AD NO. _____
DTC PROJECT NO. 8-CO-160-UXO-021
REPORT NO. ATC-9004

STANDARDIZED

UXO TECHNOLOGY DEMONSTRATION SITE

MOGULS SCORING RECORD NO. 547

SITE LOCATION:
U.S. ARMY ABERDEEN PROVING GROUND

DEMONSTRATOR:
G-TEK AUSTRALIA PTY LIMITED
3/10 HUDSON ROAD
ALBION QLD 4010 AUSTRALIA

TECHNOLOGY TYPE/PLATFORM:
MAGNETOMETER TM-4/SLING

PREPARED BY:
U.S. ARMY ABERDEEN TEST CENTER
ABERDEEN PROVING GROUND, MD 21005-5059

JUNE 2005

Prepared for:
U.S. ARMY ENVIRONMENTAL CENTER
ABERDEEN PROVING GROUND, MD 21010-5401

U.S. ARMY DEVELOPMENTAL TEST COMMAND
ABERDEEN PROVING GROUND, MD 21005-5055

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Overbay, Larry; Robitaille, George
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Commander
U.S. Army Aberdeen Test Center
ATTN: CSTE-STC-ATC-SL-E
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Commander
U.S. Army Environmental Center
ATTN: SFIM-AEC-ATT
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14. ABSTRACT
This scoring record documents the efforts of G-TEK Australia Pty Limited to detect and discriminate inert unexploded ordnance (UXO) utilizing the APG Standardized UXO Technology Demonstration Site Moguls. The scoring record was coordinated by Larry Overbay and the Standardized UXO Technology Demonstration Site Scoring Committee. Organizations on the committee include the U.S. Army Corps of Engineers, the Environmental Security Technology Certification Program, the Strategic Environmental Research and Development Program, the Institute for Defense Analysis, the U.S. Army Environmental Center, and the U.S. Army Aberdeen Test Center.

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Authors:

Larry Overbay Jr.
Matthew Boutin
Military Environmental Technology Demonstration Center (METDC)
U.S. Army Aberdeen Test Center (ATC)
U.S. Army Aberdeen Proving Ground (APG)

Rick Fling
Christina McClung
Aberdeen Test and Support Services (ATSS)
Sverdrup Technology, Inc.
U.S. Army Aberdeen Proving Ground (APG)

Contributor:

George Robitaille
U.S. Army Environmental Center (AEC)
U.S. Army Aberdeen Proving Ground (APG)

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SECTION 1. GENERAL INFORMATION

1.1 BACKGROUND

Technologies under development for the detection and discrimination of unexploded ordnance (UXO) require testing so that their performance can be characterized. To that end, Standardized Test Sites have been developed at Aberdeen Proving Ground (APG), Maryland and U.S. Army Yuma Proving Ground (YPG), Arizona. These test sites provide a diversity of geology, climate, terrain, and weather as well as diversity in ordnance and clutter. Testing at these sites is independently administered and analyzed by the government for the purposes of characterizing technologies, tracking performance with system development, comparing performance of different systems, and comparing performance in different environments.

The Standardized UXO Technology Demonstration Site Program is a multi-agency program spearheaded by the U.S. Army Environmental Center (AEC). The U.S. Army Aberdeen Test Center (ATC) and the U.S. Army Corps of Engineers Engineering Research and Development Center (ERDC) provide programmatic support. The program is being funded and supported by the Environmental Security Technology Certification Program (ESTCP), the Strategic Environmental Research and Development Program (SERDP) and the Army Environmental Quality Technology Program (EQT).

1.2 SCORING OBJECTIVES

The objective in the Standardized UXO Technology Demonstration Site Program is to evaluate the detection and discrimination capabilities of a given technology under various field and soil conditions. Inert munitions and clutter items are positioned in various orientations and depths in the ground.

The evaluation objectives are as follows:

a. To determine detection and discrimination effectiveness under realistic scenarios that vary targets, geology, clutter, topography, and vegetation.

b. To determine cost, time, and manpower requirements to operate the technology.

c. To determine demonstrator's ability to analyze survey data in a timely manner and provide prioritized "Target Lists" with associated confidence levels.

d. To provide independent site management to enable the collection of high quality, ground-truth, geo-referenced data for post-demonstration analysis.

1.2.1 Scoring Methodology

a. The scoring of the demonstrator's performance is conducted in two stages. These two stages are termed the RESPONSE STAGE and DISCRIMINATION STAGE. For both stages, the probability of detection (P_d) and the false alarms are reported as receiver-operating

characteristic (ROC) curves. False alarms are divided into those anomalies that correspond to emplaced clutter items, measuring the probability of false positive (P_{fp}), and those that do not correspond to any known item, termed background alarms.

b. The RESPONSE STAGE scoring evaluates the ability of the system to detect emplaced targets without regard to ability to discriminate ordnance from other anomalies. For the blind grid RESPONSE STAGE, the demonstrator provides the scoring committee with a target response from each and every grid square along with a noise level below which target responses are deemed insufficient to warrant further investigation. This list is generated with minimal processing and, since a value is provided for every grid square, will include signals both above and below the system noise level.

c. The DISCRIMINATION STAGE evaluates the demonstrator's ability to correctly identify ordnance as such and to reject clutter. For the blind grid DISCRIMINATION STAGE, the demonstrator provides the scoring committee with the output of the algorithms applied in the discrimination-stage processing for each grid square. The values in this list are prioritized based on the demonstrator's determination that a grid square is likely to contain ordnance. Thus, higher output values are indicative of higher confidence that an ordnance item is present at the specified location. For digital signal processing, priority ranking is based on algorithm output. For other discrimination approaches, priority ranking is based on human (subjective) judgment. The demonstrator also specifies the threshold in the prioritized ranking that provides optimum performance, (i.e. that is expected to retain all detected ordnance and rejects the maximum amount of clutter).

d. The demonstrator is also scored on EFFICIENCY and REJECTION RATIO, which measures the effectiveness of the discrimination stage processing. The goal of discrimination is to retain the greatest number of ordnance detections from the anomaly list, while rejecting the maximum number of anomalies arising from non-ordnance items. EFFICIENCY measures the fraction of detected ordnance retained after discrimination, while the REJECTION RATIO measures the fraction of false alarms rejected. Both measures are defined relative to performance at the demonstrator-supplied level below which all responses are considered noise, i.e., the maximum ordnance detectable by the sensor and its accompanying false positive rate or background alarm rate.

e. Based on configuration of the ground truth at the standardized sites and the defined scoring methodology, there exists the possibility of having anomalies within overlapping halos and/or multiple anomalies within halos. In these cases, the following scoring logic is implemented:

(1) In situations where multiple anomalies exist within a single R_{halo}, the anomaly with the strongest response or highest ranking will be assigned to that particular ground truth item.

(2) For overlapping R_{halo} situations, ordnance has precedence over clutter. The anomaly with the strongest response or highest ranking that is closest to the center of a particular ground truth item gets assigned to that item. Remaining anomalies are retained until all matching is complete.

(3) Anomalies located within any R_{halo} that do not get associated with a particular ground truth item are thrown out and are not considered in the analysis.

f. All scoring factors are generated utilizing the Standardized UXO Probability and Plot Program, version 3.1.1.

1.2.2 Scoring Factors

Factors to be measured and evaluated as part of this demonstration include:

a. Response Stage ROC curves:

(1) Probability of Detection (P_d^{res}).

(2) Probability of False Positive (P_{fp}^{res}).

(3) Background Alarm Rate (BAR^{res}) or Probability of Background Alarm (P_{BA}^{res}).

b. Discrimination Stage ROC curves:

(1) Probability of Detection (P_d^{disc}).

(2) Probability of False Positive (P_{fp}^{disc}).

(3) Background Alarm Rate (BAR^{disc}) or Probability of Background Alarm (P_{BA}^{disc}).

c. Metrics:

(1) Efficiency (E).

(2) False Positive Rejection Rate (R_{fp}).

(3) Background Alarm Rejection Rate (R_{BA}).

d. Other:

(1) Probability of Detection by Size and Depth.

(2) Classification by type (i.e., 20-, 40-, 105-mm, etc.).

(3) Location accuracy.

(4) Equipment setup, calibration time and corresponding man-hour requirements.

(5) Survey time and corresponding man-hour requirements.

(6) Reacquisition/resurvey time and man-hour requirements (if any).

(7) Downtime due to system malfunctions and maintenance requirements.

1.3 STANDARD AND NONSTANDARD INERT ORDNANCE TARGETS

The standard and nonstandard ordnance items emplaced in the test areas are listed in Table 1. Standardized targets are members of a set of specific ordnance items that have identical properties to all other items in the set (caliber, configuration, size, weight, aspect ratio, material, filler, magnetic remanence, and nomenclature). Nonstandard targets are inert ordnance items having properties that differ from those in the set of standardized targets.

TABLE 1. INERT ORDNANCE TARGETS

Standard Type	Nonstandard (NS)
20-mm Projectile M55	20-mm Projectile M55
	20-mm Projectile M97
40-mm Grenades M385	40-mm Grenades M385
40-mm Projectile MKII Bodies	40-mm Projectile M813
BDU-28 Submunition	
BLU-26 Submunition	
M42 Submunition	
57-mm Projectile APC M86	
60-mm Mortar M49A3	60-mm Mortar (JPG)
	60-mm Mortar M49
2.75-inch Rocket M230	2.75-inch Rocket M230
	2.75-inch Rocket XM229
MK 118 ROCKEYE	
81-mm Mortar M374	81-mm Mortar (JPG)
	81-mm Mortar M374
105-mm HEAT Rounds M456	
105-mm Projectile M60	105-mm Projectile M60
155-mm Projectile M483A1	155-mm Projectile M483A
	500-lb Bomb

JPG = Jefferson Proving Ground
HEAT = high-explosive antitank

SECTION 2. DEMONSTRATION

2.1 DEMONSTRATOR INFORMATION

2.1.1 Demonstrator Point of Contact (POC) and Address

POC: Peter Clark
011 61 7 3862 2588
pclark@g-tek.biz

Address: G-TEK Australia PTY Limited
3/10 Hudson Road
ALBION QLD 4010 Australia

2.1.2 System Description (provided by demonstrator)

Sensor System Description.

The hand-held TM-4 magnetometer system consisting of the following components:

Item	Manufacturer	Model
Magnetometer Control Module	G-TEK	TM-4
Cs Vapor type TMI Sensors	Geometrics	G822AS
Base-station magnetometer	G-TEK	TM-4
Digital Global Positioning System (DGPS)	NovAtel	Rt-2/OEM-4
Odometer	G-TEK	TM-4D

The TM-4 is a self-contained magnetometer system, which may be configured with up to four optically pumped magnetic sensors each recording the total magnetic field intensity in units of nT to a resolution of 0.01 nT. These sensors will be mounted in an array oriented perpendicular to the survey direction permitting up to four sensor transects to be recorded simultaneously in the open terrain with high survey productivity. The proposed sensor separation is 300 mm and ground clearance 250 mm. The measurement rate from each sensor is selectable from nominally 50 per second at 0.003 nT resolution to 400 per second at 0.08 nT. The high measurement rate permits effective real-time filtering of 50/60 Hz electromagnetic interference prior to recording position or time-based measurements at intervals appropriate to the application (in this case 50 mm or 10 Hz). The TM-4 interfaces with both industry standard real-time kinematic (RTK) DGPS and proprietary cotton thread based odometer systems. This provides versatile time or position-based positioning that is adaptable to varied terrain and vegetation conditions. A key attribute of the TM-4 is the operating system software that provides a continuous set of data quality monitors reducing the need to resurvey and improving data quality. In particular there are audio and graphic displays and alarms monitoring sensor signal quality, position data quality and navigation aids.

A two-person crew operates the TM-4 system (fig.1). One-person carries the sensor array to which is attached the DGPS antenna and odometer system. This array measures 1500 mm length by the array width, which in this case will be 900 mm. The quad-sensor array weighs 10 kg. The second person operates the navigation and data acquisition hardware carried in a backpack with batteries. This backpack measures 600 by 400 by 250 mm and weighs approximately 12 kg. The user interface is a hand-held personal computer (PC). A 5-meter cable eliminating interference at the sensors from the other hardware separates the two operators. There are no specific safety hazards identified with the use of this equipment.

Figure 1. Demonstrator's system, TM-4 magnetic data acquisition system.

Data processing consists of magnetic base-station subtraction, optional band-pass spatial filtering to enhance particular source depths, grading and imaging. Interpretation of picked anomalies involves classification (by type) and ranking (by probability UXO) using model inversion involving both magnetic remanence and the use of a database of anticipated UXO types. Products are data images and dig sheets conforming to DID OE-005-05.02 standards.

The TM-4 has been used with the G-TEK odometer system by industry and the Australian Department of Defense operators for over 14 years and with DGPS for over 7 years. The odometer remains the positioning technology of choice in adverse terrains (such as wooded scenarios), DGPS is preferred in open environments. Combined, they meet the requirements of most situations.

Positioning System Description:

G-TEK propose using a combination of the following survey/navigation technologies:

Item	Manufacturer	Model
DGPS	NovAtel	RT-2/OEM-4
Odometer	G-TEK	TM-4D
Polychain	PEKO	100M
Siters	Various	Generic traffic cones. Wooden Dowels and flagging

The TM-4 magnetometer system interfaces with both industry standard RTK DGPS and proprietary cotton thread based odometer systems providing versatile time or position-based positioning that is adaptable to varied terrain and vegetation conditions. In both cases, where an UXO detection standard of survey coverage is required, G-TEK operators use a pre-established control grid and visual sighters for straight-line navigation, and use the DGPS or odometer primarily for data positioning.

Using DGPS in the Open Area:

DGPS is the technology of choice in situations where satellite coverage is reliable. In this case, any of the industry standard RTK systems may be used although in this program we propose using the NovAtel RT-2 system (Ashtech Z-Extreme as a backup). Our preference is to establish a Global Positioning System (GPS) base-station on a monument that is within 1 km of the survey area and to use a radio link to the roving GPS receiver. In the roving instrumentation, sensor data is time tagged with GPS time and transformed DGPS positions (and the raw National Maritime Electronics Association (NMEA) GPS data for backup) are recorded. In this way, sensor data is positioned in post processing to achieve position accuracy better than 5 cm. Prior to commencing survey, the roving GPS is located at a known reference to confirm the integrity of the system and transformations used.

Using the Odometer in the Wooded Area:

The control grid setup will combine the use of DGPS and traditional survey techniques. Navigation will be done the same as described above. However, 5 meters before the commencement of each new transect, the cotton thread is tied to either vegetation or a small peg anchored to the ground. When each control line is reached, a distance mark is recorded in the TM-4 prior to moving the cone. At the completion of each survey grid section the cotton is gathered and removed from the site. In post-processing, linear error distribution delivers positional accuracy that is typically less than 0.1 percent of the distance between control lines (0.1 percent of 25 m delivers 25 mm accuracy in this case.) Because the odometer is used in more adverse terrain including forests, protocols have been developed using the electronic notepad facility of the TM-4 for recording the location of obstacles (e.g., trees) and the direction taken around these. Thus if a UXO is detected close to such a tree, the validation team will know which side of the tree to search. Experience over many years surveying in forested

conditions has indicated that an RMS target position error of less than 300 mm can be anticipated with the greatest errors occurring where obstacles are circumvented. These errors are not cumulative and are comparable with the interpreted target position errors achieved using DGPS.

2.1.3 Data Processing Description (provided by demonstrator)

Data Processing:

The data will be processed in the following sequence (the software used at each step is noted in square brackets):

Data Acquisition:

a. The output from up to four sensors of magnetometer data will be recorded at 10 Hz in GPS mode and 5 cm in cotton odometer distance-mode G-TEK's TM-4 magnetometer acquisition software.

b. The magnetometer data will be precisely time-tagged with reference to the connected GPS, at 1 Hz.

c. The GPS positions and GPS quality information will be logged at no less than 1 Hz in the required coordinate system. Extraneous position data will be either automatically or manually flagged as "not required". Raw untransformed GPS NMEA standard strings will also be logged as backup [G-TEK's SurvNav].

d. In cotton odometer mode the precise vertices of the survey boundary and control lines are measured with the RTK-DGPS and entered into the magnetometer. The operator will be responsible for hitting the start and stop button for each line [G-TEK's TM-4 magnetometer acquisition software].

e. A magnetometer base-station will record time tagged, stationary, temporal variations at 10 Hz.

f. All data will be transferred from the field devices to the processing computer and a "Field Data Sheet" completed by each crew leader ("Attachment A, DID OE-005-05.01").

g. The GPS data will automatically be assigned unique line-numbers during the data acquisition. The data will be indexed by these line-numbers during the line-based post-processing (i.e., up to the grading stage). Extraneous data will be automatically and manually flagged as "not required" [G-TEK's SurvNav].

Post-Processing by the Processing Geophysicist:

a. The GPS track will be checked, edited and smoothed as required [GEOSOFT]. For cotton positioning the distance recorded by the precise electronic odometer will be compared to the expected known length of each line. Variations exceeding a certain tolerance will trigger the issue of a "Line-ReDo" order to the field crew leader [G-TEK's Distance-Based Processing Software].

b. At this stage the positions of individual sensors will be calculated from the precisely measured sensor-GPS antennae offsets and the instantaneous track direction of the array. These individual sensor track positions will be referenced as sub-lines 1 to 4. In distance-mode this stage is automated [G-TEK's Preprocessing software].

c. The GPS, rover magnetometer and base magnetometer data will be merged on the 10-z time-base during post-processing and corrections will be then applied [GEOSOFT]. In distance-mode just the magnetometer and base-station data are merged, positioned and corrected.

d. The magnetometer data will be automatically and manually scanned for the removal of invalid data [GEOSOFT].

e. At this stage the raw data will be exported to GEOSOFT ASCII XYZ format (with line reference headers and column labels) complying with the Raw Data Submittal guidelines on the "Standardized UXO Technology Demonstration Site - Submission for Scoring" web site. The data will then be written to compact disk (CD) for submission [GEOSOFT].

f. The data will then be re-sampled to a distance-base of no greater than 0.05 meter to facilitate band-pass filtering to reduce effects from wavelengths determined to be inconsistent with the target anomalies (e.g., deep geology, system noise) [G-TEK's GEOSOFT GXs].

g. The data will then be graded to a square mesh no greater than 0.05 meter, using minimum curvature grading and using the GEOSOFT "FLOAT" grid format [GEOSOFT].

h. The graded data will then be loaded into the viewing and interpretation software for semi-automated interpretation. This process involves the automatic selection of associated maximums and minimums whose amplitudes exceed the interpretation threshold. These are then manually checked. The selected anomalies are then inverted against a list of target items to find the best fit and the degree of magnetic remanence required. Use will be made of the ground-truth data from the Calibration Lane to fine-tune the discrimination parameters. This will then provide the basis for the discrimination classification and prioritization in the submittal [G-TEK's MagSys software].

i. The information from the selected anomalies ("Processed Data") will then be imported into a Microsoft (MS)-Excel spreadsheet for formatting for presentation as a dig sheet based on the template "Attachment C, DID OE-005-05.01" and written to CD for submittal [G-TEK's EOD Reporter MS Excel macro].

j. The dig sheet data ("Processed Data") will also be reformatted to comply with the Processed Data Submittal guidelines on the "Standardized UXO Technology Demonstration Site - Submission for Scoring" web site. The data will then be written to CD for submission [MS EXCEL].

k. The color contour, processed magnetic grid-image, with selected anomalies marked will be presented based on the map template "Attachment D, DID OE-005-05.01" also on CD [GEOSOFT].

Discrimination:

The discrimination will be performed using G-TEK's MagSys display, interpretation and discrimination software. This tool enables the selected anomalies to be inverted to a series of spheroids representing UXO and cluster items know to exist at this site. A user selectable amount of remanence will be permitted into inversion parameters. The dipole moment direction, and strength will also be listed for each item. These discrimination parameters will then be fine-tuned using the Calibration Lane data.

2.1.4 Data Submission Format

Data were submitted for scoring in accordance with data submission protocols outlined in the Standardized UXO Technology Demonstration Site Handbook. These submitted data are not included in this report in order to protect ground truth information.

2.1.5 Demonstrator Quality Assurance (QA) and Quality Control (QC) (provided by demonstrator)

Quality Control. G-TEK will perform QC steps and tests using the DID OE_005.05.02 using the following QC frequency:

Test Description	Power on	Day start	Day start/end	First day	Repeat last 2 grid lines
Equipment warm-up	5-min.				
Record sensor offsets		X			
Personnel test		X			
Vibration test		X			
Static and spike test			3 min/1 min/3 min		
Six line test				X	
Repeat line test					X
Visit survey point			X		

Equipment/Electronics warm-up for 5 minutes: This allows for thermal stabilization of electronics.

Record Relative Sensor Position (1 cm accuracy): Document relative navigation and sensor offsets, detector separation, and detector heights above the ground surface.

Personnel Test (10 emu at 10 cm from the sensors): To ensure survey personnel have removed all potential metallic interference sources from their bodies.

Shake Test (<10 emu at 10 cm from the sensor): To identify and replace shorting cables and broken pin-outs on connectors, with the instrument held in a static position and collecting data, cables are shaken to test for shorts and broken pin-outs. Repaired or replaced cables are rigorously retested before use.

Static Background and Static Standard Response (Spike) Test (10 emu): To quantify instrument background readings, electronic drift, locate potential interference spikes, and determine impulse response and repeatability of the instrument to a standard test item. Review in real-time.

Six Line Test (Repeatability of Response Amplitude ±20 percent, Positional Accuracy ±20 cm): To document latency, heading effects, repeatability of response amplitude, and positional accuracy. The test line will be well marked to facilitate data collection over the exact same line each time the test is performed. Background response over the test line is established in Lines 1 and 2. A standard test item, such as a steel trailer hitch ball, will be used for Lines 3 through 6.

Visit Survey Point (±25 mm): Check that GPS base location and transformations are correct.

Repeat Last Two Lines of Each Grid (Repeatability of Response Amplitude ±20 percent, Positional Accuracy +/-20 cm): To determine positional and geophysical data repeatability.

TM-4 MAG Calibration (>250 emu): By the use of calibration device known as an "EMUlator" (developed by G-TEK for the purpose of establishing the integrity of the TM-4 MAG) the EMUlator is placed touching the rim of the sensor coil and data is recorded for a period of 60 seconds. The EMUlator delivers a controlled response to the excitation transmitted by the TM-4 MAG.

Sensor Elevation: The TM-4 MAG will be operated at a low but uniform elevation. To help the operator achieve the elevation, a piece of non-conductive tape will be attached to the back of the coil such that it hangs 10 cm. The operator then maintains the end of the tape just touching the ground (or where he judges the ground to be below the grass cover). Higher elevations due to vegetation will be noted.

Data Processing: The data processing and interpretations will be checked by a second geophysicist, and all intermediate processing stages of the data will be retained in meaningfully named columns within GEOSOFT for this purpose. All data will be backed up daily.

Quality Assurance (QA). The data collected during the pre-survey QC checks will be processed, documented and checked by the Data Processing Geophysicist to assure that the entire system will provide the quality to achieve the desired outcome of detecting and correctly discriminating the UXO items down to their specified depths as determined by the site conditions.

- The RT-DGPS systems have a quoted accuracy of 2.0 cm + 0.1 mm/(km to the base-station) Central Error Probability (CEP) in dynamic mode. In practice, however, assuming a consistent differential correction of 1 per second and a baseline less than 2 km the worst-case absolute accuracy will be +5.0 cm with a typical accuracy of +2.5 cm. Synchronization errors between the EM detector and the GPS will be reduced by calibration down to the resolution of the sampling rate of 0.03 second. In sloping terrain there will be an additional error when the GPS antennae pole varies from the vertical.

- In the forested areas the use of an electronic cotton odometer system to track the sensors' positions along the line will be used. This system has an inherent along-line accuracy of <1 percent and a resolution of 5 cm. However, when the start and the end positions are known, this error is reduced to <0.2 percent of the distance between known points. In this case we propose to have control lines at no greater than 25 m intervals. That is an accuracy of +5 cm.

Estimated Accuracy of the Navigation System: The primary navigation method will be the use of accurately placed sighters along the control lines. The operators must then keep at least two sighters in line with the center point of the sensor array. This navigation technique will be used with both the cotton and the GPS positions tracking systems. The advantage of this system is its simplicity and applicability to difficult situations. The accuracy of this system depends on the accuracy of the pegged grid and the diligence of the operators. The anticipated typical across-line error is $\pm$10 cm. The effective swath width of the 2-sensor array will be 1.2 meter. The nominal lane space of 1.0 meter will allow for cross-line navigation variations.

QA of Positioning: The GEOSOFFT DoD UXO QA system will be used to report on "Line Coverage Comparisons." This report will allow the quantifications of the data positioning on a line basis. Lines that fail will trigger "Re-Do" orders to the field crew leaders.

QA of Sensor Data Quality: The quality of each sub-line of data will be quantified as the largest distance with consecutive invalid sensor data. If a sub-line fails the criteria then a "Re-Do" order will be triggered. The magnetometer base-station will be subjected to similar quality quantification and recording processes.

QA Based on a Two Traverse Resurvey: The sensor data and interpretation will be compared to the original and whole-system repeatability will be reported for quality assurance.

QA of Data Processing: During data processing the dates and times of the various data streams will be automatically correlated by the software. A second QC geophysicist will check the quality of the raw data, the selected processing parameters, interpretation parameters, and the final grid data. The data will then provide QA of the interpretation by checking each grid of the data for missed anomalies. Thee QC geophysicist can then add but not delete more anomalies. The QC geophysicist will then repeat the discrimination process on 10 percent of the anomalies and compare the results. The process will assure the quality of the final prioritized dig sheet results. The results will allow the generation of quantified assured depth of detection verse caliber graph.

2.1.6 Additional Records

The following record(s) by this vendor can be accessed via the Internet as MicroSoft Word documents at www.uxotestsites.org. The counterparts to this report are the Blind Grid, Scoring Record No. 268, the Open Field, Scoring Record No. 311, and the Woods, Scoring Record No. 454.

2.2 APG SITE INFORMATION

2.2.1 Location

The APG Standardized Test Site is located within a secured range area of the Aberdeen Area. The Aberdeen Area of APG is located approximately 30 miles northeast of Baltimore at the northern end of the Chesapeake Bay. The Standardized Test Site encompasses 17 acres of upland and lowland flats, woods and wetlands.

2.2.2 Soil Type

According to the soils survey conducted for the entire area of APG in 1998, the test site consists primarily of Elkton Series type soil (ref 2). The Elkton Series consist of very deep, slowly permeable, poorly drained soils. These soils formed in silty aeolin sediments and the underlying loamy alluvial and marine sediments. They are on upland and lowland flats and in depressions of the Mid-Atlantic Coastal Plain. Slopes range from 0 to 2 percent.

ERDC conducted a site-specific analysis in May of 2002 (ref 3). The results basically matched the soil survey mentioned above. Seventy percent of the samples taken were classified as silty loam. The majority (77 percent) of the soil samples had a measured water content between 15- and 30-percent with the water content decreasing slightly with depth.

For more details concerning the soil properties at the APG test site, go to www.uxotestsites.org on the web to view the entire soils description report.

2.2.3 Test Areas

A description of the test site areas at APG is included in Table 2.

TABLE 2. TEST SITE AREAS

Area	Description
Calibration Grid	Contains 14 standard ordnance items buried in six positions at various angles and depths to allow demonstrator to calibrate their equipment.
Blind Test Grid	Contains 400 grid cells in a 0.2-hectare (0.5 acre) site. The center of each grid cell contains ordnance, clutter or nothing.
Open Field	A 4-hectare (10-acre) site containing open areas, dips, ruts and obstructions that challenge platform systems or hand held detectors. The challenges include a gravel road, wet areas and trees. The vegetation height varies from 15 to 25 cm.
Moguls	A 1.30-acre area consisting of two areas (the rectangular or driving portion of the course and the triangular section with more difficult, non-drivable terrain). A series of craters (as deep as 0.91m) and mounds (as high as 0.91m) encompass this section.

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SECTION 3. FIELD DATA

3.1 DATE OF FIELD ACTIVITIES (23 and 24 October 2003)

3.2 AREAS TESTED/NUMBER OF HOURS

Areas tested and total number of hours operated at each site are summarized in Table 3.

TABLE 3. AREAS TESTED AND NUMBER OF HOURS

Area	Number of Hours
Calibration Lanes	0.92
Mogul	9.75

3.3 TEST CONDITIONS

3.3.1 Weather Conditions

An APG weather station located approximately one mile west of the test site was used to record average temperature and precipitation on a half hour basis for each day of operation. The temperatures listed in Table 4 represent the average temperature during field operations from 0700 to 1700 hours while precipitation data represents a daily total amount of rainfall. Hourly weather logs used to generate this summary are provided in Appendix B.

TABLE 4. TEMPERATURE/PRECIPITATION DATA SUMMARY

Date, 2003	Average Temperature, °F	Total Daily Precipitation, in.
October 23	44.38	0.00
October 24	49.45	0.01

3.3.2 Field Conditions

G-TEK surveyed the Mogul area with the Magnetometer array on 23-24 October 2003. The Mogul area was muddy due to rain events which occurred before and during testing.

3.3.3 Soil Moisture

Three soil probes were placed at various locations within the site to capture soil moisture data: Blind Grid, Calibration, Open Field, and Wooded areas. Measurements were collected in percent moisture and were taken twice daily (morning and afternoon) from five different soil depths (1 to 6 in., 6 to 12 in., 12 to 24 in., 24 to 36 in., and 36 to 48 in.) from each probe. Soil moisture logs are included in Appendix C.

3.4 FIELD ACTIVITIES

3.4.1 Setup/Mobilization

These activities included initial mobilization and daily equipment preparation and break down. A three-person crew took 5 hours and 10 minutes to perform the initial setup and mobilization. There was 3 hours and 15 minutes of daily equipment preparation and end of the day equipment break down lasted 1-hour and 5 minutes.

3.4.2 Calibration

G-TEK spent a total of 55 minutes in the calibration lanes, of which 50 minutes was spent collecting data. An additional 15 minutes was spent calibrating in the mogul area.

3.4.3 Downtime Occasions

Occasions of downtime are grouped into five categories: equipment/data checks or equipment maintenance, equipment failure and repair, weather, Demonstration Site issues, or breaks/lunch. All downtime is included for the purposes of calculating labor costs (section 5) except for downtime due to Demonstration Site issues. Demonstration Site issues, while noted in the Daily Log, are considered non-chargeable downtime for the purposes of calculating labor costs and are not discussed. Breaks and lunches are discussed in this section and billed to the total Site Survey area.

3.4.3.1 Equipment/data checks, maintenance. Equipment data checks and maintenance activities accounted for 20 minutes of site usage time. These activities included changing out batteries and routine data checks to ensure the data was being properly recorded/collected. G-TEK spent no time for breaks and lunches.

3.4.3.2 Equipment failure or repair. No time was needed to resolve equipment failures that occurred while surveying the Mogul.

3.4.3.3 Weather. No weather delays occurred during the survey.

3.4.4 Data Collection

G-TEK spent a total time of 9 hours and 45 minutes in the Mogul area, 5 hours and 5 minutes of which was spent collecting data.

3.4.5 Demobilization

The G-TEK survey crew went on to conduct a full demonstration of the site. Therefore, demobilization did not occur until 24 October 2003. On that day, it took the crew 1-hour and 35 minutes to break down and pack up their equipment.

3.5 PROCESSING TIME

G-TEK submitted the raw data from the demonstration activities on the last day of the demonstration, as required. The scoring submittal data was also provided within the required 30-day timeframe.

3.6 DEMONSTRATOR'S FIELD PERSONNEL

Mr. Peter Clark, Site Manager
Mr. Paul O'Donnell, Geophysicist
Mr. Bruce Symans, Crew Leader
Mr. Graham Browne, Field Technician
Mr. Terry Foot, Data Acquisition, Grid Setup

3.7 DEMONSTRATOR'S FIELD SURVEYING METHOD

G-TEK started surveying the Mogul area in the southwest portion and surveyed in a south/north direction. One lane was surveyed and then the demonstrator returned to the beginning of the next lane, until completion.

3.8 SUMMARY OF DAILY LOGS

Daily logs capture all field activities during this demonstration and are located in Appendix D. Activities pertinent to this specific demonstration are indicated in highlighted text.

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SECTION 4. TECHNICAL PERFORMANCE RESULTS

4.1 ROC CURVES USING ALL ORDNANCE CATEGORIES

Figure 2 shows the probability of detection for the response stage (P_d^{res}) and the discrimination stage (P_d^{disc}) versus their respective probability of false positive. Figure 3 shows both probabilities plotted against their respective background alarm rate. Both figures use horizontal lines to illustrate the performance of the demonstrator at two demonstrator-specified points: at the system noise level for the response stage, representing the point below which targets are not considered detectable, and at the demonstrator's recommended threshold level for the discrimination stage, defining the subset of targets the demonstrator would recommend digging based on discrimination. Note that all points have been rounded to protect the ground truth.

The overall ground truth is composed of ferrous and non-ferrous anomalies. Due to limitations of the magnetometer, the non-ferrous items cannot be detected. Therefore, the ROC curves presented in this section are based on the subset of the ground truth that is solely made up of ferrous anomalies.

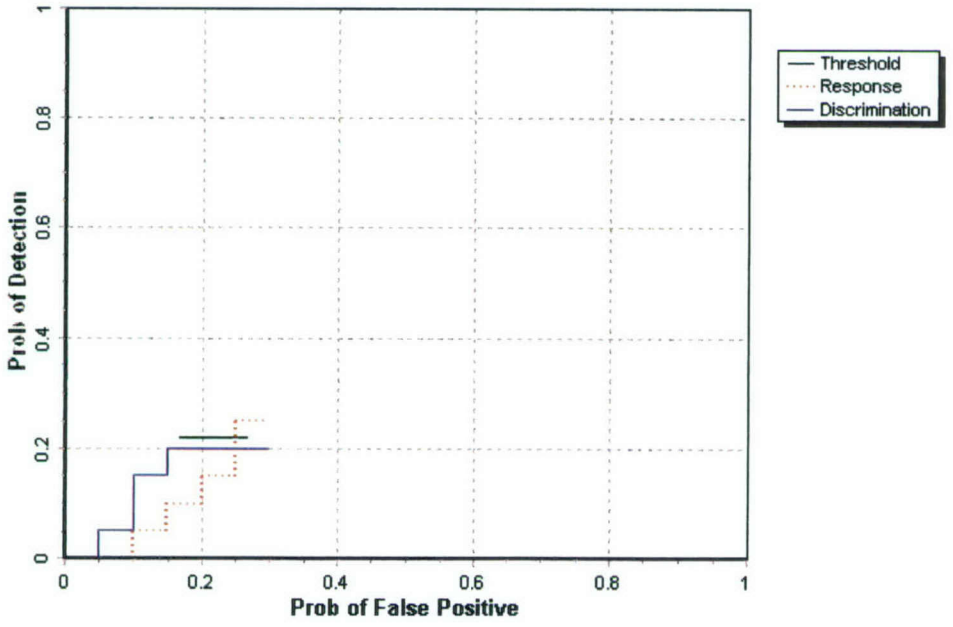

Figure 2. MAG TM-4/sling mogul probability of detection for response and discrimination stages versus their respective probability of false positive over all ordnance categories combined.

