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FINAL REPORT

ON

THE DEVELOPMENT OF CONTOURED INTERLOCKING TAPE WOUND TITANIUM ROCKET MOTOR CASES

PART I

DESIGN, METALLURGY AND EXPERIMENTAL FABRICATION

Submitted in Partial Fulfillment of U. S. Army Ordnance Materials Research Office Contract DA-30-069-ORD-3101

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Curtiss-Wright Corporation Wright Aeronautical Division Wood-Ridge, New Jersey

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Experimental Mfg. Metallurgy

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1.0 INTRODUCTION

The development of pressure vessels for use in solid fuel rocket motor cases has reached a state wherein further progress may be restricted by lack of suitable high strength metals and limitations in methods of fabrication. Though the potentially high strength to weight ratio of fiber reinforced cases is recognized, the use of metallic cases offers certain advantages peculiar to metals alone.

The application of metal wire or tape as reinforcement in pressure vessels dates back at least a century. High-tensile steel wire has been used as the banding material on certain rifles and guns as well as in other hollow bodies (1). With the possible exception of one recent investigation (2, 3) no attempt has been made to utilize the transverse strengths of wire or tape to support the axial stress in pressurized vessels. Valenta (2) describes vessels reinforced with wound profile strip which is shrunk on to a vessel (while simultaneously quenched to high strength), putting the monolithic portion of the vessel into compression. Though the tape is contoured and interlocked, it does not appear to support any of the axial load. The present report describes a means whereby the transverse strength of severely cold reduced tape is fully utilized. The method simultaneously facilitates application of ultra high strength materials which might otherwise be difficult or impossible to use.

The interlocking titanium tape concept is an outgrowth of relatively recent work carried out by this contractor (4) in the development of the high strength titanium alloy Bl20VCA. In sheet form, this alloy is heat-treatable to a yield strength of 180,000 psi, a strength level which on a strength-to-weight basis is higher than that of the best ferrous materials used in rocket motor casings today. Unfortunately, this alloy is difficult to weld and even a successful weld cannot be heat treated to maximum strength because the aging response of base material and weldment differ considerably. It was observed that this alloy, similarly to most precipitation hardenable alloys, benefits considerably as a result of cold work prior to aging. Thus, the useful strength level of Bl20VCA can be increased to 300,000 psi, a strength which if fully utilized in a pressure vessel would result in a strength-to-weight ratio of about 1.7 x 10° in.

1.0 <u>INTRODUCTION</u> (Continued)

The objectives of the present contract consisted primarily of the development of fabrication and metallurgical procedures for the manufacture of two basic structural shapes, the development of a wrapping machine and finally the experimental manufacture of two sub-scale vessels. These objectives have been met.

The Curtiss-Wright Corporation wishes to acknowledge financial support from the U. S. Army through the Ordnance Materials Research Office. The assistance of Dr. J. L. Martin, Messrs. G. A. Darcy, Jr. and I. Kahn of that Office as well as of Messrs. R. L. Weatherington and C. H. Martens of the U. S. Army Rocket and Guided Missile Agency is gratefully acknowledged.

2.0 SUMMARY

During the contract period, June 15, 1960 to January 14, 1961, the Wright Aeronautical Division of the Curtiss-Wright Corporation has pursued the work program as originally detailed in the Proposal (5) and has demonstrated the feasibility of interlocked tape wound pressure vessels from both the metallurgical and experimental manufacturing standpoint. Demonstration of the design concept as based on hydrostatic pressure and other environmental tests will be carried out as part of a proposed follow-on to the present contract (6).

"I" beam and channel shapes were designed, fabricated and tested. Turks heading was selected in preference to die drawing, though the latter process might be utilized at a future date for final sizing.

A structural rig for experimental verfication of stress analysis data has been fabricated. Several techniques for precise determination of tape dimensions have been evaluated resulting in the selection of a metallographic method. A specification for Bl2OVCA titanium starting wire has been written and coordinated with two potential sources. The static coefficients of friction of drawn and heat treated tape have been measured and separate interference fit measurements of the interlock have been carried out. The aging response of both shapes in terms of metallographic structure and mechanical properties have been determined and a final heat treatment selected. The low temperature properties of the Bl2OVCA sheet, including notch sensitivity tests have been determined. Several vessel liner materials and bonding methods have been evaluated.

Vessel wrapping apparatus including dummy arbors, collapsible mandrels and other auxiliary apparatus have been designed, manufactured and utilized in the fabrication of two prototype vessels. Design modifications in tape as well as manufacturing techniques based on experience gained in the present program have been carried out and will be incorporated in the proposed follow-on effort.

3.0 RECOMMENDATIONS FOR FUTURE WORK

Limitations inherent in the "Turks Heading" process of wire manufacture, together with observations made both during interference fit testing and wrapping require that the currently used tape shapes be redesigned to incorporate deeper grooves in both shapes. This will assure greater contact area and permit loosening of tolerances on internal corner radii.

Several changes in the wrapping apparatus, collapsible arbor and mandrel removal will be carried out. Presently used 300M steel used in end adapters will be replaced by 25% nickel iron resulting in a higher available yield strength.

The proposed second phase of the present contract will include experimental manufacture of six pressure vessels which will be subjected to hydrostatic tests. The program will further include such studies and analyses relating to adapter attachment, wrapping technique, tape design, metallurgy and other areas found critical during the course of investigation leading to the development of a practical application of the concept. 4.0 DESIGN AND STRESS

4.0 DESIGN

4.1 Mechanical Design

The feasibility of using a high-strength interlocking tape wrapped vessel for a light-weight rocket motor was investigated from a design and stress point of view. Figure 1 shows the selected interlocking tape configuration of three layers. The configurations analyzed were based on a motor I.D. of 6.2 inches and an operating pressure of 4700 psi. This diameter sub-scale vessel was selected because of the availability of a piston rig adaptable to hydrotesting this vessel. In the stress analysis of this vessel, the effects of the small diameter on bending stresses and elastic instability were neglected. This was done to permit direct up scaling to a larger diameter motor.

The design of the interlocking titanium tape is based on a minimum allowable longitudinal and transverse yield strength of 250,000 psi and total (elastic plus plastic) strain of 4% in the transverse direction.

Based on these mechanical properties, two interlocking configurations were studied with emphasis placed on manufacturing feasibility and minimum weight. Figure 2 (b) shows one arrangement with "full-line" contact between adjacent butted channels; and Figure 2 (a) shows another arrangement resulting in "point" contact (under load) between butted channels. Stress analysis has indicated that the full-line butted contact between adjacent channels produces the more efficient arrangement. The final tape dimensions for both the channel and "I" beam are shown in Figure 3.

Additional stress analysis was performed on the inner channel layer in order to determine the local bending stress in each channel caused by the internal pressure (Figure 4). This bending stress is a result of the longitudinal bending of the channel between "I" beam flanges, and adds directly to the longitudinal stress. However, this condition would not arise in a full-scale rocket motor case since the internal pressure for the same tape stress level would be greatly reduced. The present six inch diameter sub-scale test vessel is designed to yield at 4700 psi pressure, whereas a larger diameter vessel would operate at approximately 1000 psi. To alleviate this local bending stress in the sub-scale vessel, the width of the "I" beam flanges was increased from .025 to .040 inches This reduces the free beam length of the channel (Figure 5). and thus reduces the local bending stress.

4.1 Mechanical Design (Continued)

As seen in Figure 3, the legs of the "I" beam and channels are tapered. This is to permit assembly of the wires under the worst tolerance condition. To insure interlocking of the wire assembly, the "I" beams are pre-stressed in the transverse direction. The theoretical load required to force an "I" beam or channel into position is approximately equal to 2500 pounds. This load should be exerted by a roller of 5 inches minimum diameter. The theoretical axial tension required when wrapping either an "I" beam or channel should not exceed 200 pounds. The 2500 pound applied load required to force the wire into position was calculated on the basis of an assumed coefficient of friction between titanium of 0.2 and a roller contact length of .1 inch. A survey of the literature, later confirmed by direct tests, indicated that this value is low and a value of 0.3 is more realistic. The maximum axial load of 200 pounds results in a residual pre-stress of 50,000 psi for the tape in position on the vessel. This assumes that the entire axial winding load remains in the wrapped tape due to friction along the interlocking surface.

4.2 Stress Analysis

Stress analyses of the butted and spaced channel configurations have been completed. When the channel ends are spaced, it is possible to design channels and "I" beams so that only two different tape shapes are required and any number of layers can be added. This situation will occur when

 $t_{1A} = t_{1B}$ and $L_D = L_C$. (See Figure 6 for nomen-

clature). The spacing between the channels will then equal the spacing between the "I" beams. This arrangement is not ideal from a stress standpoint. The loading on the channels produces bending stresses in addition to the axial stresses. This arrangement also results in a varying load distribution across the wall of the vessel which tends to overstress the inside and outside layers while understressing the middle layers. Thus, the efficiency is reduced.

When the adjacent channel ends are butted, two different shapes of tape are sufficient only when n (the number of "I" beams) is equal to 1 (3 layers) or the spacing between the "I" beams is 0. For all other configurations, more than one shape of "I"

4.2 Stress Analysis (Continued)

beam is required. For optimum hoop stress design, it is desirable to have spacing between the "I" beams; therefore, the case where n = 1 is recommended. This case also affords the minimum overall wall thickness. From a stress standpoint, the butted channel arrangement is preferable to the spaced channel arrangement because the channel bending stresses and the varying load distribution across the wall are reduced.

Having established the interlock configuration which yields minimum stresses, an analysis was performed to determine the actual tape dimensions. The butted channel tape configurations were analyzed in detail and the results are shown in Figure 7.

An outline of the stress analysis is given below:

- (a) Consideration of the load in the longitudinal direction determines the shank thicknesses of the "I" beam and the channel. Since there are two channel layers sandwiching an "I" beam layer in a three layer vessel, the shank must be twice as thick as the channel shank. This assumes no pre-stressing of the "I" beam at the interlock. However, an initial compressive prestress imposed on the butted channel ends will tend to maintain line-to-line contact and minimize channel bending.
- (b) The thickness of the interlocking legs is obtained next. For short interlocking leg heights (△ = 0.010), the allowable shear stress determines the thickness of the leg. In general, this thickness is more than two and one-half times the channel leg height. Since the interlocking legs are relatively short in height and broad in thickness, the interlocking load was assumed to be transmitted in shear without accounting for bending effects.
- (c) The length of the "I" beam must be equal to the sum of twice the channel leg thickness plus twice the "I" beam leg thickness.
- (d) The height of the channel leg (\triangle) is determined by the allowable bearing stress on the interlocking joints.

4.2 Stress Analysis (Continued)

(e) The length of the channel (Lc) is determined last. The metal-filled area of the wall is varied by varying the channel lengths. For an optimum design, the metal-filled area is sized for the allowable vessel hoop stress.

The detailed stress calculations made in determining the final shapes of the "I" beam and channel are shown in Appendix I.

4.3 Weight Estimates

A weight estimate was made to determine the percent weight saving of the titanium tape over a solid wall steel shell of 300M material having a uniaxial yield strength of 200,000 psi minimum. The weight of the tape wrap includes the interlocking tape and the plastic liner. The weight of the interlocking tape shell is 50% less than the weight of the 300M shell (Figure 8).

4.4 End Attachments

The design for attaching the ends of the interlocking tape to the domes is shown schematically in Figure 9. All three layers of tape, after being wrapped around the threaded dome adapter, are held in place by groove pins. (An investigation of other bonding methods was carried out and is reported in Section 5.) Because of the helical winding of the interlocking tape, the natural tendency of the tape under pressure would be to unwind (See Figure 10). The necessary restraint can be attained in three ways: (1) by bonding the interlocking tapes with an epoxy resin to withstand the shearing tendency to unwind; (2) by using a counter-winding combination of layers in which the unwinding tendencies can be mechanically neutralized; (3) by relying on the interference fit between interlocking tapes to withstand the unwinding tendency through friction. Stress analyses have indicated that the torsional shear stresses are low (422 psi) and the friction between tapes will restrain the vessel from unwinding.

Figure 9 shows the adapter to be tapered where the unsupported cylindrical section of the interlocking tape starts. This taper minimizes the discontinuity stresses at the intersection. Under internal pressure the tapered adapter section in contact with the tape will yield radially outward and reduce the discontinuity effects.

4.4 End Attachments (Continued)

Sealing of the vessel against internal pressure can be accomplished by coating the inside of the motor with a layer of vinyl. Vinyl, which has a relatively low modulus of elasticity, is capable of adhering to the tape wrapped vessel without cracking when subjected to the radial and longitudinal strains of the pressurized vessel.

The final design of the sub-scale vessel is shown in Figure 11. This drawing shows details of the tape, adapters, and the assembly. The piston rig, which is used for hydrotesting, is shown in Figure 12.

4.5 Piston Rig - Jacking Fixture

In order to test the operation of the Piston Rig Apparatus, a burst test of a solid 300M steel vessel was carried out. The vessel was pressurized to a burst pressure of 5000 psi without damage to the piston rig. However, in assembling the piston covers containing the hard rubber "O" rings and leather back-up ring, a larger than expected force was required to compress the "O" ring. This force was transmitted through the vessel to ground. Consequently, a jacking fixture was designed and fabricated which will prevent this high compressive force from being transmitted into the vessel. The design of the jacking fixture is shown in Figure 13.

4.6 Structural Rig

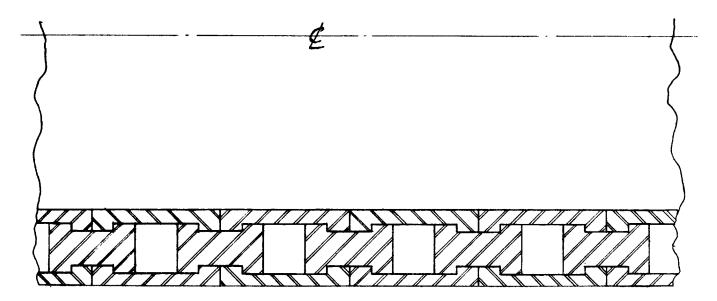
A structural rig which will be used to evaluate the interference fit has been designed and fabricated. The purpose of this rig is to determine the parameters which affect the stresses in the tapes. Schematically shown in Figure 14 is a freebody diagram of the channel subjected to the loads resulting from the interference fit. It may be observed that the interference fit tends to clamp the channel flange and prevent rotation during pressurization. Figure 15 shows the apparatus which will be used to evaluate these stresses. The channel sections are fabricated from Bl20VCA titanium strip and will be ten times the actual cross-sectional dimensions. The clamping plates will also be fabricated from Bl2OVCA titanium. These plates when bolted together will produce an interference fit with the channel sections. Hoop restraint is induced by transverse clamping which simulates the internal pressure The test procedure to be used for this rig is effects. detailed in Appendix II, and the instrumentation layout is shown in Figure 16.

4.7 Roll Redesigns

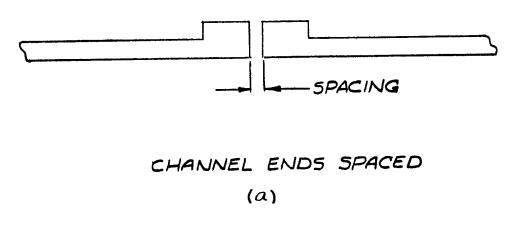
The following procedure was used to determine the dimensions of the proper finish "I" beam rolls that would yield the correct tape cross-section. The form rolls were not reworked and are shown in Figure 17. Figure 18 shows the finished rolls assembled, the dimensions of the rolls, and the resulting rolled tape dimensions. Since the angle of 17^o is more than the desired 12^o, a new roll was made (Figure 19) having an angle of 1 to 3^o. This roll produced a tape angle of 7.5^o. A plot was then constructed (Figure 20) which relates roll angle to tape angle. Based on this data a new roll was made having angles of 4.5 to 5.5^o. The resulting tape dimensions are shown in Figure 21. The "I" beam roll width was also changed to produce a greater interference fit.

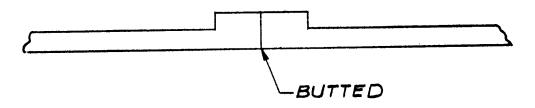
A similar procedure was carried out for the redesign of finish channel rolls. The form rolls shown in Figure 22 were also not reworked. The first shape rolled is shown in Figure 23, the second in Figure 24, and the third in Figure 25. A plot of channel roll angle versus tape angle is shown in Figure 26.

TYPICAL WIRE CONFIGURATION

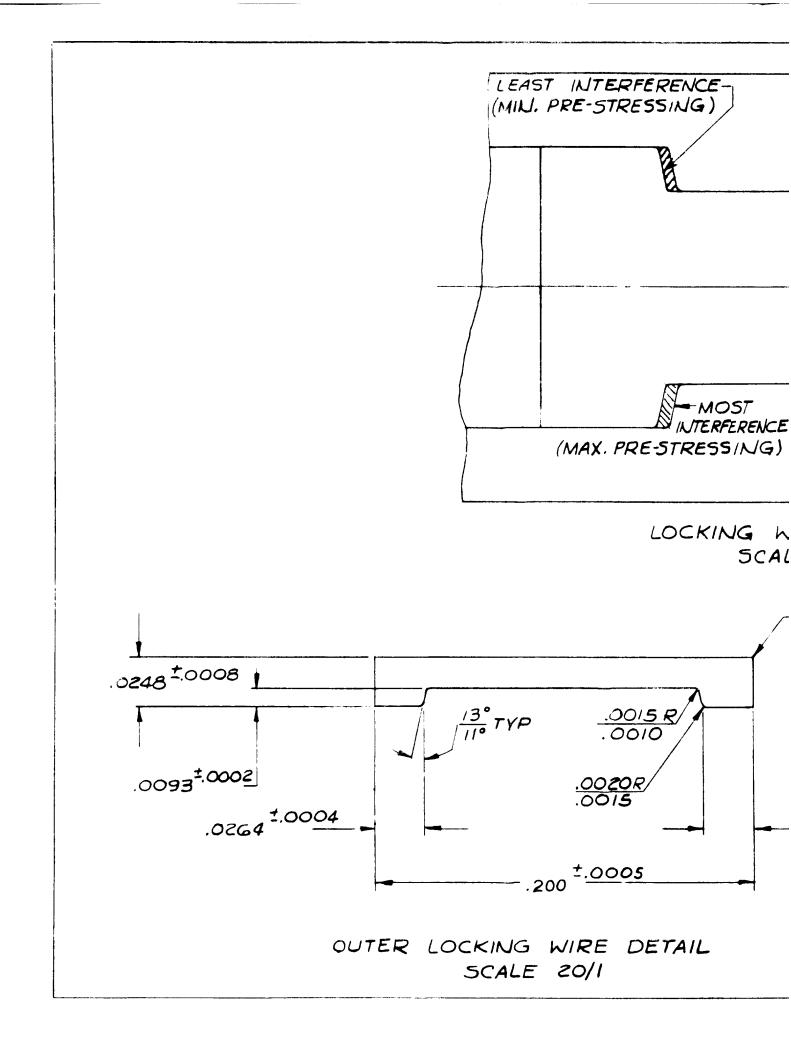


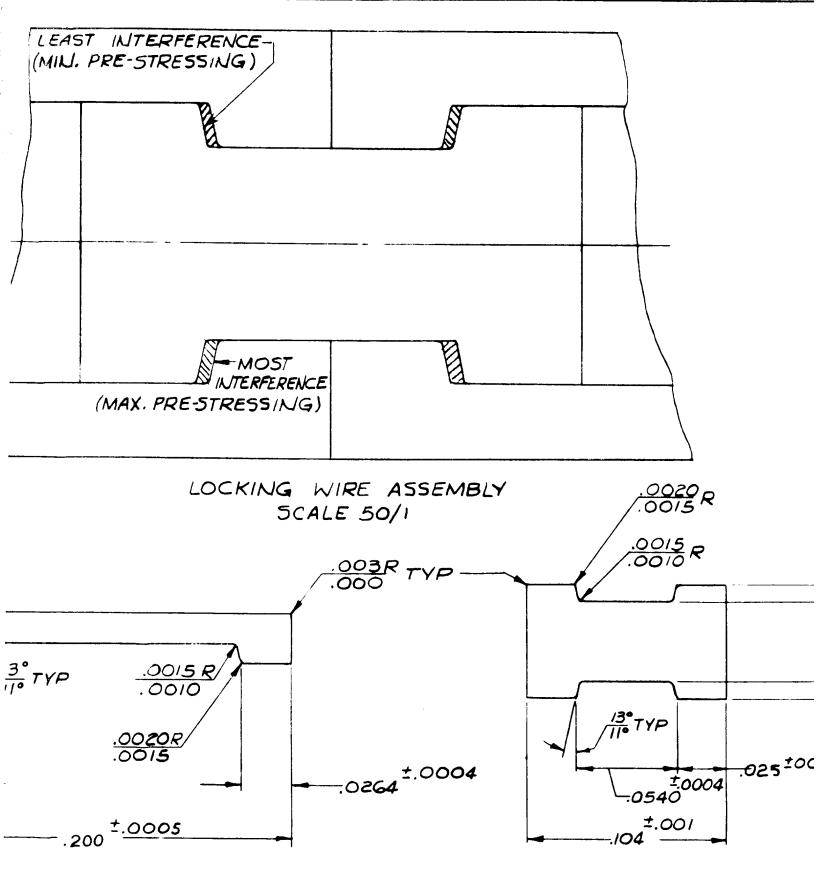
CHANNEL END ARRANGEMENT



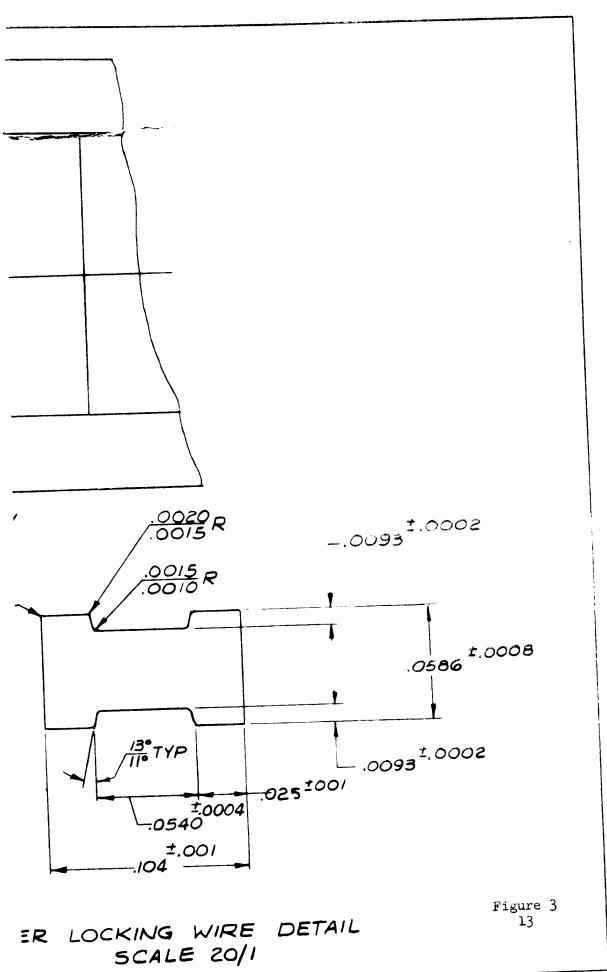


CHANNEL ENDS BUTTED (b)





KING WIRE DETAIL SCALE 20/1 INNER LOCKING WIRE DETA SCALE 20/1



BENDING STRESS - CHANNEL

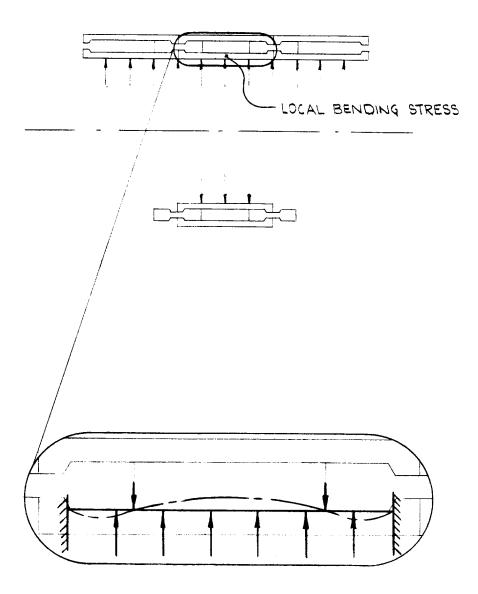
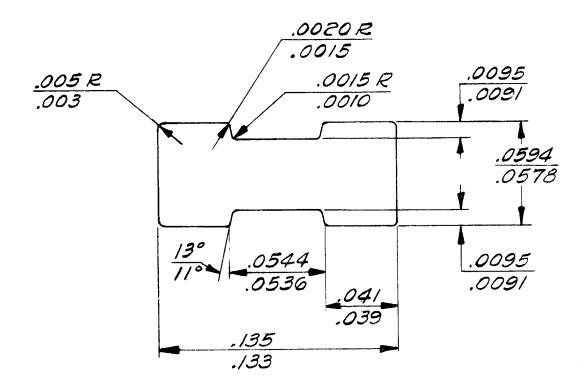
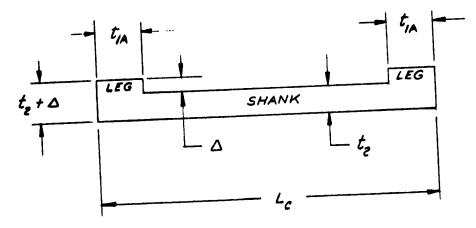


Figure 4 14



WIRE - I-BEAM







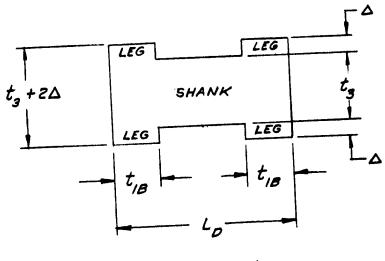


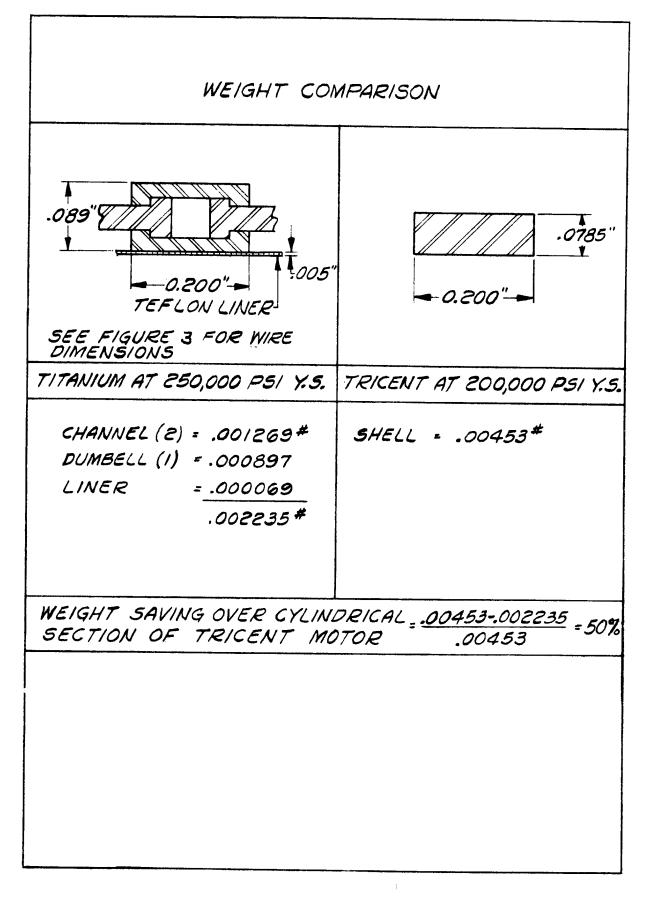


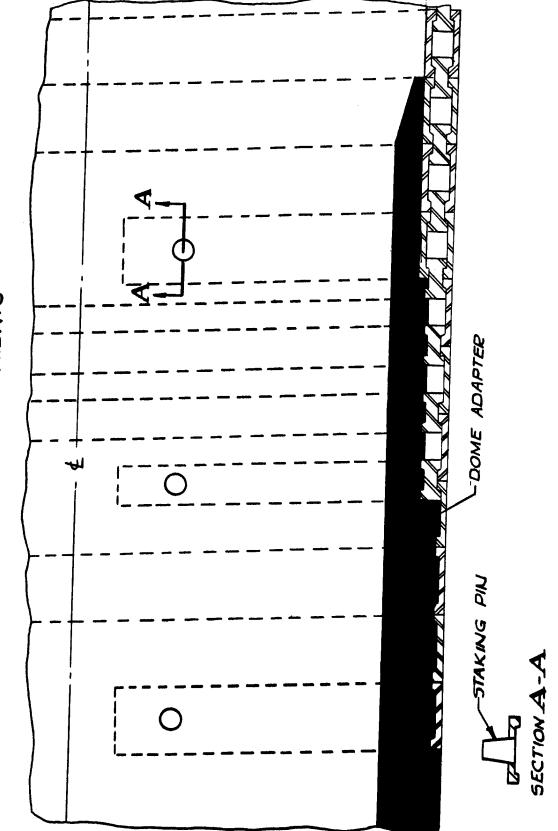
Figure 6 16

STRESS ANALYSIS SUMMARY

Configuration	3 Layers Butted Channels
Wire Material	Titanium Alloy, Bl2OVCA
Mechanical Properties (psi) Longitudinal Transverse Bearing Shear	250,000 250,000 417,000 150,000
Dumbell Dimensions (in.) Length - LD Shank Thick t_3 Leg Thick t_{1B} Spacing - S Interlock - \bigtriangleup	0.104 0.040 0.026 0.093 0.0093
Channel Dimensions (in.) Length - L_C Shank Thick t_2 Leg Thick t_{1A} Spacing - S Interlock - \bigtriangleup	0.197 0.0155 0.026 0 0.0093
Overall Vessel Thickness (in.) Helix Angle	0.089 00-46.2'
Dumbell Stresses (psi) Hoop Axial Interlock Bearing	250,000 250,000 416,000
Channel Stresses (psi) Hoop Axial Leg Bending Leg Shear Shank Bending	250,000 250,000 0 150,000 0
Torsional Shear Stress (psi)	422

