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**ANALYSIS OF A LEAKY TRAVELING
WAVE ANTENNA (PREPRINT)**

**Gregory M. Zelinski, Gary A. Thiele, M. Larkin Hastriter,
Michael J. Havrilla, and Andrew J. Terzuoli**



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Analysis of a Leaky Traveling Wave Antenna

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Abstract—Several leaky traveling wave antennas using the first microstrip higher order mode were simulated with the Finite Difference Time Domain (FDTD) method. The leaky wave antennas investigated here differ from previous designs. The propagation constant of each antenna was extracted from the resulting guided field distribution for comparison with a transverse resonance approximation, measured far-field patterns, and other simulated antennas. Variations of geometry were explored to investigate the complex propagation constant and its effect on the far-field pattern and the bandwidth.

Index Terms—Antennas, traveling waves, leaky waves, Finite Difference Time Domain (FDTD), bandwidth.

I. INTRODUCTION

MICROSTRIP antennas are attractive because of their light weight, low profile, and low cost. These antennas may be grouped into two classes: 1) the resonant patch, which is narrow band with a fixed main beam, and 2) the non-resonant leaky wave antenna, which typically has a wider bandwidth with a frequency-steerable main beam.

A leaky wave antenna must be excited by a higher order mode, since the fundamental mode of microstrip does not produce fields that decouple from the structure, as shown in Fig. 1(a). If the fundamental mode is not allowed to propagate, the next higher order mode may dominate above its cutoff frequency. Fig. 1(b) shows the electric field lines due to the first higher order mode EH_1 . A phase reversal, or null, appears along the centerline that results in oppositely directed \mathbf{E} fields at the edges allowing the fields to decouple and radiate.

In the late 1970's, Ermert [1], [2] was the first to publish the properties of higher order microstrip modes. However, his work was incomplete because his longitudinal propagation constant consisted solely of a phase constant β but neglected the leakage constant α . At about the same time, Menzel [3] published a paper on a microstrip transmission line antenna employing the first higher order mode. He assumed there was a meaningful leakage constant to allow the structure to radiate, but he did not recognize that he had developed a leaky

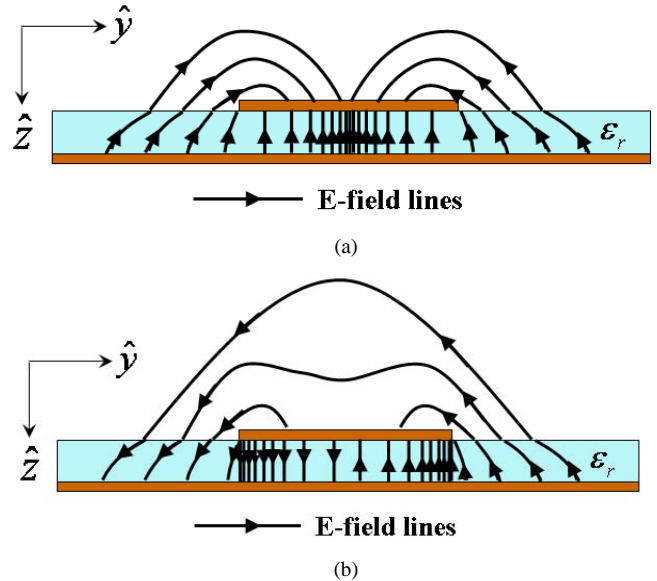


Fig. 1. (a) The electric field pattern associated with the fundamental mode of microstrip EH_0 . (b) The electric field pattern associated with the first higher order mode of microstrip EH_1 .

wave antenna and, thus, built it too short [4], [5]. Oliner [6] further clarified the fact that Menzel had actually built a leaky traveling wave antenna with a complex propagation constant.

Since the late 1970's there have been a number of papers on microstrip leaky wave propagation. Leaky wave propagation has been studied in [7]–[10] and leaky wave antennas in [11]–[17], although, the potential of these antennas has not been fully explored.

The performance parameters of a traveling wave antenna can be predicted as a function of the wavenumber in the direction of propagation within the structure. The guided wave phase constant β determines the direction of the main beam from endfire, and the guided wave attenuation constant α determines the beamwidth of the main beam. Both constants together determine the leaky wave bandwidth. Walter [18] provided an excellent source for analysis of traveling wave antennas.

As seen in Fig. 2(a), Menzel's antenna uses seven slots cut from the conductor along the centerline to suppress the fundamental mode allowing leaky wave radiation via the first higher order mode. Fig. 2(b) shows an evolved antenna that incorporates a metal wall down the centerline to block the fundamental mode instead of transverse slots. Symmetry along this metal wall invites the application of image theory. One entire side of the antenna is now an image of the other side, making it redundant and unneeded. The resulting antenna in

