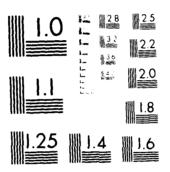
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TWO-DIMENSIONAL FLUX-CORRECTED TRANSPORT

JAYCOR Report Number J206-83-003/6201

FINAL REPORT by Raafat H. Guirguis

March 21, 1983

Submitted to: Naval Research Laboratory 4555 Overlook Avenue, SW Washington, DC 20375

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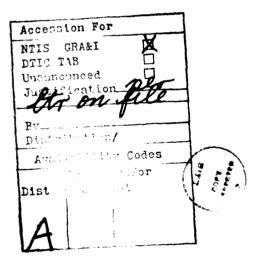
# TWO-DIMENSIONAL FLUX-CORRECTED TRANSPORT

by

Raafat H. Guirguis

Jaycor, Inc.

# Alexandria, Virginia



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#### ACKNOWLEDGMENT

I wish to express my appreciation to Dr. David L. Book for his active participation and his continuous support. I also would like to express my appreciation to Dr. Steven T. Zalesak whose suggestions were adopted in many parts of this work. I would like to thank Dr. Jay P. Boris for his guidance and support, and Dr. David Fyfe and Mr. Theodore Young for many useful discussions.

#### TABLE OF CONTENTS

I.	INTRODUCTION AND MOTIVIATION	1
II.	FOURIER ANALYSIS; DEFINITIONS	3
III.	AMPLITUDE AND PHASE ANALYSIS	10
	AMPLITUDE ANALYSIS	15
IV.	POSITIVITY AND ANTIDIFFUSION	18
۷.	A STABLE SIXTH-ORDER DIFFUSION ERROR FOURTH-ORDER PHASE ERROR SCHEME	24
VI.	EXTENSION TO HIGHER ORDERS IN DIFFUSION AND PHASE ERRORS .	27
VII.	PHYSICAL ASPECTS	34
	ACCURACY	37
	GRID MOTION	40
	Variable Velocity Field and Source Terms	42
	Example of an Algorithm	43
XI.	TWO-DIMENSIONAL TRANSPORT	50
XII.	AMPLITUDE AND PHASE ANALYSIS	62
	PHASE ERRORS	62
	AMPLITUDE ANALYSIS	68
	POSITIVITY	70
	STABILITY	71
XIII.	RECTANGULAR GRID MOTION	74
XIV.	GEOMETRICAL ASPECTS	75
	Cartesian Coordinates	75
	Cylindrical (r-z) Coordinates	77
	Spherical r- $\theta$ Coordinates	81
xv.	SOURCE TERMS	86
XVI.	ALGORITHM	90
	FLUX CORRECTION	96
	ANTIDIFFUSION AND HALF-STEP UPDATING	99
XVII.	TWO-DIMENSIONAL TIME SPLITTING VERSUS FULLY TWO-DIMENSIONAL ALGORITHMS	01
	FULLY TWO-DIMENSIONAL VERSIONS OF TIME-SPLITTED SCHEMES 1	04
XVIII.	IMPROVING DIFFUSION ERROR OF THE FULLY TWO-DIMENSIONAL	1 7

# TABLE OF CONTENTS

## (Continued)

REFERENCE	s	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	113
FIGURES.	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	114
APPENDIX	•	•	•	•	٠	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	145

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#### I. INTRODUCTION AND MOTIVATION

A well-documented module ETBFCT for solving generalized continuity equations was presented in NRL Memorandum Report 3237, dated March 1976. The module PRBFCT was also included to treat the case of periodic boundary conditions. In these modules, the cell centers are specified while the cell boundaries are located midway between the centers. In August 1980, JPBFCT, in which the cell boundaries are tracked, was documented.

The above modules are based on the Flux-Corrected Transport (FCT) technique introduced first by Boris and Book.<sup>1</sup> FCT, instead of adhering to an asymptotic ordering, requires positivity, a physical and mathematical property of continuity equations. To assure positivity, the convective stage includes or is supplemented by a large diffusive flux of zeroth order (in  $\varepsilon = \frac{u\delta t}{\delta x}$ ). Consequently, an antidiffusive or corrective step has to follow. The two stages together are able to treasteep gradients without generating dispersive ripples. Antidiffusion being a physically (and numerically) unstable process, the corrective flux is limited according to a criterion which may be stated, "The antidiffusion stage should generate no new maxima or minima in the solution, nor should it accentuate already existing extrema."

FCT was shown to be applicable to any finite difference transport scheme and able to improve it.<sup>2</sup> Phoenical FCT, a refinement which minimizes residual diffusive errors, was introduced. Clipping and terracing, two nonlinear processes resulting from the flux limiter were discussed. Finally, splitting techniques were recommended to extend FCT to multidimensions.

The most detailed error analysis of FCT algorithms was performed in Ref. 3. Low-residual-diffusion and low-phase-error algorithms were derived. An optimal algorithm, Fourier FCT, was introduced.

The requirements for positivity of a general three-point scheme and the antidiffusion flux for a minimum residual diffusion were derived in Ref. 4.

Zalesak<sup>5</sup> provided a general mathematical interpretation of the antidiffusion flux as the difference between a high-order transport scheme and a low-order one. He also described a generalized fully multidimensional flux limiter guaranteeing that the antidiffusion fluxes on all sides of the control volume, acting in concert, do not create any ripples. It was shown that by proper selection of the flux limiter parameters the clipping and terracing phenomena can be reduced.

The goal of the present work is to extend JPBFCT to a fully twodimensional algorithm, without time splitting, and incorporate the Zalesak flux limiter while still keeping the implementation of the convective, diffusion and antidiffusion processes as physical fluxes.

#### II. FOURIER ANALYSIS; DEFINITIONS

A generalized conservation equation can be written in the form:

$$\frac{\partial \rho}{\partial t} + \vec{u} \cdot \nabla \rho = \rho \nabla \cdot \vec{u} + s(\vec{x}, t, \rho, \dots), \qquad (1)$$

where  $\vec{u}$  is the velocity vector, P is the generalized density or the transported quantity whose positivity is to be conserved, and s is a source term including all the remaining terms, i.e., gradients, divergences, body forces, etc.

In the analysis we assume s = 0 and  $\vec{u} = constant$ . We shall : 't with the one-dimensional case. Eq. (1) reduces to

$$\frac{\partial \rho}{\partial t} + u_0 \frac{\partial \rho}{\partial x} = 0, \qquad (2)$$

whose analytic solution is

$$\rho(x,t) = \rho(x - u_t,0),$$
 (3)

a rightward-propagating wave with velocity  $u_0$ . Let us Fourier analyze p(x,t) in space, assuming periodic boundary conditions. Assuming an initial distribution of density p(x,0) = F(x),

$$F(x) = \frac{a_0}{2} + \sum_{k=1}^{\infty} (a_k \cos kx + b_k \sin kx), \qquad (4a)$$

where k is assumed to be normalized, i.e., k replaces  $\frac{2\pi k}{L}$ . In complex

form

$$F(\mathbf{x}) = \sum_{\mathbf{k}=-\infty}^{\infty} \hat{\rho}_{\mathbf{k}} e^{\mathbf{i}\mathbf{k}\mathbf{x}}$$
(4b)

where  $i \equiv \sqrt{-1}$ . From the reality of  $\rho(x,0)$ , the  $a_k$  and  $b_k$  are real. The quantity  $\hat{\rho}_k$  is related to these by

$$\hat{\xi}_{k} = \begin{cases} \frac{a_{k} - ib_{k}}{2} & \text{for } k > 0; \\ \frac{a_{k} + ib_{k}}{2} & \text{for } k < 0; \\ \frac{a_{0}}{2} & = 0 & \text{for } k = 0. \end{cases}$$
(5)

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Notice that we could have started the summation in Eq. (4a) from k = 0 since sin 0 = 0 and cos 0 = 1. The zeroth order term would then be a<sub>0</sub>. The form (4a) is preferred, however, since it is compatible with the symmetric formulation of Eqs. (4b) and (5). Then  $\hat{z}_k$  is given by

$$\hat{\hat{c}}_{\mathbf{k}} = \frac{1}{L} \int_{0}^{L} \mathbf{F}(\mathbf{x}) e^{-i\mathbf{k}\cdot\mathbf{x}} d\mathbf{x}.$$
 (6)

From Eq. (3), the density profile at time t is given by

$$z(\mathbf{x}, \mathbf{t}) = \sum_{k=-\infty}^{\infty} \hat{z}_{k} e^{ik(\mathbf{x} - \mathbf{u}_{0}\mathbf{t})} = \sum_{k=-\infty}^{\infty} \hat{z}_{k}(\mathbf{t}) e^{ik\mathbf{x}}, \qquad (7)$$

where

$$\hat{z}_{k}(t) = \hat{z}_{k} e^{-iku} z^{t}, \qquad (8)$$

showing that each harmonic independently advances uniformly in phase without changing its magnitude (see Fig. 1).

Suppose p is known at all times only as a set of N + 1 quantities  $c_j$ ; on discrete grid points with separation  $\delta x = \frac{L}{N}$ ;  $x_j = j\delta x$  (j = 0,1,..., N-1), since  $c_0 = c_N$ . We can have only  $\frac{N}{2}$  + 1 different harmonics. Namely, wave numbers (0,1,...,N/2) and wave lengths ( $\infty = L/0$ ,  $\frac{L}{1}$ ,  $\frac{L}{2}$ ,...,  $\frac{L}{N/2}$ ) respectively, where we note that the shortest wave length is  $2\delta x$ . Let

$$f(x) = \frac{A_0}{2} + \sum_{k=1}^{N/2} (A_k \cos kx + B_k \sin kx), \qquad (9a)$$

or

$$f(\mathbf{x}) = \sum_{\mathbf{k}=-N/2}^{N/2} \hat{\boldsymbol{a}}_{\mathbf{k}} e^{\mathbf{i}\mathbf{k}\mathbf{x}}$$
(9b)

(see Fig. 2). We notice in Eq. (9a) that at k = N/2,  $\sin kx_j = \frac{2\pi(N/2)}{L} j\delta x$ =  $\sin \pi j = 0$ ; hence only  $\cos kx$  is needed at k = N/2. There are then N coefficients,  $A_k$  (k = 0, ..., N/2) and  $B_k$  (k = 1, 2, ..., N/2 - 1), which can be determined using  $f(x_j) = \rho_j^0$  (j = 0, ..., N-1), where superscript 0 denotes time t = 0. Similarly, since for all j, exp [ $i \frac{2\pi}{L} (\frac{-N}{2}) j\delta x$ ] = exp ( $i \frac{2\pi}{L} (\frac{N}{2}) j\delta x$ ], Eq. (9b) is rewritten as

$$f(x) = \sum_{k=-N/2+1}^{N/2} \hat{\beta}_{k} e^{ikx}$$
(9c)

Again, we get N coefficients  $\hat{\beta}_{k}(k = -N/2+1,...,0,...,N/2)$ . The relation between the  $\hat{\beta}_{k}$  and  $A_{k}$ ,  $B_{k}$  are given by equations similar to Eq. (5). Formally,

$$\hat{S}_{k} = \frac{1}{N} \sum_{j=0}^{N-1} \sum_{j=0}^{n-1} e^{ikx}_{j}$$
(10)

Eq. (3) predicts the density at time t as

$$\rho(\mathbf{x}, t) = \sum_{k=-N/2+1}^{N/2} \hat{\beta}_{k} e^{ik(\mathbf{x} - u_{o}t)} = \sum_{k=-N/2+1}^{N/2} \hat{\beta}_{k}(t) e^{ikx}$$

where  $\hat{\rho}_{k}(t) = \hat{\hat{\rho}}_{k} e^{-iku} o^{t}$ . Since we are only concerned with  $\rho(x_{j}, t)$ , substituting  $x = x_{j} = j \delta x$ , we get

$$\rho(\mathbf{x}_{j}, t) = \sum_{k=-N/2+1}^{N/2} \hat{\rho}_{k}(t) e^{ikj\delta \mathbf{x}}$$
(11)

If the time is also discretized, let  $t^n \equiv n\delta t$ ,  $o_j^n \equiv \rho(x_j, t^n), \hat{o}_k^n \equiv \hat{\varepsilon}_k(t^n)$ ,

$$\upsilon_{j}^{n} = \sum_{k=-N/2+1}^{N/2} \vartheta_{k}^{n} e^{ikj\delta x}$$
(12)

where

$$\hat{c}_{k}^{n} = \hat{\beta}_{k} e^{-iku} o^{n\delta t}$$
(13)

If we space-discretize only, after we Fourier analyze the initial density profile  $\beta_j^0$ , i.e., after getting the  $\hat{\beta}_k$  in Eq. (9c), the problem is reduced to that of propagation of the complex harmonics  $e^{ikx}$  (k = 0,...,N/2). In a nonlinear problem, each harmonic can couple into components of the other harmonics. In the linear problem of Eq. (2), however, each harmonic propagates independently (this is also true if u = u(t)). Since the number of spatial points does not change, we can always express the density at any time as a Fourier expansion of the form Eq. (9c). In a nonlinear problem  $\hat{\rho}_k(t)$  is a function of  $(\hat{\delta}_{-N/2+1}, \dots, \hat{\delta}_0, \dots, \hat{\delta}_{N/2})$  at time t = 0. But in the linear problem  $\hat{\beta}_k$  as is obvicus from Eq. (13). If the time is also discretized, we can then define a transfer function

$$A(k) \equiv \frac{\delta_{k}^{n+1}}{\delta_{k}^{n}}$$
(14)

which is independent of n if  $u = u_0$  as is obvious from Eq. (13) (analytic solution), yielding

$$A(k) = e^{-iku} \delta^{t}$$
(15)

Eq. (12) may be rewritten then as

$$\rho_{j}^{n} = \sum_{k=-N/2+1}^{N/2} \hat{\beta}_{k} [A(k)]^{n} e^{ikj\delta x}, \qquad (16)$$

Denoting the constant  $\frac{u_0 \delta t}{\delta x}$  by  $\varepsilon$  and the dimensionless wave number  $k\delta x$  by  $\varepsilon$ ,  $A(\beta) = e^{-i\beta\varepsilon}$ . The amplification is  $|A(\beta)| = 1$  and the phase shift is  $-\varepsilon$ . Notice that the smallest  $\varepsilon = 0$  and largest  $\beta = \frac{2\pi}{L} \frac{N}{2} \delta x = \pi$ . For a finitedifference scheme applied to the linear problem, each harmonic propagates independently. Consequently, a method equivalent to Fourier-analyzing  $\varepsilon_j^{n+1}$  and  $\rho_j^n(j = 0, ..., N-1)$  and evaluating  $A_k$  from Eq. (14) is to study the propagation of only one harmonic by assuming  $\rho_j^n = \varepsilon^0 e^{ikj\delta x}$ , where  $\varepsilon^0$  is constant. Then

$$A(k) = \frac{\rho_{j}^{n+1}}{\rho_{j}^{n}}$$
(17)

By writing A(k) as

$$A = |A|e^{i\theta}, \qquad (18)$$

we define the amplitude (or diffusion) error and the relative phase error as

$$a = |A| - 1 \tag{19a}$$

and

$$R = \frac{(-\theta) - \beta\varepsilon}{\beta\varepsilon} = \frac{-(\theta/\beta)}{\varepsilon} - 1, \qquad (19b)$$

respectively. We define a scheme as stable if A  $\leq$  1 (see Fig. 3).

#### Example:

Assuming  $u = const = u_0$ , the original explicit SHASTA Algorithm can be written as

$$\rho_{j}^{TD} = \rho_{j}^{n} - \frac{\varepsilon}{2}(\rho_{j+1}^{n} - \rho_{j-1}^{n}) + (\frac{1}{8} + \frac{\varepsilon}{2}^{2})(\rho_{j+1}^{n} - 2\rho_{j}^{n} + \rho_{j-1}^{n})$$

$$\rho_{j}^{n+1} = \rho_{j}^{TD} - \frac{1}{8}(\rho_{j+1}^{TD} - 2\rho_{j}^{TD} + \rho_{j-1}^{TD})$$
(20)

in which we identify  $-\frac{\varepsilon}{2}(\rho_{j+1}^n - \rho_{j-1}^n)$  as the net transportive flux, denoted by a superscript T, and  $(\frac{1}{8} + \frac{\varepsilon}{2})(\rho_{j+1}^n - 2\rho_j^n + \rho_{j-1}^n)$  as the net diffusive flux, denoted by a superscript D, from which we have the notation  $\rho^{TD}$ . Expressing  $\rho^{TD}$  as a three-point formula we can write

$$o_{j}^{\text{TD}} = \left[\frac{1}{8} + \frac{\varepsilon^{2}}{2} - \frac{\varepsilon}{2}\right]o_{j+1}^{n} + \left[1 - 2\left(\frac{1}{8} + \frac{\varepsilon^{2}}{2}\right)\right]o_{j}^{n} + \left[\frac{1}{8} + \frac{\varepsilon^{2}}{2} + \frac{\varepsilon}{2}\right]o_{j-1}^{n}$$

Each of the quantities in square brackets is  $\geq 0$  for  $|\varepsilon| \leq \frac{1}{2}$ , assuring the positivity of  $\rho_j^{\text{TD}}$  if  $\rho_j^n \geq 0$ . The positivity requirement will be discussed later in detail. Assuming  $\rho_j^n = \rho^0 e^{ikj\delta x}$ ,

$$\rho_{j}^{\text{TD}} = \rho^{\circ} e^{ikj\delta x} - \frac{\varepsilon}{2} (\rho^{\circ} e^{ik(j+1)\delta x} - \rho^{\circ} e^{ik(j-1)\delta x}) + (\frac{1}{8} + \frac{\varepsilon^{2}}{2}) (\rho^{\circ} e^{ik(j+1)\delta x} - 2\rho^{\circ} e^{ikj\delta x} + \rho^{\circ} e^{ik(j-1)\delta x})$$

giving

$$\rho_{j}^{TD}/\rho_{j}^{n} = 1 - \frac{\varepsilon}{2} (e^{i\beta} - e^{-i\beta}) + (\frac{1}{8} + \frac{\varepsilon}{2}^{2}) (e^{i\beta} - 2 + e^{-i\beta}).$$
Denoting the operator  $\frac{e^{i\beta} - e^{-i\beta}}{2} = i \sin \beta$  by t and  $e^{i\beta} - 2 + e^{-i\beta}$   
 $= 2(\cos \beta - 1)$  by d, we have  $\rho_{j}^{TD} = (1 - \varepsilon t + \nu d) \rho_{j}^{n}$  where  $\nu \equiv \frac{1}{8} + \frac{\varepsilon}{2}^{2}$ . Then if  
 $\mu \equiv \frac{1}{8}, \rho_{j}^{n+1} = (1 - \varepsilon t + \nu d) \rho_{j}^{n} - \mu d(1 - \varepsilon t + \nu d) \rho_{j}^{n}$ , whence  
 $A \equiv \frac{\rho_{j}^{n+1}}{\rho_{j}^{n}} = (1 - \varepsilon t + \nu d) (1 - \mu d).$ 
(21)

We notice that at  $\varepsilon = 0$ , A  $\neq 1$ . In fact, A =  $(1 + \frac{1}{8}d)(1 - \frac{1}{8}d)$ , a deficiency that led to the introduction of a phoenical algorithm in Ref. 2, in which the antidiffusion operates on a transported density which is free from any zeroth-order diffusion. Phoenical SHASTA is written as

$$\rho_{j}^{T} = \rho_{j}^{n} - \frac{\varepsilon}{2}(\rho_{j+1}^{n} - \rho_{j-1}^{n}) + \frac{\varepsilon^{2}}{2}(\rho_{j+1}^{n} - 2\rho_{j}^{n} + \sigma_{j-1}^{n});$$

$$\rho_{j}^{TD} = \rho_{j}^{T} + \frac{1}{8}(\rho_{j+1}^{n} - 2\rho_{j}^{n} + \rho_{j-1}^{n});$$

$$\rho_{j}^{n+1} = \rho_{j}^{TD} - \frac{1}{8}(\rho_{j+1}^{T} - 2\rho_{j}^{T} + \rho_{j-1}^{T}).$$
(22)

thus yielding

$$A = (1 - \varepsilon t + \lambda \varepsilon^{2} d) (1 - \mu d) + \nu d, \qquad (23)$$
  
where  $\lambda = \frac{1}{2}, \nu = \mu = \frac{1}{8}$ , satisfying  $A = 1$  at  $\varepsilon = 0$ .

The importance of phoenicity lies in the fact that the total diffusion through a surface is proportional to the time of diffusion and therefore should vanish as  $\delta t \neq 0$ , i.e.,  $\varepsilon \neq 0$ .

Later, in Ref. 6, ETBFCT and JPBFCT, based on the scheme

$$\rho_{J}^{T} = \rho_{j}^{n} - \frac{\varepsilon}{2}(\rho_{j+1}^{n} - \rho_{j-1}^{n})$$

$$\rho_{j}^{TD} = \rho_{j}^{T} + \nu(\rho_{j+1}^{n} - 2\rho_{j}^{n} + \rho_{j-1}^{n})$$

$$\rho_{j}^{n+1} = \rho_{j}^{TD} - \mu(\rho_{j+1}^{T} - 2\rho_{j}^{T} + \rho_{j-1}^{T}), \qquad (24)$$

were introduced, yielding

$$A = (1 - \varepsilon t) (1 - \mu d) + \nu d, \qquad (25)$$

where  $v \equiv \frac{1}{6} + \frac{\varepsilon^2}{3}$  and  $\mu \equiv \frac{1}{6} - \frac{\varepsilon^2}{6}$ . Notice that the zeroth order term is the same in both v and v, thus yielding a residual diffusion  $O(\varepsilon^2)$ , which vanishes as  $\delta t \neq 0$ .

#### III. AMPLITUDE AND PHASE ANALYSIS

If in Eq. (18) A is expressed as A = A  $_{\rm R}$  + iA  $_{\rm I},$  where R stands for real and I for imaginary, then

$$|\mathbf{A}|^{2} = \mathbf{A}_{\mathbf{R}}^{2} + \mathbf{A}_{\mathbf{I}}^{2}, \qquad (31a)$$
  
$$\boldsymbol{\theta} = \tan^{-1}(\mathbf{A}_{\mathbf{I}}/\mathbf{A}_{\mathbf{R}}). \qquad (31b)$$

Equations (31) yield numerical values of |A| and  $\theta$  for a given  $\beta$ . These should be expanded, however, in a power series in  $\beta$  and plugged into Eqs. (19) to get an estimate of the order of a given scheme. Expanding Eqs. (31) in power series is a huge task. Instead, we use a scheme based on successive differentiation, as follows:

#### PHASE ERRORS

As seen from Eqs. (21), (23), and (25), three-point schemes can be expressed in terms of a transport operator  $t \equiv i \sin \beta$  and a diffusion operator  $d \equiv 2(\cos \beta - 1)$ . In other words, A = A(t,d) where  $t = t(\beta)$  and  $d = d(\beta)$ . Taking the logarithm of Eq. (18), we obtain  $\log A = \log |A| + i\partial$ , yielding

$$\theta = Im[log A]. \tag{33}$$

Expanding  $\theta$  in a power series of  $\beta$ , near  $\beta = 0$ , we have

$$\theta = \theta_0 + \theta'_0 \frac{\beta}{1!} + \theta''_0 \frac{\beta^2}{2!} + \dots$$

where ()' =  $\frac{d()}{d\beta}$  and the subscript 0 denotes the value at  $\beta$  = 0. Since, from Eq. (33),

$$\frac{\mathrm{d}^{n}}{\mathrm{d}\beta^{n}} \mid_{\beta=0} = \mathrm{Im} \left\{ \frac{\mathrm{d}^{n}}{\mathrm{d}\beta^{n}} \left( \log A \right) \right|_{\beta=0} \right\},$$

all we need are the derivatives of (log A) with respect to  $\beta$ , at  $\beta = 0$ .

First, by direct differentiation we get  $(\log A)' = A'/A$ ,  $(\log A)'' = A''/A - (A'/A)^2$  and so on. Noticing that the "consistency" of any scheme requires  $A(\beta = 0) = 1$ , we can write

$$(\log A)'_{O} = A'_{O}; \tag{35a}$$

$$(\log A)_{o} = A_{o} - A_{o}^{2};$$
 (35b)

$$(\log A)_{0}^{\prime\prime\prime} = A_{0}^{\prime\prime} - 3A_{0}A_{0}^{\prime} + 2A_{0}^{\prime3};$$
 (35c)

$$(\log A)_{0}^{\prime \prime} = A_{0}^{\prime \prime} - 4A_{0}^{\prime}A_{0}^{\prime} - 3A_{0}^{\prime \prime 2} + 12A_{0}^{\prime 2}A_{0}^{\prime \prime} - 6A_{0}^{\prime 4};$$
 (35d)

$$(\log A)_{0}^{V} = A_{0}^{V} - 5A_{0}A_{0}^{V} - 10A_{0}^{''}A_{0}^{'''} + 20A_{0}^{'2}A_{0}^{'''} + 30A_{0}^{''2}A_{0}^{''}$$
  
-  $60A_{0}^{'3}A_{0}^{''} + 24A_{0}^{'5},$  (35e)

Next denoting  $\frac{\partial(\cdot)}{\partial t}$  by ()<sup>t</sup> and  $\frac{\partial}{\partial d}$  () by ()<sup>d</sup>, we get by direct differentiation A' = t'A<sup>t</sup> + d'A<sup>d</sup>, A'' = t''A<sup>t</sup> + d''A<sup>d</sup> + t'<sup>2</sup>A<sup>tt</sup> + 2t'd'A<sup>td</sup> + d'<sup>2</sup>A<sup>dd</sup>, and so on. Confining our scope to schemes of first degree in t (composite transport excluded) and of second degree in d, we have

$$A^{tt} = 0, A^{tdd} = constant, and A^{ddd} = 0.$$
 (36)

We obtain then

$$A_{o} = 1;$$
  

$$A_{o} = t'A_{o}^{t} + d'A_{o}^{d};$$
(37a)

$$A_{o}'' = t_{o}'' A_{o}^{t} + d_{o}' A_{o}^{d} + 2t_{o}' d_{o}' A_{o}^{t} + d_{o}'^{2} A_{o}^{dd};$$
(37b)

$$A_{o}^{'''} = t_{o}^{''} A_{o}^{t} + d_{o}^{''} A_{o}^{d} + 3(t_{o}^{''} d_{o}^{'} + t_{o}^{''} d_{o}^{'}) A_{o}^{td} + 3d_{o}^{d} d_{o}^{'} A_{o}^{dd} + 3t_{o}^{''} d_{o}^{'} A_{o}^{tdd}; \quad (37c)$$

$$A_{o}^{''''} = t_{o}^{''} A_{o}^{t} + d_{o}^{''} A_{o}^{d} + (4t_{o}^{''} d_{o}^{'} + 6t_{o}^{''} d_{o}^{''} + 4t_{o}^{''''} d_{o}^{'}) A_{o}^{td}$$

$$+ (4d_{o}^{''} d_{o}^{''} + 3d_{o}^{''}) A_{o}^{dd} + (12t_{o}^{'} d_{o}^{''} + 6t_{o}^{''} d_{o}^{'}) A_{o}^{tdd}; \quad (37d)$$

$$A_{o}^{V} = t_{o}^{V} A_{o}^{t} + d_{o}^{V} A_{o}^{d} + (5t_{o}^{''} d_{o}^{'} + 10t_{o}^{''} d_{o}^{''} + 10t_{o}^{''} d_{o}^{''} + 10t_{o}^{''} d_{o}^{''}$$

$$+ 5t_{o}^{'} d_{o}^{'}) A_{o}^{td} + (5d_{o}^{'} d_{o}^{''} + 10d_{o}^{''} d_{o}^{''}) A_{o}^{dd} + (30t_{o}^{''} d_{o}^{''})$$

12

+ 
$$5t_{o}d_{o}^{''2}$$
 +  $20t_{o}d_{o}d_{o}^{''}$  +  $10t_{o}^{''d_{o}^{''}}A_{o}^{tdd}$ . (37e)

Going back to the definition of t and d

$$t_0 = 0, t_0 = i, t_0 = 0, t_0 = -i, t_0 \approx 0, and t^V = i,$$
 (38a)

$$d_{o} = 0, d_{o} = 0, d_{o} = -2, d_{o} = 0, d_{o} = 2, and d_{o} = 0.$$
 (38b)

Substituting in Eqs. (37), we get

$$A_{o} = 1;$$

$$A_{o} = iA_{o}^{t};$$
(39a)

$$\mathbf{A}_{O}^{\prime\prime} = -2\mathbf{A}_{O}^{d}; \tag{39b}$$

$$A_{o}^{''} = -i(A_{o}^{t} + 6A_{o}^{td}); \qquad (39c)$$

$$A_{o}^{'V} = 2(A_{o}^{d} + 6A_{c}^{dd});$$
 (39d)

$$A_{0}^{V} = i(A_{0}^{t} + 30A_{0}^{td} + 60A_{0}^{tdd}).$$
 (39e)

Finally, with Eqs. (30), Eqs. (35) yield

$$(\log A)_{o} = 0;$$
  
 $(\log A)_{o} = iA_{o}^{t};$  (40a)

$$(\log A)_{o}^{"} = -2A_{o}^{d} + (A_{o}^{t})^{2};$$
 (40b)

$$(\log A)_{o}^{""} = -iA_{o}^{t}(1 - 6A_{o}^{d}) - i[6A_{o}^{td} + 2(A_{o}^{t})^{3}]; \qquad (40c)$$

$$(\log A)_{o}^{V} = 12A_{o}^{dd} + 2(1 - 6A_{o}^{d})[A_{o}^{d} - 2(A_{o}^{t})^{2}] - 6A_{o}^{t}[4A_{o}^{td} + (A_{o}^{t})^{3}];$$

$$(40d)$$

$$(\log A)_{o}^{v} = 60iA_{o}^{tdd} + iA_{o}^{t}[1-30A_{o}^{d} - 60A_{o}^{dd} + 120(A_{o}^{d})^{2}] + 20i(A_{o}^{t})^{3}[1 - 6A_{o}^{d}] + 30iA_{o}^{td}[1 - 4A_{o}^{d} + 4(A_{o}^{t})^{2}] + 24i(A_{o}^{t})^{5}.$$
(40e)

Eqs. (40) invoke the fact that only the odd derivatives of log A are imaginary. Therefore, with the use of Eqs. (33) and (34), we get

$$\theta = \frac{(\log A)}{i} + \frac{(\log A)}{i} + \frac{\beta^3}{3!} + \dots$$
(41)

#### Example:

Let us phase-analyze the scheme described by Eqs. (22), i.e., the transfer function of Eq. (23)

A =  $(1 - \varepsilon t + \lambda \varepsilon^2 d) (1 - ud) + vd$ where  $v = u = \frac{1}{8}$  and  $\lambda = \frac{1}{2}$ .

First we notice that it is phoenical: A = 1 at  $\varepsilon = 0$ . By direct differentiation,  $A^{t} = -\varepsilon(1 - \mu d)$  and  $A^{d} = \lambda \varepsilon^{2}(1 - \mu d) - \mu(1 - \varepsilon t + \lambda \varepsilon^{2} d) + \nu$ ;  $A^{td} = \varepsilon \mu$ ,  $A^{dd} = -2\lambda \varepsilon^{2} \mu$ , and  $A^{tdd} = 0$ .

At  $\beta = 0$ , t = 0 and d = 0, yielding  $A_0^t = -\varepsilon$ , and  $A_0^d = \lambda \varepsilon^2 + (\nu - \mu) = \frac{\varepsilon^2}{2}$ ;  $A_0^{td} = \varepsilon \mu = \frac{\varepsilon}{8}$ ,  $A_0^{dd} = -2\lambda \varepsilon^2 \mu = -\frac{\varepsilon^2}{8}$ , and  $A_0^{tdd} = 0$ . Substituting in Eqs. (40), (41), we get

$$\theta = - \epsilon\beta + \frac{1}{6}(\frac{1}{4} \epsilon - \epsilon^3)\beta^3 + \dots$$

Using Eq. (19b), the relative phase error is found to be

$$R = \frac{1}{6}(\frac{1}{4} - \varepsilon^2)\beta^2 + O(\beta^4),$$

showing that the scheme is second order in phase.

Alternatively, let us derive an expression for v which renders the scheme of Eqs. (24) fourth-order in phase. Upon differentiating the transfer function  $A = (1 - \varepsilon t)(1 - \mu d) + v d$  we get, when we substitute  $\beta = 0$ ,

$$A_{o}^{t} = -\varepsilon; \text{ and } A_{o}^{d} = v - \mu;$$

$$A_{o}^{td} = \varepsilon\mu, A_{o}^{dd} = 0, \text{ and } A_{o}^{tdd} = 0, \qquad (42)$$

which with Eqs. (39a) through (39c) gives

$$A'_{0} = -i\epsilon$$

$$A''_{0} = -2(v - \mu)$$

$$A'''_{0} = -i(-\epsilon + 6\epsilon\mu).$$
(43)

Substituting in Eq. (35c), we obtain

Im 
$$(\log A)_{0}^{\prime\prime\prime} = \varepsilon (1 - 6\mu) - 6\varepsilon (\nu - \mu) + 2\varepsilon^{3} = \varepsilon (1 - 6\nu + 2\varepsilon^{2}).$$

To reduce the coefficient of  $\beta^2$  in the R expansion to zero we require  $(\log A) \frac{m}{c} = 0$ , yielding  $y = \frac{1}{6} + \frac{\epsilon^2}{3}$ 

(44)

#### AMPLITUDE ANALYSIS

Denote the complex conjugate by a bar on top:

$$|\mathbf{A}|^2 = \mathbf{A} \ \overline{\mathbf{A}}.$$
 (45)

Since  $\frac{d^n}{d\beta^n} = \frac{d^n()}{d\beta^n}$ , we get by successive differentiation of Eq. (45)

$$(|A|^2)_0 = 1;$$
  
 $(|A|^2)_0' = A_0 \overline{A_0} + A_0 \overline{A_0};$  (46a)

$$(|A|^2)''_{0} = A''_{0} \overline{A}_{0} + 2A_{0}A_{0} + A_{0}A_{0};$$
 (46b)

$$(|A|^2)_{0}^{''} = A_{0}^{''} \overline{A_{0}} + 3A_{0} \overline{A_{0}} + 3A_{0} \overline{A_{0}} + A_{0} \overline{A_{0}};$$
 (46c)

$$(|A|^2)_{0}^{\vee} = A_{0}^{\vee}A_{0}^{\vee} + 4A_{0}^{\vee}A_{0}^{\vee} + 6A_{0}^{\vee}A_{0}^{\vee} + 4A_{0}^{\vee}A_{0}^{\vee} + A_{0}^{\vee}A_{0}^{\vee} + A_{0}^{$$

(47)

Noticing from Eqs. (39) that the odd derivatives of A are pure imaginary while the even ones are pure real.

$$A_{o} = + \overline{A}_{o} = 1;$$
$$A_{o}' = - \overline{A}_{o}';$$
$$A_{o}'' = - \overline{A}_{o}';$$
$$A_{o}''' = - \overline{A}_{o}'';$$

and

$$A_{O}^{\prime V} = + A_{O}^{\prime V}.$$

Substituting in Eqs. (46), we get

$$(|A|^2)_{o} = 1;$$
 (48a)

$$(|\mathbf{A}|^2)_{0}^{\prime} = 0;$$
 (48b)

$$(|\mathbf{A}|^2)_{o}^{"} = 2[\mathbf{A}_{o}^{"} + (\frac{\mathbf{A}_{o}}{\mathbf{i}})^2];$$
 (48c)

$$(|\mathbf{A}|^2)_0^{(i)} = 0;$$
 (48d)

$$(|\mathbf{A}|^2)_{o}^{v} = 2[\mathbf{A}_{o}^{v} + 4(\frac{o}{i})(\frac{A_{o}}{i}) + 3(\mathbf{A}_{o}^{v})^2],$$
 (48e)

where we notice that the odd derivatives vanish. Accordingly,  $\left|A\right|^2$  can be expanded as

$$|\mathbf{A}|^{2} = \mathbf{1} + (|\mathbf{A}|^{2})_{0}^{\prime\prime} \frac{\beta^{2}}{2!} + (|\mathbf{A}|^{2})_{0}^{\prime\prime} \frac{\beta^{4}}{4!} + \dots$$
(49)

Example:

Let us derive an expression for  $\mu$  to render the diffusion error of ETBFCT fourth order. Substituting Eqs. (42) into Eq. (39d), we find

$$A_{0}^{'V} = 2(v - \mu),$$
 (50)

Using Eqs. (43) with (48), we obtain  $(|\mathbf{A}|^2)_{0}^{\prime\prime} = 2[-2(\nu - \mu) + \epsilon^2]$ , which has to vanish for a fourth-order diffusion, yielding

$$\nu - \mu = \frac{\varepsilon^2}{2}.$$
 (51)

Solving Eqs. (44) and (51), we have  $\mu = \frac{1-\varepsilon^2}{6}$ , whence  $\frac{A_0}{i} = -\varepsilon$ ,  $A_0' = -\varepsilon^2$ ,

$$\frac{A_o}{i} = \varepsilon (1 - 6\mu) = \varepsilon^3, \text{ and } A_o^{\dagger V} = \varepsilon^2. \text{ We can then write}$$
$$(|A|^2)_o^{\dagger V} = 2[\varepsilon^2 + 4(-\varepsilon)(\varepsilon^3) + 3\varepsilon^4] = 2\varepsilon^2(1 - \varepsilon^2),$$

which when substituted into Eq. (49) gives

$$|\mathbf{A}|^{2} = 1 \frac{\varepsilon^{2}}{12} (1 - \varepsilon^{2}) \beta^{4} + O(\beta^{6}), \qquad (52)$$

showing a slight instability near  $\beta = 0$  (the coefficient of  $\beta^4$  is positive).

A warning is in order at this point. Although a positive coefficient of the leading term in the expansion implies unstable behavior, a negative one does not guarantee a stable scheme, since the expansion is valid only near  $\beta = 0$ .

Figure 4 shows the amplification |A| versus  $\beta$ . We notice a maximum value of |A| = 1.0018 at  $\beta = 53.668^{\circ} \pm 0.001$  for  $\varepsilon = \frac{1}{2}$ . We can get rid of the potential instability by using a slightly different expression for u,

$$\mu = \frac{1}{6} - \alpha \frac{\varepsilon^2}{6}.$$
 (53)

By trial and error,  $\alpha$  was found to be  $\geq 1.056$ . The dashed line in Fig. 4 shows the resulting amplification for  $\alpha = 1.056$ . The maximum value of  $|\mathbf{A}|$ becomes 0.999998 at  $\beta = 45.775^{\circ} \pm 0.001$ . Since the phase error depends on  $\nu$  only, the resulting scheme is still fourth-order in phase error. The zeroth-order antidiffusion being kept at  $\frac{1}{6}$ , phoenicity is preserved, i.e., the residual diffusion is  $O(\varepsilon^2)$ . Later, a modified algorithm which is stable and has sixth-order diffusion and fourth-order phase error is described.

# IV. POSITIVITY AND ANTIDIFFUSION

The concept underlying FCT is "positivity." This means that the sign of the dependent variable must be preserved under the influence of convection alone. Source terms can alter the sign. Positivity is particularly important near steep gradients where the convective fluxes tend to make the transported quantity undershoot or overshoot. Positivity is ensured by supplementing the convective step with a large diffusive flux of zeroth order in St. For example, in the scheme of Eq. (24), consider the transport step alone,

 $\boldsymbol{\sigma}_{j}^{\mathrm{T}} = \boldsymbol{\sigma}_{j}^{\mathrm{n}} - \frac{\varepsilon}{2}(\boldsymbol{\rho}_{j+1}^{\mathrm{n}} - \boldsymbol{\rho}_{j-1}^{\mathrm{n}}) \; , \label{eq:solution_state}$ 

applied to the discontinuities of Fig. 5(a) and (b), where z = + 1/2. The negative density in Fig. 5(a) and overshoot in Fig. 5(b) are obviously major errors. By supplying enough diffusion,

 $s_{j}^{\text{TD}} = s_{j}^{\text{T}} + \left(\frac{1}{6} + \frac{\varepsilon^{2}}{3}\right) \left(s_{j+1}^{n} - 2s_{j}^{n} + s_{j-1}^{n}\right),$ 

we see the negative density in Fig. 5(a) disappear, as does the overshoot in Fig. 5(b). Formally, in the expression

 $b_{j}^{\text{TD}} = [1 - 2(\frac{1}{6} + \frac{\varepsilon^{2}}{3})] \ b_{j}^{n} + i(\frac{1}{6} + \frac{\varepsilon^{2}}{3}) - \frac{\varepsilon}{2}]b_{j+1}^{n} + [(\frac{1}{6} + \frac{\varepsilon^{2}}{3}) + \frac{\varepsilon}{2}]b_{j-1}^{n},$ 

the quantities in square brackets are all  $\geq 0$  for  $|\varepsilon| \leq 1/2$ , therefore ensuring positivity of  $\circ_j^{TD}$  as long as  $\circ_j^n \geq 0$ .

A side benefit of the zeroth-order term is more accurate propagation i.e., high-order phase preservation. As seen from Eq. (44), selecting  $y = \frac{1}{6} + \frac{\epsilon^2}{3}$  assures a fourth-order phase error.

A byproduct of this large added diffusion is antidiffusion, which is needed to extract at least the zeroth order part. This leaves a residual diffusion  $O(\epsilon^2)$  near almost uniform distributions. Near steep gradients,

antidiffusion fluxes have to be reduced enough to maintain the positivity of  $p^{TD}$ . This process is called correction of fluxes, and gives rise to the name "flux-corrected transport." In the case of a discontinuity, the local antidiffusion flux is cancelled completely. This trimming means that the amplitude no longer has the order of accuracy derived above. But near steep gradients the concept of order is meaningless anyway. On the other hand, Eq. (44) is independent of  $\mu$ . The fourth order phase error is therefore assured regardless of the antidiffusion fluxes. Specifically, "the antidiffusion stage should generate no new maxima or minima in the solution, nor should it accentuate already existing extrema" (Ref. 1).

The first mathematical formulation of the above statement was given in connection with explicit SHASTA,  $^{\rm 1}$ 

$$\rho_{j}^{\text{TD}} = \rho_{j}^{n} - \frac{\varepsilon}{2}(\rho_{j+1}^{n} - \rho_{j-1}^{n}) + (\frac{1}{8} + \frac{\varepsilon^{2}}{2})(\rho_{j+1}^{n} - 2\rho_{j}^{n} + \rho_{j-1}^{n})$$
(61a)

$$\rho_{j}^{n+1} = \rho_{j}^{TD} - (f_{j+\frac{1}{2}}^{C} - f_{j-\frac{1}{2}}^{C})$$
(61b)

The corrected antidiffusion flux,

$$f_{j+\frac{1}{2}}^{c} = \operatorname{sign} \Delta_{j+\frac{1}{2}} \cdot \max \{0, \min [\Delta_{j-\frac{1}{2}} \cdot \operatorname{sign} \Delta_{j+\frac{1}{2}}, \dots \\ \frac{1}{8} |\Delta_{j+\frac{1}{2}}|, \Delta_{j+3/2} \cdot \operatorname{sign} \Delta_{j+\frac{1}{2}}\}$$
(62)

is the corrected form of the raw flux

$$f_{j+\frac{1}{2}} \equiv \frac{1}{8} \Delta_{j+\frac{1}{2}} \equiv \frac{1}{8} (\rho_{j+1}^{TD} - \rho_{j}^{TD}), \qquad (63)$$

which in this scheme is always in the same direction as the gradient in  $p^{TD}$ . There are eight different possible cases, shown schematically in Fig. 6. Cases 5-8 are mirror images of 1-4, respectively.

Equation (62) will cancel an antidiffusion flux whenever it would lead to accentuate a maximum or a minimum, as illustrated in Fig. 6, and will trim it enough not to generate a new maximum or minimum whenever it is not cancelled.

Later in Ref. 2 the raw antidiffusion fluxes were evaluated using  $c_j^T$  in the raw flux  $f_{j+\frac{1}{2}} \equiv \frac{1}{8}(\rho_{j+1}^T - o_j^T)$ , where

$$\rho_{j}^{T} \equiv \rho_{j}^{n} - \frac{\varepsilon}{2}(\rho_{j+1}^{n} - \rho_{j-1}^{n}) + \frac{\varepsilon^{2}}{2}(\rho_{j+1}^{n} - 2\rho_{j}^{n} + \rho_{j-1}^{n}).$$

The corrected flux is expressed as

$$f_{j+\frac{1}{2}}^{c} = \operatorname{sign} f_{j+\frac{1}{2}} \cdot \max \{0, \min [ \bot_{j-\frac{1}{2}} \cdot \operatorname{sign} f_{j+\frac{1}{2}}' \\ |f_{j+\frac{1}{2}}|, \bot_{j+3/2} \cdot \operatorname{sign} f_{j+\frac{1}{2}}] \}, \qquad (64)$$

where we get sixteen possible cases (twice as many as before, depending whether  $f_{j+\frac{1}{2}}$  is parallel to  $f_{j+\frac{1}{2}}$  or opposite to it). In Fig. 7 we consider only those cases when  $f_{j+\frac{1}{2}}$  is positive, since the other cases are their mirror images.

Again, the flux is cancelled whenever it would accentuate a maximum or minimum. But it is also cancelled in cases 6-8 where it would not in general cause any problems, an unnecessary action. This is due to the fact that  $f_{j+\frac{1}{2}}$  is corrected independently of  $f_{j-\frac{1}{2}}$  and  $f_{j+3/2}$ .

Zalesak<sup>5</sup> reexpressed the role of the flux limiter as "guaranteeing that the two antidiffusion fluxes associated with each cell, <u>acting in</u> <u>concert</u>, should not create any ripples." The mathematical formula

implementing the above statement is described for 1-D schemes by the following steps:

$$p_{j}^{\dagger} \equiv \text{sum of antidiffusive fluxes "into" grid point j}$$
$$= \max (0, f_{j-\frac{1}{2}}) - \min (0, f_{j+\frac{1}{2}})$$
(65)

$$Q_{j}^{\dagger} \equiv (\rho_{j}^{\max} - \rho_{j}^{TD})$$
(66)

$$R_{j}^{+} = \begin{cases} \min (1, Q_{j}^{+}/P_{j}^{+}) & \text{if } P_{j}^{+} > 0 \\ \\ 0 & \text{if } P_{j}^{+} = 0. \end{cases}$$
(67)

Similarly,

$$P_{j}^{T} \equiv \text{sum of antidiffusive fluxes "out of" grid point j}$$
$$= \max (0, f_{j+\frac{1}{2}}) - \min (0, f_{j-\frac{1}{2}})$$
(68)

$$Q_{j}^{T} = (O_{j}^{TD} - J_{j}^{min})$$
(69)

$$R_{j}^{-} \equiv \begin{cases} \min (1, Q_{j}^{-}/P_{j}^{-}) & \text{if } P_{j}^{-} > 0 \\ 0 & \text{if } P_{j}^{-} = 0, \end{cases}$$
(70)

where  $p_{j}^{\max}$  and  $z_{j}^{\min}$  are the upper and lower bounds on  $p_{j}^{n+1}$ , respectively, which ensure that no ripples form at grid point j. Defining the correction ratio

$$C_{j+\frac{1}{2}} \equiv \begin{cases} \min (R_{j+1}^{+}, R_{j}^{-}) & \text{if } f_{j+\frac{1}{2}} > 0 \\ \min (R_{j}^{+}, R_{j+1}^{-}) & \text{if } f_{j+\frac{1}{2}} < 0. \end{cases}$$
(71)

we set

$$f_{j+\frac{1}{2}}^{c} = C_{j+\frac{1}{2}}f_{j+\frac{1}{2}}.$$
 (72)

A conservative choice for  $\rho_{j}^{max}$  and  $\rho_{j}^{min}$  is

$$\rho_{j}^{\max} = \max \left( c_{j-1}^{\text{TD}}, c_{j+1}^{\text{TD}} \right)$$

$$\rho_{j}^{\min} = \min \left( \rho_{j-1}^{\text{TD}}, \rho_{j+1}^{\text{TD}} \right).$$
(73)

This choice will guarantee that no maxima or minima form other than those already existing in the  $o^{\text{TD}}$  distribution. The flux limiter of Eq. (64), however, not only guarantees no ripples, but it also cancels the flux in cases 6-8 of Fig. /. To reproduce the results of Eq. (64), one should apply the extra limiter

$$f_{j+\frac{1}{2}}^{c} = 0$$

 $if (f_{j+\frac{1}{2}} \cdot \Delta_{j+\frac{1}{2}} < 0 \text{ and } (f_{j+\frac{1}{2}} \cdot \Delta_{j+3/2} < 0 \text{ or } f_{j+\frac{1}{2}} \cdot \Delta_{j-\frac{1}{2}} < 0))$ (74) before Eq. (64).

