

A Comprehensive Simulation-Based Framework for Design of Army Ground Vehicles

G.M. Hulbert, Z.-D. Ma, Y. Hahn, G. Ryu

2007 SAE World Conference

April 16, 2007



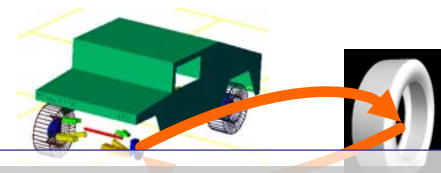
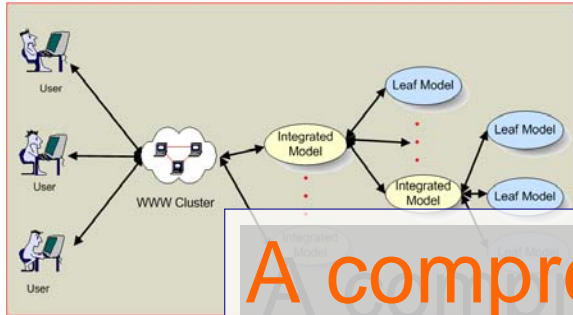
Report Documentation Page

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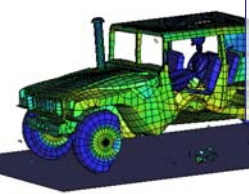
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Presentation Overview

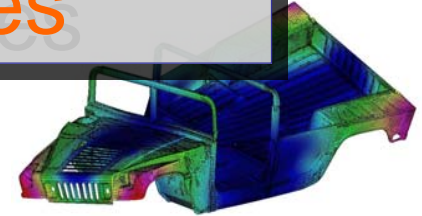
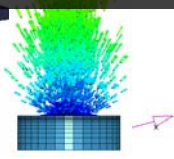


A comprehensive framework for supporting analysis and design of Army's current and next generations of tactical vehicles

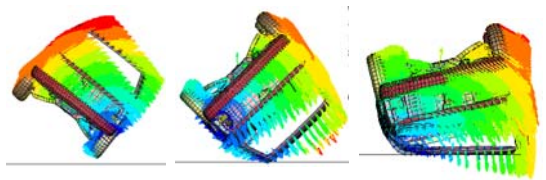
Distributed & Design Platform



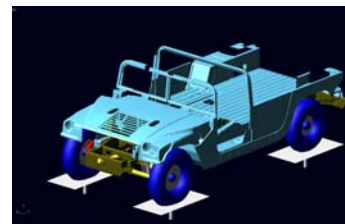
Blast



Durability and Ride



Crash

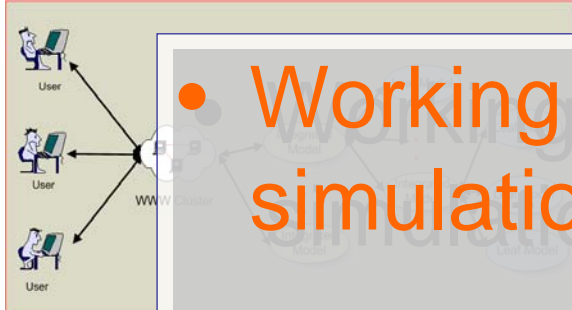


Rollover

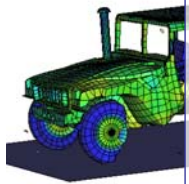


Presentation Overview

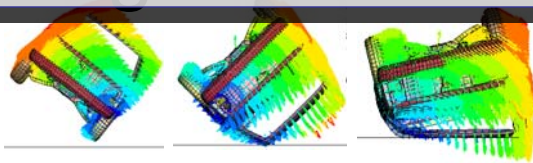
- Working capability for distributed simulation across multiple domains
- New modeling capability for rapid configuration of HMMWV variants
- New modeling techniques for accurate, efficient simulation and design



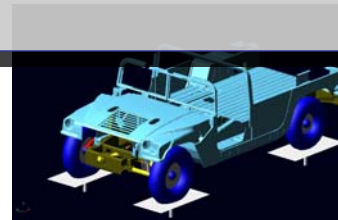
Distributed
& Design



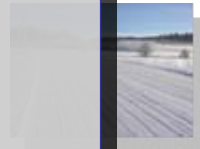
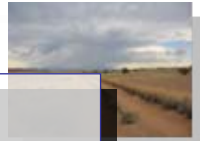
Blast



Crash



Rollover



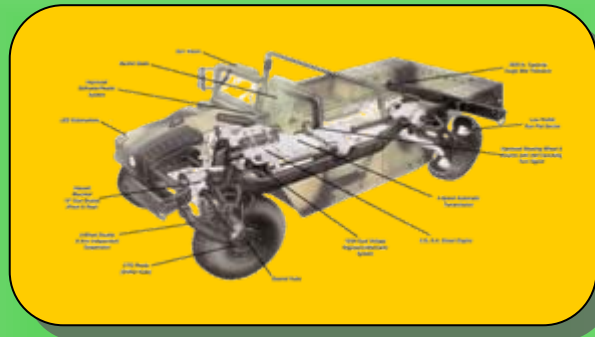
Durability and Ride

Research Objectives

- Develop an integrated simulation and design capability to support:
 - Modularized product development of current and future vehicle families



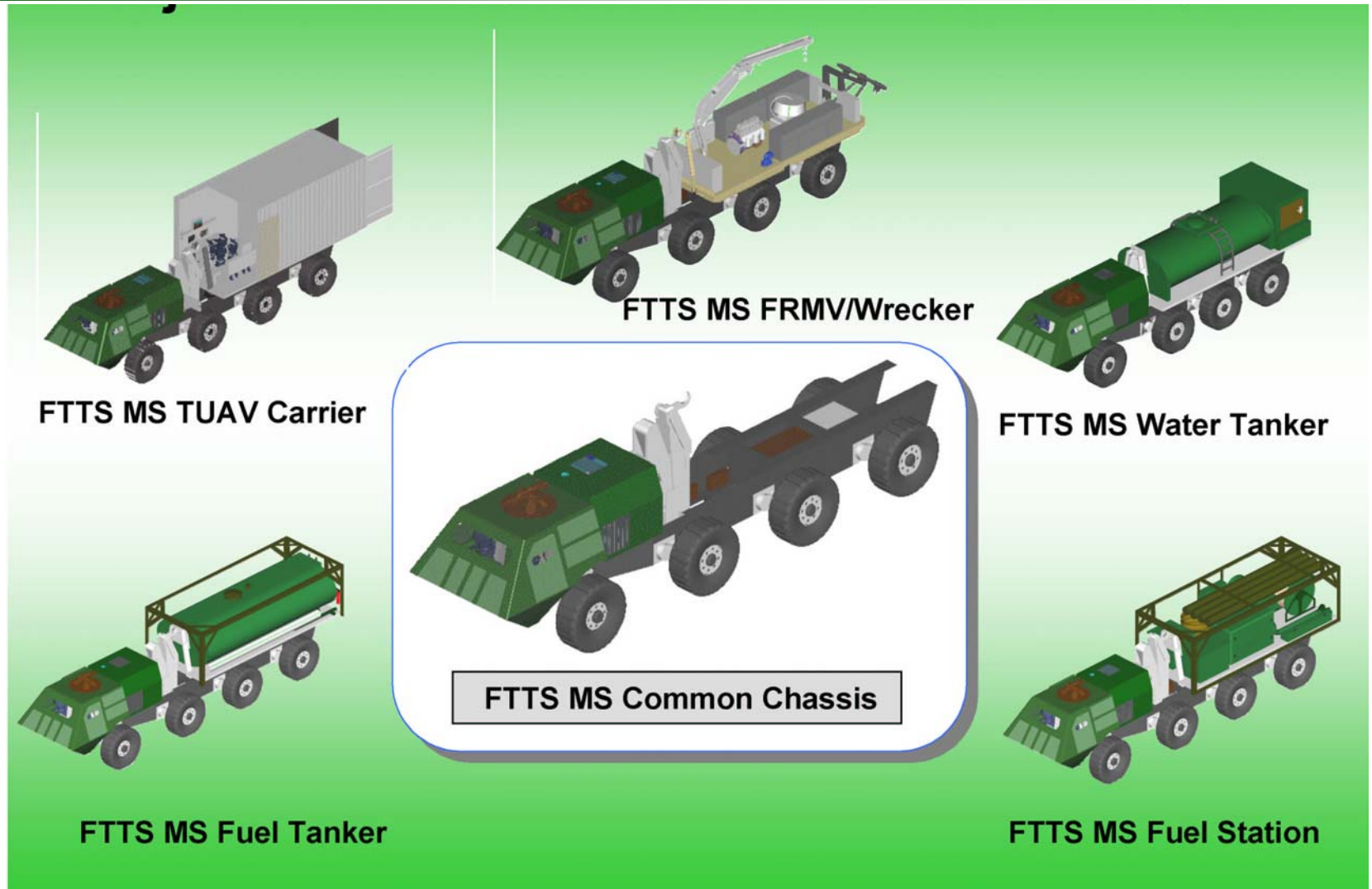
The HMMWV Family



Research Objectives

- Develop an integrated simulation and design capability to support:
 - Modularized product development of current and future vehicle families
 - Innovative vehicle concepts in support of Army transformation

