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LINEAR STABILITY OF THE MODIFIED BETATRON. (U)
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UNCLASSIFIED AMRC-R-354

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LINEAR STABILITY OF THE MODIFIED BETATRON

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April 1982

Prepared for: Office of Naval Research
800 North Quincy Street
Arlington, Virginia 22217

Under Contract: N00014-81-C-0647

Prepared by: MISSION RESEARCH CORPORATION
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### Linear Stability of the Modified Betatron

The linear stability of the modified betatron is investigated by deriving and numerically solving a dispersion relation. For nonresistive modes, growth rates significantly larger than those of previous calculations are obtained. The effects of a thermal spread in beam energy is estimated, and we conclude that there will be significant Landau damping of the most dangerous nonresistive and resistive modes.
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I. INTRODUCTION

The modified betatron concept,\textsuperscript{1-3} illustrated in Fig. 1, may provide a compact means of accelerating intense electron beams to high energies. A dispersion relation for the linear stability of the electron ring in the device has been derived by Sprangle and Vomvoridis.\textsuperscript{4} In this report, we show that some of the approximations in their derivation are not well justified, and we obtain more accurate expressions. In Sec. II, the approximation that the phase velocity of unstable waves is approximately the same as the beam velocity,\textsuperscript{4} \(V_p \approx V_b\), is discarded. This significantly alters the results obtained in two ways. Firstly, the growth rates obtained are typically two to ten times larger. Secondly, we find that the conventional negative mass instability does not exist in modified betatrons. Rather, the beam is subject to a predominantly transverse instability at high energies. We have made a rough estimate of the effect of a spread in beam energy on this mode. In Sec. III, we examine the effect of a moderate spread in beam energy on the transverse resistive wall instability. We find that in some cases, the effect is negligible because \(V_b - V_p\) is too large. For the most dangerous nonresistive and resistive instabilities, however, significant damping is expected.
II. LINEAR DISPERSION RELATION

A. Derivation

Our analysis follows that of Ref. 4, except that we assume a monoenergetic beam. The details of the derivation are given in the Appendix, and here we give only the main points. The beam is modeled as a circulating ring of charge which can displace rigidly in the transverse direction and which can compress in the toroidal direction (see Fig. 1).

In equilibrium, the beam is positioned at the center of the minor cross-section of the torus, and executes a cyclotron orbit in the mirror $B_z$ field. Toroidal corrections to the field equations are dropped, so that the $m = 0$ and $m = 1$ fields are not directly coupled. They are, however, coupled via the perturbed charge and current. Thus, the $m = 0$ component of the charge density $\rho$ satisfies

$$\frac{\partial \rho}{\partial t} + \frac{\rho V_r}{r} + \frac{\partial}{\partial \theta} \frac{\rho V_\theta}{r} = 0,$$

where $r(\theta)$ is the radial location of the center of the beam, and $V_r, V_\theta$ are the beam velocity components. The second term in Eq. (1) shows that a rigid transverse ($m = 1$) displacement contributes to the perturbed net ($m = 0$) charge density. Contributions from perturbed $m = 0$ quantities to the $m = 1$ charge density are second order in the beam transverse displacement, and so do not enter the linear dispersion relation. Consequently, the perturbed $m = 1$ fields can be computed directly in terms of the transverse displacements of the beam. The results are substituted into the $m = 0$ field equation for the perturbed toroidal electric field $E_\theta(1)$, namely

$$\nabla^2 E_\theta(1) = \left(\nabla \rho(1) + \frac{\partial j(1)}{\partial t}\right)_\theta$$

$$= i\varepsilon/r_\theta \rho(1) - i\omega j(1).$$
(see Appendix for definitions and normalizations.) Linearizing Eq. (1), we obtain

$$V_{E_0}^2 = \frac{iE}{r_0} \frac{\rho_0}{\Delta \omega} \left( \frac{1}{r_0} \nu_0(1) - \frac{iV_1^r(1)}{r_0} \right) \left( 1 - \frac{\omega^2 r_0^2}{\ell^2} \right) + \frac{\rho_0 \omega V_r(1)}{r}$$

(2)

Solving this equation with appropriate conducting wall boundary conditions yields the linear dispersion relation

$$1 = \frac{1}{4} \rho_0 r_0^2 \left( \frac{1}{\gamma_0^2} \frac{\Delta \omega}{r_0^2} \left( 1 - \frac{\omega^2 r_0^2}{\ell^2} \right) \left( \frac{1}{\gamma_0^2} - \frac{\omega_0^2/\gamma_0}{\Delta \omega} \left( \omega_z - \Delta \omega^2 - \xi \right) \right) \right)$$

$$\frac{\omega_0^2/\gamma_0}{\Delta \omega} \left( \omega_z - \Delta \omega^2 - \xi \right) \right)$$

(3)

This equation differs from the results of all earlier work in that the approximation \( \omega = \omega_0^2/\gamma_0 \) has not been made. Also, the first term on the second line is new.

