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GLOBAL POSITIONING SYSTEM - A MODIFICATION TO THE BASELINE SATELLITE CONSTELLATION FOR IMPROVED GEOMETRIC PERFORMANCE

THESIS

David W. Thomin Captain, USAF

AFIT/GA/ENG/84D-4

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DEPARTMENT OF THE AIR FORCE
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Wright-Patterson Air Force Base, Ohio

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GLOBAL POSITIONING SYSTEM - A MODIFICATION TO THE BASELINE SATELLITE CONSTELLATION FOR IMPROVED GEOMETRIC PERFORMANCE

THESIS

of the Air Force Institute of Technology

Air University

In Partial Fulfillment of the

Requirements for the Degree of

Master of Science in Astronautical Engineering

 $\label{eq:decomposition} \textbf{David W}. \ \textbf{Thomin, B.S}.$

Captain, USAF

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Approved for public release; distribution unlimited

Preface

The purpose of this study was to investigate the geometric performance of a modification to the proposed baseline constellation for the NAVSTAR Global Positioning System (GPS). To assist in the evaluation, a computer program developed by the **Rand Corporation** (17) was obtained and modified for use in analyzing the geometric performance of this pseudoranging navigation satellite system. The geometric performance of the currently proposed baseline constellation was analyzed using this tool and was compared with the performance of the modified constellation. Although additional factors still need to be considered in selecting the optimum satellite constellation, the modification presented here greatly reduces the percentage of system outages that occur due to the poor geometry of available satellites and, at least on the surface, appears to provide a significant improvement over the present proposal. Perhaps more importantly, it suggests that the expectation of Walker (22:4) that "continuous whole-Earth coverage would be provided most effectively by a system in which the distribution of satellites over the Earth's surface was maintained as uniform as possible," is *not necessarily true*. Since practically every analysis to date has assumed Walker's "expectation" as a basis for comparing constellations, the results of this study could prove to be of significant value in future analyses.

I have had help from many individuals in this thesis effort, and would like to express my thanks to all of them. In particular, I would like to thank Ms. Sandy Berning (AFWAL/AAAN-3), for her assistance in obtaining access to several computer files, to Dr. John Weever (ASD/ENSSE), for his aid in modifying and debugging the computer program used in my analysis, and to Professor C.R. Edstrom (AFIT Math Department), for his assistance in understanding the mathematical concepts involved.

I extend my deep appreciation and special thanks to Dr. George M. Siouris for his extensive

guidance as my thesis advisor, for the special interest he showed in my work, and for all the encouragement he provided me throughout the many months of effort involved. Finally, I wish to thank my wife Jeannette for her patience and understanding during the course of my graduate program, and to my sons, James and Michael, for sacrificing many hours of each day that they could have shared with me while I worked on this thesis.

David W. Thomin

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Abstract

This investigation determined the effect of changes in eccentricity to the orbits of the proposed Global Positioning System (GPS) 18-satellite baseline constellation by analyzing the geometric performance obtained. The effect of satellite losses upon global coverage was also examined with an emphasis on determining which combination of remaining satellites provided the best and worst cases. The potential of GPS for navigation of the space-based user was explored by analyzing the geometric performance obtained for a variety of user trajectories and GPS antenna beamwidths. A computer program which analyzes the many aspects of the geometric performance of pseudoranging navigation satellite systems was used for the analysis.

The results of this analysis indicate that a simple modification to the baseline constellation could reduce system outages on a global basis by nearly 50%. The modification consists of changing the shape of the GPS circular satellite orbits to slightly elliptical ones, resulting in more favorable satellite geometry and fewer outages to the user on a global average. Further consideration to determine its feasibility was recommended. The degradation of coverage due to satellite losses was found to be largely dependent on the combination of the remaining satellites, and suggests that rephasing the remaining satellites could significantly improve the degraded performance. The potential for conventional use of GPS for navigation in space was shown to exist for the low altitude user, but will be very limited for the higher altitude user due to the present GPS antenna design. Increasing the designed antenna beamwidth was shown to significantly improve performance for the high altitude user. It was recommended that this modification be considered in future GPS antenna design, if conventional GPS navigation is to be desired for the high altitude space user.

GLOBAL POSITIONING SYSTEM - A MODIFICATION TO THE BASELINE SATELLITE CONSTELLATION FOR IMPROVED GEOMETRIC PERFORMANCE

1. Introduction

The Navstar Global Positioning System (GPS) is a space-based, pseudoranging navigation satellite system that will provide worldwide, nearly continuous, three dimensional position, velocity, and coordinated universal time to the suitably equipped user (2:226). Although designed primarily for global navigation of a terrestrial or near-earth user, the potential exists for expanding its use to the space-based user. This study analyzes the geometric performance of the proposed baseline orbital constellation not only for the earth-based user, but for the space-based user as well. In addition, the effect on geometric performance of modifying antenna beamwidth is examined for a variety of space-based user trajectories, including both low and high altitude orbits, intermediate transfer orbits, and typical ICBM trajectories. The effect of satellite losses on geometric performance and system accuracy is examined with a special emphasis on the 'best' and 'worst' case scenarios.

The position accuracy available from GPS can be divided into two multiplicative factors: position dilution of precision (PDOP) and other "system" errors (17:1). The "system" errors depend on the accuracy of the ephemeris data and transmitted time from the satellites, ionispheric and atmospheric effects, and various other error sources as indicated in Table I. Since the PDOP factors depend predominantly on the user/navigation satellite geometries, they can be analyzed

independently of system errors, which depend on a multitude of factors. This characteristic allows separate analyses of alternative orbital configurations, user motion, and satellite losses sustained for the purposes of comparison and choosing the optimal constellation (17:3).

TABLE | GPS Error Budget (2:228)

		,	INTRIBUTION ETERS)
	ERROR SOURCE	L ₁ /L ₂ P-Code	L ₁ C/A Code
Space & Control Segments	Clock & Navigation Subsystem Stability Predictability of Satellite Perturbation Ephemeris Prediction & Model Implementation Other	2.1 (1-Sigma) 1.0 2.5 0.7	2.7 (1-Sigma 1.0 2.5 0.7
User Equipment	lonospheric Delay Compensation Tropospheric Delay Compensation Receiver Noise & Resolution Multipath Other	2.3 2.0 1.5 1.2 0.5	10.0 2.0 15.0 1.2 2.0
Ranging Error = RSS Total 1-Sigma		5.3	18.7
3D RMS Navigation Error = (PDOP RMS) (Ranging Error) = (3.7) (Ranging Error)		19.6	69.2
3D Spherical Error Probable = (0.8) (3D RMS)		15.7	55.4

After fully analyzing the geometric performance of the proposed baseline constellation, a modification to this constellation will be incorporated and then be analyzed for comparison. This modification will "target" the geographic areas of weaker coverage in an attempt to reduce the number and length of system outages that occur (due to poor geometry) on a global basis by

changing the eccentricity of the six orbital planes and selectively positioning the periapsis point of each orbit. As the primary tool for the analysis, a computer program on the geometric performance of pseudoranging navigation satellite systems, developed by the Rand Corporation (17), was obtained and modified for this purpose. (For more information on the computer program and its operation, see Appendix B).

In order to better understand the significance of the geometric performance of each constellation and its effect on system accuracy, a thorough review of the terminology and GPS concept of operation is necessary. Therefore, Chapter II will be devoted to providing the background necessary for understanding the system concepts involved. The mathematical derivations for the navigation equations will be presented in Chapter III, and the dilutions of precision (DOPs) will be defined and related to overall system accuracy.

Chapters IV and V will be devoted to the data analysis for both the proposed baseline constellation and the modification to that constellation. The geometric performance of each constellation will be directly compared with that of the other, and from this comparison, conclusions and recommendations will be made and presented in Chapter VI.

To further assist the reader in understanding the information contained in this report, a glossary of technical terms is provided in Appendix A. Appendix B provides an explanation of the variables and subroutines of the computer program utilized in the analysis and explains the modifications that were incorporated. The complete computer program listing is provided in Appendix C, followed by samples of the program output (Appendix D) and selected data extracts (Appendix E) from the more than 150 computer runs made during this evaluation.

II. System Concept

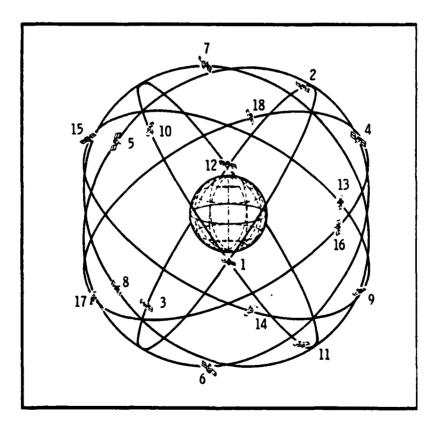
Background

Since the early 1960's, the idea that navigation and positioning could be accomplished using radio signals transmitted from satellites has been actively pursued by both the Navy and the Air Force. Each service separately established its own concept of such a system through an extensive program of studies and tests designed to demonstrate the feasibility of a space-based positioning and navigation system (19:21.1.1). The success of the Navy Navigation Satellite System, better known as TRANSIT, stimulated both the Navy and Air Force to develop a more advanced system that would provide enhanced capabilities and global coverage. The Navy's concept, TIMATION, was essentially a two-dimensional system and could not provide position updates in a high-dynamic aircraft environment. The Air Force concept, Program 621B, could provide the high-dynamic capability but had its own shortcomings as well, particularly from a survivability standpoint (10:1177).

Recognizing the need to integrate these systems, the Deputy Secretary of Defense issued a memorandum in 1973 which designated the Air Force as the primary agency to develop, test, and deploy a single system that could best serve the needs of the defense (19:21.1.1). A system concept which combined the best features of both programs, designated the Navstar Global Positioning System, was the resulting system design. Management of the Navstar GPS was assigned to the Joint Program Office (JPO) located at Space Division in Los Angeles.

When first conceived, the design for the fully operational system consisted of a total of 24 satellites, deployed with eight satellites uniformly distributed in each of three orbital planes, providing continuous three-dimensional global coverage with predicted accuracies in the ten meter range (10:1177). In 1978 and 1979 Defense budgetary constraints forced a reduction in

funding for the GPS program. As a result, in 1980, the Navstar GPS program was restructured and the number of satellites for the fully operational system was reduced from the 24 originally planned to 18. Exhaustive studies have been made since that time to establish the optimum orbital configuration for these remaining 18 satellites. System accuracy, survivability, satellite visibility, ease of buildup, location and duration of outages, ease of sparing and replacement, and growth potential of the constellation to 24 satellites were considered in the selection of what is now the baseline constellation, which will consist of 18 satellites, uniformly distributed in six orbital planes with three satellites per plane, and will provide nearly continuous world-wide coverage that optimizes accuracy over the primary areas of interest (15: E9.3.1).



D

Figure 1. The Six-Plane, 18-Satellite Baseline Configuration (15:E9.3.2)

Navstar System Overview

The Navstar Global Positioning System (GPS) is composed of three segments as described below (Figure 2):

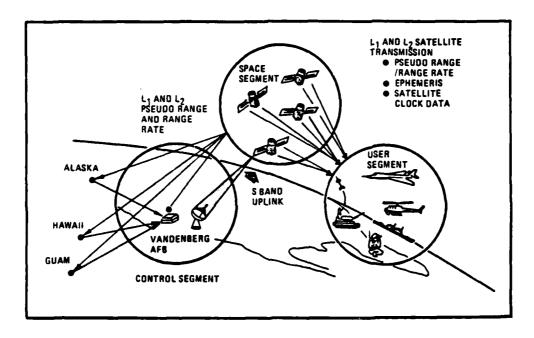


Figure 2. Nevstar GPS Segments (6:218)

Space Segment. Designed to be fully operational in late 1988, the orbital constellation will consist of 18 satellites deployed in circular, 12 hour orbits of 26,600 km radius (10,900 nautical mile altitude). The satellites will be uniformly spaced (120^0 apart) with three satellites in each of six orbital planes, each orbital plane inclined at 55^0 to the equator. Each orbital plane

will be separated from each other in longitude by 60° . Relative phasing of the satellites from one orbital plane to the next is 40° , which simply means that when an ascending satellite in one plane is crossing the equatorial plane, an ascending satellite in the adjacent plane to the east is 40° above the equatorial plane in its own orbital plane (15:E9.3.1). Each satellite transmits navigation signals at frequencies of 1575.4 MHz and 1227.6 MHz, which contain navigation data such as satellite ephemeris and satellite clock bias information (2:227). Use of the two signals permits the user's equipment to compensate for the ionospheric group delay or electromagnetic disturbances in the atmosphere which may alter the affected signals (19: 21.1.1). Each satellite has a mean mission duration of 6.2 years and a design life of 7.5 years (15: E9.3.7), and the present design provides for the placement of three additional satellites within the constellation to act as active, in-orbit, replacement spares.

Control Segment. The Ground Control Segment monitors the broadcast satellite signals and uplinks corrections to ensure predefined accuracies. The operational control segment will consist of five monitor stations, a master control station, and three uplink antennas. The widely separated monitor sets, positioned worldwide, will allow simultaneous tracking of the full satellite constellation and will relay orbital and clock information to the master control station (2:226). The ranging data accumulated by the monitor stations will be processed by the Navstar Operations Center (master control station) for use in satellite determination and systematic error elimination (19: 21.1.1). The master control station then forms corrections that are uploaded to the satellites by the uplink antennas (2:227).

<u>User Segment</u>. The User Segment selects the four, best positioned satellites from those visible and, using the navigation signals passively received from each of these satellites, the user's receiver measures four independent pseudoranges and pseudorange rates to the satellites. The receiver/processor then converts these signals to three-dimensional position, velocity, and

system time. The position solution is in the World Geodetic System Coordinates (WGS-72), an earth-centered, earth-fixed coordinate system, which can be converted to any other coordinate system the user desires (19:21.1.2).

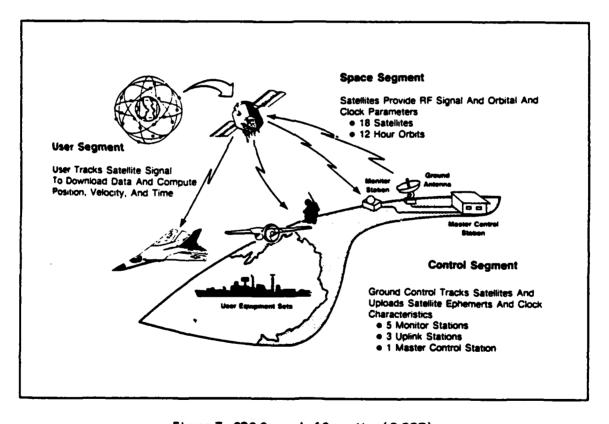


Figure 3. GPS Concept of Operation (2:227)

Concept of Operation

With 18 satellites, if the user is able to receive the navigation signal from satellites above a five degree elevation angle, there are always four or more satellites available for use. (The limit on elevation angle is due to terrain masking, line -of-sight obstructions, etc.) GPS satellites continuously transmit navigation signals at two L-band carrier frequencies: L1, at 1575.42 MHz and L2, at 1227.6 MHz. L1 is modulated by a Coerse/Aquisition (or C/A) code and a Precision (or P) code, whereas L2 contains either the P or C/A code but not both; the P-code is normally used. In addition, superimposed on both frequencies is system data at 50 bits per second that provide handover information from the C/A to P-code, satellite orbital characteristics, satellite health satatus, and satellite clock errors (2:227). Comparison of the delay between the two signals allows for proper computation of errors due to ionospheric propagation or electromagnetic disturbances in the atmosphere (19:21.1.1).

Navigation using GPS is accomplished by passive triangulation. To obtain a navigation solution, the user measures "pseudorange" to each of the four satellites by timing the received pseudorandom code epoch with respect to his local estimate of time. The term "pseudorange" is used since the timing measurement of true range to the satellite contains an error in the form of a yet undetermined clock bias. The position of the four satellites is computed using the received ephemeris data. Using this data and the pseudorange measurements, the user then solves four equations in four unknowns to determine his three-dimensional position and precise time. Three-dimensional velocity is determined by measuring the doppler shifts on the received carrier frequency (2:227).

III. Navigation Equations

The Navigation Solution

In order to develop the navigation equations used in solving for the user's three-dimensional position and time, we will utilize the earth-centered, right-handed, Cartesian coordinate system as illustrated in Figure 4. At time zero, the X-axis passes through the intersection of the equatorial plane and prime meridian, the Z-axis passes through the North Pole, and the Y-axis completes the right-handed orthogonal system. Because of the earth's rotation, the x and y coordinates are constantly changing in longitude with time.

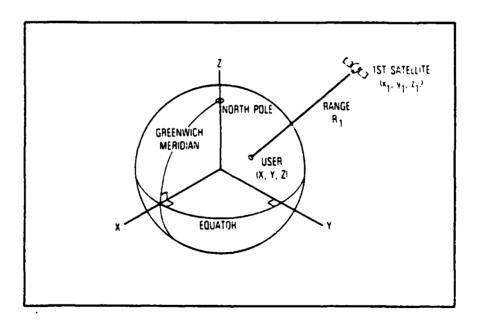


Figure 4. Earth-Centered Inertial Frame (14:97)

The basic nonlinear equations using four satellites are

$$[(x-x_i)^2 + (y-y_i)^2 + (z-z_i)^2]^{1/2} + T = R_i$$
 (1)

where

 x_i, y_i, z_i = position of the ith satellite (known)

x, y, z = user position (unknown)

? = clock bias (unknown)

 R_i = pseudo range measurement to the ith satellite

The quantities R_1 , R_2 , R_3 , and R_4 are "pseudoranges" in that they are the sum of the actual range displacements plus the offset due to user time error. Although these equations can be solved directly, user equipment employs a much simpler version of these equations which can be derived by linearization methods as follows (14:97):

Let

 $x_n,y_n,z_n,T_n = nominal (a priori best estimate) values of x,y,z, and T$

 Δx , Δy , Δz , ΔT = corrections to nominal values

 R_{ni} = nominal pseudorange measurement to ith satellite

ΔR_i = residual (difference) between actual and nominal range measurements

Thus we obtain the following incremental relationships:

$$x = x_n + \Delta x$$

$$y = y_n + \Delta y$$

$$z = z_{n+} \Delta z$$

$$T = T_n + \Delta T$$

$$R_i = R_{ni} + \Delta R_i$$

and

$$R_{ni} = [(x_n - x_i)^2 + (y_n - y_i)^2 + (z_n - z_i)^2]^{1/2} + T_n$$

Substituting these incremental relationships into (1) we obtain

$$[(x_n + \Delta x - x_i)^2 + (y_n + \Delta y - y_i)^2 + (z_n + \Delta z - z_i)^2]^{1/2}$$

$$= R_{ni} + \Delta R_i - T_n - \Delta T_i$$
(2)

Working with the left hand side of the equation and expanding terms we obtain

$$[(x_n + \Delta x - x_i)^2 + (y_n + \Delta y - y_i)^2 + (z_n + \Delta z - z_i)^2]^{\frac{1}{2}}$$

$$= [(x_n - x_i)^2 + 2\Delta x(x_n - x_i) + (\Delta x)^2 + (y_n - y_i)^2 + 2\Delta y(y_n - y_i)$$

$$+ (\Delta z)^2 + (z_n - z_i)^2 + 2\Delta z(z_n - z_i)^2 + (\Delta z)^2]^{\frac{1}{2}}$$
(3)

Rearranging terms and eliminating second order terms, this expression can be written simply as

$$(a + 2b)^{\frac{1}{2}}$$

where

$$a = [(x_n - x_i)^2 + (y_n - y_i)^2 + (z_n - z_i)^2]$$

$$b = [\Delta x(x_n - x_i) + \Delta y(y_n - y_i) + \Delta z(z_n - z_i)]$$

Expanding this form using the binomial series expansion we obtain

$$(a + 2b)^{\frac{1}{2}}$$
 = $(a)^{\frac{1}{2}}[1 + 2b/a]^{\frac{1}{2}}$
= $(a)^{\frac{1}{2}}[1 + b/a + \text{Higher order terms}]$

By noting that all higher order terms contain second order and higher terms of Δx , Δy , or

 Δz , we may ignore them and our equation reduces to

$$(a)^{\frac{1}{2}}[1 + b/8] = (a)^{\frac{1}{2}} + (a)^{\frac{1}{2}}[b/8]$$

$$= (a)^{\frac{1}{2}} + b/(a)^{\frac{1}{2}}$$

$$= R_{ni} + \Delta R_{i} - T_{n} - \Delta T$$
(4)

Substituting our incremental relationship for $\mathbf{R}_{\mathbf{n}i}$ into this equation and simplifying

$$(a)^{\frac{1}{2}} + b/(a)^{\frac{1}{2}} = [(a)^{\frac{1}{2}} + T_0] + \Delta R_i - T_0 - \Delta T$$
 (5)

or

$$b/(a)^{1/2} = \Delta R_i - \Delta T \tag{6}$$

But

$$R_{ni} = (a)^{\frac{1}{2}} + T_n \implies (a)^{\frac{1}{2}} = R_{ni} - T_n$$

Substituting this expression and our expression for b into equation (6) we obtain the linearized equations (i= 1,2 3,4) that relate pseudorange measurements to the desired user navigation information as well as the user's clock bias:

$$[(x_{n}-x_{i})/(R_{ni}-T_{n})] \Delta x + [(y_{n}-y_{i})/(R_{ni}-T_{n})] \Delta y$$

$$+ [(z_{n}-z_{i})/(R_{ni}-T_{n})] \Delta z + \Delta T$$

$$= \Delta R_{i}$$
(7)

The quantities on the right-hand side of equation (7) are known; they are simply the differences between the actual measured pseudoranges and the predicted measurements which are supplied by the user's computer based on knowledge of the satellite position and current estimate of the user's position and clock bias. The quantities to be computed (Δx , Δy , Δz , and ΔT) are the corrections that the user will make to his current estimate of his position and time bias. The coefficients of these quantities on the left-hand side represent the direction cosines of the line of sight vector from the user to the satellite as projected along the x, y, and z coordinate axis system (14:98).

The four linearized equations represented by (7) can be expressed in matrix notation as

$$\begin{bmatrix} B_{11} & B_{12} & B_{13} & 1 \\ B_{21} & B_{22} & B_{23} & 1 \\ B_{31} & B_{32} & B_{33} & 1 \\ B_{41} & B_{42} & B_{43} & 1 \end{bmatrix} \times \begin{bmatrix} \Delta \times \\ \Delta y \\ \Delta z \\ \Delta T \end{bmatrix} = \begin{bmatrix} \Delta R_1 \\ \Delta R_2 \\ \Delta R_3 \\ \Delta R_4 \end{bmatrix}$$

where β_{ij} is the direction cosine of the angle between the range to the ith satellite and the jth coordinate (14:98).

To express this equation more compactly we will let

r = the four element pseudorange measurement difference vector

x = user position and time correction vector

B = the 4 x 4 solution matrix

$$B \equiv \begin{bmatrix} B_{11} & B_{12} & B_{13} & 1 \\ B_{21} & B_{22} & B_{23} & 1 \\ B_{31} & B_{32} & B_{33} & 1 \\ B_{41} & B_{42} & B_{43} & 1 \end{bmatrix}$$

$$x = \begin{bmatrix} \Delta x & \Delta y & \Delta z & \Delta T \end{bmatrix}^{T}$$

$$r = \begin{bmatrix} \Delta R_{1} & \Delta R_{2} & \Delta R_{3} & \Delta R_{4} \end{bmatrix}^{T}$$

Thus our equation becomes simply

$$Bx = r \quad or \quad x = B^{-1}r \tag{8}$$

which compactly expresses the relationship between pseudorange measurements and user position and clock bias.

To understand how the geometry of the satellites at a point in time can result in a system outage, we need only examine the solution matrix. If the ends of the unit vectors from the user to the four satellites selected are in a common plane, the direction cosines of the four unit vectors along a direction perpendicular to this plane are all equal. When this occurs, the determinant of the 4×4 solution matrix becomes zero (solution matrix becomes singular) and no solution is

possible from the four equations. Consequently, the navigation equations "blow up" and what is known as a "system outage" occurs due to the poor geometry. The situation where this occurs is very close to where the four satellites are in a common plane in space as shown in Figure 5 below.

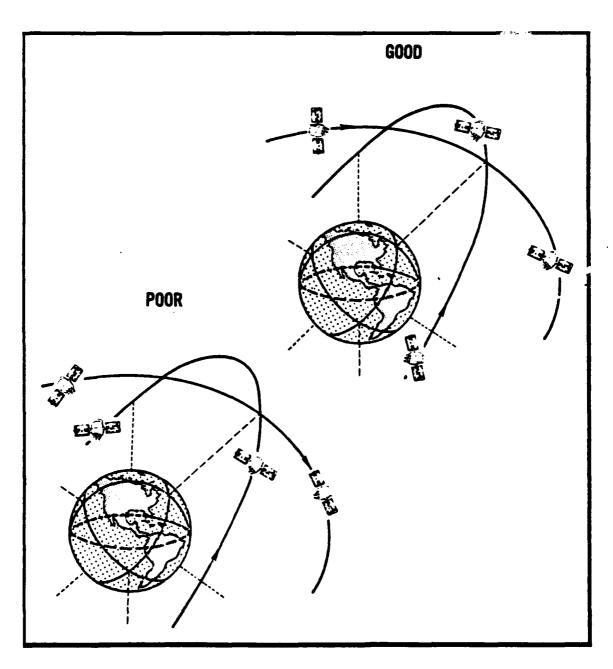


Figure 5. Laustration of Navstar Satellite Geometry (11:433)

User Position Accuracy

In order to determine the accuracy available from the four satellites selected as a function of their geometry, we must calculate the dilution of precision (DOP) values available from the four satellites selected. Since the overall position accuracy is a product of this value and other system errors, small DOP values are highly desirable in order to yield accuracies on the order of those previously shown in Table I. We have already seen how a poor geometry of the four satellites selected results in the "blowing up" of the navigation equations; the corresponding effect on the DOP values is to cause them to become infinitely large (resulting in a system "outage") which lasts until the geometry of the four satellites improves or an additional satellite becomes available providing a new combination with more favorable geometry.

Since the navigation equation (8) we derived in the last section is a linear relationship, it can also be used to express the relationship between errors in pseudorange measurement and the errors in user position and clock bias. Mathematically, the relationship can be expressed

$$\varepsilon_{x} = \beta^{-1} \varepsilon_{r}$$

where

 $\mathbf{E_r}$ = pseudorange measurement errors

€ corresponding error in user position and clock bias

If we let

C_n = covariance matrix of errors in pseudorange measurements

and

C_v = covariance matrix of the resulting errors in the three components of user position and clock bias

then the matrix relationship between the two covariance matrices becomes

$$C_v = B^{-1} C_r B^{-T}$$
 (9)

where B is the same 4×4 matrix of coefficients of the unknowns that we derived previously and is a function only of the direction cosines of the LOS unit vectors from the user to the four navsats and the user's clock bias (17:10). Thus, the error relationships are functions only of satellite geometry, which leads to the concept of geometric dilution of precision as a measure of how satellite geometry degrades accuracy (14:99).

In order to provide a method of quantitatively determining whether a given satellite geometry is good or bad, we will assume that the geometric effects on the errors in pseudorange measurements are very small (a reasonable assumption). Thus, a good approximation of the geometric performance can be obtained by letting each individual pseudorange measurement have a one sigma error of unity; thus, the covariance matrix for the errors in pseudorange measurements becomes a 4×4 identity matrix (14:99). This means that the ranging errors from each satellite are assumed to be unity, completely random, and that the correlation of ranging errors between satellites is zero. To a good approximation,

$$C_{v} = (B^{\mathsf{T}}B)^{-1},$$

and assuming sufficient signal strength, this covariance matrix depends only on the *direction* and is in no way dependent on the *distances* between the user and each satellite (17:10). Since the diagonal elements of this covariance matrix are actually the variances of user position and time, various DOP values can be obtained from looking at appropriate elements of this matrix. These values can then be used to compare position accuracies (from a geometry standpoint) of different orbital configurations as well as to measure the overall effect of geometry to errors in the user's position and time bias.

Dilution of Precision Values

If we express the diagonal elements of the covariance matrix of errors in user position and clock bias as V_x , V_y , V_z , and V_T , then the four dimensional *geometrical dilution of precision* (GDOP) is obtained by taking the square root of the trace of the matrix:

GDOP =
$$[V_X + V_y + V_z + V_T]^{1/2}$$

This factor includes all four unknowns (three dimensions of position and time) and is the conventional measure of overall geometric performance.

A more frequently used measure of geometric performance is the three dimensional position dilution of precision (PDOP) which relates only to the three components of position error. PDOP is also invariant with the coordinate system and is used because the most important consideration in any navigation system is position accuracy; knowing time is a secondary byproduct (14:100). It is defined as the square root of the sum of the squares of the three components of position error, or mathematically:

$$PDOP = [V_x + V_y + V_z]^{\frac{1}{2}}$$

Several other alternative DOP values are also occasionally used in evaluating satellite constellations and relate only some of the variances of user position and time. These include the horizontal dilution of precision (HDOP), the altitude dilution of precision (YDOP), the time dilution of precision (TDOP), and the larger component of horizontal position error (MDOP). HDOP, VDOP, TDOP, and MDOP are the DOP factors that apply for the horizontal position error, the altitude error, the error in user clock bias (multiplied by the speed of light), and the larger component of the horizontal position error, respectively. They are defined mathematically as follows (17:10):

HDOP =
$$[V_x + V_y]^{\frac{1}{2}}$$

VDOP = $[V_z]^{\frac{1}{2}}$
TDOP = $[V_T]^{\frac{1}{2}}$
MDOP = Max $[(V_x)^{\frac{1}{2}}, (V_y)^{\frac{1}{2}}]$

Satellite Selection

In order to obtain the most accurate user position, it would be highly desirable to utilize those four satellites with the most favorable geometry (lowest DOP values) with respect to the user at any instant of time. This presents no problem, should there be only four visible satellites to choose from, as all four must be used to determine the user's three dimensional position. The majority of the time, however, there will be six or more satellites in view by an earth based user and even more by a low altitude satellite user, and the computational time required to compute PDOP values for all the possible combinations of satellites is excessive.

