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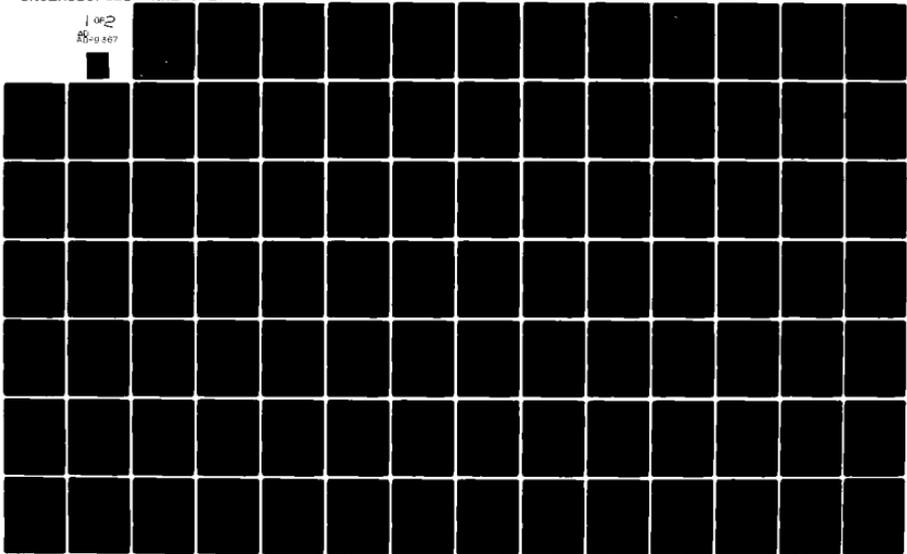
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NRL Report 8429

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**Modal Acoustic Transmission Loss (MOATL):
A Transmission-Loss Computer Program Using a
Normal-Mode Model of the Acoustic Field
in the Ocean.**

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*Applied Ocean Acoustics Branch
Acoustics Division*

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20. ABSTRACT (Continue on reverse side if necessary and identify by block number) A FORTRAN program which calculates coherent and incoherent acoustic transmission loss is described. The program is based on normal-mode theory of ocean acoustics. The theory models the ocean as two fluid layers, each with an arbitrary sound-speed profile, which overlay a uniform half-space. The half-space may be a fluid or a shear-supporting solid. The model incorporates losses due to acoustic absorption in all three media and losses due to roughness of the upper and lower boundaries of the upper fluid layer. An acoustic environment changing slowly with range is treated using the adiabatic approximation.		

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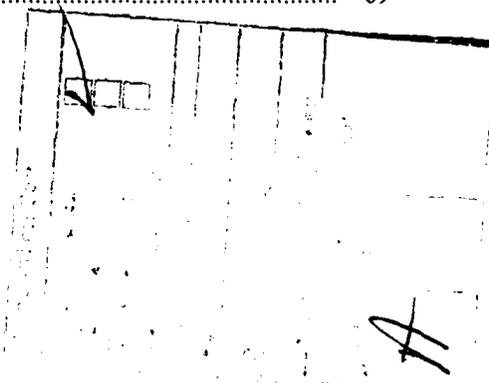
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MODAL ACOUSTIC TRANSMISSION LOSS (MOATL): A TRANSMISSION-LOSS COMPUTER PROGRAM USING A NORMAL-MODE MODEL OF THE ACOUSTIC FIELD IN THE OCEAN

INTRODUCTION

Investigations of acoustic transmission in shallow water typically consider propagation to ranges of 100 to 1000 times the thickness of the water column. The ocean may therefore be considered to be a thin film through which the signal is propagated. In many ocean areas the thickness of this film will show considerable variation over propagation ranges of interest. In addition, the acoustical properties of the water and the ocean bottom can depend upon range. However, these range dependences are usually slow and the acoustical properties are uniform over range intervals many times the acoustic wavelength. In contrast to the slow range-dependence, the acoustical properties of the ocean bottom and the water column frequently show rapid depth-dependence. Appreciable changes in these media occur over vertical distances comparable to the acoustic wavelength. In addition to this spatial variability, the properties of the water column are time-dependent and can change considerably over the period of a day due both to diurnal heating and cooling and to tidal flow.

The relative shallowness of the water column and the strong depth-dependence of its acoustical properties make normal-mode representations of the acoustic field more useful and reliable than the ray-tracing methods frequently used in transmission loss calculations for the deep ocean. NRL has developed a computer program that calculates transmission loss by using a normal-mode model. The subroutines which perform the normal-mode calculations have been described previously [1]. The transmission-loss calculation using the normal-mode parameters is the subject of the present report.

This transmission-loss model may be used with arbitrary depth-dependence of the sound speed in the water column and in the sediment layer. Provision is made, *via* the adiabatic approximation, for calculating loss in an environment changing slowly with range. The third source of variability mentioned above, temporal change in the water column, is not considered.

In the following section the normal-mode model of the acoustic field is described briefly. Details of this model and the associated FORTRAN programs are found in Ref. 1. Recent revisions of these programs are described in Appendix A. The transmission-loss model for the coherent and incoherent modal field sum for the perfectly stratified (range-independent) ocean is then presented. Modifications made to the calculation to incorporate an environment changing slowly with range follow.

THEORY

Normal-Mode Model for a Perfectly Stratified Medium

The model geometry is shown in Fig. 1. A fluid layer of thickness H_1 and uniform density ρ_1 is bounded above by a pressure-release surface and below by a second fluid layer, which has thickness H_2 and uniform density ρ_2 . These layers will be referred to as the water layer and the sediment layer. The (arbitrary) sound speed profiles in the water and sediment layers are $c_1(z)$ and $c_2(z)$, respectively. Beneath the sediment layer is a homogeneous semi-infinite basement of uniform density ρ_3 and compressional sound speed c_{3c} . The basement may be modeled as a fluid or as a shear-supporting solid. In the latter case, the shear sound speed is c_{3s} .

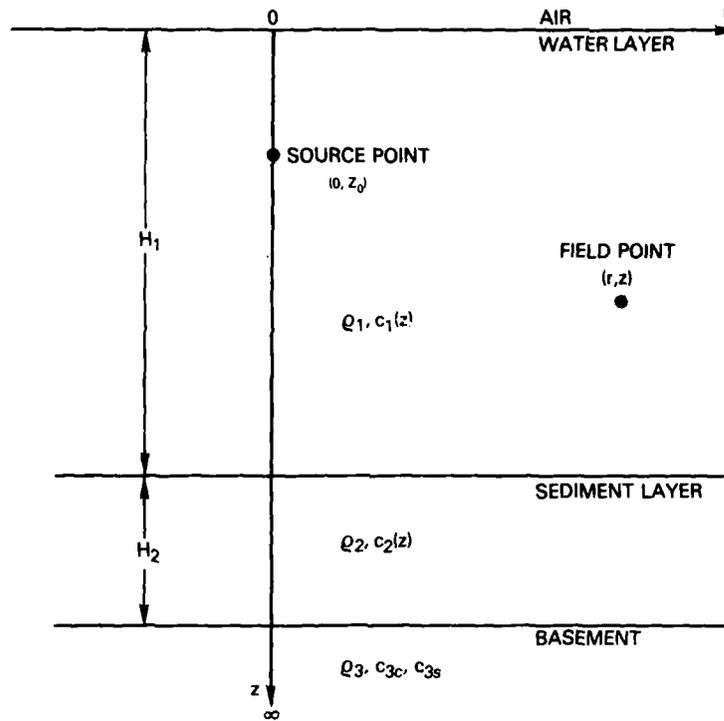


Fig. 1 — Physical model. An infinite half-space consisting of two fluid layers bounded above by air and having respective depths H_1 and H_2 , densities ρ_1 and ρ_2 , and a third, semi-infinite layer of density ρ_3 , compressional velocity c_{3c} , and shear velocity c_{3s} (if it is a solid). At the source point the z -axis of a cylindrical coordinate system is established perpendicular to the pressure-release surface (the r -axis) with increasing z downward. The sound speed profile in the water and sediment layers, $c_1(z)$ and $c_2(z)$ respectively, is a function of depth.

A cylindrical coordinate system is defined so the pressure-release surface lies in the (r, θ) plane, and the z -axis is perpendicular to the surface with z increasing downward. A harmonic point source of unit strength and angular frequency ω lies on the z -axis at depth z_0 . The velocity potential Φ at any field point (r, θ, z) satisfies the wave equation:

$$\nabla^2 \Phi + \left[\frac{\omega}{c(z)} \right]^2 \Phi = -\frac{1}{r} \delta(r) \delta(\theta) \delta(z - z_0). \quad (1)$$

The model geometry possesses cylindrical symmetry. The boundary conditions at the media interfaces, the water depth, and $c(z)$ do not depend on r , so we may separate Eq. (1) into two ordinary differential equations. The resulting solution is:

$$\Phi(r, \zeta) = \frac{i}{4H_1} \rho(\zeta_0) \sum_{n=1}^N u_n(\zeta_0) u_n(\zeta) H_0^{(1)}(k_n r),$$

where N is the number of discrete normal modes allowed and where we have introduced the dimensionless depth coordinate $\zeta = z/H_1$. The eigenfunctions $u_n(\zeta)$ satisfy the eigenvalue equation:

$$\frac{d^2 u_n}{d\zeta^2} + H_1^2 \left[\left[\frac{\omega}{c(\zeta)} \right]^2 - k_n^2 \right] u_n = 0, \quad (2)$$

and in the case of a fluid basement are subject to the normalization condition

$$\int_0^{\infty} \rho(\zeta) u_n^2(\zeta) d\zeta = 1, \quad (3)$$

where, depending on the value of ζ , $\rho = \rho_1, \rho_2$, or ρ_3 and $c = c_1, c_2$, or c_3 . A similar (but more complicated) condition applies to the solid-basement model [1]. These normalized eigenfunctions are the acoustic normal modes of the given environment. At sufficiently long range the Hankel function $H_0^{(1)}(k_n r)$ may be replaced by its asymptotic form. Thus

$$\Phi(r, \zeta, t) \sim i\rho(\zeta_0) \left(\frac{1}{8\pi H_1 r} \right)^{1/2} \sum_{n=1}^N \frac{u_n(\zeta_0) u_n(\zeta)}{k_n^{1/2}} e^{i(k_n r - \omega t - \pi/4)}, \quad (4)$$

where the time dependence $e^{-i\omega t}$ has been inserted.

Each of the terms in the sum in Eq. (4) corresponds to the contribution of a single normal mode of propagation. Each of these modal contributions is propagated independently of the others. Attenuation of the signal field is introduced by allowing the wave number (eigenvalue of Eq. (2)) of each mode to become complex:

$$k_n \rightarrow k_n + i\delta_n.$$

The attenuation coefficient, δ_n , assumes the form:

$$\delta_n = \epsilon_2 \gamma_n^{(2)} + \epsilon_{3c} \gamma_n^{(3c)} + \epsilon_{3s} \gamma_n^{(3s)} + S_{0,n} + S_{1,n} + \alpha_n. \quad (5)$$

Here ϵ_2 is the plane-wave attenuation coefficient (imaginary part of the wavenumber) in a hypothetical infinite medium consisting of the material in the sediment layer. The quantities ϵ_{3c} and ϵ_{3s} represent the compressional and shear plane-wave attenuation coefficients of the basement. The quantities $\gamma_n^{(2)}$, $\gamma_n^{(3c)}$, $\gamma_n^{(3s)}$ measure the degree to which the n th mode interacts with the sediment and the basement compressional and shear wave mechanisms. If the basement is a fluid, the term $\epsilon_{3s} \gamma_n^{(3s)}$ is absent. Of the remaining terms, $S_{0,n}$ and $S_{1,n}$ represent attenuation of the modal field due to interaction of the mode with statistically rough boundaries at the pressure-release boundary and the water-sediment boundary, respectively. The rough-boundary interaction is discussed in Refs. 2 and 3. The term α_n represents the attenuation due to absorption by the water (see Appendix A). The inclusion of the attenuation, Eq. (5), due to rough boundaries and water and bottom absorption in Eq. (4) gives:

$$\Phi(r, \zeta, t) \sim i\rho(\zeta_0) \left(\frac{1}{8\pi H_1 r} \right)^{1/2} \sum_{n=1}^N \frac{u_n(\zeta_0) u_n(\zeta)}{k_n^{1/2}} e^{i(k_n r - \omega t - \pi/4)} e^{-\delta_n r}. \quad (6)$$

The (real) instantaneous pressure $p(t)$ due to a signal source of rms source pressure level S , referred to unit distance from the source, is:

$$p(t) = S(4\pi)^{1/2} \rho(\zeta_0) \sum_{n=1}^N \frac{u_n(\zeta_0) u_n(\zeta)}{(H_1 k_n r)^{1/2}} \cos(k_n r - \omega t - \pi/4) e^{-\delta_n r}. \quad (7)$$

Details of the results presented in this section are given in Ref. 4.

Transmission Loss for a Perfectly Stratified Medium

To obtain transmission loss we consider the rms pressure averaged over a time $T \gg \frac{2\pi}{\omega}$:

$$\langle p^2(t) \rangle^{1/2} = \frac{S(4\pi)^{1/2}}{H_1} \rho_1 \left\{ \frac{1}{T} \int_0^T \left[\sum_{n=1}^N \frac{u_n(\zeta_0) u_n(\zeta)}{(k_n r)^{1/2}} \cos(k_n r - \omega t - \pi/4) e^{-\delta_n r} \right]^2 dt \right\}^{1/2}.$$

This expression, in which the summation includes the phases of the individual modal pressure contributions, is called the coherent sum. The coherent transmission loss obtained from this expression, expressed in decibels, is:

$$L_{coh} = -10 \log_{10} \left\{ \frac{(2\pi\rho_1^2)}{H_1^2} \left[\left[\sum_{n=1}^N \frac{u_n(\zeta_0) u_n(\zeta)}{(k_n r)^{1/2}} e^{-\delta_n r} \cos(k_n r) \right]^2 + \left[\sum_{n=1}^N \frac{u_n(\zeta_0) u_n(\zeta)}{(k_n r)^{1/2}} e^{-\delta_n r} \sin(k_n r) \right]^2 \right] \right\}. \quad (8)$$

When N is large, loss calculated from this expression usually exhibits rapid oscillations of order 10 to 20 dB as range changes (see Fig. 2). Transmission loss measurements employing CW acoustic signals show similar oscillations (see Fig. 3). These oscillations are caused by phase interference effects among the normal modes in which the signals are propagated. Details of the interference pattern are extremely sensitive to the values of k_n . The values of k_n are, in turn, sensitive to the sound-speed structure of the ocean bottom. In most cases of practical interest when there are more than a few modes the sound-speed structure of the ocean bottom is not known with sufficient accuracy to permit detailed agreement between calculated and measured interference patterns. Comparison of calculated and measured results is aided if the rapidly varying interference pattern is removed, leaving only a smooth curve. In treating experimental data this is accomplished by smoothing CW loss measurements over a range interval or by using broadband signals and processing techniques. The interference pattern is removed from the model calculations by performing an incoherent mode summation. That is, the energy contributions of individual modes rather than the phased pressures are added. The resulting expression for the incoherent loss is

$$L_{inc} = -10 \log_{10} \left\{ \frac{(2\pi\rho_1^2)}{H_1^2} \sum_{n=1}^N \left[\frac{u_n(\zeta_0) u_n(\zeta)}{(k_n r)^{1/2}} e^{-\delta_n r} \right]^2 \right\}. \quad (9)$$

Treatment of Nearly Stratified Media

In most shallow water areas of interest the assumption that the geometry and acoustical properties of the medium do not depend upon range is not valid, even over relatively short (~ 10 km) propagation paths. When a range-dependent medium is introduced, the acoustic wave equation (Eq. (1)) cannot be treated by the separation-of-variables technique used above. Since solutions of this generalized problem do not exist, it is necessary to employ approximation techniques. The approximation used here is that the range-dependence of the environment is sufficiently slow that the wave equation is "locally separable." By this we mean that any property of a given normal mode, say the eigenvalue k_n or the attenuation coefficient δ_n , in the vicinity of some point in the range-dependent medium is the same as it would be in a hypothetical range-independent medium with an environment the same as at the point of interest. In other words, the normal modes of propagation adapt to the local environment and the local properties can be calculated from the range-independent model.

An additional approximation, that the range-dependent environment does not transfer energy from one mode to another, is made. In this approximation [5,6], called the adiabatic approximation or the conservation of mode index, energy originally propagated in a particular normal mode remains in that mode until it is removed by absorption.

The modifications [7] to Eqs. (8) and (9) necessary to employ these two approximations are:

$$u_n(\zeta_0) u_n(\zeta) \rightarrow u_n(\zeta_0) u_n'(\zeta)$$

and

$$H_1 \rightarrow \sqrt{H_1 H_1'}$$

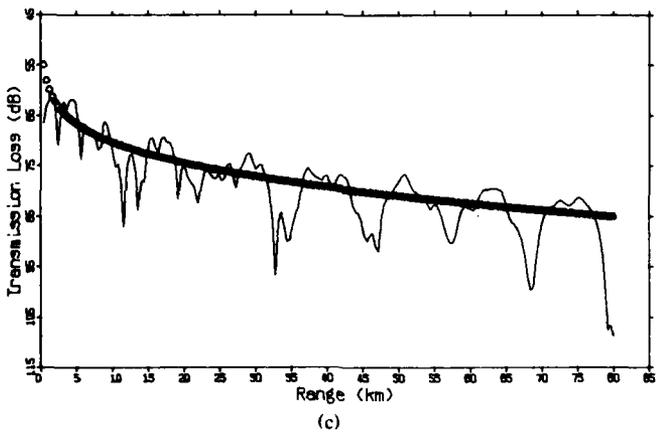
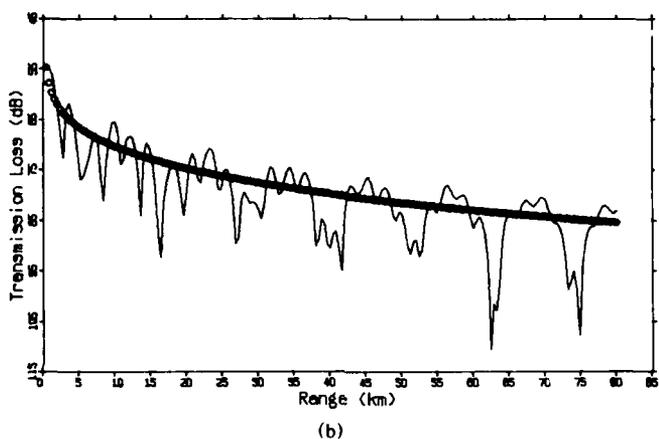
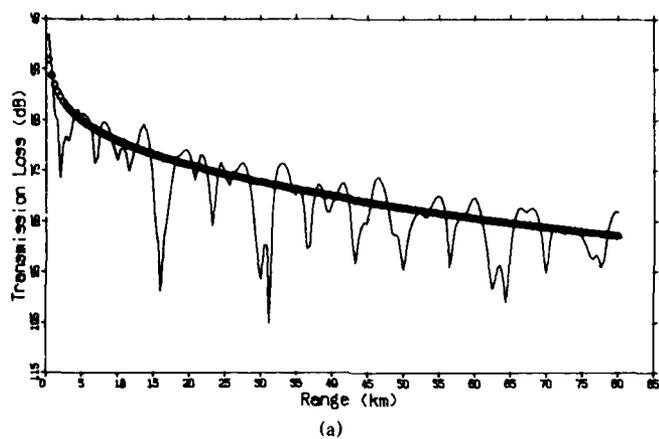


Fig. 2 — Calculated transmission loss. These three graphs are examples of the plotted output generated by PROGRAM MOATL. All result from the same physical environment (given as "Test Case Number 1" in the "OUTPUT" section of this report), but each corresponds to a different value of the receiver depth: (a) 70 m, (b) 200 m, and (c) 400 m. The value of L_{coh} (see Eq. (8)) is plotted as a continuous line and exhibits the oscillations due to modal interference. The value of L_{inc} at each range (see Eq. (9)) is plotted as a circle. The circles overlap at most of the ranges in these illustrations.

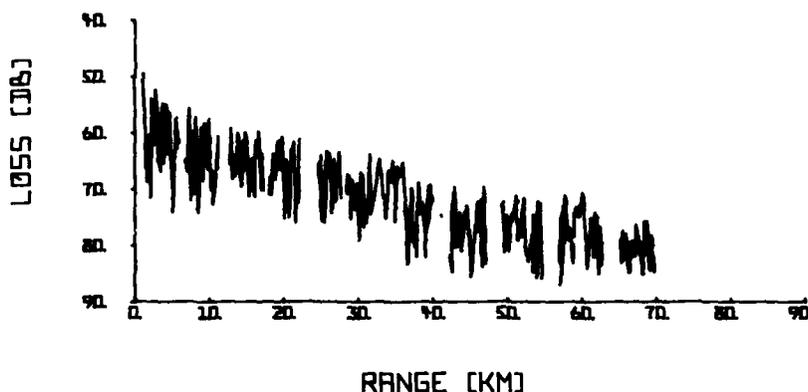


Fig. 3 — Measured CW transmission loss. Oscillations in the transmission loss are shown here for some typical measurements employing a towed CW source. The places where data are missing correspond to intervals during which the source was turned off.

where unprimed quantities u_n and H_1 apply to the source location and primed quantities u'_n and H'_1 apply to the field point at range r ;

$$k_n r \rightarrow \phi_n \equiv \int_0^r k_n(r) dr$$

is the cumulative phase; and

$$\delta_n \rightarrow \Delta_n \equiv \frac{1}{r} \int_0^r \delta_n(r) dr$$

is the average attenuation coefficient. Eqs. (8) and (9) then become:

$$L_{coh} = -10 \log_{10} \left\{ \frac{(2\pi\rho_1^2)}{H_1 H'_1} \left[\left(\sum_{n=1}^N \frac{u_n(\zeta_0) u'_n(\zeta)}{\phi_n^{1/2}} e^{-\Delta_n r} \cos\phi_n \right)^2 + \left(\sum_{n=1}^N \frac{u_n(\zeta_0) u'_n(\zeta)}{\phi_n^{1/2}} e^{-\Delta_n r} \sin\phi_n \right)^2 \right] \right\} \quad (10)$$

and

$$L_{inc} = -10 \log_{10} \left\{ \frac{(2\pi\rho_1^2)}{H_1 H'_1} \sum_{n=1}^N \left[\frac{u_n(\zeta_0) u'_n(\zeta)}{\phi_n^{1/2}} e^{-\Delta_n r} \right]^2 \right\}. \quad (11)$$

The phase of the signal is obtained as the arctangent of the ratio:

$$\frac{\left[\sum_{n=1}^N \frac{u_n(\zeta_0) u'_n(\zeta)}{\phi_n^{1/2}} e^{-\Delta_n r} \sin\phi_n \right]}{\left[\sum_{n=1}^N \frac{u_n(\zeta_0) u'_n(\zeta)}{\phi_n^{1/2}} e^{-\Delta_n r} \cos\phi_n \right]}.$$

ANALYSIS OF PROGRAM AND TECHNIQUES

General Remarks

For each point source of harmonic frequency f ($f = \omega/2\pi$) PROGRAM MOATL calculates the transmission loss as a function of range r and depth z . The model described above located the source at the range origin and considered the field point associated with the receiver to be a variable. In the program code, however, source-receiver reciprocity is employed to locate the receiver at the range origin

and depth z_0 . The source is located at the point (r, z) . This change was made so that the program conforms to the common experimental situation in which a source is towed along a radial track extending from a fixed receiver. In model calculations for range-independent environments the location of the receiver at the origin is largely for convenience of notation. In range-dependent environments, however, locating the fixed transducer at the origin makes the calculation more economical, since ϕ_n and Δ_n may be evaluated over the track without repetitive integrations over range. The program described in this report may be applied to situations in which the source is fixed and the receivers are moving, if the user exchanges the variables associated with source and receiver.

In the following description and in programming Eqs. (10) and (11), $u_n(\zeta_0)$ is taken to be the m th modal eigenfunction calculated by using the environment found at the origin and evaluated at the (normalized) depth ζ_0 associated with the receiver. The quantity $u_n'(\zeta)$ is calculated for the environment associated with range r and is evaluated at the source depth ζ . Note that if the water depth at the source H_1' depends upon range, the normalized source depth $\zeta(r) = z/H_1'(r)$ is also range-dependent.

The needed values u_n are obtained from the normal-mode representation of the sound field in an ocean consisting of a three-layer half-space, as discussed previously. To this end, the main program (MOATL) calls one of two sets of subroutines; the set FLUID, HALFF, and ITRTF assume the semi-infinite basement to be a fluid, whereas the set SOLID, HALFS, and ITRTS assume a basement capable of supporting shear. These subroutines are streamlined versions of the programs described in Ref. 1. Some improvements have been made since Ref. 1 was published; the major changes are discussed in Appendix A. Variable namelists are given in Appendix B.

When two distinct bottom layers with different properties are not required, a two-layer model may be realized. This is accomplished by giving the sediment layer (a) a small thickness and (b) physical properties identical to those either of the water layer (SOLID or FLUID) or of the basement (FLUID only). Realization of the single-medium bottom is illustrated by the first test case in the "OUTPUT" section.

Provision is made for the receiver to be located in the water or sediment layer; the source must be in the water layer.

The range points at which loss is to be calculated or the calculation ranges, as we shall sometimes call them, are assumed to be equally spaced. The user supplies the number of points and the maximum range at which calculated transmission loss is desired. The program obtains the spacing between points by division. Nevertheless, it is a simple matter to obtain results at unequally spaced range points. There are two places in the main program where the FORTRAN code must be altered slightly. These places are marked with COMMENT statements which give examples of how to make the required modifications (see the listing given in Appendix C). One word of caution: difficulties may be encountered if NMFREQ is given a value other than one; unequally spaced-calculation-range cases should be run one-at-a-time.

The user must always supply an environmental data set (including water depth, sound-speed profile, bottom properties, and other relevant parameters) at zero range. If a range-independent model is to be used, no further environmental input is required. For a range-dependent model calculation, additional environmental data sets are required. Each set may differ from the others by any arbitrary combination of the environmental parameters, subject to the constraint that the fluid-basement and solid-basement models may not both be used along the track. Such data sets may be supplied at any number of user-selected ranges (not necessarily equally spaced and not necessarily coincident with any of the ranges at which loss is to be calculated). Guidelines for the selection of spacing of environmental data sets are given in the "INPUT DATA" section below. The normal-mode parameters are calculated at each of these ranges. The modal properties are obtained at the intermediate range points (where the loss is to be calculated) by performing a linear interpolation. If loss calculations are desired out past the last data set, a linear extrapolation is performed.

With regard to this interpolation, there are four range points of interest at any given moment during the execution of the program (for a range-dependent model). The first is the range origin. Since an environmental profile is always supplied here, no range-interpolation is necessary to obtain the modal parameters at the receiver position. The second range of interest is the calculation range r , which together with the source depth locates the source position. Since r is not usually coincident with the range of one of the user-supplied input environments, a linear interpolation between the two input ranges which bound r is required in order to obtain the modal parameters at the source position. The ranges at which environmental data are supplied are the third and fourth ranges of interest. The smaller input range or any group of variables at that range will be designated hereafter by SR; the larger input range by LR. Details of the interpolation are presented below in Part 7 of the "Step-by-Step Analysis" section.

The dimensioning of many of the arrays implies an application for which the number of normal modes is less than or equal to 150. If more modes are expected, redimensioning and some minor FORTRAN code modifications are required; these are not discussed here. Knowledge of the expected number of modes is also required for determination of the input variables LI1 and LI2. For this purpose, we give the following "rule of thumb" guide:

$$N \approx \frac{2fH}{c_{\min}} \sqrt{1 - \left(\frac{c_{\min}}{c_3}\right)^2} + 1/2, \quad (12)$$

where N is the total number of modes, f is the frequency, H is the sum of the thicknesses of the water and sediment layers, c_{\min} is the minimum sound speed found in the water and sediment layers, and c_3 is c_{3c} (FLUID case) or c_{3s} (SOLID case). For an isovelocity profile and slight redefinition of variables, the expression becomes exact [8].

Before using the program, one must first inspect the two PARAMETER statements at the beginning of the main program and change them if necessary. The variables REC and SOC should be assigned values equal to or greater than the number of receiver and source depth points, respectively, at which calculated results are desired. The variable REC5 should be equal to or greater than REC and should be an integral multiple of five. This parameter is used for dimensioning the output transmission loss arrays, but the purpose of introducing it in place of REC is solely to make the printout more aesthetic; if resulting program storage requirements exceed the limitations of the given computer, the parameter may be eliminated by minor output adjustments. The variable RNG should be assigned a value equal to or greater than the number of range points at which calculations are desired. Before using the program for the first time on a given machine, the parameters MGNTD and PRCSN should be assigned appropriate values (see the COMMENT statement preceding the PARAMETER statement in the listing). They will not have to be changed subsequently.

The program was written in ASC FORTRAN for use with the Texas Instruments Advanced Scientific Computer (ASC) located at NRL. Wherever possible, however, the source code was put into standard form. Thus it should compile on most FORTRAN compilers with a minimum amount of preliminary code-changing.

The ASC has a single precision floating point word (32 bits) consisting of 1 bit for the sign, 7 bits for the exponent, and 24 bits for the fraction (precise to approximately 7 decimal digits). Some of the program variables are in DOUBLE PRECISION. A double precision word (64 bits) consists of 1 bit for the sign, 7 bits for the exponent, and 56 bits for the fraction (precise to approximately 16 decimal digits). In general, any variable involved in or affecting the calculation of an eigenvalue or eigenfunction is in DOUBLE PRECISION.

The required storage allocations for the main program, subroutines, and COMMON blocks are given in Table 1.

Table 1 — Storage Requirements

Routines	Number of Words (in hexadecimal base)
MOATL	4C59
FLUID	195B
ITRTF	4E3
HALFF	306
SOLID	1B9E
ITRTS	581
HALFS	335
Common Blocks	
TNIH	2
TNH	12C
TNI	7
TH	1
TN	58680
NIH	968
NH	5
NIFLU	2
NI	12DB
IH	2
NISOL	7

As an aid to following the flow of control in the program when reading the code, the following types of control statements have been indented three spaces: (1) DO loop; (2) GO TO statement; (3) transfer-of-control IF statement; and (4) calls to subroutines.

The Naval Research Laboratory's computer peripherals include an 11-inch Calcomp (California Computer Products) Model 565 Drum Plotter. The on-line plotter software on NRL's ASC currently supports this plotter. PROGRAM MOATL includes an option which uses this package to plot coherent and incoherent transmission loss as functions of range. Separate plots are generated for each frequency, receiver depth, and source depth.

Input to the program is from logical unit five (card reader by convention), and printed output is to logical unit six (line printer by convention).

Step-by-Step Analysis

In the present discussion, we follow PROGRAM MOATL step-by-step from start to finish. The FORTRAN namelist (Appendix B) should prove useful to the reader at this time. A synopsis of the workings of the program will be sketched and, whenever appropriate, the numerical methods and programming techniques will be described. Wherever the normal-mode subroutines are mentioned, reference to Appendix A may prove useful.

The program has been broken up into 11 parts for discussion. The program listing is given in Appendix C. The parts are defined, by control statement number (CSN), as follows:

Part 1: 34-58	Part 7: 189-214
Part 2: 59-66	Part 8: 215-247
Part 3: 67-120	Part 9: 248-262
Part 4: 121-141	Part 10: 263-271
Part 5: 142-146	Part 11: 272-299
Part 6: 147-188	

Preceding the executable code are CSNs 1-33, which set up the necessary COMMON blocks, PARAMETERS, DIMENSIONS, and FORMATS.

Part 1: Input Data and Initialization

The plot package is initialized and the parameters PMGTD and PPRCN are defined. These two parameters are used in the normal-mode subroutines. The transmission-loss input parameters are next read in and printed out. The variable DR is the calculation-range increment, defined by dividing the maximum range by the number of calculation-range points. The array RAN(I) contains integral multiples of DR, which are the ranges at which calculations are to be performed. If plotting is desired, parameters are now defined for this purpose.

Part 2: Frequency and Attenuation

The frequency loop (DO 340) marks the beginning of an actual calculation of transmission loss. A value of NMFREQ greater than one may be used, not only to obtain results for more than one frequency, but for more than one run of the program for any reason (e.g. different sediment thickness, different profile, etc.). For each case, the TITLE and frequency F are read in and printed out. The equation for EP4 converts the plane-wave absorption coefficient of the sediment, ϵ_2 (EP1 in the FORTRAN), from units of dB/Hz-m into units of nepers/m, in which form it is subsequently used. Similar equations convert the basement compressional plane-wave absorption coefficient, ϵ_{3c} (EP2 in the FORTRAN), and the basement shear plane-wave absorption coefficient, ϵ_{3s} (EP3 in the FORTRAN). They become EP5 and EP6, respectively.

Part 3: Input Data, Initialization, Receiver Parameters

The environmental input parameters (at zero range) needed for the normal-mode calculations at the site of the receiver are first read in and printed out. The appropriate normal-mode subroutines are next called to perform modal calculations. Prior to the call to FLUID or SOLID, NMODE is set to 10000. This is done for the following reason. In a range-dependent calculation, one of the input environments may support more modes than a previous environment, i.e., one at closer range. However, the program implements conservation of mode index by excluding the higher order modes which are not present at the previous environment. For example, if only five modes exist at an input range of 10 km, then at each of the calculation ranges beyond 10 km, only the five lowest order modes will be used for a calculation of transmission loss. Additional modes allowed at ranges greater than 10 km are assumed to be cut off at 10-km range. Each time FLUID or SOLID is called at a new input range, NMODE is redefined to be the smaller of (a) the previous value of NMODE or (b) the maximum number of modes existing for the given environment. Since this test is performed even for the first call to FLUID or SOLID, NMODE must have been defined prior to the first subroutine call. Since "redefinition" is actually to be definition by criterion (b), NMODE must be preset to a large number.

Prior to the first call to FLUID or SOLID, KA is set to zero. The variable KA is a flag which when zero causes the eigenfunctions to be stored in UNRM1(IM,I) and when one causes the eigenfunctions to be stored in UNRM2(IM,I). Mode order is designated by the variable IM, depth index by the variable I.

Many of the variables defined in Part 3 have names ending with the numeral 1 or 2, for example RANGE1 and RANGE2. The reason for this (the same as for UNRM1(IM,I) and UNRM2(IM,I)) rests in the numerical technique employed to calculate the transmission loss for a range-dependent environment. Any given source range at which loss calculations are desired will fall between two ranges at which environmental input data have been supplied. Environmental and modal parameters required at the source position are approximated by a linear interpolation which uses the given input at each of the bounding ranges. (This procedure is described later.) The parameters at the smaller (i.e.,

closer to the receiver) input range (hereafter designated SR) are stored in the variables whose names contain the trailing numeral 1. The parameters at the larger range (LR) use the trailing numeral 2. Parameters used for interpolation are: H11, H12 (water layer thickness); RANGE1, RANGE2 (range at which environmental input is supplied); CT1, CT2 (sound speed at the surface of the water layer); CB1, CB2 (sound speed at the bottom of the water layer); N11, N12 ($N1 = LI1 + 1$, where LI1 is the number of incremental intervals into which the water layer is broken); EIGVL1(IM), EIGVL2(IM) (the eigenvalue k_n); R11(IM), R12(IM) (sediment attenuation ratio $\gamma_n^{(2)}$); R21(IM), R22(IM) (basement compressional attenuation ratio $\gamma_n^{(3c)}$); R31(IM), R32(IM) (basement shear attenuation ratio $\gamma_n^{(3s)}$); RA1(IM), RA2(IM) (water absorption α_n — see Appendix A); RT1(IM), RT2(IM) ($\Gamma_{0,n}$ — see below); RB1(IM), RB2(IM) ($\Gamma_{1,n}$ — see below).