B. Nonresistive Instabilities

Equation (3) has some unstable roots due to the coupling of longitudinal and transverse modes of oscillation. The instabilities persist when the wall conductivity is infinite. The instabilities are low frequency in the sense the transverse component of their motion is associated with the slow rotation frequency \( \omega_B = \omega_r r_0/(\rho_0/\gamma_0) \). The beam can also oscillate transversely at the fast rotation frequency, \( \rho_0/\gamma_0 \), but there are no nonresistive instabilities associated with this resonance.
We can clarify the origin of the nonresistive instabilities by simplifying Eq. (3). We assume $\omega_0^2 < \Omega_0^2 / \gamma_0$, $\Delta \omega^2 < \omega_z^2$ and obtain

$$P = \frac{1}{4} \rho_0 r_b^2 (1 + 2\pi n a/r_b) \left[ \frac{\pi^2 - \omega^2}{\Delta \omega^2} - \frac{\omega a^2}{\Delta \omega^2} \left( \Delta \omega - B_z/\gamma_0^3 \right) \right] = 1$$

where $\alpha = \gamma_0^2 (1 - n - n_s r_b^2 / a^2)$. The function $P(\Delta \omega)$ has a different character depending on whether $|\omega_B| < \gamma_0^3 / \gamma_0^3$ or $|\omega_B| > \gamma_0^3 / \gamma_0^3$, as shown in Fig. 2. For typical betatron parameters, the point $|\omega_B| = \gamma_0^3 / \gamma_0^3$ occurs approximately at $\gamma_0 = \gamma_{\text{tran}} = [4\pi r_0^2 / a^2]^{1/3}$ where $\pi$ is Budker's parameter. When $\gamma_0 < \gamma_{\text{tran}}$, the roots of the quartic $P(\Delta \omega) = 1$ consist of two complex conjugate pairs. For $\gamma_0 > \gamma_{\text{tran}}$, we have two real roots and a complex conjugate pair. We note that the conventional negative mass instability is not present in typical modified betatrons. The derivation of the dispersion relation for the latter instability involves the replacement of $\gamma_f^2 = (1 - \omega^2 r_0^2 / a^2)^{-1}$ by $\gamma_B^2 = (1 - \gamma_B^2)^{-1}$ in the field equation. This procedure is valid only if $2\gamma_0 (1 + 2\pi n a/r_b) < 1$ which is not the case for modified betatron parameters (cf. Table 1).

Frequencies and growth rates for the $\ell = 1, 2, 3,$ and 4 nonresistive modes obtained by solving Eq. (3) numerically for the parameters in Table 1 are given in Figs. 3, 4, and 5. As we have seen, for $\gamma_0 < \gamma_{\text{tran}}$ there are two unstable modes, one with $\omega > \gamma_0 Z_0 / \gamma_0$, the other with $\omega < \gamma_0 Z_0 / \gamma_0$, and we term these modes "fast" and "slow" accordingly. In Figs. 3 and 4, only the slow modes are depicted for clarity. The maximum growth rates are for $\gamma_0 > \gamma_{\text{tran}}$, and since most of the acceleration period lies in this region, we shall examine the region more closely. For $\alpha = 2\gamma_0^2 > 1$, Eq. (3a) reduces to

$$\Delta \omega (\Delta \omega^2 - \omega_B^2) + \nu (1 + 2\pi n a/r_b) \omega a^2 / \gamma_0^3 = 0$$

(3b)
The condition for this cubic in $\Delta \omega$ to have complex roots is $v(1 + 2\pi a/r_b) \omega \gamma_0^3 > 2 \omega B/(3\sqrt{3})$. This criterion yields the upper bound on the unstable range of $\gamma_0$, namely

$$\gamma_{\text{max}} = (6\sqrt{3}v \gamma_0 (1 + 2\pi a/r_b) B_{80})^{1/2}$$

where we have assumed $\omega B < \Omega_2 \gamma_0$. This expression gives $\gamma_{\text{max}} = 153$ for the parameters in Table 1(a). The exact numerical results give $\gamma_{\text{max}} = 156$.

