

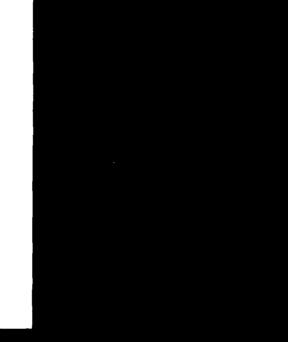
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MRC Technical Summary Report #2844 A NOTE ON LEAST TWO NORM SOLUTIONS OF MONOTONE COMPLEMENTARITY PROBLEMS

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July 1985

(Received July 25, 1985)



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ABSTRACT

This downsn't)For the monotone nonlinear complementarity problem, we considers Tihonov regularizations which reduce the solution of the problem to the solution of a sequence of strongly monotone complementarity problems. The sequence of solutions obtained are called approximate solutions and it is known that for a solvable monotone complementarity problem, the approximate solutions converge to the least two norm solution of the given problem. This paper provides new growth rates for these approximate solutions, sharp- *Computational* ens some previously known results and gives a procedure for obtaining an approximate solution for any apriori prescribed tolerance.

Keywords: Monotone operators, complementarity, monotonicity, Tihonov regularization.

Work Unit Number 5: Optimization and Large Scale Systems

Sponsored by the United States Army under Contract No. DAAG29-80-C-0041. This material is based on work sponsored by National Science Foundation Grants DCR-8420963 and MCS-8102684.

SIGNIFICANCE AND EXPLANATION

Tihonov regularization is a useful computational procedure for monotone complementarity problems which leads to approximate solutions when the given problem is solvable. Growth rates are given for these approximants which sharpen some known results. These results provide a unified framework for finding approximate solutions of important classes of constrained optimization problems.

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A NOTE ON LEAST TWO NORM SOLUTIONS OF MONOTONE COMPLEMENTARITY PROBLEMS

P. K. Subramanian

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1. Introduction

Given an operator $F: \mathfrak{R}^n \longrightarrow \mathfrak{R}^n$, the celebrated complementarity problem NLCP(F) consists in finding $z \ge 0$ such that $F(z) \ge 0$ and $z^T F(z) = 0$. We say F is monotone if

$$ig(F(x)-F(y)ig)^T(x-y)\geq 0, \qquad orall x,y\in \Re^n,$$

and strongly monotone with modulus λ if

$$(F(x) - F(y))^T(x - y) \ge \lambda ||x - y||^2$$

for some real number $\lambda > 0$. When F is an affine operator, that is, F(x) = Mx + q for some $n \times n$ matrix M and a vector $q \in \Re^n$, NLCP(F) is referred to as the *linear complementarity problem* and denoted by LCP(M, q). It is well known that if M is positive semidefinite and LCP(M, q) is feasible, that is there exists a $z \ge 0$ such that $F(z) \ge 0$, then it is solvable [Eaves, 1971]. However this is known to be false for NLCP(F) in general as shown by the

Sponsored by the United States Army under Contract No. DAAG29-80-C-0041. This material is based on work sponsored by National Science Foundation Grants DCR-8420963 and MCS-8102684. counterexample of [Megiddo, 1977] and [Garcia, 1977]. On the other hand, if F is monotone and satisfies some growth conditions to be defined below or the distributed Slater constraint qualification [Mangasarian & McLinden, 1985], then NLCP(F) is solvable.

In this note we shall be concerned with NLCP(F) when F is monotone and the complementarity problem in this case will be referred to as the monotone complementarity problem. For such an operator F, given $\varepsilon > 0$, the Tihonov regularization of F is defined to be $F_{\varepsilon} := F + \varepsilon I$. It is well known that $NLCP(F_{\varepsilon})$ has a unique solution $x(\varepsilon)$. The prinicpal theorem of this note provides new growth rates for $||x(\varepsilon)||$. As a corollary, we obtain the well known result $x(\varepsilon) \to x^*$ where x^* is the least two-norm solution of NLCP(F), provided NLCP(F) is solvable. These growth rates are also useful in obtaining δ -approximate solutions when NLCP(F) needs only to be solved within a preassigned tolerance δ in some special cases.

