



TECHNOLOGY DRIVEN. WARFIGHTER FOCUSED.

MCAP

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Report Documentation Page

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MCAP Operational View







MCAP Potential Exploratory Areas



- Vehicle to Vehicle (V2V) Collision Avoidance
 - Fault detection of failed transponder (device)
 - Communication failure (network)
 - "Hacker"
- Examples:
 - Two or more vehicle entering a common intersection from different directions
 - Leader-follower convoy
 - Traffic signal pre-emption



Sensing Technology

Safety Considerations

Connected, Autonomous Vehicle

Infotain./
Telematics

Also, Safety Critical Systems, Wireless Technologies, and Ad-hoc vehicular systems





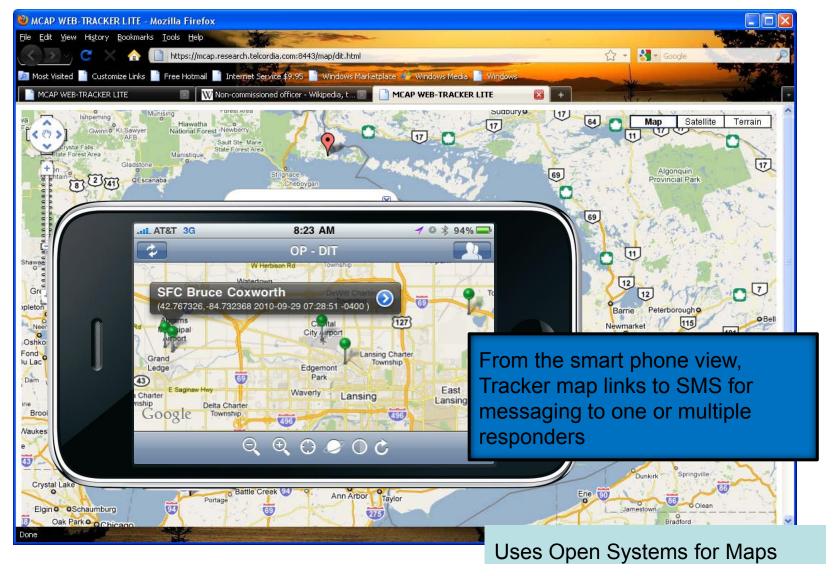
Back -up





MCAP Tracker: Web (for EOC Display)







MCAP In-Vehicle



Vehicle Health Assessment

- Vehicle vital signs talking on the CAN bus
- Assess ability of vehicle to execute response

Vehicle Asset Tracking and Control

- Assessment of additional capability to serve mission
- Adding functionality for remote control of vehicle assets

Vehicle to X

- V-2-V Collision detection and avoidance
- V-2-Traffic signals and control, navigation
- V-2-I for asset sharing

Vehicle as a Communications Cond

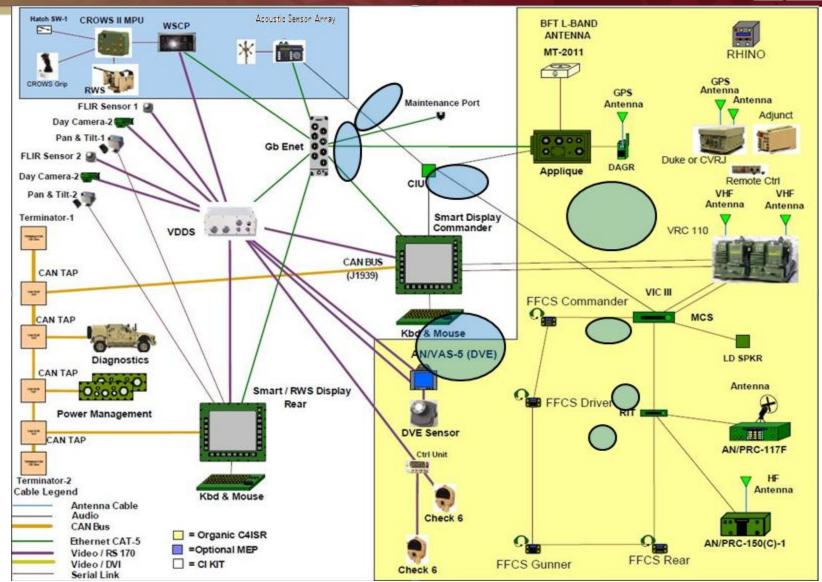
- More power / longer range to back-end
- More power / longer range from dismounted Soldiers / Responders
- Alternate schemes for comm denied to back end including satellite, hardwired, portable cell towers





