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INVESTIGATION OF POLAR MOTION FROM DOPPLER TRACKING OF THE NAVY NAVIGATION SATELLITE SYSTEM DURING THE MERIT CAMPAIGN

WILLIAM H. WOODEN, JOHN A. BANGERT, AND J. MILO<sup>®</sup>ROBINSON DEFENSE MAPPING AGENCY WASHINGTON, DC 20305, USA

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## SUMMARY

For more than a dozen years, Doppler tracking of the Navy Navigation Satellite System (NNSS) has demonstrated the ability to give solutions for polar motion as a byproduct of precise ephemerides generation. This paper reviews the polar motion estimation process at the Defense Mapping Agency from Doppler measurements of the NNSS and gives comparisons to polar motion series from newer observational techniques and to the Bureau International de l'Heure (BIH) Circular-D series. The different techniques are compared for the period of the MERIT Main Campaign. In addition to comparing results for the Nova and Oscar NNSS satellites, comparisons are done utilizing the WGS 84 and the NWL 972 gravitational fields in the precise ephemerides generation process.

## 1.0 INTRODUCTION

Since the late nineteenth century, it has been recognized that the instantaneous spin axis of the Earth moves with respect to the geographic pole of the Earth's crust. This "polar motion" was predicted by Euler in 1752, but was not conclusively observed until kuenstner s work in 1884-86. The International Latitude Service (ILS) was established in 1899 to continuously monitor the motion of the pole by maxing systematic determinations of latitude. With the nevelopment of new astrometric instruments during the LeSus and these use at the national observatories, it was decided to reorganize the LES into the International Polar Monitoring Bervice (IPMS) in 1952 with the charter of deriving polar motion from latitude and universal time data of all astronomical instruments.

The Bureau International de l'Heure (BiH) was created to 1PtZ to unity time by publishing the time or emission (in usiversal times of radio time signals. Wich the sovent of elemic time standards in 1.955 and the need to account for prior motion in a timely manner tor Uff determination. tne 31H Decian to doternine its own set of coordinates of the pule from Lamburg data supplied tγ participating observatories. Until 1972, the BiH used only the same data as the LEMS so a complete overlap of functions with the IEMS evisted. Since 1972, pole positions based on Doppler observations of the Navy Navigation Satellite System (NNSS)

satellites have been incorporated into the BIH global solution. The methods used by the BIH in the treatment of data are given by Feissel [1].

Research at the Naval Weapons Laboratory (now the Naval Surface Weapons Center) by Anderle and Beuglass [2] demonstrated that it was possible to use Doppler observations of NNSS satellites to compute pole positions. Doppler solutions of pole position have been distributed by the Dahlgren Polar Monitoring Service since 1969. The pole positions are a byproduct of the orbit computation process. Hence, when the responsibility of computing the NNSS satellite orbits was transferred to the Defense Mapping Agency (DMA) in 1975, the derivation of pole position was continued by DMA. The DMAHTC Polar Monitoring Service (DPMS) reports are distributed by the Hvdrographic/ Topographic Center of DMA to users on a weekly or monthly basis.

Project MERIf [3] was a program of international collaboration to monitor Earth rotation and intercompare techniques of observation and analysis. The MERIT Main Campaign of observations was held during the period September 1, 1983, to October 31, 1984 and included a variety of techniques for determining polar coordinates.

## 2.0 COMPUTATIONAL METHODS FOR DOPPLER DATA

The pole determination method utilized by DNA is the method adopted by the Naval Surface Weapons Center (NSWC) in August 1971. The brief description of the method that follows is taken, from the detailed description of the observational procedures and the data reduction techniques given by Anderle [4].

Doppier observations are mane daily by a network of approximately do worldwide tracking stations controlled by DMA and a network of 4 U.S. tracking stations controlled by the Nevy Astronautics Group, Ail observations taken in a AS noun period are processed with the CELESF computer program [5]. A teast-squares solution is obtained which includes the sign constants of orbital integration. A drag ecaling factor for each day, a frequency and a troopspheric restantion scaling factor for each pass, the two components of the pole position, and the courdinates on any mobile alservion station. The least-squares solution is pased on dimensional between the observations and computed data, which consequed to a predicted sevenite orbit. Ine succel conductors for the equations of motion come from the presente day a rule rul. The integration scheme is a (Promunder Cower, with a operinder stepsize. The outhemorical model includes the Earth's gravitational field, absolutions, drag, solar radiation pressure, luni-solar

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gravity perturbations, and solid Earth tidal forces. The integration is done in the true-of-date system.

