

# Analysis of Thermal Imagery Collected at Grayling 1 Grayling, Michigan

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U.S. Army Engineer Waterways Experiment Station Vicksburg, MS



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#### FOREWORD

SWOE Report 94-2, January 1994, was prepared by S. Rivera, Jr. of U.S. Army Engineer Waterways Experiment Station, Vicksburg, Mississippi.

This report is a contribution to the Smart Weapons Operability Enhancement (SWOE) Program. SWOE is a coordinated, Army, Navy, Marine Corps, Air Force and ARPA program initiated to enhance performance of future smart weapon systems through an integrated process of applying knowledge of the broadest possible range of battlefield conditions.

Performance of smart weapons can vary widely, depending on the environment in which the systems operate. Temporal and spatial dynamics significantly impact weapon performance. Testing of developmental weapon systems has been limited to a few selected combinations of targets and environmental conditions, primarily because of the high costs of full-scale field tests and limited access to the areas or events for which performance data are required.

Performance predictions are needed for a broad range of battlefield environmental conditions and targets. Meeting this need takes advantage of significant DoD investments by Army, Navy, Marine Corps and Air Force in 1) basic and applied environmental research, data collection, analysis, modeling and rendering capabilities, 2) extensive target measurement capabilities and geometry models, and 3) currently available computational capabilities. The SWOE program takes advantage of these DoD investments to produce an integrated process, the SWOE Process.

SWOE is developing, validating, and demonstrating the capability of the SWOE Process to handle complex target and environment interactions for a broad range of battlefield conditions. SWOE is providing the DoD smart weapons and autonomous target recognition (ATR) communities with a validated capability to integrate measurements, information bases, modeling, and simulation techniques for complex environments. This is a DoD-wide partnership that works in concert with advanced weapon system developers and major weapon system test and evaluation programs.

The SWOE program started in FY89 under Balanced Technology Initiative (BTI) sponsorship. Present sponsorship is by the U.S. Army Corps of Engineers (lead service), the individual services, and the Joint Test and Evaluation (JT&E) program of the Office of the Director of Test & Evaluation, Office of the Under Secretary of Defense OUSD(A/DT&E).

The Joint Test Director is Dr. J.P. Welsh. The Deputy Test Directors are: (Army) LTC Jerre Wilson and (Air Force) Maj Richard Jennings. The Integration Manager is Mr. Richard Palmer. The Modeling Configuration Manager is Dr. George G. Koenig.



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<ul> <li>13. ABSTRACT (Maximum 200 words)</li> <li>The purpose of the Smart Weapons Operability Enhancement (SWOE) Joint Test and Evaluation Program is to validate the SWOE synthetic scene generation procedure. Once validated, this procedure will hopefully change the design-test-redesign approach to smart weapons development, test, and evaluation. Using the SWOE process, smart weapons designers will be able to evaluate their sensor algorithms on simulated scenes with a greater degree of variability than is often presented during the test phase of the design process. The SWOE process will also allow for the smart weapon designs to be evaluated for different environments without the need for expensive and time-consuming data collection exercises.</li> <li>This report is an analysis of thermal data collected by the U.S. Army Engineer Waterways Experiment Station during the Grayling 1 field program 15 September-30 October 1992 to help understand variations in image characteristics using image metrics and to present data in a format that could be used for synthetic image validation tasks.</li> <li>The report also describes in graphical format the meteorological and terrain data at the time the infrared imagery data were collected and correlates measured data with meteorological and terrain data.</li> </ul>					
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### Preface

The analysis activities reported herein were conducted by the U.S. Army Engineer Waterways Experiment Station (WES) is support of the Smart Weapons Operability Enhancement (SWOE) Joint Test and Evaluation (JT&E) Grayling 1 exercise conducted at Grayling, MI, from 15 September to 25 October 1992. This effort was funded by the Department of Defense SWOE JT&E Program Office, Hanover, NH. Dr. J. Pat Welsh was the Joint Test Director. LTC Jerre W. Wilson was Army Deputy Director, SWOE JT&E.

WES has prepared three related reports in support of the Grayling 1 exercise for the SWOE JT&E Program. These are as follows:

- a. "Grayling 1 Information Base for Generation of Synthetic Thermal Scenes"
- b. "Grayling 1 Site Characterization and Data Summary"
- c. "Analysis of Thermal Imagery Collected at Grayling 1, Grayling, Michigan"

This study was conducted under the general supervision of Dr. John Harrison, Director, Environmental Laboratory (EL), WES, and Mr. H. Roger Hamilton, Acting Chief, Natural Resources Division (NRD), EL, and Mr. Harold W. West, Chief, Environmental Characterization Branch (ECB), NRD, and under the direct supervision of Mr. Charles D. Hahn, WES project coordinator.

Mr. Salvador Rivera, Jr., ECB, prepared this report. Field support was provided by Messrs. Hahn, Thomas Berry, Marvin J. Wooley, David Leese, Clarence Currie, Alfonzo Vasquez, Jerrell R. Ballard, and Stephen Pranger. Mr. Bruce Sabol, ECB, assisted in the image analysis

At the time of publication of this report, Director of WES was Dr. Robert W. Whalin. Commander was COL Bruce K. Howard, EN.

### **1** Introduction

The Smart Weapons Operability Enhancement (SWOE) Joint Test and Evaluation (JT&E) Program is a Department of Defense (DOD) coordinated multiservice effort to address problems related to smart weapon system development, test, and evaluation (DT&E) in the worldwide range of battlefield environment conditions. The thrust of the Grayling 1 field exercise was to collect environmental data necessary to generate various synthetic thermal scenes and to collect thermal infrared (IR) image data for use in the validation of the SWOE thermal scene generation procedure.

### Background

Future smart weapons systems will be forced to become more "autonomous" because of the ever-shrinking manpower available on the modern battlefield. The typical approach to developing smart weapons has been the test-fix-test methodology for the test and evaluation phases of development. Tests or technology demonstrations are scheduled, and the proposed system is thoroughly tested under various environmental conditions. The results, however, may not be similar if the environmental conditions are changed. Also, the cost of this type of testing is extremely high. The primary thrust of the SWOE JT&E Program is to produce a validated procedure for generation of synthetic thermal and millimeter wave images that accurately model the environmental conditions and can then be processed through the sensor and sensor logic to produce results representative of those from a weapon system captive flight demonstration, all at a much lower cost. An added benefit of this analytical procedure allows the environmental conditions to be changed so that the sensor logic may be evaluated over a variety of background and weather conditions quickly and efficiently.

### **Objectives**

The objectives of this report are as follows:

- a. To conduct an analysis of thermal data collected by the U.S. Army Engineer Waterways Experiment Station (WES) during the Grayling 1 field program 15 September-30 October 1992 to help understand variations in image characteristics using image metrics, and to present the data in a format that could be used for synthetic image validation tasks.
- b. To describe in graphical format the meteorological and terrain data at the time the IR imagery data were collected and correlate measured data with meteorological and terrain data.

#### Scope

The intent of this report is to describe the analysis of WES IR imagery. The data and results are presented in a format useful for synthetic image validation tasks. The final image data are stored in the SWOE program database managed by the SWOE Program Office, Hanover, NH, and made available to the development, test, and evaluation community.

## 2 Summary of Image Data Collected

### **Image Geometry**

Image data were collected by WES using a ground-based system at Grayling, MI, from September 15 to October 30, 1992. Figure 1 shows a photograph of Site E and surrounding areas that was imaged with a 20-deg lens throughout the field program. Given the importance of features surrounding the Site E area, this study takes into consideration all the information within the field of view (FOV). The dominant terrain features that composed this scene are a large oak tree (deciduous) in the center, three evergreen trees (coniferous) on the left, two small evergreen and one oak tree in the foreground, soil with very short grass, a sandy road or vehicle test track in the background, and a tree line (mixture of coniferous and deciduous trees) just beyond the test track. The approximate image geometry was an azimuth of 76°58'55" (grid north reference), an elevation angle of 99°47'53" (measured from vertical), and a slant range of 147.9 m (=distance from WES camera to center of Site E area imaged). The camera was located at universal transverse Mercator (UTM) coordinates 687083E 4951896N and at a height of 17.2 m above the ground surface.