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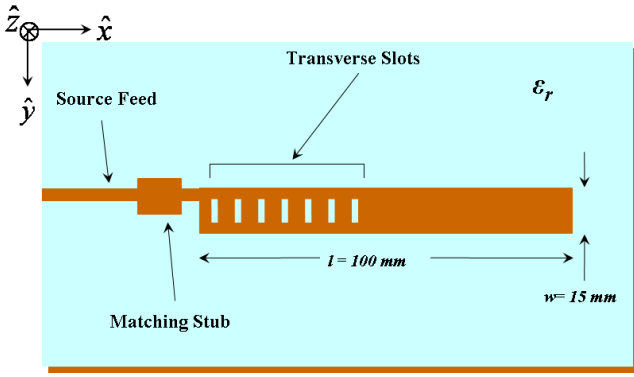
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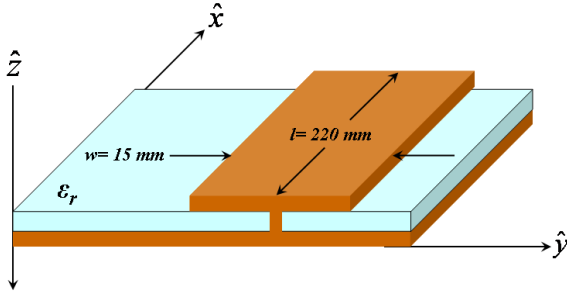
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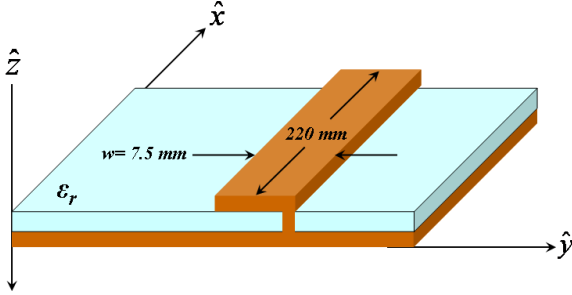
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(a)



(b)



(c)

Fig. 2. (a) Menzel's original antenna [3], (b) the full width (FW) antenna, and (c) the half width (HW) antenna.

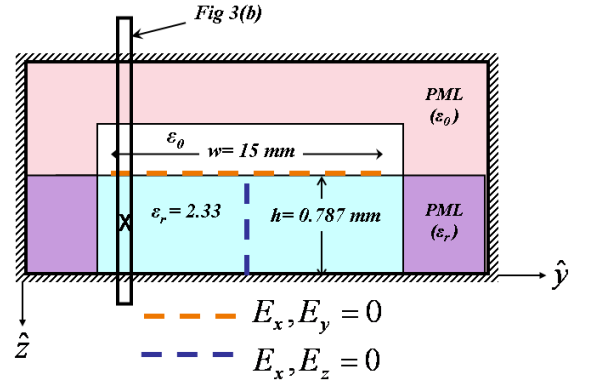
Fig. 2(c) is half the width of Menzel's antenna.

Advantages of the half width (HW) antenna compared to the Menzel antenna are: 1) no need to suppress the EH_0 mode; 2) no slot cross-polarized radiation that reduces radiation efficiency; 3) purer guided mode compared to the Menzel configuration, which improves radiation efficiency; 4) potentially less mutual coupling in an array environment.

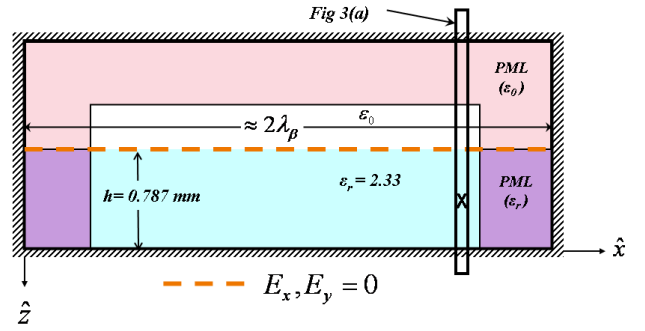
II. FDTD SIMULATION

A. The computational domain

The three antennas of Fig. 2 were simulated for analysis. An FDTD algorithm [19] was used employing a 3-D central differencing Yee-cell formulation with a Uniaxial Perfectly Matched Layer (UPML). The UPML was 10-cell-thick, 4th order polynomial graded, and PEC-backed on all six faces. The loss mechanism was normalized to free space to allow layers of unlike materials within the PML.



(a)



(b)

Fig. 3. A 2-D depiction of the 3-D computational space. (a) The $\hat{y} - \hat{z}$ slice of the FW antenna extending into the UPML (not to scale). The single source cell is marked by an X. The $\hat{x} - \hat{z}$ slice of Fig. 3(b) is outlined. (b) The $\hat{x} - \hat{z}$ slice of the FW antenna extending into the UPML (not to scale). The $\hat{y} - \hat{z}$ slice of Fig. 3(a) is outlined.

The copper conductor was modelled as a zero-thickness perfect electric conductor (PEC) by setting the tangential electric field to zero at the desired cell boundaries. Care was taken to accurately model the width of each antenna by reducing the PEC width by 1 cell, as demonstrated by Sheen [20].

The excitation means was a *hard* source with cubic growth over the first few periods to eliminate the problematic high frequency components of rapid transitions. A single source cell midway between the ground plane and the conductor strip, two cells inside from the open edge of the antenna and five cells from the PML created the best traveling wave distribution, although, nearly all contiguous geometries of source cells performed adequately.

To isolate the forward traveling wave, the reflections from the free space boundaries at the ends of the substrate needed to be eliminated. This was accomplished by extending the substrate directly into the UPML, and modifying the affected UPML cells to match the substrate. The resulting grid space for the full width (FW) antenna is seen in Fig. 3. The UPML absorbs all outward propagating waves in the substrate allowing the forward traveling wave to develop exclusively.