The results of many computer runs and analytical studies have demonstrated an almost total correlation between PDOP and the volume of a tetrahedron formed by lines connecting the tips of the four unit vectors from the user toward the four nevsats (17:11). Usually, the larger the volume of this tetrahedron, the smaller the corresponding PDOP value will be for this same set of satellites. Since the computational time for computing the volume of a tetrahedron for each different combination of satellites is much less than the time required to calculate a PDOP value (which requires a matrix inversion), the computer program used in this work as well as many other similar studies in the past is designed to first compute the volumes of the tetrahedrons associated with each different combination of four satellites, identify the "best four" which yield the largest tetrahedron volumes, and then use that combination of satellites to compute the DOP

values (17:12). Other methods of selecting the optimum four satellites may possibly be more efficient and have been the subject of many analytical studies, but they will not be addressed in this paper. The problem of satellite selection is not only a problem to those conducting global analyses of orbital constellations for evaluation, but it is just as significant a problem to the designers of User Set Equipment, as the equipment must be designed to operate quickly in a dynamic environment and large computer resources are not available.

IV. Baseline Constellation Analysis

Global Distribution Run

Introduction. The reference orbit parameters for the GPS baseline constellation used in this analysis are given in Table II. The computer program used in conducting the analysis was a modified version of a program developed by the Rand Corporation of Santa Monica, California, on the geometric performance of pseudoranging navigation satellite systems (17). This program, which itself is a modification of an earlier program, developed by the Aerospace Corporation for earth-based users, was selected for the evaluation over the computer program currently being used by the Aerospace Corporation, EGAD (Efficient GPS Availability Determination) Program (5:2), for several reasons. First, the Rand Corporation program had been modified to accommodate users in any earth orbit, while the EGAD program did not have any provision for the space-based user. The EGAD program, although a much longer program with many more capabilities, restricted the shape and size of the orbits of the navigation satellites; the program modified by the Rand Corporation allows the user to select any size or shape of the orbits of either the navsats or the user satellite. Finally, the Rand Corporation program includes a feature which allows for the variation of the navsat antenna beamwidth and determines the effect of this variation on navigational accuracy for satellite users; the EGAD Program has no such capability.

A modification was made to the Rand program to allow for the determination of the effect of satellite losses on the baseline or any other alternative constellation. In addition, a few corrections were found necessary in order for the program to give reliable statistics on DOP's when fewer than four satellites were visible. A minor modification of the program output was also made to provide the number of satellites visible to the space-based user when fewer than four satellites were available to the user satellite. A description of the program and its modifications

is provided in Appendix B, and the complete computer program listing is given in Appendix C.

TABLE II

Baseline Constellation Orbital Parameters (13: D2.3.3)

Satellite Number	Orbit <u>Plane</u>	Longitude of the Ascending Node [Deg]	Right Ascension of the Ascending Node [Deg ⁸]
1	1	000	030
2	1	060	030
3	1	120	030
4	2	080	090
5	2	1 4 0	090
6	2	020	090
7	3	160	150
8	3	040	150
9	3	100	150
10	4	060	210
11	4	120	210
12	4	000	210
13	5	1 <i>4</i> 0	270
14	5	020	270
15	5	080	270
16	6	040	330
17	6	100	330
18	6	160	330

^a Referenced to astronomical coordinates of 1950.0 as of 1 July 1985, 0 hr 0 min GMT and regressing at -0.04009 deg/day.

<u>Selection of Parameters</u>. For all global distribution runs, a uniform distribution of users is approximated by the DOP's of users at a given latitude by the cosine of that latitude. Whenever the constellation selected was a symmetrical arrangement of satellites, only the DOP's

for the northern hemisphere were calculated as this permitted a larger number of sample points to be selected for the analysis. Since the arrangement is symmetrical, an analysis (on a global basis only) of the same number of sample points uniformly distributed in the southern hemisphere would yield identical results. Consequently, the results shown for the analysis of the northern hemisphere are statistically representative of the entire globe.

The proper latitude and longitude step sizes were determined from the analysis of several data runs using alternative parameters. The largest step sizes that would provide statistically representative values were selected to provide a good balance between accuracy and computer computation costs, which are enormous for global distribution runs. The time increments used were selected in a similar manner.

For symmetrical constellations, the time interval selected for each run was four hours, since after this length of time, each satellite within the sastellation would have moved to the original position of the satellite adjacent (within the same orbit) to it at the start of the run. (Each satellite is separated from each other within the orbital planes by four hours.) Since this analysis was concerned only with the geometric performance of the baseline constellation for a global basis, rather than for specific user locations, this four hour time period provides statistically good data for any 24 hour period, due to the repetiveness of the satellite motion.

For the non-symmetrical constellations, the time interval analyzed was increased to six hours, or half the 12 hour orbital periods of the GPS satellites. This is the minimum time period that could be chosen to provide statistically representative data (on a global basis) for any 24 hour period. As a result of the longer time interval required for each run, the time increments were doubled in order to remain within computer constraints and yet still provide reasonably accurate data. Since the analysis in these cases focused on the comparative results between constellations analyzed, rather than exact DOP values, this step size was found to be adequate.

TABLE III

Baseline Constellation Orbital Elements

ORBITAL ELEMENTS												
	ECC	ARGP	RASC	INC	ANOM	PER						
		(Deg)	(Deg)	(Deg)	(Deg)	(Hrs)						
1	0.00	0.00	30.00	55.00	0.00	12.00						
2	0.00	0.00	30.00	55.00	120.00	12.00						
3	0.00	0.00	30.00	55.00	240.00	12.00						
4	0.00	0.00	90.00	55.00	40.00	12.00						
5	0.00	0.00	90.00	55.00	160.00	12.00						
6	0.00	0.00	90.00	55.00	280.00	12.00						
7	0.00	0.00	150.00	55.00	80.00	12.00						
8	0.00	0.00	150.00	55.00	200.00	12.00						
9	0.00	0.00	150.00	55.00	320.00	12.00						
10	0.00	0.00	210.00	55.00	120.00	12.00						
11	0.00	0.00	210.00	55.00	240.00	12.00						
12	0.00	0.00	210.00	55.00	360.00	12.00						
13	0.00	0.00	270.00	55.00	160.00	12.00						
14	0.00	0.00	270.00	55.00	280.00	12.00						
15	0.00	0.00	270.00	55.00	40.00	12.00						
16	0.00	0.00	330.00	55.00	200.00	12.00						
17	0.00	0.00	330.00	55.00	320.00	12.00						
18	0.00	0.00	330.00	55.00	80.00	12.00						

PARAMETERS USED IN GLOBAL DISTRIBUTION CALCULATIONS:

MASKING ANGLE = 5.00 DEGREES LATITUDE STEP = 10.00 DEGREES LONGITUDE STEP = 20.00 DEGREES TOTAL TIME (MIN) = 240 TIME INCREMENT (MIN) = 5

HEMISPHERE EVALUATED = NORTHERN

Results. If we define an "outage" to be situations where the PDOP for a given location at some time exceeds 6.0 (a 1-sigma ranging error of 7 meters would provide a RMS error of $6.0 ext{ x}$ 7m, or 42 meters in this case), as is commonly chosen on analyses of this nature, then we can observe (Table IV) that for the 18-satellite baseline constellation, outages occur only 0.55% of the time over a 24 hour period, or stated in another way, PDOP values of less than 6.0 are available 99.45% of the time.

TABLE IV

Baseline Constellation Global Distribution - DOP Values

DILUTION OF PRECISION PARAMETERS - ACCUMULATIVE GLOBAL DISTRIBUTION (Percentage of Time That DOP Value Shown is Exceeded)

VALUE	YDOP	HDOP	MDOP	IDOP	POOP	GDOP
0.0	1.0000	1.0000	1.0000	1.0000	1.0000	1.0000
1.0	1.0000	1.0000	.8772	.7294	1.0000	1.0000
2.0	.5489	.0397	.0141	.1080	.9832	.9976
3.0	.1183	.0060	.0041	.0098	.2125	.3149
4.0	.0288	.0025	.0025	.0049	.0523	.1080
5.0	.0055	.0025	.0025	.0041	.0114	.0317
6.0	.0049	.0025	.0025	.0041	.0055	.0103
7.0	.0041	.0025	.0025	.0025	.0041	.0055

The highlighted number represents the percentage of time that an *outage* occurs due to poor satellite geometry of the baseline constellation. A PDOP value greater than 6.0 is considered to constitute such an outage.

This agrees closely with a similar analysis conducted earlier by the Aerospace Corporation on the same six-plane constellation (15: E9.3.2), and verifies the accuracy of the data. If we choose to alternatively define an outage as a PDOP greater than 7.0, as some studies on earlier constellation designs have assumed, then we can see that PDOP's greater than 7.0 occur only 0.41% of the time for the proposed baseline constellation. Although this paper is concerned primarily with the PDOP values, statistics for all six DOP's are listed in Table IV, and a complete breakdown of each DOP by latitude is provided in the appendix.

The maximum and minimum number of satellites available to the user at each latitude and longitude are shown in Table V. (Note that not all latitudes and longitudes are observed.) The probabilities of n or more satellites being visible above a 5 degree elevation angle are shown in Table VI. For the proposed 18-satellite baseline constellation, at least four satellites are always available to the earth-based user, and consequently, the outages that occur are due solely to the poor geometry of the satellites available to the user. By examining the computer output located in the appendix on each individual DOP for each latitude, we can also determine the location of these outage areas during any 24 hour period. Typical location of outages and time durations for the six-plane constellation are depicted in Figure 6, 7, 8, and 9. As one can observe from either these pictorial presentations or by the computer output located in the appendix, the primary outage locations for the baseline constellation occur in pairs approximately centered on latitudes of 35N and 65S, with corresponding pairs centered at 35S and 65N, as shown in Figure 7.

TABLE V

Maximum and Minimum Numbers Seen at Each Latitude and Longitude

MAXIMUM

LONGITUDE (DEG)

						1	1	1	1	1	2	2	2	2	2	3	3	3
		2	4	6	8	0	2	4	6	8	0	2	4	6	8	0	2	4
LAT	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
90	8	8	8	8	8	8	8	8	8	8	8	8	8	8	8	8	8	8
80	8	8	8	7	8	8	8	8	7	8	8	8	7	8	8	8	8	7
70	8	8	8	8	8	8	8	8	8	8	8	8	8	8	8	8	8	8
60	8	8	8	8	8	8	8	8	8	8	8	8	8	8	8	8	8	8
50	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7
40	7	6	7	8	7	б	7	8	8	7	6	7	8	7	6	7	8	8
30	7	6	7	8	7	6	6	8	8	7	6	7	8	7	6	6	8	8
20	7	7	7	7	6	7	7	7	7	7	7	7	7	6	7	7	7	7
10	7	8	8	8	7	8	8	8	8	7.	8	8	8	7	8	8	8	8
0	7	8	7	8	8	8	8	7	8	7	8	7	8	8	8	8	7	8

MINIMUM

LONGITUDE (DEG)

		_		_	_	1	1	1	1	1	2	2	2	2	2	3	3	3
LAT	0	0	4	6	8	0	2	4	6	8	0	2	0	6	8	0	0	4
	•	-	-	-	•	•	•	•	٠	•	•	•		•	•	•	•	•
90	6	6	6	6	6	6	6	6	6	6	6	6	6	6	6	6	6	6
80	6	6	6	6	6	6	6	6	6	6	6	6	6	6	6	6	6	6
70	5	6	5	5	5	5	5	5	5	5	6	5	5	5	5	5	5	5
60	4	5	4	5	4	4	4	4	4	4	5	4	5	4	4	4	4	4
50	5	5	5	5	5	5	5	5	5	5	5	5	5	5	5	5	5	5
40	5	4	4	5	5	4	4	5	5	5	4	4	5	5	4	4	5	5
30	5	5	5	5	5	5	5	5	5	5	5	5	5	5	5	5	5	5
20	5	5	5	5	5	5	5	5	5	5	5	5	5	5	5	5	5	5
10	5	6	6	5	5	6	6	6	5	5	6	6	5	5	6	6	6	5
0	6	6	6	6	6	6	6	6	6	6	6	6	6	6	6	6	6	6

TABLE VI
Probability of Seeing N or More Satellites

NUMBER OF SATELLITES

LAT	0	1	2	3	4	5	6	7	8
		PROBAB	ILITY (IN F	PERCENT) (of seeing n	OR MORE S	ATELLITES		
00	100.00	100.00	100.00	100.00	100.00	400.00	400.00	70.64	70.44
90	100.00	100.00	100.00	100.00	100.00	100.00	100.00	30.61	30.61
80	100.00	100.00	100.00	100.00	100.00	100.00	100.00	62.13	3.40
70	100.00	100.00	100.00	100.00	100.00	100.00	97.05	42.40	16.78
60	100.00	100.00	100.00	100.00	100.00	98.41	77.78	44.22	11.34
50	100.00	100.00	100.00	100.00	100.00	100.00	73.02	7.03	0.00
40	100.00	100.00	100.00	100.00	100.00	94.33	57.6	8.84	1.36
30	100.00	100.00	100.00	100.00	100.00	100.00	52.61	14.51	2.72
20	100.00	100.00	100.00	100.00	100.00	100.00	74.38	21.32	0.00
10	100.00	100.00	100.00	100.00	100.00	100.00	89.57	47.85	4.99
0	100.00	100.00	100.00	100.00	100.00	100.00	100.00	57.37	1.36

ON A 6LOBAL BASIS THE PROBABILITY (IN PERCENT) THAT N OR MORE SATELLITES WILL BE VISIBLE NUMBER OF SATELLITES

PROB	0	1	2	3	4	5	6	7	8
	100.00	100.00	100.00	100.00	100.00	99.17	77.9	31.5	3.49

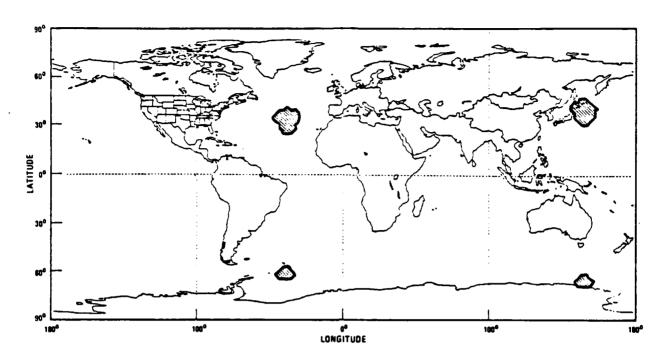


Figure 6. Typical Outages for the Baseline Constellation (15: E9.3.4)

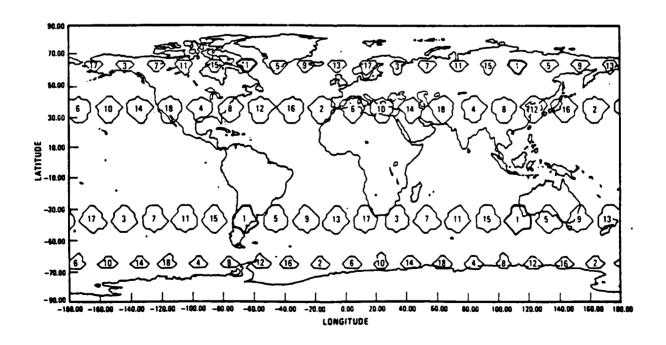


Figure 7. Composite Outages for the Baseline Constellation (15:E9.3.4)

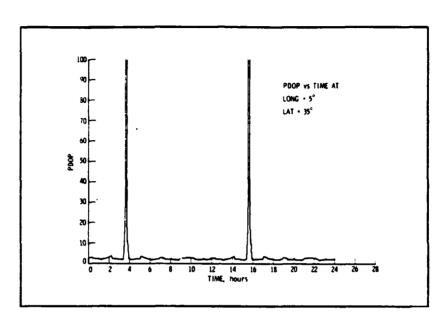


Figure 8. Sample Outage Time Profile for the Baseline Constellation (15: E.9.3.5)

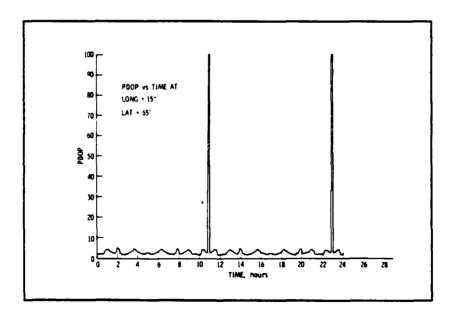


Figure 9. Sample Outage Time Profile for the Baseline Constellation (15:E9.3.5)

System Degradation Due to Satellite Losses

Introduction. The effect of satellite losses from the 18-satellite baseline constellation was also analyzed on a global basis, as this was one of several factors considered in selecting the optimum configuration of the 18 satellites. For this part of the analysis, it was assumed that no active, in-orbit spares were available. The effect upon geometric performance from losses of one to three satellites was evaluated was evaluated for several representative cases, with an emphasis on determining the best and worse cases possible, instead of on the expected performance due to random satellite losses, as most earlier studies have dealt with. "Best case" information might be particularly useful to those involved in the initial buildup of the constellation to its full operational 18-satellite configuration as a means of determining both the order and placement of each successive satellite deployment. Likewise, "worst case" scenarios might prove to be useful to those military planners seeking defenses against anti-satellite weapons that potential enemies might design and deploy. Since computer restraints did not permit all possible combinations of satellité losses to be analyzed (for the three satellite case there are 816 possible combinations). the satellite losses analyzed were carefully selected in order to determine the *most probable* best and worst cases. In addition, many of the combinations, due to the symmetric arrangement of the satellites and their repetitive nature, provided identical degradation of performance (from a global standpoint) and could be excluded. For example, if only one satellite is lost (or destroyed), any satellite selected will degrade the geometric performance in the same way as any other one satellite lost. (Only the location of the outages will differ, which could be of interest to military planners). Similarly, a loss of a pair of satellites (1) and (4) degrade system performance the same amount (on a global basis) as a loss of satellites (2) and (5), (3) and (6), (5) and (8), and many other symmetrically equivalent pairs. (One need only realize that in four hours satellites (1) and (4) move to the same inertial positions as (2) and (5) were originally located in order to understand this).

Results. By examining the tabular data on some representative runs in Table VII, one can easily see that which satellites are deleted from the constellation greatly affect the amount of degradation to system performance.

TABLE VII

System Performance Degradation Due to Satellite Losses

Satellites Deleted	% PDOP ≥ 6.0	% PDOP <u>>7.0</u>
None	.0055	.0041
6	.0230	.0198
1	.0232	.0201
1,5*	.0478	.0407
1,12	.0488	.0458
1,2	.0507	.0434
1,7	.0515	.0450
1,8	.0720	.0634
1,6	.0749	.0695
1,4	.0779	.0697
1,11	.0782	.0716
1,9	.0787	.0709
1,10**	.0800	.0725
4,5,6*	.0780	.0679
1,7,13	.1017	.0900
1,7,8	.1042	.0920
1,4,5	.1057	.0928
1,2,4	.1349	.1245
1,4,7	.1380	.1258
1,9,15	.1387	.1289
1,10,11	.1435	.1325
1,8,15**	.1584	.1454

^{*} Best Case

^{**} Worst Case

As is evident from this table, the percentage of time a system outage occurs in the two satellite loss "worst case" scenario is actually greater than the percentage of time that an outage occurs in the three satellite loss "best case" (8.00% versus 7.80%). The range of values (expressed as percentages of PDOP > 6) is rather widely spread from the best to worst cases, varying from 4.78% to 8.00% in the two satellite case and from 7.80% to 15.84% in the three satellite case. From examining this data, it appears that a loss of closely grouped satellites, such as three adjacent satellites within the same plane, provide the "best case" situation, while, as might be expected, losses of satellites widely separated generally result in the "worst case" scenario. For the three satellite (loss) cases analyzed, this is easily deduced from observing that the best case occurs when all satellite losses occur in the same plane, while the worst case occurs when the satellites deleted are separated to the maximum. From this information, it appears that should satellite losses be sustained. a significant improvement in performance might be obtained in the interim (until replacement spares could be launched) by rephasing the remaining satellites to provide as wide as possible average separation between all satellites per period. Should the three satellite spares already be on-orbit as presently planned, it suggests that these sparcs would be optimally positioned in every other orbital plane, and repositioned as necessary within each orbit when losses are sustained, to obtain the widest possible distribution of remaining satellites. Presently, the planned location for placement of these three additional in-orbit spares is depicted in Figure 10, and should provide this opportunity.

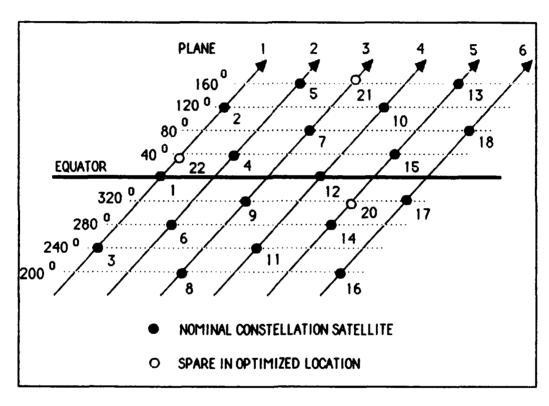


Figure 10. Baseline Constellation With Three Spares (15:E9.3.7)

Satellite User

Introduction. Although the Global Positioning System was designed for use by the earth or near-earth based user, its potential application for autonomous navigation of satellites and space navigation is highly desirable. Until recently, few studies have been conducted in this area, yet based on the those studies that have been made regarding this potential application, the results appear promising. At least one analysis has shown that a three-dimensional accuracy on the order of 100 meters can be obtained for autonomous navigation of geosynchronous satellites (13:D2.3.1), and even better accuracies can be achieved for space-based users at lower altitudes.

In analyzing the geometric performance of the baseline constellation for the satellite user, the antenna pattern design of the GPS satellites severely limits the times and numbers of GPS satellites that can be observed by the satellite user, particularly at the higher altitudes. In this somewhat limited analysis of the geometric performance of the GPS satellites for the satellite user, its potential for navigation of the spaceborne user was examined by analyzing DOP's obtainable for a user in low-earth orbit, high-earth orbit, and intermediate elliptical orbits, as well as for a high altitude ballistic missile trajectory. The effect of changing the antenna beam angle of the GPS satellites upon the geometric performance of the system for these spaceborne users was also analyzed to determine if significant improvement could be obtained, particularly for the high altitude user.

Antenna Design. The OPS satellites utilize a helical array that provides a conical shaped beam to cover the earth uniformly from their altitude of 10,900 nautical miles. This antenna array also provides a skirt within its main lobe that extends beyond the edge of the earth to a limited degree, and it is this part of the antenna pattern that the geosynchronous satellite user may utilize for navigation. For the L1 frequency, the main beam antenna gain at the edge of the

earth is approximately 14 dB, dropping gradually to about 3 dB at about 21.4 degrees from the satellite to earth center line, or an 11 dB variability in antenna gain (Figure 11) over this skirt region (13:D2.3.2).

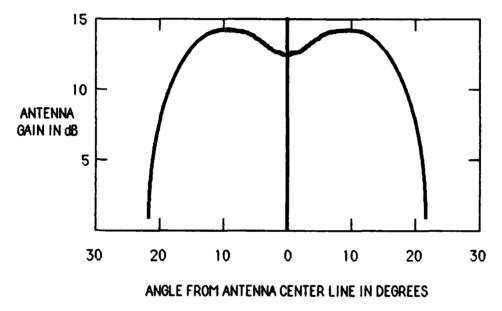


Figure 11. Main Beam Antenna Gain at L1 Frequency (13:D2.3.3)

As the user spacecraft approaches the GPS satellites, the NAVSTAR satellites keep their antennas directed toward the center of the earth, thus forcing the user to obtain signals coming from the NAVSTAR sidelobes and/or backlobe (11:432), as shown in Figure 12. Although at high altitudes, users will have only the edge of the antenna pattern available, this could be adequate for updating ephemerides if an accurate on-board clock is available (20:21.2.1).

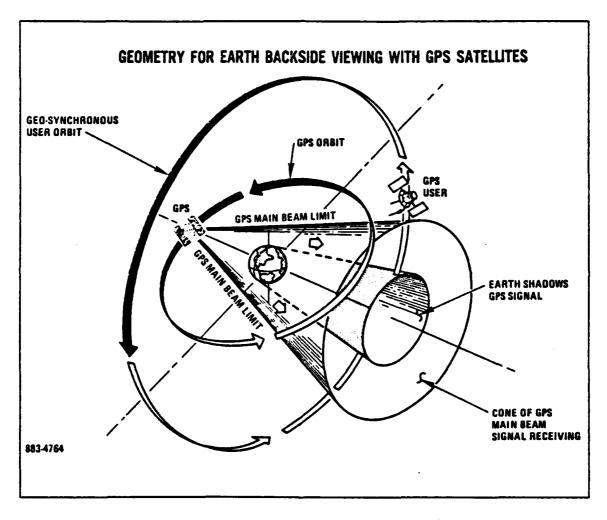


Figure 12. Main GPS Beam Geometry (11:432)

Low Altitude Earth Orbits. A 150 nautical mile altitude circular parking orbit (Case 1) was selected as a typical low altitude earth orbit for the evaluation. The orbit chosen had an inclination of 28 degrees and a 90 minute period. DOP values were computed at increments of 5 minutes over a total time of 12 hours. For the designed antenna half-angle beamwidth of 21.4 degrees, the PDOP values obtained were extremely good, as were expected, and ranged from a best value of 1.61 to a worst value of 2.155. Since the PDOP values using the designed antenna beamwidth were significantly better than even for the typical earth-based users, evaluation at other antenna beamwidths was not necessary.

1

Intermediate Altitude Earth Orbits. For this evaluation, a highly elliptical Hohman transfer orbit (Case 2) from a low altitude parking orbit to geosynchronous orbit was chosen as representative of an intermediate altitude earth orbit. The eccentricity of the selected orbit was 0.73, and it had a 0 degree inclination. The orbital period was 10.56 hours. DOP values were computed at 5 minute intervals over a 12 hour period. When analyzed with the designed antenna half-angle beamwidth of 21.4 degrees, four or more satellites were visible only 17.9% of the time, three or more satellites for 24.1% of the time, and two or more satellites for 51% of the time. No satellites were visible to the user in this orbit 29% of the time.

The same satellite user orbit was also analyzed using an antenna half-angle beamwidth of 45 degrees, with significantly better results. With this modification to antenna design, four or more satellites were available to the user at all times, with PDOP values ranging from 1.539 to 38.663. PDOP values less than 6.0 were achieved 35.2% of the time. The results are summarized in Table VIII.

Table VIII

Baseline Constellation Evaluation - Satellite User

% of Time n or More Satellites User Antenna Visible												
<u>Satellite</u>	<u>BWIDTH</u>	1	2	3	4	PDOP Range						
Case 1	21.4	100.0	100.0	100.0	100.0	1.61 - 2.155						
Case 2	21.4 45.0	71.0 100.0	51.0 100.0	24.1 100.0	17.9 100.0	1.544 - 1.539 - 38.663						
Case 3	21.4	100.0	100.0	100.0	100.0	1.537 - 1.818						
Case 4	21.4 45.0 90.0	62.8 100.0 100.0	29.5 100.0 100.0	12. 4 100.0 100.0	7.8 100.0 100.0	1.505 - 1.523 - 127.57 1.504 - 9.361						
Case 5	21.4 45.0 90.0 180.0	55.2 100.0 100.0 100.0	22.1 100.0 100.0 100.0	1.4 100.0 100.0 100.0	0.0 100.0 100.0 100.0	14.55 - 93.023 6.199 - 7.928 5.560 - 7.505						

Low Altitude ICBM Trajectory. A typical ICBM profile (Case 3) was chosen for this portion of the evaluation. The elliptical trajectory selected had an eccentricity of .55 and a period of about 1.2 hours. Time of flight from launch to impact was approximately 40 minutes, and the maximum altitude attained was slightly less than 1400 nautical miles. DOP values were computed at one minute intervals for the duration of the flight. As in the low altitude earth orbit (Case 1), exceptionally good PDOP values were achieved with the designed antenna beamwidth throughout the flight, ranging from 1.537 to 1.818, as shown in Table VIII. Four or more

satellites were always visible, and the PDOP values improved with increasing altitude all the way to approximately 1400 nautical miles.

High Altitude Ballistic Missile Trajectory. A highly elliptical ballistic trajectory (Case 4) with an eccentricity of .82 and a period of 11.05 hours was analyzed. Maximum altitude attained during flight was approximately 21,200 nautical miles. DOPs were computed at five minute intervals for the duration of the flight. For the designed antenna half-angle beamwidth, four or more satellites were visible only 7.8% of the time, three or more satellites only 12.4% of the time, and two or more visible only 29.5% of the time. There were no satellites visible 37.2% of the time.

When the same case was analyzed using an antenna half-angle beamwidth of 45 degrees, four or more satellites were always visible, with PDOP values ranging from 1.523 to 127.569. PDOP values less than 6.0 were achieved 20.9% of the time. As in the previous case, PDOP values actually improved from launch up to approximately 1400 to 1800 nautical miles in altitude. When the antenna half-angle beamwidth was increased to 90 degrees, PDOP values improved significantly, ranging from 1.504 to 9.361, and PDOP values less than 6.0 were achieved 50.3% of the time, and values less than 7.0 were achieved over 72% of the time.

High Altitude Earth Orbits. A circular, geosynchronous earth orbit (Case 5) was selected for evaluation and analyzed for several different antenna configurations. DOPs were again computed at five minute intervals over a 12 hour period. With the designed antenna beamwidth there were never four satellites visible. Three or more satellites were visible only 1.4% of the time, two or more 22.1% of the time, and one or more visible only 55.2% of the time. The geosynchronous user can observe no satellites 44.8% of the time with the designed antenna beamwidth.

When the antenna half-angle beamwidth was increased to 45 degrees (and higher), four or

more satellites were always visible (Table VIII), and PDOP values improved significantly with increasing beamwidth angle. At an antenna half-angle beamwidth of 90 degrees, PDOP values less than 7.0 were achieved 62.1% of the time. When increased even further to the maximum 180 degrees, PDOP values less than 7.0 were achieved 87.6% of the time, ranging from values of 5.56 to 7.505.

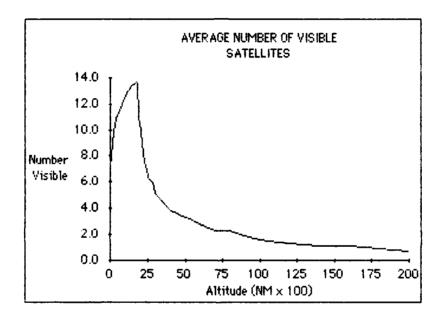


Figure 13. Average Satellite Visibility as a Function of Altitude

Summary. For the low altitude satellite user, the baseline GPS constellation will provide accuracies far exceeding those obtained on the earth's surface, as for these altitudes (less than about 1800 nautical miles), PDOP values generally improve with increasing altitude. More satellites are generally visible to choose from, resulting in better geometry, as shown in Figure 13. As the satellite user approaches higher altitudes, however, the constraints due to antenna beemwidth cause a significant degradation of performance and result in frequent outages caused by the insufficient number of satellites available to the user. Even in these situations, however,

navigation can be made possible by means of sequential measurements from the GPS satellites as they become visible to the user, a precise on-board clock, and the knowledge of the known orbital dynamics of the satellite. Furthermore, the improvements in accuracy that can be obtained by increasing the antenna half-angle beamwidth can certainly not be overlooked, as such a modification of antenna design could significantly increase the position accuracy available to the high altitude satellite user and should be considered if GPS is to be designed for space navigation as well as for tactical earth navigation.

