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MARINE SEISMIC SYSTEM (MSS) ADVANCED OPERATIONS EVALUATION, PHASE V MSS DEPLOYMENT

30 MARCH 1984

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REPORT DOCUMENT	ATION PAGE	READ INSTRUCTIONS BEFORE COMPLETING FORM
REPORT NUMBER	2. GOVT ACCESSION NO.	3. RECIPIENT'S CATALOG NUMBER
MSSA04-SYS-R003	00 0000 000	
TITLE (and Subtitio)	AU-747243	5. TYPE OF REPORT & PERIOD COVERED
Marino Solemia Suston		
Operations Evaluation		Technical Report, Mar.8
MSS Deployment	on, Phase v	6. PERFORMING ORG. REPORT NUMBER
AUTHOR(2)		B CONTRACT ON GRANT NUMBERIAL
Robert L. Wallersted	lt	100014-33-C-0034
PERFORMING ORGANIZATION NAME AND	ADDRESS	10. PROGRAM EL EMENT PROJECT TASK
Global Marine Developme	ent Inc.	AREA & WORK UNIT NUMBERS
2302 Martin Street		ARPA Order 4152
Irvine, CA 92715		
CONTROLLING OFFICE NAME AND ADDR		12. REPORT DATE
Advanced Research Proje	ects Agency	March 30, 1984
1400 Wilson Boulevard	ees ngener	13. NUMBER OF PAGES
Arlington, VA 22209		Approx. 45 plus Appendi
MONITORING AGENCY NAME & ADDRESS	(If different from Controlling Office)	15. SECURITY CLASS. (of this report)
Naval Ocean Research an	d Development Agend	¢y
STL Station, MS 39529	l de la constante de	Unclassified
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SECTION 1.0 - SUMMARY

This report provides information and background concerning the potential application of the Marine Seismic System's (MSS) seismic and deployment technology to future Department of Defense/U.S. Navy operations. The MSS '81, '82 and '83 operations have verified the capability to 1) effectively obtain short and medium period seismic data from within a deep ocean emplaced borehole and 2) deploy large sensitive instrument packages into emplaced reentry boreholes at water depths of 20,000 feet. Technical considerations involved with the reentry borehole emplacement and borehole package deployment are discussed. Potential single development site tests and multiple operational stations considerations are also reviewed. ROM costs for these possible projected test demonstrations are provided.



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SECTION 2.0 - CONCLUSIONS

Based upon the technology developed jointly by the National Science Foundation's (NSF) Deep Sea Drilling Program (DSDP) and the Defense Advanced Research Projects Agency's (DARPA) MSS Program, a variety of deepwater borehole large instrument applications could now be scheduled. An 8-inch, 3,300 pound seismometer has been successfully deployed into a borehole at a depth of 19,000 feet. Potentially, instrument packages measuring up to 24 inches in diameter and weighing 10,000 to 20,000 pounds can now be deployed into encased reentry boreholes. These reentry borehole can be drilled and emplaced 1,000 to 2,000 feet below the seabed in water depths of 20,000 feet. The borehole instrument packages would be initially deployed utilizing a drillstring reentry technique. Associated seabed positioned or subsea buoy type recording packages can also be deployed at these water depths. Both borehole and recording instrument packages are also recoverable, if desired.

Future programs could also consider deployment of new instruments into existing boreholes without the use of a dynamic positioned drillship. This would require development of either a cable guideline or cable guided "fly-in" capability. The basic technology for either approach is available but has not been specifically demonstrated for deepwater applications. Development would take 1 to 2 years for the cable guideline and 2 to 3 years for a cable guided fly-in deployment technique.

A shallow water test deployment of an existing 8 inch diameter seismometer at depths of about 2,000 feet would require approximately 20 at-sea days at a cost of approximately \$2 million. A similar deepwater test deployment at depths of about 15,000 feet would require approximately 30 at-sea days to accomplish and would cost approximately \$6 million. These estimates exclude any specialized instrumentation development, data evaluation or management costs.

Installation of an 8 to 12 station, multiple deepwater site, operational deployment program could be accomplished within a year. Such an undertaking would be an extensive program employing sophisticated communications

elements. Typical costs associated with only the deployment would be about \$37 million including ship charter operations, deployment equipment, planning and engineering.



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SECTION 3.0 - PROGRAM OVERVIEW

MSS Program focused on developing a sensitive seismic Borehole The Instrumentation Package (BIP) plus the associated support equipment which can be deployed into the basalt layer of the ocean floor in water depths to 20,000 feet. Deep boreholes were drilled and cased through the sediment and into the basalt layer by utilizing standard deep ocean drilling techniques and equipment which have been developed during the NSF-sponsored DSDP. The dynamically positioned drillship Glomar Challenger, operated by Global Marine Drilling Company (GMDC), was the vessel utilized for the program. Deployment was accomplished by lowering to the ocean floor a BIP mounted within a reentry sub at the lower end of a drillstring. The reentry sub incorporated a sonar controlled reentry tool which guided the BIP into a reentry cone which had previously been installed over the borehole as shown in Figure 3-1. The standard DSDP procedures were modified to accommodate the MSS configurations.

The major operational elements of the overall MSS Deployment Program are summarized as follows:

• <u>MSS '81</u>

The MSS equipment was mobilized in San Juan, Puerto Rico, and was installed on the <u>Glomar Challenger</u>, which departed for the test site on 14 March 1981. The reentry site was located in the mid-Atlantic at a depth of 14,712 feet. Within 75 hours, the <u>Glomar Challenger</u> emplanted and recovered a BIP using an existing DSDP borehole. The at-sea-test demonstration was successfully completed on 30 March 1981. Feasibility of the BIP deployment concept (using the drillstring reentry technique) and of the basic capabilities of the seismic sensor when deployed in the deep ocean borehole was successfully demonstrated.

 <u>MSS '82</u> In August-September 1982, the <u>Glomar Challenger</u> crew attempted to drill a reentry borehole and to emplace a Configuration I BIP at a Northwest Pacific site. A 30-day special DARPA operation leg

[&]quot;Phase V Marine Seismic System (MSS) Deployment, Final Report," Report No. MSSA04-SYS-R001, Rev. 0, December 1983.



had been scheduled to deploy the BIP and the associated Installation, Recovery and Reinstallation (IRR) mooring equipment in 18,100 feet water depth. Due to adverse weather conditions and equipment malfunctions, drilling of the reentry borehole could not be successfully accomplished within the time period allotted. Deployment of a smaller, through-the-pipe seismometer with its 60-day recording package was achieved.

o <u>MSS '83</u>

The MSS '83 operation was conducted at a new DARPA site in the South Pacific in January 1983. The <u>Glomar Challenger</u> transited to the site and emplanted a cased reentry borehole in approximately 18,500 feet of water. The BIP was deployed, and 5 days of seismic testing was accomplished. Subsequently, the Bottom Processing Package (BPP) and its associated IRR mooring system were then successfully deployed. During March 1983, the RV <u>Melville</u> returned to the DARPA site and successfully recovered the BPP and redeployed a dummy BPP.

Subsequent evaluations of the MSS data have indicated that 1) the noise level in the boreholes is lower, by approximately 30 dB, than corresponding Ocean Bottom Seismometer (OBS) readings, and 2) the shock levels for drillstring reentry were considerably below the defined 10G requirements. A broad band of seismic signals, down to 0.1 cps, can be accurately recorded. The seismometers were also able to detect ship noises over a very extended range.

Based upon this information, sensitive borehole instruments up to probably 24 inches in diameter can be confidently deployed and recovered from deepwater emplaced boreholes. The borehole sites can be potentially emplaced in most ocean areas, but particular attention must be directed to specific weather, current and seabed geologic conditions. The associated deepwater recording packages and mooring systems can also be installed, as required.

There are of course many factors to be specifically considered. The following potential problems need to be fully evaluated for each site:

- Drill String Failure
- Drill Out of Difficult Formations

- Drill String Dynamics
- Cable Overtension
- Cable Entanglement
- Reentry Shock Loadings
- Reentry Positioning
- Package Release

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SECTION 4.0 - DEEP OCEAN SEISMOMETERS

4.1 GENERAL

A variety of seismometers could be potentially applied to deep ocean borehole applications. However, for this study, data is only presented for the most applicable units based upon seismic capabilities, configuration limitations, associated software and experience.

4.2 GEOTECH-TELED YNE SE IS MOMETERS

A range of potential seismometers produced by Geotech-Teledyne can be considered for any future MSS type application. Table 4.1 summarizes the sensors which all have been under development and/or are in use for various U.S. seismic programs.

The seismic equipment consists primarily of a Borehole Instrumentation Package, (BIP), and Shipboard Test Console (STC), Electromechanical (EM) cable and a Bottom Processor Package (BPP). Figure 4-1 is a simplified block diagram showing only the BIP, EM cable, and STC.

The primary function is to collect seismic data in an ocean bottom Thus, the BIP consists of a primary set of seismic borehole. sensors. Secondary sensors to aid in the installation, operation and maintenance of the BIP include accelerometers to record shock levels encountered during shipboard handling and deployment, and temperature, pressure, and state of health sensors to aid in operational analysis and maintenance. Sensor data is preconditioned and digitized by the appropriate analog to digital converter, all data merged into a serial digital data stream, frequency shift key (FSK) encoded and transmitted over the EM cable to the STC. The STC demultiplexes the data and displays via analog strip chart recorders, light emitting diode (IED) status panels and/or cathode ray tube (CRT) displays under operator control.

TABLE 4.1

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POTENTIAL GEOTECH SEISHDNETERS PACIAGE CONFIGURATIONS

				r		• · · · · · · · · · · · · · · · · · · ·
MULTIPLE S-500 VERTICALS	3.75 in.	2 packages 1-14 ft signal processor	Up to 6 verticals	500 V/G typical acceleration 450V per M/sec typical velocity	1.0 Hz to 160 Hz	Vertical only Vertical only Disposable sensor packaye Through the drill striny deployment deployment
NULTIPLE S-750 VERTICALS	4.25 in.	<pre>1-12 ft, 1-6 ft, or 1-8 ft 1,000 ft suspension Max. 1-6 ft sensor separated by up to 1,000 ft Max.</pre>	Up to 6 verticals only	200V per M/sec ² typical acceleration 3 x 10 ⁴ V per M/sec typical velocity	.01 Hz to 100 Hz	Vertical only Single or dual packages Deployed through drill string
44000	4.25 in.	2-12 ft packages separated by up to 1,000 ft Max.	3 primary only	2 x 10 ⁴ v per M/sec ²	0 to 25 Hz	2-12 ft packages 1,000 ft separation max Deployed through drill string
531000/44000	8 in.	33 ft	Up to 6 3 primary 3 secondary or 3 primary 2 vertical backup	Primary 2 x 10 ⁴ V per M/mec ² Secondary 200V per M/mec ²	Primary 0 to 25 Hz Secondary .01 Hz to 100 Hz	
531000/36000	8 in.	33 ft	Up to 6 3 primary 3 secondary or 3 primary 2 vertical backup	Primary 1 x 10 ⁶ per N/sec ² Secondary 2000 per M/sec ²	Primary 0 to 20 Hz Secondary .01 Hz to 100 Hz	Built in backup sensors. Single deployment package. Technology and hardware exist. Reentry of hole necessary.
	Diameter	Length	Number of Sensors	Res ponse	Bandwi dt h	C comment s





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In parallel with the real time display, all data is recorded via mass storage devices (FM magnetic tape). The BPP (not shown in the diagram) provides long term data collection and storage in an unattended operating mode. The BPP is connected to the EM cable in place of the STC for final deployment. The same basic pressure vessel packages could be provided for the 531000/44000 unit.

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The 44000 sensor could also be packaged within an approximate 4.25 OD pressure vessel configuration. Two separate 12 foot long packages would be involved.

4.3 OCEAN SUBBOTTOM SEISMOMETER $\frac{1}{2}$

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The Ocean Subbottom Seismometer (OSS) system developed by the Hawaii Institute of Geophysics (HIG) consists of a borehole package, recording package and recovery system. The borehole package is a 3-7/8 inches diameter by 8.2 foot length pressurized container enclosing a 3 geophone seismometer, auxiliary sensors, signal multiplex, A/D converter, electronics, telemetry and Dower conditioning electronics. The present configuration has three short period geophones, two bubble tilt meters, plus temperature sensors which are multiplexed into 16 data channels. Three 4.5 Hz Geopack geophones are presently used, but other configurations are possible. The recording package consists of two aluminum tubes, each 6 feet long. One tube contains D cell batteries to supply approximate 60 days of power, and the other tube contains electronics including 5 cassette tape recorders. The recovery subsystem consists of a polypropylene rope attached to a releasable anchor.

