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RAPID PROTOTYPING OF APPLICATION SPECIFIC SIGNAL PROCESSORS (RASSP)

FINAL TECHNICAL REPORT

George J. Agule  
Stephen M. Lorusso

Kelley J. Arsenault  
Paul N. Bompastore  
Robert V. Bryant  
Victor L. Corbin  
Colleen A. Hartnett

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**RAPID PROTOTYPING OF APPLICATION  
SPECIFIC SIGNAL PROCESSORS (RASSP)**

**FINAL TECHNICAL REPORT**

**Prepared by,**

George J. Agule, Consulting Engineer, Digital Systems Laboratory

Stephen M. Lorusso, Senior Engineer, Digital Systems Laboratory

Kelley J. Arsenault, Section Manager, CAE System Level Analysis

Paul N. Bompastore, Section Manager, CAE Digital & Analog Systems

Robert V. Bryant, Section Manager, CAE Manufacturing Support

Victor L. Corbin, Department Manager, Electronic Design and Test CAE

Colleen A. Hartnett, Senior Engineer, CAE Operations

**Raytheon Company**

Missile Systems Division

Tewksbury, Massachusetts 01876

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## **1.0 Introduction**

*This document contains information useful for assessing the applicability, complexity, and feasibility of implementing the RASSP methodology. The Study Phase investigated eleven topics. Each investigation consisted of 1) a feasibility of the proposed RASSP methodology, 2) a compendium of related work, 3) a discussion of any perceived or known problems, and 4) a discussion of possible solutions to problems.*

The report is organized to provide information to program managers in support of their efforts to

manage the risks inherent in the Implementation Phase of the RASSP program. This report has three major sections. Sections 1 and 2 provide introductory and summary information. Section 3 provides detailed information on eleven separate categories as defined in the Statement of Work in solicitation RFP MDA 972-92-R-0017. These eleven sub-sections make up a compendium of study phase reports that together form a comprehensive reference useful for gaining insight into the complexities and feasibility of developing application specific signal processors that meet MODEL YEAR cost, schedule, and upgrade objectives.



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## **2.0 Executive Summary**

### **2.0.1 Study-Task Objectives**

*The objective was to study eleven critical areas and document major issues, potential problems, possible solutions, current state-of-the-art, feasibility of RASSP objectives, and related work. The eleven areas are:*

- Design and Design-System Requirements
- Interoperability Considerations
- Design/Manufacturing Interface Considerations
- Manufacturing Considerations
- Testing Procedures
- Equipment Requirements
- Facility Requirements
- Database Requirements
- Teaming Arrangements
- Establishment of Military Sources
- Target Systems

### **2.0.2 Technical Problems**

The major technical issues are concerned with the Design System, Standards, industry integration and manufacturing resource links. Action items were accepted at the Final Program Review to expand on these issues. Three action items are addressed here as a summary.

#### **ACTION ITEM 1**

**Subjects: CFI, Block Releases, Expediting**

The Final Report should contain a discussion of the present CFI plan, a suggested approach for expediting the standards development, a suggested approach for expediting its promulgation by MENTOR, CADENCE, DEC, and COMPASS, and how the improved plan might fit in with the Raytheon concept of block releases.

During the Study Phase, CFI Inc. and various CAD framework vendors were approached

concerning this issue. CFI has provided us with their proposal and funding requirements profile. The industry interaction and nuances are complex and will find many problems to overcome in the course of obtaining full CFI and RASSP goals. Our approach is one of both "push" and "pull." CFI Inc. needs support and perhaps expansion of their projects. The industry needs a means of resolving conflict, but what is more important is ensuring that what evolves is fully marketable. The RASSP funding of CAE vendors to provide the various elements of Block one, Block two, and Block three "RASSP Design System" provides the "pull." It also establishes a mechanism, along with workshops, symposia and newsletter, to sell the capabilities to industry. This is accomplished not only through demonstrations, but through making the design system available to industry evaluators for hands on use.

CFI (CAD Framework Initiative) is an international cooperative effort within the electronics industry. CFI was formed in 1988 as a non-profit organization with the following mission: "Define interface standards that facilitate the integration of design automation tools for the benefit of end users and vendors worldwide."

Today's design engineers are generally not satisfied with the performance and functionality of their hardware and software automation tools. Because no single vendor offers the best solution for all users' design problems, users often piece together their own set of solutions. This results in wasted design time spent painfully integrating tools from different sources. CFI was formed to address this problem. Among its members are design automation vendors, computer and semiconductor suppliers, and CAD tool end users, as well as government, research and academic institutions. CFI believes that effective use of standard frameworks will raise productivity among users by providing interchangeable tools, and will allow vendors to focus on tool functionality rather than reinventing

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proprietary interfaces.

CFI believes that a framework should be a layered procedural interface, supported on multiple platforms, that is modular and easily extensible. The CFI mission is synergistic with other industry standards efforts, such as the Open Software Foundation (OSF), the Electronic Data Interchange Format (EDIF) and the government funded Engineering Information System (EIS) program.

Raytheon Company has a subscription membership to the CAD Framework Initiative and has been closely tracking the activities of CFI.

Much of the work of CFI is now documented in the draft specifications, user guides, reference software and regression tests. CFI refers to this collection of items as CFI Pilot Release 1.0. It includes the following draft standards.

- Design Representation Electrical connectivity Information Model and Programming Interface.
- Inter-tool Communication Procedural Interface
- Inter-tool Communication Architecture
- Inter-tool Communication Base Object Model and Interface
- Tool Encapsulation Specification
- Execution Log Format
- Base Networking Services Guideline
- Base System Services Guideline
- CFI Users, Goals and Objectives

## RASSP Applicability

The above standards will partially address many of the areas required for RASSP including Incremental Change/Analysis Tool Invocation and Control and a Standard Extension Language.

CFI's RASSP plan defines four Integration Phases: Phase 0-EDA Systems Integration, Phase 1- Manufacturing Integration, Phase 2-CASE/Codesign Integration, and Phase 3-Enterprise Integration.

What CFI brings to the RASSP program is a model for developing framework standards. CFI has been successful in selecting a specific problem, getting large end-user companies experiencing the integration problem to participate, and getting vendors to work together to solve the end user's problem by developing the appropriate standards. CFI's RASSP funding requests, totaling \$4.1 million over 4 years, covers CFI's costs of coordinating the framework standards development effort. It includes the cost of a program manager, general support to the vendors and end-users, development of specifications, technology, and regression tests. It does not include costs incurred by the vendors or end-users involved in the standards development effort. However, CFI has been successful in the past in getting companies to volunteer their own time and effort to develop the standards.

## CFI'S RASSP Phase 0 And CFI'S Release 2.0:

CFI's release 2.0 should complete CFI's work in the EDA area including specifications for a Multi-simulator Backplane and Library Standards. Process Management and Data Management standards are just beginning to be addressed. CFI admits that there is still much work to do in these areas, specifically regarding namespace resolution, and that without additional attention, standards will not be available in the short term. RASSP program influence with CFI and the contributing CAD vendors can shorten this schedule.

## CFI'S RASSP Phase 1:

The RASSP program could have a greater influence in the Manufacturing interfaces. These programs are still in the vision stage and there exists the possibility that they may not get off the ground at all without government input. Raytheon's general belief is that manufacturing interfaces would be developed by CFI regardless of the involvement of the RASSP program but would not be at a pace sufficient to ensure

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RASSP success.

## CFI'S Phase 2 And 3:

Standards for CASE/co-design and enterprise integration play a major role for RASSP. This is basically a "cottage industry" with no standardization. The RASSP program would have a large impact in this technology area. Without RASSP involvement, there is a chance these areas will not be addressed at all. Phase 2 and 3 cannot be accomplished within the RASSP program time frame. RASSP design system will provide an implementation that will seed further CFI standard development in these areas.

## Approach

Raytheon's suggested approach is to have the DARPA fund a number of resources available to all the RASSP contractor teams. These include CFI and NIST. The funding level for CFI should be approximately \$1 million over the four years. CFI will provide general support and consulting. This funding will also help CFI in development of specifications, technology, and regression tests. The contractor team should have, as team members, at least two framework companies and a group of CAD/CAM/CASE vendors. The two framework companies will ensure that the design system is not vendor specific. The CAD/CAM/CASE vendors will provide the needed design functions within the frameworks. The contractor team will ensure that the developed design system will meet RASSP goals and conforms to CFI standards. Within this teaming and support structure, RASSP and framework houses will be coordinating releases of the RASSP design system. The main reason for this approach is to reduce the risk of CAD/CAM/CASE vendors not participating and conforming with standards.

This approach will also expedite the standards development because real application implementation and demonstration will accelerate the development process.

With regard to CFI and the Raytheon concept of

block releases: our block releases will conform to whatever is available at the time.

- At block release one, not all EDA Systems integration standards will be ready. In block one release, the contractor will bring the design system (with its tool sets) to the CFI release 1.
- In block two release, the design system should conform with CFI release 2. There should also be some implementation of manufacturing integration that will be coordinated with CFI.
- In block three release, the design system will consist of upgrade of manufacturing integration to CFI's manufacturing integration standard. Block three release will also start the implementation of CASE/co-design integration. This implementation will contribute to CFI's CASE/co-design integration.

In summary, much of the standards related work required for the RASSP program will occur regardless of the RASSP program's involvement in CFI. However, the delivery dates and the sample implementation will probably not match those required by this program. CFI's track record in the development of standards is good and there is no reason to believe that, with proper funding and participation, the additional standards required for RASSP would not be accomplished in a timely and complete manner. Raytheon's teaming approach will facilitate working with CFI. Raytheon's design system block release will conform with CFI standards available at the time and will also help CFI's framework development process.

## ACTION ITEM 2

**Subject: RASSP CAE Investment Strategy**

Indicate which design system elements are critically important to RASSP and have probable development time lines that are compatible with RASSP's four year plan. Identify which current

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industry efforts are going in the right direction.

During the RASSP Study Phase, the Raytheon team researched applicable CAE tools and methods (commercially available, advanced research, and applicable DoD initiatives). These

are presented in section 3.1 of the study phase final report. Included with the list of tools is an overview of the functionality and input and output mechanisms. Some of the tools are compatible with the use of standards (for input modeling and use of libraries) within the current

| Tools  | Use of Modeling Standards (input & Output) | Integration with Standard Libraries | Ease of Use | Open Architecture | Link to Other CAE Tools   |
|--|--|-------------------------------------|-------------|-------------------|---|
| Scientific and Engineering Software (SES) Workbench  | Yes  | Yes                                 | Yes         |                   | Link to software through pictures   |
| JRS's IDAS   | Yes  |                                     |             |                   | Link to Synopsys' Design Architect  |
| Synopsys' Design Architect                           | Yes  | Yes                                 | Yes         |                   | Link to several target technology foundries and popular digital schematic capture tools |
| Mentor Graphics' System Design Station               | Yes  | Yes                                 |             |                   | Link to University of Virginia U/I Performance Models                                   |
| Redwood Design Automation Tools                      | Yes  | Yes                                 |             |                   | Unreleased information  |
| i-Logix's Statemate, Express-VHDL                    | Yes  |                                     |             |                   | Link to major logic synthesis tools   |
| University of Virginia's U/I VHDL Performance Models | Yes  | Yes                                 | Yes         |                   | Link from Mentor's Block Diagram capability   |
| IDE's Software Through Pictures                      | Yes  |                                     | Yes         |                   | Link to SES Workbench   |
| Cadre's Teamwork                                     | Yes  |                                     | Yes         |                   | Link to Statemate and ADAS  |
| Mentor's Falcon Framework                            | Yes  | Yes                                 | Yes         | Yes               |   |
| Calence's Framework                                  | Yes  | Yes                                 | Yes         | Yes               |   |

**TABLE 2.0-1 SET OF SYSTEM ENGINEERING CAE TOOLS**

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tools. To realize RASSP goals, the block one RASSP Design System will take advantage of existing tools and concepts that make integration easier. Early proof-of-principle can be completed within the first year of the RASSP program. The following are important criteria that are followed when choosing CAE tools to integrate into this first design system.

- Functionality
- Use of modeling standards (VHDL, Ada, Verilog, etc.) for input and output mechanisms
- Integration of CAE tool with standard libraries for COTS parts
- Ease of Use
- Open architecture
- Link to other CAE tools

A particularly strong effort will be made to incorporate system engineering tools. Table 2.0-1 highlights the criteria and gives a set of system engineering tools that are moving in the direction necessary for RASSP goals. The functionality for each of these tools is available in section 3.1 of the Final Report. Table 2.0-1 does not go into detail for software, hardware, and physical design phases of the system design life cycle. Tools for software, hardware, and physical design phases are well established -- integrated to a large extent -- and take advantage of current modeling standards and libraries.

These tools are currently conforming to one or more of the criteria described above and therefore can be integrated successfully into the block one RASSP Design System within the first year of the program. However, in order to meet long-term RASSP goals, several other design system elements are important. A list of those design system elements follows along with their expectations.

Tools with the following functionality are necessary for RASSP program and should be researched and developed under the RASSP

implementation phase.

- Hardware/software co-design tools
- System and subsystem functional partitioning/high-level synthesis tools
- System-level manufacturing advisor
- System-level logistics advisor
- System-level packaging compiler

## Database Technology

The type of database technology required for RASSP model year design system makes demands on data integration rather than traditional database technology. The fact that data is stored in relational, object-oriented or system file is less important than the fact that these data entities, however represented, must be integrated.

Many activities in information integration are aggressively being pursued on an academic and practical level. Research initiatives in this area, sponsored by DoD, have been ongoing since the 1970's with the Air Force Information Integration Support System (I2S2) program, and the recent XEROX Design Research Center's DICE contract for in its explicit support for concurrent engineering, which is a fundamental requirement of the RASSP design system. However, a prototype from the XEROX activity in the meta data management area will not be available until 1993 for review. Until then, it would be recommended that this activity be closely followed. Industry activities are also prominent, such as the CALS Data Dictionary Task Force. Further, Raytheon's internal investigation of integration technologies for its implementation of the Raytheon Integrated Technical Information Service (RITIS) has reviewed several commercial products for implementation of the data dictionary service. These products include integration technologies from HyperDesk, GRC, DEC, Information Builders, Control Data Corp., Etc. The most promising thus far has been the Distributed

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Object Management System, from HyperDesk, which is OMG compliant. It would be recommended for further investigation for data model implementation.

For Block one RASSP design system, the current Raytheon RITIS plan would be followed.

## CFI PROGRAM

It is anticipated that EDA and Manufacturing Integration will be completed within the RASSP program time frame. The RASSP program should provide direct funding to CFI for any additional integration strategies such as CASE/co-design Integration and Enterprise Integration. Additionally, the RASSP implementation team should provide input to the CFI standards efforts through its CAD team members.

## M. DL, AHDL, VHDL Programs

The RASSP program should provide input to and a strong presence within the standards bodies to ensure success. The definition of AHDL is slower in proceeding but will be defined within the RASSP program time frame. The MHDL program, under Intermetrics, is still in its early stages. RASSP emphasis is on VHDL and its expanded application in supporting CALS, PAPER, High Level Co-design, etc.

## Generic System Description Language

There exists the need to develop a standard representation for system models that can be used prior to partitioning system requirements into subsystems requirements and then those subsystems into their digital, analog, microwave, and software requirements. Currently, there are no standards or industry organizations addressing this issue. RASSP can monitor and provide inputs to incipient activities.

## Library Standardization

Developing standard library representations for performance models, functional models, reliability models, manufacturing process models, etc., are currently not being addressed under a unified standards organization and should be an area of investment under the RASSP program. Any progress made in this direction will add to the success of the RASSP program.

## AVAILABILITY OF ENGINEERING ESTIMATE MODELS FOR DESIGN, LOGISTICS, AND MANUFACTURING DATA

The Raytheon RASSP Design System concept relies on the existence of models at various levels of abstraction in order to assess the cost, risk, and benefit of design upgrades and in order to design for model year. Ensuring the methodology for development and maintenance of models is an important RASSP investment area.

## ACTION ITEM 3

### Subject: Target System Application Domain

Select a single application domain that would be recommended for use as the demonstration model during RASSP development. It appears that generalized ATR processor model that has modular options to accommodate requirements of Radar, Sonar, IR, Laser, MMW Sensors would be most suitable. The Target programs would be:

- Advanced Land Combat Vehicle (ALCVT)
- Joint Direct Attack Munitions (JDAM)
- Advanced Kinetic Energy Missile (ADKEM)
- Passive Torpedo  
Detection/Classification/Localization System

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(DCLASP)

- Sonar Mine Detection Set (AN/AQS-20)
- Ground Based Radar (GBR)
- Airborne Shared Aperture Program (ASAP)

A RASSP program option would be to use, as an initial demonstration model the Synthetic Aperture Radar (SAR) processing function for both JDAM and the air to ground portion of ASAP. Much of the algorithm technology has been derived from the same research. A common hierarchical VHDL model sourced from program executable specifications would contain solutions for both systems. The VHDL model contains modular options and parametrically driven design functions that would be assembled into appropriate hardware/software demonstration models. In initial program phases, scaled portions of the system would be used to exercise the brokered flexible manufacturing and test resources. As the RASSP program progresses, the underlying database models can be extended to include capabilities for additional ATR functions and the expanded processor needs of other system programs in this category. This short list also includes two sonar applications, two combat vehicle/tank applications and a major ground radar system.

## 2.0.3 General Methodology

The study process involved three principal elements:

- The personnel, IR&D and contracts currently involved in the study areas within Raytheon's four divisions:
  - Submarine Signal Division  
Portsmouth, RI
  - Missiles Systems Division  
Tewksbury, MA
  - Equipment Division  
Marlboro, MA
  - Electromagnetic Systems Division  
Goleta, CA
- Raytheon performed a concerted interviewing process of in-house experts and of industry resources. Industry resources were

expanded to include standards groups/consortia, service laboratories, CAD/CAM/CAT vendors and universities.

- The data gathered was analyzed and resulted in suggested approaches and feasibility. Feasibility analysis included both technical and schedule concerns. Detailed recommendations were established.

## 2.0.4 Technical Results

Raytheon's Study Phase investigations produced results in each of the eleven study areas. These results are listed below.

- Established a promulgation strategy through phased releases and design-system structure
- Conceptually linked test-beds, RASSP design-system and industry resources
- Determined team structure, expertise required, and sources of support
- Defined aspects of design methodology to support MODEL YEAR concept
- Developed S/W and H/W interoperability solution sets to support management of MODEL YEAR upgrades
- Developed RASSP design-system concept -- Framework, tools, standards
- Unique design-system features -- Visualization, electronic data books, early assessment
- Strategy for test which reduces all costs over product life cycle
- Conceptual integration of RASSP, ASEM, DICE, PAP-E, and commercial industry
- Structured plan for integration of multi discipline data using standards
- Target system selection driven by growth and volatility of threat

## 2.0.5 Important Findings and Conclusions

Significantly, the commercial and military industries are enthusiastically in support of a major RASSP initiative. This philosophical alliance has many forces: product affordability, time to market or rapid response, open architectures, standards, logistics and a growing evidence of the importance of co-developments

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or shared resources. The need to start immediately was evident. The initiative would establish the urgency and focus necessary to attain the standards (e.g., VHDL, CALS, CFI, etc.) which will promote increased industry investment in the tools, methodology and equipment necessary to meet the market places need for a RASSP development process.

In many application areas, the requirements for quickly providing state-of-the-art processing throughput at affordable life cycle costs have outgrown the last generation development paradigm. Two areas covered in some detail in this report are: Automatic Target Recognition and EW processors. Desert Storm experience was reviewed in these areas; the demands of fast response and advanced algorithms were much in evidence.

The systems front ends of CAD systems are lacking today and demand well thought out techniques for high level simulation, requirement traceability and early assessment tools supported with advanced visualization techniques. A RASSP program can get this effort started on the right track with a good standard foundation and an integration of the most promising available tools. A longer range development road map in this area is also important.

It has become apparent that expertise and resources are available but highly diverse. The management of a successful RASSP program must address this complexity, provide guidance, selective funding and intense coordination. Universities, national laboratories, service laboratories, system houses, major and minor CAD/CAM/CAT/CASE vendors, manufacturing contractors, and standards organizations are all part of this resource base. It is a national effort that must involve all willing participants.

## **2.0.6 Significant Hardware Development**

Raytheon did not develop any hardware under the RASSP Study Phase contract. Raytheon's efforts consisted of literature searches, discussions with industry leaders, and development of documentation.

## **2.0.7 Special Comments**

Comments pertaining to the eleven study tasks are found within Sections 3.1 to 3.11.

## **2.0.8 Implications for Further Research**

Where appropriate, implications for further research were highlighted within Sections 3.1 through 3.11.



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## **3.0 Detailed Study Phase Reports**

*During the RASSP Study Phase, the Raytheon team researched applicable CAE tools and methods (commercially available, advanced research, and applicable DoD initiatives). These are presented in section 3.1 of this report. Included with the list of tools is an overview of the functionality and input and output mechanisms. Some of the tools are compatible with the use of standards (for input modeling and use of libraries) within the current tools.*

One of our major concerns resulting from the investigations was the successful industry integration through promulgation of the design system.

To realize RASSP goals, the block-one RASSP Design System will take advantage of existing tools and methods that make integration easier. Early proof-of-principle can be completed within the first year of the RASSP program. The following are important criteria that should be followed when choosing CAE tools to integrate into this first design system.

- Functionality
- Use of modeling standards (VHDL, Ada, Verilog, etc.) for input and output mechanisms
- Integration of CAE tool with standard libraries for COTS parts
- Ease of Use
- Open architecture
- Link to other CAE tools

A particularly strong effort will be made to incorporate system engineering tools. Functional descriptions of system engineering tools are available in section 3.1 of this report. Tools are well established in areas such as software, hardware, and physical design. These tools are well integrated, and take advantage of current modeling standards and libraries. Currently, these tools conform to one or more of the criteria described above and therefore can be integrated

successfully into the block-one RASSP Design System within the first year of the program. However, in order to meet long-term RASSP goals, many other design system elements are important. Each of these elements is explained in Section 3.1.

Promulgation of the RASSP design-system and its associated product data models can be attained by providing the user community with access and involvement during the RASSP Implementation Phase. Access and involvement are key program elements in attaining the goal of widespread acceptance and use. Access to an operable system throughout the course of the development allows hands-on evaluation that benefits both the RASSP contractor and the industry user. Most major DoD contractors and commercial system houses invest each year in tool evaluation and in decisions to upgrade their CAE resources. If the program plan incorporates a phased development where sequential block releases of systems (block 1, 2, 3) are made available to industry at no cost, then the opportunities for interest, use and comments from the user community are greatly enhanced.

Block 1, 2, and 3 of the design system must make sense to the RASSP program and to the user community. Block 1 would result from the integration of available tools placed on available frameworks (Mentor, Cadence, Compass). Tools and standards would be strongly based on VHDL in its latest form(s). Block 2 would take advantage of on-going initiatives in commercial CAE, RASSP funded advanced development, DICE, MADE, MANTECH -- that fit the timeline. Full CFI standards would tie the system together. Block 3 would be the RASSP design system and incorporate suitable results of research activity and lessons learned from block 1 and 2. Raytheon anticipates that the user community would be proactive in their evaluation and perhaps propose additional projects for contract consideration. Maturing university research would also be transitioned into the block 3 system. Block 3 is obviously the

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commercialization baseline with the justifying econometrics being provided by increased user activity and system driven demonstrations. Figure 3.0-1 is a pictorial of this phased development. Block 1 provides a baseline. Block 2 resolves many of the issues related to the current technology. Block 3 addresses evolving technology and attempts to avoid the "generation gap" that often exists between mature/highly efficient CAE and the advanced hardware technology it addresses. An example of the last issue might be the CAE necessary to manage the "power and parasitics" of several hundred megacycle component interconnections.

Another example might be the ability to use assessment tools within a framework when "look-ahead" *ad hoc* CAE design/analysis tools are used for next generation product models (next model year interoperability issues). There

are many exciting possibilities that will come from research of design systems, languages, and system test bed interfaces which can be placed within the Block 3 framework and be allowed to mature even beyond the RASSP contract.

Involvement requires a system of selectable assets for use by the industry. Figure 3.0-2 highlights the idea of a multi-dimensional design system structure. Essentially, the structure can be viewed as partitioned (perhaps virtually) into "functions" represented horizontally. Vertically, each function has a tool set, data types and standards that are not necessarily exclusive to the particular functional domain. The advantages of this structure are several. The military systems house, the commercial systems house, or the commercial CAE vendor can gain access to a particular segment of interest without resorting to a complete resource commitment. For example,

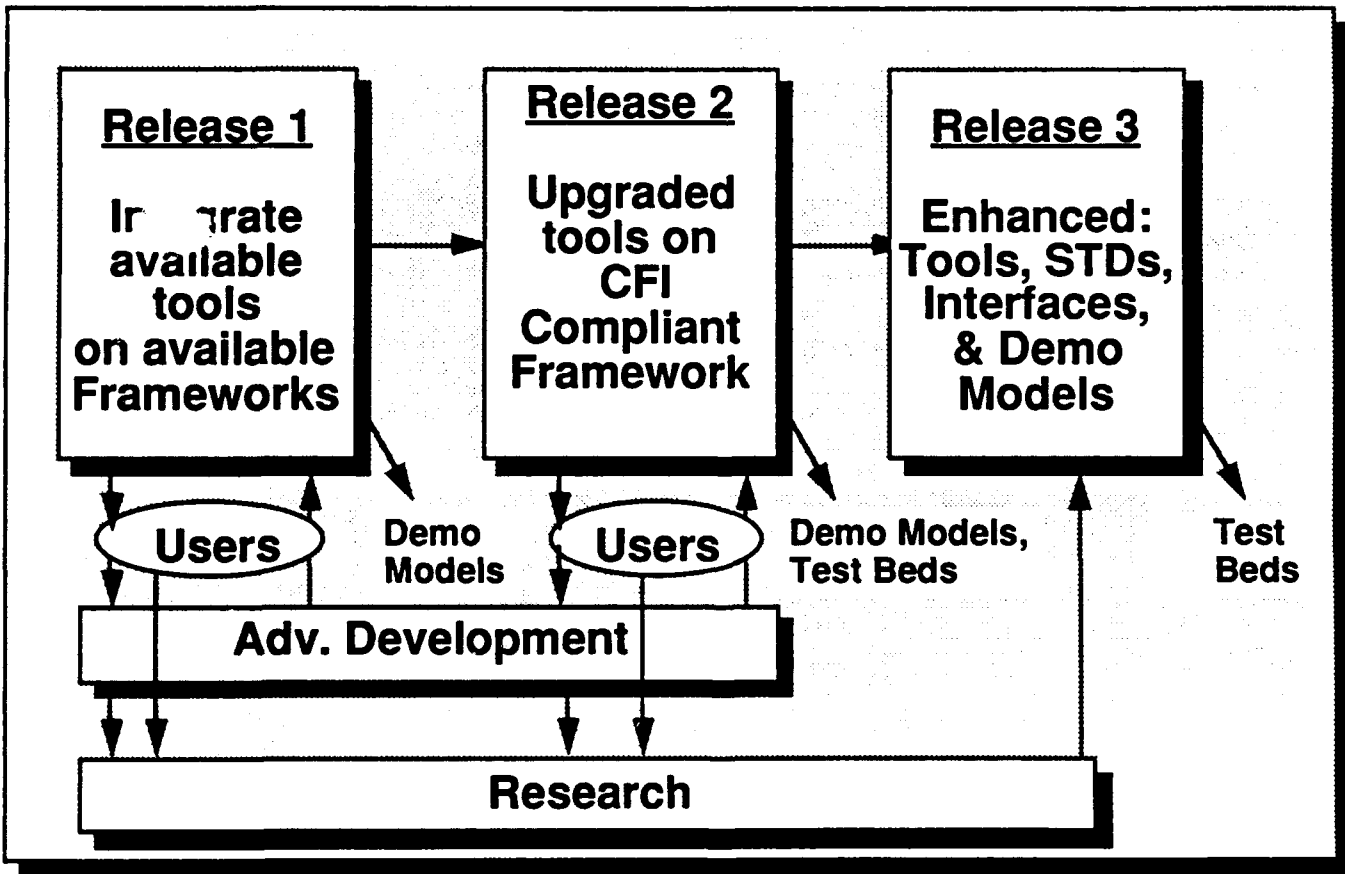


Figure 3.0-1, Phased Development Of The RASSP Design System

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a commercial CAE developer may find an increasing market for assessment tools and decide to focus their investment strategy in this area. Many other combinations of business and development situations can be envisioned. The system's structural focus on standards and the way in which functions, tools, libraries, manufacturing resources and test bed interfaces communicate throughout the design process provides an excellent environment for evaluation of upgrades, and additional language constructs and translators. This data is also made available through networked bulletin boards to the user community for comment and to the standards committees for consideration and potential action.

To meet program objectives RASSP products will rely heavily on ASICs and MCMs to realize the upgradability of the model year approach. Design agencies will need to have access to ASIC and MCM suppliers, and will demand flexibility

in how the interface is executed. While the ASIC industry is fairly well established, the MCM industry is in its infancy. Access to Application Specific Electronic Modules (ASEM) foundries will be facilitated by common electronic data exchange and an electronic brokering system. The ASEM brokering service would provide a mechanism for managing the acquisition of ASEM's through multiple suppliers. The broker manages the relationships with IC and MCM suppliers. This reduces the number of relationships to be managed by the design organizations. The broker would be responsible for qualifying suppliers, understanding vendor capabilities and particular areas of expertise, and responding to customer needs.

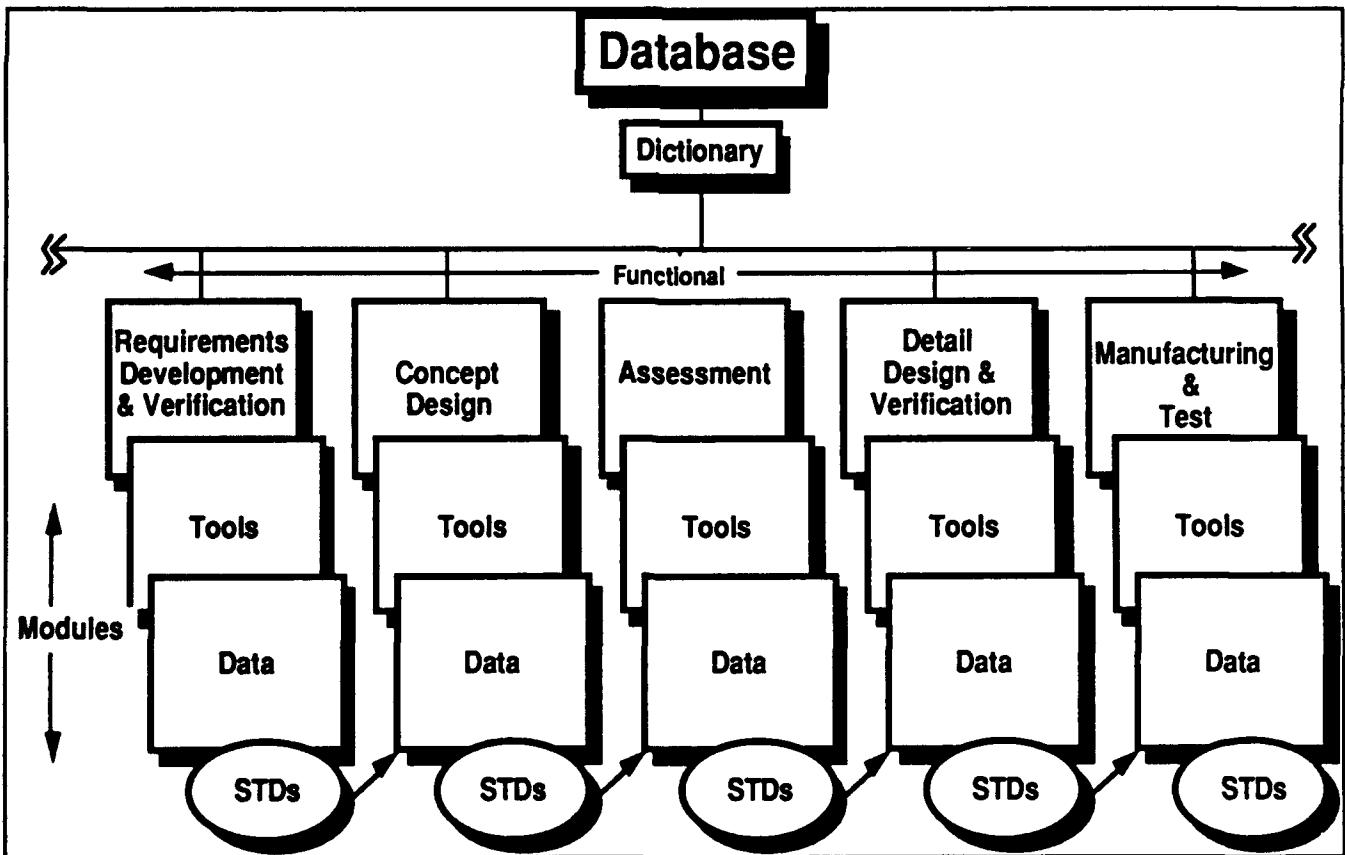


Figure 3.0-2, Multidimensional Design-System Structure

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## **3.1 Design and Design-System Requirements**

*An important element of the RASSP program is the RASSP Design System. The design system provides a support environment in which RASSP designers can assess the cost, risk and benefit of design upgrades early in the design cycle and provides a seamless environment for designing the present model year system. Given the RASSP model year concept, the designer needs to design today with look-ahead knowledge for two to three model years. The assessment criteria takes into account design information (such as the latest or next generation packaging technology or signal processing algorithm, etc.) but also takes into account manufacturing information (such as supplier capabilities - current and future, costs, lead time, etc.) and logistics information (such as field test equipment, spares, etc.). All of this data, if presented early enough, provides a good baseline for determining the feasibility of the upgrade prior to doing any detailed design or manufacturing.*

This section of the final report is organized as follows:

- Study Phase Accomplishments
- Overview of the RASSP Design System Architecture Concept
- Detailed description for each element of the RASSP Design System Architecture Concept
- RASSP Design System interface to the CALS delivery standards
- Major Issues to be addressed during development of the RASSP Design System
- Relevant Raytheon related efforts

### **3.1.1 Study Phase Accomplishments**

As a result of the RASSP study contract, a concept was developed for a system design environment which improves the design

capabilities available to the designer early in the design cycle and allows for the assessment of the impact of implementation architecture and technology on a system.

One of the key concepts is the development of an environment that has access to design, manufacturing and logistics engineering estimate and historical data. Access to historical logistics data allows the designer to assess design trade-offs based on historical support data and allows the designer to address historical support problems in the updated design. For new designs, historical data may not be available. For these cases, engineering estimates can be derived based on similar systems in the field or through theoretical models. Historical and estimated manufacturing data is also beneficial early in the design cycle. This information allows the designer to address prior manufacturability problems as the design is updated, as well as assessing the manufacturability of the design, available manufacturers, and the projected manufacturing cost.

A major portion of this phase was a study of the current state-of-the-art and advanced research in CAE tools and methodologies. The team assessed the applicability of integrating CAE tools from the current commercial CAE industry. Additionally, applicable advanced research currently underway at universities or through funded DoD initiatives was reviewed to fill in functional holes or incomplete solutions in the design system. Included in this report is a set of detailed matrices that outline various CAE tools available commercially or through advanced research avenues. Table 3.1-1 summarizes the basic design activities surveyed under the RASSP Study. Although there are tools for every activity of the design process listed, the utility of the tools is limited since they are not well integrated. Many have their own specialized data representation, and data entry means. In addition, some tools do not easily lend themselves to use by designers due to the knowledge required to operate them effectively.

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The key issues in the development and integration of tools under RASSP is the development and integration of the tools via standards, the development of a consistent means of invoking and interacting with the tools, and the ability to generate standard interchange formats to meet CALS deliverable requirements.

| Design Activities                |
|----------------------------------|
| Requirements Design and Analysis |
| Concept Design and Analysis      |
| Software Design and Analysis     |
| Hardware Design and Analysis     |
| Physical Design and Verification |
| Test Generation                  |
| Documentation                    |

**TABLE 3.1-1, RASSP DESIGN ACTIVITIES**

As part of the investigation of CAD design tools, a number of standards were investigated. The number of standards which impact CAD tools is large. They include the CFI standards for tool integration, the EDIF standards for data exchange, and standard languages for design and simulation (e.g. VHDL). However, additional standards must be considered to allow a consistent user interface, and the development of portable software. These standards are listed in Table 3.1-2. Any RASSP funded software should be consistent with these standards, as well as CFI and IEEE standards, to assure the implementation will not be obsolete in the near term, and that the software will be easily ported

to new platforms in the rapidly changing workstation and PC marketplace. Knowledge of the above mentioned standards are key to the development of a seamless design environment that is usable, extensible, supportable and portable.

As previously indicated, standards are an important technology for RASSP. We have evaluated some of the key standards such as VHDL and CFI to understand their implications. A major concern to the RASSP project is the length of time required to issue and update standards. As an example, VHDL is currently undergoing a revision, however, analog issues are not being considered for the 1992 release, which means they will not be available until the year 1997 at the earliest, since IEEE standards are reviewed on a 5 year basis. In other areas such as CFI, the initial standards will be voted on in 1992, however, additional standards as well as updates to the standards will be required to support RASSP. It is not clear that large funding will greatly increase the speed of the standards work, or the development of standards where none exist today. The adoption of standards is voted on by representatives of commercial firms, DoD contractors, universities and the DoD. It is important, therefore, to identify standards work that is of importance to RASSP and to influence voting representatives to push strongly for those standards. One manner of doing this is through RASSP implementation phase teaming arrangements with voting CAD members.

| Standard Organization | Name of Standard | Area of Applicability  |
|-----------------------|------------------|--|
| IEEE                  | POSIX            | Software standards to assure portability                         |
| ANSI                  | Various          | Computer languages, graphics standards, and networking standards |
| OSF                   | OSF/DCE          | Interoperability standard  |
| OSF                   | OSF/Motif        | Graphical user interface standard                                |
| UI                    | UNIX             | Interoperability standards                                       |
| X Consortium          | X Windows        | Protocol for base level graphics                                 |

**TABLE 3.1-2, SOFTWARE DESIGN STANDARDS**

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Additionally, the RASSP Design System will be incrementally upgraded and made available for evaluation three times throughout the implementation phase thereby giving non-team members a view of the product and the direction that CFI should head.

A key consideration in the proposed RASSP contract will be the split of funding between the development and enhancements of tools, versus the integration of tools via standards. A mixture of each activity is required, however, it is important to look at the benefits to be derived from improved synthesis and assessment tools for the system designer versus improve ease of use of currently used tools at the logic and physical design stages. Areas which are ready for exploitation include: executable specifications, requirements flow down, automatic system partitioning into commercially available parts, availability of models for design, manufacturing and logistics information, improved insertion of testability at all levels of the design, and improve manufacturability analysis prior to release to manufacturing. For RASSP to be successful, a careful funding trade-off must be performed between integration via standards which is occurring today without RASSP funding, and the acceleration of the

development of tools which are non-existent or in the prototype stage today.

Some of the technical challenges for improving the CAD tools above are being addressed in a number of DOD and DARPA initiatives. These initiatives include DICE, MADE, VTEST, etc. These programs should be leveraged by RASSP to eliminate duplicate funding and use RASSP funds to address needs not met. Table 3.1-3 lists a sample of the on-going and proposed efforts which should be monitored for inclusion in the RASSP program.

### 3.1.2 Overview of the Design System Concept

Figure 3.1-4 depicts the RASSP Design System architecture concept developed under the study phase contract. The concurrent engineering system provides a design, analysis, assessment and documentation environment for hardware and software codesign.