Fig. 7

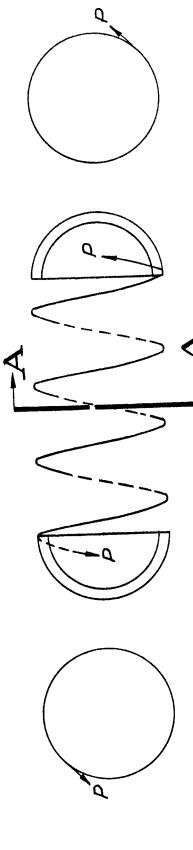




WIRE END ATTACHMENTS



FREE BODY DIAGRAM TORSIONAL SHEAR STRESSES



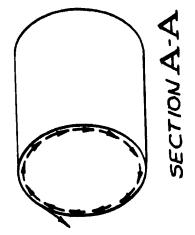
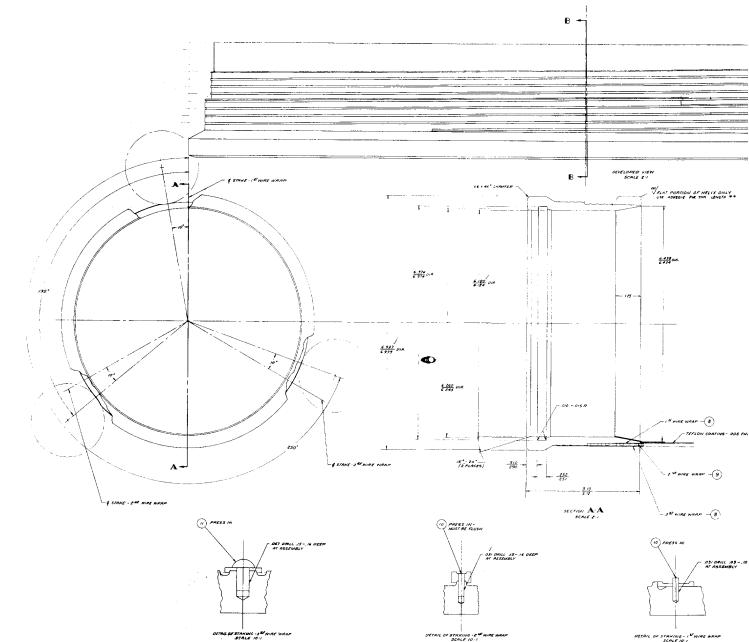
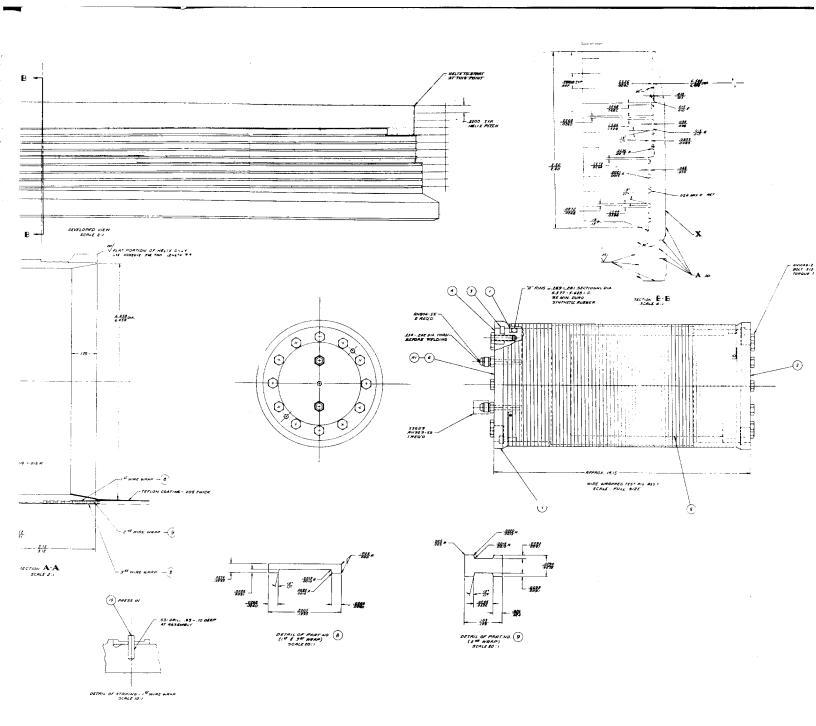


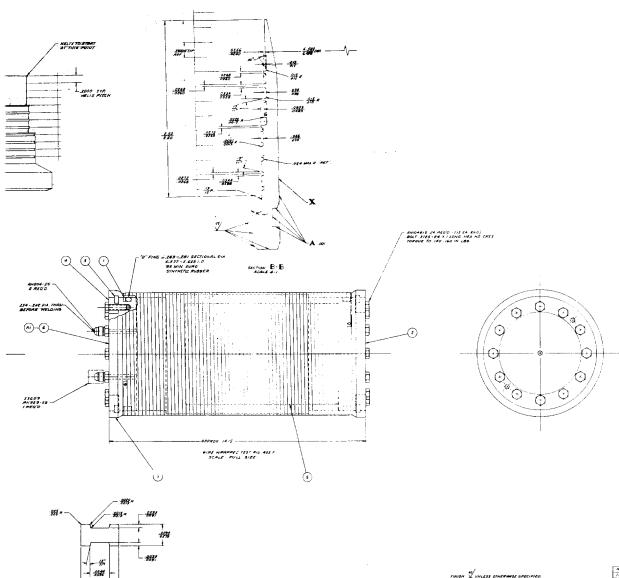
Figure 10 20



DETAIL OF STAKING - Z W W. SCALE 10:1

DETAIL OF STAKING - I WIRE WRAP SCALE 10:1





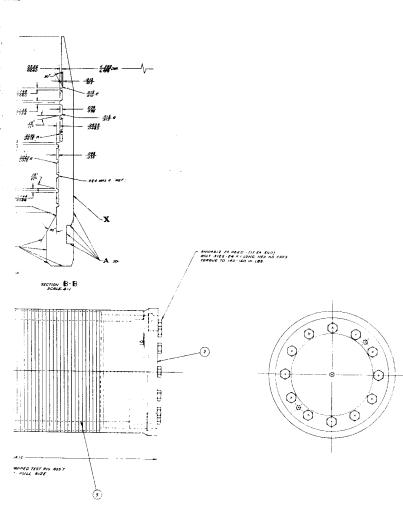
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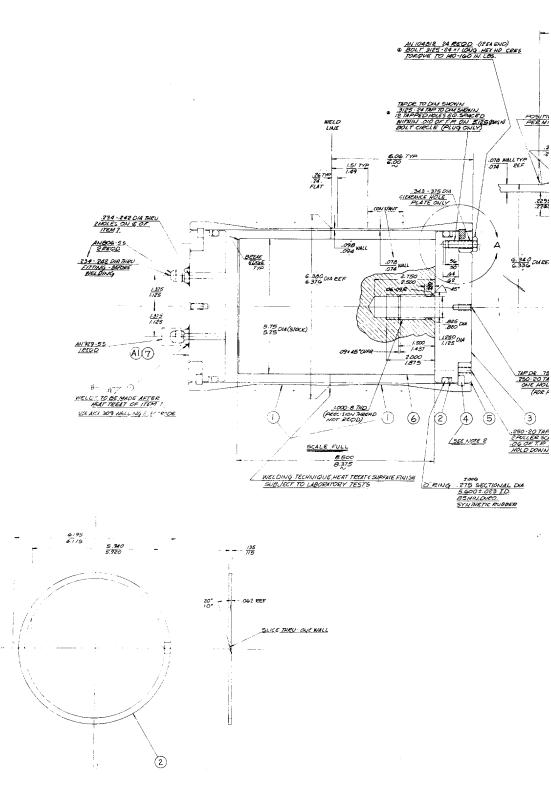
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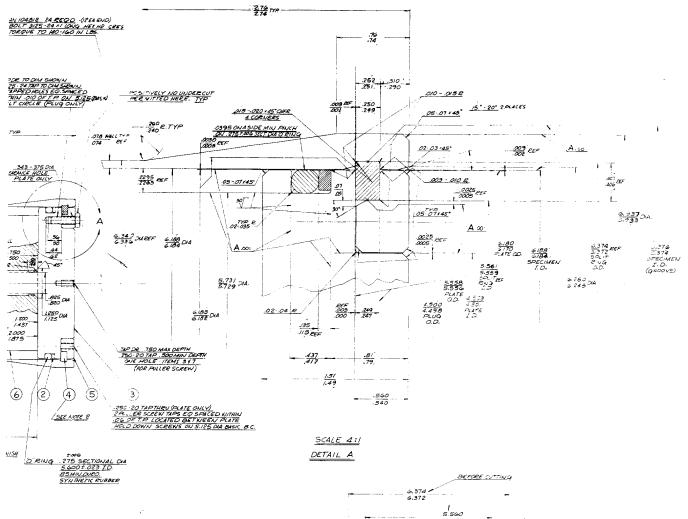
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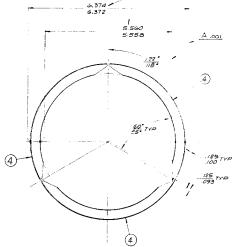
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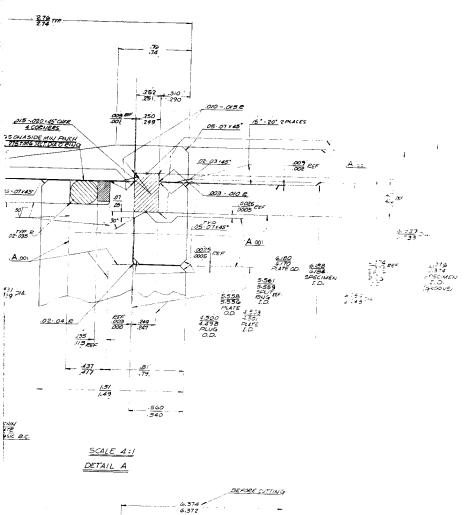


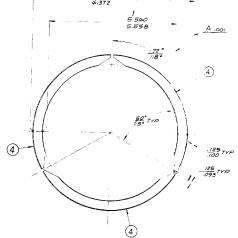
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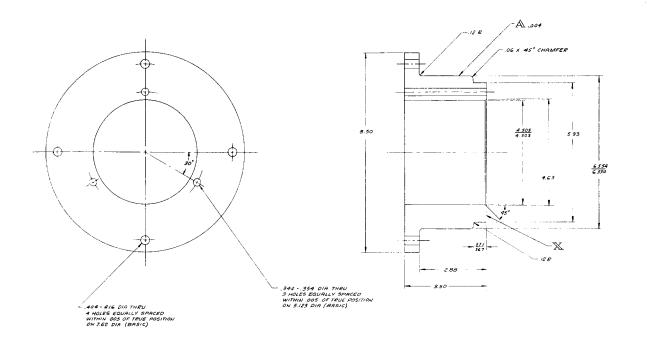
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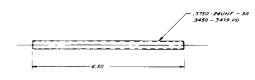


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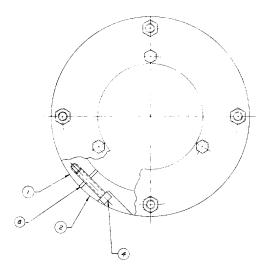
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6				+	1	CYLINDER	OFT-ONE		A SURFACES CONSTRUCTED AROUND OR AT RIGHT ANGLES TO A COMMON AXIS MUST BE
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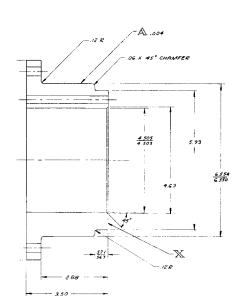
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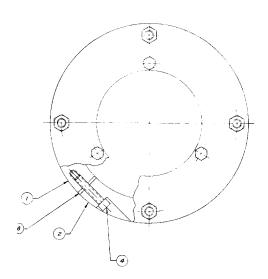


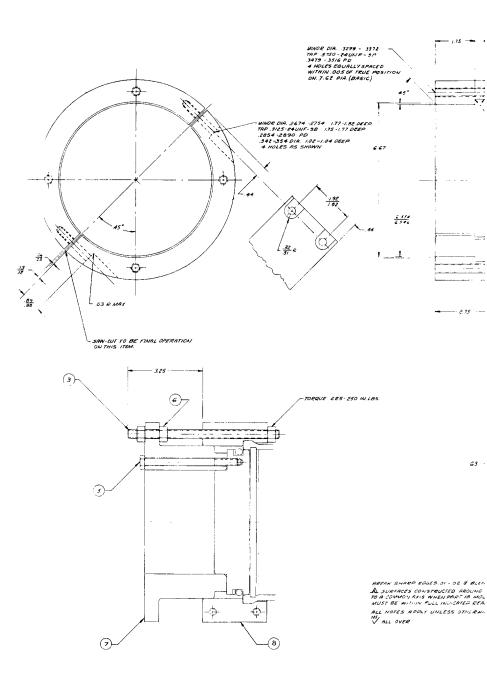
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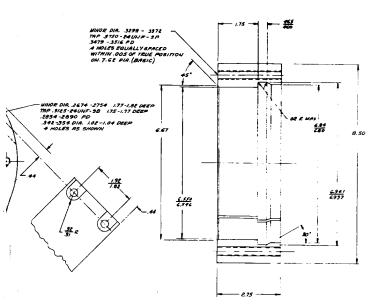


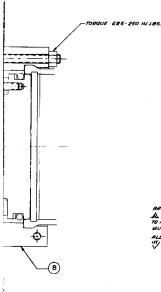
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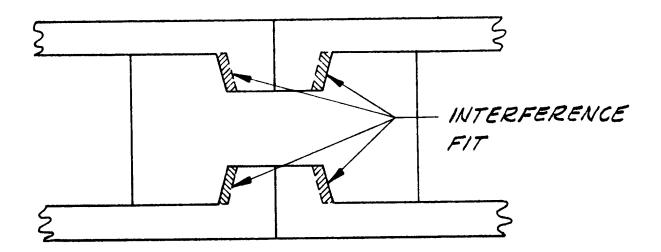


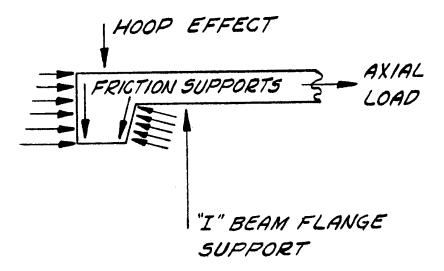
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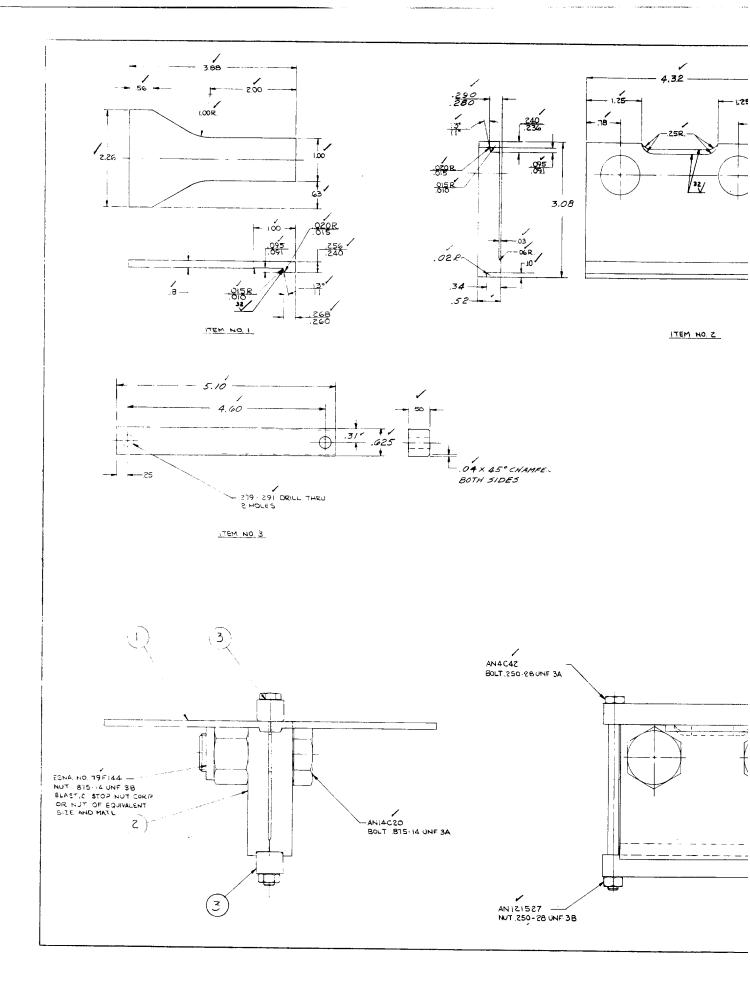
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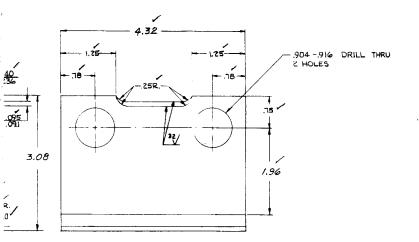
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FREEBODY DIAGRAM









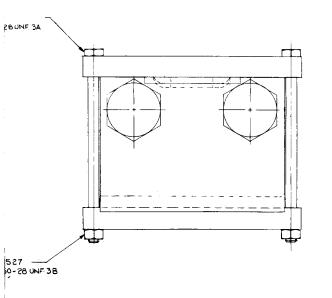
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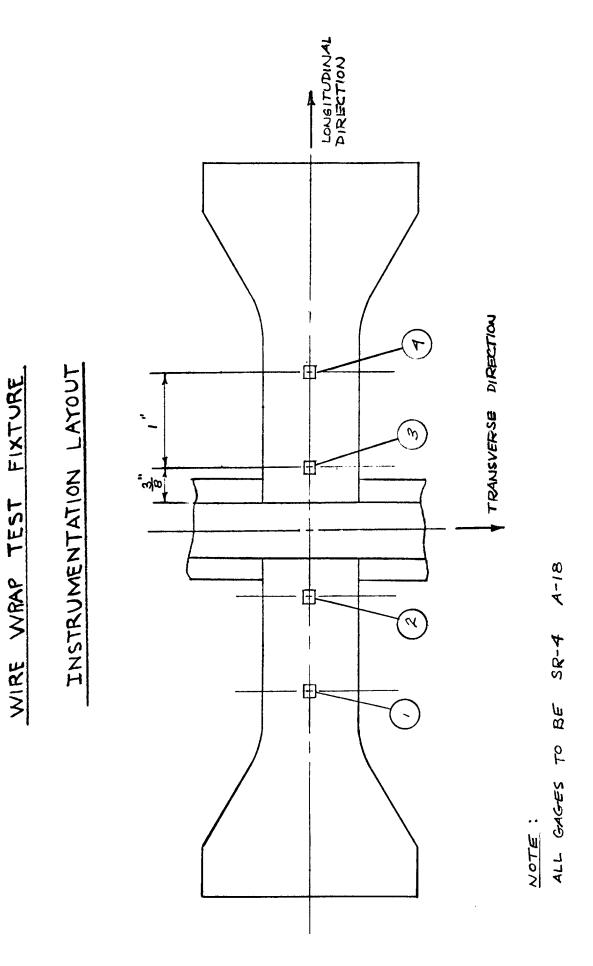


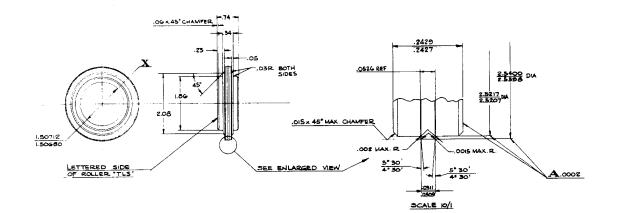
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	ANIACEO ESNA NO. 378144 OR BQUIWLENT AN4C42				Electronic Contraction Contrac	REAK SHARP EL 25 -, 015 APPED HISHED DIM. ±.011 LANGLES ± 2° LESS OTHERWISE BOLT815-14 UNF 3A NUT815-14 UNF 3B	X R D SPECIFIED 23/L LENGT. (SEE NOTE) 47/2 LENGTH			S 25	810
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32	ANIACEO ESNA NO. 378144 OR BQUIWLENT AN4C42					REAK SHARP EL 25 -, 015 APPED HISHED DIM. ±.011 L ANGLES ± 2° L NOTES APPLY LESS OTHERWISE BOLT815-14UNF 3A NUT815-14UNF 3A BLOT250-28UNF3B DLATE - SPECIMEN	X R D SPECIFIED 23/L LENGT (SEE NOTE) 4/22 LENGTH		DROLON BLISTAT MEL TALLESS TAL SELSON TAL SE	RC 32 - 36	
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2	ANI4CEO Sign ADO HOWENT AN4C42 AN121527 	ASS Y	SE TOEN.	13 (AN) 1967 - 2		REAK SHARP E1 25 -, 015 APPED AISHED DIM. ±.011 LANGLES ± 2° LOTES APPLY LESS OTHERWISE 1 BOLT815-14 UNF 3A NUT815-14 UNF 3B BLOT250-28 UNF-3A NUT250-28 UNF-3A	X R D SPECIFIED 2 XL LENGT (SEE NOTE) 4 XL LENGTH 4 CLAMP 10/1 WIRE SIZ ON		DROLLOW BITTATT BITTAT	RE 55-36 180 grand A Separation of the second sec	+OR(CAS W.F
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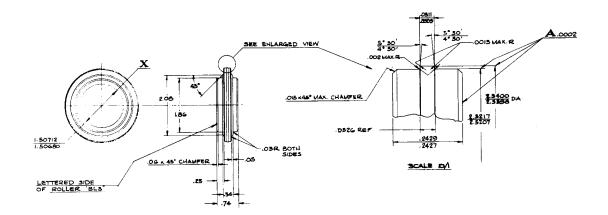
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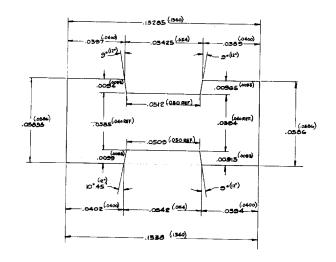
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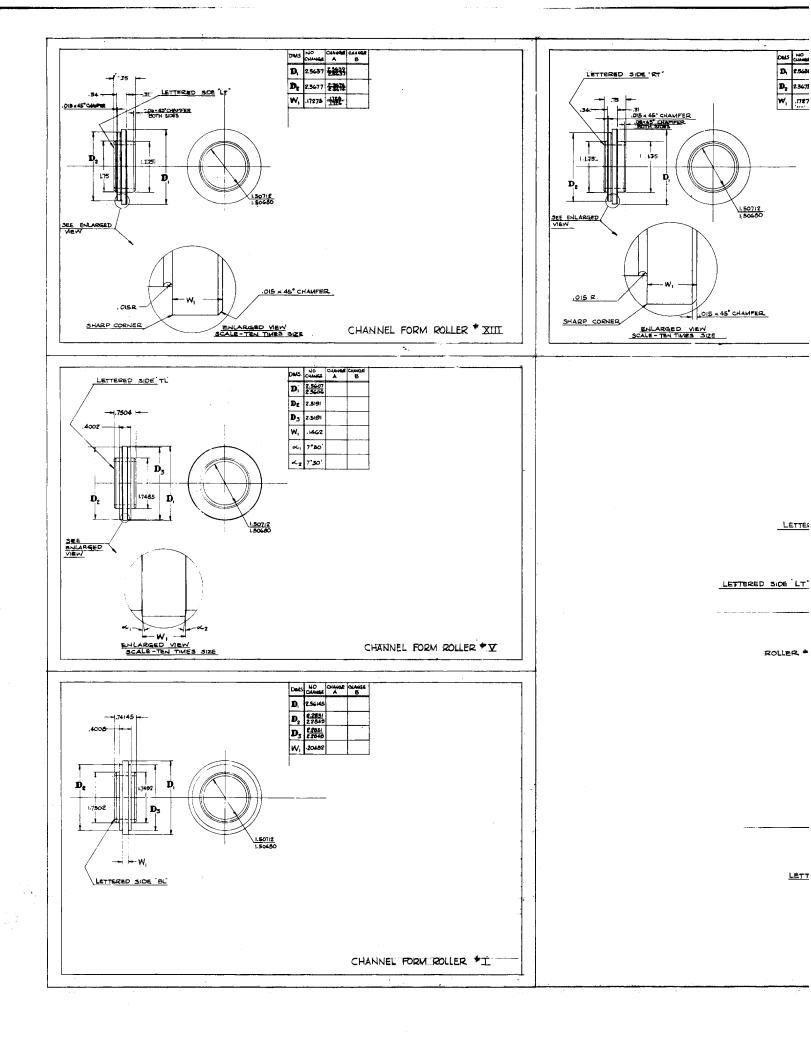
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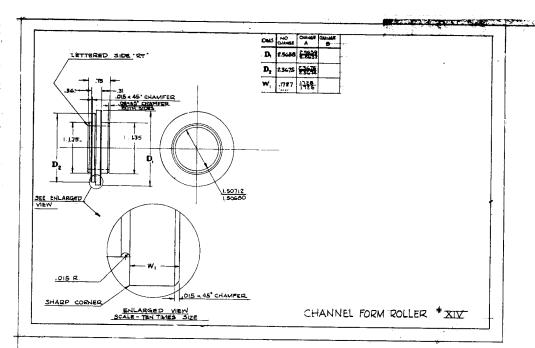


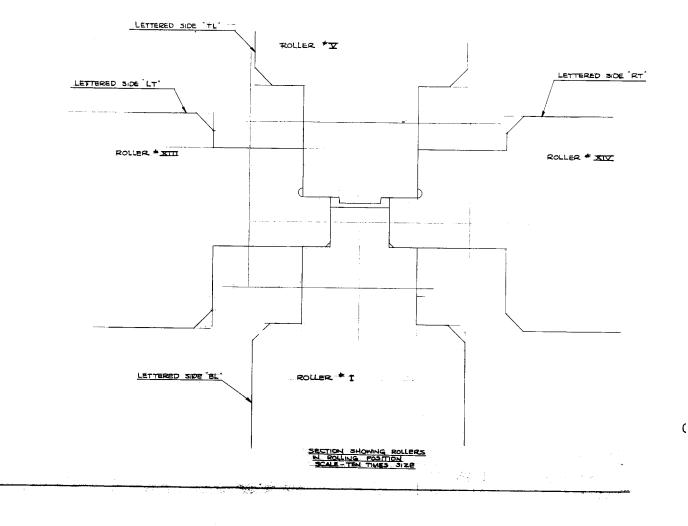
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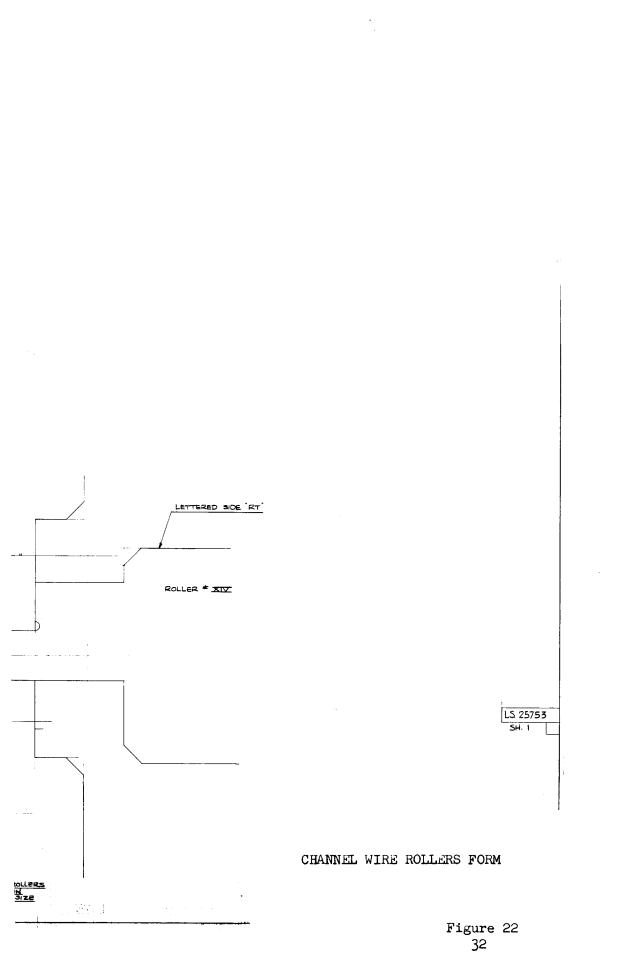
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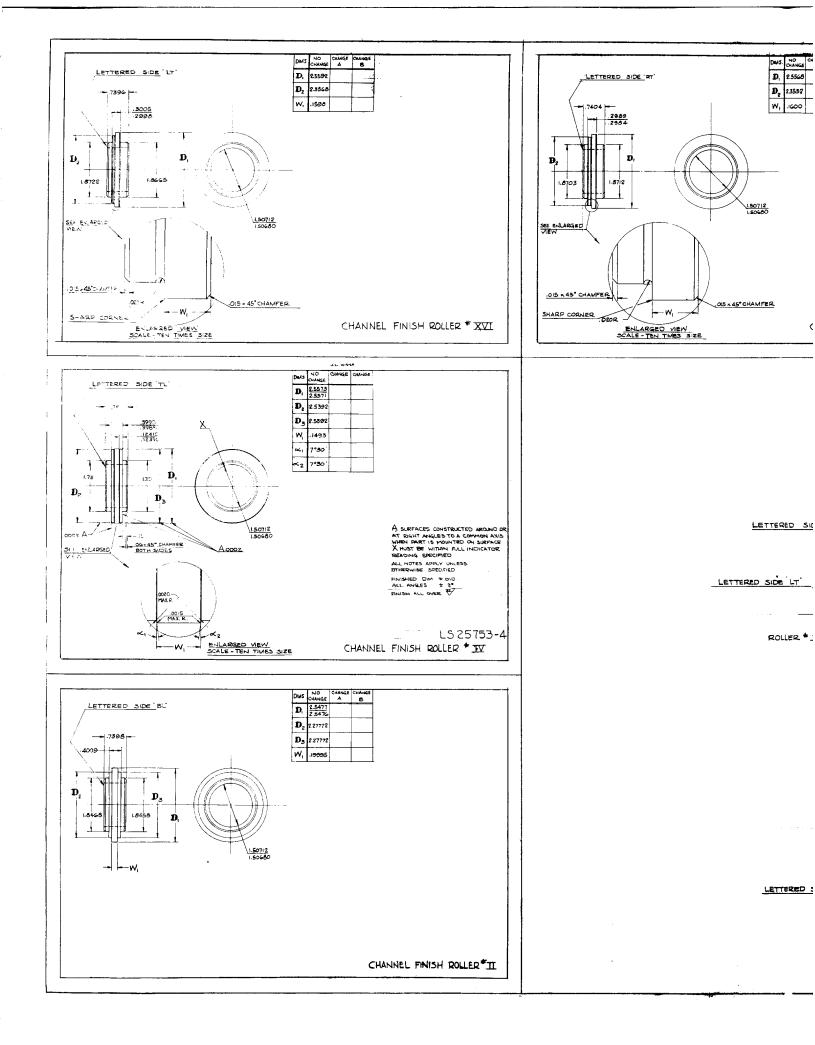
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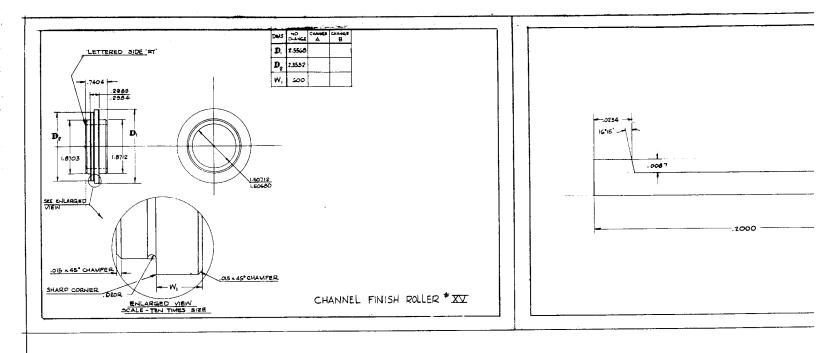


