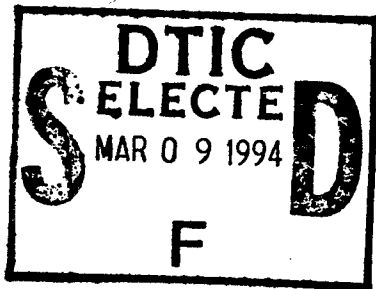




Manikin Integrated Data Acquisition (MIDAS) Initial Modifications



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19950306 019

December 1994

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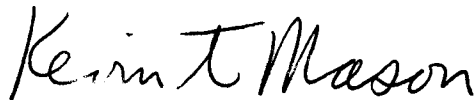
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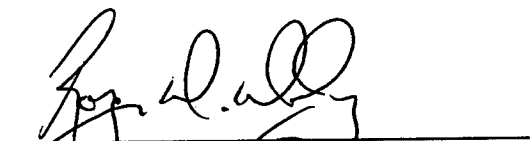
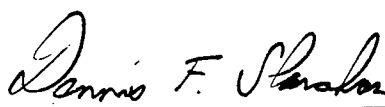
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REPORT DOCUMENTATION PAGE				Form Approved OMB No. 0704-0188	
1a. REPORT SECURITY CLASSIFICATION Unclassified			1b. RESTRICTIVE MARKINGS		
2a. SECURITY CLASSIFICATION AUTHORITY			3. DISTRIBUTION / AVAILABILITY OF REPORT Approved for public release, distribution unlimited		
2b. DECLASSIFICATION / DOWNGRADING SCHEDULE			5. MONITORING ORGANIZATION REPORT NUMBER(S)		
4. PERFORMING ORGANIZATION REPORT NUMBER(S) USAARL Report No. 95-11			7a. NAME OF MONITORING ORGANIZATION U.S. Army Medical Research and Materiel Command (Provisional)		
6a. NAME OF PERFORMING ORGANIZATION U.S. Army Aeromedical Research Laboratory		6b. OFFICE SYMBOL (If applicable) SGRD-UAD-IV	7b. ADDRESS (City, State, and ZIP Code) Fort Detrick Frederick, MD 21702-5012		
6c. ADDRESS (City, State, and ZIP Code) P.O. Box 620577 Fort Rucker, AL 36362-0577			9. PROCUREMENT INSTRUMENT IDENTIFICATION NUMBER		
8a. NAME OF FUNDING / SPONSORING ORGANIZATION		8b. OFFICE SYMBOL (If applicable)	10. SOURCE OF FUNDING NUMBERS		
8c. ADDRESS (City, State, and ZIP Code)			PROGRAM ELEMENT NO. 62787A 30	PROJECT NO. 62787A878	TASK NO. ED
			WORK UNIT ACCESSION NO. 141		
11. TITLE (Include Security Classification) Manikin integrated data acquisition system (MIDAS) initial modifications					
12. PERSONAL AUTHOR(S) Nabih M. Alem, James A. Lewis, and Robert M. Dillard					
13a. TYPE OF REPORT Final		13b. TIME COVERED FROM _____ TO _____		14. DATE OF REPORT (Year, Month, Day) 1994 December	
15. PAGE COUNT 25					
16. SUPPLEMENTARY NOTATION					
17. COSATI CODES			18. SUBJECT TERMS (Continue on reverse if necessary and identify by block number)		
FIELD	GROUP	SUB-GROUP	prototype, manikin, crash testing, data acquisition, anthropomorphic test device, injury assessment		
15	05				
05	09				
19. ABSTRACT (Continue on reverse if necessary and identify by block number)					
<p>A prototype manikin with internal data acquisition system (MIDAS) has been developed and received by the US Army Aeromedical Research Laboratory. In addition to a novel design of the spinal column and pelvis of the Hybrid III automotive manikin, the new MIDAS includes a built-in signal conditioning and acquisition electronics. This report documents the initial modifications to the manikin and includes a description of the external software (MIDAS 3.0) for control, communication, and posttest downloading and analysis of the data.</p>					
20. DISTRIBUTION / AVAILABILITY OF ABSTRACT <input checked="" type="checkbox"/> UNCLASSIFIED/UNLIMITED <input type="checkbox"/> SAME AS RPT. <input type="checkbox"/> DTIC USERS			21. ABSTRACT SECURITY CLASSIFICATION Unclassified		
22a. NAME OF RESPONSIBLE INDIVIDUAL Chief, Science Support Center			22b. TELEPHONE (Include Area Code) 205-255-6907		22c. OFFICE SYMBOL SGRD-UAX-SI

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Introduction

A prototype manikin with internal data acquisition system (MIDAS) has been developed and received by the U.S. Army Aeromedical Research Laboratory (USAARL), Fort Rucker, Alabama, for initial evaluations. New features in this anthropomorphic manikin include a novel design of the spinal column that offers more flexibility in compression and twisting than other manikins, a pelvis that contains the signal conditioning and data acquisition electronics required in most impact tests, and two new upper legs where rechargeable nickel-cadmium cells are placed to provide power supply for the instrumentation and data acquisition system.

As with most prototype systems, MIDAS must be evaluated before it can be put to full use in crash tests and other impact exposures. The evaluation process is simple: expose the manikin to impact tests, collect its biodynamic response signals, then compare the impact response to that of other validated manikins such as the original Hybrid III. This requires that the MIDAS internal electronics and data acquisition system operate properly and allow the data to be extracted in a short time.