The quantities described above are read in and/or calculated in Part 3 for the receiver (zero range); they therefore constitute the first SR group. They are stored in the variables designated by the trailing numeral 1. They are also initially stored in the LR group, for a reason which is explained in the discussion of Part 6. The terms $S_{0,n}$ and $S_{1,n}$ appearing in Eq. (5) may be rewritten as:

$$\left. \begin{aligned} S_{0,n} &= (1 - |R_{0,n}|) \Gamma_{0,n} \\ S_{1,n} &= (1 - |R_{1,n}|) \Gamma_{1,n} \end{aligned} \right\} \quad (13)$$

The variable $R_{0,n}$ is the plane-wave reflection coefficient at the air/water interface, and $R_{1,n}$ is the plane-wave reflection coefficient at the interface between the water and sediment layers. $\Gamma_{0,n}$ and $\Gamma_{1,n}$ are the respective scattering ratios, which are calculated in the normal-mode subroutines. (See also Ref. 1.) At the receiver site (RANGE1 = 0) these quantities are stored in the SR variables RT1(IM) and RB1(IM), respectively.

The quantities H10, RERHO1, and RERHO2 are defined as the water depth, water density, and sediment density, respectively, at the receiver. They are defined because H11, RHO1, and RHO2 will take on new values when subsequent input environments are read in; however, the values of these quantities at the receiver will be needed in the final transmission-loss calculation.

The arrays SE(IM), S1(IM), S2(IM), S3(IM), SA(IM), ST(IM), and SB(IM) will be described in Part 8. They are now initialized to zero.

The final calculations of Part 3 are to obtain the values of $u_n(\zeta_0)$, which appear in Eqs. (10) and (11). The outer DO 110 loop varies the mode-order index n (programmed as IM) from 1 to NMODE. The inner DO 100 loop varies the receiver identification index (programmed as J1) from 1 to NDRE (the total number of receiver depths supplied). Each of the receiver depths corresponds to a different value of $\zeta_0 \equiv z_0/H_1$. The quantity $u_n(\zeta_0)$ is programmed as RE (J1, IM).

The eigenfunction for a given mode is calculated in the normal-mode subroutines; values of the function are defined at each of the $N1 + N2 = (LI1 + 1) + (LI2 + 1)$ incremental depths (see Appendix A and Ref. 1). The receiver depth, however, will generally lie between two of these incremental depths. The program performs a linear interpolation, as follows, to obtain the value of $u_n(\zeta_0)$. Assume for convenience that the receiver is in the water layer; the calculations for a receiver in the sediment are similar. The program first defines A1 to contain the number, plus fraction, of incremental layers (numbered downward from the air/water surface) which corresponds to the receiver depth. For example, if the receiver is exactly in the middle of the third incremental layer, $A1 = 2.5$. The term IA1 contains the (truncated) integer value of A1; following the above example, $IA1 = 2$. Thus in general, $\zeta_{IA1+1} < \zeta_0 < \zeta_{IA1+2}$, where ζ_{IA1+1} is the normalized depth at the top of the (IA1+1)th incremental layer; ζ_{IA1+2} is defined similarly. Note that $\zeta_1 = 0$. In the above example, ζ_0 is bounded by the depths at the tops of the third and fourth incremental layers. (The general procedure is illustrated in Fig. 4.) Standard linear interpolation yields the value for $u_n(\zeta_0)$:

$$u_n(\zeta_0) = u_n(\zeta_{IA1+1}) + \Delta [u_n(\zeta_{IA1+2}) - u_n(\zeta_{IA1+1})] \quad (14)$$

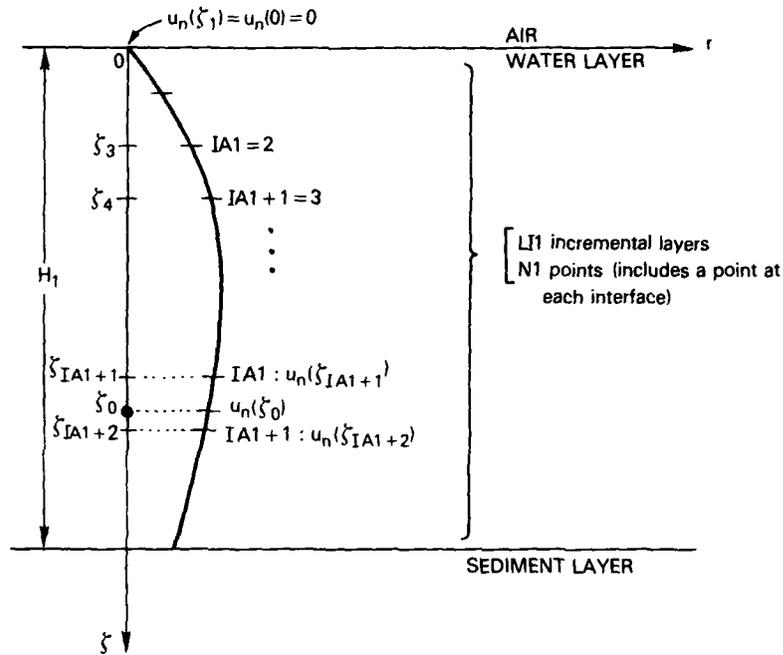


Fig. 4 — Receiver eigenfunction. The first mode (fluid-basement model) at zero range is illustrated, along with the values of the eigenfunction to be used in the interpolation of $u_n(\zeta_0)$.

The quantity Δ (programmed as *DLTA1*) is that fraction of a layer increment by which ζ_0 exceeds ζ_{IA1+1} . For a receiver in the water layer, we have:

$$\Delta = (LI1) * (\zeta_0) - IFIX\{(LI1) * (\zeta_0)\} = \frac{\zeta_0 - \zeta_{IA1+1}}{\zeta_{IA1+2} - \zeta_{IA1+1}} \quad (15)$$

For a receiver in the sediment, the calculation of Δ is performed similarly.

For a receiver depth equal to the depth of one of the incremental layer boundaries, Δ will take on the value zero or one, and the interpolation is actually a "do nothing" procedure.

Part 4: Range-Independent Parameters

If the calculation is to be based on a range-independent model, then the transmission-loss parameters and the calculated eigenfunctions at any given range will be the same as those already calculated at zero range for the receiver. Later calculations of the program use the terms *HS*, *CTS*, and *CBS* for the water-layer thickness and sound speeds at the surface and bottom of the water layer, respectively. For a range-independent calculation, these parameters and the others defined in Part 4 will not depend on the range r as the calculation point moves out in range. Thus they have simple definitions. The definitions for a range-dependent calculation are given in Part 7.

The procedure for obtaining the quantities $u'_n(\zeta)$, which are the eigenfunction values at the source, is identical to the procedure described in Part 3 for the receiver. As before, there are two loops, one for the *NDSO* source depths ζ and one for the $n = 1, \dots, NMODE$ modes. The variable $u'_n(\zeta)$ is programmed as *SM(J2,IM)*, where *J2* is the depth index and *IM* the mode-order index. The only difference in procedure between the source and receiver calculations is that the source must be in the water layer; *i.e.*, it may not be located in the sediment.

The quantities $WN(IM)$, $G1(IM)$, $G2(IM)$, $G3(IM)$, $GA(IM)$, $GT(IM)$, and $GB(IM)$ have simple definitions, thus obvious meanings, for the range-independent case (see Appendix B).

Part 5: Calculation Range Loop

The DO 300 loop uses I as the index for the NRCALC calculation-range points, which are stored in $RAN(I)$ one-by-one as encountered. If the calculations are to be range-independent, then the parameters of interest in Parts 6 and 7 have already been defined in Part 4, and Part 5 now transfers control to Part 8. This is programmed as: `IF(NRBUF.EQ.1) GO TO 209`.

If the calculations are to be range-dependent, then two more checks are made. Before calculations can be performed, we require various environmental and modal parameters, which are to be obtained for a given $RAN(I)$ by interpolating these same parameters between their known (or subroutine-calculated) values at the SR and the LR ranges (see Part 3 for definitions and Part 7 for the technique). Prior to the first time through the DO 300 loop, only the zero-range (receiver) parameters have been obtained, and they have been stored in the SR group. The first time through the DO 300 loop (and only the first time), $RANGE2$ will be equal to $RANGE1$, which is equal to zero (see Part 3). If they are equal, then Part 5 transfers control to Part 6, where the LR group is established.

The second check is made for subsequent loops over range. If, for a given value of I , $r \equiv RAN(I)$ lies between the present values of $RANGE1$ and $RANGE2$, then an interpolation between the present SR and LR groups can and should be made; Part 5 thus transfers control to Part 7. If $RAN(I)$, which has just been obtained by adding DR to the previous calculation range, is greater than $RANGE2$, then the value of $RANGE2$ must become the next value of $RANGE1$, and a new $RANGE2$ (and a new LR group) is needed before the calculations can proceed (see Part 6). Part 5 transfers control to Part 6. The quantity $RANGE2 + (DR/2)$ is actually used for this check, since for $RANGE2 < RAN(I) < RANGE2 + (DR/2)$, it is more accurate to extrapolate past the present $RANGE2$ than to make the redefinitions of Part 6 and interpolate between subsequent SR and LR groups. (See Fig. 5.)

Occasionally (when the option of unequally spaced calculation range points is used—see the "General Remarks" section and the COMMENT statements in the program listing following CSNs 51 and 142), $RAN(I)$ may be larger than $RMAX$, the range of the last input environment. In this case, linear extrapolation is to be performed past $RMAX$, which is $RANGE2$ at this point.

The formulae for extrapolation are identical to those for interpolation and are not programmed separately. We speak below only of interpolation, but the "double usage" is intended.

Part 6: Range-Dependent Parameters: Initialization

As alluded to previously, this part of the program is entered only if the present value of $RAN(I)$ lies outside the interpolation interval ($RANGE1, RANGE2 + DR/2$) and thus the interval must be redefined. To this end, all of the present LR group variables are stored in the SR group, *i.e.*, $RANGE2$ becomes the new $RANGE1$, and all of the LR parameters become the new SR parameters. For example, we encounter FORTRAN statements like `CT1=CT2` in Part 6. Note that the previous values of the SR variables are lost. (They will no longer be needed for calculation of modal parameters at the source position.) The new $RANGE2$ and its environmental parameters are next read in and printed out, and the new LR group is established. Since the normal-mode subroutines have been called previously to provide the modal parameters at zero range, the initial zero value of KA is now changed to one. When either FLUID or SOLID is subsequently called to perform the modal calculations, the value $KA=1$ ensures that the eigenfunctions are stored in the LR array $UNRM2(N,K)$.

In Part 3 we remarked that the receiver parameters were initially stored not only in the SR group, but also in the LR group. The reason for this now becomes apparent, in view of the procedure

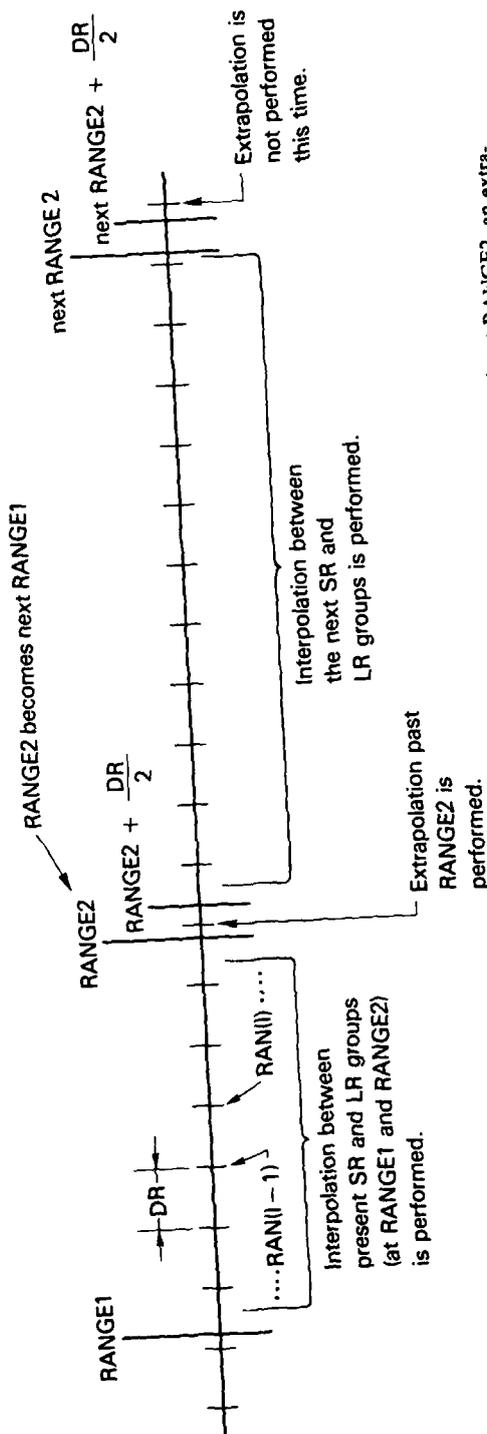


Fig. 5 — Interpolation or extrapolation at RAN(I). For the calculation range just beyond the present input RANGE2, an extrapolation is performed. If the calculation range were to lie beyond RANGE2 + (DR/2), as is the case for the next RANGE2, then RANGE2 and the present LR group would become the next RANGE1 and SR group, the next RANGE2 and LR group would be read in and/or calculated, and then an interpolation performed.

described above of shifting the values of the LR variables into the SR variables each time a new user-supplied environment is encountered. During the first pass through the DO 300 loop (I=1), the first nonzero range environment is read in. Just prior to storing it in the appropriate LR variables, however, all of the LR group is shifted into the SR group. By predefining these two groups to be identical, the receiver parameters are not lost but are still retained in the SR group. The new LR group is then established. Following the example of the last paragraph, we encounter such FORTRAN statements as CT2=C1(1) in setting up the new LR group. (The trailing numeral 1 in the array name here designates the water layer, *not* the SR group.) Storage of the eigenfunctions into the SR and LR arrays are handled in a different manner. The flag KA is set to zero to ensure that the receiver eigenfunctions are stored in UNRM1(N,K) and KA is then set to one to ensure that the eigenfunctions at the first nonzero range are stored in UNRM2(N,K). (See above and also Part 3.)

Part 7: Range-Dependent Parameters: Calculation of Source Parameters

Part 7 and Part 4 perform the same function and correspond to the range-dependent and range-independent cases, respectively. The quantities HS, CTS, and CBS depend on r for a range-dependent calculation. For the thickness of the water layer (the other two quantities are defined similarly), standard linear interpolation requires us to put:

$$HS = H11 + \Delta * (H12 - H11),$$

where

$$\Delta = \frac{RAN(I) - RANGE1}{RANGE2 - RANGE1} \tag{16}$$

The quantity Δ is programmed as SCALE. For interpolation of the eigenvalues and attenuation and scattering ratios, it is more accurate to replace the numerator in Eq. (16) by $[RAN(I) - (DR/2)] - RANGE1$, which is effected by the FORTRAN statement:

$$SCALE = SCALE - DR/(2.0 * (RANGE2 - RANGE1)). \tag{17}$$

The reason for this, illustrated in Fig. 6, is as follows.

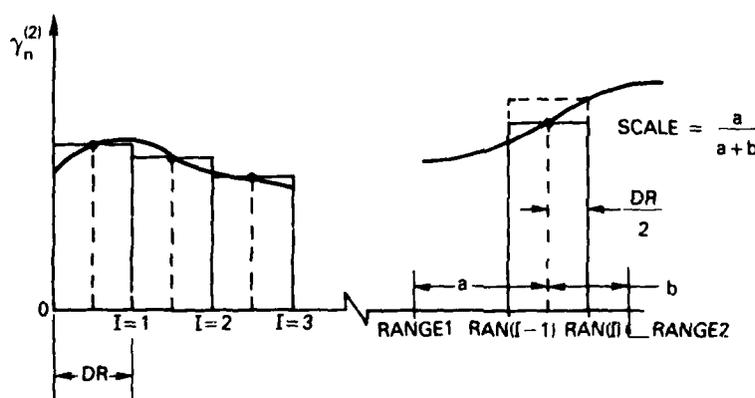


Fig. 6 - Approximation of $\int_0^r \gamma_n^{(2)}(r') dr'$. The "piece" of the integral $\int_{RAN(I-1)}^{RAN(I)} \gamma_n^{(2)}(r') dr'$ is approximated by $DR * \gamma_n^{(2)}(r'')$, where r'' is equal to $RAN(I) - (DR/2)$. The result is shown with solid lines, and is more accurate than the result (shown with dashed lines) corresponding to $r'' = RAN(I)$.

Equations (10) and (11) for the transmission loss each contain the term $e^{-\Delta_n r}$, where

$$\Delta_n \equiv \frac{1}{r} \int_0^r \delta_n(r') dr' \quad (18)$$

is the average attenuation coefficient. This integral may be broken into a number of separate integrals through use of Eq. (5). For example, one term of Eq. (18), say Δ'_n , will be

$$\Delta'_n \equiv \frac{\epsilon_2}{r} \int_0^r \gamma_n^{(2)}(r') dr'. \quad (19)$$

At any given range $r = \text{RAN}(I)$, the integral is approximated by adding a new "piece," representing the integral from $\text{RAN}(I-1)$ to $\text{RAN}(I)$, to the stored value of the (approximated) integral from zero to $\text{RAN}(I-1)$. (See Part 8.) Reference to Fig. 6 demonstrates that the appropriate value of $\gamma_n^{(2)}$ to be multiplied by DR (in order to approximate $\int_{\text{RAN}(I-1)}^{\text{RAN}(I)} \gamma_n^{(2)}(r') dr'$ by a rectangle) is the value of the function at the midpoint of the range-increment interval, *i.e.*, at $\text{RAN}(I) - (\text{DR}/2)$. In the FORTRAN code, this value of $\gamma_n^{(2)}$ is programmed as G1(IM) . Thus if we write

$$\text{G1(IM)} = \text{R11(IM)} + \text{SCALE} * (\text{R12(IM)} - \text{R11(IM)}),$$

SCALE must be given by its redefined value, Eq. (17), rather than its original value, Eq. (16).

Other variables handled in a manner identical to that of G1(IM) are: WN(IM) (the eigenvalue k_n), G2(IM) (compressional attenuation ratio $\gamma_n^{(3c)}$), G3(IM) (shear attenuation ratio $\gamma_n^{(3s)}$), GA(IM) (water absorption α_n), GT(IM) (air/water scattering ratio $\Gamma_{0,n}$), and GB(IM) (water/sediment scattering ratio $\Gamma_{1,n}$).

The values of the modal eigenfunctions $u'_n(\zeta)$ at the source position are determined as follows. The normalized source depth at range $\text{RAN}(I)$ is calculated. Then the value of the eigenfunction, XXR1 , for this normalized depth at the SR range is determined by interpolating between stored values of the eigenfunction computed for the SR range (CSN 202). The method is similar to that used for the receiver eigenfunction which is given by Eqs. (14) and (15) and which is illustrated in Fig. 4. The interpolation is repeated (CSN 203) on the eigenfunction calculated at the LR range to obtain XXR2 . Finally, the value of the eigenfunction at $\text{RAN}(I)$, programmed as $\text{SM}(J2, \text{IM})$ is determined by a range-weighted interpolation between XXR1 and XXR2 at CSN 204 where the interpolation coefficient Δ is determined from Eq. (16). After this procedure has been applied to all the normal modes which propagate to the receiver and the loss at $\text{RAN}(I)$ is determined, the normalized source depth at $\text{RAN}(I+1)$ is calculated and the above procedure is repeated.

Note that, in general, XXR1 and XXR2 will change as $\text{RAN}(I)$ moves between SR and LR. Interpolation employing the normalized depth variable has been found to be more accurate than direct interpolation using the depth variable z to obtain different normalized depths at the SR and LR ranges.

Part 8: Transmission Loss: I.

The array $\text{PL}(J1, J2, I)$ is used for the incoherent transmission loss or transmission-loss anomaly (see Part 9 for definition of transmission-loss anomaly) and $\text{QC}(J1, J2)$ and $\text{QS}(J1, J2)$ are used for the cosine and sine terms, respectively, of the coherent transmission loss or transmission-loss anomaly. These arrays are first set to zero. Note that for each new calculation-range point, they will initially contain all zeros. On the other hand, the arrays $\text{SE(IM)}, \dots, \text{SB(IM)}$, were initialized to zero outside the DO 300 range loop (see Part 3). Thus they initially contain zeros only for the first range-point calculation. For each individual mode (they are subscripted for mode index), these arrays will accumulate "pieces" of the range integrals they represent (see below and also Fig. 6) as execution of the code contained in the range loop is repeated for each new calculation-range point.

As noted in the discussion of Part 7, the average attenuation coefficient Δ_n (see Eq. (18)) may be broken into a number of integrals representing the separate attenuation mechanisms. Considering only the sediment attenuation ratio $\gamma_n^{(2)}$, for example, the coefficient Δ_n (a component of Δ_n) is given by Eq. (19). Similar equations hold for the other attenuation mechanisms. The program approximates each of these integrals by dividing it into "pieces," each "piece" representing the integral over the range from RAN(I-1) to RAN(I); recall I is the index of the DO 300 range loop. The piece $\int_{\text{RAN}(I-1)}^{\text{RAN}(I)} \gamma_n^{(2)}(r') dr'$ is approximated by the area of a rectangle having sides DR and G1(IM) (see Part 7 and Fig. 6). Thus it is programmed as G1(IM) * DR. In the FORTRAN statement:

$$S1(IM) = S1(IM) + G1(IM) * DR,$$

S1(IM) on the left-hand side represents $\int_0^{\text{RAN}(I)} \gamma_n^{(2)}(r') dr'$. On the right-hand side, S1(IM) represents the accumulated value of the integral for previous ranges, i.e., it contains the approximation for $\int_0^{\text{RAN}(I-1)} \gamma_n^{(2)}(r') dr'$.

Other variables handled in an identical manner to that of S1(IM) are: SE(IM), which represents $\int_0^{\delta} k_n(r') dr'$; S2(IM), which represents $\int_0^{\delta} \gamma_n^{(3c)}(r') dr'$; S3(IM), which represents $\int_0^{\delta} \gamma_n^{(3s)}(r') dr'$; SA(IM), which represents $\int_0^{\delta} \alpha_n(r') dr'$; ST(IM), which represents $\int_0^{\delta} \Gamma_{0,n}(r') dr'$; and SB(IM), which represents $\int_0^{\delta} \Gamma_{1,n}(r') dr'$.

Equations (10) and (11) for the transmission loss each contain the term $e^{-\Delta_n r}$. Using Eqs. (18) and (5), we have

$$\Delta_n r = \epsilon_4 \int_0^r \gamma_n^{(2)}(r') dr' + \epsilon_5 \int_0^r \gamma_n^{(3c)}(r') dr' + \epsilon_6 \int_0^r \gamma_n^{(3s)}(r') dr' + \int_0^r S_{0,n}(r') dr' + \int_0^r S_{1,n}(r') dr' + \int_0^r \alpha_n(r') dr', \quad (20)$$

where we have inserted ϵ_4 , ϵ_5 , and ϵ_6 in place of ϵ_2 , ϵ_{3c} , and ϵ_{3s} , respectively, as discussed in Part 2. The term $\Delta_n r$ is programmed as QQ. We first encounter the definition

$$QQ = EP4 * S1(IM) + EP5 * S2(IM) + EP6 * S3(IM) + SA(IM),$$

which adds the first three terms and the last term on the right-hand side of Eq. (20). The remaining two terms of Eq. (20) are added to QQ by the two FORTRAN statements following the defining statement. The terms $S_{0,n}$ and $S_{1,n}$ may be expressed in terms of the scattering ratios $\Gamma_{0,n}$ and $\Gamma_{1,n}$, respectively; the relationship is given by Eqs. (13). The plane-wave reflection coefficients appearing there may be evaluated in terms of the rms roughnesses of the boundaries. If we let σ_0 (SIG0 in the program) be the rms wave height and σ_1 (SIG1 in the program) be the rms excursion of the water/sediment interface, then Eqs. (13) take the form [3]:

$$\left. \begin{aligned} S_{0,n} &= 2\sigma_0^2 \left[\left(\frac{\omega}{c_1(0)} \right)^2 - k_n^2 \right] \Gamma_{0,n} \\ S_{1,n} &= 2\sigma_1^2 \left[\left(\frac{\omega}{c_1(H_1)} \right)^2 - k_n^2 \right] \Gamma_{1,n} \end{aligned} \right\} \quad (21)$$

If the explicit expressions for $\Gamma_{0,n}$ and $\Gamma_{1,n}$ given in Ref. 1 are inserted into Eqs. (21), the result is that of Ref. 3. The fourth term on the right-hand side in Eq. (20) may now be written

$$\int_0^r S_{0,n}(r') dr' = 2\sigma_0^2 \int_0^r \left[\left(\frac{\omega}{c_1(0)} \right)^2 - k_n^2(r') \right] \Gamma_{0,n}(r') dr'$$

The FORTRAN statement which includes this term in QQ is:

$$QQ = QQ + 2.0 * ST(IM) * SIG0 * SIG0 * ((6.2831853 * F / CTS) ** 2 - WN(IM) * WN(IM)).$$

The inclusion of the water/sediment scattering term follows in a similar manner.

The term $e^{-\Delta_n r}$ is programmed as Q2:

$$Q2 = 1.0 / EXP(QQ).$$

If $\Delta_n r > 32.25$ for any given mode n , the term Q2 will not be included in the modal sum of Eqs. (10) and (11), and the program prints out a flag informing the user of this fact. The reason for neglecting the term is as follows. Suppose that $QQ > 32.25$. Then $Q2 < 10^{-14}$. The largest value that Q1 can reasonably be expected to attain is of order 10^4 ; thus even for the largest value of Q1, Q will always be less than 10^{-10} (see below for definitions of Q1 and Q). Such a small term will not make a significant contribution to the modal sum appearing in Eqs. (10) and (11), thus it is neglected. What this means physically is that at ranges for which $\Delta_n r > 32.25$, nearly all of the energy initially in the n th mode has been removed by attenuation.

Also appearing in the modal sums of Eqs. (10) and (11) is the term $u_n(\zeta_0) u_n'(\zeta) / \phi_n^{1/2}$. Except for inclusion of a factor $r^{1/2}$ in the numerator, this term is programmed as Q1: $Q1 = RE(J1, IM) * SM(J2, IM) * DSQRT(RAN(I) / SE(IM))$. (See Part 9 for programming of the removal of the factor $r^{1/2}$.)

The variable Q is defined as the product of Q1 and Q2. We have seen above that Q may be neglected for a particular mode if it is smaller than 10^{-10} . This, in turn, imposes a restriction on the smallness of Q2 corresponding to the largest possible value of Q1. Alternatively, consider the largest possible value of Q2, which is one. We may therefore restrict the absolute value of Q1 to be greater than or equal to 10^{-10} . The test for $Q2 < 10^{-14}$, when fulfilled, will remove a given modal contribution for all source and receiver depths. The test for $Q1 > 10^{-10}$ must be a function of mode-index, source depth, and receiver depth. The corresponding FORTRAN statement thus appears within the DO 220 source and receiver loops as well as within the DO 230 mode loop.

The inclusion of terms excluded by the two above-described tests would not invalidate the transmission-loss calculations. One reason for having the tests is to save execution time. However, a more important reason exists. The argument of the exponential function, QQ, may become quite large. If no check is made, a fatal execution error may result, due to machine limitations on the size of the argument of the EXP function. Similarly, Q2 may become very small in absolute value. This will occur, for example, if either of the depths ζ_0 or ζ is such that the eigenfunction $u_n(\zeta_0)$ or $u_n'(\zeta)$ is very close to a node (for a particular mode order n). The resulting calculation of Q1 might yield a number smaller than 10^{-x} , where x specifies the dynamic range of a real constant (a machine-dependent parameter). This would cause a fatal error. Such a problem has never been encountered in years of using the program. On the other hand, numbers have been encountered which, when squared (as Eqs. (10) and (11) require), would have caused an execution error due to their extreme smallness. The test on Q1 eliminates the possibility of such errors.

After the definition of Q comes the FORTRAN statement $QS(J1, J2) = QS(J1, J2) + Q * DSIN(SE(IM))$. For each source depth and each receiver depth (for which these arrays are subscripted), QS(J1, J2) will "accumulate" NMODE terms as the DO 230 loop is executed. After the loop is finished, we have:

$$QS(J1, J2) = \sum_{n=1}^N \frac{u_n(\zeta_0) u_n'(\zeta) r^{1/2}}{\phi_n^{1/2}} e^{-\Delta_n r} \sin \phi_n.$$

In a similar manner, we have:

$$QC(J1,J2) = \sum_{n=1}^N \frac{u_n(\zeta_0) u_n'(\zeta) r^{1/2}}{\phi_n^{1/2}} e^{-\Delta_n r} \cos \phi_n$$

and

$$PL(J1,J2,1) = \sum_{n=1}^N \left[\frac{u_n(\zeta_0) u_n'(\zeta)}{\phi_n^{1/2}} e^{-\Delta_n r} \right]^2 r. \quad (22)$$

The array $PL(J1,J2,1)$ will finally represent the incoherent transmission loss or transmission-loss anomaly (see Part 9). As presently defined by Eq. (22), however, it represents an intermediate result. The multiplicative factor r has been introduced for numerical purposes and is to be removed in the final calculation.

Part 9: Transmission Loss: II

The array $COPL(J1,J2,1)$ is used for coherent loss calculations and is defined initially, for each source and receiver depth (via the DO 270 loops), as the sum of the squares of $QS(J1,J2)$ and $QC(J1,J2)$:

$$\begin{aligned} COPL(J1,J2,1) = & \left[\sum_{n=1}^N \frac{u_n(\zeta_0) u_n'(\zeta)}{\phi_n^{1/2}} e^{-\Delta_n r} \sin \phi_n \right]^2 r \\ & + \left[\sum_{n=1}^N \frac{u_n(\zeta_0) u_n'(\zeta)}{\phi_n^{1/2}} e^{-\Delta_n r} \cos \phi_n \right]^2 r. \end{aligned} \quad (23)$$

The phase of the signal, as defined in the "THEORY" section, is coded next.

$$PHASE(J1,J2) = ATAN2(QS(J1,J2), QC(J1,J2)) * 57.295779513.$$

The multiplicative factor at the end converts the result of the arctangent function from radians to degrees.

The program will calculate either the transmission loss (TL) or the transmission-loss anomaly (TLA), which is the loss in addition to that caused by cylindrical spreading. The input parameter ISPRD controls this choice. If ISPRD = 0, then the TLA is calculated. If ISPRD = 1, then the TL is calculated. The relation between the two is: $TL = 10 \log_{10} r + TLA$. We shall discuss here only the coherent and incoherent TL, which are given by Eqs. (10) and (11), respectively. The TLA is obtained in a similar manner.

To get Eq. (10) from Eq. (23), we divide by the range $r = RAN(I)$, the water depth at the receiver $H10$, and the water depth at the source HS ; we multiply by $2\pi\rho_1^2$; and we take the base-10 log of the result and multiply by (-10) . The FORTRAN statement which does this therefore completes the evaluation of Eq. (10) and stores the final result in the array $COPL(J1,J2,1)$. To get Eq. (11) from Eq. (22), we follow an identical procedure. The array $PL(J1,J2,1)$ contains the final result. In writing Eqs. (10) and (11), the "normal" situation of a receiver in the water layer was assumed. In this case, we have $DEPRE(J1).LE.H10$ fulfilled in the FORTRAN IF statement, and Eqs. (10) and (11) are programmed with ρ_1 given by $RERHO1$. As mentioned earlier, however, the program will accommodate a receiver in the sediment. In this case, the program replaces ρ_1 by ρ_2 , given in the FORTRAN by $RERHO2$.

Part 10: Printed Output

The calculated coherent transmission loss (modulus in decibels, phase in degrees) and incoherent transmission loss (in decibels) are printed out as functions of range (DO 300), source depth (DO 290), and receiver depth (DO 280). (When there is only one source and one receiver, the quantities are functions of range only, and the output is on one line per range.)

Examples are given in the "OUTPUT" section.

Part 11: Plotted Output

Plotting of loss vs range is performed separately for each source depth and receiver depth. The plots, which contain both coherent and incoherent loss, are executed in the following order, which is important to note since the plots are unlabeled:

```

DO 340 loop for frequency
DO 330 loop for receiver depth
DO 330 loop for source depth
Plot Package
330 CALL ORIGIN (XLENG +2.5, 0.)
340 CONTINUE

```

INPUT DATA**Explanation of Data Deck and Notes to the User**

There are three groups of data input statements. The first group, containing primarily data needed for transmission-loss calculations, is read in once (in Part 1). (The various "Parts" of the program are defined in the "Step-By-Step Analysis" section.) The second group, containing primarily environmental data needed for modal calculations at the receiver site, is read in once for each frequency (in Part 3). The third group is similar to the second and is read in (only for a range-dependent calculation) NRBUF-1 times for each frequency (in Part 6). Each of the second and third groups may differ from the others by any arbitrary combination of the environmental parameters, subject to the constraint that the fluid-basement and solid-basement models may not both be used for a given track. If NMFREQ is greater than one, the procedure of reading the second and third groups is repeated.

The spacing of the user-supplied environmental data profiles for the range-dependent model is usually dictated by the bathymetry of the acoustic propagation path, and to a lesser degree, by changes in the sound speed profile with range. Since water depth at a calculation range site is approximated by a linear interpolation between the depths at two user-supplied profiles, the user should approximate the known bathymetry by linear segments, supplying input data at the ranges where these segments meet. Additional profiles may be supplied at other ranges in order to take account of the range-dependence of other environmental parameters.

There is another reason for inserting extra profiles along the track. If the number of modes which the environment will support decreases rapidly with increasing range, as will be the case for a water depth, H_1 , which decreases rapidly, then the calculated loss may change discontinuously at an input range where there are many fewer modes than at the previous input range. This is due to conservation of mode-index, implemented in the program by excluding those higher order modes which are not present at both of the input environments between which range-interpolations are to be carried out on the eigenfunctions. Thus, for example, if three input profiles A, B, and C support 80, 50, and 20 modes, respectively, calculations at range points between A and B will use 50 modes, and those between B and C will use 20 modes. At ranges greater than B, some of the (excluded) higher order

modes may initially actually yield an important contribution which decreases rapidly thereafter. By exclusion of all these modes starting at range B, a small discontinuity in the loss may be caused at range B. The problem may be avoided, however, by supplying additional profiles, perhaps one between A and B which supports approximately 65 modes and one between B and C which supports approximately 35 modes. (If the discontinuity is reduced, but not eliminated, more supplemental profiles may be necessary.)

The above-described procedure will work if enough intermediate profiles are used; however, this may substantially increase the execution time of the program. We shall briefly discuss another method of circumventing the problem which is particularly suited to those tracks along which the deep sediment structure is not important. Reference to Eq. (12) shows that the total number of modes which exists at a given range is dependent, among other things, on $H \equiv H_1 + H_2$, and not on the water depth H_1 alone. (It was tacitly assumed in the previous paragraph that H_2 is nearly constant with range so the change in the number of allowed modes was due to the decrease of H_1 .) If deep sediment structure is unimportant, the sediment thickness H_2 may be assigned small values at the smaller ranges and large values at the larger ranges, thereby keeping H and consequently the total number of modes nearly constant with changing range. This procedure allows the higher order modes to accumulate large attenuation coefficients before their contributions are dropped from the modal sum in Eq. (22).

In experiments the source depth sometimes changes at one or more points along the tow track. The user of PROGRAM MOATL can incorporate source depth changes along the track by inserting the appropriate IF statement(s) between CSNs 193 and 194:

```
IF(RAN(I).GT. ....) DEPSO(1) = ... (etc.).
```

In situations in which the water depth over part of the acoustic propagation path is less than the source depth, the change of source depth is necessary since the program requires the source to be in the water layer. This change is necessary even if the source was not towed over that part of the path in the experiment whose results are to be modeled, since the program assumes that the source is towed from the range origin in order to evaluate Eqs. (18), (19), and (20) accurately. We note for completeness that for the range-dependent or range-independent model, the source depth may be changed at any range for any other reason and all the loss calculations will be correct.