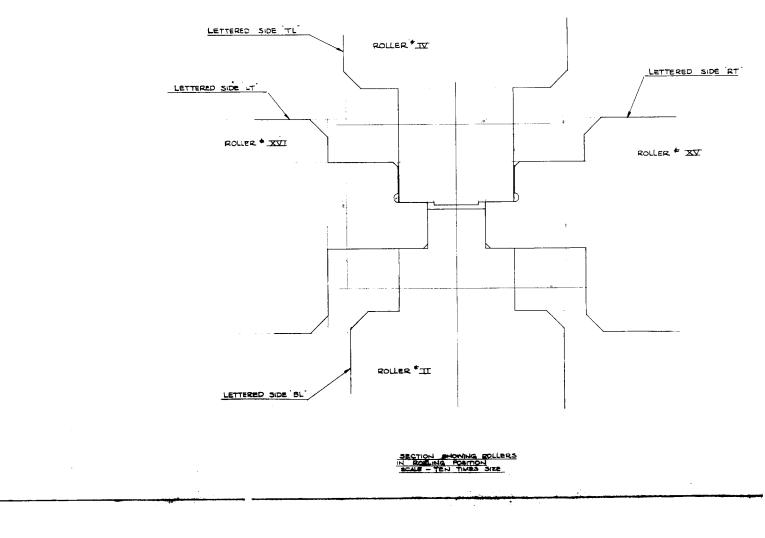


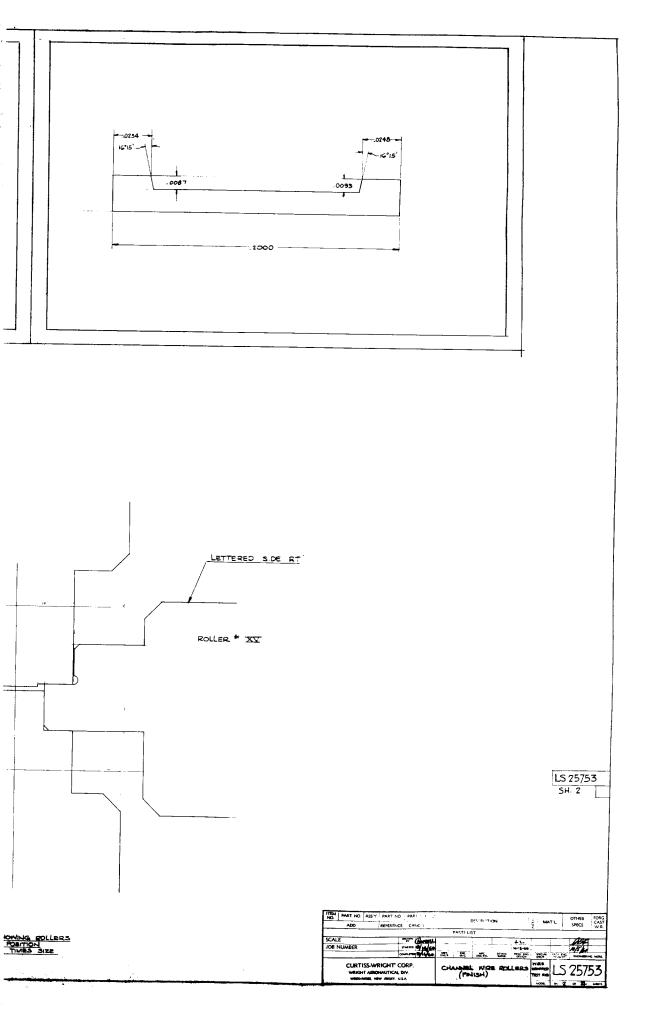




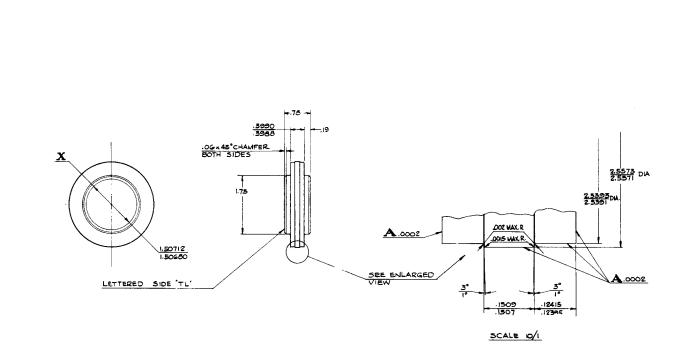


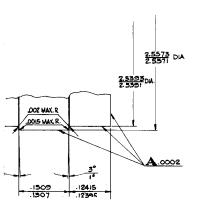


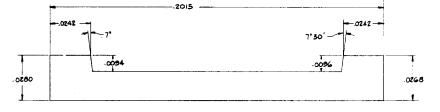




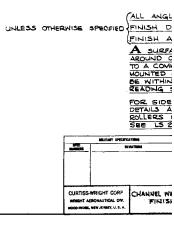
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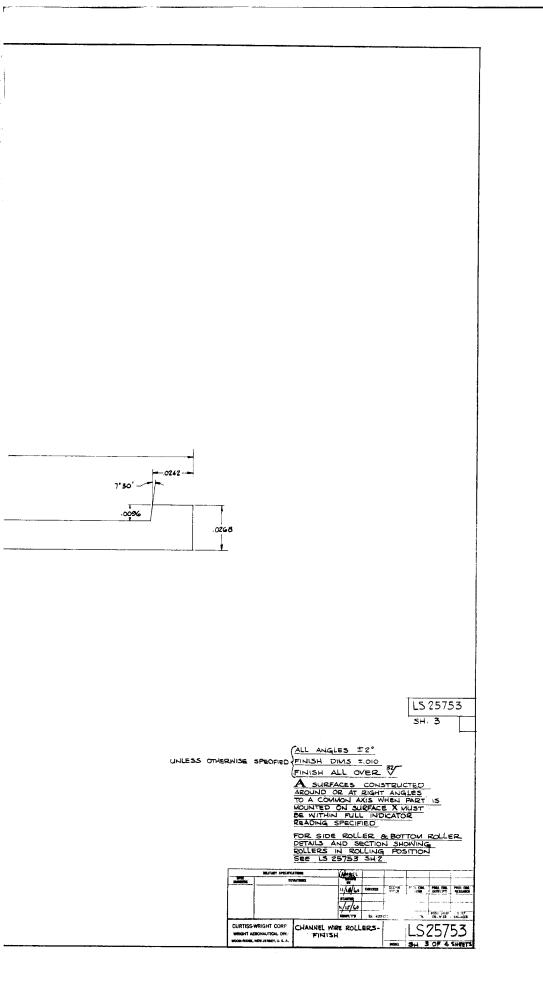


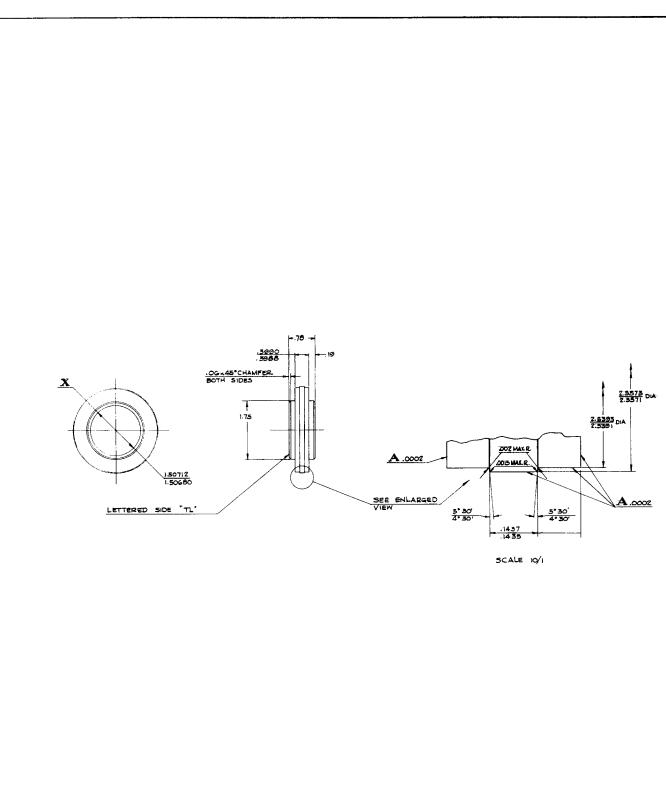






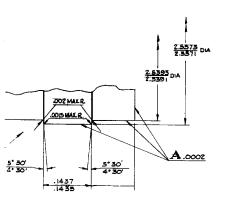
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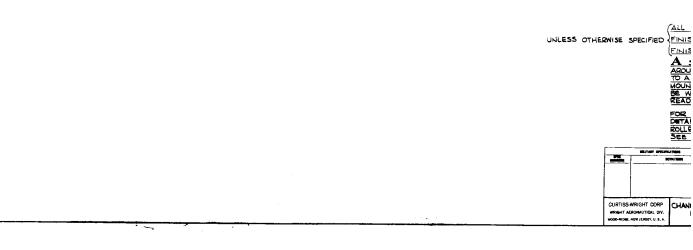


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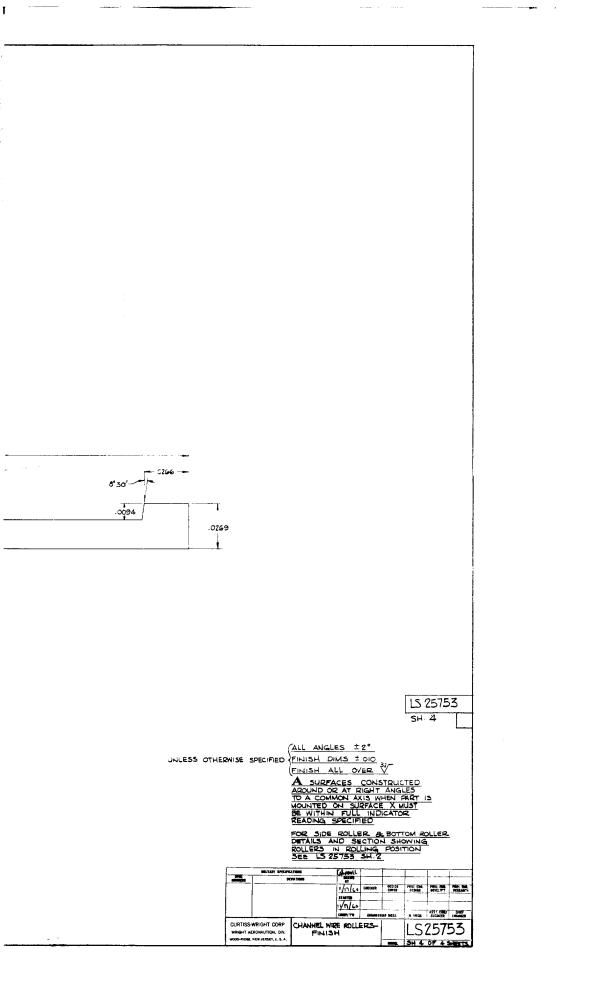
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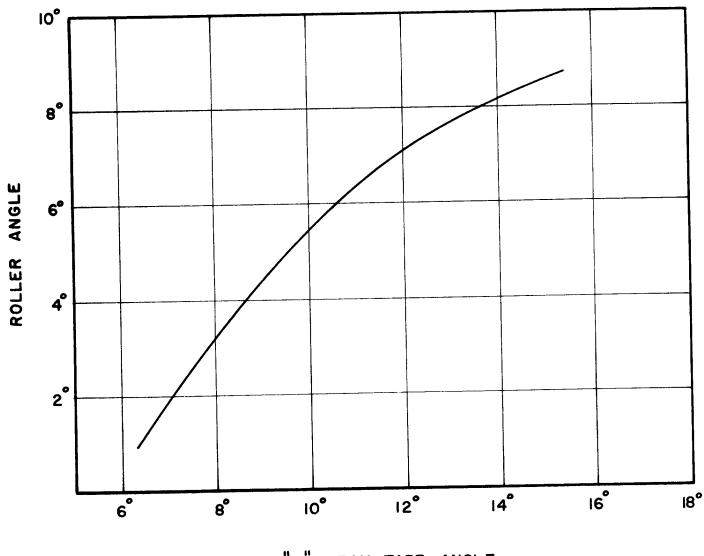
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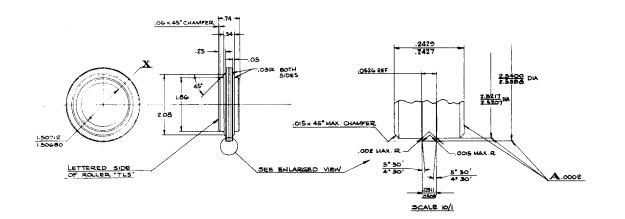
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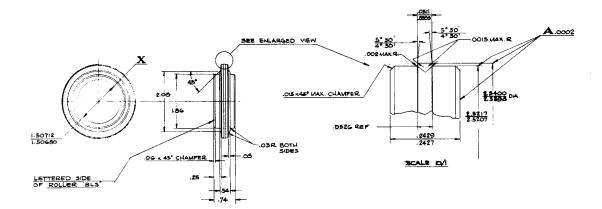


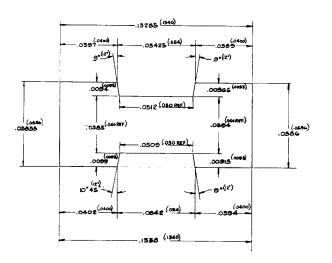
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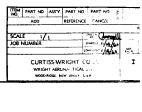
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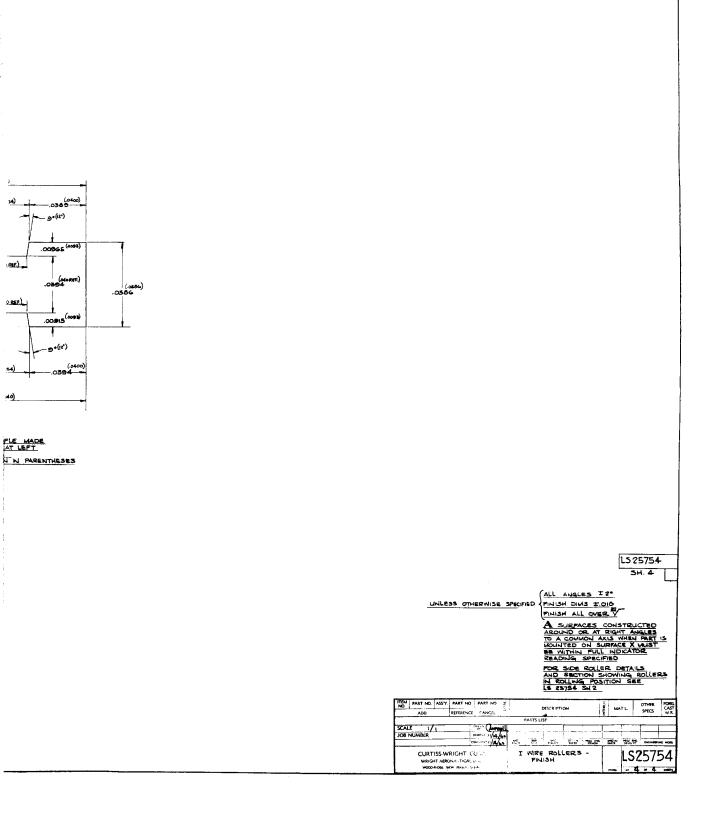
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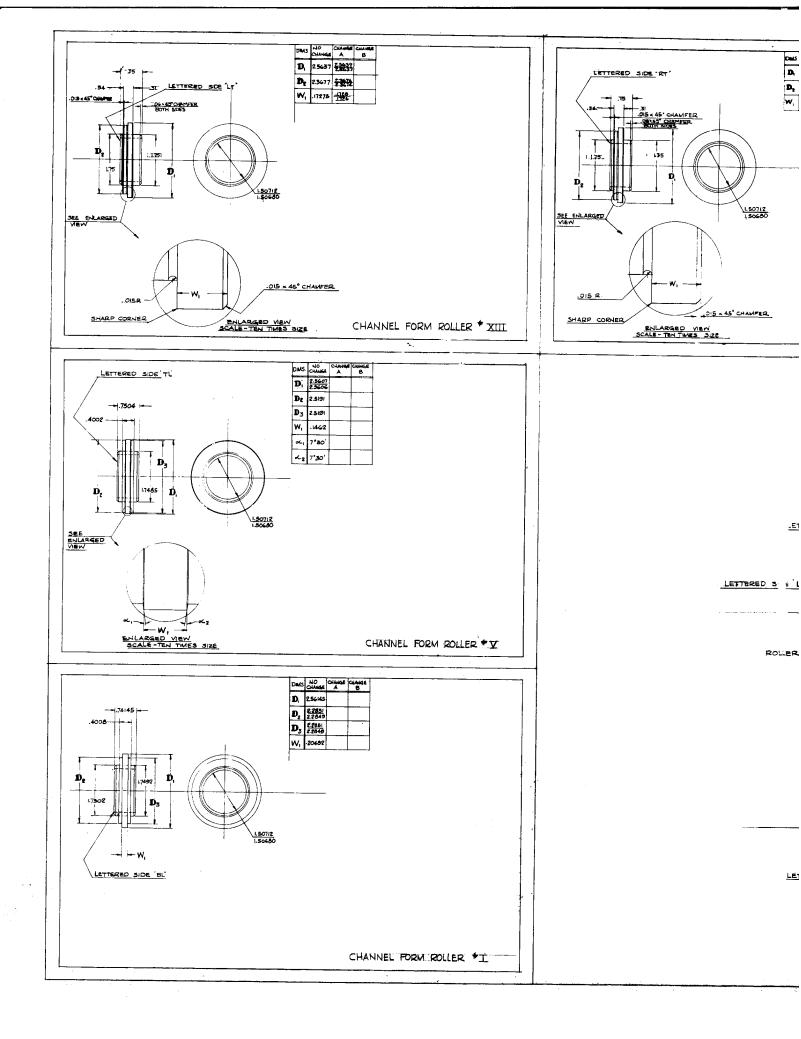
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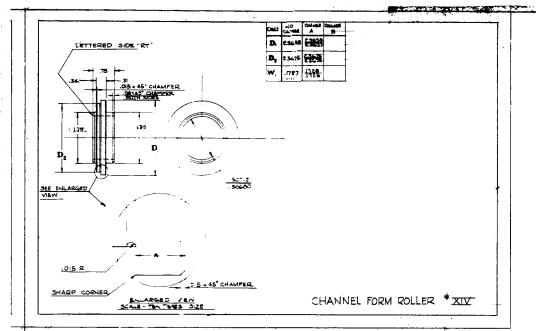
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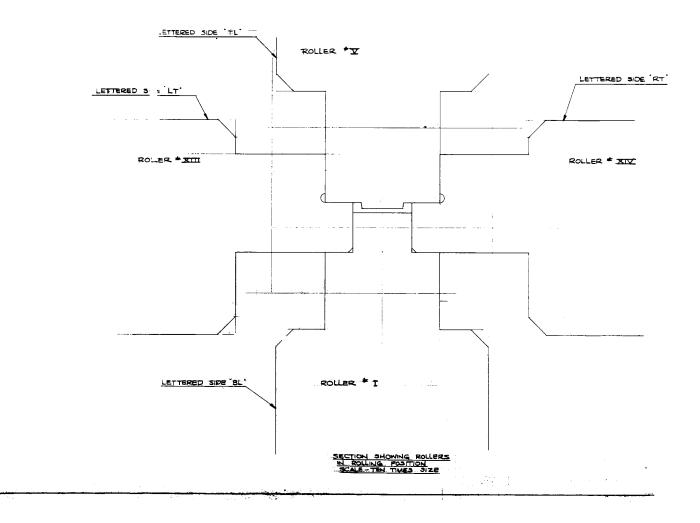
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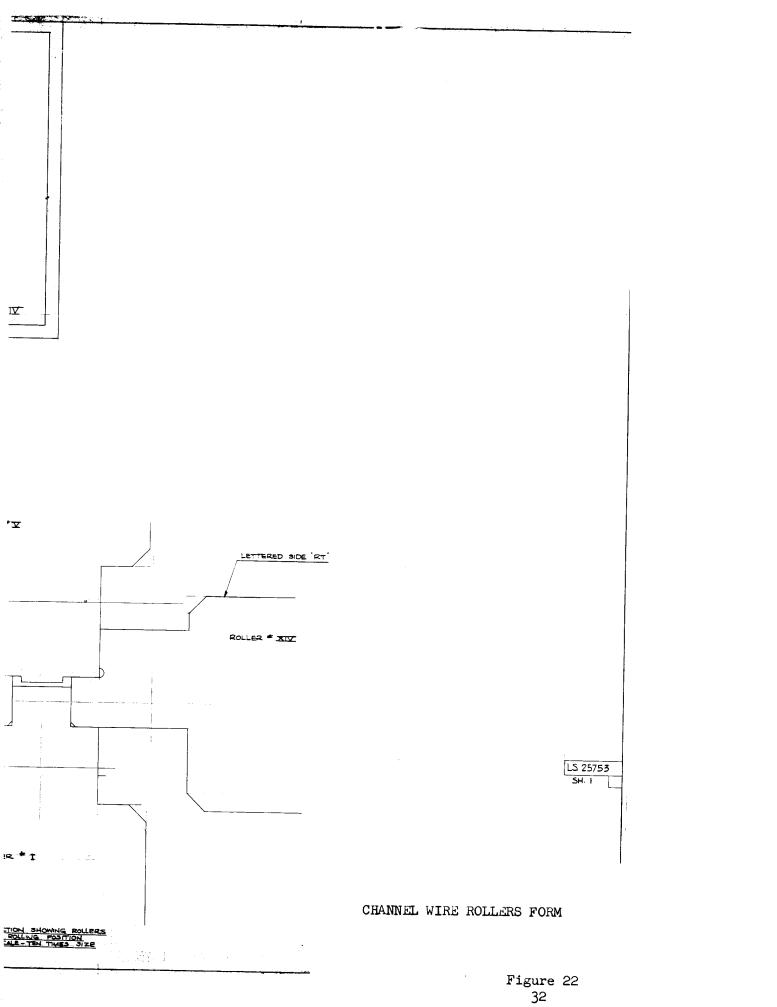


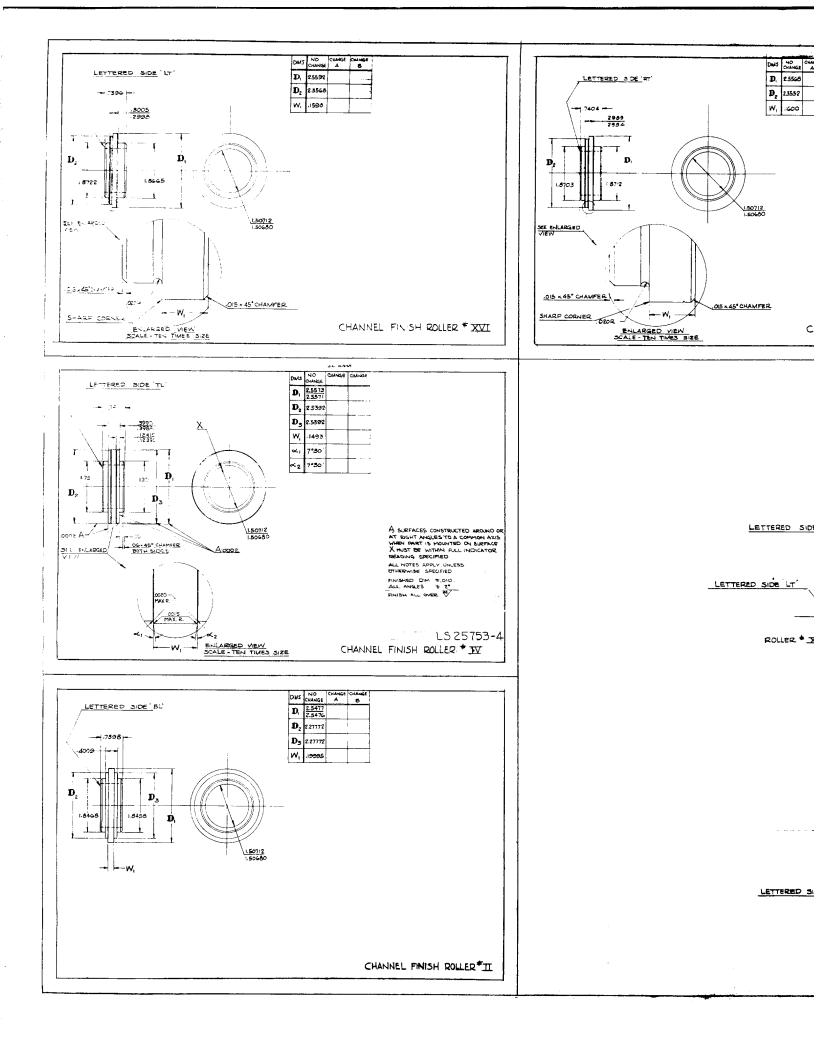


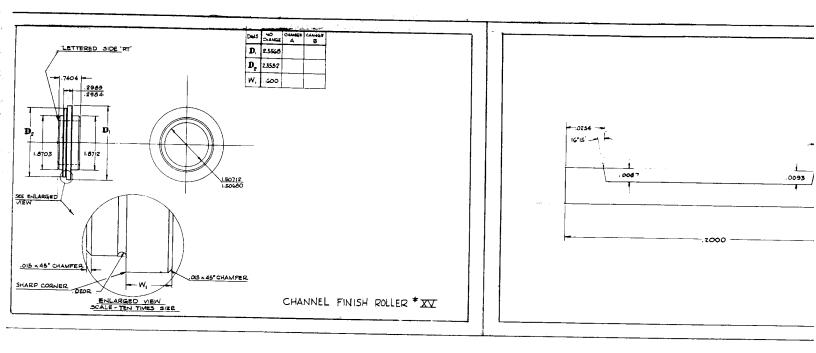


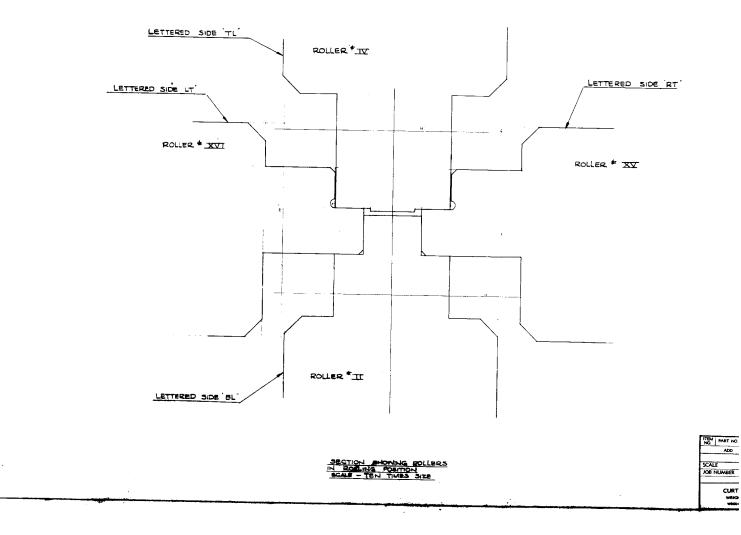


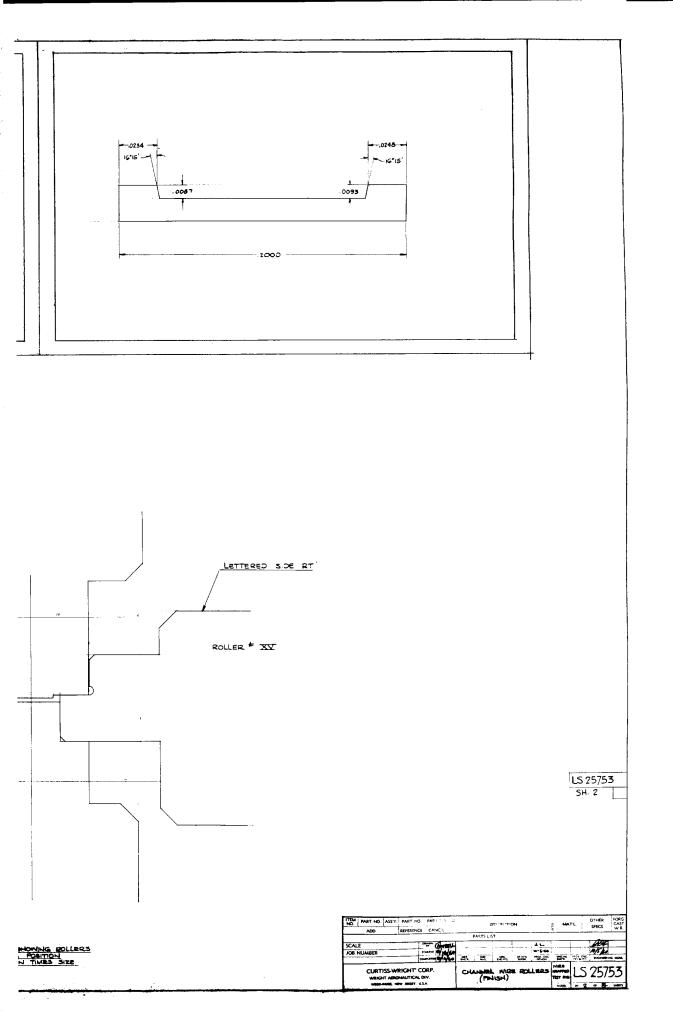


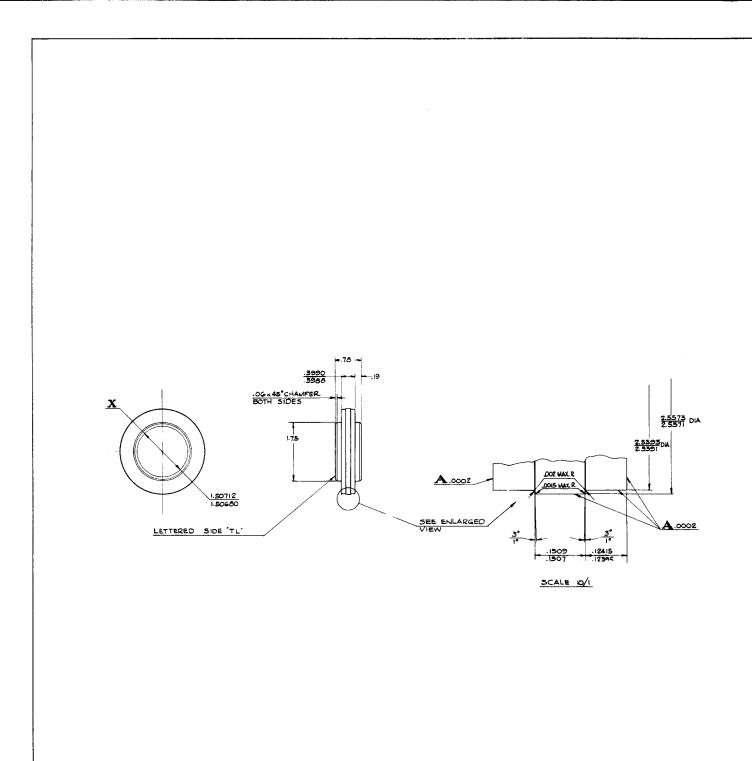




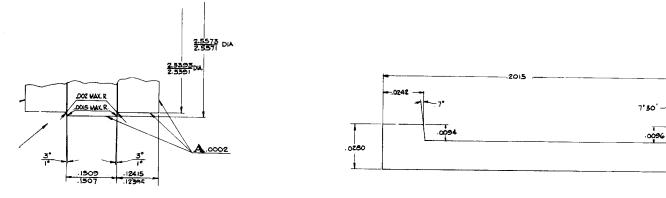








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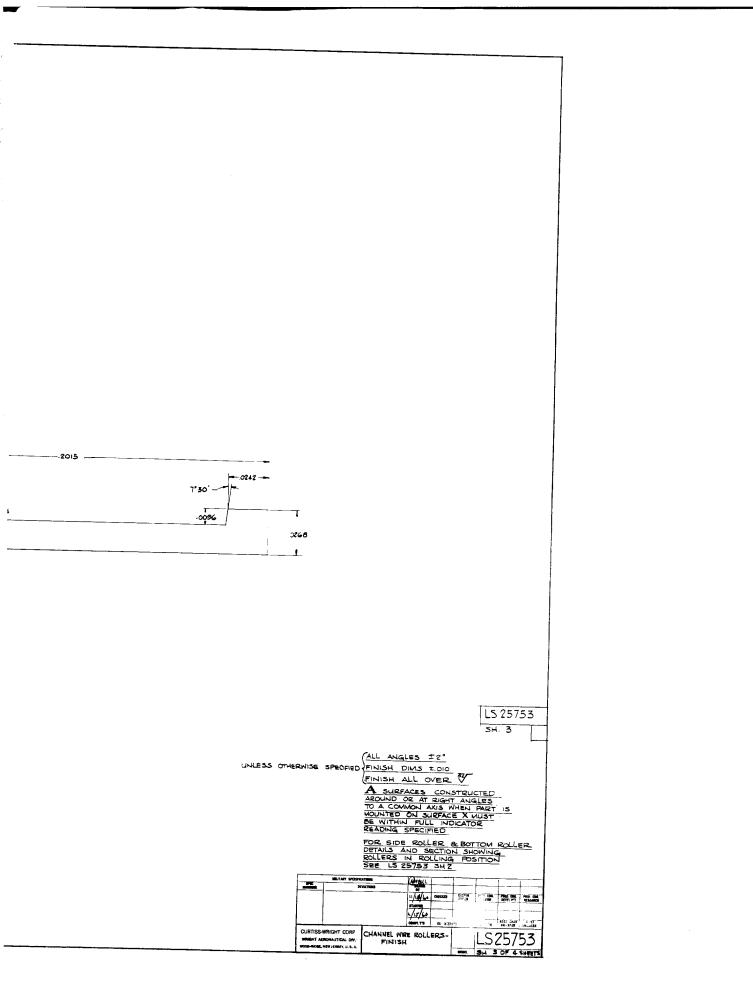
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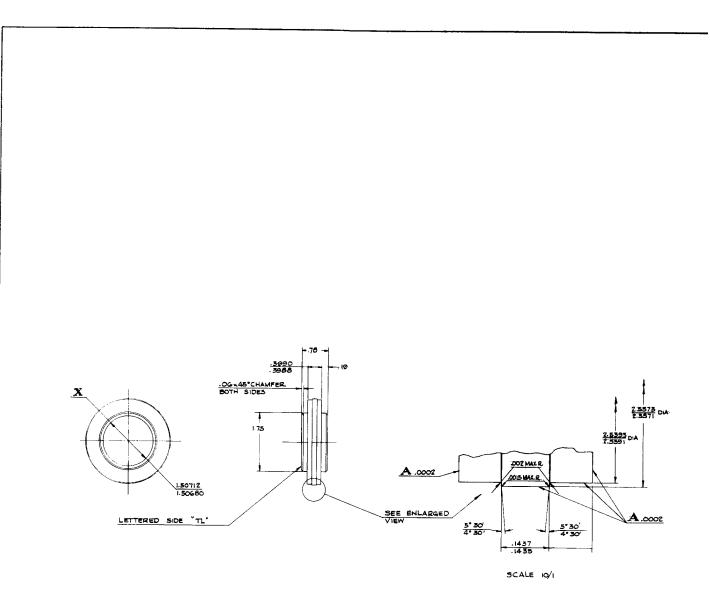
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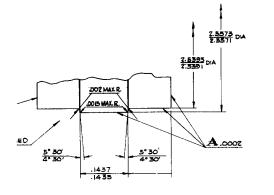
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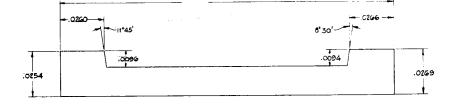




