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1	Specific and selective biosensor for Salmonella and its detection in the environment
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3	E. V. Olsen ^a , S.T. Pathirana ^b , A.M. Samoylov ^b , J.M. Barbaree ^a , B.A. Chin ^c , W.C. Neely ^d , and V.
4	Vodyanoy ^{b*}
5	^a Department of Biological Sciences, Auburn University, Alabama 36849, USA
6	^b Department of Anatomy, Physiology and Pharmacology, Auburn University, Alabama 36849,
7	USA
8	^c Material Research & Education Center, Auburn University, Alabama 36849, USA
9	^d Department of Chemistry, Auburn University, Alabama 36849, USA
10	
11	*Corresponding author. Tel.: +1-334-844-5405; fax:+1-334-844-5388.
12	E-mail address: vodyavi@vetmed.auburn.edu (V. Vodyanoy)
13	Complete correspondence address: Vitaly Vodyanoy, Department of Anatomy, Physiology and
14	Pharmacology, 109 Greene Hall, Auburn University, AL 36849, USA
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[·] Corresponding author. Tel.: 1-334-844-5405; e-mail: vodyavi@vetmed.auburn.edu

1 Abstract

The specific and selective detection of Salmonella typhymurium based on the use of a 2 polyclonal antibody immobilized by the Langmuir-Blodgett method on the surface a quartz 3 crystal acoustic wave device was demonstrated in liquid samples. These biosensors were 4 selective to Salmonella typhymurium in the presence of large concentrations of Escherichia coli 5 O157:H7. They were also specific to Salmonella typhymurium since bacteria preincubated with 6 free antibody produced no signal. Dark-field and electron microscopy showed that two different 7 antibodies, polyvalent somatic O and flagellar H7, were immobilized on the sensor surface 8 producing two distinct attachments of bacteria at the liquid/solid interface. The somatic O 9 antibody exhibits a rigid, binding, while the flagellar H7 antibody forms a flexible connection 10 allowing a large degree of freedom. When the attachment of bacteria was rigid and strong, the 11 responses of the acoustic wave sensors correlated with changes in the mass of bacteria present at 12 the liquid-solid interface. In contrast, when attachment was flexible the sensor signals were 13 inversely proportional to the additional mass of bound bacteria. This difference is probably 14 determined by the interfacial viscoelasticity and by acoustic and electromagnetic coupling. The 15 signals of environmentally aged sensors with either predominately rigid or flexible positioning of 16 bacteria were correlated with changes in mass at the liquid-solid interface. Sensors with O or H 17 18 type of binding could be used for analytical purposes.

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20 Keywords: Acoustic wave device; biosensor; Langmuir-Blodgett monolayer; antibody

1 **1. Introduction**

The thickness-shear-mode (TSM) acoustic wave sensor is proven to be an excellent 2 analytical tool for the study of specific molecular interactions at the solid-liquid interface (Bunde 3 et al., 1998, O'Sullivan and Guilbault, 1999, Cavicacute, et al., 1999, Ivnitski, et al., 1999, 4 Kaspar et al., 2000). Acoustic waves in TSM are excited by the application of a radio frequency 5 alternating voltage to the piezoelectric crystal. Changes in the resonance frequency are usually 6 attributed to the effect of the added mass due to the binding at the solid-liquid interface. Acoustic 7 wave sensors with immobilized biological recognition molecules (biosensors) were utilized for 8 the real-time study of the adsorption of biochemical macromolecules (Ghafouri and Thompson, 9 1999). Acoustic wave devices were shown to be quite specific immunosensors in complex 10 biological media containing cells and human serum (Dahint, et al., 1999). The theoretical model 11 of the responses of TSM resonators was proven experimentally under various loading conditions, 12 including an ideal mass layer (thin layers of gold and SiO₂), a semi-infinite fluid (glycerol in 13 water), and a viscoelastic layer exemplified by thin layers of oil (Martin et al., 1991, Bandey et 14 al., 1999). When TSM crystals were exposed to relatively large protein and polysaccharide 15 molecules, the responses obtained for those interactions were not correlated with change in mass 16 imposed at the liquid-solid interface (Ghafouri and Thompson, 1999). The authors ascribed this 17 phenomenon to viscoelastic and acoustic coupling at the interface. One could expect even more 18 complicated interfacial properties when the TSM sensor is exposed to much larger species, like 19 viruses and bacteria. Electromechanical forces created by live and moving organisms may 20 contribute to the apparent mass of the bacteria. Factors such as nutrition, growth, differentiation, 21 chemical signaling, and mutagenic exposure, are important in controlling the bacterial physical 22 state. The bacterial cell (e.g. E. coli), is about one million times heavier than a typical (150 kD) 23

1	antibody molecule (Neidhardt, 1987). Many bacteria are involved in various movements
2	controlled by flagella, Brownian motion, chemotaxis, swimming behavior, adaptation, and other
3	cell phenomena (Alberts et al., 1989). The ability to bind may also depend on fimbriae and
4	properties of single cells to associate and form colonies. The interaction of bacteria with the
5	biosensor may become dependent on environmental conditions.
6	The acoustic devices theory and biological applications were recently reviewed (Kaspar et
7	al., 2000, Cavicacute, et al., 1999, Ivnitski, et al., 1999).
8	In our previous work we demonstrated the feasibility of a biosensor based on Langmuir-
9	Blodgett monolayers of an antibody for the rapid and sensitive detection of Salmonella
10	typhimurium in liquid samples (Pathirana, et al., 2000). In the present work we investigated
11	specificity and selectivity of the biosensor under environmental conditions and after
12	environmental aging of the biosensors. Additionally, we studied the effects on the biosensor
13	signal of bacterial positioning at the liquid-surface interface.