Initial bench testing of MIDAS's signal conditioning electronics pointed out areas of potential problems which must be addressed prior to any sled or field testing. First, the battery packs which were installed in the manikin femurs were not supplying adequate power to the electronics. Additionally, the power supply that runs off the standard 120 VAC line and which was delivered with the prototype introduced unacceptable levels of noise to the signal amplifiers. Therefore, a new power supply was needed to replace the current battery packs and provide power from an external source through an umbilical line.

The second area where difficulties were encountered was the software for data acquisition, downloading, and display, which was delivered with the system. Since our immediate goal was the evaluation of the biodynamic response, it was essential that we are able to modify the internal settings of the electronics and to immediately examine the data captured after each test for quick assessment of the manikin performance. Our bench tests also pointed out the need for reliable and flexible software which allows us to achieve these two simple goals: modify the settings and examine the data as quickly as possible.

This report is intended to document the initial improvements made to the MIDAS prototype since its delivery. Because it was only a prototype, modifications were made only to bring the manikin to an acceptable level of reliability during sled tests.

Materials and methods

Electronics hardware

The external power supply was designed to convert 120 VAC to provide several regulated DC voltages to MIDAS's internal computer CPU, memory, disks, transducers, and amplifiers. The box delivered with the manikin had to be reworked by first removing the battery charger subsystem from the power supply box itself. Second, the soldering joints of the cables had to be redone because of potential breakage during anticipated sled mounting of the power supply box.

A serious problem that was identified after extensive debugging was the so-called "common mode problem." This problem caused the signal amplifiers to saturate due to the transducer excitation being tied to system ground. The problem was corrected by floating (relative to system ground) the 15-Volt excitation voltage of each transducer power supply.

Another shortcoming was cumbersome access to the analog signals from the 24 transducers installed in the manikin. Access to these signals is necessary for debugging and maintenance, for bypassing the data acquisition system in case of failure, and for recording the analog signals on an external data recording medium. At one stage during the development and testing of MIDAS, the contractor has built into the wiring access to all the transducer signals. Since this was not part of the contract and because of space constraints, the access cables were removed. In order for USAARL to make its evaluation, it was necessary to reconstruct the access cable and connect it to a breakout box where BNC-type connectors may be used. This proved later to be a valuable modification when it became necessary to record the signals external to the MIDAS hardware.

Data acquisition settings

Precise measurements require accurate knowledge and control of the sampling rate and the gains for each amplifier in the manikin internal data acquisition system. Therefore, it was essential to verify the values of sampling rate and gains claimed by the contractor. We used the voltage insertion method, where a low level sine wave signal, generated by a precision calibrator, was used to replace a transducer and provide an input to the amplifier. By measuring the output of the amplifier, we determined its actual gain as the ratio of its output over the input, and its zero offset as the midpoint of the peak-to-peak range of the output.

Although it was possible to determine the amplifiers' gains by monitoring analog input and output signals, it was necessary to determine the sampling rate of the A/D convertor from the digitized data after it was stored on the thin credit-card memory, then dumped onto a PC disk file and examined. This was done after the first version of the MIDAS software became operational.

External software

As delivered, the operation of MIDAS requires the user to turn on the power supply, modify the amplifier gains and other data acquisition parameters to accommodate specific test conditions, conduct the tests, then remove the credit-card memory module (where the manikin internal computer stored the data) for down-loading and analysis of the digitized data. A new MIDAS program was written to externally control the amplifier settings and sampling rate, and to extract the data from the credit-card and display it for quick look and assessment of the quality of the data acquisition.

Because of its intended use, the MIDAS program was designed to improve the communication by automating most of the functions which were required to be repeated by the user. The program was written in Fortran language (Microsoft Corp, 1988) to be run on an IBM-PC computer under a MS-DOS environment. All test data would be downloaded and archived along with descriptive and calibration data. These archived files may be accessed by MIDAS for further analysis and plotting at a later time after completing a test series. The program produces hard copies of raw and processed signals and summaries of analyzed signals. The program offered significant improvements in the operation of the manikin and, although several additions were contemplated, the first version was deemed adequate for evaluating the results from sled tests.

Results

The bench evaluation of the electronics, wiring, and data acquisition system produced the following observations. Refer to Frisch, Boulay, and Alem, 1994, for a description of the delivered MIDAS and explanation of the components mentioned here.

1. The signal conditioner circuitry has no offset capability. Potentiometers on the board that are connected to the sample-and-hold (S/H) amplifiers have no effect on the direct analog or S/H output.
2. The voltage substitution calibration, as currently provided, is not useful. The resistor calibration (RCAL) is not implemented.
3. Gain and sample rate settings cannot be verified and sometimes are in error. Occasionally the gain sets to gain code 0, and at other times the sample rate sets to lowest value, as evidenced by a very dim data card light-emitting diode (LED).
4. For proper operation of the sensors, the power supplies required rewiring to "float" the grounds. The following supplies were affected: +15 volts for all of the accelerometers, +15 volts for all of the load cells, and +10 volts for the angular accelerometer in the head.
5. The specified rates for sampling are only approximate values.

6. Sampling at the highest two rates, 5 kilo-Hertz (KHz) and 10 KHz, is not possible with the current system which writes 48 channels to the data card.
7. The manikin's internal wiring harness is difficult to check or correct. It should have been of a more replaceable design, so that sensors or cables could be replaced easily. The copper tape shielding is ineffective.
8. The definitions of channels 18 and 20 appear to be swapped from their original designations.
9. Several signal conditioner hybrid circuits are bad, in one or both channels of the hybrid.
10. The L5 load cell channels have noise problems; so do the Head-X and the T1-Y channels.
11. Channel 19 is nonfunctional, producing a 147 Hertz noise signal.
12. Signal conditioner module card #1 has bad U-11 chip.

