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A New Approach to Database Logic

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1 Introduction

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In this paper we propose a mathematical framework for unifying and generalizing the three principal data models, i.e., the relational, hierarchical and network models ([U]). Until recently most work on database theory has focussed on the relational model ([C1]), mainly due to its elegance and mathematical simplicity compared to the other models. Some of this work has pointed out various disadvantages of the relational model, among them its lack of semantics ([C2], [HM], [SmSm]) and the fact that it forces the data to have a flat structure that the real data does not always have.

Several recent papers have addressed this problem by trying to find a more general math-

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‡ This work was done while this author was at Stanford University and supported by a Weismann Fellowship and AFOSR grant 80-0212. ematical framework. Specifically, Jacobs [J] describes "database logic," a mathematical model for databases that claims to generalize all three principal data models. Also, Hull and Yap [HY] describe the "format model." In their model, they view database schemes as trees, where each leaf represents data, and each internal node represents some connection between the data.

Both these models are unsatisfactory in their ability to restructure data, i.e., the ability to query the database. While Hull and Yap ignore the issue of a data manipulation language, Jacobs' treatment is an overkill—his query language enables one to write noncomputable querics [V].

Furthermore, both approaches fail to model a significant aspect of hierarchical and network database management systems, which is the ability to use virtual records. Virtual records are essentially pointers to physical records, and they are used to avoid redundancy in the database [U]. Note that virtual records introduce cyclicity not only in the schema level but also at the instance level.

In the model we propose here a database scheme is an arbitrary directed graph. As in the format model, leaves (i.e., nodes with no outgoing edges) represent data, and internal nodes repre-

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Figure 2 Format Representation of Fig. 1.

Example 1. Assume we are given the *PER-SON-PARENT* relation shown in Fig. 1. We can represent the structure of this relation in the format model by the format in Fig. 2. This format has two nodes u and v of type \Box that correspond to the attributes of the relation, and one node w of type Ω that connects the pairs of related attributes.

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An instance of this format will be an assignment of values to each node., as follows. We shall use the notation I(u) to mean the set of values assigned to the node u by the instance I. We could just take as the instance of a node a set of elements from the underlying domain, or tuples or sets taken from the instance of the node's successor. If we were to use this approach, we would not be able to deal with cycles in the format, and even if the format were acyclic, we would lose the ability to represent pointers to other nodes in our model, since the data would be represented explicitly at each node. What we do instead is have the instance of each node consist of a set of l-values, with corresponding r-values.

Intuitively, r-values constitute the data space, and the l-values constitute the address space. The instance of a node consists of set of l-values, with an r-value assigned to each of them. Formally, the l-values are elements of a fixed set L (usually taken to be the natural numbers). We require that the instances of different nodes be disjoint. We also have a function r on L, that assigns *r*-values to these l-values, and we require that the *r*-values be of the correct form, depending on the type of the node.

Definition 2. An instance of a schema $S = \langle G, \mu \rangle$ consists of a mapping I from V to $P^{fin}(L)$ (all finite subsets of L), and a mapping r from $\bigcup_{v \in V} I(v)$; r maps l-values to their r-values. If $v \neq w$, then I(v) and I(w) must be disjoint. For each node v in G, I(v) must satisfy

- (1) If $\mu(v) = \Box$, then for each $l \in I(v)$, r(l) must be in D.
- (2) If μ(v) = □ and v₁,..., v_n are the successors of v, then for any l ∈ I(v), r(l) must be a tuple (l₁,..., l_n), such that for each i between 1 and n, l_i is an element of I(v_i). An l-value in I(v_i) can appear in any number of tuples, including none of them.
- (3) If $\mu(v) = O$ and \tilde{v} is v's successor, then r(l)must be a subset of $I(\tilde{v})$.

If l is an l-value, r(l) is called the r-value of l.