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Another limitation on the use of GPS for space navigation is geometrical in nature. Not only is it necessary to have four satellites in view for three-dimensional positioning, but the positions of these satellites should be widely distributed about the user in all directions to minimize PDOP values. Even with unlimited antenna gain and 360 degree coverage (180 degree antenna half-angle beamwidth) there is a limit to the position accuracy that can be achieved at higher and higher altitudes, as the relative separation of the GPS satellites with respect to the user continues to diminish with distance. Consequently, the altitude dilution of precision (VDOP) becomes larger and larger, and primarily as a result of this growing component, the three dimensional position dilution of precision (PDOP) becomes exceedingly high. For this reason, GPS will probably never be practical for space navigation between planets in the solar system and beyond, but certainly is feasible for satellite navigation or for the navigation of other spacecraft designed for near- earth orbital operations.

V. Baseline Modification Analysis

The Modified Constellation

2

Introduction. The six-plane, 18-satellite constellation analyzed in Chapter IV was recognized as having better overall capability than a variety of other candidate 18-satellite constellations evaluated and is now considered to be the baseline GPS constellation. One of the primary reasons that this constellation was chosen over an earlier three-plane, nonuniform constellation baseline proposal was that a significant improvement of satellite coverage was obtained with the six-plane configuration (15:E9.3.8). The 99.5% coverage of the six-plane constellation was found to be significantly better than the 98.4% coverage of the three-plane constellation, since the difference between these two is a measure of the difference from total or 100% coverage and translates into size and duration of degraded performance areas (15:E9.3.2).

In all satellite constellations considered in the selection process, circular orbits of equal period were chosen as an essential feature; it had been assumed that elliptical orbits were advantageous for coverage of limited areas, but that the more uniform patterns provided by circular orbits were preferable for whole-Earth coverage (22:4). Walker's expectation that "continuous whole-Earth coverage would be provided most effectively by a system in which the distribution of satellites over the Earth's surface was maintained as uniform as possible, subject to the practical limitations imposed on a system necessarily involving multiple intersecting orbits," has been the underlying basis for this assumption. Although it would appear to be a reasonable assumption, it does not take into account the fact that system outages are caused not only by an insufficient number of satellites visible to the user, but also by the poor geometry (with respect to the user) that may exist for those satellites in view.

Since, for the baseline constellation, there are always four or more satellites in view to the

earth-based user, all outages that occur must be due to the poor relative geometry of the visible satellites; this was a direct observation from the global distribution analysis of Chapter IV. If a modification to this baseline constellation could be made that would result in more favorable geometry during these outage periods, without causing an increase in outages at other times, it seems logical to expect that coverage could be improved even further. Since a change in the shape of the orbit, or eccentricity, would result in a change in geometry, it seems reasonable to expect that elliptical orbits might provide such an opportunity.

Assumptions. It was assumed that the only modification to be made to the baseline constellation was to the eccentricity (shape) of the orbits. Thus, all modified constellations considered consisted of 18 satellites deployed in six elliptical planes, three satellites per plane, each with an orbital period of 12 hours. Each orbital plane had an inclination of 55° , and was separated from the next by 60 degrees in longitude. The three satellites in each orbital plane were uniformly distributed in time; this means that each was separated from the other within a particular orbit by four hours, or exactly one-third of the period. Relative phasing of the satellites from one orbital plane to the next remained at 40° ; this means that when an ascending satellite in one plane is crossing the equator, an ascending satellite in the adjacent plane to the east is 40° above the equatorial plane in its own orbital plane. Since elliptical orbits were used, the relative phasing of the satellites was approximated by positioning the ascending satellite in the adjacent plane to the east ahead of the equator by 40° of eccentric anomaly. For ease in constellation buildup, as well as in the evaluation and comparison with the baseline constellation, it was assumed that the eccentricity chosen for one orbit would be used for all six orbits.

<u>Choosing the Modified Constellation</u>. With the assumptions stated above, there still remained the difficult task of choosing the optimum orbital eccentricity and perigee locations, which, it was hoped, would provide the improved coverage desired. From a practical standpoint,

a small eccentricity would be desirable, as satellite stationkeeping and antenna pointing would be easier if the orbits were kept as nearly circular as possible. In addition, if the orbits were made too elliptical, outages would begin to occur due to periods when fewer than four satellites would be visible to a user, rather than due solely to poor geometry; this would negate any advantage attained by the improving geometry resulting from the elliptically-shaped orbits. Since this is exactly what occurred at eccentricities much greater than 0.1, an eccentricity of .05 was initially chosen as a starting point for the computer analysis.

Since a satellite in an elliptical orbit travels at slowest speed near apogee and at fastest speed near perigee, it spends the majority of its time near the apogee end of its orbit. By positioning the apogees of each orbit over a specific area of the earth where increased coverage is desired, a tremendous improvement in performance was noted; unfortunately, however, this was at the expense of a significant degradation of performance in other areas of the world. Thus, when the apogees of the orbits were positioned over the middle northern latitudes, the outages were virtually eliminated in the northern hemisphere while becoming more frequent and of longer duration in the southern hemisphere (Table IX). As a result of the preliminary computer runs, it was determined that a near optimum location, on a global basis, for the perigees of the modified elliptical orbits was in the plane of the equator, as outages occurred less frequently in these particular cases than any other location analyzed.

After analyzing several data runs for constellations with eccentricities ranging from .01 to .1 and with all perigees located in the equatorial plane, an eccentricity of .07 was selected as the optimum value of eccentricity that would minimize the percentage of time outages would occur (Table IX). It is significant to note that all eccentricities between .01 and .1 provided superior performance than that of the baseline constellation in terms of reducing system outages.

TABLE IX
Global Distribution Preliminary Data Runs

Eccentricity	Arg of Perigee [Deg]	<u>Hemisphere</u>	% PDOP <u>> 6.0</u>	%PDOP <u>>7.0</u>
.05	239.7	Northern	.0012	.0010
.05	239.7	Southern	.0107	.0087
.02	239.7	Northern	.0070	.0048
.02	239.7	Southern	.0084	.0068
.05	224.5	Northern	.0009	.0003
.05	224.5	Southern	.0114	.0106
.02	224.5	Northern	.0028	.0023
.02	224 .5	Southern	.0082	.0069
.02	198.4	Northern	.0032	.0025
.02	198.4	Southern	.0071	.0062
.01	0.0	Northern	.0048	.0039
.02	0.0	Northern	.0041	.0037
.03	0.0	Northern	.0041	.0034
.04	0.0	Northern	.0038	.0029
.05	0.0	Northern	.0040	.0026
.07	0.0	Northern	.0029	.0017
.085	0.0	Northern	.0034	.0015
.10	0.0	Northern	.0037	.0016

Global Distribution Run

Introduction. Since the modified constellation selected was, like the baseline constellation, a symmetrical arrangement of satellites, only the DOP's for the northern hemisphere were calculated. The DOP's for the southern hemisphere are identical for a global analysis. The latitude, longitude, and time steps were chosen to be the same as used for the baseline constellation global distribution run, which allowed for the direct comparison of the

results. The time interval selected for the run, as in the case of the baseline constellation, was four hours, as after this length of time the pattern of outages was repetitive due to the symmetric arrangement of satellites.

TABLE X

Modified Constellation Orbital Elements

	ORBITAL ELEMENTS													
	ECC	ARGP	RASC	INC	ANOM	PER								
		(Deg)	(Deg)	(Deg)	(Deg)	(Hrs)								
1	0.07	0.00	30.00	55.00	0.00	12.00								
2	0.07	0.00	30.00	55.00	126.60	12.00								
3	0.07	0.00	30.00	55.00	233.40	12.00								
4	0.07	0.00	90.00	55.00	42.80	12.00								
5	0.07	0.00	90.00	55.00	160.30	12.00								
6	0.07	0.00	90.00	55.00	269.50	12.00								
7	0.07	0.00	150.00	55.00	83.80	12.00								
8	0.07	0.00	150.00	55.00	193.90	12.00								
9	0.07	0.00	150.00	55.00	310.00	12.00								
10	0.07	0.00	210.00	55.00	123.30	12.00								
11	0.07	0.00	210.00	55.00	230.00	12.00								
12	0.07	0.00	210.00	55.00	355.70	12.00								
13	0.07	0.00	270.00	55.00	161.40	12.00								
14	0.07	0.00	270.00	55.00	270.60	12.00								
15	0.07	0.00	270.00	55.00	44.10	12.00								
16	0.07	0.00	330.00	55.00	198.60	12.00								
17	0.07	0.00	330.00	55.00	315.90	12.00								
18	0.07	0.00	330.00	55.00	89.40	12.00								

PARAMETERS USED IN GLOBAL DISTRIBUTION CALCULATIONS:

MASKING ANGLE = 5.00 DEGREES
LATITUDE STEP = 10.00 DEGREES
LONGITUDE STEP = 20.00 DEGREES
TOTAL TIME (MIN) = 240
TIME INCREMENT (MIN) = 5
HEMISPHERE EVALUATED = NORTHERN

Results. The results of the global analysis computer run for the modified constellation are shown in Table XI. It is significant to note that, for the modified constellation, outages occur only 0.29% of the time, or stated in another way, PDOP values of less than 6.0 are available 99.71% of the time; this represents a 47% reduction of outages over the baseline constellation (Figure 14), which has outages occuring 0.55% of the time. If PDOP values greater than 7.0 are used as a means of comparison, outages (PDOP values greater than 7.0) are reduced by over 58%.

TABLE XI

Modified Constellation Global Distribution - DOP Values

DILUTION OF PRECISION PARAMETERS - ACCUMULATIVE GLOBAL DISTRIBUTION (Percentage of Time That DOP Value Shown is Exceeded)

VALUE	YDOP	HDOP	MDOP	<u>TDOP</u>	PDOP	GDOP
0.0	1.0000	1.0000	1.0000	1.0000	1.0000	1.0000
1.0	1.0000	1.0000	.8260	.7297	1.0000	1.0000
2.0	.5681	.0439	.01 8 5	.1009	.9849	.9991
3.0	.1202	.0030	.0018	.0143	.2257	.3430
4.0	.0334	.0009	.0006	.0018	.0650	.1111
5.0	.0063	.0004	.0004	.0013	.0138	.0431
6.0	.0022	.0004	.0003	.0011	.0029	.0114
7.0	.0012	.0003	.0003	.0009	.0017	.0028

The highlighted number represents the percentage of time that an *outage* occurs due to poor satellite geometry of the baseline constellation. A PDOP value greater than 6.0 is considered to constitute such an outage.

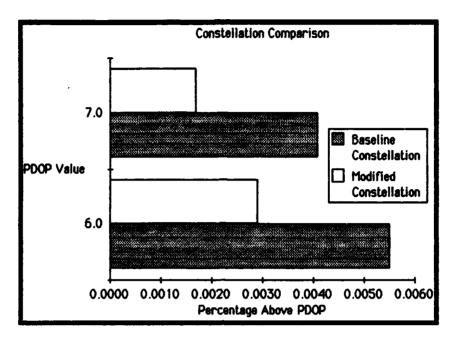


Figure 14. Comparison of System Outages

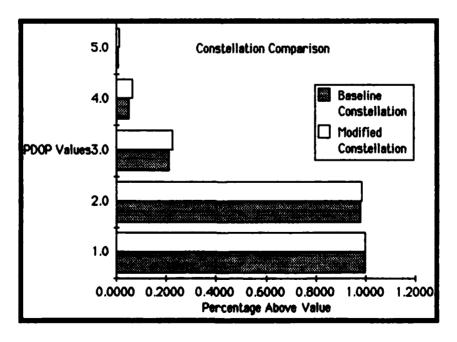


Figure 15. Comparison of PDOP Values Less Than 6.0

This reduction in system outages that occurs with the modified system is not without *some* cost. The cost of this increased coverage, however, is limited to a very slight reduction in the percentage of times that the best PDOP values are obtainable, as depicted in Figure 15. An examination of the data in Table XII and Table XIII provides the reason for this slight degradation of the best PDOP values obtainable. Although the minimum and maximum number of satellites visible to the global user remained basically the same as for the baseline constellation, the distribution of their occurrences did not. Since the analysis showed that there were always four or more satellites visible to the earth-based user for both the baseline constellation and the modified system, the outages that occurred were attributed to the poor relative geometry of the four satellites selected. In almost every case where this occurred for the baseline constellation, there were only the minimum number of four satellites from which to choose from. A close examination of Table VI confirms this, as the data clearly shows that five or more satellites were in view 100% of the time at all northern latitudes sampled except at 60°N and 40°N, which were also the latitudes at which the outages occurred.

The modified constellation, however, provides a higher probability of seeing five or more satellites at these same latitudes, which means that in addition to the change in relative geometry of satellites provided by the elliptical orbits, additional satellites from which to choose are made available over the specific regions of the earth where the outages had occurred. Consequently, the addition of a fifth satellite over these areas provided an opportunity for a better relative geometry of the four satellites selected and eliminated nearly half the outages that had previously occurred in these areas. Since this fifth satellite was provided at the expense of a reduction of the number of satellites available in other areas which previously had a higher number of satellites from which to select, the best PDOP values obtainable in these other areas were slightly degraded. Thus, although on a global basis the modified constellation provided a slightly lower probability in

percent (98.92% to 99.17%) that five or more satellites would be seen, it effectively redistributed the "wealth" by targeting those areas of the world with weakest coverage.

TABLE XII

Maximum and Minimum Numbers Seen at Each Latitude and Longitude-Modified Constellation

MUMIXAM

LONGITUDE (DEG)

						1	1	1	1	1	2	2	2	2	2	3	3	3
		2	4	6	8	0	2	4	6	8	0	2	4	6	8	0	2	4
LAT	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
90	8	8	8	8	8	8	8	8	8	8	8	8	8	8	8	8	8	8
80	7	8	8	8	7	8	8	8	7	8	8	7	7	8	8	8	8	7
70	8	8	8	8	8	8	8	8	8	8	8	8	8	8	8	8	8	8
60	8	8	8	8	8	8	8	8	8	8	8	8	8	8	8	8	8	8
50	7	7	7	7	7	7	7	7	6	7	7	7	6	7	7	7	7	7
40	7	6	6	8	7	7	6	8	8	7	7	6	8	7	6	6	8	8
3 0	7	7	6	7	7	7	6	8	8	7	7	6	7	7	7	6	7	7
20	6	8	7	7	6	8	8	7	7	7	7	7	7	6	8	8	7	7
10	7	8	7	8	8	8	8	7	7	7	8	7	7	7	8	8	7	7
0	7	8	7	7	8	7	7	7	8	7	8	7	8	7	8	8	7	7

MIMIMUM

LONGITUDE (DEG)

						1	1	1	1	1	2	2	2	2	2	3	3	3
		2	4	6	8	0	2	4	6	8	0	2	4	6	8	0	2	4
LAT	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
90	6	6	6	6	6	6	6	6	6	6	6	6	6	6	6	6	6	6
80	6	6	6	6	6	6	6	6	6	6	6	6	6	6	6	6	6	6
70	5	6	6	5	5	5	6	5	5	5	6	5	5	5	5	5	5	5
60	4	5	5	5	4	4	5	5	4	4	6	5	5	4	6	5	5	5
50	5	5	5	5	5	5	5	5	5	5	4	5	5	5	4	4	4	5
40	5	4	4	5	5	4	4	4	5	5	4	4	5	5	4	4	5	5
30	5	5	4	5	5	5	5	5	5	5	5	5	5	5	5	5	5	5
20	5	5	4	4	5	5	5	4	5	5	5	4	4	5	5	5	4	5
10	5	6	6	6	5	6	6	6	5	5	6	6	5	5	6	6	5	5
0	6	5	5	5	6	6	5	5		6			5		6	5	5	5

TABLE XIII

Probability of Seeing N or More Satellites-Modified Constellation

NUMBER OF SATELLITES

LAT	0	1	2	3	4	5	6	7	8
		PROBAB	ILITY (IN P	PERCENT) (of seeing n	OR MORE S	ATELLITES		
90	100.00	100.00	100.00	100.00	100.00	100.00	100.00	40.82	24.49
80	100.00	100.00	100.00	100.00	100.00	100.00	100.00	61.22	3.51
70	100.00	100.00	100.00	100.00	100.00	100.00	96.03	42.40	14.97
60	100.00	100.00	100.00	100.00	100.00	99.21	82.54	41.27	10.20
50	100.00	100.00	100.00	100.00	100.00	99.32	70.07	12.47	0.00
40	100.00	100.00	100.00	100.00	100.00	95.12	62.02	7.26	1.59
30	100.00	100.00	100.00	100.00	100.00	99.89	63.49	14.97	.23
20	100.00	100.00	100.00	100.00	100.00	97.85	74. 49	20.86	1.36
10	100.00	100.00	100.00	100.00	100.00	100.00	94.44	45.24	2.04
0	100.00	100.00	100.00	100.00	100.00	100.00	96.71	52.61	1.81

ON A GLOBAL BASIS THE PROBABILITY (IN PERCENT) THAT N OR MORE SATELLITES WILL BE VISIBLE NUMBER OF SATELLITES

PROB	0	1	2	3	4	5	6	7	8
	100.00	100.00	100.00	100.00	100.00	98.92	80.25	30.42	2.79

System Degradation Due to Satellite Losses

Introduction. The effect of satellite losses from the modified baseline constellation was analyzed for comparison with the results obtained from the analysis of the baseline constellation discussed in Chapter IV. For this limited analysis, the effect upon geometric performance from losses of one to three satellites was evaluated for the same cases that provided both the best and worst performance for the baseline constellation. Whether or not these cases are the equivalent best and worst cases for the modified constellation as well remains to be determined, but since this part of the analysis was conducted solely for the purpose of comparing the two constellations, these cases should provide adequate representation of the broad range of effects.

For each computer run, a ten minute time increment was selected and the constellation was evaluated over a six hour period. The latitude and longitude step sizes were 20° and both hemispheres were evaluated. These parameters were identical to those used in the analysis of satellite losses from the baseline constellation, which adds validity to the comparison.

Results. The percentage of time that system outages occurred due to satellite losses from the modified constellation are listed in Table XIV. The percentages in brackets represent the corresponding values obtained for the same losses analyzed for the baseline constellation (Table VII). In practically every case, the modified baseline constellation provided superior performance over the baseline constellation. As seen in the baseline analysis, the particular satellites removed from the constellation made a large difference in the amount of degradation occurring; outages occurred in the three satellite loss case from 8.11% to 15.3% of the time and in the two satellite case from 4.55% to 7.47% of the time, representing the best and worst case scenarios.

TABLE XIV

System Performance Degradation Due to Satellite Losses- Modified Constellation

Setellites Deleted	% PDOP <u>> 6.0</u>	% PDOP ≥ 7.0		
1	.0228 [.0232]	.0161 [.0201]		
1,5*	.0455 [.0478]	.0329 [.0407]		
1,10**	.0774 [.0800]	.0661 [.0725]		
4,5,6*	.0811 [.0780]	.0574 [.0679]		
1,8,15**	.1530 [.1584]	.1349 [.1454]		

^{*} Best Case

Satellite User

Introduction. In analyzing the geometric performance of the modified baseline constellation for the satellite user, three cases were considered: an intermediate altitude earth orbit, a high altitude earth orbit, and a high altitude ballistic missile trajectory. The low altitude earth orbit and ICBM trajectory were not considered for this analysis as it was assumed that the modified constellation would provide outstanding geometric performance for these two users, as had been the case with the baseline constellation. In any event, the three cases selected were representative of the wide range of potential satellite users and were considered adequate for the purposes of this limited comparison.

The parameters selected for the computer analyses of each case were identical with those used in the analyses of these cases for the baseline constellation, and the cases analyzed were identical to those described in Chapter IV. It was assumed that the GPS antennas remained pointed

^{**} Worst Case

at the center of the earth throughout the orbit of the satellites, and that a sufficiently strong signal was available to the user satellite at all distances.

Intermediate Altitude Earth Orbits. The orbital parameters of the highly elliptical satellite user orbit considered were described in Chapter IV (Case 2). It was analyzed for an antenna half-angle beamwidth of 21.4 degrees and 45 degrees. With the designed antenna half-angle beamwidth of 21.4 degrees, four or more satellites were visible 18.6% of the time compared with 17.9% for the baseline constellation. Three or more satellites were visible 26.2% of the time versus 24.1% for the baseline, and two or more satellites were visible 53.8% of the time compared with 51% for the baseline. No satellites were visible to the satellite user 27.6% of the time.

When the same user orbit was analyzed using an antenna half-angle beamwidth of 45 degrees, as in the case of the baseline analysis, significantly better results were obtained. Four or more satellites were available to the user at all times during its orbit, with PDOP values ranging from 1.53 to 123. PDOP values less than 6.0 were achieved 32.4% of the time compared with 35.2% for the baseline constellation. The results are summarized in Table XV.

High Altitude Ballistic Missile Trajectory. The same highly elliptical missile trajectory (Case 4) described in Chapter IV was used in this analysis as had been used for the baseline analysis. Half-angle beamwidths of 21.4 and 45 degrees were selected for the comparison evaluation. With the designed antenna half-angle beamwidth, four or more satellites were visible to the user 7.8% of the time, identical to the results of the baseline analysis. Three or more satellites were available 14.0% of the time compared to the baseline 12.4%, two or more were visible 30.2% of the time versus 29.5% for the baseline, and one or more satellites were available 61.2% of the time compared to 62.8% for the baseline constellation. There were no satellites visible 38.8% of the time. When the half-angle beamwidth was increased to 45 degrees,

four or more satellites were always visible, as was found to be the case for the baseline constellation. PDOP values less than 6.0 were achieved in this case 22.5% of the time, which was a slight improvement over the 20.9% achieved by the baseline constellation.

Table XV

Modified Constellation Evaluation - Satellite User

User	Antenna	% of 'Vis				
Satellite	BWIDTH	1	2	3	4	PDOP Range
Case 2	21.4 45.0	72.4 100.0	53.8 100.0	26.2 100.0	18.6 100.0	1.536 - 1.539 - 123
Case 4	21.4 45.0	61.2 100.0	30.2 100.0	14.0 100.0	7.8 100.0	1.506 - 1.598 -345
Case 5	21.4 45.0 90.0	53.8 100.0 100.0	25.5 100.0 100.0	2.7 100.0 100.0	0.0 100.0 100.0	14.4 - 166.2 5.7 - 8.8

High Altitude Earth Orbits. A circular geosynchronous orbit was selected (Case 5) for evaluation at antenna half-angle beamwidths of 21.4, 45, and 90 degrees. With the designed antenna beamwidth, there were never four satellites visible. Three or more satellites were visible 2.7% of the time for the modified constellation compared with 1.4% of the time fur the baseline. Two or more satellites were visible 25.5% of the time and one or more visible only 53.8% of the time, compared with 22.1% and 55.2% respectively for the baseline.

When the antenna half-angle beamwidth was increased to 45 degrees and higher, four or more satellites were always available to the user. At a half-angle beamwidth of 90 degrees, PDOP values less than 7.0 were achieved 75.8% of the time compared with 62.1% of the time for the baseline constellation.

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Summary. The geometric performance of the modified constellation for the satellite user is probably slightly favorable to that of the baseline constellation. For all three cases analyzed, the modified constellation generally provides more satellites available to the user when less than four satellites are available. When more than four satellites are visible to the user, PDOP values less than 6.0 or 7.0 are achieved a higher percentage of time than for the unmodified baseline constellation, resulting in fewer outages. Although only a limited number of representative orbits were considered in the analysis, one can only conclude from the results that the modified constellation performs at least on an equal basis with that of the baseline constellation for the typical satellite user, and probably better. Although GPS performance for the space-based user was not considered as a factor in the selection of the baseline constellation, it certainly merits consideration. Both the baseline constellation and the modified constellation show great potential for use in near-earth space navigation.

VI. Conclusions/Recommendations

The Baseline Satellite Constellation

The 18-satellite configuration now considered the GPS baseline constellation will provide nearly continuous coverage on a worldwide basis to its earth-based users, providing them with positioning capability of high accuracy on the order of tens of meters. Those system outages that do occur with the proposed system will be due solely to the poor geometry of the selected satellites, and these outages will only occur (on an average) approximately one-half percent of the time. The duration of these outages will be brief (5-30 minutes) and the locations predictable.

Satellite losses sustained by the 18-satellite constellation will significantly degrade the coverage available, and the amount of degradation caused by such losses will be largely dependent on the relative positions of those satellites lost. Should replacement spares be unavailable, rephasing the remaining satellites could substantially improve the coverage until the constellation is restored to its original number. The planned placement of three active, in-orbit spares should greatly increase the system's reliability and provide some flexibility in rephasing satellites to compensate for unplanned losses.

For the satellite or space-based user, the feasibility of using GPS for positioning in the conventional way is primarily a function of both the user's altitude and the antenna beamwidth of the GPS satellites. With the currently designed antenna half-angle beamwidth of 21.4 degrees, the low- altitude satellite user will usually have positioning accuracy capability superior to that of the typical global user due to the increased number of satellites from which to select and the resulting better geometry. Due to the limiting constraints of the antenna beamwidth, however, the space-based user's positioning accuracy will rapidly deteriorate with increasing altitude, as fewer and fewer satellites remain available for selection. Outages become more and more frequent

until altitudes are reached where conventional positioning using four satellites simultaneously becomes impossible. Modifying the antenna beamwidth design of the GPS satellites appears very promising for expanding the usefulness of GPS to the high altitude satellite user, but even without such a modification, greatly improved positioning capability for these users can be obtained by taking sequential measurements from GPS satellites as they become available. Equipping the receiver with a precise clock and incorporating these sequential measurements with the memory inherent in the known orbital dynamics of the satellite will make nevigation possible for these users as well.

The Baseline Modification

In an attempt to improve the geometric performance of the baseline constellation by reducing the number and duration of system outages, a modification was made to the baseline constellation which changed the shape of the circular GPS satellite orbits to slightly elliptical ones, each with an eccentricity of .07. The perigee of each satellite orbit was positioned in the plane of the equator; all other orbital parameters remained unchanged. This modification reduced the percentage of system outages occurring on a global basis by nearly 50%, which was a significant improvement in coverage over the baseline constellation. The "cost" for this improvement was a slight reduction in the best accuracies attainable for some areas of the world.

Although elliptical orbits are certainly advantageous for coverage of limited areas of the world, it has generally been assumed that circular orbits are preferable for whole-earth coverage. This assumption, however, does not appear to be valid at least in this particular case, as the outages that occurred with the baseline constellation were due solely to the poor geometry of the available satellites, and not to the lack of sufficient satellites for measurements. Changing the eccentricity of the satellite orbits resulted in a more favorable satellite geometry relative to the

users on a global average; consequently, fewer outages occurred.

The modified constellation also compared favorably to the baseline constellation with respect to the space-based user, providing positional accuracy generally better than that provided to the user by the unmodified constellation. Since only a limited number of user orbital trajectories were examined, it can only be concluded that the modified constellation provides the space-based user with positioning accuracy comparable to that of the baseline, and *perhaps* better.

The effect of satellite losses from the modified constellation were also examined for the cases which provided both the best and worst navigational performance for the baseline constellation. In almost every case, the modified constellation provided better overall coverage than the baseline constellation.

Recommendations

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Although the location and duration of system outages is considered a significant factor in selecting the optimum 18-satellite GPS constellation, other factors may make the proposed modification to the baseline constellation impractical to implement. It has been assumed that the necessary satellite station-keeping is available to maintain the orbital pattern for the expected lifetime of the satellite; precession of the line of apsides (perigee movement) due to earth oblateness, for example, is approximately .022 degrees per day, and would require periodic corrections. Further analysis is recommended to determine the feasibility of this modification to the proposed baseline constellation. Since the primary intent of this analysis was to determine whether changing the eccentricity of the GPS satellite orbits *could* improve geometric performance and reduce the percentage of system outages, and *not* to find the optimal constellation, other elliptical variations of the baseline should also be analyzed for comparison.

The fessibility of modifying GPS antenna design to better accommodate the space-based user

should also be closely examined. Although GPS was not originally designed for use in space navigation, the potential applications into this area appear very promising. Increasing the antenna beamwidth, if practical, would greatly improve the availability of the GPS satellites to users operating in space, and would make available to the user extremely accurate estimates of position.

Appendix A

Glossary of Technical Terms

Antenna Half-angle Beamwidth - the angle between the antenna centerline and the edge of the main lobe skirt of the GPS antenna pattern

Apogee - the point in a satellite's orbit farthest from the central attracting body (earth)

<u>Argument of Perioce</u> - the angle, in the plane of the satellite's orbit, between the ascending node and the periopsis point (perioce), measured in the direction of satellite motion

<u>Ascending Node</u> - the vector pointing from the center of the earth to the satellite as it passes through the fundamental (or equatorial) plane in a northerly direction

<u>Clock Bias</u> - the error, or fixed bias, in the user's imprecise clock relative to GPS system time provided by the GPS satellites which contributes an error in range measurement

<u>Dilution of Precision</u> (<u>DOP</u>) - a parameter used for measuring system position accuracy of the GPS satellites as a function of the variability of satellite geometry

<u>Direction</u> <u>Cosines</u> - the numbers, representing the cosines of three angles, which completely define the direction of a given vector relative to a given coordinate system

Eccentric Anomaly – the angle between the semi-major axis of an ellipse and a point on a circle circumscribed about the ellipse represented by the interesection of that circle with a line, perpendicular to the semi-major axis, through the point of interest on the ellipse

Eccentricity - a constant defining the shape of an elliptical or other conic orbit

Fundamental Plane - the plane of the equator

<u>6DOP</u> - the geometric dilution of precision, a parameter which reflects the dilution of precision of position accuracy in three dimensions plus time

<u>Geosynchronous</u> <u>Orbit</u> - a circular orbit with a period of 24 hours, situated in the plane of the equator, such that the satellite always remains over the same point of the earth

<u>Hohman Transfer</u> - an elliptical transfer orbit between two circular orbits requiring minimum fuel for the maneuver

HDOP - the horizontal dilution of precision, a parameter which reflects the dilution of precision of position accuracy in the two horizontal directions

Inclination - the angle which describes the orientation of the orbital plane with the plane of the equator

<u>lonospheric</u> <u>Delay</u> - the time delay of RF signals passing through the ionosphere due to a reduction of speed and bending of the ray from refraction, inversely proportional to the square of the frequency

Julian Time - the time from which the Julian Calendar dates (46 B.C.)

