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STRUCTURE OF INVERTIBLE (BI)INFINITE TOTALLY POSITIVE MATRICES

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STRUCTURE OF INVERTIBLE (BI)INFINITE TOTALLY POSITIVE MATRICES C. de Boor^{*}, Rong-qing Jia^{**} and A. Pinkus^{***}

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December 19 (Isubintinity) ABSTRACT ABSTRACT C Sub CAn ℓ_{∞} -invertible nontinite totally positive matrix A is shown to have one and only one main diagonal. This means that exactly one diagonal of A has the property that all finite sections of A principal with respect to this diagonal are invertible and their inverses converge boundedly and entrywise to A^{-1} . This is shown to imply restrictions on the possible shapes of such a matrix. In the proof, such a matrix is also shown to have an ℓ_{m-1} invertible LDU factorization. In addition, decay of the entries of such a matrix away from the main diagonal is demonstrated. It is also shown that a bounded sign-regular matrix carrying some bounded sequence to a uniformly alternating sequence must have all its columns in $c_0^{'}$.

Accession For NTIS GRA&I DTIC TAB AMS(MOS) Subject Classification: 47B37 (Primary), 15A09, 15A48 Unannounced Justification Key Words: Biinfinite, infinite, matrix, total positivity, sign regularity, inverse, main diagonal, decay By_ Work Unit Number 3 - Numerical Analysis and Computer Science Distribution/ Availability Codes Avail and/or Dist Special * Mathematics Research Center, University of Wisconsin-Madison ** Mathematics Department, University of Wisconsin-Madison ***Mathematics Department, Technion, Haifa Sponsored, in part, by the United States Army under Contract No. DIIC DAAG29-80-C-0041 COPY **OPECTED**

SIGNIFICANCE AND EXPLANATION

Spline approximation is often most effective when the breakpoint (knot) sequence can be chosen suitably non-uniform. At the same time, the standard approximation schemes (such as least squares approximation, or interpolation at suitable interpolation points by splines) are so far only known to be usable and bounded as long as the breakpoint sequence is almost uniform. The problem of showing existence and uniqueness of bounded spline approximants to bounded data boils down to showing invertibility of a certain infinite matrix A. The distinguished feature of this matrix is its total positivity, i.e., all minors of A are nonnegative. In this paper we show that an arbitrary invertible totally positive matrix has a main diagonal and one only. By this we mean that there is exactly one band or diagonal with the property that finite sections of the matrix whose main diagonal is a piece of that band are invertible and their inverses converge to the inverse of the matrix as the section becomes large. This says that it is possible to approximate the solution of the infinite system by the solution of appropriately chosen finite sub-systems.

These results illustrate the power of total positivity, since such results fail to hold for arbitrary infinite matrices. It is hoped that the better understanding of total positivity of <u>nonfinite matrices</u> obtained in the present report and its predecessors will aid in the resolution of certain outstanding problems concerning the stability of spline approximation schemes.

The responsibility for the wording and views expressed in this descriptive summary lies with MRC, and not with the authors of this report.

STRUCTURE OF INVERTIBLE (BI)INFINITE TOTALLY POSITIVE MATRICES

C. de Boor^{*}, Rong-qing Jia^{**} and A. Pinkus^{***}

Introduction. An investigation into the structure of invertible (bi)infinite totally positive (or, tp) matrices was begun in $[B_2]$ and $[CDMS_1]$, motivated by certain questions $[B_1]$ [M] in spline approximation. First results concerned banded matrices $[B_2]$ $[CDMS_2]$ and strictly banded block Toeplitz matrices $[CDMS_1]$. Somewhat surprisingly, such restriction to banded matrices was found to be unnecessary in [BFP], where it was proved that a tp (or, more generally, a sign regular) matrix A mapping $f_{\infty}(J)$ to $f_{\infty}(I)$ is onto if and only if it has a uniformly alternating sequence in its range. This latter condition means that, for some bounded x, $\sup_i (Ax)(i)(Ax)(i+1) < 0$.

