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RESEARCH AND DEVELOPMENT BRANCH

DEPARTMENT OF NATIONAL DEFENCE CANADA

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A DEVICE HANDLER FOR THE TIME OF ARRIVAL EMITTER

> by / · · · ) Barbara J/Ford ) Defence Electronics Division

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Carl Sterre Carlos

PROJECT NO. 31800

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### ABSTRACT

This paper describes an I/O driver (a device handler) to be used with a Direct Memory Access interface  $(DR11-B)^{\circ}$  for data transfer to the Digital Equipment Corporation PDP-11/45 computer for the Time of Arrival project. The considerations in writing the I/O driver are detailed.

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### RÉSUMÉ

Ce document décrit un contrôleur d'entree/sortie (I/O) devant être utilisé en conjonction avec un système l'interface pour accès direct de mémoire (DR11-B) dans le but de transférer des données à un miniordinateur PDP-11/45 de la compagnie Digital Equipment Corporation. Ceci s'inscrit dans le cadre d'un projet de radiogoniométrie basé sur la methode des differénces dans les temps d'arrivée (TOA). Les considérations conceptuelles du contrôleur sont déscrites en détail.

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### 1.0 INTRODUCTION

A program at DREO for the development of a Time of Arrival (TOA) emitter location system has been underway for some time. One of the major components of our current activity has been the implementation of a new data acquisition system which makes extensive use of digital signal processing and communication techniques.

Part of this data acquisition system involves the Digital Equipment Corporation (DEC) DR11-B, a direct memory access (DMA) interface, since a fast data transfer is required.

The software for the TOA is written for a PDP-11/45 and the method for delivering the data from the DR11-B to the PDP-11/45 is through use of an I/O (input/output) driver. The I/O driver is the interface between the Executive (the program that controls the resource allocation in the system) and the DR11-B.

### 2.0 AN OVERVIEW OF THE I/O DRIVER

In brief, the data from the radios used to locate the emitter are loaded into an extended buffer memory in three blocks of 1024 words. The DR11-B, controlled by the driver, is used to transfer this data to storage buffers in the PDP-11/45. The entire transfer takes approximately 8 milliseconds. This is fast compared to the 80 milliseconds needed to run the shortest task in the TOA software system.

The hardware causes an interrupt every 256 milliseconds. After the interrupt is generated the data associated with that interrupt remains for 128 milliseconds. If the interrupt is ignored because the software temporarily disabled interrupts then, once interrupts are re-enabled, the next interrupt with its associated data will be processed. Until an interrupt is received, other TOA software is being processed.

A listing of the I/O driver is given in Appendix A.

### 2.1 General I/O Driver Requirements

Generally speaking, an I/O driver to be used with the DEC operating system, RSX-11M, is an asynchronous process that calls and is called by the RSX-11M Executive to service an external I/O device. The driver does this by receiving and servicing interrupts from the I/O device. The driver also performs the function of time-out and, if necessary, other device-specific functions.

Certain conventions must be followed when using the RSX-11M operating system. The RSX-11M I/O system attempts to centralize common functions so that each driver does not have to include this common code.

An I/O driver in the RSX-11M operating system has six entry points. Each of these will be mentioned in the section involving the specifics of this particular driver. The I/O initiator, the device time-out, the power failure and the cancel I/O are entered by calls from the Executive. The device interrupt section of the driver is entered by a hardware input and/or output interrupt, depending on the device type.

Although separate from the driver, a data area defining a series of tables associated very closely with the driver must be included. The first table is called the Device Control Block (DCB). It describes the characteristics of the device controller and the units attached to the device controller. The second table is the Unit Control Block (UCB); a variable length control block. The third table is the Status Control Block (SCB), which describes the status of a device controller (the interface between the CPU and the device) that can run in parallel with all other controllers. The tables used for the driver in this paper are listed in Appendix B.

A driver must be named according to conventions established by the system. The last three letters of the driver task name must be DRV. The first two letters may be chosen to represent the function of this particular driver. The letters chosen must be different from those of drivers already in use in the system. Similarly the tables associated with the driver must be named with the last three letters TAB. The two letters used to identify the driver must also be used to identify the tables. This driver uses the letters CD to indicate the use of a central data acquisition unit.

An I/O driver can be resident or loadable. A resident driver is a permanent part of the Executive whereas a loadable driver is not permanent: it can be loaded (eg. LOA CD:) or unloaded (eg. UNL CD:) at will. A loadable driver does not tie up space in the Executive and it is easier to debug than a resident driver. For these reasons the CD driver is a loadable driver.

### 3.0 FUNCTIONS OF THE DRIVER

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### 3.1 Initialization Entry Point

In general this entry point, the I/O initiator, is called by the Executive to inform the driver that work is waiting to be done. This is after the Executive has queued an I/O packet. (An I/O packet is the description of the I/O to be done.)

A call to the system program \$GTPKT (get packet) is imperative. This subroutine will deliver to the driver the I/O packet in the driver's I/O queue with the highest priority. Then \$GTPKT sets the Status Control Block status to busy. If the driver's I/O queue is empty, \$GTPKT will indicate this. If \$GTPKT indicates there are no more I/O packets then the driver will usually exit.