<u>Longitude of Ascending Node</u> - the angle, in the plane of the equator, between the vector pointing to the vernal equinox and the ascending node, measured counterclockwise when viewed from the north side of the fundamental plane

<u>Masking Angle</u> - the minimum elevation angle, due to terrain obstructions and the earth's atmosphere, that a GPS satellite can have relative to the user and still be usable

MDOP - a parameter which reflects the dilution of precision of position accuracy in the larger component of the horizontal position error

Orbital Elements - the six, independent quantities which are sufficient to completely describe the size, shape, and orientation of an orbit and the position of the satellite along the orbit at a particular time

<u>Outage</u> - a situation occurring for a user at a specific location and time period when positioning capability is unavailable due to either unfavorable satellite geometry or an insufficient number of visible GPS satellites (less than four)

PDOP - the position dilution of precision parameter which reflects the dilution of positioning accuracy in three dimensions

Perioce - the point in a satellite's orbit closest to the earth

<u>Period</u> - the time required for a satellite to traverse its entire orbit one time, dependent only on the size of the semi-major axis

<u>Pseudorange</u> - the sum of the actual range displacement from the user to GPS satellite plus the offset due to the user time error (clock bias)

Relative Phasing - the number of degrees that an ascending satellite in one orbital plane is above the equatorial plane relative to an ascending satellite which is crossing the equatorial plane in an adjacent orbital plane to the west

<u>Satellite</u> <u>Constellation</u> - a particular arrangement or configuration of a specific number of satellites

Satellite Geometry - the geometrical relationship of the four selected GPS satellites relative to the user and each other

<u>Satellite Visibility</u> - a measurement of the number of satellites above a minimum elevation angle (masking angle) visible to a user at a specific time and location

Semi-major Axis - a constant defining the size of a conic orbit

Satellite User - a GPS user situated in space (space-based user)

<u>Sidereal</u> <u>Time</u> - the time based on a sidereal day, which is defined as the time required for the earth to rotate once on its axis relative to the stars (approximately $23^h56^m04^s$ of solar time)

TDOP - the dilution of precision in time which is an estimate of the range equivalent of the user clock bias

<u>True Anomaly</u> - the angle, in the plane of the satellite's orbit, between periapsis and the position of the satellite at a particular time, or epoch

<u>Universal Time</u> - the local mean solar time on the Greenwich meridian, also called Greenwich Mean Time or Zulu time

YDOP - the parameter reflecting the dilution of precision in the vertical dimension (altitude error)

<u>Appendix B</u> <u>The Computer Program</u>

Introduction

The computer program used for the analysis of all satellite constellations evaluated in this study is a modification of a Fortran program, developed by the Rand Corporation, on the geometric performance of pseudoranging satellite systems (17). Since a complete, detailed description of the original program and its operation can be found in Reference 17, the information contained in this appendix will be limited to an explanation of the variables and subroutines used in the program and the modifications made. In addition to providing the complete program listing in Appendix C, a sample of the output for the two types of cases (global distribution and satellite user calculations) analyzed in this study is provided in Appendix D.

There are three types of calculations performed by the program: in Case I, the user is on a satellite; in Case II, the user is positioned at a specific latitude and longitude on the earth's surface; and, in Case III, a group of users are located at a set of latitudes and longitudes forming a net over the whole surface or an entire hemisphere of the earth (17:15). Since only Case I and Case III were used in this evaluation, no sample output is provided for Case II; that portion of the program was not modified and will not be addressed in this discussion.

Program Modifications

The original program was written in Fortran IV and implemented on an IBM 370/158 computer. This version of the program has been converted to Fortran V for compatibility with a Fortran V compiler. The size dimension of matrix KXX in the main program and in subroutines TAAT and TALL was reduced to accompdate a maximum of 24 navsats, rather than the 36 navsats

provided for in the original program; this was done to cut down on the memory core storage used in the program's operation. A local library matrix inversion routine (LINV2F), was substituted for the matrix inversion routine used in subroutine COVNAV of the original program, and for greater ease in entering data, formatting was changed to allow free field data input.

Although the original program contained statements that would allow the program to continue operation when less than four satellites were available to the earth-based user, it did not consider these occurrences in the calculations of DOP values and thus provided erroneous data for the global distribution calculations when this occurred. The program was modified to incorporate these situations into the probability calculations of DOP values and thus provide accurate data. For the satellite user, it was discovered that the original program's output was not affected by a change in antenna beamwidth; this problem was corrected in the current version. A modification was also made to the satellite user portion of the program to provide as output the number of navsats available to the user when less than four satellites were visible; the original program did not provide this information as output.

Since average DOP values were not calculated by the program for the global distribution runs (the primary interest was in determining when the DOP values would exceed certain limits and cause system outages to occur), additional statements were added to the program setting default DOP values equal to 1000 when the covariance matrix became singular due to poor geometry. This allowed the program to continue operation when such situations were encountered, while the original program would have terminated. Since, in reality, the DOP values approach infinity as an outage occurs, and DOP values much less than this are considered as constituting a system outage (PDOP values less than 6, for example), the exact values are unimportant at these points as long as they are set substantially higher than those values constituting such an outage. The EGAD program currently in use by the Aerospace Corporation employs the same technique.

One additional subroutine (SATDEL) was added to the program to facilitate the analysis of the effect of satellite losses on a given constellation. Subroutine SATDEL allows for the program user to selectively delete from one to ten satellites from the original constellation for use in comparing the effect upon geometric performance caused by a particular combination of satellites. The number of satellites to be deleted and the particular identification numbers of these satellites are entered as part of the data input at the beginning of the program. This subroutine was necessary to identify which combination of satellites provided the best and worst case navigational accuracy.

Explanation of Variables In Main Program

The variables used in the main program and an explanation of their use is provided in Table XVI and Table XVII. Table XVI lists and explains the variables used for that portion of the program involving the space-based or satellite user, while Table XVII explains those variables used for the global distribution calculations involving the user on the ground.

TABLE XVI

Explanation of Variables in Main Program - Satellite User (17:19-20)

<u>FORTRAN</u>	<u>EQUATIONS</u>	EXPLANATION	
RF(IV) RMX(N,IV) R(IV)	R	Vector from the center of the earth to a navsat (where N is the "identification number" of the navsat and "IV" is the index of the components of the vector)	
UPV(IV) RMX(IP,IV)	P	Vector from the center of the earth to a user satellite (where "IP" is the identification number" of the user satellite and "IV" is as above)	
UTS	0	Vector from a user satellite to a navsat	
AR	R	Length of vector R	
AP	Р	Length of vector P	
A		$Cos^{-1}(r/R)$, where $r = radius$ of earth	
В		Cos ⁻¹ (r/P)	
PHI	ф	$\cos^{-1}(r/R) + \cos^{-1}(r/P)$	
THETN	8 _n	Cos ⁻¹ (R • P /RP)	
AU	U	Length of vector $\overline{f U}$	
BETAN	β_{n}	$\cos^{-1}(-\vec{\mathbf{U}} \bullet \vec{\mathbf{P}}/\mathrm{UP})$	
AIWID AIN	α	Navsat antenna beamwidth half-angle (input) relative to a vector from the navsat to the center of the earth	

TABLE XVI (Continued)

<u>FORTRAN</u>	<u>EQUATIONS</u>	<u>EXPLANATION</u>
BWIDTH		$\pi - (\theta_n - \beta_n)$
USUY(IINT(N),IY)	ē _i , i=1,2,3,4	Unit vectors from a user toward 4 navsats (where
U(1Y)	•	IINT(N) contains the "identification number" of the satellites which have not been eliminated and "IV" as before)
THETT	0 _T	If $P>R$ $\theta_T = Cos^{-1}(R/P)$
	•	If $P \le R$ and β (of the navsat closest to zenith)>117/2; $\theta_T = 109.5^\circ - \sin^{-1}(P \sin 19.5^\circ/R)$
		If $P \le R$ and β (of the newsat closest to zenith) $\le \pi \pi/2$; $\theta_T = 70.5^\circ - \sin^{-1}(P \sin 19.5^\circ/R)$
DELONE	δ ₁	If $\sin^2 \theta_T > C$, $\delta_1 = \sin^{-1}(C/\sin \theta_1)$
	·	If $\sin^2 \theta_T \le C$, $\delta_1 = \theta_T$
DELTW0	δ ₂	If $\sin^2 \theta_T > C$, $\delta_2 = \delta_1$
		If $\sin^2 \theta_T \le C$, $\delta_2 = \cos^{-1}(1-2C) - \theta_T$
NUL		Number of navsats
ISCMP		Navsat selection technique parameter (ISCMP=0 for zenith; ISCMP=1 for all satellites taken four at a time)
P(N,K)		Array containing the orbital elements for the satellites (where N is the identification number of the navsat and $k=1$ to 5 is the index on the first five orbital elements)
PER(N)		Orbital period of navsat or user satellite

TABLE XVI (Continued)

FORTRAN	EQUATIONS	EXPLANATION
CK	C	Numerical value representing the fraction of the area of a sphere with radius equal to the orbital radius of navsats; used in calculating width of band where best satellites will be sought (must be set equal to one when navsats are in elliptical orbits)

TABLE XVII Explanation of Variables in Main Program - User on Ground (17:21-22)

FORTRAN	EXPLANATION		
LATREA	1 _424442		

LATDEG Latitude step size (5 or 10 degrees)

ELEVAT Masking angle of users

LATIC, LONIC Latitude and longitude increments to be used

INCLITE Time increment, in minutes, at which calculations are desired

and the total number of increments, plus one, desired

R,RMX Yector from the center of the earth to a satellite

UPV Vector from the center of the earth to a user

STN Yector from a navsat to a user

SE Elevation (masking) angle of a satellite

UTS · Vector from a user to a navsat (-STN)

USUV Unit vector (of UTS)

NSTO Total number of navsats in view

NSPL(L) Total number of navsats in view at each latitude

CL(L) Total number of latitudes when there are four or more navsats in

view

Z Yector in the polar direction (origin at earth center)

YE Vector in the eastward direction (origin at the user)

XN Vector in the northward direction (origin at the user)

TABLE XVII (Continued)

FORTRAN	EXPLANATION
0(NS0D(N),I)	Direction Cosines (where NSOD(N) contains the "identification numbers" of the four selected navsats and $I=1$ to 4)
SIGT(N)	An array containing the DOP parameters
CDOP(L,K,IDOP)	Storage for DOPs at each time step; L= latitude index, K= longitude index, IDOP = DOPs index
PIB(IX)	Elevation distribution: the probability that the satellites in view will have specified elevation angles; IX= elevation angle index
CAGX(LA,LC)	Latitude elevation distribution: the probability that any nevsat in view will have an elevation angle greater than or equal to those specified; LA=latitude index, LC= elevation range index
GLEB(IC)	Accumulative elevation distribution: the probability that the elevation angle to a navsat is greater than or equal to those listed; IC= elevation range index
QSR(IQSR)	Range into which the printed variable falls; $IQSR = 1,36$ in steps of $.2$
SKEGX(LK,IQSR,JDOP)	DOP parameters for overall global performance; LK= latitude index, IQSR (see above), JDOP= DOPs index
MAX(IL,IK)	Maximum number of navsats seen at the intersections of latitudes and longitudes; IL=latitude index, IK= longitude index
MIN(IL,IK)	Minimum number of navsats seen at the intersections of latitudes and longitudes; $IL=latitude$ index, $IK=longitude$ index

TABLE XVII (Continued)

EORTRAN	EXPLANATION
OBLAT(IL,N)	Probability (in percent) of seeing exactly N navsats; IL = latitude index, N=number of navsats
ACLAT(IL,N)	Probability (in percent) of seeing N or more navsats; IL = latitude index, N=number of navsats
OBDIS(N)	On a global basis, the probability (in percent) that exactly N navsats will be seen
ACTOT(N)	On a global basis, the probability (in percent) that N or more navsats will be seen
NDEL	Number of satellites to be deleted from the constellation
JDEL(I)	An array containing the "identification numbers" of deleted satellites

Explanation of Subroutines

Table XVIII lists the individual subroutines utilized in the program and provides a brief explanation of the purpose of each. A more detailed explanation of each subroutine can be found in Reference 17.

TABLE XVIII Computer Program Subroutines (17:23-27)

SUBROUTINE NAME	DESCRIPTION
ORBINI(N)	Initializes the orbital elements for the navsats and user satellite from the input data
ORBIT(I,T,PER,R,VEL,AC)	Iterates for the eccentric anomaly and computes the true anomaly for each time step
TRMATX(TR,I)	Calculates the 3 x 3 coordinate transformation matrix, TR
MATMUL(T,Y,0)	Performs coordinate transformation of a vector by matrix multiplication
POINT(ALO,ALA,TIM,VEC)	Calculates the vector from the center of the earth to the user at a specific latitude and longitude
TAAT(MAX,MXX,MATRIX)	Sets up the sequence of navsats which are to be examined, using either the one above or below the user as one of the four in each calculation of the tetrahedron volume
VOLUME(UVEC,IDSAT,VOL)	Calculates the volume of the tetrahedron formed by the set of four satellites used
COVNAV(G,ID,NAT,SIG)	Computes the six dilution of precision values (DOPs)
BLOCK DATA	Contains various parameter values used in the program
VECTOR(V1,1,V2:,V3)	Performs vector additions, subtractions, and cross products
DOT(V1,V2)	Function which calculates dot product of two vectors
UNIVEC(Y,UY)	Calculates unit vectors
TALL(MAX,MXX,MATRIX)	Sets up the sequence of navsats which are to be examined, using all satellites taken four at a time
SATDEL(P,PER,NJ,ND,JDEL)	Deletes specified satellites from the nominal constellation

<u>Appendix C</u> <u>Computer Program Listing</u>

1.	MAIN PROGRAM	[77-90]
2.	ORBINI (I)	[91]
3.	ORBIT (I,T,PER,R,VEL,AC)	[91-92]
4.	TRMATX (TR,I)	[92-93]
5 .	MATMUL (T,V,0)	[93]
6.	POINT (ALO,ALA,TIM,VEC)	[93]
7 .	TAAT (MAX,MXX,MATRIX)	[93]
8.	VOLUME (UVEC,IDSAT,VOL)	[93-94]
9.	COVNAY (0,ID,NAT,SIO)	[94]
10.	BLOCK DATA	[95]
11.	VECTOR (V1,I,V2,V3)	[95]
12.	DOT (V1,V2)	[95]
13.	UNIVEC (Y,UY)	[95]
14.	TALL (MAX,MXX,MATRIX)	[95-96]
15	SATURE (D DED MILL MORE LIDEL)	[06]

TABLE XIX COMPUTER PROGRAM LISTING

```
PROGRAM NAVSAT
         THIS PROGRAM IS A MODIFICATION OF A COMPUTER PROGRAM BY
      THE RAND CORPORATION ON THE GEOMETRIC PERFORMANCE OF PSEUDO-
      RANGING NAVIGATION SATELLITE SYSTEMS, DEVELOPED FOR THE USAF
                      NAUSTAR (OPS) ANALYSIS PROGRAM
                            (A THESIS PROJECT)
                         CAPT DAVID H. THOMIN
                                   1984
C
                              MAIN PROGRAM
      CONTION/ORBIS/P(37,25)/CON/C(18)
      DIMENSION AA(3),6(37,4),108(37),181C(4),KXX(10626,4),NSGD(37),R(3)
      1, RF(3), RMX(37,3), SIGT(6), U(3), UPV(3), USÚU(37,3), UTS(3), UE(3), Ž(3),
     2 YE(3), XN(3), ISAUE(37), I INT(37), UEL(37), IOUT(37), STN(3)
      DIMENSION QSA(36), CAG(19, 18), GLEB(18), PIB(18), ACLAT(19, 36), 1 ACTOT(36), OBLAT(19, 36), OBDIS(36), CL(19), MIN(19, 36), MAX(19, 36),
     2 CRGX(19, 18), NSPL(19), SKEG(19, 36, 6), SKEGX(19, 36, 6), GLOS(6, 36),
     3 CDOP(19,36,6), ISAPP(32), PER(36)
      REAL LAT, LONG, LATDEG, LADG, LAD
      DIMENSION JOEL(10)
      KTR=48
       IPRINT=0
      Z(1)=0.
      Z(2)=0.
      Z(3)=1.E+10
      NDEL=0
     LOC=1; USER ON SATELLITE
     LOC=2; USER ON GROUND AT SPECIFIED LATITUDE AND LONGITUDE
     LOC=3; GLOBAL CALCULATIONS
      READ (5,*) LOC, NJL, ISCHP, NDEL
       IF(NDEL.EQ.0) GO TO 50
      READ (5,+) (JUEL(N),N=1,NDEL)
      GO TO (100, 110, 120), LOC
      00 105 K=1,5
 100
      RERD (5,+) (P(N,K),N=1,NJL)
     CONTINUÉ
```

```
READ (5,*) (PER(N),N=1,NJL)
     IF(NDEL.NE.O) CALL SATDEL (P, PER, NJL, NDEL, JDEL)
     NUMERUL+1
     READ (5,*) (P(NJM,K),K=1,5)
    READ (5,+) PER(NJH), AIN, CK
     READ (5,*) INC, ITF
     GO TO 155
110 DO 115 K=1.5
     READ (5,+) (P(N,K),N=1,NJL)
115 CONTINUE
     READ (5,+) (PER(N), N=1, NJL)
     IF (NDEL.NE.O) CALL SATDEL (P, PER, NJL, NOEL, JOEL)
     READ (5,*) ATL, ONGL, ELEVAT
     READ (5,*) INC, ITF
     GO TO 155
120 DO 125 K=1,5
     READ (5,+) (P(N,K),N=1,NJL)
125 CONTINUE
     READ (5,*) (PER(N),N=1,NJL)
     IF(NDEL.NE.O) CALL SATDEL (P, PER, NJL, NDEL, JDEL)
     READ (5,*) LATDEG, ELEVAT
     READ (5,*) LATIC, LONIC, INC, ITF, IPFREQ, ITIME
     DO 135 MA=1, 19
     CL(MA)=0.
     MSPL (MA >=0
     DO 130 MB=1,36
     HINKMA, MB >=30
     MAX(MA,MB)=0
     DO 130 MC=1,6
     SKEGX(MR, MB, MC >= 0.
     CDOP(HR, HB, HC >= 0.
130 SKEG(MR, MB, MC >= 0.
     DO 135 HD=1, 18
     CAGX(MA, MD)=0.
135 CAG(MA, MD)=0.
     DO 140 MR=1,36
     DO 140 MB=1,6
140 GLOS(MB, MR >= 0.
     DO 150 MA=1, 19
     ACTOT(HA >=0.
     OBDISCMA >= 0.
     DO 145 MD=1,35
     ACLAT (MA, MD >=0.
145 OBLAT(MA, MD >= 0.
    GLEB(MA)=0.
150
    CONTINUE
155
     PRINT 195
     PRINT 190
     00 160 IP=1,NJL
     PRINT 215, IP, (P(IP, IU), IV=1,5), PER(IP)
160 CONTINUE
     IF(LOC.EQ. 1) PRINT 200
     IP=NJL+1
     IF(LOC.EQ. 1) PRINT 215, IP, (P(IP, IV), IV=1,5), PER(IP)
     IF(LOC.EQ.2) PRINT 210, ATL, ONGL, ELEVAT
```

```
IF(LOC.EQ.3) PRINT 205, ELEVAT, LATDEG, LATIC, LONIC, ITIME
      ITT=(ITF-1)*INC
      PRINT 220, ITT, INC
      IF(LOC.EQ. 1) PRINT 225, AIN,CK
      IF(LOC.EQ. 1.AND. ISCHP.EQ.O) PRINT 166
      IF(LOC.NE. 1.AND. ISCHP.EQ.O) PRINT 165
      IF(ISCHP.EQ. 1) PRINT 170
  THE FOLLOWING FORMATS HAVE TO DO WITH INPUT
165 FORMAT (1HO, 10X, 'THE SATELLITE MOST NEARLY OVERHEAD IS USED AS ONE
     10F THE FOUR' / . 11X. 'IN ALL CALCULATIONS OF THE VOLUME OF THE TETRAH
166 Format (1HD, 10X, "The satellite most nearly above or below is used a
     IS ONE OF THE FOUR'/, IIX, 'IN ALL CALCULATIONS OF THE VOLUME OF THE
    2TETRAHEDRON')
170 FORMAT (1HO, 10X, 'ALL SATELLITES, TAKEN FOUR AT A TIME, ARE USED IN'
     1,/, 11X, 'THE CALCULATIONS OF THE VOLUME OF THE TETRAHEDRON')
175 FORMAT(1015)
180 FORMAT(12F6.0)
185 FORMAT (7F 10.0)
190 FORMAT(1H0,22X, 'ECC',5X, 'ARGP',4X, 'RASC',4X, 'INC',5X, 'ANOM',4X,
     1'PER',//>
195 FORMAT(1H1, //32X, 'ORBITAL ELEMENTS')
200 FORMAT(1H0, 10X, 'USER SATELLITE ORBITAL ELEMENTS'/)
205 FORMAT(1H0, 10X, 'GLOBAL DISTRIBUTION CALCULATIONS', //,
    1 11X, 'MASKING ANGLE = ',F6.2,' DEGREES',/,
2 11X, 'LATITUDE STEP = ',F6.2,' DEGREES',/,
    3 11X, 'LATITUDE INCREMENT = ',13,/,
4 11X, 'LONGITUDE INCREMENT = ',13,/,
5 11X, 'DILUTION OF PRECISION PARAMETERS PRINTED AT TIME INCREMENT O
    OF ',15)
210 FORMAT(1HO, 10X, 'USER LOCATION ON EARTH', /11X,
1 'LATITUDE = ',F5.2,' DEGREES'/,11X,'LONGITUDE = ',F5.2,
2 'DEGREES',/, 11X,'MASKING ANGLE = ',F6.2,' DEGREES')
215 FORMAT(1H, 15X, 13, 1X,F8.3,5F8.2)
220 FORMAT(1HO, 10X, 'TOTAL TIME(MIN) = ', 15, /, 11X,
         'TIME INCREMENT(MIN) = ',13)
225 FORMAT(1H , 10X, 'BEANHIDTH ANGLE(DEG) = ',F6.2,/,11X,
     1 'FRACTION OF NAUSRT SPHERICAL AREA = ',F6.3)
   SET UP ORBITAL ELEMENTS
     DO 230 N=1,NJL
     P(N,22)=22808.+(PER(N)/24.)++(2./3.)
      CALL OABINI (N)
230 CONTINUE
      IF(LOC.EQ.2.0R.LOC.EQ.3) GO TO 235
     P(IP,22)=22808.*(PER(IP)/24.)**(2./3.)
     CALL ORBINI (IP)
235 CONTINUE
      INCA-0
     NSTO=0
     MAXINSS=0
     DO 625 IT=1, ITF
      TID=FLORT(INCR)/1440.
      ITOUT=(IT-1)*INC
      INCA-INCA+INC
```

```
IF(LOC,EQ.2.OR,LOC,EQ.3) NH-NJL
     DO 240 N=1,NN
     CALL ORBIT (N,TID,PER,AF,VE,AA)
     DO 240 IV=1,3
     PHX(N, IV)=PF(IV)
240 CONTINUE
     IF(LOC.EQ.2) GO TO 335
     IF(LOC.EQ.3) GO TO 330
     DO 245 IV=1,3
     UPV(IV)=RMX(IP, IV)
245 CONTINUE
     IK-0
     BETRIN-4.000000
     DO 265 N=1, NJL
     DO 250 1V=1,3
     R(IV)=RMX(N, IV)
     CONTINUE
     CALL VECTOR (R,2,UPV,UTS)
     AR=SORT(DOT(R,R))
     AP=SQRT(DOT(UPV,UPV))
     R=ACOS(2.0926144E+07/AR)
     IF(RP.LE.2.0926144E+07) PRINT 251
251 FORMAT(1H ,/,3X,'TERMINATION OF AUN, ALTITUDE APPROACHING ZERO') IF(AP.LE.2.0926144E+07) STOP
     B=AC08(2.0926144E+07/AP)
     PHI=A+B
     DOTRP=OOT(R,UPV)
     THETN-ACOS(DOTRP/(ARMAP))
     IF(THETN.GE.PHI) GO TO 265
     AU=SORT(DOT(UTS,UTS))
     DOTUP-DOT(UTS,UPV)
     BETAN-ACOS(-DOTUP/(AU+AP))
     RIUID=RIN/C(2)
     BUIDTH=C(3)-(THETN+BETAN)
     IF(AINID.LT.BNIDTH) 60 TO 265
     IK=IK+1
     ISRUE(IK)=N
     BETRSU-BETRN
     IF(BETAN, GT.C(5)) BETAN-C(3)-BETAN
255 IF(BETAN.LT.BETAMN) GO TO 260
     GO TO 265
260 ISRTNO=N
     BETANN-BETAN
     BETRS-BETRSV
265 CONTINUE
     IF(IK.LT.4) GO TO 622
     DO 285 1=1,1K
     IF(ISAUE(I).EQ. ISATNO) GO TO 270
     60 TO 285
270 INDX=1
     00 275 KI=1, INDX
     K11=K1+1
     IINT(KII)=ISRUE(KI)
275 CONTINUE
     INDX=INDX+1
```

```
00 280 KI=INDX. IK
      | INT(KI )=ISAUE(KI )
 290 CONTINUE
      60 TO 290
 285 CONTINUE
 290
     I INT(1)=ISRTNO
      IF(ISCHP.EQ. 1) 60 TO 335
    THE NUMBERS OF THE SATELLITES WHICH FIT CRITERIA FOR USE. PLUS THE
    ONE NERREST TO OVERHERD HAVE BEEN CALCULATED
      108(1)=11NT(1)
      NSS=1
      DO 295 IV=1,3
      RCIU)=RMXCI INTC1), IU)
 295 CONTINUE
      CALL VECTOR (R,2,UPV,UTS)
      CALL UNIVEC (UTS,U)
      DO 300 [V=1,3
      USUV(IINT(I), IV)=U(IV)
 300 CONTINUE
      DO 325 N=2, IK
      DO 305 IV=1,3
      RCIU)=RMX(I INT(N), IU)
 305 CONTINUE
      CALL VECTOR (R,2,UPV,UTS)
      CALL UNIVEC (UTS,U)
      DO 310 IV-1,3
      USUUCI INT(N), IV)=U(IV)
 310 CONTINUE
      AR=SQRT(DOT(R,R))
      AP=SQRT(DOT(UPU, UPU))
      IF(AP.GT.AR) THETT=ACOS(AR/AP)
      IF(AP.LE.AR.AND.BETAS.GT.C(5)) THETT=109.5/C(2)-ASIN(AP+.33380686/
      IF(AP.LE.AR.AND.BETAS.LE.C(5)) THETT=70.5/C(2)-ASIN(AP+.33390666/A
     IR)
      DOTRP-OOT(R, UPV)
      THETN-ACOS(DOTRP/(ARMAP))
      SINTT=SIN(THETT)
      SINTSQ-SINTT++2
      IF(SINTSO.GT.CK) GO TO 315
      DELONE=THETT
      RMG=1.-(CK/.5)
      DELTHO-ACOS(ANG)-THETT
      60 TO 320
 315 CONTINUE
      DELONE-RSIN(CK/SINTT)
      DELTHO-DELONE
 320 IF (THETN.LT. (THETT-DELONE)) 60 TO 325
      IF(THETN.GT.(THETT+DELTHO)) 60 TO 325
      MSS=MSS+1
      IOS(NSS)=IINT(N)
     CONTINUE
      IF(MSS.LE.4) 00 TO 625
      00 TO 335
C
```