For $\gamma_0^2 < \gamma_{\text{max}}^2$ the complex roots of Eq. (3b) are given approximately by

$$\Delta \omega = [\gamma_0 v (1 + 2\pi a/r_b)/(2r_0^5 B_{80})]^{1/3} e^{i\phi},$$

where $\phi = 2\pi/3, 4\pi/3$. Thus, the growth rate scales as $\lambda^{1/3}, B^{-2/3}$, etc. For the parameters in Table 1(a), this expression yields $\omega = 6.81 \times 10^{-3} + i 2.4 \times 10^{-4}$ for $\gamma_0 = 50$, compared to the exact answer $\omega = 6.82 \times 10^{-3} + i 2.1 \times 10^{-4}$. Numerically we find that throughout most of the range of this instability we have $\Delta \omega = \omega_B$, so that the mode is mostly transverse in character. The conventional negative mass instability is longitudinal in character, being associated with the $\Delta \omega = 0$ resonance.

A comparison between our dispersion relation, Eq. (3) and that in Ref. 4 is given in Fig. 6. The mathematical differences between the two dispersion relations were described in Sec. IIA. Equation (3) gives growth rates which are two to ten times larger than those from Ref. 4. We discuss the effect of a thermal spread in energy on these instabilities in subsection D below.

C. Resistive Wall Instabilities

The presence of resistive material in the walls of the betatron gives rise to additional instabilities, and modifies the growth rates of nonresistive instabilities. To illustrate this effect, we have chosen a stainless steel wall, for which the conductivity $\sigma$ is $5.2 \times 10^6$ in normalized
units (see Appendix). The results for the \( \lambda = 1 \) mode are shown in Fig. 7. The resistive wall has little effect on the nonresistive instabilities. However, some modes whose growth rates are zero for \( \sigma = \infty \) are driven unstable by the resistivity. They are, the fast mode in the region \( \gamma_0 < \gamma_{\text{tran}} \) and a slow mode in the region \( \gamma_0 > \gamma_{\text{tran}} \), denoted by A and B respectively in Fig. 7(a). (In Fig. 7(b), branch A' is unstable even for \( \sigma = \infty \).) Branch B is due mainly to the term \( \varepsilon_{11} \) in Eq. (3). The growth rates of this branch are much smaller than those obtained by using the approximate \( \varepsilon_{11} \) in Ref. 4. Since the resistive modes are driven by boundary condition at the wall, they are sensitive to the value of \( a, \) the minor radius of the torus. This is why the resistive mode growth rate smaller in Fig. 7 than in Fig. 6 (cf. Table 1). The growth rate is approximately independent of \( \gamma_0 \).

The slow mode associated with the toroidal magnetic field cyclotron resonance, \( \omega = \frac{2\Omega_0}{\gamma_0 - \gamma_{\theta_0}} \) is also driven unstable by wall resistivity. As indicated in subsection B, none of the modes associated with this resonance are unstable when \( \sigma = \infty \). With finite wall conductivity the mode, which is primarily a transverse oscillation, becomes unstable when \( \omega \) goes through zero and becomes positive. In a betatron, \( \Omega_0 = \gamma_0 \) during the acceleration, so that the instability turns on when \( \Omega_0 = \Omega_{\theta_0}/\lambda \) and continues for the remainder of the acceleration period. This behavior is shown in Fig. 8. Again, the difference in growth rates between the two parts of the figure is due mainly to the differences in the quantities \( a \) and \( B_{\theta_0} \) in Table 1. For large \( \gamma_0 \), the growth rate is approximately independent of \( \gamma_0 \).

