

AD NO. _____ DTC PROJECT NO. 8-CO-160-UXO-021 REPORT NO. ATC-8826



STANDARDIZED

UXO TECHNOLOGY DEMONSTRATION SITE

BLIND GRID SCORING RECORD NO. 216

SITE LOCATION: U.S. ARMY YUMA PROVING GROUND

DEMONSTRATOR: U.S. ARMY CORPS OF ENGINEERS ENGINEERING RESEARCH AND DEVELOPMENT CENTER 3909 HALLS FERRY ROAD VICKSBURG, MS 39180-6199

TECHNOLOGY TYPE/PLATFORM: EM63/PUSHCART

PREPARED BY: U.S. ARMY ABERDEEN TEST CENTER ABERDEEN PROVING GROUND, MD 21005-5059

JULY 2004







U.S. ARMY DEVELOPMENTAL TEST COMMAND ABERDEEN PROVING GROUND, MD 21005-5055





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14. ABSTRACT This scoring record documents the efforts of U.S. Army Corps of Engineers Engineering Research and Development Center (ERDC) to detect and discriminate inert unexploded ordnance (UXO) utilizing the YPG Standardized UXO Technology Demonstration Site Blind Grid. The scoring record was coordinated by Larry Overbay and by the Standardized UXO Technology Demonstration Site Scoring Committee. Organizations on the committee include the U.S. Army Corps of Engineers, the Environmental, Security Technology Certification Program, the Strategic Environmental Research and Development Program, the Institute for Defense Analysis, the U.S. Army Environmental Center, and the U.S. Army Aberdeen Test Center.					
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SECTION 1. GENERAL INFORMATION

1.1 BACKGROUND

Technologies under development for the detection and discrimination of unexploded ordnance (UXO) require testing so that their performance can be characterized. To that end, Standardized Test Sites have been developed at Aberdeen Proving Ground (APG), Maryland and U.S. Army Yuma Proving Ground (YPG), Arizona. These test sites provide a diversity of geology, climate, terrain, and weather as well as diversity in ordnance and clutter. Testing at these sites is independently administered and analyzed by the government for the purposes of characterizing technologies, tracking performance with system development, comparing performance of different systems, and comparing performance in different environments.

The Standardized UXO Technology Demonstration Site Program is a multi-agency program spearheaded by the U.S. Army Environmental Center (AEC). The U.S. Army Aberdeen Test Center (ATC) and the U.S. Army Corps of Engineers Engineering Research and Development Center (ERDC) provide programmatic support. The program is being funded and supported by the Environmental Security Technology Certification Program (ESTCP), the Strategic Environmental Research and Development Program (SERDP) and the Army Environmental Quality Technology Program (EQT).

1.2 SCORING OBJECTIVES

The objective in the Standardized UXO Technology Demonstration Site Program is to evaluate the detection and discrimination capabilities of a given technology under various field and soil conditions. Inert munitions and clutter items are positioned in various orientations and depths in the ground.

The evaluation objectives are as follows:

a. To determine detection and discrimination effectiveness under realistic scenarios that vary targets, geology, clutter, topography, and vegetation.

b. To determine cost, time, and manpower requirements to operate the technology.

c. To determine demonstrator's ability to analyze survey data in a timely manner and provide prioritized "Target Lists" with associated confidence levels.

d. To provide independent site management to enable the collection of high quality, ground-truth, geo-referenced data for post-demonstration analysis.

1.2.1 <u>Scoring Methodology</u>

a. The scoring of the demonstrator's performance is conducted in two stages. These two stages are termed the RESPONSE STAGE and DISCRIMINATION STAGE. For both stages, the probability of detection (P_d) and the false alarms are reported as receiver-operating

characteristic (ROC) curves. False alarms are divided into those anomalies that correspond to emplaced clutter items, measuring the probability of false positive (P_{fp}), and those that do not correspond to any known item, termed background alarms.

b. The RESPONSE STAGE scoring evaluates the ability of the system to detect emplaced targets without regard to ability to discriminate ordnance from other anomalies. For the blind grid RESPONSE STAGE, the demonstrator provides the scoring committee with a target response from each and every grid square along with a noise level below which target responses are deemed insufficient to warrant further investigation. This list is generated with minimal processing and, since a value is provided for every grid square, will include signals both above and below the system noise level.

c. The DISCRIMINATION STAGE evaluates the demonstrator's ability to correctly identify ordnance as such and to reject clutter. For the blind grid DISCRIMINATION STAGE, the demonstrator provides the scoring committee with the output of the algorithms applied in the discrimination-stage processing for each grid square. The values in this list are prioritized based on the demonstrator's determination that a grid square is likely to contain ordnance. Thus, higher output values are indicative of higher confidence that an ordnance item is present at the specified location. For digital signal processing, priority ranking is based on algorithm output. For other discrimination approaches, priority ranking is based on human (subjective) judgment. The demonstrator also specifies the threshold in the prioritized ranking that provides optimum performance, (i.e. that is expected to retain all detected ordnance and rejects the maximum amount of clutter).

d. The demonstrator is also scored on EFFICIENCY and REJECTION RATIO, which measures the effectiveness of the discrimination stage processing. The goal of discrimination is to retain the greatest number of ordnance detections from the anomaly list, while rejecting the maximum number of anomalies arising from non-ordnance items. EFFICIENCY measures the fraction of detected ordnance retained after discrimination, while the REJECTION RATIO measures the fraction of false alarms rejected. Both measures are defined relative to performance at the demonstrator-supplied level below which all responses are considered noise, i.e., the maximum ordnance detectable by the sensor and its accompanying false positive rate or background alarm rate.

e. All scoring factors are generated utilizing the Standardized UXO Probability and Plot Program, version 3.1.1.

1.2.2 <u>Scoring Factors</u>

Factors to be measured and evaluated as part of this demonstration include:

- a. Response Stage ROC curves:
- (1) Probability of Detection (P_d^{res}) .
- (2) Probability of False Positive (P_{fp}^{res}).
- (3) Background Alarm Rate (BAR^{res}) or Probability of Background Alarm (P_{BA}^{res}).

- b. Discrimination Stage ROC curves:
- (1) Probability of Detection (P_d^{disc}) .
- (2) Probability of False Positive (P_{fp}^{disc}).
- (3) Background Alarm Rate (BAR^{disc}) or Probability of Background Alarm (P_{BA}^{disc}).

c. Metrics:

- (1) Efficiency (E).
- (2) False Positive Rejection Rate (R_{fp}) .
- (3) Background Alarm Rejection Rate (R_{BA}).

d. Other:

- (1) Probability of Detection by Size and Depth.
- (2) Classification by type (i.e., 20-mm, 40-mm, 105-mm, etc.).
- (3) Location accuracy.
- (4) Equipment setup, calibration time and corresponding man-hour requirements.
- (5) Survey time and corresponding man-hour requirements.
- (6) Reacquisition/resurvey time and man-hour requirements (if any).
- (7) Downtime due to system malfunctions and maintenance requirements.

1.3 STANDARD AND NONSTANDARD INERT ORDNANCE TARGETS

The standard and nonstandard ordnance items emplaced in the test areas are listed in Table 1. Standardized targets are members of a set of specific ordnance items that have identical properties to all other items in the set (caliber, configuration, size, weight, aspect ratio, material, filler, magnetic remanence, and nomenclature). Nonstandard targets are ordnance items having properties that differ from those in the set of standardized targets.

Standard Type	Nonstandard (NS)
20-mm Projectile M55	20-mm Projectile M55
	20-mm Projectile M97
40-mm Grenades M385	40-mm Grenades M385
40-mm Projectile MKII Bodies	40-mm Projectile M813
BDU-28 Submunition	
BLU-26 Submunition	
M42 Submunition	
57-mm Projectile APC M86	
60-mm Mortar M49A3	60-mm Mortar (JPG)
	60-mm Mortar M49
2.75-inch Rocket M230	2.75-inch Rocket M230
	2.75-inch Rocket XM229
MK 118 ROCKEYE	
81-mm Mortar M374	81-mm Mortar (JPG)
	81-mm Mortar M374
105-mm Heat Rounds M456	
105-mm Projectile M60	105-mm Projectile M60
155-mm Projectile M483A1	155-mm Projectile M483A
	500-lb Bomb
	M75 Submunition

TABLE 1. INERT ORDNANCE TARGETS

JPG = Jefferson Proving Ground.

SECTION 2. DEMONSTRATION

2.1 DEMONSTRATOR INFORMATION

2.1.1 Demonstrator Point of Contact (POC) and Address

POC: Mr. Ryan North (601) 634-3486

 Address: U.S. Army Corps of Engineers Engineering Research and Development Center
 3909 Halls Ferry Road Vicksburg, MS 39180-6199

2.1.2 System Description (provided by demonstrator)

a. The EM63/pushcart is a commercially available sensor (produced by Geonics, Ltd., of Mississauga, Ontario, Canada, who also produces the EM61). It is a high power, high sensitivity, wide bandwidth full Time Domain UXO Detector. The EM63 consists of a powerful transmitter that generates a pulsed primary magnetic field, which induces eddy currents in nearby metallic objects. The time decay of the currents is accurately measured over a wide dynamic range of time. The second receiver coil axially mounted with the main coil, is used for target depth determination. The acquisition is controlled either by wheel odometer, manual fiducial, or free running.

b. Figure 1 shows an annotated photograph of the EM63 system consists of three major hardware sub-systems: (1) EM63 Control Console Sub-System; (2) Antenna Cart Sub-System; (3) Global Positioning System (GPS) Navigation Sub-System.

(1) The EM63 Control Console Sub-System consists of receiver and transmitter unit, controlled by an integrated field computer. The control console also houses the system battery.

(2) The Antenna Cart Sub-System consists of the transmitter antenna (the 1 meter by 1 meter bottom coil), and receiver coils.

(3) The GPS Navigation Sub-System - Local positioning and geo-referencing of the Geonics EM63 system is accomplished using a Trimble 5700 Real Time Kinematic (RTK) GPS system.

c. The navigational Trimble GPS consists of two receivers that are in radio communication with each other, the rover, and base station. A roving GPS antenna is mounted in the center of the EM63 coils two meters above the bottom coil. The operator or his assistant carries the controller for the roving antenna. The antenna is positioned so that it minimizes any influence on the EM63. The roving GPS is constantly receiving coordinate corrections from the base station.

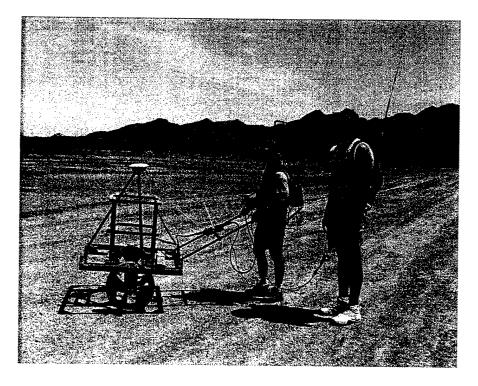


Figure 1. Demonstrator's system, the EM63 pushcart.

2.1.3 Data Processing Description (provided by demonstrator)

EM63 and GPS data are merged in real time in the control console. The EM63 output files will be processed with Geonics' proprietary DAT63W software to convert the files from Binary to American Standard Code for Information Interchange (ASCII). The ASCII data files will be imported into Geosoft's Oasis Montaj. There are no corrections required for positioning since the GPS antenna is centered with respect to the coils. The EM63 files will be combined in Oasis to create one file per area. The resulting area files exported by Oasis meet the requirements as the Raw Sensor Data that must be delivered at the end of the demonstration. The following processing steps will be performed in Oasis:

- a. Background removal or leveling.
- b. Map generation.
- c. Target picking.

2.1.4 Data Submission Format

Data were submitted for scoring in accordance with data submission protocols outlined in the Standardized UXO Technology Demonstration Site Handbook. These submitted data are not included in this report in order to protect ground truth information.

2.1.5 <u>Demonstrator Quality Assurance (QA) and Quality Control (QC) (provided by</u> <u>demonstrator)</u>

a. EM63 and GPS data are merged into real time in the control console. The EM63 output files are processed with Geonics' proprietary DAT63W software to convert the files from Binary to ASCII. There are no corrections required for positioning since the GPS antenna is centered with respect to the coils. The EM63 files were combined to create one file per area. The resulting area files exported met the requirements as the Raw Sensor Data that was delivered at the end of the demonstration. The following processing steps were performed: (1) Background removal or leveling; (2) Map generation; (3) Target picking.

b. Four levels of QC checks were performed the first day of the project: at the beginning of the day, multiple times each day, and whenever equipment was changed. The first day of the project, a 10-meter long line was laid out to orient North to South, and a 3-inch diameter steel sphere was placed at the center of the line. This line was well marked and used each time the instrument was tested or repositioned. Data was collected on the line with and without navigation equipment. Then a test for instrument response over the steel sphere, as well as a position and a latency check were performed. The cart was towed along the line slowly in two directions, and then backed up until it was centered over the sphere. This set the location of the sphere as well as the instrument response, which was used every time the equipment was checked.

c. Each morning a functional check of the equipment was conducted. A visual inspection of all equipment for damage was conducted. Equipment was assembled and powered up. A check of the cable connections for shorts or broken pin-outs was also conducted. If any shorts or pin-outs were found, the broken cable was marked and removed from service. A static and instrument response test was performed to ensure that the data was stable when the instrument was in a static position over a marked location. These tests were performed after the instrument had sufficient time to warm up.

d. Every time the batteries were changed or data was dumped, the instrument, positioning, and latency tests were repeated. If equipment was changed, all of the previous tests were performed again.

e. A 0.5 meter line spacing on all grids, while recording a reading approximately every 0.1-m along the survey line, was used. When the latency, positioning, and instrument response tests over the steel sphere were conducted, the estimated accuracy of the navigation system was also checked. The peak instrument response while moving was compared with the position established during the first day QC checks.

2.1.6 Additional Records

The following record(s) by this vendor can be accessed via the Internet as PDF files at <u>www.uxotestsites.org</u>.

2.2 YPG SITE INFORMATION

2.2.1 Location

YPG is located adjacent to the Colorado River in the Sonoran Desert. The UXO Standardized Test Site is located south of Pole Line Road and east of the Countermine Testing and Training Range. The Open Field range, Calibration Grid, Blind Grid, Mogul area, and Desert Extreme area comprise the 350- by 500 meter general test site area. The open field site is the largest of the test sites and measures approximately 200 by 350 meters. To the east of the open field range are the calibration and blind test grids that measure 30 by 40 meters and 40 by 40 meters, respectively. South of the Open Field is the 135- by 80-meter Mogul area consisting of a sequence of man-made depressions. The Desert Extreme area is located southeast of the open field site and has dimensions of 50 by 100 meters. The Desert Extreme area, covered with desert-type vegetation, is used to test the performance of different sensor platforms in a more severe desert conditions/environment.

2.2.2 Soil Type

Soil samples were collected at the YPG UXO Standardized Test Site by ERDC, (fig. 8), to characterize the shallow subsurface (<3 meters). Both surface grab samples and continuous soil borings were acquired. The soils were subjected to several laboratory analyses, including sieve/hydrometer, water content, magnetic susceptibility, dielectric permittivity, X-ray diffraction, and visual description.

There are two soil complexes present within the site, Riverbend-Carrizo and Cristobal-Gunsight. The Riverbend-Carrizo complex is comprised of mixed stream alluvium, whereas the Cristobal-Gunsight complex is derived from fan alluvium. The Cristobal-Gunsight complex covers the majority of the site. Most of the soil samples were classified as either a sandy loam or loamy sand, with most samples containing gravel-size particles. All samples had a measured water content less than 7 percent, except for two that contained 11-percent moisture. The majority of soil samples had water content between 1 to 2-percent. Samples containing more than 3 percent were generally deeper than 1 meter.

An X-ray diffraction analysis on four soil samples indicated a basic mineralogy of quartz, calcite, mica, feldspar, magnetite, and some clay. The presence of magnetite imparted a moderate magnetic susceptibility, with volume susceptibilities generally greater than 100 by 10-5 SI.

For more details concerning the soil properties at the YPG test site, go to <u>www.uxotestsites.org</u> on the web to view the entire soils description report.

2.2.3 Test Areas

A description of the test site areas at YPG is included in Table 2.

Area	Description
Calibration Grid	Contains the 15 standard ordnance items buried in six positions at various angles and depths to allow demonstrator equipment calibration.
Blind Grid	Contains 400 grid cells in a 0.16-hectare (0.39-acre) site. The center of each grid cell contains ordnance, clutter, or nothing.

TABLE 2. TEST SITE AREAS

SECTION 3. FIELD DATA

3.1 DATE OF FIELD ACTIVITIES 5, 6, 7, 8, 10, and 12 May 2003

3.2 AREAS TESTED/NUMBER OF HOURS

Areas tested and total number of hours operated at each site are summarized in Table 3.

TABLE 3. AREAS TESTED AND
NUMBER OF HOURS

Area	Number of Hours
Calibration Lanes	9.45
Blind Grid	10.5

3.3 TEST CONDITIONS

3.3.1 Weather Conditions

A YPG weather station located approximately one mile west of the test site was used to record average temperature and precipitation on a half hour basis for each day of operation. The temperatures listed in Table 4 represent the average temperature during field operations from 0700 to 1700 hours while precipitation data represents a daily total amount of rainfall. Hourly weather logs used to generate this summary are provided in Appendix B.

Date, 2003	Average Temperature, ^o F	Total Daily Precipitation, in.
5 May	Not Available	0.00
6 May	76.5	0.00
7 May	66.1	0.00
8 May	59.4	0.00
10 May	75.25	0.00

3.3.2 Field Conditions

The field conditions remained dry throughout the demonstration.

3.3.3 Soil Moisture

Three soil probes were placed at various locations within the site to capture soil moisture data: Calibration, Mogul, and Desert Extreme areas. Measurements were collected in percent moisture and were taken twice daily (morning and afternoon) from five different soil depths (1 to 6 in., 6 to 12 in., 12 to 24 in., 24 to 36 in., and 36 to 48 in.) from each probe. Soil moisture logs are included in Appendix C.