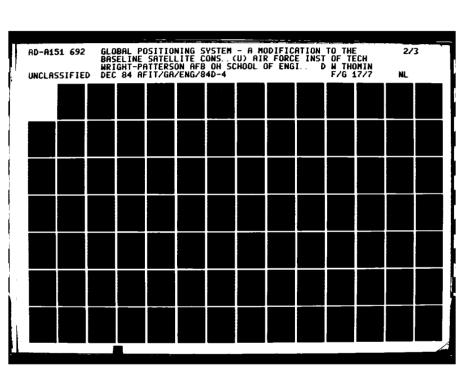
```
END OF USER ON SATELLITE
C
    CALCULATIONS FOR USER ON EARTH AT SPECIFIED LAT AND LONG, AND
    GLOBAL DISTRIBUTIUONS FOLLOW
 330 CONTINUE
      LKL=36
      LLL=19
 335 CONTINUE
      IF(LOC.EQ.2.OR.LOC.EQ.1) LKL=1
      IF(LOC.EQ.2.OR.LOC.EQ.1) LLL=1
      DO 500 K=1,LKL,LONIC
      DO 500 L=1,LLL,LATIC
      IF(LOC.EQ. 1.AND. ISCHP.EQ.0) 00 TO 401
      IF(LOC.EQ. 1, AND. ISCHP.EQ. 1) GO TO 375
      LONG=FLORT(K-1)*10.
      LAT=90.-FLORT(L-1)*LATDEG
      IF(LOC.EQ.2) LONG=ONGL
      IF(LOC.EQ.2) LAT=ATL
      CALL POINT (LONG, LAT, TID, UPV)
      NSS=0
      CL(L)=CL(L)+1.
      DO 350 N=1, NJL
      DO 340 IV-1,3
      R(IU)=RMX(N, IU)
 340 CONTINUE
      CALL VECTOR (UPV,2,R,STN)
      SE=-DOT(STN,UPV)/SQRT(DOT(STN,STN)*DOT(UPV,UPV))
      IF(RBS(SE).GE..9999999) SE=SIGN(1.,SE)
      EL=RSIN(SE)+C(2)
      IF(EL.LT.ELEVRT) GO TO 350
      NSS=NSS+1
      I INT(NSS)=N
      UEL(N)=EL
      CALL VECTOR (R,2,UPV,UTS)
      CALL UNIVEC (UTS,U)
      DO 345 IV=1.3
      USUU(N, IV >= U(IV)
 345 CONTINUE
 350 CONTINUE
 355 CONTINUE
      NSTO=NSTO+NSS
      MSPL(L)=MSPL(L)+MSS
      MSP=MSS+1
      MAXMSS=MAXO(MAXMSS, MSS)
      HIGH=0.
      DO 365 NUM=1,NSS
      IX=IINT(NUM)
      RER=UEL(IX)
      IF(REA.GT.HIGH) GO TO 360
      IF(REA.LE.HIGH) GO TO 365
 360 HIGH-REA
      NH-NUM
 365 CONTINUE
      DO 370 NU=1,NSS
      IF(NU.EQ.NN) NX=1
      IF(NU.LT.NY) NX=NU+1
      IF(NU.GT.NN) NX=NU
      IOS(NX)=IINT(NU)
```

```
370 CONTINUE
     GO TO 400
  IOS(NSS) HAS THE SATELLITE NEAREST TO OVERHEAD, THEN ALL OTHERS
 WHICH FIT CRITERIA
 NEXT CALCULATIONS ARE CONCERNED WITH FINDING THE COMBINATION OF
 FOUR SATELLITES WHICH HAVE THE GREATEST VALUE OF THE VOLUME OF THE
  TETRRHEDRON FORMED BY THEM
375 CONTINUE
     DO 390 IKN=1, IK
     DO 380 IV=1,3
     RCIU>=RMXCI INTCIKNO, IU>
380 CONTINUE
     CALL VECTOR (R,2,UPV,UTS)
     CALL UNIVEC (UTS.U)
     DO 385 IV=1.3
     USUUCI INTCIKN), IV)=UCIV)
385 CONTINUE
390 CONTINUE
     DO 395 IJK=1, IK
395 IOS(IJK)=IINŤ(IJK)
     GO TO 401
400 IF(NSS.LT.4) GO TO 479
     BOX=-10.
401
     IF(ISCHP.EQ. 1) GO TO 405
     KOT=NSS
     NSS=MSS-1
     CALL TRAT (NSS, KCOM, KXX)
     ISIC(1)=10S(1)
     LPN=2
     GO TO 410
405 KOT=1K
     IF(LOC.EQ.2.OR.LOC.EQ.3) KOT=MSS
     CALL TALL (KOT, KCOH, KXX)
     LPN=1
410 00 430 M=1,KCOM
     DO 415 LPQ-LPN.4
     NUX=KXX(H, LPQ)
     ISIC(LPQ >= IOS(NUX)
415 CONTINUE
     CALL VOLUME (USUV, ISIC, VOLUM)
     IF(VOLUM.GT.BOX) GO TO 420
     1F(VOLUM.LE.BOX) GO TO 430
420 BOX=UOLUM
     DO 425 MC=1,4
     NSGD(MC >= ISIC(MC)
425 CONTINUE
430 CONTINUE
     DO 440 N=1,4
     DO 435 IV=1,3
     RCIV)=RMX(NSGO(N), IV)
435 CONTINUE
     CALL VECTOR (R,2,UPV,UTS)
     CALL VECTOR (Z,3,UPV,YE)
     CALL VECTOR (UPV, 3, YE, XH)
     AX=SQRT(DOT(XN, XI))
```

```
AY-SORT(DOT(YE, YE))
      RP=SQRT(DOT(UPV,UPV))
      FILT=RP/6076.116-3444.
      AS=SQRT(DOT(UTS,UTS))
      G(NSGD(N), 1)=DOT(XN,UTS)/(AX*AS)
      G(NSGD(N), 2 >= DOT(YE, UTS)/(RY*AS)
      G(NSGD(N),3)=DOT(UPV,UTS)/(RP*RS)
      G(NSGD(N),4)=1.
 440 CONTINUE
      CRLL COUNRY (G, NSGD, 4, SIGT)
      IF(LOC.EQ.3) GO TO 480
      IF(LOC.EQ.2) ALT=0.
      DO 445 | |=1,4
      (OUT())>HSGD())
 445 CONTINUE
      IL=1
      LK=4
      DO 455 NH-1,KOT
      ITST=MSGD(IL)
      IF(ITST.EQ. IOS(NN)) GO TO 450
      LK=LK+1
      IOUT(LK >= IOS(NN)
      60 TO 455
 450 IL=IL+1
      IF(IL.EQ.5) GO TO 460
 455 CONTINUE
 460 KOS=191+1
      DO 465 LK=KOS, KOT
      IOUT(LK)=IOS(LK)
 465 CONTINUE
      ITOUT=(IT-1)*INC
      KTR=KTR+2
      IF(KOT.GT. 18) KTR=KTR+1
      IF(KTR.GE.40) GO TO 470
      GO TO 475
 470 PRINT 525
      KTR=0
 475 PRINT 530, ITOUT, ALT, (SIGT(KP), KP=1,6), (IOUT(KP), KP=1, KOT)
   END OF CALCULATION FOR SINGLE USER ON EARTH
C
      60 TO 625
   FOLLOWING CALCULATIONS FOR GLOBAL DISTRIBUTION
 479 KOT=MSS
      SIGT(1)=1000.
      SIGT(2)=1000.
      SIGT(3)=1000.
      SIGT(4)=1000.
      SIGT(5)=1000.
      $16T(6)=1000.
 480 DO 485 1DOP=1,6
 485 CDOP(L,K,IDOP)=SIGT(IDOP)
      DO 490 NS=1,6
      KR-HAXO(1,HINO(INT(SIGT(NS>+5.+1.),36>)
 490 SKEG(L,KA,NS >= SKEG(L,KA,NS >+ 1.
      90 495 NA-1, KOT
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1=10S(NA)
       ELT=UEL(1)
       KO=HINO(INT(ELT/5. >+1, 18)
       CRG(L, KO >= CRG(L, KO >+ 1.
       MAX(L,K)=MAXO(MAX(L,K),KOT)
       MIN(L,K)=MINO(MIN(L,K),KOT)
       OBLAT(L, NSP >= OBLAT(L, NSP >+ 1.
 500 CONTINUE
       IF(LOC.EQ.3.AND.IPFREQ.EQ.0) 00 TO 625
                                          NO INTERMEDIATE PRINT
       IF(IPRINT.EQ.O.AND.IT.EQ.1) GO TO 505
C
                                          PRINT FIRST TIME STEP
       IPRINT=IPRINT+1
       IF (IPRINT.EQ. ITIME) GO TO 505
                                        PRINT EACH TIME STEP REQUESTED
       GO TO 525
 505
       IPRINT=0
       DO 515 IDOP=1.6
       IFCIDOP.EQ. 1) PRINT 535, ITOUT
       IF(IDOP.EQ.2) PRINT 540, ITOUT
       IFCIDOP.EQ.3) PRINT 545, ITOUT
       IF(IDOP.EQ.4) PRINT 550, ITOUT
       IF(IDOP.EQ.5) PRINT 555, ITOUT
       IF(IDOP.EQ.6) PRINT 560, ITOUT
       IF(LATDEG.EQ. 10. > PRINT 565
       IF(LATDEG.EQ.5.) PRINT 570
       ICT=-10
       DO 510 IC=1,36
       ICT=ICT+10
       IF(ICT.LE.90.0A.ICT.GE.190) PRINT 575, ICT,(CDOP(IK,IC,IDOP),IK
       IF(ICT.EQ. 100) PRINT 580, (CDOP(IK, IC, IDOP), IK=1, 19)
       IF(ICT.EQ.110) PRINT 585, (CDOP(IK, IC, IDOP), IK=1, 19)
       IF(ICT.EQ. 120) PRINT 590, (CDOP(IK, IC, IDOP), IK=1, 19)
       IF(ICT.EQ. 130) PRINT 595, (CDOP(IK, IC, IDOP), IK=1, 19)
       IF(ICT.EQ. 140) PRINT 600, (CDOP(IK, IC, IDOP), IK=1, 19)
       IF(ICT.EQ. 150) PRINT 605, (CDOP(IK, IC, IDOP), IK=1, 19)
       IF(ICT.EQ. 160) PRINT 610, (CDOP(IK, IC, IDDP), IK=1, 19) IF(ICT.EQ. 170) PRINT 615, (CDOP(IK, IC, IDDP), IK=1, 19) IF(ICT.EQ. 180) PRINT 620, (CDOP(IK, IC, IDDP), IK=1, 19)
 510 CONTINUE
 515 CONTINUE
       DO 520 ICL=1, 19
       DO 520 1CK=1,36
       DO 520 ICD=1.6
      CDOP(ICL, ICK, ICD)=0.
     THE FOLLOWING FORMATS HAVE TO DO WITH A SPECIFIED TIME STEP
C
    REQUEST FOR PRINTING
 525 FORMAT(1H1, /, 1X, 'TIME(MN)', 1X, 'ALT(NH)', 4X, 'UDOP'
      1 5X, 'HOOP',5X, 'HOOP',5X, 'TOOP',5X, 'POOP',5X, 'GOOP',4X,
             'SATELLITES CHOSEN',//>
 530 FORMAT(1H0,17,F9.0,6(F9.3),1X,19(1X,12),/,72X,17(1X,12))
531 FORMAT(1H0,17,F9.0,' ONLY ',14,' SATELLITES ARE VISIBLE.')
535 FORMAT(1H1,//,10X,'TIME = ',16,20X,'UDOP - ALTITUDE')
 540 FORMATCHHI, //, 10X, 'TIME = ', 16, 20X, 'HOOP - POSITION ERROR IN HORIZ
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MICROCOPY RESOLUTION TEST CHART NATIONAL BUREAU OF STANDARDS-1963-A

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10NTRL PLANE')
545 FORMAT(1H1, //, 10X, 'TIME = ', 16, 20X, 'MDOP -- LARGER COMPONENT OF POS
       1:TION ERROR')
550 FORMAT(1H1, //, 10X, 'TIME = ',16,20X, 'TDOP - TIME')
555 FORMAT(1H1, //, 10X, 'TIME = ',16,20X, 'PDOP - THREE DIMENSIONAL POSIT
       110H ERROR')
560 FORMATCHII,//, 10X, 'TIME = ', 16,20X, 'GDOP - FOUR DIMENSIONAL POSITI
       10N ERROR')
565 FORMAT(1H0,52X,'LATITUDE',//,9X,' 90',3X,' 80',3X,' 70',3X,' 60' 1 3X,' 50',3X,' 40',3X,' 30',3X,' 20',3X,' 10',3X,' 0',3X,'-10' 2 3X,'-20',3X,'-30',3X,'-40',3X,'-50',3X,'-60',3X,'-70',3X,'-80'
       2 3X, '-20', 3X, 3 3X, '-90', /)
570 FORMAT (1H0,52X, 'LATITUDE', //,9X,' 90',3X,' 85',3X,' 80',3X,' 75', 1 3X,' 70',3X,' 65',3X,' 60',3X,' 55',3X,' 50',3X,' 45',3X,' 40', 2 3X,' 35',3X,' 30',3X,' 25',3X,' 20',3X,' 15',3X,' 10',3X,' 5',
2 3X, '35',3X, '30',3X, '25
3 3X, '0',/)
575 FORMAT(1H,2X,13,1X,19F6.2)
575 FORMAT(1H ,2X,13,1X,19F6.2)
580 FORMAT(1H ,'L',1X,'100',1X,19F6.2)
585 FORMAT(1H ,'0',1X,'110',1X,19F6.2)
590 FORMAT(1H ,'N',1X,'120',1X,19F6.2)
595 FORMAT(1H ,'0',1X,'130',1X,19F6.2)
600 FORMAT(1H ,'1',1X,'140',1X,19F6.2)
605 FORMAT(1H ,'T',1X,'150',1X,19F6.2)
616 FORMAT(1H ,'U',1X,'160',1X,19F6.2)
617 FORMAT(1H ,'U',1X,'170',1X,19F6.2)
620 FORMAT(1H ,'E',1X,'180',1X,19F6.2)
       ITOUT=(IT-1)*INC
         PLT=RP/6076.116-3444.
         KTR-KTR+2
         IF (KTR.0E.40) GO TO 623
         60 TO 624
623 PRINT 525
         KTR-0
624 PRINT 531, ITOUT, ALT, IK
625 CONTINUE
         IF(LOC.EQ. 1. OR.LOC.EQ. 2) 60 TO 920
         HNSSPO=HRXNSS+1
         DO 630 LI=1,36
630 QSR(L1)=FL0AT(L1-1)*.2
        DO 640 IX=1,18
        PIB(IX)=0.
         DO 635 1Y=1,19
635 PIB(IX)=PIB(IX)+CRG(IY,IX)
        PIB(IX)=(PIB(IX)/FLOAT(NSTO)>+100.
         DO 661 LR=1,19
         IF(CL(LA).EQ.O..OR.NSPL(LA).EQ.O) GO TO 661
         DO 650 N=1.36
         DO 650 I=1,6
         SKEGX(LA,N,I >=0.
         DO 645 J=N,36
645 SKEGX(LA,N,I)=SKEGX(LA,N,I)+SKEG(LA,J,I)
650 SKEGX(LA,N,I)=SKEGX(LA,N,I)/CL(LA)
         DO 660 LC=1, 18
         CRGX(LA,LC)=0.
         DO 655 LF=LC, 18
655 CRGX(LA,LC)=CRGX(LA,LC)+CRG(LA,LF)
         CRGX(LA,LC)=CRGX(LA,LC)/FLOAT(NSPL(LA))
```

```
660 CONTINUE
661 CONTINUE
     PRINT 790
     PRINT 785, (PIB(IX), IX=1, 18)
     IF(LATDEG.EQ.5.) PRINT 795
     IF(LATDEG.EQ. 10. ) PRINT 800
     ICT=-5
     DO 665 LC=1, 18
     ICT=ICT+5
     PRINT 815, ICT, (CAGX(LA,LC), LA=1, 19)
665 CONTINUE
     CUS=0.
     DO 680 LH=1, 19
     IF(CL(LM).EQ.O..OR.NSPL(LM).EQ.O) GO TO 680
     CV=COS((90,-FLORT(LH-1)*LRTDEB)*C(1))
     CUS=CUS+CU
     DO 670 IN-1,6
     DO 670 11=1,36
670 GLOS(IN, II) HOLOS(IN, II) HSKEGX(LN, II, IN) HOU
     DO 675 LN=1, 18
675 GLEB(LH)=GLEB(LH)+CRGX(LH,LH)+CV
500 CONTINUE
     DO 685 LN=1, 18
665 GLEB(LN)=GLEB(LN)/CUS
     PRINT 805
     PRINT 810, (GLEB(IC), IC=1, 18)
     DO 590 IN-1,6
     DO 690 11=1,36
690 GLOS(IN, II) =GLOS(IN, II)/CUS
     DO 695 JDOP-1,6
     IF(JOOP.EQ. 1) PRINT 830
     IF(JOOP.EQ.2) PRINT 835
     IF(JDOP.EQ.3) PRINT 940
     IF(JDOP.EQ.4) PRINT 845
     IF(JOOP.EQ.5) PRINT 850
     IF(JOOP.EQ.6) PRINT 855
     IF(LATDEG.EQ. 10. ) PRINT 820
     IF(LATDEG.EQ.5.) PRINT 825
     DO 595 IOSR=1.36
     PRINT 775, QSR(IQSR), (SKEGX(LK, IQSR, JDOP), LK=1, 19)
695 CONTINUE
     PRINT 860
     DG 700 IQSR=1,35
     PRINT 865, QSR(IQSR), (GLOS(IN, IQSR), IN=1,6)
700 CONTINUE
     PRINT 870
     LADG=90.
     IF(LATDEG.EQ. 10.) LAD=-10.
     IF(LATDEB.EQ.5.) LAD=-5.
     PRINT 880
     DO 705 IL=1,19
     PRINT 885, LADG, (MAX(IL, IK), IK=1,36)
     LADG-LADG+LAD
705 CONTINUE
```

PRINT 875

```
LADG=90.
     DO 715 IL=1, 19
     DO 710 IX=1,36
     IF(HINCIL, IX).EQ.30) HINCIL, IX>=0
710 CONTINUE
     PRINT 985, LADG, (MINCIL, IK), IK=1,36)
     LADG=LADG+LAD
715 CONTINUE
     DO 720 N=1.HNSSP0
     0801S(N)=0.
     DO 720 L=1,19
     IF(CL(L).EQ.O..OR.NSPL(L).EQ.O) 00 TO 720
     OBLAT(L, N)=(OBLAT(L, N)/CL(L))*100.
720 CONTINUE
     00 730 L=1,19
     DO 730 N=1, HNSSPO
     ACLAT(L, N)=0.
     DO 725 H-H, HNSSPO
725 ACLAT(L,N)=ACLAT(L,N)+OBLAT(L,N)
730 CONTINUE
     CO=O.
     00 740 L=1, 19
     IF(CL(L),EQ.O..OR,NSPL(L),EQ.O) 60 TO 740
     CR=COS((QO,-FLORT(L-1)*LRTDEG)*C(1))
     CO=CO+CR
     DO 735 N=1, HNSSPO
735 OBDIS(N)=OBDIS(N)+OBLAT(L,N)*CR
740 CONTINUE
     DO 745 N=1, MNSSPO
745 0801S(N)=0801S(N)/C0
     DO 750 N=1, HMSSPO
     ACTOT(N)=0.
     DO 750 H-H, MISSPO
750 ACTOT(N)=ACTOT(N)+0801S(N)
     DO 755 l=1,32
     ISAPP(1)=1-1
755 CONTINUE
     NP=1
     INS-INSSPO
     IF (MSSPO.GT. 16) MS=16
     PRINT 890, (ISAPP(I), I=1, 16)
760 PRINT 900
     LADG=90.
     DO 765 IL=1, 19
     PRINT 895, LADG, (OBLAT(IL, N), N=NP, NNS)
     LADG-LADG+LAD
765 CONTINUE
     PRINT 905
     LADG-90.
     DO 770 IL=1,19
     PRINT 895, LADG, (ACLAT(IL,N), N-NP, MMS)
     LADG=LADG+LAD
770 CONTINUE
     PRINT 910
     PRINT 790, (0801S(N),N-NP,NNS)
     PRINT 915
     PRINT 790, (ACTOT(N), N=NP, IMS)
```

```
IF(IMSSPO.LT. 16) GO TO 920
      IF(MS.GT. 16) GO TO 920
      HNS-HNSSPO
      NP=17
      PRINT 890, (ISAPP(1), I=17,32)
C THE FOLLOWING FORMATS HAVE TO DO WITH A GLOBAL SYSTEM
775 FORMAT(1H ,F4.1,3X,19F6.3)
 790 FORMAT(1H1, ////1X, 'ELEVATION DISTRIBUTION - PROBABILITY THAT THE
     ISATELLITE IN VIEW WILL HAVE ELEVATION ANGLES AS LISTED'.//.48X.
     2 'ELEVATION ANGLE')
 785 FORMAT( 1H0,6X,' 0-5 5-10 10-15 15-20 20-25 25-30 30-35 35-40 40
     1-45 45-50 50-55 55-60 60-65 65-70 70-75 75-80 80-85 85-90',//,2X,
     2 'PROB', 1X, 18F6.1)
 790 FORMAT (1HD, 3X, 'PROB', 5X, 16F7.2)
 795 FORMAT(1HD,////,1X,'LATÍTUDE ELEVATION DISTRIBUTION',/,
           IX, 'PROBABILITY THAT ANY SATELLITE IN VIEW WILL HAVE AN ELEVAT
     210M ANGLE GREATER THAN OR EQUAL TO THOSE LISTED',//,52X,
     3'LATITUDE',/,2X,'ELEV',/,1X,'ANGLE', 1X,'
4 70 65 60 55 50 45 40
                                                         90
                                                                             20
                               0, '\>
                         5
900 FORMATCIHO, ///, 1X, 'LATITUDE ELEVATION DISTRIBUTION', /,
           IX, 'PROBABILITY THAT ANY SATELLITE IN VIEW WILL HAVE AN ELEVAT
     210N ANGLE GREATER THAN OR EQUAL TO THOSE LISTED',//,52X, 3'LATITUDE',/,2X,'ELEV',/,1X,'ANGLE', 1X,' 90 80 4 50 40 30 20 10 0 -10 -20 -30
                                                                       70
                                                                             60
                     30
         -60
                -70
                      -60 -90',/)
 805 FORMAT(1HD, ////, 1X, 'ACCUMULATIVE ELEVATION DISTRIBUTION', /,
     11X, 'PROBABILITY THAT THE ELEVATION ANGLE IS GREATER THAN OR EQUAL
     2TO THOSE LISTED',//,48X, 'ELEVATION ANGLE')
 810 FORMAT(1H0,7X,"
                               5
                        0
                                      10
                                             15
                                                   20
                                                                 30
                                                                       35
     10
           45
                  50
                               60
                                      65
                                             70
                                                    75
                                                          80
                                                                 85',//,2X,
     2 'PROB', 1X, 19F6. 1>
815 FORMAT(1H , 13,4X, 19F6.2)
3X, ' 50', /)
 830 FORMAT(1H1, ///, 1X, 'DILUTION OF PRECISION - ACCUMULATIVE LATITUDE D
     11STRIBUTION', /, 1X, 'PROBABILITY THAT ALTITUDE DOP WILL BE GREATER T 2HAN NUMBER LISTED', //>
835 FORMAT(1H1, ///, 1X, DILUTION OF PRECISION - ACCUMULATIVE LATITUDE D
     IISTRIBUTION', /, IX, 'PROBABILITY THAT POSITION DOP IN HORIZONTAL PLA
     2NE HILL BE GREATER THAN NUMBER LISTED',//>
940 FORMAT(1H1, ///, 1X, 'DILUTION OF PRECISION - ACCUMULATIVE LATITUDE D 11STRIBUTION', /, 1X, 'PROBABILITY THAT LARGER COMPONENT OF POSITION D
20P HILL BE GREATER THAN NUMBER LISTED', //>
845 FORMAT(1H1, //, 1X, 'DILUTION OF PRECISION - ACCUMULATIVE LATITUDE D
11STRIBUTION', /, 1X, 'PROBABILITY THAT TIME DOP HILL BE GREATER THAN
     2NUMBER LISTED',//>
```

- 850 FORMAT(1H1, ///, 1X, 'DILUTION OF PRECISION ACCUMULATIVE LATITUDE D
 11STRIBUTION', /, 1X, 'PROBABILITY THAT THREE DIMENSIONAL POSITION DOP
 2 WILL BE GREATER THAN NUMBER LISTED', //>
- 855 FORMAT(1H1, ///, 1X, 'DILUTION OF PRECISION ACCUMULATIVE LATITUDE D 11STRIBUTION', /, 1X, 'PROBABILITY THAT FOUR DIMENSIONAL POSITION DOP 2HILL BE GREATER THAN NUMBER LISTED', //>
- 960 FORMAT(1H1, ///, 1X, 'DILUTION OF PRECISION PARAMETERS ACCUMULATIVE 1 GLOBAL DISTRIBUTION', //, 8X, 'NUMBER', 7X, 'VOOP', 6X, 'HOOP', 6X, 'TOOP', 6X, 'POOP', 6X, 'GOOP', />
- 965 FORMAT(1H ,9X,F3.1,3X,6F10.4)
- 870 FORMAT(1H1, 1X, 'MAXIMUM AND MINIMUM NUMBERS SEEN AT EACH LATITUDE 18 LONGITUDE')
- 875 FORMAT(1H0,/,38X,'MINIMUM',//,37X,'LONGITUDE',//,
 1 32X,2('1',9X),2('2',9X),2('3',9X),/,22X,3('5',9X,'0',9X),
 2 '5',/,5X,'LAT',4X,8('0',9X),/>
- 880 FORMAT(1H0,/,38X,'MAXIMUM',//,37X,'LONGITUDE',//,
 1 32X,2('1',9X),2('2',9X),2('3',9X),/,22X,3('5',9X,'0',9X),
 2 '5',/,5X,'LAT',4X,8('0',9X),/)
- 985 FORMAT(1H ,3X,F4.0,3X,3612)
- 990 FORMAT (1H1,40X, 'NUMBER OF SATELLITES',//,5X, 'LAT',3X, 1617)
- 895 FORMAT(1H ,3X,F4.0,5X,16F7.2)
- 900 FORMAT(1HO, /, 10X, 'PROBABILITY (IN PERCENT) OF SEEING EXACTLY IN SAT IELLITES', /)
- 905 FORMAT(1HO, /, 10X, 'PROBABILITY (IN PERCENT) OF SEEING N OR MORE SAT 1ELLITES', /)
- 910 FORMAT(1HO, /, 1X, 'ON A GLOBAL BASIS THE PROBABILITY (IN PERCENT) TH 1AT EXACTLY N SATELLITES WILL BE SEEN')
- 915 FORMAT(1HD, /, 1X, 'ON A GLOBAL BASIS THE PROBABILITY (IN PERCENT) TH 1AT N OR MORE SATELLITES WILL BE SEEN')

