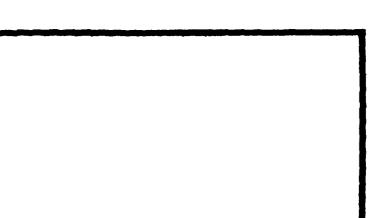
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DEPARTMENT OF THE AIR FORCE
AIR UNIVERSITY (ATC)

# AIR FORCE INSTITUTE OF TECHNOLOGY

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master's thesis,

ANALYSIS OF MODES IN AN UNSTÄBLE STRIP LASER BESONATOR.

THESIS

AFIT/GEP/PH/80D-7 /James E./Rowley USAF

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23 JAN 1981

Laurel A. Lampela LAUREL A. LAMPELA, 2Lt, USAF

Deputy Director, Public Affairs

Air Force Institute of Technology (ATC) Weight-Patterson AFB, OH 45433

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# ANALYSIS OF MODES IN AN UNSTABLE STRIP LASER RESONATOR

THESIS

Presented to the Faculty of the School of Engineering
of the Air Force Institute of Technology
Air University
in Partial Fulfillment of the
Requirements for the Degree of
Master of Science

bу

James E. Rowley, B.S.

2Lt

USAF

Graduate Engineering Physics

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Approved for public release; distribution unlimited

#### Preface

I would like to give special thanks to Captain Mark Rogers for the use of his plotting routine and for supplying me with the Moore and McCarthy Code. I would also like to thank Dr. D. Lee of the AFIT Math department for supplying the error function subroutine.

Most of all, I would like to thank my advisor, Major

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the really ellusive bugs, and for offering freely of his

invaluable insight.

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#### List of Symbols

```
series function weighting constants
bn
           series function weighting constants
c<sub>n</sub>
           series function weighting constants
E( )
           Fresnel integral
F .
           Ordinary Fresnel #
Fn
           Series function
           i<sup>th</sup> mirror g parameter
9<sub>i</sub>
g( )
           Eigenfunction
Gn
           Series function
           relative amplitude of basis wave
h
Hn
           Sum of functions F_n and G_n
i
           √-I
^{\rm I}{\rm sat}
           Saturation intensity
k
           Wave #
           Cavity length
           Magnification
m
           Mirror 1
M<sub>1</sub>
M<sub>2</sub>
           Mirror 2
           Number of terms in series of H_n's
N
N_f, NEQ
           Effective Fresnel number
           Power
           Radius Curvature, M<sub>1</sub>
R_1
           Radius Curvature, M<sub>2</sub>
R_2
```

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#### Abstract

The mode eigenvalue equation for an unstable strip laser resonator is developed from scalar diffraction theory. The field distributions are expressed as a series and the integral is then evaluated using a first order approximation to the method of stationary phase. The resulting approximate closed form is rearranged to form an eigenvalue polynomial, the roots of which are the mode eigenvalues. Eigenfunction expressions are then developed using a second order approximation to the method of stationary phase. Modifications to these expressions are then made to account for the presence of uniform gain in the resonator.

The results of a computer program using the derived expressions are presented. Comparisons to previously published results are made for the bare cavity case, and results for the loaded cavity case follow.

# ANALYSIS OF MODES IN AN UNSTABLE STRIP LASER RESONATOR

#### I. Introduction

#### Background

An unstable laser resonator is a resonator in which the geometric path of a paraxial ray traveling back and forth between the two mirrors is unbounded in an infinite number of passes. This is opposed to a stable resonator, in which the ray path is bounded. Any ray inside an unstable resonator will eventually take on a direction from which it will not come into contact with either mirror, and thus leave the cavity. In this type of resonator, the product of the resonator mirror g parameters, where

$$g_{i} \equiv 1 - \frac{L}{R_{i}}$$
  $i=1,2$ 

lies outside the stable range of

$$0 \leq g_1 g_2 \leq 1$$

The utility or benefits of unstable resonators, for instance large mode volume and minimally transmitting optics (Ref 10:353), require that some method of mode analysis be

available. Several methods are available, but have various drawbacks, such as excessive computer processor time requirements, or limited applicability.

Horwitz (Ref 6) developed a method whereby the mode eigenvalue equation for an unstable strip resonator, modified from the original, developed by Fox and Li (Ref 4), was simplified by using first a series of functions found through asymptotic analysis to approximate the field in the resonator, and then the method of stationary phase to approximate the integral. Butts and Avizonis (Ref 2) clarified this approach and modified it to allow consideration of a resonator with circular mirrors. However, neither allowed for the inclusion of a gain medium in the cavity.

#### <u>Objectives</u>

The objective of this thesis is to develop a computer code allowing analysis of modes in an unstable resonator and to then utilize that code in performing said analysis. The code is to be developed for a strip resonator and account for both bare and loaded cavity cases.

#### Assumptions

To facilitate modeling of the unstable resonator, certain simplifying assumptions will be made:

1. Scalar diffraction theory will be used to describe the physical situation in the resonator. This is reasonable,

since the dimensions of laser resonators are large compared
to optical wavelengths.

- 2. The Fresnel approximation to the Kirchoff-Fresnel formula is valid. Resonator cavity lengths make this an acceptable assumption.
- 3. In a Cartesian system, diffraction integrals and mode eigenfunctions are separable. This allows a 1-D strip resonator to be utilized in the following development.
- 4. One of the resonator mirrors is very much larger than the beam width on that mirror. In other words, that the height of this mirror be considered infinite. This is not an impossible physical constraint.
- 5. The modes in the strip resonator consist of a fundamental cylindrical wave modified by a finite number of diffraction effects. This assumption is supported by early analysis of unstable resonators. (Ref 9:279)

#### Procedure

This thesis will start with the Kirchoff-Fresnel diffraction formula and develop, following Horwitz (Ref 6:1529), the eigenvalue equation for a strip resonator

$$\lambda g(x) = \sqrt{\frac{it}{\pi}} \int_{-1}^{1} e^{-it(y-\frac{x}{m})^2} g(y) dy$$
 (1.3.1)

where the eigenfunctions g(x) are the weighting functions of the basic cylindrical wave assumed to be present in the resonator, that is, if the total field is described by u(x) then (Ref 11),

$$-i\pi N_f x^2$$
  
u(x) = g(x)e (1.3.2)

 $-i\pi N_f x^2$  e being the phase curvature term of the basis cylindrical wave.

The eigenvalues will be found by developing a suitable relation from the eigenvalue equation. The total field in the cavity is first assumed to consist of a unit amplitude cylindrical wave plus a finite series of diffraction supplements. This is stated in terms of g(x) as (Ref 2)

$$g(x) = 1 + \sum_{n=1}^{N} c_n H_n(x)$$
 (1.3.3)

This expression is substituted in the eigenvalue equation and then an approximation to the integral is developed using a first approximation to the method of stationary phase. The resulting relation will allow the eigenvalues to be expressed as roots of a polynomial with determinable coefficients. The roots can be found by using a general root-finding routine.

An eigenfunction expression may then be found by using

the original assumption ie., equation (1.3.3). However, inherent limitations of the first stationary phase approximation confining applicable x values in this relation require the development of a better approximation to the integral. The higher order expression will be developed, using the higher order approximation to the method of stationary phase (Ref 1), enabling the evaluation of the eigenfunctions throughout a continuous range of x values.

This thesis will then seek to modify the bare cavity expressions to account for a gain medium in the resonator by introducing a gain factor,  $e^{2\overline{g}L}$ , into the integral abd by relaxing the unit amplitude requirement on the fundamental cylindrical wave.

#### Organization

The derivation of the basic resonator eigenvalue equation will be covered in Chapter II. Chapter III will present the two applications of that equation: calculation of eigenvalues and evaluation of eigenfunctions. Inclusion of gain considerations will be covered in Chapter IV and Chapter V will contain results of the computer code. Chapter VI will include conclusions and further recommendations.

#### II. Development of the Eigenvalue Equation

Chapter II addresses the problem of applying the Kir-choff-Fresnel diffraction formula to the desired case of an unstable optical resonator. The development follows that in Reference 6.

A steady state mode will exist in a resonator when the field value on one mirror resulting from one round trip through the resonator multiplied by some complex constant is equal to the original field value on that mirror. Mathematically this can be stated as

$$\gamma E^{-}(x,y) = E(x,y)$$
 2.1.1

where E is the original field distribution on  $M_2$  , the second mirror, E´ is the distribution after one round trip, and  $\gamma$  is the constant, in general complex.

Wave propagation through the resonator can be expressed using scalar diffraction theory. Wave propagation from a rectangular aperture, dimensions 2a x 2c , on one plane to another plane a distance L away, as seen in Fig.1, is given in the Fresnel approximation by

$$E(x_2,y_2) = \frac{ie^{-ikL}}{\lambda L} \int_{-c}^{c} \int_{-a}^{a} E(x_1,y_1)e^{-\frac{ik}{2L}[(x_1-x_2)^2+(y_1-y_2)^2]} dx_1 dy_1$$

2.1.2

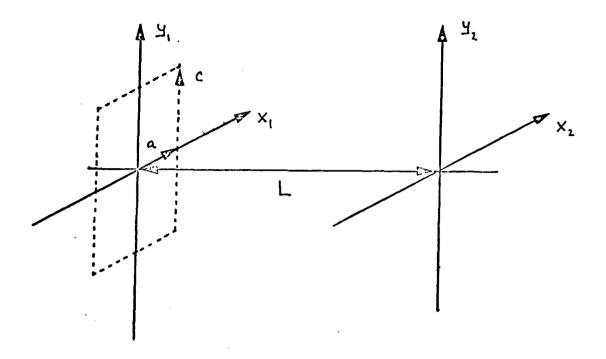


Figure 1

Since this is presented in a Cartesian system, the field distribution can be separated. This is done by assuming (Ref 4:485-486),

$$E(x,y) = U(x)U(y)$$
 2.1.3

Substitution of 2.1.3 into the diffraction formula yields two independent diffraction formulae.

$$U(x_2) = \sqrt{\frac{i}{\lambda L}} e^{-\frac{ikL}{2}} \int_{-a}^{a} U(x_1)e^{-\frac{ik}{2L}(x_1-x_2)^2} dx_1 \qquad 2.1.4$$

$$U(y_2) = \sqrt{\frac{i}{\lambda L}} e^{-\frac{i k L}{2}} \int_{-c}^{c} U(y_1) e^{-\frac{i k}{2 L} (y_1 - y_2)^2} dy_1 \qquad 2.1.5$$

Consideration of only one of these formulae is equivalent to considering diffraction from a strip aperture. No generality is lost, however, since the effects of a finite aperture can be found from the product of two separate strip cases. Thus the one remaining equation is

$$U(x_2) = \sqrt{\frac{i}{\lambda L}} e^{-\frac{ikL}{2}} \int_{-a}^{a} e^{-\frac{ik}{2L}(x_1 - x_2)^2} U(x_1) dx_1 \qquad 2.1.6$$

Equation 2.1.6 represents propagation from one plane to another. For this to correctly represent propagation in a resonator, the phase lag introduced by mirror curvature must be accounted for.

The phase lag introduced by the mirrors can be expressed as a function of distance from the optic axis. This expression can be derived from the paraxial lens thickness function, (Ref 5:80), which is

$$\Delta(x,y) = \Delta_0 - \frac{x^2 + y^2}{2} \left( \frac{1}{R_1} - \frac{1}{R_2} \right)$$
 2.1.7

Where  $\Delta$ = thickness,  $\Delta_0$ = maximum lens thickness, x and y are coordinates of the point where the ray of interest is incident on the lens, and  $R_1$  and  $R_2$  are the radii of

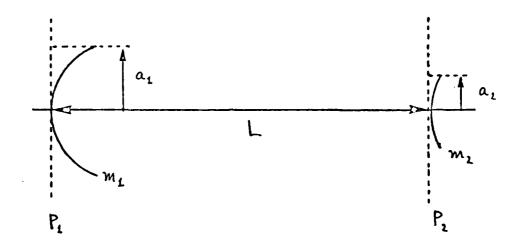


Figure 2

curvature of the lens' surface. In the case of a strip mirror the lens equation applys if

$$R_2 = \infty$$

$$\Delta_0 = 0$$

giving

$$\Delta(x) = \frac{x^2}{2R_i}$$
 2.1.8

for the ith mirror. The phase lag at some particular distance from the optic axis  $\, x \,$  is given by

$$\Delta\phi(x) = \frac{kx^2}{2R}$$
 2.1.9

However, since

$$g_i = 1 - \frac{L}{R_i}$$
 2.1.10

it is seen that

$$1-g_i = \frac{L}{R_i}$$

and

$$\frac{1}{R_i} = \frac{1 - g_i}{L}$$
 2.1.11

where  $g_i$  is the g parameter for the  $i^{th}$  mirror. Therefore the phase lag can be expressed as

$$\Delta \phi_{i} = \frac{kx^{2}}{2} \frac{1-g_{i}}{L} \qquad 2.1.12$$

 $\label{localization} \textbf{Introduction of this phase lag into the diffraction} \\ \textbf{formula gives}$ 

$$U(x_2) = \sqrt{\frac{i}{\lambda L}} e^{-\frac{ikL}{2}} \int_{-a}^{a} U(x_1)$$

$$e^{-\frac{ik}{2L}\left[x_1^2+x_2^2-2x_1x_2-x_1^2(1-g_1)-x_2^2(1-g_2)\right]}dx_1$$

$$U(x_2) = \sqrt{\frac{i}{\lambda L}} e^{-\frac{ikL}{2}} \int_{-a}^{a} U(x_1)e^{-\frac{ik}{2L}[g_1x_1^2 + g_2x_2^2 - 2x_1x_2]} dx_1$$

2.1.13

This expression, now modified to describe propagation of  $U(x_1)$  from  $M_1$  to  $M_2$ , can be used to set up two equations: one for propagation from  $M_2$  to  $M_1$  and the other for propagation from  $M_1$  to  $M_2$ . Combination of the two will then yield an expression describing propagation of a field through one round trip in the resonator. The one way formulae are

$$U(x_2) = e^{-\frac{i k L}{2}} \sqrt{\frac{i}{\lambda L}} \int_{-a_1}^{a_1} U(x_1) e^{-\frac{i k}{2 L} [g_1 x_1^2 + g_2 x_2^2 - 2x_1^2 x_2]} dx_1$$
2.1.14

and

$$U(x_1) = e^{-\frac{i k L}{2}} \sqrt{\frac{i}{\lambda L}} \int_{-a_2}^{a_2} U(x_2) e^{-\frac{i k}{2 L} [g_1 x_1^2 + g_2 x_2^2 - 2x_1 x_2^2]} dx_2^2$$
2.1.15

If 2.1.15 is substituted for  $u(x_1^c)$  in 2.1.14, the resultant expression will give the field on  $M_2$  due to the propagation of an original field on  $M_2$  through one round trip in the resonator. Substitution gives

$$U(x_2) = e^{-ikL} \sqrt{i/\lambda L} \int_{-a_2}^{a_2} \sqrt{i/\lambda L} \int_{-a_1}^{a_1} U(x_2^2)$$

$$e^{-\frac{ik}{2L}[g_1x_1^2+g_2x_2^2-2x_1^2x_2^2]}dx_2^2e^{-\frac{ik}{2L}[g_1x_1^2+g_2x_2^2-2x_1^2x_2]}dx_1^2$$

2.1.16

In the case considered in Fig. 2, the assumption that  $M_1$  is much bigger than the beam width on that mirror for any laser mode that is likely to resonate, allows  $a_1$  to be thought of as essentially infinite. Then 2.1.16 becomes

$$U(x_2) = e^{ikL} \int_{-a_2}^{a_2} \int_{-\infty}^{\infty} \frac{i}{\lambda L} e^{\frac{ik}{2L} [g_1 x_1^2 + g_2 x_2^2 - 2x_1^2 x_2^2]}$$

$$-\frac{ik}{2L}[g_1x_1^2+g_2x_2^2-2^2x_2]$$
e
$$U(x_2^2)dx_1^2dx_2^2$$
2.1.17

This expression can be simplified by extracting the interior integral

$$\frac{i}{\lambda L} \int_{-\infty}^{\infty} e^{-\frac{i k}{2 L} [g_1 x_1^2 + g_2 x_2^2 - 2x_1^2 x_2^2]}$$

$$e^{-\frac{ik}{2L}[g_1x_1^2+g_2x_2^2-2x_1^2x_2]} dx_1^2 \qquad 2.1.18$$

Evaluation of this integral in Appendix B yields

$$\sqrt{\frac{i}{2L\lambda g}} e^{-\frac{i}{2\lambda Lg_1} \left[ (2g_1g_2-1)(x_2^2+x_2^2)-2x_2x_2^2 \right]}$$
 2.1.19

Substitution of this for the complete kernel in 2.1.17 in turn yields

$$U(x_2) = e^{-ikL} \sqrt{\frac{i}{2L\lambda g_1}} \int_{-a_2}^{a_2}$$

$$e^{-\frac{i\pi}{\lambda L 2g_1} \left[ (2g_1g_2 - 1)(x_2^2 + x_2^2) - 2x_2x_2^2 \right]} U(x_2^2) dx_2^2$$
2.1.20

To simplify this further, the definitions

$$2g_1g_2-1 \equiv g$$
 2.1.21

and

$$\frac{a_2^2}{2g_1 \lambda L} = \frac{F_2}{2g_1} \equiv F$$
 2.1.22

are introduced.

Here,  $g_1$  and  $g_2$  are the familiar g parameters and  $F_2$  is the ordinary Fresnel number of the smaller feedback mirror. The ordinary Fresnel number is defined as the additional length per pass in half wavelengths for a ray traveling from one mirror's center to the other mirror's edge, compared to one traveling from mirror center to mirror

center. (Ref 11:159-161).

The dimensions of the quantities are also scaled such that  $a_2\!=\!1$  . These modifications yield

$$U(x_2) = e^{-ikL} \sqrt{iF} \int_{-1}^{1} U(x_2^2) e^{-i\pi F[g(x_2^2 + x_2) - 2x_2 x_2^2]} dx_2^2 = 2.1.23$$

Imposition of the reproducability constraint, equation 2.1.1, and absorption of the constant  $e^{-ikL}$  into  $\gamma$  yields

$$\gamma U(x_2) = \sqrt{iF} \int_{-1}^{1} U(x_2) e^{-i\pi F \left[g(x_2^2 + x_2^2) - 2x_2 x_2^2\right]} dx_2^2 \qquad 2.1.24$$

Introducing the dummy variable y and dropping subscripts and superscripts yields

$$\gamma U(x) = \sqrt{iF} \int_{-1}^{1} U(y) e^{-i\pi F[g(x^2+y^2)-2xy]} dy$$
 2.1.25

To further simplify this equation, the following quantities are defined

$$N_f = \frac{F}{2}(m - \frac{1}{m})$$
 2.1.26

and g(x) such that

$$U(x) = e^{-i\pi N} f^{x^2} g(x)$$
 2.1.27

N<sub>f</sub> is the equivalent Fresnel number of the resonator. The equivalent Fresnel number can be interpreted as the additional path length per pass in half wavelengths for a ray traveling from a mirror's virtual center to the edge of the next mirror, as opposed to a ray traveling from the virtual center of one mirror to the actual center of the next (Ref 11:159-161). The virtual center is defined as that point from which a cylindrical wave would eminate if that wave were to be reflected from a feedback mirror, and then return to the original mirror in the same form as when it left (Ref 9:279-280). That cylindrical wave is then assumed to take the form

$$e^{-i\pi N_f x^2}$$

and the entire wave function is assumed to be based on that wave, stated by 2.1.27. Substitution of 2.1.26 and 2.1.27 into 2.1.25 yields

$$\gamma g(x)e^{-i\pi \frac{F}{2}(\frac{m^2-1}{m})x^2} = \sqrt{iF} \int_{-1}^{1} g(y)e^{-i\pi Fy^2(\frac{m^2-1}{2m})}$$

$$e^{-i\pi F[g(x^2+y^2)-2xy]}$$
 e dy 2.1.29

After some manipulation, detailed in Appendix C,

2.1.29 simplifies to the final form of the resonator integral equation

$$\gamma g(x) = \sqrt{it/\pi m} \int_{-1}^{1} g(y)e^{-it(y-\frac{x}{m})^{2}} dy$$
 2.1.30

where

$$t = \pi mF$$

2.1.31

and if

$$\lambda = \gamma \sqrt{m}$$

2.1.32

$$\lambda g(x) = \sqrt{it/\pi} \int_{-1}^{1} e^{-it(y-\frac{x}{m})^{2}} g(y) dy$$
 2.1.33

# III. <u>Determination of Eigenvalues and</u> <u>Evaluation of Eigenfunctions</u>

Chapter III is concerned with solving the resonator mode eigenvalue equation and with developing expressions for the resulting eigenfunctions. The eigenfunctions are most desireable since they will ultimately express field values across the output mirror plane.

#### Approximation of Eigenvalue Equation

The eigenvalue equation that must be solved is

$$\lambda g(x) = \sqrt{it/\pi} \int_{-1}^{1} g(y)e^{-it(y-\frac{x}{m})^{2}} dy$$
 3.1.1

where g(x) is the quantity multiplying the primary cylindrical wave expressed as a function of normal distance from the optic axis.

Now it is assumed that the field on the mirror before the round trip, U(y), consists of a unit amplitude cylindrical wave plus an infinite series of edge diffracted waves given by some functions  $H_n(y)$  (Ref 2). In terms of g(y) this is stated as

$$g(y) = 1 + \sum_{n=1}^{\infty} c_n H_n(y)$$
 3.1.2

The physical basis for this assumption is that the original field on M2 will consist of that primary cylindrical wave which makes the round trip unchanged plus other contributions which are the diffraction additions to that wave from previous reflections. To make this viable, however, it is then assumed that the series terminates when eventually some function  $H_N(y)$  is the last contribution that has any new effect on the field, or that  $H_{N+1}(y)$  is constant. If the resonator is thought of as an infinite lens train, the mode components between the last two lenses will consist of the basic cylindrical wave and one diffraction effected wave from each preceeding lens group. series terminates when the consideration of another lens group, farther back, adds no more new information to the final mode. Then the addition of one more diffraction effected wave would add only to amplitude, and not change the shape of the total wave. 3.1.2 then becomes  $g(y)=1+\sum_{n=1}^{\infty} c_n H_n(y)$  . A good approximation is to let (Ref. 6:1533)

$$N \ge \frac{\ln 250N_f}{\ln m}$$
 3.1.3

and the quality of this approximation is displayed in Appendix E.

When 3.1.2 is substituted into 3.1.1, the result is

$$\lambda g(x) = \sqrt{it/\pi} \int_{-1}^{1} \left\{ 1 + \sum_{n=1}^{N} c_n H_n(y) \right\} e^{-it(y - \frac{x}{m})^2} dy$$
 3.1.4

Some method of approximating this integral is needed.

The method chosen is the method of stationary phase. This

method states that an integral of the form

$$\int_{a}^{b} e^{-i t p(y)} q(y) dy$$
 3.1.5

can, when t is large and q(y) is slowly varying, be expressed as a series, the first two terms of which are approximately (Ref.2:1073).

$$e^{-i\pi/4}q(y_0)e^{-itp(y_0)} \sqrt{\frac{2\pi}{tp''(y_0)}}$$

$$+\frac{i}{t}\left[\frac{q(b)}{p^{2}(b)}e^{-itp(b)}-\frac{q(a)}{p^{2}(a)}e^{-itp(a)}\right]$$
 3.1.6

where  $y_0$  is the point of stationary phase, ie.

$$p'(y_0) = 0$$
 3.1.7

To utilize this however some explicit form of  $H_n(y)$  is needed. The form used here is the same as that developed by Horwitz through asymptotic analysis of the resonator integral, 2.1.33. The form is as follows:

Given the functions (Ref 3)

$$F(x,t) = -\frac{1}{2\sqrt{i\pi t}} \frac{e^{-it(1-x)^2}}{1-x}$$
 3.1.8

$$G(x,t) = -\frac{1}{2\sqrt{i\pi t}} \frac{e^{-it(1+x)^2}}{1+x}$$
 3.1.9

the functions  $F_n(x)$  and  $G_n(x)$  are formed such that

$$F_{n}(x) = F\left(\frac{x}{m^{n}}, \frac{t}{m_{n-1}}\right)$$
 3.1.10

and

$$G_n(x) = G\left(\frac{x}{m^n}, \frac{t}{m_{n-1}}\right)$$
 3.1.11

where

$$m_n = \sum_{k=0}^{n} m^{-2k}$$
 3.1.12

**and** m is the magnification.

It is therefore seen that

$$F_{n}(x) = -\frac{\sqrt{m_{n-1}}}{2\sqrt{i\pi t}} \frac{-it(1-\frac{x}{m^{n}})^{2}/m_{n-1}}{1-x/m^{n}}$$
 3.1.13

and

$$G_n(x) = -\frac{\sqrt{m_{n-1}}}{2\sqrt{i\pi t}} \frac{e^{-it(1+\frac{x}{m^n})^2/m_{n-1}}}{1+x/m^n}$$
 3.1.14

 $H_n(x)$  is then assumed to be some combination of these functions:

$$c_n H_n(x) = a_n F_n(x) + b_n G_n(x)$$
 3.1.15

Since the cavity under consideration here is centered on the optic axis, symmetry dictates either odd or even field functions. To get an even field function, then it is assumed that  $H_n(x)$  is even. Odd would require that  $H_n(x)$  be odd.

It is seen from 3.13-3.15 that  $H_n(x)$  can be made even if  $a_n = b_n$  . So, if

$$a_n = b_n$$
 3.1.16

then with

$$c_n = a_n = b_n$$
 3.1.17

$$c_n H_n(x) = c_n (F_n(x) + G_n(x))$$
 3.1.18

and

$$c_n H_n(-x) = c_n (F_n(-x) + G_n(-x))$$
 3.1.19

However, since

$$F_n(x) = G_n(-x)$$
 3.1.20

$$c_n H_n(-x) = c_n(G_n(x) + F_n(x))$$
 3.1.21

$$= c_n H_n(x)$$
 3.1.22

Thus,  $H_n(x)$  is an even function.

Similarly,  $H_n(x)$  can be made odd by assuming

$$a_n = -b_n$$
 3.1.23

and that

$$a_n = -b_n = c_n$$
 3.1.24

it is seen that

$$c_n H_n(x) = c_n (F_n(x) - G_n(x))$$
 3.1.25

and

$$c_n H_n(-x) = c_n(F_n(-x)-G_n(-x))$$
 3.1.26  
=  $c_n(G_n(x)-F_n(x))$  3.1.27  
=  $-c_n H_n(x)$  3.1.28

Thus  $H_n(x)$  is an odd function. One additional assumption is that in the odd case, the amplitude of the cylindrical wave is zero. This is necessary for the field function to be odd.

In the following development, the even parity case will be the one dealt with. The odd parity equations can be found from those for the even case by deleting the leading term in eq. 3.1.2 and following the procedure as above.