The system reportedly has a ± 0.6 micro V to 2.5 V capability, covering a dynamic range of 138 dB. A variable AGC system is used to accommodate the 40 dB dynamic range of analog tape recorders. Four tracks of data can be recorded.

I/ Isolated Sensor Ocean Bottom Seismometer, D. Byrne, et al., Marine Geophysical Researcher, 5 (1983) 437-449; and the Ocean Subbottom Seaismometer, F. Duennebier and G Blackenton, CRC Handbook of Geophysical Exploration at Sea.

SECTION 5.0 - DEPLOYMENT SYSTEM CAPABILITIES

5.1 INTRODUCTION

An alternative to (the through the drillstring) instrument deployment has been recently developed. The original approach involves drilling an uncased borehole into the sediment/basalt formation and then, without recovery, deploying the seismometer with its attached EM cable through the drillstring's internal bore. This requires subsequent stripping out the EM cable from the drillstring before deployment of a recording capability. In this approach, the seismometer package is limited by the pipe ID.

The recently developed approach requires drilling out and emplacing an encased borehole followed by deployment of the seismometer and its attached EM calle carried down at the bottom end of the drillstring. Several successive reentries are generally required. Upon release of the seismometer and EM cable, the recording package can then be installed. Table 5.1 summarizes the general considerations of both concepts.

5.2 DRILLSTRING CHARACTERISTICS

Within the foreseeable near future, only a small range of drillstring configurations can be practically considered for deep ocean (20,000 feet) operations. The size range is between 5 to 6-5/8 inches (nominal) based upon the available American Petroleum Institute (API) drill pipe sections. Smaller drillpipe sections cannot support the necessary weight or drilling function. Larger sections would need to be specially made up from casing sections, would require new joints, and probably would require extensive shipboard handling capabilities.

A variety of considerations are involved with selection of a specific drillstring configuration. The drilling is accomplished by the

TABLE 5.1

DEPLOYMENT CONCEPT CONSIDERATIONS

THROUGH THE DRILLSTRING:

- Package diameter constrained by drillstring ID
- Only one drillstring trip required
- Minimal extra handling equipment
- EM cable must be stripped out of drillstring
- Recovery of instruments may not be possible
- Possible limit to penetration depth in basalt

DRILLSTRING REENTRY:

States and

- Multiple drillstring trips and reentries required
- No practical package limits up to about 24 inches dia
- Special subsea and shipboard handling equipment
- Recovery of borehole package possible
- Possible redeployment of new instrument into borehole
- Cased or uncased borehole can be provided

ocean drilling and emplacement applications, the system's resonance and damping characteristics become of critical importance under even moderate weather conditions. Table 5.2 defines basic capabilities of four different drillstrings at three total depths.

Most existing DP drillships can accommodate 4, 5 or 5-1/2 inch pipe strings. A 6-5/8 inch drillstring will most probably require some modification to the drillship's pipe racker, derrick pipe handling, and power drilling subsystems. Basically, the drillships will all have sufficient derrick load capabilities.

The previous MSS deployment operations have indicated the need for drillstring heave compensation for operations at the deepest water depth. Where weather conditions are severe or allotted time is short, heave compensations of some type are definitely required. T^{+} ? heave compensation can be active or passive, with an active system being more desirable.

Of particular importance is the need for accurate pipe string load measurements. The equipment for such measurements must be able to record both static and dynamic load indication. Quite often it can be expected that operations will be near the limits of the pipe, particularly when all combined loadings are taken into account. Such data should be correlated with computerized load evaluation taking into account both axial and lateral dynamic effects.

5.3 REENTRY BOREHOLES

Over the past 13 years the DSDP has developed a remarkably successful reentry borehole technology. This technology has been demonstrated in over 50 sites under varying depths and geologic conditions. The basic reentry borehole guided cone assembly is shown in Figure 5-1.

This particular assembly is designed to provide a 16 inch surface conductor casing plus an interface with the 11-3/4 inch casing. The reentry cone and surface conductor are basically washed down into the top seabed sediment. Subsequently, the lower portions of the

		T	· · · · · · · · · · · · · · · · · · ·	1
DRILL STRING	4 INCH	5 INCH	5-1/2 INCH	6-5/8 INCH
ID (inches)	3.34	4.25**	4.50**	5.00
Joint OD (inches)	4.5	7.5	7.5	8
I (inch ⁴)	6.5	14.3	21.6	32.4
Dry Wt Per Ft (H/Ft)	15.6	19.50	24.7	25.2
*DS Load Capacity (Lbs)	514,000	712,000	895,000	881,000
*DS Torque Capacity (Ft/Lbs)	36,320	64,210	88,240	110,090
Drill Power Capacity	86	151	192	240
(120 RPM) Ft/Lbs				
Mud Velocity	18.5	11.3	11.3	8.1
(500 GPM) Ft/Sec				
BHA Weight (Lbs)	40,000	50,000	60,000	90,000
Topside DS Weight (Lbs)	25,000	30,000	35,000	40,000
-				
······································				
TYPICAL HOOK LOADS				
2,000 Feet (Lbs)	98,000	115,000	135,000	175,000
10,000 Feet (Lbs)	208,000	250,000	305,000	350,000
20,000 Feet (Lbs)	341,000	425,000	525,000	575,000

TABLE 5.2 MSS DRILL STRING COMPARISON

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* High strength S-135 drillstring ** Special tool joint

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borehole are successively drilled out and encased. Typically, the solid basalt regions are not cased. These latter operations usually employ drillstring trips and reentries.

This depicted borehole arrangement can accommodate an instrument with a diameter up to 9 inches. Greater diameter packages would require larger entry borehole diameters plus associated casing strings. A 24 inch package would probably need an approximate 36 inch surface conductor.

Drilling requirements would obviously be increased. A large "Big Hole" land drilling technology exists with capabilities up to 96 inch diameters and can be transferred with some restrictions to ocean riserless drilling.

5.4 SUBSEA DEPLOYMENT EQUIPMENT

The external drillstring reentry deployment requires the use of a comprehensive Bottom Hole Assembly (BHA) which performs the following functions:

- Supports the seismometer or instrument package during initial deployment to the seabed
- Guides the reentry sonar tool during reentry
- Guides the drillstring into the reentry cone using a stinger
- Centers over and releases the seismometer into the borehole
- Guides the EM cable during final lowering
- Interconnects with the drillstring through appropriate bumper subs and transition elements

The BHA measures approximately 150 feet in length and can weigh 50,000 to 75,000 pounds. The custom lower reentry subassembly portion must be constructed to support and release instrument packages and to interface with the borehole reentry cone. The upper elements are generally standardized oil field components.

5.5 SHIPBOARD HANDLING EQUIPMENT

The deployment of sensitive instruments does not really require extensive equipment. The most expensive single element is the EM winch. This winch must be capable of handling 20,000 to 40,000 feet of EM cable. Along with the EM cable there is the additional handling of the specialized mooring line, if required.

For the external drillstring deployment, an A-Frame, an associated heave compensator, idler wheel, cable tension and cable payment measurement devices are required. All the above equipment can also be designed to handle the deployment of the subsea recording package plus associated mooring equipment. Figures 5-2 and 5-3 show a portion of a typical installation on the <u>Glomar Challenger</u>.

A through the pipe deployment requires an additional cable stripping equipment which is used to strip off the drillpipe from around the EM cable during recovery of the drillstring.

5.6 RECOVERY/REDEPLOYMENT CONSIDERATIONS $\frac{2}{}$

The reentry borehole concept affords the advantage of recovery and subsequent redeployment of another instrument package into the borehole. This capability could potentially be accomplished without the use of a dynamic positioned drillship. What would be required is the development of either a guided line reentry system or a fly-in reentry system. The deep ocean guided cable capability could possibly be available within 1 to 2 years. Development of the fly-in capability would probably take 2 to 3 years.

The guided cable reentry system is certainly the easiest to develop but has certain failure modes associated with entanglement which may limit its practical utility. The fly-in approach is in the long run more promising by having fewer operational constraints. Both approaches require accurate bottom positioning acoustic equipment.

^{2/} Marine Seismic System (MSS) Deployment Phase III," Report No. MSSA01-001, Rev 0, March, 1982.



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Supervised Street

FIGURE 5-2 A-FRAME 5-8



FIGURE 5-3 EN WINCH

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SECTION 6.0 - DEPLOYMENT DRILLSHIPS

6.1 GLOMAR CHALLENGER

As noted earlier, all of the deep ocean MSS technology development was achieved on the DSDP vessel <u>Glomar Challenger</u>. Figure 6-1 depicts the <u>Glomar Challenger</u> in service. Although relatively small in size compared to newer dynamic positioned drillships, it conducted very successful operations throughout the world for over 14 years. The major attribute of the <u>Glomar Challenger</u> as compared to other vessels is its direct experience in deep ocean riserless drilling/ coring and reentry borehole operations. The <u>Glomar Challenger</u> was removed from active service in November 1983, but today still retains the basic capability to perform the deep ocean deployments desired in this report.

In early 1984 attempts were made to set-up a special deep ocean coring program for the USGS and to utilize the <u>Glomar Challenger</u>. The ship was offered to the U.S. Government by Global Marine, Inc. to be used for oil reservoir surveys and specialized DOD type operations. Apparently, this USGS program will not be established.

The probable outcome for the <u>Glomar Challenger</u> is major conversion for another use or scrappage.

6.2 ALTERNATE DRILLSHIPS

A variety of alternate dynamic positioned drillships could be considered for future MSS type operations. Both drillships and semisubmersibles could be potentially utilized for the type of deployment operations herein considered. Tables 6.1 and 6.2 are a partial list of U.S. owned and foreign built vessels to be considered.

In fact, almost all the vessels listed have more extensive equipment and basic capabilities than the <u>Glomar Challenger</u>. Refer to





TABLE 6.1 U.S. FLAG LP DRILLING SHIP

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Vesser, Ame	OWNER	DI MENS IONS (FEET)	DP 8 YSTEM	PROPILLS ICM/THRUETER (HP)	MATER DEPTH/ Drilling Depth (Feet)	DERUCK CAPACITY
SEDC0 472	SEDCO	470 × 70 × 32	N SK TIBMA SNOH	9,000/9,600	6, 000/25, 000	1.000.000 185
GLOMAR PACIFIC	G.CB.M. MRINE	452 x 72 x 35	DEL CO	9,600/8,375	2.000/25.000	2.000/25.000 184
GLOPPR ATLANTIC	GLOBAL MARINE	452 x 72 x 35	0071201	9, 600/8, 375	2.000/25.000	2.000/25.000 tas
GLOMR CHALLENGER	GLOBAL MARINE	400 x 65 x 26.75	DELCO	4, 500/3, 400	25, 000/25, 000	L. 000. 000 LBS
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and lassen	ANNE R	di Mens Iong (feet)	WELLSK 9 do	PROPULSION/THRUSTER (HP)	WATER DEPTH/ DRILLING DEPTH / SECOND	LIERRICK
SE000 445	SEDCO	445 v 70 v 333				
SEDCO/BP471	OVERSEAS DRILLING	470 × 70 × 32	HONE WELL AS N	9,000/9,000	3, 000/20, 000	1,000,000
	COMPANY			000 % / 000 %	6, 000/25, 000	1,000,000
DISCOVERER SEVEN	SONAT OF PSHORE	534 x 80 x 32	HONRYARL, AGE	16 MO 75 MO		
SEAS	DRILLING, INC.			nn 'et/nn int	1e, 000/18, 000	1, 300, 000
DISCOVERER 534	SONAT OF PS HORE	534 × 80 × 32	BONE WELL ASK	16.000.75.000		
	DRILLING, INC.	_			000 '07/000 'c	
BEN OCEAN LANCER	OE CO/BP	450 x 77 x 41	HONE WELL AS I	9 760		
SEDCO 709 (SEMI)	MRINE DRILLING	295 x 245 x 113	HONEVNELT. ASK	000 00	s, uuu/20, 000	1
(IW2S) 011 00025	SEIPEX INC.	295 x 249		24,000	e, 000/25, 000	1,100,000
HENRY GOODRICH (SENI)	SUNAT	316 x 246		100 ° 17	5, 000/25, 000	ı
(IMas)	(DE(T)/BNDC	360 - 731		1	10,000/30,000	1
			1	I	1, 500/25, 000	1,400,000

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Appendix A for certain important data of these vessels. The modifications that would be required for a MSS type deployment are really quite minimal.

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The charter vessel cost of the listed drillships will vary considerably depending on ship age, oil field economic conditions, season, length of charter, potential site hazards, etc. A typical projected short-term charter rate for an older vessel could be between \$30,000 to \$60,000 per day, while rates for the newer vessels could be in the \$70,000 to \$100,000 per day range. Additional considerations are fuel, supplies, mobilization, field office support and demobilization cost factors.