14 2. Materials and methods

15 2.1. Cultures.

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Salmonella typhimurium and Escherichia coli O157:H7 cultures from the Auburn
 University culture collection were used in these experiments. Each culture was confirmed for
 identity using traditional biochemical, cell morphology, and serologic tests. The cultures were
 maintained on Trypticase agar (TSA) slants.

20 2.2. Growth of cultures and dilutions.

Each culture was streaked for isolation on TSA plates before inoculation of a fresh culture to trypticase soy broth for overnight incubation at 37 °C in a shaking water bath

incubator. The cells were then washed by centrifugation (3500 rpm for 10 minutes) of the broth
and resuspension in 10 mL of sterile phosphate buffered saline (PBS) (pH 7.0) then repeating
centrifugation and resuspension in 2 mL PBS. Aseptic procedures were used throughout the
procedure . Serial dilutions were made with PBS. All tubes were shaken before each pipetting to
assure mixing before delivery.

6 2.3. Colony forming unit (CFU) determinations.

The number of viable cells in each dilution was determined by spread plating 0.1 mL of each dilution onto duplicate plates of TSA, and incubating 48 hours before making a final count of the CFU/ml and calculating the average CFU based on dilutions yielding 30-300 colonies/plate. The tubes with diluted cells were immediately placed on ice and delivered to another laboratory for testing with the sensor.

12 2.4. Antibodies.

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Antibodies used as capture antibodies on the membranes attached to the sensor were obtained from Oxoid, Inc. (Ogdensburg, NY). For *S. typhimurium*, a polyvalent somatic O antibody specific for most *Salmonella* serovars was employed. To capture *E. coli* O157:H7, polyvalent H7 (flagellar) antibodies were used. In most cases, the same lot of antibody was used throughout. Reactivity was checked against the target bacterium by a slide agglutination test.

18 2.5. Procedures for examining the reactivity of antibodies.

Three types of tests were employed to examine the reactivity of antibodies:
(1) a dot blot ELISA test using nitrocellulose or nylon filters with antigen fixed and subjected to
chromogenic anti-mouse (for monoclonal antibody) or anti-animal-based antibody conjugated
with enzyme assay; (2) kit tests for target organisms; and (3) agglutination tests.

1 2.6. Monolayer techniques.

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2 2.6.1. Surface Film Balance.

Measurements of surface pressure were performed using a Langmuir-Blodgett film 3 balance KSV 2200 LB (KSV-Chemicals, Finland). This fully computerized system contains a 4 Wilhelmy-type surface balance (range 0-100 mN/m; sensitivity 0.05 mN/m), a Teflon trough 5 (45x15 cm²), a variable speed motor-driven Teflon barrier (0-200 mm/min), and a laminar flow 6 hood. The trough was mounted on a 200 kg marble table. Vibration control was provided by 7 interposing rubber shock absorbers, and by mounting the laminar flow hood on a separate bench. 8 Surface pressure was monitored by the use of a sandblasted platinum plate of 4 cm perimeter. 9 Temperature of the subphase was controlled ($\pm 0.1 \text{ oC}$) by water circulation through a quartz 10 tube coil on the bottom of the trough. Temperature was measured by a thermistor located just 11 below the water interface. Surface pressure data were collected during slow, steady-state 12 compression of the monolayers 13

14 2.6.2. Monolayer formation and deposition.

Phospholipid monolayers. Phospholipid solutions were spread on the surface balance as hexane solutions (1 mg/mL) containing 2% ethanol (Ito et al., 1989). The subphase used in the experiments was a solution containing 55 mM KCl, 4 mM NaCl, 0.1 mM CaCl₂, 1 mM MgCl₂ and 2 mM 3-(N-morpholino)-propanesulfonic acid (MOPS) made with deionized double distilled water (pH adjusted to 7.4 with KOH).

20 Monolayers with immobilized antibodies. The quartz crystals with gold electrodes for the 21 acoustic wave sensor were cleaned by treatment with 50 % (v/v) HNO₃ and were rinsed in 22 running distilled water until the acid was completely removed. The quartz crystals were then

dried and stored until use. The monolayer was formed on the air-liquid interface by allowing the 1 spreading solution to run down an inclined wettable planar surface that is partially submersed 2 into the subphase. One hundred and fifty μL of the antiserum was spread on the subphase surface 3 by allowing it to flow down a wet glass plate that crossed the interface. The flow rate down the 4 plate was maintained at about 0.1 mL/min. After spreading, the glass plate was removed, and the 5 monolayer was allowed to equilibrate and stabilize for 10 minutes at 19 ± 0.1 °C. The 6 monolayer was then compressed at a rate of 30 mm/min and the vertical film deposition was 7 carried out with a vertical rate of 4.5 mm/min and at a constant surface pressure of 23 mN/m. 8 Seven monolayers of the Salmonella antibody film were transferred to the gold surface of the 9 quartz crystals in this manner. Monolayers containing antibodies were transferred at a constant 10 surface pressure onto the round (d=1") quartz crystals with gold electrodes for acoustic wave 11 device measurements, or onto standard microscope slides (test slides) for visual observations and 12 13 cell counting.