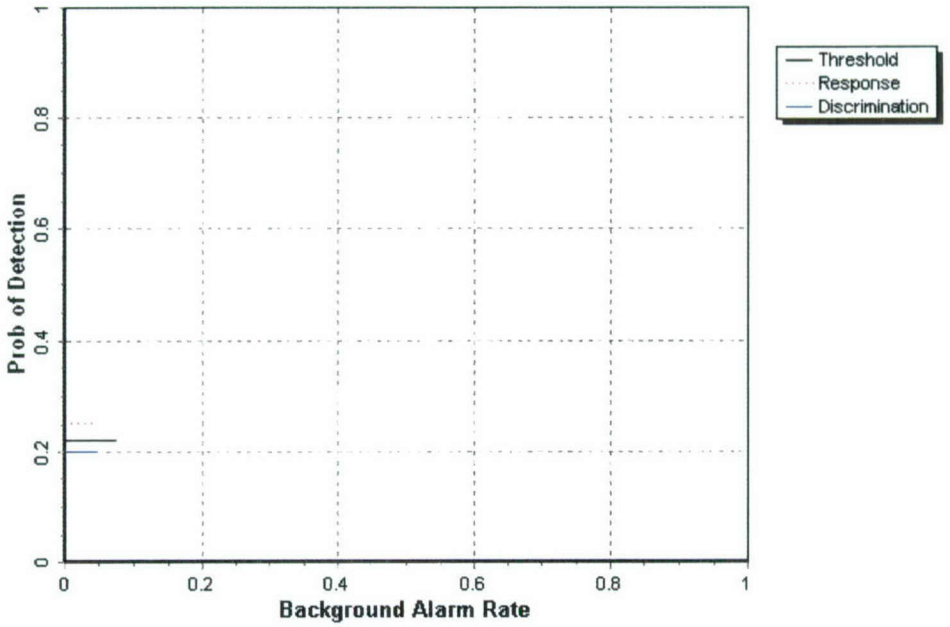

Figure 3. MAG TM-4/sling mogul probability of detection for response and discrimination stages versus their respective background alarm rate over all ordnance categories combined.

4.2 ROC CURVES USING ORDNANCE LARGER THAN 20 MM

Figure 4 shows the probability of detection for the response stage (P_d^{res}) and the discrimination stage (P_d^{disc}) versus their respective probability of false positive when only targets larger than 20 mm are scored. Figure 5 shows both probabilities plotted against their respective probability of background alarm. Both figures use horizontal lines to illustrate the performance of the demonstrator at two demonstrator-specified points: at the system noise level for the response stage, representing the point below which targets are not considered detectable, and at the demonstrator's recommended threshold level for the discrimination stage, defining the subset of targets the demonstrator would recommend digging based on discrimination. Note that all points have been rounded to protect the ground truth.

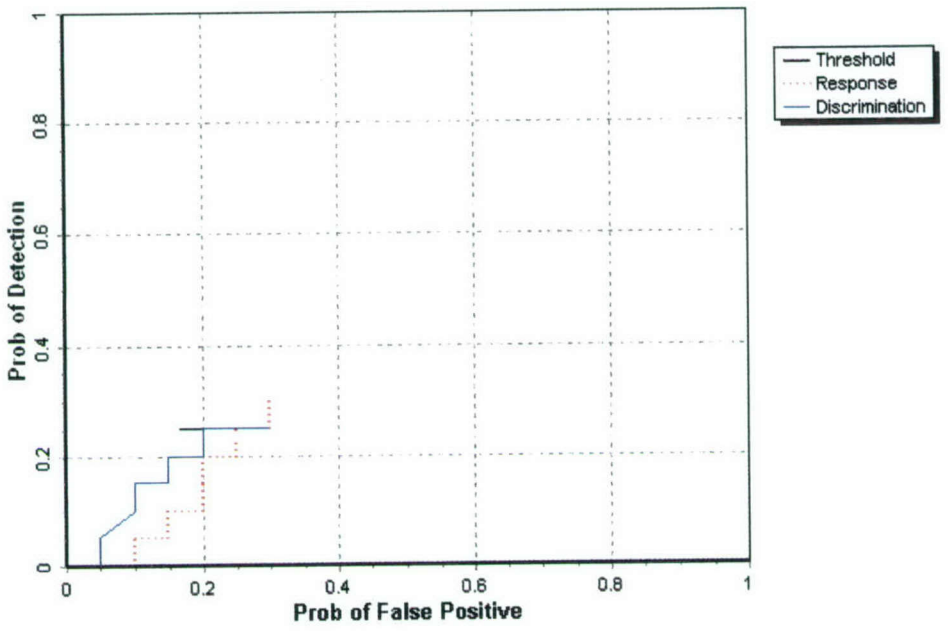

Figure 4. MAG TM-4/sling mogul probability of detection for response and discrimination stages versus their respective probability of false positive for all ordnance larger than 20 mm.

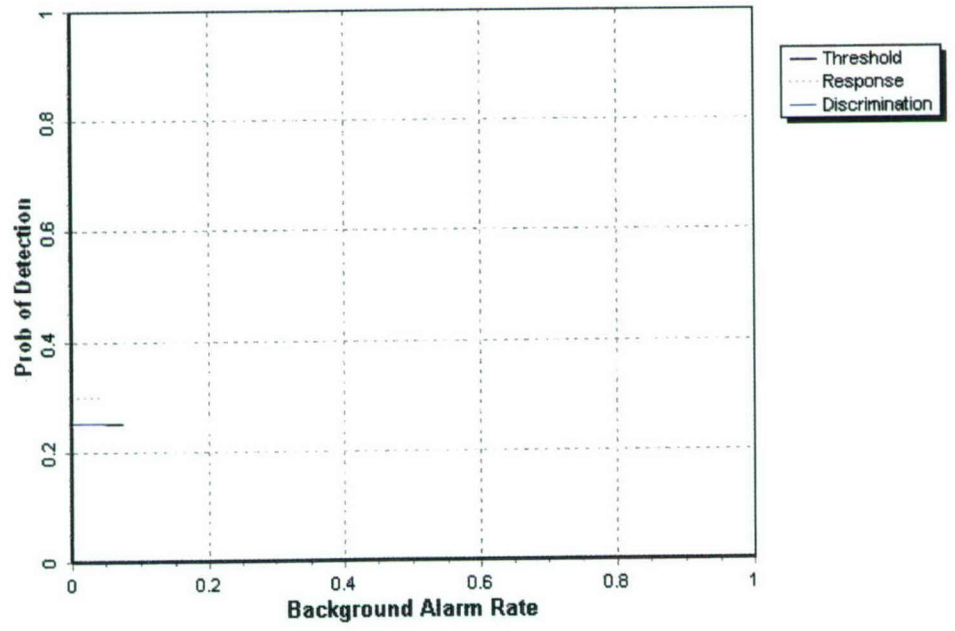

Figure 5. MAG TM-4/sling mogul probability of detection for response and discrimination stages versus their respective background alarm rate for all ordnance larger than 20 mm.

4.3 PERFORMANCE SUMMARIES

Results for the Mogul Area test, broken out by size, depth and nonstandard ordnance, are presented in Tables 5a and 5b (for cost results, see section 5). Results by size and depth include both standard and nonstandard ordnance. The results by size show how well the demonstrator did at detecting/discriminating ordnance of a certain caliber range (see app A for size definitions). The results are relative to the number of ordnances emplaced. Depth is measured from the geometric center of anomalies.

The RESPONSE STAGE results are derived from the list of anomalies above the demonstrator-provided noise level. The results for the DISCRIMINATION STAGE are derived from the demonstrator's recommended threshold for optimizing UXO field cleanup by minimizing false digs and maximizing ordnance recovery. The lower 90-percent confidence limit on probability of detection and probability of false positive was calculated assuming that the number of detections and false positives are binomially distributed random variables. All results in Tables 5a and 5b have been rounded to protect the ground truth. However, lower confidence limits were calculated using actual results.

The overall ground truth is composed of ferrous and non-ferrous anomalies. Due to limitations of the magnetometer, the non-ferrous items cannot be detected. Therefore, the summary presented in Table 5a exhibits results based on the subset of the ground truth that is solely the ferrous anomalies. Table 5b exhibits results based on the full ground truth. All other tables presented in this section are based on scoring against the ferrous only ground truth. The response stage noise level and recommended discrimination stage threshold values are provided by the demonstrator.

TABLE 5a. SUMMARY OF MOGUL RESULTS (FERROUS ONLY)

Metric	Overall	Standard	Nonstandard	By Size			By Depth, m		
				Small	Medium	Large	< 0.3	0.3 to <1	>= 1
RESPONSE STAGE									
P_d	0.25	0.30	0.25	0.10	0.35	0.50	0.30	0.30	0.15
P_d Low 90% Conf	0.23	0.23	0.17	0.06	0.26	0.36	0.24	0.20	0.05
P_d Upper 90% Conf	0.32	0.36	0.33	0.18	0.42	0.64	0.38	0.37	0.28
P_{fp}	0.30	-	-	-	-	-	0.35	0.25	0.15
P_{fp} Low 90% Conf	0.28	-	-	-	-	-	0.30	0.23	0.01
P_{fp} Upper 90% Conf	0.34	-	-	-	-	-	0.39	0.31	0.41
BAR	0.35	-	-	-	-	-	-	-	-
DISCRIMINATION STAGE									
P_d	0.20	0.25	0.20	0.10	0.25	0.45	0.25	0.25	0.15
P_d Low 90% Conf	0.18	0.18	0.13	0.05	0.17	0.32	0.18	0.16	0.05
P_d Upper 90% Conf	0.27	0.31	0.27	0.16	0.32	0.60	0.31	0.31	0.28
P_{fp}	0.20	-	-	-	-	-	0.30	0.15	0.00
P_{fp} Low 90% Conf	0.19	-	-	-	-	-	0.24	0.13	0.00
P_{fp} Upper 90% Conf	0.25	-	-	-	-	-	0.32	0.20	0.25
BAR	0.25	-	-	-	-	-	-	-	-

Response Stage Noise Level: 7.00
Recommended Discrimination Stage Threshold: 0.50

TABLE 5b. SUMMARY OF MOGUL RESULTS (FULL GROUND TRUTH)

Metric	Overall	Standard	Nonstandard	By Size			By Depth, m		
				Small	Medium	Large	< 0.3	0.3 to <1	>= 1
RESPONSE STAGE									
P_d	0.25	0.25	0.20	0.10	0.35	0.50	0.25	0.25	0.15
P_d Low 90% Conf	0.20	0.20	0.16	0.06	0.26	0.36	0.20	0.19	0.05
P_d Upper 90% Conf	0.29	0.32	0.29	0.15	0.42	0.64	0.33	0.35	0.27
P_{fp}	0.30	-	-	-	-	-	0.35	0.25	0.10
P_{fp} Low 90% Conf	0.27	-	-	-	-	-	0.29	0.23	0.01
P_{fp} Upper 90% Conf	0.33	-	-	-	-	-	0.37	0.31	0.37
BAR	0.35	-	-	-	-	-	-	-	-
DISCRIMINATION STAGE									
P_d	0.20	0.20	0.20	0.10	0.25	0.45	0.20	0.20	0.15
P_d Low 90% Conf	0.16	0.16	0.12	0.05	0.17	0.32	0.15	0.15	0.05
P_d Upper 90% Conf	0.24	0.27	0.25	0.13	0.32	0.60	0.27	0.30	0.27
P_{fp}	0.20	-	-	-	-	-	0.25	0.15	0.00
P_{fp} Low 90% Conf	0.19	-	-	-	-	-	0.23	0.13	0.00
P_{fp} Upper 90% Conf	0.24	-	-	-	-	-	0.30	0.20	0.23
BAR	0.25	-	-	-	-	-	-	-	-

Response Stage Noise Level: 7.00
Recommended Discrimination Stage Threshold 0.50

Note: The recommended discrimination stage threshold values are provided by the demonstrator.

4.4 EFFICIENCY, REJECTION RATES, AND TYPE CLASSIFICATION

Efficiency and rejection rates are calculated to quantify the discrimination ability at specific points of interest on the ROC curve: (1) at the point where no decrease in P_d is suffered (i.e., the efficiency is by definition equal to one) and (2) at the operator selected threshold. These values are reported in Table 6.

TABLE 6. EFFICIENCY AND REJECTION RATES

	Efficiency (E)	False Positive Rejection Rate	Background Alarm Rejection Rate
At Operating Point	0.81	0.29	0.28
With No Loss of P_d	1.00	0.20	0.12

At the demonstrator's recommended setting, the ordnance items that were detected and correctly discriminated were further scored on whether their correct type could be identified (table 7). Correct type examples include "20-mm projectile, 105-mm HEAT Projectile, and 2.75-inch Rocket". A list of the standard type declaration required for each ordnance item was provided to demonstrators prior to testing. For example, the standard type for the three example items are 20mmP, 105H, and 2.75in, respectively.

TABLE 7. CORRECT TYPE CLASSIFICATION OF TARGETS CORRECTLY DISCRIMINATED AS UXO

Size	Percentage Correct
Small	16.7
Medium	12.5
Large	41.7
Overall	23.5

4.5 LOCATION ACCURACY

The mean location error and standard deviations appear in Table 8. These calculations are based on average missed depth for ordnance correctly identified in the discrimination stage. Depths are measured from the closest point of the ordnance to the surface. For the Blind Grid, only depth errors are calculated, since (X, Y) positions are known to be the centers of each grid square.

TABLE 8. MEAN LOCATION ERROR AND STANDARD DEVIATION (M)

	Mean	Standard Deviation
Northing	0.10	0.21
Easting	-0.05	0.24
Depth	0.02	0.26

SECTION 5. ON-SITE LABOR COSTS

A standardized estimate for labor costs associated with this effort was calculated as follows: the first person at the test site was designated "supervisor", the second person was designated "data analyst", and the third and following personnel were considered "field support". Standardized hourly labor rates were charged by title: supervisor at $95.00/hour, data analyst at $57.00/hour, and field support at $28.50/hour.

Government representatives monitored on-site activity. All on-site activities were grouped into one of ten categories: initial setup/mobilization, daily setup/stop, calibration, collecting data, downtime due to break/lunch, downtime due to equipment failure, downtime due to equipment/data checks or maintenance, downtime due to weather, downtime due to demonstration site issue, or demobilization. See Appendix D for the daily activity log. See section 3.4 for a summary of field activities.

The standardized cost estimate associated with the labor needed to perform the field activities is presented in Table 9. Note that calibration time includes time spent in the Calibration Lanes as well as field calibrations. "Site survey time" includes daily setup/stop time, collecting data, breaks/lunch, downtime due to equipment/data checks or maintenance, downtime due to failure, and downtime due to weather.

TABLE 9. ON-SITE LABOR COSTS

	No. People	Hourly Wage	Hours	Cost
Initial Setup				
Supervisor	1	$95.00	5.16	$490.20
Data Analyst	1	57.00	5.16	294.12
Field Support	1	28.50	5.16	147.06
SubTotal				**$931.38**
Calibration				
Supervisor	1	$95.00	1.17	$111.15
Data Analyst	1	57.00	1.17	66.69
Field Support	1	28.50	1.17	33.35
SubTotal				**$211.19**
Site Survey				
Supervisor	1	$95.00	9.75	$926.25
Data Analyst	1	57.00	9.75	555.75
Field Support	1	28.50	9.75	277.88
SubTotal				**$1,759.88**

See notes at end of table.

TABLE 9 (CONT'D)

	No. People	Hourly Wage	Hours	Cost
Demobilization				
Supervisor	1	$95.00	1.58	$150.10
Data Analyst	1	57.00	1.58	90.06
Field Support	1	28.50	1.58	45.03
Subtotal				**$285.19**
Total				**$3,187.64**

Notes: Calibration time includes time spent in the Calibration Lanes as well as calibration before each data run.

Site Survey time includes daily setup/stop time, collecting data, breaks/lunch, downtime due to system maintenance, failure, and weather.

SECTION 6. COMPARISON OF RESULTS TO OPEN FIELD DEMONSTRATION (BASED ON FERROUS ONLY GROUND TRUTH)

6.1 SUMMARY OF RESULTS FROM OPEN FIELD DEMONSTRATION

Table 10 shows the results from the Open Field survey conducted prior to surveying the Moguls during the same site visit in October of 2003. Due to the system utilizing magnetometer type sensors, all results presented in the following section have been based on performance scoring against the ferrous only ground truth anomalies. For more details on the Open Field survey results reference section 2.1.6.

TABLE 10. SUMMARY OF OPEN FIELD RESULTS FOR THE MAGNETOMETER TM-4/SLING (FERROUS ONLY)

Metric	Overall	Standard	Nonstandard	By Size			By Depth, m		
				Small	Medium	Large	< 0.3	0.3 to <1	>= 1
RESPONSE STAGE									
P_d	0.60	0.65	0.55	0.45	0.60	0.85	0.60	0.60	0.55
P_d Low 90% Conf	0.57	0.60	0.47	0.38	0.54	0.77	0.56	0.55	0.47
P_d Upper 90% Conf	0.64	0.70	0.60	0.51	0.66	0.89	0.67	0.68	0.64
P_{fp}	0.45	-	-	-	-	-	0.45	0.50	0.55
P_{fp} Low 90% Conf	0.45	-	-	-	-	-	0.41	0.47	0.38
P_{fp} Upper 90% Conf	0.49	-	-	-	-	-	0.47	0.53	0.74
BAR	0.30	-	-	-	-	-	-	-	-
DISCRIMINATION STA-GE									
P_d	0.50	0.55	0.45	0.30	0.55	0.80	0.50	0.55	0.50
P_d Low 90% Conf	0.48	0.51	0.40	0.26	0.47	0.71	0.43	0.50	0.42
P_d Upper 90% Conf	0.56	0.61	0.53	0.39	0.59	0.84	0.54	0.63	0.60
P_{fp}	0.25	-	-	-	-	-	0.25	0.25	0.40
P_{fp} Low 90% Conf	0.24	-	-	-	-	-	0.23	0.23	0.21
P_{fp} Upper 90% Conf	0.28	-	-	-	-	-	0.29	0.28	0.57
BAR	0.20	-	-	-	-	-	-	-	-

6.2 COMPARISON OF ROC CURVES USING ALL ORDNANCE CATEGORIES

Figure 6 shows P_d^{res} versus the respective P_{fp} over all ordnance categories. Figure 7 shows P_d^{disc} versus their respective P_{fp} over all ordnance categories. Figure 7 uses horizontal lines to illustrate the performance of the demonstrator at the recommended discrimination threshold levels, defining the subset of targets the demonstrator would recommend digging based on discrimination. The ROC curves in this section are a sole reflection of the ferrous only survey.

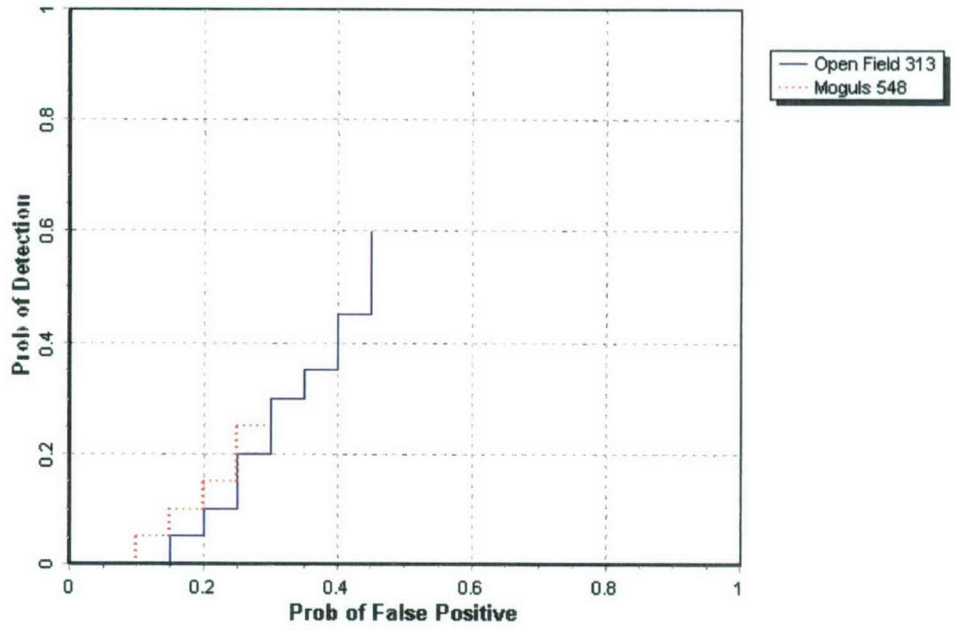

Figure 6. MAG TM-4/sling P_d^{res} stages versus the respective P_{fp} over all ordnance categories combined.

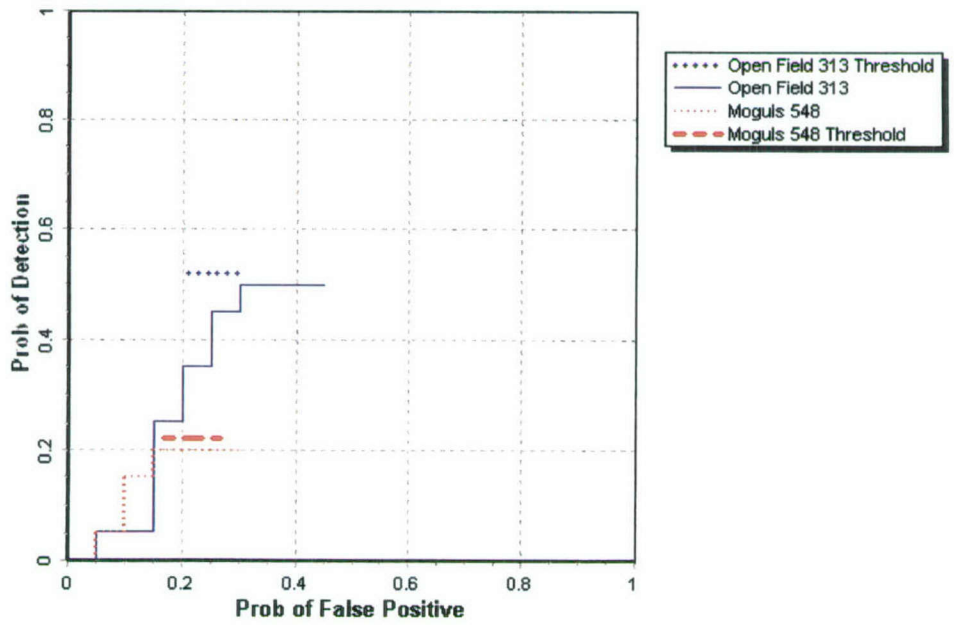

Figure 7. MAG TM-4/sling P_d^{disc} versus the respective P_{fp} over all ordnance categories combined.

6.3 COMPARISON OF ROC CURVES USING ORDNANCE LARGER THAN 20 MM

Figure 8 shows the P_d^{res} versus the respective probability of P_{fp} over ordnance larger than 20 mm. Figure 9 shows P_d^{disc} versus the respective P_{fp} over ordnance larger than 20 mm. Figure 9 uses horizontal lines to illustrate the performance of the demonstrator at the recommended discrimination threshold levels, defining the subset of targets the demonstrator would recommend digging based on discrimination.

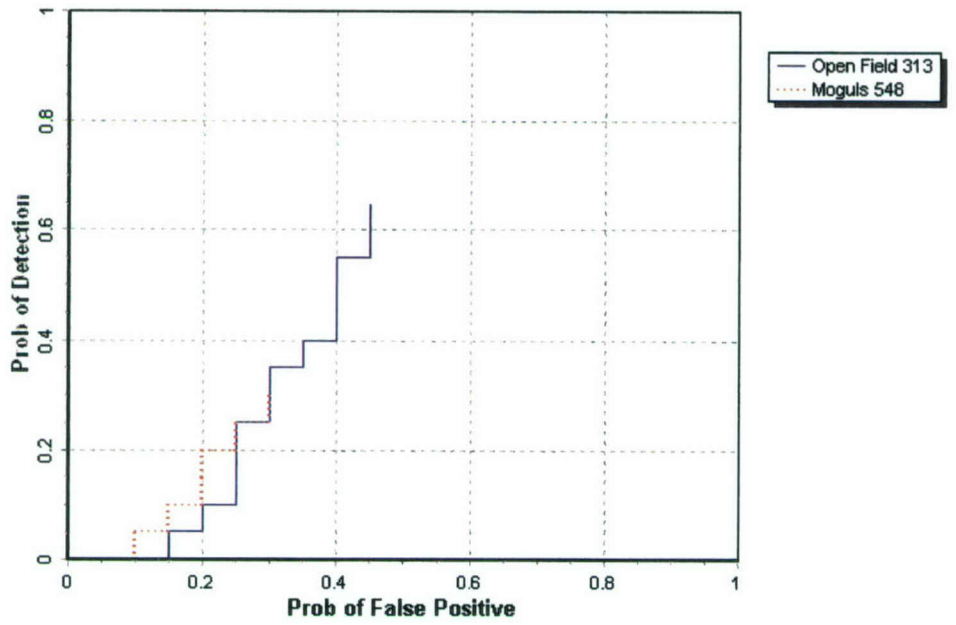

Figure 8. MAG TM-4/sling P_d^{res} versus the respective P_{fp} for ordnance larger than 20 mm.

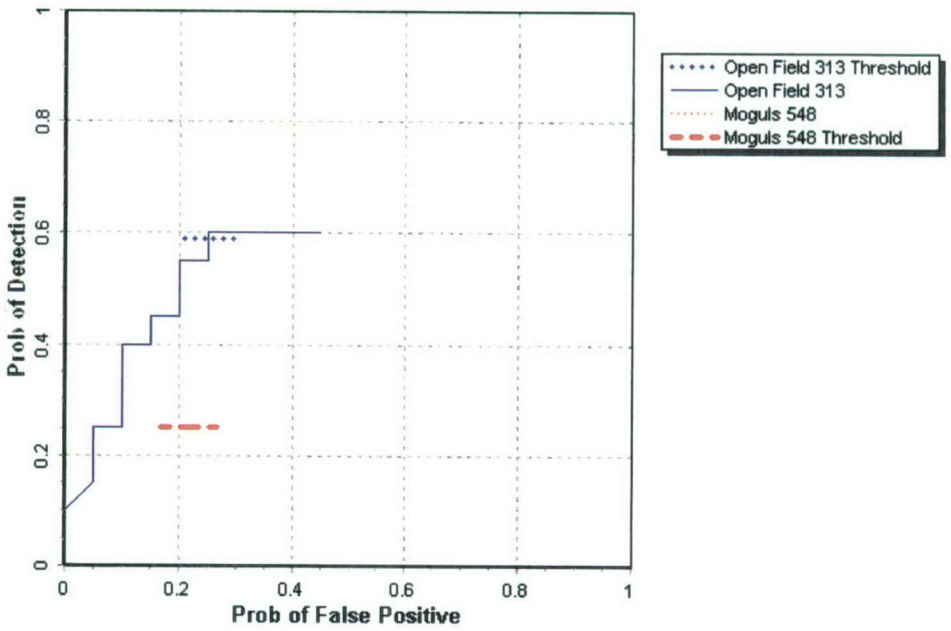

Figure 9. MAG TM-4/sling P_d^{disc} versus the respective P_{fp} for ordnance larger than 20 mm.

6.4 STATISTICAL COMPARISONS

Statistical Chi-square significance tests were used to compare results between the Open Field and Mogul Area scenarios. The intent of the comparison is to determine if the feature introduced in each scenario has a degrading effect on the performance of the sensor system. However, any modifications in the UXO sensor system during the test, like changes in the processing or changes in the selection of the operating threshold, will also contribute to performance differences.

The Chi-square test for comparison between ratios was used at a significance level of 0.05 to compare Open Field to Mogul Area with regard to P_d^{res}, P_d^{disc}, P_{fp}^{res} and P_{fp}^{disc}, Efficiency and Rejection Rate. These results are presented in Table 11. A detailed explanation and example of the Chi-square application is located in Appendix A.

TABLE 11. CHI-SQUARE RESULTS – OPEN FIELD VERSUS MOGULS

Metric	Small	Medium	Large	Overall
P_d^{res}	Significant	Significant	Significant	Significant
P_d^{disc}	Significant	Significant	Significant	Significant
P_{fp}^{res}	Not Significant	Not Significant	Not Significant	Not Significant
P_{fp}^{disc}	-	-	-	Significant
Efficiency	-	-	-	Not Significant
Rejection rate	-	-	-	Significant

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SECTION 7. APPENDIXES

APPENDIX A. TERMS AND DEFINITIONS

GENERAL DEFINITIONS

Anomaly: Location of a system response deemed to warrant further investigation by the demonstrator for consideration as an emplaced ordnance item.

Detection: An anomaly location that is within R_{halo} of an emplaced ordnance item.

Emplaced Ordnance: An ordnance item buried by the government at a specified location in the test site.

Emplaced Clutter: A clutter item (i.e., non-ordnance item) buried by the government at a specified location in the test site.

R_{halo}: A pre-determined radius about the periphery of an emplaced item (clutter or ordnance) within which a location identified by the demonstrator as being of interest is considered to be a response from that item. If multiple declarations lie within R_{halo} of any item (clutter or ordnance), the declaration with the highest signal output within the R_{halo} will be utilized. For the purpose of this program, a circular halo 0.5 meters in radius will be placed around the center of the object for all clutter and ordnance items less than 0.6 meters in length. When ordnance items are longer than 0.6 meters, the halo becomes an ellipse where the minor axis remains 1 meter and the major axis is equal to the length of the ordnance plus 1 meter.

Small Ordnance: Caliber of ordnance less than or equal to 40 mm (includes 20-mm projectile, 40-mm projectile, submunitions BLU-26, BLU-63, and M42).

Medium Ordnance: Caliber of ordnance greater than 40 mm and less than or equal to 81 mm (includes 57-mm projectile, 60-mm mortar, 2.75 in. Rocket, MK118 Rockeye, 81-mm mortar).

Large Ordnance: Caliber of ordnance greater than 81 mm (includes 105-mm HEAT, 105-mm projectile, 155-mm projectile, 500-pound bomb).

Shallow: Items buried less than 0.3 meter below ground surface.

Medium: Items buried greater than or equal to 0.3 meter and less than 1 meter below ground surface.

Deep: Items buried greater than or equal to 1 meter below ground surface.

Response Stage Noise Level: The level that represents the point below which anomalies are not considered detectable. Demonstrators are required to provide the recommended noise level for the Blind Grid test area.

Discrimination Stage Threshold: The demonstrator selected threshold level that they believe provides optimum performance of the system by retaining all detectable ordnance and rejecting the maximum amount of clutter. This level defines the subset of anomalies the demonstrator would recommend digging based on discrimination.

Binomially Distributed Random Variable: A random variable of the type which has only two possible outcomes, say success and failure, is repeated for n independent trials with the probability p of success and the probability 1-p of failure being the same for each trial. The number of successes x observed in the n trials is an estimate of p and is considered to be a binomially distributed random variable.

RESPONSE AND DISCRIMINATION STAGE DATA

The scoring of the demonstrator's performance is conducted in two stages. These two stages are termed the RESPONSE STAGE and DISCRIMINATION STAGE. For both stages, the probability of detection (P_d) and the false alarms are reported as receiver operating characteristic (ROC) curves. False alarms are divided into those anomalies that correspond to emplaced clutter items, measuring the probability of false positive (P_{fp}) and those that do not correspond to any known item, termed background alarms.

The RESPONSE STAGE scoring evaluates the ability of the system to detect emplaced targets without regard to ability to discriminate ordnance from other anomalies. For the RESPONSE STAGE, the demonstrator provides the scoring committee with the location and signal strength of all anomalies that the demonstrator has deemed sufficient to warrant further investigation and/or processing as potential emplaced ordnance items. This list is generated with minimal processing (e.g., this list will include all signals above the system noise threshold). As such, it represents the most inclusive list of anomalies.

The DISCRIMINATION STAGE evaluates the demonstrator's ability to correctly identify ordnance as such, and to reject clutter. For the same locations as in the RESPONSE STAGE anomaly list, the DISCRIMINATION STAGE list contains the output of the algorithms applied in the discrimination-stage processing. This list is prioritized based on the demonstrator's determination that an anomaly location is likely to contain ordnance. Thus, higher output values are indicative of higher confidence that an ordnance item is present at the specified location. For electronic signal processing, priority ranking is based on algorithm output. For other systems, priority ranking is based on human judgment. The demonstrator also selects the threshold that the demonstrator believes will provide "optimum" system performance, (i.e., that retains all the detected ordnance and rejects the maximum amount of clutter).

Note: The two lists provided by the demonstrator contain identical numbers of potential target locations. They differ only in the priority ranking of the declarations.

RESPONSE STAGE DEFINITIONS

Response Stage Probability of Detection (P_d^{res}): P_d^{res} = (No. of response-stage detections)/ (No. of emplaced ordnance in the test site).

Response Stage False Positive (fp^{res}): An anomaly location that is within R_{halo} of an emplaced clutter item.

Response Stage Probability of False Positive (P_{fp}^{res}): P_{fp}^{res} = (No. of response-stage false positives)/(No. of emplaced clutter items).

Response Stage Background Alarm (ba^{res}): An anomaly in a blind grid cell that contains neither emplaced ordnance nor an emplaced clutter item. An anomaly location in the open field or scenarios that is outside R_{halo} of any emplaced ordnance or emplaced clutter item.

Response Stage Probability of Background Alarm (P_{ba}^{res}): Blind Grid only: P_{ba}^{res} = (No. of response-stage background alarms)/(No. of empty grid locations).

Response Stage Background Alarm Rate (BAR^{res}): Open Field only: BAR^{res} = (No. of response-stage background alarms)/(arbitrary constant).

Note that the quantities P_d^{res}, P_{fp}^{res}, P_{ba}^{res}, and BAR^{res} are functions of t^{res}, the threshold applied to the response-stage signal strength. These quantities can therefore be written as $P_d^{res}(t^{res})$, $P_{fp}^{res}(t^{res})$, $P_{ba}^{res}(t^{res})$, and $BAR^{res}(t^{res})$.

DISCRIMINATION STAGE DEFINITIONS

Discrimination: The application of a signal processing algorithm or human judgment to response-stage data that discriminates ordnance from clutter. Discrimination should identify anomalies that the demonstrator has high confidence correspond to ordnance, as well as those that the demonstrator has high confidence correspond to nonordnance or background returns. The former should be ranked with highest priority and the latter with lowest.

Discrimination Stage Probability of Detection (P_d^{disc}): P_d^{disc} = (No. of discrimination-stage detections)/(No. of emplaced ordnance in the test site).

Discrimination Stage False Positive (fp^{disc}): An anomaly location that is within R_{halo} of an emplaced clutter item.

Discrimination Stage Probability of False Positive (P_{fp}^{disc}): P_{fp}^{disc} = (No. of discrimination stage false positives)/(No. of emplaced clutter items).

Discrimination Stage Background Alarm (ba^{disc}): An anomaly in a blind grid cell that contains neither emplaced ordnance nor an emplaced clutter item. An anomaly location in the open field or scenarios that is outside R_{halo} of any emplaced ordnance or emplaced clutter item.

Discrimination Stage Probability of Background Alarm (P_{ba}^{disc}): P_{ba}^{disc} = (No. of discrimination-stage background alarms)/(No. of empty grid locations).

Discrimination Stage Background Alarm Rate (BAR^{disc}): BAR^{disc} = (No. of discrimination-stage background alarms)/(arbitrary constant).

Note that the quantities P_d^{disc}, P_{fp}^{disc}, P_{ba}^{disc}, and BAR^{disc} are functions of t^{disc}, the threshold applied to the discrimination-stage signal strength. These quantities can therefore be written as $P_d^{disc}(t^{disc})$, $P_{fp}^{disc}(t^{disc})$, $P_{ba}^{disc}(t^{disc})$, and $BAR^{disc}(t^{disc})$.

RECEIVER-OPERATING CHARACERISTIC (ROC) CURVES

ROC curves at both the response and discrimination stages can be constructed based on the above definitions. The ROC curves plot the relationship between P_d versus P_{fp} and P_d versus BAR or P_{ba} as the threshold applied to the signal strength is varied from its minimum (t_{min}) to its maximum (t_{max}) value.[1] Figure A-1 shows how P_d versus P_{fp} and P_d versus BAR are combined into ROC curves. Note that the "res" and "disc" superscripts have been suppressed from all the variables for clarity.

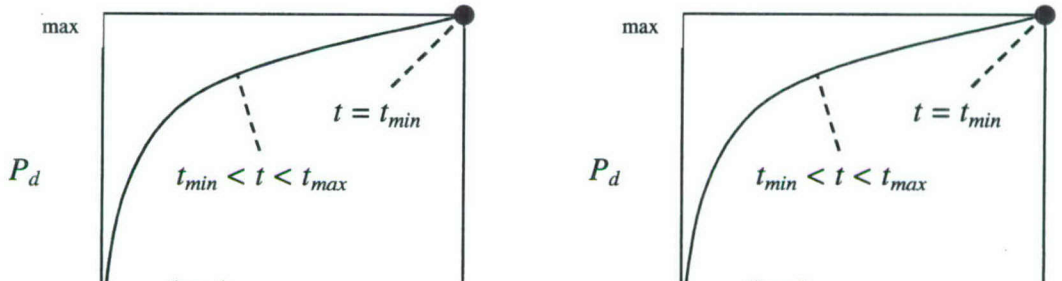

Figure A-1. ROC curves for open field testing. Each curve applies to both the response and discrimination stages.

