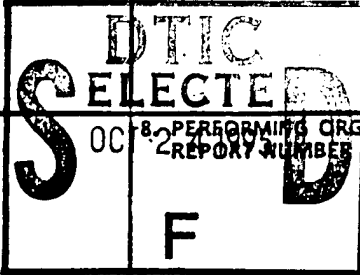


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FINAL TECHNICAL REPORT

Paul T. Inglefield

22 September 1995

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STATEMENT OF THE PROBLEM.

Epoxy resins containing the bisphenol-A unit are among the most commonly employed crosslinked or network polymer systems. These materials display significant relaxations below the glass transition. These sub-glass transition relaxations of bisphenol-A based epoxide resins have been widely studied by dynamic mechanical response¹⁻¹⁶, dielectric response¹⁷⁻¹⁸ and by solid state NMR¹⁹⁻²². In both the mechanical and dielectric studies, the principal low temperature loss peak (the β peak) is quite broad and lies between -80 and -40 °C at a frequency of 1 Hz. The effects of crosslink density and changes in chemical structure on the β peak have been studied.

The interpretation of the main loss peak in terms of a molecular level motion remains unclear. One group of investigators^{6-7,23} has attributed this loss to motion of the diphenylpropane unit, specifically phenylene group rotation¹⁹. Others attribute the relaxation to motion of the hydroxyether groups^{3-4,8-12,22,24} while some of the more recent mechanical studies feel the β peak is a composite of motions of both of these units^{8,13-17}. According to this latter interpretation, the low temperature side (-110 to -80°C) of the β peak arises from motion of the phenylene groups in the diphenyl propane and the high temperature side of the β peak arises from the motion of the hydroxyether groups (- 70 to -55 °C). To the current authors, the literature is not definitive on the molecular sources of the sub-glass transition motion. It is difficult to establish the molecular origin of a mechanical loss by observing changes in mechanical loss produced by structural variations. It is the purpose of this contribution to use solid state deuterium echo line shapes to more clearly identify the structural source, geometry, time scale and temperature dependence of the molecular motions present and to associate them with the mechanical response of the bisphenol epoxide resin.

Deuterium²⁵⁻²⁷ and carbon-13 ²⁸ line shape studies have been established as a definitive technique for the characterization of motion in solid polymers and for establishing the relationship between molecular motions and the bulk mechanical response of the solid material. To apply these techniques most directly, isotopically labeled samples must be prepared. For the current study, the obvious sites to label with deuterium in separate samples are the phenylene rings of the diphenylpropane portion and the methylene groups of the hydroxyether portion. This will allow for

detailed, direct monitoring of motion in each of the two key regions of the material separately. To test the effects of crosslinking or curing the dynamics of a cured, crosslinked material will be compared with a linear material.

SUMMARY OF RESULTS.

Experimental

Four deuterium labeled materials were prepared for this study. First linear poly(diglycidyl ether of bisphenol A) (poly(DGEBA)) was prepared with deuterated methylene units in the hydroxyether portion. A second sample of the same linear polymer was prepared with deuterated phenylene units in the diphenylpropane portion. The third labeled sample is made by curing the methylene labeled DGEBA with 4,4' methylene dianiline (MDA) to produce a model one to one network. A similar network sample is prepared by curing the phenylene labeled DGEBA with MDA. The crosslinked resins were synthesized by the addition of 1 equivalent of MDA to 4 equivalents of DGEBA. They were then cured by heating for 16 hours at 55°C followed by 2 hours at 125°C and 2 hours at 175°C. The linear polymers were made by addition of Bisphenol-A and DGEBA (1:1) followed by the same cure conditions. The structures of the four labeled systems are shown in Figure 1.

The deuterium NMR experiments were carried out with a Bruker MSL-300 spectrometer operating at a deuterium resonance frequency of 46.07 MHz. Temperature was regulated with a Bruker VT-1000 control unit. The deuterium spectra were obtained using a quadrupole echo pulse sequence with echo delay times of 15, 30, 50, 80, and 120 μ s. The 90° pulse width was 2.5 μ s and the recycle time of the experiment was 5 to 20 s depending on the sample and the temperature.

Results

Solid echo spectra on the four samples as a function of echo time and temperature over the range of about -100 to 100°C are shown in Figures 2, 3, 4, and 5. At the lowest temperatures (-80°C), Pake patterns are observed corresponding to nearly rigid specimens. The quadrupole coupling constant for the methylene labeled systems is 170 kHz; and for the phenylene labeled systems, 180 kHz. As temperature is raised, the methylene labeled systems partially collapse to a line shape corresponding to an asymmetric tensor which has generally been associated with the onset of trans-gauche isomerization plus rapid libration²⁶⁻²⁷. The phenylene labeled systems partially collapse as temperature is raised and show a splitting at high temperatures which is indicative of π flips plus rapid libration²⁵. Both methylene and phenylene labeled systems show lineshape changes as a function of echo delay time at certain temperatures which verifies the presence of motions on time

scales comparable to the selection of echo delay times. Also the spectra show significant intensity reductions with increasing echo delay time at these same temperatures further identifying the time scale of motion as comparable to the echo delay times²⁵.

Interpretation

To quantitatively determine the rates and amplitudes of motion, the deuterium line shapes are simulated according to the procedures described by Wittebort²⁹ and Mehring³⁰. Simulation calculations were performed on a DEC UNIX workstation and the simulated spectra include the effects of finite pulse width. Because of the complexities of molecular dynamics in polymeric glasses several additions to these procedures must be made. The first is that motion in a glass cannot be characterized by a single rate but rather the motion is heterogeneous and must be described by a distribution of rates^{19,31}. In this regard one of the more successful functions for describing relaxation in polymers is the stretched exponential or Kohlrausch-William-Watts function^{19,32-32}

$$\phi(t) = \exp -(t/\tau_p)^\alpha \quad (1)$$

which can be written as sum of exponentials³³. The fractional exponent, α , controls the breadth of the distribution and the characteristic time, τ_p , controls the time scale. Accordingly these two parameters will be quoted when summarizing the rates or time scales of motion.

Two jump motions are considered in the interpretation: trans-gauche isomerization for the methylene units and π flips for the phenylene units. However in disordered glasses a distribution jump angles is required for both of these motions and following English²⁶⁻²⁷ et al a Gaussian distribution of jump angle centered around the conformational minimum will be used. The usual Gaussian breadth parameter σ is reported to characterize this aspect of the dynamics.

The last dynamic influence on the line shape spectra comes from the presence of librational motion which is relatively rapid on the line shape collapse time scale. To include the effect of this motion, the quadrupole tensor is pre-averaged before the line shape collapse calculation is made²⁵⁻²⁸. Again a distribution of librational amplitudes is often required in glasses²⁶⁻²⁷ but to simplify the calculations and reduce the time required on the computer a single librational amplitude was employed.

