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ON ELIMINATING INFERIOR REGRESSION MODELS*

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ABSTRACT

Consider a linear regression model with (p-1) predictor variables which is taken as the "true" model. The goal is to select a subset of all possible reduced models such that all inferior models (to be defined) are excluded with a guaranteed minimum probability. A procedure is proposed for which the exact evaluation of the probability of a correct decision is difficult; however, it is shown that the probability requirement can be met for sufficiently large sample size. Monte Carlo evaluation of the constant associated with the procedure and some ways to reduce the amount of computations involved in the implementation of the procedure are discussed.

1. INTRODUCTION

A problem of great interest to many practitioners of linear regression analysis is that of selecting an appropriate subset of the predictor variables which adequately describe the variance of the response variable. Some of the commonly employed techniques are all possible regressions, forward selection, backward selection and stepwise procedures. These procedures along with some variations and computational methods are given in Draper and Smith (1966). Several criteria for defining the best set of predictor variables and

*This research was supported by the Office of Naval Research contract NO0014-75-C-0455 at Purdue University. Reproduction in whole or in part is permitted for any purpose of the United States Government. various techniques for selecting the best set have been discussed in a nice expository paper by Hocking (1976). A brief review of these methods is also given by Thompson (1978). However, these techniques do not have an accompanying probability guarantee for selecting the best set; moreover, the measures of goodness of models are based on the data. Formulation of this problem in the framework of the multiple decision subset selection procedures of Gupta (1956, 1965) has been recently considered by Arvesen and McCabe (1975), Gupta and Huang (1977), and McCabe and Arvesen (1974). We adopt the same framework here. For details of the general subset selection theory, see Gupta and Panchapakesan (1979).

Formulation of the problem is given in Section 2. In the next section, a procedure is proposed and the infimum of the probability of a correct decision (PCD) is expressed in terms of the models obtained by dropping one predictor variable at a time. Section 3 discusses asymptotic results and establishes the (asymptotic) least favorable configuration for PCD. However, this still does not make the calculation of the necessary constant easy. The next section describes a Monte Carlo method of determining the constant. A few facts which can be effectively used in reducing the amount of computations needed in implementing the procedure are discussed in Section 5.

2. FORMULATION OF THE PROBLEM

Consider the model

$$Y_{j} = \beta_{0} + \beta_{1} x_{j1} + \dots + \beta_{p-1} x_{j,p-1} + \epsilon_{j}, \quad j = 1, \dots, N$$
(2.1)

where $x_{j,r}$, j = 1, ..., N, are fixed levels of the predictor variables $x_1, ..., x_{p-1}$, the β_i are unknown parameters, and the ϵ_j are independent normal random variables with mean zero and variance σ_0^2 . Let $\underline{Y}' = (Y_1, ..., Y_N), \ \underline{\beta}' = (\beta_0, ..., \beta_{p-1}), \ \underline{\epsilon}' = (\epsilon_1, ..., \epsilon_N),$

 $\underline{1}' = (1, ..., 1)$, and $\underline{x}'_i = (x_{1i}, ..., x_{Ni})$, i = 1, ..., p-1. Then the model (2.1) can be written in the familiar matrix form

$$Y = X_{\beta} + \epsilon$$
 (2.2)

where $X = (1 x_1 \dots x_{p-1})$ and the rank of X is assumed to be p < N. It is assumed that (2.2) represents the "true" model. We wish to compare

with this true model all the models that can be obtained by taking only some of the predictor variables. In order to define inferior models, we need a measure of goodness of a model. For any fixed $\alpha = 0, 1, \ldots, p-1$, consider all the $\binom{p-1}{\alpha}$ subsets of the set of predictor variables $\{x_1, \ldots, x_{p-1}\}$ and the corresponding reduced models obtained from (2.2). Associated with these reduced models are the multiple correlation coefficients $R_{i,\alpha}$, $i = 1, 2, \ldots, \binom{p-1}{\alpha}$. The indexing of these reduced models can be done in an arbitrary manner. Let $\theta_{i,\alpha} = E(1-R_{i,\alpha}^2)$. Then the goodness of a reduced model is defined by comparing $\theta_{i,\alpha}$ for the model with the parameter $\theta_{1,p-1}$ of the true (full) model.

