



STANDARDIZED

UXO TECHNOLOGY DEMONSTRATION SITE

DESERT EXTREME SCORING RECORD NO. 509

SITE LOCATION: U.S. ARMY YUMA PROVING GROUND

DEMONSTRATOR:
U.S. ARMY CORPS OF ENGINEERS
ENGINEERING RESEARCH AND
DEVELOPMENT CENTER
3909 HALLS FERRY ROAD
VICKSBURG, MS 39180-6199

TECHNOLOGY TYPE/PLATFORM: GEM-3/PUSHCART

PREPARED BY:
U.S. ARMY ABERDEEN TEST CENTER
ABERDEEN PROVING GROUND, MD 21005-5059

JULY 2005









Prepared for:
U.S. ARMY ENVIRONMENTAL CENTER
ABERDEEN PROVING GROUND, MD 21010-5401

U.S. ARMY DEVELOPMENTAL TEST COMMAND ABERDEEN PROVING GROUND, MD 21005-5055

DISTRIBUTION UNLIMITED, JULY 2005.

DISPOSITION INSTRUCTIONS

Destroy this document when no longer needed. Do not return to the originator.

The use of trade names in this document does not constitute an official endorsement or approval of the use of such commercial hardware or software. This document may not be cited for purposes of advertisement.

REPORT DOCUMENTATION PAGE

Form Approved OMB No. 0704-0188

maintaining the data ne suggestions for reduc Suite 1204, Arlington, of information If It doe PLEASE DO NO	eded, and completing a sing the burden, to De VA 22202-4302. Res not display a current DT RETURN YOU	nd reviewing the coll partment of Defense, pondents should be a yvalid OMB control of JR FORM TO T	ection of Information. Send comm Washington Headquarters Service ware that notwithstanding any off number. HE ABOVE ADDRESS.	ents regarding this es, Directorate for In her provision of law	burden estim nformation Op no person s	vate or any other aspect of this collection of information, including serations and Reports (0704-0188), 1215 Jefferson Davis Hightway, hall be subject to any penalty for failing to comply with a collection		
	TE (DD-MM-YY	(Y) 2. REPO	ORT TYPE Final			3. DATES COVERED (From - To) 3 through 5 November 2003		
4. TITLE AND SUBTITLE STANDARDIZED UXO TECHNOLOGY DEMONSTRATION SITE DESERT EXTREME SCORING RECORD NO. 509 (U.S. ARMY CORPS OF ENGINEERS ENGINEERING RESEARCH AND DEVELOPMENT CENTER (ERDC))					5a. CONTRACT NUMBER 5b. GRANT NUMBER 5c. PROGRAM ELEMENT NUMBER			
6. AUTHOR(S) Overbay, Larry; Robitaille, George The Standardized UXO Technology Demonstration Site Scoring Committee				ommittee	5d. PROJECT NUMBER 8-CO-160-UXO-021 5e. TASK NUMBER 5f. WORK UNIT NUMBER			
Commander U.S. Army Ab ATTN: CSTE	NG ORGANIZATI erdeen Test Ce E-DTC-AT-SL- ving Ground, M	nter E	ND ADDRESS(ES)			8. PERFORMING ORGANIZATION REPORT NUMBER ATC-8996		
Commander U.S. Army Env ATTN: SFIM	vironmental Ce	nter	E(S) AND ADDRESS(ES	·)		10. SPONSOR/MONITOR'S ACRONYM(S) 11. SPONSOR/MONITOR'S REPORT NUMBER(S) Same as item 8		
12. DISTRIBUT Distribution u	_	TY STATEMEN						
to detect and of Desert Extrem Scoring Comm Technology C	ecord document liscriminate include. The scoring nittee. Organize this control of the control of	rt unexploded record was co- ations on the o gram, the Strat	ordinance (UXO) utilized by Larry Overcommittee include the	ing the YPG rbay and the S U.S. Army Co esearch and D	Standard Standard rps of En evelopm	Research and Development Center (ERDC) ized UXO Technology Demonstration Site ized UXO Technology Demonstration Site gineers, the Environmental Security ent Program, the Institute for Defense r.		
15. SUBJECT T ERDC, UXO GEM-3/Pusho	Standardized S	ite, YPG, Stan	dardized UXO Techno	logy Demons	stration S	ite Program, Desert Extreme,		
16. SECURITY a. REPORT	CLASSIFICATIO		17. LIMITATION OF ABSTRACT	OF	ER 19a. NAME OF RESPONSIBLE PERSON			
a. REPORT b. ABSTRACT c. THIS PAGE Unclassified Unclassified Unclassified ULL ABSTRACT OF PAGES 19b. TELEPHONE NUMBER (Include are)					EPHONE NUMBER (Include area code)			

ACKNOWLEDGEMENTS

Authors:

Larry Overbay Jr.

Matthew Boutin

Military Environmental Technology Demonstration Center (METDC)

U.S. Army Aberdeen Test Center (ATC)

U.S. Army Aberdeen Proving Ground (APG)

Robert Archiable EC 111, Limited Liability Company (LLC) U.S. Army Yuma Proving Ground (YPG)

Christina McClung
Aberdeen Test and Support Services (ATSS)
Sverdrup Technology, Inc.
U.S. Army Aberdeen Proving Ground (APG)

Contributor:

George Robitaille
U.S. Army Environmental Center (AEC)
U.S. Army Aberdeen Proving Ground (APG)

TABLE OF CONTENTS

		PAGE
	ACKNOWLEDGMENTS	i
	SECTION 1. GENERAL INFORMATION	
1.1	BACKGROUND	1
1.2	SCORING OBJECTIVES	1
	1.2.1 Scoring Methodology	1
	1.2.2 Scoring Factors	3
1.3	STANDARD AND NONSTANDARD INERT ORDNANCE TARGETS	4
	SECTION 2. DEMONSTRATION	
2.1	DEMONSTRATOR INFORMATION	5
	2.1.1 Demonstrator Point of Contact (POC) and Address	5
	2.1.2 System Description	5
	2.1.3 Data Processing Description	6
	2.1.4 Data Submission Format	6
	2.1.5 Demonstrator Quality Assurance (QA) and Quality Control (QC)	7
	2.1.6 Additional Records	7
2.2	YPG SITE INFORMATION	8
	2.2.1 Location	8
	2.2.2 Soil Type	9
	2.2.5 Test rueus	
	SECTION 3. FIELD DATA	
3.1	DATE OF FIELD ACTIVITIES	11
3.2	AREAS TESTED/NUMBER OF HOURS	11
3.3	TEST CONDITIONS	11
	3.3.1 Weather Conditions	11
	3.3.2 Field Conditions	11
-	3.3.3 Soil Moisture	11
3.4	FIELD ACTIVITIES	12
	3.4.1 Setup/Mobilization	12
	3.4.2 Calibration	12 12
	3.4.4 Data Collection	12
	3.4.5 Demobilization	12
3.5	PROCESSING TIME	13
3.6	DEMONSTRATOR'S FIELD PERSONNEL	13
3.7	DEMONSTRATOR'S FIELD SURVEYING METHOD	13
3.8	SUMMARY OF DAILY LOGS	13

SECTION 4. TECHNICAL PERFORMANCE RESULTS

		PAGE
4.1	ROC CURVES USING ALL ORDNANCE CATEGORIES	15
4.2	ROC CURVES USING ORDNANCE LARGER THAN 20 MM	16
4.3	PERFORMANCE SUMMARIES	18
4.4	EFFICIENCY, REJECTION RATES, AND TYPE CLASSIFICATION	20
4.5	LOCATION ACCURACY	20
	SECTION 5. ON-SITE LABOR COSTS	
<u>S1</u>	ECTION 6. COMPARISON OF RESULTS TO OPEN FIELD DEMONSTRA	<u> TION</u>
6.1	SUMMARY OF RESULTS FROM OPEN FIELD DEMONSTRATION	23
6.2	COMPARISON OF ROC CURVES USING ALL ORDNANCE	
	CATEGORIES	23
6.3	COMPARISON OF ROC CURVES USING ORDNANCE LARGER THAN	
	20 MM	25
6.4	STATISTICAL COMPARISONS	26
	SECTION 7. APPENDIXES	
A	TERMS AND DEFINITIONS	A-1
В	DAILY WEATHER LOGS	B-1
C	SOIL MOISTURE	C-1
D	DAILY ACTIVITY LOGS	D-1
E	REFERENCES	E-1
F	ABBREVIATIONS	F-1
G	DISTRIBUTION LIST	G-1

SECTION 1. GENERAL INFORMATION

1.1 BACKGROUND

Technologies under development for the detection and discrimination of unexploded ordnance (UXO) require testing so that their performance can be characterized. To that end, Standardized Test Sites have been developed at Aberdeen Proving Ground (APG), Maryland and U.S. Army Yuma Proving Ground (YPG), Arizona. These test sites provide a diversity of geology, climate, terrain, and weather as well as diversity in ordnance and clutter. Testing at these sites is independently administered and analyzed by the government for the purposes of characterizing technologies, tracking performance with system development, comparing performance of different systems, and comparing performance in different environments.

The Standardized UXO Technology Demonstration Site Program is a multi-agency program spearheaded by the U.S. Army Environmental Center (AEC). The U.S. Army Aberdeen Test Center (ATC) and the U.S. Army Corps of Engineers Engineering Research and Development Center (ERDC) provide programmatic support. The program is being funded and supported by the Environmental Security Technology Certification Program (ESTCP), the Strategic Environmental Research and Development Program (SERDP) and the Army Environmental Quality Technology Program (EQT).

1.2 SCORING OBJECTIVES

The objective in the Standardized UXO Technology Demonstration Site Program is to evaluate the detection and discrimination capabilities of a given technology under various field and soil conditions. Inert munitions and clutter items are positioned in various orientations and depths in the ground.

The evaluation objectives are as follows:

- a. To determine detection and discrimination effectiveness under realistic scenarios that vary targets, geology, clutter, topography, and vegetation.
 - b. To determine cost, time, and manpower requirements to operate the technology.
- c. To determine demonstrator's ability to analyze survey data in a timely manner and provide prioritized "Target Lists" with associated confidence levels.
- d. To provide independent site management to enable the collection of high quality, ground-truth, geo-referenced data for post-demonstration analysis.

1.2.1 Scoring Methodology

a. The scoring of the demonstrator's performance is conducted in two stages. These two stages are termed the RESPONSE STAGE and DISCRIMINATION STAGE. For both stages, the probability of detection (P_d) and the false alarms are reported as receiver-operating

characteristic (ROC) curves. False alarms are divided into those anomalies that correspond to emplaced clutter items, measuring the probability of false positive (P_{fp}), and those that do not correspond to any known item, termed background alarms.

- b. The RESPONSE STAGE scoring evaluates the ability of the system to detect emplaced targets without regard to ability to discriminate ordnance from other anomalies. For the blind grid RESPONSE STAGE, the demonstrator provides the scoring committee with a target response from each and every grid square along with a noise level below which target responses are deemed insufficient to warrant further investigation. This list is generated with minimal processing and, since a value is provided for every grid square, will include signals both above and below the system noise level.
- c. The DISCRIMINATION STAGE evaluates the demonstrator's ability to correctly identify ordnance as such and to reject clutter. For the blind grid DISCRIMINATION STAGE, the demonstrator provides the scoring committee with the output of the algorithms applied in the discrimination-stage processing for each grid square. The values in this list are prioritized based on the demonstrator's determination that a grid square is likely to contain ordnance. Thus, higher output values are indicative of higher confidence that an ordnance item is present at the specified location. For digital signal processing, priority ranking is based on algorithm output. For other discrimination approaches, priority ranking is based on human (subjective) judgment. The demonstrator also specifies the threshold in the prioritized ranking that provides optimum performance, (i.e. that is expected to retain all detected ordnance and rejects the maximum amount of clutter).
- d. The demonstrator is also scored on EFFICIENCY and REJECTION RATIO, which measures the effectiveness of the discrimination stage processing. The goal of discrimination is to retain the greatest number of ordnance detections from the anomaly list, while rejecting the maximum number of anomalies arising from non-ordnance items. EFFICIENCY measures the fraction of detected ordnance retained after discrimination, while the REJECTION RATIO measures the fraction of false alarms rejected. Both measures are defined relative to performance at the demonstrator-supplied level below which all responses are considered noise, i.e., the maximum ordnance detectable by the sensor and its accompanying false positive rate or background alarm rate.
- e. Based on configuration of the ground truth at the standardized sites and the defined scoring methodology, there exists the possibility of having anomalies within overlapping halos and/or multiple anomalies within halos. In these cases, the following scoring logic is implemented:
- (1) In situations where multiple anomalies exist within a single R_{halo} , the anomaly with the strongest response or highest ranking will be assigned to that particular ground truth item.
- (2) For overlapping R_{halo} situations, ordnance has precedence over clutter. The anomaly with the strongest response or highest ranking that is closest to the center of a particular ground truth item gets assigned to that item. Remaining anomalies are retained until all matching is complete.

- (3) Anomalies located within any R_{halo} that do not get associated with a particular ground truth item are thrown out and are not considered in the analysis.
- f. All scoring factors are generated utilizing the Standardized UXO Probability and Plot Program, version 3.1.1.

1.2.2 Scoring Factors

Factors to be measured and evaluated as part of this demonstration include:

- a. Response Stage ROC curves:
- (1) Probability of Detection (P_d res).
- (2) Probability of False Positive (P_{fp} res).
- (3) Background Alarm Rate (BAR^{res}) or Probability of Background Alarm (P_{BA}^{res}).
- b. Discrimination Stage ROC curves:
- (1) Probability of Detection (P_d^{disc}).
- (2) Probability of False Positive (Pfp disc).
- (3) Background Alarm Rate (BAR^{disc}) or Probability of Background Alarm (P_{BA}^{disc}).
- c. Metrics:
- (1) Efficiency (E).
- (2) False Positive Rejection Rate (Rfp).
- (3) Background Alarm Rejection Rate (RBA).
- d. Other:
- (1) Probability of Detection by Size and Depth.
- (2) Classification by type (i.e., 20-, 40-, 105-mm, etc.).
- (3) Location accuracy.
- (4) Equipment setup, calibration time and corresponding man-hour requirements.
- (5) Survey time and corresponding man-hour requirements.

- (6) Reacquisition/resurvey time and man-hour requirements (if any).
- (7) Downtime due to system malfunctions and maintenance requirements.

1.3 STANDARD AND NONSTANDARD INERT ORDNANCE TARGETS

The standard and nonstandard ordnance items emplaced in the test areas are listed in Table 1. Standardized targets are members of a set of specific ordnance items that have identical properties to all other items in the set (caliber, configuration, size, weight, aspect ratio, material, filler, magnetic remanence, and nomenclature). Nonstandard targets are inert ordnance items having properties that differ from those in the set of standardized targets.

TABLE 1. INERT ORDNANCE TARGETS

Standard Type	Nonstandard (NS)		
20-mm Projectile M55	20-mm Projectile M55		
	20-mm Projectile M97		
40-mm Grenades M385	40-mm Grenades M385		
40-mm Projectile MKII Bodies	40-mm Projectile M813		
BDU-28 Submunition			
BLU-26 Submunition			
M42 Submunition			
57-mm Projectile APC M86			
60-mm Mortar M49A3	60-mm Mortar (JPG)		
	60-mm Mortar M49		
2.75-inch Rocket M230	2.75-inch Rocket M230		
	2.75-inch Rocket XM229		
MK 118 ROCKEYE			
81-mm Mortar M374	81-mm Mortar (JPG)		
	81-mm Mortar M374		
105-mm HEAT Rounds M456			
105-mm Projectile M60	105-mm Projectile M60		
155-mm Projectile M483A1	155-mm Projectile M483A		
	500-lb Bomb		

JPG = Jefferson Proving Ground HEAT = high-explosive antitank

SECTION 2. DEMONSTRATION

2.1 DEMONSTRATOR INFORMATION

2.1.1 Demonstrator Point of Contact (POC) and Address

POC: Mr. Jose Llopis

(601) 634-3164

Address: U.S. Army Corps of Engineers Engineering Research and Development Center

3909 Halls Ferry Road

Vicksburg, MS 39180-6199

2.1.2 System Description (provided by demonstrator)

The GEM-3 system is able to collect multiple channels of complex frequency domain electromagnetic interference (EMI) data over a wide range of audio frequencies (30 Hz to 48 kHz). The system is a wheeled pushcart with a 96-cm sensor head, a mounted electronics console, a user interface, and a real-time kinematic (RTK) Global Positioning System (GPS) (fig. 1). The sensor head consists of three coils. The primary transmitter coil is the outer coil in the sensor head. The receiver coil is the inner coil in the sensor head. The bucking transmitter coil is the middle coil in the sensor head. The current in the bucking coil flows in the opposite direction of the current in the primary transmitter coil. This suppresses the dipole moment on the receiver coil that is directly from the primary transmitter coil. The electronics console contains the multifrequency current waveform generator, the analog-to-digital converter receiver electronics, the digital signal processor, and the power management module. The user interface utilizes a personal digital assistant (PDA). The PDA is used for data logging and allows for real-time control of the system. The PDA also allows for real-time display of the data collected. The RTK GPS will require a base station to be set up at a suitable reference point for radio communication with the mobile unit on the GEM-3 system. The GEM-3 system's acquisition of multifrequency data allows for performing what Geophex Ltd., the developer of the system, calls electromagnetic induction spectroscopy (EMIS) on buried objects. EMIS provides a method to discriminate UXO targets from natural and man-made clutter objects by means of their unique, complex (in-phase and quadrature) frequency responses.



Figure 1. Demonstrator's system, GEM-3 pushcart.

2.1.3 Data Processing Description (provided by demonstrator)

The GEM-3 data acquired at the test site will be processed using a combination of ERDC-developed programs and Geosoft's Oasis Montaj. First, basic data corrections such as background subtraction and time-synchronization between the sensor data and GPS data will be performed. The raw data, after these basic corrections, will be submitted in Geosoft XYZ format. Two Response Stage submissions will be made within 30 days. One will be based on a threshold applied to the total magnitude of the sensor inphase and quadrature response for all frequencies. The second will be based on interactive histogram analysis of the data. Data from each of these detection schemes will be used by the target discrimination algorithm to generate separate Discrimination Stage submissions. The discrimination algorithm compares sensor data collected near each detected anomaly with calibration data acquired over the target types of interest at the beginning of the data collection.

One of ERDC's primary objectives for this data acquisition is to obtain high quality data to further our modeling and analysis research. Therefore, ERDC plans to make further data submissions using other detection and discrimination algorithms on this same dataset, alone and in combination with data from other sensors.

2.1.4 Data Submission Format

Data were submitted for scoring in accordance with data submission protocols outlined in the Standardized UXO Technology Demonstration Site Handbook. These submitted data are not included in this report in order to protect ground truth information.

2.1.5 <u>Demonstrator Quality Assurance (QA) and Quality Control (QC) (provided by demonstrator)</u>

The operators will perform three levels of quality control (QC) checks: the first day of the project, the beginning of the day, and whenever there is an equipment change (i.e. batteries, data dump, etc.). On the first day of the project, the operators will lay out a 10-meter long line oriented North to South with a ferrite bar at the center. This line will be well marked and used each time we test the instrument and positioning are tested. The operators will test for instrument response over the ferrite bar, as well as conduct a position check and a latency check. The operators will walk the line slowly in two directions and then back the pushcart up until it is centered on the ferrite bar. This will set the location of the ferrite bar as well as the instrument response, which will be referenced every time the operators check the equipment.

Each morning the operators will perform functional equipment checks. The operators will visually inspect all equipment for damage. They will then power up the equipment. The operators will perform static and instrument response tests to ensure that the data is stable when the instrument is in a static position over a marked location. These tests will be performed after the instrument has had sufficient time to warm up.

Quality assurance (QA) will be the responsibility of the project lead; he will ensure that test data will be inspected and recorded each day using a known target (e.g. ferrite bar) with the GEM-3 sensors, and using a reference position with the RTK GPS. Geo-referenced data sets will be inspected at the end of the day for GEM-3 data quality and navigation integrity (reasonableness criteria).