Improved fits could be achieved if a distribution of librational amplitudes was employed but the essential aspects of the dynamics are captured without a distribution for this influence on the line shape. The amplitude of libration is temperature dependent in the modeling presented here and is allowed to increase with temperature. Improved simulations could also be produced if the librational motion was given an actual rate and not simply assumed to be fast on the NMR time scale. Again this simplification is made to limit the simulation to reasonable times on a work station.

To properly calculate the changes in amplitude with increasing echo delay times, the spin-spin relaxation time, T_2 , must be included and it can be estimated from the low temperature spectra or the high temperature spectra where the reduction of intensity associated with dynamics are minimal.

The calculated line shapes and reductions factors are compared with the experimental results in Figure 2 for the linear poly(DGEBA) with methylene deuterated hydroxyether units. The simulation parameters are summarized in Table 1. The analogous comparisons of experiment and simulation for the crosslinked methylene deuterated hydroxyether system are shown in Figure 3 and the associated simulation patterns are given in Table 2. Figure 4 contains the comparison of experiment and simulation for the phenylene labeled linear poly(DGEBA) and the simulation parameters are contained in Table 3. The last set of simulations for the phenylene labeled cross linked system are compared with experiment in Figure 5 and the parameters are listed in Table 4.

Apparent activation energies are calculated from a fit of the simulation values of τ_p according to the Arrhenius equation

$$\tau_p = \tau_{\infty} \exp(E_a/RT) \quad (2)$$

which are shown in Figure 6. Since the time scales of motion are all rather similar, a fixed value of the prefactor of 10^{-14} is used in all fits. Table 5 gives a summary of the apparent activation energies obtained for the motion in each system.

The amplitude of libration as a function of temperature is shown in Figure 7. Actually the libration amplitude has a nearly linear dependence on the square root of temperature as has been observed in other systems so Figure 7 is plotted accordingly.

Discussion

The most rapid motion observed in the four systems studied is for π flips of the phenylene group in the linear poly(DGEBA) and the second most rapid motion is for π flips of the phenylene groups in the crosslinked network. The effect of crosslinking on phenylene group motion is about equivalent to a shift of time scale corresponding to a temperature change of 5 or 10 degrees. The breadth parameter determining the distribution of correlation times, α , is 0.6 for the linear system and 0.7 for the crosslinked network. This corresponds to a fairly narrow distribution of correlation times and a prediction of the temperature of the maximum of the mechanical loss peak can be obtained by extrapolating the fit of the NMR data to a time scale of 1 Hz. The 1Hz line is indicated in Figure 6 and the corresponding temperature is -95°C for the linear resin as listed in Table 5. The position of the mechanical loss peak predicted from the NMR data for the crosslinked network is 11 degrees higher. The positions of these predicted mechanical loss peaks place them on the low temperature side of the β peak but part of the overall envelope of loss associated with β peak. This is consistent with the views of some of the mechanical investigators^{8,13-17} though mechanical data is so featureless that changes produced by structure variation leave considerable uncertainty as to the position of the peak to be associated with phenylene group motion. The absolute uncertainty of the NMR estimate of the temperature of the loss peak is between 5 and 10 degrees though the error in the relative difference of 11 degrees between linear and crosslinked is closer to 2 degrees.

The activation energy of 48-51 kJ/mole for the π flip motion is typical of those found for phenylene groups in the backbones of polymers. For instance, the apparent activation energy for the same motion in linear polycarbonate is 40 to 50 kJ/mole^{28,31}. In Garroway's NMR study¹⁹, a value of 60kJ/mole is obtained for phenylene group motion in a crosslinked epoxy.

The trans-gauche isomerization of the methylene groups in the hydroxyether portion is a slower motion than π flips in either the crosslinked or linear systems though the two geometries of motion are only separated by about a decade in time or frequency. The effect of crosslinking is to slow the isomerization motion slightly relative to the linear system. The slowing corresponds to a temperature shift of about 5 degrees. The apparent activation energy obtained for this motion is 55-58 kJ/mole which leads to a slightly larger temperature separation at the

time scale of 1 Hz corresponding to mechanical measurements. Since the distributions of correlation times are again relatively narrow the relaxation map of Figure 6 leads to a predicted temperature for mechanical loss of -70°C for the linear system and -57°C for the crosslinked system. This difference between linear systems and crosslinked systems seems reasonable relative to mechanical data on similar systems¹⁶. These temperatures fall on the high side of the envelope of mechanical loss associated with the β peak. Thus in both the linear and crosslinked systems the two motions, π flips and trans-gauche isomerization, would likely overlap in a mechanical experiment and contribute to the overall mechanical peak described as the β peak. This coincidence between the mechanical experiment and the prediction based on the interpretation of the NMR lineshape data can be further visualized when a calculated³¹ loss peak is plotted and compared with the experimental loss data²² (Figure 8). The equation³¹ used to calculate the shear loss from the rate and temperature dependence established from the interpretation of the NMR data is

$$G(\omega)^{\text{loss}} = \frac{\langle \sigma(0)^2 \rangle}{kT} \int_0^{\infty} \sin(\omega t) [-\phi'(t)] dt \quad (3)$$

The calculation provides information on the breadth of the loss peak and the position in frequency and temperature but not on the amplitude of the loss peak. An amplitude is assumed which matches experimental observation. The calculated loss peak includes the low temperature (fast) ring motion and the slower, higher temperature chain motion and these can be discerned in the calculated line. It is clear from the comparison that the β relaxation contains contributions from further slower motions not detected in our NMR study which contribute to loss at the high temperature side of the mechanical relaxation. There are two potential sources for this slower motion in the crosslinked system. One is motion associated with the crosslinking agent itself, MDA. Since a sample with deuterium labeled MDA is not available we would not observe any local motion of the MDA moiety in the resin. The crosslinked epoxy might also exhibit an additional slow motion component associated with the presence of the crosslinker at one side of the methylene units relative to the more symmetric linear system. This could explain the slightly lower quality of the simulations for the crosslinked system (figures 3 and 5). The fit could

obviously be improved by the inclusion of more parameters to account for this but this does not seem justified in view of the inherent information content of the lineshapes and since the general interpretation is not enhanced.

The apparent activation energy of ca. 57 kJ/mole is high relative to other observed trans-gauche isomerization energies for methylene units. For instance the value obtained by English et al on the methylene groups in nylon is 33kJ/mole. The higher value may reflect the presence of the hydroxyl groups on this portion of the network which can participate in hydrogen bonding.