We briefly indicate the notation used in this paper. We denote by \Re^n the space of real ordered *n*-tuples. We use the Euclidean two-norm throughout. All vectors are column vectors. Given a vector x, we indicate its i^{th} component by x_i . We say $x \ge 0$ if one has $x_i \ge 0 \forall i$ and the set of all such vectors in \Re^n is denoted by \Re^n_+ . Given x, y in \Re^n , we shall indicate their inner product $x^T y$ by $\langle x, y \rangle$. Given NLCP(F), we define

its feasible set S(F) and solution set $\overline{S}(F)$ by

$$S(F) = \{x \in \mathfrak{R}^n_+ : F(x) \in \mathfrak{R}^n_+\}$$

$$\overline{S}(F) = \{x \in S(F) : \langle x, F(x) \rangle = 0\}.$$

The end of a proof is indicated by **I**.

2. Variational inequalities and NLCP(F)

The following notions are essential for this paper and the reader is referred to [Auslender, 1976] for proofs.

2.1 Definition. Let $D \subseteq \mathbb{R}^n$, $F: D \to \mathbb{R}^n$. The variational inequality problem consists in finding $z_o \in D$, if it exists, such that

$$\langle F(z_o), x-z_o \rangle \geq 0 \quad \forall x \in D.$$

In this case we say that z_o solves the variational inequality

$$(VI): \quad \langle F(z), x-z \rangle \geq 0 \quad \forall x \in D.$$

Although many problems can be cast as variational inequality problems, our interest in them stems from the following well known proposition (see e.g., [Karamardian, 1972]).

2.2 Proposition. Let $F: \mathfrak{R}^n_+ \to \mathfrak{R}^n$. Then z_o solves NLCP(F) if and only if z_o solves (VI).

2.3 Definition. Let C be a closed convex set in \Re^n , and let $F: \Re^n \to \Re^n$. We say F is hemicontinuous on C if for all $x, y \in C$, the map

$$\lambda \longmapsto \langle F(\lambda x + (1-\lambda)y), x-y \rangle$$

is continuous on the interval [0, 1].

2.4 Proposition. Let C be a closed convex set contained in D and let $F: D \longrightarrow \Re^n$ be monotone and hemicontinuous on C. Then

$$\langle F(z^{\star}), (z-z^{\star}) \rangle \geq 0 \quad \forall z \in C$$

if and only if

$$\langle F(z), (z-z^{\star}) \rangle \geq 0 \quad \forall z \in C.$$
 (2.5)

Further, $Z_o = \{z^* : z^* \text{ solves } (4.5)\}$ is closed and convex.

See Auslender [1976, page 121] for a proof.

2.6 Definition. Let $C \subseteq D$ be a nonempty closed convex set and assume $F: D \to \Re^n$. We say F is coercive (strongly coercive) if there exist $v_o \in C$, $\lambda \in \Re$ positive such that

$$v \in C, ||v|| \geq \lambda \implies F(v)(v-v_o) > 0$$

(respectively,

$$v \in C, ||v|| \to \infty \implies \frac{F(v)(v-v_o)}{||v-v_o||} \to +\infty).$$

The proof of the following Theorem may be found in [Auslender, 1976].

2.7 Theorem. Let $F : \Re^n \to \Re^n$ be a monotone operator, coercive and hemiconintuous on \Re^n_+ . Then NLCP(F) is solvable. If in addition F is strongly coercive, then NLCP(F) has a unique solution.

We now define the Tihonov regularization of an operator.

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2.8 Definition. Let $F : \mathfrak{R}^n \longrightarrow \mathfrak{R}^n$ and let $\varepsilon > 0$. The Tihonov regularization F_{ε} of F is defined by $F_{\varepsilon}(x) = F(x) + \varepsilon x$.

If $F: \mathfrak{R}^n \to \mathfrak{R}^n$ is monotone and hemicontinuous, then F_{ε} is also hemicontinuous and strongly monotone with modulus of monotonicity at least ε . It is immediate that F_{ε} is strongly coercive. Thus we get the following useful corollary to Theorem 2.7.