[1]Strictly speaking, ROC curves plot the P_d versus P_{ba} over a pre-determined and fixed number of detection opportunities (some of the opportunities are located over ordnance and others are located over clutter or blank spots). In an open field scenario, each system suppresses its signal strength reports until some bare-minimum signal response is received by the system. Consequently, the open field ROC curves do not have information from low signal-output locations, and, furthermore, different contractors report their signals over a different set of locations on the ground. These ROC curves are thus not true to the strict definition of ROC curves as defined in textbooks on detection theory. Note, however, that the ROC curves obtained in the Blind Grid test sites are true ROC curves.

METRICS TO CHARACTERIZE THE DISCRIMINATION STAGE

The demonstrator is also scored on efficiency and rejection ratio, which measure the effectiveness of the discrimination stage processing. The goal of discrimination is to retain the greatest number of ordnance detections from the anomaly list, while rejecting the maximum number of anomalies arising from nonordnance items. The efficiency measures the amount of detected ordnance retained by the discrimination, while the rejection ratio measures the fraction of false alarms rejected. Both measures are defined relative to the entire response list, i.e., the maximum ordnance detectable by the sensor and its accompanying false positive rate or background alarm rate.

Efficiency (E): $E = P_d^{disc}(t^{disc})/P_d^{res}(t_{min}^{res})$; Measures (at a threshold of interest), the degree to which the maximum theoretical detection performance of the sensor system (as determined by the response stage tmin) is preserved after application of discrimination techniques. Efficiency is a number between 0 and 1. An efficiency of 1 implies that all of the ordnance initially detected in the response stage was retained at the specified threshold in the discrimination stage, t^{disc}.

False Positive Rejection Rate (R_{fp}): $R_{fp} = 1 - [P_{fp}^{disc}(t^{disc})/P_{fp}^{res}(t_{min}^{res})]$; Measures (at a threshold of interest), the degree to which the sensor system's false positive performance is improved over the maximum false positive performance (as determined by the response stage tmin). The rejection rate is a number between 0 and 1. A rejection rate of 1 implies that all emplaced clutter initially detected in the response stage were correctly rejected at the specified threshold in the discrimination stage.

Background Alarm Rejection Rate (R_{ba}):

Blind Grid: $R_{ba} = 1 - [P_{ba}^{disc}(t^{disc})/P_{ba}^{res}(t_{min}^{res})]$.
Open Field: $R_{ba} = 1 - [BAR^{disc}(t^{disc})/BAR^{res}(t_{min}^{res})])$.

Measures the degree to which the discrimination stage correctly rejects background alarms initially detected in the response stage. The rejection rate is a number between 0 and 1. A rejection rate of 1 implies that all background alarms initially detected in the response stage were rejected at the specified threshold in the discrimination stage.

CHI-SQUARE COMPARISON EXPLANATION:

The Chi-square test for differences in probabilities (or 2 x 2 contingency table) is used to analyze two samples drawn from two different populations to see if both populations have the same or different proportions of elements in a certain category. More specifically, two random samples are drawn, one from each population, to test the null hypothesis that the probability of event A (some specified event) is the same for both populations (ref 3).

A 2 x 2 contingency table is used in the Standardized UXO Technology Demonstration Site Program to determine if there is reason to believe that the proportion of ordnance correctly detected/discriminated by demonstrator X's system is significantly degraded by the more challenging terrain feature introduced. The test statistic of the 2 x 2 contingency table is the

Chi-square distribution with one degree of freedom. Since an association between the more challenging terrain feature and relatively degraded performance is sought, a one-sided test is performed. A significance level of 0.05 is chosen which sets a critical decision limit of 2.71 from the Chi-square distribution with one degree of freedom. It is a critical decision limit because if the test statistic calculated from the data exceeds this value, the two proportions tested will be considered significantly different. If the test statistic calculated from the data is less than this value, the two proportions tested will be considered not significantly different.

An exception must be applied when either a 0 or 100 percent success rate occurs in the sample data. The Chi-square test cannot be used in these instances. Instead, Fischer's test is used and the critical decision limit for one-sided tests is the chosen significance level, which in this case is 0.05. With Fischer's test, if the test statistic is less than the critical value, the proportions are considered to be significantly different.

Standardized UXO Technology Demonstration Site examples, where blind grid results are compared to those from the open field and open field results are compared to those from one of the scenarios, follow. It should be noted that a significant result does not prove a cause and effect relationship exists between the two populations of interest; however, it does serve as a tool to indicate that one data set has experienced a degradation in system performance at a large enough level than can be accounted for merely by chance or random variation. Note also that a result that is not significant indicates that there is not enough evidence to declare that anything more than chance or random variation within the same population is at work between the two data sets being compared.

Demonstrator X achieves the following overall results after surveying each of the three progressively more difficult areas using the same system (results indicate the number of ordnance detected divided by the number of ordnance emplaced):

	Blind Grid	Open Field	Moguls
P_d^{res}	100/100 = 1.0	8/10 = .80	20/33 = .61
P_d^{disc}	80/100 = 0.80	6/10 = .60	8/33 = .24

P_d^{res}: BLIND GRID versus OPEN FIELD. Using the example data above to compare probabilities of detection in the response stage, all 100 ordnance out of 100 emplaced ordnance items were detected in the blind grid while 8 ordnance out of 10 emplaced were detected in the open field. Fischer's test must be used since a 100 percent success rate occurs in the data. Fischer's test uses the four input values to calculate a test statistic of 0.0075 that is compared against the critical value of 0.05. Since the test statistic is less than the critical value, the smaller response stage detection rate (0.80) is considered to be significantly less at the 0.05 level of significance. While a significant result does not prove a cause and effect relationship exists between the change in survey area and degradation in performance, it does indicate that the detection ability of demonstrator X's system seems to have been degraded in the open field relative to results from the blind grid using the same system.

P_d^{disc}: BLIND GRID versus OPEN FIELD. Using the example data above to compare probabilities of detection in the discrimination stage, 80 out of 100 emplaced ordnance items were correctly discriminated as ordnance in blind grid testing while 6 ordnance out of 10 emplaced were correctly discriminated as such in open field-testing. Those four values are used to calculate a test statistic of 1.12. Since the test statistic is less than the critical value of 2.71, the two discrimination stage detection rates are considered to be not significantly different at the 0.05 level of significance.

P_d^{res}: OPEN FIELD versus MOGULS. Using the example data above to compare probabilities of detection in the response stage, 8 out of 10 and 20 out of 33 are used to calculate a test statistic of 0.56. Since the test statistic is less than the critical value of 2.71, the two response stage detection rates are considered to be not significantly different at the 0.05 level of significance.

P_d^{disc}: OPEN FIELD versus MOGULS. Using the example data above to compare probabilities of detection in the discrimination stage, 6 out of 10 and 8 out of 33 are used to calculate a test statistic of 2.98. Since the test statistic is greater than the critical value of 2.71, the smaller discrimination stage detection rate is considered to be significantly less at the 0.05 level of significance. While a significant result does not prove a cause and effect relationship exists between the change in survey area and degradation in performance, it does indicate that the ability of demonstrator X to correctly discriminate seems to have been degraded by the mogul terrain relative to results from the flat open field using the same system.

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APPENDIX B. DAILY WEATHER LOGS

TABLE B-1. WEATHER LOG

Date & Time	Average Temp (°F)	Maximum Temp (°F)	Minimum Temp (°F)	Relative Humidity (%)	Total Precip (in)
10/13/2003 00:00:00	63	63.9	62.4	86.5	0
10/13/2003 01:00:00	64	64.9	62.8	80.2	0
10/13/2003 02:00:00	63	64.5	61.6	71.39	0
10/13/2003 03:00:00	60.8	62.1	59.8	70.15	0
10/13/2003 04:00:00	59.1	60.3	57.7	70.46	0
10/13/2003 05:00:00	55.3	57.8	53	78.39	0
10/13/2003 06:00:00	55.1	56.3	52.8	76.67	0
10/13/2003 07:00:00	51.6	53.2	50.3	86.3	0
10/13/2003 08:00:00	55.8	60.6	51.2	81.9	0
10/13/2003 09:00:00	62	63.3	60.5	62.18	0
10/13/2003 10:00:00	64.6	65.9	63	54.9	0
10/13/2003 11:00:00	66.7	67.7	65.5	48.23	0
10/13/2003 12:00:00	68.6	70.2	67.5	44.38	0
10/13/2003 13:00:00	70.5	71.5	69.7	42.08	0
10/13/2003 14:00:00	72	73	71.3	39.13	0
10/13/2003 15:00:00	72.5	73.2	71.7	37.51	0
10/13/2003 16:00:00	72.9	74.1	71.9	37.03	0
10/13/2003 17:00:00	70.5	73.1	67.7	44.83	0
10/13/2003 18:00:00	63.6	67.7	60.4	64.13	0
10/13/2003 19:00:00	58.2	60.8	56.1	81.3	0
10/13/2003 20:00:00	54.8	56.5	52.6	89.6	0
10/13/2003 21:00:00	52.6	53.3	51.8	95.1	0
10/13/2003 22:00:00	51.7	53	50.2	96.6	0
10/13/2003 23:00:00	50.1	51.3	48.6	97.5	0

Date & Time	Average Temp (°F)	Maximum Temp (°F)	Minimum Temp (°F)	Relative Humidity (%)	Total Precip (in)
10/14/2003 00:00:00	49.5	50.6	48.5	97.7	0
10/14/2003 01:00:00	48.4	49	47.9	98.1	0
10/14/2003 02:00:00	48.1	48.9	47.6	98.5	0
10/14/2003 03:00:00	47.8	48.6	47.2	98.6	0
10/14/2003 04:00:00	48.5	49.8	47.4	98.7	0
10/14/2003 05:00:00	48.9	49.7	48.4	98.6	0
10/14/2003 06:00:00	49.2	49.8	48.6	98.2	0
10/14/2003 07:00:00	50.2	51.4	49.5	98.4	0
10/14/2003 08:00:00	53.5	57.6	49.6	97.8	0
10/14/2003 09:00:00	58.2	58.8	57	93.2	0
10/14/2003 10:00:00	59.4	61.5	58.2	90.9	0
10/14/2003 11:00:00	62.1	63.4	60.9	76.27	0
10/14/2003 12:00:00	64.8	66.8	63.1	68.16	0
10/14/2003 13:00:00	66.3	66.8	65.8	62.79	0
10/14/2003 14:00:00	67.1	67.9	66	65.61	0
10/14/2003 15:00:00	67.4	67.9	66.9	61.98	0
10/14/2003 16:00:00	66.9	67.7	65.6	62.65	0
10/14/2003 17:00:00	66.6	67.1	65.9	64.35	0
10/14/2003 18:00:00	66.7	67.2	66	59.18	0
10/14/2003 19:00:00	64.4	66.3	61.6	66.71	0.01
10/14/2003 20:00:00	60.9	62.3	59.6	85.4	0.06
10/14/2003 21:00:00	59.8	60.9	59.1	96.7	0.54
10/14/2003 22:00:00	60.6	62.6	58.8	97.3	0.58
10/14/2003 23:00:00	59	59.4	58.6	97.4	0.09

Date & Time	Average Temp (°F)	Maximum Temp (°F)	Minimum Temp (°F)	Relative Humidity (%)	Total Precip (in)
10/15/2003 00:00:00	59.4	59.8	58.9	95.9	0.05
10/15/2003 01:00:00	58.6	59.4	58.2	95.2	0.06
10/15/2003 02:00:00	58.4	59	57.8	95.9	0
10/15/2003 03:00:00	58.2	59.6	56.6	84	0
10/15/2003 04:00:00	56.9	57.7	56.3	76.63	0
10/15/2003 05:00:00	57.5	58.1	56.6	68.15	0
10/15/2003 06:00:00	56.9	57.5	56.3	68.6	0
10/15/2003 07:00:00	57.1	58.4	56.4	67.96	0
10/15/2003 08:00:00	59.3	61.1	57.9	62.94	0
10/15/2003 09:00:00	61.1	61.8	60.2	56.07	0
10/15/2003 10:00:00	61.6	62.8	60.4	49.26	0
10/15/2003 11:00:00	61.6	63.6	60.6	45.58	0
10/15/2003 12:00:00	62.1	63.1	61.4	37.39	0
10/15/2003 13:00:00	62.3	63.2	61.6	34.49	0
10/15/2003 14:00:00	62.3	63.4	61.3	35.6	0
10/15/2003 15:00:00	62.1	62.9	60.9	34.25	0
10/15/2003 16:00:00	61.9	62.6	61.4	32	0
10/15/2003 17:00:00	60.9	62.1	59.5	32.13	0
10/15/2003 18:00:00	57.9	59.7	56.2	38.03	0
10/15/2003 19:00:00	54	56.6	51.4	48.83	0
10/15/2003 20:00:00	51.5	52.3	50.3	56.15	0
10/15/2003 21:00:00	49.4	50.7	48.4	62.51	0
10/15/2003 22:00:00	49.1	51	46.7	61.25	0
10/15/2003 23:00:00	46.1	47.1	44.7	70.62	0

Date & Time	Average Temp (°F)	Maximum Temp (°F)	Minimum Temp (°F)	Relative Humidity (%)	Total Precip (in)
10/16/2003 00:00:00	45.3	47.6	42.9	74.08	0
10/16/2003 01:00:00	45	46.1	43.3	76.85	0
10/16/2003 02:00:00	43.2	44.3	42.5	85.9	0
10/16/2003 03:00:00	44	45.3	43	81.6	0
10/16/2003 04:00:00	45	46.3	44.1	79.04	0
10/16/2003 05:00:00	45.1	46.3	43.7	79.29	0
10/16/2003 06:00:00	44.6	45.2	43.9	80.2	0
10/16/2003 07:00:00	45	46.4	44.1	78.73	0
10/16/2003 08:00:00	49.5	52.4	46.3	73.12	0
10/16/2003 09:00:00	55.3	58	52.1	61.45	0
10/16/2003 10:00:00	60.4	62	57.8	49.01	0
10/16/2003 11:00:00	63.1	64.9	61.6	44.5	0
10/16/2003 12:00:00	65.9	67.1	64.3	40.73	0
10/16/2003 13:00:00	67.4	68.6	66	38.93	0
10/16/2003 14:00:00	68.6	70.2	67.2	38.51	0
10/16/2003 15:00:00	69.5	70	69	37.41	0
10/16/2003 16:00:00	68.3	69.1	66.3	42.96	0
10/16/2003 17:00:00	66	66.9	65	48.21	0
10/16/2003 18:00:00	63.8	65.2	62.8	54.51	0
10/16/2003 19:00:00	61.1	63.2	59.5	54.05	0
10/16/2003 20:00:00	57.7	59.8	55.9	60.26	0
10/16/2003 21:00:00	54	56.2	52.7	72.68	0
10/16/2003 22:00:00	53.2	53.6	52.7	79.79	0
10/16/2003 23:00:00	53.5	54.5	52.9	81.2	0

Date & Time	Average Temp (°F)	Maximum Temp (°F)	Minimum Temp (°F)	Relative Humidity (%)	Total Precip (in)
10/17/2003 00:00:00	52.7	53.4	52	84.5	0
10/17/2003 01:00:00	51.4	52.8	50.1	88.4	0
10/17/2003 02:00:00	50.9	51.3	50.3	91.9	0
10/17/2003 03:00:00	50.5	51.7	49.1	90.6	0
10/17/2003 04:00:00	50.3	51.2	49.1	89.5	0
10/17/2003 05:00:00	50.5	51.2	49.6	87.9	0
10/17/2003 06:00:00	50	51	48.5	87.7	0
10/17/2003 07:00:00	49.6	50.8	48.6	90.5	0
10/17/2003 08:00:00	51.8	53	50.6	86.9	0
10/17/2003 09:00:00	54.1	55.8	52.5	82	0
10/17/2003 10:00:00	55.4	56	54.7	75.27	0
10/17/2003 11:00:00	55.8	56.4	55.3	73.27	0
10/17/2003 12:00:00	55.6	56.3	55.2	71.2	0
10/17/2003 13:00:00	56.6	57.7	55.7	69.08	0
10/17/2003 14:00:00	58.1	59	57.3	66.98	0
10/17/2003 15:00:00	57.6	58.4	56.8	68.63	0
10/17/2003 16:00:00	56.8	57.2	56.5	70.86	0
10/17/2003 17:00:00	55.3	56.7	54.2	80.1	0
10/17/2003 18:00:00	53.6	54.7	52.8	85.7	0
10/17/2003 19:00:00	52.2	53.3	51.1	88.5	0.01
10/17/2003 20:00:00	50.7	51.5	49.7	92.8	0.02
10/17/2003 21:00:00	49.3	50.2	48.8	94.7	0.02
10/17/2003 22:00:00	48.8	49.3	48.4	93.5	0
10/17/2003 23:00:00	48.3	48.6	47.8	93.3	0

Date & Time	Average Temp (°F)	Maximum Temp (°F)	Minimum Temp (°F)	Relative Humidity (%)	Total Precip (in)
10/18/2003 00:00:00	48.1	48.4	47.8	94	0
10/18/2003 01:00:00	48.1	48.4	47.8	94.7	0
10/18/2003 02:00:00	47.4	48.3	46.4	94.9	0
10/18/2003 03:00:00	46	46.7	44.9	96.3	0
10/18/2003 04:00:00	44.8	45.3	43.7	97.6	0
10/18/2003 05:00:00	44.8	45.4	44.1	97.9	0
10/18/2003 06:00:00	44.3	44.8	43.8	98.5	0
10/18/2003 07:00:00	44.2	44.8	43.8	98.7	0
10/18/2003 08:00:00	45.4	48.3	43.7	98.6	0
10/18/2003 09:00:00	49.8	51.9	47.4	87.3	0
10/18/2003 10:00:00	53.3	55	51.2	70.82	0
10/18/2003 11:00:00	56	57.2	54.5	53.7	0
10/18/2003 12:00:00	56.9	57.9	55.9	48.82	0
10/18/2003 13:00:00	58.6	59.7	57.6	40.83	0
10/18/2003 14:00:00	58.6	59.7	57.2	37.97	0
10/18/2003 15:00:00	59	60.2	57.9	39.36	0
10/18/2003 16:00:00	58.8	59.8	58.2	39.33	0
10/18/2003 17:00:00	57.4	58.6	56.2	41.5	0
10/18/2003 18:00:00	52	56.5	48.7	61.14	0
10/18/2003 19:00:00	47.2	49.8	44.7	79.42	0
10/18/2003 20:00:00	44.1	45	42.9	90.4	0
10/18/2003 21:00:00	42.5	43.5	41.1	94.2	0
10/18/2003 22:00:00	41.9	42.3	41.2	96.5	0
10/18/2003 23:00:00	41.5	42.3	40.9	96.7	0

Date & Time	Average Temp (°F)	Maximum Temp (°F)	Minimum Temp (°F)	Relative Humidity (%)	Total Precip (in)
10/19/2003 00:00:00	41.4	41.8	41	97.7	0
10/19/2003 01:00:00	42.4	43.4	41.3	97.9	0
10/19/2003 02:00:00	44	44.8	43.1	96.8	0
10/19/2003 03:00:00	45.4	46.3	44.6	95.9	0
10/19/2003 04:00:00	46.3	47	45.8	95.4	0
10/19/2003 05:00:00	47.1	48.3	46.4	96.3	0
10/19/2003 06:00:00	50.2	51	48.3	80.5	0
10/19/2003 07:00:00	51.7	52.6	50.8	75.4	0
10/19/2003 08:00:00	53	53.7	52.1	67.44	0
10/19/2003 09:00:00	54.4	55.6	52.7	67.01	0
10/19/2003 10:00:00	57	59.9	54.6	61.51	0
10/19/2003 11:00:00	62.4	63.8	59.6	53.53	0
10/19/2003 12:00:00	63.4	65.3	62.2	48.72	0
10/19/2003 13:00:00	65.1	66.3	63.6	44.24	0
10/19/2003 14:00:00	65.6	67.1	64.2	41.7	0
10/19/2003 15:00:00	65.6	66.4	64.1	38.45	0
10/19/2003 16:00:00	64.9	65.6	64	38.83	0
10/19/2003 17:00:00	63.4	64.5	61.8	41.49	0
10/19/2003 18:00:00	58.6	62	56.2	54.36	0
10/19/2003 19:00:00	53.5	56.7	49.8	69.72	0
10/19/2003 20:00:00	49.9	52	48.5	79.79	0
10/19/2003 21:00:00	47.8	50.4	45.3	86	0
10/19/2003 22:00:00	46.1	48.8	44.9	88.3	0
10/19/2003 23:00:00	47.2	49.1	44.8	80	0

Date & Time	Average Temp (°F)	Maximum Temp (°F)	Minimum Temp (°F)	Relative Humidity (%)	Total Precip (in)
10/20/2003 00:00:00	47.3	48.3	46.3	79.55	0
10/20/2003 01:00:00	46.3	47.5	45.1	81.4	0
10/20/2003 02:00:00	45.6	46.5	44.9	82.2	0
10/20/2003 03:00:00	44.2	46	41.5	85.4	0
10/20/2003 04:00:00	41	41.8	40.1	95.7	0
10/20/2003 05:00:00	40.5	42.1	38.8	96.4	0
10/20/2003 06:00:00	39.2	39.9	38.1	97.7	0
10/20/2003 07:00:00	38.7	39.8	37.8	98.5	0
10/20/2003 08:00:00	45	49.5	39.4	92.6	0
10/20/2003 09:00:00	50.9	52.2	49.3	78.03	0
10/20/2003 10:00:00	53.8	55.6	51.9	67.64	0
10/20/2003 11:00:00	55.7	56.6	54.7	65.53	0
10/20/2003 12:00:00	58.3	60.3	56.5	59.89	0
10/20/2003 13:00:00	60.7	61.8	59.6	60.4	0
10/20/2003 14:00:00	61.1	61.9	60.4	62.19	0
10/20/2003 15:00:00	61.8	62.4	61.3	61.34	0
10/20/2003 16:00:00	61.7	62.2	61	62.69	0
10/20/2003 17:00:00	59.9	61.7	57.1	68.05	0
10/20/2003 18:00:00	54.9	57.2	52.9	82.6	0
10/20/2003 19:00:00	52.1	53.2	50.9	91.6	0
10/20/2003 20:00:00	50.5	52.1	49.6	95	0
10/20/2003 21:00:00	50.1	53	48.6	97.3	0
10/20/2003 22:00:00	52.5	53.8	49.9	97	0
10/20/2003 23:00:00	54.1	55.8	52.8	95.9	0

Date & Time	Average Temp (°F)	Maximum Temp (°F)	Minimum Temp (°F)	Relative Humidity (%)	Total Precip (in)
10/21/2003 00:00:00	56.2	58.2	54.7	95.4	0
10/21/2003 01:00:00	58.4	59.6	57	93	0
10/21/2003 02:00:00	58.7	59.7	57.6	92.8	0
10/21/2003 03:00:00	59.3	59.9	58.6	91	0
10/21/2003 04:00:00	60	60.6	59.5	83.3	0
10/21/2003 05:00:00	61	61.8	60.1	76.24	0
10/21/2003 06:00:00	60.9	61.5	60.4	76.52	0
10/21/2003 07:00:00	60.8	61.4	60.3	79.51	0
10/21/2003 08:00:00	62	63.2	60.9	77.63	0
10/21/2003 09:00:00	63.9	65.2	62.8	73.79	0
10/21/2003 10:00:00	65.7	66.8	64.2	69.71	0
10/21/2003 11:00:00	68.2	70	66.3	64.61	0
10/21/2003 12:00:00	70.2	70.8	69.5	60.71	0
10/21/2003 13:00:00	70.9	72	70.1	61.1	0
10/21/2003 14:00:00	72.1	72.4	71.6	58.93	0
10/21/2003 15:00:00	71.6	72.1	71	62.39	0
10/21/2003 16:00:00	69.7	71.2	68.2	68.65	0
10/21/2003 17:00:00	67.5	69	66.5	73.14	0
10/21/2003 18:00:00	67.3	67.7	66.8	72.37	0
10/21/2003 19:00:00	68.2	69.4	67.2	67.6	0
10/21/2003 20:00:00	69.2	69.9	68.6	53.48	0
10/21/2003 21:00:00	67.9	68.8	67	54.01	0
10/21/2003 22:00:00	65.1	67.4	61.8	58.37	0
10/21/2003 23:00:00	61.3	62.1	60.4	70.99	0

Date & Time	Average Temp (°F)	Maximum Temp (°F)	Minimum Temp (°F)	Relative Humidity (%)	Total Precip (in)
10/22/2003 00:00:00	59.7	61	58.4	77.06	0
10/22/2003 01:00:00	58.9	59.8	58.2	78.13	0
10/22/2003 02:00:00	58.8	59.8	57.6	73.63	0
10/22/2003 03:00:00	57	58	56.1	78.07	0
10/22/2003 04:00:00	55.9	56.5	55.2	81.1	0
10/22/2003 05:00:00	54.8	56.3	52.9	82.6	0
10/22/2003 06:00:00	52.8	53.6	52.3	84.6	0
10/22/2003 07:00:00	52.1	52.6	51.4	81.9	0
10/22/2003 08:00:00	53.1	54.1	51.5	76.09	0
10/22/2003 09:00:00	54.7	55.9	53.8	73.2	0
10/22/2003 10:00:00	56.6	57.3	55.6	60.99	0
10/22/2003 11:00:00	58.2	60	56.6	54.83	0
10/22/2003 12:00:00	57.4	58.6	56.4	57.11	0
10/22/2003 13:00:00	57.4	59.6	56.4	57.89	0
10/22/2003 14:00:00	56.6	59.6	53	57.29	0
10/22/2003 15:00:00	53.4	54	52.9	67.26	0
10/22/2003 16:00:00	53.8	55.2	53	60.9	0
10/22/2003 17:00:00	52.7	53.6	51.7	55.96	0
10/22/2003 18:00:00	50.4	52.1	49	55.99	0
10/22/2003 19:00:00	47.8	49.1	47	62.61	0
10/22/2003 20:00:00	47	47.6	46.5	64.2	0
10/22/2003 21:00:00	46.4	47.1	45.6	63.04	0
10/22/2003 22:00:00	45.1	46.1	44.2	64.12	0
10/22/2003 23:00:00	44.4	44.9	43.7	57.34	0

Date & Time	Average Temp (°F)	Maximum Temp (°F)	Minimum Temp (°F)	Relative Humidity (%)	Total Precip (in)
10/23/2003 00:00:00	43.5	44.5	42.1	59.12	0
10/23/2003 01:00:00	42.3	42.9	41.8	66.12	0
10/23/2003 02:00:00	42	42.4	41.2	64.67	0
10/23/2003 03:00:00	41.1	42.2	39.9	60.97	0
10/23/2003 04:00:00	39.3	40.2	37.6	64.36	0
10/23/2003 05:00:00	37	38.1	36.2	74.28	0
10/23/2003 06:00:00	36.2	36.9	35.7	76.52	0
10/23/2003 07:00:00	36.2	37.8	35	78.67	0
10/23/2003 08:00:00	39.7	41.5	37.5	70.46	0
10/23/2003 09:00:00	42.9	44.8	41.2	60.1	0
10/23/2003 10:00:00	45.4	46.7	44.1	47.69	0
10/23/2003 11:00:00	44.8	45.5	44.1	43.87	0
10/23/2003 12:00:00	45.7	46.7	44.3	40.99	0
10/23/2003 13:00:00	45.4	46.1	44.9	43.86	0
10/23/2003 14:00:00	47.3	49.5	45	43.51	0
10/23/2003 15:00:00	47.3	48.9	46.1	43.71	0
10/23/2003 16:00:00	46.6	47.1	46.2	43.78	0
10/23/2003 17:00:00	46.9	47.7	46.1	44.3	0
10/23/2003 18:00:00	44	46.2	41.4	54.06	0
10/23/2003 19:00:00	39.1	41.7	37.4	73.81	0
10/23/2003 20:00:00	35.9	38.1	34.2	85.6	0
10/23/2003 21:00:00	35.6	37.4	33.9	87.9	0
10/23/2003 22:00:00	35.6	36.9	33.8	85	0
10/23/2003 23:00:00	34.7	37.2	33.1	86.5	0

Date & Time	Average Temp (°F)	Maximum Temp (°F)	Minimum Temp (°F)	Relative Humidity (%)	Total Precip (in)
10/24/2003 00:00:00	33	35.2	31.8	90.5	0
10/24/2003 01:00:00	31.7	33	30.8	94.7	0
10/24/2003 02:00:00	31.1	33	30.5	95	0
10/24/2003 03:00:00	30.6	31.4	29.9	96.5	0
10/24/2003 04:00:00	30.7	32.4	29.6	97	0
10/24/2003 05:00:00	33.2	34.2	32.1	92.2	0
10/24/2003 06:00:00	33.8	35	32.3	85.5	0
10/24/2003 07:00:00	34.6	35.5	33.9	80.1	0
10/24/2003 08:00:00	37.3	40.3	35.3	75.9	0
10/24/2003 09:00:00	43.4	46.5	39.9	65.98	0.01
10/24/2003 10:00:00	48.3	50.2	46.3	54.67	0
10/24/2003 11:00:00	51.5	52.6	49.7	48.88	0
10/24/2003 12:00:00	53.7	55.3	52	46.17	0
10/24/2003 13:00:00	54.6	55.9	53.5	43.21	0
10/24/2003 14:00:00	55.2	57.5	54	43.19	0
10/24/2003 15:00:00	56.2	57.6	54.4	42.75	0
10/24/2003 16:00:00	55.1	56.1	54.4	44.07	0
10/24/2003 17:00:00	54	55.1	51.9	48.64	0
10/24/2003 18:00:00	48.2	52.2	44.3	66.22	0
10/24/2003 19:00:00	43.4	44.8	42	81.5	0
10/24/2003 20:00:00	41	42.3	39.3	89.1	0
10/24/2003 21:00:00	39.3	41	38.1	92.7	0
10/24/2003 22:00:00	37.9	39	37.2	96.4	0
10/24/2003 23:00:00	37.3	38	36.7	97.9	0

APPENDIX C. SOIL MOISTURE

Daily Soil Moisture Logs

Demonstrator: GTEK
Date: October 14, 2003
Times: No AM Readings, 1600 hours

Probe Location:	Layer, in.	AM Reading, %	PM Reading, %
Wet Area	0 to 6	No Readings Taken	
	6 to 12		
	12 to 24		
	24 to 36		
	36 to 48		No Readings Taken
Wooded Area	0 to 6	No Readings Taken	
	6 to 12		
	12 to 24		
	24 to 36		
	36 to 48		No Readings Taken
Open Area	0 to 6	No Readings Taken	
	6 to 12		
	12 to 24		
	24 to 36		
	36 to 48		No Readings Taken
Calibration Lanes	0 to 6	No Readings Taken	39.5
	6 to 12		37.7
	12 to 24		0.8
	24 to 36		4.5
	36 to 48		4.6
Blind Grid/Moguls	0 to 6	No Readings Taken	2.7
	6 to 12		23.4
	12 to 24		36.6
	24 to 36		35.8
	36 to 48		37.9

Demonstrator: GTEK
Date: October 15, 2003
Times: 0800 hours, 1600 hours

Probe Location:	Layer, in.	AM Reading, %	PM Reading, %
Wet Area	0 to 6	60.2	59.1
	6 to 12	73.1	73.6
	12 to 24	76.8	76.3
	24 to 36	53.7	54.0
	36 to 48	48.4	49.1
Wooded Area	0 to 6	No Readings Taken	No Readings Taken
	6 to 12		
	12 to 24		
	24 to 36		
	36 to 48		
Open Area	0 to 6	22.1	20.2
	6 to 12	6.3	5.7
	12 to 24	16.8	17.3
	24 to 36	26.7	26.1
	36 to 48	49.9	51.3
Calibration Lanes	0 to 6	No Readings Taken	No Readings Taken
	6 to 12		
	12 to 24		
	24 to 36		
	36 to 48		
Blind Grid/Moguls	0 to 6	No Readings Taken	No Readings Taken
	6 to 12		
	12 to 24		
	24 to 36		
	36 to 48		

Demonstrator: GTEK
Date: October 16, 2003
Times: 0830 hours, 1445 hours

Probe Location:	Layer, in.	AM Reading, %	PM Reading, %
Wet Area	0 to 6	69.4	70.1
	6 to 12	73.1	73.8
	12 to 24	71.9	70.9
	24 to 36	54.8	54.2
	36 to 48	50.1	49.7
Wooded Area	0 to 6	No Readings Taken	No Readings Taken
	6 to 12		
	12 to 24		
	24 to 36		
	36 to 48		
Open Area	0 to 6	18.1	17.6
	6 to 12	0.3	0.3
	12 to 24	18.9	18.7
	24 to 36	21.9	21.6
	36 to 48	29.3	29.7
Calibration Lanes	0 to 6	No Readings Taken	No Readings Taken
	6 to 12		
	12 to 24		
	24 to 36		
	36 to 48		
Blind Grid/Moguls	0 to 6	No Readings Taken	No Readings Taken
	6 to 12		
	12 to 24		
	24 to 36		
	36 to 48		

Demonstrator: GTEK
Date: October 17, 2003
Times: 0825 hours, 1345 hours

Probe Location:	Layer, in.	AM Reading, %	PM Reading, %
Wet Area	0 to 6	70.2	70.8
	6 to 12	72.5	73.1
	12 to 24	72.2	71.8
	24 to 36	52.6	53.1
	36 to 48	49.1	48.8
Wooded Area	0 to 6	No Readings Taken	No Readings Taken
	6 to 12		
	12 to 24		
	24 to 36		
	36 to 48		
Open Area	0 to 6	16.5	16.6
	6 to 12	0.2	0.4
	12 to 24	19.2	18.9
	24 to 36	22.3	21.9
	36 to 48	29.8	29.9
Calibration Lanes	0 to 6	No Readings Taken	No Readings Taken
	6 to 12		
	12 to 24		
	24 to 36		
	36 to 48		
Blind Grid/Moguls	0 to 6	No Readings Taken	No Readings Taken
	6 to 12		
	12 to 24		
	24 to 36		
	36 to 48		

Demonstrator: GTEK
Date: October 18, 2003
Times: 0845 hours, 1400 hours

Probe Location:	Layer, in.	AM Reading, %	PM Reading, %
Wet Area	0 to 6	69.3	69.1
	6 to 12	71.3	72.8
	12 to 24	71.8	71.2
	24 to 36	52.5	53.5
	36 to 48	49.7	50.1
Wooded Area	0 to 6	No Readings Taken	No Readings Taken
	6 to 12		
	12 to 24		
	24 to 36		
	36 to 48		
Open Area	0 to 6	15.7	15.6
	6 to 12	0.3	0.4
	12 to 24	18.3	18.9
	24 to 36	21.8	21.2
	36 to 48	29.3	29.1
Calibration Lanes	0 to 6	No Readings Taken	No Readings Taken
	6 to 12		
	12 to 24		
	24 to 36		
	36 to 48		
Blind Grid/Moguls	0 to 6	No Readings Taken	No Readings Taken
	6 to 12		
	12 to 24		
	24 to 36		
	36 to 48		

Demonstrator: GTEK
Date: October 20, 2003
Times: 0800 hours, 1400 hours

Probe Location:	Layer, in.	AM Reading, %	PM Reading, %
Wet Area	0 to 6	78.6	78.1
	6 to 12	75.3	75.0
	12 to 24	68.7	69.0
	24 to 36	51.8	52.1
	36 to 48	48.1	48.2
Wooded Area	0 to 6	No Readings Taken	No Readings Taken
	6 to 12		
	12 to 24		
	24 to 36		
	36 to 48		
Open Area	0 to 6	12.4	12.2
	6 to 12	2.1	2.3
	12 to 24	14.6	14.4
	24 to 36	20.8	20.8
	36 to 48	25.6	25.3
Calibration Lanes	0 to 6	No Readings Taken	No Readings Taken
	6 to 12		
	12 to 24		
	24 to 36		
	36 to 48		
Blind Grid/Moguls	0 to 6	No Readings Taken	No Readings Taken
	6 to 12		
	12 to 24		
	24 to 36		
	36 to 48		