Future Tactical Truck System

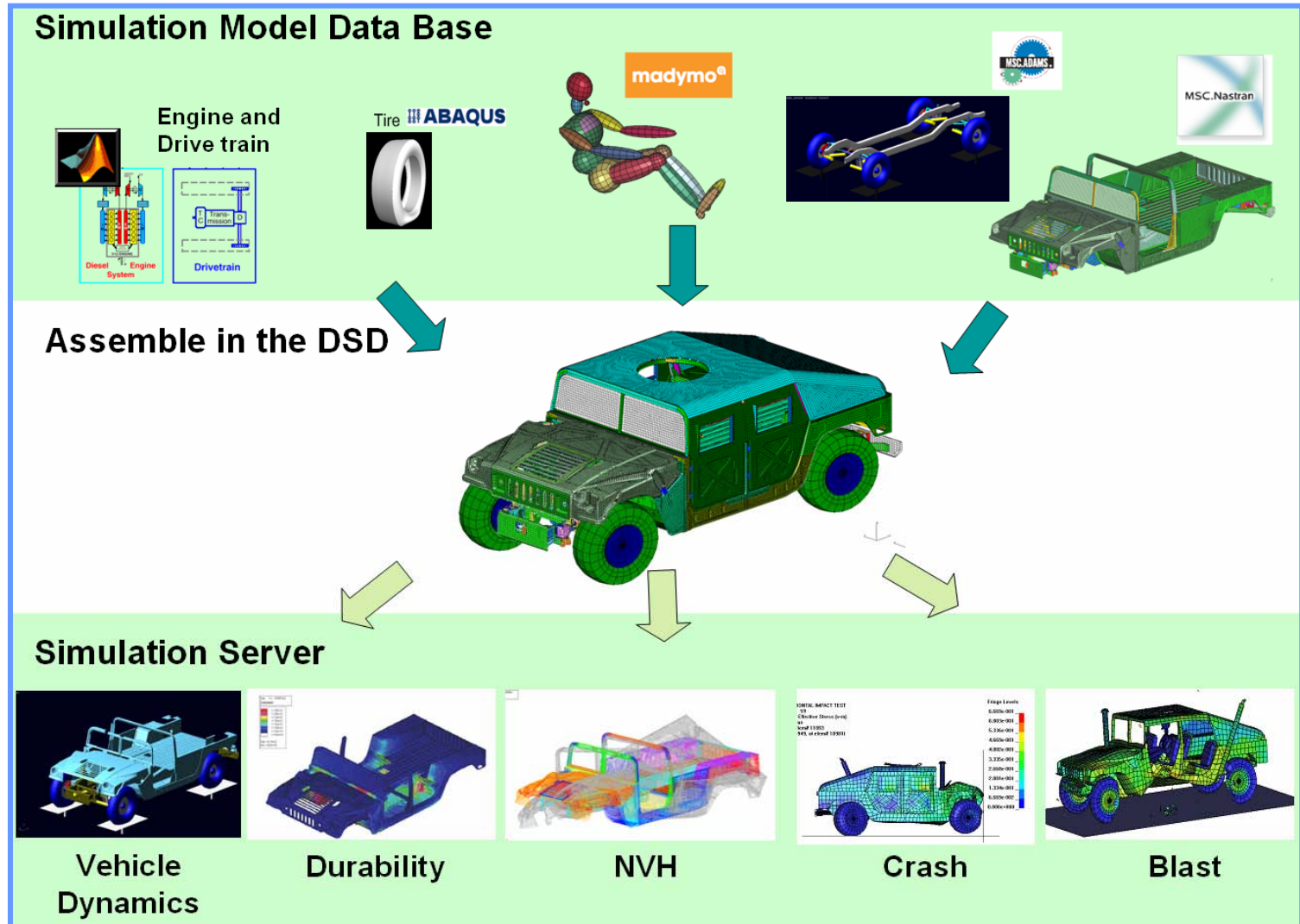


Research Objectives

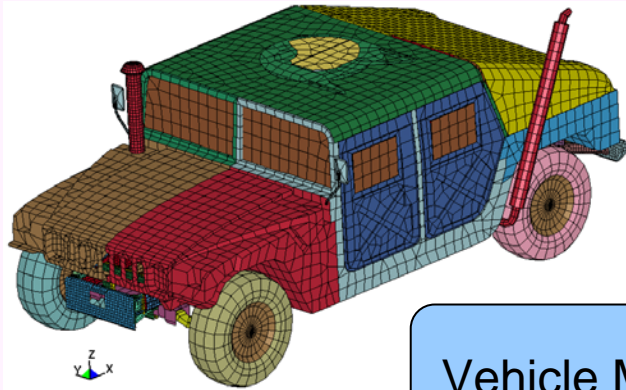
- Develop an integrated simulation and design capability to support:
 - Modularized product development of current and future vehicle families
 - Innovative vehicle concepts in support of Army transformation
 - Efficient integration of distributed models, simulation codes, and new design methodologies for commercial and military applications



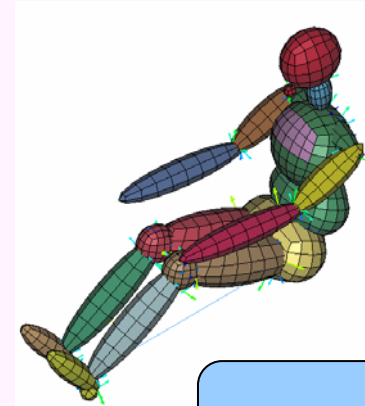
Vision of Distributed Simulation and Design