Convergence of the extracted wavenumber was maintained while reducing the substrate thickness to only five cells and elongating the cells in the \hat{x} direction to a size of 3:1:1.

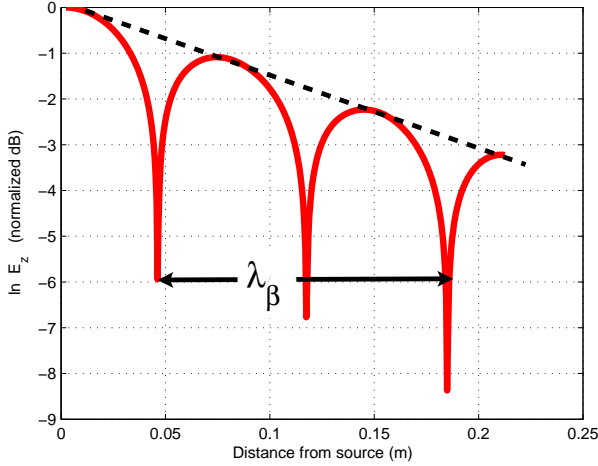


Fig. 4. The natural logarithm of the simulation data was used to determine the propagation constant.

Resolution within the structure was well over 100 cells per wavelength for all trials. The substrate modelled, Rogers Duroid 5870 high frequency laminate, has a loss tangent of only 0.0012. Neglecting this loss showed no noticeable effect on the extracted propagation constant. To further reduce memory demands of the largest simulations, single precision was used resulting in approximately 40% decrease in memory usage. These parameters allowed simulations to be accurately run on a personal computer with only 1 GB of RAM.

B. Determination of α and β

The objective of the FDTD simulations was to provide the propagation constant of the vertical component of the electric field E_z inside the substrate between the top conductor and the bottom ground plate. The E_z data was retrieved from a single row of cells stretching the length of the antenna in the \hat{x} direction. The logarithm of the normalized magnitude of the \hat{z} -directed electric field from these cells created a waveform from which α and β were extracted using:

$$\begin{aligned} E_z &= e^{(\alpha - j\beta)x} \\ \ln E_z &= \alpha x - j\beta x \end{aligned} \quad (1)$$

As shown in Fig. 4, α is the slope of the peaks of $\ln E_z$ (shown as a dotted line) and β is found from the separation of nulls using:

$$\beta = \frac{2\pi}{\lambda_\beta} \quad (2)$$

If the simulation is run long enough to ensure steady state (the traveling wave distribution has a constant wavelength), only $\lambda_\beta/2$ is needed for determination of the wavenumber.

C. Transverse resonance approximation

For comparison, a transverse resonance approximation was created following the work of Oliner and Lee [4], [21] which

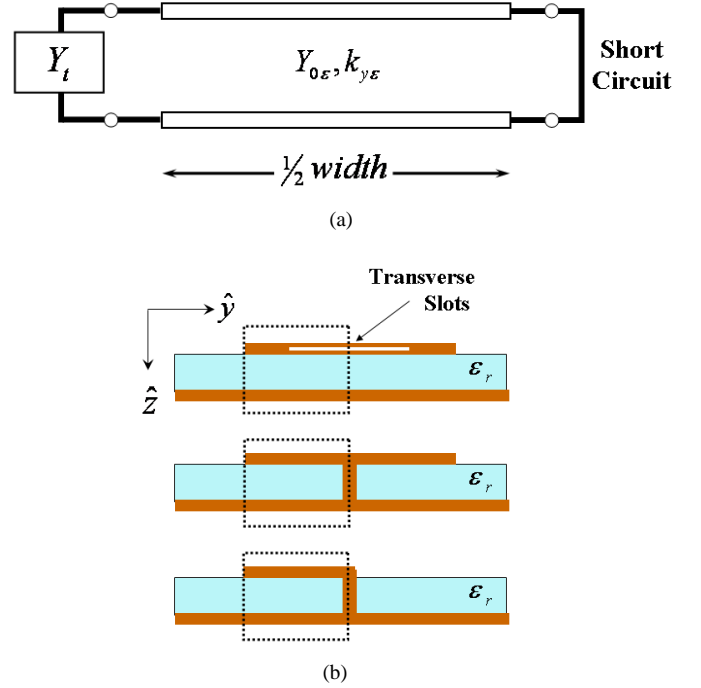


Fig. 5. (a) is a transmission line circuit that approximates the cross section of each of the three structures in (b) operating in mode EH_1 . The cross sections in (b) represent Menzel (top), FW (center), and HW (bottom).

they confirmed with a steepest descent contour analysis. Fig. 5 shows a transmission line model that is applicable to the cross section of the Menzel, FW, and HW antennas. Each structure can be modelled as a dielectric-filled parallel plate waveguide of admittance $Y_{0\epsilon}$ terminated at one end by a short circuit and the other end by admittance Y_t . The \mathbf{E} null generated in the EH_1 mode by a vertical wall or transverse slots is represented by a short circuit. Y_t is an approximation of the admittance of an open edge of microstrip developed by Chang and Kuester [22], [23] using the Weiner-Hopf technique to analyze a TEM wave that is completely reflected.

The transverse resonance relation:

$$\Gamma_{\text{right}}(y) \cdot \Gamma_{\text{left}}(y) = 1 \quad (3)$$

must hold for all points in the transverse \hat{y} direction.