If a packet is returned it is necessary to determine the function the driver is to perform. This driver is only involved with IO.RLB (read logical block). If the function code does not coincide with IO.RLB then an error is indicated.

The read logical block function retrieves the byte count, which had been stored in the device dependent parameter section of the QIO Executive call in the user program. Appendix C contains a listing of a sample user program. The byte count is converted to word count and stored in the appropriate place in the UCB. Interrupts are enabled and the DR11-B will cause an interrupt almost immediately because the hardware generates interrupts every 256 milliseconds.

### 3.2 Time-out Entry Point

When a driver initiates an I/O operation it permits establishment of a time-out count. If the function is not completed (for example, data not completely transferred) within the specified time interval the Executive calls the driver at this entry point.

Further DMA interrupts are disabled for the duration of the message printout. The message "Device Not Ready" is printed on the console terminal.

### 3.3 Miscellaneous Entry Points

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The Cancel I/O and Power Failure entry points must exist in the driver. However, they are not important to this driver so the driver immediately returns control to the Executive, causing nothing to be done in either routine. The Cancel I/O routine would, if required, terminate an in-progress I/O operation. The Power Failure routine would have normally been entered by a call from the Executive when the driver is loaded; when the system is bootstrapped; or when power is restored after a failure.

### 3.4 Device Interrupt Entry Points

These entry points are the interrupt service routines. In our case there are no output interrupts, only input interrupts, so the output service routine is not present. The actual purpose of the driver is handled in this input interrupt service routine. The first code generated is an INTSV\$ (interrupt save) which is generally called if the interrupt processing requires more than 100 microseconds. INTSV\$ frees two general purpose registers to use in processing the interrupt.

Further interrupts by the DR11-B are not allowed while the interrupt is being serviced. A call to \$FORK is necessary to decrease the high priority of the interrupt service routine.

The control and status register (CSR) address is retrieved and saved. (Figure 1 is a representation of the DR11-B CSR). Some of the bits are tested to determine the cause of the interrupt. The results of the set bits are peculiar to this DR11-B associated hardware. Figure 2 is a flowchart of the order of bit setting. If the error bit (bit 15) is not set, then the interrupt was caused by an erroneous word count overflow. If the non-existent memory (NEX) bit (bit 14) is set then a fatal hardware error occurred. However, if the error bit is set and the NEX and attention bits (bits 14 and 13) are not set then the bus address overflowed.

The DR11-B is not capable of incrementing the memory extension bits (bits 4 and 5 of the CSR) when the bus address overflows. In other words, the DR11-B transfers cannot, without software aid, cross 32K word boundaries. In order to handle this in software the value held in bits 4 and 5 is incremented to move to the next 32K partition.

If the error bit in the CSR is set, the NEX bit is clear, and the attention bit is set then only one check remains. The word count should be zero. If not, a glitch has caused a problem. If the word count is zero, it is time to load the word count and the buffer address into the appropriate place in memory. The Driver's time-out count value is set, then the manipulation of CSR bits to trigger hardware function begins. A go pulse is sent in order to clear the ready bit (bit 7). The ready bit must be cleared to allow a Direct Memory Access (DMA) transfer. The three function bits (bits 1, 2 and 3) and the go bit (bit 0) are cleared to initialize the hardware for the next operation. Finally the bits to start the DMA transfer are set. Function 2 (bit 2) is among the set bits. It grabs the bus and holds it until the ready bit is set. The ready bit (bit 7) is set when the word count overflows, indicating the required amount of data has been transferred.

Just before completing the interrupt process the CSR bits are cleared. This removes all undesired bits that may have been set. A call to the system program \$IODON is necessary to do final processing. The unit and controller are set idle. A jump back to the initiator allows the next call to \$GTPKT to determine if another request for I/O has been queued.

### 4.0 DRIVER DATA STRUCTURES

The first of the three tables associated with an I/O driver is the Device Control Block (DCB). The following values in the DCB are required by the CD driver:

- a 0 in the first word indicates there is only one DCB in the chain.
- the second word contains the link to the UCB.
- the third word indicates the driver is named CD.
- the fourth word contains the lowest unit number and the highest unit number.
- the fifth word holds the length of the UCB.
- the sixth word is a 0 to denote a loadable driver.
- the seventh and eleventh words show the following functions to be legal:
  - cancel I/O
  - read logical block
  - attach device
  - detach device
  - access file for read
  - access file for read/write
  - access file for read/write/extend
  - deaccess file
  - read virtual block.

For example, if bit 0 is set cancel I/O is legal. Similarly each function has an associated bit.

- the eighth and twelth words show no control functions are set.
- the ninth and thirteenth words have the following set as "NO OP" functions:
  - attach device
  - detach device
  - access file for read
  - access file for read/write

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- access file for read/write/extend
- deaccess file.
- the tenth and fourteenth words indicate there are no ACP functions (ancillary control processor: a file processor for performing I/O and other operations on files).

- the fifteenth word is used only for loadable drivers. It must be initialized to zero but will contain the address of the driver's partition control block.