Data analysis will be performed each day. This analysis will include inspection of the data for inconsistencies (bad data and errors) and to verify RTK GPS data show good coverage and limited dropouts. If the data show the sensor or electronics are not taking acceptable data or the RTK GPS dropouts are too numerous/large for data analysis or good coverage, that section will be flagged for a resurvey.

2.1.6 Additional Records

The following record(s) by this vendor can be accessed via the Internet as MicroSoft Word documents at www.uxotestsites.org. The counterparts to this report are the Blind Grid, Scoring Record No. 134, and the Open Field, Scoring Record No. 135.

2.2 YPG SITE INFORMATION

2.2.1 Location

YPG is located adjacent to the Colorado River in the Sonoran Desert. The UXO Standardized Test Site is located south of Pole Line Road and east of the Countermine Testing and Training Range. The Open Field range, Calibration Grid, Blind Grid, Mogul area, and Desert Extreme area comprise the 350 by 500-meter general test site area. The open field site is the largest of the test sites and measures approximately 200 by 350 meters. To the east of the open field range are the calibration and blind test grids that measure 30 by 40 meters and 40 by 40 meters, respectively. South of the Open Field is the 135- by 80-meter Mogul area consisting of a sequence of man-made depressions. The Desert Extreme area is located southeast of the open field site and has dimensions of 50 by 100 meters. The Desert Extreme area, covered with desert-type vegetation, is used to test the performance of different sensor platforms in a more severe desert conditions/environment.

2.2.2 Soil Type

Soil samples were collected at the YPG UXO Standardized Test Site by ERDC to characterize the shallow subsurface (< 3 m). Both surface grab samples and continuous soil borings were acquired. The soils were subjected to several laboratory analyses, including sieve/hydrometer, water content, magnetic susceptibility, dielectric permittivity, X-ray diffraction, and visual description.

There are two soil complexes present within the site, Riverbend-Carrizo and Cristobal-Gunsight. The Riverbend-Carrizo complex is comprised of mixed stream alluvium, whereas the Cristobal-Gunsight complex is derived from fan alluvium. The Cristobal-Gunsight complex covers the majority of the site. Most of the soil samples were classified as either a sandy loam or loamy sand, with most samples containing gravel-size particles. All samples had a measured water content less than 7 percent, except for two that contained 11-percent moisture. The majority of soil samples had water content between 1 to 2 percent. Samples containing more than 3 percent were generally deeper than 1 meter.

An X-ray diffraction analysis on four soil samples indicated a basic mineralogy of quartz, calcite, mica, feldspar, magnetite, and some clay. The presence of magnetite imparted a moderate magnetic susceptibility, with volume susceptibilities generally greater than 100 by 10-5 SI.

For more details concerning the soil properties at the YPG test site, go to www.uxotestsites.org on the web to view the entire soils description report.

2.2.3 Test Areas

A description of the test site areas at YPG is included in Table 2.

TABLE 2. TEST SITE AREAS

Area	Description		
Calibration Grid	Contains the 15 standard ordnance items buried in six positions at various angles and depths to allow demonstrator equipment calibration.		
Blind Grid	Contains 400 grid cells in a 0.16-hectare (0.39-acre) site. The center of each grid cell contains ordnance, clutter, or nothing.		
Open Field	A 4-hectare (10-acre) site containing open areas, dips, ruts, and obstructions, including vegetation.		
Desert Extreme			

SECTION 3. FIELD DATA

3.1 DATE OF FIELD ACTIVITIES (20 through 22 May 2003)

3.2 AREAS TESTED/NUMBER OF HOURS

Areas tested and total number of hours operated at each site are summarized in Table 3.

TABLE 3. AREAS TESTED AND NUMBER OF HOURS

Area	Number of Hours		
Calibration Lanes	5.25		
Desert Extreme	10.55		

3.3 TEST CONDITIONS

3.3.1 Weather Conditions

A YPG weather station located approximately one mile west of the test site was used to record average temperature and precipitation on a half hour basis for each day of operation. The temperatures listed in Table 4 represent the average temperature during field operations from 0700 to 1700 hours while precipitation data represents a daily total amount of rainfall. Hourly weather logs used to generate this summary are provided in Appendix B. Weather was not documented during this survey due to weather station issues.

TABLE 4. TEMPERATURE/PRECIPITATION DATA SUMMARY

Date, 2003	Average Temperature, °F	Total Daily Precipitation, in.
May 20	N/A	N/A
May 21	N/A	N/A
May 22	N/A	N/A

3.3.2 Field Conditions

The conditions were warm and dry throughout the ERDC survey.

3.3.3 Soil Moisture

Three soil probes were placed at various locations within the site to capture soil moisture data: Blind Grid, Calibration, Open Field, and Mogul areas. Measurements were collected in percent moisture and were taken twice daily (morning and afternoon) from five different soil depths (1 to 6 in., 6 to 12 in., 12 to 24 in., 24 to 36 in., and 36 to 48 in.) from each probe. Soil moisture logs are included in Appendix C.

3.4 FIELD ACTIVITIES

3.4.1 Setup/Mobilization

These activities included initial mobilization and daily equipment preparation and break down. A five-person crew took 6 hours and 30 minutes to perform the initial setup and mobilization. There was 1-hour and 54 minutes of daily equipment preparation and end of the day equipment break down lasted 10 minutes.

3.4.2 Calibration

ERDC spent a total of 5 hours and 15 minutes in the calibration lanes, 1-hour and 50 minutes of which was spent collecting data. 18 minutes of calibration took place in the Desert Extreme area

3.4.3 Downtime Occasions

Occasions of downtime are grouped into five categories: equipment/data checks or equipment maintenance, equipment failure and repair, weather, Demonstration Site issues, or breaks/lunch. All downtime is included for the purposes of calculating labor costs (section 5) except for downtime due to Demonstration Site issues. Demonstration Site issues, while noted in the Daily Log, are considered non-chargeable downtime for the purposes of calculating labor costs and are not discussed. Breaks and lunches are discussed in this section and billed to the total Site Survey area.

- **3.4.3.1** Equipment/data checks, maintenance. Equipment data checks and maintenance activities accounted for 1-hour and 53 minutes of site usage time. These activities included changing out batteries and routine data checks to ensure the data was being properly recorded/collected. ERDC spent an additional 1-hour and 25 minutes for breaks and lunches.
- **3.4.3.2** Equipment failure or repair. An additional 5 minutes was needed to resolve equipment failures that occurred while surveying the Desert Extreme.
- **3.4.3.3** Weather. No weather delays occurred during the survey.

3.4.4 Data Collection

ERDC spent a total time of 10 hours and 33 minutes in the Desert Extreme area, 5 hours and 6 minutes of which was spent collecting data.

3.4.5 Demobilization

The ERDC survey crew went on to conducted a full demonstration of the site. Therefore, demobilization did not occur until 22 May 2003. On that day, it took the crew 46 minutes to break down and pack up their equipment.

3.5 PROCESSING TIME

ERDC submitted the raw data from the demonstration activities on the last day of the demonstration, as required. The scoring submittal data was also provided within the required 30-day timeframe.

3.6 DEMONSTRATOR'S FIELD PERSONNEL

Field Manager: Jose Llopis

Field Engineer: Troy Broston, Eric Smith

Quality Assurance: Don Yule GPS Support: Tom Berry

3.7 DEMONSTRATOR'S FIELD SURVEYING METHOD

ERDC collected data in a linear fashion and in a north to south direction.

3.8 SUMMARY OF DAILY LOGS

Daily logs capture all field activities during this demonstration and are located in Appendix D. Activities pertinent to this specific demonstration are indicated in highlighted text.

SECTION 4. TECHNICAL PERFORMANCE RESULTS

4.1 ROC CURVES USING ALL ORDNANCE CATEGORIES

Figure 2 shows the probability of detection for the response stage (P_d^{res}) and the discrimination stage (P_d^{disc}) versus their respective probability of false positive. Figure 3 shows both probabilities plotted against their respective background alarm rate. Both figures use horizontal lines to illustrate the performance of the demonstrator at two demonstrator-specified points: at the system noise level for the response stage, representing the point below which targets are not considered detectable, and at the demonstrator's recommended threshold level for the discrimination stage, defining the subset of targets the demonstrator would recommend digging based on discrimination. Note that all points have been rounded to protect the ground truth.

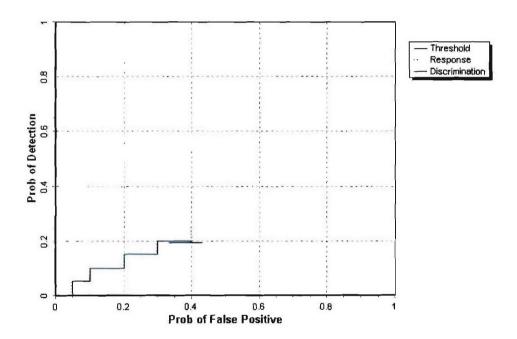


Figure 2. GEM-3/pushcart desert extreme probability of detection for response and discrimination stages versus their respective probability of false positive over all ordnance categories combined.

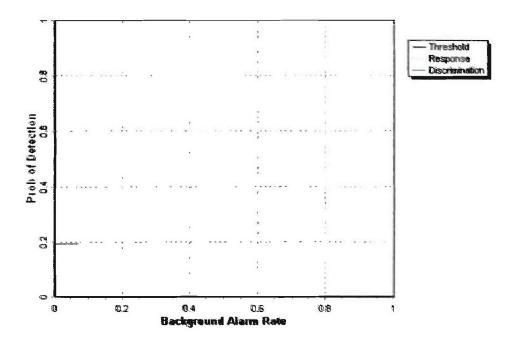


Figure 3. GEM-3/pushcart desert extreme probability of detection for response and discrimination stages versus their respective background alarm rate over all ordnance categories combined.

4.2 ROC CURVES USING ORDNANCE LARGER THAN 20 MM

Figure 4 shows the probability of detection for the response stage (P_d^{res}) and the discrimination stage (P_d^{disc}) versus their respective probability of false positive when only targets larger than 20 mm are scored. Figure 5 shows both probabilities plotted against their respective background alarm rate. Both figures use horizontal lines to illustrate the performance of the demonstrator at two demonstrator-specified points: at the system noise level for the response stage, representing the point below which targets are not considered detectable, and at the demonstrator's recommended threshold level for the discrimination stage, defining the subset of targets the demonstrator would recommend digging based on discrimination. Note that all points have been rounded to protect the ground truth.

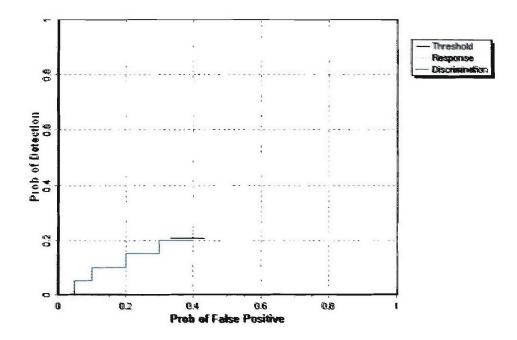


Figure 4. GEM-3/pushcart desert extreme probability of detection for response and discrimination stages versus their respective probability of false positive for all ordnance larger than 20 mm.

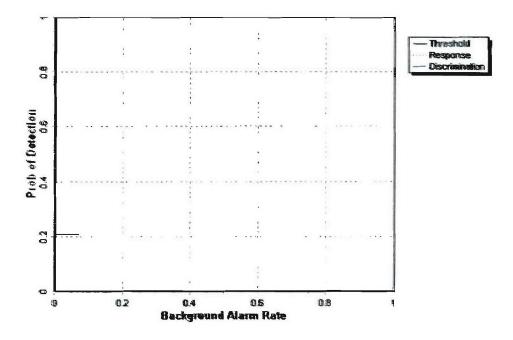


Figure 5. GEM-3/pushcart desert extreme probability of detection for response and discrimination stages versus their respective background alarm rate for all ordnance larger than 20 mm.

4.3 PERFORMANCE SUMMARIES

Results for the desert extreme test broken out by size, depth and nonstandard ordnance are presented in Table 5 (for cost results, see section 5). Results by size and depth include both standard and nonstandard ordnance. The results by size show how well the demonstrator did at detecting/discriminating ordnance of a certain caliber range (see app A for size definitions). The results are relative to the number of ordnance items emplaced. Depth is measured from the geometric center of anomalies.

The RESPONSE STAGE results are derived from the list of anomalies above the demonstrator-provided noise level. The results for the DISCRIMINATION STAGE are derived from the demonstrator's recommended threshold for optimizing UXO field cleanup by minimizing false digs and maximizing ordnance recovery. The lower 90 percent confidence limit on probability of detection and $P_{\rm fp}$ was calculated assuming that the number of detections and false positives are binomially distributed random variables. All results in Table 5 have been rounded to protect the ground truth. However, lower confidence limits were calculated using actual results.

TABLE 5. SUMMARY OF DESERT EXTREME RESULTS FOR GEM-3/PUSHCART

			Nonstandard	By Size			By Depth, m		
Metric	Overall	Standard		Small	Medium	Large	< 0.3	0.3 to <1	>= 1
			RESPONSE S	STAGE					moaner anni
P_d	0.25	0.25	0.15	0.10	0.30	0.60	0.20	0.30	0.20
P _d Low 90% Conf	0.18	0.21	0.10	0.06	0.18	0.43	0.13	0.22	0.02
P _d Upper 90% Conf	0.29	0.35	0.26	0.17	0.39	0.77	0.26	0.43	0.58
P_{fp}	0.40	-	-	-	-	7-	0.40	0.40	0.00
Pfp Low 90% Conf	0.37	-	1-	-	-	-	0.37	0.32	0.00
P _{fp} Upper 90% Conf	0.45	-	-	-	-	-	0.46	0.49	0.90
BAR	0.00	-	-	-	-		-	-	-
			DISCRIMINATIO	ON STAG	E			are a	
P _d	0.20	0.20	0.15	0.05	0.25	0.55	0.15	0.25	0.00
Pd Low 90% Conf	0.15	0.16	0.08	0.03	0.16	0.38	0.11	0.18	0.00
P _d Upper 90% Conf	0.24	0.29	0.23	0.12	0.36	0.72	0.23	0.38	0.37
P _{fp}	0.40	-	-	-	-	-	0.40	0.35	0.00
P _{fp} Low 90% Conf	0.34	-		-	-	-	0.35	0.26	0.00
P _{fp} Upper 90% Conf	0.42	-	-	-	-	-	0.44	0.43	0.90
BAR	0.00	-	-	-		72	-	-	-

Response Stage Noise Level: 50.00.

Recommended Discrimination Stage Threshold: 70.00.

Note: The recommended discrimination stage threshold values are provided by the demonstrator.

4.4 EFFICIENCY, REJECTION RATES, AND TYPE CLASSIFICATION

Efficiency and rejection rates are calculated to quantify the discrimination ability at specific points of interest on the ROC curve: (1) at the point where no decrease in P_d is suffered (i.e., the efficiency is by definition equal to one) and (2) at the operator selected threshold. These values are reported in Table 6.

TABLE 6. EFFICIENCY AND REJECTION RATES

	Efficiency (E)	False Positive Rejection Rate	Background Alarm Rejection Rate
At Operating Point	0.83	0.06	0.11
With No Loss of Pd	1.00	0.00	0.06

At the demonstrator's recommended setting, the ordnance items that were detected and correctly discriminated were further scored on whether their correct type could be identified (table 7). Correct type examples include "20-mm projectile, 105-mm HEAT Projectile, and 2.75-inch Rocket". A list of the standard type declaration required for each ordnance item was provided to demonstrators prior to testing. For example, the standard type for the three example items are 20mmP, 105H, and 2.75in, respectively.

TABLE 7. CORRECT TYPE CLASSIFICATION OF TARGETS CORRECTLY DISCRIMINATED AS UXO

Size	Percentage Correct		
Small	N/A		
Medium	N/A		
Large	N/A		
Overall	N/A		

Note: The demonstrator did not attempt to provide type classification.

4.5 LOCATION ACCURACY

The mean location error and standard deviations appear in Table 8. These calculations are based on average missed depth for ordnance correctly identified in the discrimination stage. Depths are measured from the closest point of the ordnance to the surface. For the Blind Grid, only depth errors are calculated, since (X, Y) positions are known to be the centers of each grid square.

TABLE 8. MEAN LOCATION ERROR AND STANDARD DEVIATION (M)

	Mean	Standard Deviation
Northing	-0.06	0.19
Easting	-0.14	0.22
Depth	-0.12	0.19

SECTION 5. ON-SITE LABOR COSTS

A standardized estimate for labor costs associated with this effort was calculated as follows: the first person at the test site was designated "supervisor", the second person was designated "data analyst", and the third and following personnel were considered "field support". Standardized hourly labor rates were charged by title: supervisor at \$95.00/hour, data analyst at \$57.00/hour, and field support at \$28.50/hour.

Government representatives monitored on-site activity. All on-site activities were grouped into one of ten categories: initial setup/mobilization, daily setup/stop, calibration, collecting data, downtime due to break/lunch, downtime due to equipment failure, downtime due to equipment/data checks or maintenance, downtime due to weather, downtime due to demonstration site issue, or demobilization. See Appendix D for the daily activity log. See section 3.4 for a summary of field activities.

The standardized cost estimate associated with the labor needed to perform the field activities is presented in Table 9. Note that calibration time includes time spent in the Calibration Lanes as well as field calibrations. "Site survey time" includes daily setup/stop time, collecting data, breaks/lunch, downtime due to equipment/data checks or maintenance, downtime due to failure, and downtime due to weather.

TABLE 9. ON-SITE LABOR COSTS

	No. People	Hourly Wage	Hours	Cost
		Initial Setup	7-9	
Supervisor	1	\$95.00	6.50	\$630.50
Data Analyst	1	57.00	6.50	370.50
Field Support	3	28.50	6.50	555.75
SubTotal				\$1,556.75
		Calibration		
Supervisor	1	\$95.00	5.55	\$527.25
Data Analyst	1	57.00	5.55	316.35
Field Support	3	28.50	5.55	474.53
SubTotal				\$1,318.13
		Site Survey		
Supervisor	1	\$95.00	10.55	\$1,002.25
Data Analyst	1	57.00	10.55	601.35
Field Support	1	28.50	10.55	300.68
SubTotal				\$1,904.28

See notes at end of table.

TABLE 9 (CONT'D)

	No. People	Hourly Wage	Hours	Cost			
Demobilization							
Supervisor	1	\$95.00	0.77	\$73.15			
Data Analyst	1	57.00	0.77	43.89			
Field Support	1	28.50	0.77	21.95			
Subtotal				\$138.99			
Total				\$4,918.15			

Notes: Calibration time includes time spent in the Calibration Lanes as well as calibration before each data run.

Site Survey time includes daily setup/stop time, collecting data, breaks/lunch, downtime due to system maintenance, failure, and weather.

SECTION 6. COMPARISON OF RESULTS TO OPEN FIELD DEMONSTRATION

6.1 SUMMARY OF RESULTS FROM OPEN FIELD DEMONSTRATION

Table 10 shows the results from Open Field survey conducted prior to surveying the Desert Extreme during the same site visit in May of 2003. For more details on the Open Field survey results reference section 2.1.6.