<i>I</i> (u)			I(v)		I(w)		
l	r(l)	l	r (l)	ı	r(l) .		
1	Rehoboam	4	Solomon	8	(1,4)		
2	Solomon	5	David	9	(2,5)		
3	David	6	Batsheba	10	(2,6)		
	•	7	Jesse	11	(3,7)		

Figure 9 I	nstance for	the First	Examp	le
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sent connections between the data. While it is not hard to model cyclicity at the schema level, it is not quite apparent how to do it at the instance level without running into cyclic definitions. Our solution is to keep the obvious distinction between memory locations and their content. Thus, instances in our model consists of *r*-values, which constitutes the data space, and *l*-values, which constitutes the address space. This mechanism enables us to give semantics to instances in a welldefined way.

A data model consists of several components (see [TL]). The first is the database structure mentioned above which describes the static portion of the database. The second component is a way to specify integrity constraints on the database, that restrict the allowed instances of the schema. We shall describe a logic in which integrity constraints can be specified. Unlike Jacobs' logic, our logic is effective. That is, given a database and a sentence in the logic, one can test effectively whether the sentence is true in the database or not.

The third component will be a way to restructure data, in order to describe user views, query languages, etc. We describe two such mechanisms, a logical, i.e., non-procedural, query language and an algebra, i.e., procedural, query language that are analogous to Codd's tuple calculus and relational algebra, and we prove them equivalent. These languages have a novel feature: not only can they access a non-flat data structure, i.e., a hierarchy, but the answers they produce do not have to be flat either. Thus, the language really does have the ability to restructure data and not only to retrieve it.

2 The Format Model

In our model, a schema is an arbitrary directed graph, with a type associated with each node. These types can be as follows.

- (1) Basic type, written \Box . Nodes of this type contain the data stored in the database.
- (2) Composition, written . Nodes of this type contain tuples whose components are taken from the successors of the node.
- (3) Collection, written O. Nodes of this type contain sets, all of whose elements are taken from the node's successor.

Formally,

Definition 1. A schema is a directed graph G, together with a function μ that assigns a type to each node of G. μ is a function from V, the set of nodes of G, to the set $\{\Box, O, \bigcup\}$. $\mu(v)$ can be \Box only when v has no successors; It can be \bigcirc only when v has at least one successor; \bigcirc only when v has exactly one successor.

For each node v of type \bigcirc we have an ordering of its successors, so that we can refer uniquely to "the kth successor" of v. Note that we do not have pointer types explicitly. However if we wanted them in the model, we could describe them as \bigcirc -nodes with exactly one successor.





Figure 4 Hierarchy for the Genealogy.

I(u)			I(w)	I(v)		
l	r(l)	l	r(l)	l	r(l)	
1 2 3 4 5	Rehoboam Solomon David Batsheba Jesse	6 7 8	{2} {3,4} {5}	9 10 11	(1,6) (2,7) (3,8)	

Figure 5 Instance of the Format in Example 2.

In Fig. 3 we show an instance of the format in Fig. 2 corresponding to the data in Fig. 1.

Example 2. We could also be given the genealogy as a hierarchy, as shown in Fig. 4. This could be represented in the format model as the format in Fig. 4, with the instance in Fig. 5. In general, given a hierarchy, we can convert it to a hierarchy as follows. Let R_1, \ldots, R_n be the nodes in the hierarchy (the logical record types). For each R_i we have a corresponding \square -node v_i in the format. For each field of the logical record type R_i , v_i has one successor of type \square . The links are represented as follows. If L_i is a link in the hierarchy, with owner R_j and member R_k , we have in the format a node w_i of type \bigcirc , that is a successor of R_k , and whose successor is R_j .



Figure δ Another Representation of the Genealogy.

I(u)		I(v)		I(w)		
ŀ	r(l)	L	r(l)	1	r(l)	
1	Rehoboam	6	(1,11)	11	{7}	
2	Solomon	7	(2, 12)	12	{8,9}	
3	David	8	(3, 13)	13	{10}	
4	Batsheba	9	(4, 14)	14	Ø	
5	Jesse	10	(5, 14)		•	

Figure 7 Instance of the Format in the Figure 6.

Example 3. We can also use the format model to represent data structured in ways that do not correspond to any of the standard data models. For example, we could represent the genealogy by the format in Fig. 6, and the instance in Fig. 7.

