AFWAL-TR-85-3096 VOLUME I



DESIGN METHODOLOGY AND LIFE ANALYSIS OF POSTBUCKLED METAL AND COMPOSITE PANELS

R. B. DEO

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DECEMBER 1985

Final Report for Period September 1981 - August 1985

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Land Land FLIGHT DYNAMICS LABORATORY Ser. AIR FORCE WRIGHT AERONAUTICAL LABORATORIES AIR FORCE SYSTEMS COMMAND WRIGHT-PATTERSON AIR FORCE BASE, OHIO 45433

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>of the design procedures. The results from Task II showed that the semiempirical strength predictions were conservative for composite panels by approximately 30 percent. In Task III nonempirical analysis methods based on the principle of minimum potential energy were developed to predict the displacement and strain fields in curved metal and composite panels. These predictions were compared against the test data generated in Task II. The predictions showed the same trends as the measured data. However, the numerical values could not be accurately matched. Additional work necessary to enhance the predictive capability was identified. Under Task IV, the semiempirical design methodology was documented in a Preliminary Design Guide for postbuckled metal and composite panels.

The significant conclusions of the program and details pertaining to activities performed under the various tasks are documented in this final report designated as Volume I. The computer programs are documented in Volume II - Software Documentation. The preliminary Define Guide forms Volume III of the documentation for this contract.

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PREFACE

The work documented in this report was performed by Northrop Corporation, Aircraft Division, Hawthorne, California under Contract F33615-81-C-3008 sponsored by the Air Force Wright Aeronautical Laboratories, Flight Dynamics Laboratory, AFWAL/FIBE. The work was performed in the period from September 1981 through August 1985. The Air Force Program Monitors were Capt. M. L. Becker (September 1981 to June 1983), Capt. M. Sobota (June 1983 to February 1985), and Lt. P. Alsup (February 1985 onwards) who reviewed and suggested improvements to the report.

Dr. B. L. Agarwal was the Northrop Program Manager and Principal Investigator until June 1983. From June 1983 onwards Dr. R. B. Deo was the Principal Investigator. The following Northrop personnel also contributed to the performance of the contract in their respective areas of responsibility:

Ε.	Madenci/Dr. N. J. Kudva	Analysis
F.	Uldrich	Specimen Fabrication
М.	Kerbow	Testing
R.	Cordero	Data Analysis/Graphics
ĸ.	H. Gonzalez/B. Tuzzolino	Documentation

The results of the program were used to develop a preliminary design guide for postbuckled structures. The Design Guide (Initial Release) is published separately as Volume III.

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SECTION 1

INTRODUCTION

1.1 BACKGROUND

Several recent studies have demonstrated that the structural efficiency of future USAF aircraft can be improved by taking advantage of the postbuckled strength of stiffened panels. A majority of these studies, performed under the auspices of the USAF, the U.S. Navy and NASA, have provided a sizeable data base on the static and fatigue behavior of postbuckled stiffened panels. The test data from the experimental studies have been used to verify the predominantly empirical design methodology for postbuckled panels and to establish static and fatigue failure characteristics of metal and composite parels. The results of the correlation between the semiempirical design methodology and the experimental data indicate several shortcomings in the analysis capabilities as well as lack of essential test data.

The application of existing postbuckling methodology to the design of advanced composite panels has resulted in unconservative designs due to the presence of additional failure modes, such as delamination in the skin, stiffener/web separation and compression failure of the skin. Such failure modes are not accounted for in the existing methodology. These deficiencies in the analysis and design methodology have to be corrected to realize the full weight savings potential of postbuckled designs.

Aircraft panels operating in the postbuckling range are usually curved. These panels are subjected to shear, compression (or tension), and a combination of compression (or tension) and shear loads. Extensive test data are available for flat metal and composite panels subjected to shear or compression loading. However, the test data for curved shear or compression panels are minimal and insufficient to develop and verify improved analysis methods. These gaps in the available test data need to be filled.

Damage tolerance and durability requirements for the design of U.S. military aircraft call for the economic life of an aircraft to be greater than the design service life when subjected to the design service loads. A fatigue design methodology for metal or composite postbuckled panels is not available and test data are sketchy or incomplete. Additional experimental data must be generated to identify and meet the fatigue requirements of postbuckled designs.

1.2 PROGRAM OBJECTIVES

In view of the above postbuckling technology needs, a combined analytical and experimental program was undertaken to develop a unified design methodology, design validation data and fatigue life data for composite and metal panels operating in the postbuckled regime. The specific objectives of the program were to develop an experimentally validated analysis capability and simple to use, yet accurate, design procedures for curved metal and composite postbuckled panels loaded in compression or shear. Inherent in this program objective was the need to develop techniques to predict the initial buckling load, ultimate failure load and failure mode, and fatigue life of postbuckled panels.

The results of the design methodology development program are documented in this report.

1.3 PROGRAM SUMMARY

The program plan was to first review the available analysis and design techniques for metal and composite panels and establish a design methodology for curved postbuckled panels loaded in compression or shear. This methodology was then used in designing curved panels for a test program to generate design validation and fatigue life data.

All panels were cylindrically curved and had a radius of 45 inches. The composite panels were stiffened with hat section stringers and in the case of the composite shear panels J-section frames were used as circumferential stiffeners. The composite compression panels were not circumferentially stiffened in the test section since they simulated the region between two adjacent bulkheads. The metal panels were stiffened with Z-section stringers

and in the case of shear panels circumferential Z-section frames. Fabrication of the composite panels was accomplished using specially designed tooling with careful attention paid to details at the stringer/frame intersection.

The test plan called for static and fatigue tests on the curved metal and composite panels loaded either in compression or in shear. The static test data were used to verify the semiempirical design methodology, whereas the fatigue test data were u-ilized to determine the fatigue failure modes and obtain load versus life data to formulate fatigue analyses approaches.

Comparison of the static test data with the semiempirical design methodology demonstrated a need to develop a more rigorous analysis procedure for postbuckled panels. In addition, the fatigue analysis method proposed requires that the local skin displacements be known. Therefore, rigorous analysis methods using the principle of minimum potential energy were developed for the compression and the shear panels. The predictions from the rigorous analysis are compared with the test data.

Finally, the semiempirical design methodology for curved composite and metal panels subjected to compression or shear loads in the postbuckled regime was documented in a Preliminary Design Guide.

1.4 REPORT OUTLINE

The program was performed in four tasks. Task I consisted of selecting analysis methods and design procedures for postbuckled metal and composite panels. These methods were selected from the available technology on postbuckled structures design. The selected design methodology and an assessment of the technology available prior to the start of this program are documented in Section 2. Design of postbuckled composite and metal panels, panel fabrication and testing were accomplished in Task II entitled "Experimental Test Program." A description of Task II and the test data obtained are documented in Section 3. Task III consisted of comparing the test results with the predictions based on the design methodology selected in Task I, and of developing the more rigorous strain energy based analyses for the compression and shear panels. Under Task III, a fatigue analysis approach for postbuckled panels was also developed on the basis of the test data generated in

Task II. Development of the compression and shear panel analyses based on the principle of minimum potential energy is detailed in Section 4 along with the proposed fatigue analysis approaches. Correlation of test data with results of the analysis is discussed in Section 5. The Preliminary Design Guide developed in Task IV is published separately as Volume III of the Final Report. The program conclusions and recommendations for future work are summarized in Section 6.

SECTION 2

SELECTION OF ANALYTICAL METHODS

2.1 BACKGROUND

The large deflections associated with postbuckled structures make the elementary theories of structural analysis inapplicable to determining the detailed stress field in such structures, and in general, closed-form or analytical solutions cannot be obtained. In current design practice, semiempirical analysis methods are most widely used in sizing stiffened panels operating in the postbuckled range. The semiempirical analysis methods are attractive for use in actual design situations due to their simplicity, ease of application and the built-in conservatism in the static analysis results. The main drawback of these methods, besides the weight penalty associated with the conservatism in the analysis, is that they do not provide a detailed stress or displacement field in the postbuckled stiffened panels. Determination of the stress field is essential in formulating a viable fatigue analysis approach. A few numerical solutions have been attempted, and although these techniques provide the local displacements and stresses, they are cumbersome to use, and too expensive in terms of computer costs to be considered viable design tools.

The design and analysis approach adopted in this program was to review the available technology base on postbuckled metal and composite panels and then select a semiempirical methodology for modification and subsequent use in the test program. The purpose of the modifications was to extend the applicability of the analysis techniques, developed for metal panels, to composite panels. The semiempirical methodology was used to design the program test panels which in turn provided verification test data. Recognizing the previously mertioned drawbacks in the semiempirical techniques, development of a new non-empirical analysis methodology with the objective of predicting the total postbuckling behavior of compression or shear loaded panels was also undertaken. It was envisioned that the results of this rigorous analysis would find immediate application in formulating approaches to fatigue analysis

of postbuckled stiffened panels.

In this section, an assessment of the current technology related to design, analysis and fatigue life prediction of postbuckled structures is presented and the analytical methods selected for use in the program are detailed. The objectives of this to 'nology assessment were: (a) to enable selection of promising analytical methods for further verification, and for test panel design; and (b) to compile test data that could be used in characterizing the fatigue behavior of postbuckled panels. The technology assessment was also used to select an approach to developing a non-empirical analysis methodology for postbuckled compression and shear panels.

2.2 TECHNOLOGY ASSESSMENT

An exhaustive review of several preliminary design studies and test programs was conducted towards selecting design methods for postbuckled metal and composite panels loaded in compression or shear. The currently available design and analysis methodologies were assessed for simplicity, accuracy and generality. The following paragraphs describe in a summary form the state-of-the-art methodology for design, analysis, and durability validation of postbuckled metal and composite panels.

2.2.1 Semi-Empirical Static Analysis Methods

The semi-empirical analysis methods evolved from an extensive data base for metal panels and their final form is a result of several modifications. The numerous sources of postbuckled panel test data surveyed and their contributions to the development of the semi-empirical analysis techniques are summarized in Table 2.1. A detailed discussion of the significant contributions is presented in the following paragraphs.

<u>Shear Panels</u> - The semi-empirical analysis and design method currently used for stringer stiffened panels loaded in shear or a combination of shear and compression loading has evolved over the years from the "tension field theory." This theory was originally conceived by Wagner (Reference 1) for thin flat metallic shear webs. Based on the results of several hundred tests, some empirical constants were introduced in this theory to broaden its applicability by Kuhn (Reference 2). The theory was extended to the analysis

TABLE 2.1. SUMMARY OF EXPERIMENTAL DATA FOR POSTBUCKLED PANELS (SHEET 1 OF 4)

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REMARKS	LARGE NUMBER OF PANEL TESTS WITH VARIOUS GEO- METRIES FORM A SOLID BASE FOR ANAL YSIS OEVELOPMENT	FOURTEEN BEAM TESTS WITH DIFFERENT WEB THICKNESSES FORM A USEFUL BODY OF EXPERIMENTAL DATA	TESTS ON TWO DIFFERENT MATERIAL SYSTEMS POINTED OUT SHORTCOMINGS OF TEN- JON FIELD THEORY	A TGTAL OF 12 CV.IMDERS WITH DIFT JENT WEB THICK- NESSES AND STIFFENER THICK- NESSES WE RE EXAMINED	TEST DATA DEMONSTRATED FAIRTUE PROBLEMS DF METAL PRNELS	A TOTAL OF 5 TESTS EXAMINED THE 2FFECT OF VANYANG THE NATIO OF AXIAL COMPRESSION AND SNEAR LOADING ON PANEL BEHAVIOR	TESTS DEMONSTRAFED POST BUCKLING STRENGTH OF COM- POSITE PANELS	SEVENAL DIFFERENT LAMIN- ATE CONFIGURATIONS AND THICKNESSES EXAMINED	SEVERAL DIFFERENT LAMIN- ATE CONFIGURATIONS AND MAYERIAL SYSTEMS EXAMINED	SEVERAL DIFFERENT LAMIN ATE CONFIGURATIONS AND ASPECT RATIOS EXAMINED	DATA PRIOR TO FAILURE MAY BE USEFUL	
MERIT FOR AMALYSIS DEVELOP- MENT (1)	m	m	m	m	n	m	-	~	~	~	-	
TEST FIXTURE	CANTILEVER AND SIMPLE SUPPORTED BEAM	ECCENTRI- Cally Loaded Cantilever Beam	ECCENTRI- Cally Loadeo Cantilever Beam	COMPLETE CVLINDER UNDER UNDER TORSION	TRIANGULAR BOX UNDEP TORSION	COMPLETE CYLINDER UNDER UNDER TENSION AND COMPRESSION	PICTURE FRAME	PICTURE FRAME	PICTURE FRAME	PICTURE FRAME	PICTURE FRAME	
TEST CONDI- TION	STATIC	STATIC AND FATIGUE	STATIC	STATIC	STATIC AND FATIGUE	STATIC	STATIC AND FATIGUE	STATIC	STATIC AND FATIGUE	STATIC AND FATIGUE	STATIC AND FATIGUE	
TEST Envi- Roment	RTO (2)	810	A TO	RTO	RTD	810	RTD	AT0	R T0	RT0	RTO	
STIFFENER/ WEB ATTACHMENT METHOD	RIVETED	RIVETED	RIVETED	RIVETED	RIVETED	RIVETED	ı	ŝ	ı	1	i	
STIFFENER GEOMETRY	ANGLE AND Z-SECTION	Z-SECTION	ANGLE, J. AND Z-SECTION	Z-SECTION	Z-SECTION	Z-SECTION	I	ł	I	1	ı	
CONDITION	SHEAR	SHEAR	SHEAR	SHEAR	SHEAR COMPRESSION	COMBINED COMPRESSION AND SHEAR	SHEAR	SHEAR	SHEAR	SHEAR	SHEAR), 3-EXCELLENT
PANEL GEOMETRY	FLAT	FLAT	FLAT	CURVED	CURVED	CURVED	FLAT	FLAT	FLAT	FLAT	FLAT	1-FAIR 2 GOD
MATERIAL	ALUMINUM	ALUMINUM	ALUMINUM AND TITANIUM	MUMIMULA	ALUMINUM	ALUMINUM	80RUN. EPOXV	GRAPHITE- EPOXY	GRAPHITE- EPOXY	GRAPHITE. EPOXY	GRAPHITE- EPOXY AND KEVLAR FPOXY	IT OF TEST DATA
REFERENCE	KUHN (2)	TSONGAS (3)	BAREVICS (4)	KUHN (2)	CURRENT PROGRAM	PETERSON (5)	KAMINSKI (6)	FANT (7)	(#) WHI	BHATIA (7)	FOREMAN (10)	NOTES (1) MER

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TABLE 2.1. SUMMARY OF EXPERIMENTAL DATA FOR POSTBUCKLED PANELS (SHEET 2 OF 4)

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AERIT FOR ALYSIS VLOP- REMARKS	3 STRENGTH DATA BELIEVED TO BE MORE RELIABLE THAN PICTUHE FRAME TEST DATA	2 SEVERAL DIFFERENT PANEL WEB CONFIGURATIONS EXAMINED	1 SINGLE PANEL TEST TU ESTANLISH POSTBUCK2.MG STREAGTH	3 VARIATIONS IK STIFFINER SPACING AND SHAPE PROVIDE VALUABLE EXPERIMENTAL DATA	3 REPLICATED TESTS PROVIDE STATISTICALLY RELIABLE DATA	2 PANEL FAILURE AFFECTED BY STRESS CONCENTRATION IN THE DIAGONAL CORNERS	2 TEST DATA MAY HAVE BEEN AFFECTED BY TEST FL/TURE DESIGN	2 UNREPLICATED UMINSTRU- MENTED TESTS TO ESTABLISH THE EFFECT OF DIFFERENT DESIGN VARIABLES	3 SIX UNREPLICATED TESTS TO ESTABLISH THE EFEET OF FATIGUE LOADING AND ENVIRONMENTAL EXPOSURE	TEST DATA AFFECTED BY POOR PANEL QUALITY	W – ROOM TEMPERATURE WET
L AN LEST AN L	ECCENTRI- CALLY LOADED CANTILEVER BEAM	PICTURE FRAME	PICTURE FRAME	ECCENTRI- CALLY LOADED CANTILEVER BEAM	ECCENTRI- Cally Loaded Cantilever Beam	PICTURE FRAME	MODI-IED PICTURE FRAME	PICTURE FRAME	ECCENTRI- Cally Loaded Cantilever Bean	CANTILEVER GEAM	(5)
TEST CONDI- TION	STATIC AND FATIGUE	STATIC	FATIGUE	STATIC AND FATIGUE	STATIC AND FATIGUE	STATIC AND FATIGUE	STATIC AND FATIGUE	STATIC AND FATIGUE	STATIC AND FATIGUE	STATIC AND FATIGUE	RE DRY
TEST Envi- Ronment	RTO (2)	RT0	ATD	RTD	6TD	RTD	ATD	RTD ETD (3) ETW (4)	RTD RTW (5) ETW	RTD (2)	D TEMPERATUR
STIFFENER/ Stiffener/ Mes Method	ł	BONDED	COCURED	COCURED	COCURED	COCURED	COCURED	COCURED AND STITCHED	COCURED	сасияер) ETO - ELEVATEC
STIFFEMER GEOMETRY	1	HAT AND ANGLE	нат	HAT AND I-SECTION	НАТ	J-SECTION	HAT	НАТ	HAT AND BEAD	HONEYCOMB FILLED HAT	
LUAD CONDITION	SHEAR	SHEAR	SHEAR	SHEAR	SHEAR	SHEAR	SHEAR	SHEAR	SHEAR	SHEAR	3-EXCELLENT
PANEL CEOMETRY	FLAT	FLAT	FLAT	FLAT	FLAT	FLAT	FLAT	FLAT	FLAT	FLAT	I FAIH, 2-G000.
MATERIAL	GRAPHITE GRAPHITE EPOXY AND KEVLAR EPOXY	GRAPHITE EPOXY AND BORDN- EPOXY	GRAPHITE- EPOXY	GRAPHITE- EPOXY	GRAPHITE. EPOXY	GRAPHITE- EPOXY	GRAPHITE- ЕРОХҮ	GRAPHITE. EPOXY	GRAPHITE- EPOXY	KEVLAR- WEBAND GRAPHITE STIFFENEHS	T OF TEST DATA
REFERENCE	RICH (11)	I AKT (7)	LEHMAN (12)	AGARWAL (13)	AGARWAL (14)	0CTROM (15)	RENIERI (16)	DASTIN (17)	SURDENAS (18)	FOREMAN (19)	NOTES (1) MERI

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TABLE 2.1. SUMMARY OF EXPERIMENTAL DATA FOR POSTBUCKLED PANELS (SHEET 3 OF 4)

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REFERENCE	MATERIAL	PAREL GEOMETRY	LONDITION	STIFFENER GEOMETRY	STIFFENER/ WEB ATTACHMENT METHOD	TEST Envi- Ronment	TEST CONDI- TION	TEST FIXTURE	MERIT FOR ANALYSIS DEVELOP- MENT (1)	REMARKS
AGARWAL (20)	GRAPHITE - EPOXY	FLAT	SHEAR	НАТ	COCURED	RTO	FATIGUE	ECCENTRI- CALLY I OADED CANTILEVER BEAM	ñ	TESTS DEMONSTRATED COMCEPTS FOR INPROVING STIFFENERWEB INTERFACE STRENGTH
BHATIA (21)	GRAPHIJE - EPOXY	FLAT	COMBINED SHEAR, COMPRESSION AND BENDING	HAT	COCURED	RTD 0	STATIC AND FATIGUE	ECCENTRI- CALLY LOADEO CANTILEVER BEAM	m	OMLY TEST DATA CUARENTLY AVAILABLE FOR COMPOSITE PANELS SUBJECTED TO COM BINED LOAD
GRIMES (22)	GRAZHITE- POLVIMIDE	FLAT	SHEAR	HAT	COCURED	RT0 9TW (3) ETW (4)	STATIC AND FATIGUE	ECCUNTRI- Cally Loaded Cantilever Beam	m	SEVERA', PANELS ARE TO BE TESTED TO EVALUATE THE NEW MATERIAL SYSTEM
AGARWAL (23)	GRAPHITE- EPOXY	FLAT	SHEAR	HAT	COCURED	810	STATIC AND FATIGUE	ECCENTRI- CALLY LOADED CANTILEVER BEAM	m	A PROGRAM CURRENTLY UNDER WAY AT NORTHROP DAMELS TO BE SUBJECTED TO PAMELS TO BE SUBJECTED TO SPECTRUM FATIGUE LODDING. REPLICATED TESTSHILL PRO- VIDE RELIABLE DATA
GARRETT (24)	GRAPHITE- EPOXY	FLAT	SHEAR	НАТ	DIFFERENT IMPROVEMENT CONCEPT TO BE EXAMINED	RTD	STATIC AND FATIGUE	MODIFIED PICTURE FRAME	n	SEVERAL DIFFERENT STIFFENER/NE8 INTERFACF IMPROVEMENT CONCEPTS TO BE EXAS:ifED
E'JES (25)	GRAPHITE- EPOXY	FLAT	COMBINED SHEAR AND COMPRESSION	НАТ	COCURED	RTD	STATIC ARD FATIGUE	BUX BEAM	m	EXPERIMENTAL DATA TO BE GENERATED FOR PANELS SUB- LECTED TO COMBINED LOADING. REPLICATED TESTS TO PROVIDE RELIABLE DATA
STARNES (36)	GRAPHITE- EPOXY	FLAT	COMPRESSION	I-SECTION	COCURED	AT0	STATIC	FLAT END TFSTING	ę.	VARIOUS DFSIGN CONFIGURA- TIONS PROVIDE USEFUL TEST DATA
GARRETT (27)	GRAPHITE- EPOXY	FLAT	COMBINED COMPRESSION AND SHEAR	НАТ	COCURED	RTO ETW	STATIC AND FATIGUE	TRIANGULAR POX	m	REPLICATED TESTS PROVIDE USEFUL DATA BASE
FANT (7)	GRAPHITE- EPOXY AND BORON-EPOXV	CURVED	SHEAR	1	1	810	STATIC	COMPLETE CVLINDER IN TORSION	2	ONE GRAPHITE AND ONE BORON PANEL TERTE TO DEMONSTRATE THE POST- BUCKLING STRENGTH OF CURVED PANELS
NOTES (1) MEI	RIT OF TEST DATA) - ROOM TEMPERA	1-FAIR, 2-6000 TURE DRY). 3-EXCELLENT	22	1) RTW - 900M TEN 1) ETW - ELEVATED	APERATURE W	'ET RE WET			

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TABLE 2.1. SUMMARY

REMARKS	VERY THIN KEVLAR-EPOXY PANELS DEMONSTRATED POST- BUCKLING STRENGTH	POSTBUCKLING STRENGTH UNDER COMPRESSION LOAD- ING DEMONSTRATEO	REPLICATED TESTS DEMON- STRATED THE USE: OLNESS OF CURRENT DESIGN METHODS AND PROVIDED EXTEMSIVE STRAIN DATA	REPLICATED TESTS PROVIDED USEFUL EXPERIMENTAL DATA	REPLICATED TE STS PROVIDE USEFUL EXPERI MENTAL DATA	REPLICATED T°STS PROVIDE Useful Eaperimental Data	
MERIT FOR ANALYSIS DEVELOP- MENT (1)	2	7	m	m	m	m	
TEST FIXTURE	COMPLETE CVLINDER IN TORSION	FLAT END TESTING	FLAT END TESTING	FLAT END TESTING	FLAT END TESTING AND TRIANGULAR BOX	TRIANGULAR BOX	
TEST CONDI- TION	STATIC	STATIC AND FATIGUE	STATIC AND FATIGUE	STATIC AND FATIGUE	STATIC AND FATIGUE	STATIC AND FATIGUE	
TEST ENVI- RONMEN ¹	RTD (2)	ATD	810	91 6	0 U	RTD ETW	
STIFFEWER/ STIFFEWER/ ATTACHMEWT METHOD	i	COCURED	COCURED	COCURED	COCURED	COCURED	
STIFFENER GEOMETRY	I	НАТ	НАТ	НАТ	НАТ	НАТ	
LOAD CONDITION	SHEAR	COMPRESSION	COMPRESSION	COMPRESSION	COMPRESSION AND SHEAR	COMBINED COMPRESSION AND SHEAR	D. 3-EXCELLENT
PANEL GEOMETRY	CURVED	CURVED	CURVED AND FLAT	CURVED	CURVED R = 45 IN	CURVED R = 42 IN R = 23 IN	1-FAIR, 2-GOO TURE DRY
MATERIAL	KEVLAR- EPOXY	GRAFAITE- EPOXY	GRAPHITE- EPOXY	GRAPHITE- EPOXV	GRAPHITE- GPOXY ANJ ALUMINUM	GRAPHITE EPOXY	IT OF TEST DATA ROOM TEMPERA
REFERENCE	H0 (28)	AGARWAL (29)	AGARWAL (30)	HINKLE (31)	CURRENT PROGRAM	GARRETT (32)	NOTES (1) MERI (2) ATO

of curved panels as well. The empirical constants were chosen such that the theory yields conservative results over the entire range of its applicability.

The tests conducted by Kuhn (Reference 2) at NACA generated elaborate experimental data which were used to formulate the theory, while tests conducted throughout the industry verified the strength predictions. The flat beams tested by NACA may be divided into three groups: small but heavily loaded beams (12 inches deep); medium-sized beam (25 or 40 inches deep), which formed the largest group; and large beams (75 inches deep).

Small but heavily loaded beams were tested using a simply supported beam loaded at the beam center. The lateral movement of the compression chords was restricted to prevent lateral buckling. The medium sized and large beams were tested as eccentrically loaded cantilever beams. Uprights or stiffeners on these panels consisted of single or double angles or Z-sections. A number of variations in upright and web geometry were tested. The experimental data generated from these tests are well documented in Reference 2 and are quite useful for a design methodology development over a large spectrum of panel configurations.

In the late 1960's, the results of 14 full-scale shear beams were reported in Reference 3. The beams had thin, chem-milled aluminum webs with lands to which lipped and unlipped Z-stiffeners and T-flanges of the same material were riveted. The web and stiffener thicknesses were varied to verify the tension field theory. The panels were tested at Room Temperature Dry (RTD) conditions through the use of an eccentrically loaded cantilever beam. The load was incremented in small steps. Between increments the load was dropped to zero to observe permanent buckling in the web. Based upon the results of static tests some modifications to the tension field theory were recommended.

As part of an SST technology program a number of aluminum and titanium shear panel tests were conducted as discussed in Reference 4. Results of 18 aluminum and titanium shear panel tests were reported. Panels were tested through the use of eccentrically loaded cantilever beams. The

test panels consisted of angle, J- and Z-section stiffeners which were riveted to the panel web. The aluminum and titanium panels had identical configurations to evaluate the usefulness of tension field theory to accommodate different material systems. The tests conducted on aluminum and titanium panels under this program pointed out deficiencies of tension field theory and provided very useful data for future analysis development.

Almost all of the information available on curved web systems in diagonal tension has been obtained on circular cylinders tested in torsion. Because cylinders are more expensive to manufacture and test than plane web beams, the lotal number of cylinder tests is rather small. The tension field theory for curved panels has thus seen a limited verification. A total of 12 tests were reported in Reference 2. In these tests an unconventional arrangement of double stringers was used to eliminate bending stresses in the stringer. The rings were made relatively large to preclude ring failure. All the cylinders tested were 15 inches in radius, a dimension which is not quite representative of real aircraft panel configuration. However, variety of ring spacings and web thicknesses were tested. All cylinders were tested statically under RTD conditions. The results of these cylinder tests are well documented in Reference 2 and have been used to modify the tension field theory for application to curved web systems.

The only results available for metal panels subjected to combined loading are reported in Reference 5. Five cylinders were tested under combined compression and shear loading. All cylinders were identical in construction and geometry. The cylinders were 15 inches in radius and contained 2-section stringers and rings which were bolted to the cylinder web. The ratio of torsional and compression load was varied for each cylinder. All the cylinders were cested statically under RTD conditions. The results of these tests are uniquely suited to verification of analyses for metal curved panels under combined loading.

Data from the tests described in the preceding paragraphs (References 2 through 5) were used to examine the validity of the tension field theory. The results showed that the internal loads predicted by the tension field theory were conservative by as much as 50 percent for aluminum beams and by as much as 90 percent for the titanium beams. In some

cases, failure load predictions based on local crippling of stiffeners were found to be unconservative. The primary reason for this unconservatism in predicting stiffener failure was the inability of tension field theory to accurately compute stresses in the eccentric stiffeners, especially for panel loads several times the initial skin buckling load.

The introduction of advanced composite materials as viable candidates in airframe usage has stimulated a large number of studies in recent years to determine their postbuckling behavior. One of the earliest demonstrations of the postbuckling strength of composite materials was presented in Reference 6. Several boron/epoxy unstiffened shear panels were tested statically and under fatigue loading at load magnitudes several times their initial buckling load. In similar studies in References 7, 8 and 10 the postbuckling strength of graphite/epoxy and Kevlar/epoxy materials was demonstrated. The test data for composite flat shear panels were obtained in these studies through the use of picture frame test setups. This test setup results in the introduction of severe stress concentrations in the diagonal corners, which influence the panel failure load as well as the mode of failure. Thus, the test data generated in the above studies are of limited use for the purpose of failure analysis development and strength verification. However, the test data are useful in determining the panel response before failure. Some of the unstiffened composite shear panel data were obtained from tests in an eccentrically loaded cantilever beam setup. Although the strain data generated in these tests are not extensive, the data are more reliable and suited to failure analysis verification.

Several composite stiffened flat panels have been tested under shear loading over the past decade through the use of various test methods. In Reference 7, several panels containing bonded hat and angle section stiffeners were examined. The panel web thickness was varied to study its effect on postbuckling behavior. The panels were tested in a picture frame. Although severe stress concentrations affected most of the panel failure modes, some panels failed away from the region of stress concentrations. An examination of these results indicates that variations in panel thickness are most influential in determining the magnitude of postbuckling deformations which a panel can sustain. Panels containing thin webs can sustain loads much higher than their initial buckling load without failure, as compared to

panels containing thicker webs. For example, a panel containing a 4-ply web failed at a load of 10 times its initial buckling load, whereas a similar panel containing an 8-ply web failed at a load 5 times its initial buckling load. The failures in most cases were due to stiffener/web separation. The stiffener shape, as would be expected in practical structural designs, does not seem to affect the failure load or mode of failure in any significant way.

In Reference 13, the influence of various design parameters on the behavior of composite tension field panels was investigated. The stiffener spacing was varied to change the onset of initial buckling load. The stiffener shape was varied to study the differences between the behavior of a panel containing a closed section ("hat") and an open section ("I") stiffener. The graphite-epoxy stiffened panels in this study were designed using the metal panel tension field theory with modifications that account for the directional dependence of the composite web moduli. The panels were tested under static and constant -- amplitude fatigue loading. The test results were used to verify the design methodology. Two failure modes somewhat different from metal panel failure modes were discovered. One mode of failure, stiffener/web separation, was due to separation of stiffeners from the panel web. The second mode, compression failure, was due to deep buckles resulting in large compressive stresses in the web corners. The test fixture used in this study was an eccentrically loaded cantilever beam which in Reference 2 has been demonstrated to apply a uniform shear to the panel. The stiffener shape (Hat or I-section) did not seem to affect panel postbuckling behavior. Additional static tests on similar panels were performed in Reference 14. Heavily instrumented and carefully replicated tests established the static behavior of the panels. In a similar manner, the fatigue behavior of identical panels was studied for panels subjected to fully reversed fatigue loading. The panels consisted of cocured hat stiffeners. The panel failure was due to stiffener/web separation. These test data proved valuable for analysis verification and modifications.

In Reference 15, J-stiffened composite shear webs were examined. The test specimen contained three integrally cocured J-stiffeners. The panels were tested statically as well as under constant-amplitude fatigue loading (with no load reversal). The test setup used for testing these panels was

a "picture frame." The statically tested panels failed prematurely due to separation of the stiffeners from the panel skin in the diagonal corners of the test fixture. The results of these tests may be useful in predicting the lower bound of panel strength.

In Reference 16, the test specimens contained two hat stiffeners (simulating a fuselage panel), and two blade stiffeners (simulating the fuselage frames or bulkheads). The panels were tested through the use of a modified picture frame in which the load is applied along one edge, as opposed to along the panel diagonal in a conventional picture frame test setup. The panels tested statically under this program failed due to separation of the blade stiffeners from the skin. The hat stiffeners were unaffected. From phenomenological considerations it would seem logical for stiffener/web separation to occur between hat stiffeners and the panel skin where maximum peel and interlaminar shear stresses are introduced due to the buckles. The relative magnitude of peel and interlaminar stresses should be small near the blade stiffeners. Thus, the blade stiffener/skin separation mode of failure was not anticipated.

In a recently completed Advanced Composite Center Fuselage Program (References 17 and 18), a few graphite/epoxy stiffened and unstiffened shear panels were tested. The tests were conducted on panels subjected to different environmental conditions as well as on panels containing impact damage. None of the test conditions was replicated. Because the panels were tested as part of a design verification program, no attempt was made to obtain extensive strain distributions or to replicate test conditions. Although the test results have limited value in analysis verification, they do provide valuable design data. Evaluation of a variety of design concepts and stiffener/web interface improvements to increase the strength of postbuckled composite panels was conducted in References 19 through 25.

In Reference 19, a Kevlar panel with embedded graphite plies in the stiffener flanges was examined for postbuckling strength. However, uncertainty in the panel quality casts some doubt on the reliability of the test results.

The shear panels tested in Reference 20 incorporated a design improvement at the stiffener/web interface. The improvement consisted of

applying a single layer of FM-300 film adhesive between the interface before the panel was cured. Another panel was fabricated with an extra layer of 3501-6 resin at the interface. Both panels when tested showed significant improvement in the stiffener/web interface strengths.

The postbuckling behavior of flat stiffened multibay composite panels was examined in Reference 21. The panels were subjected to a combination of inplane shear, compression, and bending loads. Because test results for panels under combined load are rare in the literature, the results of this study are valuable for preliminary analysis verification. The panels tested under this program consisted of a 10-ply graphite/epoxy web with cocured hat section stringers and bead section frames. The panels were designed to buckle at 30 percent of the design limit load. Extensive instrumentation was provided to measure the stress distribution as well as the postbuckling behavior. A significant loss in the panel initial buckling load was reported due to fatigue loading.

The postbuckling behavior of graphite/epoxy polyimide panels was examined under a Navy contract (Reference 22). The panels in this program were identical to the panels tested earlier in Reference 14 except for the materials. The results of this program showed that the strength of polyimide materials under out-of-plane loads was rather poor. This poor strength was manifested as skin/stiffener separation which was a severe problem in these panels.

As part of the Wing/Fuselage program (Reference 25), several composite stiffened flat panels were designed, fabricated and tested. These panels consisted of two cocured hat stiffeners. The overall panel dimensions were 22 by 26 inches. A total of 12 panels were tested to determine the postbuckling behavior under combined compression and shear loading. Replicated tests were used to examine the static as well as fatigue behavior under RTD conditions as well as under Elevated Temperature Wet (ETW) conditions. A flight by flight spectrum loading typical of a Mach 2 fighter aircraft was used to study durability of these panels for two lifetimes of fatigue loading. The results of this study are potentially useful in developing a design methodology for postbuckled panels subjected to combined loading.

Another design improvement for the stiffener/web interface was examined in Reference 24. The results of this study show that tailoring the skin/stiffener interface results in improved fatigue life. The tailoring consisted of tapering the flanges of the stiffeners at the interface with the skin. This tapering was accomplished by selectively dropping off the flange plies. The influence of environment and combined loads on flat composite stiffened panels is examined in Reference 27. This study is currently in progress and will provide much needed data for analysis development and verification.

The analysis methodology for curved composite panels under shear loading is still in its infancy. This is primarily due to a lack of reliable, detailed test data. The postbuckling strength of curved composite shear panels was demonstrated in Reference 7 where a graphite/epoxy and a boron/ epoxy panel were tested through the use of a cylinder torque test. These data in conjunction with data from Reference 27 and those being generated in Reference 32 will prove valuable in verifying the applicability of the modified tension field theory to curved composite shear panels.

<u>Compression Panels</u> - The semiempirical postbuckling analysis of flat and curved stiffened panels loaded in compression is generally done in steps because it involves several complexities which are difficult to account for simultaneously. The method normally used to analyze metal panels is in four parts:

- 1. Determine the panel initial buckling load.
- 2. Determine the compressive strength of the stiffener alone.
- 3. Determine the effective width of the skin for a load equal to the compressive strength of the stiffener alone.
- 4. Determine the total load carried by the panel by taking into account the load on the stiffener plus the effective width of the skin, plus the critical buckling load of the skin.

The above method requires calculation of the panel buckling load, the behavior of the skin after buckling and the failure strength of a column of any arbitrary shape. For design purposes, the above process is generally repeated several times to obtain positive margins on all structural elements.

Analytical and semiempirical methods for predicting the initial buckling load of the skin are well developed for metal and composite panels and are extensively documented in References 34 through 39, for example. These methods vary widely in rigor and accuracy. The analysis methods developed for metals up to the early 1950's and documented in References 34 and 35, are semiempirical in nature and are based on the results of an extensive test data base.

Several more rigorous analytical methods were made possible by the evolution of high-speed digital computers. Some of the most recent and advanced analysis methods for linear bifurcation buckling analysis are described in References 40, 41 and 42 (Computer codes SX8, BUCLASP2, and VIPASA). Computer code SX8 is based upon the Rayleigh-Ritz energy principle for analysis of flat composite and metal stiffened panels. The stiffeners are assumed to be axial members and their effect on panel behavior is included by taking into consideration the bending and torsional stiffnesses of the discrete stiffeners in the energy expression for the panel. In doing so, the effects of stiffener shape are neglected. The main advantage of this method is that arbitrary boundary conditions along the panel edges can be analyzed.