Therefore, the eigenvalue equation to be solved is

$$\lambda g(x) = \sqrt{it/\pi} \int_{-1}^{1} e^{-it(y-\frac{x}{m})^2}$$

$$\left\{1 + \sum_{n=1}^{N} (a_n F_n(y) + b_n G_n(y))\right\} dy \qquad 3.1.29$$

Substitution of the actual forms of the functions allows explicit forms of p(y) and g(y) found in 3.1.4 and 3.1.5 to be found. Employing equation 3.1.5, according to Appendix A allows the following first order approximation

$$\lambda g(x) \simeq 1+F_1(x)+G_1(x)$$

+ 
$$\sum_{n=1}^{N} (a_n F_{n+1}(x) + b_n G_{n+1}(x))$$

+F<sub>1</sub>(x)
$$\sum_{n=1}^{N}$$
(a<sub>n</sub>F<sub>n</sub>(1)+b<sub>n</sub>G<sub>n</sub>(1))

$$+G_1(x)\sum_{n=1}^{N}(a_nF_n(-1)+b_nG_n(-1))$$
 3.1.30

$$= 1 + H_1(x) + \sum_{n=1}^{N} c_n H_{n+1}(x) + H_1(x) \sum_{n=1}^{N} c_n H_n(1)$$
3.1.31

$$= \lambda (1 + \sum_{n=1}^{N} c_n H_n(x))$$
 3.1.32

In the odd case this would become

$$\lambda \sum_{n=1}^{N} c_{n} H_{n}(x) \simeq \sum_{n=1}^{N} c_{n} H_{n+1}(x) + H_{1}(x) \sum_{n=1}^{N} c_{n} H_{n}(1) \qquad 3.1.33$$

## The Eigenvalue Polynomial

In the even parity case, the eigenvalue equation is approximately given by

$$\lambda(1+\sum_{n=1}^{N}c_{n}H_{n}(x)) \simeq 1+H_{1}(x)+\sum_{n=1}^{N}c_{n}H_{n=1}(x)$$

$$+H_1(x)\sum_{n=1}^{N}c_nH_n(1)$$
 3.2.1

The relation between  $\,\lambda\,$  and the known functions is constructed in the following manner:

First, the coefficients of terms in 3.2.1 involving  $H_{\mathbf{n}}(\mathbf{x})$  , where  $\mathbf{n} \neq 1$  , are set equal:

$$\lambda c_{n+1} = c_n \qquad \qquad 3.2.2$$

It follows that

$$c_{n+1} = \frac{c_n}{\lambda}$$
 3.2.3

$$c_2 = \frac{c_1}{\lambda}$$
,  $c_3 = \frac{c_2}{\lambda} = \frac{c_1}{\lambda \cdot \lambda}$  3.2.4

and generally it is seen that

$$c_{n+1} = \frac{c_1}{\lambda^n} = \frac{c_n}{\lambda}$$
 3.2.5

In other words

$$c_1 \lambda = c_n \lambda^n$$
 3.2.6

$$= c_N \lambda^N \qquad 3.2.7$$

This in turn implies that

$$c_n = c_N \lambda^{N-n}$$
 3.2.8

Equating coefficients of H(x) now yields

$$\lambda c_1 = 1 + \sum_{n=1}^{N} c_n H_n(1)$$
 3.2.9

Substituting for  $c_n$  and  $c_1$  according to 3.2.8, gives

$$\lambda c_N \lambda^{N-1} = 1 + \sum_{n=1}^{N} c_N \lambda^{N-n} H_n(1)$$
 3.2.10

Equating constant terms in 3.2.1 shows that

$$\lambda = 1 + c_N H_{N+1}$$
 3.2.11

$$\lambda - 1 = c_N^H_{N+1}$$
 3.2.12

$$\frac{\lambda - 1}{H_{N+1}} = c_N \qquad \qquad 3.2.13$$

Substituting for  $c_N$  in 3.2.10 according to 3.2.13 yields

$$\frac{\lambda(\lambda-1)\lambda^{N-1}}{H_{N+1}} = 1 + \sum_{n=1}^{N} \frac{(\lambda-1)\lambda^{N-n}}{H_{N+1}} H_n(1) \qquad 3.2.14$$

or

$$\lambda^{N}(\lambda-1) = H_{N+1} + (\lambda-1) \sum_{n=1}^{N} \lambda^{N-n} H_{n}(1)$$
 3.2.15

which is a polynomial in the complex variable  $\lambda$  . Its roots can be determined from any root-finding subroutine, since its coefficients all involve known quantities such as

$$H_n(1)$$

or the constant

$$H_{N+1}$$

It is from this polynomial that the mode eigenvalues of the resonator are determined. A preliminary evaluation of the eigenfunction for a particular mode can be made by substituting into equation 3.1.2 the values for  $\, c_n \,$ , which are given by

$$c_{n} = c_{N} \lambda^{N-n}$$

$$= \frac{(\lambda - 1)}{H_{N+1}} \lambda^{N-n}$$
3.2.16

However, due to the singularities in the first approximation to the integral, 3.1.6, whenever x approaches  $y_0$ , this particular expression for the eigenfunction is invalid. This problem will be remedied in the next section.

The odd parity solution is given by 3.1.33, and the polynomial development for that case is as follows.

After equating the coefficients of  $H_n(x)$ ,  $n \ne 1$ , it is seen that the same relations arise as 3.2.2 - 3.2.8.

Equating coefficients of  $H_1(x)$  indicates that

$$\lambda c_1 = \sum_{n=1}^{N} c_n H_n(1)$$
 3.2.17

Equating constant terms indicates that

$$0 = c_N H_{N+1}$$

This is only reasonable since the condition imposed on  $\,N\,$  , namely that  $\,H_{\,N+1}\,$  is a constant, also implies that

$$F_{N+1} = Constant = G_{N+1}$$
 3.2.18

and since

$$H_{N+1} = F_{N+1} - G_{N+1}$$
 3.2.19

$$H_{N+1} = 0$$
 3.2.20

This indicates that  $\,c_n\,$  is completely arbitrary since there are no other restrictions imposed by either 3.2.8 or 3.2.17. If  $\,c_n\,$  is indeed arbitrary, and

$$c_n = c_N \lambda^{N-n}$$
 3.2.21

then  $c_n$  can be chosen such that

$$c_n \lambda^n = c_N \lambda^N = 1 \qquad 3.2.22$$

leaving the relation

$$c_n = \lambda^{-n}$$
 3.2.23

which can be used in the limited range eigenfunction expression for the odd parity case.

The polynomial is developed by substitution for  $\ c_n$  of 3.2.8 in 3.2.17 giving

$$\lambda c_1 = \sum_{n=1}^{N} c_n H_n(1)$$
 3.2.24

$$\lambda c_N \lambda^{N-1} = \sum_{n=1}^{N} c_N \lambda^{N-n} H_n(1)$$
 3.2.25

$$\lambda^{N} = \sum_{n=1}^{N} \lambda^{N-n} H_{n}(1)$$
 3.2.26

### Development of Eigenfunction

### Expressions Valid for All X

To develop an eigenfunction expression valid for all x, it is first necessary to return to the original equation, 2.1.32, which is

$$\lambda g(x) = \sqrt{\frac{it}{\pi}} \int_{-1}^{1} g(y)e^{-it(y-\frac{X}{M})^{2}} dy$$
 3.3.1

Since the eigenvalues are known or can be determined, it can then be said that

$$g(x) = \frac{1}{\lambda} \sqrt{i t / \pi} \int_{-1}^{1} \left[ 1 + \sum_{n=1}^{N} c_n H_n(y) \right] e^{-i t (y - \frac{x}{m})^2} dy$$
 3.3.2

One might question the validity of this expression, since  $\lambda$  was determined from the first order approximation. However, that previous approximation yields perfectly valid values for  $\lambda$  , because all that determines the mode eigenvalue is the field on the smaller feedback mirror,

where  $x \le 1$ . In this region, the approximation is always valid. Therefore the  $\lambda$ 's are perfectly valid.

All expressions and quantities on the right side of 3.3.1 are known, and therefore one can once again utilize the method of stationary phase, but in a second approximation, yielding an expression no longer as simple as 3.1.6 but one that is valid for all x . The higher approximation to the integral is given by (Ref 1)

$$I = e^{-itp(b)}q(b) \sqrt{\frac{\pi}{tp^{\prime}(b)}} e^{-\frac{itp^{\prime}(b)^2}{2p^{\prime\prime}(b)}}$$

$$\left\{E \star \left(\sqrt{\frac{t}{\pi p^{\prime\prime}(b)}} p^{\prime}(b)\right) - \frac{1-i}{2}\right\} - e^{-itp(a)}$$

$$q(a) \sqrt{\frac{\pi}{tp^{2}(a)}} e^{-\frac{itp^{2}(a)^{2}}{2p^{2}(a)}}$$

$$\left\{E^{\bullet}\left(\sqrt{\frac{t}{\pi p^{-\prime}(a)}} p^{\prime}(a)\right) - \frac{1-i}{2}\right\}$$
 3.3.3

wnen  $y_0$  is such that

$$y_0 \le a$$
 3.3.4

and

$$\approx e^{-i\pi/4}q(y_0) e^{-itp(y_0)} \sqrt{\frac{2\pi}{tp^2(y_0)}}$$

$$+e^{-itp(b)}\sqrt{\frac{\pi}{tp^{-}(b)}}e^{-\frac{itp^{-}(b)^{2}}{2p^{-}(b)}}\left\{E*\left(\sqrt{\frac{t}{\pi p^{-}(b)}}p^{-}(b)\right)-\frac{1-i}{2}\right\}$$

$$-e^{-tp(a)} \sqrt{\frac{\pi}{tp^{-}(a)}} e^{-\frac{itp^{-}(a)^{2}}{2p^{-}(a)}} \left\{ E^{*} \left( \sqrt{\frac{t}{\pi p^{-}(a)}} p^{-}(a) \right) + \frac{1-i}{2} \right\}$$

3.3.5

when  $y_{\theta}$  is such that

$$a \le y \le b$$
 3.3.6

and

$$= e^{-itp(b)} \sqrt{\frac{\pi}{tp^{-}(b)}} e^{-\frac{itp^{-}(b)^{2}}{2p^{-}(b)}} \left\{ E \times \left( \sqrt{\frac{t}{\pi p^{-}(b)}} p^{-}(b) \right) + \frac{1-i}{2} \right\}$$

$$-e^{-itp(a)} \sqrt{\frac{\pi}{tp^{\prime\prime}(a)}} e^{-\frac{itp^{\prime\prime}(a)^{2}}{2p^{\prime\prime\prime}(a)}} \left\{ E^{\bullet} \left( \sqrt{\frac{t}{\pi p^{\prime\prime\prime}(a)}} p^{\prime\prime}(a) \right) + \frac{1-i}{2} \right\}$$

3.3.7

when  $y_0$  is such that

$$y_0 \ge b$$
 3.3.8

Here, E\* is the complex conjugate of the Fresnel integral.

In both the even and the odd cases the integral

$$\frac{1}{\lambda} \sqrt{it/\pi} \int_{-1}^{1} e^{-it(y-\frac{x}{m})^{2}} \sum_{n=1}^{N} (a_{n}F_{n}(y)+b_{n}G_{n}(y)) dy \qquad 3.3.9$$

must be evaluated. Specific differences for even and odd cases will be treated later. Manipulating 3.3.5 yields

$$\frac{1}{\lambda} \sqrt{it/\pi} \sum_{n=1}^{N} \int_{-1}^{1} e^{-it(y-\frac{x}{m})^{2}} (a_{n} F_{n}(y) + b_{n} G_{n}(y)) dy \qquad 3.3.10$$

To make use of equations 3.3.3, 3.3.5 and 3.3.7, it is necessary to get p(y) and q(y) expressions for the  $n^{th}$  term in the series. Substitution of the explicit forms of the  $F_n$  and  $G_n$  functions yields an integral of the form

$$\int_{-1}^{1} e^{-it(y-\frac{x}{m})^{2}} \left[ -\frac{\sqrt{a_{n} m_{n-1}}}{2\sqrt{i\pi t}} \frac{e^{-it(1-\frac{y}{m}n)^{2}/m_{n-1}}}{1-\frac{y}{m^{n}}} - \frac{b_{n}\sqrt{m_{n-1}}}{2\sqrt{i\pi t}} \frac{e^{-it(1+y/m^{n})^{2}/m_{n-1}}}{1+\frac{y}{m^{n}}} \right] dy \qquad 3.3.11$$

where  $m_n$  has been previously defined in 3.1.12.

Upon consideration of the term involving the  $\[ \mathbf{a}_{n} \]$  constants, it is seen that

$$p(y) = (y - \frac{x}{m})^2 + \frac{(1 - \frac{y}{mn})^2}{m_{n-1}}$$
 3.3.12

$$p'(y) = 2(y-\frac{x}{m}) - \frac{2}{m_{n-1}} \frac{1}{m^n} (1-\frac{y}{m^n})$$
 3.3.13

$$p^{-}(y) = 2 + \frac{2}{m_{n-1}m^{2n}}$$
 3.3.14

$$q(y) = \frac{1}{1 - \frac{y}{mn}}$$
 3.3.15

Solving for  $y_0$  yields

$$y_0 - \frac{x}{m} - \frac{1}{m_{n-1}m^n} + \frac{y_0}{m_{n-1}m^2n} = 0$$
 3.3.16

$$y_0 \left(1 + \frac{1}{m_{n-1}m^n}\right) = \frac{x}{m} + \frac{1}{m_{n-1}m^n}$$
 3.3.17

$$y_{n}^{a} = \left(\frac{x}{m} + \frac{1}{m^{n}m_{n-1}}\right) \left(\frac{1}{1 + \frac{1}{m_{n-1}m^{2}n}}\right)$$
 3.3.18

Similarly, for the part involving the  $\, b_n \,$  constants it is seen that

$$p(y) = (y - \frac{x}{m})^2 + \frac{\left(1 + \frac{y}{mn}\right)^2}{m_{n-1}}$$
 3.3.19

$$p'(y) = 2(y-\frac{x}{m}) + \frac{2}{n-1} \frac{1}{m^n} (1+\frac{y}{m^n})$$
 3.3.20

$$p^{-}(y) = 2 + \frac{2}{m^2 n_{n-1}}$$
 3.3.21

$$q(y) = \frac{1}{1 + \frac{y}{m0}}$$
 3.3.22

Solving for  $y_0$  , it is seen that

$$y_0 - \frac{x}{M} + \frac{1}{m^n m_{n-1}} + \frac{y_0}{m^2 n_{n-1}} = 0$$
 3.3.23

$$y_0 \left( 1 + \frac{1}{m^2 n_{m-1}} \right) = \frac{x}{m} - \frac{1}{m^n m_{n-1}}$$
 3.3.24

$$y_0^b = \left(\frac{x}{m} - \frac{1}{m^n m_{n-1}}\right) \left(\frac{1}{1 + \frac{1}{m^{2n} m_{n-1}}}\right)$$
 3.3.25

These expressions can now be substituted into the overall approximations to the integral. However, in evaluation careful consideration of the  $y_0$  values must be taken, in

order that the proper form of the approximation is used. This is rather complicated, since there are two  $y_0$ 's : one for the  $a_n$  term, and one for the  $b_n$  term.

In order to simplify things, let

$$-\frac{a_{n}\sqrt{m_{n-1}}}{2\sqrt{i\pi t}} \begin{cases} e^{-it\left[\left(1-\frac{x}{m}\right)^{2}+\left(1-\frac{1}{m^{n}}\right)^{2}/m_{n-1}\right]} & \sqrt{\frac{\pi}{2t\left(1+\frac{1}{m^{2}n_{m-1}}\right)}} \\ +4it\left[1-\frac{x}{m}-\frac{1-\frac{1}{m^{n}}}{m^{n}m_{n-1}}\right]^{2}/4\cdot 1+\frac{1}{m^{2}n_{m-1}}\cdot \left[E^{*}\sqrt{\frac{t}{2\pi\left(1+\frac{1}{m^{2}n_{m-1}}\right)}} \right] \\ \cdot \left(2\left(1-\frac{x}{m}\right)-\frac{2}{m^{n}m_{n-1}}\left(1-\frac{1}{m^{n}}\right)\right)\right)-\frac{1-i}{2} \end{cases} + \frac{a_{n}}{2\sqrt{i\pi t}} \\ \begin{cases} e^{-it\left[\left(-1-\frac{x}{m}\right)^{2}+\left(1+\frac{1}{m^{n}}\right)^{2}/m_{n-1}\right]}\sqrt{\frac{\pi}{2t\left(1+\frac{1}{m^{2}n_{m-1}}\right)}} \\ e^{-it\left[-1-\frac{x}{m}-\left(-1+\frac{1}{m^{n}}\right)^{m}m_{n-1}\right]^{2}}\sqrt{4\cdot 1+1\sqrt{m^{2}n_{m-1}}} \\ e^{-it\left[-1-\frac{x}{m}-\left(-1+\frac{1}{m^{n}}\right)^{m}m_{n-1}\right]^{2}}\sqrt{4\cdot 1+1\sqrt{m^{2}n_{m-1}}} \\ = ATERM \end{cases}$$

$$3.3.26$$

when  $y_0^a \le -1$ . When  $y_0^b$  is in the same region, let

$$-\frac{b_{n}\sqrt{m_{n-1}}}{2\sqrt{i\pi t}} \left\{ \frac{e^{-it\left[\left(1-\frac{x}{m}\right)^{2}+\left(1+\frac{1}{m^{n}}\right)^{2}/m_{n-1}\right]}}{1-\frac{1}{m^{n}}}\sqrt{\frac{\pi}{2t\left(1+\frac{1}{m^{2}n_{m-1}}\right)}} \right\}$$

4it 
$$\left[1 - \frac{x}{m} + \left(1 + \frac{1}{mn}\right) / m_{n-1} m^n\right]^2 / 4 \cdot 1 + \frac{1}{m^2 n_{m-1}}$$

$$\left\{ E * \left( \sqrt{\frac{t}{2\pi \left( 1 + \frac{1}{m^{2} n_{m-1}} \right)}} \left( 2 \left( 1 - \frac{x}{m} \right) + \frac{2}{m^{n} m_{n-1}} \left( 1 + \frac{1}{m^{n}} \right) \right) - \frac{1 - i}{2} \right\} \right\}$$

$$+ \frac{b_{n}\sqrt{m_{n-1}}}{2\sqrt{i\pi t}} \begin{cases} \frac{-it\left[\left(-1-\frac{x}{m}\right)^{2}+\left(1-\frac{1}{m^{n}}\right)^{2}/m_{n-1}\right]}{1-\frac{1}{m^{n}}} \sqrt{\frac{\pi}{2t\left(1+\frac{1}{m^{2}n_{m-1}}\right)}} \end{cases}$$

4it 
$$-1 - \frac{x}{m} + (1 - \frac{1}{m^n}) / m_{n-1} m^n = 4 \cdot 1 + \frac{1}{m^2 n_{m-1}}$$

• e

$$\cdot \left\{ E * \left( \sqrt{\frac{t}{2\pi \left( 1 + \frac{1}{m^2 n_{m-1}} \right)}} \left( 2 \left( -1 - \frac{x}{m} \right) + \frac{2}{m^n m_{n-1}} \left( 1 - \frac{1}{m^n} \right) \right) - \frac{1 - i}{2} \right) \right\}$$

= BTERM

3.3.27

Then, it can be said that

$$\int_{-1}^{1} e^{-it(y-\frac{x}{m})^{2}} (a_{n}F_{n}(y)+b_{n}G_{n}(y)) \simeq ATERM + BTERM \qquad 3.3.28$$

provided that both points of stationary phase are less than negative one, the lower endpoint of the integral. Therefore, in that region, 3.3.10 is equal to

$$\frac{1}{\lambda} \sqrt{it/\pi} \sum_{n=1}^{N} \{ATERM + BTERM\}$$
 3.3.29

However, if one or both points of stationary phase fail the magnitude condition, the expressions ATERM and BTERM can be corrected through some slight modifications. If  $y_0^a \ge 1$ , or  $y_0^b \ge -1$  all that has to be done is to change the sign of each  $\frac{1-i}{2}$  term. If either  $y_0$  is such that

$$-1 \stackrel{<}{-} y \stackrel{<}{-} 1$$
 3.3.30

then two things must be done. First, only the second  $\frac{1-i}{2}$  term requires a change of sign. Second, the stationary phase point contribution term must be added to the entire expression.

For the 
$$a_n$$
 term, this contribution is
$$-\frac{a_n\sqrt{m_{n-1}}}{2\sqrt{i\pi t}} \left\{ \frac{e^{-i\pi/4}}{1-y_0^a/m^n} e^{-it\left[\left(y_0^a - \frac{x}{m}\right)^2 + \left(1 - \frac{y_0^a}{m^n}\right)^2 / m_{n-1}\right]} \sqrt{\frac{\pi}{t\left(1 + \frac{1}{m^2 n_{m-1}}\right)}} \right\}$$
3.3.31

and for the  $b_n$  term the contribution is

and for the 
$$b_n$$
 term the contribution is 
$$-\frac{b_n\sqrt{m_{n-1}}}{2\sqrt{i\pi t}} \ \frac{e^{-i\pi/4}}{1 \ y_0^b/m^n} \ e^{-it\left[(y_0^a-\frac{x}{m})^2+(1+\frac{y_0^b}{m^n})^2/m_{n-1}\right]}\sqrt{\frac{\pi}{t\left(1+\frac{y_0^b}{m^2n_{n-1}}\right)}}$$

3.3.32

These expressions are added to ATERM or BTERM, whichever is required. In this way the complete expression for the integral

$$\frac{1}{\lambda} \sum_{n=1}^{N} \int_{-1}^{1} e^{-it(y-\frac{x}{m})^{2}} (a_{n}F_{n}(y)+b_{n}G_{n}(y)) dy \qquad 3.3.33$$

can be stated.

However, in the even parity case, one more modification must be made. The term involving the '1' must be added to the expression. Explicity, that term is

$$\frac{1}{\lambda} \sqrt{i t/\pi} \int_{-1}^{1} e^{-i t (y - \frac{x}{m})^{2}} dy$$
 3.3.34

From this it is seen that

$$p(y) = (y - \frac{x}{m})^2$$
 3.3.35

$$p'(y) = 2(y - \frac{x}{m})$$
 3.3.36

$$p''(y) = 2$$
 3.3.37

$$q(y) = 1$$
 3.3.38

and

$$y_0 = \frac{x}{m}$$
 3.3.39

Substituting into 3.3.2 for  $y_0 \le -1$  gives

$$\frac{1}{\lambda} \sqrt{it/\pi} \left[ e^{-it(1-\frac{x}{m})^{2}} e^{-it/4\cdot4(1-\frac{x}{m})^{2}} \left\{ E \star \left( \sqrt{\frac{t}{2\pi}} \cdot 2(1-\frac{x}{m}) - \frac{1-i}{2} \right) \right\} - e^{-it(-1-\frac{x}{m})^{2}} \sqrt{\frac{\pi}{2t}} e^{it/4\cdot4(-1-\frac{x}{m})^{2}} \left\{ E \star \frac{t}{2\pi} \cdot 2(1-\frac{x}{m}) - \frac{1-i}{2} \right\} \right]_{3.3.40}$$

If  $y_0 \ge 1$ , once again, all that needs to be done is to change the sign of the  $\frac{1-i}{2}$  terms. If  $y_0$  is such that 3.3.30 is satisfied, then only the second  $\frac{1-i}{2}$  term is changed in sign and the stationary phase point contribution term is added. That term is given by

$$e^{-i\pi/4} \sqrt{\pi/t}$$
 3.3.41

Thus, the higher order approximation expressions for the eigenfunctions

$$\frac{1}{\lambda} \sqrt{it/\pi} \sum_{n=1}^{N} \int_{-1}^{1} e^{-it(y-\frac{x}{m})^{2}} (1+a_{n}F_{n}(y)+b_{n}G_{n}(y)) dy \qquad 3.3.42$$

in the even case, and

$$\frac{1}{\lambda} \sqrt{it/\pi} \sum_{n=1}^{N} \int_{-1}^{1} e^{-it(y-\frac{x}{m})^{2}} (a_{n}F_{n}(y)+b_{n}G_{n}(y)) dy \qquad 3.3.43$$

in the odd case are expressed, per 3.3.2-3.3.4. These expressions are valid for all x. In this way, the fields across the output mirror plane can be evaluated. It follows that intensities are then given by

$$I = E * E = g * g$$
 3.3.44

where E is given by the eigenfunctions.

# IV. Modifying the Expressions to Account for Gain

Chapter IV addresses the problem of generalizing the previous development so that the expressions can account for the presence of gain in the resonator. It is noted here that the method set forth here is not the only way to include gain in mode analysis (Ref 8).

In this thesis, the method taken to include gain in the preceding development will require two changes in that development. The first is that the fundamental cylindrical wave is no longer assumed to be of unit amplitude. In the even case, to which consideration will be limited, g(x) is then assumed to be of the form

$$g(x) = h + \sum_{n=1}^{N} c_n H_n(x)$$
 4.1.1

where h is the amplitude of the basis wave, in general not equal to 1, which will be determined later. The second modification made is to include a gain factor,  $e^{2\overline{g}(y)L}$ , in the kernel of the diffraction integral. The integral equation then becomes

$$\lambda g(x) = \sqrt{it/\pi} \int_{-1}^{1} e^{2\overline{g}(y)L} e^{-it(y-\frac{x}{m})^{2}} g(y) dy$$
4.1.2

$$\lambda(h + \sum_{n=1}^{N} c_n H_n(x)) = \sqrt{it/\pi} \int_{-1}^{1} e^{2\overline{g}(y)L} e^{-it(y - \frac{x}{m})^2} (h + \sum_{n=1}^{N} c_n H_n(y)) dy$$
4.1.3

The best value of h can be found from a relaxation process wherein gains are assumed to be equal to losses. First however, the equations require a round value as a starting point.

To determine that rough value, it is assumed that there is a uniform intensity across the laser cavity, in particular, at the output plane. Thus, the gain there is affected in a similarly uniform manner. If the gain medium is homogeneous, then

$$\overline{g}(x) = \frac{g_0}{1 + 2\frac{I(x)}{I_{sat}}} = \overline{g}$$
 4.1.4

where  $g_0$  is the small signal gain, and  $I_{sat}$  is the saturation intensity, both determinable from actual laser parameters. I(x) is multiplied by 2 since there are intensity contributions from two waves, one propagating in each direction.

If the uniform intensity across the feedback mirror is  $\mathbf{I}_{\mathbf{f}}$  , then the feedback power is given by

$$P_{f} = I_{f} \cdot 2ad \qquad 4.1.5$$

where 2ad is the mirror area.

After one round trip, the power would be

$$P_r = P_f e^{2\overline{g}L}$$
 4.1.6

and the round trip intensity would then be

$$I_r = \frac{P_r}{2\text{mad}}$$
 4.1.7

since the area of the beam is now increased by the magnification (neglecting diffraction). In a steady state situation, I  $_{\rm r}$  must equal I  $_{\rm f}$  , and therefore it follows that

$$I_{f} = I_{r} = \frac{P_{r}}{2\text{mad}} = \frac{P_{f}e^{2g}L}{2\text{mad}} = \frac{I_{f}2\text{ad}e^{2g}L}{2\text{mad}}$$
 4.1.8

and thus

$$m = e^{2\overline{g}L}$$
 4.1.9

$$2\overline{g}L = 1n m$$
 4.1.10

Substituting 4.1.4 for  $\overline{g}$  , it is then seen that

$$\ln m = 2L \frac{g_0}{1+2\frac{I(x)}{I_{sat}}}$$

$$1+2\frac{I(x)}{I_{sat}} = \frac{2g_{sL}}{In\ m}$$
 4.1.12

$$\frac{I(x)}{I_{sat}} = \left(\frac{2g_0L}{1nm} - 1\right) \frac{1}{2}$$
 4.1.13

$$= \frac{g_0 L}{\ln m} - \frac{1}{2}$$
 4.1.14

This ratio is the ratio of the intensity on the mirror to the saturation intensity, and it will be considered as the relative intensity of the fundamental cylindrical wave.

Therefore,

$$h = \sqrt{\frac{g_0 L}{1 n m} - \frac{1}{2}}$$
 4.1.15

in a first approximation. This will give a rough starting
point for h from which the equations can begin.