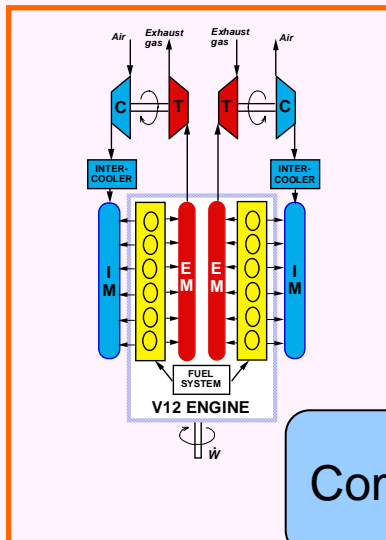
Requirement: Multi-Domain Simulation



Vehicle Model

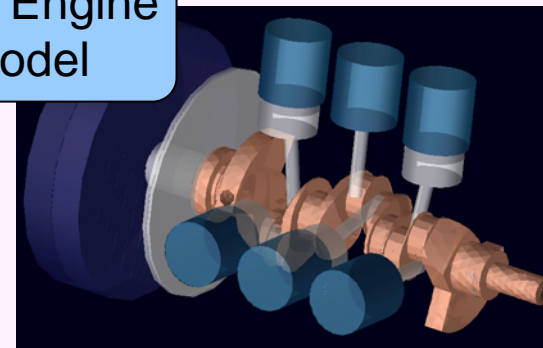


Human Model

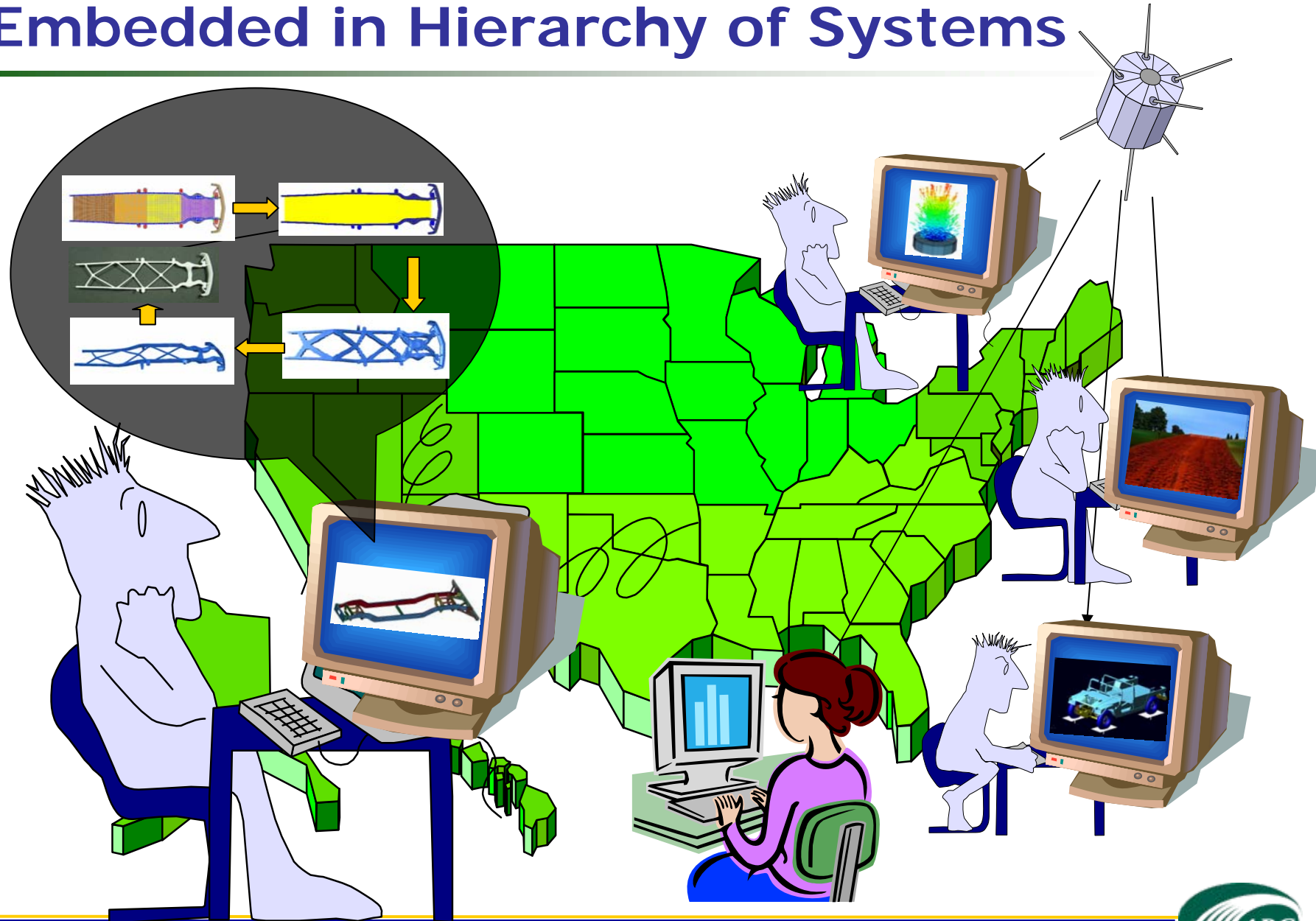


Combustion Model

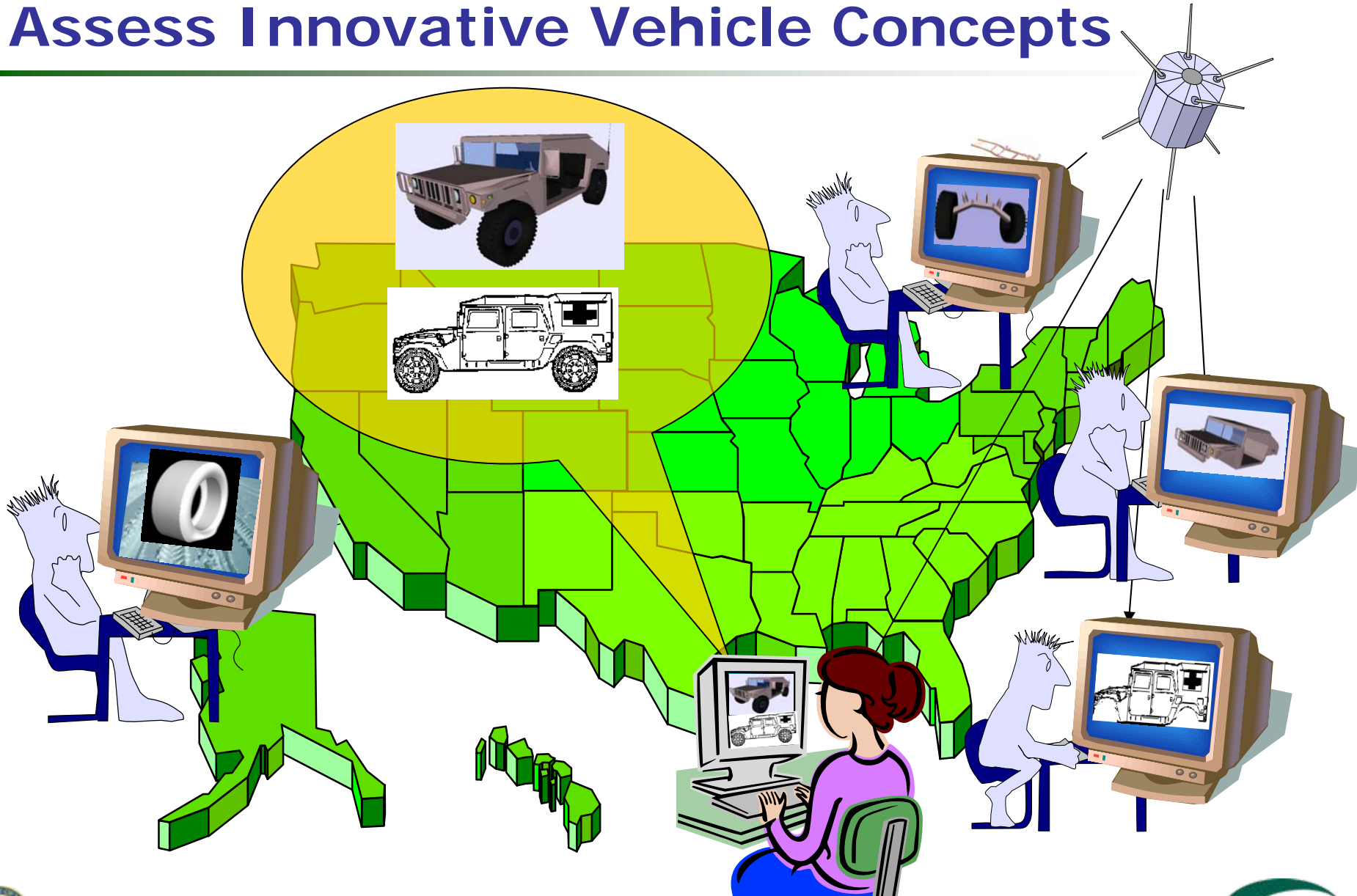
MBD Engine Model



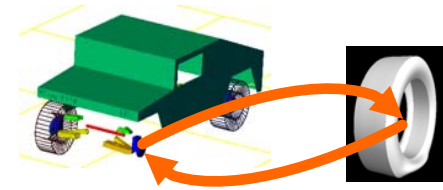
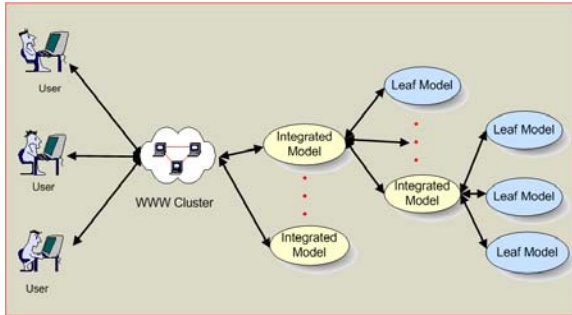
Requirement: Subsystem Design Embedded in Hierarchy of Systems



Requirement: Rapid Configuration to Assess Innovative Vehicle Concepts

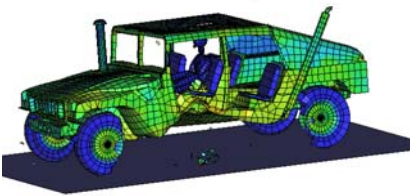


Overview

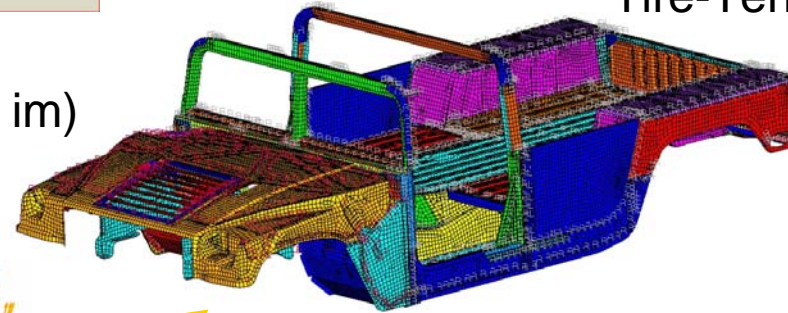
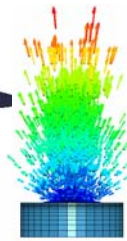


Tire-Terrain Interaction

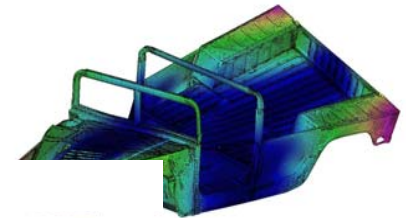
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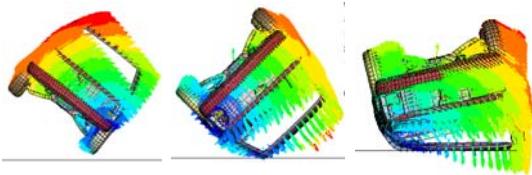
Blast



**Distributed Simulation
& Design Platform (D-Sim)**



Durability and Ride



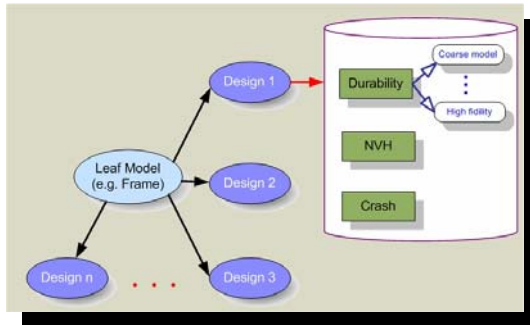
Crash



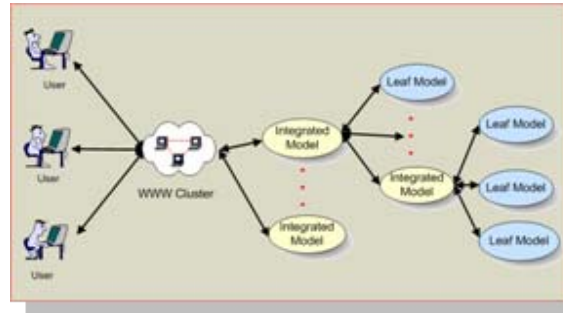
Rollover

Major Components of D-Sim

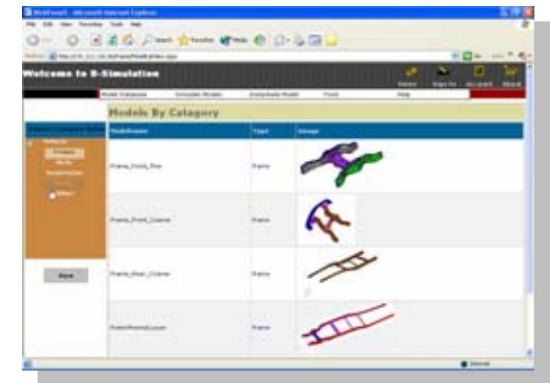
Model Database



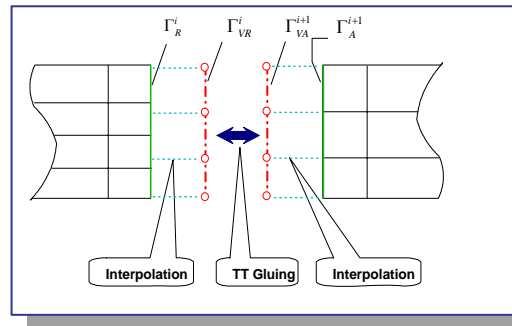
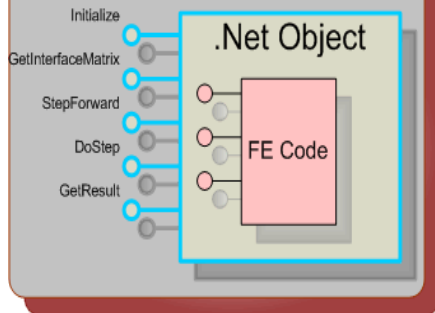
Distributed Architecture