2.9 Corollary. Let $F : \Re^n \to \Re^n$ be monotone and hemicontinuous. Then $\forall \varepsilon > 0$, there exists a unique $x(\varepsilon)$ (called ε -approximant or simply approximant), which solves NLCP(F).

3. Properties of approximants

In this section we shall prove the principal theorems of this paper on the growth rate of ϵ -approximants.

3.1 Theorem. Let $F : \mathbb{R}^n \to \mathbb{R}^n$ be a monotone operator which is hemicontinuous on \mathbb{R}^n_+ . Let $\{\varepsilon_n\}$ be a sequence of positive reals such that $\varepsilon_n \downarrow 0$. Let $F_n = F + \varepsilon_n I$ be the Tihonov regularization of F and let x_n be the unique solution of $NLCP(F_n)$. Let m > n and assume that $F(0) \geq 0$. Then

$$\|x_m-x_n\|^2 \leq \frac{(\varepsilon_n-\varepsilon_m)}{(\varepsilon_n+\varepsilon_m)} \cdot \{\|x_m\|^2-\|x_n\|^2\}.$$

Proof

From Proposition 2.2, it follows that

$$\langle F_m(x_m), x-x_m \rangle \geq 0 \qquad \forall x \in \Re^n_+.$$

By taking $x = x_n$,

$$\langle F_m(x_m), x_n - x_m \rangle \geq 0.$$
 (3.2)

Likewise,

$$\langle F_n(x_n), x_m - x_n \rangle \geq 0,$$

which we rewrite as

$$< -F_n(x_n), \ x_n - x_m > \ge 0.$$
 (3.3)

Adding (3.2) and (3.3) we get

$$\langle F_m(x_m)-F_n(x_n), x_n-x_m \rangle \geq 0.$$

Hence remembering that $F_m = F + \epsilon_m I$,

$$\langle F(x_m) + \varepsilon_m x_m - F(x_n) - \varepsilon_n x_n, x_n - x_m \rangle \geq 0.$$

From the monotonicity of F this yields

$$< \epsilon_m x_m - \epsilon_n x_n, \ x_n - x_m > \geq < F(x_n) - F(x_m), \ x_n - x_m > \geq 0,$$

that is,

$$\varepsilon_m < x_m - x_n, \ x_n - x_m > + (\varepsilon_m - \varepsilon_n) < x_n, \ x_n - x_m > \geq 0.$$

By assumption m > n so that $\varepsilon_m < \varepsilon_n$. We now have

$$(\varepsilon_n - \varepsilon_m) < x_n, \ x_m - x_n > \geq \ \varepsilon_m \|x_m - x_n\|^2.$$
 (3.4)

Obviously,

$$||x_m||^2 = ||x_m - x_n||^2 + ||x_n||^2 + 2 < x_m - x_n, x_n > 0$$

so that from (3.4) we now get

$$||x_m||^2 \geq ||x_m - x_n||^2 + ||x_n||^2 + \left\{\frac{2\epsilon_m}{\epsilon_n - \epsilon_m}\right\} ||x_m - x_n||^2.$$

Hence,

$$\|x_m\|^2 - \|x_n\|^2 \geq \left\{\frac{\varepsilon_n + \varepsilon_m}{\varepsilon_n - \varepsilon_m}\right\} (\|x_m - x_n\|^2).$$

This completes our proof.

Theorem 3.1 has some interesting consequences. We present them in the following corollary.

3.5 Corollary. Assume that the hypotheses of Theorem 5.1 are satisfied. Then

- a) $||x_m|| > ||x_n||$
- b) $\varepsilon_m \|x_m\| \leq \varepsilon_n \|x_n\|$

Let $\overline{S} = \{x : x \text{ solves } NLCP(F)\}$. Then

c) $\sup\{||x_n||\} < \infty \iff x_n \longrightarrow \overline{x} = P_{\overline{S}}(0) \iff \overline{S} \neq \emptyset.$

where $P_{\overline{S}}(0)$ denotes the projection of the origin on $\overline{S}(F)$, that is the closest point to 0 in $\overline{S}(F)$ in the two-norm.