TABLE 10. SUMMARY OF OPEN FIELD RESULTS FOR THE GEM-3/PUSHCART

Metric	Overall	Standard	Nonstandard	By Size		By Depth, m			
				Small	Medium	Large	< 0.3	0.3 to <1	>= 1
			RESPONSE S	STAGE					
Pd	0.45	0.45	0.55	0.35	0.60	0.65	0.50	0.50	0.05
Pd Low 90% Conf	0.44	0.39	0.48	0.31	0.52	0.60	0.46	0.46	0.03
P _d Upper 90% Conf	0.50	0.47	0.57	0.39	0.63	0.73	0.54	0.56	0.16
Pfp	0.50	72	-	F 1	-	-	0.55	0.50	0.00
P _{fp} Low 90% Conf	0.50	~	-		-	·	0.51	0.47	0.00
P _d Upper 90% Conf	0.54	-	-	-		-	0.55	0.55	0.21
BAR	0.15	-		-	-		-	-	-
			DISCRIMINATION	ON STAG	E		-		
P_d	0.45	0.40	0.50	0.30	0.55	0.65	0.45	0.50	0.05
Pd Low 90% Conf	0.41	0.37	0.44	0.27	0.50	0.57	0.43	0.44	0.03
P _d Upper 90% Conf	0.47	0.45	0.53	0.35	0.61	0.71	0.50	0.54	0.16
P _{fp}	0.50	-		1 2	-	-	0.50	0.45	0.00
P _{fp} Low 90% Conf	0.47	-		-	-	le le	0.48	0.42	0.00
P _d Upper 90% Conf	0.50	-			18	H.	0.52	0.49	0.21
BAR	0.05	-		14	-	-	1=	-	

6.2 COMPARISON OF ROC CURVES USING ALL ORDNANCE CATEGORIES

Figure 6 shows P_d^{res} versus the respective P_{fp} over all ordnance categories. Figure 7 shows P_d^{disc} versus their respective P_{fp} over all ordnance categories. Figure 7 uses horizontal lines to illustrate the performance of the demonstrator at the recommended discrimination threshold levels, defining the subset of targets the demonstrator would recommend digging based on discrimination.

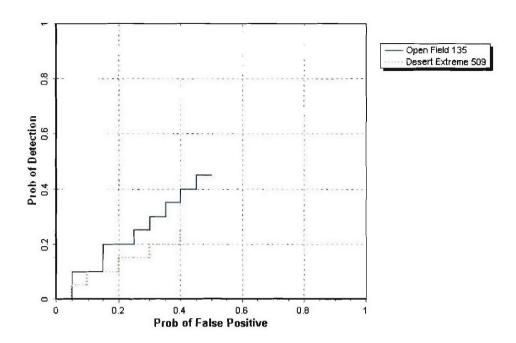


Figure 6. GEM-3/pushcart P_d^{res} stages versus the respective P_{fp} over all ordnance categories combined.

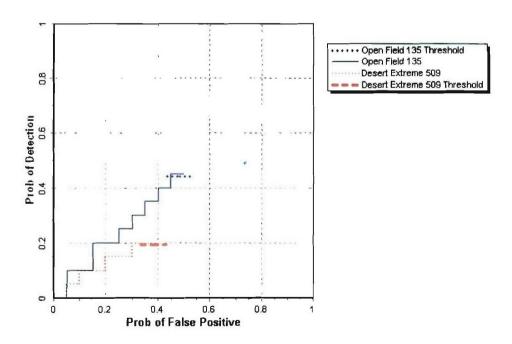


Figure 7. GEM-3/pushcart P_d^{disc} versus the respective P_{fp} over all ordnance categories combined.

6.3 COMPARISON OF ROC CURVES USING ORDNANCE LARGER THAN 20 MM

Figure 8 shows the P_d^{res} versus the respective probability of P_{fp} over ordnance larger than 20 mm. Figure 9 shows P_d^{disc} versus the respective P_{fp} over ordnance larger than 20 mm. Figure 9 uses horizontal lines to illustrate the performance of the demonstrator at the recommended discrimination threshold levels, defining the subset of targets the demonstrator would recommend digging based on discrimination.

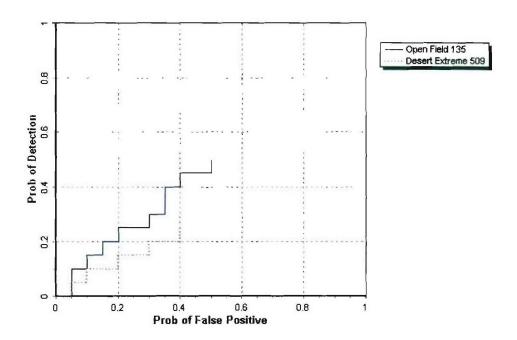


Figure 8. GEM-3/pushcart P_d^{res} versus the respective P_{fp} for ordnance larger than 20 mm.

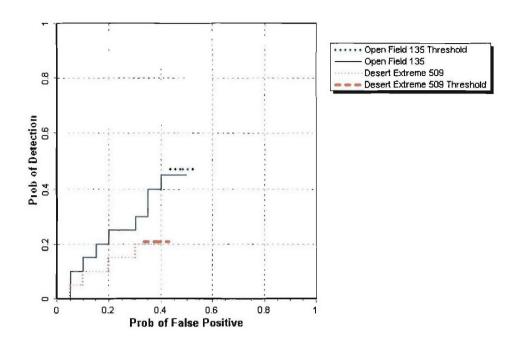


Figure 9. GEM-3/pushcart P_d^{disc} versus the respective P_{fp} for ordnance larger than 20 mm.

6.4 STATISTICAL COMPARISONS

Statistical Chi-square significance tests were used to compare results between the Open Field and Desert Extreme scenarios. The intent of the comparison is to determine if the feature introduced in each scenario has a degrading effect on the performance of the sensor system. However, any modifications in the UXO sensor system during the test, like changes in the processing or changes in the selection of the operating threshold, will also contribute to performance differences.

The Chi-square test for comparison between ratios was used at a significance level of 0.05 to compare Open Field to Desert Extreme with regard to P_d^{res} , P_d^{disc} , P_{fp}^{res} and P_{fp}^{disc} , Efficiency and Rejection Rate. These results are presented in Table 11. A detailed explanation and example of the Chi-square application is located in Appendix A.

TABLE 11. CHI-SQUARE RESULTS – OPEN FIELD VERSUS DESERT EXTREME

Metric	Small	Medium	Large	Overall
P _d res	Significant	Significant	Not Significant	Significant
P _d disc	Significant	Significant	Not Significant	Significant
P _{fp} res	Not Significant	Not Significant	Not Significant	Significant
P _{fp} disc	-		-	Significant
Efficiency	F	-	-	Significant
Rejection rate	-	-	-	Not Significant

SECTION 7. APPENDIXES

APPENDIX A. TERMS AND DEFINITIONS

GENERAL DEFINITIONS

Anomaly: Location of a system response deemed to warrant further investigation by the demonstrator for consideration as an emplaced ordnance item.

Detection: An anomaly location that is within R_{halo} of an emplaced ordnance item.

Emplaced Ordnance: An ordnance item buried by the government at a specified location in the test site.

Emplaced Clutter: A clutter item (i.e., non-ordnance item) buried by the government at a specified location in the test site.

R_{halo}: A pre-determined radius about the periphery of an emplaced item (clutter or ordnance) within which a location identified by the demonstrator as being of interest is considered to be a response from that item. If multiple declarations lie within R_{halo} of any item (clutter or ordnance), the declaration with the highest signal output within the R_{halo} will be utilized. For the purpose of this program, a circular halo 0.5 meters in radius will be placed around the center of the object for all clutter and ordnance items less than 0.6 meters in length. When ordnance items are longer than 0.6 meters, the halo becomes an ellipse where the minor axis remains 1 meter and the major axis is equal to the length of the ordnance plus 1 meter.

Small Ordnance: Caliber of ordnance less than or equal to 40 mm (includes 20-mm projectile, 40-mm projectile, submunitions BLU-26, BLU-63, and M42).

Medium Ordnance: Caliber of ordnance greater than 40 mm and less than or equal to 81 mm (includes 57-mm projectile, 60-mm mortar, 2.75 in. Rocket, MK118 Rockeye, 81-mm mortar).

Large Ordnance: Caliber of ordnance greater than 81 mm (includes 105-mm HEAT, 105-mm projectile, 155-mm projectile, 500-pound bomb).

Shallow: Items buried less than 0.3 meter below ground surface.

Medium: Items buried greater than or equal to 0.3 meter and less than 1 meter below ground surface.

Deep: Items buried greater than or equal to 1 meter below ground surface.

Response Stage Noise Level: The level that represents the point below which anomalies are not considered detectable. Demonstrators are required to provide the recommended noise level for the Blind Grid test area.

Discrimination Stage Threshold: The demonstrator selected threshold level that they believe provides optimum performance of the system by retaining all detectable ordnance and rejecting the maximum amount of clutter. This level defines the subset of anomalies the demonstrator would recommend digging based on discrimination.

Binomially Distributed Random Variable: A random variable of the type which has only two possible outcomes, say success and failure, is repeated for n independent trials with the probability p of success and the probability 1-p of failure being the same for each trial. The number of successes x observed in the n trials is an estimate of p and is considered to be a binomially distributed random variable.

RESPONSE AND DISCRIMINATION STAGE DATA

The scoring of the demonstrator's performance is conducted in two stages. These two stages are termed the RESPONSE STAGE and DISCRIMINATION STAGE. For both stages, the probability of detection (P_d) and the false alarms are reported as receiver operating characteristic (ROC) curves. False alarms are divided into those anomalies that correspond to emplaced clutter items, measuring the probability of false positive (P_{fp}) and those that do not correspond to any known item, termed background alarms.

The RESPONSE STAGE scoring evaluates the ability of the system to detect emplaced targets without regard to ability to discriminate ordnance from other anomalies. For the RESPONSE STAGE, the demonstrator provides the scoring committee with the location and signal strength of all anomalies that the demonstrator has deemed sufficient to warrant further investigation and/or processing as potential emplaced ordnance items. This list is generated with minimal processing (e.g., this list will include all signals above the system noise threshold). As such, it represents the most inclusive list of anomalies.

The DISCRIMINATION STAGE evaluates the demonstrator's ability to correctly identify ordnance as such, and to reject clutter. For the same locations as in the RESPONSE STAGE anomaly list, the DISCRIMINATION STAGE list contains the output of the algorithms applied in the discrimination-stage processing. This list is prioritized based on the demonstrator's determination that an anomaly location is likely to contain ordnance. Thus, higher output values are indicative of higher confidence that an ordnance item is present at the specified location. For electronic signal processing, priority ranking is based on algorithm output. For other systems, priority ranking is based on human judgment. The demonstrator also selects the threshold that the demonstrator believes will provide "optimum" system performance, (i.e., that retains all the detected ordnance and rejects the maximum amount of clutter).

Note: The two lists provided by the demonstrator contain identical numbers of potential target locations. They differ only in the priority ranking of the declarations.

RESPONSE STAGE DEFINITIONS

Response Stage Probability of Detection (P_d^{res}): $P_d^{res} = (No. of response-stage detections)/(No. of emplaced ordnance in the test site).$

Response Stage False Positive (fp^{res}): An anomaly location that is within R_{halo} of an emplaced clutter item.

Response Stage Probability of False Positive (P_{fp}^{res}) : $P_{fp}^{res} = (No. of response-stage false positives)/(No. of emplaced clutter items).$

Response Stage Background Alarm (ba res): An anomaly in a blind grid cell that contains neither emplaced ordnance nor an emplaced clutter item. An anomaly location in the open field or scenarios that is outside R_{halo} of any emplaced ordnance or emplaced clutter item.

Response Stage Probability of Background Alarm (P_{ba}^{res}): Blind Grid only: $P_{ba}^{res} = (No. of response-stage background alarms)/(No. of empty grid locations).$

Response Stage Background Alarm Rate (BAR^{res}): Open Field only: BAR^{res} = (No. of response-stage background alarms)/(arbitrary constant).

Note that the quantities P_d^{res} , P_{fp}^{res} , P_{ba}^{res} , and BAR^{res} are functions of t^{res} , the threshold applied to the response-stage signal strength. These quantities can therefore be written as $P_d^{res}(t^{res})$, $P_{fp}^{res}(t^{res})$, $P_{ba}^{res}(t^{res})$, and $BAR^{res}(t^{res})$.

DISCRIMINATION STAGE DEFINITIONS

Discrimination: The application of a signal processing algorithm or human judgment to response-stage data that discriminates ordnance from clutter. Discrimination should identify anomalies that the demonstrator has high confidence correspond to ordnance, as well as those that the demonstrator has high confidence correspond to nonordnance or background returns. The former should be ranked with highest priority and the latter with lowest.

Discrimination Stage Probability of Detection (P_d^{disc}) : $P_d^{disc} = (No. of discrimination-stage detections)/(No. of emplaced ordnance in the test site).$

Discrimination Stage False Positive (fp^{disc}): An anomaly location that is within R_{halo} of an emplaced clutter item.

Discrimination Stage Probability of False Positive (P_{fp}^{disc}): $P_{fp}^{disc} = (No. of discrimination stage false positives)/(No. of emplaced clutter items).$

Discrimination Stage Background Alarm (ba^{disc}): An anomaly in a blind grid cell that contains neither emplaced ordnance nor an emplaced clutter item. An anomaly location in the open field or scenarios that is outside R_{halo} of any emplaced ordnance or emplaced clutter item.

Discrimination Stage Probability of Background Alarm (P_{ba}^{disc}): $P_{ba}^{disc} = (No. of discrimination-stage background alarms)/(No. of empty grid locations).$

Discrimination Stage Background Alarm Rate (BAR^{disc}): BAR^{disc} = (No. of discrimination-stage background alarms)/(arbitrary constant).

Note that the quantities P_d^{disc} , P_{fp}^{disc} , P_{ba}^{disc} , and BAR^{disc} are functions of t^{disc} , the threshold applied to the discrimination-stage signal strength. These quantities can therefore be written as $P_d^{disc}(t^{disc})$, $P_{fp}^{disc}(t^{disc})$, $P_{ba}^{disc}(t^{disc})$, and $BAR^{disc}(t^{disc})$.

RECEIVER-OPERATING CHARACERISTIC (ROC) CURVES

ROC curves at both the response and discrimination stages can be constructed based on the above definitions. The ROC curves plot the relationship between P_d versus P_{fp} and P_d versus BAR or P_{ba} as the threshold applied to the signal strength is varied from its minimum (t_{min}) to its maximum (t_{max}) value. Figure A-1 shows how P_d versus P_{fp} and P_d versus BAR are combined into ROC curves. Note that the "res" and "disc" superscripts have been suppressed from all the variables for clarity.

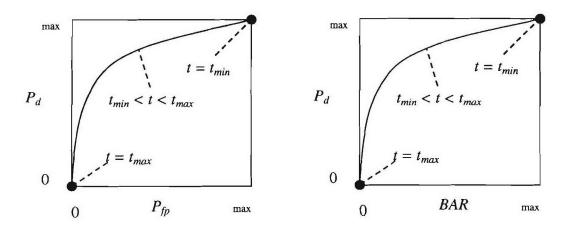


Figure A-1. ROC curves for open field testing. Each curve applies to both the response and discrimination stages.

Strictly speaking, ROC curves plot the P_d versus P_{ba} over a pre-determined and fixed number of detection opportunities (some of the opportunities are located over ordnance and others are located over clutter or blank spots). In an open field scenario, each system suppresses its signal strength reports until some bare-minimum signal response is received by the system. Consequently, the open field ROC curves do not have information from low signal-output locations, and, furthermore, different contractors report their signals over a different set of locations on the ground. These ROC curves are thus not true to the strict definition of ROC curves as defined in textbooks on detection theory. Note, however, that the ROC curves obtained in the Blind Grid test sites are true ROC curves.

METRICS TO CHARACTERIZE THE DISCRIMINATION STAGE

The demonstrator is also scored on efficiency and rejection ratio, which measure the effectiveness of the discrimination stage processing. The goal of discrimination is to retain the greatest number of ordnance detections from the anomaly list, while rejecting the maximum number of anomalies arising from nonordnance items. The efficiency measures the amount of detected ordnance retained by the discrimination, while the rejection ratio measures the fraction of false alarms rejected. Both measures are defined relative to the entire response list, i.e., the maximum ordnance detectable by the sensor and its accompanying false positive rate or background alarm rate.

Efficiency (E): $E = P_d^{disc}(t^{disc})/P_d^{res}(t_{min}^{res})$; Measures (at a threshold of interest), the degree to which the maximum theoretical detection performance of the sensor system (as determined by the response stage tmin) is preserved after application of discrimination techniques. Efficiency is a number between 0 and 1. An efficiency of 1 implies that all of the ordnance initially detected in the response stage was retained at the specified threshold in the discrimination stage, t^{disc} .

False Positive Rejection Rate (R_{fp}) : $R_{fp} = 1 - [P_{fp}^{\ disc}(t^{\ disc})/P_{fp}^{\ res}(t_{min}^{\ res})]$; Measures (at a threshold of interest), the degree to which the sensor system's false positive performance is improved over the maximum false positive performance (as determined by the response stage tmin). The rejection rate is a number between 0 and 1. A rejection rate of 1 implies that all emplaced clutter initially detected in the response stage were correctly rejected at the specified threshold in the discrimination stage.

Background Alarm Rejection Rate (Rba):

$$\begin{split} &Blind\ Grid:\ R_{ba}=1\ \hbox{-}\ [P_{ba}^{\ disc}(t^{disc})\!/P_{ba}^{\ res}(t_{min}^{\ res})].\\ &Open\ Field:\ R_{ba}=1\ \hbox{-}\ [BAR^{disc}(t^{disc})\!/BAR^{res}(t_{min}^{\ res})]). \end{split}$$

Measures the degree to which the discrimination stage correctly rejects background alarms initially detected in the response stage. The rejection rate is a number between 0 and 1. A rejection rate of 1 implies that all background alarms initially detected in the response stage were rejected at the specified threshold in the discrimination stage.

CHI-SQUARE COMPARISON EXPLANATION:

The Chi-square test for differences in probabilities (or 2 x 2 contingency table) is used to analyze two samples drawn from two different populations to see if both populations have the same or different proportions of elements in a certain category. More specifically, two random samples are drawn, one from each population, to test the null hypothesis that the probability of event A (some specified event) is the same for both populations (ref 3).

A 2 x 2 contingency table is used in the Standardized UXO Technology Demonstration Site Program to determine if there is reason to believe that the proportion of ordnance correctly detected/discriminated by demonstrator X's system is significantly degraded by the more challenging terrain feature introduced. The test statistic of the 2 x 2 contingency table is the

Chi-square distribution with one degree of freedom. Since an association between the more challenging terrain feature and relatively degraded performance is sought, a one-sided test is performed. A significance level of 0.05 is chosen which sets a critical decision limit of 2.71 from the Chi-square distribution with one degree of freedom. It is a critical decision limit because if the test statistic calculated from the data exceeds this value, the two proportions tested will be considered significantly different. If the test statistic calculated from the data is less than this value, the two proportions tested will be considered not significantly different.

An exception must be applied when either a 0 or 100 percent success rate occurs in the sample data. The Chi-square test cannot be used in these instances. Instead, Fischer's test is used and the critical decision limit for one-sided tests is the chosen significance level, which in this case is 0.05. With Fischer's test, if the test statistic is less than the critical value, the proportions are considered to be significantly different.

Standardized UXO Technology Demonstration Site examples, where blind grid results are compared to those from the open field and open field results are compared to those from one of the scenarios, follow. It should be noted that a significant result does not prove a cause and effect relationship exists between the two populations of interest; however, it does serve as a tool to indicate that one data set has experienced a degradation in system performance at a large enough level than can be accounted for merely by chance or random variation. Note also that a result that is not significant indicates that there is not enough evidence to declare that anything more than chance or random variation within the same population is at work between the two data sets being compared.

