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RESEARCH AND DEVELOPMENT OF EFFECT OF RANGE OF STRESS AND PRESTRAIN ON THE FATIGUE PROPERTIES OF TITANIUM AND ITS ALLOYS -INTERIM REPORT PREPARED BY CARNEGIE INSTITUTE OF TECHNOLOGY **~**; 10 ഹ 5. ~ OFFICE CHIEF OF ORDNANCE RESEARCH AND DEVELOPMENT BRANCH AL UNDER CONTRACT NO. DA -36-061-ORD-68 :

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Title of Project

RESEARCH AND DEVELOPMENT OF EFFECT OF RANGE OF STRESS AND PRESTRAIN

ON THE FATIGUE PROPERTIES OF TITANIUM AND ITS ALLOYS

Object

To report on the construction and calibration of two fatigue testing machines.

Summary

Two fatigue machines were constructed for the study of the effect of range of stress and prestrain on titanium and titanium alloys. The machines are identical in design with a machine previously designed and constructed by the Department of Civil Engineering of Carnegie Institute of Technology. The machines of the rotating-beam type are readily assembled and operated. A full range of loading from pure tension to pure bending in any combination can be obtained. The machines have been calibrated for both static and dynamic loading and proved adequate throughout their operative range.

Conclusion

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The machines are fully described, and calibration data are summarized in tables and graphs. Working formulas and a nonographic chart bring the analysis of combined stresses into convenient form for use in the laboratory. A REPORT ON THE CONSTRUCTION AND CALIBRATION

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OF TWO FATIGUE TESTING MACHINES

BY

CARNEGIE INSTITUTE OF TECHNOLOGY

PITTSBURGH, PENNSYLVANIA MARCH 1, 1952

CONTENTS

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Thereduction	J
Synopsis Acknowledgements	1 2
Description of Machine	2
Details of Construction and Design	4
Calibration of Fatigue Machine	5
Operation Curves	8
Correction Factors	9
Summary and Conclusions	10
Appendix A - Development of Formula for Combined Bending and Tension	11
Appendix B - Notation	12

LIST OF FIGURES

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Figure

- 1 Schematic Drawing of Fatigue Machine
- 2 Section View of Connections of Specimen, Chuck, and Shaft
- 3 Section View of Bearing Housing

4 Calibration Specimen

5 Stress Strain Curve for Assembly Specimen

6 Results of Static Calibration Test in Pure Tension (Machine No 1)

7 Results of Static Calibration Test in Pure Tension (Machine No 2)

8 Results of Static Calibration Test in Pure Bending (Machine No 1)

- 9 Results of Static Calibration Test in Pure Bending (Machine No 2)
- 10 Curves From the Oscillograph Showing the Strain in the Specimen Under Repeated Loading for Machine No 1
- 11 Curves From the Oscillograph Showing the Strain in the Specimen Under Repeated Loading for Machine No 2

12 Curves of Mo, To, Plotted Against Stress Ratio

- 13 Nomograph for the Solution of Equation (3)
- 14 Moment Diagram for Specimen and Shaft Assembly

15 Photograph of Fatigue Machine

LIST OF TABLES

۰.

Table

1.

いいい ちちちち ちちんち ちちんていち

2

- 1 Strain Gage Calibration Data 2 Calibration of Fatigue Machine No 1 Pure Tension 3 Calibration of Fatigue Machine No 2 Pure Tension 4 Calibration of Fatigue Machine No 1 Pure Bending 5 Calibration of Fatigue Machine No 2 Pure Bending 6 Calibration of Fatigue Machine No 1 Varying Bending at Constant Tension of 390 1b 7 Calibration of Fatigue Machine No 1 Varying Tension at Constant Bending of 45.5 in-1b 8 Calibration of Fatigue Machine No 2 Varying Bending at Constant Tension of 380 1b 9 Calibration of Fatigue Machine No 2 Varying Tension at Constant Bending of 56 in-1b
- 10 Correction Factors

iv

A REPORT ON THE CONSTRUCTION AND CALIBRATION OF TWO FATIGUE TESTING MACHINES

INTRODUCTION

Synopsis.--Two testing machines of the rotating-beam type, described in this report, are in operation to study the effect of range of stress and prestrain on the fatigue strength of titanium and titanium alloys. The machines were made at Carnegie Institute of Technology in all essentials like an earlier machine designed and built as part of a doctoral program of research in civil engineering at Carnegie by Chao-Lin Chang in 1950-51.* The testing machines are described in detail in this report.