The design system will be implemented using commercial framework tools such as Mentor's Falcon framework and Cadence's Framework. It will be developed using the framework standards for tool and data integration and communication as defined by CFI. CAE tools will be encapsulated and integrated into the design

| Program Name                                     | Objective  |
|--|--|
| DICE (DARPA)                                     | Development and demonstration of enabling technologies for concurrent engineering                                |
| Simulatable Specifications (Wright Laboratories) | Develop guidelines/ methodologies and CAD tools to support the use and integration of simulatable specifications |
| PAP-E (Wright Laboratories)                      | PDES Application Protocols for electronics   |
| VTEST (Wright Laboratories)                      | Development of a virtual test environment to support multiple testers  |
| QUEST (DARPA)                                    | Advanced CAD algorithms for VHDL-based parallel processing   |
| Multi-Component Synthesis (Wright Laboratories)  | Extend high-level partitioning and synthesis algorithms and tools for multi-component devices                    |

**TABLE 3.1-3, DARPA AND DOD PROGRAMS OF INTEREST TO RASSP**

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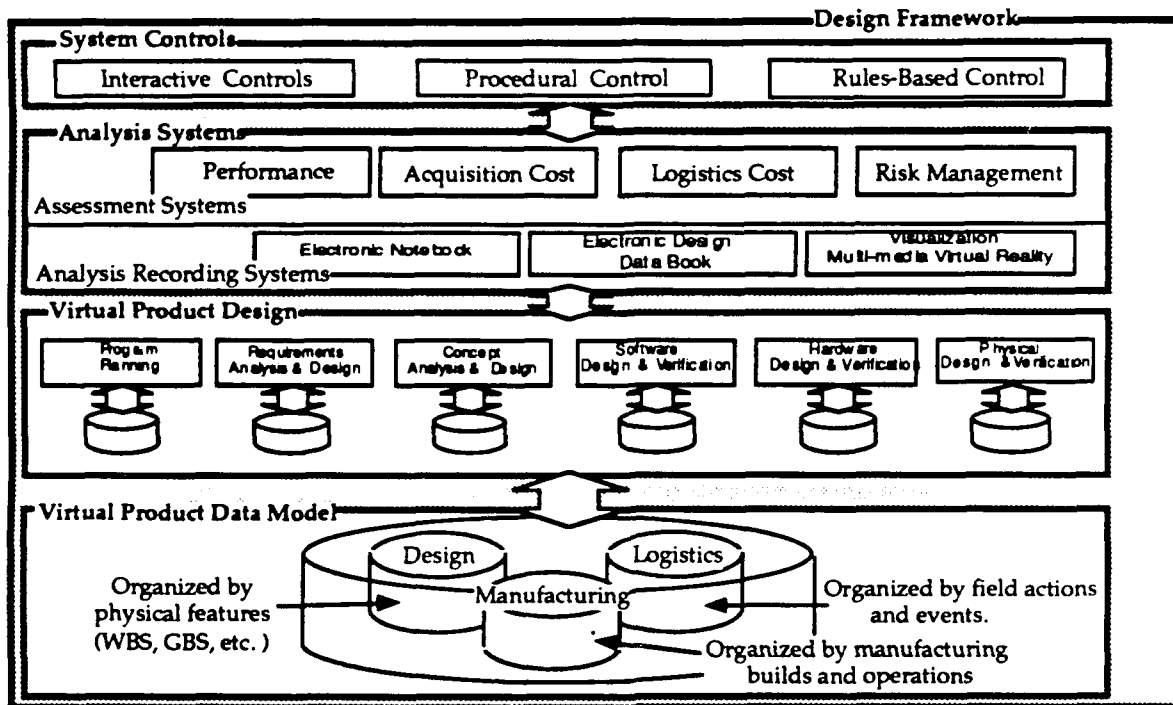


Figure 3.1-4, RASSP Design System Architecture Concept

framework. There are four main elements of the system:

1. Design System Framework (discussed in section 3.1.2.1)
2. Analysis Recording and Assessment Tools (discussed in sections 3.1.2.2.x)
3. Concurrent Engineering Product Design Tools (discussed in section (3.1.2.3)
4. Product Data Models that support the design system (discussed in sections 3.1.2.2.x)

Each of the four parts of the design system will be discussed in more detail throughout the remainder of section 3.1.2.

### 3.1.2.1 Design System Framework

In recent years, an EDA standards organization, the CAD Framework Initiative (CFI), was founded to develop a framework standard for CAD tools. CFI is an international cooperative effort within the electronics industry. CFI believes that a framework should be a layered procedural interface, supported on multiple platforms, that is modular and easily extensible.

The CFI mission is synergistic with other industry standards efforts, such as the Open Software Foundation (OSF), the Electronic Data Interchange Format (EDIF) and the government funded Engineering Information System (EIS) program. Raytheon Company has a subscription membership to the CAD Framework Initiative and has been closely tracking the activities of CFI. Much of the work of CFI is now documented in the draft specifications, user guides, reference software and regression tests. CFI refers to this collection of items as CFI Pilot Release 1.0. It includes the following draft standards:

- Design Representation Electrical Connectivity Information Model and Programming Interface
- Inter-Tool Communication Procedural Interface
- Inter-Tool Communication Architecture
- Inter-Tool Communication Base Object Model and Interface
- Tool Encapsulation Specification
- Execution Log Format

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- Base Networking Services Guidelines
- Base System Services Guidelines
- CFI Users, Goals and Objectives

The above standards will partially address many of the areas required for RASSP including Incremental Change/Analysis, Tool Invocation and Control and a Standard Extension Language. CFI has defined a plan that supports RASSP. This plan consists of four Integration Phases: Phase 0-EDA Systems Integration, Phase 1-Manufacturing Integration, Phase 2-CASE/Codesign Integration, and Phase 3-Enterprise Integration. What CFI brings to the RASSP program is a model for developing framework standards. CFI has been successful in selecting a specific problem, getting large end-user companies experiencing the integration problem to participate, and getting vendors to work together to solve the end-users problem by developing the appropriate standards. CFI's RASSP funding requests, totaling \$4.1 million over 4 years, covers CFI's costs of coordinating the framework standards development effort. It includes the cost of a program manager, general support to the vendors and end-users, development of specifications, technology, and regression tests. It does not include the costs incurred by the vendors or end-users involved in the standards development effort. However, CFI has been successful in the past in getting companies to volunteer their own time and effort to develop the standards.

CFI's RASSP Phase 0 and CFI's release 2.0: CFI's release 2.0 should complete CFI's work in the EDA area including specifications for a Multi-simulator Backplane and Library Standards. Process Management and Data Management standards are just beginning to be addressed. CFI admits that there is still much work to do in these areas, specifically regarding namespace resolution, and that without additional attention, standards will not be available in the short term. Without funding from the RASSP program, the EDA interfaces (CFI's release 2.0) will almost certainly be created anyway. These projects have

already begun. By adding additional funding, the RASSP program would have some influence in determining the release 2.0 delivery date and would be able to ensure that the RASSP problems were addressed. Without RASSP involvement, these standards will probably be delivered 3-6 months later than they would with RASSP involvement.

CFI's RASSP Phase 1: The RASSP program could have a far greater influence in the Manufacturing interfaces. These programs are still in the vision stage and there exists the possibility that they may not get off the ground at all without government input. Raytheon's general belief is that these manufacturing interfaces would be developed by CFI regardless of the involvement of the RASSP program. However, they would probably be developed at a slower pace.

CFI's Phases 2 and 3: As for standards for CASE/Codesign and Enterprise integration, RASSP could play a major role. This is basically a "cottage industry" with no standardization. The RASSP program would have a large impact in this technology area. Without RASSP involvement, there is a chance these areas will not be addressed at all. Phase 2 and 3 can not be accomplished within the RASSP program time frame, but the RASSP design system will provide an implementation that will seed further CFI standards development in these areas.

The suggested approach is to have DARPA fund a number of resources which will be available to all the RASSP contractor teams. These may include CFI and NIST. CFI will provide general support and consulting. This funding will also help CFI in development of specifications, technology, and regression tests. The contractor team should have, as team members, at least two framework companies and a group of CAD/CAM/CASE vendors. Working with two framework companies will ensure that the design system is not vendor specific. The CAD/CAM/CASE vendors will provide the needed design functions within the frameworks.



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The contractor team will insure that the developed design system will meet RASSP goals and conform to CFI standards. Within this team and support structure, RASSP and framework houses will be coordinating releases of the RASSP design system.

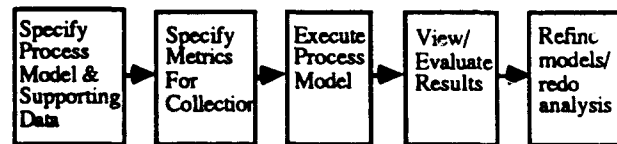
The main reason for this approach is to reduce the risk of CAD/CAM/CASE vendors not participating and conforming with standards. CFI's plan depends on vendors participating voluntarily. Given that many vendors are already involved with current CFI activities on their own funding, can they afford more free involvement? Also, some of the small vendors that will provide critical functions, may not have the resources to provide donations. This approach will also expedite the standards development because real application implementation and demonstration will accelerate the development process.

With regard to CFI releases and Raytheon's concept of block releases: our block releases will conform to whatever is available at the time. Releases are not necessarily marketable entities but are a structured design system made available to industry for evaluation.

- **Block One Design System:**
  - Not all EDA Systems integration standards will be ready. The contractor will bring the design system (with its tool sets) to the CFI release 1.
- **Block Two Design System:**
  - The design system will conform with CFI release 2. There will also be some implementation of manufacturing integration that will be coordinated with CFI.
- **Block Three Design System:**
  - The design system will upgrade its manufacturing integration interface to CFI's manufacturing integration standard. Block release 3 will also start

the implementation of CASE/codesign integration. This implementation will contribute to CFI's CASE/codesign integration effort.

In addition to the EDA framework, there is a need for a design process framework to control the flow of design data and the sequencing of CAD applications. Process control capabilities have been implemented on existing frameworks for modeling static flow. The RASSP design system should leverage the dynamic process control mechanisms that are available through DARPA's Initiative In Concurrent Engineering (DICE) sponsored Computer-Aided Concurrent Engineering/ Process Modeler (CACE/ PM) tool developed by Perceptronics and by the methodology developed by Carnegie Mellon University using the Statemate tool. CACE/ PM is a process modeling and simulation software package that supports modeling and analysis of the product development processes in terms of resource requirements, schedule, timelines, budgets, resource utilization time and cost, and activity flows. While EDA frameworks support tool integration, CACE/ PM supports process integration which is essential to concurrent engineering and allows the definition of metrics to measure development progress. The CACE/PM tool is currently encapsulated and running both stand-alone and under Mentor's Falcon framework. Figure 3.1-5 shows the flow of the CACE/ PM tool.



*Figure 3.1-5, Flow of the CACE/PM Tool*

For the software development environment, a process modeling and analysis capability has been researched and successfully implemented by Carnegie Mellon University's (CMU) Software

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Engineering Institute (SEI). Raytheon has used this methodology to model and analyze the software process through the use of the Statemate tool from i-Logix, Inc. Statemate provides a representation formalism that is highly visual, yet formally defined. Three types of diagrams are used to represent different perspectives of a process: 1) Functional perspective (Figure 3.1-6) - representing what functions are being performed, and what information flows are pertinent to the functions; 2) behavioral perspective (Figure 3.1-7) - representing when tasks are performed, along with feedback loops, iteration, complex decision-making conditions, etc.; 3) organizational perspective (Figure 3.1-8) - representing which organizational units perform the tasks and the physical communications mechanisms used for information transfer. One of the goals of the CMU project was to facilitate the management of a software development process to provide a basis for measurements, metrics, and data collection. Both of these methodologies should be looked at for potential application to RASSP.

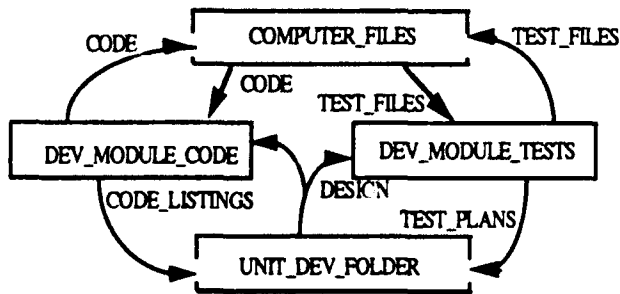


Figure 3.1-6, Statemate Functional Perspective

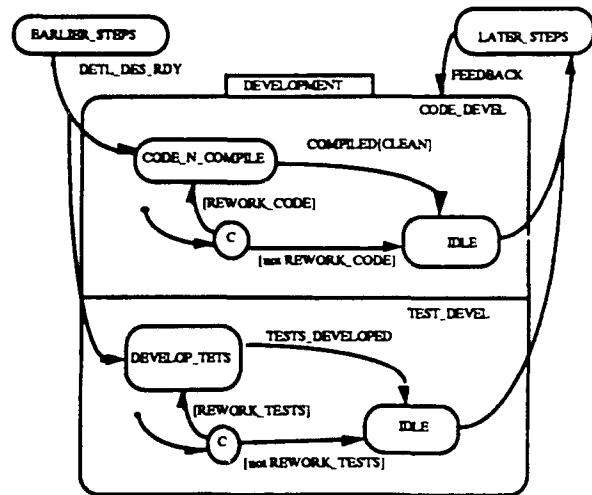


Figure 3.1-7, Statemate Behavioral Perspective

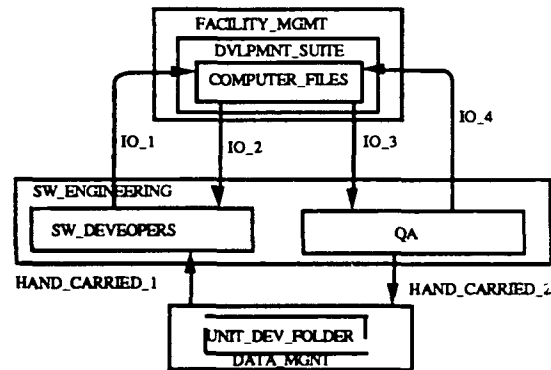
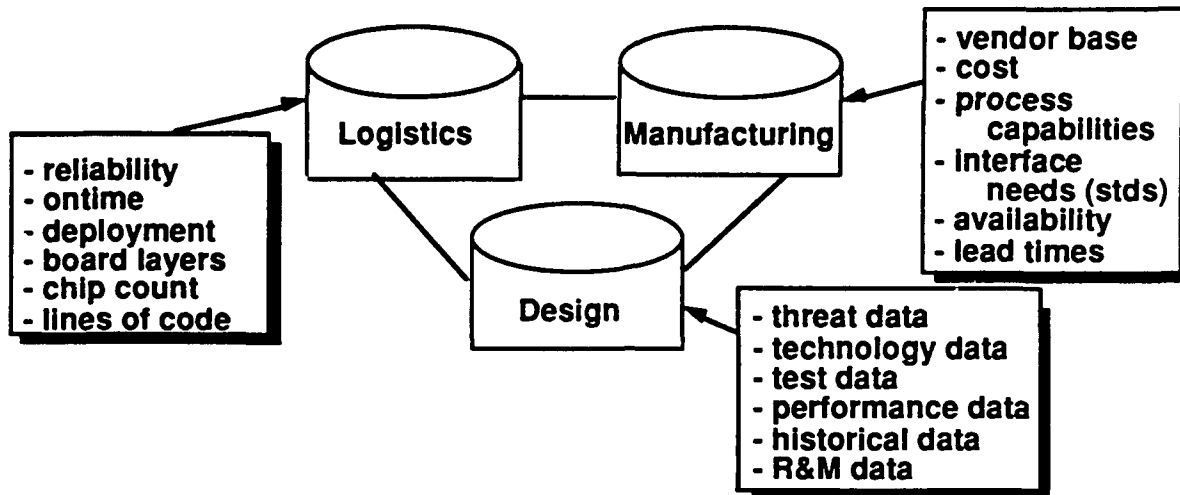


Figure 3.1-8, Statemate Organizational Perspective

### 3.1.2.2.1 Assessment Tools

In the design of systems, one of the current deficiencies in the tool suite is the lack of high level assessment tools that use engineering estimate and historical data to drive the assessments. The availability of this assessment capability would improve the accuracy of trade-off studies performed early in the design cycle. Historically the costs associated with design, manufacturing or logistics has not been made available to the system designer to allow that data to influence the updated design. One of the major achievements of the integration of assessment tools and a historical database would be to make information available to the designers

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*Figure 3.1-9, Examples of Estimate Data Elements*

and the assessment tools which will improve the design based on actual field support data, such as ease of fault identification and isolation, repair time due to accessibility of components, and part failure rates. Similarly for manufacturing, information on part availability, production lead times, and manufacturing capability play an important role in the design trade-off analysis of a system. Figure 3.1-9 is an example of data elements which would be analyzed by the assessment tools.

prototyping may be adequate for a high-level of analysis. However, when the modules are defined in more detail (as to functions, components, and structure), current design, logistics and manufacturing cost models can be used to give an accurate estimate of manufacturing cost. The concept of the data hierarchy is illustrated in Table 3.1-10.

Another difficulty with the current assessment tools is access to the appropriate type of data. That is, in the early phases of a design, the use of historically extrapolated engineering estimate data would be sufficient if available. The challenge is to meet the needs of the tools given their level of granularity and detail with supporting data at the same level. For example, knowing that a system is composed of 30 modules and an average module cost of \$100K for design and

### 3.1.2.2.2 Electronic Design Notebook

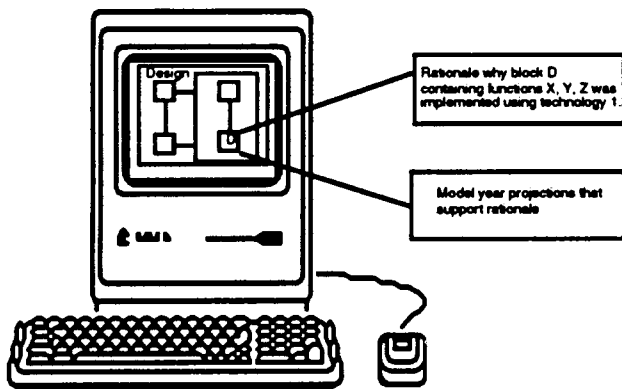
In the design of electronic systems, considerable effort goes into the formal documentation of the system. However, there is also a large amount of missing information. In the process of designing a circuit, the design engineer makes many decisions regarding the selection of parts, critical component placement, critical signal timing, and other information which is lost. In addition, information concerning the intent of function of the circuit, and the rationale for its design are also not documented. Thus upon re-design or updating by another engineer, the

| Design Phase             | Required Data                                 |
|--------------------------|---|
| Requirements Development | Historical extrapolated engineering estimates |
| Concept Development      | Technology data (current and look-ahead)      |
| Detail Design            | Actual engineering data                       |

**TABLE 3.1-10, DATA HIERARCHY**

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information in the original designer's head is not available, and has not been captured in the technical data package. With the electronic notebook the designer would be able to easily add notes to the design he is working on, and thus easily document all his detailed design decisions, and their rationale. The key issues for this notebook to work effectively are ease of use, non-intrusive to the design, and availability during all phases of the design. Information retrieval system and organization structure of the data in the notebook are requirements. Work in this area was performed under the DICE contract resulting in a product referred to as the Electronic Design Notebook (EDN). This system was based on the FRAMEMAKER tool, with dialog boxes and menus developed to ease the designers access to the notebook and data entry. The system allows the entry to not only textual data but also graphical and spreadsheet data. Figure 3.1-11a illustrates the Electronic Design Notebook concept. This capability should be integrated into the design environment under RASSP, since it is gaining acceptance in the industry, and STEP will provide a capability to store this information.

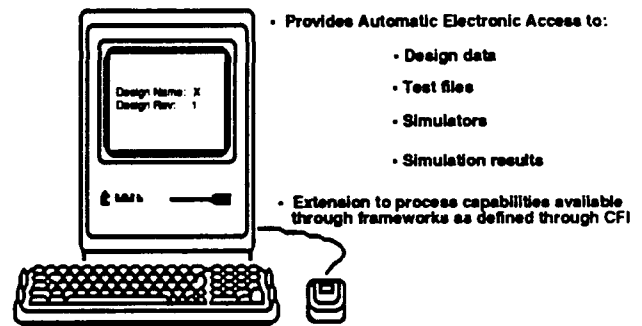


*Figure 3.1-11a, Electronic Design Notebook Concept*

### 3.1.2.2.3 Electronic Design Databook

In order for a system to be upgraded efficiently and effectively, the current designers must gain an understanding of the original design and must

work in a design system environment for concurrent engineering. To do that requires a combination of the electronic design notebook together with an electronic design databook. The electronic design databook provides immediate access to design data from the original and current design while the electronic design notebook provides access to the rationale for original, current, and look-ahead design decisions. Access to design information includes test files, simulation results, design schematics, documentation, etc. Today, designers can spend a considerable amount of time tracking down the correct revision and location of an electronic test file or design schematic. To assess the impact of a design change, the electronic design databook will provide automatic access to the appropriate simulator used to analyze the design and test file format that has changed. Figure 3.1-11b shows the Electronic Design Databook concept.



*Figure 3.1-11b, Example of Electronic Databook Concept*

Currently available commercial frameworks provide a portion of this capability through the static process flow capabilities. Additionally, there exists some commercial products that can be incorporated into the databook concept. An example is on-line access to component data. Designers spend considerable time searching through data books to select parts which meet the specifications for their design. Some systems, such as CAPS, provide on-line access to textual data, however, the extraction of the data for

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simulation or other electrical analysis is manual. ASPECT has developed a system which is beginning to meet the needs of the designer with an on-line search and extraction capability. More effort is needed to format the extracted data for the analysis tools. Data, such as schematic symbols with the proper data annotation, physical models for physical design and manufacturing checks, simulation models, and data for cost. This is an area where standards for databook formats, and standards for interfacing to analysis tools would benefit the users. Currently CFI under the Component Information Representation (CIR) Technical Subcommittee (TSC) is developing a standard for the component database, with a draft specification due in mid-1993.

### 3.1.2.2.4 Visualization Techniques

Until now, this report has focused on the gathering and analysis of design data. This section deals with the presentation of that design data. From research into virtual reality and visualization techniques, the interpretation of

complex data is realizable by many individuals representing different disciplines. Through research conducted at the University of San Francisco, Professor Bradford Smith stated that "The ability of many individuals to simultaneously view the display and, using their disparate experiences, negotiate the meaning of past data and likelihood of possible futures is a major strength of this analysis and presentational technique."

To apply this concept to RASSP needs, the team looked at the use of visualization techniques in the design system, for the display of complex design, logistics, and manufacturing data. To the expert in those disciplines, a detailed Mentor analysis or fault tolerance analysis report or perhaps the supplier's process capabilities etc. would be the best view on the data. Without the details, the interpretation of the results would not be as exact or complete as necessary. However, to the designer attempting to make an informed decision based on the process capabilities or life-cycle cost model, the details of that raw data are

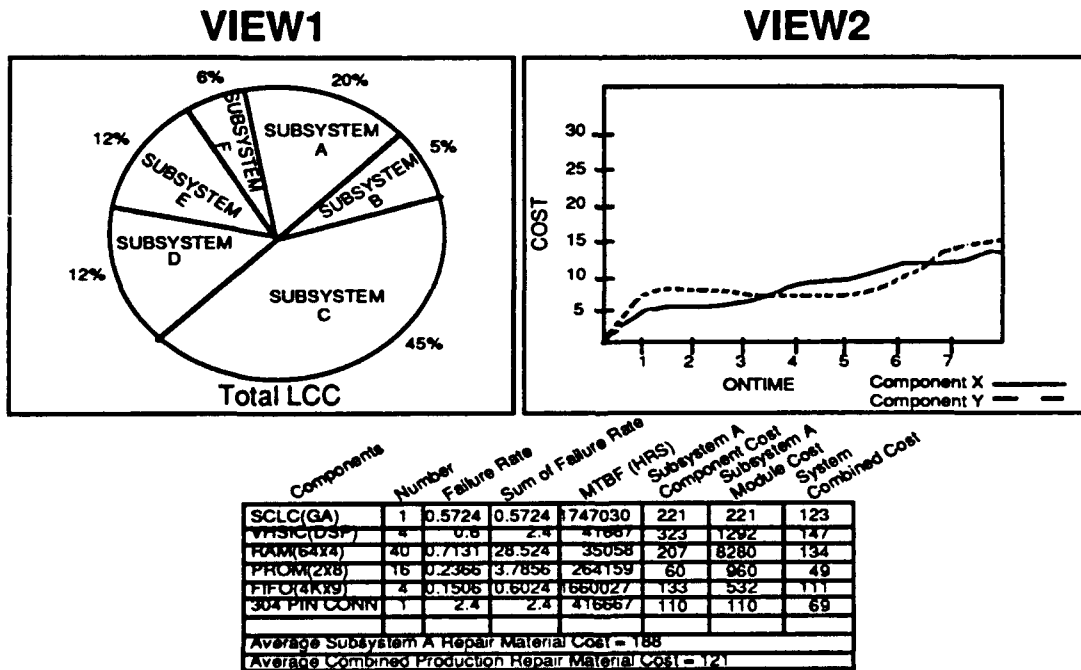


Figure 3.1-12, Alternate views on a dense LCC spreadsheet

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too complex to be of immediate use. In the case of RASSP, the assessment of the analysis results from a design upgrade trade study would be of use to several people, including the customer, program management and the system developer. The ability to view assessment data in a form that is meaningful and allows for a quick interpretation of the results would be important. Figure 3.1-12 shows an example of two different abstract views on a Life Cycle Cost (LCC) spreadsheet. In an LCC spreadsheet there are multiple relating parameters. A change in any one variable has the potential of producing multiple changes throughout the spreadsheet.

This example shows the LCC spreadsheet represented as:

VIEW1 - LCC subsystem percentage cost

VIEW2 - subsystem cost vs. system on time

In addition to the virtual reality research underway at the University of San Francisco, there is also work on Virtual Reality and Synthetic Environments at Washington University. Also, companies have begun to use visualization techniques within their current product line. An example is Mentor Graphics' Decision Support System (DSS) product.

### 3.1.2.3 Product Design Concurrent Engineering Environment

During the RASSP Study Phase, the team researched applicable CAE tools and methods

(commercially-available, advanced research, and applicable DoD initiatives). Some of the tools already rely on the use of standards (for input modeling and use of libraries) within their current tools. To realize RASSP goals, the block one RASSP Design System will take advantage of tools and concepts that use advanced techniques so that integration is easier and the proof-of-principle can be completed within the first year of the RASSP program. The following are the important criteria that will be followed when choosing CAE tools to integrate for the block one design system:

- Functionality
- Use of modeling standards (VHDL, Ada, Verilog, etc.) for input and output mechanisms
- Integration of CAE tool with standard libraries of COTS parts
- Ease of Use
- Open architecture
- Link to other CAE tools

Table 3.1-13a highlights the criteria and gives an example set of system engineering tools that are moving in the direction necessary for RASSP goals. The table does not go into detail for software, hardware and physical design phases of the system design life cycle. Tools used by designers in these phases are well established, integrated to a large extent, and taking advantage of current modeling standards and libraries.

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| Use of Modeling Standards<br>(input/ output)   | Integration with Standard Libraries  | Ease of Use  | Open Architecture   | Link to Other CAE Tools  |
|--|--|--|---|--|
| <ul style="list-style-type: none"> <li>-SES Workbench</li> <li>-IDAS</li> <li>-Synopsys Design Architect</li> <li>- Mentor System Design Station</li> <li>- Statemate/ Express V-HDL</li> <li>- VHDL</li> <li>- Redwood Design Aut.</li> <li>- University of Virginia U/I VHDL Performance models</li> </ul> | <ul style="list-style-type: none"> <li>-SES Workbench</li> <li>- Synopsys Design Architect</li> <li>- VHDL</li> <li>- Redwood Design Aut.</li> <li>- University of Virginia U/I VHDL Performance models</li> </ul> | <ul style="list-style-type: none"> <li>- SESWorkbench</li> <li>- Teamwork</li> <li>- Mentor to UVA U/I Performance models</li> <li>- Software thru Pictures</li> </ul> | <ul style="list-style-type: none"> <li>- Mentor Falcon Framework (and suite of design tools)</li> <li>- Cadence Framework (and suite of CAE tools)</li> <li>- DEC Framework (and suite of CAE tools)</li> <li>- Racal-Redac Framework (and suite of CAE tools)</li> </ul> | <ul style="list-style-type: none"> <li>- Statemate to Teamwork</li> <li>- Statemate to Synopsys (&amp; other synthesis companies)</li> <li>- Statemate to UVA U/I models</li> <li>- Mentor to UVA U/I models</li> <li>- ADAS to Teamwork</li> <li>- IDAS to Synopsys</li> <li>- SES Workbench to Software thru Pictures</li> </ul> |

**TABLE 3.1-13A, EXAMPLE SET OF SYSTEM ENGINEERING CAE TOOLS CURRENTLY MEETING RASSP DESIGN SYSTEM CRITERIA**

This table provides an example set of tools that are currently conforming to one or more of the criteria elements described above and therefore can be integrated successfully into the block one RASSP Design System release within the first year of the program. However, in order for

RASSP to be successful, several other design system elements are important for meeting RASSP goals. A list of important design system elements follows along with the expectations for which of these elements are being addressed by industry within the time frame of this program.

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- CFI Program: EDA and Manufacturing Integration will be completed within the RASSP program time frame regardless of additional RASSP funding. The RASSP program should provide direct funding to CFI for any additional integration strategies such as CASE/ Codesign Integration and Enterprise Integration.
- MHDL, AHDL, VHDL Programs: VHDL is continuing to proceed and will do so regardless of additional RASSP funding. However, the RASSP program should provide input to and a strong presence with the standards bodies to ensure success. The definition of AHDL is slower in proceeding but will be defined within the RASSP program time frame. The MHDL program, under Intermetrics, is still in its early stages and will need to be monitored to determine its RASSP potential.
- Generic System Description Language: - There exists the need to develop a standard representation for system models that can be used prior to partitioning a system into digital, analog, microwave, and software subsystems. There is currently no standards or industry organization addressing this issue. It is important for RASSP goals and should be an area of investment for RASSP.
- Library Standardization: Developing standard library representations for performance models, functional models, reliability models, manufacturing process models, etc. is an area that the RASSP program should consider as an investment area.
- Database Integration Techniques: The industry move towards integrated databases rather than the replacement of existing databases is emerging with various data dictionary techniques that use metadata to describe the relationships between existing

databases. Tools, such as those under development by Xerox, are moving forward and should be available for use on the RASSP program.

- Availability of engineering estimate models for design, logistics and manufacturing data: The Raytheon RASSP Design System concept relies on the existence of models at various levels of abstraction in order to assess the cost, risk and benefit of design upgrades and in order to design for model year. Ensuring that these models are available should be a consideration and a possible RASSP investment area.
- Development of CAE tools which provide the following functionality: This functionality is necessary for the RASSP program and it should be a possible RASSP investment area.
  - Early assessments based on engineering estimate data
  - Hardware/ Software codesign tools
  - System and subsystem functional partitioning/high-level synthesis tools
  - System-Level manufacturing advisor
  - System-Level logistics advisor
  - System-Level packaging compiler
  - Behavioral mixed-mode simulation (Behavioral VHDL co-simulated with Behavioral MHDL)
  - System-Level Testability Advisor/ BIT Insertion

Under the product design concurrent engineering environment, the product design activities are as follows:

- Requirements design and analysis
- Concept (preliminary) design and analysis
- Software design and analysis
- Hardware design and analysis
- Physical design and analysis

In keeping with the concurrent engineering philosophy, these product design activities work



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in parallel and do not necessarily need information from one phase in order to complete work in another phase (although that paradigm will work also).

Each of these phases breaks down into the major activities performed under the phase. For example, under the requirements design and analysis phase, the four major activities performed are:

1. Requirements Development
2. Requirements Analysis
3. Requirements Traceability
4. Requirements Documentation

Under the study phase, the Raytheon team researched the state-of-the-art CAE tools (commercially available and public domain), applicable research efforts, and applicable DoD programs available for each activity. Additionally, we researched the advanced ideas and methods for those areas. The following subsections break down each of those phases into the major activities, provides a matrix chart detailing a subset of State-Of-The-Art (SOTA) and advanced research tools and methods for those activities. Additionally, a detailed table is included that details all tools and methods identified and researched as applicable under the RASSP study phase.

### 3.1.2.3.1 Requirements Design and Analysis Phase

The main activities in system requirements design and analysis are:

- 1) Requirements Development (Dev.)
- 2) Requirements Analysis (Anal.)
- 3) Requirements Traceability (Trace)
- 4) Requirements Documentation (Doc.)

Tables 3.1-13 and 3.1-14 represent a subset of the tools (both current state-of-the-art and advanced research) that address the system requirements design and analysis activities.

Table 3.1-15 gives details for each of the tools researched. A brief overview of the pros and cons found during our study for a sample set of tools follows:

### State-of-the-Art

| Tools         | Dev. | Anal. | Trace | Doc |
|---------------|------|-------|-------|-----|
| VHDL          | ✓    | ✓     |       | ✓   |
| Statemate     | ✓    | ✓     |       |     |
| RDD           | ✓    | ✓     | ✓     |     |
| TAGS          | ✓    | ✓     |       |     |
| Product Track |      |       | ✓     |     |
| Rtrace        |      |       | ✓     | ✓   |

**TABLE 3.1-13B, EXAMPLE SET OF STATE-OF-THE-ART CAE TOOLS FOR THE SYSTEM LEVEL REQUIREMENTS ANALYSIS PHASE**

### Advanced Research

| Tools              | Dev. | Anal. | Trace | Doc |
|--------------------|------|-------|-------|-----|
| Syst. Des. Station | ✓    | ✓     | ✓     | ✓   |
| Redwood Des. Aut   | ✓    | ✓     | ✓     |     |
| Martin Marletta RM |      |       | ✓     | ✓   |
| HRL RAPIDWS        | ✓    | ✓     | ✓     | ✓   |

**TABLE 3.1-14, EXAMPLE SET OF ADVANCED RESEARCH CAE TOOLS AND METHODS FOR THE SYSTEM LEVEL REQUIREMENTS ANALYSIS PHASE**

The VHDL (VHSIC Hardware Descriptive Language) standard is used to develop, analyze, and document system requirements and design. The VHDL standards committee has continued to advance the standard language with features necessary for it to be the complete top-down design and documentation language for electronics. Through design and development of

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the RASSP Design System, the RASSP team will identify any features missing or incomplete in VHDL and will work with the standards organization to address the issues.

The Statemate tool, from i-Logix, Inc., is used to graphically develop and analyze system requirements. Statemate requires proprietary graphical languages as input and will not accept input from any other graphical or textual environment. Statemate outputs C, Ada, VHDL, MIL-STD 2167A (and user-defined) documentation. The current version of Statemate does not allow the use of parameterized library models. It has been used at Raytheon for developing and analyzing system, software and digital hardware requirements.

The Product Track tool, from Cimflex Technologies, was originally developed under

DARPA DICE funding (originally called Requirements Manager). It gives the user the ability to track requirements throughout the design process. It does not, however, automatically link from the allocated requirements to the appropriate design documents, design models and design rationale that support those requirements. If a requirement changes, updates must be tracked manually to assure synchronization.

A new, as yet unreleased, tool from Redwood Design Automation provides the capabilities of developing, analyzing, and documenting requirements. It will provide both a VHDL & a Verilog input and output mechanism. It will support library models.

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| Tool Name                 | Company Name                 | Function  | Input Formats                                 | Output Formats                  | Commercial / Research / DoD / IR&D | Released / Unreleased |
|---------------------------|------------------------------|---|---|---------------------------------|------------------------------------|-----------------------|
| Statemate                 | i-Logix, Inc.                | Reqs. Design & Analysis   | Statemate Proprietary Graphical Languages     | C, Ada, VHDL, 2167A             | Commercial                         | Released              |
| RDD                       | Ascent Logic Corp.           | Reqs. Design & Analysis & Traceability                              | RDD Proprietary Graphical Languages           | C, Ada, VHDL, 2167A             | Commercial                         | Released              |
| TAGS                      | Teledyne Brown Eng.          | Reqs. Design & Analysis   | TAGS Proprietary Graphical Languages          | C, Ada, VHDL, 2167A             | Commercial                         | Released              |
| Various VHDL simulators   | Various Vendors              | Reqs. Design & Analysis   | VHDL & Verilog                                | VHDL simulation model VHDL doc. | Commercial                         | Released              |
| Redwood Design Automation | Redwood Design Automation    | Sys. Design Reqs. & Performance Analysis, simulation w/ COTS models | VHDL & Verilog                                | VHDL & Verilog                  | Commercial                         | Unreleased            |
| System Design Station     | Mentor Graphics              | Reqs. Design & Analysis   | Mentor Proprietary Graphical Languages & VHDL | VHDL, links to CASE tools       | Commercial                         | Unreleased            |
| Rtrace                    | Protocol                     | Reqs. Traceability  | Reqs./ Documents                              | Reqs. Matrix                    | Commercial                         | Released              |
| Product Track             | Cimflex                      | Reqs. Traceability  | Reqs./ Documents                              | Reqs. Matrix                    | Commercial                         | Released              |
| Raytracer                 | Raytheon                     | Reqs. Traceability  | Reqs./ Documents                              | Reqs. Matrix                    | Raytheon IR&D                      | Released              |
| AF Program RAPIDWS        | Knowledge Based Systems Inc. | Reqs. Traceability / Analysis                                       | Reqs./ Documents                              | Reqs. Matrix                    | AF's HRL DoD Program               | Unreleased            |
| RM                        | Martin Marietta              | Reqs. Traceability  | Reqs./ Documents                              | Reqs. Matrix                    | Martin Marietta IR&D               | Released              |

**TABLE 3.1-15, DETAILED INFORMATION ON THE SYSTEM LEVEL REQUIREMENTS ANALYSIS TOOLS RESEARCHED**

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## 3.1.2.3.2 Concept (Preliminary) Design and Analysis Phase

The main activities in concept design and analysis are:

- 1) Concept Development (CD)
- 2) Functional Analysis (F)
- 3) Performance Analysis (P)
- 4) Testability Analysis (T)
- 5) Manufacturability Analysis (M)
- 6) Reliability/ Safety Analysis (R/S)
- 7) Functional Partitioning (FP)
- 8) High-Level Synthesis (S)
- 9) HW/SW Co-design (C)

Tables 3.1-16 and 3.1-17 represent a subset of the tools (both current state-of-the-art and advanced research) that address the concept design and analysis activities. Included in this section is a brief overview of the pros and cons found during our study for a sample set of tools. Additionally, Table 3.1-18 gives details for each of the tools researched in our study.

| Tools          | State-of-the-Art |   |   |   |   |     |    |   |   |
|----------------|------------------|---|---|---|---|-----|----|---|---|
|                | CD               | F | P | T | M | R/S | FP | S | C |
| VHDL           | ✓                | ✓ |   |   |   |     |    |   |   |
| IDAS           | ✓                |   | ✓ |   |   |     | ✓  | ✓ | ✓ |
| Statemate      | ✓                | ✓ | ✓ | ✓ |   | ✓   |    |   |   |
| SES Workbench  | ✓                |   | ✓ |   |   |     |    |   |   |
| ADAS/ Teamwork | ✓                | ✓ | ✓ |   |   |     |    |   |   |
| HARP           | ✓                |   |   |   |   | ✓   |    |   |   |
| STAT           | ✓                |   |   | ✓ |   |     |    |   |   |

**TABLE 3.1-16, EXAMPLE SET OF STATE-OF-THE-ART CAE TOOLS FOR THE CONCEPT DESIGN AND ANALYSIS PHASE**

The IDAS tool, from JRS Research, Inc., allows the user to design and analyze processors, software, and pre-processing hardware for embedded processing systems concurrently. The tool inputs an Ada algorithm and a subset of VHDL, generates microcode to run on the target architecture, and evaluates the performance of the embedded processing system through simulation. Under the DARPA DICE initiative, the IDAS tool is being enhanced to include additional hardware

entities, architectural rules and to accept multiple behavioral specifications.

| Tools                    | Advanced Research |   |   |   |   |     |    |   |   |
|--------------------------|-------------------|---|---|---|---|-----|----|---|---|
|                          | CD                | F | P | T | M | R/S | FP | S | C |
| MCC Testability Advisor  | ✓                 |   |   | ✓ |   |     |    |   |   |
| UVA U/ VHDL Models       | ✓                 | ✓ | ✓ |   |   | ✓   |    |   | ✓ |
| DICE Man. Opt.           |                   |   |   |   | ✓ |     |    |   |   |
| University of Cincinnati | ✓                 | ✓ |   |   |   |     |    |   |   |

**TABLE 3.1-17, EXAMPLE SET OF ADVANCED RESEARCH CAE TOOLS AND METHODS FOR THE CONCEPT DESIGN AND ANALYSIS PHASE**

The SES Workbench tool, from Scientific and Engineering Software, Inc., provides the user with a proprietary graphical input format to analyze the performance of the system concept. The tool provides a link to the CASE tool from IDE called Software Through Pictures. This allows the user to develop software functional requirements and manually analyze them for conformance to the performance requirements defined in SES Workbench.

