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FLOATING POINT MULTIPLY-ADD-SUBTRACT

IMPLEMENTATION

STATEMENT OF GOVERNMENT INTEREST

[0001] The invention described herein may be manufactured and used by or for the Government of the United States of America for governmental purposes without the payment of any royalties thereon or therefor.

CROSS REFERENCE TO OTHER PATENT APPLICATIONS

[0002] None.

BACKGROUND OF THE INVENTION

(1) Field of the Invention

[0003] The present invention is directed to an implementation of a floating point multiply-add-subtract implementation for digital circuitry.

(2) Description of the Prior Art

[0004] In digital computer processing, signed floating point numbers can be utilized in a form having a mantissa multiplied by a base having an exponent. Mathematical functions are carried out on these numbers in semiconductor floating point units or processors in binary format. The floating point unit does addition, subtraction, multiplication, and division operations on floating point numbers. In many implementations the exponent is usually biased which means that a number called

the bias is subtracted from the written exponent before computation. This allows implementations to use a positive representation of a negative exponent, since the written exponent minus the bias is negative. The examples assume a normalized format, which means that the first bit of the mantissa is '1'.

[0005] The Institute of Electrical and Electronics Engineers (IEEE) has standards for floating point representation of numbers. The current standard used by most commercial processors is IEEE-754-2008. The output of this format is a binary floating point number that contains a sign, biased exponent, and mantissa. A 16-bit IEEE-754 floating point number is given by the following format:

seee eemm mmmm mmmm

where each letter represents a binary digit or bit; s is the sign bit; each e is an exponent bit; and each m is a mantissa bit. In this format the minimum exponent is -14, and the maximum exponent is 15. The exponent bias is 15. This means that 15 is subtracted from the exponent value to give the actual value. An exponent value having all 1s is used to represent infinity or "not a number" known as NaN. An exponent value having all zeroes is used to represent a denormalized number. IEEE-754 32 bit, 64 bit, and 128 bit floating point formats are similar.

[0006] Important resources for floating point unit implementation are its size and its speed. The size of the implementation is the number of gates that are required. Typical commercial 32 bit multiply/accumulate floating point units without division take approximately 12,800 gates. This commercial implementation runs at 1MFlop/Mhz or 55Mhz.

[0007] When utilizing field programmable gate arrays and other special purpose semiconductors, it is often desirable to reduce the number of gates and chip resources required for processing floating point numbers. It is further desirable to process these numbers as quickly as possible.

SUMMARY OF THE INVENTION

[0008] The first object of the present invention is to provide an implementation of a floating point unit utilizing fewer gates.

[0009] Another object is to provide an implementation of a floating point unit capable of operating at faster speeds than existing units.

[0010] Accordingly, there is provided a floating point multiply and addition/subtraction implementation. Two operands are received in a standard floating point format with a code

selecting a mathematic operation from addition, subtraction, and multiplication. Result mantissas and exponents are calculated simultaneously for all operations. The implementation simplifies computation of a result mantissa by dropping the least significant bits of the operands before computing the result. Underflow and overflow errors are shown by two extra bits in the exponent portion of the result. The mantissa result and the exponent result are selected by providing the operation code to a mantissa multiplexer and an exponent multiplexer. The selected mantissa and exponent are combined as output.

BRIEF DESCRIPTION OF THE DRAWINGS

[0011] Reference is made to the accompanying drawings in which are shown an illustrative embodiment of the invention, wherein corresponding reference characters indicate corresponding parts, and wherein:

[0012] FIG. 1 is a diagram of an overview of the implementation;

[0013] FIG. 2 is a detailed diagram of the add/subtract section of the implementation; and

[0014] FIG. 3 is a detailed diagram of the multiply section of the implementation.

DETAILED DESCRIPTION OF THE INVENTION

The benefits of the floating point unit implementation [0015] contained herein are accomplished via pipelining, simplification of exception handling and other hardware techniques. The current implementation calculates NaN, underflow, and overflow exception conditions by calculating the exponent with two additional bits of precision and using signed two's complement binary format. This eliminates complex error/exception detection circuitry because in this format, either of the two most significant bits of the exponent will only be 1 when an exception occurs. Underflow occurs when the most significant bit is 1 because the exponent is negative. Overflow occurs when the two most significant bits are 01 because the exponent portion has exceeded its range. NaN is indicated when the exponent bits following the two most significant bits are all 1's, and the mantissa is non-zero. In the current implementation, post calculation detection of this condition is unnecessary.