920 CONTINUE END

```
SUBROUTINE ORBINI(1)
COMMON/ORB 15/P(37,25)/COM/C(18)
P(1,2)=P(1,2)*C(1)
P(1,3)=P(1,3)+C(1)
P(1,4)=P(1,4)*C(1)
P(1,5)=P(1,5)*C(1)
P(1,9)=81N(P(1,4))
P(1, 10 >= COS(P(1,4>)
P(1,11)=SIN(P(1,3))
P(1,12)=C08(P(1,3))
P(1,21) = P(1,22) C(6)
SRR=22908. *C(6)
P(1,23)=(SRA/P(1,21))##1.5
P(1,6)=P(1,21)*(1.-P(1,1)*P(1,1))
P(1,7)=80AT( C(12)/P(1,6))
P(1,8)=C(12)/(P(1,6)*P(1,6))
RETURN
END
SUBROUTINE ORBIT(1,T,PER,R,VEL,AC)
COMMON/ORBIS/OP(37,25)/CON/C(18)
DIMENSION R(3), UEL(3), RC(3), TRANS(3,3), Q(3), QEL(3), QC(3), U(36),
   E(36),BIGT(36),LILT(36),U(36),CU(36),SU(36),PER(36)
REAL LILT
1F(T.GT.0) 00 TO 10
V(1)=0P(1,5)
SINE=(SQRT(1.-OP(1,1)**2)*SIN(OP(1,5)))/(1.+OP(1,1)*COS(OP(1,5)))
RRD=(OP(1,22)*(1.-OP(1,1)**2))/(1.+OP(1,1)*COS(OP(1,5)))
E(I)=ASIN(SINE)
IF(OP(1,1).NE.O.) 60 TO 15
IF(U(1).LT.(C(3)/2.)) E(1)=E(1)
IF((U(1).GE.(C(3)/2.)).AND.
   (V(1).LE.(3.*C(3)/2.))) E(1)=C(3)-E(1)
IF(U(1).GT.(3.*C(3)/2.)) E(1)=C(4)+E(1)
60 TO 20
CONTINUE
IF(RAD.LT.OP(1,22).AND.U(1).LE.C(3)) E(1)=E(1)
IF(RAD.GT.OP(1,22)) E(1)=C(3)=E(1)
IF(RAD.LT.OP(1,22).AND.U(1).GT.C(3)) E(1)=C(4)+E(1)
CONTINUE
BIGT(1)=(PER(1)+(E(1)-OP(1,1)+SINE))/(24.+C(4))
LILT(I >=BIGT(I)
60 TO 25
DEL=. 1
LILT(I >=BIGT(I >+T
E(1)=0.
E(1)=E(1)+DEL
Y=L!LT(| >= <PER(| >= <E(| >= OP(|, | >= SIN(E(| >>>)/(24. *C(4>)
IF(ABS(Y).LE..00001) 80 TO 30
IF(Y.GT.0) 00 TO 35
E(I)=E(I)-DEL
DEL=DEL/10.
00 TO 35
CONTINUE
```

```
IF(E(1).GE.C(4)) E(1)=E(1)-C(4)
     SINU=(SQRT(1.-OP(1,1)**2)*SIN(E(1)))/(1.-OP(1,1)*COS(E(1)))
     U(I)=ASIN(SINU)
     RP=0P(1,22)*(1.-0P(1,1)*C0S(E(1)))
     P=0P(1,22)*(1.-0P(1,1)**2)
     IF(OP(1,1).NE.O.) GO TO 40
     IF(E(1),LT.(C(3)/2,)) U(1)=U(1)
     IF((E(1).GE.(C(3)/2.)).RMD.
        (E(1).LE.(3.*C(3)/2.))) U(1)=C(3)-U(1)
     1F(E(1).6T.(3.*C(3)/2.)) U(1)=C(4)+U(1)
     GO TO 25
     CONTINUE
40
     IF(RP.LT.P.AND.E(1).LE.C(4)) U(1)=U(1)
     IF(RP.GT.P) V(1)=C(3)-V(1)
     IF(RP.LT.P.RMD.E(1).GT.C(4)) U(1)=C(4)+U(1)
     CONTINUE
     CU(1)=COS(U(1))
     SU(1)=SIN(U(1))
     U(1)=U(1)+0P(1.2)
     OP(1, 13)=C06(U(1))
     0P(1,14)=SIN(U(1))
     SPH=OP(1, 14)*OP(1,9)
     CPH=SQRT(1.+SPH*SPH)
     OP(1, 15)=RSIN(SPH)*C(2)
     OP(1, 18)=U(1)
     F1=1.+0P(1,1)+CV(1)
     Q(1)=0P(1,6)/F1
    Q(2)=0.
Q(3)=0.
    QEL(1)=0P(1,1)*0P(1,7)*SU(1)
    QEL(2)=QP(1,7)4F1
    ŒL(3)=0.
    QC(1)=-QP(1,8)4F14F1
    QC(2)=0.
    QC(3)=0.
    CALL TRHATX (TRANS, I)
    CALL MATHUL (TRANS, Q, R)
    CALL MATHUL (TRANS, QEL, VEL.)
    CALL MATHUL (TRANS.QC.AC)
    OP(1,24)=(T- AINT(T+.5))*C(4)
    OP(1, 16)=ATAM2(R(2),R(1))=OP(1,24)
    OP(1, 16)=OP(1, 16)+C(2)
    RETURN
    SUBROUTINE THYRTX(TR, !)
    DIMENSION TR(3.3)
    COMMON/ORBIS/OP(37,25)/CON/C(18)
    TR(1, 1)=0P(1, 12)+0P(1, 13)=0P(1, 11)+0P(1, 10)+0P(1, 14)
    TR(1,2)=0P(1,12)+0P(1,14)+0P(1,11)+0P(1,10)+0P(1,13)
    TR(1,3)=0P(1,11)*0P(1,9)
    TR(2, 1) = OP(1, 11) + OP(1, 13) + OP(1, 12) + OP(1, 10) + OP(1, 14)
    TR(2,2)=-0P(1,11)+0P(1,14)+0P(1,12)+0P(1,10)+0P(1,13)
    TR(2,3)=-0P(1,12)*0P(1,9)
    TR(3,1)=0P(1,9)*0P(1,14)
    TR(3,2) = OP(1,9) + OP(1,13)
    TR(3,3)=0P(1,10)
```

```
TR(1,2)=-1.*TR(1,2)
     RETURN
     END
     SUBROUTINE MATHUL(T,V,0)
     DIMENSION T(3,3),U(3),O(3)
     00 10 1=1,3
     0(1)=0.
     DO 10 J=1,3
     OC1 >= OC1 >+TC1, J>+VCJ>
     RETURN
     END
     SUBROUTINE POINT(RLD, RLR, TIN, VEC)
     COPPION/CON/C(18)
     DIMENSION VEC(3)
     EH-RLO*C(1)+C(4)*TIN
     SN-ALA+C(1)
     VEC(1)=C(10)*C08(SN)*C08(EH)
     VEC(2)=C(10)+COS(SH)+SIN(EH)
     VEC(3)=C(10)+SIN(SN)
     RETURN
     END
     SUBROUTINE TRAT (MAX, MXX, MATRIX)
     DIMENSION MATRIX(10626,4)
     00 10 1=1, 10626
     DO 10 | |=1,4
     MATRIX(1, 11 >= 0
     IF(MAX.LT.3) GO TO 30
     MXX=(MRX-2)*(MRX-1)*MRX/6
     1881-19FX-1
     HERN-HEX
     1810=11RX+1
     NA-0
     DO 25 K=2,HMH
     KD=K+1
     DO 20 L-KO, HIN
     KT=L+1
     DO 15 H-KT, HHO
     NA-NA+1
     MATRIX(NA,2)=K
     MATRIX(NA,3)=L
     MATRIX(NA, 4)=H
     CONTINUE
15
20
     CONTINUE
25
     CONTINUE
30
     RETURN
     END
     SUBROUTINE VOLUME (UVEC, IDSAT, VOL.)
     DIMENSION UVEC(37,3), IDSAT(4), ONE(3), THO(3), THREE(3), FOUR(3)
     DIMENSION THF(3), THT(3), ONT(3), CROSS(3)
     KR=IDSAT(1)
```

```
KB=IDSAT(2)
     KC=IDSAT(3)
     KD=1DSAT(4)
     DO 10 N=1.3
     ONE(N)=UVÉC(KR,N)
     THO(N)=UNEC(KB.N)
     THREE(N)=UVEC(KC.N)
     FOUR(N)=UVEC(KD,N)
     CALL VECTOR (THO, 2, FOUR, THF)
     CALL VECTOR (THREE, 2, THO, THT)
     CALL VECTOR (ONE,2,THO,OHT)
     CALL VECTOR (THT, 3, THF, CROSS)
     VOL=RBS(DOT(OHT, CROSS))
     RETURN
     END
     SUBROUTINE COUNAU (6, 10, NAT, S16)
     DIMENSION ID(37),B(4),SIG(6),G(37,4)
     DIMENSION RINU(4,4), HKARER(40), TRA(4,4)
     DO 20 I=1,4
     DO 15 J=1,1
     TRACI, J>=0.
     DO 10 K=1,NAT
     L=ID(K)
     TRACI, J)=TRACI, J)+G(L, I)+G(L, J)
     CONTINUE
     TRACU, I >=TRACI, J>
15
     CONTINUE
     TRR(1,1)=TRR(1,1)+1.E-12
20
     CONTINUE
     CALL LINU2F (TRA,4,4,AINU,1,HKAREA,IER)
     IF(IER.EQ. 129) 80 TO 35
     DO 30 I=1,4
     DO 25 J=1.4
     TRACI, J>AINUCI, J>
     AINU(1.J)=0
     CONTINUE
     CONTINUE
     $18(1)=$QRT(TRA(3,3))
     $18(2)=$QRT(TRA(1,1)+TRA(2,2))
     $18(3)=AMAX1(SQRT(TRA(1,1)),SQRT(TRA(2,2)))
     SIG(4)=SQRT(TRA(4,4))
     $16(5)=$QRT(TRA(1,1)+TRA(2,2)+TRA(3,3))
     $16(6)=$QRT(TRA(1,1)+TRA(2,2)+TRA(3,3)+TRA(4,4))
     RETURN
     $16(1)=1000.
     $16(2)=1000.
     $16(3)=1000.
     $1644 >= 1000.
     SIG(5)=1000.
     $16(6)=1000.
     RETURN
     60
```

```
BLOCK DATA
     COMMON/CON/C(18)
     DRTR C/.01745329252,57.295779513,3.1415926536,6.28318530718,
    11.57079630,6076.116,0.,0.,0.,2.0926143504E+07,
    27.29211585E-05, 1.4076380E+16,365.2563835 ,92.91
    3E+06,0.0167272,23.44436,-77.7303,5290./
     SUBROUTINE VECTOR(V1,1,V2,V3)
     DIMENSION U1(3), U2(3), U3(3)
     GO TO (10, 15, 20), !
     U3(1)=U1(1)+U2(1)
     U3(2)=U1(2)+U2(2)
     U3(3)=U1(3)+U2(3)
     RETURN
    U3(1)=U1(1)=U2(1)
     U3(2)=U1(2)-U2(2)
     U3(3)=U1(3)-U2(3)
     RETURN
     U3(1)=U1(2)+U2(3)-U1(3)+U2(2)
20
     U3(2)=U1(3)+U2(1)-U1(1)+U2(3)
     V3(3)=V1(1)+V2(2)-V1(2)+V2(1)
     RETURN
     END
     FUNCTION DOT(V1,V2)
     DIMENSION V1(3), V2(3)
     DOT=U1(1)+U2(1)+U1(2)+U2(2)+U1(3)+U2(3)
     RETURN
     SUBROUTINE UNIVEC (V.UV)
     DIMENSION V(3),UV(3)
     DENOM = SQRT(DOT(V,V))
     UV(1) = V(1)/DENOH
     UU(2) = U(2)/DENOH
     UU(3) = V(3)/DENOH
     RETURN
     EMD
     SUBROUTINE TALL (MAX, MXX, MATRIX)
     DIMENSION MATRIX(10626,4)
     DO 10 I=1, 10626
     00 10 11=1,4
     MATRIX(I, II >=0
     IF(MAX.LT.3) 00 TO 35
     MXX=(MRX-3)+(MRX-2)+(MRX-1)+MRX/24
     KK=MRX-3
     LL=MAX-2
     HEHMAX-1
     NH-HAX
```

```
NA=0
     DO 30 K=1,KK
     K0=K+1
     00 25 L=K0,LL
     KT=L+1
     DO 20 H=KT, HH
     KP=#+1
     DO 15 N-KP, NN
     NA=NA+1
     MATRIX(NA, 1)=K
     MATRIX(NA,2)=L
     MATRIX(NA,3)=1
     MATRIX(NA, 4)=N
15
     CONTINUE
20
     CONTINUE
     CONTINUE
30
     CONTINUE
    RETURN
     END
          This subroutine allows the user to selectively
      DELETE UP TO TEN SATELLITES FROM THE NOMINAL CONSTEL-
      LATION. 'NOEL' IS THE NUMBER OF SATELLITES TO BE DELETED
      AND IS ENTERED AS THE LAST ITEM ON THE FIRST LINE OF
      DATA INPUT. WHEN SATELLITES ARE TO BE DELETED, THE NEXT
      LINE OF DATA SHOULD CONTAIN THE IDENTIFICATION NUMBERS
      OF THE SATELLITES TO BE DELETED FROM THE CONSTELLATION
      ENTERED IN DESCENDING ORDER (HIGHEST ID NUMBER TO LOWEST).
       JOEL(1)' CONTRINS THE ID NUMBERS OF THESE SATELLITES.
     SUBROUTINE SATDEL(P, PER, NUL, NDEL, JDEL)
     DIMENSION P(37,25), PER(36), JOEL(10)
     DO 40 J=1, NOEL
     NJL=NJL-1
     DO 20 N=JDEL(J), NJL
     M=N+1
     DO 10 K=1,5
     P(N,K)=P(N,K)
     PER(N)=PER(M)
10
     CONTINUE
20
     CONTINUE
     DO 25 L=1,5
25
    P(H,L)=0
     PER(H)=0
40
    CONTINUE
     RETURN
```

Appendix D Samples of Computer Output

This section of the appendix contains a sample of the computer program output for each of the two types of runs utilized in this analysis. Table XX provides the complete output obtained for a representative global distribution run in which a network of earth-based users are uniformly distributed over the surface of the earth. Table XXI contains the complete output listing representing the case in which the user is situated on a satellite (space-based user). No sample output is provided for the case of a single user at a specific location on the earth (Case 2), as this portion of the program was not used in this analysis.

TABLE XX Sample Output - Global Distribution Run

C ANOM PER	00 0.00 12.00	125.00	8	42.00		272.30	8	195.80	313.30	122.30	232.60	357.00	161.00	273,30	42.80	199 00	86.70	00 317.20 12.00			D AT TIME INCREMENT OF 0	
RASC INC	30.00 55.	30 00		90.00 55.	90.00 55.	90.00 55.	150.00 55.	150.00 55.	150.00 55	210.00 55.	210.00 55.	210.00 55.	270.00 55.	270.00 55	270.00 55.	330 00	330.00	330.00 55.	LATIONS	DEGREES DEGREES 2	2 PARAMETERS PRINTED AT	
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TABLE XX (Continued)

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TABLE XX (Continued)

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TABLE XX (Continued)

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TABLE XX (Continued)

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TABLE XX (Continued)

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TABLE XX (Continued)

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TABLE XXI Sample Output - Satellite User

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		-	~	C	4	ស	Ø	7	60	6	0	11	12	5	4-	2	91	17	9	USER SATELLI	61	TOTAL TIME(MIN) = 59 TIME INCREMENT(MIN) = 1 BEAMMIOTH ANGLE(DEG) = 21.40 FRACTION OF NAVSAT SPHERICAL AREA	ALL SATCLLITES, TAKEN FOUR AT A TIME THE CALCULATIONS OF THE VOLUME OF TH

TABLE XXI (Continued)

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TABLE XXI (Continued)

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Appendix E Selected Data Extracts

This section of the appendix contains some selected output from the numerous computer runs made and used in the analysis of the baseline constellation and its modification. The complete program output listing is provided for the global distribution run made for each of these satellite constellations. Portions of the output from several other runs, which were used in analyzing the effect of satellite losses on each constellation, have also been provided. Finally, extracts of output from several of the computer runs used in the analysis of the geometric performance for the space-based user are included as indicative of the performance obtainable for varying antenna half-angle beamwidths.

TABLE XXII Global Distribution - Baseline Constellation

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TABLE XXII (Continued)

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TABLE XXIII (Continued)

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TABLE XXIII (Continued)

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© .	0000	- 0000	0000	- 0000 -	- 0000	0000
€0.	.0000	- 0000	.0000	. 9673	0000	1.0000
0.	1.0000	- 0000	. 8260	7297	.0000	0000
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7.0	. 5681	.0493	.0185	1009	9849	1666
2	3797	0241	0122	0720	9863	9761
			1100			
7	BC / 7	7610.	3	2.65	/700	0/0
B .	. 2096	9800	.005	0328	4322	. 6672
2.8	1539	0056	0029	0227	2937	4811
•	4000	200	2	0143	2267	2420
•	1000		200			
y .) DEO.	3	3	700	1601	1007
₩.	.0793	. 0013	.0012	.0054	1265	. 2218
ත	.0802	6	6	0034	. 1012	1758
3,38	0453	00100	6000	.0023	.0835	1383
•	0334	6000	9000	8100	0650	1111
	9000	2000	900	5 5	01.0	9290
		200	200	9 6	9000	
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6	0049	.000	.000	.00	0105	.0336
5 .	.0036	000	4 000	.0012	.0073	.0249
9.0	.0026	4 000.	4 000	2100	.0053	.0180
80	0024	4000	4000	9	6000	0145
_	0055	4000	000	1100	0029	0114
	21.00	4000		000	000	200
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9 9	200	.000	.0003	00.00	. 00 81 00	900.
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ر 0.	2100	.000	.0003	6000	.001	. 0028

TABLE XXIII (Continued)

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TABLE XXIII (Continued)

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	n	Z	8	38	8	25	3 6	8	25	8	= :	88	3 6	3 %	38	20	38	-	MORE SA	8	88	8 8	38	8	7	8	8 8	3 2	88	2 8	2	8	8 8		AT EXAC	18,68		AT N OR	98.92	
•	•	IG EXACTLY	8	38	8.0	88	3 c	8	89	8	4. 88	8	= 8	3 5	2 0	8	88		SEEING N OR	8	88	88	38	8	8	8	88	8	8	38	8	8	88	88	ENT) TH	1.08		ENT) TH		
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TABLE XXIV Global Distribution - Baseline 17

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	PER	12.00	12.00	12.00	2.00	12.00	12.00	12.00	12.00	12.00	12.00	12.00	12.00	12.00	12 00		12.00		CREMENT OF
	ANOM	120,00	240.00	40.00	160.00	80.00	200.00	320 00	120 00	240.00	360.00	180 00	280.00	40 00	200.00	320 00	80.00		TIME INCREMENT
ITS	INC	55 00	55.00	55.00	25.00 6.00	55.00	55.00	55 00	55.00	55.00	55.00	55.00	55.00	55.00	55.00	55.00	55.00		INTED AT
L ELEMENTS	RASC	30.00	30.00	90.06	2 2	150.00	150.00	150.00		2 10 00	210.00	270.00	270.00	270.00	330.00	330.00	330.00	TIONS	EES EES ETERS PR
ORBITAL	ARGP	00	8	8	<u>8</u> 8	8	00	8	8	8	0 0.			0	00	8	8	CALCULA	5 00 DEGREES 0.00 DEGREES 1.1 2 1.1 2 1.10N PARAMETE 360
	ECC	000	000	000	8	000	000	000	000	000	000	000	000	000	000	000	000	RIBUTION	NGLE = 5 STEP = 10 INCREMENT : INCREMENT OF PRECISION
		-	8	·	4 π	, w	7	a	Ø	2	=	12	<u>.</u>	<u>-</u>	5	5	17	GLOBAL DISTRIBUTION CALCULATIONS	MASKING ANGLE = 5 00 DEGREES LATITUDE STEP = 10.00 DEGREES LATITUDE INCREMENT = 2 LONGITUDE INCREMENT = 2 DILUTION OF PRECISION PARAMETERS PRINTED AT

TABLE XXIV (Continued)

DISTRIBUTION	PD0P GD0P	0000 1 0000	0000 1 0000		0000 1 0000	-	_	-	_	_	_	•	٠	•	•	•	•	. 2465 . 3350	•	•	•	•	•	•	. 0684	•	•	•	•	.0262 .0570	•	•	٠	•		_	.0201 .0223
GLOBAL DISTR	T00P	1.0000	1.0000	1.0000	1.0000	. 9604	. 7933	. 4463	3468	2837	. 2315	1794	. 1310	.0952	.0754	.0605	.0391	.0277	.0228	.0185	.0169	0151	0146	.0138	.0138	.0133	.0127	0125	.0124	0116	0112	0112	.0102	8600	.0094	9800	0081
ACCUMULATIVE	MDOP	1.0000	1.0000	1.0000	1.0000	1.0000	8868	. 4412	2119	.0929	.0632	. 0469	. 0320	. 0255	.0226	.0204	.0134	0119	.0113	.0108	0106	.0101	0101	0600	.0082	0080	.0076	.0073	6900	0064	. 0059	0057	.0057	.0057	0056	0051	.0051
1	HDOP	1.0000	1.0000	1.0000	1.0000	1.0000	1.0000	. 9824	. 6602	. 3729	. 1439	. 0877	. 0568	.0383	0289	.0258	.0222	.0153	.0138	.0121	.0110	.0106	0.00	.0103	66 00 .	.0092	9800	.0082	9200	6900	9900	9900	.0062	6500	.0057	0057	0057
ION OF PRECISION PARAMETERS	VDOP	1.0000	1.0000	1 0000	1 0000	1.0000	1.0000	1.0000	8666	9590	8 156	. 5841	. 4281	3545	. 2869	2282	1954	1558	1303	9260	0872	0769	.0646	0530	.0400	.0278	.0254	.0243	0232	0217	.0209	.0205	0200	0191	0110	0189	0185
	NUMBER	0	7	₹.	9	so .	1.0	1.2	4 -	9.			•	,				3.2																			

TABLE XXIV (Continued)

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TABLE XXIV (Continued)

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TABLE XXY Baseline 16 - Best Case

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	PER	12.00	12.00		2.00	12.00			22	22.00		12.00		ICREMENT (IF THE FOUR	
	ANOM	120 00 240 00	40 00 280 00		320 00	120.00	360 00	160.00	280.00	200 00		80 00		NG ANGLE = 5 00 DEGREES UDE STEP = 10 00 DEGREES UDE INCREMENT = 2 TUDE INCREMENT = 2 ION OF PRECISION PARAMETERS PRINTED AT TIME INCREMENT		.EARLY OVERHEAD IS USED AS ONE OF OF THE VOLUME OF THE TETRAHEDRON	
NTS	INC	55.00 55.00	55 00 55 00	55 00	55.00 55.00	15 15 10 10 10 10 10 10 10 10 10 10 10 10 10	55 00	55.00	15 CO	55.00	55.00	22 00		RINTED AT		IS USED DF THE TI	
AL ELEMENTS	RASC	30 00	00 06	150 00	150.00	210.00	210.00	270.00.	270.00	330 00		330 00	ALIONS	DEGREES OEGREES 2 2 PARAMETERS PI		JVERHEAD VGLUME (
ORBITAL	ARGP	00	00	8	38	8 8	88	8 6	8	8	88	00	V CALCUL	5 00 DEGI 5 00 DEGI 7 2 1 1 2 10N PARAI	360	.EARLY (OF THE	
	ECC	000	000	000	800	000	000	000	88	000	000	000	DISTRIBUTION CALCULATIONS	NG ANGLE = 5 UDE STEP = 10 UDE INCREMENT = 1UDE INCREMENT = 100 OF PRECISIO	TIME(MIN) = INCREMENT(MIN)	ITE MOT. SULATES	
		- ~	n 4	មាល	0 /	ത ഗ	. ō	= 9	25	2 4	15	16	GLOBAL DIS	MASKING ANGLE LATITUDE STEP LATITUDE INCREI LONGITUDE INCRE	TOTAL TIME	THE SATELLITE MO. IN ALL CALGULATION	

TABLE XXV (Continued)

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DILUTION OF PRECISION PARAMETERS - ACCUMULATIVE GLOBAL DISTRIBUTION

TABLE XXY (Continued)

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Continued)

PRIMAMENTITY -IN PERCENTIL OF STETING CACTLY N SATILLITIES 10.		
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TABLE XXYI Baseline 16 - Worst Case

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	PER	12.00	12 00	12.00	12.00	27.00	25.5	12.00	12.00	12.00	12.00	12.00	12.00	12.00	12.00					CREMENT OF		F THE FOUR
	ANOM	120.00	240 00	40.00	160.00	280 00		320.00	240.00	360 00	160.00	280.00	40.00	200.00	80 00 80 00					UTION OF PRECISION PARAMETERS PRINTED AT TIME INCREMENT		SATELLITE MOST NEARLY OVERHEAD IS USED AS ONE OF LL CALCULATIONS OF THE VOLUME OF THE TETRAHEDRON
ITS	INC	55.00			55.00	55.00	2 2 3 3 8	55 00	8	8	55.00	55.00	55 00	55.00	55.00 55.00					INTED AT		IS USCO F THE TE
L ELEMENTS	RASC	30.00	30 00	00 06	90.06	00 00	50.00	150.00	210 00	210.00	270.0b	270.00	270.00	330.00	330 00	TIONS	EES	EES		ETERS PR		VERHEAD VOLUME O
ORBITAL	ARGP	8					3 8					8		8	38	CALCULA	. OO DEGR	10.00 DEGREES	, Z , "	ON PARAM	360 = 10	NEARLY O Of the
	ECC	000	000	000	000	000	3 8	000	000	000	000	000	000	00	38	RIBUTION	רב י 5	STEP = 10	CREMENT	PRECISI	MIN) = ENT(MIN)	TE MOST ULATIONS
		-	~	က	₹ 1	រព (۰ م	- 00	on.	9	=	13	5	7	<u>. </u>	GLOBAL DISTRIBUTION CALCULATIONS	MASKING ANGLE	I CUDE	LONGITUDE INCREMENT	DILUTION OF	TOTAL TIME(MIN) = TIME INCREMENT(MIN)	THE SATELLITE MOST NEARLY OVERHEAD IS IN ALL CALCULATIONS OF THE VOLUME OF

TABLE XXVI (Continued)

MDOP TDOP PDOP GDOP	1.0000 1.0000 1.0000 1.	1 0000 1 0000 1 0000 1	1.0000 1.0000 1.0000 1.	1 0000 1 0000 1.0000 1.	1.0000 .9673 1.0000 1.	.9028 .8211 1.0000 1.	.5150 .5147 1.0000 1.	3006 4143 1.0000 1.	1751 3503 1.0000 1.	.1360 2978 1.0000 1.	. 1129 . 2488 . 9907	. 0918 . 1958 . 9297	. 0811 . 1596 7781	0757 . 1371 . 5450	. 0695 1196 . 4429	. 0626 . 0983 . 3794	. 0581 . 0867 . 3244	. 0546 . 0785 . 2811	. 0534 . 0698 . 2478	.0518 .0647 .2056 .2919	. 0510 0610 1819	. 0508 0593 1619	0487 0588 1460	. 0470 . 0588 . 1370	0470 0574 1222	.0458	0455 0551 1057	0445 0542 0945	0422 0527	. 0415 0508 . 0830	.0406 .0503 .0800	.0391 .0483 .0786	.0391 0478 .0768	•	0377 0463 0725	0370 0444 0725
HDOP	1.0000	1.0000	1 0000	1 0000	1.0000	1.0000	. 9857	. 7099	4468	. 2363	1701	1297	1044	0885	0812	.0741	9990	.0821	.0589	.0533	.0526	.0517	.0513	.0505	0493	0485	0477	.0466	0442	0435	.0431	.0414	0400	0393	.0393	.0386
VDOP	1.0000	1.0000	1 0000	1 0000	1.0000	1.0000	1.0000	9995	9670	8461	.6372	. 4927	4240	3576	2990	2650	2283	1994	1682	. 1562	1410	1271	1149	1030	0878	.0822	0794	1770	0753	0743	.0733	7170	0000	0693	0688	0672
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TABLE XXVI (Continued)

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TABLE XXVI (Continued)

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7	ES	24.32	8	26.0	3 9		6.01		21 17	8	2 5	3 5		3 %		20.87	88			24.32	8	17.72		2 8	3;	8	22.52	8	22 67	8		3 8		26 58		40 54	SATELLITES WILL	12		SATELLITES WILL	13 41	
ø	SATELLITES	21.62		2 2	26 88		21.47		36.49		20°	3 2		37 69		42 49	38		SATELLITES	45.95		55 56		2	3		59.01		58 86	8		3 4		69 07	8	70 27		99 10	2		45 07	;
ស	Z	54 05	8	7 8	45 20		41 74		27 93		20.05 0.05	38		4°		29 88	8		MORE S	00 001	8	93 09		? 8	3 5		8C 94		89 49	8		9 9 9		26 R6		100 00	HAT EXA	17 67		HAT N 0	82 74	
~	NG EXACTLY	8	8	- S	22 07	8	21.82	8	11 86	8	- (c	3 6	1 2	3 2	8	1 05	88	3	SEEING N OR MORE	8000		8 8 8		6 8	3		98 80		98 80	8		3 4		800		00 00	CENT) TO	9	<u> </u>	CENT 1 T	97 64	;
۳	OF SEEING	8	8	3 8	3 4		7 68	00	1 20	8	2 2	3 9	2 8	3 12	8	8	88	3			8			38	38		8 8		8	88	38	3 2			8		PROBABILITY (IN PERCENT) THAT EXACTLY N	35		PROBABILITY I IN PERCENT! THAT N OR MORE	100	} }
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TABLE XXVII Baseline 15 - Best Case

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	PER	12 00	12.8	12.00	12.00	12.8	12.00	12.00	12.00	12.00	12.00	12.00	12.00	12.00	12.00	12.00		REMENT OF		THE FOLID
	ANOM	00	120.00	240.00	80.00	200.00	320.00	120.00	240.00	360.00	160.00	280.00	4 0.00	200.00	320.00	80 00		TIME INCREMENT		SATELLITE MOST NEARLY OVERHEAD IS USED AS ONE OF
£TS	INC	55.00	55.00	55.00	55.00	55.00	55.00	55.00	55.00	55.00	55.00	55.00	55.00	55.00	55.00	55.00		PRINTED AT		TS USED
AL ELEMENTS	RASC	30,00	30.00	30°08	150.00	150.00	150.00	210.00	210.00	210.00	270.00	270.00,	270.00	330.00	330.00	330.00	VIIONS	IEES IEES Ieters pr		VERMEAN
ORBITAL	ARGP	8	8	8	8	8	8	8	8	8	8	8	8	8	8	8	I CALCULA	1.00 DEGR 2.00 DEGR 2.2 0N PARAM	360 = 10	NFARI V
	£CC	000	000	000	000	8	8	000	8	000	000	000	000	000	000	000	RIBUTION	ALE = E TEP = 10 ACREMENT INCREMENT	MIN) = IENT(MIN)	TE MOST
		-	7	m	4	វភ	•	7		on.	9	=	12	<u>.</u>	=	51	GLOBAL DISI	MASKING ANGLE = 5.00 DEGREES LATITUDE STEP = 10.00 DEGREES LATITUDE INCREMENT = 2 LONGITUDE INCREMENT = 2 DILUTION OF PRECISION PARAMETERS PR	TOTAL TIME	THE SATELLI

TABLE XXVII (Continued)

1.0000 1.	1.0000 1.	1.0000 1.0000 1. 1.0000 1.0000 1. 1.8721 1.0000 1. 1.8344 1.0000 1.	1,0000 1,0000 1. .9721 1,0000 1. .8344 1,0000 1.	.8344 1.0000 1. 5562 1.0000 1.	8344 1.0000 1.	4	2000 -	.4315 1.0000 1.	3716 1.0000 1.	.3259 1.0000 1.	. 2738 . 9926	. 2301 . 9408 .	. 1921	. 1604 . 6002	1321 . 4749	1058 .4121	. 0934 . 3589	. 0778 . 3159	. 0643 . 2833	. 0588 . 2448	. 0546 . 2209	•	. 0300	9000		100 T T T T T T T T T T T T T T T T T T	0461 0952	0437 0877	0419 . 0823	0419 0780	. 0392 . 0752	. 0380 . 0727	. 0366 . 0691	1 .0329 .0679 .07	. 0303
1.0000 1.0000 1.0000 1.0000 1.0000 1.0000			÷		_	•	. 9826 . 5749	•	•	•	. 1860 . 1150	•	. 1035 0738		•	•	. 0555	•	. 0471 . 0425	•	•	0400 0080	8050 . 0040 .	•	•	ACCO.	•	•			.0268 .0239	. 0248 . 0239	•	•	.0239 .022
0000	1.0000	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	1.0000	1.0000	1.0000		1.0000	0000	. 9720	. 8571	.6701	. 5212	4485	3915	3300	. 2964	2632	. 2347	2045	20.00	7601	0.4.	7071	900	1280	. 600	4870	0724	0020	0688	929	. 0647	.0643	. 0641	. 0629
	0.	7	₹.	9.	₩.	1.0	1.2	▼ .	9 -	8 -	2.0	2.2	2.4	2.6		0.0	3.2	•	10 °	•			7 4) v3			4.0	9.9	89. U	

TABLE XXVII (Continued)

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1	TES	.4	_							'n	•	•	a			TES	24	;	7		·	7	•	m		**		•		24	SATE	3.74	SATE	3.74
•	ATELL!	 - 8	28.66	. 15 0.00	8	13.51	36.0	8	37.69	15.02	8	= 8 =	27.18	86		MORE SATELLITES	32.43	88	8	15.32	3.6	8	60.38	*	Ξ.	2 8	4.4	88		40.54	CTLY N	23.83	R MORE	27.56
L	LY N S	67.57	55.71	82 OO		37.99	50.45	8	49 . 25	36.49		. SS	59.91			MORE S	00.00	88		68.17	8 8		90.84	30.39		2	69.52	8		00.00	AT EXA	47.89	AT N Q	75.48
•	SEEING EXACTLY N SATELLITES	88	3.00	28	8	14.29	9 5	8	9. 19. 8	44 29	8	9 8 8 8 8 8	3 15	88	3				38	100.00		g 8	00.00		8			8	38		NT) TH	24 22	NT (TM	88 86
e		88											38	88	}	SEEING N OR							100.001 50.001	-							PROBABILITY (IN PERCENT) THAT EXACTLY N	. 32 2	4 PERCE	
~	NT, OF	88	8	88	8	88	38	8	88	38	8	8 8	38	88	}	NT.) OF	8.	§ 88	<u>3</u> 8	8	\$ 8 8	<u>2</u> 38	9.001 20.00	88 5	8	<u>₹</u> 88	ĕ 88	88	38	8	ITY (IA	8	ITY (10	100.00 100.00 100.00
	IN PERCENT	88	8	88	2	22	3 2	2	22	88	2	2 9	2 2	22	!	IN PERCENT	00 00	29	3	8	<u> </u>	3	8 8	5 5 8	9	2 ç	8 8	29		9	BABIL		BABIL	8 0 0
-		•	•	•	•	•		•	•	•				•	•		00.0	2	3	8	9	3	8 8 8	8	0	3	90	9.00	3	00	ш	8		9.00
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LAI		90	2	9 6	9	၉ ရ	3 2	0	9 6	8	9	9	26,	8	2		06	8	2	9	9 6	2 2	<u>o</u> 0	9 0	2	9 9	209	9	9	ė,	A GLOBAL	PROB	A GLOBAL	PROB
																															ş		. ₹	

TABLE XXVIII
Baseline 15 - Worst Case

			URBITAL ELEMENTS	^		
	r.cc	ARGP	RASC	INC	ANUM	PER
-	8	8	30.00	55 00	120.00	12 00
3	800	8.0		٠.	240 00	12.00
e	00.0	0.0	90 00		40 00	12 00
	000	8.0	90.06	55 00	160.00	12 00
រភ	00.0	0.00	90.00		280 00	12.00
	00.0	80.0	150.00	55.00	80.00	12.00
	00.0	0.00	150.00	55.00	320.00	12.00
	00 0	00.0	210 00	55.00	120.00	12.00
o	00 0	00.0	210.00	55.00	240.00	12.00
	00	8	210 00	55 00	360 00	12.00
	00.0	00.0	270.00	55.00	160 00	12.00
	00	00	270.00	90	280 00	12.00
2	800	8	330.00	55.00	200 00	12.00
	00 0	0.00	330.00	55.00	320 00	12.00
	000	0.00	330.00		80 00	12.00
GLOBAL DISTRIBUTION CALCULATIONS	BUTION C	ALCULA	TIONS			
MASKING ANGLE = 6 LATITUDE STEP = 10 LATITUDE INCREMENT LONGITUDE INCREMENT	= 6.00 = 10.00 EMENT = REMENT =	O DEGREES O DEGREES 2	EES			
DILLITION OF PRECISION PARAMETERS PRINTED AT TIME INCREMENT	RECISION	PARAN	ETERS PI	RINTED A	T TIME I	NCREMENT OF
TOTAL TIME(MIN) = TIME INCREMENT(MIN)		360 = 10		٠		
THE SATELLITE MOST NEARLY OVERHEAD IS USED AS ONE OF THE	MOST NE	ARLY 0	VERHEAD	IS USED	AS ONE	OF THE FOUR
IN ALL CALCULATIONS OF THE VOLUME OF THE TETRAHEDRON	ATIONS D	F THE	VOLUME (OF THE T	ETRAHEDR	NO

