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# NATIONAL ADVISORY COMMITTEE FOR AERONAUTICS

REPORT No. 788

## ON THE PLANE POTENTIAL FLOW PAST A LATTICE OF ARBITRARY AIRFOILS

By L. E. GARRICK

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## AERONAUTIC SYMBOLS

### 1. FUNDAMENTAL AND DERIVED UNITS

|             | Symbol   | Metric                    |                   | English                |                   |
|-------------|----------|---------------------------|-------------------|------------------------|-------------------|
|             |          | Unit                      | Abbrevia-<br>tion | Unit                   | Abbrevia-<br>tion |
| Length..... | <i>l</i> | meter.....                | m                 | foot (or mile).....    | ft (or mi)        |
| Time.....   | <i>t</i> | second.....               | s                 | second (or hour).....  | sec (or hr)       |
| Force.....  | <i>F</i> | weight of 1 kilogram..... | kg                | weight of 1 pound..... | lb                |
| Power.....  | <i>P</i> | horsepower (metric).....  |                   | horsepower.....        | hp                |
| Speed.....  | <i>V</i> | kilometers per hour.....  | kph               | miles per hour.....    | mph               |
|             |          | meters per second.....    | mps               | feet per second.....   | fps               |

### 2. GENERAL SYMBOLS

|          |  |          |   |
|----------|--|----------|---|
| <i>W</i> | Weight= $mg$   | <i>ν</i> | Kinematic viscosity   |
| <i>g</i> | Standard acceleration of gravity= $9.80665 \text{ m/s}^2$<br>or $32.1740 \text{ ft/sec}^2$         | <i>ρ</i> | Density (mass per unit volume)<br>Standard density of dry air, $0.12497 \text{ kg-m}^{-3}$ at $15^\circ \text{ C}$<br>and $760 \text{ mm}$ ; or $0.002378 \text{ lb-ft}^{-3} \text{ sec}^2$ |
| <i>m</i> | Mass= $\frac{W}{g}$  | <i>γ</i> | Specific weight of "standard" air, $1.2255 \text{ kg/m}^3$ or<br>$0.07651 \text{ lb/cu ft}$   |
| <i>I</i> | Moment of inertia= $mk^2$ . (Indicate axis of<br>radius of gyration <i>k</i> by proper subscript.) |          |   |
| <i>μ</i> | Coefficient of viscosity   |          |   |

### 3. AERODYNAMIC SYMBOLS

|                      |   |                      |   |
|----------------------|---|----------------------|---|
| <i>S</i>             | Area  | <i>i<sub>w</sub></i> | Angle of setting of wings (relative to thrust line)   |
| <i>S<sub>w</sub></i> | Area of wing  | <i>i<sub>t</sub></i> | Angle of stabilizer setting (relative to thrust<br>line)  |
| <i>G</i>             | Gap   | <i>Q</i>             | Resultant moment  |
| <i>b</i>             | Span  | <i>Ω</i>             | Resultant angular velocity  |
| <i>c</i>             | Chord   | <i>R</i>             | Reynolds number, $\rho \frac{Vl}{\mu}$ where <i>l</i> is a linear dimen-<br>sion (e.g., for an airfoil of 1.0 ft chord, 100 mph,<br>standard pressure at $15^\circ \text{ C}$ , the corresponding<br>Reynolds number is 935,400; or for an airfoil<br>of 1.0 m chord, 100 mps, the corresponding<br>Reynolds number is 6,865,000) |
| <i>A</i>             | Aspect ratio, $\frac{b^2}{S}$                                 | <i>α</i>             | Angle of attack   |
| <i>V</i>             | True air speed  | <i>ε</i>             | Angle of downwash   |
| <i>q</i>             | Dynamic pressure, $\frac{1}{2}\rho V^2$                       | <i>α<sub>0</sub></i> | Angle of attack, infinite aspect ratio  |
| <i>L</i>             | Lift, absolute coefficient $C_L = \frac{L}{qS}$               | <i>α<sub>i</sub></i> | Angle of attack, induced  |
| <i>D</i>             | Drag, absolute coefficient $C_D = \frac{D}{qS}$               | <i>α<sub>a</sub></i> | Angle of attack, absolute (measured from zero-<br>lift position)  |
| <i>D<sub>0</sub></i> | Profile drag, absolute coefficient $C_{D0} = \frac{D_0}{qS}$  | <i>γ</i>             | Flight-path angle   |
| <i>D<sub>i</sub></i> | Induced drag, absolute coefficient $C_{Di} = \frac{D_i}{qS}$  |                      |   |
| <i>D<sub>p</sub></i> | Parasite drag, absolute coefficient $C_{Dp} = \frac{D_p}{qS}$ |                      |   |
| <i>C</i>             | Cross-wind force, absolute coefficient $C_C = \frac{C}{qS}$   |                      |   |

E R R A T A

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Page 4, column 2, line 3: The term at the end of the line should have a bar over  $\psi$ ; thus  $\bar{\psi}[\theta(\phi)]$

Page 7,

Column 1, equation (28): The left-hand side of the equation should read  $e^{i\sigma}$

Column 1, line following equation (28): Change  $\sigma$  to  $\delta$ .

Column 2, line 16: The bracket and the fractional exponent at the end of the equation for  $E$  should be transposed to read

$$\dots \sin 2\theta]^{1/2}$$

Page 13, column 1, last line: The equation should read

$$y = y_{0_1} \approx \frac{c_1 \psi^2}{\pi} G_0$$

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**By I. E. GARRICK**

**Langley Memorial Aeronautical Laboratory  
Langley Field, Va.**

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By I. E. GARRICK

#### SUMMARY

*The two-dimensional, incompressible potential flow past a lattice of airfoils of arbitrary shape is investigated theoretically. The problem is treated by usual methods of conformal mapping in several stages, one stage corresponding to the mapping of the framework of the arbitrary line lattice and another significant stage corresponding to the Theodorsen method for the mapping of the arbitrary single wing profile into a circle. A particular feature in the theoretical treatment is the special handling of the regions at an infinite distance in front of and behind the lattice. Expressions are given for evaluation of the velocity and pressure distribution at the airfoil boundary. An illustrative numerical example is included.*

#### INTRODUCTION

This paper treats the problem of determining the flow pattern, or the velocity and pressure fields, associated with the uniform flow past an infinite row of symmetrically placed airfoils of the same shape. This airfoil-lattice problem occurs in the design of turbine blades, wind-tunnel vanes or grids, and elsewhere. There is a purely mathematical interest in the problem that concerns the field of conformal mapping of infinitely connected regions. Analogous two-dimensional "lattice" problems occur in the steady flow of heat and electricity.

Considerable ingenuity has been devoted to the airfoil-lattice problem, especially in the turbomachine studies in the German literature and more recently in the British studies; nevertheless, a survey of the available literature indicates that nearly all the treatments employed and the results obtained are of a special or indirect nature which involves, for example, lattices of thin lines or approximate graphical procedures. Recently, however, A. R. Howell in a British paper of limited circulation has written briefly on the theory of arbitrary airfoils in cascade. Howell applies a special transformation to an airfoil lattice to convert the lattice region to a somewhat random, simply connected region and, with the aid of several stages of conformal mapping, obtains a region about a circle.

The problem of determining the incompressible potential flow past an arbitrary single wing section was studied by Theodorsen (reference 1), who gave a practical procedure for its solution. The case of two wing sections, or the arbitrary biplane, was later treated in reference 2. The determination of the flow past an infinite lattice of airfoils of the same shape is a problem intermediate in difficulty in

comparison with the aforementioned ones. The treatment for resolving this problem given in the present report is similar to that for the arbitrary single wing section but the calculations are more involved.

The problem will herein be studied by the usual method of conformal mapping. It is convenient to accomplish the result in three or four stages: The airfoil lattice is first replaced by its skeleton, or framework of line segments. The initial mapping function employed transforms the lattice skeleton into a circle. In the plane of this circle there are two singular points, known as branch points. These points have dual significance: They correspond to infinite regions in front of and behind the lattice of lines, and they enter in the problem of reducing the lattice region (multiply connected region) to the region of a single body (simply connected region). If now an arbitrary airfoil shape is generated or given around the framework of lines, then in the plane of the circle a circular-like contour is generated around the original circle. This contour may be transformed into an exact circle by the well-known procedure given in reference 1 or 3. The original two significant points are then traced by a transformation due to H. A. Schwarz. A final elementary transformation will bring the circle into a standard circle for which the two characteristic branch points are symmetrically placed. The region of this circle is considered the standard region for determining the flow pattern.

For illustrative purposes an outline of a procedure for calculating pressure distributions is included. The method may be followed without reference to the theory by readers interested mainly in numerical results. For convenience, a list of symbols is given in appendix A.

#### ANALYSIS

**Initial transformation for lattice of straight lines.**—Consider the transformation (reference 4)

$$\zeta_1 = \frac{g}{2\pi} \left( \log \frac{b+z'}{b-z'} + \log \frac{z'+\frac{a^2}{b}}{z'-\frac{a^2}{b}} \right) \quad (1)$$

where  $g$ ,  $b$ , and  $a$  are real numbers and  $b > a$ . Introduce coordinates  $\psi$  and  $\theta$  by means of the relation

$$z' = ae^{\psi+i\theta} \quad (2)$$

and let

$$\frac{b}{a} = e^{\gamma_0} \quad (3)$$

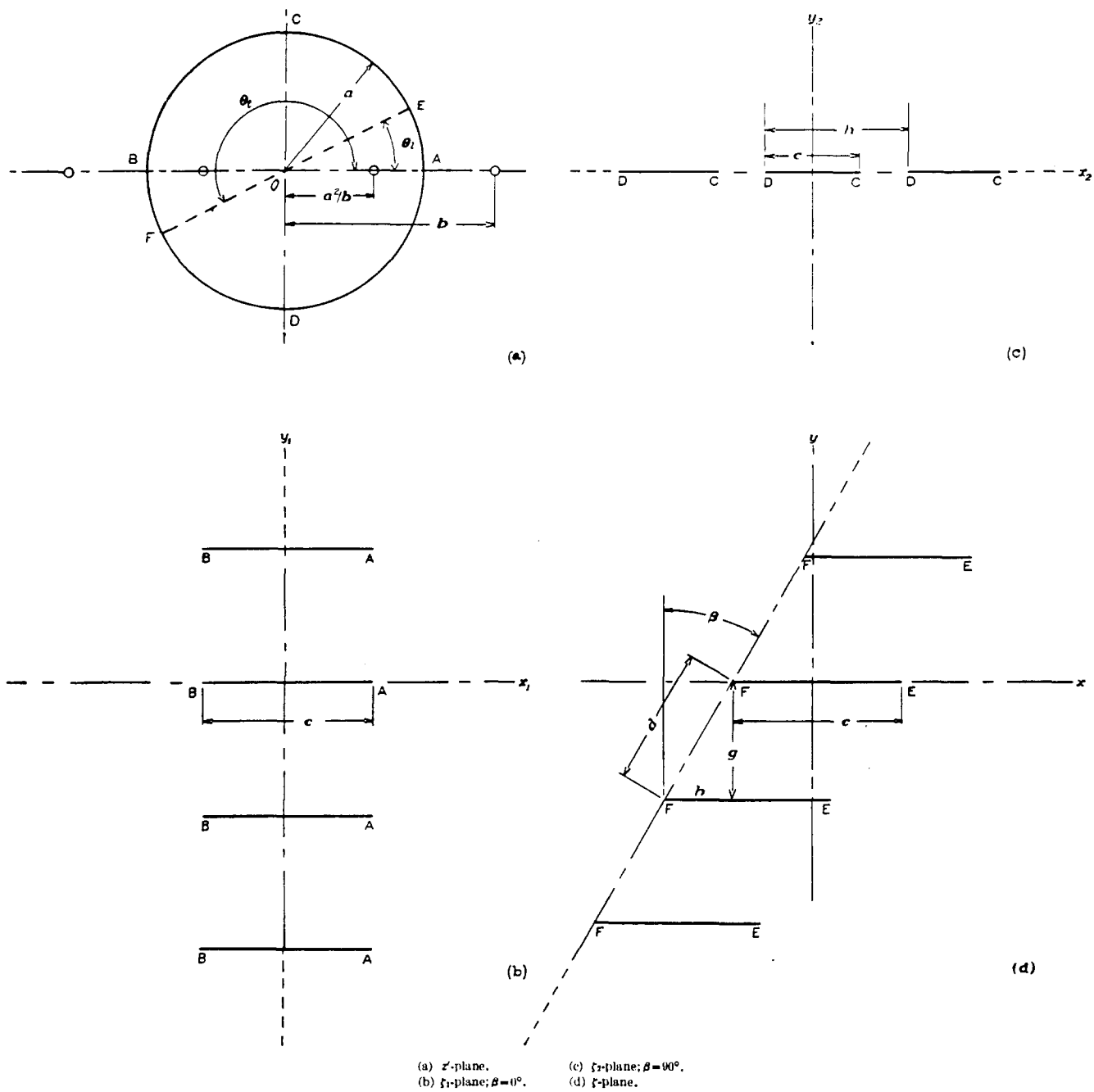


FIGURE 1.—The properties of initial transformation.

