



EQUIVALENT GAUSSIAN MEASURES WHOSE R-N DERIVATIVE IS THE EXPONENTIAL OF

> A DIAGONAL FORM . by

Dong M./Chung and Balram S./Rajput ENTERIA 18.6. 4. University of Tennessee

Knoxville, Tennessee 37916

AMS 1970 subject classification. 60G15, 60G30.

Hart .

Key words and phrases: Gaussian process, measurable process, Radon-

Nikodým derivative.

(14 TR-1906)



(11- . 11)

[]]]]]



tab

ABSTRACT

A simple necessary and sufficient condition, on a trace-class kernel K , is given in order for the existence of a measurable (relative to the completed product σ -algebra) Gaussian process with covariance K . Using this result, sufficient conditions are given on the means and the covariances (relative to two equivalent (~) Gaussian measures P and P_{λ}) of a process X so that the Radon-Nikodým (R-N) derivative dp_{λ}/dP is the exponential of the diagonal form in X . Analogues of the last two results in the set up of Hilbert space are also proved.

Adea	lion for	Ī
ITTIS	GILALI	57
DUCI	AB	
Uncom	ouncod	
j Just I.	lication	
· · · · · ·		
. By		
Distri	butten/	
Aval	ability C	odes
•	Availand/	'01 [.]
Dist	special	
$\boldsymbol{\Lambda}$		1
n		
		····

والمرقب المحافظ والمحافظ الم

;;

1. INTRODUCTION

Let (T,T,v) be an arbitrary σ -finite measure space and K a trace-class kernel on $T \times T$. We give a simple necessary and sufficient condition on K for the existence of a measurable (relative to the completed product σ -algebra) Gaussian process with covariance K (Theorem 1).

Assume that K satisfies the condition of the above theorem, so that there exists a measurable Gaussian process X on a probability space (Ω, F, P) with covariance K. Assume, further, that the mean θ of X belongs to $L_2(v)$; then we, explicitly, evaluate $\int_{\Omega} \int_{T} \exp\{1/2 \lambda | f(t) | X^2(t, \omega) v(dt) \} P(d\omega)$, where λ is a certain number and f is a certain measurable function (Theorem 2, Corollary 2). Assume the hypotheses and notation of the previous result and let, for each λ , a function θ_{λ} on T and a covariance function K_{λ} on T × T be given; then we give sufficient conditions on θ_{λ} and K_{λ} in order that (i) θ_{λ} and K_{λ} determine a probability measure P_{λ} on (Ω, F) with respect to which X is Gaussian, (ii) $P_{\lambda} \sim P$,

and (iii) the R-N derivative dP_{λ}/dP is of the diagonal form in X; i.e., is expressible as $\int_{T} \exp \{1/2 \ \lambda | f(t) | X^{2}(t,\omega) \} v(dt)$ (Theorem 3, Corollary 2).

The results of the previous paragraph are motivated by some of the work of D. E. Varberg [7] and L. A. Shepp [6], and they are generalizations of two results of the former author and are related to similar results of the latter. We may point out that these results are central and are best possible in the sense that they are proved under minimal hypotheses on the functions θ and K (see Remark 2). Analogues of Theorem 2 and 3, in the set up of separable Hibert spaces, are also proved (Theorem 4(i) and 4(ii)).

All results are stated and discussed in Section 2 and their proofs are given in Section 3.

2. STATEMENT AND DISCUSSION OF RESULTS

We begin by stating a few definitions, notation, and conventions that will be used throughout the paper.

(A.1) (T,T,v) denote an arbitrary σ -finite measure space; whenever we write T, it is implicitly assumed that T and v are associated with it. If (Γ, A, γ) is a measure space, then \overline{A} and $L_2(\gamma)$ denote, respectively, the completion of A relative to γ and the Hilbert space of real γ -square integrable functions.

(A.2) A real, nonnegative definite, symmetric and measurable function K on T × T is called a <u>kernel</u>; if, in addition, $\int_{T} K(t, t)v(dt) < \infty$, K is called a <u>trace-class kernel</u>. Let K be a trace-class kernel, and $\{\lambda_n\}$ and $\{\phi_n\}$ be, respectively, the positive eigenvalues (including multiplicities) and the corresponding (normalized) eigenfunctions of the integral equation

(2.1) $\lambda \phi(s) = \int_{T} K(s, t) \phi(t) v(dt);$

then K is called a <u>Mercer kernel</u> (<u>M-kernel</u>⁽¹⁾ for short), if K admits the representation

(2.2)
$$K(s, t) = K_1(s, t) + K_2(s, t)$$
, s,t ε T,

where K_1 and K_2 are trace-class kernels such that $K_2(t, t) = 0$ a.e. [v], and

(2.3)
$$K_{1}(s, t) = \sum_{n=1}^{\infty} \lambda_{n} \phi_{n}(s) \phi_{n}(t) , \quad s, t \in T ,$$

where the series converges absolutely, for all s, t ε T. We note that there exist numerous examples of such kernels.

(A.3) If K denotes an M-kernel on $T \times T$, then we denote, consistently, by $\{\lambda_n\}$ and $\{\phi_n\}$, respectively, the positive eigenvalues (including multiplicities) and the corresponding (normalized) eigenfunctions of the equation (2.1), and by K_1 and K_2 the kernels related to K as in (2.2). We will assume that the set $\{\lambda_n\}$ (and hence $\{\phi_n\}$) is not finite, since it is the only case of interest here.

(A.4) We consider here only real linear spaces and real stochastic processes.

Now, we are ready to state the first result of the paper.

THEOREM 1. Let K be a trace-class kernel on $T \times T$; then we have the following:

(a) If K is an M-kernel, then there exists a $\overline{T \times F}$ -measurable Gaussian process X on some probability space (Ω, F, P) such that K is the covariance of X; further, if $K_1, K_2, \{\phi_n\}$ and $\{\lambda_n\}$ are realted to K as described in (A.3), then X can be so chosen that

$$X_t = Y_t + Z_t$$
, teT,

where Y and Z are independent Gaussian processes with covariances K_1 and K_2 , respectively, and

(2.4)
$$Y_{t} = \sum_{n=1}^{\infty} \sqrt{\lambda_{n}} \phi_{n}(t) Y_{n},$$

where I_n 's are independent N(0, 1) r.v.'s and the series converges in $L_2(P)$ and also a.s. [P], for each fixed t ε T. Finally,

(2.5)
$$Y(\cdot, \omega) = \sum_{n=1}^{\infty} \sqrt{\lambda_n} \phi_n(\cdot) Y_n(\omega)$$

where the series converges in $L_2(v)$ and also a.e. [v], for every ω outside a P-null set.

(b) Conversely, if K is the covariance function of a $\overline{T \times F}$ measurable Gaussian process X on a probability space (Ω, F, P), then K is an M-kernel.