14 2.7. Bacteria binding measurements.

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15 2.7.1 Acoustic Wave Device Measurements (AWD).

Measurements were carried out using Maxtek PM-740 or TM-400 monitors (Maxtek Inc, Santa Fe Springs, CA) with a frequency resolution of 0.5 Hz at 5 MHz. The devices were capable of working in both single and dual probe modes. Voltage output of the Maxtek device was recorded and analyzed using a standard personal computer, data acquisition card and software. The voltage output from the Maxtek device is directly related to the resonance frequency of the quartz crystal sensor. Changes in the resonance frequency of the quartz crystal sensor were used to monitor the binding of bacteria to the sensor surface. The observed changes in the resonance frequency of the quartz crystal sensor during binding of bacteria is hypothesized
to be due both to viscoelastic changes of the LB film-bacteria-near surface fluid media and the
mass change associated with the binding of bacteria.

4 2.7.2. AWD quartz crystal sensors.

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5 AT-cut planar quartz crystals with a 5 MHz nominal oscillating frequency were 6 purchased from Maxtek, Inc. Circular gold electrodes were deposited on both sides of the crystal 7 for the electrical connection to the oscillatory circuit.

8 2.7.3. Binding measurements.

The Quartz crystal microbalance was calibrated by the deposition of well-characterized 9 stearic acid monolayers. The sensor covered with the antibody film was positioned in the probe 10 arm of the instrument just before delivery of test solutions. Immediately after the recording was 11 started, 1000 μ L of the control solution was delivered with a pipette to the dry sensor surface and 12 the voltage was recorded for 4 - 8 minutes. Then the test solution was carefully removed with a 13 plastic pipette tip. After removal of the control solution a new recording was initiated and 1000 14 μL of solution containing bacteria was added and the same measuring procedure was followed. 15 Temperature of the test solutions was controlled (± 0.1 °C). In order to examine the specificity 16 of bacteria binding by antibody immobilized in the sensor membrane, the sensor was exposed to 17 bacteria previously incubated with a solution of free antibody for the optimized contact time. 18 After all the solutions were tested, the sensor crystal was carefully removed and placed in 19 absolute ethanol and subsequently cleaned with concentrated nitric acid. All the equipment used 20 in the experiment was sterilized with ethanol. The data collected were stored and analyzed off 21 22 line.

1 2.8. Dark-field microscopy.

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Optical observation and recording of bacteria binding were performed with an Olympus 2 microscope fitted with a 100-W mercury lamp illumination source, a polarizer, a Naessens dark-3 field condenser (COSE Corp., Canada) and a 100× objective (oil, NA 1.4). The dark-field images 4 (Vodyanoy et al., 1994) were directed to a DEI-470T Optronics CCD Video Camera System 5 (Optronics Engineering, CA). The system provided real-time, direct-view optical images of high 6 resolution. The samples needed no freezing, dehydration, staining, shadowing, marking, or any 7 other manipulation. They were observed in the natural aqueous environment. A direct count of 8 bacteria was used to determine their concentrations in liquid samples. The count of bound 9 bacteria in the presence of a large concentrations of motile cells was used to estimate the surface 10 concentration of specific antibody. 11

12 *2.9.1*

2.9. Environmental aging of sensors

One hundred-forty eight Salmonella antibody sensors and 35 test slides were fabricated 13 by transferring 7 monolayers of Salmonella antibody serum to each of the quartz crystal 14 substrates and microscope slides using the LB technique. One hundred-forty samples were 15 divided into five sets: a control set, and sets with samples immersed in raw chicken exudate at 16 temperatures ~ 4°C, 11°C, 23°C and 33°C (Olsen, E. 2000). Each set of crystals was divided 17 into groups of 4 crystals and 1 test slide. The control group was tested immediately after 18 production. Each day for 7 days, 4 sensors and 1 test slide from other groups were removed from 19 the chicken exudate, rinsed and tested. The sensor was positioned in the holder of the acoustic 20 wave device and the output voltage of the balance was recorded for eight minutes after 1000 μL 21 of the following solutions were applied in sequence: subphase solution, concentrated salmonella 22 suspension diluted 1/625, 1/125, 1/25, 1/5 and undiluted bacterial suspension. Eight initial (not-23

aged) sensors were also tested as a control for interaction with *Salmonella* suspended in chicken
exudate and in exudate containing no *Salmonella*. The bacterial count was measured each day and
the concentrations were calculated accordingly. The concentration of bacteria ranged from 10⁷10¹⁰ cells/mL. The dose-response experiments were carried out at a temperature of 25^oC.