An extension of Eq. (64) to more than one dimension, however, cannot guarantee that there will be no ripples since it lacks knowledge of  $f_{j+3/2}$ and  $f_{j-\frac{1}{2}}$  when correcting  $f_{j+\frac{1}{2}}$ . We are left then with only one safe solution, which is the extension of Eqs. (65) to (74) to multidimensions. Now, going back to Eq. (73), a more tolerant choice would be

$$b_{j}^{\max} = \max \{\max (b_{j-1}^{TD}, b_{j-1}^{n}), \max (b_{j}^{TD}, b_{j}^{n}), \max (b_{j+1}^{TD}, b_{j+1}^{n})\};$$

$$b_{j}^{\min} = \min \{\min (b_{j-1}^{TD}, b_{j-1}^{n}), \min (b_{j}^{TD}, b_{j}^{n}), \min (b_{j+1}^{TD}, b_{j+1}^{n})\}.$$
(75)

This choice will partially avoid the clipping associated with the flux correction of Eq. (73), as explained in Ref. 5. In summary, by calibrating  $\binom{\max, \min_j}{j}$  using a guaranteed positive profile, positivity is still preserved after the antidiffusion step is performed.

Now that we have all the definitions and tools necessary for analysis, let us go back to analyzing schemes.

# V. A STABLE SIXTH-ORDER DIFFUSION ERROR FOURTH-ORDER PHASE ERROR SCHEME

As mentioned earlier, ETBFCT can be made stable by using  $u = 1/6 - \alpha \frac{\varepsilon^2}{6}$ , where  $\alpha \ge 1.056$ . Then

$$(|\mathbf{A}|^2)''_{0} = 2[-2(v - \mu) + \varepsilon^2] = 2[-2(\frac{2+\alpha}{6}) + 1]\varepsilon^2,$$

yielding

$$|A|^{2} = 1 - \left(\frac{\alpha - 1}{3}\right)\varepsilon^{2}\beta^{2} + O(\beta^{4}), \qquad (81)$$

which gives for  $\alpha = 1.056$ 

$$|\mathbf{A}|^2 = 1 - \frac{0.056}{3} \epsilon^2 \beta^2 + O(\beta^4)$$
,

thus giving the scheme a small second-order error, but leaving it essentially fourth order in amplitude.

An alternative is to add a small phoenical diffusion  $O(\epsilon^2)$  to  $\wp^T.$  We get then

Assuming  $\rho_j^n = \sigma^0 e^{ikj\delta x}$ ,

A

$$= (1 - \varepsilon t + \lambda \varepsilon^{2} d) (1 - \mu d) + \nu d, \qquad (83)$$

where t  $\equiv$  i sin  $\beta$  and d  $\equiv$  2 (cos  $\beta$  - 1). Following the method of analysis described above, we write

$$A_{o}^{t} = -\varepsilon, A_{o}^{d} = (v + \lambda \varepsilon^{2}) - \mu,$$
$$A_{o}^{td} = \varepsilon \mu, A_{o}^{dd} = -2\lambda \varepsilon^{2} \mu, \text{ and } A_{o}^{tdd} \approx 0$$

Then

$$\begin{aligned} \mathbf{A}_{o}^{\prime} &= -i\varepsilon; \\ \mathbf{A}_{o}^{\prime\prime} &= -2[(\nu + \lambda\varepsilon^{2}) - u]; \\ \mathbf{A}_{o}^{\prime\prime} &= -i[-\varepsilon + 6\varepsilon\mu]; \\ \mathbf{A}_{o}^{\prime\prime} &= 2[\nu + \lambda\varepsilon^{2} - \mu - 12\lambda \varepsilon^{2}\mu]; \end{aligned}$$

For a fourth-order diffusion error,

$$(\left|\mathbf{A}\right|^2)_{o}^{\prime\prime} = 2\left[-2\left(v + \lambda\varepsilon^2 - \mu\right) + \varepsilon^2\right] = 0,$$

yielding

$$v + \lambda \varepsilon^2 - \mu = \frac{\varepsilon^2}{2}.$$

Going back to the  $A_0^{''}$ ,  $A_0^{v}$  expressions, we can rewrite them as

$$A_{o}^{''} \approx -\varepsilon^{2},$$
$$A_{o}^{''} \approx \varepsilon^{2} - 24\lambda\varepsilon^{2}\mu$$

For a fourth-order phase error

$$(\log A)_{0}^{\prime\prime\prime} = -i[-\varepsilon + 6\varepsilon\mu] - 3(-i\varepsilon)(-2)(\nu + \lambda\varepsilon^{2} - \mu) + 2(-i\varepsilon)^{3}$$
$$= i\varepsilon[1 - 6(\nu + \lambda\varepsilon^{2}) + 2\varepsilon^{2}] = 0,$$

yielding

$$v + \lambda \varepsilon^2 = 1/6 + \varepsilon^2/3,$$

which gives

 $\mu = 1/6 - \epsilon^2/6$ We can then rewrite  $A_0^{''}$  and  $A_0^{'V}$  as  $A_0^{''} = i\epsilon^3$ ,  $A_0^{'V} = \epsilon^2 - 4\lambda\epsilon^2(1 - \epsilon^2)$ .

Checking,

$$(|\mathbf{A}|^2)_{o}^{\mathbf{V}} = 2[\varepsilon^2 - 4\lambda\varepsilon^2(1 - \varepsilon^2) - 4\varepsilon^4 + 3\varepsilon^4]$$
$$= 2[1 - 4\lambda)\varepsilon^2(1 - \varepsilon^2)].$$

showing that we can make the scheme sixth-order in diffusion by selecting

 $\lambda = 1/4.$ 

In summary,

$$v = 1/6 + \epsilon^2/12, \ \mu = 1/6 - \epsilon^2/6, \ \lambda = 1/4.$$
 (84)

Again, we have to check <sup>TD</sup>:

$$\rho_{j}^{\text{TD}} = \left[1 - 2\left(\frac{1}{6} + \frac{\varepsilon^{2}}{2}\right)\right] \rho_{j}^{n} + \left[\frac{1}{6} + \frac{\varepsilon^{2}}{3} - \frac{\varepsilon}{2}\right] \rho_{j+1}^{n} + \left[\frac{1}{6} + \frac{\varepsilon^{2}}{3} + \frac{\varepsilon}{2}\right] \rho_{j-1}^{n}.$$

Each quantity in square brackets is  $\geq 0$  if  $|\varepsilon| \leq 1/2$ , yielding  $\rho_j^{TD} \geq 0$  if  $\rho_j^n \geq 0$ , thus ensuring positivity. Figure 8 shows |A| and R versus  $\beta$ . Finally, we note that this is still a 5-point scheme.

# VI. EXTENSION TO HIGHER ORDERS IN DIFFUSION AND PHASE ERRORS

We seek a combination of transport operator  $t(t \ge i \sin \beta)$  and diffusion operator  $d(d \ge 2(\cos \beta - 1))$  which approaches the analytic solution up to a prescribed order of  $\beta$ . Since the transfer function of the analytic solution is expressed as  $A = e^{-i\beta\epsilon}$ ,

$$A = \cos \beta \varepsilon - i \sin \beta \varepsilon$$
 (85)

or

$$A_{I} = -\sin\beta\epsilon$$
  
 $A_{R} = \cos\beta\epsilon$ . (86)

Now, we write  $\sin\beta\epsilon$  as

$$\sin \beta \varepsilon = \sin \beta [A_0 + A_1 (1 - \cos \beta) + A_2 (1 - \cos \beta)^2 + ...], \qquad (87)$$

where  $A_0$ ,  $A_1$ ,  $A_2$ ,... are determined such as to make the series expansion of both sides of Eq. (87) agree up to a prescribed order of  $\beta$ . In other words, the derivatives of both sides with respect to  $\beta$  at  $\beta = 0$  have to be equal. We get the following system of algebraic equations:

<b>—</b>	-	<b>-</b>				<b>–</b>	
ε		1	0	0	0	•••	A
			3	0	0		A O A 1
ε	5   =	1	-15	30	0	••••	А <sub>2</sub>
		•	•	•	•	•	.
.		.	•	•	•	•	.
L.	J	L.	•			. ]	L. ]

(88)

solved by "forward substitution" since the matrix of coefficients is already

"left-triangular." We solve for  $A_{0}$  first, then for  $A_{1}$ , etc. We get

$$A_0 = \varepsilon, A_1 = \frac{\varepsilon (1-\varepsilon^2)}{3}, A_2 = \frac{\varepsilon (4-\varepsilon^2) (1-\varepsilon^2)}{30}, \dots$$
 (89)

As for the construction of the matrix, the first column is the odd derivatives of sin  $\beta$ , the second, those of sin  $\beta(1 - \cos \beta)$ , the third, those of sin  $\beta(1 - \cos \beta)^2$ ,... and so on, all at  $\beta = 0$ . We notice that the even derivatives are all zero. To get these, let  $\phi \equiv 1 - \cos \beta$ , and define K recursively  $K_{i+1} \equiv K_i \beta$  where  $K_0 \equiv \sin \beta$ . If we have the derivatives of  $K_i$ , those of  $K_{i+1}$  will be

$$K_{i+1} = K_{i}^{\dagger}\phi;$$

$$K_{i+1}' = K_{i}^{\dagger}\phi + K_{i}\phi';$$

$$K_{i+1}'' = K_{i}^{\dagger}\phi + 2K_{i}^{\dagger}\phi' + K_{i}\phi'',$$
(90)

and so on. Generally if ()  $\binom{n}{\beta} \equiv \frac{d^n(\beta)}{d\beta^n} = 0$  and ()  $\binom{0}{\beta} \equiv 0$ , we get

$$K_{i+1}^{(n)} = \sum_{m=0}^{n} {n \choose m} K_{i}^{(m)} \phi^{(n-m)}$$
(91)

where  $\binom{n}{m} = \frac{n!}{(n-m)!m!}$ . All we need then is the derivatives of  $K_0 \equiv \sin \beta$ and  $\phi \equiv 1 - \cos \beta$  at  $\beta = 0$ ; namely,

$$K_{o} = 0, K_{o} = 1, K_{o} = 0, K_{o} = -1, \dots, \text{ and}$$
  
 $\phi = 0, \phi' = 0, \phi'' = 1, \phi''' = 0, \phi'^{V} = -1, \dots$  (92)

Now, we write  $\cos \beta \epsilon$  as

$$\cos \beta \epsilon = B_0 + B_1 (1 - \cos \beta) + B_2 (1 - \cos \beta)^2 + \dots$$
 (93)

where  $B_0$ ,  $B_1$ ,  $B_2$ ,..., are determined such as to make the series expansion of both sides of Eq. (93) agree up to a prescribed order of  $\beta$ . In this case

$$K_{0} = 1, K_{0} = K_{0} = K_{0} = \dots = 0.$$
 (94)

Using Eq. (91), we get

		<b>[</b> 1	0	0	0	]	В	
-ε <sup>2</sup>		0	1	0	0		B <sub>1</sub>	
ε4		0	-1	6	0	···· ····	B <sub>2</sub>	
	=		•					
		.	•	•	•			
		L.	•	•	•			(95)

where we notice again a "left-triangular" coefficients matrix. By "forward substitution" we obtain

$$B_0 = 1, B_1 = -\epsilon^2, B_2 = \frac{-\epsilon^2}{6}(1 - \epsilon^2) \dots$$
 (96)

Obviously, we can get Eq. (93) by differentiating Eq. (87) and vice versa, but we need then to continue the expansion one more term and use trigonometric identities. The direct approach followed is, however, preferred, since it enforces a given form on the expansion which is in no way unique, as explained below.

Noticing that sin  $\beta$  = t/i and 1 - cos  $\beta$  = -d/2, we can write a sixth-order diffusion error, sixth-order phase error scheme, for example, as

$$A_{R} = 1 + \frac{\varepsilon^{2}}{2} d - \frac{\varepsilon^{2}}{24} (1 - \varepsilon^{2}) d^{2}$$
  

$$iA_{1} = -\varepsilon t \left[1 - \frac{1 - \varepsilon^{2}}{6} d + \frac{1 - \varepsilon^{2}}{30} (1 - \frac{\varepsilon^{2}}{4}) d^{2}\right].$$
(97)

If we stop at  $A_1$ ,  $B_1$ , we get ETBFCT, which has fourth-order diffusion and phase error. Although t and d are both three-point operators, td<sup>2</sup> is a seven-point formula. An important conclusion follows: We need three points for a second-order diffusion and phase error, five points for a fourth-order error, and so on, adding two points at a time. We can, however, get sixth-order diffusion and fourth-order phase accuracy with only five points since we have to match the sum  $|A|^2 = A_1^2 + A_R^2$  up to a prescribed order of  $\beta$  and not  $A_1$  and  $A_R$  separately. Scheme (82) is an example. Alternatively one can construct a scheme with fourth-order diffusion and sixthorder phase accuracy using only five points since we have to expand  $\tan^{-1} \frac{A_1}{A_R}$ , not  $A_1$  and  $A_R$  separately.

Before implementing Eq. (97), it is important to emphasize that the expansion is not unique. For example, we can use the expansions

$$\sin \beta \epsilon = \sin \beta \left[ A_0 + A_1 (1 - \cos \beta) + A_2 (1 - \cos 2\beta) + \dots \right],$$
  
$$\cos \beta \epsilon = B_0 + B_1 (1 - \cos \beta) + B_2 (1 - \cos 2\beta) + \dots$$
(98)

We get then

(99)

and

By solving the two systems (99), (100), we obtain

$$A_{0} = \varepsilon, A_{1} = \frac{\varepsilon(9 - \varepsilon^{2})(1 - \varepsilon^{2})}{15}, A_{2} = \frac{-\varepsilon(4 - \varepsilon^{2})(1 - \varepsilon^{2})}{60}$$
 (100)

and

$$B_{0} = 1, B_{1} = \frac{-\varepsilon^{2}}{3}(4 - \varepsilon^{2}), B_{2} = \frac{\varepsilon^{2}}{2}(1 - \frac{\varepsilon^{2}}{6}).$$
(101)

We notice that the matrices are full and the coefficients (A,,  $A_2,\ldots); (B_1, B_2,\ldots)$  are more complex in form than the corresponding coefficients Eq. (89), (96). Moreover, they change if the expansion is extended to higher order. The operator  $(1 - \cos 2\beta)$  results from a fivepoint formula; namely,  $\rho_{j+2} = 2\rho_j + \rho_{j-2}$ . It is abandoned therefore in favor of the three-point operator formula of Eq. (97) since the latter requires knowledge of only one point outside the boundary.

We rewrite Eq. (97) as

$$A = A_{R} + iA_{I} = -\varepsilon t \{1 - (\frac{1 - \varepsilon^{2}}{6})d + (\frac{1 - \varepsilon^{2}}{6})\frac{1}{5}(1 - \frac{\varepsilon^{2}}{4})d^{2}\} + \{1 + \frac{\varepsilon^{2}}{2}d - \frac{\varepsilon^{2}}{4}(\frac{1 - \varepsilon^{2}}{6})d^{2}\}.$$

Noting that  $\rho^{n+1} = A\rho^n$ , let us collect the terms in such a way as to ensure positivity at every step. First,  $(-\varepsilon t)c^n = c^T - c^n$  where

$$\rho_{j}^{\mathrm{T}} = \rho_{j}^{\mathrm{n}} - \frac{\varepsilon}{2} (\rho_{j+1}^{\mathrm{n}} - \rho_{j-1}^{\mathrm{n}}).$$

Then

$$\rho^{n+1} = \rho^{n} + \left(\frac{\varepsilon^{2}}{2}d\right)\rho^{n} - \left[\left(\frac{1-\varepsilon^{2}}{6}d\right)\left(\frac{\varepsilon^{2}}{4}d\right)\right]\rho^{n} + \left(1-\left(\frac{1-\varepsilon^{2}}{6}d\right) + \left(\frac{1-\varepsilon^{2}}{6}d\right)\right) + \left(\frac{1-\varepsilon^{2}}{6}d\right)\left[\frac{1}{5}\left(1-\frac{\varepsilon^{2}}{4}d\right)\right]\left(\rho^{T}-\rho^{n}\right),$$
(102)

whence

$$z^{n+1} \equiv z^{T} + \left[\left(\frac{\varepsilon^{2}}{2} + \frac{1 - \varepsilon^{2}}{6}\right)d\right]z^{n} - \left(\frac{1 - \varepsilon^{2}}{6}d\right)\left[z^{T} + \left(\frac{\varepsilon^{2}}{4}d\right)z^{n}\right] + \left\{\left(\frac{1 - \varepsilon^{2}}{6}d\right)\left[\frac{1}{5}\left(1 - \frac{\varepsilon^{2}}{4}d\right)d\right]\right\}(z^{T} - z^{n})$$
(103)

From our earlier experience, the combination

 $p^{\mathrm{T}} + (\frac{\varepsilon^2}{2} + \frac{1-\varepsilon^2}{6}) \mathrm{d}p^{\mathrm{n}}$ 

is known to be positive for  $|\varepsilon| \le 1/2$ . The remaining terms are regarded as antidiffusion. The following scheme is recommended:

$$p_{j}^{T} = p_{j}^{n} - \frac{s}{2}(p_{j+1}^{n} - p_{j-1}^{n}); \qquad (104a)$$

$$\rho_{j}^{TA} - \rho_{j}^{T} - \frac{1}{5}(1 - \frac{\varepsilon^{2}}{4})(\rho_{j+1}^{T} - 2\rho_{j}^{T} + \rho_{j-1}^{T}); \qquad (104b)$$

$$p_{j}^{\text{TAD}} = p_{j}^{\text{TA}} + \frac{1}{5}(1 + \epsilon^{2})(p_{j+1}^{n} - 2p_{j}^{n} + p_{j-1}^{n}); \qquad (104c)$$

$$s_{j}^{TD} = s_{j}^{T} + \left(\frac{1}{6} + \frac{\varepsilon^{2}}{3}\right) \left(s_{j+1}^{n} - 2s_{j}^{n} + s_{j-1}^{n}\right);$$
(104d)

$$o_{j}^{n+1} = o_{j}^{TD} - \left(\frac{1-\varepsilon^{2}}{6}\right) \left(c_{j+1}^{TAD} - 2o_{j}^{TAD} + o_{j-1}^{TAD}\right)^{*}, \qquad (104e)$$

where the asterisk of Eq. (104e) means that the antidiffusive fluxes in this step are to be corrected. It is worth noticing that if  $v^{TAD}$  is taken as  $v^{T}$ , we obtain a fourth-order diffusion, fourth-order phase algorithm. If

$$\rho^{\text{TAD}} \equiv \rho^{\text{T}} + \frac{\varepsilon^2}{4} d\rho^n,$$

we get a sixth-order diffusion, fourth-order phase, and finally,

$$\rho^{\text{TAD}} \equiv \rho^{\text{T}} + \frac{1}{5}(1 + \varepsilon^2) d\rho^{\text{T}}$$

yields a fourth-order diffusion, sixth-order phase error scheme. The amplitude and phase error versus  $\beta$  are shown in Fig. 9.

## VII. PHYSICAL ASPECTS

The conservation of mass, momentum, and energy applied to a system are expressed as

$$\frac{d}{dt} \int c(\vec{x}, t) d\Psi = 0$$

$$\frac{d}{dt} \int c(\vec{x}, t) \vec{u}(\vec{x}, t) d\Psi = \int c(\vec{x}, t) \vec{t}(\vec{x}, t) d\Psi + \int \vec{T}(\vec{n}, \vec{x}, t) dS$$

$$\frac{d}{dt} \int c(\vec{x}, t) \vec{u}(\vec{x}, t) d\Psi = \int c(\vec{x}, t) \vec{t}(\vec{x}, t) d\Psi + \int \vec{T}(\vec{n}, \vec{x}, t) dS$$
(112)
$$\frac{d}{dt} \vec{t}(t) = \Psi^{f}(t) = S^{f}(t)$$

and

$$\frac{d}{dt} \int \rho(\vec{x},t) \left\{ e(\vec{x},t) + \frac{|\vec{u}(\vec{x},t)|^2}{2} \right\} d\Psi = \int \rho(\vec{x},t) \vec{G}(\vec{x},t) \cdot \vec{u}(\vec{x},t) d\Psi$$

$$\Psi^{f}(t) \qquad \Psi^{f}(t)$$

$$+ \int \vec{T}(\vec{n},\vec{x},t) \cdot \vec{u}(\vec{x},t) dS + \int \vec{q} \cdot \vec{n} dS \qquad (113)$$

$$S^{f}(t) \qquad S^{f}(t)$$

where e and G are the internal energy and body force per unit mass,  $\vec{T}$  is the stress on an element of surface dS with unit normal  $\vec{n}$ , and  $\vec{q}$  is the flux of energy through the surface, for example, heat flux. The integrations are carried out over  $\forall^{f}(t)$ ,  $S^{f}(t)$ , where the superscript indicates that the control volume moves with the fluid. We notice that all the terms contributing to the balance of any of the conserved quantities are volume or surface integrals.

In the case of an inviscid fluid

$$\vec{T}(\vec{n},\vec{x},t) = - p(\vec{x},t)\vec{n}.$$
 (114)

The surface integrals 
$$\int \vec{T} dS$$
 and  $\int \vec{T} \cdot \vec{u} dS$  reduce then to  $\int \vec{pn} dS$  and  $\int \vec{pu} \cdot \vec{n} dS$   
s<sup>f</sup> s<sup>f</sup> s<sup>f</sup> s<sup>f</sup> s<sup>f</sup>  
which yield  $\int \text{grad } p d\Psi$  and  $\int \text{div} (\vec{pu}) d\Psi$ , respectively, when we apply the  $\Psi^{f}$   $\Psi^{f}$ 

divergence theorem.

Recalling Reynold's transport theorem

$$\frac{d}{dt} \int \chi(\vec{x},t) d\Psi = \int \frac{\partial \chi}{\partial t} d\Psi + \int \chi \vec{u} \cdot \vec{n} dS$$

$$\stackrel{*}{\Psi}(t) \qquad \stackrel{*}{\Psi}(t) \qquad \stackrel{*}{S}(t) \qquad (115)$$

where  $\forall$  (t) is a control volume whose surface elements dS move with arbitrary velocity  $\vec{u}^*$ . Notice that the two integrals on the RHS are over space and therefore depend only on the instantaneous position of the control volume. Consequently, the integration can be carried out over any control volume which happens to coincide with  $\forall$  at this instant, whether it is fixed or moving with another velocity. Denoting the fluid velocity by  $\vec{u}^{f}$  and the control surface velocity by  $\vec{u}^{g}$  we get, using Eq. (115)

$$\frac{d}{dt} \int \chi d\Psi = \int \frac{\partial \chi}{\partial t} d\Psi + \int \chi \dot{u}^{f} \cdot \dot{n} dS$$

$$\frac{d}{dt} \int \chi d\Psi = \int \frac{\partial \chi}{\partial t} d\Psi + \int \chi \dot{u}^{g} \cdot \dot{n} dS$$

$$\frac{d}{dt} \int \chi d\Psi = \int \frac{\partial \chi}{\partial t} d\Psi + \int \chi \dot{u}^{g} \cdot \dot{n} dS$$
(116)

If  $\Psi^{g}$  coincide with  $\Psi^{f}$  at time t, we get

$$\frac{d}{dt} \int_{X} d\Psi = \frac{d}{dt} \int_{X} d\Psi + \int_{Y} (\vec{u}^{f} - \vec{u}^{g}) \cdot \vec{n} dS$$

$$\Psi^{f} \qquad \Psi^{g} \qquad S^{g} \qquad (117)$$

When G = 0 and q = 0, Eqs. (111) through (113) become

$$\frac{d}{dt} \int \rho d\Psi + \int \rho (\vec{u}^f - \vec{u}^g) \cdot \vec{n} dS = 0; \qquad (118)$$

$$\frac{d}{dt} \int_{\rho} \vec{u}^{f} d\Psi + \int_{\sigma} \vec{u}^{f} [(\vec{u}^{f} - \vec{u}^{g}) \cdot \vec{n}] dS = -\int_{\sigma} p \vec{n} dS; \qquad (119)$$

$$\frac{\mathrm{d}}{\mathrm{dt}} \int_{\Psi} \mathfrak{g}(\mathbf{e} + \frac{|\vec{u}^{\mathrm{f}}|^2}{2}) \mathrm{d}\Psi + \int_{\Im} (\mathbf{e} + \frac{|\vec{u}^{\mathrm{f}}|^2}{2}) (\vec{u}^{\mathrm{f}} - \vec{u}^{\mathrm{g}}) \cdot \vec{\mathbf{u}} \mathrm{d}S = -\int_{\Psi} \vec{p} \vec{u}^{\mathrm{f}} \cdot \vec{\mathbf{n}} \mathrm{d}S.$$
(120)

Using the divergence theorem we can get the differential form of the conservation equations. However, it is far more convenient to use the integral form, because a numerical scheme based on the integral form is already conservative, since the fluxes leaving one control volume have to enter an adjacent one, and discontinuities can be propagated in principle without any smoothing, since one can always integrate a profile including a discontinuity, in contrast with differentiation. Consider Fig. 10, representing a uniform fixed one-dimensional grid and a continuous density profile incorporating one discontinuity. If we know the mass in the hatched cell and the velocity at interfaces A and B, Eq. (118) will give us the rate of change of mass within the cell, and hence the mass itself after an infinitesimal time  $\delta t$ . But we have to get the density at A and B and the velocity for the next time step. We must have recourse then to "averaging" procedures to get the density from a known cell mass and "interpolation" procedures to get the values of the interfaces from the cell average values. Through these two procedures, errors are introduced. Finally, we have to use a finite grid in any case.

Equations (118) to (120) can be written in a reduced form as

$$\frac{d}{dt} \int \rho \, d\Psi + \int \rho^* (\dot{u}^f - \dot{u}^g) \cdot \dot{n} dS = - \int T^* dS + \int G^* d\Psi$$
$$\Psi^g S^g S^g \Psi^g$$

where  $\rho^{\star}$  is a generalized density ( $\rho^{\star}$  denotes  $\rho$ ,  $\rho u^{\text{f}}$  and  $E \equiv \rho \left(e + \frac{|u|^2}{2}\right)$ ) in Eqs. (118) to (120), respectively),  $T^{\star}$  is a generalized surface stress  $(T^{\star} = 0, pn, pu^{\text{f}}, n)$ , while  $G^{\star}$  denotes a generalized body force ( $G^{\star} = 0$  in Eqs. (118) to (120)). The two integrals on the RHS are referred to as source terms.

A naive "finite-integral" form solution can be written as

$$\begin{bmatrix} mass within \\ control volume \\ att + \delta t \end{bmatrix} = \begin{bmatrix} mass within \\ control volume \\ att \end{bmatrix} = \begin{bmatrix} net outgoing \\ mass flux through \\ control surface \end{bmatrix} + [source terms].$$

As will be explained next, the above formula is supplemented with diffusion flux terms (actually diffusion and antidiffusion) to improve its accuracy.

#### ACCURACY

The above mathematical analysis was carried out assuming a fixed uniform grid and  $\frac{3\rho}{\partial t} + u_0 \frac{\partial \rho}{\partial x} = 0$ , where  $u_0 \equiv$  constant. We notice also the absence of any source term (inhomogeneous part of a conservation equation). The analytical solution was found out to be

 $\rho^{n+1} = A\rho^n$ 

where  $A = e^{-i\beta\epsilon}$ , then was expanded to get a numerical scheme that matches it up to a prescribed order of  $\beta$ . In this context the numerical scheme

is an approximate solution of the whole PDE, in contrast to schemes which approximate  $\frac{\partial}{\partial x}$  alone by a finite difference and  $\frac{\partial}{\partial t}$  alone. By getting a solution of the PDE as a whole, we mix the time and space derivatives for a higher order scheme. To see that, let us expand  $p(t + \delta t, x)$  in a Taylor series:

$$\rho(t + \delta t, \mathbf{x}) = \rho(t) + \delta t \frac{\partial o}{\partial t} \Big|_{\mathbf{x}} + \frac{\delta t^2}{2!} \frac{\partial^2 \rho}{\partial t^2} \Big|_{\mathbf{x}} + \dots$$
(121)

From the PDE

$$\frac{\partial \rho}{\partial t} = - u_0 \frac{\partial \rho}{\partial x}$$
(122a)

$$\frac{\partial^2 \rho}{\partial t^2} = \frac{\partial}{\partial t} \left( \frac{\partial}{\partial t} \right) = \frac{\partial}{\partial t} \left( -u_0 \frac{\partial \rho}{\partial x} \right) = -u_0 \frac{\partial}{\partial x} \left( \frac{\partial \rho}{\partial t} \right) - u_0^2 \frac{\partial^2 \rho}{\partial x^2} .$$
(122b)

Substituting Eqs. (122) into (121) we obtain

$$\rho(t + \delta t, x) = \rho(t) - u_0 \delta t \frac{\partial \rho}{\partial x} + \frac{u_0^2 \delta t^2}{2} \frac{\partial^2 \rho}{\partial x^2} + \dots, \qquad (123)$$

showing that we can get a better solution in the time domain (of higher order in  $\delta t$ ) by adding to  $[\varepsilon(t) - u_0 \delta t \frac{\partial \rho}{\partial x}]$  a diffusion term,  $\frac{u_0^2 \delta t^2}{2} \frac{\partial^2 \rho}{\partial x^2}$ , a purely spatial derivative. Notice that  $\frac{u_0^2(\delta t)^2}{2}$  is equivalent to  $\frac{\varepsilon}{2}^2$ , the coefficient of  $d\rho^n$  in the schemes discussed earlier. The remaining terms appear when we try to express  $\frac{\partial \rho}{\partial x}$  and  $\frac{\partial^2 \rho}{\partial x^2}$  in terms of finite differences accurately.

A scheme which splits the time and space domains, on the other hand, treats Eq. (122a) as an ODE, where the right-hand side is assumed to be a function of time. A second-order Runge-Kutta explicit scheme can be written as

$$\rho(t + \delta t, x) = \rho(t, x) - u_0 \delta t \frac{\partial \rho}{\partial x} t + \frac{\partial t}{2}, x \qquad (124)$$

where  $\frac{\partial \rho}{\partial x} |_t + \frac{\partial t}{2}$ , x is obtained by first getting a provisional value of the density at t +  $\frac{\partial t}{2}$  using a lower-order scheme

$$\rho(t + \frac{\delta t}{2}, x) = \rho(t, x) - u_0 \frac{\delta t}{2} \frac{\partial \rho}{\partial x} \Big|_{t, x}$$
(125)

then getting  $\frac{\partial o}{\partial x}\Big|_{t} + \frac{\partial t}{2}$ , x by differentiating  $\rho(t + \frac{\delta t}{2}, x)$  spatially, with the result

$$\frac{\partial \rho}{\partial \mathbf{x}} \Big|_{\mathbf{t}} + \frac{\delta \mathbf{t}}{2}, \mathbf{x} = \frac{\partial \rho}{\partial \mathbf{x}} \Big|_{\mathbf{t},\mathbf{x}} - \mathbf{u}_0 \frac{\delta \mathbf{t}}{2} \frac{\partial^2 \rho}{\partial \mathbf{x}^2} \Big|_{\mathbf{t},\mathbf{x}}$$

Upon substituting in Eq. (124), this yields Eq. (123) again. One can deduce therefore that up to a given order, schemes which mix the time and space domains and those which split them are equivalent. A warning, however, is in order here: A concept derived for a split time-space scheme cannot be applied directly to one that mixes both domains. For example, using a half point density in Eq. (123), i.e., the scheme

$$\rho(t + \frac{\delta t}{2}, x) = \rho(t, x) - u_0 \frac{\delta t}{2} \frac{\partial \rho}{\partial x} \Big|_{t, x} + \frac{u_0^2 \delta t^2}{8} \frac{\partial^2 \rho}{\partial x^2} \Big|_{t, x}$$
(126a)

$$\rho(t + \delta t, x) = \rho(t, x) - u_0 \delta t \frac{\partial \rho}{\partial x} t + \frac{\delta t}{2} x + \frac{u_0^2 \delta t^2}{2} \frac{\partial^2 \rho}{\partial x^2} t + \frac{\delta t}{2} x$$
(126b)

will cause a decrease in accuracy instead of improving it, as can be seen from differentiating Eq. (126a) with respect to x and substituting in Eq. (126b). The key point is that Eq. (123) is a solution of the PDE as a whole.

In summary, the schemes derived in earlier sections are solutions of the conservation equations if  $u^{f}$  = constant,  $u^{g}$  = 0, and source terms = 0.

If these are not satisfied, a correction that preserves the order of the scheme should be adopted. Here we split the two effects:

- (1)  $u^{f}$  variable and source terms are variable  $\neq 0$
- (2)  $u^g \neq 0$

and treat each separately.

#### GRID MOTION

According to the above splitting, we need to consider a case where  $u^{\hat{t}} \approx 0$  and source terms vanish, but  $u^{\hat{g}} \neq 0$ . This is a static field, where the density and energy are constants. Equations (118) and (120) reduce then to

$$\frac{d}{dt} \int \frac{d}{dt} = \int \vec{u}^{g} \cdot \vec{n} ds$$

$$\psi^{g} s^{g} s^{g}$$
(127)

This exhibits the formula for an accurate scheme when the grid is moving: the rate of change of volume equals the rate of sweeping by the moving surface, as illustrated in Fig. 11. Here we can achieve an infiniteorder accuracy in  $\delta t$  by defining a mean control area s<sup>mean</sup> such that

$$\int \vec{u}^{g} \delta t \cdot \vec{n} dS = swept volume$$

Let us consider the three cases of 1-D geometry; namely, planar, cylindrical, and spherical symmetries, denoted from now on by  $\chi = 1$ , 2, and 3, respectively.

In the planar case, the area is independent of the radius, so that

$$A_{\rm L}^{n+\frac{1}{2}} = A_{\rm R}^{n+\frac{1}{2}} = 1, \qquad (128)$$

41

where L and R denote the left and right interfaces of the control cell, respectively.

In cylindrical 1-D geometry, the volume swept by the interface is

$$\Delta \Psi_{\rm B} = \pi [(r_{\rm B}^{\rm n+1})^2 - (r_{\rm B}^{\rm n})^2],$$

where B indicates L or R. Here the depth of the cell being considered is taken equal to unity. Since  $u^g \, st = r_B^{n+1} - r_B^n$ , the average area is

$$A_{B}^{n+\frac{1}{2}} \equiv \frac{\Delta \Psi_{B}}{u^{g} \delta t} = \pi \frac{\left[ \left( r_{B}^{n+1} \right)^{2} - \left( r_{B}^{n} \right)^{2} \right]}{r_{B}^{n+1} - r_{B}^{n}} = \pi \left( r_{B}^{n+1} + r_{B}^{n} \right)$$
(129)

One can define then average radii

$$r_{B}^{n+\frac{1}{2}} \equiv \frac{1}{2}(r_{B}^{n} + r_{B}^{n+1}), \qquad (130)$$
  
since  $A_{B}^{n,n+\frac{1}{2},n+1} = 2\pi r_{B}^{n,n+\frac{1}{2},n+1}.$ 

Finally, in spherical geometry, the swept volume is

$$\Delta \Psi = \frac{4}{3} \pi [(r_{B}^{n+1})^{3} - (r_{B}^{n})^{3}],$$

yielding

$$A_{B}^{n+\frac{1}{2}} \equiv \frac{\Delta \Psi}{r_{B}^{n+1} - r_{B}^{n}} = \frac{4}{3} \pi [(r_{B}^{n})^{2} + (r_{B}^{n})(r_{B}^{n+1}) + (r_{B}^{n+1})^{2}].$$
(131)

whence

$$r_{\rm B}^{n+\frac{1}{2}} = \left\{ \frac{1}{3} \left[ \left( r_{\rm B}^{\rm n} \right)^2 + \left( r_{\rm B}^{\rm n} \right) \left( r_{\rm B}^{\rm n+1} \right) + \left( r_{\rm B}^{\rm n+1} \right)^2 \right\} \right\}^{\frac{1}{2}}, \tag{132}$$

since

$$A_{B}^{n,n+\frac{1}{2},n+\frac{1}{2}} = 4\pi(r_{B}^{n,n+\frac{1}{2},n+1})^{2}.$$

Equations (128), (129), and (131) should be used as the proper interface areas when evaluating the fluxes and surface forces. To complete the formulation, when body forces are present, the volume used should be that confined between the average interfaces. It can be arbitrarily selected for  $\alpha = 1$ , and is defined as

$$\Psi^{n+\frac{1}{2}} = \pi [(r_R^{n+\frac{1}{2}})^2 - (r_L^{n+\frac{1}{2}})^2]$$
(133)

for  $\alpha = 2$ , and

$$\Psi^{n+\frac{1}{2}} = \frac{4}{3} \pi \left[ \left( r_{R}^{n+\frac{1}{2}} \right)^{3} - \left( r_{L}^{n+\frac{1}{2}} \right)^{3} \right]$$
(134)

for  $\alpha = 3$ . This choice will ensure a proper balance between surface and body forces.

#### Variable Velocity Field and Source Terms

To account for these two effects, the fluid velocity and source terms used in the "finite-integral" solution should be evaluated at some intermediate time between  $t^n$ ,  $t^{n+1}$  so as to preserve the accuracy of the scheme. Since we split the effects of grid motion, variable velocity field and source terms, the above intermediate values should be derived from an ODE solver of a consistent order in  $\delta t$ . For a fourth-order (diffusion and phase error) accurate scheme, for example, we need a secondorder-accurate explicit ODE solver. In other words, for the system of Eqs. (118) to (120), we advance the time one-half step using  $\vec{u}^f = \vec{u}^n$ and  $p = p^n$  to get  $\rho^{n+\frac{1}{2}}$ ,  $(\sigma \vec{u}^f)^{n+\frac{1}{2}}$ . We define  $\vec{u}^{n+\frac{1}{2}} \equiv (\rho \vec{u}^f)^{n+\frac{1}{2}}/\rho^{n+\frac{1}{2}}$ and  $p^{n+\frac{1}{2}} \equiv p(\rho^{n+\frac{1}{2}}, e^{n+\frac{1}{2}})$  where  $p(\rho, e)$  is the equation of state and

$$e^{n+\frac{1}{2}} = (E^{n+\frac{1}{2}}/\rho^{n+\frac{1}{2}}) - \frac{|\dot{u}^{n+\frac{1}{2}}|^2}{2}$$
.

Then we advance the system a whole time step using  $\dot{u}^f = \dot{u}^{n+\frac{1}{2}}$  and  $p = p^{n+\frac{1}{2}}$ . As explained earlier, we need not and should not update  $\rho$ ,  $c\dot{u}^f$  and E, during the full time step, since the scheme is already a solution of the whole PDE. For a sixth-order-accurate scheme, we need a fourth-order ODE solver and so on.

#### Example of an Algorithm

Let us implement the scheme

$$\begin{split} \rho_{j}^{T} &= \rho_{j}^{n} - \frac{\varepsilon}{2} (\rho_{j+1}^{n} - \rho_{j-1}^{n}) + \frac{\varepsilon^{2}}{4} (\rho_{j+1}^{n} - 2\rho_{j}^{n} + \rho_{j-1}^{n}); \\ \rho_{j}^{TD} &= \rho_{j}^{T} + (\frac{1}{6} + \frac{\varepsilon^{2}}{12}) (\rho_{j+1}^{n} - 2\rho_{j}^{n} + \rho_{j-1}^{n}); \\ \rho_{j}^{n+1} &= \rho_{j}^{TD} - (\frac{1}{6} - \frac{\varepsilon^{2}}{6}) (\rho_{j+1}^{T} - 2\rho_{j}^{T} + \rho_{j-1}^{T}), \end{split}$$
(135)

a stable, fourth-order phase error, sixth-order diffusion error scheme, where  $\rho$  denotes either of  $\rho$ ,  $\rho u^{f}$ , or E.

If we have N cells whose interfaces are at radii  $(r_{1/2}^n, r_{3/2}^n, \ldots, r_{N+1/2}^n)$  at time t<sup>n</sup>, moving to  $(r_{1/2}^{n+1}, r_{3/2}^{n+1}, \ldots)$  at t<sup>n+1</sup>, let us denote the cell centers by the subscripts j = 1, 2,...,N, located at

$$\mathbf{r}_{j}^{n,n+1} = \begin{cases} \frac{1}{2} (\mathbf{r}_{j-1/2}^{n,n+1} + \mathbf{r}_{j+1/2}^{n,n+1}) & \text{for } \alpha = 1,2 \\ \\ (136) \\ (\frac{1}{3} [(\mathbf{r}_{j-1/2}^{n,n+1})^{2} + (\mathbf{r}_{j-1/2}^{n,n+1}) (\mathbf{r}_{j+1/2}^{n,n+1}) + (\mathbf{r}_{j+1/2}^{n,n+1})^{2}] \}^{\frac{1}{2}} & \text{for } \alpha = 3. \end{cases}$$

The volume of the j<sup>th</sup> cell per unit angle is given by

$$\Psi_{j}^{n,n+1} = \begin{cases} r_{j+1/2}^{n,n+1} - r_{j-1/2}^{n,n+1}, & \alpha = 1 \\ \frac{1}{2} \left[ (r_{j+1/2}^{n,n+1})^{2} - (r_{j-1/2}^{n,n+1})_{2} \right], & \alpha = 2 \\ \frac{1}{3} \left[ (r_{j+1/2}^{n,n+1})^{3} - (r_{j-1/2}^{n,n+1})_{3} \right], & \alpha = 3 \end{cases}$$
(137)

Denoting the mean interface radii by  $r_{j+\frac{1}{2}}^{n+\frac{1}{2}}$ , Eqs. (128), (130), and (132) imply for  $j = 0, \dots, N$ ,

$$r_{j+\frac{1}{2}}^{n+\frac{1}{2}} = \begin{cases} (r_{j+\frac{1}{2}}^{n} + r_{j+\frac{1}{2}}^{n+1})/2 & \alpha = 1, 2 \\ \\ (r_{j+\frac{1}{2}}^{n} + r_{j+\frac{1}{2}}^{n+1}) (r_{j+\frac{1}{2}}^{n+1}) - (r_{j+\frac{1}{2}}^{n+1})^{2} \\ \\ (138) \\ (138) \end{cases}$$

giving, according to Eqs. (128), (129), and (131), mean interface area per unit angle

$$A_{j+\frac{1}{2}}^{n+\frac{1}{2}} = \begin{cases} 1 \\ r_{j+\frac{1}{2}}^{n+\frac{1}{2}} \\ (r_{j+\frac{1}{2}}^{n+\frac{1}{2}})^{2} \\ (r_{j+\frac{1}{2}}^{n+\frac{1}{2}})^{2} \end{cases}$$
(139)

and mean cell volume per unit angle

$$\stackrel{n+\frac{1}{2}}{\forall j} = \begin{cases} (r_{j+\frac{1}{2}}^{n+\frac{1}{2}}) & -(r_{j-\frac{1}{2}}^{n+\frac{1}{2}}) \\ \frac{1}{2}[(r_{j+\frac{1}{2}}^{n+\frac{1}{2}})^{2} & -(r_{j-\frac{1}{2}}^{n+\frac{1}{2}})^{2}] \\ \frac{1}{3}[(r_{j+\frac{1}{2}}^{n+\frac{1}{2}})^{3} & -(r_{j-\frac{1}{2}}^{n+\frac{1}{2}})^{3}] \end{cases}$$
(140)

for  $\alpha = 1, 2, 3$ , respectively. We write Eq. (135a) in the form

$$\begin{aligned} \Psi_{j}^{n+1} \wp_{j}^{T} &= \Psi_{j}^{n} \wp_{j}^{n} - \delta t \left( \wp_{j+\frac{1}{2}}^{n} A_{j+\frac{1}{2}}^{n+\frac{1}{2}} \delta U_{j+\frac{1}{2}}^{n+\frac{1}{2}} \right) + \delta t \left( \wp_{j-\frac{1}{2}}^{n} A_{j-\frac{1}{2}}^{n+\frac{1}{2}} \delta U_{j-\frac{1}{2}}^{n+\frac{1}{2}} \right) \\ &+ \lambda_{j+\frac{1}{2}}^{n+\frac{1}{2}} \Psi_{j+\frac{1}{2}}^{n} \left( \wp_{j+\frac{1}{2}}^{n} - \wp_{j}^{n} \right) - \lambda_{j-\frac{1}{2}}^{n+\frac{1}{2}} \Psi_{j-\frac{1}{2}}^{n} \left( \wp_{j}^{n} - \wp_{j-1}^{n} \right) + \text{source } \frac{n+\frac{1}{2}}{j}, \end{aligned}$$
(141)

where

$$\rho_{j+\frac{1}{2}}^{n} = \frac{1}{2}(\rho_{j}^{n} + \rho_{j+1}^{n})$$
(142)

for  $j = 1, \ldots, N-1$ , while

$$z_{\frac{1}{2}}^{n} = \frac{1}{2}(z_{L}^{n} + z_{1}^{n}) , \quad \rho_{N-\frac{1}{2}}^{n} = \frac{1}{2}(\rho_{N}^{n} + \rho_{R}^{n}) ,$$

where L and R denote left and right guard cells, respectively. The difference  $3U_{j+\frac{1}{2}}$  between the fluid and grid velocities is given by

$$\delta U_{j+\frac{1}{2}}^{n+\frac{1}{2}} \delta t = U_{j+\frac{1}{2}}^{n+\frac{1}{2}} \delta t - U_{j+\frac{1}{2}}^{g} \delta t = U_{j+\frac{1}{2}}^{n+\frac{1}{2}} \delta t - (r_{j+\frac{1}{2}}^{n+1} - r_{j+\frac{1}{2}}^{n}), \qquad (143)$$

while the diffusion coefficient is

$$\lambda_{j+\frac{1}{2}}^{n+\frac{1}{2}} = \frac{1}{4} \left( \varepsilon_{j+\frac{1}{2}}^{n+\frac{1}{2}} \right)^2, \tag{244}$$

where

$$\varepsilon_{j+\frac{1}{2}}^{n+\frac{1}{2}} = \frac{\delta U_{j+\frac{1}{2}}^{n+\frac{1}{2}} A_{j+\frac{1}{2}}^{n+\frac{1}{2}} \delta t}{2} \left(\frac{1}{\psi_{j}^{n}} + \frac{1}{\psi_{j}^{n}}\right).$$
(145)

The velocity at the interfaces satisfies

$$U_{j+\frac{1}{2}}^{n+\frac{1}{2}} \approx \frac{1}{2} (U_{j}^{n+\frac{1}{2}} + U_{j+1}^{n+\frac{1}{2}})$$
(146)

for  $j = 1, \ldots, N-1$ , while

$$U_{\frac{1}{2}}^{n+\frac{1}{2}} = U_{L}^{n+\frac{1}{2}}, U_{N+\frac{1}{2}}^{n+\frac{1}{2}} = U_{R}^{n+\frac{1}{2}}.$$

The volumes  $\forall_{j+\frac{1}{2}}^n$  are defined as

$$\Psi_{j+\frac{1}{2}}^{n} = \frac{1}{2}(\Psi_{j}^{n} + \Psi_{j+1}^{n})$$
(147)

for  $j = 1, \ldots, N-1$ , and

$$\Psi_{\frac{1}{2}}^{n} = \Psi_{1}^{n}, \quad \Psi_{N+\frac{1}{2}}^{n} = \Psi_{N}^{n}.$$

Equation (135b) then adds the main diffusion, giving

$$\Psi_{j}^{n+1}\rho_{j}^{\text{TD}} = \Psi_{j}^{n+1}\rho_{j}^{\text{T}} + \nu_{j+\frac{1}{2}}^{n+\frac{1}{2}}\Psi_{j+\frac{1}{2}}^{n}(\rho_{j+j}^{n} - \rho_{j}^{n}) - \nu_{j-\frac{1}{2}}^{n+\frac{1}{2}}\Psi_{j-\frac{1}{2}}^{n}(\rho_{j}^{n} - \rho_{j-1}^{n})$$
(148)

where

$$v_{j+\frac{1}{2}}^{n+\frac{1}{2}} = \frac{1}{6} + \frac{\left(\frac{z_{j+\frac{1}{2}}^{n+\frac{1}{2}}\right)^2}{12}}{12} .$$
 (149)

Finally, the antidiffusive fluxes are evaluated according to

$$F_{j+\frac{1}{2}} = u_{j+\frac{1}{2}}^{n+\frac{1}{2}} \frac{v_{j+1}^{n+1}}{v_{j+\frac{1}{2}}^{n+1}} (v_{j+1}^{T} - v_{j}^{T}), \qquad (150)$$

where

$$\mu_{j+\frac{1}{2}}^{n+\frac{1}{2}} = \frac{1}{6} - \frac{\left(\varepsilon_{j+\frac{1}{2}}^{n+\frac{1}{2}}\right)^2}{6}, \qquad (151)$$

and then corrected using one of the flux limiters Eq. (64) or Eqs. (65)-(75). Let us select Eq. (64) on account of its simplicity. The corrected fluxes are given by

$$F_{j+\frac{1}{2}}^{c} = \text{sign} (F_{j+\frac{1}{2}}) \cdot \max \{0, \min [\text{sign} (F_{j+\frac{1}{2}}) \cdot \Psi_{j+\frac{1}{2}}^{n+1} \cdot (\circ_{j+2}^{\text{TD}} - \circ_{j+1}^{\text{TD}}), \\ |F_{j+\frac{1}{2}}|, \text{sign} (F_{j+\frac{1}{2}}) \cdot \Psi_{j-\frac{1}{2}}^{n+1} \cdot (\circ_{j}^{\text{TD}} - \circ_{j-1}^{\text{TD}})\}$$
(152)

whence

$$v_{j}^{n+1} = v_{j}^{TD} - \frac{1}{v_{j}^{n+1}} \left( F_{j+\frac{1}{2}}^{C} - F_{j-\frac{1}{2}}^{C} \right).$$
(153)

As for the source terms, they are summations over the surface or the volume of the cell. Let us consider first  $[-\int_{S} pn \, dS]$ , which yields [-grad p]. In  $s^{g}$ 

cartesian coordinates, following the diagram of Fig. 12,

source 
$$\frac{n+\frac{1}{2}}{j} = p_{j-\frac{1}{2}}^{n+\frac{1}{2}} A_{j-\frac{1}{2}}^{n+\frac{1}{2}} - p_{j+\frac{1}{2}}^{n+\frac{1}{2}} A_{j+\frac{1}{2}}^{n+\frac{1}{2}}$$
 (154)

where

$$p_{j+\frac{1}{2}}^{n+\frac{1}{2}} = \frac{1}{2}(p_{j}^{n+\frac{1}{2}} + p_{j+1}^{n+\frac{1}{2}})$$
for  $j = 1, ..., N-1$ , while  $p_{\frac{1}{2}}^{n+\frac{1}{2}} = p_{L}^{n+\frac{1}{2}}$  and  $p_{N+\frac{1}{2}}^{n+\frac{1}{2}} = p_{R}^{n+\frac{1}{2}}$ .
$$(155)$$

In cylindrical geometry, following Fig. 13, we have

source 
$$\sum_{j=1}^{n+\frac{1}{2}} = p_{j-\frac{1}{2}}^{n+\frac{1}{2}} A_{j-\frac{1}{2}}^{n+\frac{1}{2}} - p_{j+\frac{1}{2}}^{n+\frac{1}{2}} A_{j+\frac{1}{2}}^{n+\frac{1}{2}} + p_{j}^{n+\frac{1}{2}} (r_{j+\frac{1}{2}}^{n+\frac{1}{2}} - r_{j-\frac{1}{2}}^{n+\frac{1}{2}})$$

and since

$$r_{j+\frac{1}{2}}^{n+\frac{1}{2}} - r_{j-\frac{1}{2}}^{n+\frac{1}{2}} = \frac{(r_{j+\frac{1}{2}}^{n+\frac{1}{2}})^2 - (r_{j-\frac{1}{2}}^{n+\frac{1}{2}})^2}{r_{j+\frac{1}{2}}^{n+\frac{1}{2}} + r_{j-\frac{1}{2}}^{n+\frac{1}{2}}} = \frac{\psi_j^{n+\frac{1}{2}}}{r_j^{n+\frac{1}{2}}},$$

where from Eq. (136)

$$r_{j}^{n+\frac{1}{2}} = \frac{1}{2} \left( r_{j+\frac{1}{2}}^{n+\frac{1}{2}} + r_{j-\frac{1}{2}}^{n+\frac{1}{2}} \right)$$
(156)

for  $\alpha = 2$ , we can rewrite the expression for source  $\frac{n+\frac{1}{2}}{j}$  as

source 
$$\frac{n+\frac{1}{2}}{j} = p_{j-\frac{1}{2}}^{n+\frac{1}{2}} A_{j-\frac{1}{2}}^{n+\frac{1}{2}} - p_{j+\frac{1}{2}}^{n+\frac{1}{2}} A_{j+\frac{1}{2}}^{n+\frac{1}{2}} + \frac{p_{j}^{n+\frac{1}{2}}}{r_{j}^{n+\frac{1}{2}}} \nabla_{j}^{n+\frac{1}{2}},$$
 (157)

where we notice that  $p_j^{n+\frac{1}{2}}/r_j^{n+\frac{1}{2}}$  acts as a body force per unit volume per unit angle.