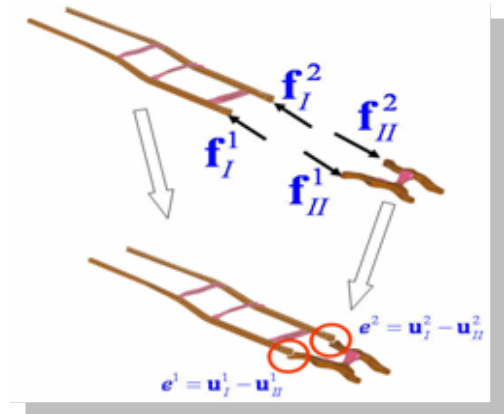
Web-based Interface



Component Model Server



Non-matching Interfaces



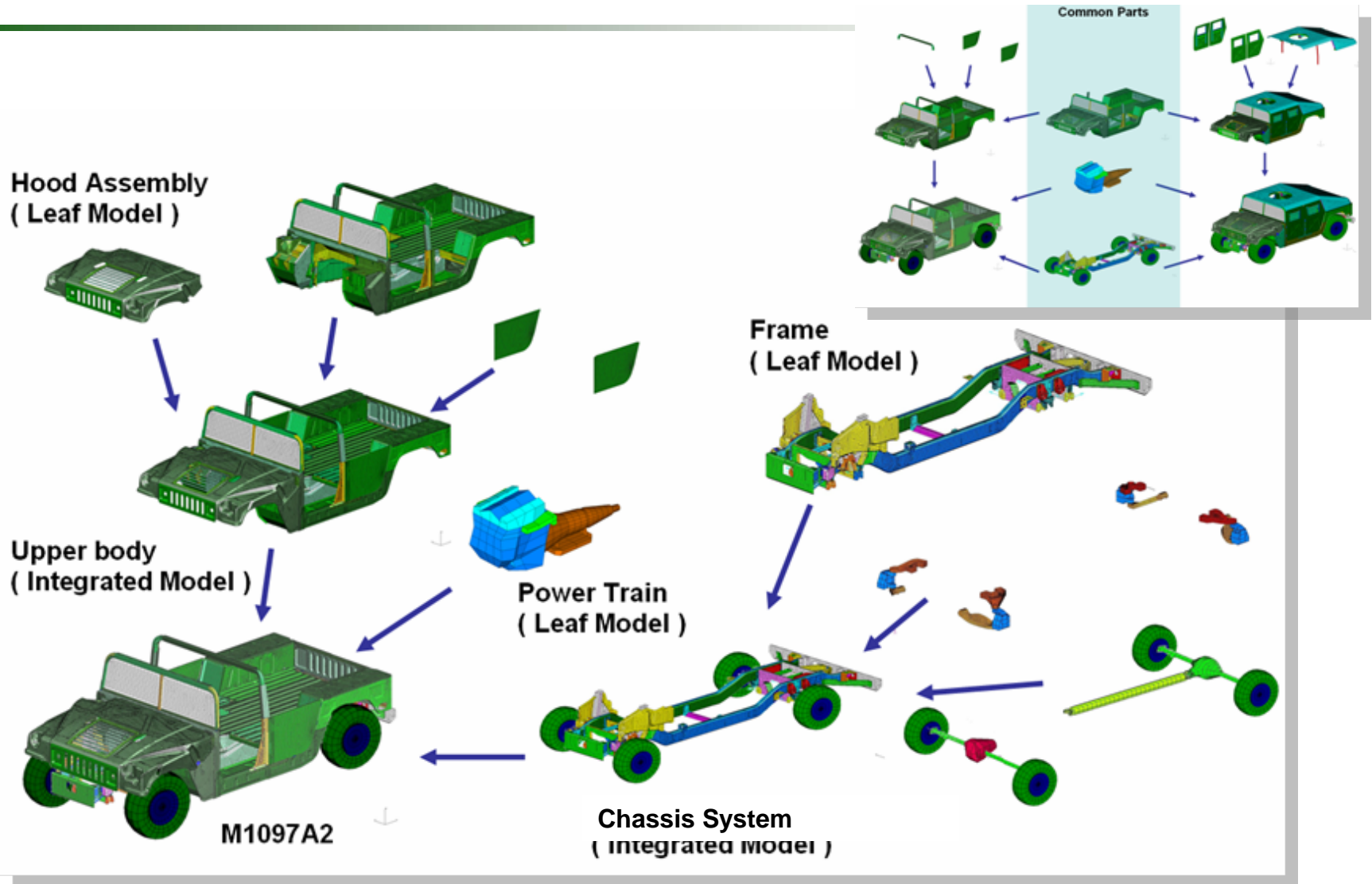
Gluing Algorithm

Simulation Code Wrapper

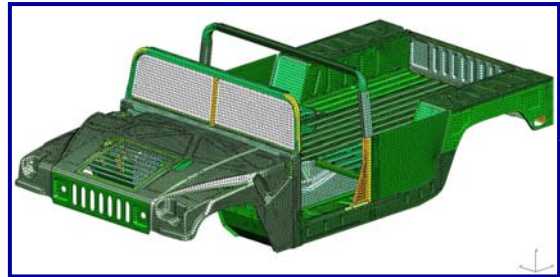
Collection of HMMWV Subsystem Models



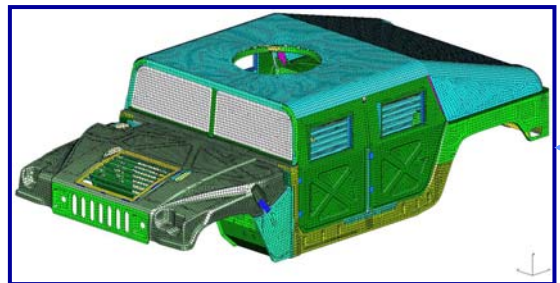
Integrated Systems Approach



Rapid Configuration of Different Vehicles



M1097A2 UPPER BODY

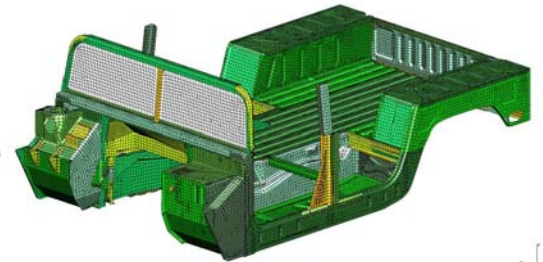


M1025 UPPER BODY

Common Parts



HOOD ASSEMBLY



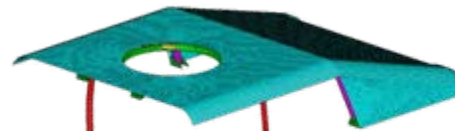
HMMWV BASE UPPER BODY



B-PILLAR
CROSS MEMBER



RR DOOR

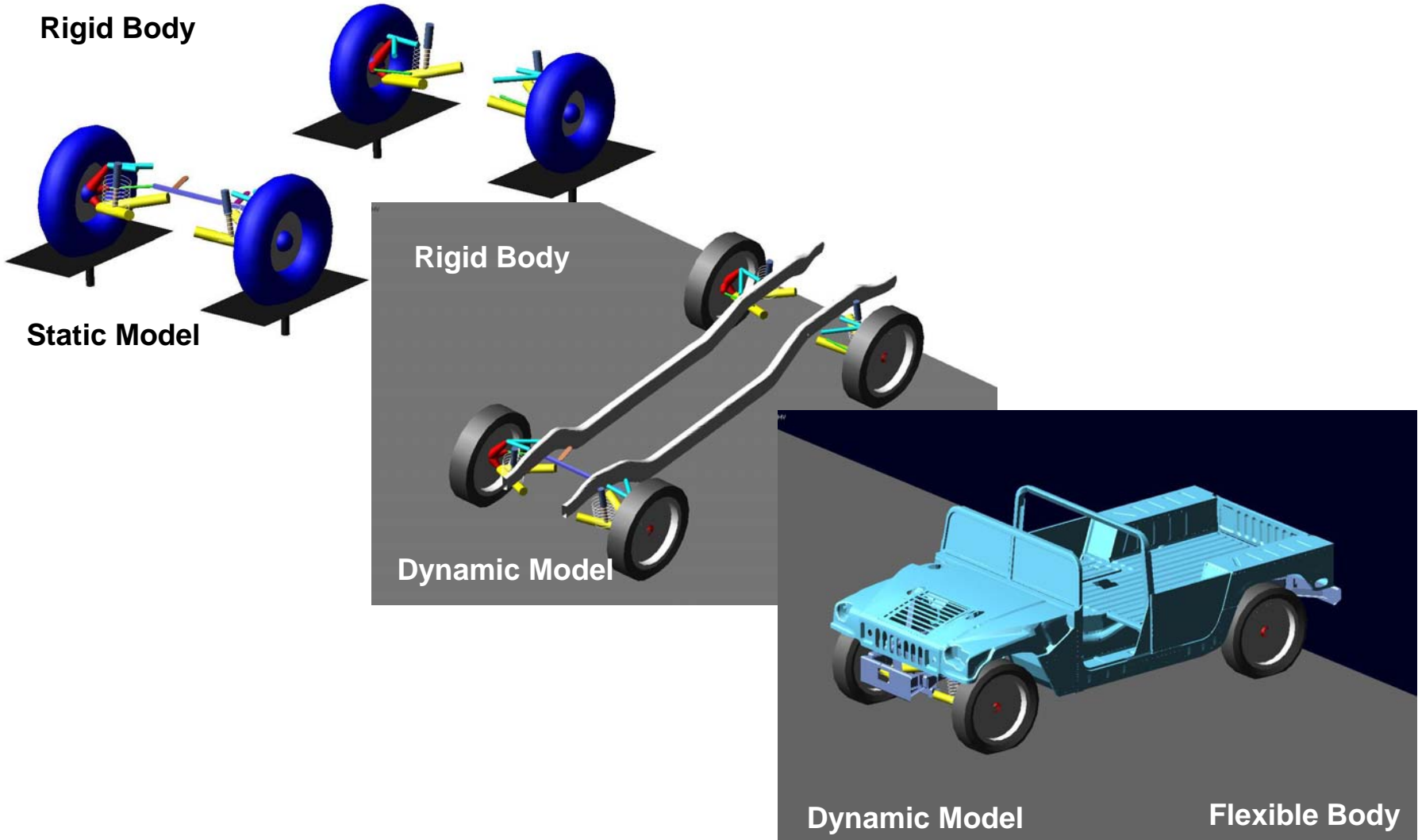


ROOF ASSEMBLY



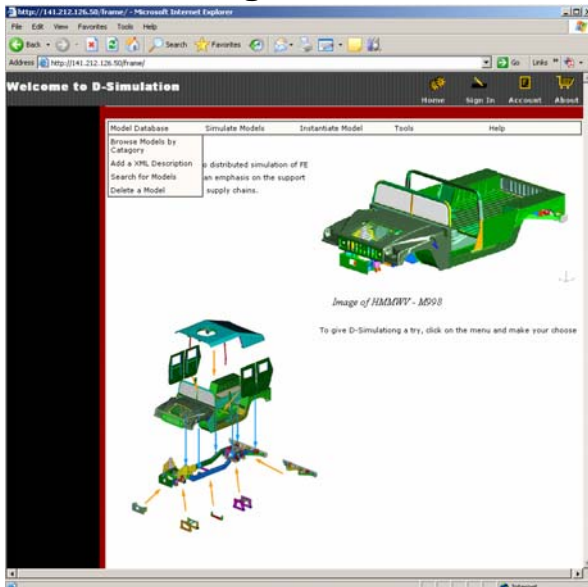
DOOR
ASSEMBLY

Rapid Substitution of Different Fidelity Models



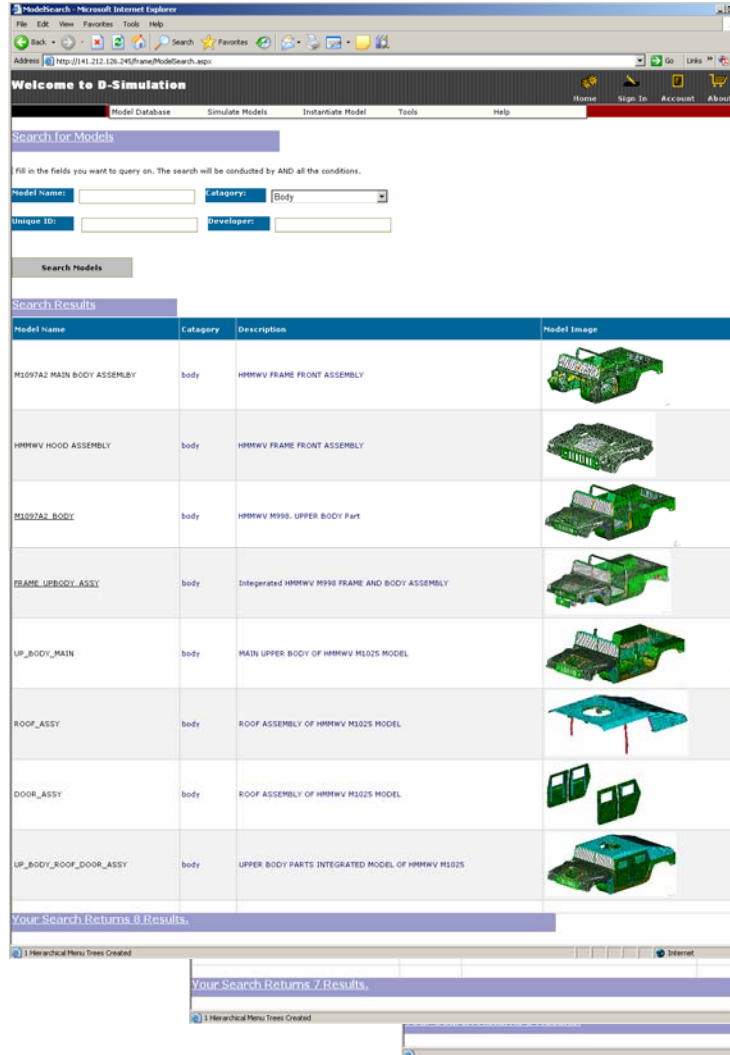