Demonstrator: GTEK
Date: October 21, 2003
Times: 0800 hours, 1400 hours

Probe Location:	Layer, in.	AM Reading, %	PM Reading, %
Wet Area	0 to 6	77.8	77.6
	6 to 12	75.8	75.9
	12 to 24	69.3	69.2
	24 to 36	52.3	52.4
	36 to 48	49.3	49.7
Wooded Area	0 to 6	No Readings Taken	No Readings Taken
	6 to 12		
	12 to 24		
	24 to 36		
	36 to 48		
Open Area	0 to 6	11.9	11.9
	6 to 12	2.2	2.4
	12 to 24	14.7	14.5
	24 to 36	21.2	21.3
	36 to 48	26.3	26.1
Calibration Lanes	0 to 6	No Readings Taken	No Readings Taken
	6 to 12		
	12 to 24		
	24 to 36		
	36 to 48		
Blind Grid/Moguls	0 to 6	No Readings Taken	No Readings Taken
	6 to 12		
	12 to 24		
	24 to 36		
	36 to 48		

Demonstrator: GTEK
Date: October 22, 2003
Times: 0800 hours, 1400 hours

Probe Location:	Layer, in.	AM Reading, %	PM Reading, %
Wet Area	0 to 6	No Readings Taken	No Readings Taken
	6 to 12		
	12 to 24		
	24 to 36		
	36 to 48		
Wooded Area	0 to 6	11.8	12.2
	6 to 12	5.7	5.1
	12 to 24	4.3	4.4
	24 to 36	51.8	51.4
	36 to 48	54.3	53.9
Open Area	0 to 6	No Readings Taken	No Readings Taken
	6 to 12		
	12 to 24		
	24 to 36		
	36 to 48		
Calibration Lanes	0 to 6	No Readings Taken	No Readings Taken
	6 to 12		
	12 to 24		
	24 to 36		
	36 to 48		
Blind Grid/Moguls	0 to 6	4.4	4.5
	6 to 12	9.6	9.3
	12 to 24	34.8	34.9
	24 to 36	36.7	36.2
	36 to 48	38.5	38.8

Demonstrator: GTEK
Date: October 23, 2003
Times: 0800 hours, 1400 hours

Probe Location:	Layer, in.	AM Reading, %	PM Reading, %
Wet Area	0 to 6	No Readings Taken	No Readings Taken
	6 to 12		
	12 to 24		
	24 to 36		
	36 to 48		
Wooded Area	0 to 6	12.1	12.0
	6 to 12	6.2	5.9
	12 to 24	4.7	4.4
	24 to 36	52.3	52.0
	36 to 48	54.7	54.2
Open Area	0 to 6	No Readings Taken	No Readings Taken
	6 to 12		
	12 to 24		
	24 to 36		
	36 to 48		
Calibration Lanes	0 to 6	No Readings Taken	No Readings Taken
	6 to 12		
	12 to 24		
	24 to 36		
	36 to 48		
Blind Grid/Moguls	0 to 6	4.3	4.1
	6 to 12	9.5	9.4
	12 to 24	34.8	35.0
	24 to 36	36.3	36.2
	36 to 48	38.1	37.8

Demonstrator: GTEK
Date: October 24, 2003
Times: 0800 hours, 1400 hours

Probe Location:	Layer, in.	AM Reading, %	PM Reading, %
Wet Area	0 to 6	No Readings Taken	No Readings Taken
	6 to 12		
	12 to 24		
	24 to 36		
	36 to 48		
Wooded Area	0 to 6	12.2	11.9
	6 to 12	6.7	6.4
	12 to 24	4.8	4.9
	24 to 36	52.7	52.4
	36 to 48	55.2	54.6
Open Area	0 to 6	No Readings Taken	No Readings Taken
	6 to 12		
	12 to 24		
	24 to 36		
	36 to 48		
Calibration Lanes	0 to 6	No Readings Taken	39.2
	6 to 12		36.2
	12 to 24		0.5
	24 to 36		4.1
	36 to 48		3.8
Blind Grid/Moguls	0 to 6	4.5	4.0
	6 to 12	9.7	9.7
	12 to 24	34.9	34.5
	24 to 36	36.7	36.2
	36 to 48	38.4	38.7

Date	No. of People	Area Tested	Status Start Time	Status Stop Time	Duration, min	Operational Status	Operational Status - Comments	Track Method	Track Method = Other Explain	Pattern	Field Conditions	
TM-5 EMU DUAL SENSOR												
10/14/2003	2	CALIBRATION LANE	1015	1300	165	INITIAL SET UP	INITIAL SET UP	GPS	NA	LINEAR	CLOUDY	MUDDY
10/14/2003	2	CALIBRATION LANE	1300	1310	10	CALIBRATE	CALIBRATE EQUIPMENT USING METAL OBJECTS	GPS	NA	LINEAR	CLOUDY	MUDDY
10/14/2003	2	CALIBRATION LANE	1310	1430	80	COLLECT DATA	COLLECT DATA	GPS	NA	LINEAR	CLOUDY	MUDDY
10/14/2003	2	CALIBRATION LANE	1430	1440	10	DOWNTIME MAINTENANCE CHECK	CHANGE BATTERY	GPS	NA	LINEAR	CLOUDY	MUDDY
10/14/2003	2	BLIND TEST GRID	1440	1530	50	COLLECT DATA	COLLECT DATA	GPS	NA	LINEAR	CLOUDY	MUDDY
10/14/2003	2	BLIND TEST GRID	1530	1540	10	BREAK/LUNCH	BREAK/LUNCH	GPS	NA	LINEAR	CLOUDY	MUDDY
10/14/2003	2	BLIND TEST GRID	1540	1600	20	COLLECT DATA	COLLECT DATA	GPS	NA	LINEAR	CLOUDY	MUDDY
10/14/2003	2	BLIND TEST GRID	1600	1630	30	CALIBRATE	CALIBRATE EQUIPMENT USING METAL OBJECTS	GPS	NA	LINEAR	CLOUDY	MUDDY
10/14/2003	2	BLIND TEST GRID	1630	1745	75	DOWNTIME MAINTENANCE CHECK	CHECKED GPS EQUIPMENT	GPS	NA	LINEAR	CLOUDY	MUDDY
10/14/2003	2	BLIND TEST GRID	1745	1815	30	DAILY START/STOP	EQUIPMENT BREAKDOWN/ END OF DAILY OPERATIONS	GPS	NA	LINEAR	WINDY	MUDDY

Date	No. of People	Area Tested	Status Start Time	Status Stop Time	Duration, min	Operational Status	Operational Status - Comments	Track Method	Track Method = Other Explain	Pattern	Field Conditions	
TM-5 EMU DUAL SENSOR												
10/15/2003	2	OPEN FIELD	0800	1015	135	DAILY START/STOP	START OF DAILY OPERATIONS	GPS	NA	LINEAR	WINDY	MUDDY
10/15/2003	2	OPEN FIELD	1015	1100	45	DAILY START/STOP	SET UP SPACING WITH TAPES	GPS	NA	LINEAR	WINDY	MUDDY
10/15/2003	2	OPEN FIELD	1100	1115	15	CALIBRATE	CALIBRATE EQUIPMENT USING METAL OBJECTS	GPS	NA	LINEAR	WINDY	MUDDY
10/15/2003	2	OPEN FIELD	1115	1245	90	COLLECT DATA	COLLECT DATA	GPS	NA	LINEAR	WINDY	MUDDY
10/15/2003	2	OPEN FIELD	1245	1300	45	DOWNTIME MAINTENANCE CHECK	EQUIPMENT CHECK, PUT TAPE ON SENSORS TO PREVENT WATER DAMAGE	GPS	NA	LINEAR	WINDY	MUDDY
10/15/2003	2	OPEN FIELD	1300	1400	60	COLLECT DATA	COLLECT DATA	GPS	NA	LINEAR	WINDY	MUDDY
10/15/2003	2	OPEN FIELD	1400	1405	5	COLLECT DATA	COLLECT DATA	GPS	NA	LINEAR	WINDY	MUDDY
10/15/2003	2	OPEN FIELD	1405	1710	185	COLLECT DATA	COLLECT DATA	GPS	NA	LINEAR	WINDY	MUDDY
10/15/2003	2	OPEN FIELD	1710	1800	50	DAILY START/STOP	EQUIPMENT BREAKDOWN/ END OF DAILY OPERATIONS	GPS	NA	LINEAR	SUNNY	MUDDY

Date	No. of People	Area Tested	Status Start Time	Status Stop Time	Duration, min	Operational Status	Operational Status - Comments	Track Method	Track Method = Other Explain	Pattern	Field Conditions	
TM-5 EMU DUAL SENSOR												
10/16/2003	2	OPEN FIELD	0800	0845	45	DAILY START/STOP	START OF DAILY OPERATIONS	GPS	NA	LINEAR	SUNNY	MUDDY
10/16/2003	2	OPEN FIELD	0845	0900	15	CALIBRATE	CALIBRATE EQUIPMENT USING METAL OBJECTS	GPS	NA	LINEAR	SUNNY	MUDDY
10/16/2003	2	OPEN FIELD	0900	1010	70	COLLECT DATA	COLLECT DATA	GPS	NA	LINEAR	SUNNY	MUDDY
10/16/2003	2	OPEN FIELD	1010	1020	10	DOWNTIME MAINTENANCE CHECK	CHANGE BATTERY	GPS	NA	LINEAR	SUNNY	MUDDY
10/16/2003	2	OPEN FIELD	1020	1310	170	COLLECT DATA	COLLECT DATA	GPS	NA	LINEAR	SUNNY	MUDDY
10/16/2003	2	OPEN FIELD	1310	1315	5	DOWNTIME MAINTENANCE CHECK	CHANGE BATTERY	GPS	NA	LINEAR	SUNNY	MUDDY
10/16/2003	2	OPEN FIELD	1315	1700	225	COLLECT DATA	COLLECT DATA	GPS	NA	LINEAR	SUNNY	MUDDY
10/16/2003	2	OPEN FIELD	1700	1730	30	DAILY START/STOP	EQUIPMENT BREAKDOWN/ END OF DAILY OPERATIONS	GPS	NA	LINEAR	SUNNY	MUDDY
10/17/2003	2	OPEN FIELD	0730	0850	80	DAILY START/STOP	START OF DAILY OPERATIONS	GPS	NA	LINEAR	SUNNY	MUDDY
10/17/2003	2	OPEN FIELD	0850	0910	20	DAILY START/STOP	SET UP SPACING TAPES	GPS	NA	LINEAR	SUNNY	MUDDY

Date	No. of People	Area Tested	Status Start Time	Status Stop Time	Duration, min	Operational Status	Operational Status - Comments	Track Method	Track Method = Other Explain	Pattern	Field Conditions	
TM-5 EMU DUAL SENSOR												
10/17/2003	2	OPEN FIELD	0910	0930	20	COLLECT DATA	COLLECT DATA	GPS	NA	LINEAR	SUNNY	MUDDY
10/17/2003	2	OPEN FIELD	0930	955	25	DAILY START/STOP	SET UP SPACING WITH TAPES	GPS	NA	LINEAR	SUNNY	MUDDY
10/17/2003	2	OPEN FIELD	0955	1100	65	COLLECT DATA	COLLECT DATA	GPS	NA	LINEAR	SUNNY	MUDDY
10/17/2003	2	OPEN FIELD	1100	1110	10	BREAK/LUNCH	BREAK/LUNCH	GPS	NA	LINEAR	SUNNY	MUDDY
10/17/2003	2	OPEN FIELD	1110	1140	30	COLLECT DATA	COLLECT DATA	GPS	NA	LINEAR	SUNNY	MUDDY
10/17/2003	2	OPEN FIELD	1140	1150	10	DOWNTIME MAINTENANCE CHECK	CHANGE BATTERY	GPS	NA	LINEAR	SUNNY	MUDDY
10/17/2003	2	OPEN FIELD	1150	1350	120	COLLECT DATA	COLLECT DATA	GPS	NA	LINEAR	SUNNY	MUDDY
10/17/2003	2	OPEN FIELD	1350	1410	20	DOWNTIME MAINTENANCE CHECK	CHANGE BATTERY	GPS	NA	LINEAR	SUNNY	MUDDY
10/17/2003	2	OPEN FIELD	1410	1600	110	COLLECT DATA	COLLECT DATA	GPS	NA	LINEAR	SUNNY	MUDDY
10/17/2003	2	OPEN FIELD	1600	1640	40	DAILY START/STOP	EQUIPMENT BREAKDOWN/ END OF DAILY OPERATIONS	GPS	NA	LINEAR	SUNNY	MUDDY

Date	No. of People	Area Tested	Status Start Time	Status Stop Time	Duration, min	Operational Status	Operational Status - Comments	Track Method	Track Method = Other Explain	Pattern	Field Conditions	
TM-5 EMU DUAL SENSOR												
10/18/2003	2	OPEN FIELD	0725	0810	45	DAILY START/STOP	START OF DAILY OPERATIONS	GPS	NA	LINEAR	SUNNY	MUDDY
10/18/2003	2	OPEN FIELD	0810	0840	30	CALIBRATE	CALIBRATE EQUIPMENT USING METAL OBJECTS	GPS	NA	LINEAR	SUNNY	MUDDY
10/18/2003	2	OPEN FIELD	0840	1040	120	COLLECT DATA	COLLECT DATA	GPS	NA	LINEAR	SUNNY	MUDDY
10/18/2003	2	OPEN FIELD	1040	1100	20	DOWNTIME MAINTENANCE CHECK	CHANGE BATTERY	GPS	NA	LINEAR	SUNNY	MUDDY
10/18/2003	2	OPEN FIELD	1100	1220	80	COLLECT DATA	COLLECT DATA	GPS	NA	LINEAR	SUNNY	MUDDY
10/18/2003	2	OPEN FIELD	1220	1230	10	BREAK/LUNCH	BREAK/LUNCH	GPS	NA	LINEAR	SUNNY	MUDDY
10/18/2003	2	OPEN FIELD	1230	1325	55	COLLECT DATA	COLLECT DATA	GPS	NA	LINEAR	SUNNY	MUDDY
10/18/2003	2	OPEN FIELD	1325	1335	10	DOWNTIME MAINTENANCE CHECK	CHANGE BATTERY	GPS	NA	LINEAR	SUNNY	MUDDY
10/18/2003	2	OPEN FIELD	1335	1605	150	COLLECT DATA	COLLECT DATA	GPS	NA	LINEAR	SUNNY	MUDDY
10/18/2003	2	OPEN FIELD	1605	1640	35	DAILY START/STOP	EQUIPMENT BREAKDOWN/ END OF DAILY OPERATIONS	GPS	NA	LINEAR	SUNNY	MUDDY

Date	No. of People	Area Tested	Status Start Time	Status Stop Time	Duration, min	Operational Status	Operational Status - Comments	Track Method	Track Method = Other Explain	Pattern	Field Conditions	
TM-5 EMU DUAL SENSOR												
10/20/2003	2	OPEN FIELD	0745	0830	45	DAILY START/STOP	START OF DAILY OPERATIONS	GPS	NA	LINEAR	SUNNY	MUDDY
10/20/2003	2	OPEN FIELD	830	0850	20	CALIBRATE	CALIBRATE EQUIPMENT USING METAL OBJECTS	GPS	NA	LINEAR	SUNNY	MUDDY
10/20/2003	2	OPEN FIELD	0850	1100	130	COLLECT DATA	COLLECT DATA	GPS	NA	LINEAR	SUNNY	MUDDY
10/20/2003	2	OPEN FIELD	1100	1105	5	DOWNTIME MAINTENANCE CHECK	CHANGE BATTERY	GPS	NA	LINEAR	SUNNY	MUDDY
10/20/2003	2	OPEN FIELD	1105	1115	10	COLLECT DATA	COLLECT DATA	GPS	NA	LINEAR	SUNNY	MUDDY
10/20/2003	2	OPEN FIELD	1115	1130	15	DOWNTIME MAINTENANCE CHECK	DATA CHECK	GPS	NA	LINEAR	SUNNY	MUDDY
10/20/2003	2	OPEN FIELD	1130	1300	90	COLLECT DATA	COLLECT DATA	GPS	NA	LINEAR	SUNNY	MUDDY
10/20/2003	2	OPEN FIELD	1300	1350	50	BREAK/LUNCH	BREAK/LUNCH	GPS	NA	LINEAR	SUNNY	MUDDY
10/20/2003	2	OPEN FIELD	1350	1410	20	DAILY START/STOP	SET UP SPACING WITH TAPES	GPS	NA	LINEAR	SUNNY	MUDDY
10/20/2003	2	OPEN FIELD	1410	1450	40	DOWNTIME MAINTENANCE CHECK	EQUIPMENT CHECK	GPS	NA	LINEAR	SUNNY	MUDDY
10/20/2003	2	OPEN FIELD	1450	1555	65	COLLECT DATA	COLLECT DATA	GPS	NA	LINEAR	SUNNY	MUDDY

Date	No. of People	Area Tested	Status Start Time	Status Stop Time	Duration, min	Operational Status	Operational Status - Comments	Track Method	Track Method = Other Explain	Pattern	Field Conditions	
TM-5 EMU DUAL SENSOR												
10/20/2003	2	OPEN FIELD	1555	1610	15	DOWNTIME MAINTENANCE CHECK	DATA CHECK	GPS	NA	LINEAR	SUNNY	MUDDY
10/20/2003	2	OPEN FIELD	1610	1655	45	COLLECT DATA	COLLECT DATA	GPS	NA	LINEAR	SUNNY	MUDDY
10/20/2003	2	OPEN FIELD	1655	1730	35	DAILY START/STOP	EQUIPMENT BREAKDOWN/ END OF DAILY OPERATIONS	GPS	NA	LINEAR	SUNNY	MUDDY
10/21/2003	2	OPEN FIELD	0735	0910	95	DAILY START/STOP	START OF DAILY OPERATIONS	GPS	NA	LINEAR	SUNNY	MUDDY
10/21/2003	2	OPEN FIELD	0910	0940	30	CALIBRATE	CALIBRATE EQUIPMENT USING METAL OBJECTS	GPS	NA	LINEAR	SUNNY	MUDDY
10/21/2003	2	OPEN FIELD	0940	1030	50	COLLECT DATA	COLLECT DATA	GPS	NA	LINEAR	SUNNY	MUDDY
10/21/2003	2	OPEN FIELD	1030	1105	35	DOWNTIME MAINTENANCE CHECK	DATA CHECK	GPS	NA	LINEAR	SUNNY	MUDDY
10/21/2003	2	OPEN FIELD	1105	1315	130	COLLECT DATA	COLLECT DATA	GPS	NA	LINEAR	SUNNY	MUDDY
10/21/2003	2	OPEN FIELD	1315	1330	15	DOWNTIME MAINTENANCE CHECK	CHANGE BATTERY	GPS	NA	LINEAR	SUNNY	MUDDY
10/21/2003	2	OPEN FIELD	1330	1450	80	COLLECT DATA	COLLECT DATA	GPS	NA	LINEAR	SUNNY	MUDDY

Date	No. of People	Area Tested	Status Start Time	Status Stop Time	Duration, min	Operational Status	Operational Status - Comments	Track Method	Track Method = Other Explain	Pattern	Field Conditions	
TM-5 EMU DUAL SENSOR												
10/21/2003	2	OPEN FIELD	1450	1520	30	DOWNTIME MAINTENANCE CHECK	DATA CHECK	GPS	NA	LINEAR	SUNNY	MUDDY
10/21/2003	2	OPEN FIELD	1520	1610	50	COLLECT DATA	COLLECT DATA	GPS	NA	LINEAR	SUNNY	MUDDY
10/21/2003	2	OPEN FIELD	1610	1630	20	DAILY START/STOP	EQUIPMENT BREAKDOWN/ END OF DAILY OPERATIONS	GPS	NA	LINEAR	SUNNY	MUDDY
10/22/2003	2	MOGUL AREA	0735	0945	130	DAILY START/STOP	START OF DAILY OPERATIONS	GPS	NA	LINEAR	CLOUDY	MUDDY
10/22/2003	2	MOGUL AREA	0945	1000	15	CALIBRATE	CALIBRATE EQUIPMENT USING METAL OBJECTS	GPS	NA	LINEAR	CLOUDY	MUDDY
10/22/2003	2	MOGUL AREA	1000	1150	110	COLLECT DATA	COLLECT DATA	GPS	NA	LINEAR	CLOUDY	MUDDY
10/22/2003	2	MOGUL AREA	1150	1200	10	DOWNTIME MAINTENANCE CHECK	CHANGE BATTERY	GPS	NA	LINEAR	CLOUDY	MUDDY
10/22/2003	2	MOGUL AREA	1200	1315	75	COLLECT DATA	COLLECT DATA	GPS	NA	LINEAR	CLOUDY	MUDDY
10/22/2003	2	MOGUL AREA	1315	1355	40	DOWNTIME MAINTENANCE CHECK	DATA CHECK	GPS	NA	LINEAR	CLOUDY	MUDDY
10/22/2003	2	MOGUL AREA	1355	1705	190	COLLECT DATA	COLLECT DATA	GPS	NA	LINEAR	CLOUDY	MUDDY

Date	No. of People	Area Tested	Status Start Time	Status Stop Time	Duration, min	Operational Status	Operational Status - Comments	Track Method	Track Method = Other Explain	Pattern	Field Conditions	
TM-5 EMU DUAL SENSOR												
10/22/2003	2	MOGUL AREA	1705	1730	25	DAILY START/STOP	EQUIPMENT BREAKDOWN/ END OF DAILY OPERATIONS	GPS	NA	LINEAR	CLOUDY	MUDDY
10/23/2003	2	WOODED AREA	0730	0810	40	DAILY START/STOP	START OF DAILY OPERATIONS	GPS	NA	LINEAR	CLOUDY	MUDDY
10/23/2003	2	WOODED AREA	0810	0830	20	CALIBRATE	CALIBRATE EQUIPMENT USING METAL OBJECTS	GPS	NA	LINEAR	CLOUDY	MUDDY
10/23/2003	2	WOODED AREA	0830	0930	60	COLLECT DATA	COLLECT DATA	GPS	NA	LINEAR	CLOUDY	MUDDY
TM-5 EMU SINGLE SENSOR												
10/23/2003	2	WOODED AREA	0930	1045	75	COLLECT DATA	STARTED USING SINGLE HEAD AND COTTON MARKING SYSTEM	NA	COTTON ODOMETER	LINEAR	CLOUDY	MUDDY
10/23/2003	2	WOODED AREA	1045	1105	20	DOWNTIME MAINTENANCE CHECK	CHANGE BATTERY	NA	COTTON ODOMETER	LINEAR	CLOUDY	MUDDY
10/23/2003	2	WOODED AREA	1105	1330	145	COLLECT DATA	COLLECT DATA	NA	COTTON ODOMETER	LINEAR	CLOUDY	MUDDY
10/23/2003	2	WOODED AREA	1330	1400	30	DOWNTIME MAINTENANCE CHECK	CHANGE BATTERY, DATA CHECK	NA	COTTON ODOMETER	LINEAR	CLOUDY	MUDDY
10/23/2003	2	WOODED AREA	1400	1500	60	COLLECT DATA	COLLECT DATA	NA	COTTON ODOMETER	LINEAR	CLOUDY	MUDDY

Date	No. of People	Area Tested	Status Start Time	Status Stop Time	Duration, min	Operational Status	Operational Status - Comments	Track Method	Track Method = Other Explain	Pattern	Field Conditions	
TM-5 EMU SINGLE SENSOR												
10/23/2003	2	WOODED AREA	1500	1615	75	COLLECT DATA	COLLECT DATA	NA	COTTON ODOMETER	LINEAR	CLOUDY	MUDDY
10/23/2003	2	WOODED AREA	1615	1630	15	DAILY START/STOP	EQUIPMENT BREAKDOWN/ END OF DAILY OPERATIONS	NA	COTTON ODOMETER	LINEAR	CLOUDY	MUDDY
10/24/2003	2	WOODED AREA	0800	0815	15	DAILY START/STOP	START OF DAILY OPERATIONS	NA	COTTON ODOMETER	LINEAR	CLOUDY	MUDDY
10/24/2003	2	WOODED AREA	0815	0830	15	COLLECT DATA	COLLECT DATA	NA	COTTON ODOMETER	LINEAR	CLOUDY	MUDDY
10/24/2003	2	WOODED AREA	0830	0845	15	DOWNTIME MAINTENANCE CHECK	CHANGE BATTERY	NA	COTTON ODOMETER	LINEAR	CLOUDY	MUDDY
10/24/2003	2	WOODED AREA	0845	0930	45	COLLECT DATA	COLLECT DATA	NA	COTTON ODOMETER	LINEAR	CLOUDY	MUDDY
10/24/2003	2	CALIBRATION LANE	0930	0945	15	CALIBRATE	CALIBRATE EQUIPMENT USING METAL OBJECTS	NA	COTTON ODOMETER	LINEAR	CLOUDY	MUDDY
10/24/2003	2	CALIBRATION LANE	0945	1115	90	COLLECT DATA	COLLECT DATA IN TEST PIT	NA	COTTON ODOMETER	LINEAR	CLOUDY	MUDDY
10/24/2003	2	CALIBRATION LANE	1115	1200	45	DEMOBILIZATION	DEMOBILIZATION	NA	COTTON ODOMETER	LINEAR	CLOUDY	MUDDY
10/24/2003	2	CALIBRATION LANE	1200	1220	20	COLLECT DATA	COLLECT DATA	NA	COTTON ODOMETER	LINEAR	CLOUDY	MUDDY

Date	No. of People	Area Tested	Status Start Time	Status Stop Time	Duration, min	Operational Status	Operational Status - Comments	Track Method	Track Method = Other Explain	Pattern	Field Conditions	
TM-5 EMU SINGLE SENSOR												
10/24/2003	2	BLIND TEST GRID	1220	1245	25	COLLECT DATA	COLLECT DATA	NA	COTTON ODOMETER	LINEAR	CLOUDY	MUDDY
10/24/2003	2	BLIND TEST GRID	1245	1505	140	DEMOBILIZATION	DEMOBILIZATION	NA	COTTON ODOMETER	LINEAR	CLOUDY	MUDDY
MAGNETOMETER												
10/14/2003	3	CALIBRATION LANE	1015	1525	310	INITIAL SET UP	INITIAL SET UP	NA	GPS	LINEAR	CLOUDY	MUDDY
10/14/2003	3	CALIBRATION LANE	1525	1615	50	COLLECT DATA	COLLECT DATA	NA	GPS	LINEAR	CLOUDY	MUDDY
10/14/2003	3	CALIBRATION LANE	1615	1620	5	DOWNTIME MAINTENANCE CHECK	CHANGE BATTERY	NA	GPS	LINEAR	CLOUDY	MUDDY
10/14/2003	3	BLIND TEST GRID	1620	1640	20	DAILY START/STOP	SET UP SPACING TAPES	NA	GPS	LINEAR	CLOUDY	MUDDY
10/14/2003	3	BLIND TEST GRID	1640	1720	40	COLLECT DATA	COLLECT DATA	NA	GPS	LINEAR	CLOUDY	MUDDY
10/14/2003	3	BLIND TEST GRID	1720	1725	5	DOWNTIME MAINTENANCE CHECK	CHANGE BATTERY	NA	GPS	LINEAR	CLOUDY	MUDDY
10/14/2003	3	BLIND TEST GRID	1725	1745	20	COLLECT DATA	COLLECT DATA	NA	GPS	LINEAR	CLOUDY	MUDDY
10/14/2003	3	BLIND TEST GRID	1745	1815	30	DAILY START/STOP	EQUIPMENT BREAKDOWN/ END OF DAILY OPERATIONS	NA	GPS	LINEAR	CLOUDY	MUDDY

Note: Activities pertinent to this specific demonstration are indicated in highlighted text.

Date	No. of People	Area Tested	Status Start Time	Status Stop Time	Duration, min	Operational Status	Operational Status - Comments	Track Method	Track Method = Other Explain	Pattern	Field Conditions	
MAGNETOMETER												
10/15/2003	3	OPEN FIELD	0800	1015	135	DAILY START/STOP	START OF DAILY OPERATIONS	NA	GPS	LINEAR	WINDY	MUDDY
10/15/2003	3	OPEN FIELD	1015	1145	90	DAILY START/STOP	SET UP SPACING TAPES	NA	GPS	LINEAR	WINDY	MUDDY
10/15/2003	3	OPEN FIELD	1145	1210	25	CALIBRATE	CALIBRATE	NA	GPS	LINEAR	WINDY	MUDDY
10/15/2003	3	OPEN FIELD	1210	1245	35	COLLECT DATA	COLLECT DATA	NA	GPS	LINEAR	WINDY	MUDDY
10/15/2003	3	OPEN FIELD	1245	1300	15	DOWNTIME MAINTENANCE CHECK	EQUIPMENT CHECK, PUT TAPE ON SENSORS TO PREVENT WATER DAMAGE	NA	GPS	LINEAR	WINDY	MUDDY
10/15/2003	3	OPEN FIELD	1300	1500	120	COLLECT DATA	COLLECT DATA	NA	GPS	LINEAR	WINDY	MUDDY
10/15/2003	3	OPEN FIELD	1500	1515	15	DOWNTIME MAINTENANCE CHECK	CHANGE BATTERY	NA	GPS	LINEAR	WINDY	MUDDY
10/15/2003	3	OPEN FIELD	1515	1600	45	COLLECT DATA	COLLECT DATA	NA	GPS	LINEAR	WINDY	MUDDY
10/15/2003	3	OPEN FIELD	1600	1615	15	DOWNTIME MAINTENANCE CHECK	CHANGE BATTERY	NA	GPS	LINEAR	WINDY	MUDDY
10/15/2003	3	OPEN FIELD	1615	1715	60	COLLECT DATA	COLLECT DATA	NA	GPS	LINEAR	WINDY	MUDDY

Date	No. of People	Area Tested	Status Start Time	Status Stop Time	Duration, min	Operational Status	Operational Status - Comments	Track Method	Track Method = Other Explain	Pattern	Field Conditions	
MAGNETOMETER												
10/15/2003	3	OPEN FIELD	1715	1800	45	DAILY START/STOP	EQUIPMENT BREAKDOWN/ END OF DAILY OPERATIONS	NA	GPS	LINEAR	WINDY	MUDDY
10/16/2003	3	OPEN FIELD	0800	0845	45	DAILY START/STOP	START OF DAILY OPERATIONS	NA	GPS	LINEAR	SUNNY	MUDDY
10/16/2003	3	OPEN FIELD	0845	0930	45	CALIBRATE	CALIBRATE	NA	GPS	LINEAR	SUNNY	MUDDY
10/16/2003	3	OPEN FIELD	0930	1050	80	COLLECT DATA	COLLECT DATA	NA	GPS	LINEAR	SUNNY	MUDDY
10/16/2003	3	OPEN FIELD	1050	1100	10	DOWNTIME MAINTENANCE CHECK	CHANGE BATTERY	NA	GPS	LINEAR	SUNNY	MUDDY
10/16/2003	3	OPEN FIELD	1100	1210	70	COLLECT DATA	COLLECT DATA	NA	GPS	LINEAR	SUNNY	MUDDY
10/16/2003	3	OPEN FIELD	1210	1215	5	DOWNTIME MAINTENANCE CHECK	CHANGE BATTERY	NA	GPS	LINEAR	SUNNY	MUDDY
10/16/2003	3	OPEN FIELD	1215	1345	90	COLLECT DATA	COLLECT DATA	NA	GPS	LINEAR	SUNNY	MUDDY
10/16/2003	3	OPEN FIELD	1345	1510	85	DAILY START/STOP	SET UP SPACING TAPES	NA	GPS	LINEAR	SUNNY	MUDDY
10/16/2003	3	OPEN FIELD	1510	1640	90	COLLECT DATA	COLLECT DATA	NA	GPS	LINEAR	SUNNY	MUDDY
10/16/2003	3	OPEN FIELD	1640	1645	45	DOWNTIME MAINTENANCE CHECK	CHANGE BATTERY	NA	GPS	LINEAR	SUNNY	MUDDY

Date	No. of People	Area Tested	Status Start Time	Status Stop Time	Duration, min	Operational Status	Operational Status - Comments	Track Method	Track Method = Other Explain	Pattern	Field Conditions	
MAGNETOMETER												
10/16/2003	3	OPEN FIELD	1645	1700	15	COLLECT DATA	COLLECT DATA	NA	GPS	LINEAR	SUNNY	MUDDY
10/16/2003	3	OPEN FIELD	1700	1730	30	DAILY START/STOP	EQUIPMENT BREAKDOWN/ END OF DAILY OPERATIONS	NA	GPS	LINEAR	SUNNY	MUDDY
10/17/2003	3	OPEN FIELD	0730	0910	100	DAILY START/STOP	START OF DAILY OPERATIONS	NA	GPS	LINEAR	SUNNY	MUDDY
10/17/2003	3	OPEN FIELD	0910	0930	20	CALIBRATE	CALIBRATE	NA	GPS	LINEAR	SUNNY	MUDDY
10/17/2003	3	OPEN FIELD	930	1100	90	COLLECT DATA	COLLECT DATA	NA	GPS	LINEAR	SUNNY	MUDDY
10/17/2003	3	OPEN FIELD	1100	1120	20	DOWNTIME MAINTENANCE CHECK	CHANGE BATTERY	NA	GPS	LINEAR	SUNNY	MUDDY
10/17/2003	3	OPEN FIELD	1120	1150	30	COLLECT DATA	COLLECT DATA	NA	GPS	LINEAR	SUNNY	MUDDY
10/17/2003	3	OPEN FIELD	1150	1230	40	DAILY START/STOP	SET UP SPACING TAPES	NA	GPS	LINEAR	SUNNY	MUDDY
10/17/2003	3	OPEN FIELD	1230	1325	55	COLLECT DATA	COLLECT DATA	NA	GPS	LINEAR	SUNNY	MUDDY
10/17/2003	3	OPEN FIELD	1325	1350	25	EQUIPMENT FAILURE	BAD CABLE CONNECTION, RECONNECTED CABLES	NA	GPS	LINEAR	SUNNY	MUDDY

Date	No. of People	Area Tested	Status Start Time	Status Stop Time	Duration, min	Operational Status	Operational Status - Comments	Track Method	Track Method = Other Explain	Pattern	Field Conditions	
MAGNETOMETER												
10/17/2003	3	OPEN FIELD	1350	1445	55	COLLECT DATA	COLLECT DATA	NA	GPS	LINEAR	SUNNY	MUDDY
10/17/2003	3	OPEN FIELD	1445	1500	15	DOWNTIME MAINTENANCE CHECK	CHANGE BATTERY	NA	GPS	LINEAR	SUNNY	MUDDY
10/17/2003	3	OPEN FIELD	1500	1550	50	COLLECT DATA	COLLECT DATA	NA	GPS	LINEAR	SUNNY	MUDDY
10/17/2003	3	OPEN FIELD	1550	1640	50	DAILY START/STOP	EQUIPMENT BREAKDOWN/ END OF DAILY OPERATIONS	NA	GPS	LINEAR	SUNNY	MUDDY
10/18/2003	3	OPEN FIELD	0725	0810	45	DAILY START/STOP	START OF DAILY OPERATIONS	NA	GPS	LINEAR	SUNNY	MUDDY
10/18/2003	3	OPEN FIELD	0810	0835	25	CALIBRATE	CALIBRATE	NA	GPS	LINEAR	SUNNY	MUDDY
10/18/2003	3	OPEN FIELD	0835	0940	65	COLLECT DATA	COLLECT DATA	NA	GPS	LINEAR	SUNNY	MUDDY
10/18/2003	3	OPEN FIELD	0940	0950	10	DOWNTIME MAINTENANCE CHECK	CHANGE BATTERY	NA	GPS	LINEAR	SUNNY	MUDDY
10/18/2003	3	OPEN FIELD	0950	1110	80	COLLECT DATA	COLLECT DATA	NA	GPS	LINEAR	SUNNY	MUDDY
10/18/2003	3	OPEN FIELD	1110	1115	5	DOWNTIME MAINTENANCE CHECK	CHANGE BATTERY	NA	GPS	LINEAR	SUNNY	MUDDY
10/18/2003	3	OPEN FIELD	1115	1125	10	EQUIPMENT FAILURE	BAD SATELLITE QUALITY	NA	GPS	LINEAR	SUNNY	MUDDY