The second of the three tables is the Unit Control Block (UCB). The following values in the UCB are required by the CD driver;

- the first and second words are not required by the CD driver.
- the third word contains a back pointer to the DCB.
- the fourth word contains a pointer to the UCB to which this device-unit has been redirected. Since there is only one device in the chain, this word points to the beginning of the one UCB.
- the low byte of the fifth word indicates the buffers must be word-alligned and this device is a non-processor request (DMA) device.
- the high byte of the fifth word must be initialized to zero, but it will be used to indicate whether the device-unit is busy. Other information involved with this byte is not relevant to this device.
- the low byte of the sixth word shows the physical unit number is 0.
- the high byte of the sixth word indicates the device is a public device and it cannot be redirected.
- the seventh word is zero since none of the possible device characteristics apply to this driver.
- the eighth and ninth words must be initialized to zero. These words are specific to a given device driver. The CD driver uses the eighth word as a flag and the ninth word to save the word count.
- the tenth word houses the default buffer size.
- the eleventh word contains the pointer to the SCB.
- the twelfth word must be initialized to zero. When the task (eg. DR2QIO) attaches itself to the device-unit this word contains its task control block address.
- two words of storage (words thirteen and fourteen) must be reserved. This region serves as a communication area between \$GTPKT and the driver. In this driver the region serves as an intermediary for the CSR and the bit setting.
- the fifteenth word must be reserved to contain the byte count of the buffer.

The third of the three tables is the Status Control Block (SCB). The following values in the SCB are required by the CD driver:

- the first and second words form the I/O queue listhead. Since the I/O packet queue is empty the first word is zero, and the second word points to the first word.
- the low byte of the third word contains the priority at which the device interrupts.
- the high byte of the third word holds the interrupt vector address divided by four.
- the low byte of the fourth word must be inititalized to zero. It will contain the current time-out count.
- the high byte of the fourth word is set to the initial time-out value.
- the low byte of the fifth word is the controller (DR11-B) number times 2. For the CD driver its value is zero since this is not a multi-controller driver.
- the high byte of the fifth word must be initialized to zero, but it will be used to establish whether the controller is busy (nonzero) or not busy (zero). The byte is tested and set by \$GTPKT then later reset by \$IODON.
- the sixth word contains the address of the CD control and status register (172434: address bits 16 and 17 are set by default).
- the seventh word must be reserved for the address of the current I/O packet. This address is established by \$GTPKT.
- the eighth to the twelfth words are reserved for Fork block storage. The area is used when there is a call to \$FORK.

### 5.0 ACCESSING THE DRIVER

Appendix C gives an example of a program that accesses the CD driver. This program illustrates the standard code necessary to access a driver.

A call to the RSX-11M directive ASNLUN is required to represent the CD physical unit by a logical unit number 2. The PDP-11 RSX-11M operating system refers to the CD device by a number.

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The GETADR subroutine call stores the address of the data buffer, IBUF, in a temporary storage, ITEMP, where the value may be accessed when required.

The array IBUF is dimensioned to hold the 3K (3072) words of data that will be sent from the DR11-B. The array IPR is a 6 word integer array accommodating device dependent parameters. The first word will contain the address of the data buffer. The second word will contain the number of data bytes to be transferred. This value will be put in I.PRM of the I/O packet.

The most important call in a program accessing a driver is the queue I/O (QIO) directive. This directive instructs the system to place an I/O request for the CD physical device into the queue of priority ordered requests. The parameters passed in this routine are the I/O function code, the logical unit number, the event flag number, the I/O status array, the device dependent parameters array, and the directive status.

The CD driver only uses the read logical block function so octal 1000 is the function code to use.

Event flags are used to coordinate events local or global to the program or system. The event flag number should be chosen from the numbers 1 to 24 since these numbers are available for local use by a program. The CD driver uses 1 for the event flag number.

The two-dimensional array ISTAT receives the final I/O status. A status of 1 returned from the driver indicates a successful transfer. A negative number may also be returned indicating an error condition, for example, a fatal hardware error.

If a directive status of +1 is returned then the QIO was successfully queued. If a negative number is returned as the directive status then the QIO request was not successfully queued. The reason for failure may be determined by the value of the negative number.

The wait for event flag (WAITFR) directive in the program causes a wait for the event flag, 1, set by a completed QIO. This wait stops the program to allow the I/O transfer to complete before continuing processing.

### 6.0 CONCLUSIONS

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The I/O driver as detailed in this Tech Note was written and incorporated into a PDP-11/45. Repeated successful fast data transfers were made from an extended buffer memory to the storage buffers of the PDP-11/45 under software control of the driver. This has confirmed that the driver design is wholly satisfactory and is able to perform all its functions in accordance with design criteria. It is evident that this CD driver may be successfully utilized in other similar DMA interface applications.

### 7.0 REFERENCES

- 1. DR11-B/DA11-B Manual, Digital Equipment Corp., Maynard, Massachussetts, September 1974.
- 2. PDP-11 Peripherals Handbook, Digital Equipment Corp., Maynard, Massachusetts, December 1975.
- 3. RSX-11M Guide to Writing an I/O Driver, Digital Equipment Corp., Maynard, Massachusetts, May 1979.
- 4. RSX-11M/M-PLUS Executive Reference Manual, Digital Equipment Corp., Maynard, Massachusetts, May 1979.