3.4 FIELD ACTIVITIES

3.4.1 Setup/Mobilization

These activities included initial mobilization and daily equipment preparation and break down. Initial set up accounted for 3 hours and 10 minutes of demonstration time while setting up on the Calibration Lanes. Overall daily set up took 3 hours and 47 minutes while daily breakdown took 54 minutes during the four days of operation in the calibration Lanes and Blind Grid.

3.4.2 Calibration

The Calibration Lanes were surveyed on three separate days. Prior to surveying the Blind Grid, a total of 4 hours and 5 minutes spent in the calibration lanes on 6 May 2003. An additional 3 hours and 17 minutes time was spent in the calibration lanes after the Blind Grid was surveyed on 7 May 2003. Surveying of the Calibration Lanes continued the morning of 8 May 2003 for an additional 2 hours and 5 minutes.

3.4.3 Downtime Occasions

Occasions of downtime are grouped into five categories: equipment/data checks or equipment maintenance, equipment failure and repair, weather, Demonstration Site issues, or breaks/lunch. All downtime is included for the purposes of calculating labor costs (section 5) except for downtime due to Demonstration Site issues. Demonstration Site issues, while noted in the Daily Log, are considered non-chargeable downtime for the purposes of calculating labor costs and are not discussed. Breaks and lunches are not discussed either.

3.4.3.1 Equipment/data checks, maintenance. A total of 115 minutes was spent checking/ downloading data while surveying the Blind Grid.

3.4.3.2 Equipment failure or repair. No equipment failures occurred while surveying the Blind Grid.

3.4.3.3 <u>Weather</u>. No weather delays occurred during the survey.

3.4.4 Data Collection

ERDC spent 6 hours and 15 minutes collecting data in the Blind Grid. This time excludes break/lunches and downtimes described in paragraph 3.4.3.

2

3.4.5 Demobilization

The ERDC survey crew went on to conduct a survey of the Open Field. Therefore, demobilization did not occur until 22 May 2003. On that day, it took the crew 3 minutes to break down and pack up their equipment.

3.5 PROCESSING TIME

ERDC submitted the raw data from the demonstration activities on the last day of the demonstration, as required. The scoring submittal data was also provided within the required 30-day timeframe.

3.6 DEMONSTRATOR'S FIELD PERSONNEL

Field Manager:	Ryan North
Field Engineer:	Troy Broston, Eric Smith
Quality Assurance:	Don Yule
GPS Support:	Tom Berry

3.7 DEMONSTRATOR'S FIELD SURVEYING METHOD

The Calibration Lanes was surveyed in four directions: NS, SN, EW, and WE. Then, repeated in the SN orientation to check for repeatability. The Blind Grid was surveyed in the exact same method.

3.8 SUMMARY OF DAILY LOGS

Daily logs capture all field activities during this demonstration and are located in Appendix D. Activities pertinent to this specific demonstration are indicated in highlighted text.

SECTION 4. TECHNICAL PERFORMANCE RESULTS

4.1 ROC CURVES USING ALL ORDNANCE CATEGORIES

Figure 2 shows the probability of detection for the response stage (P_d^{res}) and the discrimination stage (P_d^{disc}) versus their respective probability of false positive. Figure 3 shows both probabilities plotted against their respective probability of background alarm. Both figures use horizontal lines to illustrate the performance of the demonstrator at two demonstrator-specified points: at the system noise level for the response stage, representing the point below which targets are not considered detectable, and at the demonstrator's recommended threshold level for the discrimination stage, defining the subset of targets the demonstrator would recommend digging based on discrimination. Note that all points have been rounded to protect the ground truth.

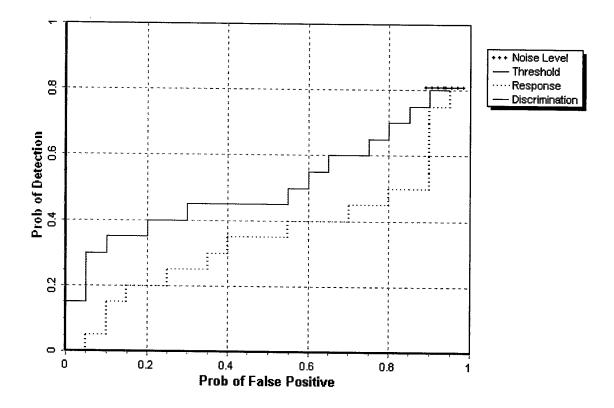


Figure 2. EM63 blind grid probability of detection for response and discrimination stages versus their respective probability of false positive over all ordnance categories combined.

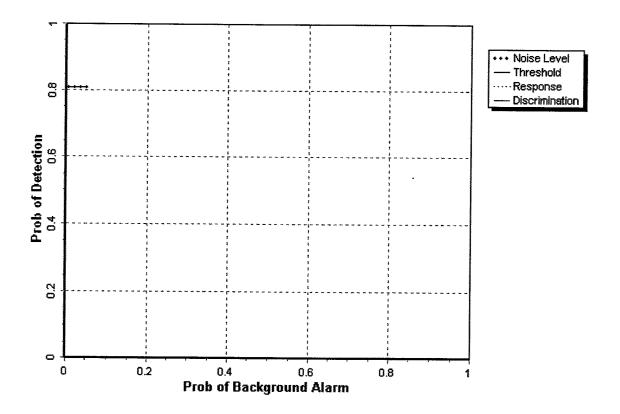


Figure 3. EM63 blind grid probability of detection for response and discrimination stages versus their respective probability of background alarm over all ordnance categories combined.

4.2 ROC CURVES USING ORDNANCE LARGER THAN 20 MM

Figure 4 shows the probability of detection for the response stage (P_d^{res}) and the discrimination stage (P_d^{disc}) versus their respective probability of false positive when only targets larger than 20 mm are scored. Figure 5 shows both probabilities plotted against their respective probability of background alarm. Both figures use horizontal lines to illustrate the performance of the demonstrator at two demonstrator-specified points: at the system noise level for the response stage, representing the point below which targets are not considered detectable, and at the demonstrator's recommended threshold level for the discrimination stage, defining the subset of targets the demonstrator would recommend digging based on discrimination. Note that all points have been rounded to protect the ground truth.

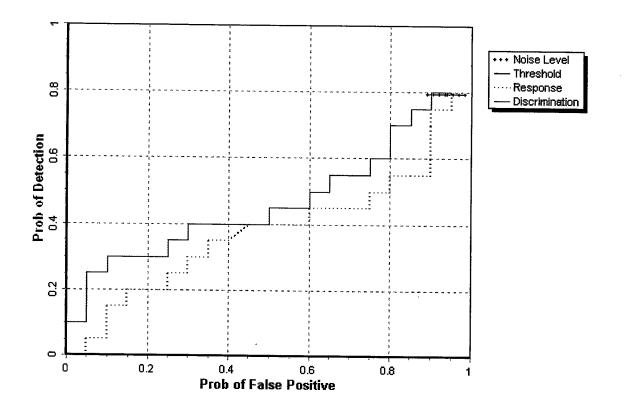


Figure 4. EM63 blind grid probability of detection for response and discrimination stages versus their respective probability of false positive for all ordnance larger than 20 mm.

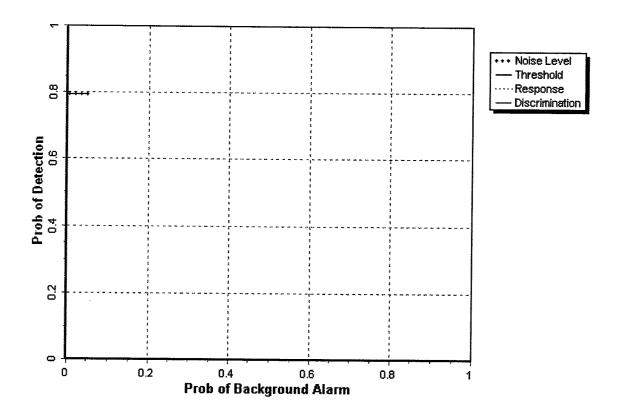


Figure 5. EM63 blind grid probability of detection for response and discrimination stages versus their respective probabilities of background alarm for all ordnance larger than 20 mm.

4.3 PERFORMANCE SUMMARIES

Results for the Blind Grid test, broken out by size, depth and nonstandard ordnance, are presented in Table 5. (For cost results, see section 5.) Results by size and depth include both standard and nonstandard ordnance. The results by size show how well the demonstrator did at detecting/discriminating ordnance of a certain caliber range (see app A for size definitions). The results are relative to the number of ordnances emplaced. Depth is measured from the closest point of anomaly to the ground surface.

The RESPONSE STAGE results are derived from the list of anomalies above the demonstrator-provided noise level. The results for the DISCRIMINATION STAGE are derived from the demonstrator's recommended threshold for optimizing UXO field cleanup by minimizing false digs and maximizing ordnance recovery. The lower 90-percent confidence limit on probability of detection and probability of false positive was calculated assuming that the number of detections and false positives are binomially distributed random variables. All results in Table 6 have been rounded to protect the ground truth. However, lower confidence limits were calculated using actual results.

				By Size			By Depth, m		
Metric	Overall	Standard	Nonstandard	Small	Medium	Large	< 0.3	0.3 to <1	>= 1
	_		RESPONSE S	TAGE					
P _d	0.80	0.80	0.80	0.80	0.75	0.95	0.90	0.80	0.30
P _d Low 90% Conf	0.74	0.73	0.67	0.70	0.59	0.75	0.82	0.65	0.08
P _{fp}	0.95	-	-	-	-	-	0.95	0.95	0.00
Pfp Low 90% Conf	0.90	-	-	-	-	-	0.89	0.82	-
P _{ba}	0.00	-	-	-	-	-	-	-	-
		DI	SCRIMINATIO	N STA	GE			·	
P _d	0.80	0.80	0.80	0.80	0.75	0.95	0.90	0.80	0.30
P _d Low 90% Conf	0.74	0.73	0.67	0.70	0.59	0.75	0.82	0.65	0.08
P _{fp}	0.95	-	-	-	-	-	0.95	0.95	0.00
Pfp Low 90% Conf	0.90	-	-	-	-	-	0.89	0.82	-
P _{ba}	0.00	-		-	~	-	-	-	_

 TABLE 5.
 SUMMARY OF BLIND GRID RESULTS FOR EM63

Response Stage Noise Level: 1.1 Recommended Discrimination Stage Threshold: 0.90

Notes: The response stage noise level and recommended discrimination stage threshold values are provided by the demonstrator.

4.4 EFFICIENCY, REJECTION RATES, AND TYPE CLASSIFICATION

Efficiency and rejection rates are calculated to quantify the discrimination ability at specific points of interest on the ROC curve: (1) at the point where no decrease in P_d is suffered (i.e., the efficiency is by definition equal to one) and (2) at the operator selected threshold. These values are reported in Table 6.

	Efficiency (E)	False Positive Rejection Rate	Background Alarm Rejection Rate
At Operating Point	1.00	0.00	0.00
With No Loss of P _d	1.00	0.01	0.00

TABLE 6. EFFICIENCY AND REJECTION RATES

At the demonstrator's recommended setting, the ordnance items that were detected and correctly discriminated were further scored on whether their correct type could be identified (table 8). Correct type examples include "20-mm projectile, 105-mm HEAT Projectile, and 2.75-inch Rocket". A list of the standard type declaration required for each ordnance item was provided to demonstrators prior to testing. For example, the standard type for the three example items are 20mmP, 105H, and 2.75in, respectively.

TABLE 7. CORRECT TYPE CLASSIFICATION OF TARGETS CORRECTLY DISCRIMINATED AS UXO

Size	% Correct		
Small	0.0		
Medium	0.0		
Large	0.0		
Overall	0.0		

Note: The demonstrator did not attempt to provide type classification.

4.5 LOCATION ACCURACY

The mean location error and standard deviations appear in Table 8. These calculations are based on average missed depth for ordnance correctly identified in the discrimination stage. Depths are measured from the closest point of the ordnance to the surface. For the Blind Grid, only depth errors are calculated, since (x, y) positions are known to be the centers of each grid square.

TABLE 8. MEAN LOCATION ERROR AND
STANDARD DEVIATION (M)

	Mean	Standard Deviation
Depth	-0.32	0.28

(Page 22 Blank)

SECTION 5. ON-SITE LABOR COSTS

A standardized estimate for labor costs associated with this effort was calculated as follows: the first person at the test site was designated "supervisor", the second person was designated "data analyst", and the third and following personnel were considered "field support". Standardized hourly labor rates were charged by title: supervisor at \$95.00/hour, data analyst at \$57.00/hour, and field support at \$28.50/hour.

Government representatives monitored on-site activity. All on-site activities were grouped into one of ten categories: initial setup/mobilization, daily setup/stop, calibration, collecting data, downtime due to break/lunch, downtime due to equipment failure, downtime due to equipment/data checks or maintenance, downtime due to weather, downtime due to demonstration site issue, or demobilization. See Appendix D for the daily activity log. See paragraph 3.4 for a summary of field activities.

The standardized cost estimate associated with the labor needed to perform the field activities is presented in Table 9. Note that calibration time includes time spent in the Calibration Lanes as well as field calibrations. "Site survey time" includes daily setup/stop time, collecting data, breaks/lunch, downtime due to equipment/data checks or maintenance, downtime due to failure, and downtime due to weather.

	No. People	Hourly Wage	Hours	Cost
		Initial Setup		
Supervisor	1	\$95.00	3.17	301.15
Data Analyst	1	57.00	3.17	180.69
Field Support	3	28.50	3.17	271.05
SubTotal				\$752.89
		Calibration		
Supervisor	1	\$95.00	9.45	897.75
Data Analyst	1	57.00	9.45	538.65
Field Support	3	28.50	9.45	807.98
SubTotal				\$2,244.38
		Site Survey		
Supervisor	1	\$95.00	10.5	997.50
Data Analyst	1	57.00	10.5	598.50
Field Support	3	28.50	10.5	897.75
SubTotal				\$2,493.75

TABLE 9. ON-SITE LABOR COSTS

See notes at end of table.

TABLE 9 (CONT'D)

	No. People	Hourly Wage	Hours	Cost
		Demobilization		······································
Supervisor	1	\$95.00	0.60	\$57.00
Data Analyst	1	57.00	0.60	\$34.20
Field Support	3	28.50	0.60	\$51.30
Subtotal				\$142.50
Total				\$5,633.52

Notes: Calibration time includes time spent in the Calibration Lanes as well as calibration before each data run.

Site Survey time includes daily setup/stop time, collecting data, breaks/lunch, downtime due to system maintenance, failure, and weather.

SECTION 6. COMPARISON OF RESULTS TO DATE

No comparisons to date.

SECTION 7. APPENDIXES

APPENDIX A. TERMS AND DEFINITIONS

GENERAL DEFINITIONS

Anomaly: Location of a system response deemed to warrant further investigation by the demonstrator for consideration as an emplaced ordnance item.

Detection: An anomaly location that is within R_{halo} of an emplaced ordnance item.

Emplaced Ordnance: An ordnance item buried by the government at a specified location in the test site.

Emplaced Clutter: A clutter item (i.e., non-ordnance item) buried by the government at a specified location in the test site.

 R_{halo} : A pre-determined radius about the periphery of an emplaced item (clutter or ordnance) within which a location identified by the demonstrator as being of interest is considered to be a response from that item. If multiple declarations lie within R_{halo} of any item (clutter or ordnance), the declaration with the highest signal output within the R_{halo} will be utilized. For the purpose of this program, a circular halo 0.5 meters in radius will be placed around the center of the object for all clutter and ordnance items less than 0.6 meters in length. When ordnance items are longer than 0.6 meters, the halo becomes an ellipse where the minor axis remains 1 meter and the major axis is equal to the length of the ordnance plus 1 meter.

Small Ordnance: Caliber of ordnance less than or equal to 40 mm (includes 20-mm projectile, 40-mm projectile, submunitions BLU-26, BLU-63, and M42).

Medium Ordnance: Caliber of ordnance greater than 40 mm and less than or equal to 81 mm (includes 57-mm projectile, 60-mm mortar, 2.75 in. Rocket, MK118 Rockeye, 81-mm mortar).

Large Ordnance: Caliber of ordnance greater than 81 mm (includes 105-mm HEAT, 105-mm projectile, 155-mm projectile, 500-pound bomb).

Shallow: Items buried less than 0.3 meter below ground surface.

Medium: Items buried greater than or equal to 0.3 meter and less than 1 meter below ground surface.

Deep: Items buried greater than or equal to 1 meter below ground surface.

Response Stage Noise Level: The level that represents the point below which anomalies are not considered detectable. Demonstrators are required to provide the recommended noise level for the Blind Grid test area.

Discrimination Stage Threshold: The demonstrator selected threshold level that they believe provides optimum performance of the system by retaining all detectable ordnance and rejecting the maximum amount of clutter. This level defines the subset of anomalies the demonstrator would recommend digging based on discrimination.

Binomially Distributed Random Variable: A random variable of the type which has only two possible outcomes, say success and failure, is repeated for n independent trials with the probability p of success and the probability 1-p of failure being the same for each trial. The number of successes x observed in the n trials is an estimate of p and is considered to be a binomially distributed random variable.

RESPONSE AND DISCRIMINATION STAGE DATA

The scoring of the demonstrator's performance is conducted in two stages. These two stages are termed the RESPONSE STAGE and DISCRIMINATION STAGE. For both stages, the probability of detection (P_d) and the false alarms are reported as receiver operating characteristic (ROC) curves. False alarms are divided into those anomalies that correspond to emplaced clutter items, measuring the probability of false positive (P_{fp}) and those that do not correspond to any known item, termed background alarms.

The RESPONSE STAGE scoring evaluates the ability of the system to detect emplaced targets without regard to ability to discriminate ordnance from other anomalies. For the RESPONSE STAGE, the demonstrator provides the scoring committee with the location and signal strength of all anomalies that the demonstrator has deemed sufficient to warrant further investigation and/or processing as potential emplaced ordnance items. This list is generated with minimal processing (e.g., this list will include all signals above the system noise threshold). As such, it represents the most inclusive list of anomalies.