A similar result had been proved in $[B_3]$ for band matrices, following up a conjecture in [M]. The argument in $\{B_3\}$ provided much additional information about the inverse of a banded tp matrix. In the present paper, we obtain the same information for an arbitrary ℓ_m -invertible tp matrix.

We prove (in Section 1) that an l_{∞} -invertible tp matrix A G R^{I×J} has a "main diagonal". By this we mean that all sufficiently large square submatrices of A taken from consecutive rows and columns and principal with respect to a fixed diagonal are invertible and their inverses are bounded uniformly. This implies that A^{-1} is the pointwise limit of these inverses. We even show that such convergence is monotone. As a consequence, $D^{J}A^{-1}D^{J}$ or its negative is again tp, with $D^{K} \in \mathbb{R}^{K \times K}$ the diagonal matrix tor which $D^{K}(k) = (-1)^{k}$, all $k \in K$.

In addition, we show (in Section 2) the uniqueness of such a main diagonal. For the proof, we establish a result of independent interest, namely the existence and uniqueness of an invertible LDU factorization for A. By this we mean the possibility of writing A

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as the product LDU of bounded and boundedly invertible tp matrices, with L and its inverse unit lower triangular, D and its inverse diagonal, and U and its inverse unit upper triangular.

We also follow up some consequences of the existence of a main diagonal for the matrix A: (i) A can have only certain shapes. Explicitly, we must have J = I + r for some r. We settle (in Section 3) the related question of possible choices for I and J in case we only know that A is tp and onto. (ii) The main diagonal must be bounded away from zero. This leads to the observation (made in Section 4) that the entries of A must decay at least linearly away from the main diagonal. We leave open the intriguing question whether, in fact, this decay is exponential, as was shown for arbitrary matrices with a <u>banded</u> inverse in [D].

In the last section, we settle a conjecture from [BFP] whose consideration gave much impetus to the present paper. We prove that a sign regular i_{oo} -invertible matrix A G $R^{I \times J}$ must already carry $c_0(J)$ to $c_0(I)$, i.e., all its columns must vanish at infinity.

We use the following notation and conventions.

We use lower case letters to denote elements of \mathbb{R}^{I} , i.e., real valued functions (or, sequences) on some integer interval (or, more generally, some integer set) I, with x(1) the ith entry, or value at i, of the sequence x. If K is a subset of I, then x_{K} denotes the restriction of x to K. The i-th unit sequence is denoted by e^{i} and defined by

$$e^{1}(j) := \delta_{ij}$$
, all i, j .

Further, for $x \in \mathbf{R}^{I}$,

$$|x|(i) := |x(i)|$$
, all i.

We use the customary abbreviation $l_{\infty}(I)$ for the normed linear space of all sequences x on I with

$$\|x\| := \|x\|_{m} := \sup |x(i)|$$

timite, and use $c_0(I)$ for its closed linear subspace of all bounded sequences x vanishing at infinity, i.e., for which {i G I : $|x(i)| > \alpha$ } is finite for all positive

-2-

 α . We use $\ell_1(I)$ for the normed linear space of all absolutely summable sequences x on I , i.e., with

$$|\mathbf{x}|_1 := \Sigma |\mathbf{x}(\mathbf{i})|$$

finite, and we make use of the fact that $\ell_{\infty}(I)$ is the dual of $\ell_1(I)$, which, in turn, is the dual of $c_0(I)$.

Let also J be an integer interval (or, more generally, a set of integers). We are interested in A G R^{I×J} which carries $l_{\omega}(J)$ to $l_{\omega}(I)$, and we identify such a matrix A with the linear map from $l_{\omega}(J)$ to $l_{\omega}(I)$ induced by it. Such A is necessarily bounded and we denote by TAT its map norm. If A is one-one and onto, it is boundedly invertible. We will then say that A is l_{ω} -invertible, for short. As with sequences, |A|(i,j) := |A(i,j)|, all i,j.