Equation (1) may then be expressed as

$$\zeta_1 = \frac{g}{2\pi} \log \left[ \frac{\cosh \gamma_0 + \cosh (\psi + i\theta)}{\cosh \gamma_0 - \cosh (\psi + i\theta)} \right] \quad (4)$$

If  $\psi=0$ , according to equation (2),  $z'$  lies on a circle of radius  $a$  (fig. 1(a)). According to equation (4),  $\zeta_1 = x_1 + iy_1$  is the logarithm of a real positive function and, consequently, represents a real function (its principal value) and the infinite sequence of values differing from this function by  $\frac{g}{2\pi} 2k\pi i$ , where  $k$  is any integer. The transformation illustrated in figure 1(b) is that of an infinite lattice of unstaggered lines of gap  $g$  in the  $\zeta_1$ -plane into the circle of radius  $a$  in the  $z'$ -plane. The points  $z' = b$  and  $z' = -b$  correspond to infinity in front of and behind the lattice, respectively. The inverse points  $z' = \frac{a^2}{b}$  and  $z' = -\frac{a^2}{b}$  are inside the circle of radius  $a$ .

In order to introduce stagger, it is convenient to consider the transformation

$$\zeta_2 = -\frac{ih}{2} \left( \log \frac{b+z'}{b-z'} - \log \frac{z'+\frac{a^2}{b}}{z'-\frac{a^2}{b}} \right)$$

where  $h$  is real. This transformation can be written with the use of equations (2) and (3) as

$$\zeta_2 = -i \frac{h}{2\pi} \log \left[ \frac{\sinh \gamma_0 + \sinh (\psi + i\theta)}{\sinh \gamma_0 - \sinh (\psi + i\theta)} \right] \quad (5)$$

If  $\psi=0$ , the expression within the brackets is a complex number of unit magnitude; hence, the logarithm is a pure imaginary number plus an infinite sequence of numbers differing by  $2\pi i$ . Then  $\zeta_2 = x_2 + iy_2$  represents a sequence of real numbers differing by  $h$  and the lattice is one of horizontal lines displaced from each other by  $h$  (fig. 1(c)).

The transformation for the general staggered-line lattice is a combination of equations (4) and (5)

$$\zeta = \zeta_1 + \zeta_2 \quad (6a)$$

or

$$\zeta = \frac{d}{2\pi} \left( e^{-i\beta} \log \frac{b+z'}{b-z'} + e^{i\beta} \log \frac{z'+\frac{a^2}{b}}{z'-\frac{a^2}{b}} \right) \quad (6b)$$

where

gap  $g = d \cos \beta$

stagger  $h = d \sin \beta$

stagger ratio  $\frac{h}{g} = \tan \beta$

the parameter  $d$  may be called the slant gap (fig. 1(d)), and  $\beta$  the stagger angle.

The geometry of the lattice may be expressed in terms of the parameters  $\gamma_0$  and  $\beta$  by noting that the chord length may be obtained from the (singular or critical) values of  $\theta$  which correspond to the end points of the chord and are

solutions of the equation  $\frac{d\zeta}{dz'} = 0$ . This equation gives the result

$$\tan \theta = \tanh \gamma_0 \tan \beta \quad (7a)$$

or, for later reference,

$$\left. \begin{aligned} \cos \theta &= \frac{\cosh \gamma_0 \cos \beta}{Q} \\ \sin \theta &= \frac{\sinh \gamma_0 \sin \beta}{Q} \end{aligned} \right\} \quad (7b)$$

where

$$Q = (\cosh^2 \gamma_0 - \sin^2 \beta)^{1/2}$$

Relations (7) may be employed in two ways: (1) When the parameters  $\gamma_0$  and  $\beta$  are given, the relation determines the two critical values of  $\theta$ ,  $\theta_l$  and  $\theta_r$ , where the subscripts  $l$  and  $r$  refer to leading edge and trailing edge, respectively, and  $\theta_r = \theta_l + \pi$ . (2) When  $\theta_l$  or  $\tan \theta_l$  and the stagger angle  $\beta$  are given, the relation determines the parameter  $\gamma_0$ .

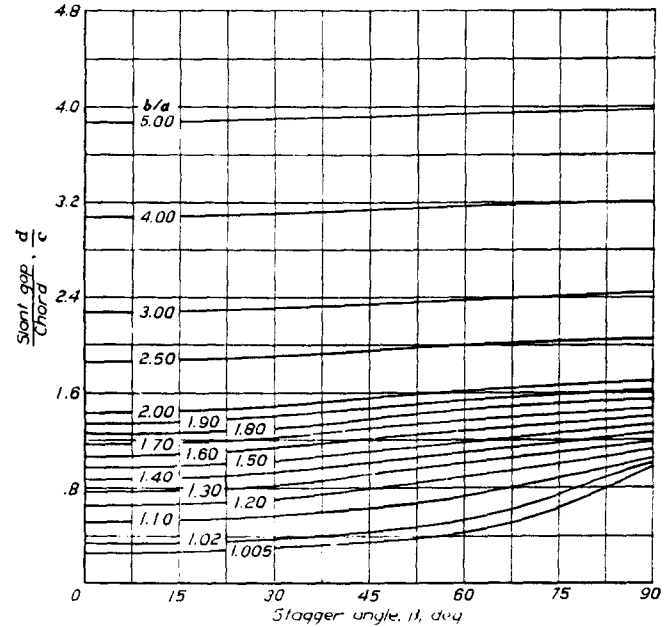


FIGURE 2.—Gap-chord ratio against stagger angle for various values of  $\frac{b}{a} = e^{\gamma_0}$ .

The chord  $c$  may be obtained by putting  $\theta = \theta_l$  and  $\theta = \theta_r$  in equation (6a) and taking the difference in abscissas  $x_l$  and  $x_r$ . From equations (4) to (7),

$$\begin{aligned} c &= x_r - x_l \\ &= \frac{2d}{\pi} \left( \cos \beta \log \frac{Q + \cos \beta}{\sinh \gamma_0} + \sin \beta \tan^{-1} \frac{\sin \beta}{Q} \right) \quad (8) \end{aligned}$$

By means of equation (8), the parameter  $\gamma_0$  can be presented directly in terms of given values of the gap-chord ratio for any stagger ratio. A representative chart relating gap-chord ratio, stagger angle, and  $\gamma_0$  is shown in figure 2; some values are given in table I.



TABLE I.—GAP-CHORD RATIO, PARAMETER  $\gamma_0$ , AND CORRESPONDING VALUES OF  $\theta_t$  FOR VARIOUS STAGGER ANGLES

| $b/a$ | $\gamma_0$ | $\sinh \gamma_0$ | $\cosh \gamma_0$ | $\beta=0^\circ; \theta_t=0^\circ$ |         | $\beta=30^\circ$ |         | $\beta=60^\circ$ |         | $\beta=90^\circ;$ |
|-------|------------|------------------|------------------|-----------------------------------|---------|------------------|---------|------------------|---------|-------------------|
|       |            |                  |                  | $d/c$                             | $d/c$   | $\theta_t$ (deg) | $d/c$   | $\theta_t$ (deg) | $d/c$   |                   |
| 1.005 | 0.004988   | 0.004988         | 1.000012         | 0.26207                           | 0.29481 | 0.13             | 0.44157 | 0.50             | 1.00319 |                   |
| 1.01  | .009950    | .009950          | 1.000050         | .29619                            | .33208  | .33              | .48904  | .59              | 1.00657 |                   |
| 1.02  | .019803    | .019804          | 1.000196         | .34636                            | .37997  | .66              | .54774  | 1.97             | 1.01277 |                   |
| 1.05  | .048790    | .048809          | 1.001191         | .42299                            | .46845  | 1.61             | .65010  | 4.83             | 1.03204 |                   |
| 1.10  | .095310    | .095455          | 1.004545         | .51594                            | .56641  | 3.14             | .75547  | 9.35             | 1.06450 |                   |
| 1.15  | .139762    | .140217          | 1.009783         | .58995                            | .64331  | 4.58             | .83357  | 13.52            | 1.09732 |                   |
| 1.20  | .182322    | .183333          | 1.016667         | .65507                            | .71028  | 5.94             | .89006  | 17.55            | 1.13051 |                   |
| 1.25  | .223144    | .225000          | 1.025000         | .71490                            | .77129  | 7.22             | .93724  | 20.82            | 1.16400 |                   |
| 1.30  | .262364    | .265385          | 1.034615         | .77118                            | .82829  | 8.42             | 1.01064 | 23.96            | 1.19781 |                   |
| 1.35  | .300105    | .304630          | 1.045370         | .82489                            | .88241  | 9.55             | 1.06073 | 26.78            | 1.23191 |                   |
| 1.40  | .336472    | .342857          | 1.057143         | .87698                            | .93433  | 10.61            | 1.10841 | 29.33            | 1.26627 |                   |
| 1.45  | .371564    | .380172          | 1.069828         | .92690                            | .98456  | 11.59            | 1.15433 | 31.61            | 1.30086 |                   |
| 1.50  | .405465    | .416667          | 1.083333         | .97599                            | 1.03340 | 12.52            | 1.19890 | 33.67            | 1.33570 |                   |
| 1.60  | .470004    | .487500          | 1.112500         | 1.07124                           | 1.12792 | 14.20            | 1.28505 | 37.20            | 1.40601 |                   |
| 1.70  | .530628    | .555882          | 1.144118         | 1.16362                           | 1.21927 | 15.67            | 1.36849 | 40.08            | 1.47708 |                   |
| 1.80  | .587787    | .622222          | 1.177778         | 1.25387                           | 1.30830 | 16.96            | 1.45020 | 42.46            | 1.55123 |                   |
| 1.90  | .641854    | .686842          | 1.213158         | 1.34250                           | 1.39561 | 18.10            | 1.53067 | 44.44            | 1.62114 |                   |
| 2.0   | .693147    | .750000          | 1.250000         | 1.42980                           | 1.48157 | 19.11            | 1.61036 | 46.10            | 1.68997 |                   |
| 2.5   | .916291    | 1.050000         | 1.450000         | 1.85391                           | 1.89894 | 22.69            | 2.00292 | 51.44            | 2.06407 |                   |
| 3.0   | 1.098613   | 1.333333         | 1.666667         | 2.26619                           | 2.30553 | 24.79            | 2.39240 | 54.18            | 2.44105 |                   |
| 4.0   | 1.386294   | 1.875000         | 2.125000         | 3.07484                           | 3.10588 | 27.00            | 3.17118 | 56.80            | 3.20605 |                   |
| 5.0   | 1.609438   | 2.400000         | 2.600000         | 3.87402                           | 3.89894 | 28.06            | 3.95163 | 57.98            | 3.97883 |                   |
| 10.0  | 2.302585   | 4.950000         | 5.050000         | 7.82840                           | 7.84191 | 29.51            | 7.86040 | 59.50            | 7.88022 |                   |

**Inversion of equations (4) to (6).**—The initial transformations may be thought of as mapping a framework of chords of an arbitrary lattice into a circle. If a shape is generated around the chords in the  $z'$ -plane, a contour is generated around the circle of radius  $a$ . This contour, which must exclude the points  $z'=-b$  and  $z'=b$  and must enclose the points  $z'=-\frac{a^2}{b}$  and  $z'=\frac{a^2}{b}$ , may be considered to be completely defined by the function  $\psi(\theta)$ . If a lattice of airfoils is preassigned, the function  $\psi(\theta)$  must be found from the given coordinates of the airfoil shape. In order not to interrupt the sequence of main ideas, the details of this problem are relegated to appendix B, with certain remarks on the practical achievement of a nearly circular contour.