In spherical geometry,

source 
$$\frac{n+\frac{1}{2}}{j} = p_{j-\frac{1}{2}}^{n+\frac{1}{2}} A_{j-\frac{1}{2}}^{n+\frac{1}{2}} - p_{j+\frac{1}{2}}^{n+\frac{1}{2}} A_{j+\frac{1}{2}}^{n+\frac{1}{2}} + p_{j}^{n+\frac{1}{2}} ((r_{j+\frac{1}{2}}^{n+\frac{1}{2}})^{2})$$
  

$$- (r_{j-\frac{1}{2}}^{n+\frac{1}{2}})^{2}] = p_{j-\frac{1}{2}}^{n+\frac{1}{2}} A_{j-\frac{1}{2}}^{n+\frac{1}{2}} - p_{j+\frac{1}{2}}^{n+\frac{1}{2}} A_{j+\frac{1}{2}}^{n+\frac{1}{2}}$$

$$+ \frac{2p_{j}^{n+\frac{1}{2}}}{(r_{j}^{n+\frac{1}{2}})^{2}/r_{j,\alpha=2}^{n+\frac{1}{2}}} v_{j}^{n+\frac{1}{2}},$$

where from Eq. (136),

$$r_{j}^{n+\frac{1}{2}} = \frac{1}{3} \left[ \left( r_{j-\frac{1}{2}}^{n+\frac{1}{2}} \right)^{2} + \left( r_{j-\frac{1}{2}}^{n+\frac{1}{2}} \right) \left( r_{j+\frac{1}{2}}^{n+\frac{1}{2}} \right) + \left( r_{j+\frac{1}{2}}^{n+\frac{1}{2}} \right) \right]^{\frac{1}{2}}$$
(159)

for  $\alpha = 3$ , and

$$r_{j,\alpha=2}^{n+\frac{1}{2}} = \frac{r_{j+\frac{1}{2}}^{n+\frac{1}{2}} + r_{j-\frac{1}{2}}^{n+\frac{1}{2}}}{2}$$
Again,  $\frac{2p_{j}^{n+\frac{1}{2}}}{(r_{j}^{n+\frac{1}{2}})^{2}/r_{j,\alpha=2}^{n+\frac{1}{2}}}$  acts as a body force per unit volume per unit angle.  
Next we consider  $[-\int p u \cdot n dS]$ , which gives rise to the term  $[-div (pu)]$ .  
S<sup>g</sup>

For the three geometries, we get

source 
$$\frac{n+\frac{1}{2}}{j} = p_{j-\frac{1}{2}}^{n+\frac{1}{2}} U_{j-\frac{1}{2}}^{n+\frac{1}{2}} A_{j-\frac{1}{2}}^{n+\frac{1}{2}} - p_{j+\frac{1}{2}}^{n+\frac{1}{2}} U_{j+\frac{1}{2}}^{n+\frac{1}{2}} A_{j+\frac{1}{2}}^{n+\frac{1}{2}}$$
 (160)

In summary, all we need for the source terms is a routine to multiply by the frontal area for the surface integrals, or cell volume in the case volume integrals. Finally,  $U_j^{n+\frac{1}{2}}$  and source  $\frac{n+\frac{1}{2}}{j}$  are obtained by first advancing the whole system of Eqs. (136)-(160) a half time step using  $U_j^n$ , source  $\frac{n}{j}$ , then a whole time step using

$$U_{j}^{n+\frac{1}{2}}\Big|_{t \to t+\delta t} = U_{j}^{n+1}\Big|_{t \to t+\delta t/2}$$
(161)

and

source 
$$\frac{n+\frac{1}{2}}{j}\Big|_{t \to t+\delta t} = \text{source } \frac{n+1}{j}\Big|_{t \to t+\delta t/2}$$
 (162)

#### XI. TWO-DIMENSIONAL TRANSPORT

Now let us consider the two-dimensional equivalent of Eq. (2),

$$\frac{\partial \rho}{\partial t} + u_1 \frac{\partial \rho}{\partial x} + u_2 \frac{\partial \rho}{\partial y} = 0, \qquad (201)$$

whose analytic solution is

$$\rho(\mathbf{x},\mathbf{y},\mathbf{t}) = \rho(\mathbf{x} - \mathbf{u}_1 \mathbf{t},\mathbf{y} - \mathbf{u}_2 \mathbf{t},0), \qquad (202)$$

a wave propagating with velocity  $\vec{u} = (u_1, u_2)$ . Assuming an initial density (x, y, 0) = F(x, y), we Fourier analyze F(x, y) in space on a rectangle  $L_1 \times L_2$ with periodic boundary conditions:

$$F(\vec{r}) = \sum_{k=-\infty}^{\infty} \hat{\vec{s}}_{k} e^{-i\vec{k}\cdot\vec{r}}, \qquad (203a)$$

where  $\vec{r} = (x,y)$ , and  $\vec{k} = (k_1,k_2)$  is assumed to be normalized, i.e.,  $\vec{k}$ denotes  $2\pi (\frac{k_1}{L_1}, \frac{k_2}{L_2})$ . Notice that the summation of (203a) is actually a double summation.

$$\mathbf{F}(\mathbf{x},\mathbf{y}) = \sum_{k_1 = -\infty}^{\infty} \sum_{k_2 = -\infty}^{\infty} \hat{\delta}_{k_1} \cdot k_2 e^{i(k_1 \mathbf{x} + k_2 \mathbf{y})}.$$
(203b)

To gain insight, let us consider only one wave component of Eq. (203),

$$F(\vec{r}) = \sin \vec{k} \cdot \vec{r}$$
 (204a)

or

$$F(x,y) = \sin 2\pi \left(\frac{k_1 x}{L_1} + \frac{k_2 y}{L_2}\right).$$
 (204b)

Figure 21 shows the resulting waves for different values of  $(L_1, L_2)$ ,  $(k_1, k_2)$ . From Eq. (204b), F(x,y) is constant along lines of constant

 $(\frac{k_1x}{L_1} + \frac{k_2y}{L_2})$ . For example, the nodes of the wave coincide with the lines

$$\frac{k_1 x}{L_1} + \frac{k_2 y}{L_2} = 0, \frac{1}{2}, 1, \frac{3}{2}, 2, \dots$$
 (205)

which are normal to the wave vector  $\vec{k}$ .

To find the wave length for a given  $(k_1,k_2)$ , we first go back to the one-dimensional case. For a system of length L and periodic boundary conditions, the harmonics sin  $2\pi \frac{kx}{L}$  and cos  $2\pi \frac{ky}{L}$  are admitted, where k = 0,  $1,2,\ldots,\infty$ . With each of these is associated a wave length  $\lambda$  defined as the distance between two successive "even" nodes. Since sin  $2\pi \frac{kx}{L} = 0$  at  $\frac{2\pi kx}{L} = 0$ ,  $\pi, 2\pi, 3\pi, \ldots, \lambda$  is obtained from  $\frac{2\pi k\lambda}{L} \approx 2\pi$ , yielding

$$\lambda = \frac{L}{k} .$$
 (206)

We get therefore wave lengths  $\infty$ , L,  $\frac{L}{2}$ ,  $\frac{L}{3}$ ,  $\frac{L}{4}$ ,..., where the longest finite wave length equals L, the system length. In two-dimensional, the wave length for a given k is defined analogously as the distance between two points on successive "even" node lines, projected on the direction of  $\vec{k}$ . From Eq. (204b),

$$F(x,0) = \sin 2\pi \frac{k_1 x}{L_1}$$

which, as explained above, yields  $\lambda_{\mathbf{x}} = \frac{\mathbf{L}_1}{\mathbf{k}_1}$  where  $\lambda_{\mathbf{x}}$  is the wave length along the x-direction, which when projected on  $\mathbf{k} = 2\pi (\frac{\mathbf{k}_1}{\mathbf{L}_1}, \frac{\mathbf{k}_2}{\mathbf{L}_2})$  yields  $\lambda$ :

$$\lambda = \frac{\left(\frac{k_{1}}{k_{1}}, 0\right) \cdot \left(\frac{k_{1}}{L_{1}}, \frac{k_{2}}{L_{2}}\right)}{\sqrt{\left(\frac{k_{1}}{L_{1}}\right)^{2} + \left(\frac{k_{2}}{L_{2}}\right)^{2}}} = \frac{1}{\sqrt{\left(\frac{k_{1}}{L_{1}}\right)^{2} + \left(\frac{k_{2}}{L_{2}}\right)^{2}}} = \frac{2\pi}{\left|\vec{k}\right|},$$
(207a)

where

$$|\vec{k}| = \sqrt{\left(\frac{2\pi k_1}{L_1}\right)^2 + \left(\frac{2\pi k_2}{L_2}\right)^2}$$

or

$$\lambda = \frac{1}{\sqrt{\left(\frac{1}{\lambda_{x}}\right)^{2} + \left(\frac{1}{\lambda_{y}}\right)^{2}}}$$
(207b)

Now we find all the wavelengths along a given direction  $\frac{k_1}{L_1} : \frac{k_2}{L_2} =$  constant c. Noticing that  $k_1$ ,  $k_2$  for periodic boundary conditions can take only integer values, the waves along a given direction correspond to

$$k_1^{(n)} = nk_1^{(1)}, k_2^{(n)} = nk_2^{(1)}$$
  $(n = 1, 2, ..., \infty)$  where  $k_1^{(1)}, k_2^{(1)}$  are the smallest integers that satisfy

$$\frac{k_1^{(1)}/L_1}{k_2^{(1)}/L_2} = c$$

From Eq. (207a)

$$\lambda_{n} = \frac{1}{\sqrt{\frac{nk_{1}^{(1)}}{L_{1}}^{2} + (\frac{nk_{2}^{(1)}}{L_{2}})^{2}}}} = \frac{\lambda_{1}}{n}.$$
(208)

where

$$\lambda_{1} = \frac{1}{\sqrt{\left(\frac{k_{1}}{L_{1}}\right)^{2} + \left(\frac{k_{2}}{L_{2}}\right)^{2}}}.$$
(209)

Along a given direction we have wave lengths  $\lambda_1$ ,  $\frac{\lambda_1}{2}$ ,  $\frac{\lambda_1}{3}$ ,  $\dots$ ,  $\frac{\lambda_1}{\infty}$ . Consider, for example, Fig. 21(b), where  $L_1 = 2$ ,  $L_2 = 1$ . Along direction  $(1/2, 1), k_1^{(1)} = k_2^{(1)} = 1$ , whence  $\lambda_1 = 1\sqrt{(\frac{1}{2})^2 + 1} = 2\sqrt{5}$ . The maximum system length along this direction being  $\sqrt{\left(\frac{1}{2}\right)^2 + 1} = \sqrt{\frac{5}{2}}, \frac{\lambda_1}{L_{\frac{1}{2},1}} = \frac{2\sqrt{5}}{\sqrt{5}/2} = \frac{4}{5},$ showing that because of the periodic boundary condition independently in each direction the longest wave length is only 80 percent of the maximum system length in the direction  $(\frac{1}{2},1)$ , in contrast to one-dimensional cases where  $\lambda_1 = L$ . For the case of Fig. 21(a),  $\lambda_1$  is 50 percent of the system length.

From Eq. (202),

k<sub>1</sub>

$$\rho(\mathbf{x}, \mathbf{y}, \mathbf{t}) = \sum_{k_{1}=-\infty}^{\infty} \sum_{k_{2}=-\infty}^{\infty \hat{\rho}} k_{1}, k_{2} e^{i[k_{1}(\mathbf{x} - \mathbf{u}_{1}\mathbf{t}) + k_{2}(\mathbf{y} - \mathbf{u}_{2}\mathbf{t})]}$$
$$= \sum_{k_{1}} \sum_{k_{2}} \hat{\rho}_{k_{1}}, k_{2}^{(\mathbf{t})} e^{i(k_{1}\mathbf{x} + k_{2}\mathbf{y})}$$
(210a)

or

$$\rho(\vec{r},t) = \sum_{\vec{k}=-\infty}^{\infty} \hat{\rho}_{\vec{k}} e^{i\vec{k}\cdot(\vec{r}-\vec{u}t)} = \sum_{\vec{k}\neq0}^{\gamma} \hat{\rho}_{\vec{k}} e^{i\vec{k}\cdot\vec{r}}$$
(210b)

where

$$\hat{\rho}_{k_{1},k_{2}}^{(t)} = \hat{\rho}_{k_{1},k_{2}}^{-i(k_{1}u_{1} + k_{2}u_{2})t}$$
(211a)

or

$$\hat{\rho}_{i}(t) = \hat{\rho}_{i} e^{-i\vec{k}\cdot\vec{u}t}$$

$$\hat{k} \qquad (211b)$$

Thus each harmonic independently advances uniformly in phase without changing its magnitude, as shown in Fig. (22).

We notice that the different harmonics advance in the direction  $\vec{u}$ , which is generally different from that of k, as illustrated in Fig. (23). They keep their front normal to  $\vec{k}$  and therefore the projection of  $\vec{u}$  on  $\vec{k}$  is the speed of advance. This adds extra requirements that were not invoked in the one-dimensional case, namely:

- The scheme should keep the wave front a straight line;
   otherwise distortion of profiles occurs.
- 2. It should also keep the wave front normal to  $\vec{k}$ ; otherwise "scattering" occurs, namely waves with different  $|\vec{k}|$  but the same direction  $(k_1:k_2)$  will come out in different directions, causing scattering of the transported profile.

As will be proved later, the speed of propagation  $\vec{V}$  of a numerical scheme differs from  $\vec{u}$  not only in magnitude as in one dimension but also in direction, providing one more source of error. If the above two requirements are satisfied, however, only  $\vec{k} \cdot (\vec{v} - \vec{u})$  contributes to the phase error.

Now suppose 0 is known at all times only on a set of  $(N_1 + 1) \cdot (N_2 + 1)$ discrete grid points with separation  $\delta x = \frac{L_1}{N_1}$ ,  $\delta y = \frac{L_2}{N_2}$ , namely,  $x_1 = 1 \delta x$  $(i = 0, 1, ..., N_1 - 1)$ ,  $y_1 = j \delta y$   $(j = 0, 1, ..., N_2 - 1)$ , the origin being a member of the set. According to periodicity assumption  $\delta_{0,j} = \delta_{N_1,j}\delta_{1,0} = \delta_{1,N_2}$ hence we can have only  $\frac{N_1N_2}{2} + 1$  different harmonics. Let  $f(x,y) = \sum_{k_1} = \frac{N_1}{2} \sum_{k_2} = \frac{N_2}{2} \hat{\delta}_{k_1,k_2} e^{i(k_1x + k_2y)}$ . (212)

Since  

$$e^{i(k_1x + k_2y)} |_{k_1} = \frac{N_1}{2} = e^{i(\frac{2\pi}{L_1}(\frac{N_1}{2})i\delta x + \frac{2\pi k_2}{L_2}j\delta y)} = e^{i(i\pi + 2\pi}\frac{k_2}{L_2}j\delta y)$$
  
 $= e^{i[i\pi + 2\pi}\frac{k_2}{L_2}j\delta y) - 2\pi i] = e^{i(-i\pi + \frac{2\pi k_2}{L_2}j\delta y)}$   
 $= e^{i[\frac{2\pi}{L_1}(\frac{-N_1}{2})i\delta x + \frac{2\pi k_2}{L_2}j\delta y]} = e^{i(k_1x + k_2y)} |_{k_1} = \frac{-N_1}{2}$ 

for all i, and similarly

$$e^{i(k_1x + k_2y)} k_2 = \frac{-N_2}{2} = e^{i(k_1x + k_2y)} k_2 = \frac{N_2}{2}$$

for all j, Eq. (212) can be rewritten as

$$f(x,y) = \sum_{k_{1}=\frac{-N_{1}}{2}}^{\frac{N_{1}}{2}} \sum_{k_{2}=\frac{-N_{2}}{2}}^{\frac{N_{1}}{2}} \hat{\rho}_{k_{1}} k_{2} e^{i(k_{1}x + k_{2}y)},$$

$$k_{1} = \frac{-N_{1}}{2} + 1 \quad k_{2} = \frac{-N_{2}}{2} + 1$$

showing that  $\vec{k}$  space structure contains only  $N_1 \times N_2$  independent points (see Fig. 24). The amplitudes  $\hat{\beta}_{k_1,k_2}$  can be obtained from

$$\rho_{i,j}^{0} = \sum_{k_{1}} \sum_{l=1}^{\frac{N_{1}}{2}} \sum_{k_{2}} \sum_{l=1}^{\frac{N_{2}}{2}} \hat{\rho}_{k_{1},k_{2}} e^{i(\frac{2\pi k_{1}i\delta x}{L_{1}} + \frac{2\pi k_{2}j\delta y}{L_{2}})}$$
(214)  
$$k_{1} = \frac{-N_{1}}{2} + 1 \quad k_{2} = \frac{-N_{2}}{2} + 1$$

for  $i = 0, 1, 2, ..., N_1^{-1}$ , and  $j = 0, 1, 2, ..., N_2^{-1}$ .

In terms of sines and cosines, Eq. (213) can be written as

$$f(x,y) = A_{0,0} + \left( \sum_{k_1=1}^{N_1} \sum_{k_2=1}^{N_2} A_{k_1,k_2} \cos \left( \frac{2\pi k_1 x}{L_1} + \frac{2\pi k_2 y}{L_2} \right) \right)$$

$$+ B_{k_{1},k_{2}} \sin \left(\frac{2\pi k_{1}x}{L_{1}} + \frac{2\pi k_{2}y}{L_{2}}\right) + C_{k_{1},k_{2}} \cos \left(\frac{2\pi k_{1}x}{L_{1}} - \frac{2\pi k_{2}y}{L_{2}}\right) + \sum_{k_{1}=1}^{N_{1}} \left(\frac{2\pi k_{1}x}{L_{1}} - \frac{2\pi k_{2}y}{L_{2}}\right) + \sum_{k_{1}=1}^{N_{1}} \left(\frac{2\pi k_{1}x}{L_{1}} - \frac{2\pi k_{2}y}{L_{2}}\right) + \sum_{k_{1}=1}^{N_{1}} \left(\frac{2\pi k_{1}x}{L_{1}} - \frac{2\pi k_{2}y}{L_{2}}\right) + \frac{N_{1}}{k_{1}} + \sum_{k_{1}=1}^{N_{2}} \left(\frac{N_{1}}{k_{1}} - \frac{2\pi k_{2}y}{L_{1}}\right) + \frac{N_{1}}{k_{1}} + \frac{N_{1}}{k_{2}} - \frac{2\pi k_{2}y}{L_{2}} + \frac{N_{2}}{k_{1}} + \frac{N_{2}}{k_{2}} - \frac{2\pi k_{2}y}{L_{2}} + \frac{N_{2}}{k_{2}} + \frac{N_{2}}{k_{2}$$

S.

where

$$\hat{\delta}_{k_{1},k_{2}} = \begin{cases} \frac{A_{k_{1},k_{2}} - iB_{k_{1},k_{2}}}{2} & \text{for } k_{1} > 0, \ k_{2} > 0 \\ \frac{A_{k_{1},k_{2}} + iB_{k_{1},k_{2}}}{2} & \text{for } k_{1} < 0, \ k_{2} < 0 \\ \frac{C_{k_{1},k_{2}} - iD_{k_{1},k_{2}}}{2} & \text{for } k_{1} > 0, \ k_{2} < 0 \\ \frac{C_{k_{1},k_{2}} + iD_{k_{1},k_{2}}}{2} & \text{for } k_{1} > 0, \ k_{2} < 0 \end{cases}$$

Again, we have in Eq. (215)  $N_1 \times N_2$  coefficients:  $A_{k_1,k_2}(k_1 = 0,1,...,\frac{N_1}{2})$ and  $k_2 = 0,1,...,\frac{N_2}{2})$ ,  $B_{k_1,k_2}(k_1 = 0,1,...,\frac{N_1}{2} - 1)$  and  $k_2 = 0,1,...,\frac{N_2}{2} - 1)$ ,  $C_{k_1,k_2}$ ,  $D_{k_1,k_2}(k_1 = 1,2,...,\frac{N_1}{2} - 1)$  and  $k_2 = 1,2,...,\frac{N_2}{2} - 1)$  that can be

determined from the system of equations  $f(x_i, x_j) \equiv \rho_{i,j}^{\circ}$ .

Going back to Fig. 24 let us count the different harmonics. The harmonics are considered equal if they have the same magnitude

 $|\vec{k}| = \sqrt{\frac{2\pi k_1}{L_1}}^2 + \frac{2\pi k_2}{L_2}^2$  and are aligned, i.e.,  $\frac{k_1}{L_1} : \frac{k_2}{L_2} = \text{constant}$ . The number of the harmonics is almost half the space of Fig. 24 since  $(k_1, k_2)$  is equivalent to  $(-k_1, -k_2)$  and  $(k_1, -k_2)$  is equivalent to  $(-k_1, k_2)$ . For example: a and b in Fig. 24 are equivalent. Figure 25 shows the independent harmonics selected to match the choice in Eq. (215). The number of the harmonics is therefore,  $\frac{N_1N_2}{2} + 1$ .

If we count the maximum number of wave lengths, we get an even smaller number, since according to Eq. (207a),  $\lambda = \frac{2\pi}{|\vec{k}|}$ . Two harmonics such as a and b in Fig. 25 will give the same value for  $|\vec{k}|$ . The maximum number of wave lengths is therefore  $(\frac{N_1}{2} + 1) \cdot (\frac{N_2}{2} + 1)$ , corresponding to the positive quadrant of Fig. 25. This is an upper limit. This is because the number of wave lengths can be less if the ratio  $\frac{\delta x}{\delta y}$  is a rational number. As explained above, decomposition in two directions puts a limit on the longest finite wave length  $\lambda$  in a given direction. Discretization, on the other hand, puts a limit on the shortest wave length in a given direction since it reduces n in Eq. (208). The largest value occurs for  $k_1 = \frac{N_1}{2}$ ,  $k_2 = \frac{N_2}{2}$ . If  $k_1^{(1)}$ ,  $k_2^{(2)}$  are the smallest integers for a given direction, the shortest wave length along this direction

corresponds to

$$n = \min_{\text{integer}} \left( \frac{N_1/2}{k_1^{(1)}}, \frac{N_2/2}{k_2^{(2)}} \right).$$
(216)

Assuming  $\rho(x,y,0) = f(x,y)$ , i.e., assuming the density in between the grid points values  $\rho_{i,j}^{0}$  to be f(x,y), Eq. (202) predicts the density at time t as

$$\rho(\mathbf{x},\mathbf{y},\mathbf{t}) = \sum_{k_{1}=-N_{1} \atop k_{2}=-N_{1}}^{N_{1}} \sum_{k_{2}=-N_{2} \atop k_{1},k_{2}=-N_{2} \atop k_{2}=-N_{2} \atop k_{1},k_{2}=-N_{2} \atop k_{2}=-N_{2} \atop k_{2}=-N_{$$

where  $\hat{o}_{k_1,k_2}(t) = \hat{\delta}_{k_1,k_2} e^{-i(k_1u_1t + k_2u_2t)}$ . Since we are only concerned with  $p(x_i, y_j, t)$ , let  $x = x_i = i\delta x$ ,  $y = y_j = j\delta y$ . We then get

$$\rho(x_{i}, y_{j}, t) = \sum_{k_{1}} \frac{N_{1}}{2} \sum_{k_{2}} \frac{N_{2}}{2} \hat{\rho}_{k}(t) e^{i(k_{1}i\delta x + k_{2}j\delta y)}.$$
 If the time  
$$k_{1} = \frac{-N_{1}}{2} + 1 \quad k_{2} = \frac{-N_{2}}{2} + 1$$

is also discretized, let  $t^{n} \equiv n\delta t$ ,  $\rho_{i,j}^{n} \equiv \rho(x_{i}, y_{j}, t^{n})$  and  $\hat{\rho}_{k_{1}}^{n}, k_{2} = \hat{\rho}_{k_{1}}^{n}, k_{2}^{(t^{n})}$ . Then  $\rho_{i,j}^{n} = \sum_{k_{1}} \sum_{k_{2}} \beta_{k_{1}}^{n}, k_{2} e^{i(k_{1} i\delta x + k_{2} j\delta y)}$ (217)

where

$$\hat{v}_{k_{1},k_{2}}^{n} = \hat{s}_{k_{1},k_{2}}^{n} e^{-i(k_{1}u_{1} + k_{2}u_{2})n\delta t}$$
(218)

We define  $A(k_1, k_2)$  as

$$A(k_1, k_2) = \frac{\hat{s}_{k_1, k_2}^{n+1}}{\hat{s}_{k_1, k_2}^{n}}.$$

Equation (218) expresses the analytic solution as

$$A(k_{1},k_{2}) = e^{-i(k_{1}u_{1}\delta t + k_{2}u_{2}\delta t)}.$$
(219)

If we denote  $\frac{u_1 \delta t}{\delta x}$  by  $\varepsilon_x$ ,  $\frac{u_2 \delta t}{\delta y}$  by  $\varepsilon_y$ ,  $k_1 \delta x$  by  $\beta_x$ , and  $k_2 \delta y$  by  $\beta_y$ , Eq. (219) reduces to

$$A(k_1, k_2) = e^{-i(\varepsilon_x \beta_x + \varepsilon_y \beta_y)}$$
(220)

Now let us analyze a fully two-dimensional scheme, a direct extension of the one-dimensional scheme

$$\rho_{j}^{T} = \rho_{j}^{n} - \frac{\varepsilon}{2}(\rho_{j+1}^{n} - \rho_{j-1}^{n})$$

$$\rho_{j}^{TD} = \rho_{j}^{T} + \nu(\rho_{j+1}^{n} - 2\rho_{j}^{n} + \rho_{j-1}^{n})$$

$$\rho_{j}^{n+1} = \rho_{j}^{TD} - \nu(\rho_{j+1}^{T} - 2\rho_{j}^{T} + \rho_{j-1}^{T}), \qquad (221)$$

namely,

$$\rho_{i,j}^{Tx} = \rho_{i,j}^{n} - \frac{\varepsilon_{x}}{2} (\rho_{i+1,j}^{n} - \rho_{i-1,j}^{n}); \qquad (222a)$$

$$\rho_{i,j}^{TY} = \rho_{i,j}^{n} - \frac{\varepsilon_{Y}}{2} (\rho_{i,j+1}^{n} - \rho_{i,j-1}^{n}); \qquad (222b)$$

$$\rho_{i,j}^{T} = \rho_{i,j}^{n} - \frac{\varepsilon_{x}}{2} (\rho_{i+1,j}^{n} - \rho_{i-1,j}^{n}) - \frac{\varepsilon_{y}}{2} (\rho_{i,j+1}^{n} - \rho_{i,j-1}^{n}); \qquad (222c)$$

$$\rho_{i,j}^{TD} = \rho_{i,j}^{T} + v_{x}(\rho_{i+1,j}^{n} - 2\rho_{i,j}^{n} + \rho_{i-1,j}^{n}) + v_{y}(\rho_{i,j+1}^{n} - 2\rho_{i,j}^{n}) + \rho_{i,j-1}^{n}); \qquad (222d)$$

150

$$b_{i,j}^{n+1} = p_{i,j}^{TD} - \mu_x (p_{i+1,j}^{Tx} - 2p_{i,j}^{Tx} + b_{i-1,j}^{Tx}) - \mu_y (p_{i,j+1}^{Ty} - 2p_{i,j}^{Ty} + p_{i,j-1}^{Ty}).$$
(222e)

Again as in one-dimension, after Fourier-analyzing the initial density profile, i.e., after we have gotten the  $[\hat{\beta}_{k_1}, k_2]$ , the problem is reduced to propagation of the complex harmonics  $e^{i(k_1x^2 + k_2y)}$ . Since for the linear problem Eq. (201), each harmonic propagates independently, we can get  $A(k_1, k_2)$  by assuming only one harmonic:

$$p_{i,j}^{n} = p_{e}^{o} e^{i(k_{1}i\delta x + k_{2}j\delta y)} = p_{e}^{o} e^{i(i\beta_{x} + j\beta_{y})}, \qquad (223)$$

then using

$$A(k_{1},k_{2}) = \frac{p_{1,j}^{n+1}}{p_{1,j}^{n}}.$$
 (224)

Substituting Eq. (223) into (222a) we get

$$\sigma_{i,j}^{Tx} = \rho^{\circ} e^{i(k_{1}i\delta x + k_{2}j\delta y)} - \frac{\varepsilon_{x}}{2} \{\rho^{\circ} e^{i[k_{1}(i+1)\delta x + k_{2}j\delta y]} - \rho^{\circ} e^{i[k_{1}(i-1)\delta x + k_{2}j\delta y]} \}$$
(225)

hence

$$\frac{c_{i,j}^{Tx}}{p_{i,j}^{n}} = 1 - \frac{\varepsilon_{x}}{2} (e^{i\beta_{x}} - e^{-i\beta_{x}}) = 1 - i\varepsilon_{x} \sin\beta_{x}$$
(226a)

Similarly Eq. (222b) gives

$$\frac{\sum_{i,j}^{Ty}}{\sum_{i,j}^{n}} = 1 - i \varepsilon_{y} \sin \beta_{y}.$$
(226b)

Denoting i sin  $\beta_x$  by t and i sin  $\beta_y$  by t, Eq. (222c) gives

$$\frac{\partial_{i,j}^{T}}{\partial_{i,j}^{n}} \approx 1 - \varepsilon_{x} t_{x} - \varepsilon_{x} t_{x}$$
(226c)

Substituting Eq. (223) into (222d)

$$\frac{\rho_{i,j}^{T}}{\rho_{i,j}^{n}} = \frac{\rho_{i,j}^{T}}{\rho_{i,j}^{n}} + v_{x} (e^{i\beta_{x}} - 2 + e^{-i\beta_{x}}) + v_{y} (e^{i\beta_{y}} - 2 + e^{-i\beta_{y}})$$

$$= \frac{\rho_{i,j}^{T}}{\rho_{i,j}^{n}} + v_{x} d_{x} + v_{y} d_{y}, \qquad (226d)$$

where  $d_x \equiv 2(\cos \beta_x - 1)$  and  $d_y \equiv 2(\cos \beta_y - 1)$ . Finally, Eq. (222e) yields with Eqs. (226c) and (226d)

$$A(\beta_{\mathbf{x}},\beta_{\mathbf{y}}) = \frac{\rho_{\mathbf{i},\mathbf{j}}^{\mathbf{n}+1}}{\rho_{\mathbf{i},\mathbf{j}}^{\mathbf{n}}} = (1 - \varepsilon_{\mathbf{x}}t_{\mathbf{x}} - \varepsilon_{\mathbf{y}}t_{\mathbf{y}}) + \nu_{\mathbf{x}}d_{\mathbf{x}} + \nu_{\mathbf{y}}d_{\mathbf{y}} - \mu_{\mathbf{x}}d_{\mathbf{x}}(1 - \varepsilon_{\mathbf{x}}t_{\mathbf{x}}) - \mu_{\mathbf{y}}d_{\mathbf{y}}(1 - \varepsilon_{\mathbf{y}}t_{\mathbf{y}})$$

$$(226e)$$

From which

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$$p_{i,j}^{n+1} = A(\beta_x, \beta_y) p_e^{i(i\beta_x + j\beta_y)}$$

We notice that the coefficient of  $e^{i(i\beta_x + j\beta_y)}$  is independent of i and j, i.e., independent of x,y. Consequently,  $\rho_{i,j}^{n+1}$  have the same wave front inclination and shape as  $\rho_{i,j}^n$ ; i.e., along the lines of  $k_1x + k_2y$ = constant,  $\rho_{i,j}^{n+1}$  = constant. Finally, this is a nine-point explicit scheme, as illustrated in Fig. 26, which shows the points involved in determining  $\rho_{i,j}^{n+1}$ .

### XII. AMPLITUDE AND PHASE ANALYSIS

We write A as  $A = |A|e^{i\vartheta}$ , where |A| is the amplitude and  $\vartheta$  is the phase angle. To classify the order of the scheme we need to expand |A| and  $\vartheta$  in a power series in  $\beta_x$  and  $\beta_y$ .

#### PHASE ERRORS

In the two-dimensional case we have  $A = A(t_x, t_y, d_x, d_y)$  where  $t_x, d_x$ are functions of  $\beta_x$ , while  $t_y, d_y$  are functions of  $\beta_y$ . Since log  $A = \log |A|$ + i(3),

$$\theta = \operatorname{Im} (\log A). \tag{229}$$

Expanding  $\beta$  in a power series of  $\beta_x$ ,  $\beta_y$  near  $\beta_x$ ,  $\beta_y = 0$ , we get

$$\vartheta = \vartheta_{0} + (\vartheta_{0}^{x} \vartheta_{x} + \vartheta_{0}^{y} \vartheta_{y}) + (\vartheta_{0}^{xx} \frac{\vartheta_{x}^{2}}{2} + \vartheta_{0}^{xy} \vartheta_{x} \vartheta_{y} + \vartheta_{0}^{yy} \frac{\vartheta_{y}^{2}}{2})$$
(230)

+ 
$$(\theta_{o}^{\mathbf{x}\mathbf{x}\mathbf{x}} \frac{\beta_{\mathbf{x}}^{3}}{6} + \theta_{o}^{\mathbf{x}\mathbf{x}\mathbf{y}} \frac{\beta_{\mathbf{x}}^{2}\beta_{\mathbf{y}}}{2} + \theta_{o}^{\mathbf{x}\mathbf{y}\mathbf{y}} \frac{\beta_{\mathbf{x}}\beta_{\mathbf{y}}^{2}}{2} + \theta_{o}^{\mathbf{y}\mathbf{y}\mathbf{y}} \frac{\beta_{\mathbf{y}}}{6}) + \dots,$$
 (230)

where  $\vartheta_{0}^{\mathbf{X}} \equiv (\vartheta \vartheta / \vartheta \beta_{\mathbf{X}})$  at  $\beta_{\mathbf{X}} = 0$ , while  $\vartheta_{0}^{\mathbf{Y}} \equiv (\vartheta \vartheta / \vartheta \beta_{\mathbf{Y}})$  at  $\beta_{\mathbf{Y}} = 0$ , etc.

We therefore need the derivatives of log A. Noticing that 
$$A(\beta_x, \beta_z = 0) = 1$$
 we get

$$(\log A)_{0}^{X} = A_{0}^{X}$$
(231a)

$$(\log A)_{O}^{Y} = A_{O}^{Y};$$
(231b)

$$(\log A)_{o}^{XX} = A_{o}^{XX} - (A_{o}^{X})^{2};$$
 (232a)

$$(\log A)_{0}^{XY} = A_{0}^{XY} - A_{0}^{X}A_{0}^{Y};$$
(232b)

62**-**a

$$(\log A)_{o}^{YY} = A_{o}^{YY} - (A_{o}^{Y})^{2}$$
 (232c)

$$(\log A)_{0}^{XXX} = A_{0}^{XXX} - 3A_{0}^{XX}A_{0}^{X} + 2(A_{0}^{X})^{3};$$
(233a)

$$(\log A)_{0}^{XXY} = A_{0}^{XXY} - 2A_{0}^{XY}A_{0}^{X} - A_{0}^{XX}A_{0}^{Y} + 2(A_{0}^{X})^{2}A_{0}^{Y};$$
(233b)

$$(\log A)_{O}^{XYY} = A_{O}^{XYY} - 2A_{O}^{XY}A_{O}^{Y} - A_{O}^{X}A_{O}^{YY} + 2A_{O}^{X}(A_{O}^{Y})^{2}; \qquad (233c)$$

$$(\log A)_{O}^{YYY} = A_{O}^{YYY} - 3A_{O}^{YY}A_{O}^{Y} + 2(A_{O}^{Y})^{3};$$
(233d)

and so on.