External software (MIDAS 3.0)

The MIDAS software initially was written to replace the software delivered as part of the contract because that software did not allow sufficient flexibility and reliability in operating the manikin, nor adequate speed in downloading and examining the acquired data. The latest version of MIDAS (version 3.0) was the result of actual tests and experience in the manikin's operation as intensive bench testing was conducted.

The step-by-step procedure to operate the manikin is summarized in Appendix A. This requires the MIDAS software and a PC connected through an RS-232 cable to the manikin internal computer. The capabilities of the MIDAS (version 3.0) software are summarized in Appendix B in the form of a series of screen printouts of the program menus. Although shown in black and white, these "screens" are produced on a VGA monitor in colors which are used for emphasis of key words or important text, and for demarcation between blocks of information. The following features are the highlights of the software.

1. The program consists of over 200 subroutines, written in Microsoft Fortran 5 and developed in its entirety at USAARL.
2. The program is interactive when necessary and automated when possible, and is entirely menu driven. All of the major submenus in MIDAS are reproduced in Appendix A as screen printouts.

3. The program requires an IBM-PC compatible running MS-DOS 5.0 or higher.
4. The PC hardware should have a VGA color monitor, although a laptop LCD screen may be used after adjusting the "color" settings to suit the particular screen.
5. No mouse is needed but a serial port (COM1 or COM2) must be available to communicate with the manikin internal computer.
6. MIDAS software is designed to run independent of the manikin to analyze, plot, and produce hard copies of the analyzed data after all the data from a series of tests have been archived.
7. Hard copies are produced in PCL/5 and HP-GL/2 languages and require printers capable of interpreting these languages, such as the HP Laserjet 3 or 4.

Discussion

As with most prototype systems, some adjustments to the delivered version of the system was necessary. The initial modifications were designed primarily to put the manikin in an acceptable and reliable working condition so its performance as a test device could be evaluated. The reliability of the power supply, the calibration of the amplifiers, and the identification and repair (when possible) of known problems were of the utmost concern. Just as critical was the down-load and quick-look capability without which the manikin simply could not have been tested efficiently.

The manikin was designed to be self contained, i.e., capable of operation from an internal power source. The design of the prototype included two sets of nickel-cadmium (nicad) batteries installed in the femur in two cylindrical arrays. Although this approach was discussed and approved during the development phase of the manikin, the execution of this design by a subcontractor resulted in a product that functioned below our expectations. A remedy to this problem was set aside while more important issues were addressed. Thus, the manikin was to operate from external power supply until the internal battery supply issue has been resolved. Indeed, an external power supply was delivered but it also had problems: noise, ground loops, poor shielding, weak soldering connections and unnecessary wiring. All these problem areas were addressed and resolved in the more reliable configuration which was fabricated. This allowed us to advance to the next stage in this research program: the actual sled and controlled drop tests.

Equally important was our ability to program the internal amplifiers' gains and adjust the sampling rate of the manikin data acquisition system to meet the different impact test requirements. The manikin had default settings for all amplifiers and sampling rate which were stored on an erasable/programmable ROM chip in the MIDAS computer and read each time the manikin was turned on. Access to these stored defaults required the "undressing" of the manikin

and the removal of the CPU board, then its installation in a separate but equivalent computer for re-coding. The alternative to this time-consuming task was the transmittal of the desired gain values over the serial communication port every time the manikin was turned on to override the default values.

This approach was an acceptable solution if all goes well. Unfortunately, it took nearly half an hour of interaction between the user and the manikin internal software before the new settings had been transmitted. Frequently, the transmittal was so erratic because of poor COM port hardware and software drivers or because of unexplainable malfunction in the MIDAS internal electronics that it was necessary to reset the internal electronics by turning off the manikin power supply then switching it back on to restart the entire operation. This frustrating and inefficient process was one of the two primary reasons for writing our own external MIDAS control software.

The other motive for rewriting the MIDAS software was our inability to examine the data immediately after it was acquired. This essential requirement was somewhat met by the software as it was delivered. In fact, we were able to quickly remove the credit card and "download" the raw data to a PC file using utilities supplied by the manufacturer of the credit card. Unfortunately, plotting one impact pulse, which may be of 20 or 30 millisecond duration, required the manual plotting of the entire channel signal (1200 msec) in small segments and, when all segments were finally plotted, did not give the user sufficient timing and magnitude information to judge the quality of the test. The tedious process was lengthy and often was abandoned after examining one or two channels inconclusively.

Therefore, the MIDAS program was designed to truly assist the user in making informed decisions regarding a test. Just as the manikin could not have been operated without a reliable power supply, it would have been unwise to operate this new prototype without the benefit of "quick look" and "hard copy" capabilities.

Summary and conclusions

As with most prototypes, initial modifications were necessary to the hardware and the software delivered with the manikin in order to bring it to an acceptable operating status. These include improvements to the external power supply to be used temporarily in lieu of the internal battery system, and a PC-based program (MIDAS) which facilitates the settings of internal amplifiers gains and sampling rate, and allows quick look at the down-loaded data immediately following a test. Eventually, it will be necessary to redesign the internal battery-based power supply so that field tests can be conducted independent of external connections. Also, it will be necessary to modify the internal data acquisition software to improve serial communication and to allow easier modification and retention of default data acquisition parameters.

