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# NOTATION

L	Length between perpendiculars
В	Ship beam
cp	Prismatic coefficient
C <sub>w</sub>	Waterplane coefficient
c <sub>x</sub>	Maximum section area coefficient
GM	Metacentric height
KM	Vertical location of metacenter above the baseline
LCF	Longitudinal center of floatation expressed as percentage of L aft of the forward perpendicular
p%	p statistic (expected error, see page 3)
Т	Ship draft
VCG	Vertical center of gravity
۰.	Displacement

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#### ABSTRACT

This report describes a statistical analysis of ship roll response as influenced by hull form parameters. A data base of 17 ships is described and regression analyses for the effect of hull form on roll angle are performed for three values of ship heading to wave direction and the maximum observed roll angle. Data for the ships that have antiroll fins are also presented.

#### ADMINISTRATIVE INFORMATION

Funding for this work was provided by the Ship Performance and Hydromechanics Program under Program Element Number 62543N, Subj Project SF43-421. At the David W. Taylor Naval Ship Research and Development Center it is identified as Work Unit 1506-120.

## INTRODUCTION

The success of Bales<sup>1\*</sup> in quantifying the relation between hull form parameters and seakeeping performance in head seas has led to great interest in extending this work to oblique seas. The most important additional motion introduced by this extension is roll. <sup>1</sup>The present work describes an investigation into the feasibility of developing seakeeping performance estimates based on hull form parameters for roll motion in a manner analogous to Bales' work for head seas.

## HULL FORM AND ROLL MOTION DATA BASE

In order to investigate the roll response of surface combatants, a data base of 17 ships was selected. These ships are frigates and destroyers and are a subset of ships used by Bales<sup>1</sup>. Seven of the 17 ships are equipped with antiroll fins and data is presented for these ships with and without antiroll fins.

The principal dimensions and hull form parameters are listed in Table 1.

## ROLL MOTION ANALYSIS

Ship motion calculations were carried out using the Navy's Standard Ship Motion Program (SMP81)<sup>2</sup> from which tabulated values of roll angles for long-crested seas were obtained. Roll angle data for ship headings to the wave direction of

\*A complete listing of references is given on page 5.

60 (bow), 90 (beam), and 120 (quartering) degrees were extracted from the SMP81 output as well as the maximum observed roll angle.\* In all cases, a Bretschneider spectrum with a significant wave height of 3.5 meters and a ship speed of 30 knots was used. These are conditions in which frigates are expected to be fully operational. Table 2 contains a summary of the computed significant single amplitude roll angles.

To analyze the data, several regressions using ship characteristics and roll response were performed. These regressions were done using both multivariable stepwise and single independent variable regression methods.

In order to maintain statistical confidence in a regression with a relatively small sample size, a minimum number of independent variables should be used. To achieve this, two sets of regression calculations were performed. The first set of regressions uses a relatively large number of independent variables, while the second set of regressions use a much smaller number of variables.

Selection of the variables for the first set of regressions was based on an understanding of ship roll and previous analysis of the data used in this investigation. Ship motion theory indicates that the primary factors that determine roll response are functions of mass distribution (gyradius and the vertical center of mass), hydrodynamic damping (bilge keel area for example), and excitation force (governed by hull form, wave height and slope, and wave encounter frequency). One goal of the study was to determine if roll response could be predicted given the level of detail available at very early design stages. While vertical center of gravity and thus metacentric height is usually not available, it was decided to include metacentric height so that it would be possible to make a comparison of the regressions with and without the metacentric height included. Based on the regressions performed previously, the geometric variables that are considered to be of importance are ship length, beam, draft, prismatic coefficient, waterplane coefficient, and displacement.