D. Practical Implications for Betatrons

For the sample parameters given in Table 1, it is clear that the nonresistive instability in the region \( \gamma_0 < \gamma_{\text{tran}} \) is the most important instability. Thus, for the parameters in Table 1(a), the number of e-
foldings of the $l=1$ component during a 1 millisecond acceleration time is about 4000. This result is for a monoenergetic beam, and gives an upper bound on the growth. We can estimate the effect of a spread in beam energy as follows. The thermal spread enters the model in the combination $\omega - \omega_0 = \omega_0 (\Omega_{zo}/\gamma_0 - k\Delta P_0)$, where $\Delta P_0$ is the spread in canonical toroidal momentum (cf. Eq. (4)). The instability for $\gamma_0 > \gamma_{tran}$ is associated with the resonance $\Delta \omega = \omega_B$. Therefore, a small-thermal-expansion for this mode is an expansion in the parameter $e^2 = (k\Delta P_0)^2/(\Delta \omega - \omega_B)^2$. If $e^2 \ll 1$, Landau damping is negligible, whereas if $e^2 > 1$, we expect significant damping. As an example, we use the numerical results shown in Fig. 3(a), and assume an initial spread in $\gamma_0$ of 5%. Then, for the $l=1$ mode at $\gamma_0 = 50$, we obtain $e^2 = 4$, so that we can expect a significant reduction in growth rate. A more rigorous treatment of thermal effects is needed to confirm this result.
III. THERMAL EFFECTS ON RESISTIVE INSTABILITIES

It has been suggested that a moderate spread in beam particle energies may reduce instability growth rates to acceptably low values through Landau damping. Here we look at the effect of a thermal spread on the transverse cyclotron resistive wall instability. We choose this case because the dispersion relation, Eq. (4) is relatively simple and does not require numerical solution.

A. High Frequency Limit: $\delta/a << 1$

From Ref. 4 the approximate dispersion relation for the cyclotron mode including thermal effects is

$$1 + \Omega_s^2 \int \frac{g(\Delta P) \ d\Delta P}{\omega_r - \Delta \omega + \Delta \omega_\delta / \gamma_0} = 0,$$

where, in normalized units,

$$\Delta \omega = \omega - k(\Omega_{zo}/\gamma_0 - k \Delta P),$$

$$k = \frac{1}{\gamma_0 r_0^2} \left( \frac{1}{\gamma_0} - \frac{1}{n - n_s} \right),$$

$$\Omega_s^2 = n_s (1 - r_b^2/a^2) [1 - \rho_0^2 \gamma_0^2 (1 + i) \frac{r_b^2}{a^2} \frac{\delta}{a}] \frac{\Omega_{zo}^2}{\gamma_0^2}$$

$$\delta = \left( \frac{2}{\omega_0} \right)^{1/2},$$

$$\omega_r^2 = \left( \frac{1}{2} - n_s \right) \Omega_{zo}^2 / \gamma_0^2, \ (n = 1/2 \ is \ assumed)$$

$g(\Delta P)$ = distribution function of toroidal canonical momentum spread. See Appendix for additional definitions.
Write $\Delta \omega^2 - \omega_r^2 = \Delta \omega \Delta \theta_0 / \gamma_0 = (\Delta \omega + \varepsilon k \Delta P - a_1) (\Delta \omega + \varepsilon k \Delta P - a_2)$. Assuming $|a_2| >> |a_1|$, the instability comes from the following choice of roots,

$$a_1 = \frac{\omega_r^2 \gamma_0}{\Delta \theta_0}, \quad a_2 = -\Delta \theta_0 / \gamma_0.$$  (5)

For $g$, choose a flat-topped distribution function,

$$g(\Delta P) = \frac{1}{2\Delta P_0} \quad \text{for} \quad |\Delta P| < \Delta P_0,$$

$$g(\Delta P) = 0 \quad \text{for} \quad |\Delta P| > \Delta P_0.$$  (6)

Performing the integration in Eq. (4), we get

$$1 + \frac{\Omega^2_s}{2 \varepsilon k \Delta P_0 (a_1 - a_2)} \ln \frac{\Delta \omega_0 - \varepsilon k \Delta P_0 - a_2}{\Delta \omega_0 + \varepsilon k \Delta P_0 - a_2} \cdot \frac{\Delta \omega_0 + \varepsilon k \Delta P_0 - a_1}{\Delta \omega_0 - \varepsilon k \Delta P_0 - a_1} = 0,$$  (7)

where $\Delta \omega_0 = \omega - \varepsilon \Omega_0 / \gamma_0$. The mode we are concerned with has $\Delta \omega = a_2$. To do a small-thermal-spread expansion, we assume $\Delta \theta_0 << \Delta \omega - a_2$.

