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19. ABSTRACT (Continue on reverse if necessary and identify by block number)The Tire Quality Monitor (TQM) is a microcomputer-controlled, ultrasonic tire inspector.It not only performs the computations required to classify and analyze ultrasonicsignals reflected from tire structures, it also formats and controls the displays,intercepts and interprets the operator's pressing of the front panel keyboard switches,controls the inspection rate and the characteristics of the signal reception hardware,and provides a reprogramming capability to modify tire classification and analysisparameters. This report describes the software used to perform these functions,provides information to a software engineer on how the TQM supports itself and performsits programmed functions, and contains information on how the computer recognizes andanalyzes tire structures. This document is addressed to tire engineers or nondestructiveevaluation personnel responsible for the TQM's implementation/modification.						
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1.0. INTRODUCTION

1.1. Background

This is the final technical report on the theory of operation for the Tire Quality Monitor (TQM) prepared by Chamberlain National, GARD Division, for the U.S. Army Tank-Automotive Command (TACOM) under Contract DAAE07-83-C-R088.

The TQM is an ultrasonic testing device that uses a microprocessor to analyze data from a tire to test its suitability for retreading. The TQM has the ability to detect and analyze defects which cannnot be determined by current visual inspection methods. The TQM can detect tire degradation, bond and ply separation, bond line defects, and porosity in the rubber.

1.2. Scope

This report is a detailed technical description of the processes that the TQM goes through to inspect tires. The report describes the software used to perform the inspection, provides information to a software engineer on how the TQM supports itself and performs its programmed functions, and contains information on how the computer recognizes and analyzes the internal structure of the tires.

1.3. Purpose

The purpose of the TQM is to supplement the visual inspection of tires. The use of the TQM greatly improves the efficiency of the retreading process and quality of the retreaded tires by decreasing the number of bad tire carcasses entering the process.

2.0. OBJECTIVES

The primary goal of this report is to provide the software engineer for the TQM a detailed description of the processes that the TQM goes through in collecting and analyzing data during the inspection of tires.

3.0. CONCLUSIONS

The TQM, when used as a supplement to the visual inspection of tires, greatly increases the level of quality of the retreaded tires, as well as decreases the in-process failures by reducing the number of bad tire carcasses entering the process.

4.0. RECOMMENDATIONS

4.1. Tire Carcass Shipment

Tire carcasses should be inspected by the TQM before shipping to retreaders to eliminate the cost associated with the shipment of bad tire carcasses.

4.2. Depot Use

The TQM should be used at depot tire retreading operations to screen out defective tire carcasses to reduce the process costs by reducing the number of carcasses that fail during retreading.

4.3. Checking Retreaded Tires

The TQM should be used to check retreaded tires returning from contractor retreading facilities to determine if the same quality carcasses supplied to the contractor have been returned to the government.

5.0. DISCUSSION

5.1. Operating System

The TQM software "Operating System" is extremely primitive, consisting of a cold-start initialization sequence and two hardware interrupt handlers. The cold-start sequence (Figures 5-1 and 5-2) tests the TQM workspace random access memory (RAM) (FOOO through FFFF). If there is any test failure, the sequence branches to a routine which presents a flashing "E O" message to the displays in an infinite loop. Otherwise, if the RAM test is passed, the RAM is cleared and the program continues to:

- Copy receiver section control voltages from Programmable Read-Only Memory (EEPROM) into RAM and then out to the hardware interface
- Transmit display blanking codes to the hardware interface
- Initialize all nonzero indices and pointers held in PAM to their respective starting values.
- Call routines that set the TOM into:
 - Glass-Reinforced Plastic (GPP) maintenance mode
 - TEMP display
 - PRE retreat mode
 - MIDLINE test location
- Reset the display refresh clocks in RAM

Cold Start : v Initilize Stack Pointer Process Walking Bit Test of RAM (Flowchart 1.1a) V Clear RAM U Initialize Receiver Hardware age(1) (- [RAM_TMP_INGAIN] (- [ROM_INGAIN] age(2,c) (- [RAM_TMP_FN_GAIN] (- [ROM_FN_GAIN] age(2,a) (- [RAM_TMP_PK_GAIN] (- [ROM_PK_GAIN] agc(2, b) (- [RAM_TMP_SLOPE] (- [ROM_SLOPE] age (3) (- ERAM_TMP_OUTGAIN] (- EROM OUTGAIN] υ Initialize Displays Hardware disp (- DSPLY0 Array (- Blanking codes disp (- DSPLY1 Array (- Blanking codes Initialize Update Mode Indices UPDATESTATUS (- Ø TEMPINDEX (- 8 THICKINDEX (- 4 <- FF00H ADDRESS U Initialize Temperature Indices CALIB_TEMP (- 70-30 Array "OOT" Flags (- 0 TEMPDIVBY5 (- CCALIB_TEMP]/5 TEMPREMAIN (- Module([CALIB_TEMP], 5) Initialize Temperature Averaging Pointer TEMP_POINTER (- #TEMP_ARR U Initialize TQM State to TEMP Display, PRE Retread Mode, MIDLINE Test Location, and GRP Type V Initialize Clocks TIMERDSP (- 100/6 (1/6 second timer) TIMERED (- 1 (1/3 second timer) U Enable RST 5.5 and RST 7.5 Enable Interrupts : V <----. :

Figure 5-1. Powerup Initialization Sequence

Process Walking Bit Test of RAM 2 υ Set bit b0 into Reference Pattern V : V Pattern (- Reference Pattern * U m (- F000 (Start of RAM) V -> v 2 [m] (- Pattern : V 2 no m = Pattern? -------2 yes : 8 8 • V 2 g Rotate Pattern Left : m (- m + 1 2 V 2 ---- m≈0? yes : V Pattern (- Pattern m (- F000 V ·---> 8 U 2 rici ۷ [m] = Pattern? -----> : 1 1 yes : . 8 V 2 8 2 Rotate Pattern Left 2 2 2 m (- m + 1 . 8 2 2 1 V ğ V Display Flashing "E 0" Message no . -- m=Ø? 2 2 yes : V Rotate Reference Pattern Left 1 2 . no v ---- Has Bit Walked Through Entire Pattern? yes : V Exit

Figure 5-2. RAM Test

At this point, the TQM is initialized. The 8085 Central Processing Unit (CPU) interrupts Recovery Sequence Tester (PST) 5.5 and PST 7.5 are then enabled, and the program sits in an infinite wait loop for interrupt-driven processes.

The highest priority interrupt handler (EST 7.5) is assigned the tasks of pulsing the TCM ultrasonic transducer and of scheduling the reception and processing of ultrasonic reflections. This interrupt is driven by a 100-hertz (Hz) hardware clock. Figures 5-3 through 5-7 outline the steps executed by this handler. Note that the receiver automatic gain control (AGC) section is triggered and the transducer pulsed at every service of the interrupt, but the return signal is digitized only when no processing of a previously digitized signal is in progress. This is done to maintain the oscilloscope display as described in par. 5.6. One of the software clocks serviced by this handler then schedules, at a 6-Hz rate, the processing of digitized data if a gain calibration is active and such processing is not already in progress. This clock also updates receiver hardware parameters, controls requests for listing (as described in par. 5.6.), and alternates displays and task groups.

Specifically, the "odd" task group will process the calibration period clocks always, execute temperature calibration when active, and send to the hardware interface those codes formatting the "odd" display (i.e., the dark half of a flashing pattern). If the update mode is disabled, the "even" task group will process the STORE and CLEAR switch light-emitting diode (LED) clocks, process the information necessary to refresh the enabled display if not already being processed, and send to the hardware interface those codes formatting the "even" display (i.e., the lit half of a flashing pattern). If the update mode is enabled, the "even" task group does not process any information and updates the "even" display according to the latest sequence of update commands as derived from servicing the RST 5.5 interrupt.

The lowest priority interrupt handler (RST 5.5) is assigned the tasks of receiving, interpreting, and executing commands from the operator's pressing of keyboard switches. This interrupt is driven by a common trigger line from the front panel keyboard array. Figures 5-8 through 5-10 outline the execution of this handler. All mode change, inspection and update commands to the TQM are serviced by this handler. Figures 5-11 through 5-13 and Table 5-1 summarize the manner in which TQM mode changes and inspection states are handled.

5.2 Signal Acquisition

5.2.1. General. The transducer pulse timing, signal reception parameters, and signal capture and digitization are under computer control in the TQM. This chapter describes the software which controls the computer and the parameters which control the hardware.

5.2.2. Fulse Generation. The high-voltage electrical pulse which drives the ultrasonic transducer is generated by circuitry which is



Figure 5-3. Highest Priority Interrupt Service

Process Even/Odd Tasks 2 U. Reset 1/6 second timer U no Gain Calibration in Service? ------. : yes : yes V · V ···-- . . ------> Ultrasonic Data Processing Active? -----> no : . . v Set Semaphore 3 Enable RST 7.5 Enable Interrupts V Retard 1/6 second timer U. Process Gain Calibration (Flowchart 4.5) • • U Disable Interrupts Clear Semaphore . V Advance 1/6 second timer v 9 rici yes V I ----- Has 1/3 second passed? -----v v Process Even Tasks Process Odd Tasks (Flowchart 1.2c) (Flowchart 1.2b) 2 . U Send Vectored Display Codes to Hardware Interface Update Receiver Hardware V no STORE listing enabled? ----. yes : : v : Process STORE listing ; (Flowchart 3-10) : \mathbf{U} : ----nci V. ANALYZE listing enabled? ----. yes : : V Process ANALYZE listing : (Flowchart 3-11) : : U . <----! v Exit Figure 5-4. Even/Odd Task Allocation

Process Odd Tasks : • V yes Update Mode Enabled? -----. V yes : TEMP CAL Time Up? -----. no : V : Process TEMP CAL Timer : (Flowchart 1.2d) : 8 8 8 5 8 ۔ ج ج ا V yes TEST CAL Time Up? -----. 2 no: U 2 v 8 . Process TEST CAL Timer : (Flowchart 1.2d) : 2 8. 8 . 5 V <----» 2 rici 5 V TEMP CAL Active? -----. ê yes : V : 8 . . . 8 Process TEMP CAL 2 (Flowchart 4.4) 5 . 8 · 8 V : V rice TEMP CAL Time Up? -----. 8 . V : Turn Even TEMP led On : Turn Odd TEMP led Off : V : 8 8 . 8 ة 1 محمد جيده مدي اعنه مدي وجه دنيه ه (-----2 V 110 : TEST CAL Time Up? -----. 2 yes: : 2 . U . Turn Even TEST led On : Turn Odd TEST led Off : : : : 3 V <----· : V yes . Any CAL Time Up? -----. 1 : : no : V 2 . Set Even Seven-Segment : Codes into Odd Array : V V 8 5 5 ---- (---! v Point to Odd Display Array V yes Exit

Figure 5-5. Odd Tasks



```
Process TEMP CAL Timer
          5
          V
ITEMTIM3 (- ITEMTIM3 - 1
          :
          V
     TEMTIM = 0? ----> Exit
      yes :
          V
     Set FLAGS(b6) ["timed-out" true]
    Clear FLAGS(b4,b2) ["hold", "in-service" false]
          .
          V
          Exit
Process TEST CAL Timer
         1
          ۷
[CALTIM] (- [CALTIM] - 1
          2
         V
    CALTIM = 0? ----> Exit
     yes :
         U
     Set FLAGS(b7) ["timed-out" true]
   Clear FLAGS(b5,b3) ["hold", "in-service" false]
         :
         V
         Exit
```

Figure 5-7. Calibration Period Timers

RST 5.5 Interrupt (Keyboard Switch Service) 1 V Disable RST 7.5 Disable RST 5.5 : no V Calibration In Service? ----. : yes : V : Process Keyboard Switch : (Flowchart 1.3b) : : : : V 1 V Enable RST 5.5 Enable RST 7.5 Enable Interrupts \$ V Exit

Figure 5-8. Lowest Priority Interrupt Service

Process Keyboard Switch 2 v Enable Interrupts : U no Has Switch Been Pressed for 5 Consecutive Reads? -----. yes : v Disable Interrupts Read Input into KEY_INPUT 1 yes V 2 Ultrasonic Data Processing Active? -----. 2 no : 8 V 1 Process Command Translation and Execution : (Flowchart 1.3c) 2 . 2 U . . 1 . U Enable Interrupts : υ 2 9 8 2 2 v no : 8 Has Switch Been Open for 5 Consecutive Reads? ----* 8 yes : 5 5 -----. V Disable Interrupts : V Exit

Figure 5-9. Front Panel Keyboard Services

Process Command Translation and Execution : V yes 10 ----- Update Mode Enabled? ------8 2 V ν Point to Update Vector Table Point to Operations Vector Table ŝ _____> <_____ : V Read Execution Address from Vector Table + KEY_INPUT : V KEY_INPUT (- Ø : rio V Error Condition? -----. yes: 5 · V no V : Exit (---- Is command a CLEAR? : yes : 8 U. : ----<-: V Execute Procedure (Table 1.1) 2 V Exit

Figure 5-10. Switch Command Translation and Execution

			intry	0 Du	. Ted	-ECT (b6)	RP_OUTGAIN1	
		• • 2	GRP E	-)		FSEL	• <u>- 0</u> •	
		>	Entry		160 - >	LECT (b7) Set	agc (3)	
			R/N	Tur		E FBEI		
			Entry	5		ECT (b3) Be		n setpoint ress ameters farameter n Paramete nolds (x5R) x5R) x5R) x5R) TTX) TTX)
		>	968/8 2	- Turn		Set FBEL V		nt able Add able Add dfb Par trion Par ufficatio anficatio eshold eshold eshold dile Peak
			Entry P	0r 10r				m setpoi ckness T ckness T mask Len mask Len mask Len mask Len mask Len at Len the R case case case case case case case case
act i on	lada -	•	FRUCK/T 8	Turn T		Set FBEL	CNIE	alibratic tion case tion case Ringout De Featur Fratura Jeited Ti Jeited Ti
e Sel	E TYP		ntry	1 - - -		T (b5)	oute	Mess Mess Mess Mess Mess Mess Mess Mess
e Typ	° V V IIA	- >	ଆ ସ ପ	urn C =	>		v C ROM	, aatomtototototototototototototototototot
ess Tir	Off Al		TRUCK	Ť ia) Set F	c (3) (-	ETPOINT TABBASE ALTPOINT TABBASE Raingou Lopegad Cipegad Raint Cipegad Cipegad Al Cipegad Cipegad Cipegad Calint Tentim
Prou	- Turn		Entry	on Led		CT (be	01	PULSE FARCUE FARCUE FARCUE FARCUE C C C C C C C C C C C C C
		• • >	3 .	v V Turn Oga/a	->	FSELE		211 ME
			PAS9.	ā) Set		
			Entry	- - -	1	CT (b)		
	•	, ∾ >		rurn (->	; 285 285		I THE
			RUCK.	L IAT		Set		
			try 1	had		(192)		ະ ີ ບັ
		- >	ч Н Ел	- 10 - 10 - 10	>			
			TRUCK/S	TRUCK		Set FBE		TEXT

Figure 5-11. Tire Type Selection

Process Retread Mode Selection 3 2 : 5 : 5 V V POST Entry PRE Entry : : V v Turn On POST led Turn On PRE led Turn Off PRE led Turn Off POST led : 2 ν v Clear FSELECT+1(bØ) Set FSELECT+1(b0) : : ν V Point to POST-Retread Parameters Appropriate Parameters Appropriate to TIRE TYPE Selected Point to PRE-Retread to TIRE TYPE Selected : . ____> (_____ : V NDISEAMP (- Noise Amplitude and Width Thresholds A1 (- Absolute Degradation Threshold A2 (- Absolute Separation Threshold A11 (- Absolute Porosity Threshold LOWERLIMIT (- Absolute Degradation Threshold (TTX) UPPERLIMIT (- Absolute Separation Threshold (TTX) A18 (- Absolute Bondline Threshold LOWSHOPLIMIT, HIGHSHOPLIMIT (- Time Limits for TTX Single Peak Classificati v Exit

Figure 5-12. Retread Mode Selection



Figure 5-13. Test Location Selection

	SWITCH COMMAND	OPERATIONS FLOWCHART		OPERATIONS	UPDATE ROUTINE
THICH TEMP QUAL	< ITY	Flowchart Flowchart Flowchart	3.2 3.3 3.1	DEPTH TEMPERATURE QUALITY	
TEMP TEST	CAL CAL	Flowchart Flowchart	4.1 4.2	TEMP_CAL_START GAIN_CAL_START	
TRUCI TRUCI PASS TRUCI TRUCI PASS R/N GRP	K/S 1 K/T 1 /S 1 K/S 2 K/T 2 /S 2	Flowchart Flowchart Flowchart Flowchart Flowchart Flowchart Flowchart Flowchart	1.4 1.4 1.4 1.4 1.4 1.4 1.4 1.4	DTSR_I OTTX_I OPSR_I OTSR_II OTTX_II OPSR_II	
PRE POST		Flowchart Flowchart	1.5 1.5	OPRE OPOST	
MIDL Shou	INE LDER	Flowchart Flowchart	1.6 1.6	OMID OSHLDR	
STOR	E YZE	Flowchart Flowchart	3.10 3.11	STORE ANALYZE	

triggered by CFU control at a 100-Hz rate. Normally, an AGC trigger (discussed in par. 5.2.3.) starts the gain variation in the receiver's depth compensation circuit and a pulse trigger follows 16.0 microseconds later. However, if the CPU is not actively processing a digitized ultrasonic signal, this normal sequence will be immediately preceded by a Transient Data Pecorder (TDR) trigger to start the acquisition and digitization of the next signal. The resultant acquisition, therefore, contains coupled AGC trigger noise sampled along with the transducer's "main-bang" and the returning tire structure reflections. Figure 5-14 illustrates the relationship of these pulses.

As discussed in par. 5.1., the CPU control of this 100-Hz pulse generation sequence comes from the execution of the highest priority interrupt service in the software. It was designed this way to provide a stable oscilloscope display (described in par. 5.6.) of the ultrasonic signals detected by the transducer. The actual processing of the digitized signals is done at a nominal 3-Hz rate. The 100-Hz interrupt service has been designed to allow the CPU to perform multiple tasks between the pulse generation task and the signal-processing task so that neither task is significantly impeded by the execution of the other. Those branches in Figures 5-3 through 5-7 which act on the presence of ultrasonic data processing assure this.

5.2.3. Signal Reception. The receiver section amplifies the incoming signal by two constant factors and by a factor which monotonically increases with time. This increasing factor is required to compensate the received signal for the attenuation caused by passage through tread rubber. The compensation factor value is controlled by a section of the receiver's AGC circuit known as the Distance-Amplitude Compensator (DAC) and designated as AGC₂ since it is the second gain stage in the receiver. This AGC₂ stage is configured by the CPU via three voltages. The ways the AGC₂ is configured are listed in Table 5-2 and illustrated in Figure 5-14.

Table 5-2 and Figure 5-14 also refer to three other voltages. One controls the constant gain of the first amplifier stage (AGC₁) and two control alternate gains of the third amplifier stage (AGC₃). At any time, the total gain of the receiver section is a composite of the constant AGC₁ and AGC₃ gains and the varying AGC₂ gain.

The initial gains are imposed on the hardware before the time of the TDR or AGC trigger pulse. The AGC trigger pulse preceeds the high-voltage pulse generation trigger by 16.0 microseconds to allow the receiver AGC circuits time to settle before digitizing ultrasonic reflections.

The rate of gain change is imposed to control how rapidly the gain compensation factor increases with time from its initial set value. The rate is factory preset to 1.25 decibels (dP) per one-sixteenth inch to compensate for the average depth attenuation in tread rubber. The largest AGC2 gain is imposed to limit post-signal noise amplification. The value required depends on amplifier or TDP input capacity, the maxi-

Table 5-2. Peceiver Section Control Voltages

LAEEL	ADDPFSS	DESCRIPTICN
RCM_INGALN	F780	Gain control for age(1)
RCM_FN_GAIN	E782	Gain control for age(2,c)
ECM_FK_GAIN	E784	Gain control for age(2,a)
PON_SLOPE	E736	Slope control for age(2,t)
ROM_OUTGAIN	E788	Gain control for age(3) when GPP rot active
CRP_OUTCAIN	e78a	Cain control for age(3) when CPP active





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mum depth of tire to be inspected by the TQM, and the rate of gain change. For these reasons, the settings of largest gain and rate of gain change are interactive. The largest gain is factory preset to be imposed at approximately twenty-sixteenths inch of tread depth.

The only parameter the CPU uses to control the AGC circuit during normal TQM operation is the ACC_1 gain. Pecause each of the three amplifiers in the AGC circuit acts independently, variation of the AGC_1 gain will not alter the rate of gain change or the value of the largest gain. Note in Figure 5-14 that the time when largest gain is imposed can be altered, but not its value. As a consequence, CPU control of the AGC_1 gain effectively yields proportional CPU control of any gain throughout the sampled signal domain.

The CPU exerts its control of the AGC at a 3-Hz rate, but it varies the value of the AGC₁ gain control parameter only during TEST calibrations. This value is altered by a hardware/software servosystem to compensate the TQM for variations in the material being inspected or monitored. As can be inferred from Figure 5-14 adjustment of the value of the initial gain will alter the gain compensation factor throughout the signal period in a linear and predictable manner.

By monitoring a precisely machined reference block of material whose acoustic attenuation is invariant with temperature, a known and universally invariant ultrasonic reflection amplitude can be received and compared to a setpoint amplitude for the purpose of automatically adjusting the value of the initial gain. A reference block of GRP meets all requirements of invariance, and two are supplied with each TQM. The TQM holds eight setpoint amplitude values in EEPRCM, one for each of six inspectable tire types and two for reference or calibration blocks. Table 5-3 lists these setpoints. Table 5-3(a) lists the primary gain calibration setpoints (described in more detail in par. 5.3.5.).