5

6 3. Results and discussion

3.1. Rigid versus flexible positioning of bacteria onto the surface of acoustic wave sensor. 7 When the somatic O antibody against Salmonella was employed the firm, whole body, 8 attachment of bacteria was confirmed by electron and dark field microscopy (Figure 1 and 2 A). 9 Electron micrographs show that bacterial binding in this case is characterized by the parallel 10 alignment of cells with visible filaments firmly attaching cells to the surface. The real time dark-11 field recordings of live bacteria bound to the surface confirm this observation (Figure 2A). In 12 contrast, H7 flagellar antibodies provide a flexible attachment of cells to the sensor surface 13 allowing a large degree of freedom. The molecular machinery of a bacterium produces the 14 rotation of its flagella (Schuster and Khan, 1994). When a single flagellum is fixed to the surface 15 by an antibody, the molecular machinery of the bacterium generates a rotation of the whole cell. 16 This rotation can be videotaped; representative frames are shown in Figure 2 B. These figures 17 depicts nine consecutive positions of a rotating bacterium at intervals of about 100 ms. If 18 several flagella are bound to the surface, the video recording showed side-to-side oscillation of 19 cells (not shown). When sensors with somatic O antibodies against Salmonella were subjected to 20 environmental aging, dark-field observation of the sensors showed an increase in the surface 21 buildup of indigenous bacteria as the time of aging and the temperature were increased (Olsen, 22 2000). The buildup partially obstructed the antibodies on the sensor surface and the accessibility 23

of antibodies to *Salmonella* was decreased. Dark-field microscope observation showed that the firm, whole body, binding of *Salmonella* was replaced with a loose attachment of bacteria with a considerable degree of freedom as the time of the sensor aging and the temperature were increased. Thus, the positioning of *Salmonella* at the sensor surface changed from rigid to flexible as environmental aging occurred.

6

7 3.2. Validation of mass measurements of monolayers.

The deposition of increasing numbers of stearic acid monolayers onto the surface of an 8 acoustic wave crystal resulted in a linear increase of the mass (Figure 3). The deposition of a 9 single monolayer of the stearic acid on the crystal adds an additional mass of 2.5×10^{-7} g/cm² (for 10 a 38 mNm⁻¹ transfer surface pressure). This agrees well with the theoretical estimate based on the 11 molecular area of the stearic monolayer in the condensed state. At this state, the area per 12 molecule is ~ 20 Å² (for a single alkyl chain) (Davies and Rideal, 1963). The number of the 13 stearic acid molecules in a monolayer of 1 cm² is equal $1 \times 10^{16}/20 = 5 \times 10^{14}$. The mass of one 14 stearic acid molecule equals 284 g/mole/ 6.023×10^{23} molecules/mole= 4.72×10^{-22} g. The mass of 15 the single monolayer then is $1 \times 5 \times 10^{14} \times 4.72 \times 10^{-22} \text{g}=2.4 \times 10^{-7} \text{g}$. This compares well with our 16 experimental value of 2.5×10^{-7} g. 17

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19 3.3. Specificity and selectivity of bacterial binding

Response curves obtained by exposing the sensor to buffer solutions containing different
concentrations of the bacteria were characterized by fast reaction, the attainment of a steadystate, and very low non-specific binding (Pathirana, et al., 2000). In Figure 4, curve 1, the mean
values of the steady-state output sensor voltages are plotted as a function of bacteria

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1	concentration from 10^2 to 10^{10} cells/mL. The dose response is linear over 5 decades of bacterial
2	concentration (R>0.98, p<0.001). The sensor sensitivity, measured as a slope of the linear
3	portion of the dose response, is $18 \pm 5 \text{ mV}$ per decade of <i>Salmonella</i> concentration, based on
4	experiments from 112 sensors. The interaction of Salmonella typhimurium with the antibody is
5	specific because the sensor does not respond to the bacteria preincubated with the antibody
6	(Figure 4, line 2). The estimated Hill coefficient (Pathirana, et al., 2000), n, was found to be
7	equal to 0.45 ± 0.02 indicating that 2 binding sites were needed to anchor one bacterial cell to the
8	sensor surface. Figure 5 shows the selectivity of the sensor. Line 1 represents the dose response
9	of the Salmonella biosensor to Salmonella typhimurium in the presence of 5.6×10^8 cells of E.
10	coli. Line 2 show the dose response of the Salmonella sensor to E. coli within the same range of
11	concentration with no Salmonella present. For any given concentration the sensor response for
12	Salmonella is greater than that for E. coli. A marked response difference for Salmonella over E.
13	coli is observed even when the number of E. coli exceeds the number of Salmonella by a factor
14	of 1000. The non-specific interactions of the sensor with E. coli were small and compare well
15	with those found using an antibody-immobilized QCM (Park et al., 2000, Si et al., 2001, Su et
16	al., 2001, Wong et al., 2002).
17	The sensors retain \sim 75% of their sensitivity (slope of V versus log concentration curve)
18	over a period of 32 days, and above 25 % after 64 days (Pathirana, et al., 2000).
19	
20	3.4. Effects of rigid and flexible positioning of bacteria on the apparent mass measured by