SECTION 7.0 - PROJECTED DEVELOPMENT TESTS

7.1 GENERAL

As noted earlier, several new applications of MSS technology are being considered. It is probable that single site development testing would be initially required in order to verify the sensor specific capabilities and to establish associated data hardware and software requirements. Deployment of instruments measuring up to 8 inches in diameter have been demonstrated. Borehole instruments up to 24-inch diameters can be potentially considered. Both shallow depths (to 2,000 feet) and deepwater sites may be programmed. The deepwater test can be a more expensive undertaking (by at least a factor of 2 to 3).

7.2 SHALLOW WATER TEST

A shallow water test of a borehole emplaced seismic system is currently under consideration by the U.S. Navy. This would be a specific test to correlate ASW parameters. Detailed seismic characteristics and instrumentation requirements have not yet been defined. A shallow water test can be easily accomplished at a number of U.S. offshore sites. A dynamically positioned drillship, although desirable, is not required for water depths approaching 2,000 feet. For shallow depths, however, most drillships carry adequate anchoring/mooring gear in order to maintain position over the site for short good weather periods. A high strength drill string would not be mandatory. The site should be at least 10 miles offshore to reduce shore and surf noise.

Either a reentry borehole or a through the pipe deployment can be considered, but a permanent test station site would require a reentry encased borehole. As noted in Section 4.0, there are many involved considerations with either approach, and the decision rests upon the projected use of the site and the size of instruments to be used. A major consideration for even a relatively inexpensive test is the data recording capability. The basic requirements are established by the data format, range, sensitivity level, number of tracks and time period objectives. Fortunately, many recording packages which can be adapted to this type of application are available. The basic problem is deciding where to install the recording package, particularly for extended periods of time. Table 7.1 outlines some of the options. All of these options will probably fall within the same ge gral cost range, considering all factors, except for the possible hard line tieup with a nearby (up to 5 miles away) existing platform or structure. Although each recording option has its specific concern, all can be quite readily accomplished using basically only the deployment vessel.

There are four offshore towers on the edge of the continental shelf which could be potentially used as instrument platforms. These towers form part of the Hatteras East Coast Tracking Range (HECTOR) operated by the DTNSROC Command.

The project required to provide the necessary subsea equipment, to deploy that equipment and to record the data is not really extensive. The major cost elements, as summarized on Table 7.2, are for a permanent 1,000 foot deep emplaced reentry borehole located in 2,000 foot water depth. A 30-day in situ recording capability would be provided.

The general scenario would be to first define the specific equipment requirements and to select the borehole package and recording package configurations as well as the EM cable. Pressure vessel packaging of the various subsea components would then be undertaken. A deployment engineering and planning effort would be conducted. An appropriate standard drillship and mobilization base would be selected. Procurement of any long lead items (i.e., EM cable, reentry cone, reentry sonar, special drill string, fixtures, etc.) would be initiated. Refurbishment of existing MSS equipment would also be accomplished.

	REMARKS	1				1			Susceptible to Damaye	or Theft		Emergency release	required	Noise on ship	Noise on Platform	Site near platform	Distance from Shore	
	DATA FORMAT	Tape				Tape			Tape			Real-Time	and/or Tape		Real-Time	and/or tape	Real-Time	and/or tape
SN	AVAILABLE UNITS	91H	OBS		448	• DIH	0BS #	8PP *	* 91H	4 SBD	8PP *	Many	_		Many		Many	
CRACE INSTALLATION OPTIO	RECOVERY FUNCTIONS	Re ¹ ease Transponder	will float	Package Riser or	Grapnel Line Lift	Release Transponder	Riser or Graphel	Line Lift	Pickup Buoy			ž			¥		N.	
ALLON MATER TEST RECORDING PA	DEPLOYNENT FUNCTIONS	Lower Package to Seabed	Controlled Freefall			Lower Package from Ship			Deploy over side			Cable terminated at Ship			Deploy Cable to Platform		Deploy Cable to Shore	
R	MODRING/RETRIEVAL SYSTEM	Possibly Riser	Line			Anchor Cable	Possibly Riser	Line	Anchor Line			Anchor or DP			Ŷ		 Ŷ	
	PRESSURE VESSEL	Moderate Wall				Light Wall			Light Wall			Ň			2		Ŷ	
	TYPE	Sea bed				Subsur face	Buoy		Surface Buoy			Standby Ship			Platform		Shore Station	

*Could be configured surface or subsurface for buoy installation.

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TABLE 7.2

SHALLOW WATER (2,000 FT) TEST COST PROJECTION*

(Commercial DP Drillship)

Borehole Package Procurement & Integration	\$300,000
Recording Package Procurement & Integration	200,000
EM Cable/Winch Procure	60,000
Deployment Engineering and Planning	100,000
Deployment Equipment Refurbishment	90,000
Ship Charter (30 Days)	800,000
Test Equipment (Shipboard)	60,000
Mobilization and Conversion	80,000
Demobilization	40,000
Recovery Vessel Charter (15 Days)	60,000
Operations Support	120,000
Miscellaneous and Contingency	190,000
\$2	,100,000

*Does not include Instrumentation Development, Data Evaluation or Management Costs.

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At the selected mobilization port, all of the elements would be received and assembled. All the mechanical and electrical interfaces would be checked out. A dockside test would be conducted simulating to the greatest extent possible the at-sea operations.

The ship would then proceed to the site where a deepwater moor would be installed. A pilot core would be taken preparatory for the initial reentry cone/conductory casing installation. The borehole would then be drilled out to depth and encased as directed. Several reentries may be required for a deeply drilled borehole emplacement. The borehole package would be deployed at the end of the drillstring and after reentry, released and lowered into the borehole. Possibly 4 to 5 days of real time recording may be performed. The recording package or hard line interconnection would then be deployed with associated recovery equipment.

The drilling vessel would then return for demobilization. Subsequently, a small workboat type vessel would be chartered to recover the recording package and/or borehole package, as desired.

The overall integration and deployment would take 9 months to one year, assuming the borehole instrument could be provided within the initial 6 months. The drill ship charter is estimated at about 30 days necessary to cover mobilization, transit, on-site operations (estimated at 10 days) and demobilization.

7.3 DEEPWATER TEST

A deepwater test can be accomplished at a number of U.S. offshore sites. A dynamically positioned drillship is required for water depths over 2,000 feet. The site location should probably be at least 10 miles offshore to reduce shore and surf noise. At these depths, a high strength drill string is definitely required. Section 5.0 provides data on drillstring capabilities as a function of depth.

Either a reentry borehole or a through the pipe deployment can be considered. As noted in Section 4.0, there are many involved
considerations with either approach. The decision rests upon the projected use of the site and the size of the selected instruments. A permanent, reusable test station site would require a reentry encased borehole.

Of prime importance are the depth of the site, seabed geologic conditions, and environmental factors. For deepwater sites the drillstring is probably the limiting shipboard handling element.

The recording capability becomes a major consideration due to pressure vessel and/or mooring system restrictions. The basic requirements are established by the data format, range sensitivity level, number of tracks and time period objectives. Only a few available recording packages can be adapted to this type of application unless a shallow subsurface buoy is utilized. The basic problem is deciding where to position the recording package, particularly for extended periods of time. Table 7.3 can be referred to for an indication of possible recording package installation concepts. These options will fall within the same general cost range. Although each recording option has its own specific concern, all can be quite readily accomplished using basically only the deployment vessel.

The availability of very long length, high strength, low impedance deepwater EM cable is very limited. The EM Cable becomes a critical element particularly if sophisticated and sensitive data recording is desired.

The project required to provide the necessary subsea deepwater equipment, deploy that equipment and record the data is rather extensive. The major cost elements, as summarized on Table 7.4, would be required for a permanent 1,000 foot emplaced reentry borehole located in 15,000 foot water depth. A 30-day in situ recording capability would be provided.

The general scenario would include defining the specific equipment requirements and selecting the borehole package and recording package

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	CUNARDA							Susceptible to Dama	or Theft	Very long EM Cable	Inter connection				
	Tape				Tape			Tape		Real-Time					
AVAILABLE	91H	580	đđ		+ DIH	• S80	# dd8	Many		HIG	OBS	BPP		·	
	Release Transponder	with Package Float	Riser or Grapnel	Line Lift	Riser or Grapnel	Line Lift	Release Transponder	Pickup Buoy		Riser or Grapnel	Line Lift				
	Lower Package to Seabed				 Lower Package or	Controlled Freefall		Deploy over side		Lower Pack to Seabed					(net all at form
MOORING/RETRIEVAL	Extensive Anchor	and Riser Line			Anchor Cable	Possibly Riser	Line	Anchor Cable		Riser Line					re or subsurface huov
P RESS URB	Heavy Wall				Moderate Wall			Light Wall		Heavy Wall					figured for surfa
BA BA E	Seabed				Subsur face	Buoy		 Surface Buoy		Seahed (Hard	Line)				• Could be con

DEEPWATER TEST RECORDING PACKAGE INSTALLATION OFTIONS TABLE 7.3

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TABLE	7	•	4
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DEEPWATER (15,000 FT) TEST COST PROJECTION*

(Commercial DP Drillship)

Borehole Package Procurement & Integration	\$500,000
Recording Package Procurement & Integration	400,000
EM Cable/Winch Procure	150,000
Deployment Engineering and Planning	250,000
Deployment Equipment Refurbishment	120,000
Ship Charter (40 Days)	2,800,000
Test Equipment (Shipboard)	80,000
Mobilization and Conversion	120,000
Demobilization	50,000
Recovery Vessel Charter (15 Days)	80,000
Operations Support	380,000
IRR Mooring/Subsea Buoy	200,000
Miscellaneous and Contingency	480,000
	\$5,610,000

* Does not include Instrumentation Development, Data Evaluation or Management Costs.

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positioned drillship and mobilization base would be selected. Procurement of any long lead items (i.e., reentry cone, reentry sonar, special drillstring, fixtures, etc.) would be initiated. Refurbishment of existing MSS equipment would also be accomplished.

At the selected mobilization port, all of the elements would be received and assembled. All the mechanical and electrical interfaces would be checked out. A dockside test would be conducted simulating to the greatest extent possible the at-sea operations. A special shallow water checkout should be considered dependent on the complexity of the equipment and the experience of the crew.

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The drillship would then proceed to the site where a subsea positioning beacon would be established. A pilot core would be taken preparatory for the initial reentry cone/conductory casing installation. The borehole would then be drilled out to depth and encased as directed. Several reentries would be required for a deep borehole emplacement. The borehole package would be deployed at the end of the drillstring and after reentry, released and lowered into the borehole. Possibly 4 to 5 days of real time recording may be performed. The recording package would then be deployed with associated recovery equipment.

The drilling vessel would then return for demobilization. Subsequently, a medium sized oceanographic research vessel or large workboat would be chartered to recover the recording package and/or borehole package, as desired.

The overall integration and deployment would take 18 to 24 months, assuming the borehole instrument could be provided within the initial 12 months. The drillship charter is estimated at about 40 days in order to cover mobilization, transit, on-site operations (estimated at 20 days) and demobilization.

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SECTION 8.0 - DEEPWATER OPERATIONAL PROGRAM

8.1 INT RODUCTION

A string of deepwater operational borehole sites can be installed by basically utilizing the deployment and emplacement techniques already discussed. The major considerations are:

- Specific site(s) parameters
- Instrumentation package characteristics and capabilities
- Weather and environmental conditions
- Communication network

The MSS development program has demonstrated that the first three considerations can probably all be accommodated. However, the biggest unknown is the communications requirements, particularly if a rapid data feedback is necessary. The communications network can be either a recoverable recording package, a hard line link to existing subsea circuits, satellite communications, a long wave radio system or acoustic data transmission. Pop-up buoy systems can be utilized for either of the radio communications approaches. Each of the above networks presents different specific requirements, but all should be resolved, though with difficulty, as part of the deployment scenario herein envisioned.

8.2 PROGRAM ELEMENTS

A deployment program of 8 to 12 deepwater sites positioned across the Atlantic and Pacific Oceans has been projected. An operational deployment subprogram would be made up of the major cost elements as defined in Table 8.1. These elements would form part of a larger national strategic system.