We write A(*,j) for the sequence which makes up the j-th column of A, and A(i,*) for the i-th row. We call the sequence A(*,*+r) the r-th band or diagonal of A.

If $K \times L \subseteq I \times J$, then we denote by $A_{K,L}$ the restriction of A to $K \times L$. At times, it is also convenient to use the alternate notation

$$A\begin{bmatrix} K\\ L \end{bmatrix} := A_{K,L}$$

and even

$$A[K] := A_{K,K}$$

On replacing square brackets by round brackets, we get to the determinant:

A(...) := det A[...].

Thus A(i,i) and A(i) both denote the i-th diagonal entry of A, - the latter involving an abuse of notation since $A(\{i\})$ would have been correct.

We recall that A is sr_k (:= sign regular of order k) if, for some $\varepsilon_1, \ldots, \varepsilon_k \in \{-1, 1\}$ and for all $k \times L \subseteq I \times J$ with $|K| = |L| \leq k$,

$$\epsilon_{|K|} A \binom{K}{L} > 0$$

where |K| denotes the cardinality of the index set K . If all $\varepsilon_1 = 1$, then we use tp_k (:= totally positive of order k) instead of sr_k . If A is sr_k (tp_k) for all k, then A is simply called sr (tp). We intend to make use of Sylvester's determinant identity (see, e.q., [K; p.3]) and Hadamard's inequality (see, e.q., [K; p.88]).

-3-

1. Existence of a main diagonal. We establish that any ℓ_{go} -invertible to matrix A must have a main diagonal. By this we mean that A is the stable limit of its finite sections which are principal with respect to a particular diagonal. It is this diagonal that we then call the "main diagonal". We use here the definite article in anticipation of the uniqueness established in the next section.

Theorem 1. If the matrix $A \in \mathbb{R}^{I \times J}$ is tp and l_{∞} -invertible, then, for some r, and for all finite intervals $M \subseteq I$, $A_{M,M+r}$ is invertible and $(A_{N,M+r})^{-1}$ converges, monotonely in each entry, to A^{-1} as $M \longrightarrow I$.

Proof. Since A is onto, there exists a bounded sequence x such that

$$(Ax)(i) = (-1)^{1}$$
, all i.

with this, the argument for Theorem 1 of [BFP] and, especially, the Claim proved there, provide us, for each finite interval $L \subseteq I$, with an index set $K \subseteq J$ so that $\|A_{L,K}^{-1}\| \leq \|x\|$. (In the Claim, choose $S = l_1$, hence $S^* = l_{\infty}$, choose I = L, choose $u(i) = (-1)^1$, all i, and choose for s an extremal for $F_V: \Sigma a_i A(i, \cdot) \longmapsto \Sigma a_i v(i)$ with v = u.)

Extend each $A_{L,K}^{-1}$ to a matrix $C^{L} \in \mathbb{R}^{J \times I}$ by taking its value to be zero off K×L. Since, for each i, $\|C^{L}(\cdot,1)\| \leq \|x\|$, we are permitted to choose a sequence of integer intervals L approaching I for which, for each i $\in I$, $C^{L}(\cdot,1)$ converges weak^{*} (i.e., pointwise on $\ell_{1}(J)$) to some $y^{i} \in \ell_{\infty}(J)$. Then, for each m $\in I$, the sequence $A(m, \cdot)$ being in $\ell_{1}(J)$, we have

$$(Ay^{1})(m) \approx \lim_{L \neq I} \sum_{s} A(m,s) C^{L}(s,1) \approx \lim_{L \neq I} \left\langle \begin{array}{c} e^{1}(m), m \in L \\ \\ L \neq I \end{array} \right\rangle = e^{1}(m)$$

showing that $Ay^1 = e^1$, therefore $y^1 = A^{-1}(\cdot, 1)$, all 1. We conclude that $c^L(\cdot, 1)$ converges pointwise on ℓ_1 and so, in particular pointwise, to $A^{-1}(\cdot, 1)$.