Demonstrator X achieves the following overall results after surveying each of the three progressively more difficult areas using the same system (results indicate the number of ordnance detected divided by the number of ordnance emplaced):

Blind Grid	Open Field	Moguls
$P_d^{\text{res}} 100/100 = 1.0$	8/10 = .80	20/33 = .61
$P_d^{\text{disc}} 80/100 = 0.80$	6/10 = .60	8/33 = .24

P_d^{res}: BLIND GRID versus OPEN FIELD. Using the example data above to compare probabilities of detection in the response stage, all 100 ordnance out of 100 emplaced ordnance items were detected in the blind grid while 8 ordnance out of 10 emplaced were detected in the open field. Fischer's test must be used since a 100 percent success rate occurs in the data. Fischer's test uses the four input values to calculate a test statistic of 0.0075 that is compared against the critical value of 0.05. Since the test statistic is less than the critical value, the smaller response stage detection rate (0.80) is considered to be significantly less at the 0.05 level of significance. While a significant result does not prove a cause and effect relationship exists between the change in survey area and degradation in performance, it does indicate that the detection ability of demonstrator X's system seems to have been degraded in the open field relative to results from the blind grid using the same system.

- P_d disc: BLIND GRID versus OPEN FIELD. Using the example data above to compare probabilities of detection in the discrimination stage, 80 out of 100 emplaced ordnance items were correctly discriminated as ordnance in blind grid testing while 6 ordnance out of 10 emplaced were correctly discriminated as such in open field-testing. Those four values are used to calculate a test statistic of 1.12. Since the test statistic is less than the critical value of 2.71, the two discrimination stage detection rates are considered to be not significantly different at the 0.05 level of significance.
- P_d^{res}: OPEN FIELD versus MOGULS. Using the example data above to compare probabilities of detection in the response stage, 8 out of 10 and 20 out of 33 are used to calculate a test statistic of 0.56. Since the test statistic is less than the critical value of 2.71, the two response stage detection rates are considered to be not significantly different at the 0.05 level of significance.
- P_d disc. OPEN FIELD versus MOGULS. Using the example data above to compare probabilities of detection in the discrimination stage, 6 out of 10 and 8 out of 33 are used to calculate a test statistic of 2.98. Since the test statistic is greater than the critical value of 2.71, the smaller discrimination stage detection rate is considered to be significantly less at the 0.05 level of significance. While a significant result does not prove a cause and effect relationship exists between the change in survey area and degradation in performance, it does indicate that the ability of demonstrator X to correctly discriminate seems to have been degraded by the mogul terrain relative to results from the flat open field using the same system.

APPENDIX B. DAILY WEATHER LOGS

TABLE B-1. WEATHER LOG

		er Data from Yuma		
D-4	Time,	Average	Relative	Precipitation
Date	EDST	Temperature, °F	Humidity, %	in.
5/7/2003	01:00	66.1	33	0.00
5/7/2003	02:00	64.8	35	0.00
5/7/2003	03:00	63.2	36	0.00
5/7/2003	04:00	62.0	37	0.00
5/7/2003	05:00	61.2	37	0.00
5/7/2003	06:00	60.2	38	0.00
5/7/2003	07:00	62.1	37	0.00
5/7/2003	08:00	63.4	38	0.00
5/7/2003	09:00	66.0	36	0.00
5/7/2003	10:00	69.2	33	0.00
5/7/2003	11:00	72.1	30	0.00
5/7/2003	12:00	74.6	26	0.00
5/7/2003	13:00	76.5	25	0.00
5/7/2003	14:00	77.4	24	0.00
5/7/2003	15:00	77.4	23	0.00
5/7/2003	16:00	77.9	23	0.00
5/7/2003	17:00	76.6	25	0.00
5/7/2003	18:00	74.7	26	0.00
5/7/2003	19:00	71.8	33	0.00
5/7/2003	20:00	69.5	36	0.00
5/7/2003	21:00	67.8	40	0.00
5/7/2003	22:00	65.8	45	0.00
5/7/2003	23:00	64.9	46	0.00
5/7/2003	24:00	63.8	47	0.00
5/8/2003	01:00	62.6	47	0.00
5/8/2003	02:00	61.8	45	0.00
5/8/2003	03:00	59.7	45	0.00
5/8/2003	04:00	58.0	48	0.00
5/8/2003	05:00	56.8	53	0.00
5/8/2003	06:00	55.5	56	0.00
5/8/2003	07:00	57.5	53	0.00
5/8/2003	08:00	60.5	47	0.00
5/8/2003	09:00	65.1	40	0.00
5/8/2003	10:00	67.3	36	0.00
5/8/2003	11:00	71.1	30	0.00
5/8/2003	12:00	72.9	29	0.00
5/8/2003	13:00	74.4	27	0.00
5/8/2003	14:00	76.4	24	0.00
5/8/2003	15:00	77.2	23	0.00
2 22		78.1	23	0.00
5/8/2003	16:00	77.3		
5/8/2003	17:00		24	0.00
5/8/2003	18:00	76.2	22	0.00
5/8/2003	19:00	73.5	22	0.00

TABLE B-1 (CONT'D)

		er Data from Yuma		
Date	Time, EDST	Average Temperature, °F	Relative Humidity, %	Precipitation in.
5/8/2003	20:00	69.5	29	0.00
5/8/2003	21:00	67.3	28	0.00
5/8/2003	22:00	64.5	32	0.00
5/8/2003	23:00	62.8	32	0.00
5/8/2003	24:00	60.8	38	0.00
5/9/2003	01:00	58.6	43	0.00
5/9/2003	02:00	57.9	45	0.00
5/9/2003	03:00	56.1	49	0.00
5/9/2003	04:00	54.6	52	0.00
5/9/2003	05:00	55.1	52	0.00
5/9/2003	06:00	55.0	51	0.00
5/9/2003	07:00	56.7	49	0.00
5/9/2003	08:00	59.7	45	0.00
5/9/2003	09:00	62.9	39	0.00
5/9/2003	10:00	65.8	33	0.00
5/9/2003	11:00	67.7	29	0.00
5/9/2003	12:00	69.8	26	0.00
5/9/2003	13:00	71.4	22	0.00
5/9/2003	14:00	72.2	17	0.00
5/9/2003	15:00	73.0	18	0.00
5/9/2003	16:00	75.0	16	0.00
5/9/2003	17:00	76.0	14	0.00
5/9/2003	18:00	75.8	12	0.00
5/9/2003	19:00	73.5	20	0.00
5/9/2003	20:00	71.4	20	0.00
5/9/2003	21:00	68.5	22	0.00
5/9/2003	22:00	66.4	24	0.00
5/9/2003	23:00	65.9	23	0.00
5/9/2003	24:00	63.4	27	0.00
5/10/2003	01:00	60.5	34	0.00
5/10/2003	02:00	59.6	39	0.00
5/10/2003	03:00	56.9	42	0.00
5/10/2003	04:00	54.6	44	0.00
5/10/2003	05:00	53.2	43	0.00
5/10/2003	06:00	51.0	44	0.00
5/10/2003	07:00	58.1	32	0.00
5/10/2003	08:00	64.8	31	0.00
5/10/2003	09:00	68.4	25	0.00
5/10/2003	10:00	72.5	20	0.00
5/10/2003	11:00	76.3	15	0.00
5/10/2003	12:00	77.8	12	0.00
5/10/2003	13:00	79.8	13	0.00
5/10/2003	14:00	81.7	12	0.00
5/10/2003	15:00	81.8	12	0.00
5/10/2003	16:00	83.2	10	0.00

TABLE B-1 (CONT'D)

		er Data from Yuma		nd
	Time,	Average	Relative	Precipitation
Date	EDST	Temperature, °F	Humidity, %	in.
5/10/2003	17:00	83.3	10	0.00
5/10/2003	18:00	82.7	10	0.00
5/10/2003	19:00	81.6	10	0.00
5/10/2003	20:00	78.1	13	0.00
5/10/2003	21:00	75.4	15	0.00
5/10/2003	22:00	72.8	15	0.00
5/10/2003	23:00	68.9	18	0.00
5/10/2003	24:00	66.1	19	0.00
5/12/2003	01:00	71.2	21	0.00
5/12/2003	02:00	69.7	21	0.00
5/12/2003	03:00	67.2	23	0.00
5/12/2003	04:00	63.2	24	0.00
5/12/2003	05:00	63.4	25	0.00
5/12/2003	06:00	61.7	26	0.00
5/12/2003	07:00	65.9	21	0.00
5/12/2003	08:00	74.7	15	0.00
5/12/2003	09:00	81.7	14	0.00
5/12/2003	10:00	86.5	12	0.00
5/12/2003	11:00	89.3	10	0.00
5/12/2003	12:00	90.8	11	0.00
5/12/2003	13:00	93.0	8	0.00
5/12/2003	14:00	94.3	8	0.00
5/12/2003	15:00	95.7	8	0.00
5/12/2003	16:00	95.0	8	0.00
5/12/2003	17:00	94.7	9	0.00
5/12/2003	18:00	94.7	9	0.00
5/12/2003	19:00	92.2	9	0.00
5/12/2003	20:00	89.5	9	0.00
5/12/2003	21:00	85.3	10	0.00
5/12/2003	22:00	83.4	16	0.00
5/12/2003	23:00	80.4	17	0.00
5/12/2003	24:00	79.1	19	0.00
5/14/2003	01:00	76.0	21	0.00
5/14/2003	02:00	74.1	21	0.00
5/14/2003	03:00	72.4	22	0.00
5/14/2003	04:00	73.2	21	0.00
5/14/2003	05:00	71.8	21	0.00
5/14/2003	06:00	73.4	18	0.00
5/14/2003	07:00	73.2	19	0.00
5/14/2003	08:00	77.0	15	0.00
5/14/2003	09:00	82.6	13	0.00
5/14/2003	10:00	85.0	12	0.00
5/14/2003	11:00	88.9	10	0.00
5/14/2003	12:00	92.4	9	0.00
5/14/2003	13:00	94.8	8	0.00

TABLE B-1 (CONT'D)

	Weathe	er Data from Yuma	Proving Groun	nd
	Time,	Average	Relative	Precipitation,
Date	EDST	Temperature, °F	Humidity, %	in.
5/14/2003	14:00	97.4	7	0.00
5/14/2003	15:00	96.2	6	0,00
5/14/2003	16:00	96.5	7	0.00
5/14/2003	17:00	94.6	9	0.00
5/14/2003	18:00	93.8	7	0.00
5/14/2003	19:00	92.0	8	0.00
5/14/2003	20:00	87.9	10	0.00
5/14/2003	21:00	84.4	11	0.00
5/14/2003	22:00	81.9	11	0.00
5/14/2003	23:00	79.4	12	0.00
5/14/2003	24:00	78.6	12	0.00
5/15/2003	01:00	62.5	39	0.00
5/15/2003	02:00	61.1	40	0.00
5/15/2003	03:00	60.0	44	0.00
5/15/2003	04:00	58.1	49	0.00
5/15/2003	05:00	57.9	51	0.00
5/15/2003	06:00	57.0	52	0.00
5/15/2003	07:00	60.8	46	0.00
5/15/2003	08:00	64.5	45	0.00
5/15/2003	09:00	68.3	37	0.00
5/15/2003	10:00	73.1	31	0.00
5/15/2003	11:00	78.0	26	0.00
5/15/2003	12:00	81.0	23	0.00
5/15/2003	13:00	83.4	22	0.00
5/15/2003	14:00	85.7	20	0.00
5/15/2003	15:00	87.5	18	0.00
5/15/2003	16:00	89.7	17	0.00
5/15/2003	17:00	89.8	17	0.00
5/15/2003	18:00	89.9	17	0.00
5/15/2003	19:00	88.4	18	0.00
5/15/2003	20:00	86.0	19	0.00
5/15/2003	21:00	83.4	21	0.00
5/15/2003	22:00	80.2	22	0.00
5/15/2003	23:00	75.7	25	0.00
5/15/2003	24:00	73.7	26	0.00
5/16/2003	01:00	73.9	29	0.00
5/16/2003	02:00	70.8	32	0.00
5/16/2003	03:00	69.2	32	0.00
5/16/2003	04:00	68.5	33	0.00
5/16/2003	05:00	66.7	35	0.00
5/16/2003	06:00	65.4	35	0.00
5/16/2003	07:00	70.5	30	0.00
5/16/2003	08:00	79.3	23	0.00
5/16/2003	09:00	86.4	17	0.00
5/16/2003	10:00	90.0	14	0.00

TABLE B-1 (CONT'D)

	Time,	er Data from Yum Average	Relative	Precipitation
Date		Temperature, °F		in.
5/16/2003		92.0	14	0.00
5/16/2003		94.0	13	0.00
5/16/2003	The second second	95.5	12	0.00
5/16/2003		97.9	11	0.00
5/16/2003		98.9	11	0.00
5/16/2003	0.750	99.9	11	0.00
5/16/2003		99.4	12	0.00
5/16/2003	0.00 0.00 0.000000000000000000000000000	99.1	10	0.00
5/16/2003		97.7	11	0.00
5/16/2003		93.1	12	0.00
5/16/2003		87.8	14	0.00
5/16/2003		86.1	16	0.00
5/16/2003	23:00	83.0	18	0.00
5/16/2003		80.4	19	0.00
5/19/2003		79.3	19	0.00
5/19/2003	E - 100 E 200	77.6	19	0.00
5/19/2003		75.2	20	0.00
5/19/2003		73.4	21	
5/19/2003			24	0.00
		71.6		
5/19/2003		68.4	25	0.00
5/19/2003		74.2	23	0.00
5/19/2003		80.5	25	0.00
5/19/2003		84.5	24	0.00
5/19/2003	10:00	89.7	14	0.00
5/19/2003		94.4	11	0.00
5/19/2003	12:00	97.3	10	0.00
5/19/2003		99.8	8	0.00
5/19/2003		101.0	8	0.00
5/19/2003		101.1	8	0.00
5/19/2003		101.3	7	0.00
5/19/2003		101.9	7	0.00
5/19/2003		101.0	7	0.00
5/19/2003	19:00	99.1	8	0.00
5/19/2003		95.2	9	0.00
5/19/2003	21:00	91.4	11	0.00
5/19/2003	22:00	88.1	11	0.00
5/19/2003	23:00	83.8	13	0.00
5/19/2003	24:00	81.7	15	0.00
6/4/2003	01:00	81.0	19	0.00
6/4/2003	02:00	80.0	22	0.00
6/4/2003	03:00	78.0	22	0.00
6/4/2003	04:00	75.5	28	0.00
6/4/2003	05:00	75.1	32	0.00
6/4/2003	06:00	74.3	34	0.00
6/4/2003	07:00	77.1	32	0.00

TABLE B-1 (CONT'D)

	Weath	er Data from Yun	na Proving Gr	ound
	Time,	Average	Relative	Precipitation,
Date	EDST	Temperature, °F	Humidity, %	in.
6/4/2003	08:00	82.1	27	0.00
6/4/2003	09:00	87.3	22	0.00
6/4/2003	10:00	89.9	19	0.00
6/4/2003	11:00	93.9	15	0.00
6/4/2003	12:00	95.8	14	0.00
6/4/2003	13:00	98.5	13	0.00
6/4/2003	14:00	100.8	12	0.00
6/4/2003	15:00	102.5	12	0.00
6/4/2003	16:00	103.5	11	0.00
6/4/2003	17:00	103.4	10	0.00
6/4/2003	18:00	102.5	10	0.00
6/4/2003	19:00	100.0	10	0.00
6/4/2003	20:00	96.6	11	0.00
6/4/2003	21:00	94.1	11	0.00
6/4/2003	22:00	90.9	12	0.00
6/4/2003	23:00	86.7	14	0.00
6/4/2003	24:00	84.1	16	0.00

APPENDIX C. SOIL MOISTURE

SOIL MOISTURE LOGS (6 through 17, 19 through 22, and 28 through 30 May 2003)

Date	Time			bratio ading			Time			ogul A			Time]		Extre	eme Ar	ea
		0 to		12 to		36 to		0 to		12 to		36 to			6 to	0.000	24 to	36 to
	0=10			24 in.	36 in.	48 in.		6 in.		24 in.	_	48 in.			12 in.	24 in.		48 in.
5/6/2003	0748	1.8	2.2	3.7	3.6	4.0	0807	1.7	2.0	3.4	4.0	4.1	800	1.7	2.0	3.5	3.9	4.0
<i>E 17 1</i> 0003	1237	1.8	2.2	3.6	3.6	4.0	1246	1.6	2.0	3.6	3.9	4.0	1254	1.7	2.0	3.4	3.9	4.1
5/7/2003	0723	1.8	2.2	3.6	3.6	3.9	0740	1.6	2.0	3.6	3.9	3.9	733	1.7	2.0	3.4	3.9	4.1
T 10 10 000	1255	1.8	2.2	3.7	3.6	4.0	1310	1.6	2.0	3.5	3.9	4.0	1305	1.7	2.0	3.4	3.9	4.1
5/8/2003	0715	1.8	2.2	3.6	3.6	3.9	0724	1.6	2.0	3.6	4.0	3.9	732	1.7	2.0	3.4	3.9	4.1
	1243	1.8	2.2	3.7	3.6	3.9	1250	1.6	2.0	3.5	4.0	4.0	1258	1.7	2.0	3.4	3.9	4.1
5/9/2003	0623	1.8	2.2	3.6	3.6	3.9	0638	1.6	2.0	3.5	3.9	3.9	631	1.7	2.0	3.4	3.9	4.1
	1306	1.8	2.2	3.6	3.6	3.9	1315	1.6	2.0	3.5	3.9	3.9	1324	1.7	2.0	3.4	3.9	4.1
5/10/2003	0618	1.8	2.2	3.7	3.6	3.9	0626	1.6	2.0	3.5	3.9	4.0	634	1.7	2.0	3.4	3.9	4.1
	1203	1.8	2.2	3.6	3.6	3.9	1212	1.6	2.0	3.6	3.9	4.0	1221	1.7	2.0	3.4	3.9	4.1
5/12/2003	0630	1.8	2.2	3.7	3.6	3.9	0638	1.6	2.0	3.6	3.9	4.0	644	1.7	2.0	3.4	3.9	4.1
	1256	1.8	2.2	3.6	3.6	3.9	1305	1.6	2.0	3.5	3.9	4.0	1313	1.7	2.0	3.4	3.9	4.1
5/13/2003	0711	1.8	2.2	3.6	3.6	3.9	0719	1.7	2.0	3.6	3.9	4.0	726	1.7	2.0	3.4	3.9	4.1
	1312	1.8	2.2	3.7	3.6	4.0	1323	1.6	2.0	3.6	3.9	4.0	1332	1.7	2.0	3.4	3.9	4.1
5/14/2003	0630	1.8	2.2	3.7	3.6	4.0	0639	1.7	2.0	3.6	3.9	4.0	647	1.7	2.0	3.4	3.9	4.1
	1302	1.8	2.2	3.7	3.6	3.9	1312	1.7	2.0	3.6	4.0	4.0	1318	1.7	2.0	3.4	3.9	4.1
5/15/2003	0626	1.8	2.2	3.6	3.6	3.9	0640	1.7	2.0	3.6	3.9	4.0	648	1.7	2.0	3.4	3.9	4.1
	1302	1.8	2.2	3.7	3.6	4.0	1310	1.6	2.0	3.6	4.0	4.0	1318	1.7	2.0	3.4	3.9	4.1
5/16/2003	0622	1.8	2.2	3.7	3.6	3.9	0629	1.7	2.0	3.6	4.0	4.0	0637	1.7	2.0	3.4	3.9	4.1
	1250	1.8	2.2	3.6	3.6	3.9	1258	1.6	2.0	3.5	3.9	4.0	1305	1.7	2.0	3.4	3.9	4.1
5/17/2003	0610	1.8	2.2	3.7	3.6	3.9	0618	1.6	2.0	3.6	3.9	4.0	0626	1.7	2.0	3.4	3.9	4.1
	1319	1.8	2.2	3.6	3.6	4.0	1327	1.6	2.0	3.6	3.9	4.0	1334	1.7	2.0	3.4	3.9	4.1
5/19/2003	0600	1.8	2.2	3.6	3.6	4.0	0608	1.6	1.9	3.6	3.9	4.0	0615	1.7	2.0	3.4	4.0	4.1
	1306	1.8	2.2	3.7	3.6	4.0	1316	1.6	2.0	3.6	3.9	4.0	1324	1.7	2.0	3.4	4.0	4.1
5/20/2003	0534	1.8	2.2	3.7	3.6	4.0	0542	1.6	2.0	3.6	3.9	4.0	0550	1.7	2.0	3.4	3.9	4.1
3	1311	1.8	2.2	3.7	3.6	4.0	1320	1.6	2.0	3.6	3.9	4.0	1326	1.7	2.0	3.4	4.0	4.1
5/21/2003	0547	1.8	2.2	3.7	3.6	4.0	0555	1.6	2.0	3.6	4.0	4.1	0603	1.7	2.0	3.4	4.0	4.1
	1301	1.8	2.2	3.7	3.6	4.0	1309	1.6	2.0	3.6	4.0	4.0	1316	1.7	2.0	3.4	4.0	4.1
5/22/2003	0535	1.8	2.2	3.7	3.6	4.0	0543	1.6	2.0	3.6	4.0	4.0	0550	1.7	2.0	3.4	4.0	4.1
	1303	1.8	2.2	3.7	3.6	4.0	1311	1.6	2.0	3.6	4.0	4.0	1318	1.7	2.0	3.4	4.0	4.1
5/28/2003	0722	1.8	2.2	3.7	3.6	4.0	0730	1.6	2.0	3.6	4.0	4.0	0743	1.7	2.0	3.4	4.0	4.1
	1210	1.8	2.2	3.7	3.6	4.0	1218	1.6	2.0	3.6	4.0	4.0	1225	1.7	2.0	3.4	4.0	4.1
5/29/2003	0645	1.8	2.2	3.7	3.6	4.0	0653	1.6	2.0	3.6	4.0	4.0	0700	1.7	2.0	3.4	4.0	4.1
	1222	1.8	2.2	3.7	3.6	4.0	1230	1.6	2.0	3.6	4.0	4.0	1237	1.7	2.0	3.4	4.0	4.1
5/30/2003	0600	1.8	2.2	3.7	3.6	4.0	0609	1.6	2.0	3.6	4.0	4.0	0616	1.7	2.0	3.4	4.0	4.1
	1239	1.8	2.2	3.7	3.6	4.0	1248	1.6	2.0	3.6	4.0	4.0	1255	1.7	2.0	3.4	4.0	4.1