Denoting 
$$\frac{\partial()}{\partial t_x} | \beta_x, \beta_y = 0$$
 by (),  $\frac{t_x}{\partial t_x}, \frac{\partial()}{\partial d_x} | \beta_x, \beta_y = 0$  by (),  $\frac{d_x}{\partial t_x}, \frac{\partial()}{\partial d_x}$ 

so on, confining our scope to schemes of second degree in the operators  $t_x, t_y, d_x$ , or  $d_y$ , and using the chain rule of differentiation we get

$$A_{0}^{X} = A_{0}^{X} t_{X0}' + A_{0}^{X} d_{X0}';$$
(235a)

$$A_{0}^{Y} = A_{0}^{Y} t_{y0}^{i} + A_{0}^{Y} d_{y0}^{i};$$
(235b)

$$A_{0}^{XX} = t_{X0}^{t} A_{0}^{X} + d_{X0}^{t} A_{0}^{X} + t_{X0}^{t} A_{0}^{t} + 2t_{X0}^{t} d_{X0}^{X} + d_{X0}^{t} A_{0}^{d} + t_{X0}^{t} A_{0}^{d} + 2t_{X0}^{t} d_{X0}^{d} A_{0}^{d} + d_{X0}^{t} A_{0}^{d} + t_{X0}^{t} +$$

$$A_{o}^{xy} = t_{xo}^{t} t_{yoo}^{xy} + t_{xo}^{t} d_{xo}^{xy} + d_{xo}^{t} t_{yoo}^{xy} + d_{xo}^{t} d_{yoo}^{xy} + d_{xo}^{t} d_{yoo}^{xy}, \qquad (236b)$$

$$A_{0}^{YY} = t_{y00}^{'t} + d_{y00}^{'t} + t_{y00}^{'t} + t_{y00}^{'t} + 2t_{y00}^{'t} + d_{y00}^{'t} + d_{y000}^{'t} + d_{y$$

$$A_{o}^{XXX} = t_{XOo}^{'''} + d_{XOo}^{''} + 3t_{XO}^{''} + 3t_{XOO}^{''} +$$

$$-3(t_{xo}d_{xo} + t_{xo}d_{xo})A_{o} + 3d_{xo}d_{xo}A_{o}; \qquad (237a)$$

$$\mathbf{A}_{o}^{\mathbf{X}\mathbf{X}\mathbf{Y}} = \mathbf{t}_{\mathbf{X}o}^{\mathbf{T}} \mathbf{t}_{\mathbf{Y}o}^{\mathbf{T}} \mathbf{A}_{o}^{\mathbf{T}} + \mathbf{t}_{\mathbf{X}o}^{\mathbf{T}} \mathbf{d}_{\mathbf{Y}o}^{\mathbf{T}} \mathbf{d}_{\mathbf{X}}^{\mathbf{T}} \mathbf{y} + \mathbf{d}_{\mathbf{X}o}^{\mathbf{T}} \mathbf{d}_{\mathbf{Y}o}^{\mathbf{T}} \mathbf{y} + \mathbf{d}_{\mathbf{X}o}^{\mathbf{T}} \mathbf{y} + \mathbf{d}_{\mathbf{T}o}^{\mathbf{T}} \mathbf{y} + \mathbf{$$

$$A_{o}^{XYY} = t_{xo}^{'} t_{yoo}^{'} t_{yoo}^{'} + t_{xo}^{'} t_{yoo}^{'} + d_{xo}^{'} t_{yoo}$$

$$\mathbf{A}_{o}^{YYY} = t_{yo}^{'''} \mathbf{A}_{o}^{''} + d_{yo}^{'''} \mathbf{A}_{o}^{''} + 3t_{yo}^{''} t_{yo}^{''} \mathbf{A}_{o}^{''} \mathbf{Y}$$

$$+ 3(t_{yo}^{''} d_{yo}^{''} + t_{yo}^{''} d_{yo}^{''}) \mathbf{A}_{o}^{''} + 3d_{yo}^{''} d_{yo}^{''} \mathbf{A}_{o}^{''} \mathbf{Y}$$
(237d)

Finally,

$$A_{o}^{XXXX} = t_{xo}^{v} t_{o}^{t} + d_{xo}^{v} t_{o}^{t} + (4t_{xo}^{v} t_{xo}^{t} + 3t_{xo}^{v}) A_{o}^{t} + (4t_{xo}^{v} t_{xo}^{t} + 4t_{xo}^{v} t_{o}^{t}) A_{o}^{t} + (4t_{xo}^{v} t_{xo}^{t} + 3t_{xo}^{v}) A_{o}^{t} + (4t_{xo}^{v} t_{xo}^{t} + 3t_{xo}^{v} + 3t_{xo}^{v}) A_{o}^{t} + (4t_{xo}^{v} t_{xo}^{t} + 3t_{xo}^{v} + 3t_{xo}^{v}) A_{o}^{t} + (4t_{xo}^{v} t_{xo}^{t} + 3t_{xo}^{v}) A_{o}^{t} + (4t_{xo$$

$$A_{0}^{XXXY} = t_{X0}^{''} (t_{y00}^{t} + t_{y00}^{t}) + t_{y00}^{t} + t_{y000}^{t} +$$

$$A_{o}^{xxyy} = t_{xo}^{"} t_{yo}^{t} A_{o}^{x} + d_{xo}^{d} A_{o}^{x} + t_{xo}^{d} A_{yo}^{t} + d_{xo}^{t} t_{yo}^{d}$$
(239c)

$$A_{0}^{XYYY} = t_{y0}^{'''} (t_{x00}^{t} + d_{x00}^{t}) + d_{y0}^{t} (t_{x00}^{t} + d_{x00}^{t}); \qquad (239d)$$

$$A_{o}^{YYYY} = t_{yoo}^{'v} t_{o}^{'v} + d_{yoo}^{'v} t_{o}^{'y} + (4t_{yo}^{'v} t_{yo}^{'v} + 3t_{yo}^{'v} t_{o}^{'v} - (4t_{yo}^{'v} t_{yo}^{'v} t_{o}^{'v} + 6t_{yo}^{'v} t_{o}^{'v} + 4t_{yo}^{'v} t_{o}^{'v} + (4t_{yo}^{'v} t_{o}^{'v} + 3t_{yo}^{'v} t_{o}^{'v} + 3t_{yo}^{'v} t_{o}^{'v} + 3t_{yo}^{'v} t_{o}^{'v} + 3t_{o}^{'v} t_{o}^{'v} + 3t$$

Going back to the definitions of  $t_x, t_y, d_x$ , and  $d_y$ ,

$$t_{x0} = t_{y0} = 0;$$
  

$$t_{x0}' = t_{y0}' = i;$$
  

$$t_{x0}'' = t_{y0}'' = 0;$$
  

$$t_{x0}''' = t_{y0}'' = -i;$$
  

$$t_{x0}''' = t_{y0}'' = 0;$$
  
(240a)

$$d_{xo} = d_{yo} = 0;$$
  

$$d_{xo} = d_{yo} = 0;$$
  

$$d_{xo} = d_{yo} = -2;$$
  

$$d_{xo} = d_{yo} = -2;$$
  

$$d_{xo} = d_{yo} = 0;$$
  

$$d_{xo} = d_{yo} = 0;$$
  

$$d_{xo} = d_{yo} = 2.$$
  
(240b)

Substituting into Eqs. (235)-(239) and assuming A x = A = y = 0, we get

$$A_{0} = 1;$$
 (241)

$$A_{O}^{X} = iA_{O}^{X}, \quad A_{O}^{Y} = iA_{O}^{Y};$$
(242)

$$A_{o}^{XX} = -2A_{o}^{d}, A_{o}^{XY} = -A_{o}^{t}, A_{o}^{YY} = -2A_{o}^{Y};$$
 (243)

$$A_{o}^{XXX} = -i(A_{o}^{X} + 6A_{o}^{X}); \qquad (244a)$$

$$A_{o}^{XXY} = -2i A_{o}^{tyd}; \qquad (244b)$$

$$A_{o}^{XYY} = -2i A_{o}^{t X^{d}Y}; \qquad (244c)$$

$$A_{o}^{YYY} = -i(A_{o}^{Y} + 6A_{o}^{Y^{Y}}); \qquad (244d)$$

and

$$A_{0}^{XXXX} = 2(A_{0}^{d} + 6A_{0}^{d}); \qquad (245a)$$

$$A_{0}^{XXXY} = A_{0}^{t}X^{t}Y; \qquad (245b)$$

$$A_{O}^{XXYY} = 4A_{O}^{X}$$
(245c)

$$A_{o}^{xyyy} = A_{o}^{t}; \qquad (245d)$$

$$A_{o}^{YYYY} = 2 \left( A_{o}^{Y} + 6 A_{o}^{Y} \right).$$
(245e)

It is worth noticing that Eqs. (241)-(244) are valid for schemes of higher degree in the operators  $t_x, t_y, d_x$ , and  $d_y$ , as long as A  $t_x t_x$ = A y y = 0, i.e., as long as composite transport is excluded. With the above equations, Eqs. (231)-(233) yield

$$(\log A)_{o}^{\mathbf{x}} = iA_{o}^{\mathbf{x}}, \quad (\log A)_{o}^{\mathbf{y}} = iA_{o}^{\mathbf{y}}; \qquad (246)$$

$$(\log A)_{0}^{XX} = -2A_{0}^{d} + (A_{0}^{X})^{2};$$
 (247a)

$$(\log A)_{o}^{XY} = -A_{o}^{t} + A_{o}^{XY} + A_{o}^{XY}, \qquad (247b)$$

$$(\log A)_{O}^{YY} = -2A_{O}^{O}Y + (A_{O}^{Y})^{2};$$
 (247c)

$$(\log A)_{O}^{XXX} = -iA_{O}^{X}(1 - 6A_{O}^{X}) - i[6A_{O}^{X} + 2(A_{O}^{X})^{3}]; \qquad (248a)$$

$$(\log A)_{0}^{XXY} = -2i(A_{0}^{XY} - A_{0}^{X}A_{0}^{Y} + 2iA_{0}^{X}(A_{0}^{Y} - A_{0}^{X}A_{0}^{Y}); \qquad (248b)$$

$$(\log A)_{O} = -2i(A_{O}^{YX} - A_{O}^{Y}A_{O}^{X}) + 2iA_{O}^{Y}(A_{O}^{XY} - A_{O}^{X}A_{O}^{Y}); \qquad (248:)$$

$$(\log A)_{o}^{YYY} = -iA_{o}^{Y}(1 - 6A_{o}^{Y}) - i[6A_{o}^{Y}Y + 2(A_{o}^{Y})^{3}].$$
(248d)

Only the odd derivatives are imaginary. Therefore, Eq. (229) implies

$$\theta = \left[\frac{(\log A)_{0}^{X}}{i} \beta_{X} + \frac{(\log A)_{0}^{Y}}{i} \beta_{Y}\right] + \left[\frac{(\log A)_{0}^{XXX}}{i} \frac{\beta_{X}^{3}}{6} + \frac{(\log A)_{0}^{XXY}}{i} \frac{\beta_{X}^{2} \beta_{Y}}{2} + \frac{(\log A)_{0}^{XYY}}{i} \frac{\beta_{X} \beta_{Y}^{2}}{2} + \frac{(\log A)_{0}^{YYY} \beta_{1}^{3}}{i} \frac{\beta_{X}^{3}}{6} + \dots \right]$$

## Example:

Let us analyze the phase error associated with Eq. (226e),

$$A = (1 - \varepsilon_{\mathbf{x}\mathbf{x}}^{\mathsf{t}} - \varepsilon_{\mathbf{y}\mathbf{y}}^{\mathsf{t}}) + v_{\mathbf{x}\mathbf{x}}^{\mathsf{d}} + v_{\mathbf{y}\mathbf{y}}^{\mathsf{d}} - \mu_{\mathbf{x}\mathbf{x}}^{\mathsf{d}}(1 - \varepsilon_{\mathbf{x}\mathbf{x}}^{\mathsf{t}}) - u_{\mathbf{y}\mathbf{y}}^{\mathsf{d}}(1 - \varepsilon_{\mathbf{y}\mathbf{y}}^{\mathsf{t}}).$$

By direct differentiation we get

$$\begin{array}{l} \begin{array}{l} {}^{t}x_{o} = \varepsilon_{x}, \quad A_{o}^{y} = -\varepsilon_{y}; \\ \\ {}^{d}x_{o} = \upsilon_{x} - \mu_{x}, \quad A_{o}^{y} = \upsilon_{y} - \mu_{y}; \\ \\ {}^{t}x_{o}^{x} = 0, \quad A_{o}^{t}x_{o}^{x} = \varepsilon_{x}\mu_{x}, \quad A_{o}^{d}x_{o}^{x} = 0; \\ \\ {}^{t}y_{o}^{y} = 0, \quad A_{o}^{t}y_{o}^{y} = \varepsilon_{y}\mu_{y}, \quad A_{o}^{d}y_{o}^{y} = 0; \\ \\ \\ {}^{t}x_{o}^{x} = 0, \quad A_{o}^{t}x_{o}^{y} = 0, \quad A_{o}^{t}y_{o}^{y} = 0, \quad A_{o}^{d}x_{o}^{y} = 0; \end{array}$$

$$\begin{array}{c} (250) \\ \end{array}$$

whence

$$\frac{(\log A)_{o}^{X}}{i} = -\varepsilon_{X}, \quad \frac{(\log A)_{o}^{Y}}{i} = -\varepsilon_{Y}; \quad (251)$$

$$\frac{(\log A)_{o}^{XXX}}{i} = 6\varepsilon_{x}\left(\frac{1}{6} - v_{x} + \frac{\varepsilon_{x}^{2}}{3}\right)$$
(252a)

$$\frac{(\log A)_{o}^{XXY}}{i} = -2\varepsilon_{y}(v_{x} - \mu_{x} - \varepsilon_{x}^{2}); \qquad (252b)$$

$$\frac{(\log A)_{o}^{xxy}}{i} = -2\varepsilon_{x}(v_{y} - \mu_{y} - \varepsilon_{y}^{2}); \qquad (252c)$$

$$\frac{(\log A)_{o}^{YYY}}{i} = 6\epsilon_{y}\left(\frac{1}{6} - \nu_{y} + \frac{\epsilon_{y}^{2}}{3}\right).$$
(252d)

Substituting in Eq. (249), we get

$$\theta = -\epsilon_{\mathbf{x}}\beta_{\mathbf{x}} \left[1 + (\nu_{\mathbf{x}} - \frac{1}{6} - \frac{\epsilon_{\mathbf{x}}^{2}}{3})\beta_{\mathbf{x}}^{2} + (\nu_{\mathbf{y}} - \mu_{\mathbf{y}} - \epsilon_{\mathbf{y}}^{2})\beta_{\mathbf{y}}^{2} + \dots\right] -\epsilon_{\mathbf{y}}\beta_{\mathbf{y}}\left[1 + (\nu_{\mathbf{y}} - \frac{1}{6} - \frac{\epsilon_{\mathbf{y}}^{2}}{3})\beta_{\mathbf{y}}^{2} + (\nu_{\mathbf{x}} - \mu_{\mathbf{x}} - \epsilon_{\mathbf{x}}^{2})\beta_{\mathbf{x}} + \dots\right].$$

Noting that  $\varepsilon_x \beta_x = (\frac{u_1 \delta t}{\delta x})(k_1 \delta x) = u_1 k_1 \delta t$  and  $\varepsilon_y \beta_y = u_2 k_2 \delta t$ , we can rewrite the above equation as

where 
$$\vec{k} = (k_1, k_2)$$
,  $\vec{v} = (v_1, v_2)$ . If  $\vec{U} = (u_1, u_2)$ ,  
 $v_1 = u_1 [1 + (v_x - \frac{1}{6} - \frac{\varepsilon_x^2}{3}) \beta_x^2 + (v_y - \mu_y - \varepsilon_y^2) \beta_y^2 + ...];$ 

and

$$v_2 = u_2 [1 + (v_y - \frac{1}{6} - \frac{\varepsilon_y^2}{3})\beta_y^2 + (v_x - \mu_x - \varepsilon_x^2)\beta_x^2 + \dots].$$
 (254b)

Ccomparing Eq. (253) to the analytical solution, we find

$$\theta_{\text{analytic}} = -\vec{k} \cdot \vec{v}_{\delta t}$$
(255)

as is obvious from Eqs. (211).

such that

$$\vec{V} = \vec{U} + R\vec{U}, \qquad (256)$$

where R, given by Eqs. (254), in this scheme is

$$R = \begin{pmatrix} (v_{x} - \frac{1}{6} - \varepsilon_{x}^{2}/3)\beta_{x}^{2} + (v_{y} - \mu_{y} - \varepsilon_{y}^{2})\beta_{y}^{2} \dots \\ 0 & (v_{y} - \frac{1}{6} - \varepsilon_{y}^{2}/3)\beta_{y}^{2}(v_{x} - \mu_{x} - \varepsilon_{x}^{2})\beta_{x}^{2} + \dots \end{pmatrix},$$
(257)

Thus we can reduce the phase error to fourth order by selecting

$$v_{X} = \frac{1}{6} + \varepsilon_{X}^{2}/3; \qquad (258a)$$

$$\begin{array}{c}
\nu - \mu = \varepsilon^2 \\
\mathbf{x} & \mathbf{y} & \mathbf{y} \\
\mathbf{y} & \mathbf{y} & \mathbf{y}
\end{array}$$
(258b)

Solving Eqs. (258a, b), we get

$$\mu_{x} = \frac{1}{6} - \frac{2}{3} \epsilon_{x}^{2} .$$
(258c)

# AMPLITUDE ANALYSIS

(

Following the analysis of the one-dimensional case, since  $|A|^2 = A\overline{A}$  we have

$$(|\mathbf{A}|^{2})_{0} = 1;$$

$$(|\mathbf{A}|^{2})_{0}^{\mathbf{x}} = \mathbf{A}_{0}^{\mathbf{x}}\overline{\mathbf{A}_{0}} + \mathbf{A}_{0}^{\mathbf{x}}\overline{\mathbf{A}_{0}^{\mathbf{x}}}$$

$$(|\mathbf{A}|^{2})_{0}^{\mathbf{y}} = \mathbf{A}_{0}^{\mathbf{y}}\overline{\mathbf{A}_{0}} + \mathbf{A}_{0}^{\mathbf{x}}\overline{\mathbf{A}_{0}^{\mathbf{y}}},$$
(259)

and so on. Noticing from Eqs. (241)-(245) that odd derivatives are purely imaginary while even ones are real, we get after substituting in Eqs. (259)

$$(|\mathbf{A}|^2)_0 = 1;$$
 (260)

$$(|\mathbf{A}|^2)_{o}^{\mathbf{X}\mathbf{X}} = 2[\mathbf{A}_{o}^{\mathbf{X}\mathbf{X}} + (\frac{\mathbf{A}_{o}^{\mathbf{X}}}{\mathbf{i}})^2];$$
 (261a)

$$(|A|^2)_{o}^{xy} = 2[A_{o}^{xy} + \frac{A_{o}^{x}}{i} \frac{A_{o}^{y}}{i}];$$
 (261b)

$$(|A|^2)_{o}^{YY} = 2[A_{o}^{YY} + (\frac{A_{o}^{Y}}{i})^2];$$
 (261c)

$$(|A|^2)_{o}^{XXXX} = 2[A_{o}^{XXXX} + 4(\frac{o}{i})(\frac{A^{XX}}{i}) + 3(A_{o}^{XX})^2];$$
 (262a)

$$(|\mathbf{A}|^2)_{o}^{\mathbf{XXXY}} = 2(\mathbf{A}_{o}^{\mathbf{XXXY}} + (\frac{\mathbf{A}_{o}}{\mathbf{i}})(\frac{\mathbf{A}_{o}}{\mathbf{i}}) + 3(\frac{\mathbf{A}_{o}}{\mathbf{i}})(\frac{\mathbf{A}_{o}}{\mathbf{i}}) + (3\mathbf{A}_{o}^{\mathbf{XX}}\mathbf{A}_{o}^{\mathbf{XY}}); \qquad (262b)$$

$$|A|^{2} \sum_{0}^{xxyy} = 2 [A_{0}^{xxyy} + (\frac{A_{0}^{xyy}}{i})(\frac{A_{0}^{y}}{i}) + A_{0}^{xx}A_{0}^{yy} + 2(\frac{A_{0}^{xyy}}{i})(\frac{A_{0}^{x}}{i}) + 2(A_{0}^{xy})^{2}]; \qquad (262c)$$

$$(|\mathbf{A}|^{2})_{o}^{\mathbf{x}\mathbf{y}\mathbf{y}\mathbf{y}} = 2[\mathbf{A}_{o}^{\mathbf{x}\mathbf{y}\mathbf{y}\mathbf{y}} + (\frac{\mathbf{A}_{o}^{\mathbf{x}}}{\mathbf{i}})(\frac{\mathbf{A}_{o}^{\mathbf{y}\mathbf{y}\mathbf{y}}}{\mathbf{i}}) + 3(\frac{\mathbf{A}_{o}^{\mathbf{x}\mathbf{y}\mathbf{y}}}{\mathbf{i}})(\frac{\mathbf{A}_{o}^{\mathbf{y}\mathbf{y}}}{\mathbf{i}}) + 3\mathbf{A}_{o}^{\mathbf{x}\mathbf{y}\mathbf{x}}\mathbf{A}_{o}^{\mathbf{y}\mathbf{y}}];$$
(262d)

.

$$(|A|^{2})_{o}^{yyyy} = 2[A_{o}^{yyyy} + 4(\frac{A_{o}^{y}}{i})(\frac{A_{o}^{yyy}}{i}) + 3(A_{o}^{yy})^{2}], \qquad (262e)$$

while the odd derivative vanishes. Consequently, the expansion of  $\left|A\right|^{2}$  takes the form

$$|\mathbf{A}|^{2} = (|\mathbf{A}|^{2})_{0} + [(|\mathbf{A}|^{2})_{0}^{\mathbf{X}\mathbf{X}} \frac{\beta_{\mathbf{X}}^{2}}{2} + (|\mathbf{A}|^{2})_{0}^{\mathbf{X}\mathbf{Y}} \beta_{\mathbf{X}}\beta_{\mathbf{Y}} + (|\mathbf{A}|^{2})_{0}^{\mathbf{Y}\mathbf{Y}} \frac{\beta_{\mathbf{Y}}^{2}}{2}] + [|\mathbf{A}|^{2})_{0}^{\mathbf{X}\mathbf{X}\mathbf{X}\mathbf{X}} \frac{\beta_{\mathbf{X}}^{4}}{24} + (|\mathbf{A}|^{2})_{0}^{\mathbf{X}\mathbf{X}\mathbf{Y}} \frac{\beta_{\mathbf{X}}^{3}\beta_{\mathbf{Y}}}{6} + (|\mathbf{A}|^{2})_{0}^{\mathbf{X}\mathbf{X}\mathbf{Y}\mathbf{Y}} \frac{\beta_{\mathbf{X}}^{2}\beta_{\mathbf{Y}}^{2}}{4} + (|\mathbf{A}|^{2})_{0}^{\mathbf{X}\mathbf{Y}\mathbf{Y}\mathbf{Y}} \frac{\beta_{\mathbf{X}}^{3}\beta_{\mathbf{Y}}^{3}}{6} + (|\mathbf{A}|^{2})_{0}^{\mathbf{Y}\mathbf{Y}\mathbf{Y}} \frac{\beta_{\mathbf{Y}}^{4}}{24} + \dots$$
(263)

Example:

Using Eqs. (250), Eqs. (241)-(243) yield

$$A_{o} = 1;$$

$$\frac{A_{o}^{x}}{i} = -\varepsilon_{x}, \quad \frac{A_{o}^{y}}{i} = -\varepsilon_{y};$$

$$A_{o}^{xx} = -2(v_{x} - \mu_{x}) = -2\varepsilon_{x}^{2};$$

$$A_{o}^{xy} = 0;$$

$$A_{o}^{yy} = -2(v_{y} - \mu_{y}) = -2\varepsilon_{y}^{2},$$

which when substituted into Eqs. (260), (261) give

$$(|\mathbf{A}|^2)_0 = 1;$$
  
 $(|\mathbf{A}|^2)_0^{\mathbf{X}\mathbf{X}} = -2\varepsilon_{\mathbf{X}}^2;$ 

$$(|\mathbf{A}|^{2})_{o}^{\mathbf{X}\mathbf{y}} = 2\varepsilon_{\mathbf{x}}\varepsilon_{\mathbf{y}};$$
$$(|\mathbf{A}|^{2})_{o}^{\mathbf{Y}\mathbf{y}} = -2\varepsilon_{\mathbf{y}}^{2}.$$

Equation (263) then expresses the amplitude expansion as

$$|\mathbf{A}|^{2} = 1 - (\varepsilon_{\mathbf{x}}^{2}\beta_{\mathbf{x}}^{2} - 2\varepsilon_{\mathbf{x}}\varepsilon_{\mathbf{y}}\beta_{\mathbf{x}}\beta_{\mathbf{y}} + \varepsilon_{\mathbf{y}}^{2}\beta_{\mathbf{y}}^{2}) + \dots$$

$$|\mathbf{A}|^{2} = 1 = -|\varepsilon_{\mathbf{x}}\beta_{\mathbf{x}} - \varepsilon_{\mathbf{y}}\beta_{\mathbf{y}}|^{2} + \dots, \qquad (264)$$

showing that the diffusion of the scheme is second-order.

#### POSITIVITY

From Eqs. (223) and using Eq. (258a),

$$\rho_{i,j}^{\text{TD}} = \rho_{i,j}^{n} [1 - 2(\frac{1}{6} + \frac{\varepsilon_x^2}{3}) - 2(\frac{1}{6} + \frac{\varepsilon_y^2}{3})] + \rho_{i+1,j}^{n} [(\frac{1}{6} + \frac{\varepsilon_x^2}{3}) - \frac{\varepsilon_x}{2}] + \rho_{i-1,j}^{n} [\frac{1}{6} + \frac{\varepsilon_x^2}{3}) + \frac{\varepsilon_x}{2}] + \rho_{i,j+1}^{n} [(\frac{1}{6} + \frac{\varepsilon_y^2}{3}) - \frac{\varepsilon_y}{2}] + \rho_{i,j-1}^{n} [(\frac{1}{6} + \frac{\varepsilon_y^2}{3}) + \frac{\varepsilon_y}{2}]$$

Each of the square brackets is  $\geq 0$  for  $|\varepsilon_x|, |\varepsilon_y| \leq \frac{1}{2}$ . Consequently,  $\rho_{i,j}^{\text{TD}} \geq 0$  if all  $\rho_{i,j}^n \geq 0$ . Now we get

$$\rho_{i,j}^{n+1} = \rho_{i,j}^{TD} - \mu_{x}(\rho_{i+1,j}^{T} - 2\rho_{i,j}^{T} + \rho_{i-1,j}^{T}) * - \mu_{y}(\rho_{i,j+1}^{T} - 2\rho_{i,j}^{T} + \rho_{i,j-1}^{T}) *$$

The asterisks denote the fact that the antidiffusion fluxes are trimmed enough such that  $\rho_{i,j}^{n+1}$  is limited by the sign of  $\rho_{i,j}^{TD}$ . Then  $\rho_{i,j}^{n+1} \ge 0$ .

STABILITY

Equation (264) proves the stability of the scheme near  $\beta_x = \beta_y = 0$ . For the scheme to be completely stable, however, we must have  $|A| \leq 1$  for  $0 \leq \beta_x, \beta_y \leq \pi$ . Let us check A, at the largest values admitted for  $\varepsilon_x, \varepsilon_y$ , namely 1/2.

From Eq. (226e)

$$A_{R} = 1 - 2(v_{x} - \mu_{x})(1 - \cos \beta_{x}) - 2(v_{y} - \mu_{y})(1 - \cos \beta_{y}); \qquad (266a)$$
$$A_{I} = -\varepsilon_{x} \sin \beta_{x} [1 + 2\mu_{x}(1 - \cos \beta_{x})]$$
$$-\varepsilon_{y} \sin \beta_{y} [1 + 2\mu_{y}(1 - \cos \beta_{y})] \qquad (266b)$$

Substituting for  $\nu = \mu$  from Eq. (258b), and  $\mu$  from Eq. (258c), we get  $\begin{array}{c} x \\ y \\ y \end{array}$ 

$$A_{R} = 1 - 2\varepsilon_{x}^{2}(1 - \cos \beta_{x}) - 2\varepsilon_{y}^{2}(1 - \cos \beta_{y}); \qquad (267a)$$
$$A_{I} = -\varepsilon_{x} \sin \beta_{x} \left[1 + \frac{1}{4}(1 - 4\varepsilon_{x}^{2})(1 - \cos \beta_{x})\right]$$

$$- \epsilon_{y} \sin \beta_{y} \left[ 1 + \frac{1}{4} (1 - 4\epsilon_{y}^{2}) (1 - \cos \beta_{y}) \right].$$
 (267b)

At  $\varepsilon_x$ ,  $\varepsilon_y = 1/2$ ,  $\mu_x = \mu_y = 0$ ; Eqs. (267) reduce to

$$\begin{split} \mathbf{A}_{\mathbf{R}} &= 1 - \frac{1}{2}(1 - \cos \beta_{\mathbf{x}}) - \frac{1}{2}(1 - \cos \beta_{\mathbf{y}}); \\ \mathbf{A}_{\mathbf{I}} &= -\frac{1}{2}(\sin \beta_{\mathbf{x}} + \sin \beta_{\mathbf{y}}). \end{split}$$

Noticing that  $1 - \cos \beta = 2 \sin^2(\beta/2)$  and  $\sin \beta = 2 \sin(\beta/2) \cos(\beta/2)$ , we get

$$\begin{split} \mathbf{A}_{\mathrm{R}} &= 1 - \sin^{2}(\beta_{\mathrm{x}}/2) \sin^{2}(\beta_{\mathrm{y}}/2); \\ \mathbf{A}_{\mathrm{I}} &= - \left[ \sin (\beta_{\mathrm{x}}/2) \cos (\beta_{\mathrm{x}}/2) + \sin (\beta_{\mathrm{y}}/2) \cos (\beta_{\mathrm{y}}/2) \right], \end{split}$$

yielding

$$\begin{aligned} |\mathbf{A}|^{2} &= \mathbf{A}_{\mathbf{R}}^{2} + \mathbf{A}_{\mathbf{I}}^{2} = 1 + \sin^{4} \frac{\beta_{\mathbf{x}}}{2} + \sin^{4} \frac{\beta_{\mathbf{y}}}{2} + 2\sin^{2} \frac{\beta_{\mathbf{x}}}{2} \sin^{2} \frac{\beta_{\mathbf{y}}}{2} \\ &- 2(\sin^{2} \frac{\beta_{\mathbf{x}}}{2} + \sin^{2} \frac{\beta_{\mathbf{y}}}{2}) + \sin^{2} \frac{\beta_{\mathbf{x}}}{2} \cos^{2} \frac{\beta_{\mathbf{x}}}{2} + \sin^{2} \frac{\beta_{\mathbf{y}}}{2} \cos^{2} \frac{\beta_{\mathbf{y}}}{2} \\ &+ 2\sin \frac{\beta_{\mathbf{x}}}{2} \sin \frac{\beta_{\mathbf{y}}}{2} \cos \frac{\beta_{\mathbf{x}}}{2} \cos \frac{\beta_{\mathbf{y}}}{2} \cos \frac{\beta_{\mathbf{y}}}{2}. \end{aligned}$$

Collecting the terms containing  $\sin^2 \frac{\beta_x}{2}$ , we have

$$-\sin^{2}\frac{\beta_{x}}{2}[(1-\sin^{2}\frac{\beta_{y}}{2}) + (1-\cos^{2}\frac{\beta_{x}}{2})] = -\sin^{2}\frac{\beta_{x}}{2}[\cos^{2}\frac{\beta_{y}}{2} + \sin^{2}\frac{\beta_{x}}{2}] = -\sin^{2}\frac{\beta_{x}}{2}\cos^{2}\frac{\beta_{y}}{2} - \sin^{4}\frac{\beta_{x}}{2}.$$

Similarly  $\sin^2 \frac{\beta_y}{2}$  terms yield -  $\sin^2 \frac{\beta_y}{2} \cos^2 \frac{\beta_x}{2} - \sin^4 \frac{\beta_y}{2}$ , resulting in

$$|\mathbf{A}|^{2} = 1 - (\sin^{2} \frac{\beta_{\mathbf{x}}}{2} \cos^{2} \frac{\beta_{\mathbf{y}}}{2} - 2 \sin \frac{\beta_{\mathbf{x}}}{2} \sin \frac{\beta_{\mathbf{y}}}{2} \cos \frac{\beta_{\mathbf{x}}}{2} \cos \frac{\beta_{\mathbf{y}}}{2} \cos \frac{\gamma_{\mathbf{y}}}{2} + \sin^{2} \frac{\beta_{\mathbf{y}}}{2} \cos^{2} \frac{\beta_{\mathbf{x}}}{2}) = 1 - (\sin \frac{\beta_{\mathbf{x}}}{2} \cos \frac{\beta_{\mathbf{y}}}{2} - \sin \frac{\beta_{\mathbf{y}}}{2} \cos \frac{\beta_{\mathbf{x}}}{2})^{2} = 1 - \sin^{2} (\frac{\beta_{\mathbf{x}}}{2} - \frac{\beta_{\mathbf{y}}}{2}) = \cos^{2} (\frac{\beta_{\mathbf{x}}}{2} - \frac{\beta_{\mathbf{y}}}{2}).$$

Consequently,

$$|\mathbf{A}|_{\varepsilon_{\mathbf{X}}=\varepsilon_{\mathbf{Y}}=\frac{1}{2}} = \cos\left(\frac{\beta_{\mathbf{X}}}{2} - \frac{\beta_{\mathbf{Y}}}{2}\right) \le 1,$$
(268)

showing the scheme to be stable at  $\varepsilon_x$ ,  $\varepsilon_y = \frac{1}{2}$ . The value |A| for smaller values of  $\varepsilon_x$ ,  $\varepsilon_y$  was evaluated numerically and found always to satisfy  $\leq 1$ . Hence the scheme is completely stable.

It is worth noticing the diagonal symmetry of Eqs. (264), (268). In fact, on the  $\beta_x$ ,  $\beta_y$  plane, |A| looks like a wave with front parallel to the  $\beta_x = \beta_y$  diagonal, as illustrated in Fig. 27.

## XIII. RECTANGULAR GRID MOTION

Consider a system of points tagged by the double indices i, j;

$$x_{i,j} = x(i,j,t);$$
 (270a)

$$y_{i,j} = y(i,j,t).$$
 (270b)

Figure 28 illustrates the grid formed by Eq. (270) at a given time t. The pair of numbers at each point indicates (i,j). For a strictly rectangular grid at all times (which includes Langrangian grid motion),

$$x_{i,j} = x(i,t);$$
 (271a)

$$y_{i,j} = y(j,t).$$
 (271b)

which we therefore denote from now on by

$$x_{i} = x(i,t);$$
 (272a)

$$y_{j} = y(j,t)$$
. (272b)

This leads to a mesh as in Fig. 29.

## XIV. GEOMETRICAL ASPECTS

We consider seven geometries. (These by no means cover the whole spectrum of two-dimensional systems.) In cartesian geometry, we have x-y (x-z or y-z); in cylindrical geometry, r-z, r- $\Rightarrow$ , and z- $\Rightarrow$ , and finally in spherical geometry r- $\Rightarrow$ , r- $\Rightarrow$ , and  $\Rightarrow$ - $\Rightarrow$ . Figure 30 illustrates a finite control volume in each of the different cases.

As explained earlier, when the grid moves the control surface area in the integral form of the conservation equations should be an average surface area defined as

$$\int_{s^{\text{mean}}} (\vec{u}^{g} \hat{s} t \cdot \vec{n}) dS = \text{swept volume.}$$

In one-dimensional cases, the above definition reduces to defining  $A_{interface} = \frac{swept \ volume}{u^{2} \delta t}$ . In two dimensions, however, this is not enough. We have to find a path between the old grid and the new one such that we can construct a mean cell having its surfaces equal to the average areas and corners located on the above path.

## 1. Cartesian Coordinates

Figure 31 illustrates the location of cell (i,j) at times t<sup>n</sup> and  $t^{n+1} = t^n + \delta t$ . The left and right interfaces are denoted by (i - 1/2, j), (i,j + 1/2, j), respectively, and the bottom and top ones by (i,j - 1/2), (i,j + 1/2). We notice here that since all i ± 1/2, j interfaces (different j's) move as a whole, the grid velocity is independent of j. It is therefore denoted by  $u_{i\pm\frac{1}{2}}^g$  without a j index. The same is true for  $v_{i\pm\frac{1}{2}}^g$ .

In cartesian geometry, it is obvious that the path needed is a straight line between the new and old corners of the cell, and the mean cell is halfway between the old cell and the new one.

The volume swept by interface (i  $\pm 1/2$ , j) is given by the product (average base) x (height):

$$\Delta \Psi_{i\pm\frac{1}{2},j} = \frac{(y_{j+\frac{1}{2}}^{n} - y_{j-\frac{1}{2}}^{n}) + (y_{j+\frac{1}{2}}^{n+1} - y_{j-\frac{1}{2}}^{n+1})}{2} [x_{i\pm\frac{1}{2}}^{n+1} - x_{i\pm\frac{1}{2}}^{n}]$$
$$= \frac{1}{2} (A_{j}^{n} + A_{j}^{n+1})^{2} (x_{i\pm\frac{1}{2}}^{n+1} - x_{i\pm\frac{1}{2}}^{n}),$$

where we notice again that the i index is omitted from  $A_{j\pm\frac{1}{2},j}$  since all the  $A_{j\pm\frac{1}{2},j}$  interfaces (different i's) are equal. The above equation can be written as

$$\Delta \Psi_{i\pm\frac{1}{2},j} = \left[ \left( \frac{y_{j\pm\frac{1}{2}}^{n} + \frac{n+1}{j+\frac{1}{2}}}{2} \right) - \left( \frac{y_{j-\frac{1}{2}}^{n} + y_{j-\frac{1}{2}}^{n+1}}{2} \right) \right] \left( x_{i\pm\frac{1}{2}}^{n+1} - x_{i\pm\frac{1}{2}}^{n} \right)$$
(286)

showing that the mean area is halfway between old and new. The grid velocity  $u_{i\pm\frac{1}{2}}^{g}$  in this case is considered constant,

$$u_{i\pm\frac{1}{2}}^{g} = \frac{x_{i\pm\frac{1}{2}}^{n+1} - x_{i\pm\frac{1}{2}}^{n}}{\delta t},$$
 (287)

and the mean area is

$$A_{j}^{n+\frac{1}{2}} = y_{j+\frac{1}{2}}^{n+\frac{1}{2}} - y_{j-\frac{1}{2}}^{n+\frac{1}{2}} = \frac{A_{j}^{n} + A_{j}^{n+1}}{2}, \qquad (288a)$$

where

$$y_{j\pm\frac{1}{2}}^{n+\frac{1}{2}} = \frac{1}{2}(y_{j\pm\frac{1}{2}}^{n} + y_{j\pm\frac{1}{2}}^{n+1}).$$
(288b)

Similarly,

$$A_{i}^{n+\frac{1}{2}} = x_{i+\frac{1}{2}}^{n+\frac{1}{2}} - x_{i-\frac{1}{2}}^{n+\frac{1}{2}} = \frac{A_{i}^{n} + A_{i}^{n+1}}{2}, \qquad (289a)$$

where

$$\mathbf{x}_{\underline{i}\pm\underline{1}}^{n+\underline{1}} = \frac{1}{2}(\mathbf{x}_{\underline{i}\pm\underline{1}}^{n} + \mathbf{x}_{\underline{i}\pm\underline{1}}^{n+1}).$$
(289b)

The mean cell colume is

$$\Psi_{i,j}^{n+\frac{1}{2}} = (y_{j+\frac{1}{2}}^{n+\frac{1}{2}} - y_{j-\frac{1}{2}}^{n+\frac{1}{2}}) (x_{i+\frac{1}{2}}^{n+\frac{1}{2}} - x_{i-\frac{1}{2}}^{n+\frac{1}{2}}).$$
(290)

### 2. Cylindrical (r-z) Coordinates

Let us derive the required path between the corners of old and new cells such that the corners of the mean cell fall on that path. Figure 32 illustrates the old and new cells. Figure 33 shows the volume swept by interfact (i,j  $\pm 1/2$ ):

$$\forall_{i,j\pm\frac{1}{2}} = \int_{\substack{z_{j\pm\frac{1}{2}}^{n} \\ z_{j\pm\frac{1}{2}}^{n} \\$$

where it is obvious that a linear average can be obtained if  $r_{i\pm\frac{1}{2}}^2$  is assumed to be linear in  $z_{i\pm\frac{1}{2}}$ . Let

$$\frac{(r_{i\pm\frac{1}{2}})^{2} - (r_{i\pm\frac{1}{2}}^{n})^{2}}{(r_{i\pm\frac{1}{2}}^{n+1})^{2} - (r_{i\pm\frac{1}{2}}^{n})^{2}} = \frac{z_{j\pm\frac{1}{2}} - z_{j\pm\frac{1}{2}}^{n}}{z_{j\pm\frac{1}{2}}^{n+1} - z_{j\pm\frac{1}{2}}^{n}},$$
(292a)

i.e., a parabolic path. The above formula can be written concisely as

$$\frac{\Delta r_{\underline{i} \pm \underline{j}}^{2}}{\Delta R_{\underline{i} \pm \underline{j}}^{2}} = \frac{\Delta z_{\underline{j} \pm \underline{j}}}{\Delta z_{\underline{j} \pm \underline{j}}}, \qquad (292b)$$

yielding

$$r_{i\pm\frac{1}{2}}^{2} = (r_{i\pm\frac{1}{2}}^{n})^{2} + \frac{\Delta z_{j\pm\frac{1}{2}}}{\Delta z_{j\pm\frac{1}{2}}} \Delta R_{i\pm\frac{1}{2}}^{2}.$$
 (292c)

Substituting (292c) into (291), we get

$$\Delta \Psi_{i,j\pm\frac{1}{2}} = \pi \Delta Z_{j\pm\frac{1}{2}} \int_{0}^{1} (r_{i+\frac{1}{2}}^{2} - r_{i-\frac{1}{2}}^{2}) d(\frac{\Delta Z_{j\pm\frac{1}{2}}}{\Delta Z_{j\pm\frac{1}{2}}})$$
$$= \pi \Delta Z_{j\pm\frac{1}{2}} [\frac{(r_{i+\frac{1}{2}}^{n} + (r_{i+\frac{1}{2}}^{n+1})^{2}}{2} + \frac{(r_{i-\frac{1}{2}}^{n})^{2} + (r_{i-\frac{1}{2}}^{n+1})^{2}}{2}],$$

yielding a mean area

$$A_{i}^{n+\frac{1}{2}} = \frac{\Delta \Psi_{i,j\pm\frac{1}{2}}}{\Delta Z_{j\pm\frac{1}{2}}} = \pi[(r_{i+\frac{1}{2}}^{n+\frac{1}{2}})^{2} - (r_{i-\frac{1}{2}}^{n+\frac{1}{2}})^{2}] = \frac{A_{i}^{n} + A_{i}^{n+1}}{2}, \qquad (293a)$$

where

$$r_{\underline{i\pm\frac{1}{2}}}^{n+\frac{1}{2}} = \left(\frac{(r_{\underline{i\pm\frac{1}{2}}}^{n})^{2} + (r_{\underline{i\pm\frac{1}{2}}}^{n})^{2}}{2}\right)^{\frac{1}{2}}$$
(293b)

This shows the advantage of the parabolic path (292a), namely

$$\frac{\Delta z_{j\pm\frac{1}{2}}}{\Delta z_{j\pm\frac{1}{2}}} = \frac{\Delta r_{i\pm\frac{1}{2}}^2}{\Delta R_{i\pm\frac{1}{2}}^2} = 1/2, \qquad (293c)$$

i.e., the average area  $\mathtt{A}_{\underline{i}}^{n+\frac{1}{2}}$  is halfway along z between the old and new ones, at

$$z_{j\pm\frac{1}{2}}^{n+\frac{1}{2}} = \frac{z_{j\pm\frac{1}{2}}^{n} + z_{j\pm\frac{1}{2}}^{n+1}}{2} .$$
(293d)

Following the nomenclature of Fig. 34, the volume swept by the interface  $i\pm\frac{1}{2}$ , j is

But

$$z_{j\pm\frac{1}{2}} = z_{j\pm\frac{1}{2}}^{n} + \Delta z_{j\pm\frac{1}{2}}, \qquad (295)$$

yielding

$$\Delta \mathbf{w}_{i\pm\frac{1}{2},j} = \int_{\substack{r_{i\pm\frac{1}{2}} \\ r_{i\pm\frac{1}{2}} \\ i\pm\frac{1}{2}}}^{r_{i\pm\frac{1}{2}}^{n+1}} \pi_{i} (z_{j+\frac{1}{2}}^{n} - z_{j-\frac{1}{2}}^{n}) + (\frac{\Delta z_{j+\frac{1}{2}}}{\Delta Z_{j+\frac{1}{2}}} \Delta Z_{j+\frac{1}{2}} - \frac{\Delta z_{j-\frac{1}{2}}}{\Delta Z_{j-\frac{1}{2}}} \Delta Z_{j-\frac{1}{2}}) ] dr_{i\pm\frac{1}{2}}^{2}$$

which, with (292b) gives

$$\Delta \Psi_{i\pm\frac{1}{2},j} = \pi \Delta R_{i\pm\frac{1}{2}}^{2} \int_{0}^{1} [(z_{j+\frac{1}{2}}^{n} - z_{j-\frac{1}{2}}^{n})]_{0}^{\Delta r_{j+\frac{1}{2}}^{2}} + \frac{\Delta r_{i+\frac{1}{2}}^{2}}{\Delta R_{i+\frac{1}{2}}^{2}} (\Delta Z_{j+\frac{1}{2}} - \Delta Z_{j-\frac{1}{2}})]_{\Delta R_{i\pm\frac{1}{2}}^{2}}^{\Delta r_{i\pm\frac{1}{2}}^{2}} = \pi \Delta R_{i\pm\frac{1}{2}}^{2} [z_{j+\frac{1}{2}}^{n+\frac{1}{2}} + z_{j-\frac{1}{2}}^{n+\frac{1}{2}}].$$
(296)

Now to be able to construct a rectangular mean cell with its four corners on the parabolic paths of Eq. (292a), the quantities  $A_{i\pm\frac{1}{2},j}^{n+\frac{1}{2}}$  have to be also half way between old and new, i.e.,

$$A_{j\pm\frac{1}{2},j}^{n+\frac{1}{2}} = 2\pi r_{j\pm\frac{1}{2}}^{n+\frac{1}{2}} \left[ z_{j+\frac{1}{2}}^{n+\frac{1}{2}} - z_{j-\frac{1}{2}}^{n+\frac{1}{2}} \right],$$
(297)

where we notice that the interface area is dependent on both i,j, in contrast to the cartesian case. With Eq. (296), Eq. (297) yields

$$A_{i\pm\frac{1}{2},j}^{n+\frac{1}{2}} = \frac{\Delta \Psi_{i\pm\frac{1}{2}}}{\Delta R_{i\pm\frac{1}{2}}^{2}/2r_{i\pm\frac{1}{2}}^{n+\frac{1}{2}}}$$
(298)

whence, if  $u_{i\pm\frac{1}{2}}^{g}$  denotes the average velocity of the grid during t,

$$u_{i\pm\frac{1}{2}}^{g}\delta t = \frac{\left(r_{i\pm\frac{1}{2}}^{n+1}\right)^{2} - \left(r_{i\pm\frac{1}{2}}^{n}\right)^{2}}{2r_{i\pm\frac{1}{2}}^{n+\frac{1}{2}}}$$
(299)

where, as is clear from Eq. (293a), it was assumed that

$$v_{j\pm\frac{1}{2}}^{g}\delta t = \Delta z_{j\pm\frac{1}{2}} = z_{j\pm\frac{1}{2}}^{n+1} - z_{j\pm\frac{1}{2}}^{n}$$
 (300)

The difference between the form of (299) and that of (300) is attributed to the parabolic path of the corner. If the grid velocity  $v_{j\pm\frac{1}{2}}^{g}$  is a constant during  $\delta t$ , we evaluate  $u_{i\pm\frac{1}{2}}^{g}$  at  $t^{n+\frac{1}{2}} = t^{n} + \frac{\delta t}{2}$  from (292c)

$$2r_{\underline{i\pm\frac{1}{2}}}\frac{dr_{\underline{i\pm\frac{1}{2}}}}{dt} = \frac{\Delta R_{\underline{i\pm\frac{1}{2}}}^2}{\Delta Z_{\underline{j\pm\frac{1}{2}}}}\frac{d\Delta z_{\underline{j\pm\frac{1}{2}}}}{dt} = \frac{\Delta R_{\underline{i\pm\frac{1}{2}}}^2}{\Delta Z_{\underline{j\pm\frac{1}{2}}}}\frac{dz_{\underline{j\pm\frac{1}{2}}}}{dt},$$

whence

$$u_{i\pm\frac{1}{2}}^{g} = \frac{\Delta R_{i\pm1}^{2}}{2r_{i\pm\frac{1}{2}}} \frac{v_{j\pm\frac{1}{2}}^{g}}{\Delta Z_{j\pm\frac{1}{2}}} = \frac{\Delta R_{i\pm\frac{1}{2}}^{2}}{2r_{i\pm\frac{1}{2}}\delta t} , \qquad (301)$$

using Eq. (300). Since  $v_{j\pm\frac{1}{2}}^g = \text{const.}$ ,  $(\Delta z_{j\pm\frac{1}{2}}/\Delta Z_{j\pm\frac{1}{2}})_{t+\frac{\delta t}{2}} = 1/2$ . Consequently, from (292c)

$$\mathbf{r}_{i\pm\frac{1}{2}}^{2}\Big|_{t+\frac{\delta t}{2}} = \frac{1}{2}[(\mathbf{r}_{i\pm\frac{1}{2}}^{n})^{2} + (\mathbf{r}_{i\pm\frac{1}{2}}^{n+1})^{2}] = (\mathbf{r}_{i\pm\frac{1}{2}}^{n+\frac{1}{2}})^{2},$$

thus reproducing Eq. (299) when substituted in Eq. (301). A more general definition of the average interface is therefore

mean  
interface  
area
$$= \frac{\text{swept volume}}{(\text{velocity of interface at } t^n + \frac{\delta t}{2}).\delta t}$$
(302)

where the denominator is approximately but not quite exactly equal to the distance the interface is shifted. Finally, the mean cell volume is

$$\Psi_{i,j}^{n+\frac{1}{2}} = \pi \left[ \left( r_{i+\frac{1}{2}}^{n+\frac{1}{2}} \right)^2 - \left( r_{i+\frac{1}{2}}^{n+\frac{1}{2}} \right)^2 \right] \left[ z_{j+\frac{1}{2}}^{n+\frac{1}{2}} - z_{j-\frac{1}{2}}^{n+\frac{1}{2}} \right],$$
(303)

# 3. Spherical $r \rightarrow 0$ Coordinates

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Figure 35 illustrates cell i,j at t<sup>n</sup> and t<sup>n+1</sup>. Consider Fig. 36 showing the motion of interface i,j $\pm \frac{1}{2}$ . The volume swept by interface i,j $\pm \frac{1}{2}$  is

$$\Delta \Psi_{i,j\pm\frac{1}{2}} = \int_{\theta_{j\pm\frac{1}{2}}}^{\theta_{j\pm\frac{1}{2}}} \frac{2\pi}{3} (r_{i+\frac{1}{2}}^3 - r_{i-\frac{1}{2}}^3) \sin \theta_{j\pm\frac{1}{2}} d\theta_{j\pm\frac{1}{2}}$$
$$= \int_{\theta_{j\pm\frac{1}{2}}}^{\theta_{j\pm\frac{1}{2}}^{n+1}} \frac{2\pi}{3} (r_{i+\frac{1}{2}}^3 - r_{i-\frac{1}{2}}^3) d(-\cos \theta_{j\pm\frac{1}{2}}), \qquad (304)$$

showing that we can get a linear average if  $r_{i\pm\frac{1}{2}}^3$  is assumed to be a linear function of  $(-\cos\theta_{j\pm\frac{1}{2}})$ . Let

$$\frac{(r_{i\pm\frac{1}{2}})^{3} - (r_{i\pm\frac{1}{2}}^{n})^{3}}{(r_{i\pm\frac{1}{2}}^{n+1})^{3} - (r_{i\pm\frac{1}{2}}^{n})^{3}} = \frac{\cos \theta_{j\pm\frac{1}{2}}^{n} - \cos \theta_{j\pm\frac{1}{2}}}{\cos \theta_{j\pm\frac{1}{2}}^{n} - \cos \theta_{j\pm\frac{1}{2}}^{n+1}},$$
(305a)

or in a more concise form,

$$\frac{\Delta r_{i \pm \frac{1}{2}}^{3}}{\Delta R_{i \pm \frac{1}{2}}^{3}} = \frac{\Delta \left(-\cos \theta_{j \pm \frac{1}{2}}\right)}{\Delta \left(-\cos \theta_{j \pm \frac{1}{2}}\right)} . \tag{305b}$$

This yields

$$r_{i\pm\frac{1}{2}}^{3} = (r_{i\pm\frac{1}{2}}^{n})^{3} + \frac{\Delta(-\cos\theta_{j\pm\frac{1}{2}})}{\Delta(-\cos\theta_{j\pm\frac{1}{2}})} \Delta R_{i\pm\frac{1}{2}}^{3}.$$
 (305c)

Substituting into Eq. (304) we get

$$\Delta \Psi_{i,j\pm\frac{1}{2}} = \frac{2\pi}{3} \Delta (-\cos \theta_{j\pm\frac{1}{2}}) \int_{0}^{1} [(r_{i+\frac{1}{2}}^{n3} - r_{i-\frac{1}{2}}^{n3}) + \frac{\Delta (-\cos \theta_{j\pm\frac{1}{2}})}{\Delta (-\cos \theta_{j\pm\frac{1}{2}})} (\Delta R_{i+\frac{1}{2}}^{3} - \Delta R_{i-\frac{1}{2}}^{3})] d \frac{\Delta (-\cos \theta_{j\pm\frac{1}{2}})}{\Delta (-\cos \theta_{j\pm\frac{1}{2}})} = \frac{2\pi}{3} (\cos \theta_{j\pm\frac{1}{2}}^{n} - \cos \theta_{j\pm\frac{1}{2}}^{n+1}) [\frac{(r_{i+\frac{1}{2}}^{n})^{3} + (r_{i+\frac{1}{2}}^{n+1})^{3}}{2} - \frac{(r_{i-\frac{1}{2}}^{n})^{3} + (r_{i-\frac{1}{2}}^{n+1})^{3}}{2}].$$
(306)

We notice that the mean interface  $i, j \pm \frac{1}{2}$  is halfway on a cosine scale between  $\theta_{j\pm\frac{1}{2}}^{n}, \theta_{j\pm\frac{1}{2}}^{n+1}$  or on a cubic scale between  $r_{i\pm\frac{1}{2}}^{n}, r_{i\pm\frac{1}{2}}^{n+1}$ . As for interface  $(i\pm\frac{1}{2},j)$ , it sweeps a volume (see Fig. 37),

$$\Delta \Psi_{i\pm\frac{1}{2},j} = \int_{r_{i\pm\frac{1}{2}}}^{r_{i\pm\frac{1}{2}}^{n+1}} 2\pi r_{i\pm\frac{1}{2}}^{2} (\cos \theta_{j-\frac{1}{2}} - \cos \theta_{j+\frac{1}{2}}) dr_{i\pm\frac{1}{2}}$$

$$= \int_{r_{i\pm\frac{1}{2}}}^{r_{i\pm\frac{1}{2}}^{n+1}} \frac{2\pi}{3} (\cos \theta_{j-\frac{1}{2}} - \cos \theta_{j+\frac{1}{2}}) dr_{i\pm\frac{1}{2}}^{3}. \qquad (307)$$