8.3 SCHEDULE

The overall deployment of 8 to 12 stations herein considered would probably require about 30 months to accomplish assuming the sensor

TABLE 8.1

MULTIPLE SITE OPERATIONAL DEPLOYMENT PROGRAMS

(Commercial DP Drillship)

Instrument Package Develop & Hardware	\$ 6,500,000
Communications/Data Recording Develop & Hardware	3,900,000
Deployment System Engineering	1,500,000
Shallow Water Checkout	600,000
Deployment Hardware Procurement	3,200,000
Ship Charter (9 months)	14,600,000
Mobilization	700,000
Operations, Fuel and Supplies	1,500,000
Demobilization	500,000
Recovery/Maintenance Support (1 year)	1,200,000
Miscellaneous and Contingency	3,300,000
	\$ 37,500,000

The costs constitute only rough estimates of an 8-12 multiple deep ocean site deployment program but are indicative of the magnitude.

7.6. 20

instrumentation needs only to be packaged into a deepwater configuration. Actual at-sea operations should be accomplished in an approximate 9-month period if the projected sites are near to each other. Figure 8-1 depicts a typical projected schedule.

8.4 BRIEF SCENARIO

Based upon specified requirements, deepwater packaging of the defined borehole instrument would be initiated. In parallel, development of either a recording package, a communications buoy or a hard line connection would begin. A comprehensive evaluation of all projected station sites would be undertaken, and a tentive schedule would be established taking into account difficult site and probable weather conditions. A preliminary operations plan would be prepared from which to establish specific vessel and support equipment requirements.

Upon selection of the deployment vessel, detailed design of the subsea and specialized shipboard handling would be accomplished. Major procurement action on long lead items (i.e., drill pipe, winches, BHA, etc.) would be initiated. A preliminary mobilization and logistics support plan would be prepared. A comprehensive ground test checkout and shallow water demonstration would be defined. A base port of operations would also be established.

At or near the selected port of operations, conversion of the drillship would take place including installation of special shipboard handling equipment. During this period final development and checkout functional testing would be accomplished. Dockside testing of various integrated equipment subsystems would be performed, as applicable. After necessary developmental and shore test checkout was accomplished, a shallow water demonstration would be performed to demonstrate the equipment capabilities, personnel and data "ransmittal techniques. training, procedures This demonstration would take about a month to accomplish and in some cases would perhaps initially utilize breadboard type hardware/ software.

8-3

THIRD YEAR MOBILIZATION/DEMOBILIZATION DATA EVALUATION **OPERATIONS** SECOND YEAR TEST PACKAGE INTEGRATION PROCUREMENT ENGINEERING SITE EVALUATION FIRST YEAR PACKAGE DEVELOPMENT

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FIGURE 8-1 PROJECTED MULTIPLE SITE DEPLOYMENT SCHEDULE

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possibly be conducted into Atlantic and Pacific legs. Each leg would be 4 to 6 months in duration. Crew changeover, refueling and resupply would be scheduled every 6 to 8 weeks and would be accomplished in foreign ports, as necessary. It is assumed that the drilling ship would require at least one trip through the Panama Canal.

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Operations at each projected site would require an average of 20 days for borehole emplacement, deployment, plus real time recording. Certain stations may require up to 30 days to allow for possible severe weather holds. In addition to the program's specialized equipment, fuel, food, etc., the major expendables would include the casing, borehole cones, and cement.

The demobilization portion of the overall program would be completed with the reconversion of the drilling vessel. All program-procured shipboard handling equipment would be stored, as directed.

APPENDIX A

BROCHURES OF DRILLSHIPS

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GLOMAR CHALLENGER GLOMAR PACIFI " GLOMAR ATLANTIC SEDCO 445 SEDCO/BP 471 SEDCO 472 S-709 DISCOVERER SEVEN SEAS HENRY GOODRICH ODECO

GLOMAR CHALLENGER

Length, Beam, Draft: Length: 400' - Beam: 65'2'' - Draft: 9'2'' (Light ship) Displacement 4,470 L.T. (Light ship) Centerwell: 22' x 24' **Propulsion:** Diesel electric, twin screw, driven by GE 752 RI electric motors. Ground Tackle: 3 - 111,000 lb, anchors with 900' 2" anchor chain. **Anchor Winches:** American Hoist and Derrick Company 2-1/16" galvanized wire, diesel driven. Cranes: 1 — Mariner 500, 50 ton, diesel. 1 - 15 ton, diesel. **Auxiliary Pumps:** Fuel Salt water Fresh water **Compressed Air System:** 1 — 3.2 CFM 100 PSI air compressor 2 - 358 125 PSI air compressors with after coolers 1 - 22 CFM 100 PSI emergency air compressor Water Distillation Unit: 2 — Aqua Chem Radio: Northwest Instruments Model NW-38 radio-

telephone and RCA type CRM CIC radiotelegraph.

Radar:

2 — Decca Model RM 914

Fathometer: EDO Model 185 **RDF** Unit: Bendix Model ADF-100 Intercom System: Sound powered telephone system. Welding Machine: 2 — Lincoln 300 amp. electric driven. **Reserve Mud:** 2,490 barrels **Drilling Water:** 4,769 barrels **Bulk Mud:** 12, 300 cu. ft. **Bulk Cement:** N/A



Sack Material Storage:

12,000 sacks Fuel:

16,568 barrels

Potable Water:

1,019.2 barrels

Derrick:

- 142' x 61' x 38' special design galvanized with 1,000,000 hookload capacity, API rating. Drawworks:
 - National type, 1625 DE, with Elmagco type eddy current brake; driven by 2 GE 752 RI electric motors, with 11/2" drilling line and 26,000' 1/2" sand line.

Rotary Table:

Power swivel

Mud Pumps:

2 - National type, N-1300 duplex power slush pumps driven by dual GE 752, 800 HP each. Mud Mixing Pump: 2 — Mission 6 x 8R centrifugals, 75 HP each. **Traveling Block:** National, 500 ton cap, with special guide rail rollers. Swivel: National type N-1324, 335 ton. National type NSF-650, 450 ton. Air Tuggers: 8 - 2,000 lb. capacity 1 - 4,000 lb. capacity 3 — 4,000 lb. capacity 2 - 5,000 lb. capacity **Rotary Hose:** 31/2" x 65 **Crown Block:** National 760-H, 500 ton capacity. Master Bushing: None **Drill Pipe:** 5" drill pipe, Grade S-135, 19.5 lb./ft., Range 2 **Drill Collars:** 8¼'' OD x 30' 7¼"OD x 30" Logging Unit: None **BOP Control System:** None **BOP Stack:** None **Riser Tensioning:** None





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GLOMAR PACIFIC

The GLOMAR PACIFIC is a self-propelled drillship that maximizes the advantages of the hull-shaped structure — capacity, mobility, safety, and fuel efficiency for automatic station keeping.

Equipped with both conventional mooring and dynamic positioning systems, this design provides for operations in water depths from 100 feet to 2,000 feet. Its loaded displacement of 14,751 tons and maximum speed of 14 knots make this exploratory vessel ideally suited to meet the growing demands of worldwide offshore exploration.

The GLOMAR PACIFIC has a hull configuration which incorporates a high freeboard-to-depth ratio which results in a high degree of stability and dryer working decks. Major design features include a wide beam, a rounded, modified cruiser stern; a semibulbous bow; a longitudinal frame with double bottom and wing tanks; and a concentration of mass near the boundaries of the hull. These design features provide for reduced hull resistance and a minimum of angular motion under normal operating conditions by lowering the center of gravity. Due to reduced windage and underwater areas in beam-on conditions, this drillship, using the main propulsion units and thrusters, requires a minimum of power to maintain position within allowable limits. Emphasis is placed on the GLOMAR PACIFIC's ability to sustain long term operations under demanding conditions with a minimum of support within a wide range of water depths.

When combined, the structural design, weight distribution, and excellent stability characteristics result in the assurance of a reliable, safe, and cost-effective floating drilling unit for offshore programs.

For further information please contact Global Marine Drilling Company 7500 San Felipe, Houston, Texas 77063 Phone (713) 978-4204



Dynamic Positioning Control Station



Tubular storage area



Drilling floor area with the "Iron Roughneck" in foreground



Main generators in the engine room

GLOMAR PACIFIC

GLOBAL MARINE DRILLING COMPANY



GLOMAR PACIFIC

The GLOMAR PACIFIC is a self-propelled drillship that maximizes the advantages of the hull-shaped structure — capacity, mobility, safety, and fuel efficiency for automatic station keeping.

Equipped with both conventional mooring and dynamic positioning systems, this design provides for operations in water depths from 100 feet to 2,000 feet. Its loaded displacement of 14,751 tons and maximum speed of 14 knots make this exploratory vessel ideally suited to meet the growing demands of worldwide offshore exploration.

The GLOMAR PACIFIC has a hull configuration which incorporates a high freeboard-to-depth ratio which results in a high degree of stability and dryer working decks. Major design features include a wide beam; a rounded, modified cruiser stern; a semibulbous bow; a longitudinal frame with double bottom and wing tanks; and a concentration of mass near the boundaries of the hull. These design features provide for reduced hull resistance and a minimum of angular motion under normal operating conditions by lowering the center of gravity. Due to reduced windage and underwater areas in beam-on conditions, this drillship, using the main propulsion units and thrusters, requires a minimum of power to maintain position within allowable limits. Emphasis is placed on the GLOMAR PACIFIC's ability to sustain long term operations under demanding conditions with a minimum of support within a wide range of water depths.

When combined, the structural design, weight distribution, and excellent stability characteristics result in the assurance of a reliable, safe, and cost-effective floating drilling unit for offshore programs.

For further information please contact Global Marine Drilling Company 7500 San Felipe, Houston, Texas 77063 Phone (713) 978-4204



Dynamic Positioning Control Station



Tubular storage area



Drilling floor area with the "Iron Roughneck" in foreground



Main generators in the engine room

PRINCIPAL CHARACTERISTICS

normation	Classification: Length Overall: Beam Overall: Depth of Hull: Draft (Loaded): Displacement: Centerwell: Water Depth Capability: Drilling Depth	A.B.S. ★ A1 (£) 452 ft. 72 ft. 35 ft. 23 ft. 6 in. 8,153 LT lightship 26 ft.x26 ft. 2,000 feet	Maximum Speed: Berths & Galleys: Heliport: Allowable Variable	14 knots Air conditioned quar- ters and dining facil- ities certified for 101 persons. 83 ft.x90 ft. design- ed for Sikorsky S-61 helicopter: 2.000 gal- lons fuel storage capacity.				
	Capability:	25,000 11	Load:	7.400 tons (approx)				
Storage Capacities	General Cargo: Tubular Goods: Sack Materials: Bulk Cement: Dry Bulk Mud: Fuel:	200 tons Casing Rack-400 tons Casing Hold-600 tons 15,000 sacks 7,415 cu. ft. 16,800 cu. ft. 15,751 bbl.	Active Mud: Reserve Mud: Potable Water: Wash Water: Drilling Water: Lube Oil:	594 bbl. 3,044 bbl. 1,140 bbl. 2,748 bbl. 19,163 bbl. 407 bbl.				
Power Generation Power Conversion Emergency Power	Four GE type AT1 (rated at 3860 HP a Ten Westinghouse One 600 KW Delco 1,800 RPM.	Generators rated at 2750 KW It 1200 RPM for main power SCR DC Power Conversion o Generator driven by a V-12	V 600 Volts, each driven t Units Detroit Diesel Engine rat	ed at 975 HP at				
Main Propulsion	Two 11 foot, four bladed, fixed pitch propellers, each driven by three GE 1600 HP DC motors developing 9600 SHP giving a maximum speed of 14 knots							
	Five Schottel thruster units (three forward and two aft) each rated at 1675 HP.							
Thrusters	Five Schottel thrus	ster units (three forward and	two aft) each rated at 16	75 HP.				
Thrusters Conventional Mooring System Dynamic Positioning	Five Schottel thrus Anchors: Eight 30 6,000 ft.x3 in. wire Winches: Eight S A Delco dual redu acoustic beacons	ster units (three forward and 0.000 lb. Offdrill II anchors. e e rope. kagit model ETW 300 moorir indant computerized system , hydraphone assemblies. ta	two aft) each rated at 165 each with 1.750 ft ×234 in ng winches. . Complete with backup o iut wire sensor system an	75 HP stud link chain and computer, high frequency d riser angle indicator.				
Thrusters Conventional Mooring System Dynamic Positioning Communications Equipment	Five Schottel thrus Anchors: Eight 30 6,000 ft.x3 in. wire Winches: Eight S A Delco dual redu acoustic beacons ITT McKay Main H Motorola Marine S Motorola VHF/FM ITT McKay portab	ster units (three forward and 0.000 lb. Offdrill II anchors, e e rope. kagit model ETW 300 moorir indant computerized system , hydraphone assemblies, ta tigh Seas Radio System SSB Radio Radio Telephone ole lifeboat transmitter receiv	two aft) each rated at 165 each with 1.750 ft x 2¾ in ng winches. . Complete with backup (iut wire sensor system an er.	75 HP stud link chain and computer, high frequency d riser angle indicator.				
Thrusters Conventional Mooring System Dynamic Positioning Communications Equipment Navigational Equipment	Five Schottel thrus Anchors: Eight 30 6,000 ft.x3 in. wire Winches: Eight S A Delco dual redu acoustic beacons ITT McKay Main H Motorola Marine S Motorola VHF/FM ITT McKay portab LORAN "C" receir Tracor OMEGA N. Raytheon forward ITT McKay type 4	ster units (three forward and 0.000 lb. Offdrill II anchors. e e rope. kagit model ETW 300 moorir indant computerized system , hydraphone assemblies. ta tigh Seas Radio System SSB Radio Radio Telephone ole lifeboat transmitter receiv ver avigator II Receiver Land aft radar units 1005A ARDF	two aft) each rated at 163 each with 1.750 ft x 234 in ng winches. . Complete with backup o uit wire sensor system an er. ITT McKay EPIRB EDO/Western Fath Sperry Gyro Comp	75 HP stud link chain and computer, high frequency d riser angle indicator.				