The computer codes BUCLASP-2 and VIPASA (References 41 and 42) are quite similar to each other except in their ability to solve cases with different loading and boundary conditions. These methods are based on solving exact force-displacement relations for a plate-strip element with the assumption of simple support boundary conditions along the edges normal to the longitudinal direction and arbitrary boundary conditions along the longitudinal edges. An assembly method, similar to the one used in finite element analysis, is used to generate any desired panel configuration. The advantage of this method of analysis is that both general and local instability modes can be simultaneously predicted. Additionally, any combination of

local and general instability modes, which results in lower buckling loads, can also be predicted. This method of analysis was used very successfully to correlate experimental data for hat-stiffened and J-stiffened graphiteepoxy compression panels in References 43 and 44.

The analytical methods for determining the onset of buckling for curved-stiffened panels are limited in number and have developed along lines similar to the corresponding methods for flat panels. The methods described in References 41, 42 and 45 (Computer codes BUCLASP-2, VIPASA, and SS8) have been used more recently throughout the aircraft industry for metal and composite panels. These methods can also be used for flat-stiffened panels.

In order to predict stiffened panel behavior after initial buckling and the ultimate compressive strength of stiffeners, semiempirical techniques have to be utilized. The semiempirical methodology for predicting local buckling and crippling strength of metal stiffeners has been derived from a large data base and is documented in References 34 and 39 for various stiffener configurations. Test data on the crippling strength of composite stiffeners are sparse and as a result no definitive analysis techniques exist. One approach suggested in Reference 46 is based on tests performed on several composite stiffener elements. These tests included plates with both sides simply supported as well as plates with one edge free and the other edge simply supported. In Reference 46, the following empirical equation was suggested for use in predicting the crippling strength of composite plates:

$$F_{cc}/F_{cr} = \alpha (F_{cu}/F_{cr})^{\beta}$$

In the above equation, F_{cc} is the crippling stress, F_{cr} is the theoretical initial buckling stress, and F_{cu} is the plate compressive strength. The values of α and β are material dependent constants. The values of these constants for AS/3501-6 and T300/5208 graphite/epoxy systems were obtained in Reference 46 by fitting a curve to the test data. Validity of the empirical equation in predicting the crippling strength of built-up sections was demonstrated in Reference 46 by tests on square composite tubes.

Generally, metal compression panels sized using the above approach are conservatively designed. In recent studies (References 29 and 30), composite compression panels were designed using the above approach. The panels consisted of cocured hat-stiffeners and were designed to buckle at loads significantly below the panel ultimate strength. The methods used for determining initial buckling load and stiffener crippling strength were those mentioned above. The replicated tests indicated that the analysis methods were sufficiently accurate, although on the conservative side. However, additional verification of the semiempirical methodology for composite panels was necessary and, therefore, carried out in this program. Test data obtained in References 26, 29 through 31, 47 and 48 were used for verification. This process of correlating the data base with the semiempirical predictions, resulted in some modifications to the crippling strength prediction equation given above. These results and modifications are discussed in Section 2.3.

2.2.2 Non-empirical Static Analysis Methods

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Analysis of stringer stiffened panels loaded beyond skin buckling requires solution of nonlinear equations and no closed-form expressions describing the response can be obtained. Thus, numerical methods must be resorted to. The numerical methods of solution are generally iterative in nature, and their efficiency and utility are limited by the number of unknown variables in the solution process. Two of the most commonly used nonempirical solution methods for postbuckling analysis are Finite-Difference/Finite Element Methods (FD/FEM) and Rayleigh-Ritz type methods. Several applications of these techniques to postbuckled structures are discussed in the following paragraphs.

<u>Finite Difference/Finite Element Methods</u> - The main advantage of using FD/FEM is that several large computer codes exist (e.g., NASTRAN, STAGS, ANSYS) and are easy to access in the aerospace industry. However, a few basic problems in using these techniques make them undesirable for design purposes. The problems are related to questions of accuracy, efficiency, and convergence.

The accuracy of the finite element solution method depends upon the type and number of finite elements used to model structural behavior. Since the structural behavior is not known in advance, a general practice is to start with a reasonably fine mesh size and refine it subsequently to establish the accuracy of the solution. Thus, the solution process can be expensive if several such iterations are needed. The analytical solutions of problems involving large deflections are iterative in nature by themselves and this added iteration can make the solution economically unfeasible.

The efficiency of the finite element solution depends upon the nature of the problem and also upon the mesh size used to model structural response. For example, in order to model the stiffener/web separation, three-dimensional finite elements must be used in the interface area. Since the thickness of the interface is quite small, a large number of elements will be required in this region to avoid numerical difficulties as well as to model the behavior accurately. Recent experience at Northrop and results in the literature indicate that the interface stresses are sensitive to element size in structures involving small displacements. It can be anticipated that similar or even worse difficulties will be encountered in panels subjected to postbuckling deformations. Again due to the iterative nature of the solution process, a large number of elements can make the solution economically unfeasible.

The governing nonlinear equations for postbuckled structures are solved incrementally. A general practice is to increase the applied load or displacement in small increments with the size of these increments determining the progress of the solution towards the maximum applied load. Since the increment size is not known in advance, several trials are generally needed to obtain a convergent solution. Convergence difficulties are also encountered due to the size of the mesh used in making a geometric representation of the problem. Several such convergence difficulties have been reported in References 49 through 57 and are discussed below. Another simplifying assumption made in the application of FD/FEM to postbuckled structures is to model the skin separately without regard to the interaction effects of the skin and the stringers. Similar drawbacks also apply to finite difference solution methods.

Due to the difficulties encountered in the use of FD/FEM methods, most of the studies reported in the literature on postbuckled structures have been conducted making several simplifying assumptions. One of the most common assumptions made is to model the skin of the skin-stringer panel separately, without regard to the interacting effect of skin and stringers.

Sharifi (Reference 49) modeled the behavior of an unstiffened shear panel subjected to postbuckling loads, using finite elements, and showed that the postbuckling deflections could be predicted quite accurately. In a similar study by Bhatia (Reference 9) the STAGS program was used to predict the postbuckling behavior of composite shear webs. In these studies no attempt to predict failure was made. Turney and Wittrick (Reference 50) and Rushton (Reference 51) used a finite difference lterative method known as "dynamic relaxation" for the postbuckling analysis of square plates subjected to uniaxial compression and shear. Rectangular finite elements with bi-cubic Hermitian interpolation functions were used in Reference 52 to study the postbuckling behavior of uniaxially compressed sandwich panels.

Postbuckling behavior of stiffened shear webs was also studied by Stein and Starnes (Reference 53) through the use of the STAGS computer code. They conducted parametric comparisons on the efficiencies of metal and composite shear webs loaded up to about twice the buckling load. Several convergence difficulties were pointed out. This study demonstrated the usefulness of STAGS in performing postbuckling stress analysis, but failed to establish the accuracy of the solution process.

Vestergren and Knutsson (Reference 54) also used STAGS to study the postbuckling behavior of unstiffened compression and shear panels. The initial buckling loads were predicted quite accurately for compression as well as shear panels using the bifurcation analysis. However, the failure load predicted for compression panels was twice the experimentally obtained value. No data were presented for the failure load predictions of shear panels. Again, several difficulties in the use of computer code STAGS for analysis purposes were acknowledged.
The change in stiffness of a plate loaded under combined loading was discussed by Rothwell and Allahyari (Reference 55). The finite element analysis used in this reference provided guidelines for minimizing the loss of the beam flexural stiffness as a result of web buckling.

The postbuckling behavior of a composite panel shear web (excluding the stiffeners) was modeled in Reference 13 using the computer code NASTRAN. In this study, the web was assumed to be simply supported on all four edges. The analytically obtained displacements and strains in the postbuckling regime were shown to compare favorably with experimental values. Web rupture due to compressive stresses resulting from deep buckles was shown to be predictable. The analytical results in this study indicated a concentration of out-of-plane constraint forces in the diagonal corners where failure due to stiffener/web separation was observed. Since the stiffener/web interface was not modeled in the NASTRAN analysis, no accurate prediction of failure due to stiffener/web separation was made. Further attempts to enlarge the model to include the total panel behavior had to be aborted due to convergence difficulties. A NASTRAN finite element analysis of postbuckled shear panels was also attempted in Reference 16. The initial buckling load was shown to agree quite well with the experimental data. However, the analysis attempt was again aborted above 150 percent of the initial buckling load due to convergence difficulties.

In Reference 29, the postbuckling behavior of a composite stiffened compression panel was modeled through the use of the large deflection theory of NASTRAN. A convergence difficulty resulting from using a relatively coarse mesh size was encountered after the load exceeded twice the initial buckling load, and the solution attempt was aborced. However, a fairly good correlation with experimental data was observed for the results obtained.

Several recent attempts have been made at improving the efficiency and reducing the convergence difficulties of finite difference/finite element methods (References 56 and 57), but their implementation as a design tool in the near future is unlikely.

Rayleigh-Ritz Type Methods - These methods are widely used to model the behavior of complex structures, since they are conceptually simple

to use. The displacement field is approximated by assumed functions with unknown coefficients. The number of equations to be solved is reduced sigsilicantly when compared to the finite element methods, thus, reducing the computation time and cost. Furthermore, once the problem is formulated, parametric studies can be conducted with little additional cost. However, there are some difficulties in using this approach also. The main difficulty arises from selecting the deformed structural shape. This is usually resolved by selecting a shape which is a combination of several possible shapes. The experimentally observed behavior greatly enhances this selection process. The difficulty, which is common to all numerical methods (finite element methods as well), is that the computed deflections may be quite accurate, but the computed strains tend to be in error. This difficulty can be rectified by increasing the number of terms in the assumed displacement function. This increases the computation time required, but the relative magnitude of the increase is quite small for the Rayleigh-Ritz type of analysis as compared to the finite element analyses. However, since the advantages overshadow the disadvantages in a Rayleigh-Ritz solution, several such solution methods have been attempted over the years. As discussed below, these studies have addressed different aspects of the postbuckling problem.

The Rayleigh-Ritz technique was used to analyze an incomplete tension field stiffened beam by Denke (Reference 58). The wave form of the buckled surface was approximated by a function that contained the wave length, wave angle, and wave depth as parameters. Four additional parameters - namely, stiffener compressive strain, chord compressive strain, the chord bending deflection and the panel shearing strain - were introduced to account for the effect of inplane membrane forces. The resultant governing equations were solved to predict the principal midplane stresses, maximum web bending stresses, stiffener and chord compressive stress. A comparison with limited experimental data showed reasonably good correlation. This analysis was limited in scope, as it failed to include rotation and out-of-plane bending in the chords and stiffeners. In addition, the limited number of unknown terms (seven) restricted the accuracy of the solution process.

Levy, et al (References 59 and 60) used the Von Karman large deflection plate equations to study the postbuckling behavior of unstiffened metal plates loaded in shear. The Von Karman equations were solved approximately by assuming a truncated Fourier double sine series. The maximum number of terms in the solution was relatively small, which limited the accuracy of the results obtained.

The analyses in the above studies (References 58 through 60) were limited to a few terms in the assumed functions primarily due to the absence of high speed computers. Modern computers have increased the feasibility of introducing a significantly larger number of terms in the analysis at a reasonable cost.

Several later studies used considerably larger numbers of terms to obtain more accurate solutions. Mayers and Budiansky (Reference 61) used a combination of algebraic and trigonometric functions to represent the inplane and out-of-plane deflections of a flat plate loaded in compression beyond initial buckling. The analytical results were shown to agree reasonably well with the test results. Since material plasticity was not included in these analyses, a small difference in the experimental and analytical results was to be expected which did, in fact, occur.

Chia and Prabhakara (Reference 62) presented an analysis based on the Von Karman type of large deflection equations. These equations were solved by expressing the force function and transverse deflection as a double Fourier series in terms of approximate beam Eigen functions for unsymmetrically laminated rectangular plates. These plates were subjected to uniaxial and biaxial compression. Both simply supported and clamped-boundary conditions were considered. Harris (References 63 and 64) presented approximate analytical expressions for the inplane stiffness immediately after buckling for rectangular composite plates subjected to biaxial compression.

Chan (Reference 65) presented a slightly different form of Rayleigh-Ritz analysis to obtain the postbuckling behavior of compression loaded composite flat plates. The solution was carried out with only the transverse displacement mode assumed. The inplane displacements were obtained exactly from the two membrane displacement equations. Although this method of solution reduces the number of simultaneous nonlinear equations to be solved, it introduces a few additional restrictions. The inplane

displacements become dependent on the assumed shape of transverse deflection and the resulting displacements are not in general capable of accommodating the imposed inplane boundary conditions. In addition, this analysis method cannot be extended to the analysis of stringer stiffened panels under general loading conditions. Further, the advantage offered by this method for postbuckling analysis is not as significant because in conventional applications of the Rayleigh-Ritz method, most of the resulting equations involving inplane displacements are linear in terms of transverse displacement coefficients and, thus, can easily be solved in terms of these transverse deflection coefficients.

The effect of inplane flexural and axial rigidity of stiffeners on the postbuckling behavior of square metal panels was examined in Reference 66. The panels were loaded in shear and compression. The Von-Karman equations were solved by assuming the shape of the normal displacement and the stress function. The analysis failed to include the torsion and outof-plane flexibility of the stiffeners.

In an attempt to improve the empirical analysis of Kuhn, a rather rigorous analysis of flat tension field beams was formulated during the development of SST technology (Reference 67). The problem was formulated for a cantilever beam consisting of internal stiffeners. The beam displacement functions were selected to satisfy the boundary conditions imposed during the tests. This resulted in the inclusion of the shear and bending deformations of the beam; inplane bending, out-of-plane bending, axial deformation, rotation, and warping of internal stiffeners; inplane bending, axial deformation, rotation, and warping of the chords; and axial deformation, rotation, and warping of the two edge vertical stiffeners. The analysis was the first attempt to duplicate the exact mechanism of load introduction for the tension field shear beam specimen. The analysis was formulated and some results were presented for a single-bay panel. The cancellation of the SST program and some convergence difficulties in the solution process halted further development and verification of the analysis for multibay panels.

Khot (References 68 and 69) demonstrated the usefulness of this approach by studying the postbuckling behavior and imperfection sensitivity

of composite cylindrical shells loaded under axial compression. Dickson, et al, References 70 through 72, formulated the problem of composite stiffened panels in the postbuckling range using the Rayleigh-Ritz approach. In Reference 72, the Rayleigh-Ritz solution procedure has been used in conjunction with an optimization routine to design a curved composite stiffened panel. The analysis has also been extended to predicting the local stress state at the skin/stiffener interface in stiffened composite panels (Reference 73). Experimental evaluation of this predictive methodology, however, has not been carried out.

In References 74 and 75 the analysis suggested in Reference 58 for metal panels was modified for use with composite panels loaded in shear. The results of this analysis were compared with several existing composite panel tests. A fairly good correlation between measured and predicted maximum out-of-plane deflections and inplane strains in the panel center was demonstrated. This analysis, once gain, demonstrated the usefulness of the Rayleigh-Rotz type of solutions to predict the postbuckling behavior of composite panels. Because of the limited number of terms used in the assumed functions, the predicted and measured values were not in as good agreement near the panel edges as at the center. This shortcoming can be improved by taking additional terms in the solution. Rapid convergence coupled with nominal computer run times makes the approach attractive for design purposes. The increasing popularity of the Rayleigh-Ritz approach is manifested in several recent studies (References 76 through 78) where attempts have been made to develop the technique into a design tool.

2.2.3 Fetigue Analysis Methods

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The phenomenon of fatigue crack initiation and propagation in metallic structures has been studied by many investigators. As a result, several useful and practical damage propagation models have been established on the basis of classical linear elastic fracture mechanics. One such example is the Forman equation (Reference 79) which is useful in predicting the fatigue crack growth life of metallic structures. Before applying these techniques to postbuckled metal panels, however, test data are required to determine the fatigue failure modes of these panels. In addition, analytical techniques are needed to predict the local stress intensity factors.

The only fatigue test data available in the literature for postbuckled metal shear panels are shown in Figure 2.1. These data were obtained in Reference 3 from constant amplitude fatigue tests on multibay shear panels. The four panels tested in Reference 3 exhibited very short fatigue lives (500 to 4000 cycles) due to cracks initiating at the corners of the chem-milled stiffener attachment pads on the skin. These data show that fatigue is a serious concern in the design of postbuckled metal panels. Additional test data are required, however, to establish the fatigue failure modes and S-N curves for curved metal shear panels.

Compression fatigue test data for flat stiffened panels loaded in the postbuckling range have been obtained in References 80, 81 and 82. In these panels fatigue cracks occurred in the stiffeners at stiffener attachment fastener holes and propagated along the loading direction as illustrated in Figure 3.2. The fatigue failure mode for flat stiffened panels loaded in compression, however, is unique to this design. Crack initiation in the skins at these fastener holes is also possible depending on the local stresses in the skin and in the stiffener. Thus, to interrogate all possible modes of fatigue failure in postbuckled metal panels, additional tests on different designs, including curved panels, need to be conducted.

In order to develop a generally applicable fatigue life prediction methodology for postbuckled metal shear and compression panels, analytical techniques that can predict the local stress intensity factors are required. This in turn requires a knowledge of the detailed stress field in the skins and the stiffeners. As mentioned before, the local stress field can only be obtained from nonempirical analyses. Thus, a Rayleigh-Ritz type analysis in conjunction with a fatigue crack growth law such as that given by the Forman equation can be readily used to predict the fatigue life of postbuckled metal panels.

In contrast to the state-of-the-art in fatigue analysis of metals, fatigue analysis of composites is still in its infancy. However, a sizeable fatigue test data base for postbuckled composite panels is available and indicates that composite panels, in general, are extremely durable.





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Figure 2.2. Fatigue Crack Propagation in Metal Compression Panels (Reference 82)

The fatigue test data generated in some of the investigations cited in Table 2.1 provide a good insight into the durability characteristics of postbuckled composite designs.

Test data for shear panels subjected to constant amplitude and spectrum fatigue loading are shown in Figure 2.3. These data were obtained from several test specimens in various government-funded programs. From Figure 2.3 it can be seen that the spectrum fatigue lives are considerably longer than constant amplitude fatigue lives; this illustrates the relatively high severity of constant amplitude loading. The test data from Reference 16 appear to be the lower bound for the fatigue data. The relatively steep S-N curve for these data is due to a design flaw at the stiffener skin junction where no ply drop-offs were included for a smooth transition. This design drawback when corrected for (Reference 83) yields a fatigue life comparable with the test data from References 14 and 23. The lack of tapered stiffener flanges in Reference 16 is also responsible for making the R = 0.1 fatigue data appear more severe than the R = -1 data of Reference 14. In all cases, however, it should be noted that the fatigue endurance limit is at least the design limit load. Thus, the data indicate extremely long fatigue lives at panel design limit load. In these designs, the panels were prevented from buckling during the level flight condition of a typical V/STOL aircraft. The minimum gage* requirements resulted in panel failure load being much greater than the required ultimate load, a condition which is typical in most aircraft applications.

The fatigue response of composite compression panels is summarized in Figure 2.4. The data indicate that extremely long fatigue life can be expected for design limit strain levels of 2,500 µinches/inch. Most postbuckled panels are buckling-critical and not strength-critical. The current design practice does not allow the average compressive limit strain to be higher than 3,000 µinches/inch. Thus, fatigue for composite panels may not be a design driver.

^{*} Minimum gage defines the minimum laminate thickness. In current industry practice minimum laminate thickness ranges between 0.02 inch and 0.04 inch.



Figure 2.3. Composite Shear Panel Fatigue Response



Figure 2.4. Composite Compression Panel Fatigue Response

The available test data for composite panels loaded under combined compression and shear also demonstrate the same trend. The test data (Reference 25) presented in Figure 2.5 indicate almost no loss in panel strength after two lifetimes of spectrum fatigue with the maximum load set at 71.6 percent of the failure load. Preliminary test data from ongoing Navy programs (References 28, 32) also indicate similar trends. The dominant failure mode in all these fatigue tests was stiffener/skin separation which is a direct consequence of initiation and propagation of delaminations in the skin/stiffener interface. Analytical prediction of fatigue life of postbuckled composite panels, therefore, requires a knowledge of the interfacial stresses and a fatigue analysis methodology that can predict damage propagation in composites.

Several analysis methods to predict skin/stiffener interfacial stresses and subsequent interface failure have been proposed (References 20, 73, 83 and 84). However, experimental validation of these methods has not been very successful. In Reference 20, Agarwal has proposed a stiffener/ web interface stress analysis using a two-dimensional nonlinear model of a diagonal strip from a shear panel. The model utilizes a Rayleigh-Ritz type procedure to obtain the shear and normal stresses at the skin-stiffener interface. Experimental validation of the model was attempted by testing metal coupon specimens and comparing the measured failure loads with predictions. The coupon tests showed good agreement with the predictions which were based on a quadratic failure criterion. However, correlations with data from tests on stiffened composite panels have not been successful due to uncertainties in the interface properties and the validity of the quadratic failure criterion. The model proposed in Reference 84 by Tsai is similar to the beam model in Reference 20, except that Tsai uses experimentally measured out-of-plane displacements to obtain the stiffener web interfacial peel stresses.

In Reference 83 a detailed 3-D NASTRAN stress analysis of the stiffener/web interface has been performed. These results although useful for comparison with other simplified analyses, have not been experimentally validated and the method itself cannot be used as a cost-effective design tool. A more rigorous approach of first predicting the nonlinear postbuckled response of a stiffened composite panel and then using the local



Figure 2.5. Fatigue Response of Flat Panels Under Combined Loading (Reference 25)

stress field in the skin to predict the stiffener/web interface stresses by a linear analysis has been developed in Reference 73. The global nonlinear analysis (Reference 72) and the local (stiffener/web interface) linear analysis (Reference 73) are both carried out using the Rayleigh-Ritz method. The analysis takes into consideration several skin/stiffener interface variables that are not accounted for in the simple beam models, and at the same time is less cumbersome to use than a finite element analysis. However, the results have not been experimentally validated. Thus, at present a fully developed stiffener/skin interface stress analysis methodology is not available for use in fatigue analysis of composite stiffened panels. The approach proposed in Reference 73, however, seems to be the most promising.

An extensive survey (Reference 85) of the available methods for fatigue life prediction of composites showed that these can be broadly clacsified as empirical techniques, degradation models, and damage propagation models. A summary comparison of the advantages and disadvantages of these methods is shown in Table 2.2 taken from Reference 85. Among these methods, the damage propagation models appear to be well suited to the fatigue analysis of postbuckled composite panels. In particular, the strainenergy-release-rate based delamination propagation model (Reference 86) appears most promising. It is necessary, however, to extend this model for application to postbuckled composite panels.

In summary, therefore, the observation of different failure modes in metal and composite postbuckled structures and the significantly different response of composite structures makes it essential that separate methodologies be developed to predict the fatigue life of metal and composite panels. A key prerequisite in both cases is that the local displacement or stress field in the postbuckled regime be known. In addition, for composite panels a validated methodology to predict the skin/stiffener interface stresses is required. Finally, development of a fatigue analysis methodology by coupling the local analyses with a crack growth or delamination growth law needs to be carried out.

2.3 SELECTION OF ANALYTICAL METHODS

A complete static analysis of postbuckled structures consists of predicting the initial buckling load of the skin, failure load of the

TABLE 2.2. SUMMARY OF LIFE PREDICTION MODELS FOR COMPOSITES

Γ	Technique or model	Method	Adventages	Disadvantages
-	Empirical	Experimental	Simple analysis	Extensive testing No general conclusions Conservative design
2	Miner's rule	Linear cumulative damage	Simple analysis	 Loading sequence not accounted for Poor correlation
3	Linear strength degradation	Nonlineer demage accumulation based on lineer strength degradation	Simple analysis Load sequence accounted for	 Assumed strength degradation model does not agree with actual degradation generally observed in composites
4	Wear-out model	Strength degradation based on fracture mechanics of metals Statistical	 Fatigue life and rasidual strength directly related to static strength 	 Extensive testing parameters dapend on laminete and load spectrum Cannot be used for life prediction from S-N curves
5	Strength degradation model and other statistical models	Assumed strength degradation laws Statistical	Similar to wear-out model	Similar to wear-out model
6	Dolamination propagation model	Detamination propagates under interlaminar stresses Growth-rate equation similar to crack growth equation in metals	 Actual damage propagation modeled Constants depend on resin system only Correlates data well 	Not applicable to nondelamination- prone laminates Interlaminar stress computation time-consuming
7	Fracture mechanics delamination model	 Relating delamination growth rate to strain energy release rate Both modes I and II considered 	Similar to determination propagation model Strain energy release rate easier to obtain Detamination size determined more accuratly	Not applicable to nondelamination- prone laminates Actual application to life prediction not investigated
8	Intralaminar cracking model	Strain enargy density matrix cracking	 Process of matrix cracking can be modeled by a single- strain energy density parameter 	Not applicable to delamination- prone laminates Prediction not verified by data

structure after skin buckling. The scope of this program encompassed cylindrically curved stiffened panels loaded in compression or shear only.

As discussed in subsection 2.2, several analysis methods, ranging from closed form semiempirical methods to extremely sophisticated large computer codes, are available to predict the initial buckling loads of curved panels. The main difficulty in accurately predicting the initial buckling load arises from a lack of definition of the exact boundary conditions and due to the presence of structural imperfections. In view of these uncertainties, semiempirical methods based on test data are best suited for preliminary analyses. Furthermore, due to the lack of a wellestablished, rigorous failure analysis methodology for postbuckled panels, semiempirical analysis methods have to be utilized for predicting the strength of curved metal or composite panels. Thus, to meet the objectives of the present program semiempirical analytical methods that are well documented for metal panels (e.g., References 2 and 34) were selected. Based on available test data for composite panels loaded in shear or compression, the semiempirical analyses were modified for generic application to composites.

The semiempirical analysis techniques selected are detailed in the following paragraphs. The modifications that extend the applicability of the analyses to composites along with supporting data are also discussed.

2.3.1 COMPRESSION PANELS

Analysis of postbuckled curved compression panels is performed in the steps outlined below. The critical parameters in the analysis are evaluated in terms of strain, since strain is more convenient to use for composite panels whereas for metal panels it can be used interchangeably with stress. The analysis proceeds as follows:

- (a) Determine the buckling strains for all possible modes of instability. These include: skin buck-. ling between stiffeners, Euler buckling of the stiffened panel, and stiffener cripping.
- (b) Determine the failure load due to Euler buckling, stiffener crippling and other modes of failure

peculiar to composite or metal panels. For composite panels the load for stiffener/web separation mode of failure needs to be calculated whereas for metal panels loads causing permanent set in the skin or the stiffener must be calculated.

(c) The load carrying capacity of the panel is then determined as the lowest of the loads calculated in (b) above.

Calculation of Skin Buckling Strain/Load - The buckling stress

for curved metal sheet panels can be calcusated from:

$$F_{CR} = \frac{K_c \pi^2 E}{12(1-\nu^2)} \left(\frac{t_w}{b_s}\right)^2$$
(1)

where,

FCRbuckling stress, psitwthickness of the skin, inbsstiffener spacing measured between the
fastener lines, inE,Vmodulus and Foisson's ratio for the
sheet materialKcbuckling coefficient determined from
Figure 2.6 (Reference 34 and 35)

The theoretical value of K_c is obtained from the buckling equations for thin cylindrical shells and is a function of the nondimensional curvature z of the panel expressed as

$$z = \frac{b_{g}^{2} (1-v^{2})^{\frac{1}{2}}}{rt_{w}}$$

where r is the radius of the cylindrical panel. Experimental data (Reference 35) have shown that K_{c} is also a function of the r/c ratio for the panel. The design curves of Figure 2.6, obtained from test data, show this dependence of K_{c} on r/t.

Compression buckling strains for curved composite panels can be accurately determined through the use of computer codes SS8 (Reference 45)





and BUCLASP-2 (Reference 41), for example. However, for an approximate calculation of the skin buckling strain in cases where the stiffener spacing is realistic, the simplified equation given below can be used.

$$\varepsilon_{cr}^{W} = \left(\frac{m\pi}{L}\right)^{2} \frac{1}{E_{xW}^{t} t_{W}} \left[D_{11} + 2 \left(D_{12} + 2D_{66} \right) \left(\frac{nL}{mb_{W}}\right)^{2} + D_{22} \left(\frac{nL}{mb_{W}}\right)^{4} \right]$$

$$+ \frac{E_{yW}}{\left(\frac{m\pi}{L}\right)^{2} R^{2} \left[E_{xW} - \left(2v_{xyW}^{E} t_{yW} - \frac{E_{xW}^{E} t_{yW}}{G_{xyW}}\right) \left(\frac{nL}{mb_{W}}\right)^{2} + E_{yW} \left(\frac{nL}{mb_{W}}\right)^{4} \right]$$

$$(2)$$

where D_{ij} are the terms of the bending stiffness matrix of the composite skin, E_{xw} , E_{yw} , G_{xyw} , v_{xyw} and t_w are the web elastic constants and thickness, respectively, L is the panel length, b_w is the width of the skin, R is the radius of curvature of the panel and n and m are integer coefficients representing the number of half buckle waves in the width and length direction, respectively. The lowest value of strain for various values of n and m represents the buckling strain of the specimen.

The effective width of the skin, b_w , was assumed to be equal to the distance between the two adjacent stiffeners measured from one stiffener flange edge to the next stiffener flange edge as shown in Figure 2.7.* Note that b_w is less than the stringer spacing b_e .

Equation (2) was derived in Reference 87 from the equations developed for the buckling of orthotropic complete cylinders by making simplifying assumptions.

<u>Euler Buckling Strain Calculations</u> - The Euler buckling strain for a stiffened panel is calculated by treating the panel as a wide column with the width set equal to the stiffener spacing. The critical strain is calculated using the standard column equation:

*Note that this definition of b_w was used initially. The test data in Section 3 indicate that b_w should be measured between stiffener flange centerlines. See Section 5 for details.



Figure 2.7 Skin Width b_w for Composite Panel Initial Buckling Strain Calculations, b = Stringer Spacing.

$$\varepsilon_{CR}^{E} = \frac{C \pi^{2} EI}{EA L^{2}}$$
(3)

where, EI is the equivalent bending stiffness of the panel, EA is the equivalent axial stiffness, L is the panel length, and C is the end fixity coefficient. The fixity coefficient depends upon the support conditions at the pane¹ ends. Most compression panels are tested by flat end testing and the results obtained by using C = 4 are quite unconservative; therefore, a value cf C = 3 is recommended. The values of C for other end conditions can be obtained from Reference 34 (Section A18.23).

<u>Stiffener Crippling Strain/Stress Calculation</u> - The crippling strength of metal stiffeners is calculated using the well established Needham and Gerard methods documented in Reference 34. In the present program, the Gerard method was used since it is a generalization of the Needham method and was derived from a broader data base. The empirical Gerard equation for calculating the crippling stress for 2 corner sections, such as the Z, J and channel sections, is:

$$\frac{F_{cs}}{F_{cy}} \approx 3.2 \left[\left(\frac{t^2}{A} \right) \left(\frac{E}{F_{cy}} \right)^{1/3} \right]^{0.75}$$
(4)

where,

 F_{cs} = crippling stress for the section, psi F_{cy} = compressive yield stress of the material, psi t = element thickness, in A = section area, in²

A design curve based on Equation (3) is shown in Figure 2.8 taken from Reference 34. Additional crippling equations that apply to sections other than 2 correr sections are also given in Reference 34.



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Figure 2.8. Crippling Stress F_{cs} for Two Corner Sections e.g., Z, J and Channel Sections (Reference 34, Figure C7-9)

In order to calculate the crippling strains for stiffeners made of composite materials, a semiempirical methodology was developed in the program. The methodology consists of modelling the stiffener in terms of interconnected flat plate elements, calculating the initial buckling and crippling strains for each element, and determining the crippling strain for the stiffener as the lowest strain that causes crippling of the most critical element in the stiffener section. It should be noted here that the absolute minimum of the crippling strains for the various plate elements is not necessarily the stiffener crippling strain; element criticality with respect to stiffener stability has to be considered as well. The procedural details of this methodology given in the following paragraphs provide additional clarifications relating to the determination of the most critical plate element.

The first step in calculating the stiffener crippling strain is to model the stiffener as an interconnected assembly of plate elements. As examples, plate element models of a hat-section and a J-section stiffener are shown in Figure 2.9. The hat-section stiffener is made up of six elements, whereas, the J-section stiffener consists of five elements.

The crippling strains for the plate elements are calculated from empirical equations of the form

$$\frac{\varepsilon_{\rm cs}}{\varepsilon_{\rm cr}} = \alpha \left(\frac{\varepsilon_{\rm cu}}{\varepsilon_{\rm cr}}\right)^{\beta}$$
(5)

where,

- ε_{cs} = crippling strain of the plate ε lement
- ε_{cr} = initial buckling strain of the plate element
- e compression ultimate strain for the plate element
 laminate
- α, β = material dependent coefficients obtained from test data



Equation (5) has the same functional form as that used by Gerard (Reference 35) for metal stiffeners. The coefficients α and β depend on the plate edge conditions and have been obtained in References 46 and 47 from a large data base for plate elements that are connected on both sides (e.g., elements 2, 3, 4 and 5 of the hat-section stiffener shown in Figures 2.9). The crippling strain for stiffener plate elements connected on both sides is given by (Reference 47):

$$\varepsilon_{\rm cs} = 0.56867 \varepsilon_{\rm cr} \left(\frac{\varepsilon_{\rm cu}}{\varepsilon_{\rm cr}}\right)^{0.47567}$$
(6)

where ε_{cr} , the buckling strain for the plate element is given by (Reference 89):

$$\varepsilon_{\rm cr} = \frac{2\pi^2}{b^2 t E_{\rm x}} \left(\sqrt{D_{11}D_{22}} + D_{12} + 2D_{66} \right)$$
(7)

In Equation (7)

b = plate element width
t = plate element thickness
E_x = compression modulus of the plate laminate
along the longitudinal direction
D_{ij} = terms from the laminate bending stiffness
matrix, (i,j = 1, 2, 6)

Equation (7) applies to plate elements for which the length to width ratio (L/b, where L = stiffener length) is at least 4.

The crippling strain for plate elements that are connected on one side only is calculated using the following equation:

$$\varepsilon_{cc} = 0.4498\varepsilon_{cr} \left(\frac{\varepsilon_{cu}}{\varepsilon_{cr}}\right)^{0.72715}$$
(8)

where,

$$\varepsilon_{\rm cr} = \frac{\frac{12 \, {}^{\rm b} 66}{{}^{\rm b}{}^{\rm c} t \, {}^{\rm E}_{\rm x}} + \frac{4\pi^2 {}^{\rm D}_{11}}{{}^{\rm L}{}^{\rm c} t \, {}^{\rm E}_{\rm x}}$$
(9)

L = length of the stiffener

with the other nomenclature remaining the same as for Equations (6) and (7).

The coefficients in Equation (8) were obtained by fitting Equation (5) to the crippling data generated from tests on one-edge free plates in References 46 and 47. Data for two material systems, T300/5208 and AS/3501 graphite/epoxy, were pooled to obtain Equation (8).

In Equations (6) through (8), the thickness of plate elements attached to the skin is taken as the sum of the plate element and the cocured skin thicknesses. In the case of the hat-section stiffener, crippling strains for plate elements representing the skin only, such as element 5 in Figure 2.9 are also calculated. Another consideration in calculating the crippling strain for stiffener flange elements attached to the skin is the choice of an appropriate element width. For example, in most practical designs the stiffener flanges attached to the skin are tapered by droppingoff plies as shown in Figure 2.10 for a hat-section stiffener. The flange plate element width in this case is defined as the width to the end of the taper with the weighted average of the element thickness added on to the attached skin thickness to obtain the total thickness for use in Equations (6) through (8).

Equations (6) through (8) are quite general in nature and take into account ply composition, stacking sequence, and material characteristics. The ply composition, i.e., the percentages of 0° , 45° and 90° plies, is reflected in the compression ultimate strain ε_{cu} . Stacking sequence effects are accounted for in the expression for ε_{cr} where the bending stiffnesses D_{ij} are used. The $D_{ij's}$ and ε_{cu} also account for mechanical property changes from one material system to another. Use of strain rather than stress for crippling calculations provides another significant advantage in that laminate non-linearity (e.g., stress-strain response



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Figure 2.10 Ply Drop-Offs in Hat-Section Stiffener.

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of $\pm 45^{\circ}$ laminates) is accounted for by way of the compression ultimate strain ε_{cu} .

<u>Failure Load Calculation</u> - The failure load for the panel is determined as the lowest of the loads calculated for the various instability modes mentioned above, for stiffener-web separation in composite panels, and for skin or stiffener yielding in metal panels. The methods for failure load calculation are given in the following paragraphs.