Date	No. of People	Area Tested	Status Start Time	Status Stop Time	Duration, min	Operational Status	Operational Status - Comments	Track Method	Track Method = Other Explain	Pattern	Field Conditions	
MAGNETOMETER												
10/18/2003	3	OPEN FIELD	1125	1155	30	COLLECT DATA	COLLECT DATA	NA	GPS	LINEAR	SUNNY	MUDDY
10/18/2003	3	OPEN FIELD	1155	1230	35	BREAK/LUNCH	BREAK/LUNCH	NA	GPS	LINEAR	SUNNY	MUDDY
10/18/2003	3	OPEN FIELD	1230	1300	30	COLLECT DATA	COLLECT DATA	NA	GPS	LINEAR	SUNNY	MUDDY
10/18/2003	3	OPEN FIELD	1300	1325	25	DAILY START/STOP	SET UP SPACING TAPES	NA	GPS	LINEAR	SUNNY	MUDDY
10/18/2003	3	OPEN FIELD	1325	1420	55	COLLECT DATA	COLLECT DATA	NA	GPS	LINEAR	SUNNY	MUDDY
10/18/2003	3	OPEN FIELD	1420	1425	5	DOWNTIME MAINTENANCE CHECK	CHANGE BATTERY	NA	GPS	LINEAR	SUNNY	MUDDY
10/18/2003	3	OPEN FIELD	1425	1520	55	COLLECT DATA	COLLECT DATA	NA	GPS	LINEAR	SUNNY	MUDDY
10/18/2003	3	OPEN FIELD	1520	1535	15	DOWNTIME MAINTENANCE CHECK	CHANGE BATTERY	NA	GPS	LINEAR	SUNNY	MUDDY
10/18/2003	3	OPEN FIELD	1535	1610	35	COLLECT DATA	COLLECT DATA	NA	GPS	LINEAR	SUNNY	MUDDY
10/18/2003	3	OPEN FIELD	1610	1640	30	DAILY START/STOP	EQUIPMENT BREAKDOWN/ END OF DAILY OPERATIONS	NA	GPS	LINEAR	SUNNY	MUDDY
10/20/2003	3	OPEN FIELD	0745	0845	60	DAILY START/STOP	START OF DAILY OPERATIONS	NA	GPS	LINEAR	SUNNY	MUDDY

Date	No. of People	Area Tested	Status Start Time	Status Stop Time	Duration, min	Operational Status	Operational Status - Comments	Track Method	Track Method = Other Explain	Pattern	Field Conditions	
MAGNETOMETER												
10/20/2003	3	OPEN FIELD	0845	0915	30	CALIBRATE	CALIBRATE	NA	GPS	LINEAR	SUNNY	MUDDY
10/20/2003	3	OPEN FIELD	0915	1020	65	COLLECT DATA	COLLECT DATA	NA	GPS	LINEAR	SUNNY	MUDDY
10/20/2003	3	OPEN FIELD	1020	1030	10	DOWNTIME MAINTENANCE CHECK	CHANGE BATTERY	NA	GPS	LINEAR	SUNNY	MUDDY
10/20/2003	3	OPEN FIELD	1030	1115	45	COLLECT DATA	COLLECT DATA	NA	GPS	LINEAR	SUNNY	MUDDY
10/20/2003	3	OPEN FIELD	1115	1200	45	DAILY START/STOP	SET UP SPACING TAPES	NA	GPS	LINEAR	SUNNY	MUDDY
10/20/2003	3	OPEN FIELD	1200	1210	10	DOWNTIME MAINTENANCE CHECK	CHANGE BATTERY	NA	GPS	LINEAR	SUNNY	MUDDY
10/20/2003	3	OPEN FIELD	1210	1230	20	BREAK/LUNCH	BREAK/LUNCH	NA	GPS	LINEAR	SUNNY	MUDDY
10/20/2003	3	OPEN FIELD	1230	1320	50	COLLECT DATA	COLLECT DATA	NA	GPS	LINEAR	SUNNY	MUDDY
10/20/2003	3	OPEN FIELD	1320	1330	10	DOWNTIME MAINTENANCE CHECK	CHANGE BATTERY	NA	GPS	LINEAR	SUNNY	MUDDY
10/20/2003	3	OPEN FIELD	1330	1500	90	COLLECT DATA	COLLECT DATA	NA	GPS	LINEAR	SUNNY	MUDDY
10/20/2003	3	OPEN FIELD	1500	1505	5	DOWNTIME MAINTENANCE CHECK	CHANGE BATTERY	NA	GPS	LINEAR	SUNNY	MUDDY

Date	No. of People	Area Tested	Status Start Time	Status Stop Time	Duration, min	Operational Status	Operational Status - Comments	Track Method	Track Method = Other Explain	Pattern	Field Conditions	
MAGNETOMETER												
10/20/2003	3	OPEN FIELD	1505	1525	20	DAILY START/STOP	SET UP SPACING TAPES	NA	GPS	LINEAR	SUNNY	MUDDY
10/20/2003	3	OPEN FIELD	1525	1615	50	COLLECT DATA	COLLECT DATA	NA	GPS	LINEAR	SUNNY	MUDDY
10/20/2003	3	OPEN FIELD	1615	1625	10	DOWNTIME MAINTENANCE CHECK	CHANGE BATTERY	NA	GPS	LINEAR	SUNNY	MUDDY
10/20/2003	3	OPEN FIELD	1625	1700	35	COLLECT DATA	COLLECT DATA	NA	GPS	LINEAR	SUNNY	MUDDY
10/20/2003	3	OPEN FIELD	1700	1730	30	DAILY START/STOP	EQUIPMENT BREAKDOWN/ END OF DAILY OPERATIONS	NA	GPS	LINEAR	SUNNY	MUDDY
10/21/2003	3	OPEN FIELD	0735	0820	45	DAILY START/STOP	START OF DAILY OPERATIONS	NA	GPS	LINEAR	SUNNY	MUDDY
10/21/2003	3	OPEN FIELD	0820	0900	40	CALIBRATE	CALIBRATE	NA	GPS	LINEAR	SUNNY	MUDDY
10/21/2003	3	OPEN FIELD	0900	1010	70	COLLECT DATA	COLLECT DATA	NA	GPS	LINEAR	SUNNY	MUDDY
10/21/2003	3	OPEN FIELD	1010	1030	20	DOWNTIME MAINTENANCE CHECK	DOWNLOAD DATA	NA	GPS	LINEAR	SUNNY	MUDDY
10/21/2003	3	OPEN FIELD	1030	1040	10	DOWNTIME MAINTENANCE CHECK	CHANGE BATTERY	NA	GPS	LINEAR	SUNNY	MUDDY
10/21/2003	3	OPEN FIELD	1040	1100	20	BREAK/LUNCH	BREAK/LUNCH	NA	GPS	LINEAR	SUNNY	MUDDY

Date	No. of People	Area Tested	Status Start Time	Status Stop Time	Duration, min	Operational Status	Operational Status - Comments	Track Method	Track Method = Other Explain	Pattern	Field Conditions	
MAGNETOMETER												
10/21/2003	3	OPEN FIELD	1100	1150	50	COLLECT DATA	COLLECT DATA	NA	GPS	LINEAR	SUNNY	MUDDY
10/21/2003	3	OPEN FIELD	1150	1200	10	DOWNTIME MAINTENANCE CHECK	CHANGE BATTERY	NA	GPS	LINEAR	SUNNY	MUDDY
10/21/2003	3	OPEN FIELD	1200	1330	90	COLLECT DATA	COLLECT DATA	NA	GPS	LINEAR	SUNNY	MUDDY
10/21/2003	3	OPEN FIELD	1330	1345	15	DOWNTIME MAINTENANCE CHECK	CHANGE BATTERY	NA	GPS	LINEAR	SUNNY	MUDDY
10/21/2003	3	OPEN FIELD	1345	1435	50	COLLECT DATA	COLLECT DATA	NA	GPS	LINEAR	SUNNY	MUDDY
10/21/2003	3	OPEN FIELD	1435	1445	10	DOWNTIME MAINTENANCE CHECK	CHANGE BATTERY	NA	GPS	LINEAR	SUNNY	MUDDY
10/21/2003	3	OPEN FIELD	1445	1600	75	COLLECT DATA	COLLECT DATA	NA	GPS	LINEAR	SUNNY	MUDDY
10/21/2003	3	OPEN FIELD	1600	1630	30	DAILY START/STOP	EQUIPMENT BREAKDOWN/ END OF DAILY OPERATIONS	NA	GPS	LINEAR	CLOUDY	MUDDY
10/22/2003	3	WOODED AREA	0735	0935	120	DAILY START/STOP	START OF DAILY OPERATIONS	NA	COTTON ODOMETER	LINEAR	CLOUDY	MUDDY
10/22/2003	3	WOODED AREA	0935	1000	25	CALIBRATE	CALIBRATE	NA	COTTON ODOMETER	LINEAR	CLOUDY	MUDDY

Date	No. of People	Area Tested	Status Start Time	Status Stop Time	Duration, min	Operational Status	Operational Status - Comments	Track Method	Track Method = Other Explain	Pattern	Field Conditions	
MAGNETOMETER												
10/22/2003	3	WOODED AREA	1000	1145	105	COLLECT DATA	COLLECT DATA	NA	COTTON ODOMETER	LINEAR	CLOUDY	MUDDY
10/22/2003	3	WOODED AREA	1145	1205	20	DOWNTIME MAINTENANCE CHECK	CHANGE BATTERY	NA	COTTON ODOMETER	LINEAR	CLOUDY	MUDDY
10/22/2003	3	WOODED AREA	1205	1300	55	COLLECT DATA	COLLECT DATA	NA	COTTON ODOMETER	LINEAR	CLOUDY	MUDDY
10/22/2003	3	WOODED AREA	1300	1305	5	DOWNTIME MAINTENANCE CHECK	CHANGE BATTERY	NA	COTTON ODOMETER	LINEAR	CLOUDY	MUDDY
10/22/2003	3	WOODED AREA	1305	1400	55	COLLECT DATA	COLLECT DATA	NA	COTTON ODOMETER	LINEAR	CLOUDY	MUDDY
10/22/2003	3	WOODED AREA	1400	1410	10	DOWNTIME MAINTENANCE CHECK	CHANGE BATTERY	NA	COTTON ODOMETER	LINEAR	CLOUDY	MUDDY
10/22/2003	3	WOODED AREA	1410	1515	65	COLLECT DATA	COLLECT DATA	NA	COTTON ODOMETER	LINEAR	CLOUDY	MUDDY
10/22/2003	3	WOODED AREA	1515	1520	5	DOWNTIME MAINTENANCE CHECK	CHANGE BATTERY	NA	COTTON ODOMETER	LINEAR	CLOUDY	MUDDY
10/22/2003	3	WOODED AREA	1520	1615	55	COLLECT DATA	COLLECT DATA	NA	COTTON ODOMETER	LINEAR	CLOUDY	MUDDY
10/22/2003	3	WOODED AREA	1615	1730	75	DAILY START/STOP	EQUIPMENT BREAKDOWN/ END OF DAILY OPERATIONS	NA	COTTON ODOMETER	LINEAR	CLOUDY	MUDDY

Date	No. of People	Area Tested	Status Start Time	Status Stop Time	Duration, min	Operational Status	Operational Status - Comments	Track Method	Track Method = Other Explain	Pattern	Field Conditions	
MAGNETOMETER												
10/23/2003	3	MOGUL AREA	0730	0900	90	DAILY START/STOP	START OF DAILY OPERATIONS	NA	GPS	LINEAR	CLOUDY	MUDDY
10/23/2003	3	MOGUL AREA	0900	0915	15	CALIBRATE	CALIBRATE	NA	GPS	LINEAR	CLOUDY	MUDDY
10/23/2003	3	MOGUL AREA	0915	1015	60	DAILY START/STOP	SET UP SPACING TAPES	NA	GPS	LINEAR	CLOUDY	MUDDY
10/23/2003	3	MOGUL AREA	1015	1110	55	COLLECT DATA	COLLECT DATA	NA	GPS	LINEAR	CLOUDY	MUDDY
10/23/2003	3	MOGUL AREA	1110	1115	5	DOWNTIME MAINTENANCE CHECK	CHANGE BATTERY	NA	GPS	LINEAR	CLOUDY	MUDDY
10/23/2003	3	MOGUL AREA	1115	1215	60	COLLECT DATA	COLLECT DATA	NA	GPS	LINEAR	CLOUDY	MUDDY
10/23/2003	3	MOGUL AREA	1215	1220	5	DOWNTIME MAINTENANCE CHECK	CHANGE BATTERY	NA	GPS	LINEAR	CLOUDY	MUDDY
10/23/2003	3	MOGUL AREA	1220	1230	10	COLLECT DATA	COLLECT DATA	NA	GPS	LINEAR	CLOUDY	MUDDY
10/23/2003	3	MOGUL AREA	1230	1315	45	DAILY START/STOP	SET UP SPACING TAPES	NA	GPS	LINEAR	CLOUDY	MUDDY
10/23/2003	3	MOGUL AREA	1315	1410	55	COLLECT DATA	COLLECT DATA	NA	GPS	LINEAR	CLOUDY	MUDDY
10/23/2003	3	MOGUL AREA	1410	1420	10	DOWNTIME MAINTENANCE CHECK	CHANGE BATTERY	NA	GPS	LINEAR	CLOUDY	MUDDY

Note: Activities pertinent to this specific demonstration are indicated in highlighted text.

Date	No. of People	Area Tested	Status Start Time	Status Stop Time	Duration, min	Operational Status	Operational Status - Comments	Track Method	Track Method = Other Explain	Pattern	Field Conditions	
MAGNETOMETER												
10/23/2003	3	MOGUL AREA	1420	1525	65	COLLECT DATA	COLLECT DATA	NA	GPS	LINEAR	CLOUDY	MUDDY
10/23/2003	3	MOGUL AREA	1525	1630	65	DAILY START/STOP	EQUIPMENT BREAKDOWN/ END OF DAILY OPERATIONS	NA	GPS	LINEAR	CLOUDY	MUDDY
10/24/2003	3	CALIBRATION TEST PIT	0800	0900	60	DAILY START/STOP	START OF DAILY OPERATIONS	NA	GPS	LINEAR	CLOUDY	MUDDY
10/24/2003	3	CALIBRATION TEST PIT	0900	0915	15	CALIBRATE	CALIBRATE	NA	GPS	LINEAR	CLOUDY	MUDDY
10/24/2003	3	CALIBRATION TEST PIT	0915	1100	105	COLLECT DATA	COLLECT DATA IN TEST PIT	NA	GPS	LINEAR	CLOUDY	MUDDY
10/24/2003	3	CALIBRATION TEST PIT	1100	1110	10	DOWNTIME MAINTENANCE CHECK	CHANGE BATTERY	NA	GPS	LINEAR	CLOUDY	MUDDY
10/24/2003	3	CALIBRATION TEST PIT	1110	1125	15	COLLECT DATA	COLLECT DATA IN TEST PIT	NA	GPS	LINEAR	CLOUDY	MUDDY
10/24/2003	3	CALIBRATION TEST PIT	1125	1230	65	BREAK/LUNCH	BREAK/LUNCH	NA	GPS	LINEAR	CLOUDY	MUDDY
10/24/2003	3	MOGUL AREA	1230	1330	60	COLLECT DATA	COLLECT DATA	NA	GPS	LINEAR	CLOUDY	MUDDY
10/24/2003	3	MOGUL AREA	1330	1505	95	DEMOBILIZATION	DEMOBILIZATION	NA	GPS	LINEAR	CLOUDY	MUDDY

Note: Activities pertinent to this specific demonstration are indicated in highlighted text.

APPENDIX E. REFERENCES

1. Standardized UXO Technology Demonstration Site Handbook, DTC Project No. 8-CO-160-000-473, Report No. ATC-8349, March 2002.

2. Aberdeen Proving Ground Soil Survey Report, October 1998.

3. Data Summary, UXO Standardized Test Site: APG Soils Description, May 2002.

4. Yuma Proving Ground Soil Survey Report, May 2003.

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APPENDIX F. ABBREVIATIONS

AEC	=	U.S. Army Environmental Center
APG	=	Aberdeen Proving Ground
ASCII	=	American Standard Code for Information Interchange.
ATC	=	U.S. Army Aberdeen Test Center
CEP	=	Central Error of Probability
EM	=	electromagnetic
EMI	=	electromagnetic interference
EMIS	=	Electromagnetic Induction Spectroscopy
ERDC	=	U.S. Army Corps of Engineers Engineering Research and Development Center
ESTCP	=	Environmental Security Technology Certification Program
EQT	=	Army Environmental Quality Technology Program
GPS	=	Global Positioning System
JPG	=	Jefferson Proving Ground
NMEA	=	National Maritime Electronics Association
POC	=	point of contact
QA	=	quality assurance
QC	=	quality control
ROC	=	receiver-operating characteristic
RTK	=	real time kinematic
RTS	=	Robotic Total Station
SERDP	=	Strategic Environmental Research and Development Program
UXO	=	unexploded ordnance
YPG	=	U.S. Army Yuma Proving Ground

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DTC PROJECT NO. 8-CO-160-UXO-021
REPORT NO. ATC-9014

STANDARDIZED

UXO TECHNOLOGY DEMONSTRATION SITE

MOGULS SCORING RECORD NO. 136

SITE LOCATION:
U.S. ARMY YUMA PROVING GROUND

DEMONSTRATOR:
U.S. ARMY CORPS OF ENGINEERS
ENGINEERING RESEARCH AND
DEVELOPMENT CENTER
3909 HALLS FERRY ROAD
VICKSBURG, MS 39180-6199

TECHNOLOGY TYPE/PLATFORM:
GEM-3/PUSHCART

PREPARED BY:
U.S. ARMY ABERDEEN TEST CENTER
ABERDEEN PROVING GROUND, MD 21005-5059

JUNE 2005

Prepared for:
U.S. ARMY ENVIRONMENTAL CENTER
ABERDEEN PROVING GROUND, MD 21010-5401

U.S. ARMY DEVELOPMENTAL TEST COMMAND
ABERDEEN PROVING GROUND, MD 21005-5055

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Overbay, Larry; Robitaille, George
The Standardized UXO Technology Demonstration Site Scoring Committee

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Commander
U.S. Army Aberdeen Test Center
ATTN: CSTE-STC-ATC-SL-E
Aberdeen Proving Ground, MD 21005-5059

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Commander
U.S. Army Environmental Center
ATTN: SFIM-AEC-ATT
Aberdeen Proving Ground, MD 21005-5401

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14. ABSTRACT
This scoring record documents the efforts of ERDC to detect and discriminate inert unexploded ordnance (UXO) utilizing the YPG Standardized UXO Technology Demonstration Site Mogul. The scoring record was coordinated by Larry Overbay and the Standardized UXO Technology Demonstration Site Scoring Committee. Organizations on the committee include the U.S. Army Corps of Engineers, the Environmental Security Technology Certification Program, the Strategic Environmental Research and Development Program, the Institute for Defense Analysis, the U.S. Army Environmental Center, and the U.S. Army Aberdeen Test Center.

15. SUBJECT TERMS
ERDC UXO Standardized Site, YPG, Standardized UXO Technology Demonstration Site Program, Moguls UXO GEM-3/Pushcart

16. SECURITY CLASSIFICATION OF:			17. LIMITATION OF ABSTRACT	18. NUMBER OF PAGES	19a. NAME OF RESPONSIBLE PERSON
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Authors:

Larry Overbay Jr.
Matthew Boutin
Military Environmental Technology Demonstration Center (METDC)
U.S. Army Aberdeen Test Center (ATC)
U.S. Army Aberdeen Proving Ground (APG)

Robert Archiable
EC 111, Limited Liability Company (LLC)
U.S. Army Yuma Proving Ground (YPG)

Christina McClung
Aberdeen Test and Support Services (ATSS)
Sverdrup Technology, Inc.
U.S. Army Aberdeen Proving Ground (APG)

Contributor:

George Robitaille
U.S. Army Environmental Center (AEC)
U.S. Army Aberdeen Proving Ground (APG)

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SECTION 6. COMPARISON OF RESULTS TO OPEN FIELD DEMONSTRATION

SECTION 7. APPENDIXES

SECTION 1. GENERAL INFORMATION

1.1 BACKGROUND

Technologies under development for the detection and discrimination of unexploded ordnance (UXO) require testing so that their performance can be characterized. To that end, Standardized Test Sites have been developed at Aberdeen Proving Ground (APG), Maryland and U.S. Army Yuma Proving Ground (YPG), Arizona. These test sites provide a diversity of geology, climate, terrain, and weather as well as diversity in ordnance and clutter. Testing at these sites is independently administered and analyzed by the government for the purposes of characterizing technologies, tracking performance with system development, comparing performance of different systems, and comparing performance in different environments.

The Standardized UXO Technology Demonstration Site Program is a multi-agency program spearheaded by the U.S. Army Environmental Center (AEC). The U.S. Army Aberdeen Test Center (ATC) and the U.S. Army Corps of Engineers Engineering Research and Development Center (ERDC) provide programmatic support. The program is being funded and supported by the Environmental Security Technology Certification Program (ESTCP), the Strategic Environmental Research and Development Program (SERDP) and the Army Environmental Quality Technology Program (EQT).

1.2 SCORING OBJECTIVES

The objective in the Standardized UXO Technology Demonstration Site Program is to evaluate the detection and discrimination capabilities of a given technology under various field and soil conditions. Inert munitions and clutter items are positioned in various orientations and depths in the ground.

The evaluation objectives are as follows:

a. To determine detection and discrimination effectiveness under realistic scenarios that vary targets, geology, clutter, topography, and vegetation.

b. To determine cost, time, and manpower requirements to operate the technology.

c. To determine demonstrator's ability to analyze survey data in a timely manner and provide prioritized "Target Lists" with associated confidence levels.

d. To provide independent site management to enable the collection of high quality, ground-truth, geo-referenced data for post-demonstration analysis.

1.2.1 Scoring Methodology

a. The scoring of the demonstrator's performance is conducted in two stages. These two stages are termed the RESPONSE STAGE and DISCRIMINATION STAGE. For both stages, the probability of detection (P_d) and the false alarms are reported as receiver-operating

characteristic (ROC) curves. False alarms are divided into those anomalies that correspond to emplaced clutter items, measuring the probability of false positive (P_{fp}), and those that do not correspond to any known item, termed background alarms.

b. The RESPONSE STAGE scoring evaluates the ability of the system to detect emplaced targets without regard to ability to discriminate ordnance from other anomalies. For the blind grid RESPONSE STAGE, the demonstrator provides the scoring committee with a target response from each and every grid square along with a noise level below which target responses are deemed insufficient to warrant further investigation. This list is generated with minimal processing and, since a value is provided for every grid square, will include signals both above and below the system noise level.

c. The DISCRIMINATION STAGE evaluates the demonstrator's ability to correctly identify ordnance as such and to reject clutter. For the blind grid DISCRIMINATION STAGE, the demonstrator provides the scoring committee with the output of the algorithms applied in the discrimination-stage processing for each grid square. The values in this list are prioritized based on the demonstrator's determination that a grid square is likely to contain ordnance. Thus, higher output values are indicative of higher confidence that an ordnance item is present at the specified location. For digital signal processing, priority ranking is based on algorithm output. For other discrimination approaches, priority ranking is based on human (subjective) judgment. The demonstrator also specifies the threshold in the prioritized ranking that provides optimum performance, (i.e. that is expected to retain all detected ordnance and rejects the maximum amount of clutter).

d. The demonstrator is also scored on EFFICIENCY and REJECTION RATIO, which measures the effectiveness of the discrimination stage processing. The goal of discrimination is to retain the greatest number of ordnance detections from the anomaly list, while rejecting the maximum number of anomalies arising from non-ordnance items. EFFICIENCY measures the fraction of detected ordnance retained after discrimination, while the REJECTION RATIO measures the fraction of false alarms rejected. Both measures are defined relative to performance at the demonstrator-supplied level below which all responses are considered noise, i.e., the maximum ordnance detectable by the sensor and its accompanying false positive rate or background alarm rate.

e. Based on configuration of the ground truth at the standardized sites and the defined scoring methodology, there exists the possibility of having anomalies within overlapping halos and/or multiple anomalies within halos. In these cases, the following scoring logic is implemented:

(1) In situations where multiple anomalies exist within a single R_{halo}, the anomaly with the strongest response or highest ranking will be assigned to that particular ground truth item.

(2) For overlapping R_{halo} situations, ordnance has precedence over clutter. The anomaly with the strongest response or highest ranking that is closest to the center of a particular ground truth item gets assigned to that item. Remaining anomalies are retained until all matching is complete.

(3) Anomalies located within any R_{halo} that do not get associated with a particular ground truth item are thrown out and are not considered in the analysis.

f. All scoring factors are generated utilizing the Standardized UXO Probability and Plot Program, version 3.1.1.

1.2.2 Scoring Factors

Factors to be measured and evaluated as part of this demonstration include:

a. Response Stage ROC curves:

(1) Probability of Detection (P_d^{res}).

(2) Probability of False Positive (P_{fp}^{res}).

(3) Background Alarm Rate (BAR^{res}) or Probability of Background Alarm (P_{BA}^{res}).

b. Discrimination Stage ROC curves:

(1) Probability of Detection (P_d^{disc}).

(2) Probability of False Positive (P_{fp}^{disc}).

(3) Background Alarm Rate (BAR^{disc}) or Probability of Background Alarm (P_{BA}^{disc}).

c. Metrics:

(1) Efficiency (E).

(2) False Positive Rejection Rate (R_{fp}).

(3) Background Alarm Rejection Rate (R_{BA}).

d. Other:

(1) Probability of Detection by Size and Depth.

(2) Classification by type (i.e., 20-, 40-, 105-mm, etc.).

(3) Location accuracy.

(4) Equipment setup, calibration time and corresponding man-hour requirements.

(5) Survey time and corresponding man-hour requirements.

(6) Reacquisition/resurvey time and man-hour requirements (if any).

(7) Downtime due to system malfunctions and maintenance requirements.

1.3 STANDARD AND NONSTANDARD INERT ORDNANCE TARGETS

The standard and nonstandard ordnance items emplaced in the test areas are listed in Table 1. Standardized targets are members of a set of specific ordnance items that have identical properties to all other items in the set (caliber, configuration, size, weight, aspect ratio, material, filler, magnetic remanence, and nomenclature). Nonstandard targets are inert ordnance items having properties that differ from those in the set of standardized targets.

TABLE 1. INERT ORDNANCE TARGETS

Standard Type	Nonstandard (NS)
20-mm Projectile M55	20-mm Projectile M55
	20-mm Projectile M97
40-mm Grenades M385	40-mm Grenades M385
40-mm Projectile MKII Bodies	40-mm Projectile M813
BDU-28 Submunition	
BLU-26 Submunition	
M42 Submunition	
57-mm Projectile APC M86	
60-mm Mortar M49A3	60-mm Mortar (JPG)
	60-mm Mortar M49
2.75-inch Rocket M230	2.75-inch Rocket M230
	2.75-inch Rocket XM229
MK 118 ROCKEYE	
81-mm Mortar M374	81-mm Mortar (JPG)
	81-mm Mortar M374
105-mm HEAT Rounds M456	
105-mm Projectile M60	105-mm Projectile M60
155-mm Projectile M483A1	155-mm Projectile M483A
	500-lb Bomb

JPG = Jefferson Proving Ground
HEAT = high-explosive antitank

SECTION 2. DEMONSTRATION

2.1 DEMONSTRATOR INFORMATION

2.1.1 Demonstrator Point of Contact (POC) and Address

POC: Mr. Jose Llopis
(601) 634-3164

Address: U.S. Army Corps of Engineers Engineering Research and Development Center
3909 Halls Ferry Road
Vicksburg, MS 39180-6199

2.1.2 System Description (provided by demonstrator)

The GEM-3 system is able to collect multiple channels of complex frequency domain electromagnetic interference (EMI) data over a wide range of audio frequencies (30 Hz to 48 kHz). The system is a wheeled pushcart with a 96-cm sensor head, a mounted electronics console, a user interface, and a real-time kinematic (RTK) Global Positioning System (GPS) (fig. 1). The sensor head consists of three coils. The primary transmitter coil is the outer coil in the sensor head. The receiver coil is the inner coil in the sensor head. The bucking transmitter coil is the middle coil in the sensor head. The current in the bucking coil flows in the opposite direction of the current in the primary transmitter coil. This suppresses the dipole moment on the receiver coil that is directly from the primary transmitter coil. The electronics console contains the multifrequency current waveform generator, the analog-to-digital converter receiver electronics, the digital signal processor, and the power management module. The user interface utilizes a personal digital assistant (PDA). The PDA is used for data logging and allows for real-time control of the system. The PDA also allows for real-time display of the data collected. The RTK GPS will require a base station to be set up at a suitable reference point for radio communication with the mobile unit on the GEM-3 system. The GEM-3 system's acquisition of multifrequency data allows for performing what Geophex Ltd., the developer of the system, calls electromagnetic induction spectroscopy (EMIS) on buried objects. EMIS provides a method to discriminate UXO targets from natural and man-made clutter objects by means of their unique, complex (in-phase and quadrature) frequency responses.

Figure 1. Demonstrator's system, GEM-3 pushcart.

2.1.3 Data Processing Description (provided by demonstrator)

The GEM-3 data acquired at the test site will be processed using a combination of ERDC-developed programs and Geosoft's Oasis Montaj. First, basic data corrections such as background subtraction and time-synchronization between the sensor data and GPS data will be performed. The raw data, after these basic corrections, will be submitted in Geosoft XYZ format. Two Response Stage submissions will be made within 30 days. One will be based on a threshold applied to the total magnitude of the sensor inphase and quadrature response for all frequencies. The second will be based on interactive histogram analysis of the data. Data from each of these detection schemes will be used by the target discrimination algorithm to generate separate Discrimination Stage submissions. The discrimination algorithm compares sensor data collected near each detected anomaly with calibration data acquired over the target types of interest at the beginning of the data collection.

One of ERDC's primary objectives for this data acquisition is to obtain high quality data to further our modeling and analysis research. Therefore, ERDC plans to make further data submissions using other detection and discrimination algorithms on this same dataset, alone and in combination with data from other sensors.

2.1.4 Data Submission Format

Data were submitted for scoring in accordance with data submission protocols outlined in the Standardized UXO Technology Demonstration Site Handbook. These submitted data are not included in this report in order to protect ground truth information.

2.1.5 Demonstrator Quality Assurance (QA) and Quality Control (QC) (provided by demonstrator)

The operators will perform three levels of quality control (QC) checks: the first day of the project, the beginning of the day, and whenever there is an equipment change (i.e. batteries, data dump, etc.). On the first day of the project, the operators will lay out a 10-meter long line oriented North to South with a ferrite bar at the center. This line will be well marked and used each time the instrument and positioning are tested. The operators will test for instrument response over the ferrite bar, as well as conduct a position check and a latency check. The operators will walk the line slowly in two directions and then back the pushcart up until it is centered on the ferrite bar. This will set the location of the ferrite bar as well as the instrument response, which will be referenced every time the operators check the equipment.

Each morning the operators will perform functional equipment checks. The operators will visually inspect all equipment for damage. They will then power up the equipment. The operators will perform static and instrument response tests to ensure that the data is stable when the instrument is in a static position over a marked location. These tests will be performed after the instrument has had sufficient time to warm up.

Quality assurance (QA) will be the responsibility of the project lead; he will ensure that test data will be inspected and recorded each day using a known target (e.g. ferrite bar) with the GEM-3 sensors, and using a reference position with the RTK GPS. Geo-referenced data sets will be inspected at the end of the day for GEM-3 data quality and navigation integrity (reasonableness criteria).

Data analysis will be performed each day. This analysis will include inspection of the data for inconsistencies (bad data and errors) and to verify RTK GPS data show good coverage and limited dropouts. If the data show the sensor or electronics are not taking acceptable data or the RTK GPS dropouts are too numerous/large for data analysis or good coverage, that section will be flagged for a resurvey.

2.1.6 Additional Records

The following record(s) by this vendor can be accessed via the Internet as MicroSoft Word documents at www.uxotestsites.org. The counterparts to this report are the Blind Grid, Scoring Record No. 134, and the Open Field, Scoring Record No. 135.

2.2 YPG SITE INFORMATION

2.2.1 Location

YPG is located adjacent to the Colorado River in the Sonoran Desert. The UXO Standardized Test Site is located south of Pole Line Road and east of the Countermine Testing and Training Range. The Open Field range, Calibration Grid, Blind Grid, Mogul area, and Desert Extreme area comprise the 350 by 500-meter general test site area. The open field site is the largest of the test sites and measures approximately 200 by 350 meters. To the east of the open field range are the calibration and blind test grids that measure 30 by 40 meters and 40 by 40 meters, respectively. South of the Open Field is the 135- by 80-meter Mogul area consisting of a sequence of man-made depressions. The Desert Extreme area is located southeast of the open field site and has dimensions of 50 by 100 meters. The Desert Extreme area, covered with desert-type vegetation, is used to test the performance of different sensor platforms in a more severe desert conditions/environment.

2.2.2 Soil Type

Soil samples were collected at the YPG UXO Standardized Test Site by ERDC to characterize the shallow subsurface (< 3 m). Both surface grab samples and continuous soil borings were acquired. The soils were subjected to several laboratory analyses, including sieve/hydrometer, water content, magnetic susceptibility, dielectric permittivity, X-ray diffraction, and visual description.

There are two soil complexes present within the site, Riverbend-Carrizo and Cristobal-Gunsight. The Riverbend-Carrizo complex is comprised of mixed stream alluvium, whereas the Cristobal-Gunsight complex is derived from fan alluvium. The Cristobal-Gunsight complex covers the majority of the site. Most of the soil samples were classified as either a sandy loam or loamy sand, with most samples containing gravel-size particles. All samples had a measured water content less than 7 percent, except for two that contained 11-percent moisture. The majority of soil samples had water content between 1 to 2 percent. Samples containing more than 3 percent were generally deeper than 1 meter.

An X-ray diffraction analysis on four soil samples indicated a basic mineralogy of quartz, calcite, mica, feldspar, magnetite, and some clay. The presence of magnetite imparted a moderate magnetic susceptibility, with volume susceptibilities generally greater than 100 by 10-5 SI.

For more details concerning the soil properties at the YPG test site, go to www.uxotestsites.org on the web to view the entire soils description report.

2.2.3 Test Areas

A description of the test site areas at YPG is included in Table 2.

TABLE 2. TEST SITE AREAS

Area	Description
Calibration Grid	Contains the 15 standard ordnance items buried in six positions at various angles and depths to allow demonstrator equipment calibration.
Blind Grid	Contains 400 grid cells in a 0.16-hectare (0.39-acre) site. The center of each grid cell contains ordnance, clutter, or nothing.
Open Field	A 4-hectare (10-acre) site containing open areas, dips, ruts, and obstructions, including vegetation.
Mogul	A 2.64 acre area consisting of two areas (the rectangular or driving portion of the course and the triangular section with more difficult, non-drivable terrain). A series of craters (as deep as 0.91m) and trenches (as deep as 0.91m) encompass this section.

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SECTION 3. FIELD DATA

3.1 DATE OF FIELD ACTIVITIES (21 May 2003)

3.2 AREAS TESTED/NUMBER OF HOURS

Areas tested and total number of hours operated at each site are summarized in Table 3.

TABLE 3. AREAS TESTED AND NUMBER OF HOURS

Area	Number of Hours
Calibration Lanes	5.25
Mogul	5.55

3.3 TEST CONDITIONS

3.3.1 Weather Conditions

A YPG weather station located approximately one mile west of the test site was used to record average temperature and precipitation on a half hour basis for each day of operation. The temperatures listed in Table 4 represent the average temperature during field operations from 0700 to 1700 hours while precipitation data represents a daily total amount of rainfall. Hourly weather logs used to generate this summary are provided in Appendix B.

TABLE 4. TEMPERATURE/PRECIPITATION DATA SUMMARY

Date, 2003	Average Temperature, °F	Total Daily Precipitation, in.
21 May	N/A	N/A

3.3.2 Field Conditions

The field was dry and the weather was warm throughout the ERDC survey.