0	99
-	Punction
~	FUNCTION 2
n	FUNCTION 3
*	Errences Bus Adomess 16
ŝ	EXTENDED RUS ADDNEDS 17
٠	INTERNUPT DIABLE
4	Ne kon
•	CHER
•	DEVICE STATUS C
õ	DEVICE STATUS B
=	DEVICE STATUS
12	-CLUMM
5	ATTENTION
<u>+</u>	NON- EXISTENT MEMORY
5	and Cancel

FIGURE 1: THE DR11-B CONTROL AND STATUS REGISTER

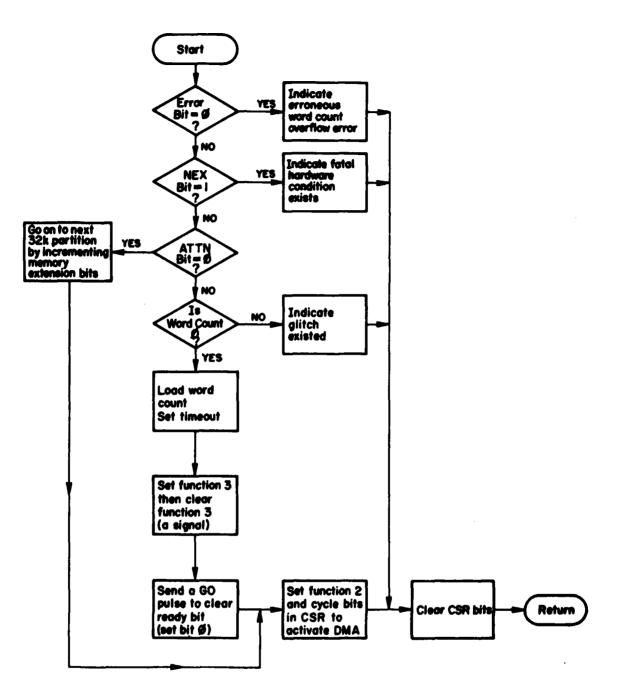


FIGURE 2: FLOWCHART OF THE BIT SETTING

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APPENDIX A

CD LOADABLE DEVICE DRIVER

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(8.J. FORD) USING CODE FROM: (W.T. MACKENZIE AND D. STARR - 25 JUN 77) DEVICE DRIVER CODE FOR GENERAL DMA INTERFACE FOR TIME OF Arrival (toa) data transfer to dec pop 11/45. RELATED MODULES: [290,200]usrty - CD Loadable data structures [290,200]nsxmc - Exec Assembly prefix file MACRA LIBRARIFS USED: [1,1]Exe<sup>4</sup>c - Exec Macro Library ELECTRONICS DIVISION (COMM EW) Research establishment ottama, RSX114 V23.2 BL26 SBCRV.MAC XP100L - 44RCH 1980 SBITL REFERENCES REFERENCES DEFENCE .TITLE .IDENT SPECIAL CORED

	<b>SATTL</b>	SYMBOL DEFINITIONS	SND	
-	SYMBOL	DEFINITIONS		
	MACRO L	MACRO LIBRARY CALLS		
	. MCALL	ARODFS, DEVDFS, HWDDFS, PKThFS, TCRDF	NDDFS, PK1	hFS, TCBOFS
	A 800FS A 800FS A 700FS A 7		906511NC 906511NC 906511NC 906511NC 906511NC 906511NC	TASK ABORT CODES. Device control block dffsets. Hardware register symbols. I/O packet offsets. Task control block offsets.
-	EQUATED	SYMBOLS		
LD3CD=1				JFLAG DRIVER AS LOADABLE.
C\$\$011#1	-			INCULTED IN INISYS.
	.SBTTL	LOCAL DATA		
-	LOCAL 5	DATA		
	CONTROL (INDEXE	COWTROLLER IMPURE MATA (Indexed by controller	TABLES Number)	
CNTBL:	. 0LK 1	<b>C32011</b>		ADDRESS OF UCB.
	• 16	GT C\$\$011-1		IASSEMBLE ACCORDING TO NUMBER 10F controllers.
TEMP1	. BLKK . E vDC	-		JTEMPORARY STORAGE FOR JCONTROLLER NUMBER, JEND CONDITIONAL ASSEMBLY,

Constant and and an and an and an an and an an and an and an and an and an and an an and an an an an an an an a

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ABLE		DEVICE INITIATOR ENTRY. ICANCEL I/O OPERATION ENTRY. IDEVICE TIMEOUT ENTRY. IPD*ERFAIL ENTRY.	
CD DRIVER DISPATCH TABLE	ER DISPATCH TABLE	H 2 F F Z 4 3 4 H 0000 U U U U U	
.S≞TTL	F CD DRIVER	5 5 5 5 5 5 5 5 5 5 5 5 5 5	