[0016] The floating point unit implementation receives two floating point numbers A_{in} and B_{in} . The floating point number is separated into component parts for processing. For this purpose, in FIG. 2 the mantissa of A_{in} is identified as A_{man} , and the mantissa of B_{in} is identified as B_{man} . The exponent of A_{in} is identified as A_{exp} , and the exponent of B_{in} is identified as B_{exp} .

The sign of each number is identified as A_{sgn} and $B_{\text{sgn}}.$ This can be performed by segregating the appropriate bits.

[0017] FIG. 1 gives an overview of the floating point unit implementation 10. The floating point unit implementation 10 receives A_{in} and B_{in} in a floating point format that can be broken up into signs, mantissas, and exponents. These numbers are provided to an initial error detection module 11, an add/subtract section 12 and a multiply section 14. The user also provides an opcode that selects the operation multiplication, addition, or subtraction - of the floating point unit implementation 10.

[0018] Prior to computation, error detection module 11 checks for NaNs at the inputs by checking if the exponent of either operand, A_{in} or B_{in} , is all 1s, and its mantissa is non-zero. (This can be performed by conducting an AND operation among all of the exponent bits of the operand, conducting an OR operation among all of the mantissa bits of the operand, and executing an AND between the two results.) Error detection module 11 then asserts signal A_{NaN} if A_{in} is NaN, B_{NaN} if B_{in} is NaN, and a signal NaN if either A_{in} , B_{in} , or both is NaN. Next error detection module 11 checks for zeroes at the inputs, and then asserts A_{zero} if both A_{exp} is negated and A_{man} is zero. Error detection module 11 then checks for infinities at the inputs and asserts

 A_{inf} if A_{exp} is all asserted while A_{man} is all negated. B_{inf} is asserted if B_{exp} is all asserted, and B_{man} is all negated. Next, error detection module 11 checks for signaling NaNs at the inputs, and A_{sNaN} is asserted when both A_{NaN} is asserted and the most significant bit of A_{man} is negated. Similarly, B_{sNaN} is asserted when B_{NaN} is asserted and the most significant bit of B_{man} is negated.

Next, error detection module 11 checks if invalid [0019] operation exceptions/signaling NaNs exist at the inputs based upon the opcode. If the opcode indicates addition an invalid operations flag, InvOp, is asserted when $A_{\scriptscriptstyle SNaN}$ is asserted, or B_{sNaN} is asserted, or both A_{inf} and B_{inf} are asserted and A_{sqn} and B_{sqn} differ. If the opcode indicates subtraction then InvOp is asserted when A_{sNaN} is asserted, or B_{sNaN} is asserted, or both A_{inf} and B_{inf} are asserted and A_{sgn} and B_{sgn} match. If the opcode indicates multiplication then InvOp is asserted when A_{sNAN} is asserted, or B_{sNaN} is asserted, or both A_{inf} and B_{zero} are asserted and NaN is negated, or both A_{zero} and B_{inf} are asserted and NaN is negated. Next error correction module 11 modifies the diagnostic mantissa output, Y_{NaN} , to indicate invalid operations and NaN error conditions. Y_{NaN} is set to A_{man} if A is a NaN, that is if either A_{NaN} or A_{sNaN} is asserted. Y_{NaN} is set to B_{man} if B is a NaN. If both A and B are NaNs, Y_{NaN} is set to A_{man} . The first

bit of Y_{NaN} can be use to indicate a signaling NaN versus a quiet NaN under the IEEE standard.

