Army Research Laboratory



Simulation Comparisons of Three Different Meander Line Dipoles

by Seth A McCormick

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Seth A McCormick Sensors and Electron Devices Directorate, ARL

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1. Introduction

Meandering is a method by which a resonant antenna can be reduced in size to fit a smaller application.¹ Because resonant antennas are directly proportional to the operating wavelength, applications that require lower frequencies but possess size limitations are challenged by the contradiction. Most common meanders use a square function as the basis for the meander line; this allows for efficient use of space as the meanders can be placed quite close to one another as long as the distance of separation between traces is not be less than the trace width (preferably slightly larger). However, continued meandering of the antenna trace introduces some detrimental effects.

The biggest negative impact is the reduced reflection coefficient that occurs when an antenna line is meandered. Each turn introduces a mutual capacitance that not only influences the resonant frequency but also the reflection coefficient, making it difficult to design an efficient meander as the antenna may not be able to be reduced by as much as desired without severe detrimental effects. Gain loss also occurs since with every additional turn opposing currents are introduced creating field cancelations.² Bandwidth reduction is another problem with meandered line antennas.

The goal of this report is to design a square meander line antenna using a circuit equivalent model and compare its function to 2 other types of meander: sinusoidal and triangular. The 2 new meanders use the square meander as a template in order to maintain construction consistency. All 3 are simulated using FEKO³ and subsequently compared to determine the individual impact on size reduction (frequency shift), realized gain, reflection coefficient, and bandwidth.

2. Design

The circuit equivalent for the meandered dipole is a modified version of the well-known dipole circuit equivalent model.⁴ Figure 1 shows the standard circuit model for the straight line dipole antenna (SLDA) that will be used for the meander line dipole antenna (MLDA).^{4,5} Figure 2 shows 1 of the 2 MLDA arms with 3 meanders. In this report, a meander is defined as an individual section made of 3 additional segments. This is important to note as the equations are dependent upon the number of meanders and a different definition can result in a different answer.

$$C_{31} = \left\{ \frac{12.0674(L-2wN)}{\log\left(\frac{2L-2wN}{a}\right) - 0.7245} \right\} pF$$
(1)

$$C_{32} = 2(L - 2wN) \left\{ \frac{0.89075}{\left(\log^{\frac{2(L - 2wN)}{a}}\right)^{0.8006} - 0.861} - 0.02541 \right\} pF$$
(2)

$$L_{31} = 0.2L \left\{ \left(1.4813 \log \left(\frac{2L}{a} \right) \right)^{1.012} - 0.6188 \right\} \mu H$$
(3)

$$C_m = \left\{ \frac{\pi \varepsilon_0 w}{\ln\left(\frac{l_s}{a} + \sqrt{\left(\frac{l_s}{a}\right)^2 - 1}\right)} \right\} F$$
(4)

$$f_0 = \left\{ \frac{1}{2\pi \sqrt{L_{31} \left(C_{31} + C_{32} + \frac{C_m}{2(2N-1)} \right)}} \right\} Hz$$
(5)



Fig. 1 SLDA circuit model



Fig. 2 Square meandered dipole arm

Equations 1–3 are the SLDA equivalent circuit equations adapted for an MLDA, where L is the total wire length, w is the meander width, N is the number of meanders, and a is the equivalent wire radius for trace width d (a = d/4).^{4,6} Equation 4 determines the mutual capacitance between the adjacent wire sections, where l_s is the spacing between the 2 parallel wires that form a meander.⁴ Equation 5 is the estimated resonant frequency for the MLDA. It should be noted that these equations are reasonably accurate for an MLDA whose number of meanders lie between 1 and 6 with an accuracy of less than 15% error, providing a good start for MLDA design.

The design constraints required that the MLDA does not occupy anymore area than what is present on the baseline model's substrate. The baseline model is an antipodal planar dipole structure with a tapered micro-strip line feed; the structure and modifications were validated in a previous report.⁷ Due to the space restrictions, the arms of the MLDA cannot exceed 152.4 mm in mechanical length, and the meander width must be less than 50 mm. Also, the spacing between the arms must not interfere with the placement of the micro-strip feed and its associated ground plane. For these reasons, the meander width was held constant at 30.42 mm with only the meander lengths being free to change. Both the triangular and sinusoidal meanders used the square meander as a template in order to maintain relative consistency with the definition of a meander.

