB-1,SUP-THETA                                         000240
C S2R  => S SUB-2,SUP-RHO                                         000250
C S2T  => S SUB-2,SUP-THETA                                         000260
15     C T  => TIME AT WHICH IKIRK IS TO BE EVALUATED                      000270
C   2) INPUT HAVING TO DO WITH THE EVALUATION DOMAIN OF THE FUNCTION      000280
C TIKRK, NAMELY:
C   X0  => GAUSSIAN FOCAL DISTANCE (METERS)                               000290
C   X1  => MINIMUM X-VALUE FOR FUNCTION EVALUATION (METERS)               000300
C   X2  => MAXIMUM X-VALUE FOR FUNCTION EVALUATION (METERS)               000310
20     C RH001 => MINIMUM RADUS VALUE FOR FUNCTION EVALUATION                000320
C RH002 => MAXIMUM RADUS VALUE FOR FUNCTION EVALUATION                  000330
C MP  => NUMBER OF EVALUATION POINTS IN THE RADIAL DIRECTION             000340
C NP  => NUMBER OF EVALUATION POINTS IN THE AXIAL (X) DIRECTION           000350
30     C TTM  => ARRAY (UP TO 10) OF TIME VALUES FOR FUNCTION EVALUATION      000360
C   (TIME VALUES SHOULD BE IN INCREASING SEQUENCE)
C UMIN  => MINIMUM U-VALUE FOR FUNCTION EVALUATION (SEE MORE)            000370
C UMAY  => MAXIMUM U-VALUE FOR FUNCTION EVALUATION                         000380
C VMIN  => MINIMUM V-VALUE FOR FUNCTION EVALUATION                         000390
C VMAY  => MAXIMUM V-VALUE FOR FUNCTION EVALUATION                         000400
35     C   3) INPUT HAVING TO DO WITH PROGRAM CONTROL, NAMELY:
C   FST  => ERROR VALUE FOR INTERPOLATION OF THE TEMPERATURE             000410
C FUNCTION OUTPUTTED BY TEMP5 AND INTERPOLATED BY IBM SCI. SUB. ALI.      000420
C   MTNT => NUMBER OF TEMPERATURE FUNCTION POINTS TO BE USED IN        000430
C THE INTERPOLATION (DEFAULT=6)                                         000440
40     C   IPRNT => USED TO CONTROL DEBUG OUTPUT (1 CAUSES DEBUG OUTPUT)      000450
C   (2 CAUSES WINDOW TEMPERATURE DISTRIBUTION SUITABLE FOR             000460
C DISPLAY TO BE OUTPUT)
C   NGRMS => NUMBER OF FUNCTION VALUS FOR GAUSSIAN INTEGRATION          000470
C   MODE  => IF MODE=1 THEN THE INTENSITY FUNCTION IS EVALUATED AT       000480
C EQUALLY-SPACED X AND RH00-POINT VALUES; IF MODE=2 IT IS EVALUATED AT    000490
C EQUALLY-SPACED U AND V VALUES.
C   I2  => IF 1 USE TIKRK, IF 2 USE IKTRKP                                000500
45     C   (NOTE THAT IKTRKP SHOULD ONLY BE USED ON THE AXES                 000510
C FOR CONSTANT TEMPERATURE WINDOW)                                       000520
50     C ALL THE ABOVE MENTIONED DATA IS OBTAINED BY TWO CALLS TO THE          000530
C INTERACTIVE INPUT SUBROUTINE GETDATA DESCRIBED IN PML TM-16. IN THE      000540
C FIRST CALL ALL DATA IN THE FIRST CATEGORY IS OBTAINED. IN THE          000550
C SECOND CALL ALL DATA IN THE SECOND AND THIRD CATEGORIES ARE           000560
55     C OBTAINED. AN EXCEPTION TO THIS IS I2 (CONTROLS USE OF             000570
C TIKRK AND IKTRKP) WHICH IS OBTAINED ON THE FIRST CALL TO GETDATA.
C FOR A LISTING OF DEFAULT INPUT DATA IT IS RECOMMENDED THAT           000580
C TIKRK BE RUN INTERACTIVELY UNDER INTERCOM AFTER GIVING THE COMMAND      000590
60     C CONNECT(TAPE4,TAPES).
C THE MAIN OUTPUT OF TIKRK IS A SEQUENCE OF UNFORMATTED RECORDS           000600
C OF INTENSITY VALUES WITH CORRESPONDING DOMAIN VALUES. EACH RECORD      000610
C CONSISTS OF THE FOLLOWING SEQUENCE OF VALUES:
C RECORD NO., NUMBER(MP) OF INTENSITY VALUES IN THE AXIAL DIRECTION.      000620
C AXIAL COORDINATE X OR U, TIME VALUE (T) IN SECONDS, NUMBER (NP)        000630
65     C OF INTENSITY VALUES IN THE RADIAL DIRECTION, MINIMUM RADIAL         000640
C COORDINATE RH001 OR VMIN, MAXIMUM RADIAL COORDINATE RH002 OR           000650
C VMAX, MP INTENSITY VALUES.
C FOR EACH VALUE OF T, NP RECORDS ARE OUTPUTTED CORRESPONDING TO THE      000660
C NP X EVALUATION POINTS. THE RECORD NUMBER RUNS FROM 1 TO NP FOR        000670
C EACH TIME VALUE.
C THERE ARE SIX FILES ASSOCIATED WITH THIS PROGRAM (NOT INCLUDING FILE      000680
C OUTPUT). THE FILES ARE REFERRED TO IN THE PROGRAM AND ASSOCIATED        000690
C SUBROUTINES AS IT3, IT4, IT5, IT6, IT7, IT8. THE FILE VALUES ARE IN TURN      000700
C ASSIGNED TO THE USUAL FORTRAN #TAPEN# BY A DATA STATEMENT AND PROGRAM      000710
70     C
      000720
      000730
      000740
      000750
      000760
      000770
      000780
      000790
      000800
      000810
      000820
      000830

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C ASSOCIATION IT IS NECESSARY TO CHANGE EITHER OR BOTH THE DATA AND      000850
C PROGRAM STATEMENTS.                                                 000860
C THESE FILES SERVE THE FOLLOWING PURPOSES%                           000870
C   IT3 => FILE OUTPUTTED BY PROGRAM TEMPS                           000880
C   IT4 => @INTERACTIVE INPUT FILE (SEE GETDATA)                      000890
C   IT5 => @INTERACTIVE OUTPUT FILE (SEE GETDATA)                      000900
C   IT6 => LISTING OF ALL INPUT PARAMETERS AND DEBUG OUTPUT           000910
C   IT7 => UNFORMATTED INTENSITY VALUES. ALSO MAY BE USED TO INSERT  000920
C   IT8 => UNFORMATTED TEMPERATURE DISTRIBUTION VALUES                000930
C   IT9 => SUITABLE FOR DISPLAY PURPOSES                               000940
C
C   PREASSIGNED DATA IN CATEGORIES 2 AND 3                            000950
C
C   IN ADDITION TO THE ABOVE FACTS, THE USER SHOULD BE AWARE OF TWO      000960
C   PROGRAM @CONSTANTS%. THE FIRST UNDER THE VARIABLE NAME NT IS THE NUM- 000970
C   BER OF TIME VALUES PERMITTED. AT PRESENT THIS IS SET TO 104 (THE      000980
C   DIMENSION OF THE TIME ARRAY TIM). ALSO NOTE THAT ALL THE TIME        000990
C   DEFAULT VALUES ARE ZERO EXCEPT THE FIRST AND THAT THE PROGRAM STOPS    001000
C   AS SOON AS A SUCCEEDING TIME VALUE IS LESS THAN THE PRECEDING       001010
C   TIME VALUE.                                                       001020
C
C   THE SECOND @CONSTANT HAS TO DO WITH THE SIZE OF THE RECORD OUTPUTTED 001030
C   BY TEMPS. THE SUBROUTINE RTAPE3 READS THE TEMPS OUTPUT UNDER THE      001040
C   ASSUMPTION THAT ALL @REAL@ ARRAYS ARE OF DIMENSION 82 AND MAXVAL@      001050
C   ARRAYS ARE OF DIMENSION 22. SEE COMMENTS WITHIN SUBROUTINE RTAPE3.     001060
C   THE INTENSITY FUNCTION IKIRK IS DEFINED EXPLICITLY AS A FUNCTION OF 001070
C   THE NONDIMENSIONAL VARIABLES U AND V AND IMPLICITLY AS A FUNCTION    001080
C   OF NON-DIMENSIONAL TIME TAU THROUGH THE TIME DEPENDANT FUNCTIONS     001090
C   PHI-THETA AND PHI-RHO AS DEFINED IN THE ABOVE REFERENCE. THESE      001100
C   VARIABLES ARE PASSED THROUGH AN ARGUMENT LIST. ALL OF THEM ARE        001110
C   REQUIRED FOR EVALUATION OF IKIRK ARE PASSED THROUGH BLOCK COMMON       001120
C   @PHIRLK. THESE PARAMETERS ARE%                                     001130
C
C   CS1R => @S1R (SEE IKIRK COMMENTS)                                001140
C   CS2R => @S2R "                                         001150
C   CS1P => @S1T "                                         001160
C   CS2T => @S2T "                                         001170
C
C   XS => STARTING ARGUMENT FOR FUNCTIONS F1+F2 (SEE FUNCTUN        001180
C   PHI COMMENTS)                                              001190
C   DX => INTERVAL BETWEEN EQUALLY-SPACED ARGUMENTS OF F1+F2.          001200
C   NF => NUMBER OF VALUES OF F1+F2                                001210
C   MNNT => MINT (SEE INPUT DATA)                                 001220
C   FDP => EPS1 "                                         001230
C
C   F1(20) => HOLDS VALUES OF F1 FROM TEMPS                         001240
C   F2(20) => HOLDS VALUES OF F2 FROM TEMPS                         001250
C   HOLD => STORES PHI-THETA (PHI-RHO AND PHI-THETA ARE EVALUATED     001260
C             SIMULTANEOUSLY)                                         001270
C   A => 1/SQRT(2)/SIG (ALPHA IN THE ABOVE REFERENCE)                 001280
C   KE => WAVE NUMBER                                              001290
C   TLAST => STORES TIME VALUE READ FROM TEMPS RECORD                001300
C   TNEXT => "                                         001310
C   IERR => ERROR INDICATOR FOR RTAPE3 (INDICATES OUT OF RANGE        001320
C             TIME OR OUT OF SEQUENCE TIME)                             001330
C   IP => DEBUG OUTPUT @SWITCH@                                001340
C   MP1 => =NF                                               001350
C   ISW => SWITCH FOR GAUSSIAN INTEGRATION. WHEN ISW=1 THEN THE        001360
C             X-VALUES FOR GAUSSIAN INTEGRATION ARE FOUND.               001370
C   NGAUSS => NUMBER OF POINTS USED IN THE GAUSSIAN INTEGRATION      001380
C             (NOTE THAT IS NGAUSS IS CHANGED THEN THE GAUSSIAN INTEGRATION 001390
C             SUBROUTINE IS NOT RECALLED)
C   RA1) => WINDOW PARTIS                                         001400
C   NP1 => NUMBER OF TEMPERATURE SAMPLES IN AXIAL DIRECTION          001401
C             (USED FOR OUTPUTTING DISPLAY COMPATIBLE                  001402
C             TEMPERATURE DATA)                                         001403
C
C   C3 => CONSTANT TO DIMENSIONALIZE TEMPERATURE DATA              001404
C
C   C1 => CONSTANT USED TO DIMENSIONALIZE TIME FOR                 001405
C             REAL K,IKIRK,LAMDA,MX,KE                                001406
C
C   REAL IKIRK
C   LOGICAL S
C   DIMENSION BUF(100)
C   COMMON/FILES/IT3,IT4,IT5,IT6,IT7,IT8
C   COMMON/PHIRLK/CS1P,CS2P,CS1T,CS2T,XS,DX,NF,MNNT,EPP,F1(20)*
C   +F2(20)*HOLD,A,KE,TLAST,TNEXT,IERR,IP,MP1,ISW,NGAUSS,
C   +RA1,NP1,C3,C1
C   INTEGER DATAIN1(100,3),DATAIN1(100,3)
C   COMMON/BLOCK2/X1,X2,RHOP1,RHOP2,MP,NP,TIM(10),EPS1
C   COMMON/TEMPERATURE DISPLAY
C
C
C

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150      * ,MINT,IPPN1,NGAIS,MODE,UMIN,UMAX,VMIN,VMAX,DUM(20),MSKIP,NSKIP
      COMION/RLOCK1/
      *     11,12,13,14,15,16,17,M,N,MI,NI,ICNT,IU,IO,NO,NMX,TRUN,
      * ICARD,IPPRINT,IPNCH,ITAP3,ITAP4,RHO1,RHO12,ZED1,ZED12,UTAIU,
      * TAU,X,TANOFF,SIG,00,01,    EPS,01(4),MATER,NX,WTA.
      * K,LAMBDA,SIR,SIT,S2P,S2T,
      * DFN,CP,R,EXPEH,PW,R1,71,R2,IPLOT,PROBNO,TICU,XLEN,YLEN,SCALEX,
      * SCALEY1,SCALEY2,XTITLE(5),YTITLE(5),NAME
      * EQUVALENCE (11,DATA1N1),(X0,DATA1N1)
      DATA (DATA1N1(I,1),I=1,92)/7*2,80,20,3*1+0,1+2+11+100,4+6,6,3,
      * 4+0,1,55461,1002,0035,5,5,,1292,2*0,,001,4*0,0,,3*,015,
      * 3HKCL,1,47,4,8E-4,,0553,10,6,-34E-5,,05E-5,,1E-5,-1E-5,1,98,
      * 6,91,1,25A,1H1,24,7,81,11,1,4H7204,,5,20,,9,,30,,1,,1,
      * 10HTIME(SFCON,3HDS),7*1H,10HTEMP-DEGC,10H ABOVE AMR,
      * 3*1H,10HMFAN TEMP,10H ABOVE AMR,3*1H,7HBARRETT,
      * 10RADIAL DIS,10HTANCE,PH0-,4H(CM),1H,1H,10HAXIAL DIST.
      * 10HANCE,7-(CM,1H),1H,1H /
      DATA (DATA1N1(I,1),I=1,92)/2H11,2H12,2H13,2H14,2H15,
      * 2H16,2H17,1HM,1HN,2HM,2H1,4HICNT,2H1U,2H1G,2HN0,3HNMX,
      * 4HIDUN,54ICARD,6HTPPNT,SHIPNCH,SHITAP3,SHITAP4,4HRHO1,
      * 5HRH012,4HZED1,5H7EN12,5H7AU10,5HTAUMX,6HTAU09,3HSIG,
      * 2HQA,2HUN,3HEPS,5HG1(1),5HG1(2),5HG1(3),5HG1(4),5HH1(1),
      * 5HH1(2),5HH1(3),5HH1(4),8HMATERIAL,8HDEF,IND,4HBETA,
      * 9HTHER,COND,6HЛАМРДА,3HS1H,3HS1T,3HS2P,3HS2T,
      * 7HDFNSITY,9HSPEC,HEAT,6HRADIUS,5HEXPER,
      * 3HPRMR,3HRI,2H71#-3H2#-4HPI T?LY,2N,6HPROBNO,4HT1CU,
      * 4HXL,EN,4HYLEN,7HX-SCALE,8HY1-SCALE,8HY2-SCALE,6HXTITLE,
      * 1H2,1H3,1H4,1H5,7HYTITLE1,1H>1H3,1H4,1H5,7HYTITLE2,1H2,
      * 1H3,1H4,1H5,8HOPERATOR,
      * 3HXT1,3HXT2,3HXT3,3HXT4,3HXT5,3HYT1,3HYT2,3HYT3,3HYT4,
      * 3HYT5,
      DATA (DATA1N1(I,1),I=1,92)/22*0,19*1,-1,11*1,-1,1,4*0,
      * -1,6*1,26*1/
      DATA (DATA1N1(I,1),I=1,48)/1500,0,1000,0,0,20,100,100,0,100,0
      * 9*-1,0,0,0,1,0,1,2,2,40,40,0,0,10,0,
      * 10HKIRKHOFF,1,10HNTENS,F,9HFUNCTION,I,1H,1H,10HTIME TN SE.
      * 5HCNDNS,1H,1H,1H,10HNOM-DTMENS,10HTONAL RADI,10HAL DISTANC,
      * 3HE,V,1H,10HNOM-nIMFNS,10HIONAL AXIA,1UHL DISTANCE,2H,0,1H,5,5/
      DATA (DATA1N1(I,2),I=1,48)/2HXA0,2HXA1,2HXA2,5HRH0P1,5HRH0P2,2HMP,
      * 2HND,2H1,2H2,2H3,2H4,2H5,2H6,2H7,2H8,2H9,3HT1U,
      * 4HES1,4HMINT,5HEDNT,5HNGAUS,4HMODE,4HUMAN,4HUMAX,
      * 4HVMIN,4HVMAX,3HST1,3HST2,3HST3,3HST4,3HST5,3HPT1,3HPT2,
      * 3HPT3,3HPT4,3HPT5,3HXT1,3HXT2,3HXT3,3HXT4,3HXT5,3HYT1,
      * 3HYT2,3HVT3,3HYT4,3HYT5,5HMSK1P,5HNSKTP/
      DATA (DATA1N1(I,3),I=1,48)/5* -2*0,11*1,4*0,4*1,20*-1,2*0/
      DATA IT1,IT4,IT5,IT6,IT7,IT8/3,4,5,6,7,8/
      IND1C=0
      S=,E,
      ISW=1
      NT=10
      200      CALI GETDATA(DATA1N,92,4,5,6,3,100,300,IND1C)
      CALI GETDATA(DATA1N,48,4,5,6,7,100,300,IND1C)
      IF (MODE .NE. 1) GOTO 150
      DATA1N1(37,1)=10HDTAL DIS
      DATA1N1(38,1)=10HTANCE,PH0-
      DATA1N1(39,1)=10HDTIME (CM)
      DATA1N1(40,1)=10H
      DATA1N1(42,1)=10HAXIAL DIST
      DATA1N1(43,1)=10HANCE,X (CM)
      DATA1N1(44,1)=1H
      205      WRITE (TT7) DATA1N1
      WRITE (TT7) DATA1N1
      IF (MODE .EQ. 1) S=.T.
      REWIND TT3
      READ (IT3)
      TLAST=TNEXT=0.
      KE=2.28318E4/LAMBDA
      EPD=EPS1
      TP=TPRNT
      NGAIS=NGAUS
      XSP=0.
      DX=1./M
      MNNT=MINT
      M01=M+1
      NF=0P1
      IF (S) GOTO 120
      XMAX=VMAX
      XMIN=VMTN
      GOTO 140
      210      150
      215
      220
      225

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	120	XMIN=RHOP1	002310
		XMAX=RHOP2	002320
230	140	CONTINUE	002330
		A=5/SIG	002340
		C=C*(NX**2+1)/P./NX	002350
		C=C*R*BETA/3.14159/K	002360
235		CS10=C*S1R	002370
		CS20=C*S2R	002380
		CS1T=C*S1T	002390
		CS2T=C*S2T	002400
		RSQR=R*R	002410
240		X0=X0*100.	002420
		X1=X1*100.	002430
		X2=X2*100.	002440
		C1=K/RSQ/DEN/CP	002450
245		DELPH0=(RHOP2-RHOP1)/(AMAX0(1,MP-1))	002460
		DELV0=(VM4X-VMIN)/(AMAX0(1,MP-1))	002480
		DELI0=(UMAX-XMIN)/(AMAX0(1,MP-1))	002490
		RAD=R	002500
		NP1=N+1	002510
250		C3=C/R	002520
		X0I=1/X0	002530
		NREC=0	002540
		IT=1	002550
		TR=T=TIM(1)	002560
255		IF (T .LT. 0.) GOTO 2000	002570
		IF (IP,E0,2) WRITE(TTB) DATATN	002580
	1000	T=T+C1	002590
		WRITE(IT5,2) T	002600
		IF (T .GT. TAUMX) GOTO 2000	002610
260		XIT=X1	002620
		XII=1/XIT	002630
		U=UMIN	002640
		DO 100 I=1,NP	002650
265		CX=(X0*XII)**2	002660
		IF (S) II=KE*RSQ*(X0I-XII)	002670
		RHOP0=RHOP1	002680
		V=VMIN	002690
		DO 110 J=1,MP	002700
		IF (S) V=KE*R*XII*RHOP	002710
270	220	GOTO (220+200) I2	002720
	220	BUF(J)=CX*IKIRK0(II,V,T)	002730
		GOTO 210	002740
	200	BUF(J)=CX*IKIRK(U,V,T)	002750
	210	RHOD=RHOP+DEL_RHO	002760
275		V=V+DELV	002770
	110	CONTINUE	002774
		P=U	002776
		IF (S) P=XIT	002780
280		WRITE(TTB) I,NP,P,TR,MP,XMIN,XMAX,(BUF(J),J=1,MP)	002790
		CALL_PRT(RUF,MODE,I,TT,MP,NP,MSKIP,NSKIP,RHOP1,	002800
		+DEL_RHO,VMIN,DELV,XIT,U,TR,T,TT)	002810
		NREC=NREC+1	002820
		XIT=XIT+DELX	002830
		XII=1/XIT	002840
285		U=U+DELU	002850
	100	CONTINUE	002860
		IT=IT+1	002870
		IF (IT .GT. NT) GOTO 2000	002880
		TR=TR+TIM(IT)	002890
290		IF (T .GT. TIM(IT-1)) GOTO 1000	002900
	2000	WRITE(TTB) NREC	002910
	1	FORMAT(IX,* THE NUMBER OF RECORDS IS-,I10)	002920
	2	FORMAT(IX,* NEW VALUE OF IAU IS*,E13.5)	002930
	3	FORMAT(IX,I6.4E12.4)	002940
	4	FORMAT(IX,4E13.5)	002950
295	5	FORMAT(IX,I6.4G12.4,7(/,5X,5G13.5))	002960
		END	

B.2 Function IKIRK

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1      REAL FUNCTION IKIRK(U,V,T)                                0J2970
C FUNCTION IKIRK IS THE KIRKHOFF INTENSITY FUNCTION DESCRIBED IN
C -BENDOW,B. AND GIANTIN,D. OPTICAL PERFORMANCE EVALUATION OF
C INFRARED TRANSMITTING WINDOWS AFTRL-72-0565. ASSUMING A GAUSSIAN
C SHAPED UNPOLARIZED SOURCE. THE INTENSITY FUNCTION CAN BE WRITTEN*
C IKIRK(U,V)=?((A!2/(1-EXP(-A!2)))!2*(1/(0,1,DX))(FW*FX))!2+
C           IT(0,1,DX)(FW*FY))!2
C WHERE*
C   FW(V!)=EXP(-(A*X)!2)*EXP(-I*U*X)!2/2)                0J2990
10    FX(V,V)=V*J0(X*V)*EXP(I*K*PHIR(X))-FZ(X,V)          0J3000
C   FY(V,V)=V*J0(X*V)*EXP(I*K*PHIT(X))+FZ(X,V)          0J3010
C   FZ(V,V)=|1(X*V)*(EXP(I*K*PHIR(X))-EXP(I*K*PHIT(X)))/(V) 0J3020
C   A=1/SQRT(2)/SIG**2                                     0J3030
C   K=WAVE NO. (OMEGA/C)                                    0J3040
15    C NOTATION*
C     ! => EXPONENTIATION
C     I => IMAGINARY
C     I(0,1,DX)() MEANS INTEGRATION OF THE FUNCTION WITHIN (1 W.R.T.X
C     OVER THE INTERVAL (0,1).
20    C I0 AND I1 ARE BESSEL FUNCTIONS OF THE FIRST KIND,ZEROTH AND FIRST
C ORDER RESPECTIVELY.
C PHIR(X) AND PHIT(X) ARE THE FUNCTIONS PHI-SUPERSCRIPT-RHO AND PHI-
C SUPERSCRIPT-T-THETA RESPECTIVELY IN THE ABOVE REFERENCE.        0J3100
C THESE FUNCTIONS ARE GIVEN BY*
25    C PHIR(X)=C*S10*F1(X)+4*C*S2R*F2(X)                      0J3110
C PHIT(X)=C*S1T*F1(X)+4*C*S2T*F2(X)                      0J3120
C WHERE*
C   C=R1*B0*RFTA/KT                                         0J3130
C   R=WINDOW RADIUS (CM)                                     0J3140
30    C D=MEAN INCIDENT POWER DENSITY (WATTS/CM!2)            0J3150
C   RFTA=BULK ABSORPTION COEFFICIENT (1/CM)                  0J3160
C   KT= THERMAL CONDUCTIVITY (WATTS/CM DEG)                 0J3170
C   S1R,S2R,S1T,S2T ARE MATERIAL CONSTANTS DEFINED IN THE ABOVE REF. 0J3180
C   F1,F2 ARE THE FUNCTIONS DELTRAR-PRIME(X) AND             0J3190
35    C (1/X!2)I(0,X,DS) (DELTRAR-PRIME(S))
C GIVEN IN THE ABOVE REFERENCE AND WHICH ARE PROVIDED AT SELECTED
C ARGUMENTS BY PROGRAM ATTEMPS*.                                0J3200
C *****                                                       0J3210
C COMMON/PHTBLK/CS1D,CS2R,CS1T,CS2T,XS,NZ,NF,MINT,EPS,FL(2nU), 0J3220
40    *F2(200),HOLD,A,K ,TLAST,TNEXT,IERR,IP,MP1,ISW,N,          0J3230
C RAD,NP1,C3,C1                                              0J3240
C COMMON/TFILES/IT3,IT4,IT5,IT6,IT7,IT8                     0J3250
C COMPLEX Q1,EXPR,EXPT,FX,FY,FZ,FW                         0J3260
45    C RFAI J0,I1                                           0J3270
C RFAI K
C DTENSION XA(100),YR(100),YI(100),ZR(100),ZI(100)       0J3280
C A2=A2
C IF (A2 .GT. 220.) 1020+1040                               0J3290
50    1020 CONST=2.*A2*A2                                     0J3300
C GOTO 1040
1030 CONST=2.*((A2/(1.-EXP(-A2)))**2)                   0J3310
1040 UN2=U/2Fn
C IF ISW=1 THEN THE ARRAY OF POINTS FOR GAUSSIAN INTEGRATION
C M ST BE FOUND
55    C M ST BE FOUND
C GOTO (1050,1060) TSW                                     0J3320
1050 TSW=2
C CALL, DQG24A(0E0,1F0,XA)
C IF (IP .EQ. 1) WRITF(IT6+1) (XA(I),I=1,N)              0J3330
1060 CALL RTAPE3(T)
C IF (IERR .NE. 0) GOTO 2000
DO 100 I=1,N
X=XA(I)
X2=X*X
XV=X*V
65    FW=EXP(-A2*X2)*CEXP(CMPLX(UEN,-UN2*X2))
EXPO=CEXP(CMPLX(0E0,K*PHI(X)))
EXPT=CEXP(CMPLX(0E0,K*HOLD))
IF (V .EQ. 0.) FZ=(EXPR-EXPT)*X/2.
IF (V .NE. 0.) FZ=(EXPR-EXPT)*J1(XV)/V
Q1=X*J0(XV)
FX=Q1*EXPR-FZ
FY=Q1*EXPT+FZ
Q1=FW*FX
YR(T)=REAL(Q1)                                             0J3340
70    0J3350
0J3360
0J3370
0J3380
0J3390
0J3400
0J3410
0J3420
0J3430
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0J3650
0J3660
0J3670
0J3680
0J3690
0J3700
0J3710

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75	YT(T)=ATMAG(01)	003720
	01=F*FY	003730
	ZR(T)=REAL(01)	003740
	ZI(T)=ATMAG(01)	003750
100	CONTINUE	003760
80	1 FORMAT(5(X,G12.5))	003770
	CALI DOG24R(0E0,1F0,YP,YRI)	003780
	CALI DOG24R(0E0,1F0,YT,ZII)	003790
	CALI DOG24R(0E0,1F0,ZP,ZRI)	003800
	CALI DOG24R(0E0,1F0,ZI,ZII)	003810
85	TR(DK=CONST*(YRT*YRT+YII*YII+ZRI*ZRI+ZII*ZII))	003820
2000	RETURN	003830
	END	003840

B.3 Function PHI

1	FUNCTION PHI(X)	003850
	C IF SNT=.F. THEN PHIP(X)=C*S1R*F1(X)+4*S2R*F2(X) IS FOUND	003860
	C IF SNT=.T. THEN PHIT(X)=C*S1T*F1(X)+C*S2T*F2(X) IS FOUND	003870
5	C WHERE C=B!3*D0*BETA/KAPPA (SEE CALLING SUBROUTINE)	003880
	C THE PROGRAM IS DESIGNED TO BE CALLED IN THE ORDER .F., .T. FOR A	003890
	C GIVEN VALUE OF X IN ORDER TO ELIMINATE DOUBLE CALLS TO THE INTERPOLATI	003900
	C ROUTINE	003910
	C THE ARRAYS F1,F2 CONTAIN THE FUNCTION VALUES TO BE INTERPOLATED*	003920
10	C F1(1=X1),F1(2=X2),...,F1(NF). ETC AS PROVIDED BY TEMPS.	003930
	C THE IRM SCI. SUB. ATSE (P,PS1) RETURNS MINT FUNCTION VALUES AND	003940
	C ARGUMENTS TO BE USED FOR INTERPOLATION IN ARRAYS ARG,VAL RESPECTIVELY.	003950
	C GIVEN THE ARGUMENT X,ETC.	003960
	C (THE ARGUMENT ICOL IN ATSE IS 1 IF THE FUNCTION IS STORED IN A	003970
	C 1-DIMENSIONAL ARRAY)	003980
15	C THE IRM SCI. SUB. ALTI(P,P41) DOES AITKEN-LAGRANGE INTERPOLATION	003990
	C ON (ARG,VAL) AND RETURNS THE RESULTING VALUE Y. EPS IS AN ABSOLUTE	004000
	C ERROR FIGURE AND IER IS AN ERROR FLAG.	004010
	COMMON/PHTALK/CS1P,CS2P,CS1T,CS2T,XS,NX,NF,MINT,EPS,F1(200),	004020
	+F2(200),HOLD,A,KE,TLAST,TNEXT,IERR,IP,MP1,ISW,N,	004030
20	+RAD,NP1,C3,C1	004040
	C HOLD IS USED TO STORE PHI(.T.,X)	004050
	DIMENSION ARG(20),VAL(20)	004060
25	1010 CALI ATSE(X,XS,IX,F1,NF,1,ARG,VAL,MINT)	004070
	CALI ALTI(X,ARG,VAL,Y1,MINT,EPS,IER)	004080
	CALI ATSE(X,XS,NX,F2,NF,1,ARG,VAL,MINT)	004090
	CALI ALTI(X,ARG,VAL,Y2,MINT,EPS,IER)	004100
	PHI=CS1R*Y1+4E0*CS2P*Y2	004110
	HOLD=S1T*Y1+4E1*S2T*Y2	004120
30	2000 RETURN	004130
	END	004140

B.4 Function J0

```

1      REAL FUNCTION J0(X)                                004150
C J0 IS THE BESSSEL FUNCTION OF THE FIRST KIND,ZEROTH ORDER. SEE
C HANDBOOK OF MATHEMATICAL FUNCTIONS-AMS 55. FOR VALUES OF THE ARGUMENT
C I=5 EQUATION 9.1.12 IS USED. OTHERWISE 9.4.3 IS USED.          004160
5      DIMENSION FACT(20)                               004170
      DATA MT/1/
      IF(X.GT.5.) GO TO 1                               004180
      IF(.T.NE.0) GO TO 2                               004190
      MT=1
      FACT(1)=1.0                                         004200
10     DO 3 I=2,20                                     004210
      FACT(I)=FACT(I-1)*FLOAT(I*1)                     004220
      3 CONTINUE                                         004230
      DO 4 I=2,20                                     004240
      FACT(I)=1.0/FACT(I)                            004250
4      CONTINUE                                         004260
2      CONTINUE                                         004270
      ANSP=0.0                                         004280
      ANSN=0.0                                         004290
20     ARG=0.25*X*X                                    004300
      ARGII=ARG                                         004310
      DO 5 T=1.19*2                                    004320
      ANSN=ANSN+ARGU*FACT(T)                         004330
      J=1,1
      ARGII=ARGII*ARG                                 004340
      ANSP=ANSP+ARGU*FACT(1)                         004350
      ARGII=ARGII*ARG                                 004360
25     5 CONTINUE                                         004370
      J=1.0+(ANSP-ANSN)                           004380
      RETURN                                            004390
30     1 CONTINUE                                         004400
      TX=3.0/X                                         004410
      F7=.79788456-.00000077*TOX-.0055274*TOX**2-.00009512*TOX**3+
1.00137237*TOX**4-.00072805*TOX**5+.00014476*TOX**6           004420
35     TH2=X-.79539816-.04166397*TOX-.00003954*TOX**2+.00262573*TOX**3-
1.00154125*TOX**4-.00029333*TOX**5+.00013558*TOX**6           004430
      J0=FZ*COS(THZ)/SQRT(X)                         004440
      RETURN                                            004450
      END                                              004460