The main features of the machines are that specimens 1/4 in. in diameter can be subjected to a full range of loading from pure tension to pure bending in any combination, and that changes in loading can be made while the test is in progress. The machines have been calibrated for both static and dynamic operation and proved adequate throughout their operative range.

The machines are fully described, and calibration data are summarized in tables and graphs. Working formulas and a nomographic chart bring the analysis of combined stresses into convenient form for use in the laboratory.

This project is under the technical supervision of the Applied Mechanics Branch of the Watertown Arsenal Laboratories.

- A 225

^{*}Chang, Chao-Lin, "Effects of range of stress and low temperature on fatigue of metals-Background and apparatus". Thesis submitted to the department of civil engineering in partial fulfillment of the requirements of the degree Doctor of Science, Carnegie Institute of Technology, June 1952.

<u>Acknowledgements</u>.--Dr. Elio D'Appolonia, assistant professor of civil engineering, is project supervisor. Assisting him in detail work are James P. Romauldi and Richard J. Magner, civil engineering students, and Joseph J. Wolfe and Claude Argall, mechanicians in the department.

Dr. Charles F. Peck, Jr., assistant professor of civil engineering, and Dr. Frederic T. Mavis, head of the civil engineering department advised on the design and construction of the testing equipment and on matters related to the research as a whole.

DESCRIPTION OF MACHINE

Stresses are induced in the specimen by loads that produce tension and bending. Alternating stresses, varying from complete reversal to pure tension, can be developed by varying the magnitudes of the axial and bending stresses.

The testing machine is shown in Fig. 1. The shaft, or rotating beam, consists of the specimen; two chucks, C_1 and C_2 ; and the two shafts, S_1 and S_2 .

The shaft is supported by the two bearing housings, H_1 and H_2 , and driven by the motor D, through a flexible coupling. The housings, pivoted at P_1 and P_2 , are free to rotate about axes perpendicular to the plane of loading. They are supported by two vertical tension arms, T_1 and T_2 , attached to the main chassis by pivots P_3 and P_L .

Bending stresses are produced in the specimen by the weight W_1 that is connected to the arms M_1 and M_2 by the nylon string A_1 . The vertical arms are securely fastened to the bearing housings. Since the housings are free

to rotate about the horizontal pivots, P_1 and P_2 , the bending moment due to the weight W_1 is resisted solely by the specimen. The length of the moment arm is 12 inches and the bending moment produced in the specimen due to the weight W_1 is 24 W_1 (in-1b). Tests carried out on the machine show that the effect of the flexible coupling in offering resistance to this moment is negligible.

When the specimen breaks the arms M_1 and H_2 are drawn together bringing the adjustable arm G into contact with the micro-switch F to shut off the motor. The arm G also prevents the specimen from striking the chassis after fracture.

Tension is applied to the specimen by the weight W_2 . Because the bar T_2 is free to rotate about the pivot P_4 , the pull in the cable A_2 is resisted by the tension in the specimen. This tension is transmitted to the arms through thrust bearings in the housings. The bar T_1 is held fixed to the chassis by the turn-buckle B.

The pivot P_{i_1} can be moved longitudinally along the chassis so that specimens of various lengths can be tested. After a specimen has been mounted further movement of this pivot is prevented by the stop nut E that is drawn up tight against the chassis. The stop rod R checks the swing of bar T_2 after the specimen breaks, but it offers no resistance to movement of bar T_2 while the specimen is still intact.

The cable A_2 and the pulleys P_5 and P_6 form a system with a mechanical advantage of two, hence the force tending to draw the bottom of the arms T_1 and T_2 together is $2W_2$. The pivots, P_3 and P_4 , divide the vertical tension

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arms into a ratio of 8:1 and, therefore, the tensile force in the specimen, due to the weight W_{2} , is $16W_{2}$ (1b).

The motor is 1/2-hp, single phase, 155-v, a-c, 1800 rpm. It is connected in series with the micro-switch and an electric clock that runs and stops with the motor. The total number of revolutions that the specimen has undergone can be computed by multiplying the difference in time, in minutes, from the start of the experiment to fracture. by 1800 rpm.

DETAILS OF CONSTRUCTION AND DESIGN

The design of the chucks that are used to attach the specimen to the shaft was based on the following considerations;

- (1) Specimens should be installed and removed readily.
- (2) Specimens must be in proper alignment during a test.
- (3) Threads should not be depended upon for longitudinal alignment.