References

Frisch, P., Boulay, W., and Alem, N. 1994. Design and development of an enhanced biodynamic manikin. Phase I report for contract DAMD17-90-C-0116. Fort Rucker, AL: U.S. Army Aeromedical Research Laboratory. USAARL contractor report No. CR 94-1.

Microsoft Corporation. 1989. Fortran reference manual, version 5.0 for MS-DOS operating systems.

Appendix A.

MANIKIN operating procedures.

1. Connect RS-232 cable between manikin and PC communications port 1 or 2, as set in the USAARL manikin integrated data acquisition system (MIDAS) program.
2. Install the memory module (credit-card) into the manikin chassis slot.
3. Power-up manikin. The green LED on control unit indicates +5 volt power is present. Wait approximately 20 seconds - a short flash of the red LED indicates end of boot sequence.
4. On PC, run the MIDAS program. Verify sample rate in the "Sampling setup" function, gains and correction factors in "Amplifiers" function, and sensitivities in "Transducers" function.
5. Using "Identify test" function, enter the new test ID and other desired information.
6. Use the "Manikin controls" function to send gains and sample rate (press F1). If manikin will not respond, send "escape" characters (press F8) to clear the communications port. If this doesn't help, check for correct communication settings under the "Colors and comm." section, set port at 1200 baud, 8 bits, no parity, and 1 stop bit. Verify cabling is connected to correct port. Manikin uses upper communications port connector on manikin input/output (I/O) card, which is located inside the rib cage.
7. "Arm" manikin when ready (press F9). Observe that red LED is on and bright. A dim LED indicates improper sample rate. If LED goes off after 6 seconds (at 2500 Hz sample rate) or after 16 seconds (at 1000 Hz sample rate), then a false trigger has occurred. Turn off manikin power, ensure trigger signal is at ground potential (0 volts), and reapply power to manikin. Resend sample rate and gains after manikin boots up. A steady on LED indicates the proper "armed" condition (data is being written to the card in a circular buffer).
8. Disconnect the RS-232 cable from the manikin.
9. Run test. A 0-to-5 volt transition on the trigger signal input will end the 200-points/channel circular buffer and start the post-trigger data recording. When the red LED goes out, the 12,000 post-trigger data points/channel have been written to the card (storage complete).

10. Remove data card. Insert data card in the PC, perform "Backup card data" operation, saving the card image to hard disk. Use "Extract signals" to retrieve data from the data card (or from a saved file). Use the "Process" function to view signals.

11. Turn off manikin power if done, or press RESET and go to step 2 for the next test.

Appendix B

External manikin software.

MIDAS version 3.0.

This appendix contains screen printouts of most menus and sub-menus which are available in the MIDAS program. Because they are printed in black and white, much of the color highlights used to emphasize various key words and text, and to separate blocks of information on the screen are, of course, missing. However, these "screens" do provide a printed documentation in lieu of actually running the MIDAS program itself.

Test: LX65-56		MIDAS-3.0	Manikin Integrated DAS	13:01:03
Identify test				
Extract signals	Data ID/Label: LX65-56			
Process signals	Description of data:			
Sampling setup	Dynamic testing of MIDAS prototype crash manikin			
Define channels	Sled acceleration pulse: 10.3 peak G, 23.1 mph			
Amplifiers	Seat pitch: +35 degrees			
Transducers				
Backup card data				
Manikin controls				
Colors and comm.				
Quit to DOS	Identify test data with a unique label to be used in naming binary and exchange data files. Descriptive text may also be added to identify test conditions.			

Figure B-1. Screen printout of the test identification menu which allows the user to enter a test label and additional comment associated with the test.

Test: LX65-56		MIDAS-3.0	Manikin Integrated DAS	13:06:32
Identify test	F1	EXTRACT data from THINCARD into RAM, and store them in MIDAS Internal Format on file	20 signals	LX65-56.MIF
▶ Extract signals	F2	SELECT from listed files ⇒ the name and type of MIDAS file to retrieve from disk	LX65-56.MIF LX65-55.MIF LX65-52.MIF LX65-45.MIF	
Process signals	F3	RETRIEVE the selected .MIF disk file into RAM memory.	LX65-44.MIF LX65-43.MIF	
Sampling setup	F4	RESTORE data from 3 backup files now on directory C:\NBDL\BACK\	LX65-56.ini LX65-56.pre LX65-56.dat	
Define channels	F5	EXPORT data to text file:	LX65-56.MXP	
Amplifiers				
Transducers				
Backup card data				
Manikin controls				
Colors and comm.				
Quit to DOS	Extract data from CC memory and save on hard disk in the desired format. Retrieve binary files from hard disk for plotting or export in another format.			

Figure B-2. Screen printout of the data extraction menu where the user selects the source and destination of the data to be extracted.

Test: LX65-56	MIDAS-3.0	Manikin Integrated DAS	13:06:57
Identify test	F1	Raw channels	
Extract signals	F2	Test/channel information	
► Process signals	F3	[3] Integral/derivative	
Sampling setup	F4	[2] Over-plot signals	
Define channels	F5	[3] Integral/derivative	
Amplifiers	F6	[6] Head triax & HIC	
Transducers	F7	[5] Triax and resultant	
Backup card data	F8	[5] Triax and resultant	
Manikin controls	F10	VGA: 640x480, 80x30	
Colors and comm.			
Quit to DOS			
Plot signals for screen quick look or hardcopy print. To print, LaserJet III printer port must already be defined with the DOS PRINT command.			

Figure B-3. Screen printout of the data processing and analysis menu. This menu opens several submenus where various types of signal analyses are allowed.