REMARK 1. It should be noted that, for a given M-kernel, Theorem 4.1(a) guarantees the existence of a Gaussian process which has the given kernel as its covariance and is measurable relative to the <u>completed</u> product σ -algebra. The question, whether for every M-kernel K there exists a Gaussian process which has covariance K and is measurable relative to the <u>uncompleted</u> product σ -algebra, has a negative answer. (see Remark 1, [2, p. 470]).

For the statements and the proofs of some of the following results, we need a few more notation and conventions which we record in the following:

(A.5) If K denotes an M-kernel on $T \times T$ (so that, in view of (A.3), $\{\lambda_n\}$ and $\{\phi_n\}$ are, respectively, the eigenvalues and corresponding eigenfunctions of (2.1)) and θ a v-square integrable function on T, then we denote, consistently, by $\dot{\theta}$, the orthogonal projection of θ onto the space orthogonal to the $L_2(v)$ -closure of the linear space of $\{\phi_n\}$, by λ , a real number such that $1 - \lambda\lambda_n > 0$, for all n, and by θ_{λ} , and K_{λ} the functions defined as follows

(2.6)
$$\theta_{\lambda}(t) = \theta(t) + \lambda \sum_{n=1}^{\infty} \lambda_n (1 - \lambda \lambda_n)^{-1} \langle \phi_n, \theta \rangle \phi_n(t), \quad t \in \mathbb{T},$$

(2.7)
$$K_{\lambda}(s,t) = \sum_{n=1}^{\infty} \lambda_n (1 - \lambda \lambda_n)^{-1} \phi_n(s) \phi_n(t) + K_2(s,t), \quad s, t \in \mathbb{T},$$

where <,> is the inner product in $L_2(v)$ and K_2 is related to K as in (2.2). Further, we consistently use the notation $D(\lambda)$ and $W(\lambda)$, respectively, for

(2.8)
$$\prod_{n=1}^{\infty} (1 - \lambda \lambda_n)$$

and

(2.9)
$$D(\lambda)^{1/2} \exp[-1/2 \lambda \{ ||\theta||^2 + \sum_{n=1}^{\infty} (1 - \lambda \lambda_n)^{-1} \langle \phi_n, \theta \rangle^2 \}]$$

where $||\cdot||$ is the norm in $L_2(v)$. The series in (2.6) and (2.7) converge absolutely, respectively, for t ε T and s, t ε T. This follows from the boundedness of the sequence $\{(1 - \lambda \lambda_n)^{-1}\}$ (recall that $\overset{\bullet}{\Sigma} \lambda_n < \bullet$), Cauchy inequality for sequences and (2.3). Since n=1

$$\begin{split} 1 &= \lambda\lambda_n > 0 \ , \ \lambda_n > 0 \ \ \text{for all } n \ , \ \text{and} \ \ \sum_{\substack{n=1 \\ n=1}}^{\sum_{n} < \infty} \ , \ \text{we have that} \\ 0 &< D(\lambda) < 1 \ . \ \text{From this and the boundedness of the sequence} \\ \{(1 &= \lambda\lambda_n)^{-1}\} \ , \ \text{it follows that} \ \ \mathbb{W}(\lambda) \ \ \text{is a well defined positive} \\ \text{real number.} \end{split}$$

In Theorem 2 and 3 and Corollaries 1 and 2, it will be assumed that the space $L_p(v)$ is separable.

We are now ready to state the following two results.

THEOREM 2. Let K be an M-kernel on $T \times T$ and $\theta \in L_2(v)$; then there exists a $\overline{T \times F}$ -measurable Gaussian process ξ on a probability space (Ω, F, P) such that θ and K are, respectively, the mean and the covariance of ξ ; further, if λ and $W(\lambda)$ are related to θ and K as in (A.5), then

(2.10)
$$\int_{\Omega} \exp \{1/2 \lambda \int_{T} \xi^{2}(t,\omega) v(dt)\} P(d\omega) = W(\lambda)^{-1} < \infty.$$

THEOREM 3. Let K, θ , ξ and (Ω, F, P) be as in Theorem 2, and let λ , θ_{λ} , K_{λ} and $W(\lambda)$ be related to θ and K as in (A.5). Then K_{λ} is a covariance function, and there exists a probability measure P_{λ} on (Ω, F) such that ξ is Gaussian on (Ω, F, P_{λ}) with mean θ_{λ} and covariance K_{λ} , $P \sim P_{\lambda}$, and the R-N derivative $dP_{\lambda} | dP$ is given by

(2.11)
$$dP_{\lambda} | dP(\omega) = W(\lambda) \exp\{1/2 \lambda \int_{T} \xi^{2}(t,\omega)v(dt)\} \quad a.s [P].$$

REMARK 2. It is clear, from (2.10) and (2.11), that in order to obtain results similar to Theorems 2 and 3 the functions θ and K appearing in these results must guarantee the existence of the process ξ which is measurable and whose almost all paths are ν -square integrable. Since, in view of Proposition 3.4 of [5] and Theorem 1, these conditions on ξ are equivalent to the facts that K is an M-kernel and that θ is ν -square integrable, it follows that Theorems 2 and 3 are best possible, i.e., they are proved under the weakest possible hypotheses on θ and K.

In order to point out the relation between the above two theorems and the corresponding results of Varberg (Theorems 1 and 2 of [7]) and Shepp [6, p. 352], we now state two corollaries. These corollaries are, essentially, the restatements of Theorems 1 and 2; nevertheless, their inclusion is necessary in order to compare our results with the corresponding results of Shepp and Varberg.

COROLLARY 1. Let r be a kernel on $T \times T$ (see (A.2)), and ρ and f be measurable with |f(t)| > 0 on T such that (i) K(s,t) = $r(s, t)|f(s)|^{1/2}|f(t)|^{1/2}$, s, t \in T, is an M-kernel, and (ii) $\theta(t) = \rho(t)|f(t)|^{1/2}$, t \in T, is v-square integrable (both of these conditions are satisfied, for instance, when r is an M-kernel, $\rho \in L_2(v)$, and f is bounded, this follows from Theorem 1). Then there exists a $\overline{T \times F}$ -measurable Gaussian process ζ on a probability space (Ω , F, P) such that ρ and r are, respectively, the mean and the covariance of ζ . Further, if λ and $W(\lambda)$ are related to θ and K as in (A.5), then

7

A CONTRACTOR OF THE OWNER OF THE OWNER

(2.12)
$$\int_{\Omega} \exp\{1/2\lambda \int_{T} |f(t)| \zeta^{2}(t,\omega) v(dt)\} P(d\omega) = W(\lambda)^{-1}.$$