```

B.5 Function J1

```

1      REAL FUNCTION J1(X)                                004540
C J1 IS THE BESSSEL FUNCTION OF THE FIRST KIND,FIRST ORDER. SEE
C HANDBOOK OF MATHEMATICAL FUNCTIONS-AMS 55. FOR VALUES OF THE
C ARGUMENT [=1] EQUATION 9.1.10 IS USED. OTHERWISE 9.4.4 IS USED. 004550
5      DIMENSION FACT(20)                               004560
      DATA MT/1/
      IF(X.GT.10.) GO TO 1                            004570
      IF(.T.NE.0) GO TO 2                            004580
      MT=1
      FACT(1)=2.0                                       004590
10     DO 3 I=2,20                                     004600
      FACT(I)=FACT(I-1)*FLOAT(I*(I+1))               004610
      3 CONTINUE                                         004620
      DO 4 I=1,20                                     004630
      FACT(I)=1.0/FACT(I)                            004640
4      CONTINUE                                         004650
2      CONTINUE                                         004660
      ANSP=0.0                                         004670
      ANSN=0.0                                         004680
15     4 CONTINUE                                         004690
      2 CONTINUE                                         004700
      RETURN                                            004710
      END                                              004720

```

```

        ARGF=0.5*x          004730
        ARG=0.25*x*x        004740
        ARGH=ARG             004750
        DO 5 I=1,19,2       004760
        ANSN=ANSN+ARGU*FACT(T)
        5=I+1                004770
        ARGH=ARGH+ARG         004780
        ANSH=ANSH+ARGU*FACT(T)
        ARGH=ARGH+ARG         004790
        5 CONTINUE           004800
        JI=ARGS*(1.0+(ANSP-ANSN)) 004810
        RFT=RN               004820
        1 CONTINUE           004830
        TX=3.0/x             004840
        F1=.79789456+.00000156*TOX+.01659667*TOX**2+.00017105*TOX**3 004850
        1=.0*249511*TOX**4+.10113653*TOX**5-.00020033*TOX**6 004860
        TH1=X-2.75619449+.12499612*TOX+.00005650*TOX**2-.00637870*TOX**3 004870
        1+.0*074348*TOX**4+.000079824*TOX**5-.00029166*TOX**6 004880
        JI=J1*COS(TH1)/SQRT(X) 004890
        RETURN               004900
        49 ENDO               004910
                                         004920
                                         004930

```

B.6 Subroutine RTAPE3

```

1      SUBROUTINE RTAPE3(T)
004940
COMMON/PHTRLK/C1,C2P,C5T,CS2T,XS,NX,NF,MINT,EPS,F1(200)*
004950
+F2(200),HOLD,A,KF,TLAST,TNEXT,IERR,IP,MP1,ISW,N,
004960
+RAI,NU1,C1
004970
5      COMMON/TFILES/IT3,IT4,IT5,IT6,IT7,IT8
004980
DIMENSION F1M(82),F2M(82),F1P(82),F2P(82),RFIN(82),ZFIN(22)*
004990
+IPT,IP(82,22),UFINM(82,22)
005000
DATA ISW/0/
005010
C RTAPE3 CAN BE USED AS A GENERAL PURPOSE SUBROUTINE FOR LINEARLY
005020
C INTERPOLATING FUNCTION VALUES BETWEEN RECORDS, I.E. ASSUME
005030
C RECORD N INCLUDES THE INFORMATION TN,F(1:TN),F(2:TN),...,*
005040
C AND RECORD N+1 INCLUDES TN+1,F(1:IN+1),F(2:TN+1),...,*
005050
C THEN IF TN<=T<=TN+1 IS GIVEN, THE QUANTITIES F(1:T),F(2:T),...,*
005060
C ARE RETURNED WHERE*
005070
15     C F(1:T)=F(1:TN)+C*(F(1:TN+1)-F(1:IN)): C=(T-TN)/(TN+1-TN), ETC.
005080
C IT IS ASSUMED THAT THE PARAMETER I INCREASES WITH INCREASING RECORD
005090
C NUMBER AND NO FILE DUMPINGS ARE PERMITTED. I.E. RTAPE3 SHOULD BE CALLED
005100
C W/ TN INCREASING VALUES OF T ONLY.
005110
C RTAPE3 RECOGNIZES TWO ERROR CONDITIONS WHICH SHOULD BE CHECKED FOR IN
005120
C THE CALLING PROGRAM. IF IERR=0 THEN NO ERROR HAS OCCURRED. IF IERR=1
005130
C THEN THE TIME VALUE IS LESS THAN THE TIME VALUE OF THE PRECEEFING CALL
005140
C TO RTAPE3. IF IERR=2 THEN THE TIME VALUE IS GREATER THAN THE TIME VALUE
005150
C ASSOCIATED WITH THE LAST INPUT RECORD.
005160
C T THE PRESENT VERSION OF RTAPE3 EACH OUTPUT RECORD (FROM TEMP5) IS
005170
C ASSUMED TO BE IN THE FORM
005180
C   NF,ZFIN,RFIN(82),ZFIN(22),UFIN(82,22),F1(82),F2(82)
005190
C WHERE ZFIN IS THE TIME VALUE AND F1(82),F2(82) ARE THE DESIRFU
005200
C FUNCTION VALUES CORRESPONDING TO FIN.
005210
C RTAPE3 ALSO OUTPUTS THE DIMENSIONALIZED (AND LINEARLY INTERPOLATED)
005220
C IN TIME1 WINDOW TEMPERATURE FUNCTIN IN A FORM SUITABLE FOR USE WITH
005230
C DISPLAY. PROVIDED IPTNT=2.
005240
        IERD=1
005250
        T=T/C1
005255
        IF (ISW) 1115,1100
005260
35     1100 ISW=1
005270
        READ(IT3),NG,TLAST,ZFIN,UFINM,F1M,F2M
005280
        TT=TLAST
005290
        QMIN=OF(TN(1))*RAI
005300
        QMAX=OF(TN(MP1))*RAI
005310
        IF (EOF(IT3)) 1110,1120
005320
        1110 IERR=2
005330
        GOTO 2000
005340
        1120 IF (T-TLAST) 1130,1140,1140
005350
        1130 IERR=1
005360

```

```

45      GOTO 2000          005370
1140 READ(17) NG,TNEXT,PFIN,ZFIN,UFINP,F1P,F2P 005380
115 IF (T .LT. TT) 1000-1010 005400
1000 IERR=1           005410
                  GOTO 2000 005420
50      C TF T .EQ. LAST THEN NOTHING MORE TO DO 005430
1010 IF (T .EQ. TT) GOTO 2000 005440
C TF T .LT. TNEXT THEN A PFAID IS NOT REQUIRED 005450
      IF (T .LT. TNEXT) GOTO 1020 005460
1030 READ(17) NG,TLAST,PFIN,ZFIN,UFINM,F1M,F2M 005470
      IF (EOF(17)) 1040-1050 005480
1040 IERR=2           005490
                  GOTO 2000 005500
1050 IF (T .LE. TLAST) GOTO 1080          005510
      READ(17) NG,TNEXT,PFIN,ZFIN,UFINP,F1P,F2P 005520
      IF (EOF(17)) 1060-1070 005530
1060 IERR=2           005540
                  GOTO 2000 005550
1070 IF (T .LE. TNEXT) GOTO 1020          005560
                  GOTO 1030 005570
65      1020 C=(T-TLAST)/(TNEXT-TLAST)          005580
      DO 100 I=1,MP1           005590
      F1(T)=F1M(I)+C*(F1P(T)-F1M(I)) 005600
      F2(T)=F2M(I)+C*(F2P(T)-F2M(I)) 005610
100   CONTINUE          005620
      GOTO(2000,120) IP          005630
120   DO 130 I=1,NP1           005640
      U=RAD*ZFIN(I)           005650
      DO 140 J=1,MP1           005660
      PFIN(J)=C3*((UFINM(J,T)+C*(UFINP(J,I)-UFINM(J,I))) 005670
140   CONTINUE          005680
      WPTE(17)=I,NP1,II,TM,MP1,RMTN,RMAX,(PFIN(J),J=1,MP1) 005690
130   CONTINUE          005700
      GOTO 2000          005710
1080 TTTEMP=TLAST          005720
      TLAST=TNEXT          005730
      TNEXT=TTTEMP          005740
      DO 110 I=1,MP1           005750
      FT=F1M(I)           005760
      F1M(I)=F1P(I)           005770
      F1P(I)=FT           005780
      FT=F2M(I)           005790
      F2M(I)=F2P(I)           005800
      F2P(I)=FT           005810
110   CONTINUE          005820
      GOTO(1020,150) IP          005830
150   DO 160 I=1,NP1           005840
      DO 160 J=1,MP1           005850
      FT=(FINM(J,I))        005860
      UFINM(J,T)=UFINP(I,T) 005870
      UFINP(J,T)=FT           005880
160   CONTINUE          005890
      GOTO 1020          005900
2000 TT=T               005910
      RETURN             005920
      END                005930

```

B.7 Subroutine ALI

```

1      SUBROUTINE ALI(X,ARG,VAL,Y,NDIM,EPS,IER)          005940
C
C.....*****.....*****.....*****.....*****.....*****.
5      C
5      C
5      C
5      C      SUBROUTINE ALI
5      C
5      C
5      C      PURPOSE
5      C      TO INTERPOLATE FUNCTION VALUE Y FOR A GIVEN ARGUMENT VALUE
5      C      X USING A GIVEN TABLE (ARG,VAL) OF ARGUMENT AND FUNCTION
5      C      VALUES.
10     C
10     C      USAGE
10     C      CALL ALI (X,ARG,VAL,Y,NDIM,EPS,IER)
15     C
15     C      DESCRIPTION OF PARAMETERS
15     C      X      - THE ARGUMENT VALUE SPECIFIED BY INPUT.
15     C      ARG     - THE INPUT VECTOR (DIMENSION NDIM) OF ARGUMENT
15     C      VALUES OF THE TABLE (NOT DESTROYED).
15     C      VAL     - THE INPUT VECTOR (DIMENSION NDIM) OF FUNCTION
15     C      VALUES OF THE TABLE (DESTROYED).
20     C      Y      - THE RESULTING INTERPOLATED FUNCTION VALUE.
20     C
20     C      NDTM   - AN INPUT VALUE WHICH SPECIFIES THE NUMBER OF
20     C      POINTS IN TABLE (ARG,VAL).
25     C      EPS    - AN INPUT CONSTANT WHICH IS USED AS UPPER ROUND
25     C      FOR THE ABSOLUTE ERROR.
25     C      IER    - A RESULTING ERROR PARAMETER.
25     C
25     C
30     C      REMARKS
30     C
30     C      (1) TABLE (ARG,VAL) SHOULD REPRESENT A SINGLE-VALUED
30     C      FUNCTION AND SHOULD BE STORED IN SUCH A WAY, THAT THE
30     C      DISTANCES ABS(ARG(I)-X) INCREASE WITH INCREASING
30     C      SUBSCRIPT I, TO GENERATE THIS ORDER IN TABLE (ARG,VAL).
30     C      SUBROUTINES ATSG, AISM OR ATSE COULD BE USED IN A
30     C      PREVIOUS STAGE.
35     C
35     C      (2) NO ACTION BEYOND ERROR MESSAGE IN CASE NDIM LESS
35     C      THAN 1.
35     C
35     C      (3) INTERPOLATION IS TERMINATED EITHER IF THE DIFFERENCE
35     C      BETWEEN TWO SUCCESSIVE INTERPOLATED VALUES IS
35     C      ABSOLUTELY LESS THAN TOLERANCE EPS, OR IF THE ABSOLUTE
35     C      VALUE OF THIS DIFFERENCE STOPS DIMINISHING, OR AFTER
35     C      (NDIM-1) STEPS. FURTHER IT IS TERMINATED IF THE
35     C      PROCEDURE DISCOVERS TWO ARGUMENT VALUES IN VECTOR ARG
35     C      WHICH ARE IDENTICAL. DEPENDENT ON THESE FOUR CASES,
35     C      ERROR PARAMETER IER IS CODED IN THE FOLLOWING FORM
35     C
35     C      IER=0 - IT WAS POSSIBLE TO REACH THE REQUIRED
35     C      ACCURACY (NO ERROR).
35     C      IER=1 - IT WAS IMPOSSIBLE TO REACH THE REQUIRED
35     C      ACCURACY BECAUSE OF ROUNDING ERRORS.
35     C
35     C      IER=2 - IT WAS IMPOSSIBLE TO CHECK ACCURACY BECAUSE
35     C      NDIM IS LESS THAN 2, OR THE REQUIRED ACCURACY
35     C      COULD NOT BE REACHED BY MEANS OF THE GIVEN
35     C      TABLE. NDIM SHOULD BE INCREASED.
35     C
35     C      IER=3 - THE PROCEDURE DISCOVERED TWO ARGUMENT VALUES
35     C      IN VECTOR ARG WHICH ARE IDENTICAL.
50     C
50     C      SUBROUTINES AND FUNCTION SUBPROGRAMS REQUIRED
50     C
50     C      NONE.
50     C
50     C
50     C      METHOD
50     C      INTERPOLATION IS DONE BY MEANS OF ATKENS SCHEME OF
50     C      LAGRANGE INTERPOLATION. ON RETURN Y CONTAINS AN INTERPOLATED
50     C
55     C      FUNCTION VALUE AT POINT X, WHICH IS IN THE SENSE OF REMARK
55     C      (3) OPTIMAL WITH RESPECT TO GIVEN TABLE. FOR REFERENCE, SEE
55     C      F. WILDEBRAND, INTRODUCTION TO NUMERICAL ANALYSIS,
55     C      MCGRAW-HILL, NEW YORK/TORONTO/LONDON, 1958, PP. 47-50.
55     C
55     C.....*****.....*****.....*****.....*****.....*****.
70     C
70     C      DIMENSION ARG(1),VAL(1)
70     C      IER=2

```

```

75      DFLT2=0.          006680
        IF(NDIM-1)9.7.1 006690
C       START OF ATTKEN-LOOP 006700
1      DO 4 J=2,NDIM 006710
C       DFLT1=DFLT2 006720
C       TEND=J-1 006730
2      DO 3 I=1,TEND 006740
C       H=ARG(I)-ARG(J) 006750
C       TF((I-2)*13.2 006760
3      2 VAL(J)=(VAL(I)*(X-ARG(I))-VAL(J)*(X-ARG(I)))/H 006770
C       DFLT2=ABS(VAL(J)-VAL(TEND)) 006780
C       TF((I-2)*16.6.3 006790
4      3 TF(DFLT2-EPS)10.10.4 006800
C       4 TF((I-5)*16.5.5 006810
5      5 IF((DFLT2-DELT1)6.11.1) 006820
90     6 CONTINUE 006830
C       END OF ATTKEN-LOOP 006840
C
7      J=NDIM 006850
95     8 Y=VAL(J) 006860
9     9 RETURN 006870
C       THERE IS SUFFICIENT ACCURACY WITHIN NDIM-1 ITERATION STEPS 006880
10    10 TER=0 006890
C       GOTO 8 006900
100   11 TEST VALUE DELT2 STARTS OSCILLATING 006910
C
105   12 TER=1 006920
C       GOTO 8 006930
C       THERE ARE TWO IDENTICAL ARGUMENT VALUES IN VECTOR ARG 006940
13    13 TER=3 006950
C       GOTO 12 006960
110   END 006970

```

B.8 Subroutine ATSE

```

1      SUBROUTINE ATSE (X,ZS,DZ,F,IRW,ICOL,ARG,VAL,NDIM) 007050
C       ..... 007060
C
5      C       SUBROUTINE ATSE 007070
C
C       PURPOSE 007080
C       NDIM POINTS OF A GIVEN TABLE WITH EQUIDISTANT ARGUMENTS ARE 007090
10     C       SELECTED AND ORDERED SUCH THAT 007100
C       ABS(ARG(I)-Y).GE.ABS(ARG(J)-X) TF I.GT.J. 007110
C
C       USAGE 007120
C       CALL ATSE (X,ZS,DZ,F,IRW,ICOL,ARG,VAL,NDIM) 007130
15     C
C       DESCRIPTION OF PARAMETERS 007140
C       X      - THE SEARCH ARGUMENT. 007150
C       ZS     - THE STARTING VALUE OF ARGUMENTS. 007160
C       DZ     - THE INCREMENT OF ARGUMENT VALUES. 007170
20     C       F      - IN CASE ICOL=1, F IS THE VECTOR OF FUNCTION VALUES 007180
C                   (DIMENSION IRW). 007190
C                   IN CASE ICOL>1, F IS AN IRW BY 2 MATRIX, THE FIRST 007200
C                   COLUMN SPECIFIES THE VECTOR OF FUNCTION VALUES AND 007210
C                   THE SECOND THE VECTOR OF DERIVATIVES. 007220
25     C       IRW    - THE DIMENSION OF EACH COLUMN IN MATRIX F. 007230
C       ICOL   - THE NUMBER OF COLUMNS IN F (I.E. 1 OR 2). 007240
C       ARG    - THE RESULTING VECTOR OF SELECTED AND ORDERED 007250
C                   ARGUMENT VALUES (DIMENSION NDIM). 007260
C       VAL    - THE RESULTING VECTOR OF SELECTED FUNCTION VALUES 007270

```

```

30      C      (DIMENSION NDIM) IN CASE ICOL=1. IN CASE TCOL=2,  

C      VAL IS THE VECTOR OF FUNCTION AND DERIVATIVE VALUES  

C      (DIMENSION 2*NDIM) WHICH ARE STORED IN Pairs (I.E.  

C      EACH FUNCTION VALUE IS FOLLOWED BY ITS DERIVATIVE  

C      VALUE).
35      C      NDIM - THE NUMBER OF POINTS WHICH MUST BE SELECTED OUT OF  

C      THE GIVEN TABLE.
C
C      REMARKS
C      NO ACTION IN CASE IROW LESS THAN 1.
40      C      IF INPUT VALUE NDIM IS GREATER THAN IROW, THE PROGRAM  

C      SELECTS ONLY A MAXIMUM TABLE OF IROW POINTS. THEREFORE THE  

C      USER OUGHT TO CHECK CORRESPONDENCE BETWEEN TABLE (ARG,VAL)  

C      AND ITS DIMENSION BY COMPARISON OF NDIM AND IROW. IN ORDER  

C      TO GET CORRECT RESULTS IN FURTHER WORK WITH TABLE (ARG,VAL).  

C      THIS TEST MAY BE DONE BEFORE OR AFTER CALLING  

C      SUBROUTINE ATSF.
45      C
C      SUBROUTINE ATSF ESPECIALLY CAN BE USED FOR GENERATING THE  

C      TABLE (ARG,VAL) NEEDED IN SUBROUTINES ALI, AHI, AND ACFI.
50      C
C      SUBROUTINES AND FUNCTION SUBPROGRAMS REQUIRED
C      NONE
C
C      METHOD
C      SELECTION IS DONE BY COMPUTING THE SUBSCRIPT J OF THAT  

C      ARGUMENT, WHICH IS NEXT TO X.  

C      Afterwards NEIGHBOURING ARGUMENT VALUES ARE TESTED AND  

C      SELECTED IN THE ABOVE SENSE.
60      C      .....
C
C      DIMENSION F(1),ARG(1),VAL(1)
65      C      IF(IROW-1)*DZ+1
C
C      CASE DZ=0 IS CHECKED OUT
1  IF(DZ)=0,17*2
2  N=NDIM
70      C
C      IF N IS GREATER THAN IROW, N IS SET EQUAL TO IROW.
1  IF(N-IROW)=4,4*3
3  N=IROW
75      C
C      COMPUTATION OF STARTING SUBSCRIPT J.
4  J=(Y-ZS)/DZ+1.5
5  IF(J)=5,5*6
5  J=1
6  IF(I-IROW)=8,8*7
7  J=IROW
80      C
C      GENERATION OF TABLE ARG,VAL IN CASE DZ,NE,0.
8  IT=I
9  JL=*
10  JR=0
DO 16 I=1,N
    ARG(I)=75+FLOAT(IT-1)*DZ
    IF(TCOL=2)=9,9*10
9  VAL(I)=F(IT)
    GOTO 11
10  VAL(2*I-1)=F(IT)
    IT=IT+IROW
    VAL(2*I)=F(IT)
11  IF((I-JR-IROW)=12,15*12
12  IF((I-JL-1)=13,14*13
13  IF((ARG(I)-X)*DZ)=14,15*15
14  JR=JR+1
    IT=IT+JR
    GOTO 16
15  JL=JL+1
    IT=IT-JL
16  CONTINUE
    RETURN

```

105	C CASE DZ=^	008100
	17 ARG(1)=ZS	008110
	VAL(1)=F(1)	008120
	TF(1)COL=?)19,19,18	008130
110	18 VAL(2)=F(2)	008140
	19 RETURN	008150
	END	008160

B.9 Subroutine DQG24A

1	SUBROUTINE DQG24A(XL,XU,XA)	008170
	008180
	008190
5	CURSUBROUTINE DQG24	008200
	008210
	PURPOSE	008220
	TO COMPUTE INTEGRAL(FCT(X)). SUMMED OVER X FROM XL TO XU)	008230
	008240
10	USAGE	008250
	CALL DQG24 (XL,XU,FCT,Y)	008260
	PARAMETER FCT PREFERENCES AN EXTERNAL STATEMENT	008270
	008280
	008290
	DESCRIPTION OF PARAMETERS	008300
15	XL - DOUBLE PRECISION LOWER BOUND OF THE INTERVAL.	008310
	XU - DOUBLE PRECISION UPPER BOUND OF THE INTERVAL.	008320
	FCT - THE NAME OF AN EXTERNAL DOUBLE PRECISION FUNCTION	008330
	SUBPROGRAM USEU.	008340
	Y - THE RESULTING DOUBLE PRECISION INTEGRAL VALUE.	008350
20	REMARKS	008360
	NONE	008370
	008380
	008390
25	SUBROUTINES AND FUNCTION SUBPROGRAMS REQUIRED	008400
	THE EXTERNAL DOUBLE PRECISION FUNCTION SUBPROGRAM FCT(X)	008410
	MUST BE FURNISHED BY THE USER.	008420
	008430
30	METHOD	008440
	EVALUATION IS DONE BY MEANS OF 24-POINT GAUSS QUADRATURE	008450
	FORMULA, WHICH INTEGRATES POLYNOMIALS UP TO DEGREE 47	008460
	EXACTLY. FOR REFERENCE, SEE	008470
	V.T.KRYLOV, APPROXIMATE CALCULATION OF INTEGRALS,	008480
	MACMILLAN, NEW YORK/LONDON, 1962, PP.100-111 AND 317-340.	008490
35	008500
	008510
	008520
	008530
	008540
	DTIMENSION XA(1)	008550
40	A=.RD0*(XU-XL)	008560
	R=XU-XL	008570
	C=.4975916099985106800*R	008580
	XA(1)=A+C	008590
45	XA(2)=A-C	008600
	C=.4873642779856547500*R	008610
	XA(3)=A+C	008620
	XA(4)=A-C	008630
	C=.4691372760011663800*R	008640
50	XA(5)=A+C	008650
	XA(6)=A-C	008660
	C=.4432077635022005200*R	008670
	XA(7)=A+C	008680
	XA(8)=A-C	008690
55	C=.4100009929869514600*R	008700
	XA(9)=A+C	008710
	XA(10)=A-C	008720
	008730

	C= .700620957892771900*R	008750
60	XA(1)=A+C	008760
	XA(12)=A-C	008770
	C= .124048259684877000*R	008780
	XA(13)=A+C	008790
	XA(14)=A-C	008800
65	C= .77271173569441977000*R	008810
	XA(15)=A+C	008820
	XA(16)=A-C	008830
	C= .168967538130225700*R	008840
	XA(17)=A+C	008850
	XA(18)=A-C	008860
70	C= .15752111984808160000*R	008870
	XA(19)=A+C	008880
	XA(20)=A-C	008890
	C= .055594337368081500-1*R	008900
	XA(21)=A+C	008910
	XA(22)=A-C	008920
75	C= .202844643130281300-1*R	008930
	XA(23)=A+C	008940
	XA(24)=A-C	008950
	RETURN	
80	END	008960

B.10 Subroutine DQG24B

1	C SUBROUTINE DQG24B(XL,XU,FCT,Y)	008970
	008980
5	C	008990
	C SUBROUTINE DQG24	009000
	C	009010
	DOPURPOSE	009020
	TO COMPUTE INTEGRAL(FCT(X)), SUMMED OVER X FROM XL TO XU	009030
	C	009040
10	C	009050
	USAGE	009060
	CALL DQG24 (XL,XU,FCT,Y)	009070
	PARAMETER FCT REQUIRES AN EXTERNAL STATEMENT	009080
	C	009090
15	C DESCRIPTION OF PARAMETERS	009100
	XL - DOUBLE PRECISION LOWER BOUND OF THE INTERVAL.	009110
	XU - DOUBLE PRECISION UPPER BOUND OF THE INTERVAL.	009120
	FCT - THE NAME OF AN EXTERNAL DOUBLE PRECISION FUNCTION	009130
	SUBPROGRAM USFU.	009140
	Y - THE RESULTING DOUBLE PRECISION INTEGRAL VALUE.	009150
20	C	009160
	REMARKS	009170
	NONE	009180
	C	009190
25	C SUBROUTINES AND FUNCTION SUBPROGRAMS REQUIRED	009200
	THE EXTERNAL DOUBLE PRECISION FUNCTION SUBPROGRAM FCT(X)	009210
	MUST BE FURNISHED BY THE USER.	009220
	C	009230
	METHOD	009240
30	EVALUATION IS DONE BY MEANS OF 24-POINT GAUSS QUADRATURE	009250
	FORMULA, WHICH INTEGRATES POLYNOMIALS UP TO DEGREE 47	009260
	EXACTLY. FOR REFERENCE, SEE	009270
	V.T.KRYLOV, APPROXIMATE CALCULATION OF INTEGRALS,	009280
	MACMILLAN, NEW YORK/LONDON, 1962, PP.100-111 AND 337-340.	009290
	C	009300
35	009310
	C	009320
	C	009330
	C	009340
	DIMENSION FCT(1)	009350

40	C	R=XIJ-XL I=1 Y=.+1706148999935098D-1*(FCT(I)+FCT(I+1)) I=I+2 Y=Y+.1425569431446912D-1*(FCT(I)+FCT(I+1)) I=I+2 Y=Y+.22138719408769903D-1*(FCT(I)+FCT(I+1)) I=I+2 Y=Y+.29649292457718790D-1*(FCT(I)+FCT(I+1)) I=I+2 Y=Y+.36673240705540153D-1*(FCT(I)+FCT(I+1)) I=I+2 Y=Y+.43005080765976638D-1*(FCT(I)+FCT(I+1)) I=I+2 Y=Y+.48819326052056944D-1*(FCT(I)+FCT(I+1)) I=I+2 Y=Y+.537221350579A2817D-1*(FCT(I)+FCT(I+1)) I=I+2 Y=Y+.577528340268A2801D-1*(FCT(I)+FCT(I+1)) I=I+2 Y=Y+.608352364639A1696D-1*(FCT(I)+FCT(I+1)) I=I+2 Y=Y+.62918728173414148D-1*(FCT(I)+FCT(I+1)) I=I+2 Y=Y+.63969097673376078D-1*(FCT(I)+FCT(I+1)) RETUR END	009360 009370 009380 009390 009400 009410 009420 009430 009440 009450 009460 009470 009480 009490 009500 009510 009520 009530 009540 009550 009560 009570 009580 009590 009600 009610 009620 009630
45			
50			
55			
60			
65			

B.11 Function IKIRKP

1	C	REAL FUNCTION IKIRKP(U,V,T)	009640
	C	APRIL 11, 1974	009650
	C	THIS FUNCTION COMPUTES THE KIRKHOFF INTENSITY FUNCTION	009660
5	C	ALONG THE U=0 AND/or V=0 AXIS OF THE PLANE.	009670
	C	SEE COMMENTS IN TKIRK AND COMPUTE FOR BACKGROUND INFO.	009680
	C	IT IS VALID ONLY FOR CONSTANT TEMPERATURE WINDOWS.	009690
	C	DIMENSION AA(10)	009700
	C	COMMON/FILES/IT3,IT4,IT5,IT6,IT7,IT8	009710
	C	COMMON/VECTOR/VV	009720
10	C	COMMON/PUBLK/CS1P,CS2P,CS1T,CS2T,XS,NX,NF,MNNT,EPP,F1(2n0),	009730
	+F2(200),HOLD,ALPHA,KF,TLAST,TNEXT,IERP,IP,MP1,ISW,NGAUSS,	009740	
	+RAD,NP1,*3,C1	009750	
	C	COMPLEX AJ0Q,CRH0Q,CTHETAQ,A1Q,A2Q,A3Q,A4Q,A6Q,A7Q	009760
	R	REAL KE	009765
15	D	DATA (AA(T),T=1,10)/1.-.9999999958,.4999999206,-.16666e3019,	009770
	*.0416573475,-.0087013598,.0013298820,-.000143161.0e.0,/	009780	
	VV=V	009790	
	C	CALL RTAPE3(T)	009800
	I	IF (ERR,NE.0) GOTO 2000	009810
20	C	CTHETAQ=CS1T*F1(1)+4.*CS2T*F2(1)	009820
	C	CTHETAO=CTHETAQ*KF	009825
	C	CRH0Q=CS1R*F1(1)+4.*CS2R*F2(1)	009830
	C	CRH0Q=CRH0Q*KE	009835
	A	AJ0=(0.,1.)	009840
25	A	A2Q=CEXP(AJ0Q*CRH0Q)	009850
	A	A3Q=CEXP(AJ0Q*CTHETAO)	009860
	A	A1Q=A2Q-A3Q	009870
	A	A=-((ALPHA**2)	009880
30	I	IF (A .LT. -1000) GOTO 110	009900
	E	EXPA=EXP(A)	009910
	A	AS=2.*((A/(1.-EXPA))**2	009920
	G	GOTO 120	009930
110	E	EXPA=0.	009940
	A	AS=2.*A*A	009950

35	120	B=U/2.	009960
		IF(V.EQ.0) GOTO 200	009970
		C=(ALPHA/V)**2	009980
		IF(U.EQ.0) GOTO 100	009990
	200	SINB=SIN(B)	010000
40		COSB=COS(B)	010010
		ASQ=A**2	010020
		BSQ=B**2	010030
		A40=EAL=.5*((EXP(A*COSB+B*SINB))-A)/(ASQ+BSQ)	010040
		A40TMAG=-.5*((EXP(A*SINB-B*COSB))+B)/(ASQ+BSQ)	010050
45		A40=CMPLX(A40REAL,A40TMAG)	010060
		A6Q=A10/P.*A40	010070
		IKTKP=A5*((CABS(A20*A40-A6Q))**2+(CARS(A3Q*A40+A6Q))**2)	010080
		RETURN	010090
	100	IF(-A.GT.-.693) GOTO 1000	010095
50		CALL COMPUTE(C,AA,FF1,FF2,IER)	010100
		IF(IER.EQ.2) GOTO 1000	010110
		A7Q=A10*FF2	010120
		IKTKP=A5*((CABS(A20*FF1-A7Q))**2+(CARS(A3Q*FF1+A7Q))**2)	010130
		RETURN	010140
55	1000	WRITE(11,5,10)	010150
	10	FORMAT(/ ALPHABET IS OUT OF RANGE/)	010160
	2000	RETURN	010170
		END	010180