Conclusion

Deuterium line shape data and the subsequent analysis identifies the role of π flips of the bisphenol A unit and trans-gauche isomerization of the methylene units in the mechanical response of epoxy networks. Both motions contribute to the main sub-glass transition relaxation process, the β process, with the π flips occurring at lower temperatures and the trans-gauche isomerization at higher temperatures but with overlap of the two relaxations. The activation energy of the trans-gauche isomerization is about 7kJ/mol higher than the π flip process. The effect of cross-linking is a shift of either relaxation process about ten degrees at the typical frequency of a mechanical experiment of 1 Hz. Cross-linking may produce some subtle changes in the distribution of relaxation times but it was not necessary to include these to produce reasonable simulations.

TABLE I
Simulation parameters for the chain (methylene)
motion for the linear epoxy.

| T(°C) | $\tau_p(s)$ | α | Libration(°) | $\sigma(°)$ | T ₂ (ms) |
|-------|----------------------|----------|--------------|-------------|---------------------|
| 70 | 6.6x10 ⁻⁶ | 0.6 | 85 | 18 | 1.5 |
| 48 | 1.6x10 ⁻⁵ | 0.6 | 80 | 18 | 1.5 |
| 35 | 2.5x10 ⁻⁵ | 0.6 | 76 | 18 | 1.5 |
| 24 | 4.5x10 ⁻⁵ | 0.6 | 71 | 18 | 1.5 |
| 0 | 1.5x10 ⁻⁴ | 0.6 | 61 | 18 | 1.5 |
| -20 | 5.0x10 ⁻⁴ | 0.6 | 52 | 18 | 1.5 |

TABLE II
Simulation parameters for the chain (methylene) motion
for the crosslinked epoxy.

| T(°C) | $\tau_p(s)$ | α | Libration(°) | $\sigma(°)$ | T ₂ (ms) |
|-------|----------------------|----------|--------------|-------------|---------------------|
| 90 | 1.0x10 ⁻⁵ | 0.7 | 75 | 18 | 0.8 |
| 70 | 1.5x10 ⁻⁵ | 0.7 | 72 | 18 | 0.8 |
| 48 | 3.5x10 ⁻⁵ | 0.7 | 65 | 18 | 0.8 |
| 35 | 6.0x10 ⁻⁵ | 0.7 | 60 | 18 | 0.8 |
| 24 | 1.4x10 ⁻⁴ | 0.7 | 56 | 18 | 0.8 |
| 0 | 6.0x10 ⁻⁴ | 0.7 | 47 | 18 | 0.8 |
| -20 | 2.8x10 ⁻³ | 0.7 | 39 | 18 | 0.8 |

TABLE III

Simulation parameters for the ring motion for the linear epoxy.

| T(°C) | τ_p (s) | α | Libration(°) | σ (°) | T ₂ (ms) |
|-------|----------------------|----------|--------------|--------------|---------------------|
| 70 | 2.4x10 ⁻⁷ | 0.6 | 50 | 25 | 0.28 |
| 48 | 6.5x10 ⁻⁷ | 0.6 | 47 | 25 | 0.28 |
| 35 | 1.4x10 ⁻⁶ | 0.6 | 44 | 25 | 0.28 |
| 24 | 2.8x10 ⁻⁶ | 0.6 | 41 | 25 | 0.28 |
| 0 | 1.5x10 ⁻⁵ | 0.6 | 35 | 25 | 0.28 |
| -20 | 4.0x10 ⁻⁵ | 0.6 | 30 | 25 | 0.28 |

TABLE IV

Simulation parameters for the ring motion for the crosslinked epoxy.

| T(°C) | τ_p (s) | α | Libration(°) | σ (°) | T ₂ (ms) |
|-------|----------------------|----------|--------------|--------------|---------------------|
| 90 | 2.9x10 ⁻⁷ | 0.7 | 50 | 25 | 0.20 |
| 70 | 6.7x10 ⁻⁷ | 0.7 | 47 | 25 | 0.20 |
| 48 | 1.8x10 ⁻⁶ | 0.7 | 43 | 25 | 0.20 |
| 35 | 4.1x10 ⁻⁶ | 0.7 | 40 | 25 | 0.20 |
| 24 | 7.8x10 ⁻⁶ | 0.7 | 37 | 25 | 0.20 |
| 0 | 3.7x10 ⁻⁵ | 0.7 | 31 | 25 | 0.20 |
| -20 | 2.8x10 ⁻⁴ | 0.7 | 26 | 25 | 0.20 |

TABLE V

Activation parameters for linear and crosslinked epoxies

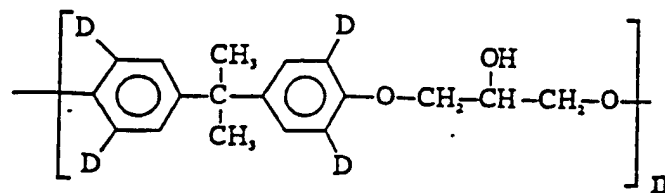
| | E _a (kJ/mol) | Temp at 1Hz(°C) |
|---------------------------|-------------------------|-----------------|
| Linear, chain motion | 54.6 | -70 |
| Crosslinked, chain motion | 57.9 | -57 |
| Linear, ring motion | 47.7 | -95 |
| Crosslinked, ring motion | 50.7 | -84 |

Figure captions.

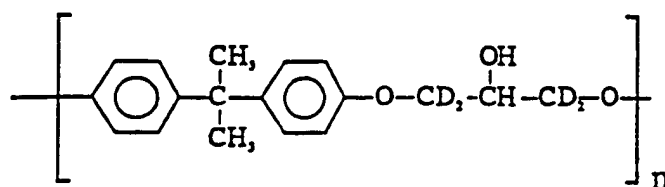
- Figure 1: Chemical structures of the four deuterium labeled epoxy systems.
- Figure 2: ^2H experimental (left) and simulated (right) lineshapes for the chain labeled linear epoxy as a function of echo delay times: 15, 30, 50, 80, 120 μs from bottom to top; reduction factors are listed at the right.
- Figure 3: ^2H experimental (left) and simulated (right) lineshapes for the chain labeled crosslinked epoxy as a function of echo delay times: 15, 30, 50, 80, 120 μs from bottom to top; reduction factors are listed at the right.
- Figure 4: ^2H experimental (left) and simulated (right) lineshapes for the ring labeled linear epoxy as a function of echo delay times: 15, 30, 50, 80, 120 μs from bottom to top; reduction factors are listed at the right.
- Figure 5: ^2H experimental (left) and simulated (right) lineshapes for the ring labeled crosslinked epoxy as a function of echo delay times: 15, 30, 50, 80, 120 μs from bottom to top; reduction factors are listed at the right.
- Figure 6: Arrhenius plot for both the chain and ring motion in the epoxy systems studied. The rate for comparison with the mechanical relaxation (1Hz) is shown as a dotted line.
- Figure 7: The temperature dependence of the amplitude of the librational motion of the chain methylenes and the phenylene rings.
- Figure 8: A comparison of the experimental mechanical response²² (circles) with the prediction (line) based on the ring and chain dynamics obtained from the NMR analysis.