<u>Definition 2.1</u>. A reduced model whose associated parameter $\theta_{i,\alpha}$ is said to be inferior if $\theta_{1,p-1} \leq \delta^* \theta_{i,\alpha}$, where $\delta^* \in (0,1)$ is a specified constant.

It is to be noted that comparison of models based on $\theta_{i,\alpha}$ is equivalent to that based on the expected residual sums of squares in the ANOVA of these models. However, it is more practical to fix δ^* in relation to multiple correlation coefficients as they are unit-free.

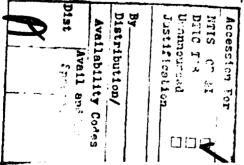
The true model is, of course, the best model. While eliminating the inferior models, we do not want to overly reject good models. Formally stated, our <u>goal</u> is: Select c subset of all possible models with preferably a large subset size so that all the inferior models are excluded from the selected subset of models with a guaranteed minimum probability P* (0 < P* < 1).

<u>Definition 2.2</u>. Model A is said to be a <u>submodel</u> of Model B if the set of predictor variables of A is a subset of that of B.

Since the multiple correlation coefficient for a model cannot be smaller than the coefficient for any of its submodels, we make the following remark.

<u>Remark 2.1</u>. If any model is inferior, then all its submodels are inferior.

The number of inferior models, t_1 , is unknown. Of course, $0 \le t_1 \le t-1$, where $t = 2^{p-1}-1$. Let $\Omega(t_1)$ denote the set of all parametric configurations that give rise to exactly t_1 inferior models and let $\Omega = \bigcup \Omega(t_1)$.



We now propose a procedure based on the sample multiple correlation coefficients for the different models. Let $R_{i,\alpha}$ denote the sample coefficient corresponding to the model associated with $\theta_{i,\alpha}$ and set $\hat{\theta}_{i,\alpha} = 1 - R_{i,\alpha}^2$.

3. PROCEDURE R

The proposed procedure $\ensuremath{\mathfrak{R}}$ is: exclude from the selected subset any model for which

$$\hat{\theta}_{i,\alpha} \geq \frac{c}{\delta^{\star}} \hat{\theta}_{i,p-1}$$
(3.1)

where the constant $c = c(N,p,P^*) > \delta^*$ is determined such that $P(CD|\Omega)$, the probability of a correct decision using Ω , satisfies the inequality

$$P(CD|_{\Re}) \geq P^*. \tag{3.2}$$

We first note that if any model is excluded by \mathfrak{R} , then all its submodels are also excluded. Further, we need only to determine the ratio $c/\delta^* = d$ (say).

For a parametric configuration in $\Omega(t_1)$,

$$P(CD|R) \ge Pr\{\hat{\theta}_{i,p-2} \ge d\hat{\theta}_{i,p-1}, i = 1,...,p-1\}.$$
 (3.3)

The above inequality is obvious because of Remark 2.1 and the fact that the right-hand side of (3.3) is the probability of a correct decision when $t_1 = t-1$. Consequently,

$$\inf_{\Omega} P(CD|_{\mathcal{R}}) = \inf_{\Omega} Pr(\hat{\theta}_{i,p-2} \ge d \hat{\theta}_{1,p-1}, i = 1,...,p-1).$$
(3.4)

Let $X_{(i)}$ denote the matrix obtained from X by deleting the column vector \underline{x}_i , and $\underline{\beta}_{(i)}$ denote the vector obtained from $\underline{\beta}$ by leaving $\underline{\beta}_i$ out. Consider the (p-1) reduced models given by

$$\underline{Y} = X_{(i)} \underline{\beta}_{(i)} + \underline{\epsilon}_{i}, \quad i = 1, \dots, p-1, \quad (3.5)$$

where $\in_i \sim N(0, \sigma_i^2 l_n)$. It should be noted that in stating the reduced model

(3.5), we mean that the model is used for prediction purposes using only the (p-1) variables of $X_{(i)}$. However, our comparisons of models are made under the true model assumptions. The expectation of the residual mean square in the corresponding ANOVA evaluated under the true model is σ_i^2 given by the result (e) at the end of this section. The reduced model described in (3.5) reflects this fact.