The DISCRIMINATION STAGE evaluates the demonstrator's ability to correctly identify ordnance as such, and to reject clutter. For the same locations as in the RESPONSE STAGE anomaly list, the DISCRIMINATION STAGE list contains the output of the algorithms applied in the discrimination-stage processing. This list is prioritized based on the demonstrator's determination that an anomaly location is likely to contain ordnance. Thus, higher output values are indicative of higher confidence that an ordnance item is present at the specified location. For electronic signal processing, priority ranking is based on algorithm output. For other systems, priority ranking is based on human judgment. The demonstrator also selects the threshold that the demonstrator believes will provide "optimum" system performance, (i.e., that retains all the detected ordnance and rejects the maximum amount of clutter).

Note: The two lists provided by the demonstrator contain identical numbers of potential target locations. They differ only in the priority ranking of the declarations.

RESPONSE STAGE DEFINITIONS

Response Stage Probability of Detection (P_d^{res}) : $P_d^{res} = (No. of response-stage detections)/$ (No. of emplaced ordnance in the test site).

Response Stage False Positive (fp^{res}): An anomaly location that is within R_{halo} of an emplaced clutter item.

Response Stage Probability of False Positive (P_{fp}^{res}) : $P_{fp}^{res} = (No. of response-stage false positives)/(No. of emplaced clutter items).$

Response Stage Background Alarm (ba^{res}): An anomaly in a blind grid cell that contains neither emplaced ordnance nor an emplaced clutter item. An anomaly location in the open field or scenarios that is outside R_{halo} of any emplaced ordnance or emplaced clutter item.

Response Stage Probability of Background Alarm (P_{ba}^{res}): Blind Grid only: $P_{ba}^{res} = (No. of response-stage background alarms)/(No. of empty grid locations).$

Response Stage Background Alarm Rate (BAR^{res}): Open Field only: BAR^{res} = (No. of response-stage background alarms)/(arbitrary constant).

Note that the quantities P_d^{res} , P_{fp}^{res} , P_{ba}^{res} , and BAR^{res} are functions of t^{res}, the threshold applied to the response-stage signal strength. These quantities can therefore be written as $P_d^{res}(t^{res})$, $P_{fp}^{res}(t^{res})$, $P_{ba}^{res}(t^{res})$, and BAR^{res}(t^{res}).

DISCRIMINATION STAGE DEFINITIONS

Discrimination: The application of a signal processing algorithm or human judgment to response-stage data that discriminates ordnance from clutter. Discrimination should identify anomalies that the demonstrator has high confidence correspond to ordnance, as well as those that the demonstrator has high confidence correspond to nonordnance or background returns. The former should be ranked with highest priority and the latter with lowest.

Discrimination Stage Probability of Detection (P_d^{disc}) : $P_d^{disc} = (No. of discrimination-stage detections)/(No. of emplaced ordnance in the test site).$

Discrimination Stage False Positive (fp^{disc}): An anomaly location that is within R_{halo} of an emplaced clutter item.

Discrimination Stage Probability of False Positive (P_{fp}^{disc}): $P_{fp}^{disc} = (No. of discrimination stage false positives)/(No. of emplaced clutter items).$

Discrimination Stage Background Alarm (ba^{disc}): An anomaly in a blind grid cell that contains neither emplaced ordnance nor an emplaced clutter item. An anomaly location in the open field or scenarios that is outside R_{halo} of any emplaced ordnance or emplaced clutter item.

Discrimination Stage Probability of Background Alarm (P_{ba}^{disc}): $P_{ba}^{disc} = (No. of discrimination-stage background alarms)/(No. of empty grid locations).$

Discrimination Stage Background Alarm Rate (BAR^{disc}): BAR^{disc} = (No. of discrimination-stage background alarms)/(arbitrary constant).

Note that the quantities P_d^{disc} , P_{fp}^{disc} , P_{ba}^{disc} , and BAR^{disc} are functions of t^{disc}, the threshold applied to the discrimination-stage signal strength. These quantities can therefore be written as $P_d^{disc}(t^{disc})$, $P_{fp}^{disc}(t^{disc})$, $P_{ba}^{disc}(t^{disc})$, and BAR^{disc}(t^{disc}).

RECEIVER-OPERATING CHARACERISTIC (ROC) CURVES

ROC curves at both the response and discrimination stages can be constructed based on the above definitions. The ROC curves plot the relationship between P_d versus P_{fp} and P_d versus BAR or P_{ba} as the threshold applied to the signal strength is varied from its minimum (t_{min}) to its maximum (t_{max}) value.¹ Figure A-1 shows how P_d versus P_{fp} and P_d versus BAR are combined into ROC curves. Note that the "res" and "disc" superscripts have been suppressed from all the variables for clarity.

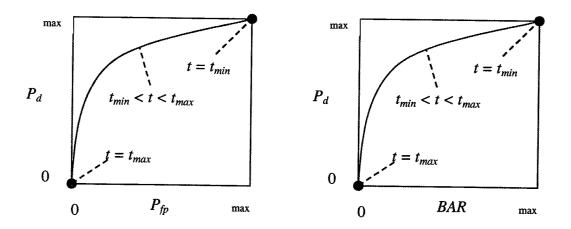


Figure A-1. ROC curves for open field testing. Each curve applies to both the response and discrimination stages.

¹Strictly speaking, ROC curves plot the P_d versus P_{ba} over a pre-determined and fixed number of detection opportunities (some of the opportunities are located over ordnance and others are located over clutter or blank spots). In an open field scenario, each system suppresses its signal strength reports until some bare-minimum signal response is received by the system. Consequently, the open field ROC curves do not have information from low signal-output locations, and, furthermore, different contractors report their signals over a different set of locations on the ground. These ROC curves are thus not true to the strict definition of ROC curves as defined in textbooks on detection theory. Note, however, that the ROC curves obtained in the Blind Grid test sites are true ROC curves.

METRICS TO CHARACTERIZE THE DISCRIMINATION STAGE

The demonstrator is also scored on efficiency and rejection ratio, which measure the effectiveness of the discrimination stage processing. The goal of discrimination is to retain the greatest number of ordnance detections from the anomaly list, while rejecting the maximum number of anomalies arising from nonordnance items. The efficiency measures the amount of detected ordnance retained by the discrimination, while the rejection ratio measures the fraction of false alarms rejected. Both measures are defined relative to the entire response list, i.e., the maximum ordnance detectable by the sensor and its accompanying false positive rate or background alarm rate.

Efficiency (E): $E = P_d^{disc}(t^{disc})/P_d^{res}(t_{min}^{res})$; Measures (at a threshold of interest), the degree to which the maximum theoretical detection performance of the sensor system (as determined by the response stage tmin) is preserved after application of discrimination techniques. Efficiency is a number between 0 and 1. An efficiency of 1 implies that all of the ordnance initially detected in the response stage was retained at the specified threshold in the discrimination stage, t^{disc} .

False Positive Rejection Rate (R_{fp}): $R_{fp} = 1 - [P_{fp}^{disc}(t^{disc})/P_{fp}^{res}(t_{min}^{res})]$; Measures (at a threshold of interest), the degree to which the sensor system's false positive performance is improved over the maximum false positive performance (as determined by the response stage tmin). The rejection rate is a number between 0 and 1. A rejection rate of 1 implies that all emplaced clutter initially detected in the response stage were correctly rejected at the specified threshold in the discrimination stage.

Background Alarm Rejection Rate (Rba):

Blind Grid: $R_{ba} = 1 - [P_{ba}^{disc}(t^{disc})/P_{ba}^{res}(t_{min}^{res})].$ Open Field: $R_{ba} = 1 - [BAR^{disc}(t^{disc})/BAR^{res}(t_{min}^{res})]).$

Measures the degree to which the discrimination stage correctly rejects background alarms initially detected in the response stage. The rejection rate is a number between 0 and 1. A rejection rate of 1 implies that all background alarms initially detected in the response stage were rejected at the specified threshold in the discrimination stage.

CHI-SQUARE COMPARISON EXPLANATION:

The Chi-square test for differences in probabilities (or $2 \ge 2$ contingency table) is used to analyze two samples drawn from two different populations to see if both populations have the same or different proportions of elements in a certain category. More specifically, two random samples are drawn, one from each population, to test the null hypothesis that the probability of event A (some specified event) is the same for both populations (ref 4).

A 2 x 2 contingency table is used in the Standardized UXO Technology Demonstration Site Program to determine if there is reason to believe that the proportion of ordnance correctly detected/discriminated by demonstrator X's system is significantly degraded by the more challenging terrain feature introduced. The test statistic of the $2 \ge 2$ contingency table is the Chi-square distribution with one degree of freedom. Since an association between the more challenging terrain feature and relatively degraded performance is sought, a one-sided test is performed. A significance level of 0.05 is chosen which sets a critical decision limit of 2.71 from the Chi-square distribution with one degree of freedom. It is a critical decision limit because if the test statistic calculated from the data exceeds this value, the two proportions tested will be considered significantly different. If the test statistic calculated from the data is less than this value, the two proportions tested will be considered not significantly different.

An exception must be applied when either a 0 or 100 percent success rate occurs in the sample data. The Chi-square test cannot be used in these instances. Instead, Fischer's test is used and the critical decision limit for one-sided tests is the chosen significance level, which in this case is 0.05. With Fischer's test, if the test statistic is less than the critical value, the proportions are considered to be significantly different.

Standardized UXO Technology Demonstration Site examples, where blind grid results are compared to those from the open field and open field results are compared to those from one of the scenarios, follow. It should be noted that a significant result does not prove a cause and effect relationship exists between the two populations of interest; however, it does serve as a tool to indicate that one data set has experienced a degradation in system performance at a large enough level than can be accounted for merely by chance or random variation. Note also that a result that is not significant indicates that there is not enough evidence to declare that anything more than chance or random variation within the same population is at work between the two data sets being compared.

Demonstrator X achieves the following overall results after surveying each of the three progressively more difficult areas using the same system (results indicate the number of ordnance detected divided by the number of ordnance emplaced):

Blind Grid	Open Field	Moguls
$P_d^{res} 100/100 = 1.0$	8/10 = .80	20/33 = .61
$P_d^{\text{disc}} 80/100 = 0.80$	6/10 = .60	8/33 = .24

 P_d^{res} : BLIND GRID versus OPEN FIELD. Using the example data above to compare probabilities of detection in the response stage, all 100 ordnance out of 100 emplaced ordnance items were detected in the blind grid while 8 ordnance out of 10 emplaced were detected in the open field. Fischer's test must be used since a 100 percent success rate occurs in the data. Fischer's test uses the four input values to calculate a test statistic of 0.0075 that is compared against the critical value of 0.05. Since the test statistic is less than the critical value, the smaller response stage detection rate (0.80) is considered to be significantly less at the 0.05 level of significance. While a significant result does not prove a cause and effect relationship exists between the change in survey area and degradation in performance, it does indicate that the detection ability of demonstrator X's system seems to have been degraded in the open field relative to results from the blind grid using the same system. P_d^{disc} : BLIND GRID versus OPEN FIELD. Using the example data above to compare probabilities of detection in the discrimination stage, 80 out of 100 emplaced ordnance items were correctly discriminated as ordnance in blind grid testing while 6 ordnance out of 10 emplaced were correctly discriminated as such in open field testing. Those four values are used to calculate a test statistic of 1.12. Since the test statistic is less than the critical value of 2.71, the two discrimination stage detection rates are considered to be not significantly different at the 0.05 level of significance.

 P_d^{res} : OPEN FIELD versus MOGULS. Using the example data above to compare probabilities of detection in the response stage, 8 out of 10 and 20 out of 33 are used to calculate a test statistic of 0.56. Since the test statistic is less than the critical value of 2.71, the two response stage detection rates are considered to be not significantly different at the 0.05 level of significance.

 P_d^{disc} : OPEN FIELD versus MOGULS. Using the example data above to compare probabilities of detection in the discrimination stage, 6 out of 10 and 8 out of 33 are used to calculate a test statistic of 2.98. Since the test statistic is greater than the critical value of 2.71, the smaller discrimination stage detection rate is considered to be significantly less at the 0.05 level of significance. While a significant result does not prove a cause and effect relationship exists between the change in survey area and degradation in performance, it does indicate that the ability of demonstrator X to correctly discriminate seems to have been degraded by the mogul terrain relative to results from the flat open field using the same system.

APPENDIX B. DAILY WEATHER LOGS

TABLE B-1. WEATHER LOG

Weat	her Da	ta from Yuma]	Provi	ng Ground
		Average		
		Temperature,		Precipitation,
Date	EDST	^ ° F	%	in.
5/7/2003		66.1	33	0.00
5/7/2003		64.8	35	0.00
5/7/2003		63.2	36	0.00
5/7/2003		62.0	37	0.00
5/7/2003 5/7/2003		61.2	37	0.00
5/7/2003		60.2 62.1	38	0.00
5/7/2003		63.4	37 38	0.00
5/7/2003		66.0	36	0.00
5/7/2003	10:00	69.2	33	0.00
5/7/2003		72.1	30	0.00
5/7/2003		74.6	26	0.00
5/7/2003		76.5	25	0.00
5/7/2003		77.4	24	0.00
5/7/2003	15:00	77.4	23	0.00
5/7/2003	16:00	77.9	23	0.00
5/7/2003	17:00	76.6	25	0.00
5/7/2003	18:00	74.7	26	0.00
5/7/2003	19:00	71.8	33	0.00
5/7/2003	20:00	69.5	36	0.00
5/7/2003	21:00	67.8	40	0.00
5/7/2003	22:00	65.8	45	0.00
5/7/2003	23:00	64.9	46	0.00
5/7/2003	24:00	63.8	47	0.00
5/8/2003	01:00	62.6	47	0.00
5/8/2003 5/8/2003	02:00 03:00	61.8	45	0.00
5/8/2003	03:00	<u>59.7</u> 58.0	45 48	0.00
5/8/2003	05:00	56.8	53	0.00
5/8/2003	06:00	55.5	56	0.00
5/8/2003	07:00	57.5	53	0.00
5/8/2003	08:00	60.5	47	0.00
5/8/2003	09:00	65.1	40	0.00
5/8/2003	10:00	67.3	36	0.00
5/8/2003	11:00	71.1	30	0.00
5/8/2003	12:00	72.9	29	0.00
5/8/2003	13:00	74.4	27	0.00
5/8/2003	14:00	76.4	24	0.00
5/8/2003	15:00	77.2	23	0.00
5/8/2003	16:00	78.1	22	0.00
5/8/2003	17:00	77.3	24	0.00
5/8/2003	18:00	76.2	22	0.00
5/8/2003	19:00	73.5	22	0.00

Weather Data from Yuma Proving Ground Average Time, |Temperature, |RH, |Precipitation, Date EDST °F % in. 5/8/2003 20:00 29 69.5 0.00 5/8/2003 21:00 67.3 28 0.00 5/8/2003 22:00 64.5 32 0.00 5/8/2003 23:00 62.8 32 0.00 5/8/2003 24:00 60.8 38 0.00 5/9/2003 01:00 58.6 43 0.00 5/9/2003 02:00 57.9 45 0.00 5/9/2003 03:00 56.1 49 0.00 5/9/2003 04:00 54.6 52 0.00 5/9/2003 05:00 55.1 52 0.00 5/9/2003 06:00 55.0 51 0.00 5/9/2003 07:00 56.7 49 0.00 5/9/2003 08:00 59.7 45 0.00 5/9/2003 09:00 62.9 39 0.00 5/9/2003 10:00 65.8 33 0.00 5/9/2003 11:00 67.7 29 0.00 5/9/2003 12:00 69.8 26 0.00 5/9/2003 13:00 71.4 22 0.00 5/9/2003 14:00 72.2 17 0.00 5/9/2003 15:00 73.0 18 0.00 5/9/2003 16:00 75.0 16 0.00 5/9/2003 17:00 76.0 14 0.00 5/9/2003 18:00 75.8 12 0.00 5/9/2003 19:00 73.5 20 0.00 5/9/2003 20:00 71.4 20 0.00 5/9/2003 21:00 68.5 22 0.00 5/9/2003 22:00 66.4 24 0.00 5/9/2003 23:00 65.9 23 0.00 5/9/2003 24:00 63.4 27 0.00 5/10/2003 01:00 60.5 34 0.00 5/10/2003 02:00 59.6 39 0.00 5/10/2003 03:00 56.9 42 0.00 5/10/2003 04:00 54.6 44 0.00 5/10/2003 05:00 53.2 43 0.00 5/10/2003 06:00 51.0 44 0.00 5/10/2003 07:00 58.1 32 0.00 5/10/2003 08:00 64.8 31 0.00 5/10/2003 09:00 68.4 25 0.00 5/10/2003 10:00 72.5 20 0.00 5/10/2003 11:00 76.3 15 0.00 5/10/2003 12:00 77.8 12 0.00 5/10/2003 13:00 79.8 13 0.00 5/10/2003 14:00 81.7 12 0.00 5/10/2003 15:00 81.8 12 0.00

TABLE B-1 (CONT'D)

83.2

10

0.00

5/10/2003 16:00

TABLE B-1 (CONT'D)