B.12 Subroutine COMPUTE

1		SUBROUTINE COMPUTE (C,AA,F0,F1,IER)	010190
		THIS SUBROUTINE RETURNS THE APPROXIMATION TO THE INTEGRAL	010200
		F0=(1/V)**2*INTEGRAL(Y**J0(Y)*F**(-CY**2))DY OVER (0,V)	010210
		F1=(1/V)**2*INTEGRAL(J1(Y)*F**(-CY**2))DY OVER (0,V) GIVEN BY	010220
5		F0=(1/V)**2*SUM(A(I)*(C**I)*(INTEGRAL(Y**((2I+1)*J0(Y))))) AND	010230
		F1=(1/V)**2*SUM(A(I)*(C**I)*INTEGRAL(Y**((2I+1)*J1(Y)))) OVER(0,V)	010240
		FOR I=0,1,...,N	010250
		WHERE THE A(I) ARE GIVEN (FOR EXAMPLE) IN NBS 55 P. 71	010260
		NOTE THAT FOR THE	010270
10		APPROXIMATIONS TO BE VALID, 0L=CI=.693	010280
		COMMON/VICTOR/V	010290
		DIMENSION AA(1)	010300
		REAL AA,I	010310
		IER=1	010320
15		I=0	010330
		F0=L=0.	010340
	110	IF(A(I+1).EQ.0.) GOTO 2000	010350
		F0=F0+AA(I+1)*(C**I)*J1(0*I)	010360
		F1=F1+AA(I+1)*(C**I)*J1(1*I)	010370
20		I=I+1	010380
		GOTO 110	010390
	2000	F0=F0/V**2	010400
		F1=F1/V**2	010410
		RETURN	010420
25	1000	IER=2	010430
		RETURN	010440
		END	010450

B.13 Function JI

```

1      C          010460
C          REAL FUNCTION JT(T,N)
C          REAL N11,N22
C          COMMON/VICTOR/V
5      C          IF T=1, THEN THIS FUNCTION RETURNS%
C          INTEGRAL((T**2N)J1(T)) OVER(0,V)
C          IF T=0, THEN THIS FUNCTION RETURNS%
C          INTEGRAL((T**2(N+1)) J0(T)) OVER (0,V)
C          SEE LIKE,Y.L., "INTEGRALS OF BESSEL FUNCTIONS"
10     C          MCGRAW HILL 1962 (P.51)
C          OR JBS 55 (P.48)
C          N1=N
C          N2=N+2
C          I1=T+1
C          GOTO 110,100,I1
100    IF(N=.NF,0) GOTO 120
C          I1=T-HFSJF(0)
C          RETURN
15      C          N1=-N
C          JT=2.*BESJF(2)
C          EXP=2*N
C          K21=2
C          GOTO 130
110    N1=-(N+1)
C          JT=BESJF(1)
C          EXP=2*N+1
C          K21=1
130    N11=N22=1
C          N2=N+2
140    N1=N1+1
C          IF(N1.E0,0) GOTO 2000
C          K21=K21+2
C          N11=N1*N1
C          N22=N22*N2
C          N2=N2+1
C          JT=I1+K21*N11/N22*BESJF(K21)
2000  JT=I1*K21*N11/N22*BESJF(K21)
C          GOTO 140
C          JT=V**EXP/(N+1)*JT
C          RETURN
C          END

```

B.14 Function BESJF

```

1      C          010840
C          FUNCTION BESJF ( M )
C          COMMON/VICTOR/V
C          COMMON/T=FILES/IT3,IT4,IT5,IT6,IT7,IT8
5      N=M
D=.001
CALL BESJ(V,N,B,I,D,TFR)
IER=IER+1
GOT0 (10,20+30+40,50) IER
10     BESJF=8.1
RETURN
20     WRITE (IT5,200)
210    FORMAT(* ORDER OF BES FUN NEG,PROGRAM STOP*)
GOT0 1000
15     30     WRITE (IT5,300)
300    FORMAT(* ARG OF BES FUN NEG OR ZERO,PROGRAM STOP*)
GOT0 1000
40     40     WRITE (IT5,400)
400    FORMAT(* ACCURACY OF BES FUN NOT OBTAINED,PROGRAM CONTINUES*)
20     50     WRITE(IT5,500)
500    FORMAT(* RANGE ERROR IN BES FUN. RANGE ADJUSTED*)
GOT0 10
1000  STOP
25     END

```

B.15 Function BESJ

```

1      SUBROUTINE BESJ(X,N,R,I,IER)          011130
C ..... 011140
C
C      SUBROUTINE BESJ               011150
5      C
C      PURPOSE               011160
C      COMPUTE THE J BESSSEL FUNCTION FOR A GIVEN ARGUMENT AND ORDER 011170
C
C      USAGE                011180
10     C      CALL BESJ(X,N,R,I,IER)          011190
C
C      DESCRIPTION OF PARAMETERS 011200
C      X -THE ARGUMENT OF THE J BESSSEL FUNCTION DESIRED 011210
C      N -THE ORDER OF THE J BESSSEL FUNCTION DESIRED 011220
C      R -THE RESULTANT J BESSSEL FUNCTION 011230
C      IER -REQUIRED ACCURACY 011240
C      IER=RESULTANT ERROR CODE WHERE
C          IER=0 NO ERROR 011250
C          IER=1 N IS NEGATIVE 011260
C          IER=2 X IS NEGATIVE OR ZERO 011270
C          IER=3 REQUIRED ACCURACY NOT OBTAINED 011280
C          IER=4 RANGE OF N COMPARED TO X NOT CORRECT (SEE REMARKS) 011290
C
C      REMARKS               011300
25     C      N MUST BE GREATER THAN OR EQUAL TO ZERO, BUT IT MUST BE 011310
C          LESS THAN 011320
C          20+10*X-X** 2/3   FOR X LESS THAN OR EQUAL TO 15 011330
C          90+X/2           FOR X GREATER THAN 15 011340
C
C      SUBROUTINES AND FUNCTION SUBPROGRAMS REQUIRED 011350
30     C      NONE 011360
C
C      METHOD                011370
C      RECURRENCE RELATION TECHNIQUE DESCRIBED BY H. GOLDSTEIN AND 011380
C      R.M. THALER, "RECURRENCE TECHNIQUES FOR THE CALCULATION OF 011390
C      BESSSEL FUNCTIONS", M.T.A.C., V.13, PP.102-108 AND I.A. STEGUN 011400
C      AND M. Abramowitz, "GENERATION OF BESSSEL FUNCTIONS ON HIGH 011410
C      SPEED COMPUTERS", M.T.A.C., V.11, 1957, PP.255-257 011420
C
C
40     C ..... 011430
C
C      R:=0 011440
45     C      IF(I)=0, P0=2.0 011450
C      10 IER=1 011460
C      RETURN 011470
C      20 IF(Y)=0, P0=3.1 011480
C      30 IER=2 011490
C      RETURN 011500
C
50     C      31 JF(X=15.)=2.32+32.34 011510
C      32 NTEST=20.+10.*X-X** 2/3 011520
C      GO TO 36 011530
C
C      34 NTEST=90.+X/2. 011540
C      36 IF(I)=NTEST)40+3R+38 011550
C
C      38 IER=6 011560
C      N=NTEST-1 011570
C      GOTO 41 011580
C
C      40 IER=0 011590
C      41 N=NP1 011600
C      RPREV=0.0 011610
C
C      COMPUTE STARTING VALUE OF M 011620
C
C      50 IF(X=5.)=0+60+60 011630
C
C      50 MA=X+6. 011640
C      GO TO 70 011650
C
C      60 MA=1.4*X+60./X 011660
C      70 MR=N+IF(X(X)/4+2 011670
C      M7E=0=MAX(N(MA+M-1) 011680
C
C      SET UPPER LIMIT OF M 011690
C
C      MMAX=NTEST 011700
C
C      100 DO 190 M=ZERO,MMAX,1 011710

```

75	C	SET F(M),F(M-1)	011870
	C	FMI=1.0F-28	011880
	C	FMS=0	011890
80	C	ALPHA=.9	011900
	C	IF(M-(M/2)*2)120+110+120	011920
	110	JT=-1	011930
		GO TO 130	011940
	120	JT=1	011950
85	130	M2=M-2	011960
		DO 160 K=1,M2	011970
		MK=N-K	011980
		RMK=2.*FLOAT(MK)*FM1/X-FM	011990
		FMS=FM1	012000
90		FM1=RMK	012010
		IF((K-N-1)150+140+150	012020
	140	R I=RMK	012030
	150	JT=JT	012040
		S=I,JT	012050
95		S=I,JT	012060
	160	ALPHA=ALPHA+RMK*S	012070
		RMK=2.*FM1/X-FM	012080
		TF(I)=180+170+180	012090
100	170	R J=RMK	012100
	180	ALPHA=ALPHA+RMK	012110
		R I=J/ALPHA	012120
		IF((I-BS(R,I-BPREV)-1)BS(D*RJ))200+200+190	012130
	190	BPREV=B I	012140
		IPR=3	012150
105	200	RETURN	012160
		END	012170
			012180

B.16 Subroutine GETDATA

1		SUBROUTINE GETDATA(DATAIN,NV,LIN,IOUT1,IOUT2,IIN),ISIZE	012190
		*ISIZE,IINDIC)	012200
5	C	THE MAIN PURPOSE OF THIS SUBROUTINE IS TO INPUT CHARACTER STRING OR	012210
	C	NUMERICAL DATA IN A CONVERSATIONAL MODE I.E. FOR INPUTTING DATA	012220
	C	TO PROGRAMS BEING RUN UNDER INTERCOM.	012230
	C	IT ALSO MAY BE USED FOR BATCH PROCESSING-IN WHICH CASE THE DATA	012240
	C	SHOULD APPEAR 6 VALUES TO A CARD, DATA WHICH IS NOT TO BE CHANGED	012250
	C	SHOULD BE REPLACED BY BLANKS. FOR BATCH ALL OR SOME OF THE DATA MAY	012260
	C	BE DEFAULTED BY USING AN EOF AFTER THE LAST DATA TO BE INPUTTED.	012270
10	C	THE SUBROUTINE ASSUMES THAT DEFAULT VALUES HAVE BEEN ASSIGNED	012280
	C	AND WILL PRINT OUT THESE DEFAULT VALUES BEFORE ASKING FOR DATA INPUT.	012290
	C	IT ASKS FOR NEW VALUES BY PRINTING OUT THE NAMES OF THE DATA AND THEN	012300
	C	SKIPPING A LINE. VALUES TO BE ASSIGNED TO THE NAMES SHOULD BE	012310
	C	ENTERED STARTING IN THE SAME COLUMN AS THE START OF THE NAME.	012320
15	C	EACH DATUM IS ASSIGNED TO COLUMNS AND UP TO 6 ITEMS MAY BE INPUTTED	012330
	C	IN A SINGLES ROW.	012340
	C	ARGUMENTS*****	012350
	C	DATAIN (DIMENSION (NV+?) WHERE NV IS THE TOTAL # OF DATA	012360
	C	TO BE INPUTTED)	012370
20	C	DATAIN HOLDS THE FOLLOWING INFORMATION ABOUT EACH DATUM-	012380
	C	NAME,VALUE,CODE WHERE-	012390
	C	NAME => NAME BY WHICH THE DATUM IS IDENTIFIED TO THE USER (IT MAY OR	012400
	C	MAY NOT BE EQUAL TO THE FORTRAN VARIABLE NAME TO BE ASSIGNED TO THE	012410
	C	DATUM.)	012420
25	C	VALUE => NUMERICAL OR CHARACTER STRING VALUE TO BE ASSIGNED (THE DATUM)	012430
	C	CODE => HOW THE DATUM IS TO BE INTERPRETED	012440
	C	-1 => CHARACTER STRING	012450
	C	0 => INTEGER	012460
	C	1 => FLOATING POINT NUMBER	012470
30	C	NV TOTAL NUMBER OF DATUM TO BE INPUTTED	012480
	C	IIN FILE NO. FOR INPUTTING	012490
	C	IOUT1 PRIMARY OUTPUT FILE	012500
	C	IOUT2 SECONDARY OUTPUT FILE	012510
	C	ISIZE => SIZE OF FIRST DIMENSION OF DATAIN	012520

35	DIMENSION DATAIN(TSTZFT),IA(6)	012530
	COMMON/S=NSE/IINNN,TOUTNN,IND1CC	012540
	INTEGER DATAIN,F	012550
	EXTERNAL SSWTCH	012560
	CALI ERRSET(KOUNT,21000)	012570
	KOUNT=LKOUNT	012580
	IF (INDIC,NE,0) 200+210	012590
40	200 TSW=2	012600
	LI=2	012610
	L=INDIC-1	012620
	GOTO 1655	012630
45	210 CONTINUE	012640
	ISW=1	012650
	I001=00000000000000000000538	012660
	IINNN=IIN	012670
50	IOUTNN=IOUT1	012680
	IOUTT=IOUT1	012690
	ISN=1	012700
	TRLINK=124	012710
	CALI SSWTCH(IINI,TSW+10HREAD DATA ,SHFILE-),RETURNS(1060)	012720
55	IF (ISW,NE,1) 1310+1290	012730
	1300 WRITE (IOUTT,17) IINI	012740
	REWIND TTM1	012750
	READ(IINI) DATAIN	012760
	REWIND TTM1	012770
60	IF (EOF(TTM1)) 1400+1290	012780
	1400 WRITE(IOUTT,24) IINI	012790
65	1491 CONTINUE	012800
	CALI SSWTCH(0,ISW+1AHDEFAULTS L,SHISTED),RETURNS(1060)	012810
	IF (ISW,NE,1) GOTO 1490	012820
	1490 DO 110 I=1,NV	012830
	IT=SIZE+1	012840
	IT2=II+ISIZE	012850
70	IF (DATAIN(I12)) 1020+1030+1040	012860
	1020 WRITE(IOUTT,2) DATAIN(II)+DATAIN(III)	012870
	GOTO 110	012880
	1030 WRITE (IOUTT,3) DATAIN(II)+DATAIN(III)	012890
	GOTO 110	012900
75	1040 WRITE(IOUTT,4) DATAIN(II)+DATAIN(III)	012910
	110 CONTINUE	012920
	GOTO (1150+1130) TSN	012930
	1150 CALI SSWTCH(0,ISW+10HNAME-VALUE,SH MODE),RETURNS(1060)	012940
	IF (ISW,NE,1) 1270+1050	012950
80	1250 L=1	012960
	ISW=2	012970
	LI=1	012980
	1255 L=L+LL	012990
	IF (L,GT.,NV) GOTO 1060	013000
85	1310 WRITE (IOUTT,18) DATAIN(ISIZE+L)	013010
	LL=1	013020
	DO 100 J=1,6	013030
	IA(J)=104	013040
90	140 CONTINUE	013050
	READ(IIN,10) (IA(J),J=1,6)	013060
	IF (EOF(IIN)) 1320+1070	013070
	1420 THDTC=1	013080
	GOTO 1060	013090
	1470 IF (IA(1),EQ,TRLINK) GOTO 1045	013100
95	DO 180 J=1,6	013110
	DO 180 K=1,10	013120
	IF (MXGETX(IA(J),K+1),EQ,10UL) GOTO 1270	013130
	180 CONTINUE	013140
	DO 190 J=1,6	013150
	JP=L+J-1	013160
	F=DATAIN(JP+2*ISIZE)	013170
	IF (F,1000+100,110)	013180
100	1493 IF (IA(J),NE,TRLINK) DECODE(10,11,IA(J)) DATAIN(JR)	013190
	GOTO 1080	013200
105	1494 CALL RJUST(IA(J))	013210
	IF (IA(J),NE,TRLINK) DECODE(10,12+IA(J)) DATAIN(JR)	013220
	GOTO 1080	013230
	1110 CALL RJUST(IA(J))	013240
	IF (IA(J),NE,TRLINK) DECODE(10,13+IA(J)) DATAIN(JR)	013250
	GOTO 1080	013255
110	1499 CONTINUE	013260
	1580 LL=1	013270
	IF (INDIC,NE,0) LL=1000	013280
	IF (KOUNT,NE,0) KOUNT1) GOTO 1055	013290
		013300
		013310

115.	KOUNT1=KOUNT	013320
	WRITE(IOUT1,25)	013330
1270	WRITE(IOUT1,23)	013340
1250	WRITE(IOUT1,8)	013350
	DO i50 I=1,6	013360
120	I4(I)=10H	013370
150	CONTINUE	013380
	READ(IN,10) (IA(I)+I=1,6)	013390
	IF (EOF(IN)) 1330+1085	013400
1130	TND1CC=1	013410
125	GOTO 1060	013420
1085	II=IA(I)	013430
	IF (II .EQ. 1BLANK) GOTO 1060	013440
	DO i30 I=1,NV	013450
	J=I+ISIZE	013460
130	IF (II .EQ. DATAIN(J)) GOTO 1160	013470
130	CONTINUE	013480
	WRITE(IOUT1,16)	013490
	GOTO 1270	013500
1160	F=DATAIN(J)+ISIZE	013510
	J,J= I-ISIZE	013520
	IF (F) 1170,1180+1190	013530
1170	DO i60 I=2,6	013540
	IF (IA(I) .EQ. 1BLANK) GOTO 1240	013550
	DECODE(I1,11,IA(I)) DATAIN(J,I-2)	013560
140	CONTINUE	013570
	GOTO 1240	013580
1180	CALL RJUST(IA(2))	013590
	DECODE(I1,12,IA(2)) DATAIN(JJ)	013600
145	GOTO 1260	013610
1190	CALL RJUST(IA(2))	013615
	DECODE(I1,13,IA(2)) DATAIN(JJ)	013620
1240	IF (KOUNT .EQ. KOUNT1) GOTO (1250+1310) ISW	013630
	KOUNT1=KOUNT	013640
	WRITE(IOUT1,25)	013650
150	GOTO 1250	013660
1060	WRITE(IOUT1,14)	013670
	IF (IOUT2 .EQ. 0) GOTO 1130	013680
	WRITE(IOUT2,15)	013690
	IOUT=T=IOUT?	013700
155	ISN=2	013710
	GOTO 1140	013720
1130	INDIC=INDICC	013730
	RETURN	013740
160	FORMAT(/.* THE DEFAR,T INPUT DATA ARE*)	013750
1	FORMAT(1X,A10,*=@@,A10,*=*)	013760
2	FORMAT(1X,A10,*=*,I10)	013770
3	FORMAT(1X,A10,*=*,G16,6)	013780
4	FORMAT(1X,A10,*=*,*)	013790
5	FORMAT(//*)	013800
6	FORMAT(/.* ENTER DATA. START IN COL. BENEATH START OF NAME*)	013810
165	FORMAT(BX,6A10)	013820
7	FORMAT(BX)	013830
8	FORMAT(6A10)	013840
9	FORMAT(A10)	013850
10	FORMAT(I10)	013860
11	FORMAT(F10,0)	013870
12	FORMAT(/.* DATA INPUT COMPLETE*)	013880
13	FORMAT(/.* THE TINPUT DATA VALUES ARE*/)	013890
14	FORMAT(1X,* TRY AGAIN*)	013900
15	FORMAT(1X,* READING DATA FROM **I5)	013910
16	FORMAT(1X,A10,*=*)	013920
17	FORMAT(BX,*NAME VALUE.....*)	013930
18	FORMAT(1X,A10,*=*)	013940
19	FORMAT(BX,*FILE*,I5,* IS EMPTY*)	013950
20	FORMAT(1X,* WRONG DATA TYPE-TRY AGAIN*)	
21	END	

B.17 Subroutine PRT

```

1      SUBROUTINE PRT(RUF,MODE,I1,IT,MP,NP,MSKIP,NSKIP,RHOP),
+DELRHO,VMIN,DELV,XIT,II,TR,T,T16)          015000
2      DIMENSION R(100),RUF(1),D(2)              015010
3      DATA ITT/0/                                015020
4      IF (ITT .EQ. IT) GOTO 100                 015030
5      WRITE(IT6,1) TR+T                         015040
6      DO 130 I=1,MP+MSKIP                     015050
7      GOTO 110+120) MODE                         015060
8      R(I)=RHOP+DELRHO*(I-1)                   015070
9      GOTO 130                                 015080
10     R(I)=VMIN+DELV*(I-1)                      015090
11     CONTINUE                                  015100
12     GOTO (170+180) MODE                       015110
13     WRITE(IT6,2) (R(I)+I*MP+MSKIP)           015120
14     GOTO 100                                 015130
15     WRITE(IT6,3) (R(I)+I*MP+MSKIP)           015140
16     GOTO (140+150) MODE                       015150
17     ENCODE(20,4,D) XIT                        015160
18     GOTO 160                                 015170
19     ENCODE(20,5,D) II                         015180
20     IF (MOD(IT-1,NSKIP) .EQ. 0) WRITE(IT6,6) D+
+ (RUF(J),J=1,MP+MSKIP)                      015190
21     ITT=IT                                     015200
22     1000 RETURN                                015210
23     1   FORMAT(//* TIME(SECONDS)= *G12.4* TAU= *G12.4/
+-----*)                                     015220
2   FORMAT(/* INTENSITIES EVALUATED AT RHOD=PRIME=*/(5X,5G13.5)) 015230
3   FORMAT(/* INTENSITIES EVALUATED AT V=*/(5X,5G13.5))        015240
4   FORMAT(* X= *G13.5)                          015250
5   FORMAT(* U= *G13.5)                          015260
6   FORMAT(/%A10/(5X,5G13.5))                  015270
    END                                         015280
                                         015290
                                         015300

```

Appendix C

The Evaluation of $I'(u,0,t)$ and $I'(0,v,t)$ Used in the IKIRKP Option

1. INTRODUCTION

Consider the circumstance when the temperature distribution is constant throughout the window but is a function of time only, viz., $w(t)$. Then, returning to Eq. (16), Volume I, we see that:

$$F_1(\rho, t) = \int_{\xi_1}^{\xi_2} w(t) d\xi = (\xi_2 - \xi_1) w(t) = w(t) L/a = F_1(t).$$

In a similar fashion, Eq. (17), Volume I, becomes:

$$F_2(\rho, t) = \rho^{-2} \int_0^\rho d\rho \rho L w(t)/a = L w(t)/2a = F_2(t).$$

Equation (18), Volume I, simplifies to:

$$\begin{aligned} \Phi^\gamma(\rho, t) &= a \Delta T_c \left[S_1^\gamma w(t) L/a + 4 S_2^\gamma w(t) L/2a \right] \\ &= L w(t) \Delta T_c \left[S_1^\gamma + 2 S_2^\gamma \right] \equiv d^\gamma(t). \end{aligned}$$

2. EVALUATION OF $I'(u, 0, t)$

For the condition $v = 0$ and u arbitrary, then $J_0(0) = 1$ and $\lim_{v \rightarrow 0} J_1(\rho v)/\rho v = 1/2$. Equations (25-27), Volume I, reduce to:

$$f_z(\rho, 0, t) = \rho [\exp(i k d^\rho) - \exp(-i k d^\theta)] / 2 \equiv \rho A_1(t) / 2,$$

$$f_x(\rho, 0, t) = \rho [\exp(i k d^\rho) - f_z] \equiv \rho A_2(t) - \rho A_1(t) / 2,$$

$$f_y(\rho, 0, t) = \rho [\exp(i k d^\theta) + f_z] \equiv \rho A_3(t) + \rho A_1(t) / 2.$$

Then, from Eq. (23), Volume I,

$$\begin{aligned} I'(u, 0, t) &= 2\alpha^4 (1 - \exp(-\alpha^2))^{-2} \left\{ \left| \int_0^1 \exp(-\alpha^2 \rho^2) \exp(-iu\rho^2/2) (\rho A_2 - \rho A_1/2) d\rho \right|^2 \right. \\ &\quad \left. + \left| \int_0^1 \exp(-\alpha^2 \rho^2) \exp(-iu\rho^2/2) (\rho A_3 + \rho A_1/2) d\rho \right|^2 \right\}. \end{aligned}$$

$$I'(u, 0, t) = 2\alpha^4 (1 - \exp(-\alpha^2))^2 \left\{ \left| (A_2 - A_1/2) \int_0^1 \rho \exp(-\alpha^2 \rho^2) \exp(-iu\rho^2/2) d\rho \right|^2 + \left| (A_3 + A_1/2) \int_0^1 \rho \exp(-\alpha^2 \rho^2) \exp(-iu\rho^2/2) d\rho \right|^2 \right\}.$$

Expressing the integral in terms of sin and cos, we find:

$$\int_0^1 \rho \exp(-\alpha^2 \rho^2) \exp(-iu\rho^2/2) d\rho = \int_0^1 \rho \exp(-\alpha^2 \rho^2) \cos(u\rho^2/2) d\rho - i \int_0^1 \rho \exp(-\alpha^2 \rho^2) \sin(u\rho^2/2) d\rho.$$

Let $a = -\alpha^2$, $b = u/2$ and $y = \rho^2$, to get:

$$\frac{1}{2} \int_0^1 e^{ay} \cos by dy - \frac{i}{2} \int_0^1 e^{ay} \sin by dy = \frac{1}{2} \left\{ \frac{e^a(a \cos b + b \sin b) - a}{a^2 + b^2} \right\} - \frac{i}{2} \left\{ \frac{e^a(a \sin b - b \cos b) + b}{a^2 + b^2} \right\} \equiv A_4.$$

Thus, we get the final result:

$$I'(u, 0, t) = 2\alpha^4 (1 - \exp(-\alpha^2))^2 \left\{ \left| (A_2 - A_1/2) A_4 \right|^2 + \left| (A_3 + A_1/2) A_4 \right|^2 \right\}.$$

3. EVALUATION OF $I'(0, v, t)$

Consider when $u = 0$ and v is arbitrary. Then,

$$f_w(\rho) = \exp(-\alpha^2 \rho^2)$$

$$f_z(\rho, v, t) = v^{-1} J_1(\rho v) A_1(t)$$

$$f_x(\rho, v, t) = \rho J_0(\rho v) A_2(t) - f_z$$

$$f_y(\rho, v, t) = \rho J_0(\rho v) A_3(t) + f_z .$$

Inserting these functions into Eq. (23), Volume I, the integral terms become:

$$\left| A_2 \int_0^1 \rho J_0(\rho v) \exp(-\alpha^2 \rho^2) d\rho - A_1 v^{-1} \int_0^1 J_1(\rho v) \exp(-\alpha^2 \rho^2) d\rho \right|^2 \\ + \left| A_3 \int_0^1 \rho J_0(\rho v) \exp(-\alpha^2 \rho^2) d\rho + A_1 v^{-1} \int_0^1 J_1(\rho v) \exp(-\alpha^2 \rho^2) d\rho \right|^2.$$

Thus, the integrals to consider are:

$$\int_0^1 \rho J_0(\rho v) \exp(-\alpha^2 \rho^2) d\rho; v^{-1} \int_0^1 J_1(\rho v) \exp(-\alpha^2 \rho^2) d\rho$$

Let $y = \rho v$ and obtain:

$$v^{-2} \int_0^V y J_0(y) \exp(-\alpha^2 y^2/v^2) dy; v^{-2} \int_0^V J_1(y) \exp(-\alpha^2 y^2/v^2) dy.$$

In order to perform these integrations, consider a polynomial approximation to $\exp(-\alpha^2 y^2/v^2)$. On p. 71 of Abramowitz and Stegun,¹ various approximations to e^{-x} are given, valid for the domain $0 \leq x \leq 0.693$. They all have the generic form: $e^{-x} = 1 + a_1 x + a_2 x^2 + a_3 x^3 + \dots$. Since $\alpha^2 y^2/v^2$ is a maximum at $y = v$ (where $\rho = 1$) for any value of v , we get the condition that $0 \leq \alpha^2 \leq 0.693$. Using the polynomial approximations mentioned above, the typical n -th term from each of the above two integrals will have the form:

$$a_n \alpha^{2n} v^{-(2n+2)} \int_0^V y^{2n+1} J_0(y) dy; a_n \alpha^{2n} v^{-(2n+2)} \int_0^V y^{2n} J_1(y) dy.$$

On p. 480 of Abramowitz and Stegun¹ or p. 51 of Luke,² we find:

$$J_0^{2n+1}(v) = \int_0^V y^{2n+1} J_0(y) dy = \frac{v^{2n+1}}{n+1} \sum_{k=0}^{\infty} \frac{(2k+1)(-n)_k}{(n+2)_k} J_{2k+1}(v)$$

-
1. Abramowitz, M., and Stegun, I.A., Editors (1964) Handbook of Mathematical Functions, National Bureau of Standards, Washington, D.C.
 2. Luke, Y. L. (1962) Integrals of Bessel Functions, McGraw-Hill Co., New York.

$$J_{i_1}^n(v) = \int_0^v y^n J_1(y) dy = \frac{v^{2n}}{n+1} \sum_{k=0} \frac{(2k+2)(1-n)_k}{(n+2)_k} J_{2k+2}(v) \quad (n \neq 0)$$

and

$$\int_0^v J_1(y) dy = 1 - J_0(v)$$

where:

$$(a)_0 = 1$$

$$(a)_k = a \cdot (a+1) \cdot (a+2) \dots (a+k-1)$$

Since $(-n)_k = 0$ for $k = n+1$ and $(1-n)_k = 0$ for $k = n$, the series terminates.

The above results have been coded in a function subroutine JI (i, n) which returns $J_{i_0}^{2n+1}(v)$ if $i = 0$ and $J_{i_1}^n(v)$ if $i = 1$. It uses the IBM Scientific Subroutine BESJ to compute the $J_{2k+1}(v)$ and $J_{2k+2}(v)$.