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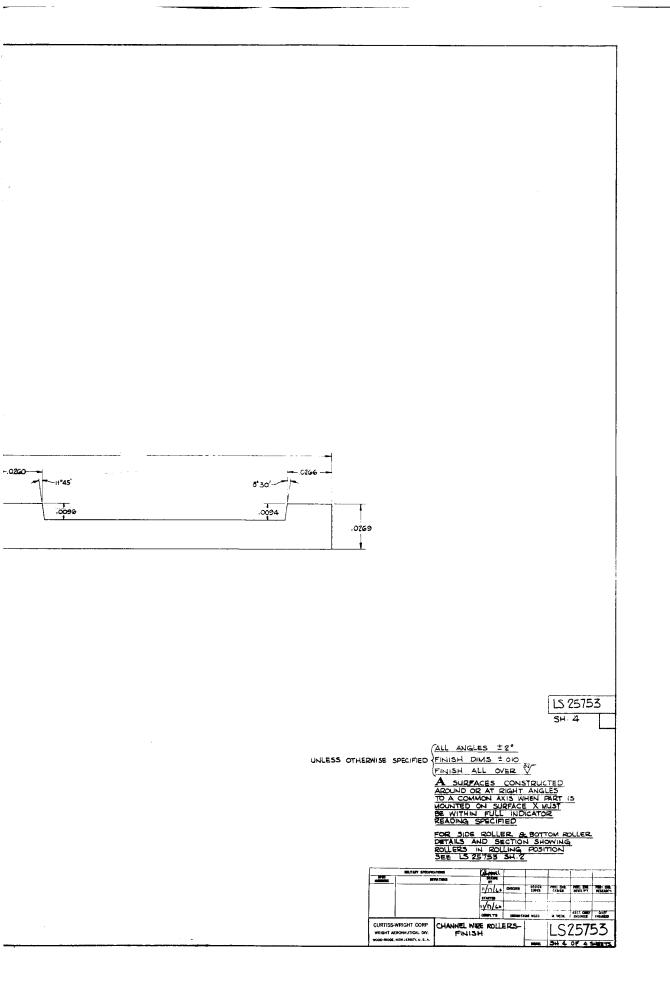
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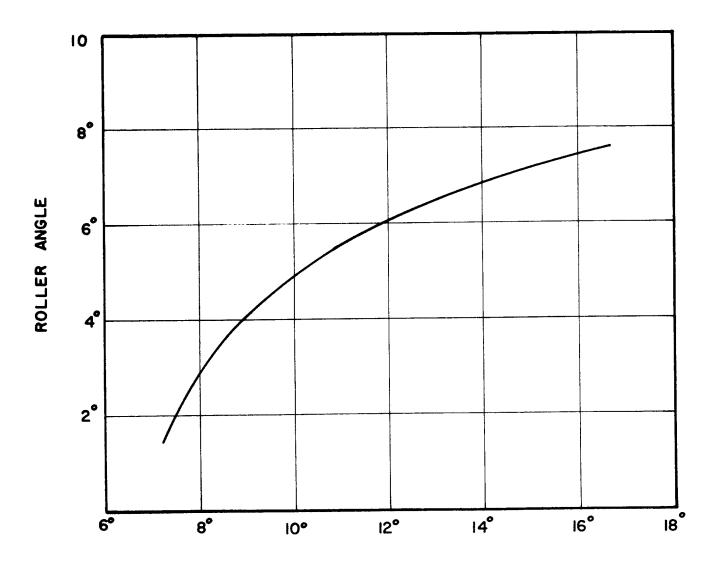


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CHANNEL TAPE ANGLE

5.0 METALLURGY

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5.0 METALLURGY

5.1 Work Statement

Metallurgical work carried out under the present contract includes tape manufacture, development of measuring techniques, measurement of interference fit, development of heat treatment, determination of frictional coefficients, evaluation of liner and bonding methods and a limited number of low temperature tensile tests.

5.2 Starting Material

Commercial B120VCA titanium alloy weld wire produced by centerless grinding and drawing was procured in the mill annealed condition. Two sizes, .154" and .123" were evaluated resulting in the final selection of .123" nominal gage for both shapes. The fabrication of lengths in excess of 100 ft., though successful in some heats, resulted in cracking and rupture in the case of the most recently purchased material. Poor wire surface in "as received" material was observed to contribute to this problem. Superficial pickling, either acid or basic, found effective in improving surface condition was not always found to alleviate the problem. Other possible causes include hydrogen embrittlement, surface contamination, and variances in chemical composition. In order to insure quality and uniformity in future purchases a specification for B120VCA material in the form of coils of wire was prepared. This specification is reproduced in detail in Appendix III.

5.3 Rolling Techniques

5.3.1 Round Wire Breakdown

5.3.1.1 "I" Beam

The round wire discussed in Section 5.2 is cold reduced to a rectangular shape prior to further reduction in the Turks head mill. Originally, a Universal Turks head was used to produce all rectangular shapes. This procedure was abandoned in favor of a more rapid procedure which utilizes power driven rolls. The current breakdown is carried out in a groove mill and a flat mill, and is as follows:

5.3.1.1 "I" Beam (Continued)

Pass No.	Mill	Thickness of Rectangle	Width of Rectangle
1	Groove	.118	.118
2	Groove	.108	.108
3	Groove	.100	.100
4	Flat	.092	.108
5	Flat	.084	.116
6	Flat	.076	.124
7	Flat	.068	.132
8	Flat	.062	.140

5.3.1.2 Channel

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The breakdown of round wire into rectangular cross-sections for the channel tape is more complicated since the amount of spread (.121" Dia. to .2165") is much greater. This procedure also requires the use of a groove mill and a flat mill, and is as follows:

Pass No.	Mill	Thickness Rectangle	Width of <u>Rectangle</u>
1	Groove	0.1050	0.1320
2	Groove	0.0990	0.1352
3	Groove	0.0950	0.1395
4	Groove	0.0900	0.1425
5	Groove	0.0855	0.1466
6	Flat	0.0810	0.1510
7	Flat	0.0760	0.1570

5.3.1.2 Channel (Continued)

Pass No.	Mill	Thickness of Rectangle	Width of Rectangle
8	Flat	0.0720	0.1615
9	Flat	0.0590	0.1760
10	Flat	0.0540	0.1816
11	Flat	0.0494	0.1887
12	Flat	0.0443	0.1950
13	Flat	0.0396	0.2030
14	Flat	0.0350	0.2100
15	Flat	0.0310	0.2165

The problem of reducing round wire to the rectangular starting shapes necessary for Turks heading was further complicated by the necessity of avoiding the use of oxide coatings which normally serve as lubricants. Oxide coatings were found to result in embrittlement in the subsequent Turks heading operation.

5.3.2 Turks Heading of Rectangular Wire

Initially, two procedures of cold reducing rectangular Bl2OVCA titanium wire were considered. Use of power driven rolls in a "shell mill" was believed to offer the advantages of spreading rather than elongating the material and allowing heavier reductions per pass because no extremely heavy pull was needed. It was, however, found that the accuracy of the shell mill was not sufficient to maintain the critical internal shapes, particularly the angles. Heavy passes resulted in cracking of the wire. Intermediate annealing was discarded since it lowered the attainable strength of the final product. Emphasis was, therefore, placed on the Turks heading method.

5.3.2 Turks Heading of Rectangular Wire (Continued)

This method, utilizing idling rolls through which wire is drawn, was believed to offer greater flexibility and sensitivity of adjustment, hence, better accuracy. The Turks head mill is an apparatus comprising four rolls which are housed at a 90° angle to one another. Depending on the model, the rolls may be adjusted independently or in pairs. The rolls can move in one direction only, i.e., up or down. A third available model, the "combination" Turks head incorporates the above and in addition, provides means for lateral adjustment.

It was initially thought that by limiting reductions in each pass to a small percentage, large total reductions in area could be obtained. In addition, it appeared advisable to employ one or more intermediate anneals.

Numerous samples were produced by thus "babying" the material, but with varying degrees of success. Intermediate anneals were found to reduce the final attainable strength. It was found that optimum aging response was obtained when the cold worked material after the final pass exhibited a tensile yield strength of 210,000 psi.

Patterning the shaping steps for either the "I" beam or channel shapes after steel mill practice proved unrewarding since the flow characteristics of titanium are totally different. The forming rolls, each taking relatively heavy reductions, were arrived at by trial and error. An extremely heavy finishing pass was necessary in order to avoid steps in the internal walls.

Though the finished dimensions obtained by the heavy reduction method proved superior to those produced by the previously used light reduction method, a number of new problems were introduced. These problems included cracking of the rolls as well as excessive wear of the roll arbors. Changes in the roll materials, heat treatment and chrome plating of arbors, though successful to a limited extent, were not considered satisfactory for rolling long lengths. Consequently, a larger Turks head mill (No. 3TH) was purchased. This resulted in lower Hertz stresses in the rolls and lower bearing stresses in the arbors. A Kerosene-water mixture was used as a lubricant.

5.3.2 Turks Heading of Rectangular Wire (Continued)

The techniques developed for the processing of tape in the small mill were found applicable in the larger mill, resulting in the successful production of the desired shape (Figure 3). Roll design, spring back calculations and modifications of rolls are reported in another portion of the present report (Section 4).

5.3.2.1 "I" Beam

Using the procedure outlined in the above section, the best "I" beam shape was produced in two (2) heavy passes. The first pass reduced the webb to 0.0416 and the overall length to .1370. The final pass reduced the webb to .0395 and the length to 0.134.

5.3.2.2 Channel

The final channel cross-section being smaller, but wider, than the "I" beam required somewhat smaller reductions. The following is the procendre employed for the manufacture of the channel type.

Pass No.	Channel Webb Thickness	Channel Width
1 2 34 56 7 8 9 10	.029 .027 .025 .023 .021 .0195 .0185 .0175 .0165 .0155	.2045 .2043 .2042 .2041 .2041 .2040 .2035 .2030 .2000 .2000

Figure 27 illustrates the major steps in the fabrication of the channel shape. As illustrated, shapes K through O contain ridges at the base of the channel which are used to force material to flow upward.

Figures 28 and 29 illustrate both cross sections in the etched and unetched condition. As may be observed from Figure 29, flow lines follow the internal corners indicating favorable flow with respect to the interference fit and final pressure vessel requirements.

5.4 Evaluation of Measuring Techniques

The measurement of both shapes has presented a serious problem due to the close tolerance requirement imposed. An investigation of several measuring methods was carried out. These include measurement by means of a comparator, projection by means of a metallograph, micrometer measurement of external dimensions, measurement of a calcium sulfate mold and use of toolmakers' microscopes and air gages.

The projection of both shapes by means of a comparator resulted in readings differing by as much as .0025 from outside dimensions as measured by a micrometer. This was primarily due to distortion in the tape produced by cutting. Glancing of the comparator beam from a flexed portion of the tape also proved inaccurate because of distortion.

The above attempt also showed that any twist or bend could produce erroneous results. This imposed the requirement that measurement must be made in a perpendicular plane. This was accomplished by copper plating (non-adhering) the tape to a thickness of approximately 0.005 inch. The tape was then placed in special metallographic clamps as illustrated in Figure 30. The specimen was then polished metallographically and photographed at 50X. The photographs were then measured.

Comparison of the results obtained using the above procedure with micrometer measurements revealed a difference much less than those obtained with a comparator. However, this difference (.0005 - .0001 inch) was still considered too great. It was decided that the metallographic method be used to measure only dimensions which could not be measured with a micrometer.

In an effort to obtain greater accuracy a fourth method was attempted whereby a small mold was clamped onto a portion of the tape, and filled with $CaSO4*\cdot 1/2 H_2O$ solution. This solution was allowed to set for 2 hours. The impression thus produced was then projected on a comparator and measured. These measurements also did not agree (0.001 inch larger) with micrometer measurements.

External comparators, toolmakers' microscopes, and air gages, in combination, were tried next. A comparison of the dimensions obtained by this method versus those obtained by metallographic and micrometer methods is as follows:

5.4 Evaluation of	Measuri	ng Tech	niques	(Conti	nued)		
	Width	Height	Groove Depth	<u>}1</u>	<u>}2</u>	<u> 23 24</u>	
"I" Beam						000 150	
Non-Metallographic Metallographic	.1378 .1343	.060 .0586	.0093 .0100	7 ° 30'	6 0	20° 15° 16° 15°3	30'
Channel							
Non-Metallographic Metallographic	.2025 .2015	.0265 .0268	.0095 .0095	90 70	14° 7°30'		

Note:

1 = top left side
2 = top right side
3 = bottom left side
4 = bottom right side

The above comparisons show that there is a large discrepancy between the two methods. More significant however, is the fact that the non-metallographic measurements do not agree with succeeding attempts to measure the same tape.

5.5 Interference Fit

It was desired to obtain a measurement of the forces involved to produce an interference fit between the "I" beam and the channel, even though the "I" beam was out of tolerance initially. The test was accomplished in the following manner: Two one inch lengths of channel were butted against each other and the "I" beam placed over the flats. Two more channels were then added to complete the top layer. The assembly was then hydraulically pressed together in a flat position. The gauge pressure was increased from 0 to 3000 psi, to 5000 psi, to 7000 psi and finally to 10,000 psi. At each pressure reading the tapes were polished, etched and photographed. Pressure was maintained on the sample at all times.

This procedure determined the force required to produce an interference fit.

5.5 Interference Fit (Continued)

A determination of the force needed to achieve an interference fit is carried out as part of evaluation of each tape lot produced. Figure 31 shows the results of pressing together the tapes shown in Figure 32. The load was applied in the center of the "I" beam. It may be noted that the center of the "I" beam has deflected before one side has had a chance to seat. This caused a cocking effect resulting in an unsatisfactory interference fit. Another set of channels and an "I" beam were pressed together with the load applied to the "I" beam flanges. The result is illustrated in Figure 33. This loading method eliminated some of the bowing and resulted in better seating of the sides. The lack of good fit is due to the undersized width of the "I" beam groove. Despite this the tapes stayed locked after the load was released.

In order to determine the amount of interference fit from the standpoint of assembled dimensions and force needed for separation, an experiment was carried out whereby the "I" beam and channel tapes shown in Figures 21 and 25 were pressed together (2 layers) and the total thickness measured (from inside of "I" beam to outside of channel) as a function of applied load. The results are given in Figure 34. It can be seen that a 2400 psi force was necessary to initiate a permanent interference fit and a 5000 psi force was necessary to seat the "I" beam on the channel. Figure 36 shows a 3 layer assembly pressed together under a 5000 psi force. Though some separation is still believed to be present, the illustration exaggerates this due to rounding of edges during polishing. This fact is confirmed by observation of strain markings adjacent to "gaps" when the assembly was subjected to higher compressive loads.

In order to estimate the force needed to overcome the interference fit, the fully seated sample was attached to small tensile machine grips by means of wires. Despite non-concentric loading, a load of 14 pounds was required to fail the 1" long assembly. Reseating of the specimen and repetition of the test resulted in a failure load of 11 lbs. A third test of the same specimen yielded a failure load of 6 pounds.

The values obtained are considered sufficient to prevent unwrapping (during vessel assembly) of a partially wrapped layer upon removal of the restraining forces imposed by the wrapping mechanism and drag break. This was verified during trial wrapping of a dummy arbor.

5.6 Tensile Testing Apparatus

All attempts to test both "I" beam and channel shaped tapes in tension have failed to give reproducible values. This is due to the fact that the tapes broke at the grips. Consequently, a rig has been designed whereby the tape is wound on a drum at each end. These drums, in turn, have plates welded to them which are held by the grips. The frictional force created by the wound tape is sufficient to prevent slippage. This apparatus has been constructed and is shown in Figure 36 (LS 25806).

5.7 Heat Treatment

The heat treat proceudre was designed to produce optimum properties in both channel and "I" beam tape, keeping in mind the goal of a 250,000 psi yield strength with 4 percent ductility.

The specimens to be heat treated were first degreased and then capsulated in vacuo. Heat treatment was carried out in a furnace of constant heat zone (\pm 5°F) for various times ranging from 5 hours to 38 hours at a given temperature. This procedure was repeated at several temperatures until the time and temperature to produce maximum properties was found. The results are presented in the following sections.

5.7.1 Channel Heat Treatment

The results of aging channel tape are presented in Table I and Figure 37. The maximum yield strength was obtained after aging at 700°F for 12.5 hours. The yield strength produced by this treatment was approximately 278 ksi while the ultimate strength was 280 ksi. The elongation was 1.5 percent in an 1" gage length. This heat treatment results in approximately the same properties as the "I" beam heat treatment.

5.7.2 "I" Beam Heat Treatment

The results of aging "I" beam tape are given in Table II and are presented in Figure 38. The maximum yield strength was obtained after aging at 750°F for 25 hours. The ultimate tensile strength produced by this treatment was approximately 279,000 psi and the yield strength was 272,000 psi. The elongation was 1.5 percent (1" gage length).

5.7.3 Metallographic and Hardness Study

The aging response of the channel tape as a function of percent reduction in area and hardness was investigated. This was accomplished by aging samples, having the cross-sections shown in Figure 27 at 750°F for 20 and 46 hours in a vacuo. The resulting microstructures are presented in Figure 39. It may be seen that these microstructures indicate behavior in a normal fashion with evidence of aging taking place at the first Turks head breakdown pass on (a) and (b). The presence of a spheroidal precipitate (probably TiCr2) shown in Figure 39 (c) is indicative of overaging.

A Vickers hardness survey using a 5 kilogram load was taken across the above specimens. The results are shown in Figure 41. The curves indicate an increase in hardness with increasing reductions. The 47 hour-aged hardness is less than the hardness obtained with the 20 hour treatment.

5.8 Elimination of Twist* and Bow **

Twisting and bowing of tapes was found to cause difficulty during the wrapping operation. Twisting resulted in cocking, particularly in the case of the "I" beam, resulting in loss of interference fit. Bowing resulted in a "pre-set" helix causing difficulty during stacking, particularly in the case of the first channel layer.

Both problems are associated with the use of the bull block which supplies the force necessary to draw the tape through the Turks head. In order to eliminate bowing as well as twisting, a specially designed arrangement is being substituted for the presently used bull block.

5.9 Coefficient of Friction

The design of both channel and "I" beam shapes assumed a coefficient of static friction of 0.3-0.5. An investigation to determine the actual value was performed in the following manner:

Twist - Rotation of cross-section about tape axis.
 ** Bow - Bending of the tape axis parallel to the plane of the web.

5.9 <u>Coefficient of Friction (Continued)</u>

Two titanium channel tapes were mounted back-to-back and clamped with a predetermined load (Figure 41). The channels were then pulled in opposite directions and the load to initiate slippage noted. This experiment was repeated with different clamping loads and the corresponding slippage loads recorded. The results are tabulated in Table III.

An increase in the coefficient of static friction from .270 to .348 as a result of heat treating was observed. Analysis shows the interlock to be effective only when the condition $\tan \theta < \alpha$ is satisfied, where θ is the interference fit angle, and α the coefficient of static friction. Figure 42 shows the derived relationship between the tape angle and coefficient of friction.

5.10 Evaluation of Bonding Methods

In accordance with design requirements, it is essential that the tape be bonded to the adapters. The possibilities considered include brazing, soldering, ultrasonic welding, and the use of resins.

The goal was to obtain a tensile shear strength of 4,500 psi with 0.001" strain.

Brazing was not attempted since the temperatures involved are usually above 1000°F which is in excess of the upper limit of the aging temperature. Low temperature brazing or soldering and ultrasonic welding were found unsatisfactory. Epoxy resins appeared attractive since they are either room temperature curing or cure at slightly elevated temperatures. An evaluation was carried out wherein a piece of steel large enought to contain a piece of Bl20VCA channel tape was zirconite blasted and degreased. The titanium tape was cleaned in 3 parts HF-30 parts HNO₂ solution for one minute and washed in water. The resin was applied to both parts which were then allowed to come in contact with each other. The specimens were pulled in uniaxial tension using self-aligning grips. A deflectometer was used to measure the cross-head movement. B120VCA channel tape was previously tested and stress-strain curves determined. At given loads a corresponding strain of the tape was subtracted from the total deflection and stress-strain curves for the resins were then drawn. From these curves a modulus of elasticity for each resin was calculated.

5.10 Evaluation of Bonding Methods (Continued)

Tests showed that the resins all had modulli of elasticity in the neighborhood of 10,000 to 25,000. These results are tabulated in Table IV and are illustrated in Figure 43. It was found that Maraset (Marbellette Corporation) had the highest strength and elastic modulus while Bondmaster (Rubber and Asbestos Corporation) was next. Eastman 910 and Goodyear Plibond did not adhere. Since a value of 4,500 psi was required at a 0.001" strain, the material would require a modulus of elasticity of 4.5×10^6 . This could not be attained in resins.

5.11 Vessel Liner Evaluation

A test was carried out to determine the adherence and elastic properties of Teflon as a vessel liner. The vessel is so designed that a sharp angle exists where the first tape layer leaves the adapter. For testing purposes two (2) pieces of metal (titanium and steel) were joined together as shown in Figure 44. Teflon was then sprayed over the joint and the metal pieces pulled in tension with a 4500 pound force.

The results of this test showed that Teflon could not be relied upon to fill this corner and provide a leak-tight joint. In view of this, a modified Teflon and vinyl were tried. The results of this evaluation indicated that the modified Teflon flaked when subjected to tensile loading. However, the vinyl coating withstood the required strain (4500 lb. load) without any noticeable cracking or flaking.

5.12 Cryogenic Properties of Bl20VCA Ti

The results of limited low temperature tensile tests are presented in Figure 45 and shown in Figure 46.

The room temperature smooth sheet specimens had a gage length of 2-1/2" and a width of .400 \pm .005". The low temperature smooth sheet specimens were the same except that the specimen width was .250".

The notched specimens were the same as the room temperature smooth specimens, except for a notch with a root radius of $0.010 \pm .001$ ", an included angle of 45° and the minimum width was .270 $\pm .003$ ".

It can be seen from these results that this alloy is not reliable for cryogenic vessels, the notched-to-unnotched tensile strength ratios being 0.34 at $-320^{\circ}F$.

Tests run on a second heat and a 0.050" gage thickness produced the same results.

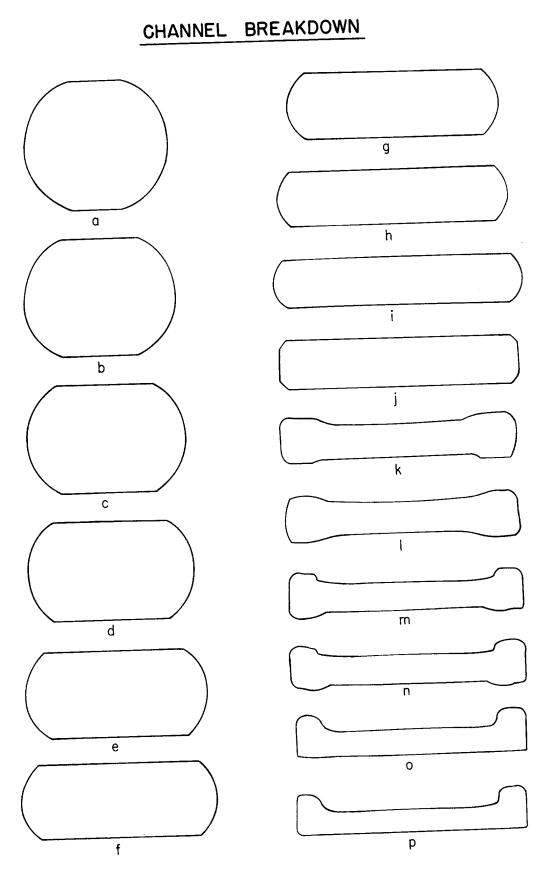
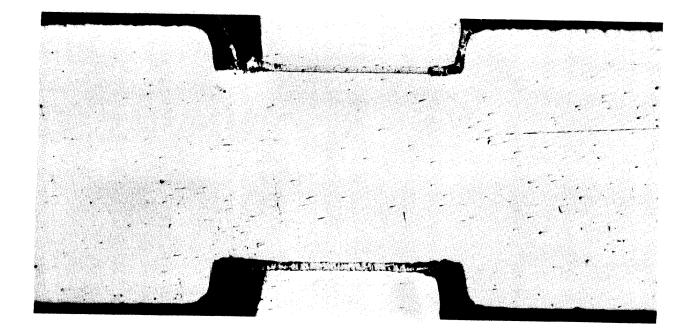
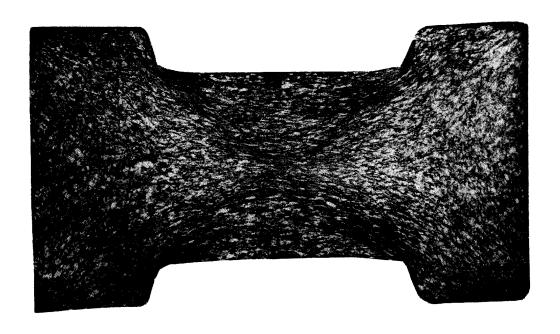