Further details of the add/subtract section 12 will be [0020] given in reference to FIG. 2, and further details of the multiply section 14 will be given in reference to FIG. 3. The mantissa outputs of the add/subtract section 12, Ymadd and Ymmin, and the multiply section 14, Y_{mmult} , are provided to a mantissa multiplexer 16. The opcode is further provided to the mantissa multiplexer 16 to select the correct mantissa function input as the mantissa output, Y_{man} . The exponent outputs of the add/subtract section 12, Y_{pexp} , and the multiply section 14, Y_{mexp} , are provided to an exponent multiplexer 18. The opcode is further provided to the exponent multiplexer 18 to select the correct exponent function input as the exponent result output, Y_{exp} . An error check module 20 receives the exponent result output Yexp, and Yman, the input operands Ain and Bin and NaN output from error detection module 11. Error check module 20 both computes the diagnostic error output and corrects the exponent and mantissa result outputs for the output format as described hereinafter. The mantissa output Y_{man} and the exponent output Y_{exp} are combined in at an output 22 to give the preferred output form. The diagnostic error output of error check module 20 can be a bus which contains the InvOp, overflow, underflow, and inexact error flag signals from error detection module 11 and

error check module 20. A divide by zero flag can be included for compatibility, but this flag will never be asserted. In an alternative embodiment, error check module 20 can give a diagnostic code that can be used to give these flags.

[0021] FIG. 2 provides a detailed view of add/subtract section 12. Add/subtract section 12 includes an exponent comparator 24 and an exponent subtractor 26. Exponent comparator 24 receives the exponent component of the inputs, A_{exp} and B_{exp}, and provides the larger of the two exponents as the preliminary add/subtract result exponent, Y_{pexp}. Exponent subtractor 26 receives the exponent inputs, A_{exp} and B_{exp}, and provides the difference between them, C_{dexp}, for use in scaling the values. Register 28 receives exponent difference, C_{dexp}, and the mantissa inputs, A_{man} and B_{man}, and scales these inputs relative to one another. An adder/subtractor 30 receives the scaled mantissa inputs Y_{mmin} for these inputs.

[0022] FIG. 3 provides a detailed view of multiply section 14. A mantissa multiplier 32 receives mantissa inputs A_{man} and B_{man} and provides a multiplied mantissa output M_{out} . The multiplied mantissa output, M_{out} , is provided to a priority encoder 34 which determines the maximum place value of the mantissa output M_{out} . This maximum place value is provided to shift logic 36 which provides a number of shifts N_{shifts} , for the

mantissa to fit into the places allocated for the format. A mantissa shift register 38 receives the mantissa output, M_{out} , and the number of shifts, N_{shifts} . Shift register 38 shifts the mantissa output by dropping the least significant bits of the mantissa output until the mantissa is the same length in bits as the mantissa portion of the format. Shift register 38 provides an unsigned multiplication result Y_{imult} . Shift register 38 also provides an exponent correction that will be used as described below.

[0023] In order to calculate the sign of the output, an XOR gate receives the sign bits of the inputs, A_{sgn} and B_{sgn} , and provides the sign of the result Y_{sgn} as the exclusive or of the sign inputs. The sign of the result Y_{sgn} is combined in a combiner 42 with the unsigned mantissa multiplication result Y_{imult} to give Y_{mmult} .

[0024] A preliminary multiplication exponent result, Y_{pmexp} , is calculated from the input exponents, A_{exp} and B_{exp} , in a multiplication exponent adder 44. Exponent calculation logic 46 receives the preliminary multiplication exponent result, Y_{pmexp} , and combines this with the exponent correction from the mantissa shift register 38 to give a multiplication exponent result, Y_{mexp} .

[0025] Overall operation of the floating point unit implementation is described in the following text.

[0026] Mantissa multiplier 32 calculates the mantissa of $A_{man}*B_{man}$ and provides the product, M_{out} , with sufficient precision to store the entire result. This could be the place number precision of A_{man} added to the place number precision of B_{man} , or double the precision of A_{man} or B_{man} if both have the same precision. Of course a lower precision result may be acceptable for some applications. This product, M_{out} , will be shifted in operations in a later stage to drop the least significant digits.

[0027] A preliminary result exponent, Y_{pmexp} , is determined by adding A_{exp} to B_{exp} in multiplication exponent adder 44. Multiplication exponent adder 44 utilizes two extra bits in the most significant places in these exponent calculations. For example, in IEEE 764 16 bit, the exponents and results would each be five bit values; however, in this implementation, the result is a seven bit value. These extra, most significant bits will only be asserted in cases of underflow and overflow. This will be explained below.

[0028] The sign of the final output is determined by executing an "exclusive or" or XOR operation on A_{sgn} and B_{sgn} to give Y_{sgn} . This allows use of a simple XOR 40 gate to give the sign for multiplication.