APPENDIX D. DAILY ACTIVITY LOGS

	ions	DRY	NDV	INC	DRY	DRY	DRY	DRY		DRY		DRY	DRY		DRY	DRY		DRY		DRY		DRY	DRY
	Field Conditions	HOT	HOT	IOU I	HOT	HOT	HOT	HOT		HOT		HOT	HOT		HOT	HOT		HOT		HOT		HOT	HOT
	Pattern	NA	MA	WAT	Y _Z	AN	AN	AN		AN		Y Y	AZ		NA	AN		AN		N.		NA	NA
Track	Track Method=Other	NA	MA	UNI	A	NA	NA	AN		NA		NA	NA		NA	AN		NA		NA		NA	NA
	Track	NA	VIV	CAL	NA	AN	CPS	NA		GPS		GPS	NA		CPS	AN		GPS		GPS		GPS	GPS
_	Operational Status -		LINCH	CONCIL	SETTING UP EQUIPMENT	BREAKING DOWN EQUIPMENT EOD	SETTING UP	RUNNING CAL LANE,	BI DIRECTION, NORTH/SOUTH	CHECKING/	DOWNLOADING DATA	RUNNING CAL LANE BI DIRECTION EAST/WEST	CHECKING/	DOWNLOADING DATA	LUNCH	CHECKING/	DOWNLOADING DATA	RUNNING BTG,	BIDIRECTION EAST/WEST	CHECKING/ DOWNLOADING DATA		SETTING UP EQUIPMENT	COLLECT DATA OVER PIT
	Onerational Status	SET UP/MOBILIZATION	BBEAKTINCH	DNEAMEDIACII	SET UP/MOBILIZATION	SET UP/MOBILIZATION	SET UP/MOBILIZATION	COLLECTING DATA		DOWNTIME DUE TO	EQUIPMENT MAINTENANCE/CHECK	COLLECTING DATA	DOWNTIME DUE TO	EQUIPMENT MAINTENANCE/CHECK	BREAK/LUNCH	DOWNTIME DUE TO	EQUIPMENT MAINTENANCE/CHECK	COLLECTING DATA		DOWNTIME DUE TO EQUIPMENT	MAINTENANCE/CHECK	SET UP/MOBILIZATION	COLLECTING DATA
	Duration,	30	31	C	270	30	45	09		75		<mark>30</mark>	20		30	30		75		35	ļ.	20	25
	Stop	1045	1100	3	1530	1600	0815	0915		1030		1120	1140		1210	1240		1355		1430		1450	1515
Status Status	Start	1015	1045		1100	1530	0730	0815		0915		1030	1120		1140	1210		1240		1355	lle.	1430	1450
	Area Tested		INTIAL SETTIE	THE SELECT	INTIAL SETUP	INITIAL SETUP	INITIAL SETUP	CALIBRATION	LANES	CALIBRATION	LANES	CALIBRATION LANES	CALIBRATION	LANES	CALIBRATION	CALIBRATION	LANES	BLIND TEST	GRID	BLIND TEST GRID		CALIBRATION PIT	CALIBRATION PIT
No.	of People		A		4	4	S	S		5		N N	5		2	5		5		5		5	5
	Date	3	5/5/2003	20071010	5/5/2003	5/5/2003	5/6/2003	5/6/2003		5/6/2003		5/6/2003	5/6/2003		5/6/2003	5/6/2003		5/6/2003		5/6/2003		5/6/2003	5/6/2003

Note: Activities pertinent to this specific demonstration are indicated in highlighted text.

	ditions	DRY		DRY	DRY	Y DRY	Y DRY	/ DRY	/ DRY	/ NRY		-						
	Field Conditions	HOT		HOT	HOT	COOLWINDY	COOL/WINDY	HOT/WINDY	HOT/WINDY	HOT/WINDY		HOT/WINDY	HOT/WINDY	HOT/WINDY HOT/WINDY HOT/WINDY	HOT/WINDY HOT/WINDY HOT/WINDY	HOT/WINDY HOT/WINDY HOT/WINDY HOT/WINDY	HOT/WINDY HOT/WINDY HOT/WINDY HOT/WINDY	HOT/WINDY HOT/WINDY HOT/WINDY HOT/WINDY COOL/WINDY
	Pattern	NA		NA	NA	NA	NA	NA A	NA	AN	•	NA	AN AN	NA NA NA	N N N N N	N N N N N N	A N N N N N N N N N N N N N N N N N N N	NA N
Track	Method=Other Explain	NA		NA.	NA	NA	NA	NA	NA	AZ	CH	AN AN	AN AN	NA N	A A A A A	A A A A A A A A	N N N N N N N N N N N N N N N N N N N	AN A
_	Track	GPS		GPS	AN	NA	GPS	GPS	GPS	Sdy	5	GPS GPS	GPS GPS	GPS GPS	GPS GPS GPS GPS	GPS AA AA GPS GB	GPS GPS GPS GPS	GPS
	Operational Status -	T	BATTERY	COLLECT DATA OVER PIT	BREAKING DOWN EQUIPMENT EOD	SETTING UP EQUIPMENT	RUNNING OPEN RANGE, GRID A2, BIDIRECTIONAL EW	CHECKING/ DOWNLOADING DATA	SETTING UP EQUIPMENT	RUNNING OPEN	RANGE, GRID A3, BIDIRECTIONAL EW	RANGE, GRID A3, BIDIRECTIONAL E/W CHECKING/ DOWNLOADING DATA	RANGE, GRID A3, BIDIRECTIONAL E/W CHECKING/ DOWNLOADING DATA BREAK	RANGE, GRID A3, BIDIRECTIONAL E/W CHECKING/ DOWNLOADING DATA BREAK SETTING UP EQUIPMENT	RANGE, GRID A3, BIDIRECTIONAL E/W CHECKING/ DOWNLOADING DATA BREAK SETTING UP EQUIPMENT RUNNING OPEN RANGE GRID G2, BIDIRECTIONAL E/W	RANGE, GRID A3, BIDIRECTIONAL E/W CHECKING/ DOWNLOADING DATA BREAK SETTING UP EQUIPMENT RUNNING OPEN RANGE GRID G2, BIDIRECTIONAL E/W CHECKING/ DOWNLOADING DATA	RANGE, GRID A3, BIDIRECTIONAL E/W CHECKING/ DOWNLOADING DATA BREAK SETTING UP EQUIPMENT RUNNING OPEN RANGE GRID G2, BIDIRECTIONAL E/W CHECKING/ DOWNLOADING DATA	RANGE, GRID A3, BIDIRECTIONAL E/W CHECKING/ DOWNLOADING DATA BREAK SETTING UP EQUIPMENT RUNNING OPEN RANGE GRID G2, BIDIRECTIONAL E/W CHECKING/ DOWNLOADING DATA BREAKING DOWN EQUIPMENT EOD SETTING UP EQUIPMENT EOD SETTING UP
	Operational Status	DOWNTIME DUE TO	EQUIPMENT MAINTENANCE/CHECK	COLLECTING DATA	SET UP/MOBILIZATION	SET UP/MOBILIZATION	COLLECTING DATA	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	SET UP/MOBILIZATION	COLLECTING DATA		DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK BREAK/LUNCH	DOWNTIME DUE TO EQUIPMENT MAINTENANCECHECK BREAKLUNCH SET UPMOBILIZATION	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK BREAK/LUNCH SET UP/MOBILIZATION COLLECTING DATA	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK BREAK/LUNCH SET UP/MOBILIZATION COLLECTING DATA COLLECTING DUE TO EQUIPMENT MAINTENANCE/CHECK	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK BREAK/LUNCH SET UP/MOBILIZATION COLLECTING DATA COLLECTING DUE TO EQUIPMENT MAINTENANCE/CHECK SET UP/MOBILIZATION	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK BREAK/LUNCH SET UP/MOBILIZATION COLLECTING DATA COLLECTING DUE TO EQUIPMENT MAINTENANCE/CHECK SET UP/MOBILIZATION SET UP/MOBILIZATION
	Duration,	5		S	10	100	001	40	10	95		30	30	30 20 10	30 20 10 90	30 20 20 20 20 20 20 20 20	30 20 20 20 10 10 10	30 20 20 90 10 45
Status	Stop			1525	1535	0855	1035	1115	1125	1300		1330	1330	1330 1350 1400	1330 1350 1400 1530	1330 1350 1400 1530	1330 1350 1400 1530 1550	1330 1350 1400 1530 1550 1600
Status	Start	1515		1520	1525	0715	0855	1035	1115	1125		1300	1300	1300 1330 1350	1300 1330 1350 1400	1300 1330 1350 1400 1530	1300 1330 1400 1530	1300 1350 1400 1530 1550
	Area Tested	S	PIT	CALIBRATION PIT	CALIBRATION PIT	OPEN RANGE	OPEN RANGE	OPEN RANGE	OPEN RANGE	OPEN RANGE		OPEN RANGE	OPEN RANGE	OPEN RANGE OPEN RANGE OPEN RANGE	OPEN RANGE OPEN RANGE OPEN RANGE	OPEN RANGE OPEN RANGE OPEN RANGE OPEN RANGE	OPEN RANGE OPEN RANGE OPEN RANGE OPEN RANGE	OPEN RANGE OPEN RANGE OPEN RANGE OPEN RANGE OPEN RANGE
No.	of People	S		5	5	4	4	4	4	4		4	4 4	4 4 4	4 4 4	4 4 4 4	4 4 4 4 4	4 4 4 4 4 0
	Date	5/6/2003		5/6/2003	5/6/2003	5/7/2003	5/7/2003	5/7/2003	5/7/2003	5/7/2003		5/7/2003	5/7/2003	5/7/2003 5/7/2003 5/7/2003	5/7/2003 5/7/2003 5/7/2003 5/7/2003	5/7/2003 5/7/2003 5/7/2003 5/7/2003	5/7/2003 5/7/2003 5/7/2003 5/7/2003	5/7/2003 5/7/2003 5/7/2003 5/7/2003 5/7/2003 5/7/2003

3		Status	Status Status					Track			
of People Area Tested		Start	Stop Time	Duration,	Operational Status	Operational Status - Comments	Track Method	Method=Other Explain	Pattern	Field Conditions	ons
0	[77]	0620		30	DOWNTIME DUE TO		GPS	AN	NA	COOLWINDY	DRY
					EQUIPMENT MAINTENANCE/CHECK	DOWNLOADING DATA					
BLIND TEST GRID	_	1020	1130	70	COLLECTING DATA	RUNNING BTG BIDIRECTIONAL NORTH/SOUTH	GPS	NA	NA	HOT/WINDY	DRY
BLIND TEST GRID		1130	1145	15	DOWNTIME DUE TO EOUIPMENT	CHECKING/ DOWNLOADING DATA	GPS	AN	NA	HOT/WINDY	DRY
	ł				MAINTENANCE/CHECK						
BLIND TEST GRID	۲.	1145	1215	30	BREAK/LUNCH	LUNCH	GPS	NA	NA	HOT/WINDY	DRY
OPEN RANGE	E	1215	1300	45	SET UP/MOBILIZATION	LAYOUT LANES WITH ROPE	NA	NA	NA	HOT/WINDY	DRY
CALIBRATION PIT	Z	1300	1440	001	COLLECTING DATA	COLLECT DATA OVER PIT	GPS	NA	NA	HOT/WINDY	DRY
CALIBRATION PIT	Z	1440	1500	02	BREAK/LUNCH	BREAK	NA	AN	NA	HOT/WINDY	DRY
OPEN RANGE	3E	1500	1550	50	SET UP/MOBILIZATION	LAYOUT LANES WITH ROPE	NA	AN	NA	HOT/WINDY	DRY
OPEN RANGE	GE	1550	0091	10	SET UP/MOBILIZATION	BREAKING DOWN EQUIPMENT EOD	NA	NA	NA	HOT/WINDY	DRY
OPEN RANGE	GE	0645	0720	35	SET UP/MOBILIZATION	SETTING UP EQUIPMENT	NA	NA	NA	T000	DRY
OPEN RANGE	GE	0720	0845	82	COLLECTING DATA	RUNNING OPEN RANGE, GRID F2,F3,F4,F5 BIDIRECTIONAL F/W	GPS	NA	LINEAR	LINEAR COOL/WINDY	DRY
OPEN RANGE	GE	0845	5060	20	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	AN	COOLWINDY	DRY
OPEN RANGE	GE	0905	1030	82	COLLECTING DATA	RUNNING OPEN RANGE, GRID F2,F3,F4,F5 BIDIRECTIONAL E/W	CPS	NA	LINEAR	COOLWINDY	DRY
OPEN RANGE	{GE	1030	1100	30	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	A'A	NA	COOL/WINDY	DRY
OPEN RANGE	GE	1100	1130	30	BREAK/LUNCH	LUNCH	AN	NA	NA	COOLWINDY	DRY

	No.		Status	Status					Track			
	of		Start	Stop	Duration,		Operational Status -	Track	Track Method=Other			
-	People		Time	Time	min	Operational Status	Comments	Method	Explain	Pattern	Field Conditions	ions
5/9/2003	4	OPEN RANGE	1130	1250	08	COLLECTING DATA	RUNNING OPEN	GPS	NA	LINEAR	HOT/WINDY	DRY
							RANGE, GRID					
							F2,F3,F4,F5 BIDIRECTIONAL E/W					
5/9/2003	4	OPEN RANGE	1250	1300	10	DOWNTIME DUE TO	CHANGE OUT	GPS	NA	N.A.	HOT/WINDY	DRY
						EQUIPMENT	PROCESSOR UNIT					
						MAINTENANCE/CHECK						
5/9/2003	S	OPEN RANGE	1300	1330	30	COLLECTING DATA	RUNNING OPEN	GPS	NA VA	LINEAR	HOT/WINDY	DRY
							RANGE, GRID					
							PLY,F3,F4,F3					
5/9/2003	5	OPEN RANGE	1330	1430	09	DOWNTIME DUE TO	CHECKING/	GPS	NA A	AN	HOT/WINDY	DRY
	ē.					EQUIPMENT	DOWNLOADING					
						MAINTENANCE/CHECK	DATA					
5/9/2003	5	OPEN RANGE	1430	1445	15	COLLECTING DATA	RUNNING OPEN	GPS	NA	LINEAR	HOT/WINDY	DRY
							RANGE, GRID					
							F2,F3,F4,F5					
							BIDIRECTIONAL EW					
5/9/2003	'n	OPEN RANGE	1445	1500	15	DOWNTIME DUE TO	CHANGE OUT	GPS	NA	NA	HOT/WINDY	DRY
						EQUIPMENT	BATTERY					
				_		MAINTENANCE/CHECK			3		2	
5/9/2003	2	OPEN RANGE	1500	1520	20	COLLECTING DATA	RUNNING OPEN RANGE, GRID	GPS	NA	LINEAR	HOT/WINDY	DRY
				A 20			F2,F3,F4,F5					
							BIDIRECTIONAL E/W					
5/9/2003	5	OPEN RANGE	1520	1540	20	SET UP/MOBILIZATION	BREAKING DOWN	N.	NA	AN	HOT/WINDY	DRY
5/10/2003	S	OPEN RANGE	0630	0020	30	SET UP/MOBILIZATION	SETTING UP	X	AN	AZ	COOL	DRY
							EQUIPMENT					
5/10/2003	2	OPEN RANGE	0020	0826	98	COLLECTING DATA	RUNNING OPEN	GPS	NA	LINEAR	T000	DRY
				0.00			RANGE, GRID					
							BIDIRECTIONAL EW					
5/10/2003	5	OPEN RANGE	0826	0828	2	DOWNTIME DUE TO	SWAPPED OUT FIELD	GPS	AN	LINEAR	T000	DRY
		7001				MAINTENANCE/CHECK	COMPUTER					
5/10/2003	5	OPEN RANGE	0828	1015	107	COLLECTING DATA	RUNNING OPEN	GPS	AN	LINEAR	HOT	DRY
							RANGE, GRID F2 F3 F4 F5			Ann A		
							BIDIRECTIONAL EW					

Date Pe 5/10/2003 5/10/2003 5/10/2003	•			-					Track			
	o		Start	Stop	Duration,		Operational Status -		Method=Other			
5/10/2003 5/10/2003 5/10/2003	People			Time	min	Operational Status	S	Method	Explain	Pattern	Field Conditions	tions
5/10/2003	5	OPEN RANGE	1015	1040	25	BREAK/LUNCH	LUNCH	NA	NA	NA	HOT	DRY
5/10/2003	2	OPEN RANGE	1040	1100	20	DOWNTIME DUE TO	CHECKING/	GPS	NA	NA	HOT	DRY
5/10/2003						EQUIPMENT	DOWNLOADING			_		
5/10/2003	- 2					MAINTENANCE/CHECK	DATA					
	4	OPEN RANGE	1100	1243	103	COLLECTING DATA	RUNNING	GPS	A'A	LINEAR	HOT	DRY
	_						OPENRANGE, GRID					
							E2,E3,E4,E5					
							BIDIRECTIONAL E/W					
5/10/2003	4	OPEN RANGE	1243	1246	3	DOWNTIME DUE TO	CHANGE OUT	GPS	NA	Ϋ́Z	HOT	DRY
						EQUIPMENT	PROCESSOR UNIT					
				-		MAINTENANCE/CHECK						
5/10/2003	4	OPEN RANGE	1246	1340	54	COLLECTING DATA	RUNNING OPEN	GPS	NA	LINEAR	HOT	DRY
					-		RANGE, GRID					
							E2,E3,E4,E5					
					1		BIDIRECTIONAL E/W					
5/10/2003	4	OPEN RANGE	1340	1400	20	SET UP/MOBILIZATION	BREAKING DOWN	GPS	NA	NA	HOT	DRY
							EQUIPMENT EOD					
5/12/2003	5	OPEN RANGE	00/0	0721	21	SET UP/MOBILIZATION	SETTING UP	GPS	AN	NA	HOT	DRY
							EQUIPMENT					
5/12/2003	5	OPEN RANGE	0721	0725	4	COLLECTING DATA	EQUIPMENT WAS	GPS	NA	NA	HOT	DRY
							CALIBRATED USING					
							CAL BALL					
5/12/2003	5	OPEN RANGE	0725	0825	09	COLLECTING DATA	RUNNING OPEN	GPS	NA	LINEAR	HOT	DRY
							RANGE, GRID					
							E2,E3,E4,E5	0				
0000	,			1000			BIDINEC HORAL EW	0				3
5/12/2003	S	OPEN RANGE	0825	0935	- 05	DOWNTIME DUE TO	CHECKING/	GPS	A'A	Y Z	HOT	DRY
						MAINTENANCEICHECE	DOWNLOADING					
5/12/2003	٧.	OPEN RANGE	0935	1005	20	COLLECTING DATA	RI INNING OPEN	GPS	AN	LINEAR	HOT	DRY
	1)		RANGE GRID 44.45)		i		
							BIDIRECTIONAL EW					
5/12/2003	S	OPEN RANGE	1025	1030	S	DOWNTIME DUE TO	CHECKING/	CPS	AN	NA	HOT	DRY
						EQUIPMENT	DOWNLOADING					
		100				MAINTENANCE/CHECK	DATA					
5/12/2003	2	OPEN RANGE	1030	1325	175	DOWNTIME DUE TO	WHEEL AXLE BROKE	NA	AN	NA	HOT	DRY
-	1					EQUIPMENT FAILURE						
5/12/2003	S	OPEN RANGE	1325	1330	S	SET UP/MOBILIZATION	BREAKING DOWN	A V	AN	Z Z	HOT	DRY
							EQUIPMENT EOD					