In what follows, we shall in essence be checking the consistency of these two approximations. Expanding Eq. (7), we obtain

$$1 - \frac{\Omega^2_s}{a_2^2} \left( \frac{1}{\Delta \omega_0 - a_2} + \frac{1}{3} \frac{(\varepsilon k \Delta P_0)^2}{(\Delta \omega_0 - a_2)^3} \right) = 0.$$
Assuming \( \delta/a \ll 1 \), the real part of the frequency, \( \Delta \omega_r \), is

\[
\Delta \omega_r = -\Omega_{\theta 0}/\gamma_0 - \frac{\Omega_s^2}{\Omega_{\theta 0}/\gamma_0} \left( 1 + \frac{1}{3} \frac{(\Delta k \Delta P_0)^2}{(\Delta \omega_r - \alpha_2)} \right)
\]

(8)

Our expansion parameter is thus

\[
\epsilon = \left| \frac{\Delta k \Delta P_0}{\Delta \omega_r - \alpha_2} \right| = \frac{\Delta k \Delta P_0 \Omega_{\theta 0}/\gamma_0}{\Omega_s^2}
\]

With \( \Delta P_0 \equiv \gamma_{th} r_0 \), and \( \gamma_0 \) large enough such that \( n_s \ll 1 \), we have

\[
\epsilon = \frac{4 \Delta k \Omega_{\theta 0}^2 r_0^2}{n_0 r_0} \cdot \frac{\gamma_{th}}{\gamma_0}
\]

If \( \epsilon \ll 1 \) for a given choice of parameters, then our small-thermal-spread expansion is valid. In this limit, there is no Landau damping from a flat-topped distribution. If \( \epsilon \gg 1 \), on the other hand, the phase velocity of the mode lies well within the distribution of particle velocities. The mode is then highly damped. Putting in numbers from Table 1(a) with \( \gamma_0 = 50 \), we obtain \( \epsilon = 3.3 \times 10^3 (\gamma_{th}/\gamma_0) \). Assuming a 10% spread in \( \gamma_0 \) at the beginning of the acceleration period, we have \( \gamma_{th} = 0.5 \). Thus \( \epsilon = 33 \) at \( \gamma_0 = 50 \). Consequently, there will be significant Landau damping of this mode.

B. **Low Frequency Limit: \( \omega = 0 \)**

When \( \omega = 0 \), the small-thermal-spread expansion of Eq. (7) leads to

\[
\frac{\Omega_{so}^2}{\alpha_2} n e^{i\pi/4} \left( 1 + \frac{1}{3} \epsilon \right) = 0
\]

(9)

where \( \Omega_{so}^2 = n_s (1 - r_b^2/a^2) \Omega_{z0}/\gamma_0^2 \), and \( n = \beta_{so}^2 r_b^2/a^3 (2/a)^{1/2} \). The
unstable solutions to Eq. (9) are

\[ \omega = \frac{\Omega_s^2}{\Omega_0} \frac{n}{\gamma_0} \left( 1 + \frac{e}{3} \right)^{2/3} \cos \phi \]  

(10)

where \( \phi = \pi/6, -7\pi/6 \). In this case, we obtain

\[ \epsilon = \frac{\gamma_{th}}{\gamma_0} \frac{e a^2}{2 \gamma_0} \left( \frac{\Omega_0^2}{2 \gamma_0} \right)^{2/3} \left( \frac{a}{2} \right)^{1/3} \]

For the parameters in Table 1(a), we obtain \( \epsilon = 27(\gamma_{th}/\gamma_0) \). Thus, for an initial 10% spread in \( \gamma_0 \), there will be substantially less Landau damping in this case than where \( \delta/a \ll 1 \). For the parameters in Table 1(b), \( \epsilon = 4(\gamma_{th}/\gamma_0) \). In this case, Landau damping will be negligible, and Eq. (10) shows that there will be a slight increase in the growth rate due to thermal effects.
IV. SUMMARY

We have rederived the dispersion relation for linear instabilities in betatrons based on the simple model of Ref. 4. Our analysis shows that at high beam energies, the dispersion relation does not reduce to that of the conventional negative mass instability. Instead, we find a mode which is primarily transverse in nature. Furthermore, we obtain growth rates which are from two to ten times larger than those obtained in previous calculations. We have estimated the effects of a moderate spread in beam energy on nonresistive and resistive instabilities, and find that significant damping is expected. A more rigorous calculation is needed to prove this.