Web-Based Interface

Main Web Page for D-Simulation

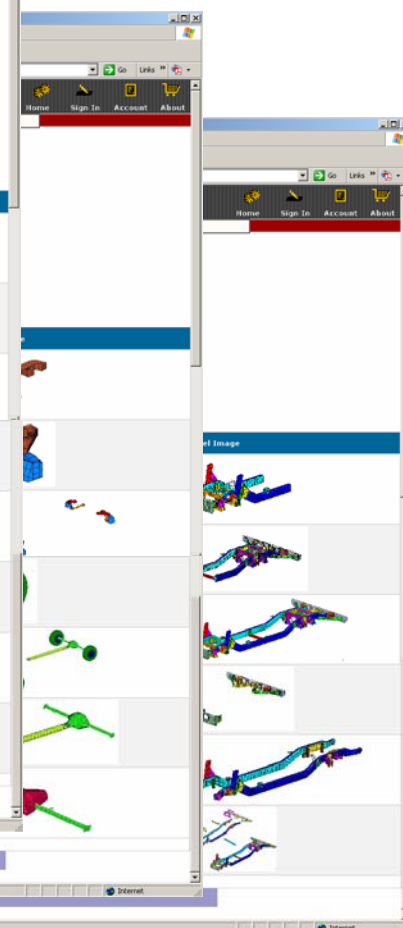


- Search multi-layered model database
- Define interfaces for model integration
- Generate new distributed simulation and design models

UPPER BODY PARTS

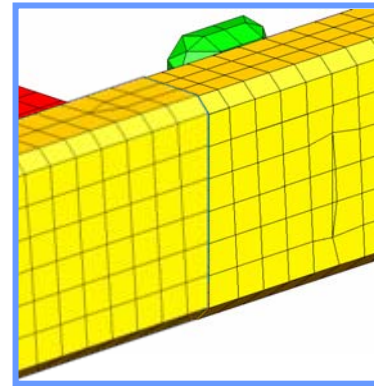
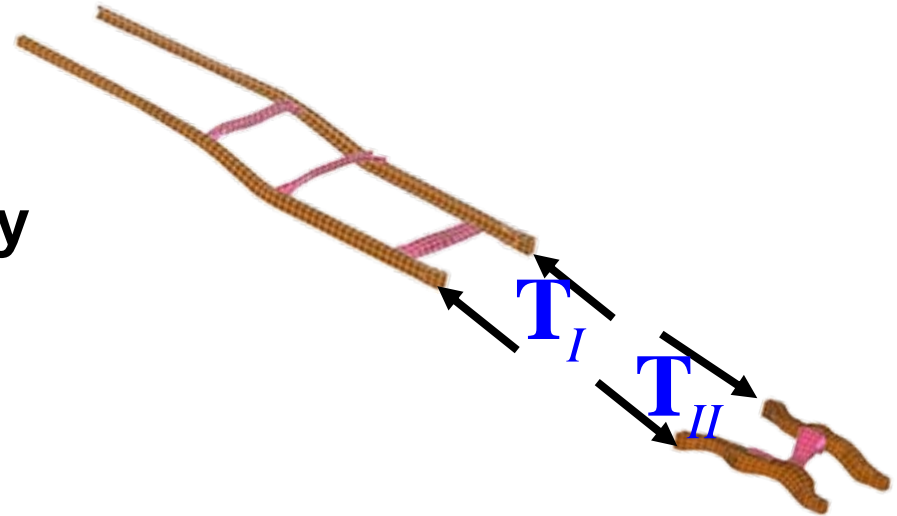


ARTS

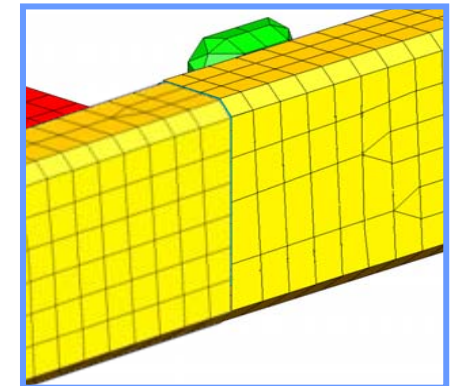


Gluing Algorithm and Non-Matching Interfaces

- Enables multi-platform, multi-layered plug and play capability
- Standardizes model interfacing
- Protects proprietary data / models

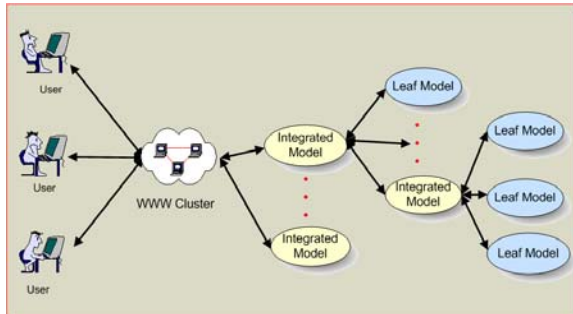


Matching

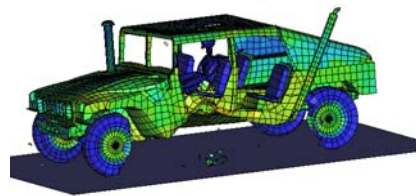


Non-Matching

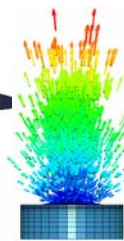
Overview



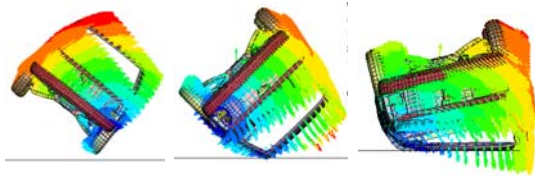
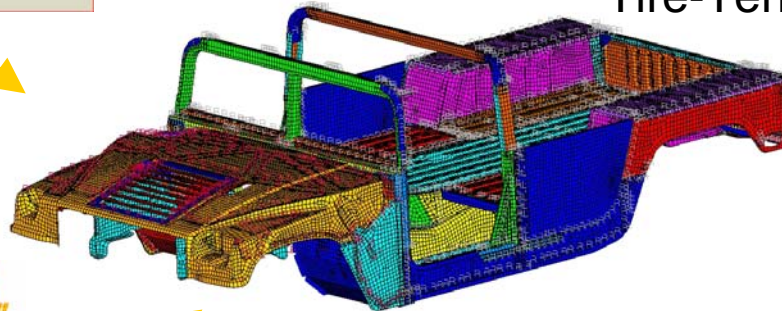
D-Sim