Proof

Observe that m > n implies that $x_m \neq x_n$. To see this, suppose the contrary and write $x_m = x_n = x$. Then x solves $NLCP(F_i)$ for i = m, n

so that

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$$\langle F(x) + \varepsilon_m x, x \rangle = 0$$

and

$$\langle F(x) + \varepsilon_n x, x \rangle = 0$$

which imply $\langle \varepsilon_m x - \varepsilon_n x, x \rangle = 0$. Since $\varepsilon_m \langle \varepsilon_n$ we must have x = 0. But $F_m(x) \ge 0$, so that we must have $F(0) \ge 0$ contradicting our hypothesis. Hence $||x_m - x_n|| > 0$ and (a) follows from Theorem 3.1.

Next we prove (b). By Cauchy-Schwarz inequality from (3.4),

$$\frac{\varepsilon_n-\varepsilon_m}{\varepsilon_m}\|x_n\|\|x_m-x_n\|\geq \|x_m-x_n\|^2.$$

Hence

$$\frac{\varepsilon_n-\varepsilon_m}{\varepsilon_m}\|x_n\| \geq \|x_m-x_n\| \geq \|x_m\|-\|x_n\|$$

and

$$\varepsilon_n \|x_n\| \geq \varepsilon_m \|x_m\|.$$

This proves (b).

Finally we prove (c).

We start by showing that $\{||x_n||\}$ bounded $\Rightarrow x_n$ converges to an element of \overline{S} . From (a), since $\{||x_n||\}$ is strictly increasing, $\sup ||x_n|| = \lim ||x_n||$. Taking m > n and letting $m, n \to \infty$, it follows from Theorem 3.1that $\{x_n\}$ is Cauchy. Hence x_n converges. Let $x_n \to \xi$. Since x_n solves $NLCP(F_n)$,

$$x_n \geq 0, F_n(x_n) \geq 0, < x_n, F_n(x_n) > = 0$$

which implies

$$\xi \geq 0, F(\xi) \geq 0, -, <\xi, F(\xi) > = 0$$

so that $\xi \in \overline{S}$.

On the other hand, if $\bar{S} \neq \emptyset$, let \bar{z} be any arbitrary element of \bar{S} . Assume that *n* is arbitrary but fixed. By Proposition (2.2),

$$\langle F_n(x_n), x-x_n \rangle \geq 0 \qquad \forall x \in \Re^n_+.$$

Take $x = \bar{z}$ to get

$$\langle F(x_n) + \varepsilon_n x_n, \ \overline{z} - x_n \rangle \geq 0.$$
 (3.6a)

Since \tilde{z} solves NLCP(F), by Proposition (2.4),

$$\langle F(x), x-\bar{z} \rangle \geq 0 \qquad \forall x \in \Re^n_+$$

Taking $x = x_n$,

$$\langle F(x_n), x_n - \overline{z} \rangle \geq 0.$$
 (3.6b)

From (3.6a) and (3.6b) we get

$$\varepsilon_n < x_n, \ \bar{z} - x_n > \geq 0 \tag{3.7}$$

so that $\langle x_n, \bar{z} \rangle \geq ||x_n||^2$. Hence $||x_n|| \leq ||\bar{z}||$, that is, $\sup_n ||x_n||$ is bounded proving the converse.

It remains only to show that if $x_n \to \xi$ then $\xi = P_{\bar{S}}(0)$. But from (3.7) we have $\langle \xi, \bar{z} - \xi \rangle \ge 0$ and since \bar{z} was an arbitrary element of \bar{S} it follows that $\xi = P_{\bar{S}}(0)$. This completes the proof.

Remark

Parts (a) and (c) of Corollary 3.5 are known when F is a multifunction on a Hilbert space H. For a proof using the theory of Yosida approximations, see [Brézis, 1974], who also proves a weaker form of Theorem 3.1.