The accuracy of the orbit determination process is reflected by two statistics: the discontinuity in the ephemeris at the ends of each 2-day span and the root mean square of the residuals of the least-squares adjustment process. The current accuracy of the ephemerides is approximately three meters according to Murphy and Fell [6]. This value agrees with the previous values given by Bowman and Leroy [7] and Wooden [8].

During the MERIT Campaign, four NNSS satellites were used at DMAHTC: three "Oscar-type" satellites (DMA 60=1767-92A, DMA 68=1970-67A, and DMA 59=1967-48A) and one "Nova-type" satellite (DMA 105=1981-44A). The Nova satellite is equipped with sensors and thrusters which compensate for non-conservative forces in the direction of the velocity vector. Thus, polar motion results from the Nova satellite are largely unaffected by variations in solar activity.

## 3.0 ANALYSIS OF DUPPLER FOLAR MOTION VALUES

The most important components of polar motion are terms with a Chandler period (420-435 days) and terms with an annual period. The annual motion is believed to be due to seasonal variations such as meteorological effects of changes in air masses over the Earth and changes in vegetation and snow loading. The Chandler motion is a consequence of the fact that the inertial spin of the Earth is about an aris other than its principal axis of inertia.

In an entempt to highlight other geophysical properties or the dotion and trastrumental errors between series of Each orientation parameters, the dominant annual and Chandler motions and a bias were removed by fitting a fiveparameter expression of the following form to each component of polar motion:

 $f(t) = H_1 + H_2 \cos H + H_3 \sin H + H_4 \cos (1 + H_3 \sin (1 + 1))$ 

where  $A = (2 \Pi t/255.25)$   $C = (C \Pi t/435)$  $h_1, h_2, h_3, h_4, H_6 = Coetticients of the fit$ 

in the enalysis that follows, the two types of NNSS satellites are compared with each other and the SIH Cincular-D values. Special data sets are created for concernson with other Farth orientation parameter series.

## 3.1. COMPARISON OF OSCAR-TYPE AND NOVA-TYPE NNSS SATELLITES

The differences between the bi-daily values for each individual NNSS satellite and the BIH Circular-D values for the MERIT period are shown in Figure 1. Unfortunately, only the Nova satellite (DMA 105) has observations for the entire MERIT timespan. Although the x and y curves for this satellite have different biases, they show similar behavior with a time offset of approximately 30 days. Tne x components of Oscar satellites, DMA 59 and DMA 60, tend to follow the Nova satellite curve, while DMA 68 appears to have periodic oscillations about a constant offset. The v components of the Oscar satellites show less variation than the x components. The scatter associated with the Nova satellite values is much smaller than the scatter in the Oscar satellite values. The statistics associated with these comparisons are given in Table 1. The means and standard deviations in the table are in arc seconds. The number of observations is given in the column labeled n. The second set of means and standard deviations in Table 1 🎬 taken from the study by Colquitt, Stein, and Anderle [9].

SERIES	X-MEAN	SIGMA-X	Y-MEAN	SIGMA-Y	N	X-MEAN	SIGMA-X	Y-MEAN	SIGMA-Y
105-BIH	009	.015	.007	.015	217				·
59-81H	.005	.016	.007	.013	65	1			
60-8IH	003	.025	.002	.016	103	1			
68BIH	010	.018	.012	.015	154		,		
68-60	007	.031	.010	.022		008	.037	.015	.031
59-60	.008	.024	.004	.021		007	.029	.001	.023
105-60	006	.023	.005	.022		~.009	.026	.010	.024

TABLE 1. STATISTICS FOR THE OSCAR - NOVA COMPARISONS

In addition to examining the new observations of the incovioual satellites, esecial data sets of 5-day means were created from the individual bi-dariv values for the Oscar satellites and for the Mova satellite to make comparisons on the standard polar motion days. These two data sets are designated NOVA and USCAR. Using these special data sets, the brases and the annual and Chandler motions were removed aroun the observations by means of Equation 1. Figure 2 gives the differences datween the residuals of the fits. The largest differences datween the residuals of the fits. The largest differences catween 200 and 300 days into the MCGIT timespan. The statistics associated with these sits world to diver in the next section.