ACKNOWLEDGEMENTS

We would like to thank Dr. P. Sprangle for useful conversations. This research is supported by the Office of Naval Research contract N00014-81-C-0647, monitored by C. Roberson.
Figure 1 illustrates the physical parameters of the system. The beam is modeled as a line of charge. In equilibrium, it is situated at \( r = r_0 \), \( z = 0 \), and executes a cyclotron orbit in the mirror \( B_z \) field.

As pointed out in Sec. IIA, only the transverse motion of the beam needs to be considered when computing the perturbed transverse fields. When the center of the beam is displaced rigidly to position \( (r_0 + \Delta r, \Delta z) \), it experiences the following fields:

**Applied fields:**

- \( B_z = B_{z0} (1 - n \Delta r/r_0) \),
- \( B_r = -B_{z0} \frac{n \Delta r}{r_0} \), \hspace{1cm} (A1)
- \( B_\theta = B_{\theta0} (1 - \Delta r/r_0) \).

**Induced fields:**

- \( E_r^{(1)} = \frac{n}{2} \frac{r_b^2}{a^2} \Delta r \),
- \( E_z^{(1)} = \frac{n}{2} \frac{r_b^2}{a^2} \Delta z \),
- \( B_r^{(1)} = \frac{n_0 v_{\theta0}}{2} \left( \frac{r_b^2}{a^2} - (1 - r_b^2/a^2) \xi \right) \Delta z \), \hspace{1cm} (A2)
- \( B_z^{(1)} = -\frac{n_0 v_{\theta0}}{2} \left( \frac{r_b^2}{a^2} - (1 - r_b^2/a^2) \xi \right) \Delta r \), \hspace{1cm} (A2)

where \( \xi = (1 + 1) \frac{r_b^2}{a^2} - \frac{r_b^2}{a^2} \left( \frac{2}{\sigma a^2} \right)^{1/2} \).
In our normalization scheme, frequencies are normalized to \( \omega_0 \) which is defined by \( c/\omega_0 = 1 \text{ cm} \). Lengths are normalized to \( c/\omega_o \), velocities to \( m\omega_0/e \), and densities to \( \omega_0^2 m/4\pi e^2 \), where \( m \) and \( e \) are the electronic mass and charge respectively. Thus, for example, \( B_{zo} \) and \( \Omega_{zo} \) have the same normalized values. The conductivity is normalized to \( \omega_0/4\pi \). In Eqs. (A1) and (A2) above \( n \) is the external field index, i.e., \( r_0 \partial/\partial r \& B_2(r_0) \), \( n_0 \) is the equilibrium beam density and \( V_{\theta 0} \) is the equilibrium azimuthal beam velocity. A positive beam charge is assumed. The equations of motion of a beam particle are,

\[
\begin{align*}
- \gamma \frac{V^2}{r} + \frac{dp_r}{dt} &= E_r + V_0 B_z - V_z B_0 , \\
\frac{dp_z}{dt} &= E_z + V_r B_0 - V_\theta B_r , \\
\gamma \frac{V_\theta V_r}{r} + \frac{dp_\theta}{dt} &= E_\theta + V_z B_r - V_r B_z ,
\end{align*}
\]

where \((V_r, V_\theta, V_z)\) and \((p_r, p_\theta, p_z)\) are the velocity and momentum components of a beam particle. Linearizing these equations, we obtain

\[
\Delta \vec{r} + (\omega_r^2 - \bar{\xi}) \Delta r + \Delta \vec{z} \frac{B_{zo}}{\gamma_0} = - \gamma_0 \frac{B_{zo}}{\gamma_0} V^{(1)} ,
\]

\[
\Delta \vec{z} + (\omega_z^2 - \bar{\xi}) \Delta z - \Delta \vec{r} \frac{B_{zo}}{\gamma_0} = 0 ,
\]

\[
\frac{dV_\theta^{(1)}}{dt} = \frac{E_\theta^{(1)}}{\gamma_0^3} ,
\]