Weat	her Dat	a from Yuma F	rovi	ng Ground
		Average		
	Time,	Temperature,	RH,	Precipitation
Date	EDST	°F	%	in.
5/10/2003	17:00	83.3	10	0.00
5/10/2003	18:00	82.7	10	0.00
5/10/2003	19:00	81.6	10	0.00
5/10/2003	20:00	78.1	13	0.00
5/10/2003	21:00	75.4	15	0.00
5/10/2003	22:00	72.8	15	0.00
5/10/2003	23:00	68.9	18	0.00
5/10/2003	24:00	66.1	19	0.00
5/12/2003	01:00	71.2	21	0.00
5/12/2003	02:00	69.7	21	0.00
5/12/2003	03:00	67.2	23	0.00
5/12/2003	04:00	63.2	24	0.00
5/12/2003	05:00	63.4	25	0.00
5/12/2003	06:00	61.7	26	0.00
5/12/2003	07:00	65.9	21	0.00
5/12/2003	08:00	74.7	15	0.00
5/12/2003	09:00	81.7	14	0.00
5/12/2003	10:00	86.5	12	0.00
5/12/2003	11:00	89.3	10	0.00
5/12/2003	12:00	90.8	11	0.00
5/12/2003	13:00	93.0	8	0.00
5/12/2003	14:00	94.3	8	0.00
5/12/2003	15:00	95.7	8	0.00
5/12/2003	16:00	95.0	8	0.00
5/12/2003	17:00	94.7	9	0.00
5/12/2003	18:00	94.7	9	0.00
5/12/2003	19:00	92.2	9	0.00
5/12/2003	20:00	89.5	9	0.00
5/12/2003	21:00	85.3	10	0.00
5/12/2003	22:00	83.4	16	0.00
5/12/2003	23:00	80.4	17	0.00
5/12/2003	24:00	79.1	19	0.00
5/14/2003	01:00	76.0	21	0.00
5/14/2003	02:00	74.1	21	0.00
5/14/2003	03:00	72.4	22	0.00
5/14/2003	04:00	73.2	21	0.00
5/14/2003	05:00	71.8	21	0.00
5/14/2003	06:00	73.4	18	0.00
5/14/2003	07:00	73.2	19	0.00
5/14/2003	08:00	77.0	15	0.00
5/14/2003	09:00	82.6	13	0.00
5/14/2003	10:00	85.0	12	0.00
5/14/2003	11:00	88.9	10	0.00
5/14/2003	12:00	92.4	9	0.00
5/14/2003	13:00	94.8	8	0.00

TABLE B-1 (CO	NT'D)
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Weat	her Dat	a from Yuma F	rovi	ng Ground
		Average		l
	Time,	Temperature,	RH,	Precipitation,
Date	EDST	°F	%	in.
5/14/2003	14:00	97.4	7	0.00
5/14/2003	15:00	96.2	6	0.00
5/14/2003	16:00	96.5	7	0.00
5/14/2003	17:00	94.6	9	0.00
5/14/2003	18:00	93.8	7	0.00
5/14/2003	19:00	92.0	8	0.00
5/14/2003	20:00	87.9	10	0.00
5/14/2003	21:00	84.4	11	0.00
5/14/2003	22:00	81.9	11	0.00
5/14/2003	23:00	79.4	12	0.00
5/14/2003	24:00	78.6	12	0.00
5/15/2003	01:00	62.5	39	0.00
5/15/2003	02:00	61.1	40	0.00
5/15/2003	03:00	60.0	44	0.00
5/15/2003	04:00	58.1	49	0.00
5/15/2003	05:00	57.9	51	0.00
5/15/2003	06:00	57.0	52	0.00
5/15/2003	07:00	60.8	46	0.00
5/15/2003	08:00	64.5	45	0.00
5/15/2003	09:00	68.3	37	0.00
5/15/2003	10:00	73.1	31	0.00
5/15/2003	11:00	78.0	26	0.00
5/15/2003	12:00	81.0	23	0.00
5/15/2003	13:00	83.4	22	0.00
5/15/2003	14:00	85.7	20	0.00
5/15/2003	15:00	87.5	18	0.00
5/15/2003	16:00	89.7	17	0.00
5/15/2003	17:00	89.8	17	0.00
5/15/2003	18:00	89.9	17	0.00
5/15/2003	19:00	88.4	18	0.00
5/15/2003	20:00	86.0	19	0.00
5/15/2003	21:00	83.4	21	0.00
5/15/2003	22:00	80.2	22	0.00
5/15/2003	23:00	75.7	25	0.00
5/15/2003	24:00	73.7	26	0.00
5/16/2003	01:00	73.9	29	0.00
5/16/2003	02:00	70.8	32	0.00
5/16/2003	03:00	69.2	32	0.00
5/16/2003	04:00	68.5	33	0.00
5/16/2003	05:00	66.7	35	0.00
5/16/2003	06:00	65.4	35	0.00
5/16/2003	07:00	70.5	30	0.00
5/16/2003	08:00	79.3	23	0.00
5/16/2003	09:00	86.4	17	0.00
5/16/2003	10:00	90.0	14	0.00

TABLE B-1 (CONT'D)

Weat	her Dat	a from Yuma P	rovii	ng Ground
		Average		
Date	Time, EDST	Temperature, °F	· ·	
5/16/2003		<u> </u>	<u>%</u> 14	in.
5/16/2003				0.00
5/16/2003		94.0	13	0.00
		95.5	12	0.00
5/16/2003	14:00	97.9	11	0.00
5/16/2003	15:00	98.9	11	0.00
5/16/2003		99.9	11	0.00
5/16/2003	17:00	99.4	12	0.00
5/16/2003		99.1	10	0.00
5/16/2003	19:00	97.7	11	0.00
5/16/2003	20:00	93.1	12	0.00
5/16/2003	21:00	87.8	14	0.00
5/16/2003	22:00	86.1	16	0.00
5/16/2003	23:00	83.0	18	0.00
5/16/2003	24:00	80.4	19	0.00
5/19/2003	01:00	79.3	19	0.00
5/19/2003	02:00	77.6	19	0.00
5/19/2003		75.2	20	0.00
5/19/2003	04:00	73.4	21	0.00
5/19/2003	05:00	71.6	24	0.00
5/19/2003	06:00	68.4	25	0.00
5/19/2003	07:00	74.2	23	0.00
5/19/2003	08:00	80.5	25	0.00
5/19/2003	09:00	84.5	24	0.00
5/19/2003	10:00	89.7	14	0.00
5/19/2003	11:00	94.4	11	0.00
5/19/2003	12:00	97.3	10	0.00
5/19/2003	13:00	99.8	8	0.00
5/19/2003	14:00	101.0	8	0.00
5/19/2003	15:00	101.1	8	0.00
5/19/2003	16:00	101.3	7	0.00
5/19/2003	17:00	101.9	7	0.00
5/19/2003	18:00	101.0	7	0.00
5/19/2003	19:00	99.1	8	0.00
5/19/2003	20:00	95.2	9	0.00
5/19/2003	21:00	91.4	11	0.00
5/19/2003	22:00	88.1	11	0.00
5/19/2003	23:00	83.8	13	0.00
5/19/2003	24:00	81.7	15	0.00
6/4/2003	01:00	81.0	19	0.00
6/4/2003	02:00	80.0	22	0.00
6/4/2003	03:00	78.0	22	0.00
6/4/2003	04:00	75.5	28	0.00
6/4/2003	05:00	75.1	32	0.00
6/4/2003	06:00	74.3	34	0.00
6/4/2003	07:00	77.1	32	0.00

Weat	her Da	ta from Yuma I	Provi	ng Ground
		Average		
	Time,	Temperature,	RH,	Precipitation,
Date	EDST	°F	%	in.
6/4/2003	08:00	82.1	27	0.00
6/4/2003	09:00	87.3	22	0.00
6/4/2003	10:00	89.9	19	0.00
6/4/2003	11:00	93.9	15	0.00
6/4/2003	12:00	95.8	14	0.00
6/4/2003	13:00	98.5	13	0.00
6/4/2003	14:00	100.8	12	0.00
6/4/2003	15:00	102.5	12	0.00
6/4/2003	16:00	103.5	11	0.00
6/4/2003	17:00	103.4	10	0.00
6/4/2003	18:00	102.5	10	0.00
6/4/2003	19:00	100.0	10	0.00
6/4/2003	20:00	96.6	11	0.00
6/4/2003	21:00	94.1	11	0.00
6/4/2003	22:00	90.9	12	0.00
6/4/2003	23:00	86.7	14	0.00
6/4/2003	24:00	84.1	16	0.00

TABLE B-1 (CONT'D)

APPENDIX C. SOIL MOISTURE

Date	Time		R	ibratio eading	s (%)		Time			ogul / adings			Time]		t Extre ading	eme Ar s (%)	ea
			6 to	12 to		36 to		0 to	6 to			36 to		0 to	6 to		24 to	36 to
5/6/2003	0748			<u>24 in.</u>		<u>48 in.</u>		<u>6 in.</u>			<u>36 in.</u>	48 in.			12 in.		<u>36 in.</u>	48 in.
5/0/2005		1.8	2.2	3.7	3.6	4.0	0807	1.7	2.0	3.4	4.0	4.1	800	1.7	2.0	3.5	3.9	4.0
T 17 10 000	1237	1.8	2.2	3.6	3.6	4.0	1246	1.6	2.0	3.6	3.9	4.0	1254	1.7	2.0	3.4	3.9	4.1
5/7/2003	0723	1.8	2.2	3.6	3.6	3.9	0740	1.6	2.0	3.6	3.9	3.9	733	1.7	2.0	3.4	3.9	4.1
	1255	1.8	2.2	3.7	3.6	4.0	1310	1.6	2.0	3.5	3.9	4.0	1305	1.7	2.0	3.4	3.9	4.1
5/8/2003	0715	1.8	2.2	3.6	3.6	3.9	0724	1.6	2.0	3.6	4.0	3.9	732	1.7	2.0	3.4	3.9	4.1
	1243	1.8	2.2	3.7	3.6	3.9	1250	1.6	2.0	3.5	4.0	4.0	1258	1.7	2.0	3.4	3.9	4.1
5/9/2003	0623	1.8	2.2	3.6	3.6	3.9	0638	1.6	2.0	3.5	3.9	3.9	631	1.7	2.0	3.4	3.9	4.1
	1306	1.8	2.2	3.6	3.6	3.9	1315	1.6	2.0	3.5	3.9	3.9	1324	1.7	2.0	3.4	3.9	4.1
5/10/2003	0618	1.8	2.2	3.7	3.6	3.9	0626	1.6	2.0	3.5	3.9	4.0	634	1.7	2.0	3.4	3.9	4.1
	1203	1.8	2.2	3.6	3.6	3.9	1212	1.6	2.0	3.6	3.9	4.0	1221	1.7	2.0	3.4	3.9	4.1
5/12/2003	0630	1.8	2.2	3.7	3.6	3.9	0638	1.6	2.0	3.6	3.9	4.0	644	1.7	2.0	3.4	3.9	4.1
	1256	1.8	2.2	3.6	3.6	3.9	1305	1.6	2.0	3.5	3.9	4.0	1313	1.7	2.0	3.4	3.9	4.1
5/13/2003	0711	1.8	2.2	3.6	3.6	3.9	0719	1.7	2.0	3.6	3.9	4.0	726	1.7	2.0	3.4	3.9	4.1
	1312	1.8	2.2	3.7	3.6	4.0	1323	1.6	2.0	3.6	3.9	4.0	1332	1.7	2.0	3.4	3.9	4.1
5/14/2003	0630	1.8	2.2	3.7	3.6	4.0	0639	1.7	2.0	3.6	3.9	4.0	647	1.7	2.0	3.4	3.9	4.1
	1302	1.8	2.2	3.7	3.6	3.9	1312	1.7	2.0	3.6	4.0	4.0	1318	1.7	2.0	3.4	3.9	4.1
5/15/2003	0626	1.8	2.2	3.6	3.6	3.9	0640	1.7	2.0	3.6	3.9	4.0	648	1.7	2.0	3.4	3.9	4.1
	1302	1.8	2.2	3.7	3.6	4.0	1310	1.6	2.0	3.6	4.0	4.0	1318	1.7	2.0	3.4	3.9	4.1
5/16/2003	0622	1.8	2.2	3.7	3.6	3.9	0629	1.7	2.0	3.6	4.0	4.0	0637	1.7	2.0	3.4	3.9	4.1
	1250	1.8	2.2	3.6	3.6	3.9	1258	1.6	2.0	3.5	3.9	4.0	1305	1.7	2.0	3.4	3.9	4.1
5/17/2003	0610	1.8	2.2	3.7	3.6	3.9	0618	1.6	2.0	3.6	3.9	4.0	0626	1.7	2.0	3.4	3.9	4.1
	1319	1.8	2.2	3.6	3.6	4.0	1327	1.6	2.0	3.6	3.9	4.0	1334	1.7	2.0	3.4	3.9	4.1
5/19/2003	0600	1.8	2.2	3.6	3.6	4.0	0608	1.6	1.9	3.6	3.9	4.0	0615	1.7	2.0	3.4	4.0	4.1
	1306	1.8	2.2	3.7	3.6	4.0	1316	1.6	2.0	3.6	3.9	4.0	1324	1.7	2.0	3.4	4.0	4.1
5/20/2003	0534	1.8	2.2	3.7	3.6	4.0	0542	1.6	2.0	3.6	3.9	4.0	0550	1.7	2.0	3.4	3.9	4.1
	1311	1.8	2.2	3.7	3.6	4.0	1320	1.6	2.0	3.6	3.9	4.0	1326	1.7	2.0	3.4	4.0	4.1
5/21/2003	0547	1.8	2.2	3.7	3.6	4.0	0555	1.6	2.0	3.6	4.0	4.1	0603	1.7	2.0	3.4	4.0	4.1
	1301	1.8	2.2	3.7	3.6	4.0	1309	1.6	2.0	3.6	4.0	4.0	1316	1.7	2.0	3.4	4.0	4.1
5/22/2003	0535	1.8	2.2	3.7	3.6	4.0	0543	1.6	2.0	3.6	4.0	4.0	0550	1.7	2.0	3.4	4.0	4.1
	1303	1.8	2.2	3.7	3.6	4.0	1311	1.6	2.0	3.6	4.0	4.0	1318	1.7	2.0	3.4	4.0	4.1
5/28/2003	0722	1.8	2.2	3.7	3.6	4.0	0730	1.6	2.0	3.6	4.0	4.0	0743	1.7	2.0	3.4	4.0	4.1
	1210	1.8	2.2	3.7	3.6	4.0	1218	1.6	2.0	3.6	4.0	4.0	1225	1.7	2.0	3.4	4.0	4.1
5/29/2003	0645	1.8	2.2	3.7	3.6	4.0	0653	1.6	2.0	3.6	4.0	4.0	0700	1.7	2.0	3.4	4.0	4.1
	1222	1.8	2.2	3.7	3.6	4.0	1230	1.6	2.0	3.6	4.0	4.0	1237	1.7	2.0	3.4	4.0	4.1
5/30/2003	0600	1.8	2.2	3.7	3.6	4.0	0609	1.6	2.0	3.6	4.0	4.0	0616	1.7	2.0	3.4	4.0	4.1
	1239	1.8	2.2	3.7	3.6	4.0	1248	1.6	2.0	3.6	4.0	4.0	1255	1.7	2.0	3.4	4.0	4.1

			Status	Status								
Date	No. of Peonle	Area Tested	Start Time	Stop Time	Duration, Op Stat	Op Stat	Onerational Status	Operational Status-	Track			
20030505	4	ĽŨ	1110	1215	65	-	SET-UP MOBILIZATION	SETTING	NA	NA	HOT DRY	DRY
20030505	4	CALIBRATION LANES	1215	1330	75	3	BREAK/LUNCH	LUNCH	NA	NA	HOT	DRY
20030505	4	CALIBRATION LANES	1330	1535	125	1	SET-UP MOBILIZATION	SETTING UP EQUIPMENT	NA	NA	НОТ	DRY
20030505	4	CALIBRATION LANES	1535	1600	25	1	SET-UP MOBILIZATION	EQUIPMENT BREAKDOWN EOD	NA	NA	НОТ	DRY
20030506	4	CALIBRATION LANES	730	915	105	1	SET-UP MOBILIZATION	SETTING UP EQUIPMENT	NA	LINER	нот	DRY
20030506	4	CALIBRATION LANES	915	940	25	5	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	NA	нот	DRY
20030506	4	CALIBRATION LANES	940	1030	50	ũ	DOWNTIME DUE TO EQUIP MAINT/CHECK	CHECKING DOWNLOADING DATA	GPS	NA	НОТ	DRY
20030506	4	CALIBRATION LANES	1030	1055	25	1	SET-UP/ MOBILIZATION	SETTING UP EQUIPMENT ROPED LANES	NA	NA	HOT	DRY
20030506	4	CALIBRATION LANES	1055	1145	50	3	BREAK/LUNCH	LUNCH	NA	NA	HOT	DRY
20030506	4	CALIBRATION LANES	1145	1210	25	1	SET-UP MOBILIZATION	SETTING UP EQUIPMENT	NA	NA	НОТ	DRY
20030506	4	CALIBRATION LANES	1210	1400	110	5	COLLECTING F DATA	RUNNING CAL. LANE BIDIRECTIONAL WEST/EAST	GPS	LINER	НОТ	DRY
20030506	4	CALIBRATION LANES	1400	1500	60	5	DOWNTIME DUE TO EQUIP MAINT/CHECK	CHECKING DOWNLOADING DATA	GPS	NA	HOT	DRY
20030506	4	BLIND TEST GRID	1500	1515	15	1	SET-UP MOBILIZATION	SETTING UP EQUIPMENT	GPS	NA	нот	DRY
20030506	4	BLIND TEST GRID	1515	1530	15	5	COLLECTING C DATA L	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	нот	DRY

Note: Activities pertinent to this specific demonstration are indicated in highlighted text.