The University of Virginia is researching the applicability of using VHDL to model and analyze the system concept for conformance to functional, performance, reliability, and operational concept requirements. In addition, UVA is looking at VHDL as an environment for hardware and software codesign. UVA has defined a set of primitive VHDL models that can be used to create the simulation models.

To realize model year objectives, RASSP designers must have tools available to analyze the producibility/ manufacturability of the design at an early point in the design cycle. Current and future information regarding the vendor base capabilities, costs, availability, etc. must be analyzed. Under the DARPA DICE program, Raytheon's Manufacturing Optimization program is bringing manufacturing information to module designers during the design process. These capabilities must be extended to the system designers under the RASSP Design System.

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**TABLE 3.1-18, DETAILED INFORMATION ON THE CONCEPT DESIGN AND ANALYSIS TOOLS RESEARCHED**

| Tool Name               | Company Name                                | Function   | Input Formats  | Output Formats   | Commercial / Research/ DoD / IR&D | Released/ Unreleased             |
|-------------------------|---|--|--|--|-----------------------------------|----------------------------------|
| Statemate               | i-Logix, Inc.                               | Performance Analysis                                 | Statemate Proprietary Graphical Languages                  | Performance statistics, C, Ada, VHDL, 2167A doc.               | Commercial                        | Released                         |
| ADAS/ Teamwork          | Research Triangle Institute/ Cadre          | Performance Analysis linked to S/W Reqs. Design Tool | Petri Nets   | Performance Statistics/ Teamwork's input language format/ VHDL | Commercial                        | Released                         |
| CPN                     | MetaSoftware                                | Performance Analysis                                 | Colored Petri Nets   | Performance statistics   | Commercial                        | Released                         |
| VHDL Performance Models | University of Virginia                      | Performance Analysis - HW/SW Codesign                | VHDL   | Performance statistics   | Research                          | Released                         |
| VHDL Performance Models | Honeywell                                   | Performance Analysis                                 | VHDL   | Performance statistics   | Honeywell IR&D                    | Released                         |
| USEE                    | Raytheon                                    | Performance Analysis                                 | Colored Petri Net defined in LISP                          | Performance statistics   | Raytheon IR&D                     | Released                         |
| SES Workbench/ STP      | Scientific and Engineering Software Inc./IE | Performance Analysis                                 | SES Proprietary Graphical Languages                        | Performance statistics/ STP's input language format            | Commercial                        | Released                         |
| N.3                     | TD Technologies, Inc.                       | Performance Analysis                                 | ISP, C, VHDL, Verilog, N.3 Proprietary Graphical Languages | Performance Statistics   | Commercial                        | Unreleased beta product Q4, 1992 |
| Matrix-X                | Integrated Systems Inc.                     | Control System Design and Implementation             | Matrix-X Proprietary Graphical Languages                   | Ada, C, FORTRAN  | Commercial                        | Released                         |
| HARP                    | NASA Langley                                | R&M Analysis   | Proprietary Graphical Languages                            | System Failures  | Public Domain                     | Released                         |

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|                                 |   |                                     |  |   |                                  |            |
|---------------------------------|---|-------------------------------------|--|---|----------------------------------|------------|
| SURE                            | NASA Langley  | Finite State                        | Proprietary Language                                 | System Reliability  | Public Domain                    | Released   |
| CARAT                           | Raytheon  | R&M Analysis                        | Subsystem & Block Failure Data                       | System Reliability  | Raytheon IR&D                    | Released   |
| FLEX                            | Navy  | LCC                                 | GB & WBS Support Environment                         | Cost Analysis Data  | Public Domain                    | Released   |
| Price                           | GE  | LCC                                 | GB & WBS Support Environment                         | Cost Analysis Data  | Commercial                       | Released   |
| STAT                            | DETEX Systems Inc.                                    | Testability Analysis & Diagnostics  | STAT Proprietary format for H/W Block Diagram        | ASCII reports & STAT proprietary format   | Commercial                       | Released   |
| WSTA                            | Harris  | Testability Analysis & Diagnostics  | VHDL & WSTA Proprietary format for H/W Block Diagram | ASCII reports & WSTA proprietary format   | Navy Program                     | Released   |
| IDAS                            | JRS Research  | Custom Processor Software synthesis | Ada, C, VHDL   | Microcode running on target architecture, rapid test results of design alternatives | Commercial                       | Released   |
| Multi-Component Synthesis Tools | University of Cincinnati, Michigan State, DASYS, Inc. | Multi-Component Synthesis           | VHDL   | Partitioned MCM   | Wright Laboratories' DoD program | Unreleased |
| Signal Processing WorkStation   | Comdisco Systems, Inc.                                | DSP Design & Analysis               | SPW Proprietary Graphical Languages                  | VHDL that drives Synopsys synthesis tool  | Commercial                       | Released   |
| DSP                             | Mentor Graphics                                       | DSP Design & Analysis               | VHDL, Mentor Languages                               | VHDL, silicon compiler/synthesis format   | Commercial                       | Released   |
| Hypersignal                     | Hyperception  | DSP Design & Analysis               | Hypersignal Proprietary Graphical Languages          | Text displays   | Commercial                       | Released   |
| HiTEA                           | MCC   | Testability Advisor                 | VHDL   | Recommendations   | Research                         | Released   |

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## 3.1.2.3.3 Software Design and Analysis

The main activities in software design and analysis are:

- 1) Software Reqs Development (RD)
- 2) Preliminary Design (PD)
- 3) Detail Design Development (DD)
- 4) Code and Unit Test (CUT)
- 5) Integration and Test (IT)
- 6) Independent Validation & Verification (IV&V)

Table 3.1-19 represents a subset of the tools that address the software design and analysis activities. Table 3.1-20 gives details for a subset of the tools researched. Advanced technologies that should be leveraged on RASSP are being done under DARPA's DSSA (Domain Specific Software Architecture) program, SW Reusability, and Synthetic Environments research.

| Tools                | State-of-the-Art |    |    |     |    |      |
|----------------------|------------------|----|----|-----|----|------|
|                      | RD               | PD | DD | CUT | IT | IV&V |
| STP                  | ✓                | ✓  |    |     |    |      |
| Statemate            | ✓                | ✓  |    |     |    |      |
| Interleaf            | ✓                | ✓  | ✓  |     |    |      |
| Teamwork/SART        | ✓                | ✓  |    |     |    |      |
| Teamwork/Ada         |                  |    | ✓  |     |    |      |
| Teamwork/DSE         |                  |    | ✓  |     |    |      |
| Ada Compiler         |                  |    |    |     | ✓  |      |
| Static Analyzer      |                  |    |    |     | ✓  |      |
| Performance Analyzer |                  |    |    |     | ✓  |      |
| Coverage Anal.       |                  |    |    |     | ✓  |      |
| Support SW           |                  |    |    |     | ✓  |      |
| Thread Testing       |                  |    |    |     | ✓  |      |
| Integration          |                  |    |    |     | ✓  |      |
| Test Builds          |                  |    |    |     | ✓  |      |

**TABLE 3.1-19, EXAMPLE SET OF STATE-OF-THE-ART CASE TOOLS FOR THE SOFTWARE DESIGN AND ANALYSIS PHASE**

| Tool Name     | Company Name | Function               | Input Formats                   | Output Formats     | Commercial / Research / DoD / IR&D | Released / Unreleased |
|---------------|--------------|------------------------|---------------------------------|--------------------|------------------------------------|-----------------------|
| Teamwork/SART | Cadre, Inc.  | Structured Analysis    | Cadre Prop. Graphical Languages | C, Ada, 2167A doc. | Commercial                         | Released              |
| Teamwork/Ada  | Cadre, Inc.  | Object-oriented design | Cadre Prop. Graphical Languages | C, Ada, 2167A doc. | Commercial                         | Released              |
| Teamwork/DSE  | Cadre, Inc.  | Syntax Editor          | Cadre Prop. Graphical Languages | C, Ada, 2167A doc. | Commercial                         | Released              |

**TABLE 3.1-20, DETAILED INFORMATION ON A SUBSET OF THE SOFTWARE DESIGN AND ANALYSIS TOOLS RESEARCHED**

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## 3.1.2.3.4 Hardware Design and Analysis

The main activities in hardware design and analysis are:

- 1) Simulation (S)
- 2) Logical Partitioning (L)
- 3) Design Capture (D) through schematic capture (Syn) and synthesis (SC)
- 4) Emulation (E)
- 5) Acceleration (A)
- 6) H/W Modeling (M)
- 7) Test (T)

Tables 3.1-21 and 3.1-22 represent a subset of the tools (both current state-of-the-art and advanced research) that address the hardware design and analysis activities. Table 3.1-23 gives details for each of the tools researched. Commercially-available tools under this design phase have been user-hardened. In many cases they are integrated into frameworks and should be an easy integration into the RASSP Design System.

Wright Laboratories currently has a program called MultiComponent Synthesis that has been awarded to University of Cincinnati, Michigan State and DASYS, Inc. Under this contract, advanced research and development is underway to develop high-level partitioning and synthesis techniques for MCMs. The ideas developed under this contract will be watched for the possible extension to partitioning and synthesis of modules and subsystems.

| Tools          | State-of-the-Art |   |   |     |    |   |   |   |
|----------------|------------------|---|---|-----|----|---|---|---|
|                | S                | L | D | Syn | SC | E | A | M |
| VHDL - 1076    | ✓                |   |   |     |    |   |   |   |
| VHDL - XL      | ✓                |   |   |     |    |   |   |   |
| RPM Emul. Sys. |                  |   |   |     |    | ✓ |   |   |
| IKOS           |                  |   |   |     |    |   | ✓ |   |
| Capfast        |                  |   | ✓ |     | ✓  |   |   |   |
| Synopsys       |                  |   | ✓ | ✓   |    |   |   |   |
| Spice          | ✓                |   | ✓ |     |    |   |   |   |
| LM Modelers    |                  |   |   |     |    |   |   | ✓ |

**TABLE 3.1-21, EXAMPLE SET OF STATE-OF-THE-ART CAE TOOLS FOR THE HARDWARE DESIGN AND ANALYSIS PHASE**

| Tools            | Advanced Research |   |   |     |    |   |   |   |
|------------------|-------------------|---|---|-----|----|---|---|---|
|                  | S                 | L | D | Syn | SC | E | A | M |
| DASYS, Inc.      |                   | ✓ |   | ✓   |    |   |   |   |
| U. of Cincinnati |                   | ✓ |   | ✓   |    |   | ✓ |   |
| Michigan St.     |                   | ✓ |   | ✓   |    |   |   |   |

**TABLE 3.1-22, EXAMPLE SET OF ADVANCED RESEARCH CAE TOOLS AND METHODS FOR THE HARDWARE DESIGN AND ANALYSIS PHASE**



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**TABLE 3.1-23, DETAILED INFORMATION ON THE HARDWARE DESIGN AND ANALYSIS TOOLS RESEARCHED**

| Tool Name                       | Company Name                | Function                            | Input Formats                                       | Output Formats                               | Commercial / Research / DoD / IR&D | Released / Unreleased |
|---------------------------------|-----------------------------|-------------------------------------|---|--|------------------------------------|-----------------------|
| Express VHDL                    | i-Logix, Inc.               | Reqs. Design & Analysis             | Statestate Proprietary Graphical Languages          | VHDL   | Commercial                         | Released              |
| VHDL-1076                       | Mentor Graphics             | Behavioral Simulation               | VHDL  | Simulation Reports                           | Commercial                         | Released              |
| VHDL-XL                         | Cadence                     | Behavioral Simulation               | VHDL  | Simulation Reports                           | Commercial                         | Released              |
| Spreadsheet                     | Vantage Systems Inc.        | Behavioral Simulation               | VHDL  | Simulation Reports                           | Commercial                         | Released              |
| VSS                             | Synopsys Inc.               | Behavioral Simulation               | VHDL  | Simulation Reports                           | Commercial                         | Released              |
| VHDL 2000                       | Racal Redac                 | Behavioral Simulation               | VHDL  | Simulation Reports                           | Commercial                         | Released              |
| Verilog                         | Cadence                     | Simulator                           | Verilog   | Simulation Reports                           | Commercial                         | Released              |
| MARS                            | PiE Inc.                    | Emulation                           | Interface with major ASIC vendors (Mentor, Cadence) | Simulation Reports                           | Commercial                         | Released              |
| RPM Emulation System            | QuickTurn Inc.              | Emulation                           | EDIF/ all major ASIC vendor formats                 | Simulation Reports                           | Commercial                         | Released              |
| XP                              | Zycad                       | Hardware accelerator                | All major ASIC vendor formats                       | Simulation Reports                           | Commercial                         | Released              |
| IKOS Accelerators               | IKOS                        | Hardware accelerator                | Interface to all major ASIC vendors                 | Simulation Reports                           | Commercial                         | Released              |
| LM-family of universal modelers | Logic Modeling Systems Inc. | Hardware modeler                    | Interface to all major ASIC vendors                 | Simulation Reports                           | Commercial                         | Released              |
| Design Architect                | Mentor Graphics             | Schematic capture for boards or ICs | Proprietary graphical language                      | EDIF/ proprietary link to other Mentor tools | Commercial                         | Released              |

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|                 |   |                              |   |   |            |          |
|-----------------|---|------------------------------|---|---|------------|----------|
| Composer        | Cadence                                 | Schematic capture for ICs    | Proprietary graphical language          | EDIF/<br>proprietary link to other Cadence tools  | Commercial | Released |
| Futurenet       | DATA I/O                                | Schematic capture for boards | Proprietary graphical language          | Simulation Reports                                | Commercial | Released |
| Capfast         | Phase Three Logic Inc.                  | Schematic capture for boards | EDIF;<br>Proprietary graphical language | EDIF  | Commercial | Released |
| Logic Assistant | Compass Design Automation               | Schematic capture for ICs    | Proprietary graphical language          | EDIF;<br>Proprietary links to other Compass tools | Commercial | Released |
| Motive          | Quad Design Technology                  | Timing Analysis              | Netlist & Component timing data         | Timing violation reports                          | Commercial | Released |
| Design Compiler | Synopsys Inc.                           | ASIC Synthesis               | Verilog;<br>VHDL                        | EDIF;<br>schematic for major ASIC vendors         | Commercial | Released |
| QuickPath       | Mentor Graphics                         | Static timing                | VHDL,<br>Mentor Languages               | Timing reports & diagrams                         | Commercial | Released |
| SilcSyn         | Racal Redac Design Systems              | ASIC Synthesis               | VHDL                                    | schematic for major ASIC vendors                  | Commercial | Released |
| Autologic       | Mentor Graphics                         | ASIC Synthesis               | VHDL                                    |   | Commercial | Released |
| SPICE           | Various companies                       | Analog Simulation            | Spice netlist                           | Simulation reports                                | Commercial | Released |
| Virtual ASIC    | Integrated Circuits Applications (INCA) | Emulation                    | Interface with major ASIC vendors       | Simulation reports                                | Commercial | Released |

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## 3.1.2.3.5 Physical Design and Analysis

The main activities in physical design and analysis are:

- 1) Place and Route (PR) of MCMs (M), Boards (B) and Custom devices (C)
- 2) Verification (V)

Table 3.1-24 represents a subset of the tools that address the physical design and analysis activities. Table 3.1-25 gives details for each of the tools researched. Commercially-available tools under this design phase have been user-hardened and should be an easy integration into the RASSP Design System.

### State-of-the-Art

| Tools         | PR | M | B | C | V |
|---------------|----|---|---|---|---|
| Visula        | ✓  |   | ✓ |   |   |
| Boardstation  | ✓  |   | ✓ |   |   |
| Gate Ensemble | ✓  |   |   | ✓ |   |
| Cell Compiler | ✓  |   |   | ✓ |   |
| Dracula       |    |   |   |   | ✓ |
| Checkmate     |    |   |   |   | ✓ |
| MCM Station   | ✓  | ✓ |   |   |   |

**TABLE 3.1-24, EXAMPLE SET OF STATE-OF-THE-ART CAE TOOLS FOR THE PHYSICAL DESIGN AND ANALYSIS PHASE**

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| Tool Name     | Company Name              | Function                                | Input Formats                        | Output Formats               | Commercial/ Research/ DoD / IR&D | Released/ Unreleased |
|---------------|---------------------------|---|--------------------------------------|------------------------------|----------------------------------|----------------------|
| Visula        | Racal Redac Inc.          | Board Place and Route                   | Proprietary Input format             | GDSII                        | Commercial                       | Released             |
| Board Station | Mentor Graphics           | Board Place and Route                   | Proprietary Input format, VHDL, EDIF | EDIF                         | Commercial                       | Released             |
| Allegro       | Cadence                   | Board Place and Route                   | Proprietary Input format, VHDL, EDIF | GDSII                        | Commercial                       | Released             |
| Gate Ensemble | Cadence                   | Gate Array Place and Route              | Proprietary Input format, EDIF       | GDSII; CIF                   | Commercial                       | Released             |
| Cell Ensemble | Cadence                   | Standard Cell Place and Route           | Proprietary Input format, EDIF       | GDSII; CIF                   | Commercial                       | Released             |
| Gate Compiler | Compass Design Automation | Gate Array Place and Route              | Proprietary Input format, EDIF       | CIF                          | Commercial                       | Released             |
| Cell Compiler | Compass Design Automation | Standard Cell Place and Route           | Proprietary Input format, EDIF       | CIF                          | Commercial                       | Released             |
| DRACULA       | Cadence                   | Design verification<br>ERC, DRC,<br>LVS | GDSII                                | various verification reports | Commercial                       | Released             |
| Checkmate     | Mentor Graphics           | Design verification<br>ERC, DRC,<br>LVS | GDSII                                | various verification reports | Commercial                       | Released             |

**TABLE 3.1-25, DETAILED INFORMATION ON THE PHYSICAL DESIGN AND ANALYSIS TOOLS RESEARCHED**

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## 3.1.3 CALS Interface

The DoD has become very concerned with the completeness of technical data packages, the receipt of these packages in a paper format, and the availability of the data. As a result, the CALS initiative was formulated to allow the electronic capture and delivery of the technical data package in a standard format. In addition, the DOD would like access to the technical data during the development phase of a program, as defined in MIL-C-CITIS (Contractor Integrated Technical Information Service), rather than only at the program's completion. As a result of these requirements, there exists accepted standards for the delivery of graphical data, such as schematics and board layouts in MIL-M-28001A compliant standards, the delivery of documentation in SGML format, and the delivery of VHDL models. One of the difficulties with the current standards is that the schematic and board layout data is generally delivered as a raster format, rather than IGES. The principal reason for this is the problem with *CAD systems being able to read each others IGES*. The intent is that the CALS deliverable data be in a format which will allow interchange of the data with other CAD systems and support the acquisition process. To achieve this objective, improvements to the delivery standards such as EDIF 2.0 for schematics, for PCB view and for test vectors, which are due to be released in 1993, and STEP for the product data are required. Under the RASSP program, it is imperative that the technical information package be automatically derived from the CAD framework, and support the current, as well as the emerging standards, for CALS compliance.

In order to accomplish the above goals, RASSP should maintain contact with the CALS Industry Working Group (IWG) to support the requirements for DOD access to the design data, as well as involvement in the PAP-E/STEP program to assure that the CAD framework supports the emerging standards. Work should also address the generation of SGML compliant data from the electronic notebook application, as

well as other required textual deliverable elements in the technical data package.

A major benefit that the RASSP program can provide is a test bed for the emerging CALS standards. A major improvement in the current CFI standards development activity is the implementation of the standard in a pilot program after the draft has been issued, and prior to voting on the standard. This methodology allows for the exercise of the standard and the resolution of problems prior to the adoption of the standard. In this way, the release standards are more robust and complete.

## 3.1.4 Design System Issues

Design standards, such as VHDL, provide good candidates for the design and documentation description language for use in the RASSP model year concept. VHDL is a technology and process independent language used in design to define and document an electronic system. However, due to the flexibility of the language, standards must be refined before the RASSP system can maximize the effectiveness of VHDL.

The VHDL standards committee has not completed the definition of the VHDL standard for 1992. As with any IEEE standard, IEEE-1076 must be reaffirmed at least every 5 years. The VHDL Analysis and Standardization Group (VASG) has reviewed more than 250 change requests submitted by users of VHDL. VASG decided not to radically change the language during this restandardization period due to the acceptance VHDL has recently gained by the commercial vendors. The changes to the language are minimal and address the semantics of the language and additional language constructs. The reaffirmation of IEEE 1076 is currently in the balloting phase.

A number of important areas were not included in the 1992 restandardization. The VASG elected to have these areas studied further. Table 3.1-26 represents the standards activities currently being addressed that have an impact on the RASSP

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program. These standards are currently incomplete. The RASSP program must monitor each of these standards areas closely and influence the direction of the standard by being a member of the committee to ensure the RASSP needs are met. Those standards area that have a direct impact on RASSP are discussed further in the following sections.

Detailed timing is critical to the successful development of a high performance system. A VHDL model must be developed to support minimum, typical, and maximum timing and support derating factors such as temperature, process, and voltage variations. Currently vendors are supporting back annotation outside the VHDL model through their simulator interface since it is extremely difficult to do this through the model. A standard way to represent timing and a standard way to back annotate to a VHDL model is very important to the RASSP program. A study group for VHDL timing and back annotation has been set up by the IEEE Computer Society Design Automation Standards Society (DASS). The purpose of this group is to develop standard methods for representing timing related information for use in VHDL models, and standard modeling practices for

making use of this information in a consistent, simulator independent manner. The RASSP program must influence this group to make sure its needs are addressed.

A standard package for synthesis is required by the RASSP program. The synthesis tools in use today all accept only a subset of the VHDL language for synthesis. Each vendor happens to accept a different subset. Additionally, the style that is used in writing the VHDL will produce different results depending on the synthesis tool used. The RASSP concept calls for reusable models that can be synthesized to generate a part on demand by a qualified line. What is required is a defined subset for synthesis. The VHDL Synthesis Package Study Group is an IEEE committee working on a standard package to make synthesis from VHDL uniform across vendors. The RASSP program must follow this effort and make sure the package is defined and influence the synthesis vendors to adopt the package.

VHDL supports a basic set of arithmetic functions for integer and real types. The algorithmic development of systems requires higher level mathematical functions. The VHDL Math Package Study group is studying the best

| Standards Area             | IEEE Computer Society DASS  |
|----------------------------|---|
| Timing and Back Annotation | VHDL Timing Study Group   |
| Standard Packages          | VHDL Math Package Study Group<br>VHDL Synthesis Package Study Group |
| Analog VHDL                | VHDL Analog Extensions Study Group                                  |
| Modeling Guidelines        | VHDL Modeling Practices, PAR 1164                                   |
| Information Modeling       | Working group on Information Modeling, PAR 1078                     |
| Interoperability           | VHDL - EDIF Interoperability Group, PAR 1165                        |
| Intermediate Forms         | VHDL Intermediate Form Analysis and Standardization Group, PAR 1163 |
| System Design              | Working Group on System Design Languages                            |
| Test                       | DASS/SCC20 Test Standards, PAR 1029.x, TASG                         |

**TABLE 3.1.-26, VHDL STANDARDS STUDY AREAS**

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way to implement a standard math package in VHDL.

Analog modeling in VHDL can be accomplished since VHDL is such a heavily typed language, however it is very cumbersome for the developer. The VHDL Analog Extensions Study group is studying the best mechanisms to implement greater analog modeling capability into VHDL.

The following areas are important to the RASSP Design System but are currently not being addressed under the VHDL standards organizations. The RASSP program should influence these efforts, however, it is unlikely that the time frame for developing and gaining agreement on these standards will coincide with the RASSP Design System need.

Signal processors contain both analog and digital elements. In order to truly model the system in a hardware description language the language must support both analog and digital components and the interaction between the devices. In addition, a simulation environment must be available to accurately and correctly simulate the mixed mode model at various levels of abstraction. Mixed mode simulation must address issues of synchronization, signal representation and mapping, and partitioning.

Object-oriented VHDL is required when a VHDL system model is developed to model both hardware and software in VHDL. As more software development activities are moving towards object-oriented languages, VHDL will be most effective if it can map directly into the software object-oriented constructs.

Library standards are currently being developed for logic synthesis and math functions. CFI, under the CIR subcommittee, is looking at the standardization of component libraries which should set the stage for the development of standards for modeling components in VHDL. Standards for other library models, such as standards for performance models, have not been addressed under any standards group. The

University of Virginia has done extensive research into the development of performance model primitives. Certainly, UVA's work should be a starting point for the standardization effort.

VHDL is gaining acceptance in the commercial marketplace. Many products are available that either input or output VHDL. The problem is many tools accept or generate only a subset of the language. In the seamless RASSP Design System it is essential that VHDL be used by the many tools in the system without manual intervention to resolve unsupported language constraints. VHDL automatically generated by these tools is not easily read.

The CAD Framework Initiative (CFI) compliance standards have not been fully defined. Major CAD vendors such as Mentor Graphics and Cadence have developed and are marketing their own frameworks. Resolution requires compromise.

The abstract nature of model representations complicates the translation and verification of models passed between CAE tools. CAE tools use models that support the function provided by that tool. For example, there are unique models for performance, cost, reliability, testability, and functionality. There is no means to verify that the models represent the same system. The accuracy and validation of these abstract models is critical to the success of the RASSP design system.

The following list identifies functional areas in the RASSP design system where commercially available CAE tools are not available or are incomplete and could be potential RASSP investments. These tools should use a VHDL model as input.

1. Hardware / Software codesign tool
2. System Functional partitioning/ High-level synthesis tool
3. System-level manufacturing advisor
4. System-level logistics advisor
5. System-level packaging compiler

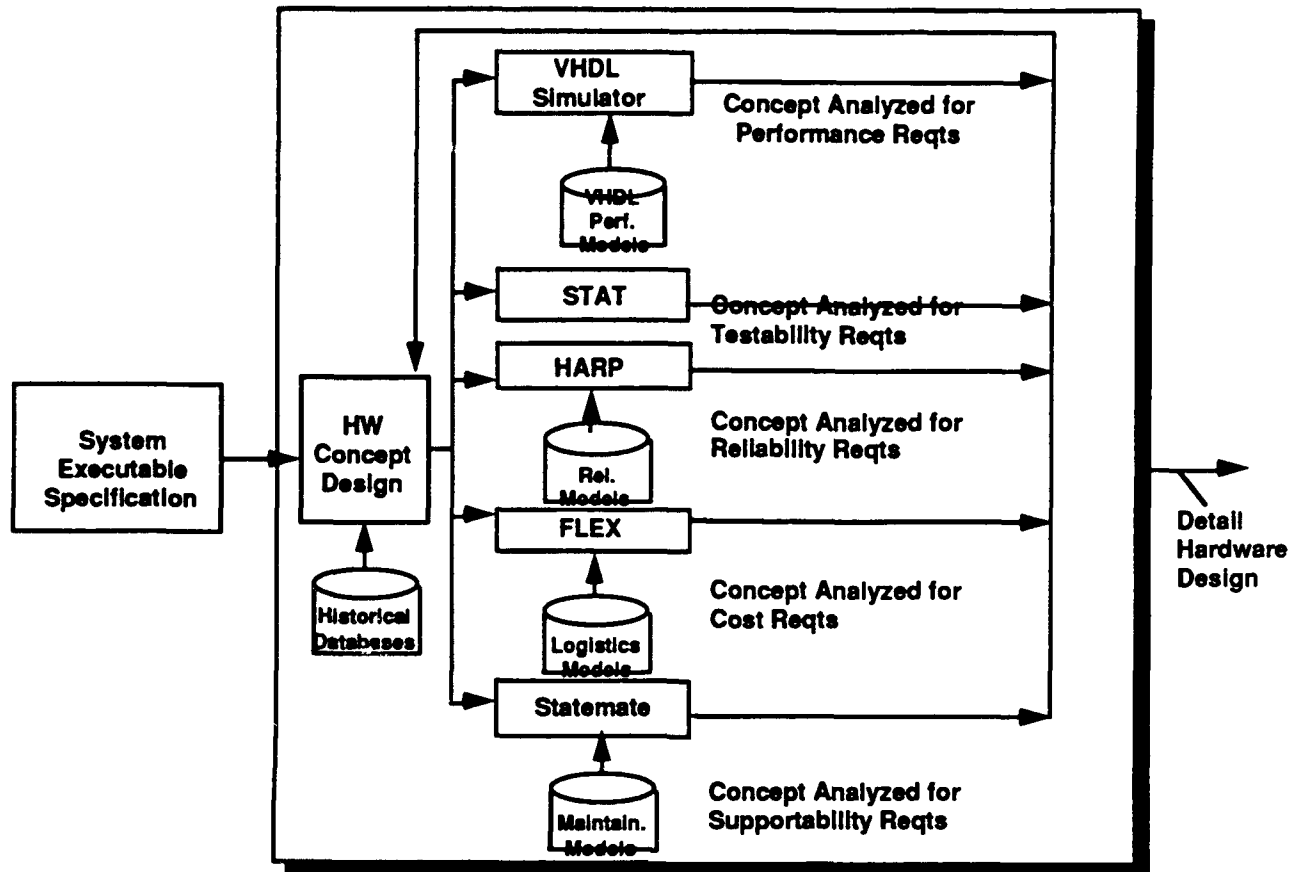


Figure 3.1-27, Prototype System Design Environment

6. System-Level Testability Advisor/ BIT Insertion

7. Behavioral mixed-mode simulators

### 3.1.5 Raytheon Related Efforts

Raytheon has been active in the development of integrated design environments. A few years ago, Raytheon implemented a prototype "System Design Environment" shown in Figure 3.1-27. The specification of the system was captured using i-Logix's Statemate product. The Statemate model was converted to a VHDL behavioral model for further analysis. The results of this activity were presented at the VHDL International User's Meeting in two parts: 1) "VHDL - Transition from System to Detailed Design" presented in the Spring of '90, 2) "The Use of VHDL from System To Chip" presented in the Fall of '90.

Raytheon also demonstrated a seamless VHDL based design environment for the design of

digital sub-systems. In this effort, Raytheon developed a model of a sub-system using the i-Logix Express V-HDL product, and synthesized the model into a gate array. The model was also synthesized into an FPGA system. Table 3.1-28 lists the tools used or evaluated as part of this demonstration. Results of this activity were presented at the VHDL International User's Meeting. The paper was entitled "From Statecharts to Hardware FPGA and ASIC Synthesis" and was presented in the Spring of '92.

A more recent system modeling activity performed by Raytheon was the development and application of a system re-engineering methodology to a sub-system of the PATRIOT radar. Figure 3.1-29 illustrates the methodology. Under this methodology, an executable Statemate model of the sub-system was developed. The model was validated against the current system



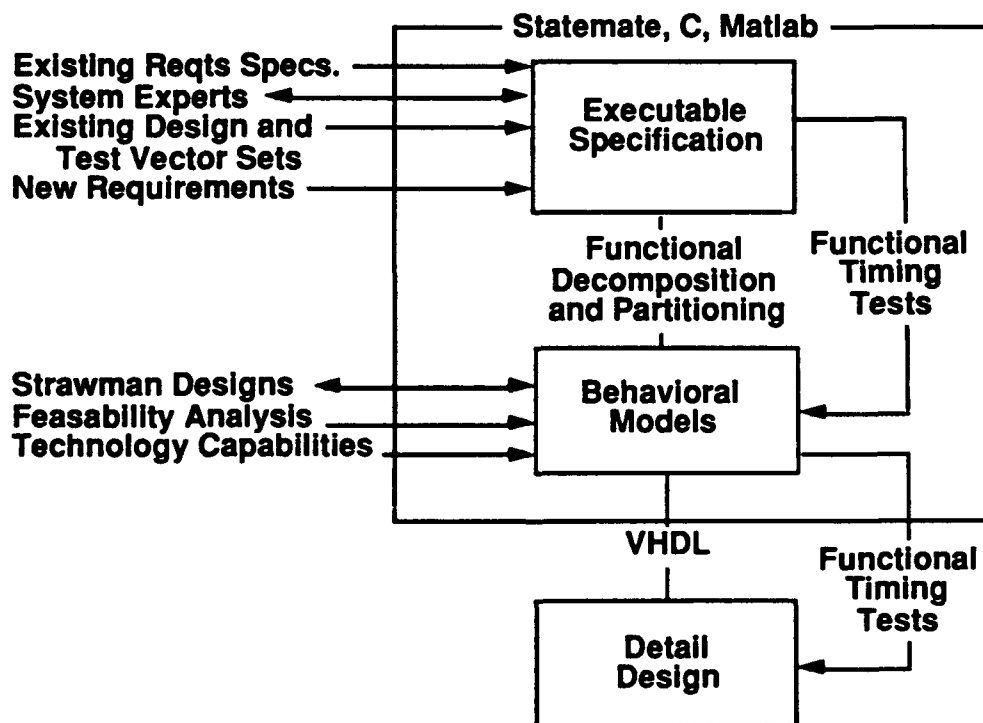
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| Vendor   | Tool             | Function                |
|----------|------------------|-------------------------|
| i-Logix  | Express/VHDL     | System Modeling         |
| SES      | Workbench        | Performance Modeling    |
| Mentor   | Silicon Compiler | Synthesis               |
| Vantage  | Spreadsheet      | Simulation              |
| IKOS     |                  | Simulation acceleration |
| SYNOPTIS | Design Compiler  | Gate level synthesis    |
| XILINX   |                  | FPGA synthesis          |

**TABLE 3.1-28, TOOLS USED AND EVALUATED FOR SEAMLESS DIGITAL DESIGN ENVIRONMENT**

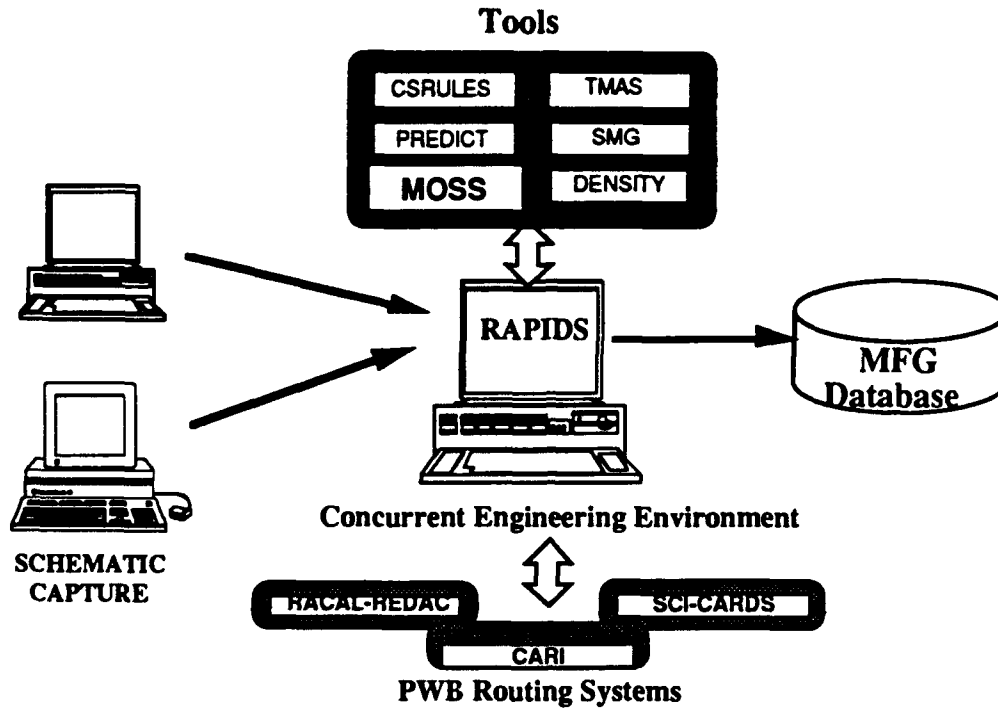
test data. In this way, the completeness and accuracy of the model was verified. As seen in Figure 3.1-29, many sources of information were utilized to develop the model. Information was not limited to functionality but also included performance data. This model now serves as a complete description of the system and can be used to develop an implementation as well as providing the verification data to insure the re-engineered system matches the original system.

Another Raytheon program aimed at integrating tools for concurrent engineering was the RAPIDS project, shown in Figure 3.1-30. This system integrated schematic capture, physical layout, manufacturability analysis, thermal analysis, and created an electronic database which was transferred to Raytheon's manufacturing facilities for fabrication. This system is currently used by a number of Raytheon engineering sites today.