3 Logic

We define a calculus on formats in two stages. In this section we define a logic on formats. Then in the next section, we use this logic to define queries on formats. These queries will correspond to tuple calculus expressions in the relational model. We can also use the calculus to describe integrity constraints in the database.

Each variable in our logic has a fixed sort, where the sorts are nodes in the graph. The sorts restrict the possible values the variable may take. For example, if x is a variable of sort v, x can take only values in I(v). In future, we will usually subscript the variable with its sort, e.g., x_v . Though the values of variables are always l-values, we shall say "the l-value of x_v " when we mean the value of x_v , and "the r-value of x_v " when we mean the r-value of the value of x_v .

Definition 3. An atomic formula is one of

- (1) $x_v \pi_t y_w$, meaning that the l-value of x_v is the t^{th} component of the r-value of y_w .
- (2) $x_v \in y_w$, meaning that the l-value of x_v is a member of the r-value of y_w .
- (3) $x_v =_l y_w$, meaning that the l-values of x_v and y_w are equal.
- (4) x_v =_r y_w, meaning that the r-values of x_v and y_w are equal.
- (5) $x_v = r d$, where d is an element of the domain D, meaning that the r-value of x_v is d.

We then define well formed formulas in the usual way. $\models_I \phi(l_1, \ldots, l_n)$ will mean that ϕ is satisfied by l_1, \ldots, l_n in the instance *I*. This is defined as follows.

Definition 4. Let $\phi(x_{v_1}^1, \ldots, x_{v_n}^n)$ be a formula with free variables $x_{v_1}^1, \ldots, x_{v_n}^n$. Let l_1, \ldots, l_n be l-values, where for each $i, l_i \in I(v_i)$. Then $\models_I \phi(l_1, \ldots, l_n)$ is defined by induction on the size of ϕ , as follows.

(1a) If ϕ is $x_v^i \pi_t y_w^j$, then $\models (x_v^i \pi_t x_w^j)(l_1, \ldots, l_n)$ iff w is of type \bigcap with at least t successors, and $l_i = \prod_t (l_j)$.

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- (1b) If ϕ is $x_v^i \in x_w^j$, then $\models (x_v^i \in x_w^j)(l_1, \ldots, l_n)$ iff w is of type \bigcirc and l_i is an element of $r(l_j)$.
- (1c) If ϕ is $x_v^i =_l x_w^j$, then $\models (x_v^i =_l x_w^j)(l_1, \ldots, l_n)$ iff $l_i = l_j$.
- (1d) If ϕ is $x_v^i = r x_w^j$, then $\models (x_v^i = r x_w^j)(l_1, \ldots, l_n)$ iff $r(l_i) = r(l_j)$.
- (1e) If ϕ is $x_{\phi}^{i} = r d$, where d is an element of D, then $\models (x_{\phi}^{i} = r d)(l_{1}, ..., l_{n})$ iff $r(l_{i}) = d$.

- (2) If ϕ is $\phi_1 \lor \phi_2$ or $\neg \phi_1$, then the definition is the usual one.
- (3) If ϕ is a formula with free variables $x_{v_1}^1, \ldots, x_{v_n}^n$, and y_w , then

 $\models ((\exists y_w)\phi)(l_1,\ldots,l_n)$

iff there is an l in I(w) such that

$$\models \phi(l_1,\ldots,l_n,l).$$

Example 4. The formula $x_u \pi_1 y_v$ says that the l-value of x_u is equal to the first component of the r-value of y_v . It is satisfied in the instance of Example 3 by the (x_u, y_v) pairs (1,7), (2,8), (3,9), (4,10), and (5,11).

Lemma 1. If $\phi(x_{v_1}^1, \ldots, x_{v_n}^n)$ is a formula with free variables $x_{v_1}^1, \ldots, x_{v_n}^n$, and l_1, \ldots, l_n are *l*-values, where for each *i*, $l_i \in I(v_i)$, then $\models_I \phi(l_1, \ldots, l_n)$ can be determined effectively.