Appendix D

**Fortran Listings for the Main Programs in the Alternate TIKIRK
Package Containing All Three Options**

D.1 Modified Main Program TIKIRK

```

1      PROGRAM TIKIRK(TAPE4=65,TAPE5=65,TAPE7=513,TAPE8=513,
+TAPE6=65,OUTPUT=65)
C THIS PROGRAM CAN BEST BE DESCRIBED AS THE I/O INTERFACE FOR FUNCTION
C SUBROUTINE IKTRK WHICH COMPUTES THE KIPKHOFF INTENSITY FUNCTION AS
C DESCRIBED IN AFTRL-72-0565.
C THE INPUT FALLS INTO THREE CLASSES*
C 1) INPUT HAVING TO DO WITH PROPERTIES OF THE WINDOW MATERIAL AND
C THE LASER BEAM, NAMELY X QUANTITIES (AS UNLESS OTHERWISE INDICATED)
C SIG => VALUE OF SIGMA IN GAUSSIAN BEAM
C LAMBDA => WAVELENGTH OF THE LIGHT BEAM IN MICRONS
C OW => TOTAL BEAM POWER
C R => WINDOW RADIUS
C RETA => BULK ABSORPTION COEFFICIENT
C K => THERMAL CONDUCTIVITY
C NX => INDEX OF REFRACTION
C S1P => S SUB-1,SUB-PHI
C S1T => S SUB-1,SUB-THETA
C S2P => S SUB-2,SUB-PHI
C S2T => S SUB-2,SUB-THETA
C T => TIME AT WHICH IKTRK IS TO BE EVALUATED
C 2) INPUT HAVING TO DO WITH THE EVALUATION DOMAIN OF THE FUNCTION
C IKIRK, NAMELY
C X0 => GAUSSIAN FOCAL DISTANCE (METERS)
C X1 => MINIMUM Y-VALUE FOR FUNCTION EVALUATION (METERS)
C X2 => MAXIMUM Y-VALUE FOR FUNCTION EVALUATION (METERS)
C RHOP1 => MINIMUM RADIAL VALUE FOR FUNCTION EVALUATION
C RHOP2 => MAXIMUM RADIAL VALUE FOR FUNCTION EVALUATION
C NP => NUMBER OF EVALUATION POINTS IN THE RADIAL DIRECTION
C ND => NUMBER OF EVALUATION POINTS IN THE AXIAL (X) DIRECTION
C TTM => ARRAY (UP TO 10) OF TIME VALUES FOR FUNCTION EVALUATION
C (*TIME VALUES SHOULD BE IN INCREASING SEQUENCE)
C UMIN => MINIMUM U-VALUE FOR FUNCTION EVALUATION (SEE MODE)
C UMAX => MAXIMUM U-VALUE FOR FUNCTION EVALUATION
C VMIN => MINIMUM V-VALUE FOR FUNCTION EVALUATION
C VMAX => MAXIMUM V-VALUE FOR FUNCTION EVALUATION
C 3) INPUT HAVING TO DO WITH PROGRAM CONTROL, NAMELY*
C EPS1 => ERROR VALUE FOR INTERPOLATION OF THE TEMPERATURE
C FUNCTION OUTPUTTED BY TEMPS AND INTERPOLATED BY IBM SCI. SUB. ALI.
C MNT => NUMBER OF TEMPERATURE FUNCTION POINTS TO BE USED IN
C THE INTERPOLATION (OFFAII,T=6)
C IPRT => USED TO CONTROL DEBUG OUTPUT (1 CAUSES DEBUG OUTPUT)
C (2 CAUSES WINDOW TEMPERATURE DISTRIBUTION SUITABLE FOR
C DISPLAY TO BE OUTPUT)
C NGAUSS => NUMBER OF FUNCTION VALUES FOR GAUSSIAN INTEGRATION
C MODE => IF MODE=1 THEN THE INTENSITY FUNCTION IS EVALUATED AT
C EQUALLY-SPACED X AND RHOP1-PRIME VALUES; IF MODE=2 IT IS EVALUATED AT
C EQUALLY-SPACED U AND V VALUES.
C IP => IF 1 USE IKTRK, IF 2 USE IKTRKP
C (NOTE THAT IKTRKP SHOULD ONLY BE USED ON THE AXES
C FOR CONSTANT TEMPERATURE WINDOW)
C ALL THE ABOVE MENTIONED DATA IS OBTAINED BY TWO CALLS TO THE
C INTERACTIVE INPUT SUBROUTINE GETDATA DESCRIBED IN PML TM-16. IN THE
C FIRST CALL ALL DATA IN THE FIRST CATEGORY IS OBTAINED. IN THE
C SECOND CALL ALL DATA IN THE SECOND AND THIRD CATEGORIES ARE
C OBTAINED. AN EXCEPTION TO THIS IS IP (CONTROLS USE OF
C IKIRK AND IKTRKP) WHICH IS OBTAINED ON THE FIRST CALL TO GETDATA.
C FOR A LISTING OF DEFAULT INPUT DATA IT IS RECOMMENDED THAT
C TIKIRK BE RUN INTERACTIVELY UNDER INTERCOM AFTER GIVING THE COMMAND
C CONNECT(TAPE4,TAPE5).
C THE MAIN OUTPUT OF TIKIRK IS A SEQUENCE OF UNFORMATTED RECORDS
C OF INTENSITY VALUES WITH CORRESPONDING DOMAIN VALUES. EACH RECORD
C CONSISTS OF THE FOLLOWING SEQUENCE OF VALUES*
C RECORD NO., NUMBER(NP) OF INTENSITY VALUES IN THE AXIAL DIRECTION,
C AXIAL COORDINATE X OR U, TIME VALUE (T) IN SECONDS, NUMBER (NP)
C OF INTENSITY VALUES IN THE RADIAL DIRECTION, MINIMUM RADIAL
C COORDINATE RHOP1 OR VMIN, MAXIMUM RADIAL COORDINATE RHOP2 OR
C VMAX, NP INTENSITY VALUES.
C FOR EACH VALUE OF T, NP RECORDS ARE OUTPUTTED CORRESPONDING TO THE
C NP X EVALUATION POINTS. THE RECORD NUMBER RUNS FROM 1 TO NP FOR
C EACH TIME VALUE.
C THERE ARE SIX FILES ASSOCIATED WITH THIS PROGRAM (NOT INCLUDING FILE
C MOINPUT). THE FILES ARE REFERRED TO IN THE PROGRAM AND ASSOCIATED
C SUBROUTINES AS IT3,IT4,IT5,IT6,IT7,IT8. THE FILE VALUES ARE IN TURN
C ASSIGNED TO THE USUAL FORTRAN WTAPEN® BY A DATA STATEMENT AND PROGRAM
000100
000110
000120
000130
000140
000150
000160
000170
000180
000190
000200
000210
000220
000230
000240
000250
000260
000270
000280
000290
000300
000310
000320
000330
000340
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000380
000390
000400
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000580
000590
000600
000610
000620
000630
000640
000650
000660
000670
000680
000690
000700
000710
000720
000730
000740
000750
000760
000770
000780
000790
000800
000810
000820
000830

```

75 C STATEMENT SUCH THAT IT3 => TAPE3+ETC. THIS IS TO CHANGE THE
 C ASSOCIATION IT IS NECESSARY TO CHANGE EITHER OR BOTH THE DATA AND
 C PROGRAM STATEMENTS.
 C THESE FILES SERVE THE FOLLOWING PURPOSES:
 C IT3 => FILE OUTPUTTED BY PROGRAM TEMPS
 C IT4 => @INTERACTIVE@ INPUT FILE (SEE GETDATA)
 C IT5 => @INTERACTIVE@ OUTPUT FILE (SEE GETDATA)
 C IT6 => LISTING OF ALL INPUT PARAMETERS AND DEBUG OUTPUT
 C IT7 => UNFORMATTED INTENSITY VALUES. ALSO MAY BE USED TO INSERT
 C IT8 => UNFORMATTED TEMPERATURE DISTRIBUTION VALUES
 85 C SUITABLE FOR DISPLAY PURPOSES
 C PBEASIGNED DATA IN CATEGORIES 2 AND 3
 C IN ADDITION TO THE ABOVE FACTS, THE USER SHOULD BE AWARE OF TWO
 C PROGRAM #CONSTANTS#. THE FIRST UNDER THE VARIABLE NAME NT IS THE NUM-
 C BER OF TIME VALUES PERMITTED. AT PRESENT THIS IS SET TO 100 (THE
 99 C DIMENSION OF THE TIME ARRAY TIM). ALSO NOTE THAT ALL THE TIME
 C DEFAULT VALUES ARE 7E30 EXCEPT THE FIRST AND THAT THE PROGRAM STOPS
 C AS SOON AS A SUCCEEDING TIME VALUE IS LESS THAN THE PRECEDING
 C TIME VALUE.
 95 C THE SECOND #CONSTANT# HAS TO DO WITH THE SIZE OF THE RECORD OUTPUTTED
 C BY TEMPS. THE SUBROUTINE RTAPE3 READS THE TEMPS OUTPUT UNDER THE
 C ASSUMPTION THAT ALL #BANTAL@ ARRAYS ARE OF DIMENSION 82 AND #AXIAL@
 C ARRAYS ARE OF DIMENSION 22. SEE COMMENTS WITHIN SUBROUTINE RTAPE3.
 C THE INTENSITY FUNCTION TKIRK IS DEFINED EXPLICITLY AS A FUNCTION OF
 C THE NONDIMENSIONAL VARIABLES U AND V AND IMPLICITLY AS A FUNCTION
 C OF NON-DIMENSIONAL TIME TAU THROUGH THE TIME DEPENDANT FUNCTIONS
 C PHI-THETA AND PHI-RHO AS DEFINED IN THE ABOVE REFERENCE. THESE
 C VARIABLES ARE PASSED THROUGH AN ARGUMENT LIST. ALL #PARAMETERS#
 C REQUIRED FOR EVALUATION OF TKIRK ARE PASSED THROUGH BLOCK COMMON
 C #PHIRLK#. THESE PARAMETERS ARE:
 105 C CS1P => C*S1R (SEE TKIRK COMMENTS)
 C CS2P => C*S2R "
 C CS1P => C*S1T "
 C CS2P => C*S2T "
 110 C XS => STARTING ARGUMENT FOR FUNCTIONS F1,F2 (SEE FUNCTION
 C PHI COMMENTS)
 C DX => INTERVAL BETWEEN EQUALLY-SPACED ARGUMENTS OF F1,F2
 C NF => NUMBER OF VALUES OF F1,F2
 C MNNT => MINT (SEE INPUT DATA)
 C EPP => EPS1 "
 115 C F1(20) => HOLDS VALUES OF F1 FROM TEMPS
 C F2(20) => HOLDS VALUES OF F2 FROM TEMPS
 C HOLD => STORES PHI-THETA (PHI-RHO AND PHI-THETA ARE EVALUATED
 C SIMULTANEOUSLY)
 C A => 1/SQRT(2)*STG (ALPHA IN THE ABOVE REFERENCE)
 120 C KE => WAVE NUMBER
 C TLAST => STORES TIME VALUE READ FROM TEMPS RECORD
 C TNEXT =>
 C IERR => ERROR INDICATOR FOR RTAPE3 (INDICATES OUT OF RANGE
 C TIME OR OUT OF SEQUENCE TIME)
 125 C TP => DEBUG OUTPUT #SWITCH#
 C MPI => =NF
 C ISW => SWITCH FOR GAUSSIAN INTEGRATION. WHEN ISW=1 THEN THE
 C X-VALUES FOR GAUSSIAN INTEGRATION ARE FOUND.
 C NGAUSS => NUMBER OF POINTS USED IN THE GAUSSIAN INTEGRATION
 130 C (NOTE THAT IF NGAUSS IS CHANGED THEN THE GAUSSIAN INTEGRATION
 C SUBROUTINE MUST ALSO BE CHANGED.)
 C RAD => WINDOW RADIUS
 C NP1 => NUMBER OF TEMPERATURE SAMPLES IN AXIAL DIRECTION
 C (USED FOR OUTPUTTING DISPLAY COMPATIBLE
 C TEMPERATURE DATA)
 135 C C3 => CONSTANT TO DIMENSIONALIZE TEMPERATURE DATA
 C FOR DISPLAY
 C C1 => CONSTANT USED TO DIMENSIONALIZE TIME FOR
 C RFAL, KTKRK, LAMBDA, NX, KE
 C RFAL, IKTPKP, IKIRK1
 C LOGICAL S
 C DIMENSION BUF(100)
 C COMMON/FILES/IT3,IT4,ITS,IT6,IT7,IT8
 C COMMON/BHRLK/CS1P,CS2P,CS1T,CS2T,XS,DX,NF,MNNT,EPP,F1(200),
 140 C +F2(200),HOLD,A,KE,TLAST,TNEXT,IERR,IP,MPI,ISW,NGAUSS,
 C +RAD,NP1,C3,C1,TERM,ERRORM
 C INTEGER DATAIN(100,3),DATAIN(100,3)
 C COMMON/BLOCK2/X0,X1,X2,RHOP1,RHOP2,MP,NP,TIM(10),EPS1
 C TEMPERATURE DISPLAY
 C ,MIN1,IPRNT,NGAUS,MODE,UMIN,UMAX,VMIN,VMAX,DUM(20),MSKIP,NSKIP
 C COMMON/BLOCK1/
 C ,T1,T2,T3,T4,T5,I6,I7,M,N,MI,NI,ICNT,IU,IQ,NO,NMA,TRUN,
 145 C +TCADD,IPPOINT,IPNCH,TTAP3,ITAP4,RHO12,ZED12,ZED12,DTAUD,
 C +TAUD,X,TAUOFF,SIG .00,IU0, EPS,G1(4),H1(4),MATER,NX,WETA,
 C

```

155      *K+LAMBDA,SIR+SIT,S2D,S2T,          001640
*DEN,CPA,EXPER,PW,R1,71,R2,IPLT,PROBNO,TICU,XLEN,YLEN,SCALEX, 001650
*SCALE,LEY1=SCALEY2,XTITLE(5)+YTITLE1(5),YTITLE2(5),NAME        001660
FOUTVALENCE(I1,DATAIN), (XU,DATAIN1)                         001670
DATA (DATAIN(I1,1),I=1,92)/7*2,80,20,3*1,0,1,2,11,100,4,6,6,3, 001680
+4,0,1,-0,-5546,1,1092,,0035,5,0,1,1292,2*0,,001,4*0,0,0,3*0,015, 001690
+3HCOL,1,4,7,4,8E-4,.0653,10,6,-.34E-5,.05E-5,.1E-5,-.1E-5,1,98, 001700
+.A91,1,278,1H1,24,7,41,1*1*1,4H204,.5,20,9,30,,1,1. 001710
+10HTIME(IFCON,3HDS),3*1H,10HTEMP-DEGC,10H ABOVE AMB, 001720
+3*1H,10HMEAN TEMO,10H ABOVE AMB,3*1H,7HBARRETT, 001730
165      +10HRADIAL DIS,10HTIME,PHO,10H(CM),1H,1H,10HAXIAL DIST. 001740
+10HANCE,7-(CM*1H),1H,1H / 001750
DATA (DATAIN(I1,2),I=1,92)/2H11,2H12,2H13,2H14,2H15, 001760
+2H16,2H17,1H1,2H18,2H19,4HICNT,2H1U,2H1Q,2HNO,3HNMX, 001770
+4H1,1H1,5HTCAPD,6HTPD,INT,5H1PNCH,5H1TA03,5H1TA04,4HRHO1, 001780
+5H1P012,1H7E01,5H7E01,5HUTAI9,5HTAUMX,6HTAUOFF,3HSIG, 001790
+2H0,2H11,3HFP5,5H01(1),5H01(2),5H01(4),5H01(1), 001800
+5H41(2),5H41(3),5H41(4),8HMATERIAL,8HREF,IND.,4HBETA, 001810
+8HTHERP,COND,6H1AMDA,3HS1K,3HS1T,3HS2R,3HS2T, 001820
+7HDENSITY,9HSPEC,HEAT,6HRADIUS,5HEXPER, 001830
+3HPO,8R,1H1,2H11,2H12,2H13,2H14,2H15, 001840
+4HXLIN,4HYLEN,7HXL SCALE,8HY1-SCALE,8HY2-SCALE,6HTITLE, 001850
+1H2,1H3,1H4,1H5,7HYTITLE1,1H2,1H3,1H4,1H5,7HYTITLE2,1H2, 001860
+1H3,1H4,1H5,8HOPEDATOR, 001870
+3HXT1,3HXT2,3HXT3,3HXT4,3HXT5,3HYT1,3HYT2,3HYT3,3HYT4, 001880
+3HYT5, 001890
DATA (DATAIN(I1,3),I=1,48)/22*0,19*1*-1,11*1,-1,1*4*0, 001900
+1,1*4*1,25*1/ 001910
DATA (DATAIN(I1,4),I=1,48)/1500..1000,..2000,..0..2,..100,100..10,.. 001920
+0*-1,..0*1,6,1,24,2,-40,..40,..0,..10,.. 001930
185      +1HHRKHF,1,10HTINTEN,1,1H,1H,10HTIME IN SE, 001940
+5HCONDS,1H,1H,1H,1H,10HNON-DIMENS,10HTONAL RADI,10HAL DISTANC, 001950
+THE,V,1H,10HNON-DIMENS,10HONAL AXIA,10HL DISTANCE,2H0,1H,5,5/ 001960
DATA (DATAIN(I1,5),I=1,48)/2H0,2H1,2H2,2H3,2H4,2H5,2H6,2H7,2H8,2H9,3H1U, 001970
+2H10,2H11,2H12,2H13,2H14,2H15, 001980
+4HEDS1,4HMINT,5H1ORTN,5HNGAU5,4HMODE,4HUMIN,4HUMAX, 001990
+4HV-IN,4HUMAX,3HST1,3HST2,3HS13,3HST4,3HST5,3HPT1,3HPT2, 002000
+3HPT3,3HPT4,3HPT5,3HYT1,3HYT2,3HYT3,3HYT4,3HYT5,3HYT1, 002010
+3HYT2,3HYT3,3HYT4,3HYT5,5HMSKP,5HNSKP/, 002020
DATA (DATAIN(I1,6),I=1,48)/5*1,2*0,11*1,4*1,20*-1,2*0/ 002030
DATA (IT1,IT4,IT5,IT6,IT7,IT8/3,4,5,6,7,8/ 002040
DATA (EPH,ERPM/0,1F-10/ 002050
INDYC=0 002060
S=.F. 002070
ISW=1 002080
200      NT=10 002090
CALC GETDATA(DATAIN,92,4,5,6,3,100,300,INUIC) 002100
CALC GETDATA(DATAIN,48,4,5,6,7,100,300,INUIC) 002110
IF (MODE .NE. 1) GOTO 150 002120
DATAIN(I1,7,1)=10HAXIAL DIS 002130
205      DATAIN(I1,8,1)=10HANCE,PHO 002140
DATAIN(I1,9,1)=10HDTIME (CM) 002150
DATAIN(I1,10,1)=10HAXIAL DIST 002160
DATAIN(I1,11,1)=10HANCE,1,RE 002170
DATAIN(I1,12,1)=10HACTIVE TO 002180
DATAIN(I1,13,1)=10HGAUSS FOCU 002190
DATAIN(I1,14,1)=7HS1 (CM) 002200
150      WRITE (IT7) DATAIN 002210
WRITE (IT7) DATAIN1 002220
IF (MODE .EQ. 1) S=.T. 002230
REWIND IT3 002240
READ (IT3) 002250
TLAST=TNEXT=0. 002260
K=2,2831E4/LAMBDA 002270
EPR=EPS1 002280
TOP=PRNT 002290
NGAIISS=NGAIISS 002300
KS=. 002310
DX=1./M 002320
MMIN=MINT 002330
MP1=M+1 002340
NFS=-P1 002350
IF (S1) GOTO 120 002360
XMAX=VMAX 002370
XMIN=VMIN 002380
GOTO 140 002390
120 XMIN=RH001 002400
XMAX=RH002 002410
140 CONTINUE 002420
A=.F./SIG 002430

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235	C=P*(INX#*2+1)/2,NY	002440
	C=C*R*RFA/3,14150/X	002450
	CS1D=C*S1R	002460
	CS2D=C*S2P	002470
	CS1T=C*S1T	002480
	CS2T=C*S2T	002490
240	RSD=R*R	002500
	X0=X0*100.	002510
	X1=V1*100.	002520
	X2=V2*100.	002530
245	C1E/RSD/DFN/CP	002540
	DEFY=(X2-X1)/(AMAX0(1,NP-1))	002550
	DELDHO=(RHOP2-RHOP1)/(AMAX0(1,MP-1))	002560
	DELV=(VMAX-VMIN)/(AMAX0(1,MP-1))	002570
	DELI=(UMAX-UMIN)/(AMAX0(1,NP-1))	002580
250	RAD=R	002590
	N01=N+1	002600
	CR=C/R	002610
	X0T=1./X0	002620
	NDE=1	002630
255	IT=1	002640
	TR=IT*TIM(1)	002650
	IF (T .LT. 0.) GOTO 2000	002660
	IF (TP.EQ.2) WRITE(TTR) DATATN	002670
1000	T=T+CI	002680
260	WRITE(IT,?) T	002690
	IF (T .GT. TAUMX) GOTO 2000	002700
	XIT=X1	002710
	XIT=1./XIT	002720
	U=U*IN	002730
265	DO 100 IT=1,MP	002740
	CX=(X0*XIT)**2	002745
	IF (S) U=KE*RSD*(X0T-X1T)	002750
	RHOD=RHOP)	002760
	V=V*IN	002770
270	DO 110 J=1,MP	002780
	IF (S) V=KE*R*XIT*RHOP	002790
	RHF(J)=CX*IKTRK(U,V,T)	002800
	IF (IERR .NE. 0) GOTO 2000	002810
210	RHOD=RHOD+DEL(RHO)	002820
	V=V+DELV	002830
275	110 CONTINUE	002840
	WRITE (IT7, I+NP,1,TP,MP,XMIN,XMAX,(RHF(J)+J=1,MP)	002850
	CALL PRT(RHF,MODE,I,TT,MP,NP,NSK1P,NSK1P,RHOP1,	002860
	+DELDHO,VUTN,DELV,Y T,U,TR+I,T16)	002870
280	NREC=NREC+1	002880
	XIT=X1T*DFLX	002890
	XIT=1./XIT	002900
	U=U+DFLU	002910
110	CONTINUE	002920
285	IT=IT+1	002930
	IF (IT .GT. NT) GOTO 2000	002940
	TR=IT*TIM(1)	002950
	IF (T .GT. TIM(IT-1)) GOTO 1000	002960
2000	WRITE(ITS,1) NREC	002970
	WRITE(ITS,6) TEP,ERROH	002980
1	FORMAT(IY,* THE NUMBER OF RECORDS IS-* ,110)	002990
2	FORMAT(IY,* NEW VALUE OF TAU IS-* E13.5)	003000
3	FORMAT(IY,I6.4E12.4)	003010
4	FORMAT(IY,4E13.5)	003020
5	FORMAT(IY,I6.4E12.4,7(/,5X,SG13.5))	003030
6	FORMAT(* MAX ERROR DAPM= *14* EST ABS. ERROR INTEG.= *E16.4)	003040
	END	003050

D.2 Major Function IKIRK Pertaining to Option No. 3 (IKIRK1)

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1      REAL FUNCTION IKIRK(IIV,V,T)          014800
COMMON/PHTBLK/CS1D,CS2R,CS1T,CS2T,XS,DZ,NF,MINT,EPS,F1(200), 014810
+FP(200),HOLD,A,KTLAST,TNEXT,IERR,IP,MP1,ISW,N, 014820
+RAD,NP1,C3,C1,IERM,ERRORM 014830
COMMON/IIV/I1,V1 014835
EXTERNAL FREAL1,FTMAG1,FRREAL2,FMAG2 014840
DATA AERO,RERR/R1E-3,1E-6/ 014850
I1=U 014852
V1=V 014854
A2=A*A 014860
IF (A2 .GT. 220.) 1020,1030 014870
1020 CONST=2.*A2*A2 014880
GOTO 1040 014890
1030 CONST=2.*((A2/(1.-EXP(-A2)))**2 014900
1040 CALL RTAPE3(T) 014910
IF (IERR .NE. 0) GOTO 2000 014920
YRI=DCADRE(FREAL1,0.,1.,AERR,HERR+ERROR,IER) 014930
IF (ERRO=DCADRE(FTMAG1,0.,1.,AERR,HERR+ERROR,IER) 014940
IF (ERRO=DCADRE(FIMAG2,0.,1.,AERR,HERR+ERROR,IER) 014950
IF (IERR .GT. IERM) IERM=IER 014960
YTI=DCADRE(FIMAG1,0.,1.,AERR,HERR+ERROR,IER) 014970
IF (ERRO=DCADRE(FIMAG2,0.,1.,AERR,HERR+ERROR,IER) 014980
IF (IERR .GT. IERM) IERM=IER 014990
ZRI=DCADRE(FREAL2,0.,1.,AERR,HERR+ERROR,IER) 015000
IF (ERRO=DCADRE(FIMAG1,0.,1.,AERR,HERR+ERROR,IER) 015010
IF (IERR .GT. IERM) IERM=IER 015020
ZTI=DCADRE(FIMAG2,0.,1.,AERR,HERR+ERROR,IER) 015030
IF (ERRO=DCADRE(FIMAG1,0.,1.,AERR,HERR+ERROR,IER) 015040
IF (IERR .GT. IERM) IERM=IER 015050
30    (K1K=CONST*(YRI*YTI+YIT*YII+ZRI*ZII+ZTI*ZII)
2000 RETURN 015060
END 015070

```

D.3 Function FREAL1

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1      FUNCTION FREAL1(X)          015080
COMMON/IIV/I1,V 015090
COMMON/PHTBLK/CS1D,CS2R,CS1T,CS2T,XS,DZ,NF,MINT,EPS,F1(200), 015100
+FP(200),HOLD,A,KTLAST,TNEXT,IERR,IP,MP1,ISW,N, 015110
+RAD,NP1,C3,C1,IERM,ERRORM 015120
COMPLEX O1,EXPR,EXPT,FX,FY,FZ,FW 015130
RFA1=.J0,.11,K 015140
A2=A*A 015150
I1D2=.5*I1 015152
ISW=1 015154
GOTO 100 015156
100   ENTRY FTMAG1 015158
ISW=2 015160
GOTO 100 015162
100   ENTRY FRREAL2 015164
ISW=3 015170
GOTO 100 015172
100   ENTRY FMAG2 015174
ISW=4 015180
X2=X*X 015182
XV=Y*Y 015184
FX=CEXP(-42*X2)*CMPLX(0E0,-0H2*X2) 015190
EXPO=CEXP(CMPLX(0=0,K*PHI(X))) 015200
EXPT=CEXP(CMPLX(0=0,K*HOLD)) 015210
IF (V .EQ. 0.) FZ=(EXPR-EXPT)*X/2. 015220
IF (V .NE. 0.) FZ=(EXPR-EXPT)*J1(XV)/V 015230
Q1=Y*J0(XV) 015240
GOTO (110,120,130,140) ISW 015242
110  FX=O1*EXPR-FZ 015250

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30	FREAL1=WFAL(FW*FX1)	015255
	RFTURN	015257
120	FX=1*EXP0-FZ	015260
	FREAL1=ATMAG(FW*FX)	015270
	RETURN	015280
35	130 FY=1*EXP0+FZ	015300
	FREAL1=RFAI(FW*FY)	015310
	RFTURN	015320
140	FY=1*EXP0+FZ	015340
	FREAL1=ATMAG(FW*FY)	015350
40	RETURN	015390
	END	015400

D.4 Function DCADRE

1	FUNCTION DCADRE (F,A+B,AERR,RERR,ERROR,IER)	015450
C	C-DCADRE-----S-----LTDREADY 3-----	015460
C	C FUNCTION	015470
C	C - INTEGRATE F(X) FROM A TO B, USING CAUTIOUS	015480
C	C ADAPTIVE ROMBERG EXTRAPOLATION.	015490
C	C USAGE	015500
C	C PARAMETERS DCADRE - ESTIMATE OF THE INTEGRAL OF F(X) FROM A TO B.	015510
C	C F - A SINGLE-ARGUMENT REAL FUNCTION SUBPROGRAM	015520
C	C SUPPLIED BY THE USER. F MUST BE DECLARED	015530
C	C EXTERNAL IN THE CALLING PROGRAM.	015540
C	C A+B - THE TWO ENDPOINTS OF THE INTERVAL OF	015550
C	C INTEGRATION. (INPUT)	015560
C	C AERR - DESIRED ABSOLUTE ERROR IN THE ANSWER. (INPUT)	015570
C	C RERR - DESIRED RELATIVE ERROR IN THE ANSWER. (INPUT)	015580
C	C ERROR - ESTIMATED BOUND ON THE ABSOLUTE ERROR OF	015590
C	C THE OUTPUT NUMBER. DCADRE.	015600
C	C IER - ERROR PARAMETER	015610
C	C WARNING ERROR(WITH FIX) = 64 + N	015620
C	C N = 1 IMPLIES THAT ONE OR MORE SINGULARITIES	015630
C	C WERE SUCCESSFULLY HANDLED.	015640
C	C N = 2 IMPLIES THAT, IN SOME SUBINTERVAL(S),	015650
C	C THE ESTIMATE OF THE INTEGRAL WAS ACCEPTED	015660
C	C MERELY BECAUSE THE ESTIMATED ERROR WAS	015670
C	C SMALL, EVEN THOUGH NO REGULAR BEHAVIOR	015680
C	C WAS RECOGNIZED.	015690
C	C TERMINAL ERROR = 128 + N	015700
C	C N = 3 -- FAILURE DUE TO INSUFFICIENT	015710
C	C INTERNAL WORKING STORAGE.	015720
C	C N = 4 -- FAILURE. THIS MAY BE DUE TO TOO	015730
C	C MUCH NOISE IN THE FUNCTION (RELATIVE	015740
C	C TO THE GIVEN ERROR REQUIREMENTS) OR	015750
C	C DUE TO AN ILL-BEHAVED INTEGRAND.	015760
C	C N = 5 INDICATES THAT RERR IS GREATER THAN	015770
C	C 0.1, OR RERR IS LESS THAN 0.0, OR RERR	015780
C	C IS TOO SMALL FOR THE PRECISION OF THE	015790
C	C MACHINE.	015800
C	C PRECISION - SINGLE	015810
C	C READ. IMSL ROUTINES - IFERTS	015820
C	C LANGUAGE - FORTRAN	015830
C	C-----	015840
C	C LATEST REVISION - SEPTEMBER 17, 1974	015850
C	C-----	015860
45	DIMENSION T(10,10),R(10),AIT(10),DIF(10),RN(4),TS(2049)	015870
	TREGS(30),BEGIN(30),FINIS(30),EST(30)	015880
	REGLSV(30)	015890
	H2CONV,ATKLEN,RIGHT,REGLAR,REGLSV	015900
	LNGTH,JUMPTL	015910
	ATTLOW,H2TUL,AITTOL,JUMPTL,MAXTS,MAXTL,MXSTGE	015920
	/1.1,.15,.1,.01,2049+10+30/	015930
50	DATA RN(1),RN(2),RN(3),RN(4)/	015940
	.7142005,.3466282,.843751,.1263305/	015950
	ZERO,PI,HALF,ONE,TWO,FOUR,FOURPS,TFN,HUN	015960
	/0.0.0+1.0,51.0+2.0,4.0,4.5,10.0+100.0/	015970
55	ALG402 = ALGIO(TWO)	015980
	CADRE = ZERO	015990
	ERROR = FRO	016000
		016010

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60      CIRFST = ZERO          016020
       VINT = ZERO          016030
       IFO = 0
       LENGTH = ABS(B-A)
       IF (LENGTH .EQ. ZERO) GO TO 215
       IF (RERR .GT. PI .OR. RERR .LT. ZERO) GO TO 210
       IF (RERR .EQ. ZERO .AND. (RERR+HIN) .LE. HUN) GO TO 210
65      FEND = RERR
       ERRA = ABS(AERR)
       STEPMN = (LENGTH/FLOAT(2**MXSIGE))
       STEPMN = AMAX1((LENGTH+ABS(A)+ABS(B))/TEN
       STAGE = HALF
70      IStage = 1
       FNsize = ZERO
       DREVER = ZERO
       RFGLAR = .FALSE.
       THE GIVEN INTERVAL OF INTEGRATION
       IS THE FIRST INTERVAL CONSIDERED.
75      C      C
       REG = A
       FREG = F(REG)*HALF
       TS(1) = FREG
       TREG = 1
80      END = B
       FFEND = F(FEND)*HALF
       TS(2) = FFEND
       IFEND = 2
       ERIGHT = .FALSE.
       INVESTIGATION OF A PARTICULAR
       SUBINTERVAL BEGINS AT THIS POINT.
85      C      C
       10 STEP = END - REG
       ASTEP = ABS(STEP)
       IF (ASTEP .LT. STEPMN) GO TO 205
       IF (STEPMN+ASTEP .LE. STEPMN) GO TO 205
       T(L,1) = FREG + FFEND
       TABS = ABS(FREG) + ABS(FFEND)
       L = 1
       N = 1
90      H2CONV = .FALSE.
       ATTKEN = .FALSE.
       15 LMI = L
       L = L + 1
       CALCULATE THE NEXT TRAPEZOID SUM,
       T(L,1), WHICH IS BASED ON *N2* + 1
       EQUISPACED POINTS. HERE.
       N2 = N*2 + 2*(L-1).
100     C      C
       NP = N*N
       FN = N2
       105 ISTEP = (IFEND - TREG)/N
       IF (ISTEP .GT. 1) GO TO 25
       IT = IFEND
       IFEND = IFEND + N
       IF (IFEND .GT. MAXTS) GO TO 200
       HUVN = STEP/FN
       ITI = IFEND
       FT = ONE
       DO 20 I=1,N*2
         TS(ITI) = TS(IT)
         TS(ITI-1) = F(IFEND - FT * HUVN)
         FT = FT+TWO
         ITI = ITI-2
         IT = IT-1
       20 CONTINUE
120      25 ISTEP2 = THEG + ISTEP/2
       SUM = ZERO
       SUMABS = ZERO
       DO 20 I=ISTEP2,IFEND-ISTEP
         SUM = SUM + TS(I)
         SUMABS = SUMABS + ABS(TS(I))
       30 CONTINUE
       T(L,1) = T(L-1+1)*HALF+SUM/FN
       TABS = TABS+HALF+SUMABS/FN
       ASTP = ASTEP*TABS
       N = N2