Considering the new integral equation, 4.1.3, in light of the first stationary phase approximation, it is seen that a term has been added to the various q(y)'s . From the approximation it is then concluded from the results of Appendix A, that

$$\lambda(h+c_nH_n(x)) \simeq he^{2\overline{g}(y_0)L} + he^{2\overline{g}(1)L}H_1(x) + \sum_{n=1}^N e^{2\overline{g}(y_0^a)}a_nF_{n+1}(x)$$

$$+\sum_{n=1}^{N} e^{2\overline{g}(y_{0}^{b})} b_{n} G_{n+1}(x) + F_{1}(x) \sum_{n=1}^{N} c_{n} H_{n}(1) e^{2\overline{g}(1)L} + G_{1}(x) \sum_{n=1}^{N} c_{n} H_{n}(-1)$$

Since the intensity profile is even, in this case it is assumed that the gain function  $\overline{g}$  is even too, and the approximation then simplifies to

$$\lambda(h+\Sigma c_{n}H_{n}(x)) = he^{2\overline{g}/(y_{0})L} + he^{2\overline{g}(1)L}H_{1}(x)$$

$$+ \sum_{n=1}^{N} e^{2\overline{g}(y_{0}^{a})} a_{n}F_{n+1}(x) + \sum_{n=1}^{N} e^{2\overline{g}(y_{0}^{b})} a_{n}G_{n+1}(x)$$

$$+ H_{1}(x)e^{2\overline{g}(1)L} \sum_{n=1}^{N} c_{n}H_{n}(1) \qquad 4.1.17$$

Equating coefficients of  $H_n(x)$ ,  $n \neq 1$  shows that

$$\lambda c_{n+1} = a_n e^{2\overline{g}(y_0^a) L_{F_n}(x) + b_n} e^{2\overline{g}(y_0^b) L_{G_n}(x)}$$
 4.1.18

However,  $y_0^a$  and  $y_0^b$  themselves are now functions of x, and therefore, the sequential arguments leading up to an eigenvalue polynomial can no longer be made.

In order to build that polynomial, one more simplifying assumption is made, that being whatever intensity fluctuations present across the output plane exist, their effect on the gain is negligible. The gain factor is then assumed to be a constant, for all points across the resonator.

Defining the gain factor

$$\xi = e^{2\overline{g}L} \qquad 4.1.19$$

where  $\overline{g}$  is given by 4.1.4, then, the equation becomes

$$\lambda(h+\sum_{n=1}^{N}c_{n}H_{n}(x)) = h\xi+h\xi H_{1}(x)+\sum_{n=1}^{N}\xi c_{n}H_{n+1}(x)$$

$$+H_1(x)\sum_{n=1}^{N}\xi c_n H_n(1)$$
 4.1.20

Equating coefficients of  $H_n(x)$  now gives

$$c_{n+1} = \frac{\xi}{\lambda} c_n$$
 4.1.21

$$c_2 = \frac{\xi}{\lambda} c_1$$
 4.1.22

$$c_{n+1} = c_1 (\frac{\xi}{\lambda})^n$$
 4.1.22

and in turn it is seen that

$$c_n(\frac{\lambda}{\xi})^n = c_1 \frac{\lambda}{\xi} = c_N(\frac{\lambda}{\xi})^N$$
 4.1.23

Equating coefficients of H(x) yields as before

$$\lambda c_1 = h\xi + \sum_{n=1}^{N} \xi c_n H_n(1)$$
 4.1.24

Equating constant terms shows that

$$\lambda h = h\xi + \xi c_N H_{N+1}$$
 4.1.25

$$\frac{\lambda h - h\xi}{\xi H_{N+1}} = c_n \qquad 4.1.26$$

$$\frac{h(\lambda-\xi)}{\xi H_{N+1}} = c_n \qquad 4.1.27$$

Therefore, from 4.1.27 and 4.1.23,

$$c_n = \left(\frac{\lambda}{\xi}\right)^{N-n} \frac{(\lambda - \xi)h}{H_{N+1}}$$
 4.1.28

Substituting this into 4.1.24 yields

$$\lambda \left(\frac{\lambda}{\xi}\right)^{N-1} \frac{h(\lambda-\xi)}{\xi H_{N+1}} = h\xi + \sum_{n=1}^{N} \xi \left(\frac{\lambda}{\xi}\right)^{N-n} \frac{h(\lambda-\xi)}{\xi H_{N+1}} H_n(1) \qquad 4.1.29$$

which simplifies to

$$\left(\frac{\lambda}{\xi}\right)^{N}(\lambda-\xi) = \xi H_{N+1} + (\lambda-\xi) \sum_{n=1}^{N} \left(\frac{\lambda}{\xi}\right)^{N-n} H_{n}(1) \qquad 4.1.30$$

and the polynomial is then given by

$$\lambda^{N}(\lambda - \xi) = \xi^{N+1} H_{N+1} + (\lambda - \xi) \sum_{n=1}^{N} \lambda^{N-n} \xi^{N} \xi^{n-N} H_{n}(1)$$
 4.1.31

$$= \xi^{N+1} H_{N+1} + (\lambda - \xi) \sum_{n=1}^{N} \lambda^{N-n} \xi^n H_n(1)$$
 4.1.32

The roots of this polynomial can be found using the same method as before, which will then be rough approximations

to mode eigenvalues. If the model is to be correct for a steady state resonator, gain should just balance loss in that resonator, implying that

$$u'(x) = u(x)$$
 4.1.33

and therefore

$$\gamma = 1$$
 4.1.34

If  $\gamma=1$ , then from 2.1.32

$$\lambda = \sqrt{m} \qquad 4.1.35$$

Using this condition, 4.1.35, then h can be modified until the lowest loss mode has an eigenvalue equal to  $\sqrt{m}$ . The value of h that allows this should then be the most reasonable value of h .

When h is found, the proper gain factor is in turn found by substituting  $h^2$  for the intensity ratio in 4.1.4.

To extend these solutions beyond the shadow boundaries, one merely has to multiply the constants  ${\bf a}_n$  and  ${\bf b}_n$  in the expressions derived in the last section of the previous chapter by  $\xi$  , and change the constant factor to  ${\bf h}$  .

#### V. Results

## Implementation of Code and Result Check

The expressions developed in chapters three and four were incorporated into a CDC Fortran IV program, BARC, which was organized into two basic sections. The first section included development of the coefficients of the eigenvalue polynomials 3.2.15 and 3.2.26, the computation of the roots through IMSL routine ZCPOLY, the computation of the weighting constants  $\, c_n \,$  according to 3.2.16 and 3.1.23, and the preliminary eigenvalue expressions based on 3.1.2. The second part, in a separate subroutine, implemented the expressions developed in the third section of chapter three: the eigenvalue expressions valid for all  $\, x \,$ . The program was then run for various cavity parameters and the results were compared with the results of other programs (Ref 6:1536; Ref 8:239).

Table 1 represents a comparison of eigenvalue moduli resulting from the program developed in this work, and those from the Moore and McCarthy program.

These results are for a cavity with magnification of 2.9 and an effective Fresnel number of 16.4 . The solution compared is that of the even parity case.

It is seen that the two codes predict modes with very

TABLE 1 m&m<sup>C</sup> Mode Mod BARC Mod 1 1.040105 1.040105 2 ..625501 .625501 3 .606668 .606668 .496561 .496561 .467285 .467285 6 .157664 .139999

similar losses, since

loss = 1 - 
$$\frac{\lambda * \lambda}{m^2}$$
 5.1.1

and the  $\lambda * \lambda$  values are all very close.

Figures 3 through 8 are included to show results of eigenfunction intensity plots over similar ranges for the Moore and McCarthy program and program BARC. Figures 10 through 15 show comparison between BARC's results and those published in reference 6 (Ref 6:1536-1539). In both cases, through visual comparison, program BARC produces results that are very similar to results from previous methods. This indicates that BARC produces valid results, at least to the extent that the previous methods are valid.

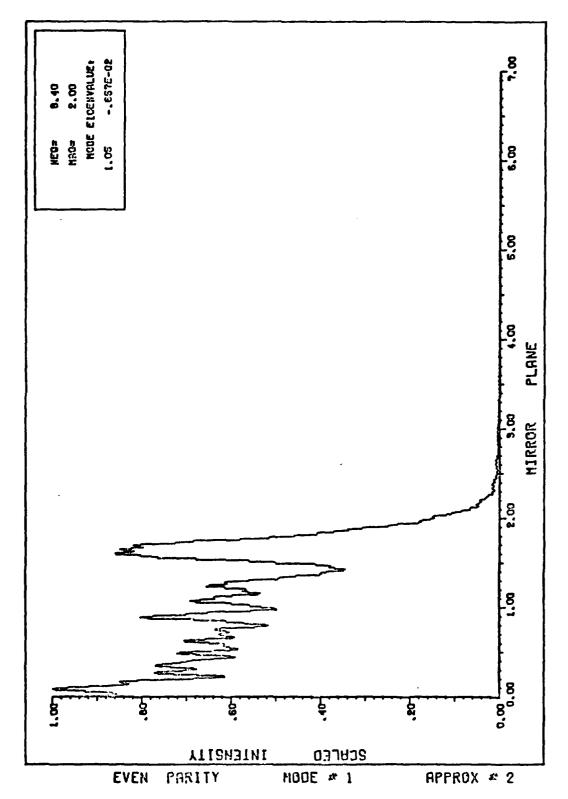


Figure 3

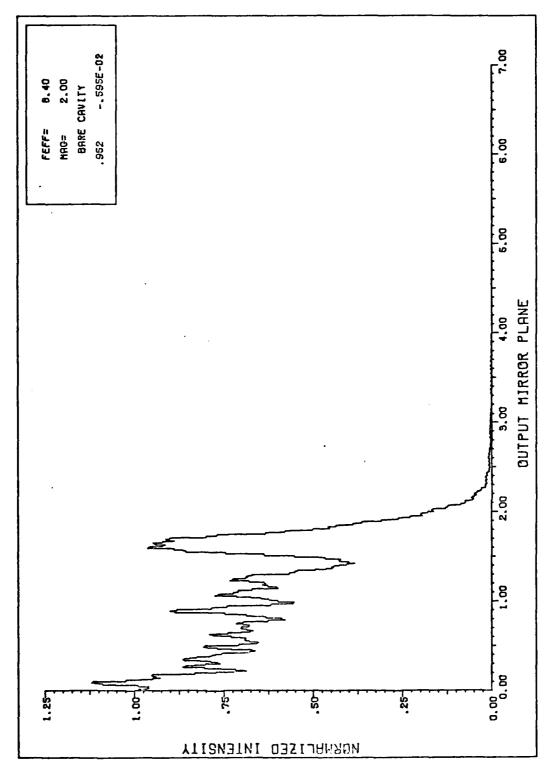


Figure 4

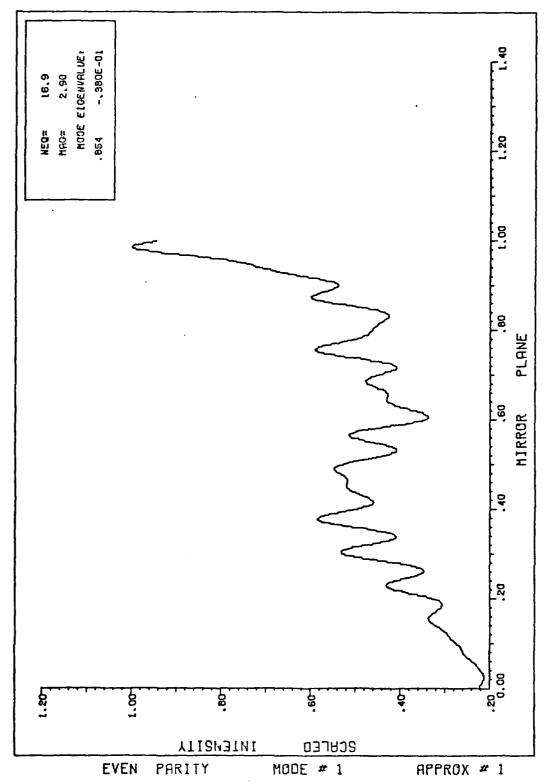


Figure 5

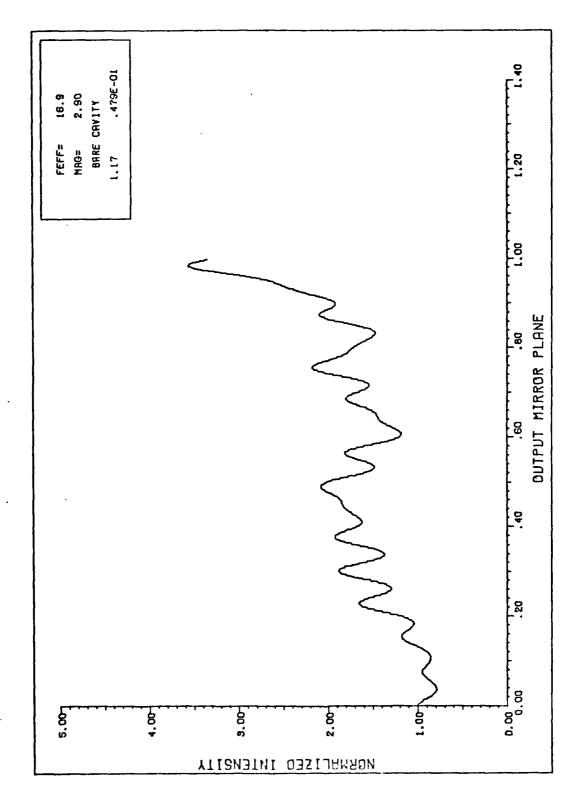


Figure 6

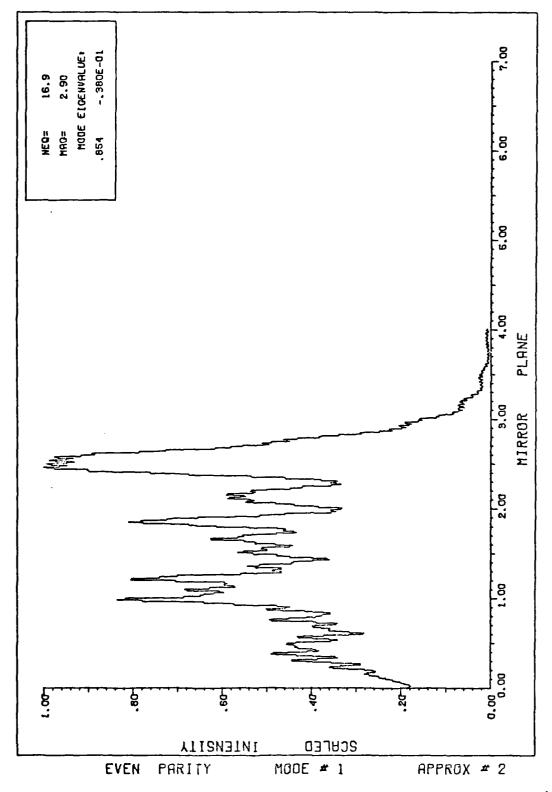


Figure 7

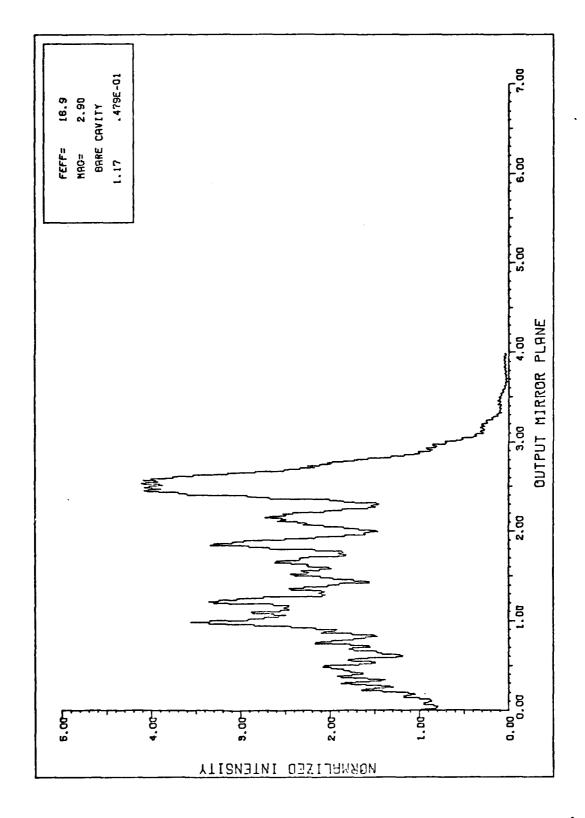


Figure 8

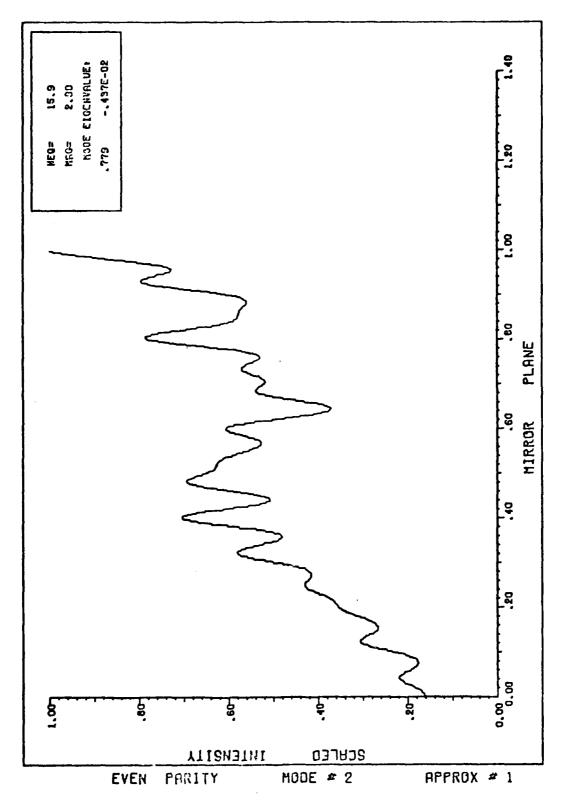


Figure 9 57

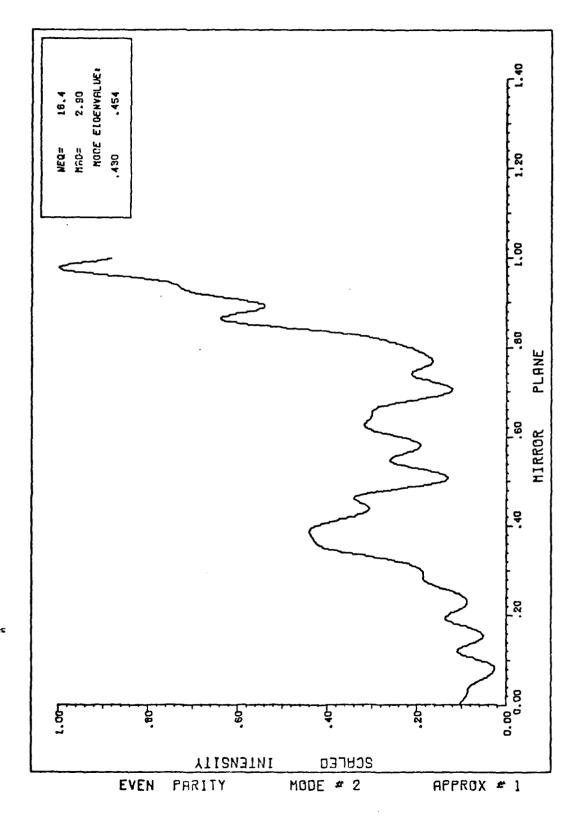


Figure 10

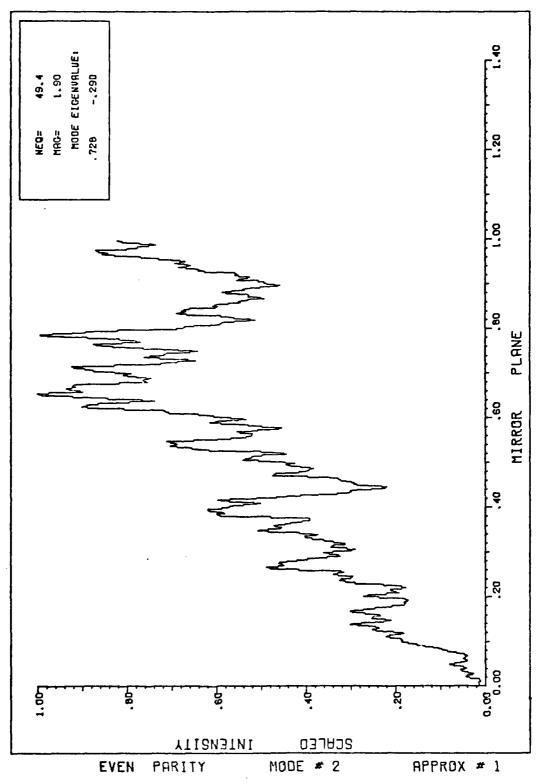


Figure 11 59

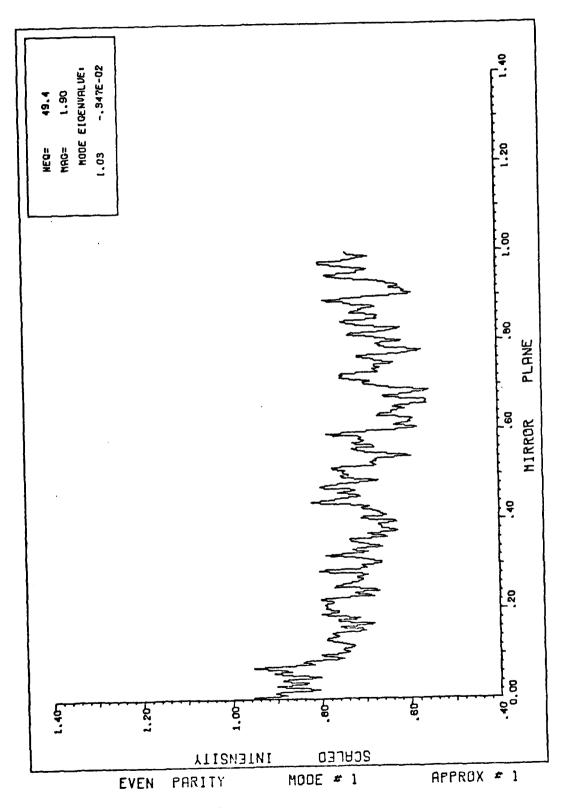


Figure 12 60

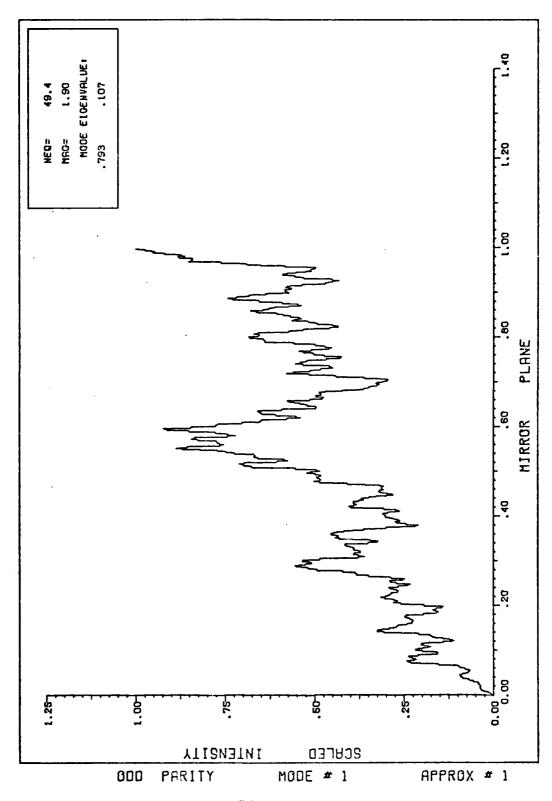


Figure 13

### Bare Cavity and Gain Results

After the validity of the code was ascertained, the code was modified according to the expressions generated in chapter four. Figures 14 through 21 illustrate results obtained for a bare resonator of magnification 2.9 and equivalent fresnel numbers of 15.863 and 16.4. These parameters are chosen to facilitate mode separation comparisons later in this section. Figures 22 through 29 illustrate results of a loaded cavity of the same configurational parameters but containing a gain medium of small signal gain 5%cm<sup>-1</sup> and cavity length of 200cm. This group of plots allows comparison between bare and loaded cavity cases. It is seen that this particular resonator model predicts that loaded cavity modes have nearly the same intensity profiles as bare cavity modes, differing only by a scale factor.

At first glance this seems reasonable, since in the bare cavity case, the whole eigenfunction was based on a wave of unit relative amplitude, and slight modifications on that wave by diffraction supplied by the oscillatory functions  $H_n(x)$ . In the loaded cavity, the eigenfunction is also based on a wave modified by the same functions, only the relative amplitude of that wave is no longer unity. Thus it seems likely that the profile would look moderately similar in both cases.