	No.		Status Status	Status					Track			
	Jo		Start		Duration,		Operational Status -	Track	Track Method=Other			
Date	People	Area Tested	Time	Time	min	Operational Status	Comments	Method	Explain	Pattern	Field Conditions	tions
5/13/2003	4	OPEN RANGE	1130	1215	45	SET UP/MOBILIZATION	SETTING UP	GPS	NA	AN	HOT	DRY
5/13/2003	4	OPEN RANGE	1215	1300	45	COLLECTING DATA	RUNNING OPEN RANGE, A4,A5 BIDIRECTIONAL F/W	GPS	NA	LINEAR	HOT	DRY
5/13/2003	4	OPEN RANGE	1300	1320	20	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	A'N	NA	HOT	DRY
5/13/2003	4	OPEN RANGE	1320	1430	70	COLLECTING DATA	RUNNING OPEN RANGE, A4,A5 BIDIRECTIONAL E/W	GPS	AN	LINEAR	HOT	DRY
5/13/2003	4	OPEN RANGE	1430	1447	17	BREAK/LUNCH	BREAK	NA	NA	AN	HOT	DRY
5/13/2003	4	OPEN RANGE	1447	1535	48	COLLECTING DATA	RUNNING OPEN RANGE, A4,A5 BIDIRECTIONAL E/W	A A	AN	LINEAR	HOT	DRY
5/13/2003	4	OPEN RANGE	1535	1545	10	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	A'A	HOT	DRY
5/13/2003	4	OPEN RANGE	1545	1600	15	SET UP/MOBILIZATION	BREAKING DOWN EQUIPMENT EOD	NA	NA	AN	HOT	DRY
5/14/2003	5	OPEN RANGE	0630	0735	65	SET UP/MOBILIZATION	SETTING UP EQUIPMENT	NA	NA	NA	WARM	HUMID
5/14/2003	v	OPEN RANGE	0735	0739	4	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL BALL	GPS	NA	LINEAR	WARM	HUMID
5/14/2003	8	OPEN RANGE	0739	0820	17	COLLECTING DATA	RUNNING OPEN RANGE, A4,A5 BIDIRECTIONAL EW	GPS	NA	LINEAR	WARM	HUMID
5/14/2003	8	OPEN RANGE	0820	0920	30	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	WARM	HUMID
5/14/2003	ς.	OPEN RANGE	0920	1020	09	COLLECTING DATA	RUNNING OPEN RANGE, D4,D5 BIDIRECTIONAL E/W	GPS	NA	LINEAR	WARM	HUMID
5/14/2003	'n	OPEN RANGE	1020	1035	15	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	AN	WARM	HUMID
5/14/2003	S	OPEN RANGE	1035	1130	55	BREAK/LUNCH	LUNCH	AN	NA	NA	WARM	HUMID

	No.		Status	Status Status					Track			
	of		Start	_	Duration,	7.70	Operational Status -	Track	Track Method=Other	ŕ		
5/14/2003	reopie	OPEN RANGE	1130	1325	115	COLI ECTING DATA	RI INNING OPEN	GPS	Explain	I INFAR	WARM HID	HIMID
	(}		RANGE, D4,D5 BIDIRECTIONAL E/W) ;				
5/14/2003	S	OPEN RANGE	1325	1400	35	DOWNTIME DUE TO EQUIPMENT	CHECKING/ DOWNLOADING	GPS	NA	NA	WARM	HUMID
5/14/2003	5	OPEN RANGE	1400	1430	30	BREAKLUNCH	BREAK	N.A.	AN	N.	WARM	HUMID
5/14/2003	S	OPEN RANGE	1430	1530	120	COLLECTING DATA	RUNNING OPEN	GPS	NA	LINEAR	WARM	HUMID
							RANGE, D4,D5 BIDIRECTIONAL E/W					
5/14/2003	5	OPEN RANGE	1530	1600	30	SET UP/MOBILIZATION	BREAKING DOWN EQUIPMENT EOD	NA	NA	AN AN	WARM	HUMID
5/15/2003	2	OPEN RANGE	0645	0110	25	SET UP/MOBILIZATION	SETTING UP EQUIPMENT	NA	NA	NA	T000	DRY
5/15/2003	2	OPEN RANGE	07.10	0735	25	COLLECTING DATA	RUNNING OPEN	GPS	NA	LINEAR	COOL	DRY
			ŀ				RANGE, B2,B3 BIDIRECTIONAL E/W					
5/15/2003	5	OPEN RANGE	0735	0742	7	DOWNTIME DUE TO	CHECKING/	GPS	NA	AN A	T000	DRY
						MAINTENANCE/CHECK	DATA					
5/15/2003	5	OPEN RANGE	0742	0750	∞	COLLECTING DATA	RUNNING OPEN	GPS	AN	LINEAR	COOL	DRY
							RANGE, B2,B3 BIDIRECTIONAL E/W					
5/15/2003	S	OPEN RANGE	0750	0755	S	DOWNTIME DUE TO EQUIPMENT FAILURE	GPS DOWN	GPS	AN	NA A	7000	DRY
5/15/2003	5	OPEN RANGE	0755	0925	06	COLLECTING DATA	RUNNING OPEN RANGE. B2.B3	GPS	NA	LINEAR	T000	DRY
			-400				BIDIRECTIONAL EW					
5/15/2003	S	OPEN RANGE	0925	0945	20	DOWNTIME DUE TO	CHECKING/	GPS	AN	NA	T000	DRY
						EQUIPMENT MAINTENANCE/CHECK	DOWNLOADING					
5/15/2003	S	OPEN RANGE	0945	1140	115	COLLECTING DATA	RUNNING OPEN	GPS	NA	LINEAR	HOT	DRY
							RANGE, B2,B3 BIDIRECTIONAL E/W					
5/15/2003	2	OPEN RANGE	1140	1150	10	DOWNTIME DUE TO	CHECKING/	GPS	NA	AN	HOT	DRY
						MAINTENANCE/CHECK	DOWNLOADING					
5/15/2003	5	OPEN RANGE	1150	1250	09	BREAK/LUNCH	CHOW	NA	NA	NA	HOT	DRY

Columents Colu		Z		Chotre	Chatric					Twook			
Propries Area Tested Time Tim		of		Start		Duration.		Operational Status -	Track	Method=Other			
5 OPEN RANGE 1250 125 SET UPMOBILIZATION RUNNING OPEN NA NA NA 5 OPEN RANGE 1251 1320 25 COLLECTING DATA RUNNING OPEN GPS NA LINBAR 5 OPEN RANGE 1320 132 5 DOWNTING DUE TO COMMUNICATION GPS NA LINBAR 5 OPEN RANGE 1325 130 5 DOWNTING DUE TO COMMUNICATION GPS NA NA 5 OPEN RANGE 1320 130 5 DOWNTING DUE TO CHANGE OLF FIELD GPS NA LINBAR 5 OPEN RANGE 130 130 120 COLLECTING DATA RUNNING OPEN GPS NA LINBAR 4 OPEN RANGE 150 150 SET UPMOBILIZATION BIDIRECTING LEW PNA LINBAR 4 OPEN RANGE 1050 30 SET UPMOBILIZATION BUDWATUNG OPEN PNA LINBAR 4 OPEN RANGE 1050		People		Time	Time	min	Operational Status	Comments	Method	Explain		Field Cond	itions
5 OPEN RANGE 1255 1320 25 COLLECTING DATA RANNEC C4C5 NA LINEAR 5 OPEN RANGE 1320 1325 5 DOWNTIME DUE TO COMPUTOR GPS NA INA 5 OPEN RANGE 1320 1330 15 DOWNTIME DUE TO COMPUTORS NA NA NA 5 OPEN RANGE 1330 130 COLLECTING DATA RUNNING OPEN GPS NA NA NA 4 OPEN RANGE 1330 150 COLLECTING DATA RUNNING OPEN GPS NA NA NA 4 OPEN RANGE 640 655 15 SET UPMOBILIZATION BRAKENDO DWN NA NA NA 4 OPEN RANGE 640 655 15 SET UPMOBILIZATION SETTING UPW NA NA NA 4 OPEN RANGE 665 670 5 COLLECTING DATA RUNNING OPEN GPS NA NA 4 OPEN		5		1250	1255	5	SET UP/MOBILIZATION	SET UP ON C4,C5	AN	NA	NA	HOT	DRY
S	5/15/2003	S	OPEN RANGE	1255	1320	25	COLLECTING DATA	RUNNING OPEN	GPS	NA VA	LINEAR	HOT	DRY
5 OPEN RANGE 1325 5 DOWNTIME DUE TO COMMUNICATION GPS OPEN RANGE NA NA NA 5 OPEN RANGE 1325 1330 5 DOWNTIME DUE TO COMPUTORS NA NA NA NA 5 OPEN RANGE 1330 1530 120 COLLECTING DATA RUNNING OPEN RANGE, C4.C5 NA LINEAR 5 OPEN RANGE 1330 1530 120 COLLECTING DATA RUNNING OPEN NA NA NA 4 OPEN RANGE 0540 055 15 SET UPMOBILIZATION BREAAING OPEN NA NA NA 4 OPEN RANGE 0650 0653 15 SET UPMOBILIZATION SET TING UP NA NA NA 4 OPEN RANGE 0700 5 COLLECTING DATA RUNNING OPEN GPS NA LINEAR 4 OPEN RANGE 0700 10 SET UPMOBILIZATION SET UPOND GPS NA LINEAR 4 OP						-2		RANGE, C4,C5 BIDIRECTIONAL E/W			0.00		
5 OPEN RANGE 1325 1330 5 DOWNTIME DUE TO CHANGE OUT FIELD GPS NA NA	5/15/2003	2	OPEN RANGE	1320	1325	8	DOWNTIME DUE TO EQUIPMENT FAILURE	COMMUNICATION ERROR INFIELD	CPS	A'N	N A	HOT	DRY
SET UPMOBILIZATION PRINTING OPEN RANGE 1330 1330 140 100 1	\$/15/2003	2	OPEN RANGE	1325	1330	٧	DOWNTIME DITE TO	CHANGE OF THE FIFT D	SdS	AN	A'Z	HOT	DRY
S	200710110)	TO TO TO TO	777	1000)	EOUIPMENT	COMPUTORS	5	Ç	¢	1011	
5 OPEN RANGE 1330 120 COLLECTING DATA RUNNING OPEN GPS NA LINEAR 4 OPEN RANGE 6640 6655 15 SET UP/MOBILIZATION BREAKING DOWN NA NA NA 4 OPEN RANGE 6640 6655 15 SET UP/MOBILIZATION EQUIPMENT WAS NA NA NA 4 OPEN RANGE 6640 6655 15 SET UP/MOBILIZATION EQUIPMENT NA NA NA 4 OPEN RANGE 6650 30 5 COLLECTING DATA RUNNING OPEN NA NA NA 4 OPEN RANGE 670 825 85 COLLECTING DATA RUNNING OPEN NA LINEAR 4 OPEN RANGE 6820 95 COLLECTING DATA SET UP/MOBILIZATION SET UP/MOBILIZATION RANGE, DS NA LINEAR 4 OPEN RANGE 6820 110 130 COLLECTING DATA RANGE, DS NA LINEAR 4							MAINTENANCE/CHECK					2.0	
5 OPEN RANGE 1530 1600 30 SET UPMOBILIZATION BRIBECTIONAL E-W NA NA NA 4 OPEN RANGE 6640 0655 15 SET UPMOBILIZATION BREAKING DOWN NA NA NA 4 OPEN RANGE 0650 15 SET UPMOBILIZATION EQUIPMENT EOD NA NA NA 4 OPEN RANGE 0650 700 6825 700 5 COLLECTING DATA EQUIPMENT WAS GPS NA NA 4 OPEN RANGE 0700 0825 85 COLLECTING DATA RUNNING OPEN GPS NA LINEAR 4 OPEN RANGE 0820 0830 25 DOWNTIME DUE TO CHECKING GPS NA LINEAR 4 OPEN RANGE 0820 10 SET UPMOBULZATION SET UP ON DS NA NA NA 4 OPEN RANGE 1110 130 COLLECTING DATA RUNNING OPEN GPS NA LINEAR	5/15/2003	5	OPEN RANGE	1330	1530	120	COLLECTING DATA	RUNNING OPEN	GPS	NA	LINEAR	HOT	DRY
5 OPEN RANGE 1530 1600 30 SET UPMOBILIZATION BREAKING DOWN NA NA <td></td> <td></td> <td></td> <td></td> <td></td> <td>*</td> <td></td> <td>RANGE, C4,C5 BIDIRECTIONAL E/W</td> <td></td> <td>B</td> <td></td> <td></td> <td></td>						*		RANGE, C4,C5 BIDIRECTIONAL E/W		B			
4 OPEN RANGE 6640 6655 15 SET UPMOBILIZATION EQUIPMENT NA NA 4 OPEN RANGE 6655 0700 5 COLLECTING DATA EQUIPMENT WAS GPS NA NA 4 OPEN RANGE 0700 6825 85 COLLECTING DATA RUNNING OPEN GPS NA LINEAR 4 OPEN RANGE 0700 825 85 COLLECTING DATA RUNNING OPEN GPS NA LINEAR 4 OPEN RANGE 0720 825 6850 25 DOWNTIME DUE TO CHECKING GPS NA LINEAR 4 OPEN RANGE 0850 110 130 COLLECTING DATA RUNNING OPEN RANGE, D3 NA LINEAR 4 OPEN RANGE 1110 1125 15 DOWNTIME DUE TO CHECKING GPS NA LINEAR 4 OPEN RANGE 1125 123 70 BREAKLUNCH CHECKING GPS NA LINEAR	5/15/2003	5	OPEN RANGE	1530	1600	30	SET UP/MOBILIZATION	BREAKING DOWN	NA	NA	NA	HOT	DRY
4 OPEN RANGE 6640 6655 15 SET UPMOBILIZATION SETTING UP NA NA NA 4 OPEN RANGE 6655 0700 5 COLLECTING DATA EQUIPMENT ANA NA NA 4 OPEN RANGE 0700 8255 85 COLLECTING DATA RUNNING OPEN GPS NA LINEAR 4 OPEN RANGE 0700 0825 85 COLLECTING DATA RUNNING OPEN GPS NA LINEAR 4 OPEN RANGE 0800 110 130 COLLECTING DATA RUNNING OPEN GPS NA LINEAR 4 OPEN RANGE 1110 130 COLLECTING DATA RUNNING OPEN GPS NA LINEAR 4 OPEN RANGE 1110 1125 15 DOWNTIME DUE TO CHGCWING GPS NA LINEAR 4 OPEN RANGE 1125 123 1330 55 COLLECTING DATA CHGW NA NA LINEAR <								EQUIPMENT EOD					
4 OPEN RANGE 6655 0700 5 COLLECTING DATA EQUIPMENT WAS CALIBRATED USING GPS NA NA 4 OPEN RANGE 072 855 COLLECTING DATA RUNNING OPEN RANGE, C4,C5 GPS NA LINEAR 4 OPEN RANGE 0825 0850 25 DOWNTIME DUE TO BUILD CHECKING CHECKING CHECKING GPS NA NA 4 OPEN RANGE 0850 10 SET UPMOBILIZACHICK MAINTENANCECHECK DATA NA NA NA 4 OPEN RANGE 0850 1110 130 COLLECTING DATA RUNNING OPEN GPS NA LINEAR 4 OPEN RANGE 1110 1125 15 DOWNTIME DUE TO CHECKING GPS NA LINEAR 4 OPEN RANGE 1125 15 DOWNTIME DUE TO CHECKING GPS NA LINEAR 4 OPEN RANGE 1125 130 55 COLLECTING DATA RANDRIGE DATA NA NA NA <td>5/16/2003</td> <td>4</td> <td>OPEN RANGE</td> <td>0640</td> <td>0655</td> <td>15</td> <td>SET UP/MOBILIZATION</td> <td>SETTING UP</td> <td>NA</td> <td>Z</td> <td>AN</td> <td>T000</td> <td>DRY</td>	5/16/2003	4	OPEN RANGE	0640	0655	15	SET UP/MOBILIZATION	SETTING UP	NA	Z	AN	T000	DRY
4 OPEN RANGE 0000 5 COLLECTING DATA EQUIPMENT WAS GPS NA NA 4 OPEN RANGE 0700 0825 85 COLLECTING DATA RUNNING OPEN GPS NA LINEAR 4 OPEN RANGE 0820 25 DOWNTIME DUE TO CHECKINGL GPS NA NA NA 4 OPEN RANGE 0820 10 SET UP/MOBILIZATION SET UP ON D3 NA NA NA 4 OPEN RANGE 0900 10 SET UP/MOBILIZATION SET UP ON D3 NA NA NA 4 OPEN RANGE 0900 110 130 COLLECTING DATA RUNNING OPEN A NA LINEAR 4 OPEN RANGE 1110 1125 15 DOWNTIME DUE TO CHECKINGL GPS NA LINEAR 4 OPEN RANGE 1125 123 70 BREAKLUNCH DOWNLOADING MA NA NA NA 4 OPEN RANGE 1125 1330 55 COLLECTING DATA RANGE, D3 NA LINEAR 4 OPEN	00000			11,00	0000			EQUIFMENT	9	,	į		1
4 OPEN RANGE 0700 0825 85 COLLECTING DATA RUNNING OPEN GPS NA LINEAR 4 OPEN RANGE 0825 850 25 DOWNTIME DUE TO CHECKING/I GPS NA NA 4 OPEN RANGE 0850 10 SET UP/MOBILIZATION SET UP ON D3 NA NA NA 4 OPEN RANGE 0900 110 130 COLLECTING DATA RUNNING OPEN GPS NA NA 4 OPEN RANGE 1110 110 130 COLLECTING DATA RUNNING OPEN GPS NA LINEAR 4 OPEN RANGE 1110 1125 15 DOWNTIME DUE TO CHECKING/I GPS NA LINEAR 4 OPEN RANGE 1110 1125 15 DOWNTIME DUE TO CHECKING/I GPS NA NA NA 4 OPEN RANGE 1125 133 53 COLLECTING DATA RUNNING OPEN GPS NA LINEAR	2/16/2003	4	OPEN KANGE	0655	03/0	ς.	COLLECTING DATA	EQUIPMENT WAS	GPS	Y.	YZ.	COOL	DRY
4 OPEN RANGE 0700 0825 85 COLLECTING DATA RUNNING OPEN GPS NA LINEAR 4 OPEN RANGE 0825 0850 25 DOWNTIME DUE TO CHECKING/I GPS NA NA 4 OPEN RANGE 0820 110 SET UPMOBILIZATION SET UP ON D3 NA NA NA 4 OPEN RANGE 0800 110 SET UPMOBILIZATION SET UP ON D3 NA NA NA 4 OPEN RANGE 0800 1110 130 COLLECTING DATA RUNNING OPEN GPS NA LINEAR 4 OPEN RANGE 1110 1125 125 15 DOWNTIME DUE TO CHECKING/I GPS NA NA NA 4 OPEN RANGE 1112 1235 70 BREAK/LUNCH CHOWN NA NA NA 4 OPEN RANGE 1330 1410 40 BREAK/LUNCH RANGE, D3 NA NA NA 4 OPEN RANGE 1330 1410 40 BREAK/LUNCH NA	5							CALIBRATED USING CAL BALL					
4 OPEN RANGE 0825 0850 25 DOWNTIME DUE TO CHECKING/ CHECKING/ DOWNTORNALOADING GPS NA NA NA 4 OPEN RANGE 0830 10 SET UPMOBILIZATION SET UPMOBILIZATION SET UP ON D3 	5/16/2003	4	OPEN RANGE	00/0	0825	85	COLLECTING DATA	RUNNING OPEN	GPS	NA	LINEAR	COOL	DRY
4 OPEN RANGE 0825 0850 25 DOWNTIME DUE TO CHECKING/ GPS NA NA NA 4 OPEN RANGE 0800 110 SET UPMOBILIZATION SET UP ON D3 NA NA NA 4 OPEN RANGE 0900 1110 130 COLLECTING DATA RUNNING OPEN GPS NA LINEAR 4 OPEN RANGE 1110 1125 15 DOWNTIME DUE TO CHECKING/ GPS NA NA 4 OPEN RANGE 1125 130 55 COLLECTING DATA CHOW NA NA NA 4 OPEN RANGE 1235 1330 55 COLLECTING DATA RUNNING OPEN GPS NA LINEAR 4 OPEN RANGE 1330 1410 40 BREAKLUNCH RANGE, D3 NA NA NA 4 OPEN RANGE 1330 1410 40 BREAKLUNCH RANGE, D3 NA NA NA						•		RANGE, C4,C5 BIDIRECTIONAL E/W					
4 OPEN RANGE 0850 0900 10 SET UPMOBILIZATION SET UP ON D3 NA NA NA 4 OPEN RANGE 0900 110 130 COLLECTING DATA RUNNING OPEN GPS NA LINEAR 4 OPEN RANGE 1110 1125 15 DOWNTIME DUE TO CHECKING/ CHECKING/ DOWNLOADING GPS NA NA NA 4 OPEN RANGE 1125 1235 70 BREAK/LUNCH CHOW NA NA NA 4 OPEN RANGE 1235 1330 55 COLLECTING DATA RUNNING OPEN GPS NA LINEAR 4 OPEN RANGE 1235 130 55 COLLECTING DATA RANGE, D3 NA LINEAR 4 OPEN RANGE 1330 1410 40 BREAK/LUNCH BREAK/LUNCH NA NA NA	5/16/2003	4	OPEN RANGE	0825	0880	25	DOWNTIME DUE TO	CHECKING/	GPS	AN	NA	T000	DRY
4 OPEN RANGE 0850 100 SET UP/MOBILIZATION SET UP ON D3 NA NA NA INA NA INA NA INA INA <t< td=""><td></td><td></td><td></td><td></td><td></td><td></td><td>EQUIPMENT MAINTENANCE/CHECK</td><td>DOWNLOADING DATA</td><td></td><td></td><td></td><td></td><td></td></t<>							EQUIPMENT MAINTENANCE/CHECK	DOWNLOADING DATA					
4 OPEN RANGE 0900 1110 130 COLLECTING DATA RUNNING OPEN GPS NA LINEAR 4 OPEN RANGE 1110 1125 15 DOWNTIME DUE TO CHECKING/ DOWNLOADING GPS NA NA 4 OPEN RANGE 1125 1235 70 BREAKLUNCH CHOW NA NA NA 4 OPEN RANGE 1235 1330 55 COLLECTING DATA RANGE, D3 NA LINEAR 4 OPEN RANGE 1330 40 BREAKLUNCH RANGE, D3 NA NA NA 4 OPEN RANGE 1330 40 BREAKLUNCH BREAKLUNCH NA NA NA	5/16/2003	4	OPEN RANGE	0820	0060	10	SET UP/MOBILIZATION	SET UP ON D3	AN	AN	NA	T000	DRY
A OPEN RANGE 1110 1125 15 DOWNTIME DÜE TO CHECKING/ GPS NA NA	5/16/2003	4	OPEN RANGE	0060	1110	130	COLLECTING DATA	RUNNING OPEN	GPS	NA	LINEAR	HOT	DRY
4 OPEN RANGE 1110 1125 15 DOWNTIME DUE TO CHECKING/LOCHECK GPS NA NA NA 4 OPEN RANGE 1125 1235 70 BREAK/LUNCH CHOW NA NA NA NA 4 OPEN RANGE 1235 1330 55 COLLECTING DATA RUNNING OPEN GPS NA LINEAR 4 OPEN RANGE 1330 40 BREAKLUNCH BREAKLUNCH NA NA NA NA								RANGE, D3					31
4 OPEN RANGE 1235 70 BREAK/LUNCH CHOW NA NA NA 4 OPEN RANGE 1235 1330 55 COLLECTING DATA RUNNING OPEN GPS NA LINEAR 4 OPEN RANGE 1330 40 BREAK/LUNCH BDIRECTIONAL EW NA NA NA	5/16/2003	4	OPEN RANGE	1110	1125	15	DOWNTIME DUE TO	CHECKING/	GPS	AN	NA	HOT	DRY
4 OPEN RANGE 1235 70 BREAK/LUNCH CHOW NA NA NA 4 OPEN RANGE 1235 1330 55 COLLECTING DATA RUNNING OPEN GPS NA LINEAR 4 OPEN RANGE 1330 40 BREAK/LUNCH BREAK/LUNCH BREAK NA NA NA							EQUIPMENT	DOWNLOADING					
4 OPEN RANGE 1125 1235 70 BREAK/LUNCH CHOW NA NA NA 4 OPEN RANGE 1235 1330 55 COLLECTING DATA RUNNING OPEN GPS NA LINEAR A OPEN RANGE 1330 40 BREAK/LUNCH BREAK NA NA NA NA							MAINTENANCE/CHECK	DATA					
4 OPEN RANGE 1235 1330 55 COLLECTING DATA RUNNING OPEN GPS NA LINEAR BIDIRECTIONAL E/W BIDIRECTIONAL E/W NA NA NA	5/16/2003	4	OPEN RANGE	1125	1235	70	BREAK/LUNCH	CHOW	NA	NA	NA	HOT	DRY
4 OPEN RANGE 1330 1410 40 BREAKLUNCH BREAK NA NA NA NA	5/16/2003	4	OPEN RANGE	1235	1330	55	COLLECTING DATA	RUNNING OPEN RANGE, D3	GPS	NA	LINEAR	HOT	DRY
4 OPEN RANGE 1330 1410 40 BREAKLUNCH BREAK NA NA NA NA								BIDIRECTIONAL E/W					
	5/16/2003	4	OPEN RANGE	1330	1410	40	BREAK/LUNCH	BREAK	A'A	Y.	NA	HOT	DRY