But 
$$\cos \theta_{j\pm\frac{1}{2}} = \cos \theta_{j\pm\frac{1}{2}}^{n} + \Delta(-\cos \theta_{j\pm\frac{1}{2}})$$
, yielding  

$$\Delta \Psi_{i\pm\frac{1}{2},j} = \frac{2\pi}{3} \int_{r_{i\pm\frac{1}{2}}}^{r_{i\pm\frac{1}{2}}} [(\cos \theta_{j-\frac{1}{2}}^{n} - \cos \theta_{j+\frac{1}{2}}^{n}) + \frac{\Delta(-\cos \theta_{j\pm\frac{1}{2}})}{\Delta(-\cos \theta_{j\pm\frac{1}{2}})} (\Delta(-\cos \theta_{j-\frac{1}{2}}) - \Delta(-\cos \theta_{j+\frac{1}{2}}))] dr_{i\pm\frac{1}{2}}^{3}$$

which with Eq. (305b) results in

$$\Delta \Psi_{i\pm\frac{1}{2},j} = \frac{2\pi}{3} \Delta R_{i\pm\frac{1}{2}}^{3} \int_{0}^{1} [(\cos \theta_{j-\frac{1}{2}}^{n} - \cos \theta_{j+\frac{1}{2}}^{n+1}) \\ + \frac{\Delta r_{i\pm\frac{1}{2}}^{3}}{\Delta R_{i\pm\frac{1}{2}}^{3}} \{\Delta (-\cos \theta_{j-\frac{1}{2}}) - \Delta (-\cos \theta_{j+\frac{1}{2}})\}] d \frac{\Delta r_{i\pm\frac{1}{2}}^{3}}{\Delta R_{i\pm\frac{1}{2}}^{3}} \\ = \frac{2\pi}{3} \Delta R_{i\pm\frac{1}{2}}^{3} [\frac{\cos \theta_{j-\frac{1}{2}}^{n} + \cos \theta_{j+\frac{1}{2}}^{n+1}}{2} - \frac{\cos \theta_{j+\frac{1}{2}}^{n} + \cos \theta_{j+\frac{1}{2}}^{n+1}}{2}]. (308)$$

Here we notice that interface  $i\pm\frac{1}{2}$ , j is halfway on a cubic scale between  $r_{i\pm\frac{1}{2}}^{n}$ ,  $r_{i\pm\frac{1}{2}}^{n+1}$  or on a cosine scale between  $\vartheta_{j\pm\frac{1}{2}}^{n}$ ,  $\vartheta_{j\pm\frac{1}{2}}^{n+1}$ . Consequently, we can construct a mean cell having its corners on the paths of Eq. (305a). Let

$$r_{i\pm\frac{1}{2}}^{n+\frac{1}{2}} \equiv \left(\frac{(r_{i\pm\frac{1}{2}}^{n})^{3} + (r_{i\pm\frac{1}{2}}^{n+1})^{3}}{2}\right)^{1/3}$$
(309)

and

$$\cos \theta_{j\pm\frac{1}{2}}^{n+\frac{1}{2}} \equiv \frac{\cos \theta_{j\pm\frac{1}{2}}^{n} + \cos \theta_{j\pm\frac{1}{2}}^{n+1}}{2}.$$
 (310)

Eqs. (306) and (308) can be written then as

$$\Delta \Psi_{i,j\pm\frac{1}{2}} = \frac{2\pi}{3} \left( \cos \theta_{j\pm\frac{1}{2}}^{n} - \cos \theta_{j\pm\frac{1}{2}}^{n+1} \right) \left[ \left( r_{i+\frac{1}{2}}^{n+\frac{1}{2}} \right)^{3} - \left( r_{i-\frac{1}{2}}^{n+\frac{1}{2}} \right)^{3} \right]$$
(311)

and

$$\Delta \Psi_{i\pm\frac{1}{2},j} = \frac{2\pi}{3} \left( \cos \theta \frac{n+\frac{1}{2}}{j-\frac{1}{2}} - \cos \theta \frac{n+\frac{1}{2}}{j+\frac{1}{2}} \right) \left[ \left( r_{i\pm\frac{1}{2}}^{n+1} \right)^3 - \left( r_{i\pm\frac{1}{2}}^n \right)^3 \right], \tag{312}$$

respectively. Now in order to be able to construct the average cell,  $A_{i,j\pm\frac{1}{2}}$  and  $A_{i\pm\frac{1}{2},j}$  should take the forms

$$\mathbf{A}_{i,j\pm\frac{1}{2}}^{n+\frac{1}{2}} = \pi[(\mathbf{r}_{i+\frac{1}{2}}^{n+\frac{1}{2}})^2 - (\mathbf{r}_{i-\frac{1}{2}}^{n+\frac{1}{2}})^2] \sin \theta_{j\pm\frac{1}{2}}^{n+\frac{1}{2}}, \qquad (313a)$$

forcing the choice

$$\mathbf{v}_{i,j\pm\frac{1}{2}}^{g} \,\delta t = \frac{\Delta \Psi}{A_{i,j\pm\frac{1}{2}}^{n+\frac{1}{2}}} = \frac{2}{3} \,\frac{\left(\mathbf{r}_{i+\frac{1}{2}}^{n+\frac{1}{2}}\right)^{3} - \left(\mathbf{r}_{i-\frac{1}{2}}^{n+\frac{1}{2}}\right)^{3}}{\left(\mathbf{r}_{i+\frac{1}{2}}^{n+\frac{1}{2}}\right)^{2} - \left(\mathbf{r}_{i-\frac{1}{2}}^{n+\frac{1}{2}}\right)^{2}} \,\frac{\cos \,\theta_{j\pm\frac{1}{2}}^{n} - \cos \,\theta_{j\pm\frac{1}{2}}^{n+1}}{\sin \,\theta_{j\pm\frac{1}{2}}^{n+\frac{1}{2}}}, \quad (313b)$$

and

$$A_{\underline{i}\pm\underline{j},j}^{n+\underline{1}} = 2\pi \left(r_{\underline{i}\pm\underline{j}}^{n+\underline{1}}\right)^2 \left(\cos \theta_{j-\underline{j}}^{n+\underline{1}} - \cos \theta_{j+\underline{j}}^{n+\underline{1}}\right),$$
(314a)

forcing the choice

$$u_{i\pm\frac{1}{2}}^{g} \delta t = \frac{\Delta u_{i\pm\frac{1}{2},j}}{A_{i\pm\frac{1}{2},j}^{n+\frac{1}{2}}} = \frac{(r_{i\pm\frac{1}{2}}^{n+1})^{3} - (r_{i\pm\frac{1}{2}}^{n})^{3}}{3(r_{i\pm\frac{1}{2}}^{n+\frac{1}{2}})^{2}} .$$
(314b)

To complete the formulation, it remains to check the consistency of the two velocities  $u_{i\pm\frac{1}{2}}^{g}$ ,  $v_{i,j\pm\frac{1}{2}}^{g}$ , namely that they occur at the same instant. Differentiating (305a) with respect to time and taking  $r_{i\pm\frac{1}{2}}$ ,  $\theta_{j\pm\frac{1}{2}}$  at the moment when they are halfway i.e.,  $r_{i\pm\frac{1}{2}}^{n+\frac{1}{2}}$ ,  $\theta_{j\pm\frac{1}{2}}$ , we get

$$\frac{3(r_{i\pm\frac{1}{2}}^{n+\frac{1}{2}})^{2}(dr_{i\pm\frac{1}{2}}/dt)^{n+\frac{1}{2}}}{(r_{i\pm\frac{1}{2}}^{n+1})^{3} - (r_{i\pm\frac{1}{2}}^{n})^{3}} = \frac{\sin \theta_{j\pm\frac{1}{2}}^{n+1}(d\theta_{j\pm\frac{1}{2}}/dt)^{n+\frac{1}{2}}}{\cos \theta_{j\pm\frac{1}{2}}^{n} - \cos \theta_{j\pm\frac{1}{2}}^{n+1}}.$$

Recognizing that  $(dr_{i\pm\frac{1}{2}}/dt)^{n+\frac{1}{2}} = u_{i\pm\frac{1}{2}}^{g}$ , the velocity of the grid at  $t^{n} + \frac{\delta t}{2}$ , from Eq. (314b) and the above equation we obtain

$$\frac{d\theta_{j\pm\frac{1}{2}}}{dt} \cdot \delta t = \frac{\cos \theta_{j\pm\frac{1}{2}}^n - \cos \theta_{j\pm\frac{1}{2}}^{n+1}}{\sin \theta_{j\pm\frac{1}{2}}^{n+\frac{1}{2}}}, \qquad (315)$$

whence from Eq. (313b), the velocity of the grid at  $t^n + \frac{\partial t}{2}$ ,

$$v_{i,j\pm\frac{1}{2}}^{g} = \frac{2}{3} \frac{(r_{i+\frac{1}{2}}^{n+\frac{1}{2}})^{3} - (r_{i-\frac{1}{2}}^{n+\frac{1}{2}})^{3}}{(r_{i+\frac{1}{2}}^{n+\frac{1}{2}})^{2} - (r_{i-\frac{1}{2}}^{n+\frac{1}{2}})^{2}} \frac{(\frac{d\vartheta_{j\pm\frac{1}{2}}}{dt})^{n+\frac{1}{2}}}{dt}$$
(316)

Recognizing  $(\frac{de_{j\pm\frac{1}{2}}}{dt})$  as the angular velocity at  $t^n + \delta t/2$  of the interface i,j $\pm\frac{1}{2}$  [from Eq. (315) obviously independent of index i as expected after the discussion in the section "Rectangular Grid Motion"], we can define an average radius for the interface i,j $\pm\frac{1}{2}$  (independent of j) as

$$R_{i}^{n+\frac{1}{2}} = \frac{\frac{1}{3} \left[ \left( r_{i+\frac{1}{2}}^{n+\frac{1}{2}} \right)^{2} + \left( r_{i+\frac{1}{2}}^{n+\frac{1}{2}} \right) \left( r_{i-\frac{1}{2}}^{n+\frac{1}{2}} \right)^{2} \right]}{\frac{1}{2} \left[ \left( r_{i+\frac{1}{2}}^{n+\frac{1}{2}} \right) + \left( r_{i-\frac{1}{2}}^{n+\frac{1}{2}} \right) \right]}$$
(317)

Finally, the mean cell volume is

$$\Psi_{i,j}^{n+\frac{1}{2}} = \frac{2\pi}{3} \left[ \left( r_{i+\frac{1}{2}}^{n+\frac{1}{2}} \right)^3 - \left( r_{i-\frac{1}{2}}^{n+\frac{1}{2}} \right)^3 \right] \left( \cos \theta_{j-\frac{1}{2}}^{n+\frac{1}{2}} - \cos \theta_{j+\frac{1}{2}}^{n+\frac{1}{2}} \right). \tag{318}$$

Coordinate cases 4-7 will be treated in a later report.

### XV. SOURCE TERMS

As explained earlier, source terms are integrated either over cell volume or over cell interface area. The volumes and areas used are those of the mean cell. The balance of source terms is the main reason for the necessity of a closed mean cell construction, i.e., the ability to construct a closed cell whose corners are on the paths between old and new cell corners. For example, if we try to solve a hydrostatic pressure problem in cylindrical r-z coordinates, the momentum equation is nothing but the balance of the body gravity force and the pressure force on the top and bottom surfaces. If the mid-cell interfaces compose a closed surface enclosing the midway cell which happens to have a volume consistent with the interface areas, force balance is already guaranteed (provided the pressures are correct).

Let us consider the difference form of  $-\int_{g} pnds$  (yielding - grad p) in the three coordina<sup>4</sup> ases considered above. The resulting forces along the x, y directions are

$$F_{x_{i,j}} = (p_{i-\frac{1}{2},j}^{n+\frac{1}{2}} - p_{i+\frac{1}{2},j}^{n+\frac{1}{2}})A_{i}^{n+\frac{1}{2}};$$

$$F_{y_{i,j}} = (p_{i,j-\frac{1}{2}}^{n+\frac{1}{2}} - p_{i,j+\frac{1}{2}}^{n+\frac{1}{2}})A_{j}^{n+\frac{1}{2}};$$
(321a)
(321b)

respectively, where

$$p_{i+\frac{1}{2},j}^{n+\frac{1}{2}} = \frac{p_{i,j}^{n+\frac{1}{2}} + p_{i+1,j}^{n+\frac{1}{2}}}{2}$$
(322a)

and

$$p_{i,j+\frac{1}{2}}^{n+\frac{1}{2}} = \frac{p_{i,j}^{n+\frac{1}{2}} + p_{i,j+1}^{n+\frac{1}{2}}}{2} .$$
(322b)

In cylindrical r-z coordinates,

$$F_{r_{i,j}} = p_{i-\frac{1}{2},j}^{n+\frac{1}{2}} A_{i-\frac{1}{2},j}^{n+\frac{1}{2}} - p_{i+\frac{1}{2},j}^{n+\frac{1}{2}} A_{i+\frac{1}{2},j}^{n+\frac{1}{2}} + 2\pi p_{i,j}^{n+\frac{1}{2}} (r_{i+\frac{1}{2}}^{n+\frac{1}{2}} - r_{i-\frac{1}{2}}^{n+\frac{1}{2}}) (r_{j+\frac{1}{2}}^{n+\frac{1}{2}} - r_{j-\frac{1}{2}}^{n+\frac{1}{2}}),$$

which with Eq. (303) yields

$$F_{i,j} = p_{i-\frac{1}{2},j}^{n+\frac{1}{2}} A_{i-\frac{1}{2},j}^{n+\frac{1}{2}} - p_{i+\frac{1}{2},j}^{n+\frac{1}{2}} A_{i+\frac{1}{2},j}^{n+\frac{1}{2}} + \frac{p_{i,j}^{n+\frac{1}{2}}}{r_{i}^{n+\frac{1}{2}}}, \qquad (323a)$$

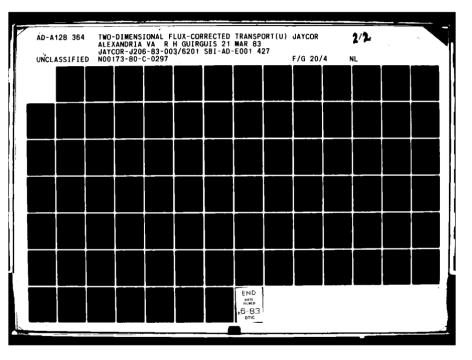
where

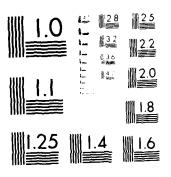
$$c_{i}^{n+\frac{1}{2}} \equiv \frac{r_{i+\frac{1}{2}}^{n+\frac{1}{2}} + r_{i-\frac{1}{2}}^{n+\frac{1}{2}}}{2} .$$
(324)

We notice that  $p_{i,j}^{n+\frac{1}{2}}/r_i^{n+\frac{1}{2}}$  acts as a body force per unit volume. The force in the z-direction is

$$F_{z_{i,j}} = (p_{i,j-\frac{1}{2}}^{n+\frac{1}{2}} - p_{i,j+\frac{1}{2}}^{n+\frac{1}{2}})A_{i}^{n+\frac{1}{2}}.$$
 (323b)

In spherical r-2 coordinates, as illustrated in Fig. 38, the pressure acting on the hatched area creates a resultant force normal to the axis from which 3 is measured, which in turn gives rise to a radial component  $F'_r$  and a tangential component  $F'_{\theta}$ . This situation, namely, the creation of a body-force-like component, occurs whenever the area of parallel surfaces of the cell are not equal. This is bound to happen whenever the interface area depends on both indices i,j. A simple way to evaluate the force generated is the "pressure x projected area" since this area is the difference between the areas of these parallel surfaces. The radial force is therefore





MICROCOPY RESOLUTION TEST CHARS

$$F_{r_{i,j}} = p_{i-\frac{1}{2},j}^{n+\frac{1}{2}} A_{i-\frac{1}{2},j}^{n+\frac{1}{2}} - p_{i+\frac{1}{2},j}^{n+\frac{1}{2}} A_{i+\frac{1}{2},j}^{n+\frac{1}{2}} + F_{r_{i,j}}'$$

where

$$F'_{r,j} = p_{i,j}^{n+\frac{1}{2}} (A_{i+\frac{1}{2},j}^{n+\frac{1}{2}} - A_{i-\frac{1}{2},j}^{n+\frac{1}{2}}) = 2\pi p_{i,j}^{n+\frac{1}{2}} ((r_{i+\frac{1}{2}}^{n+\frac{1}{2}})^{2})$$
$$- (r_{i-\frac{1}{2}}^{n+\frac{1}{2}})^{2} (\cos \theta_{j-\frac{1}{2}}^{n+\frac{1}{2}} - \cos \theta_{j+\frac{1}{2}}^{n+\frac{1}{2}}) = \frac{2p_{i,j}^{n+\frac{1}{2}} \psi_{i,j}^{n+\frac{1}{2}}}{R_{i}^{n+\frac{1}{2}}};$$

R was defined earlier in Eq. (317). Thus

$$F_{r_{i,j}} = p_{i-\frac{1}{2},j}^{n+\frac{1}{2}} A_{i-\frac{1}{2},j}^{n+\frac{1}{2}} - p_{i+\frac{1}{2},j}^{n+\frac{1}{2}} A_{i+\frac{1}{2},j}^{n+\frac{1}{2}} + \frac{2p_{i,j}^{n+\frac{1}{2}} + v_{i,j}^{n+\frac{1}{2}}}{R_{i}^{n+\frac{1}{2}}}.$$
 (325)

As for the tangential direction,

$$F_{j} = p_{i,j-\frac{1}{2}}^{n+\frac{1}{2}} A_{i,j+\frac{1}{2}}^{n+\frac{1}{2}} - p_{i,j+\frac{1}{2}}^{n+\frac{1}{2}} A_{i,j+\frac{1}{2}}^{n+\frac{1}{2}} + F_{j}^{\prime},$$

where

$$F_{\vartheta_{i,j}} = p_{i,j}^{n+\frac{1}{2}} (A_{i,j+\frac{1}{2}}^{n+\frac{1}{2}} - A_{i,j-\frac{1}{2}}^{n+\frac{1}{2}}) = \pi p_{i,j}^{n+\frac{1}{2}} [(r_{i+\frac{1}{2}}^{n+\frac{1}{2}})^{2} - (r_{i-\frac{1}{2}}^{n+\frac{1}{2}})^{2}] (\sin \vartheta_{j+\frac{1}{2}}^{n+\frac{1}{2}} - \sin \vartheta_{j-\frac{1}{2}}^{n+\frac{1}{2}}).$$

If we note that

$$\sin \theta_{j+\frac{1}{2}}^{n+\frac{1}{2}} - \sin \theta_{j-\frac{1}{2}}^{n+\frac{1}{2}} = 2 \sin \left( \frac{\theta_{j+\frac{1}{2}}^{n+\frac{1}{2}} - \theta_{j-\frac{1}{2}}^{n+\frac{1}{2}}}{2} \right) \cos \left( \frac{\theta_{j+\frac{1}{2}}^{n+\frac{1}{2}} + \theta_{j-\frac{1}{2}}^{n+\frac{1}{2}}}{2} \right)$$

and

$$\cos \theta_{j-\frac{1}{2}}^{n+\frac{1}{2}} - \cos \theta_{j+\frac{1}{2}}^{n+\frac{1}{2}} = 2 \sin \left(\frac{\theta_{j+\frac{1}{2}}^{n+\frac{1}{2}} + \theta_{j-\frac{1}{2}}^{n+\frac{1}{2}}}{2}\right) \sin \left(\frac{\theta_{j+\frac{1}{2}}^{n+\frac{1}{2}} + \theta_{j-\frac{1}{2}}^{n+\frac{1}{2}}}{2}\right)$$
  
and using Eq. (318),  $F_{\theta}$  can be expressed as

$$\mathbf{F}_{j}' = \frac{p_{i,j}^{n+\frac{1}{2}} \cdot y_{i,j}^{n+\frac{1}{2}}}{R_{i}^{n+\frac{1}{2}} \tan c_{j}^{n+\frac{1}{2}}},$$

where

$$\partial_{j}^{n+\frac{1}{2}} = \frac{\partial_{j+\frac{1}{2}}^{n+\frac{1}{2}} + \partial_{j-\frac{1}{2}}^{n+\frac{1}{2}}}{2} .$$
(326)

Thus

$$F_{j} = p_{i,j-\frac{1}{2}}^{n+\frac{1}{2}} A_{i,j-\frac{1}{2}}^{n+\frac{1}{2}} - p_{i,j+\frac{1}{2}}^{n+\frac{1}{2}} A_{i,j+\frac{1}{2}}^{n+\frac{1}{2}} + \frac{p_{i,j}^{n+\frac{1}{2}} w^{n+\frac{1}{2}}}{R_{i}^{n+\frac{1}{2}} \tan \Theta_{j}^{n+\frac{1}{2}}},$$
  
Next, let us consider the difference form of  $-\int p \vec{u} \cdot \vec{n} ds$  [yielding - div( $p \vec{u}$ )].

For the three coordinate systems considered above, the power added to the cell (i,j) is

$$P_{i,j} = p_{i-\frac{1}{2},j}^{n+\frac{1}{2}} u_{i-\frac{1}{2},j}^{n+\frac{1}{2}} A_{i-\frac{1}{2},j}^{n+\frac{1}{2}} - p_{i+\frac{1}{2},j}^{n+\frac{1}{2}} u_{i+\frac{1}{2},j}^{n+\frac{1}{2}} A_{i+\frac{1}{2},j}^{n+\frac{1}{2}} + p_{i,j-\frac{1}{2}}^{n+\frac{1}{2}} v_{i,j-\frac{1}{2}}^{n+\frac{1}{2}} A_{i,j-\frac{1}{2}}^{n+\frac{1}{2}} - p_{i,j+\frac{1}{2}}^{n+\frac{1}{2}} v_{i,j+\frac{1}{2}}^{n+\frac{1}{2}} A_{i,j+\frac{1}{2}}^{n+\frac{1}{2}}$$
(328)

where

$$u_{i+\frac{1}{2},j}^{n+\frac{1}{2}} = \frac{u_{i,j}^{n+\frac{1}{2}} + u_{i+1,j}^{n+\frac{1}{2}}}{2}$$
(329a)

and

$$v_{i,j+\frac{1}{2}}^{n+\frac{1}{2}} = \frac{v_{i,j}^{n+\frac{1}{2}} + v_{i,j+1}^{n+\frac{1}{2}}}{2}.$$
 (329b)

The forces  $(\mathbb{F}_{x}, \mathbb{F}_{y})$ ,  $(\mathbb{F}_{r}, \mathbb{F}_{z})$ , and  $(\mathbb{F}_{r}, \mathbb{F}_{\theta})$ , and the power P constitute a sample of the source terms encountered in treating generalized continuity equations. These are denoted by source  $\frac{n+\frac{1}{2}}{i,j}$  in the next section.

#### XVI. ALGORITHM

We describe the implementation of the scheme of Eqs. (223). The program and calling sequence are listed in the Appendix.

Assume a rectangular grid in two dimensions denoted by the coordinates x, y (not necessarily cartesian; for example x  $\equiv$  r, y  $\equiv$   $\theta$  yield spherical coordinates). Let the interfaces coordinates be  $x_{1/2}$ ,  $x_{3/2}$ ,...,  $x_{N_x+1/2}$ ;  $y_{1/2}$ ,  $y_{3/2}$ ,...,  $y_{N_y+1/2}$  (see Fig. 39).

The cell centers are located midway between the interfaces and are denoted by a pair of indices (i,j), corresponding to (x,y), respectively. The cell volumes are given by

$$\begin{array}{l} n,n+1 \\ \forall i,j \end{array} = \left\{ \begin{array}{l} {\mathop{\rm cartesian}}\\ x-y \end{array} : (y_{j+\frac{1}{2}}^{n,n+1} - y_{j-\frac{1}{2}}^{n,n+1}) (x_{i+\frac{1}{2}}^{n,n+1} - x_{i-\frac{1}{2}}^{n,n+1});\\ {\mathop{\rm cylindrical}}\\ r-z \end{array} : [(x_{i+\frac{1}{2}}^{n,n+1})^2 - (x_{i-\frac{1}{2}}^{n,n+1})^2] [y_{j+\frac{1}{2}}^{n,n+1} - y_{j-\frac{1}{2}}^{n,n+1}]\\ {\mathop{\rm spherical}}\\ {\mathop{\rm spherical}}\\ r-\vartheta : \frac{2\pi}{3} [(x_{i+\frac{1}{2}}^{n,n+1})^3 - (x_{i-\frac{1}{2}}^{n,n+1})^3] [\cos y_{j-\frac{1}{2}}^{n,n+1} - \cos y_{j+\frac{1}{2}}^{n,n+1}]; \end{array} \right.$$

We have then

$$\begin{aligned}
\varphi_{i,j}^{n+1} & \nabla_{x}^{T} = \psi_{i,j}^{n} \rho_{i,j}^{n} - \delta t \left( \rho_{i+\frac{1}{2},j}^{n} A_{i+\frac{1}{2},j}^{n+\frac{1}{2}} \delta U_{i+\frac{1}{2},j}^{n+\frac{1}{2}} \right) \\
&+ \delta t \left( \rho_{i-\frac{1}{2},j}^{n} A_{i-\frac{1}{2},j}^{n+\frac{1}{2}} \delta U_{i-\frac{1}{2},j}^{n+\frac{1}{2}} \right) + \text{source } \frac{n+\frac{1}{2}}{i,j} 
\end{aligned}$$
(332a)

and

$$\begin{aligned} \Psi_{i,j}^{n+1} \rho_{i,j}^{T_{Y}} &= \Psi_{i,j}^{n} \rho_{i,j}^{n} - \delta t \left( \rho_{i,j+\frac{1}{2}}^{n} A_{i,j+\frac{1}{2}}^{n+\frac{1}{2}} \delta V_{i,j+\frac{1}{2}}^{n+\frac{1}{2}} \right) \\ &+ \delta t \left( \rho_{i,j-\frac{1}{2}}^{n} A_{i,j-\frac{1}{2}}^{n+\frac{1}{2}} \delta V_{i,j-\frac{1}{2}}^{n+\frac{1}{2}} \right) + \text{ source } \overset{n+\frac{1}{2}}{i,j} \end{aligned} (332b)$$

for  $(i = 1, ..., N_x)$  and  $(j = 1, ..., N_y)$ , where

$$\rho_{i+\frac{1}{2},j}^{n} = \frac{\rho_{i,j}^{n} + \rho_{i+1,j}^{n}}{2}$$
(33a)

for 
$$i = 1, ..., N_x - 1$$
 and  $j = 1, ..., N_y$ , while  
 $\rho_{i,j+\frac{1}{2}}^n = \frac{\rho_{i,j}^n + \rho_{i,j+1}^n}{2}$ 
(333b)

for  $i = 1, ..., N_x$  and  $j = 1, ..., N_y - 1$ . The boundary values  $\rho_{\frac{1}{2},j}^n$ ,  $\rho_{N_x+\frac{1}{2},j}^n$ are obtained from

$$\rho_{\frac{1}{2},j}^{n} = \frac{\rho_{1,j}^{n} + \rho_{L,j}^{n}}{2};$$
$$\rho_{N_{x}+\frac{1}{2},j}^{n} = \frac{\rho_{N_{x},j}^{n} + \rho_{R,j}^{n}}{2}$$

for (j = 1,...,N ) where L and R denote left and right boundaries, respectively, while

$$\rho_{i,\frac{1}{2}}^{n} = \frac{\rho_{i,1}^{n} + \rho_{i,B}^{n}}{2};$$

$$\rho_{i,N_{y}+\frac{1}{2}}^{n} = \frac{\rho_{i,N_{y}}^{n} + \rho_{i,T}^{n}}{2}$$

for  $(i = 1, ..., N_x)$  where B and T denote bottom and top boundaries,

respectively. The mean interface areas  $A_{i+\frac{1}{2},j}^{n+\frac{1}{2}}$  and  $A_{i,j+\frac{1}{2}}^{n+\frac{1}{2}}$  are given by

$$A_{i+\frac{1}{2},j}^{n+\frac{1}{2}} = y_{j+\frac{1}{2}}^{n+\frac{1}{2}} - y_{j-\frac{1}{2}}^{n+\frac{1}{2}}$$
(334a)

and

$$A_{i,j+\frac{1}{2}}^{n+\frac{1}{2}} = x_{i+\frac{1}{2}}^{n+\frac{1}{2}} - x_{i-\frac{1}{2}}^{n+\frac{1}{2}},$$
(334b)

where

$$y_{j+\frac{1}{2}}^{n+\frac{1}{2}} = \frac{y_{j+\frac{1}{2}}^{n} + y_{j+\frac{1}{2}}^{n+1}}{2}$$
(335a)

and

$$x_{i+\frac{1}{2}}^{n+\frac{1}{2}} = \frac{x_{i+\frac{1}{2}}^{n} + x_{i+\frac{1}{2}}^{n+1}}{2}$$
(335b)

for cartesian x-y coordinates; by

$$A_{i+\frac{1}{2},j}^{n+\frac{1}{2}} = 2\pi x_{i+\frac{1}{2}}^{n+\frac{1}{2}} (y_{j+\frac{1}{2}}^{n+\frac{1}{2}} - y_{j-\frac{1}{2}}^{n+\frac{1}{2}})$$
(336a)

and

$$A_{i,j+\frac{1}{2}}^{n+\frac{1}{2}} = \pi \left[ \left( x_{i+\frac{1}{2}}^{n+\frac{1}{2}} \right)^2 - \left( x_{i-\frac{1}{2}}^{n+\frac{1}{2}} \right)^2 \right],$$
(336b)

where

$$y_{j+\frac{1}{2}}^{n+\frac{1}{2}} = \frac{y_{j+\frac{1}{2}}^{n} + y_{j+\frac{1}{2}}^{n+1}}{2}$$
(337a)

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$$\mathbf{x}_{i+\frac{1}{2}}^{n+\frac{1}{2}} = \begin{bmatrix} \frac{(\mathbf{x}_{i+\frac{1}{2}}^{n})^{2} + (\mathbf{x}_{i+\frac{1}{2}}^{n+1})^{2}}{2} \end{bmatrix}^{\frac{1}{2}}$$
(337b)

for cylindrical r-z coordinates; and by

93

$$A_{i+\frac{1}{2},j}^{n+\frac{1}{2}} = 2\pi \left(x_{i+\frac{1}{2}}^{n+\frac{1}{2}}\right)^2 \left[\cos y_{j-\frac{1}{2}}^{n+\frac{1}{2}} - \cos y_{j+\frac{1}{2}}^{n+\frac{1}{2}}\right]$$
(338a)

and

$$A_{i,j+\frac{1}{2}}^{n+\frac{1}{2}} = \pi [x_{i+\frac{1}{2}}^{n+\frac{1}{2}})^2 - (x_{i-\frac{1}{2}}^{n+\frac{1}{2}})^2] \sin y_{j+\frac{1}{2}}^{n+\frac{1}{2}},$$
(338b)

where

$$y_{j+\frac{1}{2}}^{n+\frac{1}{2}} = \arccos \left[\frac{1}{2} \{\cos y_{j+\frac{1}{2}}^{n} + \cos y_{j+\frac{1}{2}}^{n+1} \} \right]$$
 (339a)

and

$$x_{i+\frac{1}{2}}^{n+\frac{1}{2}} \left[ \frac{(x_{i+\frac{1}{2}}^{n})^{3} + (x_{i+\frac{1}{2}}^{n+1})^{3}}{2} \right]^{1/3}$$
(339b)

for spherical r- $\theta$  coordinates. Finally,

$$\delta U_{i+\frac{1}{2},j}^{n+\frac{1}{2}} = u_{i+\frac{1}{2},j}^{n+\frac{1}{2}} - u_{i+\frac{1}{2},j}^{g}$$
(340a)

and

$$\delta V_{i,j+\frac{1}{2}}^{n+\frac{1}{2}} = v_{i,j+\frac{1}{2}}^{n+\frac{1}{2}} - v_{i,j+\frac{1}{2}}^{g}$$
(341a)

The grid velocities  $u_{i+\frac{1}{2},j}^{g}$ ,  $v_{i,j+\frac{1}{2}}^{g}$  are given by

$$u_{i+\frac{1}{2},j}^{g} = \frac{x_{i+\frac{1}{2}}^{n+1} - x_{i+\frac{1}{2}}^{n}}{\delta t}$$
(341b)

$$v_{i,j+\frac{1}{2}}^{g} = \frac{y_{j+\frac{1}{2}}^{n+1} - y_{j+\frac{1}{2}}^{n}}{\delta t}$$

for cartesian x-y coordinates; by

$$u_{i+\frac{1}{2},j}^{g} = \frac{\left(x_{i+\frac{1}{2}}^{n+1}\right)^{2} - \left(x_{i+\frac{1}{2}}^{n}\right)^{2}}{2 x_{i+\frac{1}{2}}^{n+\frac{1}{2}} \delta t}$$
(342a)

$$v_{i,j+\frac{1}{2}}^{g} = \frac{y_{j+\frac{1}{2}}^{n+1} - y_{j+\frac{1}{2}}^{n}}{\delta t}$$
 (342b)

94

for cylindrical r-z coordinates; and by

$$u_{i+\frac{1}{2},j}^{g} = \frac{(x_{i+\frac{1}{2}}^{n+1})^{3} - (x_{i+\frac{1}{2}}^{n})^{3}}{3(x_{i+\frac{1}{2}}^{n+\frac{1}{2}})^{2} \delta t}$$
(343a)

$$v_{i,j+\frac{1}{2}}^{g} = \frac{x_{i}^{n+\frac{1}{2}}}{\delta t} \frac{\cos y_{j+\frac{1}{2}}^{n} - \cos y_{j+\frac{1}{2}}^{n+1}}{\sin y_{j+\frac{1}{2}}^{n+\frac{1}{2}}}$$
(343b)

for spherical r- $\boldsymbol{\vartheta}$  coordinates, where

$$x_{i}^{n+\frac{1}{2}} = \frac{2}{3} \frac{\left(x_{i+\frac{1}{2}}^{n+\frac{1}{2}}\right)^{2} + \left(x_{i+\frac{1}{2}}^{n+\frac{1}{2}}\right) \left(x_{i-\frac{1}{2}}^{n+\frac{1}{2}}\right) + \left(x_{i-\frac{1}{2}}^{n+\frac{1}{2}}\right)^{2}}{x_{i+\frac{1}{2}}^{n+\frac{1}{2}} + x_{i-\frac{1}{2}}^{n+\frac{1}{2}}}.$$
(344)

Equations (334)-(344) are valid for  $i = 0, 1, ..., N_x$  and  $j = 0, 1, ..., N_y$ . Equations (332) yield  $\rho_{i,j}^{Tx}$  and  $\rho_{i,j}^{Ty}$ , which are used later to evaluate the antidiffusion fluxes. The transported and diffused densities are then obtained from

$$\begin{aligned} \Psi_{i,j}^{n+1} \rho_{i,j}^{TD} &= \Psi_{i,j}^{n+1} \rho_{i,j}^{T} + \nu_{i+\frac{1}{2},j} \Psi_{i+\frac{1}{2},j}^{n+1} (\rho_{i+1,j}^{n} - \rho_{i,j}^{n}) \\ &= \nu_{i-\frac{1}{2},j} \Psi_{i-\frac{1}{2},j}^{n+1} (\rho_{i,j}^{n} - \rho_{i-1,j}^{n}) + \nu_{i,j+\frac{1}{2}} \Psi_{i,j+\frac{1}{2}}^{n+1} (\rho_{i,j+1}^{n}) \\ &= \rho_{i,j}^{n} - \nu_{i,j-\frac{1}{2}} \Psi_{i,j-\frac{1}{2}}^{n+1} (\rho_{i,j}^{n} - \rho_{i,j-1}^{n}) \end{aligned}$$
(346)  
for i = 1,..., N<sub>x</sub> and j = 1,..., N<sub>y</sub>, where

$$v_{i+\frac{1}{2},j} = \frac{1}{6} + \frac{1}{3} \varepsilon_{i+\frac{1}{2},j}^2$$
 (347a)

and

$$v_{i,j+\frac{1}{2}} = \frac{1}{6} + \frac{1}{3} \varepsilon_{i,j+\frac{1}{2}}^{2}$$
(347b)

while

$$\mathbf{y}_{i+\frac{1}{2},j}^{n+1} = \frac{1}{2} (\mathbf{y}_{i,j}^{n+1} + \mathbf{y}_{i+1,j}^{n+1})$$
(348a)

for  $i = 1, ..., N_x - 1$  and  $j = 1, ..., N_y$ . Similarly,

$$\Psi_{i,j+\frac{1}{2}} = \frac{1}{2} (\Psi_{i,j}^{n+1} + \Psi_{i,j+1}^{n+1})$$
(348b)

for  $i = 1, ..., N_x$  and  $j = 1, ..., N_y - 1$ . At the boundaries,

for  $i = 1, ..., N_x$ . The dimensionless velocities  $\varepsilon_{i+\frac{1}{2},j}$ ,  $\varepsilon_{i,j+\frac{1}{2}}$  are obtained from

$$\varepsilon_{i+\frac{1}{2},j} = \frac{\delta U_{i+\frac{1}{2},j}^{n+\frac{1}{2}} A_{i+\frac{1}{2},j}^{n+\frac{1}{2}} \delta t}{2} \left( \frac{1}{\psi_{i,j}^{n+1}} + \frac{1}{\psi_{i,j}^{n+1}} \right)$$
(350a)

for  $i = 0, \dots, N_x$  and  $j = 1, \dots, N_y$  using (349a) and

$$\varepsilon_{i,j+\frac{1}{2}} = \frac{\delta v_{i,j+\frac{1}{2}}^{n+\frac{1}{2}} A_{i,j+\frac{1}{2}}^{n+\frac{1}{2}} \delta t}{2} \left( \frac{1}{v_{i,j+\frac{1}{2}}^{n+1}} + \frac{1}{v_{i,j+\frac{1}{2}}^{n+1}} \right)$$
(350b)

for  $i = 1, ..., N_x$  and  $j = 0, ..., N_y$  using (349b). The antidiffusion fluxes are then evaluated according to

$$F_{i+\frac{1}{2},j} = \mu_{i+\frac{1}{2},j} \frac{\Psi^{n+1}_{i+\frac{1}{2},j}}{\Psi^{n+\frac{1}{2},j}} (\rho_{i+1,j}^{Tx} - \rho_{i,j}^{Tx})$$
(351a)

and

$$F_{i,j+\frac{1}{2}} = \mu_{i,j+\frac{1}{2}} + \frac{\psi_{i,j+\frac{1}{2}}^{n+1}}{\psi_{i,j+\frac{1}{2}}} (\rho_{i,j+1}^{Ty} - \rho_{i,j}^{Ty}),$$
(351b)

where

$$\mu_{i+\frac{1}{2},j} = \frac{1}{6} - \frac{2}{3} \epsilon_{i+\frac{1}{2},j}^2$$

and

$$\mu_{i,j+\frac{1}{2}} = \frac{1}{6} - \frac{2}{3} \varepsilon_{i,j+\frac{1}{2}}^{2}.$$

### FLUX CORRECTION

The flux correction adopted here is that of Zalesak<sup>5</sup> in multidimensions. It "guarantees that the four antidiffusion fluxes, associated with each cell, acting in concert, do not create any ripples." In our notation it takes the following form:

1. A flux is cancelled if it is opposite to the local gradient of  $p^{\text{TD}}$  along the same direction, and if opposite to either or both adjacent gradients of  $p^{\text{TD}}$ , i.e.,  $\mathbf{F}_{i+\frac{1}{2},j} = 0$  if

$$[F_{i+\frac{1}{2},j}(\rho_{i+1,j}^{TD} - \rho_{i,j}^{TD}) < 0]$$
 and  $\{[F_{i+\frac{1}{2},j}(\rho_{i+2,j}^{TD})]$ 

$$-\rho_{i+1,j}^{\text{TD}} < 0 ] \text{ or } [F_{i+\frac{1}{2},j}(\rho_{i,j}^{\text{TD}} - \rho_{i-1,j}^{\text{TD}}) < 0] \}$$
(352a)

and  $F_{i,j+\frac{1}{2}} = 0$  if

$$[F_{i,j+\frac{1}{2}}(\rho_{i,j+1}^{TD} - \rho_{i,j}^{TD}) < 0] \text{ and } \{[F_{i,j+\frac{1}{2}}(\rho_{i,j+2}^{TD} - \rho_{i,j+2}^{TD}) < 0]\}.$$

$$(352b)$$

2. Evaluate the total in- and out-fluxes and their upper bounds. Let  $P_{i,j}^+$  equal the sum of all antidiffusive fluxes "into" grid point (i,j):

$$P_{i,j}^{+} = \max (0, F_{i-\frac{1}{2},j}) - \min (0, F_{i+\frac{1}{2},j}) + \max (0, F_{i,j-\frac{1}{2}}) - \min (0, F_{i,j+\frac{1}{2}}).$$
(353a)

Next we evaluate the upper bound  $Q_{i,j}^{\dagger}$  on  $P_{i,j}^{\dagger}$ :

$$Q_{i,j}^{+} = (p_{i,j}^{\max} - p_{i,j}^{TD}) \Psi_{i,j}^{n+1}.$$
 (354a)

The limiting ratio  $R_{i,j}^{\dagger}$  is thus estimated as

$$R_{i,j}^{+} = \begin{cases} \min (1, Q_{i,j}^{+}/P_{i,j}^{+}) & \text{if } P_{i,j}^{+} > 0 \\ 0 & \text{if } P_{i,j}^{+} = 0 \end{cases}$$
(355a)

Figure 40 illustrates the bounding process. Similarly, an upper bound  $Q_{i,j}^-$  is placed on the "outgoing" fluxes.

$$P_{i,j}^{-} = \max (0, F_{i+\frac{1}{2},j}) - \min (0, F_{i-\frac{1}{2},j}) + \max (0, F_{i,j+\frac{1}{2}}) - \min (0, F_{i,j-\frac{1}{2}})$$
(353b)

$$Q_{i,j}^{-} = (\rho_{i,j}^{\text{TD}} - \rho_{i,j}^{\text{min}}) \psi_{i,j}^{n+1}$$

$$R_{i,j}^{-} = \begin{cases} \min(1, \frac{Q_{i,j}}{p_{i,j}}) & \text{if } p_{i,j}^{-} > 0 \\ p_{i,j}^{-} & p_{i,j}^{-} > 0 \end{cases}$$
(354b)

$$\begin{array}{c}
 i, j \\
 0 \\
 if P_{i,j} = 0 \\
 i, j \\
 (355b)
 \end{array}$$

In the above  $\rho_{i,j}^{\max}$ ,  $\rho_{i,j}^{\min}$  are the upper and lower bounds, respectively, on  $\rho_{i,j}^{n+1}$ , chosen so as to guarantee no ripples formation at grid point (i,j). Finally, since each flux leaves a cell to enter an adjacent one,

3. The fluxes correction factors are defined as

$$C_{i+\frac{1}{2},j} = \begin{cases} \min (R_{i+1,j}^{+}, R_{i,j}^{-}) & \text{if } F_{i+\frac{1}{2},j} \ge 0 \\ \\ \min (R_{i+1,j}^{-}, R_{i,j}^{+}) & \text{if } F_{i+\frac{1}{2},j} \le 0 \end{cases}$$
(356a)

and

$$C_{i,j+\frac{1}{2}} = \begin{cases} \min (R_{i,j+1}^{+}, R_{i,j}^{-}) & \text{if } F_{i,j+\frac{1}{2}} \ge 0 \\ \min (R_{i,j+1}^{-}, R_{i,j}^{+}) & \text{if } F_{i,j+\frac{1}{2}} < 0. \end{cases}$$
(356b)

The corrected fluxes are given by

$$F_{i+\frac{1}{2},j}^{C} = C_{i+\frac{1}{2},j} F_{i+\frac{1}{2},j}, \qquad (357a)$$

$$F_{i,j+\frac{1}{2}}^{C} = C_{i,j+\frac{1}{2}} F_{i,j+\frac{1}{2}}, \qquad (357b)$$

4. For  $\rho_{j}^{max}$  and  $\rho_{j}^{min}$ , two choices are presented. A conservative choice would be

$$\rho_{i,j}^{\max} = \max (\rho_{i-1,j}^{TD}, \rho_{i,j-1}^{TD}, \rho_{i,j'}^{TD}, \rho_{i,j+1,j}^{TD}, \rho_{i,j+1}^{TD}); \qquad (358a)$$

$$\rho_{i,j}^{\min} = \min \left( \rho_{i-1,j}^{\text{TD}}, \rho_{i,j-1}^{\text{TD}}, \rho_{i,j}^{\text{TD}}, \rho_{i+1,j}^{\text{TD}}, \rho_{i,j+1}^{\text{TD}} \right).$$
(358b)

A more tolerant choice that gets rid of the problems of "clipping" and "terracing" partially is

$$\rho_{i,j}^{\max} = \max \left( \rho_{i-1,j}^{a}, \rho_{i,j-1}^{a}, \rho_{i,j}^{a}, \rho_{i+1,j}^{a}, \rho_{i,j+1}^{a} \right), \quad (359a)$$

where

$$\rho_{i,j}^{a} = \max \left( \rho_{i,j}^{TD}, \rho_{i,j}^{n} \right),$$

and

$$D_{i,j}^{\min} = \min \left( p_{i-1,j}^{b}, p_{i,j-1}^{b}, p_{i,j}^{b}, p_{i+1,j}^{b}, p_{j+1}^{b} \right),$$
(359b)

where

$$s_{i,j}^{b} = \min (\rho_{i,j}^{TD}, \rho_{i,j}^{n}).$$

### ANTIDIFFUSION AND HALF-STEP UPDATING

The corrected antidiffusion fluxes are added

$$\Psi_{i,j}^{n+1} \circ_{i,j}^{n+1} = \Psi_{i,j}^{n+1} \circ_{i,j}^{TD} - (F_{i+\frac{1}{2},j}^{C} - F_{i-\frac{1}{2},j}^{C}) - (F_{i,j+\frac{1}{2}}^{C} - F_{i,j-\frac{1}{2}}^{C})$$
(360)

thus giving the new density  $j_{i,j}^{n+1}$  .