**Figure 3.1-29, System Re-Engineering Methodology**

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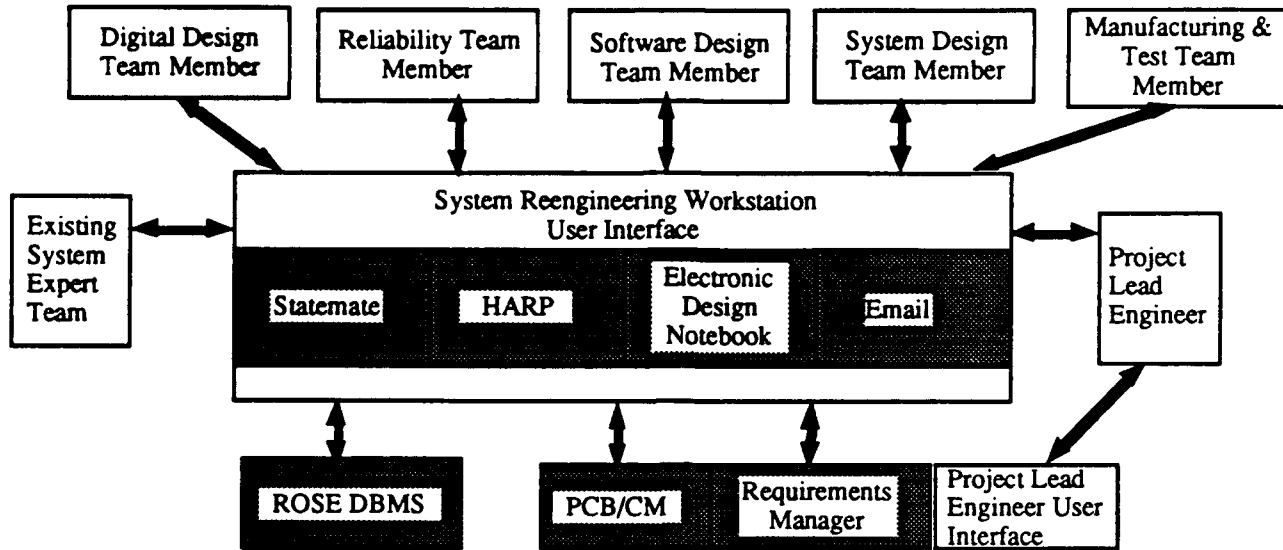


*Figure 3.1-30, RAPIDS Concurrent Engineering for PWBs*

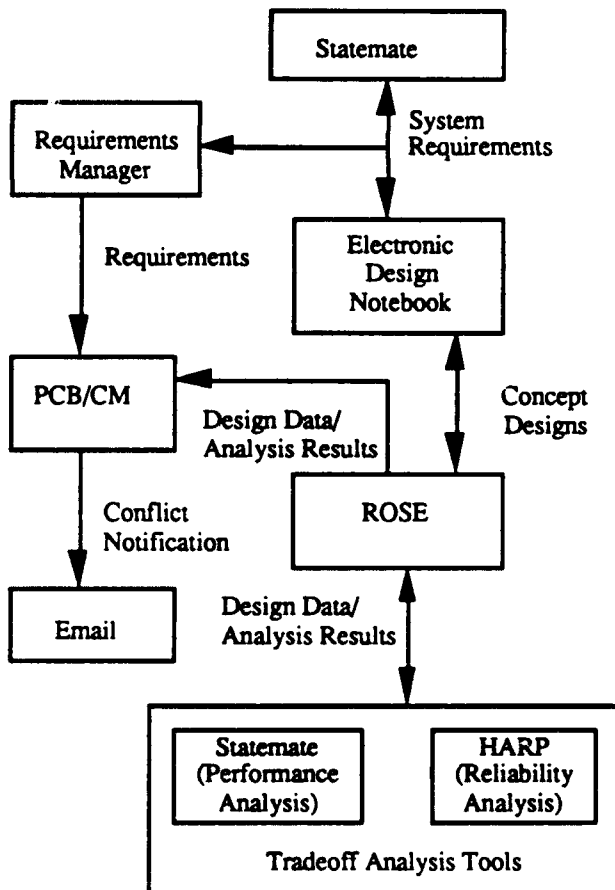
Raytheon recently proposed a "System Re-engineering System" under DICE V. This system is currently under review by DARPA. The proposed integrated tool set (shown in Figure 3.1-31) for concurrent re-engineering will improve a designer's ability to capture design intent and model it to verify adherence to current test beds prior to re-designing the system. The objective of this approach is to ensure that the

requirement of the system being re-designed are complete and model the existing system. The system will include the following DICE tools: Requirements Manager (RM), Electronic Design Notebook (EDN), Project Coordination Board/Communication Manager (PCB/CM), Statemate from i-Logix, and HARP for fault tolerant reliability analysis. Figure 3.1-32 illustrates the system information flow.

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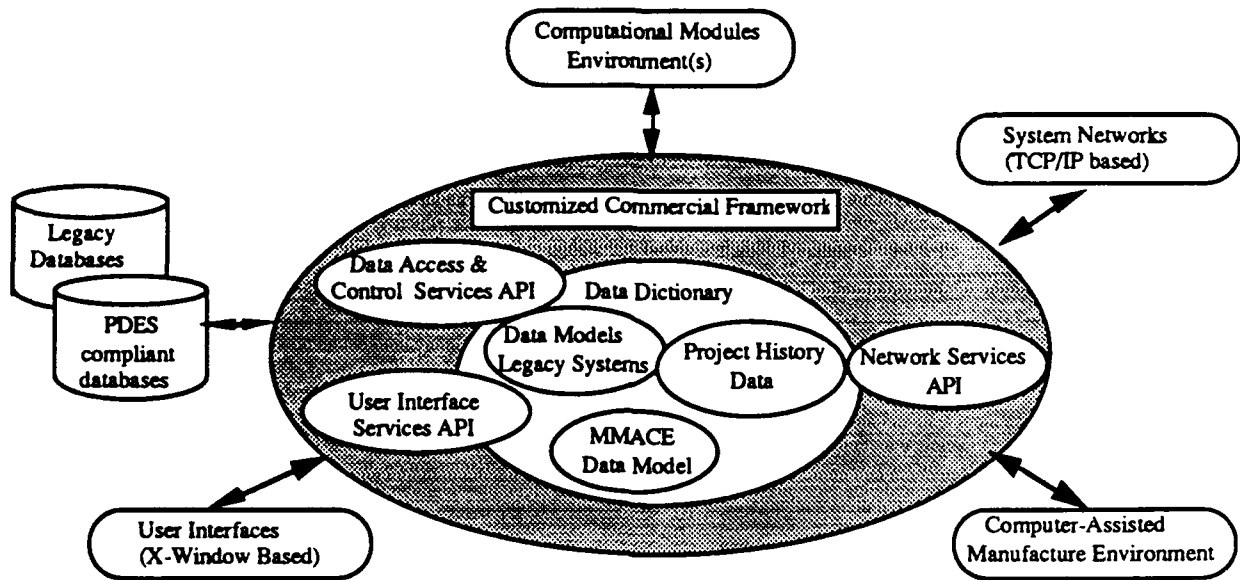
**Figure 3.1-31, System Re-engineering Workstation Environment**



**Figure 3.1-32, System Re-engineering Workstation Information Flow**

Raytheon has won one of the DoD Tri-Service MMACE programs to develop a computational framework for the design and manufacture of microwave and millimeter-wave tubes. The conceptual model of the MMACE framework is depicted in Figure 3.1-33. This program is similar to the RASSP program in that one of its goals is to develop an integrated concurrent design environment.

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**Figure 3.1-33, High Level Overview of the MMACE System**

The MIMIC program is another example where Raytheon has been involved in the design and development of a design environment. As a MIMIC PHASE 0, PHASE I, and PHASE II winner, Raytheon has been involved in the development of an integrated design environment which included CAD tools for schematic capture,

simulation, physical layout, transition to manufacturing. These tools were transitioned to Cadence and Compact Software for commercialization. Under the MIMIC funds, the design and implementation of a data base environment to capture process and test data for improve modeling and analysis was also implemented.

| VENDOR / UNIVERSITIES | DESCRIPTION OF WORKING RELATIONSHIP  |
|-----------------------|--|
| i-Logix, Inc.         | Developed algorithms and requirements to automatically generate behavioral and RTL VHDL from requirements.   |
| Mentor                | Developed requirements for Mentor's probabilistic fault grading environment and Design Management System. Raytheon has held two presidential and vice-presidential offices in the International Mentor User's Group. |
| CrossCheck            | First DoD contractor to adopt the CrossCheck methodology and build working silicon. Integrated CrossCheck tools with Mentor and Cadence tools.   |
| CAE Vendor            | Raytheon is a common beta test site for several commercially available CAE tools, e.g. Mentor, Cadence.  |
| U. Cal. at Berkeley   | Enhancement of Berkeley's SPICE algorithms.  |
| Compact Software      | Transitioned MIMIC CAD work for commercialization  |

**Table 3.1-34, Examples of Raytheon/Vendor/University Working Relationships**

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The above examples demonstrate Raytheon capabilities and understanding of the requirements for system design tools, and not just point solutions. In addition to the above efforts, Raytheon has been involved in the development of unique CAD tools, such as Express V-HDL, with i-Logix. Raytheon co-developed this capability with i-Logix which was commercialized and marketed by i-Logix. After this initial successful effort, further work was done with i-Logix to allow for the generation of RTL level VHDL which could be synthesized by Synopsys' Design Compiler.

Over the years, Raytheon has had many working relationships with vendors and

universities. Table 3.1-34 lists some of these relationships. The experience gained from these relationships will help ensure successful working relationships with RASSP, and with other appropriate government initiatives.

Raytheon is a member of a number of standards organizations such as IEEE, CFI, VHDL, the CALS IWG, the PDES Application Protocol-Electronics IRB and the IPO/ISO. In addition to these activities, Raytheon engineers have actively participated in the Mentor User Group, and the VHDL User Group and workshops, as well as attending and contributing to a number of DARPA sponsored workshops.

**3.2 Interoperability Considerations**

*Interoperability between current and next-generation products expedites MODEL YEAR development programs. With this, upgrades can leverage a significant amount of hardware and software investment from previous versions thereby reducing development cost and time.*

**3.2.1 Hardware Interoperability**

Electrical and mechanical interface interoperability between an existing and an upgraded subsystem provides a path for performance improvement for upgrades that only affect portions of a signal processor. The ability to upgrade individual sections of a signal processor provides an environment suitable for incremental MODEL YEAR improvements. Figure 3.2-1 illustrates a signal processor broken into three interoperable sections.

**3.2.1.1 Current Approaches To Interoperability**

Currently, most application specific signal processors attain interoperability at the module level by making use of standard system busses and rack-and-stack backplanes. However, within the signal processor, subsections often use nonstandard or custom interfaces. The

digital signal processor interfaces tightly to the A/D front-end in order to maximize performance. Performance objectives are met with this approach, but subsequent product upgrades are usually forced to redesign the entire signal processor because existing interfaces are hardwired and not scalable.

Upgrades that effect the entire signal processor are commonplace today because standard system busses such as VME, MultiBus II, or even FutureBus+ do not offer a high-speed data transfer network that satisfies the high-bandwidth needs of signal processors. Initial RASSP processors will require transfer rates in the range of 100 to 500 MegaHertz. Current system busses have too many layers of protocol and too much latency. As a result, connecting high-speed A/D and digital front-ends to standard system busses for the sake of attaining interoperability does not provide a solution. The solution must come from either a to-be-determined standard for high-speed data transfers or a configurable, scalable interface that can accommodate the requirements of next generation upgrades. Figure 3.2-2 illustrates the undesirable and the preferred use of a system bus for interoperability purposes.

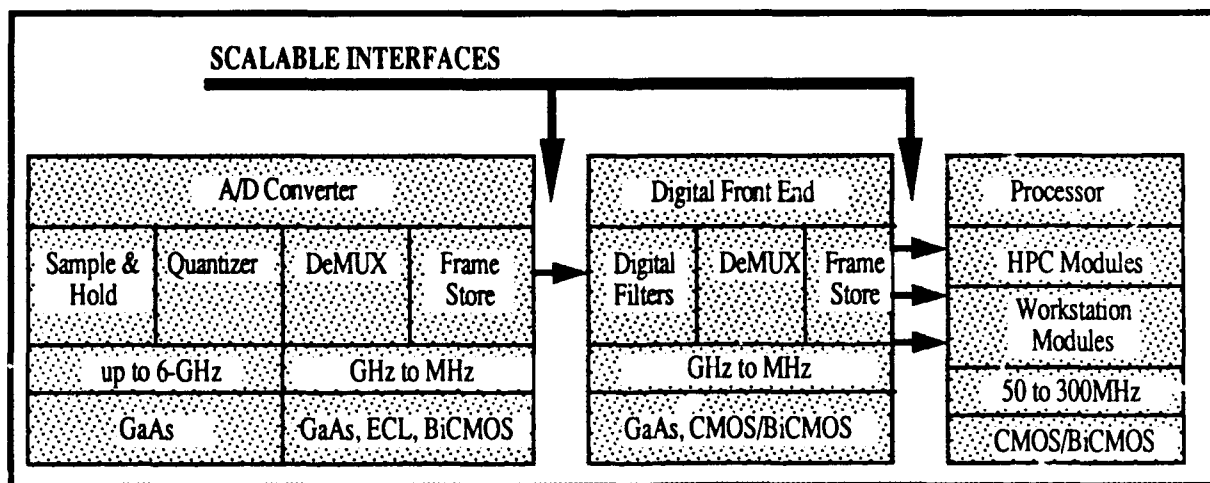
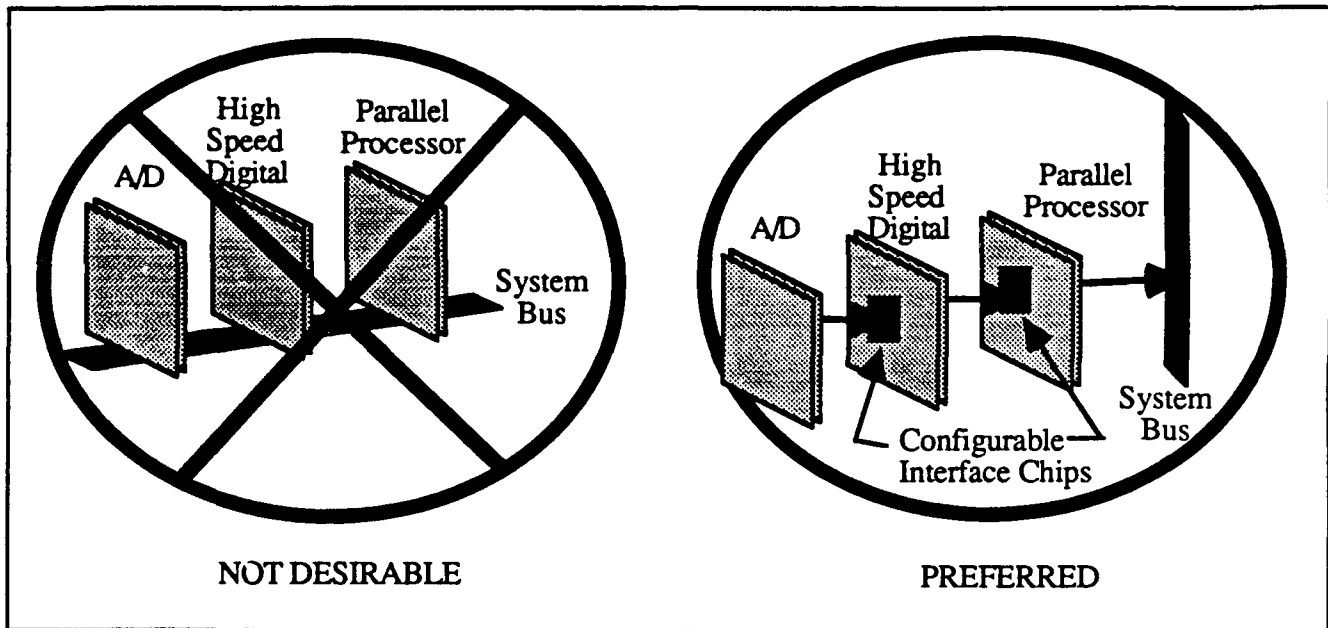


Figure 3.2-1, Application Specific Signal Processor With Interoperable Sections

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*Figure 3.2-2, System Bus Use For Interoperability*

### 3.2.1.2 Adopting A Standard For High-Speed Data Transfers

An accepted industry standard for high-speed data transfers will help to foster the development of interoperable sections within signal processors. This will facilitate independent upgrade of individual subsections thereby simplifying incremental MODEL YEAR upgr.des. Currently, no widely adopted

standard exists in this area. However, several de facto standards as well as up-and-coming interface products show some promise. Table 3.2-3 highlights some standards and products that may have future, if not immediate, bearing on interoperability.

| Name                              | Application Area  | Speed  | Approval   | Vendor Support                                |
|-----------------------------------|---|--|--|---|
| Scalable Coherent Interface (SCI) | Very broad: Packet-based bus protocol operates over unidirectional point-to-point links | 1 GByte/Sec @ 16-bits<br>1 GBit/Sec @ bit serial | Won IEEE Standardization Approval (IEEE 1596-1992) | Dolphin SCI Technology: Chip samples by Q4'92 |
| HP-IBM Standard Fiber Module      | Desktop, Medical, Imaging, and Scientific Visualization                                 | 133, 266, 531, and 1062 Mbit/Sec                 | --   | HP-IBM collaboration: Chip samples by Q2'92   |
| MAXBus                            | Video   | 40MHz  | de facto   | Datacube, Inc.                                |

**TABLE 3.2-3, STANDARDS AND PRODUCTS AFFECTING INTEROPERABILITY**

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## 3.2.1.3 Flexible Interfaces For Interoperability

In the absence of widely adopted high-speed data transfer standards, use of configurable high-speed chips can provide sufficient interface flexibility to accommodate adjoining sections that have been upgraded in a MODEL YEAR scenario.

When planning an upgrade, the design team must consider interface problems resulting from changes in frequency, word length, and duty cycle. In addition, any new use of a technology that is not indigenous to the existing system creates interface problems from component level on up. Table 3.2-4 highlights typical interface

characteristics thereby accommodating new or upgraded adjoining subsystems. This built-in configurability coupled with on-chip Phase-Lock-Loop (PLL) circuitry and high-speed memory provides enough flexibility to handle changes in frequency, channel number, word width, and duty cycle. The on-chip PLL allows for interface clock frequency increases provided that the frequency does not exceed the limits of the chip's implementation technology. On-chip configuration registers, accessible by the IEEE 1149.1 port, allow for many arrangements between channels, word width combinations, and duty cycles by controlling the organization of the on-chip memory. When subsystem upgrades necessitate a change in interface technology,

| Subsection Upgrade         | Interface Frequency | Interface Channels and Word Width                  | Sampling Duty Cycle | Implementation Technology     |
|----------------------------|---------------------|--|---------------------|-------------------------------|
| A/D converter              | Increases           | Both Increase                                      | --                  | GaAs                          |
| High-Speed Digital         | Increases           | Both Increase                                      | Increases           | CMOS, ECL or some combination |
| High-Performance Processor | Increases           | May increase or decrease depending on architecture | Variable            | CMOS                          |

**TABLE 3.2-4, INTERFACE IMPLICATIONS FOR SUBSECTION UPGRADES**

implications for signal processor subsection upgrades.

Configurable high-speed chips can accommodate many of the interface changes resulting from MODEL YEAR upgrades. The rightmost diagram of Figure 3.2-2 illustrates three subsystems connected by configurable interface chips. These chips have an IEEE 1149.1 test access port that can be used to change operational

designers can use high level language models to synthesize a new implementation in the desired technology. In the time frame of the first RASSP processor (1995), chips will have I/O cells compatible with CMOS, ECL, and possibly optical interfaces. Figure 3.2-5 illustrates a configurable interface chip capable of accommodating some of the interface changes listed in Table 3.2-4.



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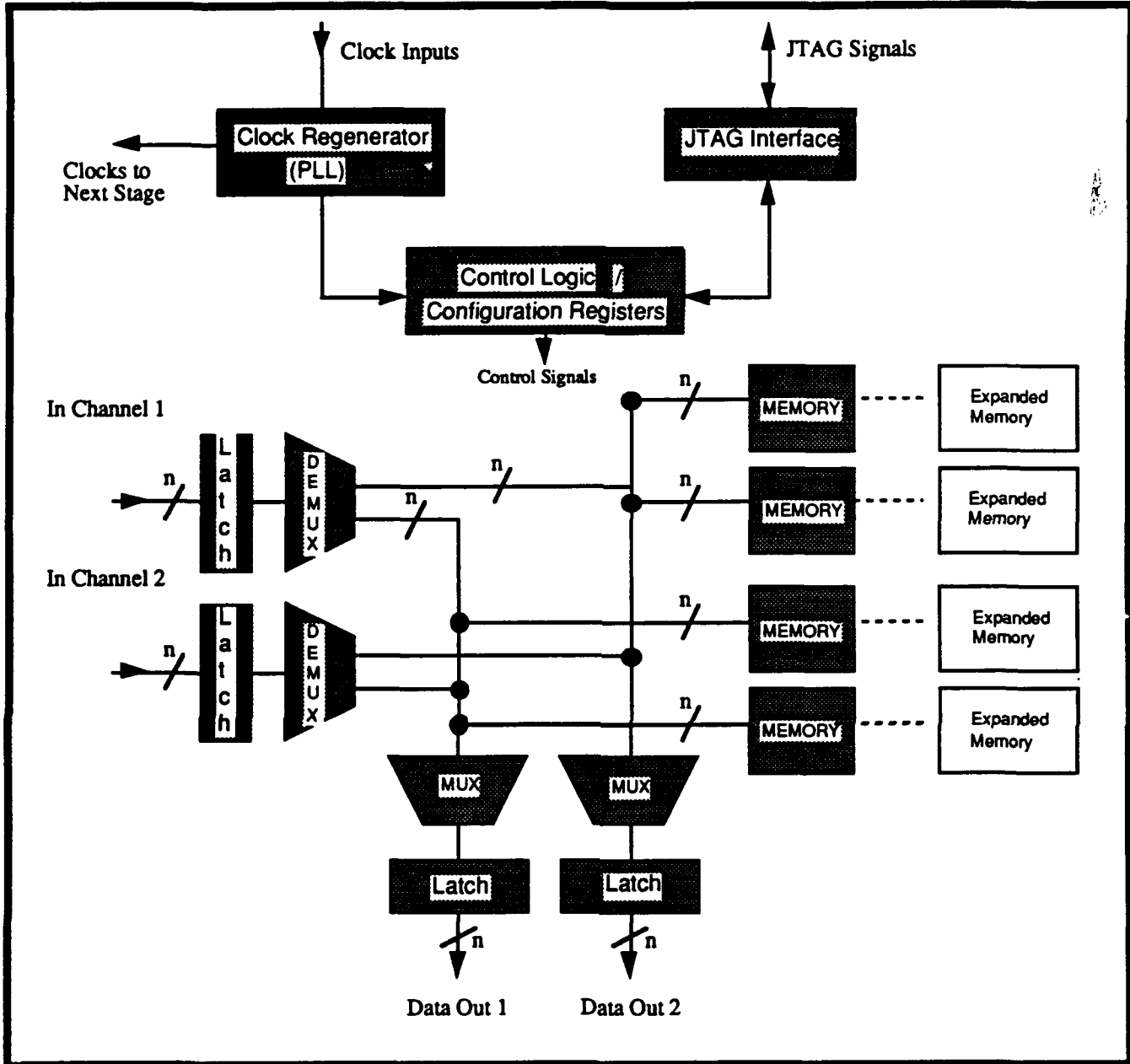


Figure 3.2-5, Configurable Interface Chip

### 3.2.1.4 Interoperability Trade Offs

System designers have much more flexibility with a system that exclusively employs standard interfaces and is functionally partitioned at well defined boundaries. However, some signal processors do not lend themselves to such an ideal. For example, high-performance signal processors usually require very tight coupling

between key subsystems. Systems constrained by very tight mechanical constraints have similar circumstances. Often, this tight coupling involves unique mechanical and electrical connections that are optimized for performance. In many cases, technology translation may be required to maintain standard interfaces. The trade-off is whether to sacrifice performance (and possibly increase life cycle costs) in order to

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maintain interoperability, or to attain performance at the expense of interoperability. It makes sense to depart from a strict policy of maintaining intrasubsection interoperability for signal processors that have very tight package constraints or ultra-high performance objectives. One approach to managing this departure is to consider interoperability in the simulation domain. In this context, upgrades can be functionally interoperable at levels other than traditional interfaces. If all else fails, a complete redesign is always an option, and perhaps in some cases, may be the best approach with these circumstances.

### 3.2.1.5 Known Interoperability Problems And Considerations

MODEL YEAR upgrades will make use of new technologies that have voltage and packaging requirements that existing systems cannot meet. To avoid this situation, RASSP processors must be designed-for-upgrade. Packaging, power supplies, and distribution schemes must be adequate for current and next generation upgrades. The design team must perform a technology look-ahead to ascertain the needs of the next generation upgrade. With this, designers can build enough provision into the current system to prepare for the next generation upgrade. For example, a system being built today should consider the requirements of integrating high-speed optoelectronic components. The Optoelectronic Technology Consortium (OETC) has plans to develop components capable of transmitting data at 16-Gbits/second. The application area being targeted is backplanes, and chips are due for sampling in 1995. Provisions included in an existing system facilitates rapid insertion of these up-and-coming devices.

Maintaining intrasubsystem interoperability by strict use of standard interfaces has life cycle cost and logistics implications. Maintaining standard interfaces may require additional special purpose components that are difficult to procure. For example, components may only be available in

commercial or industrial grades thereby creating a logistical problem of specifying, inspecting, and procuring military versions. This will tend to increase the cost of development and production. Ultimately, the solution to this problem rests with a common specification that is established for both military and commercial components. Only then, will commercial components, which largely adhere to industry standards, be completely accessible for use in military systems. The RASSP contractors involved with Implementation Phase can effectively influence working groups chartered with establishing common specifications, standards, and even products.

### 3.2.2 Software Interoperability

Raytheon has developed and upgraded many signal processing systems with embedded real-time software. Often, software interoperability is being maintained through subsystem upgrades by increasing the clock frequency while keeping the same hardware architecture. This approach minimally effects the software and results in minimum risk. While this approach is convenient, products do not attain peak capabilities since new architectures offer paths to higher levels of performance beyond what clock frequency increases can provide.

As with hardware, software interoperability is a tradeoff between generality and performance. To achieve maximum performance, domain specific software must exploit unique hardware features which, in turn, creates a potential interoperability problem for the next generation subsystem upgrade. Commercial DSP processors provide a software compatibility path between product generations; however, in order to attain the maximum performance, engineers usually have to modify software, particularly software written in machine language.

Attaining software interoperability between successive upgrades results in reduced development costs, lower risk, and shorter development time. Ideally, software interoperability can exist within upgrades of

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domain-specific embedded software, and between upgraded and existing subsystems.

Ada compilers are available for commercial DSP chips. Ada has the advantage of being the most portable programming language available, because of the rigid validation procedure required of vendors. This argues for the use of Ada as the standard language for software interoperability among processors.

A gating factor to the use of Ada in MODEL YEAR upgrades is the time delay for vendors to produce validated Ada compilers. In the evolving Ada business model, compiler vendors are now forming strategic alliances with chip vendors, sharing technologies, risk, and royalties. Such intimate knowledge of the processor architecture would argue for a reduced time to market. However, Raytheon's experience indicates that compiler upgrades from one chip type to another (MC68020 to MC68030, for example) take 6-9 months, while the development of an Ada compiler for a completely new architecture takes 1 1/2 to 2 years.

In addition to compiler production delays, vendors use incremental releases each with increasing optimization capability. Initial releases have relatively unintelligent code generators. With subsequent releases, vendors add more sophisticated optimization capabilities to the compilers. Raytheon's experience is that it requires about 3 releases of a compiler before it is mature enough to be used for high-speed, real-time applications

New concurrent engineering approaches is one possible solution for simultaneously developing new chip architectures and compilers. Tools enabling early, high level architecture descriptions coupled to compiler back ends offer some hope of decreasing the lead time for compiler availability.

### 3.2.2.1 Parallel Software

Increasingly, use of parallel processors in signal processing systems is becoming the norm. Yet,

software poses a fundamental obstacle to exploiting its full potential. The following paragraphs list the software problems associated with this situation.

Sequential software will not run efficiently on parallel architectures. Engineers must often reprogram existing software. This includes converting serial code to a parallel and/or distributed form in order to take advantage of new machine architectures. This is labor intensive and inhibits reuse of source code. As a result, software productivity diminishes.

Programming parallel architectures is difficult for most software engineers. Designing and programming for parallel architectures is distinctly different from traditional programming for sequential machines. Parallel programming requires a different mind set. Training is nontrivial; it takes six months or more for a programmer to become effective in parallel programming.

Current tools do not work well with parallel architectures. Execution analyzers, test case generators and other correctness checkers and test aids generally do not address the non determinism introduced by interacting parallel processes. Non intrusive test aids are essential for successful parallel software development projects.

Few software tools exist for new parallel architectures. Engineers have a difficult time updating off-the-shelf complex tools. Similarly, tools for software reengineering have the same problem.

A wide variety of distinctly different architectures and machine languages exist. MODEL YEAR upgrades will inevitably result in different architectures from year to year. This movement can result in a dramatic change in software tools' requirements.

Despite parallel programming obstacles, several approaches are available to alleviate some of these problems.

Automatic translation tools can convert sequential

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programs written in high level languages to a parallel form. Program analyzers can parse sequential source, identify parallelism, and attempt to rearrange or rewrite the program for a particular multiprocessor. Most of these conversions require some human intervention to achieve efficient execution. However, this is a first step in attaining interoperability between serial and parallel architectures.

Nearly all developers of parallel machines offer extensive libraries of common mathematical functions that execute efficiently. Parallel machine assembly or high level languages make subroutine calls to this library. This is a primary aid to application programmers. The pitfall here is that routines may contain bugs, and usually are not validated. Table 3.2-6 lists the characteristics of several parallel processor, vendor supplied libraries.

| Vendor                     | Library Characteristics      |
|----------------------------|------------------------------|
| Thinking Machines          | Math, Signal Proc. Functions |
| Active Memory Technologies | Math, Signal Proc. Functions |
| WaveTracer                 | Math, Signal Proc. Functions |
| MassPar                    | Math, Signal Proc. Functions |

**TABLE 3.2-6, LIBRARIES FOR PARALLEL ARCHITECTURES**

Programmers can append special constructs to standard languages that designate areas of code for conversion to parallel form. A compiler or high level language translator performs the conversion. The problem of programming for parallel operations remains, but programmers retain their basic programming skills by keeping with a familiar language.

New Languages written expressly for parallel programming offer the potential for efficient implementation and could ultimately produce a standard language.

Regardless of the level of success achieved, none of the aforementioned measures is satisfactory for embedded real-time software development for MODEL YEAR programs. The solution for the embedded computer software community will be implementation of the MIL-STD-1815 (Ada) standard for parallel processing architectures. Ada is designed for concurrent execution of tasks with process and data synchronizing mechanisms. This ensures the integrity of parallel operation. Until there are Ada compilers for parallel architectures, the embedded software community will not be able to use parallel processing architectures effectively. In the meantime, embedded software developers who need the throughput offered by highly parallel computer architectures are gearing up to program the applications in assembly language using the subroutine libraries provided by machine developers. Some software developers will select a parallel and/or distributed architecture for use in their embedded system. Then they will work with both machine and Ada vendors to interface an Ada compiler and runtime system with peculiar machine facilities and tools. This preserves their investment in Ada applications source code and avoids the Government Ada waiver process. In place of industry standards, this experience will provide an approach to transporting Ada systems and applications to future architectures.

Government needs to establish a parallel computer and distributed network operating system standards. This will facilitate porting of Ada compilers, runtime environments, and tools to various hardware architectures. Existence of standards in which both machine developers and Ada vendors could work towards would foster interoperability and stimulate the market much in the same way that Unix (Posix) and X-windows has stimulated the workstation market.

### 3.2.2.2 Real-Time Software Specification

Real time software specification strategies coupled with reusable software libraries can

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facilitate interoperability between MODEL YEAR upgrades. By specifying the software at a functional level, engineers can synthesize code for any hardware platform provided that compilers and libraries of reusable functions exist. The high level specification provides a global view of the software and allows engineers to assess partitioning and performance limits. The synthesis capability allows engineers to choose hardware or software implementations for functions. The reuse libraries provide software productivity improvements by containing a majority of the needed software functionality. Currently, reuse makes up 10-20% of software builds. Within the next few years, this percentage will likely exceed 50%.

converting software from one architecture to another. Raytheon's experience has shown that the same algorithm, coded identically, can have up to a 100x run time difference when executed on different parallel processors. Issues of data partitioning and communication overhead account for these differences. Additionally, designers must consider the entire signal processing algorithm flow when optimizing for performance. A particular function, matrix inversion for example, might be most efficient within a particular algorithm. However, the next algorithm to execute could find that data in an awkward configuration. Therefore, the first algorithm runs efficiently, but the second algorithm runs inefficiently. Thus, locally

| Repository   | Service/Organization |
|--|----------------------|
| CAMP -- Common Ada Missile Packages                                | Air Force            |
| CARDS -- Central Archive for Reusable Defense Software             | Air Force            |
| RAPID -- Reusable Ada Products for Information Systems Development | Army                 |
| ASSET -- Asset Source for Software Engineering Technology          | DoD                  |
| STARS -- Software for Adaptable, Reliable Systems                  | DoD                  |

**TABLE 3.2-7, SOFTWARE REUSE REPOSITORIES**

Market forces and the changing economy of defense technology will require contractors to bid software programs with reuse being an integral part of the software development plan. Soon enough, bids will not be competitive if software projects stay away from reuse. Contractors will have to reuse software to be competitive in the DoD arena.

The DoD has assembled several domain-specific software repositories for reuse. Table 3.2-7 lists several. Dial-in capabilities are available and soon networking capabilities will be added. For a fee, contractors will have access to domain-specific libraries.

A major drawback to reuse is the difficulty

optimal algorithms may not contribute to global efficiency.

A possible solution is to use an optimization technique known as "genetic algorithms." This approach uses a library of algorithms that perform signal processing functions. It uses a high level architectural model to simulate and determine the "cost" of each particular algorithm and resulting data partition. The genetic algorithm approach selects candidates from the set of algorithms and potential data partitions by using optimizing binary encodings of algorithm characteristics. It manipulates binary encodings by evaluating the fitness of the algorithms as determined by the simulation results.

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## **3.3 Design/Manufacturing Interface Considerations**

*During the RASSP Study Phase, the team investigated the critical elements of the interface between the RASSP design system and the manufacturing resource base capable of supplying RASSP components and products. A signal processor is a complex electronic system requiring manufacturing capability from semiconductor fabrication to multi-module assembly. The following attributes of the design/manufacturing interface were studied:*

- The major participants in the RASSP production cycle
- Design data exchanged with manufacturers
- Production/process data exchange
- Standards modes of data exchange
- Developments/progress required to facilitate RASSP

The industrial base for RASSP includes electrical component, Semiconductor, MultiChip Module, and Subsystem/ System assembly suppliers. Electrical component suppliers provide commercial off-the-shelf products, such as capacitors and resistors, that can be generally purchased through catalogs. Semiconductor suppliers include both commercial/standard integrated circuit devices and application specific integrated circuits (ASICs). Multichip module form the next level of integration, consisting of multiple bare IC die packaged directly on a common substrate. Substrate suppliers include silicon substrates, low temperature cofired ceramic (LTCC), epoxy glass, and polyimide substrate supplies. Contract or in-house assembly services complete the module and system assembly.

Each of these suppliers must interact with the design agency and with related suppliers in the production chain to effectively produce a RASSP product. RASSP users must be capable of entering the system at multiple points of design completion. The three main entry points

emerging in electronic systems are at the functional, the electrical, and the physical description levels. At the functional level the design is described through a functional specification or VHDL. At the electrical level, the design is described through a netlist, a parts list, and a set of test vectors. At the physical level, the design is detailed including component placement, routing, and documentation.

In addition to product design data, production data is exchanged among the suppliers and the RASSP user. Relevant production data includes the following:

- Scheduling/Long Lead Items/Availability
- Cost/Volume/Yield Models
- Process Capabilities (including planned product/process improvements)
- Quality Information (Qualification, Performance)
- Design Guidelines

This data flows between the RASSP user and the supplier and among the suppliers, who must coordinate their efforts to achieve the rapid turnaround goals of RASSP.

### **3.3.1 Production/Procurement Services**

To meet program objectives RASSP products will rely heavily on ASICs and MCMs to realize the upgradability of the model year approach. Design agencies will require access to ASIC and MCM suppliers through a flexible manufacturing interface. While the ASIC industry is fairly well established, the MCM industry is in its infancy. DARPA is seeking to establish a merchant capability for Application Specific Electronic Modules (ASEMs). Access to ASEM foundries will be facilitated by common electronic data exchange and an electronic brokering system. The structure of such a brokering system is depicted in Figure 3.3-1. The ASEM brokering service would provide a mechanism for managing the acquisition of ASEMs through multiple suppliers. The broker manages the relationships with IC and MCM suppliers reducing the number of relationships to be

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managed by the design organizations. The broker would be responsible for qualifying suppliers, understanding vendor capabilities and particular areas of expertise, and responding to customer needs.

The ASEM broker would be responsible for providing a network of services including:

- Foundry
- Die Supplier
- Design Services
- Test

The ASEM customer can utilize the broker for all or some of the brokering services. The customer may want to manage the design from functional through to physical layout, using the broker as a mechanism to supply design guidelines, technology files and libraries. Alternatively, the customer may want to provide just a functional description of the ASEM, acquiring design, procurement, and test services.

The broker must also work with both die suppliers and ASEM foundries to establish and maintain a viable network. The broker would manage the communication of data, capabilities and requirements among the users and suppliers. The broker must understand the capabilities and special attributes of various suppliers, and is charged with maintaining information on the qualification of new and existing suppliers.

### 3.3.2 Contract Assembly Services

Contract assembly services are also available as an option for acquiring RASSP product. Traditionally, contract assemblers have been part of a network of manufacturers providing OEMs with assembly and test services. Contract assemblers are now moving towards more full service capacity including complete responsibility for the manufactured product. Full service includes acquisition and management of all the component parts of the assembly. Essentially,

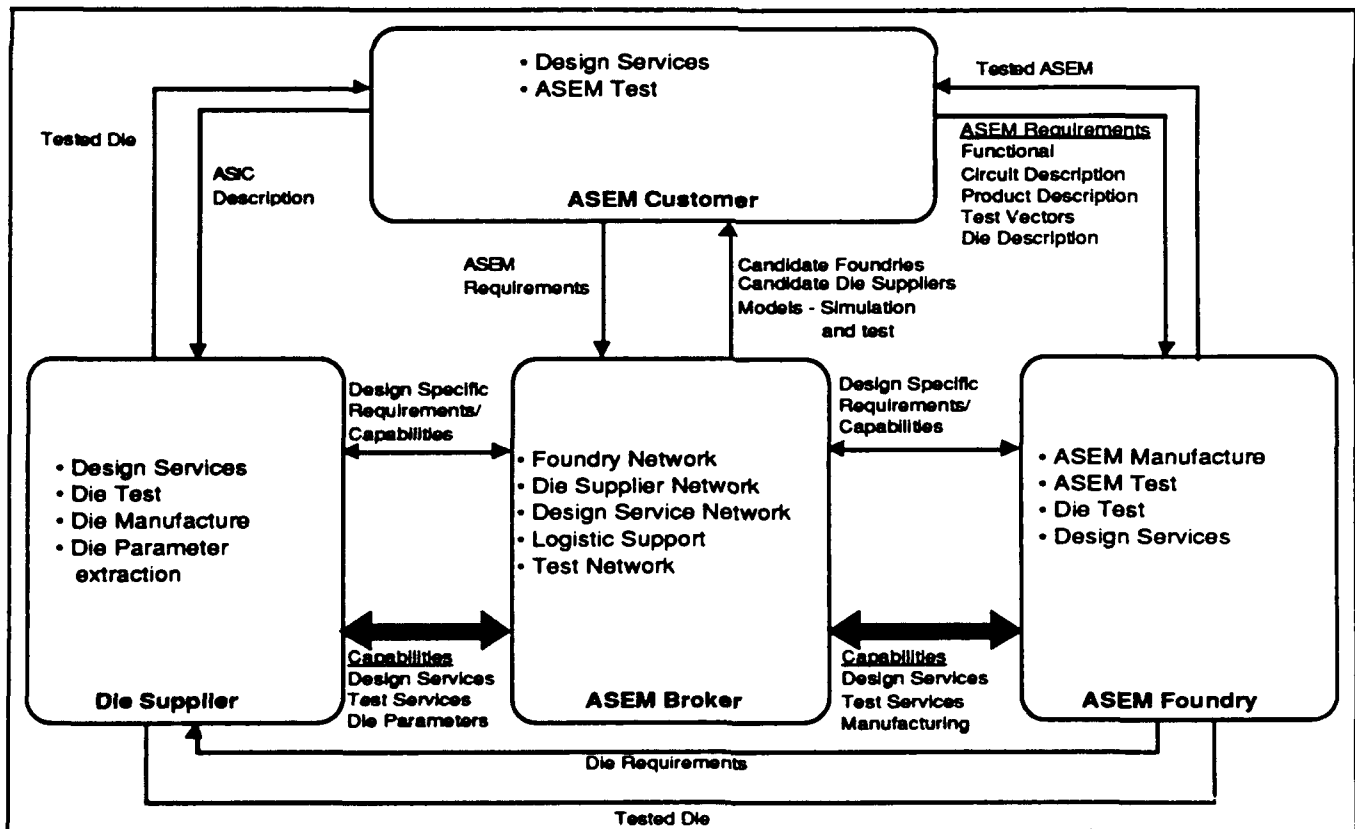


Figure 3.3-1, ASEM Broker

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the user works directly with the contractor who manages the entire manufacturing function. The contractor takes responsibility for the quality and delivery of the components and subsystems. They also provide users with design guidelines and work jointly on new process development.