Proof: This is shown by induction on the size of the formula. For atomic formulas testing for satisfaction is straightforward. Testing for disjunction and negation is also clearly effective, and the result for quantification follows from the fact that all instances are finite.

4 Queries

In the relational model the result of a query is a relation. We might therefore in analogy expect that the result of a query on the format model will be a format, i.e., a schema and an instance of it. This approach generalizes the relational algebra approach and may also suggest query languages for the other data models.

We modify this approach a bit by not requiring that the query's schema be an independent schema, but we allow the successors of nodes in the query to be nodes in the database. One reason for this is that we may want our answer to have references to the database rather than copies of large structures. Another reason is to simplify the definitions of the algebraic operations. We shall want each algebraic operation to be the result of some query, but on the other hand we would like to be able to simulate an arbitrary "safe" query by a sequence of algebraic operations, and if each operation had to create a completely new format, the definitions would be unnecessarily complicated. Notice that if the query were a "normal query," i.e., one which created a completely new structure, the corresponding algebraic operations would first copy the required nodes, and then would combine l-values only from these new nodes.

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The natural thing to do now, using the analogy with the tuple calculus in the relational model, is to take some formula ϕ and let the instance be those things satisfying it.

There are two problems with this approach. The first is that the queries cannot build the lvalues by themselves—such a formula just says when a given instance satisfies it, but gives no way to construct such an instance. One solution is to prevent the query from referring directly to l-values, and allow them to be referred to only by their r-values. We could then find all possible rvalues than could appear in the result, assign them arbitrary l-values, and try to show that the result is unique up to isomorphism.



I	1 (U)	I	ו (ש)
l	r(l)	1	r(l)
1	(3)	3	(1)
2	(4)	4	(2)

Figure 9 A Possible Result of the Query

I	2(U)	I	2(v)
l	r(l)	l	r(l)
1	(3)	3	(2)
2	(4)	4	(1)

Figure 10 Another Possible Result of the Query.

Another problem with this approach is dealing with cyclicity. We need the ability to refer directly to l-values in order to make use of the cyclicity, but even then the result of the query will not always be defined uniquely. For example, if the query schema is the format in Fig. 8, and the query just specifies that I(u) and I(v) each contain at least two different l-values. Then Fig. 9 and 10 shows two incomparable instances, and we have no way to choose between them. Our solution has been to restrict the queries to ones not containing cycles, while allowing cyclicity in the database, and allowing the query to refer explicitly to l-values in the database.

The formal definition of a query is

Definition 5. Given a database schema $S = \langle G, \mu \rangle$, and an instance I, a query $Q = \langle S', \Phi \rangle$ on the database consists of

- (1) A set of nodes and directed edges with types associated with each node, $S' = \langle G', \mu' \rangle$, such that
- (a) G' is a DAG, and edges can also connect nodes of G' to nodes of G.
- (b) $(G \cup G', \mu \cup \mu')$ is a schema, which we shall call $S^* = \langle G^*, \mu^* \rangle$.

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- (2) The fact that G' is a DAG implies that there is an order ≺ on the nodes of G', such that if v and w are nodes of G' and v is a successor of w, then v ≺ w. Let ≺ be a fized ordering of the nodes with this property.
- (3) Φ is a set of formulae, one for each node v of G'. The formula ϕ_v corresponding to v must satisfy
- (a) There is only one free variable in ϕ_v , and it is of sort v.
- (b) All other variables are bound, and their sorts are either nodes of the database, or are nodes that precede v under ≺.

Since the query is now acyclic, we can create the result of the query "bottom-up," i.e., we define the result of the query at each node in terms of the results at its successors. We define the result of the query by the following inductive construction. Assume that I(w) has been defined for all nodes w in the query that precede v under \prec . We then say that r is a candidate r-value for v if by setting r(l) = r, and letting I(v) contain the single l-value l, we get $\models_I \phi_v(l)$ (l is an arbitrary unused l-value). The construction of I(v) is as follows. Let R be the set of all candidate r-values for v. For each $\tau \in R$ arbitrarily select a different unused l-value l_r , set $r(l_r) = r$, and let I(v) contain of all these l-values. Repeat this for each node v in the order given by \prec .