The first set of regressions uses GM/B, KM/B, B/T,  $C_p$ ,  $C_w$  and the squares of these variables. Additionally, displacement-length ratio and bilge keel area divided by length square are included. Table 3 shows the results of the single variable regressions for ship headings of 60, 90, and 120 degrees. Table 4 shows

<sup>\*</sup>The convention used in SMP81 is 0 degrees for head seas and 180 degrees for following seas.

the same regression results for the maximum observed roll angle. Results of the multivariable regression for the first selection of variables are not given because the number of variables used in the regression was close to the number of observations, leading to statistical uncertainty in the numeric results. The order in which variables were selected in each step of the regression was, however, used to determine the relative importance of each variable, since selection order is based on the sum of the squares reduced by the addition of a variable in the regression equation.

From the first set of regression results, the coefficient of determination for the single variable regressions and the order of selection for the multivariable regressions are used to reduce the number of variables. For the cases of ship headings of 60, 90, and 120 degrees, the variables that had the highest coefficient of determination and early selection were the same: GM/B,  $(KM/B)^2$ ,  $(B/T)^2$ , and  $C_p$ . Plots of these coefficients versus roll angle at the three headings can be found in Figures 1 through 4. Figure 5 shows the cumulative proportion of the sum square reduced at each step in the multiple regression for beam seas. It can be seen that when GM/B is available, it gives the largest contribution. When GM/B is not used,  $(KM/B)^2$  gives the largest contribution, but the fit result is never as good as when GM/B is used. In the case of the maximum observed roll angle, a different set of variables was found to be significant, i.e.,  $(C_p)^2$ ,  $\Delta/(L/100)^3$ ,  $C_w^2$ and  $(B/T)^2$ . Figure 6 shows prismatic coefficient versus maximum expected roll angle. These two sets of variables then become the variables for the second set of regressions.

Tables 5 and 6 give the results for the second set of regressions. Table 5 gives the results for the multivariable regressions with and without GM/B for 60, 90, and 120 degree ship headings. Table 6 gives the results of the regression on the maximum observed roll angle. The coefficient of each variable in the regression equation is the slope of the regression plane in that dimension while the constant is the intercept of the regression plane with the roll angle axis. The standard deviation of the regression will give the range of error of the regression when multiplied by the square root of the number of independent variables. The  $p_{\pi}^{\pi}$  statistic is an indication of the expected error of the standard deviation as compared to the entire population and depends on the number of variables in the regression and the sample size<sup>3</sup>,<sup>4</sup>.

Table 7 shows the roll angles for the ships in the data base separated into groups of three GM/B ranges. The average roll angle for each range is plotted against ship heading in Figure 7. As the ship's heading goes from head to beam and then following seas, the influence of GM/B reverses. This can also be seen in the coefficients of the regression planes shown in Table 5. This agrees with trends shown by Schmitke<sup>5</sup>.

Figures 8 and 9 show the roll reduction obtained by using antiroll fins in beam seas and for the heading of maximum roll angle. The average reduction in roll is 64 percent for beam and 66 percent for the heading of maximum roll. Since the primary factors that control roll reduction with fins are the controller system and fin size, no correlation between hull form and roll reduction was observed.

Figure 10 shows the increase in operability for a destroyer hull form due to the addition of antiroll fins. Operability in this case is defined as the percentage of the time that the ship can operate in the winter North Atlantic without exceeding 8 degrees of roll, 3 degrees of pitch, 30 deck wetnesses per hour, 20 slams per hour, and 0.4g vertical acceleration at the bridge.

## CONCLUSIONS

It has been shown that the dominant influence on roll response is metacentric height. This makes the estimation of roll response at very early design stages difficult since the location of the VCG is not available. Further, it is not possible to provide guidance on parameters other than GM because change in these parameters can have positive or negative influence on roll motion depending on the value of GM. Since it has been shown in a recent investigation for the Naval Studies Board, that adequately sized antiroll fins can reduce roll to the point where it is not the limiting motion, the recommended procedure for Navy combatants is to develop hull forms to reduce pitch and heave related responses and to provide adequate fins and bilge keels to reduce roll.