**Transformation of contour in  $z'$ -plane to circle in  $z$ -plane.**—It is assumed now that the circular-like contour in the  $z'$ -plane which corresponds to the airfoil contour of the lattice is either given or determined; that is, the function  $\psi(\theta)$  is known in the boundary expression  $z'=ae^{i\theta}$ . By the procedure of reference 1 or 3, the transformation

$$z'=ze^{i\theta} \quad (9a)$$

where

$$f(z)=\sum_1^n c_n = \log \frac{z'}{z} \quad (9b)$$

and  $c_n$  are complex coefficients determined by the boundary, is then employed to transform the  $z'$ -contour into a circle  $z=ae^{i\theta}$  in the  $z$ -plane. The transformation (9a) keeps the regions alike at infinity in the  $z'$ - and  $z$ -planes; that is,  $z=z'$  and  $\frac{dz'}{dz}=1$  at infinity. The correspondence of the boundaries is determined by the functional equation

$$\begin{aligned} \phi-\theta &= \epsilon(\phi) \\ &= -\frac{1}{2\pi} \int_0^{2\pi} \Psi(\phi') \cot \frac{\phi'-\phi}{2} d\phi' \end{aligned} \quad (10)$$

for which a convenient numerical solution has been outlined in reference 3. The radius of the circle  $R=ae^{i\theta}$  is determined by the relation

$$\psi_0 = \frac{1}{2\pi} \int_0^{2\pi} \Psi(\phi') u_\phi \quad (11)$$

For consistency, the functional symbol  $\Psi(\phi)$  is here used to denote the quantity  $\psi$  expressed as a function of  $\phi$ —that is,  $\psi[\theta(\phi)]$ . In reference 3 the notations  $\psi(\phi)$  and  $\psi[\theta(\phi)]$  are used.

It is necessary also to trace the correspondence of the points  $z'=b$  and  $z'=-b$ . Let  $z=\beta_1$  correspond to  $z'=b$  and let  $z=-\beta_2$  correspond to  $z'=-b$ . The values  $\beta_1$  and  $\beta_2$  may be determined by a relation (due to Schwarz) that expresses the value of a complex function in terms of an integral of the real part of the function along a circle. A simple derivation of the desired relation is shown in appendix C. The expression is

$$\begin{aligned} \log \frac{z'}{z} &= f(z) \\ &= -\frac{1}{\pi} \int_0^{2\pi} \Psi(\phi) \frac{d\phi}{1-\frac{z}{R}e^{-i\phi}} \end{aligned} \quad (12)$$

The values of  $\beta_1$  and  $\beta_2$  may be determined from equation (12) by an iteration process that converges extremely rapidly. The process may be described as follows: In equation (12), let the zeroth approximation to  $\beta_1$  be  $z=z_0=b$  and let the corresponding value of  $z'$  be written  $z'=z_0'=be^{i\theta_0}$ , where  $f(b)$  is the evaluation of equation (12) for  $z=b$ . It is actually desired, however, to have  $z'=b$  but, because

$$z'=z_0'=b+z_0'-b$$

the initial value of  $z'$  differs from the desired value by  $z_0'-b$ . Furthermore,  $z=z_0$  differs from  $z=\beta_1$  by approximately the same amount; hence, reducing  $z_0$  by the quantity  $z_0'-b$  gives

$$\begin{aligned} z_1 &= z_0 + b - z_0' \\ &= b[2 - e^{i\theta_0}] \end{aligned}$$

which may be considered a first approximation to  $\beta_1$ . If it is desired to check this result or to obtain a second approximation, the process may be repeated; thus, from equation (12), find  $f(z_1)$  and

$$z_1' = z_1 e^{i\theta_1}$$

Then,

$$z_2 = z_1 + b - z_1'$$

which is a second approximation to  $\beta_1$  and, in general, the  $n$ th approximation is

$$z_n = z_{n-1} + b - z_{n-1}'$$

It is clear that, should  $z_n$  correspond to  $z_{n-1}$ ,  $z_{n-1}'$  must correspond to  $b$  and the process automatically stops. The numerical process is given in appendix C; relatively elementary steps are involved. In order to determine  $-\beta_2$ , the process is applied with  $b$  replaced by  $-b$ .

**Transformation to standard circle in  $w$ -plane.**—In order to obtain the flow pattern, it is desirable to introduce another function which transforms the circle in the  $z$ -plane into another circle in the  $w$ -plane in such a way that the characteristic points  $z = \beta_1$  and  $z = -\beta_2$  map into  $w = b$  and  $w = -b$ , respectively. The region of the circle in the  $w$ -plane may be considered the standard region. The desired transformation may be written as (see appendix D)

$$\frac{b-w}{b+w} = K \left( \frac{\beta_1 - z}{\beta_2 + z} \right) \quad (13)$$

where

$$K = \frac{b^2 - S^2 \beta_2 \bar{\beta}_1 + R^2}{b^2 + S^2 \beta_1 \bar{\beta}_1 - R^2} \quad (14)$$

and  $R = ae^{i\alpha}$  is the radius of the original circle in the  $z$ -plane,  $\bar{\beta}_1$  is the complex conjugate to  $\beta_1$ , and  $S$  is the radius of the new circle in the  $w$ -plane. The radius  $S$  is determined by

$$S = be^{-\gamma_1} \quad (15)$$

where  $\gamma_1$  is obtained from

$$\cosh \gamma_1 = \frac{1}{R} \left| \frac{R^2 + \beta_2 \beta_1}{\beta_1 + \beta_2} \right| \quad (16)$$

**Complex velocity potential in  $w$ -plane.**—Consider the flow function  $\Omega(w) = \Phi + i\Psi$ , which is defined as

$$\Omega(w) = -\frac{\Gamma d}{2\pi} \left( e^{i\alpha} \log \frac{b+w}{b-w} + e^{-i\alpha} \log \frac{w+\frac{S^2}{b}}{w-\frac{S^2}{b}} \right) - \frac{i\Gamma}{4\pi} \log \frac{w^2 - \frac{S^4}{b^2}}{b^2 - w^2} \quad (17)$$

The flow pattern may be regarded as due to a combination of singularities, sinks, sources, and vortices, placed at the points  $w = \pm b$  and  $w = \pm \frac{S^2}{b}$  as indicated in figure 3. It may

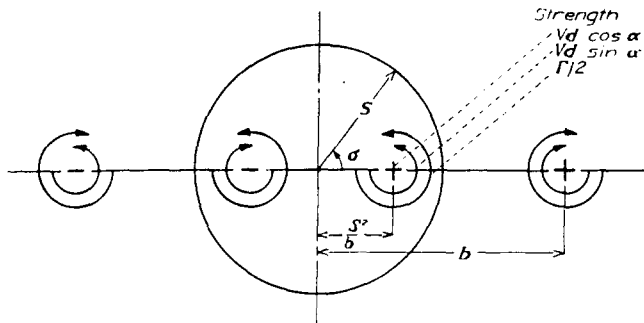


FIGURE 3.—Flow singularities in standard  $w$ -plane.

be readily verified that the circle of radius  $S$ —that is,  $w = Se^{i\alpha}$ —is part of a streamline and it may further be observed from figure 3 that the circulation around any contour which encloses the points  $w = \pm \frac{S^2}{b}$  and for which the points  $w = \pm b$  are exterior points is  $\Gamma$  (positive if counterclockwise). The parameter  $\alpha$  will be interpreted later as an angle of attack.

The value of the circulation  $\Gamma$  may be determined by means of the Kutta-Joukowski condition for smooth flow at the trailing edge of the lattice. Let  $\sigma_0$  be the value of  $\sigma$  on the boundary circle  $Se^{i\sigma}$  that corresponds to the trailing edge of the lattice. The Kutta-Joukowski condition then requires that the flow separate at  $\sigma = \sigma_0$ , or that a stagnation point exist there.

With  $\frac{d\Omega}{dw} = 0$  and  $w = Se^{i\sigma_0}$ , the following relation for  $\Gamma$  is found:

$$\Gamma = -\frac{4VSd}{b^2 - \frac{S^4}{b^2}} \left[ b \sin(\sigma_0 + \alpha) + \frac{S^2}{b} \sin(\sigma_0 - \alpha) \right] \quad (18)$$

If  $S/b$  is replaced by  $e^{-\gamma_1}$  (equation (15)), equation (18) may be expressed as

$$\Gamma = -2Vd \left( \frac{\cos \sigma_0}{\cosh \gamma_1} \sin \alpha + \frac{\sin \sigma_0}{\sinh \gamma_1} \cos \alpha \right) \quad (19)$$

**Expressions for velocity in lattice field.**—In order to obtain the flow pattern in the lattice field ( $\zeta$ -plane), the component factors of the following expression are required:

$$\frac{d\Omega}{d\zeta} = \frac{d\Omega}{dw} \frac{dw}{dz} \frac{dz}{dz'} \frac{dz'}{d\zeta} \quad (20)$$

These terms may be obtained from equations (17), (13), (9), and (6).

It is of particular interest to evaluate equation (20) explicitly for the regions at infinity in front of and behind the lattice and also on the lattice boundary itself. It is recalled that  $\zeta = \infty$  corresponds to  $z' = b$ ,  $z = \beta_1$ ,  $w = b$  and that  $\zeta = -\infty$  corresponds to  $z' = -b$ ,  $z = -\beta_2$ ,  $w = -b$ . By combining terms according to equation (20), the (reflected) inlet-velocity vector is obtained as

$$\begin{aligned} \left[ \frac{d\Omega}{d\zeta} \right]_{\infty} &= V_{z_1} - iV_{v_1} \\ &= -Ve^{i(\alpha+\beta)} - \frac{i\Gamma}{2d} e^{i\beta} \end{aligned} \quad (21)$$

and the corresponding expression for the outlet-velocity vector is

$$\begin{aligned} \left[ \frac{d\Omega}{d\zeta} \right]_{-\infty} &= V_{z_2} - iV_{v_2} \\ &= -Ve^{i(\alpha+\beta)} + \frac{i\Gamma}{2d} e^{i\beta} \end{aligned} \quad (22)$$

By addition of equations (21) and (22), it becomes clear that the velocity vector of magnitude  $V$  and angle of attack  $\alpha + \beta$  with respect to the  $x$ -axis is one-half the vector sum of the inlet and outlet velocities (fig. 4).

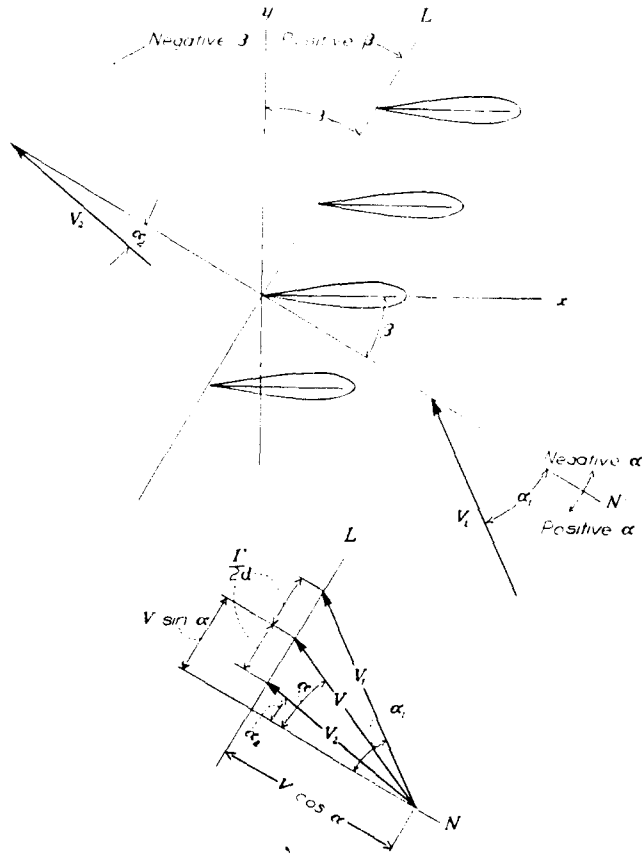


FIGURE 4.—Inlet, outlet, and mean velocity vectors and angles of attack.

If the angle of attack of the mean velocity vector with respect to the  $x$ -axis (chord direction) is denoted by  $\alpha_x = \alpha + \beta$ , the velocity components in equations (21) and (22) are

$$V_{x1} = -V \cos \alpha_x + \frac{\Gamma}{2d} \sin \beta$$

$$V_{y1} = -V \sin \alpha_x + \frac{\Gamma}{2d} \cos \beta$$

and

$$V_{x2} = -V \cos \alpha_x - \frac{\Gamma}{2d} \sin \beta$$

$$V_{y2} = V \sin \alpha_x - \frac{\Gamma}{2d} \cos \beta$$

The conventional angle of attack  $\alpha$  is measured with respect to the normal to the slant line of the lattice. The components normal to and along the slant line of the lattice, sometimes referred to as "axial" and "whirl" components, respectively, are found by rotating all vectors in the  $xy$ -plane

by angle  $\beta$  (fig. 4). These components are, for the inlet velocity,

$$V_{x1} = -V \cos \alpha$$

$$V_{y1} = V \sin \alpha + \frac{\Gamma}{2d}$$

and, for the outlet velocity,

$$V_{x2} = -V \cos \alpha = V_{x1}$$

$$V_{y2} = V \sin \alpha - \frac{\Gamma}{2d}$$

The squares of the magnitudes of the inlet and outlet velocities are

$$V_1^2 = V^2 \left[ 1 + 2 \frac{\Gamma}{2Vd} \sin \alpha + \left( \frac{\Gamma}{2Vd} \right)^2 \right]$$

$$V_2^2 = V^2 \left[ 1 - 2 \frac{\Gamma}{2Vd} \sin \alpha + \left( \frac{\Gamma}{2Vd} \right)^2 \right]$$

where  $\Gamma/2Vd$  may be obtained from equation (19). Observe that the inlet and outlet speeds are equal,  $V_1 = V_2$ , when  $\alpha = 0^\circ$  for any value of  $\Gamma$ . The inlet and outlet angles of attack with respect to the normal to the lattice line are

$$\alpha_1 = \tan^{-1} \frac{\sin \alpha + \frac{\Gamma}{2Vd}}{\cos \alpha}$$

$$\alpha_2 = \tan^{-1} \frac{\sin \alpha - \frac{\Gamma}{2Vd}}{\cos \alpha}$$

and the angle through which the stream is turned is

$$\alpha_1 - \alpha_2 = \tan^{-1} \frac{2 \frac{\Gamma}{2Vd} \cos \alpha}{1 - \left( \frac{\Gamma}{2Vd} \right)^2} \quad (23)$$

The component factors in equation (20) are now to be evaluated at the lattice boundary and, as the boundary itself is part of a streamline, only the magnitudes of the factors are of interest.