## 1... COMPARIEON OF COMPLET GATELLITE OBSCRUATIONS WITH DINER G-219 03 GENERILOH CATA TYPES

To examine the despitesical information in each. Earth orientation series, separate least-squares fits for the x and y components of the position were made using Equation 1.



#### DIFFERENCES BETWEEN NNSS AND BIH POLE VALUES FIGURE 1.



to remove the annual and Chandler information. The 41 VE free parameters of the fits were the mean position of the pole and the amplitudes of the sine and cosine terms of the annual and Chandler motions. Table 2 gives the results of these fits for each data type. The entries of Table 2 are expressed in arc seconds. The BIH series is the Circular-D final values. SLR is the satellite laser ranging series of the University of Texas. VLBI is the Very Long Baseline Interferometry series of the National Geodetic Survey. The SLR and VLBI data were taken from a magnetic tape provided by the US\_ Naval Observatory. DMA is the normal combined solution of weighted means of individual satellites published by DMA on 5-day intervals in the DPMS reports. NOVA and OSCAR are the special 5-day means discussed previously.

## TABLE 2. AMPLITUDES OF THE FITTED PARAMETERS

x - component	ponent
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## y - component

Data Set	bias	cos A	sin A	cos C	sin C	sigma	bias	cos A	sin A	cos C	sin C	signa
	11											
£1H	.046	.059	008	.206	093	.008	.282	.014	057	115	178	. ŬŬ6
SLR	.046	.062	016	.206	083	.010	.272	.012	050	115	185	.007
VLBI	.046	.073	.008	.178	107	.006	.277	.004	059	114	180	.006
DMA	.039	.064	.002	.193	105	.009	.289	.017	059	120	178	.007
NOVA	.036	.060	.004	.192	114	.009	.287	.021	051	133	178	.007
OSCAR	.039	.074	.008	. 182	108	.013	.289	.019	060	125	179	.010

Figure 3 shows the residuals of the fits whose fitted parameters are given in Table 2. The smooth line in each plot represents a 7-point moving average of the quantity being plotted. As is evident from the figure, the geophysical information is similar for all data types, i.e., the major peaks agree. All the plots of the Y value residuals exhibit a semiannual period although the OSCAR residuals show an extra hump at 200 days. The X component does not exhibit a semiannual period, but has a distinct signature. The differences in the plots occur between 200 and 300 days. BlH and VLB1 are relatively flat in that interval, whereas all the other data sets have a small peak. SLR has its peak at 275 days and NOVA has its peak at 230 days. Again the OSCAR residuals are most different with a large peak at 215 days. Paquet, Djurovic, and Techy [10] also note the similarity of the geophysical information in their residual plots.

To further differentiate subtle differences between the Earth orientation parameter series shown in Figure 3, the residuals of the fits were differenced. The results of this process are shown in Figures 4 through 9. Note that Figure 2 presents results of this process for the NOVA and OSCAR series.



## FIGURE 3. RESIDUALS OF THE FIVE-PARAMETER FITS FOR THE EOP SERIES

TIME (days)

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## 4.0 PRELIMINARY EVALUATION OF POLE POSITIONS COMPUTED USING WORLD GEODETIC SYSTEM 1984

Biases between polar motion solutions using different NNSS satellites have been shown to result from uncertainties in knowledge of the Earth's gravity field [11]. The question arises as to whether the development of the World Geodetic System 1984 (WGS 84) and its associated Earth Gravitational Model (EGM), as discussed by Decker [12] and White [13], can improve the pole position solutions. As part of (tests) of ephemeris generation) using WGS 84 (see, for example, [14]), a number of NNSS ephemerides based on WGS 84 have been computed at DMAHTC using the CELEST program. Of particular interest was an interval, beginning in late May and ending in early July 1985, within which WGS 84 precise ephemerides for 5 NNSS satellites were produced on a regular basis. At the same time, analogous precise ephemerides in the NWL 972 system using the NWL 10E-1 EGM were produced as part of DMAHTC routine production. This situation permitted a preliminary comparison of the pole position solutions computed in the two systems.