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Figure 2 - (KM/B)<sup>2</sup> versus Roll Angle

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GN/8= 0.05 - 0.06

ship S

GM/8= 0.08 - 0.10

5	<b>R60</b>	06H	R 105	R120	ship #	GN/B	<b>091</b>	R90	RMAX	R120	ship s
0.050	1.7	2.80 2	-	16.98	15	0.084	3.76	£.5	13.52	6.42	v
0.055	1.89	3.61		16.34	16	0.064	4.08	6.85	15.00	7.15	17
0.060	2.38	4.33		12.25	ŝ	0.065	3.97	6.51	19.20	9.97	~
0.066	2.68	8.9	21.18	10.94	12	0.094	2.73	6.20	25.65	10.87	=
0.072	2.74	5.23	10.54	5.2	13	0.095	3.02	5.61	17.39	8.68	1
0.072	4.4	5.27	36.67	12.29	4	960.0	3.37	5.92	19.98	9.68	10
0.072	3.06	16.4	13.70	8.67	•						
average	•	- + + + + + + + + + + + + + + + + + + +		• • • •	8 9 9 9 9 9 9 9 9 9 9	average					
0.064	2.771	4.717	20.523	11.894		0.091	3.488	6.147	18.457	8.795	

GM/8= 0.10 - 0.12

8/10	R60	R90	RMAX	R120	ship #
0.102	4.36	7.66	20.67	8.56	2
0.102	4.54	7.46	24.05	8.53	•0
0.103	3.49	6.86	19.95	8.46	-
0.117	5.41	9.59	14.58	6.18	•
average					

7.933 7.893 19.813 4.450 0.106 TABLE 7 - ROLL SEPARATED BY GM/B RANGES AND HEADING

.

TABLE 6 - MULTI-VARIABLE REGRESSION FOR MAXIMUM EXPECTED ROLL ANGLE

103.42720	-0.14628	-59.94104	-0.61700	10.37530		21%		5.63	X07
Coefficients: Co^2	Disp-L	CW^2	(B/T)^2	Constant:	Cumulative Sum of	Squares Reduced:	Standard	Deviation:	žd

	(34/8 Included In Regression	GN/B Not Include In Regression	2	0 -	24/B Included In Regression	GM/B Not Included In Regression
60 Degree Heading			8	) Degree Neading		
Coefficients:				Coefficients:		
	28.61994	• WN •		GW/B	71.88931	· VN ·
(10/10)	-16.69558	-37,13960		(101/18)~2	-3.71507	-55.06761
(8/1)~2	-0.19731	-0.21686		(8/1)^2	-0.22251	-0.27163
8	-0.77042	-2.84692		8	2.76008	-2.45580
Constant:	6.33671	13. 70484		Constant:	1.12526	19.62796
Cumulative Sum o				Cumulative sum of		
Squares Reduced:	<b>Ľ</b> 9	53%		Squares Reduced:	<b>63X</b>	X97
Standard				Standard		
Deviation:	0.58	0.69		Deviation:	0.64	1.14
셛	40%	378		ž	X07	373
		5	1/8 Included	GN/8 Not Included	_	
		Ę	Regression	in Regression		
	÷	20 Degree Keading				
	-	Coefficients:				
		8/10	-76.95155	- WN -		
		(KU/B)^2	65.04913	120.01780		
		(8/1)^2	0.57719	0.62976		
		8	-2.28124	3.30193		
		Constant:	0.83420	-18.97141		
		Cumulative Sum of				
		Squares Reduced:	63X	53%		
		Standard				
		Deviation:	1.90	2.15		
			40%	378		

TABLE 5 - MULTI-VARIABLE REGRESSIONS FOR 60, 90 AND 120 DEGREE HEADINGS

Cr.2	
5	
Cp^2	
8	
1-9210	
AREA/L^2	
(8/T)^2	
8/T	
(101/18)^2	
8/WX	
(CH/B)^2	
Roll	