The connection of specimen, chuck, and shaft is illustrated in Fig. 2. The chuck has a straight collar which is machined to fit the shaft beyond the threaded section. Thus when the shaft is pulled the alignment is not dependent on the threads but on the sliding collar. The specimen is tapered at both ends and is aligned in the chuck by an inside tapered split nut. The specimen is kept in place by the tensile pull through the assembly and the 60° center-point on the shaft which bears on the specimen as shown.

Thrust is transmitted from the bearing housing to the shaft by a radialthrust bearing in the housing. This arrangement is shown in Fig. 3. Moment is transmitted to the shaft by the radial reactions of the thrust bearing and

a radial bearing. The reaction of these two bearings on the housing form a couple with a moment equal .0 the external moment exerted by the weight W_1 and the arms M_1 and M_2 .

To avoid operating the machine through resonance the natural frequency of the combined shaft and housings was made to be greater than the speed of operation by reducing the span length between the pivot-points P_1 and P_2 and by making the vertical arms and housings of aluminum. Cold-rolled steel was used at all rotating or pivoting joints. The pulleys and housings are designed to permit lateral adjustment. By means of the stop mut E the distance between the chucks can be adjusted to take specimens from one and one-half inches to seven inches in length.

CALIBRATION OF FATIGUE MACHINES

The two machines were calibrated to determine whether appreciable dead load stresses were induced in the specimen when mounted and whether the dynamic effect of rotation produced significant variation in the stresses of the loaded specimen.

Fig. 4 shows the calibration specimen static and dynamic which was subjected to both tests. A square specimen was used because of difficulty in mounting SR-4 strain gages on a round specimen of small radius and because the curving of the strain gages would lead to erroneous readings. Two electric strain gages (SR-4, type A-7) were attached to two opposite faces of the specimen. Strain in the specimen was determined by means of strain measuring apparatus.

The strain gages were first calibrated on the specimen which was subjected to loads in a standard testing machine. Tensile loads were applied to the specimen and chucks that were held by a ball and socket arrangement to insure axial loading. Results of this test are shown in Table 1 and the stress strain curve for the assembly is shown in Fig. 5. An apparent modulus for the steel specimen assembly of 32.14×10^6 psi was obtained. This modulus was used during the calibration tests to convert strain to stress for different applied loads on the machine.

The static tests were made with the specimen in pure bending, pure tension, and combined bending and tension.

The pure tension tests were conducted by applying loads W_2 , (Fig. 1) in increments to a total load of 45.5 pounds (including weight of hanger). The results of these tests are shown in Tables 2 and 3 wherein the average strain for the two strain gages was converted to applied load by use of the apparent modulus. The tensile pull in the specimen is plotted as ordinate and the corresponding weight W_2 as abscissa in Figs. 6 and 7 for machines 1 and 2 respectively. Both calculated and observed functions are plotted.

The pure bending tests were conducted by applying loads W_{l} , (Fig. 1) until a total load of three pounds was reached. This corresponds theoretically to a moment in the specimen of 72 in-lb. Results of these tests are shown in Tables 4 and 5 wherein the average strain is converted to the applied bending moment by use of the apparent modulus. Figs. 8 and 9 show bending moment as ordinate and corresponding weight W_{l} as abscissa for machines 1 and 2 respectively. Both calculated and observed functions are plotted.

Under combined bending and tension there is a counter-action between the tensile and bending loads. In Appendix A there is developed a method whereby a correction is made for this counter-action.

Tests of combined bending and tension were conducted at a constant mean stress level and at varying mean stress levels. That is, for the first series of tests the tensile load was held constant and the bending load was varied. For the second series of tests a constant bending load was applied and the tensile load was varied. The results of these tests are shown in Tables 6, 7, 8, and 9. In each test one gage was on the compression side and one on the tension side of the specimen. The gages were then reversed and the test was repeated for the same loading. Thus there were two readings each for the maximum and minimum strains. These strains were averaged and the maximum and minimum strains. These strains were averaged and the maximum and minimum strains. These strains were averaged and the values as computed by the method developed in Appendix A. Good agreement is noted between these values.

Tests were conducted to determine whother there was any dynamic effect on the stress due to the rotation of the specimen and the vibration of the machine. For this purpose a plot of the strain in the specimen was obtained on an oscillograph. Strains were not measured quantitatively from the plotted curves since the machine had already been calibrated statically. Hence it was only necessary to compare the peak readings on the curve, or the maximum strain, when the machine was turned slowly by hand and when it was rotated by the motor.