We now give the formal definition of the result of a query. We start with the definition of candidate r-value.

Definition 6. Let $\phi_v(x_v)$ be a formula with free variable x_v and let I be an instance of some of the nodes in the format, including the sorts of all the bound variables in ϕ_v . Let l be an l-value that is unused in I. We say that τ is a candidate r-value for v if by setting r(l) = r, we get $\models_{I \cup \{l\}} \phi_v(l)$. Let R be the set of all candidate r-values for v. For each $r \in R$, select a different unused l-value l_r (the choice of l-values is arbitrary), and set $r(l_r) = r$. Then $[l \mid \phi_v(l)]$ is defined to be $\{l_r \mid r \in R\}$.

Lemma 2. In Definition 6, assume that R is finite. Then if I(v) is defined to be $[l | \phi_v(l)]$, the following hold.

- (i) For each l in I(v), $\models_I \phi_v(l)$.
- (ii) If we take different unused l-values in the definition, we get an isomorphic instance I'.
- (iii) There are no two different l-values in I(v), $l_1 \neq l_2$ with $r(l_1) = r(l_2)$.
- (iv) I(v) is maximal satisfying (i)-(iii).

Definition 7. The result of the query is an instance I^* of the schema S^* . It is defined by induction as follows. If v is a node of the database, we define $I^*(v) = I(v)$. If v is a node of the query, assume that we have already defined $I^*(w)$ for any node w that precedes v under \prec . Then $I^*(v)$ is defined as $[l | \phi_v(l)]$.



Figure 11 Query on the Genealogy Database.

I(u')
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l	r (l)
17	Rehoboam
18	Solomon
19	David
20	Batsheba
21	Jesse

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Example 5. Assume that the database is the genealogy format of Fig. 6 with the instance of Fig. 7. The query will consist of the node u' in Fig. 11, with formula $\phi_{u'}(x_{u'}) = (\exists y_u)(x_{u'} = r, y_u)$. In other words, we want I(u') to be a copy of I(u) (removing duplicated values, if I(u) had any). To answer the query we do the following. First, take an unused l-value, say 17. Now look for all possible r-values r (in this case, elements of D), such that if we set r(17) = r, and $I(u') = \{17\}$, we get $\models_I \phi_{u'}(17)$. The set R of candidate r-values is $R = \{\text{Rehoboam}, \text{Solomon}, \text{David}, \text{Batsheba}, \text{Jesse}\}$, and therefore the result of the query (up to isomorphism) is as shown in Fig. 12.

Definition 8. A query Q on a database with schema S is safe if for every instance I of S the result of the query exists.

The following lemma shows that to check if a query is safe, it suffices to check the results at the leaves.

Lemma 3. A query Q on database schema S is safe iff for every instance I of the database, and for every node v of the query of type \Box , the set of candidate r-values for v is finite.

Lemma 4. Let Q be a query on a database with schema S, and let w_1, \ldots, w_n be the nodes in the database of type \Box . Q is safe iff if there is a finite set $\{d_1^*, \ldots, d_k^*\}$ of elements of D such that

for every instance I of the database S, and for every node v of type \Box in the query Q, all of the candidate r-values for I(v) are either r-values of elements of the $I(w_i)$'s or are among the d_j 's.

The constants in the above lemma are those elements of D that are mentioned in any of the formulas ϕ_v .

5 Algebra

We now define an algebraic query language. This language is equivalent to the logical query language. That is, each logical query is equivalent to a logical query and vice versa.

The algebraic language consists of the following basic operations:

- w ← v creates a new node w of the same type as v, and with the same successors as v. I(w) contains a copy each l-value in I(v).
- (2) $w \leftarrow \Box(d)$ creates a node w of type \Box , that contains a single l-value, whose r-value is d.

Example 6. Let the database be the genealogy of Fig. 6 with the instance of Fig. 7. The operations $u' \leftarrow \Box(u)$ and $v' \leftarrow (\text{"Absalom"})$ each add a new node u' and v' respectively to the database. Their instances are shown in Fig. 13 (a) and (b).