3.3.3 Soil Moisture

Three soil probes were placed at various locations within the site to capture soil moisture data: Blind Grid, Calibration, Desert Extreme, Open Field areas. Measurements were collected in percent moisture and were taken twice daily (morning and afternoon) from five different soil depths (1 to 6 in., 6 to 12 in., 12 to 24 in., 24 to 36 in., and 36 to 48 in.) from each probe. Soil moisture logs are included in Appendix C.

3.4 FIELD ACTIVITIES

3.4.1 Setup/Mobilization

These activities included initial mobilization and daily equipment preparation and break down. A five-person crew took 6 hours and 30 minutes to perform the initial setup and mobilization. There was 1-hour and 20 minutes of daily equipment preparation and end of the day equipment break down lasted 15 minutes.

3.4.2 Calibration

ERDC spent a total of 5 hours and 15 minutes in the calibration lanes, of which 1-hour and 50 minutes was spent collecting data. An additional 7 minutes of calibration took place in the Mogul area.

3.4.3 Downtime Occasions

Occasions of downtime are grouped into five categories: equipment/data checks or equipment maintenance, equipment failure and repair, weather, Demonstration Site issues, or breaks/lunch. All downtime is included for the purposes of calculating labor costs (section 5) except for downtime due to Demonstration Site issues. Demonstration Site issues, while noted in the Daily Log, are considered non-chargeable downtime for the purposes of calculating labor costs and are not discussed. Breaks and lunches are discussed in this section and billed to the total Site Survey area.

3.4.3.1 Equipment/data checks, maintenance. Equipment data checks and maintenance activities accounted for 53 minutes of site usage time. These activities included changing out batteries and routine data checks to ensure the data was being properly recorded/collected. ERDC spent no time for breaks and lunches.

3.4.3.2 Equipment failure or repair. 12 minutes was needed to resolve equipment failures that occurred while surveying the Mogul. A GPS mount broke. It was repaired and no further action was needed.

3.4.3.3 Weather. No weather delays occurred during the survey.

3.4.4 Data Collection

ERDC spent a total time of 5 hours and 33 minutes in the Mogul area, 2 hours and 53 minutes of which was spent collecting data.

3.4.5 Demobilization

The ERDC survey crew went on to conduct a full demonstration of the site. Therefore, demobilization did not occur until 22 May 2003. On that day, it took the crew 46 minutes to break down and pack up their equipment.

3.5 PROCESSING TIME

ERDC submitted the raw data from the demonstration activities on the last day of the demonstration, as required. The scoring submittal data was also provided within the required 30-day timeframe.

3.6 DEMONSTRATOR'S FIELD PERSONNEL

Field Manager:	Jose Llopis
Field Engineer:	Troy Broston, Eric Smith
Quality Assurance:	Don Yule
GPS Support:	Tom Berry

3.7 DEMONSTRATOR'S FIELD SURVEYING METHOD

ERDC collected data in a linear fashion and in a north to south direction.

3.8 SUMMARY OF DAILY LOGS

Daily logs capture all field activities during this demonstration and are located in Appendix D. Activities pertinent to this specific demonstration are indicated in highlighted text.

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SECTION 4. TECHNICAL PERFORMANCE RESULTS

4.1 ROC CURVES USING ALL ORDNANCE CATEGORIES

Figure 2 shows the probability of detection for the response stage (P_d^{res}) and the discrimination stage (P_d^{disc}) versus their respective probability of false positive. Figure 3 shows both probabilities plotted against their respective background alarm rate. Both figures use horizontal lines to illustrate the performance of the demonstrator at two demonstrator-specified points: at the system noise level for the response stage, representing the point below which targets are not considered detectable, and at the demonstrator's recommended threshold level for the discrimination stage, defining the subset of targets the demonstrator would recommend digging based on discrimination. Note that all points have been rounded to protect the ground truth.

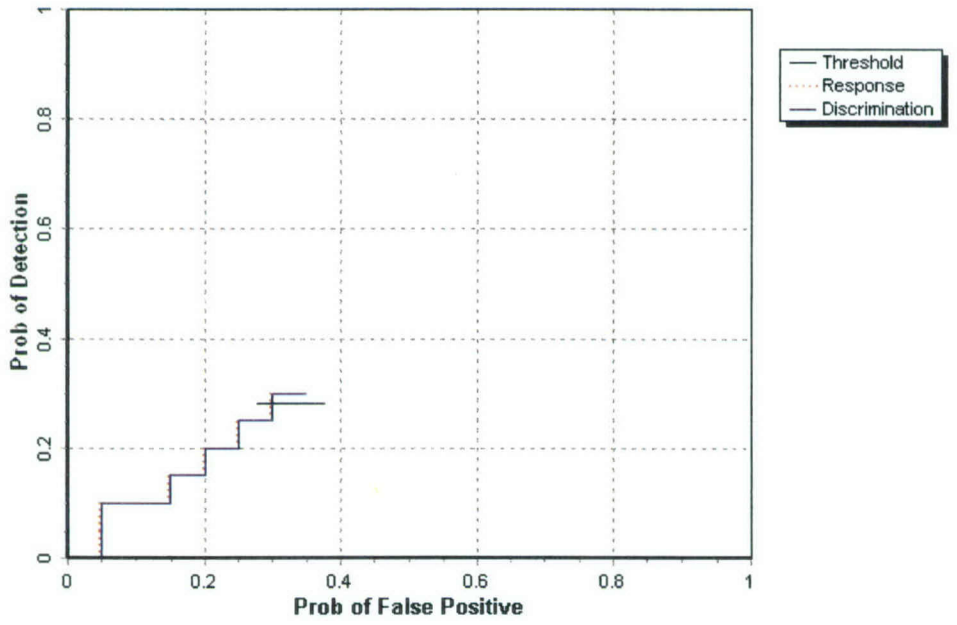

Figure 2. GEM-3/pushcart mogul probability of detection for response and discrimination stages versus their respective probability of false positive over all ordnance categories combined.

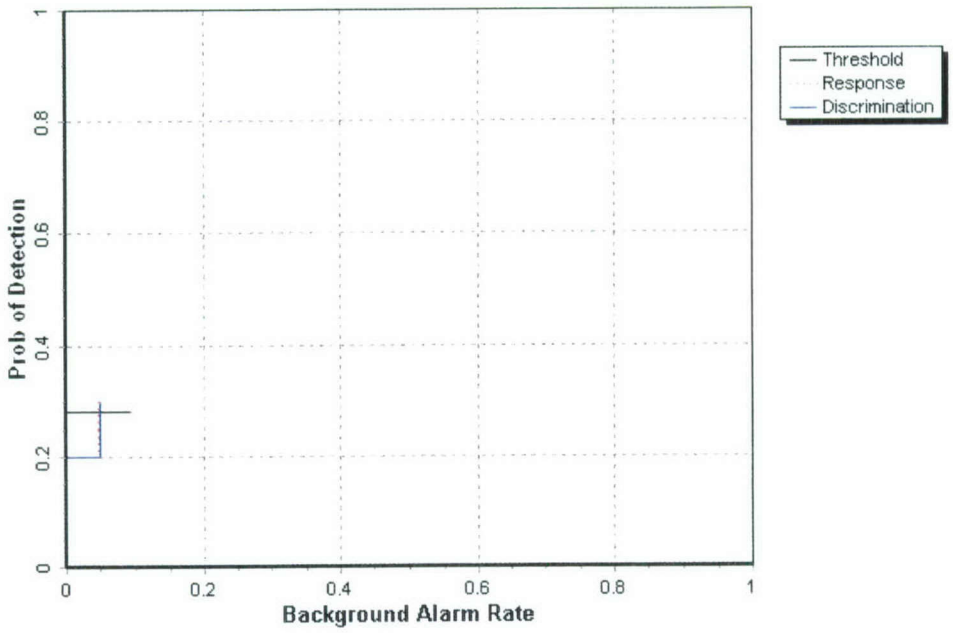

Figure 3. GEM-3/pushcart mogul probability of detection for response and discrimination stages versus their respective background alarm rate over all ordnance categories combined.

4.2 ROC CURVES USING ORDNANCE LARGER THAN 20 MM

Figure 4 shows the probability of detection for the response stage (P_d^{res}) and the discrimination stage (P_d^{disc}) versus their respective probability of false positive when only targets larger than 20 mm are scored. Figure 5 shows both probabilities plotted against their respective background alarm rate. Both figures use horizontal lines to illustrate the performance of the demonstrator at two demonstrator-specified points: at the system noise level for the response stage, representing the point below which targets are not considered detectable, and at the demonstrator's recommended threshold level for the discrimination stage, defining the subset of targets the demonstrator would recommend digging based on discrimination. Note that all points have been rounded to protect the ground truth.

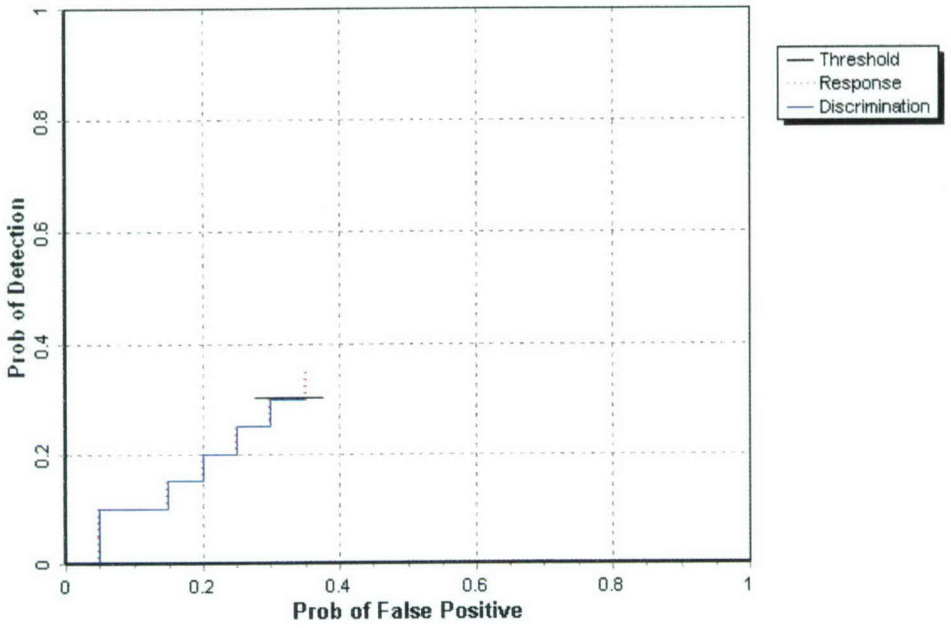

Figure 4. GEM-3/pushcart mogul probability of detection for response and discrimination stages versus their respective probability of false positive for all ordnance larger than 20 mm.

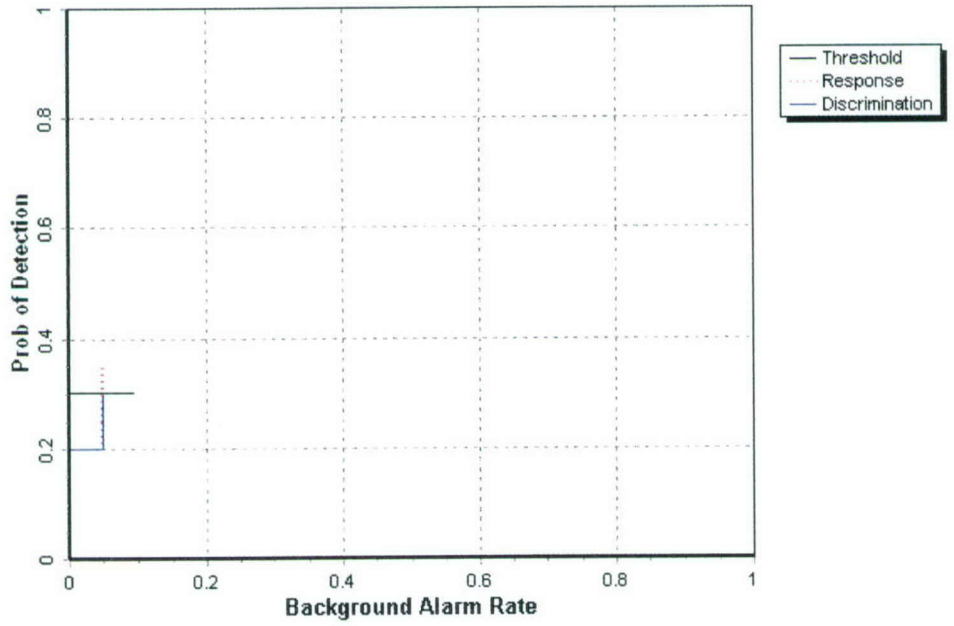

Figure 5. GEM-3/pushcart mogul probability of detection for response and discrimination stages versus their respective background alarm rate for all ordnance larger than 20 mm.

4.3 PERFORMANCE SUMMARIES

Results for the Mogul test broken out by size, depth and nonstandard ordnance are presented in Table 5 (for cost results, see section 5). Results by size and depth include both standard and nonstandard ordnance. The results by size show how well the demonstrator did at detecting/discriminating ordnance of a certain caliber range (see app A for size definitions). The results are relative to the number of ordnance items emplaced. Depth is measured from the geometric center of anomalies.

The RESPONSE STAGE results are derived from the list of anomalies above the demonstrator-provided noise level. The results for the DISCRIMINATION STAGE are derived from the demonstrator's recommended threshold for optimizing UXO field cleanup by minimizing false digs and maximizing ordnance recovery. The lower 90 percent confidence limit on probability of detection and P_{fp} was calculated assuming that the number of detections and false positives are binomially distributed random variables. All results in Table 5 have been rounded to protect the ground truth. However, lower confidence limits were calculated using actual results.

TABLE 5. SUMMARY OF MOGUL RESULTS FOR GEM-3/PUSHCART

Metric	Overall	Standard	Nonstandard	By Size			By Depth, m		
				Small	Medium	Large	< 0.3	0.3 to <1	>= 1
RESPONSE STAGE									
P_d	0.30	0.30	0.35	0.20	0.35	0.65	0.35	0.35	0.15
P_d Low 90% Conf	0.27	0.23	0.26	0.15	0.25	0.46	0.26	0.23	0.01
P_d Upper 90% Conf	0.38	0.38	0.46	0.30	0.47	0.80	0.41	0.45	0.45
P_{fp}	0.35	-	-	-	-	-	0.35	0.25	0.00
P_{fp} Low 90% Conf	0.29	-	-	-	-	-	0.31	0.17	0.00
P_{fp} Upper 90% Conf	0.38	-	-	-	-	-	0.41	0.38	0.68
BAR	0.05	-	-	-	-	-	-	-	-
DISCRIMINATION STAGE									
P_d	0.30	0.25	0.35	0.15	0.35	0.55	0.30	0.30	0.15
P_d Low 90% Conf	0.23	0.18	0.24	0.11	0.25	0.35	0.22	0.18	0.01
P_d Upper 90% Conf	0.34	0.32	0.44	0.25	0.47	0.70	0.37	0.40	0.45
P_{fp}	0.35	-	-	-	-	-	0.35	0.25	0.00
P_{fp} Low 90% Conf	0.28	-	-	-	-	-	0.30	0.15	0.00
P_{fp} Upper 90% Conf	0.37	-	-	-	-	-	0.41	0.35	0.68
BAR	0.05	-	-	-	-	-	-	-	-

Response Stage Noise Level: 50.00
Recommended Discrimination Stage Threshold: 70.00

Note: The recommended discrimination stage threshold values are provided by the demonstrator.

4.4 EFFICIENCY, REJECTION RATES, AND TYPE CLASSIFICATION

Efficiency and rejection rates are calculated to quantify the discrimination ability at specific points of interest on the ROC curve: (1) at the point where no decrease in P_d is suffered (i.e., the efficiency is by definition equal to one) and (2) at the operator selected threshold. These values are reported in Table 6.

TABLE 6. EFFICIENCY AND REJECTION RATES

	Efficiency (E)	False Positive Rejection Rate	Background Alarm Rejection Rate
At Operating Point	0.87	0.03	0.18
With No Loss of P_d	1.00	0.00	0.00

At the demonstrator's recommended setting, the ordnance items that were detected and correctly discriminated were further scored on whether their correct type could be identified (table 7). Correct type examples include "20-mm projectile, 105-mm HEAT Projectile, and 2.75-inch Rocket". A list of the standard type declaration required for each ordnance item was provided to demonstrators prior to testing. For example, the standard type for the three example items are 20mmP, 105H, and 2.75in, respectively.

TABLE 7. CORRECT TYPE CLASSIFICATION OF TARGETS CORRECTLY DISCRIMINATED AS UXO

Size	Percentage Correct
Small	N/A
Medium	N/A
Large	N/A
Overall	N/A

Note: The demonstrator did not attempt to provide type classification.

4.5 LOCATION ACCURACY

The mean location error and standard deviations appear in Table 8. These calculations are based on average missed depth for ordnance correctly identified in the discrimination stage. Depths are measured from the closest point of the ordnance to the surface. For the Blind Grid, only depth errors are calculated, since (X, Y) positions are known to be the centers of each grid square.

TABLE 8. MEAN LOCATION ERROR AND STANDARD DEVIATION (M)

	Mean	Standard Deviation
Northing	-0.05	0.24
Easting	0.00	0.19
Depth	0.05	0.28

SECTION 5. ON-SITE LABOR COSTS

A standardized estimate for labor costs associated with this effort was calculated as follows: the first person at the test site was designated "supervisor", the second person was designated "data analyst", and the third and following personnel were considered "field support". Standardized hourly labor rates were charged by title: supervisor at $95.00/hour, data analyst at $57.00/hour, and field support at $28.50/hour.

Government representatives monitored on-site activity. All on-site activities were grouped into one of ten categories: initial setup/mobilization, daily setup/stop, calibration, collecting data, downtime due to break/lunch, downtime due to equipment failure, downtime due to equipment/data checks or maintenance, downtime due to weather, downtime due to demonstration site issue, or demobilization. See Appendix D for the daily activity log. See section 3.4 for a summary of field activities.

The standardized cost estimate associated with the labor needed to perform the field activities is presented in Table 9. Note that calibration time includes time spent in the Calibration Lanes as well as field calibrations. "Site survey time" includes daily setup/stop time, collecting data, breaks/lunch, downtime due to equipment/data checks or maintenance, downtime due to failure, and downtime due to weather.

TABLE 9. ON-SITE LABOR COSTS

	No. People	Hourly Wage	Hours	Cost
Initial Setup				
Supervisor	1	$95.00	6.5	$617.50
Data Analyst	1	57.00	6.5	370.50
Field Support	2	28.50	6.5	370.50
SubTotal				**$1,358.50**
Calibration				
Supervisor	1	$95.00	5.37	$510.15
Data Analyst	1	57.00	5.37	306.09
Field Support	3	28.50	5.37	459.14
SubTotal				**$1,275.38**
Site Survey				
Supervisor	1	$95.00	5.55	$527.25
Data Analyst	1	57.00	5.55	299.25
Field Support	1	28.50	5.55	158.18
SubTotal				**$984.68**

See notes at end of table.

TABLE 9 (CONT'D)

	No. People	Hourly Wage	Hours	Cost
Demobilization				
Supervisor	1	$95.00	0.77	$73.15
Data Analyst	1	57.00	0.77	43.89
Field Support	1	28.50	0.77	21.95
Subtotal				**$138.99**
Total				**$3,757.55**

Notes: Calibration time includes time spent in the Calibration Lanes as well as calibration before each data run.

Site Survey time includes daily setup/stop time, collecting data, breaks/lunch, downtime due to system maintenance, failure, and weather.

SECTION 6. COMPARISON OF RESULTS TO OPEN FIELD DEMONSTRATION

6.1 SUMMARY OF RESULTS FROM OPEN FIELD DEMONSTRATION

Table 10 shows the results from Open Field survey conducted prior to surveying the Moguls during the same site visit in May of 2003. For more details on the Open Field survey results reference section 2.1.6.

TABLE 10. SUMMARY OF OPEN FIELD RESULTS FOR THE GEM-3/PUSHCART

Metric	Overall	Standard	Nonstandard	By Size			By Depth, m		
				Small	Medium	Large	< 0.3	0.3 to <1	>= 1
RESPONSE STAGE									
P_d	0.45	0.45	0.55	0.35	0.60	0.65	0.50	0.50	0.05
P_d Low 90% Conf	0.44	0.39	0.48	0.31	0.52	0.60	0.46	0.46	0.03
P_d Upper 90% Conf	0.50	0.47	0.57	0.39	0.63	0.73	0.54	0.56	0.16
P_{fp}	0.50	-	-	-	-	-	0.55	0.50	N/A
P_{fp} Low 90% Conf	0.50	-	-	-	-	-	0.51	0.47	N/A
P_{fp} Upper 90% Conf	0.54	-	-	-	-	-	0.55	0.55	0.21
BAR	0.15	-	-	-	-	-	-	-	-
DISCRIMINATION STAGE									
P_d	0.45	0.40	0.50	0.30	0.55	0.65	0.45	0.50	0.05
P_d Low 90% Conf	0.41	0.37	0.44	0.27	0.50	0.57	0.43	0.44	0.03
P_d Upper 90% Conf	0.47	0.45	0.53	0.35	0.61	0.71	0.50	0.54	0.16
P_{fp}	0.50	-	-	-	-	-	0.50	0.45	N/A
P_{fp} Low 90% Conf	0.47	-	-	-	-	-	0.48	0.42	N/A
P_{fp} Upper 90% Conf	0.50	-	-	-	-	-	0.52	0.49	0.21
BAR	0.05	-	-	-	-	-	-	-	-

6.2 COMPARISON OF ROC CURVES USING ALL ORDNANCE CATEGORIES

Figure 6 shows P_d^{res} versus the respective P_{fp} over all ordnance categories. Figure 7 shows P_d^{disc} versus their respective P_{fp} over all ordnance categories. Figure 7 uses horizontal lines to illustrate the performance of the demonstrator at the recommended discrimination threshold levels, defining the subset of targets the demonstrator would recommend digging based on discrimination.

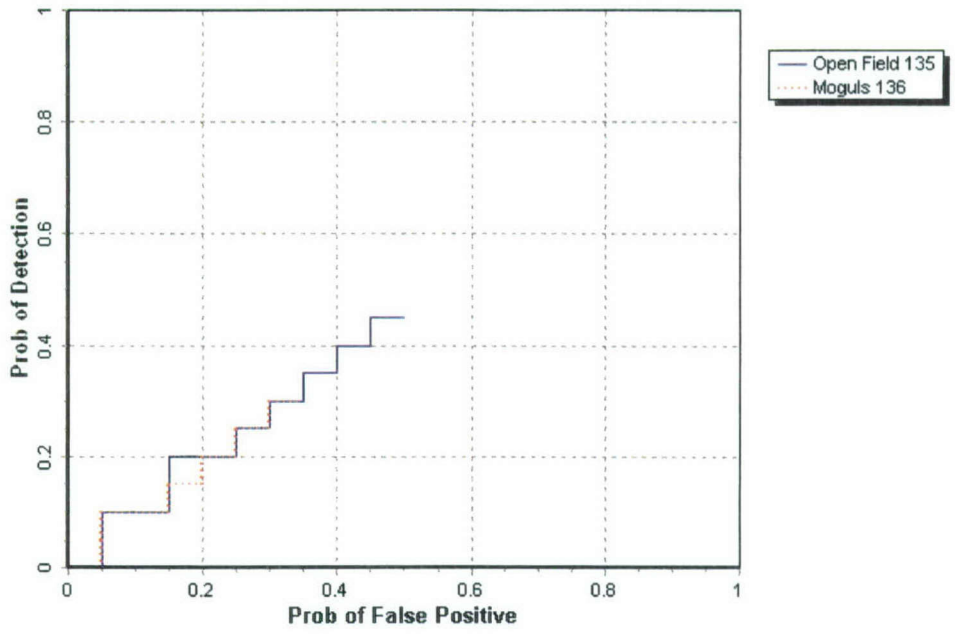

Figure 6. GEM-3/pushcart P_d^{res} stages versus the respective P_{fp} over all ordnance categories combined.

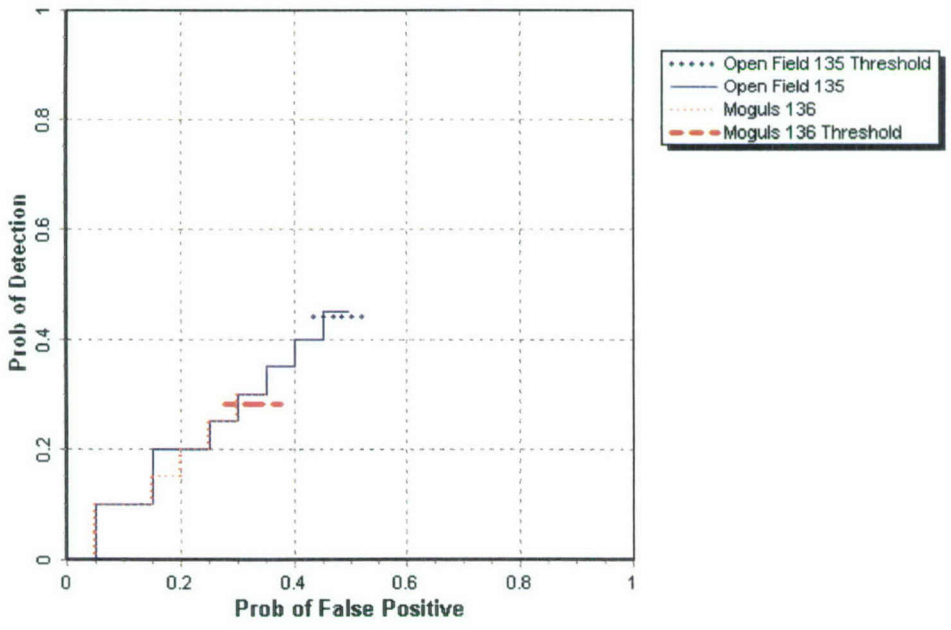

Figure 7. GEM-3/pushcart P_d^{disc} versus the respective P_{fp} over all ordnance categories combined.

6.3 COMPARISON OF ROC CURVES USING ORDNANCE LARGER THAN 20 MM

Figure 8 shows the P_d^{res} versus the respective probability of P_{fp} over ordnance larger than 20 mm. Figure 9 shows P_d^{disc} versus the respective P_{fp} over ordnance larger than 20 mm. Figure 9 uses horizontal lines to illustrate the performance of the demonstrator at the recommended discrimination threshold levels, defining the subset of targets the demonstrator would recommend digging based on discrimination.

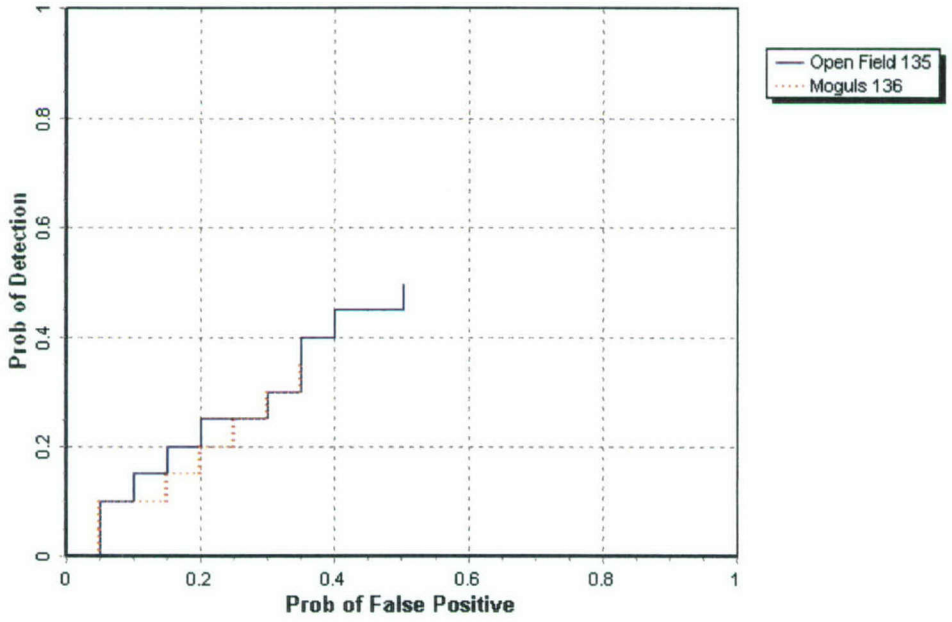

Figure 8. GEM-3/pushcart P_d^{res} versus the respective P_{fp} for ordnance larger than 20 mm.

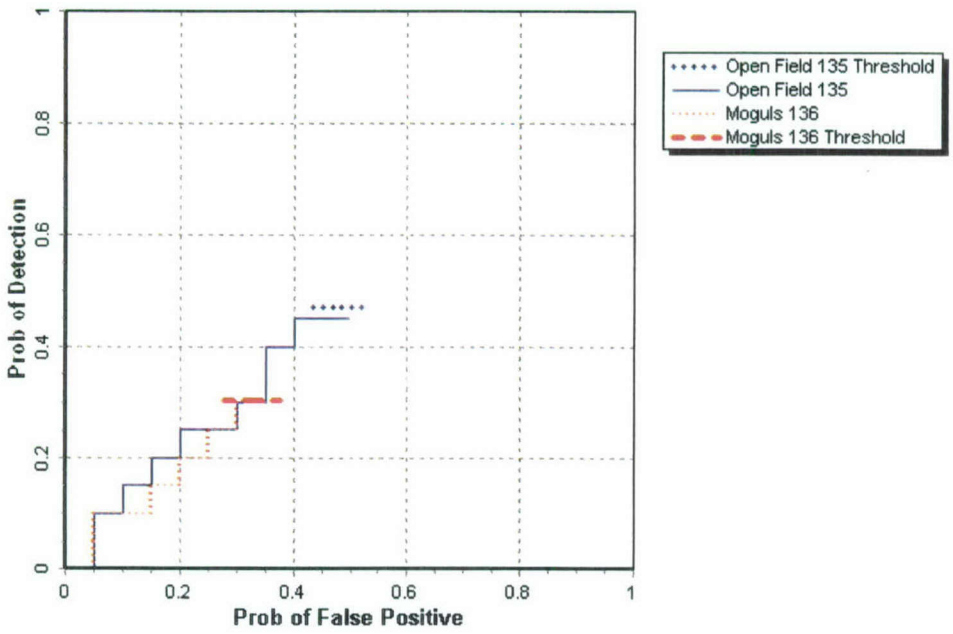

Figure 9. GEM-3/pushcart P_d^{disc} versus the respective P_{fp} for ordnance larger than 20 mm.

6.4 STATISTICAL COMPARISONS

Statistical Chi-square significance tests were used to compare results between the Open Field and Mogul Area scenarios. The intent of the comparison is to determine if the feature introduced in each scenario has a degrading effect on the performance of the sensor system. However, any modifications in the UXO sensor system during the test, like changes in the processing or changes in the selection of the operating threshold, will also contribute to performance differences.

The Chi-square test for comparison between ratios was used at a significance level of 0.05 to compare Open Field to Mogul Area with regard to P_d^{res}, P_d^{disc}, P_{fp}^{res} and P_{fp}^{disc}, Efficiency and Rejection Rate. These results are presented in Table 11. A detailed explanation and example of the Chi-square application is located in Appendix A.

TABLE 11. CHI-SQUARE RESULTS – OPEN FIELD VERSUS MOGUL

Metric	Small	Medium	Large	Overall
P_d^{res}	Significant	Significant	Not Significant	Significant
P_d^{disc}	Significant	Significant	Not Significant	Significant
P_{fp}^{res}	Not Significant	Not Significant	Not Significant	Not Significant
P_{fp}^{disc}	-	-	-	Significant
Efficiency	-	-	-	Significant
Rejection rate	-	-	-	Not Significant

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SECTION 7. APPENDIXES

APPENDIX A. TERMS AND DEFINITIONS

GENERAL DEFINITIONS

Anomaly: Location of a system response deemed to warrant further investigation by the demonstrator for consideration as an emplaced ordnance item.

Detection: An anomaly location that is within R_{halo} of an emplaced ordnance item.

Emplaced Ordnance: An ordnance item buried by the government at a specified location in the test site.

Emplaced Clutter: A clutter item (i.e., non-ordnance item) buried by the government at a specified location in the test site.

R_{halo}: A pre-determined radius about the periphery of an emplaced item (clutter or ordnance) within which a location identified by the demonstrator as being of interest is considered to be a response from that item. If multiple declarations lie within R_{halo} of any item (clutter or ordnance), the declaration with the highest signal output within the R_{halo} will be utilized. For the purpose of this program, a circular halo 0.5 meters in radius will be placed around the center of the object for all clutter and ordnance items less than 0.6 meters in length. When ordnance items are longer than 0.6 meters, the halo becomes an ellipse where the minor axis remains 1 meter and the major axis is equal to the length of the ordnance plus 1 meter.

Small Ordnance: Caliber of ordnance less than or equal to 40 mm (includes 20-mm projectile, 40-mm projectile, submunitions BLU-26, BLU-63, and M42).

Medium Ordnance: Caliber of ordnance greater than 40 mm and less than or equal to 81 mm (includes 57-mm projectile, 60-mm mortar, 2.75 in. Rocket, MK118 Rockeye, 81-mm mortar).

Large Ordnance: Caliber of ordnance greater than 81 mm (includes 105-mm HEAT, 105-mm projectile, 155-mm projectile, 500-pound bomb).

Shallow: Items buried less than 0.3 meter below ground surface.

Medium: Items buried greater than or equal to 0.3 meter and less than 1 meter below ground surface.

Deep: Items buried greater than or equal to 1 meter below ground surface.

Response Stage Noise Level: The level that represents the point below which anomalies are not considered detectable. Demonstrators are required to provide the recommended noise level for the Blind Grid test area.

Discrimination Stage Threshold: The demonstrator selected threshold level that they believe provides optimum performance of the system by retaining all detectable ordnance and rejecting the maximum amount of clutter. This level defines the subset of anomalies the demonstrator would recommend digging based on discrimination.

Binomially Distributed Random Variable: A random variable of the type which has only two possible outcomes, say success and failure, is repeated for n independent trials with the probability p of success and the probability 1-p of failure being the same for each trial. The number of successes x observed in the n trials is an estimate of p and is considered to be a binomially distributed random variable.

RESPONSE AND DISCRIMINATION STAGE DATA

The scoring of the demonstrator's performance is conducted in two stages. These two stages are termed the RESPONSE STAGE and DISCRIMINATION STAGE. For both stages, the probability of detection (P_d) and the false alarms are reported as receiver operating characteristic (ROC) curves. False alarms are divided into those anomalies that correspond to emplaced clutter items, measuring the probability of false positive (P_{fp}) and those that do not correspond to any known item, termed background alarms.

The RESPONSE STAGE scoring evaluates the ability of the system to detect emplaced targets without regard to ability to discriminate ordnance from other anomalies. For the RESPONSE STAGE, the demonstrator provides the scoring committee with the location and signal strength of all anomalies that the demonstrator has deemed sufficient to warrant further investigation and/or processing as potential emplaced ordnance items. This list is generated with minimal processing (e.g., this list will include all signals above the system noise threshold). As such, it represents the most inclusive list of anomalies.

The DISCRIMINATION STAGE evaluates the demonstrator's ability to correctly identify ordnance as such, and to reject clutter. For the same locations as in the RESPONSE STAGE anomaly list, the DISCRIMINATION STAGE list contains the output of the algorithms applied in the discrimination-stage processing. This list is prioritized based on the demonstrator's determination that an anomaly location is likely to contain ordnance. Thus, higher output values are indicative of higher confidence that an ordnance item is present at the specified location. For electronic signal processing, priority ranking is based on algorithm output. For other systems, priority ranking is based on human judgment. The demonstrator also selects the threshold that the demonstrator believes will provide "optimum" system performance, (i.e., that retains all the detected ordnance and rejects the maximum amount of clutter).

Note: The two lists provided by the demonstrator contain identical numbers of potential target locations. They differ only in the priority ranking of the declarations.

RESPONSE STAGE DEFINITIONS

Response Stage Probability of Detection (P_d^{res}): P_d^{res} = (No. of response-stage detections)/ (No. of emplaced ordnance in the test site).

Response Stage False Positive (fp^{res}): An anomaly location that is within R_{halo} of an emplaced clutter item.