The remainder of the proof relies on the following known fact.

-4-

Lemma 1. If $B \in \mathbb{R}^{n \times n}$ is to and invertible, then, for any interval $M \subseteq \{1, ..., n\}$, so is $C := B[M] = B_{N,M}$, and $0 \leq (-)^{i+j}C^{-1}(i,j) \leq (-)^{i+j}B^{-1}(i,j)$, all $i,j \in M$.

The nonsingularity of C is a consequence of Hadamard's inequality. The rest of the lemma follows by repeated application of the special case $M = \{1, ..., n-1\}$. For this case, use the checkerboard nature of the inverse of a tp matrix and the rank-one correction tormula for an inverse (called the Woodbury-Sherman-Morrison formula by Numerical Analysts) which in this case states that

$$C^{-1}(i,j) \approx B^{-1}(i,j) - B^{-1}(i,n)B^{-1}(n,j)/B^{-1}(n)$$
, $i,j=1,...,n-1$.

Of course, this identity also tollows from Cramer's rule and Sylvester's determinant identity using $B\begin{bmatrix} \langle j, \backslash n \\ \backslash i, \backslash n \end{bmatrix}$ as pivot block.

As a corollary, we find that, for an invertible tp $B\in R^{n\times n}$, $1/B(i)\leq B^{-1}(i)$, or, $1\leq B(i)B^{-1}(i)$, all i , hence

$$||B^{-1}||^{-1} \le B(i)$$
, all i.

This shows that the (main) diagonal entries of an invertible tp matrix are bounded away from zero.

Returning now to the invertible matrices $A_{L,K}$ obtained earlier, we conclude that their (main) diagonal entries must all be bounded below by $1/|\mathbf{x}||$. Assuming for simplicity of notation that $0 \in I$, it follows that, for every L containing 0, the index j^{L} for which $A(0,j^{L})$ lies on the (main) diagonal of $A_{L,K}$ must come from the set $\{j \in J : A(0,j) \ge 1/|\mathbf{x}|\}$, and this set is <u>finite</u> since $A(0, \cdot) \in I_{1}$. We are therefore permitted to choose a further subsequence of intervals L increasing to I (and all containing 0) for which $j^{L} = r$ for some fixed integer r. Since J and L are intervals and $A_{K,L}$ is square, this implies that $L+r \subseteq J$ for all such L.

Since $A_{L,K}^{-1}$, or, more precisely, its extension C^{L} to all of J×I converges pointwise to A^{-1} yet $C^{L}(j, \cdot) = 0$ for all $j \notin K$, it follows that every $j \in J$ is eventually in every K. Thus, for every interval $M \subseteq I$, there exists L so that $M+r \subseteq K$. By Lemma 1, $A_{M,M+r}$ is invertible and $|A_{M,M+r}^{-1}| \leq |A_{L,K}^{-1}| \leq |x|$. Further, by that

-5-

lemma, $M \leq N$ implies that

 $0 \le (-)^{i+j} A_{N,M+r}^{-1} (i+r,j) \le (-)^{i+j} A_{N,N+r}^{-1} (i+r,j)$, for i,j $\in M$. We conclude that $A_{N,M+r}^{-1}$, or, more precisely, its extension to all of J×I, converges, monotonely in each entry, to a bounded matrix $C \in R^{J \times I}$ which, by a repeat of the earlier argument, is necessarily A^{-1} . |||

Corollary 1. The main diagonal of A is bounded below by $|A^{-1}|^{-1}$. More precisely, $A(i,1+r)A^{-1}(i+r,i) \ge 1$ for all i.

Corollary 2. The matrix
$$((-)^{i+j}A^{-1}(i+r,j))$$
 is tp.

The second corollary improves on Proposition 1 of [BFP] in which the same conclusion is only reached under the additional assumption that the columns of A are all in $c_0(I)$. (See also Section 5.)