From equations (17) and (19) and with  $w = Se^{i\sigma}$ ,

$$\begin{aligned} \left| \frac{d\Omega}{dw} \right| &= \frac{2Vd}{\pi S} \frac{1}{\cosh 2\gamma_1 - \cos 2\sigma} [\sinh \gamma_1 \sin \alpha (\cos \sigma - \cos \sigma_0) \\ &\quad + \cosh \gamma_1 \cos \alpha (\sin \sigma - \sin \sigma_0)] \end{aligned} \quad (24)$$

where the parameter  $\gamma_1$  is defined in equation (15).

In order to obtain  $dw/dz$ , it is convenient first to express equation (13) explicitly in  $w$  as

$$w = \frac{b(1+K)z - b(K\beta_1 - \beta_2)}{(1-K)z + K\beta_1 + \beta_2} \quad (25a)$$

A standard form for the transformation of a circular region  $|z| \geq R$  into  $|w| \geq S$  is

$$w = RSe^{i\alpha} \frac{z - \delta}{R^2 - \bar{\delta}z} \quad (25b)$$

Comparison of equations (25a) and (25b) makes it clear that the complex parameter  $\delta$  and the real parameter  $\lambda$  may be obtained from the following relations:

$$\delta = \frac{K\beta_1 - \beta_2}{1 + K} \quad (26a)$$

or, as a check relation,

$$\bar{\delta} = \frac{R^2(K-1)}{K\beta_1 + \beta_2} \quad (26b)$$

and

$$\frac{S}{R} e^{\lambda} = \frac{(1+K)b}{K\beta_1 + \beta_2}$$

or, by equating angles on both sides,

$$\lambda = \arg(1+K) - \arg(K\beta_1 + \beta_2) \quad (27)$$

From equation (25b), the explicit correspondence of a point on the circle  $w = Se^{i\phi}$  to a point on the circle  $z = Re^{i\phi}$  can be obtained as follows:

$$e^i = e^{i(\phi+\lambda)} \frac{1 - \frac{\delta}{R} e^{-i\phi}}{1 - \frac{\bar{\delta}}{R} e^{i\phi}} \quad (28)$$

Let the complex number  $\sigma$  be expressed as  $|\delta|e^{i\tau}$  and let

$$1 - \frac{\delta}{R} e^{-i\phi} = me^{i\mu} \quad (29)$$

where

$$m(\phi) = 1 - 2 \frac{|\delta|}{R} \cos(\phi - \tau) + \frac{|\delta|^2}{R^2}$$

and

$$\mu(\phi) = \tan^{-1} \frac{\frac{|\delta|}{R} \sin(\phi - \tau)}{1 - \frac{|\delta|}{R} \cos(\phi - \tau)}$$

Observe that the denominator in equation (28) is the conjugate of equation (29) and is therefore equal to  $me^{-i\mu}$ . There results for the correspondence of  $\sigma$  and  $\phi$

$$\sigma = \phi + \lambda + 2\mu \quad (30)$$

In particular, if the (trailing-edge) value of  $\phi$  that corresponds to  $\theta_t$  as determined by equations (7) is written as  $\phi_0 = \theta_t + \epsilon_t$ , where  $\epsilon_t$  is the value of  $\epsilon(\phi)$  at  $\theta = \theta_t$  from equation (10), then

$$\sigma_0 = \phi_0 + \lambda + 2\mu_0$$

By differentiation of equation (25b),

$$\frac{dw}{dz} = \frac{RS(R^2 - \delta\bar{\delta})e^{i\lambda}}{(R^2 - \bar{\delta}z)^2} \quad (31)$$

On the boundary, put  $z = Re^{i\phi}$ ; then, the magnitude of equation (31) is

$$\left| \frac{dw}{dz} \right| = \frac{S}{R} \left( 1 - \frac{|\delta|^2}{R^2} \right) \frac{1}{m^2} \quad (32)$$

The expression for  $\left| \frac{dz'}{dz} \right|$  on the boundary is obtained from equation (9) in terms of the functions  $\epsilon(\phi)$  and  $\Psi(\phi)$  of equation (10) as follows (see reference 3):

$$\frac{dz'}{dz} = \frac{z'}{z} \left( 1 + z \frac{df}{dz} \right) \quad (33a)$$

and, because  $f(z)$  on the boundary is

$$f(z) = \Psi(\phi) - \psi_0 + i(\theta - \phi)$$

where

$$\theta - \phi = \epsilon(\phi)$$

then

$$\left| \frac{dz'}{dz} \right| = \left| \frac{z'}{z} \right| \left[ \left( 1 - \frac{d\epsilon}{d\phi} \right)^2 + \left( \frac{d\Psi}{d\phi} \right)^2 \right]^{1/2} \quad (33b)$$

The last factor of equation (20) is expressed from equation (6) on the boundary  $z' = ae^{i\psi + i\theta}$  as

$$\frac{d\xi}{dz'} = \frac{2d}{\pi} \frac{E}{D} \frac{1}{z'} \quad (34)$$

where

$$E = \left[ \cos^2 \beta \cosh^2 \gamma_0 (\cosh^2 \psi - \cos^2 \theta) + \sin^2 \beta \sinh^2 \gamma_0 (\cosh^2 \psi - \sin^2 \theta) - \frac{1}{4} \sin 2\beta \sinh 2\gamma_0 \sin 2\theta \right]^{1/2}$$

$$D = [\cosh 2\gamma_0 - \cosh 2(\psi + i\theta)] \\ = [(\cosh 2\gamma_0 - \cosh 2\psi \cos 2\theta)^2 + (\sinh 2\psi \sin 2\theta)^2]^{1/2}$$

Finally, combining in equation (21) the factors given in equations (24), (32), (33b), and (34) yields

$$\left| \frac{d\Omega}{d\xi} \right| = v \\ = ABCD \frac{1}{E} V \quad (35)$$

where

$$A = \frac{1}{\cosh 2\gamma_1 - \cos 2\sigma} [\sinh \gamma_1 \sin \alpha (\cos \sigma - \cos \sigma_0) + \cosh \gamma_1 \cos \alpha (\sin \sigma - \sin \sigma_0)]$$

$$B = \left( 1 - \frac{|\delta|^2}{R^2} \right) \frac{1}{m^2}$$

$$C = \left[ \left( 1 - \frac{d\epsilon}{d\phi} \right)^2 + \left( \frac{d\Psi}{d\phi} \right)^2 \right]^{-1/2}$$

$$D = [(\cosh 2\gamma_0 - \cosh 2\psi \cos 2\theta)^2 + (\sinh 2\psi \sin 2\theta)^2]^{1/2}$$

$$E = \left[ \cos^2 \beta \cosh^2 \gamma_0 (\cosh^2 \psi - \cos^2 \theta) + \sin^2 \beta \sinh^2 \gamma_0 (\cosh^2 \psi - \sin^2 \theta) - \frac{1}{4} \sin 2\beta \sinh 2\gamma_0 \sin 2\theta \right]^{1/2}$$

An application of equation (35) for the purpose of illustrating the various steps involved in a calculation of the surface velocity and pressure of the airfoil lattice is given in appendix E and illustrated in figures 5 and 6. For the sake of comparison, the single-airfoil case is given in figure 7.

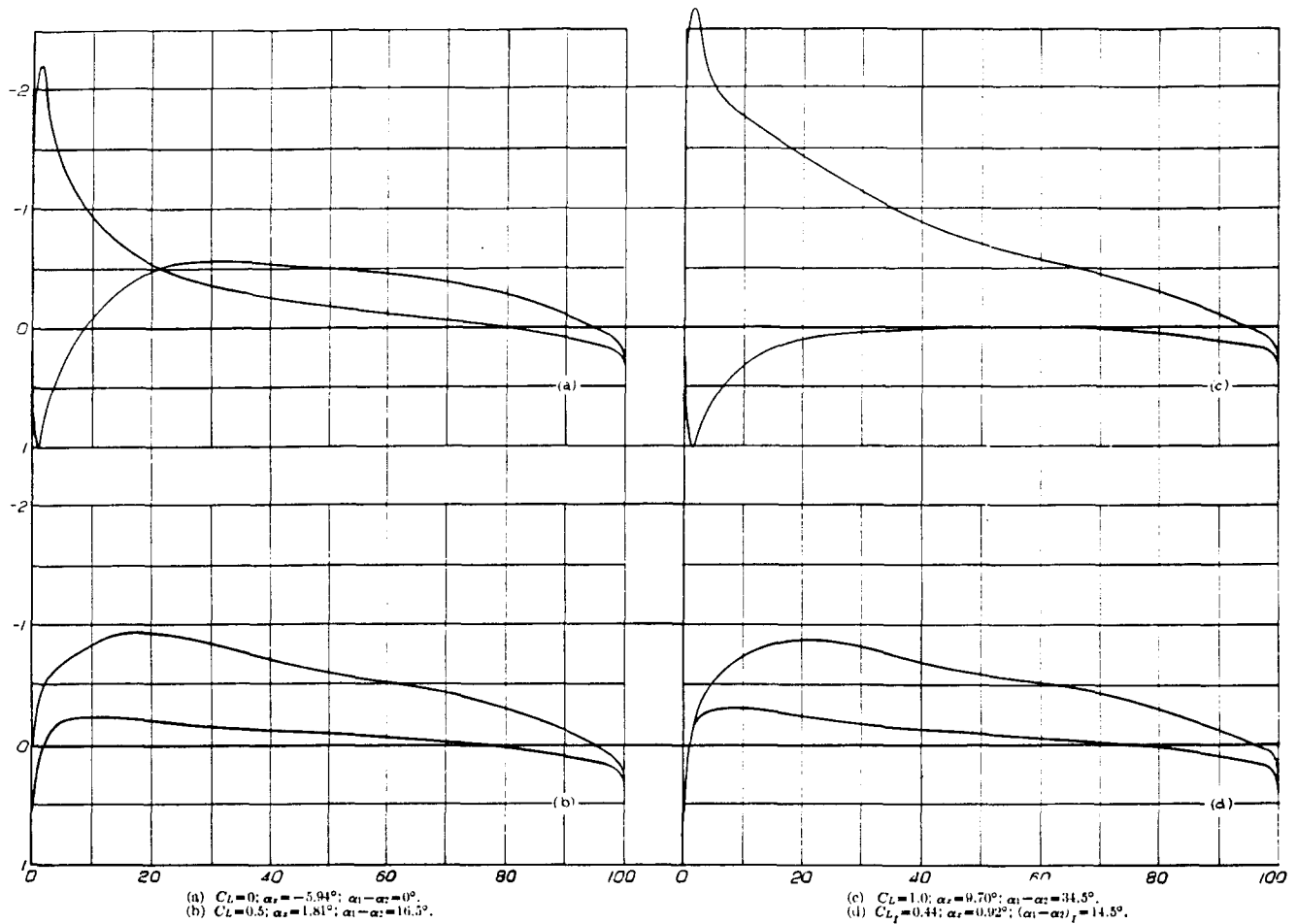


FIGURE 5.—Pressure distribution for NACA 4412 airfoil in a lattice arrangement. Stagger angle  $\beta = 0^\circ$ ; gap-chord ratio, 0.968; slope of lift curve  $\frac{dC_L}{d\alpha} = 3.71$ .