Test: LX65-56	MIDAS-3.0	Manikin Integrated DAS	13:07:29
Identify test	Sampling rate:	2500.0 Hz/channel (nominal)	
Extract signals	Actual:	2512.5 Hz per channel	
Process signals		.398 msec interval	
► Sampling setup	Sampling rate must match rate sent to manikin, other parameters may be re-defined after test.		
Define channels	Test duration:	597.0 msec = 1500 pts/ch	
Amplifiers	Trigger method:	SOFTWARE a signal FALLS BELOW threshold	
Transducers	Start of data:	-99.5 msec 250 pts BEFORE trigger	
Backup card data	Trigger signal:	Ch 15 = SLED	
Manikin controls	Threshold:	41 mV = 10.1 G BELOW initial level	
Colors and comm.			
Quit to DOS			
Define sampling rate, durations of pre- and post-test calibration lengths, pre-trigger delay and duration of test, all depending on the size of CC memory.			

Figure B-4. Screen printout of the menu to setup the data acquisition sampling rate and the parameters for impact detection and data extraction from the credit card.

Test: LX65-56	MIDAS-3.0	Manikin Integrated DAS	13:07:56
Identify test	(20)		A/D
Extract signals	ON	Label	channel
Process signals	01	AX-HEAD	Head X (forward) accel
Sampling setup	02	AY-HEAD	Head Y (lateral) accel
Define channels	03	AZ-HEAD	Head Z (vertical) accel
Amplifiers	04	AAZ-HEAD	Head Y (pitch) accel
Transducers	05	FZ-NECK	Neck Z (vertical) force
Backup card data	06	FX-NECK	Neck X (forward) force
Manikin controls	07	MY-NECK	Neck Y (pitch) moment
Colors and comm.	08	AX-T1	T1 X (forward) accel
Quit to DOS	09	AY-T1	T1 Y (lateral) accel
	10	AZ-T1	T1 Z (vertical) accel
	11	FZ-T1	T1 Z (vertical) force
	12	FX-T1	T1 X (forward) force
	13	MY-T1	T1 Y (pitch) moment
	14	MX-T1	T1 X (roll) moment
	15	SLED	Sled (external) accel
		Define and describe channels. Name engineering units for the signals. Designate signals which are to be extracted, stored, and displayed.	

Figure B-5. Screen printout of the menu to define channel labels and designate those active channels to be extracted after the test.

Test: LX65-56	MIDAS-3.0	Manikin Integrated DAS	13:09:21			
Identify test	(20)	DASS	Correction	Units @		
Extract signals	Ch	Label	Gain	Exp/actual	no load	Units
Process signals	01	AX-HEAD	100	1.000	.0000	G
Sampling setup	02	AY-HEAD	25	1.087	.0000	G
Define channels	03	AZ-HEAD	100	1.000	.0000	G
Amplifiers	04	AAZ-HEAD	100	1.000	.0000	krad/s2
Transducers	05	FZ-NECK	500	1.000	.0000	kN
Backup card data	06	FX-NECK	250	1.000	.0000	kN
Manikin controls	07	MY-NECK	250	1.000	.0000	kN-m
Colors and comm.	08	AX-T1	25	1.000	.0000	G
Quit to DOS	09	AY-T1	20	1.000	.0000	G
	10	AZ-T1	25	1.000	.0000	G
	11	FZ-T1	1000	1.000	.0000	kN
	12	FX-T1	250	1.000	.0000	kN
	13	MY-T1	250	1.000	.0000	kN-m
	14	MX-T1	250	1.000	.0000	kN-m
	15	SLED	1	.1000	.0000	G
Amplifier gains are defined here before sending them to the DASS in the manikin. Also, define slopes and intercepts of channel Out/In for correct calibration.						

Figure B-6. Screen printout of the menu to define the amplifiers gains in the data acquisition system, and to label the engineering units of each active channel.

Test: LX65-56	MIDAS-3.0	Manikin Integrated DAS	13:09:40		
Identify test	(20)	mV / Unit	Units/ADC		
Extract signals	Ch	Label	(@ gain=1)	Units	
Process signals	01	AX-HEAD	.5050	.2417E-01	G
	02	AY-HEAD	.5380	.9076E-01	G
	03	AZ-HEAD	.5570	.2192E-01	G
Sampling setup	04	AAY-HEAD	3.960	.3083E-02	krad/s2
	05	FZ-NECK	1.300	.1878E-02	kN
Define channels	06	FX-NECK	2.800	.1744E-02	kN
	07	MY-NECK	85.98	.5679E-04	kN-m
Amplifiers	08	AX-T1	2.430	.2009E-01	G
	09	AY-T1	2.440	.2501E-01	G
▶ Transducers	10	AZ-T1	2.440	.2001E-01	G
	11	FZ-T1	.8913	.1370E-02	kN
Backup card data	12	FX-T1	2.511	.1945E-02	kN
	13	MY-T1	47.60	.1026E-03	kN-m
Manikin controls	14	MX-T1	46.67	.1046E-03	kN-m
	15	SLED	4.070	.2999	G
Colors and comm.					
Quit to DOS	Transducers sensitivities (e.g., mV/G) may be edited. Overall factors to convert A/D counts to mechanical units are shown here for verification.				

Figure B-7. Screen printout of the menu to enter the transducers sensitivities of the manikin, as supplied by the manufacturers or determined from calibrations.