CD CONTROLLER INITIATOR **SBTTL** 

CD CONTROLLER INITIATOR

IF THE SPECIFIED CONTROLLER IS NOT BUSY, THEN AN ATTEMPT Is made to dequeve the next 1/0 request, else a return to the caller is executed. If the dequeve attempt is I/O OPERATION TO PROPOGATE THE EXECUTION OF THE DRIVER. AN I/O REQUEST IS QUEUED AND AT THE END OF A PREVIDUS SUCCESSFUL, THEN THE NEXT I/O OPERATION IS INITIATED. THIS ROUTINE IS FNTERED FROM THE GIO DIRECTIVE AHEN THIS REQUEST SHOULD CALL FOR DATA TO SENT FROM THE CENTRAL DATA AQUISITION CENTRE. CONTROLLER TO BE INITIATED. A RETURN TO THE CALLER IS THEN EXECUTED. ADDRESS OF THE UCB OF THE CD INITIATOR INPUTS: READ LOGICAL BLOCK ŝ

GET AN I/O PACKET IN PROCESS. Frequest successfully dequeued. CONTROLLER IS BUSY OR CANNOT DEQUEUE REQUEST. SGTPKT 105 RETURN CALL BCC CDINI:

REGISTER CONTENTS RETURNED BY SGTPKT:

ADDRESS OF THE I/O PACKET. PHYSICAL UNIT NUMBER. -- N 2 2

THE SCB. THE UCB. CONTROLLER INDEX. Address of the SCR 30 а <del>т</del> sa ъ

ADDRESS

ie.

30

ENT PARAMETER OF THE I/O REQUEST. NO, SUBFUNCTION MUST BE ILLEGAL. SAVE I/O PACKET ADDRESS. Point to first device depend-JSAVE SCB ADDRESS. JGET ADDRESS OF DEVICE CSR. JREAD LOGICAL BLOCK? LINK TO THE NEXT I/N PACKET. Priority of request, event flag number. FUNCTION CODE MODIFIER, FUNCTION CODE. Virtual address of 1/0 status block. Relocation bias of 105b. SAVE UCB POINTER FOR FINTERRUPT ROUTINE. ICLEAR ALL FLAGS. - VIPTUAL ADDRESS OF AST SERVICE TCB ADDRESS OF REQUESTING TASK. FUNCTION INDEPENDENT I/O REQUEST PACKET FORMATE REAL ADDRESS OF TOSB (REAL OR FUNCTION DEPENDENT I/O REQUEST PACKET FORMATE ADDRESS OF SECOND LUT WORD. ADDRESS OF REDIRECT UCB. PISPLACEMENT + 140000. WORD 12 - 1/0 DATA BUFFER ADDRESS Word 13 - Words. IYES. - BYTE COUNT. ROUTINE. I.FCN(R3),#IO.RLB S.CSR(P2), P4 RS, CNTRL (R3) . U.C+2(P5) ER.PRM.R] . 20RD 14 6 HORD 11 ø OPEXIT R1,R3 DORLA R4, R2 WORD W WOR0 WORD M 0403 O a O a MORD W MORD N NORO NO **UAD** 202 004 d M D a Q V CLR ×0× 201 202 1031

S. S. S. S.

READ LOGICAL BLOCK FUNCTION.

4(R1),R1 R1 R1,R2 R2,U,CW3(R5) #103,(R4)	#IE.0NP\$377,R0 \$1000 Cdini
7 4 7 7 7 7 0 0 0 0 0 0 0 7 4 7	NOP Return Mov Call Br
DORLB:	OPEXIT:

JGET BYTE COUNT FROM I/O PACKET. JCONVERT TO WORD COUNT. JSAVE IT. \$SAVE WORD COUNT. \$R4 IS SET TO POINT TO CSR IN \$CDINI. SO SET INTERRUPT ENABLE.

\$RETURN BAD PARAMETER CODE. \$Common completion exit. \$Get another 1/0 request.

day and the second

IFFALLOW ALL OTHER INTERRUPTS. SEC. PRE-ENABLE DEVICE INTERRUPT. \$ IF "DEVICE NOT READY" MESSAGES ARE DESIRED, INCLUDE THE FOLLO₩ING SET FOR "DEVICE NOT READY" TIMEOUT RESULTS IN A "NOT READY" MESSAGE ISSUED EVERY 15 Seconds. The message indicates that the device is powered down, there is a hardware fault or no new data is yet available. Device interrupt is enabled while ### INTERRUPT. 9 MESSAGE. 19ET FOR MESSAGE IN 15. IISSUE MESSAGE REQUEST. A "DEVICE NOT READY" MESSAGE IS OUTPUT EVERY Fifteen seconds from the start of timeout. DEVICE TIMEOUT STATUS, "IE, DNR", TRY AGAIN. CD TIMEOUT SERVICE ROUTINE CONTROLLER INDEX. CD TIMEOUT SERVICE ROUTINE - SCB ADDRESS. - UCB ADDRESS. #100, #S.CSR(R4) #100.03.CSP(P4) #15.,S.CTM(R4) CD TIMEOUT OUTPUTS: CD TIMEOUT INPUTS: #T.NDNR, RØ SDVMSG . 80 к к к м 4 М ŝ WATTING. SATTL RETURN CLRB CALL BIS MOVB VOP VOP >0× I CODE. CD0U7:

POWERFAIL IS HANDLFD BY THE DEVICE TIMEOUT SERVICE ROUTINE. The powerfail service routine is accordingly no op'd. RØ - ADDRESS OF ACTIVE I/O PACKET. R1 - ADDRESS OF TCR OF CURRENT TASK. R3 - CONTROLLER INDEX. R4 - SCB ADDRESS. R5 - UCB ADDRESS. NOP. (SINCE I/D CANCEL NOT REQUIRED) IND OP. 1 NO 0P. CD CANCEL I/O SERVICE ROUTINE POWERFAIL SERVICE ROUTINE CONTROLLER INDEX. CD CANCEL 1/0 SERVICE POUTINE SCB ADDRESS. PCKERFAIL SERVICE ROUTINE - UCB ADDRESS. CD CANCEL I/O OUTPUTS: CD CANCEL I/N INPUTSI CD POWERFAIL OUTPUTS: CD POWERFAIL INPUTS: NO 0P. **SBITL** .SATTL RETURN RETURN CDCAN: COPWF:

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CD DEVICE INTERRUPT SERVICE ROUTINE SATTL

CD DEVICE INTERRUPT SERVICE ROUTINE.

THO KINDS OF DEVICE INTERRUPT ARE POSSIBLE: ERROR CONDITION, AND WORD COUNT OVERFLOW. - N

FRROR CONDITION:

ARE FOUR POSSIBLE ERROR CONDITIONS: THERE

**DEVICE INITIATED INTERRUPT (ATTN),** •

VONEXISTENT MEMORY REFERENCE (NEX), DRII-B TEST BOARD INTERLOCK, AND,

DRII-B TEST N M 3

BUS ADDRESS OVERFLOW.

THUS, DR11-B AN ATTEMPT IS MADE, THE FOURTH KIND OF ERROR CONDITION OCCURS. In the case an interrupt occurs and when scoint is reenterred the BRANCH OCCURS THAT CAUSES THE EXTENDED MEMORY BITS TO INCREMENT DR11-B IS NOT CAPABLE OF INCREMENTING THE MEMORY EXTENSION IF SUCH BITS (BITS 4 AND 5) WHEN THE BUS ADDRESS OVERFLOWS. Transfers cannot normally cross 32k word boundaries. THEN HAVE THE DWA TRANSFER CONTINUE. **THE** 

AN INITIAL HARDWARE INTERRUPT OCCURS TO INDICATE THE TRANSFER MAY REGIN.

THIS IS THE SECOND SOURCE OF INTERRUPT TO THE CD DEVICE DRIVER. WORD COUNT OVERFLOW:

### SCDINT::

والتحديدة الألجميد ويتناث ومختلف والمسترجع

CD, PR5, C\$\$011 U, SC9(R5), R4 S, CSR(R4), R4	#100, (R4) Sfork #100000, (R4) 105	#040000,(R4) 205 #020000,(R4) 305
2000	B S S S S S S S S S S S S S S S S S S S	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1

JIJDISABLE CD INTERUPTS. JIJDROPS PRIORITY DOWN. TEST IF ERROR BIT SET. IF NOT, ERRONFOUS WORD COUNT OVERFLOW. TEST FOR NON-EXISTENT MEMORY. IF NOT SET THEN ERROR. IF NOT SET THEN ERROR. THE SET , INDICATE ERROR (CROSSED JZK PARTITION). IF ERROR AND ATTW BITS WERE SET (BITS 15 AND 13 OF CSR) THEN THE INTERRUPT Was Hardware (RISING EDGE OF THE PULSE).

		HARE (ALSING EIGE OF THE THE SUBJE	
	S T	-4(Ka)	JCHECK IF WORD COUNT IS ZERG.
	LLI Z	605	JIF NOT, GLITCH.
		U.CH3(RS), -4(R4)	JLOAD WORD COUNT.
	20	U.BUF+2(R5),-2(R4)	JLDAD BUFFER ADDRESS INTO CD DEVICE
			JBUS ADDRESS REGISTER.
	NOM NOM	U_SCB(R5),R3	JGET SCB ADDRESS.
	HOVB BNOW	S.ITH(R3), S.CTH(R3)	SET TIMEOUT FOR 5 SECONDS.
	>04 1	#000010, (R4)	JINDICATE TO MARDWARE CONTROL (STARTS
		•	JADDRESS CLOCK PULSE).
	>03	#000.(R4)	ITERMINATE ADDRESS CLOCK PULSE.
	NOM	#601. (R4)	SEND GO PULSE.
	BIC	#017.U.BUF(R5)	ICLEAR FUNCTION BITS AND 60.
	DON		
	dON		
	SIE	#404.U.BUF(R5)	JCYCLE BIT NOW SET.
583.	202	U. RUFIRS). (R4)	START DWA TRANSFER.
	> ( ) . E (		
2 204	CLR 2	(K4)	PREINITIATE CSP BITS.
	CALL	NODOIS	JINITIATE 1/0 COMPLETION.
	d x D	CDINI	JGET NEXT I/O REQUEST.
	- 0		101 101 101 10
			JGO ON TO NEXT SKY PARILIZON.
	20	203	
2031	NOM	#IE_FHE8377,R0	FATAL HARDWARE ERROR CONDITION.
		40.8	
402.	NOM		• ATTN GLITCH FRROR MESSAGE.
103 :	> 2 2 2 2 2	#=44.,RG 484	JERRONEOUS WORD COUNT OVERFLOW ERROR.
	• END		