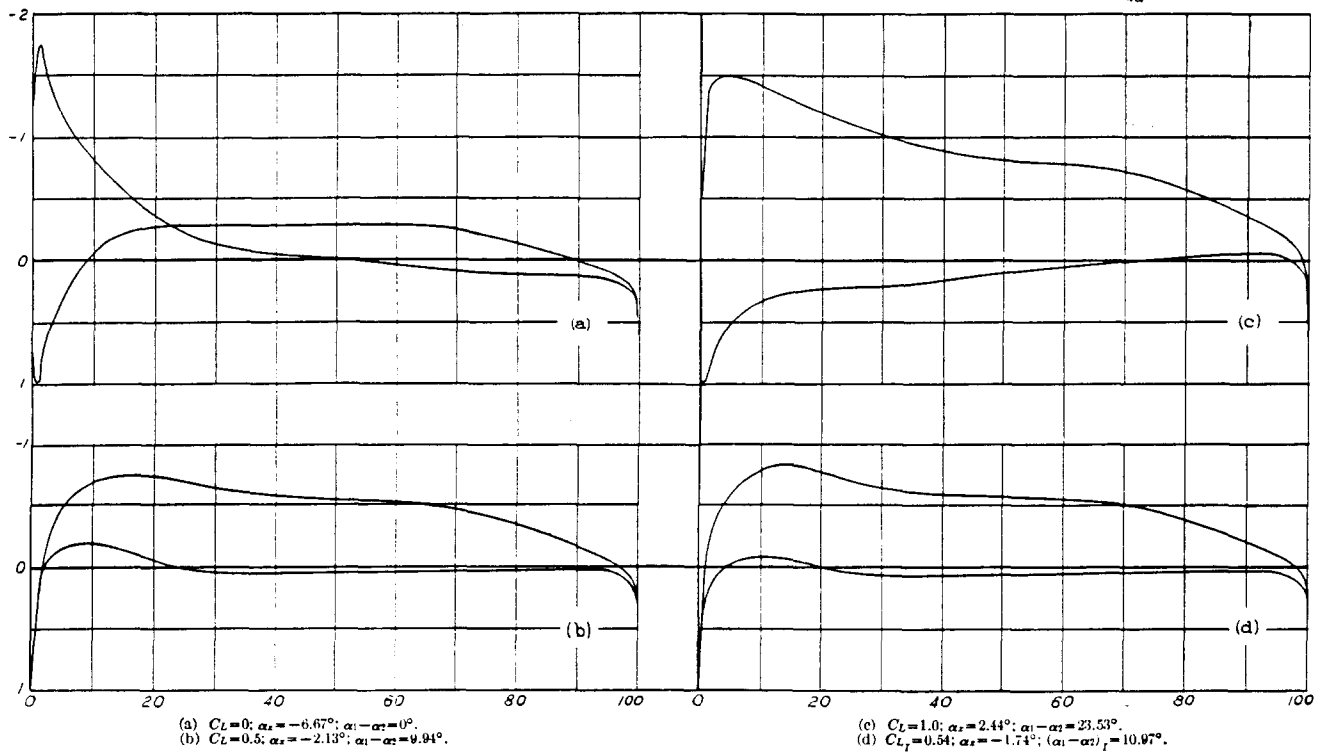


FIGURE 6.—Pressure distribution for NACA 4412 airfoil in a lattice arrangement. Stagger angle  $\beta = 45^\circ$ ; gap-chord ratio, 1.006; slope of lift curve  $\frac{dC_L}{d\alpha} = 6.31$ .

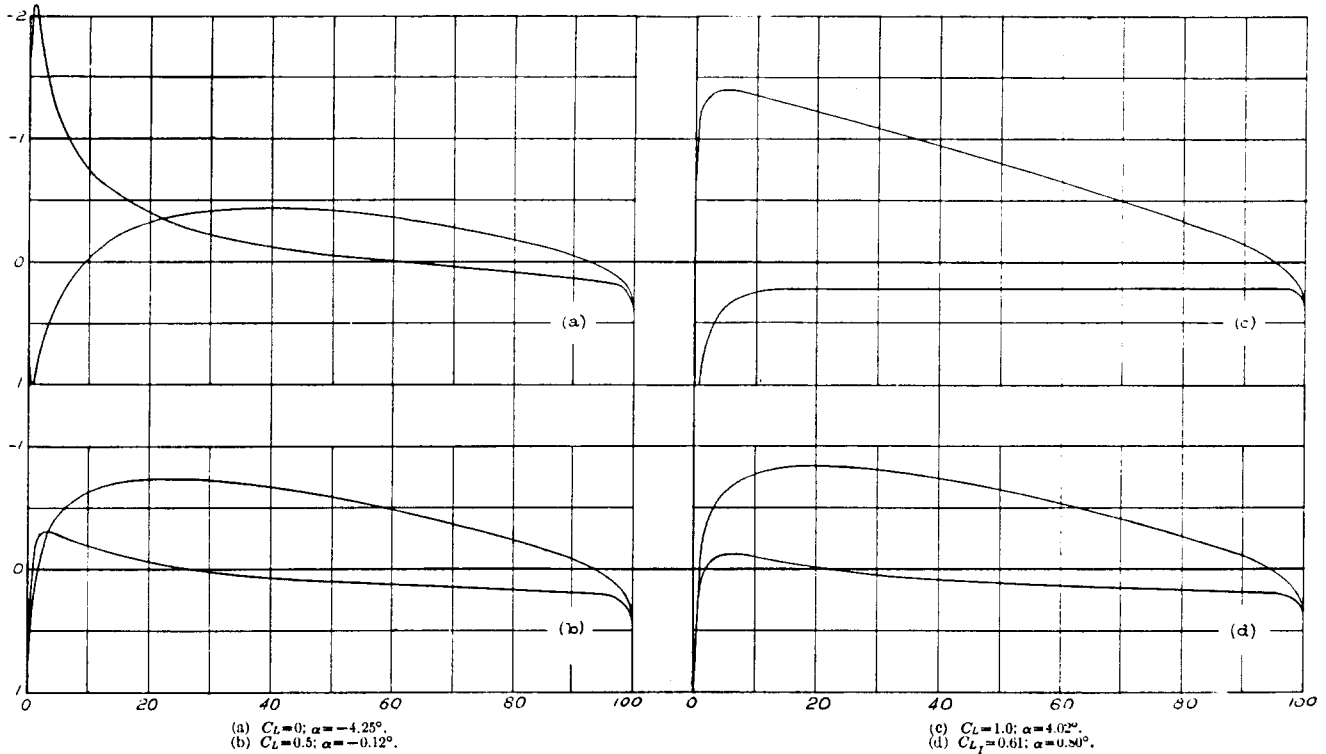


FIGURE 7.—Pressure distribution for NACA 4412 airfoil. Single-airfoil case, gap-chord ratio, infinite; slope of lift curve  $\frac{dC_L}{d\alpha} = 6.95$ .

Some special results from equation (35) for a lattice of lines.—In the case of a lattice of straight lines, the  $z'$ -,  $z$ -, and  $w$ -planes merge; hence  $\theta = \phi = \sigma$  and  $R = S = a$ .

From equations (19) and (7) and with  $\alpha + \beta = \alpha_r$ , which is the angle of attack with respect to the chord,

$$\frac{\Gamma}{2Vd} = \frac{\sin \alpha_r}{(\cosh^2 \gamma_0 - \sin^2 \beta)^{1/2}} \quad (36)$$

The lift per unit span on a single member of the lattice is given by

$$L = \rho V \Gamma$$

where  $\rho$  is the air density. The lift vector is perpendicular to the mean velocity vector (fig. 4). This result is general and not limited to a straight-line lattice. The lift coefficient is

$$C_L = \frac{\rho V \Gamma}{c \left( \frac{1}{2} \rho V^2 \right)} = \frac{2\Gamma}{cV} = 4 \frac{1}{c/d} \frac{\Gamma}{2Vd} \quad (37)$$

where  $\Gamma/2Vd$  is given in equation (36) and  $c/d$  can be found by equation (8).

The local velocity on the surface (equation (35)) becomes

$$v = V \left( \cos \alpha_r + \frac{N}{M} \sin \alpha_r \right) \quad (38)$$

where

$$N = \frac{1}{(\cosh^2 \gamma_0 - \sin^2 \beta)^{1/2}} + \frac{\cos \beta \cos \theta}{\cosh \gamma_0} + \frac{\sin \beta \sin \theta}{\sinh \gamma_0}$$

$$M = \frac{\cos \beta \sin \theta}{\sinh \gamma_0} - \frac{\sin \beta \cos \theta}{\cosh \gamma_0}$$

In the special cases in which  $\beta = 0^\circ$  and  $\beta = 90^\circ$ , the relations (36) to (38) are simpler.

For stagger angle  $\beta = 0^\circ$  and with  $d = g$ ,

$$\frac{\Gamma}{2Vg} = \frac{\sin \alpha_r}{\cosh \gamma_0}$$

From equation (8),

$$\cosh \gamma_0 = \coth \frac{\pi c}{2g}$$

and

$$L = 2\rho V^2 g \tanh \frac{\pi c}{2g} \sin \alpha_r$$

$$= \pi \rho c V^2 \frac{\tanh \frac{\pi c}{2g}}{\frac{\pi c}{2g}} \sin \alpha_r$$

The lift coefficient, according to equation (37), is

$$C_L = 2\pi \frac{\tanh \frac{\pi c}{2g}}{\frac{\pi c}{2g}} \sin \alpha_r$$

For  $\beta=0^\circ$ , therefore, the slope of the lift curve is always less than  $2\pi$ . Note that, for large gap,  $c/g \rightarrow 0$  and the lift coefficient is

$$C_L = 2\pi \sin \alpha_r$$

When the gap  $g$  is small compared with the chord  $c$ ,

$$C_L \rightarrow 4 \frac{g}{c} \sin \alpha_r$$

The local velocity at the surface, by equation (38), is

$$v = V \left( \cos \alpha_r + \tanh \gamma_0 \cot \frac{\theta}{2} \sin \alpha_r \right)$$

This result may be compared with that for the single-line airfoil ( $\gamma_0 = \infty$ )

$$v = V \left( \cos \alpha_r + \cot \frac{\theta}{2} \sin \alpha_r \right)$$

For stagger angle  $\beta=90^\circ$  and with  $d=h$ ,

$$\frac{\Gamma}{2Vh} = \frac{\sin \alpha_r}{\sinh \gamma_0}$$

From equation (8),

$$\sinh \gamma_0 = \cot \frac{\pi c}{2h}$$

and

$$\begin{aligned} L &= 2\rho V^2 h \tan \frac{\pi c}{2h} \sin \alpha_r \\ &= \pi \rho c V^2 \frac{\tan \frac{\pi c}{2h}}{\frac{\pi c}{2h}} \sin \alpha_r \end{aligned}$$

The lift coefficient, according to equation (37) is

$$C_L = 2\pi \frac{\tan \frac{\pi c}{2h}}{\frac{\pi c}{2h}} \sin \alpha_r$$

For  $\beta=90^\circ$ , therefore, the slope of the lift curve is always greater than  $2\pi$ . The local velocity at the surface is

$$v = V \left[ \cos \alpha_r + \coth \gamma_0 \cot \frac{1}{2} \left( \theta - \frac{\pi}{2} \right) \sin \alpha_r \right]$$

It may be noted in passing that, for  $c = \frac{1}{2}h$ ,

$$C_L = 8 \sin \alpha_r$$

as compared with

$$C_L = 2\pi \sin \alpha_r$$

for the single airfoil.

For the limiting case in which  $b$  and  $d$  approach  $\infty$ , the transformation (6) becomes

$$\zeta = \frac{d}{2\pi b} \left( z' e^{-i\theta} + \frac{a^2}{z' e^{-i\theta}} \right)$$

and, with limit  $\frac{d}{2\pi b} \rightarrow 1$  and a new variable  $z'' = z' e^{-i\theta}$

$$\zeta = z'' + \frac{a^2}{z''}$$

which is the familiar Joukowski transformation. If the variables  $\psi$  and  $\theta$  (equation (2)) are introduced, the corresponding result is expressed as

$$\zeta = 2a \cosh [\psi + i(\theta - \beta)]$$

where the limit, as  $\gamma_0 \rightarrow \infty$ , of  $\frac{d}{2\pi a \cosh \gamma_0}$  has been put equal to 1.