Response Stage Probability of False Positive (P_{fp}^{res}): P_{fp}^{res} = (No. of response-stage false positives)/(No. of emplaced clutter items).

Response Stage Background Alarm (ba^{res}): An anomaly in a blind grid cell that contains neither emplaced ordnance nor an emplaced clutter item. An anomaly location in the open field or scenarios that is outside R_{halo} of any emplaced ordnance or emplaced clutter item.

Response Stage Probability of Background Alarm (P_{ba}^{res}): Blind Grid only: P_{ba}^{res} = (No. of response-stage background alarms)/(No. of empty grid locations).

Response Stage Background Alarm Rate (BAR^{res}): Open Field only: BAR^{res} = (No. of response-stage background alarms)/(arbitrary constant).

Note that the quantities P_d^{res}, P_{fp}^{res}, P_{ba}^{res}, and BAR^{res} are functions of t^{res}, the threshold applied to the response-stage signal strength. These quantities can therefore be written as $P_d^{res}(t^{res})$, $P_{fp}^{res}(t^{res})$, $P_{ba}^{res}(t^{res})$, and $BAR^{res}(t^{res})$.

DISCRIMINATION STAGE DEFINITIONS

Discrimination: The application of a signal processing algorithm or human judgment to response-stage data that discriminates ordnance from clutter. Discrimination should identify anomalies that the demonstrator has high confidence correspond to ordnance, as well as those that the demonstrator has high confidence correspond to nonordnance or background returns. The former should be ranked with highest priority and the latter with lowest.

Discrimination Stage Probability of Detection (P_d^{disc}): P_d^{disc} = (No. of discrimination-stage detections)/(No. of emplaced ordnance in the test site).

Discrimination Stage False Positive (fp^{disc}): An anomaly location that is within R_{halo} of an emplaced clutter item.

Discrimination Stage Probability of False Positive (P_{fp}^{disc}): P_{fp}^{disc} = (No. of discrimination stage false positives)/(No. of emplaced clutter items).

Discrimination Stage Background Alarm (ba^{disc}): An anomaly in a blind grid cell that contains neither emplaced ordnance nor an emplaced clutter item. An anomaly location in the open field or scenarios that is outside R_{halo} of any emplaced ordnance or emplaced clutter item.

Discrimination Stage Probability of Background Alarm (P_{ba}^{disc}): P_{ba}^{disc} = (No. of discrimination-stage background alarms)/(No. of empty grid locations).

Discrimination Stage Background Alarm Rate (BAR^{disc}): BAR^{disc} = (No. of discrimination-stage background alarms)/(arbitrary constant).

Note that the quantities P_d^{disc}, P_{fp}^{disc}, P_{ba}^{disc}, and BAR^{disc} are functions of t^{disc}, the threshold applied to the discrimination-stage signal strength. These quantities can therefore be written as $P_d^{disc}(t^{disc})$, $P_{fp}^{disc}(t^{disc})$, $P_{ba}^{disc}(t^{disc})$, and $BAR^{disc}(t^{disc})$.

RECEIVER-OPERATING CHARACERISTIC (ROC) CURVES

ROC curves at both the response and discrimination stages can be constructed based on the above definitions. The ROC curves plot the relationship between P_d versus P_{fp} and P_d versus BAR or P_{ba} as the threshold applied to the signal strength is varied from its minimum (t_{min}) to its maximum (t_{max}) value.[1] Figure A-1 shows how P_d versus P_{fp} and P_d versus BAR are combined into ROC curves. Note that the "res" and "disc" superscripts have been suppressed from all the variables for clarity.

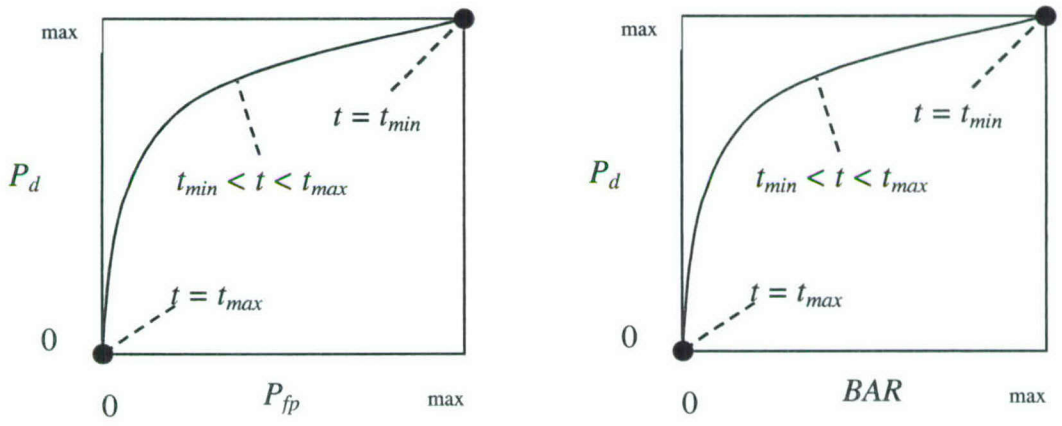

Figure A-1. ROC curves for open field testing. Each curve applies to both the response and discrimination stages.

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[1]Strictly speaking, ROC curves plot the P_d versus P_{ba} over a pre-determined and fixed number of detection opportunities (some of the opportunities are located over ordnance and others are located over clutter or blank spots). In an open field scenario, each system suppresses its signal strength reports until some bare-minimum signal response is received by the system. Consequently, the open field ROC curves do not have information from low signal-output locations, and, furthermore, different contractors report their signals over a different set of locations on the ground. These ROC curves are thus not true to the strict definition of ROC curves as defined in textbooks on detection theory. Note, however, that the ROC curves obtained in the Blind Grid test sites are true ROC curves.

METRICS TO CHARACTERIZE THE DISCRIMINATION STAGE

The demonstrator is also scored on efficiency and rejection ratio, which measure the effectiveness of the discrimination stage processing. The goal of discrimination is to retain the greatest number of ordnance detections from the anomaly list, while rejecting the maximum number of anomalies arising from nonordnance items. The efficiency measures the amount of detected ordnance retained by the discrimination, while the rejection ratio measures the fraction of false alarms rejected. Both measures are defined relative to the entire response list, i.e., the maximum ordnance detectable by the sensor and its accompanying false positive rate or background alarm rate.

Efficiency (E): $E = P_d^{disc}(t^{disc})/P_d^{res}(t_{min}^{res})$; Measures (at a threshold of interest), the degree to which the maximum theoretical detection performance of the sensor system (as determined by the response stage tmin) is preserved after application of discrimination techniques. Efficiency is a number between 0 and 1. An efficiency of 1 implies that all of the ordnance initially detected in the response stage was retained at the specified threshold in the discrimination stage, t^{disc}.

False Positive Rejection Rate (R_{fp}): $R_{fp} = 1 - [P_{fp}^{disc}(t^{disc})/P_{fp}^{res}(t_{min}^{res})]$; Measures (at a threshold of interest), the degree to which the sensor system's false positive performance is improved over the maximum false positive performance (as determined by the response stage tmin). The rejection rate is a number between 0 and 1. A rejection rate of 1 implies that all emplaced clutter initially detected in the response stage were correctly rejected at the specified threshold in the discrimination stage.

Background Alarm Rejection Rate (R_{ba}):

Blind Grid: $R_{ba} = 1 - [P_{ba}^{disc}(t^{disc})/P_{ba}^{res}(t_{min}^{res})]$.
Open Field: $R_{ba} = 1 - [BAR^{disc}(t^{disc})/BAR^{res}(t_{min}^{res})])$.

Measures the degree to which the discrimination stage correctly rejects background alarms initially detected in the response stage. The rejection rate is a number between 0 and 1. A rejection rate of 1 implies that all background alarms initially detected in the response stage were rejected at the specified threshold in the discrimination stage.

CHI-SQUARE COMPARISON EXPLANATION:

The Chi-square test for differences in probabilities (or 2 x 2 contingency table) is used to analyze two samples drawn from two different populations to see if both populations have the same or different proportions of elements in a certain category. More specifically, two random samples are drawn, one from each population, to test the null hypothesis that the probability of event A (some specified event) is the same for both populations (ref 3).

A 2 x 2 contingency table is used in the Standardized UXO Technology Demonstration Site Program to determine if there is reason to believe that the proportion of ordnance correctly detected/discriminated by demonstrator X's system is significantly degraded by the more challenging terrain feature introduced. The test statistic of the 2 x 2 contingency table is the

Chi-square distribution with one degree of freedom. Since an association between the more challenging terrain feature and relatively degraded performance is sought, a one-sided test is performed. A significance level of 0.05 is chosen which sets a critical decision limit of 2.71 from the Chi-square distribution with one degree of freedom. It is a critical decision limit because if the test statistic calculated from the data exceeds this value, the two proportions tested will be considered significantly different. If the test statistic calculated from the data is less than this value, the two proportions tested will be considered not significantly different.

An exception must be applied when either a 0 or 100 percent success rate occurs in the sample data. The Chi-square test cannot be used in these instances. Instead, Fischer's test is used and the critical decision limit for one-sided tests is the chosen significance level, which in this case is 0.05. With Fischer's test, if the test statistic is less than the critical value, the proportions are considered to be significantly different.

Standardized UXO Technology Demonstration Site examples, where blind grid results are compared to those from the open field and open field results are compared to those from one of the scenarios, follow. It should be noted that a significant result does not prove a cause and effect relationship exists between the two populations of interest; however, it does serve as a tool to indicate that one data set has experienced a degradation in system performance at a large enough level than can be accounted for merely by chance or random variation. Note also that a result that is not significant indicates that there is not enough evidence to declare that anything more than chance or random variation within the same population is at work between the two data sets being compared.

Demonstrator X achieves the following overall results after surveying each of the three progressively more difficult areas using the same system (results indicate the number of ordnance detected divided by the number of ordnance emplaced):

	Blind Grid	Open Field	Moguls
P_d^{res}	100/100 = 1.0	8/10 = .80	20/33 = .61
P_d^{disc}	80/100 = 0.80	6/10 = .60	8/33 = .24

P_d^{res}: BLIND GRID versus OPEN FIELD. Using the example data above to compare probabilities of detection in the response stage, all 100 ordnance out of 100 emplaced ordnance items were detected in the blind grid while 8 ordnance out of 10 emplaced were detected in the open field. Fischer's test must be used since a 100 percent success rate occurs in the data. Fischer's test uses the four input values to calculate a test statistic of 0.0075 that is compared against the critical value of 0.05. Since the test statistic is less than the critical value, the smaller response stage detection rate (0.80) is considered to be significantly less at the 0.05 level of significance. While a significant result does not prove a cause and effect relationship exists between the change in survey area and degradation in performance, it does indicate that the detection ability of demonstrator X's system seems to have been degraded in the open field relative to results from the blind grid using the same system.

P_d^{disc}: BLIND GRID versus OPEN FIELD. Using the example data above to compare probabilities of detection in the discrimination stage, 80 out of 100 emplaced ordnance items were correctly discriminated as ordnance in blind grid testing while 6 ordnance out of 10 emplaced were correctly discriminated as such in open field-testing. Those four values are used to calculate a test statistic of 1.12. Since the test statistic is less than the critical value of 2.71, the two discrimination stage detection rates are considered to be not significantly different at the 0.05 level of significance.

P_d^{res}: OPEN FIELD versus MOGULS. Using the example data above to compare probabilities of detection in the response stage, 8 out of 10 and 20 out of 33 are used to calculate a test statistic of 0.56. Since the test statistic is less than the critical value of 2.71, the two response stage detection rates are considered to be not significantly different at the 0.05 level of significance.

P_d^{disc}: OPEN FIELD versus MOGULS. Using the example data above to compare probabilities of detection in the discrimination stage, 6 out of 10 and 8 out of 33 are used to calculate a test statistic of 2.98. Since the test statistic is greater than the critical value of 2.71, the smaller discrimination stage detection rate is considered to be significantly less at the 0.05 level of significance. While a significant result does not prove a cause and effect relationship exists between the change in survey area and degradation in performance, it does indicate that the ability of demonstrator X to correctly discriminate seems to have been degraded by the mogul terrain relative to results from the flat open field using the same system.

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APPENDIX B. DAILY WEATHER LOGS

TABLE B-1. WEATHER LOG

Weather Data from Yuma Proving Ground				
Date	Time, EDST	Average Temperature, °F	RH, %	Precipitation, in.
5/7/2003	01:00	66.1	33	0.00
5/7/2003	02:00	64.8	35	0.00
5/7/2003	03:00	63.2	36	0.00
5/7/2003	04:00	62.0	37	0.00
5/7/2003	05:00	61.2	37	0.00
5/7/2003	06:00	60.2	38	0.00
5/7/2003	07:00	62.1	37	0.00
5/7/2003	08:00	63.4	38	0.00
5/7/2003	09:00	66.0	36	0.00
5/7/2003	10:00	69.2	33	0.00
5/7/2003	11:00	72.1	30	0.00
5/7/2003	12:00	74.6	26	0.00
5/7/2003	13:00	76.5	25	0.00
5/7/2003	14:00	77.4	24	0.00
5/7/2003	15:00	77.4	23	0.00
5/7/2003	16:00	77.9	23	0.00
5/7/2003	17:00	76.6	25	0.00
5/7/2003	18:00	74.7	26	0.00
5/7/2003	19:00	71.8	33	0.00
5/7/2003	20:00	69.5	36	0.00
5/7/2003	21:00	67.8	40	0.00
5/7/2003	22:00	65.8	45	0.00
5/7/2003	23:00	64.9	46	0.00
5/7/2003	24:00	63.8	47	0.00
5/8/2003	01:00	62.6	47	0.00
5/8/2003	02:00	61.8	45	0.00
5/8/2003	03:00	59.7	45	0.00
5/8/2003	04:00	58.0	48	0.00
5/8/2003	05:00	56.8	53	0.00
5/8/2003	06:00	55.5	56	0.00
5/8/2003	07:00	57.5	53	0.00
5/8/2003	08:00	60.5	47	0.00
5/8/2003	09:00	65.1	40	0.00
5/8/2003	10:00	67.3	36	0.00
5/8/2003	11:00	71.1	30	0.00
5/8/2003	12:00	72.9	29	0.00
5/8/2003	13:00	74.4	27	0.00
5/8/2003	14:00	76.4	24	0.00
5/8/2003	15:00	77.2	23	0.00
5/8/2003	16:00	78.1	22	0.00
5/8/2003	17:00	77.3	24	0.00
5/8/2003	18:00	76.2	22	0.00
5/8/2003	19:00	73.5	22	0.00

TABLE B-1 (CONT'D)

Weather Data from Yuma Proving Ground				
Date	Time, EDST	Average Temperature, °F	RH, %	Precipitation, in.
5/8/2003	20:00	69.5	29	0.00
5/8/2003	21:00	67.3	28	0.00
5/8/2003	22:00	64.5	32	0.00
5/8/2003	23:00	62.8	32	0.00
5/8/2003	24:00	60.8	38	0.00
5/9/2003	01:00	58.6	43	0.00
5/9/2003	02:00	57.9	45	0.00
5/9/2003	03:00	56.1	49	0.00
5/9/2003	04:00	54.6	52	0.00
5/9/2003	05:00	55.1	52	0.00
5/9/2003	06:00	55.0	51	0.00
5/9/2003	07:00	56.7	49	0.00
5/9/2003	08:00	59.7	45	0.00
5/9/2003	09:00	62.9	39	0.00
5/9/2003	10:00	65.8	33	0.00
5/9/2003	11:00	67.7	29	0.00
5/9/2003	12:00	69.8	26	0.00
5/9/2003	13:00	71.4	22	0.00
5/9/2003	14:00	72.2	17	0.00
5/9/2003	15:00	73.0	18	0.00
5/9/2003	16:00	75.0	16	0.00
5/9/2003	17:00	76.0	14	0.00
5/9/2003	18:00	75.8	12	0.00
5/9/2003	19:00	73.5	20	0.00
5/9/2003	20:00	71.4	20	0.00
5/9/2003	21:00	68.5	22	0.00
5/9/2003	22:00	66.4	24	0.00
5/9/2003	23:00	65.9	23	0.00
5/9/2003	24:00	63.4	27	0.00
5/10/2003	01:00	60.5	34	0.00
5/10/2003	02:00	59.6	39	0.00
5/10/2003	03:00	56.9	42	0.00
5/10/2003	04:00	54.6	44	0.00
5/10/2003	05:00	53.2	43	0.00
5/10/2003	06:00	51.0	44	0.00
5/10/2003	07:00	58.1	32	0.00
5/10/2003	08:00	64.8	31	0.00
5/10/2003	09:00	68.4	25	0.00
5/10/2003	10:00	72.5	20	0.00
5/10/2003	11:00	76.3	15	0.00
5/10/2003	12:00	77.8	12	0.00
5/10/2003	13:00	79.8	13	0.00
5/10/2003	14:00	81.7	12	0.00
5/10/2003	15:00	81.8	12	0.00
5/10/2003	16:00	83.2	10	0.00

TABLE B-1 (CONT'D)

Weather Data from Yuma Proving Ground				
Date	Time, EDST	Average Temperature, °F	RH, %	Precipitation, in.
5/10/2003	17:00	83.3	10	0.00
5/10/2003	18:00	82.7	10	0.00
5/10/2003	19:00	81.6	10	0.00
5/10/2003	20:00	78.1	13	0.00
5/10/2003	21:00	75.4	15	0.00
5/10/2003	22:00	72.8	15	0.00
5/10/2003	23:00	68.9	18	0.00
5/10/2003	24:00	66.1	19	0.00
5/12/2003	01:00	71.2	21	0.00
5/12/2003	02:00	69.7	21	0.00
5/12/2003	03:00	67.2	23	0.00
5/12/2003	04:00	63.2	24	0.00
5/12/2003	05:00	63.4	25	0.00
5/12/2003	06:00	61.7	26	0.00
5/12/2003	07:00	65.9	21	0.00
5/12/2003	08:00	74.7	15	0.00
5/12/2003	09:00	81.7	14	0.00
5/12/2003	10:00	86.5	12	0.00
5/12/2003	11:00	89.3	10	0.00
5/12/2003	12:00	90.8	11	0.00
5/12/2003	13:00	93.0	8	0.00
5/12/2003	14:00	94.3	8	0.00
5/12/2003	15:00	95.7	8	0.00
5/12/2003	16:00	95.0	8	0.00
5/12/2003	17:00	94.7	9	0.00
5/12/2003	18:00	94.7	9	0.00
5/12/2003	19:00	92.2	9	0.00
5/12/2003	20:00	89.5	9	0.00
5/12/2003	21:00	85.3	10	0.00
5/12/2003	22:00	83.4	16	0.00
5/12/2003	23:00	80.4	17	0.00
5/12/2003	24:00	79.1	19	0.00
5/14/2003	01:00	76.0	21	0.00
5/14/2003	02:00	74.1	21	0.00
5/14/2003	03:00	72.4	22	0.00
5/14/2003	04:00	73.2	21	0.00
5/14/2003	05:00	71.8	21	0.00
5/14/2003	06:00	73.4	18	0.00
5/14/2003	07:00	73.2	19	0.00
5/14/2003	08:00	77.0	15	0.00
5/14/2003	09:00	82.6	13	0.00
5/14/2003	10:00	85.0	12	0.00
5/14/2003	11:00	88.9	10	0.00
5/14/2003	12:00	92.4	9	0.00
5/14/2003	13:00	94.8	8	0.00

TABLE B-1 (CONT'D)

Weather Data from Yuma Proving Ground				
Date	Time, EDST	Average Temperature, °F	RH, %	Precipitation, in.
5/14/2003	14:00	97.4	7	0.00
5/14/2003	15:00	96.2	6	0.00
5/14/2003	16:00	96.5	7	0.00
5/14/2003	17:00	94.6	9	0.00
5/14/2003	18:00	93.8	7	0.00
5/14/2003	19:00	92.0	8	0.00
5/14/2003	20:00	87.9	10	0.00
5/14/2003	21:00	84.4	11	0.00
5/14/2003	22:00	81.9	11	0.00
5/14/2003	23:00	79.4	12	0.00
5/14/2003	24:00	78.6	12	0.00
5/15/2003	01:00	62.5	39	0.00
5/15/2003	02:00	61.1	40	0.00
5/15/2003	03:00	60.0	44	0.00
5/15/2003	04:00	58.1	49	0.00
5/15/2003	05:00	57.9	51	0.00
5/15/2003	06:00	57.0	52	0.00
5/15/2003	07:00	60.8	46	0.00
5/15/2003	08:00	64.5	45	0.00
5/15/2003	09:00	68.3	37	0.00
5/15/2003	10:00	73.1	31	0.00
5/15/2003	11:00	78.0	26	0.00
5/15/2003	12:00	81.0	23	0.00
5/15/2003	13:00	83.4	22	0.00
5/15/2003	14:00	85.7	20	0.00
5/15/2003	15:00	87.5	18	0.00
5/15/2003	16:00	89.7	17	0.00
5/15/2003	17:00	89.8	17	0.00
5/15/2003	18:00	89.9	17	0.00
5/15/2003	19:00	88.4	18	0.00
5/15/2003	20:00	86.0	19	0.00
5/15/2003	21:00	83.4	21	0.00
5/15/2003	22:00	80.2	22	0.00
5/15/2003	23:00	75.7	25	0.00
5/15/2003	24:00	73.7	26	0.00
5/16/2003	01:00	73.9	29	0.00
5/16/2003	02:00	70.8	32	0.00
5/16/2003	03:00	69.2	32	0.00
5/16/2003	04:00	68.5	33	0.00
5/16/2003	05:00	66.7	35	0.00
5/16/2003	06:00	65.4	35	0.00
5/16/2003	07:00	70.5	30	0.00
5/16/2003	08:00	79.3	23	0.00
5/16/2003	09:00	86.4	17	0.00
5/16/2003	10:00	90.0	14	0.00

TABLE B-1 (CONT'D)

Weather Data from Yuma Proving Ground				
Date	Time, EDST	Average Temperature, °F	RH, %	Precipitation, in.
5/16/2003	11:00	92.0	14	0.00
5/16/2003	12:00	94.0	13	0.00
5/16/2003	13:00	95.5	12	0.00
5/16/2003	14:00	97.9	11	0.00
5/16/2003	15:00	98.9	11	0.00
5/16/2003	16:00	99.9	11	0.00
5/16/2003	17:00	99.4	12	0.00
5/16/2003	18:00	99.1	10	0.00
5/16/2003	19:00	97.7	11	0.00
5/16/2003	20:00	93.1	12	0.00
5/16/2003	21:00	87.8	14	0.00
5/16/2003	22:00	86.1	16	0.00
5/16/2003	23:00	83.0	18	0.00
5/16/2003	24:00	80.4	19	0.00
5/19/2003	01:00	79.3	19	0.00
5/19/2003	02:00	77.6	19	0.00
5/19/2003	03:00	75.2	20	0.00
5/19/2003	04:00	73.4	21	0.00
5/19/2003	05:00	71.6	24	0.00
5/19/2003	06:00	68.4	25	0.00
5/19/2003	07:00	74.2	23	0.00
5/19/2003	08:00	80.5	25	0.00
5/19/2003	09:00	84.5	24	0.00
5/19/2003	10:00	89.7	14	0.00
5/19/2003	11:00	94.4	11	0.00
5/19/2003	12:00	97.3	10	0.00
5/19/2003	13:00	99.8	8	0.00
5/19/2003	14:00	101.0	8	0.00
5/19/2003	15:00	101.1	8	0.00
5/19/2003	16:00	101.3	7	0.00
5/19/2003	17:00	101.9	7	0.00
5/19/2003	18:00	101.0	7	0.00
5/19/2003	19:00	99.1	8	0.00
5/19/2003	20:00	95.2	9	0.00
5/19/2003	21:00	91.4	11	0.00
5/19/2003	22:00	88.1	11	0.00
5/19/2003	23:00	83.8	13	0.00
5/19/2003	24:00	81.7	15	0.00
6/4/2003	01:00	81.0	19	0.00
6/4/2003	02:00	80.0	22	0.00
6/4/2003	03:00	78.0	22	0.00
6/4/2003	04:00	75.5	28	0.00
6/4/2003	05:00	75.1	32	0.00
6/4/2003	06:00	74.3	34	0.00
6/4/2003	07:00	77.1	32	0.00

TABLE B-1 (CONT'D)

Weather Data from Yuma Proving Ground				
Date	Time, EDST	Average Temperature, °F	RH, %	Precipitation, in.
6/4/2003	08:00	82.1	27	0.00
6/4/2003	09:00	87.3	22	0.00
6/4/2003	10:00	89.9	19	0.00
6/4/2003	11:00	93.9	15	0.00
6/4/2003	12:00	95.8	14	0.00
6/4/2003	13:00	98.5	13	0.00
6/4/2003	14:00	100.8	12	0.00
6/4/2003	15:00	102.5	12	0.00
6/4/2003	16:00	103.5	11	0.00
6/4/2003	17:00	103.4	10	0.00
6/4/2003	18:00	102.5	10	0.00
6/4/2003	19:00	100.0	10	0.00
6/4/2003	20:00	96.6	11	0.00
6/4/2003	21:00	94.1	11	0.00
6/4/2003	22:00	90.9	12	0.00
6/4/2003	23:00	86.7	14	0.00
6/4/2003	24:00	84.1	16	0.00

APPENDIX C. SOIL MOISTURE

SOIL MOISTURE LOGS (6 through 17, 19 through 22, and 28 through 30 May 2003)

Date	Time	Calibration Area Readings (%)					Time	Mogul Area Readings (%)					Time	Desert Extreme Area Readings (%)				
		0 to 6 in.	6 to 12 in.	12 to 24 in.	24 to 36 in.	36 to 48 in.		0 to 6 in.	6 to 12 in.	12 to 24 in.	24 to 36 in.	36 to 48 in.		0 to 6 in.	6 to 12 in.	12 to 24 in.	24 to 36 in.	36 to 48 in.
5/6/2003	0748	1.8	2.2	3.7	3.6	4.0	0807	1.7	2.0	3.4	4.0	4.1	800	1.7	2.0	3.5	3.9	4.0
	1237	1.8	2.2	3.6	3.6	4.0	1246	1.6	2.0	3.6	3.9	4.0	1254	1.7	2.0	3.4	3.9	4.1
5/7/2003	0723	1.8	2.2	3.6	3.6	3.9	0740	1.6	2.0	3.6	3.9	3.9	733	1.7	2.0	3.4	3.9	4.1
	1255	1.8	2.2	3.7	3.6	4.0	1310	1.6	2.0	3.5	3.9	4.0	1305	1.7	2.0	3.4	3.9	4.1
5/8/2003	0715	1.8	2.2	3.6	3.6	3.9	0724	1.6	2.0	3.6	4.0	3.9	732	1.7	2.0	3.4	3.9	4.1
	1243	1.8	2.2	3.7	3.6	3.9	1250	1.6	2.0	3.5	4.0	4.0	1258	1.7	2.0	3.4	3.9	4.1
5/9/2003	0623	1.8	2.2	3.6	3.6	3.9	0638	1.6	2.0	3.5	3.9	3.9	631	1.7	2.0	3.4	3.9	4.1
	1306	1.8	2.2	3.6	3.6	3.9	1315	1.6	2.0	3.5	3.9	3.9	1324	1.7	2.0	3.4	3.9	4.1
5/10/2003	0618	1.8	2.2	3.7	3.6	3.9	0626	1.6	2.0	3.5	3.9	4.0	634	1.7	2.0	3.4	3.9	4.1
	1203	1.8	2.2	3.6	3.6	3.9	1212	1.6	2.0	3.6	3.9	4.0	1221	1.7	2.0	3.4	3.9	4.1
5/12/2003	0630	1.8	2.2	3.7	3.6	3.9	0638	1.6	2.0	3.6	3.9	4.0	644	1.7	2.0	3.4	3.9	4.1
	1256	1.8	2.2	3.6	3.6	3.9	1305	1.6	2.0	3.5	3.9	4.0	1313	1.7	2.0	3.4	3.9	4.1
5/13/2003	0711	1.8	2.2	3.6	3.6	3.9	0719	1.7	2.0	3.6	3.9	4.0	726	1.7	2.0	3.4	3.9	4.1
	1312	1.8	2.2	3.7	3.6	4.0	1323	1.6	2.0	3.6	3.9	4.0	1332	1.7	2.0	3.4	3.9	4.1
5/14/2003	0630	1.8	2.2	3.7	3.6	4.0	0639	1.7	2.0	3.6	3.9	4.0	647	1.7	2.0	3.4	3.9	4.1
	1302	1.8	2.2	3.7	3.6	3.9	1312	1.7	2.0	3.6	4.0	4.0	1318	1.7	2.0	3.4	3.9	4.1
5/15/2003	0626	1.8	2.2	3.6	3.6	3.9	0640	1.7	2.0	3.6	3.9	4.0	648	1.7	2.0	3.4	3.9	4.1
	1302	1.8	2.2	3.7	3.6	4.0	1310	1.6	2.0	3.6	4.0	4.0	1318	1.7	2.0	3.4	3.9	4.1
5/16/2003	0622	1.8	2.2	3.7	3.6	3.9	0629	1.7	2.0	3.6	4.0	4.0	0637	1.7	2.0	3.4	3.9	4.1
	1250	1.8	2.2	3.6	3.6	3.9	1258	1.6	2.0	3.5	3.9	4.0	1305	1.7	2.0	3.4	3.9	4.1
5/17/2003	0610	1.8	2.2	3.7	3.6	3.9	0618	1.6	2.0	3.6	3.9	4.0	0626	1.7	2.0	3.4	3.9	4.1
	1319	1.8	2.2	3.6	3.6	4.0	1327	1.6	2.0	3.6	3.9	4.0	1334	1.7	2.0	3.4	3.9	4.1
5/19/2003	0600	1.8	2.2	3.6	3.6	4.0	0608	1.6	1.9	3.6	3.9	4.0	0615	1.7	2.0	3.4	4.0	4.1
	1306	1.8	2.2	3.7	3.6	4.0	1316	1.6	2.0	3.6	3.9	4.0	1324	1.7	2.0	3.4	4.0	4.1
5/20/2003	0534	1.8	2.2	3.7	3.6	4.0	0542	1.6	2.0	3.6	3.9	4.0	0550	1.7	2.0	3.4	3.9	4.1
	1311	1.8	2.2	3.7	3.6	4.0	1320	1.6	2.0	3.6	3.9	4.0	1326	1.7	2.0	3.4	4.0	4.1
5/21/2003	0547	1.8	2.2	3.7	3.6	4.0	0555	1.6	2.0	3.6	4.0	4.1	0603	1.7	2.0	3.4	4.0	4.1
	1301	1.8	2.2	3.7	3.6	4.0	1309	1.6	2.0	3.6	4.0	4.0	1316	1.7	2.0	3.4	4.0	4.1
5/22/2003	0535	1.8	2.2	3.7	3.6	4.0	0543	1.6	2.0	3.6	4.0	4.0	0550	1.7	2.0	3.4	4.0	4.1
	1303	1.8	2.2	3.7	3.6	4.0	1311	1.6	2.0	3.6	4.0	4.0	1318	1.7	2.0	3.4	4.0	4.1
5/28/2003	0722	1.8	2.2	3.7	3.6	4.0	0730	1.6	2.0	3.6	4.0	4.0	0743	1.7	2.0	3.4	4.0	4.1
	1210	1.8	2.2	3.7	3.6	4.0	1218	1.6	2.0	3.6	4.0	4.0	1225	1.7	2.0	3.4	4.0	4.1
5/29/2003	0645	1.8	2.2	3.7	3.6	4.0	0653	1.6	2.0	3.6	4.0	4.0	0700	1.7	2.0	3.4	4.0	4.1
	1222	1.8	2.2	3.7	3.6	4.0	1230	1.6	2.0	3.6	4.0	4.0	1237	1.7	2.0	3.4	4.0	4.1
5/30/2003	0600	1.8	2.2	3.7	3.6	4.0	0609	1.6	2.0	3.6	4.0	4.0	0616	1.7	2.0	3.4	4.0	4.1
	1239	1.8	2.2	3.7	3.6	4.0	1248	1.6	2.0	3.6	4.0	4.0	1255	1.7	2.0	3.4	4.0	4.1

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Date	No. of People	Area Tested	Status Start Time	Status Stop Time	Duration, min	Operational Status	Operational Status - Comments	Track Method	Track Method=Other Explain	Pattern	Field Conditions	
5/5/2003		INTIAL SETUP	1015	1045	30	SET UP/MOBILIZATION	SETTING UP EQUIPMENT	NA	NA	NA	HOT	DRY
5/5/2003	4	INTIAL SETUP	1045	1100	15	BREAK/LUNCH	LUNCH	NA	NA	NA	HOT	DRY
5/5/2003	4	INTIAL SETUP	1100	1530	270	SET UP/MOBILIZATION	SETTING UP EQUIPMENT	NA	NA	NA	HOT	DRY
5/5/2003	4	INITIAL SETUP	1530	1600	30	SET UP/MOBILIZATION	BREAKING DOWN EQUIPMENT EOD	NA	NA	NA	HOT	DRY
5/6/2003	5	INITIAL SETUP	0730	0815	45	SET UP/MOBILIZATION	SETTING UP EQUIPMENT	GPS	NA	NA	HOT	DRY
5/6/2003	5	CALIBRATION LANES	0815	0915	60	COLLECTING DATA	RUNNING CAL LANE, BI DIRECTION, NORTH/SOUTH	NA	NA	NA	HOT	DRY
5/6/2003	5	CALIBRATION LANES	0915	1030	75	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	HOT	DRY
5/6/2003	5	CALIBRATION LANES	1030	1120	50	COLLECTING DATA	RUNNING CAL LANE BI DIRECTION EAST/WEST	GPS	NA	NA	HOT	DRY
5/6/2003	5	CALIBRATION LANES	1120	1140	70	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	NA	NA	NA	HOT	DRY
5/6/2003	5	CALIBRATION LANES	1140	1210	30	BREAK/LUNCH	LUNCH	GPS	NA	NA	HOT	DRY
5/6/2003	5	CALIBRATION LANES	1210	1240	30	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	NA	NA	NA	HOT	DRY
5/6/2003	5	BLIND TEST GRID	1240	1355	75	COLLECTING DATA	RUNNING BTG, BIDIRECTION EAST/WEST	GPS	NA	NA	HOT	DRY
5/6/2003	5	BLIND TEST GRID	1355	1430	35	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	HOT	DRY
5/6/2003	5	CALIBRATION PIT	1430	1450	20	SET UP/MOBILIZATION	SETTING UP EQUIPMENT	GPS	NA	NA	HOT	DRY
5/6/2003	5	CALIBRATION PIT	1450	1515	25	COLLECTING DATA	COLLECT DATA OVER PIT	GPS	NA	NA	HOT	DRY

Note: Activities pertinent to this specific demonstration are indicated in highlighted text.