Now, let SS_i denote the residual sum of squares in the ANOVA corresponding to the model with $X_{(i)}$ and let SS₀ denote the residual sum of squares in the ANOVA of the full model. Then we can summarize our discussion thus far in the following theorem.

Theorem 3.1. For the procedure \mathfrak{X} defined in (3.1),

 $\inf_{\Omega} P(CD|_{\Re}) \geq \inf_{\Omega} Pr\{SS_i \geq d SS_0, i = 1,...,p-1\}.$ (3.6)

Exact evaluation of the infimum on the right-hand side of (3.6) is difficult. We take recourse to asymptotic theory and try to achieve the probability requirement in (3.2) for large N in the next section. We state below a few well-known results in regression theory which we need.

(a) $SS_{i} = \underline{Y}'\{1 - X_{(i)}(X_{(i)}' X_{(i)})^{-1}X_{(i)}'\}\underline{Y} = \underline{Y}'Q_{i}\underline{Y}, say.$

(b)
$$SS_0 = \underline{Y}'\{1 - X(X'X)^{-1}X'\}\underline{Y} = \underline{Y}'Q_0\underline{Y}$$
, say,

(c) $SS_{i}/\sigma_{0}^{2} \sim \chi^{2}(v, (X_{\underline{\beta}})'Q_{i}(X_{\underline{\beta}})/2\sigma_{0}^{2})$ (under the true model)

where v = N - p+1 and $\chi^2(v, \lambda)$ denotes the noncentral chi-square distribution with v degrees of freedom and noncentrality parameter λ .

(d) $SS_0/\sigma_0^2 \sim \chi^2(v_0)$, the (central) chi-square distribution with $v_0 = N-p$ degrees of freedom.

(e)
$$\sigma_i^2 = \sigma_0^2 + (X_{\underline{\beta}})'Q_i(X_{\underline{\beta}})/v$$
.

4. ASYMPTOTIC RESULTS

Since our rule is invariant with respect to $\sigma_0^2 > 0$, we can assume that $\sigma_0^2 = 1$. Following Arvesen and McCabe (1975), we write $\underline{Y}'Q_{\underline{i}}\underline{Y} = \underline{U}_{\underline{i}}U_{\underline{i}}$,

i = 0,1,...,p-1, where $\underline{U}_i = B_i \underline{Y}$ with $B_j B_j^i = 1$ and $B_j^i B_j = Q_j$. Here B_j is a v × n matrix for i = 1,...,p-1 and B_0 is a $v_0 \times n$ matrix. The joint distribution of $\underline{U}' = (\underline{U}_0', \underline{U}_1', \dots, \underline{U}_{p-1}')$ is multivariate normal in $v_0 + (p-1)v$ dimensions with mean vector $\underline{n}' = (\underline{n}_0', \underline{n}_1', \dots, \underline{n}_{p-1}')$ with $\underline{n}_i = B_i X \underline{\beta}$, i = 0,1,...,p-1, and covariance matrix $\underline{\Sigma} = (\underline{\Sigma}_{ij})$ where $\underline{\Sigma}_{ij} = B_i B_j'$. Note that $\underline{\Sigma}$ is possibly singular.

Now, letting

$$Z_{i} = (SS_{i} - v - \underline{n}_{i} \underline{n}_{i})/\sqrt{2v} + 4\underline{n}_{i} \underline{n}_{i}, \quad i = 1,...,p-1,$$

$$Z_{0} = (SS_{0} - v_{0})/\sqrt{2v_{0}},$$
(4.1)

we have

$$\Pr\{SS_i \ge d SS_n, i = 1, ..., p-1\}$$

$$= \Pr\{\frac{SS_{i}}{\sqrt{2\nu + 4\underline{n}_{i} \underline{n}_{i}}} \ge d \frac{SS_{0}}{\sqrt{2\nu_{0}}} \sqrt{\frac{2\nu_{0}}{2\nu + 4\underline{n}_{i} \underline{n}_{i}}}, i = 1, \dots, p-1\}$$

$$\geq \Pr\{\frac{SS_i}{\sqrt{2\nu + 4\underline{n}_i \underline{n}_i}} \geq d \frac{SS_0}{\sqrt{2\nu_0}} \sqrt{\frac{\nu_0}{\nu}}, \quad i = 1, \dots, p-1\}$$