Maximum Expected Roll Angle

	10.54	0.0498	0.0025	0.3736	0.1397	2.5605	6.5560	0.0066	50.9415	0.5800	0.3364	0.7130	0.5064
antina.	16.67	0.1172	0.0137	0.4563	0.2082	3.7318	13.9261	0.0136	77.7691	0.6700	0.4489	0.8150	0.6642
everage	18.67	0.0633	0.0073	0.4133	0.1712	3.1445	9.9713	0.0108	63.0614	0.6194	0.3844	0.7585	0.5761
intercept		14.746	16.8421	22.5628	20.5448	32.8230	26.0233	14.0995	4.2007	-34.1712	-7.2758	-17.3188	0.8417
stope		47.5585	220.7170	-9.4276	-10.9692	-4.5021	-0.7378	421.4876	0.2294	85.3030	67.4908	47.4445	30.9389
veriance of x		0.0004	0.0001	0.0005	0.0003	0.0891	3.5172	0.000003	60.1752	0.0008	0.0012	0.000	0.0021
variance of y 3	18.60												
var of regression	-	40.1309	50.34 Z	1272.04	40.9754	39,0975	38.9820	40.4372	37.6518	35.1722	35.1934	38.83%	38.6459
correlation coeff		0.1469	0.1277	-0.0326	-0.0315	-0.2163	-0.2227	0.1188	0.2864	0.3775	0.3768	0.2304	0.2300
coef of determine	it ion	0.0216	0.0163	0.0011	0.0010	0.0468	0.0496	0.0141	0.0820	0.1425	0.1420	0.0531	0.0529

TABLE <sup>1</sup> - LINEAR REGRESSIONS OF A SINGLE INDEPENDENT VARIABLE ON MAXIMUM EXPECTED ROLL ANGLE

.