APPENDIX D. DAILY ACTIVITY LOGS

			_									ſ
Date	No. of People	Area Tested	Status Start Time	Status Stop Time	Duration, Op Stat min Code		Operational Status	Operational Status- Comments	Track Method	Pattern	Field Conditions	nditions
20030506	4	BLIND TEST GRID	1530	1545	15	2	COLLECTING DATA	RUNNING BTG LANE BIDIRECTIONAL EAST/ WEST	GPS	LINER	нот	DRY
20030506	4	BLIND TEST GRID	1545	1550	2,	5	DOWNTIME DUE TO EQUIP MAINT/CHECK	CHECKING DOWNLOADING DATA	GPS	NA	HOT	DRY
20030506	4	BLIND TEST GRID	1550	1600	10	1		EQUIPMENT BREAKDOWN EOD	AN	NA	нот	DRY
20030507	4	BLIND TEST GRID	755	840	45	1	SET-UP MOBILIZATION	SETTING UP EQUIPMENT	NA	NA	COOL	DRY
20030507	4	BLIND TEST GRID	840	905	20	2	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	COOL	DRY
20030507	4	BLIND TEST GRID	905	1105	120	2	COLLECTING DATA	RUNNING BTG LANE BIDIRECTIONAL EAST/WEST	GPS	LINER	COOL	DRY
20030507	4	BLIND TEST GRID	1105	1120	15	2	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	COOL	DRY
20030507	4	BLIND TEST GRID	1120	1150	30	5	DOWNTIME DUE TO EQUIP MAINT/CHECK	CHECKING DOWNLOADING DATA	GPS	NA	COOL	DRY
20030507	4	BLIND TEST GRID	1150	1220	30	Э	BREAK/LUNCH I	LUNCH	NA	NA	COOL	DRY
20030507	4	CALIBRATION LANES	1220	1335	75	1	SET-UP MOBILIZATION	SETTING UP EQUIPMENT ROPED LANES	NA	NA	COOL	DRY
20030507	4	CALIBRATION LANES	1335	1400	85	2	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	COOL	DRY
20030507	4	CALIBRATION LANES	1400	1420	20	2	COLLECTING F DATA E	RUNNING CAL LANE BIDIRECTIONAL N/S	GPS	LINER	COOL	DRY
20030507	4	CALIBRATION LANES	1420	1435	15	2	COLLECTING E DATA I	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	NA	COOL	DRY

Note; Activities pertinent to this specific demonstration are indicated in highlighted text.

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	onditio	DRY	DRY	DRY	DRY	DRY	DRY	DRY	DRY	ĎRY	DRY	DRY	DRY	DRY	DRY
	Field Conditions	COOL	COOL	COOL	COOL	COOL	COOL	COOL WINDY	COOL	COOL	COOL	COOL	COOL	COOL	COOL
	Pattern	LINER	LINER	NA	NA	LINER	LINER	LINER	NA	NA	LINER	LINER	LINER	NA	NA
E	Method	GPS	GPS	NA	NA	GPS	GPS	GPS	GPS	NA	GPS	GPS	GPS	NA	GPS
	Operational Status- Comments	RUNNING CAL LANE BIDIRECTIONAL N/S	EQUIPMENT WAS CALIBRATED USING CAL DISK	EQUIPMENT BREAKDOWN EOD	SETTING UP EQUIPMENT	EQUIPMENT WAS CALIBRATED USING CAL DISK	RUNNING CAL LANE BIDIRECTIONAL N/S	EQUIPMENT WAS CALIBRATED USING CAL DISK	CHECKING DOWNLOADING DATA	SETTING UP EQUIPMENT	EQUIPMENT WAS CALIBRATED USING CAL DISK	RUNNING OPEN RANGE GRID A2 BIDIRECTIONAL	EQUIPMENT WAS CALIBRATED USING CAL DISK	LUNCH	CHECKING DOWNLOADING DATA
	Operational Status	COLLECTING DATA	COLLECTING DATA	SET-UP MOBILIZATION	SET-UP MOBILIZATION	COLLECTING DATA	COLLECTING DATA	COLLECTING DATA	DOWNTIME DUE TO EQUIP MAINT/CHECK	SET-UP/ MOBILIZATION	COLLECTING DATA	COLLECTING	COLLECTING DATA	BREAK/LUNCH	DOWNTIME DUE TO EQUIP MAINT/CHECK
on Stat		2	2	1	1	2	2	2	5	1	2	2	7	3	۶ I
Duration On Stat	min	60	17	4	40	18	59	∞	40	30	7	167	5	40	20
Status	Time	1535	1552	1556	740	758	857	905	945	1015	1023	1310	1315	1355	1415
Status	Time	1435	1535	1552	700	740	758	857	905	945	1015	1023	1310	1315	1355
		CALIBRATION LANES	CALIBRATION LANES	CALIBRATION LANES	CALIBRATION LANES	CALIBRATION LANES	CALIBRATION LANES	CALIBRATION LANES	CALIBRATION LANES	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE AREA
No. of	People	4	4	4	4	4	4	4	4	4	4	4	4	4	4 A
	Date	20030507	20030507	20030507	20030508	20030508	20030508	20030508	20030508	20030508	20030508	20030508	20030508	20030508	20030508

4 4 4 4 4 4 4 0 0	E 1415	Time Time	Duranon, min	Duration, Op Stat min Code	Operational Status	Operational Status- Comments	Track Method	Dattern	Piold Conditions	مسما الجار
4 4 4 4 4 0 0			12			EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	COOL	DRY
4 4 4 4 4 0 0	E 1427	1510	43	2	COLLECTING	RUNNING OPEN RANGE GRID A2 BIDIRECTIONAL	GPS	LINER	COOL	DRY
4 4 4 4 0 0	E 1510	1517	7	2	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	COOL	DRY
4 4 4 0 0	E 1517	1600	43	5	DOWNTIME DUE TO EQUIP MAINT/CHECK	CHECKING DOWNLOADING DATA	GPS	NA	COOL	DRY
4 4 0 0	E 1600	1610	10	1	SET-UP MOBILIZATION	EQUIPMENT BREAKDOWN EOD	NA	NA	COOL	DRY
	E 630	705	35	1	SET-UP MOBILIZATION	SETTING UP EQUIPMENT	NA	NA	COOL	DRY
5 5	E 705	752	47	2	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	COOL	DRY
5	E 752	915	83	2	COLLECTING DATA	RUNNING OPEN RANGE GRID A3 BIDIRECTIONAL	GPS	LINER	COOL	DRY
	E 915	930	15	3	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	COOL	DRY
20030509 2 OPEN RANGE AREA	E 930	935	5	3	BREAK/LUNCH	BREAK	NA	AN	COOL	DRY
20030509 2 OPEN RANGE AREA	3 935	940	ŝ	4	DOWNTIME DUE TO EQUIPMENT FAILURE	FIELD COMPUTER WAS MALFUNTIONING	GPS	NA	COOL	DRY
20030509 2 OPEN RANGE	940	1050	70	ŝ	DOWNTIME DUE TO EQUIP MAINT/CHECK	SWAPPED FIELD COMPUTER BATTERY	NA	NA	COOL	DRY

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Status Status			v l								
Stop Duration, C	Start Stop Time Time	Stop	Duration, Op	åč	Dp Stat	Onorational Statuc	Operational Status-	Track			
OPEN RANGE 1050 1102 12 AREA	1050 1102 12	1102 12		-		SET-UP/ MOBILIZATION	SETTING	AN	NA	COOL	DRY
2 OPEN RANGE 1102 1220 78 2 AREA	1102 1220 78	78		5		COLLECTING DATA	RUNNING OPEN RANGE GRID A3 BIDIRECTIONAL	GPS	LINER	COOL	DRY
2 OPEN RANGE 1220 1230 10 2 AREA	1220 1230 10	10		2		COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	COOL	DRY
2 OPEN RANGE 1230 1330 60 5	1230 1330 60	60		5		DOWNTIME DUE TO EQUIP MAINT/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	COOL	DRY
2 OPEN RANGE 1330 1400 30 3	1330 1400 30	30		3		BREAK/LUNCH	LUNCH	NA	NA	COOL	DRY
4 OPEN RANGE 1400 1436 36 2	1400 1436 36	36		2		COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	COOL	DRY
4 OPEN RANGE 1436 1512 36 2 AREA	1436 1512 36	36		7		COLLECTING DATA	RUNNING OPEN RANGE GRID A2 BIDIRECTIONAL	GPS	LINER	COOL	DRY
4 OPEN RANGE 1512 1521 9 2 AREA	1512 1521 9	6		3		COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	COOL	DRY
4 OPEN RANGE 1521 1535 14 5 AREA	1521 1535 14	14		S		DOWNTIME DUE TO EQUIP MAINT/CHECK	CHECKING DOWNLOADING DATA	GPS	NA	COOL	DRY
4 OPEN RANGE 1535 1540 5 1	1535 1540 5	S		1		SET-UP I MOBILIZATION	EQUIPMENT BREAKDOWN EOD	NA	NA	COOL	DRY
4 OPEN RANGE 630 725 55 1 AREA	630 725		55 1	1		SET-UP/ MOBILIZATION	SETTING UP EQUIPMENT	NA	NA	COOL	DRY
4 OPEN RANGE 725 740 15 2 AREA	725 740 15	15		5		COLLECTING E DATA II	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	COOL	DRY
4 OPEN RANGE 740 900 80 2 AREA	740 900 80	80		7		COLLECTING F DATA C	RUNNING OPEN RANGE GRID F2 BIDIECTIONAL	GPS	LINER	COOL	DRY

Date	No. of People	Area Tested	Status Start Time	Status Stop Time	Duration, Op Stat min Code		Onerstions] Status	Operational Status-	Track			
20030510	4	OPEN RANGE AREA	006	910	10	1	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	COOL	DRY
20030510	4	OPEN RANGE AREA	910	1035	85	2	COLLECTING DATA	RUNNING OPEN RANGE GRID F2 BIDIRECTIONAL	GPS	LINER	COOL	DRY
20030510	4	OPEN RANGE AREA	1035	1040	5	3	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	HOT	DRY
20030510	4	OPEN RANGE AREA	1040	1042	2	5	DOWNTIME DUE TO EQUIP MAINT/CHECK	SWAPPED OUT MAIN BATTERY	NA	NA	HOT	DRY
20030510	2	OPEN RANGE AREA	1042	1100	18	5	DOWNTIME DUE TO EQUIP MAINT/CHECK	CHECKING DOWNLOADING DATA	GPS	NA	HOT	DRY
20030510	2	OPEN RANGE AREA	1100	1130	30	e	BREAK/LUNCH	LUNCH	NA	NA	HOT	DRY
20030510	2	BLIND TEST GRID	1130	1132	2	1	SET-UP MOBILIZATION	SETTING UP EQUIPMENT	NA	NA	HOT	DRY
20030510	2	BLIND TEST GRID	1132	1144	12	5	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	нот	DRY
20030510	2	BLIND TEST GRID	1144	1252	68	3	COLLECTING DATA	RUNNING BTG BIDIRECTIONAL NORTH/SOUTH	GPS	LINER	нот	DRY
20030510	5	BLIND TEST GRID	1252	1302	10	2	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	нот	DRY
20030510	2	BLIND TEST GRID	1302	1310	8	2	COLLECTING DATA	RUNNING BTG BIDIRECTIONAL NORTH/SOUTH	GPS	LINER	нот	DRY
20030510	7	BLIND TEST GRID	1310	1320	10	N.	DOWNTIME DUE TO EQUIP MAINT/CHECK	FIELD COMPUTER FULL/OUT OF RAM	GPS	LINER	нот	DRY

Note: Activities pertinent to this specific demonstration are indicated in highlighted text.

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			Status	Status								
Date	No. of People	Area Tested	Start Time		Duration, Op Stat min Code		Operational Status	Operational Status- Comments	Track Method	Pattern	Field Conditions	nditions
20030510	2	BLIND TEST GRID	1320	1345	25	5	DOWNTIME DUE TO EQUIP MAINT/CHECK	CHECKING DOWNLOADING DATA	GPS	NA	HOT	DRY
20030510	2	BLIND TEST GRID	1345	1350	5	1	SET-UP MOBILIZATION	EQUIPMENT BREAKDOWN EOD	NA	NA	HOT	DRY
20030512	4	BLIND TEST GRID	735	800	25	1	SET-UP/ MOBILIZATION	SETTING UP EQUIPMENT	NA	NA	нот	DRY
20030512	4	BLIND TEST GRID	800	825	25	2	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL DISK	SdD	LINER	HOT	DRY
20030512	4	BLIND TEST GRID	825	930	65	2	COLLECTING DATA	RUNNING BTG GRID F3 BIDIRECTIONAL E/W	GPS	LINER	HOT	DRY
20030512	4	BLIND TEST GRID	930	940	10	2	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	HOT	DRY
20030512	4	BLIND TEST GRID	940	1025	45	5	DOWNTIME DUE TO EQUIP MAINT/CHECK	CHECKING/ DOWNLOADING DATA	GPS	LINER	НОТ	DRY
20030512	4	OPEN RANGE AREA	1025	1045	20	1	SET-UP MOBILIZATION	SETTING UP EQUIPMENT	NA	NA	HOT	DRY
20030512	4	OPEN RANGE AREA	1045	1050	5	2	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	нот	DRY
20030512	4	OPEN RANGE AREA	1050	1206	76	2	COLLECTING DATA	RUNNING OPEN RANGE GRID F3 EAST/WEST	GPS	LINER	нот	DRY
20030512	4	OPEN RANGE AREA	1206	1215	6	S	DOWNTIME DUE TO EQUIP MAINT/CHECK	FIELD COMPUTER FULL/ OUT OF RAM	NA	NA	НОТ	DRY
20030512	4	OPEN RANGE AREA	1215	1230	15	5	DOWNTIME DUE TO EQUIP MAINT/CHECK	SWAPPED OUT FIELD COMPUTER	NA	NA	НОТ	DRY
20030512	4	OPEN RANGE AREA	1230	1245	15	5	DOWNTIME DUE TO EQUIP MAINT/CHECK	CHECKING/ DOWNLOADING DATA	SdD	NA	HOT	DRY
20030512	4	OPEN RANGE AREA	1245	1320	20	3	BREAK/LUNCH I	LUNCH	NA	NA	нот	DRY

Note: Activities pertinent to this specific demonstration are indicated in highlighted text.

	No. of		Status		Duration On Stat	1010						
Date	People	Area Tested	Time	Time	purauou, min		Operational Status	Uperational Status- Comments	Track Method	Pattern	Field Co	Field Conditions
20030512	4	OPEN RANGE AREA	1320	1330	10	7	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	NA	нот	DRY
20030512	ю	OPEN RANGE AREA	1330	1520	110	2	COLLECTING DATA	RUNNING OPEN RANGE GRID F3 EAST/WEST	GPS	LINER	HOT	DRY
20030512	e	OPEN RANGE AREA	1520	1530	10	2	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	HOT	DRY
20030512	æ	OPEN RANGE AREA	1530	1555	25	5	DOWNTIME DUE TO EQUIP MAINT/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	HOT	DRY
20030512	з	OPEN RANGE AREA	1555	1600	S	1	SET-UP MOBILIZATION	BREAKING DOWN EQUIPMENT EOD	NA	NA	HOT	DRY
20030513	3	OPEN RANGE AREA	700	810	70	1	SET-UP MOBILIZATION	SETTING UP EQUIPMENT	NA	NA	HOT	DRY
20030513	°.	OPEN RANGE AREA	810	820	10	3	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	NA	нот	DRY
20030513	3	OPEN RANGE AREA	820	940	80	5	COLLECTING DATA	RUNNING OPEN RANGE GRID F3 EAST/WEST	GPS	LINER	нот	DRY
20030513	ю	OPEN RANGE AREA	940	945	S	3	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	нот	DRY
20030513	m	OPEN RANGE AREA	945	1000	15	5	DOWNTIME DUE TO EQUIP MAINT/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	нот	DRY
20030513	m	OPEN RANGE AREA	1000	1005	S.	s	DOWNTIME DUE TO EQUIP MAINT/CHECK	SWAPPED OUT FIELD COMPUTER	NA	NA	нот	DRY
20030513	m	OPEN RANGE AREA	1005	1020	15	3	COLLECTING H DATA II	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	нот	DRY
20030513	3	OPEN RANGE AREA	1020	1050	30	2	COLLECTING F	RUNNING OPEN RANGE GRID F4 EAST/WEST	GPS	LINER	HOT	DRY

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Date	No. of People	Area Tested	Status Start Time	Status Stop Time	Duration, min	Op Stat Code	Op Stat Code	Operational Status- Comments	Track Method	Pattern	Field Conditions	nditions
20030513	æ	OPEN RANGE AREA	1050	1058	∞	2	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	HOT	DRY
20030513	ŝ	OPEN RANGE AREA	1058	1111	13	1	SET- UP/MOBILIZATIO N	SET- UP/MOBIL/IZATIO SETTING UP EQUIPMENT N	NA	NA	НОТ	DRY
20030513	æ	OPEN RANGE AREA	1111	1115	4	2	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	нот	DRY
20030513	3	OPEN RANGE AREA	1115	1155	40	2	COLLECTING DATA	RUNNING OPEN RANGE GRID F4 EAST/WEST	GPS	LINER	HOT	DRY
20030513	ŝ	OPEN RANGE AREA	1155	1202	7	3	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	нот	DRY
20030513	Э	OPEN RANGE AREA	1202	1220	18	5	DOWNTIME DUE TO EQUIP MAINT/CHECK	CHECKING DOWNLOADING DATA	GPS	NA	НОТ	DRY
20030513	ю	OPEN RANGE AREA	1220	1254	34	3	BREAK/LUNCH	LUNCH	NA	NA	HOT	DRY
20030513	e	OPEN RANGE AREA	1254	1307	13	2	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	нот	DRY
20030513	m	OPEN RANGE AREA	1307	1453	106	2	COLLECTING I DATA (RUNNING OPEN RANGE GRID F4 EAST/WEST	GPS	LINER	HOT	DRY
20030513	m	OPEN RANGE AREA	1453	1510	17	5	DOWNTIME DUE TO EQUIP MAINT/CHECK	SWAPPED OUT MAIN BATTERY	NA	NA	нот	DRY
20030513	3	OPEN RANGE AREA	1510	1513	ε	2	COLLECTING E DATA I	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	НОТ	DRY