Failure Load Due to Euler Buckling - The failure load due to Euler buckling is calculated using the following equation:

$$P_{E} = \varepsilon_{cr}^{E} \left(\varepsilon_{xs} A_{g} + \varepsilon_{xw} b_{w} t_{w} \right)$$
(10)

where,

- $\varepsilon_{c\tau}^{E}$ = Euler buckling strain determined using Equation (3)
- E = Compression modulus of the stifiener in the loading direction
 - = Cross-sectional area of the stiffener
- E = Compression modulus of the web (skin) in the loading direction
- b₁ = Stiffener spacing
- t = Skin thickness

<u>Failure Load Due to Stiffener Crippling</u> - In order to determine the failure load due to stiffener crippling, it is necessary to determine the load carried by the stiffener and the panel web individually. The load carried by the stiffener (P_g) is determined as tollows:

- 1. Determine the two lowest crippling strains (ε_{ccl}) and (ε_{cc2}) of all the elements making up the cross-section using Equations (6) through (8).
- 2. If the element with the lowest crippling strain (ε_{ccl}) is normal to the axis of least bending stiffness of the closs-section, the stiffener

will fail at a strain equal to ε_{c21} , and the corresponding failure of the stiffener is given by:

$$P_{S} = E_{XS} A_{CC1}$$
(11)

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3. If the element with the lowest crippling strain is parallel to the axis of least bending stiffness of the cross-section, the stiffener will carry additional load until the second member in the cross-section becomes critical due to crippling. In this case the load carried by the stiffener is given by:

$$P_{S} = (EA)_{1} (\varepsilon_{ccl} - \varepsilon_{cc2}) + \varepsilon_{cc2} E_{xs} A_{s}$$
(12)

where (EA)₁ is the extensional stiffness of the member becoming critical first, and the stiffener failure strain $\varepsilon_{cc}^{S} = \varepsilon_{cc2}$.

The total load carried by the panel is the sum of the load carried by the stiffener up to crippling and the load carried by the buckled skin. In order to calculate the load carried by the skin, the effective width concept is utilized. The effective width for metal panels is calculated using the semiempirical equation given below (Reference 34):

$$w = 1.9t_w \sqrt{\frac{E}{F_{st}}}$$
 (13)

where,

w = effective width of the skin after initial buckling
t_ = skin thickness

F = stress in the stringer

For composite panels, in the absence of any other guidelines, Equation (13) expressed in terms of strain is used to compute the effective skin width. Thus,

$$w = 1.9t_w(\varepsilon^8)$$
(13A)

for composite skins where, $e^{S} = strain$ in the stiffener.

Thus, the total load carried by the panel for a stiffener crippling mode of failure is given by:

$$P = P + P \tag{14}$$

where,

P_{cc} = load carried by the panel at stiffoner crippling
P_s = stiffener load given by Equation (12)
P_u = load carried by the skin

The load P is calculated as:

$$P_{w} = F_{cs} w t_{w} = 1.9 t_{w}^{2} \sqrt{EF_{c3}}$$
(15)

for metal panels, and for composite panels as:

$$P_{w} = 1.9t_{w}^{2} E_{xw}(\varepsilon_{cc}^{s})$$
(16)

<u>Failure Load Due to Stiffener/Web Separation</u> - Failure of composite stiffened panels due to stiffener/web separation is a common mode of failure in the postbuckling range. It is extremely difficult to predict this failure, even by using rather sophisticated analysis methods. The attempts to date on making such predictions have been inconclusive. A simple empirical equation to predict such failure was developed in this program. The correlation of experimental data with the predicted failure loads based upon this equation is surprisingly good. The empirical equation was derived by analogy with the crippling data for plates with one edge simply supported and one edge free. It is hypothesized that when the panel web strain reaches the crippling strain the interfacial streeves become high enough to cause failure. The equation should represent the lower bound on predicted failure loads. Any attempts to improve the interface (for example, by stitching, riveting, etc.) can result in higher failure loads.

$$P_{SS} = \varepsilon_{SS} \left(\sum_{xs}^{A} S + \sum_{xw}^{b} t_{w} \right)$$
(17)

where,

$$\varepsilon_{\rm SS} = 0.4498 \ \varepsilon_{\rm cr} \left(\frac{\varepsilon_{\rm cu}}{\varepsilon_{\rm cr}}\right)^{.72715}$$
 (18)

 ε_{gg} = Failure strain for stiffener/web separation

 P_{SS} = Failure load for the stiffener/web separation mode

The metal compression panel analysis methodology outlined in the preceding paragraphs has been experimentally validated (e.g., Reference 35) and is representative of current usage. In the case of composite panels, experimental validation was necessary before the methodology could be used in designing the program test panels. Composite compression panel test data available from some of the studies cited in Table 2.1 were utilized to validate the semiempirical analysis. Results of the correlation between the predictions and the test data are given in the following subsection.

Experimental Validation of Composite Compression Panel Analysis -Experimental verification of the semiempirical equations was accomplished in two parts: (i) test data on stiffeners of various shapes (e.g., hat, channel, 2, cruciform) were compared with predictions mode using Equations (6) through (8); and (ii) test data for flat and curved stiffened composite compression panels were compared with the initial buckling and failure strain predictions.

Stiffener local buckling and crippling test data for channel, Z, hat cruciform and I grahpite/epoxy sections were obtained from References 46, 47 and 48. A summary comparison of the predictions with the test results is shown in Table 2.3. A comparison of the predicted and measured failure loads for the stiffeners as a function of the strain ration c_F/ε_{cu} , where, ε_F is the strain at failure, is illustrated in Figure 2.11. As seen in the figure, a majority of the test data fall on or above the $P_{exp}/P_{anl} = 1$ line, indicating conservatism in the analysis which is at most 25 percent. A few data points 'n Figure 2.11 fall below the $P_{exp}/P_{anl} = 1$ line. However, these data correspond to stiffeners for which the failure strain was very close to the compression ultimate strain of the laminates and the failure ure mode was column buckling rather than crippling. Thus, the semiempirical

CORRELATION OF SEMI-EMPIRICAL STIFFENER CRIPPLING PREDICTIONS WITH TEST DATA (Continued) TABLE 2.3.

					EYPERIMENT	AL VALUE	
	NUMBER		J.	Ę	ANALYTICA	L VALUE	
Ë)	EFERENCE)	PANEL TYPE	3		BUCKLING	FAILURE	REMARKS
CRIA	MCAIR (48)	+	1.00	1.00	0.79	0.79	FAILURE DUE TO COLUMN BUCKLING
CR18	MCAIR (48)	+	0.222	0.298	0.85	1.10	FAILURE DUE TO FLANGE CRIPPLING
CR2A	MCAIR (48)	-	0.820	0.820	0.77	0.77	FAILURE DUE TO FLANGE CRIPPLING
CR28	MCAIR (48)	-	0.169	0.277	1.02	1.15	FAILURE DUE TO FLANGE CRIPPLING
CR3A	MCAIR (48)	-	3.00	1.00	160	0.91	NO BUCKLING UP TO FAILURE
CR38	MCAIR (48)	+	0.203	0.292	0.87	1.20	FAILURE DUE TO FLANGE CRIPPLING
CR3C	MCAIR (48)	-	0.054	0.204	1.20	66 10	FAILURE DUE TO FLANGE CRIPPLING
CIA	MCAIR (48)	Ľ	0.53	0.53	0.95	6.0	FAILURE DUE TO COLUMN BUCKLING
CIB	MCAIR (48)	[0.039	0.164	1.49	1.06	FAILURE DUE TO WEB CRIPPLING
C2A	MCAIR (48)		0.69	0.69	0.76	0.76	FAILURE DUE TO COLUMN BUCKLING
C28	MCAIR (48)	Ľ	0.028	0.154	0.85	0.884	FAILURE DUE TO WEB CRIPPLING
C3A	MCAIR (48)		1.00	1.00	0.85	0.85	NO BUCKLING UP TO FAILURE
C38	MCAIR (48)		0.048	0.218	1.09	0.94	FAILURE DUE TO WEB CRIPPLING
C3C	MCAIR (48)	۲ ۲	0 045	0.108	1.17	1.12	FAILURE DUE TO WEB CRIPPLING
Ħ	MCAIR (48)	Þ	0.688	0.688	1.04	1.04	FAILURE DUE TO FLANGE CRIPPLING
4	IN A LATCAL BI	ANALYTING CERAIN & ANALYTICA		CTDAIN 6	I AMINATE III	TIMATE CTOAL	

 $\epsilon_{
m cr}$ -- ANALYTICAL BUCKLING STRAIN, $\epsilon_{
m F}$ -- ANALYTICAL FAILURE STRAIN, $\epsilon_{
m cu}$ -- LAMINATE ULTIMATE STRAIN

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CORRELATION OF SEMI-EMPIRICAL STIFFENER GRIPPLING PREDICTIONS WITH TEST DATA (Concluded) TABLE 2.3.

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	REMARKS	FAILURE DUE TO FLANGE CRIPPLING	FAILURE DUE TO EULER BUCKLING	FAILURE DUE TO WEB CHIPPLING	FAILURE DUE TO WEB AND FLANGE CRIPPLING	FAILURE DUE TO COMBINED COLUMN BUCKLING AND CRIP- PLING. PREDICTION BASEG UPON CRIPPLING	FAILURE DUE TO WEB AND FLANGE CRIPPLING	FAILURE DUE TO FLANGE CRIPPLING	FAILURE DUE TO VERTICAL WEB CRIPPLING	PREMATURE FAILURE DUE TO COMBINED CRIPPLING AND COLUMN BUCKLING	FAILURE D'JE YO VERTICAL WEB CRIPPLING	FAILURE DUE TO FLANGE AND WEB CRIPPLING
AL VALUE	FAILURE	1.11	0.7v	1.14	. 1.28	0.78	1.24	1.27	1.10	0.43	1.18	1.52
EXPERIMENT ANAL TTICA	BUCKLING	1.35	0.57	1.úŻ	1.15	0.87	1.12	1.12	83.0	I	1.21	2.29
u U	E CEL	0.245	0.180	0.165	0.287	0.287	0.288	0.256	0.253	0.253	0.154	0.288
	5 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	0.1 P 8	0.180	0.055	0.126	0.126	0.126	0.126	0.213	0.213	0.083	0.045
	PANEL TYPE									5		Ι
SPECIMEN	REFERENCE)	(69) (J) 6	10 GD (89)	11 GD (89)	12 GD (89)	t3 GD (89)	14 GD (39)	15 GD (89)	16 GD (89)	17 GD (89)	18 GD (89)	19 GD (89)

 $\epsilon_{
m cu}$ – Laminate ultimate allowasie strain, $\epsilon_{
m cr}$ – ana: vtical buckling strain, $\epsilon_{
m F}$ – analytical failure strain

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Figure 2.11. Comparison of Analytical and Experimental Data for Stiffener Crippling

stiffener crippling predictive methodology is substantiated by test data over a wide range of stiffener geometries and laminate lay-ups. The analysis can be used as a design tool with a high degree of confidence due to the built-in conservatism.

A similar comparison of analysis and test data was performed for stiffened compression panels. A majority of the data available in the literature pertained to flat panels. Table 2.4 summarizes the results of analytical failure predictions and measured data for a series of flat stiffened panels. To evaluate the accuracy of the predictions the failure load data were plotted as shown in Figure 2.12, where the ratio of the measured failure load to the analytically determined failure load (P_{exp}/P_{anl}) is plotted against the failure strain to ultimate allowable strain ratio ($\varepsilon_{\rm F}/\varepsilon_{\rm cu}$). The data trend is similar to that observed for stiffener crippling predictions in that a majority of the data fall on or above the $P_{exp}/P_{anl} = 1.0$ line, indicating conservatism in the analysis of approximately 25 percent. A data point corresponding to NASA flat panels (Reference 26) falls approximately 20 percent below the analytically predicted failure value. However, this panel was designed such that failure occurred simultaneously with initial buckling of the skin and as such the panel was not loaded into the postbuckling range. Secondly, the initial buckling and failure strain of $6700 \ \mu in/in$ is substantially greater than the current design allowable strain levels for strength critical parts which in turn are higher than the operating strain levels for postbuckled designs. Thus, the semiempirical analysis methodology for composite compression panels is well suited to the design of postbuckled panels where the operating strain levels are of the order of 2500-3500 μ in/in. As a design tool, the semiempirical methodology is somewhat on the conservative side and can be used with a high degree of confidence.

<u>Automation of Stiffened Composite Panel Design Methodology</u> - The semiempirical compression panel analysis documented in the preceding paragraphs has been used to develop a computer program named CRIP to provide an effective design tool. This program is fully documented in Reference 91 where its use is also demonstrated by a design example.

COMPARISON OF ANALYTICAL PREDICTIONS AND TEST DATA FOR STIFFENED COMPRESSION PANELS TABLE 2.4

SPECIMEN.				FXPFRIMENT	AL VALUE	
NUMBER		Eer	6F	ANALYTICA	L VALUE	
(REFERENCE)	PANEL TYPE	Ecu	Gen Gen	อพเาหวกส	FAILURE	REMARKS
NURTHROP/ NAVY (30)		0.0134	0.192	1.13	1.25	FAILURE DUE TO STIFFENER/WEB SEPARATION (ϵ_{cu} = 0.015)
NORTHROP/ NAVY (30)	A D D D	0.077	0.280	6.91	1.25	FAILURE DUE TO STIFFENER/WEB SEPARATION (ϵ_{cu} = 0.015)
MCAIR/NAVY (BASELINE) PANEL (90)		0.056	0.262	1.18	1.09	FAILURE DUE TO STIFFENER/WEB SEPARATION
AIR FORCE+	\subseteq	0.115	0.239	1.08	0.933	FAILURE DUE TO VERTICAL WEB CRIPPLING
U1 NASA (26)	TTT	0.561	0.561	0.78	0.81	ALL PANELS FAILED DUE TO STIFFENER/WEB SEPARATION
U2 NASA (26)		0.258	0.379	0.87	1.04	(€cu = 0.012)
U3 NASA (26)		0.148	0.300	1.00	0.97	
U4 NASA (26)		0.253	0.376	0.83	1.18	
U5 NASA (26)		0.1:7	0.272	10,1	1.18	
UB (MASA) (26)		0.067	0.215	11.1	1.15	
U7 NASA (26)		0.067	0.215	1.14	1.13	
U8 NASA (26)		0.067	0.215	1.20	16.0	
20, 21 GD (89)		0.208	0.235	NDT AVAILABLE	1.24	FAILURE DUE TO STIFFENER/WEB SEPARATION ($\epsilon_{cu} = 0.12$)
E - LAMINATE UL	TIMATE ALLOWABLE STRAIN.	- ANALYTIC	AL BUCKLI	NG STRAIN. E	ANALYTICAL I	AILURE STRAIN


Figure 2.12. Comparison of Analytical and Experimental Data for Composite Compression Panels

The program has been written for interactive use and has several built-in stiffener shapes for application to a wide variety of designs.

2.3.2 Shear Panels

Flat or curved shear panel analysis is accomplished by means of the semiempirical tension field theory developed by Kuhn (Reference 2) for metal panels. In this program the tension field theory was modified for application to composite shear panels by taking into account material anisotropy.

The essential elements of the generalized (for application to metals as well as composites) tension field theory and its application are summarized in Figure 2.13. Details of the semiempirical analyses required to perform the various steps in Figure 2.13 are given in the following paragraphs. The equations as presented below pertain to cylindrically curved composite panels and to flat composite panels if terms incorporating the radius of curvature R are set equal to zero. Use of the appropriate values for elastic constants in the equations permits their direct application to metal panels. The analysis procedure is based entirely on the theory presented in Reference 2 unless specifically noted.

<u>Computation of the Diagonal Tension Factor</u> - The diagonal tension factor k characterizes the degree to which diagonal tension is developed in the skin of sriffened panels loaded in shear. A value of k = 0 characterizes an unbuckled skin with no diagonal tension; a value of k = 1.0 characterizes a web in pure diagonal tension. The diagonal tension factor is computed using the following expression:

$$k = \operatorname{Tanh}\left[\left(0.5 + 300 \, \frac{t_{w}^{h} r}{R \, h_{s}}\right) \log \frac{\tau}{\tau_{cr}}\right]$$
(19)

where,

t_w = web thickness h_r = ring spacing h_c = stringer spacing



Figure 2.13 Application of Tension Field Theory to Shear Panels.

R panel radius

applied shear stress τ

$$\tau_{cr}$$
 = buckling shear stress of web

The shear buckling stress or strain for composite webs can be calculated using program SS8 (Reference 45). The buckling stress for curved metal webs can be calculated using:

$$\tau_{\rm cr,elastic} = \frac{\frac{K_{\rm sl}\pi^2 \ Eh_{\rm s}^2}{12R^2 z^2}}{\frac{16}{12R^2 z^2}} \qquad \text{if } h_{\rm r} \ge h_{\rm s} \qquad (20)$$
$$= \frac{\frac{K_{\rm s2}\pi^2 \ Eh_{\rm s}^2}{12R^2 z^2}}{\frac{16}{12R^2 z^2}} \qquad \text{if } h_{\rm s} \ge h_{\rm r} \qquad (20)$$

where,

R

E

Z

ν

 K_{s1}, K_{s2} = critical shear stress coefficients for simply supported curved plates, given in Reference 2 panel radius, in Young's modulus for the material, psi

$$= \frac{h_s^2}{Rt_w} \sqrt{(1 - v^2)} \qquad \text{if } h_r \ge h_s$$
$$= \frac{h_r^2}{Rt_w} \sqrt{(1 - v^2)} \qquad \text{if } h_s \ge h_r$$

= Poisson's ratio for the material

Computation of Diagonal Tension Angle 'a' - An initial value is assigned to the diagonal tension angle ' α ' that defines the angle of the 'folds' in the buckled skin. For curved web systems $\alpha = 30^{\circ}$ was found to be a convenient starting point. The actual value of a is determined by the iterative procedure outlined below.

Using the assumed initial value of α , a 'new' value for α is calculated by the equation:

$$\alpha_{1} = \operatorname{Tan}^{-1} \left[\frac{\varepsilon - \varepsilon_{s}}{\varepsilon - \varepsilon_{r} + R_{f}} \right]^{0.5}$$
(21)

where,

$$\varepsilon = \frac{\tau}{E_{w\alpha}} \left[\frac{2k}{\sin 2\alpha} + \frac{E_{w\alpha}}{2G_{rs}} (1-k) \sin 2\alpha \right]$$
(21a)

$$\varepsilon_{s} = \frac{-k\tau \operatorname{Cot}\alpha}{\left[\frac{\overline{EA}}{h_{s}} + 0.5 (1-k) E_{ws}\right]}$$
(21b)

$$E_{\mathbf{r}} = \frac{-k\tau \operatorname{Tan}\alpha}{\left[\frac{\overline{EA}}{r}}{\frac{\mathbf{r}}{\mathbf{h}_{\mathbf{r}}t}} + 0.5 (1-k) E_{\mathbf{wr}}\right]}$$
(21c)

$$R_{f} = \frac{1}{24} \left(\frac{h_{s}}{R}\right)^{2} \qquad \text{if } h_{r} > h_{s} \qquad (21d)$$
$$= \frac{1}{8} \left(\frac{h_{r}}{R}\right)^{2} Tan^{2} \alpha \qquad \text{if } h_{s} > h_{r}$$

For eccentric stringers and rings

$$\overline{EA_{s}} = EA_{s} \frac{\overline{EI}_{s}}{\overline{EI}_{s}}$$
(21e)
$$\overline{EA_{r}} = EA_{r} \frac{\overline{EI}_{s}}{\overline{EI}_{r}}$$

In Equations (21), ε is the skin strain in the diagonal tension direction, and ε_s and ε_r are the strains in the stringer and the ring leg attached to the web averaged over their lengths, respectively. $E_{w\alpha}$, E_{ws} and E_{wr} are the web moduli in the direction of the tension field, stringers and rings, respectively. G_{rs} is the web shear modulus. \overline{EA}_s and \overline{EA}_r are the effective axial stiffnesses of the stringers and the rings, respectively. EI is the hending stiffness about the stiffener neutral axis and $\widetilde{\text{EI}}$ the bending stiffness about the web midsurface.

In general, α_1 , the new diagonal tension angle will not equal the initially assumed value of 30°. Therefore, α_1 is used as the next guess and the computations of Equations (21) are repeated until the process converges, i.e., $\alpha_{new} \approx \alpha_{old}$.

Once the diagonal tension angle has been determined with sufficient accuracy, the next step is to compute the margins of safety.

<u>Computation of Stringer and Frame Margins of Safety</u> - The diagonal tension angle value computed above is now substituted in Equations (21) to obtain the diagonal tension strain in the skin, the stringer strain, and the ring strain. Next, the stringer and ring strains averaged over the cross section and the length (ε_{ave}) and the maximum strains in the legs attached to the web (ε_{max}) are computed using the following equations:

$$\varepsilon_{save} = \varepsilon_{s} \frac{\overline{EA}}{EA}$$
 (22)

$$\varepsilon_{s_{max}} = \varepsilon_{s} \begin{bmatrix} 1 + 0.775 \ (1-k) \ (1-0.8 \ \frac{h_{r}}{h_{s}}) \end{bmatrix} \text{ if } h_{s} > h_{r}$$

$$\varepsilon_{s_{max}} = \varepsilon_{s} \begin{bmatrix} 1 + 0.775 \ (1-k) \ (1-0.8 \ \frac{h_{s}}{h_{r}}) \end{bmatrix} \text{ if } h_{s} < h_{r}$$

$$\varepsilon_{r_{ave}} = \varepsilon_{r} \ \frac{\overline{EA}_{r}}{EA_{r}}$$
(23)
(23)
(23)
(23)
(24)

$$\varepsilon_{r_{max}} = \varepsilon_{r} \begin{bmatrix} 1 + 0.775 \ (1-k) \ (1-0.8 \ \frac{h_{r}}{h}) \\ s \end{bmatrix} \text{ if } h_{s} > h_{r}$$
(25)
$$= \varepsilon_{r} \begin{bmatrix} 1 + 0.775 \ (1-k) \ (1-0.8 \ \frac{h_{s}}{h}) \\ r \end{bmatrix} \text{ if } h_{s} < h_{r}$$

The stringer and ring crippling mode of failure is then analyzed for by computing the stringer and ring forced crippling strains (ε_{os} and ε_{or} , respectively) using the following equations:

$$\varepsilon_{\rm os} = 0.00058 \left[\left(\frac{\varepsilon_{\rm all} \ \varepsilon_{\rm cs}}{1000} \right)^{0.4} k^{2/3} \left(\frac{t_{\rm us}}{t_{\rm w}} \right)^{1/3} \right]$$
(26)

$$\varepsilon_{\text{or}} = 0.00058 \left[\left(\frac{\varepsilon_{a11} E_{\text{cr}}}{1000} \right)^{0.4} k^{2/3} \left(\frac{t_{\text{ur}}}{t_{\text{w}}} \right)^{1/3} \right]$$
(27)

where ε_{all} is the laminate allowable strain, E_{cs} and E_{cr} , are the modulus of the stringer and ring leg attached to the web, respectively, and t_{us} and t_{ur} are the thickness of the stringer and the ring leg attached to the web.

The critical stiffener strains corresponding to the bending stiffness required for stiffener stability are calculated using Equations (28) and (29).

$$\varepsilon_{sB} = \frac{4\pi^2 EI_s}{E_{xs}A_sh_r^2}$$
(28)

$$\varepsilon_{\mathbf{r}\mathbf{B}} = \frac{4\pi^2 \operatorname{EI}_{\mathbf{r}}}{\operatorname{E}_{\mathbf{x}\mathbf{r}} \operatorname{A}_{\mathbf{r}} \operatorname{h}_{\mathbf{s}}^2}$$
(29)

where, ε_{sB} and ε_{rB} are the Euler buckling strains for the stiffener and the ring, respectively.

The margins of safety can now be computed for each of the possible failure modes by comparing the calculated strain values with the allowables. Thus, to ensure positive margins, the following failure modes are examined and the corresponding inequalities verified.

- (i) For stringer and ring stability,i.e., no column failure
- (ii) For stability of the entire panel, i.e., to prevent buckling of the web as a whole, before formation of the tension field
- $\epsilon_{sB} > \epsilon_{save}$ $\epsilon_{rB} > \epsilon_{save}$ $\epsilon_{rB} > \epsilon_{save}$ $EI_{s} > E_{s}t_{w}^{3} (\frac{3h_{s}}{h_{r}} 2)h_{s}$ $EI_{r} > E_{r}t_{w}^{3} (\frac{3h_{r}}{h_{s}} 2)h_{r}$ (30)
- (iii) For prevention of forced crippling of stiffeners $\varepsilon_{os} > \varepsilon_{smax}$ $\varepsilon_{or} > \varepsilon_{rmax}$

An additional check needs to be performed for metal panels where yielding or permanent set in the web is likely due to excessive skin deformation. The only available criterion for permanent set check has been empirically obtained from tests on flat aluminum metal panels. Its applicability to other materials or curved panels has not been verified. Thus, in the absence of any other guidelines, the flat panel requirement that the maximum allowable value of the diagonal tension factor k_{all} be limited to

$$k_{all} = 0.78 - (t - 0.012)^{0.50}$$
 (31)

at design ultimate load to prevent permanent buckling of the web at limit load, is used in the present analysis.

Experimental Validation of Shear Panel Analysis - The semiempirical analysis outlined above has been experimentally verified for metal panels in References 2 and 5. In order to validate the modifications introduced in the methodology for anisotropic materials, the analysis results were compared with available test data for composite shear panels. The analysis methodology was exercised on composite shear panels designed, fabricated and tested in References 13 through 17. In these studies a total of 7 panel configurations with different stiffener shapes, web thicknesses, web laminate orientations, and stiffener spacings were tested through the

use of various test setups. Table 2.5 summarizes some of the key parameters of the panels, and the ratio of the analytically predicted failure loads to the experimentally observed failure loads. The analytical predictions were based on stringer forced crippling mode of failure. The failure mode for all panels tested was separation of the stringers from the panel skin. The good agreement between the measured and predicted failure strains inspite of the difference in failure modes indicates that the two failure modes are closely related and it is hypothesized that forced crippling of the stringers in shear panels precipitates skin/stiffener separation. Thus, the stiffener forced crippling criteria can be used to predict stiffener/skin separation in composite shear panels.

INVESTIGATOR (REFERENCE)	h s(INCH)	^h r/ ^h s	ST1FFENER SHAPE	ea _s (KSI)	EI _s LB/IN ² X 10	$\frac{\tau_{\rm ULT}}{\tau_{\rm cr}}$	P _{ANL} / ^P EXP
NORTHROP/NAVY (14)	10	1.5	HAT	2.5	0.40	5	0.93
MCDONNELL/NAVY (16,94)	6	2.67	HAT	1.8	0.37	9.2	0.91 (1.03)*
LOCKHEED NAVY (15)	6	3.75	I	1.5	0.90	6	1.08
GRUMMAN/NAVY (17)	7	3.43	HAT	2.9	1.0	6	1.025
NORTHROP/IR&D (13)	13	1.15	HAT	2.9	0.73	10	1.05
NORTHROP/IR&D (13)	13	1.15	I	2.9	0.313	10	0.91
NORTHROP/IR&D (13)	9	1.66	HAT	2.9	0.30	7	0.80

TABLE 2.5. CORRELATION OF SEMI-EMPIRICAL ANALYSIS WITH TEST DATA FOR SHEAR PANELS

Failure due to ring crippling ==

Stringer spacing

h

Ring spacing h,

Stringer axial stiffness EA

Stringer bending EI =

Ultimate failure stress τ_{ULT}

Buckling stress τ_{cr}

Analytical failure load PANL

Experimental failure load PEXP

It should be noted that the forced crippling equations used in the analysis, Equations (26) and (27), do not specifically include the interface material properties. Additional verification using data generated for a variety of material systems is essential before the application of these equations to stiffener/web separation prediction can be generalized. Failure of the stifferer/web interface does not necessarily have to occur if the interfacial strength can sustain the applied stresses due to forced crippling. Thus, the forced crippling criterion seems to present a lower bound for the failure load of cocured composite stringers by stiffener/web separation. This information is of significance to designers.

All panels examined above consisted of composite stringers and metal frames (rings) with the exception of the panels in Reference 16. The ring crippling failure load and the stringer crippling failure load for the panels in Reference 16 were nearly equal in magnitude with analytically predicted failure due to stringer separation. Although the experimental data showed failures due to frame (ring) separation, subsequent efforts to improve the strength of these panels by improving the ring/web interface (Reference 83) resulted in failure due to stringer/web separation without much increase in the panel failure load, indicating both modes of failure to be quice close to each other as predicted.

The analytical and experimental correlations presented above, thus, mark a milestone in the analysis of postbuckled composite shear panels since they validate the modifications to the tension field theory.

<u>Automation of Shear Panel Analysis Methodology</u> - The modified tension field theory outlined above has been incorporated in a computer program called TENWEB that can be used as an efficient design tool. Detailed documentation for this shear panel analysis program is given in Reference 91. The program is interactive and has several built-in stiffener profiles for design flexibility.

Program TENWEB was used to design the shear panels tested in this study. Details of program operation are given in Reference 91.

SECTION 3

EXPERIMENTAL PROGRAM

3.1 INTRODUCTION

The technology assessment documented in Section 2 showed that the current design methodology for postbuckled panels is predominantly empirical and was originally developed on the basis of flat metal panel test data. Although the methodology was later extended to curved metal panels, the data base to verify this extension was extremely limited. Since the near term application of postbuckled metal or composite panel designs is expected to be in curved fuselage structures, it is essential that the differences in the static and fatigue response of flat and curved panels be understood and the available data base on curved metal and composite panels be expanded for verification of the analysis methodology.

There are two main differences in the postbuckling behavior of curved and flat panels. First, evidence exists to show that the initial buckling load of curved metal panels, while higher than flat panels of the same size, is reduced significantly after repeated loading. Test data do not show the same phenomenon for flat metal panels. Test data show that the buckling load of composite flat panels is reduced due to fatigue loading.

Second, the buckling of curved shear panels produces significant inward normal forces on the stringers and frames. These forces may prove beneficial for cocured composite panels, since they tend to delay the separation of stringers and frames from the skin, which was found to be a primary mode of failure in flat composite tension field panels. These differences in the behavior of curved and fiat panels may have a significant effect on their ultimate strength and fatigue life. Therefore, in this experimental program, curved metal and composite panels were tested to establish a reliable data base on their static and fatigue response. As a first step in developing a design methodology for curved postbuckled panels, it was also decided that the panels would be loaded either in compleasion or shear only, so that once panel behavior under these simpler

loading conditions was understood, the more complex case of combined loading could be addressed next.

Thus, the specific objective of the test program was to conduct static and fatigue tests on curved metal and composite panels, loaded well into the postbuckling range under compression or shear so that data could be obtained to fill the gaps in the current technology related to postbuckled aircraft structures. In order to define a cos: -effective test matrix for the program, the most crucial data requirements were identified from the technology assessment of Section 2. These data gaps are summarized in Table 3.1 and were used in selecting the test matrix. Selection of the test specimen configuration, and the design criteria was based on the geometric and loading conditions encountered in actual aircraft fuselage construction. Design of the test specimens is detailed in Section 3.2.

A detailed rationale for the selected test matrix and the scope of the tests is given in Section 3.3. The other significant aspects of the experimental program such as fabrication of the test specimens, the test fixture and instrumentation used, and the test procedure are described in Section 3.4 through 3.6. The test data obtained are summarized in Section 3.7.

3.2 DESIGN OF CURVED TEST PANELS

Aircraft fuselage structural panels are rarely, if ever, of constant curvature. Typical military aircraft fuselage structures range approximately between 6 and 20 feet in diameter. Stiffened panels used in constructing : large diameter fuselage have relatively mild curvatures, and flat panels can generally be used to simulate their behavior. Fuselage panels in fighter aircraft have considerably smaller radii of curvature. In order to duplicate the behavior of such panels and to evaluate the effect of curvature on postbuckling behavior, panels with relatively small radii of curvature must be tested. The panels selected for the present test program fall in this latter category and have a radius of 45 inches. This radius of curvature was selected since it is representative of small diameter fuselage panels and to enable demonstration of the most significant differences between the behavior of flat and curved postbuckled panels. The results obtained

TABLE 3.1. DATA GAPS IN THE CURRENT TECHNOLOGY FOR DESIGN AND LIFE ANALYSIS OF CURVED POSTBUCKLED PANELS

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	DATA (1 SAPS	
MATERIAL AND LOADING	STATIC ANALYSIS Validation	FATIGUE FAILURE MODE AND S-N RESPONSE	REMARKS
METAL COMPRESSION PANELS	<pre>R/t_w ratio dependence of skin buckling load Skin buckle pattern progression with load Skin and stringer strain distribution Load to out-oi-plene displacement relation</pre>	 Failure mode Load vs. fatigue life curves Skin and stringer strain pattern correlation with S-N data Stiffness change with repeated loading 	 No fatigue data avail- able for curved metal compression panels. Static strain distribu- tion data useful in verifying non-empirical analysis
COMPOSITE COM- PRESSION PANELS	Stiffener crippling strain Stiffener/web sepøra- tion strain Skin buckle pattern progression with load Boundary conditions and skin dimensions for cdiculation	• Fatigue failure modes • Additional strain-life data to establish en- durance limit	 Jemi-empirical static failure prediction methodology needs to be verified Force fatigue failures to uncover any possible modes other than stiff- ener/web separation
METAL SHEAR PANELS	Skin and stringer strain distribution in post- huckled regime Forced crippling load for stiffeners Fajlure mode identification Permanent set criterion	 Failure mode Load vs. fatigue life curves Skin and stiffener Strain pcttern corre- lation with S-N data Stiffness change with repeated loading 	 Fatigue data not avail- able Static strain distribu- tion useful for non- empirical analysis veri- fication Tension field theory ap- plication
COMPOSITE SHEAR PANELS	Skin dimensions and boundary conditions for c _{cr} calculations Failure mode identi- fication Forced crippling strains for stiffeners Skin and stringer strain distribution	 Failure mode Load vs. fatigue life curves Skin and sciffener strain distribution; correlation with S-N data 	 Fatigue data not avail- able Applicability of modi- fied tension field theory to curved com- posite panels needs verification

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will be directly applicable to a large number of future aircraft. In addition, the metal and composite panels are designed to satisfy the same design criteria so that their relative efficiencies can be compared.

The design of metal and composite shear and compression panels, and the design criteria are described in this section. The analysis methodology used for this purpose has been detailed in Section 2. The resulting panel configurations were used in the test program.

3.2.1 Design Criteria

The typical compression and shear loads acting on an aircraft fuselage panel can have a relatively wide range of values depending upon the panel location and the type of aircraft. However, panels allowed to buckle are generally lightly loaded and thus the loading range is significantly narrowed. A limit load intensity range of 300 to 800 pounds per inch for shear and compression panels can accommodate a large number of fighter as well as larger aircraft. Recent studies conducted under Navy sponsorship have concentrated on a limit load intensity of 400 pounds per inch. In order to extend the range of currently available experimental data, the panel configurations selected for this program were designed for a limit load intensity of 600 pounds per inch. The panels are designed to buckle at approximately 30 percent of the limit load and to withstand ultimate load (1.5 times design limit load) without rupture or collapse. The design loads for the metal and composite panels are summarized in Table 3.2.

Material Selection

The composite shear and compression panels were fabricated using a combination of woven and unidirectional graphite/epoxy materials. The woven graphite/epoxy material selected was Hercules A370-5H/3501-6, whereas Hercules AS/3501-6 graphite/epoxy tape was used for the unidirectional material. These material systems are representative of the composite materials currently being used in fighter aircraft structures. The mechanical properties of these materials are summarized in Table 3.3.

The metal panels were fabricated using rolled aluminum sheet and extruded stringers. The alloy used was 7075 with a T6 heat treatment. The

DESIGN LOADS	COMPRESSION PANELS N _x , Ibs/in	SHEAR PANELS N _{xy} , Ibs/in
SKIN BUCKLING LOAD, N _{cr}	200	200
DESIGN LIMIT LOAD, DLL	600	600
DESIGN ULTIMATE LOAD, DUL	900	900

TABLE 3.2. DESIGN LOADS FOR METAL AND COMPOSITE TEST PANELS

TABLE 3.3. GRAPHITE/EPOXY MATERIAL PROPERTIES

PROPERTY	AS/3501-6	A370-5H/3501-6 (FABRIC)
E ^C 1, psi	18.7 x 10 ⁶	10.0 x 10 ⁶
E ^C 2, psi	1.87 x 10 ⁶	9.2 × 10 ⁶
G ₁₂ , psi	0.85 x 10 ⁶	0.9 x 10 ⁶
ν ₁₂	0.3	0.055

properties for this material were obtained from MIL-HDBK-5.

3.2.2 Curved Shear Panel Design

A flow chart summarizing the design procedure for curved composite and metal shear panels is shown in Figure 3.1. The design loads for the shear panels are given in Table 3.2. A frame spacing (h_r) of 24 inches was selected for the shear panels since it is representative of actual fuselage structures. The stiffener configuration selection was based on consideration of structural efficiency, manufacturing feasibility and cost (for composites), and current design practice.

In several recent studies hat section stringers have been chosen for composite shear panels because of their superior efficiency. Design application and fabrication studies have shown that, due to their higher torsional stiffness as compared to open sections, hat stiffened panels can be efficiently accommodated in fuselage construction. Thus, a hat section stringer configuration was selected for the composite shear panels. The frame configuration selected was a J-section since it is relatively easy to fabricate, while at the same time providing ease of attachment to other substructure.

For the metal shear panels, Z-section stringers and frames were selected since they offer the best cost and efficiency advantages as demonstrated by their widespread use in many existing aircraft.

The overall shear panel configuration selected consists of three stringers and two frames (rings). Sizing of the composite and metal panels to meet the design criteria was carried out as follows:

- a. Determine the optimum stringer spacing, and web configuration to satisfy design buckling loads.
- b. Size stringers and frames to accommodate ultimate panel load.

Details of the procedure used are given in the following paragraphs.



Figure 3.1 Shear Panel Design Procedure.

Composite Shear Panel

Two possible web configurations $(45_2, 90, 45_2)$ and (45, 0, 90, 0, 45), which are efficient in the range of design loads being considered, were studied to determine their initial buckling loads. The first configuration consists of four fabric plies and one unidirectional tape ply and has a nominal thickness of 0.0572 inch. The second configuration consists of two fabric plies and three unidirectional tape plies and is 0.0416 inch thick. The second ply skin configuration barely exceeds the minimum gage that is permitted in sound design practice.