Theorem 1 implies that an l_{∞} -invertible tp matrix A has a main diagonal in the sense introduced in $[B_1]$: For some r and for all sufficiently large intervals M, $A_{M,M+r}$ is invertible and lim $\sup_{M+1} \|A_{M,M+r}^{-1}\| < \infty$. This means that one can approximate the solution x of the nonfinite linear system $A_X = b$ by the solution $x^M := A_{M,M+r}^{-1}b_M$ of the finite system $A_{M,M+r}x^M = b_M$, at least when b and x are in c_0 . We show in Section 5 that $x \in c_0$ if and only if $b \in c_0$.

Finally, Theorem 1 implies that I + r = J for some r. Hence it is no restriction to assume, after a shift, that I = J. If I has a first or a last element, this then forces band 0 to be the main diagonal.

-6-

2. Existence of stable LU factorization and uniqueness of main diagonal. The LDU factorization of a matrix A of order n is a basic tool in the solution of linear algebraic systems. The matrix A is written, if possible, in the form LDU, with L lower triangular, D diagonal, and U upper triangular. Both L and U are required to be <u>unit</u> triangular, i.e., to have all their diagonal entries equal to 1, and this insures uniqueness of the factorization (see the proof of Lemma 2 below). Such a factorization can be obtained in case all upper left principal minors of A are nonzero. By Hadamard's inequality, this condition is satisfied for an invertible tp A. Further, if LDU = A, then $(DU)(i, \cdot)$ is the particular linear combination of the first i rows of A which vanishes at 1,2,...,i-1 and in which A(i, \cdot) has coefficient 1. Therefore

$$(DU)(i,*) = A(1,...,i-1,\frac{1}{*})/A(1,...,i-1)$$

since the right hand side has the same properties. Also,

$$A(1,...,i) = L(1,...,i)D(1,...,i)U(1,...,i) = D(1)...D(i)$$

hence

$$D(i) = A(1,...,i)/A(1,...,i-1)$$
.

Therefore, finally,

$$L(*,j) = A(1,...,j-1, \frac{1}{j})/A(1,...,j)$$

We have recalled these well known facts to facilitate discussion of an LDU factorization of a <u>nonfinite</u> matrix. We intend to obtain such a factorization by a limiting process and need therefore to consider the behavior of the LDU factorization of A as we add rows and columns to A.

Let now $A \in \mathbf{R}^{I \times J}$. We say that the matrices L, D, and U provide a (normalized) LDU factorization for A provided A = LDU, L is unit lower triangular with band 0 as its rightmost (nontrivial) band, D has band U as its only nontrivial band, and U is unit upper triangular. We call such a factorization (boundedly) invertible if each factor is bounded and boundedly invertible, with L^{-1} and U^{-1} being again triangular.

We are not certain that having a "good" diagonal (i.e., a diagonal all of whose principal minors are nonzero) is sufficient for having an LDU factorization; it may not even be sufficient to have a main diagonal. But it A is also tp, then having a main

-7-

diagonal is sufficient for having a boundedly invertible LDU factorization. This insures that the main diagonal is unique, as we will see.

Lemma 2. If L, D, U and L_1 , U_1 and U_1 are both invertible normalized LDU factorizations for A (as maps from ℓ_{∞} to ℓ_{∞}), then $L = L_1$, $D = D_1$, $U = U_1$.

Proof. Let band r be the lettmost band of U , and band r_1 the leftmost band of U₁, and assume without loss that $r \leq r_1$. Then, by assumption,

$$L_1^{-1}LD = D_1U_1U^{-1}$$

and the left hand side is lower triangular with band 0 as its rightmost band and equal to the interesting diagonal of D, while the right hand side is upper triangular with band r_1 -r as its leftmost band, and equal to the interesting diagonal of D_1 . Since $r_1 > r$, it rollows that $r_1 = r$, hence $D = D_1$, and further $L_1^{-1}L = 1 = U_1U^{-1}$.