TABLE XXVIII (Continued)

	400A	HDOH	MDOM	TDOP	PDOP	GDOD
0.0	1.0000	1.0000	1.0000	1.0000	1.0000	1.0000
~	1.0000	0000	1,0000	1.0000	1 0000	1 0000
₹.	1 0000	1.0000	1.0000	0000	1.0000	1 0000
6 0.	1.0000	0000	+ 0000 -	0000	1.0000	1 0000
₩.	1.0000	. 0000	6666 .	. 9764	0000	-000
<u> </u>	1.0000	0000	1118.	. 8522	1.0000	1.0000
7.7	- 0000	. 9865	. 5770	5824	1.0000	- 000
-	9997	7424	3798	. 4921	1.0000	1.0000
6	9740	.5113	. 2596	4308	1.0000	1.0000
80.	8698	3220	. 2156	3815	1.0000	1.0000
7.0	7016	2519	1915	3350	9836	9866
2	8754	2129	1694	2900	9430	9904
•	507A	1889	1567	2558	8211	828
. 60	4414	1860	1487	2237	6159	8235
, c	6686	1572	1407	1938	5224	65
	0000.	1481	1316	1690	4658	8644
) (n	3000	1264	1282	1574	4124	49
	2010		1237	1454	3720	A 4 4 1
e C	25.78	1278	12.15	1378	6666	417
) e	986	1281	1202	1305	3061	28.
0	2175	1225	1178	1275	2820	3524
7	1997	1203	1165	1258	2594	3265
7.7	1861	1189	. 1151	1236	. 2335	3065
₽.4	. 1726	. 1178	. 1130	. 1224	. 2 186	.2780
8 0.	1619	. 1151	1119	. 1212	1966	. 2613
0.	. 1577	1126	1101	1197	. 1829	. 2397
S 2	1548	1118	1091	. 1193	. 1754	. 225
מו	1526	1099	1071	1190	. 1672	. 2125
8 9.	1508	1087	1048	1180	. 1623	1977
٠.	1474	. 1078	. 1045	1176	1191	1869
0.9	1459	. 1067	. 1037	1160	. 1584	. 1777
٠.	1435	. 1052	1037	. 1137	. 1550	. 1702
٦,	1418	1046	. 1037	1121	1510	1631
90	141	1039	1035	1100	. 1482	1602
8	1402	1034	1024	1080	1468	. 157
7.0	1393	1028	. 1012	1069	1454	. 1532

TABLE XXVIII (Continued)

MINIMUM LAT COMETTUDE 1	NANTHUM LONGITUDE	707070707070707070707080808080807070707			0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	HAXIMUH LONGITUDE		00000000000000000000000000000000000000		60000000000000000000000000000000000000				000000000000000000000000000000000000000		>0000000000000000000000000000000000000	00000000000000000000000000000000000000		00000000000000000000000000000000000000	_	
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TABLE XXVIII (Continued)

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9																																																
- -																																										SEEN			7000			
•																				38		_				1.80								1.50							38	S WILL BE	ļ	*	ABILITY (IN PERCENT) THAT N OR MORE SATELLITY (IN PERCENT)		5	
7		•	. .1	8	5 8	3 8	38	S	8	22	8	20	: 8	3 %	3 8	3 8	2 6	3 8	8	3 5	-	-		=	8	=	8	9	8	92	8	11	8	57	8	9 6	3 8	2 8	3 2	5 8	200	ABILITY (IN PERCENT) THAT EXACTLY N SATELLITES WILL	;	₩. •	TELL TTE		10.1	
9		SEEIMS EXACILT N SATELLIIES	37.84	38	3 8	3 2	8	22	8	33	8	33	8	38	8	3	9 6	3 6	B 8	3 22	•	STI ITES		8 23	8	3	8	87	8	87	8	20	8	8	3	2 6	3 5	9	3 5	; 8	56.76	LY N SA		25.23	MORE SA		35.40	
S	2	Z Z	27.03 3	3:	7 8	3 4	8	63	8	77	8	88	8	3	8	3	3 8	3:	2	3 %		MORE SATELLIT		97	8	41	8	35	8	50	8	27	8	77	3 :	2 8	3 8	; 8	3 2	38	38	T EXACT	;	2	2	<u> </u>	7	
•	9	EXACII	27.03 2	36	3 6	3 6	8	33	8	87	8	47	8	=	3	2	: 8	3 6	38	8				8	8	2	8	76	8	83	8	=	8	7	3 2		3 8	38	8	38	38	IT) THA	5	2.77 33	THE		91.61 68	
C	9	7E F 1 75	0.00	38	2 8	38	8	52	8	99	8	92	8	9	8) C	3 8	3 8	38	8		SEETING N OR		8	8	8	8	8	8	38	8	2	8	8	3 9	2 9	2 5	8	2	2	2 8	PERCEN	;	.84 22	PERCEN		99.45 91	
~	č	5	8	3 8	3 8	8	8	99	8	20	8	8	8	9	8	8	3 8	3 8	3 8			Ö	;	8	8	8	8	8	8	8	8	8	8	8	38	38	38	38	8	8	38	ITY (IN	•	9	TY (IN			
_		N PERCENT	86	3 8	3 8	38	8	8	8	8	8	8	8	8	8	8	3 8	3 8	38			N PERCENT																			38 5 8	OBABIL	5	8	OBABIL		00 100 00	
		MI ALI	8	38	38	38	8	8	8	8	8	8	8	8	8	8	3 8	3 8	38	8		IIV IIN																			88 88 88	BASIS THE PROB	•	3	BASIS THE PROB	!	00.001 00.001	
3	7.1.1.1.1.1.1.1.1.1.1.1.1.1.1.1.1.1.1.1	CEABIL	ö	3	•	0	ō	ō	ō	ō	0	0	a	a						0		PROBABILITY		50.0	•	<u>8</u>	0	<u>5</u>													8			9			0.00	
LAT	Ğ	ť	ġ	2 0	2 2	9	9	30	20	2	0	-10.	-20	-30	-	-50				9		a.		0	9	2	90	50	9	30	50 .	<u>.</u>	o :	<u>.</u>		2	Ş	2	70	9	3 2	A GLOBAL	900	7 X C B	A GLOBAL		PROB	
												•	•	•	•	•	•	•	٠	•														r		• •	'	,	,	•	•	3	٥	•	Z		•	

TABLE XXIX Global Distribution - Modified 17

		ORBITAL	ואר בר	ELCMENIS)			
	ECC	ARGP	RA	RASC	INC	ANOM	PER	
-	070	8	98	8	55.00	126 80	12.00	
7	070	000	30.00	8	55.00			
e	070	00	90	8	55.00	42.80		
4	070		90.00	8	55.00	160 30		
s S	.070	00.0	90.00	8	55.00	269.50	12.00	
9	.070	00.0	150.00	8	55.00			
2	.070	9	150	8	55.00	193.90	12.00	
90	070	0	150.00	8	55.00	310.00	12.00	
o	070	0.0	210.00	8	55 00	123.30	12.00	
01	070	000	210.00	8		230.00	12.00	
=	.070	0.00	210	8	55.00	355.70	12.00	
12	070	00	270.00	8	55.00	161,40	12.00	
13	.070	00	270	8	56 00	270.80	12.00	
4	.070	00	270.00	8	55.00	44. 10	12.00	
15	070	000	330.00	8	55 00	198.60	12.00	
91	070	000	330	8	22 00	315.90	12.00	
17	.070	0.00	330	8	22 00	89.40		
AL DISTRIBUTION CALCULATIONS	BUTION	CALCUI	LATION	S			٠	
ING ANGLE = 5 FUDE STEP = 10 FUDE INCREMENT	EMEN REME	00 DE(00 DE(1 2	5.00 DEGREES 10.00 DEGREES T = 2 NT = 2					
ION OF PI	PRECISION		AMETER	S PRI	PARAMETERS PRINTED AT		TIME INCREMENT	O.
TIME(MIN) = INCREMENT(MIN)		360 = 10						
TELLITE	MOST N	EARLY	OVERH	EAD 1	IS USEC	THE SATELLITE MOST NEARLY OVERHEAD IS USED AS ONE OF	OF THE FOUR	K
CALCUL	ATTONS (F 1		뿔	三王.	ETRAHEDR	Z	

TABLE XXIX (Continued)

NUMBER	VDOP	HDOP	MDOP	100P	PDOP	GDOP
0	1.0000	1.0000	1.0000	1.0000	1,0000	1.0000
~	1.0000	0000	1.0000	1.0000	1 0000	1.0000
•	1.0000	0000	1.0000	1.0000	1.0000	1.0000
9	1.0000	- 0000	1.0000	1.0000	1.0000	1.0000
∞	1.0000	1.0000	1.0000	. 9702	1.0000	1.0000
0	1.0000	0000	. 8664	. 7722	1.0000	1.0000
~	- 0000	. 9850	. 4824	5045	1.0000	1.000
-	9970	. 6787	. 2444	3565	1.0000	1.0000
9	. 9434	.3911	. 1172	. 2798	0000	1.0000
•	8232	1953	0701	.2177	1.0000	1.0000
0	.6352	1039	0478	1570	. 9877	9886
~	4552	0830	0352	1208	9208	9809
•	3518	0434	0252	. 0867	7316	8008
	. 2821	.0305	0.185	0611	5383	7375
60	2160	.0222	0144	0458	3916	5684
0	1807	.0167	.0115	.0327	3085	.4430
7	1484	.0135	.0105	.0275	. 2459	.3578
•	. 1243	.0112	.009	. 0222	. 1936	3011
9	. 1015	.0103	.0082	.0189	. 1615	. 2532
20	.0827	6800	.0073	.0164	1342	. 2 106
0	. 0653	.0082	.0073	.0148	1149	1721
~	.0522	.0078	6900	0139	. 0915	. 1483
~	.0428	.0078	0067	.0131	.0735	. 1319
₽	. 0357	0000	.0063	.0119	. 0591	1158
•	.0298	8900 .	.0057	.0104	.0457	.0939
0	.0266	0900	.0052	8600	.0376	.0774
~	.0243	0900	.0050	.0093	.0337	.0634
•	. 0221	.0058	.0050	.0085	.0302	.0525
6	.0204	.0053	.0048	0083	.0266	.0428
•	.0182	. 0051	.0048	.007	.0245	.0374
0	.0172	. 0051	.0048	6900	.0228	.0337
~	.0165	.0050	.0046	0900	. 0207	.0299
₹.	0.154	0000	.0044	.0057	.0186	.0279
₩.	0144	.0044	.0042	. 0057	.0175	.0256
€0,	0134	0042	.0042	. 0055	0.168	.0238

TABLE XXIX (Continued)

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TABLE XXIX (Continued)

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																																							BE SEEN		BE SEEN		
	a		8	81	25	3 5	38	38	38	98	8	8.	0 .8	8	8	8	8	13.81	35.00 43.00			8	38	37.50	8	8	8.0	8	8	8 8	38	8	86	88	3 8	13.81	8	32.43	ES WILL	40	MILL	- 40	
	7	u	8	8	58	8 %	68	3 5	. 8	3 4	8	23	8	=	8	-	8	63	0.6 10.00		- - ~	5	38	32	8	72	8	7	8	27.4 8.6	3 =	8	5	8:	ā 8	3 7	8	15 60	PROBABILITY (IN PERCENT) THAT EXACTLY N SAFELLITES WILL	16. 15	SATELLITES	17.55	1
	•	N SATELLITES	7	8:	* 8	82	2 5	3 5	9	3 15	8	9	8	5	8	5	8	26	5.00 5.00 5.00	-	MORE SATELLITES		28	3 2	8	29	8	8	8	75.23	38	8	9	8:	B 8	38	8	8	TLY N SL	44.69	MORE SA	62.24	
	s o	Y N SA	4	8	4 6	8 4	g 8	3 2	98	3 2	: 8	57	8	2	8	7	8	8	88 80 80		ORE SAT		38	38	8	23	8	8	8	86.35	3 6	8	20	8	2 2	38	8	8	T EXACT	31.95 4	PROBABILITY (IN PERCENT) THAT N OR MORE	94.20 6	
	•	SEEING EXACTLY	8	8	2 8	8 8	2 8	3 5	2 8	3 5	38	35	8	8	8	08	8	8	88		8	٠	38	38	8	2	8	8	8	88	38	8	8	88	3 5	38	8	8	NT) THA	5.78 3	VT.) THA	98.98	
	m		8	8	88	8 4	2 8	38	38	38	8	8	8	8	8	8	8	8	88		SEEING N		38	8	8	8	8	8	8	88	38	8	8	88	38	38	8	8	1 PERCE	6	1 PERCE		
	~	INT) OF	8	8	88	88	88	38	38	38	8	8	8	8	8	8	8	8	88		Õ	}	88	38	8	8	8	8	8	88	38	8	88	88	38	38	8	8	ITY (IA	0.0	ITY (IN	100.00 100.00	<u> </u>
		IN PERCENT)	8	8	88	88	88	38	38	38	38	8	8	8	8	8	8	8	8 8		M PERCENT)	, ,	38	38	8	8	8	8	8	8.8 8.8	38	8	88	88	38	38	8	8	108ABIL	8	TOBABIL	8	}
		_																	e e 88		ITY (IN	•								88 88										8		000 00 100	!
	•	PROBABILITY																	00		PROBABILITY		3 c	9	0	0.00	0	0.00	0.0	80	90	0	00	0 6	3 c	9	0	100	BASIS THE	0	BASIS THE	90)
!	ב	ĕ	8	2	2 (3 5	3 €	}	3 6	2	ė	01	-20	9	9	-50	9	2.	<u> </u>		PR		B C	2	9	20	9	30	20	<u>ō</u> c	2	-20	ဇ္	9	200	2	90	06-	ON A GLOBAL	PROB	ON A GLOBAL	PROB	1

TABLE XXX Modified 16 - Best Case

																			0		œ
	PER	12 00	00	12.00	12.00	12.00	12.00	12.00	12.00	12.00	12.00	12.00	12.00	12.80	12.00	12.00	12.00		CREMENT OF		THE FOUR
	ANOM	126.80			269.50		193.90	310.00	123.30	230.00	355.70	161.40	270.60	44.10		315 90	89.40		TIME INCREMENT		SATELLITE MOST NEARLY OVERHEAD IS USED AS ONE OF
MTS	INC	55,00			55 00					55.00	55.00	. 55.00	55.00	55.00	55.00		22 .00		INTED AT		IS USED
ORBITAL ELEMENTS	RASC	30,00	30.00	90.00	90.00	150.00	150.00	150.00	210.00	210.00	210.00	270.00	270.00	270.00	330.00	330.00	330.00	TIONS	IEES IEES IETERS PR		VERHEAD
ORBIT/	ARGP	00	0	00 0	00.0	0.00	8.0	00.0	000	00 0	0.0	00.0	0.0	00.0	000	00.0	0.0	CALCULA	00 DEGR	360 = 10	NEARLY O
	503	070	070	070	070	.070	070	070	070	070	070	070	070	.070	040	070	070	RIBUTION	ILE = 5 EP = 10 ICREMENT NCREMENT PRECISI	MIN) = Jent(min)	TE MOST
		_	7	m	•	uñ	•	7	30	6	2	=	12	<u>C</u>	=	5	16	GLOBAL DISTRIBUTION CALCULATIONS	MASKING ANGLE = 5.00 DEGREES LATITUDE STEP = 10.00 DEGREES LATITUDE INCREMENT = 2 LONGITUDE INCREMENT = 2 DILUTION OF PRECISION PARAMETERS PRINTED AT TI	TOTAL TIME! TIME INCREM	THE SATELLI

TABLE XXX (Continued)

VD0P 1.0000 1.0000	HDOP 1.0000 1.0000	MDDP 1.0000 1.0000	1.0000 1.0000 1.0000	PD0P 1.0000 1.0000	6D0P 1.0000 1.0000
1 . 0000 . 0000 . 0000 . 0000	1.0000 1.0000 1.0000 9880	1.0000 1.0000 8885 5533	1.0000 .9780 8074	0000	00000
9975 9554 66874 5762 5762	. 7279 . 4570 . 2524 . 1505 . 0995	. 3092 . 1672 . 1076 . 0782	2375 2702 2055 2055	1.0000 1.0000 1.0000 9928 9456	9893 9893 9883
2429 2429 2338 2335 1959 1396	0437 0437 0437 0294 0237 0234	0247 0313 0213 0218 0218	. 1267 . 0939 . 0753 . 0583 . 0438 . 0391	. 482 6176 4699 3762 3094 2560 2181	
0978 0841 0710 0632 0552 0552	0.000	260000 260000 2600000000000000000000000	0322 0228 0228 02228	1594 1313 1313 0929 0776 0680	2294 2000 1883 1138 1484 1484
00000 00384 00384 00384 00386 00386 00386	0129 0120 0120 0113 0113	6000 6000 6000 6000 6000 6000 6000 600	00000000000000000000000000000000000000	05577 0619 0687 0687 0687 0397	0850 0680 0680 0580 0580 0580

TABLE XXX (Continued)

		LONGITUDE	MIMINIM				70	00 00 00 00 00 00 00 00 00 00 00 00 00	LOWGITUDE	MAXIMUM	LONGITUDE 5
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TABLE XXX (Continued)

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	7	ķ.																			8			- - - -															2 25					ATELLIT		7.43	ATELL 1T		7.80	
)	ø	SATELLITES																			8		•	MORE SATELLITES															32.28							37.01			44.81	
	vo	z																			8			MORE SA		88	38	9	8	10 C	3		31	n (3 5	8	6	8	83.63	8	9	8	8	AT FXAC		43.73	4T & 00		88.54	
	•	IG EXACTLY																			8			SEEING N OR	;	38	38	3	8	2 8	3	8	38	38	38	8	8	8	80.82	8	8	8	8	(IN DEBCENT) THAT EXACTLY N		11.34	SECH OF THE THAT WE DESCRIPTION OF THE PROPERTY OF THE PROPERT		88 . 68	
!	m	F SEEING																			8				1	88	3 8	3	8	3	3	8	3 8	3 8	3 8	8	8	8	100.001	8	8	8	8	Case M	247	27.	Jasa Mi	2	100.001	
	~	PERCENT) OF																			8			PERCENT) OF	1	88	38	3	8	38	3	8	38	38	38	8	8	8	100.001	8	8	8	8	. YT1 (8.0	17 AT1 11		100.001	
	-	IN PER																			8			IN PER		88	88	3	8	8	3	8	38	38	38	8	8	8	100.001	8	8	8	8	PROBABLE LTV	200	8.0	OPCRAR		20.00	
	•	PROBABILITY (8 8																8			PROBABILITY	1		38	8		38	3	8	38	38		8	8	8	100.001	8	8	8	8	BASIS THE	2175	0.00	RACIC THE		100 00 100 001	
	וען	PRO	a	2		2 6	3	20	ç	90	20	2	0	0.	-20	-30	9	50	9	-20	9	- 90		PRO	į	9	9	é	9	2	2	e e	2 9	<u>.</u>	9	-20	90	-40	-50	• 9 0	-70	-80	06-	A GLOBAL		PROB	() () () () () ()		PROB	
																																												ē	5		Ž	5		

TABLE XXXI Modified 16 - Worst Case

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				•	•													of.	
	PER	12.00	25.00	88	12.00	12.00	12.00	12.00	12.00	12.00	12.00	12.00	12.00	12.00	12.00	12.00			
	ANOM		233 40	160.30			193.90	310.00	30.00	55.70	161.40	270.60	44.10		315.90	89.40		TIME INC	
s	INC	8	88	•	8		8				-			8	55.00 3	55.00		PRINTED AT TIME INCREMENT	
ELEMENTS	RASC		90.00								•	270.00			8	330.00	SNO	ES ES TERS PRI	
ORBITAL	ARGP	8	88						•	•							ALCULAT	5.00 DEGREES 10.00 DEGREES NT = 2 ENT = 2 ISION PARAMETER	360 = 10
	ECC	.070	070	020	070	.070	.070	.070	070	.070	.070	.070	.070	070	070	.070	BUTION	NGLE = 5.0 STEP = 10 0 INCREMENT = INCREMENT = OF PRECISION	
		-	~ °) 4	ß	99	7	œ	G)	5	=	12	13	7	2	16	GLOBAL DISTRIBUTION CALCULATIONS	MASKING ANGLE = 5.00 DEGREES LATITUDE STEP = 10.00 DEGREES LATITUDE INCREMENT = 2 LONGITUDE INCREMENT = 2 DILUTION OF PRECISION PARAMETERS	TOTAL TIME(MIN) = TIME INCREMENT(MIN)

TABLE XXXI (Continued)

NUMBER	400A	HDOP	MDOP	T00P	PDOP	GDOP
		000	.000	.000	1.0000	.0000
		0000	0000	000	0000	0000
	0000	1.0000	0000	0000	1.0000	1.0000
	1.0000	1.0000	1.0000	.9758	1.0000	1.0000
	1.0000	1.0000	. 8839	.8036	1.0000	1.0000
	- 0000	. 9879	. 5424	5706	- 0000	+ 0000 -
	. 9977	7225	. 3207	4301	- 0000	1.0000
	9510	.4598	1981	. 3538	1.0000	1.0000
	. 8529	. 2744	1396	. 2850	1.0000	1.0000
	.6875	1808	1084	. 2234	. 99 15	9991
	R242	1223	0007	1804	9371	9856
	9 6 6 4		920	4.50	7749	
		200				4 6 6 6
	3534	5680	020	. 1141	. 5070	. 7833
	. 2850	.0753	.0641	.0968	.4805	.6370
	. 2449	0690	.0589	.0820	. 3925	. 5240
	.2117	.0632	.0546	.0757	. 3270	. 4429
	. 1846	.0572	.0514	.0711	. 2739	. 3833
	1611	.0537	.0497	. 0868	. 2339	. 3318
	1405	.0515	.0479	.0628	. 2043	. 2879
	1207	.0501	.0475	. 0603	. 1780	. 2479
	1056	.0489	.0460	0577	1546	. 2173
	8960	.0483	.0451	. 0561	. 1326	. 1968
	.0901	.0464	.0438	. 0549	. 1170	1788
	.0840	.0454	.0419	. 0533	. 1038	1540
	.0802	.0439	.0412	0230	.0951	1361
	.0776	.0428	. 0405	.0517	.0905	. 1202
	0758	.0420	.0396	0496	.0869	. 1082
	.0724	.0409	.0391	. 0482	.0831	1004
	.0695	.0402	.0383	.0477	9080	. 0948
	.0874	.0398	.0381	.0462	.0774	. 0895
	. 0853	.0382	.0375	.0448	.0742	.0852
	.0630	.0388	.0370	.0446	.0697	.0825
	. 0625	.0374	9960	.0438	. 0675	.0793
	6090	.0369	.0364	.0429	.0670	.0763
	. 0585	.0368	.0353	.0425	.0661	.0736

TABLE XXXI (Continued)

LONGITUDE LONGITUDE
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TABLE XXXI (Continued)

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9																																			SEEN		SEEN		
d																																			9E S		9E S		
50																8.5												9.6						ē :		67		.67	
7	ES															96.		- -	2									16.67						1	DBABILITY (IN PERCENT) THAT EXACTLY N SATELLITES WILL	11.00	SATELLITES WILL	11.67	
•	SATELLITES															95		. !	SATELLITES									56.16						0 0 0	CTLY N	34.06		45.73	
vo.	z															86			E E									91.74						3	HAT EXA	38.89	AT N Q	84.82	
•	SEEING EXACTLY															88			NO NO ST									99.70						3	ENT) TI	13.53	ENT) T	98.15	
e	OF SEEIN															88			OF SEEING	8	88	38	38	8	8	88	38	9.00	38	8	88	38	88	3	IN PERC	1.85	IN PERC		
~	PERCENT) Q															88			PERCENT) 0	8	88	38	38	8	8	88	8	90.00	38	8	88	38	88	3	ILITY (0.0	OBABILITY (IN PERCENT) THAT N OR MORE	00 100 00 100 00	
-	(IN PER															88		:	IN PER	8	88	8 8	38	8	8	88	38	20.00 2.00	38	8	88	38	88	3	Ē	0 0	PROBAB	100.001	
•	PROBABILITY															88			PROBABILITY	8	88	88	38	8	8	88	38	200 001	38	8	88	38	88	3	BASIS THE	000	BASIS THE PRO	100.001	
LAT	PR	9	9 6	9	. 20	2 6	200	2	0	9	200	2	Š	-60	-70	9	i	i	Z.	9	9	2 9	9 05	9	30	0 9	و و	-10	200	-40	05	32	08.		ON A GLOBAL	PROB	ON A GLOBAL	PROB	

TABLE XXXII Modified 15 - Best Case

	08	ORBITAL	L ELEMENTS	S .				
ECC	ARGP	<u>و</u>	RASC	INC	ANOM	PER		
1 020		9	30,00	55.00	00.00	12.00		
•		Ö	30.00	55 00	126.60	12.00		
2000		2	30.00	55.00	233.40	12.00		
-		2	150.00	55.00	83.80	12.00		
•		2	150.00	55.00	193.90	12.00		
		2	150.00	55.00	310.00	12.00		
		2	210.00	55.00	123.30	12.00		
•			210.00	55.00	230.00	12.00		
•			210 00	55,00	355.70	12.00		
•			270.00	59.00	161.40	12.00		
•			270.00	55,00	270.60	12.00		
•			270.00	55.00	44.10	12.00		
•			000000000000000000000000000000000000000	55.00	198.80	12.00		
2000		2 2	330.00	55.00	315.90	12.00		
	00.0	88	330.00		89.40	12.00		
GLOBAL DISTRIBUTION CALCULATIONS	ION CAL	CULA	TIONS					
MASKING ANGLE = 5.00 DEGREES LATITUDE STEP = 10.00 DEGREES LATITUDE INCREMENT = 2 LONGITUDE INCREMENT = 2 DILUTION OF PRECISION PARAMETERS	5.00 DEGREES 10.00 DEGREES NT = 2 IENT = 2 ISION PARAMETE	DEGREES DEGREES 2 2 PARAMETE	LEES REES RETERS P	PRINTED AT	TIME	INCREMENT	0 JO	0
TOTAL TIME(MIN) = TIME INCREMENT(MIN)	360	õ						
THE CATELLITE MAST NEARLY OVERHEAD IS USED AS ONE OF	ST NEAR	۲	VERHEAD	1S USEC	AS ONE	THE	FOUR	
THE STREET ATTOMS OF THE VOLUME OF THE TETRAHEDRON	ONC OF	Į	VOLUME	OF THE 1	FTRAHED	RON		

TABLE XXXII (Continued)

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TABLE XXXII (Continued)

LONGITUDE LONGITUDE 1 2 2 3 3 3 4 1 1 2 2 2 3 3 3 4 1 1 2 2 2 3 2 3 2 4 1 1 1 2 2 2 3 3 3 3 4 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	00000000000000000000000000000000000000	MINIM	LUMBATIONE	800
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TABLE XXXII (Continued)

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•		-00086	○ ₩○₩○○○₩○○○	~0=00000000000000000000000000000000000	SATELLITES WILL 2.22 SATELLITES WILL 2.22
•	TES	<u> </u>	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	16.5 16.5 16.5 16.5 16.5 16.5 16.5 16.5	SATELL 2.22 SATELL 2.22
1 0	SATELLITES		29.00 mm	SAFELLIT 37.84 30.00 17.87 17.87 17.87 17.87 17.87 17.87 17.87 18.00 18.	25.48 25.48 38 MORE 27.70
	Z		0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	MORE 100 100 100 100 100 100 100 100 100 10	50.99 50.99 HAT N 0
•	SEEING EXACTLY	99998	0 7 0 7 0 8 0 7 0 8 0 0 0 0 8 0	SEE ING N G N G N G N G N G N G N G N G N G	ME PROBABILITY (IN PERCENT) THAT EXACTLY N 0.00 0.00 .77 20 55 50.99 25.48 ME PROBABILITY (IN PERCENT) THAT N OR WORE 100.00 100.00 100.00 98.23 78.69 27.70
	OF SEE11		9699999999999	96 96 96 96 96 96 96 96 96 96 96 96 96 9	(IN PER (IN PER 100.00
~	ICENT) (8888888888888		0.00 11.177 (
-	(IN PERCENT)		8888888888888	(1M PERCENT) 60 00 00 00 00 00 00 00 00 00 00 00 00 0	E PROBABILITY 0.00 0.00 E PROBABILITY
•	PROBABILITY	888888	88888888888888	PROBABILLIY 100 00 00 00 00 00 00 00 00 00 00 00 00	6A51S TH 0.00 BAS1S TH 100.00
LAT	ď	9 9 C 9 9 6	\$ 6 5 5 5 5 5 5 5 5 5 5 5 5 5 5 5 5 5 5	8 8 5 8 8 5 6 8 5 6 5 6 6 8 8 8 8 8 8 8	ON A GLOBAL ON A GLOBAL PROB

TABLE XXXIII
Modified 15 - Worst Case

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	œ	88	38	8	8	8	8	88	38	38	38	88	8	00		ENT OF	
	PER	5.5	2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2									2	2	12		INCREM	
	ANOM	126.80	42.80	160.30	269.50	83.80	310.00	123.30	230.00	333.70	270 60			89.40		PRINTED AT TIME INCREMENT	
STS	INC		20 20 20 20 20 20 20 20 20 20 20 20 20 2	55.00	55.00	55.00	55.00	55.00	9.00	200	90. S	55 00		55.00		RINTED A	
NL ELEMENTS	RASC	30.00	900	90.00	90.06	150.00	150.00	210.00	20.00	200	270.02	330.00	330.00	330.00	TIONS	IEES IEES IETERS PI	
ORBITAL	ARGP	9.6	3 8	8	8	8	8	88	38	38	96	8	00.0	0.0	CALCULA	.00 DEGR	360 = 10
	203	.070	0 0	070	.070	.070	.070	070	0.00	9,6	9,6	020	070	.070	RIBUTION	LE = 5 EP = 10 CREMENT NCREMENT PRECISI	MIN) = ENT(MIN)
		- (N E	•	ស	10	-	00 (n (2 ‡	- 2	. <u> </u>	=	£	GLOBAL DIST	MASKING ANGLE = 5.00 DEGREES LATITUDE STEP = 10.00 DEGREES LATITUDE INCREMENT = 2 LONGITUDE INCREMENT = 2 DILUTION OF PRECISION PARAMETERS PR	TOTAL TIME() TIME INCREM