I(u')			I(v')
l	r(l)	l	r(l)
17	Rehoboam	17	Absalom
18	Solomon		•
19	David		
20	Batsheba		
21	Jesse		

Figure 13 Examples of (a) $u' \leftarrow u$ (b) $v' \leftarrow \Box(d)$.

(3) w ← O(v) creates a new node w of type O with successor v. I(w) contains a copy of each possible subset of I(v).

(4) $w \leftarrow \bigcap (v_1, \ldots, v_n)$ creates a new node w of type \bigcap , with successors v_1, \ldots, v_n . I(w) contains all possible tuples with i^{th} component in $I(v_i)$.

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- (5) If v is a node of type () with n successors, and i θ j is one of the relations i ∈ j, i Π_t j, i =_t j, i =_r j and i =_r d, then w ← σ_i θ_j(v) creates a node w of the same type as v and with the same successors, that contains a copy of each tuple from I(v) whose ith and jth components are in the specified relation.
- (6) If v₁,..., v_n are all of the same type and have the same successors, then w ← ∪(v₁,...,v_n) creates another similar node w that contains a copy of each element that is in one of the I(v_i)'s.
- (7) If v₁ and v₂ have the same type and the same successors. then w ← v₁ v₂ creates another similar node w that contains a copy of each element of I(v₁) whose r-value is not the r-value of any element of I(v₂).
- (8) If v is of type \bigcirc with successors v_1, \ldots, v_n , and $S = \{s_1, \ldots, s_k\}$ is a subset of the set $\{1, \ldots, n\}$, then $u \leftarrow \prod_S(v)$ creates a new node w of type \bigcirc with successors v_{s_1}, \ldots, v_{s_k} , that contains all projections of tuples in I(v)onto these components.
- (9) If v is of type () and has exactly one successor, v, then w ← I(v) creates a new node w similar to v, that contains a copy of each element of I(v) that is the component of some element of I(v).





I	(u')			I(x)
L	r(l)		l	r(l)
15	(3)	•	17	David
16	(4)		18	Batsheba

Figure 15 Example of $\Pi(u')$.

Example 7. Suppose the database is the genealogy format with the extra node u' shown in Fig. 14 and with the instances in Fig. 7 (u, v and w) and Fig. 15 (u'). Then $x \leftarrow \tilde{\Pi}(u')$ creates the node xin Fig. 14, with I(x) as in Fig. 15.

Main Theorem. The algebraic language and the logical language are equivalent, i.e., every algebraic query is equivalent to a safe logical query, and every safe logical query is equivalent to an algebraic query.

Outline of Proof. The first direction of the theorem, that for each algebraic operation there is an equivalent query, is shown by creating, for each operation, a query that consists of one new node w with formula ϕ_w . This query will be safe and will have the same result as the corresponding algebraic operation. The details are fairly straightforward and will not be given here.

For the second part of the theorem, we are given a safe query, and we have to show that it can be simulated by a sequence of algebraic operations. Let Q be the query. We shall construct the desired algebraic expression by induction on the nodes in the query using the order \prec . Assume therefore that we have an algebraic expression for each node that precedes a node w in the query, and we now want to find an algebraic expression that constructs the node w. The formula corresponding to w is $\phi_w(x_w)$. Let the bound variables of ϕ_w be $x_{w_1}^1, \ldots, x_{w_n}^n$ (where each variable is bound by exactly one quantifier). Since the query is safe, there is a set $\{d_1, \ldots, d_k\}$ of elements of D, such that each r-value of a node of type \Box is either one of these constants, or is an r-value of some node in the database of type \Box .

Our first step is to create a node \tilde{w} that represents the domain of w, i.e., all the r-values that elements of I(w) could possibly have, if ϕ_w contained no restrictions apart from the safeness requirement given above. We define \tilde{w} as follows.