[0029] The priority encoder 34 is used to get the order of the multiplication result M_{out} from the mantissa multiplier 32.

The order is the position of the most significant bit of $M_{\rm out}$. (For example, if 0100 (4) * 0011 (3) = 1100 (12) the binary order would be 4 because the most significant digit 1xxx is in the fourth position.) This is used to determine the number of right shifts of M_{out} that will be required for the product to fit in the floating point format. (In 16 bit implementations, 10 bits are allowed. In 8 bit implementations, 4 bits are allowed.) In a preferred embodiment the priority encoder 34 with shift logic 36 determines the order of the bits beyond the number of bits allowed. This can be used directly as the number of shifts, N_{shifts}. In an alternate embodiment the order is the absolute order of the product, and this order is converted into a number of shifts, N_{shifts}. There are no shifts if the order is less than number of bits allowed. If the order is greater than the number of bits allowed, the number of shifts is an adjustment calculated as the order minus the number of bits allowed.

[0030] The product of A_{man} and B_{man} , M_{out} , is shifted by N_{shifts} in mantissa shift register 38 so that it fits into the number of bits allowed by dropping the least significant digits. This gives Y_{mmult} , the mantissa of the multiplication result. The multiplication exponent Y_{mexp} is calculated in an exponent calculation component 46 by adding the preliminary result

exponent Y_{pmexp} to the number of shifts required for the mantissa $N_{\text{shifts}}.$

[0031] The addition/subtraction process is more fully described below. A_{exp} and B_{exp} are compared using exponent comparator 24 to give the greater of the two exponents as a preliminary addition/subtraction result exponent, Y_{pexp}. The difference between A_{exp} and B_{exp} is calculated by exponent subtractor 26, by for example, subtracting B_{exp} from A_{exp} as C_{dexp} using two's complement addition. Two's complement addition uses less complicated logic to manage the signs and give a difference. A_{man} and B_{man} are scaled in register 28 by shifting the mantissa of the operand having the lower exponent. This shift uses the exponent difference C_{dexp} to shift the mantissa's bits to less significant places. The operand being shifted is governed by the sign of the difference, C_{dexp} . (One of ordinary skill in the art would understand this as "right shifting" the mantissa.) For example if C_{dexp} is positive this means that A_{exp} is greater than B_{exp} and B_{man} is shifted by C_{dexp} positions. If C_{dexp} is negative B_{exp} is less than A_{exp} , and A_{man} is shifted by C_{dexp} positions. This shift truncates the least significant digits of the smaller operand if one operand is significantly smaller than the other. The register 28 also aligns the mantissas prior to addition so that when the operand and the shifted operand are added the bits will be in the appropriate place value.

[00321 The register 28 adds an extra bit of precision to A_{man} and B_{man} which have been shifted as described above. A combined adder/subtractor receives the shifted mantissa A_{man} and B_{man} having the extra exponent bit. The adder/subtractor converts these numbers to signed two's complement format by taking the complement of each number and adding one to the complement of each number if the sign bit is 1. While two's complement addition requires the extra bit of precision, it greatly simplifies addition and subtraction because the sign can be ignored. The adder/subtractor 30 calculates an addition result $A_{man}+B_{man}$ to give the mantissa of the addition result, Y_{madd} , and a subtraction result $A_{\text{man}}-B_{\text{man}}$ to give the mantissa of the subtraction result, Y_{mmin} . Y_{madd} and Y_{mmin} are then converted by adder/subtractor 30 from two's complement form to signed magnitude form of the result mantissas.