There are two other notable variations that the program will treat. First, although the program is set up to model a three-layer half-space, a two-layer model may be practically realized when the basement rock interfaces with the water (SOLID) or the sediment is so thick that deep sediment structure is not important (FLUID). Such an example for the fluid basement is given in the "OUTPUT" section. The second variation is that, although the code as programmed assumes the calculation ranges to be equally spaced, minor code alterations will allow unequally spaced ranges. Details concerning each of these two variations, along with additional information, may be found in the section "General Remarks."

Listed below are the required input data. Each line (and an indented continuation) corresponds to a single data card (or a single record of 80 characters if input is not by use of cards). If there is more than one of each type of card, the variable specifying the number of cards is printed to the left and is underlined. All of such cards appear together in the data deck. (By "NDSO ÷ 8" it is meant, for example, that if there are to be eleven source depths, there will be two data cards, eight values on the first and three on the second.) The three input groups described in the first paragraph of this section are separated by brackets. If there is more than one set of a group of cards, the variable specifying the number of sets is printed to the left and is underlined. These sets are clustered in the data deck. The FORMAT to be used for each card is specified in parentheses at the end of each line.

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TITLE(I) (20A4)

ISPRD,NMFREQ,NRBUF,NRCALC,RMAX,EP1,EP2,
EP3,SIG0,SIG1 (4I5,F10.3,5F10.7)

NDSO,NDRE (2I5)

III (I5)

I PLOT,DBMIN,DBMAX,DY,DX (I5,2F10.3,2 F10.7)

NDSO+8 - DEPSO(I), I=1,8 (8F10.3)

NDRE+8 - DEPRE(I), I=1,8 (8F10.3)

TITLE(I) (20A4)

F (F10.3)

MDPRNT,INC1,INC2,RHO1,RHO2,RHO3,H11,H2
(3I5,5F10.3)

EPSLN,COMP,SHEAR,RANGE1,LI1,LI2,ND1,ND2
(F10.8,3F10.3,4I5)

ND1 - Z1(I),C1(I) (2F10.3)

ND2 - Z2(I),C2(I) (2F10.3)

NMFREQ

MDPRNT,INC1,INC2,RHO1,RHO2,RHO3,H12,H2
(3I5,5F10.3)

EPSLN,COMP,SHEAR,RANGE2,LI1,LI2,ND1,ND2
(F10.8,3F10.3,4I5)

NRBUF-1

ND1 - Z1(I),C1(I) (2F10.3)

ND2 - Z2(I),C2(I) (2F10.3)

Description of Input Data

We now describe the function and use of each of the input variables. They are arranged here in the same order as they are read in by the program. For determining input values further information is given in the previous section and the "General Remarks" section.

No specific units (m or km, for example) are required; however, it is necessary to see that the units chosen are consistent for all the input variables. (The only two exceptions are the density of the water, which must always be unity (see below), and DX (km/in.) and RMAX (m) when the plot package is desired.) We assume below the m-k-s system for convenience, which serves also as a useful example.

TITLE(I) — An array containing any alphanumeric label (80 characters maximum).

ISPRD — If 0, the loss anomaly (no cylindrical spreading) will be calculated. If 1, the loss (cylindrical spreading included) will be calculated. (See discussion in the section "Step-By-Step Analysis—Part 9".)

NMFREQ — The number of source frequencies (or alternatively, the number of different environmental cases for a given frequency) for which the calculations are desired. Should be set to unity when unequally spaced calculation ranges are used.

NRBUF — The number of environmental data profiles to be input. If 1, the environment is range-independent. If greater than 1, the environment is range-dependent.

NRCALC — The number of range points at which loss calculations are desired (limited by PARAMETER statement). In general, these will be equally spaced out to the maximum range specified. (See the "General Remarks" section for further discussion and limitations.)

RMAX — Maximum range (m) at which loss calculations are desired.

EP1 — Sediment layer plane-wave absorption coefficient (dB/Hz-m).

EP2 — Basement compressional plane-wave absorption coefficient (dB/Hz-m).

EP3 — Basement shear plane-wave absorption coefficient (dB/Hz-m). Set equal to 0 for a FLUID model.

SIG0 — The rms wave height (m) used for calculating attenuation due to air/water interface scattering.

SIG1 — The rms bottom roughness (m) used for calculating attenuation due to water/sediment interface scattering.

NDSO — Number of source depths. (Limited by PARAMETER statement.)

NDRE — Number of receiver depths. (Limited by PARAMETER statement.)

III — If 0, a FLUID basement is assumed. If 1, a SOLID basement is assumed. (The type of basement is fixed by III for the entire track.)

IPLT — If 0, no plots are included in the output. If 1, plotting is executed.

DBMIN — Lower bound for transmission loss (dB) on the plotted graph's loss axis.

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- DBMAX — Upper bound for transmission loss (dB) on the plotted graph's loss axis.
- DY — Number of decibels per inch determining the scale of the plotted graph's loss axis.
- DX — Determines the scale of the plotted graph's range axis. If the units used for range are meters, DX should specify the number of kilometers per inch on the axis.
- DEPSO(I) — An array storing the source depths (m). (Each of these values must be $\leq H_1$.)
- DEPRE(I) — An array storing the receiver depths (m). (Each of these values must be $\leq H_1 + H_2$.)
- TITLE(I) — Another arbitrary alphanumeric label (80 characters maximum).
- F — Source frequency (Hz).
- MDPRNT — If 0, none of the calculated mode-amplitude functions will be printed out. Otherwise, they will be printed out in accordance with the following two inputs.
- INC1 — A variable containing a value one greater than the number of depth-increment values to be skipped between printed-out values of the mode-amplitude functions, in the water layer. Note: first determine LI1; then set INC1 to give the desired number of printed out values. As an example, if LI1 = 300 and INC1 = 6, then 50 values will be printed out.
- INC2 — Same as INC1, but for the sediment layer. The number of output values is based on LI2.
- RHO1 — The variable RHO1 = 1.0 always. It is the density to be used for water regardless of the units used for the rest of the data.
- RHO2 — Ratio of the density of the sediment layer to that of water.
- RHO3 — Ratio of the density of the basement to that of water.
- H11 — The thickness (m) of the water layer at the receiver.
- H12 — The thickness (m) of the water layer at any nonzero range where the environmental data are read in.
- H2 — The thickness (m) of the sediment layer. (Same variable name used at all ranges.)
- EPSLN — The variable EPSLN = 0.0001 always. It is the criterion for the accuracy of the calculated eigenvalues (modal wave numbers), *i.e.*, the amount by which the air/water surface value of the normalized eigenfunction may differ from the pressure-release boundary-condition requirement of being identically zero.
- COMP — Compressional velocity (m/s) in the basement.
- SHEAR — Shear velocity (m/s) in the basement for the SOLID model; it must exceed the minimum sound speed found in the water and sediment layers. However, for the FLUID model, set SHEAR = 0.
- RANGE1 — The variable RANGE1 = 0 always. It is the receiver range, which is zero by definition.
- RANGE2 — The range (m) from the fixed receiver of the present environmental profile being read in.

L11 — The number of incremental steps into which the water layer is to be divided for the calculations. (See "Notes" below.)

L12 — The number of incremental steps into which the sediment layer is to be divided for the calculations. (See "Notes" below.)

Notes: The numbers of layers L11 and L12 help to determine the accuracy of the eigenvalues and mode-amplitude functions. The quantity L11 should be set equal to about ten times the number of modes expected; L12 should be set to yield approximately the same spacing. To estimate N, the total number of modes, see Eq. (12). Dimensioning of arrays requires that N be less than or equal to 150. In no event should either L11 or L12 be less than four, nor should their sum exceed 1200. They must each be even-valued to be consistent with the Simpson's rule integration method used in the subroutines.

ND1 — The number of sound-speed profile depths to be read in for the water layer (not to exceed 150).

ND2 — The number of sound-speed profile depths to be read in for the sediment layer (not to exceed 150).

Z1(I), C1(I) — The arrays for the depth (m) and sound speed (m/s), respectively, profile values of the water layer.

Z2(I), C2(I) — The arrays for the depth (m) and sound speed (m/s), respectively, profile values of the sediment layer.

Notes: The following conditions must be met: $Z1(1) = 0$; $Z1(ND1) = Z2(1) = H11$ (or $H12$, if range $r \neq 0$); $Z2(ND2) = H11 + H2$ (or $H12 + H2$). Since the program interpolates linearly for sound speeds between those given, it is sufficient to supply only the two bounding depths when there are three or more consecutive depth points having sound speed a linear function of depth.

For the user who knows only the type of material comprising the sediment, we include Table 2, as a guide in determining input values. The density of a given sediment type is suitable for the input variable RH02 as given. The velocity ratio, when multiplied by the value of C1(ND1), yields the value to be used for C2(1). If the attenuation coefficient (dB/m-kHz) is to be used for EP1 (supplied in dB/m-Hz), it must first be multiplied by 10^{-3} .

Table 2^a — Sediment Layer Parameters

Sediment Type	Density (g/cm ³)	Porosity (%)	Velocity Ratio	Atten. Coeff. (dB/m-kHz)
Coarse sand	2.034	38.6	1.201	0.47
Fine sand	1.957	44.8	1.147	0.51
Very fine sand	1.866	49.8	1.111	0.68
Silty sand	1.806	53.8	1.091	0.69
Sandy silt	1.787	52.5	1.088	0.76
Silt	1.767	54.2	1.062	0.68
Sand-silt-clay	1.583	67.2	1.033	0.11
Clayey silt	1.469	72.6	1.011	0.08
Silty clay	1.421	75.9	0.994	0.07

^aCompiled by Anthony I. Eller and Frank Ingenito from data given in Refs. 9-12 — private communication

OUTPUT

Most of the input variables are also printed out, *via* WRITE statements that follow the corresponding READ statements in the code. This helps in error-checking and also serves to label the printout uniquely. The first page of printed output contains all of the input variables of group one (the three groups of input variables are discussed in the "INPUT DATA" section) except for the variable III. The value of III is reflected, however, in the inclusion or omission (on the second printed page) of the shear and Rayleigh velocities. Apart from the latter, which is a calculated quantity, the second page of output contains only the values of variables of the second input group.

Beginning on the third page are the calculated modal properties of each of the normal modes supported by the environment given on the second page. The FORTRAN WRITE commands for this output are located near the end of SUBROUTINE SOLID (or FLUID). For each mode, the mode-order and phase velocity are first printed out. Also printed is the number of iterate solutions, *i.e.*, the number of times that SUBROUTINE HALFS (or HALFF) called SUBROUTINE ITRTS (or ITRTF) in order to converge to the correct eigenvalue. Also printed on the same line is the number of times that the eigenfunction had to be scaled down, according to the technique described in Appendix A. The last two lines for a given mode contain, from left to right, the label and value for each of the following quantities: the wave number (eigenvalue k_n), the water absorption α_n , the sediment-layer attenuation ratio $\gamma_n^{(2)}$, the basement compressional attenuation ratio $\gamma_n^{(3c)}$, the basement shear attenuation ratio $\gamma_n^{(3s)}$ (included only for the solid-basement model), the air/water scattering attenuation ratio $\Gamma_{0,n}$, and the water/sediment scattering attenuation ratio $\Gamma_{1,n}$.

In addition to the modal output described in the last paragraph, there are several statements which are conditionally printed for each mode. The statement "UPPER AMPLITUDES MATCHED FOR THIS MODE STARTING AT NORMALIZED DEPTH = " will be printed out (along with the appropriate value of the normalized depth z_m) if the eigenfunction $u_n(z)$ has been calculated for $z < z_m$ according to the procedure described in Appendix A. The remaining conditional statements are "LAYER 2 ATTEN RATIO = DEFAULT ZERO" and similar statements for the compressional and/or shear attenuation ratios. These statements are printed out only if during their calculation they were determined to be small enough to be set to zero.

After the modal parameters and flags have been printed out for each mode, and if MDPRT = 1, the eigenfunctions are printed out. (If MDPRT = 0, they are not printed out.) They are printed out in columnar form, twelve to a page, with depth increasing down the page. (The first column contains the values of the normalized depth for each line.)

If the problem is a range-dependent one, the second environment (*i.e.*, the one at the first nonzero input range) and the normal-mode parameters for it are next printed out in a format identical to the first (receiver) environment.

Next to be printed out are the transmission loss calculations for the output ranges which fall between the first and second environments. (For a range-independent problem, there is no second environment, and all the transmission-loss calculations follow the output for the receiver environment.) If there is a third input range, its environmental and modal parameters are printed next, followed by loss calculations at output ranges between the second and third input ranges. This procedure is repeated until the output ranges have been exhausted.

For those pages containing the calculated loss, the coherent transmission loss is printed on the left sides of the pages; the incoherent transmission loss is printed on the right sides of the pages. The format for each is as follows. The calculations for each output range are grouped together. Following the line on which the value of this range is printed is a "group" of output for each source depth, which is also printed out. This "group" will be only one line if there are five or fewer receiver depths. (If there

are between six and ten receiver depths, there will be two lines, *etc.*) Each line contains the transmission loss for up to five values of the receiver depth. If there are fewer than an integral multiple of five receiver depths, the line is "filled out" with indeterminate form data (*i.e.*, a string of the letter "I"). The procedure for filling variables with indeterminate form data prior to execution is machine-dependent and is not described here. The transmission loss is not labeled with receiver depth, but the depths are in order of decreasing depth, as printed out on the first page of output.

We now include, on the following pages, the computer output (described in general above) for two dissimilar test cases. The differences, summarized in Table 3, illustrate many of the options available to the user.

Table 3 — Summary of Differences Between Test Cases 1 and 2

Item	Test Case 1 (for Fig. 2)	Test Case 2
Type of model	Range-independent environment	Range-dependent environment
Type of environment	2-layer fluid-basement	3-layer solid-basement
Surface and bottom scattering	No	Yes
No. of output ranges	200	10
Plots	Yes	No
No. of source depths	1	2
No. of receiver depths	3	2
Receiver in the sediment layer	No	Yes
Sound speed profile in water and sediment layers	Isovelocity	Depth-dependent
Frequency	20 Hz	100 Hz
No. of modes	6	19, 22, 24 (3 environments)
Eigenfunctions printed out	Yes	No

Note that test case 1 calls for plots of transmission loss. These plots have already been presented as Fig. 2 (see the "THEORY" section). Note also that test case 1 asks for transmission-loss calculations at 200 range points. We include only the first and last page of calculated results here. The 23 intervening pages of output have been deleted.

ACKNOWLEDGMENTS

The authors would like to thank their colleagues, Frank Ingenito, Anthony Eller, William Kuperman, and David Nutile for the numerous helpful suggestions they made while this program was being developed.

***** TRANSMISSION LOSS *****
TEST CASE NUMBER 1 (FOR FIG. 2)

NUMBER OF FREQUENCIES = 1

NO. PROFILES	NO. CALCULATION RANGES	MAXIMUM RANGE	EP1	EP2	EP3	SIG0	SIG1
1	200	80000.000	0.0006800	0.0006800	0.0000000	0.0000000	0.0000000

I PLOT = 1 DBMIN = 45.000 DBMAX = 115.000 DY = 14.0000000 DX = 10.0000000

1 SOURCE DEPTHS(S)
100.000

3 RECEIVER DEPTHS(S)
10.000
200.000
400.000

SOURCE FREQUENCY = 20.000

TEST CASE 1 PROFILE

MDPRNT = 1 INCI = 2 INC2 = 1 RH01 = 1.000 RH02 = 1.870 RH03 = 1.870 M1 = 520.000 M2 = 10.000
EPSLN = 0.00010000 RANGE = 0.000 L11 = 100 L12 = 6 MD1 = 2 MD2 = 2

COMPRESSIONAL VELOCITY
1666.000

SOUND SPEED PROFILE	
DEPTH	VELOCITY
0.000	1500.000
1.000	1500.000
1.000	520.000
1.019	1666.000
1.019	1666.000

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<p>MODE NO. = 1 NUMBER OF ITERATE SOLUTIONS = 15 WAVE NUMBER 0.8359469310610-01 WATER ABSORPTION 0.5540E-08 PHASE VELOCITY = 0.150324980539D 04 THE EIGENFUNCTION WAS SCALED DOWN LAYER 2 ATTEN RATIO 0.9142E-03 LAYER 3 ATTEN RATIO 0.8659E-03</p>	<p>MAXIMUM NUMBER OF MODES = 6 NUMBER OF MODES CALCULATED = 6</p>	<p>AIR/H2O SCATTER 0.5789E-04 H2O/2ND SCATTER 0.5784E-04</p>
<p>MODE NO. = 2 NUMBER OF ITERATE SOLUTIONS = 19 WAVE NUMBER 0.830438056033D-01 WATER ABSORPTION 0.5548E-08 PHASE VELOCITY = 0.151322191018D 04 THE EIGENFUNCTION WAS SCALED DOWN LAYER 2 ATTEN RATIO 0.3250E-02 LAYER 3 ATTEN RATIO 0.3240E-02</p>		<p>AIR/H2O SCATTER 0.1183E-03 H2O/2ND SCATTER 0.1179E-03</p>
<p>MODE NO. = 3 NUMBER OF ITERATE SOLUTIONS = 16 WAVE NUMBER 0.821039451879D-01 WATER ABSORPTION 0.5572E-08 PHASE VELOCITY = 0.153054406650D 04 THE EIGENFUNCTION WAS SCALED DOWN LAYER 2 ATTEN RATIO 0.6217E-02 LAYER 3 ATTEN RATIO 0.6812E-02</p>		<p>AIR/H2O SCATTER 0.1827E-03 H2O/2ND SCATTER 0.1815E-03</p>
<p>MODE NO. = 4 NUMBER OF ITERATE SOLUTIONS = 14 WAVE NUMBER 0.807507249729D-01 WATER ABSORPTION 0.5617E-08 PHASE VELOCITY = 0.155619291574D 04 THE EIGENFUNCTION WAS SCALED DOWN LAYER 2 ATTEN RATIO 0.9276E-02 LAYER 3 ATTEN RATIO 0.1189E-01</p>		<p>AIR/H2O SCATTER 0.2518E-03 H2O/2ND SCATTER 0.2492E-03</p>
<p>MODE NO. = 5 NUMBER OF ITERATE SOLUTIONS = 14 WAVE NUMBER 0.789597249784D-01 WATER ABSORPTION 0.5674E-08 PHASE VELOCITY = 0.15914911836D 04 THE EIGENFUNCTION WAS SCALED DOWN LAYER 2 ATTEN RATIO 0.81232E-01 LAYER 3 ATTEN RATIO 0.2609E-01</p>		<p>AIR/H2O SCATTER 0.3254E-03 H2O/2ND SCATTER 0.3206E-03</p>
<p>MODE NO. = 6 NUMBER OF ITERATE SOLUTIONS = 14 WAVE NUMBER 0.767200567659D-01 WATER ABSORPTION 0.5658E-08 PHASE VELOCITY = 0.163795116220D 04 THE EIGENFUNCTION WAS SCALED DOWN LAYER 2 ATTEN RATIO 0.1552E-01 LAYER 3 ATTEN RATIO 0.4796E-01</p>		<p>AIR/H2O SCATTER 0.3977E-03 H2O/2ND SCATTER 0.3896E-03</p>

MODE AMPLITUDES FOR THE SOURCE FREQUENCY OF 20.000 MHZ.
FIRST LAYER

DEPTH	1MODE AMPLITUDE	2MODE AMPLITUDE	3MODE AMPLITUDE	4MODE AMPLITUDE	5MODE AMPLITUDE	6MODE AMPLITUDE
0.0000	-0.0000	-0.0000	-0.0000	0.0000	-0.0000	0.0000
0.0200	0.0774	-0.1557	0.2353	-0.3152	0.3939	-0.4662
0.0400	0.1545	-0.3094	0.4635	-0.6135	0.7546	-0.8758
0.0600	0.2311	-0.4590	0.6779	-0.8769	1.0518	-1.1793
0.0800	0.3069	-0.6026	0.8720	-1.0972	1.2605	-1.3397
0.1000	0.3817	-0.7382	1.0400	-1.2567	1.3630	-1.3378
0.1200	0.4553	-0.8640	1.1769	-1.3489	1.3509	-1.1737
0.1400	0.5274	-0.9185	1.2785	-1.3688	1.2250	-0.8673
0.1600	0.5978	-1.0001	1.3420	-1.3153	0.9960	-0.4557
0.1800	0.6662	-1.1074	1.3652	-1.1913	0.6832	0.0111
0.2000	0.7324	-1.2393	1.3476	-1.0035	0.3129	0.4766
0.2200	0.7962	-1.2948	1.2897	-0.7619	-0.0838	0.8843
0.2400	0.8574	-1.3333	1.1937	-0.4795	-0.4734	1.1848
0.2600	0.9158	-1.3542	1.0610	-0.1714	-0.8232	1.3416
0.2800	0.9712	-1.3572	0.8971	0.1459	-1.0336	1.3358
0.3000	1.0234	-1.3423	0.7063	0.4554	-1.2912	1.1680
0.3200	1.0723	-1.3097	0.4944	0.7405	-1.3701	0.8587
0.3400	1.1177	-1.2598	0.2677	0.9859	-1.3337	0.4452
0.3600	1.1593	-1.1933	0.0329	1.1784	-1.1850	-0.0223
0.3800	1.1972	-1.1111	-0.2028	1.3078	-0.9366	-0.4870
0.4000	1.2312	-1.0142	-0.4324	1.3672	-0.6093	-0.8921
0.4200	1.2611	-0.9039	-0.6491	1.3532	-0.2307	-1.1902
0.4400	1.2869	-0.7817	-0.8464	1.2668	0.1672	-1.3433
0.4600	1.3085	-0.6492	-1.0184	1.1124	0.5511	-1.3337
0.4800	1.3257	-0.5081	-1.1598	0.8984	0.8886	-1.1623
0.5000	1.3387	-0.3603	-1.2666	0.6363	1.1514	-0.8500
0.5200	1.3472	-0.2077	-1.3355	0.3401	1.3172	-0.4347
0.5400	1.3514	-0.0525	-1.3644	0.0257	1.3721	0.0334
0.5600	1.3511	0.1035	-1.3525	-0.2902	1.3115	0.4974
0.5800	1.3463	0.2581	-1.3002	-0.5904	1.1406	0.9011
0.6000	1.3372	0.4093	-1.2089	-0.8590	0.8736	1.1995
0.6200	1.3237	0.5551	-1.0814	-1.0816	0.5331	1.3450
0.6400	1.3058	0.6936	-0.9216	-1.2463	0.1477	1.3315
0.6600	1.2837	0.8229	-0.7343	-1.3441	-0.2501	1.1565
0.6800	1.2573	0.9414	-0.5249	-1.3699	-0.6268	0.6413
0.7000	1.2269	1.0474	-0.2999	-1.3223	-0.9508	0.4241
0.7200	1.1924	1.1397	-0.0658	-1.2038	-1.1948	-0.0445
0.7400	1.1540	1.2169	0.1702	-1.0208	-1.3382	-0.5077
0.7600	1.1118	1.2780	0.4011	-0.7831	-1.3689	-0.8094
0.7800	1.0660	1.3223	0.6200	-0.5035	-1.2844	-1.2008
0.8000	1.0167	1.3491	0.8203	-0.1968	-1.0919	-1.3466
0.8200	0.9640	1.3582	0.9961	0.1204	-0.8074	-1.3292
0.8400	0.9082	1.3493	1.1421	0.4311	-0.4549	-1.1506
0.8600	0.8494	1.3226	1.2540	0.7187	-0.0642	-0.8325
0.8800	0.7878	1.2769	1.3283	0.9679	0.3320	-0.4135
0.9000	0.7237	1.2175	1.3628	1.1651	0.7002	0.0556
0.9200	0.6572	1.1404	1.3566	1.2999	1.0094	0.5180
0.9400	0.5885	1.0483	1.3098	1.3651	1.2337	0.9176
0.9600	0.5179	0.9424	1.2238	1.3571	1.3442	1.2060
0.9800	0.4456	0.8240	1.1012	1.2763	1.3607	1.3481
1.0000	0.3718	0.6947	0.9457	1.1272	1.2576	1.3268

MILLER AND WOLF

MODE AMPLITUDES FOR THE SOURCE FREQUENCY OF 20.000 HZ.
SECOND LAYER

DEPTH	1 ST MODE AMPLITUDE	2 ND MODE AMPLITUDE	3 RD MODE AMPLITUDE	4 TH MODE AMPLITUDE	5 TH MODE AMPLITUDE	6 TH MODE AMPLITUDE
1.0000	0.1988	0.3715	0.5057	0.6028	0.6698	0.7095
1.0032	0.1872	0.3506	0.4791	0.5745	0.6443	0.6931
1.0064	0.1763	0.3309	0.4539	0.5476	0.6197	0.6771
1.0096	0.1660	0.3123	0.4300	0.5219	0.5960	0.6615
1.0128	0.1564	0.2947	0.4074	0.4974	0.5733	0.6462
1.0160	0.1473	0.2782	0.3860	0.4741	0.5514	0.6313
1.0192	0.1387	0.2625	0.3657	0.4518	0.5304	0.6167

INCOHERENT TRANSMISSION LOSS
LOSS IN DB

RANGE(M) = 400.0
SOURCE DEPTH(M) = 100.000
53.14 54.72 55.00 I IIIII I IIIII

RANGE(M) = 800.0
SOURCE DEPTH(M) = 100.000
56.23 57.80 58.08 I IIIII I IIIII

RANGE(M) = 1200.0
SOURCE DEPTH(M) = 100.000
58.08 59.64 59.90 I IIIII I IIIII

RANGE(M) = 1600.0
SOURCE DEPTH(M) = 100.000
59.41 60.96 61.21 I IIIII I IIIII

RANGE(M) = 2000.0
SOURCE DEPTH(M) = 100.000
60.46 62.00 62.24 I IIIII I IIIII

RANGE(M) = 2400.0
SOURCE DEPTH(M) = 100.000
61.34 62.86 63.09 I IIIII I IIIII

RANGE(M) = 2800.0
SOURCE DEPTH(M) = 100.000
62.09 63.60 63.82 I IIIII I IIIII

RANGE(M) = 3200.0
SOURCE DEPTH(M) = 100.000

COHERENT TRANSMISSION LOSS
(LOSS IN DB, PHASE IN DEGREES)

RANGE(M) = 400.0
SOURCE DEPTH(M) = 100.000
(48.13/ 76.092) (54.51/ 163.416) (66.48/ 118.902) (IIIII/IIIIIIII) (IIIII/IIIIIIII)

RANGE(M) = 800.0
SOURCE DEPTH(M) = 100.000
(54.79/ 148.907) (54.80/ 241.256) (63.13/ 113.484) (IIIII/IIIIIIII) (IIIII/IIIIIIII)

RANGE(M) = 1200.0
SOURCE DEPTH(M) = 100.000
(63.86/ 258.699) (56.18/ 330.446) (61.96/ 154.769) (IIIII/IIIIIIII) (IIIII/IIIIIIII)

RANGE(M) = 1600.0
SOURCE DEPTH(M) = 100.000
(64.87/ 8.078) (58.69/ 58.893) (61.67/ 226.057) (IIIII/IIIIIIII) (IIIII/IIIIIIII)

RANGE(M) = 2000.0
SOURCE DEPTH(M) = 100.000
(76.48/ 96.168) (62.99/ 158.679) (62.36/ 296.950) (IIIII/IIIIIIII) (IIIII/IIIIIIII)

RANGE(M) = 2400.0
SOURCE DEPTH(M) = 100.000
(69.76/ 282.186) (67.64/ 262.764) (70.92/ 30.447) (IIIII/IIIIIIII) (IIIII/IIIIIIII)

RANGE(M) = 2800.0
SOURCE DEPTH(M) = 100.000
(68.06/ 345.787) (72.57/ 86.634) (64.88/ 194.353) (IIIII/IIIIIIII) (IIIII/IIIIIIII)

RANGE(M) = 3200.0
SOURCE DEPTH(M) = 100.000

MILLER AND WOLF

SOURCE DEPTH(M) = 100.000
87.76 85.34 84.98 IHHIII IHHIII

RANGE(M) = 79600.0
SOURCE DEPTH(M) = 100.000
87.82 85.38 85.03 IHHIII IHHIII

RANGE(M) = 80000.0
SOURCE DEPTH(M) = 100.000
87.88 85.42 85.08 IHHIII IHHIII

SOURCE DEPTH(M) = 100.000
(83.81/ 291.096) (83.20/ 260.794) (107.63/ 192.731) (IHHIII/IHHIII) (IHHIII/IHHIII)

RANGE(M) = 79600.0
SOURCE DEPTH(M) = 100.000
(83.06/ 27.604) (83.62/ 16.295) (106.73/ 357.067) (IHHIII/IHHIII) (IHHIII/IHHIII)

RANGE(M) = 80000.0
SOURCE DEPTH(M) = 100.000
(83.22/ 124.524) (83.24/ 131.807) (108.71/ 158.472) (IHHIII/IHHIII) (IHHIII/IHHIII)

***** TRANSMISSION LOSS *****

TEST CASE NUMBER 2

NUMBER OF FREQUENCIES = 1

NUM. PUFFLES	NO. CALCULATION RANGES	MAXIMUM RANGE	EPI	EP2	EP3	SIG0	SIG1
3	10	50000.000	0.0005100	0.0000500	0.0000550	0.1000000	0.1090000

IPLOT = 0 DBMIN = 0.000 DBMAX = 0.000 DY = 0.0000000 DX = 0.0000000

2 SOURCE DEPTH(S)
 70.000
 140.000

2 RECEIVER DEPTH(S)
 140.000
 160.000

MILLER AND WOLF

TEST CASE > PR*FILFS
 SOURCE FREQUENCY = 100.000
 MDPRNT = 0 INCL = 0 INC = 0 RHO1 = 1.000 RHO2 = 1.957 RHO3 = 2.500 H1 = 150.000 H2 = 50.000
 EPSLN = 0.000100000 PANGF = 0.000 L11 = 250 L12 = 90 MD1 = 5 MD2 = 2

COMPRESSIONAL VELOCITY 3800.000
 SHEAR VELOCITY 2194.000
 RAYLEIGH VELOCITY 2017.159

SOUND SPEED PROFILE

DEPTH	VELOCITY
0.000	1500.000
0.123	1500.000
0.333	1489.000
0.560	1486.000
1.000	1486.000
1.000	1705.000
1.333	1730.000

MAXIMUM NUMBER OF MODES = 19 NUMBER OF MODES CALCULATED = 19

MODE NO. = 1 PHASE VELOCITY = 0.148964396860 04
 NUMBER OF ITERATE SOLUTIONS = 19 THE EIGENFUNCTION WAS SCALED DOWN 0 TIME(S)
 WAVE NUMBER WATER ABSORPTION LAYER 2 ATTEN RATIO COMP ATTEN RATIO SHEAR ATTEN RATIO AIR/H2O SCATTER H2O/2ND SCATTER
 0.4220745761170 00 0.1373E-04 0.9013E-03 0.2063E-09 0.2227E-09 0.0000E 00 0.2290E-03

MODE NO. = 2 PHASE VELOCITY = 0.149542688260 04
 NUMBER OF ITERATE SOLUTIONS = 21 THE EIGENFUNCTION WAS SCALED DOWN 0 TIME(S)
 WAVE NUMBER WATER ABSORPTION LAYER 2 ATTEN RATIO COMP ATTEN RATIO SHEAR ATTEN RATIO AIR/H2O SCATTER H2O/2ND SCATTER
 0.4201599411870 00 0.1376E-06 9.2491E-02 0.1591E-08 0.1731E-08 0.0000E 00 0.3639E-03

MODE NO. = 3 PHASE VELOCITY = 0.1504817551420 04
 NUMBER OF ITERATE SOLUTIONS = 16 THE EIGENFUNCTION WAS SCALED DOWN 0 TIME(S)
 WAVE NUMBER WATER ABSORPTION LAYER 2 ATTEN RATIO COMP ATTEN RATIO SHEAR ATTEN RATIO AIR/H2O SCATTER H2O/2ND SCATTER
 0.4175380137490 00 0.1380E-06 0.4186E-02 0.2300E-07 0.2531E-07 0.3662E-03 0.4769E-03

MODE NO. = 4 PHASE VELOCITY = 0.1511915298300 04
 NUMBER OF ITERATE SOLUTIONS = 22 THE EIGENFUNCTION WAS SCALED DOWN 0 TIME(S)
 WAVE NUMBER WATER ABSORPTION LAYER 2 ATTEN RATIO COMP ATTEN RATIO SHEAR ATTEN RATIO AIR/H2O SCATTER H2O/2ND SCATTER
 0.4155778643320 00 0.4106E-13 0.5248E 00 0.4597E 00 0.5104E 00 0.1494E-09 0.1145E-09

MODE NO. = 5 PHASE VELOCITY = 0.1517234283490 04
 NUMBER OF ITERATE SOLUTIONS = 22 THE EIGENFUNCTION WAS SCALED DOWN 0 TIME(S)
 WAVE NUMBER WATER ABSORPTION LAYER 2 ATTEN RATIO COMP ATTEN RATIO SHEAR ATTEN RATIO AIR/H2O SCATTER H2O/2ND SCATTER
 0.4141482646290 00 0.1398E-06 0.6119E-02 0.1149E-06 0.1294E-06 0.5684E-03 0.6012E-03

MODE NO. = 6 PHASE VELOCITY = 0.152292536230 04
 NUMBER OF ITERATE SOLUTIONS = 16 THE EIGENFUNCTION WAS SCALED DOWN 0 TIME(S)
 WAVE NUMBER WATER ABSORPTION LAYER 2 ATTEN RATIO COMP ATTEN RATIO SHEAR ATTEN RATIO AIR/H2O SCATTER H2O/2ND SCATTER
 0.4098747655630 00 0.1399E-06 0.4653E-02 0.2212E-07 0.2520E-07 0.7774E-03 0.7679E-03

MILLER AND WOLF

MODE NO. = 7 PHASE VELOCITY = 0.15533247311D 04
 NUMBER OF ITERATE SOLUTIONS = 19 THE EIGENFUNCTION WAS SCALED DOWN 0 TIME(S)
 WAVE NUMBER WATER ABSORPTION LAYER 2 ATTEN RATIO COMP ATTEN RATIO SHEAR ATTEN RATIO H2O/2ND SCATTER
 0.4044941214L 00 0.1413E-06 0.1159E-01 0.2145E-07 0.2510E-07 0.9515E-03 0.9439E-03

MODE NO. = 8 PHASE VELOCITY = 0.157871738272D 04
 NUMBER OF ITERATE SOLUTIONS = 16 THE EIGENFUNCTION WAS SCALED DOWN 0 TIME(S)
 WAVE NUMBER WATER ABSORPTION LAYER 2 ATTEN RATIO COMP ATTEN RATIO SHEAR ATTEN RATIO H2O/2ND SCATTER
 0.39799304C170D 00 0.1431E-06 0.1508E-01 0.3969E-07 0.4808E-07 0.1142E-02 0.1123E-02

MODE NO. = 9 PHASE VELOCITY = 0.16096720789D 04
 NUMBER OF ITERATE SOLUTIONS = 22 THE EIGENFUNCTION WAS SCALED DOWN 0 TIME(S)
 WAVE NUMBER WATER ABSORPTION LAYER 2 ATTEN RATIO COMP ATTEN RATIO SHEAR ATTEN RATIO H2O/2ND SCATTER
 0.390339460415D 00 0.1452E-06 0.1990E-01 0.1267E-06 0.1605E-06 0.1329E-02 0.1313E-02