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C           GET PRELIMINARY VALUE FOR *VINT*
C           FROM LAST TRAPEZOID SUM AND UPDATE      016760
C           THE ERROR REQUIREMENT *ERGOAL*        016770
C           FOR THIS SUBINTERVAL.                  016780
135      C           IT = 1                                016790
C           VINT = STEP*T(L,1)                      016800
C           TABTLM = TABS*TEN                      016810
C           FNSTZE = AMAX1(FNSTZE,ARS(T(L+1)))    016820
C           FOGI = ASTEP*FNSTZE*TEN                016830
C           ERGOAL = STAGE*AMAX1(ERRA,EROR*ARS(CUREST+VINT)) 016840
C           COMPLETE ROW L AND COLUMN L OF *T*      016850
C           ARRAY.                                016860
C           FEXTRP = ONE                           016870
140      C           DO 75 I=1,LM1                   016880
C               FEXTDP = FEXTRP*FOUR
C               T(I,1) = T(L,I) - T(L-1,I)
C               T(L,I+1) = T(L,I) + T(L,L)/(FEXTRP-ONE)
C           35 CONTINUE
C           ERER = ASTEP*ABS(T(1,L))                 016890
C           PRELIMINARY DECISION PROCEDURE
C           IF L = 2 AND T(2,1) = T(1,1),
C           GO TO 135 TO FOLLOW UP THE          016900
C           IMPRESSION THAT INTEGRAND IS          016910
C           STRAIGHT LINE.                         016920
145      C           IF (L .GT. 2) GO TO 40            016930
C           IF (TABS+P1*ABS(T(1,2)) .EQ. TABS) GO TO 135 016940
C           GO TO 15                                016950
C           CALCULATE NEXT RATIOS FOR          016960
C           COLUMNS 1,...,L-2 OF T-TABLE          016970
C           RATIO IS SET TO ZERO IF DIFFERENCE 016980
C           IN LAST TWO ENTRIES OF COLUMN IS      016990
C           ABOUT ZERO.                          017000
150      C           40 DO 45 I=2,LM1                   017010
C               DIFF = ZERO                      017020
C               IF (TABTLM+ARS(T(I-1,L)) .NE. TABTLM) DIFF = T(I-1,LM1)/T(I-1,L)
C               T(I-1,LM1) = DIFF                017030
C           45 CONTINUE
C           IF (ARS(FOUR-T(1,LM1)) .LE. 2*TOL) GO TO 60 017040
155      C           IF (T(1,LM1) .EQ. ZERO) GO TO 55 017050
C           IF (ARS(TWO-ABS(T(1,LM1))) .LT. JUMPTL) GO TO 130 017060
C           IF (L .EQ. 3) GO TO 15                017070
C           H2CONV = .FALSE.
C           IF (ARS((T(1,LM1)-T(1,L-2))/T(1,LM1)) .LE. ATTOL) GO TO 75 017080
160      C           50 IF (REGL1R) GO TO 55            017090
C           IF (L .EQ. 4) GO TO 15                017100
C           55 IF (ERRER .GT. ERGOAL .AND. (ERGL+ERRER) .NE. ERGL) GO TO 175 017110
C           GO TO 145                                017120
C           CAUTIOUS ROMBERG EXTRAPOLATION       017130
165      C           60 IF (H2CONV) GO TO 65            017140
C           ATTEN = .FALSE.
C           H2CONV = .TRUE.                      017150
C           65 FEXTRP = FOUR                     017160
C           70 IT = IT + 1                        017170
170      C           VINT = STEP*T(L,IT)              017180
C           ERRER = ARS(STEP/(FEXTRP-ONE)*T(IT-1,L))
C           IF (ERRER .LE. ERGOAL) GO TO 160 017190
C           IF (ERGL+ERRER .EQ. ERGL) GO TO 160 017200
C           IF (IT .EQ. LM1) GO TO 125            017210
C           50 IF (T(IT,LM1) .EQ. ZERO) GO TO 70 017220
C           55 IF (T(IT,LM1) .LE. FEXTRP) GO TO 125 017230
C           IF (ABS(T(IT,LM1))/FOUR-FEXTRP) .LT. ATTOL 017240
C           1     FEXTRP = FEXTDP*FOUR            017250
C           GO TO 70                                017260
175      C           INTEGRAND MAY HAVE X**ALPHA TYPE 017270
C           SINGULARITY
C           RESULTING IN A RATIO OF *SING* = 017280
C           2** (ALPHA + 1)                      017290
C           75 IF (T(1,LM1) .LT. ATTLOW) GO TO 175 017300
200      C           IF (ATTEN) GO TO 80            017310
C           H2CONV = .FALSE.
C           ATTEN = .TRUE.                      017320
C           80 FEXTRP = T(L-2,LM1)                017330
C           IF (FEXTDP .GT. FOUR05) GO TO 65 017340
C           IF (FEXTDP .LT. ATTLOW) GO TO 175 017350
C           IF (ABS(FEXTRP-T(1,3,LM1))/T(1,LM1) .GT. H2TOL) GO TO 175 017360
C           SING = FEXTRP                      017370
C           FEXTM1 = ONE/(FEXTRP - ONE)          017380
C           ATT(1) = ZERO.                      017390
205      C           75 IF (T(1,LM1) .LT. ATTLOW) GO TO 175 017400
C           IF (ATTEN) GO TO 80            017410
C           H2CONV = .FALSE.
C           ATTEN = .TRUE.                      017420
C           80 FEXTRP = T(L-2,LM1)                017430
C           IF (FEXTDP .GT. FOUR05) GO TO 65 017440
C           IF (FEXTDP .LT. ATTLOW) GO TO 175 017450
C           IF (ABS(FEXTRP-T(1,3,LM1))/T(1,LM1) .GT. H2TOL) GO TO 175 017460
C           SING = FEXTRP                      017470
C           FEXTM1 = ONE/(FEXTRP - ONE)          017480
C           ATT(1) = ZERO.                      017490
210      C           75 IF (T(1,LM1) .LT. ATTLOW) GO TO 175 017500
C           IF (ATTEN) GO TO 80            017510
C           H2CONV = .FALSE.
C           ATTEN = .TRUE.                      017520
C           80 FEXTRP = T(L-2,LM1)                017530

```

```

210      DO 85 I=2,L          017540
         AIT(I) = T(I,I) + (T(I,I)-T(I-1,I))*FEXTM1 017550
         R(I) = T(I,I-1) 017560
         DIF(I) = AIT(I) - AIT(I-1) 017570
85 CONTINUE 017580
215      IT = 2 017590
90 VINT = STEP*AIT(L) 017600
         ERER = FPPER*FEXTM1 017610
         IF (ERER .GT. EPGOAL .AND. (ERGL+ERRER) .NE. ERGL) GO TO 95 017620
         ALGJA = ALOG10(STNG1)/ALG402 - ONE 017630
         TER = MAX0(IER,55) 017640
220      GO TO 160 017650
         95 IT = IT + 1 017660
         IF (IT .EQ. LML) GO TO 125 017670
         IF (IT .GT. 3) GO TO 100 017680
225      H2NEXT = FOURP 017690
         STNGNX = SING+SING 017700
100      IF (H2NEXT .LT. STNGNX) GO TO 105 017710
         FEXTRD = SINGNX 017720
         STNGNX = STNGNX+SINGNX 017730
230      GO TO 110 017740
105      FEXTRP = H2NEXT 017750
         H2NEXT = FOURP*H2NEXT 017760
110      DO 115 I=IT+1,L 017770
         P(I+1) = ZERO 017780
         TF (TABTLM+A-S/DTF(I+1)) .NE. TABTLM R(I+1) = DIF(I)/DIF(I+1) 017790
115      CONTINUE 017800
         H2TFLX = -H2TOL*FEXTPP 017810
         IF (R(I,L) - FEXTPP .LT. H2TFLX) GO TO 125 017820
         IF (R(I,L-1)-FEXTPP .LT. H2TFLX) GO TO 125 017830
240      ERER = ASTEP*AHS(DTF(L)) 017840
         FEXTM1 = ONE/(FEXTRD - ONE) 017850
         DO 120 I=IT+1,L 017860
         AIT(I) = AIT(I) + DIF(I)*FEXTM1 017870
         DIF(I) = AIT(I) - AIT(I-1) 017880
245      120 CONTINUE 017890
         GO TO 40 017900
C               CURRENT TRAPEZOID SUM AND RESULTING 017910
C               EXTRAPOLATED VALUES DID NOT GIVE 017920
C               A SMALL ENOUGH *ERRER*. 017930
250      C               NOTE -- HAVING PREVER .LT. ERER 017940
C               IS AN ALMOST CERTAIN SIGN OF 017950
C               BEGINNING TROUBLE WITH IN THE FUNC- 017960
C               TION VALUES. HENCE, A WATCH FOR, 017970
C               AND CONTROL OF, NOISE SHOULD 017980
C               BEGIN HERE. 017990
255      125 FEXTRP = AMAX1(PREVFR/ERRER,AITLOW) 018000
         PREVFR = FPPER 018010
         IF (L .LT. 5) GO TO 15 018020
         IF (L-IT .GT. 2 .AND. ISTAGE .LT. MXSTGE) GO TO 170 018030
         ERER = FPPER/(FEXTOP*(MAXTR-L)) 018040
         IF (ERER .GT. EPGOAL .AND. (ERGL+ERRER) .NE. EPGL) GO TO 170 018050
         GO TO 15 018060
260      C               INTEGRAND HAS JUMP (SEE NOTES) 018070
         130 IF (FPPER .GT. EPGOAL .AND. (ERGL+ERRER) .NE. EPGL) GO TO 170 018080
265      C               NOTE THAT 2*FN = 2*L 018090
         DTFF = ABS(T(I+1,I)*(FN+FN)) 018100
         GO TO 160 018110
270      C               INTEGRAND IS STRAIGHT LINE 018120
         C               TEST THIS ASSUMPTION BY COMPARING 018130
         C               THE VALUE OF THE INTEGRAND AT 018140
         C               FOUR RANDOMLY CHOSEN POINTS WITH 018150
         C               THE VALUE OF THE STRAIGHT LINE 018160
         C               INTERPOLATING THE INTEGRAND AT THE 018170
         C               TWO END POINTS OF THE SUB-INTERVAL. 018180
         C               IF TEST IS PASSED, ACCEPT *VINT*. 018190
275      135 SLOPE = (FFEND-FBEG)*TWO 018200
         FBEG2 = FBEG+FBEG 018210
         GO 140 I=1,4 018220
         DTFF = ABS(F(HFG+RN(I)*STEP) - FBEG2-RN(I)*SLOPE) 018230
280      140 IF (TABTLM+DTFF .NE. TABTLM) GO TO 155 018240
         140 CONTINUE 018250
         GO TO 160 018260
285      C               NOISE MAY BE DOMINANT FEATURE 018270
         C               ESTIMATE NOISE LEVEL BY COMPARING 018280
         C               THE VALUE OF THE INTEGRAND AT 018290

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C FOUR *RANDOMLY CHOSEN* POINTS WITH 018300
 C THE VALUE OF THE STRAIGHT LINE 018310
 C INTERPOLATING THE INTEGRAND AT THE 018320
 C TWO ENDPOINTS. IF SMALL ENOUGH, 018330
 C ACCEPT *VINT*. 018340
 C 018350
 299 C 018360
 C 145 SLOPE = (FFEND-FREG) * TWO 018370
 C FREG2 = FREG+FREG 018380
 C I = 1 018390
 C 150 DIFE = ABS(F(BEG+DN(I)*STEP) - FREG2-RN(I)*SLOPE) 018400
 295 C 155 ERROR = MAX1(ERROR,ASTEP*DIFE) 018410
 C IF (ERROR .GT. ERGOAL .AND. (ERGL+ERROR) .NE. EPGL) GO TO 175 018420
 C I = I+1 018430
 C IF (I .LE. 4) GO TO 150 018440
 C TFR = 66
 300 C INTERGRATION OVER CURRENT SUB- 018450
 C INTERVAL SUCCESSFUL 018460
 C ADD *VINT* TO *CADRE* AND *ERROR* 018470
 C TO *ERROR*, THEN SET UP NEXT SUB- 018480
 C INTERVAL, IF ANY. 018490
 305 C 160 CADRE = CADRE + VINT 018500
 C ERROR = ERROR + FREG 018510
 C IF (RIGHT) GO TO 165 018520
 C ISTAGE = 1STAGE - 1 018530
 C IF (ISTAGE .EQ. 0) GO TO 220 018540
 C REGULAR = REGLSV(1STAGE) 018550
 C REG = BEGIN(1STAGE) 018560
 C END = FINIS(1STAGE) 018570
 C CUREST = CUREST - FST(1STAGE+1) + VINT 018580
 C IEND = TREG - 1 018590
 C FFEND = TS(IEND) 018600
 C TREG = TREGS(1STAGE) 018610
 C GO TO 181 018620
 C 165 CUREST = CUREST + VINT 018630
 C STAGE = STAGE*STAGE 018640
 C IEND = TREG 018650
 C TREG = TREGS(1STAGE) 018660
 C END = REG 018670
 C REG = BEGIN(1STAGE) 018680
 C FFEND = FREG 018690
 C FREG = TS(TREG) 018700
 C GO TO 5
 C INTEGRATION OVER CURRENT SUBINTERVAL 018710
 C IS UNSUCCESSFUL. MARK SUBINTERVAL 018720
 C FOR FURTHER SUBDIVISION. SET UP 018730
 C NEXT SUBINTERVAL. 018740
 C 018750
 330 C 170 REGULAR = .TRUE. 018760
 C 175 IF (1STAGE .EQ. MAXSTG) GO TO 205 018770
 C IF (RIGHT) GO TO 185 018780
 C REGLSV(1STAGE+1) = REGULAR 018790
 C BEGIN(1STAGE) = REG 018800
 C TREGS(1STAGE) = TREG 018810
 C STAGE = STAGE*HALF 018820
 C 180 OUTLT = .TRUE. 018830
 C REG = (REG+END)*HALF 018840
 C TREG = (TREG+IEND)/2 018850
 C TS(TREG) = TS(TREG)*HALF 018860
 C FREG = TS(TREG) 018870
 C GO TO 10 018880
 C 185 NLEFT = TREG - TREGS(1STAGE) 018890
 C IF (IEND+NLEFT .GE. MAXTS) GO TO 200 018900
 C ITI = TREGS(1STAGE) 018910
 C IT = TEND 018920
 C DO 190 IT=ITI+1,BEG 018930
 C IT = IT + 1 018940
 C TS(ITI) = TS(IT) 018950
 C 190 CONTINUE 018960
 C DO 195 IT=IREG+IT 018970
 C TS(ITI) = TS(IT) 018980
 C ITI = ITI + 1 018990
 C 195 CONTINUE 019000
 C IEND = TEND + 1 019010
 C TREG = TEND - NLEFT 019020
 C FFEND = FREG 019030
 C FINIS(1STAGE) = END 019040
 C END = REG 019050
 C REG = BEGIN(1STAGE) 019060
 C BEGIN(1STAGE) = END 019070
 C REGLSV(1STAGE) = REGULAR 019080

365	ISTAGE = ISTAGE + 1 RFLGAR = RFLGSLV(ISTAGE) EST(ISTAGE) = VINT CUREST = CUREST + EST(ISTAGE) GO TO 5	019090 019100 019110 019120 019130
370	C C	FAILURE TO HANDLE GIVEN INTEGRA- TION PROBLEM
375	206 IER = 131 GO TO 215 205 IER = 132 GO TO 215 210 IER = 133 215 CADRE = CUREST + VINT 220 DCADRE = CADRE 9400 CONTINUE IF (IER .NE. 0) CALL UERTST (IER,6HDCADRE) 9405 RETURN END	019140 019150 019160 019170 019180 019190 019200 019210 019220 019230 019240 019250 019260

D.5 Subroutine UERTST

1	SUBROUTINE UERTST (IER,NAME)	019270 019280 019290 019300
5	C-UERTST-----LITERALLY 3----- C C FUNCTION - ERROR MESSAGE GENERATION C USAGE - CALL UERTST(IER,NAME) C PARAMETERS IER - ERROR PARAMETER, TYPE + N WHERE C TYPE= 12B TMPLIFS TERMINAL ERROR C 64 TMPLIFS WARNING WITH FIX C 32 TMPLIFS WARNING C N = ERROR CODE RELEVANT TO CALLING ROUTINE C NAME - INPUT SCALAR CONTAINING THE NAME OF THE C CALLING ROUTINE AS A 6-CHARACTER LITERAL C STRING. C LANGUAGE - FORTRAN C----- C LATEST REVISION - AUGUST 1, 1973	019310 019320 019330 019340 019350 019360 019370 019380 019390 019400 019410 019420 019430 019440 019450 019460 019470 019480 019490 019500 019510 019520 019530 019540 019550 019560 019570 019580 019590 019600 019610 019620 019630 019640 019650 019660 019670 019680 019690 019700 019710 019720 019730 019740 019750 01977
20	DIMENSION ITYP(2*4),IBIT(4) INTEGER ITERM,PRINTR EQUVALENCE DATA ITYP * /10HWARNING* .10H * 10HWARNING(WI*10HTH FIX) . * 10HTERMINAL* .10H * 10HNON-DEFINE*10H . * TRIT / 32.64*128*0/ DATA PRINTR/6LOUTPUT/	019470 019480 019490 019500 019510 019520 019530 019540 019550 019560 019570 019580 019590 019600 019610 019620 019630 019640 019650 019660 019670 019680 019690 019700 019710 019720 019730 019740 019750 01977
25	IF (IER2 .GE. WARM) GO TO 5 C IER1=4 GO TO 20 5 IF (IER2 .LT. TERM) GO TO 10 C IER1=3 GO TO 20 10 IF (IER2 .LT. WARE) GO TO 15 C IER1=2 GO TO 20 C 15 IER1=1 C 20 IER2=IER2-IBIT(IER1) C WRITE (PRINTR+25) (ITYP(I+IER1)-I=1,2),NAME,IER2,IER 25 FORMAT(26H *** T M S L(UERTST) *** ,2A10,4X,A6,4X,I2, 1 AH (IER = ,I3+1H)) RETURN END	019640 019650 019660 019670 019680 019690 019700 019710 019720 019730 019740 019750 01977
30	NON-DEFINED	019560 019570 019580 019590 019600 019610 019620 019630 019640 019650 019660 019670 019680 019690 019700 019710 019720 019730 019740 019750 01977
35	TERMINAL.	019600 019610 019620 019630 019640 019650 019660 019670 019680 019690 019700 019710 019720 019730 019740 019750 01977
40	WARNING	019640 019650 019660 019670 019680 019690 019700 019710 019720 019730 019740 019750 01977
45	EXTRACT *N*	019690 019700 019710 019720 019730 019740 019750 01977
50	PRINT ERROR MESSAGE	019710 019720 019730 019740 019750 01977

D.6 Major Function IKIRK Pertaining to Option No. 1 (IKIRK)

```

1      REAL FUNCTION IKIRK(U,V,T)                                000100
C FUNCTION IKIRK IS THE KIRKHOFF INTENSITY FUNCTION DESCRIBED IN
C -BENDOW,B. AND GIANINO,P. @OPTICAL PERFORMANCE EVALUATION OF
C INFRARED TRANSMITTING WINDOWSM AFTRL-72-0565. ASSUMING A GAUSSIAN
5     SHAPED UNPOLARIZED SOURCE, THE INTENSITY FUNCTION CAN BE WRITTEN*
C   IKIRK(U,V)=2(A12/(1-EXP(-A12)))*2*(II(0+,DX)*(FW*FX))!2*
C   1T(0,1*DX)*(FW*FY))!2                               000110
C WHERE*                                              000120
C   FW(V!)=EXP(-(A*X!)2)*EXP(-I*U*X!/2/2)                000130
10    FX(V)=X*J0(X*V)*EXP(I*K*PHI(X))-FZ(X,V)           000140
C   FY(X,V)=X*J0(X*V)*EXP(I*K*PHI(X))+FZ(X,V)           000150
C   FZ(X,V)=1(X*V)*(EXP(I*K*PHIR(X))-EXP(I*K*PHIT(X)))/(V)
C   A=1/SORT(2)/SIG**2                                     000160
C   K=WAVE NO. (OMEGA/C)                                    000170
15    NOTATIONS*                                           000180
C   ! => EXPONENTIATION
C   I => @IMAGINARY
C   I(0,1,DX)() MEANS INTEGRATION OF THE FUNCTION WITHIN () W.R.T.X
C   OVER THE INTERVAL (0,1).                                000190
20    J0 AND J1 ARE BESSEL FUNCTIONS OF THE FIRST KIND,ZEROTH AND FIRST
C ORDER RESPECTIVELY.
C   PHIR(X) AND PHIT(X) ARE THE FUNCTIONS PHI-SUPERSCRIPT-RHO AND PHI-
C S-PHI-SUPERSCRIPT-THETA RESPECTIVELY IN THE ABOVE REFERENCE.
C   THESE FUNCTIONS ARE GIVEN BY*
25    C PHIR(X)=C*S1*F1(X)+4*C*S2R*F2(X)                  000200
C   PHIT(X)=C*S1*T*F1(X)+4*C*S2T*F2(X)                  000210
C WHERE*                                              000220
C   C=R*3*PO*BETA/KT                                      000230
C   R=WINDOW RADUS (CM)                                    000240
30    C PO=MEAN INCIDENT POWER DENSITY (WATTS/CM!2)          000250
C   BFTA=BULK ABSORPTION COEFFICIENT (1/CM)                 000260
C   KT=THERMAL CONDUCTIVITY (WATT)/(CM DEG C)              000270
C   S1,S2R,S1T,S2T ARE MATERIAL CONSTANTS DEFINED IN THE ABOVE REF.
C   F1,F2 ARE THE FUNCTIONS DELTRAR-PRIME(X) AND
35    (1/X!2)!1(0,X,DS1)(DELTRAR-PRIME(S))                000280
C   GIVEN IN THE ABOVE REFERENCE AND WHICH ARE PROVIDED AT SELECTED
C   ARGUMENTS BY PROGRAM @TEMPS@.                            000290
*****@*****@*****@*****@*****@*****@*****@*****@*****@*****@*****@*****
COMMON/PUBLK/CS1,P,CS2R,CS1T,CS2T,XS,DZ,NF,MINT,EPS,F1(20),
40    +F2(200),HOLD,A,K ,TLAST,TNEXT,IERR,IP,MP1,ISW,N,
+RAD,NP1,C3,C1,IFRM,ERRORM
COMMON/FILES/IT3,IT4,IT5+IT6+IT7+IT8
COMMON/UV/UU,VV
COMPLEX Q1,EXPR,EXPT,FX,FY,FZ,FW
45    REAL J0,J1
REAL K
DIMENSION XA(100),YR(100)*YI(100),ZR(100),ZI(100)
UU=11
VV=11
50    A2=A*A
IF (A2 .GT. 220.) 1020+1030
1020 CONST=2.*A2*A2
GOTO 1040
1030 CONST=2.+(A2/(1.-EXP(-A2)))*2
1040 UD2=U/2E0
55    C IF ISW=1 THEN THE ARRAY OF POINTS FOR GAUSSIAN INTEGRATION
C M ST RE FOUND
      GOTO (1050+1060) ISW
1050 ISW=2
CALL DQGP4A(0E0,1E0,YA)
IF (IP .EQ. 1) WRITE(IT6+1) (XA(I),I=1,N)
1060 CALL RTAPE3(T)
IF (IERR .NE. 0) GOTO 2000
DO 100 I=1,N
XA(I)
X2=X*X
XV=X*V
55    FW=EXP(-A2*X2)*CEXP(CMPLX(UE0+-UD2*X2))
EXP0=CEXP(CMPLX(0E0,K*PHI(X)))
EXPT=CEXP(CMPLX(0E0,K*HOLD))
IF (V .EQ. 0.) FZ=(EXPR-EXPT)*X/2.
IF (V .NE. 0.) FZ=(EXPR-EXPT)*J1(XV)/V
Q1=X*J0(V)
Fx=q1*EXPR-FZ.
70    
```

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75      FY=01#EX0T+FZ          0.0840
80      Q1=FW*FX              0.0850
     YD(T)=RFAL(Q1)          0.0860
     YT(T)=ATMAG(Q1)          0.0870
     J1=FW*FY                0.0880
     ZR(T)=RFAL(Q1)          0.0890
     ZT(T)=ATMAG(Q1)          0.0900
100    CONTINUEF             0.0910
1      FOR=AT(S1IX,612.5)      0.0920
     CALL D0G24B(0E0,1F0,YR,YR1) 0.0930
85      CALL D0G24B(0E0,1F0,YI,YI1) 0.0940
     CALL D0G24B(0E0,1F0,ZR,ZR1) 0.0950
     CALL D0G24B(0E0,1F0,ZT,ZT1) 0.0960
     TKISK=CONST*(YRT*YRT+YT1*YT1+ZRI*ZRI+ZT1*ZT1) 0.0970
200    RETURN                 0.0980
90      END                     0.0990

```

D.7 Major Function IKIRK Pertaining to Option No. 2 (IKIRKP)

```

1      RFAL FUNCTION IKIRK(M,V,T)          009800
C      APRIL 11, 1974                  009810
C      THIS FUNCTION COMPUTES THE KIRKHOFF INTENSITY FUNCTION 009820
C      ALONG THE U=0 AND/or V=0 AXIS OF THE PLANE. 009830
5      SEE COMMENTS IN IKIRK AND COMPUTE FOR BACKGROUND INFO. 009840
C      IT IS VALID ONLY FOR CONSTANT TEMPERATURE WINDOWS. 009850
C      DIMENSION AA(10)                  009860
C      COMMON/FILEIS/IT3,IT4,IT5,IT6,IT7,IT8 009870
C      COMMON/VCTOP/VV                  009880
10     COMMON/PHTLK/CS1P,CS2R,CS1T,CS2T,XS,DX,NF,MNNT,EPP,F1(2n), 009890
     FP(200),HOLD,ALPHA,KF,TLAST,TNEXT,TERP,IP,MP1,ISW,NGAUSS. 009900
     *RAD,NPI,C7,C)                  009910
     COMPLEX A1Q0,CRH00,CTHETAQ,A1Q,A2Q,A3Q,A4Q,A6Q,A7Q 009920
     RFAL KE                         009930
15     DATA (AA(I),I=1,10)/1.0,-.9999999958,.4999999206,-.166663019, 009940
     *.0416573475,-.0083012598,.0013298820,-.0001413161,0.00/ 009950
     VV=V                           009960
     CALI RTADF3(T)                  009970
     IF (TERR,NE,0) GOTO 2000        009980
     CTHETAQ=CS1T*F1(1)+4.*CS2T*F2(1) 009990
     CTHETAQ=CTHETAQ*KF            010000
     CRH00=CS1R*F1(1)+4.*CS2R*F2(1) 010010
     CRH00=CRH00*KE                010020
     A1Q=(0.,1.)                   010030
     A2Q=CEXP(A1Q0*CRH00)           010040
     A1Q=CEXP(A1Q0*CTHETAQ)         010050
     A1Q=A2Q-A3Q                  010060
     A=-/(ALPHA**2)                010070
     IF (A .LT. -.1000) GOTO 110   010080
     EXPA=EXP(A)                  010090
     A5=2.*A/(1.-EXP(A))**2       010100
     GOTO 120                      010110
     110    EXPB=0.                  010120
     A5=2.*A*A                      010130
     120    B=U/2.                  010140
     IF (U,NE,0) GOTO 200          010150
     C=(ALPHA/V)**2                010160
     IF (U,NE,0) GOTO 140          010170
     SINB=SIN(B)                  010180
     COSB=COS(B)                  010190
     ASQ=A**2                      010200
     BSQ=B**2                      010210
     A40DEAL=.5*((EXPB*(A*COSB+B*SINB))-A)/(ASQ+BSQ) 010220
     A40TMAG=.5*((EXPB*(A*SINB-B*COSB))+B)/(ASQ+BSQ) 010230
     A4Q=CMPLX(A40REAL,A40TMAG)   010240
     A6Q=A1Q/.#A4Q                010250
     IKIRKP=A5*((CABS(A2Q+A4Q+A6Q))**2+(CARS(A3Q+A4Q+A6Q))**2) 010260
     RETURN                          010270
130    IF (-A,GT,.693) GOTO 1000  010280

```

50	CALC COMPUTE (C,A8*FF1*FF2*IEN)	010290
	IF (TER,FN,2) GOTO 1000	010300
	A7Q=A10*FF2	010310
	IEN=IEN*((CARS(A20*FF1-A7Q))**2+(CARS(A30*FF1+A7Q))**2)	010320
	RETURN	010330
55	1000 WRITE (TT5,10)	010340
	10 FORMAT(1A ALPHA**2 IS OUT OF RANGE*)	010350
	2000 RETURN	010360
	END	010370

Appendix E

Fortran Listings for DISPLAY Program

E.1 Main Program DISPLAY

```

1      PROGRAM DISPLAY(TAPE4=80/BU,TAPEK=80/R0,TAPE3,OUTPUT=80)          000100
C REVISION---JUNE 11.1976                                         000105
C COMMON Z(103,103),XT(103,103),YT(103,103)                      000110
C COMMON/BLOCK3/NP2,MOP,XMINF,YMINF,DX,DY,SW1,IT6                000120
5      DIMENSION DATA(8)                                           000130
C DIMENSION PROGID(7),CODE(1),DATAIN(107,3),PARM(80)            000140
C DIMENSION IND(40),ZIEVS(50),TINDEX(4,2)                         000150
C INTEGER CODE
C LOGICAL FLAG,FLAG1,SWT                                         000160
10     DATA IT4,IT6,IT3/46,3/                                     000170
C DATA XS,YS/0.,0./                                              000180
C DATA (PROGTD=7H3ANTNO.7H1D 2347.7DISPLAY)                     000190
C DATA (CODE=1,1,45,0,PARM,1,1)                                    000200
C BLANK=15H
15     !BLANK=15H
C THE FOLLOWING DATA CARDS MUST BE INPUTTED TO TAILOR THE PROGRAM    000210
C FOR THE USERS PARTICULAR APPLICATION. THE NUMBER IN PARENTHESIS IN    000220
C FRONT OF EACH DATAIN NAME IS THE CARD COLUMN AT WHICH TO START THE    000230
C DATUM. THE NUMBER IN PARENTHESIS FOLLOWING THE DATUM IS THE DEFAULT    000240
C VALUE OF THE DATUM. IF THE DEFAULT VALUE IS TO BE USED LEAVE THE    000250
C CORRESPONDING CARD FIELD PLANK.                                     000260
C CARD 1
C (1)  XMAX           (100.)   MAXIMUM PLOT LENGTH IN INCHES        000270
C (11) VMAX           (12.)    MAXIMUM PLOT WIDTH IN INCHES         000280
25     C (2)  NPT            (1.)    NUMBER OF POINTS/INCH FOR CONTOURS  000290
C (3)  TICU           (.5)    NUMBER OF INCHES BETWEEN TIC-MARKS       000300
C                               FOR USER DEFINED X-Y PLOTS
C (4)  XLEN            (10.)   X-Y PLOT COORDINATE FRAME X-SIZE        000310
C (5)  YLEN            (9.)    X-Y PLOT COORDINATE FRAME Y-SIZE        000320
30     C (6)  SCALEx          (1.)   X-Y PLOT X-SCALE (UNITS/TIC)        000330
C (7)  SCALeY          (1.)   X-Y PLOT Y-SCALE (UNITS/TIC)        000340
C
C CARD 2
C (9)  ZMIN           (0.)    X-Y PLOT XMIN                         000350
C (11) YMIN           (0.)    Y-Y PLOT YMIN                         000360
C (2)  NAME            (HARPF1) NAME ON PLOT                         000370
C (3)  PROB.           (2784) PLOT PROBLEM NUMBER                   000380
C
C CARD 3
C (CARD 3 CONTAINS THE P-1 ARRAY 'TINDEX' WHICH IS THE INDEX OF      000390
C LOCATIONS FOR LABELING INFORMATION ASSUMED TO BE CONTAINED IN THE      000400
C LAST DATAIN ON THE FILE CONTAINING THE SURFACES. IF THERE IS NO      000410
C SUCH DATA THEN THIS CARD MAY BE LEFT BLANK AND THE LABELING WILL      000420
C NOT BE DONE. TINDEX CONSISTS OF PAIRS OF NUMBERS WHEREIN THE FIRST      000430
C NUMBER IS THE STARTING LOCATION OF THE LABEL AND THE SECOND NUMBER      000440
C IS THE LENGTH OF THE LABEL.                                         000450
40     C IF THE LETTER 'D' IS PLACED IN COLUMN 1 OF CARD 2, THE FOLLOWING      000460
C DEFAULT LOCATIONS ARE USED FOR TITLE INFORMATION-                  000470
C (1)  TINDEX(1,1)          (1)    SURFACE TITLE                      000480
C (6)  TINDEX(1,2)          (20)   SURFACE TITLE LENGTH (CHARACTERS)  000490
C (11) TINDEX(1,2)          (4)    PARAMETER TITLE                    000500
C (16) TINDEX(2,2)          (31)   PARAMETER TITLE LENGTH               000510
C (21) TINDEX(3,1)          (7)    X-TITLE                         000520
C (26) TINDEX(3,2)          (30)   X-TITLE LENGTH                   000530
45     C (31) TINDEX(4,1)          (1)    Y-TITLE                         000540
C (36) TINDEX(4,2)          (31)   Y-TITLE LENGTH                   000550
C (41) NDA              (2)    NUMBER OF 'DATAIN' ARRAYS          000560
C
C CARD 4-CARD NDA+2
50     C CARD 4-      CONTAIN THE INDICES OF DATA IN 'DATAIN' WHICH ARE TO      000570
C BE PLOTTED AT THE BEGINNING OF EACH RUN OF DISPLAY. THERE MUST BE      000580
C ONE CARD FOR EACH 'DATAIN' EVEN THOUGH FOR SOME 'DATAIN' NO DATA IS      000590
C TO BE PLOTTED (A BLANK CARD IS ACCEPTABLE). THE INDEX NUMBERS START      000600
C IN COLUMNS 1,3,5,7,..., FOR A TOTAL OF UP TO 40 INDICES PER CARD.      000610
55     C THE DEFAULT IS A HLINK CARD.I.E. NO 'DATAIN' DATA IS TO BE PLOTTED.      000620
C
C DMX=100.
C DYM=X=11.
C DDF=10.
C TICU=.5
C XLEN=10.
C YLEN=9.
C SCALEx=SCALeY=1.
C XMIN=X=YMIN=Y=0.
C IND=X(1,1)=1