The next step in the design procedure was to determine the skin buckling load as a function of skin thickness (t_w) and the stiffener spacing (h_s) in order to permit a judicious selection of values for these two parameters. For this purpose a buckling parameter λ , equal to the ratio of the calculated buckling load and the design buckling load, was defined. The buckling load was calculated using computer code SS8 (Reference 45) and the previously selected frame spacing of 24 inches.

Plots of buckling parameter " λ " for the two web configurations for different widths are presented in Figures 3.2 and 3.3. These plots were obtained clamped and simply supported for boundary conditions as illustrated in the two figures. The cylindrically curved edges for both cases were clamped. In a stiffened panel the exact boundary conditions are not known and it is common practice to assume that the conditions are intermediate between the two above boundary conditions to determine the buckling load of the panel web between the stiffeners. Thus, the stiffener spacing for the two panel configurations to satisfy the design buckling requirements should be 10 and 5.25 inches, respectively.

The panel web configuration with a $(45_2, 90, 45_2)$ lay-up and with the larger stiffener spacing is much more desirable than the Figure 3.3 configuration, since it will result in substantial manufacturing cost and weight savings and, therefore, was selected for use in this program.

In order to size the stringers and the frames, tension field theory as applicable to composite panels was used. Details of the tension field theory



Figure 3.2 Buckling Load of a Curved Graphite-Epoxy Plate $(\underbrace{45}_{2}, 90, \underbrace{45}_{2})$ Under Shear Loading.



Figure 3.3 Buckling Load of a Curved Graphite/Epoxy Plate Under Shear Loading. (45/90/0/90/45) Layup.

with an accompanying summary flow chart are given in Section 2 (Refer to Figure 2.13). The iterative design procedure was implemented via computer program TENWEB (Section 2 and Reference 91). The program run used to size these test penels is given in Reference 91, Section 3, as Figure 5. The resulting panel design shown in Figure 3.4. The calculated design values and failure modes are summarized in Table 3.4. The panel edges have been increased in thickness to preclude any failures due to load introduction. As mentioned before, the hat section stringers and J-section frames have been used primarily due to their efficiency and lower fabrication costs.

Metal Shear Panel

The design of the metal shear panel proceeded exactly along the same lines as that of the composite shear panel described above. The frame and stringer spacing were selected to be the same as for the composite panel $(h_r = 24", h_s = 10")$, the web thickness $t_w = 0.063"$ was calculated using Figure 3.5 (Reference 34) as necessary to prevent buckling below design buckling load.

The stringers and the frames were sized using computer code TEN-WE3 (Reference 91). The resulting panel configuration is shown in Figure 3.6. The fastemer spacing was calculated so as to preclude inter-fastemer buckling (Reference 34) and to prevent bearing failure near the fastener holes. HYLOK fasteners were used instead of rivets to reduce fabrication costs. In order to use fluch rivers on thin skin (0.063") the skin has to be dimpled, whereas the use of HYLOK fasteners does not necessitate skin dimpling. It should be noted that the canel edges were not initially reinforced since the web thickness is sufficiently large to prevent any static failure due to load introduction. The computer output for the metal shear panel design is included in Appendix A for reference purposes. The additional check required for metal panels where yielding or permanent set in the web is likely due to excessive skin deformation, was performed using Equation 31. The predicted failure mode for the metal panel configuration shown in Figure 3.6 was permanent set in the web. The calculated design values and the failure load predictions for the metal shear panel are summarized in Table 3.4,

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Figure 3.4 Composite Shear Panel Design.

SUMMARY
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TABLE 3.

L COMPOSITE PANEL	29,40	SET FORCED CRIPPLING	OF STRINGER 4.5	1.31 LB.
METAL PANE	36.90	PERMANENT :	IN WEB 2.6	2,84 LB
CALCULATED PARAMETER	DIAGONAL TENSION ANGLE, a	FAILURE MODE	TULT	.cr Panel weight



Figure 3.5 Shear Buckling Coefficient for Long Simply Supported Curved Plates (Reference 04).



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Figure 3.6 Metal Shear Panel Configuration. Stringers are AND10138-1206 and Frames are AND10138-1306 Aluminum Z-Sections.

3.2.3 Curved Compression Panel Design

Design of the curved composite and metal compression panels was carried out in accordance with the flowchart shown in Figure 3.7. It is worthwhile to mention here that a curved compression panel can be used to simulate the behavior of a cylindrical built-up fuselage structure provided the cylindrically curved panel is of sufficient width and the appropriate boundary conditions are used. Guidelines for determining the panel width and appropriate boundary conditions, so that the panel buckling load will equal the buckling load of a cylinder loaded in axial compression, have been presented by Sobel and Agarwal (Reference 92). It was shown that a panel enclosed by an angle which is greater than 100 degrees results in a buckling load equal to the complete cylinder load for any arbitrary boundary conditions along the straight edges. At the same time, a panel which is enclosed by less than 20 degrees results in a much higher buckling load than a complete cylinder. A panel enclosed by 30 degrees is able to model a complete cylinder if the appropriate boundary conditions are used along the straight edges, namely SS1 (w = M = N = N = 0), SS3 (w = M = u = N = 0) or CC1 (w = \emptyset = $N_y = N_{xy} = 0$). A combination of boundary conditions SS1, SS3, and CC1 can be obtained if one stringer is located at each side of the panel. Thus, for the test program, a cylindrically curved panel enclosed by at least a 30degree angle with one stiffener at each side was used to simulate the complete cylinder behavior.

Selection of the stringer configuration for the composite panels was based on an experimental and analytical evaluation of several flat compression panels with different stiffener configurations conducted in Reference 44. Figure 3.8 taken from Reference 44 shows that hat stiffeners are the most efficient stiffeners for axially loaded panels (all panels assumed to be buckling resistant). Although the panels in the present program were subjected to loads beyond buckling, the stiffeners carry a major portion of the load in the postbuckling range and, therefore, the efficiency comparison shown in Figure 3.8 should be equally applicable. Thus, hat section stiffener configuration was selected for the composite compression panels. Z-section stiffeners were selected for the metal compression panels due to their



Figure 3.7. Compression Panel Design Procedure



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Figure 3.8 Compression Load Structural Efficiency Comparison for Hat-, J-, and Blade Configurations.

widespread use in current design practice. The frame spacing for the compression panels was selected as 20 inches based on the typical spacing of 15-20 inches used in stringer stiffened fuselage shells, and to allow for skin buckling and stiffener crippling at loads reasonably close to the design loads.

A four stiffener, 3-bay configuration was selected for the compression panels based on test data developed in Reference 93, where panels tested with two or three stiffeners resulted in poor agreement with analytical solutions due to distortion of edge stiffeners. However, panels tested with four stiffeners resulted in good agreement with the analytical solutions. The reason for the good correlation in the latter case was that the distortion of the edge stiffeners did not affect the panel center bay.

Design calculations for the composite and metal compression panels are summarized in the following paragraphs.

Composite Compression Panel

In selecting the web configuration, design and test studies conducted in References 30 and 31 were used for guidance. In the referenced studies the stiffeners were spaced relatively close together and the panel web was quite thin with a (\pm 45, \mp 45) lay-up. In the present program the panel web was made slightly thicker and the stiffener spacing was increased to lower manufacturing costs and improve panel efficiency. A skin lay-up of [45/0/90/0/45] with a nominal thickness equal to .0416 inch was selected in conjunction with a stiffener spacing of 12.2 inches to meet the design load requirement for skin buckling. The end bays of the four stiffener, 3-bay compression panel were made narrower to preclude early failure in the end bays while at the same time the end bay width was sufficient to ensure skin buckling at loads much lower than the failure load.

The initial buckling load and the Euler buckling load of the composite curved panels were obtained through the use of computer code BUCLASP-2 (Reference 41). Since it is easier to work with strain for composite panels, the following discussion makes extensive use of strain rather than stress.

The buckling strains obtained from the computer code BUCLASP-2 were reduced by 25 percent to accommodate lower buckling strains due to imperfection effects, a common practice for metal panels. However, the percent knockdown is dependent on several design parameters which are not defined for composite panels; therefore, for an initial design estimate, the guidelines for metal panels given in Reference 34 (see also Figure 2.7) were used.

The crippling strain (ε_{cc}) is obtained using Equations 5 through 9 and the failure load calculated using Equations 11 through 14. The total load on the panel at stiffener crippling is the sum of the loads carried by the stiffeners and the web. In order to obtain the load in the web the effective width method was used. Equation 13A given in Section 2 was used to obtain the effective width.

Detailed design calculations for the composite compression panel were conducted using computer code CRIP, a sample run for which is included in Reference 91, Section 1, as Figure 3. The panel configuration obtained using the above approach is shown in Figure 3.9. A summary of the initial buckling and final failure strain predictions for the test specimen is shown in Table 3.5.

Metal Compression Panel

The metal panel configuration selected for preliminary design was of the following geometry:

Stiffener spacing	b =	10 inches
Web thickness	t _w =	0.05 inch
Panel length	L =	20 inches

The local buckling stress for the center bay web between stiffeners was calculated using the equations given in Reference 34. In accordance with Reference 34, the buckling stress F_{cr} for a curved sheet in compression with simply supported boundary conditions is obtained as

$$F_{cr} = \frac{K_c \pi^2 E}{12(1-v^2)} \left(\frac{t_w}{b_s}\right)^2$$

where $K_c = 13$ (from Figure 2.6)

... F_{cr} = 3143 psi



SUMMARY
DESIGN
PANEL
COMPRESSION
ND METAL
COMPOSITE A
TABLE 3.5.

CALCULATED PARAMETER	METAL PANEL	COMPOSITE PANEL
INITIAL BUCKLING		
-LOAD, N_{x}^{2} lb/in	206	1
-STRAIN, µin/in	9	870
FAILURE		
-LOAD, N ^F lb/in	1050	8
STRAIN, µin/in	ł	4956
FAILURE MODE	STIFFENER CRIPPLING	
POSTBUCKLING RATIO	5.1	5.7

The design buckling load ($N_{x,cr}$), however, = 200 lb/in. Hence the stiffener area (A_{s}) required is obtained as follows:

$$A_{s} = \frac{N_{x,cr}b_{s}}{F_{cr}} - b_{s}t_{w}$$
$$A_{s} = .1363 \text{ inch}^{2}$$

Assume the stiffener configuration to be AND 10138-1004 which is shown in Figure 3.10. Thus, the predicted panel buckling load $N_{xy,cr} = 206$ lb/in which results in a 3 percent margin of safety.

Failure analysis of the panel was carried out in accordance with the procedure outlined in Section 2. Figure 2.6 was used to calculate the crippling stress F_{CS} for the stiffener and yielded:

$$F_{cs} = 48.9$$
 ksi

The effective web width at the time of stiffener crippling, w, was calculated from Equation 13A as:

w = 1.2 inch

The total load at panel failure P_{ult} is calculated using Equation (14) which yields:

$$P_{ult} = F_{cs} (A_s + wt_w)$$

= 48900 (.155 + 1.2 x .05)
$$P_{ult} = 10500 \text{ lb.}$$

Hence, the ultimate failure load per unit width $(N_{x_{ult}})$ is

$$N_{x_{ult}} = \frac{P_{ult}}{b_a} = 1050 \text{ lb/in}$$

Thus, the panel failure load allows approximately a 15 percent margin of safety.



stiffener area A = 0.155 sq. inch
stiffener M.O.I. I = 0.0236 inch⁴

Figure 3.10 2-Section 7075-T6 Aluminum Stringer. AND 10138-1004 Configuration. For overall panel instability the Euler buckling stress was calculated using Equation 3 in the following form:

$$\sigma_{\text{Euler}} = \frac{\pi^2 \text{ EI}_{\text{e}}}{L_{\text{e}}^2 A_{\text{t}}}$$

where, L_e is the effective length of the panel, A_t is the total area of the panel and I_e is the panel moment of inertia about the neutral axis. Since the frame spacing for design purposes was assumed to be 20 inches, the effective length "L" for Euler buckling is 10 inches (C = 4 in Equation 3) assuming fully fixed ends. Thus, the calculated Euler buckling stress for the panel was:

$$T_{Euler} = 90.63 \text{ ksi}$$

The actual Euler buckling stress will be lower than the value above due to eccentricity effects and yielding, but it is still well in excess of the panel crippling load. Thus, the panel design meets all the required design criteria.

A sketch of the resulting metal compression panel configuration is shown in Figure 3.11. The fastener pitch and other related details shown were obtained to prevent inter-fastener buckling and failures near fastener holes (Reference 34).

3.3 TEST PLAN

The selection of a cost-effective and suitable test matrix for the program was made after a review of the gaps in the current technology that are summarized in Table 3.1.

The principle objectives of the curved panel tests were to generate static test data for analysis methodology verification and to conduct fatigue tests for failure mode identification and development of fatigue analysis procedures. One key concern addressed in the program is the fatigue response of curved metal panels. In addition, previous studies have indicated that metal shear panels cannot survive constant amplitude fatigue test at maximum loads much higher than approximately 50 percent of their static


ultimate strength. Test data show that composite compression panels, on the other hand, can endure maximum fatigue load amplitudes as high as 70 percent of their static ultimate strength without any strength degradation. However, since fatigue data on composite compression and shear panels are sparse, additional fatigue tests on these panels were required. A greater emphasis was placed on curved shear panels in this program due to their anticipated sensitivity to fatigue loading. Static tests on the curved panels were conducted to obtain skin buckling strains, sriffener crippling strains, skin and stiffener strains at stiffener/web separation, and the strain distribution in the panels as a function of the applied load. These data were icquired for comparison with predictions made using the semiempirical analysis and the strain distribution in particular for comparison with the non-empirical Rayleigh-Ritz analysis procedure developed in the program. Additional details of the test program are given in the following paragraphs.

3.3.1 Test Matrix

The program test matrix is shown in Table 3.6. As indicated in the table, a total of 26 panels were tested in the program. Four sets of panels were tested to obtain the initial buckling load, postbuckling behavior, ultimate failure load, and mode of failure. The four sets consisted of: aluminum compression, aluminum shear, graphite/epoxy compression, and graphite/ epoxy shear panels. All tests were conducted in a room temperature dry (RTD) environment. A greater emphasis is placed on shear panel fatigue tests since fatigue data for curved composite shear panels are not available and those for metal panels are limited in quantity. Each test condition was replicated twice to demonstrate the repeatability of the test and to obtain more reliable test data for analysis verification.

The constant amplitude fatigue tests on compression panels were conducted at an R-ratio $(\sigma_{\min}/\sigma_{\max})$ of 10 with the maximum fatigue load set at 66 percent of the static strength for the first metal panel test and at 70 percent of the static strength for the first composite panel. Selection of the maximum fatigue loads for the subsequent tests was made on the basis of the measured panel response for the first set of tests and the need to obtain a definition of the S-N curve for the panels.

TABLE 3.6. COMPRESSION AND SHEAR PANEL TEST MATRIX

PANEL. IDENTIFICATION	MATERIAL/ LOADING	TYPE	R-RATIO	MAXIMUM FATIGUE LOAD AMPLITUDE % STATIC STRENGTH	CONSTANT A STRAIN SUX 0	MPLITUDE VEYS AT, 50K	FATIGUE N CYCLES 100K
MC1* MC2* MC3 MC4 IC5**	Aluminum Panel/ Compression Loading	Static Static Fatigue Fatigue Fatigue	1 1 0 0 1		>>>	>> >	>> >
cc1* cc2* cc3 cc4 cc5 cc6	Composite Panel/ Compression Loading	Static Static Fatigue Fatigue Fatigue Fatigue			>>>>	>> >>	>>>>
MS1 MS2 MS3 MS4 MS5 MS6	Aluminum Panel/ Shear Loading	Static Static Fatigue Fatigue Fatigue Fatigue	110000		>>>>	>>>>	>>>>
CS1 CS2 CS3 CS3 CS4 CS3 CS5 CS5 CS5 CS5 CS5 CS5 CS5 CS5 CS5 CS5	Composite Panel/ Shear Loading	Static Static Fatigue Fatigue Fatigue Fatigue Fatigue Fatigue		00222200	>>>>>>>>	>>>>>>>>	>>>>>>>>>>>>>>>>>>>>>>>>>>>>>>>>>>>>>
*Out-0	of-plane displacen	nents measured	by LVDT's	 **Panel tested as 	part of Nor	throp IRA	e.

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The aluminum shear panel fatigue tests were also conducted under constant amplitude loading with R = 0. The fatigue load amplitudes selected for these tests were 55 percent and 45 percent of the average static ultimate strength for similar panels. In the case of the composite shear panels the fatigue tests were conducted at R = 0.25 and R = -0.25, with the latter R-ratio allowing for partial reversal of the shear loading. The fatigue load amplitudes for the composite shear panels were higher than those used for the aluminum panels (70 percent and 60 percent of the average static strength for the panels) due to their much superior fatigue response.

The test panel instrumentation consisted mainly of strain gages and in some select cases of displacement transducers. A more complete description of the instrumentation is given in paragraph 3.3.2. It is noted here, however, that prior to and periodically during the course of the fatigue tests, strain surveys up to the maximum fatigue load were conducted on all fatigue test panels. As indicated in Table 3.1, the intermediate strain surveys during the fatigue tests were conducted at 50,000 and 100,000 cycles.

3.3.2 Instrumentation

All panels in the test program were instrumented with strain gages. The static compression test panels were instrumented with LVDT's in addition to the strain gages so that out of plane displacements could be monitored during the course of the tests. Figure 3.12 shows the layout of the strain gages and the locations of the out-of-plane displacement transducers for the compression panels. In this figure the gage layout for the less extensively instrumented compression fatigue panels is also shown. The strain gage layout for the static and fatigue tested shear panels is shown in Figure 3.13. As noted in Figures 3.12 and 3.13, all gages were located back-to-back on the convex and the concave surfaces of the panels in order to determine bending as well as membrane strains due to postbuckling deformations.

In all static tests, a visual indication of the out-of-plane displacements in the postbuckling regime was obtained by means of the Moire' grid technique. For this purpose the composite specimens were painted white and a Moire' grid placed within 0.25 inch of the specimen surface in the case of both metal and composite panels to obtain the fringes associated with the



- AXIAL GAGE
- DISPLACEMENT TRANSDUCER

ALL GAGES BACK-TO-BACK

- Static Test panels MC1, MC2, CC1, and CC2 were instrumented as shown. i. NOTE:
- Fatigue test panels MC3, CC3, and CC4 were instrumented with gages ① through ⑧ only. Fatigue test panels MC4, CC5, and CC6 were instrumented with gages ① through ⑧ only. 2.
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Figure 3.12 Compression Panel Instrumentation.

A. A. A. A.



buckle pattern.

During the course of the fatigue tests some of the strain gages were damaged due to fatigue, thus causing loss of some data. However, a majority of the strain gages were not affected and valid data were obtained at the 50,000 cycle and 100,000 cycle strain surveys. The gages that survived and the detailed nomenclature are noted in Appendix A along with the test data.

3.3.3 <u>Test Fixture</u>

The static and fatigue tests on the compression panels were conducted in a 100,000 pound capacity Tinius Olsen test machine. The panel ends were potted in an epoxy compound for load introduction. A full view of the test setup, including the Kaye data acquisition system, is shown in the photograph of Figure 3.14. A close-up view of a composite compression panel in the test machine with full instrumentation is shown in Figure 3.15.

The test fixture used for curved shear panel tests is a fixture designed and developed at Northrop under Independent Research and Development funds. This fixture results in the application of extremely uniform shear stress in the panel with no adverse stresses. The loading mechanism and the test fixture are schematically illustrated in Figure 3.16. A view of the test fixture with a metal panel installed for testing is shown in the photograph of Figure 3.17. The glossy appearance of the specimen is due to the Moire' grid which has been positioned close to the specimen surface.

The curved panel is enclosed by two flat dummy panels making up a triangular tube. The two flat panels are considered part of the test fixture and are connected at a point midway between the test panel center of curvature and the test panel. One end of the tube is clamped against all degrees of freedom. The other end is connected to the loading frame plate. Loading frame support plates are slotted to allow free rotation of the loading frame shaft about the tube centroid. The shear load is applied by a torque introduced by two load cylinders moving in opposite directions. The two torque application cylinders are each of 50,000 pound capacity and the torque arm is 74.0 inches. Operation of the test fixture was verified using an aluminum panel which was tested to failure. The fixture design permits



Figure 3.14. Test Setup for Compression Panels





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Figure 3.16. Shear Panel Test Fixture Schematic



Figure 3.17. View of Test Fixture Showing Loading Arrangement and Test Panel.

testing of curved panels in a wide range of sizes and curvatures with minimal alterations.

3.4 FABRICATION OF COMPOSITE TEST PANELS

Special testing and curing fixtures were designed and built to fabricate the composite shear and compression panels. The tooling for the shear panels was more complex due to the curvature of the J-section frames. For the shear panels a steel template formed to a 45-inch radius was used to lay up the skin. The template was marked to indicate the peripheral net trim area; stringer, frame and doubler (edge as well as under the stiffener) locations. An orientation rosette was also marked on the template to ensure angular accuracy of the various plies.

The stiffeners were shaped and fabricated using Dow Corning Silastic-J RTU rubber mandrels. The mandrels themselves were cast in sheet metal molds with the frame mandrel molds designed to allow for opening and shifting of hat cavities when the mandrel is bent into a 45-inch radius after being cast straight. After cure of the frame mandrel, slots were cut into it to allow for expansion of the rubber. The cauls for the stringers were fabricated using two plies of graphite/epoxy sandwiched between two layers of Air-Tech's Airpad black rubber. These cauls were in three pieces of which two were used on the short stringer ends outside of the frames (Refer to Figure 3.4) whereas the third one was used for the portion of a stringer between the frames. The cauls on the stiffeners extended to the surface of the frames and were tapered to prevent excessive mark-off. This kept the hat stiffeners straight, and prevented them from rolling, bowing and distorting during cure. Fiberglass cauls were fabricated for the top of the J-section frames. These kept the frames circumferentially straight, and eliminated wrinkles in the cap of the frame. Figure 3.18 shows the stringer and curved frame mandrels in place on the skin template. The graphite-epoxy cauls used to compact the stringers are also shown in the figure. The cuts in the frame mandrels to accommodate the hat section stringers are illustrated in Figure 3.19 which shows a photograph of the partially laid-up frame mandrel.



Figure 3.18. Intermediate Step-in Composite Shear Panel Fabrication Illustrating Frame and Stringer Mandrels Located on Skin Template



The panel. Drication procedure consisted of laying up the skin and the stringers separately on a flat template and then locating the preformed stringers onto the skin. The subassembly was debulked under vacuum for 30 minutes, then placed on the curved steel template used as the curing fixture and taped in place to avoid movement in subsequent operations. The frames were laid up on their mandrels and located over the subassembly in the curing fixture. The stringer cauls were then installed, followed by installation of the frame cauls. The panel assembled up to this stage is illustrated in Figure 3.20. This assembly was then covered with bleeder and breather plies as required and bagged for cure. The panel was cured and postcured in accordance with Northrop specification MA-133. The cured composite shear panel is shown in Figure 3.21.

Fabrication of the composite compression panel was considerably simpler due to the absence of the curved frames. The procedure followed in fabricating these four stringer panels (Refer to Figure 3.9) was identical to that used for the shear panels up to the stringer/skin subassembly stage. The finished composite compression panel is shown in Figure 3.22. The panels then are potted for compression load application.

The composite compression and shear panels were nondestructively inspected by means of ultrasonic C-scan to ensure defect-free panels.

3.5 TEST RESULTS

3.5.1 <u>Compression Panel Static Tests</u>

The composite and metal compression panel static test results are summarized in Table 3.7. The metal compression panels MC1 and MC2 failed due to stiffener crippling. Web buckling and inter-rivet buckling was observed in some areas prior to failure. These static test results are compared against predictions in Section 5. Development and progression of the buckle pattern for the metal panels is illustrated in Figure 3.23a through e where Moire grid pattern photographs for panel MC1 are shown. Just beyond the initial buckling load the web is seen to have buckled in two half waves along the load axis as well as across the width. This pattern becomes more easily visible as the load is increased further. However,



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Figure 3.20. Shear Panel Assembly Prior to Cure

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Figure 3.21. Cured Composite Shear Panel

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TABLE 3.7. COMPOSITE AND METAL COMPRESSION PANEL STATIC TEST RESULTS

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REMARKS	Panels failed due to stiffener crippling as predicted. See Section 4 for discus- sion of results.	Panels failed due to stiffemer/web separation.
FAILURE	42.0	84.6
LOAD, KIPS	43.6	82.0
BUCKLING	12.0	18.0
LOAD, KIPS	14.0	16.0
PANEL	NC2	CC1
NUMBER*	WC3	CC2

*Prefix M in panel number denotes metal panel and prefix C denotes graphite/epoxy panel.



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(a) Load - 0 lb



(b) Load = 16K 1b

Figure 3.23. Progression of Buckle Pattern with Load for Metal Compression Panel MCl



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(c) Load = 25K 1b



(d) Load = 30K 1b

Figure 3.23. Progression of Buckle Pattern with Load for Metal Compression Panel MCl (Continued)



(e) Load = 35K 1b

Figure 3.23. Progression of Buckle Pattern with Load for Metal Compression Panel MCl (Concluded) between 25,000 and 30,000 lbs the pattern changes to one-half wave across the width of the panel which remains unchanged to failure. A photograph illustrating the final failure mode of the panel by stiffener crippling is shown in Figure 3.24. Strain data for the two metal panels are given in Appendix A and were used to determine the buckling loads given in Table 3.8.

The composite compression panels CCl and CC2 failed by stiffener/ web separation. Final failure was abrupt and resulted in the separation of all stiffeners from the skin and in secondary rupture of all stiffeners. Development and progression of the buckle pattern in panel CCl is shown in Figure 3.25a through f. Panel CC2 also displayed the same buckle pattern. The strain data given in Appendix A were used to determine the panel buckling loads. The failure mode for these panels is illustrated in Figure 3.26.

3.5.2 Compression Panel Fatigue Tests

The metal and composite compression panel fatigue tests were conducted at an R-ratio of 10. The test data are summarized in Table 3.8. Metal panel MC3 tested under constant amplitude loading with the maximum fatigue load set at 61 percent of the average static strength, developed sizeable cracks (~2.5 in) after 16,000 cycles. The cracks in the skin were parallel to the stiffener and appeared to be caused by the web bending against the stiffener. Unlike the failure mode shown in Figure 2.2 for flat compression panels, the skin cracks in the curved panel were located along the stiffener edge away from the fasteners.

Panel MC4 tested at a load amplitude equal to 51 percent of the average static strength also developed cracks in the skin along the stiffeners at 43,000 cycles. The panel, however, retained its fatigue load carrying capacity to 100,000 cycles. The initial 2.5-inch crack grew to 4.75 inches in the last 57,000 cycles. The panel was statically tested for residual strength but did not show an appreciable loss in strength. The statically failed panel with the initial fatigue cracks marked is shown in Figure 3.27.



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(a) Skin Rupture



(a) Stiffener Crippling

Figure 3.24. Failed Metal Compression Panel MC1

TABLE 3.8. COMPOSITE AND METAL COMPRESSION PANEL FATIGUE TEST RESULTS, R = 10

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	REMARKS	Fatigue crack in skin. Parallel and adjacent to stiffener.	5-in Fatigue Crack in skin parallel to stiffener.	Stringer edge in contact with skin, founded to prevent knife edging of skin. 5-in crack in skin at run-out.	Failure due to	stiftener/web separation.	After-first 100K cycles 1cad increased to 65% of static strength	After first 100K cycles load increased to 65% of static strength.	
AT N,	100K	1	×	3	1	1	X*	X	
AIN VEYS LES	50K	T	X	I	×	1	×	×	
STR SUR CYC	0	×	×	ł	×	×	×	×	
RESIDUAL STRENGTH, KIPS		1	40.8	4.11	ŧ	ł	84.5	I	
FATIGUE LIFE, N CYCLES		16,430	100,000*∵	100,000R	61,640	12,758	100,000R 100,000	100,000R 5,900	
MAXIMUM FATIGUE LOAD, % AVG.	S TATIC S TRENGTH	1 9	51	51	70		60 65	60 65	
MAXIMUM FATIGUE LOAD,	KIPS	26.0	22.0	22.0	58.1	58.1	8.64	8.94	
SKIN BUCKLING LGADS,	KIPS	10.0	12.0	13.0	14.0	12.0	12.0	16.0	
PANEL NO. +		MC3	MC4	101	cc3	cc4	cc5	cce	

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Additional strain surveys at 150K and 200K cycles. R denotes run-out. ++ Panel tested under Northrop IRAD Prefix M in panel number denotes metal panel and prefix C denotes graphite/epoxy level.

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(a) Load = 14K 1b



(b) Load = 18K 1b

Figure 3.25. Progression of Buckle Pattern with Load for Composite Compression Panel CCl



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(c) Load = 25K lb



(d) Load = 35K 1b

Figure 3.25. Progression of Buckle Pattern with Load for Composite Compression Panel CCl (Continued)



(e) Load = 60K 1b



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(f) Load = 80K 1b

Figure 3.25. Progression of Buckle Pattern with Load for Composite Compression Panel CCl (Concluded)



(a) Stiffener/Web Separation and Failure



(b) Skin Failure

Figure 3.26. Composite Compression Panel CCl Failure Mode

A curved metal compression panel with rounded stiffener edges (IC1) was fatigue-tested under constant amplitude loading with R = 10 and at a load amplitude equal to 51 percent of the ultimate static strength. Panel IC1 was tested under Northrop's IRAD program to determine if rounding of stiffener edges is effective in improving the panel fatigue life. The stiffener edges were rounded to eliminate crack initiation adjacent to the stiffeners due to web bending against sharp stiffener edges which was observed during fatigue tests on panels MC3 and MC4. The rounded stiffener edges were effective in eliminating crack initiation at the two center stiffeners. Crack initiation at one of the edge stiffeners, however, occurred after approximately the same number of cycles (40,000) as in the case of panels MC3 and MC4 although the initial crack length was smaller (.15 inch versus 2.5 inches). Panel IC1 completed 100,000 cycles of fatigue loading without catast ophic failure. During these 100,000 cycles, the crack at the edge stiffener grow to a length of 4.75 inches. The panel was residual strength-tested and failed by stiffener crippling at 41,000 lbs. showing no reduction from the ultimate static strength. An additional observation from these tests was that just prior to failure, a sizeable crack did appear at one of the center stiffeners indicating that rounded stiffener edges were effective in reducing the web bending stresses and thus, delaying crack initiation.

Curved composite panels CC3 and CC4 were tested in fatigue with the maximum load set at 70% of the average static strength determined from panels CC1 and CC2. The panels failed due to separation of the stiffeners from the skin after 61,640 and 12,758 cycles, respectively. In the case of panel CC3 a single stiffener separated whereas for panel CC4 the damage was more extensive and resulted in the failure of three stiffeners. Panels CC5 and CC6 were fatigue-tested at 60 percent of the average static strength and both survived the first 100,000 cycles of fatigue. The load was subsequently increased to 65 percent of the static strength and the fatigue test continued. Panel CC5 survived an additional 100,000 cycles at this load without any significant loss in residual strength. Panel CC6, however, failed after approximately 6,000 cycles at the increased load. The results for panels CC3 through CC6 are discussed in Section 4.

3.5.3 Shear Panel Static Tests

The test results for curved metal and composite shear panels are summarized in Table 3.9. The load values shown in the table are the loads applied by the torque/cylinder. Metal panel static failure was due to permanent buckling of the web. The failur: load was well above the design ultimate and the panel was able to sustain loads higher than the loads at which permanent set in the web occurred. The diagonal buckle pattern representative of out-of-plane skin displacements for the metal shear panels is shown in Figure 3.28.

The composite shear panels CS1 and CS2 failed at nearly identical loads by stiffener web separation. Panel CS1 failed at a torque cylinder load of 16,000 lbs. A photograph of the failed panel is shown in Figure 3-29 with a close-up view of the failure area shown in Figure 3.30. The buckle pattern for composite shear panels was similar to that shown in Figure 3.28.

Due to the nature of the test set up for the shear panels direct measurement of the shear flow N_{xy} in the test area is not possible. The cross-sectional area of the torque box cannot be directly measured due to the presence of attachment hardware at the corners. In addition, friction inherent in the test arrangement means that all the applied torque is not converted to shear flow in the test panel. Hence, the first metal shear panel static test was used to calibrate the applied torque to panel shear flow relationship. Since the properties of 7075-T6 aluminum are well established, this calibration can be carried out by plotting the measured shear strain in the panel web prior to web buckling versus the applied torque as shown in Figure 3.31. Using this plot, the calibration proceeds as follows:

$$N_{xy} = \frac{T}{2A} = \frac{74 P_T}{2A} = G\gamma_{xy}t$$

where, T is the applied torque, A the cross-sectional area of the torque tube, P_T the applied cylinder load, the torque arm is 74 inches, t is skin thickness and γ_{xy} is the measured shear strain in the web. From the above equation

$$A = \frac{1}{2G \gamma_{xy} t}$$

TABLE 3.9. COMPOSITE AND METAL SHEAR PANEL STATIC TEST RESULTS

PANEL NUMBER*	BUCKLING LAD, LBS	FAILURE LOAD, LBS	REMARKS
			i i i soomenent set in skin
15M	3820	22800	Panel failed one to permanent out
1 (2)	4123	14600	Panel failed due to permanent set in skin
MSZ			
	4497	15760	Panels failed due to stiffener web
4 0 0 0	4492	16500	separation.
100			
			c instant arother enoxy panel.

50 * Prefix M in panel number denotes metal panel and prefix C denotes



Figure 3.27. Fatigue Cracks in Metal Compression Panel MC4









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1 , Figure 3.30. Close-Up of Composite Shear Panel Failure by Stiffener/Web Separation


or, using the data shown in Figure 3.31,

$$A = \frac{1}{2Gt} \quad \frac{\Delta T}{\Delta \gamma}$$

Thus the cross-sectional area was determined from Figure 3.31 to be 462 in². This fields the following conversion from cylinder load to panel shear flow

$$N_{xy} = 0.08 P_{T}$$

where, N_{xy} is in 1b/in and P_T in 1b. The strain data for all statically tested shear panels is given in Appendix A.

3.5.4 Shear Panel Fatigue Tests

The shear panel fatigue test data are summarized in Table 3.10. Metal panels MS3 and MS4 were tested at a maximum fatigue load equal to 80 percent of the design ultimate strength since the wide scatter in the static strength of MS1 and MS2 made it difficult to define a meaningful average static strength.

In panel MS3 test the bolt in the corner of the test bay failed after 7,200 cycles. Fatigue cracks grew soon after the fastener failure in the panel web adjacent to the corner hole as well as at the corner hole. The panel failed due to web rupture after 8,700 cycles. The rupture was caused by cracks which grew normal to the direction of diagonal tension.

In panel MS4 the corner fastemer which failed during the specimen MS3 tests was replaced by a higher strength fastemer. Panel MS4 sustained 12,500 cycles before any cracks were visible. The first crack appeared in the stringer near the intersection of the frames, where significant stringer bending was observed. The crack was located in the stiffener heel and ran along the length. A second crack developed in the panel web due to bending of the web after 14,800 cycles. The location of this crack was at the point where the buckles stop in the diagonal tension corner. This crack resulted in panel failure after additional 1200 cycles. TABLE 3.10. COMPOSITE AND METAL SHEAR PANEL FATIGUE TEST RESULTS

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REMARKS		Cracks at stiff- ener attach fas- tener holes led- to failure by web rupture.				Stiffener/web separation mode of failure.							
RAIN SURVEY, N CYCLES	100K	ł	1	1	E a	×+	xt	+-	+	+	+-	+-	+
	50K	1	1	l	ł	+-	x+	xt	+-	+	+-	+	+-
ST	0	×	x	x	×	×	X	X	X	X	Х	×	×
RESIDUAL STRENGTH	KIPS	8			8	15.2	16.8				14.5	15.8	
FATIGUE LIFE	N CYCLES	8,698	16,578	51,975	28,789	100,000 ^{**}	100,000R	62 , 000	19,351	8,737	100,000R	100,000R	69,100
WM FATIGUE LOAD % AVC STATIC	STRENCTH	54	54	43	43	60	60	69	69	60	60	69	69
MAXIM KIPS		10.0	10.0	8.0	8.0	9.7	9.7	11.3	11.3	9.7	9.7	11.3	11.3
R-RATIO		0	0	0	0	-0.25	-0.25	-0.25	-0.25	0.25	0.25	0.25	0.25
BUCKLING LOAD, LB		4453	3848	2894	3811	3970	3533	3945	3897	3461	3993	4434	3476
PANEL NO. *		WS3	WS4	MS5	9SM	CS3	CS4	CS5	cs6	cs7	CS8	cs9	CS10

* Prefix M in panel number denotes metal panel and prefix C denotes graphite/epoxy panel. ** R denotes run out. • Significant number of gages damaged due to fatigue.

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Another crack was observed after 15,000 cycles along the stiffener edge similar to the cracks in the compression panels. Complete web rupture occurred at about 16,600 cycles.

Metal shear panels MS5 and MS6 were subjected to constant amplitude fatigue with R = 0 and at a maximum fatigue load equal to 45 percent of the average static strength obtained from static tests on panels MS1 and MS2. The absolute fatigue shear load amplitude was 8,000 lbs. as compared with 10,000 lbs. for panels MS3 and MS4. The edges of panels MS5 and MS6 were thickened by means of an externally (convex side) bonded aluminum doubler to facilitate load introduction and avoid premature cracking of the web at the panel corners. Addition of the doubler did not affect the panel response as manifested by the initial buckling loads of 2,894 lbs. and 3,811 lbs. for panels MS5 and MS6, respectively. As shown in Table 3.10 these buckling loads are in the same range as those for panels MS1 through MS4 where bonded edge doublers were not used.