FIGURE 1

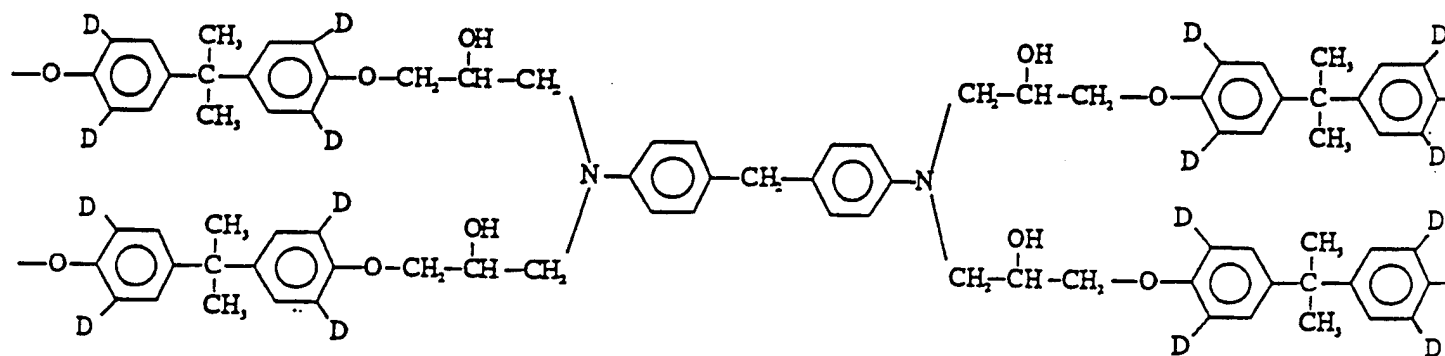
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B



C



D

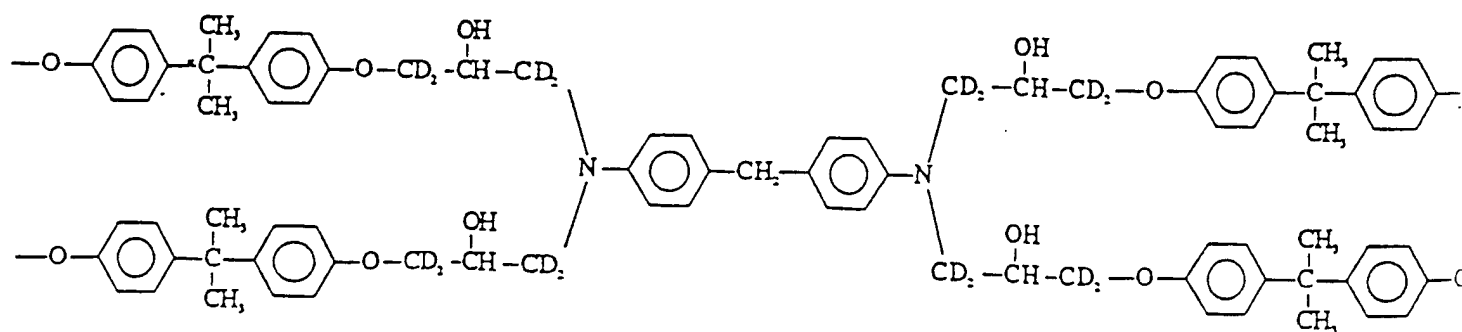


Fig 2

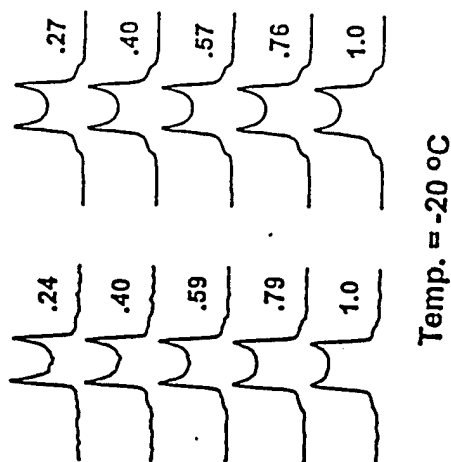
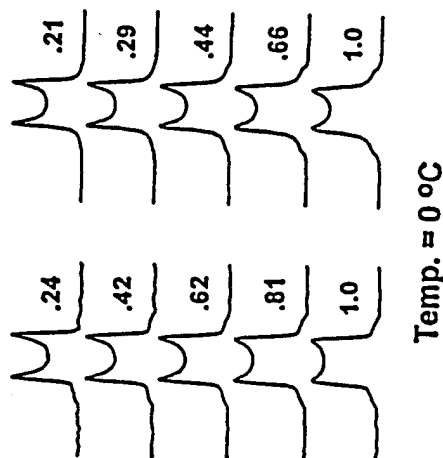
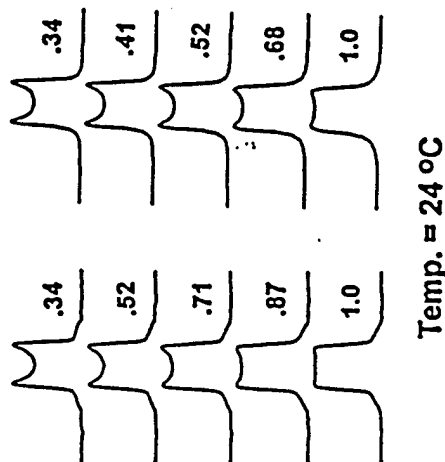
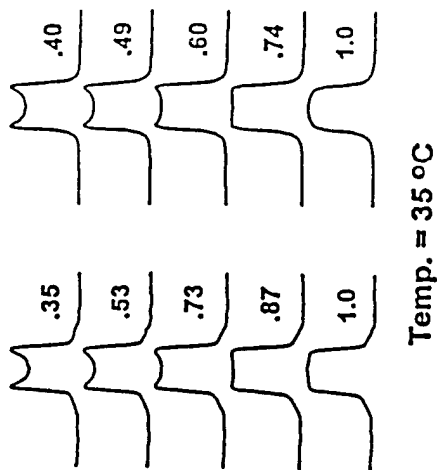
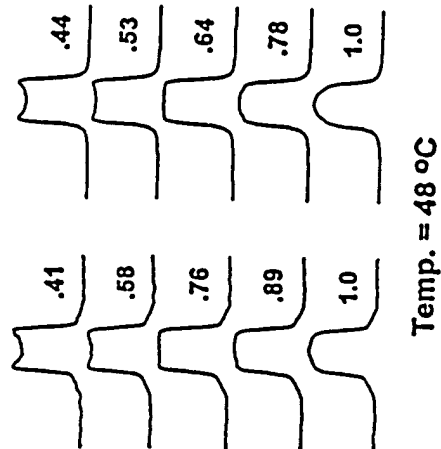
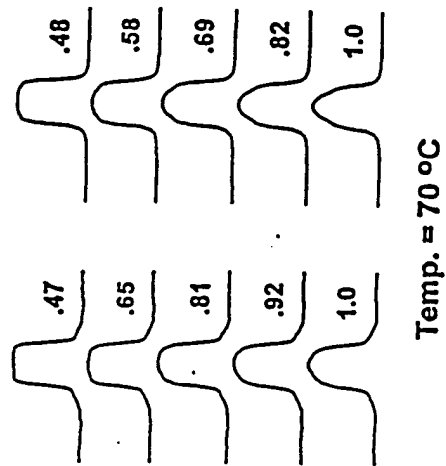