The reflection coefficient Γ due to the admittance of the end of the microstrip Y_t is unity with a phase shift χ , as defined in [22], [23]. At a point $y = y_a$ just to the right of Y_t ,

$$\Gamma_{\text{right}}(y_a) = -e^{-j2k\frac{w}{2}} \quad (4)$$

$$\Gamma_{\text{left}}(y_a) = e^{j\chi} \quad (5)$$

where $k = \beta - j\alpha$ is the complex wavenumber in the substrate and w is the width of the structure. Eq. (3) becomes:

$$\begin{aligned} -e^{-jk w} \cdot e^{j\chi} &= 1 \\ \chi - k w &= \pm n\pi \quad n = 1, 3, 5, \dots \end{aligned} \quad (6)$$

$n = 1$ for the EH_1 mode.

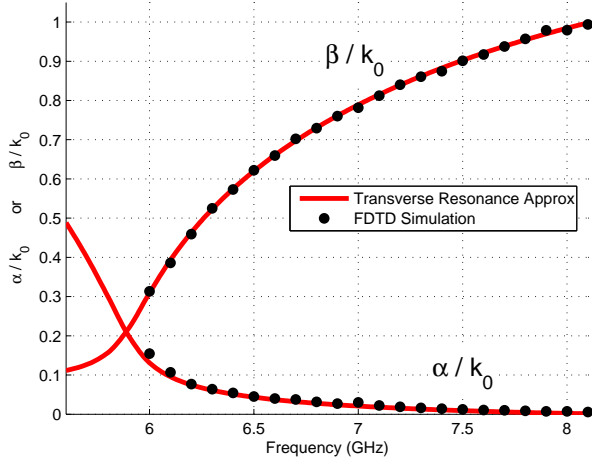


Fig. 6. The FDTD simulation of the HW is in agreement with the transverse resonance approximation.

Fig. 6 shows that the transverse resonance approximation is in agreement to within 1% of the FDTD-derived β data over the entire leaky band.

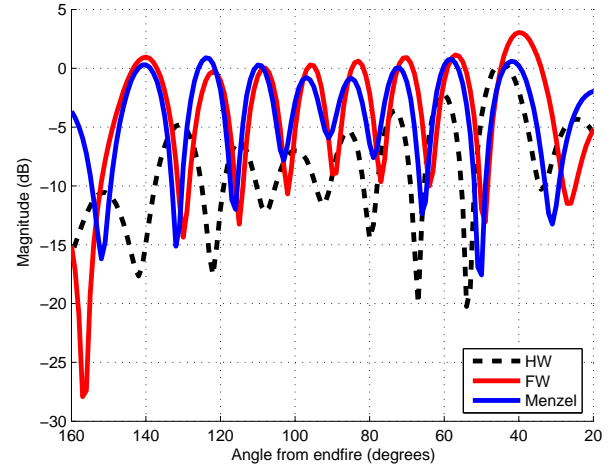
III. RESULTS

A. Similarities/Differences between HW, FW, Menzel

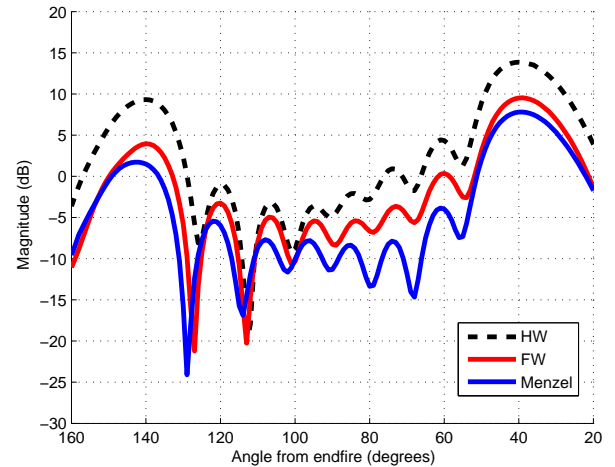
Generally our simulated and measured results showed the HW antenna to have advantages over the FW antenna and Menzel antenna. At most leaky-band frequencies, the Menzel configuration used here had noticeably larger cross-polarization (e.g. 10 dB at 6.2 GHz decreasing to 2 dB at 7.7 GHz) in the far-field as typified by the measurements in Fig. 7(a). This is due in part to radiation by the non-resonant slots used to suppress the fundamental mode in the Menzel configuration. The cross-pol energy from the Menzel slots leads to decreased co-pol gain measurements, as indicated in Fig. 7(b). The co-pol decrease of the Menzel configuration is typically on the order of 3 dB, although Fig. 7(b) shows an even greater reduction at 7.2 GHz. Further, the FDTD simulations show that the slots in the Menzel design are not as effective in keeping the fundamental mode suppressed as is the long wall in the FW and HW antennas.

The co-pol measurements showed the HW has a slightly different mainbeam location and an increased backlobe. This is due to an uncertainty in the HW fabricated model as to its effective width since the vias are of finite diameter and merely approximate a solid wall. The effective width significantly affects α and β [24]. Slightly reducing the width of the HW by 0.15 mm matched the α and β of the FW and Menzel antennas seen in Fig. 7(b).