The appropriate setpoint is selected from the front panel setting of TIRE TYPE as it exists at the time calibration. The calibration proceeds in a manner outlined in Figure 5-15. The second AGC3 voltage listed in Table 5-2 acts as an attenuation during such calibration to compensate for the extreme reflectivity of the GPP block. As long as the average received reflection amplitude differs from the setpoint, the CPU will increase or decrease the value of the ACC1 gain so as to drive the reflection amplitude toward equaling the setpoint.

As this process proceeds, the amplitude of the received reflection is displayed on the two left-most digits of the front panel. If the expected reflection occurring between eleven-sixteenths and thirteensixteeths inches time equivalent is not detected, the CPU will issue a "-CAL" display message to indicate an improperly received calibration signal. The TQM will request such gain calibration for any of the following conditions: Table 5-3. Gain Calibration Setpoint Values*

ADDRESS

TIRE TYPE

AMPTABLE	PSR I	E790	Passenger Steel-Belted 1
	TTXTI	E792	Truck Textile-Plied 1
	TSRII	E794	Truck Steel-Belted 1
	GRP	E795	Glass-Reinforced Plastic Block
	RN	E798	Pubber/Nylon Block
	PSR II	E79A	Passenger Steel-Belted 2
	TTXTII	E79C	Truck Textile-Plied 2
	TSRII	E79E	Truck Steel-Eelted 2

DESCRIPTION

(a) Primary Gain Calibration Setpoints

TIR	E TYPE	ADDRESS	DESCRIPTION
ALTTABLE	PSR I	E7A0	Passenger Steel-Pelted 1
	TTXTI	E7A2	Truck Textile-Plied 1
	TSRI	E7A4	Truck Steel-Belted 1
	GRP	E7A6	Glass-Reinforced Plastic Block
	RN	E7A8	Rubber/Nylon Elock
	PSR II	E7AA	Passenger Steel-Belted 2
	TTXTI	E7AC	Truck Textile-plied 2
	TSRII	E7AE	Truck Steel-Belted 2

(b) Secondary Gain Calibration Setpoints

*TQM Reading of Setpoints = Setpoint/4.23 Example for GRP (refer to listing in Appendix): 15 = 63/4.23 where $63_{10} = 3F_{16}$



Figure 5-15. Gain Calibration
- selection of new tire type,
- 15 minutes elapsed time from prior calibrating, or
- initial TCM turn on.

5.2.4. Signal Capture. The received and amplified signal is digitized by a very fast analog-to-digital converter and RAM system. This is the TQM's TDR and it is initialized and triggered by the CPU detection of a software grant to do sc. Triggering occurs at the TDR trigger time of the next 100-Hz pulse service request. Software grants are issued at a 3-Hz rate so that the TDR captures only 3 of 100 signals returned each second.

While the signal is being captured, the TDP hardware issues a busy signal to inform the CPU that the capture process is underway. Signals are sampled at a 20-Megahertz (MHz) rate and, since the ultrasonic information being acquired has very little spectral content in excess of 1 MHz, this rate is sufficient to obtain an amplitude sample of the signal accurate to \pm 1.2 percent of the actual amplitude. The use of a high sampling rate for capture also increases the accuracy of time measurements within the signal. The CPU software eventually uses time measurements to identify tire structures from their reflections and to measure tread depth.

5.3. Signal Processing

5.3.1. General. The sampled and digitized ultrasonic signal can now be processed to extract displayable information about the tire being inspected. If the selected display is QUALITY or THICK, the sampled signal is generally subjected to two stages of data reduction and feature extraction, a stage of saturation detection and disposition, stages of time compensation for temperature and amplitude compensation for depth, isolation of significant features, and classification of remaining features according to structural characteristics appropriate to the TIRE TYPE selected. Finally, the relevant information is measured from the set of features of relevant classification and is displayed. This process, which runs at a 3-Hz rate, is summarized in Figures 5-16 through 5-18.

If the selected display is TEMP, the sampled ultrasonic signal is not processed. Instead, the thermocouple is read and an averaged temperature is processed for display. This process, also running at a 3-Hz rate, is summarized in Figure 5-19.

5.3.2. Reflection Feature Extraction. Software processing of the digitized signal starts with the transfer of a selected window of the captured signal from the TDF memory to a workspace memory. The transferable portion of the captured signal is selected in the two-step process illustrated in Figures 5-20 through 5-23. First, the CPU is directed to begin examining the TDF memory out to an address offset of

Process QUALITY Display : v yes Holding ANALYZE Display? -----> Exit no : ν Process Reflection Feature Extraction (Flowchart 3.4) V Process Search for Reflection Saturation (Flowchart 3.5) v Process Envelope Feature Extraction (Flowchart 3.6) v GRP yes "Tire Type" _____ ? v pa(a) (- Pmax no : tp(a) (- Tmax yes V v R/N "Tire Type" ------? 1 no : υ Process Saturation Disposition (Flowchart 3.2a) Process Amplitude and Time Compensation (Flowchart 3.7) V Process Windowing : (Flowchart 3.8) : V V P3 (- Pa P2 (- P3 Process Classification (Flowchart 3.9) V 2 _____! < U Process Depth Computation (Flowchart 3.2b) V Process Preparation of P3 Amplitude Display . V Exit

Figure 5-16. Quality Display Processing

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Process DEPTH Display . V Holding ANALYZE Display? -----> Exit no : V Process Reflection Feature Extraction (Flowchart 3.4) V Process Search for Reflection Saturation (Flowchart 3.5) V Process Envelope Feature Extraction (Flowchart 3.6) V GRP yes "Tire Type" ? V pa(a) (- Pmax tp(a) (- Tmax no : V R/N - V yes "Tire Type" ? . no : 2 V 2 Process Saturation Disposition 2 (Flowchart 3.2a) U Process Amplitude and Time Compensation 2 (Flowchart 3.7) 2 V 2 Process Windowing 8 (Flowchart 3.8) 2 V V Process Classification P3 (- Pa P2 (- P3 (Flowchart 3.9) V 2 ، هي هه دي مه هه جب من منه هه هه هو هو هو هي ه (----U Process Depth Computation (Flowchart 3.2b) v Process Preparation of D Depth Display 8 v Exit

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Figure 5-17. Thickness Display Processing



Figure 5-18. Thickness Display Computation

Process TEMP Display . V Delay 480 us Turn off "Out-of-Temp" led V yes Temperature Circuit Busy? -----> Start Next Conversion no : 8 V yes V Open Probe? ------Exit no : V 2 Read Temperature : V yes Overrange? -----> no : V yes Polarity Positive? -----. 2 no:: V:: 2 V Negate Temperature Reading : Prepare "----" message V I . 2 V U Turn on "Out-of-Temp" led Start Next Conversion Start Next Conversion Insert Latest Temperature Reading into Array : Compute Average of Arrayed Readings V (- (9/5)*[([TEMP_SLOPE]/4095)*(Average)] Exit T +32+[TEMP_OFFSET] : U. yes Was Polarity Read Positive? -----no : ν 5 Negate T V Frepare Displayable "-" Prepare Displayable " " v LAST_TEMP_READ <- T-30 V yes 115 > T >= 30? -----no : Turn on "Out-of-Temp" led 2 U 5 A rest was an end on end end on end v Process Preparation of Temperature Display 1 V. Exit

Figure 5-19. Temperature Display Processing



Figure 5-20. Data Selection, Rectification, and Smoothing

PULSERINGOUT. PEAKTBL is memory where . NOISEAMP, & NOISEAMP, &VNOISEWIDTH selected fromC (- 63EEPROM at time of tirei (- 1 (PEAKTBL index))type selection.t (- EPULSERINGOUT)See Table 3.1K (- 1280 - t) V reflection features are held. J (- MASDAT + t V A set of the s v ກຕ d(j) >= [NOISEAMP]? -----. yes: no V . U. $\frac{nc}{ts(i)} = 0? t(-t-1)$ yes : V 8 Close Peak (threshold) ts(i) (- t : (Flowchart 3.4c) pa(i) (- d(j) 2 U t (- t + 1 tp(i) (- t 2 V V 2 ----- (------ (= 0? ------V yes V yes d(j+1) { d(j)? -----. yes V 6 8 ---- d(j+1) > d(j)? 2 . V no: Sign no V V 2 no Sign : Change? ----- Change? : yes : : yes : V 8 v Multiple Lookahead Multiple Lookahead ŝ 8 (Flowchart 3.4d) (Flowchart 3.4d) : : V v 2 V . Sign no no Sign 2 yes: yes: V: Close Peak (contour) (Flowchart 3.4c): V no C = CCChange? ----- Change? yes : v pa(i) (- d(j-1) tp(i) (- t 2 C = Q? -----' <-----' yes : V : : t <- t + 1 2 K (- K - 1 2 2 no V 8 -/:/--------- K = 0? yes V : ----> Set EOD markers <------> . V Exit

Process Reflection Feature Extraction (Cont.)

Figure 5-21. Reflection Feature Extraction



Figure 5-22. Peak Closure



Figure 5-23. Trend Lookahead

value stored in EEPROM address E7D2 (AGC TRIG OFFSET). During this examination of the time after the TDP start and before the AGC trigger (approximately 6 microseconds), the CPU accumulates all captured values lying within a ±10-percent band around the TDP centroid value of 128. It then computes the measured analog ground (g) of the receiver section by dividing the accumulation by the number of values accumulated. This ground value is stored in RAM memory FADE (GEOUND).

The CPU then begins to transfer data to the workspace memory MASDAT from a TDR memory address offset by the value stored in EEFROM address E7D4 (MAINBANG OFFSET). This represents a point sampled at the start of the "main bang" reflection of the transducer.

The ensuing transfer of data is itself a triple process as illustrated in Figure 5-20. Starting from that point in TDP memory which corresponds to the acquisition time of the "main bang" and continuing for the next 1,280 bytes (representing 64 microseconds of acquisition time), the CPU subjects each sampled value (d_j) to the following three steps in sequence:

(1) sampled value (d_j) is normalized to measured analog ground value (g=A/K) and then converted to an absolute positive number. This is rectification.

(2) Rectified value d_j-g is added to the time correspondent value (di) in the workspace memory and then divided by 2. This is dynamic averaging, or smoothing.

(3) Dynamically averaged value $d_j-g + d_i$ is then stored in memory where d_i was accessed in step (2) and the data acquired at the next sample times j+1, i+1 are treated similarly.

After 64 microseconds of acquired samples have been dynamically averaged, the CPU proceeds to reduce the amount of data it is required to process by extracting the features of the captured ultrasonic reflections according to logic outlined in Figure 5-21. The point in the data at which it begins the reduction is determined by a time offset used to bypass the captured transducer ringout signal. The size of this ringout "mask" depends on the tire type selected at the TQM front panel and its value is held in RAM memory PULSERINGOUT (FA90). The values held in EEPRCM are listed in Table 5-4(a).

The reduction occurs by characterizing each rectified reflection (describable by approximately 40 numbers) with a set of 4 numbers: reflection maximum amplitude $p_a^r(j)$, the time of its occurrence $t_p^r(j)$, the reflection start time $t_s^r(j)$, and its end time $t_e^r(j)$. All these times are referenced from the acquisition time of the start of the "main bang." Each reflection of amplitude greater than a characteristic threshold, and of width greater than a characteristic time, is characterized this way. The characteristic thresholds and times used depend

Table 5-4. Reflection Feature Extraction Parameters

ADDRESS

LABEL	ADDRESS	DESCRIPTION
PSR I RINGOUT	E804	Passenger Steel-Belted 1
TTX I RINGOUT	E844	Truck Textile-Plied 1
TSR I RINGOUT	E884	Truck Steel-Belted 1
PSR II RINGOUT	E8C4	Passenger Steel-Belted 2
TTX II RINGOUT	E904	Truck Textile-Plied 2
TSR II RINGCUT	E944	Truck Steel-Belted 2
GRP RINGOUT	E984	Glass-Reinforced Plastic Block
RN-RINGOUT	E9C4	Pubber/Nylon Block

(a) Main Pang Ringout Mask

LABEL

DESCRIPTION

E800	Passenger Steel-Belted 1 Pre-Retread
E802	Passenger Steel-Belted 1 Post-Retread
E840	Truck Textile-Plied 1 Pre-Retread
E842	Truck Textile-Plied 1 Post Petread
E880	Truck Steel-Belted 1 Pre-Retread
E882	Truck Steel-Eelted 1 Post-Fetread
E8C0	Passenger Steel-Belted 2 Pre-Retread
E8C2	Passenger Steel-Eelted 2 Post-Retread
E900	Truck Textile-Plied 2 Pre-Retread
E902	Truck Textile-Plied 2 Post-Petread
E940	Truck Steel-Belted 2 Pre-Retread
E942	Truck Steel-Belted 2 Fost-Retread
E980	Class-Reinforced Plastic Block
E9C0	Rubber/Nylon Block
	E800 E802 E840 E842 E880 E882 E8C0 E8C2 E900 E902 E940 E942 E980 E920

(b) Maximum Noise Amplitude from Ground

LABEL	ADDRESS	DESCRIPTION
PSR I FRE NWID	E801	Passenger Steel-Belted 1 Pre-Retread
PSRIPSTNWID	E803	Passsnger Steel-Pelted 1 Post-Retread
TTX I PRE NWID	E841	Truck Textile-Plied 1 Pre-Retread
TTXTIPSTNWID	E843	Truck Textile Plied 1 Post-Retread
TSRIPRENWID	E881	Truck Steel-Belted 1 Pre-Petread
TSRIPSTNWID	E883	Truck Steel-Belted 1 Post-Retread
PSR II PRE NWID	E8C1	Passenger Steel-Belted 2 Pre-Petread
PSRIIPSTNWID	E8C3	Passenger Steel-Belted 2 Post-Retread
TTX II PRE NWID	E901	Truck Textile-Plied 2 Pre-Petread
TTXIIPSTNWID	E903	Truck Textile-Plied 2 Post-Retread
TSR II PRE NWID	E941	Truck Steel-Belted 2 Pre-Retread
TSR II PRE NWID	E943	Truck Steel-Pelted 2 Pre-Petread
GRP PRE NWID	E981	Glass-Reinforced Plastic Block
RN PRE NWID	E9C1	Rubber/Nylon Block

(c) Maximum Noise Width

on the TIRE TYPE selected at the TQM front panel and are held in EEPROM with the characteristics shown in Tables 5-4(b) and (c).

The product of signal rectification is held in memory as a tabular array of the extracted features of the reflections. This is accessible to observation on a printer by procedures discussed in par. 5.6. From this array, the reflection data is transferred to further stages of signal processing.

5.3.3. Automatic Saturation Detection. The reflection features extracted by procedures described in the preceeding section are next searched for evidence of potential signal saturation. This search, outlined in Figure 5-24, is performed at this late processing stage for reasons of efficiency. The data population has been substantially reduced, the pertinent data (i.e., peak amplitudes) isolated, and sources of unavoidable system saturation (i.e., main bang pulse, AGC, and TDR triggers) removed. Using terminology introduced in the preceding section, the test for saturation is:

> $|\mathbf{g}| + \mathbf{d}_{i} \ge 127$ Saturation $|\mathbf{g}| + \mathbf{d}_{i} \le 127$ No Saturation

Detection of no saturation allows monitoring to proceed normally. Detection of saturation sets a condition flag which has consequences described in par. 5.3.5.

5.3.4. Feak Envelope Feature Extraction. Ultrasonic reflection data which has been rectified and smoothed contains more information than is necessary or practical for the CPU to make real-time classifications. Therefore, the first stage of the TQM pattern processing is the reduction of the captured data to a series of descriptive features. This stage has been discussed in par. 5.3.2. and it creates, for ultrasonic reflection, a set of four numbers describing that reflection. These numbers, or features, are:

- t^r_S(j) the time at which reflection j rises above noise threshold
- pr(j) the peak amplitude of reflection j
- $t_{\mathbf{F}}^{\mathbf{F}}(J)$ the time at which reflection j peaks
- tf(j) the time at which reflection j falls below noise threshold

A further reduction of the processing data base occurs in a second stage, that of extracting the features of reflection envelopes from the features of reflections. This second stage proceeds as illustrated in Figure 5-25 and is controlled by the number of reflections, the capacity of envelope feature memory, the reflection peak amplitude (p_A^E) contours,



Figure 5-24. Saturation Monitoring

and by three time limits defining the minimum interenvelope gap and the minimum and maximum envelope width.

Referring to Figure 5-25, a brief tracing of the process flow is as follows:

- During initialization, the structure envelope feature memory is cleared and the memory holding the largest peak amplitude (P_{max}) and its time of occurrence (T_{max}) is reset to zero.
- If the POST-RETREAD mode is enabled, processing of tread reflections is done according to the TEST LOCATION mode set. If the TEST LOCATION is that of MIDLINE inspection, the reflection features are ignored until a reflection with a peak time greater than or equal to a time threshold is detected. This time threshold for assuring cleanliness of the midline tread reflections is dependent on TIPE TYPE and is selected from the Table 5-5(a) parameters stored in EEPPCM. If the POST-RETREAD mode and SHOULDER TEST LOCATION are enabled, the porosity envelope feature memory is cleared and, until either it is filled or there are no more reflections detected in the porosity time window, reflection features will be transferred from the reflection features memory to the porosity envelope feature memory. The width of the porosity time window is controlled by two parameters dependent on TIRE TYPE. These parameters are a minimum, or near porosity time and a maximum, or far porosity time and, depending on TIRE TYPE, and are selected from the parameters of Tables 5-5(b) and (c) stored in EEPROM. Figure 5-25 illustrates how these windows are used. If the PETEEAD MODE set is PRE these windowing stages are passed by.

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- A demarcation time t_2 is computed equal to 1.875 times the start time $t_s^r(1)$ of the first reflection. This is to eliminate from consideration for largest peak F_{max} any reflections occurring at times during which second reflections can occur. Then, until the structure envelope feature memory is filled or until there are no more reflections detected, reflection features will be processed into envelope features. The factor 1.875 is intrinsic to the TQM firmware and can not be altered.
- The details of the following process are illustrated in Figure 5-25. If any remaining reflections are detected, the features of the envelope to be characterized are initialized by a default transfer of the features of the next reflection j into the envelope i features memory. Until the envelope characterization process ends, the envelope start time te(i) is held constant, the envelope end time te(i) is updated using the latest tr(j), and the envelope

---+ pa() is largest amplitude tp() is time of largest amplitude r (- r ۲ ENVELOFEGAP, MINIMUMWIDTH, ENVELOPEWIDTH are selected from EEPROM at time of tire type Index r sweeps through PEAKTBL memory until End-of-Data (EOD) flag detected. tp(r)) = [NEARFORDTIME]? ----) õ that holds envelope features Index n sweeps through memory detected before 2nd rebound until seven envelopes have been characterized. Clear next available porceity array selection. See Table 3.3 Pmax is largest amplitude tp(r))= [FARFOROTIME]? Tmax is time after "main FARCLEANTIME, NEARPOROTIME, FARPOROTIME selected from EEPROM at time of tire type selection. bang" that Pmax occurs. ts() is start time ŝ tp() is time of te() is end time (- ts(r) (- pa(r) (- tp(r) (- te(r) --- EOD? (--= 82 r (-1 > 5 > yes i 20 s s ts (n) limit. pa (n) te(n) tp(n)yes ĝ ì See Table 3.2 yes ł Yeu no V > > ۲ ۲ Î t ts(r) - te(n-1)) = [ENVELOPEWIDTH]? ---) Exit .- te(r) - ts(n))= [MINIMUMMIDTH]? r = 8 ? ----) Exit Î yes yes yes yes r (- r + 1 (-te(n-1))- te(n-1) n = 87 ---n (- n + 1 n = 17 ----(- ts(r) - + - te(n) (- te(r) 1+1) E007 ----9 I na V v V > > yes V 202 yes r yea ۶ 5 t = (n) te(n) pa (n) tp(n) es ro V --- tp(r))= (FARCLEANTIME]? ĝ Ĩ ----> Inspecting Shoulder? Уeв yes Exit Ŷ ---- EOD? yesı te(n)) = [ENVELOPEGAP]? ---10 10 Process Envelope Feature Extraction rio V Clear next available envelope array Charige? .-) te(r) - ts(n))= [ENVELOPEWIDTH]? yes î tp(r))= 1.075*ts(1)7 (-* Sign > yes Change? _____ (-----te(n) (- te(r) (---.---- pa(r) (pa(r+1)? V ğ yes yes yea -- pa(r) = pa(r+1)? pa(r.) = pa(n)? (---- pa(r) (pa(n)? yes pa(n) (- pa(r) ра(г))= Риах? <-r + 1 tp(n) (- tp(n) Риан (- ра(г) Тиак (- tp(r) Retread Mode? ---(- ţa(r) (- te(r) (- pa(r) (- tp(r) ---> EOD? ---1 --- E007 1 r -> r r (- 1 Рыах,Тиах (- 0 yes V Exit > vo v vo v > v o'r > усв : > > > 70 < > 101 > vo Vo > v or > 20 5 0 2 ta (n) tp (n) te(n) pa(n) yes уев yes on V --) <u>___</u> ۱ J ts (r) Sign v ou > ů L yes •• ... -...