### 3.3.3 A PWB Design/Manufacturing Interface Example

Raytheon has implemented a system that links commercial PWB design systems to manufacturing through a common database structure, standard interfaces, and a set of application programs. This system has reduced the number of point to point translators required between systems and led to a reduction in non-recurring engineering effort for production start-up. See Figure 3.3-2 The system supports Plated Through Hole, Surface Mount, Blind Pin/Buried Via, and Hybrid technologies. Since Raytheon has multiple design and manufacturing sites that employ different CAD tools, one of the goals of the system was to implement an architecture that would enable a design to be

transitioned into any one of the manufacturing facilities with the required capabilities.

The design/manufacturing interface is based on a vendor independent neutral file. The neutral file is generated, through translators, from Racal Redac's Visula, Harris' SCICARDS, and RAPIDS (an in-house tool). By employing a neutral file, dependence on a single vendor, and the number of translators, are minimized. A Computervision CADD4X database is constructed from a translation of the neutral file for use in manufacturing.

At manufacturing, non-recurring engineering effort has been reduced through a set of application tools that prepare the manufacturing technical data package. This includes preparation of Numerical Control tapes that drive the fabrication and assembly equipment, outputs for bare board and in-circuit test, and computer aided process planning. The NC tapes are produced from the output of a program that plans, through simulation, the optimal insertion sequence based

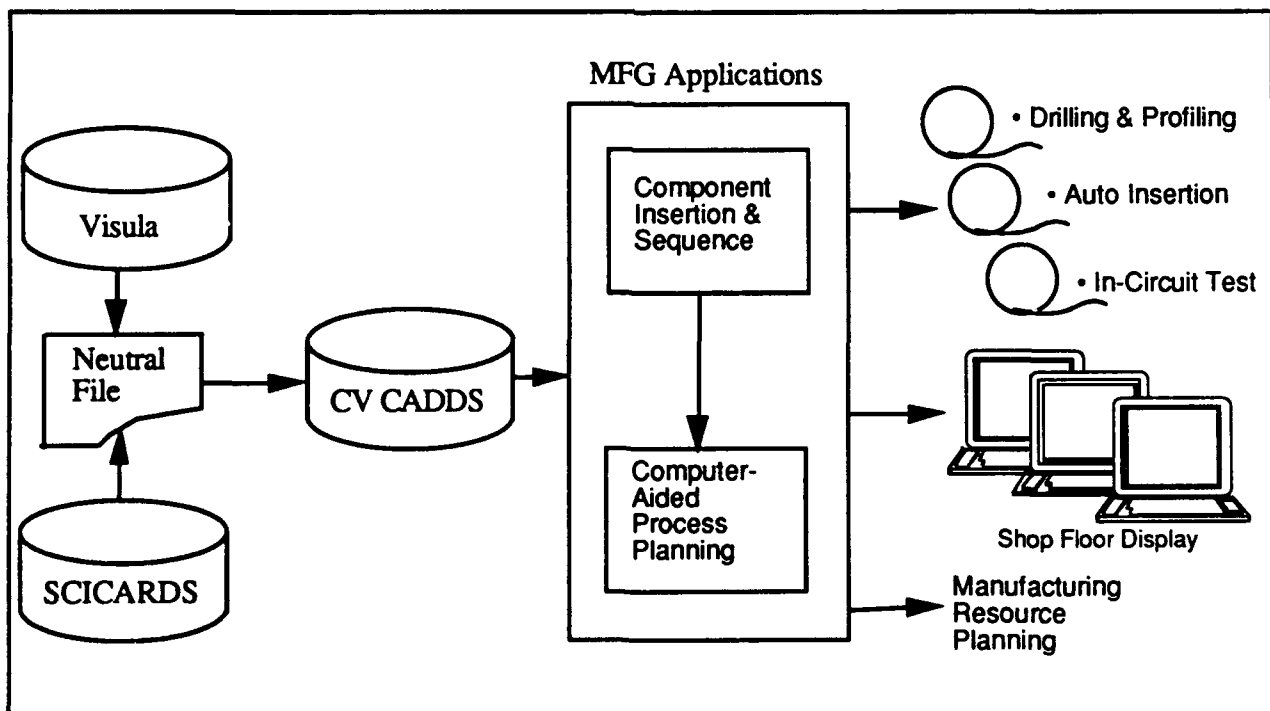


Figure 3.3-2, PWB Transition Database



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| NRE Activity                            | Application Highlights   | Product Data   |
|---|--|--|
| PWB Drill/Routing                       | Creates NC programs that drive drill/rout equipment                                      | XY Locations, PWB outline, Coupons   |
| PWB Panelization                        | Creates multi-image panelized artwork  | Artwork, coupons   |
| Bare Board Test Prep                    | Creates bare board test program  | Netlist  |
| In-Circuit Test                         | Creates In-Circuit test program  | Netlist, Parts list, Comp. values  |
| Component Insertion Machine Programming | Creates component sequence list and location file post processed for insertion equipment | Component dimensions, types, board layout.                                       |
| Process Planning                        | Creates operation sequence, operator instructions, labor standards, manufacturing BOM    | CAD database (netlist, parts list, board layout, geometry, part properties etc.) |
| Visual Aid Generation                   | Automatically creates visual aid pages for display on shop floor terminals               | CAD Database   |

**TABLE 3.3-3 NRE APPLICATIONS FROM INTERFACE**

on component types, placement location, and insertion equipment tooling clearance requirements. The CAPP program plans the

sequence of factory operations required for fabrication and assembly, and provides interfaces to a paperless operator display system and factory Manufacturing Resource Planning (MRP). A summary of the application programs and the production equipment that are programmed from the database is provided in Tables 3.3-3 and 3.3-4.

| Equipment Type            | Vendor/Model                |
|---------------------------|-----------------------------|
| PWB Drill/Rout            | Excellon, Tru-Drill         |
| Bare Board Test           | DITMCO, Integri-Test        |
| In-Circuit Test           | HP 3065, Genrad             |
| Axial Component Inserter  | Universal SSVCD<br>Dynapert |
| Radial Component Inserter | Universal                   |
| DIP Component Inserter    | Universal MultiMode         |
| SMT Device Pick & Place   | Quad Systems, EPE           |

**TABLE 3.3-4 PRODUCTION EQUIPMENT**

### 3.3.4 On-Line Process and Cost Feedback

To ensure the "first pass success" designs, the manufacturing characteristics of RASSP components must be an integral part of early assessment/analysis tools. RASSP products will consist of advanced electronic components, modules, and assemblies; Each of these must be part of an early manufacturability assessment. The following sections describe two efforts, DICE Manufacturing Optimization (MO) and the Monolithic Microwave Integrated Circuit (MMIC), that characterize manufacturing data for design trade-offs. Both programs have been

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funded by DARPA.

## 3.3.5 DICE Manufacturing Optimization

The DARPA Initiative in Concurrent Engineering (DICE) program has been chartered with developing technology that enables concurrent engineering. Part of the DICE concurrent engineering model is a replication of the human tiger team concept that has been successfully used on small scale projects to bring high quality products to market quickly. The basic tenet of the human tiger team is to have the various specialists contributing to the project co-located. In today's environment of complex product designs and geographically dispersed specialists, DICE envisioned a "virtual tiger team" working on a "unified product model" accessible by computer networks. Such an environment must enable specialists from each functional area to work on the design concurrently and share

development ideas.

The MO system is a conceptual refinement to the DICE virtual tiger team concept. In the present DICE virtual tiger team model, all functions are represented and linked concurrently to the product design at a single tier. MO proposes a two tier approach with a virtual product team having a global view supported by information supplied by the virtual process teams( See Figure 3.3-5). The rationale for this refinement is based on the growing complexity of both the products and supporting development processes. It is increasingly difficult to have one representative adequately support a manufacturing (or logistics) position that involves numerous specialized process areas. In practice, the assigned representative is usually a specialist in one of the process areas and has only generalized knowledge about the other processes. The "virtual process team" would enable

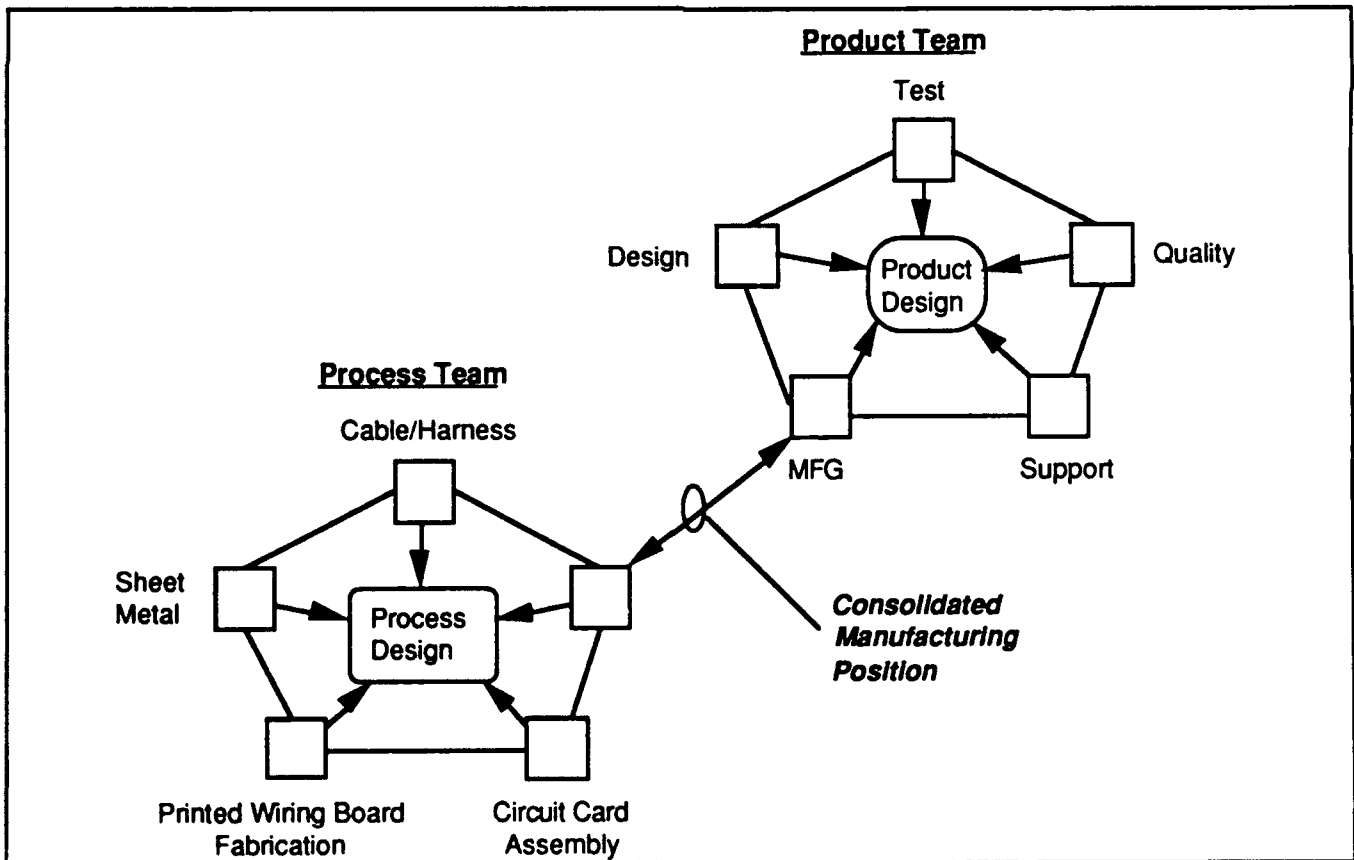


Figure 3.3-5, Two Tiered Team Concept

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representation from all the process areas. The product team would concentrate on using the analyses supplied by the process teams, and determine the best plan by taking into account the existence or implementation of manufacturing, logistics, or test plans. The product team would be responsible for decisions that span cross-functional expertise.

The virtual process team is an extension of the product team. It will consist of specialists representing all the various processes. For instance, a process team for a complex electro-mechanical assembly might consist of a Printed Wiring Board Fabrication, Circuit Card Assembly, Cable/Wire Harness, and Sheet Metal representatives. They will have access to the unified product database and will be responsible for the manufacturing inputs to the product team. Each member of the process team will review the design, perform a manufacturability analysis, and make design or process change recommendations. The product team will then negotiate with the process team to arrive at a position (and perhaps alternatives) consistent with the manufacturing plan.

The virtual process team will be supported by a set of tools that implements a concurrent Design For Manufacturing/Assembly (DFMA) system. These tools will enable the manufacturing process team to perform individual DFMA analyses, merge and review these analyses, and negotiate trade-offs among the processes. A consolidated report and recommendations is passed back to the product team.

The MO system consists of five major functions: a process analyzer, a guidelines analyzer, a yield & rework analyzer, a cost estimator, and a manufacturing advisor. The process analyzer performs the initial analysis on the design to determine the manufacturing process (a set of operations) required to produce the part. The guidelines analyzer captures design for manufacturing and assembly guidelines and associated recommendations. When guidelines are violated, the violation and the associated

recommendation are recorded. The yield & rework analyzer calculates yield and rework values by performing a look up of design features versus an operation. The cost estimator calculates cost for each operation used to produce the part. The manufacturing advisor analyzes the data generated by the individual analyses and guides the negotiation/trade-off process by identifying major cost drivers and guideline violations. It recommends design alternatives based on the influence of the design parameters on the cost analysis and produces the output of the process team that gets passed to the top tier product team.

The MO system incorporates technology developed under the early phases of the DICE program. This technology includes the STEP Tool Kit, the Project Coordination Board, the Communications Manager, and Product Track.

The STEP Tool Kit, from STEP TOOLS Inc., is an object-oriented information management system that supports the product exchange standards emerging for the PDES/STEP standards activity. The tool kit includes an EXPRESS compiler and a set of utilities for managing databases. The tool kit employs a data model that allows the differences between two design versions to be computed as a delta file. Using this mechanism, design alternatives can be explored by multiple team members concurrently and the final solutions merged.

The Project Coordination Board (PCB) is a system being developed to provide support for the coordination of the product development activities in a cooperative environment. The PCB provides common visibility and change notification through the common workspace (CW), planning and scheduling of activities through the task structure, monitoring progress of product development through the product structure (i.e. constraints), and computer support for team structure through messages. The Communications Manager (CM) is a collection of modules that facilitates distributed computing in a heterogeneous network. It

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promotes the notion of a virtual network of resources which the project team members can exploit without any prior knowledge of the underlying physical network. Both the PCB and the CM were developed at the Concurrent Engineering Research Center (CERC) of West Virginia University.

Product Track, From CIMFLEX Teknowledge, is a system designed to manage product requirements, specifications and corporate policies to support concurrent engineering. The system allows the users to define requirements for a project or incorporate standard requirements through pointers (file name). The system also tracks parties interested in specific requirements and provides notification capabilities upon modification to that requirement. Status updates could include modifications of a requirement, product design driven violations of a requirement, or satisfaction of a requirement.

### 3.3.6 MMIC Process/Cost Database

The successful design and manufacture of MMIC components and modules is dependent on an integrated system that enables the chip or module developer to design and analyze an IC based on electrical, material, and process characteristics.

While typical chip design requires contemplation of these characteristics, in MMIC design, the ability to utilize process characteristics to influence design trade-offs is accentuated by the criticality of process on the resulting performance characteristics of the chip.

One thrust of the MIMIC Program was to identify those process characteristics that influenced design manufacturability. Early on, it was determined that the best approach to this problem was to define and implement a database system to provide a data repository for process performance. This database, inserted into the Raytheon foundry in Q1 1991 has resulted in real time data usage and an in-depth understanding that has already increased manufacturing efficiency and improved product cost and yield.

In order to satisfy the requirements of successful

design and manufacture of state of the art MMICs, actual production process parameters are collected in the database at key checkpoints throughout the manufacturing process.

The database functionality enables the collected data to be aggressively and creatively analyzed. For example, statistical analysis of RF performance data has been difficult in the past due to the need to simultaneously understand the frequency variation of the device which is design dependent and the manufacturing variations which are a combinations of random and systematic factors. Efforts such as plotting all of the individual responses on the same graph obscure the comparison with too much detail. The introduction and use of advanced data organization and analysis tools has enabled innovation in displaying and evaluating RF performance data which has been useful in determining appropriate production specifications for new designs.

In order to define the process variables that effect the manufacturability of a design, causal relationships must be determined. The database has been fundamental to the examination of multi-discipline data. For example, analysis of materials, dc and RF performance done at Raytheon suggests that the processing history has a much stronger effect on the resulting output power than the starting material has and any effect of the starting material on average RF performance is perhaps swamped by the processing. As a result, material characteristics have not been considered in the design/manufacturability trade-off. Rather, concentrating on process data, actual s-parameter data has been incorporated into the design library models, thereby providing accurate models of circuit behavior to be used in subsequent design iterations.

Additionally, the database captures cost/yield information that can be used with other production data to analyze capacity and scheduling requirements and influence business plans.

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## **3.4 Manufacturing Considerations**

*The need for small size and weight is essential for a broad range of military applications. Military electronic trends have shown a decrease in feature size and an increase in packaged functionality over time. In the past, integration has taken place at the silicon level, but as IC devices push increasing lead counts, packaging technology has become the limiting factor. Packaging technology selection is a trade-off among the requirements for speed, density, testability, and cost.*

Conventional packages such as Quad Flat Packs (QFPs), Pin Grid Arrays (PGAs), and Tape Automated Bonding (TAB) can get too large and require lead pitches so fine that they get hard to work with. Additionally, QFPs are difficult to test because probes that touch the leads affect coplanarity.

At high lead counts, PGAs and Flip Chip are two main options, but are relatively expensive. These are typically used to package expensive die. For

mass produced ICs, the packaging cost would remain relatively high while the die costs would drop.

Soldering and rework become major issues as lead pitch shrinks. Defect rates and cost increase sharply as lead pitch drops below 25 mils.

Multichip modules (MCMs) are emerging as an answer to the packaging problems stated above. A number of technologies are available for MCMs including:

MCM-L: Laminate - High density laminated PWBs.

MCM-C: Ceramic - Multilayer ceramic substrates. Usually co-fired.

MCM-D: Deposited - High density thin film dielectric and interconnect metal on a supporting substrate.

Availability of known good die and multiple sources are impeding the wide spread use of MCMs. The ASEM program seeks to build an infrastructure to support a merchant capability for MCMs.

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## **3.5 Testing Procedures**

*The RASSP model year concept requires that test procedures become more Adaptable and cost effective at all levels of an electronic system's design. Standardized approaches to testing must be jointly developed by both the military and the commercial industry to ensure that testing procedures become more flexible. It is critical to design test capabilities into a system, allowing rapid insertion of cost effective hardware and software upgrades.*

### **3.5.1 Major Issues**

Historically, test has accounted for 40-50% of electronic system development costs. The changing military environment is focused on continued budget cuts, and increased weapon system mobility. Programs such as the US Air Force F-22 Advanced Tactical Fighter (ATF), and the US Army RAH-66 Light Helicopter (LH) have emphasized the need for common test programs for manufacturing, depot, and field support to reduce life cycle testing costs, and to increase weapon system mobility.

The RASSP concept requires that hardware and software upgrades to signal processors be designed, manufactured, tested, fielded and maintained in a timely manner. In order to achieve this, two fundamental objectives must be met: 1) reduce the cost and time of test program development and transportability; and (2) improve the degree of diagnostics in both the factory and the field.

Because of the life cycle time over which a weapon system must be maintained, a depot tester may become obsolete, and need to be replaced when technology upgrades to a weapon system are made. A major issue with replacing testers is that test program sets (TPS) must be transported from the installed tester to the replacement tester. A test program set includes both test programs and test fixtures. The time and cost of transporting a TPS manually make an automated TPS transporting system necessary. Portions of existing test programs must be re-

used through a system that supports a re-usable library. The use of industry standards for describing product data, test strategy data, and test procedure data is a necessary part of this TPS transporting system.

To expedite the testing process for first article product, it is necessary to provide a test system and methodology that supports the automatic comparison of test equipment measurements to simulation results. Test systems today are disjoint from the design tool's environment. The process verifying first article product is batch oriented. Typically, many iterations are necessary in transferring test data to the test station from the design tools to diagnose failures. A tight link between the CAE design verification environment, and the physical test station should be developed. This new environment would allow the design engineers to exhaust what-if scenarios during initial prototype debug more effectively.

Integrated Diagnostics (ID) provides a structured process that maximizes the effectiveness of diagnostics by coordinating diagnostic and testability requirements from the factory to the field. This process provides a cost effective capability to detect and isolate all faults known or expected to occur in a weapon system. Testability analysis is the process of assessing the inherent ability to test the design using the prescribed test equipment and procedures. This has traditionally been an ad-hoc manual effort in which engineers analyze how the design will be tested later in the weapon system life cycle based on the target test equipment and procedures. Some testability tools are available today, however the present tools have drawbacks that limit their usefulness. For example, many tools require a tedious detailed level of modeling that do not allow for global test strategy analyses. The RASSP process requires tools that can effectively provide and support the automation of Integrated Diagnostics. Specifically, tools that provide analysis during preliminary design based on functional models of the system.

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To satisfy the objective of providing increased weapon system mobility, and better support for maintenance and diagnostics in the field, built in test (BIT) must be utilized. The transfer of test equipment specific testing to BIT increases the system's availability, and avoids the cost, logistical support and training required by unique test equipment. This kind of BIT can be utilized in real time scenarios. It can advise the crew when failures occur in the field during mission operation. The RASSP model year requires a BIT approach to satisfy rapid field deployment and maintenance requirements. BIT also aids in supplementing test equipment limitations when at speed performance testing is necessary.

ATE vendors specify the performance of their test equipment based on best case conditions. For example, state-of-the-art test equipment today is specified to provide clock rates of 80 MHz, and data rates of 50 MHz. These are impressive numbers, however if at speed dynamic testing must be performed, the numbers become less impressive. When parameters such as slew rate, maximum skew, resolution, and burst length are considered, a 50 MHz ATE can turn into a 20 MHz ATE. It is up to the system house to calibrate TPS's at worst case. Other factors that degrade ATE performance include insufficient number of timing generators and timing sets. Timing generators and timing sets are ATE terms that allow timing to be mapped to the unit under test (UUT) pins. Today, this capability is limited. A dynamic test program must have flexibility to map timing that was applied within a simulation environment to the test environment.

RASSP will be taking advantage of the increased speed and density associated with state-of-the-art integrated circuits in conjunction with miniaturized substrates on which they are assembled. This state-of-the-art technology poses new challenges in the area of at-speed testing. New structural design techniques such as the 1149.1 test bus standard are useful in testing the structural integrity of interconnects

between devices on a module, but cannot be used effectively for at-speed testing. Test instruments such as logic analyzers and guided probe will no longer have the physical access needed to monitor nodal states for at speed testing. Therefore, new approaches are needed to overcome the inability for test instruments to gain access to nodal states in order to perform at-speed functional testing. High speed signal processors will require embedded test techniques. The RASSP model should include the top down design of embedded test controller chips that can act as monitors of critical bus signals within the unit under test (UUT). The test equipment would interface with the test controller chips in a mode that initiates the embedded test programs, and then the test equipment would detach itself from the test operation until the embedded test program completes. At that point, a result in the form of a signature could be read out via the test equipment.

## 3.5.2 Possible Solutions

As the model year provides for multiple technology upgrades of a weapon system, it is necessary to provide a test system that is part of the RASSP design environment which has the objective of supporting a coordinated refinement of design and test requirements. As the design process transitions from system design requirements to top-level design to detailed design, so too should the test procedures. High level test requirements should be captured in standards such as the test requirements specification language (TRSL), and checked against high level design requirements represented in VHDL. Test program data represented in WAVES, Ada, and/or ATLAS should be checked against the top level design data represented in VHDL. A tool set should be developed that supports this concept of coordinated refinement. Test must be part of the design process.

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## 3.5.2.1 Translation System For TPS Development

To reduce the time and cost of transporting test programs to multiple test environments, a translation system should be developed that provides automated generation and maintenance of electrical test specifications and test programs. The system would provide the capability to develop test program sets and test specifications based on standard data formats. The translation system would manage the product and test data

(TRS) would be in an industry standard form such as TRSL. The test requirements definition process would consist of a tool that would guide the design and/or test engineer through the generation of the TRS. The test specification would then be captured in a database for life cycle support. This database representing high level test requirements would then be used to generate target test programs in industry standard formats such as Ada, ATLAS and WAVES.

The TPS post processor step allows for the

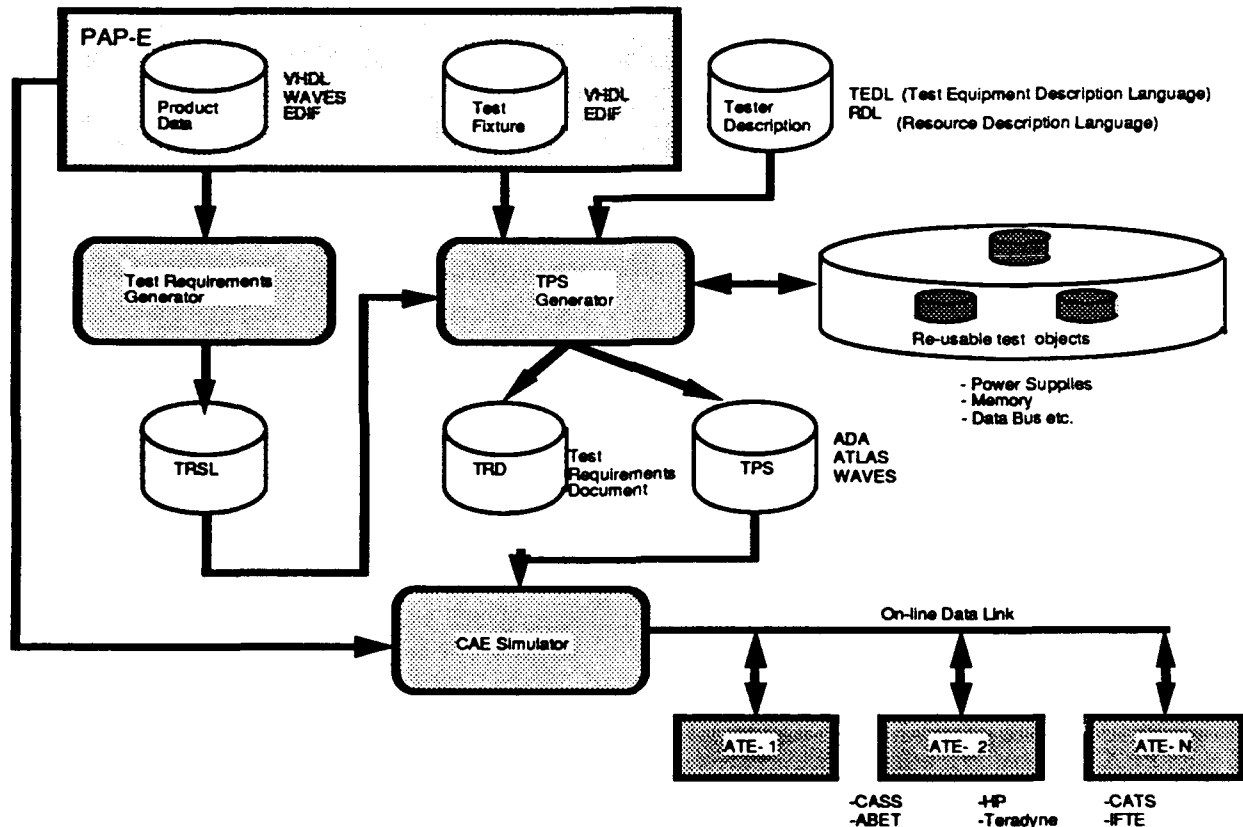


Figure 3.5-1, TPS Data Flow

over the life cycle of the weapon system. Figure 3.5-1 represents a functional flow of such a translation system.

Product design data in the form of VHDL, WAVES, EDIF etc. would drive the process of generating a test requirements specification (TRS). The test requirements specification

generation of TPS's independent of the target test equipment being used. This process would incorporate the concept of a knowledge based re-usable library. The TPS post processor "IN-STEP" developed by Harris under contract via the Tester Independent Support Software System (TISSS) program should be evaluated for applicability to RASSP. IN-STEP successfully demonstrated TPS re-targeting for an advanced



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tactical fighter (ATF) line replaceable module (LRM).

This approach to test program development would support the RASSP model year concept by reducing the time and cost associated with developing initial test programs, and the time to transport the test programs for testers in the field. On-going DoD initiatives in TISSS, Ada Based Environment For Test (ABET), Modular Automated Test Equipment (MATE), Consolidated Automated Support System (CASS) should all be evaluated, and applicable technology utilized in the RASSP concept.

### 3.5.2.2 Design/Test Interactive Link

Another aspect that would decrease the test development time would be a simulation system that in an on-line fashion communicates with the unit under test (UUT). As Figure 3.5-1 illustrates, this simulation system would actually communicate with the test equipment via a telecommunications link. The simulation platform would emulate the specific test equipment behavior up front to ensure that test patterns are compatible with the target test equipment. The specifics of the test equipment resources would be represented in an industry standard format such as the Test Equipment Description Language (TEDL) or the Resource Description Language (RDL). The test program to be simulated would be represented in either Ada, WAVES, ATLAS, or a combination of the formats. This same test program format would be used to drive the test equipment. In addition, expected responses can be compared against test equipment measurements automatically. Any discrepancies would be flagged on the simulation workstation in the form of graphical wave forms. The design and/or test engineer can then rapidly debug the first-article-product by exercising what-if scenarios quickly. First-article product problems such as design errors, vector errors, or manufacturing defects can be isolated more quickly.

### 3.5.2.3 BIT/BITE Insertion

The RASSP model year concept must support the

need for increased diagnostics with less dependence on supporting test equipment. This can be achieved through the use of increased BIT/BITE insertion. The BIT/BITE insertion must be part of the RASSP design process. A testability advisor tool that works at the high level should be used to advise on a BIT architecture for a system.

As Figure 3.5-2 illustrates, the design for test (DFT) tool would be used early in the product life cycle when hardware/software partitioning decisions are made. The tool would take as input a VHDL behavioral representation of the system. This VHDL description describes the architecture of the system by specifying functional blocks and their dependencies on each other. Another input to the tool is the testability and diagnostic requirements. Issues such as degree of fault isolation, level of fault coverage, and test time constraints are examples of test requirements. The test requirements would be in the format of the proposed IEEE Test Requirements Specification Language standard (TRSL). A third input to the advisor tool is data that describes technology specific information such as reliability data and yield parameters.

The tool would work off of a knowledge base that contains global test strategies. Examples of the global test strategies that are included in the knowledge base are: Built-In Self Test (BIST) descriptions of sub-functions, test controller chip architectures, types of scan path implementations, types of BIT associated with COTS (commercial off the shelf) and SEM-E modules. The advisor would then identify where testability is lacking and recommend where BIT should be incorporated. The key objective is to identify diagnostic requirements early so that they can influence the overall design architecture of a system.

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## 3.5.2.4 Integrated Diagnostics Design Tools

In order to reduce the time and cost of implementing Integrated Diagnostics, the RASSP model year concept must include a set of tools that help automate the process. These tools must meet certain requirements. First, the tools must be simple and easy to use. This is very important for those tasks that must be performed early in the design cycle due to tight schedules. Second, the tools must be able to support all

allocated more efficiently.

Figure 3.5-2 illustrates an environment that stresses that test activities must be part of the entire product life cycle. More specifically, the automation of test activities must be part of the concurrent engineering design system. Figure 3.5-2 also emphasizes that the automation process must utilize data from a harmonized product data model, and be available for use throughout the entire product life cycle.

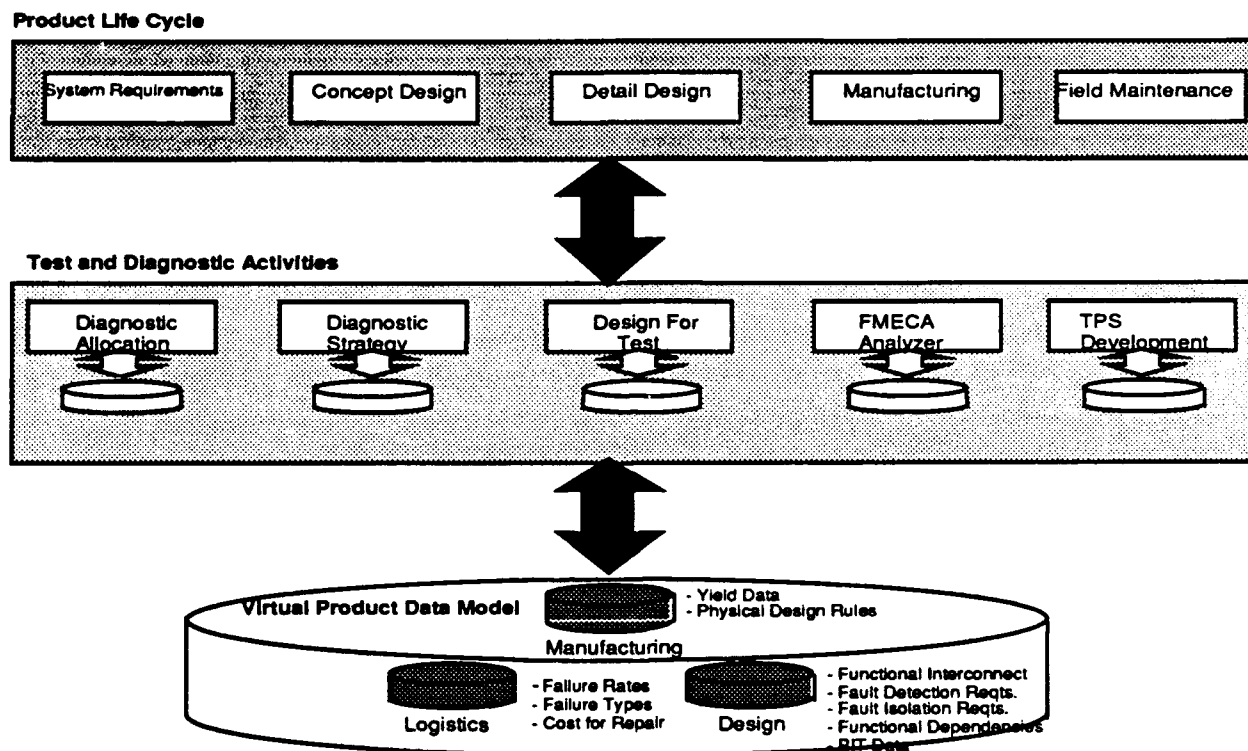


Figure 3.5-2, Life Cycle Testing

types of technology (i.e. Digital, Analog, Mechanical etc.), and also all levels of assembly (i.e. boards, subsystems and systems). Third, the tools must accept product data in the form of industry data standards from CAE/CAD tools whenever possible. Finally, the tools must link conceptual and detail design phases. This linking process includes supporting both a top/down and bottom/up methodology. This linking process will allow the high level requirements for testability, maintenance, and diagnostics to be

There are five test activities that should be automated to support Integrated Diagnostics. They are as follows :

1. A tool to automate top/down diagnostic allocation requirements.
2. A tool to develop diagnostic strategies based on functional dependencies.
3. A tool that provides BIT insertion, and

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determines BIT effectiveness.

4. A tool to automate FMECA (Failure Mode Effects and Criticality Analysis).
5. A tool to automate TPS development.

The diagnostic allocation tool would translate high level operational and support requirements into lower level diagnostic requirements for each sub function of a system. This process would include determining the fault detection and fault isolation requirements for each sub function of a system. The diagnostic allocation tool would work with a knowledge base to assess the optimal diagnostic architecture for a subsystem element. High level functional simulations would be performed as part of the analysis process.

Commercial tools exist today that generate diagnostic test strategies based on functional dependencies of a system. These tools allow what-if scenarios to be performed before a system is committed to detail design. The commercial tools should be integrated with the other tools that support Integrated Diagnostics.

BIT analysis is the process of determining the effectiveness of a system's BIT design architecture. BIT consists of a combination of hardware and software techniques that allow a system to monitor itself. Typically, the hardware aspects of BIT are defined first, while the software BIT design occurs later in the design cycle. The software is more flexible and easier to modify, therefore a tool should be developed to help analyze the overall effectiveness of the hardware BIT aspects independent of the software. Certain assumptions can be made relating to the functionality of the software. The output of this tool will be a metric defining how well the BIT design can detect and isolate failures in the system. This tool would be part of the design for test tool. As the DFT tool recommends BIT insertion, it will also provide a figure of merit as to how effective the BIT would be.

Commercial tools are also emerging that support

failure modes effects and criticality analysis (FMECA). In the past the FMECA tool set only included support for documenting the results of a FMECA analysis. Little support was available for actually defining the effects of failure modes on a system. New tools are available today that allow one to model a system at a high level, and graphically view the effects of failure modes. These FMECA tools should be integrated with a common Integrated Diagnostic tool set.

### 3.5.3 Challenges

Standards are a very important aspect linking the proposed test procedure solutions to the RASSP model year concept. Unfortunately, not all standards have been approved as of yet, and the approval process for pending standards could take years. Two critical standards that need approval are the Test Requirements Specification Language (TRSL), and the Fault Dictionary Language (FDL). In the interim, concepts can be developed around the proposed standards with the assumption that the proposed standards will become approved standards before detailed implementation issues occur. Working groups such as the Test Automation Standards Group will be a key driving force to make standards such as TRSL and FDL a reality.

Some commercial tools exist today addressing system design test procedure issues. As defined above, new tools must be developed to address the requirements for testing within the RASSP model year concept. These tools must be integrated under a common framework with existing commercial tools to provide a seamless tool environment. The challenges exist in the CAD framework standards. The CAD Framework Initiative (CFI) is still defining the standards associated with interface standards. As with the design system, close monitoring and support of CFI is required to meet the challenges of integrating commercial tools with newly developed tools.

The RASSP model year concept will be pushing the latest technology upgrades for various weapon systems. It is unlikely that ATE will

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keep pace with the latest technology. Therefore, it is essential to focus new test procedures on BIT/BITE to reduce the dependency on ATE. Interface standards for both hardware and software must be defined and implemented to support the communication of BIT architectures with existing ATE in the factory, depot, and field. The Air Force has been addressing this standard interface requirement through the ABET (Ada Based Environment For Test) program.

The increased emphasis on BIT/BITE will generate new challenges. Many weapon systems today experience a high frequency of false alarms related to BIT. A study was conducted on the B1-A which had the objective of identifying and classifying the reasons for BIT false alarms. The report (ASD-TR-81-5203) summarized that of 1704 test flight failures, 919 were classified as false alarms. New initiatives have already started to reduce the degree of false alarms associated with BIT. Raytheon Co. recently won an award from Rome Labs to address false alarm filtering using neural network principles.

### 3.5.4 Feasibility

The test subcommittee of the IEEE Computer Society Design Automation Standards Subcommittee (DASS), and the Test Automation Standards Group (TASG) have been aggressively pursuing the standardization of TRSL, and FDL. Close contact with these standardization groups is essential to stay abreast of the latest standards issues so that they can be applied to the RASSP model year concept.