Our simulated results confirmed that α and β of the FW and HW antennas were the same, as anticipated by image theory. Further, the FW antenna induced fields in the passive side that degraded the 180° phase difference across the width of the antenna [24]. This resulted in decreased radiation efficiency (i.e., reduced measured gain) for the FW antenna relative to a HW antenna with the same β , as evidenced in Fig. 7(b).



(a)



(b)

Fig. 7. (a) Cross-polarized and (b) Co-polarized measured far-field patterns of the HW, FW, and Menzel antennas at 7.2 GHz.

B. Limitations of the Transverse Resonance approximation

The transverse resonance model was useful to get a quick approximation; however, a new model would be needed for geometries other than those in Fig. 2. In addition, the Y_t approximation is not valid when the microstrip is curved or tapered.

Kuester, et al [23] state applicability to only *thin* substrates in which:

$$h \ll \frac{1}{\omega \sqrt{\epsilon\mu}} \quad (7)$$

For a substrate thickness $h = 787 \mu\text{m}$, Eq. (7) requires frequencies $\ll 40$ GHz, which is five times higher than the highest frequency of this leaky band. Fig. 8(a) shows that FDTD and transverse resonance begin to disagree as the height of the substrate increases past the *thin* criteria of Eq. (7), near $h = 1.1$ mm at 6.7 GHz.

C. Modifying dimensions to meet bandwidth specifications

The leaky bandwidth is defined by $\alpha = \beta$ at the lower end and $\beta = k_0$ at the upper end. Bandwidth around a desired center frequency f_c can be achieved by scaling the width of the conducting strip, the height (or thickness) of the substrate, and/or the permittivity of the substrate. The bandwidth can be increased, to a limited extent, by the selection of the substrate material. As a fraction of the center frequency, the percent bandwidth will be unaffected by altering the height and width, although f_c can be readily shifted. The choice of substrate material and thickness is usually dictated by cost or availability of material, therefore, the width is typically the parameter to manipulate.

Fig. 8(a) illustrates the relationship between the height, or thickness, of the substrate and the propagation constant. Like permittivity, the height of the substrate is usually dictated by the material available. All antennas simulated and fabricated for this work used material that was $787 \mu\text{m}$ thick. As mentioned in the previous section, the transverse resonance solution includes an approximation that limits its applicability to thin substrates. The difference in β between FDTD and transverse resonance becomes noticeable for heights greater than approximately 1.1 mm.

Fig. 8(b) shows that the propagation constant is very sensitive to the width of the conductor strip. As little as 0.1 mm difference in width will cause as much as 10% error in β . This sensitivity to width requires adequate fabrication precision.

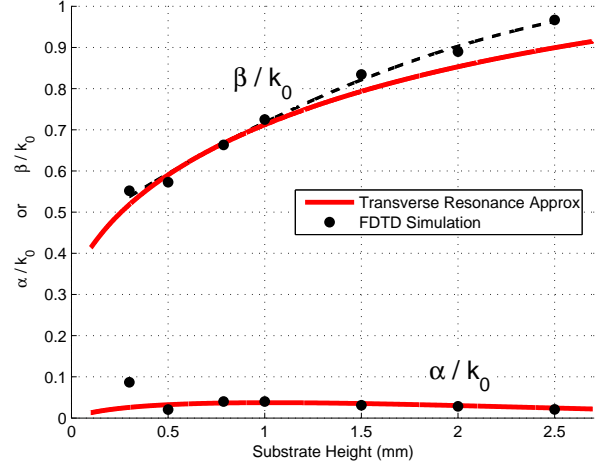
Fig. 8(c) illustrates the relationship between the relative permittivity of the substrate and the propagation constant. Fig. 9 shows the bandwidth as a function of substrate permittivity overlaid with common substrates. Bandwidth increases rapidly as the substrate dielectric constant nears that of free space. Fig. 10 shows the drawback of lower dielectric constant substrate is a very low α across most of the leaky band. Low α results in little energy radiating per unit length.

The leaky frequency band can be scaled up or down by scaling the width and height inversely while using the same permittivity. For example, Table I shows the effect on frequency by halving the height and width. While the bandwidth appears to double, the effective bandwidth remains the same percentage of the center frequency f_c .

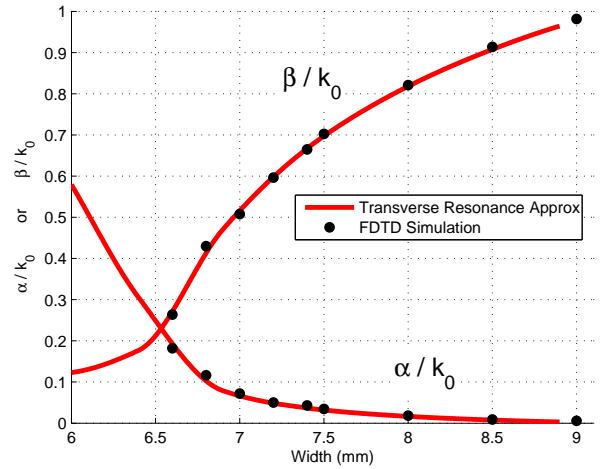
TABLE I
SCALING THE FREQUENCY BY A FACTOR OF TWO.