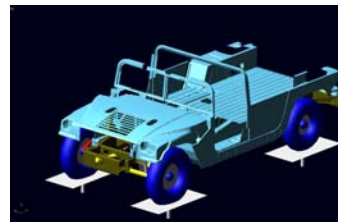
Blast



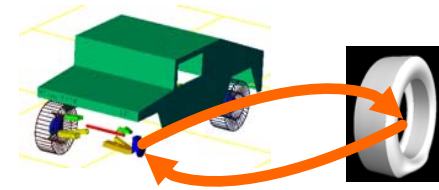
Durability



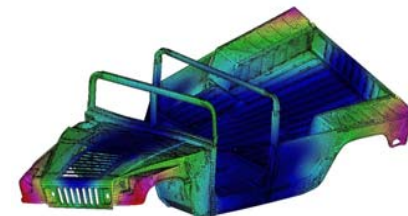
Crash



Rollover



Tire-Terrain Interaction

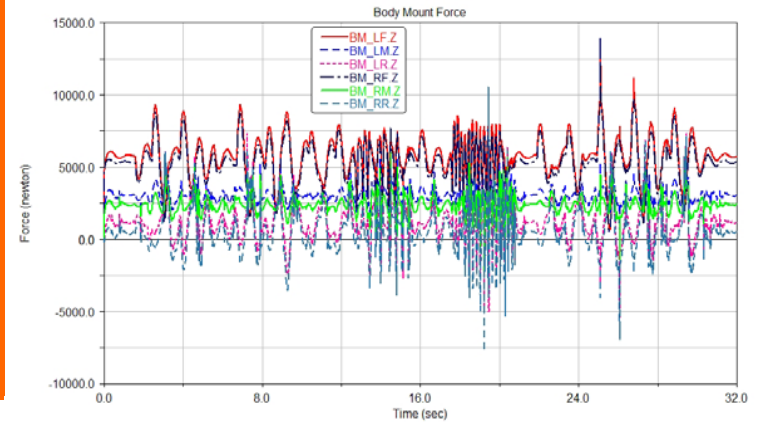


Durability Road Simulation

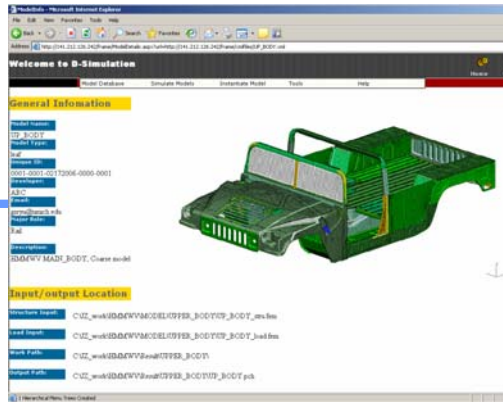
Durability Road



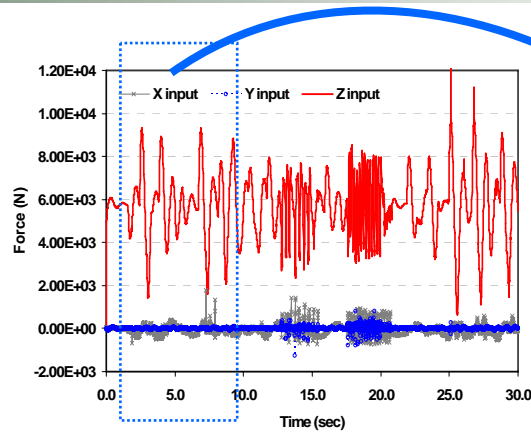
Computed Body Mount Forces



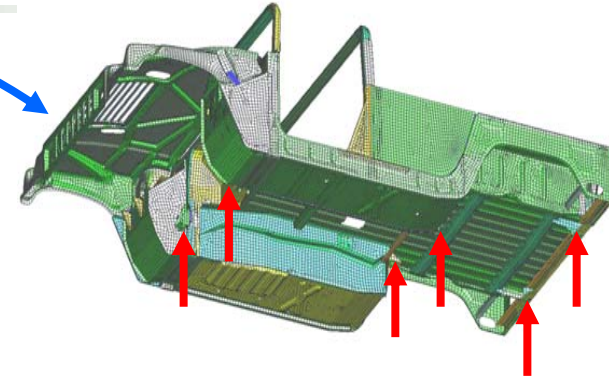
Gluing Algorithm for Durability



Assembly of Main Body and Hood



Forces computed using ADAMS

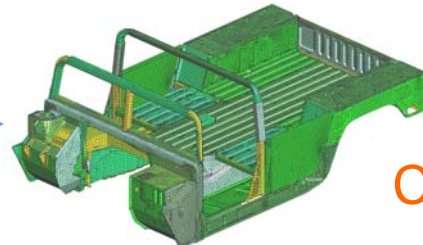


Apply external force at 6 body mounts



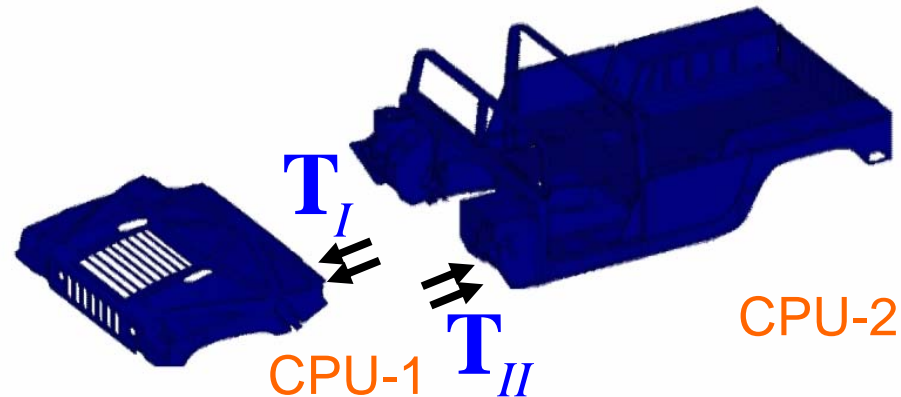
CPU-1

HOOD ASSEMBLY



CPU-2

MAIN BODY ASSEMBLY

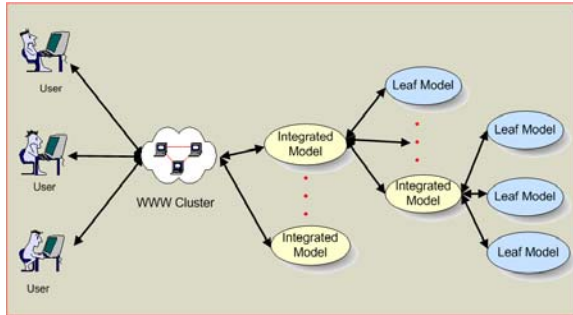


CPU-1

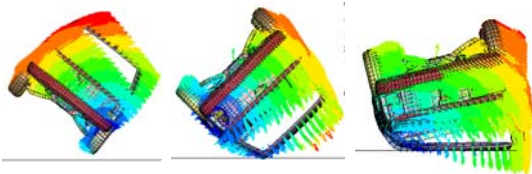
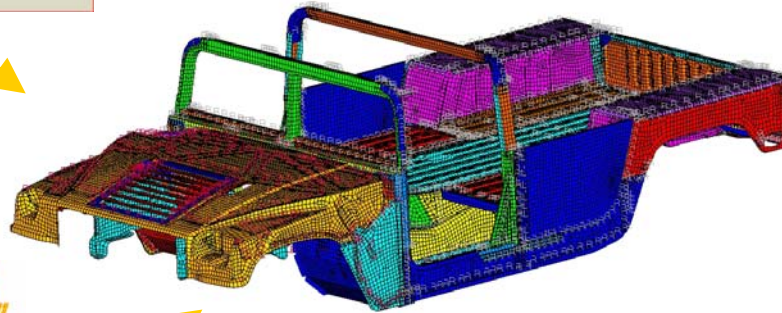
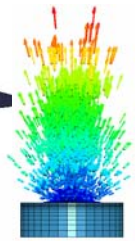
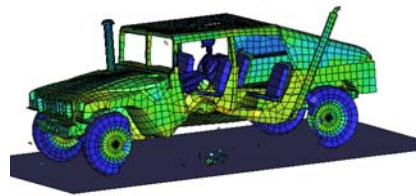
CPU-2

D-Sim Results
(coupled simulation)

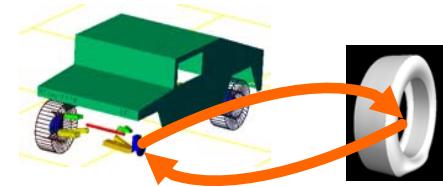
Overview



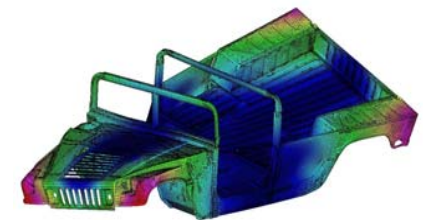
D-Sim



Safety



Terrain Interaction



Durability and Ride

Safety Applications



Rollover



Crash



Blast



Extreme Terrain

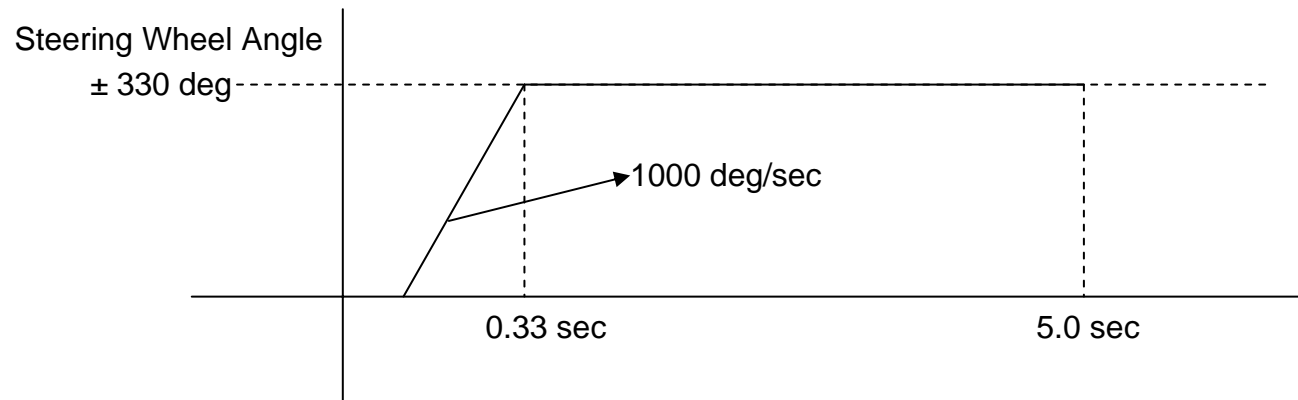
HMMWV Rollover



J-Turn Rollover Simulation (Flat Ground)

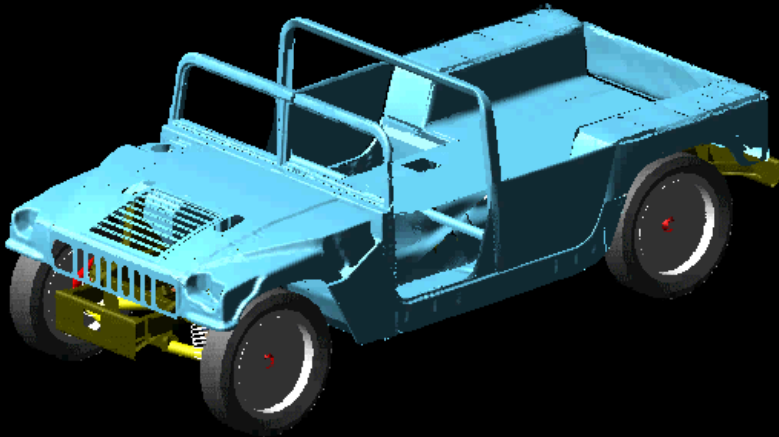
Driving Conditions

- Modified test protocol
- Initially driven in a straight line
- Initial speed: 10 mph and up
- Test runs for 5 seconds



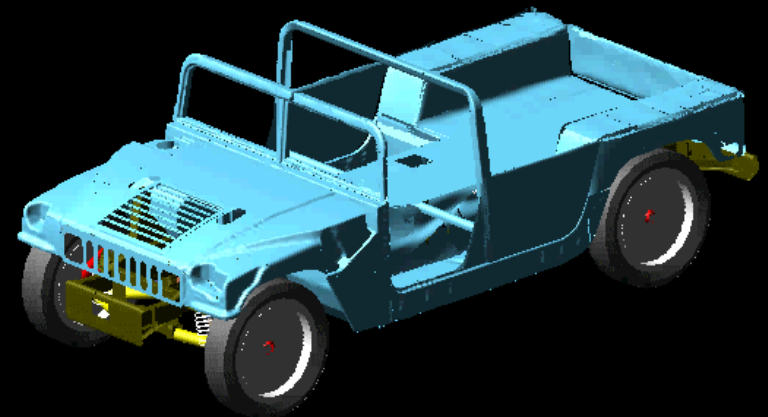
J-Turn (Rigid Body Model)

Time= 6.0000 Frame=001



- Predict critical speed range
- Study rollover behavior
- Assess effect of up-armor system
- Design for rollover prevention