COROLLARY 2. Let r, ρ , f, K and θ be as in Corollary 1 and let ζ and (Ω, F, P)

be as obtained in Corollary 1 and let λ , θ_{λ} , K_{λ} and $W(\lambda)$ be related to θ and K as in (A.5). Then there exists a probability measure P_{λ} on (Ω , F) such that ζ is Gaussian on (Ω , F, P_{λ}) with mean $|f(t)|^{-1/2} \theta_{\lambda}(t)$, $t \in T$, and covariance $|f(s)|^{-1/2} |f(t)|^{-1/2} K_{\lambda}(s,t)$, $s, t \in T$, $P_{\lambda} \sim P$, and the R-N derivative $dP_{\lambda}|dP$ is given by

(2.13)
$$dP_{\lambda}/dP(\omega) = W(\lambda) \exp\{1/2 \lambda \int_{m} |f(t)| \zeta^{2}(t,\omega)v(dt)\} \quad a.s. [P].$$

REMARK 3. If T = [a, b], T = the class of Borel subsets of T, v = the Lebesgue measure, and if r is a continuous kernel on $T \times T$, then, by Mercer's theorem, r is an M-kernel on $T \times T$. Now if f is any bounded measurable function on T, then, as indicated in Corollary 1, $r(s, t) |f(s)|^{1/2} |f(t)|^{1/2}$, $s, t \in T$, is an M-kernel. From this it is now clear that Theorem 1 and Theorem 2 of Varberg [7] are special cases, respectively, of Corollary 1 and Corollary 2. These corollaries are also related to two results of Shepp that are given on pp. 350 and 352 of [6].

We shall now state two more results (Theorems 4(i) and 4(ii)). Theorem 4(i) is important in that it is needed for the proofs of Theorem 2. Theorem 4 (iii) is included here to show that the analogue of Theorem 3 can be forumated for Gaussian measures defined on <u>abstract</u> separable Hilbert spaces.

8

14 million and the

A CARLENCE AND A CARL

We assume that the reader is familiar with the elementary properties of Gaussian measures in separable Hilbert spaces.

In the following theorem, H and B(H) denote, respectively, a separable Hilbert space and the σ -algebra generated by open sets of H; and <,> and $||\cdot||$ denote, respectively, the inner product and the norm in H.

THEOREM 4. Let μ be a Gaussian measure on (H, B(H)) with mean m and covariance operator S. Denote by $\{\delta_n\}$ and $\{\psi_n\}$, the positive eigenvalues (including multiplicities) and the corresponding normalized eigenvectors of S, by δ , a real number such that $\delta\delta_n < 1$, for all n, and, by m, the orthogonal projection of m onto the space orthogonal to the closed linear space generated by $\{\psi_n\}$. Define

$$S_{\delta}(\mathbf{x}) = \sum_{n=1}^{\infty} \delta_n (1 - \delta \delta_n)^{-1} \langle \psi_n, \mathbf{x} \rangle \psi_n, \mathbf{x} \in \mathbb{H},$$
$$m_{\delta} = m + \delta S_{\delta}(m),$$

and

$$U(\delta) = \left[\prod_{n=1}^{\infty} (1 - \delta\delta_n)\right]^{1/2} \exp\left[-\frac{1}{2} \delta\left\{\left\|\frac{1}{n}\right\|^2 + \prod_{n=1}^{\infty} (1 - \delta\delta_n)^{-1} \langle \psi_n, m \rangle^2\right\}\right]$$

deserver and a

The second in the second second

Then we have

(i)
$$\int_{H} \exp \frac{1}{2} \delta ||\mathbf{x}||^{2} \mu(d\mathbf{x})$$

(2.14) $= \left[\prod_{n=1}^{\infty} (1 - \delta \delta_{n}) \right]^{-1/2} \exp[\frac{1}{2} \delta \{ ||\mathbf{m}||^{2} + \prod_{n=1}^{\infty} (1 - \delta \delta_{n})^{-1} \langle \psi_{n}, \mathbf{m} \rangle^{2} \}]$
 $= U(\delta)^{-1} \langle \mathbf{n} \rangle$

(ii) if μ_{δ} is the Gaussian measure⁽²⁾ on (H, B(H)) with mean m_{δ} and covariance operator S_{δ} , then $\mu_{\delta} \sim \mu$, and the R-N derivative $d\mu_{\delta}/d\mu$ is given by

(2.15)
$$d\mu_{\delta}/d\mu(\mathbf{x}) = U(\delta) \exp\{1/2 \delta ||\mathbf{x}||^2\}$$
, a.s. $[\mu]$,

where $U(\delta)$ is as in (i).

3. PROOFS

<u>Proof of Theorem 1(a)</u>. For clarity, we devide our proof into three parts. In parts (i) and (ii), two auxilary processes Y^1 and Z^1 are defined; and, in part (iii), these are used to construct the required process X.

(i) There exists a $\overline{T \times F_1}$ -measurable Gaussian process Y^1 with covariance K_1 defined on a probability space (Ω_1, F_1, P_1) . Further, Y^1 can be so chosen that, for every fixed t εT ,

$$Y_t^l = \sum_{n=l}^{\infty} \sqrt{\lambda_n} \phi_n(t) Y_n^l$$
,

where the series converges in $L_2(P_1)$ and also a.s. $[P_1]$, and Y_n^1 's are independent N(0, 1) r.v.'s on (Ω_1, F_1, P_1) . Further

$$\Upsilon^{\mathbb{I}}(\cdot,\omega) = \sum_{n=1}^{\infty} \sqrt{\lambda_n} \phi_n(\cdot) \Upsilon^{\mathbb{I}}_n(\omega) ,$$

10

where the series converges in $L_2(v)$ and a.e. [v], for every ω outside a P_1 -null set.

<u>Proof of (i)</u>. Let $\{Y_n^l\}$ be a sequence of independent N(0, 1)r.v.'s defined on a probability space (Ω_1, F_1, P_1) . We now define two processes ξ and ζ in terms of λ_n 's, ϕ_n 's and Y_n^l 's, and then define the required process Y^l in terms of ξ and ζ .

We first define the process ξ . For each n , let

 $\psi_{n}(t,\omega) = \sqrt{\lambda_{n}} \phi_{n}(t) Y_{n}^{1}(\omega) , (t,\omega) \in T \times \Omega_{1}$

Since $\Sigma = \lambda_j < \infty$ and $\langle \psi_n, \psi_m \rangle = L_2(v \times P_1) = \sqrt{\lambda_n} = \delta_{n,m}$