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Main Office: 7500 San Felipe P.O. Box 4379 Houston, Texas 77210 PHONE: (713) 978-4100 TELEX: 775415 CABLE: GLOMARCO

Los Angeles:

811 West Seventh St. Los Angeles, California PHONE: (213) 486-9800 TELEX: 67272 or 677240 CABLE: GLOMARCO

London: Standbrook Housje 2 Old Bond Street London W1X 4QH England PHONE: 01-493-2933 TELEX: 264431 CABLE: GLOMARCO

Singapore: Goldhill Plaza

Newton Road Singapore 1 Republic 6 Singapore PHONE: 252-4238 TELEX: 2447 N. Contraction

GLOMAR ATLANTIC

GLOBAL MARINE DRILLING COMPANY









Dynamic Positioning control station



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Drilling floor area with the "Iron Roughneck" in foreground

Drilling Equipment	 Drawworks: National Type 1625 DE with Elmagco type 7838 electric brake driven by three GE 752 electric motors. Derrick: Global Marine design: 142 ft.x61 ft.x38 ft. galvanized with 1,000,000 lbs. hookload capacity. API rated. Crown Block: 650 ton capacity for use with a single piston motion compensator. Motion Compensator: Vetco single piston unit with a 20 ft. stroke and a 400,000 lb. capacity. Swivel: National P-650. Rotary Table: National C-495 independently driven by one GE 752 electric motor. Weight Indicator: Martin Decker, Type EB. Kelly Spinner: Varco 6500. Pipe Racker: Global Marine design, automatic, horizontal; 23,580 ft. capacity in triples. Drill Pipe: 10,000 ft. of 5 in. Grade E: 5,000 ft. of 5 in. Grade G. Drill Collars: Thirty 6½ in.x30 ft., thirty 8 in.x30 ft. Mud Pumps: Two National 12-P-160 Triplex pumps, each powered by two GE 752 electric motors.
	Mud Mixing: Two Mission 6"x 8" pumps. Cementing Unit: Twin Halliburton HT-400 skid mounted unit, driven by two GE 752 electric motors. Degasser: Wellco 5200. Desander: Pioneer T-10-6 rated at 1,100 gpm. Desilter: One Pioneer Model T-16-4 rated at 800 gpm. Shale Shaker: Brandt Dual Tandem. Air Compressors: Four Ingersoll-Rand and four Sullair air compressors.
Subsea Equipment	 BOP System: Certified for H₂S service. Stack Size/Rating: 18¾ in. 10,000 psi WP. guidelineless. Ram Preventers: One double type "LWS" and two single type "LWS." Annular Preventers: Two Shaffer 18¾ in. spherical blowout preventers rated at 5,000 psi WP. Wellhead Connector: 18¾ in. 10,000 psi WP. Regan. Riser Connector: 18¾ in. 10,000 psi WP. Regan. Choke and Kill Valves: Eight McEvoy fail safe valves, five straight and three right angle. BOP Control System: Koomey dual pod hydraulic with acoustic and hot line backup, and a single function emergency wellhead disconnect system. Choke and Kill Manifold: 10,000 psi WP. with two Swaco hydraulic, and two McEvoy manual adjustable chokes. Diverter System: Regan Model KFDH. Marine Riser: 21¼ in. Regan buoyant riser 10,000 psi WP. integral choke and kill lines. Riser Tensioners: Four dual Vetco, each with a combined line pull of 150,000 lbs. and 50 ft. line travel. Guide Line Tensioners: Four Vetco single cylinder, each with 40 ft. line travel and a 16,000 lb. line capacity (for use if guidelines are required). Pod Line Tensioners: Two Vetco single cylinder, each with 40 ft. line travel and a 16,000 lb. line capacity. Underwater Television: Complete wellhead and dual lower marine riser package re-entry TV system. Position Indicator: Honeywell Model RS-505.
Auxiliary Equipment	Water Distillation Unit: Two Aqua Chem Model S-300 Spec-E, electric powered water distillation units. Oily Water Separator: Sarex, 20 gpm capacity. Cranes: Two Devault Model 50-15 with 35 ft. booms; and one Devault Model 120-15 with 60 ft. boom. Welding Equipment: Two 400 amp welding machines.
Onboard Facilities	Machine and Welding Shop Electronic Repair Shop Electrical Repair Shop Parts Storeroom

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Singapore:

Goldhill Plaza Newton Road Singapore 1 Republic 6 Singapore PHONE: 252-4238 TELEX: 2447 TO AND

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Full Dynamic Stationing in Water Depths to 6,000 feet for Worldwide Exploration. Operated by SEDCO, INC.

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16¾" BOP Stack

MAJOR DIMENSIONS

Length, Overall	445 ft
Beam, MId	70 ft
Depth, MId at side	32 ft
Draft, Max (Summer Load Line)	24 ft 6 in
Displacement at 24 ft. 6 in. draft	18,600 st
Displacement at 22 ft.	
(Avg op. Draft)	15,000 st
Light Ship Displacement	8,538 st
Max speed at 24 ft. 6 in. draft	14 kts
Moon pool diameter	32 ft

STORAGE CAPACITIES

Liquid Mud	3,000 bbl
Drill Water	10,000 bbl
Diesel Oil	12,000 bbl
Potable Water	1,000 bbl
Bulk Dry Mud	8,050 cu ft
Bulk Dry Cement	5,250 cu ft
Sack Storage	8,560 cu ft

EQUIPMENT

Power Generation

- 5 2100 KW EMD Engine Generator sets for main power
- 2 1500 KW EMD Engine Generator sets for ship's service
- 1 250 KW GM Emergency Generator Set

DC Conversion

24 Baylor Model 15000 Thyrig bays converting 600 V AC to 0-750 V DC

Main Propulsion

2 13 ft diameter, 4 bladed, fixed-pitch propellers each driven by 6-750 HP General Electric DC motors. A.B.S. approved.

Thrusters

11 Baylor Pleuger units, mounted in pairs, each unit driven by one 800 HP General Electric DC motor

Dynamic Positioning

Honeywell Automatic Station Keeping (ASK) with redundant H316 computers, RS-5 Acoustic Position Indicators, taut wire angle sensors and riser angle indicators.

Principal Cha

Cranes

- 1 Bucyrus Erie M at 79 tons at 2
- 1 Bucyrus Erie MK at 79 tons at 25 f
- Bucyrus Erie N at 58 tons at 20.

Water Distillation

2 Meco electric v tion units each

Compressors

- 2 Gardner-Denve each delivering general service an
- 1 Gardner-Denve emergency air HP motor
- 1 Gardner-Denver start air compre 200 PSIG.

Lifeboats

4 Totally enclo propelled wate. capacity for 60 m Schat self-laun

DRILLING ANDA EQUIPM

147 ft Lee C. Moore wel 1,000,000 lb. st⁻⁺
Oilwell E 3000 drav
Oilwell A 49½" rotary
Two Oilwell A 1700 P I D-79 DC motor
Vetco 400,000 lb. 2L ft sator
8 Western Gear 80K lis in pairs.
4000 ft of Regan in. 10,000 psi choke which is equi be Cuming syntac modules

1-16%" 5,000 psi C n stack with three se of blind shear ra preventer.

racteristics

30 vith 60 ft boom rated oot adius -60 with 80 ft boom rated pot_radius -35 vith 80 ft boom rated oot adjus

wr ompression distillaated at 600 gal/hr.

W 3 air compressors 82 cfm at 200 PSIG for d control air D electrically driven ing essor driven by a 15

VEE diesel driven cold or elivering 141 scfm at

self-righting, selfraf: ifeboats, each with en and complete with ic lavits.

> SSOCIATED ENT

ded panel derrick with heod load capacity crh

Juplex mud pumps with

shoke heave compen-

erensioners, mounted

tegral marine riser with and kill lines, 3000 ft of d with Emerson and foam buoyancy

er h blowout preventer ts of pipe rams, one set ns and Hydril annular 1-163/4" 10,000 psi Cameron blowout preventer stack with three sets of pipe rams, one set of blind shear rams and Hydril annular preventer.

Koomey EH/Hydraulic B.O.P. control system and RATAC acoustic back up

Halliburton HT 400 twin cementing unit with D-79 DC motors, recirculation pumps and 10,000 psi manifold.

Vetco 10,000 psi choke and kill manifold.

Western Gear pipe racker and stabber with a Western Gear riser handling support crane system.

Tubulars

15,000	5" Grade E	19.5 lb/ft drill pipe
6,000 ft.	5" S-135	19.5 lb/ft drill pipe
15,000 ft.	31/2" Grade E	15.5 lb/ft drill pipe
20 joints	5" "Hevi-Wate"	'50.0 lb/ft drill pipe
10	91/2" x 32 ft.	drill collars
40	8" x 32 ft.	drill collars
47	61/2" x 32 ft.	spiral drill collars
30	4¾" x 32 ft.	drill collars

ONBOARD FACILITIES

- Co plete machine and welding shop
- Air conditioned electronic repair shop
- Motor rewind and electrical repair shop
- Onboard warehouse storage facility complete with warehouse office

GENERAL

Accommodation

- Total capacity 93, not including 4-man hospital 7
 - Single rooms
- 29 Two-man rooms
- 7 Four-man rooms 1 Four-man hospital

Heliport

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70' x 70' for Silorsky S61 wheeled helicopter.



HONEYWELL ASK SYSTEM

OVERSEAS DRILLING LIMITED SEDCO/BP 471



Full Dynamic Stationing in Water Depths to 6,000 feet for Worldwide Exploration, Operated by SEDCO, INC.



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SEDCO/BP 471

Sample Load for a Two Well Program (90 Days)

Wellhead and Guidance Equ	ipment		Riser	
3 30" wellheads and exte	nsions	13 st	60 50 ft Joints of Buoyed Riser	422 st
3 16 ³ 4" wellheads and ext	tensions	20 st	27 50 ft Joints of Unbuoyed Riser	112 st
3 Permanent Guide Base	S	57 st	Various Pup Joints	12 st
3 Temporary Guide Base	S	10 st	2 Telescopic Joint	28 st
	_	100 st		514 st
			B.O.P. Stacks	
Casing			2 16¾ 10,000 psi W.P. Blowout	
400 ft 30" Conductor	310 lb/ft	62 st	Preventers	330 st
2,000 ft 20" Casing	94 lb/ft	94 st		
7,000 ft 133%" Casing	68 lb/ft	238 st		330 st
18,000 ft 9%" Casing	47 lb/ft	423 st	Mud and Cement	
25,000 ft 7" Casing	29 lb/ft	362 st	5250 cu ft Cement at 94 lb/cu ft	242 st
			3850 cu ft Bentonite at 60 lb/cu ft	116 st
	1	l.179 st	4200 cu ft Barite at 135 lb/cu ft	284 st
			7500 cu ft Sack Material	281 st
Drill Pipe				
15,000 ft 19.5 lb/ft	5" Grade E	146 st		923 st
6,000 ft 19.5 lb/ft	5" S 135	59 st	Tank Storage	
10,000 ft 15.5 lb/ft	3%" Grade E	78 st	Fuel and Lube Oil	3 079 st
30 Joints of "Heviwate" Dril	I Pipe	23 st	Salt Water Ballast	614 st
	-		Drill Water	1 862 st
		306 st	Potable Water	150 st
				5,705 st
6 9%" Drill Collars		20 st	Miscellaneous	
28 8" Drill Collars		63 st	Provisions	30 st
6 8" Drill Collars with 3	// Bore	13 st	Personnel and Effects	25 st
48 6%" Drill Collars	. 2010	66 st	Various Tools	180 st
24 4 ³ / ₄ " Drill Collars		18 st		
		180 st	_	235 st
			Total Load	9,532 st
			Total Displacement	18,431 st

SEDCO, INC. SEDCO 472

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Full Dynamic Stationing in Water Depths to 6,000 feet for Worldwide Exploration, operated by SEDCO, INC.