The strain gages and the oscillograph were connected by mounting sliprings on the chucks. These were insulated from the chucks by a layer of rubber tape. The leads from the strain gages were connected to the sliprings and in turn contact with the leads from the oscillograph was made through brass brushes with carbon tips.

Different combinations of bending and tensile loads were tested. From Figs. 10 and 11, which show the charts from the oscillograph, it is evident that the maximum strain in the specimen is the same when the shaft is turned by hand or by motor.

OPERATION CURVES

It is often desirable to conduct a series of tests for a S-N diagram at certain fixed values of r (ratio of minimum to maximum stress) when the specimens are being tested under combined bending and tension. Also, most established criteria for the construction of a range of stress diagram require values of the endurance limit at r = -1 and r = 0.

The formula developed in Appendix A for the corrected moment in combined bending and tension is:*

$$M' = \frac{M_0}{1 + T_0/2300}$$
(1)

The maximum and minimum stresses are given by:

$$S = \frac{T_0 + \frac{8N!}{d}}{A}$$
(2)

*Refer to Appendix B for meaning of symbols.

and for a 0.25 inch diameter specimen

$$s = 20.4 T_0 + \frac{653 M_0}{1 + T_0/2300}$$
(3)

Thus for any combination of M_0 and T_0 the maximum and minimum stresses can be calculated directly.

In order to conduct a test at a fixed value of r, the values of M_o and T_o in equation (3) would have to be adjusted prior to the testing of each specimen. The use of equation (3) for this would be laborious and time-consuming. To overcome this difficulty the chart Fig. 12 and the nomograph Fig. 13 have been prepared. Thus for values of r and S_{max} the resulting values of M_o and T_o can be readily determined.

CORRECTION FACTORS

The numerical constants in equation (3) are developed on the basis that the diameter of the specimen is 0.250 inches. Table 10 shows correction factors which take into account small variations in the diameter of specimens as machined. The factors are applied to the values of M_0 and T_0 that are to be substituted in equation (3).

DIAMETER	lameter T _o			
0.248	0.985	0.976		
0,249	0.992	0.985		
0,250	1,000	1.000		
0,251	1.008	1.013		
0.252	1.014	1.023		

TABLE 10 CORRECTION FACTORS

Machining specifications allow a tolerance of \pm 0.001 inches; hence, with the use of the correction factors, no appreciable error in the computed stress is introduced by small changes in the diameter of the specimen.

SUMMARY AND CONCLUSIONS

Fatigue machines for the study of the effect of range of stress and prestrain on titanium and titanium alloys were constructed. The machines are identical in design with a machine previously designed and constructed by the Department of Civil Engineering of Carnegie Institute of Technology. The machines are of the rotating-beam type and are easily assembled and maintained. Dynamic calibration tests showed that the limits of stress in the specimen rotated by the motor at 1800 rpm are the same as the limits of stress when the specimen is rotated slowly by hand. The static calibration tests showed

- That the calculated and observed stresses in pure bending and pure tension agree closely when the apparent modulus, as obtained from the strain gage calibration, is used.
- (2) That the calculated and observed stresses in combined bending and tension agree when formula (3) is used to correct for the counteracting moment produced by the tensile load.

Operation curves involving μ_0 , T_0 , r, and S_{max} were developed to facilitate testing procedure. Correction factors were determined to take into account slight changes in the diameter of the specimen.

The machines fulfill the desired functions and specifications called for in their design and are satisfactory for an investigation on the effect of range of stress and prestrain on the fatigue properties of a metal.

APPENDIX A

Under loads of combined bending and tension, the maximum stress is

$$s = \frac{T_o + 8 M^{1/d}}{A}$$
(4)

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The part of the stress due to bending depends both on the moment ${\rm M}_{\rm O}$ and the moment due to $T_{\rm O},$ that is

$$M^{*} = M_{0} - T_{0} \Delta_{0}$$
 (5)

For the shaft assembly shown schematically in Fig. 14(A) the center deflection with an error of less than 1% is given by

$$\Delta_{0} = \frac{M_{0}}{C + T_{0}}$$
(6)

where

$$C = \frac{B E L_o}{L_o (2L - L_o)}$$

Substituting (6) into (5) the expression for the maximum bending moment becomes

$$M^{2} = \frac{M_{o}}{1 + T_{o/C}}$$
(7)