(δ is the Kronecker δ), it follows that n_{m}

$$|| \sum_{j=n}^{m} \psi_{j} ||^{2} = \sum_{\substack{j=n \\ L_{2}(v \times P_{1})}}^{m} j \neq 0$$

as n, $m \neq \infty$. Thus, $\{ \Sigma \ \psi_j \}$ converges in $L_2(v \times P_1)$; and, so, j=1 i_k there exists a subsequence $\{ \Sigma \ \psi_j \}$ which converges pointwise off j=1

a $v \times P_1$ -null set A. Define

$$\xi(t,\omega) = \begin{cases} \lim_{k} \int_{j=1}^{n_{k}} \psi_{j}(t,\omega) & \text{off } A \\ 0 & \text{on } A \end{cases};$$

then, clearly, ξ is $T \times F_1$ -measurable. Further, by Fubini's Theorem, there exists a v-null set T_1 such that, for every fixed t $\notin T_1$,

and the second second

the set $A_t \equiv \{\omega: (t,\omega) \in A\}$ has P_1 -measure zero, and, for every $\omega \notin A_t$,

$$\xi(t,\omega) = \lim_{k \to 0} \Sigma \psi_j(t,\omega) .$$

$$k = 1$$

Now we define the process ζ . Since for every fixed t ε T, $\sum_{n=1}^{\infty} \lambda_n \phi_n^2(t) < \infty$ (see (2.3)) and Y_n^1 's are independent mean 0 variance 1 r.v.'s, $\sum_{n=1}^{\infty} \sqrt{\lambda_n} \phi_n(t) Y_n^1$ converges in $L_2(P_1)$ and also pointwise off a P_1 -null set B_t , for each t ε T [4, p. 147]. For each t ε T, define

$$\zeta_{t}(\omega) = \begin{cases} \lim_{n \to \infty} \sum_{j=1}^{n} \lambda_{j} \phi_{j}(t) Y_{j}^{1}(\omega), & \text{if } \omega \in B_{t}^{c} \\ 0, & \text{if } \omega \in B_{t} \end{cases},$$

where B_t^c denotes the complement of B_t . Clearly, if $t \in T_1^c$, then $P_1(A_t^c \bigcap B_t^c) = 1$; further, if $\omega \in A_t^c \bigcap B_t^c$, then, since $\{ \underbrace{\sum_{j=1}^{r} \psi_j(t, \omega) }\}$ is a subsequence of

n $\{\sum_{j=1}^{n}\psi_{j}(t,\omega)\}\$, $\xi(t,\omega) = \zeta(t,\omega)$. Thus, for every $t \in T_{1}^{c}$,

(3.1) $\xi_t = \zeta_t$ **a.s.** $[P_1]$.

Finally, define

(3.2)
$$Y^{1}(t,\omega) = \begin{cases} \xi(t,\omega) & \text{if } (t,\omega) \in T_{1} \times \Omega_{1} \\ \\ \zeta(t,\omega) & \text{if } (t,\omega) \in T_{1}^{c} \times \Omega_{1} \end{cases}$$

12

State State

We now show that Y^1 is a required process.

Since, from (3.2), the set $\{(t, \omega): Y^{1}(t, \omega) \neq \xi(t, \omega)\}$ is contained in $v \times P_{1}$ -null set $T_{1} \times \Omega_{1}$, and since ξ is shown $T \times F_{1}$ -measurable, it follows that Y^{1} is $\overline{T \times F_{1}}$ -measurable. Since, as shown above, the series $\sum_{n=1}^{\infty} \sqrt{\lambda_{n}} \phi_{n}(t) Y_{n}^{1}$ converges to ζ_{t} in $L_{2}(P_{1})$ and also a.s. $[P_{1}]$, for each fixed $t \in T$, and since, from (3.1) and (3.2), $Y_{t}^{1} = \zeta_{t}$ a.s. $[P_{1}]$, for each $t \in T$, we have that $\sum_{n=1}^{\infty} \sqrt{\lambda_{n}} \phi_{n}(t) Y_{n}^{1}$ converges to Y_{t}^{1} in $L_{2}(P_{1})$ and also a.s. $[P_{1}]$, for each $t \in T$. Also, from $L_{2}(P_{1})$ convergence of the series to Y_{t}^{1} , $t \in T$, we have that Y^{1} is Gaussian (recall that Y_{n}^{1} 's are Gaussian) and that the covariance of Y^{1} is $K_{1}(s,t) = \sum_{n=1}^{\infty} \lambda_{n} \phi_{n}(s) \phi_{n}(t)$, s, $t \in T$, where $\sum_{n=1}^{\infty} \lambda_{n} \phi_{n}(s) \phi_{n}(t)$ converges absolutely for s, $t \in T$.

To complete the proof of (i), it remains to prove that $\sum_{n=1}^{\Sigma} \sqrt{\lambda} \phi_n(\cdot) Y_n^{\dagger}(\omega)$ converges to $Y^1(\cdot, \omega)$ in $L_2(v)$ and a.e. [v], for almost all ω . Since, for t ε T, $\sum_{n=1}^{\Sigma} \sqrt{\lambda_n} \phi_n(t) Y_n^{\dagger}$ is shown to converge to Y_t^{\dagger} a.s. $[P_1]$, we have, by an application of Fubini's theorem, that $\sum_{n=1}^{\Sigma} \sqrt{\lambda_n} \phi_n(\cdot) Y_n^{\dagger}(\omega)$ converges to $Y^1(\cdot, \omega)$ a.e. [v], for almost all ω . Now we show the $L_2(v)$ convergence of $\sum_{n=1}^{\Sigma} \sqrt{\lambda_n} \phi_n(\cdot) Y_n^{\dagger}(\omega)$ to $Y^1(\cdot, \omega)$ a.e. $[P_1]$. Since

 $\int_{\Omega} \{ \sum_{n=1}^{\infty} \lambda_n (Y_n^1)^2 \} \mathbb{P}_1(d\omega) = \sum_{n=1}^{\infty} \lambda_n < \infty$

we have that $\sum_{n=1}^{\infty} \lambda_n (Y_n^{\perp}(\omega))^2 < \infty$ a.s. $[P_1]$. Therefore,

$$\int_{\mathbf{T}} \left[\underbrace{\mathbf{\Sigma}}_{n}^{\mathbf{m}} \sqrt{\lambda_{j}} \phi_{j}(t) \mathbf{Y}_{n}^{1}(\omega) \right]^{2} v(dt) = \underbrace{\mathbf{\Sigma}}_{j \leq n}^{\mathbf{m}} \lambda_{j} (\mathbf{Y}_{j}^{1}(\omega))^{2} + 0$$

13

a.s. $[P_1]$ as $n, m \neq \infty$; considuently, $\sum_{n=1}^{\infty} \sqrt{\lambda_n} \phi_n Y_n^1(\omega)$ converges in $L_2(\nu)$, a.s. $[P_1]$. Now using the fact that $L_2(\nu)$ convergence implies the existence of a subsequence that converges to the same function a.e. $[\nu]$ and the fact that $\sum_{n=1}^{\infty} \sqrt{\lambda_n} \phi_n Y_n^1(\omega)$ converges to $Y^1(\cdot,\omega)$ a.e. $[\nu]$, for almost all ω , we have that $\sum_{n=1}^{\infty} \sqrt{\lambda_n} \phi_n Y_n^1(\omega)$ converges to $Y^1(\cdot,\omega)$ in $L_2(\nu)$, for almost all ω . The proof of (i) is now complete.