21 *acoustic wave device*

We found that the bacterial microenvironment and location of the antigen on the surface of a bacterium determines the value and the sign of the analytical signal generated by the

acoustic wave device. When molecules of antigen were located on the surface of the bacterial 1 envelope, thus providing firm and tight attachment to the sensor surface, the sensor output 2 voltage was found to be directly proportional to the logarithm concentration of free bacteria in 3 the liquid adjacent to the sensor surface (Figure 6A, upper line). The lower line of Figure 6A 4 indicates that bacteria with no antigen matching the sensor antibody, do not bind to the sensor 5 surface. In contrast, when the antibody was against the antigen located in the bacterial flagellum, 6 the attachment allows a great degree of freedom (rotation and oscillation) so that the output 7 signal of the sensor in was inversely proportional to the logarithm of free bacteria in solution 8 (Figure 6B, lower line). Again, bacteria with no matching antigen did not bind to the sensor 9 surface (Figure 6B, upper line). The decrease in voltage output of the sensor corresponds to an 10 increase in the resonance frequency of the sensor and hence an "apparent decrease" in effective 11 mass of bacteria attached to the surface. When sensors with somatic O antibodies against 12 Salmonella were subjected to environmental aging, the type of attachment of bound bacteria was 13 found to depend on the time of exposure. The flexible positioning of bacteria on the sensor 14 surface replaced the rigid one as time increased. With rigid positioning of bacteria, the dose 15 response plots were as shown in Figure 6A (upper line). When the flexible positioning of 16 bacteria became dominant, and mobility of the bound cells increased, the dose response signal 17 became similar to that of the flagella bound cells shown in Figure 6B (lower line). Figure 7 18 shows that the responses of the somatic antibody type Salmonella sensor aged for six days at the 19 temperature 4 °C decreased as the Salmonella concentration increased. When bacteria were 20 bound with the mixed positioning, the dose response signal depended on the relative contribution 21 of cells with predominantly rigid or predominantly flexible attachment. Control experiments 22

with fresh (not aged) Salmonella sensors measuring Salmonella in the chicken exudate and in exudate alone demonstrated low non-specific adsorption (data not shown).

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If we define the sensitivity of the biosensor as the slope of the linear portion of the dose 3 response (signal ΔV in mV per decade of Salmonella concentration) then the sensitivity of the 4 sensors is expected to be positive or negative value for the predominantly rigid or flexible 5 positioning, respectively. The experimental dose response data for environmentally challenged 6 sensors were fitted by a linear regression analysis to a line $\Delta V = A + S \times \log(C)$, the slope of the 7 line (sensitivity), S, and the regression coefficient, R, were calculated for each sensor. We found 8 the regression coefficient, R, ranged from about + 0.98 (direct linear correlation), through zero 9 (no linear correlation) to -0.98 (inverse linear correlation) for positive, zero, and negative 10 sensitivities, respectively (Appendix). Figure 8 shows the experimental regression coefficient as 11 the function of sensitivity of Salmonella sensors. The majority of the aged sensor sensitivity 12 values for measurements carried out between 4°C and 33°C fell between -30 and +30 13 mV/decade. It is clear that from these results that the acoustic wave sensor has acceptable 14 analytical value for detecting bacteria only if positioning of bacteria on the sensor surface is 15 either predominantly rigid or predominantly flexible. In the mixed cases the sensitivity and 16 correlation coefficient for dose response signals are not favorable for the effective detection of 17 bacteria. The practical resolution for this phenomenon would be the ensuring of adequate 18 bacterial binding by using antibodies (or other recognition molecules) with high affinity and 19 multiple binding valences. The antibodies should be specific for either somatic or flagella 20 proteins and they must not to be used simultaneously on the same acoustic wave sensor. 21

The observed changes of apparent mass as a function of bacterial concentration are 1 hypothesized to be due both to viscoelastic changes of the LB film-bacteria near surface fluid 2 media and the mass change associated with binding of the bacteria. The most peculiar results 3 show that at certain controlled conditions there is an appearance of a negative apparent mass, i.e. 4 with increasing bacterial concentration there can be a dose dependent decrease of the apparent 5 mass. The exact mechanism producing the negative apparent mass is not known. However, this 6 effect may be due to different physical, chemical, and biological mechanisms. These include 7 electrochemical interaction between cells and the diffusion layer of ions on the sensor/liquid 8 interface, high frequency electrophoretic driving force, the viscoelasticity of bacterial cells, 9 physiological effects including electromechanical forces created by the live, moving organisms. 10 11 There are two very different positions where bacterial antigens may bind with antibodies 12 immobilized on sensor surfaces: O somatic antigens, derived from the outer membrane of 13 bacteria, and H antigens, derived from flagella proteins. Figure 9 shows these different binding 14 sites and at least 3 different ways in which the bacterial cells may bind to the sensor surface. 15 Viscoelastic properties of the bacterial layer attached to the surface are anticipated to be different 16 depending on the mechanism of binding: somatic or flagellar. For the three cases shown in 17 Figure 9 the viscous shear and viscous drag forces of the attached bacteria are very different. It is 18 clear that bacteria at the rigid and flexible positioning (Figure 9, A and B) take different roles in 19 the oscillation of the whole system. When the binding is rigid, bacteria oscillate in unison with 20 the crystal and therefore contribute to the effective oscillating mass of the system. This is shown 21 by the increase of the apparent mass when concentration of bacteria is increased. In the case of 22