### Description and Summary of Image Data Collected

The WES imaging equipment consisted of a far infrared (long wave band (LWB)) and a midinfrared (short wave band (SWB)) thermal imager. All the analysis on the SWB imagery includes the reflected and emitted component. An LWB and SWB IR image of Site E and surrounding area are shown in Figures 2 and 3, respectively. The WES thermal cameras had 20-deg FOV lenses; the specifications for these cameras are shown in

Table 1. Appendix A offers a general explanation of the image data collection procedure; another report provides a more in-depth explanation.<sup>1</sup>

The imaging schedule (see Table 2) was arranged so that 107 2-hr image data collection missions would be accomplished during the SWOE Grayling 1 effort. One image frame was collected per second for 10 sec. These imaging periods were conducted at 5-min intervals throughout the established 2-hr data collection period. For program purposes, every 5-min time count was known as a pass (or section); at the end of a 2-hr imaging, there were 25 passes. One particular pass and frame was randomly selected and designated the critical frame. All the analysis in these reports is based on the critical frame.

The 107 data collection missions were executed under a broad variety of meteorological conditions. Another report gives a summary of meteorological data.<sup>1</sup> Of the total missions, 52 percent were accomplished during nighttime conditions. Figure 4 illustrates a frequency histogram of the air temperature values during the critical frames. The figure reflects that 14 percent of the missions were executed under temperatures below freezing, 41 percent at air temperatures between 0 and 10 °C, 42 percent at air temperatures between 10 and 20 °C, and 3 percent at air temperatures above 20 °C. By 04 October, the leaves on the deciduous trees within the site had started to turn color (red); by 13 October, the leaves were completely red. Between the dates 16 October-21 October, there were some critical frames with either snowfall/snow precipitation, snow cover on the ground and snow collected on the trees or no snow at all.

<sup>&</sup>lt;sup>1</sup> Hahn, C. D., and Berry, T. E. (1994). "Grayling 1 site characterization and data summary," Technical Report prepared by the U.S. Army Engineer Waterways Experiment Station, Vicksburg, MS, for the Smart Weapons Operability Enhancement Joint Test and Evaluation Program Office, Hanover, NH.

## 3 Imagery Analysis Procedures

### Image Metrics Computed

Image metrics were used to quantify the distribution of specific features within a digital image. Nine different scene metrics were computed in this study. All of these characterize the data-space distribution of temperature in degrees Celsius. Processing was initiated by generating histograms of digital level values within the designated region. Eight measures are computed from the histogram: the minimum value (MIN), the 5-percentile value (PERC\_05), the median value (MEDIAN), the mode (MODE), the 95-percentile value (PERC\_95), the maximum value (MAX), and the difference between the 95- and 5-percentile (RNG\_90). The first and second moments of the distribution of digital level values within the designated region (mean and standard deviation) are also computed. Results were converted to temperature by substituting them (and camera calibration constant) into Planck's equation.

### Phase I: Image Quality Assurance Analysis

A procedure was employed to verify the accuracy of the radiometric temperature estimates and to ensure that the manual settings of all images were within dynamic range. This procedure also allowed identification and elimination of image data with noise other than that resulting from the scanner. This image noise was possible given the numerous external electric sources operating at the same time at the site where data were collected. Figure 5 shows a flowchart describing the several image quality tests used to ensure that the final imagery set was within calibration, within dynamic range, and without noise. Imagery that did not pass these tests was discarded. At the end, a confirmation analysis was performed by processing WES and Atmospheric Research Laboratory (ARL) IR data (both wave bands) and comparing the mean temperature and standard deviation of the features for all the critical frames. Assuming that both systems are operating at factory calibration, the mean temperature difference of the features

should be within  $\pm 3$  °C and the standard deviation difference within  $\pm 0.5$  °C.

At the beginning and end of each of the 107 missions (refer to Appendix A for more details), an IR image of the four active blackbodies was taken, along with the actual (truth) temperature of each blackbody. The purpose was to implement the first image quality test, which consists of verifying that the absolute error between the actual temperature and estimated radiometric temperature is within  $\pm 3$  °C, which was the criteria for acceptance. A linear regression analysis was applied to the data that did not meet the criteria for acceptance. Data were accepted if they met the criteria for acceptance after the linear regression. Otherwise, the data were discarded. This analysis was applied to blackbody data collected before 120CT92:14:00 because the remaining data was considered spurious. The next paragraphs will show that IR data (both wave bands) collected after 120CT92:14:00 met calibration criteria.

Figure 6a shows a plot of the absolute error versus date for all the active blackbody data in the LWB collected throughout the field exercise. Each of the plots shows a band (horizontal lines) of  $\pm 3$  °C, the calibration criteria for acceptance. This plot indicates that most of the data met the criteria for acceptance. Figure 6b shows a frequency histogram of the absolute error, indicating that 99 percent of the data met the criteria for acceptance. Therefore, the factory calibration of the LWB camera needed no correction.

Figure 7a shows a plot of the absolute error versus date for all the blackbody data in the SWB collected during the field exercise. This plot indicates that most of the data is within  $\pm 3$  °C, with the exception of the imagery collected before 29SEP92:02:00. Figure 7b is a frequency histogram of the absolute error, showing that 93 percent of the data are within the criteria for acceptance. A linear regression was performed on the data collected before 29SEP92:02:00 to obtain an equation to correct the data. Figure 8 offers the result of this analysis (Figure 8a) where 98 percent of the data (Figure 8b) subsequently satisfied the criteria for acceptance. Imagery collected before 29SEP92:02:00 was corrected using this equation: (NEW\_TEMP=0.984\*OLD\_TEMP-2.269).

As part of the second image quality test, all the imagery collected were checked, given that cameras require manual setting of the levels and ranges, to ensure that the imagery were within dynamic range. Images with more than 2 percent of the brightness values (8 bit radiometric resolution) less than 5 or greater than 250 were rejected.

The third and last image quality test consisted of visually identifying image data with noise other than the noise due to the scanner. Once identified, these image data were processed using a Fast Fourier Transform (FFT) transforming them to the frequency domain. Low pass filter was then applied to eliminate all undesired high frequencies (noise). The image data were then transformed back to the spatial domain. If the noise test failed, the image data were rejected.

At the end, a confirmation analysis was performed by processing WES and ARL IR data (both wave bands) and comparing the feature's mean temperature and standard deviation for all the critical frames. Assuming that both systems are operating at factory calibration, the feature's mean temperature difference should be within ±3 °C and the feature's standard deviation difference within ±0.5 °C. Figures 9-12 show for the features grassy area, coniferous tree, deciduous tree, and test track, respectively, histograms of the difference in mean temperature and standard deviation between WES and ARL IR data. Figures 9a-12a show a histogram for the LWB data of frequency versus feature mean temperature difference. Figures 9b-12b show a histogram for the LWB data of frequency versus feature standard deviation difference. Figures 9c-12c show a histogram for the SWB data of frequency versus feature mean temperature difference. Figures 9d-12d show a histogram for the SWB data of frequency versus feature standard deviation difference. These histograms reflect that, for any feature/wave band combination, the mean temperature difference is within ±3 °C (WES and ARL absolute temperature accuracy is  $\pm 3$  °C and  $\pm 1$  °C, respectively). The standard deviation difference is within ±0.5 °C. After confirmation results were examined, the LWB and SWB IR data were used for further analysis.

Table 3 summarizes data based on 107 test missions. In the LWB, 83 percent of the data was considered acceptable; in the SWB, 79 percent of the data was considered acceptable.

#### Phase II: Overall Scene Analysis

Appendix B shows a listing of the image metric database for the critical frames. The information contained in the listing includes the date-time when the critical image was collected (IMAGE\_DT), date-time when the mission was started (MISSN\_DT), wave band to which the image belongs (WAVEBAND), mission number (MISSION), pass number (PASS), frame number (FRAME), and nine image metrics.

One of the first steps when analyzing IR image data is to determine the mean temperature and variability. Figure 13 shows a three-dimensional (3-D) plot of the frequency count of the image mean temperature and standard deviation (degrees Celsius) for all the critical frame data. For the LWB data (Figure 13a), 83 percent of the image data had a mean temperature between 0.0 and 20.0 °C. Also, 80 percent of the image data show very little thermal variation with standard deviation between 0.0 and 1.0 °C. The two highest peaks had a mean and standard deviation of the following (respectively):

(1) 0 and 1  $^{\circ}$ C (8 percent of data).

(2) 7.5 and 1  $^{\circ}$ C (10 percent of data).