LANGLEY MEMORIAL AERONAUTICAL LABORATORY,  
NATIONAL ADVISORY COMMITTEE FOR AERONAUTICS,  
LANGLEY FIELD, VA., November 19, 1943

## APPENDIX A

### MAIN SYMBOLS

|   |   |
|---|---|
| <p><math>\zeta</math> complex plane of airfoil lattice (<math>x+iy</math>)</p> <p><math>\zeta_1, \zeta_2</math> complex planes of airfoil lattice for stagger angles <math>\beta=0^\circ</math> and <math>\beta=90^\circ</math>, respectively (<math>x_1+iy_1; x_2+iy_2</math>)</p> <p><math>z'</math> complex plane of circular-like contour (<math>ae^{\psi+i\theta}</math>)</p> <p><math>z</math> circle of radius <math>R=ae^{\psi_0}</math> in <math>z</math>-plane (<math>ae^{\psi_0+i\theta}</math>)</p> <p><math>w</math> circle of radius <math>S=be^{-\gamma_1}</math> in <math>w</math>-plane (<math>be^{-\gamma_1+i\theta}</math>)</p> <p><math>\zeta=\infty, z'=b, z=\beta_1, w=b</math> corresponding points</p> <p><math>\zeta=-\infty, z'=-b, z=-\beta_2, w=-b</math> corresponding points</p> <p><math>a, b</math> reference lengths</p> <p><math>\gamma_0</math> gap-chord parameter (<math>b=ae^{\gamma_0}</math>)</p> <p><math>\beta</math> stagger angle</p> <p><math>d</math> lattice spacing, or "slant" gap for any value of <math>\beta</math></p> | <p><math>g</math> lattice spacing, or gap for <math>\beta=0^\circ</math></p> <p><math>h</math> lattice spacing, or stagger for <math>\beta=90^\circ</math></p> <p><math>V</math> magnitude of mean of inlet- and outlet-velocity vectors (fig. 4)</p> <p><math>\alpha_r</math> angle of attack with respect to <math>x</math>-axis of mean velocity vector</p> <p><math>\alpha</math> angle of attack with respect to normal to slant line of lattice of mean velocity vector</p> <p><math>\alpha_1, \alpha_2</math> inlet and outlet angles of attack with respect to normal to slant line of lattice, respectively</p> <p><math>V_1, V_2</math> magnitudes of inlet and outlet velocities, respectively</p> |
|---|---|

## APPENDIX B

### INVERSION OF EQUATIONS (4) TO (6) AND CHOICE OF COORDINATES

It is desired to find from a given airfoil lattice in the  $\zeta$ -plane the contour defined by  $\psi(\theta)$  in the  $z'$ -plane. This problem corresponds to an inversion of equations (4) to (6) and can be exactly treated for the cases in which  $\beta=0^\circ$  and  $\beta=90^\circ$  (equations (4) and (5), respectively) but an iteration or successive-approximation method is required for equation (6). Furthermore, although the parameters  $g$  and  $h$  are fixed by the geometry of the lattice, a choice exists in the definition of the chords and the origin of coordinates. This choice is discussed following equation (B17).

**Stagger angle  $\beta=0^\circ$ .**—From equation (3), there is obtained

$$\cosh(\psi+i\theta) = \cosh \gamma_0 \tanh \frac{\pi}{g} \zeta_1 \quad (\text{B1})$$

Putting  $\zeta_1 = x_1 + iy_1$  and denoting the real and imaginary parts of equation (B1) by  $\xi_1$  and  $\eta_1$ , respectively, leads to

$$\left. \begin{aligned} \cosh \psi \cos \theta = \xi_1 &= \frac{\cosh \gamma_0 \sinh \frac{2\pi}{g} x_1}{\cosh \frac{2\pi}{g} x_1 + \cos \frac{2\pi}{g} y_1} \\ \sinh \psi \sin \theta = \eta_1 &= \frac{\cosh \gamma_0 \sin \frac{2\pi}{g} y_1}{\cosh \frac{2\pi}{g} x_1 + \cos \frac{2\pi}{g} y_1} \end{aligned} \right\} \quad (\text{B2})$$

The expressions containing  $x_1$  and  $y_1$  in equation (B2) are considered given since these quantities are known from the coordinates of the airfoil lattice. If  $\psi$  and  $\theta$  are eliminated successively,

$$\left. \begin{aligned} \left( \frac{\xi_1}{\cos \theta} \right)^2 - \left( \frac{\eta_1}{\sin \theta} \right)^2 &= 1 \\ \left( \frac{\xi_1}{\cosh \psi} \right)^2 + \left( \frac{\eta_1}{\sinh \psi} \right)^2 &= 1 \end{aligned} \right\} \quad \text{and} \quad (\text{B3})$$

From equation (B3), there result the following expressions, which serve to define the function  $\psi(\theta)$  in terms of the airfoil coordinates:

$$\left. \begin{aligned} \sin^2 \theta &= p + \sqrt{p^2 + \eta_1^2} \\ \sinh^2 \psi &= -p + \sqrt{p^2 + \eta_1^2} \end{aligned} \right\} \quad (\text{B4})$$

where

$$p = \frac{1}{2} (1 - \xi_1^2 - \eta_1^2)$$

For small values of  $\theta$ , the relation  $\sinh \psi = \frac{\eta_1}{\sin \theta}$  may be used.

It is useful for computational purposes to record the real and imaginary parts of equation (3)

$$\left. \begin{aligned} x_1 &= \frac{g}{2\pi} \left( \frac{1}{2} \log \frac{\rho_1^2}{\rho_2^2} \right) \\ y_1 &= \frac{g}{2\pi} (\phi_1 - \phi_2) \end{aligned} \right\} \quad (\text{B5})$$

where

$$\begin{aligned} \rho_1^2 &= (\cosh \gamma_0 + \cosh \psi \cos \theta)^2 + (\sinh \psi \sin \theta)^2 \\ \rho_2^2 &= (\cosh \gamma_0 - \cosh \psi \cos \theta)^2 + (\sinh \psi \sin \theta)^2 \end{aligned}$$



$$\sin \phi_1 = \frac{1}{\rho_1} \sinh \psi \sin \theta$$

$$\sin \phi_2 = -\frac{1}{\rho_2} \sinh \psi \sin \theta$$

The angles are to be chosen between  $-\pi$  and  $\pi$ , and the quadrants may be determined by noting also the relations

$$\cos \phi_1 = \frac{1}{\rho_1} (\cosh \gamma_0 + \cosh \psi \cos \theta)$$

$$\cos \phi_2 = \frac{1}{\rho_2} (\cosh \gamma_0 - \cosh \psi \cos \theta)$$

**Stagger angle**  $\beta = 90^\circ$ .—From equation (5), there is obtained

$$\sinh(\psi + i\theta) = \sinh \gamma_0 \tan \frac{\pi}{h} \zeta_2 \quad (\text{B6})$$

With  $\zeta_2 = x_2 + iy_2$  and the real and imaginary parts of equation (B6) denoted by  $\xi_2$  and  $\eta_2$ , respectively,

$$\left. \begin{aligned} \sinh \psi \cos \theta = \xi_2 &= \frac{\sinh \gamma_0 \sin \frac{2\pi}{h} x_2}{\cosh \frac{2\pi}{h} y_2 + \cos \frac{2\pi}{h} x_2} \\ \cosh \psi \sin \theta = \eta_2 &= \frac{\sinh \gamma_0 \sinh \frac{2\pi}{h} y_2}{\cosh \frac{2\pi}{h} y_2 + \cos \frac{2\pi}{h} x_2} \end{aligned} \right\} \quad (\text{B7})$$

If  $\psi$  and  $\theta$  are eliminated successively,

$$\left. \begin{aligned} \left( \frac{\xi_2}{\cos \theta} \right)^2 - \left( \frac{\eta_2}{\sin \theta} \right)^2 &= -1 \\ \left( \frac{\xi_2}{\sinh \psi} \right)^2 + \left( \frac{\eta_2}{\cosh \psi} \right)^2 &= 1 \end{aligned} \right\} \quad (\text{B8})$$

From equations (B8) there result finally the following expressions, which serve to define the function  $\psi(\theta)$  in terms of the airfoil coordinates:

$$\left. \begin{aligned} \cos^2 \theta &= q + \sqrt{q^2 + \xi_2^2} \\ \sinh^2 \psi &= -q + \sqrt{q^2 + \xi_2^2} \end{aligned} \right\} \quad (\text{B9})$$

where

$$q = \frac{1}{2} (1 - \xi_2^2 - \eta_2^2)$$

For values of  $\theta$  near  $\pm 90^\circ$ , the relation  $\sinh \psi = \frac{\xi_2}{\cos \theta}$  may be used.

It is useful for computational purposes to write the real and imaginary parts of equation (5)

$$\left. \begin{aligned} x_2 &= \frac{h}{2\pi} (\phi_3 - \phi_4) \\ y_2 &= -\frac{h}{2\pi} \left( \frac{1}{2} \log \frac{\rho_3^2}{\rho_4^2} \right) \end{aligned} \right\} \quad (\text{B10})$$

where

$$\rho_3^2 = (\sinh \gamma_0 + \sinh \psi \cos \theta)^2 + (\cosh \psi \sin \theta)^2$$

$$\rho_4^2 = (\sinh \gamma_0 - \sinh \psi \cos \theta)^2 + (\cosh \psi \sin \theta)^2$$

$$\sin \phi_3 = \frac{1}{\rho_3} \cosh \psi \sin \theta$$

$$\sin \phi_4 = -\frac{1}{\rho_4} \cosh \psi \sin \theta$$

The angles are to be chosen between  $-\pi$  and  $\pi$ , and the quadrants may be determined by noting also the relations

$$\cos \phi_3 = \frac{1}{\rho_3} (\sinh \gamma_0 + \sinh \psi \cos \theta)$$

$$\cos \phi_4 = \frac{1}{\rho_4} (\sinh \gamma_0 - \sinh \psi \cos \theta)$$

**Arbitrary stagger angle  $\beta$  and choice of coordinates.**—

Because of the transcendental nature of equation (6), a direct inversion expression seems unobtainable; however, the values  $(\psi, \theta)$  that correspond to coordinates  $(x, y)$  may be obtained without difficulty by an iterative process. For this purpose and for the purpose of choosing the coordinate axes, expansions of  $x_1, x_2, y_1,$  and  $y_2$  in powers of  $\psi$  are useful. The following expansions may be readily verified:

$$x_1 \approx \frac{d}{2\pi} \cos \beta \left[ \log \frac{\cosh \gamma_0 + \cos \theta}{\cosh \gamma_0 - \cos \theta} + \psi^2 \cosh \gamma_0 \cos \theta \frac{\sinh^2 \gamma_0 - \sin^2 \theta}{(\cosh^2 \gamma_0 - \cos^2 \theta)^2} + \dots \right] \quad (\text{B11a})$$

$$x_2 \approx \frac{d}{2\pi} \sin \beta \left[ 2 \tan^{-1} \frac{\sin \theta}{\sinh \gamma_0} + \psi^2 \sinh \gamma_0 \sin \theta \frac{\cosh^2 \gamma_0 + \cos^2 \theta}{(\cosh^2 \gamma_0 - \cos^2 \theta)^2} + \dots \right] \quad (\text{B11b})$$

$$y_1 \approx \frac{d}{2\pi} \cos \beta \frac{2 \cosh \gamma_0 \sin \theta}{\cosh^2 \gamma_0 - \cos^2 \theta} \psi \quad (\text{B11c})$$

$$y_2 \approx -\frac{d}{2\pi} \sin \beta \frac{2 \sinh \gamma_0 \cos \theta}{\cosh^2 \gamma_0 - \cos^2 \theta} \psi \quad (\text{B11d})$$

Then

$$\begin{aligned} y &= y_1 + y_2 \\ &\approx \frac{d}{\pi} \psi F(\theta) \end{aligned} \quad (\text{B12})$$

where

$$F(\theta) = \frac{\cosh \gamma_0 \cos \beta \sin \theta - \sinh \gamma_0 \sin \beta \cos \theta}{\cosh^2 \gamma_0 - \cos^2 \theta}$$

If the  $x$ -coordinate of the straight-line lattice, which is considered the skeleton of the airfoil lattice, is denoted by  $x_0$ , then  $x_0$  is given by the value of  $x = x_1 + x_2$  for  $\psi = 0$ , or

$$x_0 = \frac{d}{2\pi} \left( \cos \beta \log \frac{\cosh \gamma_0 + \cos \theta}{\cosh \gamma_0 - \cos \theta} + 2 \sin \beta \tan^{-1} \frac{\sin \theta}{\sinh \gamma_0} \right) \quad (\text{B13})$$

and

$$x \approx x_0 + \frac{d}{2\pi} \psi^2 G(\theta) \quad (\text{B14})$$

where

$$G(\theta) = \frac{\cosh \gamma_0 \cos \beta \cos \theta + \sinh \gamma_0 \sin \beta \sin \theta}{\cosh^2 \gamma_0 - \cos^2 \theta} \\ - \frac{(\cosh \gamma_0 \cos \beta \sin \theta - \sinh \gamma_0 \sin \beta \cos \theta) 2 \sin \theta \cos \theta}{(\cosh^2 \gamma_0 - \cos^2 \theta)^2} \\ = F'(\theta)$$

In particular, the leading- and trailing-edge points  $x=x_l$  and  $x=x_t$ , are determined by the values of  $\theta=\theta_l$  and  $\theta=\theta_t$  that may be obtained from equations (7b). Then,

$$x_t \approx x_{0_t} + \frac{d}{2\pi} \psi^2 G_0 \quad (\text{B15})$$

where

$$G_0 = Q \left( \frac{\cos^2 \beta}{\sinh^2 \gamma_0} + \frac{\sin^2 \beta}{\cosh^2 \gamma_0} \right)$$

and  $x_{0_t}$  denotes the leading edge of the line given by  $\psi=0$ . A similar expression holds for  $x_l$ .