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75      INDEX(1,2)=30          000830
INDEX(2,1)=4           000840
INDEX(2,2)=30          000850
INDEX(3,1)=7           000860
INDEX(3,2)=30          000870
INDEX(4,1)=10          000880
INDEX(4,2)=30          000890
NDA=2                  000900
READ(IT4,5) (DATA(I),I=1,8) 000910
IF (DATA(1) .NE. BLANK) DECODE(10,6,DATA(1)) PXMAX 000920
IF (DATA(2) .NE. BLANK) DECODE(10,6,DATA(2)) PYMAX 000930
IF (DATA(3) .NE. BLANK) DECODE(10,6,DATA(3)) PPI 000940
IF (DATA(4) .NE. BLANK) DECODE(10,6,DATA(4)) TICU 000950
IF (DATA(5) .NE. BLANK) DECODE(10,6,DATA(5)) XLEN 000960
IF (DATA(6) .NE. BLANK) DECODE(10,6,DATA(6)) YLEN 000970
IF (DATA(7) .NE. BLANK) DECODE(10,6,DATA(7)) SCALEX 000980
IF (DATA(8) .NE. BLANK) DECODE(10,6,DATA(8)) SCALEY 000990
WRITE(IT4,10) PXMAX,PYMAX,PPI,TICU,XLEN,YLEN,SCALEX,SCALEY 001000
READ(IT4,5) (DATA(I),I=1,8) 001010
IF (DATA(1) .NE. BLANK) DECODE(10,6,DATA(1)) XMTNX 001020
IF (DATA(2) .NE. BLANK) DECODE(10,6,DATA(2)) YMINTY 001030
IF (DATA(3) .NE. BLANK) DECODE(10,4,DATA(3)) PROGID(1) 001040
IF (DATA(4) .NE. BLANK) DECODE(10,4,DATA(4)) PROGID(2) 001050
WRITE(IT4,10) XMTNX,YMINTY 001060
READ(IT4,7) (DATA(I),I=1,8),NUAT 001070
DO 100 I=1,4
DO 101 J=1,2
102 I=I+1
IF (I .GT. 1) GOTO 84
IF (DATA(I) .EQ. 1) GOTO 85
103 IF (DATA(I) .EQ. BLANK) 92+93 001130
INDEX(I,J)=0
GOTO 91
93 CALL RJUST (DATA(I))
DECODE(10,8,DATA(I)) INDEX(I,J)
91 CONTINUE
85 WRITE(IT4,14) (INDEX(I,J)*J=1,2)*I=1,4 001200
C INITIALIZE THE PLOTTER
CALL PLT103(PROGID,PYMAX,PYMAX,IE0) 001210
001220
110 C PLOT DATA BLOCKS
REWIND IT3
XPT=0.
IF (NDAT .EQ. 1)BLANK) GOTO 94 001230
CALL RJUST(NDAT)
DECODE(10,8,NDAT) NDA 001240
IF (NDA .EQ. 0) GOTO 70 001250
120 94 DO 96 I=1,NDA 001260
READ(IT4,9) (IND(I),I=1,40) 001270
DO 97 J=1,40
IF (IND(I) .EQ. 1)BLANK) 98+99 001280
95 IND(J)=1
GOTO 97
96 CALL RJUST(IND(I))
DECODE(10,8,IND(J)) TND(J)
97 CONTINUE
98 WRITE(IT4,1) NDA,(TND(K)*K=1,40) 001290
99 READ(IT3) DATAIN
CALL FIL1(DATAIN,PARM,TND*100+1,NN) 001300
CALL PARPLT(XPT,0,0,0,IE0,PARM,1,NN) 001310
XPT=XPT+3.
130 96 CONTINUE
70 CALL PLOT(XPT,0,0,-3) 001320
C START THE MAIN DISPLAY LOOP. INTERP READS AND INTERPRETS THE DISPLAY 001330
C COMMANDS. IT RETURNS A FLAG VALUE OF .FALSE. IF THE LAST COMMAND HAS 001340
C BEEN READ.
FLAG=.T.
TND1C=1
140 DO 101 K=1,7
CODE(K)=BLANK 001350
101 CONTINUE
INDEX=0
XP=.5
IPEN=2
CALL INTERP(CCODE,CODE,FLAG,I14) 001360
150 IF (.NOT. FLAG .AND. INDEX .EQ. 2) GOTO 2000 001370
IF (CCODE .EQ. 1) WRITE(IT4,15) (CODE(K),K=1,5) 001380
IF (CCODE .EQ. 2) WRITE(IT4,12) (CODE(K),K=1,4) 001390
IF (CCODE .EQ. 3) WRITE(IT4,16) (CODE(K),K=1,7) 001400
FLAG=.T. 001410

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155      IF (INDA .LE. 0) GOTO 82          001630
        RFWTND IT3
        DO 81 I=1,INDA
        READ(IT3)
81      CONTINUE
160      82      INDTC=2                001640
        ZMIN=1E100
        ZMAXA=-1E100
        NSTART=CODE(2) .OR. 0
        NSTART=NSTART-1
        IF (NSTART .LE. 0) GOTO 72
        DO 74 I=1,NSTART
        CALL RD1(IT3,D1,02,03,04,4,FLAG1,D5,D6,D7,D8,D9)
        IF (.N. FLAG1) GOTO 100
74      CONTINUE
170      72      NSKTP=CODE(1) .OR. 0       001650
        NSKTP=NSKTP-1
        GOTO (110,120,130) CCODE
C 110 => CONTOUR
C 120 => PERSPECTIVE
C 130 => PLOT
175      C NEXT ARE TO BE NORMALIZED OVER ALL SURFACES, FIND THE
C MAX. AND MIN. OVER ALL SURFACES.
        C 110 IF CONTOUR
        C 120 IF PERSPECTIVE
        C 130 IF PLOT
180      110      IF (CODE(4) .EQ. PHDN .OR. CODE(6) .EQ. ZHUN) GOTO 150 001660
        CALL RD1(IT3,NP,MP,ZMAX,ZMIN,1,FLAG1,TIM,XMIN,XMAX,YMIN,YMAX) 001670
        WRITE(IT6,13) NP,MP,ZMAX,ZMIN,TIM,XMIN,XMAX,YMIN,YMAX,FLAG1
        IF (CODE(4) .EQ. PHNF .OR. CODE(6) .EQ. ZHNE) GOTO 140 001680
        CALL SKIP(IT3,NSKTP,FLAG1,NP)
        IF (ZMAX .GT. ZMAXA) ZMAXA=ZMAX
        IF (ZMIN .LT. ZMINA) ZMINA=ZMIN
        IF (FLAG1) GOTO 140 001690
185      140      RFWTND IT3
        FLAG1=.T.
        IF (INDA .LE. 0) GOTO 145 001700
        DO 143 I=1,INDA
        READ (IT3)
190      83      CONTINUE
145      IF (NSTART .LE. 0) GOTO 150 001710
        DO 145 I=1,NSTART
        CALL RD1(IT3,DUM1,DUM2,DUM3,DUM4,4,FLAG1,DUM5,DUM6,DUM7,DUM8,
+DUM9) 001720
195      115      CONTINUE
150      GOTO (155,250,350) CCODE
C NEXT FIL THE Z-ARRAY, DETERMINE CONTOUR LEVELS AND DRAW THE CONTOUR MA 001730
155      CALL RD1(IT3,NP,MP,ZMAX,ZMIN,Z,FLAG1,TIM,XMIN,XMAX,YMIN,YMAX) 001740
        IF (.NOT. FLAG1) GOTO 100 001750
        IF (CODE(4) .EQ. PHDN) 170,180 001760
170      CALL CLEV(CODE(3),ZMAX,ZMIN,Z,EVS)
        GOTO 190 001770
180      IF (CODE(4) .EQ. PHNF) 200,210 001780
200      ZMAX=ZMAXA
        ZMIN=ZMINA
        C=100.0/(ZMAX-ZMIN)
        DO .gt;20 J=1,MP 001790
        DO .gt;20 I=1,NP 001800
        Z(I,J)=(Z(I,J)-ZMIN)*C 001810
210      220      CONTINUE
        CALL CLEV(CODE(3),100.0,ZLEVS) 001820
100      XLEN1=AMTN1((MP-1)/PP1*PYMAX-1.)
        YLEN1=AMTN1((NP-1)/PP1*PYMAX-1.) 001830
        IF (CODE(5) .EQ. PHSP .A. INDIX .EQ. 1) GOTO 205 001840
        CALL CFRAVE(INDFX,ZMTN,ZMAX,CODE(4),NP,MP,TIM,PPI,100,.0,.0,.0, 001850
+XMIN,XMAX,YMIN,YMAX,DATAIN,XLEN1,YLEN1,CCODE)
        INDIX=1 001860
205      SYMRAL(TIM)
        NX=TINDEX(2,2) 001870
        IF (NX .EQ. 0) GOTO 222 001880
        CALL SYMRAL(XLEN1,XP,PYMAX-1,1,.1E0,DATAIN(INDEX(2,1)+1),0.,NX) 001890
        GOTO 223 001900
222      CALL SYMRAL(XLEN1,XP,PYMAX-1,1,.1E0,9PARAMETER,0.,9) 001910
223      CALL SYMRAL(999F0,999E0,.1E0,SYM,0E0,10) 001920
        CALL CONTOUR(NP,MP,CODE(3),ZLEVS,BANK,XLEN1,YLEN1,XP,PYMAX-1,2) 001930
        IF (CODE(5) .NE. PHSP) GOTO 215 001940
        XP=XP+4.
        IPEN=IPEN+1 001950
        IF (IPEN .GT. 3) TP=M=1 001960
        CALL NEWOPEN(IPEN) 001970
        GOTO 196 001980
215      CALL PLOT(XLEN1+12,.0,.0,-3) 001990
196      IF (FLAG1) 195,106 001996

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235      145 CALL SKIP(IT3,NSKTP,FLAG)*NP)          002380
         IF (/FLAG1) 155,106                      002390
         146 IF (CODE(5) .NE. 2H501 GOTO 100        002400
         CALL NEWEN(?)                               002410
         CALL PLOT(XLEN1+XD+R,,0F0*-3)             002420
         GOTO 100                                  002430
240      C START OF PERSPECTIVE PLOTS. FIRST FIND ZMAX,ZMIN FOR NORMALIZATION IF 002440
C NORMALIZATION IS OVER ALL SURFACES.                                002450
         120 GOTO 110                               002460
         250 PP1=10.                                002470
         245     IF (MP .GT. NP) GOTO 390           002480
         XLEM1=5.*MP/FLOAT(NP)                     002490
         YLEM1=5.                               002500
         GOTO 400                               002510
         390 YLEM1=5.*NP/FLOAT(MP)                 002520
         XLEM1=5.                               002530
         250     C THE NEXT TASK IS TO FIND SCALING FACTORS FOR THE DISPLAY BY CALLING 002540
C FACE WITH A RECTANGLE FUNCTION.                                002550
         410 NP1=NP+1                            002560
         MP1=MP+1                            002570
         NP2=NP1+1                           002580
         MP2=MP1+1                           002590
         XP=MP2**2                           002600
         Y2=NP2**2                           002610
         H=SQRT(X2+Y2)                         002620
         THETA1=.785398164                     002630
         THETA2=CODE(3)/180.+7.14159265       002640
         X=.**MP2+H*COS(THETAP2)              002650
         Y=.**NP2+H*SIN(THETAP2)              002660
         C1=.5**H                           002670
         CALL APLACE(XP,YP,XLEN1,YLEM1,CODE(3)) 002680
         C THIS SUBROUTINE FINDS THE POINT AT WHICH TO PLACE THE VIEW-ANGLE 002690
C ARROW
         260 K=1+NP2                           002700
         Z(I,J)=7(K+MP2)=0.                   002710
         270 CONTINUEF
         DO 270 K=2,MP1                      002720
         Z(NP2+K)=7(I,K)=0.                   002730
         270 CONTINUEF
         DO 280 I=2,NP1                      002740
         DO 280 J=2,MP1                      002750
         Z(I,J)=C1                           002760
         280 CONTINUEF
         SWI=F.
         C IF SWI IS OFF (.F.) THEN FACE RETURNS XMIN,YMIN,DX,DY ONLY AND DOES NO 002770
         280     C PLOTTING
         CALL FACE(X*Y*H,THETA1+THETAP*0)      002780
         SWI=T.
         WRITE(IT6,?) XMTN,YMTN,UX,DY          002790
         2 FORMAT(1X,4E15.5)
         280     C NOW FILL UP THE Z-ARRAY
         CALL RD1(IT3,NP,MP,ZMAX,ZMIN,J,F,FLAG1,TIM,XMIN,XMAX,YMIN,YMAX) 002800
         290     IF (/NOT, FLAG1) GOTO 100        002810
         IF (CODE(4) .EQ. 2HNFI GOTO 300      002820
         ZMTN=ZMINA
         ZMAX=ZMAXA
         290     C NOW DRAW LABELS+ETC.
         30     C=C1/(ZMAX-ZMIN)                002830
         DO 310 I=2,MP1                      002840
         DO 310 K=2,NP1                      002850
         Z(I,J)=(Z(K,J)-ZMN)*C               002860
         310 CONTINUEF
         DO=1*AM*XD(NP,MP)
         CALL CFPM(E,INDX,ZMTN,ZMAX,CODE(4),NP,MP,TIM,PP,C1,6E0_1E0, 002870
         *XMIN*XMAX,YMTN,YMAX,DATAIN,XLEN1,YLEN1,CCODE)                  002880
         CALL ARROW(XP,YP,1.,CODE(3)+10HVVIEW ANGLE+10)                  002890
         XPT=XLEN1+4E0
         YDT=-1E0
         CALL PLOT(XPT,YPT,-3)                002900
         305     C NOW DRAW PERSPECTIVE DISPLAY
         CALL FACE(X*Y*H,THETA1+THETA2*0)      002910
         CALL PLOT(12F0,0E0*-3)                002920
         320     IF (FLAG1) 320,100            002930
         320     CALL SKIP(IT3,NSKTP,FLAG1)*NP)   002940
         IF (FLAG1) 240,100
         C START OF X-Y PLOTS. FIRST FIND ZMAX,ZMIN FOR SCALING IF SCALING IS 002950
C OVER ALL SURFACES
         130 GOTO 110
         350 CALL DOL(IT3,NP,MP,ZMAX,ZMIN,Z,FLAG1,TIM,XMIN,XMAX,YMIN,YMAX) 002960
         IF (/NOT, FLAG1) GOTO 105          002970

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315	IF (CODE(6) .EQ. PHNF) GOTO 370	003180
	IF (CODE(6) .EQ. PHDN) GOTO 370	003190
	ZMIN=ZMTNA	003200
	ZMAX=ZMAXA	003210
370	CONTINUE	003220
320	IF (CODE(7) .NE. PHSD) XS=YS=0.	003230
	CALI PLOT1(TICL),SCALFX,SCALFY,XLEN,YLEN,TIM,NP,MP,IT6,INDEX,	003240
	+DATA1IN,XMIN,XMAX,YMTN,YMAX,XS,YS,ZMIN,ZMAX,CODE,XMINX,YMTNY	003250
	IF (FLAG1) 380,105	003260
380	CALI SKTP(TT3+N,KTP,FLAG1+NP)	003270
325	IF (FLAG1) 350,105	003280
105	IF (CODE(7) .EQ. PHSD) CALL PLOT(XLEN+6,0,0,-3)	003290
	XS=YS=0.	003300
	GOTO 100	003310
2000	CALI ENDPLT	003320
330	16 FORMAT(1X,2I5,3X,A1,2I5,3X,A2,3XA2)	003330
15	15 FORMAT(1X,3I5,3X,A2,3XA2)	003340
14	14 FORMAT(1X,A15)	003350
13	13 FORMAT(1X,2I10/1X,4G10.2/1X,3G10.2,L10)	003360
12	12 FORMAT(1X,2I5,3X,G10.2,3X,A2,3XA2,3XA2)	003370
335	11 FORMAT(1X,I5.4/(1X,I0,T5))	003380
10	10 FORMAT(1X,4G10.2/1X,4G10.2)	003390
9	9 FORMAT(4A2)	003400
8	8 FORMAT(T10)	003410
7	7 FORMAT(9A5)	003420
340	6 FORMAT(E10.0)	003430
5	5 FORMAT(8A10)	003440
4	4 FORMAT(A10)	003450
	END	003460

E.2 Subroutine PLOTT1

1	SUBROUTINE PLOTT1(TICL,SCALXX,SCALYY,XLEN,YLEN,TIM,NP,MP,IT6,	003470
	+TN1)FX,DATA1IN,XMTNX,XMAXX,YMTNY,YMAXY,XSS,YSS,ZMIN,ZMAX,CODE,	003480
	+XMTNX,YMTNY)	003490
5	DIMENSION PTITLE(5),TITLE(5),XTITLE(5),YTITLE(5)	003500
	DIMENSION INDEX(4,2),DATA1IN(100,7),XAPRAY(101),YARRAY(101),CODE(7)	003510
	COMMON Z(103),T03	003520
10	C IN THE FIRST PART OF PLOTT1 THE COORDINATE FRAME IS DRAWN AND	003530
	C TITLED. IF CODE(7) IS ON THEN SCALING IS OBTAINED FROM THE USER.	003540
	C OTHERWISE SCALING IS DONE BY SUBROUTINE SCALE.	003550
	C THE INDEX ARRAY IS USED AS IN SUBROUTINE CFRAME TO OBTAIN VARIOUS	003560
	C TITLING INFORMATION. THE PLOT Y-APRAY IS OBTAINED FROM Z(I,J) AS	003570
	C YAPRAY(1)=Z(1,1) IF CODE(3)=X AND AS YARRAY(.)=Z(N,.) IF CODE(3)	003580
	C =Y. WHERE N STARTS AT CODE(4) AND IS INCREMENTED BY CODE(3). THE	003590
	C CALL PLOTT1 MUST SUPPLY THE FOLLOWING ARGUMENTS-	003600
15	MT=CODE(4) .OR. 0	003610
	IF (CODE(7) .EQ. PHSD .A. XS .NE. 0.) GOTO 430	003620
	XS=YS=0.	003630
370	YMIN=YAPRAY(1)=ZMTN	003640
	YARDAY(2)=ZMAX	003650
20	CALI SCALE(YARRAY,YLEN,2,1+20,+YMIN1,DELY)	003660
	IF (CODE(7) .EQ. 1) 380,390	003670
	XMIN=XMTNX	003680
	XMAX=XMAXX	003690
	PMIN=YMTNY	003700
	PMAX=YMAXY	003710
25	DELX=(XMAX-XMIN)/AMAX0(1,MP-1)	003720
	DELY=(PMAX-XMIN)/AMAX0(1,MP-1)	003730
	DO 382 I=1,MP	003740
	XAPRAY(I)=XMIN+(I-1)*DELX	003750
30	382 CONTINUE	003760
	NX=INDEX/3.2	003770
	NN=NX+91/10	003780
	IF (NX .NE. 0) GOTO 505	003790
	NX=7	003800
35	XTITLE(1)=7HX-VAL1IE	003810
	GOTO 500	003820
505	IT=INDEX(3,1)	003830
	DO 384 I=1,NN	003840
	XTITLE(I)=DATA1IN(IT+1)	003850

40	IT=IT+1	003860
	CONTINUE	003870
384	NT=INDEX(4,2)	003880
500	NN=(NT*91/10)	003890
	IF (NT .NE. 0) GOTO 515	003900
45	NT=7	003910
	TTITLE(I)=7HY-VALUE	003920
	GOTO 519	003930
515	IT=INDEX(4,1)	003940
	DO 786 IT=1,NN	003950
50	TTITLE(I)=DATAIN(IT+1)	003960
	IT=IT+1	003970
396	CONTINUE	003980
519	NP1=NP	003990
	NL1=NP	004000
55	GOTO 400	004010
	XMIN=YMINY	004020
	XMAX=YMAXY	004030
	PM1=YMINX	004040
	PMAX=YMAXX	004050
60	DELY=(XM-XMIN)/AMAX0(1,MP-1)	004060
	DELX=(PMAX-PMIN)/AMAX0(1,MP-1)	004070
	DO 792 I=1,NP	004080
	XARRAY(I)=XMIN+(I-1)*DELX	004090
392	CONTINUE	004100
	NX=INDEX(4,2)	004110
	NN=(NX*91/10)	004120
	IF (NX .NE. 0) GOTO 525	004130
65	NX=7	004140
	XTITLE(I)=7HY-VALUE	004150
	GOTO 520	004160
525	IT=INDEX(4,1)	004170
	DO 794 IT=1,NN	004180
	XTITLE(I)=DATAIN(IT+1)	004190
	IT=IT+1	004200
70	394	004210
	CONTINUE	004220
520	NT=INDEX(3,2)	004230
	NN=(NT*91/10)	004240
	IF (NT .NE. 0) GOTO 535	004250
75	NT=7	004260
	TTITLE(I)=7HX-VAL(IF)	004270
	GOTO 530	004280
	525	004290
	IT=INDEX(3,1)	004300
	DO 796 IT=1,NN	004310
	TTITLE(I)=DATAIN(IT+1)	004320
	IT=IT+1	004330
80	396	004340
	CONTINUE	004350
520	NP1=NP	004360
	NL1=NP	004370
85	400	004380
	CALI SCALE(XARRAY,X1 FN=NP1\$+1*20.,XMIN1,DELX)	004390
	NY=INDEX(1,2)	004400
	NN=(NY*91/10)	004410
	IF (NY .NE. 0) GOTO 545	004420
90	NY=7	004430
	YTITLE(I)=7HZ-VALUE	004440
	GOTO 540	004450
95	545	004460
	IT=INDEX(1,1)	004470
	DO 410 IT=1,NN	004480
	YTITLE(I)=DATAIN(IT+1)	004490
	IT=IT+1	004500
100	410	004510
	CONTINUE	004520
540	NR=INDEX(2,2)	004530
	IF (NR .NE. 0) GOTO 555	004540
	NN=(NR*91/10)	004550
	NR=10	004560
	PTITLE(1)=10HPARAMETER	004570
105	GOTO 550	004580
	555	004590
	IT=INDEX(2,1)	004600
	DO 420 IT=1,NN	004610
	PTITLE(I)=DATAIN(IT+1)	004620
	IT=IT+1	004630
110	420	004640
	CONTINUE	004650
550	TSY=0	
	Y=CODE(S) .OR. 0	
	TSWTC=3	
	IF (CODE(6) .EQ. 2) GOTO 430	
	TSWTC=2	
	SCALE,X=DELX	
	XMIN=XMIN1	
	SCALE,Y=DELY	

128	YMTI=YMTM1	004660
	C START OF MAIN PLOTTING LOOP	004670
	430 IF (M .GT. NLIM) GOTO 440	004680
	IF (CODE(3) .NE. 1HY) GOTO 450	004690
	DO 460 I=1+NPTS	004700
	YARRAY(T)=Z(T,M)	004710
125	460 CONTINUE	004720
	GOTO 470	004730
	450 DO 480 I=1+NPTS	004740
	YARRAY(T)=Z(M,I)	004750
130	480 CONTINUE	004760
	470 CURVE=PMTN+(M-1)*DE1 D	004770
	IF (CODE(7) .NE. 2HSP1 GOTO 425	004780
	TTM=TM	004790
	TM=CURVE	004800
135	CURVE-TTM	004810
	DO 215 T=1,5	004820
	TTM=PTITLE(I)	004830
	PTITLE(I)=TITLE(T)	004840
	TITLE(I)=TTM	004850
140	215 CONTINUE	004860
	TTM=N8	004870
	NRENT	004880
	NT=TTM	004890
	IF (XSS .NE. 0.) GOTO 200	004900
145	425 GOTO (201+220+210,200) TSWCH	004910
	210 CALI PLOT(XS,YS,3)	004920
	TSWCH=4	004930
	X=S=0.	004940
	SCAY=TI01/SCALXX	004950
150	SCAY=TI01/SCALYY	004960
	ENCODE(1,0,1) TSYMR YMTNYY	004970
	CALL SYMBOL(-1.0E0,.1E0,1SYMB,90E0,10)	004980
	CALI SYMBOL(XS-.2E0,YS+.1E0,.1E0,1TYTITLE,90E0,NY)	004990
	CALI SYMBOL(999E0,999E0,.1E0,10H SCALF IS .90E0,10)	005000
155	ENCODE(1,0,1) TSYMR1 SCALYY	005010
	CALI SYMBOL(999E0,999E0,.1E0,1SYMB,90E0,10)	005020
	CALI SYMBOL(999E0,999E0,.1E0,10H UNITS/TIC,90E0,11)	005030
	ENCODE(1,0,1) TSYMR1 XMINX	005040
	CALI SYMBOL(0E0,.2E0,.1E0,1SYMH,0E0,10)	005050
160	CALI SYMBOL(1.2E0,-.3E0,.1E0,XTITLE,0E0,NX)	005060
	CALI SYMBOL(999E0,999E0,.1E0,10H SCALF IS .9E0,10)	005070
	ENCODE(1,0,1) TSYMR1 SCALXX	005080
	CALI SYMBOL(999E0,999E0,.1E0,1SYMH,0E0,10)	005090
	CALI SYMBOL(999E0,999E0,.1E0,10H UNITS/TIC,0E0,11)	005100
165	CALI PLOT(0E0,0E0,3)	005110
	YD=0.	005120
	DO 100 I=1+10000	005130
	NET	005140
	XDT=I*TICU	005150
170	TF (XPT .GT. XLEN1) GOTO 1000	005160
	CALI PLOT(XPT,YPT,2)	005170
	CALI PLOT(XPT,YPT,.1,2)	005180
	CALI PLOT(XPT,YPT,2)	005190
	100 CONTINUE	005200
175	1400 YPT=(N-1)*TICU	005210
	DO 10 I=1+10000	005220
	NET	005230
	YPT=I*TICU	005240
	TF (YPT .GT. YLEN1) GOTO 1010	005250
180	CALI PLOT(XPT,YPT,2)	005260
	CALI PLOT(XPT,-.1,YPT,2)	005270
	CALI PLOT(XPT,YPT,2)	005280
	110 CONTINUE	005290
185	110 YPT=(N-1)*TICU	005300
	XOTT=EXPT	005310
	DO 120 I=1+10000	005320
	NET	005330
	XDT=XOTT-I*TICU	005340
190	TF (XDT .LT. XS) GOTO 1020	005350
	CALI PLOT(XPT,YPT,2)	005360
	CALI PLOT(XPT,YPT,.1,2)	005370
	CALI PLOT(XPT,YPT,2)	005380
	120 CONTINUE	005390
195	120 YDT=YPY	005400
	XPT=XS	005410
	CALI PLOT(XS,YPT,2)	005420
	CALI PLOT(XS,YPT,.1,2)	005430
	DO 130 I=1+10000	005440
	YDT=YDT-I*TICU	005450

```

200      IF (YPT .LT. YS) GOTO 1030          005470
        CALI, PLOT(XPT,YPT,2)
        CALI, PLOT(XPT+1,YPT,2)
        CALI, PLOT(XPT,YPT,2)
120      CONTINUE
205      1130 CALI, PLOT(XS,YS,2)
        GOTO 230
220      220 CALI, PLOT(XS,YS,3)
        ISWTCHE=1
        XS=YS=0E0
210      CALI, AXIS(XS,YS,XTITLE=-NX,XLEN,0E0,XMIN,SCALEX,20.)
        CALI, AXIS(XS,YS,YTITLE=NY,YLFN,9E0,YMIN,SCALEY,20.) 005560
        C NEXT PLOT PARAMETER AND CURVE TITLES
215      210 CALI, SYMBOL(XS+1E0,YS+YLEN+2,1E0,PTITLE,0E0,NB)
        SYMBOL(SYM1,TIM)
        CALI, SYMBOL(XS+1E0,YS+YLEN+2,1E0,PTITLE,0E0,10) 005590
        XS=XLFN+1E0
        YSS=YLFN-1E0
        CALI, SYMBOL(XSS,YS+1E0,TITLE,0E0,NT)
        C PLOT CURVE
220      200 CALI, PLOT(0E0,0E0,3)
        GOTO (241,240,250,2501,ISWTCH
240      240 CALI, LINE(XARRAY,YARRAY,NPTS+1,5,ISYM,XMIN,SCALEX,YMIN,
        +SCALEY,0.07)
        GOTO 1050
225      250 X0=0Q=-.1
        XLEN=XLFN+.1
        YLEN=YYLEN+.1
        TP=?
        DO 140 J=1,NPTS
230      230 N=J
        XDT=(XARRAY(J)-XMINXX)*SCAX
        YDT=(YARRAY(J)-YMINYY)*SCAY
        IF (XPT .GE. X0 .AND. YPT .GE. Y0 .AND. YPT .LE. YLEM) GOTO 1040
        140 CONTINUE
        WRITE(ITE,1)
        GOTO 1050
235      2 FORMAT(1X,* NO POINTS PLOTTED*)
1040    IF (ISYM>1070,1070,1080
        1070 CALI, PLOT(XPT,YPT,1P)
        TP=?
        GOTO 1060
1080    CALI, SYMBOL(XPT,YPT,1,ISYM,0E0,-1)
1060    N=N+1
        IF (N .GT. NPTS) GOTO 1050
        YDT=(YARRAY(N)-YMINYY)*SCAY
245      1050 IF (YPT .GT. YLEM .OR. YPT .LT. Y0) GOTO 1065
        XDT=(XARRAY(N)-XMINXX)*SCAX
        IF (XPT .GT. XLEM .OR. XPT .LT. X0) GOTO 1065
        GOTO 1040
250      1065 TP=3
        GOTO 1060
1050    IF (ISYM .LT. 0) ISYM=15
        YSS=YSS-.15
        IF (YSS .GT. 0.) GOTO 260
        YSS=YLEN-1.15
        XSS=XSS+?
260      260 CALI, SYMBOL(XSS,YS,1E0,ISYM,0E0,-1)
        CALI, SYMBOL(999E0,999E0,.1E0,2H ,0E0,2)
        ENCODE(10,1,ISYM), CURVE
        CALL, SYMBOL(999E0,999E0,.1E0,ISYM,0E0,10)
        ISYM=MOD(ISYM+1,17)
        IF (CODE(7) .EQ. 2HSP) GOTO 560
        M=M+1
        GOTO 430
265      440 XPT=XLEN+6E0
        CALI, PLOT(XPT,0E0,-3)
560      560 RETURN
1      1 FORMAT(G10.3)
END