MODE NO. = 10 PHASE VELOCITY = 0.164715836708D 04
 NUMBER OF ITERATE SOLUTIONS = 18 THE EIGENFUNCTION WAS SCALED DOWN 0 TIME(S)
 WAVE NUMBER WATER ABSORPTION LAYER 2 ATTEN RATIO COMP ATTEN RATIO SHEAR ATTEN RATIO H2O/2ND SCATTER
 0.381456053917C 00 0.1473E-06 0.2824E-01 0.7730E-06 0.1037E-05 0.1518E-02 0.1513E-02

MODE NO. = 11 PHASE VELOCITY = 0.169191719732D 04
 NUMBER OF ITERATE SOLUTIONS = 20 THE EIGENFUNCTION WAS SCALED DOWN 0 TIME(S)
 WAVE NUMBER WATER ABSORPTION LAYER 2 ATTEN RATIO COMP ATTEN RATIO SHEAR ATTEN RATIO H2O/2ND SCATTER
 0.371364823122C 00 0.1477E-06 0.5220E-01 0.1319E-04 0.1909E-04 0.1706E-02 0.1691E-02

MODE NO. = 12 PHASE VELOCITY = 0.17384186001D 04
 NUMBER OF ITERATE SOLUTIONS = 24 THE EIGENFUNCTION WAS SCALED DOWN 0 TIME(S)
 WAVE NUMBER WATER ABSORPTION LAYER 2 ATTEN RATIO COMP ATTEN RATIO SHEAR ATTEN RATIO H2O/2ND SCATTER
 0.36143109C713D 00 0.7369E-07 0.5441E 00 0.2276E-02 0.3593E-02 0.9403E-03 0.9311E-03

MAXIMUM NUMBER OF MODES = 19 NUMBER OF MODES CALCULATED = 19

MODE NO. = 13 NUMBER OF ITERATE SOLUTIONS = 18 WAVE NUMBER 0.3581502997040 00	PHASE VELOCITY = 0.1754299187400 04 THE EIGENFUNCTION WAS SCALED DOWN 0 TIME(S) WATER ABSORPTION LAYER 2 ATTEN RATIO 0.4624E 00	SCALED DOWN 0 TIME(S) COMP ATTEN RATIO 0.4032E-02	SHEAR ATTEN RATIO 0.6572E-02	AIR/H2O SCATTER 0.1120E-02	H2O/2ND SCATTER 0.1109E-02
MODE NO. = 14 NUMBER OF ITERATE SOLUTIONS = 20 WAVE NUMBER 0.3473954009640 00	PHASE VELOCITY = 0.1808707357800 04 THE EIGENFUNCTION WAS SCALED DOWN 0 TIME(S) WATER ABSORPTION LAYER 2 ATTEN RATIO 0.1223E-06	SCALED DOWN 0 TIME(S) COMP ATTEN RATIO 0.4694E-02	SHEAR ATTEN RATIO 0.8627E-02	AIR/H2O SCATTER 0.1714E-02	H2O/2ND SCATTER 0.1694E-02
MODE NO. = 15 NUMBER OF ITERATE SOLUTIONS = 18 WAVE NUMBER 0.3407839429360 00	PHASE VELOCITY = 0.1843744530050 04 THE EIGENFUNCTION WAS SCALED DOWN 0 TIME(S) WATER ABSORPTION LAYER 2 ATTEN RATIO 9.6121E-07	SCALED DOWN 0 TIME(S) COMP ATTEN RATIO 0.1613E-01	SHEAR ATTEN RATIO 0.3233E-01	AIR/H2O SCATTER 0.8780E-03	H2O/2ND SCATTER 0.8616E-03
MODE NO. = 16 NUMBER OF ITERATE SOLUTIONS = 13 WAVE NUMBER 0.3307162407050 00	PHASE VELOCITY = 0.1902172688020 04 THE EIGENFUNCTION WAS SCALED DOWN 0 TIME(S) WATER ABSORPTION LAYER 2 ATTEN RATIO 0.1476E-06	SCALED DOWN 0 TIME(S) COMP ATTEN RATIO 0.5296E-02	SHEAR ATTEN RATIO 0.1255E-01	AIR/H2O SCATTER 0.2261E-02	H2O/2ND SCATTER 0.2224E-02
MODE NO. = 17 NUMBER OF ITERATE SOLUTIONS = 16 WAVE NUMBER 0.3171198757470 00	PHASE VELOCITY = 0.1981328131000 04 THE EIGENFUNCTION WAS SCALED DOWN 0 TIME(S) WATER ABSORPTION LAYER 2 ATTEN RATIO 9.4632E 00	SCALED DOWN 0 TIME(S) COMP ATTEN RATIO 0.1791E-01	SHEAR ATTEN RATIO 0.5665E-01	AIR/H2O SCATTER 0.1626E-02	H2O/2ND SCATTER 0.1589E-02
MODE NO. = 18 NUMBER OF ITERATE SOLUTIONS = 16 WAVE NUMBER 0.3088260032250 00	PHASE VELOCITY = 0.2034538944770 04 THE EIGENFUNCTION WAS SCALED DOWN 0 TIME(S) WATER ABSORPTION LAYER 2 ATTEN RATIO 0.1079E-06	SCALED DOWN 0 TIME(S) COMP ATTEN RATIO 0.1822E-01	SHEAR ATTEN RATIO 0.7451E-01	AIR/H2O SCATTER 0.1800E-02	H2O/2ND SCATTER 0.1759E-02

MILLER AND WOLF

MODE NO. = 19 PHASE VELOCITY = 0.2140168491350 04
NUMBER OF ITERATE SOLUTIONS = 14 THE EIGENFUNCTION WAS SCALED DOWN 0 TIME(S)
WAVE NUMBER WATER ABSORPTION LAYER 2 ATTEN RATIO COMP ATTEN RATIO SHEAR ATTEN RATIO H2O/2ND SCATTER
0.7935376749570 00 0.1515E-06 9.1965E 00 0.7030E-02 0.7001E-01 0.2706E-02 0.2648E-02

M2 = 50.000

M1 = 190.000

RHC3 = 2.500
MD1 = 6

RH02 = 1.957
LIZ = 90

RH01 = 1.000
LII = 250

INC2 = 0
RANGE = 18000.000

INC1 = 0

EPSLN = 0.00010000

RAYLEIGH VELOCITY
2017.159

SHEAR VELOCITY
2196.000

COMPRESSIONAL VELOCITY
3800.000

SOUND SPEED PROFILE

DEPTH	VELOCITY
0.000	1500.000
0.103	1500.000
0.278	1489.000
0.467	1486.000
0.833	1482.000
1.000	1492.000
1.000	1700.000
1.278	1775.000

MILLER AND WOLF

MAXIMUM NUMBER OF MODES = 22 NUMBER OF MODES CALCULATED = 19

MODE NO. = 1 PHASE VELOCITY = 0.148559946491D 04 THE EIGENFUNCTION WAS SCALED DOWN 0 TIME(S)
 NUMBER OF ITERATE SOLUTIONS = 19 WATER ABSORPTION LAYER 2 ATTEN RATIO COMP ATTEN RATIO SHEAR ATTEN RATIO
 WAVE NUMBER 0.422939398491D 00 0.1373E-06 0.2411E-09 0.2593E-09 0.0000E 00 H2O/2ND SCATTER
 0.2534E-03

MODE NO. = 2 PHASE VELOCITY = 0.149099607821D 04 THE EIGENFUNCTION WAS SCALED DOWN 0 TIME(S)
 NUMBER OF ITERATE SOLUTIONS = 19 WATER ABSORPTION LAYER 2 ATTEN RATIO COMP ATTEN RATIO SHEAR ATTEN RATIO
 WAVE NUMBER 0.42140957705C 00 0.1375E-06 0.1773E-02 0.8039E-09 0.0000E 00 H2O/2ND SCATTER
 0.2637E-03

MODE NO. = 3 PHASE VELOCITY = 0.149791828530D 04 THE EIGENFUNCTION WAS SCALED DOWN 0 TIME(S)
 NUMBER OF ITERATE SOLUTIONS = 20 WATER ABSORPTION LAYER 2 ATTEN RATIO COMP ATTEN RATIO SHEAR ATTEN RATIO
 WAVE NUMBER 0.41945552265D 00 0.1378E-06 0.2888E-02 0.4629E-08 0.5053E-08 H2O/2ND SCATTER
 0.3475E-03

MODE NO. = 4 PHASE VELOCITY = 0.150687663359D 04 THE EIGENFUNCTION WAS SCALED DOWN 0 TIME(S)
 NUMBER OF ITERATE SOLUTIONS = 20 WATER ABSORPTION LAYER 2 ATTEN RATIO COMP ATTEN RATIO SHEAR ATTEN RATIO
 WAVE NUMBER 0.416969175759D 00 0.1394E-06 0.4178E-02 0.1639E-06 0.3402E-03 H2O/2ND SCATTER
 0.4369E-03

MODE NO. = 5 PHASE VELOCITY = 0.150989310314D 04 THE EIGENFUNCTION WAS SCALED DOWN 0 TIME(S)
 NUMBER OF ITERATE SOLUTIONS = 19 WATER ABSORPTION LAYER 2 ATTEN RATIO COMP ATTEN RATIO SHEAR ATTEN RATIO
 WAVE NUMBER 0.416134446480C 00 0.1623E-13 0.5286E 00 0.4576E 00 0.2202E-09 H2O/2ND SCATTER
 0.2648E-09

MODE NO. = 6 PHASE VELOCITY = 0.151790527314D 04 THE EIGENFUNCTION WAS SCALED DOWN 0 TIME(S)
 NUMBER OF ITERATE SOLUTIONS = 16 WATER ABSORPTION LAYER 2 ATTEN RATIO COMP ATTEN RATIO SHEAR ATTEN RATIO
 WAVE NUMBER 0.413937906294D 00 0.1391E-06 0.5607E-02 0.5452E-07 0.6097E-07 H2O/2ND SCATTER
 0.5309E-03

MODE NO. = 7 NUMBER OF ITERATE SOLUTIONS = 16 WAVE NUMBER 0.410750938951D 00	PHASE VELOCITY = 0.153154694380D 04 THE EIGENFUNCTION WAS SCALED DOWN 0 TIME(S) WATER ABSORPTION LAYER 2 ATTEN RATIO 0.7411E-02	COMP ATTN RATIO 0.1966E-07	SHEAR ATTN RATIO 0.2237E-07	AIR/H2O SCATTER 0.6530E-03	H2O/2ND SCATTER 0.6494E-03
MODE NO. = 8 NUMBER OF ITERATE SOLUTIONS = 20 WAVE NUMBER 0.405780147928E 00	PHASE VELOCITY = 0.154842106970D 04 THE EIGENFUNCTION WAS SCALED DOWN 0 TIME(S) WATER ABSORPTION LAYER 2 ATTEN RATIO 0.1414E-06	COMP ATTN RATIO 0.1875E-07	SHEAR ATTN RATIO 0.2180E-07	AIR/H2O SCATTER 0.7778E-03	H2O/2ND SCATTER 0.7736E-03
MODE NO. = 9 NUMBER OF ITERATE SOLUTIONS = 19 WAVE NUMBER 0.400528190166D 00	PHASE VELOCITY = 0.156872486418D 04 THE EIGENFUNCTION WAS SCALED DOWN 0 TIME(S) WATER ABSORPTION LAYER 2 ATTEN RATIO 0.1178E-01	COMP ATTN RATIO 0.2862E-07	SHEAR ATTN RATIO 0.3419E-07	AIR/H2O SCATTER 0.9127E-03	H2O/2ND SCATTER 0.8964E-05
MODE NO. = 10 NUMBER OF ITERATE SOLUTIONS = 20 WAVE NUMBER 0.394479013724D 00	PHASE VELOCITY = 0.159278062674D 04 THE EIGENFUNCTION WAS SCALED DOWN 0 TIME(S) WATER ABSORPTION LAYER 2 ATTEN RATIO 0.1476E-01	COMP ATTN RATIO 0.6443E-07	SHEAR ATTN RATIO 0.7962E-07	AIR/H2O SCATTER 0.1047E-02	H2O/2ND SCATTER 0.1027E-02
MODE NO. = 11 NUMBER OF ITERATE SOLUTIONS = 22 WAVE NUMBER 0.38759853316C 00	PHASE VELOCITY = 0.162109680744D 04 THE EIGENFUNCTION WAS SCALED DOWN 0 TIME(S) WATER ABSORPTION LAYER 2 ATTEN RATIO 0.1506E-01	COMP ATTN RATIO 0.2186E-06	SHEAR ATTN RATIO 0.2816E-06	AIR/H2O SCATTER 0.1177E-02	H2O/2ND SCATTER 0.1165E-02
MODE NO. = 12 NUMBER OF ITERATE SOLUTIONS = 19 WAVE NUMBER 0.379825501542D 00	PHASE VELOCITY = 0.165422945054D 04 THE EIGENFUNCTION WAS SCALED DOWN 0 TIME(S) WATER ABSORPTION LAYER 2 ATTEN RATIO 0.1484E-06	COMP ATTN RATIO 0.1253E-05	SHEAR ATTN RATIO 0.1701E-05	AIR/H2O SCATTER 0.1314E-02	H2O/2ND SCATTER 0.1305E-02

MILLER AND WOLF

NUMBER OF MODES CALCULATED = 19

MAXIMUM NUMBER OF MODES = 22

MODE NO. = 13 PHASE VELOCITY = 0.169256159484D 04
 NUMBER OF ITERATE SOLUTIONS = 22 THE EIGENFUNCTION WAS SCALED DOWN 0 TIME(S)
 WAVE NUMBER WATER ABSORPTION LAYER 2 ATTEN RATIO COMP ATTEN RATIO SHEAR ATTEN RATIO
 0.3717234350050 00 0.1494E-06 0.4923E-01 0.1716E-04 0.2486E-04
 H2O/2ND SCATTER
 0.1427E-02

MODE NO. = 14 PHASE VELOCITY = 0.173226970641D 04
 NUMBER OF ITERATE SOLUTIONS = 20 THE EIGENFUNCTION WAS SCALED DOWN 0 TIME(S)
 WAVE NUMBER WATER ABSORPTION LAYER 2 ATTEN RATIO COMP ATTEN RATIO SHEAR ATTEN RATIO
 0.362714037571C 00 0.8975E-07 0.4443E 00 0.1765E-02 0.2753E-02
 AIR/H2O SCATTER
 0.9460E-03
 H2O/2ND SCATTER
 0.9318E-03

MODE NO. = 15 PHASE VELOCITY = 0.174659530226D 04
 NUMBER OF ITERATE SOLUTIONS = 20 THE EIGENFUNCTION WAS SCALED DOWN 0 TIME(S)
 WAVE NUMBER WATER ABSORPTION LAYER 2 ATTEN RATIO COMP ATTEN RATIO SHEAR ATTEN RATIO
 0.359739047581D 00 0.7508E-07 0.5384E 00 0.4315E-02 0.6974E-02
 AIR/H2O SCATTER
 0.7982E-03
 H2O/2ND SCATTER
 0.7854E-03

MODE NO. = 16 PHASE VELOCITY = 0.179063933876D 04
 NUMBER OF ITERATE SOLUTIONS = 18 THE EIGENFUNCTION WAS SCALED DOWN 0 TIME(S)
 WAVE NUMBER WATER ABSORPTION LAYER 2 ATTEN RATIO COMP ATTEN RATIO SHEAR ATTEN RATIO
 0.350890616474D 00 0.1394E-06 0.1592E 00 0.2474E-02 0.4340E-02
 AIR/H2O SCATTER
 0.1599E-02
 H2O/2ND SCATTER
 0.1573E-02

MODE NO. = 17 PHASE VELOCITY = 0.182949463375D 04
 NUMBER OF ITERATE SOLUTIONS = 18 THE EIGENFUNCTION WAS SCALED DOWN 0 TIME(S)
 WAVE NUMBER WATER ABSORPTION LAYER 2 ATTEN RATIO COMP ATTEN RATIO SHEAR ATTEN RATIO
 0.343438302101D 00 0.6070E-07 0.6546E 00 0.1492E-01 0.2885E-01
 AIR/H2O SCATTER
 0.7316E-03
 H2O/2ND SCATTER
 0.7115E-03

MODE NO. = 18 PHASE VELOCITY = 0.186556641550D 04
 NUMBER OF ITERATE SOLUTIONS = 18 THE EIGENFUNCTION WAS SCALED DOWN 0 TIME(S)
 WAVE NUMBER WATER ABSORPTION LAYER 2 ATTEN RATIO COMP ATTEN RATIO SHEAR ATTEN RATIO
 0.336797728292E 00 0.1357E-06 0.2156E 00 0.6543E-02 0.1392E-01
 AIR/H2O SCATTER
 0.1681E-02
 H2O/2ND SCATTER
 0.1645E-02

MODE N1 = 19 PHASE VELOCITY = 0.193268796100 04
NUMBER OF ITERATE SPLITIONS = 15 THE EIGENFUNCTION WAS SCALED DOWN 0 TIMECS)
WAVE NUMBER WATER ABSORPTION LAYER 2 ATTEN RATIO COMP ATTEN RATIO SHEAR ATTEN RATIO AIR/P2C SCATTER MZ0/2ND SCATTER
0.3251099783040 00 0.1480E-06 0.1738E 00 0.6065E-02 0.1591E-01 0.1966E-02 0.1917E-02

INCOHERENT TRANSMISSION LOSS
LOSS IN DB

RANGE(M) = 5000.0
SOURCE DEPTH(M) = 70.000
63.09 76.47 IHHII IHHII IHHII
SOURCE DEPTH(M) = 140.000
61.96 75.35 IHHII IHHII IHHII

RANGE(M) = 10000.0
SOURCE DEPTH(M) = 70.000
66.98 83.51 IHHII IHHII IHHII
SOURCE DEPTH(M) = 140.000
66.07 82.85 IHHII IHHII IHHII

RANGE(M) = 15000.0
SOURCE DEPTH(M) = 70.000
69.14 87.82 IHHII IHHII IHHII
SOURCE DEPTH(M) = 140.000
69.09 87.86 IHHII IHHII IHHII

RANGE(M) = 20000.0
SOURCE DEPTH(M) = 70.000
70.74 90.55 IHHII IHHII IHHII
SOURCE DEPTH(M) = 140.000
72.04 91.48 IHHII IHHII IHHII

COHERENT TRANSMISSION LOSS
(LOSS IN DB, PHASE IN DEGREES)

RANGE(M) = 5000.0
SOURCE DEPTH(M) = 70.000
(59.19/ 352.366) (77.91/ 283.863) (IHHII/IHHII) (IHHII/IHHII)
SOURCE DEPTH(M) = 140.000
(61.35/ 175.467) (78.42/ 193.384) (IHHII/IHHII) (IHHII/IHHII)

RANGE(M) = 10000.0
EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MODE NO. 15
SOURCE DEPTH(M) = 70.000
(65.59/ 777.290) (84.65/ 267.595) (IHHII/IHHII) (IHHII/IHHII)
SOURCE DEPTH(M) = 140.000
(64.15/ 102.153) (79.51/ 114.290) (IHHII/IHHII) (IHHII/IHHII)

RANGE(M) = 15000.0
EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MODE NO. 15
EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MODE NO. 17
SOURCE DEPTH(M) = 70.000
(67.10/ 293.924) (84.69/ 319.461) (IHHII/IHHII) (IHHII/IHHII)
SOURCE DEPTH(M) = 140.000
(76.06/ 136.311) (98.88/ 195.953) (IHHII/IHHII) (IHHII/IHHII)

RANGE(M) = 20000.0
EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MODE NO. 4
EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MODE NO. 5
EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MODE NO. 14
EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MODE NO. 15
EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MODE NO. 17
EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MODE NO. 18
SOURCE DEPTH(M) = 70.000
(71.59/ 94.362) (97.97/ 131.717) (IHHII/IHHII) (IHHII/IHHII)
SOURCE DEPTH(M) = 140.000
(78.91/ 60.528) (91.02/ 106.087) (IHHII/IHHII) (IHHII/IHHII)

MDPRMT = 0 INCL = 0 INC2 = 0 RANGF = 50000.000 RMD1 = 1.000 RMD2 = 1.957 RMD3 = 2.500 H1 = 200.000 H2 = 50.000
 EPSLN = 0.00010000 RANGF = 50000.000 LII = 250 LI2 = 90 MD1 = 6 MD2 = 2

COMPRESSIONAL VELOCITY SHEAR VELOCITY RAYLEIGH VELOCITY
 3800.000 2194.000 2017.159

SOUND SPEED PROFILE

DEPTH	DEPTH	VELOCITY
0.000	0.000	1502.000
0.120	24.000	1500.000
0.325	65.000	1490.000
0.525	105.000	1488.000
0.750	150.000	1486.000
1.000	200.000	1486.000
1.000	200.000	1705.000
1.250	250.000	1730.000

MILLER AND WOLF

MAXIMUM NUMBER OF MODES = 24 NUMBER OF MODES CALCULATED = 19

MODE NO. = 1	PHASE VELOCITY = 0.1488434940400 04	SCALED DOWN 0 TIME(S)	AIR/H2O SCATTER	H2O/2ND SCATTER
NUMBER OF ITERATE SOLUTIONS = 21	THE EIGENFUNCTION WAS		0.0000E 00	0.1888E-03
WAVE NUMBER	WATER ABSORPTION LAYER 2 ATTEN RATIO	CMP ATTEN RATIO		
0.42221331E 290L 00	0.1373E-06	0.1591E-09	0.1717E-09	
	0.7149E-03			
MODE NO. = 2	PHASE VELOCITY = 0.1492932305880 04	SCALED DOWN 0 TIME(S)	AIR/H2O SCATTER	H2O/2ND SCATTER
NUMBER OF ITERATE SOLUTIONS = 17	THE EIGENFUNCTION WAS		0.0000E 00	0.2192E-03
WAVE NUMBER	WATER ABSORPTION LAYER 2 ATTEN RATIO	CMP ATTEN RATIO		
0.4228620365720 00	0.1378E-06	0.5637E-09	0.6116E-09	
	0.1324E-02			
MODE NO. = 3	PHASE VELOCITY = 0.1498823990860 04	SCALED DOWN 0 TIME(S)	AIR/H2O SCATTER	H2O/2ND SCATTER
NUMBER OF ITERATE SOLUTIONS = 18	THE EIGENFUNCTION WAS		0.0000E 00	0.2979E-03
WAVE NUMBER	WATER ABSORPTION LAYER 2 ATTEN RATIO	CMP ATTEN RATIO		
0.419207709250 00	0.1378E-06	0.2748E-09	0.3003E-08	
	0.2292E-02			
MODE NO. = 4	PHASE VELOCITY = 0.1506149706180 04	SCALED DOWN 0 TIME(S)	AIR/H2O SCATTER	H2O/2ND SCATTER
NUMBER OF ITERATE SOLUTIONS = 22	THE EIGENFUNCTION WAS		0.3175E-03	0.3538E-03
WAVE NUMBER	WATER ABSORPTION LAYER 2 ATTEN RATIO	CMP ATTEN RATIO		
0.4111687104800 00	0.1392E-06	0.2825E-07	0.3114E-07	
	0.3174E-02			
MODE NO. = 5	PHASE VELOCITY = 0.1511915290090 04	SCALED DOWN 0 TIME(S)	AIR/H2O SCATTER	H2O/2ND SCATTER
NUMBER OF ITERATE SOLUTIONS = 19	THE EIGENFUNCTION WAS		0.2138E-09	0.2161E-09
WAVE NUMBER	WATER ABSORPTION LAYER 2 ATTEN RATIO	CMP ATTEN RATIO		
0.4155778666890 00	0.1328E-13	0.4597E 00	0.5104E 00	
	0.5248E 00			
MODE NO. = 6	PHASE VELOCITY = 0.1514970794400 04	SCALED DOWN 0 TIME(S)	AIR/H2O SCATTER	H2O/2ND SCATTER
NUMBER OF ITERATE SOLUTIONS = 22	THE EIGENFUNCTION WAS		0.4299E-03	0.4283E-03
WAVE NUMBER	WATER ABSORPTION LAYER 2 ATTEN RATIO	CMP ATTEN RATIO		
0.4147399334660 00	0.1398E-06	0.2103E-06	0.2344E-06	
	0.4275E-02			

MODE NO. = 7 PHASE VELOCITY = 0.152606436803D 04
 NUMBER OF ITERATE SOLUTIONS = 21 THE EIGENFUNCTION WAS SCALED DOWN 0 TIME(S)
 WAVE NUMBER WATER ABSORPTION LAYER 2 ATTEN RATIO COMP ATTEN RATIO SHEAR ATTEN RATIO H2O/2ND SCATTER
 0.411724799517D 00 0.1396E-06 0.5730E-02 0.2790E-07 0.2587E-07 0.5283E-03 0.5281E-03

MODE NO. = 8 PHASE VELOCITY = 0.153963198097D 04
 NUMBER OF ITERATE SOLUTIONS = 18 THE EIGENFUNCTION WAS SCALED DOWN 0 TIME(S)
 WAVE NUMBER WATER ABSORPTION LAYER 2 ATTEN RATIO COMP ATTEN RATIO SHEAR ATTEN RATIO H2O/2ND SCATTER
 0.408096570147D 00 0.1407E-06 0.7254E-02 0.1496E-07 0.1719E-07 9.6339E-03 0.6239E-03

MODE NO. = 9 PHASE VELOCITY = 0.155576272963D 04
 NUMBER OF ITERATE SOLUTIONS = 20 THE EIGENFUNCTION WAS SCALED DOWN 0 TIME(S)
 WAVE NUMBER WATER ABSORPTION LAYER 2 ATTEN RATIO COMP ATTEN RATIO SHEAR ATTEN RATIO H2O/2ND SCATTER
 0.403865767139D 00 0.1419E-06 0.8970E-02 0.1677E-07 0.1969E-07 0.7359E-03 0.7244E-03

MODE NO. = 10 PHASE VELOCITY = 0.157480952975D 04
 NUMBER OF ITERATE SOLUTIONS = 20 THE EIGENFUNCTION WAS SCALED DOWN 0 TIME(S)
 WAVE NUMBER WATER ABSORPTION LAYER 2 ATTEN RATIO COMP ATTEN RATIO SHEAR ATTEN RATIO H2O/2ND SCATTER
 0.398990650579C 00 0.1433E-06 0.1098E-01 0.2660E-07 0.3205E-07 0.8336E-03 0.8295E-03

MODE NO. = 11 PHASE VELOCITY = 0.159703277065D 04
 NUMBER OF ITERATE SOLUTIONS = 20 THE EIGENFUNCTION WAS SCALED DOWN 0 TIME(S)
 WAVE NUMBER WATER ABSORPTION LAYER 2 ATTEN RATIO COMP ATTEN RATIO SHEAR ATTEN RATIO H2O/2ND SCATTER
 0.393628707444D 00 0.1450E-06 0.1344E-01 0.5720E-07 0.7112E-07 0.9433E-03 0.9351E-03

MODE NO. = 12 PHASE VELOCITY = 0.162271197717D 04
 NUMBER OF ITERATE SOLUTIONS = 22 THE EIGENFUNCTION WAS SCALED DOWN 0 TIME(S)
 WAVE NUMBER WATER ABSORPTION LAYER 2 ATTEN RATIO COMP ATTEN RATIO SHEAR ATTEN RATIO H2O/2ND SCATTER
 0.397707769130C 00 0.1468E-06 0.1686E-01 0.1710E-06 0.2209E-06 0.1057E-02 0.1046E-02

MILLER AND WOLF

MAXIMUM NUMBER OF MODES = 24 NUMBER OF MODES CALCULATED = 19

MODE NO. = 13 PHASE VELOCITY = 0.1652104714850 04
 NUMBER OF ITERATE SOLUTIONS = 19 THE EIGENFUNCTION WAS SCALED DOWN 0 TIME(S)
 WAVE NUMBER WATER ABSORPTION LAYER 2 ATTEN RATIO COMP ATTEN RATIO SHFAR ATTEN RATIO AIR/H2O SCATTER H2O/2ND SCATTER
 0.39026967509C 00 0.1497F-06 0.2251E-01 0.7742E-06 0.1048E-05 0.1172E-02 0.1161E-02

MODE NO. = 14 PHASE VELOCITY = 0.1686200599160 04
 NUMBER OF ITERATE SOLUTIONS = 19 THE EIGENFUNCTION WAS SCALED DOWN 0 TIME(S)
 WAVE NUMBER WATER ABSORPTION LAYER 2 ATTEN RATIO COMP ATTEN RATIO SHEAR ATTEN RATIO AIR/H2O SCATTER H2O/2ND SCATTER
 0.37242383150D 00 0.1497E-06 0.3558E-01 0.6561E-05 0.9400E-05 0.1289E-02 0.1269E-02

MODE NO. = 15 PHASE VELOCITY = 0.1723937606690 04
 NUMBER OF ITERATE SOLUTIONS = 23 THE EIGENFUNCTION WAS SCALED DOWN 0 TIME(S)
 WAVE NUMBER WATER ABSORPTION LAYER 2 ATTEN RATIO COMP ATTEN RATIO SHEAR ATTEN RATIO AIR/H2O SCATTER H2O/2ND SCATTER
 0.364467094564D 00 0.1392E-06 0.1237E 00 0.2153E-03 0.3304E-03 0.1300E-02 0.1274E-02

MODE NO. = 16 PHASE VELOCITY = 0.1745944653340 04
 NUMBER OF ITERATE SOLUTIONS = 19 THE EIGENFUNCTION WAS SCALED DOWN 0 TIME(S)
 WAVE NUMBER WATER ABSORPTION LAYER 2 ATTEN RATIO COMP ATTEN RATIO SHEAR ATTEN RATIO AIR/H2O SCATTER H2O/2ND SCATTER
 0.359873109102D 00 0.3165F-07 0.8095E 00 0.5016E-02 0.8079E-02 0.3057E-03 0.2965E-03

MODE NO. = 17 PHASE VELOCITY = 0.177266608948D 04
 NUMBER OF ITERATE SOLUTIONS = 14 THE EIGENFUNCTION WAS SCALED DOWN 0 TIME(S)
 WAVE NUMBER WATER ABSORPTION LAYER 2 ATTEN RATIO COMP ATTEN RATIO SHEAR ATTEN RATIO AIR/H2O SCATTER H2O/2ND SCATTER
 0.35444817549C 00 0.1425F-06 0.1286E 00 0.1646E-02 0.2789E-02 0.1432E-02 0.1402E-02

MODE NO. = 18 PHASE VELOCITY = 0.18172712071D 04
 NUMBER OF ITERATE SOLUTIONS = 22 THE EIGENFUNCTION WAS SCALED DOWN 0 TIME(S)
 WAVE NUMBER WATER ABSORPTION LAYER 2 ATTEN RATIO COMP ATTEN RATIO SHEAR ATTEN RATIO AIR/H2O SCATTER H2O/2ND SCATTER
 0.345661616704C 00 0.1146E-06 0.3279E 00 0.6090E-02 0.1144E-01 0.1232E-02 0.1201E-02

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MODE NO. = 19 PHASE VELOCITY = 0.1845507288840 04
NUMBER OF ITERATE SOLUTIONS = 19 THE EIGENFUNCTION WAS SCALED DOWN 0 TIME(S)
WAVE NUMBER WATER ABSORPTION LAYER 2 ATTEN RATIO COMP ATTEN RATIO SHEAR ATTEN RATIO AIR/H2O SCATTER H2O/2ND SCATTER
0.340584189920 00 3.7817E-07 0.5512E 00 0.1384E-01 0.2788E-01 0.8535E-03 0.8241E-03

MILLER AND WOLF

INCOHERENT TRANSMISSION LOSS
LOSS IN DB

RANGE(M) = 25000.0

SOURCE DEPTH(M) = 70.000
72.45 92.93 IHHIII IHHIII IHHIII
SOURCE DEPTH(M) = 140.000
73.73 94.01 IHHIII IHHIII IHHIII

RANGE(M) = 30000.0

SOURCE DEPTH(M) = 70.000
73.84 94.82 IHHIII IHHIII IHHIII
SOURCE DEPTH(M) = 140.000
75.39 96.36 IHHIII IHHIII IHHIII

RANGE(M) = 35000.0

SOURCE DEPTH(M) = 70.000
75.08 96.41 IHHIII IHHIII IHHIII
SOURCE DEPTH(M) = 140.000
76.79 98.37 IHHIII IHHIII IHHIII

RANGE(M) = 40000.0

COHERENT TRANSMISSION LOSS
LOSS IN DB, PHASE IN DEGREES

RANGE(M) = 25000.0
EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MODE NO. 4
EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MODE NO. 5
EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MODE NO. 14
EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MODE NO. 15
EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MODE NO. 16
EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MODE NO. 17
EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MODE NO. 18
EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MODE NO. 19

SOURCE DEPTH(M) = 70.000
(75.967 135.457) (103.38/ 23.682) (IHHIII/IHHIII) (IHHIII/IHHIII) (IHHIII/IHHIII)
SOURCE DEPTH(M) = 140.000
(74.357 773.483) (70.41/ 273.939) (IHHIII/IHHIII) (IHHIII/IHHIII) (IHHIII/IHHIII)

RANGE(M) = 30000.0
EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MODE NO. 4
EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MODE NO. 5
EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MODE NO. 14
EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MODE NO. 15
EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MODE NO. 16
EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MODE NO. 17
EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MODE NO. 18
EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MODE NO. 19

SOURCE DEPTH(M) = 70.000
(77.99/ 247.720) (100.95/ 204.795) (IHHIII/IHHIII) (IHHIII/IHHIII) (IHHIII/IHHIII)
SOURCE DEPTH(M) = 140.000
(84.957 354.092) (114.38/ 142.139) (IHHIII/IHHIII) (IHHIII/IHHIII) (IHHIII/IHHIII)

RANGE(M) = 35000.0
EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MODE NO. 4
EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MODE NO. 5
EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MODE NO. 12
EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MODE NO. 14
EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MODE NO. 15
EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MODE NO. 16
EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MODE NO. 17
EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MODE NO. 18
EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MODE NO. 19

SOURCE DEPTH(M) = 70.000
(77.497 249.767) (100.42/ 207.415) (IHHIII/IHHIII) (IHHIII/IHHIII) (IHHIII/IHHIII)
SOURCE DEPTH(M) = 140.000
(77.257 67.976) (92.70/ 51.992) (IHHIII/IHHIII) (IHHIII/IHHIII) (IHHIII/IHHIII)

RANGE(M) = 40000.0
EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MODE NO. 4

EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MADE NO. 5
 EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MADE NO. 12
 EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MADE NO. 13
 EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MADE NO. 14
 EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MADE NO. 15
 EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MADE NO. 16
 EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MADE NO. 17
 EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MADE NO. 18
 EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MADE NO. 19

SOURCE DEPTH(M) = 70.000
 76.22 97.81 IIIII IIIII IIIII IIIII
 SOURCE DEPTH(M) = 140.000
 77.96 100.04 IIIII IIIII IIIII IIIII

RANGE(M) = 45000.0

EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MADE NO. 4
 EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MADE NO. 5
 EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MADE NO. 12
 EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MADE NO. 13
 EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MADE NO. 14
 EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MADE NO. 15
 EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MADE NO. 16
 EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MADE NO. 17
 EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MADE NO. 18
 EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MADE NO. 19

SOURCE DEPTH(M) = 70.000
 77.27 99.04 IIIII IIIII IIIII IIIII
 SOURCE DEPTH(M) = 140.000
 78.95 101.41 IIIII IIIII IIIII IIIII

RANGE(M) = 50000.0

EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MADE NO. 4
 EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MADE NO. 5
 EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MADE NO. 12
 EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MADE NO. 13
 EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MADE NO. 14
 EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MADE NO. 15
 EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MADE NO. 16
 EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MADE NO. 17
 EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MADE NO. 18
 EXPONENTIAL (THUS CONTRIBUTION AT ALL SOURCE/RECEIVER DEPTHS) SET TO ZERO FOR MADE NO. 19

SOURCE DEPTH(M) = 70.000
 78.26 100.20 IIIII IIIII IIIII IIIII
 SOURCE DEPTH(M) = 140.000
 79.80 102.52 IIIII IIIII IIIII IIIII

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Appendix A
NORMAL-MODE SUBROUTINES

Detailed documentation [A1] is available for the normal-mode calculations. Although the complete model theory and its FORTRAN coding may be found in Ref. A1, we present here an outline of the salient features, with particular emphasis on the major changes and improvements made to the routines since the publication of Ref. A1.