Test: LX65-56	MIDAS-3.0	Manikin Integrated DAS	13:10:43
Identify test	Page	Save credit card data on backup files	
Extract signals	Backup subdirectory:	C:\NBDL\BACK\	
Process signals	Configuration file:	1.INI	
Sampling setup	Pre-trigger data:	2.PRE	
Define channels	Post-trigger data:	3.DAT	
Amplifiers	Esc	Do NOT backup, CANCEL edit changes	
Transducers	F1	Do NOT backup, but SAVE file names	
Backup card data	F9	RE-WRITE modified file: LX65-56.MIF	
Manikin controls	Backup card data using TCREAD.EXE utility to create pre- & post-trigger (.PRE, .DAT) data files. Manikin configuration will also be saved on (.CFG) file.		
Colors and comm.			
Quit to DOS			

Figure B-8. Screen printout of the menu to backup credit card data and other labels and settings for later retrieval and analysis.

Test: LX65-56	MIDAS-3.0	Manikin Integrated DAS	13:11:03
Identify test	F1	send SAMPLING rate and ALL GAINS to DASS	
Extract signals	F2	send only SAMPLING rate = 2512 Hz to DASS	
Process signals	F3	send GAIN = 100x <7> to Ch 01 = AX-HEAD	
Sampling setup	F4	request pre-test calibration in DASS	
Define channels	F5	MONITOR: terminal mode over COM2 serial port	
Amplifiers	F6	request post-test calibration in DASS	
Transducers	F7	future use	
Backup card data	F8	send 3 ESC to DASS (to clear hung COM2 port)	
► Manikin controls	F9	arm manikin (put DASS in acquisition mode)	
Colors and comm.			
Quit to DOS		Control Panel for manikin: initializes manikin to specified configuration, arms manikin for trigger detection, and downloads acquired data from card.	

Figure B-9. Screen printout of the manikin controls menu which allows communication with the manikin internal data acquisition subsystem over serial communication port.

Test: LX65-56	MIDAS-3.0	Manikin Integrated DAS	13:12:08
Identify test	F1	send SAMPLING rate and ALL GAINS to DASS	
Extract signals	F2	send only SAMPLING rate = 2512 Hz to DASS	
Process signals	F3	send GAIN = 100x <7> to Ch 01 = AX-HEAD	
Sampling setup	F4	request pre-test calibration in DASS	
Define channels	F5	MONITOR: terminal mode over COM2 serial port	
Amplifiers			
Transducers			
Backup card data			
► Manikin controls			
Colors and comm.			
Quit to DOS			
			Port status byte COM2: 0110 0000
			Del clear window End exit monitor
		Control Panel for manikin: initializes manikin to specified configuration, arms manikin for trigger detection, and downloads acquired data from card.	

Figure B-10. Screen printout of the manikin controls menu when the "monitor" mode is activated allowing synchronous serial communication with the manikin.

Test: LX65-56		MIDAS-3.0		Manikin Integrated DAS		13:12:32	
Identify test Extract signals Process signals Sampling setup Define channels Amplifiers Transducers Backup card data Manikin controls ► Colors and comm. Quit to DOS	Static	Lo	Hi	<div style="border: 1px solid black; padding: 5px; display: inline-block;"> <div style="text-align: center;">COLORS</div> <div>Static Static</div> <div>Dynamic Dynamic</div> <div>Key Key Key</div> <div>Message Message</div> </div>			
	Dynamic	Lo	Hi				
	Buttons	Lo	Hi				
	Messages	Lo	Hi				
	F	B	colors				
Speaker		Port	Baud	Parity	Word	Stop	
On		COM2	1200	None	8-bit	1-bit	
Change color scheme of this program, and parameters of serial port that communicates with the manikin.							

Figure B-11. Screen printout of the menu to setup the colors and communication port parameters. Choosing colors becomes important for laptop LCD screens.

F1	Raw channels	F2	Test/channel information
F3	[1] Cross-plot signals	F4	[2] Over-plot signals
F5	[3] Integral/derivative	F6	[4] 1st/2nd integrals
F7	[5] Triax and resultant	F8	[6] Head triax & HIC
F9	Execute all ◀▶ functions	F10	VGA: 640x480, 80x30

Fn or Enter	screen output	Alt - Fn	parameters	Tab	form/graph
				Esc	exit

01 = AX-HEAD = Head X (forward) accel	01	<div style="border: 1px solid black; padding: 10px; display: inline-block;"> ----- ----- ----- ----- ----- ----- ----- ----- ----- ----- </div>
02 = AY-HEAD = Head Y (lateral) accel	02	
03 = AZ-HEAD = Head Z (vertical) accel	03	
04 = AAY-HEAD = Head Y (pitch) accel	05	
05 = FZ-NECK = Neck Z (vertical) force	06	
06 = FX-NECK = Neck X (forward) force	15	
07 = MY-NECK = Neck Y (pitch) moment		
08 = AX-T1 = T1 X (forward) accel		
09 = AY-T1 = T1 Y (lateral) accel		
10 = AZ-T1 = T1 Z (vertical) accel		

Analysis span 6APRTST3

Figure B-12. Screen printout of data processing sub-menu which allows the selection of up to six channels to be graphically displayed, in raw form, on the screen.