Figure 27 49



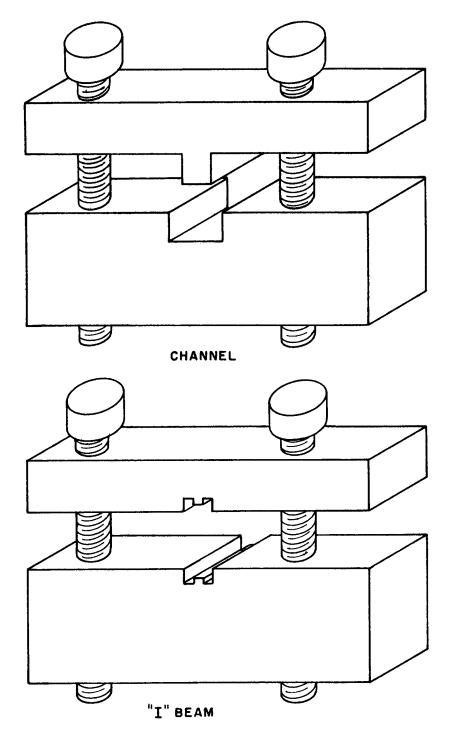


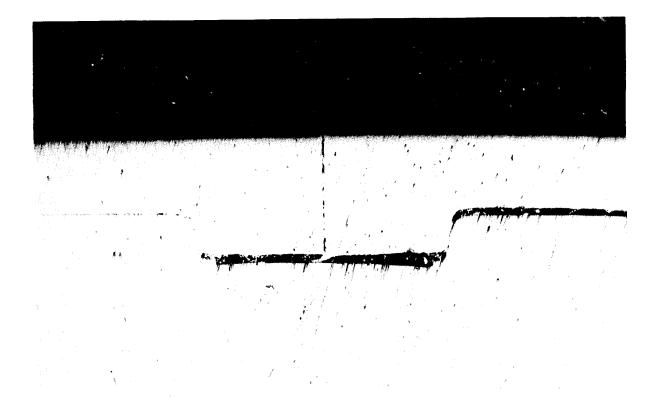
Specimens Mounted for Measurement



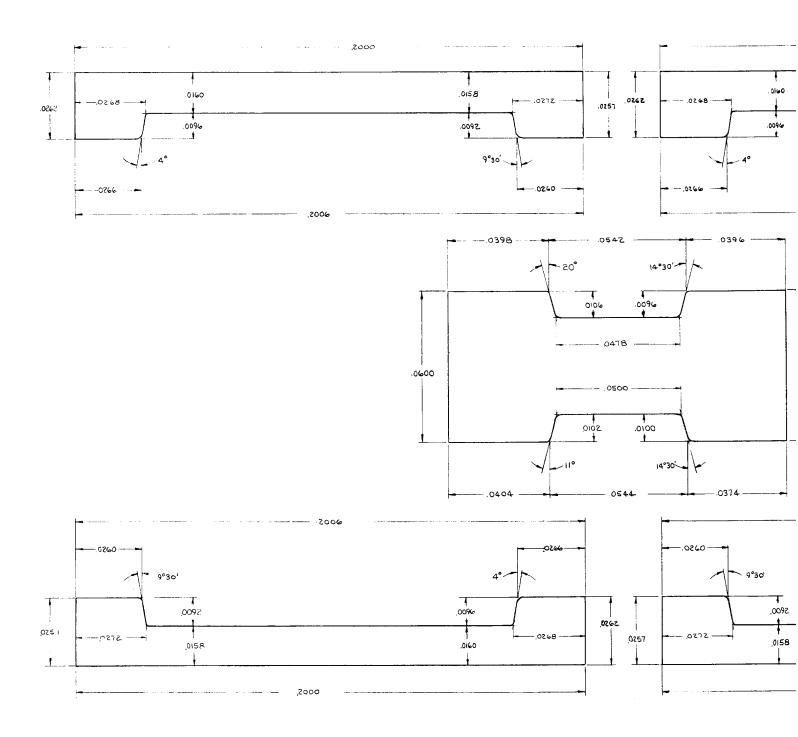


"I"-Beam and Channel Flow Lines

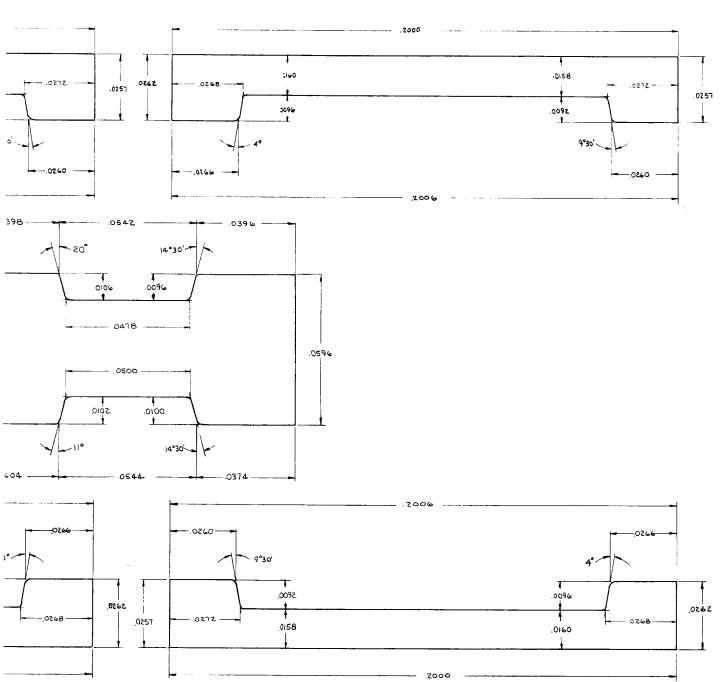




"I"-Beam - Channel - Pressed

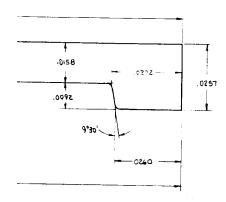


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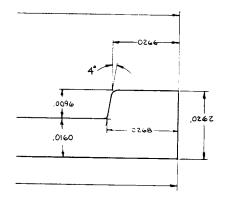
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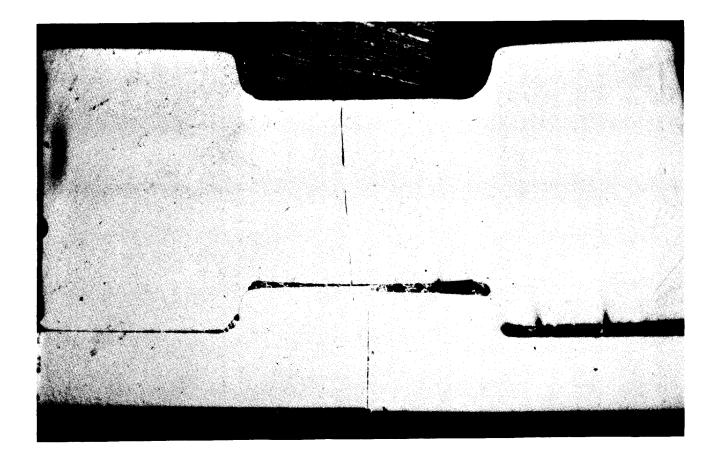
. 1



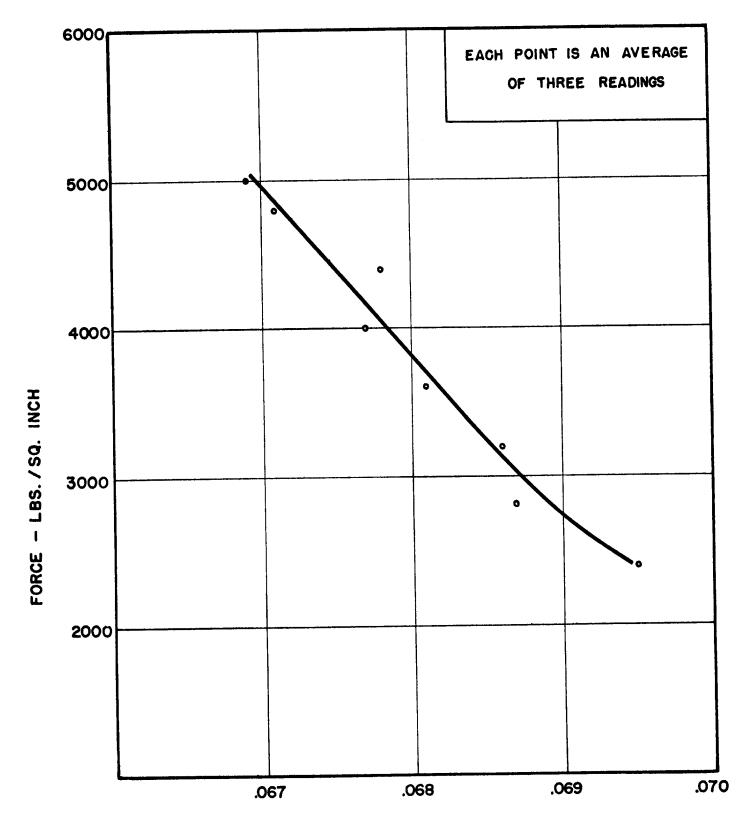
DATE -

DUMBBELL LOAD	LBS
CHANNEL LOAD	
- · · · · · · · · · · · · · · · · · · ·	LBS.
YIELD STRENGTH	85.1.

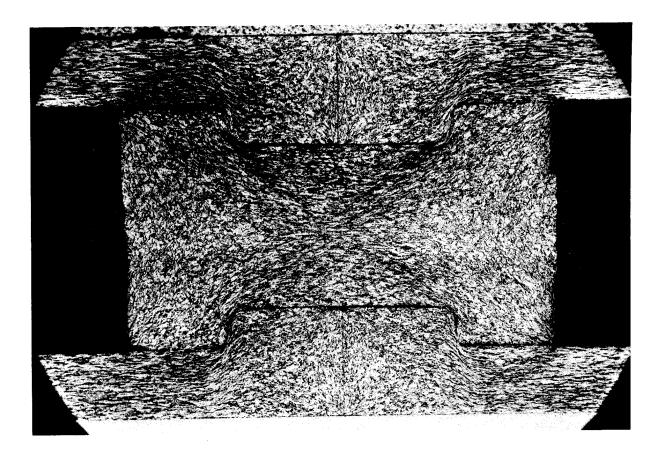




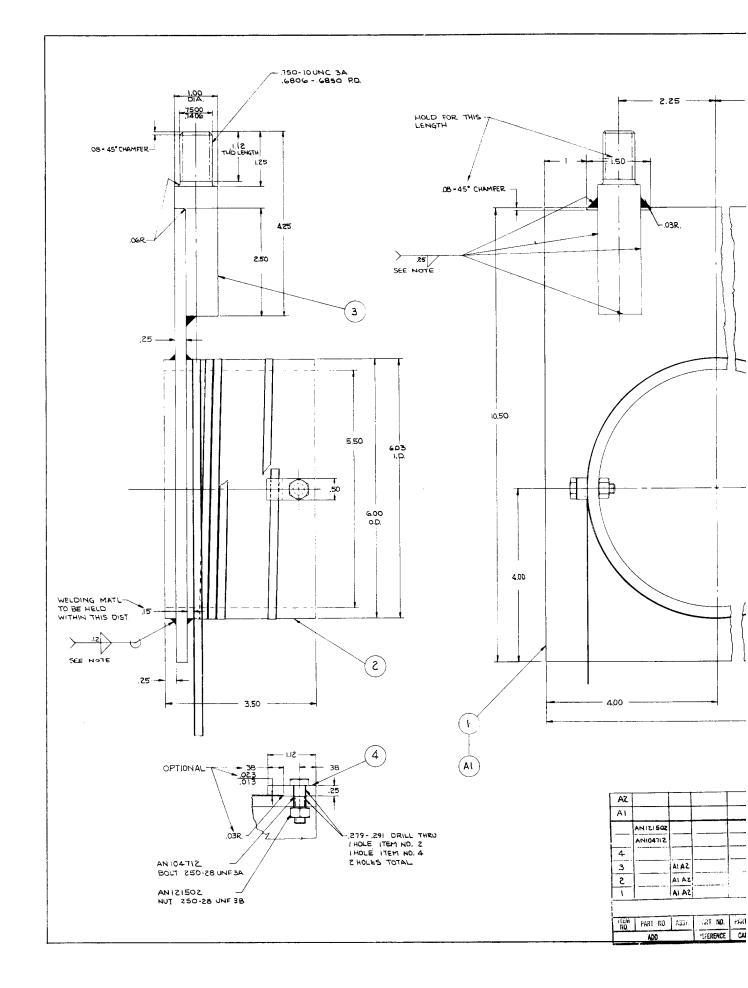
"I"-Beam - Channel - Pressed







Three Layer Interference Fit



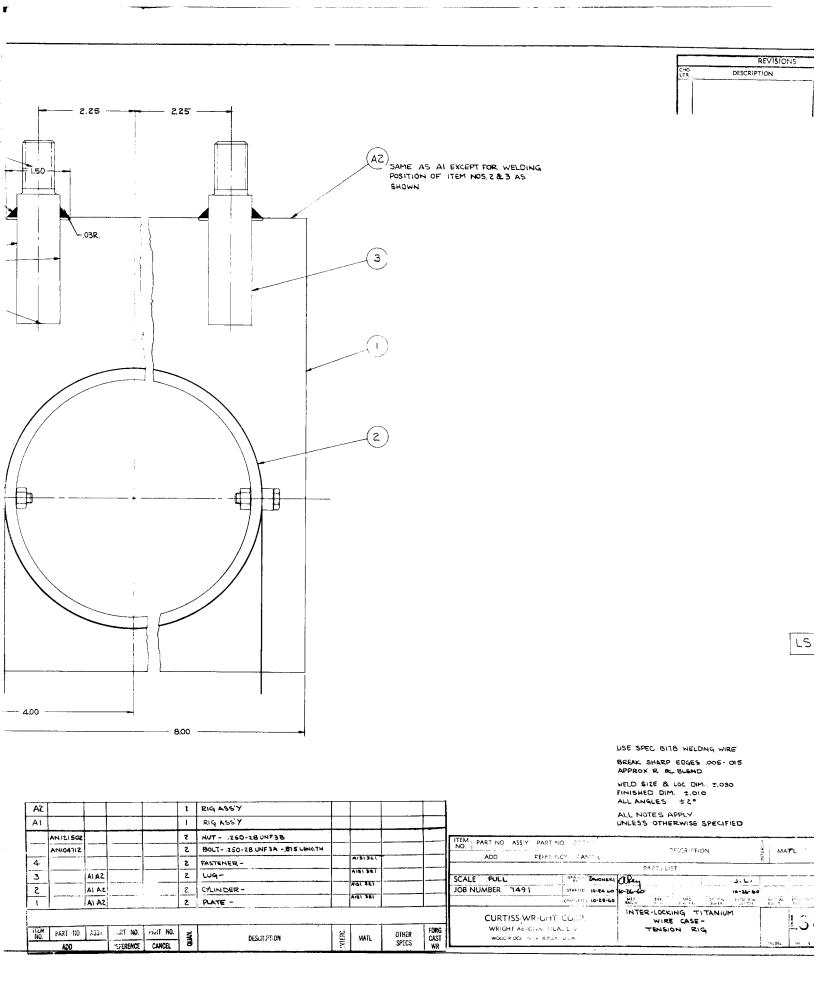


Figure 36 58

Tension Test R

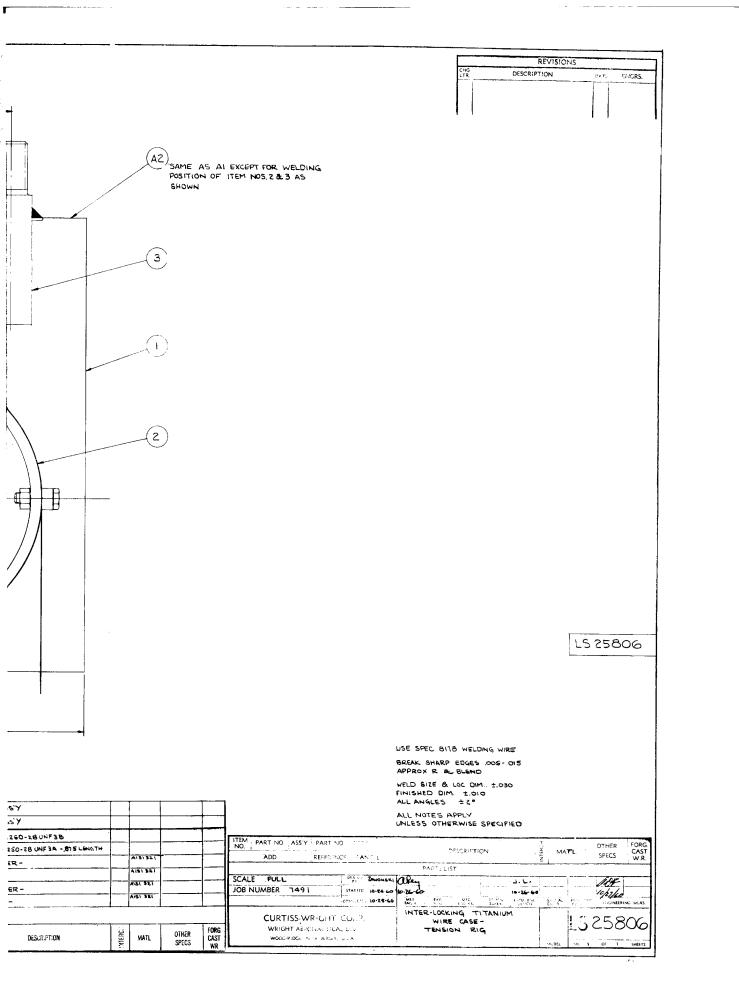


Figure 36 58 Tension Test Rig

TABLE I

AGING RESPONSE OF B120VCA TITANIUM WIRE

ROOM TEMPERATURE TENSILE PROPERTIES OF "CHANNEL" WIRE

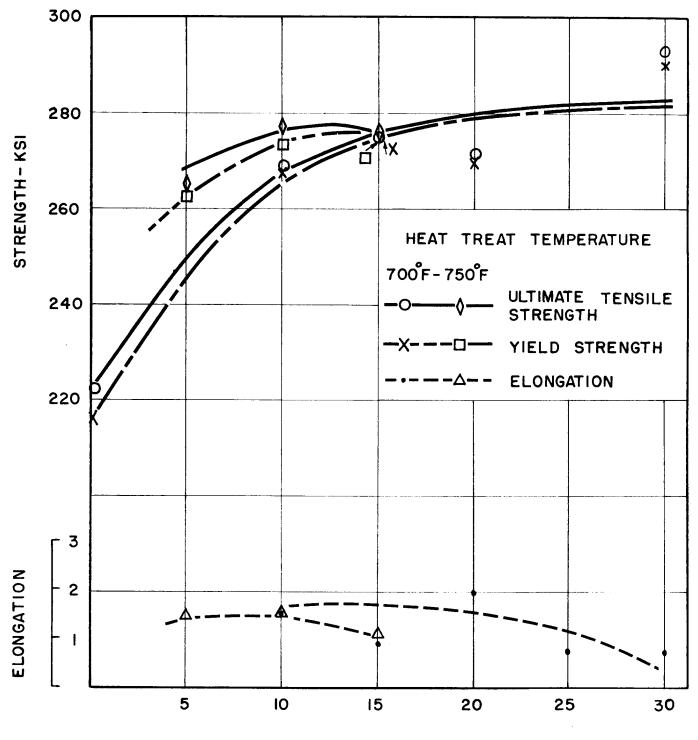
Elongation in 1" <u>Avg. Range</u>	3.1 2.5 2.0-3.0).1 1.5 1.5 	5.8 1.0 1.0	5.2 2.0 2.0	0.75 0.5-1.0	3.9 0.75 0.5-1.0	3.0 1.5 1.0-2.0	1.5 1.5	8.0 1.0 1.0		0.75	0.1 0.1
Yield Strength (.2% Offset) Avg. Range KSI KSI	215.9-218.1	268.7 ***268.5-269.1	274.4-275.8	264.6-275.2	***280.2	286.0-293.9	262.4-263.0	273.8	271.0-278.0		***289.4	***293.9
Yield (.2% C Avg. KSI	217.0	268.7	275.0	270.0	I	290.0	262.7	273.8	274.5		ł	1
mate Tensile Strength Range KSI	221.2-224.2	**267.4-271.0	**274.9-276.9	265.2-277.2	**278.8	***286.0-296.4	264.9-265.7	277.7	271.6-280.8		**287.2	**283.6
Ultimate Strer <u>Avg.</u> KSI	222.7	269.0	275.9	271.5	t	291.2	265.3	277.7	276.2	***	· 1	I
lition	0 hrs.	lo hrs.	15 hrs.	20 hrs.	25 hrs.	30 hrs.	5 hrs.	10 hrs.	15 hrs.	20 hrs.	25 hrs.	30 hrs.
Aging Condition	As rec'd.	7000F	7000F	7000F	7000F	700 ⁰ F	750°F	750°F	750°F	750°F	750of	750°F

Wright Aeronautical Serial Report No. MP.00-224

Elongation in 1" <u>Avg. Range</u>	5 C	0.75 0.5-1.0	0.75 0.5-1.0	0.5 0.5	1.0 0.5-1.5	1		/ield strength.	
Yield Strength (.2% Offset) Avg. Range KSI KSI	***294.7	275.0 274.6-275.5	280.5 279.7-281.3	275.0 ***274.4-275.8	269.1 269.1		emperature in vacuum.	strength which is related to yield strength.	, reuguu
$\frac{Y_1}{AV}$	t	27	28	27	26		oom t∈	ngth w	
Ultimate Tensile Strength Avg. Range KSI KSI	**291.1	273.5-279.7	280.2-285.8	**268.8-270.8	271.0		samples cooled to room temperature	Sample failed at listed strength which is Extrapolated value of the vield strongth	
Ultima St <u>Avg.</u> KSI	ł	275.9	283.0	269.8	271.0	***		failed lated v	
Condition	38 hrs.	lo hrs.	15 hrs.	20 hrs.	25 hrs.	30 hrs.	All wire	** Sample *** Extrapo	4
Aging Cor	750°F	800 ⁰ F	800°F	800°F	800 ⁰ F	800 ⁰ F	NOTE: *	* *	

TABLE I (Continued)

-60-

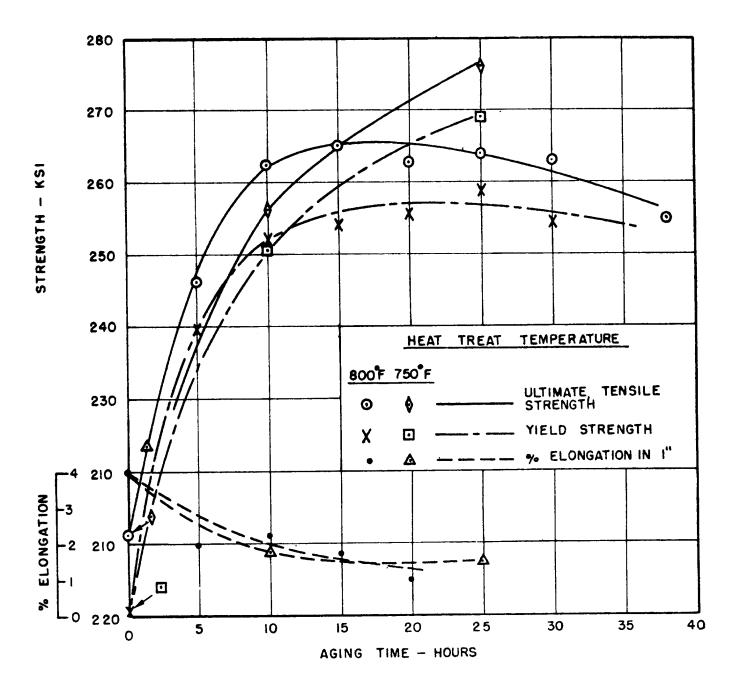


AGING TIME - HOURS

TABLE II

"I" BEAM SHAPE HAVING CROSS-SECTIONAL AREA = 5.0×10^{-3} IN²

Aging Temperature and Time	U.T.S. (ksi)	Y.S. (ksi)	Elongation in 1" (%)
As Received (50% cold work)	211.3	204.2	4.0
800°F - 5 hours	246.2	239.75	2.0
800°F - 10 hours	262.5	252.5	2.25
800°F - 15 hours	265.0	254.0	1.75
800°F - 20 hours	263.0	255.5	1.0
800°F - 25 hours	264.0	259.0	
$800^{\circ}F = 30$ hours	263.0	254.5	
800°F - 38 hours	255.0		

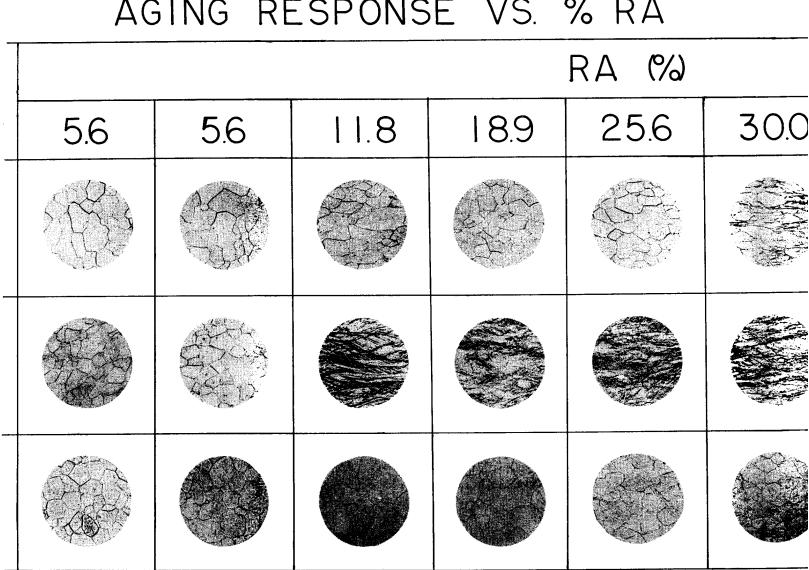


HEAT TREAT RESPONSE OF "I" BEAM WIRE

Figure 38 63

AGING R

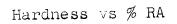
MATERIAL CONDITION	5.6	5.6
AS COLD ROLLED		
⊉ AGED 750°F-20 HRS.		
⊆ AGED 750°F-47 HRS.		



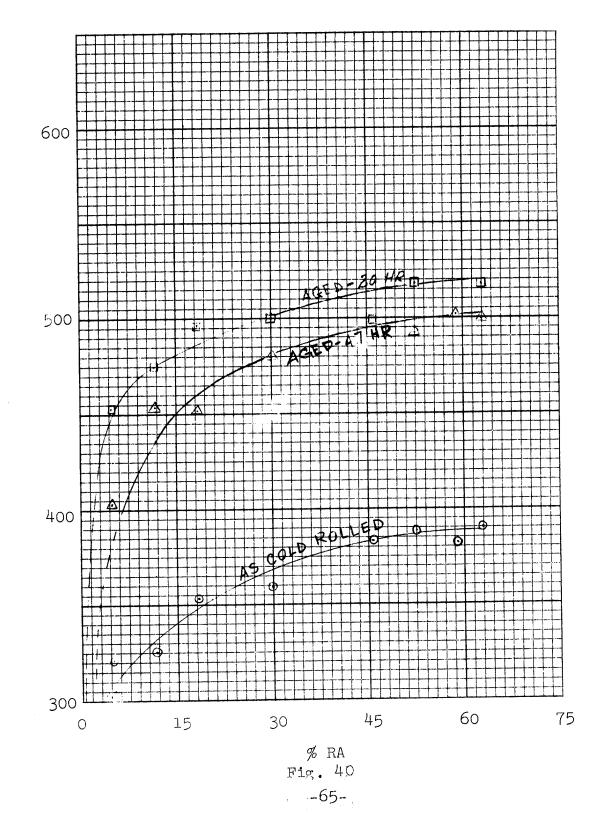
AGING RESPONSE VS. % RA

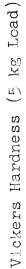
3				
5	30.0	43.3	53.3	62.8
A HARRING N.				
Accession				

r

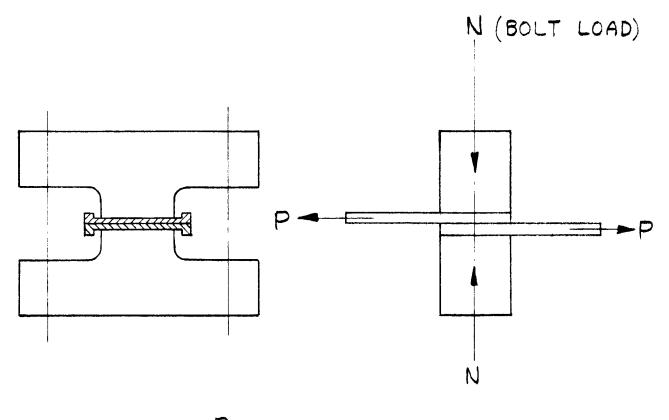


(750°F Isotherm)





FRICTION TEST CLAMP



$$M = \frac{P}{N}$$

Figure 41 66

TABLE III

COEFFICIENT OF FRICTION OF B120VCA TITANIUM WIRE

Torque (#)	Nominal Load N (#)	Tensile Load P (#)	$\begin{array}{l} \text{Coefficient} \\ \text{Coefficient} \\ \text{Coefficient} \\ \text{F} \\ \overline{N} \end{array}$
	Cold Rolled	(Drawn) Wire	
24	1046.9	280	0.267
28	1219.9	360	0.295
34	1480.0	400	0.270
42	1828.2	455	0.249
56	2436.5	660	0.271 0.270 Avg.
	Cold Rolled	, Heat Treated Wi	
24	1046.9	395	0.377
28	1219.9	415	0.340
34	1480.0	510	0.345
42	1828.2	650	0.355
56	2436.5	790	0.324 0.348 Avg.

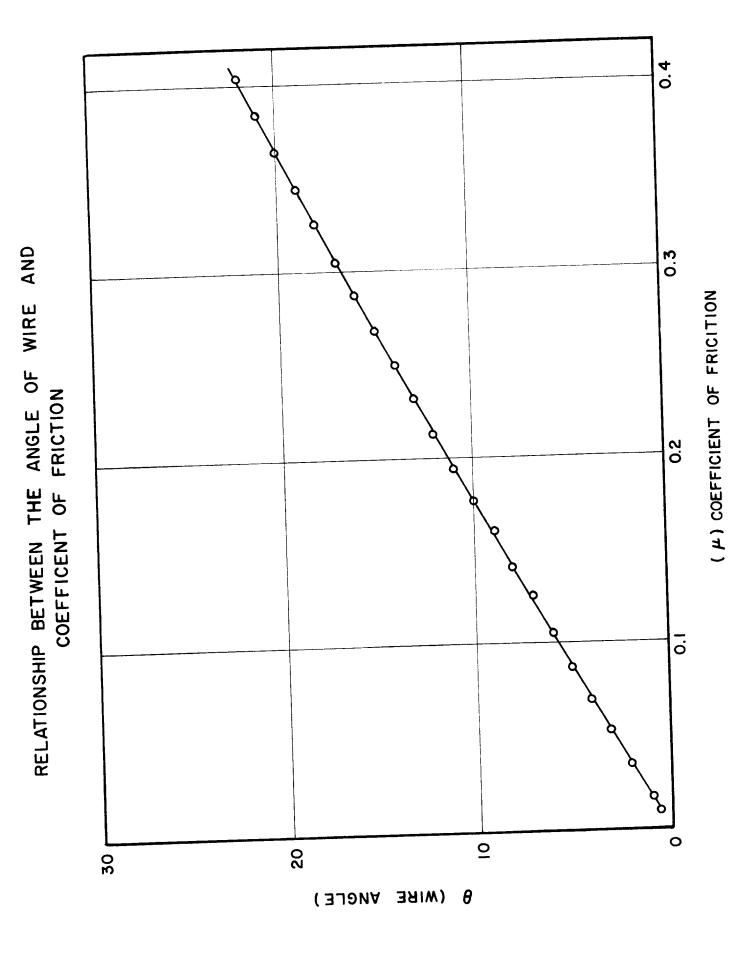
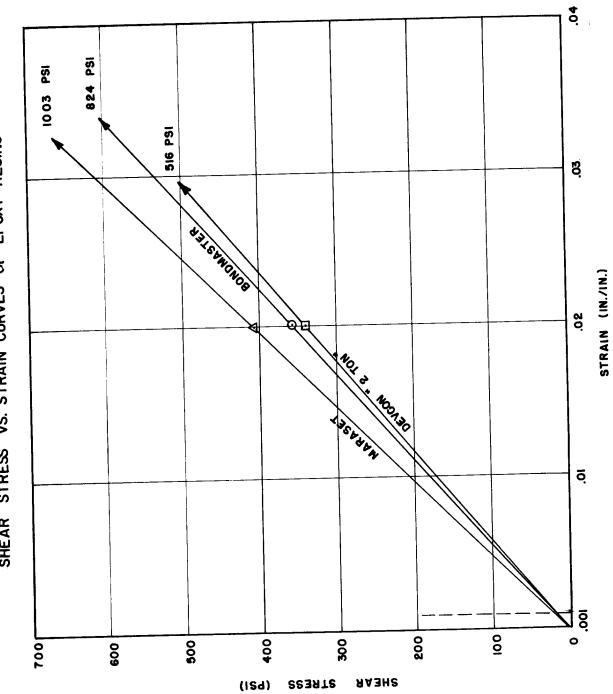


Figure 42 68

TABLE IV

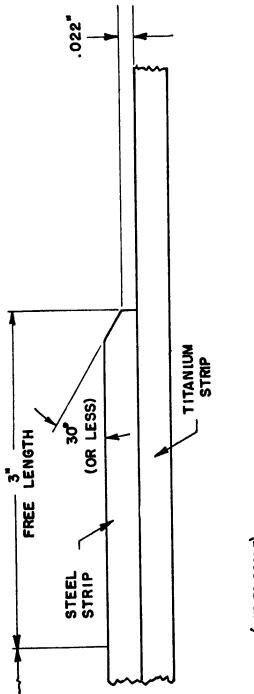
RESIN EVALUATION

Resin	Shearing Stress (psi)	Modulus of Elasticity (XlC ⁴)(psi)
"MARASET"	1003	2.04
(Marbelette Corp.)		
"BOND MASTER"	824	1.78
(Rubber & Asbestos Corp.)		
"DEVCON '2 TON'"	516	1.69
(Devcon Corp.)		