Figure 5-25. Envelope Feature Extraction Parameters

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Table 5-5. Porosity Isolation Windows

LABEL	ADDRESS	DESCRIPTION
PSR-I FCLNTIME	E80C	Passenger Steel-Belted 1
TTX I FCLNTIME	E84C	Truck Textile-Plied 1
TSR-I-FCLNTIME	E88C	Truck Steel-Belted 1
PSR-II-FCLNTIME	E8CC	Passenger Steel-Belted 2
TTX II FCLNTIME	E90C	Truck Textile-Plied 2
TSR-II-FCLNTIME	E94C	Truck Steel-Belted 2
GRPFCINTIME	E98C	Glass-Reinforced Plastic Block
RN_FCLNTIME	E9CC	Rubber/Nylon Block

(a) Maximum "Garbage" Time Limits

LABEL ADDRESS

DESCRIPTION

PSR-I-NPORTIME	E80E	Passenger Steel-Belted 1
TTX-I-NPORTIME	E84E	Truck Textile-Plied 1
TSR-I-NPORTIME	E88E	Truck Steel-Belted 1
PSR-II-NPORTIME	ESCE	Passenger Steel-Belted 1
TTX-II-NPORTIME	E90E	Truck Textile-Plied 2
TSR-II-NPORTIME	E94E	Truck Steel-Belted 2
GRP-NPORTIME	E98E	Glass-Reinforced Plastic Block
RN-NPORTIME	E9CE	Rubber/Nylon Block

(b) Minimum Porosity Time Limits

LA	BEL	
----	-----	--

DESCRIPTION

E810	Passenger Steel-Belted 1
E850	Truck Textile-Plied 1
E890	Truck Steel-Belted 1
E8D0	Passenger Steel-Belted 2
E910	Truck Textile-Plied 2
E950	Truck Steel-Belted 2
E990	Glass-Reinforced Plastic Block
E9D0	Rubber/Nylon Block
	E810 E850 E890 E8D0 E910 E950 E990 E9D0

ADDRESS

(c) Maximum Porosity Time Limits

peak amplitude and peak time $[p_{a}^{e}(i), t_{p}^{e}(i)]$ are updated from $[p_{1}^{e}(j), t_{p}^{e}(j)]$ only if $p_{1}^{e}(j)$ is greater than any prior $p_{1}^{e}(j)$ since starting the envelope. During this search, P_{max} and T_{max} are also being updated if any $p_{a}^{e}(i)$ is found greater than P_{max} . This process stops once any $t_{p}^{e}(i)$ exceeds t_{2} , the second reflection limit. An envelope is closed by one of three conditions.

(1) if the difference between the latest $t_e^r(j)$ and $t_e^r(i)$ is greater than or equal to the maximum allowable width. This is closure by width.

(2) if the contour of peak reflection amplitudes inflects from negative slope to positive. This is closure by contour.

(3) if the difference between the next $t_s^r(j+i)$ and $r_s^r(j)$ is greater than or equal to the minimum allowable gap within an envelope. This is closure by gap.

Of course, closure will also occur preemptorily if no more reflections are detected. Closures by gap or width are controlled by parameters selected by tire type from EEPRCM and listed in Table 5-6. Closure by contour is normally controlled by the profile of the data itself. However, in those unusual cases where the reflections from a single tire structure exhibit internal contours, a minimum envelope width threshold is invoked to assure that such odd tire structures are not represented by more than one envelope. In such cases, closure by contour will be disallowed if the resulting envelope width is less than the minimum width value. The active minimum width is selected by tire type from values stored in EEFRCM and listed in Table 5-6(b).

At the termination of the envelope feature extraction process, a set of envelopes will each be characterized by $t_s^e(j)$, $p_a^e(j)$, $t_p^e(j)$, $t_s^e(j)$ such that $t_s^e(i) = t_s^r(j)$, $t_s^e(i) = t_s^r(j+k)$, $p_a^e(i)$ is the largest $p_a^r(m)$ in the interval $j \le t_s^r(j+k)$, and $t_s^e(i)$ is the corresponding $t_s^r(m)$.

The influence of the envelope width and the interenvelope gap time limits on the envelope closure process can be understood more easily by studying Figures 5-26 and 5-27. Both figures present a schematic representation of how reflection features (a) from a tire with two steel belts (A,E) and body plies (C) can be combined into envelopes (b, c, d). Figure 5-26(b) illustrates how the reduction of the width limit can close envelopes too soon, yielding erroneous time and peak amplitude values for this and subsequently closed envelopes. Similarly, making the width limit too large can combine reflections from distinct casing structures into one envelope (Figure 5-25(d)) yielding other errors in peak amplitude, times, and tabulation.

In the case illustrated, three casing structures (A, E, C) are transformed into three envelopes, but poor adjustment of the envelope width

Table 5-6. Envelope Feature Extraction Farameters

ADDRESS

LABEL	ADDRESS	DESCRIPTION
PSR I ENVGAP	E806	Passenger Steel-Belted 1
TTX I-ENVGAP	E846	Truck Textile-Plied 1
TSRTITENVGAP	E886	Truck Steel-Belted 1
PSR II ENVGAP	E8C6	Passenger Steel-Belted 2
TTX II ENVGAP	E906	Truck Textile-Plied 2
TSRIITENVGAP	E946	Truck Steel-Pelted 2
GRPENVGAP	E986	Glass-Reinforced Plastic Block
RN_ENVGAP	E9C6	Rubber/Nylon Elock

(a) Interenvelope Gap

LABEL

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DESCRIPTION

PSR I WIDTHMIN	E808	Passenger Steel-Belted 1
TTX I WIDTHMIN	E848	Truck Textile-Plied 1
TSRTIWIDTHMIN	E888	Truck Steel-Belted 1
PSR II WIDTHMIN	E8C8	Passenger Steel-Belted 2
TTX II WIDTHMIN	E908	Truck Textile-Plied 2
TSR II WIDTHMIN	E948	Truck Steel-Belted 2
GRP WIDTHMIN	E988	Glass-Reinforced Plastic Block
RN WIDTHMIN	E9C8	Rubber/Nylon Block
		v v

(b) Narrow Envelope Limit

LABEL	ADDRESS	DESCRIPTION
PSR I ENVWIDTH	E80A	Passenger Steel-Belted 1
TTX I ENVWIDTH	E84A	Truck Textile-Plied 1
TSRIIENVWIDTH	E88A	Truck Steel-Belted 1
PSR II ENVWIDTH	E8CA	Passenger Steel-Belted 2
TTX II ENVWIDTH	E90A	Truck Textile-Plied 2
TSRII ENVWIDTH	E94A	Truck Steel-Belted 2
GRP EN WIDTH	E98A	Class-Reinforced Plastic Plock
RNEENVWIDTH	E9CA	Rubber/Nylon Block

(c) Maximum Envelope Width







Figure 5-27. Envelope Feature Extraction Dependance on ENVELOPEGAP

parameter causes errors in the amplitude measure of the second steel belt. Figure 5-27 shows the errors that can result from improperly adjusted interenvelope gap time limits. Too small a time limit can cause the reflections from distinct casing structures to be combined into one envelope (Figure 5-27(b)). Similarly, too large a gap limit can engender the creation of unwarranted "null" envelopes which yield tabulation and amplitude errors (Figure 5-27(d)).

In the case illustrated, three casing structures (A, B, C) are transformed into two or four envelopes depending on how the interenvelope gap parameter is adjusted. In the two-envelope case, the second steel belt is completely merged into the first envelope along with the first steel belt. In the four-envelope case, a "null" envelope has been interposed between the first and second steel belt envelopes which will result in a serious misclassification by the CPU.

5.3.5. Saturation Disposition. If the TQM is in the GRP or P/N maintenance mode, the saturation condition flag is ignored and TQM operation continues normally. This is allowed because signal saturation is inherent in the materials monitored in these maintenance modes and such saturation in no way degrades the validity of the information processing. The saturation condition flag is also ignored if the TQM is in a textile TIRE TYPE inspection mode (TRUCK/T 1 or 2) since the saturated signal does not affect the information being processed. However, if the TQM is in one of the four steel-belted TIRF TYPE inspection modes (TPUCK/S 1 or 2, FASS/S 1 or 2), the set saturation condition flag may have an effect depending on the recent inspection history of the TQM, as illustrated in Figure 5-17.

If the saturation is detected after the TIRE TYPE has been selected and gain calibrated and before the first analysis has been accomplished (by pushing the ANALYZE button and observing an inspection result), the TQM will be forced into a calibration request state signaled by a flashing "-CAL" message. When the operator responds by performing a TEST CAL gain calibration, the TQM will behave as described in par. 5.5.3. However, with the saturation condition flag set, an array of calibration setpoints different from those portrayed in Table 5-3(a) will be accessed. These setpoints will be typically lower in value to alleviate the originating saturation problem. Table 5-3(b) lists these alternate setpoints as they are stored in the EFPRCM. Until a tire type is re-selected or the TQM is turned off, these alternate setpoints will be enabled.

Because the TQM can automatically detect saturation and change state accordingly, and because the GPP reference block normally reflects saturated signals, the operator must set the TEMP display mode before placing the transducer on the reference block for TEST calibration of a tire type. This defeats ultrasonic acquisition and, hence, saturation detection and its subsequent effects. The operator thereby assures that the simple act of gain calibration will not switch the TQM to an unwanted setpoint value. Conversely, the operator must also remove the transducer from the reference block before selecting another display mode.

On the other hand, if an analysis has been successfully accomplished since the last gain calibration, or if the TQM is already calibrated to the alternate gain setpoint of the TIRE TYPE selected, the saturation condition flag will be ignored. The philosophy behind this feature is that if a subset of tires of the selected TIRF TYPE exhibits a higher reflectivity than the usual tires of the TIRE TYPE selected, and if a group of such high-reflectivity tires is being inspected, then the first tire to be inspected from this group is likely to be representative of the group. Its high reflectivity will create the saturation which, in turn, will trigger the TQM to go into a state more consistent with the inspection of this group of tires. If, on the other hand, the first tire to be inspected is representative of a group of normally reflecting tires, the TQM will not detect saturation and will maintain the principal gain setpoint of the TIRE TYPE selected. It will also ignore subsequent saturation conditions until a future selection of TIRF TYPE, in effect presuming that such saturations are not representative of the tire group being inspected.

5.3.6. Temperature/Thickness Compensations. After reflection envelope features have been extracted, the values of the maximum amplitudes $p_{e}^{a}(i)$ are next adjusted to standard conditions. This is necessary to compensate for the attenuation of ultrasound with distance of travel through rubber and to compensate for attenuation and velocity variations with temperature in rubber. The compensation factor imposed is selected as a function of the value of the last calibrated tread temperature and of the depth of each reflection envelope as measured by the times $t_{e}^{e}(i)$ at which each reflection was acquired. Because the velocity of ultrasound varies significantly with temperature, these times must be corrected to a standard temperature value. This is:

$$t_{p}^{e}(i) = t_{p}^{e}(i) \cdot [1 + \frac{SHIFTPEPTEMP}{2.125} (7C-T)] i = 1,...,7$$

The constant values 70 and 2.125 are respectively, the standard temperature (^{O}F) and its associated inverse velocity in rubber (sec/(1/16 inch)). The parameter SHIFTPEPTEMP is stored in FTPPCM at ETEA and is alterable using techniques described in par. 5.7.2.3. Its present value is hexadecimal 28, representing a velocity variation with temperature of 0.065 us/in/ ^{O}F .

The times thus corrected and the calibrated temperature serve as indices cross-referencing a look-up table of peak amplitude compensating factors. The TQM is delivered with a set of three preprogrammed temperature/thickness compensation tables in EEPROM, one table for each tire type. Selection of a TIRE TYPE automatically selects the appropriate compensation table. The entries in these tables can be altered by procedures presented in par. 5.7.2.3.

Thus, as part of its pattern recognition processing, the TQM executes simple multiplicative compensations of ultrasonic reflection amplitudes for a common temperature and for respective temperature-compensated depths. The processing logic is outlined in Figure 5-22. The envelopes are now ready to be isolated by the application of appropriate "windows."

5.3.7. Windowing. After all the maximum amplitudes of reflection envelopes have been compensated for temperature and respective depth, the envelopes' features are searched for time discrepancies. This is done to prevent features of multiply-rebounding ultrasonic reflections from contaminating the feature sample. It also helps to exclude features from the transducer ringout and, for shoulder inspections, to separate tread and casing features. This process of time "windowing" is illustrated in Figure 5-29 and creates three TIRF TYPE-dependent windows:

- Passenger steel radial (T_{max}-5us) ≤t ≤ (T_{max}+10us)
- Truck steel radial $(T_{max}-10us) \leq t \leq (T_{max}+12us)$
- Truck textile bias 10us $\leq t \leq (t_p^e(a) + 14us)$

Referring to Figure 5-29 the procedural dependence on tire type is obviously the existence of two entry points and, less obviously, the presence of the parameters NEARSTRUTIME and FARSTRUTIME. The values of these two parameters stored in RAM are selected at time of TIRE TYPE selection from all the tire-type-dependent values stored in EFPPCM (Table 5-7).

The parameter FARSTRUTIME is always used as an offset from some critical peak time, whereas the use of the parameter NEARSTRUTIME is either an offset or an absolute limit depending on whether the tire is of steel or textile construction respectively. The critical peak time is also dependent on tire type. For textile tires, it is the time $t_p^e(a)$ of peak amplitude $p_a(a)$ of the first reflection envelope P_a in the window. For steel tires, it is the time T_{max} of the largest amplitude P_{max} envelope extracted as discussed in par. 5.3.4. Therefore, as illustrated in Figure 5-29 for all tire types, those envelopes with peak times less than the type-dependent minimum structural time are eliminated from consideration.

The notation P_a , P_b ,... P_g refers to the seven sets of envelope features possible with each P_i referring to the set of features $t_s^e(i)$, $p_a^e(i)$, $t_p^e(i)$, $t_s^e(i)$ of envelope i. Once those envelopes occurring earlier than the minimum time are eliminated, envelopes with peak times larger than the type-dependent maximum structural time are sought. Note that for steel times a decision is made as to whether the computed offset time or the second reflection time is to be used as the maximum.

No such decision is made for textile tires due to the necessity of detecting at least two envelopes for precise classification, even if the second envelope is a second reflection of the first. When envelopes beyond the latest structural time are detected, they are eliminated and the envelopes, thus "windowed," have been prepared for classification. Process Amplitude and Time Compensation ν no Inspecting Shoulder? ----yes : . V Compensate porosity reflections : (Flowchart 3.7a) 2 2 : V . υ Compensate structure envelopes (Flowchart 3.7a) 1 V Exit

```
Compensate xxx xxx
              2
              ν
           j <− 1
              ν
              V
2
      ts(j) (- ts(j)*(2.125+[SHIFTPERTEMP]*(70-T))/2.125
2
      tp(j) (- tp(j)*(2.125+[SHIFTPERTEMP]*(70-T))/2.125
2
      te(j) (- te(j)*(2.125+[SHIFTPERTEMP]*(70-T))/2.125
2
2
      id(j) (- [tp(j)/2.125]-4
2
         iT (- (T-30)/5
2
2
         Cf (- F(id(j), iT))
         Cg (- F(id(j), iT+1)
2
2
         Cf (- Cf + ((Cg - Cf)*(T - 85*iT)/5))
2
              V
8
      pa(j) (- BCD[Cf*pa(j)]
2
              V
2
          j <− j + 1
2
              V
       no
8
   ----- j = 8?
         yes :
              V
           Exit
```

Figure 5-28. Amplitude and Time Compensation



Figure 5-29. Windowing Flowchart

Table 5-7. Structure Isolation Windows

LABEL	ADDRESS	DESCRIPTION	
PSR I NSTRTIME	E812	Offset before Pmax (Passenger Steel-Eelted 1)	
TTX I NSTRTIME	E852	Limit before Pa (Truck Textile-Plied 1)	
TSRTINSTRTIME	E892	Offset before Pmax (Truck Steel-Belted 1)	
PSR IT NSTRTIMF	E8D2	Offset before Pmax (Passenger Steel-Belted 2)	
TTX II NSTRTIME	E912	Limit before Pa (Truck Textile-Plied 2)	
TSRIINSTRTIME	E952	Offset before Pmax (Truck Steel-Pelted 2)	
GRPNSTRTIME	E992	Offset (Glass-Reinforced Plastic Elock)	
RN NSTRTIME	ESD2	Offset (Rubber/Nylon Block)	

(a) Minimum Peak Times ("NEAR STRUCTURE TIME")

LABEL	ADDRESS	DESCRIPTION
PSR I FSTRTIME	E814	Offset after Pmax (Passenger Steel-Eelted 1)
TTX I FSTRTIME	E854	Limit after Fa (Truck Textile-Plied 1)
TSRIFSTRTIME	E894	Offset after Pmax (Truck Steel-Belted 1)
PSR-II FSTRTIME	E8D4	Offset after Pmax (Passenger Steel-Belted 2)
TTX II FSTRTIME	E914	Limit after Pa (Truck Textile-Plied 2)
TSR II FSTRTIME	E954	Offset after Pmax (Truck Steel-Belted 2)
GRP FSTRTIME	E994	Offset (Glass-Reinforced Plastic Block)
RN FSTRTIME	E9D4	Offset (Rubber/Nylon Elock)

(b) Maximum Peak Times ("FAR STRUCTURE TIME")

5.3.8. Envelope Classification. After feature extraction, compensation of amplitudes for temperature and thickness, and windowing, the reflection envelopes are next classified into tire structure categories according to rules which have been derived from past observations of the structures. The basic structure categories are bondline, body plies, and liner. When steel-belted tires are inspected, the categories of first belt and second belt are added. In all the discussions that follow, textile tire belts are referred to as top body plies. The term "belt" is reserved for steel belts which are treated as a special case in the TQM.

The structure categories obviously vary with tire type, but so do the classification rules. The following is a summary of these rules:

• Steel Padial Tires:

 $-p_a^e(a) \ge 0.6 p_a^e(b)$ P_a is first steel belt, etc.

-pa(a) < 0.6 pa(b) Pa is bondline, etc.

• Textile Bias Tires:

-Single envelope/single superenvelope: -Pre-retread:

10.0us > t ^e (a)	P _a is bondline
30.0us > t ^e _p (a) <u>></u> 10.0us	P _a is body plies
t <mark>e</mark> (a) > 30.0us	Pa is body plies

• Post-retread:

29.9us	>	tp(a)			Pa	is	bondline
44.0us	>	te(a)	<u>></u>	29.9us	Fa	is	body plies
		tp ^e (a)	>	44.0us	P_a	is	liner

• Multi-ervelope/multi-superenvelope (<2):

5.6us > te(b) - te(a)	F _a is bondline, P _b is body plies, etc.
8.2us > t ^e (b) - t ^e (a) ≥ 5.6us	execute single envelopes/s.s. tests
13.0us > $t_p^e(b) - t_p^e(a) \ge 8.2us$	F _a is body plies, P _b is liner, etc.
t <mark>p</mark> (b) - t <mark>p</mark> (a) ≥ 13.0us	P _a is bondline, P _b is liner, etc.

Multi-envelope/multi-superenvelope (>3):

tests

te(c) - te(a) + M ≥ 2[te(b) - te(a) ≥ te(c) - te(a) - M multiple ringing detected, execute single envelope/s.s.

As before, indices a, b, and c refer to the first, second, and third isolated unclassified envelopes and P_i refers to the sets of envelope i features of which $p_e^{(i)}$ is the peak amplitude and $t_p^{e(i)}$ is its associated time. In the case of textile tire inspection, the creation of superenvelopes is an extra stage of feature extraction and will be discussed more fully in par. 5.3.8.2.

5.3.8.1. Classification of steel radial tire envelopes. Experience has shown the ultrasonic reflection envelope classification to be simply based on the relative amplitudes of the two first-detected signal envelopes. The algorithm assumes the first steel belt will always be detected and decides the classification on the results of a measurement for bondline presence. This measurement is conducted using the parameter C1 in a way such that if the first-second reflection amplitude ratio is equal to or greater than C1, the first envelope is classified as a first steel belt reflection and the second envelope is classified as a second steel belt reflection. If the amplitude ratio is less than C1, the first envelope will be classified as a first steel belt reflection. This is equivalent to saying that bondlines in steel-belted tires reflect less ultrasonic energy than belts by a factor of C1. Mathematically, this is expressed as:

p∰(a) <u>></u> C1.p∰(b)	classifies Pa as steel belt 1, Fb as steel belt 2, etc.
p <mark>e</mark> (a) < C ₁ .p <mark>e</mark> (b)	Classifies Pa as bondline F _b as steel belt 1, etc.

The value of parameter C1 is selected at the time of TIRE TYPE from values stored in EEPROM. Each is alterable by procedures discussed in par. 5.7.2.3. Figure 5-30 illustrates the logic flow of the steel tire classification process.

5.3.8.2. Classification of textile tire envelopes. Experience has shown the ultrasonic reflection envelope classification to be based on the separation in time between adjacent envelopes. There are three textile tire classification categories (i.e., bondline, body plies, and liner) and three time separation limits are used for each textile tire type. These are stored in EEPPCM and are alterable using procedures discussed in par. 5.7. Their labels are LCWCAPLIMIT_n, MIDCAPLIMIT_n, and HIGHGAPLIMIT_n and their address and values are listed in Table 5-7. The operator should remember that after altering the FEPPOM values, he must reselect the desired TIRE TYPE to activate them. (See Figure 5-31.)



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Figure 5-30, Steel-Belted Tire Classification Algorithm



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Figure 5-31. Textile-Plied Tire Classification Algorithm

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Because textile tires tend to ultrasonically exhibit less dense structure than steel-belted tires, two extra considerations must be made. First there exists the possibility that only one envelope will be detected and no separation time can be computed. Second, it is possible that a single-body ply structure may be represented by more than one envelope with a consequent misclassification of structures. The singleenvelope possibility is handled by the TQM processing a special case when it detects only one envelope. This special case decides the classification of the single envelope by how deep under the tread surface it lies. A bondline/plies limit and a plies/liner limit are used and the values set depend on the RETREAD MODE set during inspection. Table 5-7 lists the two pair of values stored in EEPROM and labeled PRELOWLIMIT_n through POSTHICHLIMIT_n. These values are also alterable by procedures discussed in par. 5.7.2.3., but the operator must remember to reset the desired RETREAD MODE after alteration to activate the new value(s).