Bandwidth	2.4 GHz	4.8 GHz
f_c	7.08 GHz	14.16 GHz
w	15 mm	7.5 mm
h	$787 \mu\text{m}$	$393.5 \mu\text{m}$
ϵ_r	2.33	2.33

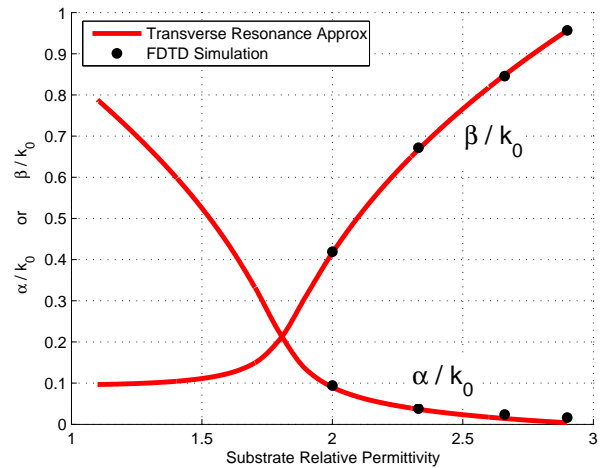
Frequency scaling does not prove useful for reduction of the FDTD simulation since cross section ratio of height to width is unchanged. However, this property could be useful to shrink the antenna to meet measurement facility size constraints. Conversely, fabrication may be made easier by increasing the size of the antenna.



(a)



(b)



(c)

Fig. 8. The parameters of the HW antenna are $h = 787 \mu\text{m}$, $\epsilon_r = 2.33$, and $w = 7.5 \text{ mm}$. Shown are the effects at 6.7 GHz of varying the (a) height, (b) conductor width, and (c) permittivity with the other parameters unchanged. The dashed line in (a) is a quadratic least square of the FDTD data points.

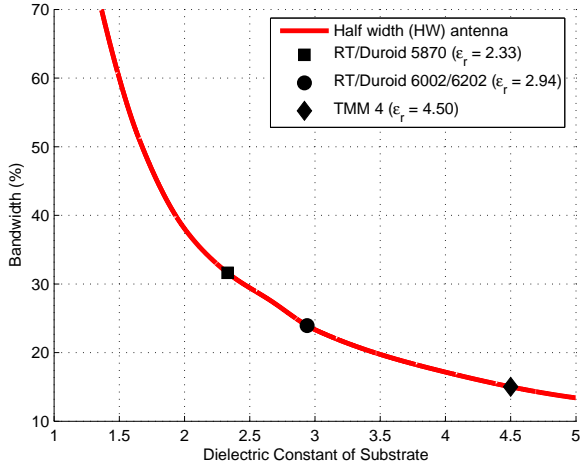


Fig. 9. The bandwidth as a function of substrate permittivity for the HW antenna ($h = 0.787$ mm; $w = 7.5$ mm.) Three common, commercially-available substrates are overlaid

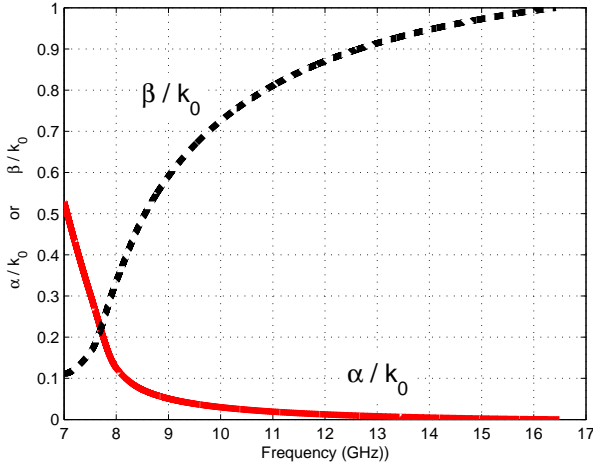


Fig. 10. The normalized α and β curves in the leaky band for the HW antenna using substrate with $\epsilon_r=1.33$ ($h = 0.787$ mm; $w = 7.5$ mm.)

D. Effect of curvature on α and β

Shown in Fig. 11 is a curved HW antenna with its wall along the inside edge. Simulations were done at radii of 3.36, 4.23, 5.32, and 9.3 cm. 180° was simulated when possible. Only 90° was simulated for the largest simulation due to availability of computing resources. The size of the computational domain of all curved simulations necessitated only single precision. The cell size 1.5:1.5:1 was used for all curved HW trials. Not enough information is available to extract the wavenumber for frequencies whose λ_β is greater than twice the length of the arc. The curvature trials are summarized in Table II. Fig. 12 shows that curvature increases bandwidth by flattening β , predominantly for the lower frequencies, while keeping α relatively unaffected. As the radius of curvature decreases, the bandwidth increases.

Curvature with the wall on the outside hampers the ability of the antenna to set-up only the EH_1 mode. As seen in Fig. 13,

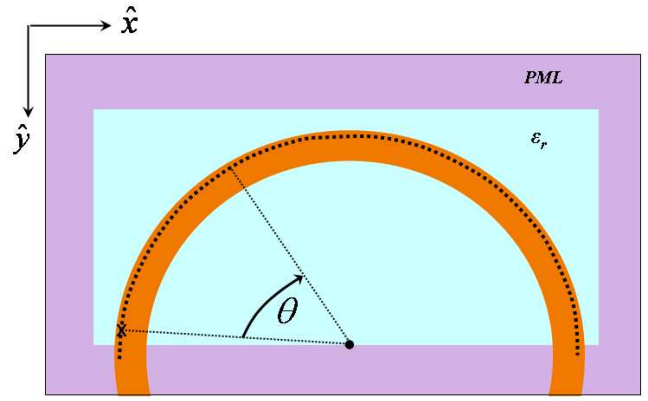


Fig. 11. The 180° curve simulated with the wall on the inside of the curve. The source cell is marked by the X in the lower left of the figure. The guided traveling wave was extracted from the cells marked by the dotted line along the open edge using angular position θ with respect to the source cell.