Time= 6.0000 Frame=001

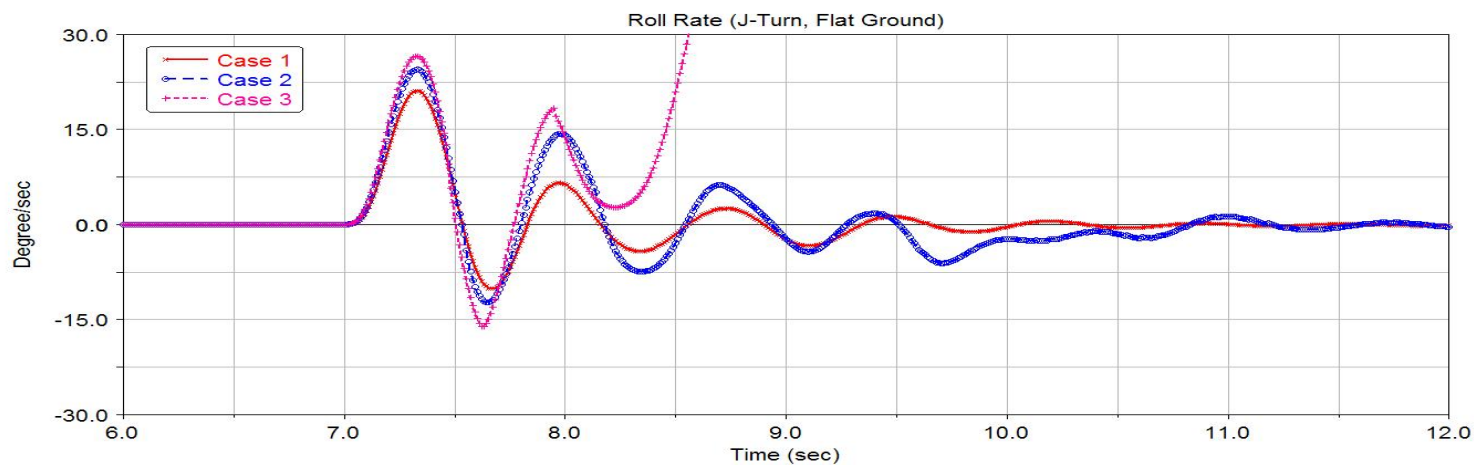
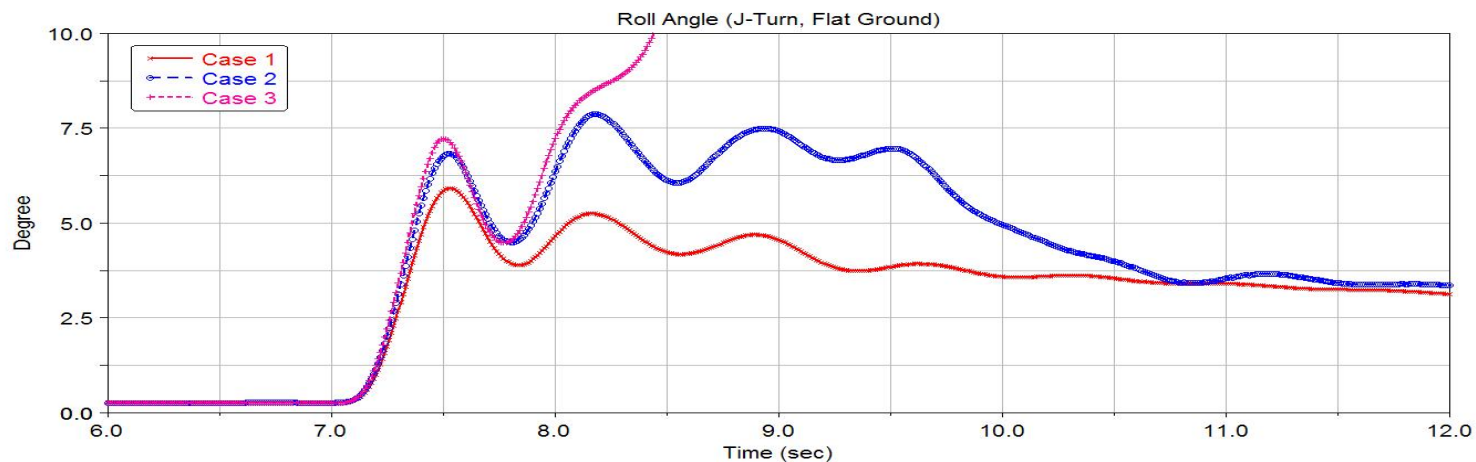


Nominal speed

Nominal speed+ 10 mph

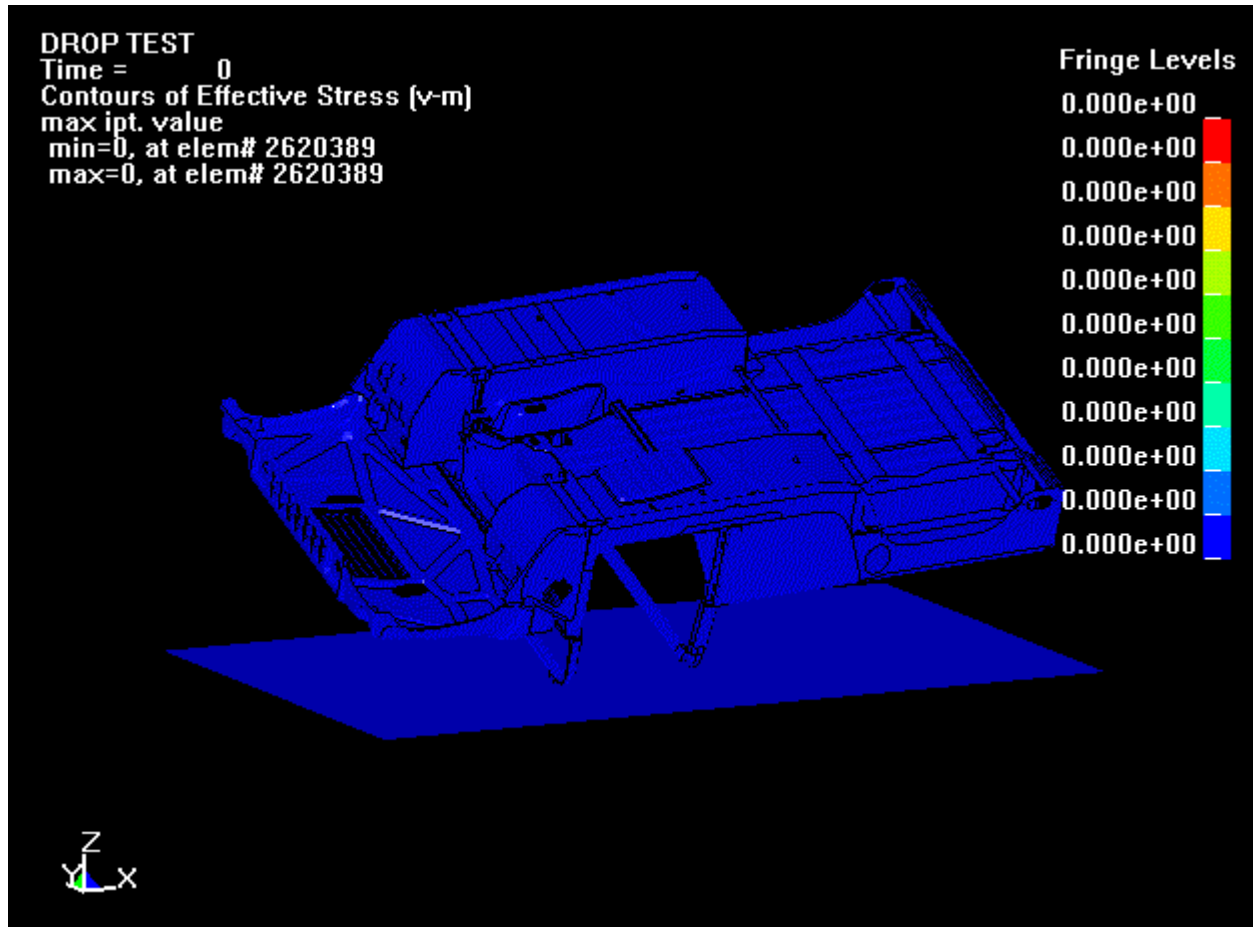


J-Turn Analysis Results

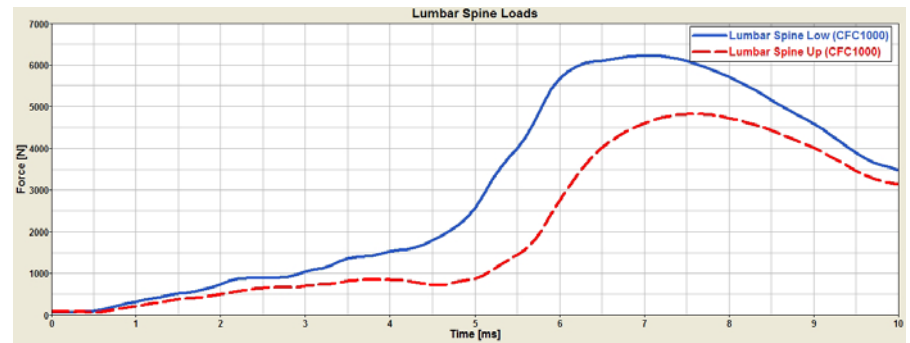
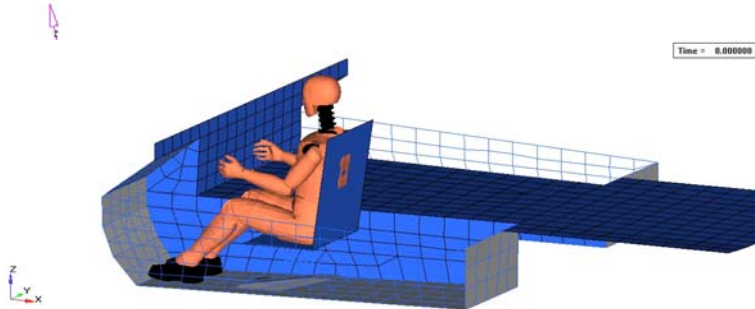
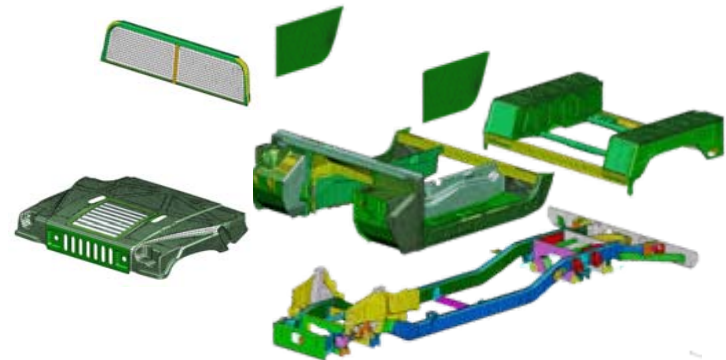
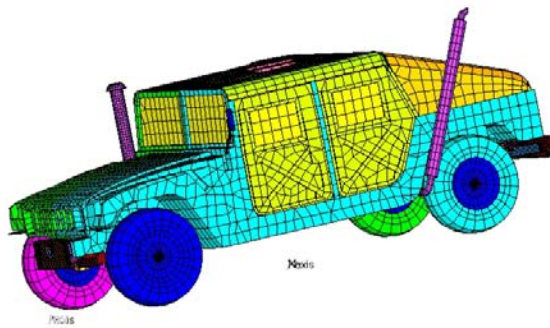