Panels MS5 and MS6 showed very similar modes of failure although there was some scatter in their fatigue life. In panel MS5, web cracks were first observed at 37,000 cycles parallel to the mid-bay longitudinal stiffener and transverse to the tension field at the vertical frame fastemer holes as illustrated in Figure 3.32. Final failure of panel MS5 occurred by web rupture due to propagation of a dominant crack in a direction transverse to the tension field after 52,000 cycles. The dominant crack initiated in the lower bay and propagated across the second bay as shown in Figure 3.32. Fatigue cracks in panel MS6 were first observed at 22,000 cycles and final rupture of the web occurred at 29,000 cycles.

Panels CS3 and CS4 were tested under constant amplitude fatigue load_ng (R=-0.25). The maximum fatigue load was set equal to 60% of the static ultimate failure load. The panels completed 100,000 cycles of fatigue loading without any detectable damage. The panels failed at loads of 15,200 and 16,400 lbs., respectively, during the residual strength test. The failure load and mode of failure were almost identical to the static tests.



The maximum load amplitude for panels CS5 and CS6 was increased to 70% of the static ultimate load. Panels were loaded under constant amplitude fatigue loading (R = -0.25). Both panels failed during fatigue after 72,000 cycles and 19,500 cycles, respectively. The failures were sudden and not detected during the inspection periods which were set to 10,000 cycles. Thus the time of damage initiation to final failure was quite rapid. The fatigue failures at such high load magnitudes are to be expected and the data continue to demonstrate excellent durability of composite shear panels.

Panel CS7 was subjected to constant amplitude fatigue loading (R = +0.25). No load reversal for this panel was chosen. The maximum load amplitude was set at 70 percent of the static ultimate load. The panel developed stiffener/web separation over a 0.5-inch length after 7,000 cycles. This disband grew rapidly resulting in total panel failure after 8,700 cycles. The slightly lower life with less severe fatigue loading points towards a weakly-bonded region at the stiffener/skin interface.

Panel CLA was tested at a fatigue load amplitude equal to 70% of the average static strength measured for similar panels. The panel survived 100,000 cycles of fatigue loading without any detectable damage. The residual strength of panel CS8 was 14,500 lbs. which is 10% lower than the average static strength. The failure mode of the panel was identical to that seen in the static tests and was by separation at the stringer/web interface. This test was identical in all respects to that conducted on panel CS7.

The fatigue test results for the two panels show significant scatter although the failure modes are identical. However, the reason for this scatter can be deduced from the observation that panel CS7 developed stiffener/web separation very early in the fatigue test at approximately 7,000 cycles and thereafter this disbond propagated very rapidly. In the case of panel CS8, no such stiffener/web separation was observed even after 100,000 cycles. This suggests that in panel CS7 a flaw in the form of a

void or incomplete resin cure at the stiffener/web interface was inadvertently introduced during fabrication and was the direct cause of the reduced fatigue life.

The last set of curved composite shear panels (CS9 and CS10) were also tested under constant amplitude fatigue loading at an R-ratio of 0.25. The fatigue load amplitude for these two panels, however, was 60% of the average static strength for similar panels. Panel CS9 completed 100,000 cycles of fatigue and survived. The residual strength of this panel was not significantly reduced from the average static strength. Panel CS10 failed by stiffener/web separation after 69,100 cycles of fatigue. The scatter in the fatigue test results for these two panels is suspected to be due to variability in fabrication of the panels.

The significance of the test results presented in this section is discussed in Section 4.

SECTION 4

DEVELOPMENT OF ANALYSIS METHODS

4.1 INTRODUCTION

The semiempirical analysis of postbuckled panels presented in Section 2 was done in steps due to the complexity of the solution process. These analyses, although useful for design purposes, do not yield the stress and displacement fields required for a fatigue analysis of the panels. Furthermore, with the semiempirical analyses, the complex mechanisms of load transfer before and after buckling such as the interaction forces between the stiffeners and the web, and the effect of stiffness changes in the postbuckling range, cannot be modelled. Most of these analysis methods were developed before the advent of high-speed computers and result in designs that are conservative by as much as 50 percent. The current technology aud recent advances in computation methods make it feasible to model all significant aspects of postbuckled panels in a single analysis with increased accuracy, thereby reducing the conservatism in the final design. Thus, development of such an analysis to accurately predict the postbuckling behavior of the panel as a whole, including the web and the stiffeners, was undertaken.

It was envisioned that the analysis methodology would be used as a design tool. Therefore, ease of application and low computational costs were prime considerations in its development. Based on the survey of nonemple cal static analysis methods presented in Section 2, the total postbuckling behavior of stiffened panels loaded in compression or in shear was modelled using the principle of minimum potential energy. The analysis methodology for each loading case is generic in that it applies to curved, flat, metal and composite panels. Details of the analysis for compression and shear panels are discussed in the following paragraphs.

4.2 COMPRESSION PANEL ANALYSIS

The governing equations in this formulation were derived for orthotropic laminates that are balanced and symmetric. It is assumed that

the webs between adjacent stringers deform in an identical fashion. The analysis is also applicable to isotropic materials provided the appropriate constitutive relations are used.

4.2.1 Geometry and Boundary Conditions

The relationship between the compression panel configuration tested in the program and the panel geometry used in the analysis is shown in Figure 4.1. Since adjacent bays are assumed to deform in an identical fashion, a single bay was analyzed. As shown in Figure 4.1, one curved edge of the panel is assumed to be fixed with compression load applied to the other curved edge At the loaded edge, due to the presence of the stiff frames, the displacement in the Z-direction (w) is restricted to zero and no displacement is permitted in the Y-direction (v = 0 at this edge). The latter boundary condition is a realistic representation of the edge conditious in panels under pure compression. The stringer deformations determine the boundary conditions at the straight edges of the panel. The stringers are assumed to be initially straight and deformation relative to the mid-surface of the panel in the Z-direction (w) occurs only due to stiffener crippling or Euler buckling of the panel which results in catastrophic failure. The u, and v displacements at the straight edges are not restricted.

4.2.2 Strain Energy Expressions

The analysis employs the principle of minimum potential energy. The method is ideally suited for this analysis since it simplifies the handling of discrete stiffeners and imposition of the boundary conditions.

According to the principle of minimum potential energy, a solution of the present problem renders the total potential a relative minimum. The total potential energy, Π , is the sum of the strain energy stored in the web, U_w , in the stringers, U_g , in the frame, U_f , and the potential of the external load, Ω , i.e.

$$\Pi = U_{\perp} + U_{\mu} + U_{\mu} + \Omega \tag{32}$$



In applying the principle of minimum potential energy, the first step is to assume kinematically admissible displacement functions with unknown coefficients. These displacement functions are selected to satisfy the geometric boundary conditions. The total potential energy is computed next as a function of the unknown coefficients. The governing equations are then obtained in terms of the unknown coefficients by minimizing the total potential energy with respect to these coefficients. Finally, the set of non-linear equations obtained by minimization of the total potential energy are numerically solved to determine the displacement coefficients.

The strain energy stored in the skin and the stiffeners can be expressed in terms of the assumed displacements u, v and w using nonlinear strain-displacement relations for curved laminates as:

Strain Energy of the Skin:

$$U_{w} = \frac{ab}{2} \left[\int_{0}^{1} \int_{0}^{1} A_{11}^{*} \left(\frac{1}{a^{2}} u_{j}^{2} + \frac{1}{4a^{4}} w_{j}^{4} + \frac{1}{a^{3}} u_{j} w_{j}^{2} \right) d\xi d\eta \right]$$

$$+ \int_{0}^{1} \int_{0}^{1} A_{12}^{*} \left(\frac{2}{ab} u_{j} v_{j} + \frac{1}{ab^{2}} u_{j} w_{j}^{2} + \frac{1}{a^{2}b} v_{j} w_{j}^{2} \right) d\xi d\eta$$

$$+ \int_{0}^{1} \int_{0}^{1} A_{22}^{*} \left(\frac{1}{b^{2}} v_{j}^{2} + \frac{1}{ab^{4}} w_{j}^{4} + \frac{2}{Ra} w_{j} + \frac{1}{a^{2}R} w_{j}^{2} \right) d\xi d\eta$$

$$+ \int_{0}^{1} \int_{0}^{1} A_{22}^{*} \left(\frac{1}{b^{2}} v_{j}^{2} + \frac{1}{4b^{4}} w_{j}^{4} + \frac{w^{2}}{R^{2}} + \frac{2}{Rb} w_{j} + \frac{1}{b^{3}} v_{j} w_{j}^{2} \right) d\xi d\eta$$

$$+ \frac{w}{b^{2}R} w_{j}^{2} \right) d\xi d\eta$$

$$+ \int_{0}^{1} \int_{0}^{1} A_{66}^{*} \left(\frac{1}{b^{2}} u_{j}^{2} + \frac{1}{a^{2}} v_{j}^{2} + \frac{1}{a^{2}b^{2}} w_{j}^{2} w_{j}^{2} + \frac{2}{ab} u_{j} v_{j} + \frac{2}{ab} u_{j} v_{j} + cont' d.$$

$$+ \frac{2}{ab^{2}} u_{,\eta}^{w}_{,\xi}^{w}_{,\eta}^{v}_{,\eta}^{+} \frac{2}{ab^{2}} v_{,\eta}^{w}_{,\xi}^{w}_{,\eta}^{,\eta} \right) d\xi d\eta$$

$$+ \int_{0}^{1} \int_{0}^{1} \left(\frac{1}{a^{4}} D_{11}^{\star} w_{,\xi\xi}^{2} + \frac{2}{a^{2}b^{2}} D_{12}^{\star} w_{,\xi\xi}^{w}_{,\eta\eta}^{,\eta}_{,\eta\eta}^{+} + \frac{4}{a^{3}b} D_{16}^{\star} w_{,\xi\xi}^{w}_{,\xi\eta}^{,\eta}_{,\eta\eta}^{,\eta}_{,\xi\xi}^{,\eta}_{,\eta\eta}^{,\eta}_{,\xi\eta}^{,\eta}_{,\eta}^{,\eta}_{,\xi\eta}^{,\eta}_{,\eta}^{,\eta}_{,\xi\eta}^{,\eta}_{,\xi\eta}^{,\eta}_{,\eta}^{,\eta}_{,\xi\eta}^{,\eta}_{,\eta}^{,\eta}_{,\eta}^{,\eta}_{,\xi\eta}^{,\eta}_{,\eta}^{,\eta$$

where, ξ and η are normalized variables as shown in Figure 4.1, and u, v and w are displacements in the x, y and z directions, respectively. A_{ij}^{*} are the elements of the laminate axial stiffness matrix and D_{ij}^{*} are the elements of the flexural stiffness matrix. Commas denote differentiation with respect to the subscripted variables. The strain energy due to shear and stretching coupling is ignored since the laminate is balanced and symmetric about the midplane, i.e., $A_{16} = A_{26} = 0$.

Strain energy in the stringer:

$$U_{\rm S} = \frac{A_{\rm S}E_{\rm S}}{2a} \int_0^1 u_{\xi}^2(\xi,0) \ d\xi + \frac{I_{\rm S}E_{\rm S}}{2a^3} \int_0^1 v_{\xi\xi}^2(\xi,0) \ d\xi \qquad (34)$$

where, A_s is the cross-sectional area of the stringer, E_s is the modulus and I_s is the equivalent moment of inertia of the stringer about the z-axis.

Strain energy in the frames:

$$U_{f} = \frac{A_{f}E_{f}}{2b} \int_{0}^{1} v_{\eta}^{2}(1,\eta) d\eta + \frac{I_{f}E_{f}}{2b^{3}} \int_{0}^{1} u_{\eta\eta}^{2}(1,\eta) d\eta \qquad (35)$$

where, A_f is the cross-sectional area of the frame, E_f is the average modulus and I_f is the equivalent moment of inertia of the frame about the z-axis.

The potential of the external load is expressed as:

$$\Omega = -\lambda \overline{P} \int_{\Omega}^{1} u(1, \eta) d\eta$$
 (36)

where, \bar{P} is a reference load and λ is an unknown load control parameter.

4.2.3 Governing Equations

The governing equations are obtained by substituting a set of assumed displacement functions with unknown coefficients into the expressions for the total potential Π and then minimizing it with respect to the unknown coefficients. As discussed in Section 4.2.1, the boundary conditions that the assumed displacement functions must satisfy are:

$$u(x,o) \neq 0 v(x,o) \neq 0 w(x,o) = 0$$

$$u(x,b) \neq 0 v(x,b) \neq 0 w(x,b) = 0$$

$$u(o,y) = 0 v(o,y) \neq 0 w(o,y) = 0$$

$$u(a,y) \neq 0 v(a,y) \neq 0 w(a,y) = 0$$
(37)

where, u(x,y), v(x,y) and w(x,y) are the displacements in the x, y and z directions, respectively. The stiffeners along the straight edges are restricted to in-plane deformations.

The admissible displacement functions for the compression panel were assumed in the following form:

 $u(\xi,\eta) = A_{nm} \phi_{n}^{c} \Psi_{m}^{c} (1-\phi_{1}^{c}) + a_{1}a\xi$

$$v(\xi,\eta) = B \phi_{nm}^{S} \Psi^{C} + b_{1}b_{\eta}$$

$$w(\xi,\eta) = C_{nm} \phi_{n}^{S} \Psi_{m}^{S} \left\{ \begin{array}{l} m = 1, ..., M \\ n = 1, ..., N \end{array} \right\}$$
(38)

where,

$$\phi_n^c = \cos n\pi\xi \qquad \Psi_m^c = \cos n\pi\eta$$

$$\phi_n^s = \sin n\pi\xi \qquad \Psi_m^s = \sin n\pi\eta$$

and

$$x = a\xi$$
 $y = b\eta$

The total potential energy for the compression panels takes the form:

$$\Pi = \Pi(A_{ij}, B_{ij}, C_{ij}, a_1, b_1, \lambda)$$
(39)

Using the indicial notation where summation over repeated indices is implied, the total potential energy can be written as follows:

$$\Pi = \frac{ab}{2} \left[\left\{ \frac{A_{11}^{\star}}{a^2} \left(A_{nm} A_{pq} F_{1nmpq}^{11} + 2A_{nm} a_{1}a F_{2nm}^{11} + a_{1}^2 a^2 \right) \right. \\ \left. + \frac{A_{11}^{\star}}{4a^4} C_{10m} C_{pq} C_{rs} C_{tu} F_{1nmpqrstu}^{12} \right. \\ \left. + \frac{A_{11}^{\star}}{a^3} \left(A_{nm} C_{pq} C_{rs} F_{1nmpqrs}^{13} + a_{1} C_{pq} C_{rs} a F_{2pqrs}^{13} \right) \right. \\ \left. + \frac{2A_{12}^{\star}}{ab} \left(A_{nm} B_{pq} F_{1nmpq}^{21} + A_{nm} b_{1}b F_{2nm}^{21} + a_{1}B_{pq} a F_{3pq}^{21} \right. \\ \left. + a_{1}b_{1}ab \right) \right. \\ \left. + \frac{A_{12}^{\star}}{ab^2} \left(A_{nm} C_{pq} C_{rs} F_{1nmpqrs}^{22} + a_{1} C_{pq} C_{rs} a F_{2pqrs}^{22} \right) \right. \\ \left. + \frac{A_{12}^{\star}}{ab^2} \left(B_{nm} C_{pq} C_{rs} F_{1nmpqrs}^{22} + a_{1} C_{pq} C_{rs} a F_{2pqrs}^{22} \right) \right. \\ \left. + \frac{A_{12}^{\star}}{a^2b} \left(B_{nm} C_{pq} C_{rs} F_{1nmpqrs}^{23} + b_{1} C_{pq} C_{rs} b F_{2pqrs}^{23} \right) \right. \\ \left. + \frac{A_{12}^{\star}}{2a^2b^2} C_{nm} C_{pq} C_{rs} C_{tu} F_{1nmpqrstu}^{24} \right]$$

$$+ \frac{2A_{12}^{*}}{Ra} (C_{nm} A_{pq} F_{1nmpq}^{25} + a_{1} C_{nm} a F_{2nm}^{25}) \\ + \frac{A_{12}^{*}}{a^{2}R} C_{nm} C_{pq} C_{rs} F_{1nmpqrs}^{26} \\ + \frac{A_{22}^{*}}{b^{2}} (B_{nm} B_{pq} F_{1nmpq}^{31} + 2B_{nmb} b_{1} b F_{2nm}^{31} + b_{1}^{2} b^{2}) \\ + \frac{A_{22}^{*}}{b^{2}} (C_{nm} C_{pq} C_{rs} C_{tu} F_{1nmpqrstu}^{32} + \frac{2A_{22}^{*}}{Rb} C_{nm} C_{pq} F_{1nmpq}^{34} \\ + \frac{A_{22}^{*}}{b^{2}} C_{nm} C_{pq} C_{rs} C_{tu} F_{1nmpqrstu}^{32} + \frac{2A_{22}^{*}}{Rb} C_{nm} C_{pq} F_{1nmpq}^{34} \\ + \frac{A_{22}^{*}}{b^{2}} C_{nm} C_{pq} C_{rs} F_{1nmpqrstu}^{35} + b_{1} C_{pq} C_{rs} b F_{2pqrs}^{35}) \\ + \frac{A_{22}^{*}}{b^{2}} C_{nm} C_{pq} C_{rs} F_{1nmpqrs}^{36} + b_{1} C_{pq} C_{rs} b F_{2pqrs}^{35}) \\ + \frac{A_{22}^{*}}{b^{2}} C_{nm} C_{pq} C_{rs} F_{1nmpqrs}^{36} + b_{1} C_{pq} C_{rs} b F_{2pqrs}^{35}) \\ + \frac{A_{22}^{*}}{b^{2}} C_{nm} C_{pq} C_{rs} F_{1nmpqrs}^{36} + b_{1} C_{pq} C_{rs} b F_{2pqrs}^{35}) \\ + \frac{A_{22}^{*}}{b^{2}} B_{nm} B_{pq} C_{rs} F_{1nmpqrs}^{36} + b_{1} C_{pq} C_{rs} c_{tu} F_{1nmpq}^{41} \\ + \frac{A_{66}^{*}}{a^{2}} B_{nm} B_{pq} F_{1nmpq}^{42} + \frac{A_{66}^{*}}{a^{2}b^{2}} C_{nm} C_{pq} C_{rs} C_{tu} F_{1nmpqrstu}^{24} \\ + \frac{2A_{66}^{*}}{a^{2}} B_{nm} B_{pq} F_{1nmpq}^{44} + \frac{2A_{66}^{*}}{a^{b}^{2}} A_{nm} C_{pq} C_{rs} F_{1nmpqrs}^{45} \\ + \frac{2A_{66}^{*}}{a^{2}} B_{nm} C_{pq} C_{rs} F_{1nmpqrs}^{46} + \frac{2A_{66}^{*}}{a^{b}^{2}} A_{nm} C_{pq} C_{rs} F_{1nmpqrs}^{45} \\ + \frac{2A_{66}^{*}}{a^{2}} B_{nm} C_{pq} C_{rs} F_{1nmpq}^{46} + \frac{2A_{66}^{*}}{a^{b}^{2}} A_{nm} C_{pq} C_{rs} F_{1nmpqrs}^{45} \\ + \frac{2A_{66}^{*}}{a^{2}} B_{nm} C_{pq} C_{rs} F_{1nmpqrs}^{46} + \frac{2A_{66}^{*}}{a^{b}^{2}} C_{nm} C_{pq} F_{1nmpqrs}^{51} \\ + \frac{2A_{66}^{*}}{a^{2}} C_{nm} C_{pq} C_{rs} F_{1nmpq}^{46} + \frac{2A_{66}^{*}}{a^{2}} C_{nm} C_{pq} F_{1nmpq}^{51} \\ + \frac{2A_{66}^{*}}{a^{2}} C_{nm} C_{pq} C_{rs} F_{1nmpq}^{46} + \frac{2A_{66}^{*}}{a^{2}} C_{nm} C_{pq} F_{1nmpq}^{51} \\ + \frac{2A_{66}^{*}}{a^{2}} C_{nm} C_{pq} C_{rs} F_{1nmpq}^{46} + \frac{2A_{66}^{*}}{a^{2}} C_{nm} C_{pq} F_{1nmpq}^{51} \\ + \frac{2A_{66}^{*}}{a^{2}} C_{m} C_{pq} C_{pq} F_{1$$

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$$+ \frac{p_{22}^{*}}{b^{4}} c_{nn} c_{pq} F_{1nmpq}^{54} + \frac{4D_{26}^{*}}{b^{3}a} c_{nm} c_{pq} F_{1nmpq}^{55}$$

$$+ \frac{4D_{66}^{*}}{a^{2}b^{2}} c_{nm} c_{pq} F_{1nmpq}^{56} \}$$

$$+ \left\{ \frac{2A_{s}E_{s}}{a^{2}b} (A_{nm} A_{pq} F_{1nmpq}^{51} + 2A_{nm} a_{1}a F_{2nm}^{51} + a_{1}^{2}a^{2}) + \frac{2I_{s}E_{s}S}{a^{4}b} B_{nm} B_{pq} F_{1nmpq}^{52} \right\}$$

$$+ \frac{A_{f}E_{f}}{ab^{2}} (B_{nm} B_{pq} \dot{F}_{1nmpq}^{52} + 2B_{nm} b_{1}b F_{2nm}^{51} + b_{1}^{2}b^{2})$$

$$+ \frac{I_{f}E_{f}h_{f}}{ab^{4}} A_{nm} A_{pq} F_{1nmpq}^{52} - 2a_{1}N_{xx} \end{bmatrix} (40)$$

where,

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A _{ij}	×	in-plane stiffness matrix
D* 11	=	bending stiffness matrix
E	=	axial modulus for the stringer
As	=	cross-sectional area of the stringer
I _s	=	equivalent moment of inertia of the stringer about the z-axis
E _f	8	axial modulus for the frame
A _f	=	cross-sectional area of the frame
^I f	=	equivalent moment of inertia of the frame about the z-axis
N _{xx}	æ	applied load (lbs/in)-



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The conditions for obtaining the values of the coefficients that minimize the total potential energy, II, are

$$\frac{\partial \Pi}{\partial A_{ij}} = 0, \quad \frac{\partial \Pi}{\partial B_{ij}} = 0, \quad \frac{\partial \Pi}{\partial C_{ij}} = 0, \quad \frac{\partial \Pi}{\partial a_1} = 0, \quad \frac{\partial \Pi}{\partial b_1} = 0. \tag{41}$$

After performing the differentiation operation, the following five nonlinear simultaneous equations are obtained:

$$\frac{\partial \Pi}{\partial A_{ij}} = \frac{2A_{11}^{*}}{a^{2}} (A_{nm} F_{1ijnm}^{11} + a_{1}a F_{2ij}^{11} + \frac{1}{2a} C_{am} C_{pq} F_{1ijnmpq}^{13}) + \frac{2A_{12}^{2}}{ab} (B_{nm} F_{1ijnm}^{21} + b_{1}b F_{2ij}^{21} + \frac{1}{2b} C_{nm} C_{pq} F_{1ijnmpq}^{22} + \frac{b}{R} C_{nm} F_{1nmij}^{25}) + \frac{2A_{66}^{*}}{b^{2}} (A_{nm} F_{1ijnm}^{41} + \frac{b}{a} B_{nm} F_{1ijnm}^{44} + \frac{1}{a} C_{nm} C_{pq} F_{1ijnmpq}^{45}) + \frac{4E_{s}A_{s}}{a^{2}b} (A_{nm} F_{1ijnm}^{51} + a_{1}a F_{2ij}^{51}) + \frac{2I_{f}E_{f}}{ab^{4}} A_{nm} F_{1ijnm}^{45} = 0$$
(42)

$$\frac{\partial \Pi}{\partial B_{ij}} = \frac{2A_{12}^{*}}{ab} (A_{nm} F_{1nmij}^{21} + a_{1}a F_{3ij}^{21} + \frac{1}{2a} C_{nm} C_{pq} F_{1ijnmpq}^{23}) + \frac{2A_{22}^{*}}{b^{2}} (B_{nm} F_{1ijnm}^{31} + b_{1}b F_{2ij}^{31} + \frac{1}{2b} C_{nm} C_{pq} F_{1ijnmpq}^{35})$$

$$+\frac{A_{66}^{*}}{a^{2}} (B_{nm} F_{1ijnm}^{42} + \frac{a}{b} A_{nm} F_{1nmij}^{44} + \frac{1}{b} C_{nm} C_{pq} F_{1ijnmpq}^{46})$$

$$+\frac{4I_{s}E_{s}}{a^{4}b} B_{nm} F_{1ijnm}^{52} + \frac{2A_{f}E_{f}}{ab^{2}} (B_{nm} F_{1ijnm}^{F1} + b_{1}b F_{2ij}^{F1}) = 0$$
(43)

$$\frac{\partial \Pi}{\partial C_{ij}} = \frac{A_{11}^{*}}{a^{4}} (C_{nm} C_{pq} C_{rs} F_{1ijnmpqrs}^{12} + 2a A_{nm} C_{pq} F_{1nmijpq}^{13} + 2a^{2}a_{1} C_{nm} F_{2ijnm}^{13}) + 2a^{2}a_{1} C_{nm} F_{2ijnm}^{13}) + \frac{A_{12}^{*}}{ab} \left[\frac{2}{b} A_{nm} C_{pq} F_{1nmijpq}^{22} + \frac{2a}{b} a_{1} C_{nm} F_{2ijnm}^{22} + \frac{2}{a} B_{nm} C_{pq} F_{1nmijpq}^{23} + \frac{2b}{a} b_{1} C_{nm} F_{2ijnm}^{23} + \frac{1}{ab} C_{nm} C_{pq} C_{rs} (F_{1ijnmpqrs}^{24} + F_{1nmpqijrs}^{23}) + \frac{2b}{R} A_{nm} F_{1ijrm}^{25} + F_{1nmpqijrs}^{24}) + \frac{2b}{R} A_{nm} F_{1ijrm}^{25} + \frac{2ab}{R} a_{1} F_{2ij}^{25} + \frac{b}{R} c_{nm} C_{pq} (F_{1ijnmpq}^{26} + 2F_{1nmijpq}^{26}) \right]$$

$$\frac{A_{22}^{*}}{b^{4}} \left[C_{nm} C_{pq} C_{rs} F_{1ijnmpqrs}^{32} + \frac{2b^{4}}{R^{2}} C_{nm} F_{1ijnm}^{33} + \frac{2b^{3}}{R} C_{nm} (F_{1ijnm}^{34} + F_{1nmij}^{34}) + \frac{2b^{3}}{R} C_{nm} (F_{1ijnm}^{35} + F_{1nmij}^{36}) + 2b B_{nm} C_{pq} F_{1nmijpq}^{35} + 2b^{2}b_{1} C_{nm} F_{2ijnm}^{35} + 2b B_{nm} C_{pq} (F_{1njnpq}^{36} + 2F_{1nm^{3}jpq}^{36}) \right] + \frac{b^{2}}{R} C_{nm} C_{pq} (F_{1ijnmpqr}^{36} + 2F_{1nm^{3}jpq}^{36}) \right] + \frac{A_{66}^{*}}{a^{2}b^{2}} \left[C_{nm} C_{pq} C_{rs} (F_{1ijnmpqrs}^{24} + F_{1nmpqijrs}^{26}) + a A_{nm} C_{pq} (F_{1nmijpq}^{45} + F_{1nmpqij}^{45}) + b B_{nm} C_{pq} (F_{1nmijpq}^{46} + F_{1nmpqij}^{46}) \right] + b B_{nm} C_{pq} (F_{1nmijpq}^{46} + F_{1nmpqij}^{45}) + \frac{2D_{11}^{*}}{a^{4}} C_{nm} F_{1ijnm}^{51} + \frac{2D_{12}^{*}}{a^{2}b^{2}} C_{nm} (F_{1ijnm}^{52} + F_{1nmij}^{52}) + \frac{4D_{16}^{*}}{a^{3}b} C_{nm} (F_{1ijnm}^{53} + F_{1nmij}^{53}) + \frac{2D_{2}^{*}}{b^{4}} C_{nm} F_{1ijnm}^{54} + \frac{4D_{26}^{*}}{a^{3}} C_{nm} (F_{1ijnm}^{55} + F_{1nmij}^{55}) + \frac{8D_{66}^{*}}{a^{2}b^{2}} C_{nm} F_{1ijnm}^{54} = 0$$

$$(44)$$

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$$\frac{\partial \Pi}{\partial a_1} = \frac{A_{11}^*}{a^2} (2a A_{nm} F_{2nm}^{11} + 2a^2 a_1 + C_{nm} C_{pq} F_{2nmpq}^{13})$$

$$+ \frac{A_{12}}{ab} (2a \ B_{nm} \ F_{3nm}^{21} + 2b_{1}ab + \frac{a}{b} \ C_{nm} \ C_{pq} \ F_{2nmpq}^{22}$$

$$+ \frac{2ab}{R} \ C_{nm} \ F_{2nm}^{25})$$

$$+ \frac{4A_{s} \ E_{s}}{ab} \ (A_{nm} \ F_{2nm}^{51} + a_{1}a) - 2N_{xx} = 0$$
(45)

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$$\frac{\partial \Pi}{\partial b_{1}} = \frac{A_{12}^{\star}}{ab} (2b \text{ Anm } F_{2nm}^{21} + 2a_{1}ab + \frac{b}{a} C_{n14} C_{pq} F_{2nmpq}^{23}) + \frac{A_{22}^{\star}}{b^{2}} (2b B_{nm} F_{2nm}^{31} + 2b^{2}b_{1} + C_{15m} C_{pq} F_{2nmpq}^{35}) + \frac{2A_{f}E_{f}}{ab} (B_{nm} F_{2nm}^{F1} + b_{1}b) = 0$$
(46)

The governing equations are obtained by linearizing Equations 42 through 46 by first expressing the total potential energy as:

$$\Pi = \Pi \left(\mathbf{q}_{,\lambda} \right) \tag{47}$$

where q is the vector of the unknown coefficients. The equilibrium equations related to the stationary condition of the total potential energy are:

$$R_{i}(\underline{q};\lambda) \equiv \frac{\partial \Pi(\underline{q};\lambda)}{\partial q_{i}} = 0 \quad \& R_{i}(q_{j};\lambda) \equiv F_{i}(q_{j}) - \lambda \overline{P}_{i}$$
(48)

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The resulting equations are a system of nonlinear coupled algebraic equations. Linearization of these equations is required in order to ensure a systematic solution scheme. Expanding these equations about a known position vector q_0 and retaining the linear terms in the expansion, the following set of equations is obtained.

$$\frac{\partial R}{\partial q} \Delta q \div \frac{\partial R}{\partial \lambda} \Delta \lambda + R(q_0; \lambda_0) = 0$$
(49)

Defining $K = \frac{\partial R}{\partial q} = \frac{\partial F}{\partial q}$, the equation above becomes,

$$\underbrace{\mathsf{K}} \Delta q = \underbrace{\mathsf{P}} \Delta \lambda - \underbrace{\mathsf{R}} \left(\operatorname{q}_{0}, \lambda_{0} \right) \tag{50}$$

The matrix K is called the tangent stiffness matrix and it provides information about the stability of the structure. At the bifurcation point K becomes singular. R, F and F are called the residual internal and external load vectors, respectively. The full set of equations to be solved numerically then appear as follows:

$$\begin{bmatrix} \frac{\partial^{2} \Pi}{\partial A_{ij} \partial A_{kl}} & \frac{\partial^{2} \Pi}{\partial A_{ij} \partial B_{kl}} & \frac{\partial^{2} \Pi}{\partial A_{ij} \partial C_{kl}} & \frac{\partial^{2} \Pi}{\partial A_{ij} \partial a_{l}} & \frac{\partial^{2} \Pi}{\partial A_{ij} \partial b_{l}} \\ \frac{\partial^{2} \Pi}{\partial B_{ij} \partial A_{kl}} & \frac{\partial^{2} \Pi}{\partial B_{ij} \partial B_{kl}} & \frac{\partial^{2} \Pi}{\partial B_{ij} \partial C_{kl}} & \frac{\partial^{2} \Pi}{\partial B_{ij} \partial a_{l}} & \frac{\partial^{2} \Pi}{\partial B_{ij} \partial b_{l}} \\ \frac{\partial^{2} \Pi}{\partial C_{ij} \partial A_{kl}} & \frac{\partial^{2} \Pi}{\partial C_{ij} \partial B_{kl}} & \frac{\partial^{2} \Pi}{\partial C_{ij} \partial C_{kl}} & \frac{\partial^{2} \Pi}{\partial C_{ij} \partial a_{l}} & \frac{\partial^{2} \Pi}{\partial C_{ij} \partial a_{l}} & \frac{\partial^{2} \Pi}{\partial C_{ij} \partial a_{l}} & \frac{\partial^{2} \Pi}{\partial C_{ij} \partial b_{l}} \\ \frac{\partial^{2} \Pi}{\partial a_{l} \partial A_{kl}} & \frac{\partial^{2} \Pi}{\partial a_{l} \partial B_{kl}} & \frac{\partial^{2} \Pi}{\partial C_{ij} \partial C_{kl}} & \frac{\partial^{2} \Pi}{\partial C_{ij} \partial a_{l}} & \frac{\partial^{2} \Pi}{\partial a_{l} \partial a_{l}} & \frac{\partial^{2} \Pi}{\partial a_{l} \partial b_{l}} \\ \frac{\partial^{2} \Pi}{\partial a_{l} \partial A_{kl}} & \frac{\partial^{2} \Pi}{\partial a_{l} \partial B_{kl}} & \frac{\partial^{2} \Pi}{\partial a_{l} \partial C_{kl}} & \frac{\partial^{2} \Pi}{\partial a_{l} \partial a_{l}} & \frac{\partial^{2} \Pi}{\partial a_{l} \partial a_{l}} & \frac{\partial^{2} \Pi}{\partial a_{l} \partial b_{l}} \\ \frac{\partial^{2} \Pi}{\partial a_{l} \partial A_{kl}} & \frac{\partial^{2} \Pi}{\partial b_{l} \partial B_{kl}} & \frac{\partial^{2} \Pi}{\partial a_{l} \partial C_{kl}} & \frac{\partial^{2} \Pi}{\partial a_{l} \partial a_{l}} & \frac{\partial^{2} \Pi}{\partial a_{l} \partial a_{l}} & \frac{\partial^{2} \Pi}{\partial a_{l} \partial b_{l}} \\ \frac{\partial \Pi}{\partial a_{l} \partial b_{l}} \\ \frac{\partial \Pi}{\partial a_{l}} \\ \frac{\partial \Pi}{\partial a_{l}} \\ \frac{\partial \Pi}{\partial b_{l}} \\ \frac{\partial \Pi}{\partial b_$$

The submatrices of the global matrix in Equation 51 can be expressed as:

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$$\frac{\partial^2 R}{\partial A_{kl} \partial A_{ij}} = \frac{2A_{1l}^*}{a^2} F_{1ijkl}^{11} + \frac{2A_{66}^*}{b^2} F_{1ijkl}^{41} + \frac{4E_s A_s}{a^2 b} F_{1ijkl}^{S1} + \frac{2I_f E_f h_f}{a b^4} F_{1ijkl}^{F1}$$
(52)

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$$\frac{\partial^2 \Pi}{\partial B_{kl} \partial A_{ij}} = \frac{2}{ab} \left(A_{12}^* F_{1ijkl}^{21} + A_{66}^* F_{1ijkl}^{44} \right)$$
(53)

$$\frac{\partial^{2} \Pi}{\partial C_{kl} \partial A_{ij}} = \frac{2A_{11}^{\star}}{a^{3}} C_{nn} F_{1ijklnm}^{13} + \frac{2A_{12}^{\star}}{ab^{2}} C_{nm} F_{1ijklrm}^{22} + \frac{2A_{12}^{\star}}{AR} F_{1klij}^{25}$$

$$+ \frac{2A_{06}^{\star}}{ab^{2}} C_{nm} (F_{1ijklum}^{45} + F_{1ijnmkl}^{45})$$
(54)

$$\frac{\partial^2 \Pi}{\partial a_1 \partial A_{ij}} = \frac{2A_{11}^*}{a} F_{2ij}^{11} + \frac{4E_s A_s}{ab} F_{2ij}^{51}$$
(55)

$$\frac{\partial^2 \Pi}{\partial b_1 \partial A_{ij}} = \frac{2A_{12}^*}{a} F_{2ij}^{21}$$
(56)

$$\frac{\partial^2 r}{\partial A_{kl} \partial B_{ij}} = \left[\frac{\partial^2 r}{\partial B_{kl} \partial A_{ij}} \right]^T$$
(57)

$$\frac{\partial^{2} \Pi}{\partial B_{kl} \partial B_{ij}} = \frac{2A_{22}^{\star}}{b^{2}} F_{1ijkl}^{31} + \frac{2A_{66}^{\star}}{a^{2}} F_{1ijkl}^{42} + \frac{4I_{s}E_{b}h}{a^{4}b} F_{1ijkl}^{S2} + \frac{2A_{f}E_{f}}{ab^{2}} F_{1ijkl}^{F1}$$
(58)

$$\frac{\Im^{2}_{\Pi}}{\partial C_{kl}\partial B_{ij}} = \frac{2A_{12}^{*}}{2} C_{nm} F_{1ijklnm}^{23} + \frac{2A_{22}^{*}}{b^{3}} C_{nm} F_{1ijklnm}^{35} + \frac{2A_{66}^{*}}{a^{2}b} C_{nm} (F_{1ijklnm}^{46} + F_{1ijnmkl}^{46})$$
(59)

$$\frac{\partial^2 \Pi}{\partial a_1 \partial B_{\underline{1}\underline{j}}} = \frac{2A_{\underline{1}\underline{2}}^*}{b} F_{\underline{3}\underline{1}\underline{j}}^{\underline{2}\underline{1}}$$
(60)