System Architecture Example







Technology Development and Transition



Develop / Transition Advanced 360 SA Capabilities

- For Now, Develop and Integrate Initial 360 SA Capability w/ COTS Items
- Transition Relevant Technologies Upon Input from Soldiers in the Field

Develop / Transition Autonomy to Sensor Inputs

- For Now, Simply Feed Sensory Data to Soldier for Direct Analysis
- Transition Autonomous Technologies that Improve Soldier Cognition and Decision-Making
 - Slew-to-Cue, Target / Obstacle Detection, Road Edge Detection, etc.

Develop / Transition Advanced Sensors Upon Platform

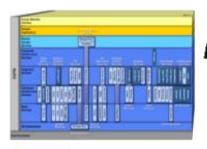
- Current Focus is on Visual (Daytime, IR) Sensors
- Transition New or Upgraded Sensors as Requirements Warrant
 - Laser Range Detectors, Millimeter Wave RADARs, etc.
 - Upgraded Cameras, Displays, Digital Backbone Architecture, etc.



Vehicle Technology Development Areas

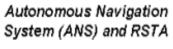


UGV Technology Development and Integration



Demonstrating UGV Control
Utilizing SOSCOE and
Battle Command Software







Hardware and Software Integration



Integrated Computer System and Vehicle Management System



UGV Platform

FCS Like Comms Network



JTRS-GMR



JTRS-GMR



MGV With Embedded UGV Control



Portfolio







Combat Vehicles

- Heavy Brigade Combat Team
- Strykers
- MRAPs
- Ground Combat Vehicles (Future)





Force Projection

- Fuel & Water Distribution
- Force Sustainment
- Construction Equipment
- Bridging
- Assured Mobility Systems



Tactical Vehicles

- HMMWVs
- Trailers
- Heavy, Medium and Light Tactical Vehicles



Robotics

- Technology Components
- Demonstrators
- Military Relevant Test & Experimentation
- Transition & Requirements Development

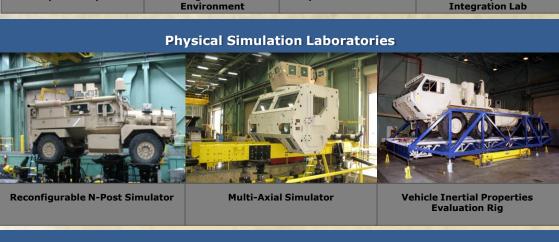
TARDEC Engineers Provide Cradle-To-Grave Engineering Support



Laboratory Capabilities

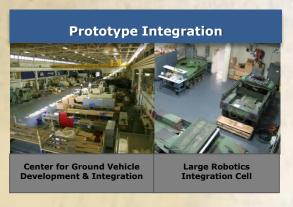








Survivability Laboratories Ballistic Testing





TARDEC's Warren, MI operations has a resource value of over \$950M and occupies 12 facilities on the Detroit Garrison totaling over 840,000 square feet of laboratory space



Enabling Integration & Technology Development









Future Force





MRAP JLTV

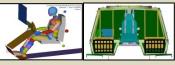


FTTS

Analytics



Thermal / CFD



Crew Safety



Structures/Durability





Blast

Hardware & Man-In-The-Loop Simulation



Characterization



Turret Testing



Human Dimension



Virtual Environments

Prototype & **Demonstrators**



FTTS







TWVS



APD

HPC & Data Management



High Performance Computing (HPC)





Computer Aided Virtual Environment (CAVE)



Advanced Collaborative Environment (ACE)

Providing rapid assessment and integration services throughout the Life Cycle of both Technology and System/Platform Development Programs.