Finally, it remains to specify  $u_{i+\frac{1}{2},j}^{n+\frac{1}{2}}$  and  $v_{i,j+\frac{1}{2}}^{n+\frac{1}{2}}$  in equations (340) and the source terms denoted by "source  $\frac{n+\frac{1}{2}}{1,j}$ ." First, the velocities at the interfaces are obtained from

$$u_{i+\frac{1}{2},j}^{n+\frac{1}{2}} = \frac{u_{i,j}^{n+\frac{1}{2}} + u_{i+1,j}^{n+\frac{1}{2}}}{2}$$
(361a)

for  $i = 1, ..., N_x - 1$  and  $j = 1, ..., N_y$  while

$$u_{\frac{1}{2},j}^{n+\frac{1}{2}} = \frac{u_{\frac{1}{2},j}^{n+\frac{1}{2}} + u_{L}}{2}$$
$$u_{N_{x}+\frac{1}{2},j}^{n+\frac{1}{2}} = \frac{u_{N_{x},j}^{n+\frac{1}{2}} + u_{R}}{2}$$

and

$$v_{i,j+\frac{1}{2}}^{n+\frac{1}{2}} = \frac{v_{i,j}^{n+\frac{1}{2}} + v_{i,j+1}^{n+\frac{1}{2}}}{2}$$
(361b)

for  $i = 1, ..., N_x$  and  $j = 1, ..., N_y - 1$  while

$$v_{i,\frac{1}{2}}^{n+\frac{1}{2}} = \frac{v_{i,1}^{n+\frac{1}{2}} + v_{B}}{2}$$
$$v_{i,N_{y}+\frac{1}{2}}^{n+\frac{1}{2}} = \frac{v_{i,N_{y}}^{n+\frac{1}{2}} + v_{T}}{2}$$

As for the source terms they were defined earlier, Eqs. (321) through (329). Next, to get  $u_{i,j}^{n+\frac{1}{2}}$ ,  $v_{i,j}^{n+\frac{1}{2}}$ , and source  $\frac{n+\frac{1}{2}}{i,j}$ , we advance our system of conservation equations  $\frac{1}{2}$  time step using  $u_{i,j}^{n}$ ,  $v_{i,j}^{n}$ , source  $\frac{n}{i,j}$ , then

$$u_{i,j}^{n+\frac{1}{2}} | t^{n} t^{n} + \delta t = u_{i,j}^{n+1} | t^{n} t^{n} + \frac{\delta t}{2}$$

$$v_{i,j}^{n+\frac{1}{2}} | t^{n} t^{n} + \delta t = v_{i,j}^{n+1} | t^{n} t^{n} + \frac{\delta t}{2}$$
source 
$$\frac{n+\frac{1}{2}}{i,j} | t^{n} t^{n} + \delta t = \text{source } \frac{n+1}{i,j} | t^{n} t^{n} + \frac{\delta t}{2}.$$

# XVII. TWO-DIMENSIONAL TIME SPLITTING VERSUS FUL V TWO-DIMENSIONAL ALGORITHMS

Going back to Eq. (202),

$$A(\beta_{x},\beta_{y}) \approx e^{-i(\varepsilon_{x}\beta_{x} + \varepsilon_{y}\beta_{y})} = e^{-i\varepsilon_{x}\beta_{x}} e^{-i\varepsilon_{y}\beta_{y}} = A(\beta_{x})A(\beta_{y})$$
(362)

If  $p_{i,j}^n = e^{i\vec{k}\cdot\vec{x}}$ , where  $\vec{x} = (i\delta x, j\delta y)$ , the analytic solution of  $\frac{\partial 0}{\partial t} + \vec{u}\cdot\nabla p = 0$ , according to Eq. (362), yields

$$\rho_{i,j}^{n+1} = A(\beta_y)A(\beta_x)\rho_{i,j}^n$$
(363)

where  $\vec{u} = (u,v)$  is constant and the two operators  $A(\beta_x)$  and  $A(\beta_y)$  are commutable. Noticing that

$$o_{i,j}^{X} = A(\beta_{X}) p_{i,j}^{n}$$
(364a)

is the analytic solution of  $\frac{\partial \rho}{\partial t} + u \frac{\partial \rho}{\partial x} = 0$ , whereas

$$o_{i,j}^{n+1} = A(\beta_y) \rho_{i,j}^{x}$$
(364b)

is the analytic solution of  $\frac{\partial \rho}{\partial t} + v \frac{\partial \rho}{\partial y} = 0$  for an initial density  $\rho_{i,j}^{x}$ , equation (363) invokes time splitting as an exact solution for the linear PDE. If we derive a numerical scheme by expanding  $A(\beta_x, \beta_y)$  in terms of sin  $\beta_x$ , cos  $\beta_x$ , sin  $\beta_y$  and cos  $\beta_y$  such that both  $A(\beta_x, \beta_y)$  and its expansion agree up to a prescribed order of  $\beta_x$  and  $\beta_y$ , we obviously end with a time splitting scheme, in which each of the x and y operators agrees with  $A(\beta_x)$  and  $A(\beta_y)$  up to a prescribed order of  $\beta_x$  and  $\beta_y$ , respectively.

Alternatively, if a 1-D scheme is n - order in phase error and m - order in diffusion error, namely

$$|A| = 1 + O(\beta^{n})$$
(365)

and

$$\hat{\theta} = \hat{\theta}_{exact} + O(\beta^{n+1})$$
(365b)

where |A| and  $\theta$  are the amplitude and angle of the scheme transfer function A, i.e.,  $A = |A| e^{i\theta}$ , using a time-splitted version of the one-dimensional scheme to solve a two-dimensional, x-y problem, gives  $|A| e^{i\theta} = A \equiv A_x A_y$ =  $(|A_x|e^{i\theta}x)(|A_y|e^{i\theta}y)$ . Thus,

$$|\mathbf{A}| = |\mathbf{A}_{x}| \cdot |\mathbf{A}_{y}| = (1 + o(\beta_{x}^{m}))(1 + o(\beta_{y}^{m})) = 1 + o(\beta_{x}^{m}) + o(\beta_{y}^{m})$$
(366a)

and

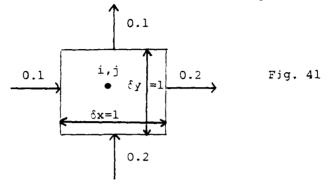
$$\hat{\theta} = \hat{\theta}_{x} + \hat{\theta}_{y} = [\hat{\theta}_{x \text{ exact}} + O(\beta_{x}^{n+1})] + [\hat{\theta}_{y \text{ exact}} + O(\beta_{y}^{n+1})]$$

$$= \hat{\theta}_{\text{exact}} + O(\beta_{x}^{n+1}) + O(\beta_{y}^{n+1})$$
(366b)

showing the two-dimensional scheme to be of the same order as the onedimensional one. Moreover, the errors in both |A| and  $\vartheta$  are free from mixed frequencies, such as  $O(\beta_x^{n_1}\beta_y^{n_2})$  where  $n_1 + n_2 = m \text{ or } n + 1$ .

Although time-splitting appears to be the perfect solution, physically unacceptable results are produced when dealing with incompressible or nearly incompressible flow fields, or when a differential identity, such as divergence free property or irrotationality, is to be strictly enforced. Moreover, because the antidiffusion fluxes are corrected in each direction independently of the other, unnecessary "clipping" occurs. Namely, the flux corrector may cancel a flux that would produce a ripple in one direction, which actually is safe in twodimensions due to the growth or decay of the adjacent cells in the other direction.

Going back to the problems arising in incompressible flows, let's consider a case where  $\vec{U} = \vec{U}(x,y)$ , independent of time, satisfying  $7 \cdot \vec{U} = 0$ . For simplicity assume  $u = u_0 + Cx$  and  $v = v_0 - Cy$ . Figure 41 illustrates the velocities at the interfaces of a cell, when  $\delta x = \delta y = 1$ , C = 0.1.



Using a simple-transport scheme with time splitting

$$\Psi_{i,j} \rho_{i,j}^{X} = \Psi_{i,j} \rho_{i,j}^{0} - (u_{i+\frac{1}{2},j} \rho_{i+\frac{1}{2},j}^{0} - u_{i-\frac{1}{2},j} \rho_{i-\frac{1}{2},j}^{0}) \delta y \delta t$$
(367a)

$$\Psi_{i,j} \rho_{i,j}^{1} = \Psi_{i,j} \rho_{i,j}^{x} - (v_{i,j+\frac{1}{2}} \rho_{i,j+\frac{1}{2}}^{x} - v_{i,j-\frac{1}{2}} \rho_{i,j-\frac{1}{2}}^{x}) \delta x \delta t$$
(367b)

where 0,1 stands for t = 0,  $\delta t$ , respectively. Assuming a uniform initial density  $\delta^{\circ} = 1$ , and  $\delta t = 1$ , Eq. (367a) gives  $(1) \cdot (\delta_{i,j}^{x}) = (1) \cdot (1) - ((0.2) \cdot (1))$ -  $(0.1) \cdot (1) \cdot (1)$  yielding  $\delta_{i,j} = 0.9$ . Since u = u(x), v = v(y),  $\delta_{i,j}^{x} = 0.9$ for all j's and since u,v are linear, it is also true for all i's. Then, from Eq. (367b), we obtain  $(1) \cdot (\delta_{i,j}^{1}) = (1) \cdot (0.9) - ((0.1) \cdot (0.9) - (0.2) \cdot (0.9)) \cdot$  $(1) \cdot (1)$  yielding  $\delta_{i,j}^{1} = 0.99$ . After n time steps, it is obvious that  $\delta_{i,j}^{n} = (0.99)^{n}$  for all i and j. Generally,  $\delta_{i,j}^{n} = \delta_{i,j}^{\circ} (1-C^{2})^{n}$ . In other words, the density keeps on uniformly distributed but decreases with time continuously. An equivalent fully two-dimensional scheme would be

which gives  $\rho_{i,j}^{I} = 1$ , i.e. conserves the mass.

The discrepancy obviously lies in the assumption of  $\vec{U}$  = const while  $\rho$  is varying when deriving Eq. (362). In terms of transfer functions, the scheme of Eqs. (367) is written as  $A = (1 - \varepsilon_x t_x)(1 - \varepsilon_y t_y)$ whereas that of Eq. (368) takes the form  $A = 1 - \varepsilon_x t_x - \varepsilon_y t_y$ .

The difference is obviously in the term " $\varepsilon_{x} \varepsilon_{y} t t$ " which as will be shown later is essential for high order diffusion. In the next section, we try to cast a time-splitted scheme into a fully two-dimensional form. A detailed explanation of the problems involved is given.

# FULLY TWO-DIMENSIONAL VERSIONS OF TIME-SPLITTED SCHEMES

Going back to the fourth order phase and diffusion scheme

$$A = (1 - \varepsilon t)(1 - \mu d) + \nu d$$
(370)
where  $\nu = \frac{1}{6} + \frac{\varepsilon^2}{3}$  and  $\mu = \frac{1 - \varepsilon^2}{6}$ . The two-dimensional, splitted version
of Eq. (370)

$$\mathbf{A} = \left[ (1 - \varepsilon_{\mathbf{x}} \mathbf{t}_{\mathbf{x}}) (1 - \mu_{\mathbf{x}} \mathbf{d}_{\mathbf{x}}) + \nu_{\mathbf{x}} \mathbf{d}_{\mathbf{x}} \right] \cdot \left[ (1 - \varepsilon_{\mathbf{y}} \mathbf{t}_{\mathbf{y}}) (1 - \mu_{\mathbf{y}} \mathbf{d}_{\mathbf{y}}) + \nu_{\mathbf{y}} \mathbf{d}_{\mathbf{y}} \right] \quad (371a)$$

or

$$A = (1 - \varepsilon_{\mathbf{x}} \mathbf{t}_{\mathbf{x}} + \upsilon_{\mathbf{x}} \mathbf{d}_{\mathbf{x}}) (1 - \varepsilon_{\mathbf{y}} \mathbf{t}_{\mathbf{y}} + \upsilon_{\mathbf{y}} \mathbf{d}_{\mathbf{y}}) - \mu_{\mathbf{x}} \mathbf{d}_{\mathbf{x}} (1 - \varepsilon_{\mathbf{x}} \mathbf{t}_{\mathbf{x}}) (1 - \varepsilon_{\mathbf{y}} \mathbf{t}_{\mathbf{y}} + \upsilon_{\mathbf{y}} \mathbf{d}_{\mathbf{y}})$$
$$- \mu_{\mathbf{y}} \mathbf{d}_{\mathbf{y}} (1 - \varepsilon_{\mathbf{y}} \mathbf{t}_{\mathbf{y}}) (1 - \varepsilon_{\mathbf{x}} \mathbf{t}_{\mathbf{x}} + \upsilon_{\mathbf{x}} \mathbf{d}_{\mathbf{x}}) - \mu_{\mathbf{x}} \mu_{\mathbf{y}} \mathbf{d}_{\mathbf{x}} \mathbf{d}_{\mathbf{y}} (1 - \varepsilon_{\mathbf{x}} \mathbf{t}_{\mathbf{x}}) (1 - \varepsilon_{\mathbf{y}} \mathbf{t}_{\mathbf{y}})$$
(371b)

can be written as

$$\mathbf{A}^{\mathrm{TD}} = 1 - \varepsilon_{\mathbf{x}} \mathbf{t}_{\mathbf{x}} \left(1 - \frac{\varepsilon_{\mathbf{y}} \mathbf{t}_{\mathbf{y}}}{2} + \frac{\nu_{\mathbf{y}} \mathbf{d}_{\mathbf{y}}}{2}\right) - \varepsilon_{\mathbf{y}} \mathbf{t}_{\mathbf{y}} \left(1 - \frac{\varepsilon_{\mathbf{x}} \mathbf{t}_{\mathbf{x}}}{2} + \frac{\nu_{\mathbf{x}} \mathbf{d}_{\mathbf{x}}}{2}\right) + \nu_{\mathbf{x}} \mathbf{d}_{\mathbf{x}} \left(1 - \frac{\varepsilon_{\mathbf{y}} \mathbf{t}_{\mathbf{y}}}{2} + \frac{\nu_{\mathbf{y}} \mathbf{d}_{\mathbf{y}}}{2}\right) + \nu_{\mathbf{y}} \mathbf{d}_{\mathbf{y}} \left(1 - \frac{\varepsilon_{\mathbf{x}} \mathbf{t}_{\mathbf{x}}}{2} + \frac{\nu_{\mathbf{x}} \mathbf{d}_{\mathbf{x}}}{2}\right)$$
(372a)

which is  $\geq 0$  for  $|\varepsilon_x|, |\varepsilon_y| \leq \frac{1}{2}$ , therefore ensuring positivity of  $\rho^{\text{TD}}$  if  $\rho^n \geq 0$ . Then,

$$\mathbf{A} = \mathbf{A}^{\text{TD}} - \mu_{\mathbf{x}} \mathbf{d}_{\mathbf{x}}^{\star} (1 - \varepsilon_{\mathbf{x}} \mathbf{t}_{\mathbf{x}}) [1 - \varepsilon_{\mathbf{y}} \mathbf{t}_{\mathbf{y}} + \nu_{\mathbf{y}} \mathbf{d}_{\mathbf{y}} - \frac{1}{2} \mu_{\mathbf{y}} \mathbf{d}_{\mathbf{y}} (1 - \varepsilon_{\mathbf{y}} \mathbf{t}_{\mathbf{y}})]$$
$$- \mu_{\mathbf{y}} \mathbf{d}_{\mathbf{y}}^{\star} (1 - \varepsilon_{\mathbf{y}} \mathbf{t}_{\mathbf{y}}) [1 - \varepsilon_{\mathbf{x}} \mathbf{t}_{\mathbf{x}} + \nu_{\mathbf{x}} \mathbf{d}_{\mathbf{x}} - \frac{1}{2} \mu_{\mathbf{x}} \mathbf{d}_{\mathbf{x}} (1 - \varepsilon_{\mathbf{x}} \mathbf{t}_{\mathbf{x}})]$$
(372b)

where the asterisks denote the operators which fluxes are to be corrected. This will allow us to correct the x and y antidiffusion fluxes simultaneously, thus avoiding unnecessary clipping. But that does not solve the problems associated with divergence free flow fields, for example, because of the term " $\varepsilon_x \varepsilon_t t_y$ ." Moreover, we notice that the form of Eq. (372) is in no way unique.

Although Eqs. (366) show in a clear simple way that  $A = A_x A_y$  is fourth order in phase and diffusion, let us analyze it using Eqs. (246) to (248), Eqs. (260)-(262) with Eqs. (241)-(244). The purpose is to determine which terms are responsible for the fourth order diffusion, fourth order phase error, positivity, stability, and so on. We notice that A = 0, A = 0, making Eqs. (241)-(244) valid.

Differentiating Eq. (371a), we get

$$\begin{aligned} \mathbf{t}_{\mathbf{X}} \\ \mathbf{A}^{\mathbf{Y}} &= -\varepsilon_{\mathbf{X}} \begin{pmatrix} \mathbf{1} - \mu_{\mathbf{X}} \mathbf{d}_{\mathbf{X}} \end{pmatrix} \mathbf{A} \\ \mathbf{Y} & \mathbf{Y} & \mathbf{Y} & \mathbf{X} \end{aligned}$$
(374)

$$\mathbf{A}_{\mathbf{Y}}^{\mathbf{X}} = \begin{bmatrix} (\mathbf{v}_{\mathbf{X}}^{\mathbf{-}} \boldsymbol{\mu}_{\mathbf{X}}^{\mathbf{+}}) + \boldsymbol{\varepsilon}_{\mathbf{X}} \boldsymbol{\mu}_{\mathbf{X}}^{\mathbf{+}} \mathbf{\lambda}_{\mathbf{X}}^{\mathbf{+}} \mathbf{\lambda}_{\mathbf{X}$$

$$\mathbf{A}_{\mathbf{Y}}^{\mathbf{t}} \mathbf{A}_{\mathbf{Y}}^{\mathbf{t}} = - \varepsilon_{\mathbf{x}} (1 - \mu_{\mathbf{x}} \mathbf{d}_{\mathbf{x}}) [(\nu_{\mathbf{y}} - \mu_{\mathbf{y}}) + \varepsilon_{\mathbf{y}} \mu_{\mathbf{y}} \mathbf{t}_{\mathbf{x}}^{\mathbf{t}}]$$

$$\mathbf{Y}_{\mathbf{Y}}^{\mathbf{t}} \mathbf{Y}_{\mathbf{Y}}^{\mathbf{t}} \mathbf{X}_{\mathbf{x}}^{\mathbf{t}} \mathbf{X}_{\mathbf{x}}^{\mathbf{t}$$

$$A^{x y} = \varepsilon_{x} \varepsilon_{y} (1 - \mu_{x} d_{x}) (1 - \mu_{y} d_{y})$$
(378a)

$$A^{d} \mathbf{x}^{d} \mathbf{x}^{d} = [(v_{\mathbf{x}} - u_{\mathbf{x}}) + \varepsilon_{\mathbf{x}} u_{\mathbf{x}} t_{\mathbf{x}}][(v_{\mathbf{y}} - u_{\mathbf{y}}) + \varepsilon_{\mathbf{y}} u_{\mathbf{y}} t_{\mathbf{y}}]$$
(378b)

At  $\beta_x = \beta_y = 0$ ,  $t_x = t_y = 0$ , and  $d_x = d_y = 0$ , thus  $A_x = A_y = 1$ , yielding

$$\begin{array}{c}
t_{x} \\
A_{y} \\
o \\
\end{array} = - \varepsilon_{x} \\
y
\end{array}$$
(379)

$$\begin{array}{c} \mathbf{A}_{\mathbf{X}}^{T} \\ \mathbf{A}_{\mathbf{O}}^{T} = \mathbf{v} - \mathbf{\mu}_{\mathbf{X}} \\ \mathbf{O} & \mathbf{Y} & \mathbf{Y} \end{array}$$
(380)

$$\mathbf{A}_{o}^{\mathbf{Y}} = \mathbf{E}_{\mathbf{Y}}^{\mathbf{U}} \mathbf{Y}_{\mathbf{Y}}$$
(381)

$$\mathbf{A}_{o}^{\mathbf{y}} = - \varepsilon_{\mathbf{x}} \begin{pmatrix} v & - \mu \\ \mathbf{y} & \mathbf{x} \end{pmatrix}$$
(382)

$$\mathbf{A}_{o}^{\mathbf{d}} \mathbf{A}_{o}^{\mathbf{d}} = (\mathbf{v}_{\mathbf{x}} - \mathbf{\mu}_{\mathbf{x}})(\mathbf{v}_{\mathbf{y}} - \mathbf{\mu}_{\mathbf{y}})$$
(383b)

Substituting into Eqs. (246) and (248), we get

$$(\log A)_{0}^{X} = -i\epsilon_{X} \qquad (384)$$

$$(\log A)_{0}^{XXX} = i\epsilon_{X} [1 - 6(v_{X} - \mu_{X})] - i[6\epsilon_{X}\mu_{X} - 2\epsilon_{X}^{5}]$$

$$= 6i\epsilon_{X} (\frac{1}{6} + \frac{\epsilon_{X}^{2}}{3} - v_{X}) \qquad (385)$$

showing  $A_x A_y$  to be fourth order in phase error, but more importantly, that the cross terms of Eqs. (382) and (393a), which do not appear in onedimension, are essential to the fourth order phase. More specifically, these cross terms reduce the dependence of phase error on v and u to dependence on v only, leaving  $\mu$  free to be adjusted for a high order diffusion.

 $d_{x y} d_{y}$ A<sub>o</sub> in Eq. (383b) is not used in either (384) or (385) and therefore can take any value without affecting the phase error.

Now we can construct the simplest fourth order phase error scheme. Such a scheme has to satisfy Eqs. (379) to (382) plus Eq. (383a) giving,

$$A = (1 - \varepsilon_{x} t_{x})(1 - \varepsilon_{y} t_{y}) + (v_{x} - \mu_{x})d_{x} + (v_{y} - \mu_{y})dy + \varepsilon_{x} t_{x} u_{x} d_{x}$$
$$+ \varepsilon_{y} t_{y} \mu_{y} d_{y} - \varepsilon_{x} t_{x} (v_{y} - \mu_{y})d_{y} - \varepsilon_{y} t_{y} (v_{x} - \mu_{x})d_{x}$$
(386)

where the integration constant was selected as unity to satisfy consistency, i.e.,  $A(\beta_x, \beta_y = 0) = 1$ . Eq. (386) can be written as

$$A = (1 - \varepsilon_{x} t_{x})(1 - \varepsilon_{y} t_{y}) + v_{x} d_{x}(1 - \varepsilon_{y} t_{y}) + v_{y} d_{y}(1 - \varepsilon_{x} t_{x})$$
$$- \mu_{x} d_{x}(1 - \varepsilon_{x} t_{x} - \varepsilon_{y} t_{y}) - \mu_{y} d_{y}(1 - \varepsilon_{x} t_{x} - \varepsilon_{y} t_{y})$$
(387)

 $d_x d_y$ Since  $A_0^{-x-y}$  does not affect the phase error order, we can assign a value for it that would ensure positivity. We add to the terms of Eq. (387) " $v_x v_y d_x d_y$ ," yielding

$$A = (1 - \varepsilon_{x}t_{x} + v_{x}d_{x})(1 - \varepsilon_{y}t_{y} + v_{y}d_{y}) - \mu_{x}d_{x}(1 - \varepsilon_{x}t_{x} - \varepsilon_{y}t_{y})$$
$$- \mu_{y}d_{y}(1 - \varepsilon_{x}t_{x} - \varepsilon_{y}t_{y})$$
(388)

Now, substituting Eqs. (379) to (383) into Eqs. (242) and (243), we get

$$A_{O}^{X} = -i\varepsilon \tag{389}$$

$$A_{O}^{XX} = -2(v_{X} - \mu_{X})$$
(390a)

$$A_{O}^{XY} = -\varepsilon_{X}\varepsilon_{Y}$$
(390b)

which when substituted into Eqs. (261), yield

$$(|\mathbf{A}|^2)_{0}^{\mathbf{XX}} = 2[-2(\mathbf{v} - \mathbf{\mu}) + \varepsilon_{\mathbf{X}}^2] = 0$$
(391a)

$$(|\mathbf{A}|^2)_{\mathbf{o}}^{\mathbf{x}\mathbf{y}} = 2[-\varepsilon_{\mathbf{x}}\varepsilon_{\mathbf{y}} + \varepsilon_{\mathbf{x}}] = 0$$
(391b)

showing  $A_{x}A_{y}$  to be fourth order in diffusion error.

Notice that  $A_0^{t_x t_y} = \varepsilon_x \varepsilon_y$ , is essential for fourth order diffusion (already satisfied by the scheme of Eq. (388)).

The simplest fourth order (phase and diffusion error) positive scheme is therefore that of Eq. (388). It is, however, unstable. For instance,

$$\mathbf{A}_{\mathbf{R}} = \mathbf{1} + (\mathbf{v}_{\mathbf{x}} - \boldsymbol{\mu}_{\mathbf{x}})\mathbf{d}_{\mathbf{x}} + (\mathbf{v}_{\mathbf{y}} - \boldsymbol{\mu}_{\mathbf{y}})\mathbf{d}_{\mathbf{y}} + \mathbf{v}_{\mathbf{x}}\mathbf{v}\mathbf{d}_{\mathbf{x}}\mathbf{d}_{\mathbf{y}} + \varepsilon_{\mathbf{x}}\varepsilon_{\mathbf{y}}\mathbf{t}_{\mathbf{x}}\mathbf{d}_{\mathbf{y}}$$
(392a)

while

$$A_{I} = -\epsilon_{x} t_{x} [1 - \mu_{x} d_{x} + (\nu_{y} - \mu_{y}) d_{y}] - \epsilon_{y} t_{y} [1 - \mu_{y} d_{y} + (\nu_{x} - \mu_{x}) d_{x}] (392b)$$
  
At  $\epsilon_{x} = \epsilon_{y} = \frac{1}{2}$  and  $\beta_{x} = \beta_{y} = \pi/2$ ,  $d_{x} = d_{y} = -2$ , and  $t_{x} = t_{y} = i$ , yielding  
 $A_{R} = 1 - \frac{1}{4} - \frac{1}{4} + \frac{1}{4} - \frac{1}{4} = \frac{1}{2}$  (393a)

$$A_{I} = -\frac{1}{2}\left[1 + \frac{1}{4} - \frac{1}{4}\right] - \frac{1}{2}\left[1 + \frac{1}{4} - \frac{1}{4}\right] = -1$$
(393b)

Since we know that A of Eq. (372) is stable, let's try to approach it in steps. First, we try

$$A = (1 - \varepsilon_{x} t_{x} + v_{x} d_{x})(1 - \varepsilon_{y} t_{y} + v_{y} d_{y}) - \mu_{x} d_{x}(1 - \varepsilon_{x} t_{x})(1 - \varepsilon_{y} t_{y})$$
$$- \mu_{y} d_{y}(1 - \varepsilon_{y} t_{y})(1 - \varepsilon_{x} t_{x})$$
(394)

thus adding "-( $\mu_x d_x + \mu_y d_y$ ) ( $\epsilon_x \epsilon_y t_x t_y$ )" to the real part, becoming then

$$A_{R} = 1/2 - 1/8 = 3/8$$
(395)

still unstable. Next, we try

$$\mathbf{A} = (\mathbf{1} - \varepsilon_{\mathbf{x}} \mathbf{t}_{\mathbf{x}} + \mathbf{v}_{\mathbf{x}} \mathbf{d}_{\mathbf{x}}) (\mathbf{1} - \varepsilon_{\mathbf{y}} \mathbf{t}_{\mathbf{y}} + \mathbf{v}_{\mathbf{y}} \mathbf{d}_{\mathbf{y}}) - \mu_{\mathbf{x}} \mathbf{d}_{\mathbf{x}} (\mathbf{1} - \varepsilon_{\mathbf{x}} \mathbf{t}_{\mathbf{x}}) (\mathbf{1} - \varepsilon_{\mathbf{y}} \mathbf{t}_{\mathbf{y}} + \mathbf{v}_{\mathbf{y}} \mathbf{d}_{\mathbf{y}})$$
$$- \mu_{\mathbf{y}} \mathbf{d}_{\mathbf{y}} (\mathbf{1} - \varepsilon_{\mathbf{y}} \mathbf{t}_{\mathbf{y}}) (\mathbf{1} - \varepsilon_{\mathbf{x}} \mathbf{t}_{\mathbf{x}} + \mathbf{v}_{\mathbf{x}} \mathbf{d}_{\mathbf{x}})$$
(396)

This will add "- $(\mu_x \nu_y + \mu_y \nu_x) d_x d_y$ " to the real part and " $(\epsilon_x t_x \mu_x \nu_y)$ +  $\epsilon_y t_y \mu_y \nu_x) d_x d_y$ " to the imaginary one. We get then

$$A_{R} = \frac{3}{8} - \frac{1}{4} = \frac{1}{8}$$
(397a)

$$A_{I} = -1 + \frac{1}{8} = -\frac{7}{8}$$
(397b)

whence  $|A|^2 = (\frac{7}{8})^2 + (\frac{1}{8})^2 = \frac{50}{64} < 1$ , showing Eq. (396) to be too stable at  $\beta_x = \beta_y = \frac{\pi}{2}$ . Moreover, it is not phoenical;  $A \neq 1$  at  $\varepsilon_x = \varepsilon_y = 0$ . These two effects can be avoided by picking

$$\mathbf{A} = (\mathbf{l} - \varepsilon_{\mathbf{x}} \mathbf{t}_{\mathbf{x}} + \nu_{\mathbf{x}} \mathbf{d}_{\mathbf{x}}) (\mathbf{l} - \varepsilon_{\mathbf{y}} \mathbf{t}_{\mathbf{y}} + \nu_{\mathbf{y}} \mathbf{d}_{\mathbf{y}}) - \mu_{\mathbf{x}} \mathbf{d}_{\mathbf{x}} (\mathbf{l} - \varepsilon_{\mathbf{x}} \mathbf{t}_{\mathbf{x}}) (\mathbf{l} - \varepsilon_{\mathbf{y}} \mathbf{t}_{\mathbf{y}} + \frac{1}{2} \nu_{\mathbf{y}} \mathbf{d}_{\mathbf{y}})$$
$$- \mu_{\mathbf{y}} \mathbf{d}_{\mathbf{y}} (\mathbf{l} - \varepsilon_{\mathbf{y}} \mathbf{t}_{\mathbf{y}}) (\mathbf{l} - \varepsilon_{\mathbf{x}} \mathbf{t}_{\mathbf{x}} + \frac{1}{2} \nu_{\mathbf{x}} \mathbf{d}_{\mathbf{x}})$$
(398)

yielding

$$A_{R} = \frac{3}{8} - \frac{1}{2} \times \frac{1}{4} = \frac{1}{4}$$
(399a)

$$A_{I} = -1 + \frac{1}{2} \times \frac{1}{8} = -\frac{15}{16}$$
(399b)

whence  $|A|^2 = (\frac{15}{16})^2 + (\frac{1}{4})^2 = \frac{241}{256} < 1$ , closer to 1, therefore promising a smaller net diffusion and phoenical since A = 1 at  $\varepsilon_x = \varepsilon_y = 0$ .

Noticing that the added terms to Eq. (388) are triple operators  $(t_x t_y d_x, t_x t_y d_y, t_x d_y d_y)$  they have no effect on  $(\log A)_0^{'''}$ . Eq. (398) is still fourth order in phase error. Furthermore, upon expanding  $|A|^2$ , we get

$$|\mathbf{A}|^{2} = 1 + \frac{1}{12} \{ \epsilon_{\mathbf{x}}^{2} (1 - \epsilon_{\mathbf{x}}^{2}) \beta_{\mathbf{x}}^{4} + [\epsilon_{\mathbf{x}}^{2} (1 - \epsilon_{\mathbf{y}}^{2}) + \epsilon_{\mathbf{y}}^{2} (1 - \epsilon_{\mathbf{x}}^{2}) \beta_{\mathbf{x}}^{2} \beta_{\mathbf{y}}^{2} + \epsilon_{\mathbf{y}}^{2} (1 - \epsilon_{\mathbf{y}}^{2}) \beta_{\mathbf{y}}^{4} \} + \dots$$
(400)

showing diffusion error to be of fourth order. The scheme is, however, slightly unstable near  $\beta_x = \beta_y = 0$ , since the fourth order coefficient is

positive. We notice also the presence of a term  $"\beta_x^2 \beta_y^2"$  in Eq. (400) (also in the phase error expansion), which does not show in the expansion of Eq. (372) (according to Eq. (366), making the scheme of Eq. (398) slightly inferior to that of Eq. (372).

Upon comparing Eq. (398) to (372), it is obvious that Eq. (372) cannot be much simplified; at least without sacrificing stability or phoenicity. Whichever we use, the  $n^{\circ}$  of operations involved in evaluating  $p^{n+1}$  is much larger than that in the fully two-dimensional scheme of Eq. (226e). Moreover, the  $n^{\circ}$  of two-dimensional arrays required to store the intermediate values is enormous.

Since the only advantage of Eqs. (372), the fully two-dimensional version of the time-splitted scheme of Eq. (371b) is the reduced clipping associated with the flux limiter, we conclude that time splitting is the sensible answer. We abandon, therefore, trials to cast the time-splitted scheme in fully two-dimensional versions.

## XVIII. IMPROVING DIFFUSION ERROR OF THE FULLY TWO-DIMENSIONAL SCHEME

Now that we have classified the terms responsible for the fourth order phase, diffusion, etc., in the time-splitted scheme, let's go back to the fully two-dimensional scheme and study the terms preventing us from reaching a fourth order diffusion error. As explained earlier, the term " $\varepsilon_x \varepsilon_y t_x t_y$ " is essential to reduce the dependence of the phase error to one on v alone, thus leaving  $\mu$  free to be adjusted for a high order diffusion. A closer look reveals, however, that the above conclusion is an indirect one. The direct conclusion is that " $\varepsilon_{1}\varepsilon_{2}t_{3}t_{4}$ " is needed to cancel "  $\varepsilon_{x} \stackrel{\beta}{}_{x} \varepsilon_{y} \stackrel{\beta}{}_{y}$ " resulting from squaring the imaginary part. Specifically, any scheme has to incorporate the combination ( $\varepsilon_{x} t + \varepsilon_{y} t$ ) leading to  $i(\varepsilon_x \sin \beta_x + \varepsilon_y \sin \beta_y)$  which is approximated by  $i(\varepsilon_x \beta_x + \varepsilon_y \beta_y)$ . To cancel it, a term including sin  $\beta_x$  sin  $\beta_y$  is needed. Besides  $t_x t_y$ , the above term can also result from cos ( $\beta_{\mathbf{x}}\pm\beta_{\mathbf{y}}$ ), i.e. diagonal diffusion  $(p_{i+1,j\pm 1}^n - 2p_{i,j}^n + p_{i-1,j\mp 1}^n)$ . Admitting diagonal terms is outside the scope of this article and is left out to an upcoming one. However, we emphasize that there is a stability problem caused by the imaginary part  $iA_{I} = -[\varepsilon_{x}t_{x}(1 - \mu_{x}d_{x}) + \varepsilon_{y}t_{y}(1 - \mu_{y}d_{y})]$  which amplitude is already larger than unity for  $\varepsilon_x = \varepsilon_y = \frac{1}{2}$ ,  $\beta_x = \beta_y = \frac{\pi}{2}$  unless  $\mu_x = \mu_y = 0$ there, in which case we have a large residual diffusion. Adding just a diagonal diffusion can't help, since it only adds to the real part.

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FIGURES

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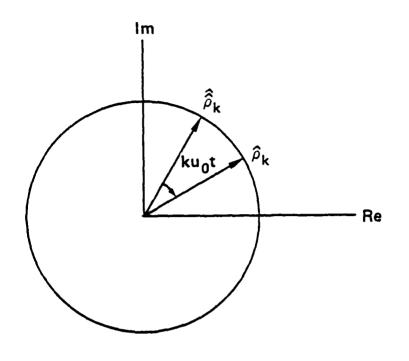
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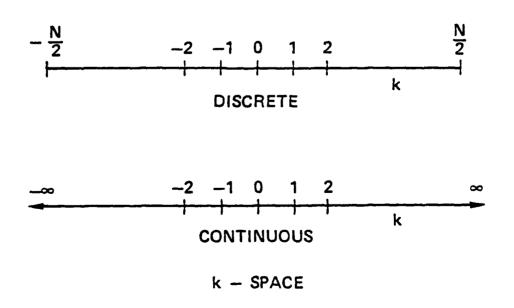
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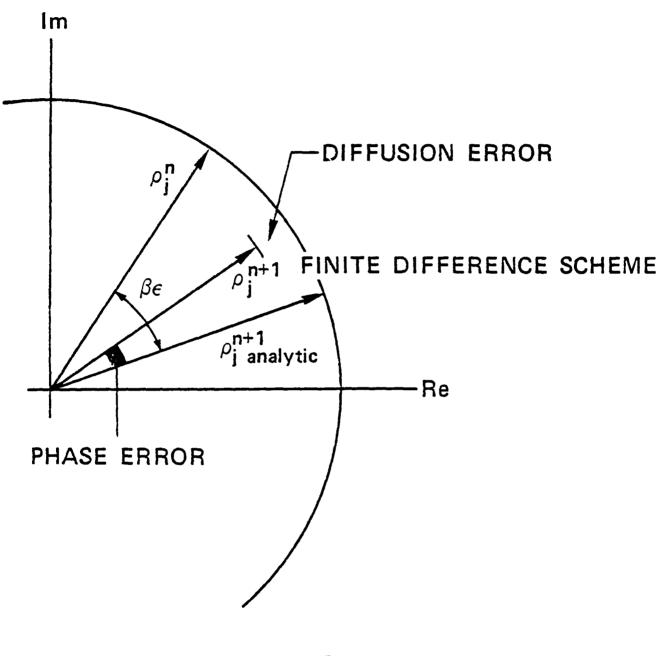




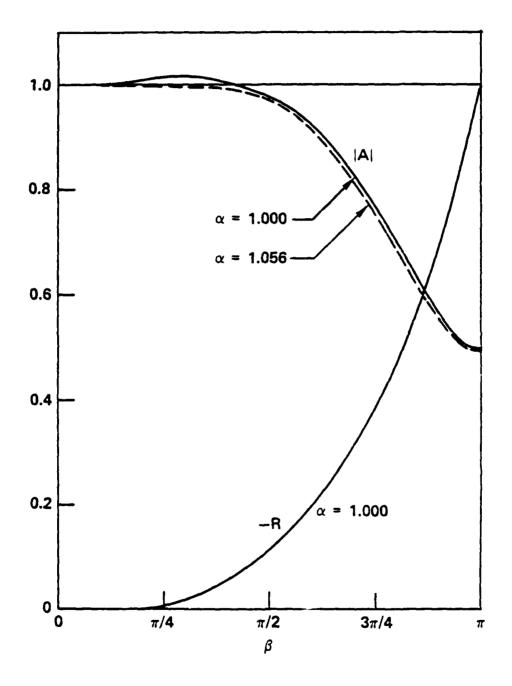


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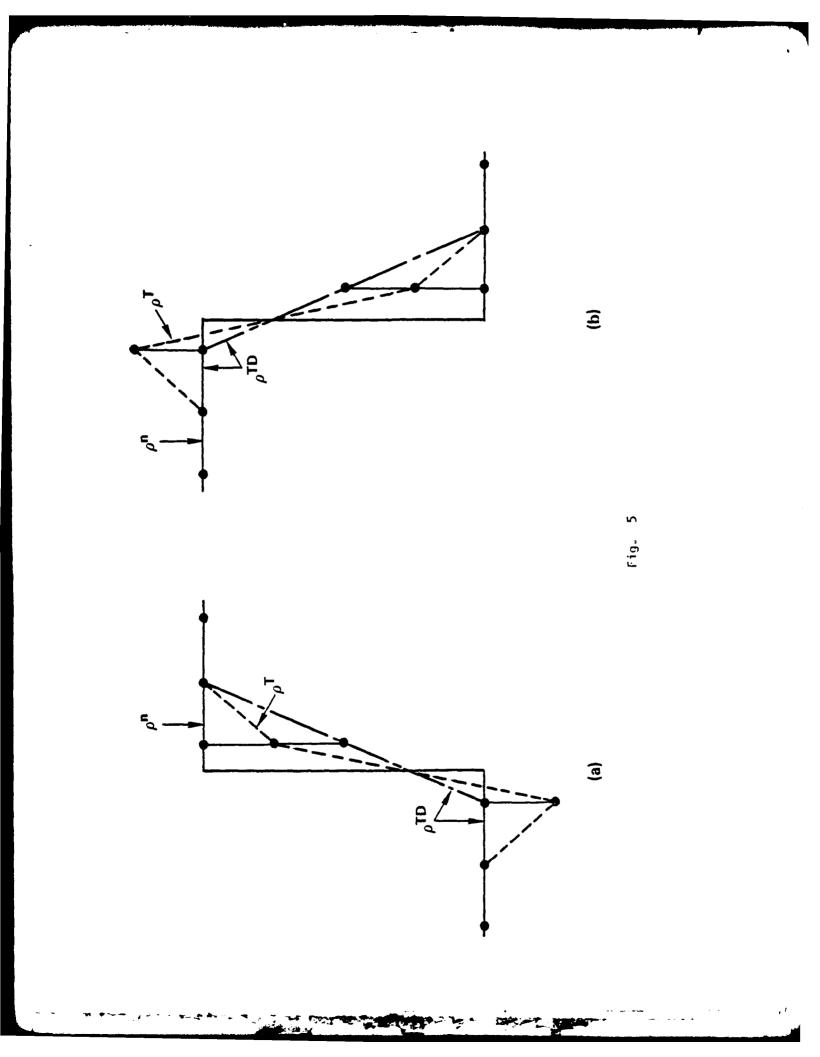
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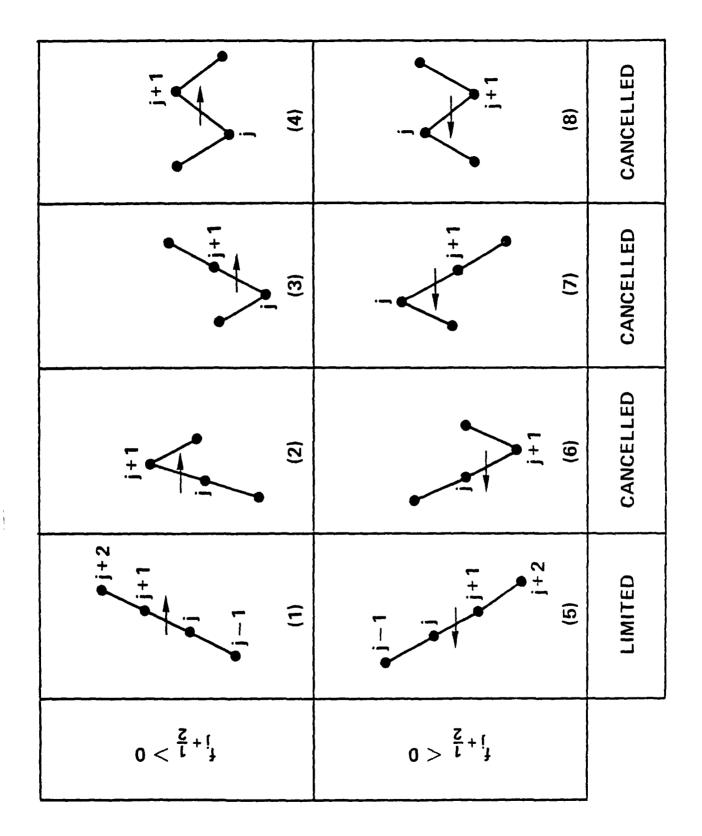


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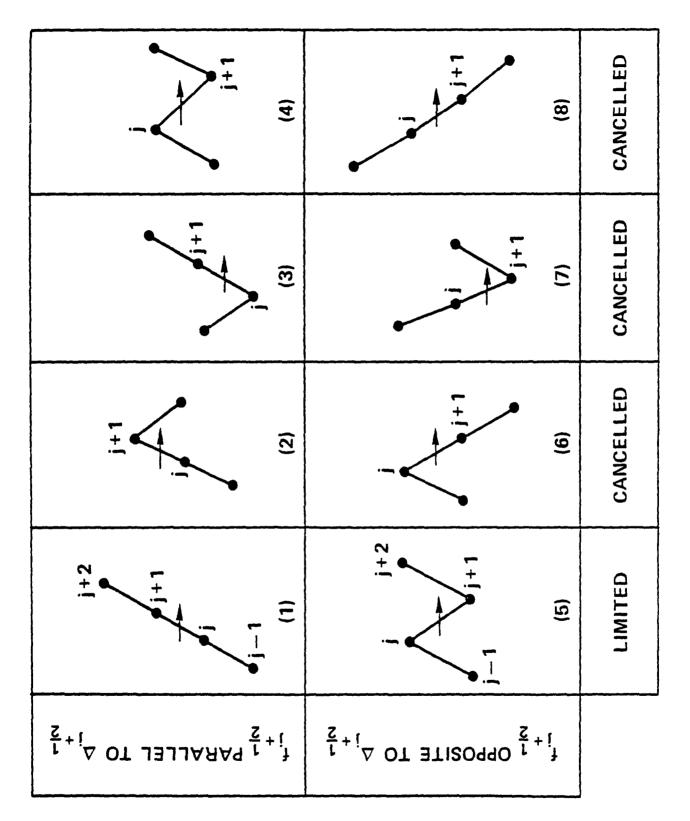


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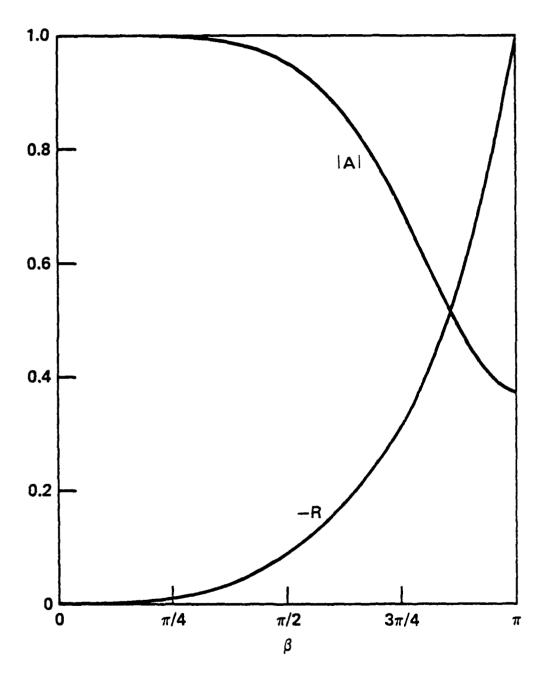


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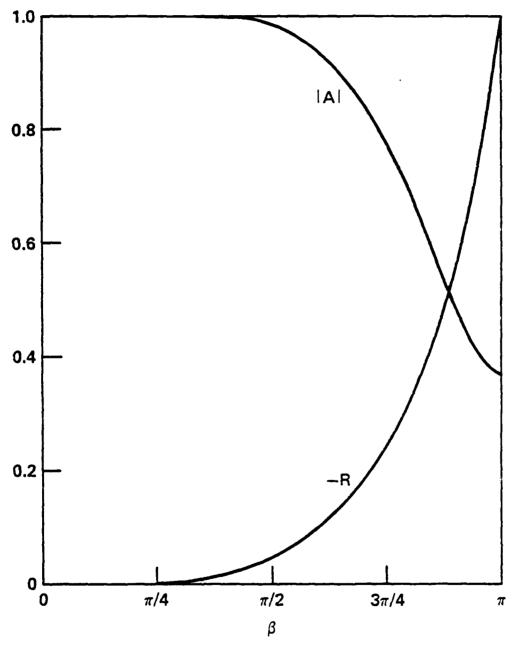
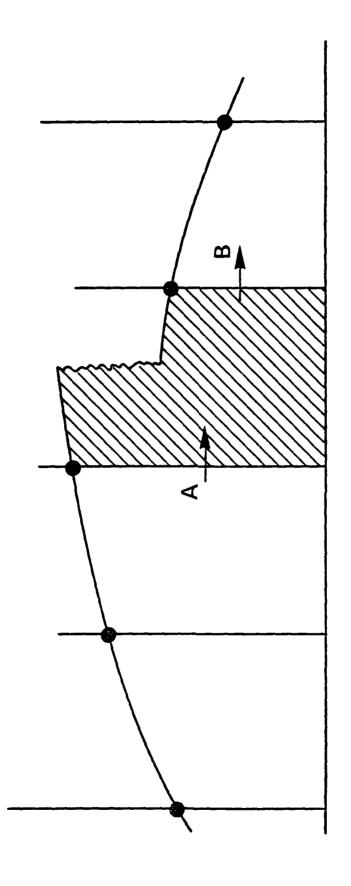