(ii) There exists a $T \times F$ -measurable Gaussian process Z^1 with covariance K_2 defined on some probability space (Ω_2, F_2, P_2) .

<u>Proof of (ii)</u>. By Kolmogorov's existence theorem, there exists a Gaussian process n with covariance K_2 defined on some probability space (Ω_2, F_2, P_2) . Let T_2 be the v-null set of T such that $K_2(t,t) = 0$ off T_2 . Define

$$Z^{\perp}(t,\omega) = n(t,\omega) \chi_{T_{2}} \times \Omega_{2}^{(t,\omega)},$$

where $\chi_{T_2} \times \Omega_2$ is the indicator of $T_2 \times \Omega_2$. Then, clearly, Z^1 is Gaussian with covariance K_2 ; further, since $Z^1(t,\omega) = 0$ a.e. $[v \times P_2]$, Z^1 is $\overline{T \times F_2}$ -measurable.

(3.3) $X_{t} = Y_{t} + Z_{t}, t \in T;$

then the processes X, Y, Z and the r.v.'s Y_n 's satisfy the required properties of Theorem 1(a).

<u>Proof of (iii)</u>. It is clear that Π_j is measurable from $(\Omega, \overline{T \times F})$ onto $(T \times \Omega_j, \overline{T \times F_j}), j = 1, 2$. Therefore, since by (i) and (ii) Υ^1 and Z^1 are $\overline{T \times F_1}$ and $\overline{T \times F_2}$ -measurable, respectively, Υ and Z are $\overline{T \times F}$ -measurable. The rest of the proof follows from (i) and (ii) and the observation that for any $t_1, \ldots, t_n, s_1, \ldots, s_m \in T$ and any $A \in \mathcal{B}(\mathbb{R}^n), B \in \mathcal{B}(\mathbb{R}^m)$, $\mathbb{P}\{(\Upsilon_{t_1}, \ldots, \Upsilon_{t_n}) \in A, (Z_{s_1}, \ldots, Z_{s_m}) \in B\} = \mathbb{P}_1\{(\Upsilon_{t_1}^1, \ldots, \Upsilon_{t_n}^1) \in A\}.$ $\mathbb{P}_2\{(Z_{s_1}^1, \ldots, Z_{s_m}^1) \in B\}$, where $\mathcal{B}(\mathbb{R}^k)$ is the class of Borel subsets of the k-Euclidian space \mathbb{R}^k . We omit the details.

<u>Proof of Theorem 1(b)</u>: This follows from Theorem 1 of [1] due to S. Cambanis.

<u>Proof of Theorem 2</u>. Let X be the Guassian process on (Ω, F, P) as constructed in Theorem 1(a) subject to the additional condition that $E(X_t) = 0$, t ε T. Note that, as follows from the proof of Theorem 1, this additional condition is satisfied by X if we choose the process Z^1 in the proof of Theorem 1(a) to have zero mean. Let

(3.4) $\xi_{+} = X_{+} + \theta(t)$, $t \in T$;

then, clearly, ξ is a $\overline{T \times F}$ -measurable Gaussian process with mean θ and covariance K.

Since $\int_{\mathbf{T}} K(t, t) v(dt) < \bullet$ and $\theta \in L_2(v)$, $\xi(\cdot, \omega) \in L_2(v)$ a.s. [P], and since $L_2(v)$ is assumed separable, ξ induces a Gaussian

measure μ on $L_2(\nu)$ via the map $\omega \mid \neq \xi(\cdot, \omega)$ if $\xi(\cdot, \omega) \in L_2(\nu)$, $\omega \mid \neq 0$ if $\xi(\cdot, \omega) \notin L_2(\nu)$ [5, Theorem 3.2]. For each $f \in L_2(\nu)$, define (pointwise)

$$S(f)(s) = \int_{\pi} K(s, t)f(t)v(dt) .$$

Then it follows from Lemma 3.2 and Proposition 3.5 of [5]; that θ and the operator S are, respectively, the mean and covariance operator of μ . Further, it is clear from the definition of S that its eigenvalues and corresponding eigenvectors, are respectively $\{\lambda_n\}$ and $\{\phi_n\}$ (see (A.3)). The proof of (2.10) now follows from Theorem 4(i), the above observations, and the following equation

$$\int_{\Omega} \exp\{\frac{1}{2} \lambda \int_{T} \xi^{2}(t,\omega) v(dt)\} P(d\omega) = \int_{L_{2}}(v) \exp\{\frac{1}{2} \lambda \int_{T} x^{2}(t) v(dt)\} u(dx),$$

which is a direct consequence of the change of variable formula [3, p. 163].

<u>Proof of Theorem 3</u>. Define, for every B ε F,

(3.5)
$$P_{\lambda}(B) = W(\lambda) \int_{B} \exp\{1/2 \lambda \int_{m} \xi^{2}(t, \omega) v(dt)\} P(d\omega),$$

then it is clear, from (2.10), that P_{λ} is a probability measure on (Ω ,F), and, from (3.5), that $P_{\lambda} \sim P$ with the R-N derivative dP_{λ}/dP equal to the right side of (2.11) a.s. [P]. Thus, the proof

of Theorem 3 will be complete, if we can show that ξ is Gaussian with mean θ_{λ} and covariance K_{λ} . We prove this in the following by showing that $E_{\lambda}[\exp\{i \int_{j=1}^{n} s_{j} \xi_{t_{j}}\}]$ is the right n-dimensional characteristic function, where E_{λ} is the expectation relative to P_{λ} , and s_{1}, \ldots, s_{n} and t_{1}, \ldots, t_{n} are arbitrary elements of R and T, respectively.

Recall that $\xi_t = Y_t + Z_t + \theta(t)$, $t \in T$, (see (3.3) and (3.4)), and that $\sum_{n=1}^{\infty} \sqrt{\lambda_n} \phi_n(\cdot) Y_n(\omega)$ converges to $Y(\cdot, \omega)$ in $L_2(\nu)$ a.s. [P] (see (2.5)). Using these, the independence of the families $\{Y_t: t \in T\}$, $\{Z_t: t \in T\}$ and the facts $E(Y_t) =$ $E(Z_t) = 0$, $t \in T$, and $E(Z_t^2) = 0$ a.e. $[\nu]$, we have

(3.6)
$$\int_{\mathbf{T}} \xi^{2}(\mathbf{t}, \omega) v(d\mathbf{t}) = \sum_{n=1}^{\infty} \lambda_{n} Y_{n}^{2}(\omega) + 2 \sum_{n=1}^{\infty} \sqrt{\lambda_{n}} \langle \phi_{n}, \theta \rangle Y_{n}(\omega) + ||\theta||^{2} \text{ a.s. [P]}.$$