In the SWB data (Figure 13b) 90 percent of the image data had a mean temperature between 5.0 and 20.0 °C. Also, 86 percent of the image data showed very little thermal variation, with standard deviation between 0.0 and 1.0 °C. The six highest peaks had a mean and standard deviation of the following (respectively):

- (1) 5 and 0 °C (9 percent of data).
- (2) 12.5 and 0 °C (10 percent of data).
- (3) 20 and 0 °C (9 percent of data).
- (4) 10 and 1  $^{\circ}$ C (9 percent of data).
- (5) 12.5 and 1  $^{\circ}$ C (9 percent of data).
- (6) 15 and 1  $^{\circ}$ C (9 percent of data).

To illustrate variability, Figure 14 shows a frequency count histogram of the temperature range (RNG\_90) of all the data processed for both wave bands. In the LWB, 90 percent of the data had a temperature range of 6 °C or less, while 90 percent of the SWB data showed a temperature range of 5 °C or less.

### Phase III: Scene Component Analysis

This analysis consisted of selecting several features/areas of interest (FOI or AOI) that were considered homogeneous within the scene (see Figure 1). Mean temperature and standard deviation were first computed for the AOI; analysis included a large red oak tree (deciduous) near the center of the scene, the smaller groups of evergreen trees (coniferous) to the left of the oak tree, a grassy area in the foreground, and a stretch of the test track in the background of the scene. These statistics were computed using all the pixels within the polygons enclosing each of the features. A database was generated with the mean temperature and the standard deviation of the features (grassy area, coniferous tree, deciduous tree, and test track) in Site E and surrounding areas.

For each wave band, the air temperature and the feature's mean temperatures bounded by one standard deviation were plotted (Figures 15a and 15b, respectively). In both wave bands, the grassy area followed by the test track exhibited warmer temperatures and more thermal variability than the deciduous and coniferous trees. The deciduous and coniferous trees exhibited very similar temperatures throughout the data collection time. After 07 October, all the features exhibited minimal thermal variability; during the same time, the air temperature remained cool (average 5 °C) until 23 October. In general, comparing the plots for each wave band indicates that the SWB data exhibited warmer temperatures and more thermal variability than the LWB data. Comparing the air temperature with the feature's mean temperature indicates that the temperature of the coniferous and deciduous trees tracked the air temperature very closely, although it was more noticeable in the LWB than in the SWB. Appendix B shows a listing of the image metrics computed on the entire image and the five features composing the image.

#### Phase IV: Within Pass Scene Analysis

The purpose of this analysis was to determine whether the scene changed significantly during the 10-sec imaging period. This analysis consisted of performing pairwise comparison of the cumulative percent distribution of all possible images within the 10-sec period. The Kolmogorov-Smirnov<sup>1</sup> like test was used to detect differences. Results were plotted as average Smirnov test statistics as a function of a time lag between images, and the trend of the line was used to determine whether these 10 images change significantly with time. The following procedure was used for 10 images collected 10 sec apart:

- a. A frequency histogram of the digital value distribution of each of the 10 images was first generated.
- b. The distributions were then normalized by constructing a cumulative percent histogram from the frequency histogram of the 10 images.
- c. Using the cumulative percent histogram, the greatest vertical distance (T) was computed for every possible combination. Figure 16 is an illustration of a frequency histogram and cumulative percent histogram for two images. Table 4 was produced by computing T for every possible combination among all 10 images.
- d. The adjacent observations were obtained for the nine possible lag times.
- e. All observations were averaged for a particular lag time, and a plot was generated of the average T versus lag time.
- f. The trend (of the line) was analyzed to determine whether the line changed significantly in 10 sec and whether or not it was dependent on time.

Lag time (seconds)	Number of observations
1	9
2	8
3	7
4	6
5	5
6	4
7	3
8	2
9	1
Total number of observations	45

<sup>&</sup>lt;sup>1</sup> Conover, W. J. (1971). *Practical nonparametrics statistics*. John Wiley and Sons, Inc., New York.

As part of the analysis, the missions were also grouped by the type of weather conditions in which they occurred. The four weather condition groups were sunny day, partly cloudy day, cloudy day, and nighttime. For each group, three image missions were selected; critical passes (10 images each) were analyzed for each of those selected.

Figures 17 and 18 show, for the LWB and SWB, respectively, a plot for each of the four weather condition groups. Each plot shows the trend of T with respect to time for each critical pass. In the SWB (Figure 18), the trend illustrates that the critical pass images from mission No. 71 (a partly cloudy day) changed significantly with time. All the other critical pass images at different weather conditions showed no change with time. The same observations were noticed in the LWB (Figure 17).

## 4 Correlation of Measured Data with Terrain and Meteorological Data

IR data were collected under a broad variety of meteorological conditions that affects the IR signatures of the imaged features within Site E and surrounding areas (Figure 1). Some meteorological factors that occurred during the data collection were dense fog, rain and snow precipitation. These factors affect (block) the feature's infrared energy being measured by the scanner. High content of soil moisture because of rain and snow precipitation as well as snow accumulation on trees, grass, and ground also affects IR signatures on natural background materials. During the data collection period, there was a wide variety of sunny, partly cloudy, and cloudy days. Air temperature, relative humidity, wind speed, and wind direction also exhibited a wide range of values. The purpose of this section is to illustrate by graphics and tables the meteorological and terrain conditions that occurred during the collection of the IR imagery. In addition, this section will correlate the mean temperature and standard deviation of the critical frame imagery with the meteorological and terrain conditions.

#### Measured Data

Figure 19 illustrates, for most of the 107 critical frames, the image mean apparent temperature bounded by the standard deviation in the LWB and SWB. The image mean apparent temperature for both wave bands exhibited a wide range of temperatures fluctuating approximately between -7 and 27 °C. Cool temperatures are grouped between missions No. 70 (12 October 1992) and No. 100 (22 October 1992), while warm temperatures are grouped between missions No. 15 (19 September 1992) and No. 55 (06 October 1992). The imagery in both wave bands exhibited a maximum thermal variability between missions No. 10 (17 September 1992) and No. 55 (06 October 1992).

A scene component analysis was performed in which each of the features was examined individually (See Scene Component Analysis section for more information). Figure 15 shows the mean temperature of the features bounded by standard deviation for the four features composing the image (grassy area, coniferous tree, deciduous tree, and test track). The mean temperature for all the features fluctuates considerably throughout the 45 days of data collection (-8 to 30 °C). The features exhibit more thermal variability in the SWB data than in the LWB data.

### **Meteorological and Terrain Data**

During the test, the WES team recorded most of the daytime missions on VHS videotapes. These videotapes were used to make color hardcopy pictures of Site E and surrounding areas at the moment the critical frame was collected (WES visual). Figure 20 illustrates physical changes that occurred at Site E and surrounding areas throughout the test period. The date and time are included on each visual photo.

Some of the most important events that occurred were as follows:

a. 20SEP,15:28 - Leaves on deciduous trees and others are green.

b. 21SEP,11:57 - A dense foggy day.

c. 050CT,15:43 - Leaves on deciduous trees beginning to turn red.

d. 12OCT,10:48 - Most of the deciduous tree leaves are red

e. 180CT,08:43 - Snow covers the ground, accumulated on trees.

f. 19OCT,08:58 - Snow precipitation.

g. 19OCT,17:58 - Snow melted on the bare ground patches.

h. 200CT,12:00 - Snow precipitation.

i. 210CT,11:34 - Snow accumulated on the ground, trees, and grass.

j. 220CT,16:19 - Normal sunny day conditions.

Figure 21 shows the WES-measured meteorological conditions throughout the test period. The total solar radiation (0.4- to 0.7- $\mu$ m range; another report provides instrument specifications<sup>1</sup>) measured was used to

<sup>&</sup>lt;sup>1</sup> Hahn, C. D., and Berry, T. E. (1994). "Grayling 1 site characterization and data summary," Technical Report prepared by the U.S. Army Engineer Waterways Experiment Station, Vicksburg, MS, for the Smart Weapons Operability Enhancement Joint Test and Evaluation Program Office, Hanover, NH.

illustrate cloud cover. Solar radiation is the real driving factor during the day, especially for the SWB sensor if the hemispherical albedo is relatively high. The test started and ended with some partly cloudy days (Figure 21a). During the test, there were many sunny days as well as partly cloudy and cloudy days. The dates 25-27 September are good samples of sunny days; the dates 15-17 September were partly cloudy days. The dates 21 September, 15 October, and 20 October were very cloudy days. From the beginning of the test, the air temperature (Figure 21a) exhibited peaks (at noon) and valleys (early morning and late evening) until 08 October. Those days exhibited some of the warmer air temperatures. Between 09 October and 22 October, the air temperature decreased and increased with a small slope and eventually dropped below freezing. At the end of the test (23 October), the air temperature was quite high.