The TQM handles the possibility of multiple envelopes from one structure by always generating "superenvelopes." This process is conceptually similar to the envelope-generating process discussed in par. 5.3.4. and is nothing more than the extraction of "superenvelope" features from envelope features when adjacent envelope start and end times are separated by less than a required amount (see Figure 5-32). This amount is labeled TEXTNULLGAP_n, and is alterable in EFPPOM by procedures presented in par. 5.7. Its address and values are listed in Table 5-9. If only one superenvelope is generated, the TQM proceeds to the singleenvelope process discussed above. Otherwise, classification is done by time separation between superenvelopes. If multiple ringing is still detected at this point, the algorithm allows a single-envelope detection using the first envelope. Mathematically, these rules are expressed below:

 P_a is bondline (P_1)

Pa is body plies (Po)

 P_a is liner (P_5)

 P_a is bondline (P_1)

 P_a is liner (P_5)

Pa is body plies (Pa)

• Single Envelope/Superenvelope:

• Pre-Retread Mode:

PRELOWLIMIT > te(a)

PREHIGHLIMIT > te(a) > PRELOWLIMIT

- te(a) > FREHIGHLIMIT
- Post-Petread Mode:

PCSTLOWLIMIT > tp(a)

POSTHICHLIMIT > te(a) > POSTLOWLIMIT

te(a) > POSTHIGHLIMIT

• Multiple Superenvelope:



Figure 5-32. Superenvelope Feature Extraction

Table 5-8. Truck Textile-Plied Tire Classification Parameters

LAPEL	ADDRESS	DESCRIPTION
PRELOWLIMIT	EA40	PRE-RETREAD depth to Body Ply
PREHIGHLIMIT	EA42	PRE-RETREAD depth to Liner
POSTLOWLIMIT	EA44	POST-RETREAD depth to Body Fly
POSTHIGHLIMIT	EA46	POST-RETREAD depth to Liner
LOWGP LIMIT	EA48	Minimum Bondline-Ply Peak Separation
MIDGAPLIMIT	EA4A	Minimum Ply-Liner Peak Separation
HIGHGAPLIMT	EA4C	Maximum Ply-Liner Peak Separation
TEXTNULLGAP	EA4E	Gap Limit

(a) TRUCK/T 1 TIRES

LABEL	ADDRESS	DESCRIPTION
PRELOWLIMIT 2	EBOO	PRE-RETREAD depth to Eody Ply
PREHIGHLIMIT 2	EB02	PRE-RETREAD depth to Liner
POSTLOWLIMIT 2	EBC4	PCST-RETREAD depth to Body Liner
POSTHIGHLIMIT	EB06	POST-RETREAD depth to Liner
LOWGP LIMIT 2	EB08	Minimum Bondline-Ply Peak Separation
MIDGAPLIMIT ²	EEOA	Minimum Ply-Liner Peak Separation
HIGHGAPLIMT ²	EBOC	Maximum Ply-Liner Peak Separation
TEXTNULLGAP 2	EBOE	Gap Limit

(b) TRUCK/T 2 TIRES

5.3.9. Storage and Quality Analysis. The discussion to this point has been of TQM action to maintain a tread depth or quality number display updated at a 3-Hz rate. Automatic analysis of the quality of the inspected tire is done by saving three to five different sets of envelope features using the STORE operation and then commencing the analysis using the ANALYZE operation. The analysis first checks all the STOREd envelope feature tables for time and amplitude consistency and, if enough consistent tables exist, they are combined into one composite table upon which a variety of tests are performed to assess tire quality. Otherwise, the TQM requests more STORE operations.

5.3.9.1. Saving envelope features. When in the QUALITY display mode the inspector is satisfied that he is receiving a stable, representative signal, he may save the envelope features of that signal by pressing the STORE button. The TQM will then save the set of envelope features extracted at the time of its receipt of the STORE command (see Figure 5-33). Upon completion of the save, the STORE LED will be turned on for 1 second. Up to five such saves can be made and, for good sampling, it is recommended that at least three be made. If more than five saves are made, only the latest five features sets will be analyzed.

5.3.9.2. Majority analysis. When the inspector depresses the ANALYZE key, the accept/reject test series appropriate to the selected tire type will commence. The first step is a check for sampled data consistency. The TQM compares each sample with the other two to four to confirm the presence of a common pattern of envelope features among them. Any sample exhibiting a categorized envelope whose peak amplitude is sufficiently different from the peak amplitudes of identically categorized envelopes for a majority of other samples is removed from the sample population because of amplitude inconsistency. Likewise, any sample with a classified envelope whose time of peak occurrence does not lie between the start and end times of identically classified envelopes for a majority. This process, referred to as "majority analysis," is summarized in Figure 5-34. If less than three samples survive this examination, the TQM will display the message:

Process STORE Command : V yes Is Display Held With ANALYZE Result? -----> Exit no : V STORELEDCLOCK (- 3 Turn on STORE led : V. YIC: Listings Enabled? -----. yes i . V : Enable STORE listing . : . υ 1 ____! 2 υ Advance Structure Cyclic Array Pointer Advance Porosity Cyclic Array Pointer Lock in Latest P1, P2, P3, P4, P5, P6, P7 : V yes TABLECOUNT = 5? -----> Exit no : U TABLECOUNT (- [TABLECOUNT] + 1 ; V Exit ,

Figure 5-33. STORE Command Execution



Figure 5-34. Majority Analysis Logic 68

"n Add"

where n is the number of additional samples required to bring the STOREd complement up to the minimum of three samples. This display will hold with a flashing ANALYZE LED until the operator pushes the ANALYZE button (see Figure 5-35). The operator can then proceed to STOPE more samples. If the TQM cannot detect three or more consistent samples after more than two tries, it will proceed with an analysis based on the surviving samples. Of course, if three or more samples survive any "majority analysis," the inspection analysis will proceed as described below.

5.3.9.3. Amplitude averaging. The next analysis step is a computation of the average value of the maximum amplitude for each categorized reflection envelope. If, during this computation, a flag is sensed indicating acquisition of data while the TQM had a stored temperature value less than 30 °F or greater than 115 °F, the analysis will abort and the OUT-OF-TEMP LED will light. Otherwise, the TQM proceeds with peak amplitude processing (see Figures 5-36 and 5-37).

5.3.9.4. Amplitude processing. After classification, storage, and averaging, the envelope peak amplitudes are measured in various ways to detect patterns characteristic of known types of tire flaws. The flaw characterization rules have been derived from past observations of tire structures by experts in the ultrasonic inspection of tires. The basic flaw categories are poor bonding, separation or degradation of the body plies, and porosity. When inspecting steel-belted tires, the categories of first and second belt separation must be added. The flaw classification rules vary with tire type. In general, flaw classification in textile tires is based on comparisons of ultrasonic amplitudes with absolute threshold limits and flaw classification in steel-belted tires is based mostly on comparisons of ultrasonic amplitudes with the ultrasonic amplitudes of neighboring structures.

5.4. Inspections

5.4.1. Steel Radial Tires. The two types of inspections performable on steel-belted tires are reflected by the implementation of two sets of flaw classification rules for these tire types.

5.4.1.1. Midline inspections. The series of accept/reject flaw classification tests programmed into the Monitor is illustrated in Figure 5-2?. It is an ordered sequence of relational comparisons of measured reflection amplitudes with each other and of absolute comparisons to set standards. The ordering of the test sequence reflects the sensitivity of each test to the detection of the flaw. For example, the detection of second belt separation is more reliably detectable by comparing second and first belt reflection energies than by comparing the second belt energy to an absolute standard (see Table 5-9). Careful examination of Figure 5-38 shows that the actual number of tests is small. There are only 11 (1 relational and 1 absolute test for separation of each belt, 2


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Figure 5-35. Analyze Command Execution



Figure 5-36. Time Majority Analysis Logic

Process [] Amplitude Consistency 2 V i (- [TABLECOUNT] 8 V 1 8 : V ŝ ј (- і Н (- Ø 8 8 M (- Ø 2 1 ν 8 : 2 5 V : : Pl(j) (- pa([]j)*(1.0-[HOMOL_OFFSET]) : 8 Ph(j) (- pa([]j)*(1.0+[HOMOL_OFFSET]) : 2 : 3 8 V no yes 5 8 Pl(j) = < pa([]i < Ph(j) ? ------</pre> 5 2 8 . . . V U 2 2 . M <− M+1 : H (- H+1 8 5 . 9 8 (------2 2 8 V 2 e j <− j−1 • 8 : . 2 V no 2 2 ງ=Ø? 8 yes : 2 V rici 8 M > H? ----2 yes : 5 8 V 2 8 Remove Sample i From Arrays : TABLECOUNT (- [TABLECOUNT] - 1 : 2 8 : 2 2 V : : V 5 i (- i-1 9 8 V rio Ξ i=0? yes : V. Exit

Figure 5-37. Amplitude Majority Analysis Logic

Process Steel-Belted Tire Accept/Reject Tests . Ū AA1 (- CA13 AA2 (- CA23 V yes No reflections? -----> r deg B 01 no i V V yes One reflection? ----> r sep 18 02 no : V no, detected bondline yes, no bondline -- P1=0? -------> P1>=(SIG_BONDLINE]? -----. yes 1 v AA1 (- CA1] + CBL_RED_FACTOR] : AA2 (- LA2] + CBL_RED_FACTOR3 : v (--no, significant bondline P3>P2? -----> r sep 2B 69,70,71 yes, small bondline ... ----- B2*P2)P1? ----no i yes P3>=B3*P2? --> r sep 2B P3)=B3*P2? --> r sep 2B 72,73,74 P3)=B3+P2? --> r sep 28 00, 33, 34 no: yes 00,03,04 no: yes no s yes no: yes 05,06,07 V yes no: yes noi yes .- B3*P2>P3>=B5*P2? -. no $V = V = \frac{1}{2} - \frac{1}{2$ yes.- 93*P2/P3/=85*P2? -. no V V V P4)=B8*P3? -. no: yes V i r sep B i 09,00,50 yes V no i yes V r sep B i r se 00,00,20 i 00, r sep B 00,00,09 V V B6+P3)P4? ----, B6+P3)P4? ----, no: yes V no: yes V i rideo P V V B6*P3>P4? ----. B6*P3>P4? ----. B6+P3>P4? ----. B6+P3) P4? ----. yes V no 1 yes V r deg B 1 r d 00,22,23 1 00, V yes V no i yes V r deg B i r deg B 91,92,93 i 80,81,82 no i yes.V i rdeo yes V r deg B no t r deg B 00,41,42 00.11.12 . ţ. ū P3>=AA1? ---. P3)=AA1? ---. no: yes V P3) =AA1? ---P3>=AA1? ----. P3>=AA1? ---. P3) =0017 ----P3)=AA17 ---. no: yes V : rsep 2B : 00,00,44 no: yes V no: yes V : r sep 2B : r sep 2B : 00,00,25 : 00,00,14 no z yes V no: yes V yes V no : r sep 2B : 06,08,55 : V i i v 3 1 V r sep 28 00, 94, 95 r sep 28 00,83,84 1 1 V 00, 00, 14 AA2) P3? ----. AA2) P3? ----. 002)032 ----AA2) P37 ----. no: yes V I r sep 18 I 90,85,86 no : yes V : r sep : 00,0 yes V noi yes V rsep 1B i rse 00,00,57 i 00, no: yes.V r sep 18 r sep 18 00, 96, 97 00, 00, 46 . V V Shoulder yes Shoulder yes Inspection? ---. Inspection? ---. no : V : V V V Shoulder yes Shoulder yes Inspection? ---. I V no I V Shoulder yes Inspection? ----, no : V Shoulder Inspection? ---. V Shoulder

 ction? ---.
 Inspection? ---.
 Inspection?
 Inspection V no i Process i no i V i Process no: V : Process i r por Cp i r por __ V V V V V v v a... P3 Post-Retread? -, Post-Retread? -, 00,00,48 no i yes V no i yes V i r bin P1 i r bin P1 i 00,00,29 i 00,00,18 V V V V V dt (- tp(5)-tp(3) dt (- tp(5)-tp(3) V yes V yes DT_F)dt)=DT_N? ---. DT_F)dt)=DT_N? ---. no : : no : : to V yes V yes V (------ P5)=B3+P3? (----- P5)=B a ... P3 00,00,59 00,00,18 V V a P3 00,00,29 a P3 00,00,18 ---- 95)=89+037 noi i V t r deg 28 i 99 i i noi i V i r deg 28 i 86 no i V 88 a ... P3 00, 98, 99 a ... P3 00, 87, 88

Pj = pa(j) for j=1,2,3,4,5

Figure 5-38. Steel-Belted Tire

Table 5-9. Liner Accept/Reject Test Parameters

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LABEL	ADDRESS	DESCRIPTION				
PSR_I_LEN TSR_I_LEN PSR_II_LEN TSR_II_LEN	E816 E896 E8D6 E956	Passenger Steel-Belted Truck Steel-Belted 1 Passenger Steel-Belted Truck Steel-Belted 2	1 2			

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(a) Minimum 2nd Belt--Liner Time Difference

LABEL	ADDRESS	DESCRIPTION				
PSR I LBF	E818	Passenger Steel-Pelted 1				
TSRĨĨLBF	E898	Truck Steel-Belted 1				
PSR II LBF	E8D8	Passenger Steel-Belted 2				
TSR_II_LBF	E958	Truck Steel-Belted 2				

(b) Maximum 2nd Belt--Liner Time Difference

relational tests for separation of the body plies, 1 relational test for body ply degradation, and 3 switching tests). When combined, there are 40 potential tests that can be applied to a tire being inspected. These tests can end in one of 69 possible results. Eight of these indicate an acceptance of the tire.

Figure 5-38 shows the flow of the accept/reject test series. Detectable and significant bondline tests split the processing flow into three branches. Close examination shows the equivalence of each branch with respect to test priority and parameters used. Test priority is such that flaws of the belts and then of the body plies are assessed by relative comparisons and then belt flaws are measured by absolute thresholds. The right-hand branch in Figure 5-3? is slightly different in that an extra test of the inspection mode is made and an absolute test for first-belt separation is deleted. This branch for "excessive bondline" presumes that the large energy return from the bondline will render meaningless any absolute measure for first-belt separation and it, of course, senses the Monitor inspection mode before judging whether the bondline is a flawed retread product or an expendable part of a retread candidate.

Each branch is bifurcated on the basis of relative second belt reflection energy. This has no obvious rationale, but has been programmed to mimic the basis upon which tire inspectors have been known to make correct decisions.

5.4.1.2. Shoulder inspections. This type of inspection is used to detect casing belt-edge separations in the shoulders of retread candidate tires or porous tread in the shoulders of retread tires resulting from undercure during the retread process. As a result, the Monitor will inspect for porosity in this mode only if the POST-PFTREAD mode is also enabled. When inspecting steel-belted tires in any SHOULDER TEST LOCATION mode, the midline accept/reject test series is always run first to inspect for belt-edge separations in the shoulders. If the Monitor is in the POST-PETREAD mode and no casing flaws are found in the shoulder, the test for rejectable porosity begins when three porosity reflections are detected within the appropriate time window. If it is then found that the amplitude of any of these reflections is greater than a set porosity threshold, a rejection due to porosity presence is indicated.

5.4.2. Textile Tires. The two types of inspection performable on textile-plied tires is reflected by the implementation of two sets of flaw classification rules for this tire type.

5.4.2.1. Midline inspections. The series of accept/reject textile tire flaw classification tests programmed into the Monitor is illustrated in Figure 5-39. It is a sequence of absolute comparisons of measured reflection amplitudes to set standards. Careful examination of Figure 5-39 shows that there are only two tests (one absolute test each for separation and for degradation of the body plies). Altogether, there are eight poten-



Figure 5-39. Textile-Plied Tire Accept/Reject Algorithm

tial tests that can be applied to a tire being inspected. These tests can end in one of 21 possible results. Six of these indicate an acceptance of the tire.

Figure 5-39 shows the flow of the accept/reject test series. Detectable and significant bondline tests split the processing flow into three branches. Close examination shows that the testing sequence in each branch is equivalent and that body ply flaws are detected by comparing reflection amplitude with absolute thresholds. The right-hand branch in Figure 5-39 is slightly different in that there is no test for body ply degradation and an extra test of inspection mode is made. The presence of a significant bondline reduces body ply amplitude and makes any degradation test meaningless. This branch is followed when a significant bondline reflection is detected and is used to sense the TCM inspection mode before judging whether the bondline is a flawed retread product or an expendable part of a retread candidate casing.

5.4.2.2. Shoulder inspections. This type of inspection is used to detect porous tread in the shoulders of retreaded tires resulting from undercure during the retreading process. As a result, the TQM will inspect for porosity in this mode only if the POST-RETRFAD mode is also selected. If the PRE-RETRFAD mode is selected, the TQM will not do accept/reject processing and will issue blank displays and "accept" decision only. If the TQM is in the POST-RETRFAD mode, the test for rejectable porosity begins when three porosity reflections are detected within the appropriate time window. If it is then found that the amplitude of any of these reflections is greater than a set porosity threshold, a rejection due to porosity presence is indicated along with a display of the number of reflections. Otherwise an acceptance is indicated. Figure 5-40 outlines the logic of porosity testing.

5.5. Calibration

5.5.1. General. The TQM is programmed to perform three types of automatic self-calibration. They are:

- (1) Temperature Calibration
- (2) Gain Calibration, and
- (3) DAC Adjustment.

Temperature and gain calibrations are frequently executed as part of the daily operation of the TQM. DAC adjustment is performed every 6 months as part of scheduled maintenance. The Operator, Maintenance, and Calibration Manuals describe the use of these calibrations in more detail. This chapter discusses the supporting software.

5.5.2. Temperature Calibration. The calibration of the TCM to the temperature of a tire casing is done by reading the output of the accessory thermocouple as it is embedded in the tire tread. As illustrated in

Process Shoulder Tests 2 V no Post-retread inspection? ----> Exit to : calling routine yes : V Cp (- Porosity reflection count V yes Cp < 4? ----> Exit to no : calling routine ν Cp (- Porosity [pa)= A11] count . V yes Cp = 0? ----> Exit to calling routine no : V r por Cp

Figure 5-40. Common Tire Porosity Accept/Reject Algorithm

Figures 5-41 and 5-42 this procedure executes the normal TEMP display process described in par. 5.3. in order to read the thermocouple and update the display. It then processes a comparison of the two most recently acquired temperatures and terminates with a finished calibration if their difference is less than 2° . The finished calibration termination is simply a storage, for later reference, of the last temperature read and a computation from its value of the indices required for data compensation. If, after a period of 20 seconds of attempting temperature calibration, the TQM cannot acquire two consecutive temperatures whose difference is less than 2° , it terminates in an uncalibrated condition.

5.5.3. Gain Calibration. The calibration of the TQM receiver section gain is an adjustment of the voltage controlling the gain of the first amplifier (AGC1) in the receiver until the maximum peak amplitude of the ultrasonic reflection sampled off a GRP-to-air interface falls within a range of one unit around a TIRE TYPE-dependent setpoint (see Table 5-10). As illustrated in Figures 5-43 and 5-44, this procedure executes the normal reflection feature extraction process described in par. 5.3., isolates the peak of maximum amplitude lying between time limits specified by EEPROM variables E7EO (CAL LOW WINDOW) and E7B2 (CAL HICH-WINDOW), and compares this amplitude value with a setpoint value selected by TIRE TYPE and by saturation disposition history (par. 5.3.5). If the maximum peak amplitude is less than the setpoint value, the ACC1 gain is increased and if the maximum amplitude is greater than the setpoint value, the AGC1 gain is decreased. The TQM then continues this acquisition, compare, and adjust cycle until a match yields a termination with good calibration or until it reaches the limits of ACC1 gain adjustment, at which point the TQM issues a "-CAL" message and terminates in an uncalibrated state.

5.5.4. Automatic DAC Adjustment. The adjustment of the DAC is a variation of the gain calibration procedure described above. As explained in Section 4.3.3.3. of the Calibration Manual, the automatic DAC adjustment is started by pressing the TEST CAL switch. However, if the RAM memory address FF01 (AUTO DAC FLAG) has been loaded with the number one (by procedures described in par. 5.7.2.3.), instead of starting the gain calibration, the TOM will start adjusting the DAC. This process is summarized in Figures 5-45 and 5-46.