Using (3.5) and (3.6), we have

$$E_{\lambda}[\exp \{i \int_{j=1}^{\infty} s_{j} \varepsilon_{t_{j}}\}]$$

$$= W(\lambda)E[\exp\{i \int_{j=1}^{m} s_{j} \varepsilon_{t_{j}} + 1/2 \lambda \int_{T} \varepsilon^{2}(t,\omega)v(dt)\}]$$

$$(3.7) = W(\lambda) E[\exp\{i \int_{j=1}^{m} s_{j} \varepsilon_{t_{j}}\}$$

$$\times \exp\{1/2 \lambda (\sum_{n=1}^{\infty} \lambda_{n} Y_{n}^{2} + 2 \sum_{n=1}^{\infty} \sqrt{\lambda_{n}} <\phi_{n}, 0 > Y_{n} + ||0||^{2})\}]$$

Noting again that $\xi_t = Y_t + Z_t + \theta(t)$, $t \in T$, and that $\sum_{n=1}^{\infty} \sqrt{\lambda_n} \epsilon_n(t) Y_n$ converges to Y_t a.s. [P] (see(2.4)), the right side of (3.7) is

17

Contraction of the second

$$= W(\lambda)E\left[\lim_{k} \left[\exp\left(i \int_{j=1}^{m} s_{j}\left(\sum_{n=1}^{k} \sqrt{\lambda_{n}} \phi_{n}(t_{j}) Y_{n} + Z_{t_{j}} + \theta(t_{j})\right)\right)\right] \\ \times \exp\left(\frac{1}{2} \lambda \left(\sum_{n=1}^{k} \lambda_{n} Y_{n}^{2} + 2 \sum_{n=1}^{k} \sqrt{\lambda_{n}} <\phi_{n}, \theta > Y_{n} + ||\theta||^{2}\right)\right)\right] \\ = W(\lambda)E\left[\lim_{k} \sum_{n=1}^{m} \left[\exp\left(i Y_{n}\left(\sqrt{\lambda_{n}} \int_{j=1}^{m} s_{j} \phi_{n}(t_{j}) - i\lambda \sqrt{\lambda_{n}} <\phi_{n}, \theta >\right) + 1/2 \lambda\lambda_{n}Y_{n}^{2}\right)\right] \\ \times \exp\left(i \int_{j=1}^{m} s_{j}\left(Z_{t_{j}} + \theta(t_{j})\right) + 1/2 \lambda ||\theta||^{2}\right)\right],$$

which, by the dominated convergence theorem, is

(3.8)
$$= W(\lambda) \lim_{k} E \left[\prod_{n=1}^{k} \left[\exp\{i Y_n B_n + 1/2 \lambda \lambda_n Y_n^2 \} \right] \right]$$

× exp {
$$i \int_{j=1}^{m} s_j (Z_{t_j} + \vartheta(t_j)) + 1/2 \lambda ||\theta||^2 \}],$$

where

(3.9)
$$B_{n} = \sqrt{\lambda_{n}} \sum_{j=1}^{n} s_{j} \phi_{n}(t_{j}) - i\lambda \sqrt{\lambda_{n}} \langle \phi_{n}, \theta \rangle$$

Now using the independence of the r.v.'s Y_n 's and the independence of the two families $\{Y_n: n = 1, 2, ...\}$, $\{Z_t: t = T\}$ and recalling that

$$E[\exp\{i Y_n B_n + 1/2 \lambda \lambda_n Y_n^2\}] = (1 - \lambda \lambda_n)^{-1/2} \exp\{-1/2 B_n^2 (1 - \lambda \lambda_n)^{-1}\},$$

it follows that the expression in (3.8) is

18

THE REAL PROPERTY OF

$$(3.10) = W(\lambda) D(\lambda)^{-1/2} \exp \{-1/2 \sum_{n=1}^{\infty} (1 - \lambda \lambda_n)^{-1} B_n^2 \}$$

$$\times \exp\{i \sum_{j=1}^{m} s_j \theta(t_j) - 1/2 \sum_{j=1}^{m} \sum_{k=1}^{m} s_j s_k K_2(t_j, t_k) \}$$

$$\times \exp\{1/2 \lambda ||\theta||^2\}.$$

Subsituting the value of B_n from (3.9) in (3.10) and observing that $\||\theta|\|^2 = \sum_{n=1}^{\infty} \langle \phi_n, \theta \rangle^2 + \||\theta\|\|^2$ (see (A.5)), we see that the expression in (3.10) is

$$(3.11) = W(\lambda) D(\lambda)^{-1/2} \exp \left[i \int_{j=1}^{m} s_{j} \{\theta(t_{j}) + \sum_{n=1}^{\infty} \lambda \lambda_{n} (1 - \lambda \lambda_{n})^{-1} \phi_{n}(t_{j}) \langle \phi_{n}, \theta \rangle \} \right]$$

$$\times \exp \left[-1/2 \int_{j=1}^{m} \sum_{k=1}^{m} s_{j} s_{k} \{K_{2}(t_{j}, t_{k}) + \sum_{n=1}^{\infty} \lambda_{n} (1 - \lambda \lambda_{n})^{-1} \phi_{n}(t_{j}) \phi_{n}(t_{k}) \} \right]$$

$$\times \exp \left[1/2 \lambda \{ ||\dot{\theta}||^{2} + \sum_{n=1}^{\infty} (1 - \lambda \lambda_{n})^{-1} \langle \phi_{n}, \theta \rangle^{2} \} \right],$$

which, in view of (2.6) - (2.8), is

$$= W(\lambda) D(\lambda)^{-1/2} \exp\{i \int_{j=1}^{m} s_{j}\theta_{\lambda}(t_{j}) - 1/2 \int_{j=1}^{m} \frac{m}{k=1} s_{j}s_{k} K_{\lambda}(t_{j}, t_{k})\}$$

$$\times \exp\left[1/2 \lambda\{||\theta||^{2} + \int_{n=1}^{\infty} (1 - \lambda\lambda_{n})^{-1} \langle \phi_{n}, \theta \rangle^{2}\}\right]$$

$$= W(\lambda) W(\lambda)^{-1} \exp\{i \int_{j=1}^{m} s_{j}\theta_{\lambda}(t_{j}) - 1/2 \int_{j=1}^{m} \frac{m}{k=1} s_{j}s_{k} K_{\lambda}(t_{j}, t_{k})\},$$

by the definition of $W(\lambda)$ (see (2.9)). Thus,

$$\mathcal{E}_{\lambda}[\exp \{i \int_{j=1}^{m} s_{j} \xi_{t_{j}}\}] = \exp\{i \int_{j=1}^{m} s_{j} \theta_{\lambda}(t_{j}) - 1/2 \int_{j=1}^{m} k_{j} s_{k} K_{\lambda}(t_{j}, t_{k})\},$$

as desired.