For a shear-supporting solid basement, PROGRAM MOATL calls subroutines SOLID, HALFS, and ITRTS for the normal-mode calculations. (The fluid-basement case is similar, but less complicated, and will not be discussed here.) The three subroutines used in the solid-basement case correspond, respectively, to PROGRAM SOLID, SUBROUTINE HALF, and SUBROUTINE ITERATE of Ref. A1.

The normal modes of a given environment are the eigenfunctions of Eq. (A1). Application of appropriate boundary conditions will yield a set of N discrete modes, with corresponding modal wave numbers, or eigenvalues k_n ($n = 1, \dots, N$). Due to the appearance of the depth-dependent $c(\zeta)$, Eq. (A1) must be replaced by a finite-difference equivalent for numerical solution; the water and sediment layers must therefore be divided into a number of intervals, or incremental steps, and these are user-specified through the input variables LI1 and LI2.

$$\frac{d^2 u_n}{d\zeta^2} + H_1^2 \left[\left(\frac{\omega}{c(\zeta)} \right)^2 - k_n^2 \right] u_n = 0. \quad (\text{A1})$$

Normal-mode calculations begin in SOLID with a determination of the maximum number of modes. The calculation of modal parameters follows. The mode order is designated and upper and lower bounds are set for the eigenvalue. HALFS is then called to repeatedly shorten the length of this interval, thus converging on the correct eigenvalue. For each new trial eigenvalue obtained, a call to ITRTS is made, where a set of "three-point extrapolation" equations (the finite-difference equivalent of Eq. (A1)) is used to generate, from bottom to surface, the corresponding trial eigenfunction. Depending on the value of the trial eigenfunction at the air/water surface, the trial eigenvalue becomes either the new left- or new right-hand bound of the now-smaller eigenvalue interval. Generally ten or more calls are made to ITRTS before an acceptable eigenvalue is found.

The correct eigenvalue has an eigenfunction which fulfills the boundary condition of being zero at the air/water (pressure-release) surface. Alternatively, HALFS requires that either of two criteria are met: (1) the surface value of the trial eigenfunction is less than EPLON and the difference between the present trial eigenvalue and either the left or the right bound of the present interval is less than 10^{-12} ; or (2) the difference between the trial eigenvalue and either bound of the interval is less than PPRCN. The variable PPRCN is defined as $10^{-\text{PRCSN}}$, where PRCSN is one less than the approximate number of decimal digits associated with the mantissa of a DOUBLE PRECISION floating-point number. What this means is that for criterion (2), the eigenvalue is correct to within the limits of the machine. The machine-dependent PRCSN is adjusted by a PARAMETER statement in MOATL.

For criterion (1), EPLON is defined as the product of EPSLN (a preselected small number) and UMAX (the maximum value that the unnormalized trial eigenfunction takes on). When the correct eigenfunction is determined, control returns to SOLID, where the eigenfunction is normalized (using the Simpson's rule numerical integral technique) according to the solid-basement equivalent of Eq. (A2).

The value of EPSLN is usually selected on the assumption that the maximum value of the eigenfunction is of the order of magnitude one. Since the surface value is checked in HALFS using the unnormalized trial eigenfunction, EPSLN is redefined as EPLON, as stated above. In this way, the normalized eigenfunction will have a surface value less than the input variable EPSLN, if criterion (1) is met.

$$\int_0^{\infty} \rho(\zeta) u_n^2(\zeta) d\zeta = 1. \quad (\text{A2})$$

In this connection, we mention another major change in the programming. It was found in some cases that the unnormalized eigenfunction generated in ITRTS took on very large values, sometimes larger than PMGTD, which is defined as 10^{MGNTD} . (The variable MGNTD depends on one-half the dynamic range of a real constant and, being machine-dependent, is defined for convenience by a PARAMETER statement in MOATL.) In the course of normalization of the eigenfunction, certain single-precision variables are set equal to the sum of the squares of unnormalized eigenfunction values. Thus a value larger than PMGTD, when squared, will cause a floating point overflow in the machine, with subsequent termination of execution and/or the generation of erroneous results. This problem was eliminated in the following way. During generation of the trial eigenfunction in ITRTS, whenever a value larger than PMGTD is encountered, the entire eigenfunction thus far generated is scaled down by dividing the value at each incremental depth by PMGTD. If a given value is so small that such a division would cause a floating point underflow, that value is redefined to be zero. Then the generation of the rest of the eigenfunction resumes. Whenever such a scaling of the eigenfunction takes place, a counter, IFG, is increased by one. The value of this counter is passed back to HALFS along with the trial eigenvalue and eigenfunction. In HALFS, the eigenvalue interval redefinition (described above) depends on the surface values of the trial eigenfunctions, so the scaling information must be taken into account.

There is another important change in the programming of the eigenfunction generation to be discussed. It is stated in Ref. A1 that for certain downward-refracting sound speed profiles, the lowest order eigenfunctions generated may exhibit large amplitude fluctuations near the surface. Previously, the eigenfunction was zeroed (the values at each of the incremental depths were set to zero) from this point up to the air/water surface. Recently, a method of calculating the actual, albeit small, values of the function has been implemented to replace the zeroing procedure.

The phase velocity, $c_{p,n} \equiv \omega/k_n$, increases monotonically with mode-order n . Consider a sound-speed profile which is strongly downward refracting near the surface, such as the deep water profile shown in Fig. A1. It may happen that the phase velocities of the lowest order eigenfunctions, although larger than c_{\min} as they must be, are smaller than the surface value of the sound speed profile. (In Fig. A1, this is true of the m th mode, but not the $(n+1)$ th mode.) Thus for some depth value z_m , we have

$$k_n > \frac{\omega}{c_1(z)} \text{ for } 0 \leq z < z_m.$$

The result is that solutions of Eq. (A1) for $z < z_m$ are exponential rather than sinusoidal, and further iteration of the solution may become unstable.

The program will now calculate the values of the eigenfunctions for $z < z_m$ (rather than setting them to zero). The technique, for a given mode, is simply to start the iteration again, this time at the air/water surface, and generate the eigenfunction down to z_m . The two functions are then matched at z_m to obtain the entire scaled eigenfunction.

To discuss this technique, it is convenient to use the symbols and notation of Ref. A1, to which the reader is referred for appropriate definitions.

The flag IZERO, which in the past controlled the zeroing procedure, now controls the matching procedure. It is set to one for the final call to SUBROUTINE ITRTS, which is the call that generates the acceptable eigenfunction. Note that when this final call is made the eigenvalue k_n has already been

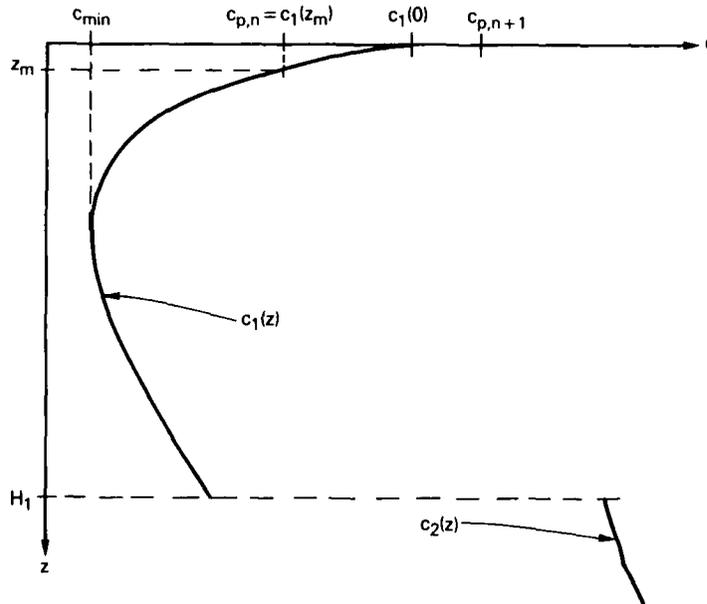


Fig. A1 — Hypothetical phase velocity configuration. For each mode order $\leq n$, there will be a depth z_m for which $c_1(z)$ (with $z < z_m$) will be greater than the corresponding modal phase velocity. For modes of order $> n$, $z_m = 0$.

determined. The matching procedure is not used (or needed) in the eigenvalue search procedure. When IZERO = 1, the DO 6 loop is executed, which searches the water layer for z_m . It may also happen that $k_n > [\omega/c_1(z)]$ everywhere in the water layer. In this case, the DO 8 loop searches the sediment layer for z_m (z_m is always less than $H_1 + H_2$). The variable MATCH stores the number of the incremental layer corresponding to z_m . Then ITRTS proceeds, as usual, to generate the eigenfunction from bottom up to z_m . Then control transfers to statement number 131, where we begin a similar calculation from the surface downward. The flag IZERO is set to two; this instructs SOLID to print a message informing the user that the present mode has been "matched" at depth z_m . Next, to accommodate the pressure-release boundary condition, we set $Z_n^{(1)}(0) = 0$. We estimate the value at the next incremental depth down from the surface by using the Taylor polynomial of second order, expanded about zero:

$$Z_n^{(1)}(t_1) = Z_n^{(1)}(0) + t_1 \left. \frac{dZ_n^{(1)}}{dz} \right|_0 + \frac{t_1^2}{2!} \left. \frac{d^2Z_n^{(1)}}{dz^2} \right|_0$$

Until normalization, the slope of the eigenfunction is arbitrary. To avoid the problem of "exponential runaway," we therefore choose the very small value of 10^{-10} for $\left. \frac{dZ_n^{(1)}}{dz} \right|_0$. We can solve Eq. (A1) for $\left. \frac{d^2Z_n^{(1)}}{dz^2} \right|_0$, and the result is zero. Thus we are left without next amplitude, YOU(2):

$$Z_n^{(1)}(t_1) = t_1 \times 10^{-10}.$$

To obtain YOU(3) through YOU(N1) (or through YOU(MATCH) if MATCH < N1, i.e., $z_m < H_1$) we employ the "three-point extrapolation" finite-difference equivalent of Eq. (A1). For $j = 2, \dots, N1-1$ we have:

$$Z_n^{(1)}(jt_1) = \left\{ Z_n^{(1)}((j-1)t_1) \left[24 - 10 \left[\frac{\omega^2 t_1^2}{c_1^2 ((j-1)t_1)} - k_n^2 t_1^2 \right] \right] - Z_n^{(1)}((j-2)t_1) \left[12 + \frac{\omega^2 t_1^2}{c_1^2 ((j-2)t_1)} - k_n^2 t_1^2 \right] \right\} \left[12 + \frac{\omega^2 t_1^2}{c_1^2 (jt_1)} - k_n^2 t_1^2 \right]^{-1}$$

If MATCH > N1, the above calculation will proceed all the way to the boundary value of the eigenfunction in the water at the water/sediment interface: YOU(N1) = $Z_n^{(1)}(H_1)$. From the boundary conditions, we immediately obtain the boundary value of the eigenfunction in the sediment layer: YOU(N1PLS1) = $Z_n^{(2)}(H_1) = (\rho_1/\rho_2) Z_n^{(1)}(H_1)$. To obtain the next point, we again use the Taylor polynomial, this time expanded about H_1 :

$$Z_n^{(2)}(H_1 + t_2) = Z_n^{(2)}(H_1) + t_2 \left. \frac{dZ_n^{(2)}}{dz} \right|_{H_1} + \frac{t_2^2}{2!} \left. \frac{d^2 Z_n^{(2)}}{dz^2} \right|_{H_1}$$

Now

$$\left. \frac{dZ_n^{(2)}}{dz} \right|_{H_1} = \left. \frac{dZ_n^{(1)}}{dz} \right|_{H_1} \equiv \left. \frac{dZ_n}{dz} \right|_{H_1}$$

because of the boundary conditions. We program the derivative numerically:

$$\left. \frac{dZ_n}{dz} \right|_{H_1} = (-3Z_n^{(1)}(H_1 - 2t_1) + 4Z_n^{(1)}(H_1 - t_1) - Z_n^{(1)}(H_1))/2t_1$$

From Eq. (A1), we have the second derivative:

$$\left. \frac{d^2 Z_n^{(2)}}{dz^2} \right|_{H_1} = - \left[\frac{\omega^2}{c_2^2(H_1)} - k_n^2 \right] Z_n^{(2)}(H_1)$$

Substituting these values into the Taylor polynomial, one obtains the value of $Z_n^{(2)}(H_1 + t_2)$.

From this point on, i.e., for calculation of YOU(N1PLS3) through YOU(MATCH), we again make use of the finite-difference equivalent of Eq. (A1); the procedure is straightforward and we shall not repeat the details.

The quantity YOU(MATCH) is the value of the eigenfunction at z_m , as calculated by the original procedure of integrating upward from the bottom. The variable PPLUS1 is the same quantity, but calculated by the present procedure of starting at the top and integrating downward. It remains to "match" the solutions, which is accomplished by the DO 149 loop. Each of the values, from the surface to z_m , is multiplied by the factor YOU(MATCH)/PPLUS1. This ensures the continuity of the eigenfunction at z_m . Continuity of its first derivative follows from the condition that the correct eigenvalue has already been determined. Continuity of higher derivatives follows from Eq. (A1). This completes the task, since normalization takes place later in SOLID.

With control returned from HALFS to SOLID, the eigenfunction is normalized, as stated above. Next, the scattering ratios and the bottom attenuation ratios are determined (see Eqs. (A3) and (A4)). The quantity $\Gamma_{0,n}$ is termed AIRH2O(I) and $\Gamma_{1,n}$ is termed H2O2ND(I), where I designates the mode order. The quantity $\gamma_n^{(2)}$ is termed ATTEN2(I), $\gamma_n^{(3r)}$ is termed ATTENC(I), and $\gamma_n^{(3s)}$ is termed ATTENS(I). The values of these parameters are as defined in the old version of the program (see Ref. A1); however, the code has been modified to take into account the discus. procedure of scaling the eigenfunction. The only numerical change is in the formula used for calculating derivatives of the eigenfunction at the surface and bottom. For example, whereas we previously [A1] defined

$$DYOUA = (YOU(2) \cdot ANORM - YOU(1) \cdot ANORM) / DL1,$$

we now use the more accurate formula:

$$DYOUA = (-3. *YOU(1) *ANORM + 4. *YOU(2) *ANORM - YOU(3) *ANORM) / 2. / DL1.$$

In the present version of SOLID, normalization is accomplished first, thus we have programmed $YOU(J) *ANORM$ as $UNRM1(I,J)$ or $UNRM2(I,J)$, where the mode order I has been inserted.

$$\delta = \epsilon_2 \gamma_n^{(2)} + \epsilon_{3c} \gamma_n^{(3c)} + \epsilon_{3s} \gamma_n^{(3s)} + S_{0,n} + S_{1,n} + \alpha_n. \quad (A3)$$

$$\left. \begin{aligned} S_{0,n} &= 2\sigma_0^2 \left[\left(\frac{\omega}{c_1(0)} \right)^2 - k_n^2 \right] \Gamma_{0,n} \\ S_{1,n} &= 2\sigma_1^2 \left[\left(\frac{\omega}{c_1(H_1)} \right)^2 - k_n^2 \right] \Gamma_{1,n} \end{aligned} \right\} \quad (A4)$$

In many cases, attenuation of the modal field due to absorption by the water is not appreciable. In some cases, however, this loss mechanism has been found to yield a significant contribution, thus it is now included in the transmission loss calculated by MOATL via Eq. (A3). In a manner similar to that of the sediment layer and basement, we may write the attenuation as $\alpha_n = \epsilon_1 \gamma_n^{(1)}$, where ϵ_1 is the plane-wave absorption coefficient in an infinite medium of ocean water. Whereas ϵ_2 , ϵ_{3c} , and ϵ_{3s} depend on the particular sediment and basement chosen (and are input variables), ϵ_1 may be taken as constant and given empirically by [A2]:

$$\epsilon_1 = \frac{(0.1) f^2}{1 + f^2} + \frac{40 f^2}{4100 + f^2} + 2.75 \times 10^{-4} f^2,$$

where f is the frequency in kHz and ϵ_1 is given in dB/kyd. The coefficient ϵ_1 is termed EPW by SOLID, where it is converted to nepers/m. The quantity $\gamma_n^{(1)}$ measures the degree of interaction of the n th mode with the absorption mechanism and is given (in a form similar to that of $\gamma_n^{(2)}$), by:

$$\gamma_n^{(1)} = \rho_1 \frac{\omega}{k_n} \int_0^{H_1} \frac{[u_n^{(1)}(z)]^2}{c_1(z)} dz.$$

The superscript on the eigenfunction refers to the layer number, in this case the water layer.

REFERENCES

- A1. J.F. Miller and F. Ingenito, "Normal Mode FORTRAN Programs for Calculating Sound Propagation in the Ocean," NRL Memorandum Report 3071, June 1975.
- A2. R.J. Urick, *Principles of Underwater Sound* (McGraw-Hill, New York, 1975), 2nd ed., p. 102.

Appendix B

FORTRAN NAMELIST OF PROGRAM MOATL VARIABLES AND SYSTEM SUBROUTINES AND FUNCTIONS

All the variables of PROGRAM MOATL are alphabetically listed below with their corresponding definitions. For the arrays in the list, the index N denotes mode-order, the index I denotes range, and the variables J1 and J2 denote receiver and source identification, respectively. Occasionally, reference is made to the "SR group" or the "LR group." For further explanation and definitions, see the section "Step-By-Step Analysis—Part 3."

Most of the variables occurring in the subroutines have been described elsewhere [B1]; some name changes and new variables are defined in Appendix A.

The computer system library functions appearing in the FORTRAN code are described at the end of this Appendix in Table B1.

The on-line plotter software includes the following subroutines, which are not discussed here: CENTRE, CNUMBR, ENDPLT, NXAXIS, NYAXIS, ORIGIN, PLOT, PLOTS, and SYMBOL.

ABSOR(N): An array containing the water absorption, α_n , calculated in the subroutines.

AIRH2O(N): An array containing the scattering ratios $\Gamma_{0,n}$, used in calculating the attenuation due to interaction of the various modes with a statistically rough boundary at the air/water interface.

AKN(N): An array containing the eigenvalues (modal wave numbers), k_n , as calculated by the subroutines.

ATTENC(N): An array containing the basement compressional attenuation ratios, $\gamma_n^{(3c)}$.

ATTENS(N): An array containing the basement shear attenuation ratios, $\gamma_n^{(3s)}$.

ATTEN2(N): An array containing the sediment attenuation ratios, $\gamma_n^{(2)}$.

A1: The number plus fraction (starting at the air/water surface) of the incremental layer corresponding to the source or receiver depth.

A2: In a range-dependent model, A1 is used (as defined above) for the SR calculation and A2 (defined the same way) is used for the LR calculation.

CBS: the range-interpolated value of $c_1(H)$, the sound speed at the bottom of the water layer.

CBI: The value of $c_1(H)$ at the SR range.

- CB2: The value of $c_1(H)$ at the LR range.
- COMP: The compressional velocity, c_{3c} , of the basement.
- COPL(J1,J2,I): An array containing the coherent transmission loss or transmission-loss anomaly in decibels.
- CTS: The range-interpolated value of $c_1(0)$, the sound speed at the surface of the water layer.
- CT1: The value of $c_1(0)$ at the SR range.
- CT2: The value of $c_1(0)$ at the LR range.
- C1(J): An array containing the sound-speed profile in the water layer, $c_1(z)$.
- C2(J): An array containing the sound-speed profile in the sediment layer, $c_2(z)$.
- DBMAX: The maximum loss (in dB) on the vertical axis of the plot.
- DBMIN: The minimum loss (in dB) on the vertical axis of the plot.
- DEPRE(J1): An array containing the receiver depths.
- DEPSO(J2): An array containing the source depths.
- DLTA1: That fraction of an incremental layer by which the source or receiver depth exceeds the depth of the nearest shallower incremental layer boundary.
- DLTA2: In a range-dependent model, DLTA1 is used (as defined above) for the SR calculation and DLTA2 (defined the same way) is used for the LR calculation.
- DR: The distance (increment) between ranges at which transmission loss (or loss anomaly) is calculated.
- DX: The number of kilometers per inch on the horizontal (range) axis of the plot.
- DY: The number of decibels per inch on the vertical (loss) axis of the plot.
- EIGVL1(N): An array containing the eigenvalues, k_n , at the SR range.
- EIGVL2(N): An array containing the eigenvalues, k_n , at the LR range.
- EPSLN: The criterion for the accuracy of the determined eigenvalues and eigenfunctions, *i.e.*, the amount by which the air/water surface value of the normalized eigenfunction may differ from the pressure-release boundary condition requirement of being identically zero.
- EP1: The plane-wave absorption coefficient of the sediment, ϵ_2 , expressed in dB/Hz-m.
- EP2: The basement compressional plane-wave absorption coefficient, ϵ_{3c} , expressed in dB/Hz-m.
- EP3: The basement shear plane-wave absorption coefficient, ϵ_{3s} , expressed in dB/Hz-m.

- EP4: Same as EP1, expressed in nepers/m.
- EP5: Same as EP2, expressed in nepers/m.
- EP6: Same as EP3, expressed in nepers/m.
- F: The source frequency, f .
- GA(N): An array containing the range-interpolated values of the water absorption, α_n .
- GB(N): An array containing the range-interpolated values of the scattering ratios $\Gamma_{1,n}$.
- GT(N): An array containing the range-interpolated values of the scattering ratios $\Gamma_{0,n}$.
- G1(N): An array containing the range-interpolated values of the attenuation ratios $\gamma_n^{(2)}$.
- G2(N): An array containing the range-interpolated values of the attenuation ratios $\gamma_n^{(3c)}$.
- G3(N): An array containing the range-interpolated values of the attenuation ratios $\gamma_n^{(3s)}$.
- HS: The range-interpolated value of the water layer thickness (*i.e.*, the water depth), H_1 .
- H10: The value of the water layer thickness H_1 at the receiver, *i.e.*, at zero range.
- H11: The value of the water layer thickness H_1 at the SR range.
- H12: The value of the water layer thickness H_1 at the LR range.
- H2: The value of the sediment layer thickness H_2 .
- H2O2ND(N): An array containing the scattering ratios $\Gamma_{1,n}$, used in calculating the attenuation due to interaction of the various modes with a statistically rough boundary at the water/sediment interface.
- I: A DO-LOOP index used primarily for the DO 300 range loop.
- IA1: The truncated integer value of A1.
- IA2: The truncated integer value of A2.
- IFREQ: The DO 340 frequency loop index.
- III: An input flag used to specify whether the basement is to be modeled as a fluid or a solid.
- IM: A DO-LOOP index denoting mode-order.
- INC1: A variable having a value one greater than the number of depth-increment values to be skipped between printed-out values of the eigenfunctions in the water layer.
- INC2: A variable having a value one greater than the number of depth-increment values to be skipped between printed-out values of the eigenfunctions in the sediment layer.
- IPLOT: An input flag used to specify whether or not plotting of transmission loss (or loss anomaly) vs range is to be included in the output.

- ISPRD:** An input flag used to specify whether transmission loss or transmission loss anomaly is to be calculated.
- J:** An implied DO-LOOP index used for the sound-speed profiles.
- J1:** A DO-LOOP index used for denoting the various receiver depths.
- J2:** A DO-LOOP index used for denoting the various source depths.
- KA:** A parameter whose value flags the normal-mode subroutines to store the calculated eigenfunctions in either the SR array UNRM1(N,K) or the LR array UNRM2(N,K).
- LI1:** The number of incremental steps into which the water layer is to be divided for the numerical calculations.
- LI2:** The number of incremental steps into which the sediment layer is to be divided for the numerical calculations.
- MDPRNT:** An input flag used to specify whether or not calculated normal-mode amplitude functions (eigenfunctions), $u_n(z)$, are to be printed out.
- MGNTD:** A machine-dependent parameter set equal to approximately half (but not larger than half) the dynamic range of a single-precision real constant.
- NDRE:** The number of receiver depths for which calculations are to be performed.
- NDSO:** The number of source depths for which calculations are to be performed.
- ND1:** The number of points (depths) in the water layer at which the sound speed is supplied.
- ND2:** The number of points (depths) in the sediment layer at which the sound speed is supplied.
- NMFREQ:** The number of source frequencies (or more accurately, the number of separate environmental cases) for which the entire transmission-loss calculations are to be performed.
- NMODE:** The total number of modes that exist and/or that are to be used in the calculations.
- NRBUF:** The number of range points at which environmental data are to be supplied.
- NRCALC:** The number of range points at which loss calculations are to be performed.
- N1:** LI1+1 in the subroutines.
- N11:** LI1+1 at the SR environmental data set.
- N12:** LI1+1 at the LR environmental data set.
- N2:** LI2+1 in the subroutines.
- PHASE(J1,J2):** An array containing the phase angles in degrees of the coherent transmission loss.
- PL(J1,J2,I):** An array containing the incoherent transmission loss or transmission-loss anomaly in decibels.

PLTAR(K): An array used solely by the machine for buffering the execution-generated plot commands onto Calcomp plotter tape.

PMGTD: The value of ten raised to the power MGNTD.

PPRCN: The value of ten raised to the power (- PRCSN).

PRCSN: A machine-dependent parameter specifying one less than the approximate number of decimal digits associated with the mantissa of a DOUBLE PRECISION real constant.

Q: A variable containing the product of Q1 and Q2.

QC(J1,J2): An array containing the intermediate results, $\sum_{n=1}^{N'} \frac{u_n(\zeta_0) u'_n(\zeta) r^{1/2}}{\phi_n^{1/2}} e^{-\Delta_n r} \cos \phi_n$, $1 \leq N' \leq N$, which are used in calculating the coherent loss.

QQ: The average attenuation coefficient, Δ_n , times the range, r .

QS(J1,J2): An array containing the intermediate results, $\sum_{n=1}^{N'} \frac{u_n(\zeta_0) u'_n(\zeta) r^{1/2}}{\phi_n^{1/2}} e^{-\Delta_n r} \sin \phi_n$, $1 \leq N' \leq N$, which are used in calculating the coherent loss.

Q1: The term $\frac{u_n(\zeta_0) u'_n(\zeta) r^{1/2}}{\phi_n^{1/2}}$.

Q2: The term $e^{-\Delta_n r}$.

RAN(I): An array containing the range points, r , at which results are to be calculated.

RANGE1: The range of the SR environmental data set.

RANGE2: The range of the LR environmental data set.

RA1(N): An array containing the water absorption, α_n , at the SR range.

RA2(N): An array containing the water absorption, α_n , at the LR range.

RB1(N): An array containing the scattering ratios $\Gamma_{1,n}$ at the SR range.

RB2(N): An array containing the scattering ratios $\Gamma_{1,n}$ at the LR range.

RE(J1,N): An array containing the depth-interpolated values of $u_n(\zeta_0)$, which are the eigenfunction values at the various receiver depths.

REC: A PARAMETER which specifies the maximum number of receiver depths.

REC5: A PARAMETER which is greater than or equal to REC and which is an integral multiple of five.

RERHO1: The water-layer density ρ_1 at the receiver, *i.e.*, at zero range.

RERHO2: The ratio of the density of the sediment layer to that of water, *i.e.*, ρ_2 , at the receiver range.

- RHO1: The water-layer density ρ_1 at the variable range r .
- RHO2: The ratio of the density of the sediment layer to that of water, *i.e.*, ρ_2 , at the variable range r .
- RHO3: The ratio of the density of the basement to that of water, *i.e.*, ρ_3 , at the variable range r .
- RMAX: The range of the final input environmental data set and/or the maximum range at which calculations are desired.
- RMXKM: The length, in km, of the range axis for plotted output.
- RNG: A PARAMETER which specifies the maximum number of range points at which loss calculations are to be performed.
- RT1(N): An array containing the scattering ratios $\Gamma_{0,n}$ at the SR range.
- RT2(N): An array containing the scattering ratios $\Gamma_{0,n}$ at the LR range.
- R11(N): An array containing the sediment-attenuation ratios $\gamma_n^{(2)}$ at the SR range.
- R12(N): An array containing the sediment-attenuation ratios $\gamma_n^{(2)}$ at the LR range.
- R21(N): An array containing the basement compressional attenuation ratios $\gamma_n^{(3c)}$ at the SR range.
- R22(N): An array containing the basement compressional attenuation ratios $\gamma_n^{(3c)}$ at the LR range.
- R31(N): An array containing the basement shear attenuation ratios $\gamma_n^{(3s)}$ at the SR range.
- R32(N): An array containing the basement shear attenuation ratios $\gamma_n^{(3s)}$ at the LR range.
- SA(N): An array containing the values of the integrals $\int_0^r \alpha_n(r) dr$.
- SB(N): An array containing the values of the integrals $\int_0^r \Gamma_{1,n}(r) dr$.
- SCALE: A variable which contains the interpolation factor Δ used in the linear range interpolation. (See the section "Step-By-Step Analysis—Part 7," specifically Eqs. (16) and (17).)
- SE(N): An array containing the values of the integrals $\phi_n = \int_0^r k_n(r) dr$.
- SHEAR: The shear velocity, c_{3s} , of the basement.
- SIG0: The root-mean-square wave height σ_0 , used in calculating the term $S_{0,n}$.
- SIG1: The root-mean-square excursion of the water/sediment interface σ_1 , used in calculating the term $S_{1,n}$.
- SM(J2,N): An array containing the depth-interpolated values of $u'_n(\xi)$, which are the eigenfunction values at the various source depths.
- SOC: A PARAMETER which specifies the maximum number of source depths.
- ST(N): An array containing the values of the integrals $\int_0^r \Gamma_{0,n}(r) dr$.

- S1(N): An array containing the values of the integrals $\int_0^r \gamma_n^{(2)}(r) dr$.
- S2(N): An array containing the values of the integrals $\int_0^r \gamma_n^{(3c)}(r) dr$.
- S3(N): An array containing the values of the integrals $\int_0^r \gamma_n^{(3s)}(r) dr$.
- TH: The name of a COMMON block used for variables common to PROGRAM MOATL, SUBROUTINE HALFF, and SUBROUTINE HALFS.
- TITLE(K): Any alphanumeric label used to identify the computer run.
- TN: The name of a COMMON block used for variables common to PROGRAM MOATL, SUBROUTINE FLUID, and SUBROUTINE SOLID.
- TNH: The name of a COMMON block used for variables common to PROGRAM MOATL, SUBROUTINE FLUID, SUBROUTINE SOLID, SUBROUTINE HALFF, and SUBROUTINE HALFS.
- TNI: The name of a COMMON block used for variables common to PROGRAM MOATL, SUBROUTINE FLUID, SUBROUTINE SOLID, SUBROUTINE ITRTF, and SUBROUTINE ITRTS.
- TNIH: The name of a COMMON block used for variables common to PROGRAM MOATL and all subroutines.
- UNRM1(N,J2): An array containing the eigenfunctions $u_n'(z)$ at the SR range.
- UNRM2(N,J2): An array containing the eigenfunctions $u_n'(z)$ at the LR range.
- WN(N): An array containing the range-interpolated values of the eigenvalues k_n .
- X: The x-coordinate of a point to be plotted on the graph.
- XLENG: The to-scale length, in inches, of the range axis for the plotted output graph.
- XXR1: The depth-interpolated value of the eigenfunction at the source depth, at the SR range.
- XXR2: The depth-interpolated value of the eigenfunction at the source depth, at the LR range.
- X2: XLENG divided by two.
- Y: The y-coordinate of a point to be plotted on the graph.
- YLENG: The length, in inches, of the loss axis for the plotted output graph.
- Y2: YLENG divided by two.
- Z1(J): An array containing the sound-speed-profile depth points in the water layer.
- Z2(J): An array containing the sound-speed-profile depth points in the sediment layer.

Table B1 — System Library Functions

Form	Definition	Mode of Argument	Mode of Result
ABS(X)	Absolute value of X	Real	Real
ALOG10(X)	Logarithm to base 10 of X	Real	Real
ATAN2(X,Y)	Arctangent [†] of (X divided by Y)	Real	Real
DCOS(D)	Cosine of D [†]	Double	Double
DSIN(D)	Sine of D [†]	Double	Double
DSQRT(D)	Square root of D	Double	Double
EXP(X)	<i>e</i> raised to power X	Real	Real
FLOAT(I)	Convert integer I to real	Integer	Real
IFIX(X)	Truncate real X to integer	Real	Integer

[†]in radians

REFERENCES

- B1. J.F. Miller and F. Ingenito, NRL Memorandum Report 3071, June 1975.

Appendix C

FORTRAN LISTING AND CROSS-REFERENCE OF PROGRAM AND SUBROUTINES

The FORTRAN code for each of the main program and subroutines is listed on the following pages. Following each listing is a cross-reference for that routine, which gives all of the variable and routine names used, in alphabetical order. Following each FORTRAN name in the cross-reference is a list of control statement numbers (CSNs) referencing the statements in which the name appears.

The following control statements are indented three spaces for ease in following the FORTRAN code: (1) DO loop, (2) GO TO statement, (3) transfer-of-control IF statement, and (4) calls to subroutines.