SHEAR STRESS VS. STRAIN CURVES OF EPOXY RESINS

Figure 43 70



(NOT TO SCALE)

Figure 44 71

LOW TEMPERATURE TENSILE PROPERTIES OF Bl20VCA T1 - AGED AT 900°F - 75 HRS. AC (HEAT #F-6236 - GAGE - 0.090")

Test Temperature	Condition	UTS	Elong- ation in l" (%)	RA (%)	RATIO: Notched UTS Smooth UTS
Room	Smooth	214.0	3.4	4.9	0.78
Temperature	Notched	164.1	1.0		
-35°F	Smooth	220.6	1.5	3.1	0.61
	Notched	135.5	•3	0.5	
-65°F	Smooth	227.2	1.2	1.5	0.57
	Notched	129.5	.05	0.1	
-110 ⁰ F	Smooth	235.8	1.0	0.5	0.52
	Notched	121.5	0	0	
-320°F	Smooth	190.0	0	0	0.34
-	Notched	64.0			

FIG. 45

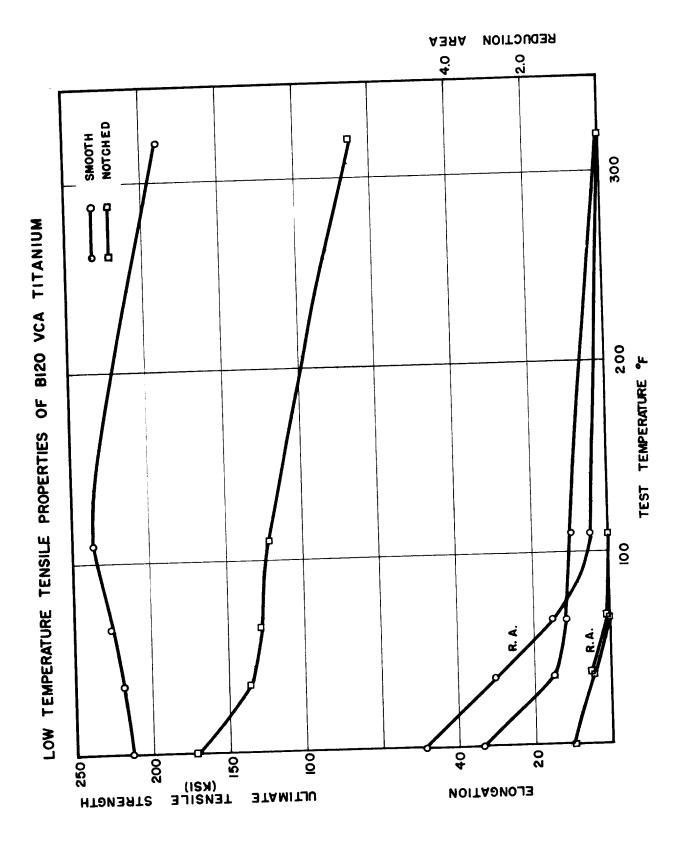


Figure 46 73

6.0 EXPERIMENTAL MANUFACTURING

-

6.0 EXPERIMENTAL MANUFACTURING

The manufacture of two 6.2" I.D. sub-scale vessels, employing the tape configurations illustrated in Figures 3 and 4, was accomplished on a converted lathe shown in Figures 47 and 48. This piece of equipment consists of the following components:

- (a) Wrapping Apparatus (6T-60924)
- (b) End Adapters (LS-25439-7)
- (c) Collapsible Mandrel (6T-60925)
- (d) Reel Equipment (6T-60988)
- (e) Dummy Arbor (DA-32360)

6.1 Wrapping Apparatus

The wrapping apparatus (Figure 49) rolls over the mandrel assembly (described in the following section) on the ways of the lathe. It is initially supported on three legs. The apparatus is fitted with three equally spaced and free rotating rollers. Two of the rollers are mounted on shafts which are clamped to the frame and the third is mounted on a cylinder. This system is capable of applying a rolling radial force of 2500 pounds on the tape. By application of the rolling force, the apparatus lifts from its legs and centers itself on the mandrel. The roller shafts are axially and angularly adjustable by means of gage blocks and sine bar devices mounted at the shaft ends (Figure 49). This provides a means of tilting the rollers to the wrapping helix angle while maintaining their correct axial positions. A spring loaded guide pushes the tape axially at the point of tangency as the tape is fed on the mandrel. Three sets of rollers are required to wrap a vessel. Each set of rollers is formed to suit the particular tape shape. The apparatus is attached to the compound of the lathe carriage through tie rods for driving through the lathe lead screw. This provides axial and square adjustment of the apparatus while it is engaged in the lead screw pitch. By removing the tie rods, the apparatus may free-track to follow the pitch of a tape lay.

Trail wrapping was attempted with spring loaded tie rods pulling the head in the anti-wrapping direction with forces which are great enough to overcome the friction between the tape and the arbor. The tests were unsuccessful since the

6.1 Wrapping Apparatus (Continued)

rollers pulled out of the tape track. The rollers were subsequently reworked to remove the .010" radii at their edges. Another trial run showed them to still roll out of the tape track. It was then concluded that the head must be able to track freely, uninhibited by external forces.

The tie rods were removed and the same tape was wrapped with the head tracking freely. The roller helix angle or tilt was set for .190" pitch or .010" less than the channel width. As the channel winds on the arbor, it is continuously pushed at the shoulder by the difference in pitch, which causes the tape to slip on the arbor until it butts the previous wrap (Figure 50). After butting is achieved, the roller slips on the tape to make up for the pitch difference. This is a continuous and smooth occurrence since the displacements are achieved in the circumferential length of 20 inches in each turn. The first trial of 14 wraps measured .011" more than 14 times the mean width of the channel. A second trial with a more uniform channel was wrapped 17 turns with a measured length of .0005" more than 17 times the mean tape width. This method of wrapping is considered acceptable for the first layer.

Trial wrapping of the second layer was first attempted with an embrittled tape section which failed under load. A second attempt was made using a unheat-treated length which distorted under a load of 1500 pounds and required 500 pounds to bottom on the first layer. The second layer was wrapped successfully with a 1000 pound radial load, but the interference fit was not sufficient for full interlock.

The third layer was similarly wrapped with a 1000 pound radial load. The three layers shown in Figure 51 were wrapped on the dummy arbor demonstrating that the wrapping technique, except for increased interference fit, is feasible.

6.2 End Adapters

300M and SAE 52100 steel end adapters are rough turned, heat treated, and ground all over. All helical surfaces are ground on a thread grinder in the solid stock. The grinding of the inner tape is done after assembly in order to maintain adapter strength during wrapping and mandrel stripping. The technique developed for grinding the helical surfaces utilizes a set of wheel dressing cams which provides a "V" shaped wheel edge with a 24° included angle. The point is dressed down so that

6.2 End Adapters (Continued)

the wheel grinds a groove of .0544"-.0536" width when fed to a sufficient depth. The adapter is clamped on an arbor (Figure 52) which has angular scribe marks to permit rotation and re-indexing of the adapter relative to the wheel and arbor which are constantly engaged in the machine's .200 pitch. In this manner, control of the pitch is maintained while the same wheel is relatively shifted from position to grind the other groove shapes which are off the pitch lines.

A comparator chart of 62-1/2 magnification was used to check the helical surfaces on an optical comparator.

The grinding of the inner taper is done after assembly in order to maintain adapter strength during wrapping and mandrel stripping. A support tube (Figure 53) was designed and fabricated which clamps the adapters of a finished vessel. This tube supports the vessel during grinding of the tapers and also acts as a protective case for the vessel.

6.3 Collapsible Mandrel

The end adapters are assembled and clamped on a mandrel (Figure 54) which holds them in position and provides a core for wrapping. This mandrel is capable of absorbing the wrapping loads and is collapsible and retractable after wrapping. It consists of a solid stepped shaft (Figure 55) onto which a five-segment shell is assembled. The segments were made from two hardened cylinders which were ground on the I.D. to fit the center shaft and on the O.D. at each end to fit the counterbore in the locating rings. The segments are clamped to the shaft by means of the locating rings which are piloted on the The end adapters shaft and are in turn clamped in the assembly. are assembled on the locating rings and held axially between the segment's shoulders and end plates. The adapters are free to rotate for angular positioning by adjustment of the end In disassembly, the end plates are removed and one plates. locating ring removed by pull-out screws. The assembly is located on a sleeve which permits the pressing out of the shaft which in turn pushes out the second locating ring. The pressing load is opposed by the reaction load passing through the sleeve, the end adapter, and the segments. The segments are then free to be pulled to the center and withdrawn. During wrapping, the mandrel assembly is driven on a lathe between the face plate and a live center (Figure 56).

6.3 Collapsible Mandrel (Continued)

The extraction of the mandrel, after wrapping, required approximately a 10,000 pound force. This was resulted in the draging of the tape causing a "saw-tooth" effect. In view of this, a new inner core was designed and constructed for the collapsible mandrel. The new core incorporates a 1/16 inch thick "Cero Alloy" sleeve which will be melted before extraction of the core, and thus reduce the extraction force.

6.4 Reel Equipment

Reel equipment is mounted on the lathe head and locates the tape reels in the axial location of the mandrel. Each reel (Figure 56) holds enough tape for one layer and spaces it to the wrapping pitch. The reel is mounted on a shaft shich is supported between bearings (Figure 57). A drag brake is mounted at one end of the shaft and is controlled by a potentiometer which can vary the tape tension in a range of 0-400 pounds.

6.5 Dummy Arbor

A dummy arbor (Figure 58) which simulates a mandrel assembly with end adapters has been designed and fabricated. This is a hardened, solid steel arbor which is used in the development of wrapping procedures. Variables due to tape tolerances and assembly of parts are minimized so that the adapters and mandrel are not jeopardized during development.

6.6 Staking

This method of joining the tapes to the adapters includes drilling for pins in the hardened tape and adapter material on a sensitive drill. The drilling must be done at the wrapping machine with a hand drill which presents risk of drill breakage. The drilling of the end adapters requires solid carbide drills which are extremely brittle. The staking pin size has been increased to 1/16" to reduce drill breakage.

6.7 Wrapping Development

Trial wrappings of the first layer were made with the roller helix angles set for .200" pitch and the wrapping head driven by the lathe lead screw. The resulting spacing was erratic. The first layer must be wrapped with channels butting tightly to permit fitting of the second layer interlock. Several modifications were made to the wrapping apparatus primarily for this

6.7 Wrapping Development (Continued)

purpose. The probability of tape width, the head tracking rate, and the lathe lead being exactly the same is remote. Therefore, axial slippage is expected and should be used to advantage. Fixing of the head to the lathe lead screw, as originally contemplated, is not considered practical.

Experiments were then run with the wrapping apparatus on the bare dummy arbor using various roller helix angles and radial loads. An inconsistency in the tracking rate was detected. Eccentricities in the roller shaft assemblies and deflections in the apparatus due to machining tolerances and roller loads were not ed. Corrected base line settings on the shaft assemblies were established to minimize the effect of these deviations.

Experiments were also carried out to determine the axial drag force required to overcome the clamping load of the rollers on the bare arbor. The apparatus was set to track the arbor by means of roller tilt and clamping load. Cables, fitted with a spring balance, were attached to the frame and fixed at opposite ends. The apparatus tracked the mandrel until the restraining force of the cables caused slippage between the rollers and the arbor. Coefficients of friction between .120-.126 were realized. A similar test was run with short pieces of channel tape located between the rollers and the arbor, but without rotation of the arbor. The drag force indicated a coefficient of friction of.5, approximately.

A modification was made on the wrapping apparatus which incorporated a third tie rod between the wrapping head and the lathe compound (Figure 59). The three equally spaced rods were fitted with springs and preloaded to pull the head back from the wrapping direction, thereby stacking the first channel tightly with a predetermined load.

In previous trial wraps, the radial forces used were 500, 1000, and 1000 pounds for the first, second, and third layers, respectively. The tape tension remained at 200 pounds.

No problems were encountered during the dummy arbor wrapping of the first layer. The second layer ("I" beam), however, fractured under the 2500 pound load on the first few laps over that portion of the cylinder equivalent to the adapter piece. The load was reduced to 1000 pounds over the adapter portion and then increased to 2500 pounds over the titanium-to-titanium interlocking sections without further cracking. The third layer was wrapped using a 500 pound load on the steel and 2500 pounds on the titanium without difficulties.

6.8 Wrapping Vessel No. 1

Vessel No. 1 (Figures 60 and 61) was wrapped, staked, and the mandrel successfully withdrawn. The force necessary to withdraw this mandrel was 10,000 pounds. This vessel appeared to be rigid and able to withstand handling despite the following condition:

- (a) A variation in outside diameters between the end adapters and the mandrel resulting in an adapter to mandrel step. Wrapping difficulties occurred in these zones on all three layers. It is felt that this situation caused a "saw-tooth" effect on the inside of the vessel when the mandrel was extracted.
- (b) The tape used (both "I" beam and channel) was slightly out of tolerance.
- (c) An incorrect "as-received" helix on the third layer increased the tendency of this tape to eject the staking pins. This incorrect helix also caused the tape to form an "S" shaped curve coming off the wrapping reel. This condition produces difficulty in attaining a tight loop-to-loop (side face) contact. It was learned from these problems that the third layer (channel) must be wrapped during the tape manufacture process onto the drum with the legs facing inward.

Wrapping of the first layer employed the proper shaped rollers loaded to 500 pounds radially with a tensile force on the tape of 200 pounds. These rollers were free-tracking and were set at a retarding pitch of 0.190 inch; the wrapping pitch being 0.200 inch. The proper angular alignment (about its axis) of the terminal end-adapter was accomplished using a "Jo" block of a thickness equivalent to a multiple of the actual channel tape width. A gain of .001 inch in width for each turn due to the compressive deformation of the tape was measured resulting in a cumulative total terminal loss of .043 inch for the complete first layer. No measurable space between turns was observed. An "Indiac" concentricity measuring device showed maximum runout of 0.002 inch except in the adapter-to-mandrel transition areas where the step caused the instrument to run off scale.

The second layer, rolled with wide, plain rollers, cracked under the imposition of the high (2500 pounds) radial force.

6.8 Wrapping Vessel No. 1 (Continued)

A check of the end adapters revealed that the adapter section which fits into the groove of the "I" beam was wider than the tape groove and that sharp edges existed. By breaking these edges, the interference fit was reduced and cracking eliminated. This second layer was removed and, using new tape (having the same cross-section), rewound under a radial force of 1350 pounds.

The third layer (channel) also was confronted with the "step" problem. In addition, the application of the high radial rolling force (2500 pounds) rlastically deformed the tape thus increasing the basic width of the channel by .0014 inch. The first few loops were unwound and the tape width reduced to 0.200 inch by hand filing. Pressure tests on subsequent wraps indicated that a gage setting of 45 psi (1300 pounds approximately), applied radially, was the optimum non-deforming force permissible. This setting was used to complete the wrapping of the third layer.

6.9 Wrapping Vessel No. 2

The first layer was successfully wrapped with a radial load of 570 pounds and tensile load of approximately80 pounds.

The second layer bottomed and locked with a radial load of 870 pounds and a tensile load of 80 pounds. A radial load of 1000 pounds caused distortion. Towards the end of the second layer at the terminal point of the first layer, a space developed between the first layer and the end-adapter shoulder. The staking pin for the first layer was removed, the adapter was rotated to close the space and wrapping of the second layer was completed. The space could be caused by a .0002 compression of the channel tape in the interference fit. The tape used in this vessel was not heat treated.

The third layer required a 1200 pound radial load and a 180 pound tensile load. No difficulties were encountered until the channel reached the first groove on the end adapter, at which point it was displaced approximately .005 forward. The last wrap had to be filed to fit.

After completion of wrapping and staking, the collapsible arbor was removed on an arbor press with no difficulty. The arbor extraction force was estimated at 5 tons. The inner tapers on the end adapters were machined to finish the vessel.

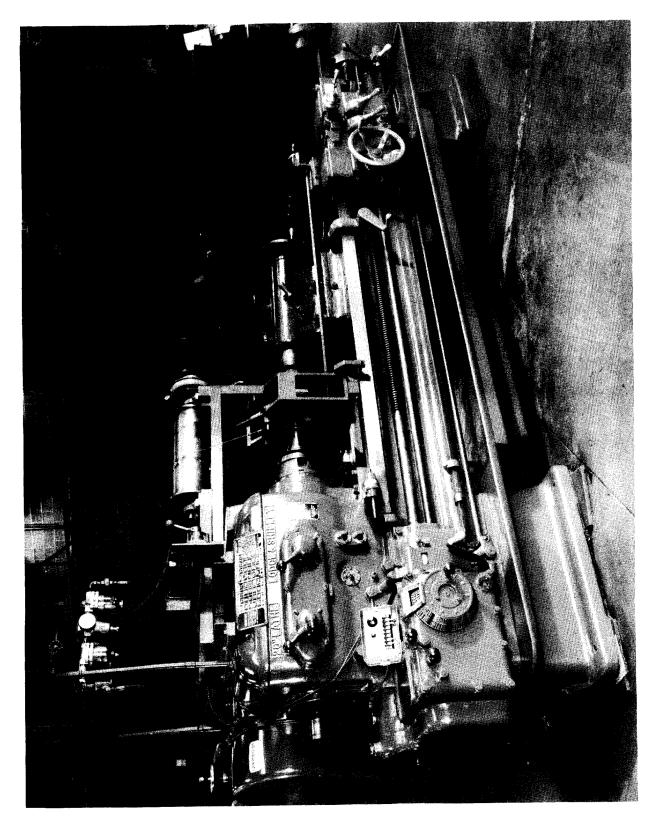
6.9 Wrapping Vessel No. 2 (Continued)

The finished vessel was approximately .020" smaller in diameter at the center than at the ends with .004" total runout of the end faces. The outer diameter remained smooth but the inner bore was slightly stepped in a manner resembling rifling. This indicates that the interlock between the 1st and 2nd layer is incomplete.

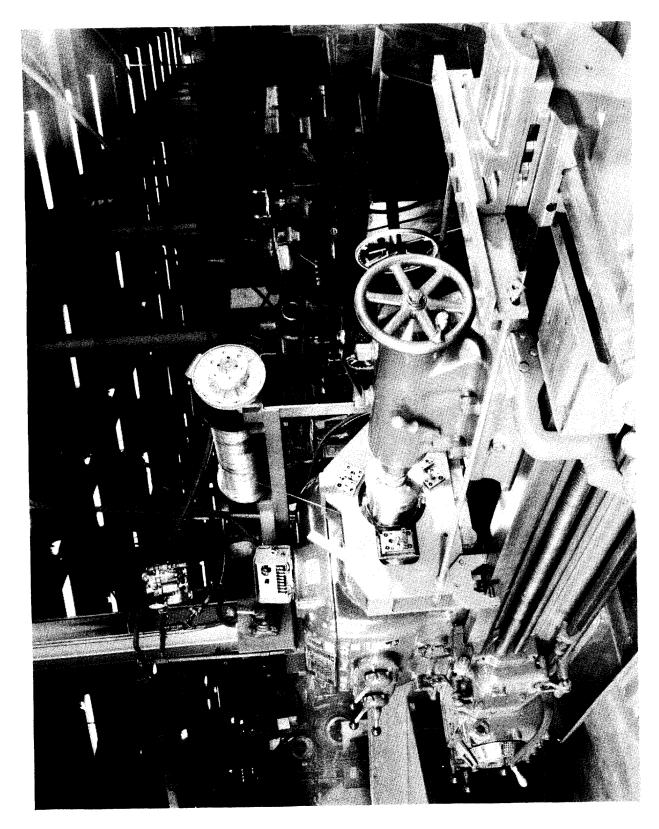
Generally, the wrapping was indicative of the feasibility of the technique. Better results are expected with more accurately sized tape with the required strength and ductility.

This vessel pressurized and leaked at 30 psig. The leak was caused by a separation of the tapes at one end of the vessel. Since the separation occurred near the edge of the end adapter, it was surmised that the flaw was caused by a compression of the end adapter as the mandrel parts were being withdrawn. The tensile force on the tape during wrapping imposes a hoop stress which is transmitted to the end adapters and the mandrel as a radial compressive force. As each portion of the mandrel is removed, the vessel contracts in that area. The first portion removed is located under the adapter near the point of failure. However, a good interlock between the tape layers should hold the vessel intact until the remainder of the mandrel is withdrawn. A modification on the mandrel could be made to permit a collapse prior to withdrawal.

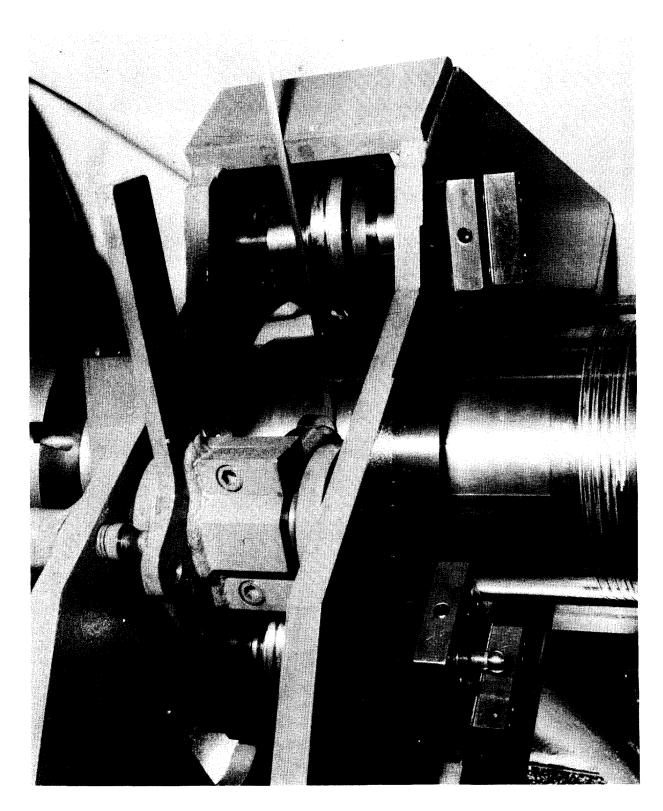
This separation was plugged by casting an inner and outer shell of a low melting alloy. A second test was conducted which resulted in failure at 50 psig. The vessel separated in the center section far from the end adapters. The tape layers unwound easily indicating a lack of interlock. These sectional radii and the locking angles were enlarged and the 'I" beam was found to be twisted. It appears that after wrapping when the mandrel was withdrawn, the wrapping stresses were relieved by contraction of the vessel. The "I" beam twisted toward its free position (Figure 62) and a stagger "tooth effect" developed on both the 0.D. and the I.D. of the vessel. It is suspected that the tape layers were not bottomed and the interlock was insufficient to prevent twisting.