Fig. 9



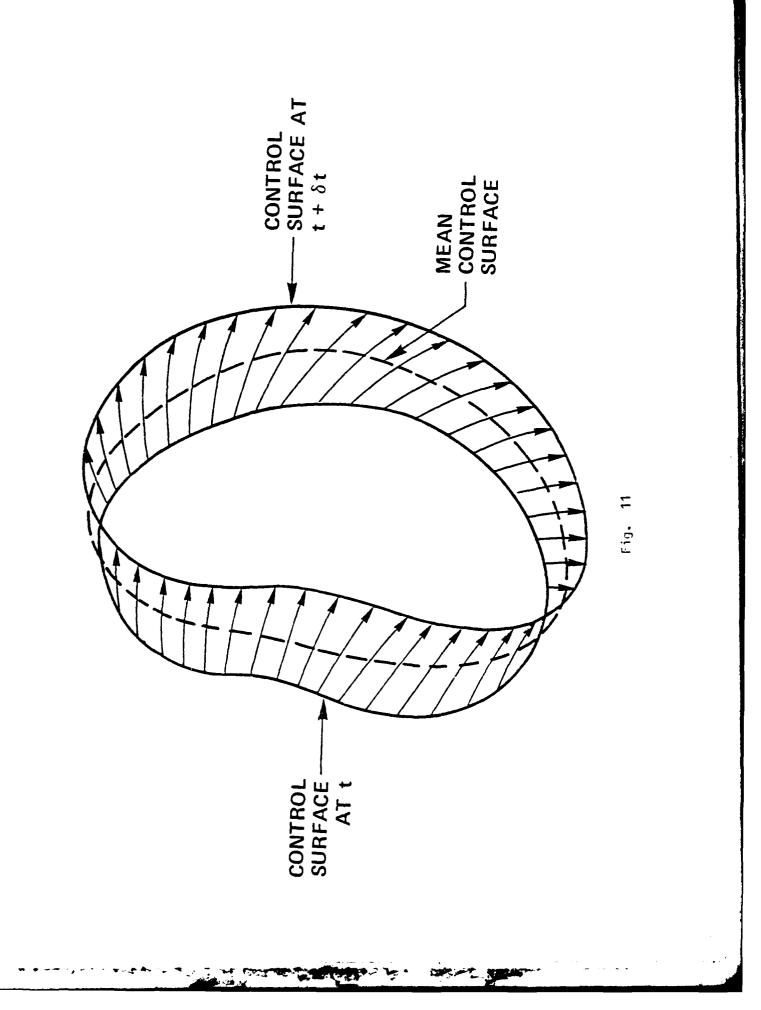
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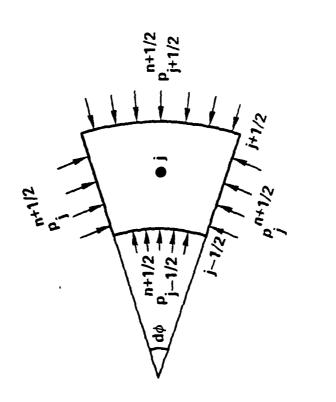
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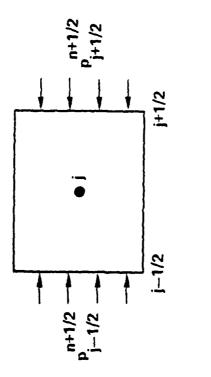


Fig. 13

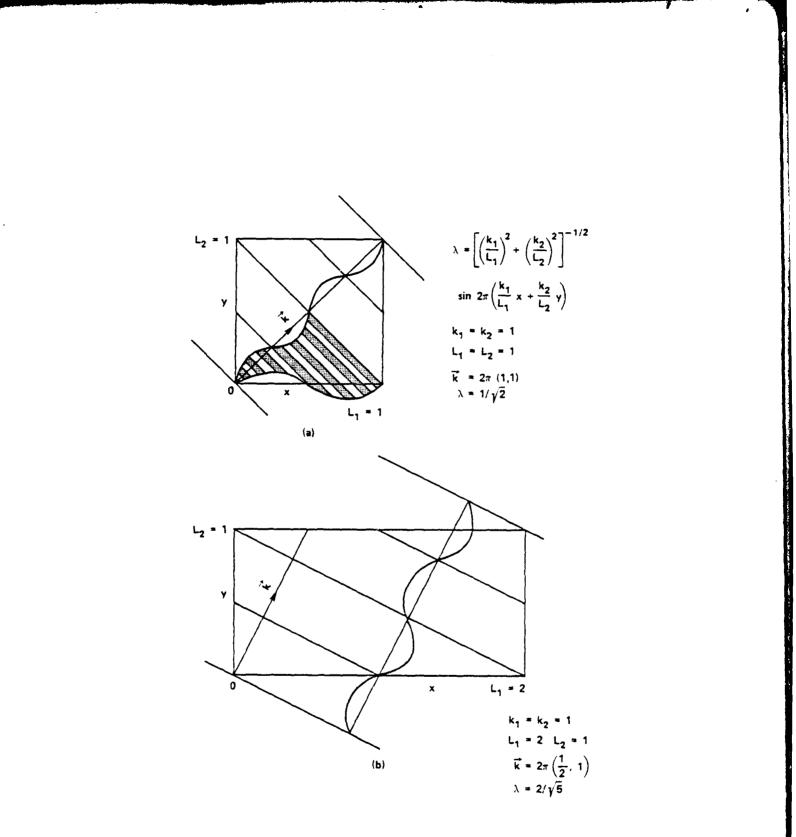
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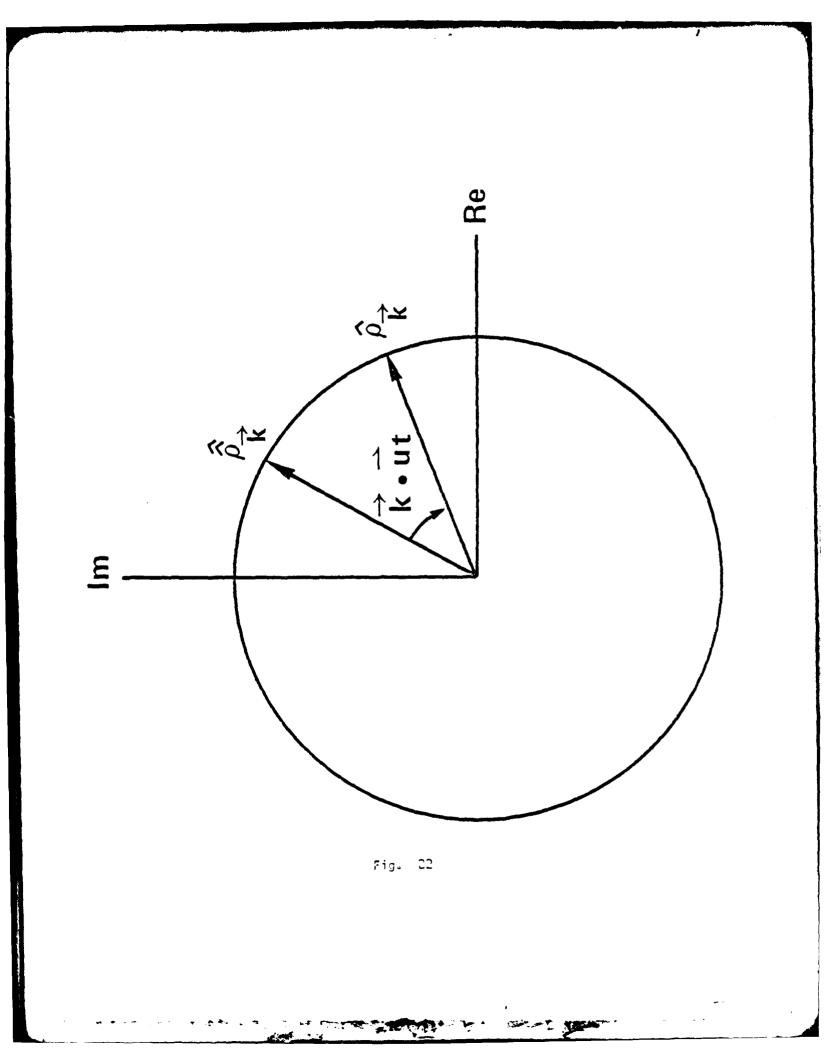
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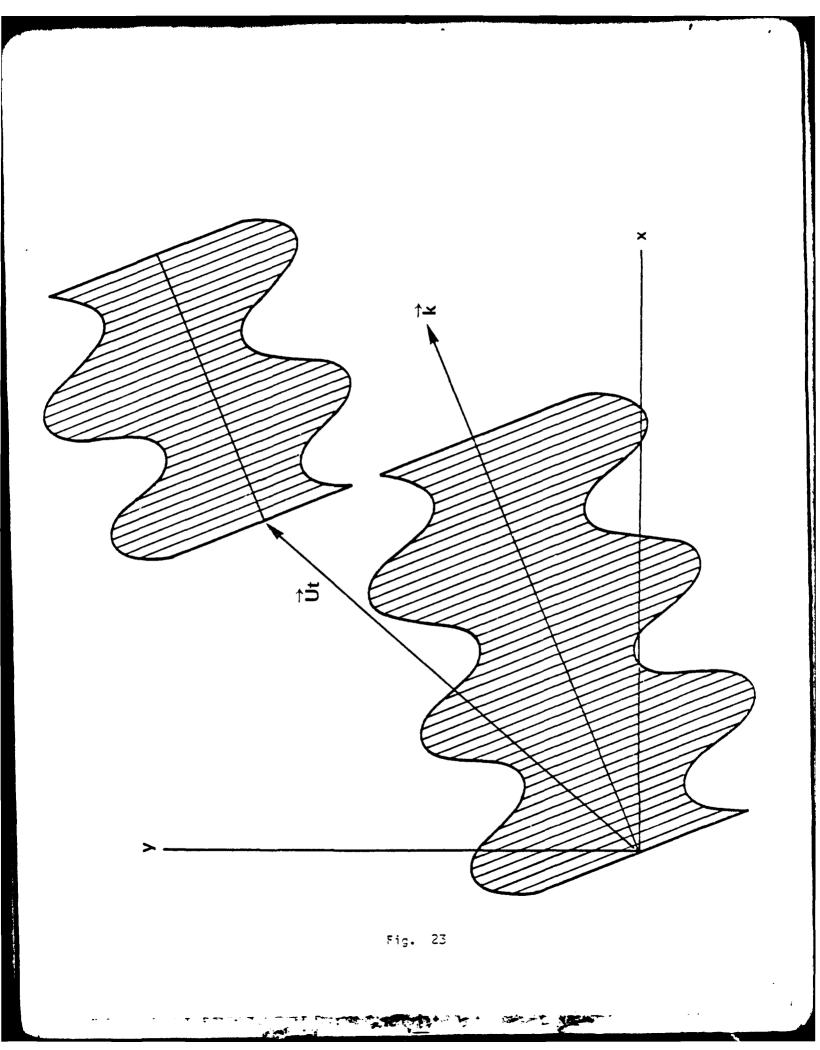
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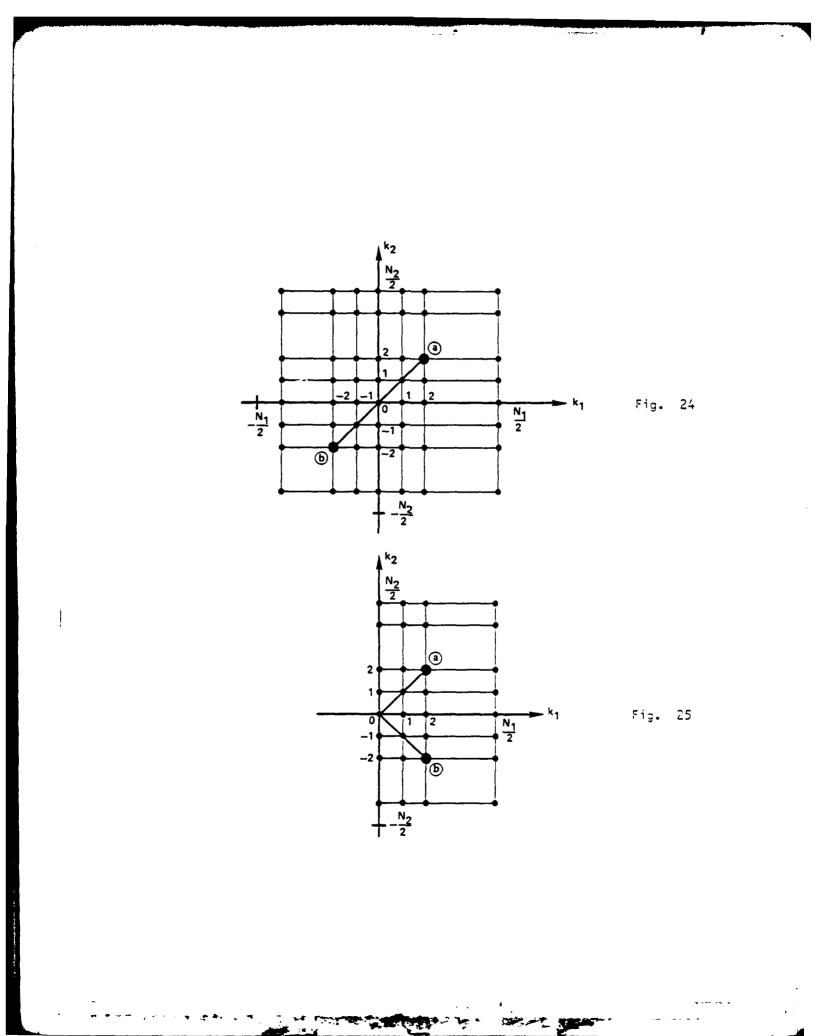


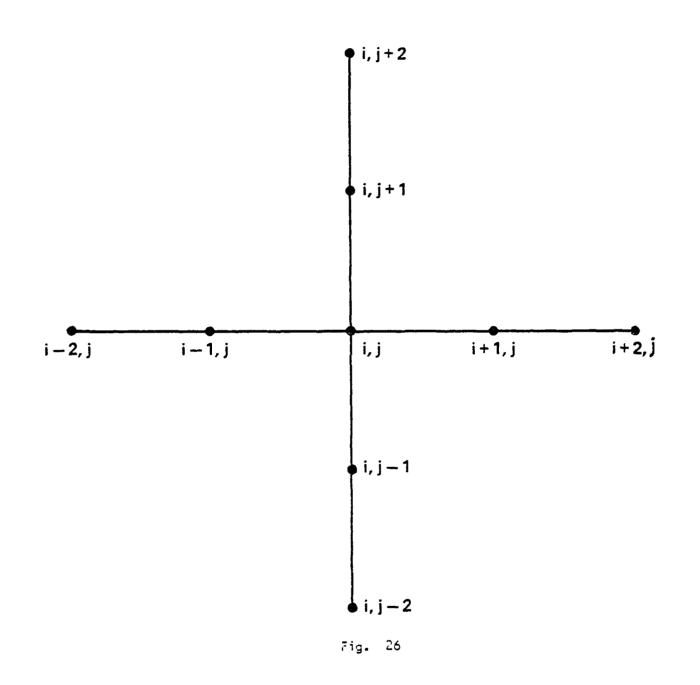


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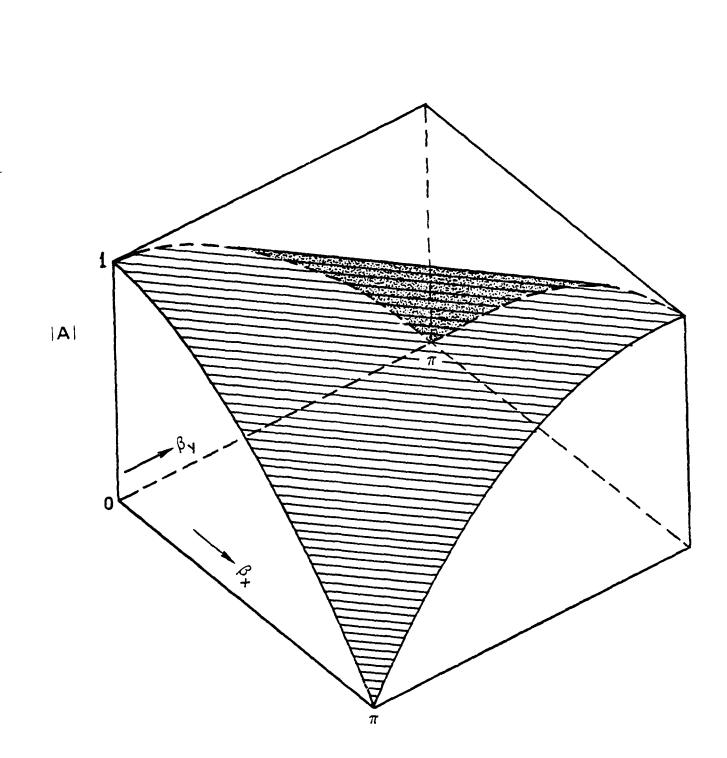
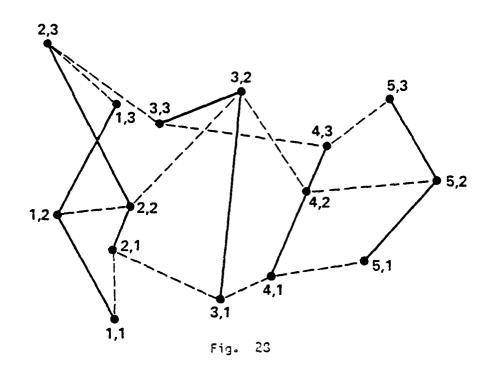


Fig. 27

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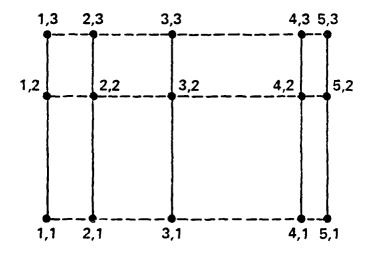
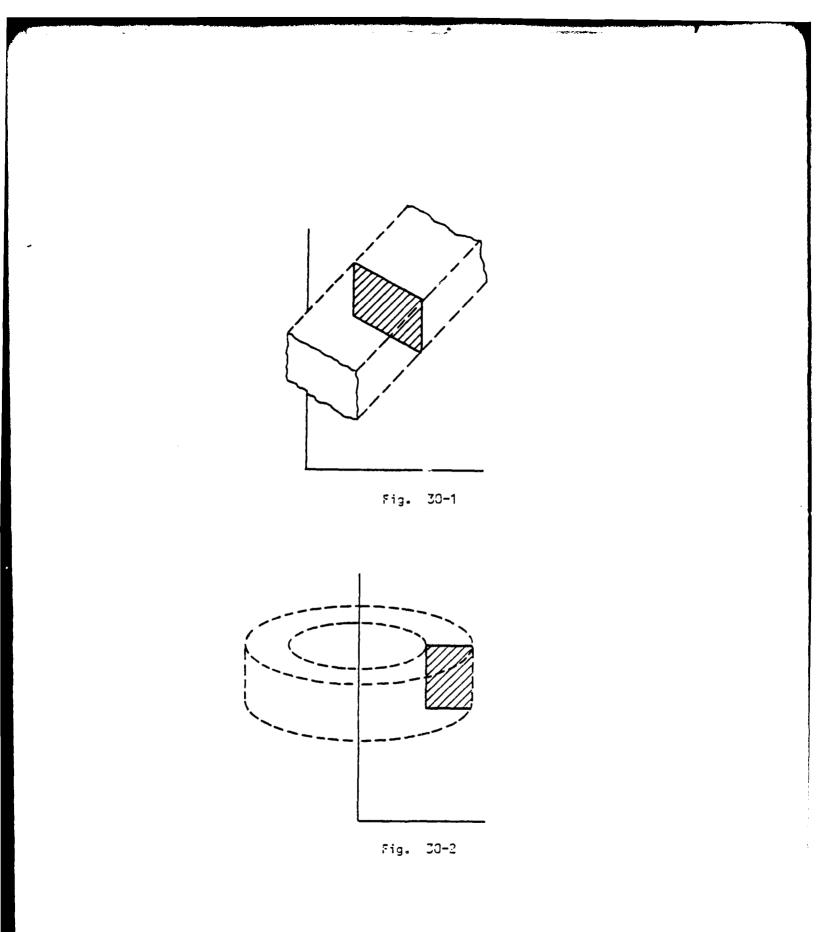
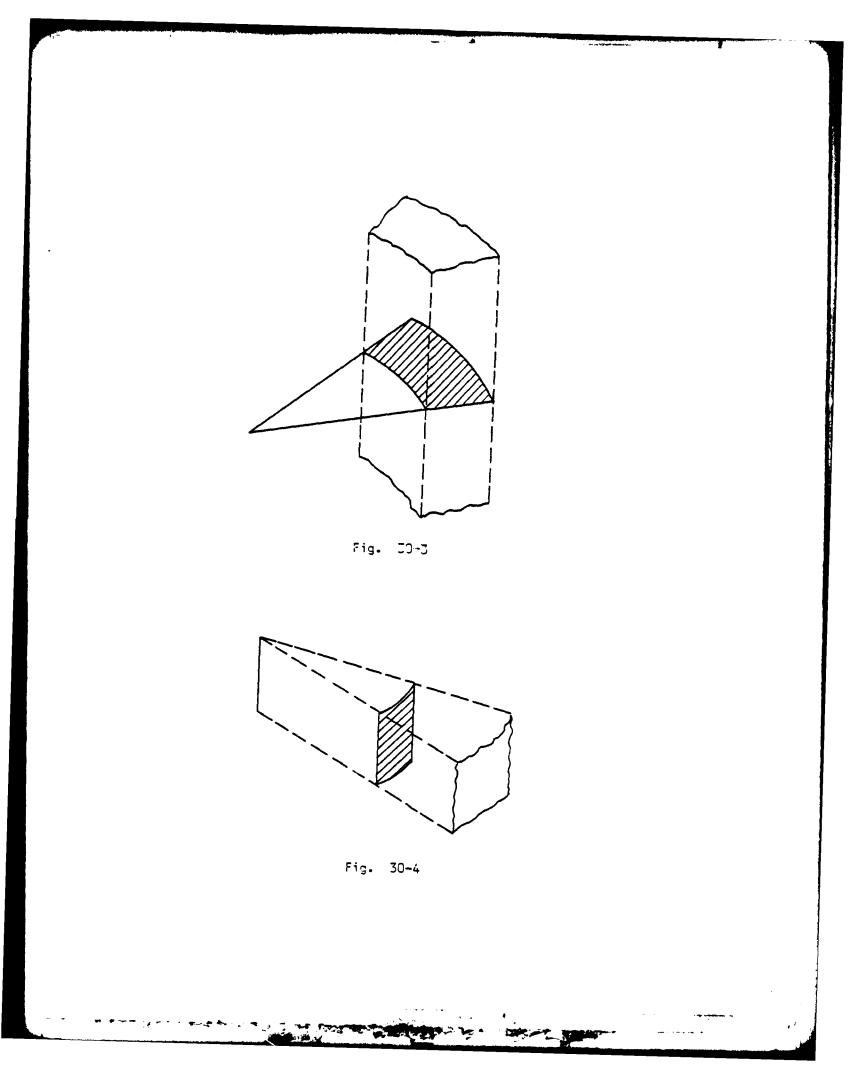
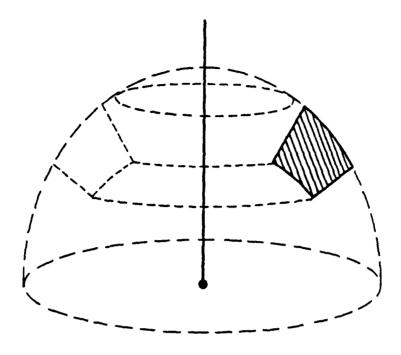


Fig. 29









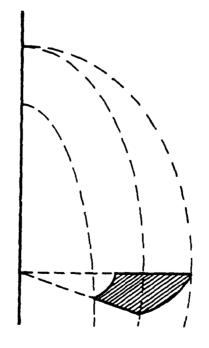
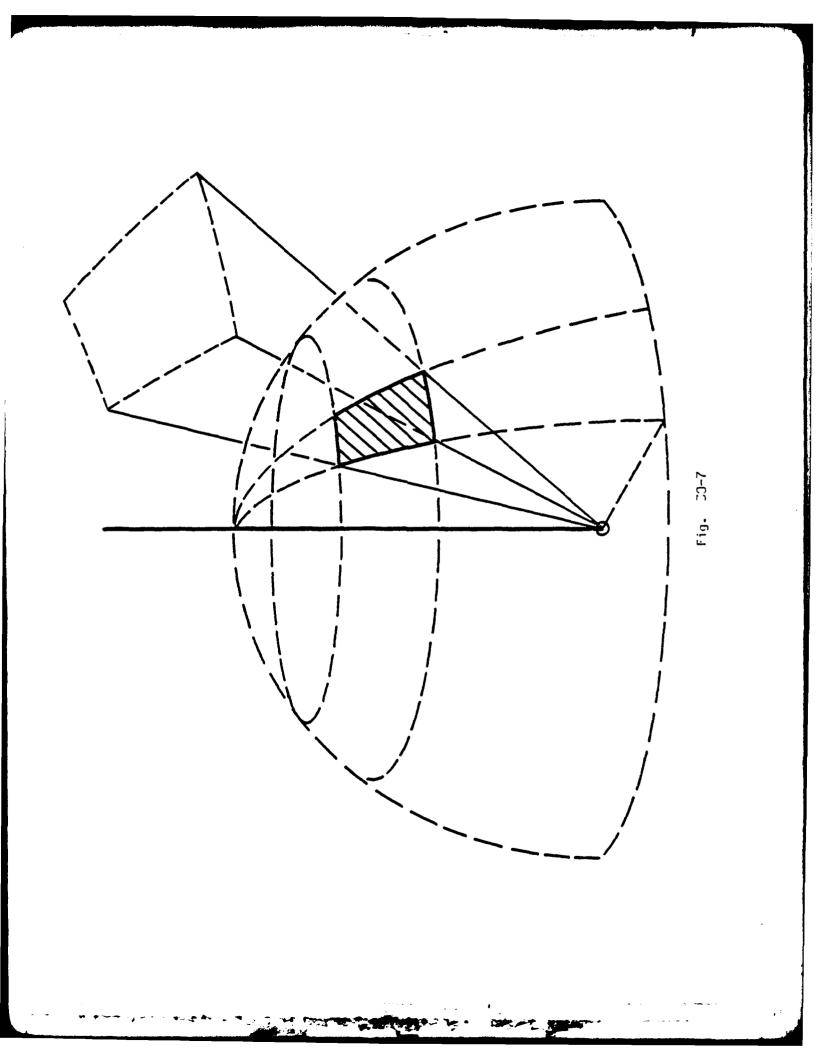
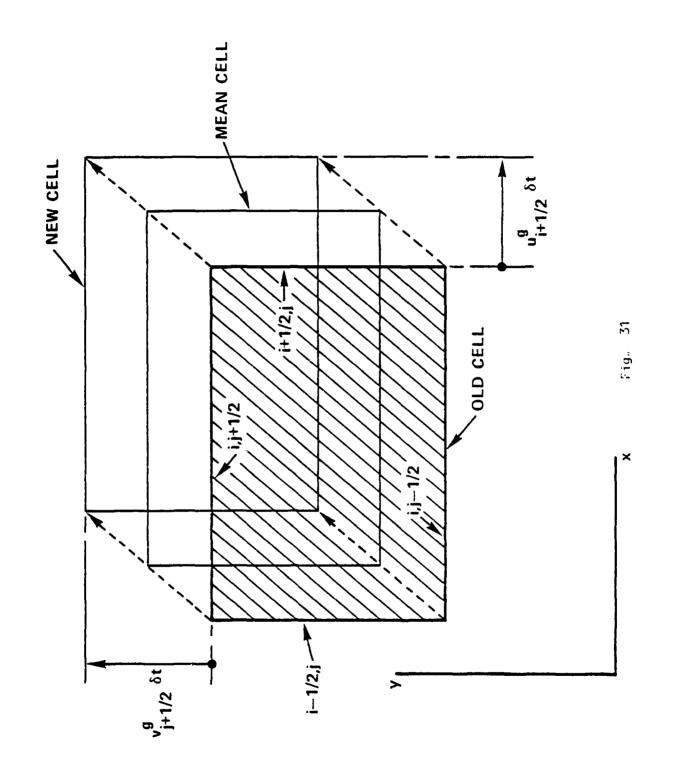


Fig. 30-5





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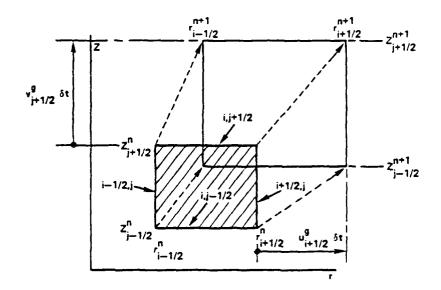
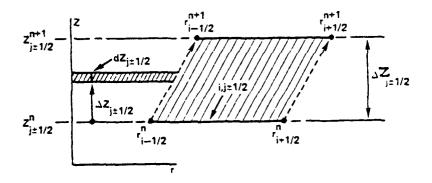
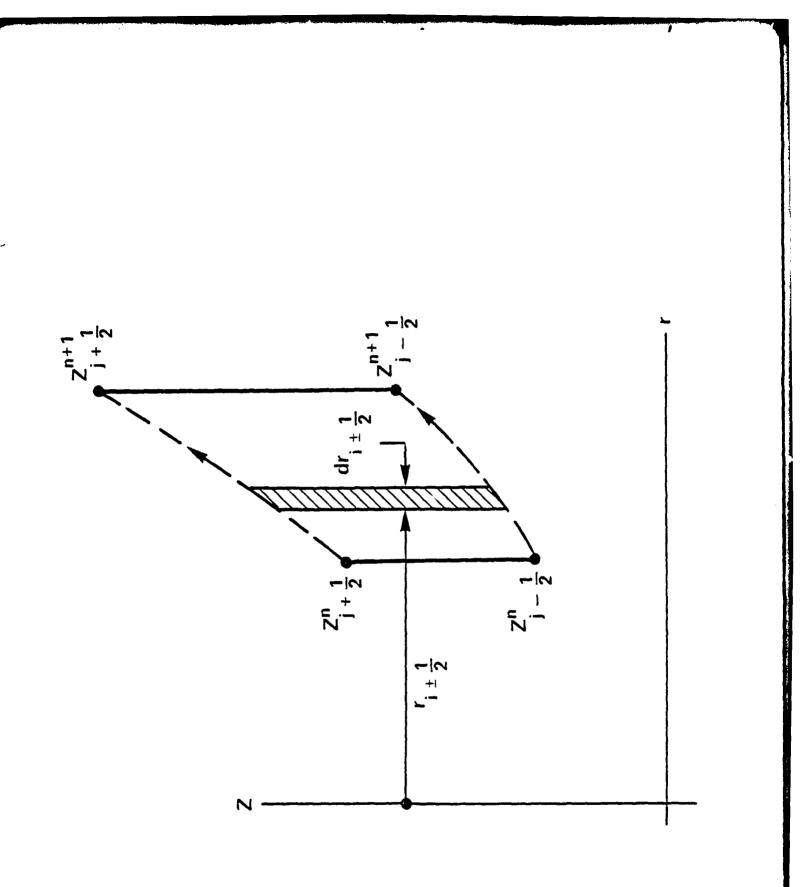


Fig. 52



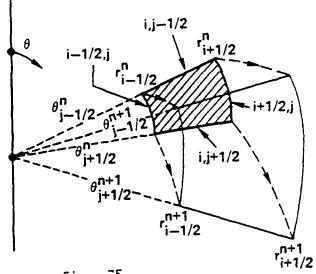
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Fig. 33





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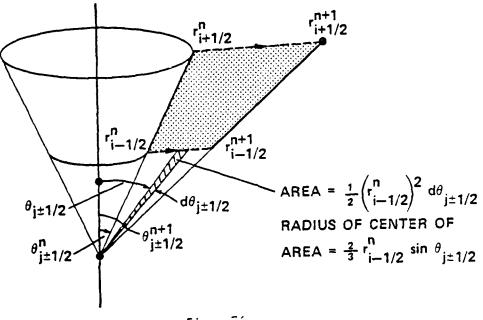
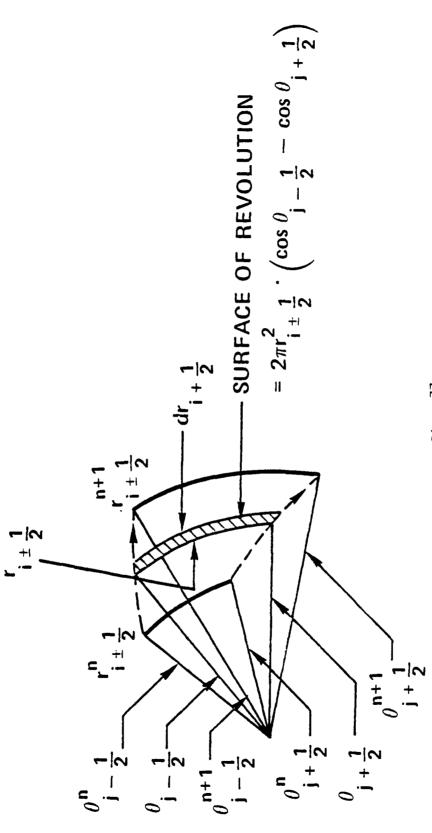


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Fig. 37

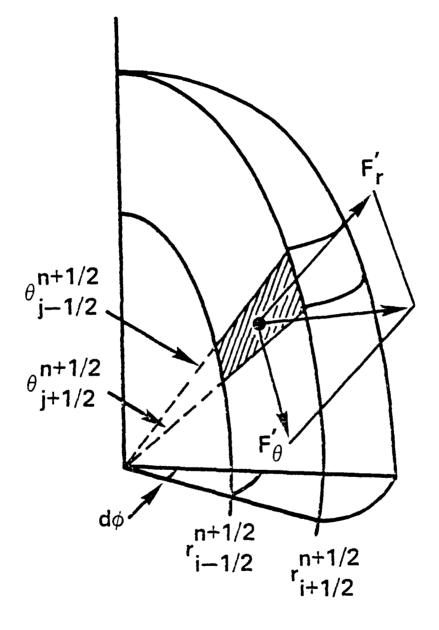


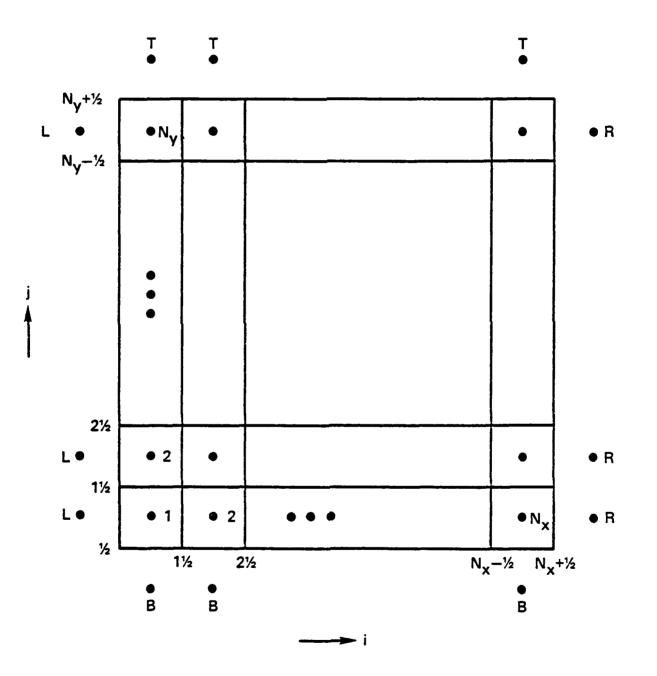
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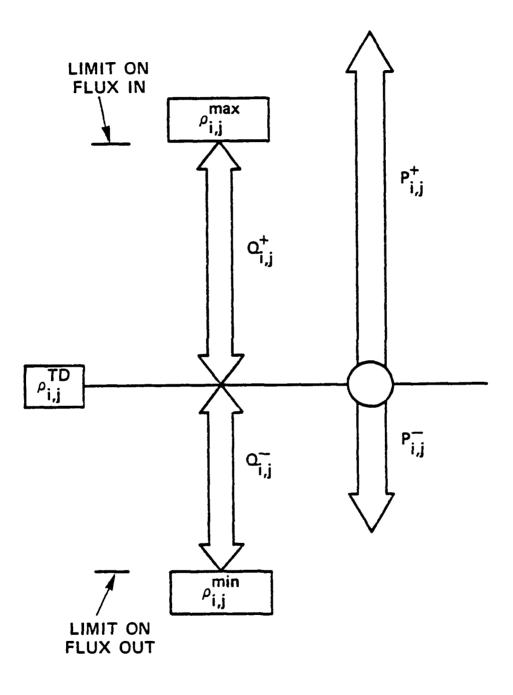
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# Fig. 39

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Fig. 40

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APPENDIX

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SUBROUTINE FCT2D(RHO,KO,KN,KR,SNKRNZ, LBC,RHOLBC,RBC,RHORBC,BBC,RHOBBC,TBC,RHOTBC)

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A FULLY 2-D ROUTINE THAT SOLVES GENERALIZED CONTINUITY EQUATIONS OF THE FORM

D RHO / D T = - DIV( RHO \* V ) - SOURCES

WHERE RHO IS THE GENERALIZED DENSITY, AND V IS THE FLUID VELOCITY. FOR SECOND ORDER ACCURACY, IT IS ADVISABLE TO ADVANCE HALF A TIME STEP USING THE VELOCITY AND SOURCE TERMS AT THE BEGINNING OF THE TIME STEP, THEN ADVANCE A WHOLE TIME STEP USING THE HALF-POINT VELOCITY AND SOURCE TERMS. USING THE HALF FOINT DENSITY IS NOT RECOMMENDED. IT IS, HOWEVER, INCLUDED AS AN OPTION, BY ALTERNATING (KO,KN) BETWEEN (1,2) FOR THE HALF TIME STEP, AND (2,1) FOR THE WHOLE TIME STEP. THE OLD, (KO), AND NEW, (KN), DENSITIES ( AT THE BEGINNING AND END OF THE TIME STEP, RESPECTIVELY ) ARE STORED IN A 2-LEVEL 2-D ARRAY ( 3-0 ARRAY ). THE MASS AND DIFFUSION FLUXES ARE EVALUATED USING KO DENSITY, WHEREAS KN DENSITY DETERMINES THE ANTI-DIFFUSION IT IS ADVISABLE TO SET KO = 1, KN = 2, UNLESS THE HALF FLUXES. POINT DENSITY IS TO BE USED DURING THE WHOLE TIME STEP. THEN KO = 2, KN = 1 FOR THE WHOLE TIME STEP. KR DETERMINES THE LOCATION OF THE RESULTING DENSITY. IT IS ADVISABLE TO SET KR = 2 , 1 , FOR THE HALF AND WHOLE TIME STEPS, THIS CHOICE ELIMINATES THE NEED TO COPY THE NEW RESPECTIVELY. DENSITY ON THE OLD ARRAY, IN FREFARATION FOR A NEW TIME STEF. SNKRNZ IS A LOGICAL VARIABLE WHICH, WHEN SET TO .TRUE., TELLS THE ROUTINE TO USE THE CORRECTION FACTORS OF THE LAST SNKRNZ = .FALSE. CALL, TO LIMIT THE ANTI-DIFFUSION FLUXES. IF SET TO .FALSE., THE CORRECTION FACTORS ARE EVALUATED FROM THE CURRENT VARIABLES AND USED IN THE LIMITING PROCESS. LBC, RHOLBC, RBC, RHORBC, BBC, RHOBBC, TBC, RHOTBC, ARE DEFINED BELOW.

(1) A PARTICULAR GEOMETRY IS SELECTED BY A CALL TO ENTRY SETGOM :

CALL SETGOM( 4HCART, 1HX, 1HY, NX, NY ) OR ..,1HX, 1HZ,... OR ..., 1HZ, 1HY,...,ASSUMES CARTESIAN COORDINATES. ORDER OF THE 2 COORDINATES IS IMMATERIAL ONLY FOR THIS CASE. CALL SETGOM( 3HCYL, 1HR, 1HZ, NX, NY ) CALL SETGOM( 3HCYL, 1HR, 3HFYE, NX, NY ) CALL SETGOM( 3HCYL, 1HZ, 3HFYE, NX, NY ) FOR THE 3 TYPICAL CYLINDRICAL COORDINATES.

CALL SETGOM( 3HSFH, 1HR, 4HCETA, NX, NY )

CALL SETGOM( 3HSFH, 1HR, 3HFYE, NX, NY ) CALL SETGOM( 3HSFH, 4HCETA, 3HFYE, NX, NY ) FOR THE 3 TYPICAL SPHERICAL COORDINATES. NX, NY, ARE THE NUMBERS OF CELLS CENTERS ALONG THE 2 COORDINATES, IN THE PRESCRIBED ORDER. IF THE LITERAL CONSTANTS DESCRIBING THE GEOMETRY ARE MISS-SPELLED, AN ERFOR MESSAGE IS ISSUED, AND EXECUTION STOPPED. NOTE : THE 2 COORDINATES ARE GENERALLY DENOTED BY (X,Y). IN SPHERICAL R-FYE GEOMETRY, FOR EXAMPLE, X MEANS R, WHILE Y MEANS FYE.

- (2) THE LEFT, RIGHT, BOTTOM, AND TOP BOUNDARIES ARE EXTENDED 1 CELL BEYOND THE LAST GRID POINT, YIELDING (NX+2)\*(NY+2) CELLS. THE DENSITY OF AN EXTRA LEFT CELL = LBC \* (DENSITY OF ADJACENT CELL ON SAME ROW) + RHOLBC. BY ADJUSTING THE VALUES OF THE TWO 1-D REAL ARRAYS ( OF DIMENSION NY+2 ) LBC AND RHOLBC, VARIOUS TYPES OF BOUNDARIES CAN BE SIMULATED. SIMILAR RELATIONS APPLY FOR RIGHT, BOTTOM, AND TOP BOUNDARIES, DENOTED BY R, B, AND T, RESPECTIVELY. NOTE THAT BOTTOM AND TOP ARRAYS ARE NX+2 CELLS LONG.
- (3) ALL THE BOUNDARIES ARE CONSIDERED PERMEABLE TO DIFFUSION AND ANTI-DIFFUSION FLUXES, UNLESS A CALL TO ENTRY SOLDFY INFORMS THE ROUTINE OTHERWISE. ANY OF

CALL SOLDFY( 4HLEFT, KSTRT, KEND ) CALL SOLDFY( 4HRITE, KSTRT, KEND ) CALL SOLDFY( 4HBOTM, KSTRT, KEND ) CALL SOLDFY( 3HTOP, KSTRT, KEND ) MAKES THE LEFT, RIGHT, BOTTOM, OR TOP BOUNDARIES IMPERMEABLE TO BOTH DIFFUSION AND ANTI-DIFFUSION FLUXES FROM CELL NUMBER KSTRT TO CELL NUMBER KEND, INCLUSIVE. NOTE : CELL 1 IS NOW THE EXTRA CELL BEYOND THE BOUNDARY, CONFINING CELLS 2 TO NX+1, OR NY+1. ANY NUMBER OF CALLS TO SOLDFY IS ALLOWED, MAKING IT POSSIBLE TO SOLIDIFY UNCONNECTED PATCHES ALONG EACH BOUNDARY. EACH TIME SOLDFY IS CALLED, A MESSAGE EXFLAINING THE ACTION TAKEN IS ISSUED.

(4) CALLS TO ENTRY FRODIC, FOR EXAMPLE,

CALL PRODIC( 1 , 1HX ) INFORM THE ROUTINE TO TREAT THE 1 ST OR 2 ND COORDINATE AS PERIODIC. THE SECOND ARGUMENT IS JUST TO GENERATE A LABEL; THE MESSAGE " X COORDINATE FERIODIC " IS ISSUED. SIMILARLY, CALL PRODIC( 2 , 3HFYE ) MAKES THE 2 ND COORDINATE PERIODIC, AND THE MESSAGE " FYE COORDINATE PERIODIC " ISSUED. IF THE PERIODIC CALL IS MADE FOR A COORDINATE THAT SHOULDN'T BE FERIODIC, A WARNING MESSAGE IS ISSUED, THEN EXECUTION FROCEEDS.