The Air Force has initiated an on-going effort to standardize on the Ada programming language to develop test program sets (TPS). In 1989, the IEEE Standards Coordinating Committee 20 (SCC20) approved using Ada as a central focus for the proposed ABET standard. The proposed ABET standard scope is to define a standard Ada based environment which uses other standards relating to design, test and maintenance activities. The Air Force ABET program is a four phase five year program to define and implement ABET. The outcome of

ABET can be directly applied to the issues of providing a common test environment for the factory, depot, and field.

The ManTech Directorate at Wright Patterson AFB will be funding a program called VTEST (Virtual Test) in 1993. The objective of VTEST is to develop an environment that allows a 5:1 reduction in test program development and re-target costs. The "core" standards that come out of ABET will be applied to VTEST. The commercial tools that are delivered for the VTEST program should be incorporated as part of the RASSP test procedures environment.

Rome labs funded a program called TISSS (Tester Independent Support Software System). The TISSS program proved that the use of CAD and tester independent electronic product data can be used for the capture and use of electronic design and test information for the automatic generation of TPS's and test specifications. The TISSS tools were successfully applied to an ATF LRM. Technology associated with the TISSS IN-STEP post processor should be investigated for applicability to RASSP.

Raytheon has a pending proposal relating to the use of BIT. In response to the DARPA ASEM BAA 92-09, Raytheon submitted a proposal called Intelligent Test Controller. This proposal addresses the requirement of inserting BIT early in the product life cycle. High level test requirements specifying test intent independent of technology is captured. The tool reads the test requirements, a knowledge base of BIT structures, a functional description of the UUT, and automatically synthesizes a test controller description in Ada or VHDL.

The commercial industry has been making progress in the area of TPS development. Teradyne has developed and demonstrated software that transports TPS's from one commercial ATE to another. The demonstration was based on translating Genrad 179x TPS's to the Teradyne L-series ATE. The translation system included both the translation of test programs and test fixtures. The fixture

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translation was based on designing a standard interface fixture that would mate with the Genrad fixtures. The concept of developing standard "interface fixtures" should be investigated further for applicability to RASSP.

Commercial CAE companies such as Synopsys have tools that automatically insert BIT structures into a component represented in VHDL. TSSI is developing software that will both read and write the IEEE WAVES standard.

Universities such as Virginia Tech. and USC are working on software that address testability at higher levels of abstraction. Virginia Tech. has software that supports the concept of functional

fault simulation based on VHDL behavioral descriptions. This functional fault simulation software is consistent with the overall direction of analyzing testability early during preliminary design.

The government, commercial industry, and the universities have been making advances in broadening the support for test. The RASSP program can take advantage of the latest technology, and apply it to meet the objective of designing test capabilities into a system, to support the concept of rapid insertion of cost effective hardware/software upgrades.

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## **3.6 Equipment Requirements**

*The RASSP program demands a manufacturing foundation that can provide the highest manufacturing flexibility, lowest cost per unit, and most rapid response time. While the tools and methodologies to achieve these objectives differ depending on assembly level, all suppliers need a strong manufacturing system support structure to drive the factory. The ability to provide rapid response and low cost is a function of the systems at the manufacturing site. Computer Integrated Manufacturing (CIM) systems have promised to enable a factory to operate profitably at an order quantity of one. While this promise has yet to be achieved, significant strides have been made in linking factory floor equipment to above floor control systems.*

The RASSP industrial base must embrace flexible manufacturing systems that can support rapid turnaround and low volume production. These systems must be scalable to higher production rates on demand. These systems must be based around a set of standard tooling on programmable equipment.

Typically, such production lines are based on a standard family of parts. Associated with this family is a set of operations and resources that can fabricate the variety of parts that belong to the family. Part families are conceived through the identification of parts that are characterized by a common set of attributes. Given the common product/process attributes, a production line is constructed to support production of the family. A communication and information infrastructure integrates equipment programs, process control,

equipment status, and WIP information. Volume is achieved through the ability to produce an family member without extensive set up. The equipment is driven by computer programs generated from CAD databases. By increasing the programmability of the equipment, standardizing on tooling, and integrating the information flow, low volume production can be economically achieved

### **3.6.1 Assembly Equipment**

Automatic assembly equipment for through hole component types include interfaces for process monitoring and off-line programming. Surface mount components are assembled by "pick and place" assembly machines. These work well down to 25 mil pitch. Pick and place technology typically relies on vision-assisted centering and squaring of components. Pick and place technology is fairly slow and will create production bottlenecks as device counts grow and density increases. Development is needed in faster, more accurate placement of devices.

As packaging moves toward ultrafine pitch technology such as TAB and Flip Chip, the assembly equipment becomes more specialized. The mixing of technology would lead to requirements for a number of different pieces of equipment.

Ultrafine pitch components and denser modules are forcing rework and repair techniques to become more sophisticated. Semi-automated systems deploying vision systems, special lighting, microscopes, and electronic displays are evolving.

Sensors and process control mechanisms are required to provide production and process status information links.

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## **3.7 Facility Requirements**

*To accomplish study phase objectives, the team examined the capabilities of easily accessible facilities with state of the art capabilities. The facility in Portsmouth RI which supplies a major portion of the Navy's Standard Electronic Modules (SEM) has a unique capability such that it can adapt to high density MCM based SEM and 3D stacking modules. The facility in Lowell, MA supplies Hybrid Electronic Assemblies. Each will be described below. The team also investigated other potential RASSP suppliers including the Microelectronics Manufacturing Science and Technology (MMST) cluster tool facility of Texas Instruments.*

### **3.7.1 Raytheon SEM-E Capabilities**

The manufacturing facility at Raytheon Submarine Signal Division (SSD), Portsmouth RI is fully equipped to produce complete electronic systems including circuit card assemblies. Raytheon SSD manufacturing facilities encompass 131,000 square feet that includes a state-of-the-art material center, all of the production level processes for through hole and surface mount technology circuit card assemblies, ceramic thick film multi-layer interconnect board manufacturing, cable and harness fabrication, electromechanical assembly of all sizes, a versatile machine shop, and transducer manufacturing.

Specifically regarding circuit card assembly manufacturing, Raytheon SSD has in place proven equipment and processes for component placement, mass reflow and wave soldering, automated conformal coating and sophisticated test capability for the existing product lines.

For the past 17 years, Raytheon has been actively involved in the development, system packaging and mass production for the Standard Electronic Module (SEM) Program. Presently Raytheon is certified for the production of SEM-A,-B,-D and E boards by the Naval Weapons Support Center (NWSC), Crane. In addition, the Copper Thick

Film Multi-Layer Ceramic Boards facility for the SEM Program is also certified by NWSC.

The facility has historically worked very closely with the Naval Avionics Center (NAC) and the Naval Weapons Support Center (NWSC) with their board documents. In support of involvement with both government and industry, we are the lead IEEE participant associated with 1101.3, a conduction-cooled Eurocard designed for avionics environments, and with 1101.4, a SEM-E size MIL module. Raytheon is the editor for the 1101.4 specification and the architect for 1101.3 specification. We have supplied design support and product to customers, successfully demonstrating capability for technology exchange.

Raytheon developed a packaging system jointly with NWSC for an open architecture system now operational on the AN/BSY-1 combat system for submarines. Developed to meet the requirements of the Navy Standard Hardware Acquisition and Reliability Program, the board set is the forerunner for concepts now specified in both the Joint Integrated Avionics Working Group (JIAWG) and the Next Generation Computer Resources (NGCR) programs. The AN/BSY-1 program provided Raytheon with exposure to the problems of inter-operability, testability and exchangeability as our standard board set was used on a major platform by multiple vendors in various configurations in an integrated system. For those vendors, we manufactured a core set of boards (CPU, global memory and I/O), supplemented by digital signal processors, A/D and D/A converters, and analog signal conditioners. These boards, SEM-D, are only slightly smaller than SEM-E. To date, the number of these SEM-D boards delivered to the Navy and maintained in the operational sonar system exceeds 35,000.

Raytheon's board facility has been certified for SEM-E by the Naval Weapons Support Center, Crane (NWSCC) to meet the requirements of QAA programs as defined in MIL-M-28787D. This facility was started in 1985 to accelerate

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ceramic MIB technology and product availability. Today, it continues to manufacture ceramic and polyimide SEM boards for the Navy's AN/BSY-1 program. Recent advances in solder/flex application, conformal coat technologies and enhanced test diagnostics are examples which have led to the improved yields.

## **3.7.2 Raytheon Lowell Capabilities**

Raytheon Missile System's Division Lowell Manufacturing Plant specializes in hybrid parts. The plant consists of 17,000+ square feet of Class 100,000 Clean room floor space. The facility manufactures over 166 hybrid part numbers of mixed types including analog, digital, high frequency and microstrip. These hybrids represent 5 programs including AMRAAM, Phoenix, Stinger, Sidewinder and Sparrow (7-P). Raytheon's Lowell facility has proven process capabilities for 0.7, 1.0, 2.0 mil Gold Ball Bonding, 0.7, 1.0 mil Gold Wedge Bonding, 3 mil, 10 mil, 20 mil Gold Ribbon Bonding and Coining thick film substrates. Materials types include Thick Film Networks, Thin Film Networks, Duroid Networks, Silicon Devices, Gallium Arsenide devices and Quartz Devices.

The Lowell plant assembles hybrids using their extensive assembly capabilities. These capabilities include semi-automatic/ automatic attachment of die and chip components, semi-automatic/ automatic application of component attach adhesives, and manual attachment of eutectic devices. Hybrid packages and assemblies are laser marked using a Control Systems Laser. There is an Autoclave for pressurized curing of epoxy preforms which are used to attach microstripline circuits to packages. Rework capabilities consist of removal and replacement of epoxy attached devices/substrates, removal and replacement of eutectically attached devices, and four delidding systems. Additionally, wirebonding capabilities include both automatic and manual ball and wedge bonders.

Lowell inspection capabilities include hi/low

power inspection, environmental screening, leak testing, burn-in, and in-circuit test. Hi/low power inspection consists of manual bond pull and semi-automatic point-point wiring inspection. Temperature cycling, acceleration and PIND testing provide full environmental screening. Capabilities also include liquid and air burn-in, Helium and Krypton 85 fine and gross leak testing, and in-circuit test with a board watch system for troubleshooting and rework. Testing capabilities at Lowell includes a manual/semi-automatic process for tuning hi-frequency and microstrip hybrids, Active and ratio laser trimming of resistors, and ATE for functional test.

The Lowell plant continues to implement advanced manufacturing systems that result in higher efficiency and better quality products. In the hybrid area, shop floor paperless display systems are being installed to provide assembly operators with color graphic assembly instructions. Over 25% of all process plans and 100% of process specification reference instructions have been put on-line. The facility will have displays on 75% of the assembly workstations by the end of 1992. The Product Assurance Inspection Reporting System (PAIRS) is a mainframe based statistical quality control system that is used to track quality trends and initiated corrective action cycles when required. PAIRS is complemented by on-line statistical process controls include epoxy screen printing, wirebonding, component attach and sealing. There is a wand/bar code system in place for the automatic tracing of work-in-process and a vertical carousel storage of hybrid part inventory for rapid kitting.

## **3.7.3 PWB Fabrication and Assembly Services**

There is a broad base of PWB fabrication and assembly contract manufacturers. Fabricated PWBs that meet Mil 55110 qualifications can be turned around in generally 48-72 hours for a multilayer epoxy glass substrate. PWB fabricators rely on Gerber and drill hole data



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product data, as well as, customer data such as quantity and schedule. Electronic transfer of product data is typical. In the PWB assembly area quick turn around is also offered as well as full service capabilities. Product data exchange includes drawings, CAD databases, parts list, and test vectors.

## 3.7.4 Cluster Tool Facilities

Cluster tool based facilities offer the ability to provide low volume access to semiconductor capabilities. The concept of the cluster tool facility is a modular factory with automated processing where the cleanroom is housed within the equipment and transport mechanisms are vacuum cassettes that house the wafers. Within tools, wafer move via robot and are processed one at a time. Sensors and expert systems provide process control and status information. The tools are linked together in the factory by a computer integrated manufacturing system that provides recipe management, equipment status, and work-in-process status. The cluster tool

approach provides scalability to higher volume production. The key to the system is that low volume production can be economically achieved and growth to higher level of productions is feasible. There is a cost trade-off with dedicated lines at high volume rates. The footnote reference<sup>1</sup> provides a summary of processes and cost models for cluster tool fabrication lines..

## 3.7.5 RASSP Sources

Despite the in-house facilities available at four divisions and seven manufacturing plants, several weapon systems produced by Raytheon have a major portion of their components purchased and manufactured outside. A major portion of the country's industrial fabrication facilities have been used. For RASSP, only the outside industrial resource will be used in the development of the demonstration units. Table 3.7-1 lists "outside" MCM suppliers which could be involved in the fabrication of RASSP processors.

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<sup>1</sup>Kinsella M., Blasingame J., (1991) 1990s  
Semiconductor Manufacturing Strategy: Progress Report,  
*GOMAC, 1991 Digest of Papers*

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| Parameters<br><br>Companies  | Technical Contact<br>(Sales Contact)  | Technology Type<br>MCM-C,<br>MCM-L, MCM-D,<br>MCM-D/C,<br>MCM-Si | HDI Base Substrate<br>(Max. Size)                            | Chip Inter-connection Options     |
|--|---|--|--|-----------------------------------|
| <b>ALCOA</b><br>16868 Via Del Campo CT<br>San Diego, CA 92127                  | Len Schaper<br>(619)451-5563<br>(Phil Scott)  | MCM-D  | Alumina,<br>Silicon<br>[4.0 X 4.0]                           | Wirebond<br>Tab<br>Flip Chip (NJ) |
| <b>ALGOSEX</b><br>45 Adams Ave.<br>Hauppauge, NY 11788                         | Bill Ciechenowski<br>(516)434-9400<br>X127<br>(Charles Sutherland)<br>(617)235-2330 | MCM-C  | Ceramic, Metal   | Wirebond<br>Tab                   |
| <b>AT&amp;T</b><br>N. Andover. MA  | George Trudel<br>(508) 960-4558   | MCM-D  | Alumina<br>[4.0 X 3.25]                                      | Wirebond<br>Tab<br>Flip Chip      |
| <b>DEC (MMS)</b><br>10 Tara Boulevard<br>Nashua, NH 03062                      | Jim McElroy<br>(603)884-0728  | MCM-D  | Alumina  | Wirebond<br>Tab                   |
| <b>GE</b><br>Schenectady, NY   | Charles Becker<br>(518)382-5472<br>(W.R. Broyles)<br>(518)337-5835                  | MCM-D<br>(Chips First)   | Alumina,<br>Silicon. Metal<br>[4.0 X 4.0]                    | Internal To<br>Structure          |
| <b>HUGHES</b><br>Newport Beach, CA   | Richard Himmel<br>(714)759-2843   | MCM-D  | Alumina, AlN<br>Silicon<br>[3.8 X 3.8]                       | Wirebond<br>Tab<br>Flip Chip      |
| <b>IBIDEN</b><br>1270 Oakland Parkway<br>Sunnyvale, CA 94086<br>RM. 206, Japan | Sataro ITO<br>(408)735-7755<br>(Rich Puchniak)<br>(508) 526-1211                    | MCM-D<br>MCM-D/C   | Aluminum<br>Nitride (AlN)<br>[4.0 X 4.0] *<br>[2.0 X 2.0] ** | Wirebond<br>Tab                   |
| <b>IBM</b><br>1580 Route 52<br>Dept. 42W Bldg. 514<br>Hopewell Junc., NY 12533 | Ed Chang<br>(914)892-9712   | MCM-D<br>MCM-D/C   | Glass Ceramic<br>[6.0 X 6.0]                                 | Flip Chip                         |
| <b>ISA</b><br>600 West Cummings Park<br>Suite 6000<br>Woburn, MA 01801         | Dr. James Kohl<br>(617)937-0177 X30   | MCM-D<br>(Chips First)   | Alumina<br>[2.0 X 2.0]                                       | Internal To<br>Structure          |
| <b>KYOCERA</b><br>San Diego, CA  | Richard Gigliano<br>(619)576-2770   | MCM-D<br>MCM-D/C   | Alumina<br>[4.0 X 4.0]                                       | Wirebond<br>Tab Flip Chip         |

*Figure 3.7-1, MCM Suppliers*

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| Parameters<br><br>Companies   | Technical Contact<br>(Sales Contact)                                 | Technology Type<br>MCM-C,<br>MCM-L, MCM-D,<br>MCM-D/C,<br>MCM-Si | HDI Base Substrate<br>(Max. Size)   | Chip Inter-connection Options      |
|---|--|--|-------------------------------------|------------------------------------|
| <b>MICRO SUB. INC.</b><br>547-D Constitution Ave.<br>Camarillo, CA 93010            | Dr. Ram Panicker<br>(805)482-2006                                    | MCM-D  | Alumina<br>[6.0 X 6.0]              | Wirebond<br>Tab<br>Flip Chip       |
| <b>N-CHIP</b><br>1971 N. Capitol Ave.<br>San Jose, CA                               | Bruce McWilliams<br>(408)945-9991<br>(Mark Trulli)                   | MCM-Si   | Silicon<br>[3.4 X 3.4]              | Wirebond<br>Flip Chip<br>Tab (FUT) |
| <b>NTK</b><br>40 Speen St.<br>Framingham, MA  | Keiichi (Keith) Fujii<br>(408) 727-5180                              | MCM-D<br>MCM-D/C   | Alumina, AlN<br>[6.0 X 6.0]         | Wirebond                           |
| <b>PMC</b><br>Burnaby, BC<br>Canada   | Colin Harris<br>(604)293-6044  | MCM-D  | Silicon<br>[2.8 X 2.8]              | Wirebond                           |
| <b>POLYCON</b><br>Tempe, AZ   | Bob Devellis<br>(602)731-9544  | MCM-D  | Silicon<br>[4.1 X 4.1]              | Wirebond                           |
| <b>ROCKWELL</b><br>2427 W. Hillcrest Dr.<br>Newbury Park, CA                        | Art Cappon<br>(805)375-1295  | MCM-D  | Silicon<br>[1.6 X 1.6]              | Wirebond                           |
| <b>ROGERS</b><br>Rogers, Conn.  | John Olenick<br>(503)774-9605  | MCM-L<br>W/RO2800  | Aluminum<br>[4.0 X 4.0]             | Wirebond<br>Tab, Flip Chip         |
| <b>TELEDYNE</b><br>Los Angeles, CA  | Ken Zust<br>(213)822-8229  | MCM-D  | Alumina                             | Wirebond                           |
| <b>TI/GE FOUNDRY</b><br>P.O. Box 660246<br>Mail Station 3137<br>Dallas, Texas 75266 | Bob Raulerson<br>(214)995-4614<br>Theresa Armstrong<br>(214)995-7089 | MCM-D<br>(Chips First)   | •                                   | •                                  |
| <b>TI</b><br>13532 N. Central<br>Expressway, MS 88<br>Dallas, Texas 75266           | Dean Fruew<br>(214)995-6511  | MCM-D<br>(Chips Last)  | Alumina<br>[4.0 X 4.0]              | Wirebond<br>Tab                    |
| <b>Z-SYSTEM</b><br>3080 Olcott St.<br>P.O. Box 110C<br>Santa Clara, CA              | Jan Hull<br>(408)980-1563<br>(Jan Hull)<br>(408)257-9921             | MCM-D  | Silicon<br>[2.8 X2.8 To<br>4.0X4.0] | Wirebond                           |

*Figure 3.7-1 Continued, MCM Suppliers*

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## 3.8 Database

### 3.8.1 Objectives

*In order to support the goals of model year concept, a 'seamless' data model that will integrate the functional areas of design, manufacture and logistics must be defined. Through the use of this seamless data model, product quality can be improved, and hardware and software product costs can be reduced. Integration of design, manufacturing and logistics data will provide critical cross-discipline information in an easy to access, timely manner. Using an integrated database, actual test data collected from manufacturing and logistics functions can be incorporated into the design process to enable design/manufacturability and design/supportability trade-offs. Further, comparing actual test data with simulated test data enables tuning of simulation models, leading to more accurate predictions. Both of these examples demonstrate design for*

*manufacturability/supportability by utilizing the integrated database to supply manufacturing and test data to design.*

### 3.8.2 Data Integration Solution

The RASSP database solution relies on a 'Virtual Product Model' that supports the integration of physically separate, existing data (files, relational databases, etc.) through the definition of a mapping between disciplines. Domain databases, such as the MIL-STD 1388-2B compliant logistics database, existing CAD databases, etc., will be logically married. Relationships will be represented through object-oriented classes and procedures utilizing the Information Resource Dictionary Standard (IRDS) for data modeling. Use of an object-oriented definition will allow data model extensibility and serve as a foundation for the RASSP design system. Figure 3.8-1 illustrates the multi-disciplines and their relationships.

In addition to the functional domains of design, manufacturing and logistics, program

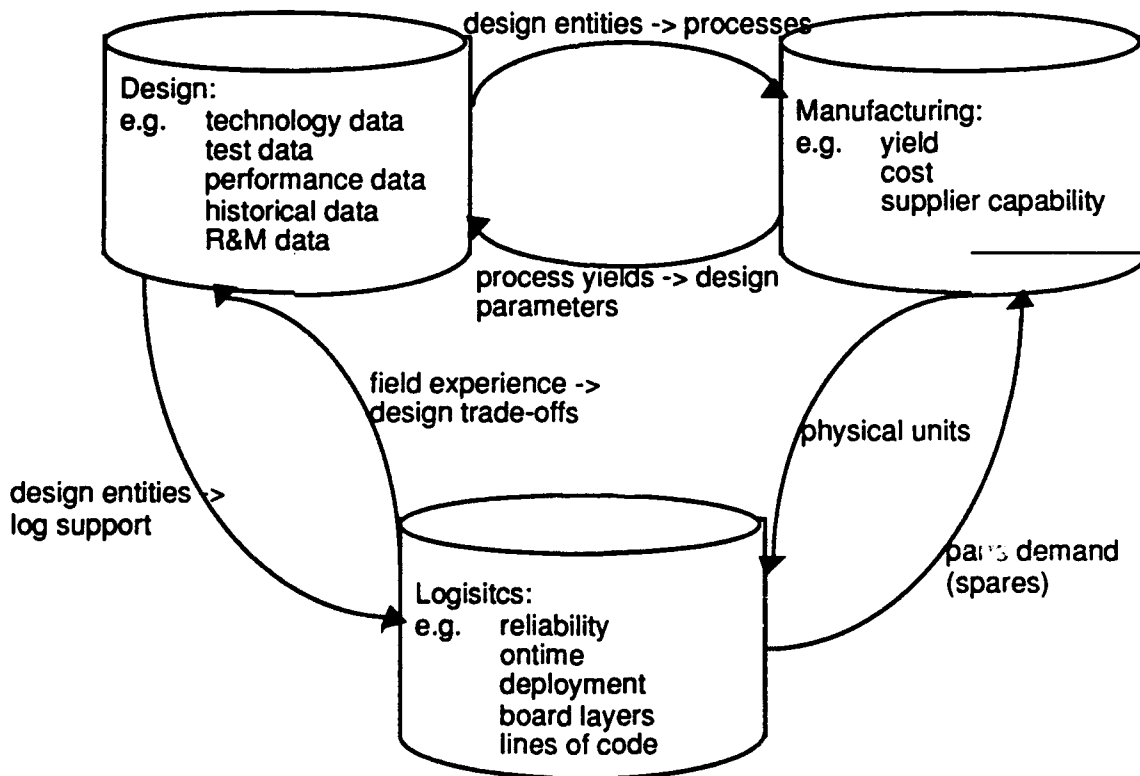


Figure 3.8-1, Domains to be Integrated

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management data such as schedule, cost, and risk factors will be collected and integrated with domain databases, allowing model year trade-off decisions to be quantified.

### 3.8.2.1 Data Model

The RASSP model year concept requires that the dynamics between design and activities that are typically downstream (i.e., manufacturing, logistics) be defined. Design decisions would be better understood with respect to life cycle cost if parameters such as manufacturing capabilities were available for consideration in trade-off analysis.

A mapping that will identify the relationship between the domains of design, manufacture and

### Design and Manufacturing

Raytheon has been researching the relationships between design and manufacturing for a number of years. In our transition to production software, printed wiring board design parameters are utilized to generate production packages, such as automated process plans. In our concurrent engineering workstation for board design, manufacturing parameters such as machining capabilities, cost and yield are quantified to determine manufacturing optimization. Further experience with MMIC technology supported research in the link between process and design success. Actual data is routinely examined, extrapolated and incorporated into more accurate design models. With expertise in this area, it is

| TO:       | Design                                     | Manufacturing                                      | Logistics  |
|-----------|--|--|--|
| FROM:     | (organized by physical features)           | (organized by manufacturing builds and operations) | (organized by field actions and events)            |
| Design    |  | map design parameters to manufacturing processes   | map design parameters to logistics support actions |
| MFG'ing   | map process yields to design parameters    |  |  |
| Logistics | map field experiences to design parameters |  |  |

**TABLE 3.8-2, MATRIX OF DOMAIN RELATIONSHIPS**

logistics must be determined. Each domain is governed by a different classification and organization of data based on use. Similar to the process and product views traditionally espoused, the design domain is organized by physical features often correlated to work breakdown structure. Manufacturing is governed by process, where data tends to be organized by manufacturing builds and operations. Finally, field support organizes data by field actions and events. A well thought out mapping will determine the translations among these data organizations. Table 3.8-2 defines the translations necessary to support the RASSP model year design system.

feasible that other technologies would leverage this capability for success. Refinement of closely correlated process parameters with design success should continue.

### Design and Logistics

The ability to utilize logistics data to support design for supportability will largely depend on research into design parameters and their effect on field support. A 1992 Raytheon proposal submitted to DICE Phase 5 (Logistics Analysis with Concurrent Engineering) explores the design entities to logistics support mapping. This area requires continued research.

Finally, further research must occur in the design/manufacturability versus

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design/supportability balance, which may have conflicting requirements. For example, a technology may be selected due to an ability to manufacture that technology with low manufacturing costs but may not be the most cost effective line replaceable unit, incurring large support costs.

Once the relationships among domains are determined, the relationship must be defined through the use of integration technology. Applications in the RASSP design system would access the virtual product database through a standard Application Programming Interface (API) call to the data dictionary. Visually, the system would be architected in the style of Figure 3.8-3.

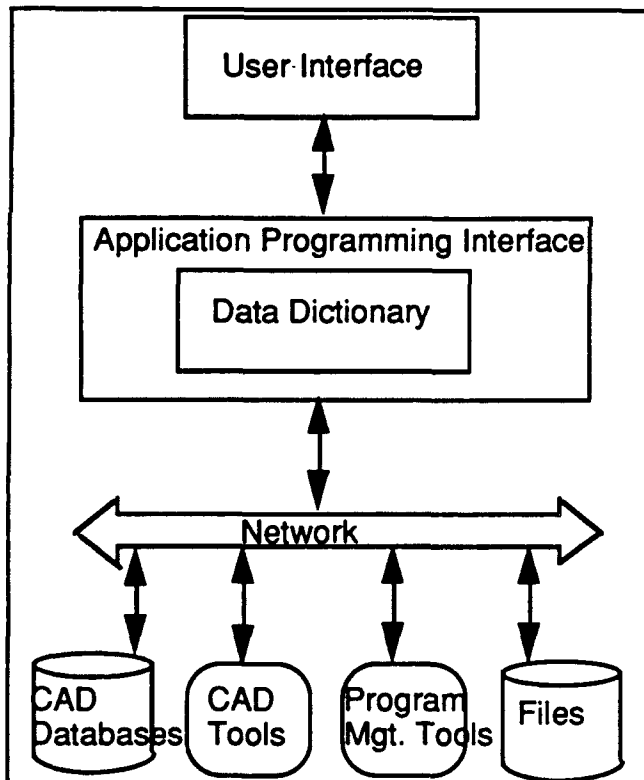


Figure 3.8-3, Data Access Architecture

Many activities in information integration are aggressively being pursued on both an academic and industry level. DoD research initiatives have been ongoing since the 1970's with the Air Force Information Integration Support System (I2S2)

program through today with the recent DICE Database Integration Platform For Concurrent Engineering. Industry activities are also prominent, such as the CALS Data Dictionary Task Force. Further, Raytheon's internal investigation of integration technologies in implementation of the Raytheon Integrated Technical Information Service (RITIS) has reviewed several commercial products for implementation of the data dictionary service. These products include integration technologies from HyperDesk, GRC, DEC, Information Builders, and Control Data Corp.. Products were reviewed based on their adherence to the Object Management Group (OMG) specification, which defines a standard API to distributed objects such as files, databases, and tools across heterogeneous hardware and software. The most promising product thus far has been the Distributed Object Management System, an object oriented data dictionary product from HyperDesk. Distributed Object Management System complies with the OMG API and supports a dynamic invocation interface allowing applications to construct requests and invoke them at run time. This dynamic distributed environment enhances the scalability and maximized performance. The HyperDesk Commercial Off The Shelf (COTS) product would be recommended for further investigation for data model implementation.

## 3.8.2.2 Standards

Standards play a significant role in the integration of data both within a single domain and among domains. Standards will be used to integrate and exchange data where available. The Standard for the Exchange of Product Model Data (STEP) is an international standardization activity, ISO 10303, to provide a digital form for representing and communicating product data throughout the life cycle of a product, independently from any application software that may be used to process it. STEP will be a multi-version standard, released as "parts" are defined. The first version of STEP is anticipated in Q4 1992 to include an

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application protocol for 3D Configuration Controlled Design (AP 203). Additional application protocols are being addressed by numerous industry and government funded activities, including the functional areas of Explicit Drafting, Associative Drafting, Mechanical Design using Boundary Representation.

As RASSP needs are evaluated, in the case that no standard expression for data exists, standards activities will be recommended. For example, the lack of a standard description of manufacturing models will hinder the goal of virtual manufacturing and brokering concepts. A STEP activity should be sponsored to address this area.

As databases migrate to STEP, the issue of integrating dissimilar data formats through the use of costly translators will diminish. The adoption of the STEP Data Access Interface (SDAI), now in committee, will standardize the interaction between applications and the STEP data model, thus simplifying the overall architecture of the design systems data access mechanism. Acceleration of the STEP standard both in the standard definition and in

implementation of the standard will simplify the database integration task.

Tools for developing and supporting STEP applications are now available commercially. There are at least five corporations now offering products or prototypes supporting STEP data model generation from EXPRESS. Raytheon has established ties with the two United States companies: STEP TOOLS, Inc., and Digital Equipment Corp. These relationships will play a key role in the implementation of the design system database solution.

While the STEP standard matures, dependency on alternative, existing standards and harmonization efforts will be paramount for an implementation maximizing portability and minimizing maintenance. An in depth understanding of the standards and their availability will be an ongoing challenge in the development of the RASSP design system. Figure 3.8-4 depicts a list of standards, current and future, that have been identified during the RASSP study phase as critical to implementation. The standards cover electrical and mechanical design, test, library formats, and technical data packages, as well as standard ways to communicate.

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Problems in using standards do exist. One common problem results from interpretation. To illustrate, consider the VHDL standard, where a single design can be represented in a number of ways. An attempt to address this standard problem is through the concept of the STEP Application Protocol that defines the context for the data model. A second limitation stems from overlap in multiple standards. In the case of VHDL and Verilog, both standards can be used to represent the same set of design data. The standard chosen is highly application dependent. Adoption and promulgation of standards represents yet another problem with the use of standards. Each of these limitations will be addressed through leverage from the industry and DoD initiatives in standard development and harmonization. The following activities should be supported:

- IGES/PDES Organization (IPO)
- CAD Framework Initiative (CFI)
- PDES/STEP Application Protocol -  
Electronics (PAP-E)
- IEEE VHDL and EDIF standardization activities

- Computer Aided Acquisition and Logistics Support (CALs) data exchange initiatives
- Microwave Hardware Design Language (MHDL) initiative
- VTEST
- Results of TISSS
- PDES, Inc.

### 3.8.3 Libraries

The RASSP model year concept relies heavily on the availability of libraries reflecting both current and projected capabilities. Through the use of libraries, the concept of reusability can be supported. An initiative within the CAD Framework Initiative (CFI) concerning Component Information Representation (CIR) is striving to develop a standard representation for electrical/electronic component information models and libraries. This type of activity is critical to the success of a library effort. Once a standard library format is adopted, applications accessing multi-vendor libraries of parts will become more prevalent and library development, support, and maintenance issues will be relieved from the RASSP design system.

| Q3 1992               | Q4 1992                                | 1993 - 1997                  | 20xx                |
|-----------------------|--|------------------------------|---------------------|
| VHDL                  | STEP V1 {AP203, Series 40, Series 100} | STEP V2 {AP204, AP205}       | STEP Vn {APxxx,...} |
| Verilog               | CFI/CIR Information Model Library      | CFI/CIR Electronic Data Book |                     |
| WAVES                 |  | TRSL                         |                     |
| IGES                  |  | FDL                          |                     |
| CCITT-G4              |  | CFI 2.0                      |                     |
| CGM                   |  |                              |                     |
| SGML                  |  |                              |                     |
| ANSI x.12 EDI         |  |                              |                     |
| CFI Pilot 1.0 (Draft) |  |                              |                     |
| ATLAS                 |  |                              |                     |
| EDIF                  |  |                              |                     |
| TEDL                  |  |                              |                     |
| RDL                   |  |                              |                     |

*Figure 3.8-4, Standards Timeline*



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Library solutions require a unique infrastructure to succeed, such as the ability to ensure integrity and quality of models. While library management presents challenges, the availability of libraries in a standard format is critical to support the model year goal of reusability.

Libraries are also required to purposefully share manufacturing models with the goal of virtual manufacturing. In order for a designer to understand what is feasible in model year, manufacturing models defining technology capability must be available. Even in the paradigm of a brokering system, manufacturing models would be required for accurate fabrication selection. Research during the RASSP Study Phase revealed a void in this area that should be corrected during the Implementation Phase. Clearly, a single, standard, model for all manufacturing technology is important to minimize integration efforts.

## 3.8.4 Risks/Issues/Recommended Research

Availability and fidelity of manufacture, test and field data under Model Year concept is uncertain. The model year concept forces projection of future manufacture and support capabilities. Alternative laboratory methods to produce accurate 'projected' (e.g., model year) models must be pursued. To further complicate the problem, as fewer systems are deployed, and the trend is that fewer will be manufactured, the availability of actual current data will also diminish. Developing close working relationships with vendors and research establishments to provide accurate current and 'projected' logistics and manufacturing data would be recommended as an activity for the Implementation Phase.

Developing standard library representations for performance models, functional models, reliability models, manufacturing process models are currently not being addressed under a unified standards organization and should be an area of investment under the RASSP program. Any progress made in this direction will add to the success of the RASSP program.

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## 3.9 Teaming Arrangements With Other Organizations

Teaming foundations can be established during the RASSP contract. Figure 3.9-1 clarifies the generic form of a RASSP program structure. In this diagram, the terminology is as follows.

- "Team Members" are partners in the program and contribute ideas to the program. They are not viewed as sub-contractors who are given a statement of work.
- The "Team Advisory Board" are senior representatives of the "Team Members" who meet on a regular basis to advise the "Prime Contractor(s)" of concerns, and their resolution.
- The "Industrial Review Board" is composed of representatives from a number of organizations interested in influencing the content and execution of the RASSP program. An alternative would be to have the IRB advise the "Program Manager."
- The "Design System Users" are interested parties who will have access to the design environment which is developed under RASSP, and will use the software for design work or evaluation.

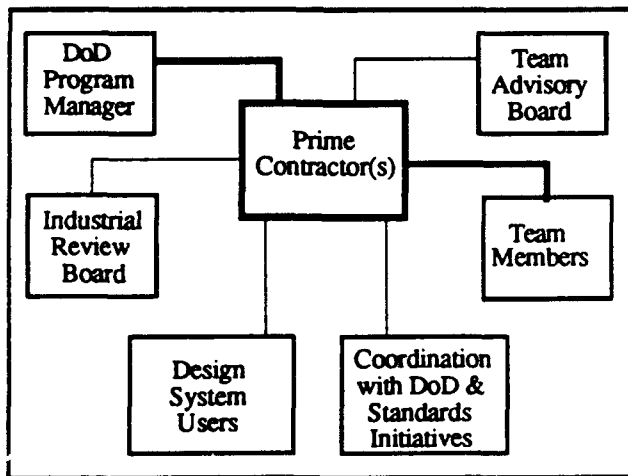


Figure 3.9-1, Teaming Organization Chart

Team members represent developers within:

- System Organization
- CAE/EDA Industry

- MCM/Board/Assembly/IC Manufacturers
- Universities

Typical CAx Vendor candidates are listed in the following Tables for reference:

|               |   |
|---------------|---|
| ASC           | VHDL test tool development                                    |
| Ascent Logic  | Requirements analysis & Traceability                          |
| Cadence       | Developed commercial framework, and commercialized MMIC tools |
| Cadre         | Developed commercial software design tools                    |
| Comdisco      | Developed commercial DSP tools                                |
| Dasys         | Developing commercial system partitioning tool                |
| DETEX         | Developed commercial test assessment tools                    |
| i-Logix       | Developed commercial system assessment tools                  |
| Interleaf     | Developed commercial product for software documentation       |
| Intermetrics  | Language development expertise, Ada compiler expertise        |
| JRS           | Processor and software synthesis and cross-compilers          |
| MCC           | Brokering, packaging and tool development                     |
| Mentor        | Developed commercial framework and DSP tools                  |
| Perceptronics | Process simulation tools                                      |
| Racal-Redac   | Developed commercial synthesis and physical design tools      |
| Synopsys      | Developed commercial synthesis tools                          |
| Teradyne      | Commercial testers and tester interface tools                 |

TABLE 3.9-2, CAx VENDOR CANDIDATES

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|                       |                 |
|-----------------------|-----------------|
| AT&T                  | MCM fabrication |
| Motorola              | MCM brokering   |
| n-Chip                | MCM technology  |
| NKT                   | MCM fabrication |
| Micro Modules Systems | MCM technology  |
| LSI Logic             | ASIC vendor     |
| TI                    | ASIC vendor     |
| VLSI                  | ASIC vendor     |
| Board Mfg             | Commercial      |

**TABLE 3.9-3, MANUFACTURER CANDIDATES**

|                   |  |
|-------------------|--|
| Univ. Cincinnati  | System partitioning and high level synthesis |
| Michigan State    | Logic partitioning and synthesis             |
| Mississippi State | VHDL Modeling                                |
| Univ. Virginia    | VHDL performance modeling, HW/SW co-design   |
| W. Virginia       | Concurrent engineering tools                 |

**TABLE 3.9-4, UNIVERSITY CANDIDATES**

Standards organizations provide a unifying effort within the industry for acceptance of standards. Industry members work together under project guidance of the organization.

|                    |   |
|--------------------|---|
| CALS               | DoD documentation standards   |
| CFI                | CAD framework database access and tool integration standards        |
| EDIF               | Schematic, netlist, physical design, and test interchange standards |
| IEEE               | VHDL, WAVES standards, modules, busses, packages                    |
| PDES Inc.          | Data modeling standards, STEP standard promotion                    |
| VHDL International | VHDL and WAVES standards  |

**TABLE 3.9-5, STANDARDS ORGANIZATIONS**

A typical example of industry cooperation and joint activities can be found in the activities of:

CAD FRAMEWORK INITIATIVE, Inc.  
403D W. Braker Lane  
Suite 550  
Austin, TX 78759  
Office (512) 338-3739  
FAX (512) 338-3853

Their experience to date has involved the entire EDA industry and has not only helped in obtaining consensus on standards, but also in selling capabilities to the user community.