	No.		Status	Status Status					Track			
Z de la company	Joon		Start	Stop	Duration,	Organization Of the free	Operational Status -		Method=Other		Total Cont.	9
Date	reopie	_	Time		mim	Operational Status	Comments	Method	Explain	Fattern	Field Conditions	Horis
5/16/2003	4	OPEN RANGE	1410	1515	65	COLLECTING DATA	RUNNING OPEN	GPS	Y X	LINEAR	HOT	DRY
							RANGE, D3 BIDIRECTIONAL E/W					
5/16/2003	4	OPEN RANGE	1515	1530	15	DOWNTIME DUE TO	CHECKING/	GPS	NA	AN	HOT	DRY
						EQUIPMENT MAINTENANCE/CHECK	DOWNLOADING DATA					
5/16/2003	4	OPEN RANGE	1530	1600	30	SET UP/MOBILIZATION	BREAKING DOWN	NA	NA.	NA AN	HOT	DRY
						ì	EQUIPMENT EOD					
5/17/2003	4	OPEN RANGE	0630	0715	45	SET UP/MOBILIZATION	SETTING UP	NA	AN	Y'A	HOT	DRY
							EQUIPMENT					
5/17/2003	4	OPEN RANGE	0715	0720	5	COLLECTING DATA	EQUIPMENT WAS	CPS	NA	NA	HOT	DRY
							CALIBRATED USING CAL BALL					
5/17/2003	4	OPEN RANGE	0720	0825	9	COLLECTING DATA	RUNNING OPEN	GPS	NA	LINEAR	HOT	DRY
							RANGE, D2					
							BIDIRECTIONAL E/W					
5/17/2003	4	OPEN RANGE	0825	0921	99	DOWNTIME DUE TO	CHECKING/	GPS	NA	NA	HOT	DRY
						EQUIPMENT MANAGEMENT	DOWNLOADING					
						MAINTENANCE/CHECK	DAIA					
5/17/2003	4	OPEN RANGE	0921	95	79	COLLECTING DATA	RUNNING OPEN	GPS	Y Y	LINEAR	HOT	DRY
							BIDIRECTIONAL EW					
5/17/2003	4	OPEN RANGE	1040	1045	2	DOWNTIME DUE TO	CHECKING/	GPS	NA	NA	HOT	DRY
						EQUIPMENT	DOWNLOADING					
				_		MAINTENANCE/CHECK	DATA					
5/17/2003	4	OPEN RANGE	1045		35	BREAK/LUNCH	CHOW	NA	NA	NA	HOT	DRY
5/17/2003	æ	OPEN RANGE	1120	1230	70	COLLECTING DATA	RUNNING OPEN	GPS	AN	LINEAR	HOT	DRY
							BIDIRECTIONAL E/W					
5/17/2003	3	OPEN RANGE	1230	1245	15	DOWNTIME DUE TO	CHECKING/	CPS	NA	AN	HOT	DRY
						EQUIPMENT MAINTENANCE/CHECK	DOWNLOADING					
5/17/2003	3	OPEN RANGE	1245	1335	50	BREAK/LUNCH	BREAK	NA	Y.	NA AN	HOT	DRY
5/17/2003		OPEN RANGE	1335	1400	25	COLLECTING DATA	CONDUCTED	GPS	NA	AN	HOT	DRY
							EQUIPMENT					
	Į,				;		INTERFERENCE TEST					
5/17/2003	m	OPEN RANGE	1400	1430	30	SET UP/MOBILIZATION	BREAKING DOWN FOI IPMENT ROD	Y Y	NA	Y V	HOT	DRY
							באר וויייווי דראים					

Status				Dermotion			Occupant Status	Though	Track			
People Area Tested Time Time min Operational Status	Time Time min	Time min	Time min		Operational Su	tatus	Operational Status -	Method	Method Explain	Pattern	Field Conditions	tions
OPEN RANGE 0600	0600 0615 15	0615 15	0615 15		SET UP/MOBILIZ	ATION	SETTING UP EQUIPMENT	N A	Y.	AN	HOT	DRY
4 OPEN RANGE 0615 0620 5 COLLECTING DATA	0615 0620 5	0620 5	S	-	COLLECTING D	ATA	EQUIPMENT WAS CALIBRATED USING CAL BALL	GPS	NA	AN A	HOT	DRY
4 OPEN RANGE 0620 0743 83 COLLECTING DATA	0620 0743 83	0743 83	0743 83		COLLECTING DA	ATA	RUNNING OPEN RANGE, B4 BIDIRECTIONAL E/W	GPS	NA	LINEAR	HOT	DRY
4 OPEN RANGE 0743 0815 32 DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	0743 0815 32	0815 32	32		DOWNTIME DUE EQUIPMENT MAINTENANCE/C	3 TO HECK	CHECKING/ DOWNLOADING DATA	AN	NA	AN	НОТ	DRY
4 OPEN RANGE 0815 0930 75 COLLECTING DATA	0815 0930 75	0930 75	75	000	COLLECTING DA	TA	RUNNING OPEN RANGE, B4 BIDIRECTIONAL E/W	GPS	NA	LINEAR	HOT	DRY
4 OPEN RANGE 0930 0945 15 DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	0930 0945 15	0945 15	0945 15		DOWNTIME DUE EQUIPMENT MAINTENANCE/CH	TO ECK	CHECKING/ DOWNLOADING DATA	AN A	NA	A	нот	DRY
0945	0945 0950 5	0950 5	5		DOWNTIME DUE T EQUIPMENT MAINTENANCE/CHE	O SCK	CHANGE OUT BATTERY	Y Y	NA	AN	НОТ	DRY
4 OPEN RANGE 0950 0955 S BREAK/LUNCH	5 5560 0960	5 5560	5 5560		BREAK/LUNCH		BREAK	ΑN	NA	Ϋ́Α	HOT	DRY
4 OPEN RANGE 0955 1005 10 COLLECTING DATA	0955 1005 10	1005 10	1005 10		COLLECTING DAT	Y.	RUNNING OPEN RANGE, B4 BIDIRECTIONAL E/W	GPS	NA	LINEAR	HOT	DRY
4 OPEN RANGE 1005 1010 5 SET UP/MOBILIZATION	1005 1010 5	1010 5	5		SET UP/MOBILIZAT	NOI	SET UP ON GRID C2,C3	NA	NA	AN	HOT	DRY
1010 1024 14 M	1010 1024 14	1024 14	41		DOWNTIME DUE 7 EQUIPMENT MAINTENANCE/CHI	ro Eck	CHECKING/ DOWNLOADING DATA	GPS	NA	NA	НОТ	DRY
4 OPEN RANGE 1024 1130 66 COLLECTING DATA	1024 1130 66	1130 66	99		COLLECTING DAT	Ą	RUNNING OPEN RANGE, C2,C3 BIDIRECTIONAL E/W	GPS	NA	LINEAR	HOT	DRY
4 OPEN RANGE 1130 1145 15 DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	1130 1145 15	1145 15	15		DOWNTIME DUE 1 EQUIPMENT MAINTENANCE/CHE	O 3CK	CHECKING/ DOWNLOADING DATA	GPS	NA	AN	HOT	DRY
4 OPEN RANGE 1145 1310 85 BREAK/LUNCH	1145 1310 85	1310 85	1310 85		BREAK/LUNCH		CHOW/BREAK	NA	NA	AN	HOT	DRY
4 OPEN RANGE 1310 1410 60 COLLECTING DATA	1310 1410 60	1410 60	1410 60		COLLECTING DA	ΓA	RUNNING OPEN RANGE, C2,C3	GPS	NA	LINEAR	HOT	DRY
							BIDIRECTIONAL E/W				8.	