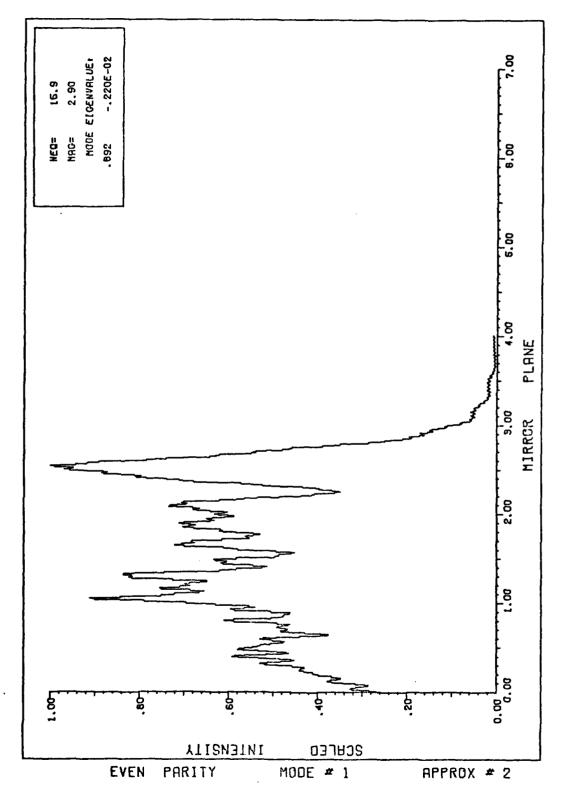


Figure 14

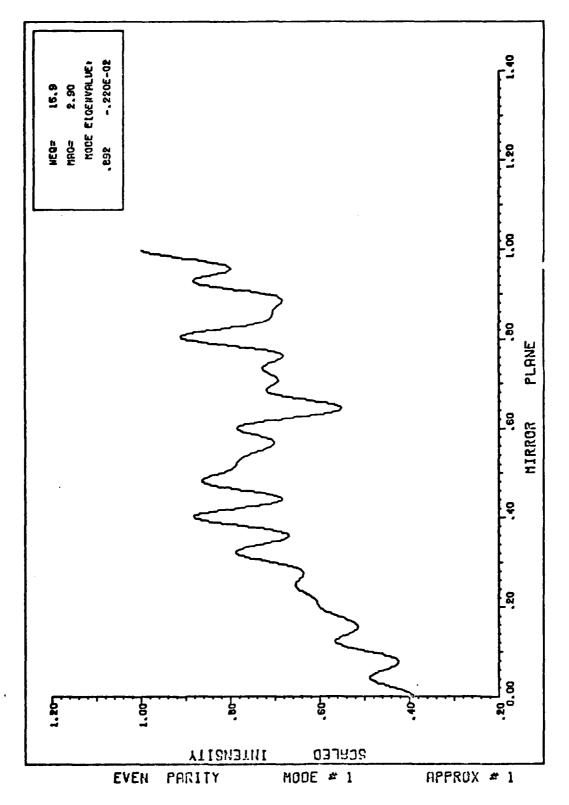


Figure 15

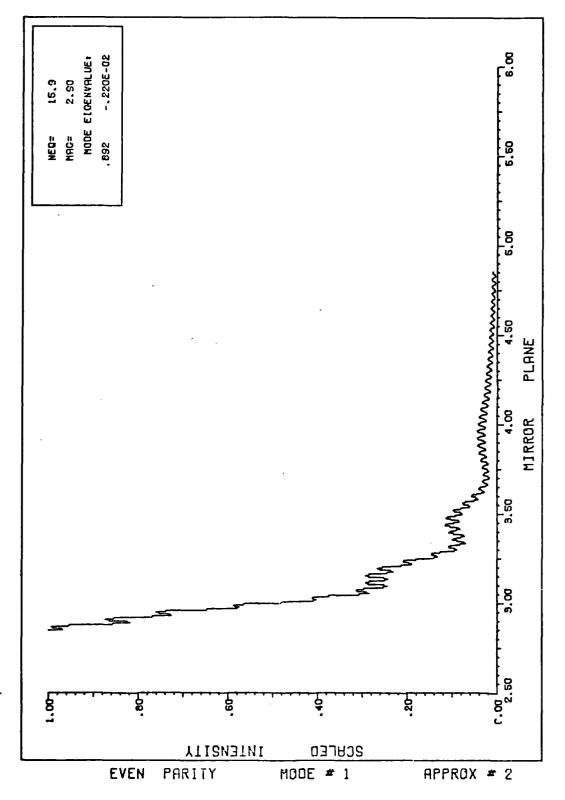
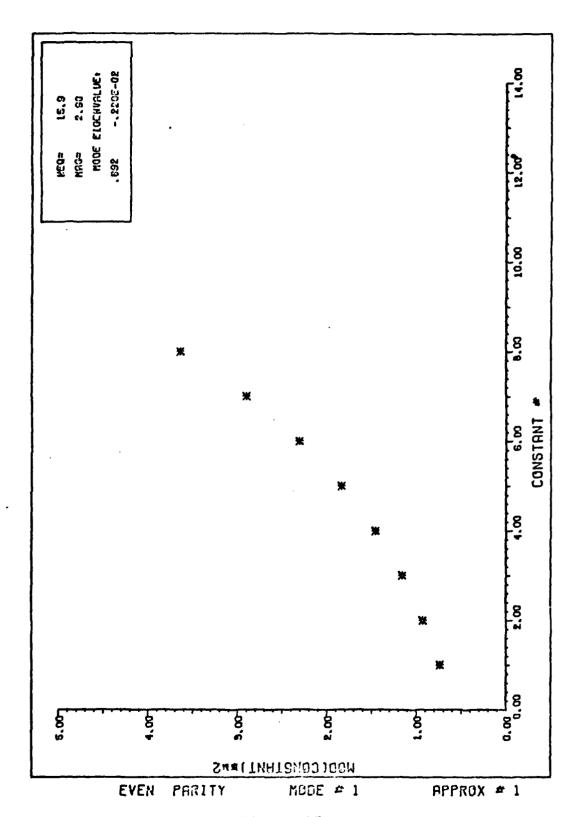


Figure 16



.Figure 17

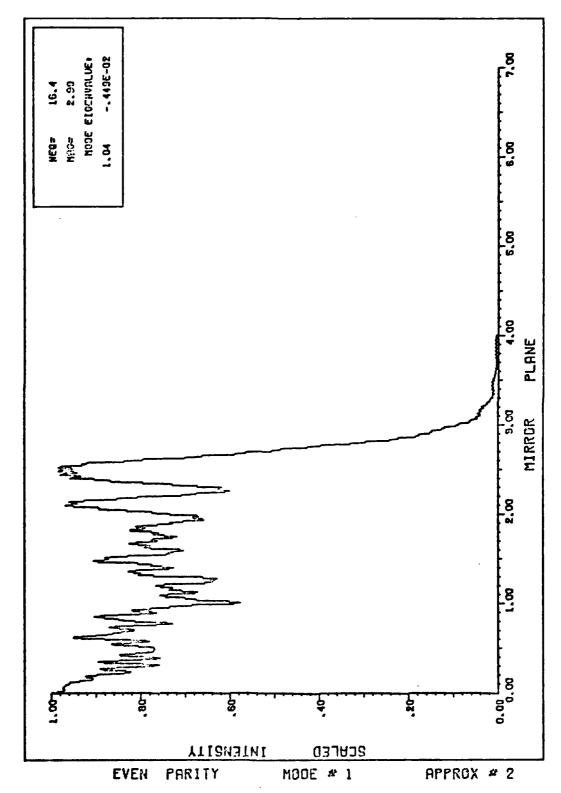


Figure 18

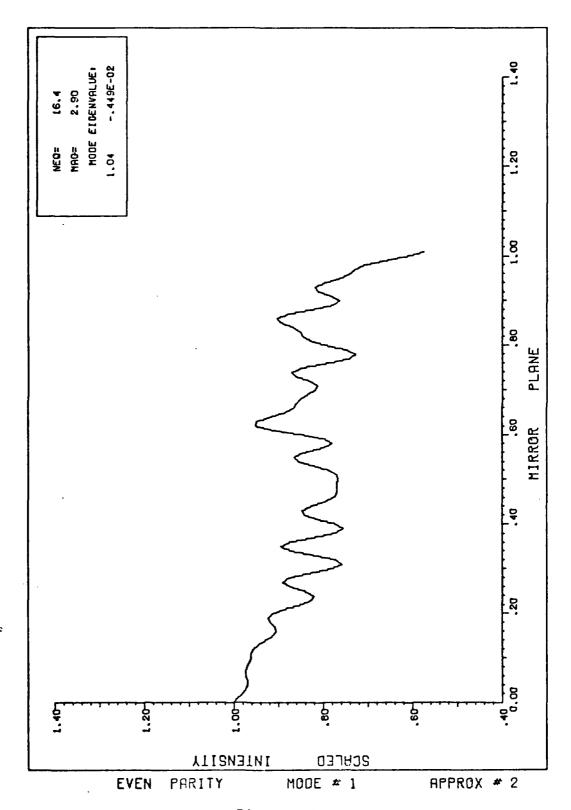


Figure 19

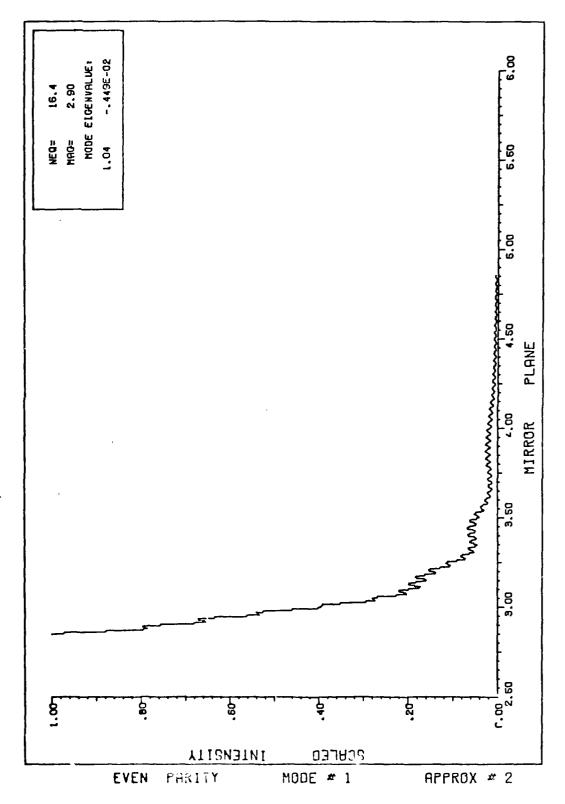


Figure 20 69

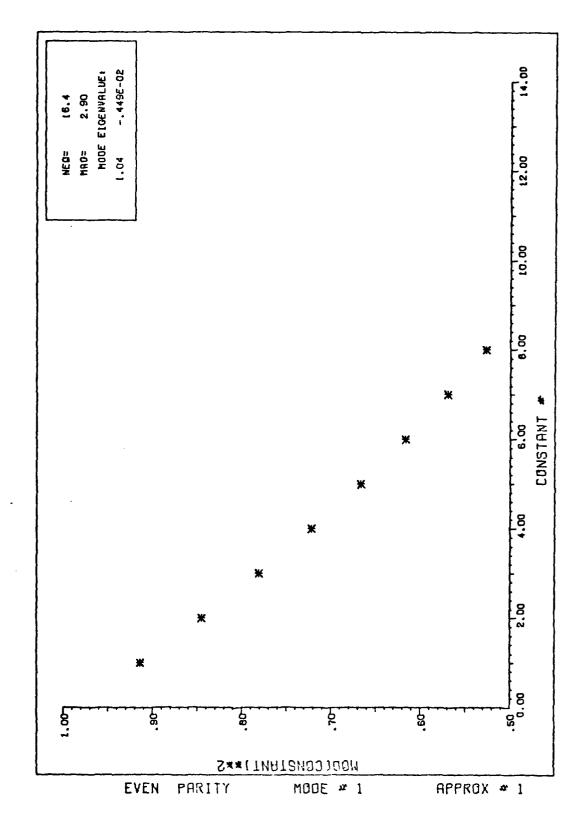


Figure 21

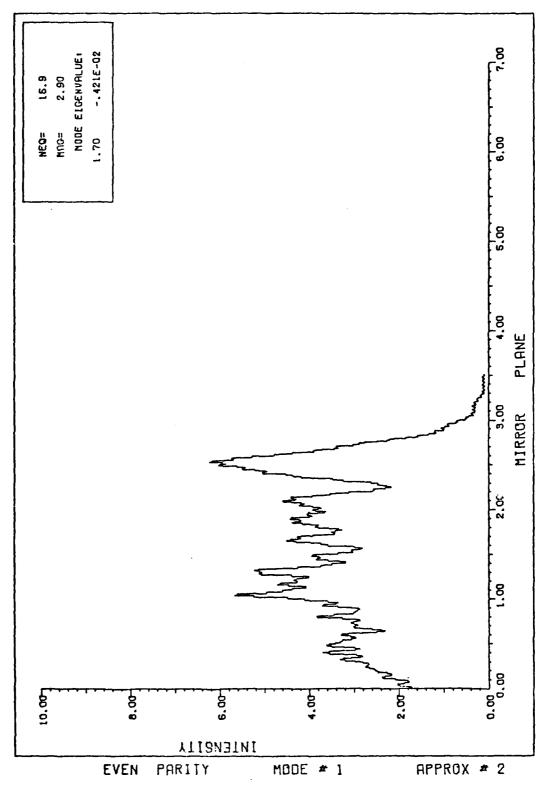


Figure 22

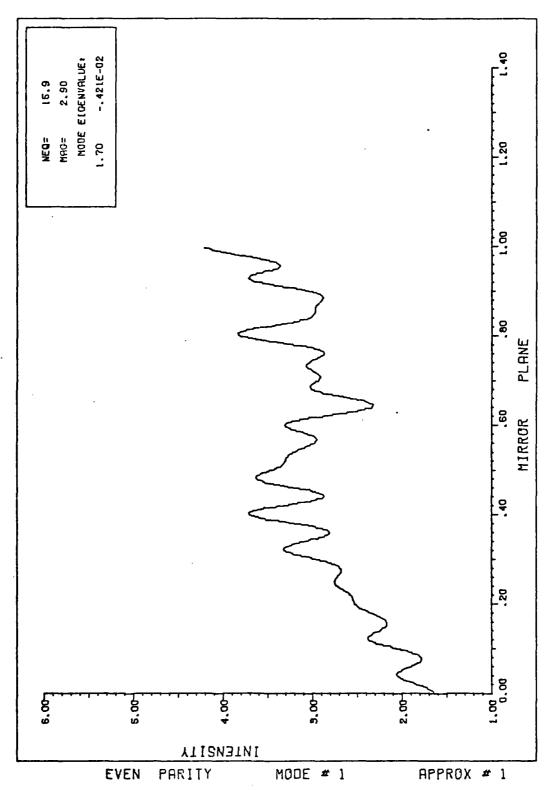
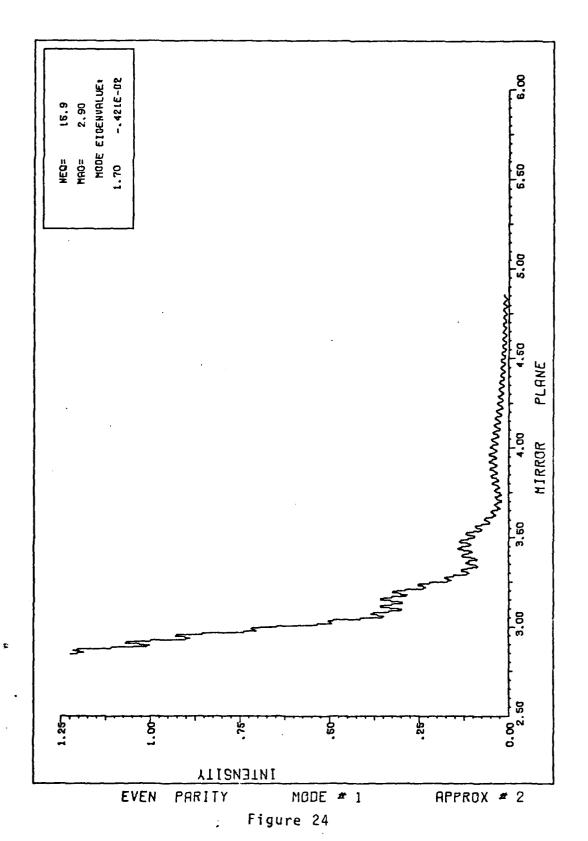


Figure 23



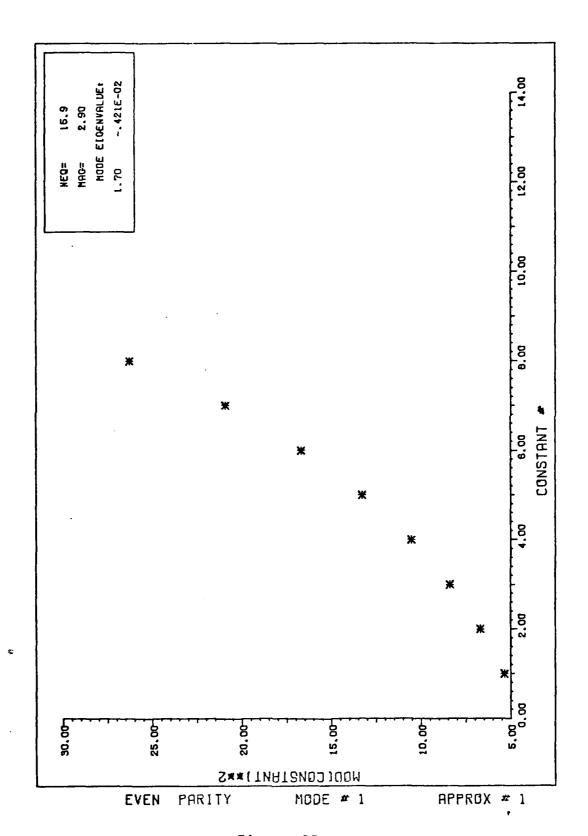


Figure 25

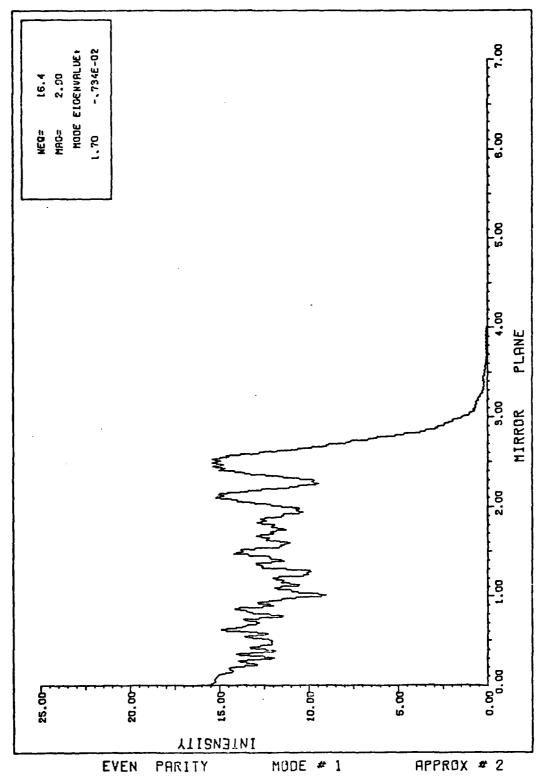


Figure 26

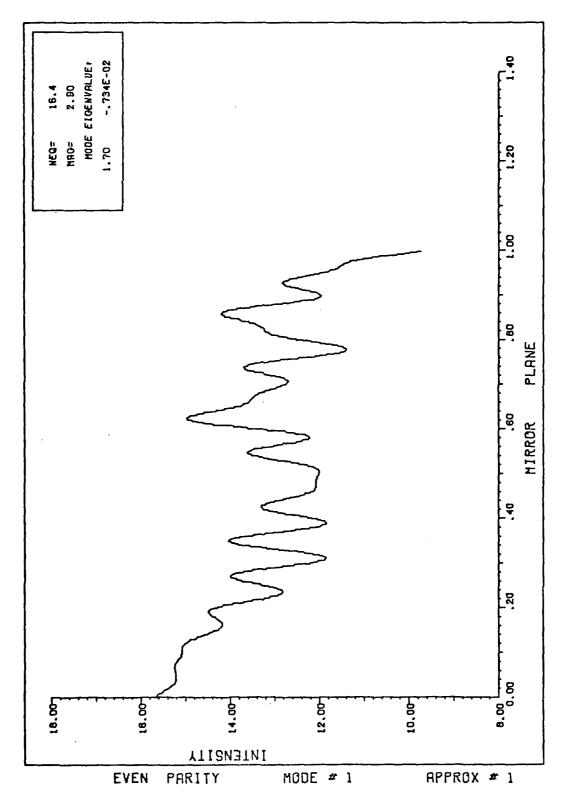


Figure 27

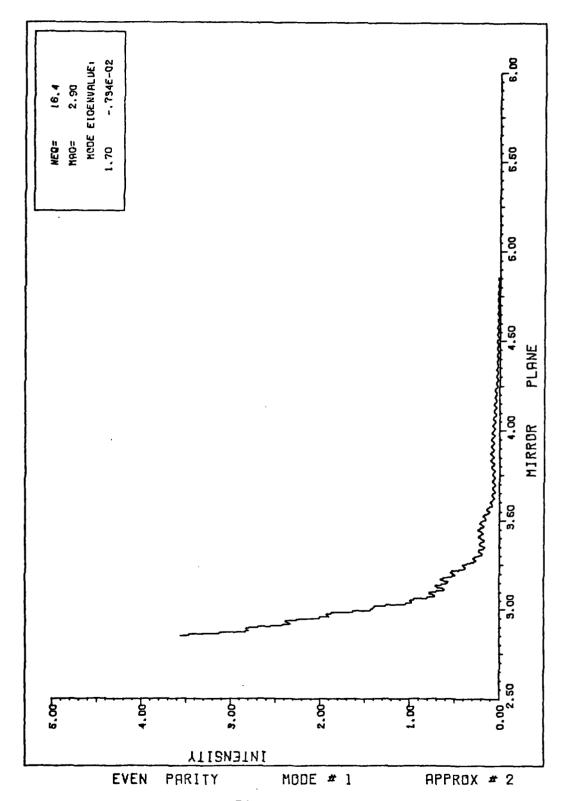


Figure 28

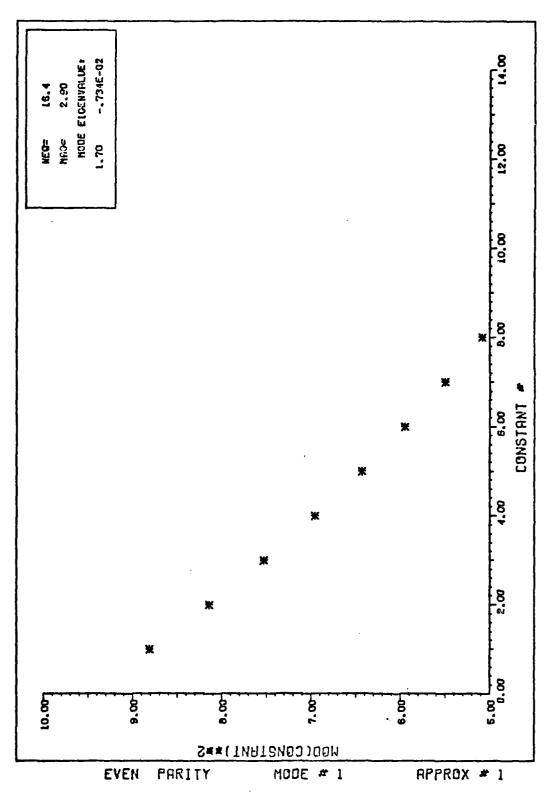


Figure 29

In closer analysis, the mode for the bare resonator
has eigenfunctions given by this expression

$$g^{b}(x) = 1 + \sum_{n=1}^{N} c_{n}^{b} H_{n}(x)$$
 5.2.1

while the loaded case has eigenfunctions given by

$$g^{L}(x) = h + \sum_{n=1}^{N} C_{n}^{L} H_{n}(x)$$
 5.2.2

Similarly, the expressions for the weighting constants are

$$C_n^b = \frac{(\lambda - 1)}{H_{N+1}} \lambda^{N-n}$$
 5.2.3

$$C_n^{L} = \frac{(\lambda - \xi)}{H_{N+1}} h(\frac{\lambda}{\xi})^{N-n} \frac{1}{\xi}$$
 5.2.4

the eigenvalue polynomial in the loaded case is (4.1.32)

$$\lambda^{N}(\lambda-\xi) = \xi^{N+1}H_{N+1} + (\lambda-\xi)\sum_{n=1}^{N} \lambda^{N-n} \xi^{n}H_{n}(1)$$
 5.2.5

Dividing through by  $\xi^{N+1}$  yields

$$(\frac{\lambda}{\xi})^{N}(\frac{\lambda}{\xi}-1) = H_{N+1} + (\frac{\lambda}{\xi}-1)\sum_{n=1}^{N} \lambda^{N-n} H_{n}(1)$$
 5.2.6

which becomes identical to the bare cavity polynomial (3.2.15)

as  $\xi \to 1$  . This condition will be fulfilled when h , the intensity ratio, becomes very large as seen from 4.1.19 and 4.1.4 . In turn H is then seen that, as  $\xi \to 1$ 

$$C_n^L \rightarrow C_n^b$$
 5.2.7

and

$$g^{L}(x) \rightarrow hg^{b}(x)$$
 5.2.8

From this it is concluded that in the well saturated case, or when the ratio of the actual intensity to the saturation intensity is much more than one, the field distributions and hence the intensity profiles will equal those of the bare cavity case multiplied by h and  $h^2$  respectively.

Tables 2 and 3 are presented to illustrate and compare mode separation properties of a loaded and a bare cavity for three different equivalent Fresnel numbers. The parameters chosen were a a magnification of 2.9 and  $\rm N_{\rm f}$ 's of 16.874, 16.4 and 15.863. These were shown in reference 6 (Ref 6:1534) to be points of least, greatest and then least loss and next to lowest loss eigenvalue moduli. It was thought that since the lowest loss mode eigenvalue was forced to the same constant value at each Fresnel number, negating any quasiperiodicity, the higher loss modes might also lose quasi periodicity. The numbers presented show that the higher loss modes do maintain their quasi periodicity.

		TABLE 2	
RE RESONATOR		Mod (λ)	
Mode	N <sub>f</sub> =15.863	N <sub>f</sub> =16.400	N <sub>f</sub> =16.874
1	0.8543652	1.040102	0.8922496
2	0.8508141	0.6255715	0.7785354
- 3	0.5385818	0.6067205	0.5400256
4	0.5049350	0.4966156	0.5290538
5	0.4737932	0.4673182	0.4752758
6	0.1718837	0.1646309	0.1593562

TABLE 3					
LOADED RESONATOR		Mod (λ)			
Mode	N <sub>f</sub> =15.863	N <sub>f</sub> =16.4	N <sub>f</sub> ≈16.874		
1.	1.702922	1.702965	1.70294		
2	1.695844	1.024215	1.485906		
3	1.073502	0.9933517	1.030688		
4	1.006437	0.8130828	1.009747		
5	0.8718129	0.7651157	0.9071073		
6	0.3425989	0.2695415	0.3041459		

The h's required to adjust  $\lambda$  to  $\sqrt{m}$  were 2.6899 3.1051, and 2.5979 for N<sub>f</sub> =15.863, 16.4, and 16.874 respectively.

### VI. Conclusion and Recommendations

## Conclusion

The primary conclusion of this thesis is that program BARC, written according to expressions developed along Horwit'z analysis, produces valid results. The program allows analysis of even and odd parity mode solutions, more general than Moore and McCarthy's program, and also allows field calculation beyond the shadow boundary.

Incorporation of gain considerations into the program to allow analysis of a loaded strip resonator has been done. After modification the program produces results from which a second conclusion can be drawn, that being, for this particular model, mode intensity profiles in a loaded strip resonator are essentially the same as those predicted for a bare strip resonator. It is also concluded that mode losses as function of equivalent fresnel number continue to exhibit quasi periodicity in the loaded case.

#### Recommendations

The computer program, as it stands, predicts some very basic results about modes in an unstable resonator. There is no doubt that the scope of the program and the model upon which it is based can be broadened considerably. As it stands, it could be used to examine a full, or more complete

range of resonator parameters either loaded or bare.

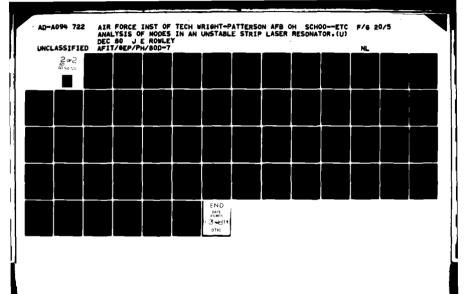
The program should be used to explore mode separation in the loaded cavity case. Mode separation could be examined for a range of Fresnel numbers as has been done for bare cavities. (Ref 6)

The model given here could be modified to account for a non uniform gain function. To do this a new series of  $H_n$ 's might be developed through asymptotic analysis of the gain-modified kernel. Another method might be the use of matrix methods to solve the eigenvalue equation.

This existing method could be applied to resonators with circular mirrors per Ref 2, and gain then included in that case.