F1	Raw channels	F2	Test/channel information
F3	[1] Cross-plot signals	F4	[2] Over-plot signals
F5	[3] Integral/derivative	F6	[4] 1st/2nd integrals
F7	[5] Triax and resultant	F8	[6] Head triax & HIC
F9	Execute all ◀▶ functions	F10	VGA: 640x480, 80x30
Ctrl - Fn hardcopy output		Alt - Fn parameters	Tab form/graph
			Esc exit
01 = AX-HEAD	= Head X (forward) accel	01	-----
02 = AY-HEAD	= Head Y (lateral) accel	02	-----
03 = AZ-HEAD	= Head Z (vertical) accel	03	-----
04 = AAY-HEAD	= Head Y (pitch) accel	04	-----
05 = FZ-NECK	= Neck Z (vertical) force		
06 = FX-NECK	= Neck X (forward) force		
07 = MY-NECK	= Neck Y (pitch) moment		
08 = AX-T1	= T1 X (forward) accel		
09 = AY-T1	= T1 Y (lateral) accel		
10 = AZ-T1	= T1 Z (vertical) accel		
		HARDCOPY	6APRTST3 ↑A

Figure B-13. Screen printout of the data processing submenu allowing the selection of up to four channels to be plotted in portrait format "A" hard copy for quick look.

F1	Raw channels	F2	Test/channel information
F3	[1] Cross-plot signals	F4	[2] Over-plot signals
F5	[3] Integral/derivative	F6	[4] 1st/2nd integrals
F7	[5] Triax and resultant	F8	[6] Head triax & HIC
F9	Execute all ◀▶ functions	F10	VGA: 640x480, 80x30
Ctrl - Fn hardcopy output		Alt - Fn parameters	Tab form/graph
			Esc exit
01 = AX-HEAD	= Head X (forward) accel	01	-----
02 = AY-HEAD	= Head Y (lateral) accel	02	-----
03 = AZ-HEAD	= Head Z (vertical) accel	03	-----
04 = AAY-HEAD	= Head Y (pitch) accel	04	-----
05 = FZ-NECK	= Neck Z (vertical) force	05	-----
06 = FX-NECK	= Neck X (forward) force	06	-----
07 = MY-NECK	= Neck Y (pitch) moment	07	-----
08 = AX-T1	= T1 X (forward) accel	08	-----
09 = AY-T1	= T1 Y (lateral) accel	09	-----
10 = AZ-T1	= T1 Z (vertical) accel		
		HARDCOPY	6APRTST3 2B

Figure B-14. Screen printout of the data processing submenu allowing the selection of up to nine channels to be plotted in portrait format "B" hard copy for quick look.

F1	Raw channels	F2	Test/channel information
F3	[1] Cross-plot signals	F4	[2] Over-plot signals
F5	[3] Integral/derivative	F6	[4] 1st/2nd integrals
F7	[5] Triax and resultant	F8	[6] Head triax & HIC
F9	Execute all ◀▶ functions	F10	VGA: 640x480, 80x30
Ctrl - Fn hardcopy output		Alt - Fn parameters	Tab form/graph
			Esc exit
01 = AX-HEAD	= Head X (forward) accel	01	-----
02 = AY-HEAD	= Head Y (lateral) accel	02	-----
03 = AZ-HEAD	= Head Z (vertical) accel	03	-----
04 = AAY-HEAD	= Head Y (pitch) accel	04	-----
05 = FZ-NECK	= Neck Z (vertical) force		
06 = FX-NECK	= Neck X (forward) force		
07 = MY-NECK	= Neck Y (pitch) moment		
08 = AX-T1	= T1 X (forward) accel		
09 = AY-T1	= T1 Y (lateral) accel		
10 = AZ-T1	= T1 Z (vertical) accel	HARDCOPY	6APRTST3 ↑C

Figure B-15. Screen printout of the data processing submenu allowing the selection of up to four channels to be plotted in landscape format "C" hard copy for quick look.

F1	Raw channels	F2	Test/channel information
F3	[1] Cross-plot signals	F4	[2] Over-plot signals
F5	[3] Integral/derivative	F6	[4] 1st/2nd integrals
F7	[5] Triax and resultant	F8	[6] Head triax & HIC
F9	Execute all ◀▶ functions	F10	VGA: 640x480, 80x30
Ctrl - Fn hardcopy output		Alt - Fn parameters	Tab form/graph
			Esc exit
01 = AX-HEAD	= Head X (forward) accel	01	-----
02 = AY-HEAD	= Head Y (lateral) accel	02	-----
03 = AZ-HEAD	= Head Z (vertical) accel	03	-----
04 = AAY-HEAD	= Head Y (pitch) accel	04	-----
05 = FZ-NECK	= Neck Z (vertical) force	05	-----
06 = FX-NECK	= Neck X (forward) force	06	-----
07 = MY-NECK	= Neck Y (pitch) moment	07	-----
08 = AX-T1	= T1 X (forward) accel	08	-----
09 = AY-T1	= T1 Y (lateral) accel	09	-----
10 = AZ-T1	= T1 Z (vertical) accel	HARDCOPY	6APRTST3 2D

Figure B-16. Screen printout of the data processing submenu allowing the selection of up to nine channels to be plotted in landscape format "D" hard copy for quick look.

F1	Raw channels	F2	Test/channel information
F3	[1] Cross-plot signals	F4	[2] Over-plot signals
F5	[3] Integral/derivative	F6	[4] 1st/2nd integrals
F7	[5] Triax and resultant	F8	[6] Head triax & HIC
F9	Execute all ◀▶ functions	F10	VGA: 640x480, 80x30
Ctrl - Fn hardcopy output		Alt - Fn parameters	Tab form/graph
			Esc exit
01 = AX-HEAD	= Head X (forward) accel	01 -----	05 -----
02 = AY-HEAD	= Head Y (lateral) accel	02 -----	06 -----
03 = AZ-HEAD	= Head Z (vertical) accel	03 -----	07 -----
04 = AAY-HEAD	= Head Y (pitch) accel	04 -----	08 -----
05 = FZ-NECK	= Neck Z (vertical) force		
06 = FX-NECK	= Neck X (forward) force		
07 = MY-NECK	= Neck Y (pitch) moment		
08 = AX-T1	= T1 X (forward) accel		
09 = AY-T1	= T1 Y (lateral) accel		
10 = AZ-T1	= T1 Z (vertical) accel	HARDCOPY	6APRTST3 3E

Figure B-17. Screen printout of the data processing submenu allowing the selection of up to eight channels to be plotted in two columns in landscape format "E" hard copy for quick look.