SEDCO 472

Sample Load for a Two Well Program (90 Days)

Wellhead and Guid	lance Equip	oment				
3 30" wellheads	13 st					
3 16 ³ / ₄ " wellhea	20 st					
3 Permanent G	3 Permanent Guide Bases					
3 Temporary G	10 st					
		-	100 st			
Casing						
400 ft 30" Con	ductor	310 lb/ft	62 st			
2,000 ft 20" Casi	ng	94 lb/ft	94 st			
7,000 ft13∛⊮″ Ca	sing	68 lb/ft	238 st			
18,000 ft 95%" Cas	ing	47 lb/ft	423 st			
25,000 ft 7" Casin	g	29 lb/ft	362 st			
		- 1	.179 st			
Drill Pipe						
15,000 ft 19.5 lb/f	t	5" Grade E	146 st			
6,000 ft 19.5 lb/f	t	5″ S 135	59 st			
10,000 ft 15.5 lb/f	t	312" Grade E	78 st			
30 Joints of "Hevi	wate" Drill F	Pipe	23 st			
		-	306 st			
Drill Collars						
6 9 ¹ 2" Drill Col	lars		20 st			
28 8" Drill Colla	rs	-	63 st			
6 8" Drill Colla	irs with 31.7	Bore	13 st			
48 6'2" Drill Col	lars		66 st			
24 4 ³ 4" Drill Coll	ars	-	18 51			
			180 st			

Riser

60 27	50 ft Joints of Buoyed Riser	422 st
_ .	Various Pup Joints	12 st
2	Telescopic Joint	28 st
		574 st
B.O .	P. Stacks	
1	16 ³ 4 10,000 psi W.P. Blowout	
	Preventers	207 st
		207 st
Mud	and Cement	
5250	cu ft Cement at 94 lb/cu ft	242 st
3850	cu ft Bentonite at 60 lb/cu ft	116 st
4200	cu ft Barite at 135 lb/cu ft	284 st
7500	cu ft Sack Material	281 st
		923 st
Tank	Storage	
Fuel	and Lube Oil	3,079 st
Salt	Wa er Ballast	614 st
Drill	Water	1,862 st
Potal	ble Water	150 st
		5,705 st
Misc	ellaneous	
Provi	sions	30 st
Perso	onnel and Effects	25 st
Vario	us Tools	180 st
		235 st
	Total Load	9,409 st
	i otal Displacement	18,097 st

MARINE DRILLING, S.A. S~709

Full Dynamic Stationing in Water Depths to 6,000 feet for Worldwide Exploration, operated by SEDCO, INC.

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AUTOMATIC STATION KEEPING



10,000 PSI BLOWOUT PREVENTER



NO GUIDELINES REQUIRED

Principal Chara

MAJOR DIMENSIONS

MAJOR DIMENSIONS		Column Tanks
Lower Hulls (Two)		(TO-IL: dia: colde his)
Length Overall	295 Ft.	TYPE
Width Overall	245 Ft.	Bulk Barite Stora e
Depth	21 Ft.	Pods
Width	50 Ft.	Bulk Cement
		Storage Pods
Stability Columns		Bulk Gel
Four Corners, Diameter	30 Ft.	Storage Pods
Four Intermediate, Diamet	er 18 Ft.	
Main Deals		Column Tanks
Main Deck	001 5	(30-ft. dia. colu.mns)
Width Overall	231 FL	TYPE
Width Overall	137 FL	Potable Water
Heights		(Port Fwd.)
Keel to Main Deck	112 Et 6 in	Reserve Mud
Main Deck to Heliconter	112 11. 0 m.	(Aft, P/S)
Main Deck to Pipe Back D	eck 17 Ft	
Main Deck to Derrick Floo	r 37 Ft.	
		Deck Load Capacity
Drafts		(Column Tanks
Normal Transit Draft	21 to 26 Ft.	Included)
Operating Draft	70 to 80 Ft.	
Minimum Survival Draft	42 Ft.	EQUIPME
Weights		Engine House
Lightship Weight	14,917 S.T.	Ger
Lightship Center		7-
of Gravity 71	.2 Ft. Above Keel	6
STODAGE CAR	AOITICO	2
STORAGE CAP	ACITIES	2-0
Hull Compartments	TOTAL	2-
TYPE	CAPACITY	1-6
Ballast Tanks	62,200 bbls.	Cor
Fuel Oil Tanks	12,700 bbls.	
Drill Water Tanks	5,800 bbls.	Switchgear Room 416
Total Displacement		Swi
of Lower Hulls	16,905 S.T.	500
Total Displacement		Tr.
at 80 Ft. Draft	25,110 S.T.	8-1
Dook Tanks and		2 - 3
Storage		Co
Storage		Noc
Active Mud Tanka	1 000 hhl	Sys
Reserve Mud Tanks	1,000 bbls.	Dunamia
Bulk Cement	1,000 DDIS.	Positioning St
Storage Pods	1.600 cu. #	Fositioning 50
Bulk Barite	1,000 cu. n.	A
Storage Pods	1.600 cu ft	Mud House
Pipe Rack Areas	1,000 00.10	nindu riouse
Available	13,500 sq. ft	1
Sack Storage Area	1.800 sq. ft	T En

TYPE ulk Barite Stora Pods ulk Cement Storage Pods lulk Gel Storage Pods mn Tanks -ft. dia. colu TYPE otable Water (Port Fwd.) eserve Mud (Aft, P/S) Load Capacity Column Tanks Included) EQUIPMENT ne House 550 KV 11 Generator 7 -500 K erator 2 ot Wat Steam (r Com resh \ - H.P. Air mpress chgear Room 116 / and 4 Switchge 500 KW Aux Tr. sforme 8 - Inruster 2 -3 Bay Th Co versio Pow r Ma System fon /well St. ion mic sitioning (ASK) House 00

> Pumps - 350 K En ne-

> > emen
Haracteristics

9.900 cu. ft 4,400 cu, ft.

4,400 cu. ft.

1,180 bbls.

2.340 bbls.

3.200 S.T.



pacity nks

UIPMENT

1 - 550 KW Engine Generator 7 - 500 KW Engine erators 2 - Hot Water Boilers 2 - Steam Generators 9 - ir Compressors 2 - resh Water Makers 1 - H.P. Air Compressor 116 / and 480V Switchgear 500 KW Auxiliary Tr sformer 3 - mruster Starters 2 -3 Bay Thyrister DC Conversion Units Power Management System for well Automatic Station Keeping (ASK) System 700 HP Mud Pumps 1 -- 350 KW Emergency En ne-Generator ementing System

	1 — Mud Solids Removal System 1 — Bulk Air Compressor
Pipe Racks	Mud House Roof — 1000 T of Drill Pipe, Casing and Drill Collars Main Deck — 800 T of Riser Pipe
Quarters	2 Decks of Accommo- dations 14 Men on Upper Deck 80 Men on Main Deck
Heliport	For Sikorsky S-61 Wheeled Helicopter
Revolving Cranes	2 — 45 T Capacity at 50 Ft. Radius, 120 Ft. Booms
Anchoring System	 8 — 30,000 lb. LWT Anchors 8 — 500 Kip Capacity Anchor Windlasses 8 — 5000 Ft. Lengths, 3 in. Diameter, Stud Link Chain 8 — Hinged Fairleads 4 — Anchor Racks Above Water Level When Floating on The Hulls (2 Anchors Each Rack).
Drilling Area	Drawworks for 25,000 Ft. Hole Depth Drilling Mast — 160 Ft. High with Heave Compensator — Hook Capacity 1,100,000 lb. Compensating Capacity 400,000 lb. Setback Capacity 600,000 lb. 2 — 16¾ in., 10,000 psi Blowout Preventers Subsea Controls Multiplex Control, 100% Redundancy Riser — 4,000 Ft., 18-5/8 in. Integral

with Buoyancy



POWER MANAGEMENT SYSTEM



2,500 HP AZIMUTHING THRUSTER

Lower Hulls

Re-Entry - Thru Drill Pipe TV/Sonar Riser Tension - (12) 80,000 lb. Units 2-65 T Capacity Travelling Bop **Bridge Cranes** 8-2500 HP Azimuth-

ing Thrusters 4 - 2500 GPM Ballast Pumps



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DISCOVERER SEVEN SEAS SELF-PROPELLED DYNAMICALLY POSITIONED DRILLSHIP

and the second s

Rated Drilling Depth:

25 000 1001

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Principal Partic	ulars
Length Between Perpendiculars	486 feet
Length Overall	534 feet
Beam Overall	80 feet
Hull Depth	32 feet
Draft, Drilling	24 feet 9 inches
Draft at Loadline	24 feet 9 inches
Lightship Displacement	12,708 long tons
Moon Pool	26 feet diameter
Propulsion	Twin propellers, 15 ft. 6 in. diameter, powered by eight (8) 2,000 hp GE CD9664 D.C. motors, providing a total input of 16,000 hp to twin Falk marine reduction gears (5.85 to 1 ratio)
Calm Water Speed	14 knots

Regulatory Body Classification

American Bureau of Shipping (ABS) Ice Class 1A A1 AMS (E) (M) Mobile Drilling Unit for unrestricted worldwide ocean use Lloyd's Register of Shipping

Regulatory Body Approvals

Meets United States Coast Guard standards Panama and Suez Canal Tonnage Regulations **DEN** Certificate of Fitness

Registry

Panama

Owner

Offshore International, S.A.

Capacities

Variable Load Capacity ...8,508 long tons

Tubular Storage	400 ft. of 30 in. casing, 2,500 ft. of
-	20 in. casing, 8,000 ft. of 13% in.
	casing, 20,000 ft. of 9% in. casing,
	15,000 ft. of 7 in. casing, 15,000 ft.
	of 41/2 in. casing, 20,000 ft. of 21/8 in.
	tubing, 23,000 ft. of 5 in. drill pipe
Bulk Mud	.12,000 cu. ft.
Bulk Cement	4,800 cu. ft.
Sack Material	22,000 cu. ft.
Liquid Mud	Active: 1.800 bbls.
	Reserve: 2,400 bbls
Diesel Fuel Oil	22,297 bbis.
Drilling Water	12,683 bbls.
Potable Water	1,400 bbis

	25,000 leet		-	Opera
Positioning	Dynamically positioned with six (6) 3,000 hp Bird Johnson con- trollable pitch right angle thrusters and twin main propulsion screws]	-	Centrifug Gas Dete
Stationkeeping System .	Honeywell computerized Auto- matic Station Keeping system (ASK) using acoustic reference with hard wired ball joint angle indicators as backup sensors.	1	•	Drill Pipe
Drilling Equipme	nt	•	•	
Derrick	Pyramid, 46 ft. x 54 ft. base x 170 ft. high, 665-ton GNC	1		Motion C
Substructure	54 ft. x 46 ft. x 39 ft., special design to allow storage of B.O.P. stack at deck level	1		Riser Tei
Drawworks	Continental Emsco C-3, type II, 3,000 hp with special grooving for 1¾ in. drilling line, Elmagco 7838 eddy current brake, TCB Crown- O-Matic]		Pipe Han
Rotary	Continental Emsco 49½ in with 3.96 to 1 reduction ratio powered by 750 hp motor	1	-	Subse H₂S S
Prime Movers	Six (6) EMD MD 20E9, 2,500 KW, 4,160 volt, 3-phase diesel electric generators and one (1) EMD MD 12E8, 1050 KW generator]	-	Riser
Auxiliary Power	One (1) Caterpillar D398 V-12 with 550 KW A.C. generator	1		
Emergency Power	One (1) Caterpillar D3304, 90 KW A.C. generator			Diverter (
D.C. Power Distribution .	GE SCR Modules, GE 752 drilling motors	1	-	Ram Prev
Crown Block	Pyramid, 665-ton capacity	4	-	Annular I
Traveling Block	. Continental Emsco RA-60-6, six (6) 60 in. sheaves, 650-ton capacity	1	-	
Hook	Byron Jackson, 550 Dynaplex, 500-ton capacity		-	
Swivel	Continental Emsco LB-650, 650- ton nominal capacity, 471-ton API bearing rating capacity]	T	Spare BC B.O.P. Co
Mud Pumps	Two (2) Gardner Denver 1,600 hp PZ-11, 7 in. bore x 11 in. stroke	2	T	Choke an
Degasser	One (1) Wellco series 5200, 1,400 GPM capacity	à	4	
Desander	One (1) Pioneer S 3-12, 1,500 GPM capacity]	Auxili
Desilters	Two (2) Pioneer T-16-4, each rated at 800 GPM		-	Accomm
Shale Shaker	One (1) Brandt dual tandem rated 1,600 GPM at 20/40 mesh and 800 GPM at 40/80 mesh based on 16 0 PPG mud]]	Cranes .