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# Appendix A

This appendix will employ the stationary phase approximation to simplify the resonator integral equation into a workable expression. The derivation starts with the functions.

$$F(x,t) = \frac{-1}{2\sqrt{i\pi t}} \frac{e^{-it(1-x)^2}}{1-x}$$
 A1

and

$$G(x,t) = \frac{-1}{2\sqrt{1\pi t}} \frac{e^{-it(1+x)^2}}{1+x}$$
 A2

These are modified by letting

$$F_n(x) = F(\frac{x}{mn}, \frac{t}{m_{n-1}})$$
 A3

and

£

$$G_n(x) = G\left(\frac{x}{m^n}, \frac{t}{m_{n-1}}\right)$$

where

$$m_n = \sum_{K=0}^{n} m^{-2K}$$
 A5

and

m = magnification

$$i = \sqrt{-1}$$

Thus it is seen that

$$F_1(x) = \frac{-1}{2\sqrt{i\pi t}} \frac{e^{-it(1-x/m)^2}}{1-x/m}$$
 A6

$$F_2(x) = \frac{-\sqrt{1+1/m^2}}{2 i t} \frac{e^{-it(1-x/m^2)^2/1+1/m^2}}{1-x/m^2}$$

and in general that

$$F_{n}(x) = \frac{\sqrt{m_{n-1}}}{2\sqrt{1\pi t}} \frac{e^{-it(1-x/m^{n})^{2}/m}n-1}{1-x/m^{n}}$$
 A8

and similarly

$$G_n(x) = \frac{\sqrt{m_{n-1}}}{2\sqrt{1\pi t}} \frac{e^{-it(1+x/m^n)^2/m_{n-1}}}{1+x/m^n}$$
 A9

Now, it is recalled that the working form of the integral equation is

$$\lambda f(x) = \sqrt{\frac{\pi t}{\pi}} \int_{-1}^{1} e^{-it(y-x/m)^2} f(y) dy$$
 A10

In the even part

$$f(x) = 1 + \sum_{n=1}^{N} (a_n F_n(x) + b_n G_n(x))$$
 All

All is substituted into the integral equation, which now becomes

$$\lambda (1+\Sigma \{a_n F_n(x)+b_n G_n(x)\}) =$$

$$\frac{it}{\pi} \int_{-1}^{1} e^{it(y-x/m)^2} (1+\sum\{a_n F_n(y)+b_n G_n(y)\}) dy \qquad A12$$

When expanded once, the right side becomes

$$= \sqrt{\frac{it}{\pi}} \int_{-1}^{1} e^{-it(y-x/m)^{2}} dy + \sqrt{\frac{it}{\pi}} \sum_{n=1}^{N} \int_{-1}^{1} e^{-it(y-x/m)^{2}}$$

$$(a_n F_n(y) + b_n G_n(y))$$
 dy A13

The first term is called  $\ensuremath{\text{I}}_{\text{o}}$  . Then

$$I_0 = \sqrt{\frac{it}{\pi}} \int_{-1}^{1} e^{-it(y-x/m)^2} dy$$
 A14

This is now considered in light of the first order approximation to the method of stationary phase which states that if

$$I = \int_{a}^{b} q(y)e^{-itp(y)}dy$$
 A15

then

$$I \simeq e^{-i\pi/4} q(y_0) e^{itp(y_0)} \sqrt{\frac{2\pi}{tp^2(y_0)}}$$

$$+ \frac{i}{t} \left[ \frac{q(b)}{p^2(b)} e^{-itp(b)} - \frac{q(a)}{p^2(a)} e^{-itp(a)} \right]$$
A16

Where  $y_0$  is such that

$$p'(y_0) = 0$$
 A17

It is seen that

$$q(y) = 1$$
 $p(y) = (y-x/m)^2$ 

A18

 $p'(y) = 2(y-x/m)$ 

A19

 $p''(y) = 2$ 

A20

And that

$$y_0 = x/m$$
 A21

Therefore, after substitution,

$$I_{0} \simeq \sqrt{\frac{it}{\pi}} \left\{ e^{-i\pi/4} \sqrt{\pi/t} + \frac{i}{t} \left[ \frac{e^{-it(1-x/m)^{2}}}{2(1-x/m)} - \frac{e^{-it(-1-x/m)^{2}}}{2(-1-x/m)} \right] \right\} A22$$

$$\simeq \sqrt{i} e^{-i\pi/4} + \frac{i}{2t} \sqrt{it/\pi} \left[ \frac{e^{-it(1-x/m)^{2}}}{1-x/m} + \frac{e^{-it(1+x/m)^{2}}}{1+x/m} \right] A23$$

However, since

$$e^{-i\pi/4}\sqrt{i} = \frac{1}{2}(1+i)(1-i)$$
 A24

Then

$$I_0 \simeq 1 + \frac{i}{2t} \sqrt{it/\pi} \left[ \frac{e^{-it(1-x/m)^2}}{1-x/m} + \frac{e^{-it(1+x/m)^2}}{1+x/m} \right]$$
 A26

$$\simeq 1 + \frac{i\sqrt{1}}{2\sqrt{\pi t}} \left[ \frac{e^{-it(1-x/m)^2}}{1-x/m} + \frac{e^{-it(1+x/m)^2}}{1+x/m} \right]$$
 A27

Since  $i\sqrt{i}=(i-1)/\sqrt{2}$  , and  $-1/\sqrt{i}=(i-1)/\sqrt{2}$  , it is seen that however,  $i\sqrt{i}=\sqrt{i}=\frac{1}{q}$ 

$$I_0 \approx 1 - \frac{1}{2\sqrt{1\pi}t} \left[ \frac{e^{-it(1-x/m)^2}}{1-x/m} + \frac{e^{-it(1+x/m)^2}}{1+x/m} \right]$$
 A28

It is now easily seen that

$$I_0 \simeq 1+F_1(x)+G_1(x)$$
 A29

The first term in the sum of integrals is now called  $I_1$ :

$$I_{1} = \sqrt{it/\pi} \int_{-1}^{1} e^{-it(y-x/m)^{2}} (a_{1}F_{1}(y) + b_{1}G_{1}(y)) dy \quad A30$$

Explicitly, this becomes

$$I_{1} = \sqrt{it/\pi} \int_{-1}^{1} \left[ \frac{-a_{1}}{2\sqrt{i\pi t}} \frac{e^{-it(1-y/m)^{2}}}{1-y/m} + \frac{-b_{1}}{2\sqrt{i\pi t}} \right]$$

$$\frac{e^{-it(1+y/m)^2}}{1+y/m} e^{-it(y-x/m)^2}$$
 A31

Upon separation the result is

$$I = \sqrt{it/\pi} \int_{-1}^{1} \frac{-a_1}{2\sqrt{i\pi t}} \frac{e^{-it|(1-y/m)^2+(y-x/m)^2|}}{1-y/m} dy$$

$$+ \sqrt{it/\pi} \int_{-1}^{1} \frac{-b_1}{2\sqrt{i\pi t}} \frac{e^{-it|(1+y/m)^2 + (y-x/m)^2|}}{1+y/m}$$
 A32

Upon consideration of the first part of this, it is seen that

$$q(y) = \frac{1}{1 - y/m}$$
 A33

$$p(y) = (1-y/m)^2 + (y-x/m)^2$$
 A34

$$p'(y) = \frac{-2}{m} (1 - \frac{y}{m}) + 2(y - \frac{x}{m})$$
 A35

$$p''(y) = \frac{2}{m^2} + 2$$
 A36

Solving for yo

$$0 = \frac{-2}{m} + \frac{2y_0}{m^2} + 2y_0 - \frac{2x}{m}$$
 A37

$$y_0 \left(1 + \frac{1}{m^2}\right) = \frac{1}{m} + \frac{x}{m}$$
 A38

$$y_0 = \frac{\left(\frac{1}{m} + \frac{x}{m}\right)}{1 + \frac{1}{m^2}}$$
 A39

These expressions are now substituted into the first part of A32 to get

$$\frac{-a_{1}}{2\sqrt{i\pi t}} \sqrt{it/\pi} \left\{ \frac{-it \left[ \left( 1 - \frac{1}{m} \cdot \frac{1}{1 + \frac{1}{m^{2}}} \cdot \left( \frac{1}{m} + \frac{x}{m} \right) \right)^{2} + \left( \left( \frac{1}{m} + \frac{x}{m} \right) \cdot \frac{1}{1 + \frac{1}{m^{2}}} - \frac{x}{m} \right)^{2} \right]}{1 - \left( \frac{1}{m} \left( \frac{1}{1 + \frac{1}{m^{2}}} \right) \left( \frac{1}{m} + \frac{x}{m} \right) \right)}$$

$$+\frac{i}{t}\left[\frac{-it\left((1-\frac{y}{m})^{2}+(1-\frac{x}{m})\right)^{2}}{(1-\frac{1}{m})(\frac{-2}{m}(1-\frac{1}{m})+2(1-\frac{x}{m}))}-\frac{it\left((1+\frac{1}{m})^{2}+(-1-\frac{x}{m})^{2}\right)}{(1+\frac{1}{m})(\frac{-2}{m}(1+\frac{1}{m})+2(-1-\frac{x}{m}))}\right]\right\}A40$$

Considering the second term of A32 shows that

$$q(y) = \frac{1}{1+y/m}$$
 A41

$$p(y) = (1+\frac{y}{m})^2 + (y-\frac{x}{m})^2$$
 A42

$$p'(y) = \frac{2}{m}(1+\frac{y}{m})+2(y-\frac{x}{m})$$
 A43

$$p^{-}(y) = \frac{2}{m^2} + 2$$
 A44

and solving for  $y_0$  , the result is

$$0 = \frac{2}{m} + \frac{2y_0}{m^2} + 2y_0 - \frac{2x}{m}$$
 A45

$$y_0(\frac{1}{m^2}+1) = \frac{x}{m} - \frac{1}{m}$$
 A46

$$y_0 = (\frac{x}{m} - \frac{1}{m}) \cdot \frac{1}{1 + \frac{1}{m^2}}$$
 A47

Substitution of these expressions into the second part of A32 results in

$$\frac{-b_{1}}{2\sqrt{1\pi}t} \sqrt{it/\pi} \left\{ e^{-\frac{i\pi}{4}} e^{-it} \left[ 1 + \frac{1}{m} \left( \frac{1}{1 + \frac{1}{m^{2}}} (\frac{x}{m} - \frac{1}{m})^{2} + \left( \frac{1}{1 + \frac{1}{m^{2}}} (\frac{x}{m} - \frac{1}{m}) - \frac{x}{m} \right)^{2} \right] + \frac{i}{t} \left[ e^{-it((1 + \frac{1}{m})^{2} + (1 - \frac{x}{m})^{2})} - e^{-it((1 - \frac{1}{m})^{2} + (-1 - \frac{x}{m})^{2})} - e^{-it((1 - \frac{1}{m})^{2} + (-1 - \frac{x}{m})^{2})} \right] \right\}$$

$$A48$$

Considering the denominator in (A-40)'s stationary phase point contribution, it is seen that

$$1 - \frac{1}{m} \frac{1}{1 + \frac{1}{m^2}} \left( \frac{1}{m} + \frac{x}{m} \right) = 1 - \frac{x + 1}{(m + \frac{1}{m}) \cdot m}$$

And similarly in (A-48)'s stat phase point cont, it is seen that

$$1 + \frac{1}{m} \frac{1}{1 + \frac{1}{m^2}} (\frac{x}{m} - \frac{1}{m}) = 1 - \frac{x - 1}{(m + \frac{1}{m}) \cdot m}$$
 A50

Also, it is seen that the argument of the exponent in A-40's stationary phase contribution can be simplified as follows

$$\left(1 - \frac{1}{m} \frac{1}{1 + \frac{1}{m^2}} \left(\frac{x}{m} + \frac{1}{m}\right)\right)^2 + \left(\frac{1}{1 + \frac{1}{m^2}} \left(\frac{1}{m} + \frac{x}{m}\right) - \frac{x}{m}\right)^2 = A51$$

$$\left(1 - \frac{1}{m + \frac{1}{m}} \frac{x}{m} + \frac{1}{m}\right)^{2} + \left(\frac{x + 1}{m + \frac{1}{m}} - \frac{x}{m}\right)^{2} = A52$$

$$\left(1 - \frac{x+1}{m^2 + 1}\right)^2 + \left(\frac{x+1}{m + \frac{1}{m}} - \frac{x}{m}\right)^2 = A53$$

$$\left(\frac{m^2+1-x-1}{m^2+1}\right)^2 + \left(\frac{m(x+1)-x(m+\frac{1}{m})}{m^2+1}\right)^2 = A54$$

$$\frac{(m^2-x)^2+(m(x+1)-x(m+m))^2}{(m^2+1)^2} = A55$$

$$= \frac{\left(1 - \frac{x}{m^{2}}\right)^{2}}{\left(1 + \frac{1}{m^{2}}\right)^{2}} + \frac{\left(1 - \frac{x}{m^{2}}\right)^{2}}{\left(m + \frac{1}{m}\right)^{2}}$$
 A56

$$= \frac{\left(1 - \frac{x}{m^2}\right)^2}{\left(1 + \frac{1}{m^2}\right)^2} + \frac{\frac{1}{m^2}\left(1 - \frac{x}{m^2}\right)^2}{\left(1 + \frac{1}{m^2}\right)^2}$$
A57

$$= \frac{\left(1 - \frac{x}{m^2}\right) \left(1 + \frac{1}{m^2}\right)}{\left(1 + \frac{1}{m^2}\right)}$$
 A58

$$= \frac{\left(1 - \frac{x}{m^2}\right)^2}{1 + \frac{1}{m^2}}$$
 A59

In A48, the exp argument in the stationary phase point contribution can be simplified as follows

$$\left(1 + \frac{1}{m} \frac{1}{1 + \frac{1}{m^2}} \left(\frac{x}{m} - \frac{1}{m}\right)\right)^2 + \left(\frac{1}{1 + \frac{1}{m^2}} \left(\frac{x}{m} - \frac{1}{m}\right) - \frac{x}{m}\right)^2$$
A60

$$= \left(1 + \frac{x-1}{m^2+1}\right)^2 + \left(\frac{x-1}{m+\frac{1}{m}} - \frac{x}{m}\right)^2$$
A61

$$= \left(\frac{m^2 + 1 + x - 1}{m^2 + 1}\right)^2 + \left(\frac{mx - m - mx - \frac{x}{m}}{m^2 + 1}\right)^2$$
A62

$$= \left(\frac{m^2 + x}{m^2 + 1}\right)^2 + \left(\frac{-\frac{x}{m} - m}{m^2 + 1}\right)^2$$
A63

$$= \frac{\left(1 + \frac{x}{m^2}\right)^2}{\left(1 + \frac{1}{m^2}\right)} + \frac{\left(\frac{x}{m^2} + 1\right)^2}{\left(\frac{m^2 + 1}{m}\right)^2}$$
A64

$$= \frac{\left(1 + \frac{x}{m^2}\right)^2}{\left(1 + \frac{1}{m^2}\right)^2} + \frac{\frac{1}{m^2}\left(\frac{x}{m^2} + 1\right)^2}{\left(1 + \frac{1}{m^2}\right)^2}$$
A65

$$= \frac{\left(\frac{1}{m^2} + 1\right) \left(1 + \frac{x}{m^2}\right)^2}{\left(1 + \frac{1}{m^2}\right)^2} = \frac{\left(1 + \frac{x}{m^2}\right)^2}{1 + \frac{1}{m^2}}$$
A66

Substituting these simplified expressions into A-32, we find that

$$I_{1} \simeq -\sqrt{it/\pi} \frac{1}{2\sqrt{i\pi t}} \left\{ e^{-i\pi/4} \cdot \sqrt{\frac{\pi}{t(1+\frac{1}{m^{2}})}} \left( \frac{a_{1}e^{-it(1-\frac{x}{m^{2}})^{2}/1+\frac{1}{m^{2}}}}{1 - \frac{x+1}{m(m+\frac{1}{m})}} \right) + \frac{b_{1}e^{-it(1+\frac{x}{m})^{2}/1+\frac{1}{m^{2}}}}{1+\frac{x-1}{m(m+\frac{1}{m})}} \right\} - \sqrt{it/\pi} \frac{1}{2\sqrt{i\pi t}} \frac{i}{t}$$

$$\left\{ \frac{a_{1}e^{-it((1-\frac{1}{m})^{2}+(1-\frac{x}{m})^{2}})}{(1-\frac{1}{m})(\frac{-2}{m}(1-\frac{1}{m})+2(1-\frac{x}{m}))} - \frac{a_{1}e^{-it((1+\frac{1}{m})^{2}+(-1-\frac{x}{m})^{2}})}{(1+\frac{1}{m})(\frac{-2}{m}(1+\frac{1}{m})+2(-1-\frac{x}{m}))} + \frac{b_{1}e^{-it(1+\frac{1}{m})^{2}+(1-\frac{x}{m})^{2}}}{(1+\frac{1}{m})(\frac{2}{m}(1+\frac{1}{m})+2(-1-\frac{x}{m}))} \right\} A67$$

Now the first part of this expression can be simplified as follows:

$$\frac{1}{1 - \frac{x+1}{m(m+\frac{1}{m})}} = \frac{1}{1 - \frac{x+1}{m^2+1}}$$
 A68

$$= \frac{1}{\frac{m^2 + 1 - x - 1}{m^2 + 1}}$$
 A69

$$= \frac{m^2 + 1}{m^2 - x}$$
 A70

$$= \frac{1 + \frac{1}{m^2}}{1 - \frac{X}{m^2}}$$
 A71

And the second part can also be simplified

$$\frac{1}{1 + \frac{x-1}{m^2 + 1}} = \frac{1}{\frac{m^2 + 1 + x - 1}{m^2 + 1}}$$

$$= \frac{m^2 + 1}{m^2 + x}$$
 A73

$$= \frac{1 + \frac{1}{m^2}}{1 + \frac{X}{m^2}}$$
 A74

If these simplified expressions are substituted into A67, the result is

$$I_{1} \simeq -\sqrt{it/\pi} \frac{1}{2\sqrt{i\pi t}} e^{-i\pi/4} \sqrt{\frac{\pi}{t(1+\frac{1}{m^{2}})}} \left( \frac{a_{1}e^{-it(1-\frac{X}{m^{2}})^{2}/1+\frac{1}{m^{2}}}}{1-\frac{X}{m^{2}}} + \frac{b_{1}e^{-it(1+\frac{X}{m^{2}})^{2}/1+\frac{1}{m^{2}})}}{1+\frac{X}{m^{2}}} - \sqrt{it/\pi} \frac{1}{2\sqrt{i\pi t}} \frac{1}{2t}$$

$$\left\{
\frac{a_{1}e}{(1-\frac{1}{m})(-\frac{1}{m}+\frac{1}{m^{2}}+1-\frac{x}{m})} - \frac{a_{1}e}{(1+\frac{1}{m})(-\frac{1}{m}+\frac{1}{m^{2}}+1-\frac{x}{m})} - \frac{a_{1}e}{(1+\frac{1}{m})(-\frac{1}{m}-\frac{1}{m^{2}}-1-\frac{x}{m})} + \frac{b_{1}e}{(1+\frac{1}{m})(\frac{1}{m}+\frac{1}{m^{2}}+1-\frac{x}{m})} - \frac{b_{1}e}{(1-\frac{1}{m})(\frac{1}{m}-\frac{1}{m^{2}}-1-\frac{x}{m})}\right\} A75$$

After a few sign manipulations and cancellations, it is seen that

$$I_{1} \simeq \frac{-1}{2\sqrt{i\pi t}} \sqrt{1+1/m^{2}} \left( \frac{a_{1}e^{-it(1-\frac{x}{m^{2}})^{2}/1+\frac{1}{m^{2}}}}{1-\frac{x}{m^{2}}} + \frac{b_{1}e^{-it(1+\frac{x}{m^{2}})^{2}/1+\frac{1}{m_{2}}}}{1+\frac{x}{m^{2}}} \right)$$

$$+ \frac{1}{4i\pi t} \left\{ \frac{a_{1}e^{-it(1-\frac{1}{m})^{2}} - it(1-\frac{x}{m})^{2}}{(1-\frac{1}{m})(1-\frac{1}{m}+\frac{1}{m^{2}}-\frac{x}{m})} + \frac{a_{1}e^{-it(1+\frac{1}{m})^{2}} - it(-1-\frac{x}{m})^{2}}{(1+\frac{1}{m})(1+\frac{1}{m}+\frac{1}{m^{2}}+\frac{x}{m})} + \frac{b_{1}e^{-it(1-\frac{1}{m})^{2}} - it(-1-\frac{x}{m})^{2}}{(1-\frac{1}{m})(1-\frac{1}{m}+\frac{1}{m^{2}}+\frac{x}{m})} \right\} A76$$

The stationary phase point contributions are seen immediately to be equal to

$$a_1F_2(x)+b_1G_2(x)$$
 A77

In the end point contributions, the denominators must be approximated and terms of  $\frac{1}{m}$  or higher order be neglected. When done, the end point contributions appear as

$$+ \frac{1}{4 i \pi t} \begin{cases} \frac{a_1 e^{-i t (1 - \frac{1}{m})^2 - i t (1 - \frac{x}{m})^2}}{e^{-i t (1 - \frac{x}{m})} (1 - \frac{x}{m})} + \frac{a_1 e^{-i t (1 + \frac{1}{m})^2 - i t (1 + \frac{x}{m})^2}}{(1 + \frac{1}{m}) (1 + \frac{x}{m})} \end{cases}$$

$$+ \frac{b_1 e^{-it(1+\frac{1}{m})^2 - it(1-\frac{x}{m})^2}}{(1+\frac{1}{m})(1-\frac{x}{m})} + \frac{b_1 e^{-it(1-\frac{1}{m})^2 - it(1+\frac{x}{m})^2}}{(1+\frac{x}{m})(1-\frac{1}{m})}$$
A78

Ιf

$$\frac{1}{4 i \pi t} = \left(\frac{-1}{2 \sqrt{i \pi t}}\right)^2$$

then these contributions are approximately equal to

$$a_1F_1(x)F_1(1)+a_1G_1(x)F_1(-1)+b_1F_1(x)G_1(1)+b_1G_1(x)G_1(-1)$$
 A80

And finally,

$$I_{1} = a_{1}F_{2}(x)+b_{1}G_{2}(x)$$

$$+a_{1}(F_{1}(x)F_{1}(1)+G_{1}(x)F_{1}(-1))$$

$$+b_{1}(F_{1}(x)G_{1}(1)+G_{1}(x)G_{1}(-1))$$
A81

The second term in the sum of integrals is now considered as  $\ensuremath{\mathrm{I}}_2$  :

$$I_{2} = \sqrt{it/\pi} \int_{-1}^{1} e^{-it(y-\frac{x}{m})^{2}} (a_{2}F_{2}(y)+b_{2}G_{2}(y)) dy$$

$$= \sqrt{it/\pi} \int_{-1}^{1} e^{-it(y-\frac{x}{m})^{2}} \left\{ \frac{-a_{2} + \frac{1}{m^{2}}}{2\sqrt{i\pi t}} + \frac{e^{-it(1-\frac{y}{m^{2}})^{2}/1 + \frac{1}{m^{2}}}}{1 - \frac{y}{m^{2}}} - \frac{b_{2} + \frac{1}{m^{2}}}{2\sqrt{i\pi t}} + \frac{e^{-it(1+\frac{y}{m^{2}})^{2}/1 + \frac{1}{m^{2}}}}{1 + \frac{y}{m^{2}}} \right\} dy$$

$$= \sqrt{it/\pi} \int_{-1}^{1} e^{-it(y-\frac{x}{m})^{2}} dy$$

$$A82$$

Considering the first term of this expression, it is seen that

$$q(y) = \frac{1}{1 - \frac{y}{m^2}}$$
 A83

$$p(y) = (y - \frac{x}{m})^2 + \frac{1}{1 + \frac{1}{m^2}} (1 - \frac{y}{m^2})^2$$
 A84

$$p'(y) = 2(y-\frac{x}{m})-\frac{2}{m^2(1+\frac{1}{m^2})}(1-\frac{y}{m^2})$$
 A85

$$p^{-}(y) = 2 + \frac{2}{m^{+}(1 + \frac{1}{m^{2}})}$$
 A86

And solving for  $y_0$  it is seen that

$$0 = y_0 - \frac{x}{m} - \left(\frac{1}{m^2 \left(1 + \frac{1}{m^2}\right)}\right) \left(1 - \frac{y_0}{m^2}\right)$$
 A87

$$0 = y_0 - \frac{x}{m} - \frac{1}{m^2 (1 + \frac{1}{m^2})} + \frac{y_0}{m^4 (1 + \frac{1}{m^2})}$$
 A88

$$y_0\left(1+\frac{1}{m^4(1+\frac{1}{m^2})}\right) = \frac{x}{m} + \frac{1}{m^2(1+\frac{1}{m^2})}$$
 A89

and

$$y_0 = \left(\frac{x}{m} + \frac{1}{m^2 \left(1 + \frac{1}{m^2}\right)}\right) \left(\frac{1}{1 + \frac{1}{m^4 \left(1 + \frac{1}{m^2}\right)}}\right)$$
 A90

Substituting these expressions into  $\,$  A82 , the result is that the first part of  $\,$  I  $_2\,$  is

$$\frac{a_{2}}{2\sqrt{i\pi t}} \sqrt{it/\pi} \sqrt{1+1/m^{2}} \begin{cases} \frac{-i\pi}{4} - it((y-\frac{x}{m})^{2} + \frac{1}{1+\frac{1}{m^{2}}}(1-y_{0})^{2}) \\ e e \end{cases}$$

$$\frac{1 - \frac{y_{0}}{m^{2}}}{1 - \frac{y_{0}}{m^{2}}}$$

$$\cdot \sqrt{\frac{1}{t \cdot 1 + \left(\frac{1}{m^{4}} (1 + \frac{1}{m^{2}})\right)}} - \frac{a_{2}}{2\sqrt{i\pi t}} \sqrt{it/\pi} \sqrt{1 + 1/m^{2}} \frac{i}{t}$$

$$-it(1 - \frac{x}{m})^{2} + \frac{1}{1 + \frac{1}{m^{2}}} (1 - \frac{1}{m^{2}})^{2}$$

$$\cdot \left[ \frac{e}{(1 - \frac{1}{m^{2}}) \left(2(1 - \frac{x}{m}) - \frac{2}{m^{2}(1 + \frac{1}{m^{2}})}(1 - \frac{1}{m^{2}})\right)} - it(-1 - \frac{x}{m})^{2} + \frac{1}{1 + \frac{1}{m^{2}}} (1 + \frac{1}{m^{2}})^{2}$$

$$- \frac{e}{(1 + \frac{1}{m^{2}}) \left(2(-1 - \frac{x}{m}) - \frac{2}{m^{2}(1 + \frac{1}{m^{2}})}(+ \frac{1}{m^{2}})\right)} \right]$$
A91

Considering the second part, it is seen that

$$q(y) = \frac{1}{1 + \frac{y}{m^2}}$$

$$\rho(y) = (y - \frac{x}{m^2})^2 + \frac{1}{1 + \frac{1}{m^2}} (1 + \frac{y}{m^2})^2$$
 A93

$$p^{-}(y) = 2(y-\frac{x}{m}) + \frac{2}{1+\frac{1}{m^2}} \frac{1}{m^2} (1+\frac{y}{m^2})$$
 A94

$$p^{-}(y) = 2 + \frac{2}{m^{+}(1 + \frac{1}{m^{2}})}$$
 A95

Solving for  $y_0$ ,

$$0 = y_0 - \frac{x}{m} + \frac{1}{m^2} \frac{1}{1 + \frac{1}{m^2}} (1 + \frac{y_0}{m^2})$$
 A96

$$0 = y_0 - \frac{x}{m} + \frac{1}{m^2} \frac{1}{1 + \frac{1}{m^2}} + \frac{y_0}{m^4 (1 + \frac{1}{m^2})}$$
 A97

$$y_0 \left(1 + \frac{1}{m^4 \left(1 + \frac{1}{m^2}\right)}\right) = \frac{x}{m} - \frac{1}{m^2 \left(1 + \frac{1}{m^2}\right)}$$
 A98

and finally

$$y_0 = \left(\frac{x}{m} - \frac{1}{m^2 (1 + \frac{1}{m^2})}\right) \left(\frac{1}{1 + \frac{1}{m^4 (1 + \frac{1}{m^2})}}\right)$$
 A99

Substituting these expressions into A82 it is seen that the second part of  $I_2$  is approximated by

$$\frac{-b_{2}}{2\sqrt{i\pi t}} \sqrt{it/\pi} \sqrt{1+1/m^{2}} \left[ e^{-i\pi/4} \sqrt{\frac{\pi}{t(1+\frac{1}{m^{2}})}} \right]$$

$$\frac{-it(y_0\frac{x}{m})^2 + \frac{1}{1 + \frac{1}{m^2}}(1 + \frac{y_0}{m^2})^2}{1 + \frac{y_0}{m^2}} = \frac{-b_2}{2\sqrt{i\pi t}} \sqrt{it/\pi} \sqrt{1 + \frac{1}{m^2}} \frac{i}{t}$$

$$\begin{cases} -it((1-\frac{x}{m})^{2} + \frac{1}{1+\frac{1}{m^{2}}}(1+\frac{1}{m^{2}}))^{2} & -it((-1-\frac{x}{m})^{2} + \frac{1}{1+\frac{1}{m^{2}}}(1-\frac{1}{m^{2}})^{2}) \\ \frac{e}{(1+\frac{1}{m^{2}})(2(1-\frac{x}{m}) + \frac{2}{m^{2}})} - \frac{e}{(1-\frac{1}{m^{2}})(2(-1-\frac{x}{m}) + \frac{2}{m^{2}})} \\ \frac{e}{(1-\frac{1}{m^{2}})(2(-1-\frac{x}{m}) + \frac{2}{m^{2}})} \end{cases}$$

