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Quarterly Progress Report
(April 1, 1992 through June 30, 1992)

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VLSI for High-Speed Digital Signal Processing

prepared for

Office of Naval Research
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Arlington, VA 22217-5000

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Grant No.: N00014-91-J-1852
R & T Project: 4148503-01

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VLSI for High-Speed Digital Signal Processing

Quarterly Progress Report – 4/1/92 through 6/30/92

During the present quarter we have made some architectural changes to the five-processor ring-structured programmable digital filter IC to improve the system performance. The main change is to insert a register between the coefficient RAM and the multiplier to eliminate the read time of the RAM from the critical path of the multiplier. This provides a substantial improvement in the system performance since the critical path of the multiplier determines the performance of the over-all five-processor system. Figure 1 shows a block diagram of the new ALU architecture. A TinyChip comprising the multiplier with the redesigned carry-select vector-merge adder described in the previous report has been sent to MOSIS for fabrication. The IC consists of the 12-bit by 11-bit multiplier, the coefficient and data input registers (see Figure 1), the output register, and RAM to store the coefficient and input data. The multiplier itself consists of 3100 transistors occupying an area of 1.53 mm^2 (1.313 mm by 1.166 mm) in $2\text{-}\mu\text{m}$ CMOS technology and is simulated to operate in 22 ns. We expect the prototype parts in the middle of the next quarter for testing. Figure 2 shows the architecture of the TinyChip submitted for fabrication and Figure 3 shows the layout of this IC.

The ALU is pipelined into two sections: the multiplier and the adder/subtractor (see Figure 1). Since the adder/subtractor will clearly operate faster than the multiplier, we can skew the clock to the register at the output of the multiplier and

the clocks at the input and output of the ALU to allow the multiplier additional time to perform its computation. This essentially allows the multiply operation to extend partially into the cycle allocated for the addition/subtraction so long as the two operations are complete in two cycles. Of course, in order to prevent race conditions the skew can be no greater than the minimum clock-to-output delay of the ALU input registers. For the current 2- μ m CMOS design this is approximately 2 ns, which allows the cycle time for the system to be reduced to 20 ns. Thus, the overall five-processor system can be expected to operate at approximately 50 MHz in 2- μ m CMOS technology.

We have also redesigned the dual-port register blocks to operate at 50 MHz. A TinyChip consisting of a 16 by 16-bit dual-port register block is currently being submitted to MOSIS.

We have just completed the design and layout of the program storage memory for our processors. Each processor requires a memory of sixteen 32-bit instructions. Program data can be stored randomly, but can only be accessed sequentially. The minimum write time is designed to be 200 ns and the minimum read time is 15.3 ns. We will fabricate and test this layout during the next quarter.

The following journal publication citing ONR support under this grant has appeared during the present quarter:

A. Y. Kwentus, M. J. Werter and A. N. Willson, Jr., "A Programmable Digital Filter IC Employing Multiple Processors on a Single Chip," *IEEE Transactions on Circuits and Systems for Video Technology*, vol. 2, June 1992, pp. 231-244.

In addition, our paper describing the ring-structured multiprocessor chip has been accepted for the IEEE Workshop on VLSI Signal Processing, to be held in Napa, California, on October 28-31, 1992. Copies of the paper and the acceptance notice are enclosed.