4. Application to LCP(M, q)

We now consider an application of Corollary 3.5 to LCP(M, q) in the case when M is positive semidefinite. From (c) of Corollary 3.5, the solution of LCP(M, q) is reduced to the solution of the sequence $LCP(M + \varepsilon_n I, q)$. We shall not be concerned here with an algorithm for the solution of the positive definite $LCP(M + \varepsilon_n I, q)$. However, we would like to show that if the solution set $\overline{S}(M, q)$ is bounded then for any preassigned tolerance δ , it suffices to solve $LCP(M + \varepsilon_I, q)$ for a single value of the parameter ε to obtain a δ -approximate solution. We make this precise in the following Theorem.

4.1 Theorem. Let $\delta > 0$ be a preassigned tolerance. Assume that M is positive semidefinite and that $\overline{S}(M, q)$ is nonempty and bounded. Then there exists $\overline{\varepsilon} > 0$ such that $\forall \varepsilon$, $0 < \varepsilon < \overline{\varepsilon}$, the unique solution $x(\varepsilon)$ of

 $LCP(M + \epsilon I, q)$ satisfies

$$x(\varepsilon) \geq 0, \qquad \|w(\varepsilon) - w(\varepsilon)_+\| \leq \delta \quad and \quad |< x(\varepsilon), \ w(\varepsilon) > | < \delta$$

where $w(\varepsilon) = Mx(\varepsilon) + q$.

Proof

Assume that $x(\varepsilon)$ solves $LCP(M + \varepsilon I, q)$. Let $v(\varepsilon) = w(\varepsilon) + \varepsilon x(\varepsilon)$. By assumption, $\exists K \ge 1$ such that $\|\overline{S}(M, q)\| \le K$. Now choose $\overline{\varepsilon} = \delta/K^2$. Since $x(\varepsilon)$ solves $LCP(M + \varepsilon I, q)$, we have

$$x(\varepsilon)v(\varepsilon) = 0, v(\varepsilon) - w(\varepsilon) = \varepsilon x(\varepsilon).$$

If x^* is the least two-norm solution of LCP(M, q), then

$$\begin{aligned} |x(\varepsilon)w(\varepsilon)| &= \varepsilon ||x(\varepsilon)||^2 &\leq K \varepsilon ||x(\varepsilon)| \quad (by \ 3.5(a) \ and \ (c)) \\ &\leq K \overline{\varepsilon} ||x^*|| \quad (by \ 3.5(a) \ and \ (c)) \\ &< K^2 \cdot \delta / K^2 \\ &= \delta. \end{aligned}$$

Also since $w(\varepsilon)_+$ is the closest point to $w(\varepsilon)$ in \Re_+^n , we have

$$\begin{split} \|w(\varepsilon) - w(\varepsilon)_{+}\| &\leq \|w(\varepsilon) - v(\varepsilon)\| = \varepsilon \cdot \|x(\varepsilon)\| \\ &\leq \overline{\varepsilon} \cdot \|x(\overline{\varepsilon})\| \leq \frac{\delta}{K^{2}} \cdot K \\ &< \delta. \end{split}$$

This completes our proof.

Remark

We remark that a sufficient condition for the boundedness of the solution set is that the interior of the feasible set S(M,q) be nonempty (see for instance [Mangasarian, 1982] where this is proved for the more general case when M is copositive plus, that is, (i) $x \ge 0 \Rightarrow xMx \ge 0$ and (ii) $xMx = 0 \Rightarrow Mx = 0$.) To find the constant K one can use the bounds obtained by Mangasarian [1985] by solving a single linear program if necessary.

Acknowledgement. This represents a portion of the author's doctoral dissertation at the University of Wisconsin-Madison written under the supervision of Professor Olvi Mangasarian. The author is grateful to Professor Mangasarian for his continued support and encouragement. でいたいでは、ためないという

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	6. PERFORMING ORG. REPORT NUMBER
7. AUTHOR(0)	S. CONTRACT OR GRANT NUMBER(+)
P. K. Subramanian	
	DAAG29-80-C-0041
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