Roof Strength Analysis

➤ Drop Test



Simulating the Response of Structures and Occupants to Blast Loads



Response of vehicle floor and occupant under blast

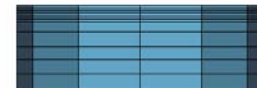
J-Turn Rollover under a Blast

blast2_3 Time= 6.0000 Frame=001

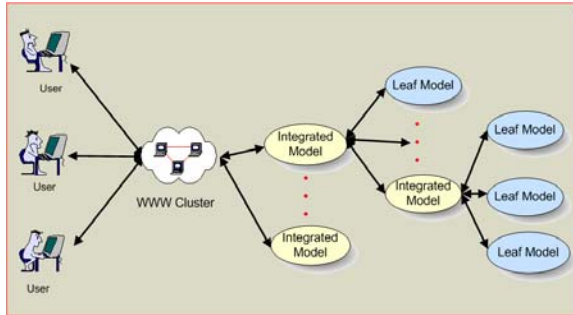


LANDMINE EXPLOSION
Time = 0
Vector of Total-velocity
min=0, at node# 50
max=0, at node# 581

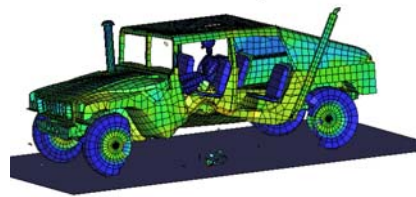
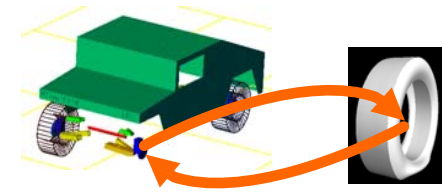
Fringe Levels
0.000e+000
0.000e+000
0.000e+000
0.000e+000
0.000e+000
0.000e+000
0.000e+000
0.000e+000
0.000e+000
0.000e+000
0.000e+000



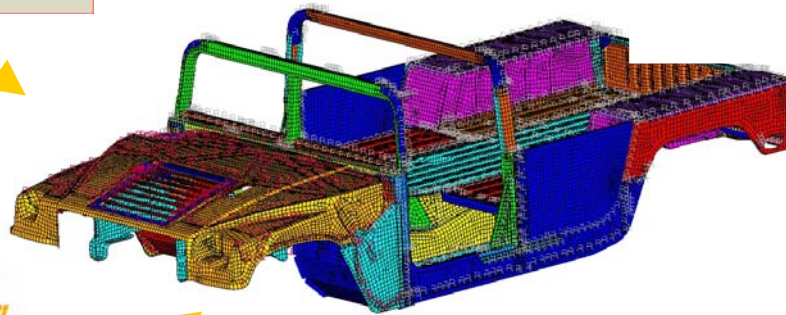
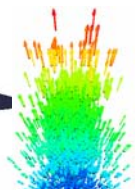
Overview



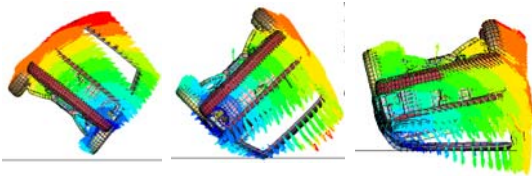
D-Sim



Blast



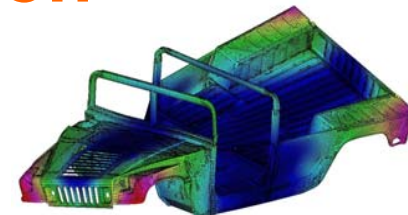
Tire-Terrain Interaction



Crash

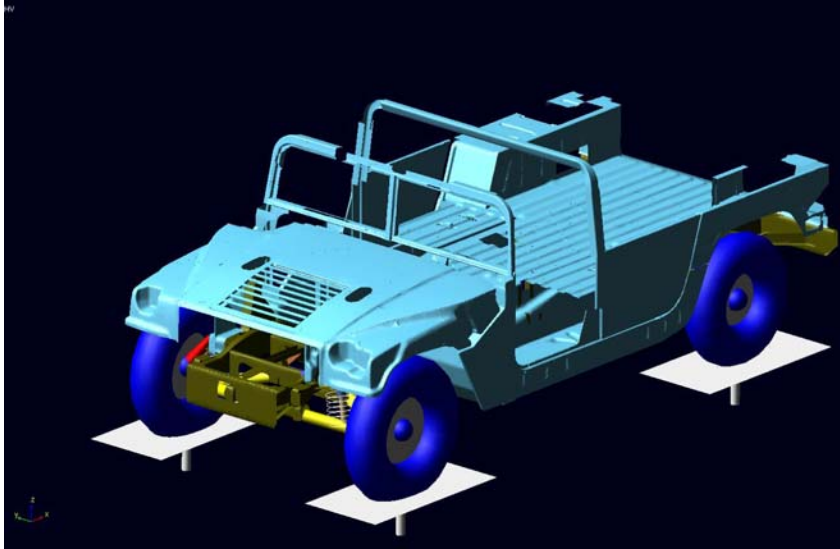


Rollover



Durability

Extreme Terrain



Sand



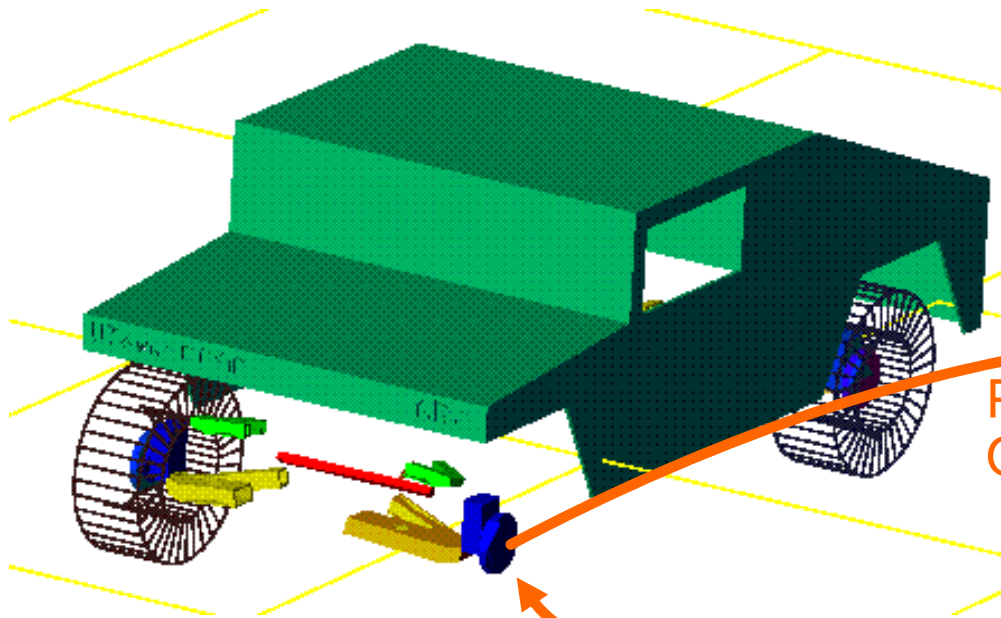
Ice



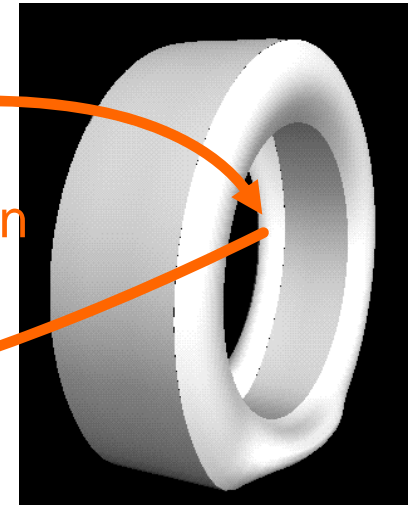
Snow

Tire-Terrain Interaction

- Tire passes forces / moments to vehicle
- Vehicle passes hub position / orientation to tire



Position / Orientation



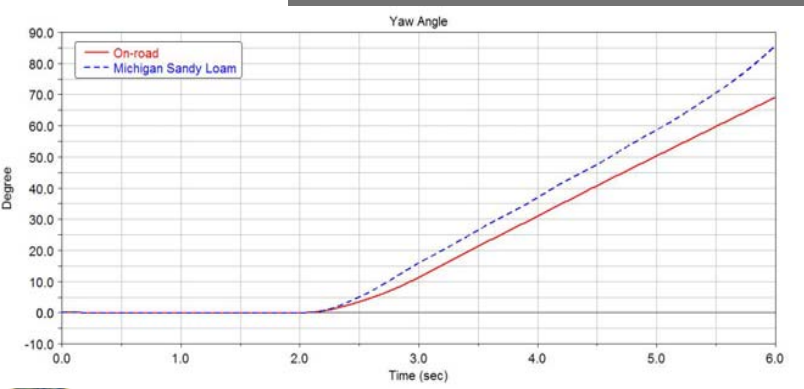
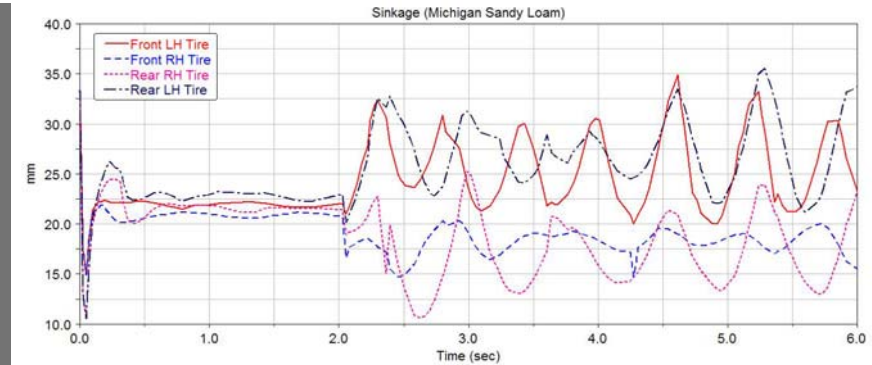
Forces/Moments

Vehicle Performance for Off-Road Events

Multiple Runs Time= 0.0000 Frame=001

Michigan Loam

On-road



Summary

- Comprehensive, integrated platform for analysis and design to support current and next generation vehicles
- Enabling technologies:
 - General, functional simulation framework
 - Algorithms for coupling different models and simulation codes
 - Algorithms for coupling non-matching interfaces



Future Developments

- Continue development of model database
- Incorporate human models
 - Driver perception
 - Assess safety systems
- Expand integration with commercial software
- Verify, validate and update model database using instrumented vehicles
- Simulation-based certification



Future Developments