## 4.1 FROCEDURES FOR GENERATING WGS 84 BASED SOLUTIONS

WGS 84 versions of CELEST input files were utilized to produce precise ephemerides of 5 NNSS satellites, from day 149 to day 154 and from day 161 to day 179, m1985. The program input included the WGS 84 EGM truncated to degree (n) and order (m) 41, as well as the WGS 84 ellipsoid parameters. The program also utilized a file of WGS 84 tracking station coordinates which were obtained by applying a geometric transformation to the "production" NWL 972 coordinates. Each orbit fit for satellites DMA 59, DMA 77, DMA 93, and DMA 113 (Nova) was based on 2 days of tracking dute, while each dit for satellite DMA 105 was based on 1 day or data.

Suring the test period, DMHH(C also produced precise aphemerides of the same S MNSS satellites for routine production purposes. These fits utilized the NWL LOE-L EGM (n=28, m=27) and the NWL 972 tracking station coordinate set. Data editing occurred independently in the analogous CELEST solutions in the two systems (i.e., no attempt was made to enforce common data between the solutions).

The pole coordinates output in the two systems were compared to all Circuler-D values of x and y. Daily values were derived from the BLH 5-day values by cubic soline interpolation, and differences were formed between the interpolated values and the Doppler-derived values. These differences were computed in the sense Doppler minus BIH. The pole position solutions which resulted from the

			:sec)	Δy (arcsec)			
SAT.		NWL 922	WG 3 84	NWL 922	WO 3 84		
59	δσ	+ .0020	+ .0147	+ .0218	+ .0242		
n=11		± .0239	± .0264	± .0180	± .0195		
77	δσ	0016	+ .0120	+ .0191	+ .0195		
n=13		± .0215	± .0189	± .0193	± .0182		
93	Δσ	+ .0304	+ .0342	+ .0269	+ .0256		
n=11		± .0123	± .0155	± .0094	± .0154		
105	δσ	+ .0138	0053	0032	+ .0048		
n=21		± .0162	± .0101	± .0113	± .0107		
115	Σ	+ .0160	+ .0068	+ .0374	+ .0160		
n=13	σ	± .0189	± .0138	± .0198	± .0063		

# Table 3: Statistics of the Differences Between the Doppler-Derived Pole Coordinates and the BIH Pole Coordinates

Table 4: Statistics of Pole Coordinate Differences Grouped By NNSS Types

Samilin Tree		Δ x (8	ucsec)	Ay (arcsec)			
Salemie Ty	he	NWL 922	WG \$ 84	NWL 922	WG \$ 84		
OSCAR <i>s</i> (59,77,93) n=35	δ	+ .0096 ± .0241	+ .0198 ± .0224	+ .0224 ± .0163	+ .0229 ± .0175		
NOYAs (105,115) n=34	α Δ	+ .0147 ± .0170	0007 ± .0129	+ .0123 ± .0250	+ .0099 ± .0112		

Notes:

 $\overline{\Delta}$  = mean difference

 $\sigma$  = standard deviation

n = number of orbit fits

and the second states of the second secon

satellite DNA 105 fits (in both systems) on day 175 were outliers and were rejected from further study.

## 4.2 PRELIMINARY RESULTS OF WGS 84 - BASED POLE SOLUTIONS

Table 3 presents statistics of the differences between the BIH and the Doppler-derived pole coordinates on a satellite-by-satellites basis. An examination of this table gave no conclusive evidence that use ΟŤ WGS 84 the agreement systematically improved between the Doppler-derived values and the BIH values. However, when the satellites were grouped by type (i.e., Nova and Oscar), as in Table 4, a possible correlation emerged. While the pole positions determined using the Oscar satellites and WGS 84 showed no improvement in agreement with the BIH values, pole positions determined using the Nova satellites and WGS 84 did show better agreement with BIH. Additionally, there was less scatter in the Nova differences when WGS 84 was utilized, as evidenced by the smaller standard deviations.

## 5.0 CONCLUSIONS

The polar motion derived from Doppler tracking of the NNBS satellites has provided and continues to provide valuable Earth orientation information. When the annual and Chandler components of polar motion are removed from the observational data of each Earth orientation series, the same geophysical information remains. Nova-type NNSS satellites provide more precise estimates of pole position than Oscar-type NNSS satellites. Preliminary analysis shows that the use of WGS 64 may improve the accuracy of the pole positions derived from the Nova satellite orbit fits, but that its use for Oscar satellites does not lead to improve accuracies. However, more data need to be processed to substantiate these proclaminary results.

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