<u>Proof of Corollary 1</u>. Since K is an M-kernel and $\theta \in L_2(\nu)$, there exists, by Theorem 2, a $\overline{T \times F}$ -measurable Gaussian process ξ on a probability space (Ω, F, P) with mean θ and covariance K. Let $\zeta_t = |f(t)|^{-1/2} \xi_t$, $t \in T$; then, clearly, ζ is $\overline{T \times F}$ -measurable and Gaussian with mean ρ and covariance r; further, the proof of (2.12) follows immediately from (2.10).

<u>Proof of Corollary 2</u>. Define P_{λ} as in (3.5) replacing ξ_t by $|\mathbf{f}(t)|^{1/2} \zeta_t$. Then by (2.12), P_{λ} is a probability measure, and, by the definition of P_{λ} , $P_{\lambda} \sim P$ with the R-N derivative dP_{λ}/dP equal to the right side of (2.13) a.s. [P]. Since the process ξ of Theorem 3 is related to ζ by $\xi_t = |\mathbf{f}(t)|^{1/2} \zeta_t$ and since it is shown to be Gaussian on (Ω, F, P_{λ}) with mean θ_{λ} and covariance K_{λ} , it follows that ζ is Gaussian on (Ω, F, P_{λ}) with mean $|\mathbf{f}(t)|^{-1/2} \theta_{\lambda}(t), t \in T$, and covariance $|\mathbf{f}(s)|^{-1/2} |\mathbf{f}(t)|^{-1/2} K_{\lambda}(s, t)$ s, $t \in T$.

<u>Proof of Theorem 4(i)</u>: Choose an orthonormal set $\{\psi_k^i: k = 1, 2, \dots, l\}$ of H so that $\{\psi_n\} \bigcup \{\psi_k^i\}$ is a Hilbert basis of H, where l is finite or $+\infty$. It follows that $\{\psi_n\} \bigcup \{\psi_k^i\}$ is a family of independent r.v.'s on (H, B(H), μ), that ψ_k^i 's are degenerate at $\langle \psi_k^i, m \rangle$ and that ψ_n 's are Gaussian with mean $\langle \phi_n, m \rangle$ and variance δ_n . Using these facts, Parseval's relation and the monotone convergence theorem, we have

$$e^{1/2\delta ||\mathbf{x}||^{2}} u(d\mathbf{x}) = \int_{\mathbf{h}} \exp\{1/2\delta(\int_{\mathbf{j}}^{\infty} \frac{1}{2} \langle \psi_{\mathbf{j}}, \mathbf{x} \rangle^{2} + \int_{\mathbf{j}}^{\infty} \frac{1}{2} \langle \psi_{\mathbf{j}}, \mathbf{x} \rangle^{2}) u(d\mathbf{x})$$

$$= \lim_{n} (\int_{\mathbf{H}} \exp\{1/2 \delta \int_{\mathbf{j}}^{\frac{n}{2}} \langle \psi_{\mathbf{j}}, \mathbf{x} \rangle^{2} u(d\mathbf{x}) \}$$

$$\times (\int_{\mathbf{H}} \exp\{1/2 \delta \int_{\mathbf{j}}^{\frac{n}{2}} \langle \psi_{\mathbf{j}}, \mathbf{x} \rangle^{2} u(d\mathbf{x}) \}$$

$$= \lim_{n} (\int_{\mathbf{j}}^{\frac{n}{2}} \int_{\mathbf{H}} \exp\{1/2 \delta \langle \psi_{\mathbf{j}}, \mathbf{x} \rangle^{2}) u(d\mathbf{x}) \}$$

$$= \lim_{n} (\int_{\mathbf{j}}^{\frac{n}{2}} \int_{\mathbf{H}} \exp\{1/2 \delta \langle \psi_{\mathbf{j}}, \mathbf{x} \rangle^{2}) u(d\mathbf{x}) \}$$

$$= \lim_{n} (\int_{\mathbf{j}}^{\frac{n}{2}} (1 - \delta\delta_{\mathbf{j}})^{-1/2} \exp\{1/2 \delta \langle \psi_{\mathbf{j}}, \mathbf{x} \rangle^{2}) u(d\mathbf{x}) \}$$

$$= \lim_{n} (\int_{\mathbf{j}}^{\frac{n}{2}} (1 - \delta\delta_{\mathbf{j}})^{-1/2} \exp\{1/2 \delta \int_{\mathbf{j}}^{\frac{n}{2}} \langle \psi_{\mathbf{j}}, \mathbf{x} \rangle^{2} (1 - \delta\delta_{\mathbf{j}})^{-1} \}]$$

$$= u(\delta)^{-1} \langle \phi \rangle .$$

<u>Proof of Theorem 4(ii)</u>. Define, for every $B \in B(H)$,

(3.12) $P_{\delta}(B) = U(\delta) \int_{B} \exp \{1/2 \delta ||x||^2\} \mu(dx)$,

 $\int_{\mathbb{H}}$

then it is clear, from (2.14), that P_{λ} is a probability measure on (H, B(H)), and, from (3.12), that $\mu \sim P_{\delta}$ with the R-N derivative $dP_{\delta}/d\mu$ equal to right side of (2.15) a.s. [μ]. Let x be a fixed element of H, then, using arguments similar to the ones used in the

proof of Theorem 3, it can be shown that

$$\int_{H} \exp\{i\langle x, y \rangle\} P_{\delta}(dy) = \exp\{i\langle x, \theta_{\delta} \rangle - 1/2 \langle x, S_{\delta} x \rangle\}$$

This shows that P_{δ} is Gaussian on H with mean θ_{δ} and covariance operator S_{δ} . Therefore, since in a separable Hilbert space the mean and the covariance operator determine the Gaussian measure uniquely (see, for example, [5, p. 399]), it follows that $P_{\delta} = \mu_{\delta}$. The proof is now complete.

22

REFERENCES

- Cambanis, S. (1973). Representation of stochastic processes of second order and linear operations, J. Math. Anal. App. <u>41</u>, 603-620.
- [2] Cambanis, S. (1975). The measurability of a stochastic process of second order and its linear space, Proc. Amer. Math. Soc., <u>47</u>, 467-475.
- [3] Halmos, P. R. (1950). Measure Theory. Van Nostrand, Princeton, N. J.
- [4] Neveu, J. (1965). Mathematical Foundations of the Calculus of Probability. Holden-Day, San Francisco.
- [5] Rajput, B. S. (1972). Gaussian measures on L spaces, $l \le p < \infty$, J. Multivariate Analysis 2, 382-403.
- [6] Shepp, L. A. (1966). Radon-Nikodým derivatives of Gaussian measures. Ann. Math. Statist. <u>37</u>, 321-354.
- [7] Varberg, D. E. (1967). Equivalent Gaussian measures with a particularly simple Radon-Nikodým derivative. Ann. Math. Statist. <u>38</u>, 1027-1030.