From equation (B12), for constant  $\psi$ ,

$$\frac{\partial y}{\partial \theta} \approx \frac{d}{\pi} \psi F'(\theta) \\ = \frac{d}{\pi} \psi G(\theta)$$

In the neighborhood of the leading edge, therefore,

$$y \approx \frac{d}{\pi} \psi G_0 (\theta - \theta_l) \quad (\text{B16})$$

For  $x_0$  near  $x_{0_t}$ , there is obtained from equation (B13),

$$x_0 = x_{0_t} + (\theta - \theta_l) x_{0_t}' + \frac{(\theta - \theta_l)^2}{2} x_{0_t}'' + \dots$$

where the following relations are found to hold:

$$x_{0_t}' = \frac{d}{\pi} [F(\theta)]_{\theta=\theta_l} = 0 \\ x_{0_t}'' = \frac{d}{\pi} [-G(\theta)]_{\theta=\theta_l} = -\frac{d}{\pi} G_0$$

Hence,

$$x_0 \approx x_{0_t} - \frac{d}{2\pi} G_0 (\theta - \theta_l)^2$$

Then, from equation (B14),

$$x - x_{0_t} \approx x_0 - x_{0_t} + \frac{d}{2\pi} \psi^2 G(\theta) \\ \approx \frac{d}{2\pi} G_0 [ -(\theta - \theta_l)^2 + \psi^2 ]$$

It follows from equation (B16) that, for  $x=x_{0_t}$ ,

$$\theta - \theta_l \approx \psi$$

and

$$y = y_0 \approx \frac{d}{\pi} \psi^2 G$$

With this value of  $y_{0_t}$  and equation (B15),

$$\frac{y_{0_t}}{x_t - x_{0_t}} \approx 2$$

If the total ordinate for both upper and lower sides at  $x=x_{0_t}$  is denoted by  $y_t$ ,

$$\frac{y_t}{x_t - x_{0_t}} \approx 4 \quad (\text{B17})$$

This result leads to a simple and convenient way of choosing axes of coordinates in order that  $\psi(\theta)$  will behave smoothly at the edges, that is, that the value of  $\psi$  at the leading edge is approximately the mean of the values of  $\psi$  at nearby ordinates on the upper and lower surfaces. For a parabola the latus rectum, or ordinate through the focus, is four times the distance from the vertex to the focus. Equation (B17) states that the end point of the skeleton chord should be approximately the focus of a parabola at the nose.

The scheme for choice of axes is as follows: Locate a point  $F$  near the leading edge where the ordinate through  $F$  is four times the distance of  $F$  from the leading edge. Similarly locate a point  $F'$  near the trailing edge. The origin of coordinates then bisects the line  $FF'$ , which is on the  $x$ -axis and represents the chord of the skeleton line airfoil  $\psi=0$ . (To the order of approximation employed, the aforementioned choice of axes coincides with that given for the single wing section in reference 1 or 3.)

**Procedure for finding  $(\psi, \theta)$  from  $(x, y)$  for arbitrary stagger angle  $\beta$ .**—An iterative procedure is given herein for finding  $\psi(\theta)$  from  $(x, y)$  for arbitrary  $\beta$ , in which the knowledge of the case for  $\beta=0^\circ$  is employed to help in formulating the initial approximation. In brief, values of  $\theta$  are obtained for stagger angle  $\beta=0^\circ$  for both the airfoil and its line skeleton. Values of  $\theta$  are then found for the skeleton, in the case of stagger angle  $\beta$ . These functions permit approximate values of  $\theta$  to be found for the airfoil, for stagger angle  $\beta$ . Equation (B12) then enables approximate values of  $\psi$  to be obtained. These values of  $(\psi, \theta)$  are then readily checked and improved, if necessary. The steps are as follows:

(1) Choose the axes as outlined and express the airfoil coordinates in percent chord, where the chord for this purpose is the part of the  $x$ -axis intercepted by the airfoil. Denote the coordinates thus obtained by  $(x_p, y_p)$ . Find  $k=FF'$  in percent chord. Find  $x_l-x_{0_t}$ , the distance from the leading edge to  $F$  in percent chord, and denote this value by  $e$ . Obtain the ratio  $c/d$ , where  $c$  means here  $FF'$  and  $d$  is the spacing between corresponding points on adjacent airfoils of the lattice. Find conversion factor  $m$  by

$$m = 2\pi \frac{c}{d} \frac{1}{k}$$

(2) Convert coordinates of the airfoil from  $(x_p, y_p)$  to  $(2\pi \frac{x}{d}, 2\pi \frac{y}{d})$  as follows:

$$2\pi \frac{x}{d} = m \left( e + \frac{k}{2} - x_p \right)$$

$$2\pi \frac{y}{d} = m y_p$$

(3) Find the parameter  $\gamma_0$  that corresponds to the determined value of  $c/d$  for the given value of  $\beta$  from graph or by calculation (equation (8)). Also find for later use the value of  $c/g$  corresponding to this value of  $\gamma_0$  for  $\beta=0^\circ$ .

(4) Consider, for this value of  $\gamma_0$ , the two straight-line cases ( $\psi=0, \beta=0^\circ$ ) and ( $\psi=0, \beta=\beta$ ); associate values of  $\theta=\theta_0$  for  $\beta=0^\circ$  with values  $\theta=\theta_\beta$  for the stagger angle  $\beta$  by referring associated values of  $\theta$  to geometrically similar points of the lines (equation (B13)).

(5) Multiply coordinates in step (2) by the ratio  $\frac{(c/g)_0}{(c/d)_\beta}$  where the chord-gap values are from step (3) for  $\beta=0^\circ$  and for  $\beta=\beta$ . Using equation (B4), find values of  $\theta$  for  $\beta=0^\circ$ .

(6) With the aid of step (4) obtain approximate values of  $\theta_3$  associated with the values of  $\theta$  obtained in step (5). Then, with  $\theta=\theta_3$ , use equation (B12) to obtain an approximate value of  $\psi$ , where

$$\psi = \frac{2\pi y}{d} \frac{F(\theta)}{2}$$

and the leading- and trailing-edge values of  $\psi$  are obtained from equation (B15).

(7) Calculate, from equations (B5) and (B10), exact values of  $(2\pi \frac{x}{d}, 2\pi \frac{y}{d})$ , associated with the initial values of  $(\psi, \theta)$  in step (6) where  $x=x_1+x_2$  and  $y=y_1+y_2$ .

(8) If, on comparison of the coordinates in step (7) with the coordinates in step (2), it is deemed necessary to approximate  $(\psi, \theta)$  more closely for several of the points  $(x, y)$ , one procedure is the following: An expression for  $\frac{d\zeta}{d(\psi+i\theta)}$  can be found from equations (4) to (6) as

$$\begin{aligned} \frac{d\zeta}{d(\psi+i\theta)} = & \frac{d}{2\pi} \cos \beta \left[ \frac{\sinh(\psi+i\theta)}{\cosh \gamma_0 + \cosh(\psi+i\theta)} + \frac{\sinh(\psi+i\theta)}{\cosh \gamma_0 - \cosh(\psi+i\theta)} \right] \\ & - i \frac{d}{2\pi} \sin \beta \left[ \frac{\cosh(\psi+i\theta)}{\sinh \gamma_0 + \sinh(\psi+i\theta)} + \frac{\cosh(\psi+i\theta)}{\sinh \gamma_0 - \sinh(\psi+i\theta)} \right] \end{aligned}$$

With the notation of equations (B5) and (B10), this expression may be written

$$\begin{aligned} \frac{d\left(\zeta \frac{2\pi}{d}\right)}{d(\psi+i\theta)} = & p+iq \\ = & \cos \beta \sinh(\psi+i\theta) \left( \frac{1}{\rho_1} e^{-i\phi_1} + \frac{1}{\rho_2} e^{-i\phi_2} \right) \\ & - i \sin \beta \cosh(\psi+i\theta) \left( \frac{1}{\rho_3} e^{-i\phi_3} + \frac{1}{\rho_4} e^{-i\phi_4} \right) \end{aligned}$$

where

$$\begin{aligned} p = & \cos \beta \left[ \sinh \psi \cos \theta \left( \frac{\cos \phi_1}{\rho_1} + \frac{\cos \phi_2}{\rho_2} \right) \right. \\ & \left. + \cosh \psi \sin \theta \left( \frac{\sin \phi_1}{\rho_1} + \frac{\sin \phi_2}{\rho_2} \right) \right] \\ & + \sin \beta \left[ \sinh \psi \sin \theta \left( \frac{\cos \phi_3}{\rho_3} + \frac{\cos \phi_4}{\rho_4} \right) \right. \\ & \left. - \cosh \psi \cos \theta \left( \frac{\sin \phi_3}{\rho_3} + \frac{\sin \phi_4}{\rho_4} \right) \right] \end{aligned}$$

and

$$\begin{aligned} q = & \cos \beta \left[ \cosh \psi \sin \theta \left( \frac{\cos \phi_1}{\rho_1} + \frac{\cos \phi_2}{\rho_2} \right) \right. \\ & \left. - \sinh \psi \cos \theta \left( \frac{\sin \phi_1}{\rho_1} + \frac{\sin \phi_2}{\rho_2} \right) \right] \\ & - \sin \beta \left[ \cosh \psi \cos \theta \left( \frac{\cos \phi_3}{\rho_3} + \frac{\cos \phi_4}{\rho_4} \right) \right. \\ & \left. + \sinh \psi \sin \theta \left( \frac{\sin \phi_3}{\rho_3} + \frac{\sin \phi_4}{\rho_4} \right) \right] \end{aligned}$$

The following relation may then be noted:

$$\Delta\psi + i\Delta\theta \approx \frac{\Delta\left(\frac{2\pi x}{d}\right) + i\Delta\left(\frac{2\pi y}{d}\right)}{p+iq} \quad (\text{B18})$$

Let

$$\Delta\left(\frac{2\pi x}{d}\right) = \left(\frac{2\pi x}{d}\right)_0 - \left(\frac{2\pi x}{d}\right)_1$$

$$\Delta\left(\frac{2\pi y}{d}\right) = \left(\frac{2\pi y}{d}\right)_0 - \left(\frac{2\pi y}{d}\right)_1$$

where the subscripts 0 and 1 refer to the coordinates given in steps (2) and (7), respectively. If the values  $(\psi, \theta)$  obtained in step (6) are used, evaluation of equation (B18) gives values  $(\Delta\psi, \Delta\theta)$ , and  $(\psi + \Delta\psi, \theta + \Delta\theta)$  represents the next approximation to the desired coordinates. The process in steps (7) and (8) can be repeated if deemed necessary.

## APPENDIX C

## DERIVATION OF EQUATION (12)

The transformation (equation (9)) from the  $z'$ - to the  $z$ -plane may be rewritten

$$\begin{aligned} \log \frac{z'}{z} &= f(z) \\ &= \sum_1^{\infty} \frac{c_n}{z^n} \end{aligned} \quad (C1)$$

where the complex constants  $c_n$  may be defined as

$$c_n = a_n + ib_n$$

On the boundaries,  $z' = ae^{\psi+i\theta}$  and  $z = ae^{\psi_0+i\phi}$ ; hence,

$$\log \frac{z'}{z} = \psi - \psi_0 + i(\theta - \phi)$$

and

$$\psi - \psi_0 = \sum_1^{\infty} \left( \frac{a_n}{R^n} \cos n\phi + \frac{b_n}{R^n} \sin n\phi \right) \quad (C2)$$

where

$$R = ae^{\psi_0}$$

With  $\psi$  considered as a function of  $\phi$  denoted by  $\Psi(\phi)$ , the coefficients in equation (C2) are obtained as

$$\left. \begin{aligned} \frac{a_n}{R^n} &= \frac{1}{\pi} \int_0^{2\pi} \Psi(\phi) \cos n\phi \, d\phi \\ \frac{b_n}{R^n} &= \frac{1}{\pi} \int_0^{2\pi} \Psi(\phi) \sin n\phi \, d\phi \\ \frac{c_n}{R^n} &= \frac{1}{\pi} \int_0^{2\pi} \Psi(\phi) e^{in\phi} \, d\phi \end{aligned} \right\} \quad (C3)$$

Substituting equation (C3) in equation (C1) yields

$$f(z) = \frac{1}{\pi} \int_0^{2\pi} \Psi(\phi) \sum_1^{\infty} \frac{R^n e^{in\phi}}{z^n} \, d\phi \quad (C4)$$

For  $\left| \frac{R}{z} \right| < 1$ , the geometric series in equation (C4) can be summed and

$$f(z) = \frac{1}{\pi} \int_0^{2\pi} \Psi(\phi) \frac{R e^{i\phi}}{z - R e^{i\phi}} \, d\phi \quad (C5)$$

which can immediately be expressed as in equation (12).