The aim of the automatic DAC adjustment procedure is to modify the slope control voltage of amplifier AGC₂ so as to minimize the variance between TQM reflection amplitudes and "idealized" amplitudes at three points in time. To do this the TQM first adjusts the gain of the first receiver amplifier (AGC₁) until the first reflection off the $\frac{1}{2}$ -inch rubber test. block is unsaturated. It then uses this amplitude to compute the specific values of the "idealized" compensation curve for the third and fifth multiple reflection. This part of the DAC adjustment is designated as stage 1 in Figure 5-46. Stage 2 is simply the computation of the initial variance (v) between the detected reflection amplitudes pa(i) and the "idealized" values ta(i) according to:

Start Temperature Calibration 8 V Set FLAGS(b2) ["in-service" true] Clear FLAGS(66) ["timed-out" false] Clear FSELECT+1(b6) [no calibration error condition] . v CALTRYCNT (- 3*20 CALAVERAGECNT (- 4 CALENDONT (- 4 CALTOTALPEAKS (- Ø 2 V TEMTIM (- 0 3 V Turn On TEMP CAL led : V Process Temperature Display (Flowchart 3.3) : V CALIB_TEMP <- ELAST_TEMP_READJ : V Exit

Figure 5-41. Start of Temperature Calibration

Process Temperature Calibration . U Process Temperature Display (Flowchart 3.3) U T(t-1) (- [CALIE_TEMP] T (- CALIB_TEMP (- LLAST_TEMP_READ) : v yes YIC: ---- |T(t) - T(t-1)| < 1? -----• CALENDONT (- [CALENDONT] - 1 CALENDONT (- 4 2 : v no CALTRYENT (- [CALTRYENT] - 1 Exit (--- CALENDENT = 0? yes : v TIC CALTRYCNT = 0? ----> ExitProcess Compensation of Limits yes : 2 Clear "Out-Of-Temp" bits in STORE Tables Compute Lookup Table (TEMPDIVBY5) index Compute Interpolation (TEMPREMAIN) index : υ yes Indices in Range? ------Set "Out-Of-Temp" bits in STORE Tables : . ν TEMTIM (- 3*60*15 Set FLAGS(b6) ["timed-out" true] Turn Off TEMP CAL led Clear FLAGS(64, 62) ["hold", "in-service" false] ٠ Set FLAGS(64) ["hold" true] Clear FLAGS(b6,b2) ["timed-out", "in-service" false] : U υ Exit Exit

Figure 5-42. Temperature Calibration

Table 5-10. Gain Calibration Setpoint Values*

TIRE TYPE ADDRESS DESCRIPTION AMPTABLE PSR I E790 Passenger Steel-Belted 1 TTXTI E792 Truck Textile-Plied 1 TSRII E794 Truck Steel-Felted 1 GRP E796 Glass-Reinforced Plastic Block RN E798 Rubber/Nylon Block PSR II Passenger Steel-Belted 2 E7SA TTX II Truck Textile-Plied 2 E79C TSRII E79E Truck Steel-Belted 2

(a) Primary Gain Calibration Setpoints

TIRE	E TYPE	ADDRESS	DESCRIPTION					
ALTTABLE	PSR I	E7A0	Passenger Steel-Belted 1					
	TTXI	E7A2	Truck Textile-Plied 1					
	TSR ¹	E7A4	Truck Steel-Belted 1					
	GRP	E7A6	Glass-Reinforced Plastic Elock					
	RN	E7A8	Rubber/Nylon Elock					
	PSR II	E7AA	Passenger Steel-Belted 2					
	TTXTII	E7AC	Truck Textile-Plied 2					
	TSRII	E7AE	Truck Steel-Belted 2					

(b) Secondary Gain Calibration Setpoints

*TQM Reading of Setpoints = Setpoint/4.23
Example for GRP (refer to Listing in Appendix):
15 = 63/4.23 where 63 = 3F
10 16

["analysis-since-calibration", "hold" false] Start DAC Adjustment [no calibration error condition] (Flowchart 4.3) ["in-service" true] ["timed-out" false] yes Reset STORE Tables and Initialize Pointers 1 Turn Off Accept/Reject and Flaw leds Automatic DAC Adjustment Enabled? NOISEWIDTH (- [GRP_PRE_NWID] agc(3) (- [0RP_OUTGAIN] Save present NOISEWIDTH Clear ANALYSTATUS(67,60) Start Gain Calibration Turn Off ANALYZE led Turn On TEST CAL led Clear FSELECT+1(b6) Set FLAGS(b3) Clear FLAGS (b7) 4 4 4 S 6 Exit I I 1 I > > 2 > " 05 CALTIM CALTRYCNT CALENDONT CALAVERAGECNT CALTOTALPEAKS

Figure 5-43. Start of Gain Calibration



Figure 5-44. Gain Calibration

Start DAC Adjustment 5 V Save RAM_TMP_SLOPE Save RAM_TMP_INGAIN Save RAM_TMP_OUTGAIN Save RAM_TMP_FN_GAIN • • . V age(2,c) (- 0600H : ۷ INC (- Ø TERM (- LRAM_TMP_SLOPE] 5 V CALTRYCNT (- 4 CALAVERAGECNT (- 4 CALENDONT (- 4 P5_TRYCNT (- 4 CALTOTALPEAKS (- 0 5 V PEAK_n (- @ (n=1,3,5) : V Enable Stage 1 : V Exit

···· · .

Figure 5-45. Start of DAC Adjustment

(---- Amplitude pa(Max) Found? Turn Off TEST CAL led Set FSELECT+1(b5) ["cal error" true] Blink CLEAR led Clear FLAGS(b7,b3) ["timed-out","in-service" false] age (1) , age (3) , age (2, c) ROM_SLOPE (- age (2, b) CALTIM (- 3*60*15 Restore Original Search Finished? ----> Exit <---- Search Finished? Prepare Display of ["hold" true] Process DAC Search Lowest Variance (Flowchart 4.6a) Values for Exit > > > yes : > yes : Process DAC Error Set FLAGS(b5) (Flowchart 4.6b) ŝ ę yes > agc(1) (- Restart agc(1) Blope (- Original slope Amplitude pa(Max) Found? ---) ĝ ŝ (- Slope-64 Stage 3 Finished? Process DAC Search (Flewchart 4.6a) Enable Stage 4 INC (- -1 Exit > yes : Yea a 0 20 TERM Search Finished? ----> Exit Bave agc(1) Value for Restart Slope (- Original slope Amplitude pa(Max) Found? ---) (--- Amplitude pa(Max) Found? yes ŝ Initialize Variance (- Slope+64 Process Search for Maximum Amplitude Process DAC Search ---> Stage 2 Finished? (Flowchart 4.6a) Enable Stage 3 s yes fix 1 t > > Yes a 0 2 2 TERM JNC Reduce age (3) Gain CALTOTALPEAKS (~ CCALTOTALGEAK93+pa (Max) CALAVERAGECNT (~ CCALAVERAGECNT3 ~ 1 Process DAC Error Amp1 i tude (Flewchart 4.6b) Prepare Display õ 2 .--- [CALTOTALPEAKS]/4 (967 ----. ŝ > PEAK_n (- @ (n=1,3,5) ŝ You Process DAC Adjustment ENIT (---- CALAVERAGECNT = 07 Prepare 1/4" Limits Stage 1 Finished? + + 4 -> 4 CALTUTALPEAKS (- Ø - 4 EHAC Ļ > > yes : yes « 0 Z P5_TRYCNT CALTRYCNT CALENDONT 1GT_n with limits for 1/4", 3/4", and 5/4" reflections CALAVERAGECNT Save unsaturated value Compute "flat" curve Enable Stage 2 ê cf agc (3) yes >

Figure 5-46. Automatic DAC Adjustment

$$v = \sum_{i=1, 3, 5} | pa(i) - ta(i) |$$

Stages 3 and 4 in Figure 5-46 constitute searches either side of the initial AGC₂ slope value for such a value which minimizes the variance (v) as computed above (see also Figures 5-47 and 5-48). Since the locus of variance with respect to slope cannot be expected to be monotonic, the search algorithm adjusts the TQM slope in a simple, sequential manner. As presently constituted, the TQM limits this search to 64 values of slope either side of the starting point, yielding a processing time of less than 10 minutes. Each time a variance is computed with value less than the previous variance, this new variance becomes the next previous and the value of the voltage controlling the slope of AGC_2 is saved. At the end of the search, this saved value then becomes both the active controlling voltage of AGC2 slope (by being sent to the hardware port) and the permanent backup value (by being written into FFPROM memory E786). As discussed in Section 4.3.3.3. of the Calibration Manual, the TCM then displays the value of the lowest variance computed (as a measure of the quality of the adjustment) and waits for the operator to press the CLEAR switch.

5.6. Displays

5.6.1. Alphanumeric Display. Various types of information are provided on the alphanumeric display. These are described in the Operating Manual. Indicated in this report is the fact that coded information supplemental to analyzed accept/reject decisions is provided. It is in a form:

Number Code

Tire Information

Number Code is specific to type of tire inspected, steel or textile. See Tables 5-11 and 5-12 for a list of code meanings.

For each code number, as appropriate, the tables provide the TQM constant which caused this code to appear, whether the critical reject decision was made on a relative or absolute basis, which part of the tire was involved, the reject decision basis, the number of peak envelopes detected, the bondline level detected, and whether (for steelbelted tires) the 2nd belt/1st belt amplitude ratio is low or high.

Tire-Information is presented as:

1b - if 1st belt signal is reason for rejection

2b - if 2nd belt signal is reason for rejection

b - if body plies are reason for rejection

averaged quality number - if the tire is accepted



Figure 5-47. DAC Search Procedure

Process DAC Error : V CALTRYENT (- CCALTRYENT] - 1 : v rici CALTRYCNT = 0? ----> Exit yes : ν Set FSELECT+1(b6) Set FLAGS(b7) Clear FLAGS(65,63) : V Restore Original RAM_TMP_SLOPE Restore Original RAM_TMP_INGAIN Restore Original RAM_TMP_OUTGAIN Restore Original RAM_TMP_FN_GAIN 1 V Exit

Figure 5-48. Automatic DAC Adjustment Error Handler

Table 5-11. Textile-Plied Tire Accept/Reject Codes

CODE INTERPRETATION

01	ply degradatio	n rejectable w	rith O	peaks
02	ply separatio	n rejectable w	rith 1	peak and significant bondline
03	ply separatio	n rejectable w	ith 2	peaks and significant bondline
80		acceptable w	ith 1	peak and significant bondline
08	if retread, bondlin	e rejectable w	ith 1	peak and significant bondline
09		acceptable w	ith 2	peaks and significant bondline
09	if retread, bondlin	e rejectable w	ith 2	peaks and significant bondline
32	ply separation	rejectable w	ith 1	peak and significant bondline
33	ply separation	rejectable w	ith 2	peaks and small bondline
34	ply degradatio	n rejectable w	ith O	peak and small bondline
35	ply degradatio	n rejectable w	ith 1	peak and small bondline
36	ply degradatio	n rejectable w	ith 2	peaks and small bondline
38		acceptable w	ith 1	peak and small bondline
39		acceptable w	ith 2	peaks and small bondline
71	ply separatio	n rejectable w	ith 1	peak
72	ply separatio	n rejectable w	ith 2	peaks
74	ply degradatio	n rejectable w	ith 1	peak
75	ply degradatio	n rejectable w	ith 2	peaks
77		acceptable w	ith 1	peak
78		acceptable w	ith 2	peaks
80	ply degradatio	n rejectable w	ith 1	peaks (Liner)

Table 5-12. Steel-Belted Tire Accept/Reject Codes

CODE	INTERPRETATION				
01	abs SE2 degradation	rejectable	with O	peaks	
02	abs SB1 separation	rejectable	with 1	peak	
03	B3 rel SB2 separation	rejectable	with 2	peaks,	significant bondline
04	B3 rel SB2 separation	rejectable	with 3	peaks,	significant bondline
05	B4 rel SB1 separation	rejectable	with 1	peak,	significant bondline
06	B4 rel SE1 separation	rejectable	with 2	peaks,	significant bondline
07	B4 rel SE1 separation	rejectable	with 3	peaks,	significant bondline
09	B7 rel ply separation	rejectable	with 3	peaks,	significant bondline, and low SE2:SE1
11	E6 rel ply degradation	rejectable	with 2	peaks,	significant bondline, and low SB2:SB1
12	B6 rel ply degradation	rejectable	with 3	peaks,	significant bondline, and low SB2:SE1
14	Al abs SB2 separation	rejectable	with 3	peaks,	significant bondline, and low SB2:SE1
18		acceptable	with 3	peaks,	significant bondline, and low SB2:SE1
18	if retread, bondline	rejectable	with 3	peaks.	significant bondline, and low SP2:SP1
20	B8 rel plv separation	rejectable	with 3	peaks,	significant bondline, and high SB2:SE1
22	B6 rel ply degradation	rejectable	with 2	peaks.	significant bondline, and high SB2:SE1
23	B6 rel ply degradation	re jectable	with 3	peaks.	significant bondline, and high SE2:SE1
25	Al abs SB2 separation	rejectable	with 3	peaks.	significant bondline, and high SE2:SE1
29		acceptable	with 3	peaks.	significant bondline, and high SE2:SE1
29	if retread. bondline	re jectable	with 3	peaks.	significant bondline, and high SB2:SE1
33	B3 rel SB2 separation	rejectable	with 2	peaks.	small bondline
34	B3 rel SB2 separation	re jectable	with 3	peaks.	small bondline
35	E4 rel SE1 separation	re jectable	with 1	peak.	small bondline
36	B4 rel SB1 separation	rejectable	with 2	peaks.	small bondline
37	B4 rel SB1 separation	rejectable	with 3	peaks.	small bondline
39	B7 rel ply separation	rejectable	with 3	peaks.	small bondline, and low SB2:SB1
41	B6 rel ply degradation	rejectable	with 2	peaks.	small bondline. and low SB2:SB1
42	B6 rel ply degradation	rejectable	with 3	peaks.	small bondline, and low SE2:SE1
44	Al abs SE2 separation	rejectable	with 3	peaks.	small bondline, and low SE2:SB1
46	A2 abs SE1 separation	re jectable	with 3	peaks.	small bondline, and low SB2:SB1
48		acceptable	with ?	peaks.	small bondline, and low SE2:SE1
50	B8 rel plv separation	re jectable	with 3	peaks.	small bondline, and high SE2:SE1
52	B6 rel ply degradation	rejectable	with 2	peaks.	small bondline, and high SE2:SB1
53	B6 rel ply degradation	re jectable	with 3	peaks.	small bondline, and high SE2:SB1
55	Al abs SE2 separation	rejectable	with 3	peaks,	small bondline, and high SE2: SP1
57	A2 abs SE1 separation	rejectable	with 3	peaks,	small bondline, and high SB2:SE1
59	•	acceptable	with 3	peaks,	small bondline, and high SE2:SE1
69	rel SE2 separation	re jectable	with 2	peaks.	no detected bondline
70	rel SB2 separation	rejectable	with 3	peaks,	no detected bondline
71	rel SB2 separation	rejectable	with 4	peaks.	no detected bondline
72	B3 rel SB2 separation	re jectable	with 2	peaks.	no detected bondline
73	B3 rel SE2 separation	rejectable	with 3	peaks.	no detected bondline
74	B3 rel SE2 separation	re jectable	with 4	peaks.	no detected bondline
75	B4 rel SB1 separation	rejectable	with 2	peaks.	no detected bondline
76	B4 rel SE1 separation	rejectable	with 3	peaks.	no detected bondline
77	B4 rel SB1 separation	rejectable	with 4	peaks.	no detected bondline
78	B7 rel ply separation	rejectable	with 3	peaks.	no detected bondline, and low SE2:SF1

Table 5-12. (Continued) Steel-Belted Tire Accept/Reject Codes

79	B7	rel	ply	separation	rejectable	with	4	peaks,	no	detected	bondline,	and	low	SE2:SB1
80	B6	rel	ply	degradation	rejectable	with	2	peaks,	no	detected	bondline,	and	low	SE2:SE1
13	в6	rel	ply	degradation	rejectable	with	3	peaks,	no	detected	bondline,	and	low	SF2:SB1
82	B6	rel	ply	degradation	re jec tab le	with	4	peaks,	no	detected	bondline,	and	low	SE2:SB1
83	A1	abs	SB2	separation	re jectable	with	3	peaks,	no	detected	bondline,	and	low	SB2:SP1
84	A 1	abs	SB2	separation	re jec tab le	with	4	peaks,	no	detected	bondline,	and	low	P2:SB1
85	A2	abs	SB1	separation	re jectab le	with	3	peaks,	no	detected	bondline,	and	low	SB2:SB1
86	A2	abs	SE 1	separation	re jectable	with	4	peaks,	no	detected	bondline,	and	low	SB2:SB1
87					acceptable	with	3	peaks,	no	detected	bondline,	and	low	SE2:SB1
88					acceptable	with	4	peaks,	no	detected	bondline,	and	low	SE2:SB1
89	B8	rel	ply	separation	rejectable	with	3	peaks,	no	detected	bondline,	and	high	SB2:SB1
90	B8	rel	ply	separation	re jectable	with	4	peaks,	no	detected	bondline,	and	high	SB2:SP1
91	B6	rel	ply	separation	rejectable	with	2	peaks,	no	detected	bondline,	and	high	SB2:SB1
92	вб	rel	ply	separation	rejectable	with	3	peaks,	no	detected	bondline,	and	high	SE2:SP1
93	B6	rel	ply	degradation	rejectable	with	4	peaks,	no	detected	bondline,	and	high	SE2:SE1
94	A1	abs	SE2	separation	rejectable	with	3	peaks,	no	detected	bondline,	and	high	SB2:SB1
95	Al	abs	SB2	separation	rejectable	with	4	peaks,	no	detected	bondline,	and	high	SP2:SP1
96	A2	abs	SB1	separation	rejectable	with	3	peaks,	no	detected	bondline,	and	high	SB2:SE1
97	A2	abs	SB1	separation	rejectable	with	4	peaks,	no	detected	bondline,	and	high	SE1:SE2
98					acceptable	with	3	peaks,	no	detected	bondline,	and	high	SE1:SE2
99					acceptable	with	4	peaks,	no	detected	bondline,	and	high	SE1:SE2.

Only the last two items will appear if the TQM is in the textile TIRF TYPE mode.

5.6.2. Oscilloscope Display. An analog FF display is available which monitors, via oscilloscope, the tire reflection signal as received by the transducer and amplified by the fixed and variable gain amplifiers in the receiver stage. This signal is supplied by a FNC output on the TQM front panel. The signal output amplitude is limited to ± 1.0 volts peak-to-peak and no external trigger or synchronization mark is supplied. Recommended oscilloscope settings are:

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- Vertical: 0.2 dc volts/div
- Horizontal: 10.0 microseconds/div, internally triggered.

The analog FF signal is refreshed at a 100-Hz rate. On a properly set and triggered oscilloscope, the transducer "main bang" response will appear approximately 17 microseconds after trigger and the region of interest (i.e., ultrasonic reflections from the tire casing) will lie between 17 and 81 microseconds (Figure 5-49). The analog PF signal is equivalent to the PF signal output of a standard ultrasonic tester.

5.6.3. Printing Listings. Tabular listings of reflection features and envelope features are available through a dedicated output on the TCM front panel. This output is compatible with the FIA serial ES232C format. The output rate is set at 9,600 baud, PTS logic positive, eight bits compose a transmitted character, there is one stop bit and no parity, and the data format has been optimized for use with a Datel APP-48 printer. The operator should consult his printer manual for equivalent alignment.

Tabular listings are enabled by access to a flag in memory and, if enabled, are activated as part of normal STOPE and ANALYZF functions. To enable listings, a code number must be entered into memory FFCO using the UPDATE mode direct memory reprogramming sequence described in par. 5.7.2.3. The allowable code numbers and their meaning are:

- 0 listings disabled
- 1 short form listing enabled
- 2 long form listing enabled

At turn-on time, the TQM defaults to a "listing disabled" stage. If listings are desired, the following steps must be performed:

- (1) Enter UPDATE mode using keyswitch
- (2) Address memory FFOO (see par. 5.7.2.3.)
- (3) Enter desired code into memory (see par. 5.7.2.3.)



(a) Transducer Response



(b) Tire Inspection

Figure 5-49. Analog RF Display

(4) Leave UPDATE mode

Figure 5-50 illustrates the listing formats available. The short-term listing (Code 1) prints the calibrated temperature, tread depth, and envelope features of the ultrasonic signal captured when the STORE key is depressed. The envelope amplitudes have been compensated for temperature and depth and are in binary-coded decimal (BCD) format. Each time has been compensated for velocity variation with temperature and is represented in two ways. The first is the accumulation of a 20-MHz clock, as used by the CPU, and the second is in terms of equivalent microseconds, useful for oscilloscope comparisons or depth computations by the operator.

The long-form listing (Code 2) prints, in addition to the short-form listing described above, the reflection features from which the envelope features were derived. The reflection amplitudes are as rectified and smoothed in memory and the times are again represented in 2C-MHz clock accumulation and in equivalent microseconds. Priefly, the tables list:

- Amplitudes of reflections (0<pa<127) or envelopes (0.00<pa<9.99)
- Reflection/envelope start times (t_s)
- Reflection/envelope peak times (t_p)
- Reflection/envelope end times (t_e)

The operator must be careful when comparing times between the reflection and the envelope parts of the long-form listing. Each reflection feature time is compensated for temperature-dependent acoustic velocity variations when it is processed into an envelope feature time. The temperature used is listed in the printout for adjustments.

Depth within the casing is derived from the propagation time by the relation:

$$d = \frac{t}{2.125}$$

d is depth in units of one-sixteenth inch

t is propagation time in microseconds

When the ANALYZE key is depressed while either printing mode is enabled, a short-form listing will be generated which tabulates the averages of features captured in the tables generated by previous STOFF operations. The number of such tables will also be listed.

5.7. Reprogramming Procedure

		50	50 n. Counts			μSeconds			
	Raw Amplitude	T _{start}	T _{peak}	Tend	T _{start}	Tpeak	Tend		
LONG FORM	Amplitude 16 22 43 61 47 16 35 28 17 18 12 10 9 15 17 17 17 17 17 17 17 17 17 19 11 11 9 12 6	154 167 175 185 199 219 243 257 269 284 296 312 337 353 366 392 408 498 517 533 573 614 696 776	159 170 179 191 204 223 234 247 260 274 286 274 286 274 358 371 399 414 507 522 538 579 622 702 781	$\begin{array}{c} 163\\ 173\\ 185\\ 197\\ 211\\ 226\\ 240\\ 253\\ 265\\ 279\\ 291\\ 303\\ 320\\ 349\\ 362\\ 377\\ 404\\ 421\\ 510\\ 527\\ 544\\ 582\\ 627\\ 710\\ 782 \end{array}$	7.70 8.35 9.25 9.95 10.95 11.45 12.15 12.85 13.45 14.20 14.80 15.60 16.85 17.65 18.30 19.60 20.40 25.85 26.65 28.65 30.70 34.80 38.80	7.95 8.50 8.95 9.55 10.20 11.15 11.70 12.35 13.00 13.70 14.30 14.95 15.85 17.20 17.90 18.55 19.95 20.70 25.35 26.10 26.90 28.95 31.10 39.05	8.15 8.65 9.25 9.85 10.55 11.30 12.00 12.65 13.25 13.25 13.95 14.55 15.15 16.00 17.45 18.10 18.85 20.20 21.05 25.50 26.35 27.20 29.10 31.35 35.50 39.10		
	TEMPERATU	RE:	72 DE	G	THICKNE	ess:	3/16"		
	STORED DA 00.00 00.99 00.46 00.20 00.12 00.00 00.00 00.00	TA: 0 154 219 267 336 0 0	19 23 27 36 T	0 1 19 4 29 2 30 9 37 0 0 7	0 0.0 97 7.7 52 10.9 92 13.3 75 16.8 0 0.0 0 0.0 0 0.0	00 0.0 70 9.5 95 11.7 95 13.6 90 18.4 90 0.0 90 0.0 T P	0 0.00 5 9.85 0 12.60 0 15.10 5 18.75 0 0.00 0 0.00 Tend		SHORT FORM
	Compensat Amplitud	iea le							

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Figure 5-50. Printer Output

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CAUTION

FROGPAMMING MUST ONLY BE PERFORMED BY AN EXPERIENCED PROGRAMMEP

IMPROPER DATA ENTRY CAN MAKE EQUIPMENT INOPERABLE.