TABLE II
SUMMARY OF CURVATURE TRIALS.

	180°	180°	180°	90°	straight
Radius(cm)	3.36	4.23	5.32	9.3	∞
Arc length (cm)	10.6	13.3	16.7	14.6	N/A
Largest λ_β possible (cm)	21.2	26.6	33.4	29.2	N/A
Lowest f possible (GHz)	6.2	6.1	6.0	6.1	N/A
Approx Bandwidth (GHz)	2.8	2.7	2.6	2.5	2.3

a 180° arc of radius 4.23 cm produces destructive interference indicating the presence of one or more other modes.

E. Effect of multiple elements on α and β

The main beam of a traveling wave antenna is frequency steerable in the longitudinal direction from near endfire to near broadside. A linear array of HW elements is able to scan in two dimensions. A first step to developing such an array is to determine the effect of spacing between neighboring elements. Two elements were simulated next to each other at 7.2 GHz. The results were nearly identical regardless of whether the second element was excited or not. The impact on the propagation constant by a neighboring element is shown in Fig. 14. There is minimal interaction between elements if they are separated by at least 0.25λ and virtually no interaction if the spacing is over 0.4λ .

IV. CONCLUSION

A three dimensional FDTD simulation was constructed to simulate various leaky wave microstrip antennas. FDTD was shown to be able to extract the complex guided wavenumber, which is useful in predicting antenna performance measures such as bandwidth, beamwidth, and main beam direction. The antenna geometry was easily manipulated in FDTD to meet various testing requirements of different structures. Several means were found to decrease the number of cells required to accurately simulate the antennas allowing elaborate simulations with only a standard desktop PC with 1 GB of memory. High performance computing resources, which are typically required for such modelling, were not used.

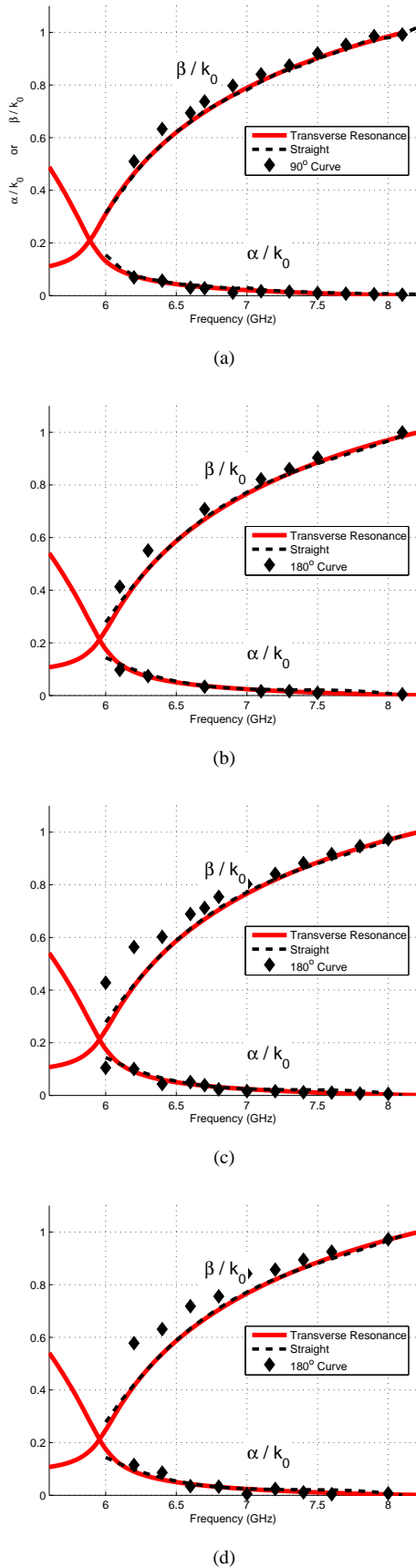


Fig. 12. The curved HW antenna with a radius of (a) 93 mm, (b) 53 mm, (c) 42 mm, and (d) 34 mm. For comparison, the single precision *curved* data is plotted alongside the single precision *straight* data.