For computational purposes, equation (12) may be separated into real and imaginary parts. Let  $f(z) = p + iq$  and  $z = x + iy$  (where, for example, in the zeroth approximation  $x = b, y = 0$ ). Then,

$$p = \frac{1}{\pi} \int_0^{2\pi} \Psi(\phi) \frac{N_1}{D} \, d\phi$$

$$q = \frac{1}{\pi} \int_0^{2\pi} \Psi(\phi) \frac{N_2}{D} \, d\phi$$

where

$$N_1 = \frac{x}{R} \cos \phi + \frac{y}{R} \sin \phi - 1$$

$$N_2 = \frac{x}{R} \sin \phi - \frac{y}{R} \cos \phi$$

$$D = 1 - 2 \left( \frac{x}{R} \cos \phi + \frac{y}{R} \sin \phi \right) + \frac{x^2 + y^2}{R^2}$$

and the integrations can be conveniently performed by Simpson's rule.

## APPENDIX D

TRANSFORMATION FROM  $z$ -PLANE TO  $w$ -PLANE

The linear fractional transformation

$$w = \frac{az + b}{cz + d}$$

on which the derivation of equation (13) is based, has the following well-known properties:

- (1) When  $z$  traverses a circle  $C_z$ ,  $w$  traverses a circle  $C_w$ .
- (2) Two points  $w_1$  and  $w_2$  inverse with respect to a circle  $C_w$  correspond to two points  $z_1$  and  $z_2$  inverse with respect to the circle  $C_z$ .
- (3) The anharmonic ratio of four points is preserved; that is, if  $z_1, z_2, z_3$ , and  $z_4$  correspond to  $w_1, w_2, w_3$ , and  $w_4$ ,

$$\frac{(z_1 - z_4)(z_2 - z_3)}{(z_1 - z_2)(z_3 - z_4)} = \frac{(w_1 - w_4)(w_2 - w_3)}{(w_1 - w_2)(w_3 - w_4)}$$

For the desired correspondence it is known that four points  $w_1 = b, w_2 = -b$ , and their inverse points  $w_3 = \frac{S^2}{b}, w_4 = \frac{-S^2}{b}$  are to correspond to  $z_1 = \beta_1, z_2 = -\beta_2$  and their inverse points  $z_3 = \frac{R^2}{\beta_1}, z_4 = \frac{-R^2}{\beta_2}$ . Property (3) yields a relation that may be used to solve for the radius  $S$  and that can be expressed by equations (15) and (16). When the radius of the circle in the  $w$ -plane has been determined, property (3) can again be used by replacing—say,  $w_4$  by  $w$  and  $z_4$  by  $z$ . This procedure will yield a result that is equivalent to equation (13).

## APPENDIX E

## OUTLINE OF CALCULATION PROCEDURE

- (1) List airfoil-section coordinates in percent chord.
- (2) Choose axes (appendix B, paragraph following equation (B17)).
- (3) List stagger angle  $\beta$  and find  $\gamma_0$  and value of  $c/d$  for the skeleton line lattice (table I, fig. 2, and equation (8)).
- (4) Find  $(\psi, \theta)$  (appendix B).
- (5) Find  $\epsilon(\phi)$  (equation (10)) by method given in appendix of reference 3.
- (6) Plot  $\psi$  against  $\phi$  where  $\phi = \theta + \epsilon$ . Find constant  $\psi_0$  (equation (11)) and  $R = ac^{i\psi_0}$ .
- (7) Find complex constants  $\beta_1$  and  $\beta_2$  (equation (12) and appendix C).
- (8) Find constants  $\cosh \gamma_1$ ,  $\gamma_1$ ,  $S$ , and  $K = k_1 + ik_2$  (equations (16), (15), and (14)).
- (9) Find complex constant  $\delta = \delta_1 e^{i\theta}$  (equation (26)) and real constant  $\lambda$  (equation (27)). Also obtain functions  $m(\phi)$  and  $\mu(\phi)$  from equation (29).
- (10) Find  $\sigma$  and, in particular,  $\sigma_0$  (equation (30)).
- (11) Evaluate factors  $B$ ,  $C$ ,  $D$ , and  $E$  (equation (35)).
- (12) Evaluate factor  $A$  in equation (35), first choosing the angle of attack  $\alpha$  as indicated in the following paragraphs:  
The lift coefficient is as in equation (37)

$$C_L = 4 \frac{1}{c/d} \frac{\Gamma}{2Vd} = 2 \frac{d}{c} \frac{V_{L_1} - V_{L_2}}{V}$$

Here  $c/d$  refers to the value of  $x/d$  at 0 percent chord minus  $x/d$  at 100 percent chord. By using equation (19) for  $\Gamma/2Vd$ ,  $C_L$  may be expressed as

$$C_L = H \sin(\alpha + \eta) \quad (\text{E1})$$

where

$$H = 4 \frac{d}{c} \left[ \left( \frac{\cos \sigma_0}{\cosh \gamma_1} \right)^2 + \left( \frac{\sin \sigma_0}{\sinh \gamma_1} \right)^2 \right]^{1/2}$$

and

$$\eta = \tan^{-1} \left( \frac{\sin \sigma_0 \cosh \gamma_1}{\cos \sigma_0 \sinh \gamma_1} \right)$$

This relation may be used to find  $\alpha$  for any desired value of  $C_L$  and it is further noted that  $\alpha = -\eta$  is the angle of zero lift.

The "ideal" angle of attack, introduced by Theodorsen, is defined for a thin section as the angle of attack for which a stagnation point exists not only at the sharp trailing edge but also at the sharp leading edge. For thick airfoils, the ideal angle of attack is defined in the same manner (the pressure difference at the leading edge vanishes) although the point that is considered the leading-edge point is not precisely defined. If this point is taken to be the intersection of the  $x$ -axis with the airfoil leading edge, the ideal lift and ideal angle of attack are found as follows: Let  $\sigma_1$  be the value of  $\sigma$  corresponding to the leading-edge point. The quantity  $\left| \frac{d\Omega}{dw} \right|$  in equation (24) (or the factor  $A$  in equation (35))

vanishes for  $\sigma = \sigma_1$ . The relation that gives the value of the ideal angle of attack  $\alpha = \alpha_I$  is then

$$\frac{\sin \alpha}{\cos \alpha} = - \frac{\cosh \gamma_1 \sin \sigma_1 - \sin \sigma_0}{\sinh \gamma_1 \cos \sigma_1 - \cos \sigma_0}$$

and the ideal lift coefficient, from equation (E1), is

$$C_{L_I} = -4 \frac{d}{c} \frac{1}{J} \cos \frac{1}{2}(\sigma_1 - \sigma_0)$$

where

$$J^2 = \left[ \cosh \gamma_1 \cos \frac{1}{2}(\sigma_1 + \sigma_0) \right]^2 + \left[ \sinh \gamma_1 \sin \frac{1}{2}(\sigma_1 + \sigma_0) \right]^2$$

(13) The surface velocity ratio  $v/V$  is now found from equation (35) and the (mean) superstream pressure is found from Bernoulli's equation as

$$\frac{p}{q} = 1 - \left( \frac{v}{V} \right)^2$$

The angle through which the stream is turned may be found from equation (23).

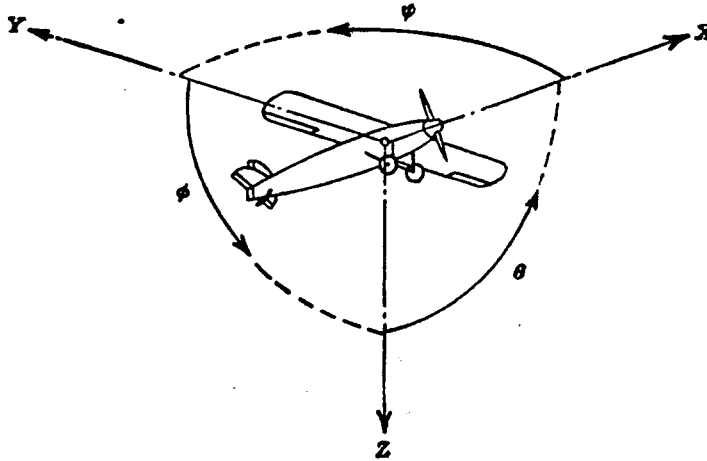
A remark may be inserted here regarding an inverse calculation procedure. Instead of starting with a given lattice, it may be convenient to start with given function  $\Psi(\phi)$ , (quantity  $\psi$  as a function of  $\phi$ ) and given parameters  $\gamma_0$  and  $\beta$ . Then both the lattice arrangement and the flow properties follow uniquely and, in this way, systematic families of lattices can be studied.

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- Other references are given in the foregoing papers; for example, Weinig lists more than 50 references published prior to 1935.



Positive directions of axes and angles (forces and moments) are shown by arrows

| Axis              |        | Force (parallel to axis) symbol | Moment about axis |        |                    | Angle       |        | Velocities                    |         |
|-------------------|--------|---------------------------------|-------------------|--------|--------------------|-------------|--------|-------------------------------|---------|
| Designation       | Symbol |                                 | Designation       | Symbol | Positive direction | Designation | Symbol | Linear (component along axis) | Angular |
| Longitudinal..... | X      | X                               | Rolling.....      | L      | Y → Z              | Roll.....   | φ      | u                             | p       |
| Lateral.....      | Y      | Y                               | Pitching.....     | M      | Z → X              | Pitch.....  | θ      | v                             | q       |
| Normal.....       | Z      | Z                               | Yawing.....       | N      | X → Y              | Yaw.....    | ψ      | w                             | r       |

Absolute coefficients of moment

$$C_l = \frac{L}{qbS} \quad C_m = \frac{M}{qcS} \quad C_n = \frac{N}{qbS}$$

(rolling)      (pitching)      (yawing)

Angle of set of control surface (relative to neutral position), δ. (Indicate surface by proper subscript.)

#### 4. PROPELLER SYMBOLS

*D* Diameter  
*p* Geometric pitch  
*p/D* Pitch ratio  
*V'* Inflow velocity  
*V<sub>s</sub>* Slipstream velocity

*T* Thrust, absolute coefficient  $C_T = \frac{T}{\rho n^2 D^4}$   
*Q* Torque, absolute coefficient  $C_Q = \frac{Q}{\rho n^2 D^5}$

*P* Power, absolute coefficient  $C_P = \frac{P}{\rho n^3 D^5}$

*C<sub>s</sub>* Speed-power coefficient =  $\sqrt[5]{\frac{\rho V_s^3}{P n^3}}$

*η* Efficiency

*n* Revolutions per second, rps

*φ* Effective helix angle =  $\tan^{-1}\left(\frac{V}{2\pi r n}\right)$

#### 5. NUMERICAL RELATIONS

1 hp = 76.04 kg-m/s = 550 ft-lb/sec  
 1 metric horsepower = 0.9863 hp  
 1 mph = 0.4470 mps  
 1 mps = 2.2369 mph

1 lb = 0.4536 kg  
 1 kg = 2.2046 lb  
 1 mi = 1,609.35 m = 5,280 ft  
 1 m = 3.2808 ft

**TITLE:** On the Plane Potential Flow Past a Lattice of Arbitrary Airfoils

**AUTHOR(S):** Garrick, I. E.

**ORIGINATING AGENCY:** National Advisory Committee for Aeronautics, Washington, D. C.

|                        |                               |                         |                         |                    |   |
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| <b>DATE</b><br>Jan '44 | <b>DOC. CLASS</b><br>Unclass. | <b>COUNTRY</b><br>U. S. | <b>LANGUAGE</b><br>Eng. | <b>PAGES</b><br>49 | <b>ABSTRACTS</b><br>tables, graphs, drwgs |
|------------------------|-------------------------------|-------------------------|-------------------------|--------------------|---|

**ABSTRACT:**

Theoretical treatment of two-dimensional, incompressible, potential flow has a purely mathematical interest besides its practical application to turbine blades and wind-tunnel grids. Conformal mapping is used to study this flow pattern which consists of velocity and pressure fields. Regions infinitely in front of and behind airfoil lattice are treated along with expressions for flow at airfoil boundary. An illustrative numerical example is included.

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ABSTRACT:

The two-dimensional, incompressible potential flow past a lattice of airfoils of arbitrary shape is investigated. The problem is treated by usual methods of conformal mapping in several stages, one stage corresponding to the mapping of the framework of the arbitrary line lattice and another significant stage corresponding to the Theodoresen method for the mapping of the arbitrary single wing profile into a circle. A particular feature in the theoretical treatment is the special handling of the regions at an infinite distance in front of and behind the lattice. Expressions are given for evaluation of the velocity and pressure distribution of the airfoil boundary.

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