	Operating Water	Depth: Minim	um: 250 feet	Maximum: 6,000 feet
•	Centrifuge Gas Detection System	Pioneer decanting Sieger 1300 for combustible a	Helicopter Deck	
	Drill Pipe	13,000 ft. of 5 in. O.D., Grade " 19.50 lbs./ft., internally plas coated drill pipe, 4½ in. I.F. conne tions: 7.000 ft. of 5 in. O.D., Gra	G ¹¹ Navigation Equipment tic dec- de	ntComplete high seas navigatio equipment, environmental motio monitoring system and data re cording
		"S-135" 19.50 lbs./ft. interna plastic coated drill pipe, 4½ in. I connections	Ily Communication F. Equipment	Conquerer SD-1500 W SSB mai transmitter, two (2) single side
	Motion Compensator	HSMC, 400,000 lbs. nominal c erating capacity with pinn capacity of 1,200,000 lbs., 18 nominal 20 ft maximum stroi	op- ed ft.	band systems, Watch Heceiver, on (1) marine VHF-FM radio, two (2 portable lifeboat radios, soun- powered telephone, P.A. system
	Riser Tensioners	Ten (10) HSMC riser tensione each rated at 100,000 lbs. pull, in sheaves	Water Distillation Un 65 Waste Treatment	itsTwo (2) waste heat Nirex unit capable of 600 GPH Two (2) Sasakura-Trident T-10
	Pipe Handling System	Byron Jackson automatic 3-a pipe handling system consisti of upper, intermediate and low racker arms	rm ng Lifesaving Equipmen ver	 units tFour (4) 64-person diesel powere- lifeboats, two (2) 25-person lif- rafts, two (2) 15-person life rafts
	Subsea and Well H ₂ S Service Riser	Control Equipment - 6,000 ft. of Regan FCF-8, 18 ³ / ₄ O.D., 0.688 in. wall thicknes Special 42 in. flotation cans, w adjustable air columns. All ris components suitable for H ₂ S so vice. Two (2) 50 ft. stroke Reg	Firefighting Equipme in. ss. ith ser er- an	two (2) 6-person life rafts Firefighting system with seventy nine (79) hydrants, seventy-eigh (78) dry powder fire extinguishers twenty-four (24) CO ₂ fire extin guishers, seventy-six (76) bottle fixed CO ₂ firefighting system, one (1) 640 gal. fixed foam system fo helideck
	Diverter System	Regan KEDS	Special Featu	res and Equipment
	Ram Preventers	Two (2) Cameron type "U" doub 16¾ in., 10,000 psi w.p.	Guidelineless Re-ent	ITYSpecial down hole TV and outside the-drill pipe TV with integrate acoustic beacon
	Annular Preventers	Two (2) Hydril GL, 16¾ in., 10,0 psi w.p., two (2) Vetco H-4 h draulic connectors and a spec design Vetco flex joint in lieu o standard pressure balanced b joint	00 Emergency Disconne ly- System ial f a all	ect Parameters tied into alarms and automatic sequence will activat specified B.O.P. functions and disconnect the riser
	Spare BOP Stack B.O.P. Control System	 Identical to equipment listed about the second secon	Video Displays ex	Current drilling parameters dis plays at four (4) locations on th vessel, B.O.P. TV and diver T' displayed at four (4) locations
	Choke and Kill System …	. McEvoy 10,000 psi dual choke a kill manifold with McEvoy valve two (2) McEvoy manually adju able chokes, and two (2) IMC remote controlled chokes	nd Prime Power Manag es, System st- CO	ement Power distribution/allocation managed by Honeywell computer Power requirements are predicter by continuous analysis of environ
	Auxiliary Equipm	ent		mental conditions, and a contro system adjusts engine load
	Accommodations	. Air-conditioned quarters for 1 persons, galley and messroom cilities, five (5) berth hospital	34 fa-	accordingly. A limiting contro loop prevents drilling machiner from using power required fo
	Cranes	Two (2) Bucyrus Erie MK-35 w	ith So	station keeping. Should this occur another prime mover is auto







F-PROPELLED SEMISUBMERSIBLE

Characteristics

- Drilling depth to 30,000 feet.
- Ice strengthened pontoons and columns.
- Operating draft of 29 meters (95 feet).
- Helideck to accommodate Boeing Chinook 234
 or Sikorsky S-61.
- Accommodations for 110 to 150 persons.
- Eight thrusters.

[·] Regulatory Bodies

- The Henry Goodrich will be registered under United States flag and designed and constructed in com pliance with the current regulations of the following
- regulatory agencies:
 - United States Coast Guard
- Canadian Oil and Gas Lands Administration
- Newfoundland and Labrador Petroleum Directorate
- Department of Energy United Kingdom
- Norwegian Maritime Directorate/ Norwegian Petroleum Directorate
- SOLAS

Environmental Conditions Wave Height 33.5 meters Wind Speed 115 knots

Wind Speed115 knots•-Current2.5 knots

Water Depth Capability

Condition	Minimum (meters)	Maximum (meters)			
Sit on Bottom	15	30			
Chain Moored	92	610			
^C Dynamically Positioned	92	3048+			

Variable Capacities

Condition	Deck Load (metric tons
Transit	5,000
Operating	5,000
Survival	5,000
Deck Icing	500

Maximum Storage Capacities

	Capacity	Unit			
Drill Water	15,000	bbls.			
Potable Water	4,000	bbls.			
Fuel Oil	22,500	bbls.			
Liquid Mud	5,500	bbls.			
Bulk Mud	708 25,000	cu. meters cu. feet			
Bulk Cement	283 10,000	cu. meters cu. feet			
Sack Storage	12,000	sacks			

Draft and Displacement

Condition	Draft (meters)	Displacement (metric tons)		
Transit	12.7	33,100		
Drilling	29	45,000		
Survival	24	41,200		

Principal Particulars

-	Length (meters)	Breadth (meters)	Depth (meters)		
Machinery					
Deck	75	75	8		
Pontoons	96.4	15	13		
Column					
Spacing	62	62			
	Pontoons (meters)	Deck (meters)	Length (meters)		
Column					
Size	15	13	27		

SEVERE ENVIRONMENT SELF-PROPELLED SEMISUBMERSIBLE

The Honry Goodrich represents a new generation of semisubmersible designed to meet the growing needs of the offshore industry in severe and arctic climates worldwide. The twin hull, self-propelled semisubmersible is a world class vessel, capable of drilling in any environment with a maximum of safety and personnel comfort.

The flexible operating characteristics of the unit include the ability to drill in three different modes: resting on the seabed in shallow water depths, conventionally moored in depths to 610 meters, or dynamically positioned in 3,050 meters of water.

A high variable capacity of 5,500 metric tons allows the Goodrich to move on location, drill and complete an average well without resupply.

ACCOMMODATIONS

The Henry Goodrich is designed with the utmost in crew safety and comfort in mind. Up to 150 people can be accommodated in one and two man rooms, each with a private bath. To insure high crew morale during long winter months in northern latitudes, crew facilities are designed to include a gymnasium, sauna, whirlpool, cinema, electronic game room, and four recreation rooms.

SAFETY EQUIPMENT

All safety equipment meets the latest requirements of national authorities. Lifeboat platforms are covered to prevent icing and to allow for timely, safe debarkation in extreme conditions.

Large warehouses and other storage areas are arranged to facilitate loading from either side of the platform.

CENTRALIZED CONTROL AREAS

The bridge, ballast control, and electrical control areas are centralized to minimize supervisory personnel requirements. In addition to modern navigation and communications equipment, the Goodrich employs a computer based monitoring and control system with capabilities ranging from power management and engine alarm monitoring to inventory control and satellite data transmission. Multiplexed control signals are transmitted over fiber optics to eliminate electrical interference.

POWER GENERATION

The rig power package comprises eight large bore, medium speed four cycle diesel engines with a combined generating capacity of approximately 37,400 KW. The engines operate well under minimum loads and have efficient fuel consumption rates, two essential characteristics for a dynamically positioned rig. The diesets are capable of burning heavy fuels or high sulfur fuels. Engine waste heat can be recycled in colder climates to generate steam, and assist in making potable and drill water, and preheating fuel.

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MUD SYSTEM

The mud system will accommodate both water based and oil based muds. The state-of-the-art system includes provisions for five shale shakers, two centrifuges, and three slush pumps. Enclosed mud pits can handle 5,500 barrels of liquid mud.

BOP HANDLING SYSTEM

The BOP house is arranged for two 18³/₄ inch, 15,000 psi guideline or guidelineless BOP's. The overhead handling equipment is designed to lift the BOP stack in one piece. A special moveable guide structure provides controlled recovery of the BOP through the splash zone to the drill floor. Because the stack is deployed through the drill floor, the integral rotary table and riser spider are mounted to skid quickly out of the way. Ten riser tensioners, with a total capacity of 1.6 million pounds, are enclosed to simplify winterization and maintenance problems. The riser rack can accommodate more than 10,000 feet of air can or syntactic foam riser in 75 foot joints.

MOORING SYSTEM

The platform mooring system employs vertical shaft type windlasses. This design allows the operator and all machinery to work below decks. Only the chain and wildcat are exposed to the outside environment.

OTHER FEATURES

The drill floor, BOP enclosure, pipe rack and heavy tool store are located on the same deck level to allow easy access to the drill floor. Bridge cranes over both the riser and pipe racks insure safe handling of tubulars in severe sea states.

Sheltered access from below decks facilitate simple transfers of equipment and enable rig personnel to work efficiently in a shirt sleeve environment year round.

The deep draft and efficient design of the pontoons and columns provide exceptional motion characteristics in any sea state. Dynamic positioning capabilities and ice strengthened columns and pontoons enable the Goodrich to extend its drilling season in arctic regions.

The Henry Goodrich is under construction at Mitsui Engineering and Shipbuilding's Tamano Works, and will be delivered on July 18, 1985.



ODECO has pioneered the design and development of mobile offshore drilling equipment since its founding in 1953.

The company's first unit, the submersible drilling barge Mr. Charlie, was a significant contribution to a fledgling industry in 1954. In 1963 ODECO designed and built the Ocean Driller, the world's first column-stabilized semi-submersible, to meet the challenge of drilling in water depths beyond the capabilities of bottom-supported units. These units continue in service today.

To satisfy the demand for improved transit time ODECO produced a series of parallel-hulled semi-submersibles which pioneered development of the North Sea. In 1971 ODECO made still another significant contribution to offshore rig development by designing and building the Ocean Prospector, the world's first semi-submersible to incorporate a propulsion-assist system.

Today ODECO operates one of the largest and most versatile fleets of offshore drilling units in the world. Balanced in class and geographic distribution, the company's 39 unit fleet consists of six submersibles, 16 semi-submersibles, 12 jack-ups, and five drillships, operating in most of the world's major offshore drilling theaters.



MR. CHARLIE

Drilling pioneers.]

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ODECO's commitment to develop the technology to meet the challenges of a dynamic industry will insure a leadership role in the years ahead.

Reflecting this commitment the Company currently has under construction two severe environment semi-submersibles: a conventionally moored unit, at Sumitomo Heavy Industries in Oppama, Japan, and a dynamically positioned unit at Scott-Lithgow in Greenock, Scotland. These units are due to be delivered in early 1983 and mid-1984, respectively.

To meet the personnel demands of rapid expansion and technological advancement, ODECO has developed a comprehensive rig training and safety program. This program combines the benefits of in-house government-approved classroom instruction, involving rig floor simulation equipment and specifically designed text, with onthe-job training administered by supervisory personnel and industrial relations representatives aboard the individual rigs. A series of outside schools provide further technical training for senior operations personnel.

In recent years ODECO has emerged as a significant energy producer with interests in oil and gas production in the Gulf of Mexico, offshore Gabon in West Africa, and in the North Sea. Company exploration programs are underway in these and other areas worldwide. Additionally, the company participates in the diving industry through its 50% ownership of Sub Sea International and in the insurance industry through Mentor Insurance I imited. The dynamically positioned drilling unit currently under construction at Scott-Lithgow, Greenock, Scotland, is the first of a new generation of deep-water, severe environment semi-submersibles. The rig will be constructed and operated under a joint venture arrangement involving Ben Odeco Limited, a 50% owned ODECO company, and the British National Oil Corporation.