$$= \Pr\{Z_{i} + \frac{v + \underline{n}_{i}' \underline{n}_{i}}{\sqrt{2v + 4\underline{n}_{i}' \underline{n}_{i}}} \ge d \sqrt{\frac{v_{0}}{v}} Z_{0} + \frac{dv_{0}}{\sqrt{2v}}, \quad i = 1, ..., p-1\}$$

$$\geq \Pr\{Z_{i} + \sqrt{\frac{\nu}{2}} \geq d\sqrt{\frac{\nu_{0}}{\nu}} \quad Z_{0} + \frac{d\nu_{0}}{\sqrt{2\nu}}, \quad i = 1, \dots, p-1\}.$$

The last inequality follows from the fact that $\underline{n}_i \cdot \underline{n}_i \ge 0$ and $\phi(t) = (v + t)/\sqrt{v + 2t}$ is strictly increasing in $t \ge 0$. Thus we have $\Pr SS_i \ge d SS_0$, i = 1, ..., p-1}

$$\geq \Pr\{Z_{i} \geq d / \frac{v_{0}}{v} Z_{0} + \frac{dv_{0}}{\sqrt{2v}} - \sqrt{\frac{v}{2}}, \quad i = 1, \dots, p-1\}.$$
(4.2)

It can be easily seen that we have equality in (4.2) when $\underline{n}_i \ \underline{n}_i = 0$. Also, the joint distribution of $Z_0, Z_1, \ldots, Z_{p-1}$ does not depend upon $\underline{n}_0, \underline{n}_1, \ldots, \underline{n}_{p-1}$ for large N. This shows that the worst configuration (asymptotically) for $Pr\{SS_i \ge d SS_0, i = 1, \ldots, p-1\}$ is when $\underline{\beta} = \underline{0}$. Thus we can achieve the probability requirement (3.2) for large N if d is determined by

$$\Pr\{Z_{i} \ge d / \frac{v_{0}}{v} Z_{0} + \frac{dv_{0}}{\sqrt{2v}} - / \frac{v}{2}, \quad i = 1, ..., p-1\} = P^{*}$$
(4.3)

where $\underline{Z}' = (Z_0, Z_1, \dots, Z_{p-1})$ has a multivariate normal distribution with mean zero and covariance matrix $\Gamma = (\rho_{ij})$ with

$$\rho_{ij} = \frac{1}{\nu} \operatorname{tr}(\Sigma_{ij}\Sigma_{ji}) = \frac{1}{\nu} \operatorname{tr}(Q_{j}Q_{i}), \quad i \neq j, \ i,j = 1, \dots, p-1,$$

and

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$$\rho_{0j} = \frac{1}{\sqrt{\nu v_0}} \operatorname{tr}(\Sigma_{0j}\Sigma_{j0}) = \frac{1}{\sqrt{\nu v_0}} \operatorname{tr}(Q_jQ_0), \quad j = 1, \dots, p-1.$$

5. EVALUATION OF THE CONSTANT

The evaluation of the constant d can be done using an Edgeworth approximation of order $1/\sqrt{N}$ as discussed by Arvesen and McCabe (1975). But, as they have remarked, this may be a formidable problem for $p \ge 4$ or 5. So we resort to Monte Carlo technique. The steps involved are described below.

- (1) Generate random observations Y_1, \ldots, Y_N from a standard normal distribution.
- (2) Calculate SS_i , i = 0,1,...,p-1.
- (3) Form the ratio A = min SS_i/SS_0 . $1 \le i \le p-1$
- (4) Repeat steps 1 to 3 m times retaining the values A_1, A_2, \ldots, A_m .
- (5) Denote the ordered A_i by $A_{[1]} \leq \ldots \leq A_{[m]}$.

Then the estimate of d is $\hat{d} = A_{[r+1]}$, where r is an integer such that $r/m \leq (1-P^*) < (r+1)/m$.

Based on the experiences of McCabe and Arvesen (1974) with their problem, it appears that m = 1000 may give adequate estimates.

6. IMPLEMENTATION OF THE PROCEDURE

The procedure R in (3.1) can be restated as follows.

7. ACKNOWLEDGEMENT

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