Theorem 2. If A is l_{∞} -invertible and tp, hence has a main diagonal, say band r, then A has an invertible normalized LDU factorization L, D, U, with band r the leftmost band of U.

Proof. Assume first that r = 0. Further, assume without loss that $A_n := A[-n,...,n]$ is a typical principal section for that main diagonal of A. Let L_n , D_n , U_n be the LDU factorization for A_n . Then

$$D_n(i) = A(-n,...,i)/A(-n,...,i-1) = 1/A(-n,...,i)^{-1}(i)$$

and, by Lemma 1 and Theorem 1,

$$A[-n,...,i]^{-1}(i) \leq A_{-1}^{-1}(i) \leq A^{-1}(i)$$

and $A[-n,...,i]^{-1}(1)$ increases as n grows. We conclude that

$$\|D_n^{-1}\| \leq \|A_n^{-1}\|$$

and D_n decreases monotonely to some invertible diagonal matrix D for which $u(i) \ge |A^{-1}|^{-1}$, all i. Therefore, D is boundedly invertible. Next consider $D_n V_n$. We saw earlier in this section that

-8-

$$(D_n U_n)(1,j) = A(-n,...,1-1, \frac{1}{j})/A(-n,...,-1-1)$$
.

Use Sylvester's determinant identity on A[-n-1,...,i-1, $\frac{i}{j}$] with pivot block A[-n,...,i-1] to conclude that

$$A(-n-1,...,i-1,\frac{1}{j})A(-n,...,i-1) = A(-n-1,...,i-1)A(-n,...,i-1,\frac{1}{j}) - A(\frac{-n}{-n},...,\frac{1}{j})A(\frac{-n-1}{-n},...,\frac{1}{j})$$

which, by tp, implies that

$$0 \leq (D_{n+1}U_{n+1})(i,j) \leq (D_nU_n)(i,j)$$

we conclude that $D_n U_n$ decreases monotonely to some matrix V, necessarily tp and upper triangular, therefore U_n converges to the tp unit upper triangular matrix $U := D^{-1}V$. Further, $D_n U_n \leq A_n$, hence

$$[U_n] < [A_n] [D_n^{-1}] < [A_n] [A_n^{-1}], \text{ thus } [U] < [A] [A^{-1}].$$

The corresponding argument shows that L_n converges to some tp unit lower triangular matrix L with #LI < #A##A⁻¹# . Finally, $A_n^{-1} = U_n^{-1}U_n^{-1}L_n^{-1}$, hence also $\|L_n^{-1}\|$, $\|U_n^{-1}\|$ < $\|A_n^{-1}\|\|$ < $\|A\|\|A^{-1}\|\|$. Indeed, $|A_n^{-1}|\|$ is again tp and , because of the checkerboard nature of inverses of tp matrices, $|U_n^{-1}||$, $|D_n^{-1}||$, and $|L_n^{-1}||$ give the UDL factorization for $|A_n^{-1}||$, i.e., the factorization obtained by starting Gauss elimination at the lower right corner rather than the upper left, hence satisfy the same bounds. For, if $B^*(i,j) := B(-i,-j)$, all i,j, i.e., the order of both the rows and the columns is reversed, then tp is preserved as well as the max-rowsum norm while, with M, E, V an LDU factorization for B, the matrices M^* , E^* , and V* provide a UDL factorization for B*. This shows that also L and U (and, of course D) have band 0 as main diagonal, and are, in particular, invertible.

It now $r \neq 0$, then we obtain such an LDU factorization (with each factor having band 0 as main diagonal) for the matrix AE^{-r} , with E the shift, (Ea)(1) := a(1+1), all 1. But then $A = LD(UE^{r})$ does it . [[]

Corollary. If also band is of A is a main diagonal for A , then s = r .