Examples of these projects are:

**DAC '90 Integration Project**

- 22 EDA users and vendor company participants
- 28 applications sharing common procedural data access
- 9 month duration - completed on schedule

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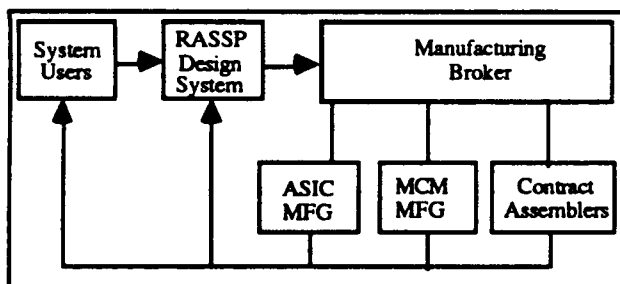
## CFI 1.0 Integration Project 1991

- 26 EDA users and vendor company participants
- 40 applications sharing common procedural data access and Inter-tool communication
- 9 month duration - completed on schedule

## CFI Pilot Projects 1992

- 4 Major Multi-Company Projects
  - HP, Cadence, mentor
  - IBM, Cadence
  - Sun, Viewlogic, Harris, Cadence, Synopsys
  - Siemens/Nixdorf, GMD
- CFI in role of Project Coordinator

This RASSP foundation for a teaming environment with DoD contractors providing the motivational system applications and program direction will initially create the environment for continuing teams. A generic team structure involving commercial ensuing organizations could take the form of Figure 3.9-6.



*Figure 3.9-6, Generic Team Structure*

The broker can be independent organizations matching industry capability to the system requirements or could be a unique organization within a major integrated circuit house or system house. An example of the later is represented in Figure 3.9-7 where Motorola is acting as a broker for MCM development under subcontract from Raytheon.

Major ASIC vendors that are also systems users are particularly driven towards development of team arrangements with the EDA industry. Texas Instruments and CADENCE, for example have a partnership to create tighter links between synthesis, floor planning and layout tools and users. TI will be installing ASIC workbench in its worldwide customer design centers. Its engineers will also work on-site at Cadence's San Jose facility to directly influence the development of an enhanced ASIC Workbench.

MCM manufacturers are taking steps to bring their capabilities to the system users through cooperative ventures with CAD framework houses. As a result Mentor Graphics Corporation has announced an MCM design kit for use with MCMs from MicroModule Systems (MMS, in Cupertino, California). The kit includes documentation, models and technology files with foundry-specific information. It works with mentor's MCM Station design system, which includes MCM layout and signal-integrity analysis.

These business liaisons will be further promoted as a result of the RASSP focus and the integration of CAD systems and manufacturers. CAD and device technology research can best be performed under Cooperative Research and Development Agreements (CRADA) with both industry and Government involvement. DoD Laboratories resources, expertise and project management offer a unifying force in coordinating multiple company activity.

Consortia of the form SEMATECH and MCC offer an opportunity for shared resources and specific projects resulting in shared benefits. It appears these activities will continue with varying degrees of success. While CRADA's and consortia have been primarily directed at technology developments among competitors in a specific business area, the RASSP focus is more on organizing the integration of unique industries into viable business entities.

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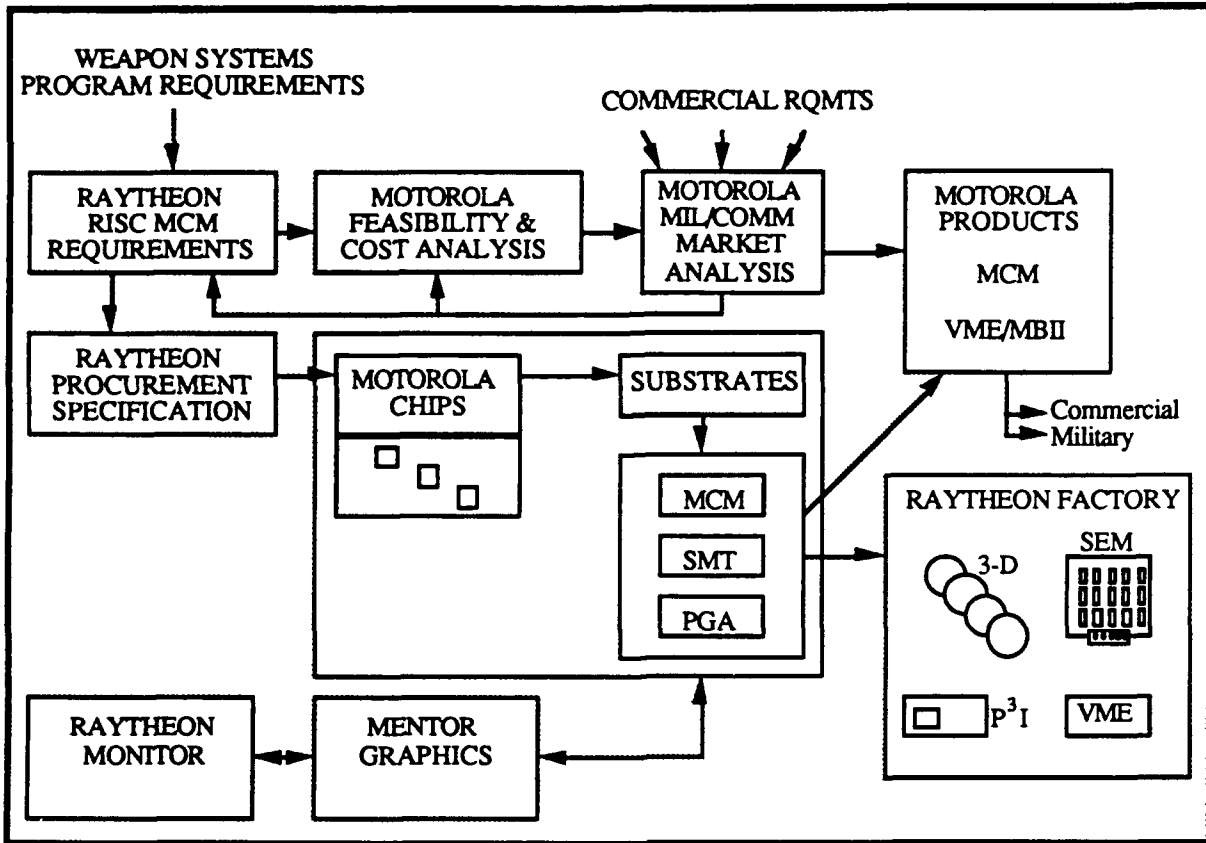
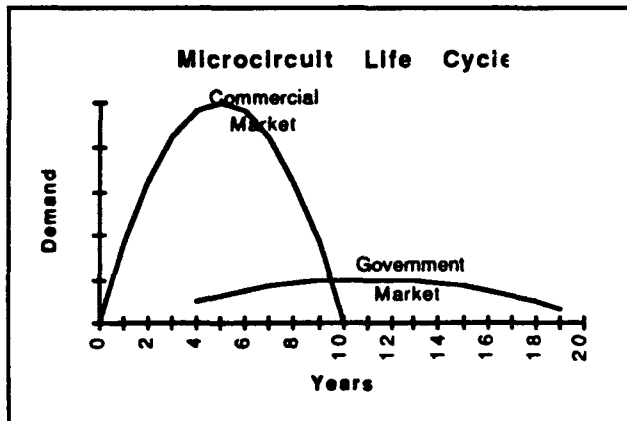


Figure 3.9-7, ASIC Vendor Acting As Broker

### 3.10 Establishment of Military Sources

*As the service lifetimes of defense electronics systems are extended, and the procurement of new systems is stretched out over longer periods of time, the already significant problem of finding suppliers for some of the key electronic assemblies of these systems is expected to worsen. Figure 3.10-1 illustrates the difference between military and commercial microcircuit life cycles. The Defense Logistics Initiatives Division (DLID) estimates that in the next 2 to 5 years, approximately 40,000 microcircuit designs will be susceptible to Diminishing Manufacturing Sources (DMS). The DLID estimates that the average cost to redesign systems around a substitute component is between \$150K and \$200K per instance. The RASSP Design-System and its associated product data models must be adopted by the user community, and be compatible with as many suppliers as possible in order to minimize the impact of this Diminishing Manufacturing Sources syndrome.*



*Figure 3.10-1, Typical Life Cycles For A Family of Microcircuits*

#### Major Issues

Establishing military sources for RASSP processors depends on two major issues. First of all, a majority of defense contractors must be adopt the RASSP design-system and its associated product data models. This will create

uniformity of design, simulation, concurrent engineering practices, and product data models among contractors. The collective efforts of RASSP contractors will create market demand which -- it is hoped -- will create sufficient business incentive for sources to commit to production of RASSP components and assemblies. Next, a traditional imposition of military specifications cannot be maintained. Where possible, military specifications should align more closely with international and commercial specifications. This will create dual-use components and assemblies thereby helping to ensure their availability with market-pull from both commercial and military industries.

#### Possible Solutions

Promulgation of the RASSP design-system and its associated product data models can be attained by providing the user community with access and involvement during the RASSP Implementation Phase. Access and involvement are key program elements in attaining the goal of widespread acceptance and use. Access to an operable system throughout the course of the development allows hands-on evaluation that benefits both the RASSP contractor and the industry user. Most major DoD contractors and commercial system houses invest each year in tool evaluation and in decisions to upgrade their CAE resources. If the program plan incorporates a phased development where block 1, 2, 3 are made available to industry at no cost, then the opportunities for interest, use and comments from the user community are greatly enhanced. A system could be made available on a network as well as on deliverable magnetic medium.

Block 1, 2, and 3 must make sense to the RASSP program and to the user community. Block 1 would result from the integration of available tools placed on available frameworks (Mentor, Cadence, Compass). Tools and standards would be strongly based on VHDL in its latest form(s). Block 2 would take advantage of on-going initiatives in commercial CAE, RASSP funded advanced development, DICE,

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MADE, MANTECH -- that fit the timeline. Full CFI standards would tie the system together. Block 3 would be the RASSP design system and incorporate suitable results of research activity and lessons learned from block 1 and 2. Raytheon anticipates that the user community would be proactive in their evaluation and perhaps propose additional projects for contract consideration. Maturing university research would also be transitioned into the block 3 system. Block 3 is obviously the commercialization baseline with the justifying econometrics being provided by increased user activity and system driven demonstrations. Block 3 addresses evolving technology and attempts to avoid the "generation gap" that often exists between mature/highly efficient CAE and the advanced hardware technology it addresses. An example of the last issue might be the CAE necessary to manage the "power and parasitics" of several hundred megacycle component interconnections.

Another might be the ability to use assessment tools within a framework when "look-ahead" or *ad hoc* CAE design/analysis tools are used for next generation product models (next model year interoperability issues). There are many exciting possibilities that will come from research of design systems, languages, and system test bed interfaces which can be placed within the Block 3 framework and be allowed to mature even beyond the RASSP contract.

Involvement requires a system of selectable assets for use by the industry. In Section 3.0, Figure 3.0-2 highlights the idea of a multi-dimensional design system structure. Essentially, the structure can be viewed as partitioned (perhaps virtually) into "functions" represented horizontally. Vertically, each function has a tool set, data types and standards that are not necessarily exclusive to the particular functional domain. The advantages of this structure are several. The military systems house, the commercial systems house, or the commercial CAE vendor can gain access to a

particular segment of interest without resorting to a complete resource commitment. For example, a commercial CAE developer may find an increasing market for assessment tools and decide to focus their investment strategy in this area. Many other combinations of business and development situations can be envisioned. The system's structural focus on standards and the way in which functions, tools, libraries, manufacturing resources and test bed interfaces communicate throughout the design process provides an excellent environment for evaluation of upgrades, and additional language constructs and translators. This data is also made available through networked bulletin boards to the user community for comment and to the standards committees for consideration and potential action.

Military specifications need to align more closely with international and commercial specifications. RASSP can be the ganglion attached to the DESC-JEDEC system, providing the focus and energy necessary to find a means of promoting use of commercial parts, prioritizing part specifications, providing advanced part (next generation) data, and facilitating procedural systems.

Use of commercial parts and standards has already begun with the current emphasis on commercial off-the-shelf procurement. In the past, DESC has purchased many commercial parts. However, most parts were procured without documentation packages. Now, DESC officials are encouraging non-government bodies to develop standards for certain commercial parts while DESC engineers develop Commercial Item Descriptions (CIDs) to cover commercial parts with no procurement documentation. As of July '92, 27 CIDs were in progress at DESC. As DESC creates more CIDs, more commercial parts will be available to contractors. The RASSP program can accelerate this process by identifying key commercial components, and initiating specification development activities with DESC.

In addition to identifying key commercial

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components, the RASSP program can prioritize parts specifications one product-generation ahead of the current system. This could be accomplished by using high level assessment tools and performance estimate data. Currently, DESC operates on a strict priority basis. They handle complaints and user recommendations at regularly scheduled document revisions. The RASSP program can use these existing channels to setup specifications required by MODEL YEAR development cycles.

DESC's manufacturer qualification provides a more economical qualification system for complex, small-volume custom parts with short life cycles and rapidly advancing technology that

requires extensive testing. In this qualification process, a manufacturing plant's procedures, materials, controls, design rules and tests are audited to ensure that a component coming off the line will meet military specifications and standards. DESC's Qualifications Division has 55 auditors who perform approximately 520 manufacturing plant and line audits per year. In the past two years, DESC has assembled a Qualified Manufacturers List (QML) that lists the manufacturers of advanced microcircuits and hybrids. Printed wiring boards will probably be the next category added to the list. The RASSP program can advise DESC on manufacturing plants critical to RASSP processors.



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## 3.11 Target Systems

*Raytheon has identified a broad range of Target Systems. The tables throughout this section list high-benefit candidates in RADAR, EW, SONAR and Missile applications. Automatic target recognition (ATR) as a class of problems is categorized as a major beneficiary of the RASSP design system. Development Test bed programs supporting ATR are identified and a relationship between RASSP and these concurrent resources are established.*

The general discussion of advantages of using RASSP in these systems includes the analyses of acquisition time lines. Typical acquisition time lines for the process of getting from concept to development contract and getting from contract

award to production contract are indicated below.

If this acquisition process is modeled after a RASSP Model Year situation where the design system has provided models to generic software test beds in the specific application area (or a target algorithm development test bed discussion later in this section). Then, the extended study/evaluation phases of the process can be reduced to a few months of evaluation. The generation of "next year's" Model Year would then be based on an interoperable upgrade and could be quickly assembled from hardware/software model libraries resident within the design system. After conceptual and architectural verification, assessment tools can be used to quickly provide cost/performance

| Month | Concept to Contract Award         | Contract Award to Production |
|-------|-----------------------------------|------------------------------|
|       | Activity                          | Activity                     |
| 1     | Concept                           | Contract Award               |
| 2     | White Paper                       |                              |
| 3     |                                   |                              |
| 4     | Evaluation/Funding authorization  | Preliminary Design Review    |
| 5     |                                   |                              |
| 6     |                                   |                              |
| 7     | Study Award                       | Proof of Design              |
| 8     | Trades/LCC/ROI/MTBF/Plan          | FAB Prototype                |
| 9     |                                   | Test                         |
| 10    | Report                            | Software Integration         |
| 11    |                                   |                              |
| 12    | Evaluation/Cost/Schedule          |                              |
| 13    |                                   | Critical Design Review       |
| 14    | Draft Engineering Change Proposal |                              |
| 15    |                                   |                              |
| 16    |                                   | Proof on Manufacture         |
| 17    |                                   | Rework                       |
| 18    | Fact Finding/Authorizations       | Procurement                  |
| 19    |                                   | Fabrication (Prod. Plant)    |
| 20    |                                   | Test                         |
| 21    |                                   | Qualification                |
| 22    |                                   |                              |
| 23    | Request for Proposal/BAFO         |                              |
| 24    | Final Engineering Change Proposal |                              |
| 25    |                                   | Subsystem/System Integration |
| 26    |                                   |                              |
| 27    | Evaluation/Selection              | System Test/Validation       |
| 28    |                                   | Formal Demonstration         |
| 29    |                                   |                              |
| 30    | Contract Award                    | Production Contract          |

**TABLE 3.11-1, HISTORICAL INSERTION TIMELINE**

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statistics. Logistics test beds can further be exercised to provide data necessary for the final contract decision based on a complete product data model. The typical separation of concept design and detail development/manufacturing is no longer necessary since both can be

totally overlapped. The manufacturing process is simulated prior to making a build decision. Manufacturing resources have been exercised through demonstration and continuing upgrades to databases. Their facilities have been previously qualified for RASSP processor technology.

An example of this integrated effort and its time line is indicated below. Obviously, each candidate system has its unique requirements, starting point, and complexity level that will significantly effect this timeline. Programmatic elements of budgets, priorities and planning will also control the activity flow. However, conceptually it is a new way to look at the acquisition process checks and balances issues.

Particularly important to the candidate target systems is the strawman design assessments that assure high payoff solutions of low risk. The power of the strawman approach is in the comparisons of quantitative data developed from the conceptual design simulation and analysis. Weakness in candidate approaches focuses necessary action. Advantages of point design over "standard" can be evaluated in terms of the overall program strategy. Data can be condensed through parameter comparison charts for weighting of factors and final decision by Program Management. The scope of the trade parameters to be analyzed can be uniquely defined for each program. Examples of trade parameters are listed in Table 3.11-3.

| <b>CONCEPT TO PRODUCTION</b> |   |
|------------------------------|---|
| <b>MONTH</b>                 | <b>ACTIVITY</b>   |
| 1                            | CONCEPT DESIGN<br>COMMENT AWARD                             |
| 2                            | REQUIREMENTS<br>DEVELOPMENT<br>FINALIZATION CONTRACT<br>BID |
| 3                            | REQUIREMENTS<br>VERIFICATION ON HIGH<br>LEVEL MODELS        |
| 4                            | STRAWMAN'S DESIGN<br>ASSESSMENTS                            |
| 5                            | DESIGN<br>SELECTION/VERIFICATION<br>ON TEST BEDS            |
| 6                            | DETAIL DESIGN   |
| 7                            | TRACEABLE<br>REQUIREMENTS<br>VERIFICATIONS                  |
| 8                            | DEVELOPMENT OF<br>PRODUCT DATA MODEL                        |
| 9                            | CRITICAL COMPONENT<br>BRASSBOARD<br>DEMONSTRATION           |
| 10                           | FINAL VERIFICATION  |
| 11                           | FINAL DOCUMENTATION &<br>REVIEW                             |
| 12                           | PRODUCTION RELEASE  |

**TABLE 3.11-2, RASSP INSERTION  
TIME LINE**

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| TRADE PARAMETERS |                                       |
|------------------|---------------------------------------|
| LCC              | TESTABILITY<br>COVERAGE               |
| UNIT COST        | MAINTAINABILITY<br>AND RELIABILITY    |
| NRE              | RISK<br>ASSESSMENTS-<br>COST/SCHEDULE |
| MTBF             | PRODUCIBILITY                         |
| SIZE/WEIGHT      | CHANGE<br>FLEXIBILITY                 |
| PROGRAM SIZE     | GROWTH                                |
| POWER            | COMMONALITY                           |
| # MODULE/TYPES   | PERFORMANCE<br>MARGINS                |
| # CHIPS/TYPES    | SUPPORT<br>SOFTWARE<br>AVAILABILITY   |

**TABLE 3.11-3, TRADE PARAMETERS**

## 3.11.1 Candidate Systems And Classes

Table 3.11-4 lists Raytheon systems that contain significant signal processing/processor technology. Table 3.11-5 provides a brief description of key programs that employ commercially based signal processing systems. The majority of the systems have had signal processor upgrades within the last five years, indicating a continuing pressure for increased performance. Recent programs, where commercial based processors have been incorporated, are identified and individually discussed in later paragraphs.

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| SYSTEM NAME                      | SERVICE/ AGENCY  | CONTRACT #   | STATUS      | Last Upgrade                 | AREA                   |
|----------------------------------|------------------|--|-------------|------------------------------|------------------------|
| GBR-T                            | ARMY/SDG         | DASG60-87-C-0014   | Awarded     | 1992                         | RADAR                  |
| TARTAR<br>BLK I, II, III         | NAVY/NSSC        | N00024-85-C-5507<br>N00024-87-C-5342<br>N00024-87-C-5501                     | Fielded     | 1987                         | ATR& ECM               |
| PAVE PAWS SITE I,<br>II, III, IV | AIRFORCE/ ESD    | F19628-76-C-0146<br>F19628-76-C-0146<br>F19628-84-C-0030<br>F19628-84-C-0030 | Fielded     | 1976<br>1976<br>1984<br>1984 | EW& ECM                |
| BMEWS I (THULE)                  | AIRFORCE/ ESD    | F19628-83-C-0113   | Fielded     | 1983                         | EW& ECM                |
| BMEWSIII<br>(FYL)                | AIRFORCE/ ESD    | F19628-88-C-0032   | Fielded     | 1988                         | EW& ECM                |
| COBRADANE                        | AIRFORCE/ ESD    | F1 9628-90-C-0070  | Fielded     | 1990                         | SIGINT & EW            |
| COBRAJUDY                        | AIRFORCE/ ESD    | F19628-79-C-0023   | Fielded     | 1979                         | SIGINT & EW            |
| WAAS                             | NAVY/S& NWSC     | N00039-78-C-0075   | Fielded     | 1984                         | EW                     |
| ROTHR                            | NAVY/S& NWSC     | N00039-90-C-0027   | EDM         | 1990                         | COMM & SIGINT &<br>ATR |
| SWOTHR                           | NAVY             | IDP 91D-236  | Proposed    | 1991                         | COMM& SIGINT           |
| TDWR                             | FAA              | DTFA01-89-C-00002  | Fielded     | 1989                         | ATR & COMM             |
| AEGIS                            | NAVY/NSSC        | N00024-90-C-5114   | Fielded     | 1990                         | ATR& ECM               |
| ASOP                             | AIR FORCE / RADC | F30602-84-C-0094   | Fielded     | 1987                         | SPACE& EW& ECM         |
| SEA-SPARROW                      | NAVY/NSSC        | N00024-89-C-5112   | Fielded     | 1987                         | ATR& ECM               |
| RTWP                             | ARMY/ SDC        | DASG60-88-C-0064   | IN PROGRESS | 1988                         | SPACE                  |
| MILSTAR                          | AIRFORCE/ ESD    | F1628-85-C-0004  | EDM         | 1989                         | SPACE & COMM           |
| NESP                             | NAVY/S & NWSC    | N00039-82-C-0146   | EDM         | 1990                         | SPACE & COMM           |
| COBRADANE                        | AIR FORCE/ ESD   | F19628-90-C-0070   | Integration | 1990                         | SIGINT                 |
| SPS-49                           | NAVY/NSSC        | N00024-89-C-561 8  | In Process  | 1990                         | ATR & ECM              |
| GPS                              | USAF/ ASD        | F08630-91-C-0053   | In Process  | 1991                         | SPACE                  |
| IATC                             | FAA              | 1DP 91D-213  | In Process  | 1992                         | ATR                    |
| MMIC                             | NAVY/NASC        | N00019-91-C-0210   | Fielded     | 1991                         | ECM& SIGINT            |
| BSTS                             | AIRFORCE / SSD   | F04701-87-C-0023   | Fielded     | 1987                         | SPACE                  |
| RAMP                             | CANADIAN GOVT    | P005-2400 AF21 125   | Fielded     | 1984                         | ATC                    |
| CART                             | AIR FORCE/ RADC  | F30602-88-C-0080   | Fielded     | 1988                         | ECM& SIGINT            |
| D3 FIRE CONTROL                  | ARMY/ AMMCCOM    | DAAA21 -88-C-0025  | Fielded     | 1988                         | EMGWS                  |
| AAS                              | FAA              | 135076, 475475   | Fielded     | 1989                         | ATC                    |
| CCS MK2 CDC                      | NAVY/NSSC        | N00024-88-C-6067   | Fielded     | 1989                         | ATC                    |

**TABLE 3.11-4, RAYTHEON'S RELEVANT SIGNAL PROCESSING PROGRAMS**

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|  |                 |                                      |                           |        |  |
|--|-----------------|--------------------------------------|---------------------------|--------|--|
| MIDWAVE LASER RADAR                              | NAVY            | --                                   | Prototype                 | 1991   | ECM                                      |
| BANSHEE  | ARMY            | --                                   | Prototype                 | 1989   | ECM                                      |
| NOVEL RECEIVER/DSP                               | AIRFORCE & NAVY | --                                   | Prototype                 | 1986   | ECM                                      |
| ALQ-184 CORRELATION PROCESSOR                    | AIRFORCE        | --                                   | Prototype                 | 1992   | ECM                                      |
| BRVAD  | BMO             | F04704-87-C-0116                     | EDM                       | 1988   | PENAIDS                                  |
| MATES  | NAVY            | PROPOSAL                             | Proposed                  | 1992   | ECM                                      |
| DIGITAL RECIEVER                                 | AIRFORCE/NAVY   | --                                   | Prototype                 | NEW    | SPACE/ COM/ EW                           |
| SLQ 32/54 ETU                                    | NAVY            | --                                   | Prototype                 | 1992   | ESM                                      |
| MDOT   | NAVY            | F33615-90-C-1433                     | ADM                       | 1992   | ECM                                      |
| Mine Hunting Sonar AN/AQS-20                     | NAVY            | N00019-91-R-0021<br>N00019-92-G-0072 | ADM/EDM                   | 1991   | Sonar Detection and classification       |
| Kingfisher Avoidance for AN/SQS-26, 56           | NAVY            | N00024-88-G-6051<br>N00024-90-G-6079 | ADM/EDM                   | 1990   | Sonar Detection and classification       |
| Shore-Based Trainer for AN/SQQ-32                | NAVY            | N00024-89-C-6115                     | ADM/EDM                   | 1990 - | Sonar,- Simulation and Stimulation       |
| International Sonar System                       | Raytheon        | IR&D                                 | ADM/EDM                   | 1991   | Sonar Detection and classification       |
| Team Trainer for AN/BSY-2                        | NAVY            | N00024-91-C-6505                     | ADM/EDM                   | 1991   | Sonar,- Simulation and Stimulation       |
| Acoustic Intercept System                        | NAVY            | N00019-89-R-0101                     | Proposed                  | 1992   | Sonar Detection and classification       |
| Transient Signal Processor                       | Raytheon        | IR&D                                 | Fielded                   | 1990   | Sonar Detection and classification       |
| Trident Sonar Processor JHU/APL analyzer (TSPAN) | NAVY            | N00039-87-C-5301                     | Fielded                   | 1997   | Sonar; Detection and Classification      |
| Trident Shore-Based Maintenance Trainer          | NAVY            | N66604-86-C-0136                     | Fielded                   | 1987   | Sonar; Simulation and Stimulation        |
| On-Board Trainer for AN/SQQ-89                   | NAVY            | N00024-85-C-6132<br>N00039-89-R-0015 | Fielded                   | 1986   | Sonar; Simulation and Stimulation        |
| Multipurpose Console AN/BSY-1                    | NAVY            | IBM P.O. 289664<br>IBM P.O. 270165   | Fielded                   | 1983   | Sonar; Comm. and Navigation              |
| Mine Hunting Sonar AN/SQQ-32                     | NAVY            | N00024-82-C-6242<br>N00024-89-C-6115 | Fielded                   | 1981   | Sonar, Detection and Communication       |
| Millimeter-Wave Attack Seeker                    | AIRFORCE        | Internal Development                 | Demonstration/ Validation | 1991-2 | Air to Air Missiles                      |
| AMRAAM   | AIRFORCE        | CONTRACT                             | Production                | 1989   | Air to Air Missiles                      |
| VHSIC Signal Processor                           | MICOM           | Internal Development                 | Proof of Principle        | 1990   | Ground-based radar, Missile Applications |
| AEGIS-ER BLK II, III, IV                         | NAVY            | N00024-87-C-5321                     | Production                | 1989   | Surface to Air Missiles                  |
| Patriot Multi-mode Seeker                        | ARMY            | CONTRACT                             | Flight Program            | 1987   | Missiles                                 |
| AAAM   | NAVY            | N00019-88-C-0152                     | DEM/VAL                   | 1989   | Missiles                                 |
| Sparrow 7R (MHIP)                                | NAVAIR          | CONTRACT                             | Production                | 1989   | Missiles                                 |
| Maverick   | AIRFORCE        | CONTRACT                             | Fielded                   | 1987   | Air to Air Missiles                      |
| Patriot Air Defense                              | ARMY            | CONTRACT                             | Fielded                   | 1989   | ATR, Radar                               |
| ASARG  | --              | --                                   | Prototype                 | 1991   | ATR                                      |

**TABLE 3.11-4 CONTINUED, RAYTHEON'S RELEVANT SIGNAL PROCESSING PROGRAMS**

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|  |  |
|--|--|
| <p><b>Airport Surveillance Radar (92D-213)</b> -- A 5-band ASR system using off-the-shelf components for the signal processor. Range 60nm / altitude 23,000 ft with dual redundant channels. Signal and data processor will utilize the Low Overhead Array Processor (LOAP) card developed by Raytheon and COTS SBCs. The LOAP boards are based on Motorola's DSP96002 chips with a VME interface.</p>   | <p><b>Architecture and Critical Technologies for New Generation IFF System (92D-218)</b> A brassboard digital signal processor to implement spread spectrum waveform processing (Mark X, Mode 4, Mode 7, Mode 8., etc). Fabricate and demonstrate this monopulse processor using a VHSIC chip set in 0.9 micron HMOS technology.</p>   |
| <p><b>Key Components for Surface Wave OTH Radar (92D-236)</b> -- The technology needed to build a ship based Prototype HF surface wave OTH radar. Hardware includes a DEC 4000 workstation and a MASPAR parallel processor. New functions to be added this year include digital beamforming and data and signal processing, detection and tracking.</p>  | <p><b>Transient signal Processor</b> -- This IR&amp;D processor used commercial VME 6U product to build a test bed for prototype algorithm development that also had the flexibility for at-sea trials. We continue to upgrade this system with newer versions of the signal processor board products.</p>   |
| <p><b>Fault Tolerant Processors for Space Applications (92D-343)</b> -- Design, develop and test, fault tolerant general purpose scalar and vector processing architectures and implementation technologies to meet the demands of space based processors. Specify and develop the design concepts for applying these fault tolerant design concepts to a RU3000 and RH -32 chip set based design. The signal processing and data reduction (detection processing) function requiring 730 M bits of memory and 3.5 GOPS of 32-bit scalar throughput.</p>   | <p><b>Miniature GPS Receiver and Inertial Navigation System (92D-345)</b> -- The six channel Global Positioning System (GPS) signal processor can acquire and track up to six satellites on CIA code, P-code, or Y-code. The data processor is for the miniature GPS receiver (MGR) processor. the NAV processor and the adaptable interface unit The TMS320C30 or TMS320C40 has been selected for this processor. Software to run on this processor chip will be written in Ada using the Tartan design Ada support software environment.</p>   |
| <p><b>Advanced Automation System/Sector Suite, Contract #135076 and 475475</b> -- Issued by IBM for FAA Air Traffic Control. Raytheon developed a workstation common console which includes a 2048 x 2048 roster display controller that drives a Sony 20" x 20" color monitor. The display controller used a commercial digital signal processor, an AT&amp;T DSP32C. The DSP provides 10 COPS and operates as a geometry engine for the display.</p>   | <p><b>Follow on Early Warning System (FEWS) Contract #F040701-85-R-002</b> -- Issued by Grumman Space Systems Division, for USAF. applies to both militarized commercial and custom designed architectures. Signal processing is performed by the Detection processor and with the Vector processor. Some commercial processing resources used on BSTS are Scalar processors (1750A for BSTS and 32 bit RISC for FEWSO and PI-Bus for BSTS).</p>   |
| <p><b>Real Time Waveform Processor (RTWP) Contract #DASG60-88-C-0064</b> -- The RTWP is a programmable digital signal processor that can be integrated into an SDI radar. The major result of the program is producing a Stand Alone Correlator Assembly, utilized for pulse compression, that is capable of greater than 4 terra-ops in performing either correlations or FIR filtering. It is based on Residue Number System (RNS) custom IC's produced by Raytheon that are capable of operating at the system bed of 62MHz.</p>  | <p><b>MIDWAVE LASER RADAR</b> -- The system utilizes commercial grade AT&amp;T's DSP32C and DSP16A, Array Microsystem's HD5P66111, Plessy's PSDP16330A, and IDT's 7381 processors and ALUs for implementing a real time digital receiver. This processor is capable of computing FFTs, and data correlation, extracting the range and Doppler information, and performing signature analysis. It operates in a 250MHz Doppler bandwidth for IR missile detection.</p>  |
| <p><b>Processing System Designs Using Open Architecture Interconnect Standards (92D-256)</b> -- Design, integration, test and demonstration of the industry's first Futurebus+ based multiprocessor system and integration of a commercial off the shelf operating system (UNIX or POSIX). Ada run-time software with the Futurebus+ system. The system contains high performance processors (R3000, 68040), memory, standard 110 channels (NTDS Fast, 15530, and SAFENET II), SCSI disk interface with file management software, a Bus monitor interface, and a VME Bridge interface. Raytheon continues to play a major role in the technical development of the Futurebus+ standards within the IEEE committee, including leadership of an Expert committee at the IEEE's request DoD has identified the commercial IEEE 896 Futurebus as a basis for future high performance systems. SAFENET II LAN technology based upon the broadly supported commercial ANSI X3T9.5 fiber distributed data interface (FDDI) is also being supported on this project.</p> | <p><b>Patriot Enhancements, Digital Signal Processor IR&amp;D (92D-133)</b> -- A major re-engineering effort is being undertaken to design a replacement digital signal processor for the PATRIOT system. In addition to supporting all existing functional modes within strict time-lines. Given the extended development cycle times associated with bringing a new subsystem from concept to a fielded production unit, it is imperative that this IDP leverage off the latest commercial trends, including working closely with leading edge microprocessor, DSP, memory, and semiconductor organizations, to ensure that a product developed in the 1992 to 1995 frame provides a competitive solution for production in the year 2000.</p> |

**TABLE 3.11-5, COMMERCIAL-BASED SIGNAL PROCESSOR PROGRAMS**

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|  |   |
|--|---|
| <p><b>Next Generation Computer Resources (NGCR), Contract # N00039-90-C-0085</b> -- For U.S NAVY SPAWAR. NCGR is an ongoing development program to develop open computer resource standards for use in the mid 90's and beyond (i.e. Futurebus+, two different ISA's, SAFENET LAN interfaces, etc...). Raytheon is applying the IEEE Futurebus+ standard a VME based circuit card assembly and bridge connections to the Futurebus+ backplane. Raytheon has selected the military VAX, based on a widely used commercial processor engine, to demonstrate the evolution of a proprietary architecture commercial product to the evolving open architecture philosophy. The second ISA processor selected was the MIPS R3000</p>      | <p><b>SLQ-32/54 Emitter Tracking Unit (ETU)</b> -- The ETU employs multiple, commercially available embedded processors to detect, identify and track emitters across the microwave bands. A 32-bit digital signal processor (TMS320C30 DSP) provides detection capability for emitters in dense signal environments of up to three(3) million pulses per second. Redundant, distributed 32-bit CISC processors (M68040) provided identification and tracking of more than 500 emitters for both ESM and ECM systems. An industry standard VME bus interconnects all processing functions to allow insertion of future enhancements hardware and Ada provides easy transportability of applications software.</p> |
| <p><b>Next Generation Air Traffic Control system (92D-206)</b> -- This is an air traffic control system which will process and display position information in the form of digitized raw radar data, digitized extracted data and global positioning system (GPS) reports. Incorporates state of the art low cost commercial computers and software hosted on a UNIX SV R4 operating system employs the Motorola Delta system.</p>   | <p><b>CCS Mk 2, Common Display Console CDC, Contract # N00024-88-C-6067</b> -- For the Naval Systems Command. Each CDC graphics function includes two circuit cards; a graphics processor and a graphics generator interconnected on a VME-bus features the Silicon Graphics custom ASIC chip (Geometry Engine) providing 20 MFLOPS capacity and a Weitek 3132 floating-point processor</p>   |
| <p><b>DIGITAL RECEIVER</b> -- A broad band digital receiver is being developed using commercial grade A/D converters, memory and DSP chips for demonstrating over 1-GHz of bandwidth with 60dB of dynamic range for applications in radar and ESM. Industrial partners such as TRW and Honeywell are supporting this effort.</p>   | <p><b>Kingfisher Avoidance for AN/SQS-26, 56</b> -- Uses commercial VME 6U DSP (i860) boards for signal processors. We combine these with the Navy's processor suite to provide a solution that ties into the existing AN/SQS-56 systems, using their sonar for data acquisition and augmenting their performance with the new object avoidance capability.</p>   |
| <p><b>Team Trainer for AN/BSY-2</b> -- The trainer for the AN/BSY-2 simulates and stimulates real operational hardware at a shore-based training site. We have used commercial technology to attain 20 GFLOPS of high performance signal processing. The equipment also emulates the functions of a military standard signal processor, the EMSP, in the AN/BSY-2 system.</p>  | <p><b>Shore-Based Trainer for AN/SQQ-32</b> -- This contract used the commercial technology from the AN/BSY-2 Team Trainer for a shore-based trainer for the AN/SQQ-32 mine hunting system now in production. VME 6U and 9U signal processor products were used. The portability of software and the tendency of the commercial world to preserve" upward compatibility in the product line made this possible.</p>   |
| <p><b>International Sonar System (ISS) IR&amp;D</b> -- This internal development was formulated to provide the basis for a building-block approach for common use in a number of US and international systems. To meet full military performance requirements, we selected VME format 6U boards with conduction cooling, largely because of the availability from multiple sources of commercial product in this format. We have developed a signal processor board (i860-based), a board for fiber optics interface for high speed data I/O, and an approach to a dual synchronous bus for the backplane routing of high speed data. We are exploring cross licensing agreements with the commercial vendors for their product.</p> | <p><b>Mine Hunting Sonar for AN/AQS-20</b> -- Raytheon recently won this highly competitive procurement contract for a helicopter-towed sonar for mine hunting, comprised of signal processing electronics both in the towed body and the helicopter. We use the signal processing building blocks from Raytheon's IR&amp;D development together with commercially purchased VME 6U products for the CPU, memory, and I/O. The success of our approach demonstrates that NDI and COTS solutions are cost effective for full military environments. For the shore-based portion, we used the equivalent equipment in their commercial form, preserving full compatibility with additional cost savings.</p>        |
| <p><b>ALQ-184 CORRELATION PROCESSOR</b> -- A new processor was developed for pulse repetition interval analysis of multiple emitters with patterned or steady pulse repetition intervals. Commercial grade Texas-Instruments TMS320 DSP chips were used to implement and flight-test the processor.</p>  | <p><b>BANSHEE</b> -- Commercial dual FFT processors were used in a flight test and radar range tests. The overall digital receiver is capable of real time computing pulse repetition frequency, angle of arrival and frequency of the emitter for high sensitivity radar altimeter detection.</p>  |

**TABLE 3.11-5 CONTINUED, COMMERCIAL-BASED SIGNAL PROCESSOR PROGRAMS**

Many of these candidate systems are good demonstration vehicles for the RASSP program and offer opportunities for image performance and cost improvements within the weapon

system. Screening of these systems has resulted in a reduced but still large set of leading candidates. Here they are organized by business area within Raytheon's government group.