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### APPENDIX B

### DRIVER DATA STRUCTURES

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IDEFINE DEVICE CONTROL BLOCK OFFSETS. Idefine Mardware registers. DEVICE DRIVER DATA STRUCTURES FOR TOA DATA TRANSFER TO 11/45. CODED - MARCH 1980 (8.J. Ford) USING CODE FROM: (W.T. MACKENZIE AND DALE STARR - 25 JUN 77) {200,200}CDDRV - CD LOADABLE DEVICE DRIVER CODE {200,200}R9XMC - EXEC ASSEMBLY PREFIX FILE COTAR - CD LOADABLE RATA STRUCTURES DEFENCE ELECTRONICS DIVISION, (COMM EW) Defence research establishment ottawa, [1.1]EXEMC - EXEC MACRO LIRRARY MACRO LIBRARIES USED \* PSX11M V03,2 BL26 \* SBTAR. MAC XOLEOL SYMBOL DEFINITIONS DEVDFS, HhDDFS MACRO LIBRARY CALLS REFERENCES SYMBOL DEFINITIONS / X 9 8 9 1 8 / RELATED MODULES REFERENCES . IDENT .717LE SPECIAL . SBTTL **.**5877L -MCALL DEVOFS HEOOFS

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WO OP FUNCTIONS ARE SET FOR FCP COMPATIBILITY AND THE ACP FUNCTION "READ VIRTUAL BLOCK" IS CONVERTED TO A "READ LOGICAL BLOCK" FUNCTION BY THE DIO PROCESSOR. TRANSFER FUNCTIONS ARE INTERPRETED BY BOTH THE DIO PROCESSOR AND THE DEVICE ORIVER. NOTE THAT CONTROL FUNCTIONS ARE INTERPRETED BY THE DRIVER, READ/WRITE/EXTEND ACCESS FILE FOR READ/WRITE/EXTEND READ/WRITE - ACCESS FILE FOR READ - ACCESS FILE FOR READ/WRITE - DISABLE RESIDUAL DATA 6,2 - ENABLE RESIDUAL DATA CD DEVICE PRIVER FUNCTIONS READ 5,20 - CLEAR CHANNEL MASK 5,100 - SET CHANNEL MASK 17 - READ VIRTUAL BLOCK READ VIRTUAL BLOCK 2 - READ LOGICAL BLOCK READ LOGICAL BLOCK ACCESS FILE FOR ACCESS FILE FOR - ACCESS FILE FCR 16 - DEACCESS FILE DEACCESS FILE CD DEVICE DRIVER FUNCTIONS LEGAL DEVICE FUNCTIONS: CANCEL 1/0 TRANSFER FUNCTIONS: 3 - ATTACH 4 - DETACH ATTACH - DETACH FUNCTIONS: FUNCTIONS: ACP FUNCTIONS: . 15 -16 -4,4 . 15 ŧ M 3 m ব 5 0 -CONTROL .SATTL 9 22

1015 2000

SBITL CD DEVICE CONTROL ALOCK (DCB)

CD DEVICE CONTROL PLOCK (DCB)

SCDCAT:: CDDCB: .W

UCREND-UCBREG 160035 000000 160030 999696 000003 000 100/ в, В 6 ASCII • • 080 • • 080 **BYTE** . NORD WORD. • NORD . KORD WORD. . WORD . WORD

. WORD

C

WORD.

1

PARTITION CONTROL BLOCK POINTER. 1(°0' FOR LOADABLE DRIVER) DRIVER DISPATCH TABLE ADDRESS. - "ORD 2. CONTROL FUNCTIONS - NORD 1 NO OP FUNCTIONS - WORD 2. LEGAL FUNCTIONS - WORD 1. NO OP FUNCTIONS - MORD 1. ILEGAL FUNCTIONS - MORD 2. ("0" FOR LOADABLE DRIVER) ACP FUNCTIONS - WORD 2. ACP FUNCTIONS - WORD 1. DATA STRUCTURES BEGIN. NO DCB CHAIN POINTER. HIGHEST UNNIT NUMBER. LOWEST UNIT NUMBER, LINK TO FIRST UCB. CONTROL FUNCTIONS DEVICE NAME. UCB LENGTH.