The barometric pressure (Figure 21b) showed very little fluctuation (970 to 1,010 mb) during the duration of the test. On sunny days, the relative humidity (Figure 21b) dropped to 40 percent, while on cloudy days dropped to 90 percent. The wind speed (Figure 21c) fluctuated between 0.2 and 3.5 m/sec. The dates with the higher wind speed occurred between 16 September and 09 October. Meanwhile, the dates with the slower wind speed occurred on the dates 15 September, 29 September, 30 September, and 15 October. The wind direction (Figure 21c) most of the time blew from the west (0°=NORTH and 90°=EAST).

Visibility (Figure 21d) varied appreciably within a 24-hr period. For example, during the first 8 hr of 15 September, the visibility was a very low 0.2 km; then it quickly changed to 22 km. There were a few days with rain as well as snow precipitation (Figure 21d). Most of the rain occurred on 17 Sepember (35 mm/hr), meanwhile the dates 16 October, 18 October, and 20 October exhibited a considerable amount of snow precipitation.

Figure 22 shows the instantaneous meteorological conditions at the moment the critical frames were collected. The air temperature (Figure 22a) fluctuated between -5 and 25 °C with a mean temperature of 9.14 °C and a variability of 7.12 °C. Also, 52 percent of the missions were executed at night or during low levels of solar radiation (Figure 22a). Relative humidity (Figure 22b) fluctuated between 100 and 44 percent. Of the critical frames, 44 percent exhibited relative humidity of 100 percent, and 74 percent exhibited relative humidity greater than 80 percent. The barometric pressure (Figure 22b) exhibited a small range of values fluctuating between 980 and 1,005 mb. The average wind speed (Figure 22c) was 1.5 m/sec with wind speed varying between 0 and 3 m/sec. The direction in which the wind was blowing (Figure 22c) for each critical frame showed a spread between 0 and 360° (0°=NORTH and 9°=EAST). Very few missions exhibited either snow or rain precipitation (Figure 22d). Rain precipitation occurred during mission No. 8 (12mm/hr), while mission No. 92 had considerable snow precipitation (6.2 mm/hr). Appendix C shows a listing of all the missions and the instantaneous meteorological conditions, accumulated (last 12 hr) rain and snow precipitation, average (for the last 12 hr)

solar radiation and air temperature, and image mean temperature and standard deviation.

Visibility data, precipitation data, and WES visual (video) data were used to detect dense fog, snow, or rain precipitation during the critical frames. Although the terrain area imaged was only a short distance (150 m), visibility with less than 5 km has some effect on the measured IR signatures. Table 5 lists all the missions where the visibility was less than 5 km. The information in this table contains mission number, collection time, visibility distance, visual (video) data availability, and type of atmospheric condition along the transmittance path.

Precipitation data and soil moisture data were used to determine the possibility of the ground being wet during the critical frame collection. The average solar radiation, air temperature, and accumulated precipitation were computed (Figure 23) for the last 12 hr prior to the critical frames. There is a high possibility that the ground remained wet during some of the missions between No. 61 and No. 95 because of precipitation accumulation and low averages of both solar radiation and air temperature (during the last 12 hr). Table 6 shows the missions with accumulated precipitation greater than 5 mm/hr during the previous 12 hr and provides data on the average solar radiation and air temperature during the previous 12 hr and the Troxler and Speedy soil moisture data for Sites E1/E2.

The Site E area was divided (in two parts) where the left side was referred to as Site E1 and the right side as Site E2. Soil moisture data were collected at each site using the Troxler Model 4640 Thin Layer Density Gauge and the Soiltest Speedy Moisture Gauge. The Troxler device determines soil moisture by measuring the backscattering of low-level radiation from the surface of the soil. The Soiltest Speedy Moisture Gauge determines the moisture by combining a measured amount of soil with a measured amount of calcium carbide. The moisture in the soil reacts with the calcium carbide to produce acetylene gas. A pressure gauge on the Speedy then reads the gas pressure, and the reading is converted to a percent moisture. An important distinction between these two instruments is that the Troxler measures the moisture in a thin soil layer at or near the surface, while the Speedy determines the moisture based on a specific depth volume of soil. Speedy soil samples were collected from the area measured with the Troxler device within a 0- to 2.5-cm depth layer. Figure 24 illustrates the soil moisture data collected at Sites E1/E2 with both instruments. See "Grayling 1 Site Characterization and Data Summary" for more information about soil composition, soil moisture data, and instrumentation.<sup>1</sup>

<sup>&</sup>lt;sup>1</sup> Hahn, C. D., and Berry, T. E. (1994). "Grayling 1 site characterization and data summary," Technical Report prepared by the U.S. Army Engineer Waterways Experiment Station, Vicksburg, MS, for the Smart Weapons Operability Enhancement Joint Test and Evaluation Program Office, Hanover, NH.

Snow precipitation data and WES visual data were used to determine the possibility of snow precipitation along the path during the critical frame collection. It could not be accurately determined whether there was snow precipitation for those critical frames without WES visual data. For these cases, the amount of snow precipitation, within the hour when the critical frame was collected, was used as an indicator. The following missions exhibited snow precipitation.

Mission Number	Collection Date-Time	Precipitation Rate, mm/hr	Source of Information
82	16OCT92:17:00:06	1.98	Visual observation and snow precipitation gauge
83	17OCT92:07:10:10	0.28	Snow precipitation gauge
88	19OCT92:03:25:09	0.04	Snow precipitation gauge
89	19OCT92:09:00:08	0.03	Visual observation and snow precipitation gauge
92	20OCT92:12:00:02	6.71	Visual observation and snow precipitation gauge

Snow precipitation data and WES visual data were used to determine whether there was snow covering the terrain features (trees, grass, and bare ground) at the critical frame collection. Table 7 lists the missions and features containing snow. The amount of snow accumulated by each feature could not be determined.

### 5 Summary of Results

The WES LWB IR camera needed no calibration correction because the camera was operating within factory specification ( $\pm 3 \,^{\circ}$ C). A linear regression was performed to obtain an equation that would correct the WES SWB infrared data so that the blackbody temperature error would be within  $\pm 3 \,^{\circ}$ C. Using that equation corrected the SWB IR data from 93 to 98 percent within  $\pm 3 \,^{\circ}$ C. WES IR imagery collected at Grayling 1 exercise showed that 83 and 79 percent, respectively, of the LWB and SWB data were considered valid.

An analysis was performed by processing WES and ARL IR data (both wave bands) and comparing the mean temperature and standard deviation of the features for all the critical frames. The results showed that for any feature/wave band combination, the mean temperature difference is within  $\pm 3$  °C (WES and ARL absolute temperature accuracy is  $\pm 3$  and  $\pm 1$  °C, respectively). The standard deviation difference is within  $\pm 0.5$  °C.

Several global image metrics were computed and stored in a database for the Grayling 1 imagery. These image metrics include minimum, maximum, mean, median, mode, 5-percentile, 95-percentile, range-90, and standard deviation. In both wave bands, the terrain scene measured indicated very little thermal variability.

In the LWB, 83 percent of the WES imagery showed a mean temperature between 0 and 20 °C. Also, 80 percent of the imagery had a standard deviation between 0.0 and 1.0 °C. In addition, 90 percent of the data showed a temperature range of 6 °C or less.

In the SWB, 90 percent of the imagery showed a mean temperature between 5 and 20 °C. Also, 86 percent of the imagery had a standard deviation between 0.0 and 1.0 °C. Moreover, 90 percent of the data indicated a temperature range of 5 °C or less.

A database was generated with the mean temperature and standard deviation of several natural background features (grassy area, coniferous tree, deciduous tree, and road or test track) within Site E and surrounding areas. This database is considered useful for understanding the variations in IR image signatures to be used in SWOE synthetic image validation tasks. In both wave bands, the grassy area followed by the test track exhibited warmer temperatures and more thermal variability than the coniferous and deciduous trees. Also, the coniferous and deciduous trees exhibited very similar temperatures. The SWB data exhibited warmer temperatures and more thermal variability than the LWB data.