Fig 3

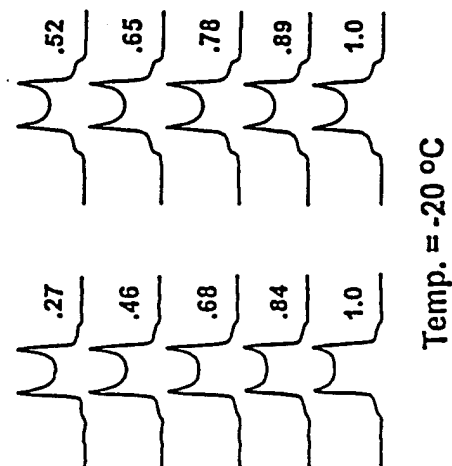
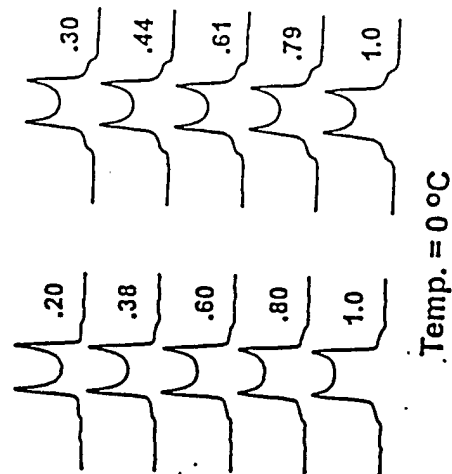
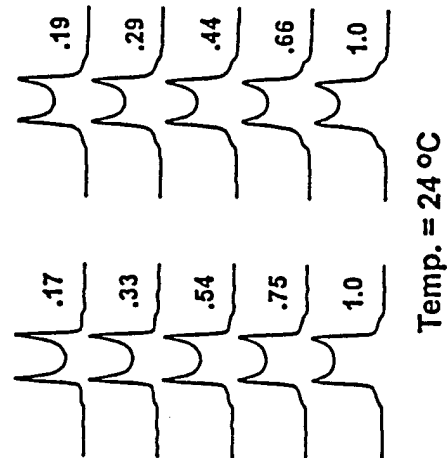
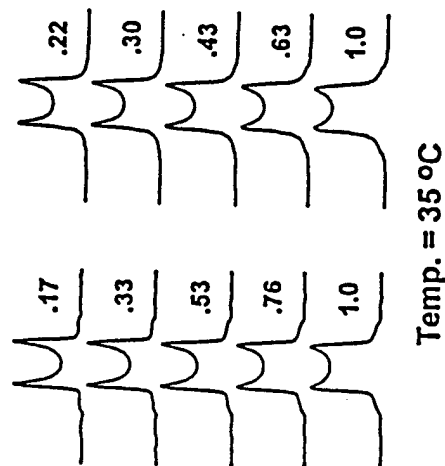
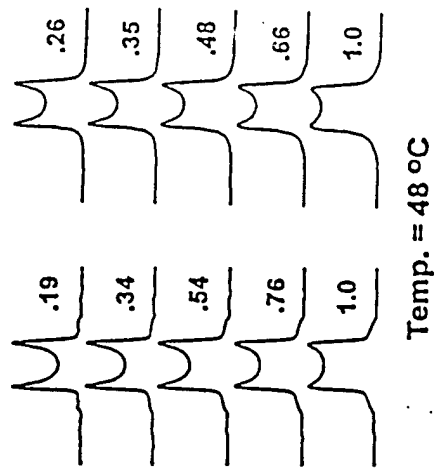
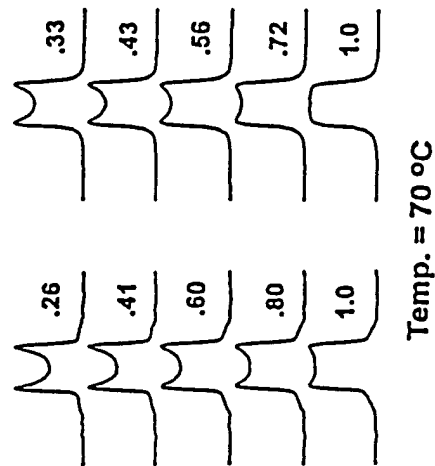
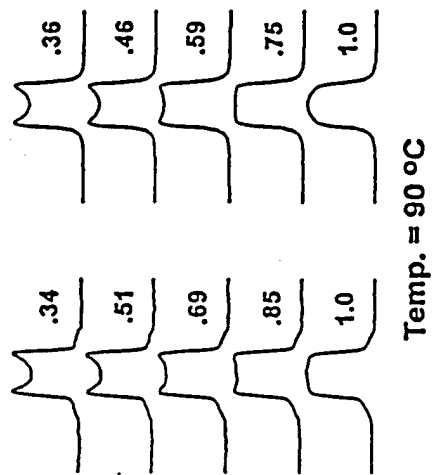
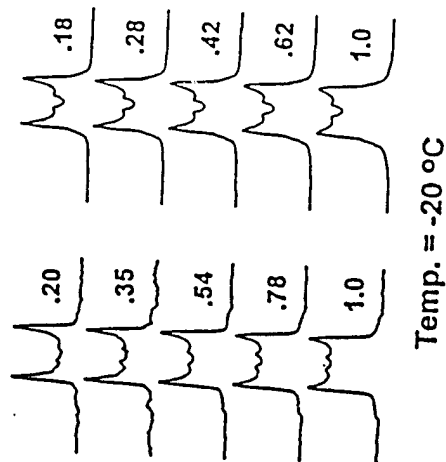
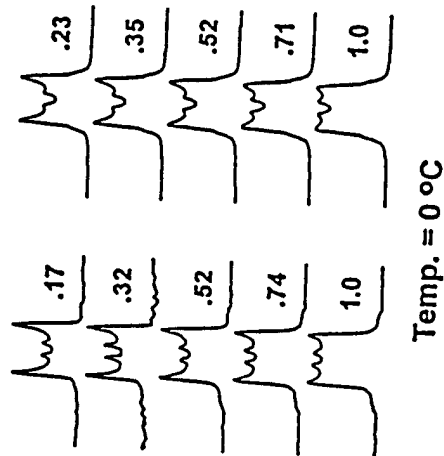
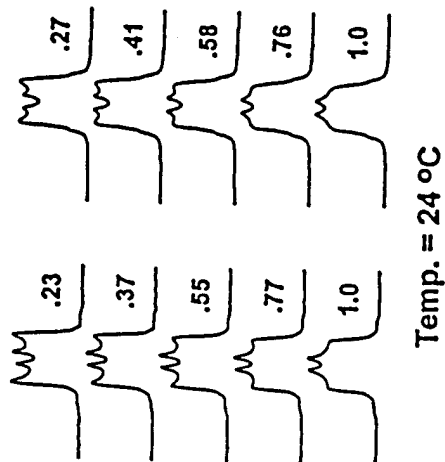
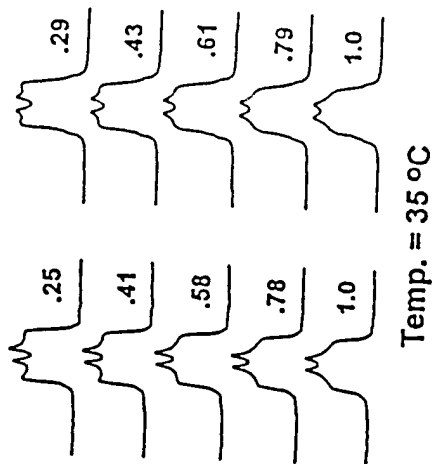
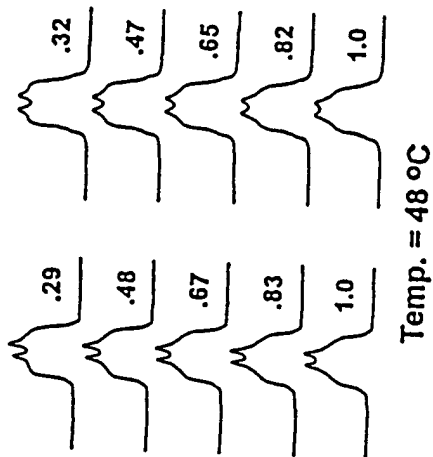
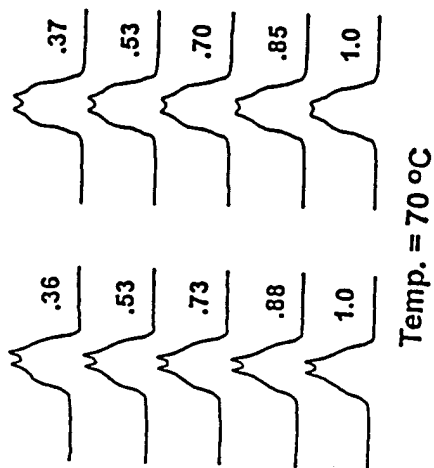