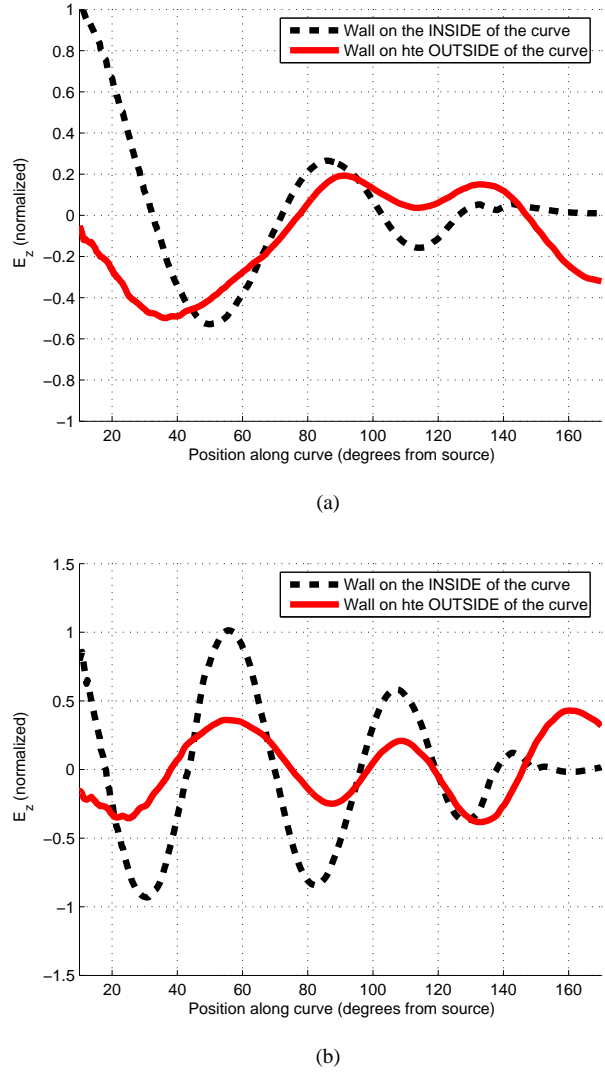


Fig. 13. Curvature with the wall on the *outside* produces field distributions, seen here at (a) 6.4 GHz and (b) 7.4 GHz, that suggest the presence of multiple modes.

The HW antenna was shown to be an improvement over both the FW antenna as well as the Menzel antenna. The propagation constant of the HW antenna behaved equivalently to the FW antenna as anticipated by image theory. In addition, the non-excited side of the FW antenna was shown to degrade the 180° phase difference across the structure's width thereby decreasing the radiation efficiency. The vertical wall of the HW antenna was found to be more capable of blocking the fundamental mode than the slots in the antenna developed by Menzel.

Two HW antenna elements were excited in close proximity to test mutual interaction. No effect to the propagation constant of elements was observed if the spacing distance was greater than 0.4λ . This lack of mutual coupling will simplify array designs.

The effect of curvature on the complex propagation constant of the HW antenna was investigated. As a function of curvature, no significant impact to α was noticed, however, the β plot showed significant flattening, particularly at lower

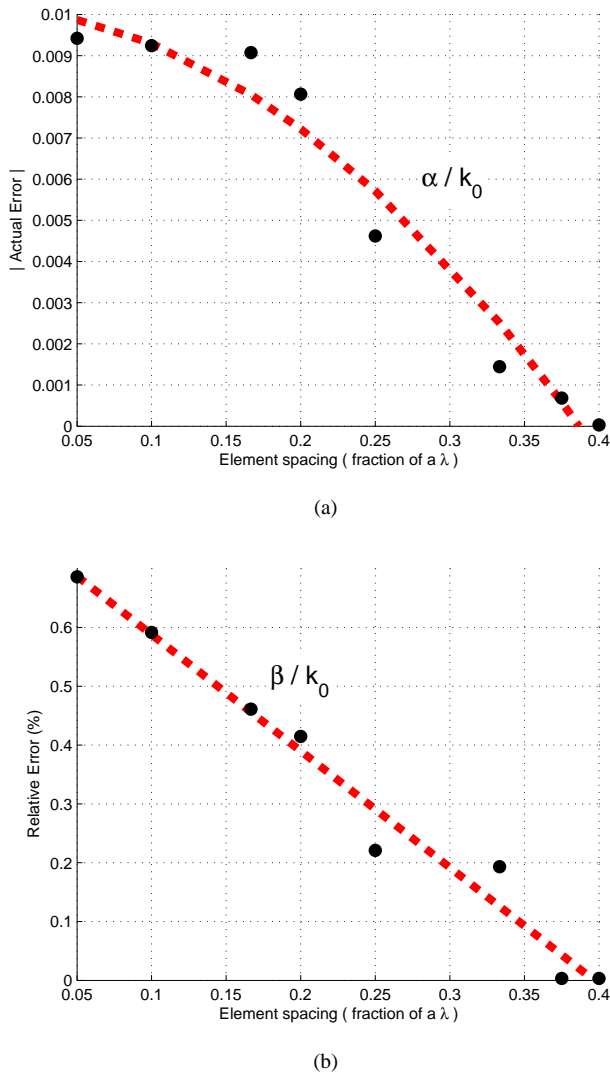


Fig. 14. (a) Actual error of $|\alpha|$ (dashed line is quadratic least square) and (b) relative error of β (dashed line is linear least square) from placing another element a fraction of a wavelength from the open end of the antenna. For both figures, the error is with respect to the guided wavenumber of a single element.

frequencies. Flattening β without affecting α results in a bandwidth increase.

The bandwidth of the HW antenna can be increased by using a lower permittivity dielectric constant; however, a commercially available substrate could not be found lower than 2.2. Lowering the dielectric constant has the drawback of a very low α across much of the leaky band, which hinders the antenna's ability to efficiently radiate. Varying the width of the conducting strip or the height of the substrate were found to move the center frequency but did not change the bandwidth as a percentage of center frequency. The width and height can be varied together to scale the center frequency.

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