Using the numerical values of length and moment of inertia shown in Fig. $l_4(A)$ the equation for the maximum stress in the steel specimens that were used for the calibration is

$$S = 20.4 T_{.0} + \frac{653 M_0}{1 + T_0/2300}$$

APPENDIX B

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NOTATION

The following symbols are arranged in the order in which they first appear in the report:

S-N Diagram	Diagram showing nominal stress at failure as ordinates and
	corresponding number of cycles as abscissas.
r	Ratio of minimum stress to maximum stress.
Mi	Corrected bending moment in a specimen under combined
	bending and tension.
Mo	Bending moment due to the applied load W_1 (Fig. 1).
м _т	Bending moment due to applied load W_2 (Fig. 1).
To	Total tensile stress due to the applied load W_2 (Fig. 1).
S	Unit stress.
Smax	Maximum unit stress.
S _{min}	Minimum unit stress.
I	Moment of inertia of cross-section about centroidal axis.
c	Distance from the neutral axis to the outermost fiber.
d	Diameter of the specimen.
٨	Cross-sectional area of the specimen.
Δ	Deflection.

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FIG. 5. STRESS-STRAIN CURVE FOR SPECIMEN ASSEMBLY





FIG 8 RESULTS OF STATIC CALIBRATION TEST IN PURE BENDING (MACHINE NO I)



	S _{MIN} =	
(A) NO LOAD ON MACHINE	(B) S _{MAX} =32,100 PSI	

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(C) S_{MAX} = ± 29,000 PSI

FIG. 10. CURVES FROM THE OSCILLOGRAPH SHOWING THE STRAINS IN THE SPECIMEN UNDER REPEATED LOADING IN MACHINE NO I

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Machine Load (1b)	Stress (psi)	Gage I* (micro-in)	Gage II* (micro-in)(Average Strain (micro-in/in)	Measured Load (1b)
0	0	0	0	0	0
200	4175	152	109	130.5	187.4
400	8350	274	251	262.5	377.0
600	12520	428	359	393.5	565.0
800	16700	561	491	526.0°	755.3
1000	20870	649	665	657.0	943.5

TABLE 1 STRAIN GAGE CALIBRATION DATA

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TABLE 2 CALIERATION OF FATIGUE MACHINE NO 1 IN PURE TENSION

Machine Load	Stress	Gage I**	Gage II**	Average Strain	Observed Tensile	Calculated Tensile
(16)	(psi)	(micro-in)	(micro-in)	(micro-in/in)	(16)	(1b)
0	0	0	0	0	0	0
10,5	3510	121.0	82.0	101.5	155.8	168.0
20.5	6850	228.5	182.5	205.5	315.5	328.0
30.5	10200	332.7	274.5	303.6	466.0	488.0
40.5	13525	453.3	361.0	407.1	625.0	648.0
45.5	15200	504.0	411.0	457.5	702.3	728.0

*Average of four tests **Average of three tests

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Machine Load	Stress	Gage I*	Gage II*	Average Strain	Observed Tensile	Calculated Tensile
(1b)	(psi)	(micro-in)	(micro-in)	(micro-in/in)	(1b)	(1b)
0	0	0	0	0	0	0
10.5	3510	105.3	101.0	103.2	158.4.	168.0
20.5	6850	200.0	197.3	198.6	304.8	328.0
30.5	10200	291.0	303.0	297.0	455.9	488.0
40.5	13525	379.3	402.0	390.6	599.6	648.0
45.5	15200	430.0	458.3	444.2	681.8	728.0

TABLE 3 CALIBRATION OF FATIGUE MACHINE NO 2 IN PURE TENSION

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TABLE 4 CALIBRATION OF FATIGUE MACHINE NO 1 IN PURE BENDING

Machine Load	Average Strain in	Average Strain in	Average Strain	Observed Moment	Calculated Moment
(1b)	Compression (micro-in)	Tension (micro-in)	(micro-in/in)	(in-lb)	(in-lb)
0	0	0	0	0	0
1.0	383.0	378.0	380.5	21.4	24.0
1.5	589.5	582.0	586.0	32.8	36.0
2,0	811.5	803.0	807.0	45.3	48.0
2.5	1041.5	1034.5	1038.0	58.1	60.0
3.0	1284.5	1278.0	1281.0	72.0	72.0

*Average of three tests

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Machine Load	Average Strain in	Average Strain in	Average Strain	Observed Moment	Calculated Moment
(1b)	(micro-in)	(micro-in)	(micro-in/in)	(in-lb)	(in-lb)
0	0	0	0	0	0
1.0	-365.0	372.0	368.5	20.3	24.0
1.5	-551.0	581.0	566.0	31.8	36.0
2.0	-807.0	810.0	808.5	45.3	48.0
2.5	-996.0	1003.0	999.5	56.0	60.0
3.0	-1220.0	1222.0	1221.0	68.5	72.0