Each Part of PROGRAM MOATL (as subdivided for the discussion in the "Step-By-Step Analysis" section) is marked with a COMMENT.

```

SOURCE LISTING
STATEMENT
C SN
0001      PROGRAM MGATL
0002      DOUBLE PRECISION AKN,EIGVL1,EIGVL2,WN,SE
0003      COMMON/TN/ZI(150),C1(150),Z2(150),C2(150),ABSOR(150),ATTEN2(150),
>ATTEN3(150),ATTENS(150),AIRH20(150),H202NDC(150),UNRA1(150,1202),
>UNRM2(150,1202),MDPRNT,INCL1,INC2,H2,LI1,LI2,SHEAR,NMODE,KA,ND1,
>ND2,NZ
0004      COMMON/TH/EPSLN
0005      COMMON/TNI/RH01,RH02,RH03,HL2,COMP,F,M1
0006      COMMON/TNH/KN(150)
0007      COMMON/TNIH/PPRCN,PMGYD
0008      PARAMETER REC=3 ,REC5=5 ,SOC=4 ,RNG=200

C
C THE FOLLOWING ARE MACHINE-DEPENDENT PARAMETERS.  MGMTD IS ROUGHLY
C (BUT SMALLER THAN) ONE-HALF THE DYNAMIC RANGE OF A REAL CONSTANT.
C PRCSN IS ONE LESS THAN THE APPROXIMATE NUMBER OF DECIMAL DIGITS TO
C WHICH A DOUBLE PRECISION NUMBER IS PRECISE.
C
0009      PARAMETER MGMTD=30,PRCSN=15
0010      DIMENSION PLTARC(500),TITLE(20),DEPRE(REC),DEPS0(SOC),RAN(RNG),
>REC(150),SM(SOC,150),QS(REC,SOC),QC(REC,SOC),PL(REC5,SOC,RNG),
>CPL(REC5,SOC,RNG),PHASE(REC5,SOC),EIGVL1(150),EIGVL2(150),
>R1(150),R12(150),R2(150),R22(150),R3(150),R32(150),RTI(150),
>RI2(150),RBI(150),R2(150),R22(150),SE(150),SI(150),S2(150),
>S3(150),WN(150),G1(150),G2(150),G3(150),ST(150),GT(150),SB(150),
>GBC(150),RA1(150),RA2(150),GA(150),SA(150)
0011      1000 FORMAT(20A4)
0012      2000 FORMAT(4I5,F10.3,5F10.7)
0013      3000 FORMAT(I5,2F10.3,2F10.7)
0014      4000 FORMAT(8F10.3)
0015      5000 FORMAT(3I5,5F10.3)
0016      6000 FORMAT(F10.8,3F10.3,4I5)
0017      7000 FORMAT(2F10.3)
0018      1001 FORMAT (1H1)
0019      2001 FORMAT (10(/),24X,27H***** TRANSMISSION LO
>SS ANOMALY ,26H*****
>MBER OF FREQUENCIES = ,I2,/,/,1X,NO. PROFILES',5X,'NO. CALCULATIO
>N RANGES',5X,'MAXIMUM RANGE',10X,'EPI',10X,'EP2',10X,'EP3',9X,'SIG
>0',9X,'SIG1',/,6X,I2,19X,I3,16X,F10.3,8X,5(F10.7,3X))
0020      3001 FORMAT (10(/),24X,31H***** TRANSMISSIO
>N LOSS ,30H*****
>MBER OF FREQUENCIES = ,I2,/,/,1X,NO. PROFILES',5X,'NO. CALCULATIO
>N RANGES',5X,'MAXIMUM RANGE',10X,'EPI',10X,'EP2',10X,'EP3',9X,'SIG
>0',9X,'SIG1',/,6X,I2,19X,I3,16X,F10.3,8X,5(F10.7,3X))
0021      3002 FORMAT (/,24X,'IPL0T =',I2,5X,'DBMIN =',F8.3,5X,'DBMAX =',F8.3,
>5X,'DY =',F10.7,5X,'DX =',F10.7)
0022      4001 FORMAT (/,55X,I3,1X,'SOURCE DEPTH(S)',/,50(58X,F10.3,/)
0023      5001 FORMAT (/,54X,I3,1X,'RECEIVER DEPTH(S)',/,50(58X,F10.3,/)
0024      6001 FORMAT (/,1X,20A4,5X,'SOURCE FREQUENCY =',F10.3)
0025      7001 FORMAT (/,1X,MDPRNT =',I1,7X,INCL1 =',I2,8X,INC2 =',I2,7X,
>'RH01 =',F5.3,6X,'RH02 =',F5.3,6X,'RH03 =',F5.3,6X,'M1 =',F9.3,6X,

```

```

MOATL SOURCE LISTING
CSN STATEMENT
0026 > H2 = ,F8.3, /,IX, EPSLN = ,F10.8,10X, RANGE = ,F10.3,10X,
> LI1 = ,I3,5X, LI2 = ,I3,5X, MD1 = ,I2,5X, MD2 = ,I2)
8001 FORMAT (I1I,IX, COHERENT TRANSMISSION LOSS ANOMALY,60X, INCOHEREN
> T TRANSMISSION LOSS ANOMALY, /,IX, (LOSS ANOMALY IN DB/ PHASE IN D
> EGRES),57X, LOSS ANOMALY IN DB)
9001 FORMAT (I1I,IX, COHERENT TRANSMISSION LOSS,68X,
> INCOHERENT TRANSMISSION LOSS,
> /,IX, (LOSS IN DB, PHASE IN DEGREES),65X, LOSS IN DB)
1001 FORMAT (///,IX, RANGE(M) = ,F8.1,76X, RANGE(M) = ,F8.1)
11001 FORMAT (IX, EXPONENTIAL THUS CONTRIBUTION AT ALL SOURCE/RECEIVER,
> DEPTHS) SET TO ZERO FOR MODE NO.,I3)
12001 FORMAT (IX, CONTRIBUTION SET TO ZERO FOR MODE NO.,I3,
> AT SOURCE DEPTH = ,F8.3, AND RECEIVER DEPTH = ,F8.3)
13001 FORMAT ( /,IX, SOURCE DEPTH(M) = ,F8.3,69X, SOURCE DEPTH(M) = ,
> F8.3)
14001 FORMAT (IX,5(,F6.2, /,F8.3, /,IX),4X,5(F6.2,2X))
15001 FORMAT ( /,IX, (,F6.2, /,F8.3, /,77X,F6.2)
C
C ***** PART 1 *****
C
0034 CALL PLOTS (PLTR,500,.7)
0035 PRGTD=10.*MCMTD
0036 PPRCN=10.*(PRCSN)
0037 READ (5,1000)ITITLE
0038 READ (5,2000)ISPRD,NMFREQ,NRBUF,NRCALC,RMAX,EPI,EP2,EP3,SIG0,SIG1
0039 READ (5,2000)NDS0,NDR
0040 READ (5,2000)III
0041 WRITE(6,1001)
0042 IF (ISPRD.EQ.0) WRITE(6,2001)ITITLE,NMFREQ,NRBUF,NRCALC,RMAX,EPI,
> EP2,EP3,SIG0,SIG1
IF (ISPRD.EQ.1) WRITE(6,3001)ITITLE,NMFREQ,NRBUF,NRCALC,RMAX,EPI,
> EP2,EP3,SIG0,SIG1
READ (5,3000)IPL0T,DBMIN,DBMAX,DY,DX
WRITE(6,3002) IPL0T,DBMIN,DBMAX,DY,DX
0045 READ (5,4000)(DEPS0(I),I=1,NDS0)
0046 READ (5,4000)(DEPRE(I),I=1,NDR)
0047 WRITE(6,4001) NDS0,(DEPS0(I),I=1,NDS0)
0048 WRITE(6,5001) NDR,(DEPRE(I),I=1,NDR)
0049 DR=RMAX/MRCALC
0050 RANCL=DR
0051
C
0052 IF (IPL0T.EQ.0) GO TO 90
0053 RMAXW=5.*(IFIX(RMAX/5000.)*1)
0054 XLENG=RMAX/DX
0055 X2=XLENG/2.
0056 YLENG=(DBMAX-DBMIN)/DY
C
C THE FOLLOWING STATEMENT EXEMPLIFIES HOW THE PROGRAM MAY BE USED FOR
C UNEQUAL RANGE INCREMENT CALCULATIONS.
C DR=RANCL=10000.
C

```

```

MOATL          SOURCE LISTING
CSN            STATEMENT
0057           Y2=YLENG/2.
0058           90 CONTINUE
C ***** PART 2 *****
C           DO 340 IFREQ=1,NMFREQ
C           READ(5,1000)TITLE
C           READ (5,4000)F
C           WRITE(6,1001)
C           EP4=EP1+F*0.1151292546
C           EP5=EP2+F*0.1151292546
C           EP6=EP3+F*0.1151292546
C ***** PART 3 *****
C           READ (5,5000)MDPRNT,INC1,INC2,RHO1,RHO2,RHO3,H11,H2
C           READ (5,6000)EPSLN,COMP,SNEAR,RANGE1,L11,L12,ND1,ND2
C           WRITE(6,7001) MDPRNT,INC1,INC2,RHO1,RHO2,RHO3,H11,H2,EPSLN,
C           >RANGE1,L11,L12,ND1,ND2
C           RANGE2=RANGE1
C           H12=H11
C           H20=H11
C           RERHO1=RHO1
C           RERHO2=RHO2
C           READ (5,7000)(Z1(J),C1(J),J=1,ND1)
C           C12=C1(1)
C           C11=C1(1)
C           CB2=C1(ND1)
C           CB1=C1(ND1)
C           KA=0
C           NMODE=10000
C           IF (III.EQ.0) CALL FLUID
C           IF (III.EQ.1) CALL SOLID
C           N11=N1
C           N12=N1
C           DO 110 IM=1,NMODE
C           EIGVL1(IM)=AKN(IM)
C           EIGVL2(IM)=AKNC(IM)
C           R11(IM)=ATTEN2(IM)
C           R12(IM)=ATTEN2(IM)
C           R21(IM)=ATTENCC(IM)
C           R22(IM)=ATTENCC(IM)
C           R31(IM)=ATTENS(IM)
C           R32(IM)=ATTENS(IM)
C           RAIK(IM)=ABSORC(IM)
C           RA2(IM)=ABSORC(IM)
C           RT1(IM)=AIRH20C(IM)
C           RT2(IM)=AIRH20C(IM)

```

MDATL	SOURCE LISTING
	STATEMENT
0100	R81(IM)=H202ND(IM)
0101	R82(IM)=H202ND(IM)
0102	SEC(IM)=0.0
0103	S1(IM)=0.0
0104	S2(IM)=0.0
0105	S3(IM)=0.0
0106	SA(IM)=0.0
0107	ST(IM)=0.0
0108	SBC(IM)=0.0
0109	DO 100 J1=1,NDRE
0110	IF (DEPRE(J1).GT.H10) GO TO 95
0111	A1=(M1-1)*DEPRE(J1)/H10
0112	IA1=IFIX(A1)
0113	DLTA1=A1-IA1
0114	GO TO 100
0115	95 A1=(M2-1)*(DEPRE(J1)-H10)/H2+FL0AT(M1)
0116	IA1=IFIX(A1)
0117	DLTA1=A1-IA1
0118	100 RE(J1,IM)=UNRMI(IM,IA1+1)+DLTA1*(UNRMI(IM,IA1+2)-UNRMI(IM,IA1+1))
0119	110 CONTINUE
0120	IF (NRBUF.GT.1) GO TO 115
	C ***** PART 4 *****
	C
0121	IF (ISPRD.EQ.0) WRITE(6,8001)
0122	IF (ISPRD.EQ.1) WRITE(6,9001)
0123	MS=H11
0124	CTS=CT1
0125	CBS=CB1
0126	DO 112 J2=1,MDS0
0127	A1=(M1-1)*DEPS0(J2)/HS
0128	IA1=IFIX(A1)
0129	DLTA1=A1-IA1
0130	DO 111 IM=1,NMODE
0131	111 SMCJ2(IM)=UNRMI(IM,IA1+1)+DLTA1*(UNRMI(IM,IA1+2)-UNRMI(IM,IA1+1))
0132	112 CONTINUE
0133	DO 113 IM=1,NMODE
0134	WN(IM)=EIGVLI(IM)
0135	G1(IM)=R11(IM)
0136	G2(IM)=R21(IM)
0137	G3(IM)=R31(IM)
0138	G4(IM)=R41(IM)
0139	G5(IM)=R51(IM)
0140	G6(IM)=R61(IM)
0141	113 CONTINUE
	C ***** PART 5 *****
	C
	C
0142	115 DO 300 I=1,NRCALC

```

SOURCE LISTING
CSN      STATEMENT
C THE FOLLOWING STATEMENT EXEMPLIFIES HOW THE PROGRAM MAY BE USED FOR
C UNEQUAL RANGE INCREMENT CALCULATIONS.
C IF (I.EQ.3) DR=2000.
C
0143      IF (I.GT.1) RANCI)=RANCI-1)+DR
0144      IF (NRBUF.EQ.1) GO TO 209
0145      IF (RANGE2-RANGE1.LT.0.00001) GO TO 125
0146      IF (RANCI).LT.RANGE2+DR/2-0.0R.RANCI)-GE.RMAX) GO TO 160
C
C ***** PART 6 *****
C
125 RANGE1=RANGE2
   HAI=HI2
   CT1=CT2
   CBI=CB2
   N11=N12
   DO 130 IM=1,NMODE
     IF (KA.EQ.0) GO TO 129
     DO 128 IAI=1,1202
       UNRM1(IM,IAI)=UNRM2(IM,IAI)
128 CONTINUE
     EIGV1(IM)=EIGV2(IM)
     R11(IM)=R12(IM)
     R21(IM)=R22(IM)
     R31(IM)=R32(IM)
     R41(IM)=R42(IM)
     R51(IM)=R52(IM)
     R61(IM)=R62(IM)
130 CONTINUE
   READ (5,500)MDPRNT,INC1,INC2,RH01,RH02,RH03,HI2,H2
   READ (5,600)EPSLM,COMP,Shear,RANGE2,LI,LI2,ND1,ND2
   WRITE(6,1001)
   WRITE(6,7001) MDPRT,INC1,INC2,RH01,RH02,RH03,HI2,H2,EPSLM,
>RANGE2,LI,LI2,ND1,ND2
   READ (5,7000)(Z1(J),CI(J),J=1,ND1)
   READ (5,7000)(Z2(J),C2(J),J=1,ND2)
   CT2=CI(1)
   C2=C1(1)
   KA=1
   IF (III.EQ.0) CALL FLUID
   IF (III.EQ.1) CALL SOLID
   IF (ISPRD.EQ.0) WRITE(6,8001)
   IF (ISPRD.EQ.1) WRITE(6,9001)
   N12=N1
   DO 150 IM=1,NMODE
     EIGV2(IM)=AKN(IM)
     R12(IM)=ATTEN2(IM)
     R22(IM)=ATTEN3(IM)
     R32(IM)=ATTENS(IM)
     RA2(IM)=ABSOR(IM)
0184

```

```

MOATL          SOURCE LISTING
CSN            STATEMENT
0185          RT2(IM)=AIRH20(IM)
0186          RB2(IM)=H202ND(IM)
0187          150 CONTINUE
0188          GO TO 120
C ***** PART 7 *****
C
0189          160 SCALE=(RANCI)-RANGE1)/(RANGE2-RANGE1)
0190          HS=H11*SCALE*(H12-H11)
0191          CFS=CF1+SCALE*(CF2-CF1)
0192          CBS=CB1+SCALE*(CB2-CB1)
0193          SCALE=SCALE-DR/(2.0*(RANGE2-RANGE1))
0194          DO 180 J2=1,MDS0
0195          A1=(M11-1)*DEPS0C(J2)/HS
0196          IA1=IFIX(A1)
0197          DLTA1=A1-IA1
0198          A2=(M12-1)*DEPS0C(J2)/HS
0199          IA2=IFIX(A2)
0200          DLTA2=A2-IA2
0201          DO 170 IM=1,NMODE
0202          XXR1=UNRM1(IM,IA1+1)+DLTA1*(UNRM1(IM,IA1+2)-UNRM1(IM,IA1+1))
0203          XXR2=UNRM2(IM,IA2+1)+DLTA2*(UNRM2(IM,IA2+2)-UNRM2(IM,IA2+1))
0204          170 SA(J2,IM)=XXR1+(SCALE*DR/2.0*(RANGE2-RANGE1))*(XXR2-XXR1)
0205          180 CONTINUE
0206          DO 200 IM=1,NMODE
0207          WN(IM)=EIGVL1(IM)+SCALE*(EIGVL2(IM)-EIGVL1(IM))
0208          G1(IM)=R11(IM)+SCALE*(R12(IM)-R11(IM))
0209          G2(IM)=R21(IM)+SCALE*(R22(IM)-R21(IM))
0210          G3(IM)=R31(IM)+SCALE*(R32(IM)-R31(IM))
0211          GA(IM)=RA1(IM)+SCALE*(RA2(IM)-RA1(IM))
0212          GT(IM)=RT1(IM)+SCALE*(RT2(IM)-RT1(IM))
0213          GA(IM)=RB1(IM)+SCALE*(RB2(IM)-RB1(IM))
0214          200 CONTINUE
C ***** PART 8 *****
C
0215          209 DO 210 J2=1,MDS0
0216          DO 210 J1=1,NMRE
0217          PL(J1,J2,I)=0.0
0218          QC(J1,J2)=0.0
0219          QS(J1,J2)=0.0
0220          WRITE(6,10001) RANCI,RANCI,RANCI
0221          DO 230 IM=1,NMODE
0222          SE(IM)=SE(IM)+WN(IM)*DR
0223          S1(IM)=S1(IM)+G1(IM)*DR
0224          S2(IM)=S2(IM)+G2(IM)*DR
0225          S3(IM)=S3(IM)+G3(IM)*DR
0226          SA(IM)=SA(IM)+GA(IM)*DR
0227          ST(IM)=ST(IM)+GT(IM)*DR
0228          SB(IM)=SB(IM)+GB(IM)*DR

```

MOATL SOURCE LISTING

CSN	STATEMENT
0229	QQ=EP4*S1(IM)+EP5*S2(IM)+EP6*S3(IM)+SA(IM)
0230	QQ=QQ+2.0*ST(IM)+SIG0*SIG0*(6.2831853*F/CTS)**2-WNC(IM)+WN(IM)
0231	QQ=QQ+2.0*SB(IM)+SIG1*SIG1*(6.2831853*F/CBS)**2-WNC(IM)+WN(IM)
0232	IF (QQ.LE.32.25) GO TO 215
0233	WRITE(6,11001) IM
0234	GO TO 230
0235	215 Q2=1.0/EXP(QQ)
0236	DO 220 J2=1,MDS0
0237	DO 220 J1=1,MORE
0238	Q1=RE(J1,IM)+SM(J2,IM)+DSQRT(RAN(I))/SE(IM)
0239	IF (ABS(Q1).GE.10.**(-10)) GO TO 217
0240	WRITE(6,12001) IM,DEPS0(J2),DEPRE(J1)
0241	GO TO 220
0242	217 Q=Q1*Q2
0243	QS(J1,J2)=QS(J1,J2)+Q*DSIN(SEC(IM))
0244	QC(J1,J2)=QC(J1,J2)+Q*DCOS(SEC(IM))
0245	PL(J1,J2,I)=PL(J1,J2,I)+Q*Q
0246	220 CONTINUE
0247	230 CONTINUE
C	C ***** PART 9 *****
C	DO 270 J2=1,MDS0
0248	DO 270 J1=1,MORE
0250	COPL(J1,J2,I)=QSC(J1,J2)+QSC(J1,J2)+QC(J1,J2)*QC(J1,J2)
0251	PHASEC(J1,J2)=ATAN2(QSC(J1,J2),QC(J1,J2))*57.295779513
0252	IF (PHASEC(J1,J2).LT.0.) PHASE(J1,J2)=360.+PHASEC(J1,J2)
0253	IF (ISPRD.EQ.0.AND.DEPRE(J1).LE.H10) COPL(J1,J2,I)=-10.0*ALOG10
	>6.283*COPL(J1,J2,I)*RERH01/RERH01/(H10*HS)
0254	IF (ISPRD.EQ.0.AND.DEPRE(J1).GT.H10) COPL(J1,J2,I)=-10.0*ALOG10
	>6.283*COPL(J1,J2,I)*RERH02/RERH02/(H10*HS)
0255	IF (ISPRD.EQ.1.AND.DEPRE(J1).LE.H10) COPL(J1,J2,I)=-10.0*ALOG10
	>6.283*COPL(J1,J2,I)*RERH01/RERH01/(H10*HS*RANCI))
0256	IF (ISPRD.EQ.1.AND.DEPRE(J1).GT.H10) COPL(J1,J2,I)=-10.0*ALOG10
	>6.283*COPL(J1,J2,I)*RERH02/RERH02/(H10*HS*RANCI))
0257	IF (ISPRD.EQ.0.AND.DEPRE(J1).LE.H10) PL(J1,J2,I)=-10.0*ALOG10
	>6.283*PL(J1,J2,I)*RERH01/RERH01/(H10*HS)
0258	IF (ISPRD.EQ.0.AND.DEPRE(J1).GT.H10) PL(J1,J2,I)=-10.0*ALOG10
	>6.283*PL(J1,J2,I)*RERH02/RERH02/(H10*HS)
0259	IF (ISPRD.EQ.1.AND.DEPRE(J1).LE.H10) PL(J1,J2,I)=-10.0*ALOG10
	>6.283*PL(J1,J2,I)*RERH01/RERH01/(H10*HS*RANCI))
0260	IF (ISPRD.EQ.1.AND.DEPRE(J1).GT.H10) PL(J1,J2,I)=-10.0*ALOG10
	>6.283*PL(J1,J2,I)*RERH02/RERH02/(H10*HS*RANCI))
0261	270 CONTINUE
0262	IF (NDRE+MDS0.EQ.2) GO TO 295
C	C ***** PART 10 *****
C	DO 290 J2=1,MDS0
0263	WRITE(6,13001) DEPS0(J2),DEPS0(J2)
0264	

MILLER AND WOLF

CROSS REFERENCE LISTING

MOATL LABEL	CROSS REFERENCE LISTING TYPE	DEFN	REFERENCES
90		58	52
95		115	110
100		118	109
110		119	87
111		131	130
112		132	126
113		141	133
115		142	120
120		146	188
125		147	145
128		155	154
129		156	153
130		164	152
150		187	179
160		189	166
170		204	201
180		205	194
200		214	206
209		215	144
210		219	215
215		235	232
217		242	239
220		246	236
230		247	221
270		261	248
280		266	265
290		267	263
295		269	262
300		270	142
310		289	282
320		295	290
330		296	272
340		297	59
1000		11	37
1001		18	41
2000		12	38
2001		19	42
3000		13	44
3001		20	43
3002		21	45
4000		14	46
4001		22	48
5000		15	67
5001		23	49
6000		16	68
6001		24	63
7000		17	75
7001		25	69
8001		26	121
9001		27	122
			114
			216
			237
			234
			249
			268
			287
			273
			271
			60
			167
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			47
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			165
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			170
			176
			177

MILLER AND WOLF

MOATL CROSS REFERENCE LISTING

SYMBOL	TYPE/USAGE	REFERENCES
EIGVL1	R*8 ARR	2 10
EIGVL2	R*8 ARR	2 10
ENDPLT	SBR	298
EPSLN	R*4 VAR	4 68
EP1	R*4 VAR	38 42
EP2	R*4 VAR	38 42
EP3	R*4 VAR	38 42
EP4	R*4 VAR	64 229
EP5	R*4 VAR	65 229
EP6	R*4 VAR	66 229
EXP	R*4 IFN	235
F	R*4 VAR	5 61
FLOAT	R*4 IFN	115
FLUID	SBR	83 174
GA	R*4 ARR	10 138
GB	R*4 ARR	10 140
GT	R*4 ARR	10 139
G1	R*4 ARR	10 135
G2	R*4 ARR	10 136
G3	R*4 ARR	10 137
MS	R*4 VAR	123 127
		260
M10	R*4 VAR	72 110
		257 258
M11	R*4 VAR	67 69
M12	R*4 VAR	5 71
M2	R*4 VAR	3 67
H202MO	R*4 ARR	3 100
I	I*4 VAR	46 47
		146 146
		254 254
		259 259
		266 266
		292
IA1	I*4 VAR	112 113
		154 155
IA2	I*4 VAR	199 200
IFIX	I*4 IFN	53 112
IFREQ	I*4 VAR	59
III	I*4 VAR	40 83
IM	I*4 VAR	87 88
		93 94
		99 100
		118 118
		135 135
		152 155
		161 162
		183 183
		203 203
		208 208
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MILLER AND WOLF

MOATL	CROSS REFERENCE LISTING		REFERENCES
SYMBOL	TYPE/USAGE		
PPRCN	R** VAR	7	36
PRCSM	I** PAR	9	36
Q	R** VAR	242	243
OC	R** ARR	10	218
OO	R** VAR	229	230
OS	R** ARR	10	219
O1	R** VAR	238	239
O2	R** VAR	235	242
R\$1ALA	SBR		
R\$1AT2	SBR		
R\$1CCS	SBR		
R\$1DSN	SBR		
R\$1DSQ	SBR		
R\$1EXP	SBR		
RAN	R** ARR	10	51
RANGE1	R** VAR	259	260
RANGE2	R** VAR	68	69
RA1	R** ARR	70	145
RA2	R** ARR	10	96
RB1	R** ARR	10	97
RB2	R** ARR	10	100
REC	R** ARR	10	101
REC	I** PAR	10	118
REC5	I** PAR	8	10
REMO1	R** VAR	73	253
REMO2	R** VAR	74	254
RHO1	R** VAR	5	67
RHO2	R** VAR	5	67
RHO3	R** VAR	5	67
RMAX	R** VAR	38	42
RHXKM	R** VAR	53	54
RNG	I** PAR	8	10
RT1	R** ARR	10	98
RT2	R** ARR	10	99
R11	R** ARR	10	90
R12	R** ARR	10	91
R21	R** ARR	10	92
R22	R** ARR	10	93
R31	R** ARR	10	94
R32	R** ARR	10	95
SA	R** ARR	10	106
SB	R** ARR	10	108
SCALE	R** VAR	189	190
SE	R** ARR	212	213
SHEAR	R** VAR	2	10
SIG0	R** VAR	3	68
SIG1	R** VAR	38	42
SM	R** ARR	38	42
	R** ARR	10	131
		143	143
		283	291
		70	145
		146	147
		138	161
		161	184
		140	163
		163	186
		238	10
		10	10
		253	255
		254	256
		69	73
		69	74
		69	74
		69	165
		69	168
		42	50
		274	278
		10	10
		139	162
		162	185
		135	158
		181	208
		159	209
		182	209
		159	210
		160	210
		226	229
		228	231
		191	192
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		209	209
		210	210
		243	243
		244	244
		230	230
		231	231
		238	238
		255	255
		238	238
		255	255
		210	210
		211	211

