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Building 410 Bolling AFR DC 20332-6448				ELEMENT NO.	NO.	TASK NO.	WORK UNIT ACCESSION NO.
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			receptors, s	ymbolic dyna	mics, fini	te-state au	utomata,
10 405704/7			neural netwo	rks.neuron m	<u>embrane pe</u>	<u>rturbation</u>	analysis
I. Progress of	on the behavior	al and the molecula	r biological goals:	umder)			
1. We hav	ve finished, as o	riginally proposed.	the software and first a	ctual physical eve	tem for comput	ter controlled to	
with wh	hich to shape an	nimal behavior and	to perform learning-co	nditioning experi	ments.		anning procedures.
all of th	ie five known n	nuscarinic receptors	this work follows or	muscarinic cholin previous AFOS	R-funded work	proteins pertain relating to chol	ing specifically to
enhance	ement of associ	iative learning [14,1	5,11-13].			0	
II. Progress	into the implic	ations of attractors,	perturbation analysis of	of neurons, and th	e use of langua	ige theory:	
3. We hav	e developed the	e conceptual rational	le and conducted comm	uter experiments	O show that attr	actor anadiente	nrovide on
integrat	live principle th	hat globally acts on a	all synapses in a netwo	rk of "cooperative	e" neurons. The	consequences	of this are
CatchSI	ve, and much fi	atorany tans out na	turany, e.g: synaptic s	trengths are optin	ally set with o	ne another; the	size of the
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network is self-limiting; networks require trainable thresholds in their constituent neurons, along with trainable synaptic strengths, to perform even simple tasks; and both task-specific and pultiferentian performance of the stractor gradients. The work began with [7,8] and is extension is econical problement of the are limited only by computational power for extending the implications of the work and for obtaining the detargoid scene table with the stractor of publications.

- 4. We have identified the cellular basis for dissipative action provide an analogy, this easy to see how heat dissipates perturbations in a simple pendulum with friction. But what is it that doep tethistipation in the control for the system or in computer simulations of biologically realistic networks? Joan Boggs
- 5. The answer to the above question in (4) has come from a service of noise and the possibility pation studies of neurons and networks of neurons (The first of a series of findings are presented in [4], which will be sent to J. Neurophysiol. within the next month).
- 6. We have identified the basis of variation in the action of single and groups of neurons. Previous AFOSR-funded work has shown that variation is essential in adaptive function of networks that can produce many different patterns of activity [e.g., 10,11]. Here we show where the variations come from [4]. We have also obtained evidence for the mechanism by which multiple patterns emerge [2,4].
- 7. We have ported considerably from formal language theory and theoretical physics to describe quantitatively the trains of action potentials that are used to transmit information between neurons. Additionally, we have implemented the formalism of finite-state automata to construct machines that represent this information [3,5]. The major consequence of this work is that it provides a vast theoretical formalism with which to handle the information flow in networks. The ultimate consequence is that network function might be examined from the point of view of statistical mechanics.
- 8. A collaboration has been established with Dr. Seth Wolpert, Department of Electrical Engineering, University of Maine, to construct analog VLSI networks of neurons as we have described them. This work will not only allow us to perform experiments (extremely) rapidly in ways that can not be done in typical desktop computers, but it will also allow us begin to implement the findings in networks that can be rapidly trained to perform particular functions that are normally found only in behaving animals.

PUBLICATIONS that have arisen in part or completely from funds in AFOSR-92J-0140:

- 1. Mpitsos, G.J., Attractor Gradients: Architects of Organization in Biological Systems. In Chaos and Society, 1994. In Press.
- 2. Mpitsos, G.J. and Edstrom, J., Bifurcation dynamics, multifunctionality, and variation in computer simulation of biologically realistic neural networks, (1994).
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Original in: K.M. Newell and D. Corcos, Variability and Motor Control, Human Kinetics, Champaign, 1993, pp. 225-290.

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- 10. Mpitsos, G.J. and Cohan, C.S., Convergence in a distributed motor system: Parallel processing and self-organization, J.
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- 16. Soinila, S. and Mpitsos, G.J., Immunohistochemistry of diverging and converging neurotransmitter systems in molluses, *Biol.* Bull., 181 (1991) 484-499.

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