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- **Equipment Division**
  - GBR Ground Based Radar - Army
  - AN/SPS-49 Long Range Surveillance Radar - Navy
  
- **Submarine Signal Division**
  - CCS MK-2 Submarine Combat Control System - Navy
  - AN/SQS-32 Mine Hunting Sonar - Navy
  - AN/AQS-20 Mine Hunting Sonar - Navy
  
- **Electromagnetic Systems Division**
  - AN/ALQ-184 Electronic Countermeasures - AF
  - AN/SLQ-32/SLQ-54 Electronic Countermeasures - Navy
  
- **Missile Systems Division**
  - Missiles -- Army, Navy, Air Force
  - Patriot -- Air Defense System - Army
  - CORPSAM -- Air Defense System - Army
  - EMR -- Electronic Combat Multifunction Radar - AF
  - ASAP -- Airborne Shared Aperture Program - Navy

candidates. They are in the process of upgrades and the growth of signal processing has been explosive. Characteristics of the missile seeker processor technology are itemized here:

- Desired Processing Capability Typically exceeds Volume Constraint
  - Throughput Has Grown From 0.5 MOPS (Sparrow 7M) to 3000 MOPS (ASARG)
  - Continued Growth:
- **Processors**
    - Absorbing Former Analog Functions
    - Scale With Technology
    - Scale With Missile volume
    - Support Maturing of Algorithms
    - Interoperable with Missile Sensor and Guidance Subsystems

The expansiveness of the missile seeker processing functions places demands on algorithms, architecture and Software. A typical set of algorithms/functions partitioned by processor architecture demonstrates the complexity level of the issues to be resolved by a RASSP design system providing Model Year processors.

### 3.11.2 Missile Systems Candidates

The missile systems are particularly interesting

| THREATS   | SENSORS          | ALGORITHMS      |
|-----------|------------------|-----------------|
| SMART ECM | PHASED ARR       | ADAPTIVE        |
| NTCR/ATR  | STARING<br>LAYER | IMAGING         |
| STEALTH   | DUAL IR/         | FUSION          |
|           | IR/EO/MMW        | KNOWLEDGE BASED |

**TABLE 3.11-6, GROWTH OF PRODUCT FUNCTIONALITY**



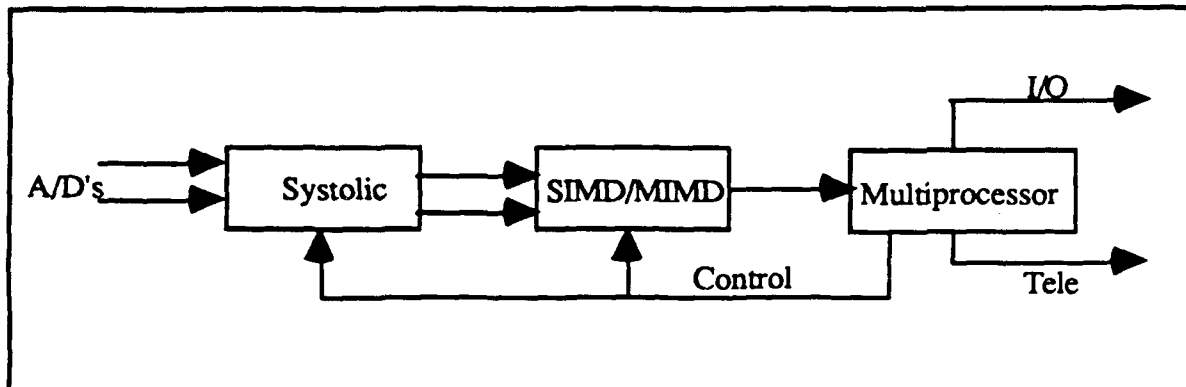
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| ARCHITECTURE        | TYPICAL FUNCTIONS                    | ARCHITECTURE       |
|---------------------|--------------------------------------|--------------------|
| SYSTOLIC ARRAY      | DECIMATING FILTERS                   | PARALLEL SIMD/MIMD |
|                     | ADAPTIVE BEAMFORMING                 |                    |
|                     | PULSE COMPRESSION                    |                    |
|                     | ADAPTIVE CHANNEL EQUALIZATION        |                    |
|                     | ADAPTIVE NULLING                     |                    |
|                     | WEIGHT GENERATION                    |                    |
|                     | WAVEFORM DECODING                    |                    |
|                     | ADAPTIVE DATA EXTRAPOLATION          |                    |
|                     | DOPPLER FILTERING                    |                    |
|                     | ADAPTIVE CLUTTER REJECTION           |                    |
|                     | MAGNITUDE DETECTION                  |                    |
|                     | POST DETECTION INTEGRATION           |                    |
|                     | THRESHOLDING                         |                    |
|                     | CONSTANT FALSE ALARM RATE            |                    |
| TARGET DETECT       |                                      |                    |
| RISC MULTIPROCESSOR | TARGET IDENTIFICATION/CLASSIFICATION |                    |
|                     | DATA FUSION                          |                    |
|                     | TARGET TRACK                         |                    |
|                     | AUTO PILOT/HEAD CONTROL              |                    |
|                     | GUIDANCE                             |                    |
|                     | ECCM LOGIC                           |                    |

**TABLE 3.11-7, MISSILE PROCESSING ALGORITHMS**

The current generation of processors in this area relies heavily on commercial based technology in the DSP and microprocessor area. Typical devices, architecture and interconnect structures are identified below.

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| PROCESSING ELEMENT (PE) | PIPELINED ALU            | DSP                         | MICRO-PROCESSOR   |
|-------------------------|--------------------------|-----------------------------|---|
| TYPICAL PE              | FIR OR CMAC              | TMS320C40                   | 88000 RISC  |
| PE INTERCONNECT         | 1D OR 2D                 | 2D                          | MP BUS  |
| INPUT/OUTPUT            | DIRECT MINIMAL BUFFERING | ROW AND COLUMN FRAME BUFFER | FIFO BUFFERED BUSSES<br>MULTIPROCESSOR<br>- TELEMETRY<br>- I/O<br>- CONTROL |

## 3.11-8, MISSILE PROCESSING ARCHITECTURE

Leading candidates within this category are systems demanding advanced technology and the ability to stay state-of-the-art in a cost effective fashion. These systems are:

### Millimeter Wave:

- Autonomous Synthetic Aperture Radar Guidance (ASARG) - AF
- Joint Direct Attack Munitions (JDAM) - AF/Navy
- Advanced Kinetic Energy Missile (ADKEM) - Army

### Infrared Imaging:

- Sidewind AIM-9X - AF

### RF/IR Dual Mode

- Advanced Sparrow
- Standard Missile (SM-2) Block IIIB - Navy

Each of these systems also has significant ATR functions and is currently have test beds in the form of capture flight configurations, hardware-in-the-loop (HIL) facilities, laboratory evaluation test beds and/or software simulation/analysis test beds. The ATR functions are at various levels of complexity as itemized below.

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| TARGET SYSTEM          | AUTOMATIC TARGET RECOGNITION (ATR) FUNCTION   |
|------------------------|---|
| ASARG JDAM<br>TOMAHAWK | AIR-TO-GROUND SYNTHETIC APERTURE IMAGING OF FIXED, RE LOCATABLE, NAVIGATION POINTS          |
| AIM-9X                 | AIR TO GROUND LOW CONTRAST SMALL TARGET DETECTION, IMAGING AND TERMINAL AIM POINT SELECTION |
| ADVANCED SPARROW       | SEA-SKIMMER AND CRUISE MISSILE MULTI SPECTRAL DATA FUSION AND CENTROID TRACKING             |
| ADKEM                  | ANTI-TANK, ANTI-AIR HIT TO KILL RECOGNITION AND AIMPOINT SELECTION                          |
| SM-2 IIIB              | DATA FUSION AND CENTROID TRACKING   |

### 3.11-9, MISSILE ATR FUNCTIONS

#### 3.11.3 ATR Category

In many ways, the RASSP effort during 1993-1997 can provide maximum benefits to concurrent development efforts in related processing/processor initiatives. In the automatic target recognition "class of problem," there are several programs which result in test beds for evaluation of future system technology. Future ATR processing technology includes high resolution signal conditioning for STARING/SCANNING IR arrays, FLIRS, EO Sensors, and wide band width RF waveforms. In some cases, data fusion techniques are applied and further augmented with acoustic sensors and links to queuing systems. Neural networks, wavelet transforms, model based vision advanced techniques are included in the broad and growing set of algorithms originally dominated by direct correlation and statistical pattern recognition.

Some of the concurrent developmental efforts underway with their related programs are listed below.

- **Advanced Land Combat Vehicle Technology (ALCVT) - DARPA**  
Multi-sensor Feature Level Fusion (MSFF)  
BIT/DARPA/ARDEC D-3 Fire Control Program

- **SCVision Research - DARPA**  
Smart Weapons Test Bed NGS
- **Air Target Algorithm Development Test Bed - AF**  
Advanced Digital Radar Imagery Exploitation (ADRIES)  
Sensor Algorithm Research Export System (SARES)  
Multi attribute ID Analysis (MAIDA)  
Intra Radar Aircraft Signature Fusion  
Air to Air Covert Sensor Technology  
Ultra High Range Resolution (ARTI)
- **Multi-Sensor Aided Targeting-Air (MSAT) - Army**  
Advanced Air Defense Elector-Optics System

These programs are representatives of a widely supported methodology in the evaluation of ATR systems/sensors and processors. Generally, these evaluation systems start as pure software emulators where models, libraries, algorithms, and assessment tools are brought together on high performance workstations employing parallel processing techniques. A massively parallel processing computer can be incorporated when data base/test vector sets grow large. Sensors and emulation hardware and then added

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and eventually test bed platforms suitable for fielded operation are developed. The RASSP design system can provide both software models of candidate processors and later rapid turn around demonstration hardware. The use of high performance workstations and massively parallel processors in these developments provide a

sound basis for transitioning to Model Year signal processors.

The conceptual partitioning of the software test bed for the Air Target Algorithm Development system is presented below. RASSP processor models can be built for all or part of the system.

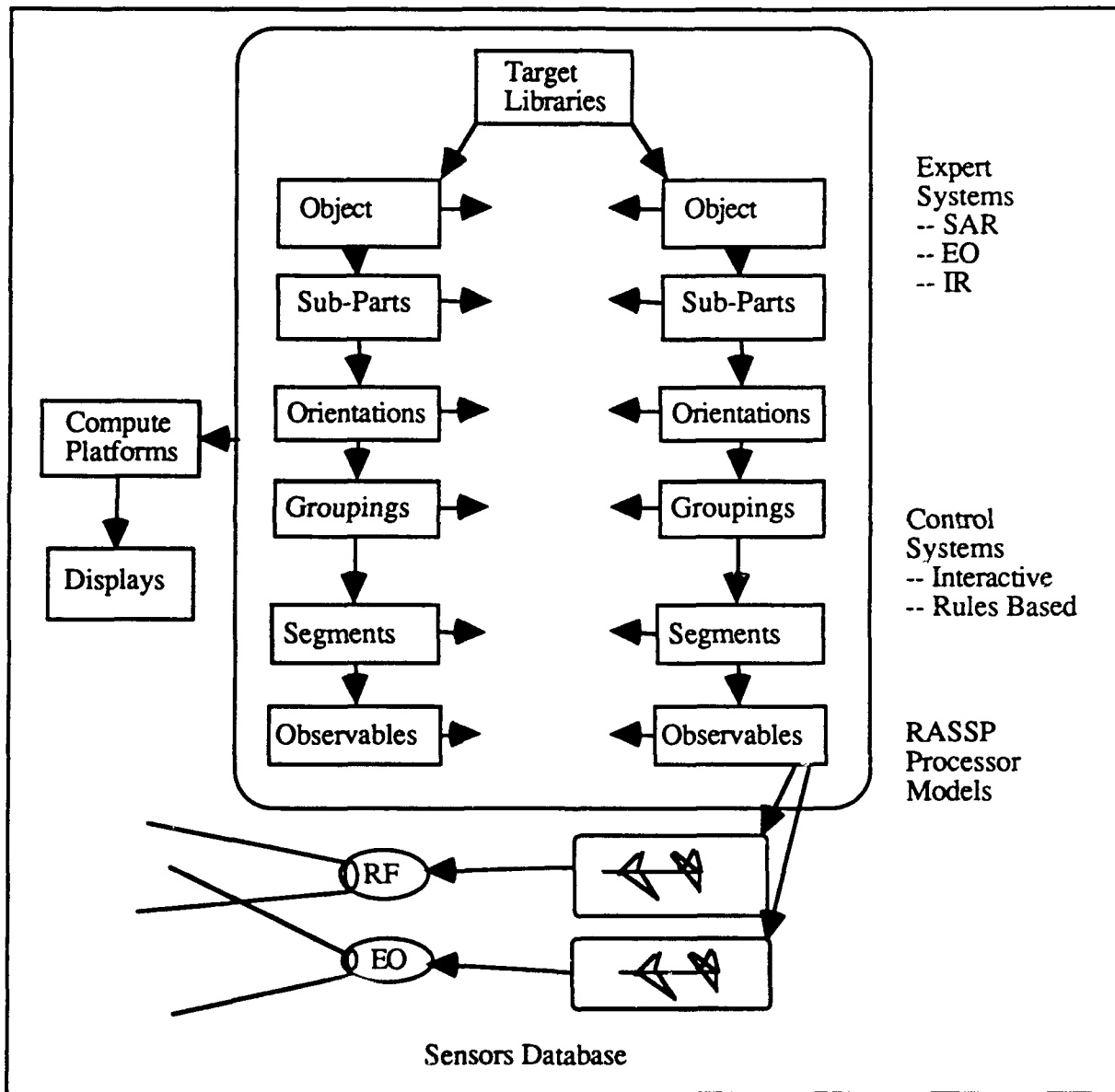


Figure 3.11-10, Air Target Algorithm Development Test Bed

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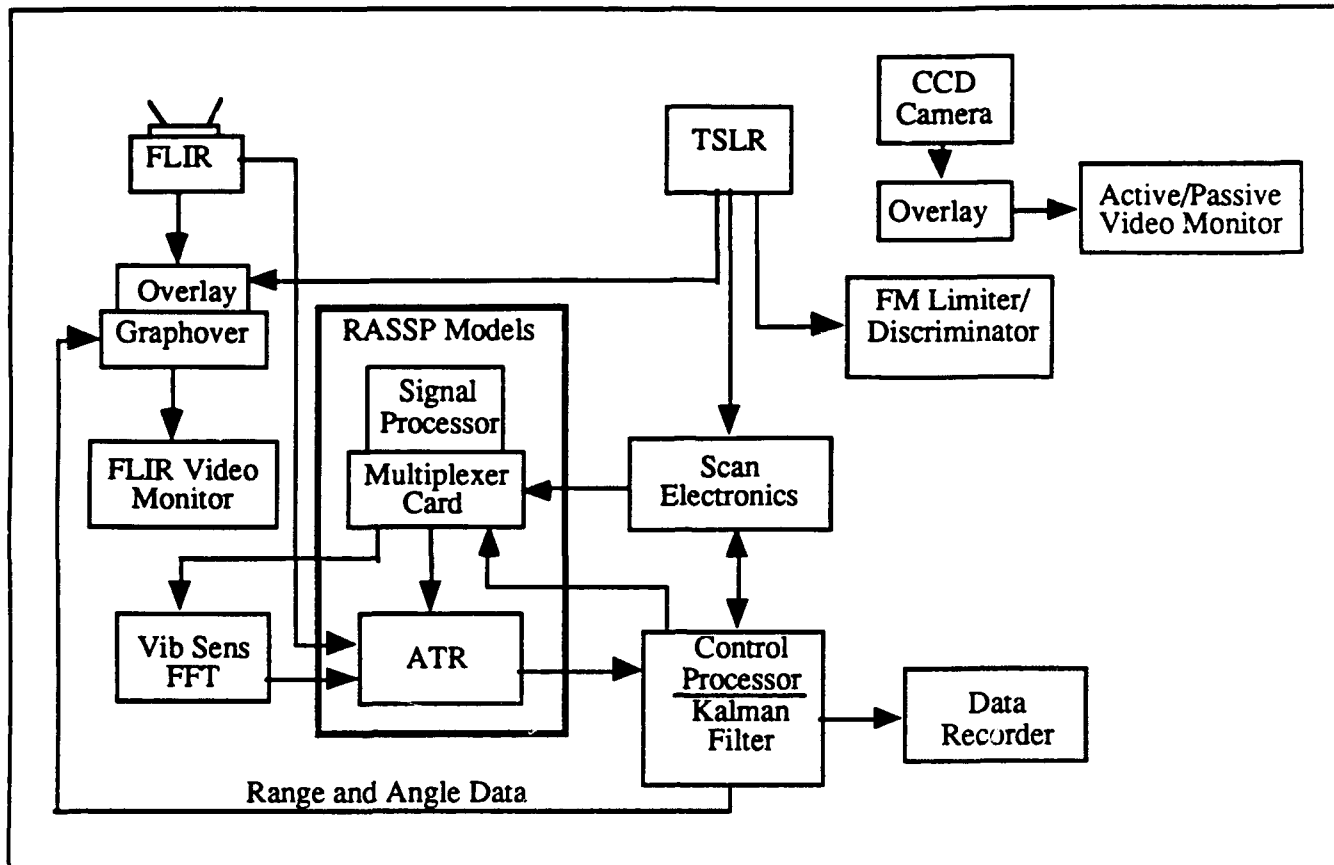


Figure 3.11-11, ALCTV Phase II Block Diagram

An example of a hardware test bed is a ALCVT Phase II possibility. Here the processor elements can be replaced with software models, emulator, or demonstration hardware derived from the RASSP system.

### 3.11.4 Classes Of Systems Which Benefit Most From The Model Year Approach

Model Year Processors can provide substantial return on investment for those important DOD programs where threat escalation is pushing advanced hardware/software/algorithm technology to new thresholds. These programs sponsor advanced activities in both development and research. They are developing evaluation test beds of various forms and are looking to advanced signals processing for solutions. Programs mentioned above in the ATR discussion are good examples. Within this context there are several other criteria that

augment the realization of benefits. These criteria are identified as follows:

#### CRITERIA A

Dual-Use Technology might be related to such components as submicron FIR filters for HDTV and radar, or modules for FUTURE BUS, or unique High Performance Computer kernels and so on.

#### CRITERIA B

Continuing Upgrades occur in systems where the computational requirements of algorithms are currently unbounded such as imaging, ATR, and NCTR. Also in this category are systems where processing capability must keep up with sensor technology -- IR STARING/SCANNING arrays, LASER RADARS, wide band phased arrays, multi-sensor, towed arrays. Other systems may not have been able to attain the throughput/performance requirements due to

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size, weight, volume or cost limits and must approach their goals through successive technology upgrades.

## CRITERIA C

This addresses the important issue of commonality. Many target systems would achieve a break through with higher sampling rates, greater dynamic range, adaptive algorithm implementations, etc. If these performance benefits can be realized in processors that are compatible with a class of systems that includes both the commercial and DoD, then we have identified a significant RASSP Target.

## CRITERIA D

Allows the inclusion of target systems that have commercial twins. Functional differences can exist and environmental or security requirements may differ but there exists a need in both areas for improvements.

### Other Categories Of Target Systems

In addition to these classes of developmental programs, there are other categories that can realize benefits from the Model Year approach.

The Rapid Response Model can be extended to include upgrades associated with:

- Altercation driven very rapid response
- Potential new high priority threat
- Pre-planned product improvement (P<sup>3</sup>I)
- Obsolete parts (perhaps unplanned)

The first item includes activities as experienced during Desert Storm where response time

for system upgrades was accomplished in a few months. In addition, to the rapid response model with tools and manufacturing in place, the ability to have resident within the design system the model of the next generation upgrade would be a powerful supporting tool in the decision and implementation process.

Item two addresses a condition where a new threat has been identified and solutions must be evaluated quickly. When the solution is total validated, the ability to implement an interoperable insertion in short order can be very significant to our defense posture.

The preplanned product improvement process must determine the optimum timing of the upgrade to obtain the best cost/performance improvement ratio. Many of the systems are complex and require mature re-engineering tools embedded in a design system in order to support a low risk undertaking. High levels of interoperability with last generation system must be support.

The obsolete parts or diminishing sources problem afford another class of problems that can realize benefits from the Model Year approach. The RASSP design system provides the tools necessary to assess various approaches such as direct functional replacement or Model Year insertion.

### 3.11.5 Primary RASSP Insertion Targets

Three systems were established as primary targets for RASSP Insertion at each division. The material in this section was presented at the Final Program Review.

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## 3.11.5.1 Equipment Division Candidates

| System Candidates                          | Planning Considerations  | Principle Benchmarks   |
|--|--|--|
| Long Range Surveillance Radar<br>AN/SPS-49 | Production Start 4Q93<br>RASSP model in 1994<br>RASSP demo in 1995 | <ul style="list-style-type: none"> <li>• 4x performance increase for volume search</li> <li>• &lt;2x performance increase for sidelobe cancel algorithms</li> </ul>                    |
| MILSTAR Tactical Comm                      | FSED System 4Q92-4Q94<br>RASSP model in 1994<br>RASSP demo in 1995 | <ul style="list-style-type: none"> <li>• &gt; 4x reduction in volume</li> <li>• Commensurate increase in reliability</li> <li>• Reduced NRE for limited production variants</li> </ul> |
| Ground Based Radar (GBR)                   | FSED System 4Q92-4Q97<br>RASSP model in 1994<br>RASSP demo in 1995 | <ul style="list-style-type: none"> <li>• Reduced cost with higher throughput margins</li> </ul>  |

**TABLE 3.11.12, ED'S PRIMARY RASSP INSERTION TARGETS**

**Target RAASP System: AN/SPS-49 (V)  
MPU ATD**

**Contacts:**

|                               |  |
|-------------------------------|--|
| Mr. Robert Pike<br>NAVSEA 62X | Mr. Michael Sosin<br>Raytheon Company<br>430 Boston Post Road<br>Wayland, MA 01778<br>(508) 440-1599 |
|-------------------------------|--|

**AN/SPS-49 (V) System Description**

- 2-D Long Range Surveillance Radar for Fleet
- Pipelined Signal Processor, Hardwired
- Digital Sidelobe Canceller in Receiver Subsystem
- Waveform Agile with Digital Pulse Compression
- Requirements Definition for Volume Search (2-1/2-D) Upgrade in Process

**Desirability for RAASP Use**

- Program in Production for 16 years with Major Upgrades every 7-8 years, Lesser Upgrades more often
- High Throughput is desired in Digital Sidelobe canceller to support more sophisticated Algorithms

- Higher throughput Required in Signal Processor to Support Volume Search Operation
- Programmability required in signal processor to adapt to changing threats between major upgrades

**Key Functions for Upgrade**

- Digital Sidelobe Canceller
  - Reduce quantity of existing H/W
  - Increase available H/W throughput
- Signal Data Processor
  - Replace hardwired logic with programmable
  - Increase throughput to support volume search operation

**Projections for RAASP Utilization**

- Perceived added risk to successful ongoing program
- Run as parallel effort with minimal interference
- Significant MIL-SPEC requirements levied on program, inconsistent with use of COTS equipment.

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## Target RASSP System: MILSTAR Tactical Communication

### Contacts:

Mr. Joseph Mardo  
Department of Air Force  
Hdqtr ESD (MILSTAR)  
Hanscom AFB, MA 01731  
(617) 271-6051

Mr. Richard Cease  
Raytheon Company  
1001 Boston Post Road  
Marlboro, MA 01752  
(508) 490-1306

Mr. Robert McGlothlin  
USN Space & Naval Warfare Systems  
Command PMW-156  
Washington, DC 20363  
(703) 602-7107

## MILSTAR Tactical Communication System Description

- Secure EHF Satellite Communication System
- Tactical versions of original strategic system
- Anti Jam Techniques with TRANSEC/COMSEC
- Multiple modulation techniques
- Multiple communication services, low rate to high rate
- Moderate processing load, multiple comm services

### Desirability for RAASP use

- Multiple programs, i.e. high volume production
- Emphasis is on cost, volume, and flexibility
- Programmability required for upgrades

### Key Functions for Upgrade

- Demodulator -- multiple techniques must be supported

- TRANSEC/COMSEC -- embedded TRANSEC/COMSEC desired
- Baseband Interface -- multiple channels, network control

### Projections for RAASP Utilization

- Identify insertion task in year 2
- Design/Fab/Test insertion task in year 3
- Test/Demonstrate at Raytheon MILSTAR test facility

### Perceived Deterrents To RAASP Use

- Perceived added risk to successful ongoing program
- Run as parallel effort with minimal interference

## Target RASSP System: Ground-Based Radar

Contacts: Col. William Ryan  
USASDC

Mr. Leroy Dirks  
Raytheon Company  
Huntsville, Alabama  
Boston Post Road  
(205) 955-4370  
Wayland, MA 01778  
(508) 440-6823

### Ground Based Radar System Description

- Land Based X-band phased array radar
- Wide bandwidth high resolution waveforms
- Real time target classification and discrimination
- Multiple variants for Theater Missile Defense and National Missile Defense
- High processing performance required
- Contract was awarded to Raytheon

### Desirability for RASSP use

- Program about to start full-scale development
- Higher throughput required for Solid



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State Array with fully adaptive nulling

Projections for RASSP Utilization

**Key Functions for Upgrade**

- Signal Processor
  - Reduce quantity of existing H/W
- Digital Waveform Generator
  - Increased processing requires distributed Receiver/Exciter architecture

- Identify insertion task in year 1993
- Design/Fab/Test in year 1994
- Demonstrate in year 1995

Perceived Deterrents to RASSP use

- Perceived added risk to NDI approach

| System Candidates  | Planning Considerations  | Principle Benchmarks   |
|--|--|--|
| SONAR MINE<br>DETECTION SET<br>AN/AQS-20   | <ul style="list-style-type: none"> <li>• JULY 1992 - MAY 1996</li> <li>• RASSP MODEL IN 1994</li> <li>• RASSP DEMO IN 1995</li> <li>• IMPACT FIRST PRODUCTION</li> </ul>                 | <ul style="list-style-type: none"> <li>• REDUCED COST WITH HIGHER PERFORMANCE MARGINS</li> <li>• VOLUME AND POWER FOR HELICOPTER AND TOWED ARRAY</li> <li>• IMAGING AND DETECTION ALGORITHMS</li> </ul>  |
| SUBMARINE COMMAND<br>AND CONTROL SYSTEM<br>MARK 2 CCS MK2                        | <ul style="list-style-type: none"> <li>• OCTOBER 1988 - OCTOBER 1993</li> <li>• RASSP MODEL IN 1993</li> <li>• RASSP DEMO IN 1994/5</li> <li>• PRODUCTION BREAK-IN IN 1995/96</li> </ul> | <ul style="list-style-type: none"> <li>• 10X IMPROVEMENT IN PROCESSOR CAPABILITIES</li> <li>• CONSOLIDATION OF SPECIAL PURPOSE ASSOCIATIVE PROCESSOR INTO WORKSTATION</li> <li>• SIGNIFICANT INCREASE IN LEVEL OF AUTOMATION</li> </ul>          |
| PASSIVE TORPEDO<br>DETECTION/CLASSIFI-<br>CATION LOCALIZATION<br>SYSTEM (DCLASP) | <ul style="list-style-type: none"> <li>• DECEMBER 1992 - DECEMBER 1993</li> <li>• RASSP MODEL IN 1993/4</li> <li>• RASSP DEMO IN 1994/5</li> </ul>                                       | <ul style="list-style-type: none"> <li>• MULTI-TARGET DATA ASSOCIATION &amp; TRACK</li> <li>• COUNTERMEASURE INTERFERENCE REJECTION</li> <li>• TORPEDO LOCALIZATION BY MULTI-PATH</li> <li>• COMPENSATION FOR PROPAGATION ENVIRONMENT</li> </ul> |

**TABLE 3.11-13, SSD'S PRIMARY RASSP INSERTION TARGETS**

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## 3.11.5.2 Submarine Signal Division Candidates

### TARGET RASSP SYSTEM: AN/AQS-20 (XN-1) SONAR MINE DETECTION

#### Contacts:

Mr. Ken Haas  
PEO (A) PMA 210  
Department of Navy Air ASW  
Washington, DC 20361-1210  
(703) 692-7697

Mr. Joe Kuzneski  
Raytheon Company  
1847 W. Main Road  
Portsmouth, RI 02871  
(401) 847-8000

#### AN/AQS-20 System Description

- Helicopter towed mine detection
- FSED award to Raytheon on 3 July 1992
- 46 Month Program; 2 equipment sets
- Processing in towed body, helicopter, and van
- Extensive use on VME-format modules

#### Desirability for RASSP Use

- Program is just entering full-scale development
- Processing already reliant on NDI and COTS
- Has modularity suited for incremental upgrades

## DETAILED CHARACTERISTICS OF AN/AQS-20 TARGET RASSP SYSTEM

### Key Functions for Upgrade

- Beamforming (spatial processing) in the towed body
- Detection processing in the helicopter
- Image enhancement in the helicopter
- Post-mission data analysis in the van

### Projections for RASSP Utilization

- Identify insertion area in year 2
- Test developed insertion in year 3
- Realize cost savings in first production

### Perceived deterrents to RASSP use

- EDM focus on successful evaluation
  - Resolve with integral plans and non-disruptive test
- Insertion proves more difficult
  - Resolve with encapsulation and planned accommodation
- Pay-offs may be minimal
  - Resolve by exploiting performance enhancements

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## 3.11.5.3 Electromagnetic Systems Division Candidates

| System Candidates                  | Planning Considerations   | Principle Benchmarks  |
|------------------------------------|---|---|
| HIGH POWER COUNTER MEASURES (HPCM) | <ul style="list-style-type: none"> <li>• MARCH 1994 - DECEMBER 1998</li> <li>• RASSP MODEL 1994/5</li> <li>• RASSP DEMO 1995/6</li> <li>• SYSTEM PRODUCTION 2000</li> </ul>                     | <ul style="list-style-type: none"> <li>• COST, VOLUME, POWER</li> <li>• NUMBER OF SIMULTANEOUS THREAT TRACKS</li> <li>• DYNAMIC RANGE, SENSITIVITY</li> <li>• RECONFIGURATION CAPABILITY</li> </ul> |
| LOW COST EW RECEIVER               | <ul style="list-style-type: none"> <li>• JANUARY 1994 - JANUARY 1997</li> <li>• RASSP MODEL 1994/5</li> <li>• RASSP DEMO 1995/6</li> <li>• SYSTEM PRODUCTION 1997</li> </ul>                    | <ul style="list-style-type: none"> <li>• COST, VOLUME, POWER</li> <li>• NEW THREAT RESPONSIVENESS</li> <li>• EMITTER SORTING</li> </ul>   |
| DIGITAL RECEIVER                   | <ul style="list-style-type: none"> <li>• JANUARY 1993 - DECEMBER 1995</li> <li>• PROTOTYPE</li> <li>• RASSP MODEL 1994</li> <li>• RASSP DEM 1994/5</li> <li>• SYSTEM PRODUCTION 1997</li> </ul> | <ul style="list-style-type: none"> <li>• LEVEL OF THREAT ENVIRONMENT DENSITY</li> <li>• SENSITIVITY</li> <li>• SINGULAR VALUE DECOMPOSITION</li> </ul>  |

**TABLE 3.11-14, ESD'S PRIMARY RASSP INSERTION TARGETS**

### TARGET RASSP SYSTEM - HPCM

HPCM is an acronym for High Power Counter Measures. HPCM is a standoff jammer mounted in an aircraft like a Boeing 707. The aircraft flies a racetrack path over friendly territory while sending high power jamming beams into enemy territory. The purpose of generating the jamming beams is to blind all enemy radar to the location of penetrating aircraft. Correctly applied, the jamming provides a safe corridor through which the friendly attacking aircraft can penetrate enemy defenses.

### PRIMARY POINT OF CONTACT

US Air Force Wright Laboratories  
Wright Patterson AFB, OH  
ASD/WL AAWD-8

### PROGRAM MANAGER

Mr. David Misek

### PRIME CONTRACTOR

Raytheon ESD

### CONTRACTOR SYSTEM ENGINEER

Mr. Lance McBride

### HPCM System Characteristics

The HPCM receiver has a number of difficult signal processing tasks that can be optimized through the use of RASSP. The receiver must handle high power emitters located at the FEBA, as well as, the lowest power emitters at the full penetration range of the strike aircraft. Therefore, the receiver must have sensitivity in excess of -- 100 dBmi and a dynamic range in excess of 80 dB. The receiver looks at the entire battle environment at a very high altitude and therefore sees all emissions, both enemy and friendly. Consequently, the radar pulse count that the receiver/processor must handle is very

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high in excess of three million pulses per second in any one GHz band. From this signal density at least 60 simultaneous threat tracks must be maintained as recipients of the jamming signal. Further, in the presence of this jamming, new signals must be identified and added to the track file within a period of two seconds after they appear. Angle of arrival is used as a signal sorting parameter by locating a threat by passive triangulation using two or more HPCM aircraft. This aircraft must share the threat data from pulse descriptor words (PDW) that are formed via data telemetry. Therefore, the aircraft must be on the same master system clock to insure that the frequency and time of arrival of signals had their origin at the same threat. All of these features pose signals processing challenges for the system designer.

## **HPCM Recommended Approach for RASSP Upgrade**

The recommended approach for RASSP methodology implementation would be to have a number of functional system modules available. The system engineer would logically arrange the modules at a computer terminal. The computer would assemble the modules and assess system performance for the requested result (sensitivity, for example). The system output would be compared to the performance goals outlined above. Then, the engineer would work interactively at the computer terminal to either improve system performance or to do cost/performance tradeoff studies. The end system would be the result of the interactive design. That is, RASSP is viewed as a design aid.

## **HPCM RASSP Use**

RASSP would initially only be used by the senior system engineers because the problems are so large and interrelated that they are almost intractable. Interactive computer aided system design is virtually the only way to efficiently attract the system design and cost control problem. Later, as the merit of the design

approach becomes obvious to both management and more junior engineers, its use will be both encouraged and desirable. This combination will cause its growth to be exponential, not unlike our experience with the use of PCs in the workplace

One of the primary features of RASSP as conceived for this program is that it is used as an interactive system design tool. Any detraction from this usage could be a deterrent to its use. For example, if RASSP could only be done as a batch process on a mainframe computer it would lose its interactive feature. Other contractual features could be deterrents to the interactive design. For example, forcing rigorous system configuration management constraints or extensive design reviews before system changes can be implemented.

## **Target RASSP System -- ESM Combat System**

### **Application:**

Advanced Submarine Tactical  
ESM Combat System  
System (ASTECS) ASARG, ADKEM

### **SYSTEMS POINT OF CONTACT:**

James Kolanek (Raytheon)

### **PROGRAM MANATER:**

Jennifer Horinek (Raytheon)

### **CONTRACTOR SYSTEM**

Engineer: Behshad Baseghi (Digital Rcvr)  
Jim Kolanek (ASTECS)

## **System Characteristics Making RASSP Use Desirable**

The receiver unit is a state-of-the-art DSP for use in ESM in different threat environments. The trade-offs between sensitivity, dynamic range, pulse width, throughput, etc for different applications requires hardware modifications with optimized size and cost. Below are recommended approaches for RASSP methodology implementation in these systems

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and how to assess progress.

- Improvements in handling denser environments, resolution and effectiveness can quickly be assessed using RASSP.
- Power dissipation, cost, I/O designs, manufacturing yield are effective elements for any system designer and PMO to use on quick turn around hardware (i.e., model year hardware) for eventual deployment system. Same as that presented in attached HPCM memo for RASSP

**Target RASSP System -- Low Cost EW Receiver**

**Contact:**

Ron Fairfield AF-LNXA  
Raytheon - Henry Leon

**Very Compact/Low cost EW system**

- Receiver Processor
- Resource Management
- Technique generation

Large real-time digital processing component of system design will benefit greatly from the ability to rapidly prototype alternate approaches to find optimal cost/performance solutions.

### 3.11.5.4 Missile Systems Division Candidates

| SYSTEM CANDIDATES                               | PLANNING CONSIDERATIONS  | PRINCIPLE BENCHMARKS  |
|---|--|---|
| ADVANCED KINETIC ENERGY MISSILE (ADKEM)         | <ul style="list-style-type: none"> <li>• HARDWARE IN THE LOOP (HIL) 1993</li> <li>• ENHANCED SIGNAL PROCESSOR 1995/6</li> <li>• RASSP MODEL IN 1994</li> <li>• RASSP DEMO IN 1995/6 HIL</li> </ul>               | <ul style="list-style-type: none"> <li>• EXTREMELY LOW LATENCY</li> <li>• VOLUME, POWER AND COST</li> <li>• GUIDANCE ALGORITHMS</li> <li>• AIM POINT SELECTION ALGORITHMS</li> </ul>              |
| JOINT DIRECT ATTACK MUNITIONS (JDAM)            | <ul style="list-style-type: none"> <li>• PHASE I 1993-1994</li> <li>• PHASE II 1995-1997/8 FULL SEEKER</li> <li>• RASSP MODEL IN 1995/6</li> <li>• RASSP DEMO IN 1996/7</li> </ul>                               | <ul style="list-style-type: none"> <li>• EXTREMELY LOW COST</li> <li>• VOLUME AND POWER</li> <li>• SAR MAPPING</li> <li>• OBJECT RECOGNITION ALGORITHMS</li> </ul>                                |
| ADVANCED LAND COMBAT VEHICLE TECHNOLOGY (ALCVT) | <ul style="list-style-type: none"> <li>• PHASE II 1992-1194</li> <li>• PHASE III 1995-1997/87</li> <li>• RASSP MODEL BASED ON 1994 TEST RESULTS</li> <li>• RASSP DEMO BY TEST BED INSERTION IN 1995/6</li> </ul> | <ul style="list-style-type: none"> <li>• VOLUME, POWER, COST</li> <li>• AUTOMATED HIGH PROBABILITY OF TARGET ACQUISITION</li> <li>• SENSOR FUSION ALGORITHMS</li> <li>• ATR ALGORITHMS</li> </ul> |

**TABLE 3.11-15, MSD'S PRIMARY RASSP INSERTION TARGETS**

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| SYSTEM CANDIDATES                                      | CONTACTS   | CHARACTERISTICS  |
|--|--|--|
| <p>ADVANCED KINETIC ENERGY MISSILE (ADKEM)</p>         | <p>TIMOTHY CAREY - RAYTHEON<br/>           MIKE SCHEXNAYER - U.S. ARMY,<br/>           MICOM LAB</p> | <ul style="list-style-type: none"> <li>• ANTI-TANK, ANTI-AIR HIT TO KILL</li> <li>• ATR, RECOGNITION, AIM POINT SELECTION</li> <li>• NEXT GENERATION SIGNAL PROCESSING - GROWTH WITH THREAT ESCALATION</li> </ul>                |
| <p>JOINT DIRECT ATTACK MUNITIONS (JDAM)</p>            | <p>STEPHEN MONAGHAN - RAYTHEON<br/>           TERRY LITTLE - AIR FORCE AFATL/AG</p>                  | <ul style="list-style-type: none"> <li>• AIR TO GROUND, PRECISION TERMINAL GUIDELINES</li> <li>• ATR, SAR IMAGING</li> <li>• LOW UNIT COST</li> <li>• ACCURACY DRIVEN NEXT GENERATION SIGNAL PROCESSING</li> </ul>               |
| <p>ADVANCED LAND COMBAT VEHICLE TECHNOLOGY (ALCVT)</p> | <p>DR. GREGORY OSCHE - RAYTHEON<br/>           LTC. THOMAS QUINN - DARPA/LSO</p>                     | <ul style="list-style-type: none"> <li>• INTEGRATED LASER AND MMW RADAR (ILAR)</li> <li>• ATR, FIR CONTROL, NON-COOPERATIVE IFF</li> <li>• FUTURE TANK DEFENSE TECHNOLOGY DEMANDING NEXT GENERATION SIGNAL PROCESSING</li> </ul> |

**TABLE 3.11-16, MSD'S CONTACTS FOR RASSP INSERTION TARGETS**

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After review of all Target Systems, it was determined that the Automatic Target Recognition application was the most suitable for use as a benchmark model throughout the development phase of RASSP. Initially a simple

model in behavioral VHDL could be established for a multi-application processor. Later specific insertion opportunities could be marketed for specific configurations of this model. Final RASSP system could be exercised for critical Target applications as appropriate at that time.