HOATL CROSS REFERENCE LISTING
SYMBOL TYPE/USAGE REFERENCES

SYMBOL	TYPE/USAGE	REFERENCES	10	10	10	10	10	10	10	10	10	10
SOC	I**	PAR	8	10	10	10	10	10	10	10	10	10
SBLTD	SBR	SBR	84	175								
ST	R**	ARR	10	107	227	227	230					
SYMBQL	SBR	SBR	295									
S1	R**	ARR	10	103	223	223	229					
S2	R**	ARR	10	104	224	224	229					
S3	R**	ARR	10	105	225	225	229					
TH	CGM	CGM	4									
TITLE	R**	ARR	10	37	42	43	60	63				
TN	CGM	CGM	3									
TNH	CGM	CGM	6									
TNI	CGM	CGM	5									
TNIN	CGM	CGM	7									
UNRPI	R**	ARR	3	118	118	118	131	131	155	202	202	202
UNRM2	R**	ARR	3	155	203	203	203					
WN	R**	ARR	2	10	134	207	222	230	230	231	231	
X	R**	VAR	283	288	289	291	295					
XLENG	R**	VAR	54	55	274	275	278	296				
XXR1	R**	VAR	202	204	204							
XXR2	R**	VAR	203	204								
X2	R**	VAR	55	281								
V	R**	VAR	284	285	285	286	286	288	289	293	293	294
YLENG	R**	VAR	295	57	275	277	278	284	285	285	285	292
Y2	R**	VAR	56	57								
Z1	R**	ARR	293	279	280							
Z2	R**	ARR	3	75	169							
	R**	ARR	3	76	170							

```

SOURCE LISTING
STATEMENT
CSN
0001 SUBROUTINE FLUID
0002 >AK4,YCU,A,PV,SOUND
0003 >C1(150),ZC(150),C2(150),ABSOR(150),ATTEN2(150),
>ATTEN3(150),ATTENS(150),AIRP2(150),H2ONDK(150),DUNRH1(150),I202),
>H2ON2(150),I202),MDPRINT,INCL,INC2,M2,L11,L12,SHEAR,NMIDE,KA,NDI,
>ND2,NZ
0004 COMMON/INI/RH01,RH02,RH03,M12,COMP,F,M1
0005 COMMON/INH/ANK(150)
0006 COMMON/NI/SOUND(1202),SPEED(1202),TWOPI,DL1,MH1,DL2,MH2,WATCH,
>N1PLS1,N1PLS2,N1PLS3,N1MNS1,N1MNS2,N2MNS1,NT,NTRNS2
0007 COMMON/NIFLUZA
0008 COMMON/NAH/AK1,AK2,LQMP
0009 COMMON/NIH/IERO,NCR,YOU(1202),I,IFG
0010 COMMON/INI/PPRCN,PMGTD
0011 DIMENSION LAMP(3),DEPTH(1202),X(650),Y(650),MNUM(12),LDEPTH(2)
0012 DATA LAMP/,DEP,TH,/,/
0013 DATA LAMP/,AMPL,ITUD,/,E,/
0014 >FORMAT (//,55X,'COMPRESSIONAL VELOCITY',/,60X,F10.3)
0015 > VELOCITY,/,/
0016 >FORMAT (45X,F11.3)
0017 >FORMAT (/)
0018 >FORMAT (I11,/,35X,'MAXIMUM NUMBER OF MGES =',I3,10X,'NUMBER OF MO
>DES CALCULATED =',I3,/)
0019 >FORMAT (I11)
0020 >FORMAT ('MODE NO. =',I3,5X,'PHASE VELOCITY =',D20.12)
0021 >FORMAT ('UPPER AMPLITUDES MATCHED FOR THIS MODE STARTING AT NORMA
>LIZED DEPTH =',F7.4)
0022 >FORMAT ('NUMBER OF ITERATE SOLUTIONS =',I3,5X,'THE EIGENFUNCTION
>WAS SCALED DOWN',I3,' TIME(S)')
0023 >FORMAT ('LAYER 2 ATTEN RATIO = DEFAULT ZERO')
0024 >FORMAT ('LAYER 3 ATTEN RATIO = DEFAULT ZERO')
0025 >RATIO LAYER 3 ATTEN RATIO WATER ABSORPTION LAYER 2 ATTEN
>ATTEN H2ON2ND SCA
2001 >FORMAT (D20.12,4X,F11.4,13X),E11.4,4X,F11.4,9X,F11.4,/,/
2101 >FORMAT (I11,'MODE AMPLITUDES FOR THE SOURCE FREQUENCY OF',F9.3,' H
>Z,/,/,',FIRST LAYER',/,/)
2201 >FORMAT (10X,I2(1X,I3,'MODE'),/,/)
2301 >FORMAT (4X,2A5,I2(1X,2A5,A1))
2401 >FORMAT (13F10.4)
2501 >FORMAT (I11,'MODE AMPLITUDES FOR THE SOURCE FREQUENCY OF',F9.3,' H
>Z,/,/,',SECOND LAYER',/,/)
TWPI=6.2831853071795800
FZ=(F/1000.)*(CF/1000.)
CPM=1.*FZ/(1.*FZ)+40.*FZ/(4100.*FZ)+7.75E-4.*FZ
FPH=CPM*.1151292546+1.093613298E-3
X(1)=Z(1)
CINI=C1(1)

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FLUID	CSN	SOURCE LISTING	STATEMENT
	0038		C*MAX1=C1(C1)
	0039		DO 70 J=2,N01
	0040		IF (C1(CJ)).LT.C*MIN1) C*MIN1=C1(CJ)
	0041		IF (C1(CJ)).GT.C*MAX1) C*MAX1=C1(CJ)
	0042		X(J)=Z1(CJ)
	0043		Z0 Z1(CJ)=Z1(CJ)/H1?
	0044		Y(1)=Z2(C1)
	0045		Z2(C1)=Z1(N01)
	0046		C*MIN2=C2(C1)
	0047		C*MAX2=C2(C1)
	0048		DO 70 J=2,N02
	0049		IF (C2(CJ)).LT.C*MIN2) C*MIN2=C2(CJ)
	0050		IF (C2(CJ)).GT.C*MAX2) C*MAX2=C2(CJ)
	0051		Y(J)=Z2(CJ)
	0052		Z0 Z2(CJ)=Z2(CJ)/H1?
	0053		C*MIN=AMIN(C*MIN1,C*MIN2)
	0054		WRITE(6,'001) COMP
	0055		WRITE(6,'9001)
	0056		WRITE(6,'10001) (Z1(I),X(I),C1(I),I=1,N01)
	0057		WRITE(6,'11001)
	0058		WRITE(6,'10001) (Z2(I),Y(I),C2(I),I=1,N02)
	0059		Z11=08LE(1.0)/L11
	0060		H*1=DL1*DL1*H12*H12
	0061		H*2=08LE(H2)/H12/L12
	0062		H*2=DL2*DL2*H12*H12
	0063		N1=L1+1
	0064		N1*PLS1=N1+1
	0065		N1*PLS2=N1+2
	0066		N1*PLS3=N1+3
	0067		N1*MNS1=N1-1
	0068		N1*MNS2=N1-2
	0069		N2=L12+1
	0070		N2*MNS1=N2-1
	0071		N2*MNS2=N2-2
	0072		N1*MNS1=N1-1
	0073		N1*MNS2=N1-2
	0074		DEPTH(1)=0.0
	0075		DEPTH(N1)=1.0
	0076		DEPTH(N1*PLS1)=1.0
	0077		DEPTH(N1)=08LE(H2)/H12+1.0
	0078		SPEED(1)=H*1/C1(C1)
	0079		SPEED(N1)=H*1/C1(N01)/C1(N01)
	0080		SPEED(N1*PLS1)=H*2/C2(C1)/C2(C1)
	0081		SPEED(N1)=H*2/C2(N02)/C2(N02)
	0082		K=>
	0083		DO 50 INTERP=2,N1*MNS1
	0084		DEPTH(INTERP)=(INTERP-1.0)*DL1
	0085		KK=K
	0086		DO 40 J=KK,N01
	0087		IF (DEPTH(INTERP).GT.Z1(J)) GO TO 40

FLUID	CSN	SOURCE LISTING	STATEMENT
	0098		SPEED(INTERP)=(C1(J)-C1(J-1))*(DEPTH(INTERP)-Z1(J-1))/
	0099		>C09LF(Z1(J))-Z1(J-1))*C1(J-1)
	009C		SOUND(INTERP)=SPEED(INTERP)
	0091		SPEED(INTERP)=HH1/(SPEED(INTERP)*SPEED(INTERP))
	0092		GM TO 50
	0093		GM TO 50
	0094		40 K=K+1
	0095		50 CONTINUE
	0096		K=?
	0097		GM TO INTERP=M1PLS2,NIANS1
	0098		DEPTH(INTERP)=(INTERP-1-N1)*DL2+1.0
	0099		KK=K
	0100		GM 60 J=KK,MD2
	0101		IF (DEPTH(INTERP)-GY-Z2(J)) GO TO 60
	0102		SPEED(INTERP)=(C2(J)-C2(J-1))*(DEPTH(INTERP)-Z2(J-1))/
	0103		>C09LF(Z2(J))-Z2(J-1))*C2(J-1)
	0104		SOUND(INTERP)=SPEED(INTERP)
	0105		SPEED(INTERP)=HH2/(SPEED(INTERP)*SPEED(INTERP))
	0106		GM TO 70
	0107		GM TO 70
	0108		60 K=K+1
	0109		70 CONTINUE
	0110		ZZERO=0
	0111		AK1=TM*PI*F/COMP
	0112		AK3=AK1
	0113		AK7=TM*PI*F/CMIN
	0114		SREC=39.4794176*F*(C1(1)*C1(1))
	0115		PJTTOM=39.4784176*F*(C1(N01)*C1(N01))
	0116		CALL IIRTF (AK1)
	0117		MAXM=NGP
	0118		MMODE=PI*NOCMODE,MAXMD)
	0119		MGRPS=INTCNMODE/12.0+0.02)+1
	0120		GM 350 M=1,MGRPS
	0121		J9ASF=(M-1)*12
	0122		IF (M.LI.MGRPS) NIC=12
	0123		IF (M.EQ.MGRPS) NIC=M00CNMODE,12)
	0124		IF (NIC.EQ.0) GO TO 350
	0125		GM 340 TC=1,NIC
	0126		I=TBASE+IC
	0127		MNUM(IC)=I
	0128		CALL HALFF
	0129		AK1=AK3
	0130		AK2=AKN(I)
	0131		POJ=0.0
	0132		POJ1=0.0
	0133		POJ2=0.0
	0134		POJ3=0.0
	0135		EVEN=0.0
			EVEN1=0.0
			EVEN2=0.0
			EVEN3=0.0
			DC 200 J=?,NIANS1,2

FLUID	CSN	SOURCE LISTING	STATEMENT
	0136	200	EVEN1=EVENT+YOU(J)*YOU(J)
	0137	DO 210 J=3,N1MNS2*2	
	0138	210	ODD1=ODD1+YOU(J)*YOU(J)
	0139	DO 220 J=N1PLS2,NTMNS1*2	
	0140	220	EVEN2=EVEN2+YOU(J)*YOU(J)
	0141	DO 230 J=N1PLS3,NTMNS2*2	
	0142	230	ODD2=ODD2+YOU(J)*YOU(J)
	0143	DO 234 J=2,N1MNS1*2	
	0144	234	EVEN3=EVEN3+YOU(J)*YOU(J)/SOUND(J)
	0145	DO 236 J=3,N1MNS2*2	
	0146	236	ODD3=ODD3+YOU(J)*YOU(J)/SOUND(J)
	0147	DO 240 J=N1PLS2,NTMNS1*2	
	0148	240	EVEN4=EVEN4+YOU(J)*YOU(J)/SOUND(J)
	0149	DO 250 J=N1PLS3,NTMNS2*2	
	0150	250	ODD4=ODD4+YOU(J)*YOU(J)/SOUND(J)
	0151	AI1=RH91*(CDL1/3.0)*(YOU(1)*YOU(1)+4.0*EVEN1+2.0*ODD1+YOU(N1)*YOU(N1))	
	0152	AI2=RH92*(CDL2/3.0)*(YOU(N1+1)*YOU(N1+1)+4.0*EVEN2+2.0*ODD2+YOU(NT)*YOU(NT))	
	0153	AI3=RH93*(RH3/2.0)*YOU(NT)*YOU(NT)/RH93/2.0/DSQRT(A)	
	0154	AI4=RH94*(CDL2/3.0)*(YOU(N1+1)*YOU(N1+1)+4.0*EVEN+2.0*ODD+YOU(NT)*YOU(NT)/C2(ND2))	
	0155	AI5=RH91*(CDL1/3.0)*(YOU(1)*YOU(1)+4.0*EVEN3+2.0*ODD3+YOU(N1)*YOU(N1)/C1(ND1))	
	0156	AI=AI1+AI2+AI3	
	0157	ANRM=SQRT(1.0/AI)	
	0158	DO 260 J=1,NT	
	0159	IF (KA.EQ.0) UNRM(I,J)=YOU(J)*ANRM	
	0160	IF (KA.EQ.1) UNRM(I,J)=YOU(J)*ANRM	
	0161	260 CONTINUE	
	0162	IF (KA.EQ.1) GO TO 270	
	0163	YN1=UNRM(I,1)	
	0164	YN2=UNRM(I,2)	
	0165	YN3=UNRM(I,3)	
	0166	YN4=UNRM(I,4)	
	0167	YN5=UNRM(I,N1PLS1)	
	0168	YN6=UNRM(I,N1PLS2)	
	0169	YN7=UNRM(I,N1PLS3)	
	0170	GO TO 275	
	0171	YN1=UNRM2(I,1)	
	0172	YN2=UNRM2(I,2)	
	0173	YN3=UNRM2(I,3)	
	0174	YN4=UNRM2(I,4)	
	0175	YN5=UNRM2(I,N1PLS1)	
	0176	YN6=UNRM2(I,N1PLS2)	
	0177	YN7=UNRM2(I,N1PLS3)	
	0178	YU6=C-3.*YN1+4.*YN2-YNM3/(2.*DL1)	
	0179	YU6=C-3.*YN5+4.*YN6-YNM6/(2.*DL2)	
	0180	AKN2=AKN(I)*AKN(I)	
	0181	IF (SREC-AKM2.GT.PPRCN) GO TO 280	

FLUID	CSN	SOURCE LISTING	STATEMENT
	0182		AIRH20(I)=0.0
	0192		GO TO 290
	0184	280	AIRH20(I)=RH01*DYQUA+DYQUA/(4.*AKN(I)*H12**3*SQR(SRFG-AKN2))
	0195	290	IF (BOTTON-AKN2-GT.0PRCN) GO TO 300
	0186		H2M2ND(I)=0.0
	0187		GO TO 310
	0188	300	H2M2ND(I)=RH01*SQR(90TTOM-AKN2)*(YH*4+YH*4+DYQUR* >DYQUR/(H12*H12*(90TTOM-AKN2)))/(4.0*AKN(I)*H12)
	0185	310	PV=YHOPI*F/AKN(I)
	0190		IF (AI4-GT.AI/PMGTD) GO TO 313
	0191		AI4=0.
	0192	313	ATTEN2(I)=6.2831853*F*AI4/(AKN(I)*AI)
	0193		IF (AI3-GT.AI/PMGTD) GO TO 315
	0194		AI3=0.
	0195	315	ATTEN2(I)=6.2831853*F*AI3/(COMP*AKN(I)*AI)
	0196		ATTEN2(I)=0.
	0197		ABSOR(I)=6.2831853*F*AI5*EPW/(AKN(I)*AI)
	0198		IF (IC-GT.1) GO TO 330
	0199		WRITE(6,12001) MAXND,MODE
	0200	330	IF (MOD(IC,7).EQ.0) WRITE(6,13001)
	0201		WRITE(6,14001) I,PV
	0202		IF (TZER.EQ.2) WRITE(6,15001) DEPTH(MATCH)
	0203		WRITE(6,16001) L7SP,IFG
	0204		IF (AI4.LE.AI/PMGTD) WRITE(6,17001)
	0205		IF (AI3.LE.AI/PMGTD) WRITE(6,18001)
	0206		WRITE(6,19001)
	0207		WRITE(6,20001) AKN(I),ABSOR(I),ATTEN2(I),ATTEN2(I),AIRH20(I), >H2M2ND(I)
	0208	340	CONTINUE
	0209		IF (MDPRNT.EQ.0) GO TO 350
	0210		WRITE(6,21001) F
	0211		WRITE(6,22001) (MDNUM(K),K=1,NIC)
	0212		WRITE(6,23001) LDEPTH,(LAMP(1),LAMP(2),LAMP(3),K=1,NIC)
	0213		I1=IBASE+1
	0214		INIC=IBASE+NIC
	0215		DO 345 J=1,N1,INCI
	0216		IF (KA.EQ.0) WRITE(6,24001) DEPTH(J),CUNRM1(K,J),K=11,INIC)
	0217		IF (KA.EQ.1) WRITE(6,24001) DEPTH(J),CUNRM2(K,J),K=11,INIC)
	0218	345	CONTINUE
	0219		WRITE(6,25001) F
	0220		WRITE(6,22001) (MDNUM(K),K=1,NIC)
	0221		WRITE(6,23001) LDEPTH,(LAMP(1),LAMP(2),LAMP(3),K=1,NIC)
	0222		DO 349 J=N1PLS1,NT,IN2
	0223		IF (KA.EQ.0) WRITE(6,24001) DEPTH(J),CUNRM1(K,J),K=11,INIC)
	0224		IF (KA.EQ.1) WRITE(6,24001) DEPTH(J),CUNRM2(K,J),K=11,INIC)
	0225	349	CONTINUE
	0226	350	CONTINUE
	0227		RETURN
	0228		END

FLUID CROSS REFERENCE LISTING

FLUID LABEL	TYPE	DEFN	REFERENCES
2C		43	39
30		52	48
40		92	86
50		93	83
60		104	98
70		105	95
200		135	135
210		137	137
220		140	139
230		142	141
234		144	143
236		146	145
240		148	147
250		50	149
260		161	158
270		171	162
275		178	170
280		184	181
290		185	183
300		188	188
310		189	187
313		192	190
315		195	193
31C		200	198
340		208	121
345		218	215
349		225	222
350		226	116
8001		14	54
9001		15	55
10001		16	56
11001		17	57
12001		18	199
13001		19	200
14001		20	201
15001		21	202
16001		22	203
17001		23	204
18001		24	205
19001		25	206
20001		26	207
21001		27	210
22001		28	211
23001		29	212
24001		30	216
25001		31	219
			120
			209
			58
			87
			91
			99
			103
			220
			221
			217
			223
			224

MILLER AND WOLF

FLUID CROSS REFERENCE LISTING

SYMBOL	TYPE/USAGE	REFERENCES
A	R#R VAR	7
ABSCR	R#4 ARR	3 197
AI	R#4 VAR	156 157 190
ATH20	R#4 APR	3 182
BJ1	R#4 VAR	151 156
BJ2	R#4 VAR	152 156
BJ3	R#4 VAR	153 156
BJ4	R#4 VAR	154 190
BJ5	R#4 VAR	155 197
BKN	R#R ARR	2 5
AKN2	R#4 VAR	190 191
AK1	R#8 VAR	2 8
BK2	R#8 VAR	2 8
BK3	R#9 VAR	2 108
AMIN1	R#4 IFN	53
AMTR*	R#4 VAR	157 159
ATTEN	R#4 ARR	3 195 207
ATTENS	R#4 ARR	3 196
ATTEN2	R#4 ARR	3 192
BOTTOM	R#6 VAR	111 145 188
CMAX1	R#4 VAR	38 41
CMAX2	R#4 VAR	47 50
CMIN	R#4 VAR	53 109
CMIN1	R#4 VAR	37 40
CMIN2	R#4 VAR	49 49
COMP	R#4 VAR	4 54
CI	R#4 ARR	3 37 88
C2	R#4 ARR	98 98
DBLE	R#4 IFN	100 100
DEPT4	R#R ARR	2 216
LI	R#R VAR	2 6
DL2	R#R VAR	2 6
DSORT	R#6 IFN	153 184
DYDUA	R#6 VAR	178 188
DYCLR	R#4 VAR	179 188
EPW	R#4 VAR	34 35
FVEN	R#4 VAR	131 148
FVEN1	R#4 VAR	136 136
FVEN2	R#4 VAR	133 160
FVEN3	R#4 VAR	134 144
F	R#4 VAR	4 33 219
FLUID	R#4 ENT	1 1
F2	R#4 VAR	33 34
HALFC	R#9 S9R	124 124
HP1	R#9 VAR	2 6
HP2	R#R VAR	2 6

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FLUTO CROSS REFERENCE LISTING REFERENCES

SYMBOL	TYPE/USAGE	REFERENCES	60	60	61	62	62	77	184	188	188	
H1?	R** VAR	4 188	43	52	60	60	61	62	62	77	184	188
M2	** VAR	3 188	61	77								
M2*2ND	R** ARR	3 186	186	188	207		58	58	122	58	184	188
Y	** VAR	9 56	56	188	56		58	58	122	58	184	188
		159	160	163	164		166	167	171	169	172	173
		174	175	176	177		180	182	184	184	188	188
		189	192	192	195		180	182	184	184	188	188
		207	207	207	195		195	197	207	201	207	207
		117	122	213	214		196	197	207	201	207	207
IRASE	I** VAR	171	122	213	214							
IC	I** VBR	171	122	123	198							
IFG	I** VAR	9	203									
INCL	I** VAR	3	215									
INCL2	I** VAR	3	272									
INIC	I** VAR	214	216	223	224							
INT	I** IFN	115										
INTERP	I** VAR	93	94	84	97	88	88	89	90	90	90	95
		96	96	99	100	100	101	102	102	102	102	
J191F	S**	112		202								
JZFR?	I** VAR	9	106	202	223	224						
Y1	I** VAR	213	216	217	223	224						
J	I** VBR	39	40	40	41	41	42	42	48	43	48	49
		50	50	51	51	51	52	52	88	88	88	88
		86	89	98	99	100	100	100	100	100	100	100
		136	137	138	138	139	140	140	142	142	143	144
		144	144	145	146	146	146	147	148	148	149	150
		150	150	158	159	159	160	160	168	168	168	168
		222	223	223	224	224	224	224	216	216	216	217
K	I** VAR	82	85	92	92	94	97	104	104	211	211	216
		216	217	217	220	220	221	223	223	224	224	
KA	I** VBR	3	159	160	162	162	217	223	224			
KK	I** VAR	85	86	97	98							
LAMP	I** ARR	11	13	212	212	212	212	212	212	212	212	212
DEPTH	I** ARR	11	12	212	221	221						
LII	I** VAR	3	59	63								
L12	I** VAR	3	61	69								
LAMP	I** VAR	8	203									
P	I** VBR	116	117	118	119							
WATCH	I** VAR	6	202									
MAXND	I** VBR	113	114	199								
ONUM	I** ARR	11	123	211	220							
DDORT	I** VAR	3	209									
MGRCS	I** VBR	115	116	119								
MINO	I** IFN	114										
CO	I** IFN	119										
NCR	I** VAR	9	113									
ND1	I** VAR	3	19	45	56	79	79	86	111	111	155	
ND2	I** VAR	3	48	58	81	81	98	154				
NI	C**	2										
NI	C**	6										

CROSS REFERENCE LISTING

FLUID	SYMRCL	CROSS REFERENCE LISTING	TYPE/USAGE	REFERENCES
	YAM7	R*4	VAR	169 177 179
	YCU	R*8	ARR	2 9 136
				146 146 148
				152 152 153
				159 160
	Z1	R*4	ARR	3 36 42
	72	R*4	ARR	3 44 45
				136 138 140
				148 150 151
				153 154 154
				138 140 142
				150 151 151
				154 154 155
				140 140 142
				151 151 151
				154 154 155
				56 56 58
				87 87 88
				99 99 100
				144 144 144
				152 152 152
				155 155 155

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SOURCE LISTING
STATEMENT
CSN
0001 SUBROUTINE ITRF (AKN)
0002 DOUBLE PRECISION OMEGA2,TWOPI,A,HH2,AKN,YOU,SPEED,DL2,PPLUS1,
0003 >PMNSI,B,DL1,HH1,UMAX,UABVL,SOUND
0004 COMMON/TN1/RHO1,RHO2,RHO3,HI2,COMP,F,N1
0005 COMMON/NI/SOUND(1202),SPEED(1202),TWOPI,DL1,HH1,DL2,HH2,MATCH,
0006 >NIPLS1,NIPLS2,NIPLS3,NIPMS1,NIPMS2,N2MNS1,N1,NTMNS2
0007 COMMON/NI/FLU/A
0008 COMMON/NIH/IZERO,NCR,YOU(1202),I,IFG
0009 COMMON/TNIH/PPRCN,PMGTD
0010 MATCH=0
0011 IF (IZERO.NE.1) GO TO 10
0012 DO 6 J=3,NIPMS2
0013 IF (TWOPI*F/SOUND(J)).LT.AKN) GO TO 6
0014 MATCH=J
0015 GO TO 10
0016 6 CONTINUE
0017 DO 8 J=NIPLS3,NTMNS2
0018 IF (TWOPI*F/SOUND(J)).LT.AKN) GO TO 8
0019 MATCH=J
0020 GO TO 10
0021 8 CONTINUE
0022 MATCH=NTMNS2
0023 10 NCR=0
0024 IFG=0
0025 OMEGA2=TWOPI*TWOPI*F*F
0026 A=DABS(HH2*(AKN*AKN-OMEGAZ/(DBLE(COMP)*COMP)))
0027 YOU(NT-1)=YOU(NT)+DSQRT(A)-YOU(NT)*(OMEGAZ*SPEED(NT)-HH2*AKN*AKN)/
>2.0
0028 UMAX=DMAX1(DABS(YOU(NT)),DABS(YOU(NT-1)))
0029 A=A/(DL2*DL2)
0030 DO 31 J=2,N2MNS1
0031 NTMJ=NT-J
0032 PPLUS1=12.0+OMEGAZ*SPEED(NTMJ)-HH2*AKN*AKN
0033 P=24.0-10.0*(OMEGA2*SPEED(NTMJ+1)-HH2*AKN*AKN)
0034 PMNS1=12.0+OMEGAZ*SPEED(NTMJ+2)-HH2*AKN*AKN
0035 YOU(NTMJ)=(P/PPLUS1)*YOU(NTMJ+1)-(PMNS1/PPLUS1)*YOU(NTMJ+2)
0036 UABVL=DABS(YOU(NTMJ))
0037 IF (UABVL.GT.UMAX) UMAX=UABVL
0038 IF (DSIGN(1.0,YOU(NTMJ))*YOU(NTMJ+1).LE.0.) NCR=NCR+1
0039 IF (UABVL.LT.PMGTD) GO TO 22
0040 DO 21 JD=NTMJ,NT
0041 IF (DABS(YOU(JD)).LT.1.1.D0) YOU(JD)=0.
0042 21 YOU(JD)=YOU(JD)/PMGTD
0043 UMAX=UMAX/PMGTD
0044 IFG=IFG+1
0045 22 IF (NTMJ.EQ.MATCH) GO TO 131
0046 31 CONTINUE
0047 B=(3.0*YOU(NIPLS1)-4.0*YOU(NIPLS1+1)+YOU(NIPLS1+2))/(2.0*DL2)

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ITRTF SOURCE LISTING

C.SN	STATEMENT
0048	YOU(N1)=RH02*YOU(N1PLS1)/RH01
0049	YOU(N1-1)=YOU(N1)+DL1*8-YOU(N1)*(OMEGA2*SPEED(N1)-HH1*AKN*AKN)/2.0
0050	IF (DABS(YOU(N1))-GT.UMAX) UMAX=DABS(YOU(N1))
0051	IF (DABS(YOU(N1-1))-GT.UMAX) UMAX=DABS(YOU(N1-1))
0052	IF (DSIGN(1.00,YOU(N1))*YOU(N1-1).LE.0.) NCR=NCR+1
0053	DO 121 J=2,N1MNS1
0054	N1MJ=N1-J
0055	PPLUS1=12.0*(OMEGA2*SPEED(N1MJ)-HH1*AKN*AKN
0056	P=24.0-10.0*(OMEGA2*SPEED(N1MJ+1)-HH1*AKN*AKN
0057	PMNS1=12.0*(OMEGA2*SPEED(N1MJ+2)-HH1*AKN*AKN
0058	YOU(N1MJ)=(P/PPLUS1)*YOU(N1MJ+1)-(PMNS1/PPLUS1)*YOU(N1MJ+2)
0059	UABVL=DABS(YOU(N1MJ))
0060	IF (UABVL.GT.UMAX) UMAX=UABVL
0061	IF (DSIGN(1.00,YOU(N1MJ))*YOU(N1MJ+1).LE.0.) NCR=NCR+1
0062	IF (UABVL.LT.PMGTD) GO TO 51
0063	DO 41 JD=N1MJ,NT
0064	IF (DABS(YOU(JD)).LT.1.00) YOU(JD)=0.
0065	41 YOU(JD)=YOU(JD)/PMGTD
0066	UMAX=UMAX/PMGTD
0067	IFG=IFG+1
0068	51 IF (N1MJ.EQ.MATCH) GO TO 131
0069	121 CONTINUE
0070	GO TO 151
0071	131 IZER0=2
0072	YOU(I)=0.0
0073	YOU(2)=DSQRT(HH1)*1.0-10
0074	DO 135 J=3,N1
0075	PPLUS1=12.0*(OMEGA2*SPEED(J)-HH1*AKN*AKN
0076	P=24.0-10.0*(OMEGA2*SPEED(J-1)-HH1*AKN*AKN
0077	PMNS1=12.0*(OMEGA2*SPEED(J-2)-HH1*AKN*AKN
0078	PPLUS1=(P/PPLUS1)*YOU(J-1)-(PMNS1/PPLUS1)*YOU(J-2)
0079	IF (J.EQ.MATCH) GO TO 148
0080	YOU(J)=PPLUS1
0081	IF (DABS(YOU(J)).LT.PMGTD) GO TO 135
0082	DO 133 JD=2,J
0083	IF (DABS(YOU(JD)).LT.1.00) YOU(JD)=0.0
0084	133 YOU(JD)=YOU(JD)/PMGTD
0085	135 CONTINUE
0086	B=(-3.0*YOU(N1MNS2)+4.0*YOU(N1MNS1)-YOU(N1))/(2.0*DL1)
0087	YOU(N1PLS1)=RH01*YOU(N1)/RH02
0088	>(OMEGA2*SPEED(N1PLS1)-HH2*AKN*AKN)/2.0
0089	DO 145 J=N1PLS1,NTMNS2
0090	PPLUS1=12.0*(OMEGA2*SPEED(J)-HH2*AKN*AKN
0091	P=24.0-10.0*(OMEGA2*SPEED(J-1)-HH2*AKN*AKN
0092	PMNS1=12.0*(OMEGA2*SPEED(J-2)-HH2*AKN*AKN
0093	PPLUS1=(P/PPLUS1)*YOU(J-1)-(PMNS1/PPLUS1)*YOU(J-2)
0094	IF (J.EQ.MATCH) GO TO 148
0095	YOU(J)=PPLUS1
0096	IF (DABS(YOU(J)).LT.PMGTD) GO TO 145

MILLER AND WOLF

ITRIF	SOURCE LISTING
CSN	STATEMENT
0097	DO 143 JD=2+J
0098	IF (DABS(YOU(JD)).LT.1.00) YOU(JD)=0.0
0099	143 YOU(JD)=YOU(JD)/PMGTD
0100	145 CONTINUE
0101	GO TO 151
0102	148 JRN51=J-1
0103	DO 149 JD=2,JRN51
0104	YOU(JD)=(YOU(JD)/PPLUS1)*YOU(MATCH)
0105	IF (DABS(YOU(JD)).LT.1./PMGTD) YOU(JD)=0.0
0106	149 CONTINUE
0107	151 CONTINUE
0108	RETURN
0109	END

ITRTF CROSS REFERENCE LISTING

LABEL	TYPE	DEFN	REFERENCES
6		15	11
8		20	16
10		22	10
21		42	40
22		45	39
31		46	30
41		65	63
51		68	62
121		69	53
131		71	45
133		84	82
135		85	74
143		99	97
145		100	89
148		102	79
149		106	103
151		107	70
			12
			17
			14
			19
			68
			81
			96
			94
			101

SYMBOL TYPE/USAGE REFERENCES

A	R*8 VAR	2	5
AKN	R*8 DAR	1	2
		34	34
		76	76
B	R*8 VAR	2	47
COMP	R*4 VAR	3	25
DABS	R*4 IFN	25	28
		83	96
		25	26
DBLE	R*4 IFN	2	4
DL1	R*8 VAR	2	4
DL2	R*8 VAR	2	4
DMAX1	R*4 IFN	28	61
DSIGN	R*4 IFN	38	52
DSQRT	R*4 IFN	27	75
F	R*4 VAR	3	12
MH1	R*8 VAR	2	4
MH2	R*8 VAR	2	4
M12	R*4 VAR	3	4
I	I*4 VAR	6	23
IFG	I*4 VAR	6	44
IH	I*4 COM	8	67
ITRTF	I*4 ENT	1	10
IZERO	I*4 VAR	6	71
J	I*4 VAR	11	13
		76	78
		93	94
		40	41
JD	I*4 VAR	40	41
		27	27
		17	17
		49	49
		77	77
		49	49
		25	25
		86	86
		36	36
		105	105
		41	41
		50	50
		29	29
		25	25
		55	55
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MILLER AND WOLF

ITRTE CROSS REFERENCE LISTING

SYMBOL	TYPE/USAGE	REFERENCES	83	84	97	98	98	99	99	103	104	104	104	105
JMNS1	I*4 VAR	83	84	84	84	84	84	84	84	84	84	84	84	84
WACH	I*4 VAR	102	103	103	103	103	103	103	103	103	103	103	103	103
MCR	I*4 VAR	6	22	22	22	22	22	22	22	22	22	22	22	22
NI	COM	4												
NIFLU	COM	5												
NIM	COM	6												
NT	I*4 VAR	4	26	27	27	27	27	28	28	31	40	63	63	68
NTMJ	I*4 VAR	31	32	33	34	35	35	35	36	38	38	40	40	45
NTMNS2	I*4 VAR	4	16	21	89	49	49	50	50	51	51	52	52	52
NI	I*4 VAR	3	68	49	49	49	49	50	50	51	51	52	52	52
		54	74	86	87	87	87	87	87	87	87	87	87	87
		54	55	56	57	58	58	59	59	61	61	63	63	68
MIMJ	I*4 VAR	4	53	86										
MIMNS1	I*4 VAR	4	11	86										
MIMNS2	I*4 VAR	4	47	47	47	48	48	88	88	88				
MIPLS1	I*4 VAR	4	88											
MIPLS2	I*4 VAR	4	88											
MIPLS3	I*4 VAR	4	16	89										
MZMNS1	I*4 VAR	4	30											
OMEGA2	R*8 VAR	2	24	25	27	32	32	49	49	55	56	57	57	75
		76	77	88	90	91	92	91	92	93	96	99	99	105
P	R*8 VAR	2	33	35	56	58	58	78	78	93	96	99	99	105
PMGTD	R*4 VAR	7	39	42	69	62	62	66	66	84	84	84	84	84
PMNS1	R*8 VAR	2	34	35	57	58	58	77	78	92	93	93	93	93
PPLUS1	R*8 VAR	2	32	35	35	55	55	78	75	78	78	78	78	80
		90	93	93	93	95	95	104	104					
PPRCM	R*4 VAR	7												
RS1DSQ	SOR	3	48	87										
RM01	R*4 VAR	3	26	48	87									
RM02	R*4 VAR	3	26											
RM03	R*4 VAR	3	26											
SOUND	R*8 ARR	2	4	12	17	33	33	55	55	56	57	75	75	76
SPEED	R*8 ARR	2	4	27	32	33	33	49	49	56	57	75	75	76
		77	88	90	91	92	92							
TNI	COM	3												
TMIM	COM	7												
TM0PI	R*8 VAR	2	4	12	17	24	24	60	60	62	62	62	62	60
UABVL	R*8 VAR	2	36	37	37	39	39	50	50	50	51	51	51	60
URAX	R*8 VAR	2	8	28	37	37	37	43	43	50	51	51	51	60
		60	66	66	66	66	66	66	66	66	66	66	66	66
YOU	R*8 ARR	2	6	26	27	27	27	28	28	35	35	35	35	36
		38	38	41	41	42	42	47	47	47	48	48	48	49
		49	49	50	50	51	51	52	52	58	58	58	58	59
		61	61	64	64	65	65	72	73	78	78	78	78	81
		83	83	84	84	86	86	86	86	87	88	88	88	88
		93	93	95	96	98	98	99	99	104	104	104	104	105

SOURCE LISTING

CSN	STATEMENT
0001	SUBROUTINE HALFF
0002	DOUBLE PRECISION AK1,AK2,ANEW,AK,ZK,YOU,AKNL,AKNR,ZL,ZR,ARI,AL1,
0003	>ZL1,ZL1,ZNEW,AKA,AKN,UMAX
0004	COMMON/TNH/AKN(150)
0005	COMMON/TH/EPSLN
0006	COMMON/NH/AK1,AK2,LOOP
0007	COMMON/NIH/ZZERG,NCR,YOU(1202),I,IFG
0008	COMMON/TNH/PPRCN,PMGT0
0009	COMMON/TH/UMAX
	DIMENSION AK(2),ZK(2)
C	***** PART 1 *****
C	
0010	IZERO=0
0011	LOOP=0
0012	DO 52 K=1,2
0013	J=I+1-K
0014	IF (K.EQ.2) GO TO 12
0015	CALL ITRTF (AK1)
0016	LOOP=LOOP+1
0017	NA1=NCR
0018	CALL ITRTF (AK2)
0019	LOOP=LOOP+1
0020	NA2=NCR
0021	ANEW=((AK2-AK1)*(J-NA1)/(NA2-NA1))+AK1
0022	CALL ITRTF (ANEW)
0023	LOOP=LOOP+1
0024	IF (NCR.EQ.J) GO TO 42
0025	IF (NCR.GT.J) GO TO 32
0026	AK2=ANEW
0027	NA2=NCR
0028	GO TO 12
0029	32 AK1=ANEW
0030	NA1=NCR
0031	GO TO 12
0032	42 AK(K)=ANEW
0033	IF (K.EQ.1) IP1=IFG
0034	IF (K.EQ.2) IP2=IFG
0035	52 ZK(K)=YOU(1)
0036	AKNL=AK(1)
0037	AKNR=AK(2)
0038	ZL=ZK(1)
0039	ZR=ZK(2)
C	***** PART 2 *****
C	
0040	ICLSIN=0
0041	62 ICLSTM=ICLSIN+1
0042	IF (ICLSIN.EQ.20) GO TO 112
0043	ARI=AKNR-(1.E-12)

MILLER AND WOLF

HALFF	CSN	SOURCE LISTING	STATEMENT
	0044		ALL=AKNL*(1.E-12)
	0045		CALL ITRTF (AR1)
	0046		IP4=IFG
	0047		ZR1=YOU(1)
	0048		CALL ITRTF (AL1)
	0049		IP3=IFG
	0050		64 IF (IP1-IP3) 66,70,68
	0051		66 IF (DABS(ZL)-LE-1.00) ZL=0.
	0052		ZL=ZL/PMGTD
	0053		IP1=IP1+1
	0054		GO TO 64
	0055		68 IF (DABS(ZL1)-LE-1.00) ZL1=0.
	0056		ZL1=ZL1/PMGTD
	0057		IP3=IP3+1
	0058		GO TO 64
	0059		70 CONTINUE
	0060		72 IF (IP2-IP4) 74,78,76
	0061		74 IF (DABS(ZR)-LE-1.00) ZR=0.
	0062		ZR=ZR/PMGTD
	0063		IP2=IP2+1
	0064		GO TO 72
	0065		76 IF (DABS(ZR1)-LE-1.00) ZR1=0.
	0066		ZR1=ZR1/PMGTD
	0067		IP4=IP4+1
	0068		GO TO 72
	0069		78 ZL1=YOU(1)
	0070		IF (DABS(ZR1)-GT-DABS(ZR)) GO TO 82
	0071		IF (DABS(ZL1)-LE-DABS(ZL)) GO TO 122
	0072		82 ANEW=(AKNR+AKNL)/2.0
	0073		CALL ITRTF (ANEW)
	0074		ZNEW=YOU(1)
	0075		IF (NGR-NE-1) GO TO 102
	0076		AKNL=ANEW
	0077		IP1=IFG
	0078		ZL=ZNEW
	0079		GO TO 62
	0080		102 AKNR=ANEW
	0081		IP2=IFG
	0082		ZR=ZNEW
	0083		GO TO 62
			C ***** PART 3 *****
			C
			C
	0084		112 IF (IP1-IP2) 117,119,118
	0085		117 IF (DABS(ZL)-LE-1.00) ZL=0.
	0086		ZL=ZL/PMGTD
	0087		IP1=IP1+1
	0088		GO TO 112
	0089		118 IF (DABS(ZR)-LE-1.00) ZR=0.
	0090		ZR=ZR/PMGTD

MALFF	CSN	SOURCE LISTING
		STATEMENT
	0091	IP2=IP2+1
	0092	GO TO 112
	0093	119 AKA=AKNL+(ZL*(AKNR-AKNL))/(ZL-ZR)
	0094	FLAG=1.0
	0095	GO TO 132
	0096	122 AKA=(AKNL+AKNR)/2.0
	0097	FLAG=2.0
	0098	132 CALL IIRTF (AKA)
	0099	LOOP=LOOP+1
	0100	EPLON=EPSLN*UMAX
	0101	IF (DABS(YOU(1))-GT.EPLON) GO TO 162
	0102	IF (DABS(AKNL-AKA).LE.1.E-12) GO TO 222
	0103	IF (DABS(AKNR-AKA).LE.1.E-12) GO TO 222
	0104	162 IF (NCR-NE-I) GO TO 192
	0105	IF (DABS(AKNL-AKA).LE.PPRCN) GO TO 212
	0106	IP1=IFG
	0107	ZL=YDU(1)
	0108	AKNL=AKA
	0109	IF (FLAG.GT.1.5) GO TO 112
	0110	GO TO 122
	0111	192 IF (DABS(AKNR-AKA).LE.PPRCN) GO TO 212
	0112	IP2=IFG
	0113	ZR=YDU(1)
	0114	AKNR=AKA
	0115	IF (FLAG.GT.1.5) GO TO 112
	0116	GO TO 122
	0117	122 IZERO=1
	0118	CALL IIRTF (AKA)
	0119	222 AKN(I)=AKA
	0120	RETURN
	0121	END

MILLER AND WOLF

CROSS REFERENCE LISTING

HLFF	TYPE	DEFN	REFERENCES
12	21	14	28 31
32	29	25	
42	32	24	
52	35	12	
62	41	79	83
64	50	54	58
66	51	50	
68	55	50	
70	59	50	
72	60	64	68
74	61	60	
76	65	60	
78	69	60	
82	72	70	
102	80	75	
112	84	42	88 92 109 115
117	85	84	
118	89	84	
119	93	84	
122	96	71	110 116
132	98	95	
162	104	101	
192	111	104	
212	117	105	111
222	119	102	103

SYMBOL TYPE/USAGE REFERENCES

AK	R*8 ARR	2	9	36	37	103	105	108	111	114	118	119
AKA	R*8 VAR	2	93	98	102	103	105	108	111	114	118	119
AKN	R*8 ARR	2	3	119								
AKNL	R*8 VAR	2	36	72	76	93	93	96	102	105	108	
AKNR	R*8 VAR	2	37	44	72	80	96	103	111	114		
AK1	R*8 VAR	2	5	15	21	21	29					
AK2	R*8 VAR	2	5	18	21	26						
AL1	R*8 VAR	2	44	48								
ANFM	R*8 VAR	2	21	22	29	32	72	73	76	90		
ARI	R*8 VAR	2	43	45	26	29						
DABS	R*4 IFN	51	55	61	65	70	71	71	85	89	101	102
		103	105	111								
EPLDM	R*4 VAR	100	101									
EPSLM	R*4 VAR	4	100									
FLOG	R*4 VAR	94	97	109	115							
I	I*4 ENT	1										
ICLSIN	I*4 VAR	6	13	75	104	119						
IFG	I*4 VAR	40	41	42	46	49	81	106	112			
		6	33	34								


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SOURCE LISTING
STATEMENT
CSN
0001 SUBROUTINE SOLID
0002 >DOUBLE PRECISION TMOPI,A,DCOMP,B,DSHEAR,URA,RAYL,XRA,RA1,RA2,
>FRA,DRA,DL1,MH1,DL2,MH2,SPEED,DEPTH,KRAY,KMAX,KSHEAR,AK1,AK2,YOU,
>AKN,PV,SOUND
0003 INTEGER ADCRS,RAYCRS
0004 REAL KCOMP,KCOMP2,KSHEAR
0005 COMMON/TN/Z1(150),C1(150),Z2(150),C2(150),ABSOR(150),ATTEN2(150),
>ATTEN(150),ATTENS(150),AIRH20(150),H2QZND(150),UNRMI(150),I202,
>UNRHZ(150),I202),MDPRINT,INC1,INC2,H2,LI1,LI2,SHEAR,NMODE,KA,MD1,
>ND2,NZ
0006 COMMON/TN/RH01,RH02,RH03,M12,COMP,F,N1
0007 COMMON/TN/AKN(150)
0008 COMMON/NI/SOUND(1202),SPEED(1202),TMOPI,DL1,MH1,DL2,MH2,MATCH,
>N1PLS1,N1PLS2,N1PLS3,N1MNS1,N1MNS2,N2MNS1,NT,NTMNS2
0009 COMMON/NI/SOL/DCOMP,DSHEAR,KRAY,ADCRS
0010 COMMON/NI/AKI,AK2,L00P
0011 COMMON/NIH/IZER0,NCR,Y0UC(1202),I,IFG
0012 COMMON/TN/PRCN,PRGTD
0013 DIMENSION LAMP(3),DEPTH(1202),X(650),Y(650),MDNUM(12),ALDEPTH(2)
0014 DATA LDEPTH/' DEP','TH'/'
0015 DATA LAMP/'AMPL','ITUD','E'/'
0016 8001 FORMAT (//,35X,'COMPRESSIONAL VELOCITY SHEAR VELOCITY RAYLEI
>GH VELOCITY',/,'40X,F10.3,3X,2(9X,F10.3))
0017 9001 FORMAT (//,55X,'SOUND SPEED PROFILE',//,49X,' DEPTH DEPTH
> VELOCITY',//)
0018 10001 FORMAT (45X,3F11.3)
0019 11001 FORMAT (/)
0020 12001 FORMAT (IHI,/,35X,'MAXIMUM NUMBER OF MODES =',I3,10X,'NUMBER OF MO
>DES CALCULATED =',I3,//)
0021 13001 FORMAT (IHI)
0022 14001 FORMAT (' MODE NO. =',I3,5X,'PHASE VELOCITY =',D20.12)
0023 15001 FORMAT (' UPPER AMPLITUDES MATCHED FOR THIS MODE STARTING AT NORMA
>LIZED DEPTH =',F7.4)
0024 16001 FORMAT (' NUMBER OF ITERATE SOLUTIONS =',I3,5X,'THE EIGENFUNCTION
> WAS SCALED DOWN',I3,' TIME(S)')
0025 17001 FORMAT (' LAYER 2 ATTEN RATIO = DEFAULT ZERO')
0026 18001 FORMAT (' COMP ATTEN RATIO = DEFAULT ZERO')
0027 18002 FORMAT (' SHEAR ATTEN RATIO = DEFAULT ZERO')
0028 19001 FORMAT (' WAVE NUMBER WATER ABSORPTION LAYER 2 ATTEN RATI
>O COMP ATTEN RATIO SHEAR ATTEN RATIO AIR/H2O SCATTER H2O/2
>ND SCATTER')
0029 20001 FORMAT (D19.12,4X,E11.4,9X,2(E11.4,10X),E11.4,2(8X,E10.4),//)
0030 21001 FORMAT (IHI,'MODE AMPLITUDES FOR THE SOURCE FREQUENCY OF',F9.3,' H
>Z',/,/, 'FIRST LAYER',//)
0031 22001 FORMAT (10X,12(3X,I3,'MODE'),/)
0032 23001 FORMAT (4X,2A4,12(1X,2A4,A1))
0033 24001 FORMAT (13F10.4)
0034 25001 FORMAT (IHI,'MODE AMPLITUDES FOR THE SOURCE FREQUENCY OF',F9.3,' H
>Z',/,/, 'SECOND LAYER',//)
TMOPI=6.2831853071795800

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SOLID	CSN	SOURCE LISTING	STATEMENT
	0036		F2=(CF/1000.)*(CF/1000.)
	0037		EPH=.1*F2/(1.+F2)+40.*F2/(4100.+F2)+2.75E-4*F2
	0038		EPH=EPH*-1151292546*1.093613298E-3
	0039		DCOMP=DBLE(COMP)
	0040		DSHEAR=DBLE(SHEAR)
	0041		A=1.0/(DCOMP*DCOMP)
	0042		B=1.0/(DSHEAR*DSHEAR)
	0043		URA=(DCOMP*DCOMP-2.0*DSHEAR*DSHEAR)/(2.0*(DCOMP*DCOMP- >DSHEAR*DSHEAR))
	0044		RAYL=((0.87+1.12*URA)/(1.0+URA))*DSHEAR
	0045		XRA=1.0/(RAYL*RAYL)
	0046		DO 10 J=1,5
	0047		RA1=DSQRT(XRA-A)*DSQRT(XRA-B)
	0048		RA2=(DSQRT(XRA-A)/DSQRT(XRA-B))+DSQRT(XRA-B)/DSQRT(XRA-A))
	0049		FRA=RA1-CXRA-(B/2.0)*(XRA-(B/2.0))/XRA
	0050		DRA=0.5*RA2-(1.0-(B*B)/(4.0*XRA*XRA))
	0051	10	XRA=XRA-(FRA/DRA)
	0052		RAYL=DSQRT(1.0/XRA)
	0053		X(1)=Z(1)
	0054		CMINI=C1(1)
	0055		CMAXI=C1(1)
	0056		DO 20 J=2,ND1
	0057		IF (C1(J)-LT.CMINI) CMINI=C1(J)
	0058		IF (C1(J)-GT.CMAXI) CMAXI=C1(J)
	0059		X(J)=Z1(J)
	0060	20	Z1(J)=Z1(J)/HI2
	0061		Y(1)=Z2(1)
	0062		Z2(1)=Z1(ND1)
	0063		CMIN2=C2(1)
	0064		CMAX2=C2(1)
	0065		DO 30 J=2,ND2
	0066		IF (C2(J)-LT.CMIN2) CMIN2=C2(J)
	0067		IF (C2(J)-GT.CMAX2) CMAX2=C2(J)
	0068		Y(J)=Z2(J)
	0069	30	Z2(J)=Z2(J)/HI2
	0070		CMIN=AMINI(CMINI,CMIN2)
	0071		WRITE(6,8001) COMP,SHEAR,RAYL
	0072		WRITE(6,9001)
	0073		WRITE(6,10001) (Z1(1),X(1),C1(1),I=1,ND1)
	0074		WRITE(6,11001)
	0075		WRITE(6,10001) (Z2(1),Y(1),C2(1),I=1,ND2)
	0076		DL1=DBLE(1.0)/LI1
	0077		HMI=DL1*DL1*HI2*HI2
	0078		DL2=DBLE(CH2)/HI2/LI2
	0079		HM2=DL2*DL2*HI2*HI2
	0080		NI=LI1+1
	0081		NIPLS1=NI+1
	0082		NIPLS2=NI+2
	0083		NIPLS3=NI+3
	0084		NIPLS4=NI+4

SOURCE LISTING

SOLID	CSN	STATEMENT
	0005	N1MNS2=N1-2
	0006	N2=L I2+1
	0007	N2MNS1=N2-1
	0008	NT=N1+N2
	0009	N1MNS1=NT-1
	0090	N1MNS2=NT-2
	0091	DEPTH(1)=0.0
	0092	DEPTH(N1)=1.0
	0093	DEPTH(N1PLS1)=1.0
	0094	DEPTH(NT)=DBLE(N2)/N12+1.0
	0095	SPEED(1)=HH1/C1(1)/C1(1)
	0096	SPEED(N1)=HH1/C1(ND1)/C1(ND1)
	0097	SPEED(N1PLS1)=HH2/C2(1)/C2(1)
	0098	SPEED(NT)=HH2/C2(ND2)/C2(ND2)
	0099	K=2
	0100	DO 50 INTERP=2*N1MNS1
	0101	DEPTH(INTERP)=(INTERP-1.0)*DL1
	0102	KK=K
	0103	DO 40 J=KK,ND1
	0104	IF (DEPTH(INTERP).GT.Z1(J)) GO TO 40
	0105	SPEED(INTERP)=(C1(J)-C1(J-1))*(DEPTH(INTERP)-Z1(J-1))/
		>(DBLE(Z1(J))-Z1(J-1))*C1(J-1)
	0106	SOUND(INTERP)=SPEED(INTERP)
	0107	SPEED(INTERP)=HH1/(SPEED(INTERP)*SPEED(INTERP))
	0108	GO TO 50
	0109	40 K=K+1
	0110	50 CONTINUE
	0111	K=2
	0112	DO 70 INTERP=N1PLS2,NTMNS1
	0113	DEPTH(INTERP)=(INTERP-1-N1)*DL2+1.0
	0114	KK=K
	0115	DO 60 J=KK,ND2
	0116	IF (DEPTH(INTERP).GT.Z2(J)) GO TO 60
	0117	SPEED(INTERP)=(C2(J)-C2(J-1))*(DEPTH(INTERP)-Z2(J-1))/
		>(DBLE(Z2(J))-Z2(J-1))*C2(J-1)
	0118	SOUND(INTERP)=SPEED(INTERP)
	0119	SPEED(INTERP)=HH2/(SPEED(INTERP)*SPEED(INTERP))
	0120	GO TO 70
	0121	60 K=K+1
	0122	70 CONTINUE
	0123	IZERO=0
	0124	ADCRS=1
	0125	KRAY=TWOP1*F/RAYL
	0126	KMAX=TWOP1*F/CMIN
	0127	KCOMP=6.2831853*F/COMP
	0128	KCOMP2=KCOMP*KCOMP
	0129	KSHEAR=TWOP1*F/DSHEAR
	0130	KSHEAR2=KSHEAR*KSHEAR
	0131	SRFC=39.4784176*F*(C1(1)*C1(1))
	0132	BOTTOM=39.4784176*F*(C1(ND1)*C1(ND1))

SLIP	CSN	SOURCE LISTING	STATEMENT
			CALL ITRTS (KRAY,I)
0133			RAYCRS=MCR
0134			CALL ITRTS (KSHEAR,I)
0135			MAXMD=MCR+1
0136			NR*DE=MINO(NMODE,MAXMD)
0137			MGROPS=INT(NMODE/12.0+0.02)+1
0138			DO 350 M=1,MGROPS
0139			IBASE=(M-1)*12
0140			IF (M.LT.MGROPS) NIC=12
0141			IF (M.EQ.MGROPS) NIC=MOD(NMODE,12)
0142			IF (NIC.EQ.0) GO TO 350
0143			DO 340 IC=1,NIC
0144			I=IBASE+IC
0145			MDNUM(IC)=I
0146			IF (I.LE.RAYCRS) GO TO 180
0147			AKI=KSHEAR
0148			AK2=KRAY
0149			ADCRS=0
0150			IM=I-1
0151			GO TO 190
0152			180 AKI=KRAY
0153			AK2=KMAX
0154			ADCRS=1
0155			IM=I
0156			IF (AK1.LT.AK2) GO TO 190
0157			AKI=KSHEAR
0158			AK2=KRAY
0159			190 CALL HALFS (IM)
0160			YDD=0.0
0161			DD01=0.0
0162			DD02=0.0
0163			DD03=0.0
0164			EVEN=0.0
0165			EVEN1=0.0
0166			EVEN2=0.0
0167			EVEN3=0.0
0168			DO 200 J=2,MIMS1,2
0169			200 EVEN1=EVEN1+YOU(J)*YOU(J)
0170			DO 210 J=3,MIMS2,2
0171			210 DD01=DD01+YOU(J)*YOU(J)
0172			DO 220 J=N1PLS2,NTMNS1,2
0173			220 EVEN2=EVEN2+YOU(J)*YOU(J)
0174			DO 230 J=N1PLS3,NTMNS2,2
0175			230 DD02=DD02+YOU(J)*YOU(J)
0176			DO 234 J=2,MIMS1,2
0177			234 EVEN3=EVEN3+YOU(J)*YOU(J)/SOUND(J)
0178			DO 236 J=3,MIMS2,2
0179			236 DD03=DD03+YOU(J)*YOU(J)/SOUND(J)
0180			DO 240 J=N1PLS2,NTMNS1,2
0181			240 EVEN=EVEN+YOU(J)*YOU(J)/SOUND(J)
0182			

SOL ID	CSN	SOURCE LISTING	STATEMENT
0183		00 250 J=N1PLS3,NTMNS2,2	
0184		000=0DD+Y0U(J)*Y0U(J)/SOUND(J)	
0185		A11=RH01*(DL1/3.0)*(Y0U(1)+Y0U(1)+4.0*EVEN1+2.0*0DD1+Y0U(N1)*>Y0U(N1))	
0186		A12=RH02*(DL2/3.0)*(Y0U(N1+1)+Y0U(N1+1)+4.0*EVEN2+2.0*0DD2+>Y0U(N1)*Y0U(N1))	
0187		AKN2=AKN(I)*AKN(I)	
0188		QC5MP=AKN2-KCOMP2	
0189		CMPT=SQRT(QCOMP)	
0190		QSHEAR=2.0*AKN2-KSHR2	
0191		SHEART=SQRT(AKN2-KSHR2)	
0192		QSHR2=QSHEAR*QSHEAR	
0193		Q=RH03*QSHR2/(M12+QCOMP*KSHR2+KSHR2)	
0194		A13=Q*(0.5/CMPT+2.0*QCOMP*KSHR2/(SHEART*QSHR2)+>6.0*SHEART*QCOMP/QSHR2-4.0*CMPT/QSHEAR)	
0195		IF (IFG.LE.0) GO TO 255	
0196		A13=A13/PNGTD/PNGTD	
0197		IF (IFG.GT.1) A13=0.	
0198		255 A14=RH02*(DL2/3.0)*(Y0U(N1+1)+Y0U(N1+1)/C2(I)+4.0*EVEN+2.0*0DD+>Y0U(N1)*Y0U(N1))	
0199		A15=RH01*(DL1/3.0)*(Y0U(1)+Y0U(1)/C1(I)+4.0*EVEN3+2.0*0DD3+>Y0U(N1)*Y0U(N1)/C1(ND1))	
0200		AI=A11+A12+A13	
0201		ANORM=SQRT(1.0/AI)	
0202		00 260 J=1,NT	
0203		IF (KA.EQ.0) UNRM(I,J)=Y0U(J)*ANORM	
0204		IF (KA.EQ.1) UNRM2(I,J)=Y0U(J)*ANORM	
0205		260 CONTINUE	
0206		IF (KA.EQ.1) GO TO 270	
0207		YNM1=UNRM1(I,1)	
0208		YNM2=UNRM1(I,2)	
0209		YNM3=UNRM1(I,3)	
0210		YNM4=UNRM1(I,M1)	
0211		YNM5=UNRM1(I,N1PLS1)	
0212		YNM6=UNRM1(I,N1PLS2)	
0213		YNM7=UNRM1(I,N1PLS3)	
0214		YNM8=UNRM1(I,NTMNS2)	
0215		YNM9=UNRM1(I,NTMNS1)	
0216		YNM10=UNRM1(I,NT)	
0217		GO TO 275	
0218		270 YNM1=UNRM2(I,1)	
0219		YNM2=UNRM2(I,2)	
0220		YNM3=UNRM2(I,3)	
0221		YNM4=UNRM2(I,M1)	
0222		YNM5=UNRM2(I,N1PLS1)	
0223		YNM6=UNRM2(I,N1PLS2)	
0224		YNM7=UNRM2(I,N1PLS3)	
0225		YNM8=UNRM2(I,NTMNS2)	
0226		YNM9=UNRM2(I,NTMNS1)	
0227		YNM10=UNRM2(I,NT)	

SOURCE LISTING

CSN	STATEMENT
0228	DYQUA=(-3.*YMM1+6.*YMM2-YMM3)/(2.*DL1)
0229	DYQUB=(-3.*YMM5+4.*YMM6-YMM7)/(2.*DL2)
0230	DYQUC=(YMM8-4.*YMM9+3.*YMM10)/(2.*DL2)
0231	DYQUC=DYQUC+DYQUC
0232	IF (SRFC-AKN2-GT.PPRCN) GO TO 280
0233	AIRH2DCI)=0.0
0234	GO TO 290
0235	AIRH2DCI)=RH01+DYQUA+DYQUB/(4.*AKN(I)+H12+3*SQRT(SRFC-AKN2))
0236	IF (BOTTOM-AKN2-GT.PPRCN) GO TO 300
0237	H202NDCI)=0.0
0238	GO TO 310
0239	H202NDCI)=RH01+SQRT(BOTTOM-AKN2)*(YMM4+YMM4+DYQUB+DYQUB/CH12+H12+(BOTTOM-AKN2)))/(4.0*AKN(I)+H12)
0240	PV=TM0PI+F/AKN(I)
0241	IF (AI4-GT.AI/PMGTD) GO TO 313
0242	AI4=0.
0243	ATTEN2CI)=6.2831853*F*AI4/(AKN(I)*AI)
0244	ATTENSCI)=KCOMP*Q*.5/(CMPRT+H12+H12*AKN(I))
0245	DYQUC=DYQUC
0246	DUTSG=1./PMGTD/ATTENCCI)
0247	IF (DYQUC-GT.DUTSC) GO TO 315
0248	DYQUC=0.
0249	ATTENCCI)=ATTENCCI)*DYQUC
0250	ATTENSCI)=AKNCI)*Q/(H12+H12+KSHEAR)*(2.*KSHR2*QCOMP/(SHEART*QSHR2))
0251	>8.*SHEART*QCOMP/QSHR2-4.*CMPRT/QSHEAR)
0252	DUTSS=1./PMGTD/ATTENSCI)
0253	IF (DYQUC-GT.DUTSS) GO TO 317
0254	DYQUC=0.
0255	ATTENSCI)=ATTENSCI)*DYQUC
0256	ABSOR(I)=6.2831853*F*AI5+EPN/(AKN(I)*AI)
0257	IF (IC.GT.1) GO TO 330
0258	WRITE(6,12001) MAXND,NNODE
0259	IF (MODCIC,7).EQ.0) WRITE(6,13001)
0260	WRITE(6,14001) I,PV
0261	IF (IZERO-EQ.2) WRITE(6,15001) DEPTH(MATCH)
0262	WRITE(6,16001) LOOP,IFG
0263	IF (AI4-LE-AI/PMGTD) WRITE(6,17001)
0264	IF (DYQUC-LE.DUTSC) WRITE(6,18001)
0265	IF (DYQUC.LE.DUTSS) WRITE(6,18002)
0266	WRITE(6,19001)
0267	WRITE(6,20001) AKN(I),ABSOR(I),ATTEN2CI),ATTENSCI),ATTENSCI),
0268	>AIRH2DCI),H202NDCI)
0269	CONTINUE
0270	IF (MDPRNT-EQ.0) GO TO 350
0271	WRITE(6,21001) F
0272	WRITE(6,22001) (MDNUM(K),K=1,NIC)
0273	WRITE(6,23001) LDEPTH,(LAMP(1),LAMP(2),LAMP(3),K=1,NIC)
0274	I1=IBASE+1
	IMIC=IBASE+NIC
	DO 345 J=1,N1,INC1

SLNO	CSN	SOURCE LISTING	STATEMENT
0275		IF (KA.EQ.0) WRITE(6,24001) DEPTH(J),(UNRW1(K,J),K=1,INIC)	
0276		IF (KA.EQ.1) WRITE(6,24001) DEPTH(J),(UNRW2(K,J),K=1,INIC)	
0277		345 CONTINUE	
0278		WRITE(6,25001) F	
0279		WRITE(6,22001) (RNUM(K),K=1,NIC)	
0280		WRITE(6,23001) LDEPTH,CLAMP(1),LAMP(2),LAMP(3),K=1,NIC)	
0281		DO 349 J=N1PLS1,NT,INC2	
0282		IF (KA.EQ.0) WRITE(6,24001) DEPTH(J),(UNRW1(K,J),K=1,INIC)	
0283		IF (KA.EQ.1) WRITE(6,24001) DEPTH(J),(UNRW2(K,J),K=1,INIC)	
0284		349 CONTINUE	
0285		350 CONTINUE	
0286		RETURN	
0287		END	

SOLID		GROSS REFERENCE LISTING			REFERENCES
LABEL	TYPE	DEFN			
10		51		46	
20		60		56	
30		69		65	
40		109		103	
50		110		108	
60		121		115	
70		122		112	
130		153		147	
190		160		152	
200		170		169	
210		172		171	
220		174		173	
230		176		175	
234		178		177	
236		180		179	
240		182		181	
250		184		183	
255		198		195	
260		205		202	
270		218		206	
275		228		217	
280		235		232	
290		236		234	
300		239		236	
310		240		238	
313		243		241	
315		249		247	
317		254		252	
330		258		256	
340		267		144	
345		277		274	
349		284		281	
350		285		139	
8001		16		71	
9001		17		72	
10001		18		73	
11001		19		74	
12001		20		257	
13001		21		258	
14001		22		259	
15001		23		260	
16001		24		261	
17001		25		262	
18001		26		263	
18002		27		264	
19001		28		265	
20001		29		266	
21001		30		269	
22001		31		270	
23001		32		271	
				143	
				268	
				75	
				279	
				280	

SOURCE LISTING

IIRTS

CSN	STATEMENT
0046	00 21 JD=NTMJ,NT
0047	IF (DABS(YOU(JD)).LT.1.00) YOU(JD)=0.
0048	21 YOU(JD)=YOU(JD)/PMGTD
0049	UMAX=UMAX/PMGTD
0050	IFG=IFG+1
0051	22 IF (NTMJ.EQ.MATCH) GO TO 131
0052	31 CONTINUE
0053	B=(-3.0*YOU(N1PLS1)-4.0*YOU(N1PLS1+1)+YOU(N1PLS1+2))/(2.0*DL2)
0054	YOU(N1)=RH02*YOU(N1PLS1)/RH01
0055	YOU(N1-1)=YOU(N1)+DL1*B-YOU(N1)*(OMEGA2+SPEED(N1)-HH1*AKN*AKN)/2.0
0056	IF (DABS(YOU(N1)).GT.UMAX) UMAX=DABS(YOU(N1))
0057	IF (DABS(YOU(N1-1)).GT.UMAX) UMAX=DABS(YOU(N1-1))
0058	IF (DSIGN(1.00,YOU(N1))*YOU(N1-1).LE.0.) NCR=NCR+1
0059	00 121 J=2,N1MNS1
0060	N1MJ=N1-J
0061	PPLUS1=12.0+OMEGA2*SPEED(N1MJ)-HH1*AKN*AKN
0062	P=24.0-10.0*(OMEGA2*SPEED(N1MJ+1)-HH1*AKN*AKN)
0063	PNMS1=12.0+OMEGA2*SPEED(N1MJ+2)-HH1*AKN*AKN
0064	YOU(N1MJ)=(P/PPLUS1)*YOU(N1MJ+1)-(PNMS1/PPLUS1)*YOU(N1MJ+2)
0065	UABVL=DABS(YOU(N1MJ))
0066	IF (UABVL.GT.UMAX) UMAX=UABVL
0067	IF (DSIGN(1.00,YOU(N1MJ))*YOU(N1MJ+1).LE.0.) NCR=NCR+1
0068	IF (UABVL.LT.PMGTD) GO TO 51
0069	00 41 JD=NTMJ,NT
0070	IF (DABS(YOU(JD)).LT.1.00) YOU(JD)=0.
0071	41 YOU(JD)=YOU(JD)/PMGTD
0072	UMAX=UMAX/PMGTD
0073	IFG=IFG+1
0074	51 IF (N1MJ.EQ.MATCH) GO TO 131
0075	121 CONTINUE
0076	GO TO 151
0077	131 IZER0=2
0078	YOU(1)=0.0
0079	YOU(2)=DSQRT(HH1)*1.0-10
0080	00 135 J=3,N1
0081	PPLUS1=12.0+OMEGA2*SPEED(J)-HH1*AKN*AKN
0082	P=24.0-10.0*(OMEGA2*SPEED(J-1)-HH1*AKN*AKN)
0083	PNMS1=12.0+OMEGA2*SPEED(J-2)-HH1*AKN*AKN
0084	PPLUS1=(P/PPLUS1)*YOU(J-1)-(PNMS1/PPLUS1)*YOU(J-2)
0085	IF (J.EQ.MATCH) GO TO 148
0086	YOU(J)=PPLUS1
0087	IF (DABS(YOU(J)).LT.PMGTD) GO TO 135
0088	00 133 JD=2,J
0089	IF (DABS(YOU(JD)).LT.1.00) YOU(JD)=0.0
0090	133 YOU(JD)=YOU(JD)/PMGTD
0091	135 CONTINUE
0092	B=(-3.0*YOU(N1MNS2)+4.0*YOU(N1MNS1)-YOU(N1))/(2.0*DL1)
0093	YOU(N1PLS2)=RH01*YOU(N1)/RH02
0094	YOU(N1PLS2)=YOU(N1PLS1)+DL2*B-YOU(N1PLS1)*>(OMEGA2+SPEED(N1PLS1)-HH2*AKN*AKN)/2.0

MILLER AND WOLF

ITRYS	CSN	SOURCE LISTING	STATEMENT
			DO 145 J=N1PLS3*NTMS2
0095			PPLUS1=12.0+OMEGA2*SPEED(J)-HM2*AKN*AKN
0096			P=24.0-10.0*(OMEGA2*SPEED(J-1)-HM2*AKN*AKN)
0097			PMS1=12.0+OMEGA2*SPEED(J-2)-HM2*AKN*AKN
0098			PPLUS1=(P/PPLUS1)*YOU(J-1)-(PMS1/PPLUS1)*YOU(J-2)
0099			IF (J.EQ.MATCH) GO TO 148
0100			YOU(J)=PPLUS1
0101			IF (DABS(YOU(J)).LT.PMGTD) GO TO 145
0102			DO 143 JD=2,J
0103			IF (DABS(YOU(JD)).LT.1.00) YOU(JD)=0.0
0104		143	YOU(JD)=YOU(JD)/PMGTD
0105		145	CONTINUE
0106			GO TO 151
0107			148 JMNS1=J-1
0108			DO 149 JD=2,JMNS1
0109			YOU(JD)=(YOU(JD)/PPLUS1)*YOU(MATCH)
0110			IF (DABS(YOU(JD)).LT.1./PMGTD) YOU(JD)=0.0
0111			
0112		149	CONTINUE
0113		151	RETURN
0114			END
0115			

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ITRYS CROSS REFERENCE LISTING

SYMBOL	CROSS REFERENCE LISTING	TYPE/USAGE	REFERENCES
IZERO J	I** VAR	VAR	6 11 77
			12 13 14
			82 83 84
JD	I** VAR	VAR	99 100 101
			46 47 48
			89 90 90
			111 108 109
JMNS1 KRAY	I** VAR	VAR	29 32
			1 10 14
L MATCH	I** DAR	DAR	33 33
			6 23
NCR NI	I** VAR	VAR	4 4
			4 4
NIH NISOL	COM	COM	5 6
			5 6
NT NTMJ	I** VAR	VAR	27 28 29
			37 38 39
NTMNS2 NI	I** VAR	VAR	4 17 22
			3 54 55
N1MJ N1MNS1	I** VAR	VAR	60 61 62
			60 59 92
N1MNS2 N1PLS1	I** VAR	VAR	4 12 92
			4 53 53
N1PLS2 N1PLS3	I** VAR	VAR	4 17 95
			4 36
N2MNS1 OPEGR2	I** VAR	VAR	4 25 27
			82 83 94
P PMGTD	R** VAR	VAR	2 39 41
			7 45 48
PMNS1 PPLUS1	R** VAR	VAR	2 40 41
			2 38 41
PPRLN R\$1DSQ	R** VAR	VAR	96 99 99
			7 29 32
RH01 RH02	R** VAR	VAR	3 54 93
			3 27 54
RH73 SCURD	R** VAR	VAR	3 27
			2 4
SPEED TNI	R** ARR	ARR	2 4 13
			2 4 30
TMH TMPI	COM	COM	83 94 96
			3 3
UABVL UMAX	R** VAR	VAR	18 18 38
			97 98
YOU	R** ARR	ARR	39 40
			98
			11 13 14 18 19 22 27 28 29 30 31 32 33 35 36 37 38 39 40 41 42 44 45 46 47 48 49 50 51 52 53 54 55 56 57 58 59 60 61 62 63 64 65 66 67 68 69 70 71 72 73 74 75 76 77 78 79 80 81 82 83 84 85 86 87 88 89 90 91 92 93 94 95 96 97 98 99 100 101 102 103 104 105 106 107 108 109 110 111 112

ITRTS CROSS REFERENCE LISTING
SYMBOL TYPE/USAGE REFERENCES

35	41	41	42	44	44	44	47	47	48	48	48	53
53	53	54	55	55	55	55	56	56	57	57	57	58
58	64	64	65	67	67	67	70	70	71	71	71	78
79	84	84	87	89	89	89	90	90	92	92	92	92
93	93	94	94	99	99	99	101	102	104	104	104	105
105	110	110	111	111	111	111						