	No. of		Status Start	Status Stop	Duration, Op Stat			Oper	Track			
Date	reople	Area Tested	Tume	Time	nin	Code	Operational Status	Comments	Method	Pattern	Field Conditions	nditions
20030513	3	OPEN RANGE AREA	1513	1544	31	2	COLLECTING DATA	RUNNING OPEN RANGE GRID E4 EAST/WEST	GPS	LINER	HOT	DRY
20030513	e	OPEN RANGE AREA	1544	1550	6	2	COLLECTING	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	нот	DRY
20030513	9	OPEN RANGE AREA	1550	1600	10	1	SET-UP MOBILIZATION	BREAKING DOWN EQUIPMENT EOD	NA	NA	HOT	DRY
20030514	4	OPEN RANGE AREA	630	725	55	1	SET-UP MOBILIZATION	SETTING UP EQUIPMENT	NA	NA	WARM	HUMID
20030514	4	OPEN RANGE AREA	725	750	25	2	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	WARM	UIMUH
20030514	4	OPEN RANGE AREA	750	905	75	2	COLLECTING DATA	RUNNING OPEN RANGE GRID E4 EAST/WEST	GPS	LINER	WARM	HUMID
20030514	4	OPEN RANGE AREA	905	913	8	2	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	WARM	HUMID
20030514	4	OPEN RANGE AREA	913	931	18	2	COLLECTING DATA	RUNNING OPEN RANGE GRID E4 EAST/WEST	GPS	LINER	WARM	HUMID
20030514	4	OPEN RANGE AREA	931	936	ŝ	2	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	WARM	DIMUH
20030514	4	OPEN RANGE AREA	936	1036	60	2	COLLECTING DATA	RUNNING OPEN RANGE GRID E4 EAST/WEST	GPS	LINER	WARM	HUMID
20030514	4	OPEN RANGE AREA	1036	1043	7	5	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	WARM	HUMID
20030514	4	OPEN RANGE AREA	1043	1055	12	1	SET-UP MOBILIZATION	SETTING UP EQUIPMENT	NA	NA	WARM	HUMID
20030514	4	OPEN RANGE AREA	1055	1105	10	s	DOWNTIME DUE TO EQUIP MAINT/CHECK	SWAPPED OUT FIELD COMPUTER	NA	NA	WARM	DIMUH

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			Status	Status								
Date	No. of People	Area Tested	Start Time	Stop 1	Duration, Op Stat min Code	Op Stat Code	Operational Status	Operational Status- Comments	Track Method	Pattern	Field Co	Field Conditions
20030514	4	OPEN RANGE AREA	1105	1115	10	1	SET-UP MOBILIZATION	RUNNING OPEN RANGE GRID A4 EAST/WEST	GPS	LINER	WARM	HUMID
20030514	4	OPEN RANGE AREA	1115	1124	6	2	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	WARM	HUMID
20030514	4	OPEN RANGE AREA	1124	1225	61	2	COLLECTING DATA	RUNNING OPEN RANGE GRID A4 EAST/WEST	GPS	LINER	WARM	HUMID
20030514	4	OPEN RANGE AREA	1225	1232	7	2	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	WARM	HUMID
20030514	4	OPEN RANGE AREA	1232	1253	21	5	DOWNTIME DUE TO EQUIP MAINT/CHECK	CHECKING DOWNLOADING DATA	GPS	LINER	WARM	HUMID
20030514	4	OPEN RANGE AREA	1253	1328	35	3	BREAK/LUNCH	LUNCH	NA	NA	WARM	HUMID
20030514	4	OPEN RANGE AREA	1328	1340	12	2	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	WARM	HUMID
20030514	4	OPEN RANGE AREA	1340	1504	84	2	COLLECTING DATA	RUNNING OPEN RANGE GRID A4 EAST/WEST	GPS	LINER	WARM	HUMID
20030514	4	OPEN RANGE AREA	1504	1513	6	Ś	DOWNTIME DUE TO EQUIP MAINT/CHECK	SWAPPED OUT FIELD COMPUTER	NA	NA	WARM	HUMID
20030514	4	OPEN RANGE AREA	1513	1516	3	2	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	WARM	HUMID
20030514	4	OPEN RANGE AREA	1516	1535	19	2	COLLECTING I DATA (RUNNING OPEN RANGE GRID A4 EAST/WEST	GPS	LINER	WARM	HUMID
20030514	4	OPEN RANGE AREA	1535	1540	S	2	COLLECTING C DATA	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	WARM	HUMID

ં	No. of		Status Start		Duration, Op Stat	Op Stat		Operational Status-	Track			
		Area Tested	Time	Time	min		Operational Status	Comments	Method	Pattern	Field Conditions	nditions
N	4	OPEN RANGE AREA	1540	1549	6	2	COLLECTING DATA	RUNNING OPEN RANGE GRID A4 EAST/WEST	GPS	LINER	WARM	HUMID
N 1	4	OPEN RANGE AREA	1549	1552	3	2	COLLECTING DATA	EQUPIMENT WAS CLAIBRATED USING CAL DISK	GPS	LINER	WARM	HUMID
N (4	OPEN RANGE AREA	715	729	14	2	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	COOL	DRY
7	4	OPEN RANGE AREA	729	750	21	2	COLLECTING DATA	RUNNING OPEN RANGE GRID A5 EAST/WEST	GPS	LINER	COOL	DRY
ম	4	OPEN RANGE AREA	750	755	S	4	DOWNTIME DUE TO EQUIPMENT FAILURE	SdD LSOT	NA	LINER	WARM	DRY
ম	4	OPEN RANGE AREA	755	1025	150	2	COLLECTING DATA	RUNNING OPEN RANGE GRID A5 EAST/WEST	GPS	LINER	HOT	DRY
ম	4	OPEN RANGE AREA	1025	1030	5	1	SET-UP MOBILIZATION	SETTING UP EQUIPMENT	GPS	LINER	HOT	DRY
ম	4	OPEN RANGE AREA	1030	1050	20	2	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	HOT	DRY
4	4	OPEN RANGE AREA	1050	1120	30	2	COLLECTING DATA	RUNNING OPEN RANGE GRID E5 EAST/WEST	GPS	LINER	HOT	DRY
4	4	OPEN RANGE AREA	1120	1130	10	5	DOWNTIME DUE TO EQUIP MAINT/CHECK	SWAPPED OUT MAIN BATTERY	NA	NA	HOT	DRY
4	4	OPEN RANGE AREA	1130	1215	45	3	BREAK/LUNCH	LUNCH	NA	NA	HOT	DRY
4	4	OPEN RANGE AREA	1215	1220	S	2	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	нот	DRY
4		OPEN RANGE AREA	1220	1345	85	2	COLLECTING DATA	RUNNING OPEN RANGE GRID E5 EAST/WEST	GPS	LINER	нот	DRY

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No. of PeopleStatus StartStatus Start54OPEN RANGE1345135054OPEN RANGE1345135054OPEN RANGE1350140554OPEN RANGE1405143054OPEN RANGE1430143754OPEN RANGE1430143754OPEN RANGE1430143754OPEN RANGE1437153564OPEN RANGE1437153564OPEN RANGE1437153564OPEN RANGE1437153564OPEN RANGE1437153514OPEN RANGE1437153514AREA1437153564OPEN RANGE154016004AREA7047047044OPEN RANGE7047044AREA7047144OPEN RANGE8398424OPEN RANGE8429034AREA7047044AREA7047044AREA7047044AREA7047044AREA7047044AREA7047044AREA7047044AREA7047044AREA7047044AREA704<										
54OPEN RANGE1345135054AREA1350140554OPEN RANGE1350140554OPEN RANGE1405143754OPEN RANGE1405143754OPEN RANGE1405143754OPEN RANGE1437153554OPEN RANGE1437153554OPEN RANGE1437153564OPEN RANGE1437153564OPEN RANGE1535154064OPEN RANGE1535154064OPEN RANGE1535154064OPEN RANGE1535154064OPEN RANGE1535154064OPEN RANGE1540160074AREA70470474OPEN RANGE7047144OPEN RANGE7048398424AREA7048398424AREA84290324OPEN RANGE84290324AREAARAGE8429034AREAARAGE8429034AREAARAGE8429034AREAARAGE8429034AREAARAGE8429034AREAARAGE8429034AREA			Duration, Op Stat min Code	Op Stat Code	Operational Status	Operational Status- Comments	Track Method	Pattern	Field Co	Field Conditions
5 4 OPEN RANGE 1350 1405 5 4 AREA 1405 1430 5 4 AREA 1430 1431 5 4 AREA 1430 1437 5 4 AREA 1430 1437 6 4 AREA 1437 1535 6 4 AREA 1540 1600 7 4 AREA 704 14 7 704 714 1 7 704 714 839 842 7 AREA 704 714 1 7 AREA 704 714 1 7 AREA 704 839 842 7 AREA AREA 704 842 4 AREA AREA 704 70	RANGE	1350	5	2	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	НОТ	DRY
5 4 OPEN RANGE 1405 1430 5 4 AREA 1437 1437 5 4 OPEN RANGE 1437 1535 5 4 OPEN RANGE 1437 1535 6 4 OPEN RANGE 1437 1535 6 4 OPEN RANGE 1437 1535 6 4 OPEN RANGE 1535 1540 6 4 AREA 1535 1540 6 4 AREA 1535 1540 6 4 AREA 1540 1600 7 4 AREA 704 714 8 4 OPEN RANGE 839 842 4 AREA 704 714 839 4 AREA 704 842 703 4 AREA 842 903 703 4 AREA </td <td>RANGE</td> <td>1405</td> <td>15</td> <td>5</td> <td>DOWNTIME DUE TO EQUIP MAINT/CHECK</td> <td>CHECKING/ DOWNLOADING DATA</td> <td>GPS</td> <td>NA</td> <td>НОТ</td> <td>DRY</td>	RANGE	1405	15	5	DOWNTIME DUE TO EQUIP MAINT/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	НОТ	DRY
5 4 OPEN RANGE 1430 1437 6 4 AREA 1437 1535 6 4 AREA 1437 1535 6 4 AREA 1437 1535 6 4 AREA 1535 1540 7 4 AREA 1535 1540 6 4 AREA 1535 1540 7 4 AREA 1540 1600 7 4 AREA 704 714 8 AREA 704 714 839 4 AREA 704 842 842 4 AREA 842 903 842 4 AREA 842 903 842 4 AREA 842 903 74 4 AREA 842 903 74 4 AREA 842 903 74 4 AREA 842 <t< td=""><td>RANGE</td><td>1430</td><td>25</td><td>1</td><td>SET-UP MOBILIZATION</td><td>SETTING UP EQUIPMENT</td><td>NA</td><td>NA</td><td>HOT</td><td>DRY</td></t<>	RANGE	1430	25	1	SET-UP MOBILIZATION	SETTING UP EQUIPMENT	NA	NA	HOT	DRY
4 OPEN RANGE 1437 1535 4 AREA 1535 1540 4 OPEN RANGE 1535 1540 4 AREA 1535 1540 4 OPEN RANGE 1540 1600 4 AREA 1540 1600 4 OPEN RANGE 630 704 4 AREA 704 714 4 OPEN RANGE 714 839 4 AREA 704 714 4 AREA 704 714 4 AREA 704 839 4 AREA 839 842 4 AREA 842 903 4 AREA 842 903 4 AREA 842 903 5 AREA 842 903	RANGE	1437	7	2	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	HOT	DRY
4 OPEN RANGE 1535 1540 4 AREA 1540 1600 4 OPEN RANGE 1540 1600 4 AREA 630 704 4 OPEN RANGE 630 704 4 AREA 704 714 4 AREA 704 714 4 AREA 714 839 4 AREA 704 714 4 AREA 842 903 4 AREA 842 903 4 AREA 842 903 4 AREA 842 903 5 AREA 842 903	RANGE	1535	58	2	COLLECTING DATA	RUNNING OPEN RANGE GRID E3 EAST/WEST	GPS	LINER	HOT	DRY
4 OPEN RANGE 1540 1600 4 AREA 630 704 4 AREA 630 704 4 AREA 704 714 4 AREA 704 714 4 AREA 714 839 4 AREA 839 842 4 AREA 839 842 4 AREA 842 903		1540	5	2	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	HOT	DRY
4 OPEN RANGE 630 704 4 AREA 630 704 4 AREA 704 714 4 AREA 704 714 4 AREA 714 839 4 OPEN RANGE 714 839 4 AREA 714 839 4 OPEN RANGE 839 842 4 AREA 839 842 4 OPEN RANGE 842 903 4 AREA 842 903 4 AREA 842 903 4 AREA 842 903	RANGE	1600	20	1	SET-UP SET-UP MOBILIZATION	BREAKING DOWN EQUIPMENT EOD	NA	NA	HOT	DRY
4 OPEN RANGE 704 714 4 AREA 714 839 4 OPEN RANGE 714 839 4 AREA 714 839 4 AREA 839 842 4 AREA 839 842 4 AREA 839 842 4 AREA 839 842 4 AREA 842 903 4 AREA 842 903 AREA OPEN RANGE 842 903	RANGE	704	34	1	SET-UP MOBILIZATION	SETTING UP EQUIPMENT	NA	NA	WARM	DRY
4 OPEN RANGE 714 839 4 AREA 839 842 4 AREA 842 903 4 AREA 842 903 AREA OPEN RANGE 842 903	RANGE	714	10	2	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	нот	DRY
4 OPEN RANGE 839 842 4 AREA 839 842 4 OPEN RANGE 842 903 AREA OPEN RANGE 842 903	RANGE	839	85	2	COLLECTING I DATA (RUNNING OPEN RANGE GRID E3 EAST/WEST	GPS	LINER	НОТ	DRY
4 OPEN RANGE 842 903 AREA OPEN RANGE	RANGE	842	3	2	COLLECTING E DATA I	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	НОТ	DRY
OPEN RANGE	RANGE	903	21	5	DOWNTIME DUE TO EQUIP MAINT/CHECK	CHECKING/ DOWNLOADING DATA	GPS	NA	НОТ	DRY
20030516 4 AREA 903 910 7	RANGE	910	7	S 1	DOWNTIME DUE TO EQUIP MAINT/CHECK	SWAPPED OUT FIELD COMPUTER	NA	NA	HOT	DRY

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Date	No. of People	Area Tested	Status Start Time	Status Stop Time	Duration, Op Stat min Code	Op Stat Code	Operational Status	Operational Status- Comments	Track Method	Pattern	Field Conditions	nditions
2030516	4	OPEN RANGE AREA	910	920	10	2	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	нот	DRY
20030516	4	OPEN RANGE AREA	920	1050	06	2	COLLECTING DATA	RUNNING OPEN RANGE GRID C5 EAST/WEST	GPS	LINER	нот	DRY
20030516	4	OPEN RANGE AREA	1050	1100	10	2	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	HOT	DRY
20030516	4	OPEN RANGE AREA	1100	1130	30	5	DOWNTIME DUE TO EQUIP MAINT/CHECK	CHECKING DOWNLOADING DATA	GPS	NA	нот	DRY
20030516	4	OPEN RANGE AREA	1130	1134	4	S	DOWNTIME DUE TO EQUIP MAINT/CHECK	SWAPPED OUT FIELD COMPUTER	NA	NA	HOT	DRY
20030516	4	OPEN RANGE AREA	1134	1136	2	2	COLLECTING	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	HOT	DRY
20030516	4	OPEN RANGE AREA	1136	1226	50	2	COLLECTING DATA	RUNNING OPEN RANGE GRID C5 EAST/WEST	GPS	LINER	HOT	DRY
20030516	4	OPEN RANGE AREA	1226	1236	10	2	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	нот	DRY
20030516	4	OPEN RANGE AREA	1236	1245	6	ŝ	DOWNTIME DUE TO EQUIP MAINT/CHECK	SWAPPED OUT MAIN BATTERY	NA	NA	нот	DRY
20030516	4	OPEN RANGE AREA	1245	1250	5	S	DOWNTIME DUE TO EQUIP MAINT/CHECK	SWAPPED OUT FIELD COMPUTER	NA	NA	нот	DRY
20030516	4	OPEN RANGE AREA	1250	1318	28	3	BREAK/LUNCH	LUNCH	NA	NA	HOT	DRY
20030516	4	OPEN RANGE AREA	1318	1330	12	3	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	нот	DRY
20030516	4	OPEN RANGE AREA	1330	1351	21	2	COLLECTING I DATA	RUNNING OPEN RANGE GRID C5 EAST/WEST	GPS	LINER	нот	DRY
20030516	4	OPEN RANGE AREA	1351	1403	12	5	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	нот	DRY
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	ions	DRY	DRY	DRY	DRY	DRY	DRY	DRY	DRY	DRY	DRY	DRY	DRY	DRY	DRY
	Field Conditions													ă 	ă
	Field (НОТ	нот	HOT	НОТ	НОТ	НОТ	нот	нот	НОТ	HOT	НОТ	НОТ	HOT	HOT
	Pattern	LINER	LINER	LINER	LINER	NA	NA	LINER	LINER	LINER	NA	NA	NA	NA	NA
	Track Method	GPS	GPS	GPS	GPS	NA	NA	GPS	GPS	GPS	NA	GPS	GPS	GPS	NA
	Operational Status- Comments	RUNNING OPEN RANGE GRID C4 EAST/WEST	EQUIPMENT WAS CALIBRATED USING CAL DISK	RUNNING OPEN RANGE GRID C4 EAST/WEST	EQUIPMENT WAS CALIBRATED USING CAL DISK	BREAKING DOWN EQUIPMENT EOD	SETTING UP EQUIPMENT	EQUIPMENT WAS CALIBRATED USING CAL DISK	RUNNING OPEN RANGE GRID C4 EAST/WEST	EQUIPMENT WAS CALIBRATED USING CAL DISK	SETTING UP EQUIPMENT	EQUIPMENT WAS CALIBRATED USING CAL DISK	RUNNING OPEN RANGE GRID D5 BIDIRECTIONAL	EQUIPMENT WAS CALIBRATED USING CAL DISK	SETTING UP EQUIPMENT
	Operational Status	COLLECTING DATA	COLLECTING DATA	COLLECTING DATA	COLLECTING DATA	SET-UP MOBILIZATION	SET-UP MOBILIZATION	COLLECTING DATA	COLLECTING DATA	COLLECTING DATA	SET-UP MOBILIZATION	COLLECTING	COLLECTING DATA	COLLECTING DATA	SET-UP MOBILIZATION
	Op Stat Code	2	2	2	2	1	1	7	2	2	1	5	2	7	
	Duration, Op Stat min Code	61	16	25	5	10	30	10	90	7	16	6	148	10	3
Status	Stop Time	1504	1520	1545	1550	1600	720	730	906	907	923	932	1200	1210	1213
Status	Start Time	1403	1504	1520	1545	1550	650	720	730	900	907	923	932	1200	1210
	Area Tested	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE AREA
	No. of People	4	4	4	4	4	4	4	4	4 7	4	4	4	4 A	4 7
	Date	20030516	20030516	20030516	20030516	20030516	20030517	20030517	20030517	20030517	20030517	20030517	20030517	20030517	20030517