TABLE 5 CALIBRATION OF FATIGUE MACHINE NO 2 IN PURE BENDING

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TABLE 6 CALIBRATION OF FATIGUE MACHINE NO 1 VARYING BENDING AT CONSTANT TENSION OF 390 LB

	Maximum Strain (micro-in/in)			Mini (mic	Minimum Strain		Observed Stress (psi)		Calculated Stress (psi)	
Мо	Ave	Diff	Sum	Ave	Diff	Sum	Max	Min	Max	Min
0	4810	E 00		4760	45		0	0	0	0
21.7	5390	260	580	4695	-05	-65	18420	-2060	16720	-2417
33.5	5565	160	755	4520	-1/2	-240	24000	-7600	24470	-8166
45.5	5725	170	915	4360	-100	-400	29060	-12700	30310	-14010
58.0	5895	170	1085	4190	-170	-570	34460	18100	36400	-20100
71.0	6070	1/2	1260	4060	-130	-700	40000	-22200	42730	-26430

To	Maxim	um Strain	Minimum Strain		Observe	ed Stress	Calculated		
(1b)	(micr	o-in/in)	(mic	ro_in/	'in)		(psi)	(psi)	
	Ave D	iff Sum	Ave	Diff	Sum	Max	Min	Max	Min
¢	4815		4755	90r		0	0	0	0
160	5735	910 910	4050	-90	-705	28900	~22400	27610	-20900
238	5750	935	4140	-,0	-90	29690	-19500	28480	-18500
315	5765	950	4225	-00	~85	30170	-16800	29378	-16200
390	5785	20 970	4305	-00	-80	30800	-14300	30312	-14010
466	5810	995	4400	-72	-95	31600	-11300	31280	-11800
545	5835	1020	4470	-70	-70	32400	-9050	32166	-9380

TABLE 7 CALIBRATION OF FATIGUE MACHINE NO 1 VARYING TENSION AT CONSTANT BENDING OF 45.5 IN-LB

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TABLE 8 CALLERATION OF FATIGUE MACHINE NO 2 VARYING BENDING AT CONSTANT TENSION OF 380 LB

к _о	Maximum Strain		Minimum Strain (micro-in/in)			Observed Stress (psi)		Calculated Stress (psi)	
• · · · · · · · · · · ·	(micro-i								
	Ave Diff	Sum	¥v0	Ditt	Sum	Max	Min	Max	Min
0	3746		3660	124		0	0	0	0
10	4143	397	3784	240	124	12720	3980	12832	3052
21	4289 166	543	3635	-149	-25	17400	-800	18209	-235
31	4455	709	3472	100	-188	22750	-6040	23098	-7214
43	4630	884	3300	-172	-360	28400	-11550	28965	-13081
56	4783	1037	3148		-512	33200	-16400	35320	-19437
68	4960	1214	2967	-181	-693	39000	-22200	41180	-25300
0	3745	-1	3663	V 70	3	0	0	0	0

To	Max	Maximum Strain		Minim	Minimum Strain			Observed Stress		Calculated Stress	
	(mic	(micro-in/in)			(micro-in/in)			(psi)		(psi)	
	Ave	Diff	Sum	Ave	Diff	Sum	Max	Min	Max	Min	
0	3755	1038	-	3675	-820	-	0	0	°0	0	
152	4793	12	1038	2855	80	-880	33200	-26300	33140	-26789	
228	4805	23	1050	2935	75	-740	33700	-23750	33816	-24286	
305	4828	20	1073	3010	80	-665	34400	-21350	34554	-21800	
380	4848	12	1093	3090	90	-585	35100	-18750	35321	-19438	
455	4860	15	1105	3180	70	-495	35400	-15900	36131	-17113	
535	4875	21	1120	3250	80	-425	35900	-13600	37040	14678	
610	4896	29	1141	3330	70	-345	36600	-11800	37532	-12434	
685	4925	-1170	1170	3400	280	-275	37500	- 8830	38856	-10224	
0	3755		0	3680	200	5	0	0	0	0	

TABLE 9 CALIERATION OF FATIGUE MACHINE NO 2 VARYING TENSION AT CONSTANT BENDING OF 56 IN-I.B

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