```

SOURCE LISTING
STATEMENT
0001 SUBROUTINE HALFS (L)
0002 DOUBLE PRECISION AK1,AK2,ANEW,AK,ZK,YOU,AKNL,AKNR,ZL,ZR,ARI,ALI,
>ZRI,ZLI,ZNEH,AKA,AKN,UMAX
COMMON/TNH/AKN(150)
COMMON/TH/EPSLN
COMMON/WH/AK1,AK2,LOOP
COMMON/NIH/ZZERO,NCR,YOU(1202),I,IFG
COMMON/TNI/PPRCR,PGTD
COMMON/IH/UMAX
DIMENSION AK(2),ZK(2)
C ***** PART 1 *****
C
0010 IZERO=0
0011 LOOP=0
0012 DO 52 K=1,2
0013 J=L+1-K
0014 IF (K.EQ.2) GO TO 12
0015 CALL ITRYS (AK1,L)
0016 LOOP=LOOP+1
0017 NAI=NCR
0018 CALL ITRYS (AK2,L)
0019 LOOP=LOOP+1
0020 NA2=NCR
0021 IF (NA1.EQ.1.AND.NA2.EQ.1) NAI=2
0022 ANEW=((AK2-AK1)*(J-NA1))/(NA2-NA1))+AK1
0023 CALL ITRYS (ANEW,L)
0024 LOOP=LOOP+1
0025 IF (NCR.EQ.J) GO TO 42
0026 IF (NCR.GT.J.AND.NCR.NE.NA2) GO TO 32
0027 AK2=ANEW
0028 NA2=NCR
0029 GO TO 12
0030 AK1=ANEW
0031 NA1=NCR
0032 GO TO 12
0033 AK(K)=ANEW
0034 IF (K.EQ.1) IP1=IFG
0035 IF (K.EQ.2) IP2=IFG
0036 ZK(K)=YOU(1)
0037 AKNL=AK(1)
0038 AKNR=AK(2)
0039 ZL=ZK(1)
0040 ZR=ZK(2)
C ***** PART 2 *****
C
0041 ICLSIM=0
0042 ICLSIM=ICLSIM+1
0043 IF (ICLSIM.EQ.20) GO TO 112

```

HALFS	CSN	SOURCE LISTING	STATEMENT
	0044		ARI=AKNR-(1.E-12)
	0045		AL1=AKNL+(1.E-12)
	0046		CALL IIRTS (AR1+L)
	0047		IP4=IFG
	0048		ZR1=YOU(1)
	0049		CALL IIRTS (AL1+L)
	0050		IP3=IFG
	0051		64 IF (IPI-IP3) 66,70,68
	0052		66 IF (DABS(ZL).LE.1.00) ZL=0.
	0053		ZL=ZL/PMGTD
	0054		IPI=IPI+1
	0055		GO TO 64
	0056		68 IF (DABS(ZL1).LE.1.00) ZL1=0.
	0057		ZL1=ZL1/PMGTD
	0058		IP3=IP3+1
	0059		GO TO 64
	0060		70 CONTINUE
	0061		72 IF (IP2-IP4) 74,78,76
	0062		74 IF (DABS(ZR).LE.1.00) ZR=0.
	0063		ZR=ZR/PMGTD
	0064		IP2=IP2+1
	0065		GO TO 72
	0066		76 IF (DABS(ZR1).LE.1.00) ZR1=0.
	0067		ZR1=ZR1/PMGTD
	0068		IP4=IP4+1
	0069		GO TO 72
	0070		78 ZL1=YOU(1)
	0071		IF (DABS(ZR1).GT.DABS(ZR)) GO TO 82
	0072		IF (DABS(ZL1).LE.DABS(ZL)) GO TO 122
	0073		82 ANEW=(AKNR+AKNL)/2.0
	0074		CALL IIRTS (ANEW+L)
	0075		ZNEW=YOU(1)
	0076		IF (MCR.NE.L) GO TO 102
	0077		AKNL=ANEW
	0078		IPI=IFG
	0079		ZL=ZNEW
	0080		GO TO 62
	0081		102 AKNR=ANEW
	0082		IP2=IFG
	0083		ZR=ZNEW
	0084		GO TO 62
			C ***** PART 3 *****
			C
	0085		112 IF (IPI-IP2) 117,119,118
	0086		117 IF (DABS(ZL).LE.1.00) ZL=0.
	0087		ZL=ZL/PMGTD
	0088		IPI=IPI+1
	0089		GO TO 112
	0090		119 IF (DABS(ZR).LE.1.00) ZR=0.

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HALFS	CSW	SOURCE LISTING	STATEMENT
			ZR=ZR/PAGTD
			IP2=IP2+1
			GO TO 112
		119	AKA=AKNL*(ZL*(AKNR-AKML))/(ZL-ZR)
			FLAG=1.0
			GO TO 132
		122	AKA=(AKNL+AKNR)/2.0
			FLAG=2.0
		132	CALL ITRTS (AKA,L)
			LOOP=LOOP+1
			EPLON=EPSLN*UMAX
			IF (DABSCYU(1)).GT.EPLON) GO TO 162
			IF (DABSCAKML-AKA).LE.1.E-12) GO TO 222
			IF (DABSCAKNR-AKA).LE.1.E-12) GO TO 222
		162	IF (NCR-ME-L) GO TO 192
			IF (DABSCAKML-AKA).LE.PPRCN) GO TO 212
			IP1=IFG
			ZL=YU(1)
			AKNL=AKA
			IF (FLAG.GT.1.5) GO TO 112
			GO TO 122
		192	IF (DABSCAKNR-AKA).LE.PPRCN) GO TO 212
			IP2=IFG
			ZR=YU(1)
			AKNR=AKA
			IF (FLAG.GT.1.5) GO TO 112
			GO TO 122
		212	IZERO=1
			CALL ITRTS (AKA,L)
		222	AKNCI=AKA
			RETURN
			END
		0122	

HALFS CROSS REFERENCE LISTING

LABEL	TYPE	DEFN	REFERENCES
12		22	14
32		30	26
42		33	25
52		36	12
62		42	80
64		51	55
66		52	51
68		56	51
70		60	51
72		61	65
74		62	61
76		66	61
78		70	61
82		73	71
102		81	76
112		85	43
117		86	85
118		90	85
119		94	85
122		97	72
132		99	96
162		105	102
192		112	105
212		118	106
222		120	103
		29	32
		84	84
		59	59
		69	69
		89	89
		93	110
		111	117
		116	116

SYMBOL TYPE/USAGE REFERENCES

AK	R*B	ARR	2	9	37	38	103	104	106	109	112	115	119	120
AKA	R*B	VAR	2	94	99	103	103	104	106	109	112	115	119	120
AKN	R*B	ARR	2	3	120	103	103	104	106	109	112	115	119	120
AKNL	R*B	VAR	2	37	45	77	77	94	94	97	103	106	109	109
AKNR	R*B	VAR	2	38	44	81	81	94	97	104	112	115	119	120
AK1	R*B	VAR	2	5	15	22	22	30	30	33	77	81	81	81
AK2	R*B	VAR	2	5	18	22	22	30	30	33	77	81	81	81
AL1	R*B	VAR	2	45	49	27	30	33	73	74	77	81	81	81
ANEM	R*B	VAR	2	22	23	27	30	33	73	74	77	81	81	81
AR1	R*B	VAR	2	44	46	66	71	71	72	72	86	90	102	103
DABS	R*B	IFM	52	56	62	66	71	71	72	72	86	90	102	103
			104	106	112									
EPLGW	R*B	VAR	101	102										
FPSLN	R*B	VAR	4	101										
FLOG	R*B	VAR	95	98	116									
HALFS	R*B	ENT	1											
I	I*B	VAR	6	120	43	50	50	78	82	107	113			
ICLSM	I*B	VAR	41	42	47	47	47	78	82	107	113			
IFG	I*B	VAR	6	34	35	47	47	78	82	107	113			

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MALFS CROSS REFERENCE LISTING REFERENCES

SYMBOL	TYPE/USAGE	REFERENCES
IN	COM	8
IP1	I+4 VAR	34 51
IP2	I+4 VAR	35 61
IP3	I+4 VAR	50 51 58
IP4	I+4 VAR	47 61 68
IPTS	I+4 SBR	15 18 23 46
IZERO	I+4 VAR	6 10 118
J	I+4 VAR	13 22 25 26
K	I+4 VAR	12 13 14 33
L	I+4 DAR	1 13 15 18
LOOP	I+4 VAR	5 11 16 19
MA1	I+4 VAR	17 21 22 31
MA2	I+4 VAR	20 21 22 26 28
MCR	I+4 VAR	6 17 20 25
NH	COM	5
NIH	COM	6
PPGTD	R+4 VAR	7 53 67 87 91
PPRCM	R+4 VAR	7 106
TH	COM	4
TNH	COM	3
TNIH	COM	7
UMAX	R+8 VAR	2 8 101
YOU	R+8 ARR	2 6 36
ZK	R+8 ARR	2 9 36
ZL	R+8 VAR	2 39 52 94
ZLI	R+8 VAR	2 56 57 70 72
ZNEW	R+8 VAR	2 75 79 83
ZR	R+8 VAR	2 40 62 63 67 71 83 90 91 91
ZR1	R+8 VAR	2 114 48 66 67 71