flexible attachment, the oscillation of the bacteria may be not in phase with the oscillation of the

crystal and thus can cause a decrease in the apparent mass when concentration of the bacteria is 1 increased. Additionally, the electrically charged bacterium on the surface of an acoustic wave 2 crystal is not only engaged in the mechanical oscillations of the crystal but also directly interacts 3 with the electric field driving the sensor crystal. This field drives the piezoelectric quartz crystal 4 and at the same time creates an electrophoretic force applied to the electrically charged bacteria. 5 The piezoelectric and electrophoretic forces can be of different values and directions, depending 6 on positioning of bacteria by O antigen (firm positioning, Figure 9 A) or H antigen (flexible 7 attachment, Figure 9 B) and their combination can contribute to the change of the apparent mass 8 of the bacteria as measured by the acoustic device. 9

10

11 4. Conclusions

The results of this work demonstrate the high specificity and selectivity of biosensors based 12 on LB monolayers of an antibody deposited on a piezoelectric crystal for rapid detection of 13 bacteria in liquid samples. A marked selectivity for Salmonella over E. coli for Salmonella was 14 observed even when the number of E. coli exceeded the number of Salmonella by a factor of 15 1000. Results also indicate the importance of positioning of bacteria on the sensor surface. When 16 attachment of bacteria is rigid and strong the responses obtained for the interaction of the 17 bacteria with somatic O-type antibodies on the surfaces of acoustic wave sensors correlated 18 directly with changes in mass imposed at the liquid-solid interface. In contrast, when attachment 19 is flexible, as observed for bacteria attached by flagella to H-type antibodies, the sensor signals 20 were inversely proportional to additional mass, and are probably determined by interfacial 21 viscoelasticity and acoustic and electromagnetic coupling. The responses of environmentally 22 aged sensors with the predominantly rigid or flexible positioning of bacteria were correlated with 23

changes in mass at the liquid-solid interface. Sensors with O or H type of binding could be used
for analytical purposes.

3 Appendix

4 Simplified analysis of the thickness-share mode acoustic resonator.

5 The acoustic wave resonator (Figure 10 A) admittance $(Y(\omega))$ can be expressed by the

6 equation:

7
$$Y(\omega) = j\omega C_o + 1/Z_m,$$
 (1)