		Field Condition	HOI	HOT DRY		HOT DRY	HOT DRY		HOT DRY			HOT DRY			HOT HOT HOT	HOT HOT	HOT HOT HOT	HOT HOT HOT	HOT HOT HOT HOT	HOT HOT HOT HOT	HOT HOT HOT HOT	HOT HOT HOT HOT	HOT HOT HOT HOT	HOT HOT HOT HOT HOT HOT	HOT	HOT
		Pattern	e Z	NA		NA	NA		LINEAR		N.Y	NA	Y Y	A A A	NA NA LINEAR	NA NA LINEAR	NA NA LINEAR NA	NA NA LINEAR NA	NA LINEAR NA LINEAR	NA LINEAR NA LINEAR	NA LINEAR NA LINEAR	NA LINEAR LINEAR	NA	NA LINEAR NA NA NA NA	NA LINEAR NA NA NA NA NA NA	NA LINEAR LINEAR NA NA NA NA
Track	Method Method=Other	Explain	ď Z	NA		NA	AN		Υ Υ		NIA	NA	NA	AN AN	A N AN AN AN	N N A A A	N N N N A	A A A A A A A A A A A A A A A A A A A	A A A A A A A A A A A A A A A A A A A	N N N N N N N N N N N N N N N N N N N	N A N A N A N A N A N A N A N A N A N A	A A A A A A A A A A A A A A A A A A A	A A A A A A A A A A A A A A A A A A A	A A A A A A A A A A A A A A A A A A A	NA N	N A A N A N A N A N A N A N A N A N A N
Track	Method	040	S	NA		NA A	GPS		CPS		Spo	GPS	GPS	GPS	GPS NA GPS	GPS GPS	GPS GPS GPS	GPS GPS GPS	GPS GPS GPS	GPS GPS GPS	GPS GPS GPS GPS GPS	GPS GPS GPS GPS	GPS GPS GPS ANA GPS	GPS GPS GPS NA MA	GPS	GPS
	Operational Status -	Comments	CHECKING/ DOWNLOADING DATA	BREAKING DOWN	EQUIPMENT EOD	SETTING UP EQUIPMENT	EQUIPMENT WAS	CAL BALL	RUNNING OPEN RANGE, C2,C3	BIDIKECTIONAL EW	CUBCVINICA	CHECKING/	CHECKING/ DOWNLOADING DATA	CHECKING/ DOWNLOADING DATA BREAK	CHECKING/ DOWNLOADING DATA BREAK RUNNING OPEN	CHECKING/ DOWNLOADING DATA BREAK RUNNING OPEN RANGE, C2,C3 BIDIRECTIONAL E/W	CHECKING/ DOWNLOADING DATA BREAK RUNNING OPEN RANGE, C2,C3 BIDIRECTIONAL EW CHECKING/	CHECKING/ DOWNLOADING DATA BREAK RUNNING OPEN RANGE, C2,C3 BIDIRECTIONAL E/W CHECKING/ DOWNLOADING DATA	CHECKING/ DOWNLOADING DATA BATA BREAK RUNNING OPEN RANGE, C2,C3 BIDIRECTIONAL E/W CHECKING/ DOWNLOADING DATA RUNNING OPEN	CHECKING/ DOWNLOADING DATA BREAK RUNNING OPEN RANGE, C2,C3 BIDIRECTIONAL E/W CHECKING/ DOWNLOADING DATA RUNNING OPEN RANGE, C2,C3 BENECTIONAL E/W CHECKING/ DOWNLOADING DATA RUNNING OPEN RANGE, C2,C3 BIDIRECTIONAL E/W	CHECKING/ DOWNLOADING DATA BATA BREAK RUNNING OPEN RANGE, C2,C3 BIDIRECTIONAL EW CHECKING/ DOWNLOADING DATA RUNNING OPEN RANGE, C2,C3 BIDIRECTIONAL EW CHECKING/ CHECKING/ CHECKING/ CHECKING/ CHECKING/ CHECKING/ CHECKING/ CHECKING/ CACACACACACACACACACACACACACACACACACACA	CHECKING/ DOWNLOADING DATA BATA BREAK RUNNING OPEN RANGE, C2,C3 BIDIRECTIONAL EW CHECKING/ DOWNLOADING DATA RUNNING OPEN RANGE, C2,C3 BIDIRECTIONAL EW CHECKING/ DOWNLOADING DATA CHECKING/ DOWNLOADING DATA CHECKING/ DOWNLOADING	CHECKING/ DOWNLOADING DATA BREAK RUNNING OPEN RANGE, C2,C3 BIDIRECTIONAL EW CHECKING/ DOWNLOADING DATA RUNNING OPEN RANGE, C2,C3 BIDIRECTIONAL EW CHECKING/ DOWNLOADING DATA CHECKING/ DOWNLOADING DATA RUNNING OPEN RANGE, C2,C3 BIDIRECTIONAL EW CHECKING/ DOWNLOADING DATA BREAK	CHECKING/ DOWNLOADING DATA BREAK RUNNING OPEN RANGE, C2, C3 BIDIRECTIONAL E/W CHECKING/ DOWNLOADING DATA RUNNING OPEN RANGE, C2, C3 BIDIRECTIONAL E/W CHECKING/ DOWNLOADING DATA RUNNING OPEN RANGE, C2, C3 BIDIRECTIONAL E/W CHECKING/ DOWNLOADING DATA BREAK SET UP IN YUMA EXTREME	CHECKING/ DOWNLOADING DATA BREAK RUNNING OPEN RANGE, C2,C3 BIDIRECTIONAL E/W CHECKING/ DOWNLOADING DATA RUNNING OPEN RANGE, C2,C3 BIDIRECTIONAL E/W CHECKING/ DOWNLOADING DATA RUNNING OPEN BREAK SET UP IN YUMA EXTREME EXTREME	CHECKING/ DOWNLOADING DATA BREAK RUNNING OPEN RANGE, C2,C3 BIDIRECTIONAL E/W CHECKING/ DOWNLOADING DATA RUNNING OPEN RANGE, C2,C3 BIDIRECTIONAL E/W CHECKING/ DOWNLOADING DATA RANGE, C2,C3 BIDIRECTIONAL E/W CHECKING/ DOWNLOADING DATA BREAK SET UP IN YUMA EXTREME EXTREME EXTREME
		Operational Status	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	SET UP/MOBILIZATION		SET UP/MOBILIZATION	COLLECTING DATA		COLLECTING DATA		OT STIME DITTE TO	DOWNTIME DUE TO	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK BREAK/LUNCH	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK BREAK/LUNCH COLLECTING DATA	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK BREAK/LUNCH COLLECTING DATA	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK BREAK/LUNCH COLLECTING DATA DOWNTIME DUE TO FOLIPMENT	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK BREAK/LUNCH COLLECTING DATA DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK BREAK/LUNCH COLLECTING DATA DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK COLLECTING DATA	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK BREAK/LUNCH COLLECTING DATA DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK COLLECTING DATA	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK BREAKLUNCH COLLECTING DATA COLLECTING DATA EQUIPMENT MAINTENANCE/CHECK COLLECTING DATA COLLECTING DATA COLLECTING DATA COLLECTING DATA COLLECTING DATA EQUIPMENT	DOWNTIME DUE TO BQUIPMENT MAINTENANCE/CHECK BREAKLUNCH COLLECTING DATA COLLECTING DATA MAINTENANCE/CHECK COLLECTING DATA COLLECTING DATA MAINTENANCE/CHECK MAINTENANCE/CHECK MAINTENANCE/CHECK	DOWNTIME DUE TO BQUIPMENT MAINTENANCE/CHECK BREAK/LUNCH COLLECTING DATA COLLECTING DATA MAINTENANCE/CHECK COLLECTING DATA COLLECTING DATA MAINTENANCE/CHECK COLLECTING DATA MAINTENANCE/CHECK RAINTENANCE/CHECK BREAK/LUNCH	DOWNTIME DUE TO BQUIPMENT MAINTENANCE/CHECK BREAKLUNCH COLLECTING DATA COLLECTING DATA MAINTENANCE/CHECK COLLECTING DATA COLLECTING DATA MAINTENANCE/CHECK COLLECTING DATA MAINTENANCE/CHECK BREAKLUNCH BREAKLUNCH SET UP/MOBILIZATION	DOWNTIME DUE TO BQUIPMENT MAINTENANCE/CHECK BREAKLUNCH COLLECTING DATA COLLECTING DATA ANINTENANCE/CHECK COLLECTING DATA COLLECTING DATA BREAKLUNCH BREAKLUNCH SET UP/MOBILIZATION COLLECTING DATA	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK BREAK/LUNCH COLLECTING DATA COLLECTING DATA MAINTENANCE/CHECK COLLECTING DATA COLLECTING DATA MAINTENANCE/CHECK COLLECTING DATA BREAK/LUNCH SET UP/MOBILIZATION COLLECTING DATA SET UP/MOBILIZATION
	Duration,	mm .	21	10		15	4		68		00	20	20	20	20 27 42	20 27 42	27 27 42 13	20 27 42 42 13	20 27 42 13 37	20 27 42 13 37	20 27 42 13 37	20 27 42 42 13 37 15	20 27 42 13 37 37 20 20	20 27 42 13 13 15 15	20 27 42 13 37 15 20 20 47	20 27 42 42 13 37 15 16 17 47
Status	Stop		1470	1430	-	0545	0549		0718		-	0738														
Status	Start	Time	1410	1420		0530	0545		0549	1	0110	0718	0718	0718	0718 0738 0805	0718 0738 0805	0718 0738 0805 0847	0718 0738 0805 0847	0718 0738 0805 0807 0900	0718 0805 0807 0847	0718 0805 0805 0847 0900	0718 0805 0805 0807 0900	0718 0805 0807 0900 0900	0718 0805 0807 0900 0937	0718 0805 0805 0900 0900 0952 1012	0718 0805 0805 0900 0952 1012
			OPEN KANGE	OPEN RANGE		OPEN RANGE	OPEN RANGE		OPEN RANGE	The state of the s	DDEN DANGE	OPEN RANGE	OPEN RANGE	OPEN RANGE	OPEN RANGE OPEN RANGE OPEN RANGE	OPEN RANGE OPEN RANGE OPEN RANGE	OPEN RANGE OPEN RANGE OPEN RANGE	OPEN RANGE OPEN RANGE OPEN RANGE	OPEN RANGE OPEN RANGE OPEN RANGE OPEN RANGE	OPEN RANGE OPEN RANGE OPEN RANGE OPEN RANGE	OPEN RANGE OPEN RANGE OPEN RANGE OPEN RANGE OPEN RANGE	OPEN RANGE OPEN RANGE OPEN RANGE OPEN RANGE	OPEN RANGE OPEN RANGE OPEN RANGE OPEN RANGE	OPEN RANGE OPEN RANGE OPEN RANGE OPEN RANGE OPEN RANGE EXTREME	OPEN RANGE OPEN RANGE OPEN RANGE OPEN RANGE OPEN RANGE SYUMA EXTREME YUMA EXTREME	OPEN RANGE OPEN RANGE OPEN RANGE OPEN RANGE OPEN RANGE OPEN RANGE XUMA EXTREME YUMA EXTREME
Š.	of	Feople	4	4		4	4		4		_	4	4	4 4	4 44	4 4	4 4 4	4 4 4	4 4 4 4	4 4 4 4	4 4 4 4 4	4 4 4 4 4	4 4 4 4 4 4	4 4 4 4 4 4 4	4 4 4 4 4 4 4	4 4 4 4 4
			2/19/2003	5/19/2003		5/20/2003	5/20/2003		5/20/2003	5/10/10/03	2007/07/0			5/20/2003			\$/20/2003 \$/20/2003 \$/20/2003									

Note: Activities pertinent to this specific demonstration are indicated in highlighted text.

	us	DRY	DRY	DRY	DRY	DRY	DRY	DRY	DRY	DRY	DRY	DRY	DRY	DRY
	Field Conditions	HOT	HOT	HOT	HOT	HOT	HOT	HOT	HOT	HOT	HOT	HOT	HOT	HOT
	Pattern	AZ	Y Y	AN	NA NA	LINEAR	AN	Y Z	AN	AN	LINEAR	NA	LINEAR	NA
Track Track Method Method=Other	Explain	AN	AN	NA	NA V	NA A	NA	NA	NA	NA V	NA	NA V	AN A	NA
Track Method 1		GPS	NA	AN	CPS	GPS	NA	NA	AN	GPS	GPS	GPS	GPS	GPS
Operational Status -	Comments	CHECKING/ DOWNLOADING DATA	LUNCH	SETUP	EQUIPMENT WAS CALIBRATED USING CAL BALL	RUNNING YUMA EXTREME BIDIRECTIONAL NORTH/SOUTH	FIELD COMPUTER OVERHEAT/FAILED	BREAKING DOWN EQUIPMENT EOD	SETTING UP EQUIPMENT	EQUIPMENT WAS CALIBRATED USING CAL BALL	RUNNING YUMA EXTREME BIDIRECTIONAL NORTH/SOUTH	CHECKING/ DOWNLOADING DATA	RUNNING YUMA EXTREME BIDIRECTIONAL NORTH/SOUTH	CHECKING/ DOWNLOADING DATA
	Operational Status	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	BREAK/LUNCH	SET UP/MOBILIZATION	COLLECTING DATA	COLLECTING DATA	DOWNTIME DUE TO EQUIPMENT FAILURE	SET UP/MOBILIZATION	SET UP/MOBILIZATION	COLLECTING DATA	COLLECTING DATA	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	COLLECTING DATA	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK
Duration,	min	10	09	15	en en	2	S	01	20	01	N.	6	<mark>96</mark>	<mark>20</mark>
Status Stop	Time	1130	1230	1245	1248	1255	1300	1310	0550	0090	9090	0614	0750	0810
Status Status Start Stop	Time	1111	1130	1230	1245	1248	1255	1300	0530	0550	0090	9090	0614	0750
	Area Tested	YUMA EXTREME	YUMA	YUMA	YUMA EXTREME	YUMA EXTREME	YUMA	YUMA	YUMA	YUMA	YUMA EXTREME	YUMA EXTREME	YUMA EXTREME	YUMA EXTREME
o yo	People	4	4	4	4	4	4	4	3	3	3	3	m	(C)
		5/20/2003	5/20/2003	5/20/2003	5/20/2003	5/20/2003	5/20/2003	5/20/2003	5/21/2003	5/21/2003	5/21/2003	5/21/2003	5/21/2003	5/21/2003

0	2 18	Status Status	_	Duration		Onerstions Status -	Track	Track Method=Other			el Vi
Area Tested Time Time		Time	•	min	Operational Status	Comments		Explain	Pattern	Field Conditions	ions
YUMA 0810 0820 EXTREME		0820		01	BREAK/LUNCH	BREAK	AN	NA	AN	HOT	DRY
YUMA 0820 0850 EXTREME		0880		30	COLLECTING DATA	RUNNING YUMA EXTREME BIDIRECTIONAL NORTH/SOUTH	CPS	NA	LINEAR	HOT	DRY
YUMA 0850 0920 EXTREME		0920		30	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	CPS	NA	AN	HOT	DRY
MOGUL AREA 0920 0930		0630		01	SET UP/MOBILIZATION	SET UP IN MOGUL AREA	AN	NA	NA	HOT	DRY
MOGUL AREA 0930 1040		1040		70	COLLECTING DATA	RUNNING MOGUL AREA, BUDIRECTIONAL NORTH/SOUTH	GPS	A'A	LINEAR	НОТ	DRY
MOGUL AREA 1040 1100		0011		20	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	AN	HOT	DRY
MOGUL AREA 1100 1158	1158			28	COLLECTING DATA	RUNNING MOGUL AREA, BIDIRECTIONAL NORTH/SOUTH	GPS	NA A	LINEAR	HOT	DRY
MOGUL AREA 1158 1210	1210			12	DOWNTIME DUE TO EQUIPMENT FAIL URE	GPS MOUNT BROKE, OPERATOR ERROR	N'A	NA	AN	HOT	DRY
MOGUL AREA 1210 1230	1230			20	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	CPS	NA	NA	НОТ	DRY
MOGUL AREA 1230 1237		1237		7	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL BALL	GPS	NA	AN	НОТ	DRY
MOGUL AREA 1237 1322		1322		45	COLLECTING DATA	RUNNING MOGUL AREA, BIDIRECTIONAL NORTH/SOUTH	GPS	NA	LINEAR	HOT	DRY
MOGUL AREA 1322 1335		1335		13	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	CHECKING/ DOWNLOADING DATA	GPS	A A	NA A	HOT	DRY

Note: Activities pertinent to this specific demonstration are indicated in highlighted text.

	3	Yau			DRY	DRY	DRY	DRY	DRY	DRY	DRY	DRY	DRY	DRY	DRY	DRY
	Kield Conditions	TOT			НОТ	HOT	HOT	HOT	HOT	HOT	HOT	HOT	HOT	HOT	HOT	НОТ
	Pattern	INEAP			NA A	AN	AZ V	LINEAR	¥Z	LINEAR	NA	LINEAR	AN	NA	NA	NA
Track	Track Method=Other	NA			VA	NA	NA	NA N	NA AN	AN	NA NA	NA	NA NA	AN	AN	NA
	Track	CDC	5		Y Y	AZ	GPS	SAS	GPS	GPS	Y Y	GPS	GPS	NA	A'N	GPS
	Operational Status -	PINNING MOGIT	AREA, BIDIDECTIONAL	NORTH/SOUTH	BREAKING DOWN EQUIPMENT EOD	SETTING UP EQUIPMENT	EQUIPMENT WAS CALIBRATED USING CAL BALL	RUNNING YUMA EXTREME BIDIRECTIONAL NORTH/SOUTH	CHECKING/ DOWNLOADING DATA	RUNNING YUMA EXTREME BIDIRECTIONAL NORTH/SOUTH	SWAP OUT BATTERIES	RUNNING YUMA EXTREME BIDIRECTIONAL NORTH/SOUTH	CHECKING/ DOWNLOADING DATA	BREAK	SET UP OVER CALIBRATION PIT	EQUIPMENT WAS CALIBRATED USING CAL BALL
	Operational Status	COLI ECTING DATA			SET UP/MOBILIZATION	SET UP/MOBILIZATION	COLLECTING DATA	COLLECTING DATA	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	COLLECTING DATA	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	COLLECTING DATA	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	BREAK/LUNCH	SET UP/MOBILIZATION	COLLECTING DATA
	Duration,	702	2		15	<u> </u>	S	63	15	06	v)	15	<u>15</u>	115	∞	2
Status Status	Stop				1500	0637	0642	0745	0080	0930	0935	0560	1005	1020	1028	1030
Status	Start	1335			1445	0230	0637	0642	0745	0080	0930	0935	0950	1005	1020	1028
	Area Tected	2			MOGUL AREA	YUMA EXTREME	YUMA EXTREME	YUMA EXTREME	YUMA EXTREME	YUMA EXTREME	YUMA	YUMA EXTREME	YUMA	YUMA	CALIBRATION PIT	CALIBRATION PIT
No.	of People	3 20))		3	3	3	m e	3	(C)	m	8	8	3	3	3
	Date	5/21/2003			5/21/2003	5/22/2003	5/22/2003	5/22/2003	5/22/2003	5/22/2003	5/22/2003	5/22/2003	5/22/2003	5/22/2003	5/22/2003	5/22/2003

Note: Activities pertinent to this specific demonstration are indicated in highlighted text.

	ı	us	DRY		DRY	DRY	DRY	DRY	DRY	DRY	DRY	DRY	DRY	DRY	DRY	DRY
		Field Conditions	HOT		HOT	НОТ	НОТ	нот	HOT	НОТ	нот	нот	НОТ	HOT	HOT	HOT
-		Pattern	LINEAR		LINEAR	LINEAR	NA	Y Z	AN	Ψ. V.	LINEAR	LINEAR	LINEAR	LINEAR	Y V	NA
Track	Track Method=Other	Explain	Y Y		Y.	AN	NA	A'A	AN	NA	NA	A'A	A'A	NA VA	NA V	NA
	Track	Method	GPS		GPS	GPS	A'	GPS	Ą.	GPS	GPS	GPS	GPS	GPS	GPS	AN
	tus -		RUNNING SIGNITURE DATA ON 40MM	MARK II	RUNNING SIGNITURE DATA ON 57MM	RUNNING SIGNITURE DATA ON 60MM	BREAK	CHECKING/ DOWNLOADING DATA	LUNCH	EQUIPMENT WAS CALIBRATED USING CAL BALL	RUNNING SIGNITURE DATA ON ROCKEYE MK118	RUNNING SIGNITURE DATA ON 2.75 ROCKET	RUNNING SIGNITURE DATA ON 105 STANDARD	RUNNING SIGNITURE DATA ON 155MM	EQUIPMENT WAS CALIBRATED USING CAL BALL	END OF TEST
	•	Operational Status	COLLECTING DATA	,	COLLECTING DATA	COLLECTING DATA	BREAK/LUNCH	DOWNTIME DUE TO EQUIPMENT MAINTENANCE/CHECK	BREAK/LUNCH	COLLECTING DATA	COLLECTING DATA	COLLECTING DATA	COLLECTING DATA	COLLECTING DATA	COLLECTING DATA	DEMOBILIZATION
	Duration,	min	22		13	23	01	11	51	3	12	25	27	25	2	46
Status	Stop	Time	1052		1105	1128	1138	1149	1240	1243	1255	1320	1347	1412	1414	1500
Status	Start	Time	1030		1052	1105	1128	1138	1149	1240	1243	1255	1320	1347	1412	1414
		- 1	CALIBRATION PIT		CALIBRATION	CALIBRATION PIT	CALIBRATION PIT	CALIBRATION PIT	CALIBRATION PIT	CALIBRATION PIT	CALIBRATION PIT	CALIBRATION PIT	CALIBRATION PIT	CALIBRATION PIT	CALIBRATION PIT	CALIBRATION PIT
No.	of .	People	က		3	6	3	3	3	3	3	3	3	3	3	3
			5/22/2003		5/22/2003	5/22/2003	5/22/2003	5/22/2003	5/22/2003	5/22/2003	D-15	5/22/2003	5/22/2003	5/22/2003	5/22/2003	5/22/2003

Note: Activities pertinent to this specific demonstration are indicated in highlighted text.

APPENDIX E. REFERENCES

- 1. Standardized UXO Technology Demonstration Site Handbook, DTC Project No. 8-CO-160-000-473, Report No. ATC-8349, March 2002.
- 2. Aberdeen Proving Ground Soil Survey Report, October 1998.
- 3. Data Summary, UXO Standardized Test Site: APG Soils Description, May 2002.
- 4. Yuma Proving Ground Soil Survey Report, May 2003.
- 5. Practical Nonparametric Statistics, W.J. Conover, John Wiley & Sons, 1980, ages 144 through 151.

APPENDIX F. ABBREVIATIONS

AEC = U.S. Army Environmental Center

APG = Aberdeen Proving Ground

ATC = U.S. Army Aberdeen Test Center

HEAT = high-explosive, antitank EMI = electromagnetic interference

EMIS = Electromagnetic Induction Spectroscopy

ERDC = U.S. Army Corps of Engineers Engineering Research and Development Center

ESTCP = Environmental Security Technology Certification Program

EQT = Army Environmental Quality Technology Program

GPS = Global Positioning System
JPG = Jefferson Proving Ground
PDA = personal digital assistant

POC = point of contact PVC = polyvinyl chloride QA = quality assurance QC = quality control

ROC = receiver-operating characteristic

RTK = real time kinematic

SERDP = Strategic Environmental Research and Development Program

UXO = unexploded ordnance

YPG = U.S. Army Yuma Proving Ground

APPENDIX G. DISTRIBUTION LIST

DTC Project No. 8-CO-160-UXO-021

Addressee	No. of Copies
Commander	
U.S. Army Environmental Center	2
ATTN: SFIM-AEC-ATT (Mr. George Robitaille) Aberdeen Proving Ground, MD 21010-5401	2
Commander	
U.S. Army Corps of Engineers Engineering	
Research and Development Center ATTN: Mr. Jose Llopis	1
3909 Halls Ferry Road	1
Vicksburg, MS 39180-619	
SERDP/ESTCP	
ATTN: (Ms. Anne Andrews)	1
901 North Stuart Street, Suite 303	
Arlington, VA 22203	
Commander	
U.S. Army Aberdeen Test Center ATTN: CSTE-DTC-SL-E (Mr. Larry Overbay)	1
(Library)	1
CSTE-DTC-AT-CS-R	1
Aberdeen Proving Ground, MD 21005-5059	
Defense Technical Information Center	2
8725 John J. Kingman Road, STE 0944 Fort Belvoir, VA 22060-6218	

Secondary distribution is controlled by Commander, U.S. Army Environmental Center, ATTN: SFIM-AEC-ATT.