5.7.1. Alternate Keyboard.

5.7.1.1. Primary interpretations. Peprogramming the TQM is initiated by setting the front panel key switch to the TAFLE UPDATE position. This disables the normal operations of the Monitor and enables the reprogramming mode. When in this mode, most of the front panel switches are disabled. Those that remain enabled fall into two groups. One group retains its operational interpretation. This includes the six TIRE TYPE and the two RETPEAD MODE switches. The other group is enabled only in the reprogramming mode. These are the CLEAP, NFXT, and ENTER switches. All other switches have no Monitor operations interpretation in the reprogramming mode. See Figure 5-51 for panel markings to be used in the update mode.

The NEXT switch is used for two functions. When depressed initially, it starts an active reprogramming sequence. This is indicated by the flashing of the NEXT LED. Any subsequent depressions of the NEXT switch while its LED is flashing act to step through the reprogramming sequence. The specifics of the stepping operation depend on which reprogramming sequence is active.

The active reprogramming sequence is determined by which switch is depressed immediately after the initial depressing of the NFXT key. This switch stroke will enable what is called the primary interpretation of the switch. The supplied keyboard shows the primary interpretation of each switch as the first text below the switch. For example, referring to Figure 5-51, the switch which selects the TPUCK/T 1 TIRE TYPE in the operational mode will have a primary interpretation of THICK in the reprogramming mode. This provides access to the stored index of tread thickness which will enable the programmer to ultimately access the stored temperature/thickness compensation factors. This switch also has a secondary interpretation as the number "6." This will be discussed later in par. 5.7.2.3. on memory modification.

If any keystroke results in an error condition (signaled by the appearance of an "E" on the display, a flashing of the CLEAE LED, and a failure in Monitor responsiveness), the CLEAP switch must be depressed to release the failure condition hold state and to abort the current reprogramming sequence. The operator may also use the CLEAR switch at any time he chooses to abort a reprogramming sequence for any reason.

The ENTER switch is used to terminate a reprogramming sequence normally. If no data has been entered, the ENTER function leaves memory unaltered and extinguishes the NEXT LED. If data has been entered, it is stored into memory.



Figure 5-51. TQM Selector Switches

5.7.1.2. Secondary interpretations. Once a parameter of primary interpretation has been entered, all the front panel switches become interpretable according to the second function indicated on the front panel overlay. Typically this is an interpretation of numeric input with value 0 to 9, alphabetic input of letters A through F, and/or a decimal point. The correctness and meaning of subsequent input will be dictated by the primary interpretation of the sequence-initiating switch.

CAUTION

AT NO TIME SHOULD POWEP BE REMOVED FROM THE TOM DUPING UPDATE OPERATIONS. ADDITIONALLY, THE TOM MUST NOT BF TURNED OFF BY REMOVING ITS LINE FLUG FROM A POWEP SOURCE AT ANY TIME. TRANSIENTS GENERATED BY SUCH FOWER LOSSES CAN PARTIALLY OR COMPLETELY EPASE EEPPOM CONTENTS.

5.7.2. Keying Instructions.

5.7.2.1. Temperature/thickness compensation tables. The Monitor is delivered with capability of revising the lookup tables used to compensate reflected ultrasonic amplitudes for both tread thickness and tread temperature. Each compensating factor is dually indexed by a temperature index between 30° and 115° and by a thickness index between four- and twenty-sixteenths of an inch. The first access to any temperature/thickness compensation factor must be preceded by at least one setting of each index. An error condition will result if an attempt is made to access a compensating factor without prior indexing.

• Temperature Indexing. Setting the compensation table temperature index is performed by pressing the NEXT and TEMP switches in sequence when in the reprogramming mode. This initiates the temperature index reprogramming sequence as indicated by the flashing of the NEXT LED and by the display of the current temperature index. If the current index is the value desired by the programmer, he should leave the value unaltered by pressing the ENTER switch next in sequence. This will terminate the temperature index reprogramming sequence. However, if the programmer wishes to alter the temperature index, he may do so by one of two methods. One method is to successively press the MEXT switch until the desired index value is displayed. The other method is to explicity enter the desired value by sequentially pressing switches according to their secondary interpretations. The number entered must be a multiple of 5 (60, 65, 70, etc.). Either method requires depression of the ENTER switch to store the new index value and terminate the temperature index reprogramming sequence. An error condition will result if an attempt is made to set the temperature index outside the range of 30° to 115° or if an index is entered that is not divisible by five.

- Thickness Indexing. Setting the compensation table thickness index is performed by pressing the NEXT and THICK switches in sequence when in the reprogramming mode. This initiates the thickness index reprogramming sequence as indicated by the flashing of the MEXT LED and by the display of the current thickness index. If the current index is the value desired by the programmer, he should leave the value unchanged by pressing the ENTER switch next in sequence. This will terminate the thickness index reprogramming sequence. However, if the programmer wishes to change the thickness index, he may do so by one of two methods. One method is to successively press the NEXT switch until the desired index value is displayed. The other method is to explicitly enter the desired value by sequentially pressing switches according to their secondary interpretation. Either method requires depression of the ENTER switch to store the new index value and terminate the thickness index reprogramming sequence. If a thickness index value outside the range of 4 to 20 is entered, an error condition will result.
- Tire Type Selections. After temperature and thickness indices have been set, the operator should assure himself that he has selected the appropriate TIRE TYPE before accessing the compensation factor. This is because the TOM holds three tables of compensation factors for the three pair of tire types. Which table is accessed is determined by the TIRE TYPE enabled at the time of access. If the type selected is that desired by the operator, he may then proceed to the access described in the next paragraph. Otherwise, he may select the desired TIRE TYPE without leaving the UPDATE mode by simply pressing the appropriate TIRE TYPE switch using its operational interpretation. For this, no use is made of the NEXT or ENTER switches.
- Compensation Factor Examination/Alteration. If both temperature and thickness indices have been set, access to the compensation factor can be made by pressing the NEXT and T/T DATA switches in sequence when in the reprogramming mode. This initiates the compensation factor reprogramming sequence as indicated by the flashing of the NEXT LED and by the display of the indexed compensation factor. If the current factor is the value desired by the programmer, he may leave the value unchanged by pressing either the MFXT switch or the ENTER switch. Pressing the NEXT switch will step the Monitor to the next compensation factor in the table. Whether this step was toward a factor related to higher temperature or to greater thickness depends upon which of the two indices was last accessed prior to the compensation factor access. The programmer will be reminded of which index was last accessed by the flashing

of its LED during the compensation factor reprogramming sequence. Pressing the ENTER switch will terminate the compensation factor reprogramming sequence. If the programmer wishes to alter the value of the indexed factor, he must explicitly enter the desired value by sequentially pressing switches according to their secondary interpretation. He must then press the ENTER switch to store the new compensation factor and to terminate the compensating factor reprogramming sequence. Any attempt to enter a factor in excess of 9.99 will cause an error condition.

5.7.2.2. Accept/reject parameters. The monitor is delivered with the capability of revising the thresholds and coefficients used in classification and analysis of the ultrasonic reflection pattern during tire quality testing. There are four parameter categories grouped according to the related tire fault. These categories are:

- Porosity detection parameters
- Separation detection parameters
- Degradation detection parameters
- Eondline detection parameters

Where a parameter is uniquely specified by the operational mode switch settings of TIRE TYPE and PETREAD MODE, reprogramming mode access to that parameter will yield its current stored value to display and modification. In all cases, access to the parameter value will be mediated by an intermediate access through the name of the parameter. That is, the programmer will not access the parameter value until he enters the parameter name using the secondary interpretation of the switches followed by an ENTER switch depression.

The principal function of the intermediate name access is to provide a built-in list reminding the programmer of the various parameters available. Thus, after he selects the parameter category, the programmer may access the parameter value by one of two methods. He may sequence through parameter names by successively pressing the NEXT switch until he finds the desired name and enters it, or he may enter the parameter name immediately without prior searching. In either case, it is the active entry of the name followed by pressing the ENTTPP switch that provides access to the value. If a nonexistent or unrelated parameter name is entered, an error condition will result.

Parameters can be of a threshold type and a coefficient type. Thresholds are integer numbers scaled to the 0 to 30 quality scale displayed during inspection. Coefficients are real positive numbers restricted to values less than 10.00. Any entry of an unexpected or inappropriate number, name, or character will generate an error condition. If the parameter value is to be left unaltered after viewing, the programmer simply presses the ENTER switch to return to a state where he can start another reprogramming sequence. However, if the programmer wishes to alter the value of the parameter, he must enter the new value by pressing the switches according to their secondary interpretation. If the new value is not an interger, the DF (decimal point) switch must be used. The new value will be echoed on the TQM display, but will not be stored until the programmer presses the ENTER switch.

Two examples are presented to clarify the techniques of accept/reject parameter reprogramming:

• Example 1: Altering the Porosity Detection Amplitude threshold applied to Fost-Petread Inspection: This parameter can take on one of two values depending on whether the RETREAD MODE is PRF or PCST. Therefore, before initiating the porosity accept/reject parameter reprogramming sequence, the programmer must assure that he will access the correct parameter by first selecting the appropriate RETREAD MODE. This can be done without leaving the reprogramming mode by simply pressing the desired EFTREAD MCDE switch according to its operational interpretation. The LED confirms successful mode selection. The programmer can now begin the reprogramming sequence by pressing the NEXT and POR DATA switches in order. The displays will show a flashing NEXT LED and the name of the accessible porosity parameter, All. As indicated in the upper left of Figure 5-52 there is only this one parameter name in the list and it accesses PETREAD MODE-specific storage. To access the parameter value, the programmer next enters the name by pressing the switch sequence:

A 1 1 ENTEP

using secondary interpretation of the relevant switches. At this point, the integer value (usually a 10) will appear. If the programmer does not want to change this value, he can exit this reprogramming sequence by pressing the ENTER switch and the value will be retained. However, if the programmer wishes to change this parameter to a new value, he must enter the new value by pressing switches according to their secondary interpretation. For example, if the new value is to be 5, the programmer must press the switch sequence:

5 ENTER

The value is stored when the ENTER switch is pressed.

• Example 2: Altering the Fondline Detection Parameter C1 Applied to Passenger 1 Inspection: The bondline



Figure 5-52. Parameters

accept/reject parameters can take on 1 of 12 possible values depending on the TIRE TYPE selected and, if a textile TIRE TYPE is selected, the RETEFAD MODE. Therefore, before initiating the bondline parameter reprogramming sequence, the programmer must assure that he will access the correct parameter by first selecting the appropriate TIRE TYPF and, if necessary, the RETREAD MODF. As explained in example 1, this can be done without leaving the reprogramming mode by pressing the relevant switches according to their operational interpretation. The LEDs will confirm successful selection. Incorrect selections will create an error lock condition with a displayed "E," capable of reset by pressing the CLEAR switch. Cnce the above assurances are made, the programmer can begin the bondline parameter reprogramming sequence by pressing the NEXT and BOND DATA switches in order. The displays will show a flashing NEXT LED and a name of a bondline parameter. As indicated in the lower right of Figure 5-52, there are two such parameters (B2 and C1) for each steel-belted TIFE TYPE and one such parameter (A18) for each textile plied TIRF TYPE. However, each textile tire bondline parameter can take on one of two values depending on the RETREAD MODE selected (as in example 1.) The reprogramming of textile tire bondline parameters is similar to that described in example 1.

In this example, the TIRE TYPE selected is PASS/S 1. Therefore, the first bondline reprogramming sequence display will be the parameter name B2. At this point, the programmer can sequence through the name list by consecutively pressing the NEXT switch and eventually he will reach the name he wants (in his case, C1). To access the parameter value, the programmer must enter the parameter name. In this example, this done by pressing the switch sequence:

C 1 ENTER

At this point, a non-integer value (usually 0.60) will appear. To change the parameter to a new value, the programmer must now enter the new value by pressing switches according to their secondary interpretation. For example, if the new value is to be 0.70, the programmer can press any one of the following switch sequences:

DP 7 ENTER

DP 7 EMTEP

O DP 7 O ENTER

O DP 7 O ENTEP

The value will stored when the ENTEP switch is pressed.

5.7.2.3. Direct memory reprogramming. The Monitor is delivered with the capability of directly examining and revising the microcomputer PAM. All communications for this type of reprogramming are done using numbers expressed in the base-sixteen, or hexadecimal, number system. Memory that can be altered lie in these address ranges:

ECOO - EFFF FEPPOM

FOOO - FF7F General RAM

FF80 - FFFF Monitor Stack Region

Any attempt to alter memory that lies outside these ranges will result in an error condition. However, any memory within the microcomputer's addressing space of 0000 - FFFF can be examined.

CAUTION

DIRECT MEMOPY PEPPOGPANMING SHOULD ONLY BE PERFORMED BY FERSONS WITH MICROCOMPUTER SYSTEM EXPERIENCE IN AND KNOWLEDGE OF THE ALLOCATION OF MEMORY WITHIN THIS MONITOR. IMPROPER ALTERATION OF MEMORY CAN CAUSE UNPREDICTABLE MALFUNCTIONS. THE PECGEAMMER ESPECIALLY SHOULD BE AWARE THAT ALTERATION OF MEMORY IN THE STACK REGION WILL CAUSE A MONITOP "CRASH."

Normal alterations for TQM maintenance or adjustment will only be done within the EEPROM address range. The TQM automatically handles addressing for alterations of the temperature/thickness compensation tables and of the accept/reject parameters as described in pars. 5.7.2.1. and 5.7.2.2. Other alterations are accomplished by directly accessing EEPROM as described in this section.

Most of the directly accessed parameters are not used as they reside in EEPROM. Instead, each is loaded into RAM by an appropriate selection process triggered from the front panel keys and it is from that RAM that the CPU reads its value. Because of this, the programmer should remember to reselect the mode(s) of the desired inspection after altering EEPRCM in this way so as to activate the altered parameter values.

Access to any memory is typically executed by first programming the memory address and then accessing the addressed memory or consecutive string of memories.

• Addressing. Setting the memory address index is performed by pressing the NEXT and ADDRESS switches in sequence when
in the reprogramming mode. This initiates the memory address reprogramming sequence as indicated by the flashing of the NEXT LED and by the display of the current address in hexadecimal code. If the displayed address is the value desired by the programmer, he should leave it unchanged by pressing the ENTEP switch next in sequence. Nowever, if the programmer wishes to alter the address, he may do so by one of two methods. One method is to successively press the NEXT switch until the desired address is displayed. The other method is to explicitly enter the desired address by sequentially pressing switches according to their secondary interpretation. Either method requires depression of the ENTER switch to set the new address and terminate the memory address reprogramming sequence.

Memory Examination/Alteration. If the programmer knows or has set the address, access to the memory can be made by pressing the NEXT and MEM DATA switches in sequence when in the reprogramming mode. This initiates the direct memory reprogramming sequence as indicated by the flashing of the NEXT LED and by the display of the addressed memory content in hexadecimal code. If the displayed content is the content desired by the programmer, he may leave it unchanged. by pressing the NEXT or the ENTEP switch. Pressing the next switch will step the Monitor to the next address in memory and display its contents. Fressing the FMTEP switch at any time will terminate the direct memory reprogramming sequence. If the programmer wishes to alter the content of the addressed memory, he must explicitly enter the desired content by sequentially pressing switches according to their secondary interpretation. He must then press the ENTER switch to store the new memory contents and to terminate the direct memory reprogramming sequence.

5.7.2.4. Summary of reprogramming key commands. The following is a summary of the reprogramming sequence initiating commands discussed above. The accompanying flowchart in Figure 5-53 illustrates the process flow within a typical reprogramming sequence. The programmer's actions are enclosed in rectangles; the Monitor's responses or processes are enclosed in circles. Ten switches have a primary interpretation when the Monitor is in the reprogramming mode and each one, when pressed subsequent to an initial NEXT switch depression, will cause a display of the current stored value of the associated parameter. For example, a NEXT TEMP switch sequence would cause a display of the current value of the stored temperature index to a temperature/thickness compensation factor.

From this state, the programmer can 1) terminate the reprogramming sequence by pressing the ENTEP switch, 2) step to another value of the associated parameter by pressing the NEXT switch to cause the Monitor to increment an index i by an associated amount j, or 3) insert a new



Figure 5-53. Reprogramming Sequences

value by pressing switches according to their secondary interpretation in a sequence terminated by an ENTER switch depression.

Note that in certain cases, entry of values according to their secondary interpretation of the keys will not terminate the reprogramming sequence, but will branch to a second display of a current stored value. This point is identified on the flowchart by a "#." This occurs when accept/reject parameters are being reprogrammed and access to the specific parameter value requires invocation of the parameter name. The first entry of a value in this case in interpreted as the entry of the parameter name. The branch to second display then shows the current value of the parameter itself. This branch will occur only once. The stepping use of the NEXT switch will not work in this branch.

As an illustration of this type of interaction, suppose the programmer has entered the switch sequence NEXT SEP DATA. If the selected TIPE TYPE is any TRUCK/S or PASS/S, the display will show the second belt separation threshold name A1. It cannot clearly show the thresholds (Bn's) associated with various comparative structural tests. The programmer must now enter a letter-number combination to specify the parameter he wants to access, e.g., A1. The branch will then show the value stored for the threshold A1. These procedures apply to all the following switch commands.

(1)	Direct Memory	Reprogramming
NEXT	ADDRESS	Accesses memory address for memory read/write
NEXT	MEM DATA	Access memory for memory read/write
(2)	Temperature/Th	ickness Compensation Factor Feprogramming
NEXT	T/T DATA	Accesses compensation factor
NEXT	TEMP	Accesses temperature factor index to factor
NEXT	THICK	Accesses thickness index to factor
(3)	Accept/Reject	Parameter Peprogramming
NEXT	POP DATA	Accesses porosity threshold name
NEXT	SEP DATA	Accesses separation parameter name
NEXT	DEG DATA	Accesses degradation parameter name
NEXT	BOND DATA	Accesses bondline parameter name
(4)	Reprogramming	Mode Control
NEXT		Steps through list
CLEAR	1	Aborts reprogramming sequence, resets errors
ENTER		Terminates reprogramming sequence.