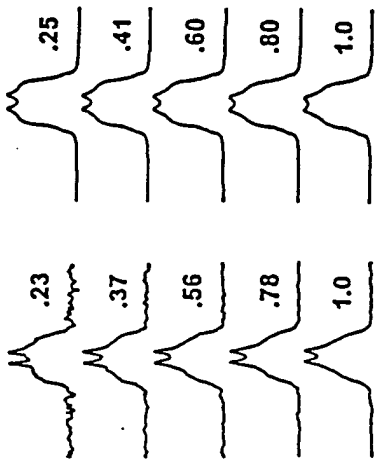
Fig 3

Fig 4

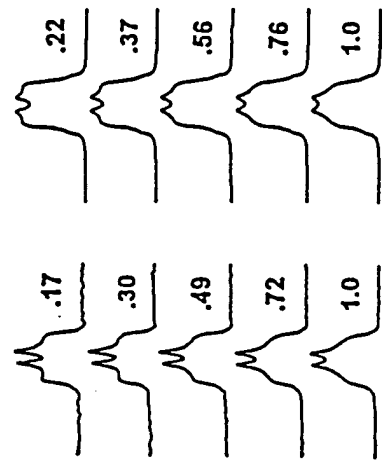


5bif

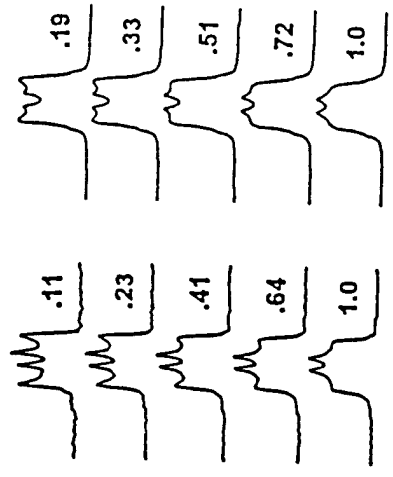
Fig 5



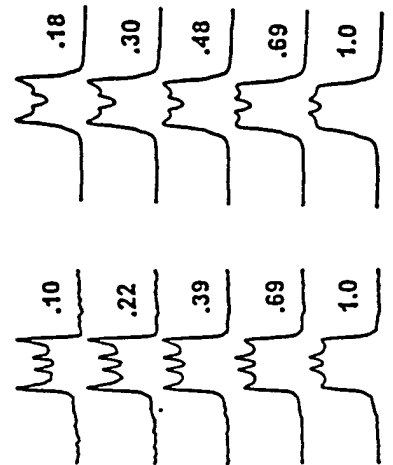
Temp. = 90 °C