(5)	THE GRID IS INITIALIZED BY A CALL TO ENTRY ORIGRD: CALL ORIGRD( XGN, YGN ) WHERE XGN, YGN ARE TWO 1-D REAL ARRAYS OF DIMENSIONS NX+1, NY+1, CONTAINING THE LOCATIONS OF X, Y INTERFACES. ORIGRD WILL THEN CONSIDER THESE AS THE INITIAL LOCATIONS. AT THE BEGINNING OF EACH TIME STEP CALL NGRID( XGN, YGN ) WILL EVALUATE VOLUME, MEAN INTERFACE AREA, OF CELLS, WHEREAS CALL OGRID( XGN, YGN ) AT THE END OF EACH TIME STEP, RESET THE OLD ARRAYS FOR THE NEXT TIME STEP.
(6)	<pre>IT IS ASSUMED THAT THE GRID IS MOVING, UNLESS CALLS TO ENTRY FIXGRD FIX ONE OR BOTH OF THE COORDINATES GRIDS.     CALL FIXGRD( 1 , 1HX ) INFORMS THE ROUTINE THAT THE 1 ST COORDINATE GRID IS FIXED. THE SECOND ARGUMENT IS JUST TO GENERATE A LABEL; THE MESSAGE "X GRID FIXED " IS ISSUED. SIMILARLY,     CALL FIXGRD( 2 , 1HZ ) FIXES THE 2 ND COORDINATE GRID AND ISSUES THE MESSAGE " Z GRID FIXED ". IF BOTH COORDINATES GRIDS ARE FIXED, CALL NGRID, THEN OGRID, ONLY ONCE AFTER INITIALIZATION.</pre>
(7)	A PARTICULAR ANTI-DIFFUSION FLUX CORRECTOR IS SELECTED BY A CALL TO ENTRY SETLMT : CALL SETLMT( SHBORIS, 4HBOOK ) INVOKES BORIS-BOOK FLUX LIMITER, WHILE CALL SETLMT( 7HZALESAK, 1H ) INVOKES ZALESAK FLUX LIMITER. THE ARGUMENTS REFER TO THE ORIGINATORS OF THE FLUX LIMITER. IF THE LITERAL CONSTANTS DESCRIBING A LIMITER ARE MISS-SPELLED, AN ERROR MESSAGE IS ISSUED, AND EXECUTION STOPPED.
(8)	A TIME STEP STARTS BY A CALL TO ENTRY NGRID, FOLLOWED BY CALL VOLFLX( U, V, DT ) WHERE U,V ARE TWO 2-D REAL ARRAYS OF DIMENSIONS (NX+2)*(NY+2) CONTAINING THE COMPONENTS OF VELOCITY VECTOR AT THE CELLS CENTERS. DT IS THE TIME STEF.
(7)	<pre>BEFORE EACH CALL TO FCT2D, THE SOURCE TERM IS DETERMINED BY A SEQUENCE OF CALLS : CALL CLRSRC CLEARS THE SOURCE TERM WHICH REMAINS ZERO UNTIL ANY OF THE NEXT CALLS IS DONE. EACH CALL ADDS TO THE SOURCE TERM. ANY NUMBER OF CALLS IS ALLOWED, TO FORM THE TOTAL VALUE OF THE SOURCE TERM. CALL SDRCES( 3HBDF, SORCE, DT ) ADDS A BODY TYPE FORCE, WHERE SORCE IS A 2-D REAL ARRAY OF DIMENSION (NX+2)*(NY+2) CONTAINING THE BODY FORCES PER UNIT VOLUME.</pre>

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CALL SORCES( 4HXGRD, SORCE, DT ) CALL SORCES( 4HYGRD, SORCE, DT ) ADDS THE X OR Y COMPONENTS OF THE GRADIENT OF THE QUANTITY IN ARRAY SORCE. CALL SORCES( 3HDIV, SORCE, DT )
ADDS THE DIVERGENCE OF THE QUANTITY IN SORCE. ENTRY SORCES DETERMINES WHICH FORM OF GRADIENT OR DIVERGENCE TO USE ACCORDING TO THE GEOMETRY. ALTERNATIVELY, ONE CAN SEFARATELY CALL ENTRY BODY FOR BODY FORCES, XGRAD OR YGRAD FOR THE GRADIENT IN CARTESIAN COORDINATES, RCGRAD OR YGRAD FOR THE GRADIENT IN CYLINDRICAL R-Z GEOMETRY, OR XGRAD AND YGRAD FOR DIVERGENCE IN CARTESIAN GEOMETRY, RCDIV AND YGRAD DIVERGENCE IN CYLINDRICAL R-Z GEOMETRY,
(10) THE TIME STEP ENDS BY A CALL TO OGRID
(11) FOR 2 ND ORDER ACCURACY, STEPS (8) , (9) ARE PERFORMED TWICE. ONCE WITH DT= TIME STEP / 2 FOR THE HALF TIME STEP, THEN DT= TIME STEP FOR THE WHOLE TIME STEP.
ENTRIES ENTRY NGRID(XGN,YGN) ENTRY OGRID(XGN,YGN) ENTRY ORIGRD(XGN,YGN) ENTRY ORIGRD(XGN,YGN) ENTRY VOLFLX(U,V,DT) ENTRY SORCES(SRCTYP,SORCE,DT) ENTRY SORCES(SRCTYP,SORCE,DT) ENTRY CLRSRC ENTRY BODY(SORCE,DT) ENTRY XGRAD(SORCE,DT) ENTRY YGRAD(SORCE,DT) ENTRY RCDIV(SORCE,DT) ENTRY RCDIV(SORCE,DT) ENTRY SETGOM(GOMTRY,CRD1,CRD2,N1,N2) ENTRY SETGOM(GOMTRY,CRD1,CRD2,N1,N2) ENTRY SETLMT(LMTR1,LMTR2) ENTRY FIXGRD(CRN1,CRD)
ENTRY SOLDFY (BONDRY, KSTRT, KEND)

CALLS TO ... SUBROUTINE NUMU(NI,NJ,EPS,NUV,MUV)

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	PARAMETE	R NFX=100, NFY=100
	PARAMETE	
_	FARAMETE	R NP2X=NPX+2,NP2Y=NPY+2
C		
С		COM CODUT
С	INTEGER	GEOM, CRUNT
Ļ	INTEGER	IFLX(NP2X,NP2Y)
С	INTEDER	1FLA (NF2A)(NF2T)
c		
-	LOGICAL	LSRC
	LOGICAL	
		XCHNG, YCHNG
		XPRDC, YPRDC
С		
С		
	REAL	TEXT (20)
	REAL	LMTR1 (2), LMTR2 (2)
-	REAL	TGM(3),TCRD(6),TLM1(2,4),TLM2(2,4)
С		
	REAL	
	REAL REAL	RBC(NF2Y), RHORBC(NF2Y) BBC(NF2X), RHOBBC(NF2X)
	REAL	TBC (NP2X), RHOTBC (NP2X)
С	NEML	
<b>L</b>	REAL	PRMBLL (NP2Y), PRMBLR (NP2Y), PRMBLB (NP2X), PRMBLT (NF
С		
	REAL	XGO(NP1X),XGN(NP1X),YGO(NP1Y),YGN(NP1Y)
	REAL	XG(NP1X),DXG(NP1X),YG(NP1Y),DYG(NP1Y)
	REAL	DXGO(NP2X), DXGN(NP2X), DYGO(NP2Y), DYGN(NP2Y)
	REAL	RDXGN(NP2X), RDYGN(NP2Y)
	REAL	DXGNH(NP1X), RDXGNH(NP1X), DYGNH(NP1Y), RDYGNH(NP1Y
	REAL	AX (NPX), AY (NPY)
_	REAL	SQ(NF1X), SQQ(NF1X), SQN(NF1X)
С		
	REAL	RHQ(NP2X,NP2Y,2)
	REAL	U(NP2X,NP2Y),ADUDT(NP1X,NPY) V(NP2X,NP2Y),ADVDT(NPX,NP1Y)
	REAL REAL	CELMAS(NFX,NFY), SOURCE(NF2X,NFY) SORCE(NF2X,NFY), SOURCE(NF2X,NF2Y), SORCE(NF2X,NF7
с	REME	CELINES (NEX) NET / SOURCE (NE2X) NEZT / SORCE (NE2X) NEZ
-	REAL	TEMP1(NP2X,NP2Y),TEMP2(NP2X,NP2Y)
	REAL	TEMP3(NP1X, NP1Y), TEMP4(NP1X, NP1Y)
	REAL	TEMPS(NP2X, NP2Y), TEMP6(NP2X, NP2Y)
С		
	REAL	OLDVOL (NF2X, NF2Y), RVOL (NF2X, NF2Y)
	REAL	AVXVL(NF1X,NF1Y), RAVXVL(NF1X,NF1Y)
	REAL	AVYVL(NP1X,NP1Y),RAVYVL(NP1X,NP1Y)
С		
	REAL	XMSFLX(NF1X,NF1Y),YMSFLX(NF1X,NF1Y)
	REAL	XDFFLX(NP2X,NP2Y),YDFFLX(NP2X,NP2Y)
~	REAL	XNTFLX(NF1X,NP1Y),YNTFLX(NF1X,NF1Y)
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	REAL	EPSX(NP1X,NP1Y),NUX(NP2X,NP2Y),MUX(NP2X,NP2Y)
	REAL	EPSY(NP1X,NP1Y),NUY(NP2X,NP2Y),MUY(NP2X,NP2Y)
	REAL	NUXVOL(NP2X,NF2Y),MUXVOL(NF2X,NF2Y)
с	REAL	NUYVOL(NF2X,NF2Y),MUYVOL(NF2X,NF2Y)
C	REAL	MXFLX(NP2X,NP2Y),MNFLX(NP2X,NP2Y)
	REAL	FLXIN(NP2X,NP2Y),FLXOUT(NP2X,NP2Y)
	REAL	RHOMX(NP2X,NP2Y),RHOMN(NP2X,NP2Y)
	REAL	MXIN(NF2X,NF2Y),MXOUT(NF2X,NF2Y)
С	REAL	DIFF(NP2X,NP2Y),FLX(NP2X,NP2Y)
8	REAL	RIN(NP2X,NP2Y),ROUT(NP2X,NP2Y)
	REAL	XFLXCR(NP2X,NP2Y),YFLXCR(NP2X,NP2Y)
С		
C	EQUIVALE	NCE (TEMP1,FLXIN,RIN)
	EQUIVALE	
	EQUIVALE	
	EQUIVALE	INCE (TEMP4, YMSFLX, YNTFLX, AVYVL, RAVYVL, EFSY)
	EQUIVALE	NCE (TEMP5,XDFFLX,YDFFLX,NUX,NUXVOL,NUY,NUYVOL)
	EQUIVALE	
	EQUIVALE	
	EQUIVALE	
С		
C		
		(T(1),TEXT(2),TEXT(3)/4H M,4HISS-,4HSPEL/
		(T(4),TEXT(5)/4HLING,4H OF /
		(T(9),TEXT(10),TEXT(11)/4H IDE,4HNTIF,4HIER / (T(12),TEXT(13),TEXT(14)/4H DE,4HDMET,4HRY /
		T(15), TEXT(16), TEXT(17)/4HFLUX, 4H LIM, 4HITER/
		(T(18), TEXT(19), TEXT(20)/4HSOUR, 4HCE T, 4HYFE /
C		
-	DATA TGM	1(1),TGM(2),TGM(3)/4HCART,4HCYL ,4HSPH /
С	<b>DATA TOD</b>	D(1),TCRD(2),TCRD(3)/4HX ,4HY ,4HZ /
		LD(1),TCRD(2),TCRD(3)/4HX ,4HY ,4HZ / RD(4),TCRD(5),TCRD(6)/4HR ,4HCETA,4HFYE /
С		
	DATA TBN	D(1),TBND(2)/4HLEFT,4HRITE/
	DATA TBN	ID(3),TBND(4)/4HBOTM,4HTOP /
С		
		R1,LMTR2/4*4H /
		11(1,1),TLM1(2,1)/4HBORI,4HS / 12(1,1),TLM2(2,1)/4HBOOK,4H /
		11(1,2),TLM1(2,2)/4HZALE,4HSAK /
		12(1,2),TLM2(2,2)/4H ,4H /
С		
<b>C</b>	DATA BOF	/3HBDF/,XGRD,YGRD/4HXGRD,4HYGRD/,DIV/3HDIV/
C		

#### FORMATS :

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10 FORMAT (///5X,7HWARNING,5X,11A4)

- 20 FORMAT(///5X,7HWARNING,5X,A4,2X,22HSHOULD NOT BE PERIODIC)
- 30 FORMAT(///5X,24HALL BOUNDARIES PERMEABLE)
- 40 FORMAT(///5X,A4,2X,19HCDORDINATE PERIODIC)
- 50 FORMAT (///5X,A4,2X,10HGRID FIXED)
- 60 FORMAT (///5X,A4,2X,22HBOUNDARY SOLID BETWEEN,

- & 2X,4HCELL,2X,14,2X,3HAND,2X,14)
- 70 FORMAT (///5X, 25HGEDMETRY NOT INCLUDED YET)
- C C

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С
      EVALUATE OLD CELL MASS "CELMAS"
           DO 110 J=1,NY
           DO 110 I=1,NX
           OLDVOL(I,J) = DXGO(I+1) * DYGO(J+1)
  110
           CELMAS(I,J) = RHO(I+1,J+1,1) * OLDVOL(I,J)
C
С
      ADD SOURCE TERM "SOURCE" WHEN APPROPRIATE
           IF(.NOT.LSRC) GO TO 125
С
С
           DO 120 J=1,NY
           DO 120 I=1,NX
  120
           CELMAS(I,J) = CELMAS(I,J) - SOURCE(I,J)
С
  125
           CONTINUE
С
С
С
      EVALUATE X-CONVECTION FLUX "XMSFLX"
           DO 130 J=1,NY
           DO 130 I=1,NXP1
           TEMP3(I,J) = RHO(I+1,J+1,KO) + RHO(I,J+1,KO)
           TEMP5(I,J)=0.5*ADUDT(I,J)
  130
           XMSFLX(I,J) = TEMPB(I,J) * TEMPB(I,J)
С
С
      EVALUATE Y-CONVECTION FLUX "YMSFLX"
           DO 140 J=1,NYP1
           DO 140 I=1,NX
           TEMP4(I,J) = RHO(I+1,J+1,KO) + RHO(I+1,J,KO)
           TEMP6(I,J) = 0.5 * ADVDT(I,J)
  140
           YMSFLX(I,J) = TEMP4(I,J) * TEMP6(I,J)
С
C
      EVALUATE X AND Y TRANSPORTED DENSITIES
           DO 150 J=1,NY
           DO 150 I=1,NX
           TEMP5(I,J) = XMSFLX(I,J) - XMSFLX(I+1,J)
           TEMP6(I,J) = YMSFLX(I,J) - YMSFLX(I,J+1)
           TEMF3(I,J) = CELMAS(I,J) + TEMF5(I,J)
           TEMP4(I,J) = CELMAS(I,J) + TEMP5(I,J)
           CELMAS(I,J) = TEMPS(I,J) + TEMPS(I,J)
           RVOL(I,J)=RDXGN(I+1)*RDYGN(J+1)
           RHO(I+1, J+1, KN) = TEMPB(I, J) * RVOL(I, J)
  150
           TEMP4(I,J) = TEMP4(I,J) * RVOL(I,J)
С
С
      EVALUATE X-TRANSPORTED DENSITY AT LEFT AND RIGHT BOUNDARIES
           DO 170 J=2,NYP1
           RHO(1, J, KN) = LBC(J) * RHO(IL, J, KN) + RHOLBC(J)
  170
           RHO(NXP2, J, KN) = RBC(J) * RHO(IR, J, KN) + RHORBC(J)
C
```

С	180	EVALUATE "EFSX" DO 180 J=1,NY DO 180 I=1,NXF1 RAVXVL(I,J)=RDXGNH(I)*RDYGN(J+1) EFSX(I,J)=RAVXVL(I,J)*ADUDT(I,J)
C	100	EVALUATE X DIFFUSION AND ANTI-DIFFUSIONTEDEFFICIENTS "NUX", "MUX" CALL NUMU(NXP1,NY,EPSX,NUX,MUX)
	185	CANCEL THE DIFFUSION AND ANTI-DIFFUSION X-FLUXES THROUGH SOLID PORTIONS OF LEFT AND RIGHT BOUNDARIES DO 185 J=1,NY NUX(1,J)=NUX(1,J)*FRMBLL(J+1) MUX(1,J)=MUX(1,J)*FRMBLL(J+1) NUX(NXP1,J)=NUX(NXF1,J)*FRMBLR(J+1) MUX(NXP1,J)=MUX(NXP1,J)*FRMBLR(J+1)
CC	100	<pre>EVALUATE x DIFFUSION AND ANTI-DIFFUSION FLUXES "XDFFLX", "XNTFLX" D0 190 J=1,NY D0 190 I=1,NXP1 AVXVL(I,J)=DXGNH(I)*DYGN(J+1) NUXV0L(I,J)=NUX(I,J)*AVXVL(I,J) MUXV0L(I,J)=MUX(I,J)*AVXVL(I,J) TEMP3(I,J)=RH0(I+1,J+1,K0)-RH0(I,J+1,K0) XDFFLX(I,J)=NUXV0L(I,J)*TEMP3(I,J) TEMP3(I,J)=RH0(I+1,J+1,KN)-RH0(I,J+1,KN) YNTELY(I,J)=RH0(I+1,J+1,KN)-RH0(I,J+1,KN)</pre>
C C	190	<pre>XNTFLX(I,J)=MUXVOL(I,J)*TEMP3(I,J) ADD X-DIFFUSION TO "CELMAS" DO 200 J=1,NY DO 200 I=1,NX RHO(I+1,J+1,KN)=TEMP4(I,J) TEMP6(I,J)=XDFFLX(I+1,J)-XDFFLX(I,J)</pre>
C C	200	CELMAS(I,J)=CELMAS(I,J)+TEMP6(I,J) EVALUATE Y-TRANSPORTED DENSITY AT BOTTOM AND TOP BOUNDARIES DO 210 I=1,NXP2 RHO(I,1,KN)=BBC(I)*RHO(I,JB,KN)+RHOBBC(I) RHO(I,NYP2,KN)=TBC(I)*RHO(I,JT,KN)+RHOTBC(I)
00	220	EVALUATE "EPSY" DO 220 J=1,NYP1 DO 220 I=1,NX RAVYVL(I,J)=RDXGN(I+1)*RDYGNH(J)
0 0 0		EVALUATE Y DIFFUSION AND ANTI-DIFFUSION COEFFICIENTS "NUY", "MUY" CALL NUMU(NX,NYF1,EFSY,NUY,MUY)

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С CANCEL THE DIFFUSION AND ANTI-DIFFUSION Y-FLUXES THROUGH SOLID C PORTIONS OF BOTTOM AND TOP BOUNDARIES DO 225 I=1,NX NUY(I,1) = NUY(I,1) \* PRMBLB(I+1)MUY(I,1) = MUY(I,1) \* PRMBLB(I+1)NUY(I,NYF1)=NUY(I,NYF1)\*FRMBLT(I+1) 225 MUY(I,NYP1) = MUY(I,NYP1) \* FRMBLT(I+1) С С EVALUATE Y DIFFUSION AND ANTI-DIFFUSION FLUXES "YDFFLX" , "YNTFLX" DO 230 J=1,NYP1 DO 230 I=1,NX AVYVL(I,J) = DXGN(I+1) \* DYGNH(J)NUYVOL(I,J) = NUY(I,J) \* AVYVL(I,J)MUYVOL(I,J) = MUY(I,J) \* AVYVL(I,J)TEMP4(I,J) = RHO(I+1,J+1,KO) - RHO(I+1,J,KO)YDFFLX(I,J) = NUYVOL(I,J) \* TEMP4(I,J)TEMP4(I,J) = RHO(I+1,J+1,KN) - RHO(I+1,J,KN)230 YNTFLX(I,J) = MUYVOL(I,J) \* TEMP4(I,J)C С ADD Y-DIFFUSION TO "CELMAS" DO 240 J=1,NY DO 240 I=1,NX TEMP6(I, J) = YDFFLX(I, J+1) - YDFFLX(I, J)240 CELMAS(I,J) = CELMAS(I,J) + TEMP6(I,J)C С IF SYNCHRONIZATION OF ANTI-DIFFUSION FLUXES IS SPECIFIED, SKIP C EVALUATION OF CORRECTION FACTORS IF (SNKRNZ) GO TO 445 С С С EVALUATE TRANSPORTED-DIFFUSED DENSITY DO 250 J=1,NY DO 250 I=1,NX RVOL(I,J) = RDXGN(I+1) \* RDYGN(J+1) 250 RH0(I+1, J+1, KN) = CELMAS(I, J) \* RVOL(I, J) С C EVALUATE TRANSFORTED-DIFFUSED DENSITY AT BOTTOM AND TOF BOUNDARIES DO 260 I=2,NXP1 TEMF1(I,1)=1.0 TEMP2(I-1,NYP1) = 1.0RHO(I, 1, KN) = PBC(I) \* RHO(I, JB, KN) + RHOBBC(I)260  $RHO(I,NYP2,KN) \approx TBC(I) * RHO(I,JT,KN) + RHOTBC(I)$ C С EVALUATE TRANSPORTED-DIFFUSED DENSITY AT LEFT AND RIGHT BOUNDARIES DO 270 J=2,NYF1 TEMP1(1, J) = 1.0TEMP2(NXF1, J-1) = 1.0RHO(1,J,KN)=LBC(J)\*RHO(IL,J,KN)+RHOLEC(J) RHO(NXF2, J, KN) = RBC(J) \* RHO(IR, J, KN) + RHORBC(J) 270 С С

A10

CANCEL THE ANTI-DIFFUSION X-FLUX IF IT IS OFFOSITE TO ITS LOCAL С С TRANSPORTED-DIFFUSED DENSITY GRADIENT AND ANY OF THE ADJACENT ONES DO 280 J=1,NY DO 280 I=1,NXP1 280 DIFF(I, J) = RHO(I+1, J+1, KN) - RHO(I, J+1, KN)C DO 290 J=1,NY DO 290 I=1,NX TEMF1(I+1, J+1) = XOR(XNIFLX(I+1, J), DIFF(I, J)) TEMP2(I,J) = XOR(XNTFLX(I,J), DIFF(I+1,J))290 С DO 300 J=1, NY DO 300 I=1,NXP1 TEMP5(I,J)=XOR(XNTFLX(I,J),DIFF(I,J)) TEMP6(I,J) = OR(TEMP1(I,J+1), TEMP2(I,J))FLX(I,J) = AND(TEMP5(I,J), TEMP6(I,J))FLX(I,J) = COMPL(FLX(I,J))IFLX(I,J) = LSHF(IFLX(I,J), -31)FLX(I,J)=FLOAT(IFLX(I,J)) 300 XNTFLX(I,J) = XNTFLX(I,J) \* FLX(I,J)С С IF X-COORDINATE IS PERIODIC AND EITHER LEFT OR RIGHT BOUNDARY'S С ANTI-DIFFUSION FLUX IS CANCELLED, CANCEL THE OTHER IF(.NOT.XPRDC) GD TO 305 С DO 304 J=1,NY XNTFLX(1,J) = AND(XNTFLX(1,J), XNTFLX(NXP1,J)) 304 XNTFLX(NXF1,J) = XNTFLX(1,J)С 305 CONTINUE С С С CANCEL THE ANTI-DIFFUSION Y-FLUX IF IT IS OPPOSITE TO ITS LOCAL С TRANSPORTED-DIFFUSED DENSITY GRADIENT AND ANY OF THE ADJACENT ONES DO 310 J=1,NYP1 DO 310 I=1,NX DIFF(I,J)=RHO(I+1,J+1,KN)-RHO(I+1,J,KN) 310 С DO 320 J=1,NY DO 320 I=1,NX  $\mathsf{TEMP1}(I+1, J+1) = \mathsf{XOR}(\mathsf{YNTFLX}(I, J+1), \mathsf{DIFF}(I, J))$ 320 TEMP2(I,J) = XOR(YNTFLX(I,J), DIFF(I,J+1))С DO 330 J=1,NYF1 DO 330 I=1,NX TEMP5(I,J)=XOR(YNTFLX(I,J),DIFF(I,J)) TEMP6(I,J) = OR(TEMP1(I+1,J), TEMP2(I,J))FLX(I,J) = AND(TEMP5(I,J), TEMP6(I,J))FLX(I,J) = COMFL(FLX(I,J))IFLX(I,J) = LSHF(IFLX(I,J), -31)FLX(I,J)=FLOAT(IFLX(I,J)) 330 YNTFLX(I,J) = YNTFLX(I,J) \* FLX(I,J)С

A11

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С IF Y-COORDINATE IS PERIODIC AND EITHER BOTTOM OR TOP BOUNDARY'S ANTI-DIFFUSION FLUX IS CANCELLED, CANCEL THE OTHER С IF(.NOT.YPRDC) GO TO 335 С DO 334 I=1,NX YNTFLX(I,1) = ANE(YNTFLX(I,1), YNTFLX(I,NYF1)) YNTFLX(I,NYF1)=YNTFLX(I,1) 334 С 335 CONTINUE С С С EVALUATE NET INCOMING "FLXIN", OUTGOING "FLXOUT" ANTI-DIFFUSION DO 340 J=1,NY DO 340 I=1,NXP1 TEMP5(I,J) = ASHF(XNTFLX(I,J), -31)MNFLX(I,J) = ANE(XNTFLX(I,J), TEMP5(I,J))TEMP5(I,J) = XOR(XNTFLX(I,J), TEMP5(I,J))340 MXFLX(I,J) = AND(XNTFLX(I,J), TEMPS(I,J))С DO 350 J=1,NY DO 350 I=1,NX FLXIN(I+1,J+1)=1, E-50+MXFLX(I,J)FLXOUT(I+1,J+1)=1.E-50-MNFLX(I,J)FLXIN(I+1, J+1)=FLXIN(I+1, J+1)-MNFLX(I+1, J) 350 FLXOUT(I+1,J+1)=FLXOUT(I+1,J+1)+MXFLX(I+1,J) С DO 360 J=1,NYP1 DO 360 I=1,NX TEMP5(I,J) = ASHF(YNTFLX(I,J), -31)MNFLX(I,J) = AND(YNTFLX(I,J), TEMP5(I,J))TEMP5(I,J)=XOR(YNTFLX(I,J),TEMPS(I,J)) 360 MXFLX(I,J) = AND(YNTFLX(I,J), TEMP5(I,J))С DO 370 J=1,NY DO 370 I=1,NX FLXIN(I+1, J+1) = FLXIN(I+1, J+1) + MXFLX(I, J)FLXOUT(I+1,J+1)=FLXOUT(I+1,J+1)-MNFLX(I,J) FLXIN(I+1,J+1) = FLXIN(I+1,J+1) - MNFLX(I,J+1)370 FLXOUT(I+1,J+1) = FLXOUT(I+1,J+1) + MXFLX(I,J+1)С С GO TO (375,385) ILMTR С 375 CONTINUE С IF BORIS-BOOK FLUX LIMITER IS REQUESTED, USE TRANSFORTED-DIFFUSED С DENSITY TO BOUND NEW DENSITY DO 380 J=1,NYP2 DO 380 I=1,NXP2 380 TEMP5(I,J) = RHO(I,J,KN)С GO TO 395 С

С	385	CONTINUE IF ZALESAK FLUX LIMITER IS REQUESTED, USE MAXIMUM OF OLD AND
Ċ		TRANSPORTED-DIFFUSED DENSITY AS UPPER BOUND FOR NEW DENSITY DO 390 J=1,NYP2
	390	DO 390 I=1,NXP2 TEMP5(I,J)=AMAX1(RHO(I,J,KO),RHO(I,J,KN))
C	395	CONTINUE
С		DD 400 J=2,NYF1
С С		EVALUATE MAXIMUM ADMISSIBLE ANTI-DIFFUSION INTO CELL "MXIN", AND IN TURN CORRECTION FACTOR "RIN"
		DD 400 I=2,NXF1 TEMP6(I,J)=AMAX1(TEMP5(I,J),TEMF5(I-1,J))
		TEMP6(I,J)=AMAX1(TEMP6(I,J),TEMP5(I+1,J)) TEMP6(I,J)=AMAX1(TEMP6(I,J),TEMP5(I,J-1))
		RHOMX(I,J)=AMAX1(TEMP6(I,J),TEMP5(I,J+1))
		TEMP6(I, J) = RHOMX(I, J) - RHO(I, J, KN)
		TEMP6(I,J)=TEMP6(I,J)*DXGN(I) MXIN(I,J)=TEMP6(I,J)*DYGN(J)
		$TEMP6(I, J) \approx MXIN(I, J) / FLXIN(I, J)$
~	400	RIN(I,J)=AMIN1(1.0,TEMF6(I,J))
с с		GD TO (415,405) ILMTR
	405	CONTINUE
C C		IF ZALESAK FLUX LIMITER IS REQUESTED, USE MINIMUM OF OLD AND TRANSPORTED-DIFFUSED DENSITY AS LOWER BOUND FOR NEW DENSITY DO 410 J=1,NYP2
		DO 410 I=1,NXF2 TEMF5(I,J)=AMIN1(RHO(I,J,KO),RHO(I,J,KN))
С	410	TENFS(1,0)~AMINI(RAU(1,0,RD),RAU(1,0,RN))
_	415	CONTINUE
C C		EVALUATE MAXIMUM ADMISSIBLE ANTI-DIFFUSION OUT OF CELL "MXOUT", AND IN TURN CORRECTION FACTOR "ROUT" DO 420 J=2,NYP1 DO 420 I=2,NXP1
		TEMF6(I,J) = AMIN1(TEMF5(I,J),TEMF5(I-1,J))
		TEMP6(I,J)=AMIN1(TEMP6(I,J),TEMP5(I+1,J)) TEMP6(I,J)=AMIN1(TEMP6(I,J),TEMP5(I,J-1))
		RHOMN(I,J)=AMIN1(TEMP6(I,J),TEMP5(I,J+1))
		$TEMP6(\mathbf{I}, \mathbf{J}) = RHO(\mathbf{I}, \mathbf{J}, KN) - RHOMN(\mathbf{I}, \mathbf{J})$
		TEMP6(I,J)=TEMP6(I,J)*DXGN(I) MXDUT(I,J)=TEMP6(I,J)*DYGN(J)
		TEMPS(I,J)=MXOUT(I,J)/FLXOUT(I,J)
С	420	ROUT(I,J) = AMIN1(1,0,TEMF6(I,J))
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C C		IF A COORDINATE IS NOT PERIODIC, "RIN", ROUT " ARE ASSUMED TO BE CONTINUOUS THROUGH ITS NORMAL BOUNDARY DO 430 I=2,NXP1 RIN(I,1)=RIN(I,JB) RIN(I,NYP2)=RIN(I,JT)
С	430	ROUT(I,1)=ROUT(I,JB) ROUT(I,NYF2)=ROUT(I,JT)
J		DO 440 J=2,NYF1 RIN(1,J)=RIN(IL,J) RIN(NXF2,J)=RIN(IR,J) ROUT(1,J)=ROUT(IL,J)
С	440	ROUT(NXP2,J)=ROUT(IR,J)
	445	CONTINUE
С С		
		LIMIT ANTI-DIFFUSION FLUXES USING MINIMUM OF ADJACENT CELLS' MAXIMUM ADMISSIBLE FLUXES DO 450 J=1,NY DO 450 I=1,NXP1 FLX(I,J)=XNTFLX(I,J) IFLX(I,J)=LSHF(IFLX(I,J),-31) FLX(I,J)=FLOAT(IFLX(I,J)) RH0(I+1,J+1,KN)=AMIN1(RIN(I,J+1),ROUT(I+1,J+1)) XFLXCR(I,J)=FLX(I,J)*RH0(I+1,J+1,KN) RH0(I+1,J+1,KN)=AMIN1(RIN(I+1,J+1),ROUT(I,J+1))
С	450	FLX(I,J)=1.0-FLX(I,J) FLX(I,J)=FLX(I,J)*RHO(I+1,J+1,KN) XFLXCR(I,J)=XFLXCR(I,J)+FLX(I,J) XNTFLX(I,J)=XNTFLX(I,J)*XFLXCR(I,J)
J		D0 460 J=1,NYP1 D0 460 I=1,NX FLX(I,J)=YNTFLX(I,J) IFLX(I,J)=LSHF(IFLX(I,J),-31) FLX(I,J)=FLOAT(IFLX(I,J)) RH0(I+1,J+1,KN)=AMIN1(RIN(I+1,J),ROUT(I+1,J+1)) YFLXCR(I,J)=FLX(I,J)*RH0(I+1,J+1,KN) RH0(I+1,J+1,KN)=AMIN1(RIN(I+1,J+1),ROUT(I+1,J)) FLX(I,J)=1.0-FLX(I,J) FLX(I,J)=FLX(I,J)*RH0(I+1,J+1,KN) YFLXCR(I,J)=YFLXCR(I,J)+FLX(I,J)
C C	460	YNTFLX(I,J)=YNTFLX(I,J)*YFLXCR(I,J)

С			CODDEDTED ANTI STEELOIDN ELLYED AND ELALVATE NEW DENOTES
<u>ل</u>		ADD	CORRECTED ANTI-DIFFUSION FLUXES AND EVALUATE NEW DENSITY
			DO 470 J=1,NY
			DO 470 I=1,NX
			TEMP5(I,J) = XNTFLX(I,J) - XNTFLX(I+1,J)
			TEMP6(I,J)=YNTFLX(I,J)-YNTFLX(I,J+1)
			CELMAS(I,J) = CELMAS(I,J) + TEMPS(I,J)
			CELMAS(I,J) = CELMAS(I,J) + TEMP6(I,J)
			RVCL(I,J)≈RDXGN(I+1)*RDYGN(J+1)
	470		RHO(I+1,J+1,KR) = CELMAS(I,J) * RVOL(I,J)
С			
С		EVAL	UATE NEW DENSITY AT BOTTOM AND TOP BOUNDARIES
			DO 490 I=2,NXF1
			RHO(I,1,KR)=BBC(I)*RHO(I,JB,KR)+RHOBBC(I)
	490		RHO(I,NYP2,KR) = TBC(I) * RHO(I,JT,KR) + RHOTBC(I)
С			
c		EVAL	UATE NEW DENSITY AT LEFT AND RIGHT BOUNDARIES
-			BD 500 J=2,NYP1
			RHO(1, J, KR) = LBC(J) * RHO(IL, J, KR) + RHOLBC(J)
	500		RHO(NXP2, J, KR) = RBC(J) * RHO(IR, J, KR) + RHORBC(J)
С	300		
<b>L</b>			RETURN
~			
C			·
C			
С			

100.7

## ENTRY NGRID (XGN, YGN)

С	ENTRY NGRID(XGN, YGN)
C EVA C ANE C IF	LUATE AVERAGE ( BETWEEN OLD AND NEW ) INTERFACE VELOCITY AND AREA NEW AND AVERAGE VOLUME COMPONENTS. X-GRID OR Y-GRID IS NOT MOVING, USE ITS OLD VALUES. ERFACE VOLUME IS CONSIDERED AVERAGE OF ADJACENT CELLS' VOLUMES.
С	GO TO (510,520,530,540,550,560,570) GEOM
C 510	ÇONTINUE
	TESIAN COORDINATES
C	IF(.NOT.XCHNG) GO TO 513
C 511	DO 511 I=1,NXP1 XG(I)=0.5*(XGN(I)+XGO(I)) DXG(I)=XGN(I)-XGO(I)
C 512 C	DO 512 I=2,NXP1 DXGN(I)=XGN(I)-XGN(I-1) AX(I-1)=XG(I)-XG(I-1) RDXGN(I)=1.0/DXGN(I)
ັ 513 C	CONTINUE IF(.NDT.YCHNG) GO TO 580
516 C	DO 516 J=1,NYP1 YG(J)=0.5*(YGN(J)+YGO(J)) DYG(J)=YGN(J)-YGO(J)
517	DO 517 J=2,NYP1 DYGN(J)=YGN(J)-YGN(J-1) AY(J-1)=YG(J)-YG(J-1) RDYGN(J)=1.0/DYGN(J)
С	GO TO 580
C 520	CONTINUE
	INDRICAL R-Z CODREINATES
С	IF(.NDT.XCHNG) GD TO 523
C 521 C	DO 521 I=1,NXF1 SQO(I)=0.5*(XGO(I)*XGO(I)) SQN(I)=0.5*(XGN(I)*XGN(I)) XG(I)=SQN(I)+SQO(I) DXG(I)=SQN(I)-SQO(I) SQ(I)=SQRT(XG(I))

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С	522	DO 522 I=2,NXP1 DXGN(I)=SQN(I)-SQN(I-1) AX(I-1)=0.5*(XG(I)-XG(I-1)) RDXGN(I)=1.0/DXGN(I)
-	523	CONTINUE IF(.NOT.YCHNG) GO TO 580
С	526	DO 526 J=1,NYP1 YG(J)=0.5*(YGN(J)+YGO(J)) DYG(J)=YGN(J)-YGO(J)
С		DO 527 J≈2,NYP1 DYGN(J)=YGN(J)-YGN(J-1)
С	527	AY (J-1) = YG (J) - YG (J-1) RDYGN (J) = 1.0/DYGN (J)
С		GO TO 580
	530	CONTINUE
С	540	CYLINDRICAL R-FYE COORDINATES
С		CYLINDRICAL Z-FYE COORDINATES
С	550	CONTINUE SPHERICAL R-THETA COORDINATES
-	560	CONTINUE
С	570	SPHERICAL R-FYE COORDINATES CONTINUE
C	5/0	SPHERICAL THETA-FYE COORDINATES
С		PRINT 70
		STOP
С		

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580	CONTINUE
	IF(.NOT.XCHNG) GO TO 586
C	
	DXGN(1) = DXGN(IL)
	DXGN(NXP2)=DXGN(IR)
	RDXGN(1)=RDXGN(IL)
	RDXGN(NXP2)=RDXGN(IR)
C	
	DO 585 I=1,NXP1
	DXGNH(I)=0.5*(DXGN(I)+DXGN(I+1))
585	RDXGNH(I)=0.5*(RDXGN(I)+RDXGN(I+1))
С	
586	CONTINUE
	IF:.NOT.YCHNG> RETURN
С	
	DYGN(1) = DYGN(JB)
	DYGN(NYP2)=DYGN(JT)
	RDYGN(1) = RDYGN(JB)
_	RDYGN(NYP2)=RDYGN(JT)
С	
	DO 590 J=1,NYF1
	DYGNH(J) = 0.5*(DYGN(J) + DYGN(J+1))
590	RDYGNH(J) = 0.5 * (RDYGN(J) + RDYGN(J+1))
С	
-	RETURN
С	
С	
С	

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С	ENTRY OGRID(XGN,YGN)
С	ESET OLD GRID PARAMETERS, IN PREPARATION FOR A NEW TIME STEP
c	IF(.NOT.XCHNG) GO TO 593
592 C	DO 592 I=1,NXP2 DXGO(I)=DXGN(I)
593	CONTINUE IF(.NOT.YCHNG) GO TO 595
C _ 594	DO 594 J=1,NYP2 DYGO(J)=DYGN(J)
c c	GO TO 595
C C	ENTRY ORIGRD(XGN, YGN)
C C	
	RIGINATE THE GRID
C S	ET DEFAULT : GRID IS MOVING XCHNG=.TRUE. YCHNG=.TRUE.
C 595	CONTINUE IF(.NOT.XCHNG) GO TO 597
C 596	DO 596 I=1,NXF1 XGQ(I)=XGN(I)
C 597	CONTINUE IF(.NOT.YCHNG) RETURN
C 578	DO 598 J=1,NYF1 YGO(J)=YGN(J)
С	RETURN
С С С	

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ENTRY VOLFLX(U,V,DT) С С С EVALUATE X AND Y VOLUMETRIC FLUX THROUGH INTERFACES С С DT2=0.5\*DT С С DO 602 J=1,NY DO 602 I=1,NXP1 602 ADUDT(I, J) = U(I, J+1) + U(I+1, J+1)С DO 604 J=1,NYP1 DO 604 I=1,NX 604 ADVDT(I, J) = V(I+1, J) + V(I+1, J+1)С GD TO (610,620,630,640,650,660,670) GEOM С С 610 CONTINUE С С CARTESIAN COORDINATES С DO 611 J=1,NY DO 611 I=1,NXP1 ADUDT(I,J)=ADUDT(I,J)\*DT2 ADUDT(I,J) = ADUDT(I,J) - DXG(I)611 ADUDT(I,J) = ADUDT(I,J) \* AY(J)С DO 612 J=1,NYP1 DO 612 I=1,NX ADVDT(I,J)=ADVDT(I,J)\*DT2 ADVDT(I,J) = ADVDT(I,J) - DYG(J)ADVDT(I,J)=ADVDT(I,J)\*AX(I) 612 С RETURN С 620 CONTINUE С С CYLINDRICAL R-Z COORDINATES С DO 621 J=1,NY DO 621 I=1,NXP1 ADUDT(I,J)=ADUDT(I,J)\*SQ(I)\*DT2 ADUDT(I,J) = ADUDT(I,J) - DXG(I)621 ADUDT(I,J) = ADUDT(I,J) \* AY(J)С DO 622 J=1,NYP1 DO 622 I=1,NX ADVDT(I,J)=ADVDT(I,J)\*DT2 ADVDT(I,J) = ADVDT(I,J) - DYG(J)622 ADVDT(I, J) = ADVDT(I, J) \* AX(I)С RETURN С

A20

	630	CONTINUE
С		CYLINDRICAL R-FYE COORDINATES
	640	CONTINUE
С		CYLINDRICAL Z-FYE COORDINATES
	650	CONTINUE
С	•	SPHERICAL R-THETA COORDINATES
	660	CONTINUE
С		SPHERICAL R-FYE COORDINATES
	670	CONTINUE
С		SPHERICAL THETA-FYE COORDINATES
С		
		PRINT 70
		STOP
С		
С		
С		

ENTRY SORCES (SRCTYF, SORCE, DT) С С c MANAGEMENT OF SOURCE TERM EVALUATION С С IF (SRCTYP.EQ.BDF) GO TO 750 С IF (SRCTYP.EQ.XGRD) GD TO (760,800,999,999,999,999,999) GEOM IF (SRCTYP.EQ.YGRD) GO TO (780,780,999,999,999,999,999) GEOM С IF (SRCTYP.EQ.DIV) GO TO (760,950,999,999,999,999,999) GEOM С TEXT(6) = TEXT(18)TEXT(7) = TEXT(19)TEXT(8) = TEXT(20)PRINT 10, (TEXT(I), I=1, 11) С STOP С С С ENTRY CLRSRC С \_\_\_\_\_\_ С С CLEAR SOURCE TERM LSRC=.FALSE. DO 710 J=1,NY DD 710 I=1,NX 710 SOURCE(I,J)=0.С RETURN С С С ENTRY BODY (SORCE, DT) С С С EVALUATE BODY FORCE TYPE SOURCE TERMS 750 CONTINUE LSRC=.TRUE. С DO 755 J=1,NY DO 755 I=1,NX TEMP3(I,J) = AX(I) \* AY(J)TEMP4(I,J)=SORCE(I+1,J+1)\*DT TEMPS(I,J) = TEMPS(I,J) \* TEMP4(I,J)755 SOURCE(I,J) = SOURCE(I,J) + TEMP5(I,J)С RETURN С С c

~		I	ENTRY	XGRAD(SORCE,DT)
C C				
c c	760		UATE SRCTYP CONTIN LSRC=. DT2=0.1	UE TRUE.
c	765		00 765	J=1,NY I=1,NXP1 I,J)=SORCE(I,J+1)+SORCE(I+1,J+1)
С	770		DO 770 TEMP4 ( TEMP5 (	J=1,NY I=1,NX I,J)=TEMF3(I+1,J)-TEMF3(I,J) I,J)=TEMF4(I,J)*AY(J)*DT2 (I,J)=SOURCE(I,J)+TEMF5(I,J)
			IF (SRC	TYP.EG.DIV) GD TO 780
с _		I	RETURN	
000				
С		1	ENTRY	YGRAD(SORCE,DT)
с с с	780	1	UATE CONTIN LSRC=. DT2=0.	TRUE.
c	785		00 785	J=1,NYP1 I=1,NX I,J)=SORCE(I+1,J)+SORCE(I+1,J+1)
J	700		DO 790 TEMP4( TEMP5(	J=1,NY I=1,NX I,J)=TEMP3(I,J+1)-TEMP3(I,J) I,J)=TEMP4(I,J)*AX(I)*DT2
С	790		RETURN	(I,J)=SOURCE(I,J)+TEMF5(I,J)
С С С				

С	• •	ENTRY REGRAD(SORCE,DT)
C C	800	EVALUATE CYLINDRICAL R GRADIENT COMPONENT Continue LSRC=.TRUE.
С	805	DO 805 J=1,NY DO 805 I=1,NXP1 TEMP3(I,J)=SORCE(I,J+1)+SORCE(I+1,J+1) TEMP4(I,J)=SQ(I)*AY(J)*DT TEMP3(I,J)=0.5*TEMP3(I,J)
С	810	DO 810 J=1,NY DO 810 I=1,NX TEMP3(I,J)=TEMP3(I,J)*TEMP4(I+1,J) TEMP5(I,J)=TEMP4(I+1,J)-TEMP4(I,J)
0 000 000 0	815	DO 815 J=1,NY DO 815 I=1,NX TEMF4(I,J)=TEMF3(I+1,J)-TEMP3(I,J) TEMP5(I,J)=TEMP5(I,J)*SORCE(I+1,J+1) SOURCE(I,J)=SOURCE(I,J)+TEMF4(I,J) SOURCE(I,J)=SOURCE(I,J)+TEMF5(I,J) RETURN
	EV4 950	ENTRY REDIV(SORCE, DT)
		EVALUATE CYLINDRICAL DIVERGENCE CONTINUE LSRC=.TRUE. DT2=0.5*DT
С	955	DO 955 J=1,NY DO 955 I=1,NXP1 TEMP3(I,J)=SORCE(I,J+1)+SORCE(I+1,J+1) TEMP4(I,J)=SQ(I)*AY(J)*DT2
c c c	960	DD 960 J=1,NY DD 960 I=1,NX TEMP5(I,J)=TEMP3(I+1,J)-TEMP3(I,J) TEMP3(I,J)=TEMP5(I,J)*TEMP4(I+1,J) SOURCE(I,J)=SOURCE(I,J)+TEMP3(I,J)
		GD TO 780
	999	RETURN FRINT 70 STOP
С С С		A24

T

ENTRY SETGOM (GOMTRY, CRD1, CRD2, N1, N2) С \_\_\_\_\_ С С SET AND CHECK REQUEST FOR A PARTICULAR GEOMETRY С С GEOM=0 С IF (GOMTRY, EQ. TGM(1)) GEOM=1 С IF (GOMTRY.NE.TGM(2)) GD TO 1210 IF (CRD1.NE.TCRD(4)) GO TO 1205 IF (CRD2.EQ.TCRD(3)) GEOM=2 IF(CRD2.EQ.TCRD(6)) GEOM=3 1205 CONTINUE IF (CRD1.ED.TCRD(3).AND.CRD2.ED.TCRD(6)) GEOM=4 С 1210 CONTINUE IF (GOMTRY.NE.TGM(3)) GD TO 1220 IF(CRD1.NE.TCRD(4)) GO TO 1215 IF (CRD2.EQ.TCRD(5)) GEOM=5 IF (CRD2.EQ.TCRD(6)) GEOM=6 1215 CONTINUE IF (CRD1.EQ.TCRD(5).AND.CRD2.EQ.TCRD(6)) GEOM=7 С 1220 CONTINUE IF (GEOM.GT.O) GO TO 1225 С С ISSUE AN ERROR MESSAGE UPON REQUEST OF AN UNRECOGNIZED GEOMETRY С AND STOP TEXT(6) = TEXT(12)TEXT(7) = TEXT(13)TEXT(8) = TEXT(14)PRINT 10, (TEXT(I), I=1, 11) С STOP С 1225 CONTINUE С С NX=N1 NXP1=NX+1 NXP2=NX+2 С NY=N2 NYP1=NY+1 NYF2=NY+2 С XPRDC=.FALSE. IL=2IR=NXP1 С YFRDC=.FALSE. JB=2JT=NYP1 С LSRC=.FALSE. С A25

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C SEI	T DEFAULT : ALL BOUNDARIES ASSUMED FERMEABLE
	DO 1226 I=1,NXP2
	PRMBLB(I) = 1.0
100/	
1226	PRMBLT(I)=1.0
C	
	DO 1227 J=1,NYP2
	FRMBLL(J) = 1.0
1227	PRMBLR(J)=1.0
С	
	PRINT 30
С	
	RETURN
С	
C	
С	

	ENTRY PRODIC(CRDNT,CRD)
C	ستا بالله که که این های بی که این
C C	IDENTIFY X OR Y COORDINATE AS PERIODIC
C	IDENTIFY X OR Y COURDINATE AS PERIODIC
c	
	IF(CRDNT.NE.1) GO TO 1230
С	
	XPRDC=.TRUE. IR=2
	IR=2 IL=NXF1
С	ייט פעש דייריז מש הייניים איניים בייריד מי
	PRINT 40, CRD
C	
1230	CONTINUE IF(CRDNT.NE.2) GO TO 1240
С	
	YPRDC=.TRUE.
	JT=2
с	JB=NYF1
L	PRINT 40, CRD
С	
1240	CONTINUE
~	IF(CRD.EQ.TCRD(4).OR.CRD.EQ.TCRD(5)) PRINT 20,CRD
С	RETURN
С	<b>NETONA</b>
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С	

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-		ENTRY SETLMT (LMTR1, LMTR2)
0000	SET	AND CHECK REQUEST FOR A PARTICULAR FLUX LIMITER
		DO 1255 I=1,4
C 1251 C		DO 1251 J=1,2 IF(LMTR1(J).NE.TLM1(J,I)) GO TO 1255 CONTINUE
1252 C		DO 1252 J=1,2 IF(LMTR2(J).NE.TLM2(J,I)) GO TO 1255 CONTINUE
		GO TO 1260
C 1255 C		CONTINUE
C C		JE AN ERROR MESSAGE UFON REQUEST OF AN UNRECOGNIZED FLUX ITER AND STOP TEXT(6)=TEXT(15) TEXT(7)=TEXT(16) TEXT(8)=TEXT(17) PRINT 10, (TEXT(I),I=1,11)
С		STOP
C 1260		CONTINUE ILMTR=I
с с с с		RETURN
`		

~	ENTRY FIXGRD (CRDNT, CRD)
С С	
С	LABEL X OR Y GRID AS FIXED
C C	
L	IF(CRENT.NE.1) GO TO 1265
С	
	XCHNG=.FALSE.
С	PRINT 50, CRD
1265	CONTINUE
	IF (CRUNT.NE.2) GD TD 1270
С	
	YCHNG=.FALSE. Print 50, crd
С	FRINI JO, CRU
1270	CONTINUE
_	RETURN
C C	
C	

С	ENTRY SOLDFY (BONDRY, KSTRT, KEND)
С С	CANCEL THE DIFFUSION AND ANTI-DIFFUSION FLUXES THROUGH PATCHES OF BOUNDARY INTERFACES
c	IF(BONDRY.NE.TBND(1)) GO TO 1280
- 1275 C	DO 1275 J=KSTRT,KEND PRMBLL(J)=0.
C	PRINT 60, BONDRY,KSTRT,KEND
1280 C	CONTINUE IF(BONDRY.NE.T2ND(2)) GO TO 1290
1285 C	DO 1285 J=KSTRT,KEND PRMBLR(J)=0.
c	PRINT 60, BONDRY,KSTRT,KEND
1290 C	CONTINUE IF(BONDRY.NE.TBND(3)) GD TO 1300
1295 C	DO 1295 I≈KSTRT,KEND PRMBLB(I)=O.
c	PRINT 60, BONDRY,KSTRT,KEND
- 1300 C	CONTINUE IF(BONDRY.NE.TBND(4)) GO TO 1310
1305 C	DO 1305 I=KSTRT,KEND PRMBLT(I)=0.
С	PRINT 60, BONDRY,KSTRT,KEND
1310	CONTINUE RETURN
С С С	END

#### SUBROUTINE NUMU (NI, NJ, EPS, NUV, MUV)

### С С С

# EVALUATE DIFFUSION AND ANTI-DIFFUSION COEFFICIENTS

FARAMETER	NFX=100, NFY=100
PARAMETER	NP1X=NPX+1,NP1Y=NPY+1
PARAMETER	NP2X=NPX+2,NP2Y=NPY+2

С

REAL EPS(NP1X,NP1Y),NUV(NP2X,NP2Y),MUV(NP2X,NP2Y)

С

DO 100 J=1,NJ DO 100 I=1,NI EFS(I,J)=EFS(I,J)\*EFS(I,J) NUV(I,J)=0.333333\*EFS(I,J) NUV(I,J)=0.166667+NUV(I,J) MUV(I,J)=NUV(I,J)-EFS(I,J)

100 C

RETURN END