	No. of				Duration, Op Stat	Op Stat		Operational Status-	Track			
Date	People	Area Tested	Time	Time	min		Operational Status	Comments	Method	Pattern	Field Conditions	nditions
20030517	4	OPEN RANGE AREA	1213	1220	7	2	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	нот	DRY
20030517	4	OPEN RANGE AREA	1220	1238	18	3	COLLECTING DATA	RUNNING OPEN RANGE GRID D4 BIDIRECTIONAL	GPS	LINER	HOT	DRY
20030517	4	OPEN RANGE AREA	1238	1250	12	2	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	HOT	DRY
20030517	4	OPEN RANGE AREA	1250	1255	5	5	DOWNTIME DUE TO EQUIP MAINT/CHECK	SWAPPED OUT MAIN BATTERY	NA	NA	HOT	DRY
20030517	4	OPEN RANGE AREA	1255	1301	ę	2	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	нот	DRY
20030517	4	OPEN RANGE AREA	1301	1400	59	2	COLLECTING DATA	RUNNING OPEN RANGE GRID D4 BIDIRECTIONAL	GPS	LINER	нот	DRY
20030517	4	OPEN RANGE AREA	1400	1405	5	5	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	нот	DRY
20030517	4	OPEN RANGE AREA	1405	1415	10	2	COLLECTING O	CONDUCTED EQUIPMENT INTERFERENCE TEST	GPS	LINER	нот	DRY
20030517	4	OPEN RANGE AREA	1415	1430	15	1	SET-UP I MOBILIZATION	BREAKING DOWN EQUIPMENT EOD	NA	NA	нот	DRY
20030519	4	OPEN RANGE AREA	645	730	45		SET-UP MOBILIZATION	SETTING UP EQUIPMENT	NA	NA	нот	DRY
20030519	4	OPEN RANGE AREA	730	735	5	2	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	HOT	DRY
20030519	4	OPEN RANGE AREA	735	915	100	2	COLLECTING I	RUNNING OPEN RANGE GRID D4 BIDIRECTIONAL	GPS	LINER	нот	DRY
20030519	4	OPEN RANGE AREA	915	923	∞	2	COLLECTING E DATA I	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	нот	DRY

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Field Conditions	DRY	DRY	DRY	DRY	DRY	DRY	DRY	DRY	DRY	DRY	DRY	DRY
Field Co	НОТ	НОТ	HOT	НОТ	HOT	HOT	HOT	HOT	НОТ	НОТ	НОТ	нот
Pattern	NA	NA	NA	LINER	LINER	LINER	NA	NA	NA	NA	LINER	LINER
Track Method	GPS	NA	NA	GPS	GPS	SdD	GPS	NA	NA	NA	GPS	GPS
Operational Status- Comments	CHECKING DOWNLOADING DATA	SWAPPED OUT FIELD COMPUTER BATTERY	SETTING UP EQUIPMENT	EQUIPMENT WAS CALIBRATED USING CAL DISK	RUNNING OPEN RANGE GRID E2 BIDIRECTIONAL	EQUIPMENT WAS CALIBRATED USING CAL DISK	CHECKING/ DOWNLOADING DATA	SWAPPED OUT FIELD COMPUTER BATTERY	SWAPPED OUT MAIN BATTERY	LUNCH	EQUIPMENT WAS CALIBRATED USING CAL DISK	RUNNING OPEN RANGE GRID E2 BIDIRECTIONAL
Operational Status	DOWNTIME DUE TO EQUIP MAINT/CHECK	DOWNTIME DUE TO EQUIP MAINT/CHECK	SET-UP MOBILIZATION	COLLECTING DATA	COLLECTING DATA	COLLECTING DATA	DOWNTIME DUE TO EQUIP MAINT/CHECK	DOWNTIME DUE TO EQUIP MAINT/CHECK	DOWNTIME DUE TO EQUIP MAINT/CHECK	BREAK/LUNCH	COLLECTING DATA	COLLECTING DATA
	S	5	1	2	2	2	5	5	5	3	2	2
Duration, Op Stat min Code	37	12	17	4	84	8	20	12	3	20	10	70
Status Stop Time	1000	1012	1029	1033	1157	1205	1225	1237	1240	1300	1310	1420
Status Start Time	923	1000	1012	1029	1033	1157	1205	1225	1237	1240	1300	1310
Area Tested	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE AREA
No. of People	4	4	4	4	4	4	4	4	4	4	4	4
Date	20030519	20030519	20030519	20030519	20030519	20030519	20030519	20030519	20030519	20030519	20030519	20030519

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Status Stop Duration, Op Stat Time min Code Operational Status
5 2
60 5
5 1
38 1
8 2
176 2
4 2
8 1
46 2
5 5 DOWNTIME DUE TO EQUIP MAINT/CHECK
10 3
10 2
12 2

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	Field Conditions	DRY	DRY	DRY	DRY	DRY	DRY	DRY	DRY	DRY	DRY	DRY	DRY	DRY
	Field C	нот	нот	НОТ	HOT	НОТ	НОТ	НОТ	НОТ	НОТ	НОТ	HOT	HOT	HOT
	Pattern	LINER	NA	NA	LINER	NA	LINER	LINER	NA	NA	NA	LINER	LINER	LINER
Track	Method	GPS	GPS	NA	GPS	NA	GPS	GPS	GPS	NA	NA	GPS	CPS	GPS
Onerational Statue.		EQUIPMENT WAS CALIBRATED USING CAL, DISK	CHECKING DOWNLOADING DATA	BREAK	EQUIPMENT WAS CALIBRATED USING CAL DISK	SWAPPED OUT GPS BATTERY	RUNNING OPEN RANGE GRID B4 BIDIRECTIONAL	EQUIPMENT WAS CALIBRATED USING CAL DISK	CHECKING DOWNLOADING DATA	BREAKING DOWN EQUIPMENT EOD	SETTING UP EQUIPMENT	EQUIPMENT WAS CALIBRATED USING CAL DISK	RUNNING OPEN RANGE GRID B3 BIDIRECTIONAL	EQUIPMENT WAS CALIBRATED USING CAL DISK
	Operational Status	COLLECTING DATA	DOWNTIME DUE TO EQUIP MAINT/CHECK	BREAK/LUNCH	COLLECTING DATA	DOWNTIME DUE TO EQUIP MAINT/CHECK	COLLECTING DATA	COLLECTING DATA	DOWNTIME DUE TO EQUIP MAINT/CHECK	SET-UP MOBILIZATION	SET-UP MOBILIZATION	COLLECTING DATA	COLLECTING I DATA 0	COLLECTING E DATA
On Stat	_	2	5	3	2	5	2	2	5	1	1	2	2	2
Duration.	min	5	36	30	10	22	120	5	20	5	30	12	98	4
Status Stop	Time	1152	1228	1258	1308	1330	1530	1535	1555	1600	610	622	800	804
Status Start	Time	1047	1152	1228	1258	1308	1330	1530	1535	1555	540	610	622	800
	Area Tested	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE AREA
No. of	People	4	4	4	4	4	4	4	4	4	3	3	3 6	3
	Date	20030520	20030520	20030520	20030520	20030520	20030520	20030520	20030520	20030520	20030521	20030521	20030521	20030521

Field Conditions	T DRY		r DRY										
¢ Pattern	NA	LINER		LINER	LINER	LINER	LINER	LINER LINER NA NA LINER	LINER LINER NA NA NA LINER	LINER LINER NA NA NA LINER LINER LINER	LINER LINER NA NA LINER LINER LINER NA	LINER LINER NA NA LINER LINER LINER NA	LINER LINER NA NA LINER LINER LINER NA NA
Track Method	NA	GPS		GPS									
Operational Status- s Comments	SWAPPED OUT FIELD COMPUTER BATTERY	EQUIPMENT WAS CALIBRATED USING CAL DISK	RUNNING OPEN RANGE	UKID B3 BIDIRECTIONAL	UKID B3 BIDIRECTIONAL EQUIPMENT WAS CALIBRATED USING CAL DISK								
Operational Status	DOWNTIME DUE TO EQUIP MAINT/CHECK	COLLECTING DATA	COLLECTING	DAIA	DALA COLLECTING DATA	Ē							
min Code	5	2	2		2	5 2	5 2	5 x x 5	2 2 5 2	5° 5 2 2 7			
min	16	6	76	-	s	۶ ۶	v s v	5 8 5 10	5 8 8 10 10 182	5 5 10 182 5 5 5	5 8 8 5 10 182 182 35 35	5 8 8 5 10 10 182 182 35 5 5	5 5 35 30 30
TANK	820	829	945	_	950	950 958	950 958 1003	950 958 1003 1013	950 958 958 1003 1013 1315	950 958 958 1003 1013 1315 1320	950 958 958 1003 1013 1315 1320 1355	950 958 958 1003 1013 1013 1315 1320 1355 1355	950 958 1003 1013 1315 1315 1320 1355 1355 1355 1360 605
Time	804	820	829	570	2	950	950	950 958 1003	950 958 958 1003 1013	950 958 958 1003 1315	950 958 958 1003 1013 1315 1320	950 958 958 1003 1013 1315 1320 1355	950 958 958 1003 1013 1013 1315 1320 1325 535
Area Tested	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE	AREA	AREA OPEN RANGE AREA	AREA OPEN RANGE AREA OPEN RANGE AREA	AREA OPEN RANGE AREA OPEN RANGE AREA OPEN RANGE AREA	AKEA OPEN RANGE AREA OPEN RANGE AREA OPEN RANGE AREA OPEN RANGE AREA	AREA OPEN RANGE AREA OPEN RANGE AREA OPEN RANGE AREA OPEN RANGE AREA OPEN RANGE AREA	AREA OPEN RANGE AREA OPEN RANGE AREA OPEN RANGE AREA OPEN RANGE AREA OPEN RANGE AREA OPEN RANGE AREA	AREA OPEN RANGE AREA OPEN RANGE AREA OPEN RANGE AREA OPEN RANGE AREA OPEN RANGE AREA OPEN RANGE AREA OPEN RANGE AREA OPEN RANGE AREA	AREA OPEN RANGE AREA OPEN RANGE AREA OPEN RANGE AREA OPEN RANGE AREA OPEN RANGE AREA OPEN RANGE AREA OPEN RANGE AREA OPEN RANGE AREA OPEN RANGE AREA
No. of People	m	e e	m	<i>m</i>		m							
Date	20030521	20030521	20030521	20030521		20030521	20030521 20030521	20030521 20030521 20030521 20030521	20030521 20030521 20030521 20030521	20030521 20030521 20030521 20030521 20030521	20030521 20030521 20030521 20030521 20030521 20030521	20030521 20030521 20030521 20030521 20030521 20030521 20030521	20030521 20030521 20030521 20030521 20030521 20030521 20030521 20030521

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Field Conditions	DRY	DRY	DRY	DRY	DRY	DRY	DRY	DRY	DRY	DRY	DRY	DRY	DRY	DRY
Field C	HOT	НОТ	HOT	нот	нот	HOT	НОТ	НОТ	HOT	HOT	НОТ	нот	нот	HOT
Pattern	LINER	NA	LINER	LINER	LINER	NA	LINER	LINER	NA	LINER	LINER	LINER	NA	NA
Track Method	GPS	NA	GPS	GPS	GPS	NA	GPS	GPS	GPS	GPS	GPS	GPS	GPS	AN
Operational Status- Comments	RUNNING OPEN RANGE GRID B2 BIDIRECTIONAL	SETTING UP EQUIPMENT	EQUIPMENT WAS CALIBRATED USING CAL DISK	RUNNING OPEN RANGE GRID G2 BIDIRECTIONAL	EQUIPMENT WAS CALIBRATED USING CAL DISK	SETTING UP EQUIPMENT	EQUIPMENT WAS CALIBRATED USING CAL DISK	RUNNING OPEN RANGE GRID G3 BIDIRECTIONAL	CHECKING DOWNLOADING DATA	EQUIPMENT WAS CALIBRATED USING CAL DISK	RUNNING OPEN RANGE GRID G3 BIDIRECTIONAL	EQUIPMENT WAS CALIBRATED USING CAL DISK	CHECKING DOWNLOADING DATA	BREAKING DOWN EQUIPMENT EOD
Operational Status	COLLECTING DATA	SET-UP MOBILIZATION	COLLECTING DATA	COLLECTING DATA	COLLECTING DATA	SET-UP MOBILIZATION	COLLECTING DATA	COLLECTING DATA	DOWNTIME DUE TO EQUIP MAINT/CHECK	COLLECTING DATA	COLLECTING DATA	COLLECTING DATA	DOWNTIME DUE TO EQUIP MAINT/CHECK	
	2	I	7	2	2	1	5	2	5	2	2	7	S D	-
Duration, Op Stat min Code	12	10	4	164	5	10	12	68	12	5	143	10	50	10
Status Stop Time	627	637	641	925	930	940	952	1100	1112	1117	1340	1350	1440	1450
Status Start Time	615	627	637	641	925	930	940	952	1100	1112	1117	1340	1350	1440
Area Tested	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE AREA
No. of People	m	m	e,	e M	en la	м м	m M	r N	Э. Ч. С.	Э <u>Ч</u> С	<u>ч</u> Э	3 70	3 9 9	3 A 0
Date	20030522	20030522	20030522	20030522	20030522	20030522	20030522	20030522	20030522	20030522	20030522	20030522	20030522	20030522