8 Where wis the angular frequency

9	ω= 2π f ,	(2)
	~~~,	

10  $C_0$  is the static capacitance of the quartz sensor (we neglect any parasitic capacitance), and  $Z_m$  is

11 the motional impedance for the unloaded resonator (Martin, et al., 1991).

12 
$$Z_m = R + j\omega L + 1/j\omega C$$
, (3)

13 where R, L, and C are the resistance, the inductance and capacitance of the motional arm in

14 parallel with the capacitance  $C_0$ . The series resonant frequency f can be determined as

15 
$$f = 1/2\pi (LC)^{1/2}$$
 (4).

16 When the resonator is loaded with solutions the resonant frequency changes due to small changes

17 of parameters L and C. The differential of resonant frequency, df, can be calculated as following:

18 
$$df = (\partial f/\partial L)dL + (\partial f/\partial C)dC$$
 (5),

19 where partial derivatives  $\partial f/\partial L$  and  $\partial f/\partial C$  can be calculated from the Eq. 4:

- $20 \quad \partial f/\partial L = -(f/2)/L \tag{6}$
- 21  $\partial f/\partial C = -(f/2)/C$  (7).

Substituting partial derivatives with Eqs (6) and (7), and replacing the differentials df, dL, and
 dC with small changes of the values, we have:

3 
$$\Delta f/f = -1/2 \times (\Delta L/L + \Delta C/C)$$
 (8).

The Eq (8) fully agrees with Eq (27) of Martin, et al., 1991 if we consider that  $\Delta C/C=0$ . If 4 binding bacteria increases the effective mass of the resonator then the serial inductance (L) 5 representing a mass in the equivalent-circuit model, should increase with the increase of bacteria 6 concentration. On the other hand, the binding of the bacteria increases the effective thickness of 7 the resonator and, consequently, decreases the equivalent capacitance (C) of the circuit. The 8 firmly attached dense layer of bacteria creates a small increase of the thickness and the increase 9 in thickness is proportional to the increase in mass. However, bacteria attached by flagella can be 10 separated from the surface as far away as 5-7 microns. In this case, the increase of the effective 11 thickness of the bound layer is not proportional to the mass of bacteria because they occupy only 12 a fraction of the layer. The electrically charged layer of bacteria spatially separated from the 13 sensor surface can create a charge distribution, which is equivalent to the serial capacitor 14 connected to the equivalent capacitor of the crystal. We can speculate, further, that relative 15 changes of the inductance and capacitance are linear functions of the bacterial concentration (C): 16 (10)

$$17 \quad \Delta L/L = \alpha \log(C) \tag{10}$$

$$18 \quad \Delta C/C = -\beta \log(C) \tag{11}$$

19 where coefficients  $\alpha$  and  $\beta$  are independent of bacteria concentration.

20 From Eqs (9-11) we have:

21 
$$\Delta f/f = -1/2 \times \alpha (1-\beta/\alpha) \log(C).$$
 (12).

22 The output voltage (V) of the Maxtek PM740 acoustic wave device is inversely related to 23 frequency f. So, we can replace  $\Delta f/f$  with  $-\Delta V/V$  in Eq. (12):

1	$\Delta V/V = 1/2 \times \alpha (1 - \beta/\alpha) \log(C).$	(13).

*	
2	Equation (13) indicates, that if the relative increase of the effective thickness is small compared
3	to increase of the effective mass ( $\alpha > \beta$ ), then the relative change of the voltage ( $\Delta V/V$ ) is directly
4	proportional to the logarithm of bacteria concentration (Figure 10B, line $\alpha > \beta$ ). If the opposite is
5	true, and $\alpha < \beta$ , then $\Delta V/V$ is inversely related to the concentration of bacteria (Figure 10 B, line
6	$\alpha < \beta$ ). If $\alpha = \beta$ then $\Delta V/V$ does not depend on the bacteria concentration (Figure 10B, line $\alpha = \beta$ ):
7	$\Delta V/V \sim 1/2 \times \alpha \log(C)$ , if $\alpha > \beta$ (14);
8	$\Delta V/V \approx 0, \alpha \approx \beta;$ (15)
9	$\Delta V/V \sim -1/2 \times \beta \log(C), \text{ if } \alpha < \beta $ (16).
10	When experimental dose response data are fitted by a linear regression analysis to a line
11	$\Delta V/V = A + Blog(C)$ , the slope of the line (sensitivity), B, and the regression coefficient, R, are
12	calculated for each sensor. When $\alpha > \beta$ a good positive correlation with a large slope (sensitivity)
13	is also is expected to be confirmed by a high regression coefficient (R $\approx$ 1). If $\alpha$ < $\beta$ , the regression
14	coefficient at a large negative slope tends to approach a large negative value ( $R\approx$ -1). At
15	conditions, when $\alpha \approx \beta$ , R $\approx 0$ . Thus the regression coefficient can be a function of the slope and
16	can vary from $-1$ to $+1$ , for different sensors with an inverse and direct concentration
17	dependence, respectively. (Figure10C).
18	
19	Acknowlegements
20	We thank Randy O. Boddie for technical assistance. This work was supported partially
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1 Figure legends

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3	Figure 1. Scanning electron microscope image of the biosensor surface after exposure to
4	Salmonella typhimurium (arrow). The bacteria were attached to the O-type somatic antibody
5	at the rough surface unpolished crystal covered with gold. The image exhibits the rigid
6	attachment of bacteria. Some filaments holding bacteria at the surface are visible.
7	Magnification, $\times 5,000$ ; bar = 5 $\mu$ m.
8	Figure 2. Dark-field microscope images of bacteria at the surface of the acoustic wave crystal.
9	The images represent time lapse frames from continuous real time video recordings. A. The
10	rigid attachment of Salmonella to the sensor surface in PBS by somatic O-type antibody.
11	The attached bacteria do not move. B. The flexible attachment of bacteria with the flagellar
12	H type antibody allows oscillation and rotation of cells at the crystal surface. Photographs
13	depict rotation of bacterium attached to the antibody by flagellum. Arrows show nine
14	consecutive positions of the rotated bacterium taken at the interval of about 100 ms.
15	Figure 3. Figure 1. Validation of measuring mass of bound monolayers by acoustic wave sensor.
16	The experimental thickness of multilayer is a linear function of the number of stearic acid
17	monolayers transferred to the sensor surface. The labels "wet multilayer" and "dry
18	multilayers" indicate sensors submerged in buffer solution and dry sensor, respectively.
19	Points show experimental data $\pm$ SD, while lines represent linear fit (R=0.921, P<0.02;
20	R=0.998, P<0.0001, respectively).