With the exception of 1 case in 11, a Kolmogorov-Smirnov like test showed no time-dependent changes in the imagery collected within 10-sec sampling periods for both wave bands.

IR data were collected under a broad variety of meteorological conditions that affected the IR signatures of the imaged terrain features (grassy area, trees, test track, etc.) within Site E and surrounding areas. Some of the meteorological factors that occurred during the data collection missions were dense fog, rain, and snow precipitation. High soil moisture content because of rain and snow precipitation as well as snow accumulation also affected measured IR signatures of terrain features. During the data collection period, there was a wide variety of sunny, partly cloudy, and cloudy days. Air temperature, relative humidity, wind speed, and wind direction also exhibited a wide range of values. Based on 107 missions, 14 percent of the missions were executed under temperatures below freezing, 41 percent at air temperatures between 0 and 10 °C, 42 percent at air temperatures between 10 and 20 °C, and 3 percent at air temperatures above 20 °C. Also, 52 percent of the missions were accomplished during nighttime conditions. Each of these parameters are associated with the critical frame.

WES equipment (infrared scanners, meteorological station, global positioning system, soil moisture equipment, and others) proved to be reliable and effective for site characterization and measurements.

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Figure 1. Photograph of Site E area



Figure 2. Sample of Site E area, LWB IR image (23OCT92:12:20)







Figure 4. Histogram of air temperature distribution at critical frames



Figure 5. Imagery quality assurance procedure



Figure 6. Blackbody calibration analysis for LWB data, no calibration correction needed







Figure 8. Blackbody calibration analysis after calibration correction applied to SWB data














Figure 13. 3-D plot of image mean temperature and standard deviation distribution for both wave bands



Figure 14. Histogram plot of temperature range distribution for LWB and SWB data



Figure 15. Air temperature and features' mean temperature bounded by standard deviation throughout Grayling 1 test



Figure 16. Within pass analysis plot

b) MISSIONS 34, 70 AND 71 UNDER PARTLY CLOUDY DAY CONDITIONS LAG TIME (Seconds) LAG TIME (Seconds) MISSION NUMBER: ---- 39 +---+ 40 ---- 101 MISSION NUMBER: +--+ 34 +--+ 70 ---- 71 ŝ d) MISSIONS 39, 40 AND 101 AT NIGHT T (x) 15.0-T (x) 10.0-T 0.0-22.5 T (\*) 15.0 2.5 7.5 2.5 7.5 0.0 20.0 5.0 0.0 20.0 5.0 22.5 17.5 17.5 d) MISSIONS 37, 38 AND 74 UNDER SUNNY DAY CONDITIONS c) MISSIONS 79 AND 92 UNDER CLOUDY DAY CONDITIONS LAG TIME (Seconds) LAG TIME (Seconds) MISSION NUMBER: +--+ 37 +--+ 38 --- 74 ŝ MISSION NUMBER: +---+ 79 +---+ 92 20.0 17.5 T (x) 15.0.1 T (12.5.1 T 10.0 7.5 5.0 2.5 2.5 0.0 22.5 7.5 0.0 22.5 5.0 20.0 17.5 15.0 15.0 12.5 10.0

Figure 17. Plot of T versus lag time at different weather conditions for LWB data



Figure 18. Plot of T versus lag time at different weather conditions for SWB data



Figure 19. Image mean temperature bounded by standard deviation for LWB and SWB data for all 107 missions



Figure 20. Physical changes at Site E area (Sheet 1 of 3)



Figure 20. (Sheet 2 of 3)



Figure 20. (Sheet 3 of 3)





42 :





Figure 21. (Sheet 3 of 4)



Figure 21. (Sheet 4 of 4)



Figure 22. Instantaneous meteorological conditions at critical frames (Continued)



Figure 22. (Concluded)



Figure 23. Meteorological conditions prior to critical frame





Table 1 IR Camera Specificati	on	
	Wave	e Band
Specification	Mid-IR	Far-IR
Model	Thermovision 870 system, infrared camera	Thermovision 782 system, infrared camera
Wavelength band	2 to 5.6 μm	8 to 12 μm
FOV lens	2.48 square deg	3.63 square deg
Screen resolution	140 by 140 square pixels	140 by 140 square pixels
Image resolution	8-bit resolution	8-bit resolution
Radiometric sensitivity	0.1 °C at 30 °C object temperature	0.1 °C at 30 °C object temperature
Radiometric accuracy	± 3% or ± 3 °C	± 3% or ± 3 °C

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Table 3 Summary of	Grayling 1 Im	agery Data (b	ased on 107 n	nissions)
Wave Bands	Good Images	Good images after Noise Removed	Bad Or Lost Images	Total
3- to 6-μm short wave band (SWB)	22%	57%	21%	100%
8- to 14-µm long wave band (LWB)	37%	46%	17%	100%

Table 4 Different Pair Im	ages Comparisor	n for 10 Images Ta	aken 1 Sec Apart
Pair Image	Combination		
Image No.	Image No.	Lag Time, seconds	T Value, %
1	2	1	T <sub>1</sub>
2	3	1	T <sub>2</sub>
1	3	2	T <sub>3</sub>
1	4	3	T4
•	•	•	•
•	•	•	•
•	•	•	•
1	10	9	T <sub>45</sub>

Table 5 Missions wi	th Visibility Les	s Than 5 km		
Mission Number	Collection Date-Time	Visibility km	Visual Data Availability	Atmospheric Condition
1	15SEP92:07:00:01	0.40	No	Fog
2	15SEP92:09:00:00	3.40	No	Fog
4	16SEP92:01:30:05	3.30	No	Fog
5	16SEP92:07:00:06	4.10	No	Fog
6	16SEP92:09:20:09	4.70	No	Fog
7	16SEP92:20:20:04	4.10	No	Fog
8	17SEP92:02:00:02	3.40	No	Rain
11	18SEP92:01:15:07	2.20	No	Fog
19	21SEP92:12:00:05	3.30	Yes	Fog
44	03OCT92:07:20:07	4.10	No	Fog
78	15OCT92:05:04:10	4.10	No	Fog
80	16OCT92:00:05:04	4.60	No	Fog
86	18OCT92:08:45:09	4.40	Yes	Fog/Snow
92	20OCT92:12:00:02	0.80	Yes	Snow

Missic	6 ons with 12-hr /		I Precipi	tation G	reater th	nan 5 mr	n/hr	
		Accumulated	Average Solar	Average	Tre	oxier,%	Sp	eedy,%
Mission Number	Collection Date-Time	Precipitation mm/hr	Radiation W/M <sup>2</sup>	Temper- ature, °C	E1	E2	E1	E2
8	17SEP92:02:00:02	19	30	22.21	14	17	22 .	17
9	17SEP92:11:00:02	34	5	19.51	14	17	22	17
12	18SEP92:11:00:02	6	10	19.58	13	18	14	27
13	18SEP92:13:15:09	7	27	19.27	13	18	14	27
30	27SEP92:11:00:08	14	13	14.32	14	15	11	23
31	27SEP92:18:05:07	6	104	12.63	14	15	11	23
63	09OCT92:09:00:09	12	5	10.19	11	14	9	23
72	12OCT92:22:10:08	6	217	6.77	10	15	10	17
73	130CT92:03:30:04	6	73	3.23	10	14	14	22
80	16OCT92:00:05:04	14	46	7.73	16	15	19	18
82	16OCT92:17:00:06	6	150	5.01	16	15	19	18
83	17OCT92:07:10:10	24	0	-0.61	11	16	12	30
87	18OCT92:21:50:03	9	168	-1.65	10	•	9	14
92	200CT92:12:00:02	16	13	-1.90	•	•	15	20
93	21OCT92:00:15:05	11	34	-0.68	•	•	10	19

.