	Roll	GN/B	(GN/B)^2	8/1021	(KM/B)^2	8/1	(8/1)^2	AREA/L^2	DISP-L	9	Cp^2	3	CM72
60 Degrees Heading	•												
minim	1.71	0.0496	\$200.0	0.3738	0.1397	2.5605	6.5560	0.0066	50.9415	0.5800	0.3364	0.7130	0.5084
max i mun	5.41	0.1172	0.0137	0.4563	0.2082	3.7318	13.9261	0.0135	77.7691	0.6700	6844.0	0.8150	0.6642
2767 806	3.42	0.0633	0.0073	0.4133	0.1712	3.1445	9.9713	0.0106	63.0614	0.6194	0.3844	0.7565	0.5761
Intercept		0.1591	1.739	15.8288	9.6799	6.4341	5.0527	3.5759	3,1384	8.4696	5.8005	6.8875	5.1646
slope		39.1361	233.0150	-30.0261	-36.5609	-0.9587	-0.1638	-14.4390	0.0045	-8.1532	-6,1946	-4.5725	-3.0291
variance of x		0.004	0.00001	0.0005	0.0003	0.0691	3.5172	0.00003	60.1752	0.0008	0.0012	0.000	0.0021
variance of y	1.09												
ver of regress	ţa	0.5555	0.5769	0.7139	0.7018	1.0679	1.0547	1.1543	1.1537	1.1015	1.1059	1.1347	1.1341
correlation co	eff	0.7204	0.7074	-0.6179	-0.6263	-0.2745	-0.2946	-0-0243	0.0332	-0.2150	-0.2061	-0.1323	-0.1342
coef of determ	instion	0.5190	0.5005	0.3618	0.3923	0.0753	0.0868	0.0006	0.0011	0.0462	0.0425	0.0175	0.0180
	2.89	0.0498	0.0025	0.3730	0.1397	2.5605	6.5560	0.0066	50.9415	0.5800	0.3364	0.7130	0.5064
a si sa	9.59	0.1172	0.0137	0.4563	0.2082	3.7318	13.9261	0.0138	1691.77	0.6700	0.4489	0.6150	0.6642
ever ede	5.97	0.0633	0.0073	0.4133	0.1712	3.1445	9.9713	0.0108	63.0614	0.6194	0.3844	0.7565	0.5761
Intercept		-0.050	2.7980	24.1393	15.1473	9777.6	7.9628	5.9106	7.2281	13.0987	9.3815	8.8877	74.1.1
e lane		71.94%	435.7637	-43.9655	-53.6017	-1.2008	-0.2020	5.3731	-0,0200	-11.5107	-8.8783	-3.6486	-2.6220
variance of x		0.0004	0.0001	0.005	0.003	0.0891	3.5172	0.00003	60.1752	0.0008	0.0012	0.000	0.0021
variance of y	2.53												
var of regress	5	0.6662	0.6708	1.7468	1.7164	2.5558	2.5399	2.6922	2.6668	2.5859	2.5915	2.6780	2.6767
correlation con	uff	0.8675	0.8665	-0.5926	-0.6014	-0.2252	-0.2380	0.0059	-0,0973	-0.1968	-0. 1935	-0.0729	-0.0761
coef of determin	intion	0.726	0.7508	0.3512	0.3617	0.0507	0.0566	0000.	0.0095	0.0395	0.0374	0.0053	0.0058
120 Nancas Kaadina													
	8			A TTA	0.1307	2 SAMS	A. SSAD	2200	50.0415	0.5800	1125	0212.0	0.5086
	16.98	0.1172	0.0137	0.4563	0.2062	3.7318	13.9261	0.0136	77.7691	0.6700	0.4489	0.8150	0.6642
ever bae	6.6	0.0633	0.0073	0.4133	0.1712	3.1445	9.9713	0.0108	63.0614	0.6194	0.3644	0.7565	0.5761
Intercept		19.5612	14.6844	-28.8765	-9.7912	0.5111	5.0343	5.3751	3.6621	-3.8082	3.4749	-3.3072	3.4502
stope		-115.916	-656.876	93.8357	115.0225	2.9874	0.4884	418.0454	0.0990	22.1386	16.7276	17.4192	11.2033
variance of x		0.004	0.0001	0.0005	0.003	0.0891	3.5172	0.000003	60.1752	0.000	0.0012	0.000	0.0021
variance of y	10.46												
var of regressi	lon	5.855	6.5180	6.8045	6.6269	10.2666	10.2199	10.5418	10.4648	10.7178	10.7537	10.8180	10.8268
correlation com	nf f	-0.6880	-0.6430	0.6226	0.6353	0.2757	0.2833	0.2264	0.2375	0.1862	0.1794	0.1625	0.1600
coef of determi	Instian	0.4733	0.4134	0.3676	0.4036	0.0760	0.0602	0.0513	0.0564	0.0354	0.0322	0.0264	0.0256

TABLE 3 - LINEAR REGRESSIONS OF A SINGLE INDEPENDENT VARIABLE ON ROLL ANGLE AT 60, 90, AND 120 DEGREE HEADINGS

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					-	Naximun	90 Degree
Ship	Naximum	Neading	60 Degree	90 begree	120 Degree	Roll With	Needing
Mutber	Roll	at Nax	Heading	Heading	heading	Fine	vith Fine
	19.95	105	3.49	6.86	8.46	6.9	3.49
2	20.67	105	- <del>1</del> 8.36	7.66	8.56	1.9.17	3.51
n	13.20	õ	3.06	4.97	8.67	19.9	1.16
4	36.67	5	- 4.8	5.27	12.90	5.06	1 0.7
5	12.25	120	2.38	1.33	12.25	1 7.58	1.67
9	13.52	5	3.76	e. 2	. 6.42	_	
-	19.20	105	3.97	6.51	1 26.97	_	_
	24.05	ŝ	1 4.54	7.46	6.53		_
•	14.58	<u>1</u> 05	1 15.2	9.59	6.18		
10 0	19.96	102	3.37	5.92	9.66	5.74	1.86
=	29.52	1 201	2.73	6.20	10.87	5.30	1.86
12	21.18	501	2.68	8.9	10.%	_	_
13	10.54	1 1 25	2.74	5.3	1 2.3	_	_
*	17.39	50	3.02	5.61	8.69	_	_
15	16.96	120	1.7	2.89	16.98	_	_
191	16.34	120	1.00	3.61	16.31		
121	15.00	- 50	4.08	6.85	7.15	_	
ever age	18.67		3.42	5.97	<b>6.</b> 6		
ainimu	10.54		1.71	2.89	5.79		
. maximum	36.67		5.41	9.59	16.98		