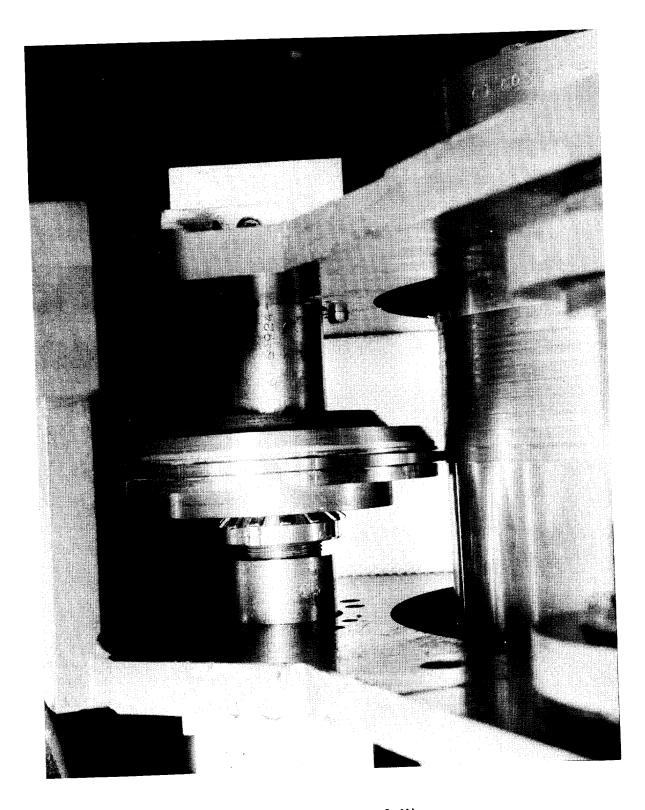
Tape Wrap Machine



Wrapping Apparatus Close-Up



Wrapping Apparatus

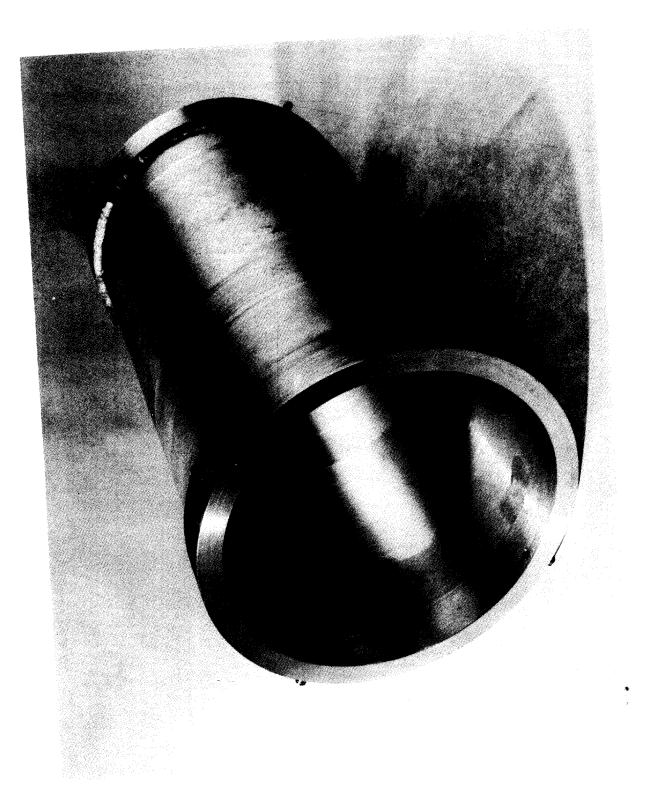


Close Up of Roller on Channel Wire

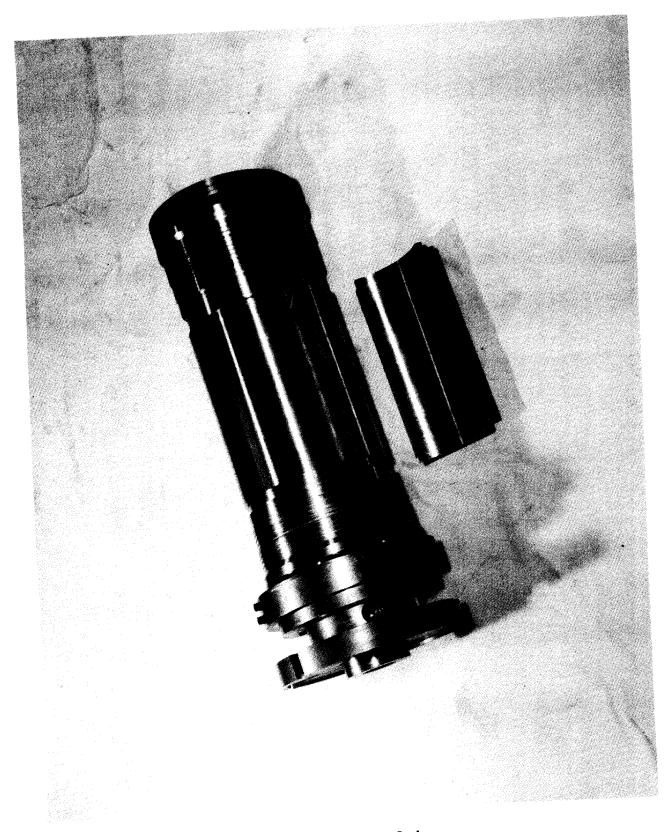




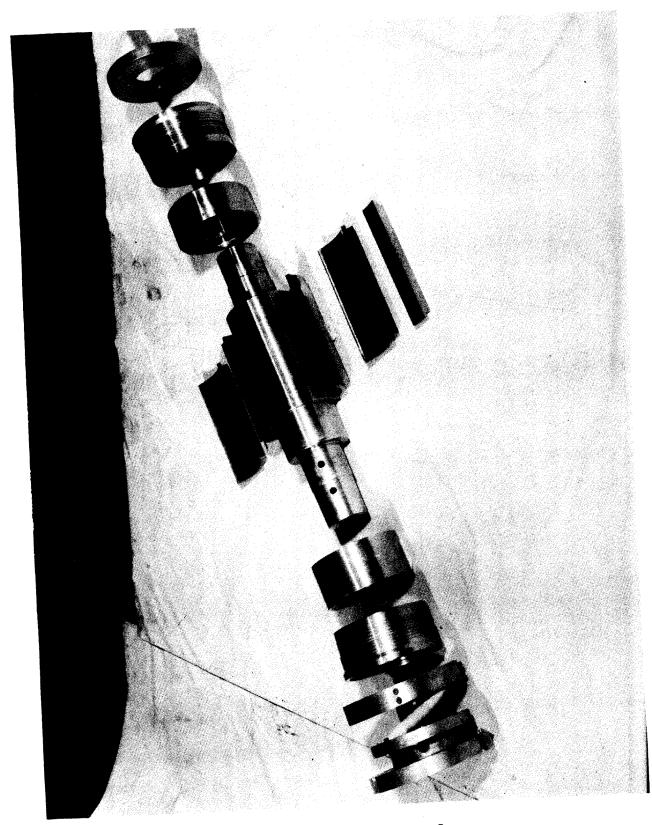
Adapter Clamped to Arbor



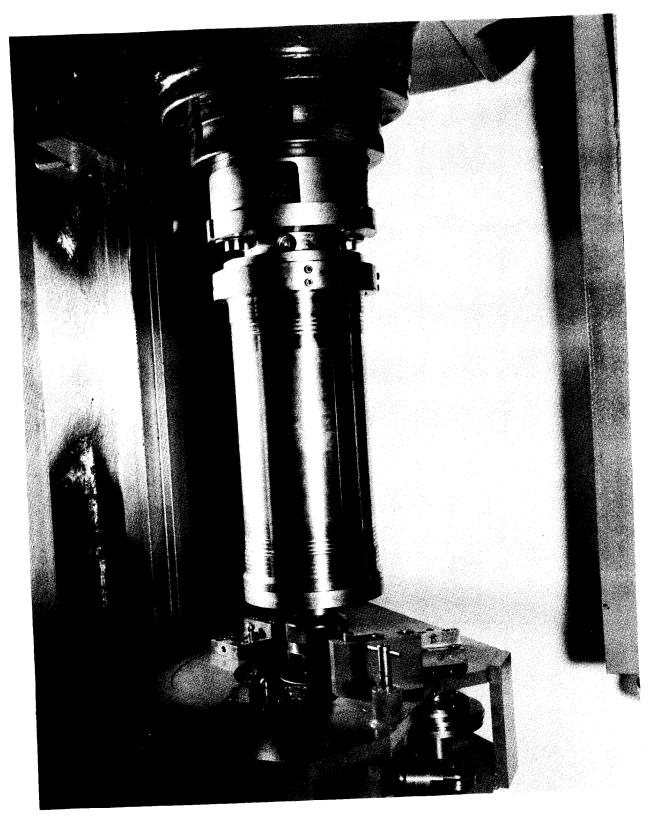
Support Tube



Mandrel Assembled



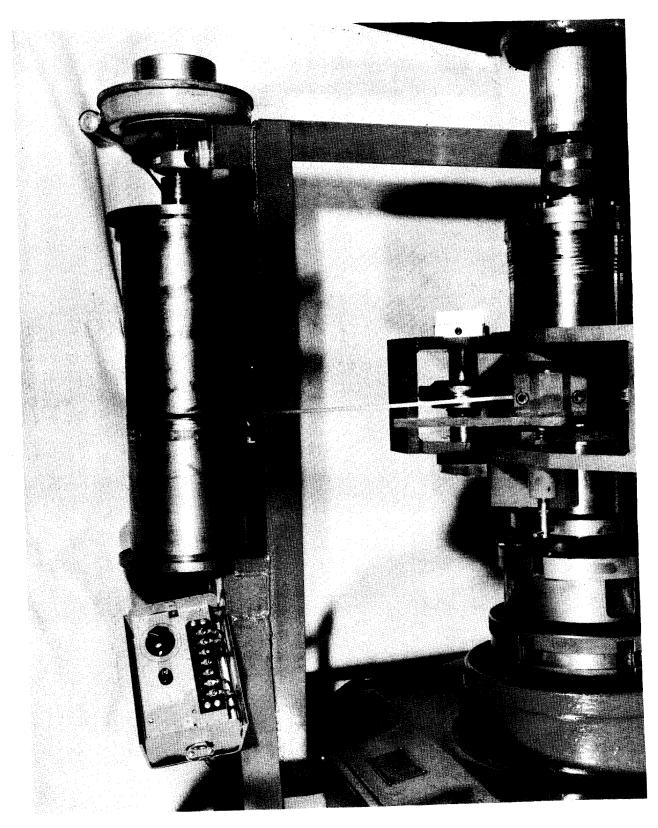
Exploded View of Mandrel



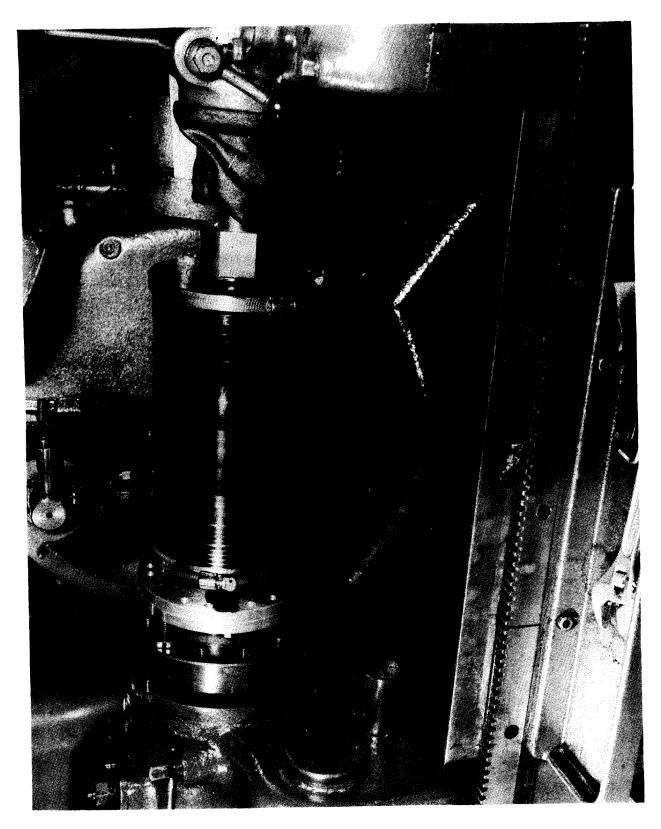
Mandrel Set on Lathe



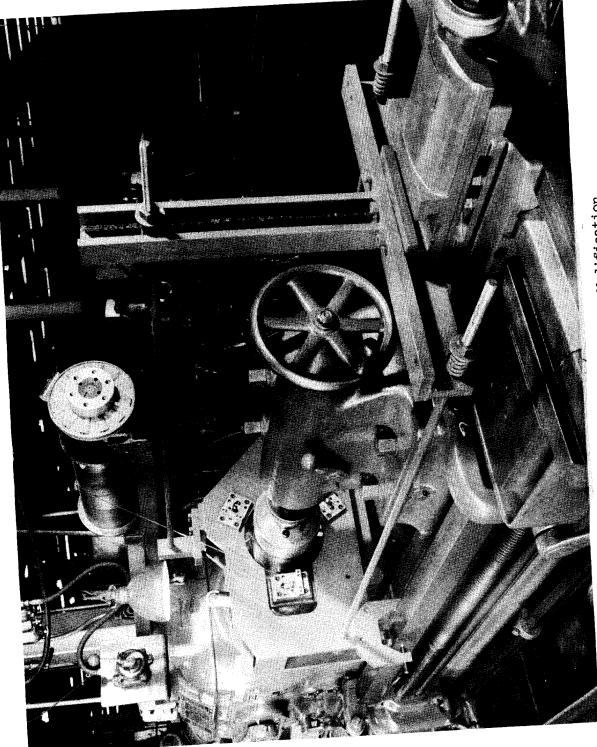
Reels



Drag Brake

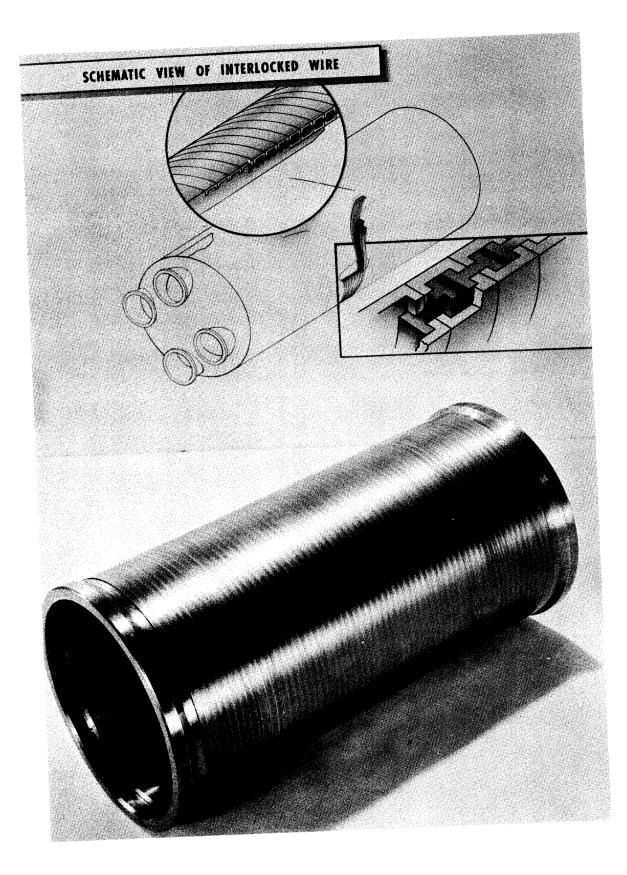


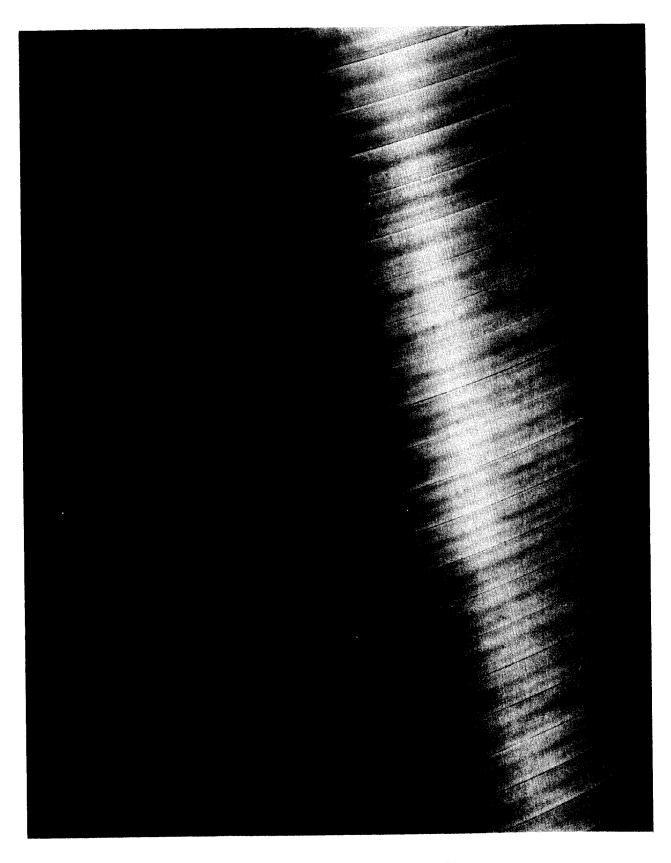
Dummy Arbor



÷

Wrapping Apparatus Modification





Wrap Vessel Specimen Close-up

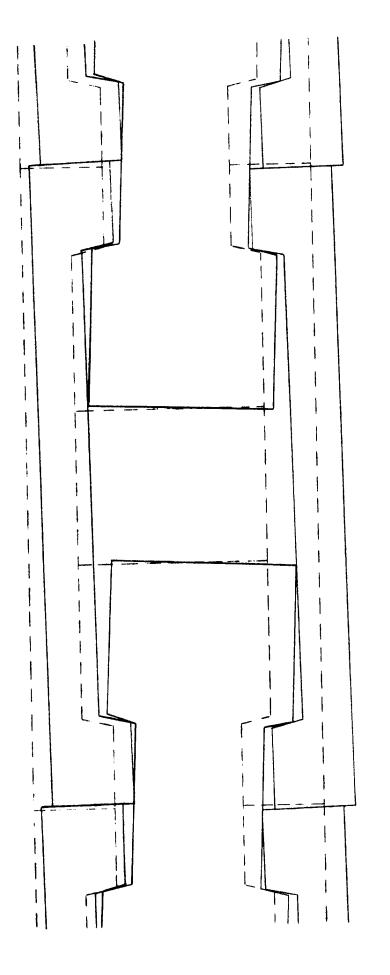








Figure 63 98

APPENDIX I

STRESS ANALYSIS

.

RECORD OF ANALYSIS

SHEET____OF SHEETS_____

WRITTEN BY	L.SEELEN
APPROVED B	Y
DATE 7	-18-60

ENGINE NO.

JOB NO. 51792

SUBJECT:

INTERIOCKING WIRE WRAP VESSEL

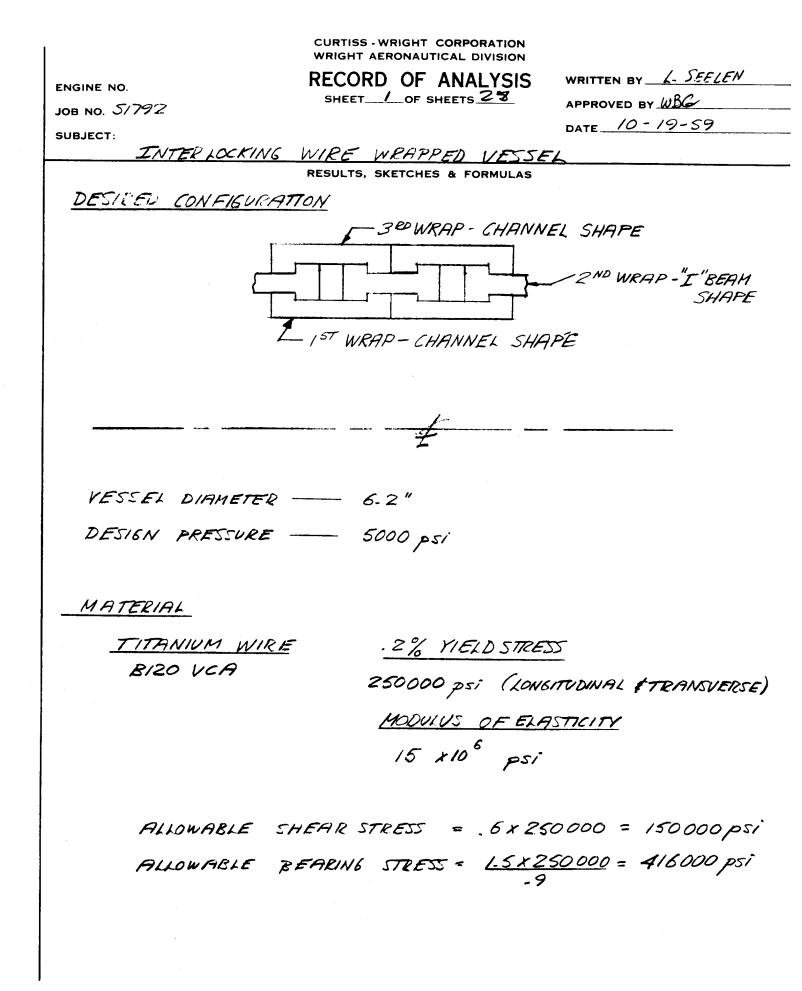
RESULTS, SKETCHES & FORMULAS

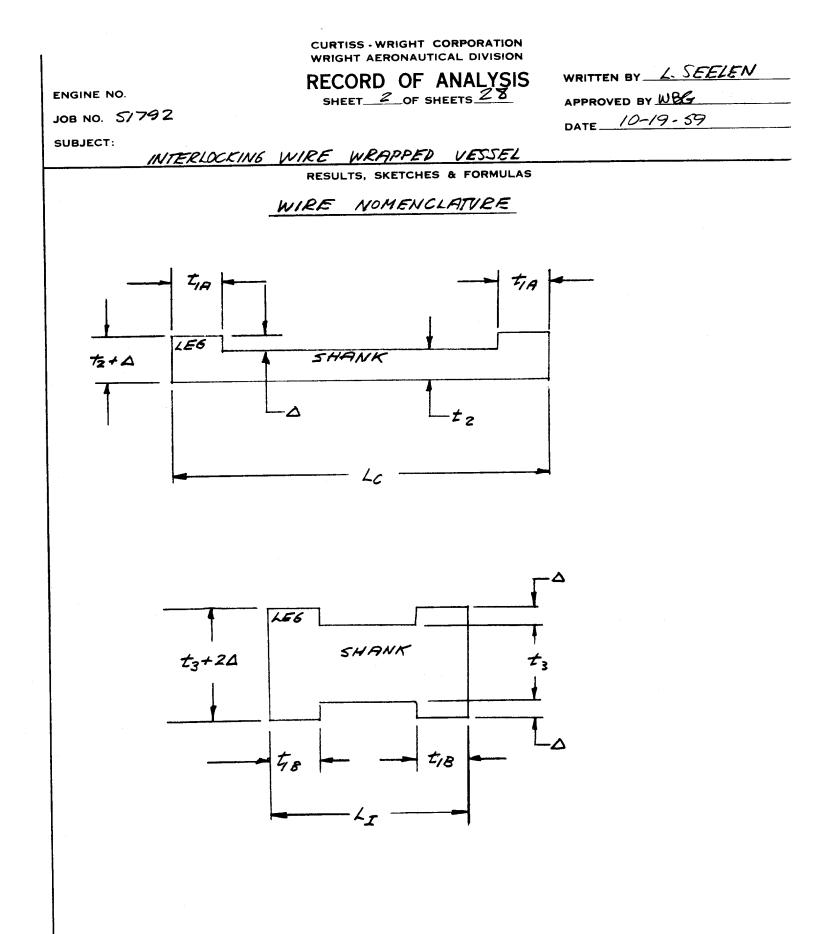
FIPPENDIX FI

STRESS ANALYSIS - CALCULATIONS

INTERLOCKING WIRE WRAP VESSEL

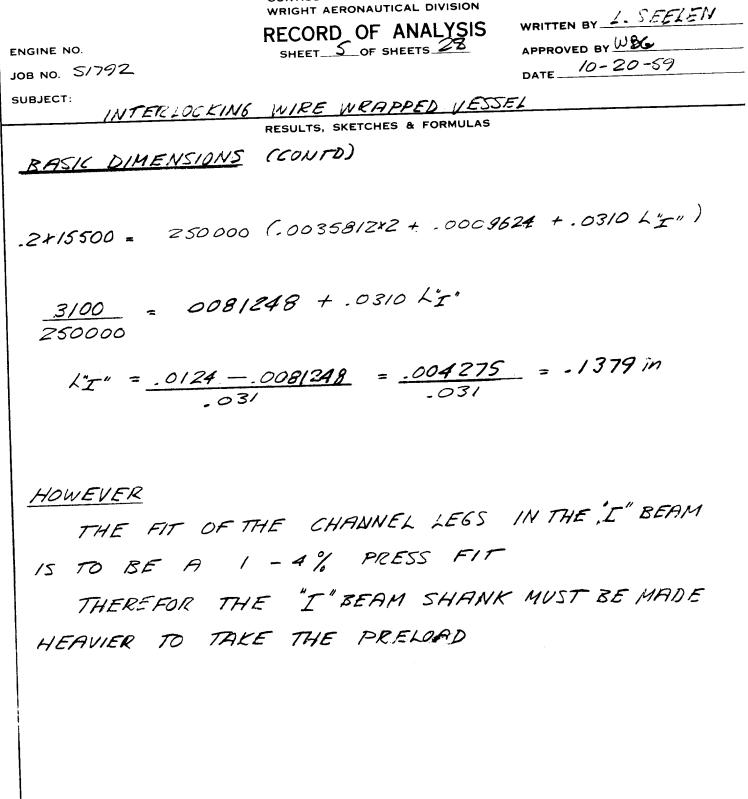
CURTISS - WRIGHT CORPORATION WRIGHT AERONAUTICAL DIVISION RECORD OF ANALYSIS SHEET_2 OF SHEETS_28 SUBJECT: INTERFOCKING WIRE WRAPPED VESSEL RESULTS, SKETCHES & FORMULAS	WRITTEN BY <u>L.S.EEL.EN</u> APPROVED BY <u>W BC</u> DATE <u>3-10-60</u>
THBLE OF CONTENTS	
SUBJECT	PAGE
CONFIGURATION AND WIRE PROPERTIES	1
WIRE NOMENCLATURE	2
LOADS	3
DETERMINATION OF BASIC DIMENSIONS	3,4,5
PRELOAD DUE TO INTERFERENCE FIT	6,7
SUMMARY OF DIMENSIONS	3
BENDING OF IST CHANNEL WRAP UNDER PRESS	IRE
STATEMENT OF PROBLEM - METHOD OF	SOLUTION 9,10
CASE 10	11 - 14
CASE 16	15
CASE Za \$26	16
CASE 3	17
LASE ZO,26- GRAPH	18
ADAPTOR PIECE	
DETERMINATION OF DIMENSIONS	19-21
WIRE	
STRESSES WHEN ON SPOOL	27
FORCES REQUIRED FOR ASSEMBLY	23-26
END TAPER OF ADAPTOR PIECE	.27,28





I	CURTISS WRIGHT CORPORATION WRIGHT AERONAUTICAL DIVISION	
	RECORD OF ANALYSIS	WRITTEN BY L. SEELEN
ENGINE NO.	SHEET 3 OF SHEETS 28	APPROVED BY WBG
JOB NO. 51792		DATE 10-20-59
SUBJECT: INTERLOCKING	WRE WRAPPED VESSEL	
	RESULTS, SKETCHES & FORMULAS	
LOADING		
p = 5000 psi 4	D=6.2"	
CIECUMFERENTTAL		
= 5000 // in ³	x 3.1/n = 15500	#/în
AXIAL LOAD		
= 5000 #/in 2	$n^2 \times 3.1$ in = 7750	#/in
BASIC DIMENSIONS	- BASED ON AXIAL	LOADS
CHANNEL SHAF	DUI	HRELL SHAPE
$2t_2 = \frac{7750}{25000}$	$\frac{1}{2}$	$= zt_z$
tz= .0155	fin t ₃	= .031 în
2 tin = 7750 150000	t_{IB}	= tin
tiA = .025	83 tib	= _ 02583
$2\Delta = \frac{7750}{416000}$ $\Delta = .009315$.009315

CURTISS - WRIGHT CORPORATION WRIGHT AERONAUTICAL DIVISION WRITTEN BY L. SEELEN RECORD OF ANALYSIS SHEET 4 OF SHEETS 28 APPROVED BY WBG ENGINE NO. DATE 10-20-59 JOB NO. 5/792 SUBJECT: INTERLOCKING WIRE WRAPPED VESSEL RESULTS, SKETCHES & FORMULAS BASIC DIMENSIONS (CONFD) - BASED ON CIRCUMFERENTIAL LOADS THE AREA OF ONE PITCH MUST CARRY THE LOAD / PITCH Ap = 2 ACHANNEL + A't" PITCH LENGTH = LC = 2 tin A + tz Lc AREA CHANNEL = 2x.02583x.009315 + .0155 Lc = .0004812 + .0155 Lc FIREAT SHAPE = 4 tis A + t3 KI. =.0009624 + .031 L'I' SETTING LC = . 200 in Ac = .0004812 + .0031 = .0035812



CURTISS - WRIGHT CORPORATION WRIGHT AERONAUTICAL DIVISION WRITTEN BY L-SEELEN RECORD OF ANALYSIS APPROVED BY WBG SHEET 6 OF SHEETS 28 ENGINE NO. DATE 10-20-59 JOB NO. 51792 SUBJECT: INTERLOCKING WIRE WRAPPED VESSEL RESULTS, SKETCHES & FORMULAS INCREASE to .040 1- WRAPPING "I" BEAM LAYER ON I ST CHANNEL LAYER TOTAL DEFORMATION = 8% COMPRESSION OF CHANNEL LEGS = -040 *8% = 5.46 % ELONGATION OF "I" BEAM SHANK - - 0186 28% = 2.54 % 2- WRAPPING 2" CHANNEL LAYER ON "I" BEAM LAYER SINCE THE "I"BEAM SHANK HAS ELONGATED 2.54% THE TOTAL DEFORMATION DURING THIS WRAP = 5.46% FURTHER ELONGATON OF I BEAM SHANK $= \frac{.0186}{.040+.0186} \times 5.46\% = 1.633\%$

RECORD OF ANALYSIS

SHEET 7 OF SHEETS 28

ENGINE NO.

JOB NO. 51792

WRITTEN BY <u>L-SEELEN</u> APPROVED BY <u>WBG</u> DATE <u>10-21-59</u>

SUBJECT: INTERIOCKING WIRE WRAPPED VESSEL RESULTS. SKETCHES & FORMULAS

TOTAL ELONGATION OF "I" BEAM SHANK = (2.54 + 1.633)% = 4:173%

THIS IS WITHIN THE ALLOWABLE VALUE, AND ENSURES AGAINST ANY LOSS OF PRELOAD DUE TO PRESSURIZATION SINCE THE PRESSURE LOAD NEVER EXCEEDS THE PREIOAD, THE CHANNEL LEGS REMAIN BUTTED, AND NEITHER THE CHANNEL LEGS NOR THE "I" BEAM LEGS ARE SUBJECT TO BENDING STRESSES.

RE-SIZE "I" BEAM

FILL DIMENSIONS EXCEPT LE REMAIN

 $L_{I} = -\frac{031}{.040} \times .1379 = .1069 \text{ in}$

RECORD OF ANALYSIS

WRITTEN BY L. SEELEN APPROVED BY WEG DATE 10-21-59

ENGINE NO.

JOB NO. 51792

SUBJECT:

INTERLOCKING WIRE WRAPPED VESSEL

RESULTS, SKETCHES & FORMULAS

FINAL SIZE CHANNEL $t_z = .0155$

t1A=.026

5 = .0093

Lc = .200

T BEAM $t_3 = -040$

tis = .026 * A = .0093 LE = . 1069

* SEE PPIO \$ 15, CASE IB, FOR SUBGESTED INCREASE TO . 040 in.

CURTISS - WRIGHT CORPORATION WRIGHT AERONAUTICAL DIVISION WRITTEN BY <u>L-SEELEN</u> RECORD OF ANALYSIS APPROVED BY WBG SHEET 9 OF SHEETS 28 ENGINE NO. DATE 10-21-59 JOB NO. 5/792 SUBJECT: INTEKLOCKING WIRE WRAPPED VESSEL RESULTS, SKETCHES & FORMULAS IF THE "I" BEAM SHAPE DOES NOT BOTTOM ON CHANNEL WRAP

THE SPAN IS . 1472 IN. THE DEFLECTION OF THE CHANNEL -025 IN FROM THE END $\frac{5000 \times .025^2 (.1472 - .025)^2}{24 \times .05 \times .0155^3} \times 12 = .000417 \text{ IN}.$

=

IF THE "I BEAM LEG HEIGHTS FRE MIN AND THE CHANNEL LEG HEIGHTS ARE MAX THE CLEARANCE IS .0004 IN.

DEFORMATION DUE TO THE PRESS FIT CRUSES THE CLEFTRANCE TO APPROACH ZERO, AND THE ANALYSIS ASSUMING THE DISTRACE BETWEEN "I" BEAMS AS THE CHANNEL SPAN IS ESSENTIALLY CORRECT

A MORE ACCURATE METHOD ASSUMES A FIXED BEAM WITH THE . 1472 SPAN LENGTH SIMPLY SUPPORTED .025" FROM EITHER END.

	CURTISS WRIGHT CORPORATION WRIGHT AERONAUTICAL DIVISION	
	RECORD OF ANALYSIS	WRITTEN BY L. SEELEN
ENGINE NO.	SHEET 10 OF SHEETS 28	APPROVED BY
JOB NO. 51792		DATE 10-21-59
SUBJECT: INTERLOCKING W	IRE WRAP VESSEL	
	RESULTS, SKETCHES & FORMULAS	
ASSUMED CONFIGURATION		
CASE IA	FIXED ENDED - SIMPLY	SUPPORTED AT
ſ.Z	"BEAM ENDS	
	025 - 0944	
CASE 1 B - S	AME AS IA EXCEPT	.025 = .040
CASE 2A, 2B	FIXED ENDED AT	"I " BEAMENDS
	.0344	

CURTISS - WRIGHT CORPORATION WRIGHT AERONAUTICAL DIVISION WRITTEN BY L. SEELEN RECORD OF ANALYSIS APPROVED BY SHEET 11 OF SHEETS 28 ENGINE NO. DATE 10-22-59 JOB NO. 51792 SUBJECT: INTERLOCKING WIRE WRAPPED VESSEL RESULTS, SKETCHES & FORMULAS BENDING OF I ST CHANNEL WRAP UNDER PRESSURE - CASE 10 LA 4 .025 .0972 .025 Kz Vi. THEEE MOMENT METHOD SPAN 0-1 $\bigcirc M_{0}h_{0} + 2M_{1}(L_{0}+h_{1}) + M_{2}L_{1} + \frac{6A_{0}\bar{a}_{0}}{L_{1}} + \frac{6A_{1}\bar{b}_{1}}{L_{1}} = 0$ SPAN 1-2 @ M14 + 2 M2(4+L2) + M3L2 + <u>6 A1ā1</u> + <u>6 A2</u>52 =0 SP/710 2-3 3 M2L2 + 2M3(12+L3) + M4L3 + 6Azāz + 6A363 =0 SYAN 3.4 $M_{3}L_{3} + 2M_{4}(L_{3}+L_{4}) + M_{5}L_{4} + \frac{6A_{3}\bar{a}_{3}}{L_{-}} + \frac{6A_{4}\bar{b}_{4}}{L_{-}} = 0$ IN APPLYING THESE EQUATION ALL TERMS REFERRING TO THE IMIZGINARY SPANS ARE NEWECTED. SINGER - STRENGTH OF MATERIALS

	WRIGHT AERONAUTICAL DIVISION	I SEEVEN
	RECORD OF ANALYSIS	WRITTEN BY <u>LSEFLEN</u>
ENGINE NO.	SHEET 2 OF SHEETS 28	APPROVED BY WBG
JOB NO. 51792		DATE 10-22-59
SUBJECT:	CKING WIRE WRAPPED VESSEL	
	PESULTS. SKETCHES & FORMOLAS	
	5000 <u>x.0</u> 25 ³ = 01954 4	
	$5000 \times .025^3 = .01954$	
-	$5000 \times .0972^3 = 1.1479$	
$6 \frac{A_z \bar{a}_z}{L_2} =$	$\frac{5000 \times .0972^3}{4} = 1.1479$	
6A363 = 23	$5000 \times .025^3 = .01954$	
6 <u>A3</u> ā3 = 43	$5000 \pm .025^3 = .01954$	

RECORD OF ANALYSIS

WRITTEN BY L. SEELEN	
APPROVED BY WAG	
DATE 10-22-59	
DATE	

ENGINE NO.