Table 7 Missio	, ns with Feature	s Covered w	<b>rith Snow</b>			
Mission Number	Collection Date-Time	Grassy Area Covered?	Coniferous Tree Covered?	Deciduous Tree Covered?	Test Track Covered	Visual Data
72	12OCT92:22:10:08	Probably	Probably	Probably	Probably	No
73	13OCT92:03:30:04	Probably	Probably	Probably	Probably	No
82	16OCT92:17:00:06	Yes	No	No	Yes	Yes
83	17OCT92:07:10:10	Probably	Probably	Probably	Probably	No
86	18OCT92:08:45:09	Yes	Yes	Yes	Yes	Yes
87	18OCT92:21:50:03	Probably	Probably	Probably	Probably	No
88	19OCT92:03:25:09	Probably	Probably	Probably	Probably	No
89	19OCT92:09:00:08	Yes	No	No	Yes	Yes
92	20OCT92:12:00:02	Yes	Yes	Yes	Yes	Yes
93	21OCT92:00:15:05	Probably	Probably	Probably	Probably	No
94	210CT92:02:10:01	Probably	Probably	Probably	Probably	No
95	210CT92:06:55:01	Probably	Probably	Probably	Probably	No
96	21OCT92:11:15:01	Yes	No	No	No	Yes
97	21OCT92:13:00:07	Yes	No	No	No	Yes
98	220CT92:01:10:07	Probably	Probably	Probably	Probably	No

## Appendix A Image Data Collection Procedures

The infrared (IR) cameras contain no built-in blackbodies; however, each was recently calibrated by the manufacturer. Further, these DCrestored scanning radiometer cameras require manual setting of the levels and ranges. Consequently, a procedure was employed to verify the accuracy of the radiometric temperature estimates and to ensure that the manually set thresholds of all images were within dynamic range. The field portion of this procedure consisted of the following two steps:

- a. Four active blackbodies were aligned such that they could be directly viewed by the sensors within a single field of view. The blackbody on the extreme left was set to ambient temperature, and the other three blackbodies (left to right) were set to the ambient temperature plus 10, 20, and 30 °C, respectively.
- b. Before and after an imagery data collection mission, the four active blackbodies were imaged by the thermal cameras, and two infrared images were taken: far-IR and mid-IR. Simultaneously, the blackbody temperatures were recorded.

Upon completion of imaging, all scene images were automatically checked to identify those out of dynamic range. Images with more than 2 percent of the brightness values, less than 2 or greater than 253, were rejected.

The accuracy of the factory calibration was examined using these blackbody images by comparing the camera's radiometric temperature estimates with the temperatures measured from the blackbodies. When 90 percent of the absolute errors were under 3 °C, the factory calibration procedures were used for a given excursion. When errors exceeded this level, a corrective procedure was employed. It consisted of a linear adjustment to fit the camera's radiometric temperature estimate to the temperature of the blackbodies. The formula of this correction is as follows:

$$T_{BB} = (a * T_C) + b$$

where:

- $T_{RR}$  = physical temperature of blackbody
  - a = slope estimated by least squares regression
- $T_C$  = camera's radiometric estimate of blackbody temperature
  - b = intercept estimated by least squares regression

When the blackbody temperature estimates could be corrected to meet the above acceptance criteria, the corresponding scene images were used. In the end, only images meeting the accuracy criteria were used for analysis.

These cameras were mounted in a remote-controlled pan and tilt mount atop a 55-ft boom on the WES boom truck.<sup>1</sup> The imaging procedure was first to rotate the boom and the cameras to point at a set of four active blackbodies provided by Eglin Air Force Base and collect image data for each of the two wave bands. Then, the boom was extended to its full height, and thermal cameras were rotated to aim at the Site E area to start the data collection. At the conclusion of the sampling period, the boom and thermal cameras were repositioned to collect a second image of the blackbody. These blackbody images collected at the beginning and end of an imaging period would later be used to check for camera accuracy and make any necessary correction.

<sup>&</sup>lt;sup>1</sup> To convert feet to meters, multiply number of feet by 0.3048.

## Appendix B Grayling 1 Image Metrics

						NINIMUM	PERC 05	NODE	MEDIAN	WW.	PERC 95	MAKINAM	STO DEV	RANGE 90	KAN	STD DEV	NEAK	STD_DEV	WW	130_012	NEAN	ST0_0E1