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$$\frac{\partial^2 \Pi}{\partial b_1 \partial B_{ij}} = \frac{2A_{22}^*}{b} F_{2ij}^{31} + \frac{2A_f E_f}{ab} F_{2ij}^{51}$$
(61)

$$\frac{\partial^2 \Pi}{\partial A_{kl}^{\partial C}_{ij}} = \left[\frac{\partial^2 \Pi}{\partial C_{kl}^{\partial A}_{ij}} \right]^T$$
(52)

$$\frac{\partial^2 r}{\partial E_{\kappa 1} \partial C_{ij}} = \left[\frac{\partial^2 r}{\partial C_{\kappa 1} \partial B_{ij}} \right]^T$$
(63)

$$\frac{\partial^2 \pi}{\partial C_{kl} \partial C_{ij}} = \frac{A_{11}^{*}}{a} (3 C_{nm} C_{pq} F_{1ijkinmpq}^{12} + 2a A_{nm} F_{1nmijkl}^{13} + 2a^2 a_1 F_{2ijkl}^{13})$$

$$+ \frac{A_{12}^{\star}}{ab} \frac{2}{b} A_{nm} F_{1,nmijkl}^{22} + \frac{2a}{b} a_{1} F_{2ijkl}^{22} + \frac{2}{a} B_{nm} F_{1,nmijkl}^{23}$$

$$+ \frac{2b}{a} b_{1} F_{2ijkl}^{23} + \frac{1}{ab} C_{pm} C_{pq} (2F_{1ijnmklpq}^{24} + 2F_{1klnmijpq}^{24}$$

$$+ F_{1ijklnmpq}^{24} + F_{1nmpqijkl}^{24}) + \frac{2b}{ak} C_{nm} (F_{1ijklnm}^{26} + F_{1nmijkl}^{26})$$

$$+ \frac{A_{22}^{2}}{b^{4}} \quad \Im \ C_{nte} \ U_{pq} \ F_{1ijklnnkjq}^{32} + \frac{2b^{4}}{R} \ F_{1ijkl}^{33} + \frac{2b^{3}}{R} \ (F_{1ijkl}^{34} + F_{1klij}^{34}) + 2b \ E_{nm} \ F_{1umijkl}^{32} + 2b^{2}b_{1} \ F_{2ijkl}^{33} + \frac{2b^{3}}{R} \ (F_{1ijkln}^{34} + 2b^{2}b_{1} \ F_{2ijkl}^{33}) + 2b \ E_{nm} \ F_{1umijkl}^{32} + 2b^{2}b_{1} \ F_{2ijkl}^{33} + \frac{2b^{2}}{R} \ S_{nm} \ (F_{1ijklnm}^{36} + F_{1nmijkl}^{36} + F_{1klijnm}^{36}) + \frac{2b^{2}}{R} \ S_{nm} \ (F_{1ijklnm}^{36} + F_{1nmijkl}^{36} + F_{1klijnm}^{36}) + \frac{2A_{66}^{5}}{a^{2}b^{2}} \ C_{nm} \ C_{pq} \ (2F_{1ijnmklpq}^{24} + 2F_{1klnmijpq}^{24} + F_{1ijklnmpq}^{24})$$

$$+ F_{1nmpqijkl}^{24} + a A_{nm} (F_{1nmijkl}^{45} + F_{1nmklij}^{45}) + b B_{nm} (F_{1nmijkl}^{46} + F_{1nmklij}^{46}) + \frac{2D_{11}^{\star}}{a^{4}} F_{1ijkl}^{51} + \frac{2D_{12}^{\star}}{a^{2}b^{2}} + (F_{1ijkl}^{52} + F_{1klij}^{52}) + \frac{4D_{16}^{\star}}{a^{3}b} (F_{Fijkl}^{53}) + F_{1klij}^{53}) + \frac{2D_{22}^{\star}}{b^{4}} F_{1ijkl}^{54} + \frac{4D_{26}^{\star}}{ab^{3}} (F_{1ijkl}^{55} + F_{1klij}^{55}) + \frac{8D_{66}^{\star}}{a^{2}b^{2}} F_{1jkl}^{56}$$
(64)

$$\frac{\partial^2 \pi}{\partial a_1 \partial C_{ij}} = \frac{2A_{11}^*}{a^2} C_{nm} F_{2ijnm}^{13} + \frac{2A_{12}^*}{b^2} C_{nm} F_{2ijnm}^{22} + \frac{2A_{12}^*}{R} F_{2ij}^{25}$$
(65)

$$\frac{\partial^{2}\pi}{\partial b_{1}\partial C_{ij}} = \frac{2A_{12}^{*}}{a^{2}} C_{nm} F_{2ijnm}^{23} + \frac{2A_{22}^{*}}{b^{2}} C_{nm} F_{2ijnm}^{25} \in (66)$$

$$\frac{\partial^2 \Pi}{\partial A_{kl} \partial a_l} = \left[\frac{\partial^2 \Pi}{\partial a_l \partial A_{ij}} \right]^T$$
(67)

$$\frac{\partial^2 \Pi}{\partial B_{kl} \partial a_{l}} = \left[\frac{\partial^2 \Pi}{\partial a_{l} \partial B_{ij}} \right]^{T}$$
(68)

$$\frac{\partial^2 \Pi}{\partial C_{kl} \partial a_l} = \left[\frac{\partial^2 \Pi}{\partial a_l C_{ij}} \right]^T$$
(69)

$$\frac{\partial^2 \pi}{\partial a_1 \partial a_1} = 2A_{11}^{\star} + \frac{4A_s E_s}{b}$$
(70)

$$\frac{\partial^2 \Pi}{\partial b_1 \partial a_1} = 2A_{12}^{\star}$$
(71)

$$\frac{\partial^2 \Pi}{\partial A_{k,1} \partial b_1} = \left[\frac{\partial^2 \Pi}{\partial b_1 \partial A_{ij}} \right]^T$$
(72)

$$\frac{\partial^2 \Pi}{\partial B_{kl} \partial b_l} = \left[\frac{\partial^2 \Pi}{\partial b_l \partial B_{lj}} \right]^T$$
(73)

$$\frac{\partial^{2} \pi}{\partial C_{kl} \partial b_{l}} = \left[\frac{\partial^{2} \pi}{\partial b_{l} \partial C_{ij}} \right]^{T}$$
(74)

$$\frac{\partial^2 \pi}{\partial b_1 \partial t_1} = 2A_{22}^* + \frac{2A_f E_f}{a}$$
(75)

Numerical solution of Equations 51 is accomplished using the method described in Section 4.2.4.

4.2.4 Numerical Solution Procedure

Among the variety of numerical solution schemes, the following method described in Reference 94 is used in the calculation of the fundamental and the post-bifurcation paths.

The full set of equations to be solved numerically can be written in the form:

$$\underbrace{K} \Delta q - \overline{P} \Delta \lambda = -R$$

$$\underbrace{t}^{\mathsf{T}} \Delta \underbrace{x}_{\sim} = \Delta s \tag{76}$$

where the unit vector t is colinear with the vector r and is defined as:

$$\left\{ \underbrace{\mathbf{r}}_{\mathbf{z}} = \underbrace{\mathbf{r}}_{\mathbf{z}} / |\underline{\mathbf{r}}| \right\} \quad \text{and} \quad \underbrace{\mathbf{r}}_{\mathbf{z}}^{(k-1)} = \underbrace{\sum_{j=1}^{k-1} \Delta \mathbf{x}_{\mathbf{z}}^{(j)}}_{j=1} \tag{77}$$

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where, $\Delta x = {\Delta q, \Delta \lambda}$ and $r^{(k-1)}$ is the vector of the total of instantaneous displacements at the $(k-1)^{th}$ iteration.

Equation 76 can be rewritten in a condensed form as:

$$\underbrace{H}\Delta \underline{x} = \underline{S} \tag{78}$$

The matrix H is constructed by addition of the column - \overline{P} and the row \underline{t}^{T} to the K matrix as shown below:

$$\begin{array}{ccc} & & -\overline{P} \\ & & & -\overline{P} \\ & & & & \\ & & & \\ & & & \\ & & & & \\ & & & & \\ & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & &$$

If one of the components q_{α} of the vector q is selected as a control parameter, then t^{T} initially will be:

$$\mathbf{t}^{\mathrm{T}} = \{0, \dots, 0, 1, \dots, 0\}$$
(80)

where, the l appears at the q position. Assuming q = 0 as the initial equilibrium position for zero applied load ($\lambda = 0$), the extended residual vector is:

$$\sum_{k=0}^{S} \sum_{k=0}^{(0)} = \{0, \Delta_{S}\}$$

$$\sum_{k=0}^{S} \sum_{k=0}^{(k)} \{q_{k}^{(k)}, 0\} \text{ for } k \ge 1 \text{ and}$$

$$\sum_{k=0}^{t} \sum_{k=0}^{(0)^{T}} \Delta_{X} \sum_{k=0}^{(1)} \{1, 0\} = 0 \text{ for } k \ge 0$$
(81)

Equation 81 governs the equilibrium on both the fundamental (prebuckling) and the post-buckling (post-bifurcation) paths. The solution method outlined above can be used for determining equilibrium points on both parts; however, to ensure convergence of the solution procedure to equilibrium points on the post-buckling path, an orthogonality condition has to be imposed. This is achieved, as illustrated in Figure 4.2, by requiring that the vector, t_F , tangent at point B to the fundamental path, be non-colinear with the vector, t_B , tangent at point B to the post-buckling path.



Figure 4.2. Tangent Vectors t_F and t_B

The vectors t_F and t_B can be approximated as:

$$t_{\sim f} = \Delta x^{m} / |\Delta x^{m}| \quad \text{and} \quad t_{\sim B} = \alpha \{a + \mu t_{\sim f}\}$$
(82)

where, $\alpha = 1/|t_B|$, $\mu = -a^T t_f$, a is the eigen-vector of the matrix K at point B.

The imposition of the above condition provents the solution from returning to the fundamental path of equilibrium in the postbuckling regime. Once the first equilibrium point is obtained on the postbuckling path, the subsequent increments follow the procedure outlined for the fundamental path. The above procedure is used to first determine the buckling load and the corresponding mode shape. In the postbuckling solution only the unknowns corresponding to the buckle mode shape are retained and the rest are ignored.

4.2.5 Displacement Predictions

The compression panel analysis has been coded in program COMPAN documented in Reference 91 along with the user instructions. The program was used to analyze the metal and composite compression panels described in Section 3. Actual program curs for these two panels are given in Reference 91.

Solutions for the metal and composite panels were obtained by first calculating the buckling load and mode shape and then retaining in the assumed displacements the unknown coefficients corresponding to this mode shape only. Thus, the number of unknowns were significantly reduced from over 20 to 5. The calculated mode shape for composite panels was six half waves along the load direction and one half wave transverse to the load direction. The metal panel was predicted to buckle into five half waves along the load direction and one half wave transverse to the load direction,

The postbuckling predictions consisted of out-of-plane displacements as a function of the applied load, the end shortening, strains in the stringers, and membrane strain distribution in the skin. The predicted endshortening for the metal and composite panels is shown in Figures 4.3 and 4.4, respectively. These predictions illustrate the nonlinear postbuckling response of the compression panels. End-shortening data were not measured in the test program, therefore, verification was not possible. Comparison of the other predictions with test data is carried out in Section 5, where the accuracy of the predictions is also discussed.

4.3 SHEAR PANEL ANALYSIS

The shear panel analysis closely followed the approach of Denke (Reference 58) and Kudva (Reference 75). In the latter study, Denke's analysis for isotropic flat shear panels was extended to anisotropic flat shear panels.

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Figure 4.3. End-Shortening for Metal Compression Panels



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Figure 4.4. End-Shortening for Composite Compression Panels

The present analysis is a further improvement on the Reference 75 analysis in that it applies to curved anisotropic panels. The von-Karman strain displacement relations used in the present analysis include the strain term that accounts for panel curvature.

4.3.1 Panel Geometry and Assumptions

The panel geometry for analysis formulation and its relationship to the three stringer panels tested in the experimental program is shown in Figure 4.5. The horizontal and vertical stiffeners correspond to the stringers and the frames, respectively.

The panel thickness is small compared with the other dimensions of the panel. This allows the use of von Karman plate theory. When subjected to shear loads above the critical load, a stiffened curved panel undergoes large deflection and, to account for this, nonlinear strain-displacement relations are considered.

The nonlinear strain-displacement relations are:

$$\begin{cases} \varepsilon_{\mathbf{x}} \\ \varepsilon_{\mathbf{y}} \\ \gamma_{\mathbf{xy}} \end{cases} = \begin{cases} u_{\mathbf{x}} - w_{\mathbf{x}}^{2}/2 \\ v_{\mathbf{y}} + w_{\mathbf{y}}^{2}/2 + w/R \\ u_{\mathbf{y}} + v_{\mathbf{x}}^{2} + w/R \\ u_{\mathbf{y}} + v_{\mathbf{x}} + w_{\mathbf{x}}^{w} , \mathbf{y} \end{cases} + z \begin{cases} -w_{\mathbf{x}} \\ -w_{\mathbf{yy}} \\ -w_{\mathbf{yy}} \end{cases} \text{ or } (83)$$

$$\varepsilon_{\mathbf{x}} = \varepsilon_{\mathbf{x}}^{2} + z \varepsilon_{\mathbf{x}} \end{cases}$$

and z is the distance from the middle surface. Superscript o indicates the mid-plane and comma denotes differentiation with respect to the subscript. The solution method employs the concept of principle of minimum potential energy. The total potential energy, II, is the sum of the strain energy stored in the web, U_w , in the stringers, U_g , in the frame, U_f , and the potential of the external load, Ω . i.e.,

$$\Pi = U_{w} + U_{g} + U_{f} + \Omega$$
(84)



The total potential is evaluated in terms of the unknown in-plane and out-of-plane deformation parameters. A two term trignometric expression is assumed for the out-of-plane displacement. The unknown parameters associated with the assumed displacement function w(x,y) given in Equation 85 below are \bar{m} , \bar{n} and \bar{f} .

$$w(x,y) = 8\overline{f} \cos px \cos qy \cos (\overline{m} \frac{x}{a} + \overline{n} \frac{y}{b})$$
 (85)

where $\overline{m} = \frac{2\pi}{\lambda_o} a \sin \alpha$, $\overline{n} = \frac{2\pi}{\lambda_c} b \cos \alpha$

$$p = \frac{\pi}{2a}$$
 and $q = \frac{\pi}{2b}$.

 α and λ_0 are the diagonal tension angle and wave length of the buckles, respectively. \overline{f} is the amplitude of the buckles. A graphic illustration of the assumed displacement functions is shown in Figure 4.6. The additional in-plane deformation parameters assumed are e_h , e_y , e_v and γ_0 which are strain quantities with physical significance as illustrated in Figure 4.7. These strain quantities are a result of the following integrations:

$$e_{h} = -\frac{1}{2a} \int_{-a}^{a} u_{,x} dx$$

$$(e_{v} + e_{y}) = -\frac{1}{2b} \int_{-b}^{b} v_{,y} dy$$

$$\gamma_{0} = \frac{1}{2b} \int_{-b}^{b} u_{,y} dy$$
(86)

with

$$\int_{-a}^{a} y_{,x} dx = 0$$

The out-of-plane displacement w(x,y) is kinematically admissible since $w(x,\pm b) = w(\pm a,y) = 0$.



Figure 4.6. Assumed Out-of-Plane Dispircement Parameters $\alpha,\ \lambda$ and f



°_V = AYERAGE STRAIN IN FRAMES

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- \tilde{c}_{H} = AVERAGE CTRAIN IN STRINGERS
- ε_{y}^{b} = AVERAGE STRINGER DEFLECTION
- γ_{o} = AVERAGE SHEAR STRAIN

Figure 4.7. In-Plane Deformation Parameters

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In addition to the above assumed displacements, the following are assumed regarding the in-plane stress resultants:

(A) N is a constant independent of x and y and is equal to the externally applied load. 씨

- (B) N_{y} is a function of y only.
- (C) N_v is a function of x only.

The latter two assumptions ensure that the in-plane equilibrium equations are satisfied.

4.3.2 Strain Energy Expressions

The strain energies U_w , U_s and U_f and the potential of the external forces are expressed as snown below.

Strain energy of the web:

$$U_{w} = \frac{1}{2} \int_{-a} \int_{-b} \int_{-a} \left[A_{ij} N_{i} N_{j} + D_{ij} \kappa_{i} \kappa_{j} \right] dx dy$$
(87)

The first and the second term of the integrand represent the stored strain energy associated with in-plane, and bending deformations, respectively. The constitutive relations for the panel under consideration are:

$$\begin{cases} N_{x} \\ N_{y} \\ N_{y} \\ N_{xy} \end{cases} = \begin{bmatrix} A_{11} & A_{12} & 0 \\ A_{12} & A_{22} & 0 \\ 0 & 0 & A_{66} \end{bmatrix} \begin{pmatrix} u_{y} + w_{y}^{2}/2 \\ v_{y} + w_{y}^{2}/2 + w/R \\ u_{y} + v_{y} + w_{y} \\ w_{y} + v_{y} + w_{y} \\ w_{y} + v_{y} \\ w_{y} + v_{y} \\ w_{y} + w_{y} \\ w_{y} \\ w_{y} + v_{y} \\ w_{y} \\ w_{$$

The average stress resultants \overline{N}_x and \overline{N}_y are defined by Equation (89) below. The average shear stress resultant \overline{N}_{xy} equals the applied shear stress due to assumption (A) above.

$$\overline{N}_{x} = \frac{1}{2b} \int_{-b}^{b} N_{x}(y) \, dy \quad \text{and} \quad \overline{N}_{y} = \frac{1}{2a} \int_{-a}^{a} N_{y}(x) \, dx \tag{89}$$

Using the average stress resultants, the constitutive relations can be rewritten as follows:

$$\left(\begin{array}{c} \overline{\mathbf{N}}_{\mathbf{x}} \\ \overline{\mathbf{N}}_{\mathbf{y}} \\ \overline{\mathbf{N}}_{\mathbf{y}} \end{array} \right) = \left[\begin{array}{c} \mathbf{A}_{11} \ \mathbf{A}_{12} \ \mathbf{0} \\ \mathbf{A}_{12} \ \mathbf{A}_{22} \ \mathbf{0} \\ \mathbf{0} \ \mathbf{0} \ \mathbf{A}_{66} \end{array} \right] \left\{ \begin{array}{c} \varepsilon_{1} \\ \varepsilon_{2} \\ \varepsilon_{3} \end{array} \right\}$$
(90)

where,

$$\epsilon_{1} = \left[-e_{h} + \frac{1}{a^{2}} \overline{f}^{2} (\pi^{2} + 4\overline{m}^{2}) \right]$$

$$\epsilon_{2} = \left[-(e_{v} + e_{y}) + \frac{1}{b^{2}} \overline{f}^{2} (\pi^{2} + 4\overline{n}^{2}) + \frac{32\pi^{2}}{R} \overline{f} \frac{\cos \overline{m}}{(\pi^{2} - 4\overline{m}^{2})} - \frac{\cos \overline{m}}{(\pi^{2} - 4\overline{n}^{2})} \right]$$
(91)
$$\epsilon_{3} = \left[-\gamma_{o} + \frac{8}{ab} \overline{f} \overline{m} \overline{n} \right].$$

The expressions for $N_x(y)$ and $N_y(x)$ can be obtained by performing the integration shown below:
$$N_{x}(y) = \frac{1}{a_{11}} \begin{cases} a \int [u_{,x} + w_{,x}^{2}/2 - a_{12} N_{y}(x)] dx \\ -a \end{bmatrix}$$
(92)
$$N_{y}(x) = \frac{1}{a_{22}} \begin{cases} b \int [v_{,y} + w_{,y}^{2}/2 + w/R - a_{12} N_{x}(y)] dy \end{cases}$$

Knowing the explicit form of $N_x(y)$ and $N_y(x)$, the strain energy due to inplane deformation can be obtained from the following:

$$U_{I} = \frac{1}{2} \int_{-a}^{a} \int_{-b}^{b} \left[a_{11} N_{x}^{2}(y) + 2a_{12} N_{x}(y) N_{y}(x) + a_{22} N_{y}^{2}(x) + a_{66} N_{xy}^{2} \right] dx dy$$
(93)

where $a_{ij} = A_{ij}^{-1}$. Also, since the laminate is symmetric and balanced about the midplane A_{16} and A_{26} are equal to zero.

Performing the integration of Equation (93) leads to the following expression:

$$\mathbf{U}_{\mathbf{I}} = 2\mathbf{a}\mathbf{b} \left[\varepsilon_{\mathbf{i}} \mathbf{A}_{\mathbf{i}\mathbf{j}} \varepsilon_{\mathbf{j}}^{\dagger} + \frac{1}{2} \left(\frac{1}{\mathbf{a}_{\mathbf{1}\mathbf{1}}} \beta^{2} + \frac{2}{\mathbf{a}_{\mathbf{2}\mathbf{2}}} \mu \right) \right]$$
(94)

where,

$$\mu = \frac{1}{2} (v - e_y)^2 - 2\phi (v - e_y) + \frac{768\pi 4}{R} \frac{1}{F} h(n) g(m) (v - e_y) - \phi^2 + (Continued)$$

$$+ \frac{16\pi^2}{R} \int_{\overline{f}^2}^{2} h^2(\overline{n}) t(\overline{m}).$$

$$\beta = \frac{1}{a^2} \overline{f}^2 (\pi^2 + 4\overline{n}^2)$$

$$\psi = \frac{1}{b^2} \overline{f}^2 (\pi^2 + 4\overline{n}^2)$$

$$\phi = \frac{32\pi^2}{R} \overline{f} h(\overline{m}) h(\overline{n})$$

$$h(\mathbf{x}) = \frac{\cos x}{\pi^2 - 4x^2}$$

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$$g(x) = \frac{h(x)}{9\pi^2 - 4x^2}$$

$$t(x) = h(x) \frac{\sin x}{x}$$
(95)

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The bending strain energy, i.e., the second term in Equation (87) can be rewritten as:

$$U_{B} = \frac{1}{2} \int_{-a}^{a} \int_{-b}^{b} \left[D_{11} w_{,xx}^{2} + 2D_{12} w_{,xx} w_{,yy} + 4D_{66} w_{,xy}^{2} + D_{22} w_{,yy}^{2} + D_{16} w_{,xx} w_{,xy} + 4D_{26} w_{,yy}^{2} w_{,xy}^{2} \right] dx dy$$
(96)

Substituting the expression for w(x,y) into Equation (96) and carrying out the integration results in:

$$U_{B} = ab \ \overline{f}^{2} \left\{ \frac{D_{11}}{a} S_{1}(\overline{m}) + \frac{D_{22}}{b^{4}} S_{1}(\overline{n}) + \frac{2D_{12}}{a^{2}b^{2}} S_{2}(\overline{m},\overline{n}) + \frac{4D_{66}}{a^{2}b^{2}} S_{2}(\overline{m},\overline{n}) + \frac{4D_{66}}{a^{2}} S_{2}(\overline{m},$$

where,

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$$S_{1}(\mathbf{x}) = (\pi^{2} + 4\mathbf{x}^{2})^{2} + 16\pi^{2}\mathbf{x}$$

$$S_{2}(\mathbf{x}, \mathbf{y}) = (\pi^{2} + 4\mathbf{x}^{2}) (\pi^{2} + 4\mathbf{y}^{2}) + 16\pi^{2}\mathbf{x}\mathbf{y}$$

$$S_{3}(\mathbf{x}, \mathbf{y}) = (\pi^{2} + 4\mathbf{x}^{2}) (\pi^{2} + 4\mathbf{z}\mathbf{y}) + 8\pi^{2}\mathbf{x}(\mathbf{x} + \mathbf{y})$$
(98)

Strain Energy of the Stringers and Frames:

The axial strain energy of a stringer is given by:

$$U_{\rm S} = \frac{1}{2} A_{\rm S} E_{\rm S} (2a) e_{\rm h}^2$$
 (99)

The axial strain energy of a frame is given by:

$$U_{F} = \frac{1}{2} A_{F} E_{F} (2b) e_{y}^{2}$$
 (100)

In addition, the deflection shape of the stringer is assumed in the form written below:

$$\delta_{y} = 2e_{y} b \cos^{2} px \qquad (101)$$

The bending strain energy for this deflection shape in a stringer

is:

$$U_{SB} = \frac{\pi^4}{2a^3} E_S I_S b^2 e_y^2$$
(102)

where,

 $A_S = Cross-sectional area of the stringer$ $<math>E_S = Young's modulus of the stringer$ $<math>A_J = Cross-sectional area of the frame$ $E_F = Young's modulus of the frame$ $I_S = Moment of inertia of the stringer.$

Total Potential Energy:

In addition to the strain energy contributions from the various components, the potential of the externally applied shear load needs to be taken into account. This is expressed as:

$$\Omega = -N_{\rm vv} \gamma_0 4 \, \rm ab \tag{103}$$

where,

 N_{xy} = applied in-plane shear load per unit length Then, the total potential I is:

 $\Pi = U_{I} + U_{B} + U_{S} + U_{S13} + U_{F} + \Omega$ (104)

4.3.3 Governing Equations and Solution Procedure

The governing equations are obtained by minimizing the total potential with respect to the deformation parameters. Hence,

$$\frac{\partial \Pi}{\partial \gamma_{o}} = \frac{\partial \Pi}{\partial f} = \frac{\partial \Pi}{\partial m} = \frac{\partial \Pi}{\partial n} = \frac{\partial \Pi}{\partial e_{h}} = \frac{\partial \Pi}{\partial e_{v}} = \frac{\partial \Pi}{\partial e_{v}} = 0$$
(105)

The seven resulting equations in the seven unknowns γ_0 , \overline{f} , \overline{m} , \overline{n} , e_h , e_v and e_y are:

$$\frac{\partial \Pi}{\partial \gamma_0} = 0 \rightarrow A_{3j} \varepsilon_j + N_{xy} = 0$$
(106a)

$$\frac{\partial \Pi}{\partial \mathbf{e}_{\mathbf{h}}} = \mathbf{0} \rightarrow \mathbf{A}_{\mathbf{j}} \, \boldsymbol{\varepsilon}_{\mathbf{j}} - \mathbf{E}_{\mathbf{S}} \, \frac{\mathbf{A}_{\mathbf{S}}}{\mathbf{b}} \, \mathbf{e}_{\mathbf{h}} = \mathbf{0}$$
(106b)

$$\frac{\partial \Pi}{\partial e_{v}} = 0 \rightarrow A_{2j} \varepsilon_{j} - E_{F} \frac{A_{F}}{2a} e_{v} = 0 \qquad (106c)$$

$$\frac{\partial II}{\partial e_{y}} = 0 \quad \Rightarrow \quad A_{2j} \quad \varepsilon_{j} - \frac{1}{4ab} \left\{ \frac{1}{2a_{22}} + 2\pi^{4} \frac{b^{2}}{a^{3}} E_{S} I_{S} \right\} e_{y}$$

$$+ \frac{1}{4ab} \frac{1}{2a_{22}} \left\{ -\nu + 2\phi - \frac{768\pi^{4}}{R} \frac{1}{f} h(\overline{n}) g(\overline{m}) \right\} = 0$$
(106d)

$$\frac{\partial \Pi}{\partial \overline{f}} = 0 \Rightarrow 4ab \left\{ A_{ij} \stackrel{\varepsilon}{\iota}_{j} \frac{\partial \varepsilon_{i}}{\partial \overline{f}} \frac{\partial}{2a_{11}} \frac{\partial}{\partial \overline{f}} + \frac{1}{2a_{22}} \frac{\partial \mu}{\partial \overline{f}} \right\} + \frac{\partial U_{B}}{\partial \overline{f}} = 0 \quad (106e)$$

$$\frac{\partial \Pi}{\partial m} = 0 \rightarrow 4ab \left\{ A_{ij} \varepsilon_{j} \frac{\partial \varepsilon_{i}}{\partial m} \frac{\partial \beta}{2a_{11}} + \frac{\partial \beta}{\partial m} + \frac{\partial \beta}{2a_{22}} \frac{\partial \nu}{\partial m} \right\} + \frac{\partial U_{B}}{\partial m} = 0 \quad (106f)$$

$$\frac{\partial \Pi}{\partial n} = 0 \quad \stackrel{+}{\rightarrow} 4ab \left\{ A_{ij} \quad \varepsilon_j \quad \frac{\partial \varepsilon_i}{\partial \overline{n}} + \frac{1}{2a_{22}} \quad \frac{\partial \mu}{\partial \overline{n}} \right\} + \frac{\partial U_B}{\partial \overline{n}} = 0 \quad (106g)$$

The above seven equations are the governing algebraic equations of equilibrium. They are highly nonlinear due to the coupling of in-plane and bending energy terms arising from panel curvature. Equations (106) were numerically solved using standard mathematical library routines. The specific library was IMSL and the solution routine used was ZSPOW.

4.3.4 Displacement Predictions

The shear panel analysis was coded in a computer program called SHRPAN1 which is documented in Reference 91 along with user instructions. The metal and composite shear panel designs of Section 3 were analyzed using SHRPAN1. Actual program runs for these two panels are given in Reference 91.

The shear panel solutions provide out-of-plane displacements, skin strains, buckle wavelength, and diagonal tension angle as a function of the applied loads. The solution is initiated above the buckling load at some pre-selected value of the displacement. The predicted out-of-plane displacements as a function of the applied load are shown in Figures 4.8 and 4.9 for the metal and composite panels, respectively. The out-of-plane displacement contours at a constant load for the metal and composite panels are shown in Figures 4.10 and 4.11, respectively. These postbuckling displacement contours illustrate the diagonal buckling pattern. Verification of the out-of-plane displacements was not possible since these displacements were not measured during the tests. However, the predicted strains and the diagonal tension angle are compared with the test data in Section 5 where the accuracy of the solution is also discussed.

4.4 FATIGUE ANALYSIS APPROACH

The fatigue tests conducted on metal and composite panels in this program were useful in identifying the panel failure modes. Based on this evidence and on test data from other sources such as Reference 80, approaches to performing fatigue life analyses of metal and composite panels were developed. These approaches utilize the results of the nonempirical analysis developed in this program and in addition require some fracture property data. These fatigue life prediction methodologies are outlined in the following paragraphs.



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4.4.1 Metal Panels

The fatigue life prediction methodology for metal panels loaded in compression or shear is summarized in Figure 4.12. The observed failure modes for metal compression panels are cracks in the skin parallel to the stringers, but away from fastener holes, or cracks in the stringer or skin itself at fastener holes (see Figure 2.2). In the case of metal shear panels, the dominant cracks are those that initiate in the skin at stiffener to skin attach fastener holes and propagate transverse to the diagonal tension direction. For fatigue failures initiating at fastener holes, the analysis approach is the same for shear and compression panels with the fatigue life being governed by crack growth at the fastener holes. In the case of skin cracks parallel to the stringers and away from fastener holes, the analysis approach, is somewhat different and the fatigue life is governed by crack initiation and growth in the skin.

As shown in Figure 4.12, a durability rather than a damage tolerance approach is adopted in the analysis of fatigue failures initiating at fastener holes. An initial 0.01-inch corner flaw is assumed to exist at the hole. The stress intensity factors for this initial flaw are computed using available analysis methods. Flaw growth in shear panels occurs due to diagonal tension stresses and, therefore, the principal tensile stress in the skin is used for computing the stress intensity factor. In compression panels transverse tensile stresses are caused at the apex of the fastener hole by the remotely applied compression stress and are equal to it in magnitude. This stress is used in computing the stress intensity factor for the initial flaw.

Once the stress intensity factors have been determined, the Forman crack growth equation (Reference 95) can be used to determine the crack growth life for the metal panels.

In the case of skin cracks parallel to the stringers, the local skin stresses have to be computed using the nonempirical analysis described in the preceeding paragraphs. The fatigue life is estimated as the sum of crack initiation life and the crack growth life. The crack initiation life (to 0.01") can be predicted using the cumulative damage analysis of

RAYLEIGH RITZ ANALYSIS COMPRESSION
SHEAR FATIGUE LIFE PREDICTION • ADJACENT TO STIFFENER COMPUTE SKIN STRESSES CRACK INITIATION & SKIN CRACKS **GROWTH LIFE** z z • MID-BAY 60 COMPRESSION LOADING • SHEAR FASTENER HOLE CRACKS FATIGUE LIFE PREDICTION COMPUTE LOCAL STRESS INITIAL CORNER FLAW
 OF .01 IN AT HOLE z CRACK GROWTH LIFE INTENSITY FACTOR STIFFENER • SKIN **-1**10. **=**°**=** - PRINCIPAL TENSION IF SHEAR
 LOAD • TRANSVERSE TENSION FOR PANEL UNDER COMPRESSION AVAILABLE ANALYSES $\frac{da}{dN} = \frac{c(\Delta k)^{n}}{(1-R)K_{c}^{-}\Delta K}$ FOREMAN EQUATION CRACK GROWTH

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Figure 4.12. Life Prediction Methodology for Postbuckled Metal Panels

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Reference 96. Crack growth life can be predicted using the Forman equation (Reference 95). A bending correction may have to be used to obtain the effective stress intensity factor.

4.4.2 Composite Panels

The predictive methodology for composite panels is more complex due to the lack of a static analysis method that can predict the stresses at the stiffener/skin interface. The life prediction approach for composite panels shown in Figure 4.13 addresses the stiffener/web separation mode of failure observed in panel fatigue failures by way of the nonempirical static analysis developed in this program and simple beam model of the stiffener/ web attach area.

The approach shown in Figure 4.13 applies to both shear and compression panels and is based on computing the strain energy release rate at the stiffener/web interface. In this approach the nonempirical analysis is used to determine the maximum skin deflection in the postbuckling regime due to fatigue. This maximum deflection is then applied to the beam model shown which represents a strip between the stiffener and the center of the skin. An initial delamination of length b_0 is assumed to exist at the interface of the doubler and the skin laminate in the beam model. The applied maximum displacement is then used to compute the strain energy release rate at the top of the initial delamination. This strain energy release rate G is the driving force for delamination growth and can be used to predict delamination growth under static as well as fatigue loading. Fatigue life prediction is accomplished by using the nonlinear growth law.

$$\frac{db}{dN} = C(\Delta G - \Delta G_{th})^n$$

where, C, n and ΔG_{th} are constants determined from fatigue tests on simple specimens as shown in the box on the extreme right hand side of Figure 4.13. Static failure prediction requires a knowledge of the critical strain energy release rate G_c which can be determined from static tests on specimens identical to the fatigue test specimens.

The essential requirements for this life prediction approach are the development of an analysis for the beam model and the appropriate fracture properties. These developments are needed to establish a fatigue life prediction methodology for postbuckled composite panels.



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SECTION 5

DISCUSSION OF RESULTS

5.1 INTRODUCTION

The static and fatigue test data presented in Section 3 and Appendix B were analyzed to correlate the measured initial buckling and ultimate strength, and strain values with predictions. The static test data were also used to determine panel stiffness change due to postbuckling. The fatigue life data were utilized to establish S-N curves for metal and composite panels. These results are discussed in the following paragraphs.

5.2 CURVED PANELS UNDER STATIC COMPRESSION LOAD

Metal compression panel static test results and their correlation with the semiempirical analysis given in Section 2 are summarized in Table 5.1. In this table, the skin buckling data obtained from the fatigue test specimens are pooled together with the static test data. As can be seen from Table 5.1 the local skin buckling predictions which were based on the use of the empirical correction factor K_c in the expression

 $F_{cr} = \frac{K_c \pi^2 E}{12(1-\nu^2)} \left(\frac{t_w}{b_w}\right)^2$

with K_c determined from Figure 2.6, are quite conservative. The modified values of K_c account for the imperfection sensitivity of curved panels. A reexamination of the equivalent K_c for the data in Table 5.1 showed that the present data are much closer to predictions based on the theoretical K_c value of 30. Thus, the theoretical curve shown in Figure 2.6 is reasonably accurate for use in predicting the local skin buckling loads and strains. The comparison of the theoretical and the semiempirical predictions is shown in Figure 5.1. The semiempirical predictions take into account the influence of r/t ratio on the buckling load. Metal panel failure under static load occurred primarily due to stiffener crippling and as a consequence the failure data shown in Figure 5.1 agree very well with predictions which were based on the calculated stiffener crippling loads.

TABLE 5.1. CURVED METAL COMPRESSION PANEL STATIC DATA*

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- * For nomenclature used see Secn. 2.
- + These panels were fatigue tested. However, their skin buckling data were obtained in a static strain survey prior to the fatigue test.

[]>Superscript '0' denotes predicted values. $P_{cr}^{0} = 5.72$ kips, $P_{cs}^{0} = 40.95$ kips

$$i \ge K_c$$
 is the empirical constant used in $F_c = \frac{K_\pi^2 E}{cr} \frac{t_w}{bw}$ and is given in Reference 3, Figure C9.1 for various panel

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radius to skin thickness ratios, $\frac{r}{t}$.

 $3 \sim c_{\rm cr}$ denotes average skin strain measured in the center bay.

 Met_{cs} demotes average stiffener strain obtained from the four stiffener strain gages.

[]>This panel was tested under Northrop IRAD program.