A100

Combining the first and second terms the result is the complete approximation to  $\ensuremath{\mathrm{I}}_2$  , or

$$I_2 \simeq -\sqrt{1+1/m^2} \sqrt{it/\pi} \frac{1}{2\sqrt{i\pi t}} \sqrt{\frac{\pi}{t(1+\frac{1}{m^4}(1+\frac{1}{m^2}))}}$$

$$\begin{cases} \frac{-i\pi}{4} & -it((y - \frac{x}{m})^{2} + (1 - \frac{y_{0}}{m^{2}})^{2} / 1 + \frac{1}{m^{2}}) \\ & e \end{cases}$$

$$1 - \frac{y_{0}}{m^{2}}$$

$$+ \frac{b_{2}e^{\frac{-i\pi}{4}}e^{-it((y_{0}-\frac{x}{m})^{2}+(1+\frac{y_{0}}{m^{2}})^{2}/1+\frac{1}{m^{2}})}}{1+\frac{y_{0}}{m^{2}}}$$

$$-it((1-\frac{x}{m})^{2}+\frac{1}{1+\frac{1}{m^{2}}}(1-\frac{1}{m^{2}}))^{2}$$

$$-it((-1-\frac{x}{m})^{2}+\frac{1}{1+\frac{1}{m^{2}}}(1-\frac{1}{m^{2}}))^{2}$$

$$-it((-1-\frac{x}{m})^{2}+\frac{1}{1+\frac{1}{m^{2}}}(1+\frac{1}{m^{2}})^{2})$$

$$-\frac{a_{2}e}{(1+\frac{1}{m^{2}})(2(-1-\frac{x}{m})-\frac{2}{m^{2}(1+\frac{1}{m^{2}})}(1+\frac{1}{m^{2}}))}$$

$$-it((1-\frac{x}{m})^{2}+\frac{1}{1+\frac{1}{m^{2}}}(1+\frac{1}{m^{2}}))$$

$$+\frac{b_{2}e}{(1+\frac{1}{m^{2}}(2(1-\frac{x}{m})+\frac{2}{m^{2}}-\frac{1}{1+\frac{1}{m^{2}}}(1+\frac{1}{m^{2}}))}$$

$$-it((-1-\frac{x}{m})^{2}+\frac{1}{1+\frac{1}{m^{2}}}(1-\frac{1}{m^{2}}))$$

$$-\frac{b_{2}e}{(1-\frac{1}{m^{2}})(2(-1-\frac{x}{m})+\frac{2}{m^{2}}(1+\frac{1}{m^{2}})}$$

$$-\frac{b_{2}e}{(1-\frac{1}{m^{2}})(2(-1-\frac{x}{m})+\frac{2}{m^{2}}(1+\frac{1}{m^{2}}))}$$

$$-\frac{b_{2}e}{(1-\frac{1}{m^{2}})(2(-1-\frac{x}{m})+\frac{2}{m^{2}}(1+\frac{1}{m^{2}}))}$$

$$-\frac{b_{2}e}{(1-\frac{1}{m^{2}})(2(-1-\frac{x}{m})+\frac{2}{m^{2}}(1+\frac{1}{m^{2}}))}$$

$$-\frac{b_{2}e}{(1-\frac{1}{m^{2}})(2(-1-\frac{x}{m})+\frac{2}{m^{2}}(1+\frac{1}{m^{2}}))}$$

$$-\frac{b_{2}e}{(1-\frac{1}{m^{2}})(2(-1-\frac{x}{m})+\frac{2}{m^{2}}(1+\frac{1}{m^{2}}))}$$

$$-\frac{b_{2}e}{(1-\frac{1}{m^{2}})(2(-1-\frac{x}{m})+\frac{2}{m^{2}}(1+\frac{1}{m^{2}}))}$$

The denominators of the stationary phase point contribution terms must be simplified:

In the first term,

$$1 - \frac{1}{m^2} \left( \frac{x}{m} + \frac{1}{m^2 (1 + \frac{1}{m^2})} \right) \left( \frac{1}{1 + \frac{1}{m^4} \frac{1}{1 + \frac{1}{m^2}}} \right)$$
 A102

$$= 1 - \frac{1}{m^2} \left( \frac{x}{m} + \frac{1}{m^2 + 1} \right) \left( \frac{1}{1 + \left( \frac{1}{m^4} \right) \left( \frac{1}{1 + \frac{1}{m^2}} \right)} \right)$$
 A103

$$= 1 - \left(\frac{x}{m^3} + \frac{1}{m^4 + m^2}\right) \frac{1}{1 + \frac{1}{m^4 + m^2}}$$
 A104

$$= \frac{1 + \frac{1}{m^4 + m^2} - \frac{x}{m^3} - \frac{1}{m^4 + m^2}}{1 + \frac{1}{m^4 + m^2}}$$
 A105

$$= (1 - \frac{x}{m^3}) \frac{1}{1 + (\frac{1}{m^4})(\frac{1}{1 + \frac{1}{m^2}})}$$
 A106

And in the second term,

$$1 + \frac{1}{m^2} \left( \frac{x}{m} - \left( \frac{1}{m^2} \right) \left( \frac{1}{1 + \frac{1}{m^2}} \right) \right) \left( \frac{1}{1 + \frac{1}{m^4} \left( \frac{1}{1 + \frac{1}{m^2}} \right)} \right)$$
 A107

$$= \left(1 + \frac{x}{m^3} - \frac{1}{m^4 + m^2}\right) \frac{1}{1 + \frac{1}{m^4 + m^2}}$$
 A108

$$= \left(1 + \frac{1}{m^4 + m^2} + \frac{x}{m^3} - \frac{1}{m^4 + m^2}\right) \frac{1}{1 + \frac{1}{m^4 + m^2}}$$
 A109

$$= \left(1 + \frac{x}{m^3}\right) \frac{1}{1 + \frac{1}{m^4} \left(\frac{1}{1 + \frac{1}{m^2}}\right)}$$
 A110

Now, considering the argument for the exponent in the first part, it is seen that

$$\left( y_{\bullet} - \frac{x}{m} \right)^{2} + \frac{\left( 1 - \frac{y_{\bullet}}{m^{2}} \right)^{2}}{1 + \frac{1}{m^{2}}} = \left( \left( \frac{x}{m} + \left( \frac{1}{m^{2}} \right) \left( \frac{1}{1 + \frac{1}{m^{2}}} \right) \right) \left( \frac{1}{1 + \frac{1}{m^{2}}} \right) - \frac{x}{m} \right)^{2}$$

$$+ \frac{\left(1 - \frac{1}{m^2} \left(\frac{x}{m} + \frac{1}{m^2} - \frac{1}{1 + \frac{1}{m^2}}\right) \frac{1}{1 + \frac{1}{m^4} - \frac{1}{1 + \frac{1}{m^2}}}\right)^2}{1 + \frac{1}{m^2}}$$
A111

$$= \left( \left( \left( \frac{x}{m} + \frac{1}{m^2 + 1} \right) \frac{1}{1 + \frac{1}{m^4 + m^2}} \right) - \frac{x}{m} \right)^2 + \frac{1}{1 + \frac{1}{m^2}} \left( 1 - \left( \frac{x}{m^3} + \frac{1}{m^4 + m^2} \right) \frac{1}{1 + \frac{1}{m^4 + m^2}} \right)^2$$
 A112

$$= \left( \left( \frac{x}{m} + \frac{1}{m^2 + 1} \right) \frac{1}{1 + \frac{1}{m^4 + m^2}} - \frac{x}{m} \right)^2 + \frac{1}{1 + \frac{1}{m^2}} \left( \frac{1 + \frac{1}{m^4 + m^2} - \frac{x}{m^3} - \frac{1}{m^4 + m^2}}{1 + \frac{1}{m^4 + m^2}} \right)^2$$
 A113

$$= \left( \left( \frac{x}{m} + \frac{1}{m^2} \frac{1}{1 + \frac{1}{m^2}} \right) \frac{1}{1 + \frac{1}{m^4}} \frac{x}{1 + \frac{1}{m^2}} - \frac{x}{m} \right)^2 + \frac{1}{1 + \frac{1}{m^2}} \left( 1 - \frac{1}{m^2} \left( \frac{x}{m} + \frac{1}{m^2} \frac{1}{1 + \frac{1}{m^2}} \right) \frac{1}{1 + \frac{1}{m^4}} \frac{1}{1 + \frac{1}{m^2}} \right)^2$$

A113.1

The first half of All3 is

$$\left(\frac{\frac{x}{m}(1+\frac{1}{m^2})+\frac{1}{m^2}}{1+\frac{1}{m^2}} - \frac{1}{1+\frac{1}{m^2}} - \frac{x}{m}\right)^2$$
A114

$$= \left( \left( \frac{x}{m} + \frac{x}{m^3} + \frac{1}{m^2} \right) \left( \frac{1}{1 + \frac{1}{m^2}} \right) \frac{1 + \frac{1}{m^2}}{1 + \frac{1}{m^2} + \frac{1}{m^4}} - \frac{x}{m} \right)^2$$
A115

$$= \left( \left( \frac{x}{m} + \frac{x}{m^3} + \frac{1}{m^2} \right) \left( \frac{1}{1 + \frac{1}{m^2} + \frac{1}{m^4}} \right) - \frac{x}{m} \right)^2$$
 A116

$$= \left(\frac{x}{m} + \frac{x}{m^3} + \frac{1}{m^2} - \frac{x}{m} \left(1 + \frac{1}{m^2} + \frac{1}{m^4}\right)\right)^2 \left(\frac{1}{1 + 1/m^2 + 1/m^4}\right)^2$$
 A117

$$= \left(\frac{1}{m^2} - \frac{x}{m^5}\right)^2 \left(\frac{1}{1+1/m^2+1/m^4}\right)^2$$
 A118

$$= \frac{1}{m^4} \left( 1 - \frac{x}{m^3} \right) \left( \frac{1}{1 + 1/m^2 + 1/m^4} \right)^2 = \text{first half}$$
 A119

And the second half is

$$\left(1 - \frac{1}{m^2} \left(\frac{x}{m} + \frac{1}{m^2} \frac{1}{1+1/m^2}\right) \frac{1}{1+\frac{1}{m^4} \frac{1}{1+\frac{1}{m^2}}}\right)^2 \frac{1}{1+\frac{1}{m^2}}$$
 A120

$$= \frac{1}{1 + \frac{1}{m^2}} \left( 1 + \frac{1}{m^4 1 + \frac{1}{m^2}} - \frac{1}{m^2} \left( \frac{x}{m} + \frac{1}{m^2} \frac{1}{1 + \frac{1}{m^2}} \right) \right)^2 \left( \frac{1}{1 + \frac{1}{m^4} \frac{1}{1 + \frac{1}{m^2}}} \right)^2$$
 A121

$$= \frac{1}{1 + \frac{1}{m^2}} \left( 1 + \frac{1}{m^4} \frac{1}{1 + \frac{1}{m^2}} - \frac{x}{m^3} - \frac{1}{m^4} \frac{1}{1 + \frac{1}{m^2}} \right)^2 \left( \frac{1}{1 + \frac{1}{m^4} \frac{1}{1 + \frac{1}{m^2}}} \right)^2$$
A122

$$= \frac{1}{1 + \frac{1}{m^2}} \left( 1 - \frac{x}{m^3} \right) \left( \frac{1 + 1/m^2}{1 + 1/m^2 + 1/m^4} \right)^2$$
 A123

$$= 1 + \frac{1}{m^2} \left( \frac{1 - \frac{X}{m^3}}{1 + \frac{1}{m^2} + \frac{1}{m^4}} \right)^2$$
 A124

the total argument is

$$\frac{1}{m^4} \left(1 - \frac{x}{m^3}\right) \left(\frac{1}{1 + \frac{1}{m^2} + \frac{1}{m^4}}\right)^2 + \left(1 + \frac{1}{m^2}\right) \left(1 - \frac{x}{m^3}\right)^2 \left(\frac{1}{1 + \frac{1}{m^2} + \frac{1}{m^4}}\right)^2$$
 A125

$$= \left(1 + \frac{1}{m^2} + \frac{1}{m^4}\right) \left(\frac{1 - \frac{x}{m^3}}{1 + \frac{1}{m^2} + \frac{1}{m^4}}\right)^2$$
 A126

$$= \frac{\left(1 - \frac{x}{m^3}\right)^2}{1 + \frac{1}{m^2} + \frac{1}{m^4}}$$
 A127

Considering the argument for the exponent in the second half,

$$\left( \left( \frac{x}{m} - \frac{1}{m^2} \cdot \frac{1}{1 + \frac{1}{m^2}} \right) \left( \frac{1}{1 + \frac{1}{m^4} \cdot \frac{1}{1 + \frac{1}{m^2}}} \right) \right)^2$$

$$+ \frac{1}{1 + \frac{1}{m^2}} \left( 1 + \frac{1}{m^2} \left( \frac{x}{m} - \frac{1}{m^2} \frac{1}{1 + \frac{1}{m^2}} \right) \left( \frac{1}{1 + \frac{1}{m^4}} \frac{1}{1 + \frac{1}{m^2}} \right) \right)^2$$
 A128

Considering the first part of this,

$$\frac{\frac{x}{m} + \frac{1}{m^2} - \frac{1}{m^2}}{1 + \frac{1}{m^2}} = \frac{1}{1 + \frac{1}{m^4} + \frac{1}{1 + \frac{1}{m^2}}} - \frac{x}{m}$$
 A129

$$= \frac{\frac{x}{m} + \frac{x}{m^3} - \frac{1}{m^2}}{1 + \frac{1}{m^2}} \frac{1 + \frac{1}{m^2}}{1 + \frac{1}{m^2} + \frac{1}{m^4}} - \frac{x}{m}$$
 A130

$$= \left(\frac{x}{m} + \frac{x}{m^3} - \frac{1}{m^2} - \frac{x}{m} \left(1 + \frac{1}{m^2} + \frac{1}{m^4}\right)\right)^2 \left(\frac{1}{1 + \frac{1}{m^2} + \frac{1}{m^4}}\right)^2$$
 A131

$$= \left(\frac{x}{m} + \frac{x}{m^3} - \frac{1}{m^2} - \frac{x}{m} - \frac{x}{m^3} - \frac{x}{m^5}\right) \left(\frac{1}{1 + \frac{1}{m^2} + \frac{1}{m^4}}\right)^2$$
 A132

$$= \left(\frac{1}{m^2} + \frac{x}{m^5}\right) \quad \left(\frac{1}{1 + \frac{1}{m^2} + \frac{1}{m^4}}\right)^2$$

$$= \frac{1}{m^4} \left(1 + \frac{x}{m^3}\right)^2 \left(\frac{1}{1 + \frac{1}{m^2} + \frac{1}{m^2}}\right)^2$$
 A134

Considering the second part, it is seen that

$$\frac{1}{1 + \frac{1}{m^2}} \left( 1 + \frac{1}{m^2} \left( \frac{x}{m} - \frac{1}{m^2} - \frac{1}{1 + \frac{1}{m^2}} \right) \left( \frac{1}{1 + \frac{1}{m^4}} - \frac{1}{1 + \frac{1}{m^2}} \right) \right)^2$$
 A135

$$= \left(\frac{1}{1 + \frac{1}{m^2}} + \frac{1}{1 + \frac{1}{m^2}} + \frac{1}{1 + \frac{1}{m^2}} + \frac{1}{m^2} + \frac{1}{m$$

$$= \left(\frac{1}{1 + \frac{1}{m^2}} + \frac{1}{1 + \frac{1}{m^2}} + \frac{1}{1 + \frac{1}{m^2}} + \frac{1}{m^3} - \frac{1}{m^4} + \frac{1}{1 + \frac{1}{m^2}}\right)^2 \left(\frac{1 + \frac{1}{m^2}}{1 + \frac{1}{m^2} + \frac{1}{m^4}}\right)^2$$
 A137

$$= \frac{1}{1 + \frac{1}{m^2}} \left(1 + \frac{x}{m^3}\right)^2 \frac{\left(1 + \frac{1}{m^2}\right)^2}{\left(1 + \frac{1}{m^2} + \frac{1}{m^4}\right)^2}$$
A138

$$= \frac{1}{1 + \frac{1}{m^2}} \left(1 + \frac{x}{m^3}\right)^2 \left(\frac{1}{1 + \frac{1}{m^2} + \frac{1}{m^4}}\right)^2$$
 A139

Then the sum of these, or the complete exponential argument, is

$$\frac{1}{m^4} \left(1 + \frac{x}{m^3}\right) \left(\frac{1}{1 + \frac{1}{m^2} + \frac{1}{m^4}}\right)^2 + \left(1 + \frac{1}{m^2}\right) \left(1 + \frac{x}{m^3}\right)^2 \left(\frac{1}{1 + \frac{1}{m^2} + \frac{1}{m^4}}\right)^2$$
 A140

$$= \left(1 + \frac{1}{m^2} + \frac{1}{m^4}\right) \left(1 + \frac{x}{m^3}\right)^2 \left(\frac{1}{1 + \frac{1}{m^2} + \frac{1}{m^4}}\right)^2$$
A141

$$= (1 + \frac{x}{m^3})^2 / 1 + \frac{1}{m^2} + \frac{1}{m^4}$$

Thus the stationary phase point contribution simplifies to

$$-\sqrt{1+1/m^{2}} \quad \sqrt{it/\pi} \; \frac{1}{2\sqrt{i\pi t}} \quad \sqrt{\frac{\pi}{t(1+(\frac{1}{m^{4}})(\frac{1}{1+\frac{1}{m^{2}}})})}$$

$$+ \frac{\frac{-i\pi}{4} - it(1 + \frac{x}{m^3})/1 + \frac{1}{m^2} + \frac{1}{m^4}}{\left(1 + \frac{x}{m^3}\right) \left(1 + \frac{1}{m^2}\right)}$$
A143

$$= -\sqrt{1+1/m^2} \sqrt{it/\pi} \frac{1}{2\sqrt{i\pi t}} \sqrt{\frac{1+1/m^2}{t \cdot 1 + \frac{1}{m^2} + \frac{1}{m^4}}} \frac{1+1/m^2 + 1/m^4}{1 + \frac{1}{m^2}}$$

$$\cdot \begin{cases}
\frac{-i\pi}{4} - it((1-\frac{x}{m^3})^2/1 + \frac{1}{m^2} + \frac{1}{m^4}) \\
\frac{a_2e}{e} = \frac{1}{1-\frac{x}{m^3}}
\end{cases}$$

$$+ \frac{\frac{-i\pi}{4} - it((1+\frac{x}{m^3})^2/1+\frac{1}{m^2}+\frac{1}{m^4})}{1+\frac{x}{m^3}}$$

A144

$$= \frac{-\sqrt{i} \sqrt{1+1/m^2+1/m^4}}{2\sqrt{i\pi t}} \left\{ \frac{\frac{-i\pi}{4} - it((1-\frac{x}{m^3})/1+\frac{1}{m^2}+\frac{1}{m^4})}{1-\frac{x}{m^3}} + \frac{\frac{-i\pi}{4} - it((1+\frac{x}{m^3})^2/1+\frac{1}{m^2}+\frac{1}{m^4})}{1+\frac{x}{m^3}} \right\}$$

$$+ \frac{b_2 e}{1+\frac{x}{m^3}}$$
A145

And this is seen to be, since  $e^{\frac{-i\pi}{4}}\sqrt{i} =$ ,

$$a_2F_3(x)+b_2G_3(x)$$
 A146

Now, considering the end point contributions, the denominators are expanded and the 2's are factored out to get

$$\frac{-\sqrt{1+1/m^{2}}}{4\sqrt{i\pi t}} \quad it / \quad \frac{i}{t} \begin{cases} a_{2}e & e \\ (1 - \frac{1}{m^{2}})(1 - \frac{x}{m} - \frac{1}{m^{2}+1}(1 - \frac{1}{m^{2}})) \\ (1 - \frac{1}{m^{2}})(1 - \frac{x}{m} - \frac{1}{m^{2}+1}(1 - \frac{1}{m^{2}})) \end{cases} \\
- it(1 + \frac{x}{m})^{2} - \frac{it}{1 + \frac{1}{m^{2}}}(1 + \frac{1}{m^{2}})^{2} - it(1 - \frac{x}{m})^{2} - \frac{it}{1 + \frac{1}{m^{2}}}(1 + \frac{1}{m^{2}})^{2} \\
- \frac{a_{2}e}{(1 + \frac{1}{m^{2}})(-1 - \frac{x}{m}} - \frac{1}{m^{2}+1}(1 + \frac{1}{m^{2}})) + \frac{b_{2}e}{(1 + \frac{1}{m^{2}})(1 - \frac{x}{m} + \frac{1}{m^{2}+1}(1 + \frac{1}{m^{2}}))} \\
- it(1 + \frac{x}{m})^{2} - \frac{it}{1 + \frac{1}{m^{2}}}(1 - \frac{1}{m^{2}})^{2} \\
+ \frac{b_{2}e}{(1 - \frac{1}{m^{2}})(-1 - \frac{x}{m}} + \frac{1}{m^{2}}(1 - \frac{1}{m^{2}}) \end{cases}$$
A147

Once more in the denominators, terms of 1/m or higher are 111

neglected, and it is seen that the end point contributions

$$-\frac{1+\frac{1}{m^{2}}}{4\sqrt{i\pi t}}\sqrt{it/\pi} \frac{i}{t} \begin{cases} -it(1-\frac{x}{m})^{2} - \frac{it}{1+\frac{1}{m^{2}}}(1-\frac{1}{m^{2}})^{2} \\ \frac{a_{2}e}{\left(1-\frac{1}{m^{2}}\right)} \left(1-\frac{x}{m}\right) \end{cases}$$

$$-it(1+\frac{x}{m})^{2} - \frac{it}{1+\frac{1}{m^{2}}}(1+\frac{1}{m^{2}})^{2} - it(1-\frac{x}{m})^{2} - \frac{it}{1+\frac{1}{m^{2}}}(1+\frac{1}{m^{2}})^{2} + \frac{a_{2}e}{\left(1+\frac{x}{m}\right)\left(1+\frac{1}{m^{2}}\right)} + \frac{b_{2}e}{\left(1-\frac{x}{m}\right)\left(1+\frac{1}{m^{2}}\right)}$$

$$\left\{ -it \left(1 + \frac{x}{m}\right)^{2} - \frac{it}{1 + \frac{1}{m^{2}}} \left(1 - \frac{1}{m^{2}}\right)^{2} + \frac{b_{2}e}{\left(1 + \frac{x}{m}\right)} \left(1 - \frac{1}{m^{2}}\right) \right\}$$
A148

The outer constant is seen to be

$$\frac{\sqrt{1+1/m^2}}{4 i \pi t} = \frac{\sqrt{1+1/m^2}}{(-2\sqrt{i \pi t})^2}$$
 A149

and there the endpoint contribution is approximately

$$a_2F_1(x)F_2(1)+a_2G_1(x)F_2(-1)$$
  
- $b_2F_1(x)G_2(1)+b_2G_1(x)G_2(-1)$  A150

Thus it is seen that, after adding,

$$I_{1} + I_{2} \approx a_{1}F_{2}(x) + b_{1}G_{2}(x) + a_{2}F_{3}(x) + b_{2}G_{3}(x)$$

$$+ F_{1}(x)(a_{1}F_{1}(1) + b_{1}G_{1}(1) + a_{2}F_{2}(1) + b_{2}G_{2}(1))$$

$$+ G_{1}(x)(a_{1}F_{1}(-1) + b_{1}G_{1}(-1) + a_{2}F_{2}(-1) + b_{2}G_{2}(-1))$$

$$112$$
A151

From this it is concluded that

$$\sqrt{it/\pi} \sum_{n=1}^{N} \int_{-1}^{1} e^{-it(y-\frac{x}{m})^{2}} a_{n}F_{n}(y)+b_{n}G_{n}(y)) dy$$

$$= \sum_{n=1}^{N} \{a_{n}F_{n+1}(x) + b_{n}G_{n+1}(x)\}$$

$$+F_{1}(x) \sum_{n=1}^{N} \{a_{n}F_{n}(1)+b_{n}G_{n}(1)\}$$

$$+G_{1}(x) \sum_{n=1}^{N} \{a_{n}F_{n}(-1)+b_{n}G_{n}(-1)\}$$
A153

A152

And in turn, adding the Io term, it is had that

$$\sqrt{it/\pi} \int_{-1}^{1} e^{-it(y-\frac{x}{m})} (1+\sum\{a_n F_n(y)+b_n(F_n(y)\}) dy$$

$$= 1 + F_1(x) + G_1(x) + \sum_{n=1}^{N} \{a_n F_{n+1}(x) + b_n G_{n+1}(x)\}$$

$$+ G_1(x) \sum_{n=1}^{N} \{a_n F_n(-1) + b_n G_n(-1)\}$$
A153

## Appendix B

This appendix simplifies the definite integral produced by assuming in 2.1.16 that  $a_2$  is effectively infinite.

$$\frac{i}{\lambda L} \int_{-\infty}^{\infty} e^{-\frac{ik}{2L} \left[ g_1 x_1^{2} + g_2 x_2^{2} - 2x_1^{2} x_2^{2} \right]} e^{-\frac{ik}{2L} \left[ g_1 x_1^{2} + g_2 x_2^{2} - 2x_1^{2} x_2 \right]} dx_1$$

$$= \frac{1}{\lambda L} \int_{-\infty}^{\infty} e^{-\frac{i k}{2 L} \left[ g_1 x_1^{2} + g_2 x_2^{2} - 2 x_1 x_2 g_1 x_1^{2} + g_2 x_2^{2} - 2 x_1 x_2 \right]} dx_1$$
 B1

$$= \frac{i}{\lambda L} \int_{-\infty}^{\infty} e^{-\frac{ik}{2L} \left[ 2g_1 x_1^2 - 2(x_2^2 + x_2) x_1^2 + g_2(x_2^2 + x_2^2) \right]} dx_1$$
B2

$$= \frac{i}{\lambda L} e^{-\frac{ik}{2L} g_2(x_2^2 + x_2^2)} \int_{-\infty}^{\infty} e^{-\frac{ik}{L} [g_1 x_1^2 - (x_2^2 + x_2) x_1^2]} dx_1$$
B3

The square is completed in the exponent by adding and subtracting  $\,b^{\,2}/4a\,$  , or

$$\frac{i}{\lambda L} e^{-\frac{ik}{2L}g_{2}(x_{2}^{2}+x_{2}^{2})} \int_{-\infty}^{\infty} e^{-\frac{ik}{L}\left[g_{1}x_{1}^{2}-(x_{2}+x_{2})x_{1}^{2}+\frac{(x_{2}^{2}+x_{2})}{4g_{1}}\right]}$$

$$= \frac{ik}{L} \frac{(x_{2}^{2}+x_{2})}{4g_{1}}$$

$$= dx_{1}^{2}$$

$$= dx_{1}^{2}$$

$$= dx_{1}$$

$$= dx_{1}$$

$$= dx_{1}$$

$$= dx_{1}$$

$$= dx_{2}$$

$$= dx_{1}$$

$$= dx_{2}$$

$$= \frac{i}{\lambda L} e^{-\frac{ik}{2L}g_2(x_2^2 + x_2^2)} \int_{-\infty}^{\infty} e^{-\frac{ik}{L} \left[\sqrt{g_1}x_1 - \frac{x_2^2 + x_2}{2\sqrt{g_1}}\right]^2} e^{\frac{ik}{L} \frac{(x_2^2 + x_2)^2}{4g_1}} dx_1^2$$
 B5

$$= \frac{i}{\lambda L} e^{-\frac{ik}{2L}g_2(x_2^2 + x_2^2)} e^{\frac{ik}{2L} \frac{(x_2^2 + x_2)^2}{2g}} \int_{-\infty}^{\infty} e^{-\frac{ik}{L} \left[\sqrt{g_1}x_1^2 - \frac{x_2^2 + x_2}{2\sqrt{g_1}}\right]^2} dx_1^2$$
B6

If

$$\beta = \frac{-K}{L}$$
 B7

and

$$V = \sqrt{g_1} x_1^2 - \frac{x_2^2 + x_2}{2\sqrt{g_1}}$$
 B8

then the result is

$$dV = \sqrt{g_1} dx_1^2$$

$$= \frac{i k}{\lambda L} \left[ g_2(x_2^2 + x_2^2) \right] e^{\frac{i k}{2L} \frac{(x_2^2 + x_2^2)^2}{2g_1}} \int_{-\infty}^{\infty} \frac{e^{-i\beta V^2}}{\sqrt{g_1}} dV$$
B10

Similarly letting

$$\sqrt{\beta}V = W$$
 B11

$$dw = \sqrt{\beta}dV$$
 B12

the result is

$$= \frac{i}{\lambda L} e^{-\frac{ik}{2L}g_2(x_2^{2} + x_2^{2})} e^{\frac{ik}{2L} \frac{(x_2^{2} + x_2^{2})^{2}}{2g_1}} \frac{1}{\sqrt{g_1\beta}} \frac{1+i}{\sqrt{\pi/2}}$$
B13

then

$$= \frac{i}{\lambda L} (1+i) \sqrt{\pi/2} \sqrt{L/-g_1} K e^{-\frac{i}{2L} \left[ g_2 x_2^{2^2} + g_2 x_2^2 - \frac{x_2^2}{2g_1} - \frac{2x_2 x_2^2}{2g_1} - \frac{x_2^2}{2g_1} \right]} B14$$

$$= \frac{1+i}{\sqrt{2}} \frac{i}{\lambda L} \sqrt{\pi} \sqrt{\frac{\lambda L}{2g_1^{\pi}}} e^{-\frac{i}{2L} \left[ \frac{2g_1 g_2 x_2^2 + g_1 g_2 x_2^2 - x_2^2 - 2x_2 x_2^2 - x_2^2}{2g_1} \right]} B15$$

$$= \sqrt{1} \sqrt{\frac{1}{2L\lambda g_1}} e^{-\frac{ik}{2L\cdot 2g_1}} \left[ (2g_1g_2-1)(x_2^2+x_2^2)-2x_2x_2^2 \right]$$
B16

which is the final kernel.