HISSIN	PASS	FRAME	NISSIN_DT	INAGE_DT	LAVEBAND	(Deg. C)	(Deg. C)	(Deg. C)	(Deg. C)	(Deg. C)	(Deg. C)	(Deg. C)	(Deg. C)	(Deg. C)	(Deg. C)	(Deg. C)	(Deg. C)	(Deg. C)	(Deg. C)	(Deg. C)	(Deg. C)	(Deg.
-			155EP92:06:00		3										•	•					•	•
~		•	15seP92:08:00		5				•	•			•••		•	•				•		•
-	•		15seP92:16:00		Eve	•	•			•	•		•									•
4	•	•	165EP92:01:00		811				•	•		•	•	•	•	•						•
•	•		16SEP92:06:00	•	91	•	•			•		•					•			•		•
•	•	•	16SEP92:08:00	•	3					•		•								•		•
~	'n	4	16SEP92:20:00 1	165EP92:20:20:04	3	20.0	20.4	20.7	20.9	20.8	21.4	21.7	0.3	1.0	20.5	0.1	21.12	0.1	21.2	0.0	20.6	0.0
-	•		175EP92:01:00	•	2		•	•	•	•		•			•	•	•		•			•
•	2	~	17SEP92:10:00 1	175EP92:11:00:02	3	19.5	19.7	20.0	19.9	19.9	20.1	8.3	0.1	9.9	19.91	0.1	20.1	1.0	20.0	0.0	19.7	0.0
2	21	•	1756P92:16:00 1	1756292:17:20:07	3	21.1	51.4	21.7	21.7	21.7	22.0	23	0.2	0.6	21.7	6.1	21.7	0.1	21.6	1.0	1.15	0.0
F	<b>1</b>	~	185EP92:00:00 1	16SEP92:01:15:07	3	17.4	16.1	18.6	18.7	16.8	19.4	19.7	4.0	7	18.5	1.9	19.4	0.2	19.4	6.1	17.8	2
12	2	~	185EP92:10:00 1	185EP92:11:00:02	2	18.4	18.6	18.8	18.9	18.9	19.3	19.6	0.2	0.6	19.1	0.1	18.6	0.1	18.6	0.1	18.8	
2	•	•	18seP92:12:00	•	3	•		•		•								•	•		•	•
ž	ŝ	~	195EP92:01:00	195EP92:01:20:07	3	5.3	ê.5	ê.ê	1.1	7.7	9.3	9.9	1.0	2.9	7.0	0.3	8.5	0.3	8.7	0.3	<b>6.6</b>	9
ŧ	51	•	1956992:13:00	1952292:14:00:07	3	10.3	13.8	17.2	17.2	16.7	\$.5	5.52	2.1	6.7	16.9	0.6	15.3	0.6	14.6	4.0	15.8	3
91	11	-	1956P92:17:00	195EP92:18:20:03	3	10.2	12.4	13.2	13.4	13.4	14.8	15.9	0.6	2.4	14.3	0.3	13.1	0.2	12.8	0.1	13.2	ð
11	5	9	20SEP92:10:00 2	205EP92:11:00:06	3	10.5	13.1	13.9	16.1	8.81	19.0	21.6	2.0	5.9	18.1	0.5	14.7	0.4	13.9	4.0	12.9	0
18	\$	۰	205EP92:14:00 2	20SEP92: 15:30:09	3	16.2	19.1	20.8	22.5	22.9	27.5	10.3	2.7	8.3	26.4	0.7	20.7	0.7	19.7	6.0	20.5	ð
\$	Ë	'n	215EP92:11:00 2	21SEP92:12:00:05	Ē	14.4	14.7	15.8	15.9	15.9	17.2	17.6	0.0	2.5	16.9	0.1	15.1	0.3	14.7	0.1	15.8	0
8	2	-	215EP92:13:00 2	215EP92:14:00:08	5	15.9	16.2	18.0	18.1	17.7	19.1	20.2	1.0	2.9	16.7	0.1	16.8	9.0	16.4	0.2	17.9	6
21	4	o	225EP92:07:00	225EP92:07:15:09	3	\$	5.7	6.0	5.3	6.5	7.8	8.3	0.7	2.1	6.1	0.2	2.5	0.3	7.5	0.2	5.7	9
22	5	-	ZZSEP92:16:00	22SEP92:17:00:08	E.	8.4	9.5	12.8	12.0	11.8	13.7	14.7	1.1	4.2	12.9	2.0	10.6	0.6	10.2	0.3	12.8	5
12	5	4	235EP92:00:00	235EP92:09:20:04	3	0.3	2.3	3.8	2.0	5.0	8.3	10.7	1.9	6.0	7.2	9.6	3.3	0.9	4.0	0.5	7	
2	2	•	Z35EP92:14:00	23seP92:15:00:04	3	10.8	13.6	14.6	18.9	19.2	2	32.0	17	12.3	24.6	<b>6</b> 70 .	15.4	1.2	14.1	9.4	18.5	
ĸ	2	'n	24SEP92:17:00	245EP92:18:00:05	3	12.2	13.0	13.4	14.2	14.6	16.8	17.5	1.1	3.8	13.4	0.2	15.9	9-6	16.1		13.9	
8	2	•	25SEP92:17:00	255EP92:18:00:06	3	16.9	20.2	21.8	22.1	27.7	24.8	27.2	1.1	s;	23.5	0.7	22.0	1.7	21.3	0.5	20.2	6
27	2	1	25SEP92:22:00	25SEP92:22:05:07	5	1.1	8.6	<b>%</b> .1	5.5	9.8	11.5	12.0	1.0	2.9	9.3	0.2	10.7	0.5	11.2	0.2	5.5	6
82	1	N	Z6SEP92:15:00 2	265EP92:16:20:02	5	16.0	16.2	16.6	16.6	16.6	16.9	17.2	0.2	0.7	16.7	0.1	16.5	0.1	16.5	0.1	16.4	0
8	2	~	265EP92:18:00	26SEP92:18:45:02	5	14.1	1	14.6	14.7	9.9	6.4	15.2	0.2	9.6	14.8	0.1	14.5	6.1	14.5		5.5	6
ñ	-	-	27sep92:11:00	27seP92:11:00:08	3	12.6	12.9	13.0	13.6	2	2.2	14.6	9.6	1.1	13.9	0.1	E.EI	0.1	13.1	0.1	13.5	6, 9
ñ	~	~	275EP92:18:00	275EP92; 18:05:07	8	12.1	12.6	12.9	13.0	13.0	13.7	14.6	0.3	2	13.2	0.2	13.0	0.1	12.9	0.1	12.5	<b>.</b>
R	5	•	285EP92:17:00	285EP92:18:00:04	9	2.6		2,6	9.4	4.9	10.0	11.5	0.8	2.6	10.6	0.3	8.4	0.3	8.0	0.2	8.9	•
5	•	•	Z95EP92:02:00	•	3	•	·	·	•	•	•	•	•	•	•	•	•	•	•	•	•	•
Å	1	-	295EP92:14:00	295EP92:15:20:01	2	6.5	6. 1	£.5	12.0	12.0	15.4	17.1	2.2	6.b	14.7	9.4	10.2	0.9	9.6	7.0	11.2	
ñ	2	₽	295EP92:19:00	295EP92:20:40:10	3	6.5	6.8	7.2	5.7	2		8.5	E.0 .	: :	1.1	0.1		0.2	7.0	0.2	1.2	÷.
2	2	2	305EP92:17:00	305EP92:18:00:10	2	12.1	14.1	14.8	15.5	15.3	17.0	21.0	0.9	2.9	16.0	9.0	15.5	0.6	15.5	0.5	13.8	ö
37	17	r	010CT92:08:00 (	0100192:09:20:03	3	51	2.1	3.0	3.9	4.0	6.9	8.8	1.4	4.8	5.4	0.5	2.9	0.4	3.6	0.5	1.5	ð
2	5	2	010CT92:11:00 (	010CT92:12:00:10	5	13.6	16.2	17.1	19.3	19.5	23.7	25.7	2.5	7.5	22.7	5.0	1.11	0.5	17.0	9.6	15.5	ò
۶	•	~	010C192:20:00 0	0100192:20:35:03	85	1.3	8.7	9.5	10.4	11.3	16.3	17.71	. 2.5	2.5	9.6	9.0	12.9	0.8	14.2	0.5	10.1	ď
97		•	010C192:23:00	•	5				•						•			•	•	•	•	•
5	\$	•0	020CT92:05:00	0200192:05:25:08	87.	5	5.6	6.3	6.8	7.3	11.5	13.3	9.4	5.9	6.7	0.5	8.4	0.7	9.8	0.6	6.5	
25			0200192:08:00	•	843		•					•	•			•				•		•
5		•	020CT92:21:00		873				•	•					•							•
77	•	~	0300192:07:00	0300192:07:20:07	5	4.9	6.0	6.7	6.9	6.9	8.3	10.0	0.7	2.3	7.0	0.1	7.4	0.2	7.5	0.1	6.3	ġ