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TABLE 2 - SIGNIFICANT SINGLE AMPLITUDE FOLL ANGLE

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-	v 	n —	•	- -	) )	•	) -		2		! -	2	:	:	2	:
2	1131.00	109.73	100.73	87.611	1161.24	124.36	126.49	93.88	121.77	106.00	105.00	1128.00	1142.50	124.00	121.31	106.51
- 2	8.11 I	13.11	1.12.73	14.33	02.91	13.78	14.26	10.92	14.40	11.98	11.01	13.33	15.29	13.85	15.24	12.00
e	1 4.62	4.14	1 15.4	3.84	1 5.97	4.52	2.4	3.43	4.27	12.2	4.30	09.4	4-50	4.95	K	4.22
_≭	1 4352	2939	3502	3645	8004	3596	14257	8771	38.05	2365	1 2761	1001	5024	3567	1 4710	2938
Ľ	5.0	2.0	00.00	K.0	10.74	1 2.0	0.74	1 0.7	0.71	8.0	19.0	0.82	<b>K</b> .0	5.0	8.0	r.0
2	0.78	0.80	19.0	0.87	10.84	6.2	18.0	0.63	8.0	1 0.77	0.00	0.63	10.01	0.82	10.64	0.00
3	1 0.61	0.60	0.67	0.62	0.56	09.0	0.60	0.59	0.60	0.63	1 0.67	1 0.67	1 0.62	1 0.61	1 0.62	0.61
2	0.55	1 0.57	0.58	0.54	0.58	0.55	0.57	1 0.57	0.57	0.59	0.55	0.55	0.55	0.55	0.50	0.56
2	158	116	119	8	1 267	191	189	110	100	137	5	174	802	1 212	182	118
12	1 1.21	1.05	8.1	2.0	1.66	1.5	67-1	11.17	1.5	1.29	1.00	1.36	1.46	1.7	1.50	1.09
5	11.51	1 0.8	0.92	0.86	1.41	1.21	1.46	1.28	1.41	1.13	5.0	0.96	1.46	69.0	10.04	1.0
ę	3 0.10	210.0 Is	220.0	0.060	100.004	0.068	0.102	1110	0.096	10.094	0.066	20.0	0.095	0.050	0.055	0.064
ĸ	1 6.07	1 5.32	5.35	5.63	6.67	5.69	5.33	4.37	5.53	5.20	2.4	R-5	6.24	6.32	6.82	5.26
ĥ	5] 0.41	0.406	0.420	0.407	0.399	0.413	0.374	007.0	0.304	1454.0	124.0	1 0.434	907-0	0.456	877-0	0.411
8	6.66	8.37	8.62	8.34	9.66	9.02	8.87	8.60	8.46	8.65	45.6	09.6	9.32	8.9	- 2.8	8.48
2	1 3.20	1 3.17	2.82	3.73	2.80	3.05	3.02	3.16	3.37	3.19	2.56	1 2.78	3.40	3.42	3.21	3.03

TABLE 1 - HULL FORM CHARACTERISTICS



Figure 10 - Operability With and Without Anti-Roll Fins on a Destroyer Hull Form

OCUKCBHJHFY CUCUTH



Figure 8 - Roll Reducting Using Anti-Roll Fins in Beam Seas





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Figure 7 - Roll Variation with Heading and GM/B



# Prismatic Coefficient Versus Maximum Expected Roll

Figure 6 - Prismatic Coefficient versus Maximum Expected Roll







Figure 3 - (B/T)<sup>2</sup> versus Roll Angle







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