The second s

CONSTRUCTION OF

FOOTNOTES

- 1. This terminology is motivated by the classical theorem of Mercer, which asserts, in the present terminology, that every continuous (hence trace-class, relative to Lebesgue measure) kernel K on $[0, 1] \times [0, 1]$ admits expansion of the type given in (2.3).
- 2. Note that, since S_{δ} is a bounded, linear, nonnegative, selfadjoint and trace-class operator on H and $m_{\delta} \in H$, the measure μ_{δ} exists (see, for example, [5, p. 398]).

Contract Products

REPORT DOCUMENTA	TION PAGE	READ INSTRUCTIONS BEFORE COMPLETING FORM
REPORT NUMBER	2. GOVT ACCESSION NO.	3. RECIPIENT'S CATALOG NUMBER
Technical Report #7906/	A090187	
. TITLE (and Sublille)	uhaa DAL dawfurtin	5. TYPE OF REPORT & PERIOD COVERE
Equivalent Gaussian measures whose R-N derivative is the exponential of a diagonal form.		Interim
		6. PERFORMING ORG. REPORT NUMBER
· AUTHOR(e)		8. CONTRACT OR GRANT NUMBER(+)
D.M. Chung and Balram S. Rajp	but	N00014-78-C-0468
PERFORMING ORGANIZATION NAME AND AS	DDRESS	10. PROGRAM ELEMENT, PROJECT, TASK
Mathematics Department		
University of lennessee, knox	VIIIe, IN 37910	NK U42-400
1. CONTROLLING OFFICE NAME AND ADDRES Statistics and Probability Dr	12. REPORT DATE December 1979	
Office of Naval Research, Arl	13. NUMBER OF PAGES	
		22
4. NONITORING AGENCY NAME & ADDRESSUI	dillerent from Controlling Office)	18. SECURITY CLASS. (of this report) Unclassified
		154. DECLASSIFICATION/DOWNGRADING SCHEDULE
		<u> </u>
Approved for public release: 7. DISTRIBUTION STATEMENT (of the obstract	Distribution unlimit	m Report)
Approved for public release: 7. DISTRIBUTION STATEMENT (of the obstract	Distribution unlimit	m Report)
Approved for public release: 7. DISTRIBUTION STATEMENT (of the obstract	Distribution unlimit	er Report)
Approved for public release: 7. DISTRIBUTION STATEMENT (of the observect	Distribution unlimit	ted. a. Report)
Approved for public release: 7. DISTRIBUTION STATEMENT (of the observect 8. SUPPLEMENTARY NOTES 0. KEY WORDS (Continue on reverse side if neces	Distribution unlimit entered in Block 20, if different fro	n Report)
Approved for public release: 7. DISTRIBUTION STATEMENT (of the obstract 8. SUPPLEMENTARY NOTES 9. KEY WORDS (Continue on reverse side if neces Gaussian Processes, Radon-Nik	Distribution unlimit entered in Block 20, if different fro enery and identify by block number) odým derivative	a Report)
Approved for public release: 7. DISTRIBUTION STATEMENT (of the observect 8. SUPPLEMENTARY NOTES 6. KEY WORDS (Continue on reverse side if neces Gaussian Processes, Radon-Nik	Distribution unlimit entered in Black 20, if different fro every and identify by block number) odým derivative	a Report)
Approved for public release: 7. DISTRIBUTION STATEMENT (of the obstract 8. SUPPLEMENTARY NOTES 9. KEY WORDS (Continue on reverse side If neces Gaussian Processes, Radon-Nik CSIG(")	Distribution unlimit entered in Block 20, if different fro encory and identify by block number) odým derivative	Transformed and the second sec
Approved for public release: 7. DISTRIBUTION STATEMENT (of the obstract 8. SUPPLEMENTARY NOTES 9. KEY WORDS (Continue on reverse side if neces Gaussian Processes, Radon-Nik Signic 3. ABSTRACT Continue on reverse side if neces 5. Signic	Distribution unlimit entered in Block 20, if different fro encery and identify by block number) odým derivative	ted. <i>Report</i>) trace-class kernel K , is relative to the completed
Approved for public release: 7. DISTRIBUTION STATEMENT (of the observed) 8. SUPPLEMENTARY NOTES 6.	Distribution unlimit entered in Block 20, if different fro every and identify by block number) odým derivative every and identify by block number) odým derivative	trace-class kernel K , is (relative to the completed ce K. Using this result, the covariances (relative to
Approved for public release: 7. DISTRIBUTION STATEMENT (of the observation 5. SUPPLEMENTARY NOTES 5. SUPPLEMENTARY NOTES 5. SUPPLEMENTARY NOTES 5. ASSTRACT Continue on reverse side if necessary Gaussian Processes, Radon-Nik Signature	Distribution unlimit entered in Block 20, if different fro entered in Block 20, if different fro overy and identify by block number) odým derivative eary and identify by block number) odým derivative	trace-class kernel K , is (relative to the completed ce K. Using this result, the covariances (relative to a process X so that the mential of the diagonal form
Approved for public release: DISTRIBUTION STATEMENT (of the observed) SUPPLEMENTARY NOTES KEY WORDS (Continue on reverse side if necession Gaussian Processes, Radon-Nik Signature Signa	Distribution unlimit entered in Block 20, if different fro every and identify by block number) odým derivative every and identify by block number) odým derivative every and identify by block number) odým derivative	trace-class kernel K , is (relative to the completed ce K. Using this result, the covariances (relative to a process X so that the mential of the diagonal form et up of Hilbert space are (arbda
Approved for public release: Approved for public release: DISTRIBUTION STATEMENT (of the observed) Supplementany notes Supplementany notes Supplementany notes Gaussian Processes, Radon-Nik Supplementany and suffic given in order for the existe product 5- algebra) Gaussian p sufficient conditions are giv two equivalent (ro) Gaussian m Radon-Nikodym (R-N) derivativ in X. Analogues of the last also proved. Different 1473 EDITION OF 1 NOV 68 IS	Distribution unlimit entered in Block 20, if different fro entered in Block 20, if different fro output in Block 20, if different fro entered identify by block number) odým derivative entered identify by block number) inter condition, on a ince of a measurable (rocess with covariance en on the means and f easures P and P ₍₁) of e dp ₂ /dP is the expor two (results in the se Sub	trace-class kernel K , is (relative to the completed ce K. Using this result, the covariances (relative to a process X so that the mential of the diagonal form et up of Hilbert space are Lanbda
Approved for public release: Approved for public release: DISTRIBUTION STATEMENT (of the observation Supplementary notes KEY WORDS (Continue on reverse elds if necessing Gaussian Processes, Radon-Nik Signic Asstract (Continue on reverse elds if neces Asstract (Continue on reverse el	Distribution unlimit entered in Block 20, if different fro every and identify by block number) odým derivative cory and identify by block number) odým derivative second identify by block number) second identify by block number)	trace-class kernel K , is (relative to the completed ce K. Using this result, the covariances (relative to a process X so that the mential of the diagonal form et up of Hilbert space are Landda

. <u>.</u>.,