- If w is of type □, and v₁,..., v_n are all the nodes in the database of type □, then define w as follows. (i) Let w_i ← v_i for 1 ≤ i ≤ n (ii' Let w_{n+i} ← □(d_i) for 1 ≤ i ≤ k, where the d_i's are the constants listed above. (iii) Let w ← w₁ ∪ ... ∪ w_{m+k}.
- (2) If w is of type \bigcap and its successors are w_1, \ldots, w_k , let $\tilde{w} \leftarrow w_1 \times \cdots \times w_k$.
- (3) If w is of type O and its successor is u, let $\tilde{w} \leftarrow O(u)$.

We can then show:

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Lemma 5. Let I(w) be the result of the given query at node w. Then every l in I(w) must satisfy $r(l) \in r[I(\tilde{w})]$.

Let the bound variables in ϕ_w be $x_{v_1}^1, \ldots, x_{v_n}^n$. Let

$$u \leftarrow v_1 \times \cdots \times v_n \times \tilde{w},$$

and "label" each v_i with the variable $x_{v_i}^i$. This cnables us to distinguish between two copies of the same node that came from different variables. Also label \hat{w} with x_w . We define nodes v_{ψ} , for each well-formed subformula ψ of ϕ_w , by induction on the size of ψ , as follows.

- If ψ is an atomic formula of the form xⁱ_{vi} θ x^j_{vj}, let v_ψ ← σ_{iθj}(u). If ψ is of the form xⁱ_{vi} θ x_w, let v_ψ ← σ_{iθn+1}(u), similarly for the cases where ψ is of the form x_w θ xⁱ_{vi} and x_w θ x_w. In each case ψ has the same successors as u.
- (3) If ψ is $\neg \psi'$, let $x_{v_{e_1}}^{s_1}, \ldots, x_{v_{e_k}}^{s_k}$ and x_w be the labels of the successors of $v_{\psi'}$. Let

 $u_{\psi'} \leftarrow \Pi_{\{s_1,\ldots,s_k,n+1\}}(u),$

and $v_{\psi} \leftarrow u_{\psi'} - v_{\psi'}$.

(4) If ψ is (∃xⁱ_{v_i})(ψ') and x^{o1}_{v_{i1}},...,x^{oh}_{v_{ik}}, x_w are the labels of the successors of v_{ψ'}, assume that v_i is the jth component of v_{ψ'}. Let

$$v_{\psi} \leftarrow \Pi_{\{1,...,k+1\}-\{j\}}(v_{\psi'})$$

It can then be shown that:

Lemma 6. For each subformula ψ of $\phi = \phi_v$,

- (1) v_{ψ} is of type \bigcap .
- (2) The successors of v_ψ are w̃ and the sorts of the all the bound variables that appear in v_φ, except for those that are bound by a quantifier in ψ.
- (3) Assume that the successors of v_{ψ} are labelled $x_{v_{x_1}}^{s_1}, \ldots, x_{v_{x_k}}^{s_k}$ and x_w . Then

$$I(v_{\psi}) = [l \mid r(l) = (l_1, \dots, l_{k+1}) \\ \wedge \models_I \psi(l_1, \dots, l_{k+1}) \\ \wedge (l_1, \dots, l_{k+1}) \in r[\Pi_{\{i_1, \dots, i_{k+1}\}}(I(u))]]$$

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where
$$\psi = \psi(x_{v_{s_1}}^{s_1}, \dots, x_{v_{s_k}}^{s_k}, x_w)$$
.

To prove the theorem, apply Lemma 6 to the formula ϕ . We get a \bigcirc -node v_{ϕ} , whose only successor is \tilde{w} (all other variables are bound in ψ), and

$$I(v_{\phi}) = [l \mid r(l) = (l') \land \models_{I} \phi(l')$$
$$\land (l') \in r[\Pi_{\{n+1\}} I(u)]].$$

Since by Lemma 5, $\models_I \phi(l')$ implies that $l' \in I(\tilde{w})$, and each element of $I(\tilde{w})$ is the only component of the r-value of some element of $r[\Pi_{n+1}(I(u))]$, we have

$$I(v_{\phi}) = [l \mid r(l) = (l') \land \vDash \phi(l')].$$

Finally, we let $w \leftarrow \Pi(v_{\phi})$, which gives us a node w of the same type as \tilde{w} that satisfies $I(w) = [l \mid \phi(l)]$.

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