(A3)
where the superscript \((1)\) denotes perturbed quantities,
\[
\omega_R^2 = (1 - n - n_s r_b^2/a^2) B_{zo}/\gamma_0, \quad \omega_z^2 = (n - n_s r_b^2/a^2) B_{zo}/\gamma_0, \quad n_s = n_0/(2\gamma_0 B_{zo})
\]
and \(\xi = n_s^2 \gamma_0^2 (1 - r_b^2/a^2) B_{zo}/\gamma_0^2\). Assuming \(\Delta r, \Delta z - \exp(-i\omega t + i\xi)\), we obtain the following solutions to Eqs. (A3),
\[
\begin{align*}
\Delta r &= \frac{V^{(1)} \gamma_0 (\Delta \omega^2 - \omega_z^2 + \xi)}{D} B_{zo}/\gamma_0, \\
\Delta z &= \frac{V^{(1)} \gamma_0^2 (B_{zo}/\gamma_0)(B_{zo}/\gamma_0)}{D},
\end{align*}
\]
where \(\Delta \omega = \omega - \xi V_{\theta_0}/r_0\) and \(D = (\Delta \omega^2 - \omega_R^2 + \xi)(\Delta \omega^2 - \omega_z^2 + \xi) - \Delta \omega^2 B_{zo}^2/\gamma_0^2\).

Using the third member of Eqs. (A3), \(V^{(1)}\) can be expressed in terms of \(E\), the only unknown. To close the system, we obtain a field equation for \(E\). We assume that the beam excites only the \(m = 0\) component of \(E^{(1)}\). This is reasonable provided \(r_b \ll a\), since higher \(m\) number components go to zero at the center of the minor cross section of the torus. Further, we assume that only the lowest radial mode is excited, so that the eigenfunction is approximately constant over the beam cross section. This is valid provided \(|\xi/r_0| - |\omega| \ll 2\pi/a\). Then from Maxwell's equations we obtain
\[
V \mathbf{E}^{(1)} = i \rho^{(1)}/r_0 - i \omega_j^{(1)},
\]
where "\(\perp\)" refers to the transverse direction, \(\rho^{(1)}\) is the perturbed charge density, and \(j^{(1)}\) is the perturbed azimuthal current. Since the eigenfunction is assumed to be flat in the center, the perturbed charge density \(\rho^{(1)}\) is proportional to the perturbed line charge \(V^{(1)}\). To obtain an expression for \(V^{(1)}\) we use the continuity equation for \(\rho\).
\[ \frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{v}) = 0. \]  

(A6)

Put \( \rho = \rho_0 (R - R_0(\theta)) \delta(\phi - \phi_0(\theta))/R \), where \( R, \phi \) are local cylindrical coordinates \( (r - r_0 = R \cos \phi, z = r \sin \phi) \), and \( (R_0, \phi_0) \) is the position of the displaced beam. Multiplying Eq. (A6) by \( \int R dR d\phi \), we obtain

\[ \frac{3v}{3t} + \frac{V_r}{r} + \frac{3}{3\phi} \left( \frac{V_\theta}{r} \right) = 0 \]  

(A7)

Linearizing, and replacing \( v \) by \( \rho \), we have

\[ \rho^{(1)} = \left( \frac{\rho_0 \mathbf{v}^{(1)}}{r_0} - \rho_0 \omega r^{(1)} / r_0 \right) / \Delta \omega \]

\[ J^{(1)}_\theta = \omega (\rho_0^{(1)} + r^{(1)} \rho_0) / \xi \]

where \( \rho_0 \) is the unperturbed charge density. Equation (A5) becomes

\[ \nabla^2 \mathbf{E}^{(1)} = -\frac{\varepsilon \rho_0 \mathbf{E}^{(1)}}{\gamma \Delta \omega} \left\{ \frac{1}{r^2} \right\} + \frac{\varepsilon B_0 / \varepsilon_0}{\Delta \omega} \left( \omega_z^2 - \Delta \omega^2 - \bar{\xi} \right) \left( 1 - \frac{\omega_0^2}{c^2} \right) \]

\[ \nabla^2 \mathbf{E}^{(1)} = \varepsilon \mathbf{E}_0^{(1)} \]

(A8)

To obtain the dispersion relation, we need to solve

\[ \nabla^2 \mathbf{E}^{(1)} = \mathbf{A} \mathbf{E}_0^{(1)} \]

\[ r < r_b \]

\[ \nabla^2 \mathbf{E}^{(1)} = 0 \]

\[ r_b < r < a \]

\[ \nabla^2 \mathbf{E}^{(1)} = -i \omega \mathbf{E}_0^{(1)} \]

\[ r > a. \]
together with the following boundary conditions,

\[ E_\theta^{(1)} , \quad \frac{\partial E_\theta^{(1)}}{\partial r} \text{ continuous at } r = r_b , \]

\[ E_\theta^{(1)} = -\frac{\omega (i + 1)}{\omega^2 - \frac{1}{\omega^2} \frac{r^2}{r_0^2}} \left( \frac{\omega}{2r_0} \right)^{1/2} \frac{\partial E_\theta^{(1)}}{\partial r} \text{ at } r = a . \]