-9-

Proof. By Theorem 2 , A has an invertible normalized LDU factorization with band r as the leftmost nontrivial band for the upper triangular factor, as well as one with band s as the leftmost nontrivial band of the upper triangular factor. But, by Lemma 2, these two factors must be the same. |||

3. The shape of a nonfinite tp matrix. The fact that any invertible tp matrix $A \in \mathbb{R}^{I \times J}$ has a main diagonal implies that $I + r \approx J$ for some r. In particular, it rules out certain combinations of I and J which might, offhand, be possible. For example, the choice $I \approx -N$ is not possible in conjunction with the choice J = N. If we merely know that A is onto or one-one, certain other combinations, though certainly not all, are possible.

In this context, the only properties of the integer intervals I and J which matter are whether or not they have a first and/or last element. In effect, there are just four choices for I and J:

finite, N, -N, 2 .

If J is finite then A cannot be onto unless $|J| \ge |I|$. The same conclusion holds in spirit when J is nonfinite.

Theorem 3. Let $A \in \mathbb{R}^{I \times J}$ be to and carry $l_{\infty}(J)$ onto $l_{\infty}(I)$. Let I and J each be one of N, -N, or Z. Then $I \subset J$.

Proof. There is nothing to prove unless J = N or -N. Assume without loss of generality that J = N. Assume by way of contradiction that I = -N or Z. A being onto, we may pick a bounded x for which $Ax = ((-1)^{\frac{1}{2}})$. Pick any i G I. Then, since $A(i, \cdot) \in \hat{L}_1(J)$, we may pick n so that

j > n implies $A(1,j) < \|x\|^{-1}$.

Since $I \approx -N$ or Z, the interval L := [i-n,i] is in $I \cdot By$ [BFP] (as used at the beginning of the proot for Theorem 1 above), we may pick a subset K of J for which $\|A_{L,K}^{-1}\| \leq \|x\|$. But then, with $K =: \{k_0 < \cdots < k_n\}$, we must have

-10-

.

 $A(i,k_n) \ge I_X I^{-1}$ yet $k_n > n$,

and this is a contradiction to our choice of $[n \ , \ ||]$

4. Decay away from the main diagonal. The fact that an l_{gg} -invertible tp matrix A has a main diagonal insures, by Corollary 1 of Theorem 1, that it has a diagonal which is bounded away from zero. This implies at least linear decay away from that diagonal. More precisely, we have the following

Theorem 4. Let $A \in \mathbb{R}^{I \times I}$ be the point of the contrast of the suppression of the supervision of t

Proof. Let s > 0. Since A is tp_2 , we have A(1,i+k)A(i+k,i+s) > A(i,i+s)A(i+k,i+k), k=1,...,s

or

This implies that $\|A\|_{1,\infty} \|A\|/d \ge \|s\| \sup_i A(i,i+s)$, using the fact that $\max_{i,j} |A(i,j)| = \|A\|_{1,\infty}$ while $\sup_i \Sigma_k |A(i,k)| = \|A\|$. An analogous argument proves the inequality for negative $s \cdot |||$

Corollary. If
$$A \in \mathbb{R}^{I \times J}$$
 is tp and l_{∞} -invertible, then, for some r
A(i,i+s) $\leq \|A\|_{1,\infty} \times (A) / |s-r|$, all i, s.

Proof. By Corollary 1 to Theorem 1, we may choose $d = IA^{-1}I^{-1}$, hence $IAI/d = IAIIA^{-1}I =: \kappa(A)$. |||

In case A^{-1} is also banded, we know from [D] that the entries of A decay exponentially away from the main diagonal of A. Explicitly (B₁),

-11-

where we are a set of the set of

$$A(i,i+s) \leq \text{const}_{\kappa(A),m}\left(\frac{\kappa(A)-1}{\kappa(A)+1}\right)|s-r|/m$$

In case A^{-1} is m-banded. In such a case, A^{-1} also decays exponentially, in a trivial way. It would be nice to know whether, in fact, <u>all</u> t_{g_0} -invertible tp matrices decay exponentially away from their main diagonal.