TABLE XXXIII (Continued)

NUMBER	VDOP	HDOP	MDQM	1 00 <i>p</i>	P00P	GDOP
0.0	1.0000	1.0000	1.0000	1.0000	1.0000	1.0000
~	1.0000	0000	1.0000	1 0000	0000	1.0000
₹.1	0000	0000	0000	0000	0000	0000
₽.	2000	•	200	2000	3	200
••	- 0000 -	-0000	- 0000	. 9811	- 000	- 0000
<u>.</u>	1 .0000	- 0000	8982	. 8355	- 0000	1.0000
	0000	9868	5957	8341	0000	1,0000
•						
•	/ ORB .	1001	7880	* COE .	200	200
9	. 9615	5255	. 2744	4284	- 0000	0000
•	1000	3466	3000	2803	0000	0000
٠	1000	7		9	3	-
•	7348	2607	1884	3166	6000°.	6000
•	400	4.60	900+	2766	1000	000
•	0000	. 4		1	400	
•	5084	. 1878	1548	. 2347	. 8111	. 9427
	AASE	4070	1428	2020	CRR7	B 152
	7			200		
	. 3826	1504	.1348	181	. 5480	6915
	3421	1204	1282	1831	4753	E924
	- 100		100			
	. 3082	. 1325	1227	1506	. 4167	. 5166
	2780	1280	1178	1440	2200	ARKE
٠						
•	. 2511	. 1223	. 1152	13/4	3352	418/
	2306	1179	2111	1310	3018	3790
•						
٠	7617.		200	7071	0017	7
٠	. 1949	1121	. 1073	1234	. 2480	3177
	1812	1103	1062	1201	2296	2968
	47.4	800	1034	_	2111	2739
•		000				
٠	. 1624	. 1062	. 1012	. 1143	1964	. 2500
	1568	1043	1008	1125	. 1820	. 2312
	15.23	100	4400	1094	1722	2150
•	9 6			•		
•	000	2	1960	2	0001	0007
•	1460	9 660 .	0960	1059	1607	1869
	1419	7880	094B	1037	1570	1771
•					0 0 0	
٠	1361	* no.	ESBO.	870	0561	2
•	1364	.0958	. 0934	1008	004	. 1658
	1320	1200	8C60	1004	1456	1818
•	0671	7400.	160.	7660.	201	7001
	1265	0934	6 060	0660	1376	1532
7.0	1250	0917	9680	0988	1349	1495
•		•				

TABLE XXXIII (Continued)

AND CONTROL CO	600		MINIMIM MINIMIM LONGITUDE	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0		
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TABLE XXXIII (Continued)

	- 2																																	
	<u>*</u>																																	
	13																																	
	12																																	
	=																																	
	0																														SEEN		SEEN	
	•		•	ð ru	90	2 0	9	<u>ب</u> و	9 0		9	3 ¢	9	Q (28	•		g c	o sa	9 0	•	9	o ru	, 0	00		o o	•		90	3	-	30	-
	a		o	o –	00	.	0	0	Ċ	,	o (5 C	0	o .	-0	j	_		-	o c	9 0	Ö	9	0	Ġ	0	00	Ö	- (99	ITES W	7	ITES W	Ę
	7	ĘŞ													283		ES	5.5												35.58	SATELLI	8.62	SATELLITES WILL	9.03
2	•	SATELLITES													1 0		SATELLIT	37.84													CTLY N	27.08		36. 10
SAIEL	w	Z													88		MORE S	75.68												88	IAT EXAC	33 18	MT N Q	69.28
MUMBER OF SATELLITES	•	4G EXACTLY													288		SEEING N OR	86												88	ENT) Th	23.63	ENT) TP	92.91
ž	е	OF SEEING													88		OF SEEIN	88	8	88	38	9	8 %	38	88	5	8 2	8	8		(IN PERCENT) THAT EXACTLY N SATELLITES WILL	6.79	ROBABILITY (IN PERCENT) THAT N OR MORE	99.70
	8	N PERCENT) 0			88							9 9			88		PERCENT) 0	100.00	8	88	38	8	88	8	88	8	88	8	8	38	ROBABILITY (90	ILITY (100 .00
	-	(IN PER	0.0	88	88	38	8	88	38	8	8	88	8	8	88	3	IN PER	100.001 100.00	8	88	38	8	8	8	88			8			•	9.8	PROBAB	100 001
	•	PROBABILITY	8	88	88	38	8	88	88	8	8	38	8	0	88	3	PROBABILITY	8.8	8	88	38	8	38	8		8	88	8	8		BASIS THE	8	BASIS THE	100 001
	LAT	PRC	90	200	09	3 4	8	20	<u>.</u>	0	-20	9	-20	9	2 2	į	PRO	9.6	2	09	2 4	ģ	9 9	įo	0.5	30	- - 4 0	9	0,	06-	ON A GLOBAL	PROB	DN A GLOBAL	PROB

TABLE XXXIV Geosynchronous User, Antenna BWDTH = 21.4°

	PER	12.00	2 2 2	00	12 00	12.00	12.00	12.00	12.00	12.00	12.00	12.00	12.00	12.00	12.00	12.00	12.00	12.00		24.00	
	ANOM		120 00		160.00	280.00	80.00	200.00	320.00	120 00	240.00	380.00	160.00	280.00	40 00 04	200.00		80.00		0	
TS	INC	55.00	55 00 54 00	55.00	55.00	55.00	55.00	55.00	22 00	55.00	55.00	55.00	55.00	55.00	55.00	55.00	55.00	55.00		0	1.000
L ELEMENTS	RASC	30.00	88	90.06	90.00	90.00	150.00	150.00	150.00	210.00	210.00	210.00	270.00	270.00	270.00	330.00	330.00	330.00	ENTS	00	40 L AREA =
ORBITAL	ARGP	8	88	8	8	8		8				8						8	TAL ELEM	00	720 = 5) = 21. SPHERICA
	ECC	00	88	000	000	000	000	000	000	000	000	000	000	000	000	000	8	000	SATELLITE ORBITAL ELEMENTS	000	NCREMENTA : NCREMENTA (NIN) (DTH ANGLE (DEG ON OF NAVSAT
		-	~ ~) प	ĽΩ	9	7	90 1	on .	9	=	12	5	14	5	91	17	18	USER SATELL	19	10TAL TIME(MIN) = 720 TIME INCREMENT(MIN) = 5 BEAMWIDTH ANGLE(DEG) = 21.40 FRACTION OF NAVSAT SPHERICAL AREA

TABLE XXXIV (Continued)

0 19364. (5 19364. (10 19364 (15 19364.	20 19364. (25 19364 (30 19364. (35 19364. (40 19364. (45 19364. (50 19364 (55 19364 (60 19364 (65 19364 (70 19364. (75 19364 (80 19364.	85 19364 (90 19364 (95 19364. (
ONLY	DNLY	ONLY																	
2 SATELLITES ARE VISIBLE	2 SATELLITES ARE VISIBLE.	3 SATELLITES ARE VISIBLE	2 SATELLITES ARE VISIBLE	1 SATELLITES ARE VISIBLE	1 SATELLITES ARE VISIBLE	1 SATELLITES ARE VISIBLE	I SATELLITES ARE VISIBLE	O SATELLITES ARE VISIBLE											
ES ARE V	ES ARE V	ES ARE V	ES ARE V	ES ARE V	ES ARE V	ES ARE V	ES ARE V	ES ARE V	ES ARE V	ES ARE V	ES ARE V	ES ARE V	ES ARE V						
/ISTBLE.	TSIBLE.	ISIBLE.	ISIBLE.	/ISTBLE.	ISIBLE.	ISIBLE.	/ISIBLE.	/1S18LE.	1518LE.	ISIBLE.	'ISIBLE	ISIBLE.	ISIBLE.	ISIBLE.	ISIBLE.	'ISIBLE.	/ISIBLE.	ISIBLE.	'ISIBLE.

TABLE XXXIV (Continued)

Ē	IIMEIMAI ALIIMAI	VDOV	HDOP	MDOP	T00P	PDOP	GDOP	SATELLITES CHOSEN
8	19364.	ONLY	O SATELL	O SATELLITES ARE VISIBLE	VISIBLE.			
105	19364.	ONLY	n SATELL	n SATELLITES ARE VISIBLE	VISIBLE.			
10	19364.	ONLY	O SATELL	O SATELLITES ARE V	VISIBLE.			
115	19364.	ONLY	O SATELL	O SATELLITES ARE VISIBLE	VISIBLE.			
120	19364.	ONLY	O SATELL	O SATELLITES ARE N	VISIBLE.			
125	19364.	ONLY	O SATELL	O SATELLITES ARE VISIBLE	VISIBLE.			
130	19364.	ONLY	O SATELL	O SATELLITES ARE VISIBLE	VISIBLE.			
135	19364.	ONLY	O SATELL	O SATELLITES ARE, VISIBLE	VISTBLE.			
140	19364.	ONLY	O SATELL	O SATELLITES ARE VISIBLE	VISIBLE			
.45	19364.	ONLY	O SATELL	O SATELLITES ARE V	VISIBLE.			
150	19364.	ONLY	O SATELL	O SATELLITES ARF V	VISTBLE.			
155	19364.	ONLY	O SATELL	O SATELLITES ARE V	VISIBLE.			
160	19364.	ONLY	O SATELL	O SATELLITES ARE V	VISIBLE.			
165	19364.	DNLY	O SATELL	O SATELLITES ARE V	VISIBLE.			
170	19364.	ONLY	O SATELL	O SATELLITES ARE V	VISIBLE.			
175	19364.	ONLY	O SATELL	O SATELLITES ARE V	VISTBLE			
180	19364.	ONLY	1 SATELL	SATELLITES ARE V	VISIBLE.			
185	19364.	ONLY	1 SATELL	SATELLITES ARE V	VISTBLE.			
190	19364.	ONLY	1 SATELL	SATELLITES ARE V	VISIBLE			
195	19364	ONLY	1 SATELL	SATELLITES ARE VISIBLE	VISIBLE.			

TABLE XXXIV (Continued)

TIME MN.	TIME MAN ALTINA	VDOV	HDOP	MDOP	TDOP	PDOP	GDOP	SATELLITES CHOSEN	
200	19364	ONLY	2 SATELI	2 SATELLITES ARE VISIBLE	VISIBLE.				
205	19364	ONLY	3 SATELI	3 SATELLITES ARE VISIBLE	VISIBLE.				
210	19364	ONLY	2 SATELI	2 SATELLITES ARE VISIBLE	VISIBLE.				
215	19364.	ONLY	2 SATELI	2 SATELLITES ARE VISIBLE	VISIBLE.				
220	19364.	ONEY	2 SATELI	2 SATELLITES ARE VISIBLE	VISIBLE.				
225	19364	ONLY	2 SATELI	2 SATELLITES ARE VISIBLE	VISIBLE				
230	19364.	ONLY	2 SATELL	SATELLITES ARE VISIBLE	VISIBLE.				
235	19364.	ONLY	2 SATELI	2 SATELLITES ARE	VISIBLE.				
240	19364	ONLY	2 SATELL	SATELLITES ARE VISIBLE	VISIBLE.				
245	19364	ONLY	2 SATELI	2 SATELLITES ARE VISIBLE	VISIBLE.				
250	19364.	ONLY	1 SATELI	1 SATELLITES ARE VISIBLE	VISIBLE.				
255	19364.	ONLY	1 SATELI	1 SATELLITES ARE VISIBLE	VISIBLE.				
260	19364.	ONLY	1 SATELI	SATELLITES ARE VISIBLE	VISIBLE.				
265	19384	ONLY	1 SATELI	SATELLITES ARE VISIBLE	VISIBLE.				
270	19364	ONLY	1 SATELI	SATELLITES ARE VISIBLE	VISIBLE.				
275	19364	ONLY	1 SATELI	SATELLITES ARE VISIBLE	VISIBLE.				
280	19364.	ONLY	1 SATELI	SATELLITES ARE VISIBLE	VISIBLE.				
285	19364.	ONLY	1 SATELI	SATELLITES ARE	VISIBLE.				
290	19364.	ONLY	1 SATELI	SATELLITES ARE VISIBLE	VISIBLE.				
295	19384	ONLY	1 SATELL	SATELLITES ARE VISIBLE	VISIBLE.				

TABLE XXXV Geosynchronous User, Antenna B \vee dth = 45°

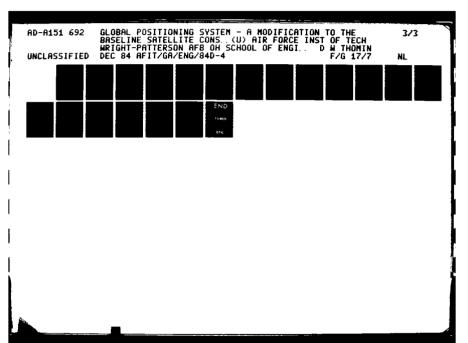
PER	2 00	12.00	2.00	2.00	12.00	7.00	2.00	2.00	2.00	2.00	2.00	12.00	2.00	12.00	2.00	12.00	2 00			24.00		
ANOW	00	•							320.00					280 00			320.00			00		ARE USED IN TETRAHEDRON
INC	55.00	8	8	8	55.00	8	8	8	8	8	8	8	8	8	8	•	8	8		8	1.000	
RASC	30.00	30.00			90.06	90.00	150.00	150.00	150.00	210.00	210,00	210.00	270.00	270.00	270.00	330.00	330.00	330.00	ENTS	8	OO . AREA =	
ARGP	8	8	8	8	8		8							8			8		'AL ELEME	8	720 = 5 } = 45.00 SPHERICAL AREA	IN FOUR AT A TI
ECC	000	000	000	000	000	000	000	000	0 00.	000	00	000	000	000	000	000	000	000	SATELLITE ORBITAL ELEMENTS	000	MIN) (DEG	
	-	7	က	•	ഹ	\$	_	∞ •	on.	2	=	12	5	7	ā	.	17	18	USER SATELLI	19	TOTAL TIME(MIN) = TIME INCREMENT(MIN) BEAMMIDTH ANGLE(DEG) FRACTION OF NAVSAT S	ALL SATELLITES, T

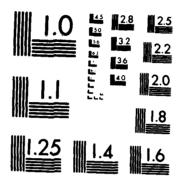
TABLE XXXV (Continued)

SATELLITES CHOSEN	16 4 7 14 2 9 12	18 4 7 14 2 9 12	16 4 7 14 2 9 12	4 7 12 14 16 2 9	4 7 12 14 16 2 9	16 4 12 14 2 9	16 4 12 14 2 9	16 4 12 14 2 9	2 4.9 14 12 16	2 4 9 14 12 16	2 4 9 14 12 16	2 4 9 14 12 16	2 4 9 14 12 16	4 9 12 14 16	4 9 12 14 16	4 9 12 14 16	4 9 12 14 16	4 9 12 14 16	4 9 11 14 16 12	4 9 11 14 16 12
GD0P	26.051	27.281	28.888	28.008	26.949	27.484	28.362	29.448	30.800	29.509	28.466	27.640	27.005	47.209	50.682	55,360	61.742	70.794	40.916	44.839
РООР	19.143	20.053	21.238	20.618	19.848	20, 133	20.769	21.556	22.535	21.597	20.839	20, 238	19.776	34.454	36.977	40.376	45.013	51,593	30,011	32,933
100P	17.668	18,497	19.583	18.956	18.229	18.708	19.315	3p.064	20.995	20, 109	19,383	18.825	18.389	32.274	34.661	37,876	42.260	48.477	27.812	30.577
MDOP	2.468	2.472	2.495	2.568	2.517	3,319	3.292	3.272	3, 103	3.038	2.986	2.944	2.912	2.377	2.368	2.429	2.512	2.635	2 436	2.411
НООР	3.279	3.334	3.421	3.310	3.283	4, 173	4 . 109	4.058	3.851	3.832	3,828	3.837	3.859	3.324	3,316	3.324	3,356	3.425	3, 173	3. 169
VDOP	18.861	19.774	20.960	20.351	19.574	19.696	20,358	21.171	22.204	21.254	20.484	19.871	19 396	34.293	36.828	40.239	44 888	51.479	29.843	32.780
ALT! NM)	19364.	19364	19364	19364.	19364.	19364	19364.	19364	19364	19364	19364.	19364	19364	19364	19364	19364	19364	19364	19364	19364
TIMEOMN	0	ĸ	10	15	20	25	30	35	04	45	50	58	60	65	70	75	80	85	06	S6

TABLE XXXY (Continued)

	AL I MA		ing i		<u> </u>		L COOR	2416	SAIELLIIES CHUSEN	5	USE
8	19364.	38.480	3.174	2.393	34.065	36.618	50.013	a	Ξ	14 12	16
105	19364.	41.238	3.190	2.383	38.552	41.361	56.542	9	Ξ	14 12	16
10	19364.	45.670	3.112	2.404	42.699	45.776	62.600	9 11	12	14	16
115	19384.	46.089	2.977	2.241	43.077	46.185	63.156	9 +	7	4	16
120	19364.	48.239	2.928	2.182	43.212	46.332	63, 355	14	=	12 4	9
125	19364	46.065	2.976	2.240	43.055	46 161	63.124	14 9	Ξ	12 4	16
130	19364.	45.676	3.111	2.403	42.705	45.782	62,608	14 9	=	12 4	16
135	19364.	41.260	3, 190	2.3830	38.573	41.383	58.572	14 9	12	16 4	=
140	19364	36 480	3, 174	2.393	34.065	36.618	50.013	14 9	12	16 4	=
145	19364.	32.789	3, 168	2.411	30,586	32.942	44.952	9 12	4	16 4	Ξ
150	19364.	29.857	3, 173	2.435	27.825	30.025	40.936	9 12	4	16 4	Ξ
155	19364	51 473	3.425	2.636	48.471	51.587	70.786	9 11	4	16 4	
160	19364.	44.895	3.357	2.513	42.267	45.021	61.752	9 11	4	16 4	
165	19364	40.251	3,324	2.429	37.888	40,388	55.378	9 11	4	16 4	
170	19364.	36.843	3 315	2.369	34 676	36,992	50.703	9 11	7	16 4	
175	19364	34.296	3.324	2.377	32.277	34.456	47.212	9 11	4	16 4	
180	19364.	19 395	3.860	2.912	18.388	19,775	27.003	2	4	16 4	=
185	19364	19.871	3.837	2.944	18.825	20.238	27.639	6	4	16 4	=
190	19364	20.484	3.827	2 985	19, 392	20,838	28 466	2	4	16 4	Ξ
195	19364	21.248	3.832	3.038	20, 104	21.582	29.502	2	4	16 4	Ξ





MICROCOPY RESOLUTION TEST CHART NATIONAL BUREAU OF STANDARDS-1963-A

TABLE XXXV (Continued)

-					±	:	1	=	=	:						16				
JSE	Ξ	=	=	=	8	8	Ξ	Ξ	Ξ	Ξ	=	Ξ	7	7	Ø	13	o	9	~	8
SATELLITES CHUSEN	*	8	8	7	4	4	7	7	8	8	8	8	8	7	7	Œ	8	N	Ξ	Ξ
2	9	5	16	16	16	16	5	9	16	16	16	16	16	6	16	7	16	16	9	9
3	7	Ξ	=	Ξ	13	13	5	13	13	13	13	13	13	13	=	8	13	13	13	13
Ā	57	Q	On .	a	=	=	OR .	a	on .	on -	a	Ø	Ø	æ	13	-	-	-	Ø	3
v)	8	4	4	4	•	9	4	4	4	4	=======================================	=	Ξ	Ξ	=	Ξ	Ξ	=	_	-
900	30.794	29.455	28.362	27.485	26.946	28.006	28.832	27.284	26.052	25. 127	37.843	41.298	45.630	51.130	55.956	23.463	23.893	24.496	33.382	32.478
Š	22.531	21.561	20.769	20.134	19.846	20.617	21.241	20.055	19.144	18.458	27.781	30.270	33.415	37.408	40.932	17.316	17.708	18.133	24.574	23.893
3	20.991	20.068	19.315	18.709	18.228	18.955	19.586	, 18.499	17.669	17.048	25.717	28.094	31.073	34.854	38.154	15.833	16.044	16.469	22.594	21.999
	3. 102	3.272	3.291	3.319	2.516	2.568	2.495	2.473	2.468	2.477	3.210	3.463	3.788	4.213	5. 130	2.103	2.953	3.034	2.189	2.271
Ì	3.851	4.058	4 . 109	4.173	3.282	3.310	3.421	3.334	3.279	3.249	3.822	4.043	4.334	4.721	5.626	2.961	3.719	3.773	2.882	2.834
3	22.199	21.176	20 358	19.697	19.572	20.350	20 963	19.776	18.861	18.170	27.497	29.999	33.133	37.110	40.543	17 061	17.311	17.737	24.405	23.712
ALT(NH)	19364.	19364.	19364	19364.	19364.	19364	19364.	19364.	19364.	19364	19364.	19364	19364	19364	19364	19364	19364.	19364	19364.	19364
TIME:MN ALTINA)	200	205	210	215	220	225	230	235	240	245	250	255	260	265	270	275	280	285	290	295

TABLE XXXVI Geosynchronous User, Antenna Bw $dth = 90^{\circ}$

	PER	12.00	12 00	12.00	12.00						12 00										24.00		
	ANOM	8	120.00	240.00	80.0	160.00	280.00	80.08	200.00	320.00	120.00	240.00	360.00	160.00	280.00	4 0 00	200 00	320.00	80.00		8		ARE USED IN TETRAHEDRON
•	INC	55,00	8	•	8	8	8	8	8	8	55 00	8	8	8	8	8	8	8			8	1.000	٠.
	RASC	30,00	30.00	30.00	90.06	90.06	90.00	150.00	150.00	150.00	210 00	210,00	210.00	270.00	270.00	270.00				ENTS	8	00 L AREA =	A TI
	ARGP	8		8							8					8			8	TAL ELEM	8	720 	TAKEN FOUR AT
	ECC	00	8	000	8	8	000	000	8	000	8	8	8	8	8	8	8	8	8	SATELLITE ORBITAL ELEMENTS	000	INCREMENT (MIN) TO STORY (MIN) TO ST	TES, TAK
		-	~	. m	•	- Wi	•		- 60	o n	2	Ξ	12	5	=	. 1	5	11	=	USER SATELL	6-	TOTAL TIME(MIN) = TIME INCREMENT(MIN) BEAMWIDTH ANGLE(DEG) FRACTION OF NAVSAT S	ALL SATELLITES. THE CALCULATIONS

TABLE XXVI (Continued)

	17	13	17	5	5	15	5	5	5	ā	ō	5	9							
	=	7	Ξ	=	=	Ξ	=	7	7	7	=	=	5							8
	5	13	13	5	13	5	13	13	13	5	5	13	7	8	18	18	18	8	5	7
	2	12	7	2	12	12	12	12	12	12	72	12	13	=	7	7	7	4	7	13
	Ξ	Ξ	=	=	Ξ	=	Ξ	Ξ	Ξ	Ξ	Ξ	Ξ	12	=	-	Ξ	13	13	5	2
	9	a	•	G	9	G	Œ	æ	3	G)	3	a	=	\$	6	9	12	12	2	Ξ
	7	7	7	2	7	7	7	7	7	7	7	7	o	7	7	7	=	Ξ	Ξ	7
	S	1O	V)	w	ហ	Ŋ	ß	20	ហ	Ŋ	N3	ហ	7	0	19	9	7	7	7	M
_	•	•	•	•	•	4	*	*	4	•	4	4	S	ΙΩ	S	ស	IO.	RJ	ស	•
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CHOSEN	a	~	8	~	~	8	~	~	~	~	~	~	6	5	5	9	5	5	5	6
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9002	7.975	8.045	1.125	8.046	B. 100	8.163	1.234	8.312	8.396	1.487	8.583	.684	8.862	10.030	10.097	10.177	10.391	10.267	10.15	10.043
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	6.246	6.301	6.364	6.317	6.350	6.391	6.439	6,494	6.555	6.622	693	6.769	6.899	7.749	7.805	7.871	8 . 103	8.013	7.928	7.849
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	4 95	5.001	5.051	4.983	5.028	5.078	5. 131	5.187	5.247	5 30	5.37	5.440	5.561	6.369	6 . 406	6.451	8.505	6.420	6.340	6 265
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TABLE XXVI (Continued)

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VDOP	7.534	7.470	7.404	7.483	7.580	7.483	7.404	7.471	7.533	7.602	7.677	7.757	7.842	7.627	7.558	7.498	6.585	6.491	6.411	6.334	
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TABLE XXVI (Continued)

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PDOP 6.555	6.484	6.439	6. 391	6.350	6.318	6.364	6.001	6.246	6. 199	6.639	6.620	6.607	6.601	6.600	6.606	6.619	6.638	999 . 9	6.701
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TABLE XXXVII High Altitude User, Antenna Bwdth = 21.4°

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TABLE XXXVII (Continued)

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TABLE XXXVII (Continued)

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TABLE XXXVII (Continued)

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PDOP	2.078	.517	520	. 565	534	513	.522	. 562	.605	1.864	2.134	4.894	5.384	5.772	7.976	8.315	9.350	9.673	10.517	11.476	
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GD0P	15.696	15.959	16.278	25.791	15.571	12 575	12.894	18.695	16.149	16.096	16.011	19.187	19.304	82.878	71.376	63.830	58.665	55.125	52.750	
P00P	11.964	12.142	12.362	19.348	11,776	999 6	9.879	12.472	12.113	12.060	11.985	14.268	14.347	60.443	52.046	46,536	42.784	40.178	38.438	
T00P	10.160	10.357	10.590	17.054	10.187	8.043	8.286	11,098	10.680	10.660	10.618	12.829	12.915	56.705	48.844	43.688	40.181	37.745	36.126	
MDOP	1.906	1.982	2.112	2.908	2.600	2.213	2.263	1.926	2.017	1.981	1.987	2.501	2.489	4.950	3.589	2.785	2.386	2.335	2.510	
HDOP	2.525	2.579	2.685	3.589	3.024	2.744	2.801	2.645	2.710	2.674	2.666	3.077	3.087	5.349	4.118	3.438	3.128	3.080	3.214	
VDOP	11.695	11,865	12.067	19.013	11.381	9.269	9.473	12.188	11.808	11.780	11.685	13.932	14.011	60.206	51.883	46.409	42.849	40.058	38,304	
ALT (NM)	12982.	13395.	13796.	14179.	14551.	14909.	15255.	15588.	159 10.	16220.	16519.	16808	17085.	17352.	17609	17855.	18082.	18320.	18538.	
TIME MIN ALT (NM)	<u>6</u>	105	110	1.00	120	125	130	135	140	145	150	155	160	165	170	175	180	185	190	

TABLE XXXVIII (Continued)

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<u>.</u>	78	99	80	67	8	62	7	77	30	7.1	0	11	37	38	35	80	30	30	89	87
	32.578	34.568	33.380	32.367	31.600	28.362	473.314	78.077	96.730	97.471	88.310	78.117	71.437	67.038	65.935	59.880	46.030	42.830	40.268	38.187
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	23.763	25.201	24.333	23.594	23.033	20.878	056	57.097	70.756	71.273	84.537	57.036	52.113	48.862	48.301	43.896	33.618	31.292	29.430	27.918
ī.	23	25	24	23	23	20	345.056	57	70	7	8	57	52	48	40	43	33	31	29	27.
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	22.286	23.958	22.849	22.157	21.634	19. 196	323.979	53.253	65.957	66.489	60.280	53.378	48.862	45.897	44.882	40.728	31.441	29.244	27.485	26.055
.	9	89	96	-	37	8	22	SD SD	ភូ	72	23	28	83	90	82	26	S.	7	22	93
	3.516	3.788	3.896	4.061	4.237	2.606	45.557	7.095	7.495	7.072	5.653	4.228	3.293	2.730	2.682	2.356	2.785	2.742	2.722	2.703
ADQH.	4.085	4.302	4.441	4.614	4.799	3.433	46.747	7.345	7.732	7.470	5.977	4.646	3.816	3.355	3.435	3.187	3.458	3.483	3.546	3.635
D.	60	31	25	38	28	94	75	23	32	-	8	41	73	47	79	8	9	4	9	0
	23.409	24.831	23.925	23.138	22.528	20.594	341.875	56.623	70.332	70.881	64.260	56.847	51.973	48.747	48.179	43.780	33.440	31.087	29.216	27.880
ALT (NM)	18945.	19136.	19318.	19491.	19655.	19811.	19958.	20097.	20228	20351.	20465.	20572.	20671.	20762.	20845.	20920.	20987.	21047.	21099.	21144.
A I ME (MA)	200	205	210	215	220	225	230	235	240	245	250	255	260	265	270	275	280	285	290	295

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This investigation determined the effect of changes in eccentricity to the orbits of the proposed Global Positioning System (GPS) 18-satellite baseline constellation by analyzing the geometric performance obtained. The effect of satellite losses upon global coverage was also examined with an emphasis on determining which combination of remaining satellites provided the best and worst cases. The potential of GPS for navigation of the space-based user was explored by analyzing the geometric performance obtained for a variety of user trajectories and GPS antenna beamwidths. A computer program which analyzes the many aspects of the geometric performance of pseudoranging navigation satellite systems was used for the analysis.

The results of this analysis indicate that a simple modification to the baseline constellation could reduce outages on a global basis by nearly 50%. The modification consists of changing the shape of the GPS circular satellite orbits to slightly elliptical ones, resulting in more favorable satellite geometry and fewer outages to the user on a global average. Further consideration to determine its feasibility was recommended. The degradation of coverage due to satellite losses was found to be largely dependent on the combination of the remaining satellites, and suggests that the rephasing of the remaining satellites could significantly improve the degraded performance. potential for conventional use of GPS for navigation in space was shown to exist for the low altitude user / but will be very limited for the higher altitude user due to the present GPS antenna design. SIncreasing the designed antenna beamwidth was shown to significantly improve performance for the high altitude user. It was recommended that this modification be considered in future GPS antenna design, if conventional GPS navigation is to be desired for the high altitude space user.

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