## CD UNIT CONTROL BLOCK (UCB) SBTTL

# CD UNIT CONTROL BLOCK (UCB)

JLOGON UIC (TERMINALS ONLY). Jowning terminal ucb address.	FOUL REQUIRED RERES BACK POINTER TO DCB. Pointer to Unit Redirect UCB. Fword Alignment & NPR Device,	981ATUS BYTE, 9PHYSICAL UNIT NUMBER, NOT •Destertarif and Phalte.	FIRST CHARACTERISTICS WORD, FEIRST CHARACTERISTICS WORD, FOEVICE DRIVER FLAG REGISTER, OFVICE STATUS REGISTER SAVE ABEA.	ES).	ITCH ADDRESS OF ATTACHED TASK. Indr device CSR register.	PHYSICAL ADDRESS REGISTER. Preserved for byte count.
616	CODCR .CD0 UC.Algiuc.NPR,0	0,US_REDIUS_PUB	888	2836 CDSCB	0	<del>•</del> •• ••
UCBBEGR. . NORD . NORD	. CDØ3 * ORD . * ORD . * ORD . * YTE	<b>,</b> BYTE			- 2020 -	. 8173 . 8173 . 8173

UCBEND=.

THIS REGISTER IS SET BY THE DRIVER FOR FUNCTION CODE, INTERRUPT PHYSICAL BUFFER ADDRESS FOR AN NPR TRANSFER ARE PASSED TO The device driver in the NPR device CSR register of the UCB. ENABLE AND GO, AND SUBSEQUENTLY TRANSFERED ALONG WITH THE CONTENTS OF THE PHYSICAL ADDRESS REGISTER OF THE UCB TO THE APPROPRIATE CD DEVICE REGISTERS PRIOR TO INITIATING AN NPR NOTE THAT THE MEMORY EXTENSION BITS ASSOCIATED WITH THE TRANSFER.

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SBITL CD STATUS CONTROL BLOCK (SCB)

CD STATUS CONTROL ALOCK (SCB)

CD CONTROL AND STATUS REGISTER. Address of current I/O Packet. JCONTROLLER I/O QUEUE LISTHEAD 3(Pointer to first entry). POINTER TO LAST ENTRY. FORK ALLOCATION BLOCK. Data Structures End. JVECTOR ADDRESS / 4. Scurrent timeout count, Jinitial timeout count. 1 = BUSY). STATUS. CONTROLLER INDEX, CONTROLLER (0 = IDLE, ADDRESS OF PR5,154/4 172434 CDSCR 0,5 в, в 6 . WORD . \*080 . 8475 **.BYTE** . \* OR D . 8 . 7 . 7 . 7 . 7 . 7 . 7 . 7 . 7 **BYTE** • E ND SCDEND: CDSCB:

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APPENDIX C

A TEST PROGRAM

ISTAT(1) CONTAINS THE I/O STATUS CODE, A 1 INDICATES A SUCCESSFUL Transfer. Istat(2) Indicates the number of bytes that were Peserved to be sent. Ibuf is the table that will hold the Ø IS THE PHYSICAL UNIT ASNLUN IS CALLED TO ASSIGN THE LOGICAL UNIT, 2 IS THE LOGICAL UNIT NUMBER CHOSEN, CD ARE THE DEVICE INITIALS CHOSEN, SIG-Nifying central data aquisition centre, 0 is the physical Uni LIKEBF STORES THE INDICATION OF WHETHER OR NOT THE USER WISHES THIS PROGRAM INVOKES THE SETUP THAT WILL ACCESS THE DRII-B FOLLOWING IS THE NUMBER OF BYTES TO BE TRANSFERRED. GETADA GETS AND SETS THE ADDRESS OF THE DATA BUFFER. DIMENSION ISTAT(2), IPR(6), IBUF(3072) BARBARA FORD (COMM EN / DRED) EQUIVALENCE (A, ISTAT(1)) DRIVER TO TRANSFER THE DATA. CALL GETADR(ITEMP, IBUF) 6000(8) TRANSFERRED WORDS. CALL ASNLUN(2, "CD". 0) 00 20 1=1,100 IPR(2) = 6144 IPR(1)=ITEMP THE BUFFER CUTPUT LIKEBF=0 BYTE A HRITTEN BY NUMBER. 1 HE U υu υυυ 000

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CHECK THE ERRCR STATUS CODE. (SEE P. B-1 OF 1/O DRIVERS IF NOT 1). The status code is in the Lower byte of istat(1). QIO IS CALLED WITH A WAIT PASSING "1000 (FOR READ LOGICAL BLOCK), 2 (FOR LOGICAL UNIT NUMPER), 1 (SET FOR EVENT FLAG NUM9ER), Blank (position reserved for priority although ignored), istat And ipr (tarles), ids (system defined for directive status), TYPE 10,IDS,A,I,IBUF(1),IBUF(2),IBUF(3),IBUF(4) Format(/, IDS = ',IA,' Status code = ',IA,' # = ',I4,405) CALL GIO("1000.2,1,,ISTAT,IPR,IDS) Call Waitfr(1) IF IDS IS 1 THEN "SUCCESSFULLY QUEUED". CONTINUE STOP ENO 5 8 8 18 0000 υυυ U C C Ð

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This paper describes an I/O driver (a device handler) to be used						
with a Direct Memory Access interface	(DR11+B) for data transfer to the					
Digital Equipment Corporation PDP-11/45 computer for the Time of Arrival						
project. The considerations in writing the I/O driver are detailed.						
Project						

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	DEVICE HANDLER		
	I/O DRIVER		
	INTERRUPTS		
	DIRECT MEMORY ACCESS		
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