Date	No. of People	Area Tested	Status Start Time	Status Stop Time	Duration, min	Operational Status	Operational Status - Comments	Track Method	Track Method=Other Explain	Pattern	Field Conditions	
5/6/2003	5	CALIBRATION PIT	1515	1520	5	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHANGE OUT BATTERY	GPS	NA	NA	HOT	DRY
5/6/2003	5	CALIBRATION PIT	1520	1525	5	COLLECTING DATA	COLLECT DATA OVER PIT	GPS	NA	NA	HOT	DRY
5/6/2003	5	CALIBRATION PIT	1525	1535	10	SET UP/MOBILIZATION	BREAKING DOWN EQUIPMENT EOD	NA	NA	NA	HOT	DRY
5/7/2003	4	OPEN RANGE	0715	0855	100	SET UP/MOBILIZATION	SETTING UP EQUIPMENT	NA	NA	NA	COOL/WINDY	DRY
5/7/2003	4	OPEN RANGE	0855	1035	100	COLLECTING DATA	RUNNING OPEN RANGE, GRID A2, BIDIRECTIONAL E/W	GPS	NA	NA	COOL/WINDY	DRY
5/7/2003	4	OPEN RANGE	1035	1115	40	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	HOT/WINDY	DRY
5/7/2003	4	OPEN RANGE	1115	1125	10	SET UP/MOBILIZATION	SETTING UP EQUIPMENT	GPS	NA	NA	HOT/WINDY	DRY
5/7/2003	4	OPEN RANGE	1125	1300	95	COLLECTING DATA	RUNNING OPEN RANGE, GRID A3, BIDIRECTIONAL E/W	GPS	NA	NA	HOT/WINDY	DRY
5/7/2003	4	OPEN RANGE	1300	1330	30	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	HOT/WINDY	DRY
5/7/2003	4	OPEN RANGE	1330	1350	20	BREAK/LUNCH	BREAK	NA	NA	NA	HOT/WINDY	DRY
5/7/2003	4	OPEN RANGE	1350	1400	10	SET UP/MOBILIZATION	SETTING UP EQUIPMENT	NA	NA	NA	HOT/WINDY	DRY
5/7/2003	4	OPEN RANGE	1400	1530	90	COLLECTING DATA	RUNNING OPEN RANGE GRID G2, BIDIRECTIONAL E/W	GPS	NA	NA	HOT/WINDY	DRY
5/7/2003	4	OPEN RANGE	1530	1550	20	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	HOT/WINDY	DRY
5/7/2003	4	OPEN RANGE	1550	1600	10	SET UP/MOBILIZATION	BREAKING DOWN EQUIPMENT EOD	NA	NA	NA	HOT/WINDY	DRY
5/8/2003	5	OPEN RANGE	0700	0745	45	SET UP/MOBILIZATION	SETTING UP EQUIPMENT	NA	NA	NA	COOL/WINDY	DRY
5/8/2003	5	OPEN RANGE	0745	0950	125	COLLECTING DATA	RUNNING OPEN RANGE, GRID G3,G4, BIDIRECTIONAL E/W	GPS	NA	NA	COOL/WINDY	DRY

Date	No. of People	Area Tested	Status Start Time	Status Stop Time	Duration, min	Operational Status	Operational Status - Comments	Track Method	Track Method=Other Explain	Pattern	Field Conditions	
5/8/2003	5	OPEN RANGE	0950	1020	30	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	COOL/WINDY	DRY
5/8/2003	5	BLIND TEST GRID	1020	1130	70	COLLECTING DATA	RUNNING BTG BIDIRECTIONAL NORTH/ SOUTH	GPS	NA	NA	HOT/WINDY	DRY
5/8/2003	5	BLIND TEST GRID	1130	1145	15	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	HOT/WINDY	DRY
5/8/2003	5	BLIND TEST GRID	1145	1215	30	BREAK/LUNCH	LUNCH	GPS	NA	NA	HOT/WINDY	DRY
5/8/2003	5	OPEN RANGE	1215	1300	45	SET UP/MOBILIZATION	LAYOUT LANES WITH ROPE	NA	NA	NA	HOT/WINDY	DRY
5/8/2003	5	CALIBRATION PIT	1300	1440	100	COLLECTING DATA	COLLECT DATA OVER PIT	GPS	NA	NA	HOT/WINDY	DRY
5/8/2003	5	CALIBRATION PIT	1440	1500	20	BREAK/LUNCH	BREAK	NA	NA	NA	HOT/WINDY	DRY
5/8/2003	5	OPEN RANGE	1500	1550	50	SET UP/MOBILIZATION	LAYOUT LANES WITH ROPE	NA	NA	NA	HOT/WINDY	DRY
5/8/2003	5	OPEN RANGE	1550	1600	10	SET UP/MOBILIZATION	BREAKING DOWN EQUIPMENT EOD	NA	NA	NA	HOT/WINDY	DRY
5/9/2003	4	OPEN RANGE	0645	0720	35	SET UP/MOBILIZATION	SETTING UP EQUIPMENT	NA	NA	NA	COOL	DRY
5/9/2003	4	OPEN RANGE	0720	0845	85	COLLECTING DATA	RUNNING OPEN RANGE, GRID F2,F3,F4,F5 BIDIRECTIONAL E/W	GPS	NA	LINEAR	COOL/WINDY	DRY
5/9/2003	4	OPEN RANGE	0845	0905	20	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	COOL/WINDY	DRY
5/9/2003	4	OPEN RANGE	0905	1030	85	COLLECTING DATA	RUNNING OPEN RANGE, GRID F2,F3,F4,F5 BIDIRECTIONAL E/W	GPS	NA	LINEAR	COOL/WINDY	DRY
5/9/2003	4	OPEN RANGE	1030	1100	30	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	COOL/WINDY	DRY
5/9/2003	4	OPEN RANGE	1100	1130	30	BREAK/LUNCH	LUNCH	NA	NA	NA	COOL/WINDY	DRY

Date	No. of People	Area Tested	Status Start Time	Status Stop Time	Duration, min	Operational Status	Operational Status - Comments	Track Method	Track Method=Other Explain	Pattern	Field Conditions	
5/9/2003	4	OPEN RANGE	1130	1250	80	COLLECTING DATA	RUNNING OPEN RANGE, GRID F2,F3,F4,F5 BIDIRECTIONAL E/W	GPS	NA	LINEAR	HOT/WINDY	DRY
5/9/2003	4	OPEN RANGE	1250	1300	10	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHANGE OUT PROCESSOR UNIT	GPS	NA	NA	HOT/WINDY	DRY
5/9/2003	5	OPEN RANGE	1300	1330	30	COLLECTING DATA	RUNNING OPEN RANGE, GRID F2,F3,F4,F5 BIDIRECTIONAL E/W	GPS	NA	LINEAR	HOT/WINDY	DRY
5/9/2003	5	OPEN RANGE	1330	1430	60	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	HOT/WINDY	DRY
5/9/2003	5	OPEN RANGE	1430	1445	15	COLLECTING DATA	RUNNING OPEN RANGE, GRID F2,F3,F4,F5 BIDIRECTIONAL E/W	GPS	NA	LINEAR	HOT/WINDY	DRY
5/9/2003	5	OPEN RANGE	1445	1500	15	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHANGE OUT BATTERY	GPS	NA	NA	HOT/WINDY	DRY
5/9/2003	5	OPEN RANGE	1500	1520	20	COLLECTING DATA	RUNNING OPEN RANGE, GRID F2,F3,F4,F5 BIDIRECTIONAL E/W	GPS	NA	LINEAR	HOT/WINDY	DRY
5/9/2003	5	OPEN RANGE	1520	1540	20	SET UP/MOBILIZATION	BREAKING DOWN EQUIPMENT EOD	NA	NA	NA	HOT/WINDY	DRY
5/10/2003	5	OPEN RANGE	0630	0700	30	SET UP/MOBILIZATION	SETTING UP EQUIPMENT	NA	NA	NA	COOL	DRY
5/10/2003	5	OPEN RANGE	0700	0826	86	COLLECTING DATA	RUNNING OPEN RANGE, GRID E2,E3,E4,E5 BIDIRECTIONAL E/W	GPS	NA	LINEAR	COOL	DRY
5/10/2003	5	OPEN RANGE	0826	0828	2	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	SWAPPED OUT FIELD COMPUTER	GPS	NA	LINEAR	COOL	DRY
5/10/2003	5	OPEN RANGE	0828	1015	107	COLLECTING DATA	RUNNING OPEN RANGE, GRID E2,E3,E4,E5 BIDIRECTIONAL E/W	GPS	NA	LINEAR	HOT	DRY

Date	No. of People	Area Tested	Status Start Time	Status Stop Time	Duration, min	Operational Status	Operational Status - Comments	Track Method	Track Method=Other Explain	Pattern	Field Conditions	
5/10/2003	5	OPEN RANGE	1015	1040	25	BREAK/LUNCH	LUNCH	NA	NA	NA	HOT	DRY
5/10/2003	5	OPEN RANGE	1040	1100	20	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	HOT	DRY
5/10/2003	4	OPEN RANGE	1100	1243	103	COLLECTING DATA	RUNNING OPENRANGE, GRID E2,E3,E4,E5 BIDIRECTIONAL E/W	GPS	NA	LINEAR	HOT	DRY
5/10/2003	4	OPEN RANGE	1243	1246	3	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHANGE OUT PROCESSOR UNIT	GPS	NA	NA	HOT	DRY
5/10/2003	4	OPEN RANGE	1246	1340	54	COLLECTING DATA	RUNNING OPEN RANGE, GRID E2,E3,E4,E5 BIDIRECTIONAL E/W	GPS	NA	LINEAR	HOT	DRY
5/10/2003	4	OPEN RANGE	1340	1400	20	SET UP/MOBILIZATION	BREAKING DOWN EQUIPMENT EOD	GPS	NA	NA	HOT	DRY
5/12/2003	5	OPEN RANGE	0700	0721	21	SET UP/MOBILIZATION	SETTING UP EQUIPMENT	GPS	NA	NA	HOT	DRY
5/12/2003	5	OPEN RANGE	0721	0725	4	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL BALL	GPS	NA	NA	HOT	DRY
5/12/2003	5	OPEN RANGE	0725	0825	60	COLLECTING DATA	RUNNING OPEN RANGE, GRID E2,E3,E4,E5 BIDIRECTIONAL E/W	GPS	NA	LINEAR	HOT	DRY
5/12/2003	5	OPEN RANGE	0825	0935	50	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	HOT	DRY
5/12/2003	5	OPEN RANGE	0935	1025	50	COLLECTING DATA	RUNNING OPEN RANGE, GRID A4,A5 BIDIRECTIONAL E/W	GPS	NA	LINEAR	HOT	DRY
5/12/2003	5	OPEN RANGE	1025	1030	5	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	HOT	DRY
5/12/2003	5	OPEN RANGE	1030	1325	175	DOWNTIME DUE TO EQUIPMENT FAILURE	WHEEL AXLE BROKE	NA	NA	NA	HOT	DRY
5/12/2003	5	OPEN RANGE	1325	1330	5	SET UP/MOBILIZATION	BREAKING DOWN EQUIPMENT EOD	NA	NA	NA	HOT	DRY

Date	No. of People	Area Tested	Status Start Time	Status Stop Time	Duration, min	Operational Status	Operational Status - Comments	Track Method	Track Method=Other Explain	Pattern	Field Conditions	
5/13/2003	4	OPEN RANGE	1130	1215	45	SET UP/MOBILIZATION	SETTING UP EQUIPMENT	GPS	NA	NA	HOT	DRY
5/13/2003	4	OPEN RANGE	1215	1300	45	COLLECTING DATA	RUNNING OPEN RANGE, A4,A5 BIDIRECTIONAL E/W	GPS	NA	LINEAR	HOT	DRY
5/13/2003	4	OPEN RANGE	1300	1320	20	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	HOT	DRY
5/13/2003	4	OPEN RANGE	1320	1430	70	COLLECTING DATA	RUNNING OPEN RANGE, A4,A5 BIDIRECTIONAL E/W	GPS	NA	LINEAR	HOT	DRY
5/13/2003	4	OPEN RANGE	1430	1447	17	BREAK/LUNCH	BREAK	NA	NA	NA	HOT	DRY
5/13/2003	4	OPEN RANGE	1447	1535	48	COLLECTING DATA	RUNNING OPEN RANGE, A4,A5 BIDIRECTIONAL E/W	NA	NA	LINEAR	HOT	DRY
5/13/2003	4	OPEN RANGE	1535	1545	10	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	HOT	DRY
5/13/2003	4	OPEN RANGE	1545	1600	15	SET UP/MOBILIZATION	BREAKING DOWN EQUIPMENT EOD	NA	NA	NA	HOT	DRY
5/14/2003	5	OPEN RANGE	0630	0735	65	SET UP/MOBILIZATION	SETTING UP EQUIPMENT	NA	NA	NA	WARM	HUMID
5/14/2003	5	OPEN RANGE	0735	0739	4	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL BALL	GPS	NA	LINEAR	WARM	HUMID
5/14/2003	5	OPEN RANGE	0739	0850	71	COLLECTING DATA	RUNNING OPEN RANGE, A4,A5 BIDIRECTIONAL E/W	GPS	NA	LINEAR	WARM	HUMID
5/14/2003	5	OPEN RANGE	0850	0920	30	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	WARM	HUMID
5/14/2003	5	OPEN RANGE	0920	1020	60	COLLECTING DATA	RUNNING OPEN RANGE, D4,D5 BIDIRECTIONAL E/W	GPS	NA	LINEAR	WARM	HUMID
5/14/2003	5	OPEN RANGE	1020	1035	15	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	WARM	HUMID
5/14/2003	5	OPEN RANGE	1035	1130	55	BREAK/LUNCH	LUNCH	NA	NA	NA	WARM	HUMID

Date	No. of People	Area Tested	Status Start Time	Status Stop Time	Duration, min	Operational Status	Operational Status - Comments	Track Method	Track Method=Other Explain	Pattern	Field Conditions	
5/14/2003	5	OPEN RANGE	1130	1325	115	COLLECTING DATA	RUNNING OPEN RANGE, D4,D5 BIDIRECTIONAL E/W	GPS	NA	LINEAR	WARM	HUMID
5/14/2003	5	OPEN RANGE	1325	1400	35	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	WARM	HUMID
5/14/2003	5	OPEN RANGE	1400	1430	30	BREAK/LUNCH	BREAK	NA	NA	NA	WARM	HUMID
5/14/2003	5	OPEN RANGE	1430	1530	120	COLLECTING DATA	RUNNING OPEN RANGE, D4,D5 BIDIRECTIONAL E/W	GPS	NA	LINEAR	WARM	HUMID
5/14/2003	5	OPEN RANGE	1530	1600	30	SET UP/MOBILIZATION	BREAKING DOWN EQUIPMENT EOD	NA	NA	NA	WARM	HUMID
5/15/2003	5	OPEN RANGE	0645	0710	25	SET UP/MOBILIZATION	SETTING UP EQUIPMENT	NA	NA	NA	COOL	DRY
5/15/2003	5	OPEN RANGE	0710	0735	25	COLLECTING DATA	RUNNING OPEN RANGE, B2,B3 BIDIRECTIONAL E/W	GPS	NA	LINEAR	COOL	DRY
5/15/2003	5	OPEN RANGE	0735	0742	7	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	COOL	DRY
5/15/2003	5	OPEN RANGE	0742	0750	8	COLLECTING DATA	RUNNING OPEN RANGE, B2,B3 BIDIRECTIONAL E/W	GPS	NA	LINEAR	COOL	DRY
5/15/2003	5	OPEN RANGE	0750	0755	5	DOWNTIME DUE TO EQUIPMENT FAILURE	GPS DOWN	GPS	NA	NA	COOL	DRY
5/15/2003	5	OPEN RANGE	0755	0925	90	COLLECTING DATA	RUNNING OPEN RANGE, B2,B3 BIDIRECTIONAL E/W	GPS	NA	LINEAR	COOL	DRY
5/15/2003	5	OPEN RANGE	0925	0945	20	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	COOL	DRY
5/15/2003	5	OPEN RANGE	0945	1140	115	COLLECTING DATA	RUNNING OPEN RANGE, B2,B3 BIDIRECTIONAL E/W	GPS	NA	LINEAR	HOT	DRY
5/15/2003	5	OPEN RANGE	1140	1150	10	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	HOT	DRY
5/15/2003	5	OPEN RANGE	1150	1250	60	BREAK/LUNCH	CHOW	NA	NA	NA	HOT	DRY

Date	No. of People	Area Tested	Status Start Time	Status Stop Time	Duration, min	Operational Status	Operational Status - Comments	Track Method	Track Method=Other Explain	Pattern	Field Conditions	
5/15/2003	5	OPEN RANGE	1250	1255	5	SET UP/MOBILIZATION	SET UP ON C4,C5	NA	NA	NA	HOT	DRY
5/15/2003	5	OPEN RANGE	1255	1320	25	COLLECTING DATA	RUNNING OPEN RANGE, C4,C5 BIDIRECTIONAL E/W	GPS	NA	LINEAR	HOT	DRY
5/15/2003	5	OPEN RANGE	1320	1325	5	DOWNTIME DUE TO EQUIPMENT FAILURE	COMMUNICATION ERROR INFIELD COMPUTOR	GPS	NA	NA	HOT	DRY
5/15/2003	5	OPEN RANGE	1325	1330	5	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHANGE OUT FIELD COMPUTORS	GPS	NA	NA	HOT	DRY
5/15/2003	5	OPEN RANGE	1330	1530	120	COLLECTING DATA	RUNNING OPEN RANGE, C4,C5 BIDIRECTIONAL E/W	GPS	NA	LINEAR	HOT	DRY
5/15/2003	5	OPEN RANGE	1530	1600	30	SET UP/MOBILIZATION	BREAKING DOWN EQUIPMENT EOD	NA	NA	NA	HOT	DRY
5/16/2003	4	OPEN RANGE	0640	0655	15	SET UP/MOBILIZATION	SETTING UP EQUIPMENT	NA	NA	NA	COOL	DRY
5/16/2003	4	OPEN RANGE	0655	0700	5	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL BALL	GPS	NA	NA	COOL	DRY
5/16/2003	4	OPEN RANGE	0700	0825	85	COLLECTING DATA	RUNNING OPEN RANGE, C4,C5 BIDIRECTIONAL E/W	GPS	NA	LINEAR	COOL	DRY
5/16/2003	4	OPEN RANGE	0825	0850	25	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	COOL	DRY
5/16/2003	4	OPEN RANGE	0850	0900	10	SET UP/MOBILIZATION	SET UP ON D3	NA	NA	NA	COOL	DRY
5/16/2003	4	OPEN RANGE	0900	1110	130	COLLECTING DATA	RUNNING OPEN RANGE, D3 BIDIRECTIONAL E/W	GPS	NA	LINEAR	HOT	DRY
5/16/2003	4	OPEN RANGE	1110	1125	15	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	HOT	DRY
5/16/2003	4	OPEN RANGE	1125	1235	70	BREAK/LUNCH	CHOW	NA	NA	NA	HOT	DRY
5/16/2003	4	OPEN RANGE	1235	1330	55	COLLECTING DATA	RUNNING OPEN RANGE, D3 BIDIRECTIONAL E/W	GPS	NA	LINEAR	HOT	DRY
5/16/2003	4	OPEN RANGE	1330	1410	40	BREAK/LUNCH	BREAK	NA	NA	NA	HOT	DRY

Date	No. of People	Area Tested	Status Start Time	Status Stop Time	Duration, min	Operational Status	Operational Status - Comments	Track Method	Track Method=Other Explain	Pattern	Field Conditions	
5/16/2003	4	OPEN RANGE	1410	1515	65	COLLECTING DATA	RUNNING OPEN RANGE, D3 BIDIRECTIONAL E/W	GPS	NA	LINEAR	HOT	DRY
5/16/2003	4	OPEN RANGE	1515	1530	15	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	HOT	DRY
5/16/2003	4	OPEN RANGE	1530	1600	30	SET UP/MOBILIZATION	BREAKING DOWN EQUIPMENT EOD	NA	NA	NA	HOT	DRY
5/17/2003	4	OPEN RANGE	0630	0715	45	SET UP/MOBILIZATION	SETTING UP EQUIPMENT	NA	NA	NA	HOT	DRY
5/17/2003	4	OPEN RANGE	0715	0720	5	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL BALL	GPS	NA	NA	HOT	DRY
5/17/2003	4	OPEN RANGE	0720	0825	65	COLLECTING DATA	RUNNING OPEN RANGE, D2 BIDIRECTIONAL E/W	GPS	NA	LINEAR	HOT	DRY
5/17/2003	4	OPEN RANGE	0825	0921	56	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	HOT	DRY
5/17/2003	4	OPEN RANGE	0921	1040	79	COLLECTING DATA	RUNNING OPEN RANGE, B5 BIDIRECTIONAL E/W	GPS	NA	LINEAR	HOT	DRY
5/17/2003	4	OPEN RANGE	1040	1045	5	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	HOT	DRY
5/17/2003	4	OPEN RANGE	1045	1120	35	BREAK/LUNCH	CHOW	NA	NA	NA	HOT	DRY
5/17/2003	3	OPEN RANGE	1120	1230	70	COLLECTING DATA	RUNNING OPEN RANGE, B5 BIDIRECTIONAL E/W	GPS	NA	LINEAR	HOT	DRY
5/17/2003	3	OPEN RANGE	1230	1245	15	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	HOT	DRY
5/17/2003	3	OPEN RANGE	1245	1335	50	BREAK/LUNCH	BREAK	NA	NA	NA	HOT	DRY
5/17/2003	3	OPEN RANGE	1335	1400	25	COLLECTING DATA	CONDUCTED EQUIPMENT INTERFERENCE TEST	GPS	NA	NA	HOT	DRY
5/17/2003	3	OPEN RANGE	1400	1430	30	SET UP/MOBILIZATION	BREAKING DOWN EQUIPMENT EOD	NA	NA	NA	HOT	DRY

Date	No. of People	Area Tested	Status Start Time	Status Stop Time	Duration, min	Operational Status	Operational Status - Comments	Track Method	Track Method=Other Explain	Pattern	Field Conditions	
5/19/2003	4	OPEN RANGE	0600	0615	15	SET UP/MOBILIZATION	SETTING UP EQUIPMENT	NA	NA	NA	HOT	DRY
5/19/2003	4	OPEN RANGE	0615	0620	5	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL BALL	GPS	NA	NA	HOT	DRY
5/19/2003	4	OPEN RANGE	0620	0743	83	COLLECTING DATA	RUNNING OPEN RANGE, B4 BIDIRECTIONAL E/W	GPS	NA	LINEAR	HOT	DRY
5/19/2003	4	OPEN RANGE	0743	0815	32	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	NA	NA	NA	HOT	DRY
5/19/2003	4	OPEN RANGE	0815	0930	75	COLLECTING DATA	RUNNING OPEN RANGE, B4 BIDIRECTIONAL E/W	GPS	NA	LINEAR	HOT	DRY
5/19/2003	4	OPEN RANGE	0930	0945	15	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	NA	NA	NA	HOT	DRY
5/19/2003	4	OPEN RANGE	0945	0950	5	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHANGE OUT BATTERY	NA	NA	NA	HOT	DRY
5/19/2003	4	OPEN RANGE	0950	0955	5	BREAK/LUNCH	BREAK	NA	NA	NA	HOT	DRY
5/19/2003	4	OPEN RANGE	0955	1005	10	COLLECTING DATA	RUNNING OPEN RANGE, B4 BIDIRECTIONAL E/W	GPS	NA	LINEAR	HOT	DRY
5/19/2003	4	OPEN RANGE	1005	1010	5	SET UP/MOBILIZATION	SET UP ON GRID C2,C3	NA	NA	NA	HOT	DRY
5/19/2003	4	OPEN RANGE	1010	1024	14	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	HOT	DRY
5/19/2003	4	OPEN RANGE	1024	1130	66	COLLECTING DATA	RUNNING OPEN RANGE, C2,C3 BIDIRECTIONAL E/W	GPS	NA	LINEAR	HOT	DRY
5/19/2003	4	OPEN RANGE	1130	1145	15	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	HOT	DRY
5/19/2003	4	OPEN RANGE	1145	1310	85	BREAK/LUNCH	CHOW/BREAK	NA	NA	NA	HOT	DRY
5/19/2003	4	OPEN RANGE	1310	1410	60	COLLECTING DATA	RUNNING OPEN RANGE, C2,C3 BIDIRECTIONAL E/W	GPS	NA	LINEAR	HOT	DRY

Date	No. of People	Area Tested	Status Start Time	Status Stop Time	Duration, min	Operational Status	Operational Status - Comments	Track Method	Track Method=Other Explain	Pattern	Field Conditions	
5/19/2003	4	OPEN RANGE	1410	1420	10	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	HOT	DRY
5/19/2003	4	OPEN RANGE	1420	1430	10	SET UP/MOBILIZATION	BREAKING DOWN EQUIPMENT EOD	NA	NA	NA	HOT	DRY
5/20/2003	4	OPEN RANGE	0530	0545	15	SET UP/MOBILIZATION	SETTING UP EQUIPMENT	NA	NA	NA	HOT	DRY
5/20/2003	4	OPEN RANGE	0545	0549	4	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL BALL	GPS	NA	NA	HOT	DRY
5/20/2003	4	OPEN RANGE	0549	0718	89	COLLECTING DATA	RUNNING OPEN RANGE, C2,C3 BIDIRECTIONAL E/W	GPS	NA	LINEAR	HOT	DRY
5/20/2003	4	OPEN RANGE	0718	0738	20	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	HOT	DRY
5/20/2003	4	OPEN RANGE	0738	0805	27	BREAK/LUNCH	BREAK	NA	NA	NA	HOT	DRY
5/20/2003	4	OPEN RANGE	0805	0847	42	COLLECTING DATA	RUNNING OPEN RANGE, C2,C3 BIDIRECTIONAL E/W	GPS	NA	LINEAR	HOT	DRY
5/20/2003	4	OPEN RANGE	0847	0900	13	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	HOT	DRY
5/20/2003	4	OPEN RANGE	0900	0937	37	COLLECTING DATA	RUNNING OPEN RANGE, C2,C3 BIDIRECTIONAL E/W	GPS	NA	LINEAR	HOT	DRY
5/20/2003	4	OPEN RANGE	0937	0952	15	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	HOT	DRY
5/20/2003	4	OPEN RANGE	0952	1012	20	BREAK/LUNCH	BREAK	NA	NA	NA	HOT	DRY
5/20/2003	4	YUMA EXTREME	1012	1024	12	SET UP/MOBILIZATION	SET UP IN YUMA EXTREME	NA	NA	NA	HOT	DRY
5/20/2003	4	YUMA EXTREME	1024	1111	47	COLLECTING DATA	RUNNING YUMA EXTREME BIDIRECTIONAL NORTH/SOUTH	GPS	NA	LINEAR	HOT	DRY

Date	No. of People	Area Tested	Status Start Time	Status Stop Time	Duration, min	Operational Status	Operational Status - Comments	Track Method	Track Method=Other Explain	Pattern	Field Conditions	
5/20/2003	4	YUMA EXTREME	1111	1130	19	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	HOT	DRY
5/20/2003	4	YUMA EXTREME	1130	1230	60	BREAK/LUNCH	LUNCH	NA	NA	NA	HOT	DRY
5/20/2003	4	YUMA EXTREME	1230	1245	15	SET UP/MOBILIZATION	SETUP	NA	NA	NA	HOT	DRY
5/20/2003	4	YUMA EXTREME	1245	1248	3	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL BALL	GPS	NA	NA	HOT	DRY
5/20/2003	4	YUMA EXTREME	1248	1255	7	COLLECTING DATA	RUNNING YUMA EXTREME BIDIRECTIONAL NORTH/SOUTH	GPS	NA	LINEAR	HOT	DRY
5/20/2003	4	YUMA EXTREME	1255	1300	5	DOWNTIME DUE TO EQUIPMENT FAILURE	FIELD COMPUTER OVERHEAT/FAILED	NA	NA	NA	HOT	DRY
5/20/2003	4	YUMA EXTREME	1300	1310	10	SET UP/MOBILIZATION	BREAKING DOWN EQUIPMENT EOD	NA	NA	NA	HOT	DRY
5/21/2003	3	YUMA EXTREME	0530	0550	20	SET UP/MOBILIZATION	SETTING UP EQUIPMENT	NA	NA	NA	HOT	DRY
5/21/2003	3	YUMA EXTREME	0550	0600	10	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL BALL	GPS	NA	NA	HOT	DRY
5/21/2003	3	YUMA EXTREME	0600	0605	5	COLLECTING DATA	RUNNING YUMA EXTREME BIDIRECTIONAL NORTH/SOUTH	GPS	NA	LINEAR	HOT	DRY
5/21/2003	3	YUMA EXTREME	0605	0614	9	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	HOT	DRY
5/21/2003	3	YUMA EXTREME	0614	0750	96	COLLECTING DATA	RUNNING YUMA EXTREME BIDIRECTIONAL NORTH/SOUTH	GPS	NA	LINEAR	HOT	DRY
5/21/2003	3	YUMA EXTREME	0750	0810	20	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	HOT	DRY

Date	No. of People	Area Tested	Status Start Time	Status Stop Time	Duration, min	Operational Status	Operational Status - Comments	Track Method	Track Method=Other Explain	Pattern	Field Conditions	
5/21/2003	3	YUMA EXTREME	0810	0820	10	BREAK/LUNCH	BREAK	NA	NA	NA	HOT	DRY
5/21/2003	3	YUMA EXTREME	0820	0850	30	COLLECTING DATA	RUNNING YUMA EXTREME BIDIRECTIONAL NORTH/SOUTH	GPS	NA	LINEAR	HOT	DRY
5/21/2003	3	YUMA EXTREME	0850	0920	30	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	HOT	DRY
5/21/2003	3	MOGUL AREA	0920	0930	10	SET UP/MOBILIZATION	SET UP IN MOGUL AREA	NA	NA	NA	HOT	DRY
5/21/2003	3	MOGUL AREA	0930	1040	70	COLLECTING DATA	RUNNING MOGUL AREA, BIDIRECTIONAL NORTH/SOUTH	GPS	NA	LINEAR	HOT	DRY
5/21/2003	3	MOGUL AREA	1040	1100	20	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	HOT	DRY
5/21/2003	3	MOGUL AREA	1100	1158	58	COLLECTING DATA	RUNNING MOGUL AREA, BIDIRECTIONAL NORTH/SOUTH	GPS	NA	LINEAR	HOT	DRY
5/21/2003	3	MOGUL AREA	1158	1210	12	DOWNTIME DUE TO EQUIPMENT FAILURE	GPS MOUNT BROKE, OPERATOR ERROR	NA	NA	NA	HOT	DRY
5/21/2003	3	MOGUL AREA	1210	1230	20	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	HOT	DRY
5/21/2003	3	MOGUL AREA	1230	1237	7	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL BALL	GPS	NA	NA	HOT	DRY
5/21/2003	3	MOGUL AREA	1237	1322	45	COLLECTING DATA	RUNNING MOGUL AREA, BIDIRECTIONAL NORTH/SOUTH	GPS	NA	LINEAR	HOT	DRY
5/21/2003	3	MOGUL AREA	1322	1335	13	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	HOT	DRY

Note: Activities pertinent to this specific demonstration are indicated in highlighted text.

Date	No. of People	Area Tested	Status Start Time	Status Stop Time	Duration, min	Operational Status	Operational Status - Comments	Track Method	Track Method=Other Explain	Pattern	Field Conditions	
5/21/2003	3	MOGUL AREA	1335	1445	70	COLLECTING DATA	RUNNING MOGUL AREA, BIDIRECTIONAL NORTH/SOUTH	GPS	NA	LINEAR	HOT	DRY
5/21/2003	3	MOGUL AREA	1445	1500	15	SET UP/MOBILIZATION	BREAKING DOWN EQUIPMENT EOD	NA	NA	NA	HOT	DRY
5/22/2003	3	YUMA EXTREME	0530	0637	67	SET UP/MOBILIZATION	SETTING UP EQUIPMENT	NA	NA	NA	HOT	DRY
5/22/2003	3	YUMA EXTREME	0637	0642	5	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL BALL	GPS	NA	NA	HOT	DRY
5/22/2003	3	YUMA EXTREME	0642	0745	63	COLLECTING DATA	RUNNING YUMA EXTREME BIDIRECTIONAL NORTH/SOUTH	GPS	NA	LINEAR	HOT	DRY
5/22/2003	3	YUMA EXTREME	0745	0800	15	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	HOT	DRY
5/22/2003	3	YUMA EXTREME	0800	0930	90	COLLECTING DATA	RUNNING YUMA EXTREME BIDIRECTIONAL NORTH/SOUTH	GPS	NA	LINEAR	HOT	DRY
5/22/2003	3	YUMA EXTREME	0930	0935	5	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	SWAP OUT BATTERIES	NA	NA	NA	HOT	DRY
5/22/2003	3	YUMA EXTREME	0935	0950	15	COLLECTING DATA	RUNNING YUMA EXTREME BIDIRECTIONAL NORTH/SOUTH	GPS	NA	LINEAR	HOT	DRY
5/22/2003	3	YUMA EXTREME	0950	1005	15	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	HOT	DRY
5/22/2003	3	YUMA EXTREME	1005	1020	15	BREAK/LUNCH	BREAK	NA	NA	NA	HOT	DRY
5/22/2003	3	CALIBRATION PIT	1020	1028	8	SET UP/MOBILIZATION	SET UP OVER CALIBRATION PIT	NA	NA	NA	HOT	DRY
5/22/2003	3	CALIBRATION PIT	1028	1030	2	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL BALL	GPS	NA	NA	HOT	DRY

Note: Activities pertinent to this specific demonstration are indicated in highlighted text.

Date	No. of People	Area Tested	Status Start Time	Status Stop Time	Duration, min	Operational Status	Operational Status - Comments	Track Method	Track Method=Other Explain	Pattern	Field Conditions	
5/22/2003	3	CALIBRATION PIT	1030	1052	22	COLLECTING DATA	RUNNING SIGNITURE DATA ON 40MM MARK II	GPS	NA	LINEAR	HOT	DRY
5/22/2003	3	CALIBRATION PIT	1052	1105	13	COLLECTING DATA	RUNNING SIGNITURE DATA ON 57MM	GPS	NA	LINEAR	HOT	DRY
5/22/2003	3	CALIBRATION PIT	1105	1128	23	COLLECTING DATA	RUNNING SIGNITURE DATA ON 60MM	GPS	NA	LINEAR	HOT	DRY
5/22/2003	3	CALIBRATION PIT	1128	1138	10	BREAK/LUNCH	BREAK	NA	NA	NA	HOT	DRY
5/22/2003	3	CALIBRATION PIT	1138	1149	11	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	HOT	DRY
5/22/2003	3	CALIBRATION PIT	1149	1240	51	BREAK/LUNCH	LUNCH	NA	NA	NA	HOT	DRY
5/22/2003	3	CALIBRATION PIT	1240	1243	3	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL BALL	GPS	NA	NA	HOT	DRY
5/22/2003	3	CALIBRATION PIT	1243	1255	12	COLLECTING DATA	RUNNING SIGNITURE DATA ON ROCKEYE MK118	GPS	NA	LINEAR	HOT	DRY
5/22/2003	3	CALIBRATION PIT	1255	1320	25	COLLECTING DATA	RUNNING SIGNITURE DATA ON 2.75 ROCKET	GPS	NA	LINEAR	HOT	DRY
5/22/2003	3	CALIBRATION PIT	1320	1347	27	COLLECTING DATA	RUNNING SIGNITURE DATA ON 105 STANDARD	GPS	NA	LINEAR	HOT	DRY
5/22/2003	3	CALIBRATION PIT	1347	1412	25	COLLECTING DATA	RUNNING SIGNITURE DATA ON 155MM	GPS	NA	LINEAR	HOT	DRY
5/22/2003	3	CALIBRATION PIT	1412	1414	2	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL BALL	GPS	NA	NA	HOT	DRY
5/22/2003	3	CALIBRATION PIT	1414	1500	46	DEMOBILIZATION	END OF TEST	NA	NA	NA	HOT	DRY

Note: Activities pertinent to this specific demonstration are indicated in highlighted text.

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APPENDIX E. REFERENCES

1. Standardized UXO Technology Demonstration Site Handbook, DTC Project No. 8-CO-160-000-473, Report No. ATC-8349, March 2002.

2. Aberdeen Proving Ground Soil Survey Report, October 1998.

3. Data Summary, UXO Standardized Test Site: APG Soils Description, May 2002.

4. Yuma Proving Ground Soil Survey Report, May 2003.

5. Practical Nonparametric Statistics, W.J. Conover, John Wiley & Sons, 1980, ages 144 through 151.

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APPENDIX F. ABBREVIATIONS

AEC	=	U.S. Army Environmental Center
APG	=	Aberdeen Proving Ground
ATC	=	U.S. Army Aberdeen Test Center
HEAT	=	high-explosive, antitank
EMI	=	electromagnetic interference
EMIS	=	Electromagnetic Induction Spectroscopy
ERDC	=	U.S. Army Corps of Engineers Engineering Research and Development Center
ESTCP	=	Environmental Security Technology Certification Program
EQT	=	Army Environmental Quality Technology Program
GPS	=	Global Positioning System
JPG	=	Jefferson Proving Ground
PDA	=	personal digital assistant
POC	=	point of contact
PVC	=	polyvinyl chloride
QA	=	quality assurance
QC	=	quality control
ROC	=	receiver-operating characteristic
RTK	=	real time kinematic
SERDP	=	Strategic Environmental Research and Development Program
UXO	=	unexploded ordnance
YPG	=	U.S. Army Yuma Proving Ground

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