21	Figure 4. Specificity of Salmonella sensor. Curve 1 represents the mean values of steady-state
22	sensor voltages as a function of Salmonella typhimurium concentrations from $10^2$ to $10^{10}$
23	cells/mL. The smooth curve is the sigmoid fit to the experimental data (Chisqr = $5.9 \times 10^{-5}$ ).

1	Line 2 shows the dose responses of the sensor exposed to Salmonella typhimurium
2	suspensions incubated with Salmonella antibodies prior to the exposure. $1.2 \times 10^9$ cells were
3	incubated with Salmonella antibodies (~200 $\mu$ g) in 1 mL of PBS for 3 h 40 min. The straight
4	line is the linear least squares fit to the data (R=-0.76, slope=-9.0 $\times$ 10 ⁻⁵ v/decade).
5	Experimental data points were obtained by averaging about 200 data points of each steady-
6	state level of response curves; bars are S.D.
7	Figure 5. Selectivity of Salmonella sensor. Curve 1 represents the mean values of steady-state
8	output sensor voltages as a function of Salmonella typhimurium concentrations from
9	$1.8 \times 10^6$ to $10^9$ cells/mL in the presence of $5.6 \times 10^6$ cells/mL of E. coli O157:H7. The line is
10	the linear fit to the experimental data ( $R=0.97$ ). Line 2 shows the dose responses of the
11	sensor exposed to E. coli O157:H7. The straight line is the linear least squares fit to the data
12	(R=-0.71). The voltage output was scaled up by a factor 5.
	(R=-0.71). The voltage output was scaled up by a factor 5. Figure 6. Dose responses for rigid and flexible positioning of bacteria. A. The curve labeled
12	
12 13	<ul> <li>Figure 6. Dose responses for rigid and flexible positioning of bacteria. A. The curve labeled</li> <li>"Salmonella" represents Salmonella dose responses of the sensor with the somatic O-type</li> <li>Salmonella antibodies. The line labeled "E. coli" represents E. coli dose responses of the</li> </ul>
12 13 14	Figure 6. Dose responses for rigid and flexible positioning of bacteria. A. The curve labeled "Salmonella" represents Salmonella dose responses of the sensor with the somatic O-type
12 13 14 15	<ul> <li>Figure 6. Dose responses for rigid and flexible positioning of bacteria. A. The curve labeled</li> <li>"Salmonella" represents Salmonella dose responses of the sensor with the somatic O-type</li> <li>Salmonella antibodies. The line labeled "E. coli" represents E. coli dose responses of the</li> </ul>
12 13 14 15 16	<ul> <li>Figure 6. Dose responses for rigid and flexible positioning of bacteria. A. The curve labeled "Salmonella" represents Salmonella dose responses of the sensor with the somatic O-type Salmonella antibodies. The line labeled "E. coli" represents E. coli dose responses of the sensor with the somatic O-type Salmonella antibodies. B. The line labeled "Salmonella"</li> </ul>
12 13 14 15 16 17	<ul> <li>Figure 6. Dose responses for rigid and flexible positioning of bacteria. A. The curve labeled "Salmonella" represents Salmonella dose responses of the sensor with the somatic O-type Salmonella antibodies. The line labeled "E. coli" represents E. coli dose responses of the sensor with the somatic O-type Salmonella antibodies. B. The line labeled "Salmonella" represents Salmonella dose responses of the sensor with the flagellar H-type E. coli</li> </ul>
12 13 14 15 16 17 18	Figure 6. Dose responses for rigid and flexible positioning of bacteria. A. The curve labeled <i>"Salmonella</i> " represents <i>Salmonella</i> dose responses of the sensor with the somatic O-type <i>Salmonella</i> antibodies. The line labeled <i>"E. coli</i> " represents <i>E. coli</i> dose responses of the sensor with the somatic O-type <i>Salmonella</i> antibodies. B. The line labeled <i>"Salmonella"</i> represents <i>Salmonella</i> dose responses of the sensor with the flagellar H-type <i>E. coli</i> antibodies. The curve labeled <i>"E. coli"</i> represents <i>E. coli</i> dose responses of the sensor with
12 13 14 15 16 17 18 19	Figure 6. Dose responses for rigid and flexible positioning of bacteria. A. The curve labeled <i>"Salmonella</i> " represents <i>Salmonella</i> dose responses of the sensor with the somatic O-type <i>Salmonella</i> antibodies. The line labeled <i>"E. coli</i> " represents <i>E. coli</i> dose responses of the sensor with the somatic O-type <i>Salmonella</i> antibodies. B. The line labeled <i>"Salmonella</i> " represents <i>Salmonella</i> dose responses of the sensor with the flagellar H-type <i>E. coli</i> antibodies. The curve labeled <i>"E. coli"</i> represents <i>E. coli</i> dose responses of the sensor with the flagellar H-type <i>E. coli</i> antibodies. Curves represent the sigmoid fit to experimental

1	Figure 8. The experimental regression coefficient as the function of sensitivity of Salmonella
1	
2	sensors with the somatic O-type antibody for environmentally aged sensors. The linear
3	portions of dose response signals were fitted by linear regression. The regression
4	coefficients (R) were plotted against the slopes (sensitivity, mV/decade) for sensors aged at
5	temperatures indicated in the label. The line is the sigmoid fit, while the points are
6	experimental data.
7	Figure 9. Different positioning of bacteria at the surface of biosensor. A. The rigid attachment of
8	bacteria by the somatic O-type antibodies. The bacteria moves in unison with the crystal.
9	The electrophoretic force ( $F_e$ ) applied to the electric charges of bacterium ("-") is aligned
10	with the cell body. The piezoelectric force $F_p$ causes the particle displacement at the surface
11	of TSM sensor crystal. B. The flexible attachment of bacteria by the flagellar H-type
12	antibodies. The bacteria have a high degree of freedom and the displacements of crystal
13	particles may be not in phase with the displacements of the bacteria. C. In the aged sensors a
14	biofilm covers certain antibody binding sites and guards against polyvalent attachment of
15	bacteria. As result, the bound bacteria have more degree of freedom than the bacteria with
16	the firm attachment.
17	Figure 10. Simplified electrical model of biosensor. A. Equivalent circuit of TSM resonator
18	(Martin et al., 1991): a capacitance $C_0$ in parallel with resistance R, inductance L, and
19	functional capacitance C. B. Dose response dependence described by Eq. 13. C. Plot of the
20	correlation coefficient as the function of the sensitivity.
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Figure 1



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Figure 3



1 Figure 4







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Figure 8





Figure 10.