APPENDIX A

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EEPROM LISTING

A-2

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HEVLETT-PACKARD: 6085 Assembler FILE: EAROMI:TQMDOC

SOURCE LINE LOCATION OBJECT CODE LINE



A-3

20/16

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115 deg Wed, 16 Oct 15E5, 12:31 70 deg TEMPERATURE/THICKNESS COMPENSATION TABLES TEMPERATURE HFWLETT-PACKARD: 8085 Assembler TEXTILE-BELTED SOURCE LINE H U M Z A SS TRUCK 30 deg 4/16" ÷ ÷ # LOCATION OBJECT CODE LINE 60 89 81 82 82 61 FILE: EARONI: TOMDOC 02400215 02540220 02620225 Ø3ØØØ2EØ Ø325Ø265 Ø31ØØ27Ø 02700230 02750235 03200263 03250265 02500220 02850245 02800240 02900250 02950255 02600225 03150275 A-4

20/16

115 deg Wed, 16 Oct 1965, 13:31 104H,158H,136H,117H,100H,086H,074H,063H,054H,047H,040H,034H,032H,025H,022H,019H 016H MULTIPLICATION FACTOR FOR TEE RUBBER BLOCKS...ENABLE FINAL FACTORS DECISION IS MADE 70 deg (THICKNESS ONLY) TFMPERATURE/THICKNESS COMPENSATION TABLES: TEMP ERATURE HEWLRTT-PACKARD: 6065 Assembler STEEL-PELTED *RUBBER CALIBRATION BLOCK HHUMZHON SOURCE LINE RUBBER TABLE 30 deg TRUCK 4/16" * 20/16 *UNITY 4 * VBEN 1 TSRTBL NG* 20 3 4 ÷ ŧ ¥ 115 05 05 05 05 14 19 20 48 49 51 LOCATION OBJECT CODE LINE 39 40 42 46 47 50 45 53 41 44 FILE: EAROM1 : TOMDOC 02240191 02130181 02020172 01920163 01830155 01830147 01650147 01550143 01550133 01550133 01550126 01510126 01410120 01340114 01280108 01210103 01150098 E72C E72C Ø1ØØØ1ØØ 02620222 02480211 02366201 E4C8 E4C8 E4 EC E708

FAGE

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A-5

(LOV CONTROL VOLTAGE) (HIGH CONTROL VOLTAGE) GAIN OF RECEIVER STAGE 2 WHEN GAP TIPE ACTIVE ESTIMATED FROM SCOPE GAIN OF RECEIVER STAGE 1 MAXIMUM AGC GAIN AT 5/4" (MINIMUM AGC GAIN AT 1/4" (1 DAC SLOPE GAIN OF RECEIVER STAGE 2 W SR*(0930-0150)/SC 7.8 US N SR*(2930+0150)/SC 10.8 US N SR*(1660-0150)/SC 17.1 US N SR*(1660+0150)/SC 20.1 US N SR*(2790-0150)/SC 26.4 US N SR*(2790-0150)/SC 26.7 US N SR*(3720+0150)/SC 29.4 US N SR*(4650+0150)/SC 49.0 US N SR*(4650+0150)/SC 48.0 US รถ รัต 23 **.0** HEWLETT-PACKARD: EP85 Assembler SR#2390/SC SR#3990/SC 12=50/4.23 15=63/4.23 22=92/4.23 15=63/4.23 15=63/4.23 12=50/4.23 15=63/4.23 22=92/4.23 12=50/4.23 15=63/4.23 12=50/4.23 15=63/4.23 15=63/4.23 12=50/4.23 15=63/4.23 12=50/4.23 *CALIBRATION CONSTANTS: *EARDVARE GAIN VALUES: ØAD2H 0900h 0740h 0206h 0964h GRP_OUTGAIN DV Ø9E8H 4 A 0 ĽS E ROM_INGAIN DV E S ROM_FN_GAIN DV E ROM_PT_GAIN DV E ROM_STOPE DV Ø ROM_STOPE DV Ø CAL_LOW_NINLOW CAL_EIGH_WINDOW SOURCE LINE DV 50 PSR I DV 50 PSR I DV 50 PSR I DV 63 TSR I DV 42 RV DV 42 RV DV 50 PSR II DV 63 TSR II DV 63 TSR II DV 63 TSR II DV 92 TSR II ORG BASE+0780H 50 PSR_II 63 TTX_II 50 TSR_II 50 PSR I 50 TTX I 50 TSR I 63 GRP I 42 RN DAC_HIGH1 DAC_HIGH1 FAC_LOW2 DAC_HIGH2 DAC_LOW3 DAC_LOW3 DAC_LOW4 FAC_LOW4 DAC_LOW4 DAC_LOW4 DAC_LOW45 DAC_LOW5 CAC_FIGH4 AMPTABLE ALTTABLE **DS 4** M 2333332 M LOCATION OFJECT CODE LINE FILE: EAROM1 : TQMDOC 0AD2 0900 0740 0206 0984 01DE 031E 00000 00000 00106 00100 00200 00200 00200 00200 00200 00200 00200 00200 00200 00200 276A 09B8 1760 1762 1762 1784 1786 1786 E7A4 E7A6 E7A6 E7A6 E7A6 E7A6 E7A6 E7B0 E7B2 E790 E790 E795 E795 E796 E798 E798 E798 E798 E798 E7AØ E7AØ E7A2 E7BB E7BB E7BB E7BB E7BB E7C8 E7C8 E7C8 E7C8 E760 E784 E7CC A-6

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FILE: EAROMI:TQMDOC HEVLETT-PACKARD: 8085 Assembler Location object code line sourcf line E7D2 0070 214 AGC TRIG_OFFSET DY SR*0600/SC TIME AGC TAKES EFF

PERCENTAGE AMPLITUDE VARIATION AMPLITUDE OF "SIGNIFICANT" BONDLINE =10 SEPARATION REJECTION LIMIT COEFFICIENT DY SR*0600/SC TIME AGC TAKES EFFECT AFTER TUR TRIGGER TV SR*1600/SC TIME MAIN BANG OCCURS AFTER TDR TRIGGER 0.265us PER DEGREE PER INCH 10 20 01 EW 0025H BCD REPRESENTATION DV 0042H BCD REPRESENTATION DV 0064F BCD REPRESENTATION - 3.00 us + 3.00 us DW -SR*£300/SC DW SR*£300/SC EV 652/16 DF 136-(-16) DV DS 4 4 2 DS DS AGC TRIG_OFFSET MAINEANG_OFFSET HOMOL_OFFSET SIG_BONDLINE BL_RED_FACTOR MULTRING_LOW MULTRING_HIGH SHIFTPERTEMP TEMP_SLOPE TEMP_OFFSET 0070 0140 0025 0042 0064 0028 0096 0000 FFC4 003C E7D2 E7D4 E7DA E7DC E7D6 E7DE E7E2 E7E4 E7E6 E7E8 E7EA E7EC E7EC

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HEWLETT-PACKARD: 6085 Assembler Wed, 16 Oct 1985, 13:31	NE SOURCE LINE	34 ORG BASE+0800H 35 36 * FEAK EXTRACTION AND WINDCVING PARAMETERS:	SY 38 PSR I_PRE_NAMP DB 6 MAXIMUM NOISE AMPLITUDE FROM GROUND 39 PSR I_PRE_NVID DE 6 53+06 NS MAX NOISE PEAKVIDTE 39 PSR I PST WAMP DE 6 MAXIMUM WOISE TEAKVIDTE PROM CROUND	LI PSR_L_FST_MAIN DE G 50#06 NS MAXING NUISE ANFLIUWE FAGT GAOUND 11 PSR_L_FST_MAID DE G 50#06 NS MAX NOISE PEAKUIDTH 12 PSR_L_RIGOUT DE SR#0760/SC 7.60 LS MAIN BANG RIGOUT MASK 13 PSR I ENNGAP DE SR#070/SC 0.70 N.5 INTROPE GAUTOPE GAO	14 PSRTITUTENIN DV SR#0150/SC 1.50 US NARROV ENVELOPE LIMIT 15 PSRTITENVULTE DV SR#0300/SC 3.00 US MAXIMUM ENVELOPE WILTH 16 PSRTITENVULTE DV SR#1500/SC 15.00 US MAX GARRAGE TIME LIMIT ("FAR CLEANLINESS TIME")	17 PSR I NPORTIME DV SR#0600/SC E.@0 US MIN POROSITY TIME LIMIT ("NEAR POROSITY TIME") 18 PSR I FPORTIME DV SR#1530/SC 15.00 US MAX POROSITY TIME LIMIT ("FAR POROSITY TIME") 10 PSR I USABATHE DU SD#05600/SC 3 40 US MIN DEAV TIME OFFERE DEADS DAILY ("FAR POROSITY TIME")	19 FOR LENGTHINE DE SATOOUGAS DOUT DE MIN FAM TIME OFFOET BEFORE FINA ("FAR STRUCTURE TIME") 50 PSR LEFSTRTIME DE SA#1030/SC 13.00 US MAI PEAK TIME OFFSET AFTER PMAI ("FAR STRUCTURE TIME") 51 PSR LEF DE SR#0200/SC 2.00 US MAI 2ND BELT - LINER TIME DIFFERENCE 52 PSR LEF DE SR#0400/SC 4.00 US MAI 2ND BELT - LINER TIME DIFFERENCE	33 54 DS 36 55	56 TTX_I_PRE_NAMP DE 5 MAXIMUM NOISE AMPLITUDE FROM GROUND 37 TTX_I_PRE_NVIC_CB 4 50*04 HS MAX NOISE PEAKWIDTH	56 TTL I PST NAMP DB 5 MAXIMUM NOISE AMPLITUDE FROM GROUND 59 TTL I PST NVID DB 4 50404 NS MAX NOISE PEAKWIDTH	SØ TIT I HINGOUT DV SR#ØE20/SC 8.02 US MAIN BAKG RINGOUT MASK 51 TIT I ENVGAP DV SR#Ø200/SC 2.00 US INTER-ENVELOPE GAP 52 TIT I EIDTEMIN DE SR#Ø150/SC 1.50 US NARROW ZNVETOPF TIMIT	53 TIX_I_ENVWIDTH DW SA*0600/SC 6.02 US MAXIMUM ENVELOPE WIDTH 54 TIX_I_FCLNTIME DW SR*2500/SC 25.00 US MAX GARBAGE TIME LIMIT ("FAR CLEANLINESS TIME")	55 TTL I NPORTIME DW SR*1000/SC 10.02 US MIN PCROSITT TIME LIMIT ("NEAR POROSITY TIME") 56 TTX I FPOATIME DW SR*2900/SC 29.20 US MAX POROSITY TIME LIMIT ("FAR POROSITY TIME") 57 TTY I NEAPTIME DW SD#1200/SC 10 00 US MIN DEAY WIME TEADE DA "NEAR CONSTITUE")	111. TRAINING TO SUPPOSE 1. TO NAME AND THE DIFFERER AND AND AND TRAINING THE TIME (" FAR STRUCTURE TIME") 18 TIX. TRATIME DW SR*1100/SC 11.02 US MAX PEAK TIME OFFSET AFTER PA (" FAR STRUCTURE TIME") 19 TIX. T. T. DW SR*0000/SC	70 TTX_I_LBF UF SR*0000/SC 71 22 DS 32	73 TEP I DPF NAMD DP 0 MAYAMIM NOTET AMDITUTIT PDAM EDATINE	75 TSR I PRE NVID DB 6 50*2C NS MAX NOISE PEAKWIDTE FROM GROUND 76 TSR I PRE NVID DB 6 50*2C NS MAX NOISE PEAKWIDTE 76 TSR I PST NAMP DE 6 MAXIMUM NOISE AMPLITUEE FROM GROUND	77 TSR I PST NWID DB 6 53406 NS MAI NOISY PEAKWIDTH 28 TSR I RINGOUT DV SR*0F00/SC 6.20 us MAIN BANG RINGOUT MASY	19 TSH. I EAVGAP DW SA*0100/SC 1.20 US INTER-ENVELOPE GAP 10 TSR. I WIDTHMIN DW SR*0200/SC 2.02 US NARROW ENVELOPE LIMIT	31 TSH I ENVWIDTH DW SH*0400/SC 4.20 US MAXIMUM ENVELOPE WIDTH 32 TSR I FCLNTIME D& SR*2500/SC 25.02 US MAX GARBAGE TIME LIMIT ("TAR CLEANLINESS TIME")	33 TSR_I_NPORTIME DW SR*1320/SC 13.00 US MIN POROSITY TIME LIMIT ("NEAR PCROSITY TIME") 34 TSR_I_FFORTIME DW SR*2700/SC 27.00 US MAX POROSITY TIME LIMIT ("EAR POROSITY TIME")	25 TER I_NSTRTIME EW SR*1000/SC 10.02 US MIN PEAL TIME OFFSET BEFORE PMAX ("NEAR STRUCTURE TIME") 26 TER I_FETRTIME DW SA*1200/SC 12.00 US MAX PEAK TIME OFFSET AFTER PMAX ("FAR STRUCTURE TIME")	37 TSR_I_LEN DW SR#0300/SC 3.00 VS MIN 2NL BELT - LINER TIME DIFFERENCE 36 TSR_I_LEF DW SR*0600/SC 6.22 VS MAX 2NG BELT - LINER TIME DIFFERENCE 39	90 DS 36
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FILE: EAROMI : TQMDOC	LOCATION OBJECT CODE		1800 06 1801 06 1802 06	E803 86 E804 0098 E806 0008	E808 001E E80A 003C E80C 012C	E80E 0078 E810 012C T812 0064	E814 00CE E816 0028 E818 0050	Eela .	E840 05 E841 04	P E842 05	0 2344 0010 0 1846 0028 1848 0011	E84A 0078 E84C 01F4	1841 0008 1850 0244 1852 0009	E854 00DC E856 0000	E658 2000 E85A	T R R R R	E881 Ø6 E882 ØE	E883 06 E864 00A0	E868 0028	LEEA 0030 EBEC 0174	E86E Ø104 E692 Ø21C	E892 ØØCE E894 ØØFØ	1896 ØØ76 1898 ØØ76	AE9A

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Wed, 16 Oct 1965, 13:31	AXIMUE NOISE AMPLITUDE FROM GROUND AXIMUM NOISE FEAKWITH AXIMUM NOISE PEAKWITH AXIMUM NOISE PEAKWITH ANN BANG RINGOUT MASK MTRA-ENVELOPE LIMIT ARROW ENVELOPE LIMIT ("FAR CLEAKLINESS TIME") ARROW ENVELOPE LIMIT ("FAR CLEAKLINESS TIME") ARROW ENVELOPE LIMIT ("FAR CLEAKLINESS TIME") ARROW ENVELOPE LIMIT ("FAR CLEAKLINESS TIME") ARROW ENVELOPE LIMIT ("FAR POROSITY TIME") ARROW ENVELOPE LIMIT ("FAR CLEAKLINESS TIME") ARROW ENVELOPE LIMIT ("FAR CLEAKLINESS TIME") ARROW ENVELOPE LIMIT ("FAR CLEAKLINESS TIME") ARROW ENVELOPE LIMIT ("FAR POROSITY TIME") ARROW ENVELOPE LIMIT ("FAR POROSITY TIME") ARROW ENVELOPE LIMIT ("FAR POROSITY TIME") ARROW ENVELOPE LIMIT ("FAR POROSITY TIME") ARROW ENVELOPE LIMIT	AXIMUM NOISE AMPLITULE FROM GROUND AXIMUM NOISE PEAKWIDTH AXIMUM NOISE PEAKWIDTH AX NOISE PEAKWIDTH ANNONE DEAVELOPE GAP ANNOW ENVELOPE LIMIT ARROW ENVELOPE LIMIT ARROW ENVELOPE LIMIT AXIMUM ENVELOPE LIMIT AX CARBAGE TIME LIMIT AX CARBAGE TIME LIMIT AX POROSITY TIME LIMIT AX POROSITY TIME LIMIT AX POROSITY TIME LIMIT AX POROSITY TIME LIMIT AX PEAK TIME OFFSET AFTER PA ("FAR STRUCTURE TIME")	AXIMUM NOISE AMPLITUDE FROM GROUND AX NOISE PEAKWIDTH AXIMUM NOISE AMPLITUDE FROM GROUND AXIMUM NOISE PEAKWIDTH AIN BANG RINGOUT MASK NTER-LUNELOPE GAP ARROW ENVELOPE GAP ARROW ENVELOPE GAP ARROW ENVELOPE GAP ARROW SUVELOPE VIDTH ARROW SUVELOPE VIDTH ARROW SUVELOPE VIDTH ARROW SUVELOPE VIDTH ARROW SUVELOPE VIDTH ARROW SUPELOPE VIDTH ARROW SUPELOPE VIDTH ARROW SUPELOPE VIDTH ARROW SUPELOPE VIDTH ARROW SUPELOPE VIDTH ARROW SUPERT TIME LIMIT AXINUT FIME LIMIT AX POROSITY TIME POROSITY TIME POROSITY TIME
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ij Assembler	6 6 7 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8	5 4 5 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8	B 6 6 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8
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HEWLETT-PACKARD: NE SOURCE LINE	22 PSR II - PRE-NAMP 24 PSR II - PRE-NAMP 25 PSR II - PRE-NAMP 26 PSR II - PRE-NAMP 26 PSR II - PRT-NAMP 27 PSR II - PRT-NAMP 28 PSR II - FULGANTIME 28 PSR II - FULUTIME 28 PSR II - FULUTIME 29 PSR II - FULUTIME 20 PSR II - FULUTIME 28 PSR II - FULUTIME 29 PSR II - FULUTIME 20 PSR II - FULUTIME 29 PSR II - FULUTIME 20 PSR II - FULUTIME 20 PSR II - FULUTIME 20 PSR II - FULUTIME 29 PSR II - FULUTIME 20 PSR III - FULUTIME 20 PSR II - FULUTIM	10 11 17 17 17 17 17 17 17 17 17	28 TSR II PRE NAMP 29 TSR II PRE NAMP 31 TSR II PST NAMP 32 TSR II PST NAID 33 TSR II PST NAID 33 TSR II ENVELOUT 34 TSR II ENVELOUT 35 TSR II ENVELOUT 36 TSR II ENVELOUT 37 TSR II ENVELOUT 38 TSR II ENVELOUT 38 TSR II ENVELOUT 39 TSR II ENVELOUT 39 TSR II ENVELOUT 30 TSR II ENVELOUT 30 TSR II ENVELOUT 31 TSR II LEN 41 TSR II LEN 42 DS 38
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FILE: EAROM1 : TQMDOC LOCATION OBJECT CODE	E8C8 Ø6 E8C3 Ø6 E8C3 Ø6 E8C4 Ø098 E8C6 Ø098 E8C6 Ø098 E8C5 Ø12C E8C5 Ø12C E8D2 Ø06 E8D2 Ø064 E8D2 Ø064 E8D8 Ø058 E8D8	E900 05 E901 04 E901 04 E903 05 E904 0028 E904 0028 E906 0028 E916 0078 E916 0078 E914 0008 E914 0000 E914 0000 E914 0000 E914 0000 E914 0000	E940 08 E941 06 E943 06 E944 066 E944 0016 E944 0014 E944 0056 E944 01174 E956 0056 E956 0056 E956 0058 E956 0058 E958 0078 E958 0078

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FILE: EAROM1:TQMDOC REWLETT-PACKARD: 8285 ASSembler

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LOCATION OBJECT CODE LINE SOURCE LINE

G ROUND G ROUND	GRODND GROUND
FROM FROM	FROM FROM
MAXIMUM NOISE AMPLITUDE MAX NOISE PEAKVIDTE HAXIMUM NOISE AMPLITUDE MAX NOISE PEAKVIDTE MAX NOISE PEAKVIDTE MAX NOISE PEAKVIDTE MAX NOISE PINGOUT MASE INTER-ENVELOPE GAP MAXIMUM ENVELOPE VIDTH MAXIMUM ENVELOPE VIDTH MAXIMAN ENVELOPE VIDTH MAXIMIM ENVELOPE VIDTH MAXIMIM ENVEL	MAXIMUM NOISE AMPLITULE MAX NOISE PEAKWIDTH MAXIMUM NOISE AMPLITUDE MAXIMUM NOISE PEAKWIDTH MAIN BANG RINGOUT MASK INTER-ENVELOPE GAP NAAROV ENVELOPE GAP HAXIMUM ENVELOPE LIMIT MAXIMUM ENVELOPE LIMIT MAXI POROSITY TIME LIMIT MIN PEAK TIME OFFSET MIN PEAK TIME OFFSET
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16 7 16 58##0380/SC 58##0280/SC 58##0280/SC 58##0010/SC 58##00010/SC 58##0000/SC 58##0000/SC 58##0000/SC 58##0000/SC	B B B B B B B B B B B B B B B B B B B
GRP_PRE_NWID GRP_PRE_NWID GRP_FST_NAMP GRP_FST_NAMP GRP_RINGOUT GRP_ENVVIDTH GRP_ENVVIDTH GRP_FCLNTIME GRP_FCLNTIME GRP_FSTRTIME GRP_I_LEF GRP_I_LEF GRP_I_LEF GRP_I_LEF	RN_PRE_NAMP RN_PRE_NAMP RN_PST_NAMP RN_PST_NAMP RN_PST_NAMP RN_ENVEGUT RN_ENVETAMIN RN_ENVETAME RN_NPORTIME RN_NSTRTIME RN_ISTRTIME RN_ISTRTIME RN_I_STRTIME RN_I_LBF DS 36
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HEWLETT-FACKARD: 6285 Assembler FILL: EAROM1:TQMDOC

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> SOURCE LINE LINE LOCATION OPJECT CODE

*PASSENCER STELL-BELTED TIRE I PLAK IDENTIFICATION PARAMETERS: щ DW @060H I.D. PARSE COEFFICIENT OF PEAK C1_PSR_I 0060

STEEL-BELTED TIRE I ACCEPT/REJECT PARAMETERS: *PASSENGER EAOO

0024

ST SB1 COLFFICIENT OF BONDLINE ROUGHNESS ST SB1 COEFFICIENT OF SE2 SEPARATION ST SB1 COEFFICIENT OF SB2 SEPARATION ST SB1 COEFFICIENT OF SB2 AMPLITUDE ST SB2 COEFFICIENT OF PLT DEGRADATION ST SB2 COEFFICIENT OF PLT SEPARATION ST SB2 COEFFICIENT OF PLT SEPARATION ST SB2 COEFFICIENT OF PLT SEPARATION ST SB2 COEFFICIENT OF THYLIED SB2 DEGRADATION ST SB2 SEPARATION THRESHOLD = 21 ST IMPLIED SB1 SEPARATION THRESHOLD = 21 ST IMPLIE SB1 SEPARATION THRESHOLD = 21 ST IMPLIE SB1 SEPARATION THRESHOLD = 21 ST IMPLIE SB1 SEPARATION THRESHOLD = 21 MIN BONDLINE-PLY PEAK SEPARATION 56.5/64 55.9/64° 83.0/64" 18.5/64 *TRUCK TEXTILE-PLIED TIRE I PEAK ILENTIFICATION PARAMETERS DV SH#3000/SC 30.00 US DEPTH TO LINER US LEPTH TO LINER TO PLY TO PLY SR*1000/SC 10.00 US DEPTE US DEPTH 44.00 DW S3*2990/SC 29.90 treet treet treet treet treet treet treet treet treet TEST DW SR#4400/SC 0024 E A/R 1 00200 A/R 1 00200 A/R 1 00200 A/R 1 00000 A/R 1 7 A/R 1 7 A/R 1 0000 A/R 1 7 A/R A C1 TTI I PRE PREIOWLIMIT 1 C2 TTX I PRE PREHIGHLIMIT 1 C1 TTX I PST POSTLOWLIMIT 1 C2 TTX I PST C2 TTX I PST POSTHIGHLIMIT_1 C3 TTI DS 38 50 50 83 10 113 115 01 0258 0256 0600 0600 0008 0370 EA40 EA40 EA16 EA18 EA42 EA ØA EA ØC EA10 EA14 EA 44 EA46 EA46 EAØE EA42 EA44 EA 02 EA06 EA08 **EA12** EALA EA 04

A-11

SU 5.60 DV SR*@560/SC UGUTAPINIT_1 LOUGAPINIT_1 C4 TTX I MIDGAPINIT_1 416 417 417 419 419 420 00700 EA48 EA48 EA4A

US MIN PLY-LINER PEAK SEPARATION E.20 DW SR#0820/SC 0044 EA4A

DW SR#1300/SC 13.00 US MAI PLY-LINER PEAK SEPARATION C5_TTX_I HIGHGAPLIMIT_1 0104 EA4C EA4E EA4E EA4C

C6 TTX 0028

2.00 US CAP LIMIT DW SR*0200/SC TEXTNULLCAP_1

*TRUCK TEXTILE-PLIED TIRE I ACCEPT/REJECT PARAMETERS:

იწიიწი DEGRADATION THRESHOLD FOR 0-5 YRS SEPARATION THRESHOLD FOR 0-5 YRS BONDLINE THRESHOLD FOR ALL AGES DEGRADATION THRESHOLD FOR 0-5 YRS SEPARATION THKESHOLD FOR 0-5 YRS BONDLINE THRESHOLD FOR ALL AGES TEST TEST TEST TEST TEST 00138 A/R 7 00938 A/R 7 00258 A/R 7 00138 A/R 7 00138 A/R 7 00388 A/R 7 A12_TTX_1_PRE D A13_TTX_1_PRE D A16_TTX_1_PRE D A12_TTX_1_PRE D A12_TTX_1_PST D A13_TTX_1_PST D A18_TTX_1_PST D 0013 0093 0025 0013 0093 0025 EA52 EA54 EA56 EA58 EA58 EA50

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EA5C

HEWLETT-PACKARD: 6085 Assembler FILE: EAROM1 : TQMDOC

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SOURCE LINF LOCATION OBJECT CODE LINE

437 *TRUCK STEEL-BELTED TIRE I PEAK IDENTIFICATION PARAMETERS: 436 439 C1_TSR_I LW 0060H I.D. PARSE COEFFICIENT OF PEAK B 441 441

EA80 0060

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ERS :	FONDLINE ROUGANESS	F SB2 SEPARATION	F IMPLIED SB1 SEPARATION	P SB2 AMPLITUDE	F PLY DEGRADATION	F PLY SEPARATION	F FLY SEPARATION	P IMPLIED SB2 DEGRADATION	RESHOLD = 21	ATION THRESHOLD = 1	RESHOLD = 21	ATION THRESHOLD = 1		
EPT/REJECT PARAMETI	SB1 COEFFICIENT OF	SB1 COEFFICIENT OI	SBI COEPPICIENT OI	SE1 COEFFICIENT OF	SEZ COEFFICIENT OI	SE2 COEFFICIENT OF	SB2 COEFFICIENT OI	SE2 COEFFICIENT OF	SE2 SEPARATION THE	IMPLIED SB1 SEPARA	SBE SEPARATION THE	IMPLIED SB1 SEPARJ		
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CEL-BELTED	DV 0024	0600 AQ	DV 0020	DV 0040	DN 2001	DV 0260	0600 AQ	DV 0030	RE DV 0089	RE DV 0004	ST DW 0089	ST DV 0004		
S TRUCE STE	L B2_TSR_I	BJ TSR I	B4_TSR_I	7 B5_TSR_I	BG TSR I	B7TSRI	BBTSRI	I B9_TSR_I	2 A1 TSR I P	SA2 TSR IP	LATTSR IP	SAZTSR_I_P	1 1 1	PS 38
44:	444	440	446	44	446	440	456	451	455	. 453	454	455	456	451
	EA 82 0024	EA84 0098	EA86 0020	EA 28 0040	EA8A 0001	EA8C 0080	EACE 0090	EA90 0030	EA92 0089	EA94 0004	EA96 0089	EA98 0004		EA 9A

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FILE: EAROMI:TQMDOC HEVLETT-PACKARD: 6085 Assembler

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LOCATION OBJECT CODE LINE SOURCE LINE

ST SEI COEFFICIENT OF BONDLINE ROUGENESS ST SEI COEFFICIENT OF SE2 SEPARATION ST SEI COEFFICIENT OF IMPLIED SEI SEPARATION ST SEI COEFFICIENT OF PLT EGRALATION ST SE2 COEFFICIENT OF PLT SEPARATION ST SE2 COEFFICIENT OF NHL SEPARATION ST SE2 COEFFICIENT OF NHL SEPARATION ST SE2 SEPARATION THRESHOLD = 21 ST IMPLIED SE1 SLPARATION THRESHOLD = 21 ST SE2 SEPARATION THRESHOLD = 21 889888 88988 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 89888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 80888 808888 80888 80888 80888 80888 80888 80888 80888 80888 80888 8088 US MIN BONDLINE-PLY PEAK SEPARATION US MIN PLY-LINER PEAK SEPARATION US MAX PLY-LINER PEAK SEPARATION SEPARATION THRESHOLD FOR 0-5 TAS EONLLINE THRESHOLD FOR ALL AGES DEGRADATION THRESHOLD FOR 0-5 YAS SEFARATION THRESHOLD FOR 0-5 YAS BONLLINE TARESHOLD FOR ALL AGES Ņ **DEGRADATION THRESHOLD FOR 2-5 YRS** IMPLIED SEI SEPARATION THRESEOLD 56.5/64" 55.9/64" 83.0/64 18.5/64" STEEL-BELTED TIRE II PEAK IDENTIFICATION PARAMETERS: *TRUCK TEXTILE-PLIED TIRE II PEAK IDENTIFICATION PARAMETERS. ACCEPT/REJECT PARAMETERS: **P** *TRUCK TEXTILE-PLIED TIRE II ACCEPT/REJECT PARAMETERS: 2060H I.D. PARSE COEFFICIENT OF PEAK **DEPTH TO LINER** TO LINER US DEPTH TO PLY US DEPTH TO PLY 2.00 US GAP LIMIT DEPTH SD ŝŋ 44.00 5.60 8.20 13.00 DW SR*3000/SC 33.00 DW SR*1000/SC 10.00 DW SR*2990/SC 29.50 TEST TEST TEST TEST TEST 0024H A/R TEST S 0090H A/R TEST S 0020H A/R TEST S 0020H A/R TEST S 2001E A/R TEST S 20002H A/R TEST S 2090H A/R TEST S 00320H A/R TEST S 0034H A/R TEST S 0069H A/R TEST S 4 CI TTX IL PRE 5 PRELOWLIMIT 2 DW SR*1000/SC 10 6 C2 TTX II PRE 7 PREHIGHLIMIT 2 DW SR*3000/SC 33 8 C1 TTX II PST 9 POŠTIOWLIMIT 2 DW SR*2990/SC 25 0 C2 TTX II PST 1 POŠTHIGELIMIT 2 DW SR*4400/SC 44 STEEL-BELTED TIRE II TEST SR*0920/SC DV SR*1300/SC SR*0560/SC DV SR*0200/SC A/A A/A A/A A/A A/A A/A A/A A/B 0053H 0025H 0013H 0013H 0093H ØØ13H 2.024H M λQ 20 A12_TTX_II_PRE D A13_TTX_II_PRE D A18_TTX_II_PRE D A12_TTX_II_PST D A13_TTX_II_PST D A13_TTX_II_PST D UCTINIT_2 LOVGAPLIMIT_2 C4 TTX II C4 TTX II DGAPLIMIT_2 C5_TTX_II HIGHGAPLIMIT_2 TEXTNULLGAP_2 *PASSENGER *PASSENGER C1_PSR_II TTX II CG TTX 36 DS 38 DS ß 0013 0025 0025 0023 0023 0023 0089 0004 0258 0256 0370 0020 00A4 0028 0000 0020 0008 0104 0600 0024 EBØØ EB10 EB14 EB14 EB16 EB16 EB18 EAC4 EAC6 EAC6 EAC8 EAC8 EACC EAD6 EBØ2 EBØ2 EBØ6 EBØ6 EBØ8 EBØ8 EBØA EPOE EACO E B 04 E B 04 EBØA EBØC EBØC EBØE EAC2 EADØ EAD4 EAD8 EADA EBØØ EB1C EAD2 A-13

HEWLETT-PACKARD: 0285 Assembler FILE: EAROM1 : TOMDOC

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> SOURCE LINE LOCATION OBJECT CODE LINE

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*TRUCK STEEL-BELTED TIRE II PEAK ILENTIFICATION PARAMETERS: 514

DW 0062E I.D. PARSE COEFFICIENT OF PEAK C1_TSR_II EB40 0060

*TRUCK STEEL-BELTED TIRE II ACCEPT/REJECT PARAMETERS: 0024H 0024 EB42

BI COEFFICIENT OF BONDLINE ROUGHNESS BI COEFFICIENT OF SN2 SEPARATION EI COEFFICIENT OF SN2 SEPARATION BI COEFFICIENT OF SN2 AMPLITUDE COEFFICIENT OF PLY DEGRADATION EZ COEFFICIENT OF PLY SEPARATION EZ COEFFICIENT OF PLY SEPARATION BZ COEFFICIENT OF PLY SEPARATION BZ COEFFICIENT OF PLY SEPARATION **=** 21 = 21 IMPLIED SHI SEPARATION THRESHOLD = SE2 SEPARATION THRESHOLD = IMPLIED SH1 SEPARATION THRESHOLD = SEPARATION THRESHOLD *ALL TYPES SHOULDER INSPECTION PARAMETERS: 00000 00201 00201 00011 00001 00001 00001 00001 00000 H6902 **B030e** 2004H 2004H **J**6800 M 20 DS 38 EB5A

0042 0042 EB60 EB62

A-14

DV 0042H A/R TEST POROSITY THRESHOLD FOR ALL TIRES DW 0042H A/R TEST PORCSITY THRESHOLD FOR ALL TIRES

A11_PRE A11_PST

0 Errors= APPENDIX B

SOFTWARE DOCUMENTATION

DAAE07-82-C-4116

ULTRASONIC TIRE QUALITY MONITOR

SOFTWARE DOCUMENTATION

The following information is provided on the Tire Quality Monitor per data requirement A002 of the subject contract in accordance with cited data item description number DI-E-1125.

- 2.1 Modifications of Prototype TQM software used in Preproduction TQM
 - 1. Addition of a separate set of absolute accept/reject thresholds for use in post-retread inspection. For Steel Radial tires, such thresholds are used to measure the presence of first or second belt separation. As a consequence of the addition, the original retread mode-independent absolute accept/reject thresholds for Steel Radial tires. labeled X1 and X2 in the flowcharts and listings, are now doubled and labeled as A1_mSR_n_PRE, A1_mSR_n_PST, A2_mSR_n_PRE, and A2_mSR_n_PST (where dummy tag m can take on the value of T or P as described in modification 2 and dummy tag n can take on the value of I or II as described in modification 4). For Truck Textile tires, such thresholds are used to measure the presence of body ply separation or degradation. As a consequence of the addition, the original retread mode-independent absolute accept/reject thresholds for Truck Textile tires, labeled X12 and X13 in the flowcharts and listings, are now doubled and labeled as A12_TTX_n_PRE, A12_TTX_n_PST, A13_TTX n PRE, and A13 TTX n_PST (where dummy tag n can take on the value of I or II as described in modification 4). Each of

these thresholds is alterable by methods described in section 6.2b of the Theory of Operation manual. Addition of this accept/reject threshold set for post-retread inspection anticipates possible differences in transmitted ultrasonic energy from the pre-retread inspection environment.

2. Separation of the set of all accept/reject thresholds used in Steel Radial tire inspection into Passenger-specific and Truckspecific sets of accept/reject thresholds. These thresholds are used to measure the presence of separation in the first or second steel belt or body ply and the presence of degradation of the body ply. As a consequence of the separation of threshold sets, the original common Steel Radial tire relative accept/reject thresholds, labeled B2, B3, B4, B5, B6, B7, and B8 in the flowcharts and listings, are now doubled and labeled as B2_PSR_n, B2_TSR_n, B3_PSR_n, B3_TSR_n, B4_PSR_n, B4_TSR_n, B5 PSR n, B5 TSR n, B6_PSR_n, B6_TSR_n, B7_PSR_n, B7_TSR_n, B8_PSR_n, and B8_TSR_n (where dummy tag n can take on the value of I or II as described in modification 4). Likewise, the original common Steel Radial tire absolute accept/reject thresholds, labeled X1 and X2 in the flowcharts and listings, are now doubled and labeled as A1_PSR_n_Pm, A1_TSR_n_Pm, A2_PSR_n_Pm, and A2_TSR_n_Pm (where dummy tag n can take on the value of I or II as described in modification 4 and dummy tag m can take on the value of RE or ST as described in modification 1). Each of these thresholds is alterable by methods described in Section 6.2b of the Theory of Operation manual. Separation of this accept/reject threshold set

into Truck and Passenger specific sets anticipates possible differences in the parameters dependent on the type of Steel Radial tire inspected.

3. Addition of a separate set of noise amplitude and width thresholds for use in post-retread inspection. For all inspection modes, such thresholds differentiate background electronic and sampling noise from valid ultrasonic reflection signals during the process of extracting reflection features from the digitized data. As a consequence of the addition, the original retread mode-independent noise thresholds. labeled mNOISEAMP and mNOISEWID in flowcharts and listings (where the dummy tag m can take on the values of PAS, TTX, TSR, RUB, and FIB), are now doubled and labeled as m_n_PRE_NAMP, m_n_PST_NAMP, m_n_PRE_NWID, and m_n_PST_NWID (where the dummy tag m now takes on values of PSR I, PSR II, TTX_I, TTX_II, TSR_I, TSR_II, RN, and GRP). Each of these thresholds is alterable by methods described in Section 6.2c in the Theory of Operation manual. Such addition anticipates possible differences in transmitted ultrasonic energy and frequency content from the pre-retread inspection environment during the inspection of retreaded tires. The following is a summary of the noise discrimination threshold additions:

Original			New		
DASNOTSEAMD	1702	PSR_I_PRE_NAMP	É800	PSR_II_PRE_NAMP	E8C0
A 20013CANL	A792	PSR_I_PST_NAMP	E802	PSR_II_PST_NAMP	E8C2
TSPNOISFAMP	0706	TSR_I_PRE_NAMP	E880	TSR_II_PRE_NAMP	E940
onio i ochan	A7A6	TSR_I_PST_NAMP	E882	TSR_II_PST_NAMP	E942

TTYNOICCAND	A7BA	TTX_I_PRE_NAMP	E840	TTX_II_PRE_NAMP	E900
TINNUISCAMP		TTX_I_PST_NAMP	E842	TTX_II_PST_NAMP	E902
	A7CE	RN_PRE_NAMP	E9C0		
KUDNUISEAMP		RN_PST_NAMP	E9C2		•
	1750	GRP_PRE_NAMP	E980		
FIBNOISEAMP	A/EZ	GRP_PST_NAMP	E982		
PASNOISEWID	A793	PSR_I_PRE_NWID	E801	PSR_II_PRE_NWID	E8C1
		PSR_I_PST_NWID	E803	PSR_II_PST_NWID	E8C3
	A7A7	TSR_I_PRE_NWID	E881	TSR_II_PRE_NWID	E941
ISKNUISEMID		TSR_I_PST_NWID	E883	TSR_II_PST_NWID	E943
TTYNOISCUID	A700	TTX_I_PRE_NWID	E841	TTX_II_PRE_NWID	E901
TIXNUISEWID	A188	TTX_I_PST_NWID	E843	TTX_II_PST_NWID	E903
DURNOTSELLED	47CE	RN_PRE_NWID	E9C1		
KUDMOIJEMIN	A/UF	RN_PST_NWID	E9C3		
FIRNOISEWID	A7F3	GRP_PRE_NWID	E981		
1 1010196010	M/6J	GRP PST NWID	E983		

4. Provision of a primary and an alternate gain calibration setpoint for each of the tire types. This was implemented by the creation of a duplicate type for each of the already e., creation of tire types Passenger Steel Radial 2. Truck Textile 2. and Truck Steel Radial 2). This was done in anticipation of extending the capability of TQM to handle additional tire categories.

Summary of elaboration of accept/reject thresholds accomplished by addition of post-retread distinction, discrimination between

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Passenger and Truck Steel Radial tires, and duplication of tire types:

New Original X12 X13 A12 TTX II PRE A12 TTX I PRE A12 TTX I PST A13 TTX I PRE A12 TTX II PST X14 A13 TTX II PRE X15 A13_TTX_II_PST A13 TTX I PST X16 •...* X17 A18_TTX_I_PRE A18_TTX_II_PRE X18 A18_TTX_II_PST A18_TTX_I_PST B2 TSR II B2 PSR II B2 PSR I B2 TSR I B2 B3 PSR I B3 TSR I B3 PSR II B3 TSR II **B**3 B4_TSR_I B5_TSR_I B4_PSR_II B4 TSR II B4 B4_PSR_I B5_TSR_II B5 PSR II B5 B5 PSR I B6_TSR_II B6 PSR I B6 TSR I B6 PSR II B6 B7 PSR I B7^{PSR}II B7 TSR II B7 B7^TSR^I B8 PSR I B8 TSR I B8_PSR_II B8_TSR_II B8

X1	A1_PSR_I_PRE	A1_TSR_I_PRE	A1_PSR_II_PRE	A1_TSR_II_PRE
	A1_PSR_I_PST	A1_TSR_I_PST	A1_PSR_II_PST	A1_TSR_II_PST
X2	A2_PSR_I_PRE	A2_TSR_I_PRE	A2_PSR_II_PRE	A2_TSR_II_PRE
	A2_PSR_I_PST	A2_TSR_I_PST	A2_PSR_II_PST	A2_TSR_II_PST

X11 A11_PRE A11_PST

> 5. Elimination of tire age range as a selectable parameter in Textile tire inspection. As a result, the accept/reject thresholds labeled as X14, X15, X16, and X17 in flowcharts and listings no

longer exist. Field tests using the TQM have found tire age to be an insignificant factor in ultrasonic tire inspection.

- 6. Enhancement of the Textile tire envelope classification logic to include an intermediate threshold for the time difference between two envelope peaks which will branch the classification algorithm away from two-envelope logic to one-envelope logic. This intermediate threshold is designated MIDGAPLIMIT in the flowcharts and listings and its value lies between the bondline-body ply maximum time difference (LOWGAPLIMIT) and the bondline-liner minimum time difference (HIGHGAPLIMIT). This enhancement was requested by the TACOM representative to improve classification in certain Textile tires where simple two-envelope logic was insufficient.
- 7. Enhancement of the Textile tire envelope classification logic to include detection of multiple ringout in the case of three or more detected envelopes and subsequent branching of the classification algorithm to one-envelope logic. The allowable variation in envelope peak times used to measure the presence of multiple ringaround is stored in EEPROM at addresses E7DA and E7DC. These are respectively labeled MULTRING_LOW and MULTRING_HIGH in the flowcharts and listings. This enhancement was made to further reduce erroneous classification resulting from envelope count ambiguity.
- 8. Reduction of absolute separation accept/reject thresholds by a preset percentage when bondline amplitude in excess of of a preset threshold is detected. This, of course, refers to the absolute second steel belt threshold in the case of Steel Radial tire

inspection and to the absolute body ply separation threshold in the case of Textile tire inspection. This reduction of absolute threshold was created to compensate for an observed apparent reduction of ultrasonic signal amplitudes returning later in time than significant bondline reflections. The reduction percentage is stored at address E7E6 in the EEPROM and is labeled BL_RED_FACTOR in the flowcharts and listings. The bondline significance threshold is stored at address E7E4 in the EEPROM and is labeled SIG_BONDLINE in the flowcharts and listings.

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9. Incorporation of a "majority logic" algorithm into the accept/reject analysis algorithm to detect and remove stored ultrasonic a-scan acquisitions whose pattern does not match the pattern exhibited by a majority of similarly stored a-scan acqui-This was done to avoid the averaging together of sitions. inappropriate a-scan envelopes, thereby increasing the reliability of the accept/reject processing. The patterns are matched in time and in amplitude for the envelope classified as body ply when inspecting Textile tires and for the envelopes classified as first and second belts when inspecting Steel Radial tires. Pattern matching in time requires that the peak time of the tested envelope of a stored acquisition fall between the start and end times of the similarly classified envelope in each of the other stored acquisitions. Pattern matching in amplitude requires that the peak amplitude of the tested envelope of a stored acquisition fall between plus and minus a preset percentage of the peak amplitude of the similarly classified envelope in each of the

other stored acquisitions. This preset percentage is stored at address E7E2 in EEPROM, is labeled HOMOL_OFFSET in the flowcharts and listings, and is presently valued at 25%. If the failure to find a majority pattern leaves an insufficient number of stored acquisitions to proceed with an analysis. the TQM informs the inspector how many acquisitions are needed to make up the deficit and if a majority pattern cannot be detected after three attempts to find one, the TQM will proceed with an analysis in a manner similar to the original algorithm.

10. Modify saturation-induced alternate gain calibration procedure so that it is enabled only until the first accept/reject analysis after gain calibration is completed. Thereafter, any saturation detected during inspection is ignored, even through successive gain recalibrations for the same tire type. Only after the tire type is explicity reselected will the saturation-induced gain reduction potential be reenabled. Of course, this continues to pertain only to Steel Radial tires. The philosophy behind this modification is that if a group of tires to be inspected during a given gain calibration interval are of a type that exhibit saturation. this will become obvious upon inspection of the first tire after calibration. Therefore, recalibration to reduce the gain for inspection of the entire group is an appropriate response. If, however, a group of tires to be inspected during a gain calibration interval are of a type that do not exhibit saturation. the inspection of the first tire in the group is not likely to show a saturated signal. Therefore, any later tire exhibiting

saturation during inspection will be treated as not representative of the group and no request to reduce gain will be made.

- 11. Provision has been made for a scheme whereby the TQM can automatically adjust the distance-amplitude correction (DAC) slope of its automatic gain control (AGC) circuit through a special mode of gain calibration. This is accomplished by requiring the monitor to find that DAC slope which minimizes the difference between multiple ultrasonic reflection amplitudes from an air-backed quarter-inch rubber block sensed at 72 degrees F and multiple embedded setpoints. Details of the procedure are explained in the Calibration manual.
- 12. Modification of the TQM power-up tire type default mode from that of Truck Steel to that of GRP Maintenance. This was done to force the inspector to be explicitly aware of what tire type is selected before commencing inspection.
- 13. Addition of a relative accept/reject test which inspects for implied degradation of the second steel belt by comparing its amplitude with that of the liner. This addition was requested by the TACOM representative to provide an accept/reject test felt to be missing from the original test sequence.

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