## Appendix C

This appendix simplifies the integral equation in 2.1.29 into the final form.

$$\gamma u(x) = \int_{-1}^{1} \sqrt{iF} u(y) e$$
 C1

Let

$$-\frac{i}{2m}(m-1)x$$

$$u(x) = g(x)e$$
C2

since

$$N = \frac{m-1}{2m} F$$

then

$$\gamma g(x)e = \sqrt{iF} \int_{-1}^{m^2-1} x^2 = \sqrt{iF} \int_{-1}^{1} g(y)e -i\pi F \frac{m^2-1}{2m} y^2 -i\pi F [g(x^2+y^2)-2xy] dy$$

However, since

$$m = \frac{\sqrt{g+1} + \sqrt{g-1}}{\sqrt{g+1} - \sqrt{g-1}}$$
 C5

$$= \frac{(\sqrt{g+1} + \sqrt{g-1})^2}{q+1-q+1}$$
 C6

$$= \frac{2g + 2\sqrt{(g+1)(g-1)}}{2}$$
 C7

$$= g + \sqrt{g^2 - 1}$$
 C8

50

$$m^2 = g^2 + 2g\sqrt{g^2 - 1} + g^2 - 1$$
 C9

$$m^2+1 = 2g^2+2g\sqrt{g^2-1}$$
 C10

$$\frac{m^2 + 1}{2} = g^2 + g\sqrt{g^2 - 1}$$
 C11

If both sides are divided by m , or rather one by m and the other by its equivalent,  $g+\sqrt{g^2-1}$  , the result is

$$\frac{m^2+1}{2m} = g$$
 C12

this can then be substituted into the integral in place of g:

$$\gamma g(x) = \sqrt{1F} \int_{-1}^{1} g(y)e^{-i\pi F \left[ \frac{m^2+1}{2m} x^2 + \frac{m^2+1}{2m} y^2 - 2xy + \frac{m^2-1}{2m} y^2 - \frac{m^2-1}{2m} x^2 \right]} dy C13$$

$$= \sqrt{1} \int_{-1}^{1} g(y) e^{-i\pi F \left[ \frac{x^2}{m} + my^2 - 2xy \right]} dy$$
 C14

$$= \sqrt{1} \int_{-1}^{1} g(y) e^{-i\pi F(y - \frac{X}{m})^{2}} dy$$
 C15

## <u>Appendix D</u>

List of program BARC employing the expressions developed in Chapter III and IV.

```
PROGRAM BARC(IMPOI, OUIPOI, TAPECTEGIPOI)

REAL NEQ, MAG, MSUBM(51), MSUPM(51), INTENS(1000)

COMPLEX EYE, COEF(51), AM(51), LAMBDA(51)

COMPLEX CL(51), COUST(51), CDUM, AM1, AM2, RTEYE

COMPLEX FIELDX(1000), SIG, BN1, 502, FNX, BOOT

DIMENSION LABEL(17), STCREX(1600), KINDEX(51), PLOCON(51)

DIMENSION FURMAL(20, 410), PLOFUE(20)
         DIMENSION FUNVAL(20,410), PLOFUL(20)
         DATA LABEL/17(10H
C
    THIS PROGRAM COMPUTES RESONATOR MODE EIGENVALUES AND
      SUBSEQUENTL EVALUATES INTENSITY VALUES FOR POINTS
C
      ACROSS THE OUTPUT PLANE OF A STRIP LASER RESONATOR.
C
      THE PROGRAM DEALS WITH SITHER A BARE OR LOADED
      CAVITY, USER'S PREFERENCE.
C
   OUTPUT CONSISTS OF AN EIGENVALUE LIST, WITH PHASE AND MAGNITUDE, FIFLD VALUES FOR A SELECTED MODE EITHER ON OR OFF THE MIRROR, PLOTS OF FIELD SERIES
C
      FUNCTIONS OR WEIGHTING CONSTANTS, AND PLOTS OF INTENSITY ACROSS THE OUTPUT PLANE WITH EITHER LIMITED OR EXTENTED
C
      RANGE.
     COMPILED CODE NEEDED AROUND 110000 OCTAL TO LOAD.
C
     INPUT QUANTITIES ARE AS FOLLOWS:
C
      MAG = CAVITY MAGNIFICATION
      NEQ = EQUIVALENT FRESHEL HUMBER
HTEST1 = FIELD SOLUTION PARITY DESIGNATOR
C
C
      NBIG = DESIRED # TERMS IN FIELD SERIES
C
      CAVLEN = CAVITY LENGTH IN LENGTH UNITS FOR LOADED CASE
C
      GNAWT = SMALL SIGNAL GAIN IN PER LENGTH
Č
      H = AVERAGE CAVITY INTENSITY, OR EIGENVALUE FORCING
C
           PARAMETER
CCC
      TO TERMINATE PROGRAM, INPUT MAG=0 OR LESS.
NOTE: EVMAG DENOTES EIGENVALUE, MAGNITUDE AND EVPH
C
     DENOTES EIGENVALUE, PHASE.
Ċ
    THIS PROGRAM ALSO REQUIRES IMSL ROUTINE ZCPOLY AND PLOT LIBRARY CCPLOT56X. FINAL COPY, 20 OCT 1980. J E ROWLEY
C
¢
C
Č
994
         FORMAT(G10.3)
          LABEL(1)=10H
                                 NEQ=
          LABEL(3)=10H
                                 MAG =
         WRITE(8,999)
FORMAT(1H1,1X,*INPUT MAG, NEQ, AND PARITY: *,/)
777
999
          IF(MAG.LE.O.) GO 10 888
```

PROGRAM BARC(INPUT, OUTPUT, TAPE8 = OUTPUT)

```
WRITE(8,88) MAG, NEQ
       IF(MTEST1.EQ.0) GO TO 8
       WRITE(8,977)
       GO TO 9
8
       WRITE(8,976)
9
       CONTINUÉ
       FORMAT(1X, *PARITY IS ODD. *,/)
FORMAT(1X, *PARITY IS EVEN. *,/)
977
976
       LABEL(5)=10H
                          MODE E
       LABEL(6) = 10HIGENVALUE:
¢
     MSUPN(I)=MAG**(I-1)
C
    MSUBN(I)=1+1/MAG**2 + ... +1/MAG**(2*I-2)
       MSUBN(1)=1.0
       MSUPN(1)=1.0
       DO 10 I=2,51
       MSUPN(I) = MAG * MSUPN(I-1)
       MSUBN(I)=MSUBN(I-1)+1./MSUPN(I)**2
10
       CONTINUE
C
       PI=2.*ASIN(1.0)
       EYE=CMPLX(0.,1.)
       RTEYE=CMPLX(1.,1.)/SQRT(2.)
DUM1=2*PI*MAG**3/(MAG**2-1.)
       RNBIG=ALOG(250*NEQ)/ALOG(MAG)
       IF(RNBIG.LE.50.) GO TO 15
       WRITE(\delta,998)
       GO TO 777
WRITE(8,996) RNBIG
996
       FORMAT(1X, *CALCULATED NBIG = *,G14.7, *INPUT INTEGER CHOICE:*,/)
       READ *, NBIG
       WRITE(8,979)NSIG
WRITE(8,975)
FORMAT(1X,*TYPE 1 FOR GAIN CONSIDERATION: #,/)
READ *,IGAINQ
WRITE(8,979)IGAINQ
975
       IF(IGAINQ.NE.1) GO TO 5
       WRITE(8,974)
FORMAT(1x,*INPUT LENGTH AND S-S-GAIN IN COMMON UNITS: *,/)
974
       READ *, CAVLEN, GNAMT
       WRITE(8,971) CAVLEN, GNAWT
C
     DIVIDE INPUT INTENSITY GAIN BY TWO TO MAKE IT THE FIELD GAIN,
C
     WHICH IS WHAT THIS PROGRAM ACTUALLY REQUIRES
Č
       GNAWT=GNAWT/2.
       FORMAT(1X,*IMPUT VALUES ARE: *,2G14.7,/)
H=SQRT(GNAWT*CAVLEN/ALOG(MAG)-.5)
971
       WRITE(8,973)H
```

```
FORMAT(1X,*H=*,G14.7,*INPUT MODIFIED VALUE OR O TO CONT : *,/)
973
       READ *, HVAL
WRITE(8,972)HVAL
       FORMAT(1X,*INPUT VALUE IS : *,G14.7,/)
972
       IF(HVAL.NE.O.) H=HVAL
       GAMMA=EXP(2*CAVLEN*(GNAWT/(1.+2*H**2)))
       GO TO 6
       H=1. $ GAMMA=1.
CONTINUE
5
       WRITE(8,993)
       FORMAT(1X,*INPUT ZERO TO LIST EIGENVALUES :*,/)
READ *,LTEST
993
       WRITE(8,979)LTEST
       LABEL(13) = 10H
                            EVEN
       NDEG=NBIG+1
       IF(MTEST1.EQ.0) GO TO 16
       LABEL(13) = 10H
       NDEG=NBIG
       T=DUM1 * NEQ
16
       LABEL(14)=10H PARITY
    COMPUTE COEFFICIENTS OF THE POLYNOMIAL
P(Z)=COEF(1)*Z**NDEG + COEF(2)*Z**(NDEG-1) + ... +
C
C
     COEF(NDEG)*Z + COEF(NDEG+1)
C
       COEF(1) = CMPLX(1.,0.)
       NCOEF=NDEG+1
DO 25 I=1,NDEG
       AN1=RTEYE*2*SQRT(PI*T/MSUBN(I))
       AN2=-T*EYE/MSUBN(I)
       AN3=1.-1./MSUPN(I+1)
       AN4=1.+1./MSUPN(I+1)
       AN(I)=(CEXP(AN2*AN3**2)/AN3+CEXP(AN2*AN4**2)/AN4)/AN1
IF(MTEST1.EQ.0) GO TO 25
       AN(I)=(CEXP(AN2*AN3**2)/AN3-CEXP(AN2*AN4**2)/AN4)/AN1
25
       CONTINUE
       IF(MTEST1.EQ.1) GO TO 27
       COEF(2)=(AN(1)-1.)*GAMMA
       DO 26 I=3, NCOEF
       COEF(I)=GAMMA**(I-1)*(AN(I-1)-AN(I-2))
26
       GO TO 666
27
28
       DO 28 I=2, NCOEF
       COEF(I) \approx AN(I-1)*GAMMA**(I-1)
C
    COMPUTE ROOTS OF POLYNOMIAL WITH IMSL ROUTINE TO
C
    OBTAIN THE EIGENVALUES
666
       CALL ZCPOLY(COEF, NDEG, LAMBDA, IER)
     NOW ORDER THE EIGENVALUES BY SIZE
```

```
IF(LTEST.EQ.O) WRITE(8,89)
       I=1
       DO 70 I1=2, NDEG
       SIZE= REAL(LAMBDA(I)) **2+AIMAG(LAMBDA(I)) **2
       K = I
       DO 75 J=11, NDEG
SIZE1=REAL(LAMBDA(J))**2+AIMAG(LAMBDA(J))**2
       IF(SIZE1.LT.SIZE) GO TO 75
       K = J
       SIZE=SIZE1
75
       CONTINUE
       CDUM=LAMBDA(I)
       LAMBDA(I)=LAMBDA(K)
       LAMBDA(K)=CDUM
       CL(I)=LAMBDA(I)
       EVPH=ATAN2(AIMAG(CL(I)), REAL(CL(I)))*180./PI
       SMA=REAL(CL(I))**2+AIMAG(CL(I))**2
       SMAG=SQRT(SMA)
       IF(LTEST.EQ.0) WRITE(8,333)I, LAMBDA(I), SMAG, EVPH
       FORMAT(1X, I10, 4(G14.7, 1X),/)
333
       I=11
70
       CONTINUE
       EVPH=ATAN2(AIMAG(LAMDDA(NDEG)), REAL(LAMBDA(NDEG)))*180./PI
SMA=REAL(LAMBDA(NDEG))**2+AIMAG(LAMBDA(NDEG))**2
       SMAG=SQRT(SMA)
       IF(LTEST.EQ.O) WRITE(8,333) NDEG, LAMBDA(NDEG), SMAG, EVPH
   NOW CALCULATE THE CONSTANTS FOR THE FUNCTION SUM FOR A PRTICULAR MODE. LOOP THEN TO CALCULATE THE FIELD AT A SELECTED NUMBER OF POINTS FROM ZERO TO ONE
45
       X=0.
       BRIGHT=0.
       WRITE(8,997)
       FORMAT(1X,*IMPUT 1 TO CALC FIELDS, 0 TO DO NEW CAVITY:*,/)
READ *,MTEST2
WRITE(8,979)MTEST2
997
        IF(MTEST2.EQ.0) GO TO 777
       WRITE(8,995)
FORMAT(1X,*IMPUT DESIRED MODE NUMBER:*,/)
995
       READ *, MODE
WRITE(8,979) MODE
LABEL(15) = 10H
                             MODE #
        ENCODE(10,987, LABEL(16)) MODE
987
        FORMAT(12,8X)
        NPOINT=0
        NL=NBIG
        ROOT=LAMBDA(MODE)
992
        FORMAT(1X,15,1X,*POINTS WILL BE EVALUATED FOR MODE #,2G14.7,/)
        CONSIDER I/O OPTIONS AND CALCULATE THE CONSTANTS FOR EITHER
```

```
PARITY CHOICE.
        IF(MTEST1.EQ.1) GO TO 40
        DO 30 I=1,NL
        RINDEX(I)=I
        CONST(I)=H*(RCOT-GAMMA)/GAMMA/AN(NDEG)*(ROOT/GAMMA)**(NL-I)
30
        GO TO 29
DO 41 I=1,NL
40
        RINDEX(I)=I
        CONST(I) = (GAMMA/ROOT) **I
41
29
        WRITE(8,982)
982
        FORMAT(1X, *INPUT O TO CALC INTENSITIES OVER EXPANDED RANGE: *./)
        READ *, JTEST WRITE(8,979) JTEST
        ENCODE(10,994,LABEL(2))NEQ
        ENCODE(10,994, LABEL(4)) MAG
        ENCODE(10,994,LABEL(7))REAL(ROOT)
ENCODE(10,994,LABEL(8))AIMAG(ROOT)
IF(JTEST.ME.O) GO TO 46
        LABEL(9) = 10HMIRROR
        LABEL(10) = 10HPLANE
        LABEL(11) = 10HSCALED
        IF(IGAINQ.EQ.1) LABEL(11)=10H
LABEL(12)=10H INTENSITY
LABEL(17)=10HAPPROX # 2
        CALL ALLINT (MAG, MSUBN, MSUPN, CONST, T, NBIG, MTEST1, RCOT, LABEL, H,
           GAMMA, IGAINQ)
        WRITE(8,981)
        WRIE(0,901)
FORMAT(1X,*INPUT O TO CONTINUE WITH OTHER I/O OPTIONS:*,/)
READ *,JTEST1
WRITE(8,979)JTEST1
IF(JTEST1.NE.0) GO TO 45
LABEL(17)=1CHAPPROX # 1
981
46
        WRITE(8,980)
980
        FORMAT(1X, *INPUT # PNTS FROM 0-1 AND 0-1 TO PLOT OR PRINT: *,/)
        READ *,INCX,MTEST3
WRITE(8,978)INCX,MTEST3
        WRITE(8,992)
     CALCULATE THE FIELD AT VARIOUS X VALUES USING THE
    CONSTANTS JUST CALCULATED:
   FOR EVEN, F(X) = 1 + SUM(H(X))

FOR ODD, F(X) = SUM(H(X)), WHERE THE H(X)'S ARE THE OMES

DERIVED FOR EACH CASE
Č
        NPOINT=NPOINT+1
        STOREX(NPOINT) =X
        SIG=CMPLX(0.,0.)
        DO 32 I=1,NL
        BN1=RTEYE*2*SQRT(PI*T/MSUBN(I))
        BN2=-T*EYE/MSUBN(I)
        BN3=1.-X/MSUPN(I+1)
```

```
BN4=1.+X/MSUPN(I+1)
       HNX=(CEXP(BH2*5H3**2)/BH3+CEXP(BH2*BH4**2)/BH4)/BH1
       FUNVAL(I, NPOINT) = REAL(-HNX) **2+4IMAG(-HNX) **2
IF(MTEST1.EQ.0) GO TO 32
       HNX=(CEXP(BN2*5N3**2)/BN3-CEXP(BN2*8N4**2)/BN4)/BN1
FUNVAL(I,NPOINT)=REAL(-HNX)**2+AIMAG(-HNX)**2
       SIG=SIG+CONST(I)*HNX
32
       IF(MTEST1.EQ.1) GO TO 33
       FIELDX(NPOINT) = H+SIG
       GO TO 34
FIELDX(NPOINT)=SIG
33
34
       INTENS(NPOINT) = REAL(FIELDX(NPOINT)) **2+AIMAG(FIELDX(NPOINT)) **2
       IF(INTENS(NPOINT).GT.BRIGHT) BRIGHT=INTENS(NPOINT)
       IF(MTEST3.EQ.0) GO TO 35
       WRITE(8,87)X, FIELDX(NPCINT)
       WRITE(8,86) INTENS(NPOINT)
       FORMAT(1X,*INTENSITY = *,G14.7,/)
FORMAT(1X,*X = *,G14.7,* FIELD = *,2G14.7)
86
87
35
       X=X+1./INCX
       IF(NPOINT.LT.INCX) GO TO 31
       IF(MTEST3.EQ.1) GO TO 777
       WRITE(8,991)
991
       FORMAT(1X, *TYPE ZERO TO PLOT CONSTANTS VS N: #,/)
       READ *, HTESTC
       WRITE(8,979)MTESTC
IF(MTESTC.NE.O) GO TO 38
       LABEL(9) = 10 HCONSTANT #
       LABEL(10)=10H
       LABEL(11) = 10H
                        MOD (CONS
       LABEL(12) = 10HTANT) **2
       DO 42 I=1, NL
42
       PLOCON(I) = REAL(CONST(I)) **2+AIMAG(CONST(I)) **2
       CALL HGRAPH(RINDEX, PLOCON, NBIG, LABEL, 1, -1, 11)
       WRITE(8,984)MODE
984
       FORMAT(1X, *COMPLETED PLOT OF CONSTANTS, MODE =*,12,/)
38
       WRITE(8,990)
990
       FORMAT(1x, *TYPE INDEX OF FUNCTION TO PLOT OR O TO CONTINUE: *./)
       READ *, INDEX
       WRITE(8,979) INDEX
LABEL(9) = 10HMIRROR
       LABEL(10) = 10HPLANE
       IF(INDEX.EQ.O) GO TO 36
       DO 43 I=1, INCX
       PLOFUN(I) = FUNVAL(INDEX, I)
43
       LABEL(11) = 10HMOD(FUN, IN
       ENCODE(10,989, LABEL(12)) INDEX FORMAT("DEX=",12,")**2")
989
       CALL HGRAFH(STOREX, PLOFUN, INCX, LABEL, 1,0,0)
       WRITE(8,986) INDEX
       FORMAT(1x, *COMPLETED PLOT OF FUNCTION, INDEX =*,12,/)
986
       GO TO 38
```

```
36
988
          WRITE(8,988)
          FORMAT(1X, *TYPE ZERO TO PLOT INTENSITY: *,/)
          READ *, ICONT
WRITE(8,979) ICONT
          IF(ICONT.NE.O) GO TO 45
          LABEL(11) = 10HSCALED
          IF(IGAINQ.EQ.1) LABEL(11)=10H
          LABEL(12)=10H INTENSITY
          IF(IGAINQ.EQ.1) BRIGHT=1.
          DO 37 I=1, INCX
INTENS(I)=INTENS(I)/BRIGHT
37
          CALL HGRAPH(STOREX, INTENS, INCX, LABEL, 1,0,0)
          WRITE(8,985)
          GO TO 45
          GO TO 45

FORMAT(1X,*INPUT VALUES ARE: #,215,/)

FORMAT(1X,*INPUT VALUE IS: #,15,/)

FORMAT(1X,*COMPLETED PLOT OF NORMALIZED INTENSITY.*,/)

FORMAT(1X,*REVISE PARAMETERS SO NDEG 50*)

FORMAT(10X,*MAG = *,F6.2,5X,*NEQ = *,F6.2,/)

FORMAT(9X,*I*,2X,*LAMBDA(REAL)*,2X,*LAMBDA(IMAG)*,6X,

1 *EVMAG*,11X,*EVPH*,/)

CALL EXIT
978
979
985
998
88
89
888
          CALL EXIT
          END
          SUBROUTINE ALLINT(MAG, MSUBN, MSUPN, CONST, T, NBIG, MTEST1, ROOT
                ,LABEL, H, GAMMA, IGAÎNQ)
          DIMENSION LABEL(17), XSAVE(2000)
REAL MSUBH(51), MSUPH(51), INARG1, INARG2, INARG3, INARG4, INARG5
          REAL INARG6, INARG7, INARG8, MAG, INTENS(2000)
          REAL MINV
          COMPLEX APART1, APART2, BPART1, BPART2, ALLFUN, CONST(51), ROOT, EYE COMPLEX AFUN, BFUN, SPINTC, SPINTD, EVENX, OUTCON, FRESL, CONSTA, CONSTB
          COMPLEX EYEFAC, SPCON
       THIS SUBROUTINE FOLLOWS PROGRAM BARC AND COMPUTES BEAM INTENSITITE IN THE OUTPUT PLANE FROM THE OPTIC AXIS TO SOME DESIRED OUTER POIN OUTER POINT AND # INTERMEDIATE POINTS FOR EVALUATION ARE INPUT
       WHILE ALL OTHER REQUIRED QUANTITIES ARE CARRIED THROUGH IN THE
       ARGUMENT LIST AS FOLLOWS:
       MAG= CAVITY MAGNIFICATION
       MSUBN= ARRAY FOR PARTIAL SUMS OF INVERSE POWERS OF MAG
       MSUPH ARRAY FOR MAG TO SOME POWER

CONST ARRAY FOR MAG TO SOME POWER

CONST ARRAY OF CONSTANTS IN THE ASYMPTOTIC SERIES

T QUANTITY DEFINED IN BARC PER HORWITZ

NBIG # TERMS IN THE SERIES
       MTEST1 = PARITY DESIGNATOR
       ROOT = MODE EIGENVALUE
C
       LABEL= PLOT LABELING ARRAY
```

```
BRIGHT=0.
       PI=2. #ASIN(1.)
       EYE=CMPLX(0.,1.)
       EYEFAC=(1.-EYE)/2.
       WRITE(8,900)
       FORMAT(1811, *ENTERING EXTENDED RANGE INTENSITY SUBROUTINE.*,/)
DO 10 I=1,51
900
       MSUPN(I) = MAG * MSUPN(I)
10
       NPOINT=1
       X=0.
       WRITE(8,901)
FORMAT(1X,*INPUT MIN AND MAX X VALUES AND # POINTS BETWEEN: *,/)
       READ #, XMIN, XMAX, INCX
X=XMIN
901
50
       ALLFUN=(0.,0.)
       XOMAG=X/MAG
       DO 310 I=1, NBIG
       MINV=1./MSUPN(I)
       EVENX=(0.,0.)
       SPNTD=(0.,0.)
       SPNTC=(0.,0.)
       CONSTA = - CONST(I) *GAMMA
       CONSTB = COMSTA
       IF(MTEST1.EQ.1) CONSTB=-CONSTA
       P2PRYM=2.*(1.+1./MSUPN(2*I)/MSUBN(I))
       STAPHA=(MINV/MSUBN(I)+XOMAG)/(.5%P2PRYM)
       STAPHB=(-MINV/MSUBM(I)+XOMAG)/(.5*P2PRYM)
       INARG1=(1.-XCMAG)**2+((1.-MINV)**2/MSUBN(I))
       INARG2=((1.-XOMAG-(MINV-MINV**2)/MSUBN(I))**2)/(.5*P2PRYM)
AARG1=INARG2-INARG1
       APART1=CEXP(EYE*T*AARG1)/(1.-MINV)*(-CONSTA)
       INARG3=(-1.-XOMAG)**2+(1.+MINV)**2/MSUBN(I)
INARG4=((-1.-XOMAG-(MINV+MINV**2)/(MSUBN(I)))**2)/(.5*P2PRYM)
       AARG2=INARG4-INARG3
       APART2=CEXP(EYE*T*AARG2)*(-CONSTA)/(1.+MINV)
       INARC5=(1.-XCMAG)**2+(1.+MINV)**2/MSUBN(I)
INARG6=(1.-XCMAG+(MINV+MINV**2)/MSUBN(I))**2/(.5*P2PRYM)
BARG1=INARG6-INARG5
       BPART1=CEXP(BARJ1*EYE*T)*(-CONSTB)/(1.+MINV)
INARG7=(1.+XOMAG)**2+(1.-MINV)**2/MSUBN(I)
       INARG8=(-1.-XOMAG+(MINV-MINV**2)/MSUBN(I))**2/(.5*P2PRYM)
       BARG2=INARG8-INARG7
       BPART2=CEXP(BARG2*EYE*T)*(-COMSTB)/(1.-MINV)
       OUTCON=SQRT(MSUBM(1)/PI/T/P2PRYM)/2./ROOT
       SPCON=SQRT(MSUBN(I)*2./P2PRYM/PI/T)/2./ROOT
       FRSPOS=SQRT(T/PI/P2PRYM)*(2.*(1.-XOMAG)-2.*(1.-HINV)/MSUPN(I)/
          KSUBN(I))
       FRSNEG=SQRT(T/PI/P2PRYM)*(2.*(-1.-XOMAG)-2.*(1.+MINV)/MSUPN(I)/
          MSUBN(I))
       IF(STAPHA.GE.-1..AND.STAPHA.LE.1.) GO TO 130
       AFUN=APART1*(FRESL(FRSPOS)-EYEFAC)-APART2*(FRESL(FRSNEG)-EYEFAC)
```

```
IF(STAPHA.LT.1.) GO TO 200
      AFUN=APART1*(FRESL(FRSPOS)+EYEFAC)-APART2*(FRESL(FRSNEG)+EYEFAC)
      GO TO 200
      AFUN=APART1*(FRESL(FRSPOS)-EYEFAC)-APART2*(FRESL(FRSNEG)+EYEFAC)
130
      SPNTC=SPCON*(-CONSTA)/(1.-STAPHA/MSUPN(I))*CEXP(-EYE*(PI/4.+T*
          ((STAPHA-XCMAG)**2+(1.-STAPHA/MSUPN(I))**2/MSUBN(I))))
      FRSPOS=SQRT(T/PI/P2PRYM)*(2.*(1.-XOMAG)+2.*(1.+MINV)/MSUPN(I)/
200
         MSUBN(I))
     1
      FRSNEG=SQRT(T/PI/P2PRYM)*(2.*(-1.-XOMAG)+2.*(1.-MINV)/MSUPN(I)/
         MSUBN(I))
      IF(STAPHB.GE.-1..AND.STAPHB.LE.1.) GO TO 140
      BFUN=BPART1*(FRESL(FRSPOS)-EYEFAC)-BPART2*(FRESL(FRSNEG)-EYEFAC)
      IF(STAPHB.LT.1.) GO TO 300
      BFUN=BPART1*(FRESL(FRSPOS)+EYEFAC)-BPART2*(FRESL(FRSNEG)+EYEFAC)
      GO TO 300
140
      BFUN=BPART1*(FRESL(FRSPOS)-EYEFAC)-BPART2*(FRESL(FRSNEG)+EYEFAC)
      SPNTD=SPCON*(-CONSTB)/(1.+STAPHB/MSUPN(I))*CEXP(-EYE*(PI/4.+T*
         ((STAPHB-XOMAG)**2+(1.+STAPHB/MSUPN(I))**2/MSUBN(I))))
300
      ALLFUN=OUTCON*(AFUN+BFUN)+SPNTC+SPNTD+ALLFUN
310
      CONTINUE
802
      FORMAT(1X,2G14.7)
      EARG1=SQRT(T/2./PI)*2.*(1.-XOMAG)
      EARG2=SQRT(T/2./PI)*2.*(-1.-XCMAG)
      EVENX=CSQRT(EYE/2.)/ROOT*(FRESL(EARG1)-FRESL(EARG2))
IF(X/MAG.GE.-1..AND.X/MAG.LE.1.) EVENX=EVENX-CSQRT(EYE/2.)/ROOT*
          (1.-EYE)+CEXP(-EYE*PI/4.)/ROOT*CSQRT(EYE)
      EVENX=EVENX*H*GAMMA
      IF(MTEST1.EQ.O) ALLFUN=ALLFUN+EVENX
      WRITE(8,802) ALLFUN
      INTENS(NPOINT) = AIMAG(ALLFUN) **2+REAL(ALLFUN) **2
      XSAVE(NPOINT) = X
      WRITE(8,800) INTENS(NPOINT), XSAVE(NPOINT)
800
      FORMAT(1X,2G14.7)
      IF(INTENS(NPOINT).GT.BRIGHT) BRIGHT=INTENS(NPOINT)
      IF(IGAINQ.EQ.1) BRIGHT=1.
      IF(X.GT.XMAX) GO TO 500
      X=X+1./INCX
      NPOINT = NPOINT+1
      GO TO 50
      DO 510 I=1, MPOINT INTENS(I) / BRIGHT
500
510
      CALL HGRAPH(XSAVE, INTENS, NPOINT, LABEL, 1,0,0)
      DO 600 I=1,51
      MSUPN(I)=MSUPN(I)/MAG
600
      WRITE(8,904)
904
      FORMAT(1X, *COMPLETED CALCULATION AND PLOT, EXTENDED. #,/)
      RETURN
      END
      SUBROUTINE HGRAPH(X,Y,N,ID,NO,NP,NS)
      DIMENSION X(1),Y(1),ID(1) $ IF (NO.EQ.2) CALL PLOT(-1.85,2.10,-3
                                  $ IF (NO.LT.0) GO TO 10
      IF (NO.EQ.2) GO TO 30
```

```
CALL SCALE(X,7.,N,1) $ CALL SCALE(Y,5., CALL PLOT(0.,11.,2) $ CALL PLOT(8.5,11.,2) CALL PLOT(8.5,0.,2) $ CALL PLOT(0.,0.,2)
                                                  $ CALL SCALE(Y,5.,N,1)
10
         CALL PLOT(1.35,1.35,-3) $ CALL PLOT(0.,8.30,-2)
         IF(ID(1).EQ.999) GO TO 25
         CALL PLOT(.1,-.1,-3)
DO 20 I=1,7,2
                                                  $ CALL PLOT(0.,-2.,-2)
20
         CALL SYMBOL( (I+1.5)*.1,.3,.07,ID(I),90.,20)
                                                  $ CALL PLOT(1.,0.,2)
         CALL PLOT(0.,0.,3)
         CALL PLOT(1.,2.,2)
                                                  $ CALL PLOT(0.,2.,-2)
         CALL PLOT(-.1,.1,-3)
         CALL PLOT(5.8,0.,-2)
25
         CALL PLOT(0.,-8.30,-2) $ CALL PLOT(-5.8,0.,-2)
         CALL SYMBOL(.5, -.2, .1, ID(13), 0., 50) $ CALL PLOT(5.3, .75, -3) CALL AXIS(0., 0., ID(9), -20, 7., 90., X(N+1), X(N+2))
         CALL AXIS(0.,0.,ID(11),20,5.,180.,Y(N+1),Y(N+2))
Y(N+2)=-Y(N+2)
$ CALL LINE(Y,X,N,1,NP,NS)
30
         Y(N+2)=-Y(N+2)
                                                  $ CALL PLOT(1.85,-2.10,-3)
                                                  $ END
         RETURN
         SUBROUTINE AXIS(XO,YO,L,NC,RL,ANG,RMIN,DR)
         DIMENSION L(1) $ A=ANG*3.14159/180. $ DX=.1*COS(A) $ DY=.1*SIN(A
         IC=ISIGN(1,NC) $ N=NC=IABS(NC) $ R=.1 $ N=1 $ X=X0 $ Y=Y0$

CALL PLOT(X,Y,3) $ X=X+DX $ Y=Y+DY $ CALL PLOT(X,Y,2)

CALL PLOT(X-.21*DY*IC,Y+.21*DX*IC,2)

IF(N.EQ.5) CALL PLOT(X-.42*DY*IC,Y+.42*DX*IC,2)
10
         IF(N.EQ.10) CALL PLOT(X-.70*DY*IC,Y+.70*DX*IC,2)
N=MOD(N,10)+1 $ R=R+.1 $ IF(R.LT.RL) GO TO 10
A=ANG-(IC+1)*45. $ DX=10.*DX $ DY=10.*DY
         C=-.175+.125*IC
                                      $
                                                 D=.19+.35*IC
         X=X0+C*DX-D*DY
                                                  Y=Y0+C*DY+D*DX
         R=AMAX1(ABS(FMIN),ABS(RMIN+DR*RL)) $ R=ALOG10(R)
         R=AGAI(ABS(R)II), ABS(KMIN+DK*KL)) $ R=ALOG10(R)
IR=INT(ABS(R)) $ IF(R.LT.O.) IR=-(IR+1) $ IR=IR-MOD(IR,3)
R1=RMIN/10.**IR $ DR1=DR/10.**IR $ R=O.
ENCODE(7,101,S)R1 $ CALL SYMBOL(X,Y,.07,S,A,7) $ R1=R1+DR1
X=X+DX $ Y=Y+DY $ R=R+1. $ IF(R.LE.RL) GO TO 20
R=(RL-.1*NNC)/2. $ C=.1+.5*IC
20
                                                    Y=Y0+R*DY+C*DX
         X = XO + R * DX - C * DY
         CALL SYMBOL(X,Y,.1,L,ANG,NNC) $ IF(IR.EQ.0) RETURN ENCODE(5,102,S) $ CALL SYMBOL(999.,999.,10,S,ANG,5)
          CALL WHERE(X,Y,A)
          ENCODE(3,103,S) IR $ CALL SYMBOL(X,Y,.07,S,ANG,3)
         FORMAT(F7.2)
FORMAT(5H *
101
102
103
          FORMAT(I3)
          RETURN
                                    END
                   SUBROUTINE SCALE(DATA, LENGTH, N, K)
              REAL DATA = N+2 DIMENSIONED ARRAY OF DATA TO BE SCALED =
              INTEGER N = NUMBER OF DATA POINTS
REAL LENGTH = LENGTH OF THE PLOT AXIS (E.G. IN INCHES)
              INTEGER K = UNUSED PARAMETER INCLUDED FOR COMPATIBILITY =
```

```
WITH THE EQUIVALENT CALCOMP SUBROUTINE
0000000
          THE FOLLOWING VALUES ARE RETURNED:
                   DATA(N+1) = ADJUSTED DATA MINIMUM
DATA(N+2) = "NICE" SCALE FACTOR IN DATA UNITS
PER LENGTH UNIT (E.G. YOLTS/INCH)
      SUBROUTINE SCALE(DATA, LENGTH, N, K)
      REAL DATA(N), LENGTH, SF(5)
DATA SF /1., 2., 2.5, 5., 10. /
C
      COMPUTE THE RAW SCALE FACTOR
      DMIN=DMAX=DATA(1)
      DO 10 I=1,N
             IF(DATA(I) .LT. DMIN) DMIN = DATA(I)
             IF (DATA(I). GT. DMAX) DMAX = DATA(I)
10
       CONTINUE
       EXCLUDE TRIVIAL ERROR CASES
      DATA(N+1) = DMIN
      DATA(N+2) = 1.0
       IF (LENGTH .LE. O.O .OR. DMAX .EQ. DMIN ) RETURN
C
      RAWSF = (DMAX - DMIN) / LENGTH
       RAWSF = SFMANT * 10. ** SFEXP, WHERE 1 .LE. SFMANT .LT. 10
      SFEXP = AINT( ALOG10( RAWSF ) )
IF ( RAWSF .LT. 1.0 ) SFEXP = SFEXP - 1.0
SFMANT = RAWSF * 10.0 ** (-SFEXP)
C
       LOCATE NEXT LARGER "NICE" SCALE FACTOR
      DO 20 I=1,5
IF ( SF(I) .GT. SFMANT ) GO TO 30
20
       PRINT , " SCALE: SCALE FACTOR ERROR ... " $ RETURN
30
       SFNICE = SF(I) * 10.0 ** SFEXP
C
       COMPUTE ADJUSTED DATA MINIMUM
       ADJMIN = AINT ( DMIN / SFNICE ) * SFNICE
       IF ( ADJMIN .GT. DMIN ) ADJMIN = ADJMIN - SFNICE
       IF ( (DMAX - ADJMIN) / SFNICE .LE. LENGTH ) GO TO 40
```

```
C
       NEED TO USE THE NEXT LARGER SCALE FACTOR
       IF ( I .LT. 5 ) SFNICE = SF(I+1) * 10.0 ** SFEXP IF ( I .EQ. 5 ) SFNICE = 20.0 * 10.0 ** SFEXP ADJMIN = AINT ( DMIN / SFNICE ) * SFNICE IF ( ADJMIN .GT. DMIN) ADJMIN = ADJMIN - SFNICE
       CONTINUE
40
       DATA(N+1) = ADJMIN
       DATA(N+2) = SFNICE
       RETURN
        END
        COMPLEX FUNCTION CERF(ZZ)
        COMPLEX 2Z, Z, A, A1, A2, B, B1, B2, F, F1
        IF(CABS(Z).GE.3.)GOTO30
        J=0.
        A = Z
       B=Z
    10 J=J+1
        B=-Z*Z*CMPLX(FLOAT(2*J-1),0.)*B
B=B/CMPLX(FLOAT(J ),0.)/CMPLX(FLOAT(2*J+1),0.)
        IF(J.GE.1000)GOT050
        IF(CABS(B/A).GE.(1.E-10)) GO TO 10
        CERF=(1.128379167,0.)*A
        RETURN
    30 IF(REAL(ZZ).LT.O.)Z=-ZZ
        A2=(1.,0.)
        B2=Z
        F2=A2/B2
        A1=Z
        B1=Z*Z+(0.5,0.)
        F1=A1/B1
        J=1
    40 J=J+1
        A=Z*A1+CMPLX(FLOAT(J)/2.,0.)*A2
        B=Z#B1+CMPLX(FLOAT(J)/2.,0.)*B2
        F=A/B
        IF(J.GT.1000)GOTO 50
IF(CABS((F-F1)/F).LT.(1.E-10))GOTO60
        A2=A1
        B2=B1
        A1=A
        B1=B
        F1=F
        GOTO40
50
        WRITE(8,99)
```

```
99 FORMAT( " ERROR FUNCTION ROUTINE DID NOT CONVERGE ")

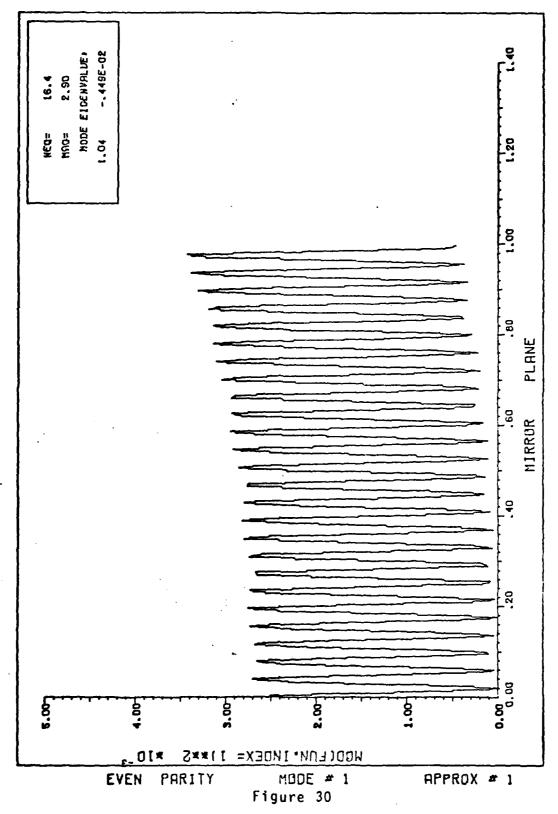
IER=1
RETURN

60 F1=(0.5,0.)*CEXP(-Z*Z)*F
CERF=1.128379167*F1
CERF=1.-CERF
IF(REAL(ZZ).LT.O.) CERF=-CERF

70 RETURN
END
COMPLEX FUNCTION FRESL(X)
COMPLEX EYE,Z,CERF
EYE=(0.,1.) $ PI=2.*ASIN(1.)
Z=SQRT(PI)*X*(1.-EYE)/2.
FRESL=(1.+EYE)/2.*CERF(Z)
FRESL=(1.+EYE)/2.*CERF(Z)
RETURN $ END
```