					- N
TEST TRACK STO_DEV (Deg. C	4.0 1.0 1.0 1.0 1.0 1.0 1.0 1.0 1.0	2.2.0 2.2.0 2.2.0 2.2.0 2.2.0 2.2.0 2.2.0 2.2.0 2.2.0 2.2.0 2.2.0 2.2.0 2.2.0 2.2.0 2.2.0 2.2.0 2.0.00 2.0.00 2.0.00000000			
TEST TRACK MEAN (Deg. C)	23.7 2.7 2.9 8.9 8.9 8.9	8.0 9.0 8.6 7.2 2.4 2.4 2.4 2.7 2.7	9.9 9.6 9.0 1.0 1.0 1.0		4.4
pecibuas TREE \$10_bEV (0eg. C)	0.5 0.3 0.3 0.2 0.2	0.3 0.5 0.2 0.2 0.2 0.2	· · · · · · · · · · · · · · · · · · ·	, 0 2 0 1	
DECTOUOS TREE MEAN (Deg. C)	21.2 11.8 3.0 3.0 1.7 11.7 12.7		9.6 4.012.2 4.02.8 8.03.8 8.03.8 8.03.8 8.03.8 8.03.8 8.03.8 8.03.8 8.03.8 8.03.8 8.03.8 8.03.8 8.03.8 8.03.8 8.03.8 8.04.8 9.04.9 9.04.9 9.04.8 9.04.90.90000000000	 	
COMIFEROUS TREE SID_DEV (Deg. C)	1.1 0.5 0.2 0.5 0.5			0.2 0.2 0.2 0.1 0.1 0.1 0.2 0.3 0.4	0.9 9.0
COM J FERCUS T A E E MEAM (Deg. C)	22.3 7.1 7.5 7.6 7.6 7.6 7.6	2.9 2.9 2.9 2.9 2.9 2.9 2.9 2.5 2.9 2.9 2.9 2.9 2.9 2.9 2.9 2.9 2.9 2.9	9.7 9.5 10.2 10.6 10.6	5.2 5.2 5.2 5.2 5.2 5.2 5.2 5.2 5.2 5.2	54 4
GRASSY AREA STO_DEV (Deg. C)	1.0 0.1 0.2 0.2 0.2 0.2	    	0.1 0.1 0.1 0.1 0.1 0.1		0.4
GRASSY AREA MEAN (Deg. C)	2.6 8.7 8.7 8.7 8.7 8.0 0.0 8.4				6.4- E.7-
INAGE RANGE PO (Deg. C)	4 0 9 1 M 10 0 4 0 9 1 M 10 0 4 0 4 0 4 0 M			· · · · · · · · · · · · · · · · · · ·	2.3
INAGE STD_DEV (Deg. C)	1,1 8,1 9,0 9,0 9,0 1,0 1,0 1,0 1,0 1,0 1,0 1,0 1,0 1,0 1			. 1 . 1 . 2 . 2 . 2 . 2 . 2 . 2 . 2 . 2 . 2 . 2	0.7
INAGE MAXIMUN (Deg. C)	35.6 14.7 5.7 5.0 2.1 2.2 2.2 2.2	x.v 5.9 1.3.2 1.3.2 1.1.3 1.1.		· · · · · · · · · · · · · · · · · · ·	-3.5 -3.6
INAGE PERC_05 (Deg. C)	30.6 13.8 3.9 2.8 12.6 12.6 12.6 26.7	5.3 5.1 1.9 8.6 8.6 8.6 7.2 8.6 7.2 9.2 10.4	10.0 10.6 14.3 7.7 7.6		-4.2 -4.2
IMAGE MEAN (Deg. C)	2.9 8.2 1.1 2.9 2.5 2.5 2.5	2.1 2.1 2.1 2.6 2.6 2.6 2.6 2.6 2.6 2.6 2.6 3.5 3.5 3.5 3.5 3.5 3.5 3.5 3.5 3.5 3.5		· · · · · · · · · · · · · · · · · · ·	4.1 6.6
INGE REDIAN (Deg. C)	25.0 2.5 2.5 2.5 2.5 2.5 2.5 2.5 2.5	21.6 21.6 21.6 21.6 21.6 21.6 21.6 21.6	· · · · · · · · · · · · · · · · · · ·	· · · · · · · · · · · · · · · · · · ·	-6.5
JMAGE MODE (Deg. C)	21.9 2.5 2.5 2.5 2.5 2.5	111 111 111 111 111 111 111 111 111 11	· · · 3 · 2355355	8 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9	4.7-
HANGE PERC_05 (Deg. C)	21.2 2.1 2.1 2.1 2.2 2.5 2.5	7.4 0.5 20.1 5.5 6.7 6.5 7.4 6.5	· · ·		5.1 8.1
INAGE KINIMUM (Deg. C)	18.9 6.7 7.7 7.7 7.7 7.7	2.5 1.0 1.0 1.0 1.0 1.0 1.0 1.0 1.0 1.0 1.0	· · · · · · · · · · · · · · · · · · ·		-6.0
QIVVB 3/VIT					87.1 178
IMAGE_DT	0017211610017 00172116100107 00172213120108 00172213120108 00172213120108	00172:16:20:04 00172:00:01 00172:00:01:06 00172:01:05:06 00172:01:05:06 00172:01:05:06 00172:05:05:06 00172:04:00:06 00172:04:15:01 00172:04:15:01	00192:22:15:03 00192:22:15:03 00192:02:02:03 10192:02:01:5:00 10192:16:5:01 00192:11:00:07 20192:11:20:06	20C192_010_20_01 20C192_010_00_01 20C192_010_010_01 20C192_0210_010_01 20C192_021_01_00_010_01 20C192_01_01_00_010_01 20C192_01_01_00_010_01 20C192_01_01_00_010_01 20C192_01_01_00_010_01 20C192_01_01_01_00_010_01 20C192_01_01_01_00_010_01 20C192_01_01_01_00_010_01 20C192_01_01_01_00_010_01 20C192_01_01_01_00_010_01 20C192_01_01_01_00_010_01 20C192_01_01_01_00_010_01 20C192_01_01_01_01 20C192_01_01_01_01 20C192_01_01_01_01 20C192_01_01_01 20C192_01_01_01 20C192_01_01_01 20C192_01_01_01 20C192_01_01_01 20C192_01_01 20C192_01_01 20C192_01_01 20C192_01_01 20C192_000000000000000000000000000000000000	800192:21:50:03 900192:03:25:09
10 <sup>-</sup> 7551N	30CT92:15:00 02 30CT92:19:00 02 40CT92:03:00 04 40CT92:07:00 04 40CT92:01:00 05 40CT92:01:00 05	Socr92:15:00 7 600:792:05:00 0 600:792:01:00 0 600:792:10:00 0 600:792:10:00 0 700:792:10:00 0 700:792:10:00 0 700:792:10:00 0 700:792:10:00 0 700:792:10:00 0	00C192.11100 00C192.2010 00C192.2010 00C192.21210 00C192.21210 110C192.12100 1110C192.12100 1110C192.12100 1110C192.12100 1120C192.141000 1120C192.141000 1120C192.141000 1120C192.14100000000000000000000000000000000000	226192.21:00 2360192.22:00 2360192.22:00 2360192.22:00 2360192.22:00 2360192 236019000000000000000000000000000	190C192:20:00
FRAME	880088	**********		·*************************************	. m o
PASS	2= 2 - 2 2	2 • • 5 5 5 5 5 5 5 5 5 5	••••	· > 2 & 4 > 5 2 2 . 5 2 m 5 3 9	<b>"</b>
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GRASSY CONFFERCUS CONFFERCUS DECIDUOS 1 AREA TREE TAEE TREE	STD_DEV NEAN STD_DEV NEAN 1	) (Deg. C) (Deg. C) (Deg. C) (Deg. C) (		0.2 12.1 0.3 12.4	0.1 16.0 0.1 15.9	0.1 14.4 0.1 14.4	•	0.0 13.1 0.0 13.1	0.2 11.1 0.5 10.7				0.8 6.9 1.1 7.4	0.5 20.8 0.5 20.4	0.3 16.2 0.6 17.1	0.3 16.6 0.4 16.7	•		0.2 20.9 0.5 41.9	0,1 12,0 v.1 ic.v 1.1.2 24,2 2.3 22.8	0.3 17.1 0.3 17.3	0.2 4.7 0.2 4.8	0.3 5.2 0.2 5.0	0.2 15.4 0.4 15.7	• • •	0.2 7.3 0.2 7.7	•	0.5 16.3 0.6 16.4	0.6 24.1 1.1 23.6	0.2 12.5 0.2 12.7	0.2 10.6 0.4 10.9	0.2 16.6 0.5 17.2	0.1 9.2 0.1 9.5	•	0.1 16.3 0.1 16.3	· · · ·		•	0.1 12.6 0.1 12.5	0.1 12.8 0.1 12.7	0.2 15.0 0.2 14.8	0.2 9.3 0.2 9.5
CRASSY VCE INAGE AREA	DEV RANGE 90 NEAR	a. C) (Deg. C) (Deg. C)		2.2 10.7	0.2 0.6 16.0	0.2 0.5 14.3	•	0.1 0.2 13.1	0.9 2.9 12.5		B.1) C.C 4.1	10 10	1.4 4.6 9.5	2.3 6.2 26.0	1.8 5.5 13.2	1.3 3.7 14.1	•	•	0.8 2.9 16.5	C.II C.I C.O	1.2 J.1	0.6 1.8 4.3	0.7 2.4 4.2	1.2 3.6 13.0	•	1.1 3.4 6.0	•	2.3 6.3 21.6	1.4 4.2 26.8	0.9 2.6 11.1	1.0 2.9 9.3			· ; ·	0.2 0.5 16.4	•	•		0.2 0.6 12.5	0.2 0.6 12.9	0.6 1.7 16.0	0.9 2.9 7.8
INAGE	<b>GIS HTMIXTN</b>	0 (Deg. C) (De		13.4	16.9	15.3	•	13.4	14.4	•	14.6	• "	12.3	29.5	19.6	18.3	•	•	21.9	7.6	1.00	2.0	7.6	1.11	•	• •	•	23.4	30.9	14.7	12.9	•	13.6	: •	17.1		•	•	11.5	13.9	17.0	11.5
HAGE IMAGE	EAN PERC 95	g. C) (Deg. C		1.3 12.6	5.9 16.3	4.4 14.7	•	5.1 15.2	13.6		-	0.6 23.2	8.7 11.1	3.5 26.6	18.2	17.6	•	•••	1.9.1 Zu.e	11.0 14.5 27.8 32.5	16.0 18.3	4.9 5.9	4.9 6.1	14.2 16.3	•	7.0 8.9		19.1 22.1	25.6 27.8	12.0 13.5	11.0 8 0 8 0 8	1.1 1.2	9.2 12.2	•	16.4 16.7	•	•	•	12.6 13.0	12.9 13.2	15.5 16.4	5.0 10.5
IMAGE	NEDIAN J	(Deg. C) (D		5.11	15.9	14.4		13.1	12.2	. ;		21.0	9.1	23.9	14.3	15.0			0.61	9.11 2. AS	15.7	4.9	6.9	14.0	•	• • •	•	19.6	25.7	1.8	9 F	5.21	6.6	•	16.3	•			12.6	12.9	15.8 2	8.7
INAGE	5 NODE	C) (Deg. C)	•	10.6	15.8	14.4		13.1	12.5			20.5	9.1	8.02	1 13.1	1.34.1	•	•	2.9 2	7 2	12	2	5	12.9	•	. 5.9	•	1 16.1	5 23.8		0 C	1 1		•	2 16. <del>3</del>	•	•	•	12.5	5 . 12.9	7 15.9	5 7.9
AGE IMAGE	THUM PEAC O	8. C) (Deg.	•	9.8 10.4	5.4 15.4	3.9 14.2	•	2.9 13.0	0.2 10.7		1.61 0.2	10.01	3.6 6.3	1.65 20.4	11.9 12.1	12.8 14.0	•	•	1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1	9.6 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2	1.21 C.11	3.4	2.6 3.1	11.4 12.4	•	. e	•	13.4 15.1	23.0	10.3 10.	8.0 • •		1 4 1	•	15.9 16.2	•	•	•	12.1 12.	12.4 12.	14.1 14.	7.1 7.
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## Appendix C Instantaneous Meteorological and Terrain Data

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Appendix C Instantaneous Meteorological/Terrain Data

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