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The vessel will be a 390' long and 231' wide, twin hull design with a 32,000 horsepower dynamic positioning system. The hull will consist of 2 ship-shape parallel pontoons which will enable a calm water transit speed of 10 knots. The rig will be a U.K. flagged vessel fully certified by the United Kingdom Department of Trade and Industry, and classed ABS-AMS A-1 for unrestricted worldwide ocean service. The rig's structure is designed to simultaneously withstand 100 knot winds, a 3-knot current and 110' waves. The design criteria for continued operations in a D/P mode are the simultaneous effects of 65 knot winds, gusting to 81 knots, a 2-knot current and a 26' significant wave height.

The rig will accommodate 110 men in its living quarters and will drill at the 81.5' draft in water depths to 4,500'. It will also be equipped with a conventional mooring system consisting of 8 windlass units equipped with 5,500' of 31/4" special strength chain per windlass for operating in water depths to 1,500'. Drilling depth capability will be 25,000'. Three revolving cranes will service the main deck and peripheral areas and the rig will have a riser handling system to handle the marine riser in extreme wind and sea conditions.

The drilling equipment will inelude a detrick rated at 1,400,000 lbs. static hook load, a 4-speed, 3,000 horsepower drawworks assembly, a 49½ " 1,200 horsepower rotary, and 2 triplex mud pumps each driven by 2 - 850 horsepower DC motors. Well control equipment will include an 18³/₄" x 15,000 psi WP BOP stack. Power will be supplied by 4 turbocharged 12 cylinder (7,415 continuous brake horsepower) engines and 2 turbocharged 6 cylinder (3,707 continuous brake horsepower) engines. Each of these engines is capable of operating on either diesel or heavy fuel oil. DC power for rig service is provided through an AC switchboard and SCR drive system. All equipment and systems are designed for service temperatures down to -20 degrees Centigrade.

CAPACITIES

Bulk Storage	
Liquid Mud	4,100 Bbls.
Sack Storage	
Heavy Fuel Oil	16,000 Bbls.
Diesel Fuel Oil	6,500 Bbls.
Drill Water	16,400 Bbls.
Potable Water	1,450 Bbls.

Ben Odeco/BNOC DP Semi



Delivery in mid-1984.

APPENDIX B

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API DRILL PIPE/DRILL COLLAR DATA

String at the state

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Dimensions and Data															
Dimensions ⁴⁴ and Data On Tool Joint Pin and Box Threaded Connections															
	1					THREAD DATA		THEORETICAL PROPERTIES OF PIN AT GAGE POINT				Radisl	Radia		
Maminal		Conn.	PIN BORE		Pitch Diam. at Gage	No.	Taper per arts Feet on		Tension		Polar Section	0.D.	Diam. of Counterbore	Width of Box Shoulder Batara	Width of Bez Shoulder
Size Inches	Type of Connection	0.D. Inches	i.D. Inches	Area Sq. Ins.	Point Inches	per Inch	Diam. Inches	Thread Form	Area ¹ Sq. Ins.	Point Lbs.	Modulus Cu. Ins.	at Base Inches	at Shouider inches	Beveling inches	Face Inches
2%	Slimine H 90 HC26(Int. Flush)	3% 3%	14 14	3.126 2.405	2.578	3 4	1%	Mod. H90 V.038R (V .065)	2250	270,040 313,680	2.140	2.625 2.876	24%s 21%s	.242 .219	171
	Slimine H 90	3162	215	3.634	3.049	3	14	Mod. H90	3.206	384,675	3.622	3.096	34%	.320	7 5.202
236	NC31 (Int. Flush)	3% 4%	1%	2.405 3.547	2568 3.183	4	2	(V.065) V.038R (V.065)	2.614	313,680 447,125	2.444 4.217	2.876 3.391	215/28 329/44	.219 .336	164
	Stimline H 90	4%	7%	5.673	1588	3	156	Mod. H90 V.038R	14.450	533,950	5231	3.735	3%	.375	.281
31/2	Fell Hele	5 4%	2%	3.547 3.547 3.547	1.734	5	3.	(V .065) V .040 V .065	6.642 -5.623	797,025 698,800	8.062 6.932	3.391 3.994 3.812	444	.330 .477 .438	-311 -311
	HC38 (Int. Flush) H 50	4% 5%	24	5.673 5.940	1.506	4 31⁄2	2	V.038R (V .065) H90	4.894 5.526	587,300 663,125	6.897 8.013	4.016 4.000	4%4	.336 .531	396
	Sim Hole	4%	7/1	4.666	1604	4	2	V .065 V.038R	4.703	564,425	6.084	3.812	3%	.375	-234
·	HC46 (Int. Flush)	574 6 574	7% 7%	6.213 8.296 6.213	4.872 4.826 4.304	4 34		(V.065) V.038R (V.065) H90	7.510	901,150 913,475	12.843 11.572	4.280 4.834 4.375	419/2 419/2 49/14	453 .547 469	
· ·	Fell Hale	6		7.069	4532	5	.3.3	V 040	8.135	976,150	13.108	4.792	4%	563	.622
4 14	HC46(XTRAHOLE)	6% 6%	3% -3%	8.296 11.045	4.625	4	2	V .038R (V .065) V .038R (V.065)	7.510	901,150 \$39,100	12.843 15.203	4.834 5.250	4 ²⁹ /m 54/m	.672 .531	.407 _305 =
		6	34	8.296	-4.638 .	31/2	2	H90 V .038R	7.818	938,150	13,411	4 70 9	48/12 SM-	555	414
544	Fall Hain	7		12,566	5,591		2	(V.065)	10 548	1 365 800	77 (84	5 825	518/	547	405
6%	Regular API	7 3 6 8	34 5	14 756 19 635	5.758 6.320	4	7	V .050 V .050	14.939 12.074	1,792,600 1,448,900	29.065 31.056	5.992 6.753	5714 8 ^{17/12}	. <u>844</u> 578	,633 434

Connection types connected by brackets are interchangeable (i.e., will screw together without interference).

* Tanave yverd point of material 120,000 ps * 3 % * 0.0. optional

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1.8 1_ * 1 995 bore available for light w ngint once

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	16 60	86 71	3.826	* 8 B	4 407 3 966 3 526	4 500	6/1.4 6//2:4	286.5 257.8 229.2	410.7 376.0 335.0	374.6 337.1 299.7	440.7 396.6 352.6	528.8 475.9 423.1	661.0 594.9 528.9	19580 17580 15610	26700 23970 21290	37370 33550 29800	48050 41140 38320
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	21 90		9// 9	3 8 B	5 828 5.245 4 662	5.500 5.432 5.363	5.1/2 5.7/15 5.23/64	378.8 340.9 303.0	553.7 498.3 422.9	495.4 4.254 396.5	502.0 524.5 466.2	699.4 629.4 559.4	674.2 786.8 699.3	32220 28940 25680	43940 39460 35020	61520 55240 49020	79100 71060 63030
-	8 R	22 54	4 670	1 8 8 1 8 8	6 630 5 967 5 304	5.500 5.423 5.423	5-1/2 5-27/64 5-21/32	421.0 367.9 344.0	629.9 566.9 503.9	543.4 507.2 450.0	663.0 596.7 530.4	795.6 716.0 636.5	994.5 895.0 795.6	35950 32290 28620	49020 44030 39030	68630 61650 54640	68240 79280 70260
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	15 50	STD.	+5/1	2	15.7	1	-						-	140	+3/8	11.2	10.8
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s	96°31	206	4. 408 4. 776	66721 66721	6.60	3.000	3-3/4	1-3/4	: : : :	:::	· · ·	:::	9.60	 5. 10	3-11/16
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Make-up Torque for Tool Joint Connections

Recommended Minimum OD* and Make-up Torque of Weld-on Type Tool Joints Based on Torsional Strength of Box and Drill Pipe

		DATA	N	EW TOOL .	IOINT DATA			PRI	EMIUM CLA	55		CLASS 2	
Nom. Size	Nom. WL ib'ft	Type Upset and Grade	Conn.	New OD	New ID in.	Torsional Yield Strength ft-Ib	Maka-Up Torque fi-lb	Min. OD Tool Joint in.	Min. Box Shoulder With Eccentric Wear in.	Make-Up Torque For Min. OD Tool Joint tt-lb	Min, OD Tool Joint in,	Min. Box Shoulder With Eccentric Wear In.	Make-Up Torque For Min OD Tool Joint R-Ib
5	19.50	I.E.U. 75	API NC50(X.H.)‡	6-3/8	3-3/4	37700	18900	5-7/8	15/64	15800	5-25/32	3/16	13300
	19.50	I.E.U. 95	API NC50(X.H.)‡	6-3/8	3-1/2	44900	22400	6-1/32	5/16	20200	5-29/32	1/4	16700
	19.50	I.E.U. 105	API NC50(X.H.)‡	6-1/2	3-1/4	51400	25800	6-3/32	11/32	21900	5-31/32	9/32	18400
	19.50 19.50	I.E.U. 135 I.E.U. 135	API NC50(X.H.)‡ 5-1/2 F.H.	6-5/8 7-1/4	2-3/4 3-1/2	63400 72500	31800 36300	6-5/16 6-3/4	29/64 3/8	28400 288()	6-1/8 6-19/32	23/64 19/64	22900 23400
	25.60 25.60	I.E.U. 75 I.E.U. 75	API NC50(X.H.)‡ .5-1/2 F.H.	6-3/8 7	3-1/2 3-1/2	44900° 62200	22400 31500	6-1/32 6-1/2	5/16 1/4	20200 20200	5-29/32 6-3/8	1/4 3/16	16700 16100
	25.60 25.60	I.E.U. 95 I.E.U. 95	API NC50(X.H.)‡ 5-1/2 F.H.	6-1/2 7	3 3-1/2	57000 62200	28600 31500	6-3/16 6-21/32	25/64 21/64	24700 25500	6-1/32 6-1/2	5/16 1/4	22000 20200
	25.60 25.60	I.E.U. 105 I.E.U. 105	API NC50(X.H.)‡ 5-1/2 F.H.	6-5/8 7-1/4	2-3/4 3-1/2	63400 72500	31800 36300	6-9/32 6-23/32	7/16 23/64	27500 27700	6-1/8 6-9/16	23/64 9/32	22900 22300
	25.60	I.E.U. 135	5-1/2 F.H.	7-1/4	3-1/4	77700	38900	6-15/16	15/32	35500	6-3/4	3/8	28800
5-1.2	21.90	I.E.U. 75	F.H.	7	4	56300	28000	6-15/32	15/64	19200	6-3/8	3/16	16200
	21.90	1.E.U. 95	E.H.	7	3-3/4	62200	31500	6-5/8	5/16	24500	6-1/2	1/4	20300
	21.90	I.E.U. 105	EH.	7-1/4	3-1/2	72500	36300	6-23/32	23/64	27700	6-9/16	9/32	22400
	21.90	I.E.U. 135	EH.	7-1/2	3	86800	43700	6-15/16	15/32	35500	6-3/4	3/8	28800
	24.70	I.E.U. 75	EH.	7	4	56300	28000	6-17/32	17/64	21300	6-7/16	7/32	18200
	24.70	I.E.U. 95	EH.	7-1/4	3-1/2	72500	36300	6-23 32	23/64	27700	6-9/16	9/32	22400
	24.70	I.E.U. 105	EH.	7-1/4	3-1/2	72500	36300	6-25/32	25/64	29900	6-5/8	5/16	24500
	24.70	I.E.U. 135	EH.	7-1/2	3	86800	43700	7-1/32	33/64	39000	6-27/32	27/64	32100

The use of outside diameters (OD) smaller than those listed in the table may be acceptable on Sum Hole (SH) tool joints due to special service requirements.

Tool joint with dimensions shown has a lower torsional yield ratio than the 0.80 which is generally used. Recommended make-up torque is based on 72,000 psi stress.

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Tool joint diameters specified are required to retain torsional strength in the tool joint comparable to the torsional strength of the attached drill pipe. These should be adequate for all service. Tool joints with torsional strengths considerably below that of the drill pipe may be adequate for much drilling service. Tool joint diameters specified are recommended by API Spec 7.

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Minimum OD, for box shoulder, and makeup torque values listed were determined using the following criteria:

Calculations for recommended tool joint makeup torque are based on the use of a thread compound containing 40-60% by weight of finely a. b. In calculation of torsional strengths of tool joints, both new and worn, the bevels of the tool joint shoulders are disregarded.
 c. Premum Class Drill String is based on drill pipe having uniform wear and a minimum wall thickness of 80%.

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Class 2 Drill String allows drill pipe with a minimum wall thickness of 65° , with all wear on one side. The tool joint to pipe torsional ratios that are used here (≥ 0.80) are recommendations only and it should be realized that other combinations of dimensions may be used. A given assembly that is suitable for certain service may be inadequate for some areas and over-designed for others