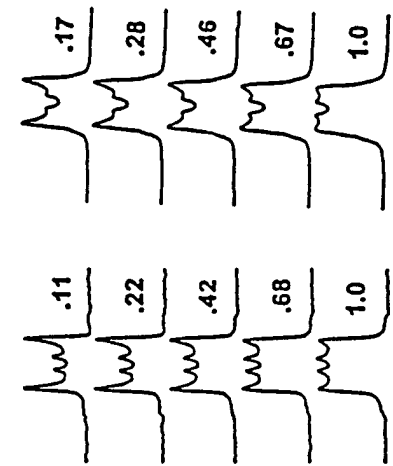
Temp. = 70 °C



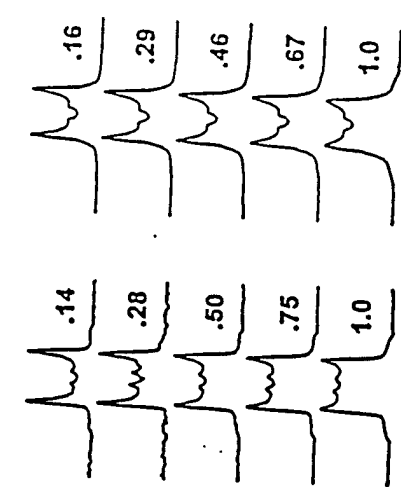
Temp. = 48 °C



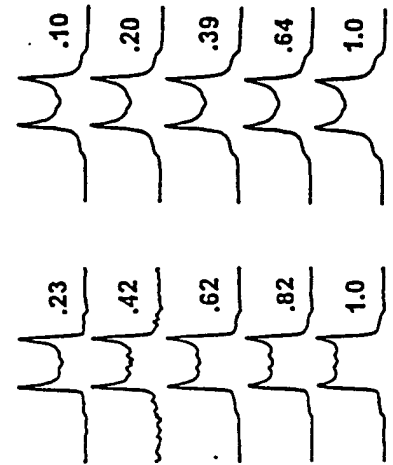
Temp. = 35 °C



Temp. = 24 °C



Temp. = 0 °C