## Appendix E

This appendix displays plots of the intensity of the function  $\rm M_n(x)$  for n=1 through 8 , for bare resonator parameters of M=2.9 , N\_f=16.4 .



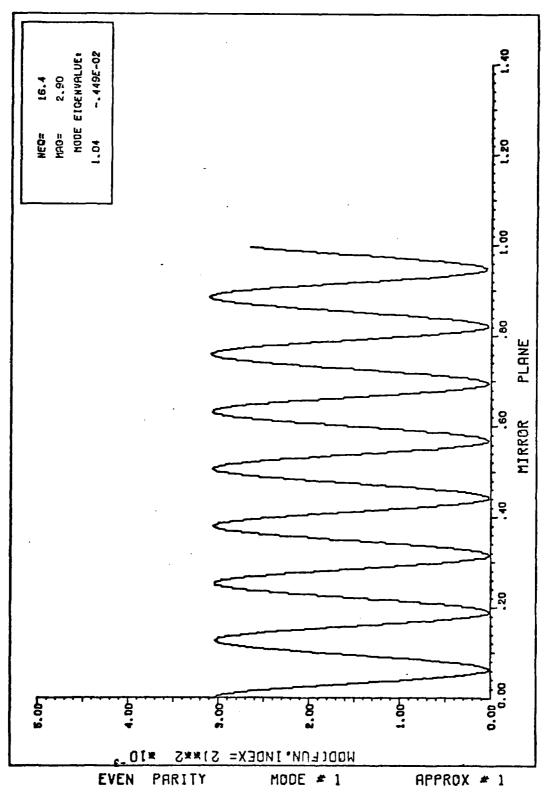
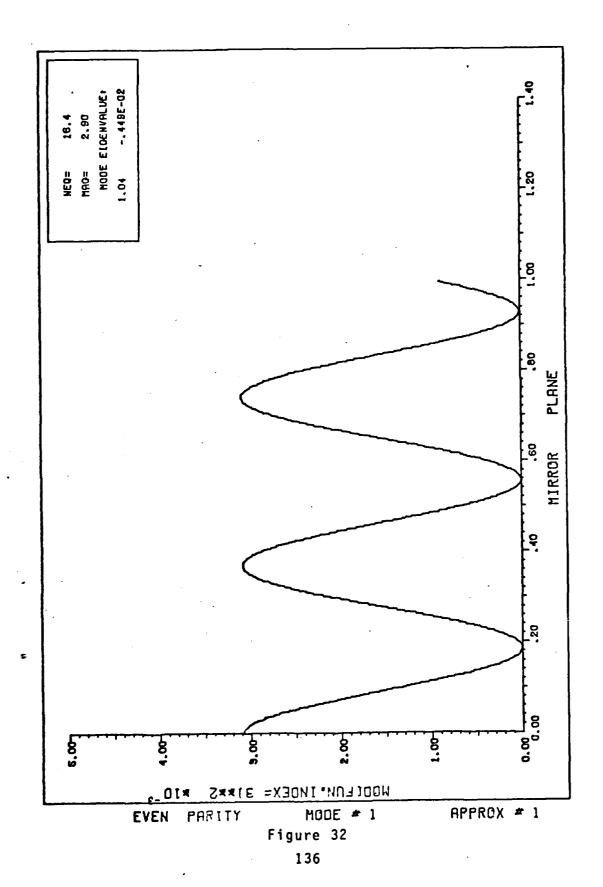


Figure 31



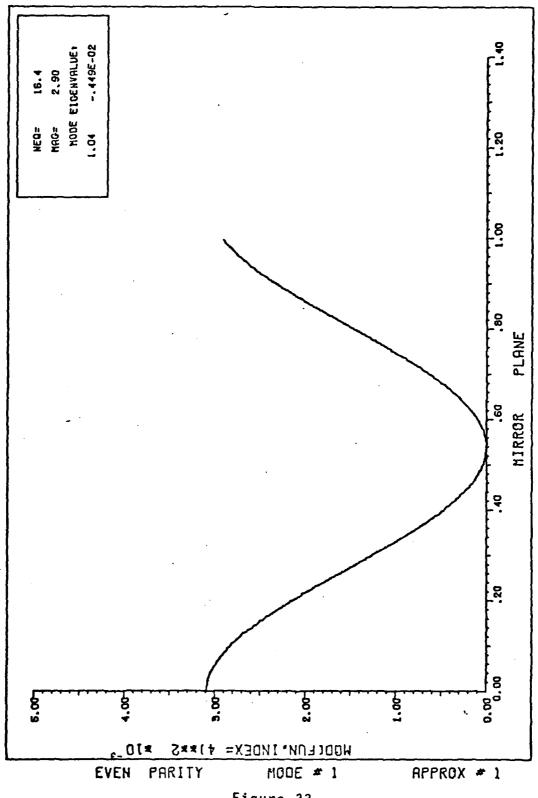


Figure 33

1

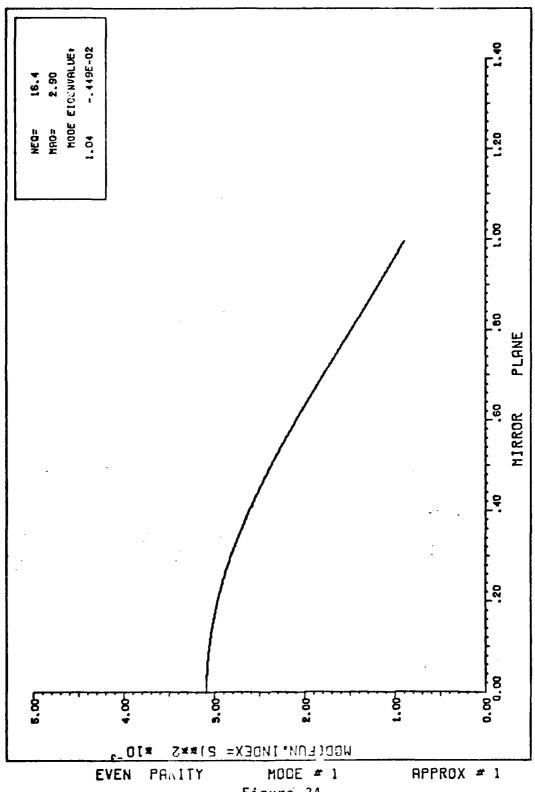


Figure 34

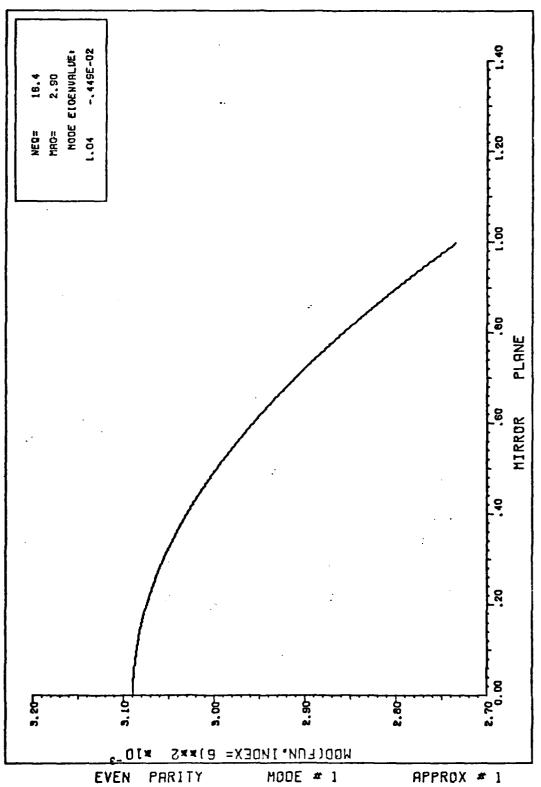
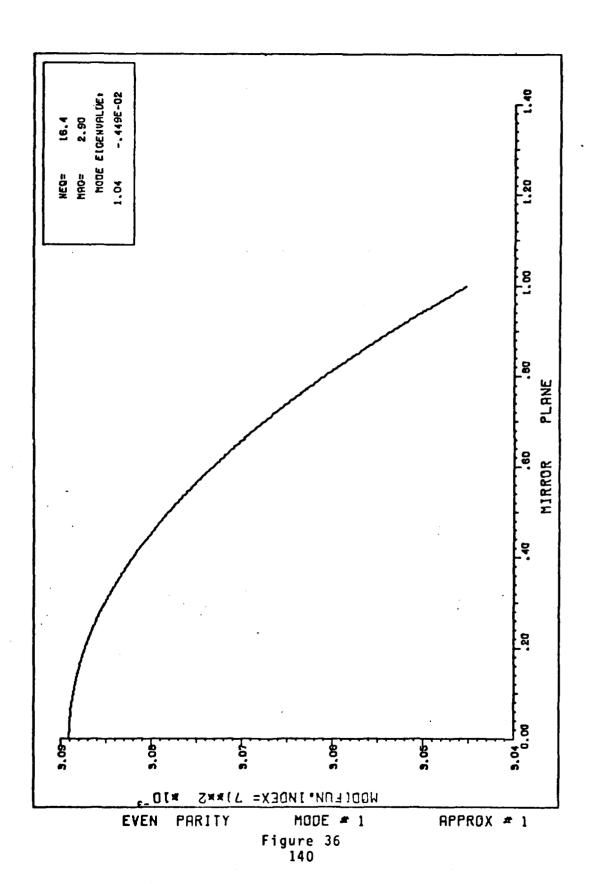


Figure 35

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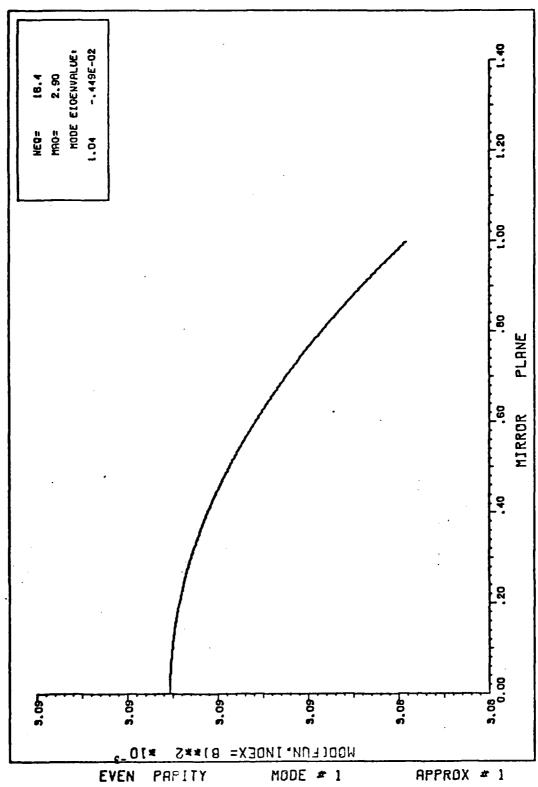


Figure 37 141

## VITA

James E. Rowley was born in Waterbury, Connecticut on 17 May 1957. He graduated from Wamogo Regional High School in Litchfield, Connecticut in June 1975. He then attended Norwich University in Northfield, Vermont from 27 August 1975 until 27 May 1979 when he graduated with a B.S. in Physics and was commissioned in the Air Force. His first active duty assignment was to the Air Force Institute of Technology at Wright-Patterson AFB.

Permanent address: Straits Turnpike Lane Morris, CT. 06763

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Asymptotic Analysis Uniform Gain	
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The mode eigenvalue equation for an unstable strip laser reson-	
ator is developed from scalar diffraction theory. The field dis-	

tributions are expressed as a series and the integral is then evaluated using a first order approximation to the method of stationary phase. The resulting approximate closed form is rearranged to form an eigenvalue polynomial, the roots of which are the mode eigenvalues. Eigenfunction expressions are then developed using sec-

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ond order approximation to the method of stationary phase. Modifications to these expressions are then made to account for the presence of uniform gain in the resonator.

presence of uniform gain in the resonator.

The results of a computer program using the derived expressions are presented. Comparisons to previously published results are made for the bare cavity case, and results for the loaded cavity case follow.

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