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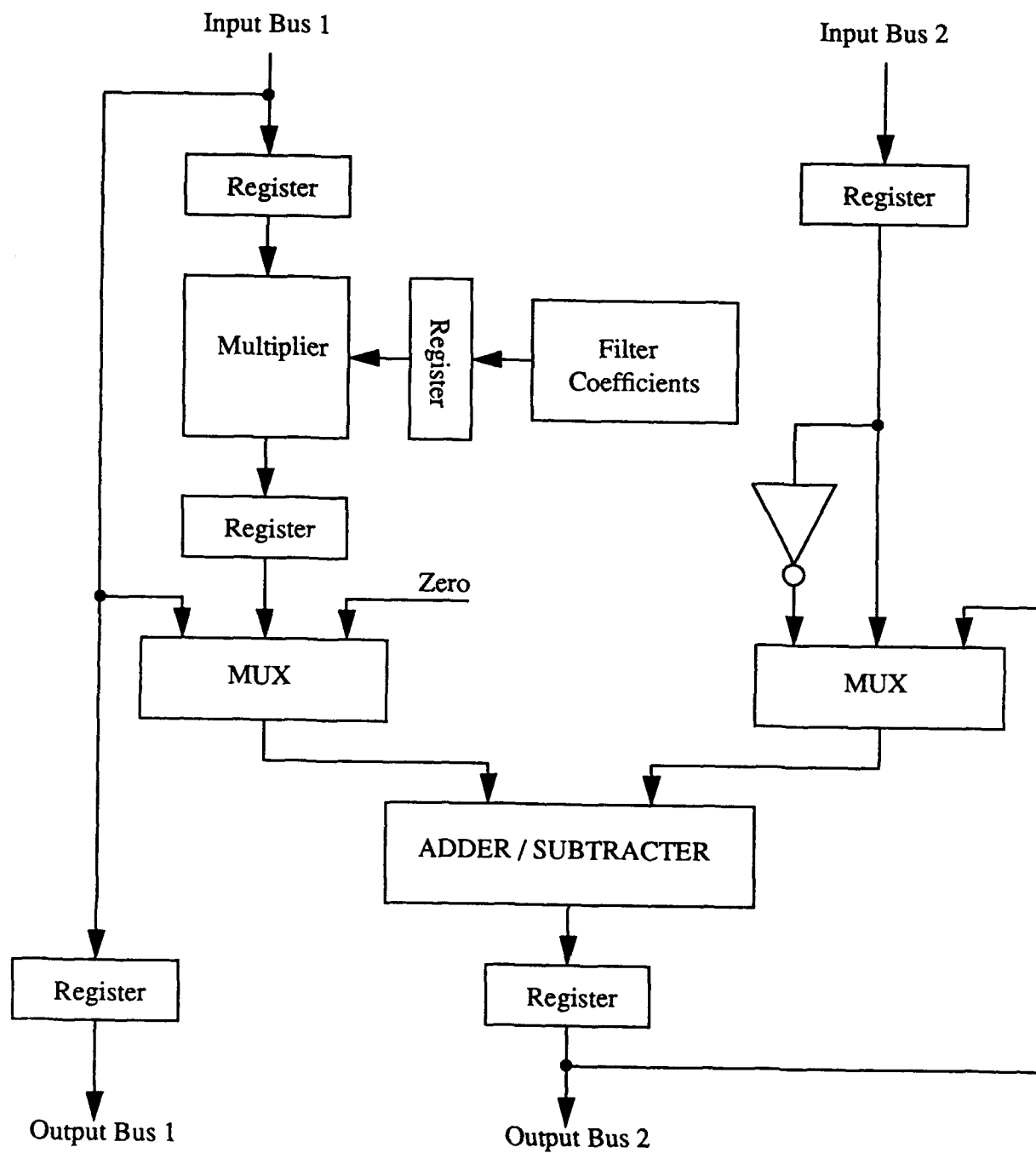