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Figure 5.1. Comparison of Metal Compression Panel Test Data with Predictions

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The skin buckling loads were determined using mid-bay back-to-back strain gage data. Figure 5.2 shows the typical response of these back-to-back strain gages. These gages were located at the panel centroid and illustrate that there was a change in the buckle wave length at approximately 30 kips. This wave length change in the postbuckled regime is also corroborated by the out-of-plane displacement data shown in Figure 5.3. The actual variation in the number of skin buckles indicated by the strain and displacement data depends on the location of these gages and, therefore, measurement at a single location is not sufficient to fully describe the buckle pattern progression with load. For instance, the displacement plot for δ_3 in Figure 5.3 shows that the buckle pattern changed thrice prior to attaining the final configuration shown in Figure 3.23e. In Figure 5.3 the out-of-plane displacements predicted using program COMPAN are also shown for comparison. The displacement corresponding to δ_1 in the figure is in reasonable agreement with the test data in the low postbuckling range. However, with increasing load the test data indicate changes in buckle mode shapes which are not accounted for in the analysis. Thus, the discrepancy between test data and predictions is significant. For displacements at δ_2 and δ_3 which were symmetrically located with respect to panel centerline, the disparity in the test data and predictions is significant. In addition to changes in the buckle mode shapes, another reason for this discrepancy could be the extreme sensitivity of the out-of-plane displacements to variations in the location of measurement on the panel. From these comparisons it is apparent that the compression panel analysis for metal panels needs additional refinement.

The axial strain in the stiffeners was approximately bilinear up to failure with a distinct change in the slope after skin buckling. Axial strain variation with appliel load for the four stringers of metal panel MCl is shown in Figure 5.4. The average of the four stringer strains was used in determining the panel gross stiffness change due to skin buckling. Panel MCl showed a postbuckled stiffness that was 64 percent of the prebuckling stiffness, whereas, for panel MC2 this number was 56 percent.

Correlation of buckling and failure strain data for composite compression panels with theoretical and semiempirical predictions is shown in



Figure 5.2. Metal Compression Panel Web Static Strain Response









Table 5.2 and Figure 5.5. The measured web buckling strains are considerably lower than the predicted values. This, however, was not surprising since the effective width of the web was not known a priori and was assumed as the distance between the adjacent stiffener flanges as shown by "CURRENT" in Figure 5.5. The test data indicate that this assumption is unconservative. An effective width equal to the distance between the centers of adjacent stiffener flanges, indicated by "PROPOSED" in Figure 5.5, yields excellent correlation between the predictions and the test data.

Composite compression panel strength measurements closely agree with semiempirical predictions based on the stiffener crippling mode of failure. Thus, the stiffener/web separation mode of failure seen in the static tests is induced by stiffener crippling.

Figure 5.6 shows the back-to-back mid-bay strain gage response for composite panel CCl and is typical of that observed for the other five panels. The buckle pattern c_{2} mges shown are significant from the point of view of developing a nonempirical analysis. The regions where the buckle pattern changes are apt to cause numerical difficulties in predicting the postbuckled response and the nonlinear analysis may have to be performed piecewise with the regions selected so that no change occurs in the buckle pattern. The out-of-plane displacement data for composite panel CCl are shown in Figure 5.7. These data corroborate the buckle pattern progression indicated by the strain gages. For comparison, the predicted values of out-of-plane displacements are also shown in Figure 5.7. The trends in the predicted displacements at δ_2 and δ_3 match the test data. However, numerically there is a significant amount of discrepancy.

The stiffener axial strain response for composite panel CCl is shown in Figure 5.8 and is representative of that seen for the remaining composite compression panels. In Figure 5.8, COMPAN predictions of stringer strains are also shown. As opposed to the skin displacements the stringer strain variation with applied loads is reasonably well matched. The strain values predicted, however, are considerably higher than the test data. The stiffener strain data were used to determine the panel stiffness changes due to buckling shown

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POSTBUCKLING STIFF- NESS, % INITIAL STIFFNESS	62	64				
ε _{cs} /ε ⁿ ss	1.61	1.62		1		
εcs/εocs	1.07	1.07	9		1	1
ε _{cs} µin/in	5281	5291				
P _{cs} , * kips	84.6	82.0	1	1	1	
$\epsilon_{\rm cr}/\epsilon_{\rm cr}^{\rm 0}$ *	0.75	0.66	0.47	0.52	0.55	0.71
BUCKLING STRAIN E _{CT} ,µin/in	862	756	543	603	638	815
BUCKLING LOAD P _{CT} kips	18.0	16.0	14.0	12.0	12.0	16.0
PANEL NO.	CCI	CC2	cc3*	cc4	CC5	900

NOTES:

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- 1153 µin/in Predicted skin buckling strain. H ిచి
- 15000 µin/in Compression ultimate strain for skin laminate. 8
- Panel failure load. R P cu Cs Cs
- Average stiffener strain at panel failure. u
- 4956 µin/in Predicted stiffener crippling strain. Ħ
- 3276 µin/in Predicted stiffener/web separation strain. 11 မ္လာ က က က အဝ ဂိုဝ လိုက္ရန္က
- Panels CC3 through CC6 were fatigue test specimens **

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in Table 5.2. The reduction in stiffness after buckling for composite panels is similar to that for metal panels and is approximately 40 percent.

5.3 CURVED PANELS UNDER COMPRESSION FATIGUE LOADING

The fatigue data for metal and composite compression panels are shown in the S-N diagram of Figure 5.9. The curves were faired to represent the data trend and due to the limited number of data points a definitive threshold for 100,000 cycles of constant amplitude fatigue cannot be established. The data for composite compression panels, however, are consistant with those obtained from other tests and summarized in Figure 2.4. Therefore, composite compression panel fatigue does not appear to be a concern in the 2500-3500 μ in/in operating strain level typically seen in postbuckled structures.

The metal panel fatigue tests were useful in identifying the failure mode that needs to be accounted for in developing a fatigue life prediction methodology (see Section 4.4). The fatigue data also show that the metal panels are quite sensitive to fatigue and, as illustrated in Figure 5.10, are inferior to composite panels designed to the same loading conditions. Additional metal panel tests, however, should be conducted to accurately define their S-N response.

The periodic strain surveys conducted during the fatigue tests were used to determine if repeated buckling of the panels influenced the initial buckling load or panel stiffness. The data showed that repeated loading did not influence the initial buckling load or the panel stiffness.

5.4 CURVED PANELS UNDER SHEAR LOADING

The metal shear panel test data analysis is summarized in Table 5.3. Comparison of the data with predictions is shown in Figure 5.11. The predictions were based on Figure 3.5 (Reference 34) assuming the skin width b_w equal to the stiffener pitch. The data show that with this definition of the skin width, the buckling load predictions are reasonable estimates considering the scatter in the initial buckling loads, and the semiempirical approach of Reference 34 can be readily used for design purposes. The failure load predicted for metal shear panels ($N_{xy}^{ult} = 900$ lbs/in) was based on the







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TABLE 5.3. METAL SHEAR PANEL STATIC TEST DATA CORRELATION WITH PREDICTIONS

[¹ 2						
POSTBUCKLIN STIFFNESS, % INITIAL STIFFNESS	83	89.5	-			-
DIAGONAL TENSION ANGLE	28 ⁰	26 ⁰	-		8	1
$\frac{\substack{N_{xy}^{ult}}}{\binom{N_{xy}^{ult}}{x}}$	1.34	1.18				
$N_{xy}^{ult} = \\ R_{xy}^{ult}$ $G_{t}\gamma_{xy}^{ult}$ Ib/in	1210	1058		3		-
γ ^{ult} γx µin/in	4800	4200				
$\frac{\binom{cr}{xy}}{\binom{n}{xy}_{0}}$	0.83	0.97	1.17	1.13	0.88	1.23
N ^{cr*} =CtY ^{cr} xy lbs/in	242	282	338	327	254	356
WEB BUCKLING SHEAR STRAIN Y ^{CT} † µin/in Xy , µin/in	963	1118	1341	1298	1007	1414
LOAD CELL READING AT BUCKLING, LB	3820	4123	4453	3848	2895	3811
PANEL NO.	1 SW	MS2	MS3**	MS4	MS5	9SM

G = 4 x 10⁶ psi

** Panels MS3 through MS6 were fatigue test panels

Lowest buckling shear strain as measured from Gages 2 and 5 in Figure 3.13 ≁

++ Quantities with subscript '0' denote predicted values

 $(N_{xy}^{cr})_0 = 290 \text{ lbs/ln} (From Figure 3.5)$ $(N_{xy}^{ult})_0 = 900 \text{ lbs/ln}$

§ Predictions based on stiffener forced crippling mode of failure

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stringer forced crippling mode of failure. The ultimate shear flow calculated for shear panels MS1 and MS2 using web-maximum shear strain data at failure, compares well with these predictions. A comparison of the measured stringer axial strains with that predicted for stringer forced crippling, however, shows that the measured strains are considerably less than the predicted crippling values. The actual failure of the metal shear panels was by permanent set in the skin. This was confirmed by an examination of the measured principal strains (Gage 5 in Figure 3.13) in the skin which showed that the 6500 µin/in yield strain for 7075-T6 aluminum had been exceeded. Thus, it is not surprising that the measured stringer axial strains did not exceed the predictions for forced crippling.

In order to verify if permanent set can be predicted using the flat metal panel criterion, the allowable diagonal tension factor for the present panels was calculated with the aid of Equation 31. The maximum value of k was calculated to be 0.554 which translated into an ultimate load to initial buckling load ratio of 2.2. However, the data show that for these panels, the ratio is of the order of 4. Thus, the flat metal panel permanent set criterion is very conservative for curved panels. A criterion needs to be developed for curved panels by additional testing.

The web shear strain variation with applied load is shown in Figure 5.12. These data were used to compute the change in panel stiffness after buckling. As shown in Table 5.3, the metal panels retain a large percentage of their initial stiffness in the postbuckling range. The maximum reduction in stiffness was approximately 17 percent. The stringer and ring axial strain variations with applied load are shown in Figures 5.13 and 5.14. For comparison, predictions from SHRPAN1 are also shown. The reasons for the large discrepancies are explained in Section 5.6. The measured diagonal tension angle was approximately 27° and is less than that predicted by tension field theory but is larger than the 20° angle predicted by SHRPAN1. A plot of the diagonal tension angle, calculated using the mid-bay strain rosettes (Gages 2 and 5), versus the applied cylinder load is shown in Figure 5.15, along with the predictions from SHRPAN1. The predicted values agree reasonably well with the test data.



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The composite shear panel test data analysis is summarized in Table 5.4. Comparison of the initial buckling and failure strain data with predictions is shown in Figure 5.16. The predictions were based on a skin width equal to the stringer spacing and are unconservative. In the case of composite shear panels, a more realistic definition of the skin width is the distance between adjacent stiffener flanges. Use of this definition yields better correlation between the test data and the predictions. Failure of the composite panels was predicted by forced crippling of the rings. In Section 2 it was also noted that forced crippling strains for the stiffeners correspond to stiffener/ skin separation strains. The data comparison in Figure 5.16 along with the ring/ web separation mode of failure observed in composite shear panels CS1 and CS2 substantiate the above hypothesis. The failure predictions made using the modified tension field theory are on the conservative side by approximately 35 percent. The measured maximum shear strains in the composite panel web shown in Figure 5.17 were used to determine panel stiffness change in the postbuckling regime. The composite shear panels show a dramatic loss in stiffness after initial buckling of the skin. As indicated in Table 5.4 the postbuckled stiffness for these panels is approximately 45 percent of the initial stiffness. These data are of significance in the design of postbuckled composite panels since the stiffness has a direct influence on the aeroelastic response of the panels. Therefore, for composite shear panels verification of the design for aeroelastic response criteria will be essential.

The hat section stringers showed significant bending during the static tests. The back-to-back strain gages were placed on the stiffener skin flange and the crown flange and due to the local bending of the crown flange, separation of axial and bending strains for the hat section stringers was not possible. In Figure 5.18 and 5.19, the stringer and ring strains measured on the skin flange of these stiffeners are shown. These data do not indicate the true axial strains due to the reasons cited above; however, they do show the buildup of strain in the stiffeners with increasing load after diagonal buckling. The stiffener strain predictions shown in Figure 5.18 were obtained from SHRPAN1.

The diagonal tension angle variation with load for the composite panels is shown in Figure 5.20. The predictions are in reasonable agreement with test

TABLE 5.4. COMPOSITE SHEAR PANEL STATIC TEST DATA CORRELATION WITH PREDICTIONS

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POSTBUCK- LING STIFF- NESS % INITIAL STIFFNESS	43	46	1	ł	1	ŀ	!	ł	1	1	
$\frac{\varepsilon_{or}}{(\varepsilon_{or})_0}$	1.31	1.39						1			
RING STRAIN AT FAILURE E _c r,µin/in	-3563	-3770		1				1	1	-	
$\frac{\varepsilon_{os}}{(\varepsilon_{os})_0}$	0.83	0.93		8	-	 	1	1	1 1 1 1	1 1 1 1	
STRINGER STRAIN AT FAILURE cos, uin/in	-2662	-2971			5				8		
γ ^{ult} γ ₀	1.49	1.74					-		1 1 1	[
WEB SHEAR STRAIN AT FALLURE Y ^u lture	5200	6100			5					1	
$\frac{\gamma_{cr}}{\gamma_{cr_0}}$	1.45	1.6	1.62	1.41	1.79	1.83	1.65	1.84	2.05	1.58	
WEB BUCKLING SHEAR STRAIN Y _{Cr} µin/in**	1115	1229	1244	1083	1381	1407	1270	1420	1577	1213	
PANEL NO.	CS1	CS2	CS3*	CS4	CS5	CS6	CS7	CS8	CS9	CS10	F

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 $(\varepsilon_{or})_0 = -2718 \, \mu in/in, (\varepsilon_{os})_0 = -3192 \, \mu in/in$ Panels CS3 through CS10 were fatigue tested. Lowest shear strain as measured by gages 2 and 5 in Figure 3.13. Quantities with subscript '0' denote predicted values. $\gamma_{cr_{n}} = 770 \,\mu in/in, \,\gamma_{0}^{ult} = 3500 \,\mu in/in, \,(\epsilon_{or})_{0} = -2718$ Y_{cr0} -89-

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data. The discontinuity in predictions at an applied cylinder load of 5,000 lbs is due to the instability of SHRPAN1 solution in a close neighborhood of the buckling load. As the load increases, the diagonal tension angle decreases, indicating the tendency of the diagonal buckles to merge and cross over the stringer into the adjacent bay. After buckling the diagonal tension angle is approximately 18 degrees and compares favorably with the predictions.

5.5 CURVED SHEAR PANELS UNDER FATIGUE LOADING

The fatigue test data for metal and composite shear panels are shown plotted as a function of the maximum fatigue load normalized to their respective static strengths in Figure 5.21. The data demonstrate the sensitivity of metal shear panels to fatigue loading and that their response is much inferior to that for composite panels designed for the same loading condition. The composite shear panel fatigue response is not affected by the partial reversal of the shear loading as is evidenced by a comparison of R = +0.25 and R = -0.25fatigue data in Figure 5.21.

The fatigue tests were also useful in identifying metal and composite panel failure modes. Crack initiation and propagation in the metal panels as shown in Figure 3.32 and stiffener/web separation in composite panels are the critical modes that are addressed in the fatigue analysis methodology proposed in Section 4.4.

Analysis of the periodic strain survey data for the metal panels did not show any influence of repeated loading on initial buckling loads or panel stiffness in the postbuckled range. A majority of the relevant gages on the composite shear panels were lost due to fatigue damage and the data obtained could not be used for a meaningful interpretation of repeated buckling effects. The buckling loads measured in these strain surveys, however, do not show any influence of repeated loading on panel stiffnesses.

5.6 DISCUSSION OF ANALYSIS AND TEST DATA CORRELATION

The out-of-plane displacement and strain predictions from programs COMPAN for compression panels and SHRPAN1 for shear panels are significantly different from the measured values.



There are several reasons for these discrepancies. First of all the results of the energy based analyses are very sensitive to the assumed displacement functions. Secondly to account for mode shape changes in the postbuckling path either the assumed displacements should be a superposition of several modes or if a limited number of terms are used, the mode shape parameters should be treated as unknowns. The latter choice is more desirable since assumed displacements with a large number of unknowns inevitably lead to numerical difficulties in the solution of the resulting nonlinear equations.

Several numerical problems were also encountered in solving for the metal and composite compression and shear panels. In the case of compression panels, the solution procedure required that the starting point be zero load and zero displacement. The solution then progressed by marching up the prebuckling path to a load value slightly less than the buckling load and then switching over to the postbuckling path with a mathematical artifice of orthogonal vectors. The multivalued nature of the postbuckling path at bifurcation of equilibrium near the buckling load leads to nonconvergent solutions due to numerical oscillations. Thus, the orthogonal vector approach works only for the simplest of assumed displacement functions. In order to circumvent these problems, a solution scheme that starts from an initially guessed pair of load and displacement values in the vicinity of the postbuckling path, but sufficiently greater than the load and displacement values at bifurcation, should be utilized. In the shear panel analysis this latter scheme was adopted with the buckling loads being computed externally by programs such as SS8. The solution, however, was extremely sensitive to the initially guessed values for the unknowns and considerable expertise was required to select initial values that led to converged solutions. One possible strategy that may be used in selecting the initial displacements is given in Reference 91.

Based on the present experience, it is recommended that in future attempts to model the postbuckling behavior of compression and shear panels the following techniques be used:

> (A) Introduce initial imperfection or a transverse load to eliminate numerical problems in the vicinity of the bifurcation point.

- (B) Treat mode shape or buckle wave length as an unknown in the assumed displacements.
- (C) Evaluate functions other than trignometric functions for the assumed displacements.

SECTION 6

CONCLUSIONS

The significant conclusions from this program are summarized in the following paragraphs.

6.1 <u>DESIGN AND ANALYSIS METHODOLOGY FOR CURVED COMPOSITE POSTBUCKLED</u> PANELS

- A semiempirical static analysis methodology was developed for curved composite panels loaded in compression or in shear.
- Experimental verification data provided guidelines for determining the skin dimensions to be used in calculating initial buckling loads for both compression and shear panels.
- 3. Ultimate load predictions based on the semiempirical analysis for compression panels are very accurate and can be readily used for design purposes.
- 4. The modified tension field theory is applicable to curved composite shear panels. Ultimate load predictions are conservative by approximately 35 percent.
- 5. The postbuckled stiffness of compression panels is decreased by approximately 40 percent from the initial stiffness.
- In shear panels the loss in stiffness after buckling is approximately 55 percent.
- 7. Stiffener/web separation was the observed failure mode for static and fatigue loading of compression and shear panels.

- 8. An empirical equation was developed to predict the static stiffener/web separation strain for shear panels.
- 9. Stringer or ring forced crippling strains correspond to the stiffener/web separation strain for shear panels.
- 10. Fatigue loading is not a concern for compression or shear panels and sufficient data exist to determine their safe operating strain levels.
- Based on the fatigue failure modes observed in the tests, an approach to life prediction for compression and shear panels was doveloped.
- 12. Repeated buckling had no influence on panel initial buckling.
- 13. Non-empirical Rayleigh-Ritz analyses of postbuckled compression and shear panels have been developed. The analyses although capable of predicting the detailed displacement and stress field in postbuckled panels require further refinement to ensure numerical accuracy.
- 14. The program results were used to develop a design guide for compression and shear panels.

6.2 DESIGN AND ANALYSIS METHODOLOGY FOR CURVED METAL POSTBUCKLED PANELS

- Applicability of the tension field theory to curved shear panels was verified by test data. Skin permanent set was seen to be the primary failure mode in these panels. A need to obtain a permanent set criterion for curved panels was identified.
- Ultimate load predictions based on the available analysis methods were found to be quite accurate for compression panels.

- 3. The postbuckled stiffness reduction for compression panels is the same as that for composite panels. In the case of shear panels the stiffness change after buckling was seen to be only about 15 percent.
- 4. Fatigue sensitivity of compression and shear panels was found to be the greatest concern.
- 5. Skin cracking parallel to the stringers and away from fastener holes was identified as a failure mode in the compression panels.
- Skin cracks originating at stiffener attach fastener holes and propagating transverse to the tension field direction was identified as the failure mode in shear panels.
- 7. Based on these failure modes, a fatigue life prediction approach was formulated for compression and shear panels.
- Repeated buckling had no influence on the initial buckling load or stiffness of compression or shear panels.
- 9. The program results were used to develop a design guide.

6.3 RECOMMENDATIONS FOR FUTURE WORK

- 1. Develop a design guide for panels under combined load.
- 2. Complete the development of the fatigue life prediction methodologies for metal and composite panels and extend the methodology to panels operating under combined loads.

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APPENDIX A

COMPRESSION AND SHEAR PANEL STRAIN DATA

A.1 <u>COMPRESSION PANEL STRAIN DATA</u>

The strain data obtained from all compression panel static tests and fatigue strain surveys are tabulated in this section of the appendix. Correspondence Table A-1 should be used to correlate the gage numbers in the strain data tables with the locations shown in Figure 3.12. All gages were axial gages.

GAGE NO. IN FIGURE 3.12*	GAGE NO. IN DATA TABLE*
1E	1
11	2
2E	3
21	4
3E	5
31	6
4E	7
41	8
5E	9
51	10
6E	11
61	12
7E	13
71	14
8E	15
81	16
9E	17
91	18
10E	19
101	20
11E	21
111	22
12E**	23
121**	24

TABLE A-1. GAGE NUMBER CORRESPONDENCE TABLE FOR STATIC COMPRESSION TEST PANELS

*Fatigue panel MC3 instrumented with gages 1 through 8.

Fatigue panels MC4, CC3 and CC4 instrumented with gages 1 through 6. Fatigue panels CC5 and CC6 instrumented with gages 1 through 4 and 6. Gage 6 data corresponds to column numbers 9 and 10 in the data table.

**Gage on midbay stringer of panel CC2.

COMPRESSION PANEL STRAIN DATA

I

STRAIN DATA FOR PANEL CCI

GACE 15	8 A 1 P 1	89	5	ភ្	2 2 2	173	212	315	543	1018	2005	1531	1861	2046	2260	2022	2732	2061	3187
GAGE 5 4	-84	440	-415	-498	- 52.6	-658	-1348	-1519	-1253	1082	1396	1458	1640	1818	2020	2259	2533	8985	3329
GAGE13	កល ទទ្ធ 	100		-467	5 0 7 0 1 1	-748	-188	-144	а '	8102-	-2136	-2211	+162-	-2430	-2583	-2797	-3071	-3464	-3973
GAGE 12	-138	-212		-436	-536	-515	-1192	-1810	-2249	2173	2476	2771	3076	3324	3572	Beac	4012	4203	4368
GAGE15	-1:9	00		404-	1921	-635	ດນ ເອັ	472	- 58 -	8322-	-3818	-3283	-3584	-3843	-4107	1968-	-4581	0.52.5	-4961
2AGE 10	-155	-236	101-	170	-010-	-619-	-830	-1236	-528	SEL-	-791	-81%-	-850	-838	-948-	1029	-1138	-1231	1325
SAGE 9 (-77-	522-	880	-468	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	ier-	-71-	-533	-423	-33 9	-203	-289	-339	1423	-617	- 542-	-1312 -	- 5151-	-2419 -
CAGE 8 (-182	-276	- 429	-545	****	-834	578-	-1263	-1491	-1763	-2076	+253-4	-2725	0240.	-3355	-3689	-4015 -	4368 -	4740
PACE 7 (-64	800	200 201 1	-578	-762	-874	1001.	-1211 -	-1493 -	1784 -	-2001 -	2272	- 9855	-2863 -	- 8416-	- SEVE.	-3765	- 9866	- 4256
34GE 6 (-183	-281	100-	-547	1010	-836	-954 -	-1251 -	1527 -	-1776 -	-2075 -	- 1963	- 2692-	- 2882-	- 3856 -	- 3592	- +586	4222 -	-4572 -
392E 5 (80- 607-	102-	- 476	-566	-24% -24%	-857	1959	- 1631	1515 -	- 2672	- 1997 -	2306	2678 -	- 2882	- 1466-	- 0695.	4058 -	- 4424	4882
¢0€ 4 6	-174	-260	147- 1906-	-523	-711	-827	- 858 -	1249 -	1522 -	1846 -	2163 -	2497 -	2887 -	3236 -	3609 -	4002 -	4385	4799 -	5239 ~
AGE 3 G	-93	14.2	1441	-533	112-	-802	-910	1320 -	1646 -	2053 -	2411 -	2786 -	3216 -	3586 -	3853 -	4292 -	4605 -	4925	521 9 -
AGE 2 9	- 36	-315	1	- 500 - 500	-796	305-	1022	1319 -	1616 ~	1936 -	2253			- 3166	- 0896	4055 -	- 2124	4808 -	5284
ACE 1 G	-223-	-323	-515	-618	-833	-966	1678 -	1425	1757 -	2114 -	2469 -	- 9685	- 3273 -	- 3669 -	- 650+	4529 -	4924 -	- ESES,	5882
9 1001	5014	90	» Q	ru ;	+ 9 	18	- 80	- 52	- 96	- SS	46 -	45 1	- S	- 22	33	- 59	- 91	r R	83

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-53	-107	-186	-271	- 365	-465	-572	-693	-831	-119	693-	ie	6462-	-2405	-2509	-2784	-2945	-3085	-3218	-3331	-3472	-3674
-34	-188	-28G	696-	-467	-567	-663	-765	1461-	1814	-2019	-2146	-2296	-2363	-2375	6222-	-2014	-1429	-829	693-	136-	のキバー
52	-180	-268	1354	844-	-543	-637	EE1	465	535	6622	SCET	1503	1602	1623	5965	1191	526	-537	-438	-646	-798
- RG	- 223	-329	\$E\$-	-532	-524	-782	48	- 263	-511	1310	798	271	2683	2871	3656	3213	5755	ふすうの	3717	6205	4156
-84	-217	-318	-418	-517	-614	-722	-875	-1277	-1108	0101-	-1172	274-	-3896	-3132	-3276	-3432	-3587	-3751	\$162-	1301-	さゆのマー
152	-175	-319	-489	-663	-863	-168?	-1332	-1627	-1702	-1924	-2358	-3107	-3555	-3972	-4420	-473B	-5:53	-5538	-5839	-6252	-6598
202	•	6	8	19	2	4	16	8	62	ູ່	ê	ŝ	8	4	ເ ເ	5	99	59	70	£	98 8

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STRAIN DATA FOR PWEL CC2

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GAGEIS	-97	-227	-382	-545	-731	6+8-	-1190	-1465	-1377	-1534	-1912	-2315	-3166	-3619	-4021	-4442	-4777	-5080	-5358	-5116	-5844	-6278
GAGE 14	+ 8 -	-163	-52-	-343	-424	-569	-602	-727-	E3E-	1329	-164	62	-2124	-2189	-224	-2333	-2438	-2582	-2737	-1072	788	1485
CACE 13	68-	-173	-273	-365	-450	-532	-590	-591	-1127	-1279	-1680	-2961	1213	1382	1530	1713	1997	2151	2397	265	-1318	-2223
GRGE12	-61	-132	-215	-289	-363	164-	-526	-652	60	340	789	1190	-2823	-3292	-3702	-4071	-4378	-4586	-4614	-567	1820	2792
GAGE11	-67	-147	-237	-318	16E-	-456	-495	-463	-1229	-1482	6461-	-2332	1632	2134	2540	2863	3124	3364	CEEE	-223	-2527	-3455
CAGE 10	-80	-160	-249	- 330	-412	-498	E05-	-717	-275	-206	-100	65	-350	-312	-279-	-271	-357	-640	-1651	-182	85	121
CAGE 9	-85	-163	-252	-336	-416	- 495	-552	-559	-1138	-1286	-1692	-1844	-798	-783	-788	-796	-815	-851	-892	-1292	-1802	-2031
GAGE 8	-141	-251	-367	-474	-574	-676	-778	-879	-1929	-1150	-1439	-1772	-2121	-2477	-2852	-3296	-37.6	-4123	-4533	-4917	-5003	-5669
GAGE 7	-162	-204	-317	-413	-500	-596	-698	-864	- 933	-1053	-1353	-1652	-1910	-2214	-252-	-2893	-3226	-3564	-3926	0004-	-4691	1605-
GAGE 6	-101	-188	-293	686 -	E84-	-578	-674	E77-	-954	-1682	-1428	-1747	-1964	8022-	-2646	-3946	-3416	964E-	-4166	-4457	-4967	-55.05
GAGE 5	-100	-202	202-	-400	-488	-578	-671	-766	200-	-1020	-1297	-1582	-1816	-2100	0052-	-2720	-2027	-3344	-3570	-4884	-4516	- 4919
GACE 4	-82	-166	-256	5402	EEP-	-526	-618	-711	1224	1000		-1501	1000	-2466	19841	-2267	. 1651	-4825	6052-	-4785	5.5	-5655
CAGE 3	-72	1011	-242	-326	6144	205-	100	-681	202-		1210		4081-		2000-	01001	- 21 40		5005-	- 4233	-4607	-5002
CRGE 2	-7.4	-170	296-	046-	-444	-548		200	-848	10	-1203	15.25			1010-	200			-442-	-4886	-6337	-4770
CAGE 1	មិ	1	866-1	3.2.1	- 454	25.34		-700	006-			1465		1000	1000			0000		0	1029-	000001
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	-46	-128	-230	-326	-428	-542	-566	608-	-417	-362	30C-	-285	-1829	-2020	8462-	-2583	-2519	-2001-	1922-	-4657	-5000	-5652
	9 4	-137	-222	-287	400-	-363	332	-258	-703	-714	-515	-600	1108	1438	1740	2939	2283	0550	888	3259	0000	48 TU
	32-	-159	-050	146-	-437	-533	643-	-750	÷£G	-938	-577	-137	326	761	3211	1611	644	63	-101	-155	-128	- - -
	-72	-160	-251	-339	464-	-532	-626	-712	-522	-496	028-	-154	-981	-1035	-2228	-2238	-1871	-1356	-1144	-1623	130-	120-
	-113	1004	308-	-410	-510	-620	-739	016-	-631	-419	746	813	010	686	1608	826	720	356	147	6	8	193
	-112	-202	E06-	200-	164-	-585-	-620	-661	-748	986- -	-1772	-1934	-2055	-2139	-2149	1502-	-1732	9887-	-66-	-787-	-774	-383
	2	99-	301	-168	-6-	-56	3	127	188	207	476	743	1157	1403	1656	2631	2066	2203	3338	2584	202	3161
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STRAIN DATA FOR PANEL CC3 (BEFORE FATIGUE)

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gage g	-07	1 2 6		144	1010 B	-465	440-	100			2451-	-1224	-1206		1051-	-1834	-2072	12242	10	i i	いのいい	-6470
GAGE 8	-150				- 386	-463	-540	101	200	- 0	282.1	· 872	-1079		5201	-1699	-1858	E112-			2000	EA32-
GAGE 7	-148	- : : 9	200		AF6-	-556	-679	-304	000		F997-	~1192	-1514		- 50%-	-2230	- 00 - 00 - 00	-2951	-2903		1000	BKBL-
GAGE 6	-78	i i	1000		າ ບ າ	-408	-486	1111	1666			-962	-1257	- 1 C X J		BAKI-	-2257	-2015	-2938	2200		12222
GAGE S	-88	-167	en u		50 50 1	-489	-626	-777-	CYC-			-1316	-1746	-2166		5070 1	-3665	-3531	1206-	4417		OA25
GAGE 4	66-	-191	2201			541	-591	-691	-832	100-		-1685	-1466	-1204			0.00	, 2009	-3348	. 2742 .		50AC.
GAGE 3	-112	-200	-286			1.44	-568	-679	-835	800-		R/ 11-	-1616	-2027	0070		9252-	- 332E-	-3803	1201-		
GAGE 2	-80	-164	-247	-226			2031	-584	-650	-772		UPS-	-1027	-1243			- 122	- 2925-	- 22233	-2567	1000	
GAGE 1	-174	-246	- 302 -	-359			7001	-625	-755	-879	1000		-1344	-1692	-20CA			2000	-3518	-3618	1250	*
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STRAIN DAYP FOR PRICL CC3 AFTER 56,80% AVALES OF FATIQUE

GAGE12	1		-153	-199	-298	-215	-267	-160	-37	145	126	523	3447	1124	1205	1269	1245	1255	1253
GAGEA1			26-	01:21 1	-332	-491	-686	-955	-1077	-1255	-1487	2067	-2162	-1996	-1989	-1978	-1871	-1864	-1854
GAGE 19		- 86	-150	-239	-319	-397	キンシー	-563	-187	516	418	693	218	995 266	1168	1354	1455	1583	1493
8999		4L-	-151	-236	-325	-415	-595	-591	-613-	1:13-	-11,38	-1259	-1426	-1715	-1251	-2179	-2324	-2423	-2443
GAGE 8		-188	9 84,		-457	-548	-610	-769	-774	1138-	960	.1205	~1416	-1648	-1095	2000	-2259	-2515	-2666
GACE 7		- 398	-550	269,	-821	キンびー	-101-	-1:70	-18 5	+341-	-1447	2841-	-2675	-2050	- 2637	(286 8	- ,238	-3562	-3750
GAGE 6		67	-43	- 115	-180	କର ଅନ୍ତ	646-	-436	-508	-672	-789	2352-	1961-	-1748	-2119	-2480	-2872	-3285	- 1536
GAGE 5	1	-147	-246	-376	-511	-644	-772	-914	-1856	125-1-	-1385	-1772	-2174	-2539	-2906	-3416	-3226	- 7263	-4329
07.5E &		1-65	-164	-202	CEE-	- 428	-513	-618	-736	808	-1031	17.E 1-	-1726	-2002-	-2428	2080-	. 3218	~3633	9885-
GAGE 3		000-	-145	-242	-365	1211	-604	-743	+88-	-1072	-1212	-1611	C061-	-2373	~ 2781	-3264	-3505	-403B	0000-
GACE 2		-178	-265	-141	14.00	104-	1-564	-643	-713	198~	-035	-1973	- 1677	- ,488	E171-	1960	-2170	2455	-2610
Gest :		-274	-386	-521	-655	-786	-902	-1026	-1:46	-1268	5/61-	-1651	-1993	-2267	-2574	-2898	-3175	-3503	-3698
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STRAIN DATA FOR PANEL CC4 BEFORE FATIQUE

GAGE12	89		22	ee	4	49	5	C	- (0 0	4	67	256	107				2661	1482	1581	
QAGE11	-47	40	-122	-162	-212	-276	-304	- 245		192-	-463	-886	-1439	-1001			-1860	-2024	-2363	10420	
GAGE10	-166	-166	-239	-311	-389	-487	-156	20		SET	640 0	840	762	110		100	1744	1739	1632	1525	
CACE 3	-112	-138	-269	-1247		-491	-714			-1042	-1158	-1250	-1132	222		5623-	-2376	-2452	-2423	-2354	
GAGE B	-123	102-	-286	-368	- 440	00.11				-785	-869	-1079	-1278			-1868	-2988	-2366	-2664	1080-	
CAGE 7	-123	-184	222	826-	200				Ņ	-711	-807	-1057	-1107			-1994	-2198	-2501	-2928	-2944	22
9 3940	-71	-151	-248	646-					-820	-953	-1004	1458	-1707		10101	8622-	- 1290	-1793	CICA-	0199-	402
GAGE 5	- 112	-182	0001			10 40 1 1		-020	-816	-972	11.11-			r (7 (7 (7 (- 373-	-2837	-3294	-1720	4182	2010-	1077
GAGE 4	~126	1010	1						-033	663	102				8662-	-2765	- 3850	CaeC-	12050)	1404-
CACE 3	-127		10						-911	1942				2021-	-2329	-2760	- 7265		2064		5356-
CAGE 2	13-				500 10 10 10	1000		-536	1 5 13	2030				-16 13	-1511	-1767	1001-				35.0-
arst 1	19.0		7 C 1 C 1		914-	166-	525-	5124	-742			かし ゆう ね・		ESCI-	-1610	-1933				20201	2115-
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STRAIN DATA FOR PANEL CCS AFTER 50,000 CYCLES OF FLITQUE

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GAGE 18	-63	191-	10.21	1000	646-	EQE-			395	27.0	388	1057	1363	1508	1670	2981
CODE N	63-	-138	-224	-299	-388	1002	584	-401	- 67Q	E.C.	007	-1571	-1653	-2087	-2285	-2452
GAGE 8	-150	-273	e dry -	-494	185-	909	-813	4401	-1086	-1213	9121-	-1896	-2258	-2620	-2985	S#66-
JACE T	153	042-	-412	-525	-648	-7,69	506-	-1037	-1:65	-1295	-1660	-1979	-2203	-2621	-2958	-3283
CAGE 6	-59	-138	-221	-293	84.E-	-468	-565	-691	-226	040-	41C1-	-1735	-214:	-2535	-2939	-3334
GAGE S	68-	-104	5992	-385	-500	-611	-765	-907-	-1850	-1184	-1547	-1872	-2245	~2695~	-2976	-3335
60GI: 4	-45	001	-109	いいや	Bre-	-437	-536	- 644	-778	-901	-12-13	2693 .	5.02	-2303	52.22	9716-
C 3000	131-	-243	~367	- 472	-583-	- 709	-861	-1003	-1148	-1277	-1643	-1992	-2375	-2739	-3105	-3652
GAGE 2	-110	-215	-321	910-	-508	-611	-713	-816	5 E3-	-1054	-1368	-1658	6191-	-2535	-2219	-2736
1 3040	-195	-328	- 459	-573	-691	-805	- 935	-1056	-1177	-1295	-1622	-1926	* 3258	-2582	-2963	-3616
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No. Sec. No.