3. Simulations

The simulations were done using computer-aided design (CAD) FEKO³ as the design and simulation tool. Figure 3 shows the baseline antipodal dipole. The MLDA simulation models are shown in Fig. 4. Each model maintains the same antipodal planar structure as the baseline model and uses a micro-strip line that has been tapered to achieve a 50- Ω impedance match; the ground plane is also reduced in width. Each model is fed with an edge feed to maintain consistency with the baseline model. It is important to note that the trace width of the triangular meander is thinner than the baseline trace width by a factor of 1.41 due to the trace being drawn along the diagonal.



Fig. 3 Baseline antipodal dipole



Fig. 4 MLDA frequency-shifted antipodal simulation models

Figures 5 and 6 show that the square meander results in the largest frequency shift at 27.5%, due to the fact that more space is being occupied on the dielectric, but has a reduced reflection coefficient (6.00 dB), severe loss of bandwidth (53.39%), and decreased realized gain (0.36 dBi). Field cancelations due to opposing current flow direction along the meander widths explain the decreased realized gain. The reductions in bandwidth and reflection coefficient are attributed to the increase in inductance due to a longer trace and the mutual capacitances between meander sections.



Fig. 5 Reflection coefficient for frequency-shifted meanders



Fig. 6 Realized gain for frequency-shifted meanders

The sinusoidal meander results in a frequency shift not as large as that achieved by the square meander (23.04%). Though the sinusoid may not have reduced the frequency by as much as the square, it does help to remove some of the field cancelations that were present in the square. The bandwidth does not decrease by as much as the square either (43.13%), most certainly due to the smaller trace inductance and mutual capacitance. There is a reduction in the reflection coefficient (2.24 dB) and a loss in realized gain (0.21 dBi)—still an improvement over the square meander. The triangular meander possesses the smallest frequency shift (19.82%), but shows the smallest reduction in realized gain (0.12 dBi) and bandwidth (40.51%), and improves the reflection coefficient (1.16 dB additional).

Taking the percentage in frequency shift and applying it to the respective meandered structures in order to reduce their sizes results in corresponding resonances that are near the baseline mode (Figs. 7, 8, and 9). From here it can be shown that the previous trends of additional loss (square and sinusoidal), reduced loss (triangular), and reduced realized gain reduction (sinusoidal and triangular) still hold true. Here bandwidth reductions seem to be more structurally dependent showing that meandering results in bandwidth loss (22.37% for square, 12.9% for sinusoidal, and 16.0% for triangular). See Table 1 for the square meander dimensions and Tables 2 and 3 for the comprehensive results.



Fig. 7 Size reduction comparisons (not to scale)



Fig. 8 Reflection coefficient for reduced-size meanders



Fig. 9 Realized gain for reduced-size meanders

Table 1	Dimensions	for the	frequency	y-shifted a	square	meander
				/		

Square Meander Dimensions						
Total Board Length	305 mm					
Total Board Width	53.5 mm					
Number of Meanders "N"	3					
Total Arm Length "L"	334.9 mm					
Mechanical Arm Length "H"	154.2 mm					
Trace Width "d"	4.0 mm					
Meander Width "w"	30.42 mm					
Meander Length "I"	25.2 mm					
Substrate Thickness	1.5748 mm					
Stripline Width [50 ohms]	3.824 mm					
Stripline Width [meander]	5.454 mm					
Ground Plane Width	10.0 mm					
Substrate Overhang	3.5 mm					

 Table 2
 Simulation results for the frequency-shifted meander results

Structure	Frequency [MHz]	Reflection Coefficient [dB]	Bandwidth [MHz]	Realized Gain [dBi]
Baseline	434	-20.39	40.76	2.03
Square	308	-14.39	19	1.67
Sinusoidal	334	-18.15	23.18	1.82
Triangular	348	-21.55	24.25	1.91

Table 3 Simulation results for the reduced-size meanders results

		Reflection			
	Frequency	Coefficient	Bandwidth	Realized Gain	Size
Structure	[MHz]	[dB]	[MHz]	[dBi]	Reduction
Baseline	434	-20.39	40.76	2.03	N/A
Square	445	-16.03	31.64	1.77	29.03%
Sinusoidal	447.5	-19.91	35.5	1.89	23.04%
Triangular	442.5	-21.08	34.22	1.94	19.82%

4. Conclusion

This report explored the impact that 3 different meander trace structures (square, sinusoidal, and triangular) can have on size reduction (frequency shift), reflection coefficient, bandwidth, and realized gain. The results show that the square meander is the preferred method for size reduction, but it can severely negatively impact the gain, reflection coefficient, bandwidth, and realized gain. The sinusoidal meander results in a more manageable reduction in bandwidth and realized gain but increases the reflection coefficient. The triangular meander improves the reflection coefficient and nearly maintains the realized gain of the baseline, but has the least impact on size reduction. Ultimately, the particular design requirements determine which meander structure should be used.

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