DuteNo. of buteSurfaceStateSt					_								
8 4 OPEN RANGE 715 805 50 1 SET-UP SETTING UP EQUIPMENT NA NA NA 8 4 AREA 805 820 15 2 COLLECTING EQUIPMENT WAS INNER INNER NA NA 8 4 AREA 805 820 15 2 COLLECTING EQUIPMENT WAS INNER INNER 8 4 OPEN RANGE 820 935 68 2 COLLECTING EQUIPMENT WAS INNER INNER 8 4 OPEN RANGE 932 4 2 COLLECTING EQUIPMENT WAS INNER INNER 8 4 OPEN RANGE 935 113 1 MOBILIZATING EQUIPMENT WAS INNER INNER 8 4 OPEN RANGE 935 1120 85 2 COLLECTING EXTING UP EQUIPMENT NA NA 8 OPEN RANGE 1120 85 2 COLLECTING </th <th>Date</th> <th>No. of People</th> <th></th> <th>Start Time</th> <th></th> <th>Duration, min</th> <th></th> <th></th> <th></th> <th>Track Method</th> <th>Pattern</th> <th>Field Co</th> <th>nditions</th>	Date	No. of People		Start Time		Duration, min				Track Method	Pattern	Field Co	nditions
8 4 OPEN RANGE 805 820 15 2 COLLECTING DATA EQUIPMENT WAS DISR GPS INBRAGE 105 LINER HOT 8 4 AREA 820 928 68 2 COLLECTING GRUDS 051G EASTWASET GPS LINER HOT 1 8 4 OPEN RANGE 928 932 4 2 COLLECTING GRUDS 051G EASTWASET GPS LINER HOT 1 8 4 OPEN RANGE 923 945 13 1 MOBLIZATION SETUP DATA GRUDPMENT WAS DATA NA HOT 1 8 4 OPEN RANGE 945 955 10 2 COLLECTING GRUPPMENT WAS DATA	20030528	4	OPEN RANGE AREA	715	805	50	1	SET-UP MOBILIZATION	SETTING UP EQUIPMENT	NA	NA	HOT	DRY
8 4 OPEN RANGE 820 928 68 2 COLLECTING RUNNING OPEN RANGE GPS LINER HOT 8 4 AREA 932 4 2 COLLECTING RUNNING OPEN RANGE 978 LINER HOT 8 4 OPEN RANGE 932 945 13 1 MOBILIZATING CALIBRATED USING CAL GPS LINER HOT	20030528	4	OPEN RANGE AREA	805	820	15	3	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	нот	DRY
8 4 0PEN RANGE 928 932 4 2 COLLECTING EQUIPMENT WAS DIST DERT HOT HOT 8 4 AREA 932 945 13 1 NBIT-UP SETTING UP EQUIPMENT NA NA HOT HOT 8 4 AREA 945 945 13 1 MOBILIZATING EQUIPMENT WAS CAL GPS LINER HOT HOT<	20030528	4	OPEN RANGE AREA	820	928	68	2	COLLECTING DATA	RUNNING OPEN RANGE GRIDS 03,G4 EAST/WEST	GPS	LINER	HOT	DRY
8 4 OPEN RANGE 932 945 13 1 MOBILIZATION SETTUG UP EQUIPMENT NA NA HOT 8 4 OPEN RANGE 945 955 10 2 COLLECTING EQUIPMENT WAS GPS LINER HOT 8 4 OPEN RANGE 955 1120 85 2 COLLECTING EQUIPMENT WAS GPS LINER HOT NA NA HOT NA NA HOT NA NA <td>20030528</td> <td>4</td> <td>OPEN RANGE AREA</td> <td>928</td> <td>932</td> <td>4</td> <td>2</td> <td></td> <td>EQUIPMENT WAS CALIBRATED USING CAL DISK</td> <td>GPS</td> <td>LINER</td> <td>НОТ</td> <td>DRY</td>	20030528	4	OPEN RANGE AREA	928	932	4	2		EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	НОТ	DRY
3 4 OPEN RANGE 945 955 10 2 COLLECTING EQUIPMENT WAS GPS LINER HOT 3 4 OPEN RANGE 955 1120 85 2 COLLECTING RUNNING OPEN RANGE GPS LINER HOT 4 OPEN RANGE 1120 1126 6 2 COLLECTING RUNNING OPEN RANGE GPS LINER HOT 4 AREA 1120 1126 6 2 COLLECTING RUNNING OPEN RANGE GPS LINER HOT 4 AREA 1126 1126 6 2 COLLECTING RUNNING OPEN RANGE GPS LINER HOT 4 AREA 1132 1140 8 2 COLLECTING RUNNING OPEN RANGE GPS LINER HOT HOT 4 AREA 1132 1140 8 2 COLLECTING RUNNING OPEN RANGE GPS LINER HOT HOT HOT 4 AREA 1132 1140 18 2 COLLECTING RUNNING OPEN RANGE <	20030528	4	OPEN RANGE AREA	932	945	13	-		SETTING UP EQUIPMENT	NA	NA	НОТ	DRY
3 4 OPEN RANGE 955 1120 85 2 COLLECTING RUNNING OPEN RANGE GPS LINER HOT 3 4 AREA 1120 1126 6 2 COLLECTING CALIBRATED USING CALL GPS LINER HOT 4 AREA 1126 1132 6 5 COLLECTING CALIBRATED USING CALL GPS LINER HOT 4 AREA 1126 1132 6 5 MINTCHER NA	20030528	4	OPEN RANGE AREA	945	955	10	2		EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	HOT	DRY
4 OPEN RANGE 1120 1126 6 2 COLLECTING EQUIPMENT WAS CRS LINER HOT 4 AREA 1126 1132 6 5 DOWNTIME DUE SWAPPED OUT FIELD NA NA HOT 4 AREA 1126 1132 6 5 DOWNTIME DUE SWAPPED OUT FIELD NA NA HOT 4 AREA 1132 1140 8 2 COLLECTING EQUIPMENT WAS CAL GPS LINER HOT I 4 AREA 1132 1140 8 2 COLLECTING EQUIPMENT WAS GPS LINER HOT I 4 AREA 1140 1320 100 2 COLLECTING RUNNING OPEN RANGE GPS LINER HOT I 4 AREA 1140 1320 100 2 COLLECTING RUNNING OPEN RANGE GPS LINER HOT I 4 AREA 1320 1326 6 2 COLLECTING CALIBRATED USING CAL GPS IN </td <td>20030528</td> <td>4</td> <td>OPEN RANGE AREA</td> <td>955</td> <td>1120</td> <td>85</td> <td>2</td> <td></td> <td>RUNNING OPEN RANGE GRID C2 EAST/WEST</td> <td>GPS</td> <td>LINER</td> <td>НОТ</td> <td>DRY</td>	20030528	4	OPEN RANGE AREA	955	1120	85	2		RUNNING OPEN RANGE GRID C2 EAST/WEST	GPS	LINER	НОТ	DRY
4OPEN RANGE1126113265TO EQUIP TO EQUIP MAINT/CHECKSwAPPED OUT FIELDNANAHOT4AREA1132114082COLLECTINGCOMPUTERNANAHOT4AREA1132114082COLLECTINGCALIBRATED USING CALGPSLINERHOT4AREA114013201002DATACALLBRATED USING CALGPSLINERHOTI4AREA1132132662DATAGRID C2 EASTWESTGPSLINERHOTI4AREA1320132662DATADATAGRID C2 EASTWESTGPSINHOTI4AREA1320132662DATADATADATADATAGPSINHOTI4AREA13261350245MOWTIME DUECHECKINGGPSNAHOTI4AREA13261350245MOWTIME DUECHECKINGGPSNAHOTI4AREA1350135885MOWTIME DUECWPUTERE DUT FIELDNAHOTI4AREA1350135885MOWTIME DUECWPUTERE DUT FIELDNAHOTI4AREA1350135885MOWTIME DUECWPUTERE DUT FIELDNAHOTI4AREA13501358	20030528	4	OPEN RANGE AREA	1120	1126	6	2		EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	HOT	DRY
4OPEN RANGE1132114082COLLECTINGEQUIPMENT WAS DISKHOTHOT4OPEN RANGE114013201002DATACALLBRATED USING CALGPSLINERHOT4OPEN RANGE114013201002COLLECTINGRUNNING OPEN RANGEGPSLINERHOT4OPEN RANGE132662DATACOLLECTINGEQUIPMENT WASGPSLINERHOT4OPEN RANGE132613265245DOWTIME DUECHECKINGGPSLINERHOT4OPEN RANGE13261350245DOWTIME DUECHECKINGGPSNAHOT4OPEN RANGE1350135885TO EQUIPDOWNLOADING DATAGPSNAHOT4OPEN RANGE1350135885TO EQUIPDOWNLOADING DATAGPSNAHOT4OPEN RANGE1350135885MANTICHECKDOWNTIME DUESWAPPED OUT FIELDNANAHOT	20030528		OPEN RANGE AREA	1126	1132	9	5		SWAPPED OUT FIELD COMPUTER	NA	NA	нот	DRY
4OPEN RANGE114013201002COLLECTINGRUNNING OPEN RANGEGPSLINERHOT4AREA1320132662DATAGRID C2 EASTWESTGPSLINERHOT4AREA1320132662DATACOLLECTINGEQUIPMENT WASGPSLINERHOT4AREA13261350245COLLECTINGCALIBRATED USING CALGPSLINERHOT4AREA13261350245DOWNTIME DUECHECKINGGPSNAHOT4OPEN RANGE1350135885TO EQUIPDOWNTOADING DATAGPSNAHOT4AREA1350135885TO EQUIPSWAPPED OUT FIELDNANANA	20030528		OPEN RANGE AREA	1132	1140	œ	2		EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	нот	DRY
4OPEN RANGE1320132662COLLECTINGEQUIPMENT WAS CALIBRATED USING CALOPEN RANGE132013261326245DOWNTIME DUE CHECKINGCHECKINGGPSLINERHOT4OPEN RANGE13261350245DOWNTIME DUE MAINT/CHECKCHECKINGGPSNAHOT4OPEN RANGE1350135885DOWNTIME DUE MAINT/CHECKSWAPPED OUT FIELDMAHOT4AREA1350135885TO EQUIP MAINT/CHECKSWAPPED OUT FIELDNANAHOT	20330528		OPEN RANGE AREA	1140	1320	100	2		RUNNING OPEN RANGE BRID C2 EAST/WEST	GPS	LINER	HOT	DRY
4 OPEN RANGE 1326 1350 24 5 DOWMTIME DUE CHECKING CHECKING 4 AREA 1350 1358 8 5 MAINTYCHECK DOWNLOADING DATA GPS NA HOT 4 OPEN RANGE 1350 1358 8 5 DOWNTIME DUE SWAPPED OUT FIELD NA NA 4 AREA 1350 1358 8 5 DOWNTIME DUE SWAPPED OUT FIELD NA NA	20030528		OPEN RANGE AREA	1320	1326	6	2		EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	нот	DRY
4 OPEN RANGE 1350 1358 8 5 DOWMTIME DUE SWAPPED OUT FIELD NA NA AREA 1356 1358 8 5 TO EQUIP COMPUTER BATTERY NA NA	20030528		OPEN RANGE AREA	1326	1350	24			CHECKING JOWNLOADING DATA	GPS	NA	HOT	DRY
	20030528		OPEN RANGE AREA	1350	1358	∞			WAPPED OUT FIELD OMPUTER BATTERY	NA	NA	нот	DRY

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	DRY	DRY	DRY	DRY	DRY	DRY	DRY	DRY	DRY	DRY	DRY	DRY	DRY
	HOT	НОТ	HOT	HOT	НОТ	HOT	HOT	HOT	HOT	HOT	нот	нот	нот
Dettor	NA	NA	LINER	LINER	LINER	NA	NA	NA	LINER	LINER	LINER	NA	NA
Track	NA	NA	GPS	GPS	GPS	GPS	NA	NA	GPS	CPS	GPS	GPS	NA
Operational Status- Comments	SWAPPEI BATTER}	SETTING UP EQUIPMENT	EQUIPMENT WAS CALIBRATED USING CAL DISK	RUNNING OPEN RANGE GRID D2 EAST/WEST	EQUIPMENT WAS CALIBRATED USING CAL DISK	CHECKING DOWNLOADING DATA	BREAKING DOWN EQUIPMENT EOD	SETTING UP EQUIPMENT	EQUIPMENT WAS CALIBRATED USING CAL DISK	RUNNING OPEN RANGE GRID D2 EAST/WEST	EQUIPMENT WAS CALIBRATED USING CAL DISK	CHECKING DOWNLOADING DATA	SWAPPED OUT FIELD COMPUTER
Onerational Status	DOWMTIME DUE TO EQUIP MAINT/CHECK	SET-UP MOBILIZATION	COLLECTING DATA	COLLECTING DATA	COLLECTING DATA	DOWMTIME DUE TO EQUIP MAINT/CHECK	SET-UP MOBILIZATION	SET-UP MOBILIZATION	COLLECTING DATA	COLLECTING DATA	COLLECTING DATA	DOWMTIME DUE TO EQUIP MAINT/CHECK	DOWMTIME DUE TO EQUIP MAINT/CHECK
		1	2	2	2	<u>د</u>	-	1	7	2	5	5	5 D
Duration, Op Stat min Code	7	10	7	78	10	30	10	35	10	162	4	16	3
Status Stop Time	1405	1415	1422	1540	1550	1620	1630	645	655	937	941	957	0001
Status Start Time	1358	1405	1415	1422	1540	1550	1620	610	645	655	937	941	957
Area Tested	AR	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE AREA	OPEN RANGE AREA
No. of People	4	4	4	4	4	4	4	4	4	4	4	4	4 AC
Date	20030528	20030528	20030528	20030528	20030528	20030528	20030528	20030529	20030529	20030529	20030529	20030529	20030529

Date	No. of People	Area Tested	Status Start Time	Status Stop Time	Status Stop Duration, Op Stat Time min Code	Op Stat Code	Operational Status	Operational Status- Comments	Track Method	Pattern	Rield Conditions	nditions
20030529	4	OPEN RANGE AREA	1000	1005	v	2	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	нот	DRY
20030529	4	OPEN RANGE AREA	1005	1105	60	2	COLLECTING DATA	RUNNING OPEN RANGE GRID C3 EAST/WEST	GPS	LINER	НОТ	DRY
20030529	4	OPEN RANGE AREA	1105	ШП	ę	S	DOWMTIME DUE TO EQUIP MAINT/CHECK	SWAPPED OUT FIELD COMPUTER	NA	NA	нот	DRY
20030529	4	OPEN RANGE AREA	1111	1122	11	3	COLLECTING	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	нот	DRY
20030529	4	OPEN RANGE AREA	1122	1205	43	2	COLLECTING DATA	RUNNING OPEN RANGE GRID C3 EAST/WEST	GPS	LINER	НОТ	DRY
20030529	4	OPEN RANGE AREA	1205	1210	S	5	DOWMTIME DUE TO EQUIP MAINT/CHECK	SWAPPED OUT MAIN BATTERY	NA	NA	нот	DRY
20030529	4	OPEN RANGE AREA	1210	1216	9	5	DOWMTIME DUE TO EQUIP MAINT/CHECK	SWAPPED OUT GPS BATTERY	NA	NA	нот	DRY
20030529	4	OPEN RANGE AREA	1216	1222	9	5	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	HOT	DRY
20030529	4	OPEN RANGE AREA	1222	1350	88	2	COLLECTING I DATA (RUNNING OPEN RANGE GRID C3 EAST/WEST	GPS	LINER	HOT	DRY
20030529	4	OPEN RANGE AREA	1350	1358	∞	2	COLLECTING E DATA I	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	HOT	DRY
20030529	4	OPEN RANGE AREA	1358	1420	22	ۍ ا	DOWMTIME DUE TO EQUIP MAINT/CHECK	CHECKING DOWNLOADING DATA	GPS	NA	HOT	DRY
20030529	4	OPEN RANGE AREA	1420	1425	5	5	DOWMTIME DUE TO EQUIP MAINT/CHECK	SWAPPED OUT FIELD COMPTER BATTERY	NA	NA	HOT	DRY
20030529	4	CALIBRATION PIT	1425	1437	12		SET-UP MOBILIZATION	SETTING UP EQUIPMENT	NA	NA	нот	DRY

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Date	No. of People	Area Tested	Status Start Time	Status Stop Time	Duration, Op Stat min Code		Operational Status	Operational Status- Comments	Track Method	Pattern	Field Co	Field Conditions
20030529	4	CALIBRATION PIT	1437	1447	10	2	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL. DISK	GPS	LINER	HOT	DRY
20030529	4	CALIBRATION PIT	1447	1519	32	2	COLLECTING DATA	RUNNING SIGNATURE DATA ON 155MM	GPS	LINER	нот	DRY
20030529	4	CALIBRATION PIT	1519	1536	17	2	COLLECTING DATA	RUNNING SIGNATURE DATA ON 105MM	GPS	LINER	НОТ	DRY
20030529	4	CALIBRATION PIT	1536	1548	12	2	ŊŊ	RUNNING SIGNATURE DATA ON ATC 44	GPS	LINER	HOT	DRY
20030529	4	CALIBRATION PIT	1548	1550	2	2	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	НОТ	DRY
20030529	4	CALIBRATION PIT	1550	1555	S		SET-UP I MOBILIZATION	BREAKING DOWN EQUIPMENT EOD	NA	NA	HOT	DRY
20030530	4	OPEN RANGE AREA	615	650	35	-	SET- UP/MOBILIZATIOS N	SET- UP/MOBILIZATIO SETTING UP EQUIPMENT N	NA	NA	НОТ	DRY
20030530	4	OPEN RANGE AREA	650	655	S	2	COLLECTING EDATA	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	HOT	DRY
20030530	4	OPEN RANGE AREA	655	1010	195	2	COLLECTING F DATA C	RUNNING OPEN RANGE GRID D3 EAST/WEST	GPS	LINER	нот	DRY
20030530	4	OPEN RANGE AREA	1010	1020	10	5	COLLECTING C DATA E	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	НОТ	DRY
20030530	4	OPEN RANGE AREA	1020	1040	20	5 D	DOWMTIME DUE TO EQUIP MAINT/CHECK	CHECKING DOWNLOADING DATA	GPS	NA	НОТ	DRY
20030530	4	OPEN RANGE AREA	1040	1048	∞	S D	DOWMTIME DUE TO EQUIP MAINT/CHECK	SWAPPED OUT FIELD COMPUTER BATTERY	NA	NA	НОТ	DRY
20030530	4	OPEN RANGE AREA	1048	1053	S	s D	DOWMTIME DUE S TO EQUIP MAINT/CHECK B	SWAPPED OUT MAIN BATTERY	NA	NA	НОТ	DRY

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	No. of		Start		Duration, Op Stat	Op Stat		Operational Status-	Track			
Date	People	Area Tested	Time	Time	min		Operational Status		Method	Pattern	Field Conditions	nditions
20030530	4	CALIBRATION PIT	1053	1115	22	-	SET-UP MOBILIZATION	SETTING UP EQUIPMENT	NA	NA	нот	DRY
20030530	4	CALIBRATION PIT	1115	1125	10	2	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	нот	DRY
20030530	4	CALIBRATION PIT	1125	1210	45	2	COLLECTING DATA	RUNNING SIGNATURE DATA AT A ZERO DEGREE ANGLE	GPS	LINER	HOT	DRY
20030530	4	CALIBRATION PIT	1210	1225	15		SET-UP MOBILIZATION	SETTING UP EQUIPMENT FOR 90 DEGREE ANGLE	NA	NA	HOT	DRY
20030530	4	CALIBRATION PIT	1225	1250	25	2	COLLECTING DATA	RUNNING SIGNATURE DATA AT A 90 DEGREE ANGLE	GPS	LINER	нот	DRY
20030530	4	CALIBRATION PIT	1250	1300	10		SET- UP/MOBILIZATIO	SET- UP/MOBILIZATIO SETTING UP EQUIPMENT N	NA	NA	нот	DRY
20030530	4	CALIBRATION PIT	1300	1320	20	5	COLLECTING DATA	RUNNING SIGNATURE DATA AT A 45 DEGREE ANGLE	GPS	LINER	нот	DRY
20030530	4	CALIBRATION PIT	1320	1330	10	2	COLLECTING DATA	EQUIPMENT WAS CALIBRATED USING CAL DISK	GPS	LINER	нот	DRY
20030530	4	CALIBRATION PIT	1330	1350	20	5	DOWMTIME DUE TO EQUIP MAINT/CHECK	CHECKING/DOWNLOADIN G DATA	GPS	NA	нот	DRY
20030530	4	CALIBRATION PIT	1350	1600	130	7	DEMOBILIZE	END OF TEST	NA	NA	нот	DRY

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APPENDIX E. REFERENCES

- 1. Standardized UXO Technology Demonstration Site Handbook, DTC Project No. 8-CO-160-000-473, Report No. ATC-8349, March 2002.
- 2. Aberdeen Proving Ground Soil Survey Report, October 1998.
- 3. Data Summary, UXO Standardized Test Site: APG Soils Description, May 2002.
- 4. Data Summary, UXO standardized Test Site: YPG Soils Description, May 2003.
- 5. Practical Nonparametric Statistics, W.J. Conover, John Wiley & Sons, 1980, pages 144 through 151.

APPENDIX F. ABBREVIATIONS

AEC	=	U.S. Army Environmental Center	
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- APG = Aberdeen Proving Ground
- ASCII = American Standard Code for International Interchange
- ATC = U.S. Army Aberdeen Test Center
- ERDC = U.S. Army Corps of Engineers Engineering Research and Development Center
- ESTCP = Environmental Security Technology Certification Program
- EQT = Army Environmental Quality Technology Program
- GPS = Global Positioning System
- JPG = Jefferson Proving Ground
- POC = point of contact

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- QA = quality assurance
- QC = quality control
- ROC = receiver-operating characteristic
- RTK = real time kinematic

SERDP = Strategic Environmental Research and Development Program

- UXO = unexploded ordnance
- YPG = U.S. Army Yuma Proving Ground

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