```

E.3 Subroutine PARMPLT

```

1      SUBROUTINE PARMPLT(XS,YS,HT,PARM,NS,N)          006160
C THIS SUBROUTINE PLOTS N PARAMETERS IN 'PARM' STARTING AT LOCATION 006170
C XS,YS, HT IS THE HEIGHT OF THE LETTERS (INCHES),NS IS THE "STARTING 006180
C LOCATION " IN PARM AT WHICH TO LOOK FOR DATA FOR PLOTTING. 006190
5      DIMENSION PARM(1)                                006200
       IF (N .LT. 0) GOTO 2000                          006210
       XPT=XS                                         006220
       YPT=YS                                         006230
       NS1=NS-1                                       006240
10      DO 100 I=1,N+2                                006250
       IT=NS1+I                                     006260
       CALL SYMBOL(XPT,YPT,HT,PARM(IT)*0E0+20)        006270
       YPT=YPT-2.*HT                                 006280
100     CONTINUE                                      006290
15      2000  RETURN                                     006300
       END                                              006310

```

E.4 Subroutine FILL

```

1      SUBROUTINE FILL(DATAIN,PARM,TINDEX,ISIZE,NS,N)    006320
C THIS SUBROUTINE SELECTS DATA FROM DATAIN(ISIZE+3) AND PLACES IT IN 006330
C 2-D ARRAY PARM STARTING AT NS ACCORDING TO NUMBERS IN INDEX. THE 006340
C PARM VALUES ARE CHARACTER-STRINGS SUITABLE FOR PLOTTING. 006350
5      DIMENSION DATAIN(1),PARM(1),TINDEX(1)           006360
       ENCL,VALENCE (IF,F1)
       IT=2*NS-1
       DO 100 I=1,40
       K=INDEX(I)
10      IF (K .EQ. 0) GOTO 100
       IT=IT+2
       K1=K+ISIZE
       K2=K1+ISIZE
       FT=DATAIN(K2)
15      PARM(I)=DATAIN(K1)
       IF (IF) 1000,1010,1020
1000    ENCODE (10.1,PARM(IT+1)) DATAIN(K)
       GOTO 100
1010    ENCODE (10.2,PARM(IT+1)) DATAIN(K)
       GOTO 100
1020    ENCODE (10.3,PARM(IT+1)) DATAIN(K)
100     CONTINUE
       N=IT
       RETURN
25      1  FORMAT(A10)                                006540
         2  FORMAT(T10)                                006550
         3  FORMAT(G10.3)                                006560
       END                                              006570
                                                 006580
                                                 006590

```

E.5 Subroutine CFRAME

```

1      SUBROUTINE CFRAME(INDEX,ZMIN,ZMAX,CODE,NP,MP,TPI,C,XS,YS,
+XMIN,XMAX,YMIN,YMAX,DATAIN,XLEN,YLEN,icode)
C INDEX IS A P-D APAY OF INTEGERS (IN SEQUENCE) DENOTING THE
C STARTING LOCATION AND NUMBER OF WORDS IN DATAIN CONTAINING THE
5      C FOLLOWING INFORMATION-
C 1.1 FUNCTION TITLE
C 1.2 F-TITLE LENGTH (WORDS)
C 2.1 PARAMETER LABEL
C 2.2 P-LABEL LENGTH
10     C 3.1 X-LABEL
C 3.2 X-LABEL LENGTH
C 4.1 Y-LABEL
C 4.2 Y-LABEL LENGTH
C C IS THE FUNCTION NORMALIZATION CONSTANT
15     C XS,YS IS THE STARTING POINT OF THE FRAME
C T IS SUBROUTINE ASSUMES THAT THE PRECEDING PLOT WAS TERMINATED AT THE
C LOWER RIGHT CORNER OF ITS ALLOCATED SPACE (AND THIS IS THE NEW ORIGIN)
C
20     DIMENSION DATAIN(100+3),INDEX(4+2)
      INTEGER CODE,CODEF
      TPI=5/PPI
C FIRST DRAW TITLE,SCALING INFO,PARAMETER
      NX=INDEX(1+2)
      IF (NX .EQ. 0) GOTO 170
25     CALL SYMBOL(1E0,8.5E0,.15E0,DATAIN(INDEX(1+1)+1),0E0,NX)
      IF (CODE .EQ. 1) GOTO 215
      SYM=SYMAL(TIM)
      NX=INDEX(2+2)
      IF (INV .EQ. 0) GOTO 200
30     CALL SYMBOL(1.5E0,8.2E0,.1E0,DATAIN(INDEX(2,1)+1),0E0,NX)
      GOTO 210
      CALL SYMBOL(1.5E0,8.2E0,.1E0,SYMPARAMETER,0E0,9)
      CALL SYMBOL(999F0,999F0,.1E0,SYM,0E0,10)
      210    IF (CODE .EQ. 2HNU) GOTO 220
35     CALL SYMBOL(1E0,8.E0,.1E0*24HALL FUNCTION VALUES HAVE.0E0+24)
      CALL SYMBOL(1E0,7.8E0,.1E0*25HHEEN SCALED ACCORDING TO-.0E0+25)
      CALL SYMBOL(1E0,7.45E0,.1E0,1H2,0E0+1)
      CALL ARPN(1.5*7.E0,.3*1E0,.1H+.0)
      ENCODE(1~1,SYM)
40     CALL SYMBOL(1.6E0,7.6E0,.1E0,SYM,0E0,10)
      CALL SYMBOL(999.F0,999.F0*.1E0,9H*(Z-ZMIN)+0E0+9)
      CALL PLOT(1,9E0,7.5E0,3)
      CALL PLOT(3,1E0,7.5E0,2)
      CALL SYMBOL(PE0,7.3E0,.1E0+1H(ZMAX-ZMIN)+0E0+11)
45     ENCODE(1~1,SYM) ZMAX
      CALL SYMBOL(1E0,7.1E0,.1E0,1HWHERE ZMAX=.0E0+1))
      CALL SYMBOL(999F0,999F0,.1E0,SYM,0E0,10)
      ENCODE(1~1,SYM) ZMIN
      1    FORMAT(G10.3)
50     CALL SYMBOL(1E0,6.9E0,.1E0+1H ZMIN=.0E0+11)
      CALL SYMBOL(999F0,999F0,.1E0,SYM,0E0,10)
      CALL SYMBOL(1E0,6.7E0,.1E0+2)ARE THE MAX. AND MIN.,.0E0,P0
      IF (CODE .EQ. 2HNU) 110,120
      110   CALL SYMBOL(1E0,5.5E0,.1E0+24HVALUES OVER ALL SURFACES,0F0+24)
      GOTO 100
55     120   CALL SYMBOL(1E0,6.5E0,.1E0+21HVALUES OF THE SURFACE,0E0+21)
      130   CONTINUE
C NEXT SET THE PLOT ORIGIN AT THE ORIGIN OF THE SURFACE COORDINATE
C FRAME,DRAW THE FRAME AND LABEL IT.
60     220   CALL PLOT(XS,YS,-1)
C THE COORDINATE FRAME IS DRAWN WITH THE TIC-MARKS EVERY TICU (INCHES).
      ENCODE(1~1,SYM) YMINT
      CALL SYMBOL(0E0,-.5E0,.1E0+SYM,0E0,10)
      NX=INDEX(3+2)
65     140   IF (NX .EQ. 0) GOTO 180
      CALL SYMBOL(0E0,-.5E0,.1E0,DATAIN(INDEX(3,1)+1),0E0,NX)
      150   ENCODE(1~1,SYM) YMAX
      XPT=0E0
      YPT=0E0
      CALL PLOT(XPT,YPT,3)
      DO 130 I=1,100000
      N=I
      XPT=I*TICU
      IF (XPT .GT. XLEN) GOTO 1000

```

75	CALI_PLOT(XPT,0E0,2)	007340
	CALI_PLOT(XPT,+1,2)	007350
	CALI_PLOT(XPT,0E0,2)	007360
130	CONTINUE	007370
140_XPTT=N*TICU		007380
80	XPT=XLEN	007390
	CALI_PLOT(XPT,0E0,2)	007400
	CALI_SYMBOL(XPT,-5,-2,1,SYM+0E0+10)	007410
	CALI_PLOT(XPT,0E0,3)	007420
DO 140 T=1,100000		007430
85	N=1	007440
	YPT=I*TICU	007450
	IF (YPT .GT. YLEN) GOTO 1010	007460
	CALI_PLOT(XPT,YPT,2)	007470
	CALI_PLOT(XPT,-1,YPT,2)	007480
90	CALI_PLOT(XPT,YPT,2)	007490
140_CONTINUE		007500
1010_YPTT=N*TICU		007510
	YPT=YLEN	007520
	CALI_PLOT(XPT,YPT,2)	007530
DO 150 I=1,100000		007540
95	N=1	007550
	XPTT=XPTT-T*TICU	007560
	IF (XPT .LT. 0E0) GOTO 1020	007570
	CALI_PLOT(XPT,YPT,2)	007580
100	CALI_PLOT(XPT,YPT,-1,2)	007590
	CALI_PLOT(XPT,YPT,2)	007600
150_CONTINUE		007610
1020_XPT=0E0		007620
	CALI_PLOT(XPT,YPT,2)	007630
105	ENCODE(10+1,SYM) YMAX	007640
	YPT<YPT--5	007650
	IF (YPT .GT. -9.5) YPT=9.5	007660
	CALI_SYMBOL(-1E0,YPT,-1E0,SYM+0E0+10)	007670
	CALI_PLOT(0E0,YPT,3)	007680
DO 160 T=1,100000		007690
110	YPTT=YPTT-I*TICU	007700
	IF (YPT .LT. 0E0) GOTO 1030	007710
	CALI_PLOT(XPT,YPT,2)	007720
	CALI_PLOT(XPT,-1,YPT,2)	007730
115	CALI_PLOT(XPT,YPT,2)	007740
160_CONTINUE		007750
170_CALI_PLOT(0E0,0E0,2)		007760
	ENCODE(10+1,SYM) YM1	007770
	CALI_SYMBOL(-1E0,0E0,-1E0,SYM+0E0+10)	007780
120	NY=INDEX(4,2)	007790
	IF (NY .EQ. 0) GOTO 190	007800
	CALI_SYMBOL(-4E0,0E0,-1E0,DATAIN(INDEX(4,1),1)+90,NA)	007810
180_CALI_PLOT(0E0,0E0,3)		007820
	RETURN	007830
125	END	007840

E.6 Subroutine INTERP

1	SUBROUTINE INTERP(CCODE,CCODE,FLAG,ICARD)	007850
	COMMON/LFT/LETTER(80)	007860
	DIMENSION CODE(7)	007870
	LOGICAL FLAG	007880
5	INTEGER CCODE,BLANK,C,L,LPAREN,RPAREN,Y,D,E/000000000000000000055B,	007890
	DATA BLANK,C,L,LPAREN,RPAREN,Y,D,E/00000000000000000000055B,	007900
	+000+0000+000000+0000000000000000000000000055B.	007910
	+000+0000+00000000000000000000000000000000000055B,	007920
	+000+00055B,	007930
10	CCODE=2	007940
	CODE(2)=1 .OR.	007950
	DO 90 I=1,80	007960
	LETTER(I)=BLANK	007970
95	CONTINUE	007980

15	READ(1,CARD,1) (LETTER(I),I=1,80)	007990
	IF (EOF(1,CARD)) 115-100	008000
115	FLAG=F.	008010
	GOTO 110	008020
100	CONTINUE	008030
20	FORMAT(RARL)	008040
	DO 120 I=1,80	008050
	N=I	008060
	IF (LETTER(I) .NE. R(ANK)) GOTO 130	008070
120	CONTINUE	008080
25	130 IF (I .EQ. 81) GOTO 110	008090
	IF (LETTER(N) .EQ. C) CODE=1	008100
	IF (LETTER(N+1) .EQ. L) CODE=3	008110
	GOTO (131,134,133) CODE	008120
30	C SET DEFAULT VALUES OF CODE.	008130
	131 CODE(1)=1 .OR. 0	008140
	CODE(3)=10 .OR. 0	008150
	CODE(4)=?HNA	008160
	CODE(5)=10H	008170
	GOTO 132	008180
35	134 CODE(1)=1 .OR. 0	008190
	CODE(3)=45.	008200
	CODE(4)=?HNA	008210
	GOTO 132	008220
40	133 CODE(1)=1 .OR. 0	008230
	CODE(3)=1HX	008240
	CODE(4)=1 .OR. 0	008250
	CODE(5)=1 .OR. 0	008260
	CODE(6)=?HNA	008270
	CODE(7)=10H	008280
45	132 DO 140 I=N,80	008290
	M=I	008300
	IF (LETTER(I) .EQ. LPAREN) GOTO 150	008310
140	CONTINUE	008320
150	IF (I .EQ. 81) GOTO 110	008330
50	CALI NUMR(CODE(1),M,1)	008340
	C IF M>1 THEN A RIGHT PAREN HAS BEEN FOUND. OTHERWISE IT RETURNS	008350
	C THE POSITION OF THE COMMA.	008360
	IF (M .EQ. 0) GOTO 110	008370
	CALI NUMR(CODE(2),M,1)	008380
55	IF (M .EQ. 0) GOTO 110	008390
	GOTO (160,170,140) CODE	008400
	160 CALI NUMR(CODE(3),M,1)	008410
	IF (M .EQ. 0) GOTO 110	008420
	CODE(4)=?HNA	008430
60	TF (LETTER(M+1) .EQ. D) CODE(4)=?HDN	008440
	TF (LETTER(M+2) .EQ. E) CODE(4)=?HNE	008450
	TF (LETTER(M+3) .EQ. 23A) CODE(5)=?HSD	008460
	GOTO 110	008470
65	170 CALI NUMR(CODE(3),M,2)	008480
	IF (M .EQ. 0) GOTO 110	008490
	TF (LETTER(M+2) .EQ. E) CODE(4)=?HNE	008500
	GOTO 110	008510
70	180 TF (LETTER(M+1) .EQ. Y) CODE(3)=?HY	008520
	TF (LETTER(M+2) .EQ. PPAREN) GOTO 110	008530
	TF (LETTER(M+1) .EQ. F6R) M=M-1	008540
	M=M+2	008550
	CALI NUMR(CODE(4),M,1)	008560
75	IF (M .EQ. 0) GOTO 110	008570
	CALI NUMR(CODE(5),M,1)	008580
	IF (M .EQ. 0) GOTO 110	008590
	CODE(6)=?HNA	008600
	TF (LETTER(M+1) .EQ. D) CODE(6)=?HDN	008610
	TF (LETTER(M+2) .EQ. E) CODE(6)=?HNE	008620
80	TF (LETTER(M+3) .EQ. 23A) CODE(7)=?HSD	008630
	110 RETURN	008640
	END	008650

E.7 Subroutine NUMB

1	SUBROUTINE NUMB(PARAM,M,FORMAT)	008660
	COMMON/LET/LETTER/RM	008670
	INTEGER PRAPEN,COMMA	008680
	DATA PRAPEN,COMMON/00000000000000000000000000000000000000568/	008690
	TOPAM=M	008700
5	C FORMAT IS THE FORMAT CODE FOR DECODING-1=>INTEGER,2=>FLOAT.	008710
	C M IS THE POSITION IN LETTER OF A 'DELIMITER' SUCH AS (OR). NUMB	008720
	C RETURNS M=0 IF A) IS FOUND.	008730
	M1=+1	008740
	NUM=0	008750
	DO 100 I=M1,80	008760
	M=1	008770
	IF (LETTER(I) .EQ. PRAPEN) 110,120	008780
10	M=0	008790
	GOTO 130	008800
	120 IF (LETTER(I) .EQ. COMMA) 130,150	008810
	150 NUM=NUM+1	008820
	C STORE THE RIGHT MOST CHARACTER FROM LETTER(I) AT CHARACTER	008830
	C NUM OF IPARAM.	008840
	IPARAM=MYPUTX(LETTER(I),IPARAM+NUM)	008850
20	130 CONTINUE	008860
	140 IF (I .EQ. M1) GOTO 160	008870
	TF(FORMAT,END) 170,180	008880
	170 CALL RJUST(IPARAM)	008890
	DECIDE ((I+1),IPARAM) PARAM	008900
25	180 FORMAT(T10)	008910
	GOTO 160	008920
	190 CALL PLOT(T10)	008925
	DECIDE ((I+2),IPARAM) PARAM	008930
30	200 FORMAT(F10.0)	008940
	160 RETURN	008950
	END	008960

E.8 Subroutine ARROW

1	SUBROUTINE ARROW(XP,YP,L,THETA,LABEL,NC)	008970
	C THETA IS THE ARROW ANGLE WRT X-AXIS IN DEGREES	008980
	C L IS THE LENGTH OF THE ARROW IN INCHES	008990
	C THE LOCATION OF THE ARROW TIP (XP,YP) IS RETURNED	009000
	C NC IS THE NUMBER OF CHARACTERS IN THE ARROW LABEL	009010
	REAL L	009020
	DIMENSION LABEL(11)	009030
	THETA=THETA*3.1415927/180.	009040
	XXP=L*COS(THETA)+XP	009050
	YYP=L*SIN(THETA)+YP	009060
10	XL=.24*L*COS(THETA-.1745)+XP	009070
	YL=.24*L*SIN(THETA-.1745)+YP	009080
	XU=.24*L*COS(THETA+.1745)+XP	009090
	YU=.24*L*SIN(THETA+.1745)+YP	009100
	CALL PLOT(XP,YP,3)	009110
	CALL PLOT(XXP,YYP,3)	009120
	CALL PLOT(XL,YL,2)	009130
	CALL PLOT(XP,YP,3)	009140
	CALL PLOT(XU,YU,2)	009150
20	XL=.25*L*COS(THETA+.0873)+XP	009160
	YL=.25*L*SIN(THETA+.0873)+YP	009170
	IF (NC .LE. 0) GOTO 1000	009180
	CALL SYMBOL(XU,YU,.1,LABEL+THETA+NC)	009190
25	1000 RETURN	009200
	END	009210
		009220

E.9 Subroutine APLACE

```

1      SUBROUTINE APLACE(XP,YP,XLEN1,YLEN1,THETA2)          009230
C THIS SUBROUTINE FINDS THE X,Y, COORDINATES (XP,YP) FOR THE TIP 009240
C OF THE ARROW WHICH INDICATES THE VIEW ANGLE (THETA2-DEGREES) 009250
C FOR PERSPECTIVE PLOTS                                         009260
5      X2=.5*XLEN1                                              009270
      Y2=.5*YLEN1                                              009280
      PI180=3.1415927/180.                                     009290
      TH=PI180*THETA2                                         009300
      R=SQRT((X2+.5)**2+(Y2+.5)**2)                           009310
      XD=Y2+R*COS(TH)                                         009320
      YD=Y2+R*SIN(TH)                                         009330
      RETURN                                                    009340
      END                                                       009350

```

E.10 Subroutine RD1

```

1      SUBROUTINE RD1(IT3,IP,MP,ZMAX,ZMIN,ISW,FLAG,TIM,XMIN,XMAX,YMIN, 009360
      *YMAX)                                                 009370
      COMMON 7(103,103)                                         009380
      DIMENSION BUF(101)                                         009390
      LOGICAL FLAG                                             009400
5      C THIS SUBROUTINE FILLS UP THE 'SURFACE ARRAY' Z(...), AND/OR FINDS THE 009410
      C SURFACE MAX. AND MIN., (ZMAX,ZMIN). IT ALSO RETURNS THE SIZE OF THE 009420
      C SURFACE (MP X NP), AND THE SURFACE PARAMETER VALUE, TIM. THE LOGICAL 009430
      C VARIABLE, FLAG, IS .TRUE. UNTIL AN END-OF-FILE IS REACHED AT WHICH 009440
      C POINT IT BECOMES FALSE. EACH UNFORMATTED RECORD OF THE INPUT FILE,IT3, 009450
      C IS ASSUMED TO BE OF THE FORM- 009460
      C   I    ROW NUMBER
      C   NP   TOTAL NO. OF ROWS
      C   Y    Y-VALUE CORRESPONDING TO THIS ROW
      C   TIM  SURFACE PARAMETER VALUE (E.G. TIME)
      C   MP   TOTAL NO. OF COLUMNS
      C   XMIN  VALUE ASSOCIATED WITH THE FIRST COLUMN
      C   XMAX  VALUE ASSOCIATED WITH THE LAST COLUMN
      C   BUF(I) MP SURFACE ELEMENTS OF THE I-TH ROW
      C TSW ACTS AS A SWITCH TO CONTROL THE ACTION OF RD1 AS FOLLOWS- 009470
      C TSW=1 => RETURN ZMAX,ZMIN ONLY
      C TSW=2 => RETURN SURFACE 7 AND ZMAX,ZMIN
      C TSW=3 => RETURN SURFACE 7 BORDERED BY ZEROS AND ZMAX,ZMIN
      C TSW=4 => SKIPS A SURFACE
      C NOTE THAT THE FIRST RECORD READ IS ASSUMED TO INCLUDE THE FIRST 009480
      C 'ROW' OF THE SURFACE
100     READ(IT3) I,NP,Y,TIM,MP,XMIN,XMAX,(BUF(J),J=1,MP)           009490
      IF (EOF(IT3)) 110,120
      110   FLAG=.F.
      GOTO 1000
120     IF (IS4.EQ.4) GOTO 220
      I1=I+1
      Z(I1,1)=7(I1,MP+2)=0.
      IF (I .EQ. 1) 210,220
35     210   ZMIN=ZMAX=BUF(1)
      YM1=Y
      MP2=MP+2
      DO 160 J=1,MP2
      90     Z(I,J)=0.
      220   IF (I .EQ. NP) YM1=X
      DO 160 J=1,MP
      170   ZT=BUF(J)
      IF (ZT .LT. ZMIN) ZMIN=ZT
      IF (ZT .GT. ZMAX) ZMAX=ZT
      GOTO (160,170,180) TSW
      170   Z(I,J)=ZT
      GOTO 160
180   Z(I1,J+1)=ZT
      GOTO 160

```

50	160	CONTINUE	009830
	230	IF (I .LT. NP) GOTO 100	009840
		GOTO (1000,1000,190,1000) 150	009850
	190	MP2=MP+2	009860
		NP2=NP+2	009870
55	200	DO 200 I=1,MP2	009880
	200	Z(NP2,J)=0.	009890
	1000	RETURN	009900
		END	009910

E.11 Subroutine CLEV

1		SUBROUTINE CLEV(NLEV,ZMAX,ZMIN,ZLEVS)	009920
		DIMENSION ZLEVS(1)	009930
		C THIS SUBROUTINE RETURNS NLEV EQUALLY-SPACED CONTOUR LEVELS BETWEEN ZMIN	009940
		C AND ZMAX (BUT NOT INCLUDING ZMIN)	009950
5		DEL=(ZMAX-ZMIN)/NLEV	009960
		DO 100 I=1,NLEV	009970
		ZLEVS(I)=ZMIN+I*DEL	009980
	100	CONTINUE	009990
		RETURN	010000
10		END	010010

E.12 Subroutine SKIP

1		SUBROUTINE SKIP(ITAPE,NSKIP,FLAG,N)	010020
		LOGICAL FLAG	010030
		IF (NSKIP .EQ. 0) GOTO 120	010040
		NPEC=N-NSKIP	010050
5		DO 100 I=1,NPEC	010060
		READ(ITAPE)	010070
		IF (EOF(ITAPE)) 110,100	010080
	100	CONTINUE	010090
		GOTO 120	010100
10	110	FLAG=.F.	010110
	120	RETURN	010120
		END	010130

E.13 Subroutine FACE

1		SUBROUTINE FACE(XP1,YP1,ZPP,THETA1,THETA2,NREFIN)	010140
		DIMENSION R(3,3)	010150
		COMMON/RLLOCK3/INUN, JNUN, XMIN, YMIN, DX, DY, SW1, IT6	010160
		COMMON/ DATA(103,103,2)	010170
5	101	WRITE(IT6,101)XP1,YP1,ZPP,THETA1,THETA2,INUN,JNUN,NREFIN	010180
		FORMAT(3(F6.2,1X),2(F7.4,1X),J(13,1X))	010190
		YES=3HYES	010200
		YNO=2HNO	010210
		INUM=INUN	010220
		JNUU=JNUN	010230
10		YPP=PP=Y01	010240
		XPP=XPP=XP1	010250
		XR = ZPP*COS(THETA2)/TAN(THETA1)	010260
		YR = ZPP*SIN(THETA2)/TAN(THETA1)	010270

```

15      XRAQ = XPP-XB          010280
        YRAQ = YPP-YB          010290
        XDP = XPP-XBAR         010300
        YDP = YPP-YBAR         010310
        DTS = SQR(XPP*XPP+YPP*YPP+ZPP*ZPP) 010320
        R(1,1) = -SIN(THETA2)   010330
        R(1,2) = COS(THETA2)    010340
        R(1,3) = 0.0             010350
        R(2,1) = -SIN(THETA1)*COS(THETA2) 010360
        R(2,2) = -SIN(THETA1)*SIN(THETA2) 010370
        R(2,3) = COS(THETA1)     010380
        R(3,1) = COS(THETA1)*COS(THETA2) 010390
        R(3,2) = COS(THETA1)*SIN(THETA2) 010400
        R(3,3) = SIN(THETA1)     010410
        DO 20 I=1,INUM          010420
        A = FLOAT(I)
        Y = A-YRAQ             010430
        DO 20 J=1,JNUM          010440
        R = FLOAT(J)
        X = B-XBAR              010450
        Z = DATA(I,J,1)          010460
        DATA(I,J,1) = R(1,1)*X + R(1,2)*Y + R(1,3)*Z 010470
        DATA(I,J,2) = R(2,1)*X + R(2,2)*Y + R(2,3)*Z 010480
        Z = DTS-(R(3,1)*X + R(3,2)*Y + R(3,3)*Z) 010490
        DATA(I,J,1) = DATA(I,J,1)/Z 010500
        DATA(I,J,2) = DATA(I,J,2)/Z 010510
        20 TNUM1 = INUM/2        010520
        JNUM1 = INUM/2          010530
        IF (YP .LE. 1.0) GO TO 45 010540
        IF (YP .GE. FLOAT(INUM)) GO TO 30 010550
        IF (XP .LE. 1.0) GO TO 40 010560
        IF (XP .GE. FLOAT(JNUM)) GO TO 39 010570
        30 DO 35 J=1,JNUM          010580
        DO 35 I=1,INUM1          010590
        T1 = DATA(I,J,1)          010600
        T2 = DATA(I,J,2)          010610
        DATA(I,J,1) = DATA(TNUM1-I,J,1) 010620
        DATA(I,J,2) = DATA(TNUM1-I,J,2) 010630
        DATA(TNUM1-I,J,1) = T1 010640
        DATA(TNUM1-I,J,2) = T2 010650
        35 GO TO 45               010660
        39 XP = YES                010670
        40 TTEMP = TNUM            010680
        INUM = JNUM               010690
        INUM = TTEMP              010700
        INUM = MAX0(INUM,JNUM)    010710
        40 DO 42 I=1,ITEMP          010720
        DO 41 J=1,I
        T1 = DATA(I,J,1)          010730
        T2 = DATA(I,J,2)          010740
        DATA(I,J,1) = DATA(I,T)    010750
        DATA(I,J,2) = T1           010760
        DATA(I,J,2) = DATA(I,T,2)  010770
        41 DATA(I,T,2) = T2       010780
        42 CONTINUE
        IF (XP .EQ. YES) GO TO 30 010790
        45 IF (DATA(I,1,1) .LT. DATA(1,INUM,1)) GO TO 46 010800
        IF (DATA(TNUM,JNUM+1) .LT. DATA(1,JNUM,1)) GO TO 50 010810
        GO TO 90
        46 IF (DATA(1,JNUM,1) .LT. DATA(TNUM,JNUM+1)) GO TO 50 010820
        GO TO 90
        50 DO 55 I=1,INUM          010830
        DO 55 J=1,JNUM1          010840
        T1 = DATA(I,J,1)          010850
        T2 = DATA(I,J,2)          010860
        DATA(I,J,1) = DATA(T,INUM+1-J,1) 010870
        DATA(I,J,2) = DATA(T,INUM+1-J,2) 010880
        55 DATA(T,INUM+1-J,1) = T1 010890
        55 DATA(T,INUM+1-J,2) = T2 010900
        90 CALL HIDE
        CONTINUE
        RETURN
        END

```

E.14 Subroutine HIDE

```

1      SUBROUTINE HIDE
011010
COMMON DATA(103,103,2)/BLOCK1/TEST(500,2),TEST1(500,2)*NUM/BLOCK2/
011020
10(2),0(2),JCUT
011030
COMMON/BLOCK3/INUM, XMIN, YMIN, DX, DY, SW1, IT6
011040
LOGICAL SW1
011050
SI7E=8
011060
KFLAG = 0
011070
JFLAG = 0
011080
IF (SW1) GOTO 200
011090
SMALL = DATA(I,J,1)
011100
BTG = SMALL
011110
DO = J=1, JNUM
011120
DO = I=1, TNUM
011130
IF (DATA(I,J,1) .LT. SMALL) SMALL = DATA(I,J,1)
011140
IF (DATA(I,J,1) .GT. BTG) BTG = DATA(I,J,1)
011150
XMIN = SMALL
011160
DX = (BTG-SMALL)/SI7E
011170
SMALL = DATA(I,J,2)
011180
BTG = SMALL
011190
DO = I=1, TNUM
011200
DO = J=1, JNUM
011210
IF (DATA(I,J,2) .LT. SMALL) SMALL = DATA(I,J,2)
011220
IF (DATA(I,J,2) .GT. BTG) BTG = DATA(I,J,2)
011230
YMIN = SMALL
011240
DY = (BTG-SMALL)/SI7E
011250
D = DY
011260
IF (DX .GE. DY) D=DY
011270
DY = 0
011280
DX = 0
011290
GOTO 2010
011300
2000 DO = 10, I=1, JNUM
011310
TEST(I,1) = DATA(I,T,1)
011320
TEST(I,2) = DATA(I,T,2)
011330
10 TEST1(I,1) = TEST(I,1)
011340
CALL LINE(TEST,TEST1,INUM+1+0,0,XMIN,DX,YMIN,DY,0)
011350
I = 1
011360
NUM = JNUM
011370
JCUT = 1
011380
JCUT = 2
011390
20 JCUT = JCUT + 1
011400
KFLAG = 0
011410
JFLAG = 0
011420
IF (JCUT .EQ. JNUM+1) GO TO 100
011430
I = 0
011440
DO = 25, I=2, NUM
011450
IF ((DATA(JCUT,JCUT,1) .LE. TEST(I,1)) .AND. (DATA(JCUT,JCUT,1)
011460
1.GE. TEST(I-1,1))) GO TO 31
011470
IF ((DATA(JCUT,JCUT,1) .LT. TEST(I,1)) .OR. (DATA(JCUT,JCUT,1)
011480
1.GT. TEST(I-1,1))) GO TO 35
011490
50 31 B = (TEST(I,2)-TEST(I-1,2))/(TEST(I,1)-TEST(I-1,1))
011500
C = TEST(I,2) - B*TEST(I,1)
011510
Y = B*DATA(JCUT,JCUT,1) + C
011520
IF (Y .NE. DATA(JCUT,JCUT,2)) GO TO 35
011530
I = J + 1
011540
55 35 CONTINUE
011550
IF (I*2*(J/2) .EQ. 1) GO TO 120
011560
GO TO 400
011570
100 JCUT = 1
011580
JCUT = JCUT + 1
011590
IF (JCUT .NE. INUM+1) GO TO 30
011600
RETURN
011610
120 IF (JCUT .EQ. 1) GO TO 200
011620
P(1) = DATA(JCUT,JCUT,1)
011630
P(2) = DATA(JCUT,JCUT-1,1)
011640
Q(1) = DATA(JCUT,JCUT,2)
011650
Q(2) = DATA(JCUT,JCUT-1,2)
011660
IF (P(2) .GE. 6.0) GO TO 130
011670
X = P(2)
011680
Y = Q(2)
011690
GO TO 200
011700
130 CALL DRAW(X*Y*K,KFLAG)
011710
IF (K .GT. NUM) GO TO 365
011720
200 P(1) = DATA(JCUT,JCUT,1)
011730
P(2) = DATA(JCUT-1,JCUT,1)
011740