STRAIN DATA FOR PAMEL CCS (AFTER 188,803 CVCLES)

GAGE 14		1 1 1	142-	0801					202		107	376	100	200			+CE3	1554	1716	41 4 7 8 4		C161
GAGE 9	001-		57 2	- 101	1000			156-	-341	1402		-410	952-	-794	1607		-1912	-2115	C06 3-			-2568
GAGE 8	93.			-203	102	1000		- AQ-	-712	861		-979	-1113	- 493	19.00		-2151	-2548	-2882-	8426-		~3556
GAGE 7	-66		1011	-288	001-	14.39		204	-809	61.0-		-1069	-1198	-1564	-1806		9222-	-2578	-2924	- 32C		+EGE-
GAGE 6	-112			-280	-369	- 463			1 548	-785		E85-	-1023	-1420	-1828		-01/0	-2543	-2937	1626-		2005-
CAGE 5	- 78			-261	-367	-476			-757	- 889		-1621	-1157	-1534	-1871		A A A A	-2575	-2941	2000-		68.
GAGE 4	-92	100	001	-261	- 353	1441			-638	-761		R/ 8-	-1661	-1386	-1757	0000	9202-	E+42-	-2221	-3198		22100-
GAGE 3	-79	1905	1	01E-	-432	~539	-794		958-	-986	1110		-1257	-1643	-2011	2200			- 3080	- 0450-		-
GAGE 2	80-	-158		222-	-363	- 456	-566		-6.7	-794	0001		-1928	-1365	-1672	-1070		2000	-2613	- 2934	100CL	
GAGE 1	- 34 4	-153		100	204	-515	-651		A2/-	-003	-1070	07071	-1168	-1527	-1867	- 2100		10440	-2885	-3213	- 7480	
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Sector Sector

STRAIN DATA FOR PAREL CUS AFTER 150,800 CVCLES OF FATIGUE

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	-88	-205	-318	-424	-526	-658	-76%	000-	-1045	-1201	-1549	-1381	-2218	-2573	-2939	-3298	-3286
	-94	201-	312	904	-556	-716	-852	-986	-1:29	-1284	-1643	-, 982	-2316	-2662	900C-	-3335	-3601
	83	-177	-258	380.	-412	-524	-622	-759	-892	-1949	-1439	-1788	-2134	6952-	-2003-	-3299	-3616
	23 68 -	-178	-281	-380	-498	-648	-774	-963	-1048	-1196	-1559	-1900	-2248	-2621	-2996	0466-	-3640
	98- -	-165	-242	-315	568-	-500	-585	-715	448-	E86-	-1344	-1684	-2005-	-2349	-2718	-3082	-3378
	-163	-223	600-	-453	-577	-741	-266	-98-	-1142	-1293	-1673	-2035	-2377	-2732	8606-	-3454	-3740
	-7	-184	662-	+ 8E-	-492	-624	-728	851	-980	-1118	-1439	-1755	-2057	-2386	-2:15	5400-	-3303
	-66	187	416,	9011	558	-718	-844	-975	-111-	-1265	-1617	-1965	-2294	-2633	-2972	BBEE-	-3560
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GAGE 1	- 20	0001		200	1 308	-337	256	956	483	5) •) •		828	1121	1306	1470	1012					19/1	1719	1617	1462
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6 865	0-	-200	-326		21	5	-646	-761	068-	-1037	1110		55671	-1882	-2223	-2564	-2039	-2310	1896-	CD01-			0996-	Cr25-	-5599
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CAGE	-8	-185	-326				2	-854	666-	-1148	-1280			2192-	-2364	-2637-	-3052	-3396	-3743	-4113	-4076			-5279	5015-
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STRAIN DATA FOR SPECIMEN CCS BEFORE FATIONE

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	-79	-176	-274	-377	149%	005-	202-	C¢8~	050-	-1503	-1426	-1757	-2078	-2411	1673-	-3083
	99- -	-168	532-	- 362	-469	-565	-669	-781	-878	938-	-1322	-1620	-1935	-2254	-2568	-2389
	-104	-190	-267	-367	-465	-359	-623	-796	-913	-1058	-1368	-1695	-1969	-2287	-2501	-2921
	-107	-194	-268	-360	-440	-532	-624	-724	-821	616-	-1366	-1718	-1958	1065-	-2637	-2995
	8Ç-	-200	-289	-408	-525	-634	-754	-899	-1034	-1163	-1514	-1351	-2222	-2581		1666-
	-122	-217	-293	+38	-472	-5555	-643	-779	++6-	-1063	-1428	-1771	-2233	-2611	-2989	-3386-
	-74	-165	-254	-377	1902	-623	-758	-897	-1030	-1154	-1500	-1823	-2152	-2478	-2804	-3158
	-85	-193	082-	-384	-487	-584	-691	-808-	-946	-1043	-1391	-1711	-2648	-2377	-2710	-3670
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STRAIN DATA FOR SPECIMEN CC6 AFTER 50,000 CYCLES OF FATIGUE

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CAGEI	- 70	-147	-230	-315	62E-	-457	-593	527	-1206	5141-	-1724	-1911	-1805	X 406	1587	963
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GAOE 8	-129	-235	-350	-478	-588	-722	E48-	-976	-1117	-1245	-1577	-1907	-2229	-2544	-2872	-3201
CACE 7	-105	-201	-315	-427	-518	-621	-713	-812	-944	-1058	-1324	-1630	-2001	-2307	-2632	-2954
CAGE 6	-109	-184	8 82-	846-	-467	-572	-671	-780	-932	-1054	-1381	-1787	-2010	-2286	-2598	-2920
GAGE 5	-77	-157	-246	966-	-413	-500	-579	-669	-832	-960	-1204	-1515	-1929	-2186	-2531	-2967
GAGE 4	-114	-219	BCE-	-468	-560	-689	-784	-915	-1058	-1198	-1514	-1856	-2210	-2539	-2896	-3259
GAGE 3	•	4	0	6	•	9	•	0	0	•	0	0	0	8	0	0
3 3040	-145	-263	966-	-532	-644	-777-	-892	-1031	-1176	-1304	-1621	-1953	-2279	-2598	-2923	- 3246
GROE 1	-113	-209	-316	-426	-516	-625	-719	-818	166-	-1119	-1428	-1753	-2081	-2413	-2752	-3089
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STRAIN DATA FORT SPECIMEN CCG AFTER 109,000 CVCLES OF FATICUE

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GAGE 8		26-	-197	-296	56E	-505	-621	-744	-872	-1010	-1135	-1463	-1801	-2122	-2451	-2809	-3162	-3448
ORCE 7		7	-175	-277	-388	-485	-578	-678	E82-	-968	-1021	-1313	-1607	-1969	-2283	-2626	-2962-	-3235
CAGE B	1	16-	-183	-269	-364	- 452	-546	-659-	-782	-914	-1035	-1355	-1692	-1981	-2264	-2597	-2946	-3220
CAGE 5	1		-177	-262	- 356	-4-13	-5:10	-621	-724	-883	-101-	-1342	-1597	-1985	-2252	-2612	-3090	-3312
CAGE 4	i		-197	-386	-426	-535	-645	-760	P28-	-1038	-1177	-1519	-1849	-2196	-2530	-2910	-3290	-3590
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CACE 1	2	2	-175	-273	646-	14-	-575	-678	-811	÷66-	-1076	-1406	-1725	-2054	-2391	-2749	-3103	-3394
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STRAIN DATA FOR SPECIFEN MCI

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GAGE 7	-54	-174	100-		5.5-	-474	-617	-1183	-1220			-1/64	-2514	-2882-	- 3453			1010-	GAGERZ		90-	-218	440-	1477	-626	-634	-1114	-1156	-1688	-1001-	-828				4391-
CACE 6	- 1 22	200			1001	-523	-656	-849	9201-			-1350	-1695	-2172	Fbbc-			A941-	CACEZI		55-	-190	-143	-182	-221	-583	632-	78	126	154	216	512	281		220
CACE 5	007				285-	-442	-584	-781	1000		-10/B	-1278	-2018	-1803	1 4 2 2		1941	AAAA	CRUEZN)		98-	-194	-281	-378	-461	-268	-458	-718	-762	-796	165-	-1453	-1537		
QAGE 4	100	0 (0 (0 (0 (0 (500	404-	-538	505-	-766		1100	1291-	-1208	-1578	1664-			44001	1681-	GAGE19		18-	-188	-274	E9E-	-456	-131	187	859	597	686	948	1316	1460	1272	1641
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QAGE 1			-11-1	- 326	- 469	0921				-883	-1001-	-1122	-1207	19971		-1888	-3326	-5405	CACE 16		90- -	-218	-346	-477	-626	-871	-1967	-1156	-1327	-1516	-2053	-1911	+665-	-2743	
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CAGE14	-99	-193	1295	805.4		*: ~ *	205-	-698	910-			-1243	-1434			3357	4070		9102																		
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GAGE 10	02) -	- 239	1240		20 0 1	185-	-667	-726		50144	12 L	-1366	0.11		ROCA	2129		1201	2612																		
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gage 5	9627		404		4900-1-	536	-762	000-		-1964	5 N N	-1417			-2140	-2798		1225-	-1915																		
GRACE 7	84.	101-			100-	-596	-834	1.001		-1316	-1561	16/13-			-1368	2366-		キカルワー	-446		GAGERE		\$21-	862-	100×-	1495	-537	-552	90G-	-328	-819	-683	-369	-1166	-130S	-1561	-2452
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STRAIN DATA FOR SPECIFIEN MC3 BEFORE FATIGUE

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CAGE 4
GAGE 3
CACE 2
CACE 1

-112	-231				194-	- 796	010-		CL01-			つかじょう	1661-
-113	-241	846-			508-	455	5			27	5		136
-117	-235	-359	1 4 8 6	- 0 90 1	1620								2887
-112	-226	-345	- 467		100						1010-	-2469	-2528
98-	-157	-243	-335		101					-1256	2251-	-1746	-1969
89-	-192	-204	-266	400-					6/21-	-1417	-1562		-2607
94-1	-189	60E-	164-	-561	-77-		2251-	ワンキュー	-1567	-1649	-1733	-1969	-2025
2		000-	-418	EES-	-657		1911-	-1410	-1707	-1993	-2294	-2765	-3680
		144	-474	-616	662-	-989-	-101-	-1016	-1942	-1063	-1633	-1086	-1107
	-115		EE4-	-569	-760	-883	-2337	-2711	-3006	-3262	-3492	-3734	-3893
		1001	-361	664-	-630	-757	-1995	4161-	-1514	-1780	-1802	-2021	-2273
	8	1911		104-	-543	-633	-854	-987	-1117	-1238			-1623
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STRAIN DATA FOR SPECINEN NC4 BEFORE FATIGUE

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	-128	-232	846-	-455	-555	-656	120	555	857	6993	1256
	-153	-247	-352	-453	-555	-663	-771	-1086	-1267	-1398	-1567
	-87	-187	-286	-378	-462	-537	669-	-749	-888	-986	-1005
	-1-	-185	-311	-428	-538	-644	-834	-987	-1148	-1269	-1396
	801	-100	996-	-411	1992-	-602	-753	-1088	-1272	-1420	-1687
	-105	-205	866-	-448	-563	-675	040-	-1110	-1366	-1448	-1634
	-118	-217	-325	-424-	-516	-609	-738	-1025	-1191	-1313	-1482
	-100	651-	-318	EE\$-	-550	-679	-879	-1968	-1255	-1368	-1551
	-102	-205	526-	-436	663-	-639	-876	-994	-1031	-1114	-1297
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ਗ਼ੑੑੑੑੑੑੑ ^{੶੶੶੶} ੶ਸ਼ਸ਼ਫ਼
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SHEAR PANEL STRAIN DATA

RS1 STATIC TEST

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STRAIN DATA FOR OPECINEM RC4 WITER S3,009 CVCLES OF FATIOUE

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8 7545B	-125	-223	-320	544-	-552	-662	375	1018	1217	1325	1361
ENC.	-130	192~	-358	- 468	-579	-687	-965	-1123	-1265	- 2411	-1551
GNGE 7	66	-179	-276	-372	-455	-524	. 611	864-	448-	-854	-1462
GRIE U	-104	-212	SEC-	-458	-554	-668	-861	3691 .	- 135	-1261	18E3-
CAGE 5	10	-1968	-117	- 424	-921	649-	250-	-1153	-1265	2002-	-1673
GAGE 4	461-	0000-	240	-672-	- 5 R.	-747	-972	-1143	-1205	~1450	-1613
CAGE 3	-118		- 10-	-417	-507	929-	-882	-1840	-1182	-1339	-1502
CAGE 2	-126	10,00	1221			-776	-023	-1117	-1261	-1413	-1563
CLAQE 1	-11.7	8.01		000		100	212-	946-	-1056	-1168	-1270
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	-107	1991	121-	-388	-470	-536	-594	+3.2-	-518	028-	-1025	0521-	-2063	-2442	-3483
	3	-211	-321	504-	-539	-653	-860	+68-	-1131	-1261	-1361	-1556	-2436	-2681	-2318
	-107	-21.	10101	679-	-518	645	1090	-1163	-1357	-1589	-1834	-2845	-1740	-1857	-1535
	-123	-241	-351	-977	-598	-755	-1690	-1168	-1345	-1522	-1663	-2026	-2516	-2757	-3151
	201-	-204	062-	0941	-492	-671	-967	-1050	-1207	-1359	-1487	-1776	-1796	-1810	-1536
	961	-210	+90e-	-463	-584	-801	-1013	-1173	-1347	-1521	-1663	-2001	-2417	-2784	- 3250
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A.2 SHEAR PANEL STRAIN DATA

The strain data obtained from all shear panel static tests and fatigue strain surveys are tabulated in this appendix. The nomenclature for the strain gages in the following tables differs from that shown in Figure 3.13. The correspondence Table A-2 below should be used to correlate the gage numbers in the strain data tables with the locations shown in Figure 3.13.

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GAGE NO. IN FIGURE 3.13	TYPE OF GAGE	GAGE NO. IN DATA TABLES
1E	Rosette	1
		2
		3
	Rosette	4
		5
		6
2F	Rosette	7
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3E	Resette	13
		14
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3I	Rosette	16
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ζ.E	Rosette	19
		20
		21
41	Rosette	22
		23
		24
6E	Axial	25
61	Axial	26
8E	Axial	27
8T	Axial	
95	Avial	29
91	Avial	30
	Avial	31
	Avial	31
	AXIAI	32
111	AX181	
111	AXIAL	
12E	Axial	
	Axial	36
<u>13E</u>	Axial	37
<u> </u>	Axial	38
5E	Shear	39
		40
51	Shear	41
		42
7E	Shear	43
	1	44
71	Shear	45
		46

TABLE A-2. SHEAR PANEL GAGE CORRESPONDENCE TABLE. GAGES ORIENTED AS SHOWN IN FIGURE 3.13.

NOTES: (1) Gages 8 through 13 omitted from fatigue test panels and gages 5 and 7 assigned numbers 27 through 34 in the data tables.

(2) After 50,000 cycles of fatigue on specimen CS4, gages 3E, 3I and the first kg of 2E were lost. All remaining strain channels numbered onsecutively.

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METAL SHEAR PANEL HS2 STATIC TEST

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CRCE13	<u>.</u> የ		214				\$32.	497.	506.	789.	939	384	5	50			20	1211.	1510.	1780.	1988.	2133.	2284.	25.01.	2812.	3138.	3465.	
CAGE12	ŗ	1	• • • • •	-174.	-265-	- 19E -	-451.	-527.	-648.	1285.	LEBI	60 20		10.00			2410.	3316.	. 458	4901.	5294.	5424.	5648.	5992	6228.	6565.	5740.	
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CHOE D	ŗ	-46.	-118.	-178.	-269.	- 336	-421.	8.V-	-516.	- 707 -		2006				-4221.	-4474.	-4687.	-4622.	- 4530.	-4459.		2929-			-3810.	-162E-	
CARE 8	-11.	-14.	-18.	-18.	ង់	ų.	R.	ร้า	5	100						-3651.	-4147.	- 4865	-4340.	-6143.		- ACCOMP	- 2010			2004	-2801	
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CONTOSTIE SHEAR PLANL CS2 STATIC TEST

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CORPOSITE FATICUE SHEAR PAREL CS4 STRAIN SURVEY

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CORPOSITE FATICLE SHERR PAREL CG3 STRAIN SUPLEY AFTER 100,040 CYCLES

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COMPOSITE FWIICHE SHEAR PANEL CS4 STRAIN SURVEY AFTER 50,080 CVCLES

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COMPOSITE FATICLE SPEAR PANEL CSA STRAIN SURVEY AFTER 100,030 CYCLES

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ڲ ۿڣڣۻڹڹڹڹڋڗڋۿڮؖۊ**ؾۊؾڝ**ڐڟڋڣڣڣڣ ؈ڡڣۻڹڹڹڹڋڗڋۿڮۿڟڂؿۺڣڟۿڎڎۻڣۼڣ UTUKERYENE SCHUDDESSER

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APPENDIX B

COMPRESSION PANEL ANALYSIS

In this appendix, expressions for the functions $F_{ijkl}^{\alpha\beta}$ in Equation 40 for compression panel total potential energy are given. The nomenclature used is as follows:

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where,

$$\Theta_{n=in\pi}$$
 and $i=\sqrt{-i}$
 $C_{r}=\frac{i}{2}$, $S_{r}=\frac{E_{r}}{2i}$ and $E_{r}=(-1)^{i}$
 $N=1, \dots, N$, $M=1, \dots, M$ and $h=1, 2$

Repeated indices imply summation.

$$\iint \mathcal{U}_{i,\overline{5}}^{t} d\overline{5} d\gamma = Anm Apq F_{inmpq} + 2Anm Q_{i} a F_{2,nm}^{t} + Q_{i}^{2} a^{2}$$

$$F_{inmpq}^{t} = \iint \left[\phi_{n}^{c} (1 - \phi_{i}^{c}) \right]_{i,\overline{5}} \mathcal{V}_{m}^{c} \left[\phi_{p}^{c} (1 - \phi_{i}^{c}) \right]_{i,\overline{5}} \mathcal{V}_{p}^{c} d\overline{5} d\eta$$

$$F_{2,nm}^{t} = \iint \left[\phi_{n}^{c} (1 - \phi_{i}^{c}) \right]_{i,\overline{5}} \mathcal{V}_{m}^{c} d\overline{5} d\eta$$

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$$\iint_{0}^{12} W_{,s}^{2} ds d\eta = C_{nm} C_{pq} C_{rs} C_{tu} F_{inmpoqrstu}^{12}$$

$$F_{inmpqrstu}^{12} = \iint_{0}^{12} \varphi_{n,s}^{s} \psi_{m}^{s} \varphi_{ps}^{s} \psi_{q}^{s} \varphi_{r,s}^{s} \psi_{s}^{s} \varphi_{t,s}^{s} \psi_{u}^{s} ds ds dy$$

$$\iint_{a} \mathcal{W}_{i}^{2} d\xi d\eta = \operatorname{Anm} \operatorname{Cpq} \operatorname{Crs} F_{inmpqrs}^{13} + \operatorname{Q}_{i} \operatorname{Cpq} \operatorname{Crs} \operatorname{Q}_{i} F_{2}^{13} p_{qrs}^{3}$$

$$= \iint_{a} \left[\left[\mathcal{P}_{n}^{c} (1 - \mathcal{P}_{i}^{c}) \right]_{i}^{2} \mathcal{V}_{m}^{c} \mathcal{P}_{p,z}^{s} \mathcal{V}_{q}^{s} \mathcal{P}_{r,z}^{s} \mathcal{V}_{s}^{s} d\xi d\eta \right]$$

$$= \int_{a}^{b} \left[\mathcal{P}_{p,z}^{c} \mathcal{V}_{q}^{s} \mathcal{P}_{r,z}^{s} \mathcal{V}_{s}^{s} d\xi d\eta \right]$$

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$$\int_{0}^{2} u_{ig} v_{i\eta} dg d\eta = Anm \, Bpg \, F_{i} nmpq + Anm \, b_{j} \, b \, F_{2nm} + a_{i} Bpg \, a \, F_{3pg}^{2} + a_{ki} a_{i}$$

$$F_{inmpq}^{a} = \iint_{0}^{i} \left[\mathcal{A}_{i}^{c} (i - \mathcal{A}_{i}^{c}) \right]_{g} \mathcal{V}_{m}^{c} \mathcal{A}_{g}^{c} \mathcal{V}_{g}^{g} q \, dg \, dg$$

$$F_{2nm}^{a} = \iint_{0}^{i} \left[\mathcal{P}_{n}^{c} (i - \mathcal{A}_{i}^{c}) \right]_{g} \mathcal{V}_{m}^{c} \, dg \, dg \, \eta$$

$$F_{3pq}^{a} = \iint_{0}^{i} \mathcal{P}_{p}^{c} \mathcal{V}_{g,\eta} \, dg \, dg \, \eta$$

$$\int_{0}^{a} u_{ig} \mathcal{V}_{i\eta}^{c} \, dg \, dg \, \eta = Anm \, Cpg \, Cs \, F_{inmpq}^{a2} + a_{i} Cp_{i} \, Cs \, a \, F_{2pq}^{a2}$$

$$F_{inimpq,rs}^{s} = \iint \left[\varphi_n^c (1 - \varphi_i^c) \right]_{s} \psi_m^c \varphi_s^s \psi_{q,\eta}^s \varphi_s^s \chi_{q,\eta}^s ds d\eta$$

$$F_{2pq,rs}^{s} = \iint \varphi_p^o \psi_{q,\eta}^s \varphi_r^s \chi_{q,\eta}^s ds d\eta$$

$$\int_{0}^{23} \psi_{ij} \psi_{ij}^{2} d\xi d\eta = g_{nm} Cpq Crs F_{inm}^{23} pq rs + b_{i} Cpq Crs b F_{2}pq rs$$

$$F_{inm}^{23} F_{inm}pq r = \iint_{0}^{3} \varphi_{n}^{2} \psi_{n,\eta}^{2} \varphi_{r,\xi}^{3} \psi_{q}^{2} \varphi_{r,\xi}^{3} \psi_{s}^{3} d\xi d\eta$$

$$F_{2}pq rs = \iint_{0}^{3} \varphi_{p,\xi}^{3} \psi_{q}^{3} \varphi_{r,\xi}^{3} \psi_{s}^{3} d\xi d\eta$$

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$$\iint_{0}^{2} W_{5}^{2} W_{7}^{2} d\xi d\eta = C_{nm} C_{pq} C_{rs} C_{tu} F_{1}^{24} m_{pq} rs tu$$

$$F_{1}^{22} F_{1}^{22} m_{pq} rs tu = \iint_{0}^{2} \varphi_{75}^{3} \psi_{m}^{3} \varphi_{75}^{3} \psi_{7}^{3} \varphi_{7}^{5} \psi_{77}^{3} \varphi_{t}^{5} \psi_{0,7}^{3} d\xi d\eta$$

$$\left\| W \mathcal{U}_{,\sharp} d\xi d\eta = Cnm Apq F_{inmpq}^{25} + Cnm A_{i} \alpha F_{2nm}^{25} \right\|$$

$$F_{inmpq}^{25} = \iint \varphi_n^s \psi_m^s \left[\varphi_p^c (1 - \varphi_1^c) \right]_{3} \psi_q^s d\xi d\eta$$

$$F_{2nm}^{25} = \iint \varphi_n^s \psi_m^s d\xi d\eta$$

$$\iint_{0}^{24} W W_{f} = Cnm Cpq Crs F_{jnmpqrs}^{26}$$

$$F_{jnmpqts} = \iint_{0}^{24} \varphi_{n}^{3} \psi_{n}^{3} \varphi_{p,3}^{3} \psi_{q}^{2} \varphi_{n,3}^{3} \psi_{s}^{4} d_{5} d_{9}$$

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$$\iint_{n}^{2} \sqrt{3} d\xi d\eta = Bnm Bpq F_{i} \frac{3!}{mmpq} + 2Bnm b_{j} bF_{2}^{3!} m + b_{j}^{2} b^{2}$$

$$F_{i}^{3!} pq := \iint_{n}^{j} \varphi_{n}^{s} \varphi_{m,\eta}^{c} \varphi_{p}^{s} \varphi_{q,\eta}^{c} d\xi d\eta$$

$$F_{2}^{3!} m = \iint_{n}^{j} \varphi_{n}^{s} \varphi_{m,\eta}^{c} d\xi d\eta$$

$$\iint_{n} W_{n}^{*} d\xi d\eta = Cnm Cpq. Crs. Ceu Finmpqrstu
F_{1nmpqrstu,}^{32} = \iint_{n} \varphi_{n}^{*} \mathcal{W}_{n,\eta}^{*} \mathcal{Y}_{p}^{*} \mathcal{Y}_{q,\eta}^{*} \mathcal{Y}_{n,\eta}^{*} \mathcal{Y}$$

 $\iint_{0}^{1} W^{2} d\xi d\eta = Cnm Cpq_{\pi} t_{1}^{33}$ $F_{TMM}^{23} = \iint_{0}^{1} \varphi_{n}^{s} \psi_{n}^{s} \varphi_{p}^{s} \psi_{p}^{s} d\xi d\eta$

$$\iint_{0}^{34} W W, \eta d\xi d\eta = Chim Cpc F_{inm,pq}^{34}$$

$$F_{inm,pq}^{34} = \iint_{0}^{3} \varphi_{n}^{s} \psi_{n}^{s} \varphi_{p}^{s} \psi_{q,\eta}^{s} d\xi d\eta$$

$$\iint \mathcal{Y}_{n} \mathcal{W}_{n}^{2} d\xi d\eta = Bnm Cpq Crs F_{inimpq,rs}^{35} + b_{i}Cpq Crs & F_{2}pqrs$$

$$F_{inimpq,rs}^{37} = \iint \mathcal{Y}_{n}^{3} \mathcal{W}_{n,\eta}^{c} \mathcal{P}_{p}^{s} \mathcal{Y}_{p,\eta}^{s} \mathcal{P}_{r}^{s} \mathcal{Y}_{s,\eta}^{s}$$

$$F_{2}pq,rs = \iint \mathcal{P}_{r}^{s} \mathcal{Y}_{q,\eta}^{s} \mathcal{P}_{r}^{s} \mathcal{Y}_{s,\eta}^{s} d\xi d\eta$$

$$\begin{aligned} & W W_{,\eta}^{2} d\xi d\eta = lnm Cpq Crs F_{inmpqrs}^{36} \\ & F_{inmpqrs}^{36} = \iint \varphi_{n}^{s} \psi_{n}^{s} \varphi_{r}^{s} \psi_{r\eta}^{s} d\xi d\eta \\ & = \iint \varphi_{n}^{s} \psi_{n}^{s} \psi_{r\eta}^{s} \varphi_{r}^{s} \psi_{r\eta}^{s} d\xi d\eta \\ & = \iint \varphi_{n}^{s} \psi_{n}^{s} \psi_{r\eta}^{s} \varphi_{r}^{s} \psi_{r\eta}^{s} d\xi d\eta \\ & = \iint \varphi_{n}^{s} \psi_{n}^{s} \psi_{r\eta}^{s} \varphi_{r}^{s} \psi_{r\eta}^{s} d\xi d\eta \\ & = \iint \varphi_{n}^{s} \psi_{n}^{s} \psi_{r\eta}^{s} \psi_{r\eta}^{s} d\xi d\eta \\ & = \iint \varphi_{n}^{s} \psi_{r\eta}^{s} \psi_{r\eta}^{s} d\xi d\eta \\ & = \iint \varphi_{n}^{s} \psi_{r\eta}^{s} \psi_{r\eta}^{s} d\xi d\eta \\ & = \iint \varphi_{n}^{s} \psi_{r\eta}^{s} \psi_{r\eta}^{s} d\xi d\eta \\ & = \iint \varphi_{n}^{s} \psi_{r\eta}^{s} \psi_{r\eta}^{s} \psi_{r\eta}^{s} d\xi d\eta \\ & = \iint \varphi_{n}^{s} \psi_{r\eta}^{s} \psi_{r\eta}^{s} d\xi d\eta \\ & = \iint \varphi_{n}^{s} \psi_{r\eta}^{s} \psi_{r\eta}^{s} d\xi d\eta \\ & = \iint \varphi_{n}^{s} \psi_{r\eta}^{s} \psi_{r\eta}^{s} \psi_{r\eta}^{s} d\xi d\eta \\ & = \iint \varphi_{n}^{s} \psi_{r\eta}^{s} \psi$$

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$$\iint_{n} \mathcal{U}_{n}^{2} d\xi d\eta = Anm Apq Finmpq$$

$$F_{inmpq}^{4'} = \iint_{0} \phi_{n}^{c} \mathcal{V}_{m,\eta}^{c} (1-\phi_{1}^{c})^{2} \phi_{p}^{c} \mathcal{V}_{q,\eta}^{c} d\xi d\eta$$

$$\iint \mathcal{V}_{is}^{2} ds d\eta = Bnm Bpq F_{inmpq}^{42}$$

$$F_{inmpq}^{42} = \iint \mathcal{P}_{n,s}^{s} \mathcal{V}_{m}^{c} \mathcal{P}_{p,s}^{s} \mathcal{V}_{q}^{c} ds d\eta$$

$$\iint \mathcal{U}_{i,\eta} \mathcal{V}_{i,\xi} d\xi d\eta = Anm Bpg Finmpq$$

$$F_{inmpq}^{44} = \iint \mathcal{P}_{n}^{c} \mathcal{V}_{m,\eta}^{c} (1-\mathcal{P}_{i}^{c}) \mathcal{P}_{p,\xi} \mathcal{V}_{q}^{c} d\xi d\eta$$

$$\begin{aligned}
\int_{0}^{4} u_{,\gamma} w_{\xi} w_{,\gamma} d\xi d\gamma &= Anm Cpq. Crs F_{inimpq.rs}^{st} \\
F_{inimpq}^{st} &= \iint_{0}^{4} d_{x}^{c} \psi_{m,\gamma}^{c} (1-d_{x}^{c}) \phi_{p\xi}^{s} \psi_{p\gamma}^{s} d\xi d\gamma \\
&= \iint_{0}^{4} d_{x}^{c} \psi_{m,\gamma}^{c} (1-d_{x}^{c}) \phi_{p\xi}^{s} \psi_{p\gamma}^{s} d\xi d\gamma \\
&= \iint_{0}^{4} d\xi d\gamma = Bnm Cpq. Crs F_{inimpq.rs}^{st} \\
F_{inimpq,rs} &= \iint_{0}^{4} \phi_{n\xi}^{s} \psi_{n\gamma}^{s} \phi_{p\xi}^{s} \psi_{p\gamma}^{s} d\xi d\gamma \\
&= \iint_{0}^{4} d_{n\xi}^{s} \psi_{p\gamma}^{s} d\xi d\gamma = Cnm Cpq. F_{inimpq.}^{st} \\
F_{inimpq}^{s} &= \iint_{0}^{4} d_{m\xi}^{s} \psi_{n\gamma}^{s} \phi_{p\xi}^{s} \psi_{p\gamma}^{s} d\xi d\gamma \\
&= \iint_{0}^{4} d_{m\xi}^{s} \psi_{n\gamma}^{s} d\xi d\gamma = Cnm Cpq. F_{inimpq.}^{st} \\
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&= \iint_{0}^{4} d_{m\xi}^{s} \psi_{n\gamma}^{s} d\xi d\gamma \\
&= \iint_{0}^{4} d_{\eta\xi}^{s} \psi_{n\gamma}^{s} d\xi d\gamma \\
&= \iint_{0}^{4} d_{\eta\xi}$$

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$$\iint_{n} W_{55} W_{57} d\xi d\gamma = C_{nm} C_{pq} F_{inmpq}^{53}$$

$$F_{jampq}^{53} = \iint_{n} W_{n55} \Psi_{m}^{5} \Psi_{n55}^{5} \Psi_{p,\eta}^{5} d\xi d\eta$$

$$\iint_{n} W_{\eta\eta}^{2} d\xi d\eta = C_{nm} C_{pq} F_{inmpq}^{54}$$

$$F_{inmpq}^{54} = \iint_{n} \Psi_{n,\eta\eta}^{5} \Psi_{p,\eta\eta}^{5} d\xi d\eta$$

$$\iint_{n} W_{\eta\eta} W_{57} d\xi d\eta = C_{nm} C_{pq} F_{inmpq}^{55}$$

$$\iint_{n} W_{\eta\eta} W_{57} d\xi d\eta = C_{nm} C_{pq} F_{inmpq}^{55}$$

$$F_{inmpq}^{55} = \iint_{n} \Psi_{n,\eta\eta}^{5} \eta \varphi_{p,5}^{5} \Psi_{p,\eta}^{5} d\xi d\eta$$

$$\iint_{n} W_{i5\eta} d\xi d\eta = C_{nm} C_{pq} F_{inmpq}^{55}$$

$$\iint_{n} W_{i5\eta} d\xi d\eta = C_{nm} C_{pq} F_{inmpq}^{55}$$

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$$F_{inmpg}^{5c} = \iint_{0}^{f} \varphi_{n,5}^{s} \psi_{m,\eta}^{s} \varphi_{p,5}^{s} \psi_{q,\eta}^{q} d5 d\eta$$

$$\int \mathcal{U}_{i\xi} d\xi = Anm Apq_{i} F_{inmpq_{i}}^{S1} + 2Anm a_{i} a F_{inm}^{S1} + a_{i}^{2} a^{2}$$

$$F_{inmpq_{i}}^{S1} = \int \left[\mathcal{P}_{n}^{c} (1 - \mathcal{P}_{i}^{c}) \right]_{i\xi} \mathcal{V}_{m}^{c} \left[\mathcal{P}_{p}^{c} (1 - \mathcal{P}_{i}^{c}) \right]_{i\xi} \mathcal{V}_{q}^{c} \right] d\xi$$

$$\eta = 0$$

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$$F_{2nm}^{5l} = \int_{0}^{l} \left[\mathscr{I}_{n}^{c} (l - \mathscr{I}_{l}^{c}) \right]_{j, \sharp} \mathscr{V}_{m}^{c} d\xi.$$

$$\eta = 0$$

$$\int_{0}^{2} \sqrt{3} \xi = Bnm Bpq F_{inmpq}^{32}$$

$$F_{inmpq}^{32} = \int_{0}^{2} p_{n,55}^{n} \sqrt{p_{n,55}} \sqrt{q} d\xi$$

$$= \int_{0}^{2} p_{n,55}^{n} \sqrt{p_{n,55}} \sqrt{q} d\xi$$

$$= \int_{0}^{2} q_{n,55}^{2} \sqrt{q} d\xi$$

$$\int_{0}^{1} \sqrt{2\eta} \, d\eta = B_{nm} \, B_{pq} - F_{inmpq}^{Fl} + 2 B_{nm} \, b_{l} \, b \, F_{2nm} + b_{l}^{2} b^{2}$$

$$F_{inmpq}^{Fl} = \int_{0}^{1} \varphi_{n}^{S} \, \psi_{n,\eta}^{C} \, \varphi_{p}^{S} \, \psi_{q,\eta}^{C} \, d\eta$$

$$F_{inmpq}^{Fl} = \int_{0}^{1} \varphi_{n}^{S} \, \psi_{n,\eta}^{C} \, \varphi_{p}^{S} \, \psi_{q,\eta}^{C} \, d\eta$$

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$$F_{2nm}^{F'} = \int_{0}^{1} \varphi_{n}^{S} \psi_{m,\eta} d\eta$$

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$$\int \mathcal{U}_{i,\eta\gamma}^{2} d\eta = A_{nm} A_{pq} F_{inmpq}$$

$$F_{inmpq}^{F2} = \int \mathcal{P}_{n}^{c} \mathcal{P}_{m,\eta\gamma}^{c} (1 - \mathcal{P}_{i}^{c})^{2} \mathcal{P}_{p}^{c} \mathcal{V}_{q,\eta\gamma}^{c} d\eta$$

$$F_{inmpq} = \int \mathcal{P}_{n}^{c} \mathcal{P}_{m,\eta\gamma}^{c} (1 - \mathcal{P}_{i}^{c})^{2} \mathcal{P}_{p}^{c} \mathcal{V}_{q,\eta\gamma}^{c} d\eta$$

$$F_{inmpq}^{F2} = \int \mathcal{P}_{n}^{c} \mathcal{P}_{m,\eta\gamma}^{c} (1 - \mathcal{P}_{i}^{c})^{2} \mathcal{P}_{p}^{c} \mathcal{V}_{q,\eta\gamma}^{c} d\eta$$

$$\begin{split} F_{inmpq}^{"} = \iint_{0}^{n} \left[\left(\mathcal{I}_{n}^{c} \left(1 - \mathcal{I}_{1}^{c} \right) \right)_{s} \left[\left(\mathcal{I}_{p}^{c} \left(1 - \mathcal{I}_{1}^{c} \right) \right)_{s} \left[\left(\mathcal{I}_{p}^{c} \left(1 - \mathcal{I}_{1}^{c} \right) \right)_{s} \left[\left(\mathcal{I}_{p}^{c} \left(1 - \mathcal{I}_{p}^{c} \right) \right)_{s} \left[\left(\mathcal{I}_{p}^{c} \left(1 - \mathcal{I}_{p}^{c} \right) \right)_{s} \left(1 - \mathcal{I}_{p}^{c} \right) \right]_{s} \left[\left(\mathcal{I}_{p}^{c} \left(1 - \mathcal{I}_{p}^{c} \right) \right)_{s} \left(1 - \mathcal{I}_{p}^{c} \left(1 - \mathcal{I}_{p}^{c} \right) \right)_{s} \left(1 - \mathcal{I}_{p}^{c} \left(1 - \mathcal{I}_$$

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