[0033] Error check module 20 checks the two most significant bits of Y_{exp} to determine if an error condition such as an underflow/overflow, inexact or NaN condition exists. If the opcode indicates addition and A_{sgn} and B_{sgn} differ or the secondmost most significant bit of Y_{exp} is asserted and the A_{inf} OR B_{inf} inputs from error detection module 11 are asserted then Y_{exp} is all asserted. Else, if the opcode indicates addition and the A_{zero} or B_{zero} inputs from error detection module 11 are asserted, or the most significant bit of Y_{exp} is asserted, then Y_{exp} changed to

all negated. If the opcode indicates subtraction and A_{sqn} and B_{sqn} match and the A_{inf} OR B_{inf} inputs from error detection module 11 are asserted, or the NaN or InvOp inputs from error detection module 11 is asserted, or the second-most most significant bit of Y_{exp} is asserted then Y_{exp} is all asserted. Else, if the opcode indicates subtraction and the Azero or Bzero inputs from error detection module 11 are asserted, or the most significant bit of Y_{exp} is asserted, or the NaN or InvOp inputs from error detection module 11 is asserted, then Y_{exp} changed to all negated. If the opcode indicates multiplication and the NaN or InvOp inputs from error detection module 11 are asserted, or the A_{inf} or B_{inf} inputs from error detection module 11 are asserted and the second most significant bit of Y_{exp} is negated, then Y_{exp} is changed to all asserted. Else, if the opcode indicates multiplication and the Azero or Bzero inputs from error detection module 11 are asserted, or the most significant bit of Y_{exp} is asserted, then Y_{exp} changed to all negated the IEEE 754 convention for indicating these conditions. If the InvOp or NaN inputs from error detection module 11 are asserted, then Y_{man} is set to the Y_{NaN} input from error detection module 11. Else, if either of the first two most significant bits of Y_{exp} are all asserted, or the remaining bits after the first two most significant bits of ${\rm Y}_{\rm exp}$ are all asserted, or all bits of Y_{exp} are negated, then Y_{man} is set to all negated, the IEEE 754 convention for indicating these

conditions. If all remaining bits after the most significant bit of Y_{exp} are asserted, and both NaN and InvOp inputs from error detection module 11 are negated then overflow is asserted. Otherwise, if all remaining bits after the most significant bit of Y_{exp} are negated, and both NaN and InvOp inputs from error detection module 11 are negated then underflow is asserted. If the A_{zero} input from error detection module 11 is asserted and A_{man} is not all negated, or the B_{zero} input from error detection module 11 is asserted and B_{man} is not all negated, then the inexact output is asserted, the IEEE 754 convention for indicating these conditions. The diagnostic error output of error check module 20 is a bus which contains the InvOp, overflow, underflow, and inexact output signals from error check module 20. Bus can include a divide by zero line for compatibility, but this line will never be asserted because this implementation lacks a divide module.

[0034] A mantissa multiplexer selects among Y_{mmin} , Y_{madd} , and Y_{mmult} based on the opcode to provide the result mantissa Y_{man} . Y_{mmin} is selected if the opcode indicates subtraction, Y_{madd} is selected if the opcode indicates addition, and Y_{mmult} is selected if the opcode indicates multiplication. In final processing, Y_{out} is composed from Y_{exp} and Y_{man} .

[0035] This apparatus can be implemented utilizing many different technologies. These technologies include field

programmable gate arrays, application specific integrated circuits, portions of integrated circuits, programmable read only memory, programmable logic arrays, hard-wired electrical circuits, or the like.

[0036] It will be understood that many additional changes in the details, materials, steps, and arrangement of parts, which have been herein described and illustrated in order to explain the nature of the invention, may be made by those skilled in the art within the principle and scope of the invention as expressed in the appended claims.

[0037] The foregoing description of the preferred embodiments of the invention has been presented for purposes of illustration and description only. It is not intended to be exhaustive, nor to limit the invention to the precise form disclosed, and obviously, many modification and variations are possible in light of the above teaching. Such modifications and variations that may be apparent to a person skilled in the art are intended to be included within the scope of this invention as defined by the accompanying claims.

FLOATING POINT MULTIPLY-ADD-SUBTRACT

IMPLEMENTATION

ABSTRACT OF THE DISCLOSURE

A floating point multiply and addition/subtraction implementation is provided. Two operands are received in a standard floating point format with a code selecting a mathematic operation from addition, subtraction, and multiplication. Result mantissas and exponents are calculated simultaneously for all operations. The implementation simplifies computation of a result mantissa by dropping the least significant bits of the operands before computing the result. Underflow and overflow errors are shown by two extra bits in the exponent portion of the result. The mantissa result and the exponent result are selected by providing the operation code to a mantissa multiplexer and an exponent multiplexer. The selected mantissa and exponent are combined as output.





FIG. 2



FIG. 3