```

```

75      Q(1) = DATA(JCUT, JCUT, 2)          011750
        Q(2) = DATA(JCUT-1, JCUT, 2)        011760
        IF (P(2) .GE. 6.0) GO TO 210       011770
        X1 = P(2)                          011780
        Y1 = Q(2)                          011790
        GO TO 305                         011800
80      210      CALL DRAW(X1,Y1,J,JFLAG)    011810
        IF (J .GT. NUM) GO TO 365         011820
        300      IF (JCUT .NE. 1) GO TO 305   011830
        K = 1                            011840
        GO TO 314                         011850
        305      CONTINUE                   011860
        600      FOR=AT (5H HERE)           011870
        IF (KFLAG .EQ. 1) GO TO 314       011880
        DO -10 T=1..NUM                  011890
        IF ((X .EQ. TEST(I,1)) .AND. (Y .EQ. TEST(I,2))) GO TO 313 011900
        310      CONTINUE                   011910
        311      FOR=AT (10H 310 EDRDP)     011920
        GO TO 365                         011930
        K = I                            011940
        314      IF (JFLAG .EQ. 1) GO TO 320  011950
        DO -15 T=1..NUM                  011960
        IF ((X1 .EQ. TEST(I,1)) .AND. (Y1 .EQ. TEST(I,2))) GO TO 318 011970
        315      CONTINUE                   011980
        316      FOR=AT (10H 316 EDRDP)     011990
        GO TO 365                         012000
        318      I = I
C       IF IFLAG IS SET, WE ARE LOOKING AT THE BACK OF THE SQUARE PIECE 012010
C       WHOSE CORNER IS DATA(JCUT,JCUT). IN THIS CASE WE DO NOT DRAW THE 012020
C       LINE TO DATA(JCUT,JCUT-1). AND WE DO NOT INCLUDE IT IN THE SKYLINE. 012030
C       C.T.E. TEST.                                         012040
        105      IFLAG = 0                   012050
        IF (JFLAG .EQ. 0) J = J + 1
        IF (J .LT. K) IFLAG = 1
        IF ((J .EQ. K) .AND. (ABS(X1-TEST(J,1)) .GT. ABS(X-TEST(J,1)))) 012060
        320      IFLAG = 1
        IF (JFLAG .EQ. 0) J = J + 1
        IF (J .LT. K) IFLAG = 1
        IF ((J .EQ. K) .AND. (ABS(X1-TEST(J,1)) .GT. ABS(X-TEST(J,1)))) 012070
        110      IFLAG = 1
        IFLAG = 0
        KFLAG = 1
        TI = 0
        DO -30 I=J..NUM
        TI = TI + 1
        TEST1(I,I,1) = TEST(I,1)
        320      TEST1(I,I,2) = TEST(I,2)
        IF (IFLAG .EQ. 0) GO TO 331
        K = J
        X = X1
        Y = Y1
        GO TO 375
        331      IF (JCUT .NE. 1) GO TO 335
        K = K - 1
        GO TO 341
        335      TEST(K+1,1) = X
        TEST(K+1,2) = Y
        340      TEST(K+1,1) = DATA(JCUT,JCUT,1)          012100
        TEST(K+1,2) = DATA(JCUT,JCUT,2)          012110
        TEST(K+2,1) = X1
        TEST(K+2,2) = Y1
        K = K + 2
        IF (J .EQ. (NUM + 1)) GO TO 350
        DO -45 T=1..I
        K = K + 1
        TEST(K+1,1) = TEST1(I,1)
        345      TEST(K+2,1) = TEST1(I,2)
        641      FOR=AT (1H 3110)
        350      NUM = K
        IF (JCUT .EQ. 1) GO TO 355
        IF (IFLAG .EQ. 1) GO TO 355
        P(2) = X
        Q(2) = Y
        CALI LINP(P,0+2+1,0,0,XMIN+DX+YMIN,DY,0+) 012120
        355      P(2) = X1
        Q(2) = Y1
        CALI LINP(P,0+2+1,0,0,XMIN+DX+Y4TN,DY,0+) 012130
        365      GO TO 20
        400      CONTINUE
        401      FOR=AT (4H 400,PX,II0)
        IF (JCUT .EQ. 1) GO TO 500
        P(1) = DATA(JCUT, JCUT-1, 1) 012140
        P(2) = DATA(JCUT, JCUT, 1) 012150

```

```

40      D(1) = DATA(1CUT+JCUT-1,2)          012540
        D(2) = DATA(1CUT+JCUT,2)           012550
        IF (P(1) .GE. 6.0) GO TO 540
        CALL DRAW(X,Y,K,KFLAG)
        IF (K .GT. NUM) GO TO 545
        P(2) = X
        P(1) = Y
        CALL LINE(P,0,2,1,0.0,XMIN+DX,YMIN,DY,0.)
420      IC = 1CUT                         012610
        JC = JCUT - 1                      012620
        CALL SORT(IC,JC,X,Y)              012630
540      P(1) = DATA(1CUT-1,JCUT,1)         012640
        P(2) = DATA(1CUT-1,JCUT,2)         012650
        D(1) = DATA(1CUT-1,JCUT-1)         012660
        D(2) = DATA(1CUT-1,JCUT-2)         012670
        IF (P(1) .GE. 6.0) GO TO 545
        CALL DRAW(X,Y,J,IFLAG)
        IF (J .GT. NUM) GO TO 545
        P(2) = X
        P(1) = Y
        CALL LINE(P,0,2,1,0.0,XMIN+DX,YMIN,DY,0.)
55      IC = 1CUT - 1                     012680
        JC = JCUT                          012690
        CALL SORT(IC,JC,X,Y)              012700
545      DATA(1CUT,JCUT+1) = DATA(1CUT,JCUT+1) + SIZE
        GO TO 365
175      520      RETURN
180      END

```

E.15 Subroutine DRAW

```

1       SUBROUTINE DRAW(X,Y,K,KFLAG)
COMMON /BLOCK1/TEST(500,2),TEST1(500,2)+NUM/BLOCK2/P(2),n(2)+JCUT
SIZE=0
DS=0
IF (P(2) .GE. 6.0) GO TO 10
GO TO 15
15     P(2)=P(2)-SIZE
16     Y=15.0
S=.00001
R1=(n(2)-n(1))/(P(1)-P(2))
I0=LEGVAR(R1)
IP=IP+1
IF (IP .NE. 0) GO TO 20
C1=n(1)+R1*I(1)
20     DO 40 I=0,NUM
DX=TEST(I+1)-TEST(I-1,1)
DY=TEST(I+2)-TEST(I-1,2)
DS=S*SQRT(DX*DX+DY*DY)
R2=(TEST(I-1,2)-TEST(I,2))/(TEST(I,1)-TEST(I-1,1))
IT=LEGVAR(R2)
IF (IT .NE. 0) GO TO 35
C2=TEST(I,2)+.024*TEST(I+1)
IF (IP .NE. 0) GO TO 40
XX=(C2-C1)/(R2-R1)
IF (LEGVAR(XX) .NE. 0) GO TO 40
YY=C1-R1*XX
40     IF ((TEST(I-1,1)-DS .LE. XX) .AND. (XX.LE. TEST(I,1)+DS)) GO TO 30
IF ((TEST(I,1)-DS .LE. XX) .AND. (XX.LE. TEST(I-1,1)+DS)) GO TO 30
GO TO 90
30     IF ((P(1))-DS .LE. XX) .AND. (XX.LE. P(2)+DS)) GO TO 45
IF ((P(2))-DS .LE. XX) .AND. (XX.LE. P(1)+DS)) GO TO 45
GO TO 90
35     IF (IP .NE. 0) GO TO 90
XX=TEST(I,1)
YY=C1-R1*XX
IF ((TEST(I-1,2)-DS .LE. YY) .AND. (YY.LE. TEST(I,2)+DS)) GO TO 30
IF ((TEST(I,2)-DS .LE. YY) .AND. (YY.LE. TEST(I-1,2)+DS)) GO TO 30
GO TO 90
40     XX=P(1)
YY=C2-R2*XX

```

```

40      IF / (Q(1)=DS .LE. YY) .AND. (YY.LE. Q(2)*DS) GO TO 20
        IF / (Q(2)=DS .LE. YY) .AND. (YY.LE. Q(1)*DS) GO TO 25
        GO TO 90
45      DX = P(1)-XX
        DY = Q(1)-YY
        D = SORT(DX*DX+DY*DY)
        IF (D .LT. DIS) GO TO 90
        DIS = D
153     FORMAT (1H ,F10.3)
        X=XX
        Y=YY
        K = I
90      CONTINUE
        IF (Y .EQ. 15.0) GO TO 110
152     FORMAT (1H ,110.1X*F10.3)
        KFLAG = 1
151     FORMAT (4H 150,*X,I10)
        RETURN
110     K = NUM + 1
171     FORMAT (15H ERROR AT .ACUTE=I2)
        RETURN
60      END.

```

E.16 Subroutine SORT

```

1      SUBROUTINE SORT(IC,JC,K,X,Y)
COMMON DATA(103,1n3,2)/ALOCK1/TEST(500,2),TEST1(500,2)*NUM
COMMON/ALOCK3/INUM,INUM,XMIN,YMIN,DX,DY,SW1,IT6
DO 10 I=1,NUM
5      IF /TEST(I,1) .NE. DATA(IC,JC,1)) GO TO 10
        IF /TEST(I,2) .NE. DATA(IC,JC,2)) GO TO 10
        I = I
        GO TO 20
10     CONTINUE
431     FORMAT (4H 430,*2X,4HK = .I3,T10)
        GO TO 99
20     IF (J .LT. K) GO TO 30
        IF /J .EQ. K) GO TO 99
        KK = J
        JJ = K
        GO TO 40
30     KK = K
        JJ = J + 1
        II = 0
40     DO E0 I=KK,NUM
        II = II + 1
        TEST1(II,1) = TEST(T,1)
50     TEST1(II,2) = TEST(T,2)
        TEST(T,1) = X
        TEST(T,2) = Y
        DO 40 I=1,II
        JJ = JJ + 1
        TEST(JJ,1) = TEST1(T,1)
60     TEST(JJ,2) = TEST1(T,2)
        NUM = JJ
        RETURN
99     END

```

E.17 Subroutine PARFIT

```

1      SUBROUTINE PARFIT(Y1,Y2,Y3,YF1,YF2)          013750
C THIS SUBROUTINE FITS A PARABOLA TO THREE DATA POINTS Y1,Y2,Y3, TAKEN     013760
C AT EQUAL INTERVALS AND COMPUTES POINTS YF1,YF2, ON THE FITTED PARABOL    013770
C * AT THE MIDDLE OF THE INTERVALS                                         013780
5      C
       A=(Y1+Y3-2.*Y2)/B,                                              013790
       B=(Y3-Y1)/4.,                                                 013800
       C=Y2,                                                        013810
       YF1=A-B+C,                                              013820
10     YF2=A+B+C,                                              013830
       RETURN,                                                013840
       END,                                                     013850
                                         013860

```

E.18 Subroutine CONTOR

```

1      SUBROUTINE CONTOR(M,N,NLEVS,HLEVS=BLANK,XLEN,YLEN,XP,YP)        013870
C
C DRAW PENTRIP CONTOURS FROM RECTANGULAR GRID INPUT                     013880
C
C
5      C PARAMETERS
C
C   Z         THE GIVEN FUNCTION                                     013930
C   M         NUMBER OF ROWS IN Z ARRAY                             013940
C   N         NUMBER OF COLS IN Z ARRAY                            013950
10     C   XT        TEMPORARY ARKAY      SIZE=(M*N)                  013960
C   YT        TEMPORARY ARKAY      SIZE=(M*N)                  013970
C   NLEVS    NUMBER OF CONTOURS                                013980
C   HLEVS    CONTOUR VALUES                                013990
C   BLANK    MSNG DATA CODE                                014000
C   XLEN     LENGTH OF X-AXIS IN INCHES                        014010
C   YLEN     LENGTH OF Y-AXIS IN INCHES                        014020
C
C   Z(I,J) ASSUMED TO BE IN ASCENDING ORDER BY X AND Y
C   TE       Z(I,1) = Z(XMIN,YMIN)                           014040
C   Z(M,N) = Z(XMAX,YMAX)                           014050
20     C
C
C   PROGRAM WILL PLOT ANY NUMBER OF CONTOURS                         014060
C   LINES ARE LABELED BY CHARACTERS 0 - 12
25     C   CHARACTERS ARE REPEATED AS NECESSARY                      014070
C
C   USES SUBROUTINES NETROR AND FUUR
C
C
30     DIMENSION HLEVS(1)
C   COMMON Z(103,103),XT(103,103),YT(103,103)                   014150
C   DIMENSION T(150)                                            014160
C   DIMENSION SX(3),SY(3),IC(9)                                014170
C   DIMENSION IO(16),IP(16)                               014180
C   DATA (IO(I),I=1,16),/1,-1,-2,-1,-1,-2,-1,-1,-1,0,0,0,0,0,-1/
35     C   DATA (IP(I),I=1,16),/1,-1,-1,0,0,1,0,0,1,0,0,0,-1,-1,-1/
C
C   K=75
C   XMTN=YMNTN=0E0
40     C   IFLAG=1
C   YSYM=YP-.2
C   XPLT=XLEN+XP
C   JLNE=8
C
C
45     C   CALL PLT(0.0,0.0,3)
C   XS17E=FLOAT(N-1)/XLEN
C   YS17E=FLOAT(M-1)/YLEN
C   UD=MN
C
C   FIND ZMAX, ZMIN
                                         014200
                                         014210
                                         014220
                                         014230
                                         014240
                                         014250
                                         014260
                                         014270
                                         014280
                                         014290
                                         014300
                                         014310
                                         014320
                                         014330
                                         014340
                                         014350

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54      C          014360
          IMAX=0
          DO 12 I=1,M
          DO 12 J=1,N
          IF (Z(I,J).EQ.BLANK) GO TO 12
          IMAX=IMAX+1
          IF (IMAX.GT.1) GO TO 11
          ZMAX=Z(I,J)
          ZMIN=Z(I,J)
          GO TO 12
55      11      IF (Z(I,J).GT.ZMAX) ZMAX=Z(I,J)
          IF (Z(I,J).LT.ZMIN) ZMIN=Z(I,J)
          CONTINUE
12      CONTINUE
          PRINT 100, ZMIN,ZMAX,NLEVS,(MLEVS(I),I=1,NLEVS)
65      C          014510
          C GET H.
          C
          ILEVS=0
99      ILEVS=ILEVS+1
          LLEVS=ILEVS-1
          IF (ILEVS.GT.NLEVS) GO TO 999
          H=H(EVS(ILEVS))
          PRINT 200, H
          TDNE=0
          IF ((H.GE.ZMIN).AND.(H.LE.ZMAX)) GO TO 101
          PRINT 300
          GO TO 99
          C
          C PREPARE THE XT-TABLE
          C
101     DO 102 I=1,M
          DO 102 J=1,N
          XT(I,J)=ID
          IF (I.EQ.M) GO TO 102
          IF (Z(I,J).EQ.BLANK) GO TO 102
          IF (Z(I+1,J).EQ.BLANK) GO TO 102
          IF (((Z(I,J)-H)*(Z(I+1,J)-H)).GE.0.0) GO TO 102
          XT(I,J)=ARS(FLOAT(I-1)+(H-Z(I,J))/(Z(I+1,J)-Z(I,J)))
102     CONTINUE
90      C          014750
          C PREPARE THE YT-TABLE
          C
          DO 103 I=1,M
          DO 103 J=1,N
          YT(I,J)=ID
          IF (J.EQ.N) GO TO 103
          IF (Z(I,J).EQ.BLANK) GO TO 103
          IF (Z(I,J+1).EQ.BLANK) GO TO 103
          IF (((Z(I,J)-H)*(Z(I,J+1)-H)).GE.0.0) GO TO 103
          YT(I,J)=ARS(FLOAT(J-1)+(H-Z(I,J))/(Z(I,J+1)-Z(I,J)))
100     103    CONTINUE
          C
          DO 201 I=1,4
201     IC(I)=0
          DO 207 I=1,M
          DO 207 J=1,N
          IF (Z(I,J).NE.H) GO TO 207
          C
          C COUNT ENTRANCES AND EXITES IN SURROUNDING BLOCKS
          C
          DO 202 I2=1,16
          I2=I0(I2)+1
          IF (II.LT.1.OR.II.GT.M) GO TO 202
          II=IP(I2)+J
          IF (JJ.LT.1.OR.JJ.GT.N) GO TO 202
          II=(I2+1)/4+1
          IF ((XT(I,J)).NE.ID1 .OR. (YT(I,J)).NE.ID2) IC(I)=IC(I)+1
202     CONTINUE
          IHOLD=0
          DO 206 I2=1,4
          IC(I2)=MOD(IC(I2),2)
          IF (IC(I2).EQ.0) GO TO 206
          IF (IHOLD.NE.0) GO TO 203
          IHOLD=I2
          GO TO 206
120     203    IF (I2-IHOLD.EQ.1) GO TO 204
          IF (IHOLD.EQ.1.AND.I2.EQ.4) GO TO 205
          GO TO 301
          IF (I2+IHOLD.EQ.5) GO TO 205

```

130	T3=T+T2-3 XT(I3,J)=-ABS(FLOAT(T3-1)+.001)	015160 015170
	GO TO 207	015180
205	I3=I-1 J4=I4-T2 YT(I3,J4)=-ABS(FLOAT(J4)+.001)	015190 015200 015210
135	GO TO 207	015220
206	CONTINUE	015230
207	CONTINUE	015240
C		015250
140	301 IL=-30 JL=-30 KL=-30 XF=10 YF=10	015260 015270
145	C C COMPILE A LIST C	015280 015290 015300
	302 CONTINUE	015310 015320
150	DO 203 I=1+N DO 203 J=1+N KEY=1 IF (XT(I,J).NE.UD) GO TO 304 KEY=2 IF (YT(I,J).NE.UD) GO TO 304	015330 015340 015350 015360 015370 015380
155	155 303 C IF (IDONE.EQ.0) PRINT 400 GO TO 99	015390 015400 015410 015420 015430 015440 015450 015460
160	C 304 IX=? IF (NEIROR(KEY+I,J,KL,IL,JL),LE.0) GO TO 305	015470 015480 015490 015500
	IX=? T(1)=XF T(2)=YF	015510 015520
165	305 IL=I IL=I KL=KEY LR=1 GO TO (306,307), KEY	015530 015540 015550 015560
170	306 XF=YT(I,J) YF=I-1 GO TO 401	015570 015580
	307 XF=I-1 YF=YT(I,J)	015590 015600
175	C C ADD A POINT TO THE LIST C	015610 015620 015630
	401 XS=YF YS=YF ISAVE=I JSAVE=J KSAVE=KEY	015640 015650 015660 015670
180	402 IF ((IX-K+2),LT.0) GO TO 404 I47=1 GO TO 801	015680 015690 015700
185	403 CONTINUE T(1)=T(IY-1) T(2)=T(IY) IX=? IX=IX+2 T(IY-1)=ARS(XS)	015710 015720 015730 015740 015750 015760
190	404 T(IY)=ARS(YS) IF (I47,EQ.1) GO TO 405 IF (IX,LT.6) GO TO 406	015770 015780 015790 015800
195	405 IF (KSAVE,EQ.1) XT(TSAVE,JSAVE)=UD IF (KSAVE,EQ.2) YT(TSAVE,JSAVE)=UD	015810 015820
	406 IF (IX,Eq.?) GO TO 501 GO TO (407,409), KEY	015830 015840
200	C C THE POINT IS ON AN HORIZONTAL LINK C	015850 015860 015870
	407 IF (XT(I,J).GE.0.0) GO TO 408 XT(I,J)=ARS(XT(I,J))	015880 015890
205	GO TO 501 408 XT(I,J)=ID GO TO 501	015900 015910 015920
C		015930 015940 015950
C C THE POINT IS ON A VERTICAL LINK C		

210	400	IF (YT(I,J).GE.9,0) GO TO 410 YT(I,J)=ABS(YT(I,J)) GO TO 501	015960 015970 015980 015990 016000 016010 016020 016030 016040 016050 016060 016070 016080 016090 016100 016110 016120 016130 016140 016150 016160 016170 016180 016190 016200 016210 016220 016230 016240 016250 016260 016270 016280 016290 016300 016310 016320 016330 016340 016350 016360 016370 016380 016390 016400 016410 016420 016430 016440 016450 016460 016470 016480 016490 016500 016510 016520 016530 016540 016550 016560 016570 016580 016590 016600 016610 016620 016630 016640 016650 016660 016670 016680 016690 016700 016710 016720 016730 016740 016750
215	410	YT(I,J)=0D	
	C		
	C	INTO BOX - IS THERE A WAY OUT	
	C		
	501	KH=1 ISAVE=I JSAVE=J KSAVE=KEY GO TO (502,601), KEY CONTINUE IF (LR,FN,2) GO TO 505 IF (J,EN,NI) GO TO 701 IF (XT(I,J+1),ED,UD) GO TO 503 KH=KH+1 KS=1 SX(1)=XT(I,J+1) SY(1)=J CONTINUE IF (YT(I,J).EQ.UD) GO TO 504 KH=KH+1 KS=2 SX(2)=I-1 SY(2)=YT(I,J) CONTINUE IF (I,EN,M) GO TO 508 IF (YT(I+1,J).EQ.UD) GO TO 508 KH=KH+1 KS=3 SX(3)=I SY(3)=YT(I+1,J) GO TO 509 CONTINUE IF (J,EN,1) GO TO 701 IF (XT(I,J-1).EQ.UD) GO TO 506 KH=KH+1 KS=4 SX(4)=XT(I,J-1) SY(4)=J-2 CONTINUE IF (YT(I,J-1).EQ.UD) GO TO 507 KH=KH+1 KS=5 SX(5)=I-1 SY(5)=YT(I,J-1) CONTINUE IF (I,EN,M) GO TO 508 IF (YT(I+1,J-1).EQ.UD) GO TO 508 KH=KH+1 KS=6 SX(6)=I SY(6)=YT(I+1,J-1) IF (KH,FN,0,OR,KH,EN,2) GO TO 701 IF (KH,NC,1) CALL FOUR (T,IX,SX,SY,KS,KEY) GO TO (509,510,511,512,513,514), KS 509 KEY=1 LR=1 J=J+1 GO TO 516 510 KEY=2 LR=2 GO TO 516 511 KEY=2 I=I+1 LR=1 GO TO 516 512 KEY=1 LR=2 GO TO 515 513 KEY=2 LR=2 GO TO 515 514 KEY=2 I=I+1 LR=1 515 KS=KS-3 J=J-1 516 XS=XS(KS)	

294		YS=ST(I,S)	016700
		IF(IFLAG=2)	016770
		GO TO 402	016780
	C		016790
	C		016800
295	601	CONTINUE	016810
		IF (I>E0,M) GO TO 604	016820
		IF (I,E0,M) GO TO 701	016830
		IF (XT(I,J),E0,HD) GO TO 602	016840
		KH=KH+1	016850
300		KS=1	016860
		SY(1)=XT(I,J)	016870
		SY(1)=J-1	016880
	602	CONTINUE	016890
		IF (J,E0,N) GO TO 603	016900
305		IF (XT(I,J+1),E0,HD) GO TO 603	016910
		KH=KH+1	016920
		KS=2	016930
		SY(2)=XT(I,J+1)	016940
		SY(2)=J	016950
310	603	CONTINUE	016960
		IF (I,E0,M) GO TO 607	016970
		IF (YT(I+1,J),E0,HD) GO TO 607	016980
		KH=KH+1	016990
		KS=3	017000
315		SY(3)=I	017010
		SY(3)=YT(I+1,J)	017020
		GO TO 607	017030
	604	CONTINUE	017040
		IF (I,E0,I) GO TO 711	017050
320		IF (XT(I-1,J),E0,HD) GO TO 605	017060
		KH=KH+1	017070
		KS=4	017080
		SY(4)=XT(I-1,J)	017090
		SY(4)=J-1	017100
325	605	CONTINUE	017110
		IF (J,E0,N) GO TO 606	017120
		IF (XT(I-1,J+1),E0,HD) GO TO 606	017130
		KH=KH+1	017140
		KS=5	017150
		SY(5)=XT(I-1,J+1)	017160
		SY(5)=J	017170
330	606	CONTINUE	017180
		IF (YT(I-1,J+1),E0,HD) GO TO 607	017190
		KH=KH+1	017200
		KS=6	017210
		SY(6)=I-2	017220
		SY(6)=YT(I-1,J)	017230
	607	CONTINUE	017240
		IF (KH,E0,Q,DR,KH,E0,P) GO TO 701	017250
340		IF (KH,NC,F,I) CALL FDMP (T*IX,SY,KS,KEY)	017260
		GO TO (608,609,...10,611,612,613)+ KS	017270
	608	KEY=1	017280
		L9=2	017290
		GO TO 615	017300
345	609	KEY=1	017310
		I=2	017320
		I=J+1	017330
		GO TO 615	017340
	610	KEY=2	017350
350		I=I+1	017360
		L9=1	017370
		GO TO 615	017380
	611	KEY=1	017390
		L9=2	017400
355		GO TO 614	017410
	612	KEY=1	017420
		L9=1	017430
		I=J+1	017440
		GO TO 614	017450
360	613	KEY=2	017460
		I=2	017470
	614	I=I-1	017480
		KS=KS-3	017490
	615	X5=SY(KS)	017500
		YS=SY(KS)	017510
		IF(IFLAG=2)	017520
		GO TO 402	017530
	C		017540
365		C NO MORE POINTS	017550

374	701	IF (NEIROR(KEY+I,J+KL,JL),LE,0) GO TO 704 IF (IX,LT,6) GO TO 704 IF (T(1),EQ,T(IX-1),AND,T(2),EQ,T(IX)) GO TO 704 IX=IX+2 T(IX-1)=ABS(XF) T(IX)=ABS(YF)	017560 017570 017580 017590 017600 017610 017620 017630 017640 017650 017660 017670 017680 017690 017700 017710 017720 017730 017740 017750 017760 017770 017780 017790 017800 017810 017820 017830 017840 017850 017860 017870 017880 017890 017900 017910 017920 017930 017940 017950 017960 017970 017980 017990 018000 018010 018020 018030 018040 018050 018060 018070 018080
375	C	GO TO (702,703)+ KEY	
380	702	XT(I,J)=UD GO TO 704	
385	703	YT(I,J)=UD GO TO (702,704)+ TFLAG T47=2	
390	801	C LLTNE=MOR(LLTNE,13) IF (IX,NE,2) GO TO 801 IF (LR,EN,2) GO TO 802 LR=2 GO TO 501	
395	802	IF (KEY,EN, 1) XT(I,J)=UD IF (KEY,EN, 2) YT(I,J)=UD GO TO 902	
400	901	C C 901 IDONE=IDONE+1 CALL LINE (T(2),T(1),IX/2+2,JLINE,LLINE,XMIN,XSIZE,YMIN,YSIZE,,06) IF (IDONE,GT,1) GO TO 902 YSYMB=YSYM#-0.2 IF (YSYMB,LT, 0.) 110+120 YSYMB=YP--.2 XPLT=XPLT+2. 120 CALL SYMBOL (XPILT ,YSYMB,0.09,LLTNE,0.0,-1) CALL SYMBOL (3HOLD,3HOLD,,09,1H=00,1) ENCODE(1n,1,SYM) H CALL SYMBOL (3HOLn,3HOLD,,09,TSYM,0.0,10) PRINT 500, LLINE	
405	902	PRINT 500, LLINE 902 IF (I47,EN, 1) GO TO 403 IFLAG=1 I=I .I=JI KEY=KL GO TO 301	
410	C	1 FORMAT(G10.3) 100 FORMAT (*1BEGIN CONTOUR PLOT*,2G13.5,75/(5X,10G13.5)) 200 FORMAT (* CONTOUR*,G13.5) 300 FORMAT (10X,*OUTSIDE GRID*) 400 FORMAT (10X,*NO DATA*) 500 FORMAT (10X,*PLOTTED CHARACTER*,13)	
420	990	C 990 RETURN END	

E.19 Subroutine NEIBOR

```

1      FUNCTION NEIBOR (KA,TA,IA,KB,IB,IB)
C
C      NETBDR=-1 IF NOT NEIGHBORS
5      NETBDR = 1 IF NEIGHBORS
C
C      DIMENSION K1(14),K2(14),IT(14),JT(14)
10     DATA K1/1,1,1,1,1,2,2,2,2,2,2,1,2/
          DATA K2/1,1,2,2,2,2,1,1,1,2,2,1,2/
          DATA IT/.0,.0,.0,.1,.1,.0,.0,-1,-1,1,-1,0,0/
          DATA JT/-1,1,0,-1,-1,0,1,0,1,0,0,0,0,0/
          ID = TB-TA
          JD = JB-IA
15     DO 90 I=1,14
          IF (KA-K1(I)) .EQ. 50,90
          IF (KA-K2(I)) .EQ. 60,90
          IF (ID-JT(I)) .EQ. 80,90
          IF (JD-JT(I)) .EQ. 90,90
20     CONTINUE
          NETBDR = -1
          GO TO 100
90     NETBDR = 1
          RETURN
25     100 CONTINUE
          RETURN
          END

```

018090
018100
018110
018120
018130
018140
018150
018160
018170
018180
018190
018200
018210
018220
018230
018240
018250
018260
018270
018280
018290
018300
018310
018320
018330
018340
018350

E.20 Subroutine FOUR

```

1      SUBROUTINE FOUR(T,IX,SX,SY,KS,KEY)
DIMENSION T(150),SX(3),SY(3)
IF (IX.GE.,4) GO TO 499
KS=2
5      RETURN
499 SLOP=T-(T(IX)-T(IX-2))/(T(IX-1)-T(IX-3))
DO 515 I=1,3
XS=ABS(SY(I))
YS=ABS(SY(I))
SLOPE=(T(IX)-YS)/(T(IX-1)-XS)
IF (SLOP+SLOPE .LT. 0.0) GO TO 515
IF (KEY.EQ.,1 .AND. I1.EQ.,1) GO TO 515
IF (KEY.EQ.,2 .AND. I1.EQ.,3) GO TO 515
IF (KS.LE.,3) GO TO 1
KS=1+3
515 CONTINUE
RETUR
1 KS=1
RETUR
20     515 CONTINUE
RETUR
END

```

018360
018370
018380
018390
018400
018410
018420
018430
018440
018450
018460
018470
018480
018490
018500
018510
018520
018530
018540
018550
018560

E.21 Function SYMBL

1	FUNCTION SYMBL(TTM)	018750
	TF: (MVGFTX(TTM+1,1) .EQ. 55H) GOTO 100	018760
	ENCODE(18+1,SYMBL) TTM	018770
	RETURN	018780
100	SYMBL=TTM	018790
	RETURN	018800
1	FORMAT(610,3)	018810
	END	018820

Appendix F

Fortran Listing for Program T3D

```

1      PROGRAM T3D(TAPE3,OUTPUT)
C REVISION---SEPT 18,1975
C PURPOSE---DISPLAY VALUES OF F1 AND F2 FROM TAPE3 (TEMPS OUTPUT)
C USING LINEAR INTERPOLATION BETWEEN TIMES.
5      C SUBROUTINE---
C       RTAPE3
        INTEGER DATAIN(100,3)
        EQUIVALENCE(I11,DATAIN)
        DATA IT3/3/
10      REWIND IT3
        READ(IT3) DATAIN
        TLAST=TNEXT=0.
        IP=1
        DELT=.1*TAUXN
15      WRITE 1,N0,NMX,DTAU0,TAUMX
        DO 100 I=1,10
        T=DELT*I
        CALL RTAPE3(T)
        WRITE 2,T
20      WRITE 3,(F1(IJ),J=1,81,10)
        WRITE 3,(F2(J),J=1,81,10)
100    CONTINUE
1      FORMAT(1H1,* N0=*I3*, NMX=*I3*, DTAU0=*E13.6* TAUMX=*E13.6/
** VALUES OF F1 AND F2 AT 1,11,...,81*)
25    2 FORMAT(* TAU=*E13.6)
3      FORMAT(* (4E13.6))
        END

```

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