F1	Raw channels	F2	Test/channel information
F3	[1] Cross-plot signals	F4	[2] Over-plot signals
F5	[3] Integral/derivative	F6	[4] 1st/2nd integrals
F7	[5] Triax and resultant	F8	[6] Head triax & HIC
F9	Execute all ◀▶ functions	F10	VGA: 640x480, 80x30
Ctrl - Fn hardcopy output		Alt - Fn parameters	Tab form/graph
			Esc exit
01 = AX-HEAD	= Head X (forward) accel	01 -----	10 -----
02 = AY-HEAD	= Head Y (lateral) accel	02 -----	11 -----
03 = AZ-HEAD	= Head Z (vertical) accel	03 -----	12 -----
04 = AAY-HEAD	= Head Y (pitch) accel	04 -----	13 -----
05 = FZ-NECK	= Neck Z (vertical) force	05 -----	14 -----
06 = FX-NECK	= Neck X (forward) force	06 -----	15 -----
07 = MY-NECK	= Neck Y (pitch) moment	07 -----	16 -----
08 = AX-T1	= T1 X (forward) accel	08 -----	17 -----
09 = AY-T1	= T1 Y (lateral) accel	09 -----	18 -----
10 = AZ-T1	= T1 Z (vertical) accel	HARDCOPY	6APRTST3 1F

Figure B-18. Screen printout of the data processing sub-menu allowing the selection of up to 18 channels to be plotted in landscape format "F" hard copy for quick look.

F1	Raw channels	◄►	F2	Test/channel information
F3	[3] Integral/derivative		F4	[2] Over-plot signals
F5	[3] Integral/derivative		F6	[2] Over-plot signals
F7	[1] Cross-plot signals		F8	[2] Over-plot signals
F9	Execute all ◄► functions		F10	VGA: 640x480, 80x30
Ctrl - Fn hardcopy output Ins mark for hardcopy Esc exit				
Test LX65-56 1500 pts @ 2512.5 Hz = 597.0 ms long Descript.: Dynamic testing of MIDAS prototype crash manikin Sled acceleration pulse: 10.3 peak G, 23.1 mph Seat pitch: +35 degrees 20 channels: 01 - 20 Analysis: 59.7 ms Span: .0 to 59.7 ms.				

Figure B-19. Screen printout of the data processing submenu showing test information and allowing the printing of hard copy of pertinent information.

F1	Raw channels	F2	Test/channel information
F3	[3] Integral/derivative	F4	[2] Over-plot signals
◄► F5	[3] Integral/derivative	F6	[2] Over-plot signals
F7	[1] Cross-plot signals	F8	[2] Over-plot signals
F9	Execute all ◄► functions	F10	VGA: 640x480, 80x30
Fn or Enter screen output Alt - Fn parameters Tab form/graph			
Ctrl - Fn hardcopy output Ins mark for hardcopy Esc exit			
Signals: 05 FZ-NECK First integral times 1.0000 First derivative times 1.0000 Filter: 100 Hz Set integral BEG. = 0 (LP) 24 dB/oct Labels: Head axial (Z) force Head Z (G) (kN) LX65-56 Caption: 7 Gx run, WITHOUT cushion			

Figure B-20. Screen printout of the data processing submenu showing (bottom third) parameters for integral/derivative analysis and allowing the user to modify the parameters.

F1	Raw channels	F2	Test/channel information
F3	[3] Integral/derivative	◄► F4	[2] Over-plot signals
F5	[3] Integral/derivative	F6	[2] Over-plot signals
F7	[1] Cross-plot signals	F8	[2] Over-plot signals
F9	Execute all ◄► functions	F10	VGA: 640x480, 80x30
Fn or Enter screen output Alt - Fn parameters Tab form/graph Ctrl - Fn hardcopy output Ins mark for hardcopy Esc exit			
Signals: 10 AZ-T1 (Left vertical) 00 Seat pit (Right vertical) Filter: 100 Hz (LP) 24 dB/oct Labels: Neck (C1) axial force (kN) LX65-56 Caption: 7 Gx run WITHOUT cushion			

Figure B-21. Screen printout of the data processing submenu showing parameters for over-plot of two signals. This analysis also allows plotting of a single channel.

F1	Raw channels	F2	Test/channel information
F3	[3] Integral/derivative	F4	[2] Over-plot signals
F5	[3] Integral/derivative	F6	[2] Over-plot signals
◄► F7	[5] Triax and resultant	F8	[2] Over-plot signals
F9	Execute all ◄► functions	F10	VGA: 640x480, 80x30
Fn or Enter screen output Alt - Fn parameters Tab form/graph Ctrl - Fn hardcopy output Ins mark for hardcopy Esc exit			
Signals: 01 AX-HEAD 02 AY-HEAD 03 AZ-HEAD Tri-axial resultant Filter: 100 Hz (LP) 24 dB/oct Labels: Head X Head Y Head Z Head resultant accel (G) (G) (G) (G) LX65-56 Caption: 7 Gx run WITHOUT cushion			

Figure B-22. Screen printout of the data processing submenu showing (bottom third) the parameters selected to analyze a triaxial cluster of transducers.

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