As a result, we obtain

\[ 1 = \frac{1}{4} \rho_0 r_b^2 (1 + 2i\pi \ln a/r_b) [1 - (i + 1)\varepsilon_{11}] \]

\[ x \left[ \frac{x}{\gamma_0 \omega^2 r_0^2} \right] (1 - \frac{\omega^2 r_0^2}{\omega^2}) \left[ \frac{x}{\gamma_0} + \frac{\omega B_0}{\gamma_0} \left( \omega_z^2 - \omega^2 - \overline{\varepsilon} \right) \right] \]

\[ + \frac{\omega}{\sqrt{\gamma_0 \Delta \omega}} \left( \omega_z^2 - \omega^2 - \overline{\varepsilon} \right) \]

\[ \varepsilon_{11} = \frac{\omega_r^2 / \omega^2 (2/\omega_0^2)^{1/2}}{(1 - \omega_r^2 / \omega^2)(1 + 2i\pi \ln a/r_b)} . \]

For a negatively charged beam, we let \( B_0 \Rightarrow B_z \).
REFERENCES

The values for $B_{\theta 0}$ are approximate practical upper and lower bounds.

<table>
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<tr>
<th>QUANTITY</th>
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<td>Acceleration Time</td>
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<td>$3 \times 10^7$ cm (1 millisecond)</td>
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Figure 1. Illustration of modified betatron concept. The major radius of the torus is $r_0$, the minor radius is $a$ and the beam radius is $r_b$. The external magnetic fields consist of a focusing mirror field $B_z$ and a toroidal field $B_0$. 
Figure 2. Illustration of nonresistive instabilities in betatrons. The dispersion relation is \( P = 1 \). The roots are denoted by \( r_1, r_2, \) etc., and brackets \( (,) \) denote complex conjugate pairs. In (a) and (b), we depict two regimes of instability in the modified betatron. In (c), we show the origin of the longitudinal negative mass instability, which requires \( A < 1 \).
Figure 3. Real and imaginary parts of the nonresistive $l = 1, 2, 3, 4$ modes obtained by solving Eq. (3) numerically for the equilibrium parameters given in Table 1(a). The frequencies are in units of $3 \times 10^{10}$ sec$^{-1}$. For $Y_o < Y_{tran}$, only the slow mode is included (cf. Fig. 2).
Figure 4. Growth rates of the nonresistive $\ell = 1, 2, 3, 4$ instabilities for the parameters in Table 1(b).
Figure 5. Growth rates of the fast (dashed lines) and slow (solid lines) branches of the nonresistive instabilities in the region $\gamma_0 < \gamma_{\text{tran}}$. In going through $\gamma_{\text{tran}}$, the fast modes join onto the instabilities in the region $\gamma_0 > \gamma_{\text{tran}}$, while the slow modes join onto modes with zero growth rate. The betatron parameters are those of Table 1(a).
Figure 6. Comparison between growth rates obtained from Eq. (3) (Curve A) and those obtained from the dispersion relation in Ref. 4 (Curve B), for the nonresistive $\epsilon = 1$ instability. The betatron parameters are from Table 1(a).
Figure 7. Growth rates for the $\ell = 1$ instability with perfectly conducting walls (dashed lines) and stainless steel walls (solid lines). Part (a) is for the parameters in Table 1(a), and part (b) is for parameters in Table 1(b). Branches A and B are modes which have become unstable due to the wall resistivity alone. In part (b) the solid and dashed lines are indistinguishable (the growth rate of Branch B is approximately $4 \times 10^{-6}$ cm$^{-1}$). Branch A' is unstable for even $\sigma = \infty$. 
Figure 8. Growth rates of the transverse resistive wall cyclotron mode. Part (a) is for the parameters in Table 1(a) and part (b) is for those in Table 1(b). For (a), \( \ell = 20 \) and for (b) \( \ell = 5 \). The instability turns on when \( \Omega z_0 = \Omega e_0/\ell \) i.e., \( y_0 = B\Omega e_0/\ell \) (= 45 for case (a)). The height of the initial peak is independent of \( \ell \) and \( y_0 \) (cf. Ref. 6).
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0.8