(n)

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2

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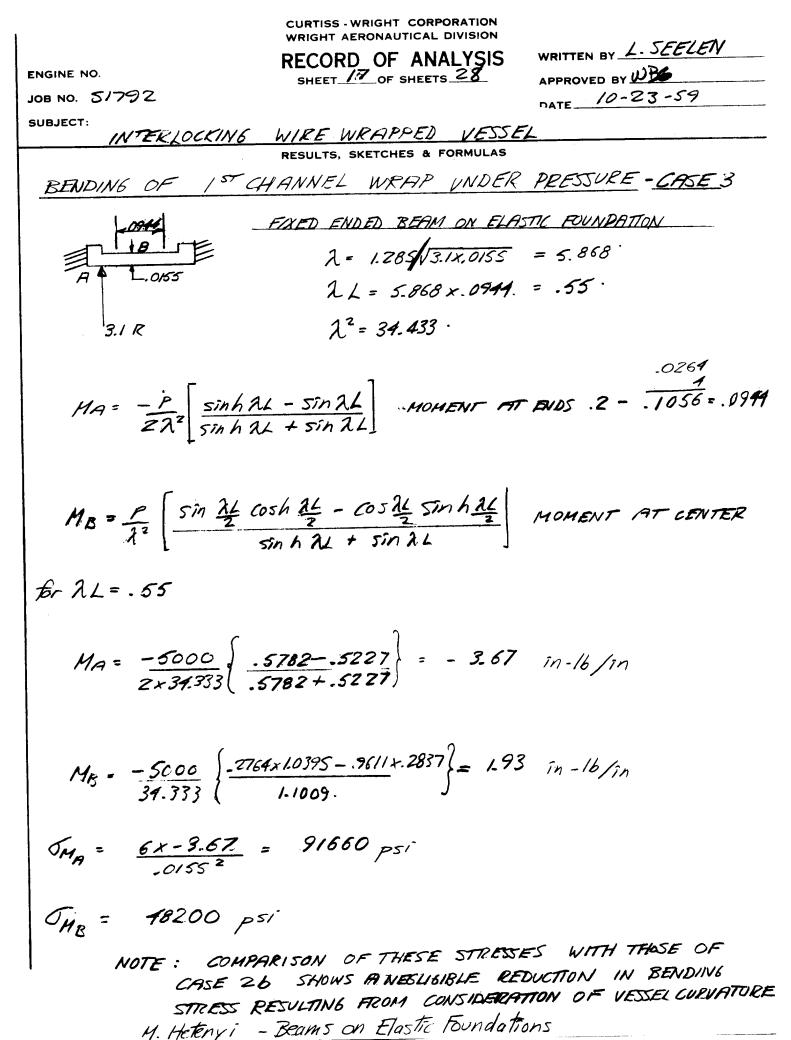
JOB NO. 51792

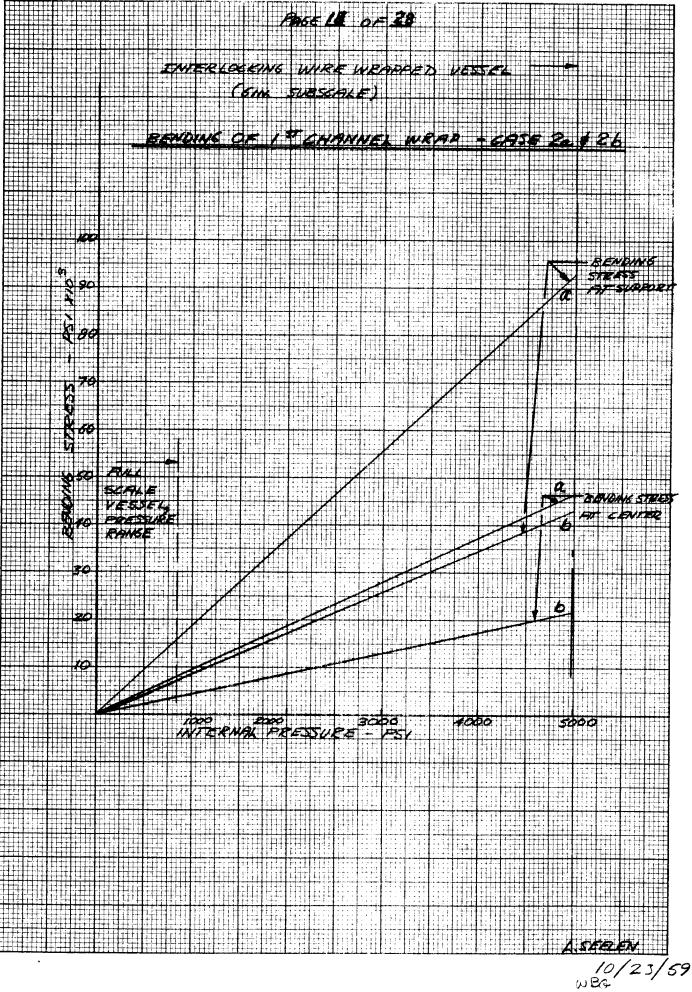
////~	R <u>JOCKINI6 WI</u>	RESULTS, SKETCH	1ES & FURMULA	NS (/ .	K
	M,	Mz	M3	M4	K
	.050	-025			01954
025 = .5	.025	- 2444	-0972		-1.16744
5+0	-025	0125			+.00977
3+3	0	.2319	.0972		-1.15767
		.0972	-2224	-025	-1.16744
		-	-	-	-
(5) # 0 <u>977</u>	a 142	.0972	.2444	.025	- 1.16744
-4192 × 3		-0972	0407	-	+ .48530
() KÊ		0	.2037	.025	68214
			.025	.050	01954
~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~			.025	.050	01954
10 HD			_	_	
	/377		-025	-050	01954
13×10 .025 =.			025	00344	+.09382
-137723			0	No. of Concession, name of	.07428

	CURTISS - WRIGHT CORPORATION WRIGHT AERONAUTICAL DIVISION	
	RECORD, OF ANALYSIS	WRITTEN BY <u>L. SEELEN</u>
ENGINE NO.	SHEET CF SHEETS 28	APPROVED BY WEG
JOB NO. 51792		DATE 10-22-59
SUBJECT:	ISE I BOARD UESEL	
INTERIOCEING	RESULTS, SKETCHES & FORMULAS	
Mg=.07428/.	04656 =+1.5954	
$M_3 =68214$	<u>025×1.59</u> 54 = -3. .2037	5446
$M_2 = -1.15767$	+.0972(3.5146) = -3.5 .2319	064
M, =01954	<u>+ .025 (3.5064)</u> = + 1 .050	3624
	TOUR MO AND 4	$I_{2} = M_{3}$
HOWEVER M, SH	IOVLD EQUAL MA AND L	C S - ALLO REPORTED
THE DISCREPANCY	IS DUE TO THE NUMBER OF	CALCULATIONS FERTONISU
ASSUME		
M, = Mq =	<u>1.5954 + 1.3624 = 1.478</u> 2	8 in-15/in
$M_2 = M_3 = =$	<u>(3.5064+3.5446)</u> =-3.52 Z	255 In-16/in
56, = 6×1.470	88 / 0155 ² = <u>36900</u>	
S62 = 6×3.52	55/.0155 ² · 88000	
•		

CURTISS - WRIGHT CORPORATION WRIGHT AERONAUTICAL DIVISION WRITTEN BY L. SEELEN RECORD OF ANALYSIS ENGINE NO. APPROVED BY US JOB NO. 5/792 DATE 10-23-59 SUBJECT: INTERLOCKING WIRE WRAPPED VESSEL RESULTS, SKETCHES & FORMULAS BENDING OF IST CHRINNEL WRITH DUE TO PRESSURE - CASE 2 a TREATING THE CHANNEL AS A FIXED ENDED BEAM WHERE "A" IS AT THE SUPPORT AND "B" IS AT THE CENTER.  $M''_{H''} = P \frac{(.0944)^2}{12} = .0007426 P.$   $\overline{Z} = \frac{1 \times .0155^2}{12} = .4 \times 10^{-4}$ M's" = p (.0944)² = .0003713 p 56"A" = .0007426 p1.00004 = 18.565 p = 93000 psi 56"8" = .0003713pl.00004 = 9.283p = 46500 psi WITH A SUBSCALE VESSEL SUCH AS THE ONE CURRENTLY UNDER DEVELOPMENT, THE BENDING STRESSES IN THE IST CHANNEL WRAP WILL BE LARGE. HOWEVER FULL SCALE VESSELS OPERATE AT SUBSTRANTIALLY

LOWER PRESSURES AND THIS STRESS IS NEGLIGIBLE. THE GHANGE IN "E" BEAM WIDTH SUGGESTED ON PAGE 15 WILL REDUCE THESE STRESS TO 43000 psi AT THE END AND 21600 psi AT THE CENTER (CASE 2B)





CURTINS - WRIGHT CORPORAT WRIGHT AERONAUTICAL DIVIL WRITTEN BY D. Kanowsky RECORD OF ANALYSIS ENGINE NO. Wire Wrop Motor APPROVED BY WBG DATE_____________ JOB NO. 51792 SUBJECT: Dome Adapter stresses RESULTS, SKETCHES & FORMULAS L= .1472 -- channel (titanum). .0155 <del>uuuuu</del>u Phricent = Philanium .026 timm Dome Adopter (tricent)  $\Sigma \delta_{+} = \delta_{c}$ hitanium tricent .026 A .0155  $\left(\frac{pl^{3}}{2ET} + \frac{b}{5}\frac{pl}{4g}\right) = \left(\frac{pl}{AE}\right)$ 16 + 106 30 × 10 6 E 12×106 G г . 1472 L 12 (.025)3 = 1.30 × 10-6  $\frac{l}{3(30)(1.30)} + \frac{6}{5} \frac{l}{(.026)(12\times10^{6})} = \frac{.1472}{(.0155)(16\times10^{6})}$ I  $\cdot 00854l^3 + 3.85 \times 0^{-6} l = .594 \times 10^{-6}$  $l^{3} + 4.51 \times 10^{-4} l = .697 \times 10^{-4}$ l=.037 (Say .035") Ptotal= 7750 #/m Pt = Pe = 3875 # 1 tricent: M= 3875x,035= 136 shear  $\sigma = \frac{3875}{026} = 149,000 \text{ psi }$  $\vec{E} = \frac{1.30 \times 10^{-6}}{1.3 \times 10^{-2}} = 1 \times 10^{-4}$ J = 136 x104 = HIGH If tricent is assumed to be prevented from bending, by the abutting channel: then: 3.85l = . 594 l= .155"

RECORD OF ANALYSIS

ENGINE NO. WIRE WROP Motor JOB NO. 51792

WRITTEN BY D. Kanowsky APPROVED BY WBB DATE 2/19/60

SUBJECT: Trial of Error solution for "L"

## RESULTS, SKETCHES & FORMULAS

l + 4.51×10-1 l = .697×10-1

1	.02	. 03	.04	. 035	.037	,038
1 ³			. 64×10-4	.43×10-4	. 507 × 104	-4 .549 x 10
L Arl Que-4	190 x10 +	135×10-4	_4 .1804 x 10	.158 x 10 -4	.167 x 10-4	
=.697×10-1	-47×10-4	405×10-4	82×10-4	.588 x 10-4	.674 x 104	720×10

l=.037

RECORD OF ANALYSIS

WRITTEN BY D. Kanows ky
APPROVED BY UBG
DATE 2/19/60

ENGINE NO. Wire Wrop Motor JOB NO. 51792 SUBJECT: Dome Adapter stress

RESULTS, SKETCHES & FORMULAS

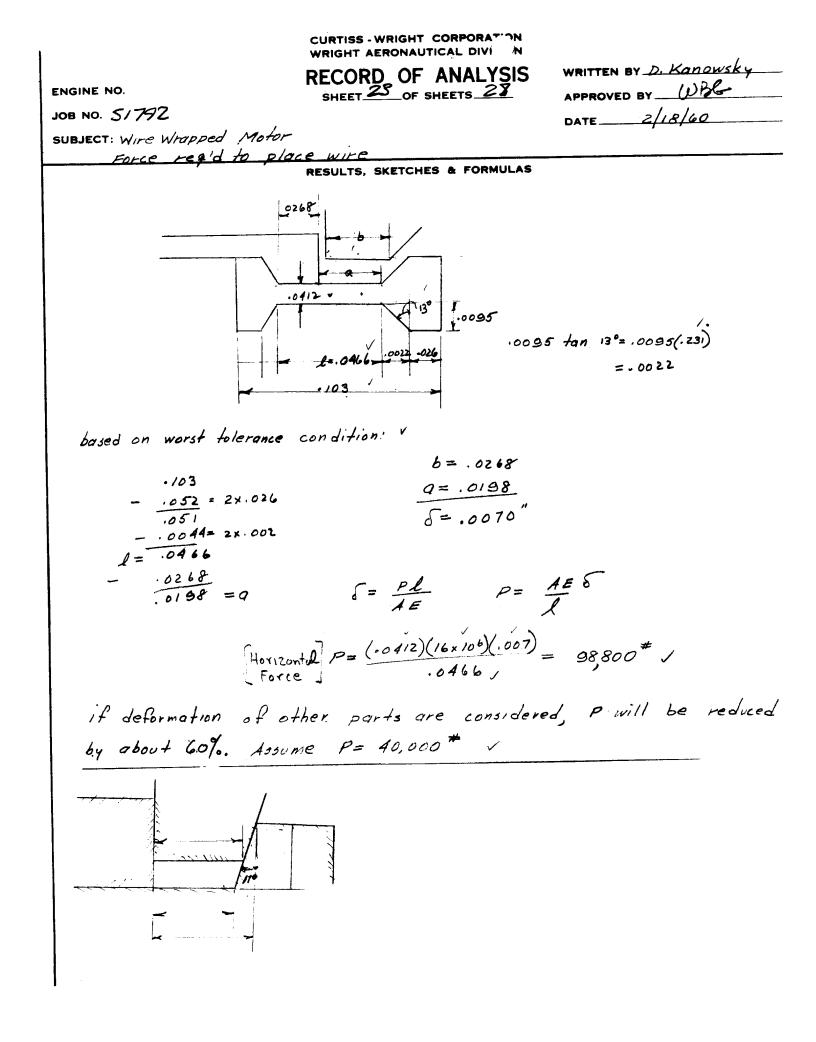
l=.035 :

Tolerance condition when tricent is stiffest." A . 0115 . 0268 E 16×106 30×106 G 12×106 l .15 .035 I  $\frac{1}{12}(.0268)^3 = 1.61 \times 10^{-6}$  $P_{f_{1}}\left[\frac{(.035)^{3}}{3(30)(1.61)} + \frac{6.035}{5(.0268)(12\times10^{6})}\right] = P_{e}\left(\frac{.15}{(.0145)(16\times10^{6})}\right)$ P+ [.297 × 10-6 + .130 × 10-6] = Pe (.648 × 10-6) P+ (.427) = R (.641) PT= = 1.52 Pc total P= 7750" PT = 4670"  $\frac{Z}{C} = \frac{1.61 \times 10^{-6}}{1.34 \times 10^{-2}} = 1.2 \times 10^{-4}$ Tricent: M= 4670x.035= 163  $\sigma = \frac{163}{1.7} \times 10^4 = High$ 

Shear.  $\sigma = \frac{4670}{.0268} = 174,000 \text{ psi}$ Titanium :  $S = \frac{P}{A} = \frac{3080}{.0145} = 210,000$  $E = \frac{S}{E} = \frac{210000}{16 \times 10^{5}} = \frac{.21}{16} = .013$ 

CURTISS - WRIGHT CORPORATION WRIGHT AERONAUTICAL DIV WRITTEN BY D. Kanowsky RECORD OF ANALYSIS APPROVED BY W.B. G. ENGINE NO. DATE_____2/18/60 JOB NO. 5/792 SUBJECT: Wire Wrapped Motor stress in wire on spool. RESULTS, SKETCHES & FORMULAS wire to be unwrapped from 6" spool: Bending stress: .0594 .0412 .1455 .0256 / .0549- $\frac{M}{EI} = \frac{1}{R}$ M= 08= 5 % J= CE / THE A A, y Ay .0161 x .1455 = .00234 .0080 .0000187  $\overline{y} = \frac{.0000362}{.00371}$ channel: E= 16 × 106 psi .00000175 .000036 Z  $2 \times 0256 \times 0268 = 00137$ y = c = .00974 ~ R= 3.1" 62=.0256-.00974  $\sigma = \frac{(.0159)}{31} \frac{16 \times 10^6}{31}$ C2=.0159 -V ·روم 82,000 = T NG reduce to 50,000 psi max 5=(50,000)=(.0159)16×106 10.1" spool min.  $R = \frac{(.0.159) 16 \times 10^6}{50 \times 10^3} = 5.05'' \sqrt{}$ Dumbell. C,=C,=.0297" √ J= .0297 x 82000 = 153,000 p31

min R for  $50000 p_{51} = \frac{.0297}{.0159} \times 5.05 = 9.43''$ <u>0.58 = 9.43''</u> <u>0.58 = 19'' sport</u></u>



_____

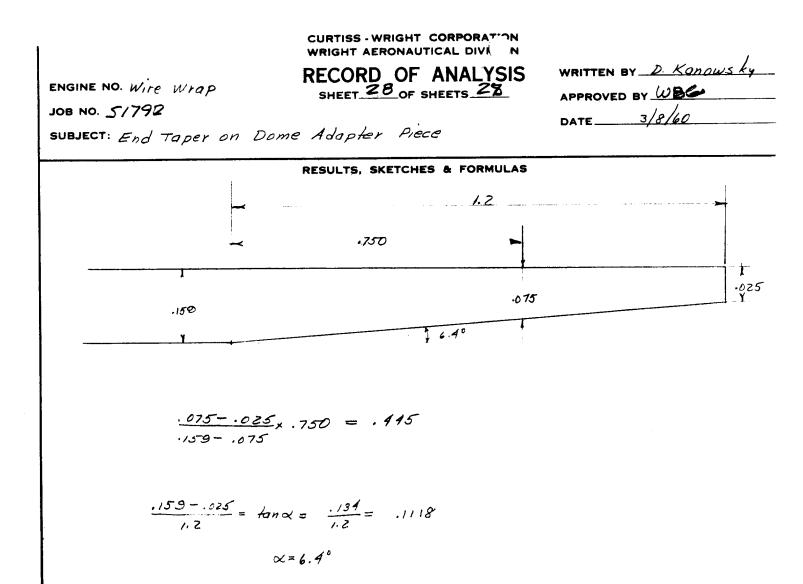
CURTISS - WRIGHT CORPORATION RIGHT AERONAUTICAL DIVI WRITTEN BY D. Kanowsky RECORD OF ANALYSIS SHEET 24 OF SHEETS 23 ENGINE NO. WITE WHOP APPROVED BY UB.G. JOB NO. 5/792 2/23/60 DATE ____ SUBJECT: Force reg'd to place wire RESULTS, SKETCHES & FORMULAS Ρ 1/3°  $P = H \tan 13^\circ + F_1' \cos 13^\circ + F_2'$ Γ'= μ.N = <u>H</u> / cosis F'= MH 1 P= 4 [ton 13 + 2 m] H= 40,000 per inch circumference M. . 2 (assumed) V tan 13°= . 231 ton 13°= .231 = <u>.400</u> .631 ZH × 40,000 P= 25,000 * /inch of civcum. assume length of contact between roller & wire = .1"

$$apply P = 2500^{\#} \vee$$

CURTISS - WRIGHT CORPORATION WRIGHT AERONAUTICAL DIVIL WRITTEN BY D. Kanowsky RECORD OF ANALYSIS ENGINE NO. WIRE Wrap APPROVED BY WBG JOB NO. 5/792 DATE 3/8/60 SUBJECT: Axial Pull for Wropping wire RESULTS, SKETCHES & FORMULAS 7" Spool Diameter Vessel Diameter 6.5"  $\frac{M}{EI} = \frac{1}{2}$  $\sigma_{\rm F} = \frac{Mc}{I} = \frac{EI.c}{RI} = \frac{Ec}{R}$ Hold J to .70 0, = .70 × 250,000 = 175,000 psi  $\sigma = \sigma_b + \sigma_a$  $\mathcal{J} = \frac{E_c}{R} + \frac{P}{A} \leq 175,000$ Dum bell C = .0297''A=.00509"" unwinding:  $\frac{E_{c}}{R} = \frac{16 \times 10^{6} \times .0297}{75} = 135,500 \text{ psi}$  $\frac{P}{1} = 175,000 - 135,500 = 39,500 \text{ ps},$ P ≤ 39,500×.00509 P= 201# <u>channel</u> max c=.016"  $\frac{E_{c}}{R} = \sigma_{b} = \frac{.016}{.0297} \times 135,500 = 73,000 \text{ psi}$ A = .0037 ""  $\frac{P}{4} = 175,000 - 73,000 = 102,000 \ Psi$ P≤ 102,000x.0037 *P* **≤** 377 [#]

	CURTISS - WRIGHT CORPORATION WRIGHT AERONAUTICAL DIVIL	, ·
	RECORD OF ANALYSIS	WRITTEN BY D. Konowsky
ENGINE NO. Wire Wrap	SHEET 26 OF SHEETS 28	APPROVED BY UBG
JOB NO. 5/792	• · · · ·	DATE 3/17/60
SUBJECT: Axial Pull for Wro	pring wive	
<u> </u>	RESULTS, SKETCHES & FORMULAS	<u> </u>
unw-apping wire	from 7" spool:	
Dumbell o	= 135,500 psi	
channell v	= 73,000 psi	
wire to be reu	wound on 6.5" diameter	vessel
$\frac{Dumbell}{\sigma^2 - \frac{ec}{R} = 0}$	<u>16×10⁶× .0297</u> = 146,000 3.25	seq (
$\frac{channel}{\sigma'} = \frac{16}{2}$	<u>×106 ×. 016</u> = 78,700, 3.25	P
	ing in wire due to	wrapping:
Dumbell:		
wrap on 6.5"	146,000	
Unwrap from 7.0"	135,500	
	10,500 psi	
channel:		
wrop on 6.5	5" 78,700	
UNWEOD from 7.0	73,000	
net stres	55 <u>5,700 psr</u>	
To keep total prelo	ad in wire below 50,00	
	-10,500 = 39,500 USE	P≦ 200 [#] as before
channel so,000-	5700 = 44,300	
44,300 -	* <del>7</del>	
P = 11	,300 x .0037 = 165#	
	axial load will remain in	wire
Recommending P= 2.	00# for Dumbell & chann	e/

CURTISS - WRIGHT CORPORAT WRIGHT AERONAUTICAL DIVL WRITTEN BY D. Kanowsky RECORD OF ANALYSIS ENGINE NO. WITE WIOP APPROVED BY WBG JOB NO. 5/792 DATE 3/8/60 SUBJECT: End Taper on Dome Adapter Piece RESULTS, SKETCHES & FORMULAS 120" .06 .00 097 Effective thickness of wire assembly: Area in . 20" length: .09x.20 = .0180 - .097 x .06 = .0058 .0122 Area per inch = .0122 x 1 = .061" Effective thickness = . 061" tricent use thickness at end of taper: t= .025" Thickness for yielding of tricent at 5000 psi pressure:  $\frac{p_R}{t} = \overline{v_y}$ 0; = 220,000 pui  $t = \frac{pR}{T_u}$  $t = \frac{5000 \times 3.25}{220.000} = .074 \sim .075$ 



The .025 end thickness and .75 length were orbitrarily chosen. The adapter will yield from the .75 kngth to the .025 end, thus reducing the effects of the interlocking wire wrapped cylinder - adapter discontinuity. Wright Aeronautical Serial Report No. MP.00-224

#### APPENDIX II

#### STRUCTURAL RIG TESTING PROCEDURE

- 1. Instrument the specimen as shown in Figure 16 and check.
- 2. Balance all gages. Take a zero and a calibration reading.
- 3. A combination of three loads is to be applied to the specimen for each reading of strain values. These are the tensile, the longitudinal clamping load from the torquing of the two 7/8 in. side bolts, and the transverse clamping load induced by torquing the two 1/4 in. top bolts. For each combination of pull load and transverse clamping load, three longitudinal clamping loads are applied.

A typical cycle in applying the loads is as follows:

- (a) Torque 1/4 in. transverse clamping bolts to 4 in. lbs. Apply 4,650 lbs. tensile load to specimen and record strain readings. Release the load.
- (b) Using the same transverse clamping load as in step (a), apply 489 in. lbs. torque on the 7/8 in. longitudinal clamping bolts. Apply the same load as in step (a) and record the strain readings. Release the load. (c) repeat step (c) using 586 in. lbs. torque on the 7/8 in. longitudinal clamping bolts.
- 4. Tabulation of the test loads and the order of their application are as follows:

# Wright Aeronautical Serial Report No. MP.00-224

## APPENDIX II (Continued)

Clamp	tudinal ing (lbs.)	Rquiv. (Approx.) 7/8 in Bolt Torque (in.lbs.)	Tensile Load (lbs.)	Trans. Clamp Load (lbs.)	Equiv. (Approx.) 1/4 in Bolt Torque (in.lbs.)
(a) (b) (c)	2360 2950 3540	391 489 486	4,650	81	4
(a) (b) (c)	3930 4910 5880	651 813 974	7,750	135	6
(a) (b) (c)	5490 6860 8230	909 1136 1363	10,850	189	9
(a) (b) (c)	7050 8840 10600	1167 1464 1755	13,950	243	11
(a) (b) (c)	8650 10800 12820	1432 1799 2123	17,050	297	14
(a) (b) (c)	10250 12750 15400	1697 2111 2550	20,150	351	16

#### APPENDIX III

### B120VCA TITANIUM WIRE SPECIFICATION

- 1. ACKNOWLEDGEMENT: Vendor shall mention the specification number and its revision letter in all quotations and when acknowledging purchasing orders.
- 2. FORM: Coils of wire.
- 3. COMPOSITION:

SITION:		CHECK J Under Min. O:	ANALYSIS r Over Max.
Vanadium Chromium Aluminum Oxygen Carbon Nitrogren Hydrogen Other Elements Iron Titanium	12.5-14.5 10.00-12.00 3.0-4.0 0.15-Max. 0.06-Max. 0.05-Max. 0.0100-Max. 0.060-Max. 0.35-Max. balance	0.15 0.15 0.40 - - - - -	0.15 0.15 0.40 - 0.02 0.02 .001 -

- 4. CONDITION:
- 4.1 Uniformly solution annealed after final draw.
- 4.2 Material shall be free from all surface and sub-surface defects.
- 4.3 No surface contamination or oxide film.
- 4.4 Wire shall be coil ground before final draw.
- 4.5 Wire shall contain no seams, nicks, kinks, bends, breaks, burrs, scratches, or marks due to grinding or drawing.
- 4.6 Wire surface must be clean and contain no foreign materials and imperfections which may adversely affect the processing or quality of finished articles.

Wright Aeronautical Serial Report No. MP.00-224

### APPENDIX III (Continued)

5. TOLERANCES: Unless otherwise specified, tolerances shall conform to the following:

Nominal Inch	Tolerance <u>Plus</u>	es, Inch <u>Minus</u>
.200	0.001	0.001
.130	0.000	0.0005
	0.0005	0.0005
		.200 0.001 .130 0.000

6. TENSILE PROPERTIES:

Tensile strength, psi 130,000 min. Reduction in area, % 25 min.

- 7. REPORTS: Unless otherwise specified, the vendor of wire shall furnish with each shipment three copies of a report of the results of tests for chemical composition and tensile strength of each coil in the shipment. This report shall include the purchase order, heat number, material specification number, size, and quantity.
- 8. PACKAGING: Packaging shall be accomplished in such a manner as to insure that the wire, during shipment and storage, will be protected against mechanical injury.
- 9. APPROVAL: To assure adequate performance characteristics, wire shall be approved by purchaser before use, unless such approval be waived.
- 10. REJECTIONS: Material not conforming to this specification or to authorized modifications will be subjected to rejection.

SS. WRIGHT CORPWRIGHT AERONAUTICAL DIV WRAP ROCKET CASE DEVELOPMENT DEPT 86:12 WRAP ROCKET CASE DEVELOPMENT DEPT 86:12 DIFT (2014)     112       VIE NO. 22141961     DATE SALEDUE     121300       DATE STEFEDUE     0.2141961     DATE SALEDUE       FFOR DITY     TARGET FRENT FOR WIRE BAL2     1/29/0       DITY     70059     02141961       DEV     001099     02141961       DEV     001099     02141961       DEV     001099     02141961       DEV     001019     02141961       DEV     001019     02141961       DEV     0112.00     040.0       DEV     0112.00     012       DEV     012.01     0129/0       DEV     0110     0129/0		$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	
SS WRIGHT CORP-WR WRAP ROCKET CASE WRAP ROCKET CASE ULLE NO 42 201410 11960 0214110 SCHEDULE 0.0214110 11960 021411961 DEV 001141961 1111 EFF OF SINGLEEL METHODS DEVEL 000090 02141961 00880100020 0880100020 110 088020010 12 088020010 14 088020010 15 088020050 16 PROC FITIING 15 088020050 16 PROC FITING	TICAL DIV DEPT 8612	EXPECTED       VARIANCE         TIME-WKS       VARIANCE         8612       1/29/0       7/08/0       112.6         8612       1/29/0       7/08/0       112.6         8612       1/29/0       5/02/0       87.6         8612       1/29/0       5/02/0       87.6         8612       1/29/0       3/21/0       35.         8612       1/29/0       3/21/0       35.         8612       1/29/0       3/21/0       37.1         8612       1/29/0       3/22/0       4/28/0       27.1         8612       1/29/0       3/30/0       42       4.2         8612       1/29/0       3/30/0       42       4.2         8612       1/29/0       3/30/0       26       42         8612       1/29/0       3/30/0       26       42         8612       1/29/0       3/30/0       42       42         8612       1/29/0       3/30/0       42       42         8612       3/01/0       4/05/0       27       26         8612       3/01/0       3/30/0       42       40         8612       3/01/0       4/05/0       3/31/0	
	RIGHT CORP-WE ROCKET CASE ON 42 E EVALUATION 22141	RIGINAL CURRENT         TARGET PREDICTION         TARGET PREDICTION         TARGET FOR WIRI         112.00         SINGLEEDUPL AGING         R7.00         SINGLEEDUPL AGING         R7.00         SINGLEEDUPL AGING         R7.00         PLASTIC         35.00         D020         D020         SEVEL         NIN         SE ROLLS         SHPES         RE DIES-CHANNEL SHA         00010       15.00         00010       15.00         200050       22.00         200050       28.00         200015       52.00         200015       52.00         200015       50.00         200015       50.00         200015       50.00         200015       50.00	

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00000016	0800200017		0800200018	0800200019 0800200019 0800200019 0800200019	0800200020 0800200020	0800200020 0800200020	0800200021 0800200021	80020002	80020002	0800200023	0800200025	0800200025 0800200025	0800200030	0800200035 0800200035	0800200035 0800200099 0800200099 0800200099	0800200099 0800200099 0800200099	0800200099 0800200105 0800200105	80020010 80020011
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0800400001 0800400001	0800400070 0800400070	0800400080 0800400080	0800400090 0800400090	0800400099 0800400099 0800400099	0800500001 0800500001	0800500004 0800500004	0800500008 0800500008	0800500010 0800500010	0800500012 0800500012	0800500014 0800500014	0800500030 0800500030	0800500032 0800500032	0800500034 0800500034	0800500035 0800500035	0800500036 0800500036	0800500038 0800500038	0800500040

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25.00	COMPLETE DES&STRESS ANAL			0800500012 .00						PROC BOLTS RND HD DR STUD 0800500035 18.00	PROC BOLTS GROOV PIN TYPE3 0800500035 18.00	TEVAL MACH METHODS-ADAPTERS 0880600001 10.00	METHODS DEVELOP-ADAPTERS 0800603001 11.00	PROC ADAPTER MATERIAL 25.00	PROC ADDIT ADAPTER MATL	TOOL DESIGN MANDREL 0800700021 7.00	TOCL SHEETS MANDREL 0800700004 •00	FABRICATE MANDREL 6800700004 57.00 0800700006 57.00 0880700010 57.00	ICOL DESIGN END ADAPTERS	IOOL SHEETS END ADAPTERS 0800700012 1.00	TOOL FAB END ADAPTERS
0800500040	0800500099	0800500099 0800500099		1				- t		0800510001 0800510001	0800510002 0800510002	0800600001 0800600001	0800600005 0800600005	0800700001 0800700001	0800700002 0800700002	0800700004 0800700004	0800700006 0800700006	0800700010 0800700010 0800700010 0800700010	0800700012	10007008 10007008	0800700018
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	8420	8241	8420		8420	8420	8420	8420	8420	8420	8420	8420	
080070005 18.00 080770014 18.00 0880700018 18.00	PART SHEETS ADAPTERS 0800500099 7.00 0880700020 7.00	E033177 RELEASE DESIGN 0800500035 5+00	FABRICATE ADAPTERS 0800200023 45.00 080050035 45.00		SHEETS-DUMMY ARBOR 0880700030 4.00	FABR-DUMMY ARBOR 0800700030 80.00	METHODS DEVELOPMT STÅKING 0800500099 8.00 0880800001 8.00	METHODS DEVELOPMT WRAPPING 0800200019 44.00 0800500099 44.00 0800700035 44.00 0880800001 44.00	TOOL DESIGN WRAPPING MACH 0800700021 22.00	TOOL SHEETS WRAPPING MACH 0800800010 3.00	TOOL         FAB         WRAPPING         MACH           0800800015         42.00	WRAP & STAKE CYL SAMPLE 0800200020 11.00 0800200035 11.000 0800200035 11.000	
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