5. Invertible sr matrices. It is not possible to extend the above results concerning main diagonals to invertible sr matrices. This is illustrated by the particular matrix B obtained from the identity matrix in $\mathbb{R}^{Z\times Z}$ by reversing the order of the rows. Every band has singular principal minors of arbitrarily large orders. Of course, one could weaken the notion of main diagonal to demand only that there be <u>some</u> sequence of principal submatrices converging stably to A. It is possible to show that an l_{∞} -invertible sr matrix has such main diagonals. For the particular matrix B, though, <u>every</u> band becomes main in this weaker sense, i.e., the distinction becomes empty. This is, of course, not surprising since, for B, there is really nothing to distinguish one band from another.

Some of the work reported on in the preceding sections was initially based on the realization that the following conjecture is true.

Conjecture ([BFP]). The columns of a tp l_{a} -invertible matrix are already in c_0 .

Indeed, this conjecture is now a simple consequence of Theorem 4. It is pointed out in [BFP] that the discussion there of the inverse of a sr matrix could be considerably shortened if this conjecture were to hold for sr matrices. We now prove the following generalization of the conjecture.

Theorem 5. Let $S \subseteq \mathbb{R}^J$ be a normed sequence space which contains the unit vector e^j for all $j \in J$ and contains |x| if it contains x, and let $A:S \longrightarrow l_{\infty}(I)$ be bounded and sr. If Ax uniformly alternates for some $x \in S$, then $Ac_0 \subseteq c_0$, i.e., the columns of A are already in c_0 .

-12-

Proof. We have to prove that

$$K := \{i \in I : |A(i,k)| \ge \alpha\}$$

is finite for all $k \in J$ and all q > 0. By considering -A and/or inverting the order of the rows of A if necessary, we can ensure that A is tp_2 . Then, for $j \leq k$, $i' \leq 1$, we have

or, for i' G K ,

$$A(i,j) \leq \frac{A(i,k)}{\alpha} A(i',j)$$

Therefore,

$$\sum_{j \leq k} |x(j)| \sup_{i \geq j} A(i,j) \leq \frac{|A(\cdot,k)|}{\alpha} \sum_{j \leq k} |x(j)| \leq \frac{|A(\cdot,k)|}{\alpha} \|A\|_{X} \|$$

or

with

[K] := [inf K, sup K].

By inverting the order of rows and of columns of A (which preserves tp_2), we obtain the same inequality for the sum over $j \ge k$, hence altogether

$$\sum_{\{K,j\}} ||\mathbf{x}(j)|| < \infty$$

 $jGJ = \begin{bmatrix} [K] \\ jGJ \end{bmatrix}$ Since $\sum_{jGJ} A(*,j)x(j)$ uniformly alternates, this implies that we can find some <u>finite</u> index set L so that $A_{\{K\},L}$ already maps x_L to a uniformly alternating sequence, and this, by a standard sr result (see, e.g., [K; Chap.5, §1] or the beginning of the proot of Theorem 1 in [BFP]), implies that $|[K]| \leq |L|$, thus $|K| < \infty$. |||

This theorem makes it possible to give a shorter proof of

Theorem 2 of [BPP]. It A
$$\in \mathbb{R}^{I \times J}$$
 is sr and ℓ_{∞} -invertible, then $D^{J}A^{-1}D^{J}$ is also sr.

by mimicking the proof of Proposition 1 of [BFP], since the assumptions allow the conclusion that A maps $c_0(J)$ to $c_0(I)$. Hence Corollary 2 to Theorem 1 of (EFP) shows

-13-

that A^{-1} is the pointwise limit of certain matrices E^{L} as the index interval L converges to I. Explicitly, E^{L} equals $A_{K,L}^{-1}$ on K×L and vanishes off K×L, with K some index set depending on L. This implies that E^{L} is sr, hence so is its pointwise limit, A^{-1} .

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-14-

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ABSTRACT (continued)

main diagonal is demonstrated. It is also shown that a bounded sign-regular matrix carrying some bounded sequence to a uniformly alternating sequence must have all its columns in c_0 .