Temp. = -20 °C

9.24

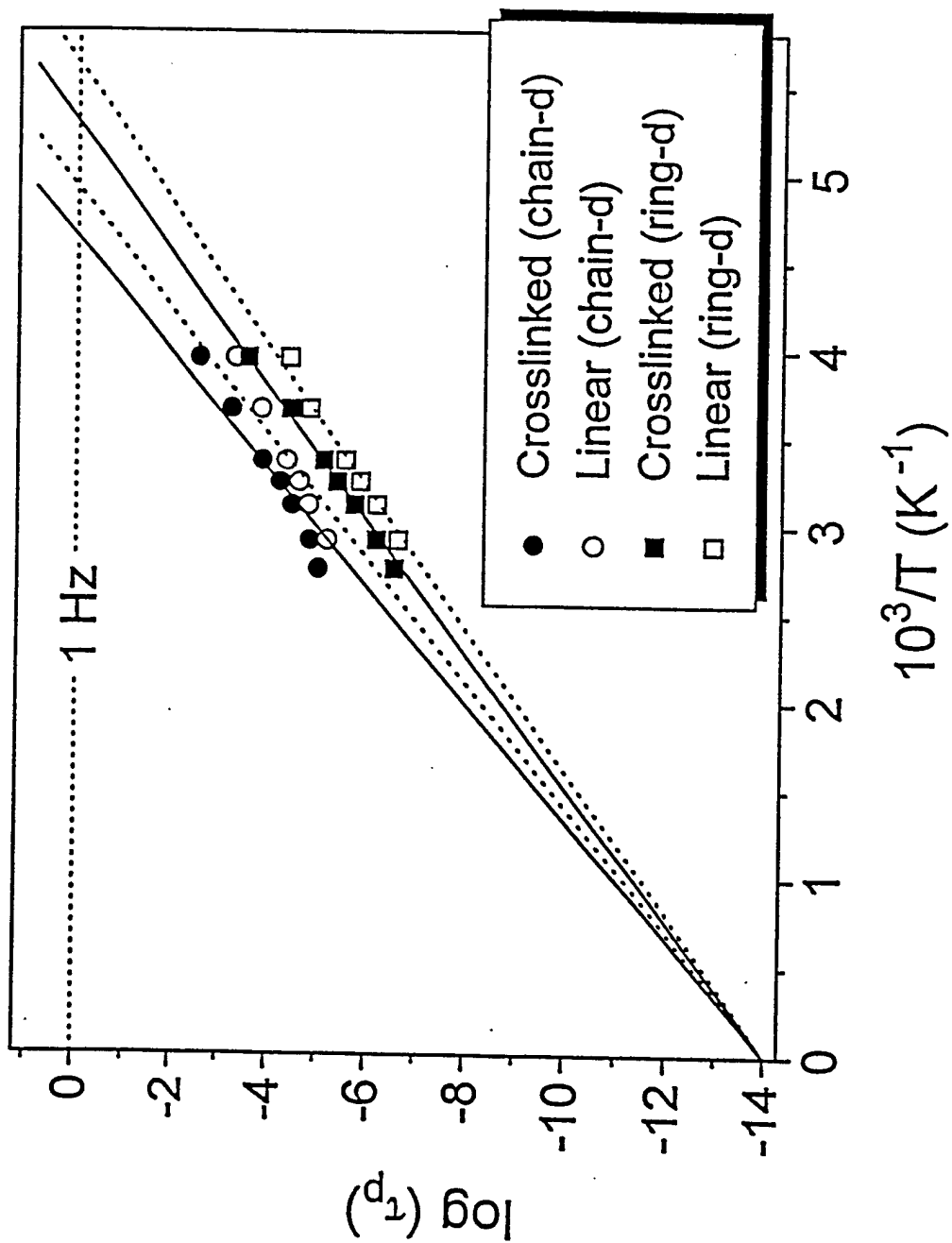


fig 6

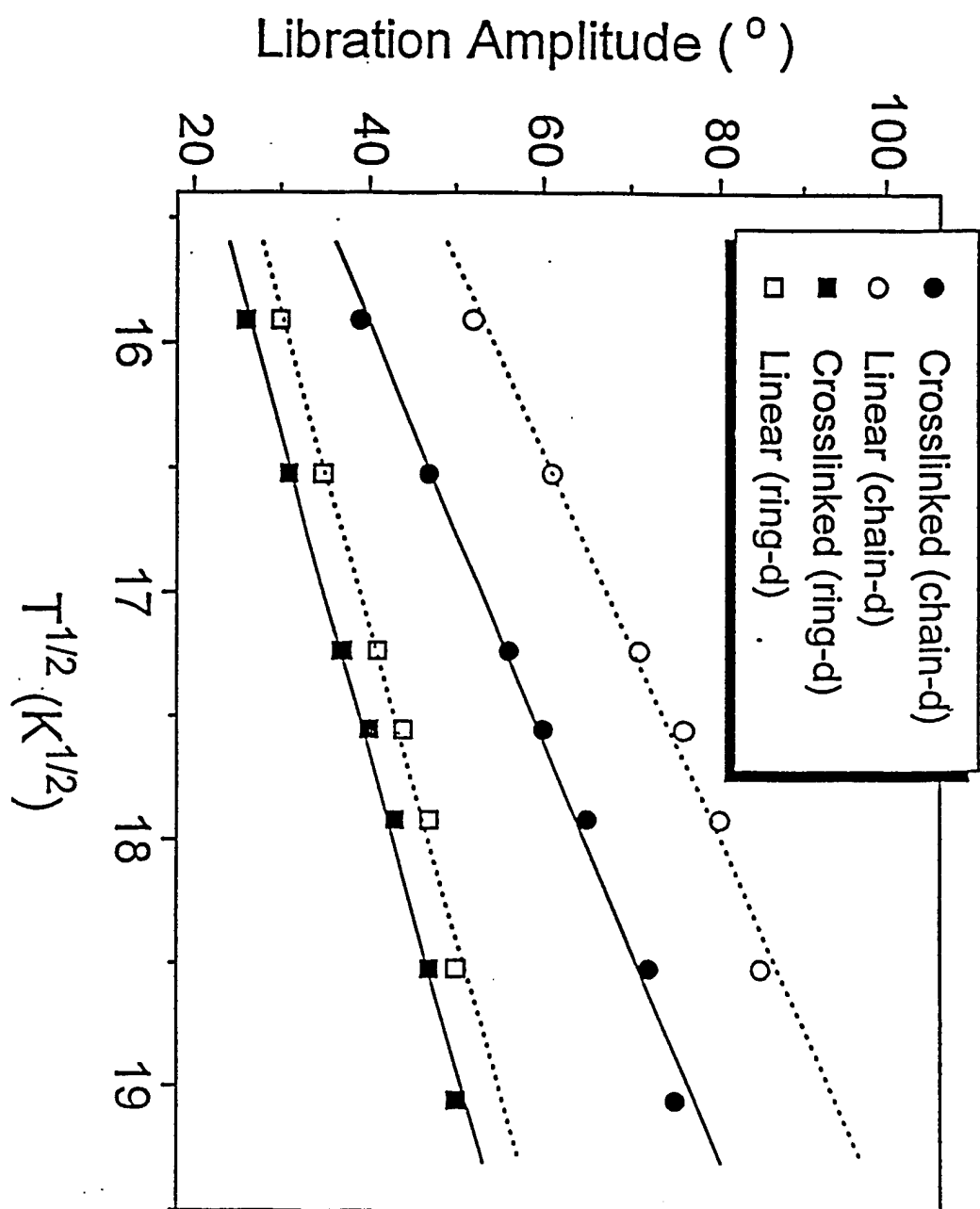
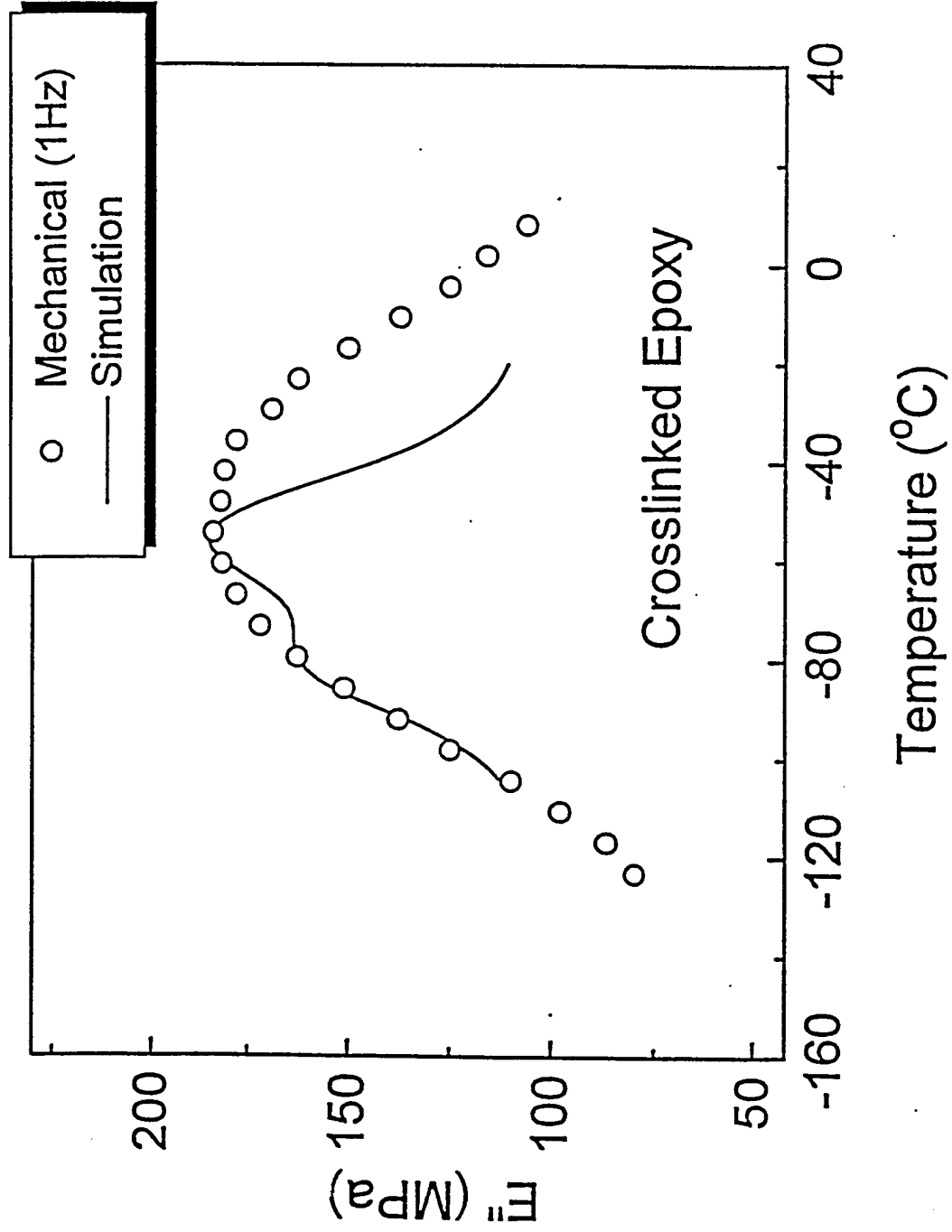


fig 7



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