Figure 1 - ALU Architecture

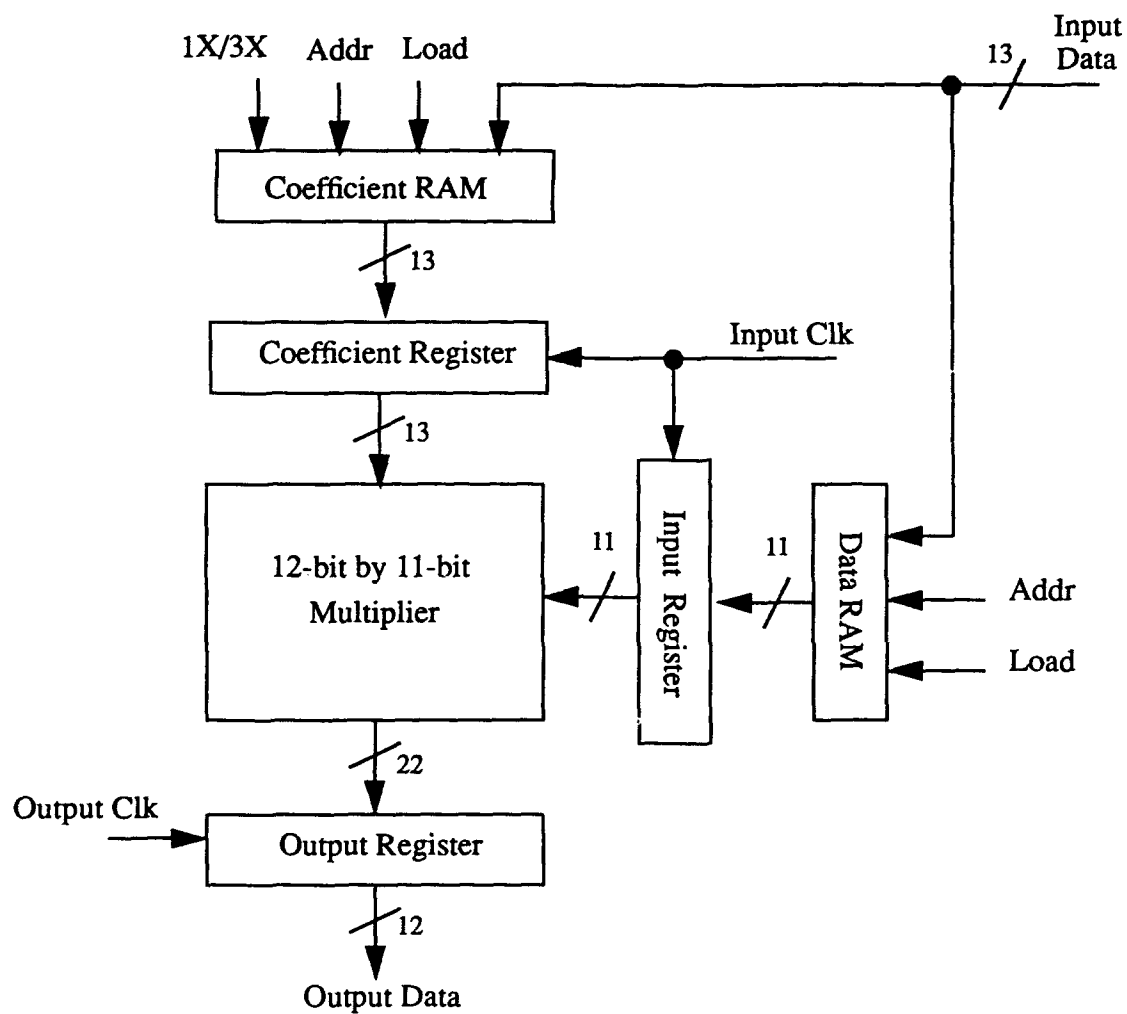


Figure 2 - Block Diagram of Multiplier Test IC

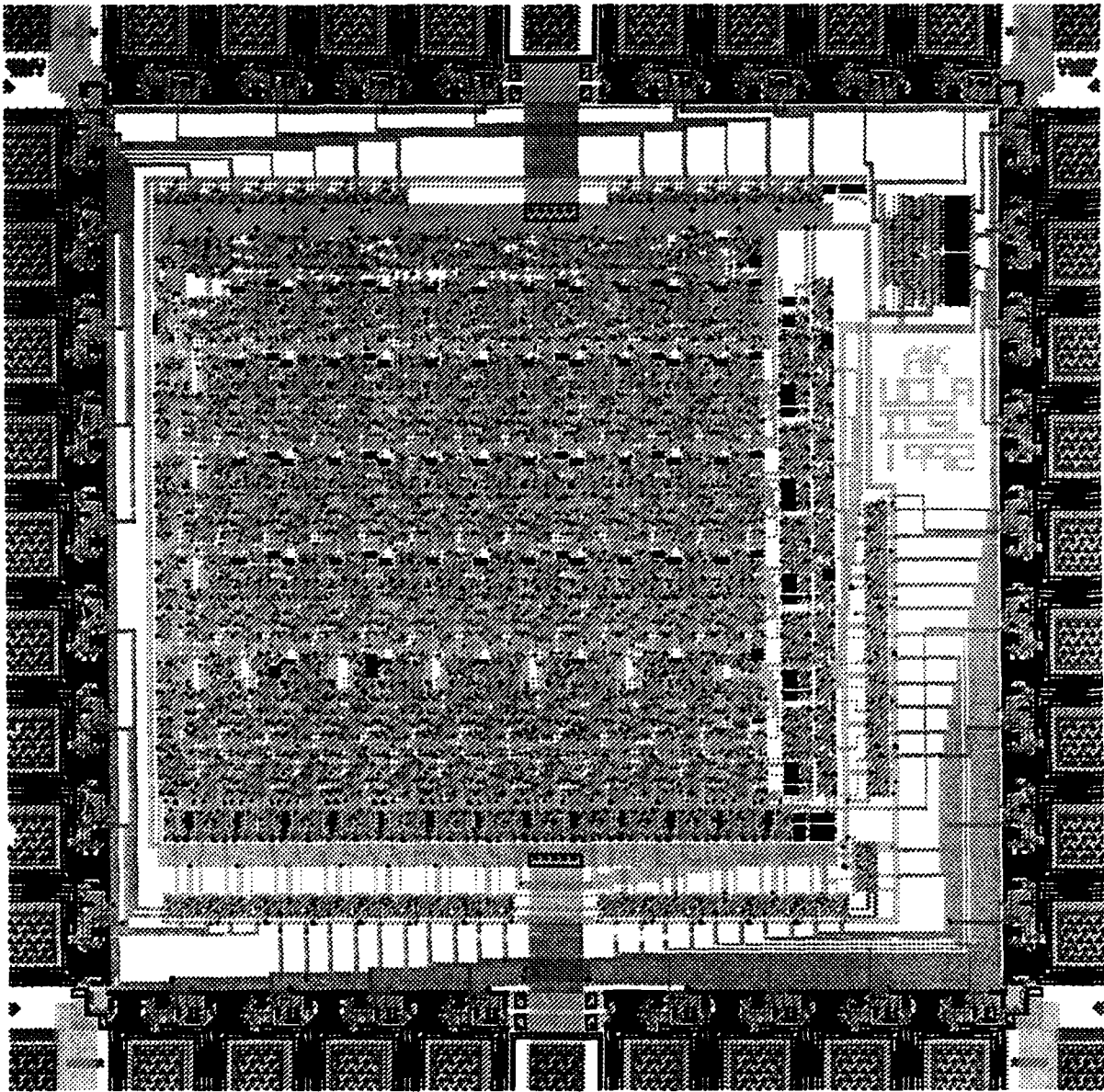


Figure 3 - Layout for the Multiplier Test IC